

10 mm

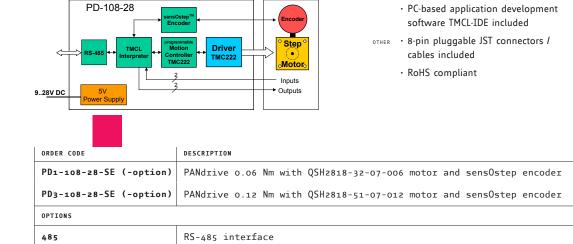
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PD-108-28

28mm / NEMA11 Stepper Motor with Controller / Driver and Serial Interface

	MAIN CHARACTERISTICS
ELECTRICAL DATA	 9V to 28V supply voltage
	 motor length: 32 mm / 51 mm max. torque 0.06 Nm / 0.12 Nm
	\cdot please also refer to the motor datasheet
INTERFACE	• RS-485
	 2 general purpose inputs
	 2 general purpose outputs
FEATURES	• up to 16 times microstepping
	 memory for 64 TMCL commands
	 automatic ramp generation in hardware
	 on the fly alteration of motion parameters (e.g. position, velocity, acceleration)
	 sensOstep[™] Encoder for motor stall detection (e.g. end position reached, overload)
	 dynamic current control
SOFTWARE	 stand-alone operation using TMCL or remote controlled operation
	 PC-based application development software TMCL-IDE included
OTHER	 8-pin pluggable JST connectors / cables included
	RoHS compliant

THEO The PD-108-28 is a full mechatronic solution including a 28 mm flange motor (NEMA11). It joins a convenient controller electronic and a sensOstep[™] encoder with a range of different motor torques. The PD-108-28 offers two motor torque options and can be controlled via RS-485 serial interface. The power supply, interface and the multi purpose I/Os can be connected via a single small JST connectors. The PD-108-28 comes with the PC based software development environment TMCL-IDE for the Trinamic Motion Control Language (TMCL). Using predefined TMCL high level commands like "move to position" a rapid and fast development of motion control applications is guaranteed. Communication traffic is kept low since all time critical operations, e.g. ramp calculation are performed on board. Full remote control of device with feedback is possible. The firmware of the module can be updated via the serial interface.



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