

# MOS INTEGRATED CIRCUIT $\mu PD4704$

# EXTENSION 8-BIT UP/DOWN COUNTER CMOS INTEGRATED CIRCUITS

#### **DESCRIPTION**

The  $\mu$ PD4704 is 8-bit up/down counters for extension of the  $\mu$ PD4702 incremental encoder counter. They perform an up/down-count using an 8-bit width with a  $\mu$ PD4702 carry or borrow signal as input. In addition, a carry output and borrow output are also provided for further extension of the count width, enabling extension to be performed in 8-bit units.

#### **FEATURES**

- 8-bit up/down counter for extension of μPD4702
- Count data output controllable (latch and 3-state output)
- Extension carry and borrow outputs
- CMOS, single +5 V power supply

#### **PIN NAMES**

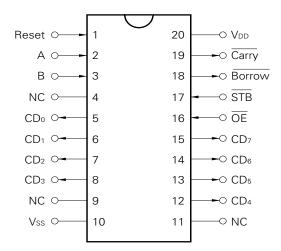
Up : Up-count input
 Down : Down-count input
 Reset : Counter reset input
 STB : Latch strobe signal input
 OE : Output control signal input

CD<sub>0-7</sub> : Count data outputs
Carry : Carry pulse output
Borrow : Borrow pulse output

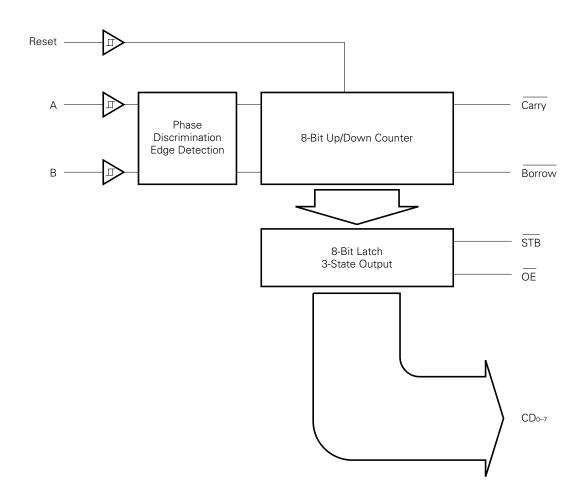
#### ORDERING INFORMATION

Part Number	Package	
μPD4704C	20-pin plastic DIP	(300 mil)
μPD4704G	20-pin plastic SOP	(300 mil)

#### PIN CONFIGURATION (Top View)



#### **BLOCK DIAGRAM**



#### **PIN FUNCTIONS**

Pin Name	Input/Output	Function
Up Down	Input	Up-count & down-count signal input pins Count is performed on rise of signal.
D <sub>0</sub> to 7	Output (3-state)	Count data output pins. Activated when $\overline{OE}$ is "L", high impedance outputs when $\overline{OE}$ is "H".
Carry	Output	8-bit counter carry signal output pin (active-low)
Borrow	Output	8-bit counter borrow signal output pin (active-low)
RESET	Input (Schmitt)	8-bit counter reset signal output pin Counter is reset when this pin is "H".
ŌĒ	Input	Count data output control signal input pin
STB	Input	Counter data output latch signal. Data is latched on the fall of $\overline{STB}$ , and is held while $\overline{STB} = \text{``L''}$ .
V <sub>DD</sub>		Power supply input pin
GND		Ground pin



#### TRUTH TABLE 1 (COUNTER BLOCK)

 $\times$ : H or L

UP	DOWN	RESET	Carry	Borrow	Remarks
×	×	Н	×	×	Reset
Н	Lf	Н	×	IJ	Reset
Н		L	×	×	Down-count
L	Н	L	×	×	Up-count
L	Ţ	L	×	×	Disabled (count undefined)
T.	L	L	×	×	Disabled (count undefined)
Н	L	L	Н	L	Borrow output when count = 00H
L	Н	L	L	Н	Carry output when count = 0FF <sub>H</sub>

#### TRUTH TABLE 2 (LATCH & OUTPUT BLOCKS)

 $\times$ : H or L

STB	ŌĒ	CD <sub>0</sub> to CD <sub>7</sub>
×	Н	Output disable (3-state)
×	L	Output enable
Н	×	Data through (count value load)
L	×	Data latch (count value retention)



#### 1. DESCRIPTION OF OPERATIONS

#### (1) Count operation

The  $\mu$ PD4704 is designed as 8-bit up/down counter for extension of the  $\mu$ PD4702. The first-stage  $\overline{Carry}$  output is connected to the  $\overline{UP}$  input of the  $\mu$ PD4704, and similarly, the  $\overline{Borrow}$  output is connected to the  $\overline{DOWN}$  input. A count is executed on the rising edge of the  $\overline{UP}$  input or  $\overline{DOWN}$  input.

If the  $\mu$ PD4704 is to be used alone, without being connected to the  $\mu$ PD4702, either  $\overline{\text{UP}}$  or the  $\overline{\text{DOWN}}$  must be "H". If a count pulse is input to  $\overline{\text{UP}}$  or  $\overline{\text{DOWN}}$  while the other is "L", the count value may change.

#### (2) Latch operation

An R-S flip-flop is inserted in the latch circuit input as shown in Fig. 1, and when STB is changed from "H" to "L" while the UP or DOWN input is "L", the internal latch signal STB' remains at "H" until the end of the count operation. Therefore, latching is not performed during a count operation. If STB changes from "H" to "L" tsudstb1 (40 ns) or more after the falling edge of UP or DOWN, the post-count data is latched, and if STB changes from "H" to "L" within tsudstb2 (10 ns) after the falling edge of UP or DOWN, then conversely, the pre-count data is latched.

Caution is required since, when  $\overline{\text{UP}}$  or  $\overline{\text{DOWN}}$  is "L" (during a count operation), the latch operation is kept waiting even if  $\overline{\text{STB}}$  is changed from "H" to "L", and therefore if a reset is executed the latch contents will also be reset (see Figs. 2 and 3).

From UP/DOWN Circuit

Count Clock

STB

Fig. 1 STB Input Circuit

STB

tsudstb1

tsudstb2

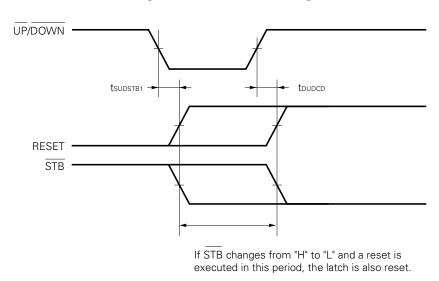
Pre-count value latched

Post-count value latched

Either pre- or post-count value latched

Fig. 2 Relation Between STB Timing and Counter Value





#### (3) Carry & borrow outputs

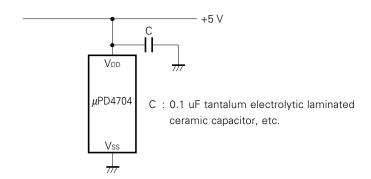
If the counter performs an up-count operation when the count value is 0FFH, an active-low pulse is output to the  $\overline{\text{Carry}}$  output (the pulse width is virtually the same as the  $\overline{\text{UP}}$  or  $\overline{\text{DOWN}}$  pulse L period). Similarly, if the counter performs a down-count operation when the count value is 00H, an active-low pulse is output to the  $\overline{\text{Borrow}}$  output. A  $\overline{\text{Borrow}}$  pulse is also output if a down-count operation is performed while RESET is "H" (during a reset), and therefore, when a  $\mu\text{PD4704}$  is added, a reset must be executed at the same time.



#### 2. OPERATING PRECAUTIONS

As the  $\mu$ PD4704 incorporates an 8-bit counter, a large transient current flows in the case of a count value which changes all the bits (such as  $00\text{H}\leftrightarrow0\text{FFH}$  or  $7\text{FH}\leftrightarrow080\text{H}$ ). This will cause misoperation unless the impedance of the power supply line is sufficiently low. It is therefore recommended that a decoupling capacitor (of around 0.1  $\mu$ F) be connected between VDD and Vss right next to the IC as shown in Fig. 4.

Fig. 4 Decoupling Capacitor





#### ABSOLUTE MAXIMUM RATINGS (TA = 25 $^{\circ}$ C, Vss = 0 V)

PARAMETER	SYMBOL	RATING		UNIT
Supply voltage	V <sub>DD</sub>	-0.5 to +7.0		V
Input voltage	Vı	-1.0 to V <sub>DD</sub> +1.0 V		V
Output voltage	Vo	−0.5 to V <sub>DD</sub> +0.5		V
Operating temperature	Topt	-40 to +85		°C
Storage temperature	T <sub>stg</sub>	−65 to +150		°C
Permissible loss	PD	500 (DIP)	200 (SOP)	mW

### DC CHARACTERISTICS (TA = -40 to +85 °C, VdD = +5 V $\pm 10$ %)

PARAMETER	SYMBOL	TEST CONDITIONS	RAT	RATING		
PANAIVIETEN	STIVIBUL	TEST CONDITIONS	MIN.	MAX.	UNIT	
Input voltage low	VIL			0.8	V	
Input voltage high	ViH	Reset	2.6		V	
Input voltage high	ViH	Other than the above	2.2		V	
Output voltage low	VoL	loL = 12 mA		0.45	V	
Output voltage high	Vон	lон = −4 mA	V <sub>DD</sub> - 0.8		V	
Static consumption current	IDD	VI = VDD, VSS		50	μΑ	
Input current	lı	VI = VDD, VSS	-1.0	1.0	μΑ	
3-state output leak current	loff		-10	10	μΑ	
Dynamic consumption current	IDD dyn	fin = 16 MHz, CL = 50 pF		12	mA	
Hysteresis voltage	VH	Reset	0.2		V	

#### AC CHARACTERISTICS (TA = -40 to +85 °C, VdD = +5 V $\pm$ 10 %)

PARAMETER		SYMBOL	TEST CONDITIONS	MIN.	MAX.	UNIT
	Cycle	tсуст	fin = 16 MHz	60		ns
Up	Input pulse width	<b>t</b> PWUDL		25		ns
Down	input puise width	<b>t</b> PWUDH		35		ns
Down	Setup time	tsrsud		0		ns
	Up/down switchover setupt time	<b>t</b> sudm		100		ns
	Reset time	<b>t</b> DRSCD			60	ns
	Output delay	toudcd			70	ns
CD <sub>0</sub> to 7	Output delay	<b>t</b> DOECD			50	ns
	Output delay	<b>t</b> DSTBCD			50	ns
	Float time				40	ns
Carry	Output dalay	tDUDCB1			50	ns
	Output delay	tDUDCB2			100	ns
Borrow	Output pulse width	<b>t</b> PWCB		30		ns
RESET	Reset pulse width	<b>t</b> PWRS		40		ns
STB	Catting time	tsudstb1		40		ns
218	Setting time	tsudstb2		10		ns



#### **AC Timings**

Fig. 1 Up/Down Signal Input Timing

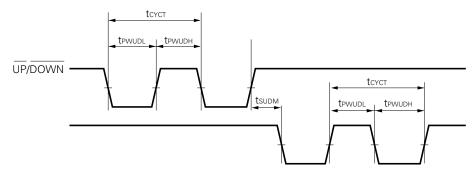


Fig. 2 Count Data Output Timing

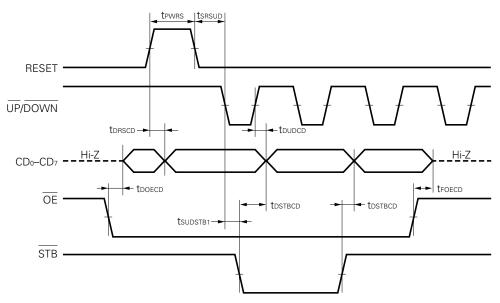


Fig. 3 Carry/Borrow Signal Output Timing

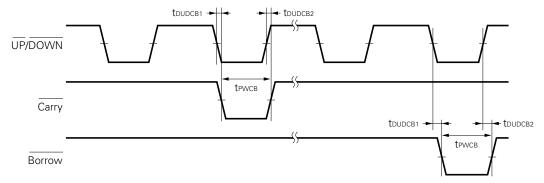
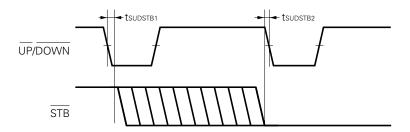
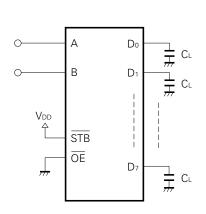


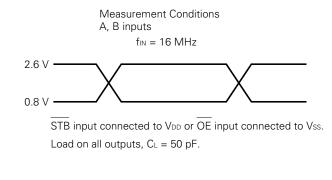
Fig. 4 Strobe Signal Output Timing



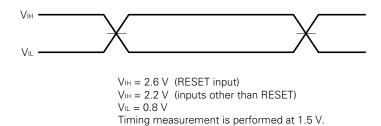


#### **Consumption Current Measurement Circuit**

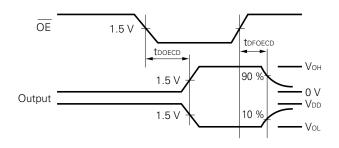


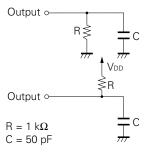


#### **AC Test Input Waveform**



#### • 3 state output

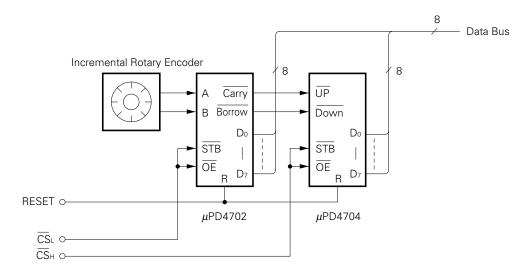






#### **Sample Application Circuits**

#### 16-bit counter



The application circuits and their parameters are for references only and are not intended for use in actual design-in's.



#### RECOMMENDED SOLDERING CONDITIONS

The following conditions (see table below) must be met when soldering this product.

Please consult with our sales offices in case other soldering process is used, or in case soldering is done under different conditions.

#### **TYPES OF SURFACE MOUNT DEVICE**

For more details, refer to our document "Semiconductor Device Mounting Technology Manual" (IEI-1207).

#### $\mu$ PD4704G

Soldering process	Soldering conditions	Symbol
Infrared ray reflow	Peak package's surface temperature: 235 °C or below, Reflow time: 30 seconds or below (210 °C or higher), Number of reflow process: 2, Exposure limit*: None	IR35-00-2
VPS	Peak package's surface temperature: 215 °C or below, Reflow time: 40 seconds or below (200 °C or higher), Number of reflow process: 2, Exposure limit*: None	VP15-00-2
Wave soldering	Solder temperature: 260 °C or below, Flow time: 10 seconds or below, Number of flow process: 1, Exposure limit*: None	WS60-00-1
Partial heating method	Terminal temperature: 300 °C or below, Flow time: 10 seconds or below, Exposure limit*: None	0

<sup>\*</sup> Exposure limit before soldering after dry-pack package is opened. Storage conditions: 25 °C and relative humidity at 65 % or less.

Note Do not apply more than a single process at once, except for "Partial heating method".

#### TYPES OF THROUGH HOLE MOUNT DEVICE

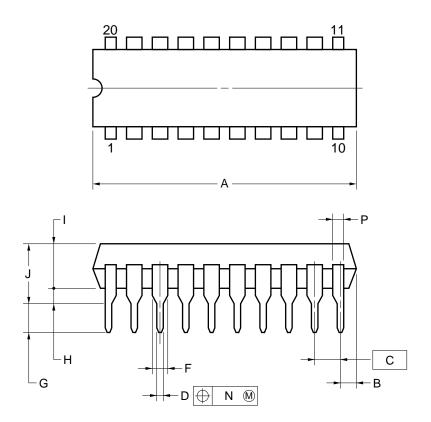
#### $\mu \mathsf{PD4704C}$

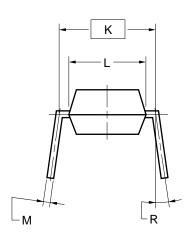
Soldering process	Soldering conditions	Symbol
Wave soldering	Solder temperature: 260 °C or below, Flow time: 10 seconds or below	

#### **REFERENCE**

Dcodument name	Document No.
NEC semiconductor device reliability/quality control system	IEI-1212
Quality grade on NEC semiconductor devices	IEI-1209
Semiconductor device mounting technology manual	IEI-1207
Semiconductor device package manual	IEI-1213
Guide to quality assurance for semiconductor devices	MEI-1202
Semiconductor selection guide	MF-1134

# 20PIN PLASTIC DIP (300 mil)





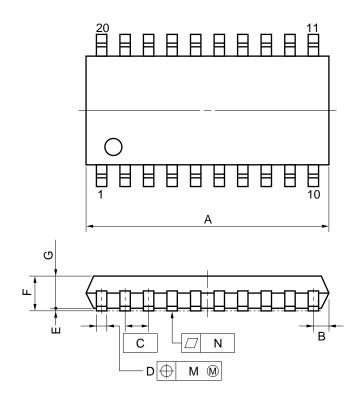
#### NOTES

- 1) Each lead centerline is located within 0.25 mm (0.01 inch) of its true position (T.P.) at maximum material condition.
- 2) Item "K" to center of leads when formed parallel.

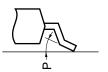
ITEM	MILLIMETERS	INCHES
Α	25.40 MAX.	1.000 MAX.
В	1.27 MAX.	0.050 MAX.
С	2.54 (T.P.)	0.100 (T.P.)
D	0.50±0.10	$0.020^{+0.004}_{-0.005}$
F	1.1 MIN.	0.043 MIN.
G	3.5±0.3	0.138±0.012
Н	0.51 MIN.	0.020 MIN.
I	4.31 MAX.	0.170 MAX.
J	5.08 MAX.	0.200 MAX.
K	7.62 (T.P.)	0.300 (T.P.)
L	6.4	0.252
М	$0.25^{+0.10}_{-0.05}$	$0.010^{+0.004}_{-0.003}$
N	0.25	0.01
Р	0.9 MIN.	0.035 MIN.
R	0~15°	0~15°

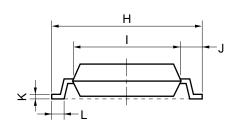
P20C-100-300A,C-1

# 20 PIN PLASTIC SOP (300 mil)



#### detail of lead end





#### NOTE

Each lead centerline is located within 0.12 mm (0.005 inch) of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS	INCHES
A	13.00 MAX.	0.512 MAX.
В	0.78 MAX.	0.031 MAX.
С	1.27 (T.P.)	0.050 (T.P.)
D	$0.40^{+0.10}_{-0.05}$	$0.016^{+0.004}_{-0.003}$
E	0.1±0.1	0.004±0.004
F	1.8 MAX.	0.071 MAX.
G	1.55	0.061
Н	7.7±0.3	0.303±0.012
I	5.6	0.220
J	1.1	0.043
K	$0.20^{+0.10}_{-0.05}$	$0.008^{+0.004}_{-0.002}$
L	0.6±0.2	$0.024^{+0.008}_{-0.009}$
М	0.12	0.005
N	0.10	0.004
Р	3°+7°	3°+7°

P20GM-50-300B, C-4



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Standard: Computers, office equipment, communications equipment, test and measurement equipment, audio and visual equipment, home electronic appliances, machine tools, personal electronic equipment and industrial robots

Special: Transportation equipment (automobiles, trains, ships, etc.), traffic control systems, anti-disaster systems, anti-crime systems, safety equipment and medical equipment (not specifically designed for life support)

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