

## Input voltage up to 80 VDC <br> Single output of 5.1-36 VDC <br> No input to output isolation

- High efficiency up to $96 \%$
- Wide input voltage range
- Low input to output differential voltage
- Very good dynamic properties
- Input undervoltage lock-out
- External output voltage adjustment and inhibit
- Two temperature ranges
- Continuous no-load and short-circuit proof
- No derating

Safety according to IEC/EN 60950
c\% ${ }^{\circ}$

Modules with input voltages up to 80 V are specially designed for secondary switched and battery driven applications. The case design allows operation at nominal load up to $71^{\circ} \mathrm{C}$ without additional cooling.

## Model Selection and Key Data

Table 1: Type survey

| Output voltage $V_{0}$ nom [V] | Output current Io nom [A] | Input voltage range $V_{\mathrm{i}}[\mathrm{V}]{ }^{1}$ | Input voltage <br> $V_{\text {i nom }}$ [V] | $\begin{array}{r} \text { Effic } \\ \eta_{\text {min }}[\%] \end{array}$ | ncy ${ }^{2}$ <br> $\eta_{\text {typ }}$ [\%] | Type designation | Options | Superseded old type (phased-out) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 5.1 | 12 | 7-40 | 20 | 82 | 83 | PSC 5A12-7iR | -9, L, P, C, D | PSR 512-7 |
| 5.1 | 10 | 8-80 | 40 | 76 | 79 | PSC 5A10-7iR |  | PSR 510-7 |
| 12 | 8 | 15-80 | 40 | 88 | 89 | PSC 128-7iR |  | PSR 128-7 |
| 15 | 8 | 19-80 | 40 | 90 | 91 | PSC 158-7iR |  | PSR 158-7 |
| 24 | 8 | 29-80 | 50 | 93 | 94 | PSC 248-7iR |  | PSR 248-7 |
| 36 | 8 | 42-80 | 60 | 95 | 96 | PSC 368-7iR |  | PSR 368-7 |

${ }^{1}$ See: Electrical Input Data: $\Delta V_{\mathrm{ion}}$ min (min. differential voltage $V_{i}-V_{0}$ ).
${ }^{2}$ Efficiency at $V_{\text {i nom }}$ and $I_{\text {o nom }}$.
Non standard input/output configurations or special custom adaptions are available on request.
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## Part Number Description


${ }^{1}$ Feature $R$ excludes option $P$ and vice versa.
Example: PSC 128-7LiPC = A positive switching regulator with a $12 \mathrm{~V}, 8 \mathrm{~A}$ output, ambient temperature range of -25 to $71^{\circ} \mathrm{C}$, input filter, inhibit input, output adjust potentiometer and thyristor crowbar.

## Functional Description

The switching regulators are designed using the buck converter topology. See also: Technical Information: Topologies. The input is not electrically isolated from the output. During the on period of the switching transistor, current is transferred to the output and energy is stored in the output choke in the form of flux. During the off period, this energy forces the current to continue flowing through the output, to the load and back through the freewheeling diode. Regulation is accomplished by varying the on to off duty ratio of the power switch.

These regulators are ideal for a wide range of applications, where input to output isolation is not necessary, or where already provided by an external front end (e.g. a transformer with rectifier). To optimise customer's needs, additional options and accessories are available.


Fig. 1
Block diagram

## Electrical Input Data

General Conditions: $T_{\mathrm{A}}=25^{\circ} \mathrm{C}$, unless $T_{\mathrm{C}}$ is specified
Table 2a: Input data

| Input |  |  | PSC 5A12 |  |  | PSC 5A10 |  |  | PSC 128 |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Characteristics |  | Conditions | min | typ | max | min | typ | max | min | typ | max |  |
| $V_{i}$ | Operating input voltage | $\begin{aligned} & I_{0}=0-I_{\text {onom }} \\ & T_{\mathrm{C} \text { min }}-T_{\mathrm{C} \text { max }} \end{aligned}$ | 7 |  | 40 | 8 |  | 80 | 15 |  | 80 | VDC |
| $\Delta V_{\text {io min }}$ | Min. diff. voltage $V_{i}-V_{0}{ }^{1}$ |  |  |  | 1.9 |  |  | 2.9 |  |  | 3 |  |
| $V_{\text {i }}$ 。 | Undervoltage lock-out |  |  | 6.3 |  |  | 7.3 |  |  | 7.3 |  |  |
| $l_{\text {i }}$ | No load input current | $I_{0}=0, V_{\text {imin }}-V_{\text {imax }}$ |  |  | 45 |  |  | 40 |  |  | 35 | mA |
| $l_{\text {inr }} \mathrm{p}$ | Peak value of inrush current | $\begin{aligned} & V_{\text {inom }} \\ & \text { without option L } \end{aligned}$ | 150 |  |  | 250 |  |  | 250 |  |  | A |
| $t_{\text {inr } r}$ | Rise time |  | 5 |  |  | 5 |  |  | 5 |  |  | $\mu \mathrm{s}$ |
| $t_{\text {inr }} \mathrm{h}$ | Time to half-value |  | 40 |  |  | 40 |  |  | 40 |  |  |  |
| $l_{\text {inr } p}$ | Peak value of inrush current | $V_{\text {inom }}$ with option L | 250 |  |  | 350 |  |  | 350 |  |  | A |
| $t_{\text {inr } r}$ | Rise time |  | 25 |  |  | 25 |  |  | 25 |  |  | $\mu \mathrm{s}$ |
| $t_{\text {inr }} \mathrm{h}$ | Time to half-value |  | 125 |  |  | 125 |  |  | 125 |  |  |  |
| $u_{i \text { RFI }}$ | Input RFI level, EN 55011/22 $0.15-30 \mathrm{MHz}$ | $V_{\text {inom }}, I_{\text {nom }}$ with option L ${ }^{2}$ |  |  | B |  |  | B |  |  | B |  |

Table 2b: Input data

| Input |  |  | PSC 158 |  |  | PSC 248 |  |  | PSC 368 |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Characteristics |  | Conditions | min | typ | max | min | typ | max | min | typ | max |  |
| $V_{i}$ | Operating input voltage | $\begin{aligned} & I_{0}=0-I_{\text {nom }} \\ & T_{\mathrm{C} \text { min }}-T_{\mathrm{C} \text { max }} \end{aligned}$ | 19 |  | 80 | 29 |  | 80 | 42 |  | 80 | VDC |
| $\Delta V_{\text {io min }}$ | Min. diff. voltage $V_{i}-V_{0}{ }^{1}$ |  |  |  | 4 |  |  | 5 |  |  | 61 |  |
| $V_{\text {io }}$ | Undervoltage lock-out |  |  | 7.3 |  |  | 12 |  |  | 19 |  |  |
| $l_{i 0}$ | No load input current | $I_{0}=0, V_{\text {imin }}-V_{\text {imax }}$ |  |  | 35 |  |  | 35 |  |  | 40 | mA |
| $l_{\text {inr }} \mathrm{p}$ | Peak value of inrush current | $\begin{array}{\|l} V_{\text {inom }} \\ \text { without option L } \end{array}$ | 250 |  |  | 250 |  |  | 250 |  |  | A |
| $t_{\text {inr } r}$ | Rise time |  | 5 |  |  | 5 |  |  | 5 |  |  | $\mu \mathrm{s}$ |
| $t_{\text {inr }} \mathrm{h}$ | Time to half-value |  | 40 |  |  | 40 |  |  | 40 |  |  |  |
| $l_{\text {inr } \mathrm{p}}$ | Peak value of inrush current | $\begin{array}{\|l} \hline V_{\text {inom }} \\ \text { with option L } \end{array}$ | 350 |  |  | 350 |  |  | 350 |  |  | A |
| $t_{\text {inr } r}$ | Rise time |  | 25 |  |  | 25 |  |  | 25 |  |  | $\mu \mathrm{s}$ |
| $t_{\text {inr }} \mathrm{h}$ | Time to half-value |  | 125 |  |  | 125 |  |  | 125 |  |  |  |
| $u_{\text {i RFI }}$ | Input RFI level, EN 55011/22 $0.15-30 \mathrm{MHz}$ | $V_{i \text { nom }}, I_{\text {o nom }}$ with option L2 |  |  | B |  |  | B |  |  | B |  |

${ }^{1}$ The minimum differential voltage $\Delta V_{\text {io min }}$ between input and output increases linearly by 0 to 1 V between $T_{\mathrm{A}}=46^{\circ} \mathrm{C}$ and $71^{\circ} \mathrm{C}$ ( $T_{\mathrm{C}}=70^{\circ} \mathrm{C}$ and $95^{\circ} \mathrm{C}$ )
${ }^{2}$ With additional external input capacitor $C_{e}=120 \mu \mathrm{~F} / 100 \mathrm{~V}$ (e.g. Nichicon PF series, or equivalent).

## External Input Circuitry

The sum of the lengths of the supply lines to the source or to the nearest capacitor $\geq 100 \mu \mathrm{~F}(\mathrm{a}+\mathrm{b})$ should not exceed 5 m unless option L is fitted. This option is recommended in order to prevent power line oscillations and reduce superimposed interference voltages. See also: Technical Information: Application Notes.


Fig. 2
Switching regulator with long supply lines.

## Electrical Output Data

General Conditions:
$-T_{\mathrm{A}}=25^{\circ} \mathrm{C}$, unless $T_{\mathrm{C}}$ is specified

- With R or option P, output voltage $V_{0}=V_{0 \text { nom }}$ at $I_{0 \text { nom }}$

Table 3a: Output data

| Outpu |  |  |  |  | C 5A |  |  | C 5A |  |  | C 12 |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Characteristics |  |  | Conditions | min | typ | max | min | typ | max | min | typ | max |  |
| V | Output voltage |  | $V_{\mathrm{i} \text { nom }}, l_{\text {o nom }}$ | 5.07 |  | 5.13 | 5.07 |  | 5.13 | 11.93 |  | 12.07 | V |
| 10 | Output current ${ }^{1}$ |  | $\begin{aligned} & V_{\mathrm{imin}}-V_{\mathrm{imax}} \\ & T_{\mathrm{C} \text { min }}-T_{\mathrm{C} \text { max }} \end{aligned}$ | 0 |  | 12.0 | 0 |  | 10.0 | 0 |  | 8.0 | A |
| $I_{0 L}$ | Output current limitation response |  |  | 12.0 |  | 15.6 | 10.0 |  | 13.0 | 8.0 |  | 10.4 |  |
| $u_{0}$ | Output voltage noise | Switching freq. | $V_{\mathrm{i} \text { nom }}, I_{\mathrm{o}}$ nom <br> IEC/EN $61204^{2}$ $B W=20 \mathrm{MHz}$ |  | 25 | 30 |  | 25 | 30 |  | 50 | 90 | mV Vp |
|  |  | Total |  |  | 29 | 34 |  | 29 | 34 |  | 54 | 94 |  |
| $\Delta V_{0} \mathrm{U}$ | Static line regulation |  | $V_{\mathrm{i} \text { min }}-V_{\mathrm{i} \text { max }}, I_{\text {onom }}$ |  | 30 | 45 |  | 30 | 45 |  | 50 | 75 | mV |
| $\Delta V_{01}$ | Static load regulation |  | $V_{\text {i nom, }}, I_{0}=0-I_{\text {o nom }}$ |  | 20 | 25 |  | 20 | 25 |  | 30 | 35 |  |
| $u_{0}$ d | Dynamic load regulation | Voltage deviat. | $\begin{aligned} & V_{\text {inom }} \\ & I_{0 \text { nom }} \leftrightarrow 1 / 3 I_{0 \text { nom }} \\ & \text { IEC/EN } 61204^{2} \\ & \hline \end{aligned}$ | 130 |  |  | 130 |  |  | 130 |  |  |  |
| $t_{\text {d }}$ |  | Recovery time |  | 40 |  |  | 50 |  |  | 60 |  |  | $\mu \mathrm{s}$ |
| $\alpha_{\text {Uo }}$ | Temperature coefficient $\Delta V_{0} / \Delta T_{\mathrm{C}}\left(T_{\mathrm{C} \text { min }}-T_{\mathrm{C} \text { max }}\right)$ |  | $\begin{aligned} & V_{\mathrm{i} \min }-V_{\mathrm{i} \max } \\ & I_{0}=0-I_{0 \text { nom }} \end{aligned}$ |  |  | $\pm 1$ |  |  | $\pm 1$ |  |  | $\pm 2$ | $\mathrm{mV} / \mathrm{K}$ |
|  |  |  |  |  | $\pm 0.02$ |  |  | $\pm 0.02$ |  |  | $\pm 0.02$ | \%/K |  |

Table 3b: Output data

| Outpu |  |  |  |  | C 15 |  |  | C 24 |  |  | C 36 |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Chara | teristics |  | Conditions | min | typ | max | min | typ | max | min | typ | max |  |
| V。 | Output voltage |  | $V_{\text {i nom }}, I_{\text {o nom }}$ | 14.91 |  | 15.09 | 23.86 |  | 24.14 | 35.78 |  | 36.22 | V |
| 10 | Output current ${ }^{1}$ |  | $V_{i \text { min }}-V_{i \text { max }}$ | 0 |  | 8.0 | 0 |  | 8.0 | 0 |  | 8.0 | A |
| $I_{0 L}$ | Output current limitation response |  | $T_{\mathrm{C} \text { min }}-T_{\mathrm{C} \text { max }}$ | 8.0 |  | 10.4 | 8.0 |  | 10.4 | 8.0 |  | 10.4 |  |
| $u_{0}$ | Output voltage noise | Switching freq. | $V_{\text {inom }}, I_{0}$ nom IEC/EN $61204^{2}$ $B W=20 \mathrm{MHz}$ |  | 50 | 90 |  | 55 | 150 |  | 80 | 190 | $m V_{p p}$ |
|  |  | Total |  |  | 54 | 94 |  | 60 | 155 |  | 85 | 195 |  |
| $\Delta V_{0} \mathrm{U}$ | Static line regulation |  | $V_{\text {i min }}-V_{\text {i max }}, I_{0}$ nom |  | 70 | 100 |  | 150 | 220 |  | 200 | 270 | mV |
| $\Delta V_{01}$ | Static load regulation |  | $V_{\text {i nom }}, I_{0}=0-I_{0}$ nom |  | 30 | 45 |  | 120 | 160 |  | 125 | 160 |  |
| $u_{0 \mathrm{~d}}$ | Dynamic <br> load regulation | Voltage deviat. | $\begin{aligned} & V_{\text {i nom }} \\ & I_{\text {nom }} \leftrightarrow 1 / 3 I_{0 \text { nom }} \\ & \text { IEC/EN } 61204^{2} \end{aligned}$ |  | 130 |  |  | 150 |  |  | 220 |  |  |
| $t_{\text {d }}$ |  | Recovery time |  |  | 60 |  |  | 80 |  |  | 100 |  | $\mu \mathrm{s}$ |
| $\alpha_{\text {Uo }}$ | Temperature coefficient $\Delta V_{0} / \Delta T_{\mathrm{C}}\left(T_{\mathrm{C} \text { min }}-T_{\mathrm{C}}\right.$ max $)$ |  | $\begin{aligned} & V_{i \min }-V_{\mathrm{imax}} \\ & I_{0}=0-I_{0 \text { nom }} \end{aligned}$ |  |  | $\pm 3$ |  |  | $\pm 5$ |  |  | $\pm 8$ | $\mathrm{mV} / \mathrm{K}$ |
|  |  |  |  |  | $\pm 0.02$ |  |  | $\pm 0.02$ |  |  | $\pm 0.02$ | \%/K |  |

[^0]

Fig. 3
Dynamic load regulation.

## Thermal Considerations

When a switching regulator is located in free, quasi-stationary air (convection cooling) at a temperature $T_{\mathrm{A}}=71^{\circ} \mathrm{C}$ and is operated at its nominal output current $I_{0}$ nom, the case temperature $T_{\mathrm{C}}$ will be about $95^{\circ} \mathrm{C}$ after the warm-up phase, measured at the Measuring point of case temperature $T_{\mathrm{C}}$ (see: Mechanical Data).
Under practical operating conditions, the ambient temperature $T_{\mathrm{A}}$ may exceed $71^{\circ} \mathrm{C}$, provided additional measures (heat sink, fan, etc.) are taken to ensure that the case temperature $T_{\mathrm{C}}$ does not exceed its maximum value of $95^{\circ} \mathrm{C}$.
Example: Sufficient forced cooling allows $T_{\mathrm{A} \max }=85^{\circ} \mathrm{C}$. A simple check of the case temperature $T_{\mathrm{C}}\left(T_{\mathrm{C}} \leq 95^{\circ} \mathrm{C}\right)$ at full load ensures correct operation of the system.


Fig. 4
Output current derating versus temperature

## Output Protection

A voltage suppressor diode which in worst case conditions fails into a short circuit (or a thyristor crowbar, option C) protects the output against an internally generated overvoltage. Such an overvoltage could occur due to a failure of either the control circuit or the switching transistor. The output protection is not designed to withstand externally applied overvoltages. The user should ensure that systems with Power-One power supplies, in the event of a failure, do not result in an unsafe condition (fail-safe).

## Parallel and Series Connection

Outputs of equal nominal voltages can be parallel-connected. However, the use of a single unit with higher output power, because of its power dissipation, is always a better solution.

In parallel-connected operation, one or several outputs may operate continuously at their current limit knee-point which will cause an increase of the heat generation. Consequently, the max. ambient temperature value should be reduced by 10 K .
Outputs can be series-connected with any other module. In series-connection the maximum output current is limited by the lowest current limitation. Electrically separated source voltages are needed for each module!

## Short Circuit Behaviour

A constant current limitation circuit holds the output current almost constant whenever an overload or a short circuit is applied to the regulator's output. It acts self-protecting and recovers - in contrary to the fold back method - automatically after removal of the overload or short circuit condition.


Fig. 5
Overload, short-circuit behaviour $V_{0}$ versus $I_{0}$.

## Auxiliary Functions

i Inhibit for Remote On and Off
Note: With open i-input, output is enabled ( $V_{0}=0 n$ )
The inhibit input allows the switching regulator output to be disabled via a control signal. In systems with several units, this feature can be used, for example, to control the activation sequence of the regulators by a logic signal (TTL, CMOS, etc.). An output voltage overshoot will not occur when switching on or off.


Fig. 6
Typical inhibit current $l_{\text {inh }}$ versus inhibit voltage $V_{\text {inh }}$


Fig. 7
Definition of $l_{\text {inh }}$ and $V_{\text {inh }}$


Fig. 8
Output response as a function of inhibit signal

Table 4: Inhibit characteristics

| Characteristics |  |  | Conditions | min | typ | max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $V_{\text {inh }}$ | Inhibit input voltage to keep regulator output voltage - | $V_{0}=$ on | $\begin{aligned} & V_{\mathrm{i}_{\text {min }}}-V_{\mathrm{imax}} \\ & T_{\mathrm{C} \text { min }}-T_{\mathrm{C} \text { max }} \end{aligned}$ | -50 |  | +0.8 | VDC |
|  |  | $V_{0}=0$ off |  | +2.4 |  | +50 |  |
| $t_{\mathrm{r}}$ | Switch-on time after inhibit command |  | $\begin{aligned} & V_{i}=V_{\text {inom }} \\ & R_{\mathrm{L}}=V_{\text {o nom }} / I_{\text {o nom }} \end{aligned}$ |  | 5 |  | ms |
| $t_{f}$ | Switch-off time after inhibit command |  |  |  | 10 |  |  |
| $l_{\text {i inh }}$ | Input current when inhibited |  | $V_{\mathrm{i}}=V_{\text {inom }}$ |  | 10 |  | mA |

R Control for Output Voltage Adjustment
Note: With open R input, $V_{0} \approx V_{\text {o nom. }}$ R excludes option P. (For superseded PSR types $V_{0} \approx 1.08 \cdot V_{0 \text { nom }}$ )
The output voltage $V_{0}$ can either be adjusted with an external voltage ( $V_{\text {ext }}$ ) or with an external resistor ( $R_{1}$ or $R_{2}$ ). The adjustment range is $0-108 \%$ of $V_{\text {onom }}$. The minimum differential voltage $\Delta V_{\text {io min }}$ between input and output (see: Electrical Input Data) should be maintained. Undervoltage lockout = Minimum input voltage.


Fig. 9
Voltage adjustment with $V_{\text {ext }}$ between $R$ and $G$ (Go-)
a) $V_{o}=0-108 \% V_{\text {onom }}$, using $V_{\text {ext }}$ between $R$ and $G(G o-)$

$$
V_{\mathrm{ext}} \approx 2.5 \mathrm{~V} \cdot \frac{V_{0}}{V_{\mathrm{onom}}} \quad V_{0} \approx V_{\mathrm{onom}} \cdot \frac{V_{\mathrm{ext}}}{2.5 \mathrm{~V}}
$$

Caution: To prevent damage $V_{\text {ext }}$ should not exceed 20 V , nor be negative and $R_{2}$ should never be less than $47 \mathrm{k} \Omega$.


Fig. 10
Voltage adjustment with external resistor $R_{1}$ or $R_{2}$
b) $V_{0}=0-100 \% V_{\text {o nom }}$, using $R_{1}$ between $R$ and $G$ (Go-):

$$
R_{1} \approx \frac{4000 \Omega \cdot V_{0}}{V_{\mathrm{onom}}-V_{0}} \quad V_{\mathrm{o}} \approx \frac{V_{\mathrm{onom}} \cdot R_{1}}{R_{1}+4000 \Omega}
$$

c) $V_{0}=V_{0 \text { nom }}-V_{0 \text { max }}$, using $R_{2}$ between $R$ and $V o+$ :
$V_{0 \text { max }}=V_{\text {onom }}+8 \%$

$$
\begin{aligned}
& R_{2} \approx \frac{4000 \Omega \cdot V_{0} \cdot\left(V_{0 \text { nom }}-2.5 \mathrm{~V}\right)}{2.5 \mathrm{~V} \cdot\left(V_{\mathrm{o}}-V_{\mathrm{onom}}\right)} \\
& V_{\mathrm{o}} \approx \frac{V_{\mathrm{onom}} \cdot 2.5 \mathrm{~V} \cdot R_{2}}{2.5 \mathrm{~V} \cdot\left(R_{2}+4000 \Omega\right)-V_{\mathrm{onom}} \cdot 4000 \Omega}
\end{aligned}
$$

## LED Output Voltage Indicator

A yellow output indicator LED shines when the output voltage is higher than approx. 3 V .

## Electromagnetic Compatibility (EMC)

## Electromagnetic Immunity

General condition: Case not earthed.
Table 5: Immunity type tests

| Phenomenon | Standard ${ }^{1}$ | Class Level | Coupling mode ${ }^{2}$ | Value applied | Waveform | Source Imped. | Test procedure | In oper | Perform. ${ }^{3}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 MHz burst disturbance | $\begin{aligned} & \hline \text { IEC } \\ & 60255-22-1 \end{aligned}$ | III | i/o, i/c, o/c | $2500 \mathrm{~V}_{\mathrm{p}}$ | 400 damped <br> 1 MHz waves/s | $200 \Omega$ | 2 s per coupling mode | yes | $A^{5}$ |
|  |  |  | +i/-i, +o/-o | $1000 \mathrm{~V}_{\mathrm{p}}$ |  |  |  |  |  |
| Voltage surge | IEC 60571-1 |  | i/c, +i/-i | $800 \mathrm{~V}_{\mathrm{p}}$ | $100 \mu \mathrm{~s}$ | $100 \Omega$ |  | yes | B |
|  |  |  |  | $1500 \mathrm{~V}_{\mathrm{p}}$ | $50 \mu \mathrm{~s}$ |  | 1 pos. and 1 neg. voltage surge per coupling mode |  |  |
|  |  |  |  | $3000 \mathrm{~V}_{\mathrm{p}}$ | $5 \mu \mathrm{~s}$ |  |  |  |  |
|  |  |  |  | $4000 \mathrm{~V}_{\mathrm{p}}$ | $1 \mu \mathrm{~s}$ |  |  |  |  |
|  |  |  |  | $7000 \mathrm{~V}_{\mathrm{p}}$ | 100 ns |  |  |  |  |
| Electrostatic discharge | $\begin{array}{\|l\|} \hline \text { IEC/EN } \\ 61000-4-2 \end{array}$ | 3 | contact discharge to case | $6000 \mathrm{~V}_{\mathrm{p}}$ | $1 / 50 \mathrm{~ns}$ | $330 \Omega$ | 10 positive and 10 negative discharges | yes | A ${ }^{4}$ |
| Electromagnetic field | $\begin{array}{\|l\|} \hline \text { IEC/EN } \\ 61000-4-3 \end{array}$ | 2 | antenna | $3 \mathrm{~V} / \mathrm{m}$ | $\begin{gathered} \hline \text { AM } 80 \% \\ 1 \mathrm{kHz} \end{gathered}$ |  | $80-1000 \mathrm{MHz}$ | yes | A |
| Electrical fast transients/burst | $\begin{aligned} & \text { IEC/EN } \\ & 61000-4-4 \end{aligned}$ | 3 | i/c, +i/-i | $2000 \mathrm{~V}_{\mathrm{p}}$ | bursts of $5 / 50 \mathrm{~ns}$ 5 kHz rep. rate transients with 15 ms burst duration and a 300 ms period | $50 \Omega$ | 60 s positive 60 s negative bursts per coupling mode | yes | A 45 |
|  |  | 4 |  | $4000 \mathrm{~V}_{\mathrm{p}}$ |  |  |  |  | $B^{45}$ |
| Surge | $\begin{aligned} & \text { IEC/EN } \\ & 61000-4-5 \end{aligned}$ | 3 | i/c | $2000 \mathrm{~V}_{\mathrm{p}}$ | 1.2/50 $\mu \mathrm{s}$ | $12 \Omega$ | 5 pos. and 5 neg. surges per coupling mode | yes | $B^{45}$ |
|  |  |  | +i/-i | $1000 \mathrm{~V}_{\mathrm{p}}$ |  | $2 \Omega$ |  |  |  |
| Conducted disturbances | $\begin{array}{\|l\|} \hline \text { IEC/EN } \\ 61000-4-6 \end{array}$ | 3 | i, o, signal wires | $\begin{aligned} & 140 \mathrm{~dB} \mathrm{\mu} \mathrm{~V} \\ & \text { (10 VAC) } \end{aligned}$ | AM 80\% 1 kHz | $150 \Omega$ | $0.15-80 \mathrm{MHz}$ | yes | A |

${ }^{1}$ For related and previous standards see: Technical Information: Safety \& EMC. ${ }^{2} \mathrm{i}=$ input, $\mathrm{o}=$ output, $\mathrm{c}=$ case.
${ }^{3} \mathrm{~A}=$ Normal operation, no deviation from specifications, B = Normal operation, temporary deviation from specs possible.
${ }^{4}$ Option L neccessary. ${ }^{5}$ With option C, manual reset might be necessary.

## Electromagnetic Emission

For emission levels refer to: Electrical Input Data.

Fig. 11
Typical disturbance voltage (quasi-peak) at the input according to EN 55011/22 measured at $V_{\mathrm{i} \text { nom }}$ and $I_{0 \text { nom }}$.


## Immunity to Environmental Conditions

Table 6: Mechanical stress

| Test | Method | Standard | Test Conditions |  | Status |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Ca | Damp heat steady state | IEC/DIN 60068-2-3 <br> MIL-STD-810D section 507.2 | Temperature: Relative humidity: Duration: | $\begin{aligned} & 40 \pm 2 \circ \mathrm{C} \\ & 93+2 l-3 \% \\ & 56 \text { days } \end{aligned}$ | Unit not operating |
| Ea | Shock (half-sinusoidal) | IEC/EN/DIN 60068-2-27 <br> MIL-STD-810D section 516.3 | Acceleration amplitude: <br> Bump duration: <br> Number of bumps: | $\begin{aligned} & 100 \mathrm{~g}_{\mathrm{n}}=981 \mathrm{~m} / \mathrm{s}^{2} \\ & 6 \mathrm{~ms} \\ & 18 \text { (3 each direction) } \end{aligned}$ | Unit operating |
| Eb | Bump (half-sinusoidal) | IEC/EN/DIN 60068-2-29 <br> MIL-STD-810D section 516.3 | Acceleration amplitude: <br> Bump duration: <br> Number of bumps: | $\begin{aligned} & 40 \mathrm{~g}_{\mathrm{n}}=392 \mathrm{~m} / \mathrm{s}^{2} \\ & 6 \mathrm{~ms} \\ & 6000 \text { (1000 each direction) } \end{aligned}$ | Unit operating |
| Fc | Vibration (sinusoidal) | IEC/EN/DIN 60068-2-6 <br> MIL-STD-810D section 514.3 | Acceleration amplitude: <br> Frequency (1 Oct/min): <br> Test duration: | $\begin{aligned} & 0.35 \mathrm{~mm}(10-60 \mathrm{~Hz}) \\ & 5 \mathrm{~g}_{\mathrm{n}}=49 \mathrm{~m} / \mathrm{s}^{2}(60-2000 \mathrm{~Hz}) \\ & 10-2000 \mathrm{~Hz} \\ & 7.5 \mathrm{~h}(2.5 \mathrm{~h} \text { each axis }) \end{aligned}$ | Unit operating |
| Fda | Random vibration wide band Reproducibility high | IEC 60068-2-35 DIN 40046 part 23 | Acceleration spectral density: <br> Frequency band: <br> Acceleration magnitude: <br> Test duration: | $\begin{aligned} & 0.05 \mathrm{~g}^{2} / \mathrm{Hz} \\ & 20-500 \mathrm{~Hz} \\ & 4.9 \text { grms } \\ & 3 \mathrm{~h} \text { (1 h each axis) } \end{aligned}$ | Unit operating |
| Kb | Salt mist, cyclic (sodium chloride NaCl solution) | IEC/EN/DIN 60068-2-52 | Concentration: <br> Duration: <br> Storage: <br> Storage duration: <br> Number of cycles: | $5 \%\left(30^{\circ} \mathrm{C}\right)$ <br> 2 h per cycle <br> $40^{\circ} \mathrm{C}, 93 \%$ rel. humidity <br> 22 h per cycle <br> 3 | Unit not operating |

Table 7: Temperature specifications, valid for air pressure of 800-1200 hPa (800-1200 mbar)

| Temperature |  |  | Standard -7 |  | Option -9 |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Characteristics |  | Conditions | min | max | min | max |  |
| $T_{\text {A }}$ | Ambient temperature | Operational ${ }^{1}$ | -25 | 71 | -40 | 71 | ${ }^{\circ} \mathrm{C}$ |
| $T_{\text {C }}$ | Case temperature |  | -25 | 95 | -40 | 95 |  |
| $T_{\text {S }}$ | Storage temperature | Non operational | -40 | 100 | -55 | 100 |  |

${ }^{1}$ See: Thermal Considerations

Table 8: MTBF and device hours

| MTBF | Ground Benign | Ground Fixed |  | Ground Mobile | Device Hours ${ }^{1}$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| MTBF acc. to MIL-HDBK-217F | $T_{\mathrm{C}}=40^{\circ} \mathrm{C}$ | $T_{\mathrm{C}}=40^{\circ} \mathrm{C}$ | $T_{\mathrm{C}}=70^{\circ} \mathrm{C}$ | $T_{\mathrm{C}}=50^{\circ} \mathrm{C}$ |  |
|  | 660000 | 143000 h | 81000 h | 68000 h | 2800000 h |

[^1]
## Mechanical Data

Dimensions in mm . Tolerances $\pm 0.3 \mathrm{~mm}$ unless otherwise specified. Projection

Fig. 12
Case C03, weight 440 g Aluminium, black finish and self cooling


## Safety and Installation Instructions

## Installation Instruction

Installation of the switching regulators must strictly follow the national safety regulations in compliance with the enclosure, mounting, creepage, clearance, casualty, markings and segregation requirements of the end-use application.
Check for hazardous voltages before altering any connections. Connections can be made using fast-on or soldering technique.

The input and the output circuit are not separated, i.e. the negative path is internally interconnected!
The units should be connected to a secondary circuit. Do not open the module.

Ensure that a unit failure (e.g. by an internal short-circuit) does not result in a hazardous condition. See also: Safety of operator accessible output circuit.

## Cleaning Agents

In order to avoid possible damage, any penetration of cleaning fluids is to be prevented, since the power supplies are not hermetically sealed.

## Protection Degree

The protection degree is IP 20.

## Standards and Approvals

All switching regulators are UL recognized according to UL 1950, UL 1012 and EN 60950, UL recognized for Canada to CAN/CSA C22.2 No. 234-M90
The units have been evaluated for:

- Building in,
- Operational insulation from input to output and input/output to case,
- The use in an overvoltage category II environment,
- The use in a pollution degree 2 environment.

The switching regulators are subject to manufacturing surveillance in accordance with the above mentioned UL and CSA and with ISO 9001 standards.

## Isolation

Electric strength test voltage between input interconnected with output against case: 750 VDC, 1 s .

This test is performed in the factory as routine test in accordance with EN50116, IEC/EN 60950 and UL 1950 and should not be repeated in the field. Power-One will not honour any guarantee claims resulting from electric strength field tests.

## Safety of Operator Accessible Output Circuit

If the output circuit of a switching regulator is operator-accessible, it shall be an SELV circuit according to IEC/EN 60950 related safety standards
The following table shows some possible installation configurations, compliance with which causes the output circuit of the switching regulator to be an SELV circuit according to IEC/EN 60950 up to a nominal output voltage of 30 V , or 48 V if option C is fitted.

However, it is the sole responsibility of the installer or user to assure the compliance with the relevant and applicable safety regulations.
More information is given in: Technical Information: Safety \& EMC.

Table 9: Insulation concept leading to an SELV output circuit

| Conditions Front end |  |  |  | Switching regulator <br> Measures to achieve the specified safety status of the output circuit | Result <br> Safety status of the switching regulator output circuit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Supply voltage | Minimum required grade of isolation, to be provided by the AC-DC front end, including mains supplied battery charger | Maximum DC output voltage from the front end ${ }^{1}$ | Minimum required safety status of the front end output circuit |  |  |
| Battery supply, considered as secondary circuit | Double or Reinforced | $\leq 60$ V | SELV circuit | None | SELV circuit |
|  |  | $>60 \mathrm{~V}$ | Earthed hazardous voltage secondary circuit ${ }^{2}$ | Input fuse ${ }^{3}$ non accessible case ${ }^{5}$ | Earthed SELV circuit |
|  |  |  | Unearthed hazardous voltage secondary circuit ${ }^{5}$ | Input fuse ${ }^{3}$ and unearthed, non accessible case ${ }^{5}$ | Unearthed SELV circuit |
|  |  |  | Hazardous voltage secondary circuit | Input fuse ${ }^{3}$ and earthed output circuit ${ }^{4}$ and non accessible case ${ }^{5}$ | Earthed SELV circuit |
| Mains$\leq 250 \text { V AC }$ | Basic | $\leq 60 \mathrm{~V}$ | Earthed SELV circuit ${ }^{4}$ | None |  |
|  |  |  | ELV circuit | Input fuse ${ }^{3}$ and earthed output circuit ${ }^{4}$ and non accessible case ${ }^{5}$ |  |
|  |  | $>60 \mathrm{~V}$ | Hazardous voltage secondary circuit |  |  |
|  | Double or reinforced | $\leq 60$ V | SELV circuit | None | SELV circuit |
|  |  | $>60 \mathrm{~V}$ | Double or reinforced insulated unearthed hazardous voltage secondary circuit ${ }^{5}$ | Input fuse ${ }^{3}$ and unearthed and non accessible case ${ }^{5}$ | Unearthed SELV circuit |

${ }^{1}$ The front end output voltage should match the specified input voltage range of the switching regulator.
${ }^{2}$ The conductor to the Gi- terminal of the switching regulator has to be connected to earth by the installer according to the relevant safety standard, e.g. IEC/EN 60950.
${ }^{3}$ The installer shall provide an approved fuse (slow blow type with the lowest current rating suitable for the application, max. 12.5 A) in a non-earthed input conductor directly at the input of the switching regulator. If Vo+ is earthed, insert the fuse in the Gi- line. For UL's purpose, the fuse needs to be UL-listed. If option C is fitted, a suitable fuse is already built-in in the Vi+ line.
${ }^{4}$ The earth connection has to be provided by the installer according to the relevant safety standard, e.g. IEC/EN 60950 .
${ }^{5}$ Has to be insulated from earth by double or reinforced insulation according to the relevant safety standard, based on the maximum output voltage from the front end.

## Description of Options

## -9 Extended Temperature Range

The operational ambient temperature range is extended to $T_{\mathrm{A}}=-40$ to $71^{\circ} \mathrm{C}$. ( $T_{\mathrm{C}}=-40$ to $95^{\circ} \mathrm{C}, T_{\mathrm{S}}=-55$ to $100^{\circ} \mathrm{C}$.)

## P Potentiometer

Option $P$ excludes R function. The output voltage $V_{0}$ can be adjusted with a screwdriver in the range from 0.92-1.08 of the nominal output voltage $V_{\text {o nom }}$.
However, the minimum differential voltage $\Delta V_{i o \text { min }}$ between input and output voltages as specified in: Electrical Input Data should be maintained.

## L Input Filter

Option L is recommended to reduce superimposed interference voltages and to prevent oscillations, if input lines exceed approx. 5 m in total length. The fundamental wave (approx. 120 kHz ) of the reduced interference voltage between $\mathrm{Vi}+$ and $\mathrm{Gi}-$ has, with an input line inductance of $5 \mu \mathrm{H}$, a maximum magnitude of 4 mVAC . A reduction can be achieved by insertion of a capacitor across the input (e.g. plastic foil between $\mathrm{Vi}+$ and $\mathrm{Gi}-$ ).

The input impedance of the switching regulator at 120 kHz is about $3.5 \Omega$. The harmonics are small in comparison with the fundamental wave. See also: Electrical Input Data: RFI.

With option L, the maximum permissible additionally superimposed ripple $u_{i}$ of the input voltage (rectifier mode) at a specified input frequency $f_{\mathrm{i}}$ has the following values:
Units with max input voltage 40 V :

$$
u_{\mathrm{i} \max }=12 \mathrm{~V}_{\mathrm{pp}} \text { at } 100 \mathrm{~Hz} \text { or } \mathrm{V}_{\mathrm{pp}}=1200 \mathrm{~Hz} / f_{\mathrm{i}} \cdot 1 \mathrm{~V}
$$

Units with max input voltage 80 V :

$$
u_{\mathrm{i} \max }=22 \mathrm{~V}_{\mathrm{pp}} \text { at } 100 \mathrm{~Hz} \text { or } \mathrm{V}_{\mathrm{pp}}=2200 \mathrm{~Hz} / f_{\mathrm{i}} \cdot 1 \mathrm{~V}
$$

## C Crowbar

This option is recommended to protect the load against power supply malfunction, but it is not designed to sink external currents.
A fixed-value monitoring circuit checks the output voltage $V_{0}$. When the trigger voltage $V_{0 \mathrm{c}}$ is reached, the thyristor crowbar triggers and disables the output. It may be deactivated by removal of the input voltage. In case of a switching transistor defect, an internal fuse prevents excessive current.
Note: As a central overvoltage protection device, the crowbar is usually connected to the external load via distributed inductance of the lines. For this reason, the overvoltage at the load can temporarily exceed the trigger voltage $V_{0}$ c. Depending on the application, further decentralized overvoltage protection elements may have to be used additionally.

Table 10: Crowbar trigger levels

| Characteristics |  | Conditions | 5.1 V |  | 12 V |  | 15 V |  | 24 V |  | 36 V |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | min | max | min | max | min | max | min | max | min | max |  |
| $V_{\text {oc }}$ | Trigger voltage | $\begin{aligned} & V_{i_{\text {min }}}-V_{i \text { max }} \\ & I_{0}=0-I_{\text {onom }} \\ & T_{\mathrm{C} \text { min }}-T_{\mathrm{C} \text { max }} \end{aligned}$ | 5.8 | 6.8 | 13.5 | 16 | 16.5 |  | 27 | 31 | 40 | 45.5 | V |
| $t_{\text {s }}$ | Delay time |  |  | 1.5 |  | 1.5 |  | 1.5 |  | 1.5 |  | 1.5 | $\mu \mathrm{s}$ |

D Save Data Input Undervoltage Monitor
Note: Output instead of input undervoltage monitor is available on request (Option D1).
Terminal D and Go- are connected to a normally conducting field effect transistor (JFET). The switching characteristics of the option D output are shown in fig. Definition of $V_{t}$ and $V_{\mathrm{H}}$. A 0.5 W Zener diode provides protection against overvoltages.
The voltage $V_{\mathrm{t}}$ can be externally adjusted with a trim potentiometer by means of a screwdriver. The hysteresis $V_{\mathrm{H}}$ of $V_{\mathrm{t}}$ is $<2 \%$. Terminal $D$ stays low for a minimum time $t_{\text {low min }}$, in order to prevent any oscillation. $V_{\mathrm{t}}$ can be set to a value between $V_{i \text { min }}$ and $V_{i \text { max }}$. Please note that the JFET becomes conductive when $V_{D}$ increases above 7 V approx.


Fig. 13
Test circuit with definition of voltage $V_{D}$ and current $I_{D}$


Fig. 14
Definition of $V_{\mathrm{t}}$ and $V_{\mathrm{H}}$

## Data

Table 11: Option D data

| Characteristics |  | Conditions | PSC |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | min | typ | max |  |
| $V_{\text {D low }}$ | Voltage - Terminal D at low impedance |  | $V_{i}<V_{\mathrm{t}}, l_{\text {d }}-2.5 \mathrm{~mA}$ |  |  | 0.8 | V |
| $V_{\text {D high }}$ | Voltage - Terminal D at high impedance | $V_{\mathrm{i}}>V_{\mathrm{t}}+V_{\mathrm{H}}, I_{\mathrm{D}}>25 \mu \mathrm{~A}$ | 4.75 |  |  |  |  |
| $t_{\text {tow min }}$ | Minimum duration $V_{\text {D low }}$ |  |  | 30 |  | ms |  |
| $t_{\text {D }}$ | Response time to $V_{\text {D low }}$ |  |  | 1 |  | $\mu \mathrm{s}$ |  |
| $I_{\text {max }}$ | Maximum current - Terminal D |  |  |  | 20 | mA |  |

Application examples:
a) The signal $V_{D}$ can be utilized in battery powered systems to provide a warning in case of low batteries.
b) In case of power failure, the signal can serve to initiate data save routines.

## Accessories

A variety of electrical and mechanical accessories are available including:

- PCB-tags and isolation pads for easy and safe PCBmounting.
- Ring core chockes for ripple and interference reduction.

For more detailed information please refer to: Accessories on the Power-One homepage.


NUCLEAR AND MEDICAL APPLICATIONS - Power-One products are not authorized for use as critical components in life support systems, equipment used in hazardous environments, or nuclear control systems without the express written consent of the respective divisional president of Power-One, Inc.

TECHNICAL REVISIONS - The appearance of products, including safety agency certifications pictured on labels, may change depending on the date manufactured. Specifications are subject to change without notice.

Changing the Shape of Power

## EC Declaration of Conformity

We<br>Power-One AG<br>Ackerstrasse 56 CH-8610 Uster

declare under our sole responsibility that all PSx Series switching regulators carrying the CE-mark are in conformity with the provisions of the Low Voltage Directive (LVD) 73/23/ EEC of the European Communities.

Conformity with the directive is presumed by conformity wih the following harmonized standards:

- EN 61204: 1995 (= IEC 61204: 1993, modified)

Low-voltage power supply devices, d.c. output - Perfomance characteristics and safety requirements

- EN 60950: 1992 + A1: 1993 + A2 (= IEC 950 second edition $1991+\mathrm{A} 1: 1992+$ A2: 1993)
Safety of information technology equipment

The installation instructions given in the corresponding data sheet describe correct installation leading to the presumption of conformity of the end product with the LVD. All PSx Series Switching Regulators are components, intended exclusively for inclusion within other equipment by an industrial assembly operation or by professional installers. They must not be operated as stand alone products.

Hence conformity with the Electromagnetic Compatibility Directive 89/336/EEC (EMC Directive) needs not to be declared. Nevertheless, guidance is provided in most product application notes on how conformity of the end product with the indicated EMC standards under the responsibility of the installer can be achieved, from which conformity with the EMC directive can be presumed.

Uster, 14 Oct. 2003
Power-One AG


Rolf Baldauf
Director Engineering


Director Projects and IP


[^0]:    ${ }^{1}$ See also: Thermal Considerations.
    ${ }^{2}$ See: Technical Information: Measuring and Testing.

[^1]:    ${ }^{1}$ Statistical values, based on an average of 4300 working hours per year and in general field use

