# 256K x 18 Bit Flow–Through BurstRAM Synchronous Fast Static RAM

The MCM69F819 is a 4M bit synchronous fast static RAM designed to provide a burstable, high performance, secondary cache for the PowerPC<sup>™</sup> and other high performance microprocessors. It is organized as 256K words of 18 bits each. This device integrates input registers, a 2–bit address counter, and high speed SRAM onto a single monolithic circuit for reduced parts count in cache data RAM applications. Synchronous design allows precise cycle control with the use of an external clock (K).

Addresses (SA), data inputs (DQx), and all control signals except output enable (G) and linear burst order (LBO) are clock (K) controlled through positive-edge-triggered noninverting registers.

Bursts can be initiated with either ADSP or ADSC input pins. Subsequent burst addresses can be generated internally by the MCM69F819 (burst <u>sequence</u> operates in linear or interleaved mode de<u>pendent</u> upon the state of LBO) and controlled by the burst address advance (ADV) input pin.

Write cycles are internally self–timed and are initiated by the rising edge of the clock (K) input. This feature eliminates complex off–chip write pulse generation and provides increased timing flexibility for incoming signals.

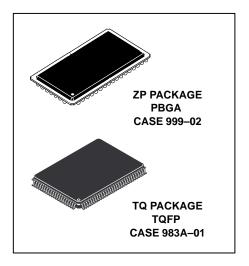
Synchronous byte write (SBx), synchronous global write (SGW), and synchronous write enable (SW) are provided to allow writes to either individual bytes or to all bytes. The two bytes are designated as "a" and "b". SBa controls DQa and SBb controls DQb. Individual bytes are written if the selected byte writes SBx are asserted with SW. All bytes are written if either SGW is asserted or if all SBx and SW are asserted.

For read cycles, a flow–through SRAM allows output data to simply flow freely from the memory array.

The MCM69F819 operates from a 3.3 V core power supply and all outputs operate on a 2.5 V or 3.3 V power supply. All inputs and outputs are JEDEC standard JESD8–5 compatible.

- MCM69F819-7.5: 7.5 ns Access/ 8.5 ns Cycle (117 MHz)
   MCM69F819-8: 8 ns Access/10 ns Cycle (100 MHz)
   MCM69F819-8.5: 8.5 ns Access/11 ns Cycle 90 MHz)
   MCM69F819-11: 11 ns Access/20 ns Cycle (50 MHz)
- 3.3 V + 10%, 5% Core Power Supply, 2.5 V or 3.3 V I/O Supply
- · ADSP, ADSC, and ADV Burst Control Pins
- Selectable Burst Sequencing Order (Linear/Interleaved)
- Single–Cycle Deselect Timing
- Internally Self–Timed Write Cycle
- · Byte Write and Global Write Control
- PB1 Version 2.0 Compatible
- JEDEC Standard 119–Pin PBGA and 100–Pin TQFP Packages

## MCM69F819

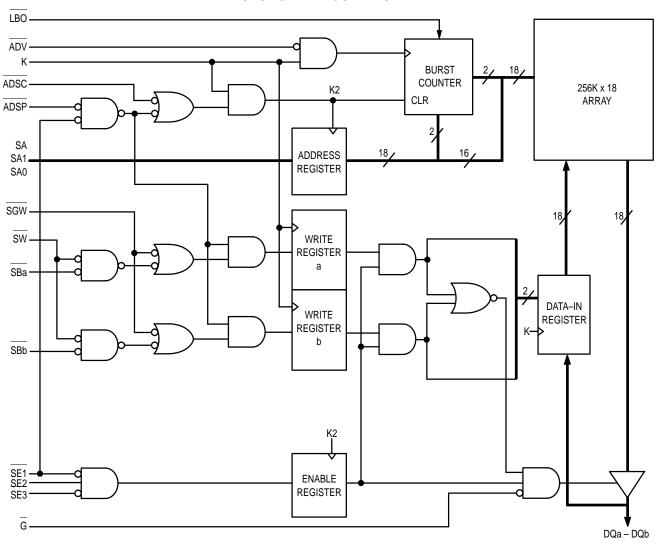


The PowerPC name is a trademark of IBM Corp., used under license therefrom.

REV 7 1/22/98

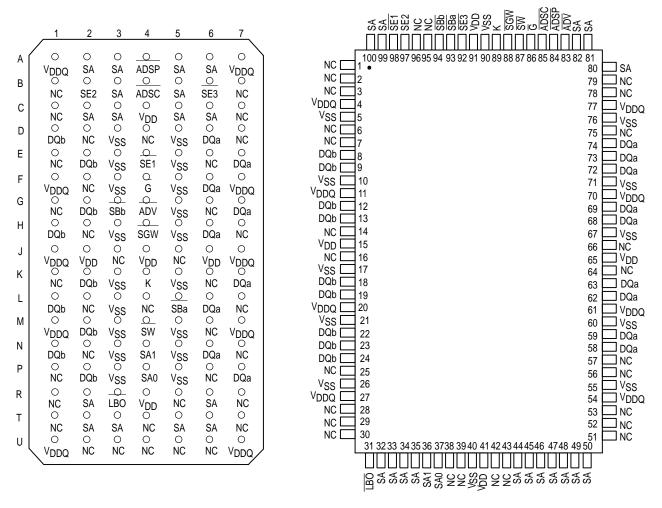


#### **FUNCTIONAL BLOCK DIAGRAM**



MCM69F819

#### **PIN ASSIGNMENTS**



**TOP VIEW 119 BUMP PBGA** 

**TOP VIEW 100 PIN TQFP** 

Not to Scale

#### **PBGA PIN DESCRIPTIONS**

Pin Locations	Symbol	Туре	Description
4B	ADSC	Input	Synchronous Address Status Controller: Active low, interrupts any ongoing burst and latches a new external address. Used to initiate a READ, WRITE, or chip deselect.
4A	ADSP	Input	Synchronous Address Status Processor: Active low, interrupts any ongoing burst and latches a new external address. Used to initiate a new READ, WRITE, or chip deselect (exception — chip deselect does not occur when ADSP is asserted and SE1 is high).
4G	ADV	Input	Synchronous Address Advance: Increments address count in accordance with counter type selected (linear/interleaved).
(a) 6D, 7E, 6F, 7G, 6H, 7K, 6L, 6N, 7P (b) 1D, 2E, 2G, 1H, 2K, 1L, 2M, 1N, 2P	DQx	I/O	Synchronous Data I/O: "x" refers to the byte being read or written (byte a, b).
4F	G	Input	Asynchronous Output Enable Input: Low — enables output buffers (DQx pins). High — DQx pins are high impedance.
4K	К	Input	Clock: This signal registers the address, data in, and all control signals except G and LBO.
3R	LBO	Input	Linear Burst Order Input: This pin must remain in steady state (this signal not registered or latched). It must be tied high or low.  Low — linear burst counter (68K/PowerPC).  High — interleaved burst counter (486/i960/Pentium).
2A, 3A, 5A, 6A, 3B, 5B, 2C, 3C, 5C, 6C, 2R, 6R, 2T, 3T, 5T, 6T	SA	Input	Synchronous Address Inputs: These inputs are registered and must meet setup and hold times.
4N, 4P	SA1, SA0	Input	Synchronous Address Inputs: These pins must be wired to the two LSBs of the address bus for proper burst operation. These inputs are registered and must meet setup and hold times.
5L, 3G (a) (b)	SBx	Input	Synch <u>rono</u> us Byte Wr <u>ite In</u> puts: "x" refers to the byte being written (byte a, b). SGW overrides SBx.
4E	SE1	Input	Synchronous Chip Enab <u>le: Ac</u> tive low to enable chip.  Negated high — blocks ADSP or deselects chip when ADSC is asserted.
2B	SE2	Input	Synchronous Chip Enable: Active high for depth expansion.
6B	SE3	Input	Synchronous Chip Enable: Active low for depth expansion.
4H	SGW	Input	Synchronous Global Write: This signal writes all bytes regardless of the status of the SBx and SW signals. If only byte write signals SBx are being used, tie this pin high.
4M	SW	Input	Synchronous Write: This signal writes only those bytes that have been selected using the byte write SBx pins. If only byte write signals SBx are being used, tie this pin low.
4C, 2J, 4J, 6J, 4R	V <sub>DD</sub>	Supply	Core Power Supply.
1A, 7A, 1F, 7F, 1J, 7J, 1M, 7M, 1U, 7U	V <sub>DDQ</sub>	Supply	I/O Power Supply.
3D, 5D, 3E, 5E, 3F, 5F, 5G, 3H, 5H, 3K, 5K, 3L, 3M, 5M, 3N, 5N, 3P, 5P	VSS	Supply	Ground.
1B, 7B, 1C, 7C, 2D, 4D, 7D, 1E, 6E, 2F, 1G, 6G, 2H, 7H, 3J, 5J, 1K, 6K, 2L, 4L, 7L, 6M, 2N, 7N, 1P, 6P, 1R, 5R, 7R, 1T, 4T, 7T, 2U, 3U, 4U, 5U, 6U	NC	_	No Connection: There is no connection to the chip.

MCM69F819 MOTOROLA FAST SRAM

#### **TQFP PIN DESCRIPTIONS**

Pin Locations	Symbol	Туре	Description
85	ADSC	Input	Synchronous Address Status Controller: Active low, interrupts any ongoing burst and latches a new external address. Used to initiate a READ, WRITE, or chip deselect.
84	ADSP	Input	Synchronous Address Status Processor: Active low, interrupts any ongoing burst and latches a new external address. Used to initiate a new READ, WRITE, or chip deselect (exception — chip deselect does not occur when ADSP is asserted and SE1 is high).
83	ADV	Input	Synchronous Address Advance: Increments address count in accordance with counter type selected (linear/interleaved).
(a) 58, 59, 62, 63, 68, 69, 72, 73, 74 (b) 8, 9, 12, 13, 18, 19, 22, 23, 24	DQx	I/O	Synchronous Data I/O: "x" refers to the byte being read or written (byte a, b).
86	G	Input	Asynchronous Output Enable Input: Low — enables output buffers (DQx pins). High — DQx pins are high impedance.
89	К	Input	Clock: This signal registers the address, data in, and all control signals except G and LBO.
31	LBO	Input	Linear Burst Order Input: This pin must remain in steady state (this signal not registered or latched). It must be tied high or low.  Low — linear burst counter (68K/PowerPC).  High — interleaved burst counter (486/i960/Pentium).
32, 33, 34, 35, 44, 45, 46, 47, 48, 49, 50, 80, 81, 82, 99, 100	SA	Input	Synchronous Address Inputs: These inputs are registered and must meet setup and hold times.
36, 37	SA1, SA0	Input	Synchronous Address Inputs: These pins must be wired to the two LSBs of the address bus for proper burst operation. These inputs are registered and must meet setup and hold times.
93, 94 (a) (b)	SBx	Input	Synch <u>rono</u> us Byte Wr <u>ite In</u> puts: "x" refers to the byte being written (byte a, b). SGW overrides SBx.
88	SGW	Input	Synchronous <u>Glo</u> bal <u>Write</u> : This signal writes all bytes regardless of the status of the SBx and SW signals. If only byte write signals SBx are being used, tie this pin high.
98	SE1	Input	Synchronous Chip Enab <u>le: Ac</u> tive low to enable chip.  Negated high — blocks ADSP or deselects chip when ADSC is asserted.
97	SE2	Input	Synchronous Chip Enable: Active high for depth expansion.
92	SE3	Input	Synchronous Chip Enable: Active low for depth expansion.
87	SW	Input	Synchronous Write: This sign <u>al writes only those bytes that have been</u> selected using the byte write SBx pins. If only byte write signals SBx are being used, tie this pin low.
15, 41, 65, 91	V <sub>DD</sub>	Supply	Core Power Supply.
4, 11, 20, 27, 54, 61, 70, 77	V <sub>DDQ</sub>	Supply	I/O Power Supply.
5, 10, 17, 21, 26, 40, 55, 60, 67, 71, 76, 90	V <sub>SS</sub>	Supply	Ground.
1, 2, 3, 6, 7, 14, 16, 25, 28, 29, 30, 38, 39, 42, 43, 51, 52, 53, 56, 57, 64, 66, 75, 78, 79, 95, 96	NC	_	No Connection: There is no connection to the chip.

#### TRUTH TABLE (See Notes 1 Through 5)

Next Cycle	Address Used	SE1	SE2	SE3	ADSP	ADSC	ADV	G 3	DQx	Write 2, 4
Deselect	None	1	Х	Х	Х	0	Х	Х	High-Z	Х
Deselect	None	0	Х	1	0	Х	Х	Х	High-Z	Х
Deselect	None	0	0	Х	0	Х	Х	Х	High-Z	Х
Deselect	None	Х	Х	1	1	0	Х	Х	High-Z	Х
Deselect	None	Х	0	Х	1	0	Х	Х	High-Z	Х
Begin Read	External	0	1	0	0	Х	Х	0	High-Z	χ5
Begin Read	External	0	1	0	1	0	Х	0	High-Z	READ <sup>5</sup>
Continue Read	Next	Х	Х	Х	1	1	0	1	High-Z	READ
Continue Read	Next	Х	Х	Х	1	1	0	0	DQ	READ
Continue Read	Next	1	Х	Х	Х	1	0	1	High-Z	READ
Continue Read	Next	1	Х	Х	Х	1	0	0	DQ	READ
Suspend Read	Current	Х	Х	Х	1	1	1	1	High-Z	READ
Suspend Read	Current	Х	Х	Х	1	1	1	0	DQ	READ
Suspend Read	Current	1	Х	Х	Х	1	1	1	High-Z	READ
Suspend Read	Current	1	Х	Х	Х	1	1	0	DQ	READ
Begin Write	External	0	1	0	1	0	Х	Х	High-Z	WRITE
Continue Write	Next	Х	Х	Х	1	1	0	Х	High-Z	WRITE
Continue Write	Next	1	Х	Х	Х	1	0	Х	High-Z	WRITE
Suspend Write	Current	Х	Х	Х	1	1	1	Х	High-Z	WRITE
Suspend Write	Current	1	Х	Х	Х	1	1	Х	High-Z	WRITE

#### NOTES:

- 1. X = Don't Care. 1 = logic high. 0 = logic low.
- 2. Write is defined as either 1) any SBx and SW low or 2) SGW is low.
- 3. G is an asynchronous signal and is not sampled by the clock K. G drives the bus immediately  $(t_{GLQX})$  following  $\overline{G}$  going low.
- 4. On write cycles that follow read cycles, G must be negated prior to the start of the write cycle to ensure proper write data setup times. G must also remain negated at the completion of the write cycle to ensure proper write data hold times.
- 5. This read assumes the RAM was previously deselected.

#### LINEAR BURST ADDRESS TABLE (LBO = VSS)

1st Address (External)	2nd Address (Internal)	3rd Address (Internal)	4th Address (Internal)
X X00	X X01	X X10	X X11
X X01	X X10	X X11	X X00
X X10	X X11	X X00	X X01
X X11	X X00	X X01	X X10

#### INTERLEAVED BURST ADDRESS TABLE (LBO = VDD)

1st Address (External)	2nd Address (Internal)	3rd Address (Internal)	4th Address (Internal)
X X00	X X01	X X10	X X11
X X01	X X00	X X11	X X10
X X10	X X11	X X00	X X01
X X11	X X10	X X01	X X00

#### WRITE TRUTH TABLE

Cycle Type	SGW	sw	SBa	SBb
Read	Н	Н	Х	Х
Read	Н	L	Н	Н
Write Byte a	Н	L	L	Н
Write Byte b	Н	L	Н	L
Write All Bytes	Н	L	L	L
Write All Bytes	L	Х	Х	Х

#### ABSOLUTE MAXIMUM RATINGS (See Note 1)

Rating	Symbol	Value	Unit	Notes
Power Supply Voltage	V <sub>DD</sub>	V <sub>SS</sub> – 0.5 to + 4.6	V	
I/O Supply Voltage	V <sub>DDQ</sub>	$V_{SS}$ – 0.5 to $V_{DD}$	V	2
Input Voltage Relative to V <sub>SS</sub> for Any Pin Except V <sub>DD</sub>	V <sub>in</sub> , V <sub>out</sub>	V <sub>SS</sub> - 0.5 to V <sub>DD</sub> + 0.5	V	2
Input Voltage (Three–State I/O)	VIT	V <sub>SS</sub> – 0.5 to V <sub>DDQ</sub> + 0.5	V	2
Output Current (per I/O)	l <sub>out</sub>	± 20	mA	
Package Power Dissipation	PD	1.6	W	3
Ambient Temperature	TA	0 to 70	°C	
Die Temperature	TJ	110	°C	3
Temperature Under Bias	T <sub>bias</sub>	– 10 to 85	°C	
Storage Temperature	T <sub>stg</sub>	- 55 to 125	°C	

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to this high—impedance circuit.

#### NOTES:

- Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to RECOMMENDED OPER-ATING CONDITIONS. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.
- 2. This is a steady–state DC parameter that is in effect after the power supply has achieved its nominal operating level. Power sequencing is not necessary.
- Power dissipation capability is dependent upon package characteristics and use environment. See Package Thermal Characteristics.

#### PACKAGE THERMAL CHARACTERISTICS — PBGA

Rating		Symbol	Max	Unit	Notes
Junction to Ambient (@ 200 lfm)	Single Layer Board Four Layer Board	$R_{ heta JA}$	38 22	°C/W	1, 2
Junction to Board (Bottom)		$R_{\theta JB}$	14	°C/W	3
Junction to Case (Top)		$R_{\theta JC}$	5	°C/W	4

#### NOTES:

- 1. Junction temperature is a function of on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, board population, and board thermal resistance.
- 2. Per SEMI G38-87.
- 3. Indicates the average thermal resistance between the die and the printed circuit board.
- 4. Indicates the average thermal resistance between the die and the case top surface via the cold plate method (MIL SPEC-883 Method 1012.1).

#### PACKAGE THERMAL CHARACTERISTICS — TQFP

Rating	Symbol	Max	Unit	Notes
Junction to Ambient (@ 200 lfm) Single Layer Board Four Layer Board		40 25	°C/W	1, 2
Junction to Board (Bottom)	$R_{\theta JB}$	17	°C/W	3
Junction to Case (Top)	$R_{ heta JC}$	9	°C/W	4

#### NOTES:

- 1. Junction temperature is a function of on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, board population, and board thermal resistance.
- 2. Per SEMI G38-87.
- 3. Indicates the average thermal resistance between the die and the printed circuit board.
- 4. Indicates the average thermal resistance between the die and the case top surface via the cold plate method (MIL SPEC-883 Method 1012.1).

#### DC OPERATING CONDITIONS AND CHARACTERISTICS

 $(V_{DD} = 3.3 \text{ V} + 10\%, -5\%, T_{A} = 0 \text{ to } 70^{\circ}\text{C}, \text{ Unless Otherwise Noted})$ 

### **RECOMMENDED OPERATING CONDITIONS: 2.5 V I/O Supply** (Voltages Referenced to $V_{SS} = 0 V$ )

Parameter	Symbol	Min	Тур	Max	Unit
Supply Voltage	V <sub>DD</sub>	3.135	3.3	3.6	V
I/O Supply Voltage	V <sub>DDQ</sub>	2.375	2.5	2.9	V
Input Low Voltage	VIL	- 0.3	_	0.7	V
Input High Voltage	VIH	1.7	_	V <sub>DD</sub> + 0.3	V
Input High Voltage (I/O Pins)	V <sub>IH2</sub>	1.7	_	V <sub>DDQ</sub> + 0.3	V

#### **RECOMMENDED OPERATING CONDITIONS: 3.3 V I/O Supply** (Voltages Referenced to $V_{SS} = 0 \text{ V}$ )

Parameter	Symbol	Min	Тур	Max	Unit
Supply Voltage	V <sub>DD</sub>	3.135	3.3	3.6	V
I/O Supply Voltage	V <sub>DDQ</sub>	3.135	3.3	$V_{DD}$	V
Input Low Voltage	V <sub>IL</sub>	- 0.5	_	0.8	V
Input High Voltage	V <sub>IH</sub>	2	_	V <sub>DD</sub> + 0.5	V
Input High Voltage (I/O Pins)	V <sub>IH2</sub>	2	_	V <sub>DDQ</sub> + 0.5	V

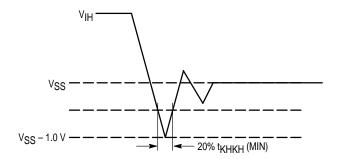


Figure 1. Undershoot Voltage

#### DC CHARACTERISTICS AND SUPPLY CURRENTS

Parameter	Symbol	Min	Тур	Max	Unit	Notes
Input Leakage Current (0 $V \le V_{in} \le V_{DD}$ )	l <sub>lkg(l)</sub>	_	_	± 1	μΑ	
Output Leakage Current (0 V $\leq$ V <sub>in</sub> $\leq$ V <sub>DDQ</sub> )	I <sub>lkg(O)</sub>	_	_	± 1	μА	
AC Supply Current (Device Selected, All Outputs Open, Freq = Max) Includes VDD Only  MCM69F819-8.5 MCM69F819-11	I <sub>DDA</sub>	_	_	350 325 300 250	mA	1, 2, 3
CMOS Standby Supply Current (Device Deselected, Freq = 0, $V_{DD}$ = Max, All Inputs Static at CMOS Levels)	I <sub>SB2</sub>	_	_	45	mA	4, 5
TTL Standby Supply Current (Device Deselected, Freq = 0, V <sub>DD</sub> = Max, All Inputs Static at TTL Levels)	ISB3	_	_	50	mA	4, 6
Clock Running (Device Deselected, MCM69F819–7.5 Freq = Max, V <sub>DD</sub> = Max, MCM69F819–8 MCM69F819–8.5 MCM69F819–11	I <sub>SB4</sub>	_	_	190 175 165 145	mA	4, 5
Static Clock Running (Device Deselected, Freq = Max, V <sub>DD</sub> = Max, All Inputs Static at TTL Levels)	I <sub>SB5</sub>	_	_	95	mA	4, 6
Output Low Voltage (I <sub>OL</sub> = 2 mA) V <sub>DDQ</sub> = 2.5 V	V <sub>OL</sub>	_	_	0.7	V	
Output High Voltage ( $I_{OL} = -2 \text{ mA}$ ) $V_{DDQ} = 2.5 \text{ V}$	Vон	1.7	_	_	V	
Output Low Voltage (I <sub>OL</sub> = 8 mA) V <sub>DDQ</sub> = 3.3 V	V <sub>OL2</sub>	_	_	0.4	V	
Output High Voltage (I <sub>OL</sub> = -4 mA) V <sub>DDQ</sub> = 3.3 V	V <sub>OH2</sub>	2.4	_	_	V	

#### NOTES:

- 1. Reference AC Operating Conditions and Characteristics for input and timing.
- 2. All addresses transition simultaneously low (LSB) then high (MSB).
- 3. Data states are all zero.
- 4. Device is deselected as defined by the Truth Table.
- 5. CMOS levels for I/O's are  $V_{IT} \le V_{SS} + 0.2 \text{ V}$  or  $\ge V_{DDQ} 0.2 \text{ V}$ . CMOS levels for other inputs are  $V_{in} \le V_{SS} + 0.2 \text{ V}$  or  $\ge V_{DD} 0.2 \text{ V}$ . 6. TTL levels for I/O's are  $V_{IT} \le V_{IL}$  or  $\ge V_{IH2}$ . TTL levels for other inputs are  $V_{in} \le V_{IL}$  or  $\ge V_{IH2}$ .

#### $\textbf{CAPACITANCE} \text{ (f = 1.0 MHz, dV = 3.0 V, T}_{A} = 0 \text{ to } 70^{\circ}\text{C}, \text{ Periodically Sampled Rather Than 100\% Tested)}$

Parameter	Symbol	Min	Тур	Max	Unit
Input Capacitance	C <sub>in</sub>	_	4	5	pF
Input/Output Capacitance	C <sub>I/O</sub>	_	7	8	pF

#### **AC OPERATING CONDITIONS AND CHARACTERISTICS**

 $(V_{DD} = 3.3 \text{ V} + 10\%, -5\%, T_{A} = 0 \text{ to } 70^{\circ}\text{C}, \text{ Unless Otherwise Noted})$ 

Input Timing Measurement Reference Level 1.25 V	Output Timing Reference Level 1.25 V
Input Pulse Levels 0 to 2.5 V	Output Load See Figure 2 Unless Otherwise Noted
Input Rise/Fall Time 1.0 V/ns (20 to 80%)	

#### READ/WRITE CYCLE TIMING (See Notes 1 and 2)

			F819–7.5 MHz		F819–8 MHz	MCM69F 90 F	F819–8.5 VIHz	MCM69 50 N	F819–11 VIHz		
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Unit	Notes
Cycle Time	tKHKH	8.5	_	10	_	11	_	20	_	ns	
Clock High Pulse Width	<sup>t</sup> KHKL	3	_	4	_	4.5	_	4.5	_	ns	
Clock Low Pulse Width	<sup>t</sup> KLKH	3	_	4	_	4.5	_	4.5	_	ns	
Clock Access Time	<sup>t</sup> KHQV	_	7.5	_	8	_	8.5	_	11	ns	
Output Enable to Output Valid	tGLQV	_	3.5	_	3.5	_	3.5	_	3.5	ns	
Clock High to Output Active	<sup>t</sup> KHQX1	0	_	0	_	0	_	0	_	ns	3, 4, 5
Clock High to Output Change	tKHQX2	2	_	2	_	2	_	2	_	ns	3, 4
Output Enable to Output Active	tGLQX	0	_	0	_	0	_	0	_	ns	3, 4
Output Disable to Q High–Z	<sup>t</sup> GHQZ	_	3.5	_	3.5	_	3.5	_	3.5	ns	3, 4
Clock High to Q High–Z	tKHQZ	2	3.5	2	3.5	2	3.5	2	3.5	ns	3, 4, 5
Setup Times: Address ADSP, ADSC, ADV Data In Write Chip Enable	tADKH tADSKH tDVKH tWVKH tEVKH	1.5	_	2	_	2	_	2	_	ns	
Hold Times: Address ADSP, ADSC, ADV Data In Write Chip Enable	tKHAX tKHADSX tKHDX tKHWX tKHEX	0.5	_	0.5	_	0.5	_	0.5	_	ns	

#### NOTES:

- 1. Write is defined as either any SBx and SW low or SGW is low. Chip Enable is defined as SE1 low, SE2 high, and SE3 low whenever ADSP or ADSC is asserted.
- 2. All read and write cycle timings are referenced from K or G.
- 3. Measured at  $\pm$  200 mV from steady state.
- 4. This parameter is sampled and not 100% tested.
- 5. At any given voltage and temperature, tKHOZ max is less than tKHOX1 min for a given device and from device to device.

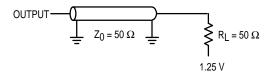


Figure 2. AC Test Load

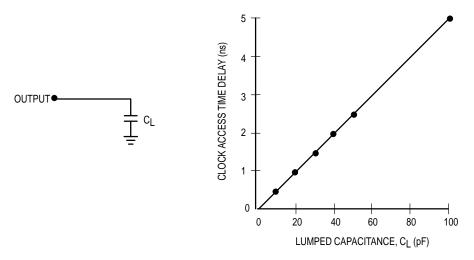
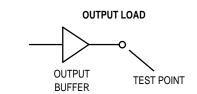
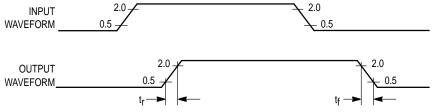


Figure 3. Lumped Capacitive Load and Typical Derating Curve



#### UNLOADED RISE AND FALL TIME MEASUREMENT

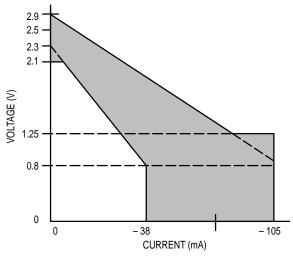


#### NOTES:

- 1. Input waveform has a slew rate of 1 V/ns.
- 2. Rise time is measured from 0.5 to 2.0 V unloaded.
- 3. Fall time is measured from 2.0 to 0.5 V unloaded.

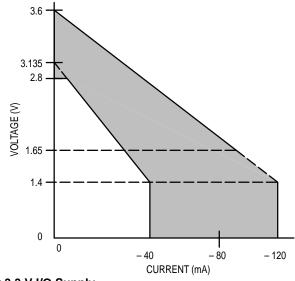
Figure 4. Unloaded Rise and Fall Time Characterization

PULL-UP						
VOLTAGE (V)	I (mA) MIN	I (mA) MAX				
- 0.5	- 38	- 105				
0	- 38	- 105				
0.8	- 38	- 105				
1.25	- 26	- 83				
1.5	- 20	- 70				
2.3	0	- 30				
2.7	0	- 10				
2.9	0	0				



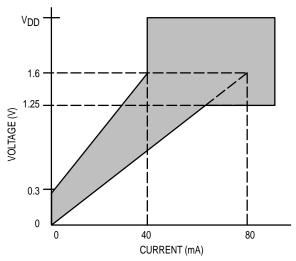
## (a) Pull-Up for 2.5 V I/O Supply

PULL-UP							
VOLTAGE (V)	I (mA) MIN	I (mA) MAX					
- 0.5	- 50	- 150					
0	- 50	- 150					
1.4	- 50	- 150					
1.65	- 46	- 130					
2.0	- 35	- 101					
3.135	0	- 25					
3.6	0	0					



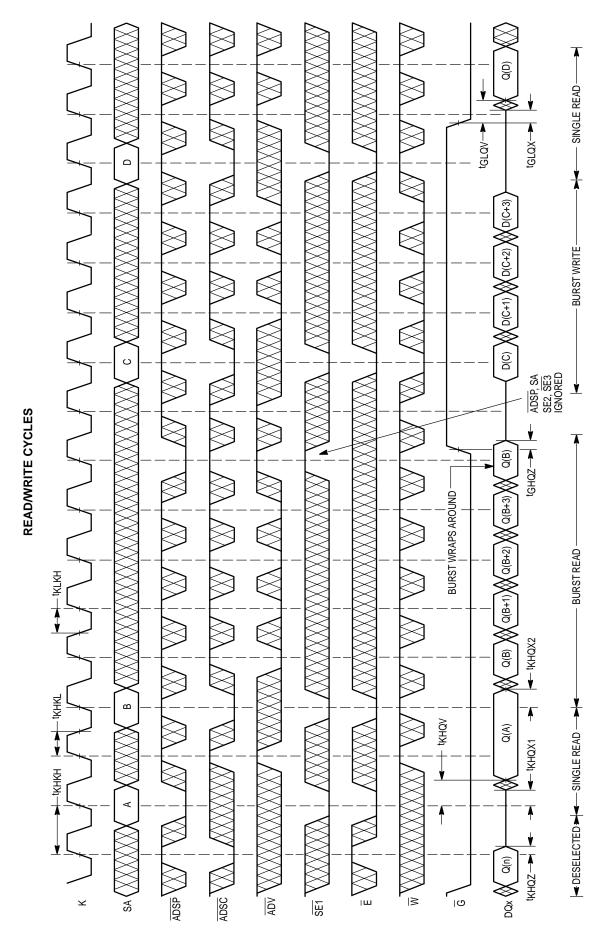
### (b) Pull-Up for 3.3 V I/O Supply

PULL-DOWN						
VOLTAGE (V)	I (mA) MIN	I (mA) MAX				
- 0.5	0	0				
0	0	0				
0.4	10	20				
0.8	20	40				
1.25	31	63				
1.6	40	80				
2.8	40	80				
3.2	40	80				
3.4	40	80				



(c) Pull-Down

Figure 5. Typical Output Buffer Characteristics



NOTE:  $\overline{E}$  low = SE2 high and  $\overline{SE3}$  low.  $\overline{\overline{W}}$  low =  $\overline{SGW}$  low and/or  $\overline{SW}$  and  $\overline{SBx}$  low.

#### APPLICATION INFORMATION

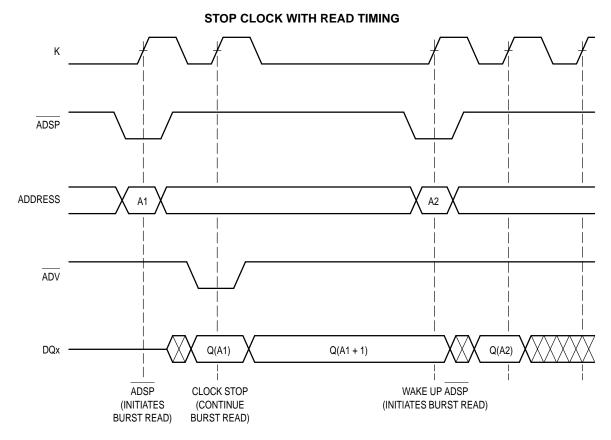
#### STOP CLOCK OPERATION

In the stop clock mode of operation, the SRAM will hold all state and data values even though the clock is not running (full static operation). The SRAM design allows the clock to start with ADSP and ADSC, and stops the clock after the last write data is latched, or the last read data is driven out.

When starting and stopping the clock, the AC clock timing and parametrics must be strictly maintained. For example, clock pulse width and edge rates must be guaranteed when starting and stopping the clocks. To achieve the lowest power operation for all three stop clock modes, stop read, stop write, and stop deselect:

To achieve the lowest power operation for all three stop clock modes, stop read, stop write, and stop deselect:

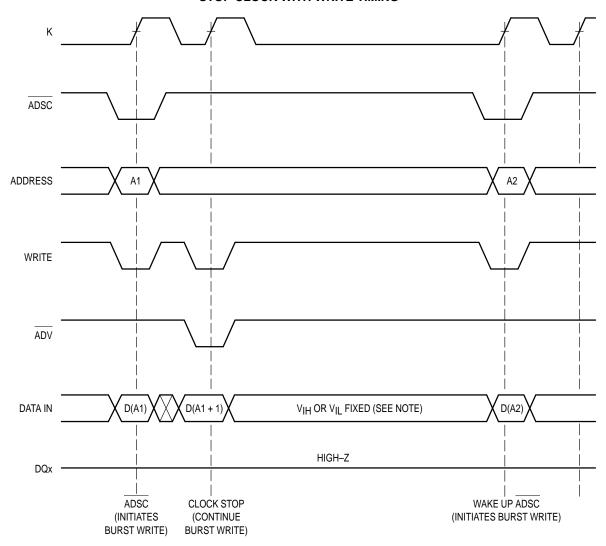
- · Force the clock to a low state.
- Force the control signals to an inactive state (this guarantees any potential source of noise on the clock input will not start an unplanned on activity).
- Force the address inputs to a low state (V<sub>IL</sub>), preferably < 0.2 V.</li>



NOTE: For lowest possible power consumption during stop clock, the addresses should be driven to a low state (V<sub>IL</sub>). Best results are obtained if  $V_{IL} < 0.2 \text{ V}$ .

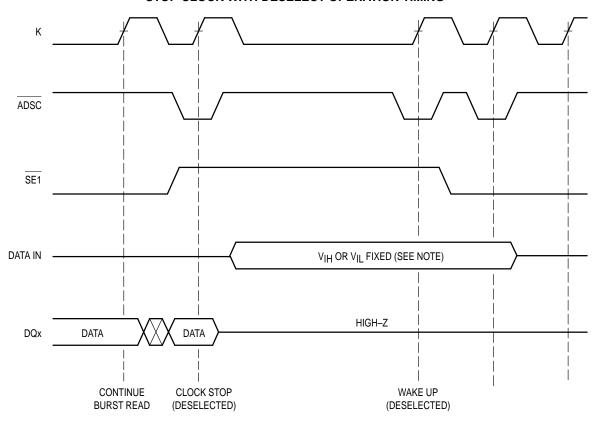
MCM69F819 MOTOROLA FAST SRAM

#### STOP CLOCK WITH WRITE TIMING



NOTE: While the clock is stopped, DATA IN must be fixed in a high (V<sub>IH</sub>) or low (V<sub>IL</sub>) state to reduce the DC current of the input buffers. For lowest power operation, all data and address lines should be held in a low (V<sub>IL</sub>) state and control lines held in an inactive state.

#### STOP CLOCK WITH DESELECT OPERATION TIMING



NOTE: While the clock is stopped, DATA IN must be fixed in a high (V<sub>IH</sub>) or low (V<sub>IL</sub>) state to reduce the DC current of the input buffers. For lowest power operation, all data and address lines should be held in a low (V<sub>IL</sub>) state and control lines held in an inactive state.

MCM69F819 MOTOROLA FAST SRAM

#### NON-BURST SYNCHRONOUS OPERATION

Although this BurstRAM has been designed for PowerPC-based and other high end MPU-based systems, these SRAMs can be used in other high speed L2 cache or memory applications that do not require the burst address feature. Most L2 caches designed with a synchronous interface can make use of the MCM69F819. The burst counter feature of the BurstRAM can be disabled, and the SRAM can be configured to act upon a continuous stream of addresses. See Figure 6.

#### CONTROL PIN TIE VALUES EXAMPLE $(H \ge V_{IH}, L \le V_{II})$

Non-Burst	ADSP	ADSC	ADV	SE1	SE2	LBO
Sync Non–Burst, Flow–Through SRAM	Н	L	I	L	Η	Х

NOTE: Although X is specified in the table as a don't care, the pin must be tied either high or low.

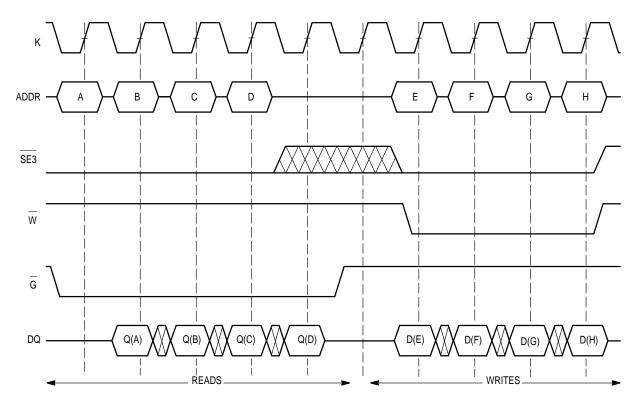
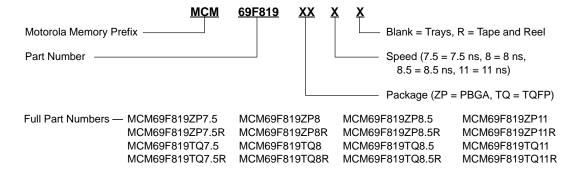


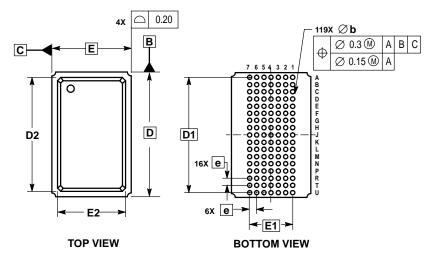
Figure 6. Example Configuration as Non-Burst Synchronous SRAM

# ORDERING INFORMATION (Order by Full Part Number)



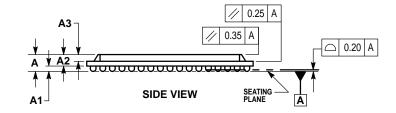
#### **PACKAGE DIMENSIONS**

#### **ZP PACKAGE** 7 x 17 BUMP PBGA **CASE 999-02**



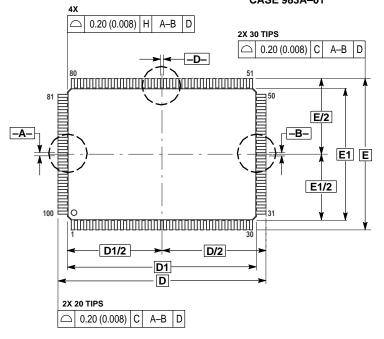
- NOTES:
  1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
  2. ALL DIMENSIONS IN MILLIMETERS.
  3. DIMENSION IS THE MAXIMUM SOLDER BALL DIAMETER MEASURED PARALLEL TO DATUM A.
  4. DATUM A, THE SEATING PLANE, IS DEFINED BY THE SPHERICAL CROWNS OF THE SOLDER BALLS.

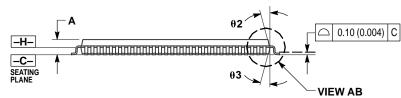
	MILLIMETERS					
DIM	MIN	MAX				
Α		2.40				
A1	0.50	0.70				
A2	1.30	1.70				
A3	0.80	1.00				
D	22.00 BSC					
D1	20.32	BSC				
D2	19.40	19.60				
E	14.00 BSC					
E1	7.62	BSC				
E2	11.90	12.10				
b	0.60	0.90				
е	1.27 BSC					

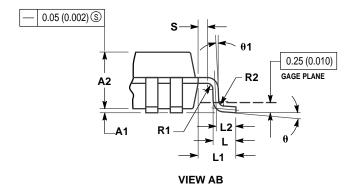


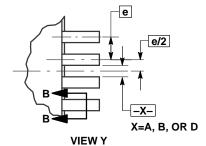
MCM69F819 MOTOROLA FAST SRAM

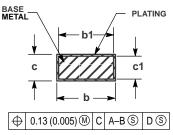
#### **TQ PACKAGE TQFP** CASE 983A-01











#### SECTION B-B

- NOTES:

  1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

  2. CONTROLLING DIMENSION: MILLIMETER.

  3. DATUM PLANE -H- IS LOCATED AT BOTTOM OF LEAD AND IS COINCIDENT WITH THE LEAD WHERE THE LEAD EXITS THE PLASTIC BODY AT THE BOTTOM OF THE PARTING LINE.

  4. DATUMS -A-, -B- AND -D- TO BE DETERMINED AT DATUM PLANE -H-.

  5. DIMENSIONS D AND E TO BE DETERMINED AT SEATING PLANE -C-.
- SEATING PLANE -C-.

  6. DIMENSIONS D1 AND E1 DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25 (0.010) PER SIDE. DIMENSIONS D1 AND B1 DO
- UNITY PER SIDE. DIMENSIONS DI AND BI DO
  INCLUDE MOLD MISMATCH AND ARE
  DETERMINED AT DATUM PLANE H.–.
  7. DIMENSION b DOES NOT INCLUDE DAMBAR
  PROTRUSION. DAMBAR PROTRUSION SHALL NOT CAUSE THE b DIMENSION TO EXCEED 0.45

	MILLIN	IETERS	INC	HES	
DIM	MIN	MAX	MIN	MAX	
Α		1.60		0.063	
A1	0.05	0.15	0.002	0.006	
A2	1.35	1.45	0.053	0.057	
b	0.22	0.38	0.009	0.015	
b1	0.22	0.33	0.009	0.013	
С	0.09	0.20	0.004	0.008	
c1	0.09	0.16	0.004	0.006	
D	22.00	BSC	0.866	BSC	
D1	20.00	BSC	0.787 BSC		
E	16.00	16.00 BSC		BSC	
E1	14.00	BSC	0.551	BSC	
е	0.65	BSC	0.026	BSC	
L	0.45	0.75	0.018	0.030	
L1	1.00	1.00 REF		REF	
L2	0.50	REF	0.020	REF	
S	0.20	_	0.008		
R1	0.08		0.003		
R2	0.08	0.20	0.003	0.008	
θ	0 °	7°	0 °	7°	
θ1	0 °		0 °		
θ2	11 °	13°	11 °	13°	
θ3	11 °	13°	11 °	13°	

Motorola reserves the right to make changes without further notice to any products herein. Motorola makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does Motorola assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters which may be provided in Motorola data sheets and/or specifications can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typicals" must be validated for each customer application by customer's technical experts. Motorola does not convey any license under its patent rights nor the rights of others. Motorola products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Motorola product could create a situation where personal injury or death may occur. Should Buyer purchase or use Motorola products for any such unintended or unauthorized application, Buyer shall indemnify and hold Motorola and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that Motorola was negligent regarding the design or manufacture of the part. Motorola and was negligent regarding the design or manufacture of the part. Motorola and was negligent regarding the design or manufacture of the part. Motorola and intended or unauthorized use, even if such claim alleges that Opportunity/Affirmative Action Employer.

How to reach us:

USA/EUROPE/Locations Not Listed: Motorola Literature Distribution; P.O. Box 5405, Denver, Colorado, 80217. 1-303-675-2140 or 1-800-441-2447

Mfax™: RMFAX0@email.sps.mot.com - TOUCHTONE 1-602-244-6609 Motorola Fax Back System - US & Canada ONLY 1-800-774-18

 $- \mbox{http://sps.motorola.com/mfax/} \\ \mbox{HOME PAGE: http://motorola.com/sps/}$ 

Mfax is a trademark of Motorola, Inc.

**JAPAN**: Nippon Motorola Ltd.: SPD, Strategic Planning Office, 141, 4-32-1 Nishi-Gotanda, Shagawa-ku, Tokyo, Japan. 03-5487-8488

- TOUCHTONE 1-602-244-6609 ASIA/PACIFIC: Motorola Semiconductors H.K. Ltd.; 8B Tai Ping Industrial Park, - US & Canada ONLY 1-800-774-1848 51 Ting Kok Road, Tai Po, N.T., Hong Kong. 852-26629298

**CUSTOMER FOCUS CENTER:** 1-800-521-6274



MCM69F819/D