

SYNCHRONOUS DRAM MODULE

MT18LSDT1672G, MT18LSDT3272G, MT18LSDT6472G

For the latest data sheet, please refer to the Micron Web site: www.micron.com/datasheets

FEATURES

- JEDEC-standard 168-pin, dual in-line memory module (DIMM)
- PC133- and PC100-compliant
- Registered inputs with one-clock delay
- Phase-lock loop (PLL) clock driver to reduce loading
- Utilizes 100 MHz and 133 MHz SDRAM components
- ECC-optimized pinout
- Single +3.3V ±0.3V power supply
- Fully synchronous; all signals registered on positive edge of PLL clock
- Internal pipelined operation; column address can be changed every clock cycle
- Internal SDRAM banks for hiding row access/precharge
- Programmable burst lengths: 1, 2, 4, 8, or full page
- Auto Precharge and Auto Refresh Modes
- Self Refresh Mode
- 128MB and 256MB: 64ms, 4,096-cycle refresh; 512MB: 64ms, 8,192-cycle refresh
- LVTTTL-compatible inputs and outputs
- Serial Presence-Detect (SPD)

OPTIONS

- Package
168-pin DIMM (gold)
- Frequency/CAS Latency*
133 MHz/CL = 2 -13E
133 MHz/CL = 3 -133
100 MHz/CL = 2 -10E

* An extra clock cycle will be incurred when the module is in registered mode.

MARKING

G

-13E

-133

-10E

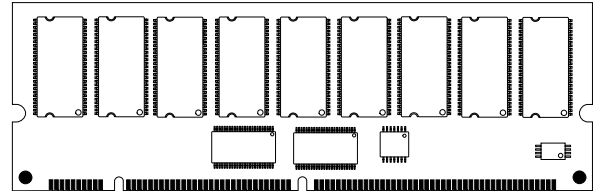
DEVICE TIMING

Module Markings	PC100 CL - 'RCD - 'RP	PC133 CL - 'RCD - 'RP
-13E	2 - 2 - 2	2 - 2 - 2
-133	2 - 2 - 2	3 - 3 - 3
-10E	2 - 2 - 2	NA

ADDRESS TABLE

	128MB Module	256MB Module	512MB Module
Refresh Count	4K	4K	8K
Device Configuration	16 Meg x 4	32 Meg x 4	64 Meg x 4
Device Banks	4 (BA0, BA1)	4 (BA0, BA1)	4 (BA0, BA1)
Row Addressing	4K (A0-A11)	4K (A0-A11)	8K (A0-A12)
Column Addressing	1K (A0-A9)	2K (A0-A9,A11)	2K (A0-A9,A11)
Module Banks	1 (S0,S2)	1 (S0,S2)	1 (S0,S2)

PIN ASSIGNMENT (FRONT VIEW) 168-PIN DIMM



PIN	SYMBOL	PIN	SYMBOL	PIN	SYMBOL	PIN	SYMBOL
1	Vss	43	Vss	85	Vss	127	Vss
2	DQ0	44	NC	86	DQ32	128	CKE0
3	DQ1	45	S2#	87	DQ33	129	NC
4	DQ2	46	DQMB2	88	DQ34	130	DQMB6
5	DQ3	47	DQMB3	89	DQ35	131	DQMB7
6	VDD	48	NC	90	VDD	132	NC
7	DQ4	49	VDD	91	DQ36	133	VDD
8	DQ5	50	NC	92	DQ37	134	NC
9	DQ6	51	NC	93	DQ38	135	NC
10	DQ7	52	CB2	94	DQ39	136	CB6
11	DQ8	53	CB3	95	DQ40	137	CB7
12	Vss	54	Vss	96	Vss	138	Vss
13	DQ9	55	DQ16	97	DQ41	139	DQ48
14	DQ10	56	DQ17	98	DQ42	140	DQ49
15	DQ11	57	DQ18	99	DQ43	141	DQ50
16	DQ12	58	DQ19	100	DQ44	142	DQ51
17	DQ13	59	VDD	101	DQ45	143	VDD
18	VDD	60	DQ20	102	VDD	144	DQ52
19	DQ14	61	NC	103	DQ46	145	NC
20	DQ15	62	NC	104	DQ47	146	NC
21	CB0	63	NC	105	CB4	147	REGE
22	CB1	64	Vss	106	CB5	148	Vss
23	Vss	65	DQ21	107	Vss	149	DQ53
24	NC	66	DQ22	108	NC	150	DQ54
25	NC	67	DQ23	109	NC	151	DQ55
26	VDD	68	Vss	110	VDD	152	Vss
27	WE#	69	DQ24	111	CAS#	153	DQ56
28	DQMB0	70	DQ25	112	DQMB4	154	DQ57
29	DQMB1	71	DQ26	113	DQMB5	155	DQ58
30	S0#	72	DQ27	114	NC	156	DQ59
31	NC	73	VDD	115	RA5#	157	VDD
32	Vss	74	DQ28	116	Vss	158	DQ60
33	A0	75	DQ29	117	A1	159	DQ61
34	A2	76	DQ30	118	A3	160	DQ62
35	A4	77	DQ31	119	A5	161	DQ63
36	A6	78	Vss	120	A7	162	Vss
37	A8	79	CK2	121	A9	163	CK3
38	A10	80	NC	122	BA0	164	NC
39	BA1	81	WP	123	A11	165	SA0
40	VDD	82	SDA	124	VDD	166	SA1
41	VDD	83	SCL	125	CK1	167	SA2
42	CK0	84	VDD	126	NC/A12	168	VDD

NOTE: Pin 126 is a NC for the 128MB and 256MB module. It is A12 for the 512MB module.



PART NUMBERS

PART NUMBER	CONFIGURATION	SYSTEM BUS SPEED
MT18LSDT1672G-13E__	16 Meg x 72	133 MHz
MT18LSDT1672G-133__	16 Meg x 72	133 MHz
MT18LSDT1672G-10E__	16 Meg x 72	100 MHz
MT18LSDT3272G-133__	32 Meg x 72	133 MHz
MT18LSDT3272G-13E__	32 Meg x 72	133 MHz
MT18LSDT3272G-10E__	32 Meg x 72	100 MHz
MT18LSDT6472G-133__	64 Meg x 72	133 MHz
MT18LSDT6472G-13E__	64 Meg x 72	133 MHz
MT18LSDT6472G-10E__	64 Meg x 72	100 MHz

NOTE: The designators for component and PCB revision are the last two characters of each part number. Consult factory for current revision codes. Example:
MT18LSDT1672G-133B1

GENERAL DESCRIPTION

The MT18LSDT1672G, MT18LSDT3272G, and MT18LSDT6472G are high-speed CMOS, dynamic random-access, 128MB, 256MB, and 512MB memory modules organized in a x72 (ECC) configuration. These modules use internally configured quad-bank SDRAM devices, with a synchronous interface (all signals are registered on the positive edge of clock signal CK0).

Read and write accesses to the SDRAM modules are burst oriented; accesses start at a selected location and continue for a programmed number of locations in a programmed sequence. Accesses begin with the registration of an ACTIVE command, which is then followed by a READ or WRITE command. The address bits registered coincident with the ACTIVE command are used to select the device bank and row to be accessed (BA0, BA1 select the device bank, A0-A11 select the device row for the 128MB and 256MB modules; A0-A12 select the device row for the 512MB module). The address bits registered coincident with the READ or WRITE command are used to select the starting device column location for the burst access.

These modules provide for programmable READ or WRITE burst lengths of 1, 2, 4, or 8 locations, or full page, with a burst terminate option. An auto precharge function may be enabled to provide a self-timed device row precharge that is initiated at the end of the burst sequence.

These modules use an internal pipelined architecture. Precharging one device bank while accessing one of the other three device banks will hide the PRECHARGE cycles and provide seamless, high-speed, random-access operation.

These modules are designed to operate in 3.3V, low-power memory systems. An auto refresh mode is provided, along with a power-saving, power-down mode. All inputs and outputs are LVTTTL-compatible.

SDRAM modules offer substantial advances in DRAM operating performance, including the ability to synchronously burst data at a high data rate with automatic device column-address generation, the ability to interleave between device banks in order to hide precharge time, and the capability to randomly change device column addresses on each clock cycle during a burst access. For more information regarding SDRAM operation, refer to the 64Mb, 128Mb, and 256Mb SDRAM data sheets.

PLL AND REGISTER OPERATION

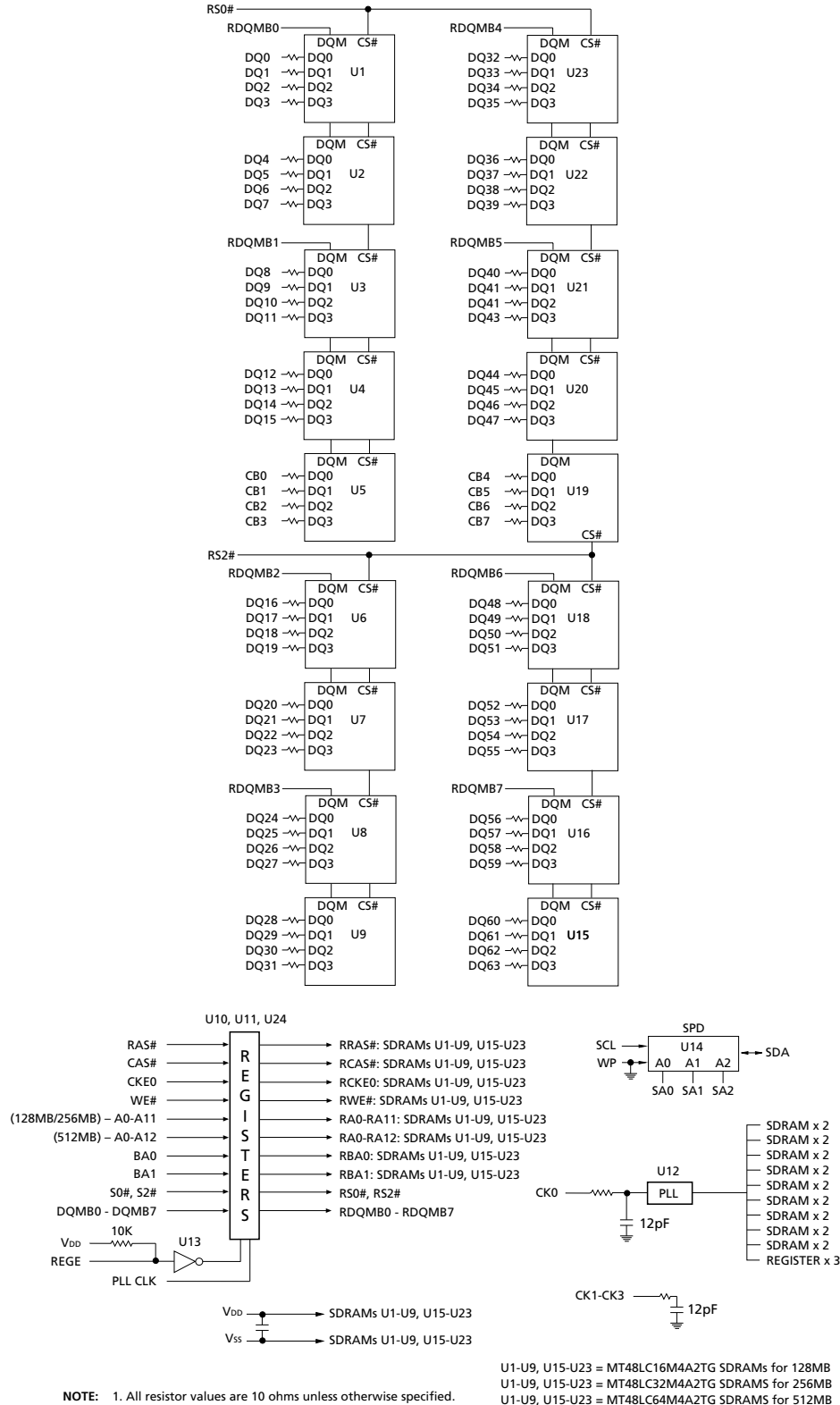
These modules can be operated in either registered mode (REGE pin HIGH), where the control/address input signals are latched in the register on one rising clock edge and sent to the SDRAM devices on the following rising clock edge (data access is delayed by one clock), or in buffered mode (REGE pin LOW) where the input signals pass through the register/buffer to the SDRAM devices on the same clock. A phase-lock loop (PLL) on the modules is used to redrive the clock signals to the SDRAM devices to minimize system clock loading (CK0 is connected to the PLL, and CK1, CK2, and CK3 are terminated).

SERIAL PRESENCE-DETECT OPERATION

These modules incorporate serial presence-detect (SPD). The SPD function is implemented using a 2,048-bit EEPROM. This nonvolatile storage device contains 256 bytes. The first 128 bytes can be programmed by Micron to identify the module type and various SDRAM organizations and timing parameters. The remaining 128 bytes of storage are available for use by the customer. System READ/WRITE operations between the master (system logic) and the slave EEPROM device (DIMM) occur via a standard IIC bus using the DIMM's SCL (clock) and SDA (data) signals, together with SA(2:0), which provide eight unique DIMM/EEPROM addresses.

FUNCTIONAL BLOCK DIAGRAM

MT18LSDT1672G (128MB), MT18LSDT3272G (256MB), MT18LSDT6472G (512MB)



PIN DESCRIPTIONS

PIN NUMBERS	SYMBOL	TYPE	DESCRIPTION
27, 111, 115	WE#, CAS#, RAS#	Input	Command Inputs: WE#, CAS#, and RAS# (along with S0#, S2#) define the command being entered.
42, 79, 125, 163	CK0-CK3	Input	Clock: CK0 is distributed through an on-board PLL to all devices. CK1-CK3 are terminated.
128	CKE0	Input	Clock Enable: CKE0 activates (HIGH) and deactivates (LOW) the CK0 signal. Deactivating the clock provides POWER-DOWN and SELF REFRESH operation (all device banks idle) or CLOCK SUSPEND operation (burst access in progress). CKE0 is synchronous except after the device enters power-down and self refresh modes, where CKE0 becomes asynchronous until after exiting the same mode. The input buffers, including CK0, are disabled during power-down and self refresh modes, providing low standby power.
30, 45	S0#, S2#	Input	Chip Select: S0#, S2# enable (registered LOW) and disable (registered HIGH) the command decoder. All commands are masked when S0#, S2# are registered HIGH. S0#, S2# are considered part of the command code.
28-29, 46-47, 112-113, 130-131	DQMB0-DQMB7	Input	Input/Output Mask: DQMB is an input mask signal for write accesses and an output enable signal for read accesses. Input data is masked when DQMB is sampled HIGH during a WRITE cycle. The output buffers are placed in a High-Z state (two-clock latency) when DQMB is sampled HIGH during a READ cycle.
39, 122	BA0, BA1	Input	Bank Address: BA0 and BA1 define to which device bank the ACTIVE, READ, WRITE or PRECHARGE command is being applied.
33-38, 117-121, 123, 126 (512MB)	A0-A11 (128MB/256MB) A0-A12 (512MB)	Input	Address Inputs: A0-A11 (128MB/256MB) or A0-A12 (512MB) are sampled during the ACTIVE command (device row-address A0-A11/12) and READ/WRITE command (device column-address A0-A9 (128MB) or A0-A9/A11 (256MB/512MB), with A10 defining auto precharge) to select one location out of the memory array in the respective device bank. A10 is sampled during a PRECHARGE command to determine if both device banks are to be precharged (A10 HIGH). The address inputs also provide the op-code during a LOAD MODE REGISTER command.
81	WP	Input	Write Protect: Serial presence-detect hardware write protect.
83	SCL	Input	Serial Clock for Presence-Detect: SCL is used to synchronize the presence-detect data transfer to and from the module.
165-167	SA0-SA2	Input	Presence-Detect Address Inputs: These pins are used to configure the presence-detect device.
147	REGE	Input	Register Enable.

NOTE: Pin numbers are listed in module pinout order and do not necessarily correlate with symbols.

PIN DESCRIPTIONS (CONTINUED)

PIN NUMBERS	SYMBOL	TYPE	DESCRIPTION
2-5, 7-11, 13-17, 19-20, 55-58, 60, 65-67, 69-72, 74-77, 86-89, 91-95, 97-101, 103-104, 139-142, 144, 149-151, 153-156, 158-161	DQ0-DQ63	Input/ Output	Data I/Os: Data bus.
21-22, 52-53, 105-106, 136-137	CB0-CB7	Input/ Output	Check Bits.
82	SDA	Input/ Output	Serial Presence-Detect Data: SDA is a bidirectional pin used to transfer addresses and data into and data out of the presence-detect portion of the module.
6, 18, 26, 40-41, 49, 59, 73, 84, 90, 102, 110, 124, 133, 143, 157, 168	V _{DD}	Supply	Power Supply: +3.3V ±0.3V.
1, 12, 23, 32, 43, 54, 64, 68, 78, 85, 96, 107, 116, 127, 138, 148, 152, 162	V _{SS}	Supply	Ground.
24, 25, 26, 31, 44, 48, 50, 51, 61, 62, 63, 80, 108, 109, 114, 126 (128/256MB), 129, 132, 134, 135, 145, 146, 164	NC	–	Not Connected: These pins are not connected on these modules.

NOTE: Pin numbers are listed in module pinout order and do not necessarily correlate with symbols.

SDRAM COMPONENT DESCRIPTION

In general, the 64Mb, 128Mb, and 256Mb SDRAM memory devices used for these modules are quad-bank DRAMs, that operate at 3.3V and include a synchronous interface (all signals are registered on the positive edge of the clock signal, CK). The four banks of a x4, 64Mb device are each configured as 4,096 bit-rows, by 1,024 bit-columns, by 4 input/output bits. The four banks of a x4, 128Mb device are each configured as 4,096 bit-rows, by 2,048 bit-columns, by 4 input/output bits. The four banks of a x4, 256MB device are configured as 8,192 bit-rows, by 2,048 bit columns, by 4 input/output bits.

MODULE FUNCTIONAL DESCRIPTION

Read and write accesses to the SDRAM are burst oriented; accesses start at a selected location and continue for a programmed number of locations in a programmed sequence. Accesses begin with the registration of an ACTIVE command, which is then followed by a READ or WRITE command. The address bits registered coincident with the ACTIVE command are used to select the device bank and row to be accessed BA0 and BA1 select the device bank, A0-A11 (for 128MB and 256MB module), or A0-A12 (for 512MB module), select the device row. The address bits A0-A9 (for 64MB) or A0-A9, A11 (for the 256MB and 512MB module), registered coincident with the READ or WRITE command are used to select the starting device column location for the burst access.

Prior to normal operation, the SDRAM must be initialized. The following sections provide detailed information covering device initialization, register definition, command descriptions and device operation.

Initialization

SDRAMs must be powered up and initialized in a predefined manner. Operational procedures other than those specified may result in undefined operation. Once power is applied to V_{DD} and V_{DDQ} (simultaneously) and the clock is stable (stable clock is defined as a signal cycling within timing constraints specified for the clock pin), the SDRAM requires a 100 μ s delay prior to issuing any command other than a COMMAND INHIBIT or NOP. Starting at some point during this 100 μ s period and continuing at least through the end of this period, COMMAND INHIBIT or NOP commands should be applied.

Once the 100 μ s delay has been satisfied with at least one COMMAND INHIBIT or NOP command having been applied, a PRECHARGE command should be applied. All device banks must then be precharged, thereby placing the device in the all device banks idle state.

Once in the idle state, two AUTO REFRESH cycles must be performed. After the AUTO REFRESH cycles are complete, the SDRAM is ready for mode register programming. Because the mode register will power up in an unknown state, it should be loaded prior to applying any operational command.

Mode Register Definition

MODE REGISTER

The mode register is used to define the specific mode of operation of the SDRAM. This definition includes the selection of a burst length, a burst type, a CAS latency, an operating mode and a write burst mode, as shown in Mode Register Definition Diagram. The mode register is programmed via the LOAD MODE REGISTER command and will retain the stored information until it is programmed again or the device loses power.

Mode register bits M0-M2 specify the burst length, M3 specifies the type of burst (sequential or interleaved), M4-M6 specify the CAS latency, M7 and M8 specify the operating mode, M9 specifies the write burst mode, and M10 and M11 are reserved for future use. For the 512MB module, address A12 (M12) is undefined but should be driven LOW during loading of the mode register.

The mode register must be loaded when all device banks are idle, and the controller must wait the specified time before initiating the subsequent operation. Violating either of these requirements will result in unspecified operation.

Burst Length

Read and write accesses to the SDRAM are burst oriented, with the burst length being programmable, as shown in Mode Register Definition Diagram. The burst length determines the maximum number of column locations that can be accessed for a given READ or WRITE command. Burst lengths of 1, 2, 4, or 8 locations are available for both the sequential and the interleaved burst types, and a full-page burst is available for the sequential type. The full-page burst is used in conjunction with the BURST TERMINATE command to generate arbitrary burst lengths.

Reserved states should not be used, as unknown operation or incompatibility with future versions may result.

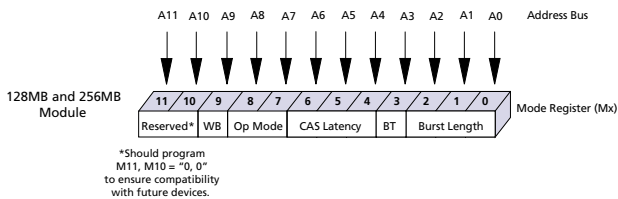
When a READ or WRITE command is issued, a block of columns equal to the burst length is effectively selected. All accesses for that burst take place within this block, meaning that the burst will wrap within the block if a boundary is reached, as shown in the Burst Definition Table. The block is uniquely selected by A1-A9 (64MB) or A1-A9, A11 (128MB/256MB) when the burst length is set to two; A2-A9 or A2-A9, A11 when the burst length is set to four; and by A3-A9 or A3-A9, A11 when the burst length is set to eight. The remaining (least significant) address bit(s) is (are) used to select the starting location within the block. Full-page bursts wrap within the page if the boundary is reached, as shown in the Burst Definition Table.

Burst Type

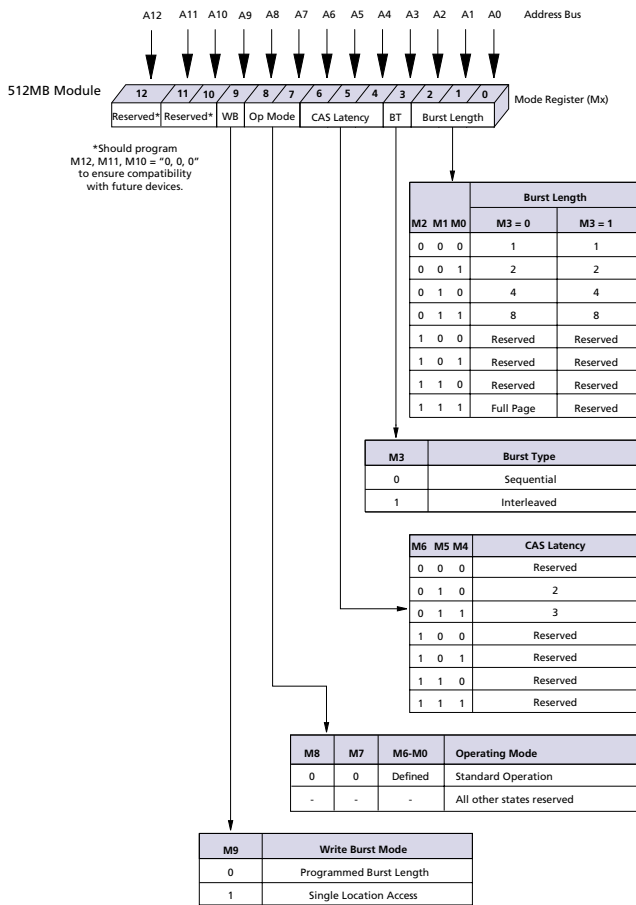
Accesses within a given burst may be programmed to be either sequential or interleaved; this is referred to as the burst type and is selected via bit M3.

The ordering of accesses within a burst is determined by the burst length, the burst type and the starting column address, as shown in the Burst Definition Table.

128MB/256MB MODULE ADDRESS BUS



512MB MODULE ADDRESS BUS



Mode Register Definition Diagram

Burst Definition Table

Burst Length	Starting Column Address	Order of Accesses Within a Burst	
		Type=Sequential	Type=Interleaved
2	A0		
	0	0-1	0-1
	1	1-0	1-0
4	A1 A0		
	0 0	0-1-2-3	0-1-2-3
	0 1	1-2-3-0	1-0-3-2
	1 0	2-3-0-1	2-3-0-1
	1 1	3-0-1-2	3-2-1-0
8	A2 A1 A0		
	0 0 0	0-1-2-3-4-5-6-7	0-1-2-3-4-5-6-7
	0 0 1	1-2-3-4-5-6-7-0	1-0-3-2-5-4-7-6
	0 1 0	2-3-4-5-6-7-0-1	2-3-0-1-6-7-4-5
	0 1 1	3-4-5-6-7-0-1-2	3-2-1-0-7-6-5-4
	1 0 0	4-5-6-7-0-1-2-3	4-5-6-7-0-1-2-3
	1 0 1	5-6-7-0-1-2-3-4	5-4-7-6-1-0-3-2
	1 1 0	6-7-0-1-2-3-4-5	6-7-4-5-2-3-0-1
1 1 1	7-0-1-2-3-4-5-6	7-6-5-4-3-2-1-0	
Full Page (y)	n = A0-A9, or n =A0-A9/A11 (location 0-y)	Cn, Cn+1, Cn+2 Cn+3, Cn+4... ...Cn-1, Cn...	Not supported

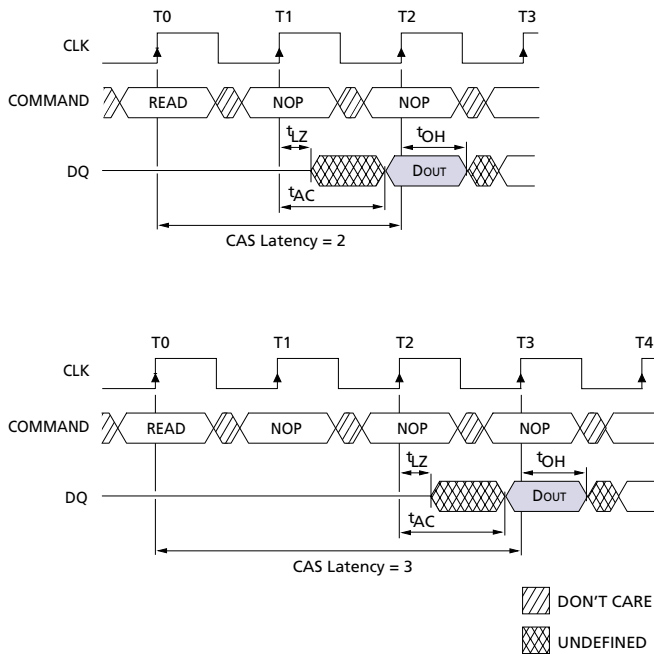
- NOTE:**
1. For full-page accesses: y = 1,024 (128MB); y = 2,048 (256MB/512MB).
 2. For a burst length of two, A1-A9 (128MB) or A1-A9/A11 (256MB/512MB) select the block of two burst; A0 selects the starting column within the block.
 3. For a burst length of four, A2-A9 or A2-A9/A11 select the block of four burst; A0-A1 select the starting column within the block.
 4. For a burst length of eight, A3-A9 or A3-A9/A11 select the block of eight burst; A0-A2 select the starting column within the block.
 5. For a full-page burst, the full row is selected and A0-A9 or A0-A9/A11 select the starting column.
 6. Whenever a boundary of the block is reached within a given sequence above, the following access wraps within the block.
 7. For a burst length of one, A0-A9 or A0-A9/A11 select the unique column to be accessed, and Mode Register bit M3 is ignored.

CAS Latency

The CAS latency is the delay, in clock cycles, between the registration of a READ command and the availability of the first piece of output data. The latency can be set to two or three clocks.

If a READ command is registered at clock edge n , and the latency is m clocks, the data will be available by clock edge $n + m$. The DQs will start driving as a result of the clock edge one cycle earlier ($n + m - 1$), and provided that the relevant access times are met, the data will be valid by clock edge $n + m$. For example, assuming that the clock cycle time is such that all relevant access times are met, if a READ command is registered at T_0 and the latency is programmed to two clocks, the DQs will start driving after T_1 and the data will be valid by T_2 , as shown in the CAS Latency Diagram. The CAS Latency Table indicate the operating frequencies at which each CAS latency setting can be used.

Reserved states should not be used as unknown operation or incompatibility with future versions may result.



CAS LATENCY DIAGRAM

Operating Mode

The normal operating mode is selected by setting M7 and M8 to zero; the other combinations of values for M7 and M8 are reserved for future use and/or test modes. The programmed burst length applies to both READ and WRITE bursts.

Test modes and reserved states should not be used because unknown operation or incompatibility with future versions may result.

Write Burst Mode

When M9 = 0, the burst length programmed via M0-M2 applies to both READ and WRITE bursts; when M9 = 1, the programmed burst length applies to READ bursts, but write accesses are single-location (nonburst) accesses.

CAS LATENCY TABLE

SPEED	ALLOWABLE OPERATING FREQUENCY (MHz)	
	CAS LATENCY = 2*	CAS LATENCY = 3*
-13E	≤ 133	≤ 143
-133	≤ 100	≤ 133
-10E	≤ 100	NA

*Input register will add an extra clock cycle when in registered mode.



COMMANDS

The Truth Table provides a quick reference of available commands. This is followed by a written description of each command. For a more detailed description

of commands and operations refer to the 64Mb, 128Mb, or 256Mb SDRAM datasheets.

TRUTH TABLE – SDRAM COMMANDS AND DQMB OPERATION

(Note: 1, notes appear below table)

NAME (FUNCTION)	CS#	RAS#	CAS#	WE#	DQMB	ADDR	DQs	NOTES
COMMAND INHIBIT (NOP)	H	X	X	X	X	X	X	
NO OPERATION (NOP)	L	H	H	H	X	X	X	
ACTIVE (Select bank and activate row)	L	L	H	H	X	Bank/Row	X	3
READ (Select bank and column, and start READ burst)	L	H	L	H	L/H ⁸	Bank/Col	X	4
WRITE (Select bank and column, and start WRITE burst)	L	H	L	L	L/H ⁸	Bank/Col	Valid	4
BURST TERMINATE	L	H	H	L	X	X	Active	
PRECHARGE (Deactivate row in bank or banks)	L	L	H	L	X	Code	X	5
AUTO REFRESH or SELF REFRESH (Enter self refresh mode)	L	L	L	H	X	X	X	6, 7
LOAD MODE REGISTER	L	L	L	L	X	Op-Code	X	2
Write Enable/Output Enable	-	-	-	-	L	-	Active	8
Write Inhibit/Output High-Z	-	-	-	-	H	-	High-Z	8

- NOTE:**
1. CKE is HIGH for all commands shown except SELF REFRESH.
 2. A0-A11 (128MB/256MB), A0-A12 (512MB) define the op-code written to the Mode Register, and should be driven low.
 3. A0-A11 (128MB/256MB), A0-A12 (512MB) provide device row address. BA0, BA1 determine which device bank is made active.
 4. A0-A9 provide device column address for 128MB module; A0-A9/A11 for 256MB and 512MB modules; A10 HIGH enables the auto precharge feature (nonpersistent), while A10 LOW disables the auto precharge feature; BA0, BA1 determine which device bank is being read from or written to.
 5. A10 LOW: BA0, BA1 determine which device bank is being precharged. A10 HIGH: both device banks are precharged and BA0, BA1 are "Don't Care."
 6. This command is AUTO REFRESH if CKE is HIGH, SELF REFRESH if CKE is LOW.
 7. Internal refresh counter controls row addressing; all inputs and I/Os are "Don't Care" except for CKE.
 8. Activates or deactivates the DQs during WRITES (zero-clock delay) and READs (two-clock delay).



ABSOLUTE MAXIMUM RATINGS*

Voltage on V_{DD} Supply
 Relative to V_{SS} -1V to +4.6V
 Voltage on Inputs, NC or I/O Pins
 Relative to V_{SS} -1V to +4.6V
 Operating Temperature, T_A (ambient) ... 0°C to +70°C
 Storage Temperature (plastic) -55°C to +150°C
 Power Dissipation 18W

*Stresses greater than those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

DC ELECTRICAL CHARACTERISTICS AND OPERATING CONDITIONS

(Notes: 1, 5, 6; notes appear following parameter tables); (V_{DD}, V_{DDQ} = +3.3V ±0.3V)

PARAMETER/CONDITION	SYMBOL	MIN	MAX	UNITS	NOTES
SUPPLY VOLTAGE	V _{DD} , V _{DDQ}	3	3.6	V	
INPUT HIGH VOLTAGE: Logic 1; All inputs	V _{IH}	2	V _{DD} + 0.3	V	22
INPUT LOW VOLTAGE: Logic 0; All inputs	V _{IL}	-0.3	0.8	V	22
INPUT LEAKAGE CURRENT: Any input 0V ≤ V _{IN} ≤ V _{DD} (All other pins not under test = 0V) For inputs: A0-A12, BA0, BA1, RAS#, CAS#, WE#, CKE0	I _{IA}	-10	10	μA	33
INPUT LEAKAGE CURRENT: Any input 0V ≤ V _{IN} ≤ V _{DD} (All other pins not under test = 0V) For inputs: S0#, S2#, DQMB1-DQMB7	I _{IB}	-5	5	μA	33
OUTPUT LEAKAGE CURRENT: DQs are disabled; 0V ≤ V _{OUT} ≤ V _{DDQ}	I _{OZ}	-10	10	μA	33
OUTPUT LEVELS: Output High Voltage (I _{OUT} = -4mA)	V _{OH}	2.4	-	V	
Output Low Voltage (I _{OUT} = 4mA)	V _{OL}	-	0.4	V	

I_{DD} SPECIFICATIONS AND CONDITIONS* (128MB MODULE)

(Notes: 1, 6, 11, 13; notes appear following parameter tables)
(V_{DD}, V_{DDQ} = +3.3V ±0.3V)

PARAMETER/CONDITION	SYMBOL	MAX			UNITS	NOTES	
		-13E	-133	-10E			
OPERATING CURRENT: Active Mode; Burst = 2; READ or WRITE; t _{RC} = t _{RC} (MIN)	I _{DD1}	1,250	2,070	1,710	mA	3, 18, 19, 30	
STANDBY CURRENT: Power-Down Mode; All device banks idle; CKE = LOW	I _{DD2}	36	36	36	mA	30	
STANDBY CURRENT: Active Mode; CKE = HIGH; CS# = HIGH; All device banks active after t _{RCD} met; No accesses in progress	I _{DD3}	810	810	630	mA	3, 12, 19, 30	
OPERATING CURRENT: Burst Mode; Continuous burst; READ or WRITE; All device banks active	I _{DD4}	2,700	2,520	2,160	mA	3, 18, 19, 30	
AUTO REFRESH CURRENT CS# = HIGH; CKE = HIGH	t _{RFC} = t _{RFC} (MIN)	I _{DD5}	4,140	3,780	3,420	mA	3, 12, 18, 19, 30, 31
	t _{RFC} = 15.6 μs	I _{DD6}	54	54	54	mA	
SELF REFRESH CURRENT: CKE ≤ 0.2V	I _{DD7}	18	18	18	mA	4	

I_{DD} SPECIFICATIONS AND CONDITIONS* (256 MODULE)

(Notes: 1, 6, 11, 13; notes appear following parameter tables)
(V_{DD}, V_{DDQ} = +3.3V ±0.3V)

PARAMETER/CONDITION	SYMBOL	MAX			UNITS	NOTES	
		-13E	-133	-10E			
OPERATING CURRENT: Active Mode; Burst = 2; READ or WRITE; t _{RC} = t _{RC} (MIN)	I _{DD1}	2,880	2,700	2,520	mA	3, 18, 19, 30	
STANDBY CURRENT: Power-Down Mode; All device banks idle; CKE = LOW	I _{DD2}	36	36	36	mA	30	
STANDBY CURRENT: Active Mode; CKE = HIGH; CS# = HIGH; All device banks active after t _{RCD} met; No accesses in progress	I _{DD3}	900	900	720	mA	3, 12, 19, 30	
OPERATING CURRENT: Burst Mode; Continuous burst; READ or WRITE; All device banks active	I _{DD4}	2,970	2,700	2,520	mA	3, 18, 19, 30	
AUTO REFRESH CURRENT CS# = HIGH; CKE = HIGH	t _{RFC} = t _{RFC} (MIN)	I _{DD5}	5,940	5,580	4,860	mA	3, 12, 18, 19, 30, 31
	t _{RFC} = 15.6 μs	I _{DD6}	54	54	54	mA	
SELF REFRESH CURRENT: CKE ≤ 0.2V	I _{DD7}	36	36	36	mA	4	

*DRAM components only.



I_{DD} SPECIFICATIONS AND CONDITIONS* (512MB MODULE)

(Notes: 1, 6, 11, 13; notes appear following parameter tables)

(V_{DD}, V_{DDQ} = +3.3V ±0.3V)

PARAMETER/CONDITION	SYMBOL	MAX			UNITS	NOTES	
		-13E	-133	-10E			
OPERATING CURRENT: Active Mode; Burst = 2; READ or WRITE; $t_{RC} = t_{RC} (MIN)$	I _{DD1}	2,430	2,250	2,250	mA	3, 18, 19, 30	
STANDBY CURRENT: Power-Down Mode; All device banks idle; CKE = LOW	I _{DD2}	36	36	36	mA	30	
STANDBY CURRENT: Active Mode; CKE = HIGH; CS# = HIGH; All device banks active after t_{RCD} met; No accesses in progress	I _{DD3}	720	720	720	mA	3, 12, 19, 30	
OPERATING CURRENT: Burst Mode; Continuous burst; READ or WRITE; All device banks active	I _{DD4}	2,430	2,430	2,430	mA	3, 18, 19, 30	
AUTO REFRESH CURRENT CS# = HIGH; CKE = HIGH	$t_{RFC} = t_{RFC} (MIN)$	I _{DD5}	5,130	4,860	4,860	mA	3, 12, 18, 19, 30, 31
	$t_{RFC} = 7.81 \mu s$	I _{DD6}	63	63	63	mA	
SELF REFRESH CURRENT: CKE ≤ 0.2V	I _{DD7}	45	45	45	mA	4	

*DRAM components only.



CAPACITANCE (128MB, 256MB, 512MB)

(Note: 2; notes appear following parameter tables)

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS
Input Capacitance: A0-A12, BA0, BA1, RAS#, CAS#, WE#, CKE0	C _{i1}	–	8	–	pF
Input Capacitance: S0#, S2#, DQMB0-DQMB7	C _{i2}	–	4	–	pF
Input Capacitance: CK0	C _{i3}	–	16	–	pF
Input Capacitance: SCL, SA0-SA2, SDA	C _{i4}	–	–	10	pF
Input Capacitance: CK1-CK3	C _{i5}	–	12	–	pF
Input Capacitance: REGE	C _{i6}	1.5	–	12	pF
Input/Output Capacitance: DQ0-DQ63, CB0-CB3, CB4-CB7	C _{i0}	8	–	12	pF



ELECTRICAL CHARACTERISTICS AND RECOMMENDED AC OPERATING CONDITIONS*

(Notes: 5, 6, 8, 9, 11; notes appear following parameter tables)

AC CHARACTERISTICS			-13E		-133		-10E		UNITS	NOTES
PARAMETER	SYMBOL	MIN	MAX	MIN	MAX	MIN	MAX			
Access time from CLK (pos. edge)	CL = 3	$t_{AC(3)}$		5.4		5.4		6	ns	27
	CL = 2	$t_{AC(2)}$		5.4		6		6	ns	
Address hold time		t_{AH}	0.8		0.8		1		ns	
Address setup time		t_{AS}	1.5		1.5		2		ns	
CLK high-level width		t_{CH}	2.5		2.5		3		ns	
CLK low-level width		t_{CL}	2.5		2.5		3		ns	
Clock cycle time	CL = 3	$t_{CK(3)}$	7		7.5		8		ns	23
	CL = 2	$t_{CK(2)}$	7.5		10		10		ns	23
CKE hold time		t_{CKH}	0.8		0.8		1		ns	
CKE setup time		t_{CKS}	1.5		1.5		2		ns	
CS#, RAS#, CAS#, WE#, DQM hold time		t_{CMH}	0.8		0.8		1		ns	
CS#, RAS#, CAS#, WE#, DQM setup time		t_{CMS}	1.5		1.5		2		ns	
Data-in hold time		t_{DH}	0.8		0.8		1		ns	
Data-in setup time		t_{DS}	1.5		1.5		2		ns	
Data-out high-impedance time	CL = 3	$t_{HZ(3)}$		5.4		5.4		6	ns	10
	CL = 2	$t_{HZ(2)}$		5.4		6		6	ns	10
Data-out low-impedance time		t_{LZ}	1		1		1		ns	
Data-out hold time (load)		t_{OH}	3		3		3		ns	
Data-out hold time (no load)		t_{OH_N}	1.8		1.8		1.8		ns	28
ACTIVE to PRECHARGE command		t_{RAS}	37	120,000	44	120,000	50	120,000	ns	29
ACTIVE to ACTIVE command period		t_{RC}	60		66		70		ns	
ACTIVE to READ or WRITE delay		t_{RCD}	15		20		20		ns	
Refresh period (8,192 rows)		t_{REF}		64		64		64	ms	
AUTOREFRESH period		t_{RFC}	66		66		70		ns	
PRECHARGE command period		t_{RP}	15		20		20		ns	
ACTIVE bank a to ACTIVE bank b command		t_{RRD}	14		15		20		ns	
Transition time		t_T	0.3	1.2	0.3	1.2	0.3	1.2	ns	7
WRITE recovery time		t_{WR}	1 CLK + 7ns		1 CLK + 7.5ns		1 CLK + 7ns		ns	24
			14		15		15		ns	25
Exit SELF REFRESH to ACTIVE command		t_{XSR}	67		75		80		ns	20

*Module AC timing parameters comply with PC100 and PC133 Design Specs, based on component parameters.



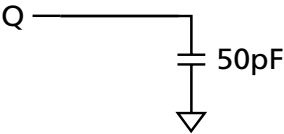
AC FUNCTIONAL CHARACTERISTICS

(Notes: 5, 6, 7, 8, 9, 11; notes appear following parameter tables)

PARAMETER	SYMBOL	-13E	-133	-10E	UNITS	NOTES
READ/WRITE command to READ/WRITE command	t_{CCD}	1	1	1	t_{CK}	17
CKE to clock disable or power-down entry mode	t_{CKED}	1	1	1	t_{CK}	14, 32
CKE to clock enable or power-down exit setup mode	t_{PED}	1	1	1	t_{CK}	14, 32
DQM to input data delay	t_{DQD}	0	0	0	t_{CK}	17, 32
DQM to data mask during WRITES	t_{DQM}	0	0	0	t_{CK}	17, 32
DQM to data high-impedance during READs	t_{DQZ}	2	2	2	t_{CK}	17, 32
WRITE command to input data delay	t_{DWD}	0	0	0	t_{CK}	17, 32
Data-in to ACTIVE command	t_{DAL}	4	5	4	t_{CK}	15, 21, 32
Data-in to PRECHARGE command	t_{DPL}	2	2	2	t_{CK}	16, 21, 32
Last data-in to burst STOP command	t_{BDL}	1	1	1	t_{CK}	17, 32
Last data-in to new READ/WRITE command	t_{CDL}	1	1	1	t_{CK}	17, 32
Last data-in to PRECHARGE command	t_{RDL}	2	2	2	t_{CK}	16, 21, 32
LOAD MODE REGISTER command to ACTIVE or REFRESH command	t_{MRD}	2	2	2	t_{CK}	26
Data-out to high-impedance from PRECHARGE command	CL = 3	$t_{ROH(3)}$	3	3	t_{CK}	17, 32
	CL = 2	$t_{ROH(2)}$	2	2	t_{CK}	17, 32

NOTES

1. All voltages referenced to V_{SS} .
2. This parameter is sampled. V_{DD} , $V_{DDQ} = +3.3V$; $f = 1\text{ MHz}$, $T_A = 25^\circ\text{C}$; pin under test biased at 1.4V.
3. I_{DD} is dependent on output loading and cycle rates. Specified values are obtained with minimum cycle time and the outputs open.
4. Enables on-chip refresh and address counters.
5. The minimum specifications are used only to indicate cycle time at which proper operation over the full temperature range is ensured; ($0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$).
6. An initial pause of 100 μs is required after power-up, followed by two AUTO REFRESH commands, before proper device operation is ensured. (V_{DD} and V_{DDQ} must be powered up simultaneously. V_{SS} and V_{SSQ} must be at same potential.) The two AUTO REFRESH command wake-ups should be repeated any time the t_{REF} refresh requirement is exceeded.
7. AC characteristics assume $t_T = 1\text{ ns}$.
8. In addition to meeting the transition rate specification, the clock and CKE must transit between V_{IH} and V_{IL} (or between V_{IL} and V_{IH}) in a monotonic manner.
9. Outputs measured at 1.5V with equivalent load:


10. t_{HZ} defines the time at which the output achieves the open circuit condition; it is not a reference to V_{OH} or V_{OL} . The last valid data element will meet t_{OH} before going High-Z.
11. AC timing and I_{DD} tests have $V_{IL} = 0V$ and $V_{IH} = 3V$, with timing referenced to 1.5V crossover point. If the input transition time is longer than 1 ns, then the timing is referenced at $V_{IL}(\text{MAX})$ and $V_{IH}(\text{MIN})$ and no longer at the 1.5V crossover point.
12. Other input signals are allowed to transition no more than once every two clocks and are otherwise at valid V_{IH} or V_{IL} levels.
13. I_{DD} specifications are tested after the device is properly initialized.
14. Timing actually specified by t_{CKs} ; clock(s) specified as a reference only at minimum cycle rate.
15. Timing actually specified by t_{WR} plus t_{RP} ; clock(s) specified as a reference only at minimum cycle rate.
16. Timing actually specified by t_{WR} .
17. Required clocks are specified by JEDEC functionality and are not dependent on any timing parameter.
18. The I_{DD} current will increase or decrease proportionally according to the amount of frequency alteration for the test condition.
19. Address transitions average one transition every two clocks.
20. CLK must be toggled a minimum of two times during this period.
21. Based on $t_{CK} = 10\text{ ns}$ for -10E, and $t_{CK} = 7.5\text{ ns}$ for -133 and -13E.
22. V_{IH} overshoot: $V_{IH}(\text{MAX}) = V_{DDQ} + 2V$ for a pulse width $\leq 3\text{ ns}$, and the pulse width cannot be greater than one third of the cycle rate. V_{IL} undershoot: $V_{IL}(\text{MIN}) = -2V$ for a pulse width $\leq 3\text{ ns}$.
23. The clock frequency must remain constant (stable clock is defined as a signal cycling within timing constraints specified for the clock pin) during access or precharge states (READ, WRITE, including t_{WR} , and PRECHARGE commands). CKE may be used to reduce the data rate.
24. Auto precharge mode only. The precharge timing budget (t_{RP}) begins 7ns for -13E; 7.5ns for -133 and 7ns for -10E after the first clock delay, after the last WRITE is executed. May not exceed limit set for precharge mode.
25. Precharge mode only.
26. JEDEC and PC100 specify three clocks.
27. t_{AC} for -133/-13E at CL = 3 with no load is 4.6ns and is guaranteed by design.
28. Parameter guaranteed by design.
29. The value of t_{RAS} use in -13E speed grade module SPDs is calculated from $t_{RC} - t_{RP} = 45\text{ ns}$.
30. For -10E, CL = 2 and $t_{CK} = 10\text{ ns}$; for -133, CL = 3 and $t_{CK} = 7.5\text{ ns}$; for -13E, CL = 2 and $t_{CK} = 7.5\text{ ns}$.
31. CKE is HIGH during refresh command period $t_{RFC}(\text{MIN})$ else CKE is LOW. The I_{DD6} limit is actually a nominal value and does not result in a fail value.
32. This AC timing function will show an extra clock cycle when in registered mode.
33. Leakage number reflects the worst case leakage possible through the module pin, not what each memory device contributes.

SPD CLOCK AND DATA CONVENTIONS

Data states on the SDA line can change only during SCL LOW. SDA state changes during SCL HIGH are reserved for indicating start and stop conditions (Figures 1 and 2).

SPD START CONDITION

All commands are preceded by the start condition, which is a HIGH-to-LOW transition of SDA when SCL is HIGH. The SPD device continuously monitors the SDA and SCL lines for the start condition and will not respond to any command until this condition has been met.

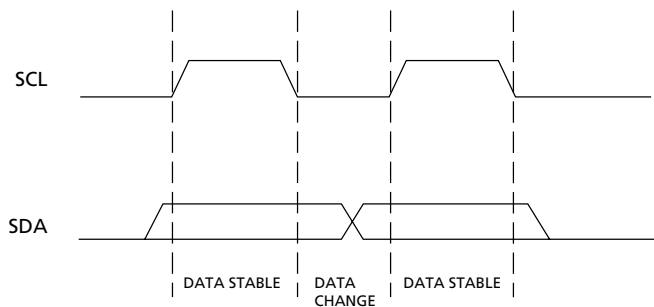
SPD STOP CONDITION

All communications are terminated by a stop condition, which is a LOW-to-HIGH transition of SDA when SCL is HIGH. The stop condition is also used to place the SPD device into standby power mode.

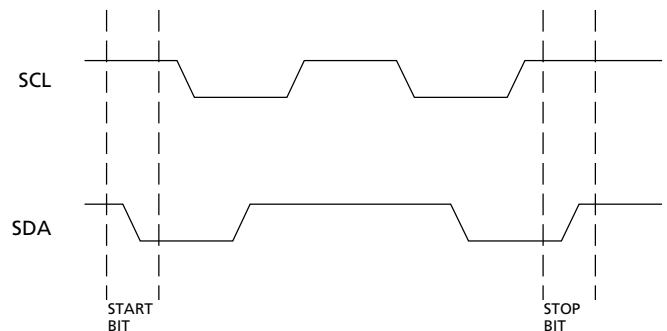
SPD ACKNOWLEDGE

Acknowledge is a software convention used to indicate successful data transfers. The transmitting device, either master or slave, will release the bus after transmitting eight bits. During the ninth clock cycle, the receiver will pull the SDA line LOW to acknowledge that it received the eight bits of data (Figure 3).

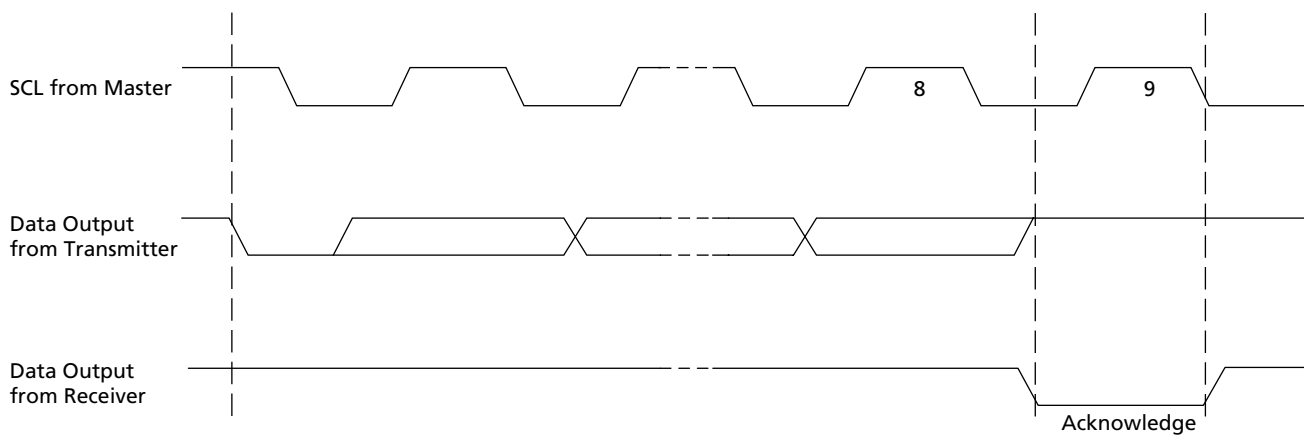
The SPD device will always respond with an acknowledge after recognition of a start condition and its slave address. If both the device and a WRITE operation have been selected, the SPD device will respond with an acknowledge after the receipt of each subsequent eight-bit word. In the read mode the SPD device will transmit eight bits of data, release the SDA line and monitor the line for an acknowledge. If an acknowledge is detected and no stop condition is generated by the master, the slave will continue to transmit data. If an acknowledge is not detected, the slave will terminate further data transmissions and await the stop condition to return to standby power mode.



**Figure 1
Data Validity**



**Figure 2
Definition of Start and Stop**



**Figure 3
Acknowledge Response From Receiver**

EEPROM DEVICE SELECT CODE

(THE MOST SIGNIFICANT BIT (B7) IS SENT FIRST)

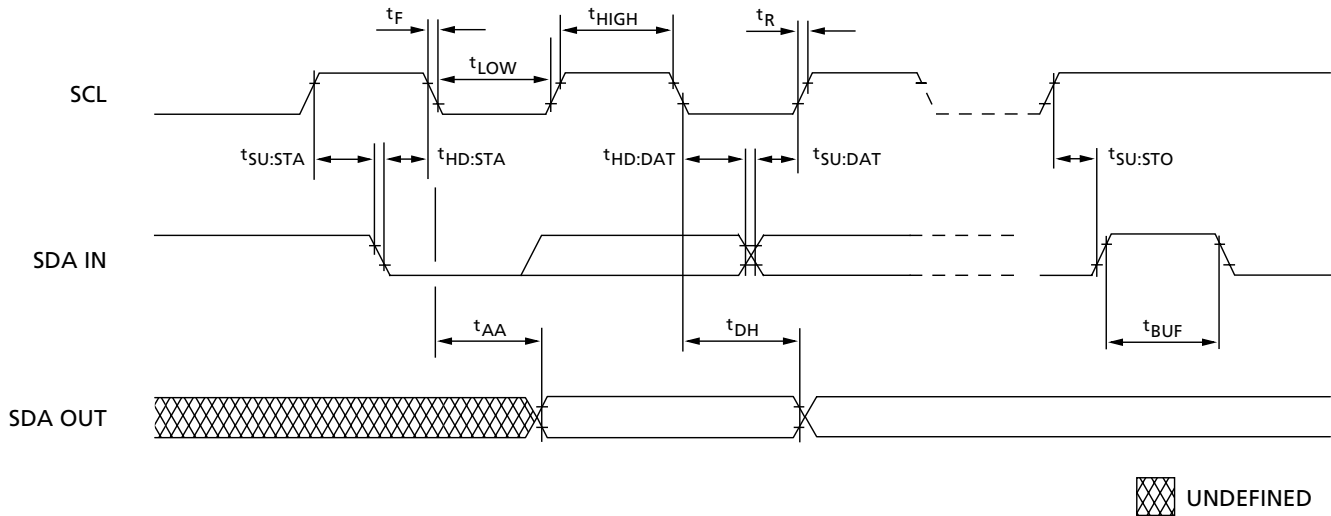
	DEVICE TYPE IDENTIFIER				CHIP ENABLE			\overline{RW}
	B7	B6	B5	B4	B3	B2	B1	B0
MEMORY AREA SELECT CODE (TWO ARRAYS)	1	0	1	0	E2	E1	E0	\overline{RW}
PROTECTION REGISTER SELECT CODE	0	1	1	0	E2	E1	E0	\overline{RW}

EEPROM OPERATING MODES

(X = V_{IH} OR V_{IL})

MODE	\overline{RW} BIT	\overline{WC}^1	BYTES	INITIAL SEQUENCE
CURRENT ADDRESS READ	1	X	1	START, DEVICE SELECT, $\overline{RW} = 1$
RANDOM ADDRESS READ	0	X	1	START, DEVICE SELECT, $\overline{RW} = 0$, ADDRESS
	1	X		RESTART, DEVICE SELECT, $\overline{RW} = 1$
SEQUENTIAL READ	1	X	≥ 1	SIMILAR TO CURRENT OR RANDOM ADDRESS READ
BYTE WRITE	0	V_{IL}	1	START, DEVICE SELECT, $\overline{RW} = 0$
PAGE WRITE	0	V_{IL}	≤ 16	START, DEVICE SELECT, $\overline{RW} = 0$

SPD EEPROM TIMING DIAGRAM



SERIAL PRESENCE-DETECT EEPROM TIMING PARAMETERS

SYMBOL	MIN	MAX	UNITS
t_{AA}	0.3	3.5	μs
t_{BUF}	4.7		μs
t_{DH}	300		ns
t_F		300	ns
$t_{HD:DAT}$	0		μs
$t_{HD:STA}$	4		μs

SYMBOL	MIN	MAX	UNITS
t_{HIGH}	4		μs
t_{LOW}	4.7		μs
t_R		1	μs
$t_{SU:DAT}$	250		ns
$t_{SU:STA}$	4.7		μs
$t_{SU:STO}$	4.7		μs

SERIAL PRESENCE-DETECT EEPROM DC OPERATING CONDITIONS

 (Note: 1) ($V_{DD} = +3.3V \pm 0.3V$)

PARAMETER/CONDITION	SYMBOL	MIN	MAX	UNITS
SUPPLY VOLTAGE	V_{DD}	3	3.6	V
INPUT HIGH VOLTAGE: Logic 1; All inputs	V_{IH}	$V_{DD} \times 0.7$	$V_{DD} + 0.5$	V
INPUT LOW VOLTAGE: Logic 0; All inputs	V_{IL}	-1	$V_{DD} \times 0.3$	V
OUTPUT LOW VOLTAGE: $I_{OUT} = 3mA$	V_{OL}	-	0.4	V
INPUT LEAKAGE CURRENT: $V_{IN} = GND$ to V_{DD}	I_{LI}	-	10	μA
OUTPUT LEAKAGE CURRENT: $V_{OUT} = GND$ to V_{DD}	I_{LO}	-	10	μA
STANDBY CURRENT: SCL = SDA = $V_{DD} - 0.3V$; All other inputs = GND or $3.3V + 10\%$	I_{SB}	-	30	μA
POWER SUPPLY CURRENT: SCL clock frequency = 100 KHz	I_{DD}	-	2	mA

SERIAL PRESENCE-DETECT EEPROM AC OPERATING CONDITIONS

 (Note: 1) ($V_{DD} = +3.3V \pm 0.3V$)

PARAMETER/CONDITION	SYMBOL	MIN	MAX	UNITS	NOTES
SCL LOW to SDA data-out valid	t_{AA}	0.3	3.5	μs	
Time the bus must be free before a new transition can start	t_{BUF}	4.7		μs	
Data-out hold time	t_{DH}	300		ns	
SDA and SCL fall time	t_F		300	ns	
Data-in hold time	$t_{HD:DAT}$	0		μs	
Start condition hold time	$t_{HD:STA}$	4		μs	
Clock HIGH period	t_{HIGH}	4		μs	
Noise suppression time constant at SCL, SDA inputs	t_I		100	ns	
Clock LOW period	t_{LOW}	4.7		μs	
SDA and SCL rise time	t_R		1	μs	
SCL clock frequency	t_{SCL}		100	KHz	
Data-in setup time	$t_{SU:DAT}$	250		ns	
Start condition setup time	$t_{SU:STA}$	4.7		μs	
Stop condition setup time	$t_{SU:STO}$	4.7		μs	
WRITE cycle time	t_{WRC}		10	ms	2

- NOTE:**
- All voltages referenced to V_{SS} .
 - The SPD EEPROM WRITE cycle time (t_{WRC}) is the time from a valid stop condition of a write sequence to the end of the EEPROM internal erase/program cycle. During the WRITE cycle, the EEPROM bus interface circuit is disabled, SDA remains HIGH due to pull-up resistor, and the EEPROM does not respond to its slave address.



SERIAL PRESENCE-DETECT MATRIX

(Note: 1)

BYTE	DESCRIPTION	ENTRY (VERSION)	MT18LSDT1672G	MT18LSDT3272G	MT18LSDT6472G
0	NUMBER OF BYTES USED BY MICRON	128	80	80	80
1	TOTAL NUMBER OF SPD MEMORY BYTES	256	08	08	08
2	MEMORY TYPE	SDRAM	04	04	04
3	NUMBER OF ROW ADDRESSES	12 or 13	0C	0C	0D
4	NUMBER OF COLUMN ADDRESSES	10 or 11	0A	0B	0B
5	NUMBER OF BANKS	1	01	01	01
6	MODULE DATA WIDTH	72	48	48	48
7	MODULE DATA WIDTH (continued)	0	00	00	00
8	MODULE VOLTAGE INTERFACE LEVELS	LVTTL	01	01	01
9	SDRAM CYCLE TIME, ^t CK (CAS LATENCY = 3)	7 (-13E) 7.5 (-133) 8 (-10E)	70 75 80	70 75 80	70 75 80
10	SDRAM ACCESS FROM CLOCK, ^t AC (CAS LATENCY = 3)	5.4 (-13E/-133) 6 (-10E)	54 60	54 60	54 60
11	MODULE CONFIGURATION TYPE	ECC	02	02	02
12	REFRESH RATE/TYPE	7.8/15.6μs/SELF	80	80	82
13	SDRAM WIDTH (PRIMARY SDRAM)	4	04	04	04
14	ERROR-CHECKING SDRAM DATA WIDTH	4	04	04	04
15	MIN. CLOCK DELAY FROM BACK-TO-BACK RANDOM COLUMN ADDRESSES, ^t CCD	1	01	01	01
16	BURST LENGTHS SUPPORTED	1, 2, 4, 8, PAGE	8F	8F	8F
17	NUMBER OF BANKS ON SDRAM DEVICE	4	04	04	04
18	CAS LATENCIES SUPPORTED	2, 3	06	06	06
19	CS LATENCY	0	01	01	01
20	WE LATENCY	0	01	01	01
21	SDRAM MODULE ATTRIBUTES	-133	1F	1F	1F
22	SDRAM DEVICE ATTRIBUTES: GENERAL	0E	0E	0E	0E
23	SDRAM CYCLE TIME, ^t CK (CAS LATENCY = 2)	7.5 (-13E) 10 (-133/-10E)	75 A0	75 A0	75 A0
24	SDRAM ACCESS FROM CLK, ^t AC (CAS LATENCY = 2)	5.4 (-13E) 6 (-133/-10E)	54 60	54 60	54 60
25	SDRAM CYCLE TIME, ^t CK (CAS LATENCY = 1)	–	00	00	00
26	SDRAM ACCESS FROM CLK, ^t AC (CAS LATENCY = 1)	–	00	00	00
27	MINIMUM ROW PRECHARGE TIME, ^t RP	15 (-13E) 20 (-133/-10E)	0F 14	0F 14	0F 14
28	MINIMUM ROW ACTIVE TO ROW ACTIVE, ^t RRD	14 (-13E) 15 (-133) 20 (-10E)	0E 0F 14	0E 0F 14	0E 0F 14
29	MINIMUM RAS# TO CAS# DELAY, ^t RCD	15 (-13E) 20 (-133/-10E)	0F 14	0F 14	0F 14
30	MINIMUM RAS# PULSE WIDTH, ^t RAS (Note: 2)	45 (-13E) 44 (-133) 50 (-10E)	2D 2C 32	2D 2C 32	2D 2C 32

- NOTE:** 1. "1"/"0": Serial Data, "driven to HIGH"/"driven to LOW."
2. The value of ^tRAS used for the -13E module is calculated from ^tRC - ^tRP. Actual device spec. value is 37ns.



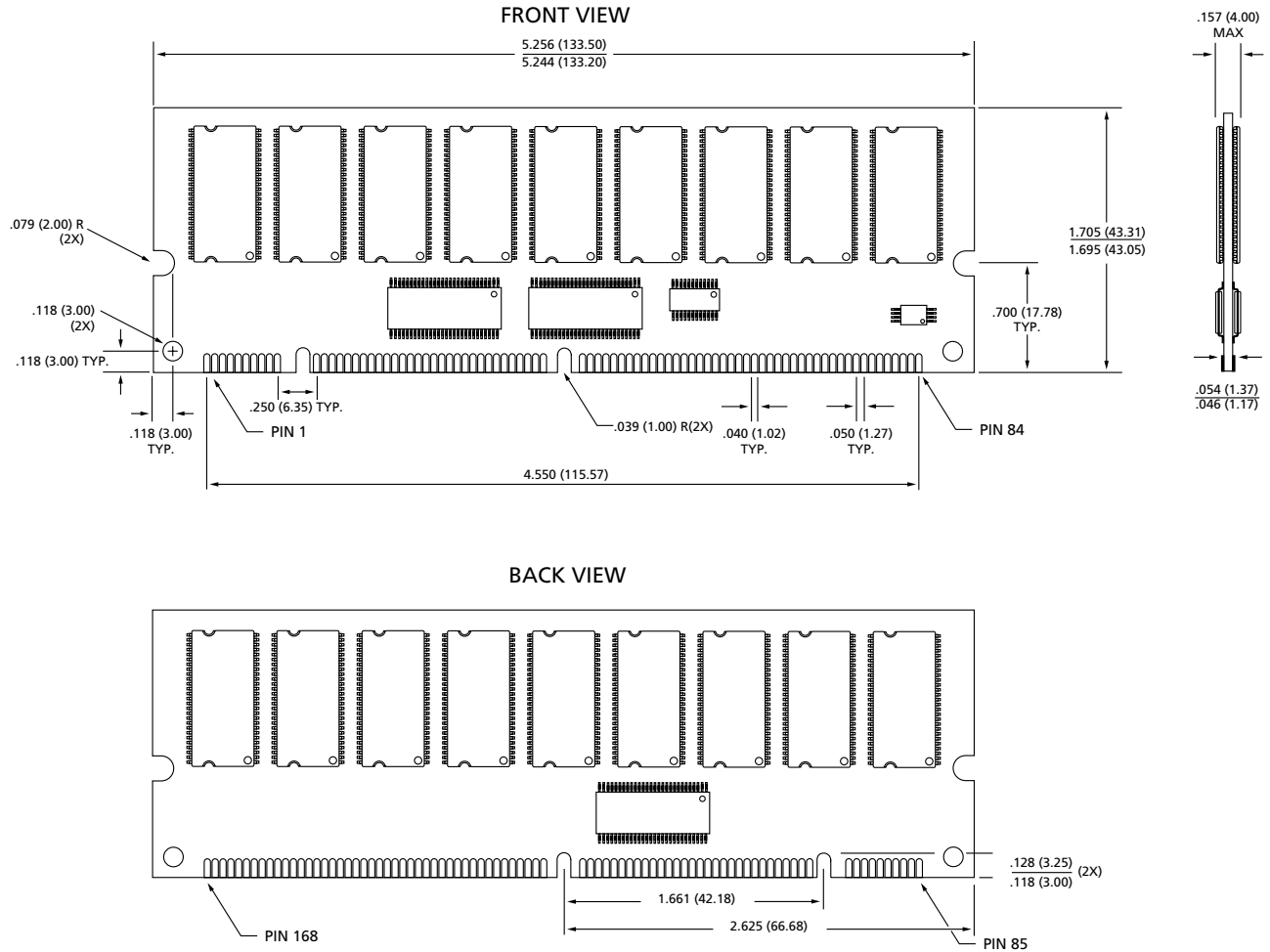
SERIAL PRESENCE-DETECT MATRIX (continued)

(Note: 1, 2)

BYTE	DESCRIPTION	ENTRY (VERSION)	MT18LSDT1672G	MT18LSDT3272G	MT18LSDT6472G
31	MODULE BANK DENSITY	128MB/256MB/512MB	20	40	80
32	COMMAND AND ADDRESS SETUP TIME, ^t AS, ^t CMS	1.5 (-13E/-133) 2 (-10E)	15 20	15 20	15 20
33	COMMAND AND ADDRESS HOLD TIME, ^t AH, ^t CMH	0.8 (-13E/133) 1 (-10E)	08 10	08 10	08 10
34	DATA SIGNAL INPUT SETUP TIME, ^t DS	1.5 (-13E/-133) 2 (-10E)	15 20	15 20	15 20
35	DATA SIGNAL INPUT HOLD TIME, ^t DH	0.8 (-13E/-133) 1 (-10E)	08 10	08 10	08 10
36-61	RESERVED		00	00	00
62	SPD REVISION	REV. 1.2	12	12	12
63	CHECKSUM FOR BYTES 0-62	-13E -133 -10E	91 D7 1F	B2 F8 40	F5 3B 83
64	MANUFACTURER'S JEDEC ID CODE	MICRON	2C	2C	2C
65-71	MANUFACTURER'S JEDEC ID CODE (CONT.)		FF	FF	FF
72	MANUFACTURING LOCATION		01 02 03 04 05 06 07 08 09 10 11	01 02 03 04 05 06 07 08 09 0A 0B	01 02 03 04 05 06 07 08 09 0A 0B
73-90	MODULE PART NUMBER (ASCII)		xx	xx	xx
91	PCB IDENTIFICATION CODE	1 2 3 4 5 6 7 8 9	01 02 03 04 05 06 07 08 09	01 02 03 04 05 06 07 08 09	01 02 03 04 05 06 07 08 09
92	IDENTIFICATION CODE (CONT.)	0	00	00	00
93	YEAR OF MANUFACTURE IN BCD		xx	xx	xx
94	WEEK OF MANUFACTURE IN BCD		xx	xx	xx
95-98	MODULE SERIAL NUMBER		xx	xx	xx
99-125	MANUFACTURER-SPECIFIC DATA (RSVD)		-	-	-
126	SYSTEM FREQUENCY	100/133 MHz	64	64	64
127	SDRAM COMPONENT AND CLOCK DETAIL		8F	8F	8F

NOTE: 1. "1"/"0": Serial Data, "driven to HIGH"/"driven to LOW."
2. x = Variable Data.

168-PIN DIMM
(128MB/256MB/512MB)



NOTE: 1. All dimensions in inches (millimeters) $\frac{\text{MAX}}{\text{MIN}}$ or typical where noted.

DATA SHEET DESIGNATION

Preliminary: This data sheet contains initial characterization limits that are subject to change upon full characterization of production devices.



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