Motorola Preferred Device

TMOS POWER FET 60 AMPERES

60 VOLTS

RDS(on) = 0.014 OHM

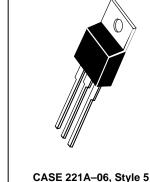
# Designer's<sup>™</sup> Data Sheet HDTMOS E-FET <sup>™</sup> Power Field Effect Transistor N-Channel Enhancement-Mode Silicon Gate

This advanced high–cell density HDTMOS power FET is designed to withstand high energy in the avalanche and commutation modes. The new energy efficient design also offers a drain–to–source diode with a fast recovery time. Designed for low voltage, high speed switching applications in power supplies, converters and PWM motor controls, these devices are particularly well suited for bridge circuits where diode speed and commutating safe operating areas are critical and offer additional safety margin against unexpected voltage transients.

- Avalanche Energy Specified
- Source-to-Drain Diode Recovery Time Comparable to a Discrete Fast Recovery Diode
- Diode is Characterized for Use in Bridge Circuits
- IDSS and VDS(on) Specified at Elevated Temperature

**MAXIMUM RATINGS** ( $T_{C} = 25^{\circ}C$  unless otherwise noted)





TO-220AB

Rating	Symbol	Value	Unit
Drain–Source Voltage	VDSS	60	Vdc
Drain–Gate Voltage (R <sub>GS</sub> = 1.0 M $\Omega$ )	VDGR	60	Vdc
Gate–Source Voltage — Continuous — Non–Repetitive (t <sub>p</sub> ≤ 10 ms)	VGS VGSM	± 20 ± 30	Vdc Vpk
Drain Current — Continuous — Continuous @ 100°C — Single Pulse (t <sub>p</sub> ≤ 10 μs)	ID ID IDM	60 42.3 180	Adc Apk
Total Power Dissipation Derate above 25°C	PD	150 1.0	Watts W/°C
Operating and Storage Temperature Range	TJ, Tstg	-55 to 175	°C
Single Pulse Drain–to–Source Avalanche Energy — Starting T <sub>J</sub> = 25°C ( $V_{DD}$ = 25 Vdc, $V_{GS}$ = 10 Vdc, Peak I <sub>L</sub> = 60 Apk, L = 0.3 mH, R <sub>G</sub> = 25 $\Omega$ )	EAS	540	mJ
Thermal Resistance — Junction to Case — Junction to Ambient	R <sub>θJC</sub> R <sub>θJA</sub>	1.0 62.5	°C/W
Maximum Lead Temperature for Soldering Purposes, 1/8" from case for 10 seconds	т∟	260	°C

**Designer's Data for "Worst Case" Conditions** — The Designer's Data Sheet permits the design of most circuits entirely from the information presented. SOA Limit curves — representing boundaries on device characteristics — are given to facilitate "worst case" design.

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Preferred devices are Motorola recommended choices for future use and best overall value.

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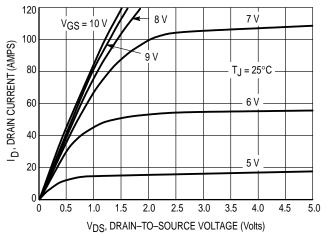
ELECTRICAL CHARACTERISTICS (T. J = 25°C unless otherwise noted)

	acteristic	Symbol	Min	Тур	Мах	Unit
OFF CHARACTERISTICS						
Drain-to-Source Breakdown Voltage (V <sub>GS</sub> = 0 Vdc, I <sub>D</sub> = 250 μAdc) Temperature Coefficient (Positive)	(C <sub>pk</sub> ≥2.0) (3)	V <sub>(BR)</sub> DSS	60		_	Vdc mV/°C
Zero Gate Voltage Drain Current		1200				μAdc
$(V_{DS} = 60 \text{ Vdc}, V_{GS} = 0 \text{ Vdc})$ $(V_{DS} = 60 \text{ Vdc}, V_{GS} = 0 \text{ Vdc}, T_{J} = 0 \text{ Vdc}$	125°C)	IDSS	_		10 100	μλάο
Gate–Body Leakage Current ( $V_{GS} = \pm 20 \text{ Vdc}, V_{DS} = 0 \text{ Vdc}$ )		IGSS	_	_	100	nAdc
ON CHARACTERISTICS (1)						
Gate Threshold Voltage ( $V_{DS} = V_{GS}$ , $I_D = 250 \mu$ Adc) Threshold Temperature Coefficient	$(C_{pk} \ge 3.0) (3) \label{eq:constraint}$ (Negative)	VGS(th)	2.0	3.0 7.0	4.0	Vdc mV/°C
Static Drain–to–Source On–Resistan (V <sub>GS</sub> = 10 Vdc, I <sub>D</sub> = 30 Adc)	ce $(C_{pk} \ge 3.0)$ (3)	R <sub>DS(on)</sub>	_	0.011	0.014	Ohm
Drain-to-Source On-Voltage (V <sub>GS</sub> = $(I_D = 60 \text{ Adc})$ ( $I_D = 30 \text{ Adc}$ , $T_J = 125^{\circ}\text{C}$ )	: 10 Vdc)	V <sub>DS(on)</sub>	_		1.0 0.9	Vdc
Forward Transconductance $(V_{DS} = 5.0 \text{ Vdc}, I_{D} = 30 \text{ Adc})$		9FS	15	20	_	mhos
YNAMIC CHARACTERISTICS		••		•		
Input Capacitance		C <sub>iss</sub>	_	1950	2800	pF
Output Capacitance	(V <sub>DS</sub> = 25 Vdc, V <sub>GS</sub> = 0 Vdc, f = 1.0 MHz)	C <sub>oss</sub>	_	660	924	-
Transfer Capacitance	I = 1.0  Will(z)	C <sub>rss</sub>	_	147	300	
WITCHING CHARACTERISTICS (2)		100		1		
Turn–On Delay Time		<sup>t</sup> d(on)	_	14	26	ns
Rise Time	$(V_{DD} = 30 \text{ Vdc}, I_D = 60 \text{ Adc},$	tr	_	197	394	1
Turn–Off Delay Time	V <sub>GS</sub> = 10 Vdc, R <sub>G</sub> = 9.1 Ω)	<sup>t</sup> d(off)	_	50	102	1
Fall Time		t <sub>f</sub>	_	124	246	1
Gate Charge		Q <sub>T</sub>	_	51	71	nC
(See Figure 8)	(V <sub>DS</sub> = 48 Vdc, I <sub>D</sub> = 60 Adc,	Q <sub>1</sub>	_	12	_	
	$V_{GS} = 10 \text{ Vdc}$	Q <sub>2</sub>	_	24	_	
		Q3	_	21	_	
OURCE-DRAIN DIODE CHARACTE	RISTICS					
OURCE-DRAIN DIODE CHARACTE Forward On-Voltage	RISTICS (I <sub>S</sub> = 60 Adc, V <sub>GS</sub> = 0 Vdc) (I <sub>S</sub> = 60 Adc, V <sub>GS</sub> = 0 Vdc, T <sub>J</sub> = 125°C)	V <sub>SD</sub>		0.99 0.89	1.2	Vdc
	(I <sub>S</sub> = 60 Adc, V <sub>GS</sub> = 0 Vdc)				1.2	Vdc ns
Forward On–Voltage	$(I_{S} = 60 \text{ Adc}, V_{GS} = 0 \text{ Vdc})$ $(I_{S} = 60 \text{ Adc}, V_{GS} = 0 \text{ Vdc}, T_{J} = 125^{\circ}\text{C})$	V <sub>SD</sub>		0.89		
Forward On–Voltage Reverse Recovery Time	(I <sub>S</sub> = 60 Adc, V <sub>GS</sub> = 0 Vdc)	V <sub>SD</sub>		0.89 60		
Forward On–Voltage Reverse Recovery Time	$(I_{S} = 60 \text{ Adc}, V_{GS} = 0 \text{ Vdc})$ $(I_{S} = 60 \text{ Adc}, V_{GS} = 0 \text{ Vdc}, T_{J} = 125^{\circ}\text{C})$ $(I_{S} = 60 \text{ Adc}, V_{GS} = 0 \text{ Vdc},$	V <sub>SD</sub>	_	0.89 60 36		
Forward On–Voltage Reverse Recovery Time (See Figure 15) Reverse Recovery Stored Charge	$(I_{S} = 60 \text{ Adc}, V_{GS} = 0 \text{ Vdc})$ $(I_{S} = 60 \text{ Adc}, V_{GS} = 0 \text{ Vdc}, T_{J} = 125^{\circ}\text{C})$ $(I_{S} = 60 \text{ Adc}, V_{GS} = 0 \text{ Vdc},$	V <sub>SD</sub> t <sub>rr</sub> t <sub>a</sub> t <sub>b</sub>	_	0.89 60 36 24		ns
Reverse Recovery Time (See Figure 15)	$(I_{S} = 60 \text{ Adc}, \text{ V}_{GS} = 0 \text{ Vdc})$ $(I_{S} = 60 \text{ Adc}, \text{ V}_{GS} = 0 \text{ Vdc}, \text{ T}_{J} = 125^{\circ}\text{C})$ $(I_{S} = 60 \text{ Adc}, \text{ V}_{GS} = 0 \text{ Vdc}, \text{ d}_{S}/\text{dt} = 100 \text{ A}/\mu\text{s})$ ab to center of die)	V <sub>SD</sub> t <sub>rr</sub> t <sub>a</sub> t <sub>b</sub>	_	0.89 60 36 24		ns

(2) Switching characteristics are independent of operating junction temperature.
(3) Reflects typical values. Control | Max limit - Typ |

$$C_{pk} = \left| \frac{\text{Max limit} - \text{Typ}}{2} \right|$$

## **TYPICAL ELECTRICAL CHARACTERISTICS**





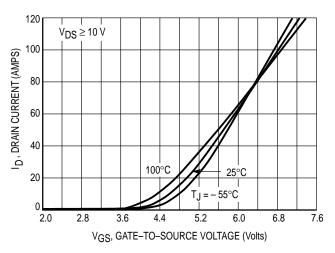
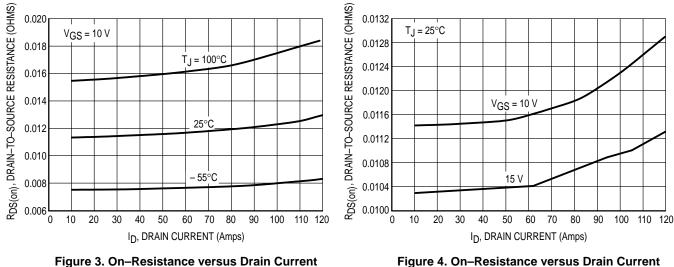


Figure 2. Transfer Characteristics



and Temperature

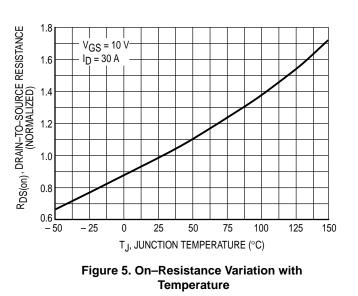


Figure 4. On–Resistance versus Drain Current and Gate Voltage

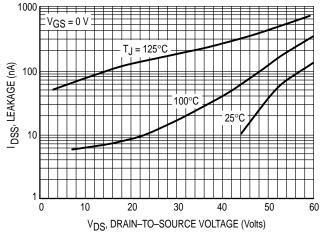


Figure 6. Drain–To–Source Leakage Current versus Voltage

## POWER MOSFET SWITCHING

Switching behavior is most easily modeled and predicted by recognizing that the power MOSFET is charge controlled. The lengths of various switching intervals ( $\Delta t$ ) are determined by how fast the FET input capacitance can be charged by current from the generator.

The published capacitance data is difficult to use for calculating rise and fall because drain–gate capacitance varies greatly with applied voltage. Accordingly, gate charge data is used. In most cases, a satisfactory estimate of average input current ( $I_{G(AV)}$ ) can be made from a rudimentary analysis of the drive circuit so that

#### $t = Q/I_G(AV)$

During the rise and fall time interval when switching a resistive load,  $V_{GS}$  remains virtually constant at a level known as the plateau voltage,  $V_{SGP}$ . Therefore, rise and fall times may be approximated by the following:

 $t_r = Q_2 \times R_G/(V_{GG} - V_{GSP})$ 

 $t_f = Q_2 \times R_G/V_{GSP}$ 

where

 $V_{GG}$  = the gate drive voltage, which varies from zero to  $V_{GG}$ 

R<sub>G</sub> = the gate drive resistance

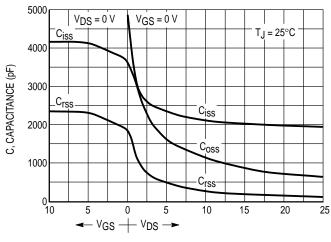
and Q<sub>2</sub> and V<sub>GSP</sub> are read from the gate charge curve.

During the turn-on and turn-off delay times, gate current is not constant. The simplest calculation uses appropriate values from the capacitance curves in a standard equation for voltage change in an RC network. The equations are:

 $t_{d(on)} = R_G C_{iss} In [V_{GG}/(V_{GG} - V_{GSP})]$  $t_{d(off)} = R_G C_{iss} In (V_{GG}/V_{GSP})$  The capacitance (C<sub>ISS</sub>) is read from the capacitance curve at a voltage corresponding to the off–state condition when calculating  $t_{d(on)}$  and is read at a voltage corresponding to the on–state when calculating  $t_{d(off)}$ .

At high switching speeds, parasitic circuit elements complicate the analysis. The inductance of the MOSFET source lead, inside the package and in the circuit wiring which is common to both the drain and gate current paths, produces a voltage at the source which reduces the gate drive current. The voltage is determined by Ldi/dt, but since di/dt is a function of drain current, the mathematical solution is complex. The MOSFET output capacitance also complicates the mathematics. And finally, MOSFETs have finite internal gate resistance which effectively adds to the resistance of the driving source, but the internal resistance is difficult to measure and, consequently, is not specified.

The resistive switching time variation versus gate resistance (Figure 9) shows how typical switching performance is affected by the parasitic circuit elements. If the parasitics were not present, the slope of the curves would maintain a value of unity regardless of the switching speed. The circuit used to obtain the data is constructed to minimize common inductance in the drain and gate circuit loops and is believed readily achievable with board mounted components. Most power electronic loads are inductive; the data in the figure is taken with a resistive load, which approximates an optimally snubbed inductive load. Power MOSFETs may be safely operated into an inductive load; however, snubbing reduces switching losses.



GATE-TO-SOURCE OR DRAIN-TO-SOURCE VOLTAGE (Volts)

**Figure 7. Capacitance Variation** 

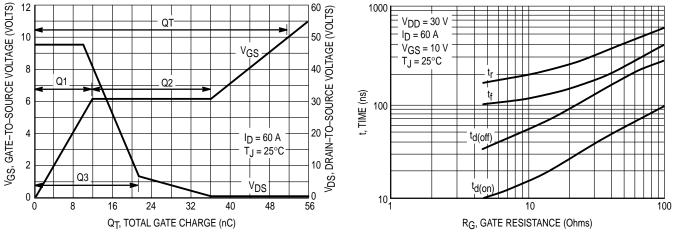


Figure 8. Gate–To–Source and Drain–To–Source Voltage versus Total Charge

Figure 9. Resistive Switching Time Variation versus Gate Resistance

### DRAIN-TO-SOURCE DIODE CHARACTERISTICS

The switching characteristics of a MOSFET body diode are very important in systems using it as a freewheeling or commutating diode. Of particular interest are the reverse recovery characteristics which play a major role in determining switching losses, radiated noise, EMI and RFI.

System switching losses are largely due to the nature of the body diode itself. The body diode is a minority carrier device, therefore it has a finite reverse recovery time,  $t_{rr}$ , due to the storage of minority carrier charge,  $Q_{RR}$ , as shown in the typical reverse recovery wave form of Figure 12. It is this stored charge that, when cleared from the diode, passes through a potential and defines an energy loss. Obviously, repeatedly forcing the diode through reverse recovery further increases switching losses. Therefore, one would like a diode with short  $t_{rr}$  and low  $Q_{RR}$  specifications to minimize these losses.

The abruptness of diode reverse recovery effects the amount of radiated noise, voltage spikes, and current ringing. The mechanisms at work are finite irremovable circuit parasitic inductances and capacitances acted upon by high di/dts. The diode's negative di/dt during  $t_a$  is directly controlled by the device clearing the stored charge. However, the positive di/dt during  $t_b$  is an uncontrollable diode characteristic and is usually the culprit that induces current ringing. Therefore, when comparing diodes, the ratio of  $t_b/t_a$  serves as a good indicator of recovery abruptness and thus gives a comparative estimate of probable noise generated. A ratio of 1 is considered ideal and values less than 0.5 are considered snappy.

Compared to Motorola standard cell density low voltage MOSFETs, high cell density MOSFET diodes are faster (shorter  $t_{fr}$ ), have less stored charge and a softer reverse recovery characteristic. The softness advantage of the high cell density diode means they can be forced through reverse recovery at a higher di/dt than a standard cell MOSFET diode without increasing the current ringing or the noise generated. In addition, power dissipation incurred from switching the diode will be less due to the shorter recovery time and lower switching losses.

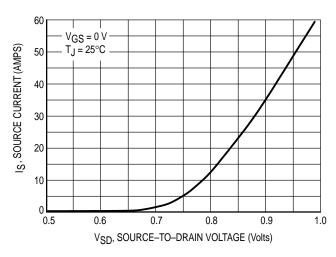
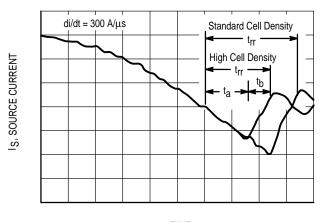


Figure 10. Diode Forward Voltage versus Current

Motorola TMOS Power MOSFET Transistor Device Data



t, TIME

Figure 11. Reverse Recovery Time (trr)

#### SAFE OPERATING AREA

The Forward Biased Safe Operating Area curves define the maximum simultaneous drain-to-source voltage and drain current that a transistor can handle safely when it is forward biased. Curves are based upon maximum peak junction temperature and a case temperature (T<sub>C</sub>) of 25°C. Peak repetitive pulsed power limits are determined by using the thermal response data in conjunction with the procedures discussed in AN569, "Transient Thermal Resistance -General Data and Its Use."

Switching between the off-state and the on-state may traverse any load line provided neither rated peak current (IMM) nor rated voltage (VDSS) is exceeded, and that the transition time  $(t_r, t_f)$  does not exceed 10 µs. In addition the total power averaged over a complete switching cycle must not exceed  $(T_J(MAX) - T_C)/(R_{\theta JC}).$ 

A power MOSFET designated E-FET can be safely used in switching circuits with unclamped inductive loads. For reli-

able operation, the stored energy from circuit inductance dissipated in the transistor while in avalanche must be less than the rated limit and must be adjusted for operating conditions differing from those specified. Although industry practice is to rate in terms of energy, avalanche energy capability is not a constant. The energy rating decreases non-linearly with an increase of peak current in avalanche and peak junction temperature.

Although many E-FETs can withstand the stress of drainto-source avalanche at currents up to rated pulsed current (IDM), the energy rating is specified at rated continuous current (ID), in accordance with industry custom. The energy rating must be derated for temperature as shown in the accompanying graph (Figure 13). Maximum energy at currents below rated continuous ID can safely be assumed to equal the values indicated.

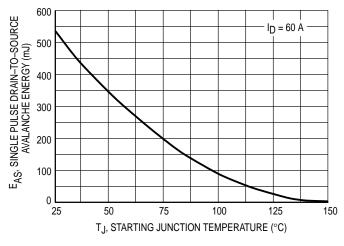
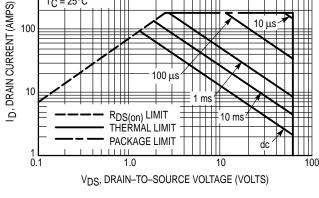


Figure 13. Maximum Avalanche Energy versus **Starting Junction Temperature** 



10 us

Figure 12. Maximum Rated Forward Biased Safe Operating Area

1000

100

V<sub>GS</sub> = 20 V

 $T_{C} = 25^{\circ}C$ 

SINGLE PULSE

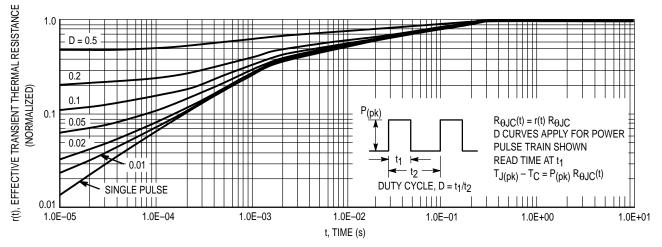


Figure 14. Thermal Response

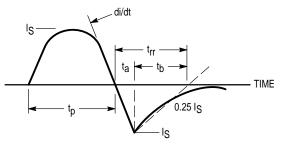
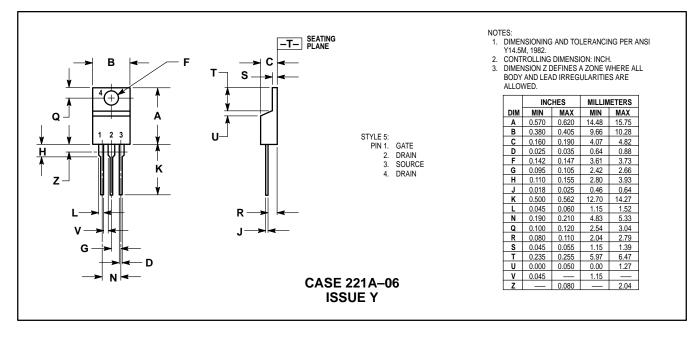


Figure 15. Diode Reverse Recovery Waveform

## PACKAGE DIMENSIONS



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