# LMX3305 <br> Triple Phase Locked Loop for RF Personal Communications 

## General Description

The LMX3305 contains three Phase Locked Loops (PLL) on a single chip. It has a RF PLL, an IF Rx PLL and an IF Tx PLL for CDMA applications. The RF fractional-N PLL uses a 16/17/20/21 quadruple modulus prescaler for PCS application and a 8/9/12/13 quadruple modulus prescaler for cellular application. Both quadruple modulus prescalers offer modulo 1 through 16 fractional compensation circuitry. The RF fractional-N PLL can be programmed to operate from 800 MHz to 1400 MHz in cellular band and 1200 MHz to 2300 MHz in PCS band. The IF Rx PLL and the IF Tx PLL are integer-N frequency synthesizers that operate from 45 MHz to 600 MHz with $8 / 9$ dual modulus prescalers. Serial data is transferred into the LMX3305 via a microwire interface (Clock, Data, \& LE).
The RF PLL provides a fastlock feature allowing the loop bandwidth to be increased by 3X during initial lock-on.
The supply voltage of the LMX3305 ranges from 2.7 V to 3.6 V . It typically consumes 9 mA of supply current and is packaged in a 24 -pin CSP package.

Features

- Three PLLs integrated on a single chip
- RF PLL fractional-N counter
- 16/17/20/21 RF quadruple modulus prescaler for PCS application
- 8/9/12/13 RF quadruple modulus prescaler for cellular application
- 2.7 V to 3.6 V operation
- Low current consumption: $\mathrm{I}_{\mathrm{CC}}=9 \mathrm{~mA}($ typ) at 3.0 V
- Programmable or logical power down mode: $\mathrm{I}_{\mathrm{CC}}=$ $10 \mu \mathrm{~A}$ (typ) at 3.0 V
- RF PLL Fastlock feature with timeout counter
- Digital lock detect
- Microwire Interface with data preset
- 24-pin CSP package


## Applications

- CDMA Cellular telephone systems


## Block Diagram



Functional Block Diagram


## Connection Diagram



Top View
Order Number LMX3305SLBX
See NS Package Number SLB24A

## Pin Descriptions

| Pin No． | Pin Name | 1／0 | Description |
| :---: | :---: | :---: | :---: |
| 1 | RF＿CP。 | $\bigcirc$ | Charge pump output for RF PLL．For connection to a loop filter for driving the input of an external VCO． |
| 2 | RF＿GND | PWR | RF PLL ground． |
| 3 | RF＿Fin | I | RF prescaler input．Small signal input from the RF Cellular or PCS VCO． |
| 4 | RF＿V VCO | PWR | RF PLL power supply voltage．Input may range from 2.7 V to 3.6 V ．Bypass capacitors should be placed as close as possible to this pin and be connected directly to the ground plane． $\mathrm{Tx}_{\mathrm{CC}}=\mathrm{Rx} \mathrm{V}_{\mathrm{CC}}=\mathrm{RF} \mathrm{V}_{\mathrm{CC}}$ ． |
| 5 | Lock＿Det | 0 | Multiplexed output of the RF，Rx，and Tx PLL＇s analog or digital lock detects．The outputs from the R， N and Fastlock counters can also be selected for test purposes． Refer to Section 2．3．4 for more detail． |
| 6 | N／C |  | No Connect． |
| 7 | RF＿En | I | RF PLL enable pin．A LOW on RF En powers down the RF PLL and TRI－STATE®s the RF PLL charge pump． |
| 8 | Rx＿En | I | Rx PLL enable pin．A LOW on Rx En powers down the Rx PLL and TRI－STATEs the Rx PLL charge pump． |
| 9 | Tx＿En | I | Tx PLL enable pin．A LOW on Tx En powers down the Tx PLL and TRI－STATEs the Tx PLL charge pump． |
| 10 | Clock | 1 | High impedance CMOS clock input．Data for the various counters is clocked on the rising edge into the CMOS input． |
| 11 | Data | I | Binary serial data input．Data entered MSB first． |
| 12 | LE | I | High impedance CMOS input．When LE goes LOW，data is transferred into the shift registers．When LE goes HIGH，data is transferred from the internal registers into the appropriate latches． |
| 13 | Tx＿FIN | I | Tx prescaler input．Small signal input from the Tx VCO． |
| 14 | Tx＿CP。 | 0 | Charge pump output for Tx PLL．For connection to a loop filter for driving the input of an external VCO． |
| 15 | Tx＿GND |  | Tx PLL ground． |
| 16 | Tx＿V ${ }_{\text {c }}$ | PWR | Tx PLL power supply voltage input．Input may range from 2.7 V to 3.6 V ．Bypass capacitors should be placed as close as possible to this pin and be connected directly to the ground plane． $\mathrm{Tx} \mathrm{V}_{\mathrm{CC}}=\mathrm{Rx} \mathrm{V}_{\mathrm{CC}}=\mathrm{RF} \mathrm{V}_{\mathrm{CC}}$ ． |
| 17 | $\mathrm{OSC}_{\text {IN }}$ | 1 | PLL reference input which has a $\mathrm{V}_{\mathrm{cc}} / 2$ input threshold and can be driven from an external CMOS or TLL logic gate．The R counter is clocked on the falling edge of the OSC $_{\text {IN }}$ signal． |
| 18 | Rx＿V ${ }_{\text {cc }}$ | PWR | Rx PLL power supply voltage．Input ranges from 2.7 V to 3.6 V ．Bypass capacitors should be placed as close as possible to this pin and be connected directly to the ground plane． $\mathrm{Tx}_{\mathrm{CC}}=\mathrm{Rx} \mathrm{V}_{\mathrm{CC}}=\mathrm{RF} \mathrm{V}_{\mathrm{CC}}$ ． |
| 19 | Rx＿GND | PWR | Rx PLL ground． |
| 20 | Rx＿CP。 | $\bigcirc$ | Charge pump output for Rx PLL．For connection to a loop filter for driving the input of an external VCO． |
| 21 | Rx＿Fin | 1 | Rx prescaler input．Small signal input from the Rx VCO． |
| 22 | RF＿Sw1 | 0 | An open drain NMOS output which can be use for bandswitching or Fastlocking the RF PLL．（During Fastlock mode a second loop filter damping resistor can be switched in parallel with the first to ground．）Refer to Section 2.5 .3 for more detail． |
| 23 | RF＿Sw2 | $\bigcirc$ | An open drain NMOS output which can be use for bandswitching or Fastlocking the RF PLL．（During Fastlock mode a second loop filter damping resistor can be switched in parallel with the first to ground．）Refer to Section 2.5 .3 for more detail． |
| 24 | $\mathrm{V}_{\mathrm{P}}$ | 0 | RF PLL charge pump power supply．An internal voltage doubler can be enabled in 3V applications to allow the RF charge pump to operate over a wider tuning range． |


| Absolute Maximum Ratings (Notes 1, 2) |  |
| :--- | ---: |
| Power Supply Voltage (PLL $\left.\mathrm{V}_{\mathrm{CC}}\right)$ | -0.3 V to +6.5 V |
| $($ Note 3) | -0.3 V to +6.5 V |
| Supply Voltage $\left(\mathrm{V}_{\mathrm{P}}\right)$ |  |
| Voltage on any Pin with | -0.3 V to $\mathrm{V}_{\mathrm{CC}}+0.3 \mathrm{~V}$ |
| GND $=0 \mathrm{~V}\left(\mathrm{~V}_{\mathrm{l}}\right)$ | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Storage Temperature Range $\left(\mathrm{T}_{\mathrm{S}}\right)$ | $+240^{\circ} \mathrm{C}$ |
| Lead Temp. (solder, 4 sec.) $\left(\mathrm{T}_{\mathrm{L}}\right)$ | 2 kV |
| ESD - Whole Body Model (Note 2) |  |

Recommended Operating Conditions (Note 1)

Power Supply Voltage (PLL $\mathrm{V}_{\mathrm{CC}}$ ) (Note 3)
2.7V to 3.6 V

Supply Voltage ( $\mathrm{V}_{\mathrm{P}}$ ) (Note 3)
Operating Temperature ( $\mathrm{T}_{\mathrm{A}}$ )
PLL $\mathrm{V}_{\mathrm{CC}}$ to 5.5 V
$-30^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$

## Electrical Characteristics

( $\mathrm{V}_{\mathrm{CC}}=\mathrm{V}_{\mathrm{P}}=3 \mathrm{~V},-30^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<85^{\circ} \mathrm{C}$ except as specified)

| Symbol | Parameter | Conditions | Value |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Typ | Max |  |

## GENERAL

| $\mathrm{I}_{\mathrm{Cc}}$ | Power Supply Current | $\begin{aligned} & \mathrm{RF}=\mathrm{On}, \mathrm{Rx}=\mathrm{On}, \mathrm{Tx}=\mathrm{On} \\ & 2.7 \mathrm{~V} \leq \mathrm{V}_{\mathrm{Cc}} \leq 3.6 \mathrm{~V} \end{aligned}$ |  | 9.0 | 15 | mA |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{I}_{\text {cc }}$-PWDN | Power Down Current |  |  | 10 | 75 | $\mu \mathrm{A}$ |
| $\mathrm{f}_{\mathrm{IN}}$ | PCS Operating Frequency |  | 1200 |  | 2300 | MHz |
|  | Cellular Operating Frequency |  | 800 |  | 1400 |  |
|  | IF Operating Frequency (Rx, Tx) |  | 45 |  | 600 |  |
| $\mathrm{f}_{\mathrm{Osc}}$ | Oscillator Frequency |  |  | 19.68 | 25 | MHz |
| $\mathrm{f}_{\phi}$ | Phase Detector Frequency |  |  |  | 10 | MHz |
| ${ }^{\text {Pf }}$ | PCS/Cellular/IF Input Sensitivity | $2.7 \mathrm{~V} \leq \mathrm{V}_{\mathrm{Cc}} \leq 3.6 \mathrm{~V}$ | -15 |  | +0 | dBm |
| $\mathrm{Pf}_{\text {Osc }}$ | Oscillator Sensitivity |  | 0.5 |  | $\mathrm{V}_{\mathrm{CC}}$ | $\mathrm{V}_{\mathrm{PP}}$ |
| RF PN | RF Phase Noise | $\mathrm{F}_{\text {OUT }}=1 \mathrm{GHz}$ |  | -70 |  | $\mathrm{dBc} / \mathrm{Hz}$ |
| IF PN | IF Phase Noise |  |  | -70 |  | aBc/iz |
|  | Fractional Spur @ 10 kHz | 1 kHz Loop Filter (Note 4) |  |  | -50 | dBc |
|  | Fractional Spur Harmonic |  | Attenuate $6 \mathrm{~dB} / \mathrm{OCT}$ after 10 kHz |  |  | dBc |
| Tsw | Switching Speed | 1 kHz Loop Filter, 60 MHz Jump to Within 1 kHz |  |  | 4.0 | ms |

## CHARGE PUMP

| RF $I_{\text {Do }}$ Source | RF Charge Pump Source Current | $\mathrm{V}_{\text {Do }}=\mathrm{V}_{\mathrm{P}} / 2$ (Note 5) | -22 | $I_{\text {NOM }}$ | 22 | \% |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| RF IDo Sink | RF Charge Pump Sink Current | $\mathrm{V}_{\text {Do }}=\mathrm{V}_{\mathrm{P}} / 2$ (Note 5) | -22 | $\mathrm{I}_{\text {NOM }}$ | 22 | \% |
| IF IDo Source | IF Charge Pump Source Current | $\mathrm{V}_{\mathrm{Do}}=\mathrm{V}_{\mathrm{CC}} / 2$ (Note 5) | 80 | 100 | 120 | $\mu \mathrm{A}$ |
| IF $\mathrm{I}_{\text {Do }}$ Sink | IF Charge Pump Sink Current | $\mathrm{V}_{\mathrm{Do}}=\mathrm{V}_{\mathrm{CC}} / 2$ (Note 5) | -80 | -100 | -120 | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {Do }}$-TRI | Charge Pump TRI-STATE Current | (Note 6) |  |  | 1000 | pA |
| $\mathrm{I}_{\mathrm{Do}}$ Sink vs $I_{\text {Do }}$ <br> Source | Charge Pump Sink vs Source Mismatch | $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ (Note 7) |  | 3 | 10 | \% |
| $\mathrm{l}_{\text {Do }}$ vs $\mathrm{V}_{\text {Do }}$ | Charge Pump Current vs Voltage | $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ (Note 6) |  | 8 | 15 | \% |
| $\mathrm{I}_{\text {Do }}$ vs $\mathrm{T}_{\text {A }}$ | Charge Pump Current vs Temperature | (Note 7) |  | 5 | 10 | \% |

DIGITAL INPUTS AND OUTPUTS

| $\mathrm{V}_{\mathrm{IH}}$ | High-Level Input Voltage | $\mathrm{V}_{\mathrm{CC}}=2.7 \mathrm{~V}$ to 3.6 V | $0.8 \mathrm{~V}_{\mathrm{CC}}$ |  |  | V |
| :--- | :--- | :--- | :--- | :--- | :---: | :---: |
| $\mathrm{V}_{\mathrm{IL}}$ | Low-Level Input Voltage | $\mathrm{V}_{\mathrm{CC}}=2.7 \mathrm{~V}$ to 3.6 V |  | $0.2 \mathrm{~V}_{\mathrm{CC}}$ | V |  |
| $\mathrm{V}_{\mathrm{OL}}$ | Low-Level Output Voltage | $\mathrm{I}_{\mathrm{OL}}=2 \mathrm{~mA}$ |  |  | 0.4 | V |
| $\mathrm{I}_{\mathrm{IH}}$ | High-Level Input Current | $\mathrm{V}_{\mathrm{IH}}=\mathrm{V}_{\mathrm{CC}}=3.6 \mathrm{~V}$ | -1.0 |  | 1.0 | $\mu \mathrm{~A}$ |
| $\mathrm{I}_{\mathrm{IL}}$ | Low-Level Input Current | $\mathrm{V}_{\mathrm{IL}}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{CC}}=3.6 \mathrm{~V}$ | -1.0 |  | 1.0 | $\mu \mathrm{~A}$ |
| $\mathrm{I}_{\mathrm{IH}}$ | OSC $_{\mathrm{IN}}$ High-Level Input Current | $\mathrm{V}_{\mathrm{IH}}=\mathrm{V}_{\mathrm{CC}}=3.6 \mathrm{~V}$ |  |  | 100 | $\mu \mathrm{~A}$ |
| $\mathrm{I}_{\mathrm{IL}}$ | OSC $_{\mathrm{IN}}$ Low-Level Input Current | $\mathrm{V}_{\mathrm{IL}}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{CC}}=3.6 \mathrm{~V}$ | -100 |  |  | $\mu \mathrm{~A}$ |

## Electrical Characteristics (Continued)

( $\mathrm{V}_{\mathrm{CC}}=\mathrm{V}_{\mathrm{P}}=3 \mathrm{~V},-30^{\circ} \mathrm{C}<\mathrm{T}_{\mathrm{A}}<85^{\circ} \mathrm{C}$ except as specified)

| Symbol | Parameter | Conditions | Value |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Typ | Max |  |
| DIGITAL INPUTS AND OUTPUTS |  |  |  |  |  |  |
| $\mathrm{t}_{\mathrm{cs}}$ | Data to Clock Setup Time |  | 50 |  |  | ns |
| $\mathrm{t}_{\mathrm{CH}}$ | Data to Clock Hold Time |  | 10 |  |  | ns |
| $\mathrm{t}_{\text {cWH }}$ | Clock Pulse Width High |  | 50 |  |  | ns |
| $\mathrm{T}_{\text {CWL }}$ | Clock Pulse Width Low |  | 50 |  |  | ns |
| $\mathrm{t}_{\text {ENSL }}$ | Clock to Load_En Setup Time |  | 50 |  |  | ns |
| $\mathrm{t}_{\text {ENW }}$ | Load_En Pulse Width |  | 50 |  |  | ns |

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Recommended Operating Conditions indicate conditions for which the device is intended to be functional, but do not guarantee specific performance limits. For guaranteed specifications and test conditions, see the Electrical Characteristics.
Note 2: This device is a high performance RF integrated circuit and is ESD sensitive. Handling and assembly of this device should be done on ESD protected workstations.
Note 3: PLL $\mathrm{V}_{\mathrm{CC}}$ represents $R F \mathrm{~V}_{\mathrm{CC}}, T x \mathrm{~V}_{\mathrm{CC}}$ and $\mathrm{Rx} \mathrm{V}_{\mathrm{CC}}$ collectively.
Note 4: Guaranteed by design. Not tested in production.
Note 5: $\mathrm{I}_{\mathrm{NOM}}=100 \mu \mathrm{~A}, 400 \mu \mathrm{~A}, 700 \mu \mathrm{~A}$ or $900 \mu \mathrm{~A}$ for RF charge pump.
Note 6: For RF charge pump, $0.5 \leq \mathrm{V}_{\mathrm{Do}_{0}} \leq \mathrm{V}_{\mathrm{P}}-0.5$; for IF charge pump, $0.5 \leq \mathrm{V}_{\mathrm{Do}_{0}} \leq \mathrm{V}_{\mathrm{CC}}-0.5$.
Note 7: For RF charge pump, $\mathrm{V}_{\mathrm{Do}}=\mathrm{V}_{\mathrm{P}} / 2$, for IF charge pump, $\mathrm{V}_{\mathrm{Do}}=\mathrm{V}_{\mathrm{CC}} / 2$.

Charge Pump Current Specification Definitions

$\mathrm{I} 1=\mathrm{CP}$ sink current at $\mathrm{V}_{\mathrm{Do}}=\mathrm{V}_{\mathrm{P}}-\Delta \mathrm{V}$
$\mathrm{I} 2=\mathrm{CP}$ sink current at $\mathrm{V}_{\mathrm{Do}}=\mathrm{V}_{\mathrm{P}} / 2$
$\mathrm{I} 3=\mathrm{CP}$ sink current at $\mathrm{V}_{\mathrm{Do}}=\Delta \mathrm{V}$
$14=C P$ source current at $V_{D o}=V_{P}-\Delta V$
$15=C P$ source current at $\mathrm{V}_{\mathrm{Do}}=\mathrm{V}_{\mathrm{P}} / 2$
$16=C P$ source current at $V_{D o}=\Delta V$
$\Delta \mathrm{V}=$ Voltage offset from positive and negative rails. Dependent on VCO tuning range relative to $\mathrm{V}_{\mathrm{CC}}$ and ground. Typical values are between 0.5 V and 1.0 V .

1. $I_{D o}$ vs $V_{D o}=$ Charge Pump Output Current magnitude variation vs Voltage $=$
$[1 / 2 *\{|11|-||3|\}] /[1 / 2 *\{| | 1|+||3|\}] * 100 \%$ and $[1 / 2 *\{| | 4|-|16|\}] /[1 / 2 *\{| | 4|+|16|\}] * 100 \%$
2. $I_{\text {Do-sink }}$ vs $I_{\text {Do-source }}=$ Charge Pump Output Current Sink vs Source Mismatch $=$ $[||2|-|15|] /[1 / 2 *\{| | 2|+|15|\}] * 100 \%$
3. $\mathrm{I}_{\mathrm{Do}}$ vs $\mathrm{T}_{\mathrm{A}}=$ Charge Pump Output Current magnitude variation vs Temperature $=$
[||2 @temp| - ||2@ $\left.25^{\circ} \mathrm{C} \mid\right] /\left|\left|2 @ 25^{\circ} \mathrm{C}\right| * 100 \%\right.$ and $\left[| | 5 @\right.$ temp| - ||5 @ $\left.25^{\circ} \mathrm{C} \mid\right] /\left|\left|5 @ 25^{\circ} \mathrm{C}\right| * 100 \%\right.$

### 1.0 Functional Description

The LMX3305 phase-lock-loop (PLL) system configuration consists of a high-stability crystal reference oscillator, three frequency synthesizers, three voltage controlled oscillators (VCO), and three passive loop filters. Each of the frequency synthesizers includes a phase detector, a current mode charge pump, as well as programmable reference [R] and feedback [ N ] frequency dividers. The VCO frequency is established by dividing the crystal reference signal down via the R-counter to obtain a comparison reference frequency. This reference signal $\left(f_{R}\right)$ is then presented to the input of a phase/frequency detector and compared with the feedback signal ( $f_{\mathrm{N}}$ ), which is obtained by dividing the VCO frequency down by way of the N -counter, and fractional circuitry. The phase/frequency detector's current source output pumps charge into the loop filter, which then converts the charge into the VCO's control voltage. The function of phase/ frequency comparator is to adjust the voltage presented to the VCO until the feedback signal frequency and phase match that of the reference signal. When the RF PLL is in a "Phase-Locked" condition, the RF VCO frequency will be ( N +F ) times that of the comparison frequency, where N is the integer divide ratio, and F is the fractional component. The fractional synthesis allows the phase detector frequency to be increased while maintaining the same frequency step size for channel selection. The divider ratio N is thereby reduced giving a lower phase noise referred to the phase detector input, and the comparison frequency is increased allowing faster switching time.

### 1.1 REFERENCE OSCILLATOR INPUTS

The reference oscillator frequency for the RF and IF PLLs are provided from the external references through the $\mathrm{OSC}_{\mathrm{IN}}$ pin. $\mathrm{OSC}_{\text {IN }}$ input can operate up to 25 MHz with input sensitivity of $0.5 \mathrm{~V}_{\mathrm{PP}}$ minimum and it drives RF, Rx and Tx R-counters. $\mathrm{OSC}_{\mathrm{IN}}$ input has a $\mathrm{V}_{\mathrm{CC}} / 2$ input threshold that can be driven from an external CMOS or TTL logic gate. Typically, the $\mathrm{OSC}_{\mathrm{IN}}$ is connected to the output of a crystal oscillator.

### 1.2 REFERENCE DIVIDERS (R-COUNTERS)

The RF, Rx and Tx R-counters are clocked through the oscillator block. The maximum frequency is 25 MHz . All RF, Rx and Tx R-counters are CMOS design. The RF R-counter is 8 -bit in length with programmable divider ratio from 2 to 255. The Rx and Tx R-counters are 10-bit in length with programmable divider ratio from 2 to 1023.

### 1.3 PRESCALERS

The LMX3305 has a 16/17/20/21 quadruple modulus prescaler for the PCS application and a 8/9/12/13 quadruple modulus prescaler for the cellular application. The Rx and Tx prescalers are dual modulus with 8/9 modulus ratio. Both RF/IF prescalers' outputs drive the subsequent CMOS flipflop chain comprising the programmable N feedback counters.

### 1.4 FEEDBACK DIVIDERS (N-COUNTERS)

The RF, Rx and Tx N-counters are clocked by the output of $R F$, Rx and Tx prescalers respectively. The RF N-counter is composed of two parts: the 15 MSB bits comprise the integer portion and the 4 LSB bits comprise the fractional portion. The RF fractional N divider is fully programmable from 80 to 32767 over the frequency range from $1200 \mathrm{MHz}-2300 \mathrm{MHz}$ for PCS application and 40 to 16383 over the frequency range from $800 \mathrm{MHz}-1400 \mathrm{MHz}$ for cellular application. The

4-bit fractional portion of the RF counter represents the fraction's numerator. The fraction's denominator base is determined by the four FRAC_D register bits.
The Rx and Tx N-counters are each a 13-bit integer divisor, fully programmable from 56 to 8,191 over the frequency range from $45 \mathrm{MHz}-600 \mathrm{MHz}$. The Rx and Tx N -counters do not include fractional compensation.

### 1.5 FRACTIONAL COMPENSATION

The fractional compensation circuitry of the LMX3305 RF divider allows the user to adjust the VCO tuning resolution in $1 / 2$ through $1 / 16$ th increments of the phase detector comparison frequency. A 4-bit denominator register (FRAC_D) selects the fractional modulo base. The integer averaging is accomplished by using a 4-bit accumulator. A variable phase delay stage compensates for the accumulated integer phase error, minimizes the charge pump duty cycle and reduces the spurious levels. This technique eliminates the need for compensation current injection into the loop filter. An overflow signal generated by the accumulator is equivalent to one full RF VCO cycle, and results in a pulse swallow.

### 1.6 PHASE/FREQUENCY DETECTORS

The RF and IF phase/frequency detectors are driven from their respective N - and R -counter outputs. The maximum frequency at the phase detector inputs is 10 MHz unless limited by the minimum continuous divide ratio of the multi-modulus prescaler. The phase detector output controls the charge pump. The polarity of the pump-up or pump-down control is programmed using RF_PD_POL, Rx_PD_POL, or Tx_PD_POL depending on whether RF or IF VC̄O characteristics are positive or negative. The phase detector also receives a feedback signal from the charge pump in order to eliminate dead zones.

### 1.7 CHARGE PUMPS

The phase detector's current source output pumps charge into an external loop filter, which then converts it into the VCO's control voltage. The charge pump steers the charge pump output $\mathrm{CP}_{\circ}$ to $\mathrm{V}_{\mathrm{cc}}$ (pump-up) or Ground (pumpdown). When locked, $\mathrm{CP}_{\mathrm{o}}$ is primarily in a TRI-STATE mode with small corrections. The IF charge pump output current magnitudes are nominally $100 \mu \mathrm{~A}$. The RF charge pump output currents can be programmed by the RF_Icpo bits at $100 \mu \mathrm{~A}, 400 \mu \mathrm{~A}, 700 \mu \mathrm{~A}$, or $900 \mu \mathrm{~A}$.

### 1.8 VOLTAGE DOUBLER ( $\mathrm{V}_{\mathrm{P}}$ )

The $\mathrm{V}_{\mathrm{P}}$ pin is normally driven from an external power supply over a range of $\mathrm{V}_{\mathrm{cc}}$ to 5.5 V to provide current for the RF charge pump circuit. An internal voltage doubler circuit connected between the $\mathrm{V}_{\mathrm{cc}}$ and $\mathrm{V}_{\mathrm{P}}$ supply pins alternately allows $\mathrm{V}_{\mathrm{CC}}=3 \mathrm{~V}( \pm 10 \%)$ users to run the RF charge pump circuit at close to twice the $\mathrm{V}_{\mathrm{Cc}}$ power supply voltage. The voltage doubler mode is enabled by setting the V2X bit to a HIGH level. The voltage doubler's charge pump driver originates from the oscillator input. The device will not totally powerdown until the V2X bit is programmed LOW. The average delivery current of the doubler is less than the instantaneous current demand of the RF charge pump when active and is thus not capable of sustaining a continuous out of lock condition. A large external capacitor connected to $\mathrm{V}_{\mathrm{P}}$ $(=0.1 \mu \mathrm{~F})$ is needed to control power supply droop when changing frequencies.

### 1.0 Functional Description (Continued)

### 1.9 MICROWIRE INTERFACE

The programmable register set is accessed through the microwire serial interface. The interface is comprised of three signal pins: Clock, Data, and LE. After the LE goes LOW, serial data is clocked into the 32-bit shift register upon the rising edge of Clock MSB first. The last three data bits shifted into the shift register select one of five addresses. When LE goes HIGH, data is transferred from the shift registers into one of the four register bank latches. Selecting the address $<000>$ presets the data in the four register banks. The synthesizer can be programmed even in the power down (or not enabled) state.

### 1.10 LOCK DETECT OUTPUTS

The open-drain Lock Detect is available in the LMX3305 to provide a digital or analog lock detect indication for the sum of the active PLLs. In the digital lock detect mode, an internal digital filter produces a logic level HIGH at the lock detect output when the error between the phase detector inputs is less than 15 ns for five consecutive comparison cycles. The lock detect output is LOW when the error between the phase detector inputs is more than 30 ns for one comparison cycle. In the analog lock detect mode, the lock detect pin becomes active low whenever any of the active PLLs are charge pumping. The Lock_Det pin can also be programmed to provide the outputs of the R, N or fastlock timeout counters.

### 1.11 POWER CONTROL

Each PLL is individually power controlled by the microwire power down bits Rx_PWDN, Tx_PWDN and RF_PWDN. Alternatively, the PLLs can also be power controlled by the Tx_En, Rx_En, and RF_En pins. The enable pins override the power down bits except for the V2X bit. When the respective PLL's enable pin is high, the power down bits determine the state of power control. Activation of any PLL power down modes result in the disabling of the respective N counter and de-biasing of its respective $f_{I N}$ input (to a high impedance state). The R counter functionality also becomes disabled when the power down bit is activated. The reference oscillator block powers down and the $\mathbf{O S C}_{\text {IN }}$ pin reverts to a high impedance state when all of the enable pins are LOW or all of the power down bits are programmed HIGH, unless V2X bit is HIGH. Power down forces the respective charge pump and phase comparator logic to a TRI-STATE condition. A power down counter reset function resets both N and R counters of the respective PLL. Upon powering up the N counter resumes counting in "close" alignment with the R counter (the maximum error is one prescaler cycle). The microwire control register remains active and capable of loading and latching in data during all of the power down modes.

## 2．0 Programming Description

2．1 MICROWIRE SERIAL BUS INTERFACE
The LMX3305 uses Clock，Data，and LE signals to accomplish all data transactions．Data is latched into the 32－bit shift register on the rising edge of Clock， LE goes HIGH．

|  | Most Significant Bit |  |  |  |  |  |  |  |  |  |  |  | SHIFT REGISTER BIT LOCATION |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Least Significant Bit |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|  | Data Field |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Address Field |  |  |
| 0 | All Register bits Preset （Upon LE latching address＜000＞） |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | 0 | 0 | 0 |
| $\underset{\sim}{\sim_{1}}$ | Tx＿R＿CNTR［9：0］ |  |  |  |  |  |  |  |  |  | $\begin{aligned} & \stackrel{\rightharpoonup}{\mathrm{o}} \\ & \mathbf{n}_{1}^{\prime} \\ & \stackrel{1}{\prime} \end{aligned}$ |  | LD［3：0］ |  |  |  | Rx＿R＿CNTR［9：0］ |  |  |  |  |  |  |  |  |  | ¢ | $\stackrel{\leftarrow}{\text { ¢ }}$ | X | 0 | 0 | 1 |
|  | $\begin{aligned} & \stackrel{\sim}{\sim} \\ & \stackrel{\sim}{\tilde{N}} \\ & \underline{\prime} \end{aligned}$ | $\begin{aligned} & \text { へ } \\ & \tilde{\sim}_{1}^{\prime} \end{aligned}$ |  |  |  |  |  |  | ® ¢ $\stackrel{1}{1}$ | $\begin{aligned} & \underline{o} \\ & \bar{\alpha} \\ & \underline{\prime} \end{aligned}$ | $\begin{aligned} & \underline{\infty} \\ & \stackrel{\infty}{\tilde{r}_{1}^{\prime}} \\ & \underline{\mu} \end{aligned}$ | $\begin{aligned} & \stackrel{\wedge}{\hat{r}_{1}^{\prime}} \\ & \underline{u^{\prime}} \end{aligned}$ | $\begin{aligned} & \underline{\varphi} \\ & \dot{r_{1}^{\prime}} \\ & \underline{\mu} \end{aligned}$ | $\begin{aligned} & \hline \stackrel{n}{\tilde{r}_{1}^{\prime}} \\ & \underline{\omega_{1}^{\prime}} \end{aligned}$ | $\begin{aligned} & \stackrel{\rightharpoonup}{\dot{c}} \\ & \underline{\mu_{1}^{\prime}} \end{aligned}$ | $\begin{aligned} & \underline{m} \\ & \stackrel{\tilde{r}}{\prime} \\ & \underline{u} \end{aligned}$ | $\begin{aligned} & \stackrel{N}{\tilde{c}} \\ & \underline{\mu_{1}} \end{aligned}$ | $\begin{aligned} & \bar{\sim} \\ & \stackrel{\rightharpoonup}{x} \end{aligned}$ | $\begin{aligned} & \text { 을 } \\ & \underline{x_{1}} \end{aligned}$ | $\begin{aligned} & \stackrel{\circ}{\stackrel{1}{\prime}} \\ & \stackrel{1}{\prime} \end{aligned}$ | $\begin{aligned} & \stackrel{\infty}{\stackrel{\infty}{\mid}} \\ & \stackrel{\mu}{\prime} \end{aligned}$ | $\begin{aligned} & \hat{x}_{1} \\ & \underline{u} \end{aligned}$ | $\begin{aligned} & \stackrel{\otimes}{\ddot{\prime}} \\ & \stackrel{1}{\prime} \end{aligned}$ | $\begin{aligned} & \stackrel{\text { ® }}{1} \\ & \stackrel{1}{1} \end{aligned}$ | $\begin{aligned} & \underset{\sim}{Z} \\ & \underline{\prime} \end{aligned}$ | $\begin{aligned} & \stackrel{\infty}{\check{~}} \\ & \stackrel{\mu}{\prime} \end{aligned}$ | $\begin{aligned} & \tilde{\sim}_{1}^{\prime} \\ & \underline{u_{n}} \end{aligned}$ | $\begin{aligned} & \bar{x}_{1}^{\prime} \\ & \underline{u_{n}} \end{aligned}$ | $\begin{aligned} & \stackrel{\circ}{{ }_{1}^{\prime}} \\ & \mathbf{u}_{1} \end{aligned}$ |  |  |  |
| $\begin{aligned} & \mathbf{z}_{1} \\ & \underline{\mathbf{I}_{1}} \end{aligned}$ | Tx＿NB＿CNTR［9：0］ |  |  |  |  |  |  |  |  |  | Tx NA CNTR［2：0］ |  |  | $\begin{aligned} & \text { z } \\ & \sum_{0}^{\prime} \\ & \text { ® }^{\prime} \end{aligned}$ | Rx＿NB＿CNTR［9：0］ |  |  |  |  |  |  |  |  |  | $\underset{\substack{\text { Rx_NA_CNTR } \\[2: 0]}}{ }$ |  |  | z | X | 0 | 1 | 0 <br>  <br>  |
|  | $\begin{aligned} & \stackrel{\sim}{\underset{\sim}{\mid}} \\ & \underline{u} \end{aligned}$ | $\underset{\underline{{\underset{N}{n}}_{\prime}^{\prime}}}{ }$ | $\underset{\sim}{\underset{\sim}{\underset{\sim}{2}}}$ | $\begin{aligned} & {\underset{\sim}{n}}_{1}^{\prime} \\ & \underline{u} \end{aligned}$ | $\underset{\sim}{\underset{\sim}{\underset{\sim}{\sim}}}$ | $\underset{\sim}{\underset{\sim}{\sim}}$ |  |  |  | $\begin{aligned} & \stackrel{\circ}{\Sigma_{1}^{\prime}} \\ & \stackrel{\mu}{\prime} \end{aligned}$ | $\begin{aligned} & \sum_{\underset{\prime}{\prime}}^{z_{1}} \end{aligned}$ | ${\underset{\sim}{\underset{\sim}{\prime}}}_{\underline{\prime}}^{\prime}$ | $\begin{aligned} & \stackrel{\varphi}{\underset{z}{\prime}} \\ & \underline{u} \end{aligned}$ | $\begin{aligned} & \sum_{\mathbf{n}}^{\boldsymbol{n}} \\ & \underline{u} \end{aligned}$ | $\underset{\underline{z_{1}^{\prime}}}{\stackrel{J}{\prime}}$ | $\begin{aligned} & \sum_{\underset{\prime}{m}}^{z_{1}} \end{aligned}$ | ${\underset{\sim}{\underset{N}{N}}}_{\underline{N}}^{\prime}$ | $\underset{\underset{\sim}{\underset{\sim}{\prime}}}{\underline{\prime}}$ | $\begin{aligned} & \stackrel{\circ}{2} \\ & \sum_{1}^{\prime} \\ & \underline{u} \end{aligned}$ | $\begin{aligned} & {\underset{\sim}{2}}_{1} \\ & \underline{u^{\prime}} \end{aligned}$ | $\begin{aligned} & {\underset{\sim}{\sim}}_{1} \\ & \underline{=} \end{aligned}$ | $\begin{aligned} & \hat{z}_{1} \\ & \underline{n^{\prime}} \end{aligned}$ |  | ${\underset{\sim}{n}}_{{\underset{u}{n}}^{n}}$ | $\begin{aligned} & \underset{z_{1}}{\prime} \\ & \underline{n_{1}} \end{aligned}$ | $\begin{aligned} & {\underset{\sim}{2}}_{1} \\ & \stackrel{1}{1} \end{aligned}$ |  | $\begin{aligned} & \bar{z}_{\mathbf{\prime}} \\ & \underline{n_{2}} \end{aligned}$ | $\begin{aligned} & {\underset{\sim}{2}}_{1} \\ & \mathbf{n}_{1} \end{aligned}$ |  |  |  |
| $\begin{aligned} & \underset{\sim}{\underset{\sim}{x}} \\ & \stackrel{\rightharpoonup}{\prime} \end{aligned}$ | RF＿R＿CNTR［7：0］ |  |  |  |  |  |  |  | FSTL＿CNTR［6：0］ |  |  |  |  |  |  | $\sum_{\substack{N \\ \hline \\ \hline}}^{N}$ | $\sum_{i}^{5}$ | $\begin{aligned} & \sum_{0}^{N} \\ & \frac{0}{5} \\ & 4 \end{aligned}$ |  | FRAC＿CAL［4：0］ |  |  |  |  | $\frac{\stackrel{\circ}{0}}{\frac{\text { O}}{1}}$ |  |  |  | $\stackrel{\times}{>}$ | 0 | 1 | 1 |
|  |  | $\begin{aligned} & \hat{\underset{\sim}{x}} \\ & \stackrel{\rightharpoonup}{\boldsymbol{c}} \end{aligned}$ |  | $\begin{aligned} & \text { N} \\ & \stackrel{\sim}{\sim} \\ & \stackrel{\rightharpoonup}{\widetilde{x}} \end{aligned}$ | $\begin{aligned} & \underset{\sim}{\check{~}} \\ & \stackrel{\rightharpoonup}{\check{x}} \end{aligned}$ | $\begin{aligned} & \stackrel{\cong}{\check{\sim}} \\ & \stackrel{\rightharpoonup}{\check{y}} \end{aligned}$ |  | $\begin{aligned} & \overline{\widetilde{\sim}} \\ & \stackrel{u_{\bar{x}}^{\prime}}{ } \end{aligned}$ |  | $\begin{aligned} & \stackrel{o}{\dot{\sim}} \\ & \frac{1}{\underset{\sim}{x}} \end{aligned}$ | $\begin{aligned} & \stackrel{\infty}{\dot{\sim}} \\ & \stackrel{\rightharpoonup}{\underset{\sim}{x}} \end{aligned}$ | $\begin{aligned} & \stackrel{N}{\tilde{x}_{1}^{\prime}} \\ & \stackrel{\rightharpoonup}{\underset{\sim}{\prime}} \end{aligned}$ |  |  |  | $\begin{aligned} & \stackrel{m}{\dot{x}} \\ & \stackrel{\rightharpoonup}{\sim} \end{aligned}$ | $\begin{aligned} & \stackrel{N}{\tilde{\sim}} \\ & \stackrel{\rightharpoonup}{\sim} \\ & \hline \end{aligned}$ |  | $\begin{aligned} & \stackrel{\circ}{\tilde{x}_{1}^{\prime}} \\ & \stackrel{\rightharpoonup}{\dot{\sim}} \end{aligned}$ | $\begin{aligned} & \stackrel{\otimes}{\underset{\sim}{\prime}} \\ & \stackrel{1}{\underset{\sim}{4}} \end{aligned}$ |  |  |  | $\begin{aligned} & \text { 先 } \\ & \stackrel{u_{1}^{\prime}}{\prime} \end{aligned}$ | $\begin{aligned} & \underset{\sim}{\square} \\ & \stackrel{\rightharpoonup}{\check{u}} \end{aligned}$ | $\begin{aligned} & \mathbb{N}_{1}^{\prime} \\ & \stackrel{\rightharpoonup}{\mathbf{u}} \end{aligned}$ |  | $\begin{aligned} & \overline{\tilde{x}_{1}^{\prime}} \\ & \stackrel{u^{\prime}}{2} \end{aligned}$ | $\begin{aligned} & \stackrel{\circ}{\underset{1}{\prime}} \\ & \stackrel{\rightharpoonup}{\underset{\sim}{2}} \end{aligned}$ |  |  |  |
| $\begin{aligned} & \mathbf{z}_{\mathbf{r}}^{\mathbf{u}} \end{aligned}$ | RF＿N＿CNTR［14：0］ |  |  |  |  |  |  |  |  |  |  |  |  |  |  | FRAC＿N［3：0］ |  |  |  | FRAC＿D［3：0］ |  |  |  | 合 | y |  | Test［2：0］ |  |  | 1 | 0 | 0 |
|  |  | $\underset{\substack{\underset{\sim}{\underset{\sim}{2}}}}{\underset{\sim}{N}}$ |  |  |  |  |  | $\underset{\substack{\underset{\sim}{x}}}{\overline{\underset{N}{\prime}}}$ |  |  | $\begin{aligned} & \sum_{\underset{\sim}{2}}^{\frac{\infty}{\sim}} \end{aligned}$ |  | $\begin{aligned} & {\underset{\sim}{2}}_{\underset{\sim}{4}}^{\substack{1}} \end{aligned}$ |  | $\begin{aligned} & \stackrel{\rightharpoonup}{\underset{\sim}{\underset{N}{\prime}}} \\ & \stackrel{\rightharpoonup}{\prime} \end{aligned}$ |  | $\begin{aligned} & \underset{\sim}{\underset{\sim}{\sim}} \\ & \stackrel{\rightharpoonup}{\mathbb{N}} \end{aligned}$ | $\begin{aligned} & \bar{z}_{\underset{1}{\prime}}^{\underset{\sim}{x}} \end{aligned}$ | $\begin{aligned} & \stackrel{\circ}{{\underset{z}{1}}_{\prime}^{\prime}} \\ & \stackrel{\rightharpoonup}{\prime} \end{aligned}$ | $\begin{aligned} & \underset{\underset{\sim}{\underset{\sim}{4}}}{\substack{1}} \end{aligned}$ |  | $\begin{aligned} & \mathbf{z}_{\mathbf{\prime}}^{\prime} \\ & \mathbf{u}_{\boldsymbol{\prime}} \end{aligned}$ | $\begin{aligned} & \underset{\sim}{\underset{\sim}{\prime}} \\ & \underset{\sim}{\prime} \end{aligned}$ |  | $\underset{\substack{\underset{\sim}{u}}}{\underset{\sim}{\prime}}$ |  | $\begin{aligned} & \underset{\underset{\sim}{\underset{\sim}{u}}}{\underset{\sim}{\prime}} \end{aligned}$ | $\begin{aligned} & {\underset{\sim}{\underset{\sim}{x}}}_{\underset{\sim}{\prime}} \end{aligned}$ | $\begin{aligned} & \underset{\underset{\sim}{\mathbf{x}}}{\substack{1}} \end{aligned}$ |  |  |  |

[^0]2.2 P REGISTER
$P$ register has the special function of programming all of the registers to a preset known set state shown below. Note that this does not prevent the other four
 These preset bit states provide the following local oscillator conditions for an OSC $_{\mathbb{N}}$ frequency of 19.68 MHz :

Fvco $=966.90 \mathrm{MHz}$ $\begin{array}{llll}\text { Tx PLL: } \operatorname{Rmod}=16 \quad \text { Nmod }=212 & \text { phase detect freq }=1.23 \mathrm{MHz} & \text { Fvco }=260.76 \mathrm{MHz} \\ \text { RF PLL: } \operatorname{Rmod}=41, \text { T.O count }=480 & \text { Nmod }=20146 / 16 \quad \text { phase detect freq }=480 \mathrm{kHz}\end{array}$
2.3 IF_R REGISTER
If the ADDRESS [2:0] field is set to 001, data is transferred from the 32 -bit shift register into the IF_R register when LE signal goes high. The IF_R register sets
counters are from 2 to 1023 .


### 2.0 Programming Description (Continued)

### 2.3.1 10-Bit IF Programming Reference Divider Ratio (Tx R Counter, Rx R Counter)

| Divide Ratio | Tx_R_CNTR [9:0] or Rx_R_CNTR [9:0] |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 |
| - | - | - | - | - | - | - | - | - | - | - |
| 1023 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Note: Divide ratio for both Tx and Rx R counters are from 2 to 1023.

### 2.3.2 Tx_PD_POL (IF_R[18])

This bit sets the polarity of the Tx phase detector. It is set to one when Tx VCO characteristics are positive. When Tx VCO frequency decreases with increasing control voltage, Tx_PD_POL should be set to zero.

### 2.3.3 Tx_RST (IF_R[17])

This bit will reset the Tx R and $N$ counters when it is set to one. For normal operation, Tx_RST should be set to zero.

### 2.3.4 LD (IF_R[16]-[13])

The LD pin is a multiplexed output. When in lock detect mode, LD does ANDing function on the active PLLs. The RF fractional test mode is only intended for factory testing.

## Lock Detect Output Truth Table

| LD [3:0] |  |  |  | LD Pin Function | Output Format |
| :---: | :---: | :---: | :---: | :--- | :---: |
| 0 | 0 | 0 | 0 | Digital Lock Detect | Open Drain |
| 0 | 0 | 0 | 1 | Analog Lock Detect | Open Drain |
| 1 | 0 | 0 | 0 | Rx R Counter | CMOS |
| 1 | 0 | 0 | 1 | Rx N Counter | CMOS |
| 1 | 0 | 1 | 0 | Tx R Counter | CMOS |
| 1 | 0 | 1 | 1 | Tx N Counter | CMOS |
| 1 | 1 | 0 | 0 | RF R Counter | CMOS |
| 1 | 1 | 0 | 1 | RF N Counter | CMOS |
| 1 | 1 | 1 | 0 | RF Fastlock Timeout Counter | CMOS |
| 1 | 1 | 1 | 1 | RF Fractional Test Mode | Analog |

## Lock Detect Digital Filter

The Lock Detect Digital Filter compares the difference between the phase of the inputs of the phase detector to a RC generated delay of approximately 15 ns . To enter the locked state (Lock Det = HIGH) the phase error must be less than the 15 ns RC delay for five consecutive reference cycles. Once in lock (Lock Det = HIGH), the RC delay is changed to approximately 30 ns. To exit the locked state (Lock Det = LOW), the phase error must become greater than the 30 ns RC delay. When the PLL is in the powerdown mode, Lock Det is forced HIGH. A flow chart of the digital filter is shown below.

### 2.0 Programming Description (Continued)



### 2.0 Programming Description (Continued)

## Typical Lock Detect Timing


2.3.5 Rx_PD_POL (IF_R[2])

This bit sets the polarity of the Rx phase detector. It is set to one when Rx VCO characteristics are positive. When Rx VCO frequency decreases with increasing control voltage, Rx_PD_POL should set to zero.
2.3.6 Rx_RST (IF_R[1])

This bit will reset the $R x R$ and $N$ counters when it is set to one. For normal operation, Rx_RST should be set to zero.
2.4 IF_N REGISTER

Note: X denotes don't care bit.

### 2.0 Programming Description (Continued)

2.4.1 3-Bit IF Swallow Counter Divide Ratio (Tx A Counter, Rx A Counter)

| Divide Ratio | Tx_NA_CNTR [2:0] or Rx_NA_CNTR [2:0] |  |  |
| :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 |
| 1 | 0 | 0 | 1 |
| $\cdot$ | $\bullet$ | $\bullet$ | $\bullet$ |
| 7 | 1 | 1 | 1 |

Divide ratio is from 0 to 7 Tx_NB_CNTR $\geq$ Tx_NA_CNTR and Rx_NB_CNTR $\geq$ Rx_NA_CNTR

### 2.4.2 10-Bit IF Programmable Counter Divide Ratio (Tx B Counter, Rx B Counter)

| Divide Ratio | Tx_NB_CNTR [9:0] or Rx_NB_CNTR [9:0] |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 3 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 |
| 4 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |
| - | - | - | - | - | - | - | - | - | - | - |
| 1023 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Divide ratio is from 3 to 1023 (Divide ratios less than 3 are prohibited)
Tx_NB_CNTR $\geq$ Tx_NA_CNTR and Rx_NB_CNTR $\geq$ Rx_NA_CNTR
$N=P B+A$
$B=N \operatorname{div} P$
$A=N \bmod P$

### 2.4.3 Tx_PWDN (IF_N[15])

This bit will asynchronously powerdown the Tx PLL when set to one. For normal operation, it should be set to zero.

### 2.4.4 Rx_PWDN (IF_N[1])

This bit will asynchronously powerdown the Rx PLL when set to one. For normal operation, it should be set to zero.
2.5 RF_R REGISTER

|  | Most Significant Bit |  |  |  |  |  |  |  |  |  |  |  | SHIFT REGISTER BIT LOCATION |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Least Significant Bit |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|  | Data Field |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | Address Field |  |  |
|  | RF_R_CNTR [7:0] |  |  |  |  |  |  |  | FSTL_CNTR [6:0] |  |  |  |  |  |  | $\sum_{\substack{\text { N }}}^{\text {N }}$ | $\sum_{i}^{\sim}$ | ¢ |  | FRAC_CAL [4:0] |  |  |  |  |  |  |  |  | $\stackrel{\times}{>}$ | 0 | 1 | 1 |
| $\stackrel{1}{x}$ |  |  |  | $\stackrel{\sim}{\sim}$ $\stackrel{1}{\sim}$ $\stackrel{1}{\sim}$ |  |  | $\begin{aligned} & \underset{\sim}{\tilde{\sim}} \\ & \stackrel{\rightharpoonup}{\Perp} \end{aligned}$ |  |  | $\begin{aligned} & \stackrel{\sigma}{\underset{\sim}{r}} \\ & \stackrel{\rightharpoonup}{\underset{\sim}{\prime}} \end{aligned}$ | $$ | $\begin{aligned} & \stackrel{N}{\dot{\sim}} \\ & \stackrel{\rightharpoonup}{\boldsymbol{x}} \end{aligned}$ |  |  | $\begin{aligned} & \stackrel{\rightharpoonup}{\underset{\sim}{x}} \\ & \stackrel{\rightharpoonup}{\underset{\sim}{x}} \end{aligned}$ | $\begin{aligned} & \frac{m}{\dot{\Gamma}} \\ & \frac{\stackrel{1}{\Perp}}{1} \end{aligned}$ | $\begin{aligned} & \stackrel{N}{\dot{\Gamma}} \\ & \frac{\stackrel{\rightharpoonup}{\sim}}{1} \end{aligned}$ |  |  |  |  | $\begin{aligned} & \widehat{c_{1}^{\prime}} \\ & \stackrel{u_{x}^{\prime}}{2} \end{aligned}$ |  |  | $\begin{aligned} & \underset{\sim}{\underset{\sim}{x}} \\ & \stackrel{\rightharpoonup}{\mathbf{u}} \end{aligned}$ |  |  | $\begin{aligned} & \bar{r}_{1}^{\prime} \\ & \stackrel{u_{x}^{\prime}}{2} \end{aligned}$ | $\begin{aligned} & \stackrel{\circ}{\underset{\sim}{\prime}} \\ & \stackrel{1}{x} \end{aligned}$ |  |  |  |

### 2.0 Programming Description (Continued)

### 2.5.1 8-Bit RF Programming Reference Divider Ratio (RF R Counter)

| Divide Ratio | RF_R_CNTR [7:0] |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| 3 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 |
| $\cdot$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| 255 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Divide ratio for RF R counter is from 2 to 255 .

### 2.5.2 FSTL_CNTR (RF_R[20]-[14])

The Fastlock Timeout Counter is a 10 bit counter wherein only the seven MSB bits are programmable. (The number of phase detector cycles the fastlock mode remains in HIGH gain is the binary FSTL_CNTR value loaded multiplied by eight.)

| Phase Detect Cycles | FSTL_CNTR [6:0] |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 24 | 0 | 0 | 0 | 0 | 0 | 1 | 1 |
| 32 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |
| $\cdot$ | $\cdot$ | $\cdot$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| 1008 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 1016 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

### 2.5.3 FSTM (RF_R[13]-[12]) and FSTSW (RF_R[11]-[10])

Fastlock enables the designer to achieve both fast frequency transitions and good phase noise performance by dynamically changing the PLL loop bandwidth. The Fastlock modes allow wide band PLL fast locking with seamless transition to a low phase noise narrow band PLL. Consistent gain and phase margins are maintained by simultaneously changing charge pump current magnitude and loop filter damping resistor. In the LMX3305, the RF fastlock can achieve substantial improvement in lock time by increasing the charge pump current by $4 \mathrm{X}, 7 \mathrm{X}$ or 9 X , which causes a $2 \mathrm{X}, 2.6 \mathrm{X}$ or 3 X increase in the loop bandwidth respectively. The damping resistors are connected to FSTSW pins.
When bit FSTM2 and/or FSTM1 is set HIGH, the RF fastlock is enabled. As a new frequency is loaded, RF_Sw2 pin and/or RF_Sw1 pin goes to a LOW state to switch in the damping resistors, the RF CP ${ }_{o}$ is set to a higher gain, and fastlock timeout counter starts counting. Once the timeout counter finishes counting, the PLL returns to its normal operation (the Icpo gain is forced to $100 \mu \mathrm{~A}$ irrespective of RF_Icpo bits).
When bit FSTM2 and/or FSTM1 is set LOW, pins RF_Sw2 and/or RF_Sw1 can be toggled HIGH or LOW to drive other devices. RF_Sw2 and/or RF_Sw1 can also be set LOW to switch in different damping resistors to change the loop filter performance. FSTSW bits control the output states of the RF_Sw2 and RF_Sw1 pins.

| RF_R[12] FSTM1 | RF_R[10] FSTSW1 | RF_Sw1 Output Function |
| :---: | :---: | :---: |
| 0 | 0 | RF_Sw1 pin reflects RF_SwBit "0" logic state |
| 0 | 1 | RF_Sw1 pin reflects RF_SwBit "1" logic state |
| 1 | x | RF_Sw1 pin LOW while T.O. counter is active |
| RF_R[13] FSTM2 | RF_R[11] FSTSW2 | RF_Sw2 Output Function |
| 0 | 0 | RF_Sw2 pin reflects RF_SwBit "0" logic state |
| 0 | 1 | RF_Sw2 pin reflects RF_SwBit "1" logic state |
| 1 | $x$ | RF_Sw2 pin LOW while T.O. counter is active |

### 2.5.4 FRAC_CAL (RF_R[9]-[5])

These five bits allow the users to optimize the fractional circuitry, therefore reducing the fractional reference spurs. The MSB bit, RF_R[9], activates the other four calibration bits RF_R[8]-[5]. These four bits can be adjusted to improve fractional spur. Improvements can be made by selecting the bits to be one greater or less than the denominator value. For example, in the 1/16 fractional mode, these four bits can be programmed to 15 or 17. In normal operation, these bits should be set to zero.

### 2.0 Programming Description (Continued)

### 2.5.5 RF_Icpo (RF_R[4]-[3])

These two bits set the charge pump gain of the RF PLL. The user is able to set the charge pump gain during the acquisition phase of the fastlock mode to $4 \mathrm{X}, 7 \mathrm{X}$ or 9 X .

| Charge Pump <br> Gain | RF_R[4] | RF_R[3] |
| :---: | :---: | :---: |
| $100 \mu \mathrm{~A}$ | 0 | 0 |
| $400 \mu \mathrm{~A}$ | 0 | 1 |
| $700 \mu \mathrm{~A}$ | 1 | 0 |
| $900 \mu \mathrm{~A}$ | 1 | 1 |

### 2.5.6 RF_PD_POL (RF_R[2])

This bit sets the polarity of the RF phase detector. It is set to one when RF VCO characteristics are positive. When RF VCO frequency decreases with increasing control voltage, RF_PD_POL should be set to zero.

### 2.5.7 RF_RST (RF_R[1])

This bit will reset the RF R and $N$ counters when it is set to one. For normal operation, RF_RST should be set to zero.

### 2.5.8 V2X (RF_R[0])

V2X when set high enables the voltage doubler for the RF charge pump supply.

### 2.0 Programming Description (Continued)



### 2.0 Programming Description (Continued)

### 2.6.1 RF_N_CNTR (RF_N[28]-[14])

The RF N counter value is determined by three counter values that work in conjunction with four prescalers. This quadruple modulus prescaler architecture allows lower minimum continuous divide ratios than are possible with a dual modulus prescaler architecture. For the determination of the A, B, and C counter values, the fundamental relationships are shown below.
$N=P C+4 B+A$
$C \geq \max \{A, B\}+2$
The $A, B$, and $C$ values can be determined as follows:
$C=N \operatorname{div} P$
$B=(N-C P) \operatorname{div} 4$
$A=(N-C P) \bmod 4$

N REGISTER FOR THE CELLULAR (8/9/12/13) PRESCALER OPERATING IN FRACTIONAL MODE

| Divide Ratio | RF_N_CNTR [14:0] |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | C Word |  |  |  |  |  |  |  |  |  |  | B Word |  | A Word |  |
| 1-23 | Divide Ratios Less than 24 are impossible since it is required that $\mathrm{C} \geq 3$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 24-39 | Some of these N values are Legal Divide Ratios, some are not |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 40 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 0 | 0 |
| 41 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 0 | 1 |
| $\ldots$ | . | . | . | . | . | . | . | . | . | . | . | 0 | . | . | . |
| 16383 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 |

N REGISTER FOR THE PCS (16/17/20/21) PRESCALER OPERATING IN FRACTIONAL MODE


### 2.6.2 FRAC_N (RF_N[13]-[10])

These four bits, the fractional accumulator modulus numerator, set the fractional numerator values in the fraction.

| Modulus Numerator | FRAC_N [3:0] |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 | 0 |
| 1 | 0 | 0 | 0 | 1 |
| 2 | 0 | 0 | 1 | 0 |
| $\cdot$ | $\bullet$ | $\bullet$ | $\cdot$ | $\bullet$ |
| 14 | 1 | 1 | 1 | 0 |
| 15 | 1 | 1 | 1 | 1 |

### 2.0 Programming Description (Continued)

### 2.6.3 FRAC_D (RF_N[9]-[6])

These four bits, the fractional accumulator modulus denominator, set the fractional denominator from $1 / 2$ to $1 / 16$ resolution.

| Modulus Denominator | FRAC_D [3:0] |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $1-8$ | Not Allowed |  |  |  |
| 9 | 1 | 0 | 0 | 1 |
| $10-14$ | $\bullet$ | $\bullet$ | $\bullet$ | $\cdot$ |
| 15 | 1 | 1 | 1 | 1 |
| 16 | 0 | 0 | 0 | 0 |

MODULUS NUMERATOR (FRAC_N) AND DENOMINATOR (FRAC_D) PROGRAMMING


Remark: The *(FRAC_N / FRAC_D) denotes that the fraction number can be represented by (FRAC_N / FRAC_D) as indicated in the parenthesis. For example, $1 / 2$ can be represented by $8 / 16$.

### 2.6.4 FBPS (RF_N[5])

This bit when set to one will bypass the delay line calculation used in the fractional circuitry. This will improve the phase noise while sacrificing performance on reference spurs. When the bit is set to zero, the delay line circuit is in effect to reduce reference spur.

### 2.6.5 PCS (RF_N[4])

This bit will determine whether the RF PLL should operate in PCS frequency range or cellular frequency range. When the bit is set to one, the RF PLL will operate in the PCS mode and when it is set to zero, the cellular mode.

### 2.6.6 RF_PWDN (RF_N[3])

This bit will asynchronously powerdown the RF PLL when set to one. For normal operation, it should be set to zero.

### 2.6.7 Test (RF_N[2]-[0])

These bits are the internal factory testing only. They should be set to zero for normal operation.

### 2.0 Programming Description (Continued)

SERIAL DATA INPUT TIMING


Notes: Parenthesis data indicates programmable reference divider data.
Data shifted into register on clock rising edge.
Data is shifted in MSB first.
Test Conditions: The Serial Data Input Timing is tested using a symmetrical waveform around $\mathrm{V}_{\mathrm{cc}} / 2$. The test waveform has an edge rate of $0.6 \mathrm{~V} / \mathrm{ns}$ with amplitudes of $1.84 \mathrm{~V} @ \mathrm{~V}_{\mathrm{cc}}=2.3 \mathrm{~V}$ and $4.4 \mathrm{~V} @ \mathrm{~V}_{\mathrm{cc}}=5.5 \mathrm{~V}$.
LMX3305 Triple Phase Locked Loop for RF Personal Communications

Physical Dimensions inches (millimeters) unless otherwise noted


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[^1]
[^0]:    Note： X denotes don＇t care bits．

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