# INTEGRATED CIRCUITS

# DATA SHEET



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# **TDA9884TS**

I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

**Product specification** 

2003 Nov 28





# $\ensuremath{\text{I}^2\text{C-bus}}$ controlled multistandard alignment-free IF-PLL for mobile reception

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### 1 FEATURES

- 5 V supply voltage
- Gain controlled wide-band Vision Intermediate Frequency (VIF) amplifier, AC-coupled
- Multistandard true synchronous demodulation with active carrier regeneration: very linear demodulation, good intermodulation figures, reduced harmonics, and excellent pulse response
- · Gated phase detector for L and L-accent standard
- Fully integrated VIF Voltage Controlled Oscillator
   WWW.DQ(VCO); alignment-free, frequencies switchable for all negative and positive modulated standards via I<sup>2</sup>C-bus
  - Digital acquisition help, VIF frequencies of 33.4, 33.9, 38.0, 38.9, 45.75, and 58.75 MHz
  - 4 MHz reference frequency input: signal from Phase-Locked Loop (PLL) tuning system or operating as crystal oscillator
  - VIF Automatic Gain Control (AGC) detector for gain control, operating as peak sync detector for negative modulated signals and as a peak white detector for positive modulated signals
  - Mobile mode for negative modulation AGC (VIF and SIF) provides very fast reaction time
  - External AGC setting via pin AGCSW; VIF-AGC and SIF-AGC monitor outputs
  - Precise fully digital Automatic Frequency Control (AFC) detector with 4-bit digital-to-analog converter, AFC bits readable via I<sup>2</sup>C-bus
  - TakeOver Point (TOP) adjustable via I<sup>2</sup>C-bus or alternatively with potentiometer
  - Fully integrated sound carrier trap for 4.5, 5.5, 6.0, and 6.5 MHz, controlled by FM-PLL oscillator

- Sound IF (SIF) input for single reference Quasi Split Sound (QSS) mode, PLL controlled
- True split sound mode for sound demodulation at low RF level
- SIF-AGC for gain controlled SIF amplifier, single reference QSS mixer able to operate in high performance single reference QSS mode and in intercarrier mode, switchable via I<sup>2</sup>C-bus
- · AM demodulator without extra reference circuit
- Alignment-free selective FM-PLL demodulator with high linearity and low noise
- Four selectable I<sup>2</sup>C-bus addresses
- I2C-bus control for all functions
- I<sup>2</sup>C-bus transceiver with pin programmable Module Address (MAD).

### 2 GENERAL DESCRIPTION

The TDA9884TS is an alignment-free multistandard (PAL, SECAM and NTSC) vision and sound IF signal PLL demodulator for positive and negative modulation, including sound AM and FM processing.

The device is specially prepared for mobile TV applications.

# 3 ORDERING INFORMATION

TYPE		PACKAGE	
NUMBER	NAME	DESCRIPTION	VERSION
TDA9884TS	SSOP24	plastic shrink small outline package; 24 leads; body width 5.3 mm	SOT340-1

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# 4 QUICK REFERENCE DATA

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V <sub>P</sub>	supply voltage	notes 1 and 2	4.5	5.0	5.5	V
l <sub>P</sub>	supply current		52	63	70	mA
Video part						
V <sub>i(VIF)(rms)</sub>	VIF input voltage sensitivity (RMS value)	-1 dB video at output	_	60	100	μV
G <sub>VIF(cr)</sub>	VIF gain control range	see Fig.9	60	66	_	dB
f <sub>VIF</sub>	vision carrier operating frequencies	see Table 16	_	33.4	_	MHz
DataSheet4U.com	1		_	33.9	_	MHz
			_	38.0	_	MHz
			_	38.9	_	MHz
			_	45.75	_	MHz
			_	58.75	_	MHz
$\Delta f_{VIF}$	VIF frequency window of digital acquisition help	related to f <sub>VIF</sub> ; see Fig.6	_	±2.3	_	MHz
$V_{o(v)(p-p)}$	video signal output voltage	see Fig.8				
	(peak-to-peak value)	normal mode	1.7	2.0	2.3	V
		trap bypass mode	0.95	1.10	1.25	V
G <sub>dif</sub>	differential gain	"CCIR 330"; note 3				
		B/G standard	_	_	5	%
		L standard	_	_	7	%
φ <sub>dif</sub>	differential phase	"CCIR 330"	_	2	4	deg
$B_{v(-1dB)}$	−1 dB video bandwidth	trap bypass mode; AC load; $C_L < 20 \text{ pF}$ ; $R_L > 1 \text{ k}\Omega$	5	6	_	MHz
$B_{v(-3dB)(trap)} \\$	-3 dB video bandwidth including	note 4				
	sound carrier trap	f <sub>trap</sub> = 4.5 MHz	3.95	4.05	_	MHz
		f <sub>trap</sub> = 5.5 MHz	4.90	5.00	_	MHz
		$f_{trap} = 6.0 \text{ MHz}$	5.40	5.50	_	MHz
		$f_{trap} = 6.5 \text{ MHz}$	5.50	5.95	_	MHz
$\alpha_{SC1}$	attenuation at first sound carrier	M/N standard	30	36	_	dB
		B/G standard	30	36	_	dB
S/N <sub>W</sub>	weighted signal-to-noise ratio	weighted in accordance with "CCIR 567"; see Fig.4; note 5	56	59	_	dB
PSRR <sub>CVBS</sub>	power supply ripple rejection at pin CVBS	f <sub>ripple</sub> = 70 Hz; video signal; grey level; positive and negative modulation; see Fig.7	20	25	_	dB
AFC <sub>stps</sub>	AFC control steepness	definition: ΔI <sub>AFC</sub> /Δf <sub>VIF</sub>	0.85	1.05	1.25	μA/kH

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Audio part					!	
V <sub>o(AF)(rms)</sub>	AF output voltage (RMS value)	27 kHz FM deviation; 50 μs de-emphasis	430	540	650	mV
THD	total harmonic distortion of audio signal	FM: 27 kHz FM deviation; 50 μs de-emphasis	_	0.15	0.50	%
		AM: m = 54 %	_	0.5	1.0	%
B <sub>AF(-3dB)</sub>	-3 dB AF bandwidth	without de-emphasis; dependent on FM-PLL filter	80	100	-	kHz
S/Nw(AF)†4U.com	weighted signal-to-noise ratio of audio signal	FM: 27 kHz FM deviation; 50 μs de-emphasis; vision carrier unmodulated	52	56	-	dB
		AM: m = 54 %	45	50	1-	dB
α <sub>AM</sub> (sup)	AM suppression of FM demodulator	50 μs de-emphasis; AM: f = 1 kHz and m = 54 %; referenced to 27 kHz FM deviation	40	46	_	dB
PSRR <sub>AUD</sub>	power supply ripple rejection on	f <sub>ripple</sub> = 70 Hz; see Fig.7				
	pin AUD	for AM	20	26	-	dB
		for FM	14	20	_	dB
V <sub>o(intc)(rms)</sub>	IF intercarrier output level	QSS mode; SC <sub>1</sub> ; SC <sub>2</sub> off	90	140	180	mV
	(RMS value)	L standard; without modulation	90	140	180	mV
		intercarrier mode; PC/SC <sub>1</sub> = 20 dB; SC <sub>2</sub> off; note 6	_	75	_	mV
Reference freq	uency					
f <sub>ref</sub>	reference signal frequency	note 7	_	4	_	MHz
V <sub>ref(rms)</sub>	reference signal voltage (RMS value)	operation as input terminal	80	-	400	mV

# Notes

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- 1. Values of video and sound parameters can be decreased at  $V_P = 4.5 \text{ V}$ .
- 2. For applications without I<sup>2</sup>C-bus, the time constant (R  $\times$  C) at the supply must be >1.2  $\mu$ s (e.g. 1  $\Omega$  and 2.2  $\mu$ F).
- 3. Condition: luminance range (5 steps) from 0 % to 100 %.
- 4. AC load:  $C_L < 20$  pF and  $R_L > 1$  k $\Omega$ . The sound carrier frequencies (depending on the TV standard) are attenuated by the integrated sound carrier traps (see Figs 15 to 20; |H(s)| is the absolute value of transfer function).
- 5.  $S/N_W$  is the ratio of the black-to-white amplitude to the black level noise voltage (RMS value measured on pin CVBS). B = 5 MHz weighted in accordance with "CCIR 567".

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6. The intercarrier output signal at pin SIOMAD can be calculated by the following formula taking into account the internal video signal with 1.1 V (p-p) as a reference:

$$V_{o(intc)(rms)} = 1.1 \times \frac{1}{2\sqrt{2}} \times 10^r \text{ V}$$

and 
$$r \,=\, \frac{1}{20} \times \left( \frac{V_{i(SC)}}{V_{i(PC)}} (dB) + 6 \; dB \pm 3 \; dB \right)$$

where:

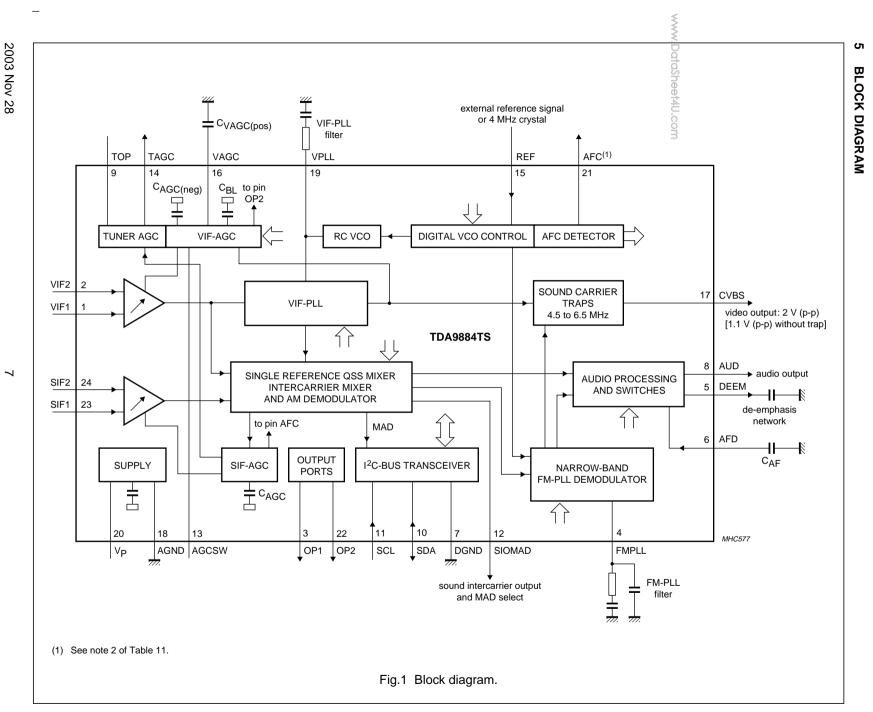
 $\frac{1}{2\sqrt{2}} \text{ is the correction term for RMS value, } \frac{V_{i(SC)}}{V_{i(PC)}} (dB) \text{ is the sound-to-picture carrier ratio at pins VIF1 and VIF2}$ 

in dB, 6 dB is the correction term of internal circuitry and ±3 dB is the tolerance of video output and intercarrier output www.Dovoring:40.c

7. Pin REF is able to operate as a 1-pin crystal oscillator input as well as an external reference signal input, e.g. from the tuning system.

# IF-PLL

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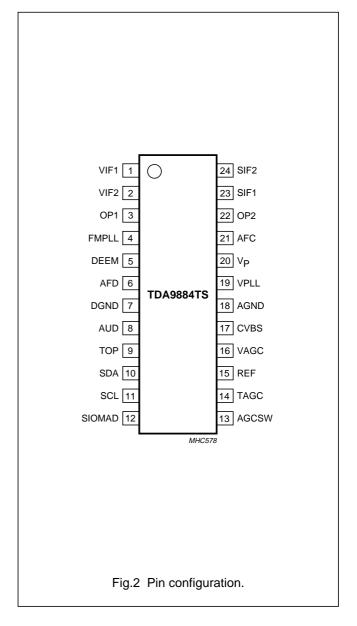


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### 6 PINNING

	SYMBOL	PIN	DESCRIPTION
	VIF1	1	VIF differential input 1
	VIF2	2	VIF differential input 2
	OP1	3	output port 1; open-collector
	FMPLL	4	FM-PLL for loop filter
	DEEM	5	de-emphasis output for capacitor
	AFD	6	AF decoupling input for capacitor
	DGND	7	digital ground
www.	മ <b>്യ</b> തിeet4l	J.c <b>g</b> m	audio output
	TOP	9	tuner AGC TakeOver Point (TOP) for resistor adjustment
	SDA	10	I <sup>2</sup> C-bus data input and output
	SCL	11	I <sup>2</sup> C-bus clock input
	SIOMAD	12	sound intercarrier output and MAD select with resistor
	AGCSW	13	fast external AGC enable switch
	TAGC	14	tuner AGC output
	REF	15	4 MHz crystal or reference signal input
	VAGC	16	VIF-AGC capacitor for L standard
	CVBS	17	composite video output
	AGND	18	analog ground
	VPLL	19	VIF-PLL for loop filter
	$V_P$	20	supply voltage
	AFC	21	AFC output
	OP2		output port 2; open-collector
	SIF1	23	SIF differential input 1 and MAD select with resistor
	SIF2	24	SIF differential input 2 and MAD select with resistor



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### 7 FUNCTIONAL DESCRIPTION

Figure 1 shows the simplified block diagram of the device which comprises the following functional blocks:

- VIF amplifier
- Tuner AGC and VIF-AGC
- VIF-AGC detector
- Frequency Phase-Locked Loop (FPLL) detector
- VCO and divider
- · AFC and digital acquisition help
- - · Sound carrier trap
  - · SIF amplifier
  - · SIF-AGC detector
  - · Single reference QSS mixer
  - · AM demodulator
  - · FM demodulator and acquisition help
  - · Audio amplifier and mute time constant
  - · Internal voltage stabilizer
  - I<sup>2</sup>C-bus transceiver and MAD (module address).

# 7.1 VIF amplifier

The VIF amplifier consists of three AC-coupled differential stages. Gain control is performed by emitter degeneration. The total gain control range is typically 66 dB. The differential input impedance is typically 2 k $\Omega$  in parallel with 3 pF.

# 7.2 Tuner AGC and VIF-AGC

This block adapts the voltages, generated at the VIF-AGC and SIF-AGC detectors, to the internal signal processing at the VIF and SIF amplifiers and performs the tuner AGC control current generation. Normally it is derived from the VIF-AGC, for the true split sound mode it is derived from the SIF-AGC. The onset of the tuner AGC control current generation can be set either via the I<sup>2</sup>C-bus (see Table 13) or optionally by a potentiometer at pin TOP (in case that the I<sup>2</sup>C-bus information cannot be stored). The presence of a potentiometer is automatically detected and the I<sup>2</sup>C-bus setting is disabled.

Furthermore, derived from the AGC detector voltage, a comparator is used to test if the corresponding VIF input voltage is higher than 200  $\mu$ V. This information can be read out via the I<sup>2</sup>C-bus (bit VIFLEV = 1).

### 7.3 VIF-AGC detector

Gain control is performed by sync level detection (negative modulation) or peak white detection (positive modulation).

For negative modulation, the sync level voltage is compared with a reference voltage (nominal sync level) by a comparator which charges or discharges the integrated AGC capacitor directly for the generation of the required VIF gain. With mobile mode the currents are increased by a factor of approximately 8 for very fast reaction. By use of an AGC event detector, the gain increase time constant (discharge current) additionally reduces in with a too-low VIF signal.

For positive modulation, the white peak level voltage is compared with a reference voltage (nominal white level) by a comparator which charges (fast) or discharges (slow) the external AGC capacitor directly for the generation of the required VIF gain. The need of a very long time constant for VIF gain increase is because the peak white level may appear only once in a field. In order to reduce this time constant, an additional level detector increases the discharging current of the AGC capacitor (fast mode) in the event of a decreasing VIF amplitude step controlled by the detected actual black level voltage. The threshold level for fast mode AGC is typically -6 dB video amplitude. The fast mode state is also transferred to the SIF-AGC detector for speed-up. In case of missing peak white pulses, the VIF gain increase is limited to typically +3 dB by comparing the detected actual black level voltage with a corresponding reference voltage.

# 7.4 FPLL detector

The VIF amplifier output signal is fed into a frequency detector and into a phase detector via a limiting amplifier for removing the video AM.

During acquisition the frequency detector produces a current proportional to the frequency difference between the VIF and the VCO signals. After frequency lock-in the phase detector produces a current proportional to the phase difference between the VIF and the VCO signals. The currents from the frequency and phase detectors are charged into the loop filter which controls the VIF VCO and locks it to the frequency and phase of the VIF carrier.

For a positive modulated VIF signal, the charging currents are gated by the composite sync in order to avoid signal distortion in case of overmodulation. The gating depth is switchable via the I<sup>2</sup>C-bus.

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### 7.5 VCO and divider

The VCO of the VIF-FPLL operates as an integrated low radiation relaxation oscillator at double the picture carrier frequency. The control voltage, required to tune the VCO to double the picture carrier frequency, is generated at the loop filter by the frequency phase detector. The possible frequency range is 50 to 140 MHz (typical value).

The oscillator frequency is divided-by-two to provide two differential square wave signals with exactly 90 degrees phase difference, independent of the frequency, for use in the FPLL detectors, the video demodulator and the intercarrier mixer.

### 7.6 AFC and digital acquisition help

Each relaxation oscillator of the VIF-PLL and FM-PLL demodulator has a wide frequency range. To prevent false locking of the PLLs and with respect to the catching range, the digital acquisition help provides an individual control, until the frequency of the VCO is within the preselected standard dependent lock-in window of the PLL.

The in-window and out-window control at the FM-PLL is additionally used to mute the audio stage (if auto mute is selected via the I<sup>2</sup>C-bus).

The working principle of the digital acquisition help is as follows. The PLL VCO output is connected to a down counter which has a predefined start value (standard dependent). The VCO frequency clocks the down counter for a fixed gate time. Thereafter, the down counter stop value is analysed. In case the stop value is higher (lower) than the expected value range, the VCO frequency is lower (higher) than the wanted lock-in window frequency range. A positive (negative) control current is injected into the PLL loop filter and consequently the VCO frequency is increased (decreased) and a new counting cycle starts.

The gate time as well as the control logic of the acquisition help circuit is dependent on the precision of the reference signal at pin REF. Operation as a crystal oscillator is possible as well as connecting this input via a serial capacitor to an external reference frequency, e.g. the tuning system oscillator.

The AFC signal is derived from the corresponding down counter stop value after a counting cycle. The last four bits are latched and can be read out via the I<sup>2</sup>C-bus (see Table 7). Also the digital-to-analog converted value is given as current at pin AFC.

### 7.7 Video demodulator and amplifier

The video demodulator is realized by a multiplier which is designed for low distortion and large bandwidth. The VIF signal is multiplied with the 'in phase' signal of the VIF-PLL VCO.

The demodulator output signal is fed into the video preamplifier via a level shift stage with integrated low-pass filter to achieve carrier harmonics attenuation.

The output signal of the preamplifier is fed to the VIF-AGC detector (see Section 7.3) and in the sound trap mode also fed internally to the integrated sound carrier trap (see Section 7.8). The differential trap output signal is converted and amplified by the following postamplifier. The video output level at pin CVBS is 2 V (p-p).

In the bypass mode the output signal of the preamplifier is fed directly through the postamplifier to pin CVBS. The output video level is 1.1 V (p-p) for using an external sound trap with 10 % overall loss.

Noise clipping is provided in both cases.

### 7.8 Sound carrier trap

The sound carrier trap consists of a reference filter, a phase detector and the sound trap itself.

A sound carrier reference signal is fed into the reference low-pass filter and is shifted by nominal 90 degrees. The phase detector compares the original reference signal with the signal shifted by the reference filter and produces a DC voltage by charging or discharging an integrated capacitor with a current proportional to the phase difference between both signals, respectively to the frequency error of the integrated filters. The DC voltage controls the frequency position of the reference filter and the sound trap. So the accurate frequency position for the different standards is set by the sound carrier reference signal.

The sound trap itself is constructed of three separate traps to realize sufficient suppression of the first and second sound carriers.

### 7.9 SIF amplifier

The SIF amplifier consists of three AC-coupled differential stages. Gain control is performed by emitter degeneration. The total gain control range is typically 66 dB. The differential input impedance is typically 2  $k\Omega$  in parallel with 3 pF.

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### 7.10 SIF-AGC detector

SIF gain control is performed by the detection of the DC component of the AM demodulator output signal. This DC signal corresponds directly to the SIF voltage at the output of the SIF amplifier so that a constant SIF signal is supplied to the AM demodulator and to the single reference QSS mixer.

By switching the gain of the input amplifier of the SIF-AGC detector via the  $I^2$ C-bus, the internal SIF level for FM sound is 5.5 dB lower than for AM sound. This is to adapt the SIF-AGC characteristic to the VIF-AGC characteristic. The adaption is ideal for a picture-to-sound FM carrier ratio of 13 dB.

Via a comparator, the integrated AGC capacitor is charged or discharged for the generation of the required SIF gain. Due to AM sound, the AGC reaction time is slow ( $f_c < 20$  Hz for the closed AGC loop). For reducing this AM sound time constant in the event of a decreasing IF amplitude step, the charging and discharging currents of the AGC capacitor are increased by a factor of 12 (fast mode) when the VIF-AGC detector (at positive modulation mode) operates in the fast mode too. An additional circuit (threshold approximately 7 dB) ensures a very fast gain reduction for a large increasing IF amplitude step.

For negative modulation and QSS mode the AGC also is set to fast mode. For negative modulation and mobile mode the currents are increased additionally by a factor of 36.

### 7.11 Single reference QSS mixer

With the present system a high performance Hi-Fi stereo sound processing can be achieved. For a simplified application without a SIF SAW filter, the single reference QSS mixer can be switched to the intercarrier mode via the I<sup>2</sup>C-bus.

The single reference QSS mixer generates the 2nd FM TV sound intercarrier signal. It is realized by a linear multiplier which multiplies the SIF amplifier output signal and the VIF-PLL VCO signal (90 degrees output) which is locked to the picture carrier. In this way the QSS mixer operates as a quadrature mixer in the intercarrier mode and provides suppression of the low frequency video signals.

In the true split sound mode the VIF-PLL VCO is locked by a synthesizer. By this the 2nd FM TV sound intercarrier signal is generated independently from the vision carrier so that in the case of a low RF level, the sound demodulation is possible where the VIF-PLL would unlock.

In the true split sound mode the VIF demodulation is not available.

The QSS mixer output signal is fed internally via a high-pass and low-pass combination to the FM demodulator as well as via an operational amplifier to the intercarrier output pin SIOMAD.

### 7.12 AM demodulator

The amplitude modulated SIF amplifier output signal is fed both to a two-stage limiting amplifier that removes the AM and to a linear multiplier. The result of the multiplication of the SIF signal with the limiter output signal is AM demodulation (passive synchronous demodulator). The demodulator output signal is fed via a low-pass filter that attenuates the carrier harmonics and via the input amplifier of the SIF-AGC detector to the audio amplifier.

### 7.13 FM demodulator and acquisition help

The narrow-band FM-PLL detector consists of:

- Gain controlled FM amplifier and AGC detector
- Narrow-band PLL.

The intercarrier signal from the intercarrier mixer is fed to the input of an AC-coupled gain controlled amplifier with two stages. The gain controlled output signal is fed to the phase detector of the narrow-band FM-PLL (FM demodulator). For good selectivity and robustness against disturbance caused by the video signal, a high linearity of the gain controlled FM amplifier and of the phase detector as well as a constant signal level are required. The gain control is done by means of an 'in phase' demodulator for the FM carrier (from the output of the FM amplifier). The demodulation output is fed into a comparator for charging or discharging the integrated AGC capacitor. This leads to a mean value AGC loop to control the gain of the FM amplifier.

The FM demodulator is realized as a narrow-band PLL with an external loop filter, which provides the necessary selectivity (bandwidth approximately 100 kHz). To achieve good selectivity, a linear phase detector and a constant input level are required. The gain controlled intercarrier signal from the FM amplifier is fed to the phase detector. The phase detector controls via the loop filter the integrated low radiation relaxation oscillator. The designed frequency range is from 4 to 7 MHz.

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The VCO within the FM-PLL is phase-locked to the incoming 2nd SIF signal, which is frequency modulated. As well as this, the VCO control voltage is superimposed by the AF voltage. Therefore, the VCO tracks with the FM of the 2nd SIF signal. So, the AF voltage is present at the loop filter and is typically 5 mV (RMS) for 27 kHz FM deviation. This AF signal is fed via a buffer to the audio amplifier.

The correct locking of the PLL is supported by the digital acquisition help circuit (see Section 7.6).

# www.7.14.ShAudio amplifier and mute time constant

The audio amplifier consists of two parts:

- · AF preamplifier
- · AF output amplifier.

The AF preamplifier used for FM sound is an operational amplifier with internal feedback, high gain and high common mode rejection. The AF voltage from the PLL demodulator is 5 mV (RMS) for a frequency deviation of 27 kHz and is amplified by 30 dB. By the use of a DC operating point control circuit (with external capacitor  $C_{AF}$ ), the AF preamplifier is decoupled from the PLL DC voltage. The low-pass characteristic of the amplifier reduces the harmonics of the sound intercarrier signal at the AF output terminal.

For FM sound a switchable de-emphasis network (with external capacitor) is implemented between the preamplifier and the output amplifier.

The AF output amplifier provides the required AF output level by a rail-to-rail output stage. A preceding stage makes use of an input selector for switching between FM sound, AM sound and mute state. The gain can be switched between 10 dB (normal) and 4 dB (reduced).

Switching to the mute state is controlled automatically, dependent on the digital acquisition help in case the VCO of the FM-PLL is not in the required frequency window. This is done by a time constant: fast for switching to the mute state and slow (typically 40 ms) for switching to the no-mute state.

All switching functions are controlled via the I<sup>2</sup>C-bus:

- · AM sound, FM sound and forced mute
- · Auto mute enable or disable
- De-emphasis off or on with 50 or 75  $\mu s$
- · Audio gain normal or reduced.

# 7.15 Internal voltage stabilizer

The band gap circuit internally generates a voltage of approximately 2.4 V, independent of supply voltage and temperature. A voltage regulator circuit, connected to this voltage, produces a constant voltage of 3.55 V which is used as an internal reference voltage.

### 7.16 I<sup>2</sup>C-bus transceiver and module address

The device can be controlled via the 2-wire I<sup>2</sup>C-bus by a microcontroller. Two wires carry serial data (SDA) and serial clock (SCL) information between the devices connected to the I<sup>2</sup>C-bus.

The device has an I<sup>2</sup>C-bus slave transceiver with auto-increment. The circuit operates up to clock frequencies of 400 kHz.

A slave address is sent from the master to the slave receiver. To avoid conflicts in a real application with other devices providing similar or complementing functions, there are four possible slave addresses available. These Module Addresses (MADs) can be selected by connecting resistors on pin SIOMAD and/or pins SIF1 and SIF2 (see Fig.21). Pin SIOMAD relates with bit A0 and pins SIF1 and SIF2 relate with bit A3. The slave addresses of this device are given in Table 1.

The power-on preset value is dependent on the use of pin SIOMAD and can be chosen for 45.75 MHz NTSC as default (pin SIOMAD left open-circuit) or 58.75 MHz NTSC (resistor on pin SIOMAD). In this way the device can be used without the I<sup>2</sup>C-bus as an NTSC only device.

**Remark:** In case of using the device without the  $I^2C$ -bus, then the rise time of the supply voltage after switching on power must be longer than 1.2  $\mu$ s.

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Table 1 Slave address detection

SLAVE ADDRESS	SELECTABLE	ADDRESS BIT	RESISTOR ON PIN			
SLAVE ADDRESS	А3	A3 A0		SIOMAD		
MAD1	0	1	no	no		
MAD2	0	0	no	yes		
MAD3	1	1	yes	no		
MAD4	1	0	yes	yes		

### 8 I2C-BUS CONTROL

# 8.1 Read format

Table 2 I<sup>2</sup>C-bus read format (slave transmits data)

S		BYTE 1							Α				BYT	TE 2				AN	Р
	A6	A5	A4	А3	A2	A1	A0	R/W		D7	D6	D5	D4	D3	D2	D1	D0		
		slave address					1					da	ıta						

Table 3 Explanation of Table 2

SYMBOL FUNCTION				
S	START condition, generated by the master			
Slave address see Table 4				
$R/\overline{W} = 1$ read command, generated by the master				
Α	acknowledge bit, generated by the slave			
Data	8-bit data word, transmitted by the slave (see Table 5)			
AN acknowledge-not bit, generated by the master				
P STOP condition, generated by the master				

The master generates an acknowledge when it has received the dataword READ. The master next generates an acknowledge, then slave begins transmitting the dataword READ, and so on until the master generates an acknowledge-not bit and transmits a STOP condition.

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### 8.1.1 SLAVE ADDRESS

The first module address MAD1 is the standard address (see Table 1).

Table 4 Slave addresses; notes 1 and 2

SLAVE A	DDRESS	BIT								
NAME	VALUE (HEX)	A6	A5	A4	А3	A2	<b>A</b> 1	Α0		
MAD1	43	1	0	0	0	0	1	1		
MAD2	42	1	0	0	0	0	1	0		
MARReet4U.co	om 4B	1	0	0	1	0	1	1		
MAD4	4A	1	0	0	1	0	1	0		

### **Notes**

WWW

- 1. For MAD activation via external resistor: see Table 1 and Fig.21.
- 2. For applications without I<sup>2</sup>C-bus: see Tables 18 and 19.

### 8.1.2 DATA BYTE

Table 5 Data read register (status register)

MSB							LSB
D7	D6	D5	D4	D3	D2	D1	D0
AFCWIN	VIFLEV	CARRDET	AFC4	AFC3	AFC2	AFC1	PONR

Table 6 Description of status register bits

BIT	VALUE	DESCRIPTION
AFCWIN		AFC window
	1	VCO in ±1.6 MHz AFC window; note 1
	0	VCO out of ±1.6 MHz AFC window
VIFLEV		VIF input level
	1	high level; VIF input voltage ≥200 μV (typically)
	0	low level
CARRDET		FM carrier detection
	1	detection
	0	no detection
AFC[4:1]		Automatic frequency control
		see Table 7
PONR		Power-on reset
	1	after Power-on reset or after supply breakdown
	0	after a successful reading of the status register

### Note

1. If no IF input is applied, then bit AFCWIN = 1 due to the fact that the VCO is forced to the AFC window border for fast lock-in behaviour.

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Table 7 Automatic frequency control bits; note 1

		В	IT		
	AFC4	AFC3	AFC2	AFC1	f <sub>VIF</sub>
	0	1	1	1	≤ (f <sub>0</sub> − 187.5 kHz)
	0	1	1	0	f <sub>0</sub> – 162.5 kHz
	0	1	0	1	f <sub>0</sub> – 137.5 kHz
	0	1	0	0	f <sub>0</sub> – 112.5 kHz
	0	0	1	1	f <sub>0</sub> – 87.5 kHz
	0	0	1	0	f <sub>0</sub> – 62.5 kHz
www.	DataSheet4U.c	om o	0	1	f <sub>0</sub> – 37.5 kHz
	0	0	0	0	f <sub>0</sub> – 12.5 kHz
	1	1	1	1	f <sub>0</sub> + 12.5 kHz
	1	1	1	0	f <sub>0</sub> + 37.5 kHz
	1	1	0	1	f <sub>0</sub> + 62.5 kHz
	1	1	0	0	f <sub>0</sub> + 87.5 kHz
	1	0	1	1	f <sub>0</sub> + 112.5 kHz
	1	0	1	0	f <sub>0</sub> + 137.5 kHz
Ī	1	0	0	1	f <sub>0</sub> + 162.5 kHz
	1	0	0	0	≥ (f <sub>0</sub> + 187.5 kHz)

### Note

1.  $f_0$  is the nominal frequency of  $f_{VIF}$ .

### 8.2 Write format

Table 8 I<sup>2</sup>C-bus write format (slave receives data); note 1

S	BYTE 1 A		Α	BYTE 2	Α	BYTE 3	Α	BYTE n	Α	Р
	A6 to A0	R/W		A7 to A0		bits 7 to 0		bits 7 to 0		
	slave address	0		subaddress		data 1		data n		

# Note

1. The auto-increment of the subaddress stops if the subaddress is 3.

Table 9 Explanation of Table 8

SYMBOL	FUNCTION
S	START condition, generated by the master
Slave address	see Table 4
$R/\overline{W} = 0$	write command, generated by the master
Α	acknowledge bit, generated by the slave
Subaddress (SAD)	see Table 10
Data 1, data n	8-bit data words, transmitted by the master (see Tables 11, 12 and 14)
Р	STOP condition

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### 8.2.1 SUBADDRESS

If more than one data byte is transmitted, then auto-increment is performed: starting from the transmitted subaddress and auto-increment of subaddress in accordance with the order of Table 10.

Table 10 Definition of the subaddress (second byte after slave address); note 1

	REGISTER	MSB							
	REGISTER	<b>A7</b> <sup>(2)</sup>	<b>A6</b> <sup>(3)</sup>	<b>A5</b> <sup>(3)</sup>	<b>A4</b> <sup>(3)</sup>	<b>A3</b> <sup>(3)</sup>	<b>A2</b> <sup>(3)</sup>	A1	A0
	SAD for switching mode	0	Х	Х	Х	Х	Х	0	0
	SAD for adjust mode	0	Х	Х	Х	Х	Х	0	1
www.	SAD for data mode	0	Х	Х	Х	Х	Х	1	0

### **Notes**

- 1. X = don't care.
- 2. Bit A7 = 1 is not allowed.
- 3. Bits A6 to A2 will be ignored by the internal hardware.

# 8.2.2 DATA BYTE FOR SWITCHING MODE

**Table 11** Bit description of SAD register for switching mode (SAD = 00)

BIT	VALUE	DESCRIPTION
B7		Output port 2 e.g. for SAW switching or AGC monitoring
	1	high-impedance, disabled or HIGH
	0	low-impedance, active or LOW
B6		Output port 1 e.g. for SAW switching or external AGC input
	1	high-impedance, disabled or HIGH
	0	low-impedance, active or LOW
B5		Forced audio mute
	1	on
	0	off
B4 and B3		TV standard modulation and mobile mode
	00	positive AM TV; note 1
	01	positive AM TV; notes 1 and 2
	10	negative FM TV
	11	negative TV mobile mode; notes 2 and 3
B2		Carrier mode
	1	QSS mode
	0	intercarrier mode
B1		Auto mute of FM AF output
	1	active
	0	inactive

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BIT	VALUE	DESCRIPTION					
B0		Video mode (sound trap)					
	1	sound trap bypass					
	0	sound trap active					

### **Notes**

- 1. For positive AM TV choose 6.5 MHz for the second SIF.
- 2. SIF-AGC monitor output at pin AFC.
- 3. AGC (VIF/SIF) provides very fast reaction time.

WWW.8.213SheeDATA BYTE FOR ADJUST MODE

Table 12 Bit description of SAD register for adjust mode (SAD = 01)

BIT	VALUE	DESCRIPTION
C7		Audio gain
	1	−6 dB
	0	0 dB
C6		De-emphasis time constant
	1	50 μs
	0	75 μs
C5		De-emphasis
	1	on
	0	off
C4 to C0		Tuner takeover point adjustment
		see Table 13

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Table 13 Tuner takeover point adjustment bits

		TOP ADJUSTMENT (dB)					
C4	C3	C2	C1	C0	TOP ADJUSTIMENT (UB)		
1	1	1	1	1	+15		
1	1	1	1	0	+14		
1	1	1	0	1	+13		
1	1	1	0	0	+12		
1	1	0	1	1	+11		
1	1	0	1	0	+10		
w.DataShqet4U.com	<sup>1</sup> 1	0	0	1	+9		
1	1	0	0	0	+8		
1	0	1	1	1	+7		
1	0	1	1	0	+6		
1	0	1	0	1	+5		
1	0	1	0	0	+4		
1	0	0	1	1	+3		
1	0	0	1	0	+2		
1	0	0	0	1	+1		
1	0	0	0	0	0 <sup>(1)</sup>		
0	1	1	1	1	-1		
0	1	1	1	0	-2		
0	1	1	0	1	-3		
0	1	1	0	0	-4		
0	1	0	1	1	<b>-</b> 5		
0	1	0	1	0	-6		
0	1	0	0	1	<b>–7</b>		
0	1	0	0	0	-8		
0	0	1	1	1	<b>–9</b>		
0	0	1	1	0	-10		
0	0	1	0	1	<b>–11</b>		
0	0	1	0	0	-12		
0	0	0	1	1	-13		
0	0	0	1	0	-14		
0	0	0	0	1	<b>–15</b>		
0	0	0	0	0	-16		

### Note

1. 0 dB is equal to 17 mV (RMS).

# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

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# 8.2.4 DATA BYTE FOR DATA MODE

Table 14 Bit description of SAD register for data mode (SAD = 10)

	BIT	VALUE	DESCRIPTION
	E7		VIF-AGC features
			dependent on bit E5; see Table 15
	E6		L standard PLL gating
		1	gating in case of 36 % positive modulation (B4 = 0)
		0	gating in case of 0 % positive modulation (B4 = 0)
		1	optimum for multipath condition (B4 = 1)
WWW.	DataSheet4U.com	0	optimum for overmodulation condition (B4 = 1)
	E5		VIF, SIF and tuner minimum gain
			dependent on bit E7; see Table 15
	E4 to E2		Vision intermediate frequency selection
			see Tables 16 and 17
	E1 and E0		Sound intercarrier frequency selection (sound 2nd IF); only valid for setting of E4 to E2 according to Table 16
		00	f <sub>FM</sub> = 4.5 MHz
		01	f <sub>FM</sub> = 5.5 MHz
		10	f <sub>FM</sub> = 6.0 MHz
		11	f <sub>FM</sub> = 6.5 MHz (for positive modulation choose 6.5 MHz)

# Table 15 Options

FUNCTION	BIT E	E7 = 0	BIT E7 = 1			
FUNCTION	BIT E5 = 0	BIT E5 = 1	BIT E5 = 0	BIT E5 = 1		
Pin OP1	port function	port function	port function	VIF-AGC external input <sup>(1)</sup>		
Pin OP2	port function	port function	VIF-AGC output <sup>(1)</sup>	VIF-AGC output <sup>(1)</sup>		
Gain	normal gain	minimum gain	normal gain	external gain		

### Note

1. The corresponding port function has to be disabled (set to 'high-impedance'); see Table 11 and Chapter 11, Table of Characteristics, notes 12 and 14.

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Table 16 TV standard selection for VIF

,	VIDEO IF SELECT BITS	f (MILITA	
E4	E3	E2	f <sub>VIF</sub> (MHz)
0	0	0	58.75 <sup>(1)</sup>
0	0	1	45.75 <sup>(1)</sup>
0	1	0	38.9
0	1	1	38.0
1	0	0	33.9
1	0	1	33.4

www.DataShe

# Note

1. Pin SIOMAD can be used for the selection of the different NTSC standards without  $I^2$ C-bus. With a resistor on pin SIOMAD,  $f_{VIF} = 58.75$  MHz; without a resistor on pin SIOMAD,  $f_{VIF} = 45.75$  MHz (NTSC-M).

Table 17 True split sound mode

			BIT	FUNCTION			
TV STANDARD	E4	E3	E2	E1	E0	f <sub>synth</sub> (MHz)	SOUND 2nd IF f <sub>FM</sub> (MHz)
M/N	1	1	1	0	1	40	5.6
B/G	1	1	1	1	1	40	6.6
I	1	1	0	0	0	36	3.1
D/K	1	1	0	1	0	36	3.6

Table 18 Data setting after power-on reset (default setting with a resistor on pin SIOMAD)

DECISTED	MSB								
REGISTER	D7	D6	D5	D4	D3	D2	D1	D0	
Switching mode	1	1	0	1	0	1	1	0	
Adjust mode	0	0	1	1	0	0	0	0	
Data mode	0	0	0	0	0	0	0	0	

Table 19 Data setting after power-on reset (default setting without a resistor on pin SIOMAD)

REGISTER	MSB							LSB
	D7	D6	D5	D4	D3	D2	D1	D0
Switching mode	1	1	0	1	0	1	1	0
Adjust mode	0	0	1	1	0	0	0	0
Data mode	0	0	0	0	0	1	0	0

For selection of the different NTSC standards without  $I^2$ C-bus, an application on pin SIOMAD is used (see Fig.21). Without a resistor, NTSC-M is selected ( $f_{VIF} = 45.75$  MHz); with a resistor, the VIF frequency is 58.75 MHz (see Table 16).

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### 9 LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 60134).

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V <sub>P</sub>	supply voltage		_	5.5	V
V <sub>n</sub>	voltage on				
	pins VIF1, VIF2, OP1, FMPLL, AGCSW, $V_P$ , AFC, OP2, SIF1 and SIF2		0	V <sub>P</sub>	V
	pin TAGC		0	8.8	v
t <sub>sc</sub>	short-circuit time to ground or V <sub>P</sub>		_	10	s
T Dotgisheet4	storage temperature		-25	+150	°C
T <sub>amb</sub>	ambient temperature		-20	+70	°C
V <sub>es</sub>	electrostatic discharge voltage on all pins	note 1	-400	+400	V
		note 2	-4000	+4000	V

### **Notes**

WWW

- 1. Machine model in accordance with SNW-FQ-302B: class C, discharging a 200 pF capacitor via a 0.75  $\mu$ H series inductance.
- 2. Human body model in accordance with SNW-FQ-302A: class 3, discharging a 100 pF capacitor via a 1.5 k $\Omega$  series resistor.

# 10 THERMAL CHARACTERISTICS

SYMBOL	PARAMETER	CONDITIONS	VALUE	UNIT
R <sub>th(j-a)</sub>	thermal resistance from junction to ambient	in free air	118	K/W

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### 11 CHARACTERISTICS

 $V_P = 5$  V;  $T_{amb} = 25$  °C; see Table 21 for input frequencies; B/G standard is used for the specification ( $f_{PC} = 38.9$  MHz;  $f_{SC} = 33.4$  MHz; PC/SC = 13 dB;  $f_{mod} = 400$  Hz); input level  $V_{i(VIF)} = 10$  mV (RMS) (sync level for B/G; peak white level for L); IF input from 50  $\Omega$  via broadband transformer 1 : 1; video modulation DSB; residual carrier for B/G is 10 % and for L is 3 %; video signal in accordance with "CCIR line 17 and line 330" or "NTC-7 Composite"; measurements taken in test circuit of Fig.21; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNI
Supply (pin V <sub>P</sub> )			•	•	•	•
V <sub>P</sub>	supply voltage	note 1	4.5	5.0	5.5	V
I <sub>P</sub>	supply current		52	63	70	mA
P <sub>tot</sub>	total power dissipation		_	305	385	mW
Power-on rese	Т		•	•	•	
V <sub>P(start)</sub>	supply voltage for start of reset	decreasing supply voltage	2.5	3.0	3.5	V
V <sub>P(stop)</sub>	supply voltage for end of reset	increasing supply voltage; I <sup>2</sup> C-bus transmission enable	_	_	4.4	V
τρ	time constant (R $\times$ C) for network at pin V <sub>P</sub>	for applications without I <sup>2</sup> C-bus	1.2	_	_	μs
VIF amplifier (p	ins VIF1 and VIF2)					
V <sub>i(VIF)(rms)</sub>	VIF input voltage sensitivity (RMS value)	-1 dB video at output	_	60	100	μV
V <sub>i(max)(rms)</sub>	maximum input voltage (RMS value)	+1 dB video at output	150	190	_	mV
V <sub>i(ovI)(rms)</sub>	overload input voltage (RMS value)	note 2	_	-	440	mV
$\Delta V_{IF(int)}$	internal IF amplitude difference between picture and sound carrier	within AGC range; Δf = 5.5 MHz	_	0.7	-	dB
G <sub>VIF(cr)</sub>	VIF gain control range	see Fig.9	60	66	_	dB
B <sub>VIF(-3dB)(II)</sub>	lower limit –3 dB VIF bandwidth		_	15	Ī-	MHz
B <sub>VIF(-3dB)(ul)</sub>	upper limit -3 dB VIF bandwidth		_	80	1-	MHz
R <sub>i(dif)</sub>	differential input resistance	note 3	_	2	_	kΩ
C <sub>i(dif)</sub>	differential input capacitance	note 3	_	3	_	pF
VI	DC input voltage		_	1.93	_	V
FPLL and true	synchronous video demodulator;	note 4	•	•		•
f <sub>VCO(max)</sub>	maximum oscillator frequency for carrier regeneration	f = 2f <sub>PC</sub>	120	140	_	MHz
f <sub>VIF</sub>	vision carrier operating	see Table 16	_	33.4	_	MHz
	frequencies		_	33.9	_	MHz
			_	38.0	_	MHz
			_	38.9	_	MHz
			_	45.75	_	MHz
			_	58.75	-	MHz

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$\Delta f_{VIF}$	VIF frequency window of digital acquisition help	related to f <sub>VIF</sub> ; see Fig.6	_	±2.3	-	MHz
t <sub>acq</sub>	acquisition time	BL = 70 kHz; note 5	_	_	30	ms
Vi(lock)(rms)	input voltage sensitivity for PLL to be locked (RMS value)	measured on pins VIF1 and VIF2; maximum IF gain	_	30	70	μV
T <sub>cy(DAH)</sub>	cycle time of digital acquisition help		_	64	_	μs
K <sub>O(VIF)</sub>	VIF VCO steepness	definition: $\Delta f_{VIF}/\Delta V_{VPLL}$	_	20	_	MHz/\
Parasneer4u.com K <sub>D(VIF)</sub>	VIF phase detector steepness	definition: $\Delta I_{VPLL}/\Delta \phi_{VIF}$	_	23	_	μA/rad
Video output 2	V (pin CVBS)			•	•	•
NORMAL MODE (S	SOUND CARRIER TRAP ACTIVE) AND SO	OUND CARRIER ON				
$V_{o(v)(p-p)}$	video output voltage (peak-to-peak value)	see Fig.8	1.7	2.0	2.3	V
$\Delta V_{o}$	video output voltage difference	difference between L and B/G standard	-12	_	+12	%
V/S	ratio between video (black-to-white) and sync level		1.90	2.33	3.00	_
V <sub>sync</sub>	sync voltage level		1.0	1.2	1.4	V
$V_{\text{clip}(u)}$	upper video clipping voltage level		V <sub>P</sub> – 1.1	V <sub>P</sub> – 1	_	V
V <sub>clip(l)</sub>	lower video clipping voltage level		_	0.7	0.9	V
R <sub>o</sub>	output resistance	note 3	_	_	30	Ω
I <sub>bias(int)</sub>	internal DC bias current for emitter-follower		1.5	2.0	_	mA
I <sub>o(sink)(max)</sub>	maximum AC and DC output sink current		1	_	_	mA
I <sub>o(source)(max)</sub>	maximum AC and DC output source current		3.9	_	_	mA
$\Delta V_{o(CVBS)}$	deviation of CVBS output	50 dB gain control	_	_	0.5	dB
	voltage	30 dB gain control	_	_	0.1	dB
$\Delta V_{o(bl)}$	black level tilt	negative modulation	_	_	1	%
$\Delta V_{o(bl)(v)}$	vertical black level tilt for worst case in L standard	vision carrier modulated by test line (VITS) only	_	_	3	%
G <sub>dif</sub>	differential gain	"CCIR 330"; note 6				
		B/G standard	_	_	5	%
		L standard	_	_	7	%
Φdif	differential phase	"CCIR 330"	_	2	4	deg
S/N <sub>W</sub>	weighted signal-to-noise ratio	weighted in accordance with "CCIR 567"; see Fig.4; note 7	56	59	_	dB

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UN
S/N <sub>UW</sub>	unweighted signal-to-noise ratio	note 7	47	51	_	dB
α <sub>IM(blue)</sub>	intermodulation attenuation at	see Fig.5; note 8				
	'blue'	f = 1.1 MHz	58	64	_	dB
		f = 3.3 MHz	58	64	_	dB
α <sub>IM(yellow)</sub>	intermodulation attenuation at	see Fig.5; note 8				
	'yellow'	f = 1.1 MHz	60	66	_	dB
		f = 3.3 MHz	59	65	_	dB
$\Delta V_{r(PC)(rms)}$	residual picture carrier (RMS value)	fundamental wave and harmonics	_	2	5	mV
$\Delta f_{unw(p-p)}$	robustness for unwanted frequency deviation of picture carrier (peak-to-peak value)	3 % residual carrier; 50 % serration pulses; L standard; note 3	_	_	12	kHz
Δφ	robustness for modulator imbalance	0 % residual carrier; 50 % serration pulses; L standard; L-gating = 0 %; note 3	_	_	3	%
$\alpha_{H}$	suppression of video signal harmonics	$C_L < 20 \text{ pF}; R_L > 1 \text{ k}\Omega;$ AC load; note 9a	35	40	_	dB
$\alpha_{\text{spur}}$	suppression of spurious elements	note 9b	40	_	_	dB
PSRR <sub>CVBS</sub>	power supply ripple rejection at pin CVBS	f <sub>ripple</sub> = 70 Hz; video signal; grey level; positive and negative modulation; see Fig.7	20	25	_	dB
M/N STANDARD INC	CLUDING KOREA; see Fig.15		•	•		•
B <sub>v(-3dB)(trap)</sub>	-3 dB video bandwidth including sound carrier trap	$f_{trap} = 4.5 \text{ MHz}; \text{ note } 10$	3.95	4.05	_	MHz
α <sub>SC1</sub>	attenuation at first sound carrier	f = 4.5 MHz	30	36	_	dB
α <sub>SC1(60kHz)</sub>	attenuation at first sound carrier $f_{SC1} \pm 60 \text{ kHz}$	f = 4.5 MHz	21	27	_	dB
α <sub>SC2</sub>	attenuation at second sound carrier	f = 4.724 MHz	21	27	_	dB
αSC2(60kHz)	attenuation at second sound carrier $f_{SC2} \pm 60 \text{ kHz}$	f = 4.724 MHz	15	21	_	dB
$t_{d(g)(cc)}$	group delay at colour carrier frequency	f = 3.58 MHz; see Fig.16	110	180	250	ns
B/G STANDARD; SE	ee Fig.17					
B <sub>v(-3dB)(trap)</sub>	-3 dB video bandwidth including sound carrier trap	$f_{trap} = 5.5 \text{ MHz}; \text{ note } 10$	4.90	5.00	_	MHz
$\alpha_{SC1}$	attenuation at first sound carrier	f = 5.5 MHz	30	36	Ī-	dB
α <sub>SC1(60kHz)</sub>	attenuation at first sound carrier $f_{SC1} \pm 60 \text{ kHz}$	f = 5.5 MHz	24	30	_	dB
α <sub>SC2</sub>	attenuation at second sound carrier	f = 5.742 MHz	21	27	_	dB

# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNI
α <sub>SC2(60kHz)</sub>	attenuation at second sound carrier f <sub>SC2</sub> ± 60 kHz	f = 5.742 MHz	15	21	_	dB
t <sub>d(g)(cc)</sub>	group delay at colour carrier frequency	f = 4.43 MHz; see Fig.18	110	180	250	ns
I STANDARD; see			1			1
B <sub>v(-3dB)(trap)</sub>	-3 dB video bandwidth including sound carrier trap	$f_{trap} = 6.0 \text{ MHz}; \text{ note } 10$	5.40	5.50	-	MHz
α <sub>SC1</sub>	attenuation at first sound carrier	f = 6.0 MHz	26	32	_	dB
CASC1(60kHz)U.com	attenuation at first sound carrier $f_{SC1} \pm 60 \text{ kHz}$	f = 6.0 MHz	20	26	_	dB
$\alpha_{SC2}$	attenuation at second sound carrier	f = 6.55 MHz	12	18	-	dB
α <sub>SC2</sub> (60kHz)	attenuation at second sound carrier f <sub>SC2</sub> ± 60 kHz	f = 6.55 MHz	10	15	-	dB
$t_{d(g)(cc)}$	group delay at colour carrier frequency	f = 4.43 MHz	_	90	160	ns
D/K STANDARD; S	ee Fig.20				•	-!
B <sub>v(-3dB)(trap)</sub>	-3 dB video bandwidth including sound carrier trap	$f_{trap} = 6.5 \text{ MHz}; \text{ note } 10$	5.50	5.95	-	MHz
$\alpha_{SC1}$	attenuation at first sound carrier	f = 6.5 MHz	26	32	_	dB
α <sub>SC1(60kHz)</sub>	attenuation at first sound carrier $f_{SC1} \pm 60 \text{ kHz}$	f = 6.5 MHz	20	26	_	dB
$\alpha_{SC2}$	attenuation at second sound carrier	f = 6.742 MHz	18	24	_	dB
α <sub>SC2</sub> (60kHz)	attenuation at second sound carrier f <sub>SC2</sub> ± 60 kHz	f = 6.742 MHz	13	18	_	dB
t <sub>d(g)(cc)</sub>	group delay at colour carrier frequency	f = 4.28 MHz	_	60	130	ns
Video output 1.	1 V (pin CVBS)		•	•	•	
TRAP BYPASS MO	DE AND SOUND CARRIER OFF; note 1	1				
$V_{o(v)(p-p)}$	video output voltage (peak-to-peak value)	see Fig.8	0.95	1.10	1.25	V
V <sub>sync</sub>	sync voltage level		1.35	1.5	1.6	V
$V_{clip(u)}$	upper video clipping voltage level		3.5	3.6	-	V
$V_{clip(I)}$	lower video clipping voltage level		_	0.9	1.0	V
B <sub>v(-1dB)</sub>	-1 dB video bandwidth	$C_L < 20 \text{ pF}; R_L > 1 \text{ k}\Omega;$ AC load	5	6	-	MHz
B <sub>v(-3dB)</sub>	-3 dB video bandwidth	$C_L < 20 \text{ pF}; R_L > 1 \text{ k}\Omega;$ AC load	7	8	_	MHz

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UN
S/N <sub>W</sub>	weighted signal-to-noise ratio	weighted in accordance with "CCIR 567"; see Fig.4; note 7	56	59	_	dB
S/N <sub>UW</sub>	unweighted signal-to-noise ratio	note 7	48	52	_	dB
VIF-AGC; note 12	2				•	
t <sub>resp(inc)</sub>	AGC response time to an increasing VIF step	negative modulation; normal mode; note 13	_	4.3	_	μs/d
DataSheet4U.com		negative modulation; mobile mode; note 13	_	1.5	_	μs/d
		positive modulation; VIF step: 20 dB; note 13	_	2.6	_	ms
t <sub>resp(dec)</sub>	AGC response time to a	negative modulation				
	decreasing VIF step	normal mode; note 13	_	1.9	_	ms/c
		fast normal mode; notes 13 and 13a	_	0.08	_	ms/d
		mobile mode; note 13	_	0.25	_	ms/d
		fast mobile mode; notes 13 and 13a	_	0.01	_	ms/d
		positive modulation				
		normal mode; VIF step: 20 dB; note 13	_	890	_	ms
		normal mode; note 13	_	143	_	ms/d
		fast mode; notes 13 and 13b	_	2.6	_	ms/d
$\Delta V_{i(VIF)}$	VIF amplitude step for activating AGC fast mode	L standard	-2	-6	-10	dB
$V_{VAGC}$	gain control voltage range	see Fig.9	0.8	_	3.5	V
CR <sub>stps</sub>	control steepness	definition: $\Delta G_{VIF}/\Delta V_{VAGC};$ $V_{VAGC} = 2 \text{ to } 3 \text{ V}$	_	-80	_	dB/∖
$V_{th(VIF)}$	threshold voltage for high level VIF input	see Tables 5 and 6	120	200	320	μV
PIN VAGC						
I <sub>ch(max)</sub>	maximum charge current	L standard	_	100	_	μΑ
I <sub>ch(add)</sub>	additional charge current	L standard: in the event of missing VITS pulses and no white video content	-	100	_	nA

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UN
I <sub>dch</sub>	discharge current	L standard; normal mode	_	35	_	nA
		L standard; fast mode	_	1.8	_	μΑ
AGC input switc	h (pin AGCSW); see Table 15; no	te 14			•	•
V <sub>ext(AGCOFF)</sub>	voltage level for external AGC = OFF	E5 = 1; E7 = 1	_	_	0.3	V
V <sub>ext(AGCON)</sub>	voltage level for external AGC = ON	E5 = 1; E7 = 1	2.5	_	-	V
RitaSheet4U.com	input resistance	E5 = 1; E7 = 1	8	_	_	kΩ
l <sub>i</sub>	input current	E5 = 1; E7 = 1; V <sub>AGCSW</sub> = 0 V	_	5	_	μА
Vi	input voltage	E5 = 1; E7 = 1; pin AGCSW open-circuit	V <sub>P</sub> – 1.7	_	-	V
t <sub>d1</sub>	switching delay for external AGC = ON	E5 = 1; E7 = 1; V <sub>AGCSW</sub> = 2.5 V	_	_	150	ns
t <sub>d2</sub>	switching delay for external AGC = OFF	E5 = 1; E7 = 1; V <sub>AGCSW</sub> = 0.3 V	_	_	150	ns
Tuner AGC (pin	TAGC); see Figs 3, 9 and 10			•	•	•
V <sub>i(VIF)(start1)(rms)</sub>	VIF input signal voltage for minimum starting point of tuner takeover at pins VIF1 and VIF2 (RMS value)	$I_{TAGC}$ = 120 μA; $R_{TOP}$ = 22 kΩ or no $R_{TOP}$ and -15 dB via $I^2$ C-bus (see Table 13)	_	2	5	mV
V <sub>i(VIF)(start2)(rms)</sub>	VIF input signal voltage for maximum starting point of tuner takeover at pins VIF1 and VIF2 (RMS value)	$I_{TAGC}$ = 120 μA; $R_{TOP}$ = 0 Ω or no $R_{TOP}$ and +15 dB via $I^2$ C-bus (see Table 13)	45	90	-	mV
Vi(SIF)(start1)(rms)	SIF input signal voltage for minimum starting point of tuner takeover at pins SIF1 and SIF2 (RMS value)	true split sound mode; $I_{TAGC}$ = 120 $\mu$ A; $R_{TOP}$ = 22 $k\Omega$ or no $R_{TOP}$ and -15 dB via $I^2$ C-bus (see Table 13)	-	1	2.5	mV
Vi(SIF)(start2)(rms)	SIF input signal voltage for maximum starting point of tuner takeover at pins SIF1 and SIF2 (RMS value)	true split sound mode; $I_{TAGC}$ = 120 $\mu$ A; $R_{TOP}$ = 0 $\Omega$ or no $R_{TOP}$ and +15 dB via $I^2$ C-bus (see Table 13)	22.5	45	_	mV
QV <sub>TOP</sub>	tuner takeover point accuracy	$I_{TAGC}$ = 120 μA; $R_{TOP}$ = 10 kΩ; or no $R_{TOP}$ and 0 dB via $I^2$ C-bus (see Table 13)				
		normal mode	7	17	43	mV
		true split sound mode	4	9	22	mV
$\Delta QV_{TOP}/\Delta T$	takeover point variation with temperature	$I_{TAGC} = 120 \mu A$	_	0.03	0.07	dB/k

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V <sub>o</sub>	permissible output voltage	from external source	_	_	8.8	V
V <sub>sat</sub>	saturation voltage	I <sub>TAGC</sub> = 450 μA	_	_	0.5	V
I <sub>sink</sub>	sink current	no tuner gain reduction; V <sub>TAGC</sub> = 8.8 V	_	_	0.75	μΑ
		maximum tuner gain reduction; V <sub>TAGC</sub> = 1 V	450	600	750	μΑ
$\Delta G_IF$	IF slip by automatic gain control	tuner gain current from 20 % to 80 %	3	5	8	dB
AFC circuit (pir	AFC); see Fig.6; notes 15 and 16					
V <sub>sat(ul)</sub>	upper limit saturation voltage		V <sub>P</sub> – 0.6	V <sub>P</sub> – 0.3	_	V
V <sub>sat(II)</sub>	lower limit saturation voltage		_	0.3	0.6	V
I <sub>o(source)</sub>	output source current		160	200	240	μΑ
I <sub>o(sink)</sub>	output sink current		160	200	240	μΑ
AFC <sub>stps</sub>	AFC control steepness	definition: ΔI <sub>AFC</sub> /Δf <sub>VIF</sub>	0.85	1.05	1.25	μΑ/kH
Qf <sub>VIF(a)</sub>	analog accuracy of AFC circuit	I <sub>AFC</sub> = 0; f <sub>REF</sub> = 4 MHz	-20	_	+20	kHz
$Qf_{VIF(d)}$	digital accuracy of AFC circuit via I <sup>2</sup> C-bus	I <sub>AFC</sub> = 0; f <sub>REF</sub> = 4 MHz; 1 digit = 25 kHz	−20 − 1 digit	_	+20 + 1 digit	kHz
SIF-AGC monit	cor (pin AFC); see Table 11; note 15	5	•			
I <sub>o(source)</sub>	SIF-AGC monitor source current		_	_	600	μΑ
I <sub>o(sink)</sub>	SIF-AGC monitor sink current		_	_	270	μА
SIF amplifier (p	pins SIF1 and SIF2)		•	•	•	•
$V_{i(SIF)(rms)}$	SIF input voltage sensitivity (RMS value)	FM mode; –3 dB at intercarrier output pin SIOMAD	_	30	70	μV
		AM mode; –3 dB at AF output pin AUD	_	70	100	μV
V <sub>i(max)(rms)</sub>	maximum input voltage (RMS value)	FM mode; 1 dB at intercarrier output pin SIOMAD	50	70	_	mV
		AM mode; 1 dB at AF output pin AUD	80	140	_	mV
V <sub>i(ovI)(rms)</sub>	overload input voltage (RMS value)	note 2	_	_	320	mV
G <sub>SIF(cr)</sub>	SIF gain control range	FM and AM mode; see Fig.10	60	66	_	dB
B <sub>SIF(-3dB)(II)</sub>	lower limit -3 dB SIF bandwidth		_	15	_	MHz
B <sub>SIF(-3dB)(uI)</sub>	upper limit –3 dB SIF bandwidth		_	80	_	MHz
R <sub>i(diff)</sub>	differential input resistance	note 3	_	2	_	kΩ
C <sub>i(diff)</sub>	differential input capacitance	note 3	_	3	_	pF
VI	DC input voltage		_	1.93	_	V

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNI
SIF-AGC detecto	r					
t <sub>resp</sub>	AGC response time to an	FM or AM fast step;				
•	increasing or decreasing SIF	normal mode; note 13b				
	step of 20 dB	increasing	_	8	_	ms
		decreasing	_	25	_	ms
		FM or AM fast step; mobile mode; note 13b				
		increasing	_	tbf	_	ms
DataSheet4U.com		decreasing	_	0.7	_	ms
		AM slow step				
		increasing	_	80	_	ms
		decreasing	_	250	_	ms
Single reference	QSS intercarrier mixer (pin SI	OMAD)	•			!
V <sub>o(intc)(rms)</sub>	IF intercarrier output level (RMS value)	QSS mode; SC <sub>1</sub> ; SC <sub>2</sub> off	90	140	180	mV
		L standard; without modulation	90	140	180	mV
		intercarrier mode; PC/SC <sub>1</sub> = 20 dB; SC <sub>2</sub> off; note 17	_	75	_	mV
B <sub>intc(-3dB)(ul)</sub>	upper limit –3 dB intercarrier bandwidth		12	15	-	MHz
$\Delta V_{r(SC)(rms)}$	residual sound carrier (RMS value)	fundamental wave and harmonics				
		QSS mode	_	2	5	mV
		intercarrier mode	_	2	5	mV
$\Delta V_{r(PC)(rms)}$	residual picture carrier (RMS value)	fundamental wave and harmonics				
		QSS mode	_	2	5	mV
		intercarrier mode	_	5	20	mV
$\alpha_{H}$	suppression of video signal harmonics	intercarrier mode; f <sub>video</sub> = 5 MHz	35	40	-	dB
R <sub>o</sub>	output resistance	note 3	_	_	30	Ω
V <sub>O</sub>	DC output voltage		_	2	_	V
I <sub>bias(int)</sub>	internal DC bias current for emitter follower		0.90	1.15	_	mA
I <sub>o(sink)(max)</sub>	maximum AC output sink current		0.6	0.8	_	mA
I <sub>o(source)(max)</sub>	maximum AC output source current		0.6	0.8	_	mA
I <sub>o(source)</sub>	DC output source current	MAD2 activated; note 18	0.75	0.93	1.20	mA

# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UN
FM-PLL demodu	lator; notes 16 and 19 to 23				•	
SOUND INTERCARE	RIER OUTPUT (PIN SIOMAD)					
V <sub>FM(rms)</sub>	IF intercarrier level for gain controlled operation of FM-PLL (RMS value)	corresponding PC/SC ratio at input pins VIF1 and VIF2 is 7 to 47 dB	3.2	_	320	mV
$V_{FM(lock)(rms)}$	IF intercarrier level for lock-in of PLL (RMS value)		_	_	2	mV
V <sub>FM(det)(rms)</sub> DataSheet4U.com	IF intercarrier level for FM carrier detect (RMS value)	see Table 6	_	_	2.3	mV
f <sub>FM</sub>	sound intercarrier operating	see Table 14	_	4.5	_	MHz
	FM frequencies		_	5.5	_	MHz
			_	6.0	_	MHz
			_	6.5	_	MHz
		true split sound mode;	_	3.1	_	MHz
		see Table 17	_	3.6	_	MHz
			_	5.6	_	MHz
			_	6.6	_	MHz
AUDIO OUTPUT (PI	n AUD)					
V <sub>o(AF)(rms)</sub>	AF output voltage (RMS value)	25 kHz FM deviation; 75 μs de-emphasis	400	500	600	mV
		27 kHz FM deviation; 50 μs de-emphasis	430	540	650	mV
V <sub>o(AF)(cl)(rms)</sub>	AF output clipping level (RMS value)	THD < 1.5 %	1.3	1.4	_	V
$\Delta V_{o(AF)}/\Delta T$	AF output voltage variation with temperature		_	3 × 10 <sup>-3</sup>	7 × 10 <sup>-3</sup>	dB/k
THD	total harmonic distortion	27 kHz FM deviation; 50 μs de-emphasis	_	0.15	0.50	%
$\Delta f_{AF}$	frequency deviation	THD < 1.5 %; note 20	_	_	±55	kHz
		<ul><li>−6 dB AF output via</li><li>I<sup>2</sup>C-bus; note 20</li></ul>	_	_	±110	kHz
B <sub>AF</sub> (-3dB)	-3 dB AF bandwidth	without de-emphasis; measured with FM-PLL filter of Fig.21	80	100	_	kHz
S/N <sub>W(AF)</sub>	weighted signal-to-noise ratio of audio signal	FM-PLL only; 27 kHz FM deviation; 50 μs de-emphasis	52	56	-	dB
		black picture; see Fig.11	50	56	_	dB
$\Delta V_{r(SC)(rms)}$	residual sound carrier (RMS value)	fundamental wave and harmonics; without de-emphasis	_	-	2	mV

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UN
$lpha_{AM(sup)}$	AM suppression of FM demodulator	referenced to 27 kHz FM deviation; 50 μs de-emphasis; AM: f = 1 kHz; m = 54 %	40	46	-	dB
PSRR <sub>FM</sub>	power supply ripple rejection	f <sub>ripple</sub> = 70 Hz; see Fig.7	14	20	_	dB
FM-PLL FILTER (P	PIN FMPLL)			•		'
$V_{loop}$	DC loop voltage		1.5	_	3.3	V
lo(source)(PD)(max)	maximum phase detector output source current		_	60	_	μΑ
I <sub>o(sink)(PD)(max)</sub>	maximum phase detector output sink current		_	60	_	μΑ
I <sub>o(source)(DAH)</sub>	output source current of digital acquisition help		_	55	_	μΑ
I <sub>o(sink)(DAH)</sub>	output sink current of digital acquisition help		_	55	_	μΑ
t <sub>W(DAH)</sub>	pulse width of digital acquisition help current		_	16	_	μs
T <sub>cy(DAH)</sub>	cycle time of digital acquisition help		_	64	_	μs
$K_{O(FM)}$	VCO steepness	definition: $\Delta f_{FM}/\Delta V_{FMPLL}$	_	3.3	_	MHz
$K_{D(FM)}$	phase detector steepness	definition: $\Delta I_{FMPLL}/\Delta \phi_{FM}$	_	4	_	μA/ra
Audio amplifier						
DE-EMPHASIS NET	WORK (PIN DEEM)					
R <sub>o</sub>	output resistance	50 μs de-emphasis; see Table 12	4.4	5.0	5.6	kΩ
		75 μs de-emphasis; see Table 12	6.6	7.5	8.4	kΩ
V <sub>AF(rms)</sub>	audio signal (RMS value)	f <sub>AF</sub> = 400 Hz; V <sub>AUD</sub> = 500 mV	_	170	_	mV
V <sub>O</sub>	DC output voltage		_	2.37	_	V
AF DECOUPLING (	PIN AFD)					
V <sub>dec</sub>	DC decoupling voltage	dependent on f <sub>FM</sub> intercarrier frequency	1.5	_	3.3	V
IL	leakage current	$\Delta V_{O(AUD)} < \pm 50 \text{ mV}$	_	_	±25	nA
I <sub>ch(max)</sub>	maximum charge current		1.15	1.50	1.85	μΑ
I <sub>dch(max)</sub>	maximum discharge current		1.15	1.50	1.85	μΑ
AUDIO OUTPUT (PI	n AUD)					
R <sub>o</sub>	output resistance	note 3	_	_	300	Ω
V <sub>O(AUD)</sub>	DC output voltage		_	2.37	_	V
R <sub>L</sub>	load resistance	AC-coupled	10	_		kΩ

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNI
R <sub>L(DC)</sub>	DC load resistance		100	_	-	kΩ
C <sub>L</sub>	load capacitance		_	_	1.5	nF
B <sub>AF(-3dB)(ul)</sub>	upper limit –3 dB AF bandwidth of audio amplifier		150	_	_	kHz
B <sub>AF(-3dB)(II)</sub>	lower limit –3 dB AF bandwidth of audio amplifier	note 21	_	_	20	Hz
$\alpha_{mute}$	mute attenuation of AF signal	via I <sup>2</sup> C-bus	70	75	_	dB
ΔV <sub>jump</sub> DataSheet4U.com	DC jump voltage for switching AF output to mute state and vice versa	activated by digital acquisition help or via I <sup>2</sup> C-bus mute	_	±50	±150	mV
FM operation; n	otes 22 and 24			•		•
INTERCARRIER AF	PERFORMANCE; note 25					
S/N <sub>W</sub>	weighted signal-to-noise ratio	PC/SC ratio is 21 to 27 dB at pins VIF1 and VIF2				
		black picture	50	56	_	dB
		white picture	45	51	_	dB
		6 kHz sine wave (black-to-white modulation)	40	46	_	dB
		sound carrier subharmonics; f = 2.75 MHz ±3 kHz	35	40	_	dB
SINGLE REFERENCE	LE QSS AF PERFORMANCE; notes 2			1	1	
S/N <sub>W(SC1)</sub> we	weighted signal-to-noise ratio for SC <sub>1</sub>	PC/SC <sub>1</sub> ratio at pins VIF1 and VIF2; 27 kHz (54 % FM deviation); "CCIR 468"	40	-	-	dB
		black picture	53	58	_	dB
		white picture	50	53	_	dB
		6 kHz sine wave (black-to-white modulation)	44	48	_	dB
		250 kHz square wave (black-to-white modulation)	40	45	_	dB
		sound carrier subharmonics; f = 2.75 MHz ±3 kHz	45	51	_	dB
		sound carrier subharmonics; f = 2.87 MHz ±3 kHz	46	52	_	dB

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UN
S/N <sub>W(SC2)</sub>	weighted signal-to-noise ratio for SC <sub>2</sub>	PC/SC <sub>2</sub> ratio at pins VIF1 and VIF2; 27 kHz (54 % FM deviation); "CCIR 468"	40	_	_	dB
		black picture	48	55	_	dB
		white picture	46	51	_	dB
		6 kHz sine wave (black-to-white modulation)	42	46	_	dB
DataSheet4U.com		250 kHz square wave (black-to-white modulation)	29	34	_	dB
		sound carrier subharmonics; f = 2.75 MHz ±3 kHz	44	50	_	dB
		sound carrier subharmonics; f = 2.87 MHz ±3 kHz	45	51	_	dB
AM operation		,	•	•	•	'
L STANDARD (PIN A	AUD); see Figs 12 and 13; note 28					
V <sub>o(AF)(rms)</sub>	AF output voltage (RMS value)	54 % modulation	400	500	600	mV
THD	total harmonic distortion	54 % modulation	_	0.5	1.0	%
B <sub>AF(-3dB)</sub>	−3 dB AF bandwidth		100	125	_	kHz
S/N <sub>W(AF)</sub>	weighted signal-to-noise ratio of audio signal	in accordance with "CCIR 468"	45	50	_	dB
V <sub>O(AUD)</sub>	DC potential voltage		_	2.37	_	V
PSRR <sub>AM</sub>	power supply ripple rejection	see Fig.7	20	26	_	dB
Reference freque	ency input (pin REF)			•	•	
VI	DC input voltage		2.3	2.6	2.9	V
R <sub>i</sub>	input resistance	note 3	_	5	_	kΩ
R <sub>xtal</sub>	resonance resistance of crystal	operation as crystal oscillator	_	_	200	Ω
C <sub>x</sub>	pull-up/down capacitance	note 29	_	_	_	pF
f <sub>ref</sub>	reference signal frequency	note 30	_	4	_	MHz
$\Delta f_{ref}$	tolerance of reference signal frequency	note 16	_	_	±0.1	%
V <sub>ref(rms)</sub>	reference signal voltage (RMS value)	operation as input terminal	80	_	400	mV
R <sub>o(ref)</sub>	output resistance of reference signal source		_	_	4.7	kΩ
C <sub>K</sub>	decoupling capacitance to external reference signal source	operation as input terminal	22	100	-	pF

# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
l <sup>2</sup> C-bus transcei	ver (pins SDA and SCL); notes 3	1 and 32				
f <sub>SCL</sub>	SCL clock frequency		0	_	400	kHz
V <sub>IH</sub>	HIGH-level input voltage		3	_	V <sub>CC</sub>	V
V <sub>IL</sub>	LOW-level input voltage		-0.3	_	+1.5	V
l <sub>IH</sub>	HIGH-level input current		-10	_	+10	μΑ
I <sub>IL</sub>	LOW-level input current		-10	_	+10	μΑ
V <sub>OL</sub>	LOW-level output voltage	I <sub>OL</sub> = 3 mA	_	_	0.4	V
l <sub>o(sink)</sub>	output sink current	$V_P = 0 V$	_	_	10	μΑ
lo(source)	output source current	$V_P = 0 V$	_	_	10	μΑ
Output ports (pi	ns OP1 and OP2); notes 12, 14 a	nd 33	•	•	-	•
V <sub>OL</sub>	LOW-level output voltage	I <sub>OL</sub> = 2 mA (sink current)	_	_	0.4	V
V <sub>OH</sub>	HIGH-level output voltage		_	_	6	V
I <sub>o(sink)</sub>	output sink current		_	_	2	mA
I <sub>o(sink/source)(max)</sub>	maximum output sink or source current	pin OP2 functions as VIF-AGC output	_	-	10	μΑ

### **Notes**

WWW

- 1. Values of video and sound parameters can be decreased at  $V_P = 4.5 \text{ V}$ .
- Level headroom for input level jumps during gain control setting.
- This parameter is not tested during the production and is only given as application information for designing the receiver circuit.
- 4. Loop bandwidth BL = 70 kHz (damping factor d = 1.9; calculated with sync level within gain control range). Calculation of the VIF-PLL filter can be done by use of the following formula:

$$BL_{-3dB} = \frac{1}{2\pi} K_O K_D R$$
, valid for  $d \ge 1.2$ 

$$d \,=\, \frac{1}{2} R \, \sqrt{K_O K_D C} \; , \label{eq:definition}$$

where

 $K_{O}$  is the VCO steepness  $\left(\frac{rad}{V}\right)$  or  $\left(2\pi\frac{Hz}{V}\right)$ ;  $K_{D}$  is the phase detector steepness  $\left(\frac{\mu A}{rad}\right)$ ;

R is the loop resistor; C is the loop capacitor;  $BL_{-3dB}$  is the loop bandwidth for -3 dB; d is the damping factor.

- 5.  $V_{i(VIF)} = 10$  mV (RMS);  $\Delta f = 1$  MHz (VCO frequency offset related to picture carrier frequency); white picture video modulation.
- 6. Condition: luminance range (5 steps) from 0 % to 100 %.
- S/N is the ratio of black-to-white amplitude to the black level noise voltage (RMS value on pin CVBS). B = 5 MHz (B/G, I and D/K standard). Noise analyzer setting: 200 kHz high-pass and SC-trap switched on.
- 8. The intermodulation figures are defined for:
  - a) f = 1.1 MHz (referenced to black and white signal) as  $\alpha_{IM} = 20 \log \left( \frac{V_0 \text{ at } 4.4 \text{ MHz}}{V_0 \text{ at } 1.1 \text{ MHz}} \right) + 3.6 \text{ dB}$
  - b) f = 3.3 MHz (referenced to colour carrier) as  $\alpha_{IM} = 20 \, log \left( \frac{V_0 \, at \, 4.4 \, MHz}{V_0 \, at \, 3.3 \, MHz} \right)$

# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

**TDA9884TS** 

- 9. Measurements taken with SAW filter M1963M (sound shelf: 20 dB); loop bandwidth BL = 70 kHz.
  - a) Modulation Vestigial Side-Band (VSB); sound carrier off; f<sub>video</sub> > 0.5 MHz.
  - b) Sound carrier on;  $f_{video} = 10 \text{ kHz}$  to 10 MHz.
- 10. AC load;  $C_L < 20$  pF and  $R_L > 1$  k $\Omega$ . The sound carrier frequencies (depending on TV standard) are attenuated by the integrated sound carrier traps (see Figs 15 to 20; |H(s)| is the absolute value of transfer function).
- 11. The sound carrier trap can be bypassed by switching the I<sup>2</sup>C-bus. In this way the full composite video spectrum appears at pin CVBS. The amplitude is 1.1 V (p-p).
- 12. If selected by the I<sup>2</sup>C-bus, the VIF-AGC voltage can be monitored at pin OP2. In this case, the OP2 cannot be used for the normal port function.
- 13. The response time is valid for a VIF input level range from 200  $\mu V$  to 70 mV.
- A) The fast mode will be activated automatically, if within a time of typically 150 μs for mobile mode and 1.2 ms for normal mode no AGC event occurs. An AGC event is a charge current pulse into the AGC capacitor due to reaching AGC reference voltage the sync level.
  - b) The fast mode will be activated automatically, if the black level drops down by half of the sync amplitude.
  - 14. If selected by the I<sup>2</sup>C-bus, pin OP1 can alternatively be used for external AGC control, activated by pin AGCSW. In this case OP1 cannot be used for normal port function.
  - 15. Pin AFC is usable as AFC output or as SIF-AGC
    - a) To match the AFC output signal to different tuning systems a current source output is provided. The test circuit is given in Fig.6. The AFC steepness can be changed by resistors R1 and R2.
    - b) In mobile mode the internal SIF-AGC is switched to pin AFC. In this case AFC out is disabled.
  - 16. The tolerance of the reference frequency determines the accuracy of the VIF-AFC, FM demodulator centre frequency and maximum FM deviation.
  - 17. The intercarrier output signal at pin SIOMAD can be calculated by the following formula taking into account the internal video signal with 1.1 V (p-p) as a reference:

$$V_{o(intc)(rms)} = 1.1 \times \frac{1}{2\sqrt{2}} \times 10^r \text{ V}$$

and 
$$r = \frac{1}{20} \times \left( \frac{V_{i(SC)}}{V_{i(PC)}} (dB) + 6 dB \pm 3 dB \right)$$

where:

 $\frac{1}{2\sqrt{2}}$  is the correction term for RMS value,  $\frac{V_{i(SC)}}{V_{i(PC)}}$  (dB) is the sound-to-picture carrier ratio at pins VIF1 and VIF2

in dB, 6 dB is the correction term of internal circuitry and  $\pm 3$  dB is the tolerance of video output and intercarrier output  $V_{o(intc)(rms)}$ .

- 18. For normal operation (with the  $I^2$ C-bus) no DC load at pin SIOMAD is allowed. The second module address (MAD2) will be activated by the application of a 2.2 k $\Omega$  resistor between pin SIOMAD and ground. If this MAD2 is activated, also the power-on set-up state activates a VIF frequency of 58.75 MHz.
- 19. SIF input level is 10 mV (RMS); VIF input level is 10 mV (RMS) unmodulated.
- 20. Measured with an FM deviation of 25 kHz and the typical AF output voltage of 500 mV (RMS). The AF output signal can be attenuated by 6 dB to 250 mV (RMS) via the I<sup>2</sup>C-bus. For handling a frequency deviation of more than 55 kHz, the AF output signal has to be reduced in order to avoid clipping (THD < 1.5 %).
- 21. The lower limit of the audio bandwidth depends on the value of the capacitor at pin AFD. A value of  $C_{AF} = 470$  nF leads to  $f_{AF(-3dB)} \approx 20$  Hz and  $C_{AF} = 220$  nF leads to  $f_{AF(-3dB)} \approx 40$  Hz.

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- 22. For all S/N measurements the VIF modulator in use has to meet the following specifications:
  - a) Incidental phase modulation for black-to-white jump less than 0.5 degrees.
  - b) QSS AF performance, measured with the television demodulator AMF2 (audio output, weighted S/N ratio) better than 60 dB (at deviation 27 kHz) for 6 kHz sine wave black-to-white video modulation.
  - c) Picture-to-sound carrier ratio PC/SC<sub>1</sub> = 13 dB (transmitter).
- 23. Calculation of the loop filter parameters can be done approximately using the following formulae:

$$\begin{split} f_{o} &= \frac{1}{2\pi} \sqrt{\frac{K_{O}K_{D}}{C_{P}}} \\ \vartheta &= \frac{1}{2B\sqrt{K_{O}K_{D}C_{P}}} \end{split}$$

$$BL_{-3dB} = f_o(1.55 - \vartheta^2)$$

The formulae are only valid under the following conditions:

 $\vartheta \le 1$  and  $C_S > 5C_P$ 

where:

 $K_{O}$  is the VCO steepness  $\left(\frac{\text{rad}}{V}\right)$  or  $\left(2\pi\frac{\text{Hz}}{V}\right)$ ;

 $K_D$  is the phase detector steepness  $\left(\frac{\mu A}{rad}\right)$  ;

R is the loop resistor;

C<sub>S</sub> is the series capacitor;

C<sub>P</sub> is the parallel capacitor;

fo is the natural frequency of the PLL;

BL<sub>-3dB</sub> is the loop bandwidth for -3 dB;

 $\vartheta$  is the damping factor. For examples, see Table 20.

- 24. The PC/SC ratio is calculated as the addition of TV transmitter PC/SC $_1$  ratio and SAW filter PC/SC $_1$  ratio. This PC/SC ratio is necessary to achieve the S/N $_W$  values as noted. A different PC/SC ratio will change these values.
- 25. Measurements taken with SAW filter G1984 (Siemens) for vision and sound IF (sound shelf: 14 dB). Picture-to-sound carrier ratio of transmitter PC/SC = 13 dB. Input level on pins VIF1 and VIF2 of  $V_{i(SIF)}$  = 10 mV (RMS) sync level, 27 kHz FM deviation for sound carrier,  $f_{AF}$  = 400 Hz. Measurements in accordance with "CCIR 468". De-emphasis is 50  $\mu$ s.
- 26. The QSS signal output on pin SIOMAD is analysed by a test demodulator TDA9820. The S/N ratio of this device is more than 60 dB, related to a deviation of ±27 kHz, in accordance with "CCIR 468".
- 27. Measurements taken with SAW filter K3953 for vision IF (suppressed sound carrier) and K9453 for sound IF (suppressed picture carrier). Input level V<sub>i(SIF)</sub> = 10 mV (RMS), 27 kHz (54 % FM deviation).
- 28. Measurements taken with SAW filter K9453 (Siemens) for AM sound IF (suppressed picture carrier).
- 29. The value of C<sub>x</sub> determines the accuracy of the resonance frequency of the crystal. It depends on the type of crystal
- 30. Pin REF is able to operate as a 1-pin crystal oscillator input as well as an external reference signal input, e.g. from the tuning system.
- 31. The SDA and SCL lines will not be pulled down if V<sub>CC</sub> is switched off.
- 32. The AC characteristics are in accordance with the I<sup>2</sup>C-bus specification for fast mode (maximum clock frequency is 400 kHz). Information about the I<sup>2</sup>C-bus can be found in the brochure "The I<sup>2</sup>C-bus and how to use it" (order number 9398 393 40011).
- 33. Port P1 and port P2 are open-collector outputs.

# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

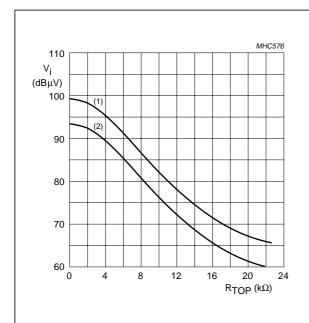
**TDA9884TS** 

Table 20 Examples to note 23 (FM-PLL filter)

BL <sub>-3dB</sub> (kHz)	C <sub>S</sub> (nF)	C <sub>P</sub> (pF)	<b>R (k</b> Ω)	ϑ
100	10	390	5.6	0.5
160	10	150	9.1	0.5

Table 21 Input frequencies and carrier ratios

	DESCRIPTION	SYMBOL	B/G STANDARD	M/N STANDARD	L STANDARD	L ACCENT STANDARD	UNIT
	VIF carrier	f <sub>PC</sub>	38.9	45.75 or 58.75	38.9	33.9	MHz
www	SIFacarrieru.com	f <sub>SC1</sub>	33.4	41.25 or 54.25	32.4	40.4	MHz
		f <sub>SC2</sub>	33.158	_	_	_	MHz
	Picture-to-sound	SC <sub>1</sub>	13	7	10	10	dB
	carrier ratio	SC <sub>2</sub>	20	_	_	_	dB



- (1)  $V_{i(VIF)}$
- (2)  $V_{i(SIF)}$ ; true split sound mode.

Fig.3 Typical tuner takeover point as a function of resistor  $R_{\text{TOP}}$ .

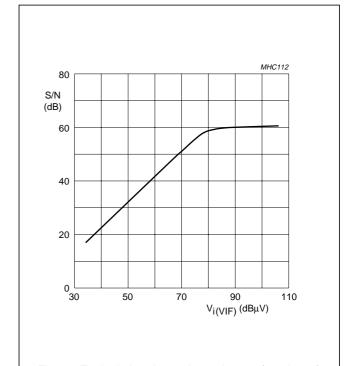
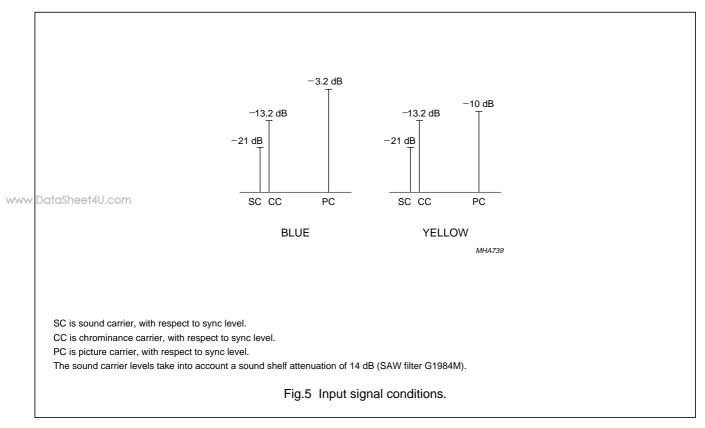
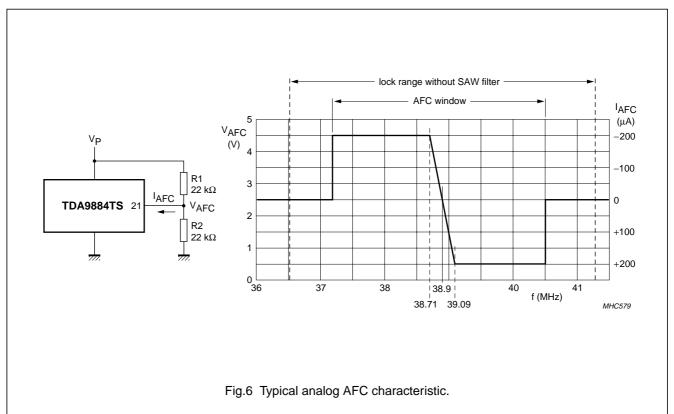


Fig.4 Typical signal-to-noise ratio as a function of VIF input voltage.

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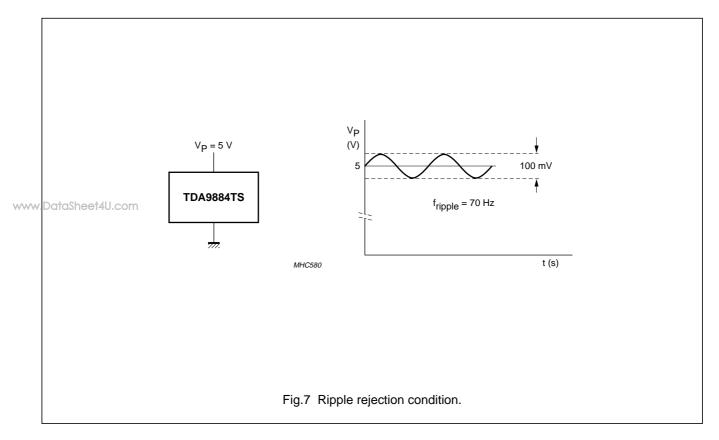
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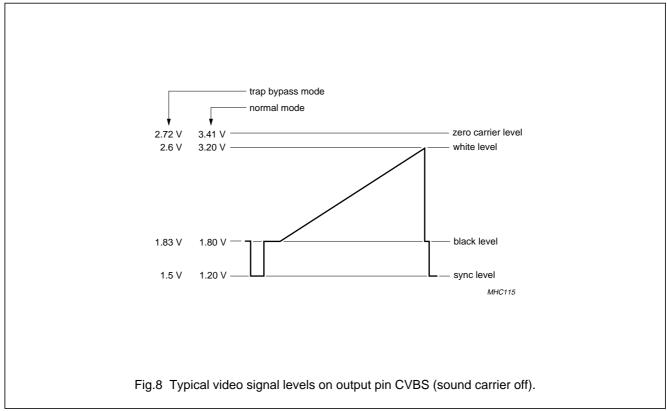




# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

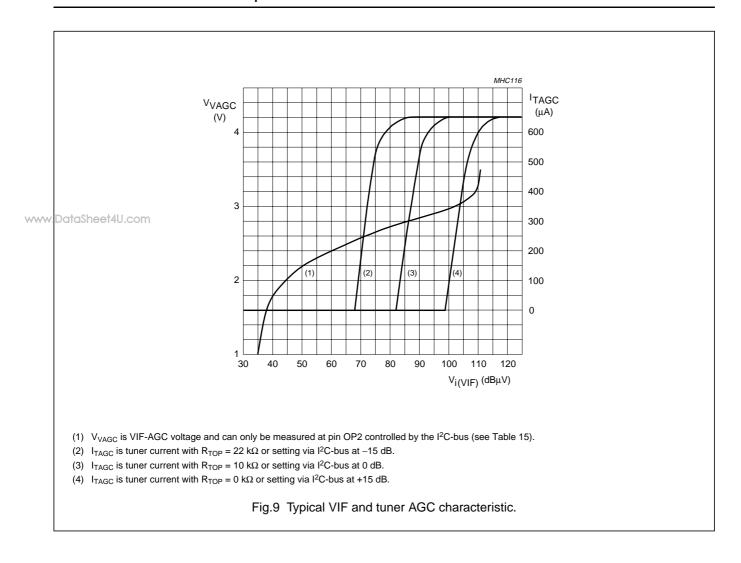
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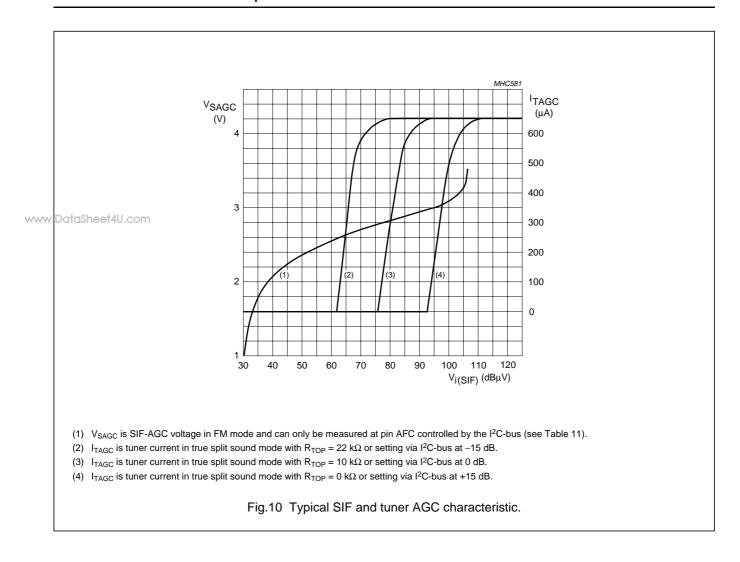
# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

**TDA9884TS** 



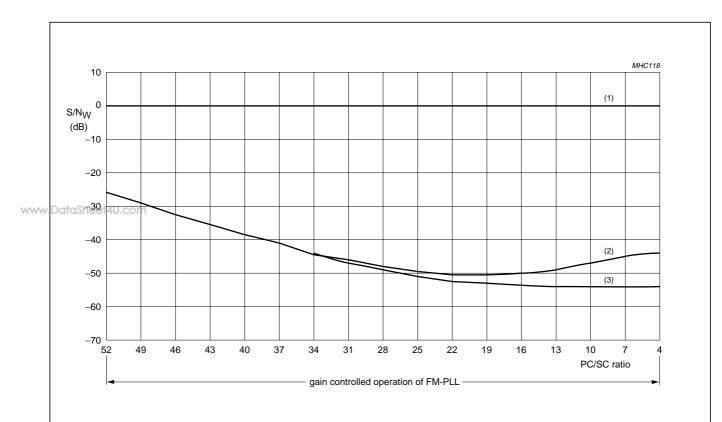
# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

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# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

**TDA9884TS** 



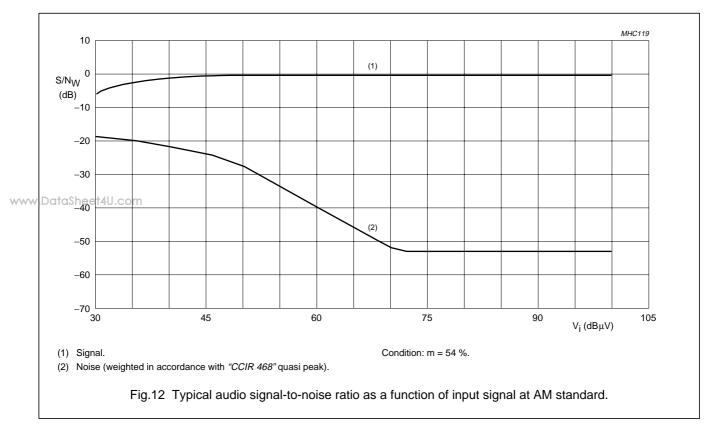
 $Conditions: PC/SC \ ratio \ measured \ at pins \ VIF1 \ and \ VIF2; via \ transformer; 27 \ kHz \ FM \ deviation; 50 \ \mu s \ de-emphasis.$ 

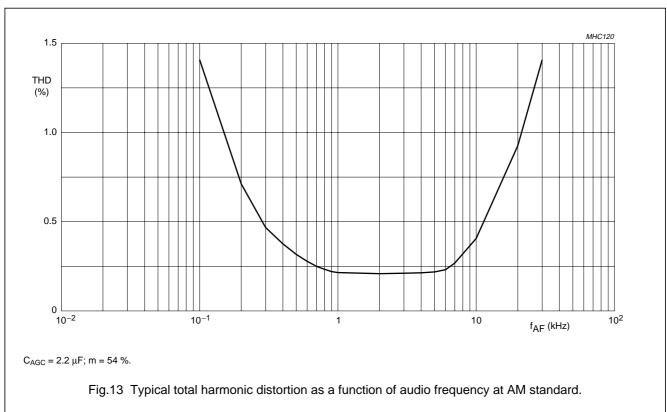
- (1) Signal.
- (2) Noise at H-picture (weighted in accordance with "CCIR 468" quasi peak).
- (3) Noise at black picture (weighted in accordance with "CCIR 468" quasi peak).

Fig.11 Audio signal-to-noise ratio as a function of picture-to-sound carrier ratio in intercarrier mode.

# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

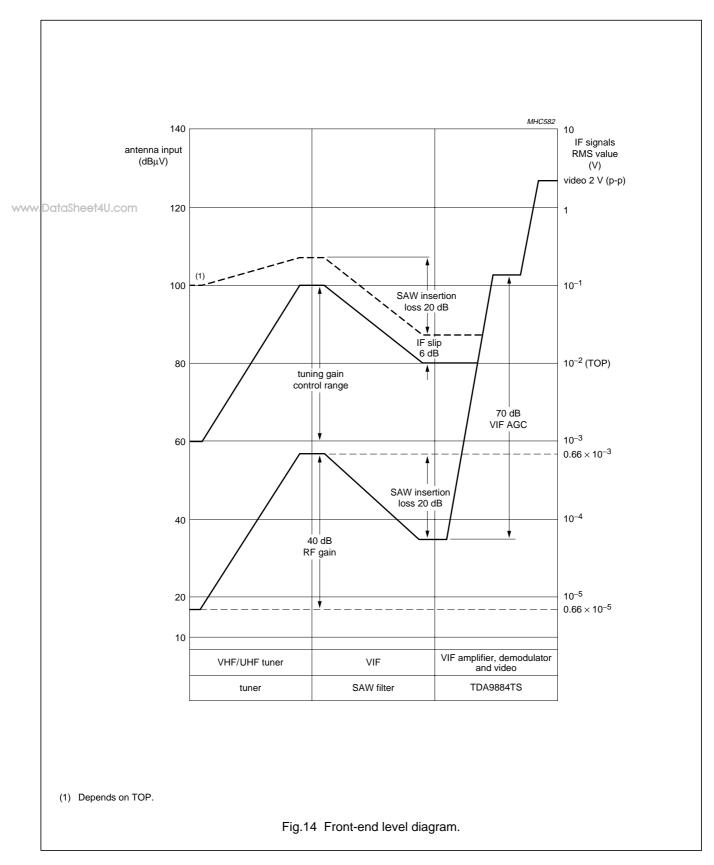
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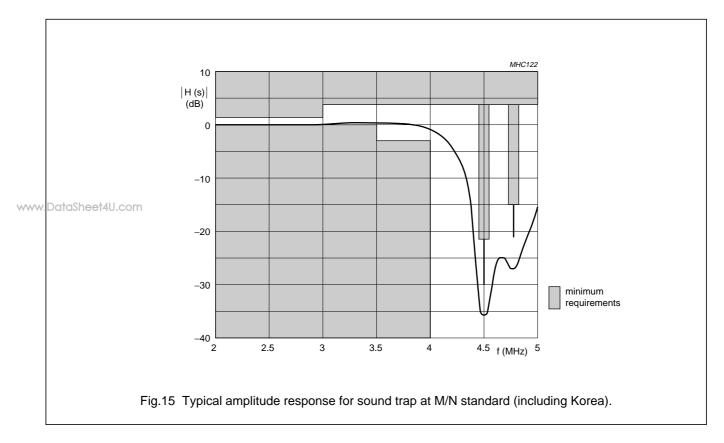
# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

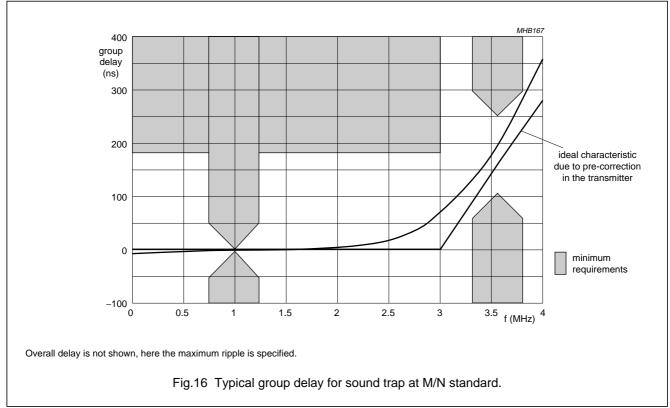
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# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

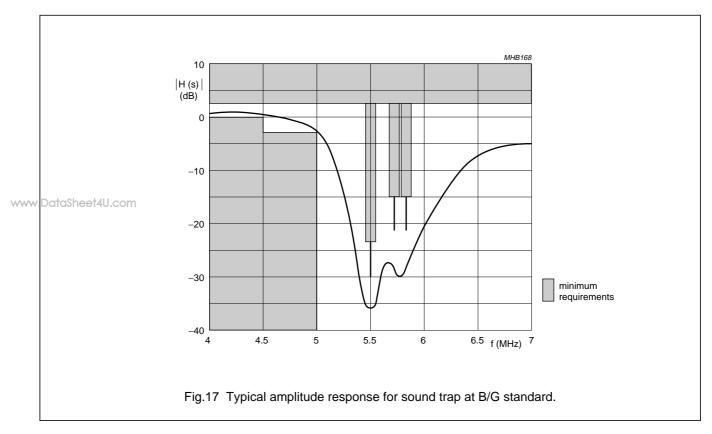
**TDA9884TS** 

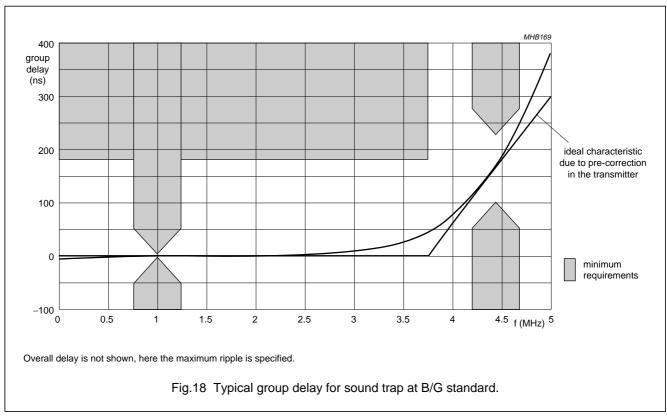




# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

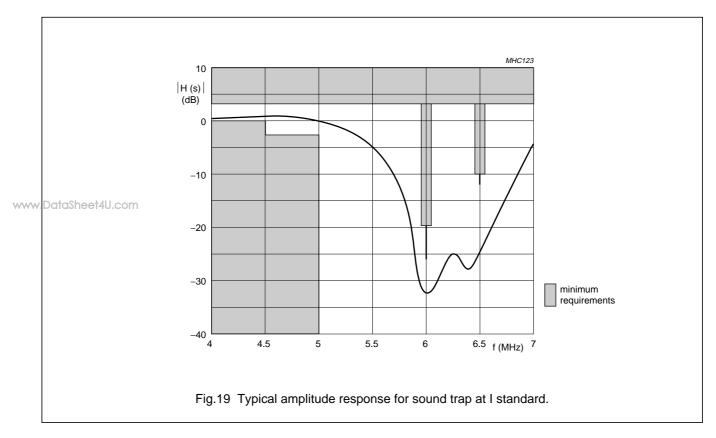
**TDA9884TS** 

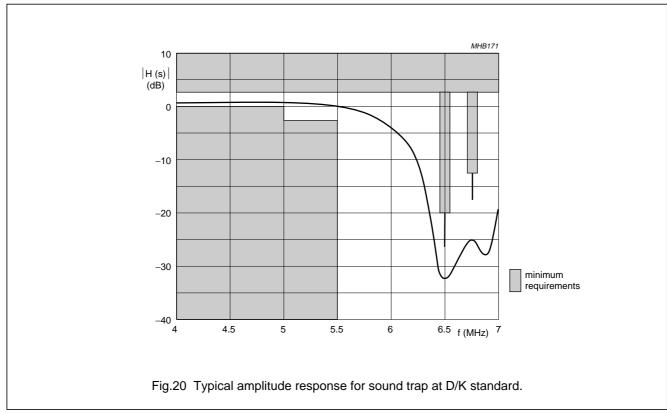




# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

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input

51 Ω

Philips Semiconductors Product specification

# IF-PLL I<sup>2</sup>C-bus controlled multistandard alignment-free for mobile reception

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# **TEST AND APPLICATION INFORMATION** AGCSW

13

external =

reference

VAGC

16

REF

15

**CVBS** 

output

CVAGC

470 nF

**CVBS** 

17

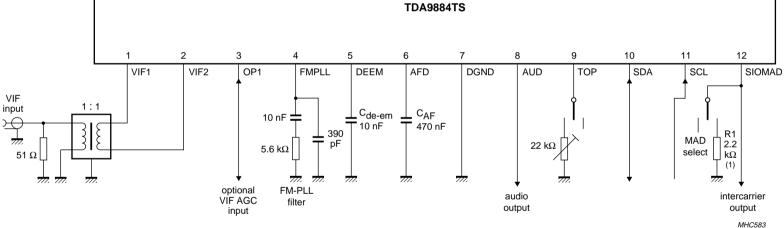
tuner AGC

output

TAGC

14

12



VIF-PLL

filter (3)

150 Ω

📥 220 nF

VPLL

19

AGND

18

(1) Optional for I2C-bus address selection.

1:1

Option	R1 not used	R1 = 2.2 kΩ		
R2 and R3 not used	1000 011 (R/W)	1000 010 (R/W)		
R2 = R3 = 150 kΩ	1001 011 (R/W)	1001 010 (R/W)		

- (2) See note 2 of Table 11.
- (3) Different VIF loop filter in comparison with the application circuit due to different input characteristics (SAW filter or transformer).

optional VIF AGC

(1) R2

150 k $\Omega$ 

SIF1

23

R3 150 k $\Omega$ 

SIF2

24

22

kΩ

OP2

22

AFC

output

100 nF

 $V_{\mathsf{P}}$ 

20

 $22 \text{ k}\Omega$ 

AFC<sup>(2)</sup>

21

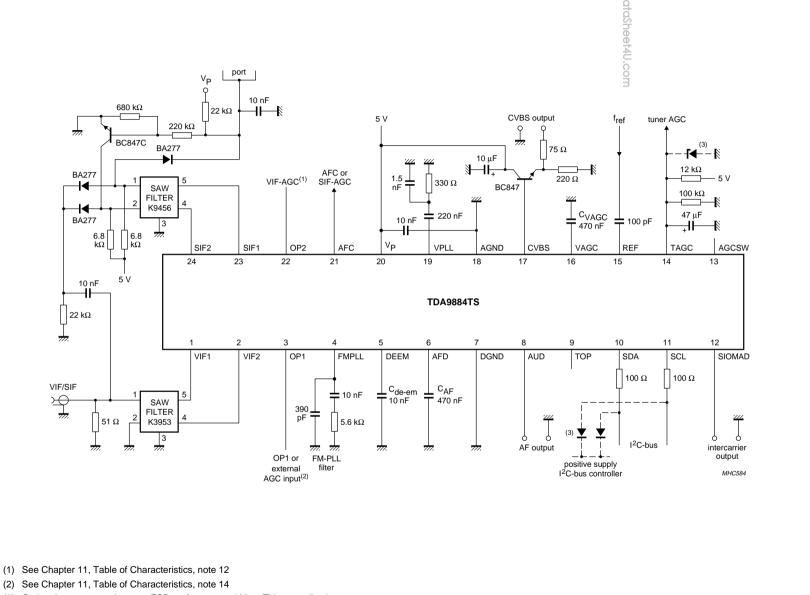
Fig.21 Test circuit.

Philips Semiconductors

IF-PLL I<sup>2</sup>C-bus controlled multistandard alignment-free for mobile reception

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Product specification



- (3) Optional measures to improve ESD performance within a TV-set application.

Fig.22 Application circuit.

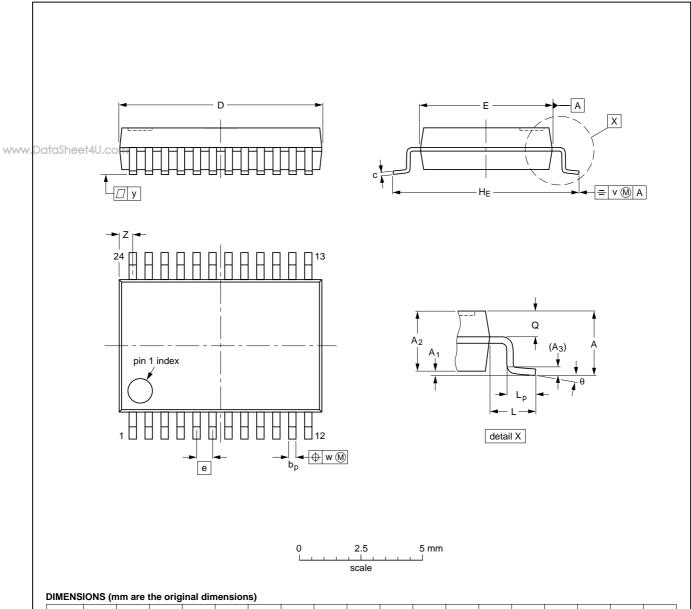
# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

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#### 13 PACKAGE OUTLINE

SSOP24: plastic shrink small outline package; 24 leads; body width 5.3 mm

SOT340-1



UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	bp	С	D <sup>(1)</sup>	E <sup>(1)</sup>	е	HE	L	Lp	Q	v	w	у	Z <sup>(1)</sup>	θ
mm	2	0.21 0.05	1.80 1.65	0.25	0.38 0.25	0.20 0.09	8.4 8.0	5.4 5.2	0.65	7.9 7.6	1.25	1.03 0.63	0.9 0.7	0.2	0.13	0.1	0.8 0.4	8° 0°

#### Note

1. Plastic or metal protrusions of 0.2 mm maximum per side are not included.

OUTLINE	REFERENCES				EUROPEAN	ISSUE DATE	
VERSION	IEC	JEDEC	JEITA		PROJECTION		
SOT340-1		MO-150				<del>99-12-27</del> 03-02-19	

# I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

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#### 14 SOLDERING

#### 14.1 Introduction to soldering surface mount packages

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our "Data Handbook IC26; Integrated Circuit Packages" (document order number 9398 652 90011).

There is no soldering method that is ideal for all surface mount IC packages. Wave soldering can still be used for certain surface mount ICs, but it is not suitable for fine pitch SMDs. In these situations reflow soldering is recommended.

#### 14.2 Reflow soldering

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement. Driven by legislation and environmental forces the worldwide use of lead-free solder pastes is increasing.

Several methods exist for reflowing; for example, convection or convection/infrared heating in a conveyor type oven. Throughput times (preheating, soldering and cooling) vary between 100 and 200 seconds depending on heating method.

Typical reflow peak temperatures range from 215 to 270 °C depending on solder paste material. The top-surface temperature of the packages should preferably be kept:

- below 220 °C (SnPb process) or below 245 °C (Pb-free process)
  - for all BGA and SSOP-T packages
  - for packages with a thickness ≥ 2.5 mm
  - for packages with a thickness < 2.5 mm and a volume ≥ 350 mm<sup>3</sup> so called thick/large packages.
- below 235 °C (SnPb process) or below 260 °C (Pb-free process) for packages with a thickness < 2.5 mm and a volume < 350 mm<sup>3</sup> so called small/thin packages.

Moisture sensitivity precautions, as indicated on packing, must be respected at all times.

#### 14.3 Wave soldering

Conventional single wave soldering is not recommended for surface mount devices (SMDs) or printed-circuit boards with a high component density, as solder bridging and non-wetting can present major problems. To overcome these problems the double-wave soldering method was specifically developed.

If wave soldering is used the following conditions must be observed for optimal results:

- Use a double-wave soldering method comprising a turbulent wave with high upward pressure followed by a smooth laminar wave.
- For packages with leads on two sides and a pitch (e):
  - larger than or equal to 1.27 mm, the footprint longitudinal axis is **preferred** to be parallel to the transport direction of the printed-circuit board;
  - smaller than 1.27 mm, the footprint longitudinal axis must be parallel to the transport direction of the printed-circuit board.

The footprint must incorporate solder thieves at the downstream end.

 For packages with leads on four sides, the footprint must be placed at a 45° angle to the transport direction of the printed-circuit board. The footprint must incorporate solder thieves downstream and at the side corners.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Typical dwell time of the leads in the wave ranges from 3 to 4 seconds at 250 °C or 265 °C, depending on solder material applied, SnPb or Pb-free respectively.

A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

#### 14.4 Manual soldering

Fix the component by first soldering two diagonally-opposite end leads. Use a low voltage (24 V or less) soldering iron applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 °C.

When using a dedicated tool, all other leads can be soldered in one operation within 2 to 5 seconds between 270 and 320  $^{\circ}$ C.

### I<sup>2</sup>C-bus controlled multistandard alignment-free IF-PLL for mobile reception

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#### 14.5 Suitability of surface mount IC packages for wave and reflow soldering methods

PACKAGE <sup>(1)</sup>	SOLDERIN	SOLDERING METHOD				
PACKAGE	WAVE	REFLOW <sup>(2)</sup>				
BGA, LBGA, LFBGA, SQFP, SSOP-T <sup>(3)</sup> , TFBGA, VFBGA	not suitable	suitable				
DHVQFN, HBCC, HBGA, HLQFP, HSQFP, HSOP, HTQFP, HTSSOP, HVQFN, HVSON, SMS	not suitable <sup>(4)</sup>	suitable				
PLCC <sup>(5)</sup> , SO, SOJ	suitable	suitable				
LQFP, QFP, TQFP	not recommended <sup>(5)(6)</sup>	suitable				
SSOP, TSSOP, VSO, VSSOP	not recommended <sup>(7)</sup>	suitable				
[ <b>P</b> MFP(8):14U.com	not suitable	not suitable				

#### **Notes**

- 1. For more detailed information on the BGA packages refer to the "(LF)BGA Application Note" (AN01026); order a copy from your Philips Semiconductors sales office.
- 2. All surface mount (SMD) packages are moisture sensitive. Depending upon the moisture content, the maximum temperature (with respect to time) and body size of the package, there is a risk that internal or external package cracks may occur due to vaporization of the moisture in them (the so called popcorn effect). For details, refer to the Drypack information in the "Data Handbook IC26; Integrated Circuit Packages; Section: Packing Methods".
- 3. These transparent plastic packages are extremely sensitive to reflow soldering conditions and must on no account be processed through more than one soldering cycle or subjected to infrared reflow soldering with peak temperature exceeding 217  $^{\circ}$ C  $\pm$  10  $^{\circ}$ C measured in the atmosphere of the reflow oven. The package body peak temperature must be kept as low as possible.
- 4. These packages are not suitable for wave soldering. On versions with the heatsink on the bottom side, the solder cannot penetrate between the printed-circuit board and the heatsink. On versions with the heatsink on the top side, the solder might be deposited on the heatsink surface.
- 5. If wave soldering is considered, then the package must be placed at a 45° angle to the solder wave direction. The package footprint must incorporate solder thieves downstream and at the side corners.
- 6. Wave soldering is suitable for LQFP, TQFP and QFP packages with a pitch (e) larger than 0.8 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.65 mm.
- 7. Wave soldering is suitable for SSOP, TSSOP, VSO and VSSOP packages with a pitch (e) equal to or larger than 0.65 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.5 mm.
- 8. Hot bar or manual soldering is suitable for PMFP packages.

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**TDA9884TS** 

#### 15 DATA SHEET STATUS

LEVEL	DATA SHEET STATUS <sup>(1)</sup>	PRODUCT STATUS <sup>(2)(3)</sup>	DEFINITION
I	Objective data	Development	This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice.
II w.DataShe	Preliminary data	Qualification	This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product.
III	Product data	Production	This data sheet contains data from the product specification. Philips Semiconductors reserves the right to make changes at any time in order to improve the design, manufacturing and supply. Relevant changes will be communicated via a Customer Product/Process Change Notification (CPCN).

#### **Notes**

WW

- 1. Please consult the most recently issued data sheet before initiating or completing a design.
- 2. The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.
- 3. For data sheets describing multiple type numbers, the highest-level product status determines the data sheet status.

#### 16 DEFINITIONS

**Short-form specification** — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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