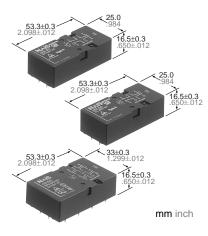




# POLARISED, MONOSTABLE **SAFETY RELAY with** (mechanical linked) forced contacts operation



# **FEATURES**

• Forced operation contacts (2 Form A 2 Form B, 3 Form A 1 Form B) N.O. and N.C. side contacts are connected through a card so that one interacts with the other in movement. In case of a contact welding, the other keeps a min. 0.5mm .020inch contact gap.

## • Independent operation contacts (4 Form A 4 Form B)

Each pair of contacts is free from the main armature and is independent from each other. So if a N.O. pair of contacts are welded, the other 3 N.O. contacts are not effected (operate properly) That

# SF-RELAYS

enables to plan a circuit to detect welding or go back to the beginning condition.

## · Separated chamber structure (2 Form A 2 Form B, 3 Form A 1 Form B, 4 Form A 4 Form B)

N.O. and N.C. side contacts are put in each own space surrounded with a card and a body-separater. That prevents short circuit between contacts, which is caused by their springs welding or damaged.

 UL/CSA, TÜV, SEV approved (UL/CSA, SEV of SF3 pending)

# SPECIFICATIONS

Co	ntad	ct

	SF2	SF3	SF4
t	2 Form A 2 Form B	3 Form A 1 Form B	4 Form A 4 Form B
t resistance, max. drop 6 V DC 1 A)	30 mΩ		
erial	Gold-flashed silver alloy		
Nominal switching capacity	6 A 250 V AC, 6 A 30 V DC		
Max. switching power	1,500 VA, 180 W		
Max. switching voltage	30 V DC, 440 V AC		' AC
Max. carrying current	6 A DC, AC		
Mechanical (at 180 cpm) (resistive)	10 <sup>7</sup>		
Electrical (at 20 cpm)	3×1	10 <sup>₅</sup>	
	t resistance, max. drop 6 V DC 1 A) erial Nominal switching capacity Max. switching power Max. switching voltage Max. carrying current Mechanical (at 180 cpm) (resistive)	t 2 Form A 2 Form A 2 Form B t resistance, max. drop 6 V DC 1 A) erial Gold-f Nominal switching capacity 6 A 250 Max. switching power 1,5 Max. switching voltage 30 V Max. carrying current Mechanical (at 180 cpm) (resistive)	t esistance, max. drop 6 V DC 1 A) erial Gold-flashed silve Nominal switching capacity 6 A 250 V AC, 6 A 3 Max. switching voltage 30 V DC, 440 V Max. carrying current 6 A DC, AC Mechanical (at 180 cpm) (resistive) 10 <sup>7</sup>

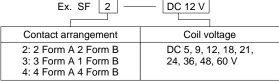
## Coil (at 25°C 77°F)

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### Remarks

- \* Specifications will vary with foreign standards certification ratings.
  \*1 More than 10<sup>5</sup> operations when applying the nominal switching capacity to one side of contact pairs of each Form A contact and Form B contact
- \*2 Measurement at same location as " Initial breakdown voltage " section
- \*3 Detection current: 10mA
- \*4 Excluding contact bounce time
- \*5 Half-wave pulse of sine wave: 11ms; detection time: 10µs
- \*6 Half-wave pulse of sine wave: 6ms
- \*7 Detection time: 10µs
- \*8 Refer to 5. Conditions for operation, transport and storage mentioned in AMBIENT ENVIRONMENT (Page 61).

# ORDERING INFORMATION



UL/CSA, TÜV, SEV approved type is standard (SF2, SF4) TÜV approved type is standard (SF3)

		SF2	SF3	SF4		
Max. operating	speed	180 (	cpm (at no	minal voltage)		
Initial insulation	resistance*2	Min. 1,000 MΩ at 500 V DC				
	Between con- tact sets	2,500 Vrms				
Initial break- down voltage*3	Between open contacts		2,500	Vrms		
	Between con- tact and coil	2,500 Vrms				
Operate time*4 (at nominal volta	age)	Approx	. 17 ms	Approx. 18 ms		
Release time (without diode)*4 (at nominal voltage)		Approx	. 7 ms	Approx. 6 ms		
Temperature rise (at nominal voltage)		Max. 45°C with nominal coil voltage and at 6 A switching current				
Shock	Functional*5	ſ	1 Min. 294 m	n/s² {30 G}		
resistance	Destructive*5	N	1in. 980 m	/s² {100 G}		
Vibration	Functional*7	117.6 m/s <sup>2</sup> {12 G}, 10 to 55 Hz at double amplitude of 2 mm				
resistance	Destructive	117.6 m/s <sup>2</sup> {12 G}, 10 to 55 Hz at double amplitude of 2 mm				
Conditions for oper- ation, transport and temp.		-40°C to +70°C -40°F to +158°F				
storage <sup>*8</sup> (Not freezing and condensing at low temperature)	Humidity	umidity 5 to 85% R.H.				
Unit weight		<b>37</b> g 1	.31 oz	47 g 1.66 oz		

# **TYPICAL APPLICATIONS**

- Signal
- Escalator
- Elevator
- Medical Instruments
- Railway
- Factory Automation

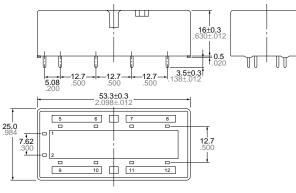
Contact arrangement	Part No.	Nominal voltage, V DC	Pick-up voltage, VDC (max.)	Drop-out voltage, V DC (min.)	Coil resistance Ω (±10%)	Nominal operating current, mA(±10%)	Nominal operating power, mW	Max. allowable voltage, V DC
	SF2-DC5V	5	3.75	0.5	50	100	500	6
	SF2-DC9V	9	6.75	0.9			500	10.8
	SF2-DC12V	12	9	1.2	288	41.7	500	14.4
	SF2-DC18V	18	13.5	1.8			500	21.6
SF2	SF2-DC21V	21	15.75	2.1			500	25.2
	SF2-DC24V	24	14.4	2.4	1.152	20.8	500	28.8
	SF2-DC36V	36	27	3.6			500	43.2
	SF2-DC48V	48	36	4.8	4.608	10.4	500	57.6
	SF2-DC60V	60	45	6.0	7.200	8.3	500	72
	SF3-DC5V	5	3.75	0.5	50	100	500	6
	SF3-DC9V	9	6.75	0.9			500	10.8
	SF3-DC12V	12	9	1.2	288	41.7	500	14.4
	SF3-DC18V	18	13.5	1.8			500	21.6
SF3	SF3-DC21V	21	15.75	2.1			500	25.2
	SF3-DC24V	24	14.4	2.4	1.152	20.8	500	28.8
	SF3-DC36V	36	27	3.6			500	43.2
	SF3-DC48V	48	36	4.8	4.608	10.4	500	57.6
	SF3-DC60V	60	45	6.0	7.200	8.3	500	72
	SF4-DC5V	5	3.75	0.75	50	100	500	6
	SF4-DC9V	9	6.75	0.9			500	10.8
	SF4-DC12V	12	9	1.8	288	41.7	500	14.4
	SF4-DC18V	18	13.5	1.8			500	21.6
SF4	SF4-DC21V	21	15.75	2.1			500	25.2
	SF4-DC24V	24	14.4	3.6	1.152	20.8	500	28.8
	SF4-DC36V	36	27	3.6			500	43.2
	SF4-DC48V	48	36	7.2	4.608	10.4	500	57.6
	SF4-DC60V	60	45	9.0	7.200	8.3	500	72

# TYPES AND COIL DATA (at 20°C 68°F)

# DIMENSIONS

1) SF2



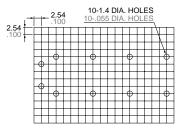


General tolerance:  $\pm 0.3 \pm .012$ 

mm inch Schematic (Bottom view)

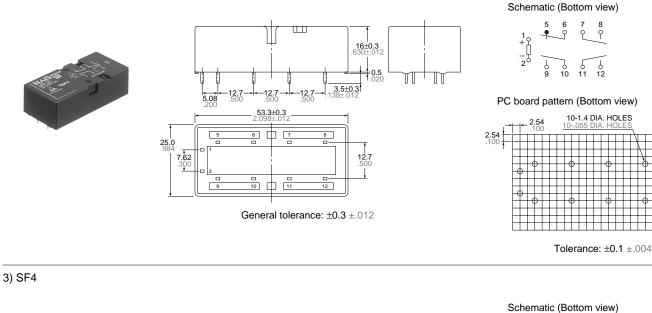
 $\begin{array}{c} 5 & 6 & 7 & 8 \\ 1 & 0 & 0 & 0 \\ -2 & 0 & 0 & 0 \\ 2 & 0 & 0 & 11 & 12 \end{array}$ 

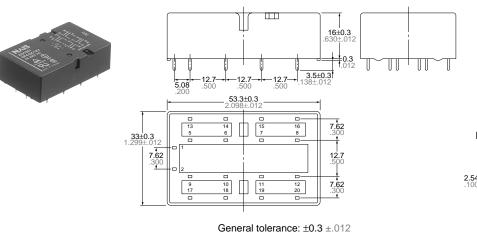
## PC board pattern (Bottom view)



Tolerance:  $\pm 0.1 \pm .004$ 

mm inch





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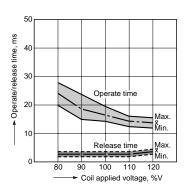
PC board pattern (Bottom view)

↓ <sup></sup>	- •-	<b>2.54</b> .100	<b>18</b> 18	- <b>1.4 [</b> 055 [	DIA. H	HOLE	S
2.54		•	•		0		Image: A line
		•	•		•		
		•			0		
	$\square$	¢	$ \phi $		$ \phi $		+

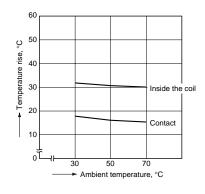
Tolerance:  $\pm 0.1 \pm .004$ 

## **REFERENCE DATA**

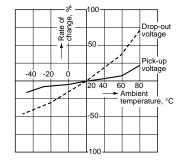
1. Operate/release time



2. Coil temperature rise Coil applied voltage: 120%V Contact switching current: 6A



3. Ambient temperature characteristics Tested sample: SF4-DC12V Quantity: n = 6  $\,$ 



# SAFETY STRUCTURE OF SF RELAYS

This SF relay design ensures that subsequent operations shut down and can automatically return to a safe state when the SF relay suffers overloading and other circuit abnormalities (unforeseen externally caused circuit or device breakdowns, end of life incidents, and noise, surge, and environmental influences) owing to contact welding, spring fusion or, in the worst-case scenario, relay breakdown (coil rupture, faulty operation, faulty return, and fatigue and breakage of the operating spring and return spring), and even in the event of end of life.

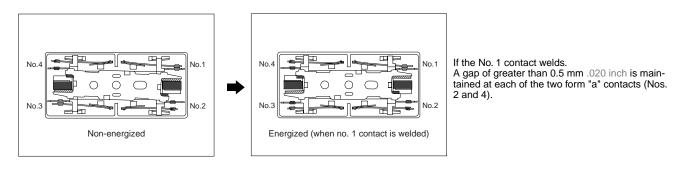
	Structure	Operation
1. Forced operation method (2a2b, 3a1b, 4a4b types)	Min. 0.5 mm .020 inch Contact a Card Card Card Contact b Weld The two contacts "a" and "b" are coupled with the same card. The operation of each contact is regulated by the movement of the other contact.	Even when one contact is welded closed, the other maintains a gap of greater than 0.5 mm .020 inch. In the diagram on the left, the lower contact "b" have welded but the upper con- tact "a" maintain at a gap of greater than 0.5 mm .020 inch. Subsequent contact movement is suspended and the weld can be detected
2. Independent operation method (4a4b type)	Return the external N.O. contacts has welded, the other three contacts have returned owing to the de-energizing of the coil.	Enables design of safety circuits that allow weld detection and return at an early stage. As shown at the top right of the diagram on the left, if the external N.O. contact welds, a 0.5 mm .020 inch gap is maintained. Each of the other contacts returns to N.O. because the coil is no longer energized.
3. Separate chamber method (2a2b, 3a1b, 4a4b types)	In independent chambers, the contacts "a" and "b" are kept apart by a body/card separator or by the card itself. Case separator Card Card Card Contact a Body Separator Contact b	Prevents shorting and fusing of springs and spring failure owing to short-circuit current. As shown on the diagram on the left, even if the operating springs numbered 1 and 2 there is no shorting between "a" and "b" contacts.
4. High-efficiency 4-gap balanced armature structure (2a2b, 3a1b, 4a4b types)	The use of high-efficiency magnetically polarized circuits and 4-gap balanced armature structure means that springs are not required.	Does away with return faults due to fatigue or breakage of the return spring, especially stoppage during contact states.
5. 2a2b contact 3a1b contact 4a4b contact	Structure with independent COM contact of (2a2b), (3a1b), (4a4b) contacts.	Independent COM enables differing pole circuit configurations. This makes it possible to design various kinds of control circuits and safety circuits.

# THE OPERATION OF SF RELAYS (when contacts are welded)

SF relays work to maintain a normal operating state even when overloading or short-circuit currents occur. It is also easy to include weld detection circuits and safety circuits in the design to ensure safety even if contacts weld.

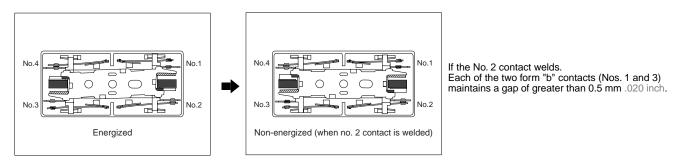
## 1) 2a2b Type

If the form "b" contacts (Nos. 1 and 3) weld, the armature becomes non-operational and the contact gap of the two form "a" contacts is maintained at greater than 0.5 mm .020 inch. Reliable isolation is thus ensured.



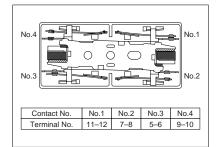
## Form "a" Contact Weld

If the two form "a" contacts (Nos. 2 and 4) weld, the armature becomes non-operational and the gap between the two form "b" contacts is maintained at greater than 0.5 mm .020 inch. Reliable isolation is thus ensured.



## Contact Operation Table

The table below shows the state of the other contacts when the current through the welded form "a" contact is 0 V and the rated voltage is applied through the form "b" contact.



Conta	Stat	State of other contacts					
Contact No.	1	2	3	4			
	1	/	>0.5		>0.5		
Welded terminal	2	>0.5		>0.5			
No.	3		>0.5	$\backslash$	>0.5		
	4	>0.5		>0.5	/		

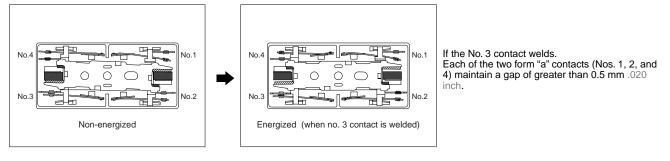
>0.5: contact gap is kept at min. 0.5 mm .020 inch Empty cells: either closed or open

Note: Contact gaps are shown at the initial state. If the contacts change state owing to loading/breaking it is necessary to check the actual loading.

## 2) 3a1b Type

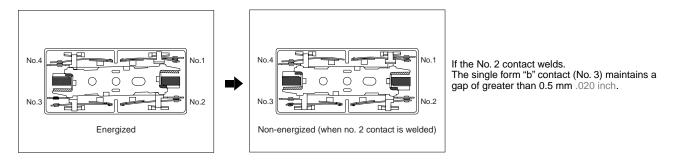
Form "b" Contact Weld

If the form "b" contact (No. 3) welds, the armature becomes non-operational, the contact gaps at the three form "a" contacts are maintained at greater than 0.5 mm .020 inch. Reliable isolation is thus ensured



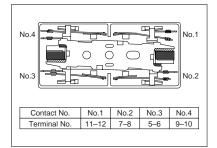
Form "a" Contact Weld

When the form "a" contacts (nos. 1, 2, and 4) weld, the armature remains in a non-returned state and the contact gap at the single form "b" contact is maintained at greater than 0.5 mm .020 inch. Reliable isolation is thus ensured.



## Contact Operation Table

The table below shows the state of the other contacts when the current through the welded form "a" contact is 0 V and the rated voltage is applied through the form "b" contact.



Con	Stat	State of other contacts				
Contact No.	1	2	3	4		
	1	/		>0.5		
Welded terminal	2		$\backslash$	>0.5		
No.	3	>0.5	>0.5		>0.5	
	4			>0.5		

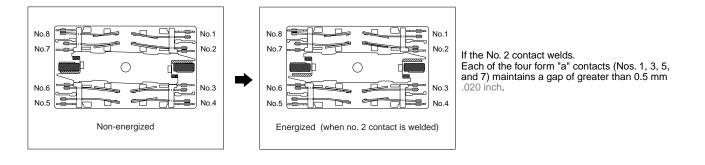
Note: Contact gaps are shown at the initial state. If the contacts change state owing to loading/breaking it is necessary to check the actual loading.

>0.5: contact gap is kept at min. 0.5 mm .020 inch Empty cells: either closed or open

## 3) 4a4b Type

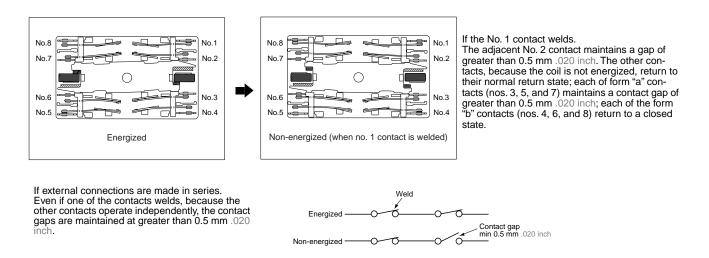
## Internal Contacts Weld

If the internal contacts (nos. 2, 3, 6, and 7) weld, the armature becomes non-operational and the contact gaps of each of the four form "a" contacts are maintained at greater than 0.5 mm .020 inch. Reliable isolation is thus ensured.



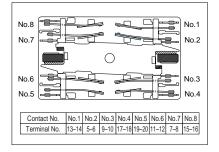
## External Contacts Weld

If the external contacts (nos. 1, 4, 5, and 8) weld, gaps of greater than 0.5 mm .020 inch are maintained between adjacent contacts and the coil returns to an non-energized state.



#### Contact Operation Table

The table below shows the state of the other contacts when the current through the welded form "a" contact is 0 V and the rated voltage is applied through the form "b" contact.



Contac	t No.		State of other contacts						
Contact No. 1		1	2	3	4	5	6	7	8
	1		>0.5	>0.5	≠	>0.5	≠	>0.5	≠
	2	>0.5	$\backslash$	>0.5		>0.5		>0.5	
	3		>0.5	$\backslash$	>0.5		>0.5		>0.5
Welded terminal	4	≠	>0.5	>0.5	$\backslash$	≠	>0.5	≠	>0.5
No.	5	>0.5	≠	>0.5	≠		>0.5	>0.5	≠
	6	>0.5		>0.5		>0.5	$\backslash$	>0.5	
	7		>0.5		>0.5		>0.5	/	>0.5
	8	≠	>0.5	≠	>0.5	≠	>0.5	>0.5	

>0.5: contact gap is kept at min. 0.5 mm .020 inch ≠: contact closed Empty cells: either closed or open

Note: Contact gaps are shown at the initial state. If the contacts change state owing to loading/breaking it is necessary to check the actual loading.

For Cautions for Use, see Relay Technical Information (Page 48 to 76).