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#### **FEATURES**

- Boundary Mode PFC Controller
- Low Input Current THD
- Controlled On-Time PWM
- Zero-Current Detection
- Cycle-by-Cycle Current Limiting
- Leading-Edge Blanking Instead of RC Filtering
- Low Start-up Current (10µA Typical)
- Low Operating Current (4.5mA Typical)
- Feedback Open-Loop Protection
- Programmable Maximum On-Time (MOT)
- Output Over-Voltage Clamping Protection
- Clamped Gate Output Voltage 16.5V

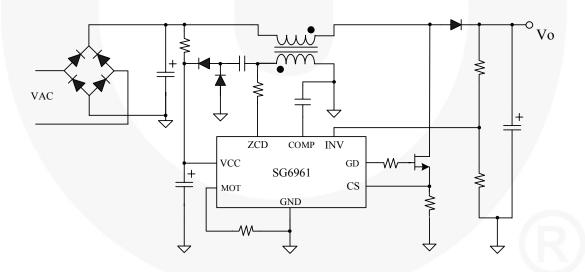
#### **APPLICATIONS**

- Electric Lamp Ballasts
- AC-DC Switching Mode Power Converter
- Open-Frame Power Supplies and Power Adapters
- Flyback Power Converters with ZCS/ZVS

#### **DESCRIPTION**

The SG6961 is an 8-pin boundary mode PFC controller IC intended for controlling PFC pre-regulators. The SG6961 provides a controlled on-time to regulate the output DC voltage and achieve natural power factor correction. The maximum on-time of the external switch is programmable to ensure safe operation during AC brownouts. An innovative multi-vector error amplifier is built in to provide rapid transient response and precise output voltage clamping. A built-in circuit disables the controller if the output feedback loop is opened. The start-up current is lower than  $20\mu A$  and the operating current is under 4.5mA. The supply voltage can be up to 20V, maximizing application flexibility.

#### TYPICAL APPLICATION

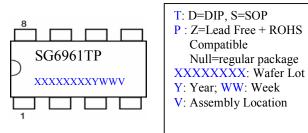


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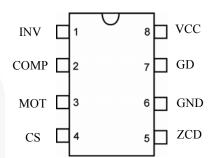


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#### **MARKING DIAGRAMS**



#### **PIN CONFIGURATION**



#### **ORDERING INFORMATION**

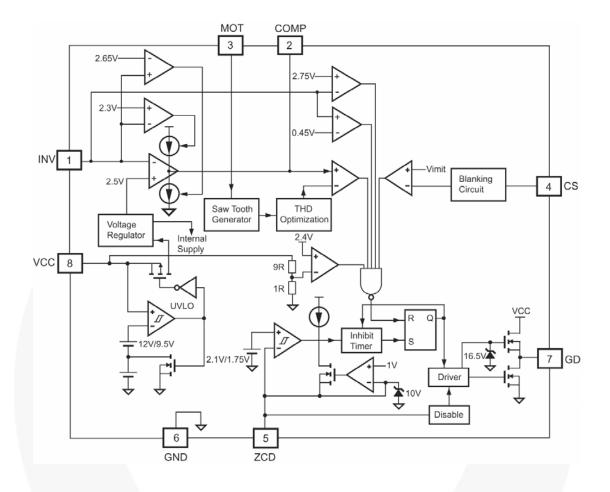
| Part Number | Pb-Free | Package   |
|-------------|---------|-----------|
| SG6961SZ    |         | 8-Pin SOP |
| SG6961DZ    |         | 8-Pin DIP |

#### **PIN DESCRIPTIONS**

| Pin No. | Symbol | Description  |
|---------|--------|--|
| 1       | INV    | Inverting input of the error amplifier. INV is connected to the converter output via a resistive divider. This pin is also used for over-voltage clamping and open-loop feedback protection.   |
| 2       | COMP   | The output of the error amplifier. To create a precise clamping protection, a compensation network between this pin and GND is suggested.  |
| 3       | мот    | A resistor from MOT to GND is used to determine the maximum on-time of the external power MOSFET. The maximum output power of the converter is a function of the maximum on-time.  |
| 4       | cs     | Input to the over-current protection comparator. When the sensed voltage across the sense resistor reaches the internal threshold (0.82V), the switch is turned off to activate cycle-by-cycle current limiting.   |
| 5       | ZCD    | Zero Current Detection. This pin is connected to an auxiliary winding via a resistor to detect the zero crossing of the switch current. When the zero crossing is detected, a new switching cycle is started. If it is connected to GND, the device is disabled. |
| 6       | GND    | The power ground and signal ground. Placing a 0.1µF decoupling capacitor between the VCC and GND pins is recommended.  |
| 7       | GD     | Totem-pole driver output to drive the external power MOSFET. The clamped gate output voltage is 16.5V.   |
| 8       | VCC    | Driver and control circuit supply voltage.   |

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# **BLOCK DIAGRAM**



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#### **ABSOLUTE MAXIMUM RATINGS**

| Symbol            | Parameter   | Parameter |              | Unit |  |
|-------------------|---|-----------|--------------|------|--|
| $V_{DD}$          | DC Supply Voltage*  |           | 25           | V    |  |
| V <sub>HIGH</sub> | GD  |           | -0.3 to 25.0 | V    |  |
| $V_{LOW}$         | Others (INV, COMP, MOT, CS,)                              |           | -0.3 to 7.0  | V    |  |
| V <sub>zcd</sub>  | Input Voltage to ZCD Pin                                  |           | -0.3 to 12.0 | V    |  |
| D                 | DIP-8   |           | 800          | 10/  |  |
| $P_D$             | Power Dissipation   | SOP-8     | 400          | mW   |  |
| D                 | Thermal Desistance (Junetics to Air)                      | DIP-8     | 48.45        | 0000 |  |
| $R_{\theta J-A}$  | Thermal Resistance (Junction-to-Air)                      | SOP-8     | 62.70        | °C/W |  |
| T <sub>J</sub>    | Operating Junction Temperature                            |           | -40 to + 150 | °C   |  |
| T <sub>STG</sub>  | Storage Temperature Range                                 |           | -65 to + 150 | °C   |  |
| TL                | Lead Temperature (Wave Soldering or Infrared, 10 Seconds) |           | 260          | °C   |  |
| ESD               | Electrostatic Discharge Capability, Human Body            | 2.0       | kV           |      |  |
| ESD               | Electrostatic Discharge Capability, Machine Mo            | del       | 200          | V    |  |

<sup>\*</sup> All voltage values, except differential voltages, are given with respect to GND pin.

#### **ELECTRICAL CHARACTERISTICS**

 $V_{CC}$ =15V,  $T_A$ =-20°C~125°C, unless otherwise noted.

# **V<sub>CC</sub> Section**

| Symbol               | Parameter                                | Test Condition   | Min. | Тур. | Max. | Unit |
|----------------------|--|--|------|------|------|------|
| V <sub>OP</sub>      | Continuously Operating Voltage           |  |      |      | 20   | V    |
| V <sub>TH-ON</sub>   | Turn-On Threshold Voltage                |  | 11   | 12   | 13   | V    |
| V <sub>TH-OFF</sub>  | Turn-Off Voltage                         |  | 8.2  | 9.5  | 10.5 | V    |
| I <sub>CC-ST</sub>   | Start-Up Current                         | V <sub>CC</sub> =V <sub>TH-ON</sub> -0.16V               |      | 10   | 20   | μA   |
| I <sub>CC-OP</sub>   | Operating Current                        | $V_{CC}$ =12V, $V_{CS}$ =0, $C_L$ =3r<br>$F_{SW}$ =50KHz | nF,  | 4.5  | 6.0  | mA   |
| V <sub>CC-OVP</sub>  | V <sub>CC</sub> Over-Voltage Protection* |  |      | 24   |      | V    |
| T <sub>VCC-OVP</sub> | V <sub>CC</sub> OVP Debounce Time*       |  |      | 30   |      | μs   |

<sup>\*</sup> Guaranteed by design.

# **Error Amplifier Section**

| Symbol                | Parameter                              | Test Condition                                   | Min. | Тур. | Max. | Unit |
|-----------------------|--|--|------|------|------|------|
| $V_{REF}$             | Reference Voltage                      |  | 2.45 | 2.50 | 2.55 | V    |
| Gm                    | Transconductance*                      | T <sub>A</sub> =25°C                             | 100  | 125  | 150  | μmho |
| $V_{\text{INVH}}$     | Clamp High Feedback Voltage            |  |      | 2.65 | 2.70 | V    |
| $V_{INVL}$            | Clamp Low Feedback Voltage             |  | 2.22 | 2.30 |      | V    |
| $V_{\text{OUT HIGH}}$ | Output High Voltage                    |  | 4.8  |      |      | V    |
| $V_{OZ}$              | Zero Duty Cycle Output Voltage         |  | 1.15 | 1.35 | 1.45 | V    |
| $V_{INV\text{-}OVP}$  | Over-Voltage Protection for INV Input* |  |      | 2.75 |      | V    |
| $V_{INV\text{-}UVP}$  | Under-Voltage Protection for INV Input |  | 0.40 | 0.45 | 0.50 | V    |
|                       | Source Current                         | V <sub>INV</sub> =2.35V, V <sub>COMP</sub> =1.5V | 7    | 20   |      | μΑ   |
| I <sub>COMP</sub>     | Source Current                         | V <sub>INV</sub> =1.5V                           | 450  | 800  |      | μΑ   |
|                       | Sink Current                           | $V_{INV}$ =2.65V, $V_{COMP}$ =5V                 | 10   | 20   |      | μΑ   |

<sup>\*</sup> Guaranteed by design.

<sup>\*</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device.

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# **Current Sense Section (VLIMIT)**

| Symbol           | Parameter   | Test Condition          | Min. | Тур. | Max. | Unit |
|------------------|---|-------------------------|------|------|------|------|
| $V_{PK}$         | Threshold Voltage for Peak Current Limit Cycle–by-Cycle Limit | V <sub>COMP</sub> =5V   | 0.77 | 0.82 | 0.87 | V    |
| $T_{PKD}$        | Propagation Delay   |                         |      |      | 200  | ns   |
| T <sub>BNK</sub> | Leading-Edge Blanking Time                                    | $R_{MOT}$ =24 $k\Omega$ |      | 400  | 550  | ns   |

# **Gate Section**

| Symbol             | Parameter                      | Test Condition                                       | Min. | Тур. | Max. | Unit |
|--------------------|--------------------------------|--|------|------|------|------|
| VZ- <sub>OUT</sub> | Output Voltage Maximum (Clamp) | V <sub>CC</sub> =20V                                 | 15.5 | 16.5 | 17.5 | V    |
| V <sub>OL</sub>    | Output Voltage Low             | V <sub>CC</sub> =15V, I <sub>O</sub> =100mA          |      |      | 1.4  | V    |
| V <sub>OH</sub>    | Output Voltage High            | V <sub>CC</sub> =14V, I <sub>O</sub> =100mA          | 8    |      |      | V    |
| $T_R$              | Rising Time                    | V <sub>CC</sub> =12V, C <sub>L</sub> =3nF, 20~80%    | 50   | 80   | 160  | ns   |
| T <sub>F</sub>     | Falling Time                   | V <sub>CC</sub> =12V, C <sub>L</sub> =3nF,<br>80~20% | 30   | 40   | 70   | ns   |

# **Zero Current Detection Section**

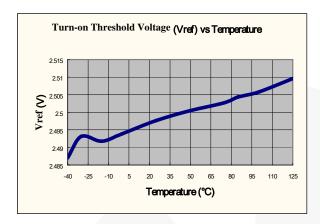
| Symbol                              | Parameter  | Test Condition                                | Min. | Тур. | Max. | Unit |
|-------------------------------------|--|---|------|------|------|------|
| $V_{ZCD}$                           | Input Threshold Voltage Rising Edge              | V <sub>ZCD</sub> Increasing                   | 1.9  | 2.1  | 2.3  | V    |
| H <sub>YS</sub> of V <sub>ZCD</sub> | Threshold Voltage Hysteresis                     | V <sub>ZCD</sub> Decreasing                   | 0.25 | 0.35 | 0.50 | V    |
| V <sub>ZCD-HIGH</sub>               | Upper Clamp Voltage                              | I <sub>ZCD</sub> =3mA                         | 8    | 10   | 12   | ٧    |
| $V_{ZCD\text{-}LOW}$                | Lower Clamp Voltage                              | I <sub>ZCD</sub> =-0.5mA                      | 0    |      |      | V    |
| T <sub>DEAD</sub>                   | Maximum Delay from ZCD to Output Turn-On         | V <sub>COMP</sub> =5V, F <sub>SW</sub> =60KHz | 100  |      | 400  | ns   |
| T <sub>RESTART</sub>                | Restart Time                                     | Output Turned Off by ZCD                      | 300  | 500  | 700  | μs   |
| T <sub>INHIB</sub>                  | Inhibit Time (Maximum Switching Frequency Limit) | $R_{MOT}$ =24 $k\Omega$                       | 1.5  | 2.5  | 3.0  | μs   |
| V <sub>DIS</sub>                    | Disable Threshold                                |   | 200  | 250  | 300  | mV   |
| T <sub>ZCD-DIS</sub>                | ZCD Disable Debounce Time                        | $R_{MOT}$ =24k $\Omega$ , ZCD=100mV           | 800  |      |      | μs   |

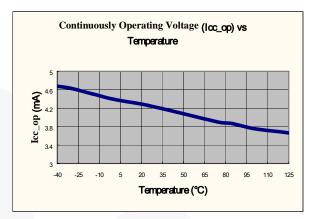
# **Maximum On-Time Section**

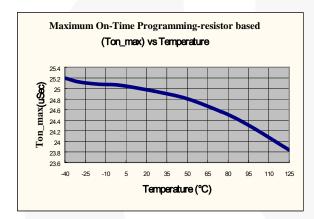
| Symbol              | Parameter                                    | Test Condition   | Min. | Тур. | Max. | Unit |
|---------------------|--|--|------|------|------|------|
| $V_{MOT}$           | MOT Voltage                                  |  | 1.25 | 1.30 | 1.35 | V    |
| T <sub>ON-MAX</sub> | Maximum On-Time Programming (Resistor Based) | $R_{MOT}$ =24k $\Omega$ , $V_{CS}$ =0, $V_{COMP}$ =5 $V$ | 21   | 25   | 27   | μs   |

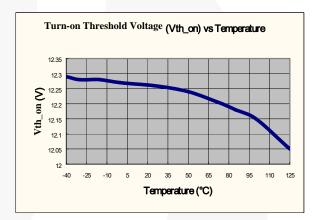
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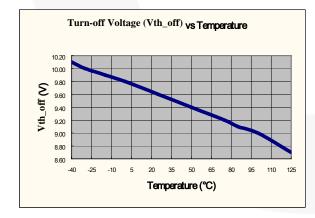
#### **TYPICAL CHARACTERISTICS**

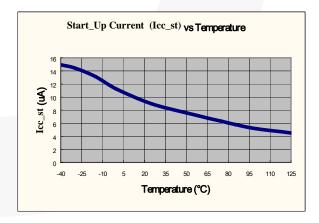




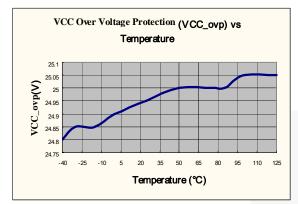


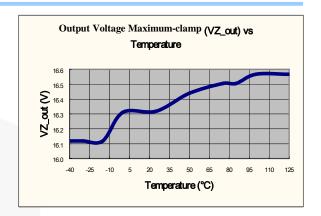


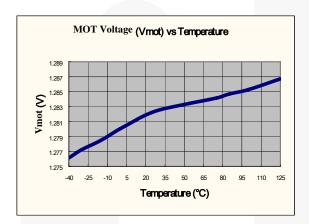


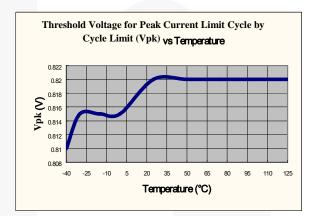














#### **OPERATION DESCRIPTION**

#### **Error Amplifier**

The inverting input of the error amplifier is referenced to INV. The output of the error amplifier is referenced to COMP. The non-inverting input is internally connected to a fixed  $2.5V \pm 2\%$  voltage. The output of the error amplifier is used to determine the on-time of the PWM output and regulate the output voltage. To achieve a low input current THD, the variation of the on-time within one input AC cycle should be very small. A multi-vector error amplifier is built in to provide fast transient response and precise output voltage clamping.

For SG6961, connecting a capacitance, such as  $1\mu F$ , between COMP and GND is suggested. The error amplifier is a transconductance amplifier that converts voltage to current with a  $125\mu mho$ .

#### **Start-Up Current**

Typical start-up current is less than  $20\mu A$ . This ultra-low start-up current allows the usage of a high resistance, low-wattage start-up resistor. For example,  $1M\Omega$  /0.25W start-up resistor and a  $10\mu F/25V$  ( $V_{CC}$  hold-up) capacitor are recommended for an AC-to-DC power adaptor with a wide input range 85 to  $265V_{AC}$ .

#### **Operating Current**

Operating current is typically 4.5mA. The low operating current enables better efficiency and reduces the requirement of  $V_{\rm CC}$  hold-up capacitance.

# **Maximum On-Time Operation**

Given a fixed inductor value and maximum output power, the relation between on-time and line voltage is:

$$t_{on} = \frac{2 \cdot L \cdot P_o}{V_{rms}^2 \cdot \eta} - \dots$$
 (1)

If the line voltage is too low or the inductor value is too high,  $T_{ON}$  is too long. To avoid extra low operating frequency and achieve brownout protection, the maximum value of  $T_{ON}$  is programmable by a resistor,  $R_{I}$ , connected between MOT and GND. A 24k $\Omega$  resistor  $R_{I}$  generates corresponds to 25 $\mu$ s maximum on-time.

$$t_{on(\text{max})} = R_I(k\Omega) \cdot \frac{25}{24} (\mu s) - \dots$$
 (2)

The range of the maximum on-time is designed as  $10 \sim 50 \mu s$ .

#### **Peak Current Limiting**

The switch current is sensed by one resistor. The signal is fed into CS pin and an input terminal of a comparator. A high voltage in the CS pin terminates a switching cycle immediately and cycle-by-cycle current limit is achieved. The designed threshold of the protection point is 0.82V.

#### Leading-Edge Blanking

A turn on spike on CS pin occurs when the power MOSFET is switched on. At the beginning of each switching pulse, the current-limit comparator is disabled for ~400ns to avoid premature termination. The gate drive output cannot be switched off during the blanking period. Conventional RC filtering is not necessary; the propagation delay of current limit protection can be minimized.

#### **Under-Voltage Lockout (UVLO)**

The turn-on and turn-off threshold voltages are fixed internally at 12V/9.5V for SG6961. This hysteresis behavior guarantees a one-shot start-up with proper start-up resistor and hold-up capacitor. With an ultra-low start-up current of  $20\mu A,$  one  $1M\Omega$  resistor,  $R_{IN},$  is sufficient for start-up under low input line voltage,  $85V_{RMS}.$  Power dissipation on  $R_{IN}$  is less than 0.1W even under high line  $(V_{AC}\!\!=\!\!265V_{RMS})$  conditions.

#### **Output Driver**

With low on resistance and high current driving capability, the output driver can drive an external capacitive load larger than 3000pF. Cross conduction current is avoided to minimize heat dissipation, such that efficiency and reliability can be improved. This output driver is internally equipped with clamped by a 16.5V Zener diode.

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#### **Zero Current Detection**

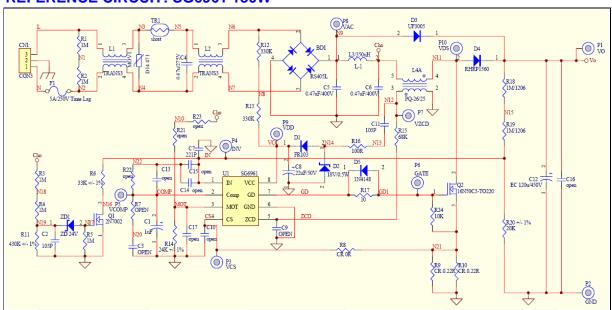
The zero current detection of the inductor is achieved using its auxiliary winding. When the stored energy of the inductor is fully released to output, the voltage on ZCD goes down and a new switching cycle is enabled after a ZCD trigger. The power MOSFET is always turned on with zero inductor current, such that turn-on loss and noise can be minimized. The converter works in boundary mode, such that the peak inductor current is always exactly twice of the average current. Moreover, a natural power factor correction function is achieved with the low-bandwidth on time modulation. An inherent maximum off-time is built in to ensure proper start-up operation. In addition, this pin can be used as a synchronous input.

#### **Noise Immunity**

Noise on the current sense or control signal can cause significant pulse-width jitter, particularly in the boundary-mode operation. Slope compensation and built-in debounce circuitry alleviate this problem. Note that the SG6961 has a single ground pin; therefore, high sink current at the output cannot be returned separately. Good high-frequency or RF layout practices should be followed. Avoid long PCB traces and component leads. Locating compensation and filter components near to the SG6961 and increasing the power MOSFET gate resistance improve performance.

SG6961

# **REFERENCE CIRCUIT: SG6961 180W**



# **BOM**

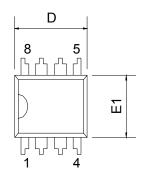
| 2,R3,R4,R5,R18,R19 |
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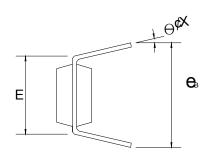


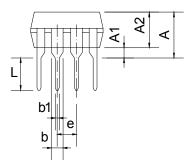
| Component                                | Symbol              |
|--|---------------------|
| TRN0196 PFC Choke 210µH PQ-26/25         | L4A                 |
| Varistor 14ψ 471                         | MOV1                |
| JUMPER WIRE 0.8ψ(mm)                     | JP1,JP2,JP3,JP4,TR1 |
| Rectifier KBL06 4A 600V                  | BD1                 |
| Diode FR103 TAPING                       | D1                  |
| Zener Diode1/2W 18V                      | D2                  |
| Diode UF3005 3A 600V                     | D3                  |
| Diode Fairchild RHRP1560 15A 600V TO-220 | D4                  |
| Diode 1N4148 SMD                         | D5                  |
| ZENER Diode 1/2W 24V SMD                 | ZD1                 |
| Diode 2N7002 SMD                         | Q1                  |
| MOSFET Infineon 16N50C3 16A 500V TO-220  | Q2                  |



# PACKAGE INFORMATION 8PINS-DIP(D)





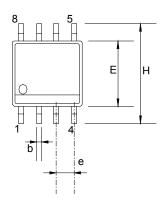


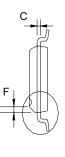
# **Dimensions**

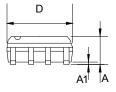
| Symbol     | Millimeter |       |        | Inch  |       |       |
|------------|------------|-------|--------|-------|-------|-------|
| Syllibol   | Min.       | Typ.  | Max.   | Min.  | Typ.  | Max.  |
| A          |            |       | 5.334  |       |       | 0.210 |
| A1         | 0.381      |       |        | 0.015 |       |       |
| A2         | 3.175      | 3.302 | 3.429  | 0.125 | 0.130 | 0.135 |
| b          |            | 1.524 |        |       | 0.060 |       |
| b1         |            | 0.457 |        |       | 0.018 |       |
| D          | 9.017      | 9.271 | 10.160 | 0.355 | 0.365 | 0.400 |
| E          |            | 7.620 |        |       | 0.300 |       |
| E1         | 6.223      | 6.350 | 6.477  | 0.245 | 0.250 | 0.255 |
| е          |            | 2.540 |        |       | 0.100 |       |
| L          | 2.921      | 3.302 | 3.810  | 0.115 | 0.130 | 0.150 |
| ев         | 8.509      | 9.017 | 9.525  | 0.335 | 0.355 | 0.375 |
| $\theta$ ° | 0°         | 7°    | 15°    | 0°    | 7°    | 15°   |

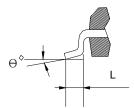
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8PINS-SOP(S)









# **Dimensions**

| Symbol | Millimeter |           |       | Inch  |           |       |
|--------|------------|-----------|-------|-------|-----------|-------|
|        | Min.       | Typ.      | Max.  | Min.  | Typ.      | Max.  |
| Α      | 1.346      |           | 1.752 | 0.053 |           | 0.069 |
| A1     | 0.101      |           | 0.254 | 0.004 |           | 0.010 |
| b      |            | 0.406     |       |       | 0.016     |       |
| С      |            | 0.203     |       |       | 0.008     |       |
| D      | 4.648      |           | 4.978 | 0.183 |           | 0.196 |
| E      | 3.810      |           | 3.987 | 0.150 |           | 0.157 |
| е      | 1.016      | 1.270     | 1.524 | 0.040 | 0.050     | 0.060 |
| F      |            | 0.381X45° |       |       | 0.015X45° |       |
| Н      | 5.791      |           | 6.197 | 0.228 |           | 0.244 |
| L      | 0.406      |           | 1.270 | 0.016 |           | 0.050 |
| θ°     | 0°         |           | 8°    | 0°    |           | 8°    |

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SuperSOT™43

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TinyPWM™
TinyVVire™
µSerDes™
UHC®
VCX™

SuperSOT™-8

SyncFET™

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Global Power Resources

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#### As used herein:

- Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body or (b) support or sustain life, and (c) whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury of the user.
- A critical component in any component of a life support, device, or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

#### PRODUCT STATUS DEFINITIONS

#### Definition of Terms

| Datasheet Identification | Product Status         | Definition   |  |  |
|--------------------------|------------------------|--|--|--|
| Advance Information      | Formative or In Design | This datasheet contains the design specifications for product development. Specifications may change in any manner without notice.   |  |  |
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