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# HA13150A

21 W × 4-Channel BTL Power IC

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ADE-207-107  
1st. Edition

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## Description

HA13150A is a four-channel BTL amplifier IC designed for car audio, featuring high output and low distortion, and applicable to digital audio equipment. It provides 21 W output per channel, with a 14.4 V power supply and at 10% distortion.

## Functions

- Built-in standby circuit
- Built-in muting circuit
- Built-in protection circuits (surge, TSD, and ASO)

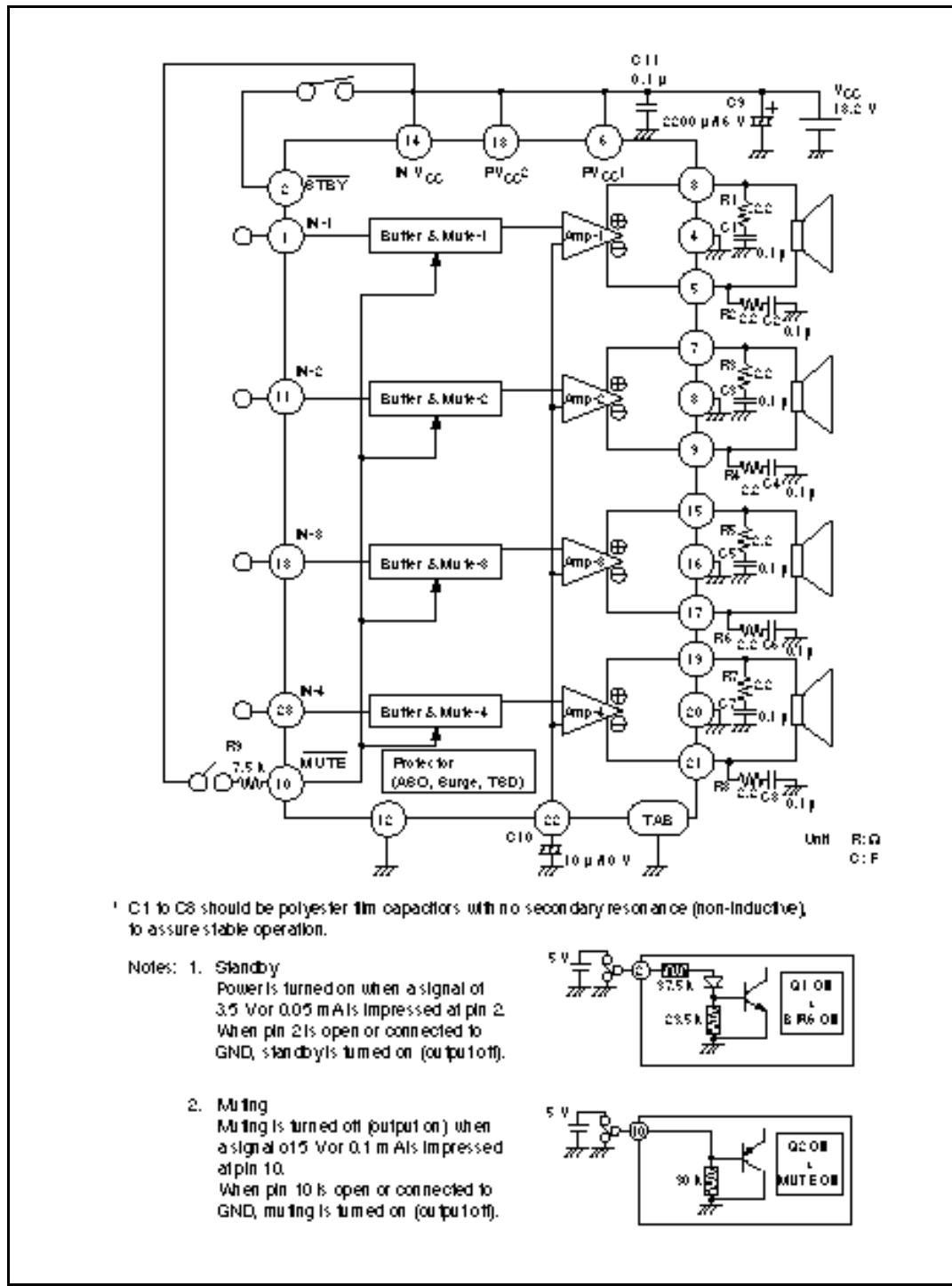
## Features

- Requires few external parts
- Low distortion (total harmonic distortion = 0.01% at 3 W)
- Low noise (at  $R_g = 620 \Omega$ , noise is 0.15 mV (muting off) or 0.1 mV (muting on))
- Popping noise minimized
- Highly reliable current-limiting ASO protector keeps speakers safe from all kinds of trouble. Reliability is further enhanced by a fast-acting thermal shutdown protection circuit with on/off hysteresis.



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## Block Diagram



## Absolute Maximum Ratings (Ta = 25°C)

Item	Symbol	Rating	Unit	Remarks
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Operating supply voltage	V <sub>cc</sub>	18	V
Supply voltage when no signal <sup>*1</sup>	V <sub>cc</sub> (DC)	26	V
Peak supply voltage <sup>*2</sup>	V <sub>cc</sub> (PEAK)	50	V
Output current <sup>*3</sup>	I <sub>o</sub> (PEAK)	4	A
Power dissipation <sup>*4</sup>	P <sub>T</sub>	83	W
Junction temperature	T <sub>j</sub>	150	°C
Operating temperature	T <sub>opr</sub>	-30 to +85	°C
Storage temperature	T <sub>stg</sub>	-55 to +125	°C

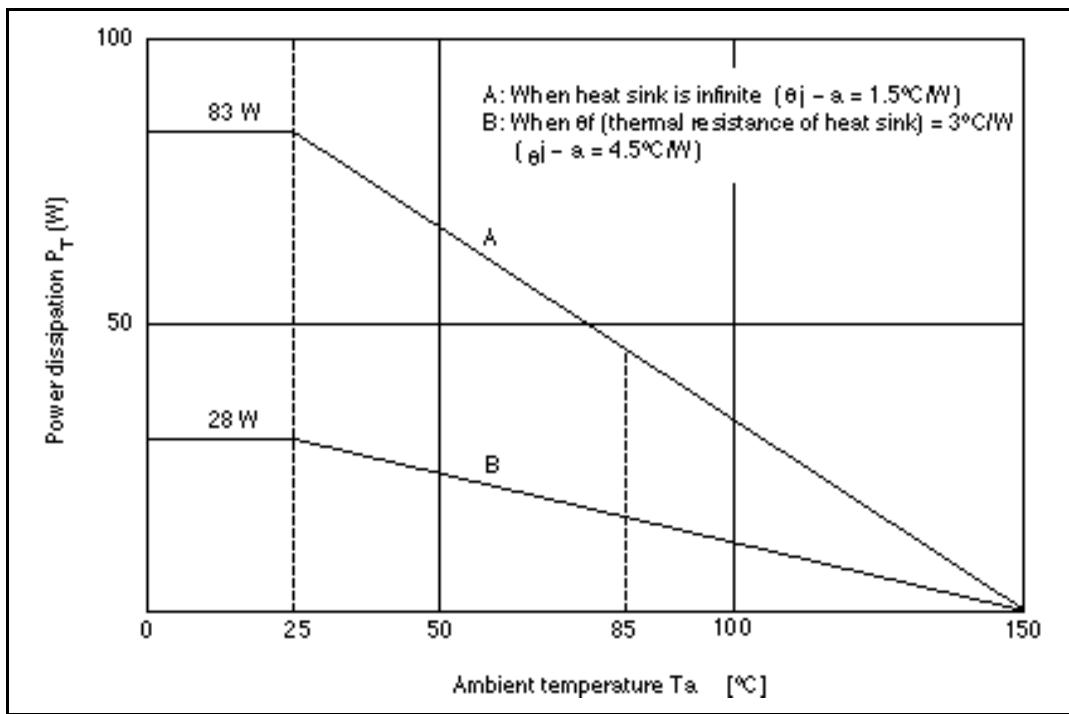
Notes: 1. Tolerance within 30 seconds

2. Tolerance in surge pulse waveform

3. Value per 1 channel

4. Value when attached on the infinite heat sink plate at Ta = 25°C.

The derating curve is as shown in the graph below.



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**Electrical Characteristics** ( $V_{CC} = 13.2$  V,  $f = 1$  kHz,  $R_L = 4\ \Omega$ ,  $R_g = 620\ \Omega$ ,  $T_a = 25^\circ C$ )

Item	Symbol	Min	Typ	Max	Unit	Test Conditions
Current when no signal	Iq1	—	240	—	mA	$V_{in} = 0$
Output offset voltage	Vq	-250	0	+250	mV	
Gain	Gv	30.5	32	33.5	dB	
Gain difference between channels	Gv	-1.5	0	+1.5	dB	
Rated output power	Po	—	18	—	W	$V_{CC} = 13.2$ V $R_L = 4\ \Omega$ , THD = 10%
Max output power	Pomax	—	30	—		$V_{CC} = 13.7$ V $R_L = 4\ \Omega$ , THD = Max
Total harmonic distortion	T.H.D	—	0.01	—	%	$Po = 3$ W
Output noise voltage	WBN	—	0.15	0.5	mVrms	$R_g = 0$ BW = 20 to 20 kHz
Ripple rejection	SVR	—	55	—	dB	$R_g = 600$ $f = 120$ Hz
Channel crosstalk	C.T	—	70	—	dB	$R_g = 600$ $V_{out} = 0$ dBm
Input impedance	Rin	—	25	—	k	
Standby current	Iq2	—	—	200	µA	
Standby control voltage (high)	$V_{STH}$	3.5	—	$V_{CC}$	V	
Standby control voltage (low)	$V_{STL}$	0	—	1.5	V	
Muting control voltage (high)	$V_{MH}$	3.5	—	$V_{CC}$	V	
Muting control voltage (low)	$V_{ML}$	0	—	1.5	V	
Muting attenuation	A <sub>TTM</sub>	—	70	—	dB	$V_{out} = 0$ dBm

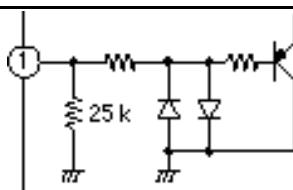
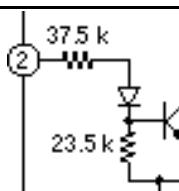
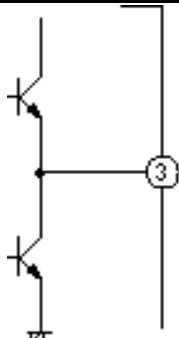
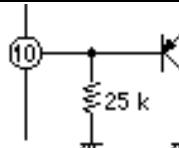
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### Pin Explanation

Pin No.	Symbol	Functions	Input Impedance	DC Voltage	Equivalence Circuit
1	IN1	CH1 INPUT	25 k (Typ)	0 V	
11	IN2	CH2 INPUT			
13	IN3	CH3 INPUT			
23	IN4	CH4 INPUT			
2	STBY	Standby control	90 k (at Trs. cutoff)	—	
3	OUT1 (+)	CH1 OUTPUT	—	V <sub>cc</sub> /2	
5	OUT1 (-)				
7	OUT2 (+)	CH2 OUTPUT			
9	OUT2 (-)				
15	OUT3 (+)	CH3 OUTPUT			
17	OUT3 (-)				
19	OUT4 (+)	CH4 OUTPUT			
21	OUT4 (-)				
10	MUTE	Muting control	25 k (Typ)	—	

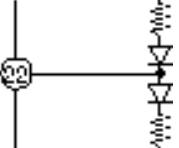
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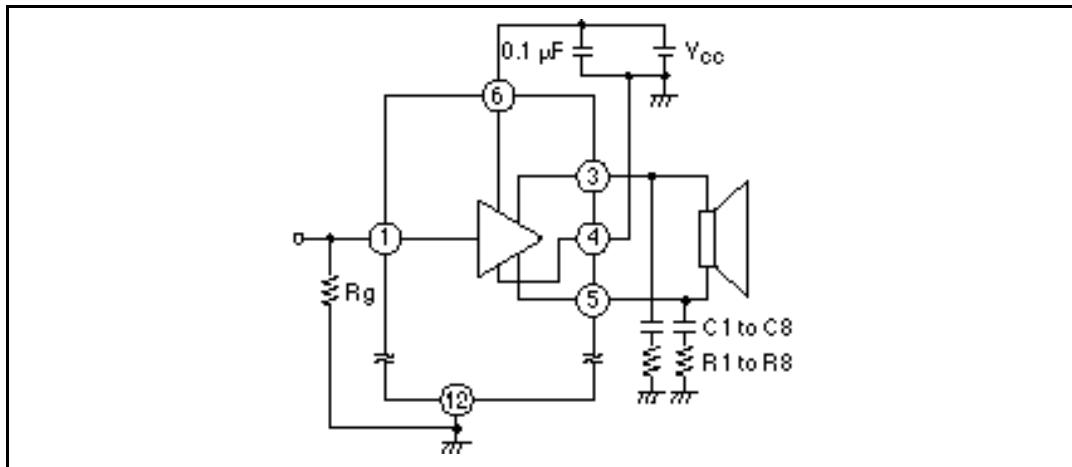
### Pin Explanation (cont)

Pin No.	Symbol	Functions	Input Impedance	DC Voltage	Equivalence Circuit
22	RIPPLE	Bias stability	—	V <sub>cc</sub> /2	
6	PV <sub>cc</sub> 1	Power of output stage	—	V <sub>cc</sub>	—
18	PV <sub>cc</sub> 2	—	—	—	—
14	INV <sub>cc</sub>	Power of input stage	—	V <sub>cc</sub>	—
4	CH1 GND	CH1 power GND	—	—	—
8	CH2 GND	CH2 power GND	—	—	—
16	CH3 GND	CH3 power GND	—	—	—
20	CH4 GND	CH4 power GND	—	—	—
12	IN GND	Input signal GND	—	—	—

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### Point of Application Board Design

1. Notes on Application board's pattern design
  - For increasing stability, the connected line of V<sub>CC</sub> and OUTGND is better to be made wider and lower impedance.
  - For increasing stability, it is better to place the capacitor between V<sub>CC</sub> and GND (0.1 μF) close to IC.
  - For increasing stability, it is better to place C1 to C8 and R1 to R8, which are for stopping oscillation, close to IC.
  - It is better to place the grounding of resistor (R<sub>g</sub>), between input line and ground, close to INGND (Pin 12) because if OUTGND is connected to the line between R<sub>g</sub> and INGND, THD will become worse due to current from OUTGND.



**Figure 1 Notes on Application Board's Pattern Design**

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### 2. How to reduce the popping noise by Muting circuit

At normal operating circuit, Muting circuit operates at high speed under 1  $\mu$ s.

In case popping noise becomes a problem, it is possible to reduce the popping noise by connecting capacitor, which determines the switching time constant, between pin 10 and GND. (Following figure 2)

We recommend value of capacitor greater than 1  $\mu$ F.

Also transitional popping noise can be reduced sharply by muting before V<sub>CC</sub> and Standby are ON/OFF.

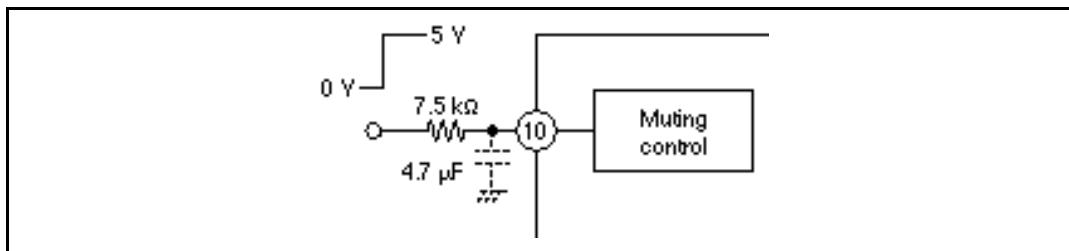
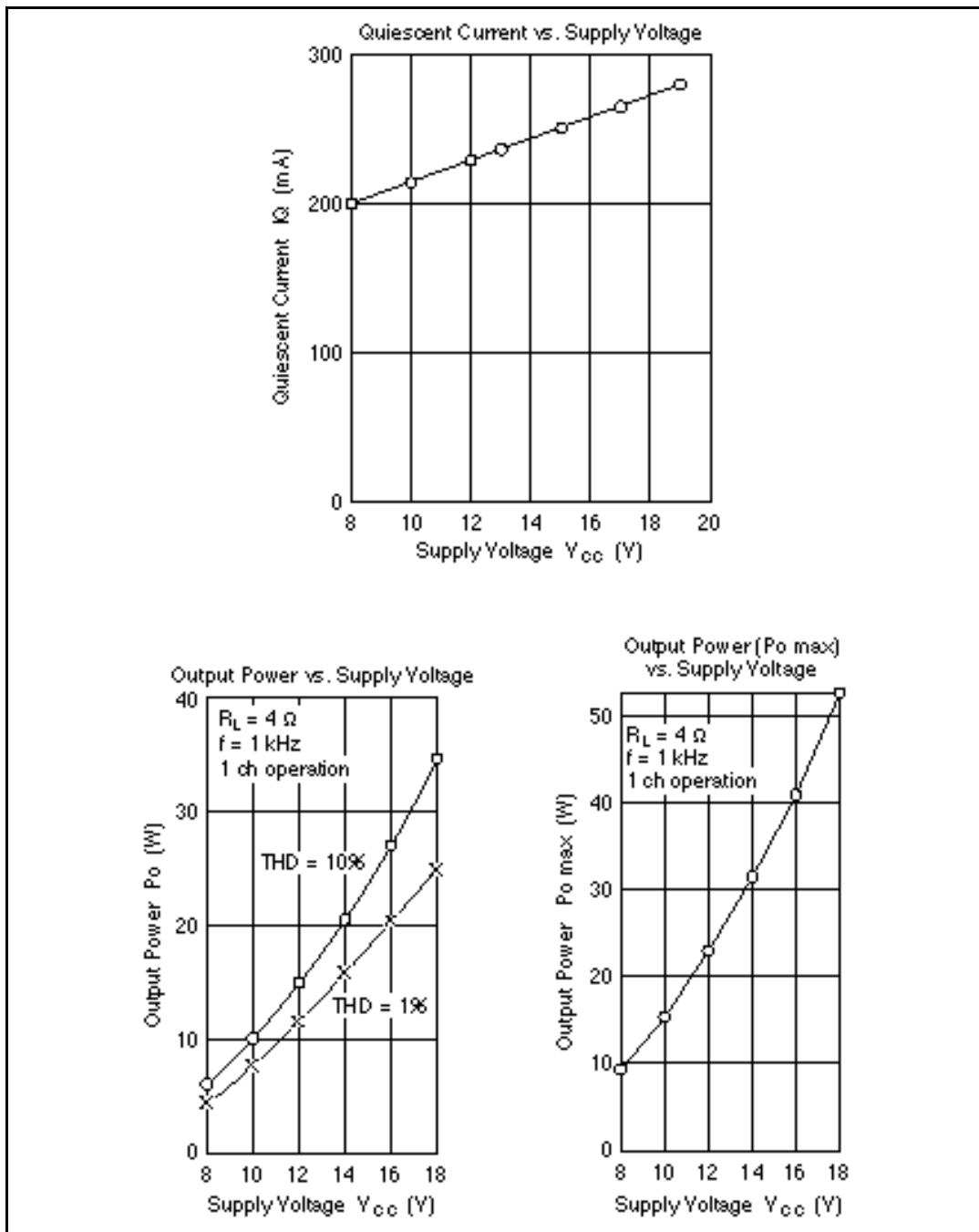


Figure 2 How to use Muting Circuit

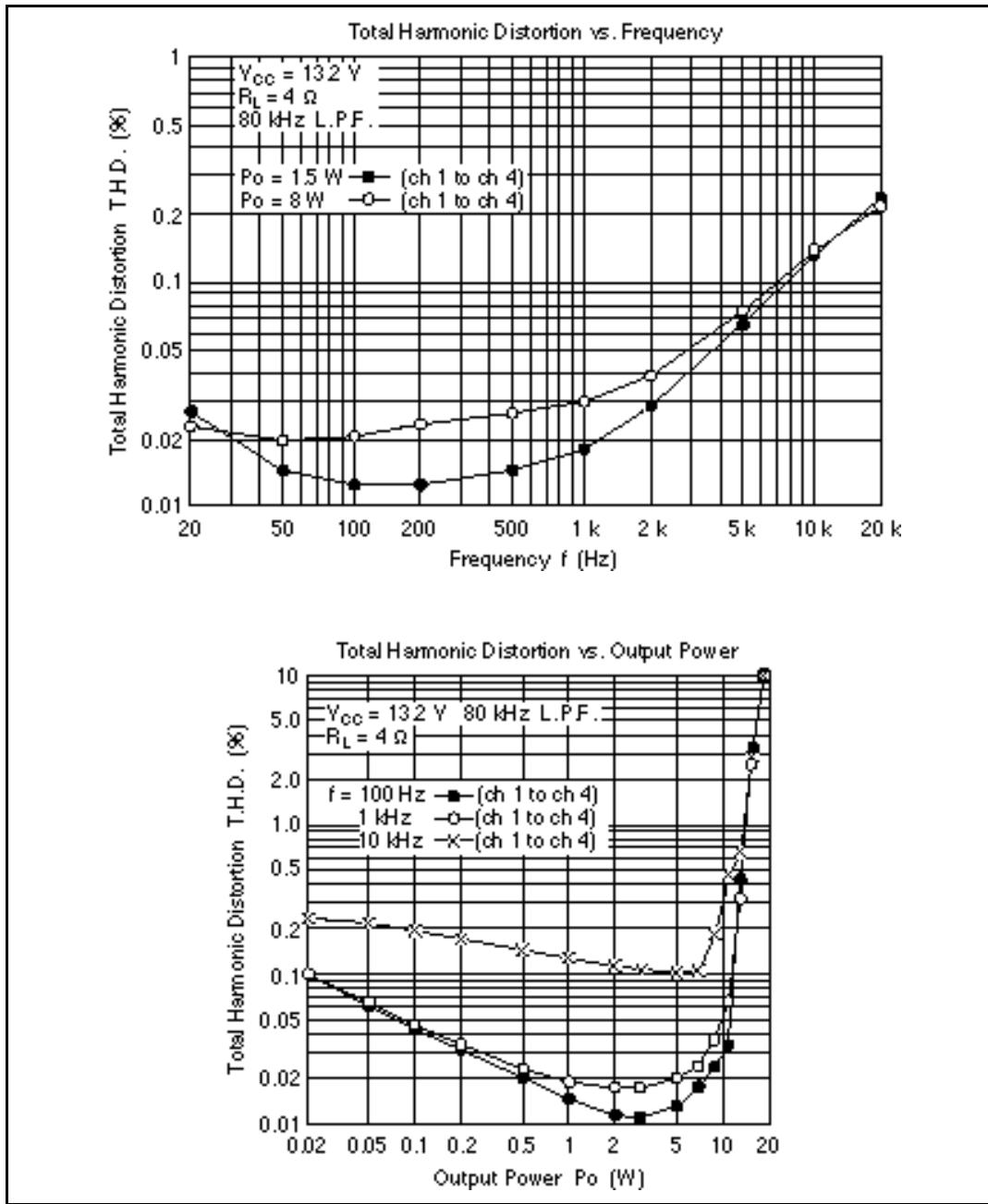
Table 1 Muting ON/OFF Time

C ( $\mu$ F)	ON Time	OFF Time
nothing	under 1 $\mu$ s	under 1 $\mu$ s
0.47	2 ms	2 ms
4.7	19 ms	19 ms

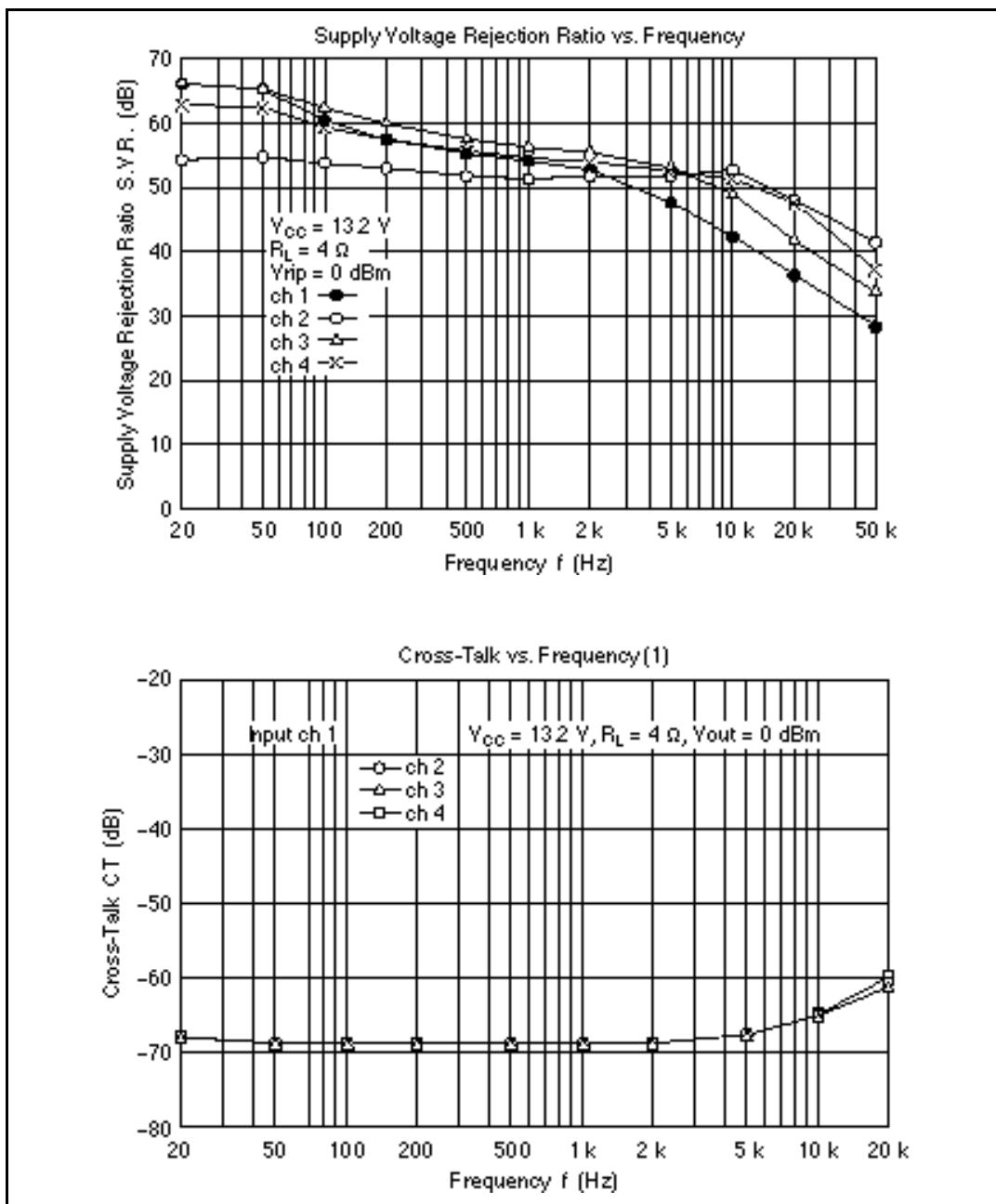
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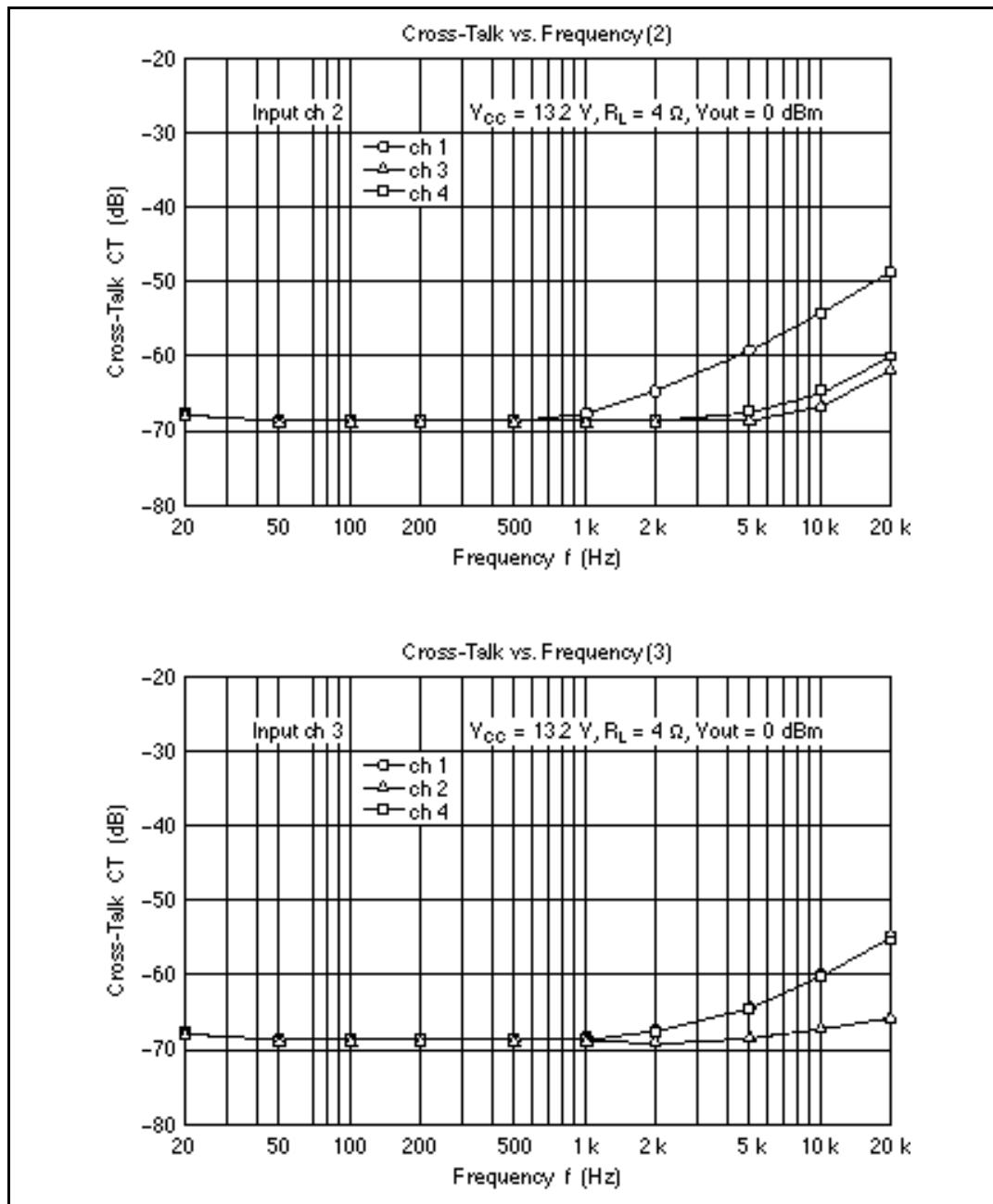
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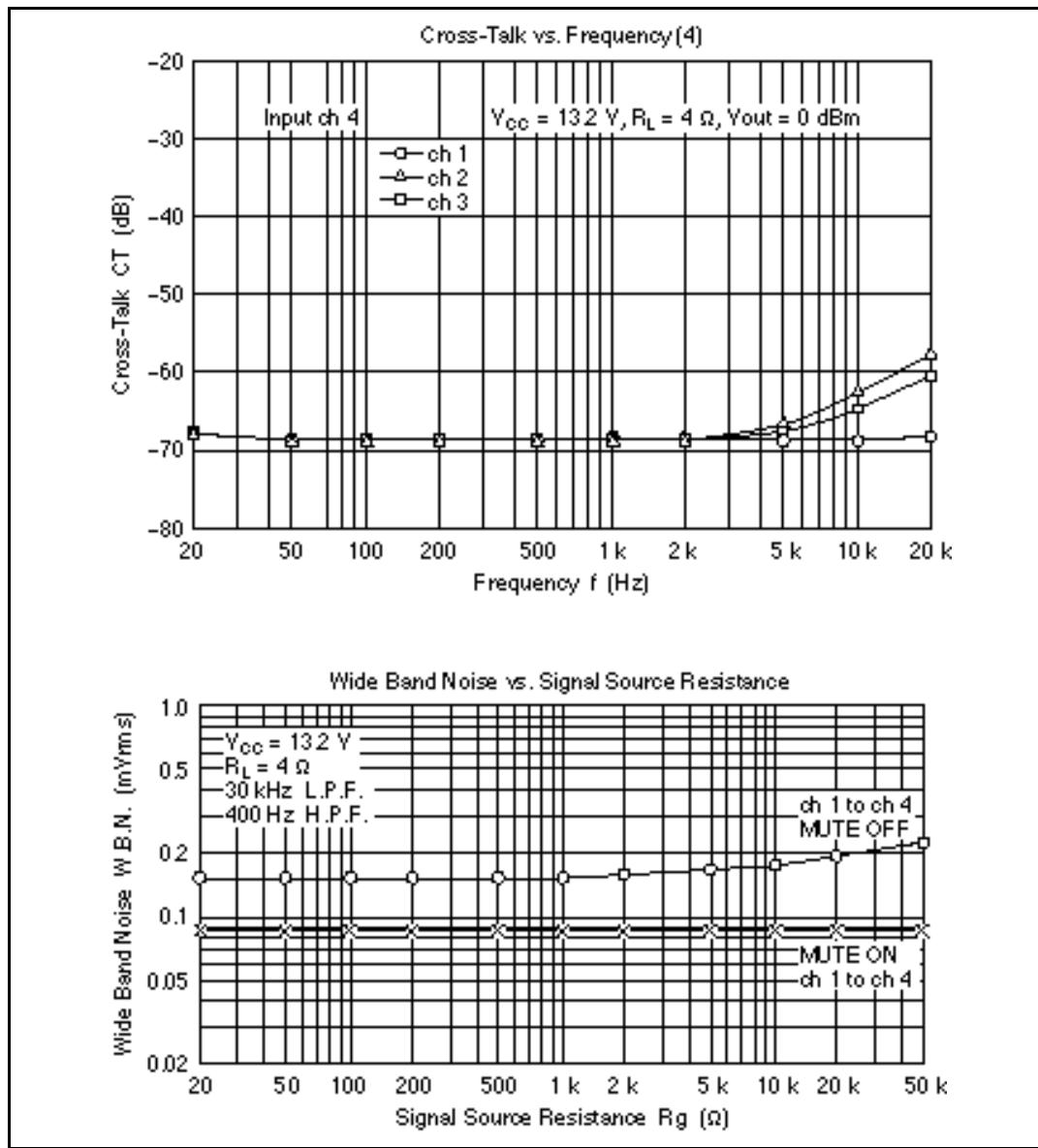
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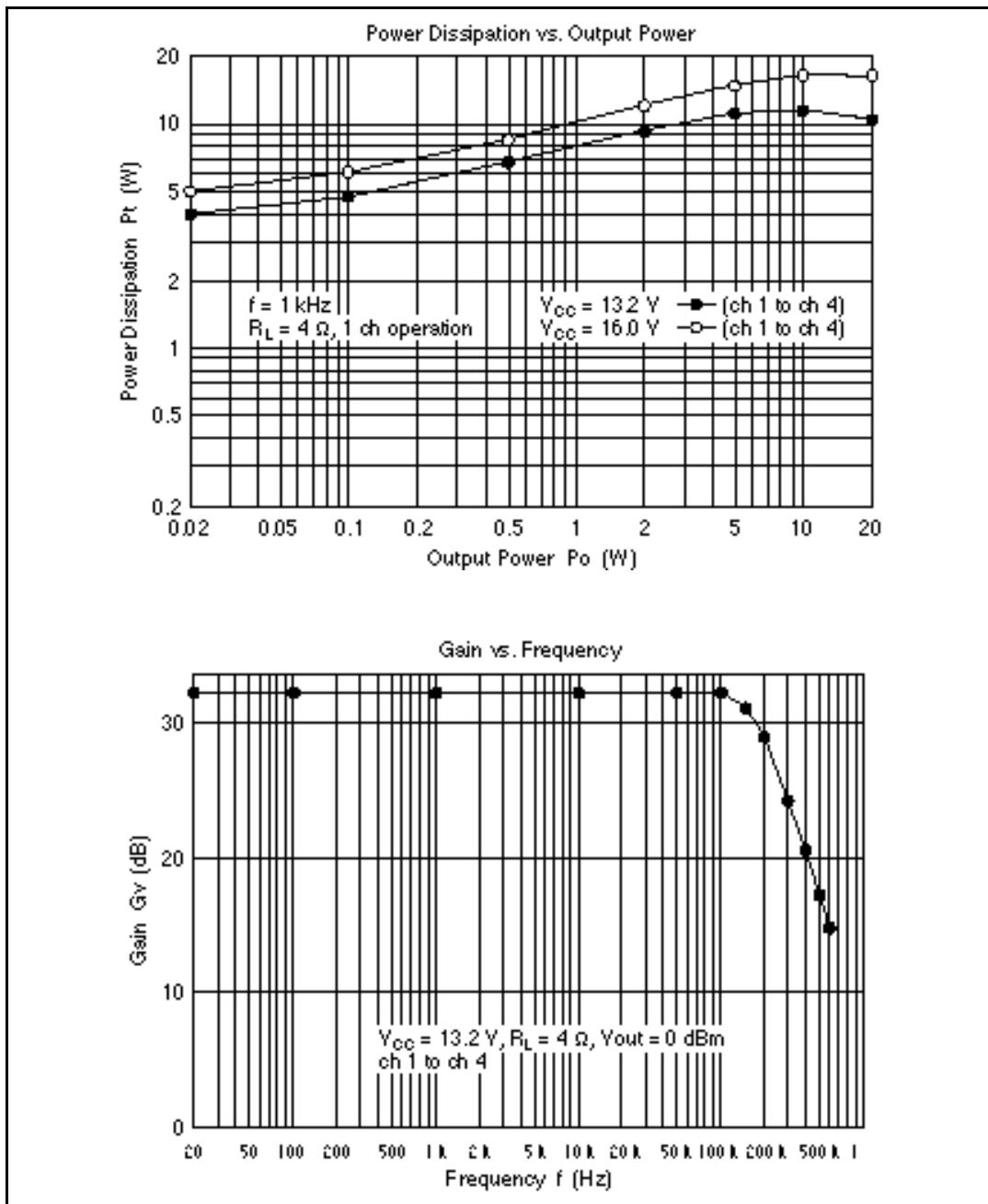
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