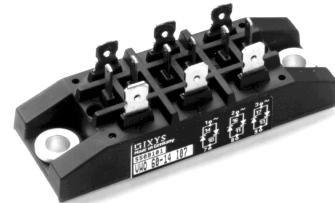
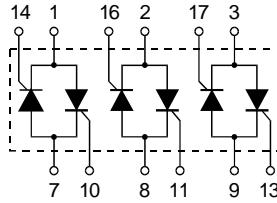


Three Phase AC Controller Modules

I_{RMS} = 3x 60 A
V_{RRM} = 800-1600 V

Preliminary data

V _{RSM}	V _{RRM}	Type
V _{DSM}	V _{DRM}	
V	V	
800	800	VWO 60-08io7
1200	1200	VWO 60-12io7
1400	1400	VWO 60-14io7
1600	1600	VWO 60-16io7



Symbol	Test Conditions		Maximum Ratings	
I _{RMS}	T _K = 85°C, 50 - 400 Hz (per phase)		60	A
I _{TRMS}	T _{VJ} = T _{VJM}		43	A
I _{TAVM}	T _K = 85°C; (180° sine)		27	A
I _{TSM}	T _{VJ} = 45°C; V _R = 0	t = 10 ms (50 Hz), sine t = 8.3 ms (60 Hz), sine	550	A
	T _{VJ} = T _{VJM} V _R = 0	t = 10 ms (50 Hz), sine t = 8.3 ms (60 Hz), sine	600	A
I ² t	T _{VJ} = 45°C V _R = 0	t = 10 ms (50 Hz), sine t = 8.3 ms (60 Hz), sine	500	A
	T _{VJ} = T _{VJM} V _R = 0	t = 10 ms (50 Hz), sine t = 8.3 ms (60 Hz), sine	550	A
I ² t	T _{VJ} = 45°C V _R = 0	t = 10 ms (50 Hz), sine t = 8.3 ms (60 Hz), sine	1520	A ² s
	T _{VJ} = T _{VJM} V _R = 0	t = 10 ms (50 Hz), sine t = 8.3 ms (60 Hz), sine	1520	A ² s
(di/dt) _{cr}	T _{VJ} = T _{VJM} f = 50 Hz, t _p = 200 μs V _D = 2/3 V _{DRM} I _G = 0.45 A di _G /dt = 0.45 A/μs	repetitive, I _T = 25 A non repetitive, I _T = I _{TAVM}	1250	A ² s
			1250	A ² s
(dv/dt) _{cr}	T _{VJ} = T _{VJM} ; R _{DK} = ∞; method 1 (linear voltage rise)	V _{DR} = 2/3 V _{DRM}	1000	V/μs
P _{GM}	T _{VJ} = T _{VJM} I _T = I _{TAVM}	t _p = 30 μs t _p = 300 μs	10 5 0.5	W
P _{GAVM}			10	V
V _{RGM}			-40...+125	°C
T _{VJ}			125	°C
T _{VJM}			-40...+125	°C
T _{stg}				
V _{ISOL}	50/60 Hz, RMS I _{ISOL} ≤ 1 mA	t = 1 min t = 1 s	2500 3000	V~
M _d	Mounting torque (M5) (10-32 UNF)		5 ± 15 % 44 ± 15 %	Nm lb.in.
Weight	typ.		110	g

Data according to IEC 60747 refer to a single thyristor/diode unless otherwise stated.
 IXYS reserves the right to change limits, test conditions and dimensions

Symbol	Test Conditions	Characteristic Values		
I_D, I_R	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	≤	5	mA
V_T	$I_T = 45 \text{ A}; T_{VJ} = 25^\circ\text{C}$	≤	1.45	V
V_{TO}	For power-loss calculations only	0.85	11	V mΩ
r_T				
V_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	≤	1.5	V
	$T_{VJ} = -40^\circ\text{C}$	≤	1.6	V
I_{GT}	$V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$	≤	100	mA
	$T_{VJ} = -40^\circ\text{C}$	≤	200	mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	≤	0.2	V
I_{GD}		≤	5	mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$	≤	450	mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$	≤	200	mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$	≤	2	μs
t_q	$T_{VJ} = T_{VJM}; I_T = 20 \text{ A}, t_p = 200 \mu\text{s}; di/dt = -10 \text{ A}/\mu\text{s}$ $V_R = 100 \text{ V}; dv/dt = 15 \text{ V}/\mu\text{s}; V_D = 2/3 V_{DRM}$	typ.	150	μs
R_{thJC}	per thyristor; sine 180°el	0.9	K/W	
	per module	0.15	K/W	
R_{thJK}	per thyristor; sine 180°el	1.1	K/W	
	per module	0.183	K/W	
d_s	Creeping distance on surface	16.1	mm	
d_A	Creepage distance in air	6.0	mm	
a	Max. allowable acceleration	50	m/s ²	

Dimensions in mm (1 mm = 0.0394")

