

# SHINDENGEN

## Stepping Motor Driver ICs

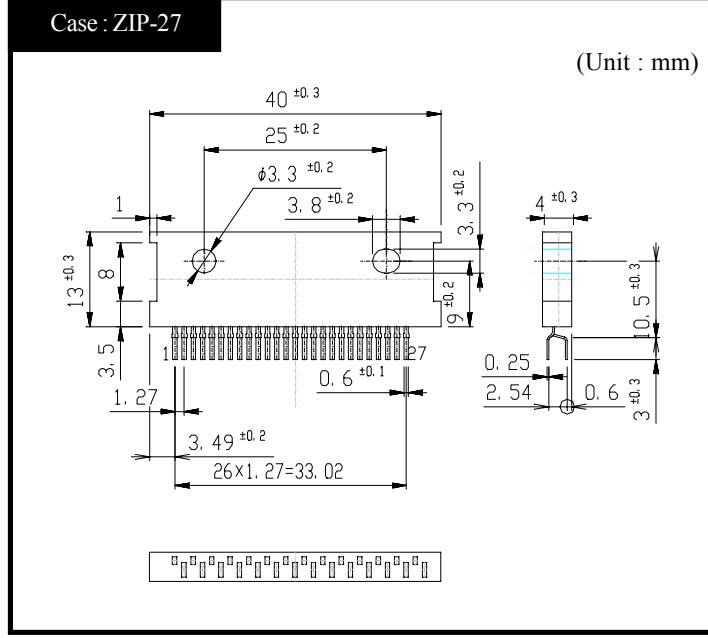
MTD Series

### MTD2003

#### FEATURES

- Constant-current chopping function  
(Frequency fixed, separate-oscillation)
- 4-phase input  
(with inhibit for simultaneously turn ON)
- Current levels can be selected in  
2 bit digital signal
- A noise cancel function is provided  
(No externally attached filter needed)
- Protection for penetration current
- Built-in flywheel diodes

#### OUTLINE DIMENSIONS



#### RATINGS

##### ● Absolute Maximum Ratings (Ta=25°C)

Item	Symbol	Ratings	Unit
Output Voltage	V <sub>CEO(SUS)</sub>	30	V
Output Current	I <sub>O</sub>	1.2	A
Logic Supply Voltage	V <sub>CC</sub>	0~6	V
Logic Input Voltage	V <sub>IN</sub>	0~V <sub>CC</sub>	V
Total Power Dissipation	P <sub>T</sub>	5	W
Junction Temperature	T <sub>j</sub>	150	°C
Storage Temperature	T <sub>stg</sub>	-40~150	°C

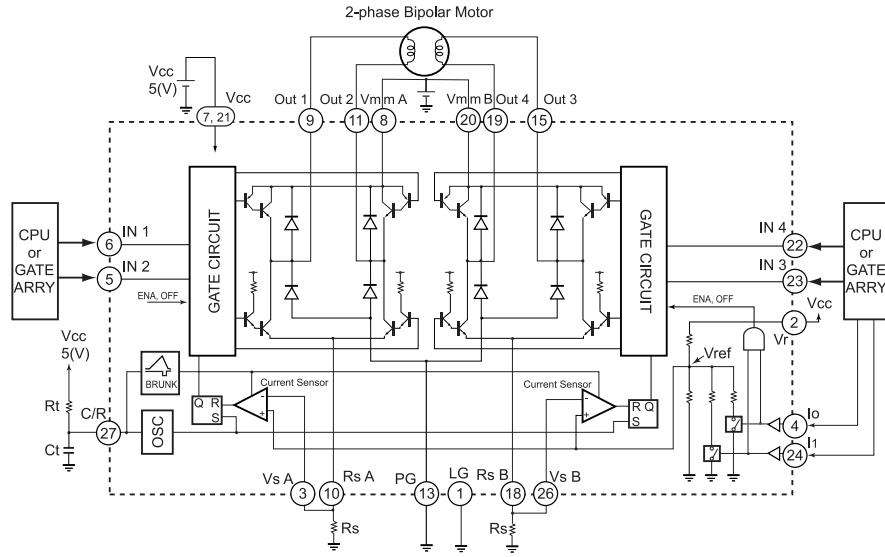
##### ● Electrical Characteristics (Ta=25°C)

Item	Symbol	Test Conditions	min.	typ.	max.	Unit
Output Saturation Voltage(Upper side)	V <sub>CE</sub> (sat)H	I <sub>O</sub> =1.0A		1.2	1.4	V
Output Saturation Voltage(Lower side)	V <sub>CE</sub> (sat)L	I <sub>O</sub> =1.0A		0.7	1.0	V
Output Leakage Current(Upper side)	I <sub>rH</sub>	V <sub>mm</sub> =30V,V <sub>out</sub> =0V		10	μA	
Output Leakage Current(Lower side)	I <sub>rL</sub>	V <sub>out</sub> =30V,V <sub>RS</sub> =0V		10	μA	
Logic Supply Current(Standby)	I <sub>CC</sub> (OFF)	V <sub>CC</sub> =5V,IN="H,H" or "L,L"		15	25	mA
Logic Supply Current(All Circuit ON)	I <sub>CC</sub> (ON)	V <sub>CC</sub> =5V		50	65	mA
Input High Voltage	V <sub>INH</sub>	V <sub>CC</sub> = 5V	2.7		Vcc	V
Input Low Voltage	V <sub>INL</sub>	V <sub>CC</sub> = 5V	GND	0.6		V
Logic High Input Current	I <sub>INH</sub>	V <sub>CC</sub> = 5V,V <sub>IN</sub> =5V		10	μA	
Logic Low Input Current	I <sub>INL</sub>	V <sub>CC</sub> = 5V,V <sub>IN</sub> =0V		-3	-20	μA
I <sub>O,I</sub> "H"Input Voltage	V(I <sub>O,I</sub> )H	V <sub>CC</sub> =5V	2.7		Vcc	V
I <sub>O,I</sub> "L"Input Voltage	V(I <sub>O,I</sub> )L	V <sub>CC</sub> =5V	GND	0.6		V
I <sub>O,I</sub> "H"Input Current	I(I <sub>O,I</sub> )H	V <sub>CC</sub> =5V,V(I <sub>O,I</sub> )=5V		10	μA	
I <sub>O,I</sub> "L"Input Current	I(I <sub>O,I</sub> )L	V <sub>CC</sub> =5V,V(I <sub>O,I</sub> )=0V		-75	-100	μA
Current Sensor Threshold(100%)	V <sub>S1</sub>	V <sub>CC</sub> =V <sub>r</sub> =5V,V(I <sub>O</sub> )=0V,V(I <sub>L</sub> )=0V	0.475	0.5	0.525	V
Current Sensor Threshold(70%)	V <sub>S2</sub>	V <sub>CC</sub> =V <sub>r</sub> =5V,V(I <sub>O</sub> )=5V,V(I <sub>L</sub> )=0V	0.322	0.35	0.378	V
Current Sensor Threshold(33%)	V <sub>S3</sub>	V <sub>CC</sub> =V <sub>r</sub> =5V,V(I <sub>O</sub> )=0V,V(I <sub>L</sub> )=5V	0.153	0.17	0.187	V
Reference Input Current	I <sub>ref</sub>	V <sub>CC</sub> =5V,V <sub>r</sub> =5V		500	650	μA
Input Current(Current Sensor)	I <sub>sense</sub>	V <sub>CC</sub> =5V,V <sub>s</sub> =0V		-1	-10	μA
Pulse Blanking Time	t <sub>b</sub>	V <sub>CC</sub> =5V,C <sub>t</sub> =3300pF		1.55		μs

# Stepping Motor Driver ICs

**MTD2003**

## ● Equivalent Circuit · Basic Application Circuit



## ● Pin Assignment

Pin 27	C/R
Pin 26	V <sub>s</sub>
Pin 25	NC
Pin 24	I <sub>o</sub>
Pin 23	IN 3
Pin 22	IN 4
Pin 21	V <sub>cc</sub>
Pin 20	V <sub>m</sub>
Pin 19	Out 4
Pin 18	R <sub>s</sub>
Pin 17	NC
Pin 16	NC
Pin 15	Out 3
Pin 14	NC
Pin 13	PG
Pin 12	NC
Pin 11	Out 2
Pin 10	R <sub>s</sub>
Pin 9	Out 1
Pin 8	V <sub>m</sub>
Pin 7	V <sub>cc</sub>
Pin 6	IN 1
Pin 5	IN 2
Pin 4	I <sub>o</sub>
Pin 3	V <sub>s</sub>
Pin 2	V <sub>ref</sub>
Pin 1	GND

○ MTD 2003 102 ON

Package  
ZIP-27

## ● True Table

IN 1 or 4	IN 2 or 3	Out 1 or 4	Out 2 or 3
L	L	OFF	OFF
L	H	L	H
H	L	H	L
H	H	OFF	OFF

## ● Recommended Parts Value

Symbol	Recommended Value	Unit
R <sub>s</sub>	0.68	Ω
R <sub>t</sub>	18	kΩ
C <sub>t</sub>	3300	pF
V <sub>r</sub>	V <sub>cc</sub>	V

## ● True Table for Current Chopping Level

I <sub>o</sub>	I <sub>1</sub>	Current Level (%)	V <sub>ref</sub> (V) (V <sub>r</sub> =5V)
L	L	100	0.5±5%
H	L	70	0.35±8%
L	H	33	0.17±10%
H	H	0	

## ● Setting of Output Current and Chopping Frequency

Fig.1 shows constant current chopping wave form.

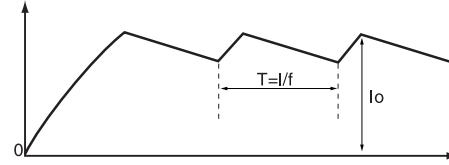
Output Current setting

$$I_o(100\%) = \frac{V_r}{10 \cdot R_s} - 0.015$$

Chopping Frequency Setting

$$f = \frac{1}{0.72 \cdot C_t \cdot R_t}$$

Fig.1 Constant current wave form (Motor current / phase)



## ● Recommended Operating Conditions (Ta=25°C)

Item	Symbol	min.	typ.	max.	Unit
Motor Supply Voltage	V <sub>m</sub>			27	V
Output Current	I <sub>o</sub>			1	A
Logic Supply Voltage	V <sub>cc</sub>	4.75		5.25	V
Chopping Frequency	f <sub>chop</sub>		20		kHz
Operating Temperature	Top	-25		120	°C