October 2010

Motion-SPM[™]

FAIRCHILD

SEMICONDUCTOR®

FNA41560/B2 Smart Power Module

Features

- 600V-15A 3-phase IGBT inverter bridge including control ICs for gate driving and protection
- Easy PCB layout due to built-in bootstrap diode and V_S output
- Divided negative dc-link terminals for inverter current sensing applications
- · Single-grounded power supply due to built-in HVIC
- · Built-in thermistor for over-temperature monitoring
- Isolation rating of 2000Vrms/min.

Applications

- AC 100V $\sim 253V\,$ three-phase inverter drive for small power ac motor drives
- Home appliances applications like air conditioner and refrigerator

General Description

It is an advanced motion-smart power module (Motion-SPMTM) that Fairchild has newly developed and designed to provide very compact and high performance ac motor drives mainly targeting low-power inverter-driven application like air conditioner and refrigerator. It combines optimized circuit protection and drive matched to low-loss IGBTs. System reliability is further enhanced by the integrated under-voltage lock-out protection, short-circuit protection, and temperature monitoring. The high speed built-in HVIC provides opto-coupler-less single-supply IGBT gate driving capability that further reduce the overall size of the inverter system design. Each phase current of inverter can be monitored separately due to the divided negative dc terminals.

Additional Information

For further infomation, please see AN-9070 and FEB305-001 in http://www.fairchildsemi.com



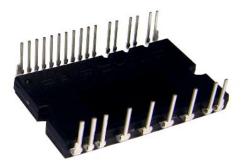
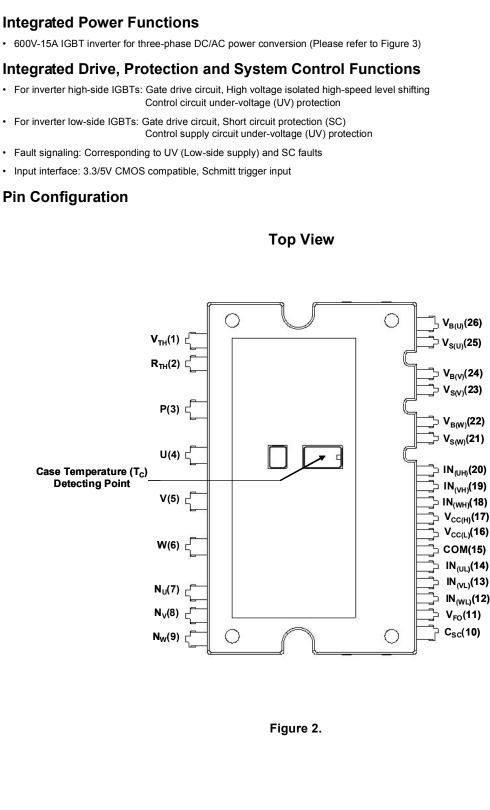
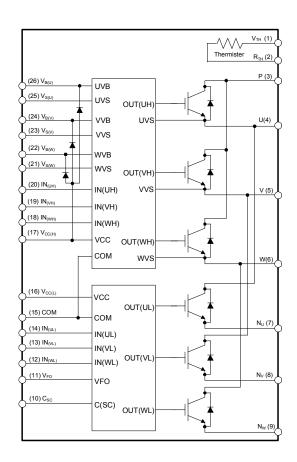


Figure 1.



Pin Number	Pin Name	Pin Description
1	V _{TH}	Thermistor Bias Voltage
2	R _{TH}	Series Resistor for the Use of Thermistor (Temperature Detection)
3	Р	Positive DC-Link Input
4	U	Output for U Phase
5	V	Output for V Phase
6	W	Output for W Phase
7	NU	Negative DC-Link Input for U Phase
8	N _V	Negative DC-Link Input for V Phase
9	N _W	Negative DC-Link Input for W Phase
10	C _{SC}	Capacitor (Low-pass Filter) for Short-Current Detection Input
11	V _{FO}	Fault Output
12	IN _(WL)	Signal Input for Low-side W Phase
13	IN _(VL)	Signal Input for Low-side V Phase
14	IN _(UL)	Signal Input for Low-side U Phase
15	СОМ	Common Supply Ground
16	V _{CC(L)}	Low-Side Common Bias Voltage for IC and IGBTs Driving
17	V _{CC(H)}	High-Side Common Bias Voltage for IC and IGBTs Driving
18	IN _(WH)	Signal Input for High-side W Phase
19	IN _(VH)	Signal Input for High-side V Phase
20	IN _(UH)	Signal Input for High-side U Phase
21	V _{S(W)}	High-side Bias Voltage Ground for W Phase IGBT Driving
22	V _{B(W)}	High-side Bias Voltage for W Phase IGBT Driving
23	V _{S(V)}	High-side Bias Voltage Ground for V Phase IGBT Driving
24	V _{B(V)}	High-side Bias Voltage for V Phase IGBT Driving
25	V _{S(U)}	High-side Bias Voltage Ground for U Phase IGBT Driving
26	V _{B(U)}	High-side Bias Voltage for U Phase IGBT Driving

Internal Equivalent Circuit and Input/Output Pins



Note:

1) Inverter high-side is composed of three IGBTs, freewheeling diodes and one control IC for each IGBT.

2) Inverter low-side is composed of three IGBTs, freewheeling diodes and one control IC for each IGBT. It has gate drive and protection functions.

3) Inverter power side is composed of four inverter dc-link input terminals and three inverter output terminals.

Figure 3.

Absolute Maximum Ratings (T_J = 25°C, Unless Otherwise Specified)

Inverter Part

Symbol	Parameter	Conditions	Rating	Units
V _{PN}	Supply Voltage	Applied between P- N _U , N _V , N _W	450	V
V _{PN(Surge)}	Supply Voltage (Surge)	Applied between P- N_U , N_V , N_W	500	V
V _{CES}	Collector-emitter Voltage		600	V
± I _C	Each IGBT Collector Current	T_{C} = 25°C, T_{J} < 150°C	15	А
± I _{CP}	Each IGBT Collector Current (Peak)	T_{C} = 25°C, $T_{J} < $ 150°C, Under 1ms Pulse Width	30	A
P _C	Collector Dissipation	T _C = 25°C per One Chip	41	W
Τ _J	Operating Junction Temperature	(Note 1)	-40 ~ 150	°C

Note:

1. The maximum junction temperature rating of the power chips integrated within the SPM is 150°C.

Control Part

Symbol	Parameter	Conditions	Rating	Units
V _{CC}	Control Supply Voltage	Applied between $V_{CC(H)}$, $V_{CC(L)}$ - COM	20	V
V_{BS}	High-side Control Bias Voltage	Applied between $V_{B(U)}$ - $V_{S(U)}, \ V_{B(V)}$ - $V_{S(V)}, \ V_{B(W)}$ - $V_{S(W)}$	20	V
V _{IN}	Input Signal Voltage	$\begin{array}{c c} \mbox{Applied between } IN_{(UH)}, \ IN_{(VH)}, \ IN_{(WH)}, \\ \ IN_{(UL)}, \ IN_{(VL)}, \ IN_{(WL)} \ - \ COM \end{array}$	-0.3~V _{CC} +0.3	V
V _{FO}	Fault Output Supply Voltage	Applied between V _{FO} - COM	-0.3~V _{CC} +0.3	V
I _{FO}	Fault Output Current	Sink Current at V _{FO} Pin	1	mA
V _{SC}	Current Sensing Input Voltage	Applied between C _{SC} - COM	-0.3~V _{CC} +0.3	V

Bootstrap Diode Part

Symbol	Parameter	Conditions	Rating	Units
V _{RRM}	Maximum Repetitive Reverse Voltage		600	V
١ _F	Forward Current	T _C = 25°C	0.5	А
I _{FP}	Forward Current (Peak)	T _C = 25°C, Under 1ms Pulse Width	1	А
Τ _J	Operating Junction Temperature		-40 ~ 150	°C

Total System

Symbol	Parameter	Conditions	Rating	Units
V _{PN(PROT)}	Self Protection Supply Voltage Limit (Short Circuit Protection Capability)	$V_{CC} = V_{BS} = 13.5 \sim 16.5 V$ T _J = 150°C, Non-repetitive, less than 2µs	400	V
T _{STG}	Storage Temperature		-40 ~ 125	°C
V _{ISO}	Isolation Voltage	60Hz, Sinusoidal, AC 1 minute, Connection Pins to heat sink plate	2000	V _{rms}

Thermal Resistance

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Units
R _{th(j-c)Q}	Junction to Case Thermal	Inverter IGBT part (per 1/6 module)	-	-	3.0	°C/W
R _{th(j-c)F}	Resistance	Inverter FWD part (per 1/6 module)	-	-	4.3	°C/W

Note:

2. For the measurement point of case temperature(T $_{C}$), please refer to Figure 2.

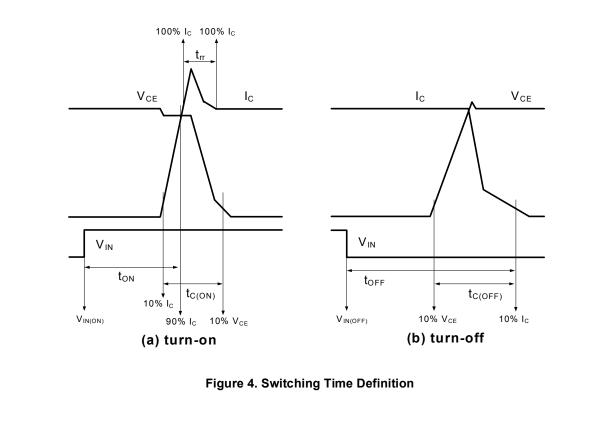
Electrical Characteristics	$(T_1 = 25^{\circ}C, Unless Otherwise Specified)$

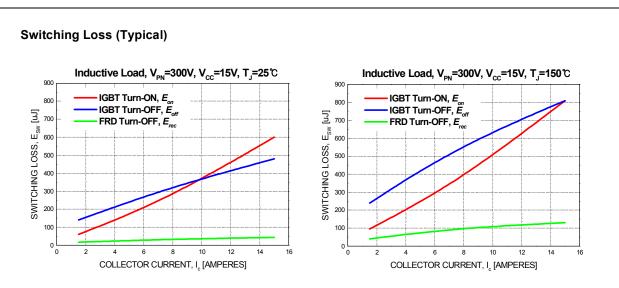
Inverter Part

S	ymbol	Parameter	Cond	itions	Min.	Тур.	Max.	Units
V	CE(SAT)	Collector-Emitter Saturation Voltage	V _{CC} = V _{BS} = 15V V _{IN} = 5V	I _C = 15A, T _J = 25°C	-	1.8	2.3	V
	V _F	FWD Forward Voltage	V _{IN} = 0V	$I_{F} = 15A, T_{J} = 25^{\circ}C$	-	1.8	2.3	V
HS	t _{ON}	Switching Times	V _{PN} = 300V, V _{CC} = V _{BS} = 15V, I _C = 15A		0.45	0.75	1.25	μS
	t _{C(ON)}		$T_J = 25^{\circ}C$ $V_{IN} = 0V \leftrightarrow 5V$, Induct	ive Load	-	0.25	0.50	μS
	t _{OFF}		(Note 3)		-	0.75	1.25	μS
	t _{C(OFF)}				-	0.25	0.50	μS
	t _{rr}				-	0.15	-	μS
LS	t _{ON}		V_{PN} = 300V, V_{CC} = V_{B}	_S = 15V, I _C = 15A	0.45	0.75	1.25	μS
	t _{C(ON)}		$T_J = 25^{\circ}C$ $V_{IN} = 0V \leftrightarrow 5V$, Induct	ive Load	-	0.25	0.50	μS
	t _{OFF}		(Note 3)		-	0.75	1.25	μS
	t _{C(OFF)}				-	0.25	0.50	μS
	t _{rr}				-	0.15	-	μS
	I _{CES}	Collector-Emitter Leakage Current	$V_{CE} = V_{CES}$		-	-	1	mA

Note:

3. t_{ON} and t_{OFF} include the propagation delay time of the internal drive IC. t_{C(ON)} and t_{C(OFF)} are the switching time of IGBT itself under the given gate driving condition internally. For the detailed information, please see Figure 4.







Symbol	Parameter	Conditions		Min.	Тур.	Max.	Units
IQCCH	Quiescent V _{CC} Supply	V _{CC(H)} = 15V, IN _(UH,VH,WH) = 0V	V _{CC(H)} - COM	-	-	0.10	mA
IQCCL	Current	V _{CC(L)} = 15V, IN _(UL,VL,WL) = 0V	V _{CC(L)} - COM	-	-	2.65	mA
I _{PCCH}	Operating V _{CC} Supply Current	$V_{CC(H)}$ = 15V, f_{PWM} = 20kHz, duty=50%, applied to one PWM signal input for High-side	V _{CC(H)} - COM	-	-	0.15	mA
I _{PCCL}		$V_{CC(L)}$ = 15V, f_{PWM} = 20kHz, duty=50%, applied to one PWM signal input for Low-side	V _{CC(L)} - COM	-	-	3.65	mA
I _{QBS}	Quiescent V _{BS} Supply Current	V _{BS} = 15V, IN _(UH, VH, WH) = 0V	$V_{B(U)} - V_{S(U)}, V_{B(V)} - V_{S(V)}, V_{B(W)} - V_{S(W)}$	-	-	0.30	mA
I _{PBS}	Operating V _{BS} Supply Current	$V_{CC} = V_{BS} = 15V$, $f_{PWM} = 20kHz$, duty=50%, applied to one PWM signal input for High-side	$V_{B(U)} - V_{S(U)}, V_{B(V)} - V_{S(V)}, V_{B(W)} - V_{S(W)}$	-	-	2.00	mA
V _{FOH}	Fault Output Voltage	V_{SC} = 0V, V_{FO} Circuit: 4.7k Ω to 5V Pull-up		4.5	-	-	V
V _{FOL}		V_{SC} = 1V, V_{FO} Circuit: 4.7k Ω to 5V	Pull-up	-	-	0.5	V
V _{SC(ref)}	Short Circuit Trip Level	V _{CC} = 15V (Note 4)		0.45	0.5	0.55	V
UV_CCD		Detection Level		10.5	-	13.0	V
UV_CCR	Supply Circuit Under-Voltage	Reset Level		11.0	-	13.5	V
UV_BSD	Protection	Detection Level		10.0	-	12.5	V
UV_BSR		Reset Level		10.5	-	13.0	V
t _{FOD}	Fault-out Pulse Width			30	-	-	μS
V _{IN(ON)}	ON Threshold Voltage	Applied between IN _(UH) , IN _(VH) , II	N _(WH) , IN _(UL) , IN _(VL) ,	-	-	2.6	V
V _{IN(OFF)}	OFF Threshold Voltage	IN _(WL) - COM		0.8	-	-	V
R _{TH}	Resistance of	@T _{TH} =25°C, (Note 5)		-	47	-	kΩ
	Thermister	@T _{TH} =100°C		-	2.9	-	kΩ

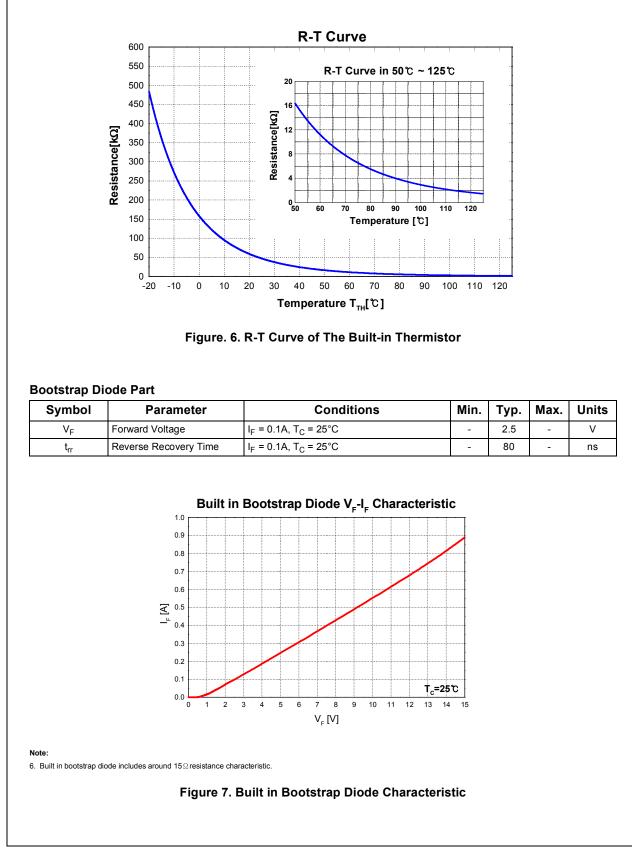
Control Part

Note:

4. Short-circuit current protection is functioning only at the low-sides.

5. T_{TH} is the temperature of thermister itselt. To know case temperature (T_C), please make the experiment considering your application.

FNA41560/B2 Smart Power Module



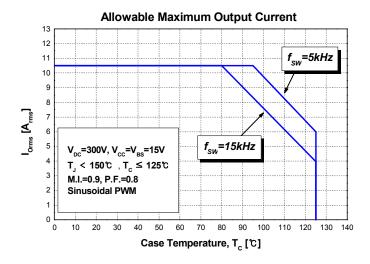
FNA41560/B2 Smart Power Module

Recommended Operating Conditions

Symbol	Deremeter	Conditions	Value			11
	Parameter Conditions		Min.	Тур.	Max.	Units
V _{PN}	Supply Voltage	Applied between P - N _U , N _V , N _W	-	300	400	V
V _{CC}	Control Supply Voltage	Applied between V _{CC(H)} , V _{CC(L)} -COM	13.5	15	16.5	V
V _{BS}	High-side Bias Voltage	Applied between $V_{B(U)}$ - $V_{S(U)}$, $V_{B(V)}$ - $V_{S(V)}$, $V_{B(W)}$ - $V_{S(W)}$	13.0	15	18.5	V
dV _{CC} /dt, dV _{BS} /dt	Control supply variation		-1	-	1	V/µs
t _{dead}	Blanking Time for Preventing Arm-short	For Each Input Signal	1.5	-	-	μs
f _{PWM}	PWM Input Signal	$-40^{\circ}C < T_{J} < 150^{\circ}C$	-	-	20	kHz
V_{SEN}	Voltage for Current Sensing	Applied between N _U , N _V , N _W - COM (Including surge voltage)	-4		4	V
P _{WIN(ON)}	Minimun Input Pulse	(Note 7)	0.5	-	-	μS
P _{WIN(OFF)}	Width		0.5	-	-	

Note:

7. SPM might not make response if input pulse width is less than the recommanded value.



Note:

8. The allowable output current value may be different from the actual application.



Package Marking and Ordering Information

Device Marking	Device	Package	Reel Size	Tape Width	Quantity
FNA41560	FNA41560	SPM26-AAA	-	-	12
FNA41560B2	FNA41560B2	SPM26-AAC	-	-	12

FNA41560/B2	
Smart	
Power	
Module	

Units

μm

N•m

kg•cm g

Parameter	Conditions Note Figure 9		Limits		
Farameter			Min.	Тур.	Max.
Device Flatness			0	-	+120
Mounting Torque	Mounting Screw: - M3	Recommended 0.7N•m	0.6	0.7	0.8
	Note Figure 10	Recommended 7.1kg•cm	6.2	7.1	8.1
Weight		•	-	11	-

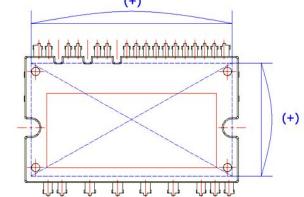
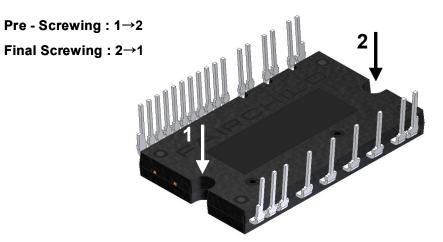


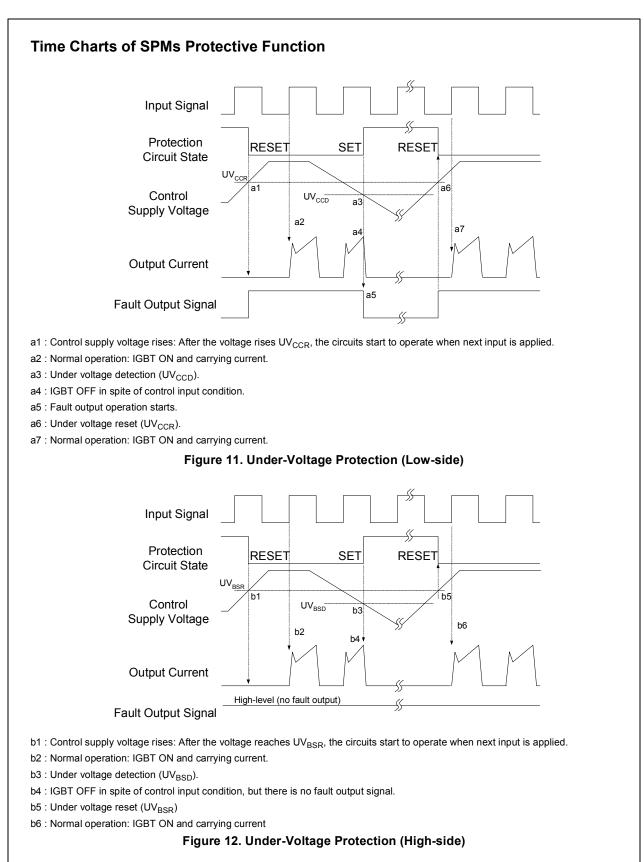
Figure 9. Flatness Measurement Position

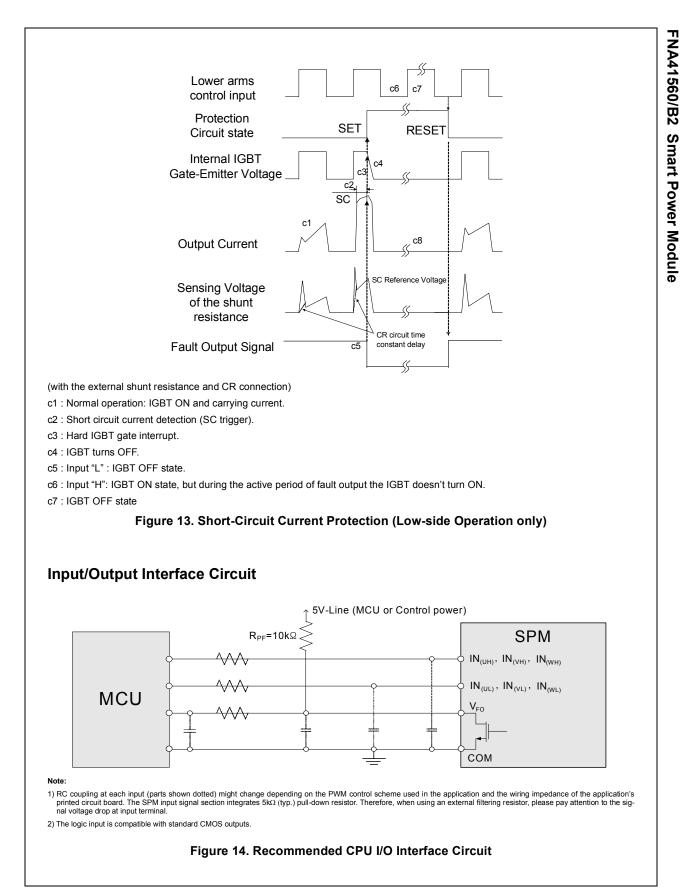


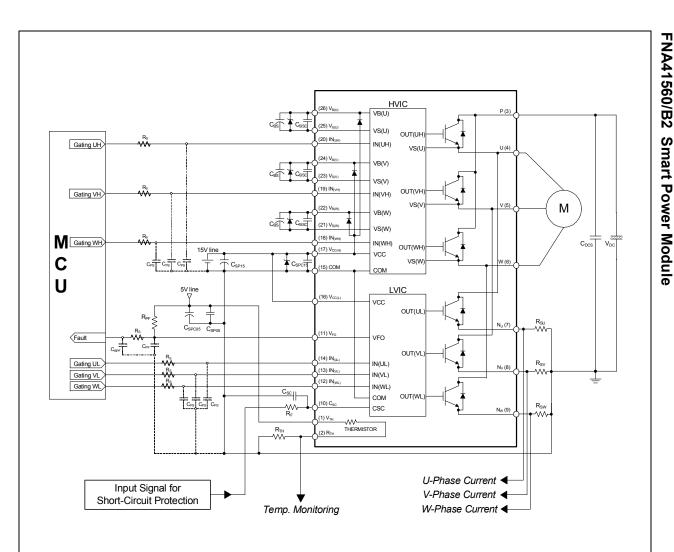
Note:

 Do not make over torque when mounting screws. Much mounting torque may cause ceramic cracks, as well as bolts and Al heat-sink destruction.
 Avoid one side tightening stress. Fig.10 shows the recommended torque order for mounting screws. Uneven mounting can cause the SPM ceramic substrate to be damaged. The Pre-Screwing torque is set to 20~30% of maximum torque rating.

Figure 10. Mounting Screws Torque Order





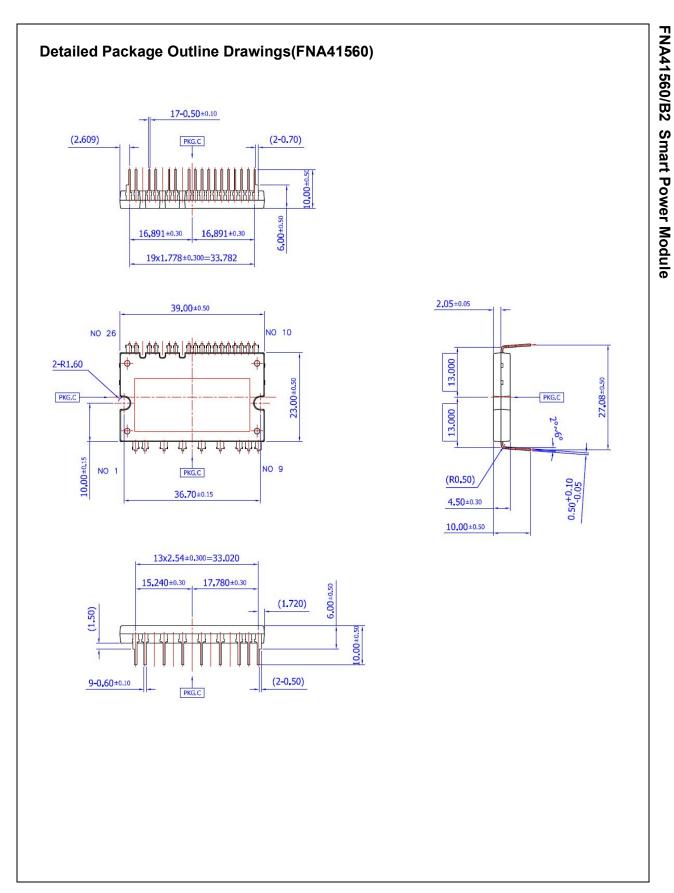


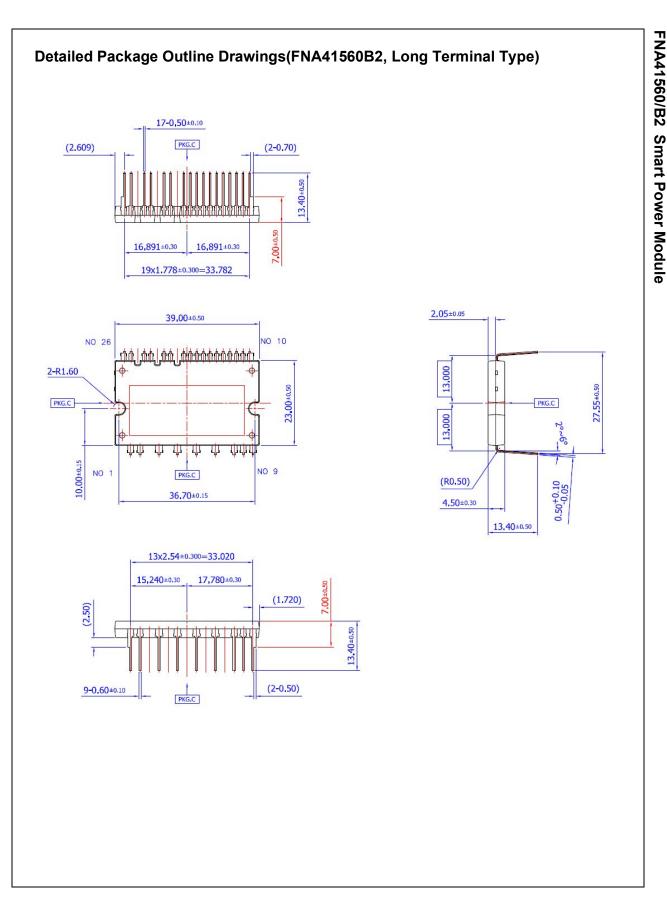
- 1) To avoid malfunction, the wiring of each input should be as short as possible. (less than 2-3cm)
- 2) By virtue of integrating an application specific type HVIC inside the SPM, direct coupling to CPU terminals without any opto-coupler or transformer isolation is possible.
- 3) V_{FO} output is open drain type. This signal line should be pulled up to the positive side of the MCU or control power supply with a resistor that makes I_{FO} up to 1mA. Please refer to Figure 14.
- 4) C_{SP15} of around 7 times larger than bootstrap capacitor C_{BS} is recommended.
- 5) Input signal is High-Active type. There is a 5kΩ resistor inside the IC to pull down each input signal line to GND. RC coupling circuits is recommanded for the prevention of input signal oscillation. R_SC_{PS} time constant should be selected in the range 50~150ns. (Recommended R_S=100 Ω, C_{PS}=1nF)
- 6) To prevent errors of the protection function, the wiring around R_F and C_{SC} should be as short as possible.
- 7) In the short-circuit protection circuit, please select the $R_F C_{SC}$ time constant in the range 1.5~2µs.
- 8) Each capacitor should be mounted as close to the pins of the SPM as possible.
- 9) To prevent surge destruction, the wiring between the smoothing capacitor and the P&GND pins should be as short as possible. The use of a high frequency non-inductive capacitor of around 0.1~0.22 µF between the P&GND pins is recommended.
- 10) Relays are used at almost every systems of electrical equipments of home appliances. In these cases, there should be sufficient distance between the CPU and the relays.
- 11) The zener diode should be adopted for the protection of ICs from the surge destruction between each pair of control supply terminals. (Recommanded zener diode=24V/1W)
- 12) Please choose the electrolytic capacitor with good temperature characteristic in C_{BS}. Also, choose 0.1~0.2µF R-category ceramic capacitors with good temperature and frequency characteristics in C_{BSC}.

13) For the detailed information, please refer to the AN-9070 and FEB305-001.

Figure 15. Typical Application Circuit

FNA41560/B2 Rev. C







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