

Symbios[®] SYM53C1010-33 PCI to Dual Channel Ultra3 SCSI Multifunction Controller

Technical Manual

May 2000

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Order Number S14025.B

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Preface

This book is the primary reference and technical manual for the LSI Logic Symbios® SYM53C1010-33 PCI to Dual Channel Ultra3 SCSI Multifunction Controller. It contains a complete functional description for the product and includes complete physical and electrical specifications.

Audience

This document was prepared for system designers and programmers who are using this device to design an Ultra3 SCSI port for PCI-based personal computers, workstations, servers or embedded applications.

Organization

This document has the following chapters and appendixes:

- [Chapter 1, Introduction](#), describes the general information about the SYM53C1010-33.
- [Chapter 2, Functional Description](#), describes the main functional areas of the chip in more detail, including the interfaces to the SCSI bus and external memory.
- [Chapter 3, Signal Descriptions](#), contains the pin diagram and signal descriptions.
- [Chapter 4, Registers](#), describes each bit in the operating registers, and is organized by register address.
- [Chapter 5, SCSI SCRIPTS Instruction Set](#), defines all of the SCSI SCRIPTS instructions that are supported by the SYM53C1010-33.
- [Chapter 6, Specifications](#), contains the electrical characteristics and AC timing diagrams.
- [Appendix A, Register Summary](#), is a register summary.

- [Appendix B, External Memory Interface Diagram Examples](#), contains several example interface drawings for connecting the SYM53C1010-33 to external ROMs.

Related Publications

For background please contact:

ANSI

11 West 42nd Street
New York, NY 10036
(212) 642-4900

Ask for document number X3.131-199X (SCSI-2)

Global Engineering Documents

15 Inverness Way East
Englewood, CO 80112
(800) 854-7179 or (303) 397-7956 (outside U.S.) FAX (303) 397-2740
Ask for document number X3.131-1994 (SCSI-2) or X3.253
(*SCSI-3 Parallel Interface*)

ENDL Publications

14426 Black Walnut Court
Saratoga, CA 95070
(408) 867-6642

Document names: *SCSI Bench Reference*, *SCSI Encyclopedia*, *SCSI Tutor*

Prentice Hall

113 Sylvan Avenue
Englewood Cliffs, NJ 07632
(800) 947-7700

Ask for document number ISBN 0-13-796855-8, *SCSI: Understanding the Small Computer System Interface*

LSI Logic (Storage Components) Electronic Bulletin Board

(719) 533-7235

Ask for document *Symbios[®] PCI to SCSI I/O Processors Programming Guide*, Order Number J25972I

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Conventions Used in This Manual

The word *assert* means to drive a signal true or active. The word *deassert* means to drive a signal false or inactive.

Hexadecimal numbers are indicated by the prefix "0x" —for example, 0x32CF. Binary numbers are indicated by the prefix "0b" —for example, 0b0011.0010.1100.1111.

Revision Record

Revision	Date	Remarks
0.5	4/99	Advanced Information Data - contains Signal Descriptions, Registers, and Mechanical Drawings.
1.0	11/15/99	Preliminary Technical Manual.
1.1	12/26/99	Numerous Rewordings.
2.0	3/00	Final Release.
3.0	5/00	Miscellaneous edits, update to Figure 6.42.

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Chapter 1

Introduction

This chapter provides a general overview on the SYM53C1010-33 PCI to Dual Channel Ultra3 SCSI Multifunction Controller. This chapter contains the following sections:

- [Section 1.1, “General Description”](#)
 - [Section 1.2, “Benefits of Ultra3 SCSI”](#)
 - [Section 1.3, “Benefits of SURElink \(Ultra3 SCSI Domain Validation\)”](#)
 - [Section 1.4, “Benefits of LVD Link”](#)
 - [Section 1.5, “Benefits of TolerANT® Technology”](#)
 - [Section 1.6, “Summary of SYM53C1010-33 Benefits”](#)
-

1.1 General Description

The SYM53C1010-33 PCI to Dual Channel Ultra3 SCSI Multifunction Controller brings Ultra3 SCSI performance to host adapter, workstation, and server designs, making it easy to add a high-performance SCSI bus to any PCI system.

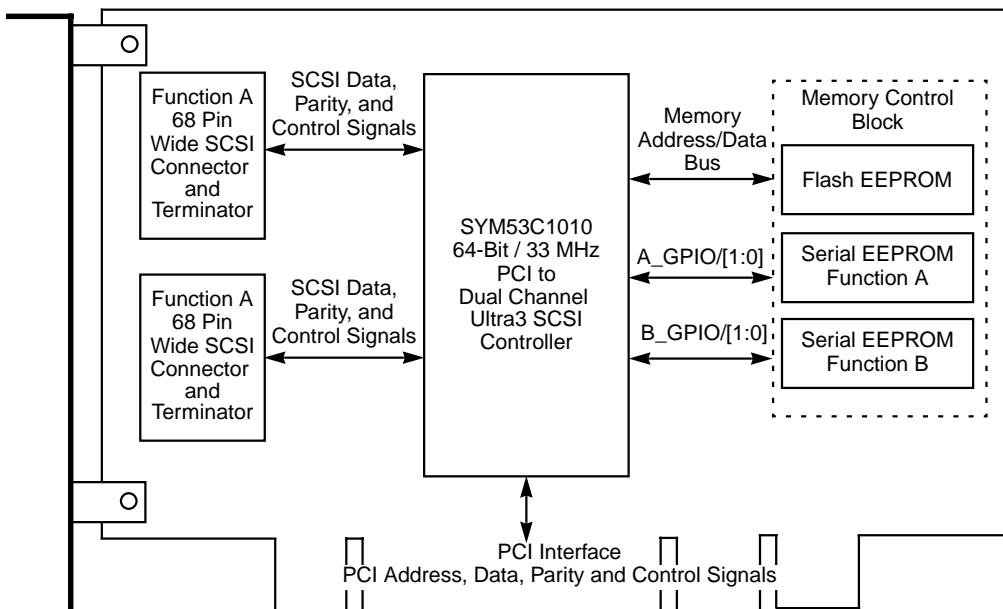
The SYM53C1010 is pin and software compatible with the SYM53C896 PCI to Dual Channel Ultra2 SCSI Multifunction Controller, thus making migration easy (pin compatible means that the SYM53C896 can operate in an SYM53C1010 socket but the SYM53C1010 cannot operate in an SYM53C896 socket). The SYM53C1010 supports a 64-bit or 32-bit, 33 MHz PCI bus. The Ultra3 SCSI features in the SYM53C1010 are: Double Transition (DT) clocking, Cyclic Redundancy Check (CRC), and Domain Validation. These features comply with the Ultra160 SCSI industry initiative.

DT clocking permits the SYM53C1010 to transfer data up to 160 megabytes per second (Mbytes/s) on each channel for a total of 320

Mbytes/s. CRC improves the integrity of the SCSI data transmission through enhanced detection of communication errors. Asynchronous Information Protection (AIP) augments CRC to protect all nondata phases, providing complete end-to-end protection of the SCSI I/O. SURElink™ Domain Validation detects the SCSI bus configuration and automatically tests and adjusts the SCSI transfer rate to optimize interoperability. Three levels of Domain Validation are provided, assuring robust system operation.

The SYM53C1010 has a local memory bus. This allows local storage of the device's BIOS ROM in flash memory or standard EPROMs. The SYM53C1010 supports programming of local flash memory for BIOS updates. The chip is packaged in a 329 Ball Grid Array (BGA). [Figure 1.1](#) shows a typical SYM53C1010 board application connected to external ROM or flash memory.

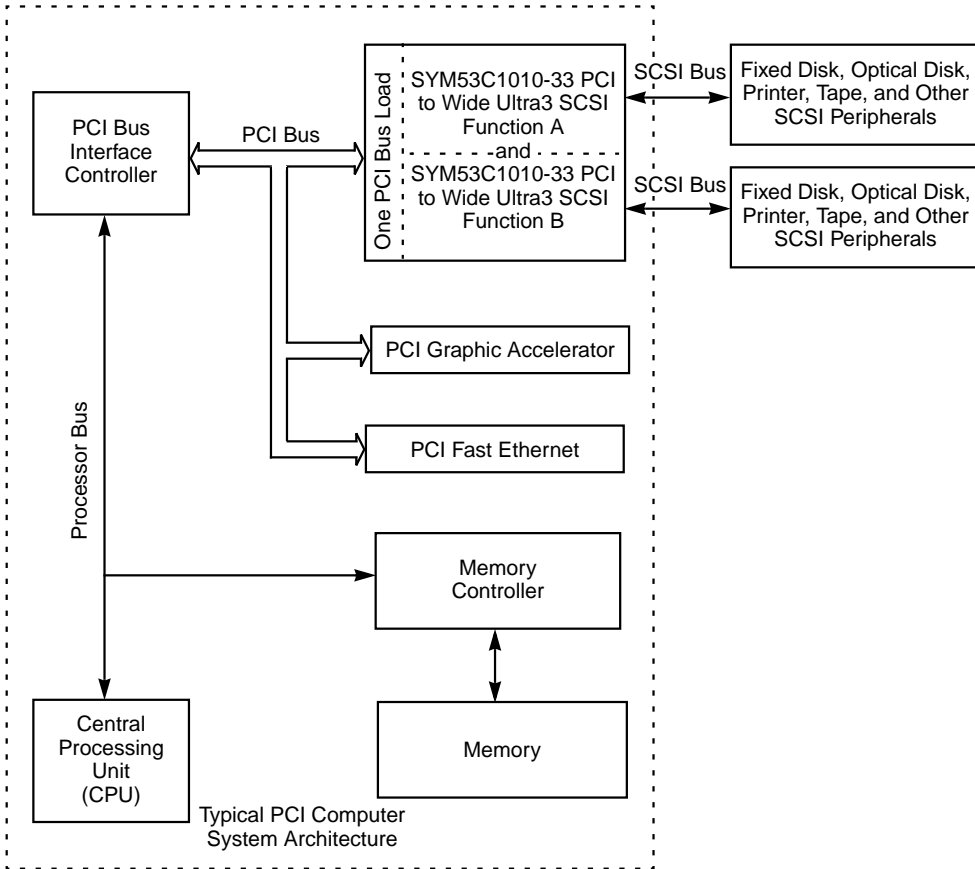
Figure 1.1 Typical SYM53C1010-33 Board Application



LVD Link™ technology is the LSI Logic implementation of Low Voltage Differential (LVD). LVD Link transceivers allow the SYM53C1010 to perform either Single-Ended (SE) or LVD transfers. The SYM53C1010 integrates two high-performance SCSI cores, a 64-bit/33 MHz PCI bus master DMA core, and the LSI Logic SCSI SCRIPTS™ processor to

meet the flexibility requirements of Ultra3 SCSI standards. It implements multithreaded I/O algorithms with minimum processor intervention, solving the protocol overhead problems of previous intelligent and nonintelligent adapter designs. [Figure 1.2](#) illustrates a typical SYM53C1010 system application.

Figure 1.2 Typical SYM53C1010-33 System Application



1.1.1 New Features in the SYM53C1010-33

The SYM53C1010 is functionally similar to the SYM53C896 PCI to Dual Channel Ultra2 SCSI Multifunction Controller, with additional features and benefits. Following is a list of new SYM53C1010 features from the SYM53C896:

- Complies with PCI Rev. 2.2 specification
- Supports Ultra3 DT clocking for data transfers up to 160 Mbytes/s per channel
- Supports enhanced protection on nondata asynchronous phases through AIP
- Supports CRC checking and generation in DT phases
- Supports Domain Validation
 - Basic (level 1) with Inquiry Command (Inquiry Check)
 - Enhanced (level 2) with Read/Write Buffer
 - Margined (level 3) with margining of LVD drivers and programmable skew test
- All cycles to SCRIPTS RAM stay internal to the device, not generating PCI cycles
- SCRIPTS engine with improved instruction fetch performance

1.2 Benefits of Ultra3 SCSI

Ultra3 SCSI delivers data up to two times faster than Ultra2 SCSI. Ultra3 SCSI is an extension of the SPI-3 draft standard that allows faster synchronous SCSI data transfer rates than Ultra2 SCSI. When enabled, Ultra3 SCSI performs 80 megatransfers per second (megatransfers/s) resulting in approximately double the synchronous data transfer rates of Ultra2 SCSI. The SYM53C1010 performs 16-bit, Ultra3 SCSI synchronous data transfers as fast as 160 Mbytes/s on each channel providing a total bandwidth of 320 Mbytes/s. This advantage is most noticeable in heavily loaded systems, or large block size applications such as video on-demand and image processing. The Ultra3 data transfer speed is accomplished using DT clocking. DT clocking refers to transferring data on both polarity edges of the request or acknowledge

signals. Data is clocked on both rising and falling edges of the request and acknowledge signals. Double-edge clocking doubles data transfer speeds without increasing the clock rate.

Ultra3 SCSI also includes CRC which offers higher levels of data reliability by ensuring complete integrity of transferred data. CRC is a 32-bit scheme, referred to as CRC-32. CRC is guaranteed to detect all single bit errors, any two bits in error, or any combination of errors within a single 32-bit range.

AIP is also supported by the SYM53C1010, protecting all nondata phases, including command, status, and messages. CRC, along with AIP, provides end-to-end protection of the SCSI I/O.

An advantage of Ultra3 SCSI is that it significantly improves SCSI bandwidth while preserving existing hardware and software investments. The primary software changes required are to enable the chip to perform synchronous negotiations for Ultra3 SCSI rates and to enable the clock quadrupler. Ultra3 SCSI uses the same connectors as Ultra SCSI and Ultra2 SCSI. [Chapter 2, “Functional Description”](#) contains more information on migrating an Ultra SCSI or Ultra2 SCSI design to an Ultra3 SCSI design.

1.3 Benefits of SURElink (Ultra3 SCSI Domain Validation)

SURElink represents the very latest SCSI interconnect management solution. It ensures robust and low risk Ultra3 SCSI implementations by extending the Domain Validation guidelines documented in the ANSI T10 SPI-3 specifications. Domain Validation verifies that the system is capable of transferring data at Ultra3 speeds, allowing it to renegotiate to lower speed and bus width if necessary. SURElink is the software control for the manageability enhancements in the SYM53C1010 PCI to Dual Channel Ultra3 SCSI Multifunction Controller. Fully integrated in the SDMS™ software solution, SURElink provides Domain Validation at boot time as well as throughout system operation. SURElink extends to the DMI (Desktop Management Interface) based System Management components of SDMS, providing the network administrator remote management capability.

SURElink Domain Validation provides 3 levels of integrity checking: Basic (level 1), Enhanced (level 2) and Margined (level 3). The basic check

consists of an inquiry command to detect gross problems. The enhanced check sends a known data pattern using the Read and Write Buffer commands to detect additional problems. Margined check verifies that the physical parameters have some degree of margin. By varying LVD drive strength and REQ/ACK timing characteristics level 3 verifies that no errors occur on the transfers. These altered signals are only used during the diagnostic check and not during normal system operation. Should errors occur with any of these checks, the system can drop back to a lower transmission speed on a per target basis to ensure robust system operation.

1.4 Benefits of LVD Link

The SYM53C1010 supports LVD through LVD Link. This signaling technology increases the reliability of SCSI data transfers over longer distances than are supported by SE SCSI. The low current output of LVD allows the I/O transceivers to be integrated directly onto the chip. LVD provides the reliability of High Voltage Differential (HVD) SCSI without the added cost of external differential transceivers. Ultra3 SCSI with LVD allows a longer SCSI cable and more devices on the bus, with the same cables defined in the SCSI-3 Parallel Interface standard for Ultra SCSI. LVD provides a long-term migration path to even faster SCSI transfer rates without compromising signal integrity, cable length, or connectivity.

For backward compatibility to existing SE devices, the SYM53C1010 features universal LVD Link transceivers that support LVD SCSI and SE SCSI. This allows use of the SYM53C1010 in both legacy and Ultra3 SCSI applications.

1.5 Benefits of TolerANT[®] Technology

The SYM53C1010 features TolerANT technology, which includes active negation on the SCSI drivers and input signal filtering on the SCSI receivers. Active negation causes the SCSI Request, Acknowledge, Data, and Parity signals to be actively driven high rather than passively pulled up by terminators.

TolerANT receiver technology improves data integrity in unreliable cabling environments where other devices would be subject to data

corruption. TolerANT receivers filter the SCSI bus signals to eliminate unwanted transitions, without the long signal delay associated with RC-type input filters. This improved driver and receiver technology helps eliminate double clocking of data which is the single biggest reliability issue with SCSI operations. TolerANT input signal filtering is a built-in feature of the SYM53C1010 and all LSI Logic fast SCSI, Ultra SCSI, Ultra2 SCSI, and Ultra3 SCSI devices.

The benefits of TolerANT technology include increased immunity to noise when the signal is going HIGH, better performance due to balanced duty cycles, and improved fast SCSI transfer rates. In addition, TolerANT SCSI devices do not cause glitches on the SCSI bus at power-up or power-down. This protects other devices on the bus from data corruption. When it is used with the LVD Link transceivers, TolerANT technology provides excellent signal quality and data reliability in real world cabling environments. TolerANT technology is compatible with both the Alternative One and Alternative Two termination schemes proposed by the American National Standards Institute.

1.6 Summary of SYM53C1010-33 Benefits

This section provides a summary of the SYM53C1010 features and benefits. It contains information on [SCSI Performance](#), [PCI Performance](#), [Integration](#), [Ease of Use](#), [Flexibility](#), [Reliability](#), and [Testability](#).

1.6.1 SCSI Performance

The SYM53C1010-33:

- Performs wide, Ultra3 SCSI synchronous data transfers as fast as 160 Mbytes/s on each SCSI channel for a total of 320 Mbytes/s using DT clocking.
- Supports CRC checking and generation in DT phases.
- Protects nondata phases with AIP.
- Supports Domain Validation:
 - Basic (level 1)
 - Enhanced (level 2)
 - Margined (level 3)

- Includes integrated LVD Link universal transceivers:
 - Supports SE and LVD signals.
 - Allows greater device connectivity and longer cable length.
 - LVD Link transceivers save the cost of external differential transceivers.
 - Supports a long-term performance migration path.
- Bursts of up to 512 bytes across the PCI bus with an independent 896–920 byte FIFO on each SCSI channel.
- Includes two separate SCSI channels on one chip.
- Handles phase mismatches in SCRIPTS without interrupting the system processor.
- Includes an on-chip SCSI clock quadrupler that allows the chip to achieve Ultra3 SCSI transfer rates with an input frequency of 40 MHz.
- Includes 8 Kbytes of internal RAM for SCRIPTS instruction storage for each SCSI channel.
- Supports 31 levels of SCSI synchronous offset in the Single Transition (ST) mode and 62 levels in the DT mode.
- Supports variable block size and scatter/gather data transfers.
- Performs sustained Memory-to-Memory DMA transfers to approximately 100 Mbytes/s.
- Minimizes the SCSI I/O start latency.
- Performs complex bus sequences without interrupts, including restoring data pointers.
- Reduces ISR overhead through a unique interrupt status reporting method.
- Includes RAID ready SCSI on the motherboard with separate interrupts for routing to a RAID adapter.
- Supports Load/Store SCRIPTS instructions to increase the performance of data transfers to and from the chip registers without using PCI cycles.
- Includes SCRIPTS support of 64-bit addressing.

- Supports target disconnect and later reconnect with no interrupt to the system processor.
- Supports multithreaded I/O algorithms in SCSI SCRIPTS with fast I/O context switching.
- Supports expanded register Move instructions to support additional arithmetic capability.

1.6.2 PCI Performance

The SYM53C1010:

- Complies with PCI 2.2 specification.
- Supports a 64-bit/33 MHz PCI interface for 264 Mbytes/s bandwidth that:
 - Can function in a 32-bit PCI slot
 - Operates at 33 MHz
 - Supports dual address cycle generation for all SCRIPTS
 - Presents a single electrical load to the PCI Bus (True PCI Multifunction Device)
- Bursts 2/4, 4/8, 8/16, 16/32, 32/64, or 64/128 Qword/Dword transfers across the PCI bus.
- Supports 32-bit or 64-bit word data bursts with variable burst lengths.
- Prefetches up to 8 Dwords of SCRIPTS instructions.
- Bursts SCRIPTS opcode fetches across the PCI bus.
- Performs zero wait-state bus master data bursts up to 264 Mbytes/s (@ 33 MHz).
- Supports PCI [Cache Line Size \(CLS\)](#) register.
- Supports PCI Write and Invalidate, Read Line, and Read Multiple commands.
- Complies with PCI Bus Power Management Specification Rev 1.1.
- Complies with PC99.

1.6.3 Integration

The following features ease integration of the SYM53C1010 into a system:

- Dual channel Ultra3 SCSI PCI multifunction controller.
- Integrated LVD transceivers.
- Full 32-bit or 64-bit PCI DMA bus master.
- Memory-to-Memory Move instructions allow use as a third-party PCI bus DMA controller.
- Integrated SCRIPTS processor.

1.6.4 Ease of Use

The following features of the SYM53C1010 make the device user friendly:

- The SYM53C1010 is pin and software compatible with the SYM53C896 PCI to Dual Channel Ultra2 SCSI Multifunction Controller, thus making migration easy (pin compatible means that the SYM53C896 can operate in an SYM53C1010 socket but the SYM53C1010 cannot operate in an SYM53C896 socket).
- Up to one Mbyte of add-in memory support for BIOS and SCRIPTS storage.
- Reduced SCSI development effort.
- Compiler-compatible with existing SYM53C7XX and SYM53C8XX family SCRIPTS.
- Direct connection to PCI and SCSI SE and LVD.
- Development tools and sample SCSI SCRIPTS available.
- Maskable and pollable interrupts.
- Wide SCSI, A or P cable, and up to 15 devices per SCSI channel supported.
- Three programmable SCSI timers: Select/Reselect, Handshake-to-Handshake, and General Purpose.
- Software for PC-based operating system support.

- Support for relative jumps.
- SCSI Selected As ID bits for responding with multiple IDs.

1.6.5 Flexibility

The following features increase the flexibility of the SYM53C1010:

- Universal LVD transceivers are backward compatible with SE devices.
- High level programming interface (SCSI SCRIPTS).
- Programs local and bus flash memory.
- Tailored SCSI sequences execute from main system RAM or internal SCRIPTS RAM.
- Flexible programming interface to tune I/O performance or to adapt to unique SCSI devices.
- Support for changes in the logical I/O interface definition.
- Low level access to all registers and all SCSI bus signals.
- Fetch, Master, and Memory Access control pins.
- Separate SCSI and system clocks.
- SCSI clock quadrupler bits enable Ultra3 SCSI transfer rates with a 40 MHz SCSI clock input.
- Selectable IRQ pin disable bit.
- Compatible with 3.3 V and 5 V PCI.

1.6.6 Reliability

The following features enhance the reliability of the SYM53C1010:

- CRC and AIP provide end-to-end SCSI I/O protection.
- 2 kV ESD protection on SCSI signals.
- Protection against bus reflections due to impedance mismatches.
- Controlled bus assertion times (reduces RFI, improves reliability, and eases FCC certification).
- Latch-up protection greater than 150 mA.

- Voltage feed-through protection (minimum leakage current through SCSI pads).
- A high proportion of pins are power and ground.
- Power and ground isolation of I/O pads and internal chip logic.
- TolerANT technology provides:
 - Active negation of SCSI Data, Parity, Request, and Acknowledge signals for improved fast SCSI transfer rates.
 - Input signal filtering on SCSI receivers improves data integrity, even in noisy cabling environments.

1.6.7 Testability

The following features enhance the testability of the SYM53C1010:

- All SCSI signals accessible through programmed I/O.
- SCSI bus signal continuity checking.
- Support for single-step mode operation.
- JTAG boundary scan.

Chapter 2

Functional Description

This chapter provides a functional description of the SYM53C1010-33 PCI to Dual Channel Ultra3 SCSI Multifunction Controller. This chapter is divided into the following sections:

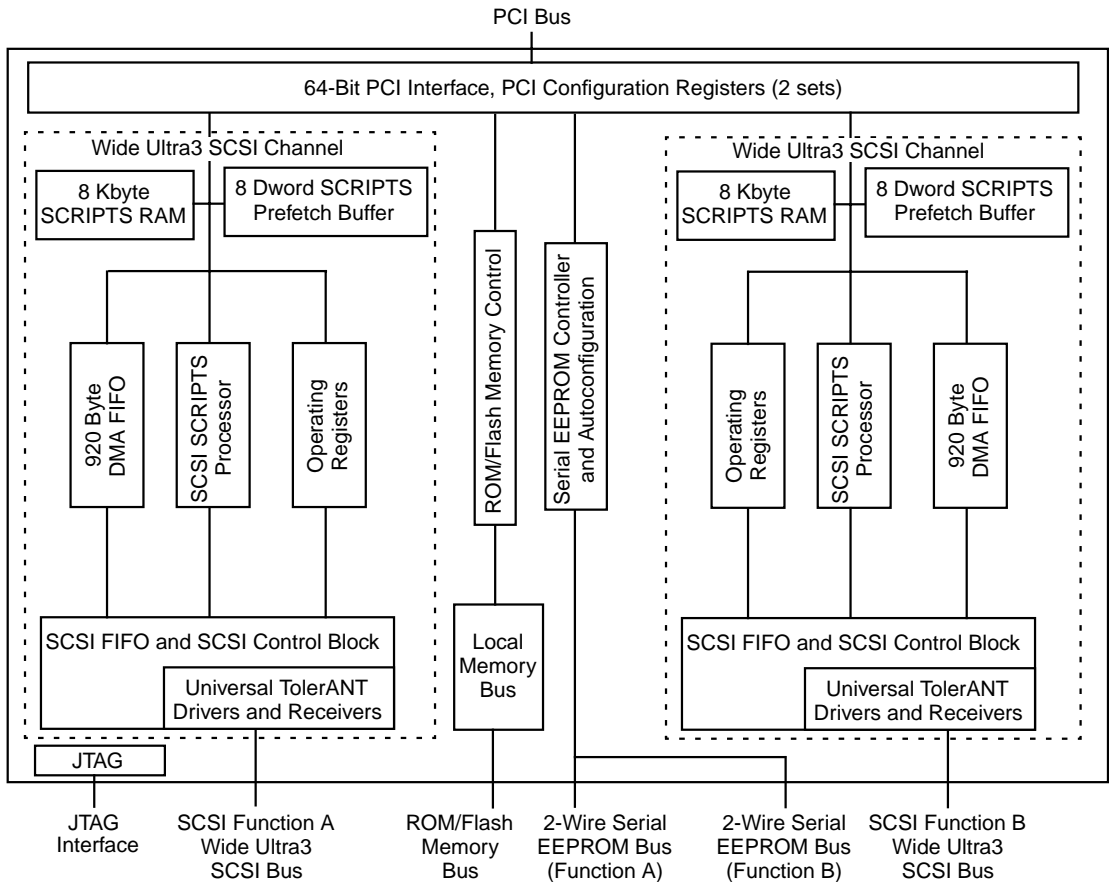
- [Section 2.1, “PCI Functional Description”](#)
- [Section 2.2, “SCSI Functional Description”](#)
- [Section 2.3, “Parallel ROM Interface”](#)
- [Section 2.4, “Serial EEPROM Interface”](#)
- [Section 2.5, “Power Management”](#)

The SYM53C1010-33 PCI to Dual Channel Ultra3 SCSI Multifunction Controller is composed of the following modules:

- 64-bit PCI Interface
- Two independent PCI to Wide Ultra3 SCSI Controllers
- ROM/Flash Memory Controller
- Serial EEPROM Controller

[Figure 2.1](#) illustrates the relationship between these modules.

Figure 2.1 SYM53C1010-33 Block Diagram



The SYM53C1010 has two wide Ultra3 SCSI channels in a single package. Each SCSI channel (A and B) incorporates an independent DMA FIFO and a separate internal 8 Kbyte SCRIPTS RAM.

2.1 PCI Functional Description

The SYM53C1010 implements two PCI to Wide Ultra3 SCSI controllers in a single package. This configuration presents only one load to the PCI bus and uses only one REQ/ - GNT/ pair for PCI bus arbitration. Separate interrupt signals are generated for SCSI Function A and SCSI Function B.

2.1.1 PCI Addressing

There are three physical address spaces defined in the PCI specification:

- PCI Configuration space
- I/O space for operating registers
- Memory space for operating registers

2.1.1.1 Configuration Space

The host processor uses this configuration space to initialize the SYM53C1010. Two independent sets of configuration space registers are defined, one set for each SCSI function. Each SCSI function contains the same register set with identical default values except for the Interrupt Pin. The configuration registers are initialized by the system BIOS using PCI configuration cycles. Each configuration space is a contiguous 256 x 8-bit set of addresses. Decoding C_BE[3:0]/ determines if a PCI cycle is intended to access the configuration register space. The IDSEL bus signal is a “chip select” that allows access to the configuration register space only. A configuration read/write cycle without IDSEL is ignored. The host processor uses the eight lower order address bits (AD[7:0]) to select a specific 8-bit register. Since the SYM53C1010 is a PCI multifunction device, bits AD[10:8] decode either SCSI Function A Configuration register (AD[10:8] = 0b000) or SCSI Function B Configuration register (AD[10:8] = 0b001). [Figure 4.1](#) is an illustration of the PCI Configuration Register Map.

At initialization time, each PCI device is assigned a base address for memory and I/O accesses. In the SYM53C1010, the upper 24 bits of the address are selected. On every access, the SYM53C1010 compares its assigned base addresses with the value on the Address/Data bus during the PCI address phase. If the upper 24 bits match, the access is designated for the SYM53C1010. The low order eight bits define the register to be accessed. A decode of C_BE[3:0]/ determines which register and what type of access is performed.

2.1.1.2 I/O Space

The PCI specification defines I/O space as a contiguous 32-bit I/O address that is shared by all system resources, including the

SYM53C1010. [Base Address Register Zero \(BAR0\) \(I/O\)](#) determines which 256-byte I/O area this device occupies.

2.1.1.3 Memory Space

The PCI specification defines memory space as a contiguous 64-bit memory address that is shared by all system resources. [Base Address Register One \(BAR1\) \(MEMORY\)](#) determines which 1 Kbyte memory area this device occupies. Each SCSI function uses an 8 Kbyte SCRIPTS RAM memory space. [Base Address Register Two \(BAR2\) \(MEMORY\)](#) determines the 8 Kbyte memory area the SCRIPTS RAM occupies.

2.1.2 PCI Bus Commands and Functions Supported

Bus commands indicate to the target the type of transaction the master is requesting. Bus commands are encoded on the C_BE[3:0] lines during the address phase. PCI bus commands and encoding types appear in [Table 2.1](#).

Table 2.1 PCI Bus Commands and Encoding Types

C_BE[3:0]	Command Type	Supported as Master	Supported as Slave
0000	Interrupt Acknowledge	No	No
0001	Special Cycle	No	No
0010	I/O Read	Yes	Yes
0011	I/O Write	Yes	Yes
0100	Reserved	N/A	N/A
0101	Reserved	N/A	N/A
0110	Memory Read	Yes	Yes
0111	Memory Write	Yes	Yes
1000	Reserved	N/A	N/A
1001	Reserved	N/A	N/A
1010	Configuration Read	No	Yes
1011	Configuration Write	No	Yes
1100	Memory Read Multiple	Yes ¹	Yes (defaults to 0110)
1101	Dual Address Cycle (DAC)	Yes	Yes
1110	Memory Read Line	Yes ¹	Yes (defaults to 0110)
1111	Memory Write and Invalidate	Yes ²	Yes (defaults to 0111)

1. See the [DMA Mode \(DMODE\)](#) register.

2. See the [Chip Test Three \(CTEST3\)](#) register.

2.1.2.1 Interrupt Acknowledge Command

The SYM53C1010 does not respond to this command as a slave and it never generates this command as a master.

2.1.2.2 Special Cycle Command

The SYM53C1010 does not respond to this command as a slave and it never generates this command as a master.

2.1.2.3 I/O Read Command

The SYM53C1010 uses the I/O Read command to read data from an agent mapped in the I/O address space. All 64 address bits are decoded.

2.1.2.4 I/O Write Command

The SYM53C1010 uses the I/O Write command to write data to an agent mapped in the I/O address space. All 64 address bits are decoded.

2.1.2.5 Reserved Command

The given bus encoding is reserved.

2.1.2.6 Memory Read Command

The SYM53C1010 uses the Memory Read command to read data from an agent mapped in the Memory Address Space. The target may perform an anticipatory read if such a read produces no side effects.

2.1.2.7 Memory Write Command

The SYM53C1010 uses the Memory Write command to write data to an agent mapped in the Memory Address Space. When the target returns "ready", it assumes responsibility for data coherency, which includes ordering.

2.1.2.8 Configuration Read Command

The SYM53C1010 uses the Configuration Read command to read the configuration space of each agent. An agent is selected during a configuration access when its IDSEL signal is asserted and AD[1:0] are 0b00. During the address phase of a configuration cycle, AD[7:2] address one of the 64 Dword registers in the configuration space of each device. Byte enables address the individual bytes within each Dword. AD[10:8] indicate which device of a multifunction agent is being addressed. AD[63:11] are logical don't cares to the selected agent.

2.1.2.9 Configuration Write Command

The SYM53C1010 uses the Configuration Write command to transfer data to the configuration space of each agent. An agent is selected when

its IDSEL signal is asserted and AD[1:0] are 0b00. During the address phase of a configuration cycle, the AD[7:2] lines address the 64 Dword registers in the configuration space of each device. Individual byte enable commands address the bytes within each Dword. AD[63:11] are logical don't cares to the selected agent. AD[10:8] indicate which device of a multifunction agent is addressed.

2.1.2.10 Memory Read Multiple Command

This command is identical to the Memory Read command, except it additionally indicates that the master intends to fetch multiple cache lines before disconnecting. The SYM53C1010 supports PCI Memory Read Multiple functionality and issues Memory Read Multiple commands on the PCI bus when the Read Multiple mode is enabled. This mode is enabled by setting bit 2 (ERMP) of the [DMA Mode \(DMODE\)](#) register. If the cache mode is enabled, a Memory Read Multiple command is issued on all read cycles, except opcode fetches, when the following conditions are met:

- The CLSE bit (Cache Line Size Enable, bit 7, [DMA Control \(DCNTL\)](#) register) is set.
- The ERMP bit (Enable Read Multiple, bit 2, [DMA Mode \(DMODE\)](#) register) is set.
- The [Cache Line Size \(CLS\)](#) register for each function contains a legal burst size value (4, 8, 16, 32, 64, or 128 Dwords) that is less than or equal to the DMODE burst size.
- The transfer crosses a cache line boundary.

When these conditions are met, the chip issues a Memory Read Multiple command instead of a Memory Read during all PCI read cycles.

Burst Size Selection – The Read Multiple command reads in multiple cache lines of data during a single bus ownership. Revision 2.2 of the PCI specification specifies the number of cache lines to read as a multiple of the cache line size. The logic selects the largest multiple of the cache line size based on the amount of data to transfer. The maximum allowable burst size is determined from the [DMA Mode \(DMODE\)](#) burst size bits and the [Chip Test Five \(CTEST5\)](#) register, bit 2.

2.1.2.11 Dual Address Cycle (DAC) Command

When 64-bit addressing is required, the SYM53C1010 performs DACs, per the PCI 2.2 specification. If any of the selector registers contain a nonzero value, a DAC is generated.

2.1.2.12 Memory Read Line Command

This command is identical to the Memory Read command, except it additionally indicates that the master intends to fetch a complete cache line. This command is intended for use with bulk sequential data transfers where the memory system and the requesting master might gain some performance advantage by reading to a cache line boundary rather than a single memory cycle. The Read Line function in the SYM53C1010 takes advantage of the PCI 2.2 specification regarding issuance of this command.

If the cache mode is disabled, no Read Line commands are issued.

If the cache mode is enabled, a Read Line command is issued on all read cycles, except nonprefetch opcode fetches, when the following conditions are met:

- The CLSE bit (Cache Line Size Enable, bit 7, of the [DMA Control \(DCNTL\)](#) register) is set.
- The ERL bit (Enable Read Line, bit 3, of the [DMA Mode \(DMODE\)](#) register) is set.
- The [Cache Line Size \(CLS\)](#) register for each function must contain a legal burst size value (4, 8, 16, 32, 64, or 128 Dwords) that is less than or equal to the DMODE burst size.
- The transfer crosses a Dword boundary but not a cache line boundary.

When these conditions are met, the chip issues a Read Line command instead of a Memory Read during all PCI read cycles. Otherwise, it issues a normal Memory Read command.

Read Multiple with Read Line Enabled – When both the Read Multiple and Read Line modes are enabled, the Read Line command is not issued if the above conditions are met. Instead, a Read Multiple command is issued.

If the Read Multiple mode is enabled, Read Multiple commands are issued if the Read Multiple conditions are met.

2.1.2.13 Memory Write and Invalidate Command

The Memory Write and Invalidate command is identical to the Memory Write command, except it additionally guarantees a minimum transfer of one complete cache line. That is, the master intends to write all bytes within the addressed cache line in a single PCI transaction unless interrupted by the target. This command requires implementation of the PCI [Cache Line Size \(CLS\)](#) register. The SYM53C1010 enables Memory Write and Invalidate cycles when bit 0 (WRIE), in the [Chip Test Three \(CTEST3\)](#) register, and bit 4 (WIE), in the PCI [Command](#) register, are set.

When the following conditions are met, Memory Write and Invalidate commands are issued:

- The following bits are set:
 - the CLSE bit (Cache Line Size Enable, bit 7, of the [DMA Control \(DCNTL\)](#) register),
 - the WRIE bit (Write and Invalidate Enable, bit 0, of the [Chip Test Three \(CTEST3\)](#) register),
 - bit 4 of the PCI configuration [Command](#) register.
- The [Cache Line Size \(CLS\)](#) register for each function contains a legal burst size value (4, 8, 16, 32, 64, or 128 Dwords) that is less than or equal to the [DMA Mode \(DMODE\)](#) burst size.
- The chip has enough bytes in the DMA FIFO to complete at least one full cache line burst.
- The chip is aligned to a cache line boundary.

When these conditions are met, the SYM53C1010 issues a Write and Invalidate command instead of a Memory Write command during all PCI write cycles.

Multiple Cache Line Transfers – The Memory Write and Invalidate command can write multiple cache lines of data in a single bus ownership. The chip issues a burst transfer as soon as it reaches a cache line boundary. The transfer size is not automatically the cache line size, but rather a multiple of the cache line size specified in Revision 2.2

of the PCI specification. The logic selects the largest multiple of the cache line size based on the transfer size. The maximum allowable burst size is determined from the [DMA Mode \(DMODE\)](#) burst size bits, and bit 2 of the [Chip Test Five \(CTEST5\)](#) register. If multiple cache line size transfers are not desired, set the DMODE burst size to exactly the cache line size and the chip will only issue single cache line transfers.

After each data transfer, the chip re-evaluates the burst size based on the amount of remaining data to transfer. It again selects the highest possible multiple of the cache line size, and no larger than the [DMA Mode \(DMODE\)](#) burst size. Usually, the chip selects the DMODE burst size after alignment and issues bursts of this size. The burst size is, in effect, throttled down toward the end of a long Memory Move or Block Move transfer until only the cache line size left is burst size. The chip finishes the transfer with this burst size.

Latency – In accordance with the PCI specification, the latency timer is ignored when issuing a Memory Write and Invalidate command. Therefore, when a latency time-out occurs, the SYM53C1010 continues to transfer up to a cache line boundary. At that point, the chip relinquishes the bus, and finishes the transfer at a later time using another bus ownership. If the chip is transferring multiple cache lines it continues to transfer until the next cache boundary is reached.

PCI Target Retry – A retry is defined as a STOP with no TRDY/, indicating that no data was transferred. If the target issues a retry during a Memory Write and Invalidate transfer, the chip relinquishes the bus and immediately tries to finish the transfer on another bus ownership. The chip issues another Memory Write and Invalidate command on the next ownership, in accordance with the PCI specification.

PCI Target Disconnect – If the target device issues a disconnect during a Memory Write and Invalidate transfer, the SYM53C1010 relinquishes the bus and immediately tries to finish the transfer on another bus ownership. The chip does not issue another Memory Write and Invalidate command on the next ownership unless the address is aligned.

2.1.3 Internal Arbiter

The PCI to SCSI controller uses a single REQ/ - GNT/ signal pair to arbitrate for access to the PCI bus. An internal arbiter circuit allows the different bus mastering functions resident in the chip to arbitrate among

themselves for the privilege of arbitrating for PCI bus access. There are two independent bus mastering functions inside the SYM53C1010, one for each of the SCSI functions.

The internal arbiter uses a round robin arbitration scheme to decide which internal bus mastering function may arbitrate for access to the PCI bus. This ensures that no function is starved for access to the PCI bus.

2.1.4 PCI Cache Mode

The SYM53C1010 supports the PCI specification for an 8-bit [Cache Line Size \(CLS\)](#) register located in the PCI configuration space. The [Cache Line Size \(CLS\)](#) register provides the ability to sense and react to nonaligned addresses corresponding to cache line boundaries. In conjunction with the [Cache Line Size \(CLS\)](#) register, the PCI commands Memory Read Line (MRL), Memory Read Multiple (MRM), and Memory Write and Invalidate (MWI) are individually software enabled or disabled. Information on PCI cache mode alignment is provided in [Table 2.2](#).

2.1.4.1 Enabling Cache Mode

To enable the cache logic to issue PCI cache commands (Memory Read Line, Memory Read Multiple, and Memory Write and Invalidate) on any PCI master operation, the following conditions must be met:

- The Cache Line Size Enable bit in the [DMA Control \(DCNTL\)](#) register must be set.
- The PCI [Cache Line Size \(CLS\)](#) register must contain a valid binary cache size, i.e., 4, 8, 16, 32, 64, or 128 Dwords. These values are the only valid cache sizes.
- The programmed burst size (in Dwords) must be equal to or greater than the cache line size register. The [DMA Mode \(DMODE\)](#) register, bits [7:6], and the [Chip Test Five \(CTEST5\)](#) register, bit 2, denote the burst length.
- The device must be performing a PCI Master transfer. The following PCI Master transactions do not utilize the PCI cache logic so no PCI cache commands are issued during these types of cycles: a nonprefetch SCRIPTS fetch, a Load/Store data transfer, and a data flush operation. All other types of PCI Master transactions utilize the PCI cache logic.

Not only must the above four conditions be met in order for the cache logic to control the type of PCI cache command that is issued, proper alignment is also necessary during write operations. If these conditions are not met for any given PCI Master transaction, a Memory Read or Memory Write is issued and no cache write alignment is done.

2.1.4.2 Issuing Cache Commands

In order to issue each type of PCI cache command, the corresponding enable bit(s) must be set.

- To issue Memory Read Line commands, the Enable Read Line (ERL) bit in the [DMA Mode \(DMODE\)](#) register must be set.
- To issue Memory Read Multiples, the Enable Read Multiple (ERMP) bit in the [DMA Mode \(DMODE\)](#) register must be set.
- To issue Memory Write and Invalidates, both the Write and Invalidate Enable (WRIE) bit in the [Chip Test Three \(CTEST3\)](#) register and the Write and Invalidate Enable (WIE) bit in the PCI configuration [Command](#) register must be set.

If the corresponding cache command is not enabled, the cache logic falls back to the next command enabled. For example, if the Memory Read Multiple command is not enabled and the Memory Read Line command is, Memory Read Line command is issued in place of Memory Read Multiple command. If no cache commands are enabled, cache write alignment still occurs but no cache commands are issued; only Memory Reads and Memory Writes are issued.

2.1.4.3 Memory Read Caching

The type of Memory Read command issued depends on the starting location of the transfer and the number of bytes to be transferred. During reads, no cache alignment is done, as it is neither required nor optional according to PCI 2.2 specification. Reads are a programmed burst length in size, as set in the [DMA Mode \(DMODE\)](#) and [Chip Test Five \(CTEST5\)](#) registers. In the case of a transfer that is smaller than the burst length, all bytes for that transfer are read in one PCI burst transaction. If the transfer crosses a Dword boundary ($A[1:0] = 0b00$) a Memory Read Line command is issued. If the transfer crosses a cache boundary, as specified by the cache line size programmed into the PCI configuration register, a Memory Read Multiple command is issued. If a transfer does

not cross a Dword or cache boundary or if cache mode is not enabled a Memory Read command is issued.

2.1.4.4 Memory Write Caching

Memory Writes are aligned in a single burst transfer to reach a cache boundary. At that point, Memory Write and Invalidate commands are issued and continue at the burst length programmed into the [DMA Mode \(DMODE\)](#) register. Memory Write and Invalidate commands continue to be issued as long as the remaining byte count is greater than the Memory Write and Invalidate threshold. When the remaining byte count drops below this threshold, a single Memory Write burst is issued to complete the transfer.

In summary, the general pattern for PCI writes is:

- A single Memory Write to align to a cache boundary
- Multiple Memory Write and Invalidates
- A single data residual Memory Write to complete the transfer

Table 2.2 PCI Cache Mode Alignment

Host Memory				
		A		0x00
	B			0x04
				0x08
		C		0x0C
		D		0x10
				0x14
				0x18
				0x1C
		E		0x20
				0x24
				0x28
				0x2C
			F	0x30
				0x34
				0x38
				0x3C
	G			0x40
				0x44
				0x48
				0x4C
		H		0x50
				0x54
				0x58
				0x5C
				0x60

2.1.4.5 Examples

MR = Memory Read, MRL = Memory Read Line, MRM = Memory Read, Multiple, MW = Memory Write, MWI = Memory Write and Invalidate.

Read Example 1 – Burst = 4 Dwords, Cache Line Size = 4 Dwords:

A to B: MRL (6 bytes)
A to C: MRL (13 bytes)
A to D: MRM (16 bytes)
MR (1 byte)
C to D: MRM (5 bytes)
C to E: MRM (16 bytes)
MRM (5 bytes)
D to F: MRM (16 bytes)
MRM (16 bytes)
A to H: MRM (16 bytes)
MRM (16 bytes)
MRM (16 bytes)
MRM (16 bytes)
MRM (16 bytes)
MR (1 byte)
A to G: MRM (16 bytes)
MRM (16 bytes)
MRM (16 bytes)
MRM (16 bytes)
MR (2 bytes)

Read Example 2 – Burst = 8 Dwords, Cache Line Size = 4 Dwords:

A to B: MRL (6 bytes)
A to C: MRL (13 bytes)
A to D: MRM (17 bytes)
C to D: MRM (5 bytes)
C to E: MRM (21 bytes)
D to F: MRM (32 bytes)
A to H: MRM (32 bytes)
MRM (32 bytes)
MRM (17 bytes)
A to G: MRM (32 bytes)
MRM (32 bytes)
MR (2 bytes)

Read Example 3 – Burst = 16 Dwords, Cache Line Size = 8 Dwords:

A to B: MRL (6 bytes)
A to C: MRL (13 bytes)
A to D: MRL (17 bytes)
C to D: MRL (5 bytes)
C to E: MRM (21 bytes)
D to F: MRM (32 bytes)
A to H: MRM (64 bytes)
MRL (17 bytes)
A to G: MRM (64 bytes)
MR (2 bytes)

Write Example 1 – Burst = 4 Dwords, Cache Line Size = 4 Dwords:

- A to B:** MW (6 bytes)
- A to C:** MW (13 bytes)
- A to D:** MW (17 bytes)
- C to D:** MW (5 bytes)
- C to E:** MW (3 bytes)
MWI (16 bytes)
MW (2 bytes)
- D to F:** MW (15 bytes)
MWI (16 bytes)
MW (1 byte)
- A to H:** MW (15 bytes)
MWI (16 bytes)
MWI (16 bytes)
MWI (16 bytes)
MWI (16 bytes)
MW (2 bytes)
- A to G:** MW (15 bytes)
MWI (16 bytes)
MWI (16 bytes)
MWI (16 bytes)
MW (3 bytes)

Write Example 2 – Burst = 8 Dwords, Cache Line Size = 4 Dwords:

A to B: MW (6 bytes)
A to C: MW (13 bytes)
A to D: MW (17 bytes)
C to D: MW (5 bytes)
C to E: MW (3 bytes)
MWI (16 bytes)
MW (2 bytes)
D to F: MW (15 bytes)
MWI (16 bytes)
MW (1 byte)
A to H: MW (15 bytes)
MWI (32 bytes)
MWI (32 bytes)
MW (2 bytes)
A to G: MW (15 bytes)
MWI (32 bytes)
MWI (16 bytes)
MW (3 bytes)

Write Example 3 – Burst = 16 Dwords, Cache Line Size = 8 Dwords:

A to B: MW (6 bytes)
A to C: MW (13 bytes)
A to D: MW (17 bytes)
C to D: MW (5 bytes)
C to E: MW (21 bytes)
D to F: MW (32 bytes)
A to H: MW (31 bytes)
MWI (32 bytes)
MW (18 bytes)
A to G: MW (31 bytes)
MWI (32 bytes)
MW (3 bytes)

2.1.4.6 Memory-to-Memory Moves

Memory-to-Memory moves also support PCI cache commands, as described above, with one limitation: Memory Write and Invalidate on Memory-to-Memory move writes are only supported if the source and destination address are quad word aligned. If the source and destination are not quad word aligned, i.e., $\text{Source Address}[2:0] \neq \text{Destination Address}[2:0]$, write alignment is not performed and Memory Write and Invalidates are not issued.

The SYM53C1010 is little endian. This mode assigns the least significant byte to bits [7:0].

2.2 SCSI Functional Description

Both Ultra3 SCSI controllers on the SYM53C1010 provide a SCSI function that supports either an 8-bit or 16-bit bus. Each controller supports Wide Ultra3 SCSI synchronous transfer rates up to 160 Mbytes/s on a LVD SCSI bus. SCSI functions can be programmed with SCSI SCRIPTS, making it easy to “fine tune” the system for specific mass storage devices or Ultra3 SCSI requirements. [Figure 2.1](#) illustrates the relationship between the SYM53C1010 modules.

The SYM53C1010 offers low level register access or a high level control interface. Like first generation SCSI devices, the SYM53C1010 is accessed as a register-oriented device. The ability to sample and/or assert any signal on the SCSI bus is used in error recovery and diagnostic procedures.

The SYM53C1010 is controlled by the integrated SCRIPTS processor through a high level logical interface. Commands controlling the SCSI functions are fetched out of the main host memory or local memory. These commands instruct the SCSI functions to Select, Reselect, Disconnect, Wait for a Disconnect, Transfer Information, Change Bus Phases, and implement all other aspects of the SCSI protocol. The SCRIPTS processor is a special high speed processor optimized for SCSI protocol.

2.2.1 SCRIPTS Processor

The SCSI SCRIPTS processor allows fetches of both DMA and SCSI commands from host memory or internal SCRIPTS RAM. Algorithms written in SCSI SCRIPTS control the actions of the SCSI and DMA cores. The SCRIPTS processor, running off of the PCI clock, executes complex SCSI bus sequences independently of the host CPU.

Algorithms can be designed to tune SCSI bus performance to adjust to new bus device types, such as scanners, communication gateways, etc. They can also incorporate changes in the SCSI logical bus definitions without sacrificing I/O performance. SCSI SCRIPTS are hardware independent, so they can be used interchangeably on any host or CPU system bus. SCSI SCRIPTS handle conditions such as Phase Mismatch.

2.2.1.1 Phase Mismatch Handling in SCRIPTS

The SYM53C1010 can handle phase mismatches due to drive disconnects without needing to interrupt the processor. The primary goal of this logic is to completely eliminate the need for CPU intervention during an I/O disconnect/reselect sequence.

SCRIPTS control the storage of appropriate information needed to restart the I/O state, eliminating the need for processor intervention during an I/O disconnect/reselect sequence. Calculations are performed such that the appropriate information is available to SCRIPTS so that an I/O state can be properly stored for restart later.

The Phase Mismatch Jump logic is disabled at power-up. It must be enabled by setting the Phase Mismatch Jump Enable bit (ENPMJ, bit 7 in the [Chip Control Zero \(CCNTL0\)](#) register). Utilizing the information supplied in the Phase Mismatch Jump Address registers allows all overhead involved in a disconnect/reselect sequence to be handled with a modest amount of SCRIPTS instructions. These registers are described in detail in [Chapter 4, "Registers"](#).

2.2.2 Internal SCRIPTS RAM

The SYM53C1010 has 8 Kbytes (2048 x 32 bits) of internal, general purpose RAM for each SCSI function. The RAM is designed for SCRIPTS program storage, but is not limited to this type of information. When the chip fetches SCRIPTS instructions or Table Indirect

information from the internal RAM, these fetches remain internal to the chip and do not use the PCI bus. In addition, any SCRIPTS instruction that contains a source or destination address residing in SCRIPTS RAM memory space remains internal to the chip and does not generate PCI cycles. SCRIPTS instructions able to access SCRIPTS RAM memory space in this manner include Memory-to-Memory moves, Load/Stores, and Block Moves. While an internal cycle is occurring, any external PCI slave cycle is retried on the PCI bus. Setting the DISRC (Disable Internal SCRIPTS RAM Cycles) bit in the [Chip Control Zero \(CCNTL0\)](#) register disables this feature.

SCRIPTS RAM should be initialized before it is read. Reading SCRIPTS RAM before initialization will result in the SCRIPTS RAM parity bit, bit 7, being set in the [Shadowed SCSI SGE Status 0](#) register.

PCI system BIOS can relocate the RAM anywhere in the 64-bit address space. [Base Address Register Three \(BAR3\) \(SCRIPTS RAM\)](#) and [Base Address Register Four \(BAR4\) \(SCRIPTS RAM\)](#), in the PCI configuration space, contain the base address of the internal RAM. To simplify SCRIPTS instruction loading, the base address of the RAM appears in the [Scratch Register B \(SCRATCHB\)](#) register when bit 3 of the [Chip Test Two \(CTEST2\)](#) register is set. The upper 32 bits of a 64-bit base address are in the [SCRIPT Fetch Selector \(SFS\)](#) register. The RAM is byte accessible from the PCI bus and is visible to any bus mastering device on the bus. External, CPU accesses to the RAM follow the same timing sequence as a standard slave register access, except that the required target wait-states drop from 5 to 3. SCRIPTS RAM must first be written before being read in order to initialize SCRIPTS RAM parity. If a SCRIPTS RAM parity error is encountered a SCSI Gross Error interrupt will be signaled.

A complete set of development tools is available for writing custom drivers with SCSI SCRIPTS. For more information on the SCSI SCRIPTS instructions supported by the SYM53C1010, see [Chapter 5, "SCSI SCRIPTS Instruction Set"](#).

2.2.3 64-Bit Addressing in SCRIPTS

The PCI interface for the SYM53C1010 provides 64-bit address and data capability in the initiator mode. The chip can also respond to 64-bit addressing in the target mode.

DACs can be generated for all SCRIPTS operations. There are six selector registers which hold the upper Dword of a 64-bit address. All but one of these is static and requires manual loading using a CPU access, a Load and Store instruction, or a Memory Move instruction. One of the selector registers is dynamic and is used during 64-bit direct block moves only. All selectors will default to zero, meaning the SYM53C1010 will power-up in a state where only Single Address Cycles (SACs) are generated. When any of the selector registers are written to a nonzero value, DACs are generated.

Direct, Table Indirect and Indirect Block Moves, Memory-to-Memory Moves, Load/Stores, and Jumps are all instructions with 64-bit address capability.

Note: Crossing the 4 Gbyte boundary on any one SCRIPTS operation is not permitted. Therefore, software must handle all such transactions.

2.2.4 Hardware Control of SCSI Activity LED

The SYM53C1010 controls an LED through the GPIO_0 pin to indicate that it is connected to the SCSI bus. This function was previously handled by a software driver.

Bit 3 (CON), in the [Interrupt Status Zero \(ISTAT0\)](#) register, is presented at the GPIO_0 pin when the following occurs:

- Bit 5 (LED_CNTL) in the [General Purpose Pin Control \(GPCNTL\)](#) register is set,
- Bit 6 (Fetch Enable) in the [General Purpose Pin Control \(GPCNTL\)](#) register is cleared,
- the SYM53C1010 is not performing an EEPROM autownload.

The CON (Connected) bit in [Interrupt Status Zero \(ISTAT0\)](#) register is set anytime the SYM53C1010 is connected to the SCSI bus either as an initiator or a target. This happens after the SYM53C1010 has successfully completed a selection or when it has successfully responded to a selection or reselection. It will also be set when the SYM53C1010 wins arbitration in low level mode.

2.2.5 Designing an Ultra3 SCSI System

Software modifications are needed to take advantage of the Ultra3 speed in the SYM53C1010. Since Ultra3 SCSI is based on existing SCSI standards, it can use existing drivers if they are able to negotiate for Ultra3 synchronous transfer rates. Also, the target device must be able to communicate at Ultra3 speed. The SYM53C1010 uses Domain Validation to determine whether or not the system is capable of Ultra3 SCSI before activating DT clocking. Refer to [Section 2.2.5.1, “Ultra160 SCSI Features,”](#) for more information on DT clocking.

LVD SCSI fulfills the hardware requirements for Ultra3 SCSI transfer rates, increased cable lengths, and additional devices on the bus. All devices on the bus must have LVD SCSI capabilities to guarantee Ultra3 SCSI transfer rates. For additional information on Ultra3 SCSI, refer to the SCSI Parallel Interface-3 (SPI-3) working document that is available on the world wide web at the T10 Home Page, <http://www.t10.org>. Also, check the SCSI Trade Association web site at <http://www.scsita.org/>. [Chapter 6, “Specifications”](#) contains Ultra3 SCSI timing information. In addition to the guidelines in the draft standard, make the following software adjustments to accommodate Ultra3 SCSI transfers.

2.2.5.1 Ultra160 SCSI Features

Domain Validation – A procedure where a host queries a device to determine its ability to communicate at the negotiated Ultra3 data rate. In software, the following steps are performed to ensure the selected device can successfully transfer data at the negotiated speed.

- Step 1. Select a device.
- Step 2. Issue Inquiry command.
- Step 3. Issue Parallel Protocol Request (PPR) message.
- Step 4. Issue Write Buffer command.
- Step 5. Issue Read Buffer command.
- Step 6. Examine the data pattern to ensure validity.

If the commands complete successfully with no CRC errors, bus hangs, or data pattern errors, then the negotiated speed is valid.

CRC – The error detecting code used in Ultra3 SCSI. Four bytes are transferred with data to increase the reliability of data transfers. CRC is used in the DT Data-In and DT Data-Out phases only. Because CRC is implied with DT mode and only works with DT mode, the DT setting can be used for CRC.

DT Clocking – Ultra3 SCSI implements DT clocking to provide speeds up to 80 megatransfers/s. DT clocking means that the data is sampled on both the asserting and deasserting edge of REQ/ACK. DT clocking is only valid using a LVD SCSI bus.

In order to support DT clocking, there are two new phases for the SCSI bus. The old Data-In and Data-Out phases are now called Single Transition (ST) Data-In and ST Data-Out. The new phases are DT Data-In and DT Data-Out. The use of DT and ST phases implies that the SCRIPTS engine may use a different jump point for DT or ST. [Table 2.3](#) illustrates SCSI signal configuration for these phases.

Table 2.3 New Phases on SCSI Bus

Phase	MSG	C/D	I/O	Description
ST Data-Out	0	0	0	–
ST Data-In	0	0	1	–
DT Data-Out	1	0	0	Previously reserved
DT Data-In	1	0	1	Previously reserved

To indicate DT or ST mode, a bit is set in the current “selection” data reserved byte. BMOVE instructions identify the current BMOVE as either DT or ST through the phase bits.

2.2.5.2 Parallel Protocol Request (PPR)

CRC, Sync/Wide, DT, QAS, and “information units” are negotiated with a new SCSI extended message:

Byte 0	0x01	Extended message
Byte 1	0x06	Length
Byte 2	0x04	PPR
Byte 3	0xXX	Transfer Period Factor
Byte 4	0x00	Reserved
Byte 5	0xXX	REQ/ACK Offset
Byte 6	0xXX	Transfer Width Exponent
Byte 7	0x0X	Protocol options

Transfer Period Factor (Byte 3) – Transfer Period Factor is the old Synchronous Period value. These are the same with one addition for 80 megatransfers/s rate:

0x09	=	12.5 ns (Ultra3 SCSI) only valid when using DT
0x0A	=	25 ns (Ultra2 SCSI)
0x0B	=	30.3 ns
0x0C	=	50 ns (Ultra SCSI)
0x0D–0xFF	=	$value \times 4 = Period$ in ns

The transfer period is related to the data transfer speed, NOT the clock period. So, in DT mode, 0x09 means 12.5 ns between clock edges which really means a 25 ns clock period. In DT mode, 0x0A would mean a clock period of 50 ns but a data rate of 40 megatransfers/s (25 ns). In ST mode, 0x0A would mean a clock period of 25 ns and a data rate of 40 megatransfers/s.

REQ/ACK Offset (Byte 5) – REQ/ACK Offset is the maximum SCSI offset.

Transfer Width Exponent (Byte 6) – Transfer Width Exponent is the old width value. It is set to 0 (8-bit SCSI width) or 1 (16-bit SCSI width).

Note: For DT mode or when the Protocol Options field is nonzero, the Transfer Width Exponent must be one indicating a SCSI width of 16-bits.

The Table Indirect data (used during selection/reselection) must be updated to enable certain control bits in the [SCSI Control Four \(SCNTL4\)](#) register. Specific bits to look at include: bit 7, U3EN (Ultra3 Transfer Enable); bit 6, AIPEN (Asynchronous Information Protection Enable); and bits [3:0] (extra clock setup/hold).

The Protocol Options are described in [Table 2.4](#).

Table 2.4 Protocol Options (Byte 7)

OAS_REQ	DT_REQ	IU_REQ	Description
0	0	0	Use ST Data-In and ST Data-Out phase to transfer data
0	1	0	Use DT Data-In and DT Data-Out phase to transfer data with CRC
0	1	1	Use DT Data-In and DT Data-Out phase to transfer data with information units
1	1	0	Use DT Data-In and DT Data-Out phase to transfer data with CRC and use the QAS method for arbitration
1	1	1	Use DT Data-In and DT Data-Out phase to transfer data with information units and use the QAS method for arbitration

A bus or device reset, power cycle, or change between LVD/SE modes invalidates these settings. A renegotiation resets the Protocol Options.

2.2.5.3 Asynchronous Information Protection (AIP)

The AIP feature provides error checking for asynchronous, nondata phases through BCH encoding. During the command, status, message in/out phases, the BCH code is transferred on the upper SCSI data bus. For details on the BCH code, see T10 119r3 document *Protection for the Asynchronous Phases*.

The AIP error status and the live AIP code values are captured in the [AIP Control One \(AIPCNTL1\)](#) register for debug purposes. AIP checking

and generation are enabled by setting bit 6 in the [SCSI Control Four \(SCNTL4\)](#) register.

The sequence ID is reset on any phase change, chip reset, bus free, or synchronous phase. It is also reset by writing the RSQAIP bit in the [AIP Control Zero \(AIPCNTL0\)](#) register. The AIP sequence value can be read using this register (the SEQAIP bits).

All AIP errors are treated in the same fashion as parity errors. Bit 0 of the [SCSI Interrupt Status Zero \(SIST0\)](#) register indicates if SCSI parity, CRC, or AIP errors are present. The LAIPERR bit in the [AIP Control One \(AIPCNTL1\)](#) register indicates if the error is an AIP error.

2.2.5.4 Register Considerations

The following is a summary of the registers and bits required to enable Ultra3 SCSI on the SYM53C1010 device.

- The PCI [Device ID](#) register value must be 0x20.
- The PCI [Max_Lat \(ML\)](#) register contains a value of 0x12, indicating it requires the bus every 4.5 μ s.
- The [SCSI Control Zero \(SCNTL0\)](#) register:
 - Bit 3, EPC (Enable Parity/CRC/AIP Checking) is set to enable the CRC feature.
 - Bit 1, AAP (Assert SATN/ on Parity/CRC/AIP Error), is set in the initiator mode to automatically assert SATN/ on the detection of an error.
- The [SCSI Control One \(SCNTL1\)](#) register:
 - Bit 5, DHP (Disable Halt on Parity/CRC/AIP Error or ATN) (Target Only), is set in accordance with user requirements. When bit 5 is cleared, a SCSI transfer halts if an error occurs. When bit 5 is set, a SCSI transfer continues if an error occurs.
- The [SCSI Control Three \(SCNTL3\)](#) register:
 - Bit 7 is now reserved. It was previously the Ultra Enable bit.
 - Bits [6:4], SCF[2:0] (Synchronous Clock Conversion Factor), select the divisor of the SCLK frequency. The SCLK is divided before its presentation to the synchronous SCSI control logic.

- Bit 3, EWS (Enable Wide SCSI), is set to enable wide SCSI. Ultra3 requires wide SCSI. Therefore, this bit must be set during these transfers.
- Bits [2:0] are reserved.
- The [SCSI Transfer \(SXFER\)](#) register:
 - Bits [7:6] are reserved.
 - Bits [5:0], MO[5:0] (Max SCSI synchronous offset), are set for the maximum offset.
- The [SCSI Status Two \(SSTAT2\)](#) register:
 - Bit 2 is reserved. HVD SCSI is not supported.
- The [SCSI Interrupt Enable Zero \(SIEN0\)](#) register:
 - Bit 0, PAR (SCSI Parity/CRC/AIP Error), is set to detect a Parity/CRC/AIP error while receiving or sending SCSI data. For more information, see [SCSI Control One \(SCNTL1\)](#), bit 5.
- The [Chip Control Three \(CCNTL3\)](#) register:
 - Bit 4, ENDSKEW (Enable REQ/ACK to Data skew control) is set to enable control of the relative skew between the SCSI REQ/ACK signal and the data signals.
 - Bits [3:2], DSKEW[1:0] (REQ/ACK – Data skew control), control the amount of skew between the SCSI REQ/ACK signal and the SCSI data signals. These bits are used for Ultra3 SCSI Domain Validation only and control the skew only if bit 4 is set.
 - Bits [1:0], LVDDL[1:0] (LVD Drive strength select), control the drive level of the LVD pad drivers. This feature is intended for use in Ultra3 SCSI Domain Validation testing environments only. These bits should be set to 0b00 during normal operation.
- The [SCSI Control Four \(SCNTL4\)](#) register:
 - Bit 7, U3EN (Ultra3 Transfer Enable) is set to enable Ultra3 transfers.
 - Bit 6, AIPEN (Asynchronous Information Protection Enable), is set to enable checking and generation of the upper byte lane of protection information during Command, Status and Message Phases.
 - Bit [5:4] are reserved.

- Bit 3, XCLKH_DT (Extra Clock of Data Hold on DT Transfer Edge) is set to add a clock of data hold to synchronous DT SCSI transfers on the DT edge.
- Bit 2, XCLKH_ST (Extra Clock of Data Hold on ST Transfer Edge) is set to add a clock of data hold to synchronous DT or ST SCSI transfers on the ST edge. This bit impacts both ST and DT transfers as it affects data hold to the ST edge.
- Bit 1, XCLKS_DT (Extra Clock of Data Setup on DT Transfer Edge) is set to add a clock of data setup to synchronous DT SCSI transfers on the DT edge. This bit only impacts DT transfers as it affects data setup to the DT edge.
- Bit 0, XCLKS_ST (Extra Clock of Data Setup on ST Transfer Edge) is set to add a clock of data setup to synchronous DT or ST SCSI transfers on the ST edge. This bit impacts both ST and DT transfers as it affects data setup to the ST edge.

Note: The XCLKH_DT, XCLKH_ST, XCLKS_DT, and XCLKS_ST bits do not affect CRC timings.

- The [AIP Control Zero \(AIPCNTL0\)](#) register:
 - Bit 7, FBAIP (Force Bad AIP Parity value), forces bad AIP values to be sent over the SCSI bus.
 - Bit 6, RSQAIP (Reset AIP Sequence value), resets the sequence value used in the protection code calculation.
 - Bits [5:4], SEQAIP (AIP Sequence value), contain the current AIP sequence value.
 - Bits [3:0] are reserved.
- The [AIP Control One \(AIPCNTL1\)](#) register:
 - Bit 7, AIPERR (AIP Error Status), indicates the live value of the AIP checking logic error status.
 - Bit 6, LAIPERR (Latched AIP Error Status), represents the latched version of the AIP checking logic.
 - Bits [5:0], AIPV (AIP Value), indicate the current, calculated protection code value.
- The [CRC Pad Byte Value \(CRCPAD\)](#) register:
 - Bits [15:0], the CRC Pad byte value, contain the value placed onto the bus for the CRC pad bytes.

- The [CRC Control Zero \(CRCNTL0\)](#) register:
 - Bit 7, DISCRCCK (Disable CRC Checking), is set to cause the internal logic to not check or report CRC errors during Ultra3 transfers. The device continues to calculate and send CRC's as requested by the target per SPI-3 specification.
 - Bit 6, DISCRC (Disable CRC protocol checking) causes the SYM53C1010 to not check for a CRC request prior to a phase change on the SCSI bus. This condition creates a SCSI error condition and makes the device noncompliant with the SPI-3 specification. This bit should not be set under normal operating conditions.
 - Bit 5, RSTCRCINT (Reset CRC Interval Counter) resets the internal CRC interval counter to zero.
 - Bit 4 is reserved.
 - Bits [3:0], CRCINT[3:0] (CRC Request Interval (Target Mode only)), determine when a CRC request is sent by the device when operating in target mode and transferring data in DT Data-In or DT Data-Out Phases.
- The [CRC Control One \(CRCNTL1\)](#) register:
 - Bit 7, CRCERR (CRC Error), indicates whether or not a CRC error has been detected during a DT Data-In SCSI transfer. This bit is independent of the DISCRCCHK bit setting. To clear this condition, either write this bit to a one or read the [SCSI Interrupt Status Zero \(SIST0\)](#) and [SCSI Interrupt Status One \(SIST1\)](#) registers. When CRC checking and the Parity/CRC/AIP Error interrupt are both enabled, CRCERR is mirrored in the SIST0 register, bit 0, as a Parity/CRC/AIP error.
 - Bit 6 is reserved.
 - Bit 5, ENAS (Enable CRC Auto Seed), is set to cause the CRC logic to automatically reseed itself after every CRC check performed during DT Data-In SCSI transfers. When this bit is cleared, the SCSI control logic controls when the CRC logic is reseeded.
 - Bit 4, TSTSD (Test CRC Seed), is set to cause the CRC logic to immediately reseed itself. This bit should never be set during normal operation as it may cause corrupt CRCs to be generated.

- Bit 3, TSTCHK (Test CRC Check), is set to cause the CRC logic to initiate a CRC check. This bit should never be set during normal operation as it creates spurious CRC errors.
- Bit 2, CRCADD (CRC Accumulate), is set to cause the CRC block to include the value present in the input register in the current CRC calculation. A new output CRC value results. This bit should not be set during normal operation as corrupt CRC values result.
- Bits [1:0], CRCDSEL[1:0] (CRC Data Register Selector), control the data visible in the CRC Data register (located at 0xE0).
- The [CRC Data \(CRCD\)](#) register:
 - Bits [31:0] CRCDATA (CRC Data). The value in this register is dependent upon the setting of the CRCDSEL bits.

2.2.5.5 Using the SCSI Clock Quadrupler

The SYM53C1010 can quadruple the frequency of a 40 MHz SCSI clock, allowing the system to perform Ultra3 SCSI transfers. This option is user selectable with bit settings in the [SCSI Test One \(STEST1\)](#), [SCSI Test Three \(STEST3\)](#), and [SCSI Control Three \(SCNTL3\)](#) registers. At power-on or reset, the quadrupler is disabled and powered down. Follow these steps to use the clock quadrupler:

1. Set the SCLK Quadrupler Enable bit ([SCSI Test One \(STEST1\)](#) register, bit 3).
2. Do not poll bit 5 of the [SCSI Test Four \(STEST4\)](#) register. Bit 5 is reserved. Use a delay of 50 μ s after the quadrupler enable bit is set in Step 1.
3. Halt the SCSI clock by setting the Halt SCSI Clock bit ([SCSI Test Three \(STEST3\)](#) register, bit 5).
4. Set the clock conversion factor using the SCF (Synchronous Clock Conversion Factor) field in the [SCSI Control Three \(SCNTL3\)](#) register.
5. Set the SCLK Quadrupler Select bit ([SCSI Test One \(STEST1\)](#), bit 2).
6. Clear the Halt SCSI Clock bit.

2.2.6 Prefetching SCRIPTS Instructions

The prefetch logic in the SYM53C1010 fetches 8 Dwords of instructions when enabled by setting the Prefetch Enable bit (bit 5) in the [DMA Control \(DCNTL\)](#) register. The maximum burst size that can be performed is automatically determined using the burst length values in the [DMA Mode \(DMODE\)](#) register. If the unit cannot perform bursts of at least four Dwords, it disables itself. While the chip is prefetching SCRIPTS instructions, it uses the PCI cache commands Memory Read Line and Memory Read Multiple, if PCI caching is enabled.

Note: This feature is only useful when fetching SCRIPTS instructions from main memory. Due to the short access time of SCRIPTS RAM, prefetching is not necessary when fetching instructions from SCRIPTS RAM.

To ensure the SYM53C1010 always operates from the current version of the SCRIPTS instruction, the contents of the prefetch unit may be flushed under certain conditions. The contents of the prefetch unit are automatically flushed under the following conditions:

- On every Memory Move instruction
The Memory Move instruction is used to place modified code into memory. To assure the device executes recent modifications, the prefetch unit flushes its contents and reloads the code each time an instruction is issued. To avoid inadvertently flushing the prefetch unit contents, use the No Flush option for all Memory Move operations that do not modify code within the next 8 Dwords. For more information refer to [Chapter 5, "SCSI SCRIPTS Instruction Set"](#).
- On every Store instruction
The Store instruction may also be used to place modified code directly into memory. To avoid inadvertently flushing the prefetch unit contents use the No Flush option for all Store operations that do not modify code within the next 8 Dwords.
- On every write to the [DMA SCRIPTS Pointer \(DSP\)](#) register
- On all Transfer Control instructions, when the transfer conditions are met

This is necessary since the next instruction to be executed is not the sequential next instruction in the prefetch unit.

- When the Prefetch Flush bit ([DMA Control \(DCNTL\)](#) register, bit 6) is set

The unit flushes whenever this bit is set. This bit is self-clearing.

2.2.7 Opcode Fetch Burst Capability

Setting the Burst Opcode Fetch Enable bit (bit 1) in the [DMA Mode \(DMODE\)](#) register (0x38) causes the SYM53C1010 to burst in the first two Dwords of all instruction fetches. If the instruction is a Memory-to-Memory Move, the third Dword is accessed in a separate ownership. If the instruction is an indirect type, the additional Dword is accessed in a subsequent bus ownership. If the instruction is a Table Indirect Block Move, the device uses two accesses, each a two Dword burst, to obtain the four Dwords required.

Note: This feature is only useful if Prefetching is disabled.

This feature is only useful if fetching SCRIPTS instructions from main memory. Due to the short access time of SCRIPTS RAM, burst opcode fetching is not necessary when fetching instructions from SCRIPTS RAM.

2.2.8 Load and Store Instructions

The SYM53C1010 supports the Load and Store instruction type, which simplifies data movement between memory and the internal registers. It also enables the chip to transfer bytes to addresses relative to the [Data Structure Address \(DSA\)](#) register. Load and Store data transfers to or from the SCRIPTS RAM remain internal to the chip and do not generate PCI bus cycles. While a Load/Store to or from SCRIPTS RAM is occurring, any external PCI slave cycles that occur are retried on the PCI bus. Setting the DISRC (Disable Internal SCRIPTS RAM Cycles) bit in the [Chip Control Zero \(CCNTL0\)](#) register disables this feature. For more information on the Load and Store instructions, refer to [Chapter 5, “SCSI SCRIPTS Instruction Set”](#).

2.2.9 JTAG Boundary Scan Testing

With one exception, the SYM53C1010 includes support for JTAG boundary scan testing in accordance with the IEEE 1149.1 specification. The exception concerns the TST_RSTN pin. This pin must not be toggled as it will reset the JTAG TAP controller. For more information, refer to the BSDL (Boundary Scan Descriptor Language) file.

This device accepts all required boundary scan instructions including the optional CLAMP, HIGH-Z, and IDCODE instructions. The optional JTAG pin TRST is not implemented. Reset of the JTAG logic through the TAP controller occurs when TMS is held high for at least 5 TCK clock cycles.

The SYM53C1010 uses an 8-bit instruction register to support all boundary scan instructions. The data registers included in the device are the Boundary Data register, the IDCODE register, and the Bypass register. This device can handle a 20 MHz TCK frequency with all TAP pins having a 50% duty cycle.

2.2.10 Parity/CRC/AIP Options

The SYM53C1010 implements a flexible parity scheme that permits control of the parity sense, allows parity checking to be turned on or off, and can deliberately send a byte with bad parity over the SCSI bus. [Table 2.5](#) defines the bits that are involved in parity control and observation. [Table 2.6](#) describes the parity control function of the Enable Parity Checking and Assert SCSI Even Parity bits in the [SCSI Control One \(SCNTL1\)](#) register, bit 2.

SCRIPTS RAM must first be written before being read in order to initialize SCRIPTS RAM parity. If a SCRIPTS RAM parity error is encountered, a SCSI Gross Error interrupt will be signaled.

The SYM53C1010 supports CRC checking and generation in DT phases and CRC checking and generation during DT Data Transfers.

The new CRC registers are [CRC Pad Byte Value \(CRCPAD\)](#), [CRC Control Zero \(CRCCNTL0\)](#), [CRC Control One \(CRCCNTL1\)](#), [CRC Data \(CRCD\)](#), [SCSI Control Zero \(SCNTL0\)](#), bit 3; EPC (Enable Parity/CRC/AIP checking), bit 1; AAP (Assert SATN/ on Parity/CRC/AIP error); [SCSI Control One \(SCNTL1\)](#), bit 5; DHP (Disable Halt on

Parity/CRC/AIP Error or ATN), and [SCSI Interrupt Enable Zero \(SIEN0\)](#), bit 0, (SCSI Parity/CRC/AIP Error).

The new AIP registers are [SCSI Control Zero \(SCNTL0\)](#), [AIP Control Zero \(AIPCNTL0\)](#), and [AIP Control One \(AIPCNTL1\)](#).

Table 2.5 Bits Used for Parity/CRC/AIP Control and Generation

Bit Name	Location	Description
AAP (Assert SATN/ on Parity/CRC/AIP Errors)	SCSI Control Zero (SCNTL0), Bit 1	When this bit is set, the SYM53C1010 SCSI function automatically asserts the SATN/ signal upon detection of a parity, CRC, or AIP error. SATN/ is only asserted in initiator mode.
EPC (Enable Parity/CRC/AIP Checking)	SCSI Control Zero (SCNTL0), Bit 3	When set, this bit enables parity checking on the SYM53C1010. The SYM53C1010 checks for odd parity.
Assert Even SCSI Parity	SCSI Control One (SCNTL1), Bit 2	When set, this bit forces even SCSI parity on each byte sent to the SCSI bus from the SYM53C1010.
Disable Halt on SATN/ or Parity/CRC/AIP Error (Target Mode Only)	SCSI Control One (SCNTL1), Bit 5	This bit determines if the SYM53C1010 should halt operations when a parity error is detected in target mode.
Enable Parity/CRC/AIP Error Interrupt	SCSI Interrupt Enable Zero (SIEN0), Bit 0	This bit determines whether the SYM53C1010 generates an interrupt when it detects a SCSI Parity/CRC/AIP error.
Parity Error	SCSI Interrupt Status Zero (SIST0), Bit 0	This status bit is set whenever the SYM53C1010 detects a Parity/CRC/AIP error on the SCSI bus.
Status of SCSI Parity Signal	SCSI Status Zero (SSTAT0), Bit 0	This status bit represents the active HIGH current state of the SCSI SDP0 parity signal.
SCSI SDP1 Signal	SCSI Status Two (SSTAT2), Bit 0	This bit represents the active HIGH current state of the SCSI SDP1 parity signal.
Latched SCSI Parity	SCSI Status Two (SSTAT2), Bit 3 SCSI Status One (SSTAT1), Bit 3	These bits reflect the SCSI odd parity signal corresponding to the data latched into the SCSI Input Data Latch (SIDL) register.
Master Parity Error Enable	Chip Test Four (CTEST4), Bit 3	This bit enables parity checking during PCI master data phases.
Master Data Parity Error	DMA Status (DSTAT), Bit 6	This bit is set when the SYM53C1010, as a PCI master, detects a target device signaling a parity error during a data phase.
Master Data Parity Error Interrupt Enable	DMA Interrupt Enable (DIEN), Bit 6	By clearing this bit, a Master Data Parity Error does not cause assertion of INTA/ (or INTB/) but the status bit is set in the DMA Status (DSTAT) register.
AIP Checking	SCSI Control Four (SCNTL4), Bit 6	Setting this bit enables the AIP checking and generation of the upper byte lane of protection information during command, status, and message phases.

Table 2.5 Bits Used for Parity/CRC/AIP Control and Generation (Cont.)

Bit Name	Location	Description
CRC Request Pending	SCSI Control Zero (SCNTL0) , Bit 2	This bit indicates it is acceptable to force a CRC request. This bit will only be clear when a CRC request has been sent and no data has been transferred since the request. This bit may be used to prevent back-to-back CRC conditions.
Disable CRC Checking	CRC Control Zero (CRCCNTL0) , Bit 7	This bit is set to cause internal logic not to check or report CRC errors during Ultra3 transfers.
Disable CRC Protocol Checking	CRC Control Zero (CRCCNTL0) , Bit 6	This bit is set to cause the device to not check for a CRC request prior to a phase change on the SCSI bus. This condition normally causes a SCSI error condition. Note: Setting this bit makes the SYM53C1010 noncompliant to the SPI-3 specification. This bit should not be set under normal operating conditions.
CRC Reset Counter (Target Mode Only)	CRC Control Zero (CRCCNTL0) , Bit 5	When set, this bit resets the internal CRC interval counter to zero.
CRC Interval Counter (Target Mode Only)	CRC Control Zero (CRCCNTL0) , Bits [3:0]	These bits determine when a CRC request is sent out by the device. The interval is only applicable when the device is operating in target mode and transferring data in DT Data-In or DT Data-Out phases. The intervals are provided, in bytes, as: 0x0 = disabled; 0x1 = 128; 0x2 = 256; 0x3 = 512; ... ; 0x9 = 32768; 0xA = 65536; 0xB–0xF = Reserved.

Table 2.6 SCSI Parity Errors and Interrupts

DHP ¹	PAR ²	Description
0	0	Halts when a parity error occurs in the target or initiator mode and does NOT generate an interrupt.
0	1	Halts when a parity error occurs in the target mode and generates an interrupt in the target or initiator mode.
1	0	Does not halt in target mode when a parity error occurs until the end of the transfer. An interrupt is not generated.
1	1	Does not halt in target mode when a parity error occurs until the end of the transfer. An interrupt is generated.

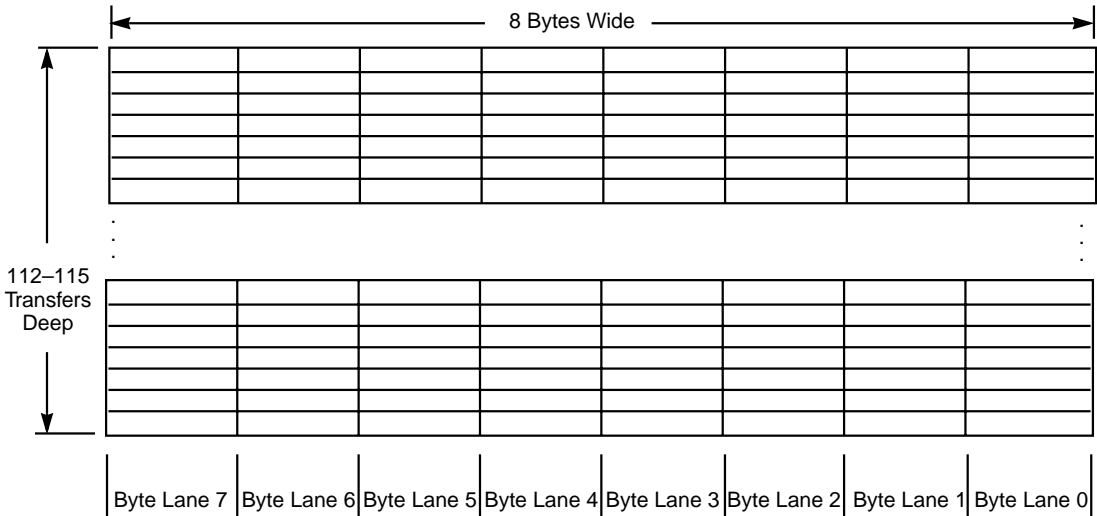
1. DHP = Disable Halt on SATN/ or Parity Error (bit 5, [SCSI Control One \(SCNTL1\)](#))

2. PAR = Parity Error (bit 0 [SCSI Interrupt Enable One \(SIEN1\)](#))

2.2.11 DMA FIFO

The DMA FIFO is 8 bytes wide by 112–115 transfers deep depending on the type and direction of data transfer. The DMA FIFO is illustrated in [Figure 2.2](#). Small FIFO mode (112 bytes) is not supported by the SYM53C1010.

Figure 2.2 DMA FIFO Sections

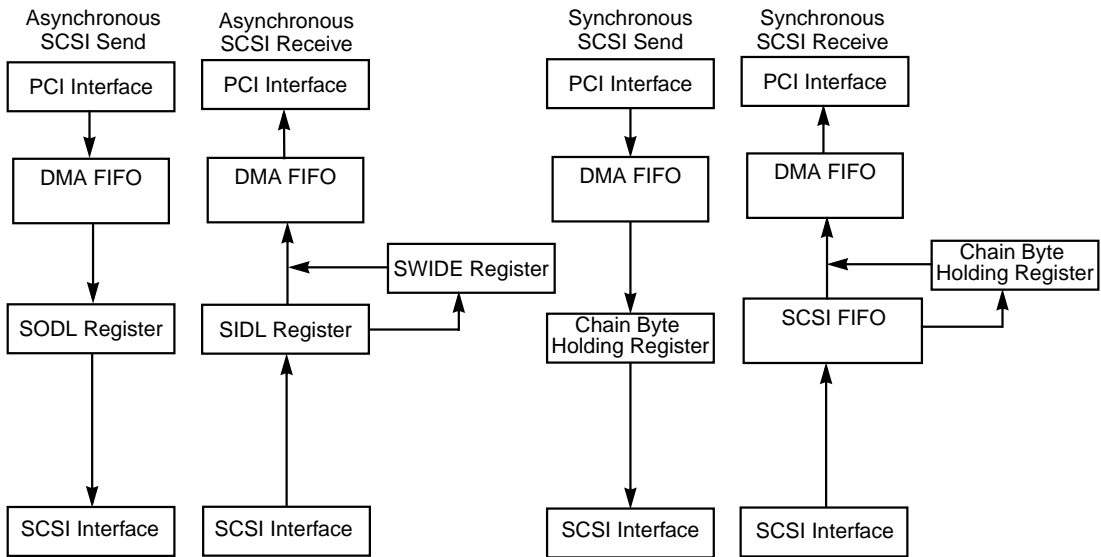


The SYM53C1010 supports 64-bit memory and automatically supports misaligned DMA transfers. The FIFO allows the SYM53C1010 to support 4, 8, 16, 32, 64, or 128 Dword bursts across the PCI bus interface.

2.2.12 SCSI Data Paths

The data path through the SYM53C1010 is dependent on whether data is moved into or out of the chip and whether the SCSI data transfer is asynchronous or synchronous. [Figure 2.3](#) illustrates how data is moved to and from the SCSI bus in each of the different modes. The following sections determine if any bytes remain in the data path when the device halts an operation.

Figure 2.3 SYM53C1010 Host Interface SCSI Data Paths



2.2.12.1 Asynchronous SCSI Send

To determine the number of bytes remaining in the DMA FIFO when a phase mismatch occurs, read the [DMA FIFO Byte Count \(DFBC\)](#) register. This 16-bit read only register contains the actual number of bytes remaining in the DMA FIFO. In addition, the [SCSI Output Data Latch \(SODL\)](#) register must be checked to determine if it contains any remaining bytes. If bit 5 (OLF) in the [SCSI Status Zero \(SSTAT0\)](#) register is set, then the least significant byte in the SODL register contains data. If bit 5 (OLF1) in the [SCSI Status Two \(SSTAT2\)](#) register is set, then the most significant byte in the SODL register contains data. Checking these bits also reveals bytes left in the SODL register from a Chained Move operation with an odd byte count. To recover from all other error conditions, the DMA FIFO should be cleared by setting bit 2 (CLF) in [Chip Test Three \(CTEST3\)](#) and the I/O should be retried.

If the Wide SCSI Send (WSS) bit in the [SCSI Control Two \(SCNTL2\)](#) register is set when a phase mismatch occurs, then adjustments must be made to the previous block move, not the current block move loaded into DCMD/DBC. To recover the byte of chain data in the SODL register the previous block move byte count should be set to 1 and the address set to the last data address for that block move.

2.2.12.2 Synchronous SCSI Send

The DMA FIFO is the only location where data can reside when a phase mismatch occurs during a synchronous SCSI send transfer. To determine the number of bytes remaining in the DMA FIFO, read the [DMA FIFO Byte Count \(DFBC\)](#) register. This 16-bit, read only register contains the actual number of bytes remaining in the DMA FIFO. To recover from all other error conditions the DMA FIFO should be cleared by setting bit 2 (CLF) in [Chip Test Three \(CTEST3\)](#) and the I/O should be retried.

If the Wide SCSI Send (WSS) bit in the [SCSI Control Two \(SCNTL2\)](#) register is set when a phase mismatch occurs, then adjustments must be made to the previous block move, not the current block move loaded into DCMD/DBC. To recover the byte of chain data in the outbound chain byte holding register, the previous block move byte count should be set to one and the address set to the last data address for that block move.

2.2.12.3 Asynchronous SCSI Receive

When a phase mismatch occurs during an asynchronous SCSI receive, the only data that may remain in the device is a potential wide residue byte in the [SCSI Wide Residue \(SWIDE\)](#) register. If bit 0 (WSR) in [SCSI Control Two \(SCNTL2\)](#) is set, then the SWIDE register contains a residual byte. This byte can be flushed by executing a block move instruction with a byte count of one. To recover from all other error conditions the DMA FIFO should be cleared by setting bit 2 (CLF) in [Chip Test Three \(CTEST3\)](#) and the I/O should be retried.

2.2.12.4 Synchronous SCSI Receive

When a phase mismatch occurs during a synchronous SCSI receive transfer no data recovery operation is necessary. All data, including chain bytes from chained block moves, are flushed from the device prior to the phase mismatch occurring. To recover from all other error conditions, the DMA FIFO should be cleared by setting bit 2 (CLF) in [Chip Test Three \(CTEST3\)](#), the SCSI FIFO should be cleared by setting bit 1 (CSF) in [SCSI Test Three \(STEST3\)](#), and the I/O should be retried.

2.2.13 SCSI Bus Interface

The SYM53C1010 performs SE and LVD transfers.

2.2.13.1 SCSI Bus Modes

To increase device connectivity and SCSI cable length, the SYM53C1010 features LVD Link technology, the LSI Logic implementation of LVD SCSI. LVD Link transceivers provide the inherent reliability of differential SCSI and a long-term migration path for faster SCSI transfer rates.

HVD is not supported by this device. Bit 2 (DIFF) of the [SCSI Status Two \(SSTAT2\)](#) register and bit 5 (DIF) of the [SCSI Test Two \(STEST2\)](#) register are now reserved. The A_ or B_DIFFSENS signals still detect the different input voltages for HVD, LVD, and SE but the HVD feature is not present.

2.2.13.2 SCSI Termination

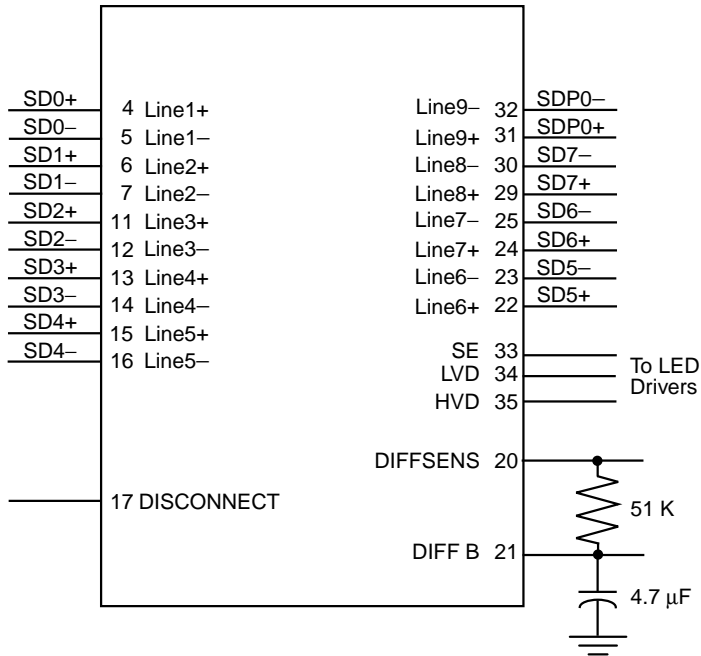
The terminator networks pull signals to an inactive voltage level and match the impedance seen at the end of the cable with the characteristic impedance of the cable. Terminators must be installed at the extreme ends of the SCSI chain, and only at the ends; no system should ever have more or less than two terminators. SCSI host adapters should provide a means of accommodating terminators. There should be a means of disabling the termination.

SE cables can use a 220 Ω pull-up resistor to the terminator power supply (Term Power) line and a 330 Ω pull-down resistor to ground. Because of the high-performance nature of the SYM53C1010, regulated (or active) termination is recommended. [Figure 2.4](#) shows an active terminator. TolerANT technology active negation can be used with either termination network.

For information on terminators that support LVD, refer to the SPI-3 draft standard.

Note: If the SYM53C1010 is used in a design with an 8-bit SCSI bus, all 16 data lines must be terminated.

Figure 2.4 Regulated Termination for Ultra3 SCSI



DIFFSENS connects to the SCSI bus DIFFSENS line to detect what type of devices (SE, LVD, or HVD) are connected to the SCSI bus. DISCONNECT shuts down the terminator when it is not at the end of the bus. The disconnect pin low enables the terminator.

2.2.14 Select/Reselect During Selection/Reselection

In multithreaded SCSI I/O environments, it is not uncommon to be selected or reselected while trying to perform selection/reselection. This situation may occur when a SCSI controller (operating in the initiator mode) tries to select a target and is reselected by another. The Select SCRIPTS instruction has an alternate address to which the SCRIPTS will jump when this situation occurs. The analogous situation for target devices is being selected while trying to perform a reselection.

Once a change in operating mode occurs, either the initiator SCRIPTS issues a Set Initiator instruction or the target SCRIPTS issues a Set Target instruction. The Selection and Reselection Enable bits ([SCSI Chip ID \(SCID\)](#) bits 5 and 6, respectively) should both be asserted, enabling the SYM53C1010 to respond as an initiator or as a target. If only selection is enabled, the SYM53C1010 cannot be reselected as an

initiator. Status bits, in the [SCSI Interrupt Status Zero \(SIST0\)](#) register, and interrupt bits, in the [SCSI Interrupt Enable Zero \(SIEN0\)](#) register, indicate if the SYM53C1010 has been selected or reselected.

2.2.15 Synchronous Operation

The SYM53C1010 can transfer synchronous SCSI data in both the initiator and target modes. The SYM53C1010's SCLK input must be connected to a 40 MHz oscillator. The [SCSI Transfer \(SXFER\)](#) register controls the synchronous offset while the [SCSI Control Three \(SCNTL3\)](#) register controls the synchronous clock converters. These registers may be loaded by the CPU before SCRIPTS execution begins, from within SCRIPTS, with a Table Indirect I/O instruction, or with a Read-Modify-Write instruction.

The SYM53C1010 can receive data from the SCSI bus at a synchronous transfer period as short as 12.5 ns, regardless of the transfer period used to send data. The SYM53C1010 can receive data at one-fourth of the divided SCLK frequency. Depending on the SCLK frequency, the negotiated transfer period, and the synchronous clock divider, the SYM53C1010 can send synchronous data at intervals as short as 12.5 ns for Ultra3 SCSI, 25 ns for Ultra2 SCSI, 50 ns for Ultra SCSI, 100 ns for fast SCSI and 200 ns for SCSI-1.

2.2.15.1 Determining the Data Transfer Rate

Synchronous data transfer rates are controlled by bits in two different registers of the SYM53C1010. Following is a brief description of these bits. [Figure 2.5](#) illustrates the clock division factors used in each register as well as the role of the register bits in determining the transfer rate.

2.2.15.2 SCSI Control Three (SCNTL3) Register, Bits [6:4] (SCF[2:0])

The SCF[2:0] bits select the factor by which the frequency of SCLK is divided before its presentation to the synchronous SCSI control logic.

The synchronous transfer speed is determined by the combination of the divided clock and the setting of the XCLKS_ST, XCLKS_DT, XCLKH_ST, and XCLKH_DT bits in the [SCSI Control Four \(SCNTL4\)](#) register. The table below gives the clock dividers available. Refer to [Table 4.4](#), “[Double Transition Transfer Rates](#)”, and [Table 4.5](#), “[Single Transition Transfer](#)

Rates”, located in the [SCSI Control Four \(SCNTL4\)](#) register description, for a full list of available synchronous transfer rates.

The SCF Divisor values are provided in [Table 2.7](#).

Table 2.7 SCF Divisor Values

SCF2	SCF1	SCF0	SCLK Divisor
0	0	0	SCLK/3
0	0	1	SCLK/1
0	1	0	SCLK/1.5
0	1	1	SCLK/2
1	0	0	SCLK/3
1	0	1	SCLK/4
1	1	0	SCLK/6
1	1	1	SCLK/8

2.2.15.3 SCSI Control Four (SCNTL4) Register, Bits [3:0]

The following extra clock bits add an extra clock of setup or hold to a ST or DT transaction.

Bit 3, XCLKH_DT (Extra Clock of Data Hold on DT transfer edge), adds a clock of data hold to synchronous DT SCSI transfers on the DT edge. This bit only impacts DT transfers as it only affects data hold to the DT edge. Setting this bit reduces the synchronous transfer send rate but will not reduce the rate at which the SYM53C1010 receives outbound REQs, ACKs, or data.

Bit 2, XCLKH_ST (Extra Clock of Data Hold on ST transfer edge), adds a clock of data hold to synchronous DT or ST SCSI transfers on the ST edge. This bit impacts DT and ST transfers as it affects data hold to the ST edge. Setting this bit reduces the synchronous transfer send rate but will not reduce the rate at which the SYM53C1010 receives outbound REQs, ACKs, or data.

Bit 1, XCLKS_DT (Extra Clock of Data Setup on DT transfer edge), adds a clock of data setup to synchronous DT SCSI transfers on the DT edge. This bit only impacts DT transfers as it only affects data hold to the DT

edge. Setting this bit reduces the synchronous transfer send rate but will not reduce the rate at which the SYM53C1010 receives outbound REQs, ACKs, or data.

Bit 0, XCLKS_ST (Extra Clock of Data Setup on ST transfer edge), adds a clock of data setup to synchronous DT or ST SCSI transfers on the ST edge. This bit impacts DT and ST transfers as it affects data hold to the ST edge. Setting this bit reduces the synchronous transfer send rate but will not reduce the rate at which the SYM53C1010 receives outbound REQs, ACKs, or data.

The synchronous receive rate can be calculated using the following formula:

$$\text{Receive Rate (DT)} = \frac{\text{Input Clock Rate}}{(\text{SCF Divisor} \times 2)} \quad (\text{megatransfers/s})$$

$$\text{Receive Rate (ST)} = \frac{\text{Input Clock Rate}}{(\text{SCF Divisor} \times 4)} \quad (\text{megatransfers/s})$$

Note: The receive rate is independent of the settings of the XCLKS_DT, XCLKS_ST, XCLKH_DT, XCLKH_ST bits.

The synchronous send rate, in units of megatransfers/s, can be calculated using the following formula:

$$\text{Send Rate (DT)} = \frac{\text{Input Clock Rate}}{\text{SCF Divisor} \times \left(2 + \frac{\text{XCLKS_DT} + \text{XCLKS_ST} + \text{XCLKH_DT} + \text{XCLKH_ST}}{2} \right)}$$

$$\text{Send Rate (ST)} = \frac{\text{Input Clock Rate}}{\text{SCF Divisor} \times (4 + \text{XCLKS_ST} + \text{XCLKH_ST})}$$

To configure the SYM53C1010 for Ultra3 DT transfers, perform the following steps:

- Step 1. Enable the SCSI Clock Quadrupler – The SYM53C1010 can quadruple the frequency of a 40 MHz SCSI clock, allowing the system to perform Ultra3 SCSI transfers. This option is user selectable through bit settings in the [SCSI Test One \(STEST1\)](#) register. At power-up or reset, the quadrupler is disabled and powered down. Follow the steps in the bit description to enable the clock quadrupler.

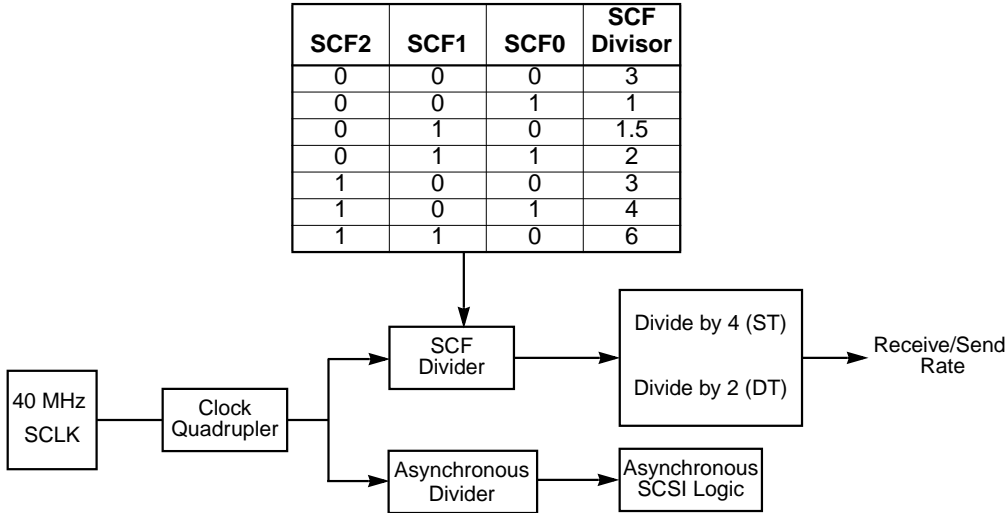
- Step 2. Program the Transfer Rate – Using [SCSI Control Three \(SCNTL3\)](#) and [SCSI Control Four \(SCNTL4\)](#), program the register to the 160 Mbytes/s transfer rate.
- Step 3. Program the Maximum SCSI Offset – Using [SCSI Transfer \(SXFER\)](#), program the maximum SCSI DT Synchronous offset to 0x3E.
- Step 4. Enable TolerANT – Set the TolerANT Enable bit, [SCSI Test Three \(STEST3\)](#), bit 7. Active negation must be enabled for the SYM53C1010 to perform Ultra3 SCSI transfers.

An example of configuring the Ultra3 SCSI transfer speed is:

1. Set SCNTL3 to 0x18.
2. Set SXFER to 0x3E.
3. Set SCNTL4 to 0x80.

These settings program the SYM53C1010 SCSI clocks to send and receive at 160 MHz with a synchronous SCSI offset of 0x3E.

Figure 2.5 Determining the Synchronous Transfer Rate



$$\text{Received Rate (DT)} = \frac{\text{Input Clock Rate}}{(\text{SCF Divisor} \times 2)} \quad (\text{megatransfers/s})$$

$$\text{Receive Rate (ST)} = \frac{\text{Input Clock Rate}}{(\text{SCF Divisor} \times 4)} \quad (\text{megatransfers/s})$$

$$\text{Send Rate (DT)} = \frac{\text{Input Clock Rate}}{\text{SCF Divisor} \times \left(2 + \frac{\text{XCLKS_DT} + \text{XCLKS_ST} + \text{XCLKH_DT} + \text{XCLKH_ST}}{2} \right)}$$

$$\text{Send Rate (ST)} = \frac{\text{Input Clock Rate}}{\text{SCF Divisor} \times (4 + \text{XCLKS_ST} + \text{XCLKH_ST})}$$

2.2.16 Interrupt Handling

The SCRIPTS processors in the SYM53C1010 perform most functions independently of the host microprocessor. However, certain interrupt situations must be handled by the external microprocessor. This section explains all aspects of interrupts as they apply to the SYM53C1010.

2.2.16.1 Polling and Hardware Interrupts

The external microprocessor is informed of an interrupt condition by polling or hardware interrupts. Polling means that the microprocessor must continually loop and read a register until it detects a bit that is set

indicating an interrupt. This method is the fastest, but it diverts CPU time from other system tasks. The preferred method of detecting interrupts in most systems is hardware interrupts. In this case, the SYM53C1010 asserts the interrupt request (INTA/ or INTB/) line that interrupts the microprocessor, causing the microprocessor to execute an Interrupt Service Routine (ISR). A hybrid approach would use hardware interrupts for long waits and polling for short waits.

SCSI Function A is routed to PCI Interrupt INTA/. SCSI Function B is normally routed to INTB/, but can be routed to INTA/ if a pull-up is connected to MAD[4]. See [Section 3.8, “MAD Bus Programming”](#) for additional information.

2.2.16.2 Registers

The registers in the SYM53C1010 used for detecting or defining interrupts are [SCSI Interrupt Status Zero \(SIST0\)](#), [SCSI Interrupt Status One \(SIST1\)](#), [DMA Status \(DSTAT\)](#), [SCSI Interrupt Enable Zero \(SIEN0\)](#), [SCSI Interrupt Enable One \(SIEN1\)](#), and [DMA Interrupt Enable \(DIEN\)](#). See the register descriptions in [Chapter 4, “Registers”](#) for additional information.

ISTAT – The ISTAT register includes the [Interrupt Status Zero \(ISTAT0\)](#), [Interrupt Status One \(ISTAT1\)](#), [Mailbox Zero \(MBOX0\)](#), and [Mailbox One \(MBOX1\)](#) registers. It is the only register that can be accessed as a slave during the SCRIPTS operation. Therefore, it is the register that is polled when polled interrupts are used. It is also the first register that should be read after the INTA/ (or INTB/) pin is asserted in association with a hardware interrupt.

The INTF (Interrupt-on-the-Fly) bit should be the first interrupt serviced. It must be written to one in order to clear it. This interrupt must be cleared before servicing any other interrupts indicated by SIP or DIP. Do not attempt to read the other chip status registers if the INTF bit is set, but SIP or DIP are not set.

If the SIP bit in the [Interrupt Status Zero \(ISTAT0\)](#) register is set, then a SCSI-type interrupt has occurred and the [SCSI Interrupt Status Zero \(SIST0\)](#) and [SCSI Interrupt Status One \(SIST1\)](#) registers should be read.

If the DIP bit in the [Interrupt Status Zero \(ISTAT0\)](#) register is set, then a DMA-type interrupt has occurred and the [DMA Status \(DSTAT\)](#) register should be read.

SCSI-type and DMA-type interrupts may occur simultaneously, so in some cases both SIP and DIP may be set. To avoid missing a SCSI interrupt the [SCSI Interrupt Status Zero \(SIST0\)](#) and [SCSI Interrupt Status One \(SIST1\)](#) registers should be read before the [DMA Status \(DSTAT\)](#) register is read.

When set, the SIRQD bit in [Interrupt Status One \(ISTAT1\)](#) disables the INT/ pin for the corresponding SCSI function. The interrupt is not lost or ignored but is merely masked at the pin. If the INT/ pin is already asserted when SIRQD is set the INT/ pin will remain asserted until the interrupt is serviced. Future interrupts will be masked at the pin until SIRQD is cleared.

Note that the host can read ISTAT as the SCRIPTS code is writing to ISTAT. In this case the data will be unstable so the read should be retried.

SIST0 and SIST1 – The [SCSI Interrupt Status Zero \(SIST0\)](#) and [SCSI Interrupt Status One \(SIST1\)](#) registers contain the status of SCSI-type interrupts whether they are enabled in [SCSI Interrupt Enable Zero \(SIEN0\)](#) and [SCSI Interrupt Enable One \(SIEN1\)](#) or not. Reading these registers determines the conditions that caused the SCSI-type interrupt, clears any bits that are set in SIST0 and SIST1, and clears the SIP bit in [Interrupt Status Zero \(ISTAT0\)](#). Since the SYM53C1010-33 SCSI functions stack interrupts, SIST0 and SIST1 are not necessarily cleared after a read; additional interrupts may still be pending.

If the SYM53C1010 is receiving data from the SCSI bus and a fatal interrupt condition occurs, the chip attempts to send the contents of the DMA FIFO to memory before generating the interrupt. Reading [SCSI Interrupt Status Zero \(SIST0\)](#) and [SCSI Interrupt Status One \(SIST1\)](#) will clear the CRC Error bit (bit 7) in the [CRC Control One \(CRCCNTL1\)](#) register.

If the SYM53C1010 is sending data to the SCSI bus and a fatal SCSI interrupt condition occurs, data could remain in the DMA FIFO. To determine if the DMA FIFO is empty, check the DMA FIFO Empty (DFE) bit in [DMA Status \(DSTAT\)](#) register. If this bit is cleared, set the CLF (Clear DMA FIFO) and CSF (Clear SCSI FIFO) bits before continuing.

The CLF bit is bit 2 in [Chip Test Three \(CTEST3\)](#) register. The CSF bit is bit 1 in [SCSI Test Three \(STEST3\)](#) register.

DSTAT – The [DMA Status \(DSTAT\)](#) register contains the status of DMA-type interrupts whether they are enabled in DIEN or not. Reading this register determines which condition(s) caused the DMA-type interrupt, clears any interrupt related bits in DSTAT, and clears the DIP bit in [Interrupt Status Zero \(ISTAT0\)](#). Since the SYM53C1010-33 SCSI functions stack interrupts, reading DSTAT does not necessarily clear the register as additional interrupts may be pending.

Bit 7 in [DMA Status \(DSTAT\)](#), DFE, is purely a status bit; it will not generate an interrupt and will not be cleared when read. DMA interrupts do not flush the DMA or SCSI FIFOs before generating the interrupt. Therefore, the DFE bit in the DSTAT register should be checked after any DMA interrupt. If the DFE bit is cleared, the FIFOs must either be cleared by setting the CLF (Clear DMA FIFO in CTEST3) and CSF (Clear SCSI FIFO in STEST3) bits, or flushed by setting the FLF (Flush DMA FIFO in CTEST3) bit.

SIEN0 and SIEN1 – The [SCSI Interrupt Enable Zero \(SIEN0\)](#) and [SCSI Interrupt Enable One \(SIEN1\)](#) registers are the interrupt enable registers for the SCSI interrupts in [SCSI Interrupt Status Zero \(SIST0\)](#) and [SCSI Interrupt Status One \(SIST1\)](#). Clearing the appropriate mask bit masks an interrupt.

DIEN – The [DMA Interrupt Enable \(DIEN\)](#) register is the interrupt enable register for DMA interrupts in [DMA Status \(DSTAT\)](#). Clearing the appropriate mask bit masks an interrupt.

2.2.16.3 Fatal vs. Nonfatal Interrupts

A fatal interrupt, as the name implies, always causes the SCRIPTS to stop running. All nonfatal interrupts become fatal when they are enabled by setting the appropriate interrupt enable bit. Interrupt masking is discussed in [Section 2.2.16.4, “Masking”](#). All DMA interrupts are fatal. The DMA interrupts are indicated by the DIP bit in [Interrupt Status Zero \(ISTAT0\)](#) and one or more bits in [DMA Status \(DSTAT\)](#).

Some SCSI interrupts are nonfatal. The SCSI interrupts are indicated by the SIP bit in the [Interrupt Status Zero \(ISTAT0\)](#) register and one or more

bits in [SCSI Interrupt Status Zero \(SIST0\)](#) register or [SCSI Interrupt Status One \(SIST1\)](#) register.

When the SYM53C1010 is operating in the Initiator mode, Interrupt-on-the-Fly, Function Complete (CMP), Selected (SEL), Reselected (RSL), General Purpose Timer Expired (GEN), and Handshake-to-Handshake Timer Expired (HTH) interrupts are nonfatal.

When operating in the Target mode, Interrupt-on-the-Fly, SATN/ active (M/A), CMP, SEL, RSL, GEN, and HTH are nonfatal. Refer to the description for the Disable Halt on a Parity/CRC/AIP Error or SATN/ active (Target Mode Only) bit, DHP, in the [SCSI Control One \(SCNTL1\)](#) register to configure the chip's behavior when the SATN/ interrupt is enabled during Target mode operation.

The reason for nonfatal interrupts is to prevent the SCRIPTS from stopping when an interrupt occurs that does not require service from the CPU. This prevents an interrupt when arbitration is complete (CMP set), when the SYM53C1010 is selected or reselected (SEL or RSL set), when the initiator asserts ATN (target mode: SATN/ active), or when the General Purpose or Handshake-to-Handshake timers expire. These interrupts are not needed for events that occur during high level SCRIPTS operation.

2.2.16.4 Masking

Masking an interrupt means disabling or ignoring that interrupt. Clearing bits in the [SCSI Interrupt Enable Zero \(SIEN0\)](#) and [SCSI Interrupt Enable One \(SIEN1\)](#) registers will mask SCSI interrupts. Clearing bits in the [DMA Interrupt Enable \(DIEN\)](#) register will mask DMA interrupts. Masking an interrupt after INTA/ (or INTB/) is asserted does not cause INTA/ (or INTB/) to be negated. How the chip responds to masked interrupts depends on: whether polling or hardware interrupts are being used; whether the interrupt is fatal or nonfatal; and whether the chip is operating in the Initiator or Target mode.

If a nonfatal interrupt occurs while masked, SCRIPTS continues. The appropriate bit in the [SCSI Interrupt Status Zero \(SIST0\)](#) or [SCSI Interrupt Status One \(SIST1\)](#) is still set, the SIP bit in the [Interrupt Status Zero \(ISTAT0\)](#) is not set, and the INTA/ (or INTB/) pin is not asserted.

If a fatal interrupt occurs while masked, SCRIPTS halts. The appropriate bit in the [DMA Status \(DSTAT\)](#), [SCSI Interrupt Status Zero \(SIST0\)](#), or [SCSI Interrupt Status One \(SIST1\)](#) register is set, the SIP or DIP bit in the [Interrupt Status Zero \(ISTAT0\)](#) register is set, but the INTA/ (or INTB/) pin is not asserted.

Setting the SIRQD bit in the [Interrupt Status One \(ISTAT1\)](#) register disables the interrupt pin for the corresponding SCSI function. If an interrupt pin is already asserted and SIRQD is then set, the interrupt pin will remain asserted until serviced. Further interrupts will be blocked from the interrupt pin.

When the SYM53C1010 is initialized, enable all fatal interrupts if hardware interrupts are being used. If a fatal interrupt is disabled and that interrupt condition occurs, the SCRIPTS halts and the system never knows it unless it times out and checks the [Interrupt Status Zero \(ISTAT0\)](#), [Interrupt Status One \(ISTAT1\)](#), [Mailbox Zero \(MBOX0\)](#), and [Mailbox One \(MBOX1\)](#) registers after a certain period of inactivity.

If ISTAT is being polled instead of using hardware interrupts, then masking a fatal interrupt makes no difference since the SIP and DIP bits in the [Interrupt Status Zero \(ISTAT0\)](#) inform the system of interrupts, not the INTA/ (or INTB/) pin.

2.2.16.5 Stacked Interrupts

The SYM53C1010 will stack interrupts, if they occur, one after the other. If the SIP or DIP bits in the [Interrupt Status Zero \(ISTAT0\)](#) register are set (first level), there is already at least one pending interrupt. Any future interrupts are stacked in extra registers behind the [SCSI Interrupt Status Zero \(SIST0\)](#), [SCSI Interrupt Status One \(SIST1\)](#), and [DMA Status \(DSTAT\)](#) registers (second level). When two interrupts have occurred and the two levels of the stack are full, any further interrupts set additional bits in the extra registers behind SIST0, SIST1, and DSTAT. When the first level of interrupts are cleared, all the later interrupts move into SIST0, SIST1, and DSTAT. After the first interrupt is cleared, the INTA/ (or INTB/) pin is deasserted for a minimum of three CLKs; the stacked interrupts move into SIST0, SIST1, or DSTAT; and the INTA/ (or INTB/) pin is asserted once again.

Since a masked nonfatal interrupt does not set the SIP or DIP bits, interrupt stacking does not occur. A masked, nonfatal interrupt still posts

the interrupt in [SCSI Interrupt Status Zero \(SIST0\)](#), but does not assert the INTA/ (or INTB/) pin. Since no interrupt is generated, future interrupts move into [SCSI Interrupt Status Zero \(SIST0\)](#) or [SCSI Interrupt Status One \(SIST1\)](#) instead of stacking behind another interrupt. When another interrupt condition occurs, the bit corresponding to the earlier masked nonfatal interrupt is set.

A related situation to interrupt stacking is when two interrupts occur simultaneously. Since stacking does not occur until the SIP or DIP bits are set, there is a small timing window in which multiple interrupts can occur but are not stacked. These could be multiple SCSI interrupts (SIP set), multiple DMA interrupts (DIP set), or multiple SCSI and multiple DMA interrupts (both SIP and DIP set).

As previously mentioned, DMA interrupts do not attempt to flush the FIFOs before generating the interrupt. It is important to set either the Clear DMA FIFO (CLF) and Clear SCSI FIFO (CSF) bits if a DMA interrupt occurs and the DMA FIFO Empty (DFE) bit is not set. This is because any future SCSI interrupts are not posted until the DMA FIFO is cleared of data. These 'locked out' SCSI interrupts are posted as soon as the DMA FIFO is empty.

2.2.16.6 Halting in an Orderly Fashion

When an interrupt occurs, the SYM53C1010 attempts to halt in an orderly fashion.

- If the interrupt occurs in the middle of an instruction fetch, the fetch is completed, except in the case of a Bus Fault. Execution does not begin, but the DSP points to the next instruction since it is updated when the current instruction is fetched.
- If the DMA direction is a write to memory and a SCSI interrupt occurs, the SYM53C1010 attempts to flush the DMA FIFO to memory before halting. Under any other circumstances, only the current cycle is completed before halting, so the DFE bit in [DMA Status \(DSTAT\)](#) should be checked to determine if any data remains in the DMA FIFO.
- SCSI SREQ/SACK handshakes that are in progress are completed before halting.
- The SYM53C1010 attempts to clean up any outstanding synchronous offset before halting.

- In the case of Transfer Control Instructions, once instruction execution begins it continues to completion before halting.
- In the case of a JUMP/CALL WHEN/IF <phase> instruction, the [DMA SCRIPTS Pointer \(DSP\)](#) is updated to the transfer address before halting.
- All other instructions may halt before completion.

2.2.16.7 Sample Interrupt Service Routine

The following is a sample of an Interrupt Service Routine (ISR) for the SYM53C1010. It can be repeated if polling is used, or should be called when the INTA/ (or INTB/) pin is asserted if hardware interrupts are used.

1. Read [Interrupt Status Zero \(ISTAT0\)](#).
2. If the INTF bit is set, write it to a one to clear this status.
3. If only the SIP bit is set, read [SCSI Interrupt Status Zero \(SIST0\)](#) and [SCSI Interrupt Status One \(SIST1\)](#) to clear the SCSI interrupt condition and get the SCSI interrupt status. The bits in the SIST0 and SIST1 tell which SCSI interrupts occurred and determine what action is required to service the interrupts.
4. If only the DIP bit is set, read [DMA Status \(DSTAT\)](#) to clear the interrupt condition and determine the DMA interrupt status. The bits in the DSTAT register indicate which DMA interrupts occurred and determine what action is required to service the interrupts.
5. If both the SIP and DIP bits are set, read [SCSI Interrupt Status Zero \(SIST0\)](#), [SCSI Interrupt Status One \(SIST1\)](#), and [DMA Status \(DSTAT\)](#) to clear the SCSI and DMA interrupt condition and determine the interrupt status. If using 8-bit reads of the SIST0, SIST1, and DSTAT registers to clear interrupts, insert a 12 clock delay between the consecutive reads to ensure that the interrupts clear properly. Both the SCSI and DMA interrupt conditions should be handled before leaving the ISR. It is recommended that the DMA interrupt is serviced before the SCSI interrupt, because a serious DMA interrupt condition could influence how the SCSI interrupt is acted upon.
6. When using polled interrupts go back to Step 1 before leaving the ISR in case any stacked interrupts moved in when the first interrupt was cleared. When using hardware interrupts, the INTA/ (or INTB/)

pin is asserted again if there are any stacked interrupts. This should cause the system to re-enter the ISR.

2.2.17 Interrupt Routing

This section documents the recommended approach to RAID ready interrupt routing for the SYM53C1010. In order to be compatible with RAID upgrade products and the SYM53C1010, the following requirements must be met:

- When a RAID upgrade card is installed in the upgrade slot, interrupts from the motherboard SCSI controller(s) assigned to the RAID upgrade card must be routed to INTC/ and INTD/ of the upgrade slot and isolated from the motherboard interrupt controller. The system processor must not see interrupts from the SCSI controllers that are serviced by the RAID upgrade card. An upgrade slot is one that is connected to the interrupt routing logic for motherboard SCSI device(s). When a PCI RAID upgrade board is installed into the system, it will be plugged into this slot if it is to control motherboard SCSI device(s).
- The TDI pin of the upgrade slot must be connected to the INT_DIR/ pin of the SYM53C1010.
- When a RAID upgrade card is not installed, interrupts from a SCSI core must not be presented to the system's interrupt controller using multiple interrupt inputs.

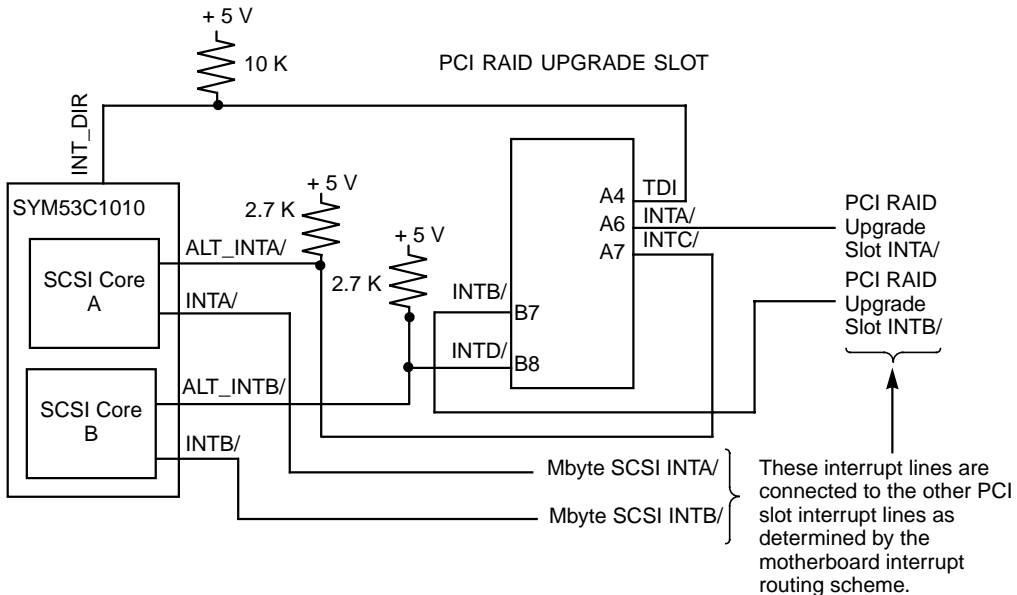
[Figure 2.6](#) shows an example configuration. In this example the SYM53C1010 Dual Channel Ultra3 SCSI Multifunction Controller contains the interrupt routing logic.

The SYM53C1010 supports four different interrupt routing modes. Additional information for these modes may be found in the register description of [SCSI Test One \(STEST1\)](#) description in [Chapter 4, "Registers"](#). Each SCSI core within the chip may be configured independently by selecting the interrupt routing mode using bits [1:0] in the [SCSI Test One \(STEST1\)](#) register within each core. Mode 0 is the default mode and is compatible with RAID upgrade products.

If the implementation shown in [Figure 2.6](#) is used, INTC/ and INTD/ of the PCI RAID upgrade slot cannot be used when a non-RAID upgrade card is installed in the slot. If this restriction is not acceptable, additional

buffer logic must be implemented on the motherboard. As long as the interrupt routing requirements stated above are satisfied, a motherboard designer could implement this design with external logic.

Figure 2.6 Interrupt Routing Hardware Using the SYM53C1010



There can only be one entity controlling a motherboard SCSI core or conflicts will occur. Typically a SCSI core will be controlled by the SCSI BIOS and an operating system driver. When a SCSI core is allocated to a RAID adapter, however, a mechanism must be implemented to prevent the SCSI BIOS and operating system driver from trying to access the SCSI core. The motherboard designer has several options to choose from for doing this:

- The **first option** is to have the SCSI core load its PCI Subsystem ID using a serial EPROM on power-up. If bit 15 in this ID is set, the LSI Logic Symbios[®] BIOS and operating system drivers will ignore the chip. This makes it possible to control the assignment of the motherboard SCSI cores using a configuration utility.
- The **second option** is to provide motherboard and system BIOS support for NVS. The SCSI core may then be enabled or disabled using the SCSI BIOS configuration utility. Not all versions of the Symbios drivers support this capability.

- The **third option** is to have the system BIOS not report the existence of the SCSI controller chips when the SCSI BIOS and operating systems make PCI BIOS calls. This approach requires modifications to the system BIOS and assumes the operating system uses PCI BIOS calls when searching for PCI devices.

2.2.18 Chained Block Moves

Since the SYM53C1010 has the capability to transfer 16-bit wide SCSI data, a unique situation occurs when dealing with odd bytes. The Chained Move (CHMOV) SCRIPTS instruction along with the Wide SCSI Send (WSS) and Wide SCSI Receive (WSR) bits in the [SCSI Control Two \(SCNTL2\)](#) register are used to facilitate these situations. The Chained Block Move instruction is illustrated in [Figure 2.7](#).

2.2.18.1 Wide SCSI Send Bit

The WSS bit is set following a wide SCSI send operation (Data-Out for initiator mode or Data-In for target mode) when the SCSI core is holding a byte of chain data. The SCSI core holds the byte when the controller detects a partial transfer at the end of a chained Block Move SCRIPTS instruction. This flag is not set if a normal Block Move instruction is used. Under this condition, the SCSI controller does not send the low-order byte of the last partial memory transfer across the SCSI bus. Instead, the low-order byte is temporarily stored in the lower byte of the [SCSI Output Data Latch \(SODL\)](#) register for asynchronous transfers or in the chain byte holding register for synchronous transfers and the WSS flag is set.

The hardware uses the WSS bit to determine what behavior must occur at the start of the next data send transfer. If the WSS bit is set at the start of the next transfer, the first byte (the high-order byte) of the next data send transfer is “married” with the byte of chain data. The two bytes are sent out across the bus regardless of the type of Block Move instruction (normal or chained). The WSS bit is automatically cleared when the “married” word is sent. Performing either a SCSI receive operation or any narrow transfer also clears the bit. In addition, SCRIPTS and the microprocessor can clear the WSS bit as well as use it for error detection and recovery purposes.

2.2.18.2 Wide SCSI Receive Bit

The WSR bit is set following a wide SCSI receive operation (Data-In for initiator mode or Data-Out for target mode) when the SCSI core is holding a byte of chain data. The SCSI core holds the byte when the controller detects a partial transfer at the end of a chained Block Move instruction. Under this condition the high-order byte is not transferred out of the DMA channel to memory. Instead, it is stored in the [SCSI Wide Residue \(SWIDE\)](#) register and the WSR flag is set.

The hardware uses the WSR bit to determine what behavior must occur at the start of the next data receive transfer. If set the stored high-order byte may be residual data, valid data for a subsequent data transfer, or overrun data. The byte may be read as normal by starting a data receive transfer. The WSR bit is automatically cleared at the start of the next data receive transfer. Performing either a SCSI send operation or any narrow transfer also clears the bit. In addition, SCRIPTS and the microprocessor can clear the WSR bit as well as use it for error detection and recovery purposes.

2.2.18.3 SWIDE Register

For wide asynchronous receive data transfers, the [SCSI Wide Residue \(SWIDE\)](#) register holds the high-order byte of a partial SCSI transfer which has not yet been transferred to memory. This stored data may be a residue byte (and therefore ignored) or it may be valid data that is transferred to memory at the beginning of the next Block Move instruction.

2.2.18.4 SODL Register

For wide asynchronous send data transfers, the low-order byte of the [SCSI Output Data Latch \(SODL\)](#) register holds the low-order byte of a partial memory transfer which has not yet been transferred across the SCSI bus. This stored data is usually “married” with the first byte of the next data send transfer, and both bytes are sent across the SCSI bus at the start of the next data send Block Move instruction.

2.2.18.5 Chained Block Move SCRIPTS Instruction

A chained Block Move SCRIPTS instruction is primarily used to transfer consecutive data send or data receive blocks. Using the chained Block

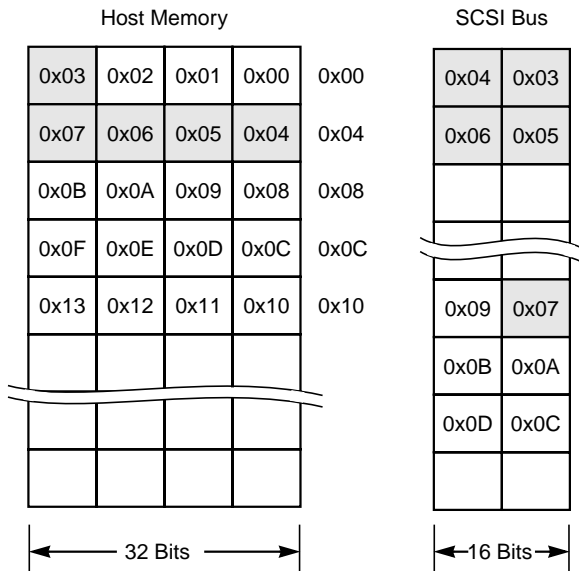
Move instruction facilitates partial receive transfers and allows correct partial send behavior without additional opcode overhead. Behavior of the chained Block Move instruction varies slightly for sending and receiving data.

For receive data (Data-In for the initiator or Data-Out for the target), a chained Block Move instruction indicates that if a partial transfer occurred at the end of the instruction the WSR flag is set. The high-order byte of the last SCSI transfer is stored in the [SCSI Wide Residue \(SWIDE\)](#) register rather than transferred to memory. The stored byte should be the first byte transferred to memory at the start of the chained Block Move or regular Block Move data stream. Since the byte count always represents data transfers to/from memory (as opposed to/from the SCSI bus), the stored byte transferred out is one of the bytes in the count. If the WSR bit is cleared when a receive data chained Block Move instruction is executed, the data transfer occurs similar to that of the regular Block Move instruction. It is recommended that all Block Move instructions be chained Block Moves.

For send data (Data-Out for the initiator or Data-In for the target), a chained Block Move instruction indicates that if a partial transfer terminates the chained block move the WSS flag is set. The low-order byte should be stored in the lower byte of the [SCSI Output Data Latch \(SODL\)](#) register for asynchronous transfers or in the outbound chain byte holding register for synchronous transfers and not sent across the SCSI bus. Without the chained Block Move instruction, the last low-order byte would be sent across the SCSI bus. The starting byte count represents data bytes transferred from memory but not to the SCSI bus when a partial transfer exists. For example, if the instruction is an initiator chained Block Move Data Out of five bytes (and WSS is not previously set), five bytes are transferred out of memory to the SCSI controller. Four bytes are transferred from the SCSI controller across the SCSI bus and one byte is temporarily stored as described above, waiting to be married with the first byte of the next Block Move instruction. If the WSS bit is set at the start of a data send command the first byte of the transfer is assumed to be the high-order byte and is “married” with the stored byte (which will be the low-order byte) before the two bytes are sent across the SCSI bus. It is recommended that all Block Move instructions be chained Block Moves.

[Figure 2.7](#) provides examples of the Block Move and Chain Block Move operations.

Figure 2.7 Block Move and Chained Block Move Instructions



CHMOV 5, 3 when Data-Out

Moves five bytes from address 0x03 in the host memory to the SCSI bus. Bytes 0x03, 0x04, 0x05, and 0x06 are moved and byte 0x07 remains in the SCSI core (in the lower byte of the [SCSI Output Data Latch \(SODL\)](#) register for asynchronous transfers, in the outbound chain byte holding register for synchronous transfers). The stored byte is combined with the first byte of the following CHMOVE instruction.

Chain Move 0x5, 0x9 when Data-In

Moves five bytes from address 0x09 in the host memory to the SCSI bus. The data in address 0x09 is married with the stored data (0x07) and transferred to the SCSI bus.

2.3 Parallel ROM Interface

The SYM53C1010 supports up to 1 Mbyte of external memory in binary increments from 16 Kbytes to allow the use of expansion ROM for add-in PCI cards. Both functions of the device share the ROM interface. This interface is designed for low speed operations such as downloading

instruction code from ROM; it is not intended for dynamic activities such as executing instructions.

System requirements include the SYM53C1010, two or three external 8-bit address holding registers (HCT273 or HCT374), and the appropriate memory device. The 4.7 kΩ pull-up resistors on the MAD bus require HC or HCT external components to be used. Pull-up resistors on the 8-bit bidirectional memory bus at power-up determine the memory size and speed. The SYM53C1010 senses this bus shortly after the release of the Reset signal and configures the [Expansion ROM Base Address \(ERBA\)](#) register and the memory cycle state machines for the appropriate conditions.

The SYM53C1010 supports a variety of sizes and speeds of expansion ROM. An example set of interface drawings is in [Appendix B, “External Memory Interface Diagram Examples”](#). The encoding of pins MAD[3:1] allows the user to define how much external memory is available to the SYM53C1010. [Table 2.8](#) shows the memory space associated with the possible values of MAD[3:1]. The MAD[3:1] pins are fully described in [Chapter 3, “Signal Descriptions”](#).

Table 2.8 Parallel ROM Support

MAD[3:1]	Available Memory Space
000	16 Kbytes
001	32 Kbytes
010	64 Kbytes
011	128 Kbytes
100	256 Kbytes
101	512 Kbytes
110	1024 Kbytes
111	No external memory present, ROM interface disabled

To use one of the configurations mentioned above in a host adapter board design, put 4.7 kΩ pull-up resistors on the MAD pins corresponding to the available memory space. Each MAD pin has an internal static pull-down therefore no external pull-down resistors are

needed. For example, to connect to a 64 Kbytes external ROM use a pull-up on MAD[2]. If the external memory interface is not used, MAD[3:1] should be pulled high.

The SYM53C1010 allows the system to determine the size of the available external memory using the [Expansion ROM Base Address \(ERBA\)](#) register in the PCI configuration space. For more information on how this works, refer to the PCI specification or the Expansion ROM Base Address register description in [Chapter 4, “Registers”](#).

MAD[0] is the slow ROM pin. When pulled up it enables two extra clock cycles of data access time to allow use of slower memory devices. The external memory interface also supports updates to flash memory.

2.4 Serial EEPROM Interface

For each SCSI function, the SYM53C1010 implements an interface permitting attachment of a serial EEPROM device to the GPIO[0] and GPIO[1] pins. There are two modes of operation relating to the serial EEPROM, the [Subsystem ID \(SID\)](#) register, and the [Subsystem Vendor ID \(SVID\)](#) register for each SCSI function. These modes are programmable through the MAD[7] pin, which is sampled at power-up.

2.4.1 Default Download Mode

In this mode, MAD[7] is pulled down internally, GPIO[0] is the serial data signal (SDA) and GPIO[1] is the serial clock signal (SCL). Certain data in the serial EEPROM is automatically loaded into chip registers at power-up.

The format of the serial EEPROM data is defined in [Table 2.7](#). If the download is enabled and an EEPROM is not present or the checksum fails, the [Subsystem ID \(SID\)](#) and [Subsystem Vendor ID \(SVID\)](#) registers read back all zeros. At power-up, five bytes are loaded into the chip from locations 0xFB through 0xFF.

The Subsystem ID and Subsystem Vendor ID registers are read only in accordance with the PCI specification, with a default value of all zeros if the download fails.

Note: The speed of the serial EEPROM must be 400 Kbits/s.

Table 2.9 Default Download Mode Serial EEPROM Data Format

Byte	Name	Description
0xFB	SVID(0)	Subsystem Vendor ID (SVID) , LSB. This byte is loaded into the least significant byte of the Subsystem Vendor ID register in the appropriate PCI configuration space at chip power-up.
0xFC	SVID(1)	Subsystem Vendor ID (SVID) , MSB. This byte is loaded into the most significant byte of the Subsystem Vendor ID register in the appropriate PCI configuration space at chip power-up.
0xFD	SID(0)	Subsystem ID (SID) , LSB. This byte is loaded into the least significant byte of the Subsystem ID register in the appropriate PCI configuration space at chip power-up.
0xFE	SID(1)	Subsystem ID (SID) , MSB. This byte is loaded into the most significant byte of the Subsystem ID register in the appropriate PCI configuration space at chip power-up.
0xFF	CKSUM	Checksum (CKSUM). This 8-bit checksum is formed by adding, bitwise, each byte contained in locations 0xFB–0xFE to the seed value (0x55) and then taking the 2's complement of the result.

2.4.2 No Download Mode

When MAD[7] is pulled up through an external resistor, the automatic download is disabled and data is not automatically loaded into chip registers at power-up. The [Subsystem ID \(SID\)](#) and [Subsystem Vendor ID \(SVID\)](#) registers are read only, per the PCI specification, with a default value of 0x1000 and 0x1000 respectively.

2.5 Power Management

The SYM53C1010 complies with the PCI Bus Power Management Interface Specification, Revision 1.1. The PCI Function Power States D0, D1, D2, and D3 are defined in that specification.

D0 is the maximum powered state, and D3 is the minimum powered state. Power state D3 is further categorized as D3hot or D3cold. A function that is powered off is said to be in the D3cold power state.

The SYM53C1010 power states are independently controlled through two power state bits that are located in the PCI Configuration Space [Power Management Control/Status \(PMCSR\) register, 0x44–0x45](#). The power state bit settings are provided in [Table 2.10](#).

Table 2.10 Power States

Configuration Register (0x44), Bits [1:0]	Power State	Function
00	D0	Maximum Power
01	D1	Disables SCSI clock
10	D2	Coma Mode
11	D3	Minimum Power

Although the PCI Bus Power Management Interface Specification does not allow power state transitions D2 to D1, D3 to D2, or D3 to D1, the SYM53C1010 hardware places no restriction on transitions between power states.

The PCI Function Power States D0, D1, D2, and D3 are described below in conjunction with each SCSI function. Power state actions are separate for each function.

As the device transitions from one power level to a lower one, the attributes that occur from the higher power state level are carried over into the lower power state level. For example, D1 disables the SCSI CLK. Therefore, D2 will include this attribute as well as the attributes defined in the [Power State D2](#) section. The PCI Function Power States D0, D1, D2, and D3 are described below in conjunction with each SCSI function. Power state actions are separate for each function.

2.5.1 Power State D0

Power state D0 is the maximum power state and is the power-up default state for each function. The SYM53C1010 is fully functional in this state.

2.5.2 Power State D1

Power state D1 is a lower power state than D0. A function in this state places the SYM53C1010 core in the snooze mode and the SCSI clock

is disabled. In the snooze mode, a SCSI reset does not generate an IRQ/signal.

2.5.3 Power State D2

Power state D2 is a lower power state than D1. A function in this state places the SYM53C1010 core in the coma mode. The following PCI Configuration Space [Command](#) register enable bits are suppressed:

- I/O Space Enable
- Memory Space Enable
- Bus Mastering Enable
- SERR/Enable
- Enable Parity Error Response

Thus, the function's memory and I/O spaces cannot be accessed, and the function cannot be a PCI bus master. Furthermore, SCSI and DMA interrupts are disabled when the function is in power state D2. If the function is changed from power state D2 to power state D1 or D0, the previous values of the PCI [Command](#) register are restored. Also, any pending interrupts before the function entered power state D2 are asserted.

2.5.4 Power State D3

Power state D3 is the minimum power state, which includes settings called D3hot and D3cold. D3hot allows the device to transition to D0 using software. The SYM53C1010 is considered to be in power state D3cold when power is removed from the device. D3cold can transition to D0 by applying V_{CC} and resetting the device.

Power state D3 is a lower power level than power state D2. A function in this state places the SYM53C1010 core in the coma mode. Furthermore, the function's soft reset is continually asserted while in power state D3, which clears all pending interrupts and 3-states the SCSI bus. In addition, the function's PCI [Command](#) register is cleared. If both of the SYM53C1010 functions are placed in power state D3, the Clock Quadrupler is disabled, which results in additional power savings.

Chapter 3

Signal Descriptions

This chapter describes the input and output signals of the SYM53C1010-33. The chapter consists of the following sections:

- [Section 3.1, “Signal Organization”](#)
 - [Section 3.2, “Internal Pull-ups and Pull-downs on SYM53C1010 Signals”](#)
 - [Section 3.3, “PCI Bus Interface Signals”](#)
 - [Section 3.4, “SCSI Bus Interface Signals”](#)
 - [Section 3.5, “Flash ROM and Memory Interface Signals”](#)
 - [Section 3.6, “Test Interface Signals”](#)
 - [Section 3.7, “Power and Ground Signals”](#)
 - [Section 3.8, “MAD Bus Programming”](#)
-

3.1 Signal Organization

The SYM53C1010-33 has four major interfaces:

- PCI Interface
- SCSI Bus Interface
- Memory Interface
- Test Interface

[Figure 3.1](#) illustrates the signals, their grouping, and their I/O direction. A slash (/) at the end of a signal name indicates that it is an active LOW signal. When the slash is absent, the signal is active at a HIGH voltage.

The PCI Interface contains many functional groups of signals. The SCSI Bus Interface contains two functional groups of signals as illustrated in [Figure 3.1](#).

There are five signal type definitions:

- I** Input, a standard input-only signal.
- O** Output, a standard output driver (typically a Totem Pole output).
- I/O** Input and output (bidirectional).
- T/S** 3-state, a bidirectional, 3-state input/output signal.
- S/T/S** Sustained 3-state, an active low 3-state signal owned and driven by one and only one agent at a time.

This section of the chapter illustrates the signal groupings in [Figure 3.1](#). Next, the signal locations on the 329 Ball Grid Array (BGA) are illustrated in [Table 3.1](#) and [Table 3.2](#). Then, the signal names are listed alphabetically, in [Table 3.3](#), and numerically, in [Table 3.5](#).

Figure 3.1 SYM53C1010-33 Functional Signal Grouping

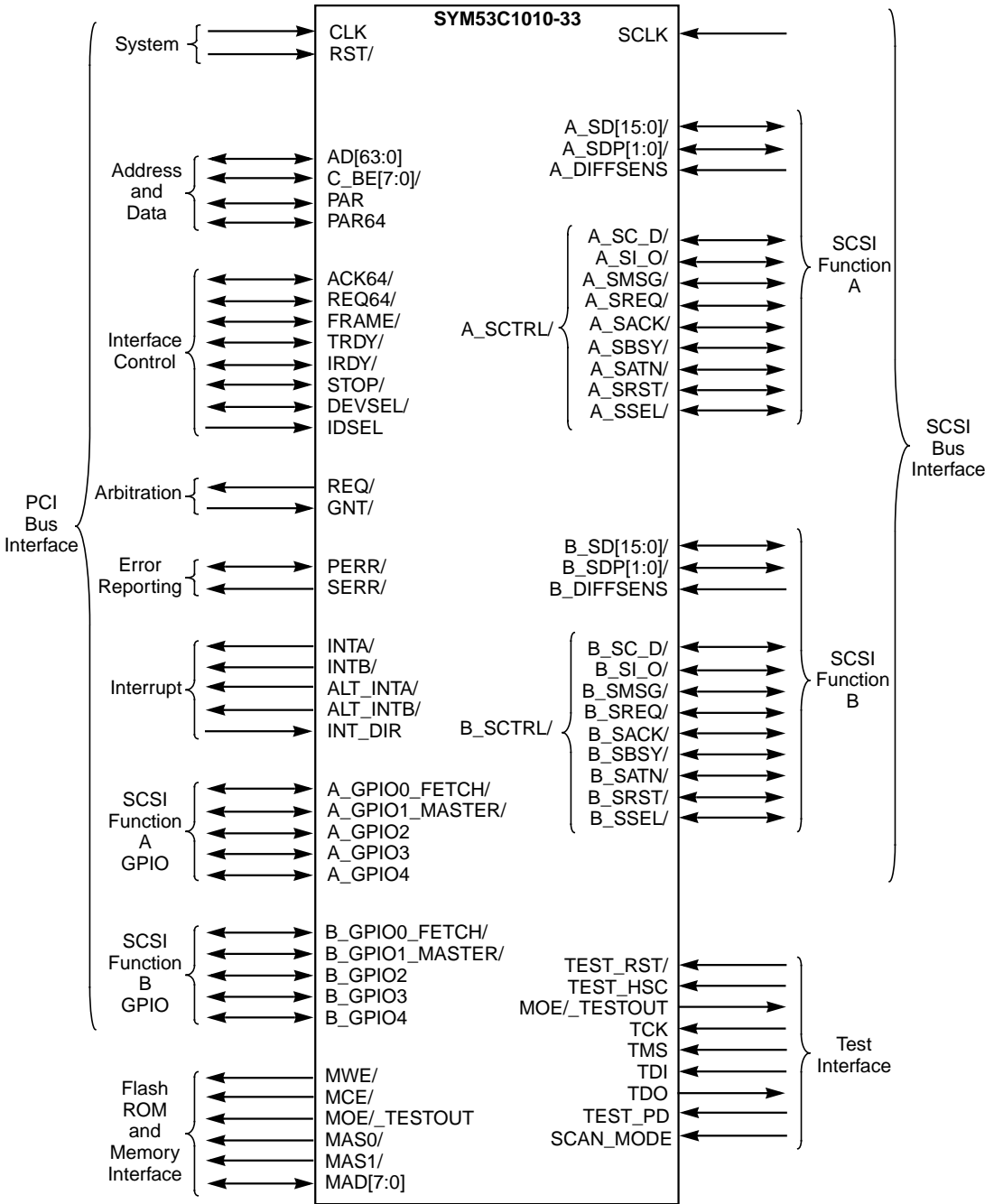


Table 3.1 Left Half of the SYM53C1010-33 329 BGA Chip - Top View

	1	2	3	4	5	6	7	8	9	10	11	12			
A	NC	TEST_PD	A_SD12+	A_SD13+	A_SD15+	A_SD0+	A_SD2-	A_SD4-	A_SD6-	A_SDP0-	V _{DD} -BIAS2	A_SBSY+	A		
B	NC	V _{DD} _A	NC	A_SD13-	A_SD15-	A_SD0-	A_SD1+	A_SD3+	A_SD5+	A_SD7+	A_SATN-	A_SATN+	B		
C	TEST_RST/	V _{SS} _A	V _{SS} _IO	A_SD12-	A_SD14-	A_SDP1-	A_SD1-	A_SD2+	A_SD4+	A_SD6+	A_SDP0+	A_SBSY-	C		
D	TCK	V _{SS} _CORE	V _{DD} _CORE	V _{SS} _IO	A_SD14+	A_SDP1+	V _{DD} _IO	A_SD3-	A_SD5-	V _{DD} _IO	A_SD7-	V _{SS} _IO	D		
E	TDO	TDI	TMS	V _{DD} _CORE								E			
F	ALT_INTA/	INTB/	V _{SS} _CORE	INTA/								F			
G	RST/	INT_DIR	ALT_INTB/	V _{DD} _IO								G			
H	AD31	REQ/	CLK	GNT/								H			
J	AD27	AD28	AD30	AD29								J			
K	C_BE3/	AD24	AD26	V _{DD} _IO								V _{SS} _IO	V _{SS} _IO	V _{SS} _IO	K
L	AD23	AD22	IDSEL	AD25								V _{SS} _IO	V _{SS} _IO	V _{SS} _IO	L
M	AD21	AD19	AD20	V _{SS} _IO								V _{SS} _IO	V _{SS} _IO	V _{SS} _IO	M
N	AD17	AD18	AD16	IRDY/								V _{SS} _IO	V _{SS} _IO	V _{SS} _IO	N
P	C_BE2/	FRAME/	TRDY/	V _{DD} _IO								V _{SS} _IO	V _{SS} _IO	V _{SS} _IO	P
R	DEVSEL/	STOP/	SERR/	PERR/											R
T	PAR	C_BE1/	AD14	AD15											T
U	AD13	AD12	AD11	V _{DD} _IO											U
V	AD10	AD9	C_BE0/	AD8											V
W	AD7	AD6	AD4	AD5											W
Y	AD3	AD2	AD0	V _{SS} _IO	AD63	AD59	V _{DD} _IO	AD52	AD48	V _{DD} _IO	AD44	V _{SS} _IO	Y		
AA	AD1	REQ64/	V _{SS} _IO	C_BE7/	PAR64	AD60	AD56	AD53	AD49	AD45	AD41	AD37	AA		
AB	ACK64/	V _{SS} _CORE	V _{DD} _CORE	C_BE5/	AD62	AD58	AD55	AD51	AD47	AD43	AD39	AD36	AB		
AC	V _{DD} _CORE	V _{SS} _CORE	C_BE6/	C_BE4/	AD61	AD57	AD54	AD50	AD46	AD42	AD40	AD38	AC		
	1	2	3	4	5	6	7	8	9	10	11	12			

Table 3.2 Right Half of the SYM53C1010-33 329 BGA Chip - Top View

	13	14	15	16	17	18	19	20	21	22	23			
A	NC	A_SACK+	A_SMSG+	A_SC_D+	A_SREQ+	A_SD8-	A_SD10-	A_DIFFSENS	SCLK	V _{SS} CORE	NC	A		
B	NC	A_SRST-	A_SSEL-	NC	A_SI_O-	A_SD8+	A_SD10+	V _{SS} _A	NC	V _{DD} CORE	V _{DD} CORE	B		
C	A_SACK-	A_SMSG-	A_SC_D-	A_SREQ-	A_SI_O+	A_SD9+	A_SD11+	V _{DD} _A	V _{SS} _IO	SCAN_MODE	TEST_HSC	C		
D	A_SRST+	V _{DD} _IO	A_SSEL+	NC	V _{DD} _IO	A_SD9-	A_SD11-	V _{SS} _IO	V _{SS} CORE	B_SD12-	B_SD12+	D		
E										B_SD13+	B_SD13-	B_SD14-	B_SD14+	E
F										B_SD15+	B_SD15-	B_SDP1-	B_SDP1+	F
G										V _{DD} _IO	B_SD0-	B_SD0+	B_SD1-	G
H										B_SD2-	B_SD1+	B_SD2+	B_SD3-	H
J										B_SD4-	B_SD3+	B_SD4+	B_SD5-	J
K	V _{SS} _IO	V _{SS} _IO								V _{DD} _IO	B_SD5+	B_SD6+	B_SD7-	K
L	V _{SS} _IO	V _{SS} _IO								B_SD6-	B_SD7+	B_SDP0+	B_SDP0-	L
M	V _{SS} _IO	V _{SS} _IO								V _{SS} _IO	RBIAS	V _{DD} _BIAS	B_SATN-	M
N	V _{SS} _IO	V _{SS} _IO								B_SACK-	B_SBSY+	B_SATN+	B_SBSY-	N
P	V _{SS} _IO	V _{SS} _IO								V _{DD} _IO	B_SACK+	NC	NC	P
R										B_SMSG-	B_SMSG+	B_SRST+	B_SRST-	R
T										B_SC_D-	B_SC_D+	B_SSEL+	B_SSEL-	T
U										V _{DD} _IO	B_SREQ-	NC	NC	U
V										B_SI_O+	B_SD8-	B_SI_O-	B_SREQ+	V
W										B_SD9+	B_SD10-	B_SD9-	B_SD8+	W
Y	V _{DD} CORE	V _{DD} _IO	V _{SS} CORE	A_GPIO1_MASTER/	V _{DD} _IO	MOE/TESTOUT	MAD7	V _{SS} _IO	B_DIFFSENS	B_SD11-	B_SD10+	Y		
AA	AD33	B_GPIO0_FETCH/	B_GPIO3	A_GPIO2	MAS1/	MCE/	MAD6	MAD3	V _{SS} _IO	V _{SS} CORE	B_SD11+	AA		
AB	AD35	RESERVED	B_GPIO2	A_GPIO0_FETCH/	A_GPIO4	V _{DD} CORE	V _{SS} CORE	MAD4	MAD1	NC	V _{DD} CORE	AB		
AC	AD34	AD32	B_GPIO1_MASTER/	B_GPIO4	A_GPIO3	MAS0/	MWE/	MAD5	V _{SS} CORE	MAD2	MAD0	AC		

Table 3.3 Signal Names and BGA Position

Signal Name	BGA Pos	Signal Name	BGA Pos	Signal Name	BGA Pos	Signal Name	BGA Pos	Signal Name	BGA Pos
A_DIFFSENS	A20	AD4	W3	B_GPIO2	AB15	FRAME/	P2	V _{DD_IO}	Y14
A_GPIO0		AD5	W4	B_GPIO3	AA15	GNT/	H4	V _{DD_IO}	Y17
A_FETCH/	AB16	AD6	W2	B_GPIO4	AC16	IDSEL	L3	V _{DD_A}	B2
A_GPIO1		AD7	W1	B_SACK-	N20	INT_DIR	G2	V _{DD_A}	C20
A_MASTER/	Y16	AD8	V4	B_SACK+	P21	INTA/	F4	V _{DD_BIAS}	M22
A_GPIO2	AA16	AD9	V2	B_SATN-	M23	INTB/	F2	V _{DD_BIAS2}	A11
A_GPIO3	AC17	AD10	V1	B_SATN+	N22	IRDY/	N4	V _{DD_CORE}	B22
A_GPIO4	AB17	AD11	U3	B_SBSY-	N23	MAD0	AC23	V _{DD_CORE}	B23
A_SACK-	C13	AD12	U2	B_SBSY+	N21	MAD1	AB21	V _{DD_CORE}	D3
A_SACK+	A14	AD13	U1	B_SC_D-	T20	MAD2	AC22	V _{DD_CORE}	E4
A_SATN-	B11	AD14	T3	B_SC_D+	T21	MAD3	AA20	V _{DD_CORE}	Y13
A_SATN+	B12	AD15	T4	B_SD0-	G21	MAD4	AB20	V _{DD_CORE}	AB3
A_SBSY-	C12	AD16	N3	B_SD0+	G22	MAD5	AC20	V _{DD_CORE}	AB18
A_SBSY+	A12	AD17	N1	B_SD1-	G23	MAD6	AA19	V _{DD_CORE}	AB23
A_SC_D-	C15	AD18	N2	B_SD1+	H21	MAD7	Y19	V _{DD_CORE}	AC1
A_SC_D+	A16	AD19	M2	B_SD2-	H20	MAS0/	AC18	V _{SS_IO}	C3
A_SD0-	B6	AD20	M3	B_SD2+	H22	MAS1/	AA17	V _{SS_IO}	C21
A_SD0+	A6	AD21	M1	B_SD3-	H23	MCE/	AA18	V _{SS_IO}	D4
A_SD1-	C7	AD22	L2	B_SD3+	J21	MOE/_TESTOUT	Y18	V _{SS_IO}	D12
A_SD1+	B7	AD23	L1	B_SD4-	J20	MWE/	AC19	V _{SS_IO}	D20
A_SD2-	A7	AD24	K2	B_SD4+	J22	NC	A1	V _{SS_IO}	K10
A_SD2+	C8	AD25	L4	B_SD5-	J23	NC	A13	V _{SS_IO}	K11
A_SD3-	D8	AD26	K3	B_SD5+	K21	NC	A23	V _{SS_IO}	K12
A_SD3+	B8	AD27	J1	B_SD6-	L20	NC	B1	V _{SS_IO}	K13
A_SD4-	A8	AD28	J2	B_SD6+	K22	NC	B3	V _{SS_IO}	K14
A_SD4+	C9	AD29	J4	B_SD7-	K23	NC	B13	V _{SS_IO}	L10
A_SD5-	D9	AD30	J3	B_SD7+	L21	NC	B16	V _{SS_IO}	L11
A_SD5+	B9	AD31	H1	B_SD8-	V21	NC	B21	V _{SS_IO}	L12
A_SD6-	A9	AD32	AC14	B_SD8+	W23	NC	D16	V _{SS_IO}	L13
A_SD6+	C10	AD33	AA13	B_SD9-	W22	NC	U22	V _{SS_IO}	L14
A_SD7-	D11	AD34	AC13	B_SD9+	W20	NC	U23	V _{SS_IO}	M4
A_SD7+	B10	AD35	AB13	B_SD10-	W21	NC	P22	V _{SS_IO}	M10
A_SD8-	A18	AD36	AB12	B_SD10+	Y23	NC	P23	V _{SS_IO}	M11
A_SD8+	B18	AD37	AA12	B_SD11-	Y22	NC	AB22	V _{SS_IO}	M12
A_SD9-	D18	AD38	AC12	B_SD11+	AA23	PAR	T1	V _{SS_IO}	M13
A_SD9+	C18	AD39	AB11	B_SD12-	D22	PAR64	AA5	V _{SS_IO}	M14
A_SD10-	A19	AD40	AC11	B_SD12+	D23	PERR/	R4	V _{SS_IO}	M20
A_SD10+	B19	AD41	AA11	B_SD13-	E21	RBIAS	M21	V _{SS_IO}	N10
A_SD11-	D19	AD42	AC10	B_SD13+	E20	REQ/	H2	V _{SS_IO}	N11
A_SD11+	C19	AD43	AB10	B_SD14-	E22	REQ64/	AA2	V _{SS_IO}	N12
A_SD12-	C4	AD44	Y11	B_SD14+	E23	RESERVED	AB14	V _{SS_IO}	N13
A_SD12+	A3	AD45	AA10	B_SD15-	F21	RST/	G1	V _{SS_IO}	N14
A_SD13-	B4	AD46	AC9	B_SD15+	F20	SCAN_MODE	C22	V _{SS_IO}	P10
A_SD13+	A4	AD47	AB9	B_SDP0-	L23	SCLK	A21	V _{SS_IO}	P11
A_SD14-	C5	AD48	Y9	B_SDP0+	L22	SERR/	R3	V _{SS_IO}	P12
A_SD14+	D5	AD49	AA9	B_SDP1-	F22	STOP/	R2	V _{SS_IO}	P13
A_SD15-	B5	AD50	AC8	B_SDP1+	F23	TCK	D1	V _{SS_IO}	P14
A_SD15+	A5	AD51	AB8	B_SI_O-	V22	TDI	E2	V _{SS_IO}	Y4
A_SDP0-	A10	AD52	Y8	B_SI_O+	V20	TDO	E1	V _{SS_IO}	Y12
A_SDP0+	C11	AD53	AA8	B_SMSG-	R20	TEST_HSC	C23	V _{SS_IO}	Y20
A_SDP1-	C6	AD54	AC7	B_SMSG+	R21	TMS	E3	V _{SS_IO}	AA3
A_SDP1+	D6	AD55	AB7	B_SREQ-	U21	TRDY/	P3	V _{SS_IO}	AA21
A_SI_O-	B17	AD56	AA7	B_SREQ+	V23	TEST_PD	A2	V _{SS_A}	B20
A_SI_O+	C17	AD57	AC6	B_SRST-	R23	TEST_RST/	C1	V _{SS_A}	C2
A_SMSG-	C14	AD58	AB6	B_SRST+	R22	V _{DD_IO}	D7	V _{SS_CORE}	A22
A_SMSG+	A15	AD59	Y6	B_SSEL-	T23	V _{DD_IO}	D10	V _{SS_CORE}	D2
A_SREQ-	C16	AD60	AA6	B_SSEL+	T22	V _{DD_IO}	D14	V _{SS_CORE}	D21
A_SREQ+	A17	AD61	AC5	C_BE0/	V3	V _{DD_IO}	D17	V _{SS_CORE}	F3
A_SRST-	B14	AD62	AB5	C_BE1/	T2	V _{DD_IO}	G4	V _{SS_CORE}	Y15
A_SRST+	D13	AD63	Y5	C_BE2/	P1	V _{DD_IO}	K4	V _{SS_CORE}	AB2
A_SSEL-	B15	ALT_INTA/	F1	C_BE3/	K1	V _{DD_IO}	K20	V _{SS_CORE}	AA22
A_SSEL+	D15	ALT_INTB/	G3	C_BE4/	AC4	V _{DD_IO}	P4	V _{SS_CORE}	AB19
ACK64/	AB1	B_DIFFSENS	Y21	C_BE5/	AB4	V _{DD_IO}	P20	V _{SS_CORE}	AC2
AD0	Y3	B_GPIO0		C_BE6/	AC3	V _{DD_IO}	U4	V _{SS_CORE}	AC21
AD1	AA1	B_FETCH/	AA14	C_BE7/	AA4	V _{DD_IO}	U20		
AD2	Y2	B_GPIO1		CLK	H3	V _{DD_IO}	Y7		
AD3	Y1	MASTER/	AC15	DEVSEL/	R1	V _{DD_IO}	Y10		

Table 3.4 Signal Names by BGA Position

Signal Name	BGA Pos	Signal Name	BGA Pos	Signal Name	BGA Pos	Signal Name	BGA Pos	Signal Name	BGA Pos
NC	A1	MAD4	AB20	A_SI_O+	C17	B_SD3+	J21	NC	P23
TEST_PD	A2	MAD1	AB21	A_SD9+	C18	B_SD4+	J22	DEVSEL/	R1
A_SD12+	A3	NC	AB22	A_SD11+	C19	B_SD5-	J23	STOP/	R2
A_SD13+	A4	V _{DD} _CORE	AB23	V _{DD} _A	C20	C_BE3/	K1	SERR/	R3
A_SD15+	A5	V _{DD} _CORE	AC1	V _{SS} _IO	C21	AD24	K2	PERR/	R4
A_SD0+	A6	V _{SS} _CORE	AC2	SCAN_MODE	C22	AD26	K3	B_SMSG-	R20
A_SD2-	A7	C_BE6/	AC3	TEST_HSC	C23	V _{DD} _IO	K4	B_SMSG+	R21
A_SD4-	A8	C_BE4/	AC4	TCK	D1	V _{SS} _IO	K10	B_SRST+	R22
A_SD6-	A9	AD61	AC5	V _{SS} _CORE	D2	V _{SS} _IO	K11	B_SRST-	R23
A_SDP0-	A10	AD57	AC6	V _{DD} _CORE	D3	V _{SS} _IO	K12	PAR	T1
V _{DD} _BIAS2	A11	AD54	AC7	V _{SS} _IO	D4	V _{SS} _IO	K13	C_BE1/	T2
A_SBSY+	A12	AD50	AC8	A_SD14+	D5	V _{SS} _IO	K14	AD14	T3
NC	A13	AD46	AC9	A_SDP1+	D6	V _{DD} _IO	K20	AD15	T4
A_SACK+	A14	AD42	AC10	V _{DD} _IO	D7	B_SD5+	K21	B_SC_D-	T20
A_SMSG+	A15	AD40	AC11	A_SD3-	D8	B_SD6+	K22	B_SC_D+	T21
A_SC_D+	A16	AD38	AC12	A_SD5-	D9	B_SD7-	K23	B_SSEL+	T22
A_SREQ+	A17	AD34	AC13	V _{DD} _IO	D10	AD23	L1	B_SSEL-	T23
A_SD8-	A18	AD32	AC14	A_SD7-	D11	AD22	L2	AD13	U1
A_SD10-	A19	B_GPIO1_		V _{SS} _IO	D12	IDSEL	L3	AD12	U2
A_DIFFSENS	A20	MASTER/	AC15	A_SRST+	D13	AD25	L4	AD11	U3
SCLK	A21	B_GPIO4	AC16	V _{DD} _IO	D14	V _{SS} _IO	L10	V _{DD} _IO	U4
V _{SS} _CORE	A22	A_GPIO3	AC17	A_SSEL+	D15	V _{SS} _IO	L11	V _{DD} _IO	U20
NC	A23	MAS0/	AC18	NC	D16	V _{SS} _IO	L12	B_SREQ-	U21
AD1	AA1	MWE/	AC19	V _{DD} _IO	D17	V _{SS} _IO	L13	NC	U22
REQ64/	AA2	MAD5	AC20	A_SD9-	D18	V _{SS} _IO	L14	NC	U23
V _{SS} _IO	AA3	V _{SS} _CORE	AC21	A_SD11-	D19	B_SD6-	L20	AD10	V1
C_BE7/	AA4	MAD2	AC22	V _{SS} _IO	D20	B_SD7+	L21	AD9	V2
PAR64	AA5	MAD0	AC23	V _{SS} _CORE	D21	B_SDP0+	L22	C_BE0/	V3
AD60	AA6	NC	B1	B_SD12-	D22	B_SDP0-	L23	AD8	V4
AD56	AA7	V _{DD} _A	B2	B_SD12+	D23	AD21	M1	B_SI_O+	V20
AD53	AA8	NC	B3	TDO	E1	AD19	M2	B_SD8-	V21
AD49	AA9	A_SD13-	B4	TDI	E2	AD20	M3	B_SI_O-	V22
AD45	AA10	A_SD15-	B5	TMS	E3	V _{SS} _IO	M4	B_SREQ+	V23
AAD41	AA11	A_SD0-	B6	V _{DD} _CORE	E4	V _{SS} _IO	M10	AD7	W1
AD37	AA12	A_SD1+	B7	B_SD13+	E20	V _{SS} _IO	M11	AD6	W2
AD33	AA13	A_SD3+	B8	B_SD13-	E21	V _{SS} _IO	M12	AD4	W3
B_GPIO0		A_SD5+	B9	B_SD14-	E22	V _{SS} _IO	M13	AD5	W4
FETCH/	AA14	A_SD7+	B10	B_SD14+	E23	V _{SS} _IO	M14	B_SD9+	W20
B_GPIO3	AA15	A_SATN-	B11	ALT_INTA/	F1	V _{SS} _IO	M20	B_SD10-	W21
A_GPIO2	AA16	A_SATN+	B12	INTB/	F2	RBIAS	M21	B_SD9-	W22
MAS1/	AA17	NC	B13	V _{SS} _CORE	F3	V _{DD} _BIAS	M22	B_SD8+	W23
MCE/	AA18	A_SRST-	B14	INTA/	F4	B_SATN-	M23	AD3	Y1
MAD6	AA19	A_SSEL-	B15	B_SD15+	F20	AD17	N1	AD2	Y2
MAD3	AA20	NC	B16	B_SD15-	F21	AD18	N2	AD0	Y3
V _{SS} _IO	AA21	A_SI_O-	B17	B_SDP1-	F22	AD16	N3	V _{SS} _IO	Y4
V _{SS} _CORE	AA22	A_SD8+	B18	B_SDP1+	F23	IRDY/	N4	AD63	Y5
B_SD11+	AA23	A_SD10+	B19	RST/	G1	V _{SS} _IO	N10	AD59	Y6
ACK64/	AB1	V _{SS} _A	B20	INT_DIR	G2	V _{SS} _IO	N11	V _{DD} _IO	Y7
V _{SS} _CORE	AB2	NC	B21	ALT_INTB/	G3	V _{SS} _IO	N12	AD52	Y8
V _{DD} _CORE	AB3	V _{DD} _CORE	B22	V _{DD} _IO	G4	V _{SS} _IO	N13	AD48	Y9
C_BE5/	AB4	V _{DD} _CORE	B23	V _{DD} _IO	G20	V _{SS} _IO	N14	V _{DD} _IO	Y10
AD62	AB5	TEST_RST/	C1	B_SD0-	G21	B_SACK-	N20	AD44	Y11
AD58	AB6	V _{SS} _A	C2	B_SD0+	G22	B_SBSY+	N21	V _{SS} _IO	Y12
AD55	AB7	V _{SS} _IO	C3	B_SD1-	G23	B_SATN+	N22	V _{DD} _CORE	Y13
AD51	AB8	A_SD12-	C4	AD31	H1	B_SBSY-	N23	V _{DD} _IO	Y14
AD47	AB9	A_SD14-	C5	REQ/	H2	C_BE2/	P1	V _{SS} _CORE	Y15
AD43	AB10	A_SDP1-	C6	CLK	H3	FRAME/	P2	A_GPIO1	
AD39	AB11	A_SD1-	C7	GN7/	H4	TRDY/	P3	MASTER/	Y16
AD36	AB12	A_SD2+	C8	B_SD2-	H20	V _{DD} _IO	P4	V _{DD} _IO	Y17
AD35	AB13	A_SD4+	C9	B_SD1+	H21	V _{SS} _IO	P10	MOE/	
RESERVED	AB14	A_SD6+	C10	B_SD2+	H22	V _{SS} _IO	P11	TESTOUT	Y18
B_GPIO2	AB15	A_SDP0+	C11	B_SD3-	H23	V _{SS} _IO	P12	MAD7	Y19
A_GPIO0		A_SBSY-	C12	AD27	J1	V _{SS} _IO	P13	V _{SS} _IO	Y20
FETCH/	AB16	A_SACK-	C13	AD28	J2	V _{SS} _IO	P14	B_DIFFSENS	Y21
A_GPIO4	AB17	A_SMSG-	C14	AD30	J3	V _{DD} _IO	P20	B_SD11-	Y22
V _{DD} _CORE	AB18	A_SC_D-	C15	AD29	J4	B_SACK+	P21	B_SD10+	Y23
V _{SS} _CORE	AB19	A_SREQ-	C16	B_SD4-	J20	NC	P22		

3.2 Internal Pull-ups and Pull-downs on SYM53C1010 Signals

Several SYM53C1010 signals use internal pull-ups and pull-downs. [Table 3.5](#) describes the conditions that enable these pull-ups and pull-downs.

Table 3.5 SYM53C1010 Internal Pull-ups and Pull-downs

Pin Name	Pull-up Current	Conditions for Pull-up
INTA/, INTB/, ALT_INTA/, ALT_INTB/	25 μ A	Pull-up enabled when the “AND-tree” mode is enabled by driving TEST_RST/ low or when the IRQ mode bit (bit 3 of DCNTL, 0x3B) is cleared. ¹
INT_DIR, TCK, TDI, TEST_RST/, TMS	25 μ A	Pulled up internally.
AD[63:32], C_BE[7:4]/, PAR64	25 μ A	Pulled down internally.
GPIO[4:0]	-25 μ A	Pulled up internally.
MAD[7:0]	-25 μ A	Pulled down internally.
TEST_HSC, TEST_PD, SCAN_MODE	-25 μ A	Pulled down internally.

1. When bit 3 of the [DMA Control \(DCNTL\)](#) register is set, the pad becomes a totem pole output pad and drives both high and low.

3.3 PCI Bus Interface Signals

The PCI Bus Interface Signals section contains tables describing the signals for the following signal groups: [System Signals](#), [Address and Data Signals](#), [Interface Control Signals](#), [Arbitration Signals](#), [Error Reporting Signals](#), [Interrupt Signals](#), [SCSI Function A GPIO Signals](#), and [SCSI Function B GPIO Signals](#).

3.3.1 System Signals

[Table 3.6](#) describes the System Signals group.

Table 3.6 System Signals

Name	Bump	Type	Strength	Description
CLK	H3	I	N/A	Clock provides timing for all transactions on the PCI bus and is an input to every PCI device. All other PCI signals are sampled on the rising edge of CLK. Other timing parameters are defined with respect to this edge.
RST/	G1	I	N/A	Reset forces the PCI sequencer of each device to a known state. All T/S and S/T/S signals are forced to a high impedance state, and all internal logic is reset. The RST/ input is synchronized internally to the rising edge of CLK. To properly reset the device, the CLK input must be active while RST/ is active.

3.3.2 Address and Data Signals

Table 3.7 describes the Address and Data Signals group.

Table 3.7 Address and Data Signals

Name	Bump	Type	Strength	Description
AD[63:0]	Y5, AB5, AC5, AA6, Y6, AB6, AC6, AA7, AB7, AC7, AA8, Y8, AB8, AC8, AA9, Y9, AB9, AC9, AA10, Y11, AB10, AC10, AA11, AC11, AB11, AC12, AA12, AB12, AB13, AC13, AA13, AC14, H1, J3, J4, J2, J1, K3, L4, K2, L1, L2, M1, M3, M2, N2, N1, N3, T4, T3, U1–U3, V1, V2, V4, W1, W2, W4, W3, Y1, Y2, AA1, Y3.	T/S	8 mA PCI	Physical longword Address and Data are multiplexed on the same PCI pins. A bus transaction consists of an address phase followed by one or more data phases. During the first clock of a transaction, AD[63:0] contain a 64-bit physical byte address. If the command is a dual address cycle (DAC), implying a 64-bit address, AD[31:0] will contain the upper 32 bits of the address during the second clock of the transaction. During subsequent clocks, AD[63:0] will contain data. PCI supports both read and write bursts. AD[7:0] define the least significant byte, and AD[63:56] define the most significant byte.
C_BE[7:0]/	AA4, AC3, AB4, AC4, K1, P1, T2, V3.	T/S	8 mA PCI	Bus Command and Byte Enables are multiplexed on the same PCI pins. During the address phase of a transaction, C_BE[3:0]/ define the bus command. If the transaction is a DAC, C_BE[3:0]/ contain the DAC command and C_BE[7:4]/ define the bus command. C_BE[3:0]/ define the bus command during the second clock of the transaction. During the data phase, C_BE[7:0]/ are used as byte enables. The byte enables determine which byte lanes carry meaningful data: C_BE[0]/ applies to byte 0, and C_BE[7]/ to byte 7.
PAR	T1	T/S	8 mA PCI	Parity is the even parity bit that protects the AD[31:0] and C_BE[3:0]/ lines. During the address phase, both the address and command bits are covered. During the data phase, both the data and byte enables are covered.

Table 3.7 Address and Data Signals (Cont.)

Name	Bump	Type	Strength	Description
PAR64	AA5	T/S	8 mA PCI	Parity64 is the even parity bit that protects the AD[63:32] and C_BE[7:4]/ lines. During the address phase, the address and command bits are covered. During the data phase, both the data and byte enables are covered.

3.3.3 Interface Control Signals

Table 3.8 describes the Interface Control Signals group.

Table 3.8 Interface Control Signals

Name	Bump	Type	Strength	Description
ACK64/	AB1	S/T/S	8 mA PCI	Acknowledge 64-bit transfer is driven by the current bus target to indicate its ability to transfer 64-bit data.
REQ64/	AA2	S/T/S	8 mA PCI	Request 64-bit transfer is driven by the current bus master to indicate a request to transfer 64-bit data.
FRAME/	P2	S/T/S	8 mA PCI	Cycle Frame is driven by the current master to indicate the beginning and duration of an access. FRAME/ is asserted to indicate that a bus transaction is beginning. While FRAME/ is deasserted, either the transaction is in the final data phase or the bus is idle.
TRDY/	P3	S/T/S	8 mA PCI	Target Ready indicates the target's ability to complete the current data phase of the transaction. TRDY/ is used with IRDY/. A data phase is completed on any clock when both TRDY/ and IRDY/ are sampled asserted. During a read, TRDY/ indicates that valid data is present on the AD bus. During a write, it indicates that the target is prepared to accept data.
IRDY/	N4	S/T/S	8 mA PCI	Initiator Ready indicates the initiator's ability to complete the current data phase of the transaction. IRDY/ is used with TRDY/. A data phase is completed on any clock when both IRDY/ and TRDY/ are sampled asserted. During a write, IRDY/ indicates that valid data is present on the AD bus. During a read, it indicates that the master is prepared to accept data.

Table 3.8 Interface Control Signals (Cont.)

Name	Bump	Type	Strength	Description
STOP/	R2	S/T/S	8 mA PCI	Stop indicates that the selected target is requesting the master to stop the current transaction.
DEVSEL/	R1	S/T/S	8 mA PCI	Device Select indicates that the driving device has decoded its address as the target of the current access. As an input, it indicates to a master whether any device on the bus has been selected.
IDSEL	L3	I	N/A	Initialization Device Select is used as a chip select, in place of the upper 24 address lines, during configuration read and write transactions.

3.3.4 Arbitration Signals

[Table 3.9](#) describes the Arbitration Signals group.

Table 3.9 Arbitration Signals

Name	Bump	Type	Strength	Description
REQ/	H2	O	8 mA PCI	Request indicates to the system arbiter that this agent requests use of the PCI bus. This is a point-to-point signal. Every master has its own REQ/ signal.
GNT/	H4	I	N/A	Grant indicates to a specific agent that access to the PCI bus has been granted. This is a point-to-point signal. Every master has its own GNT/ signal.

3.3.5 Error Reporting Signals

Table 3.10 describes the Error Reporting Signals group.

Table 3.10 Error Reporting Signals

Name	Bump	Type	Strength	Description
PERR/	R4	S/T/S	8 mA PCI	Parity Error may be pulsed active by an agent that detects a data parity error. PERR/ can be used by any agent to signal data corruption. On detection of a PERR/ pulse, a nonmaskable interrupt is generated to the host CPU, which often implies the system is unable to continue operation once error processing is complete.
SERR/	R3	O	8 mA PCI	System Error is an open drain output used to report address parity errors as well as critical errors other than parity.

3.3.6 Interrupt Signals

Table 3.11 describes the Interrupt Signals group.

Table 3.11 Interrupt Signals

Name ¹	Bump	Type	Strength	Description
INTA/	F4	O	8 mA PCI	Interrupt Function A. This signal, when asserted low, indicates that an interrupting condition in SCSI Function A requires service from the host CPU. The output drive of this pin is open drain. See SCSI Test One (STEST1) for additional information about disabling this interrupt in a RAID environment. This interrupt pin is disabled if INT_DIR is driven low. If the SCSI Function B interrupt is rerouted at power-up using the INTA/ enable sense resistor (pull-up on MAD4), this signal indicates that an interrupting condition has occurred in either SCSI Function A or SCSI Function B.

Table 3.11 Interrupt Signals (Cont.)

Name ¹	Bump	Type	Strength	Description
INTB/	F2	O	8 mA PCI	<p>Interrupt Function B. This signal, when asserted low, indicates that an interrupting condition in SCSI Function B requires service from the host CPU. The output drive of this pin is open drain. See SCSI Test One (STEST1) for additional information about disabling this interrupt in a RAID environment. This interrupt pin is disabled if INT_DIR is driven low.</p> <p>At power-up, this interrupt can be rerouted to INTA/ using the INTA/ enable sense resistor (pull-up on MAD4). This causes the SYM53C1010 to program the SCSI Function B PCI Interrupt Pin (IP) register to 0x01.</p>
ALT_INTA/	F1	O	8 mA PCI	<p>Alt Interrupt Function A. This signal, when asserted low, indicates that an interrupting condition in SCSI Function A requires service. The output drive of this pin is open drain. See SCSI Test One (STEST1) for additional information about disabling this interrupt in a RAID environment.</p> <p>If the SCSI Function B interrupt is rerouted at power-up using the INTA/ enable sense resistor (pull-up on MAD4), this signal indicates that an interrupting condition has occurred in either SCSI Function A or SCSI Function B.</p>
ALT_INTB/	G3	O	8 mA PCI	<p>Alt Interrupt Function B. This signal, when asserted low, indicates that an interrupting condition in SCSI Function B requires service. The output drive of this pin is open drain. See SCSI Test One (STEST1) for additional information about disabling this interrupt in a RAID environment.</p> <p>At power-up, this interrupt can be rerouted to INTA/ using the INTA/ enable sense resistor (pull-up on MAD4). This causes the SYM53C1010 to program the SCSI Function B PCI Interrupt Pin (IP) register to 0x01.</p>

Table 3.11 Interrupt Signals (Cont.)

Name ¹	Bump	Type	Strength	Description
INT_DIR	G2	I	N/A	Interrupt Direction. This input signal indicates whether internally generated interrupts are presented on INTA/ and INTB/. If INT_DIR is high, internal interrupts are generated on both the INTx/ pins and the ALT_INTx pin. If INT_DIR is low, the internal interrupts are generated only on the ALT_INTx/ pin. This pin has no effect if either bit 0 or 1 in STEST1 is set. This pin has a static pull-up.

1. See register 0x4D, [SCSI Test One \(STEST1\)](#) in [Chapter 4, "Registers"](#) for additional information on these signals.

3.3.7 SCSI Function A GPIO Signals

[Table 3.12](#) describes the SCSI Function A GPIO Signals group.

Table 3.12 SCSI Function A GPIO Signals

Name	Bump	Type	Strength	Description
A_GPIO0_FETCH/	AB16	I/O	8 mA	SCSI Function A General Purpose I/O pin 0. This pin is programmable at power-up, through the MAD7 pin, to serve as the data signal for the serial EEPROM interface. When GPIO_0 is not in the process of downloading EEPROM data it can be used to drive a SCSI Activity LED, if bit 5 in the General Purpose Pin Control (GPCNTL) register is set. Or, it can be used to indicate that the next bus request will be an opcode fetch if bit 6 in the GPCNTL register is set.
A_GPIO1_MASTER/	Y16	I/O	8 mA	SCSI Function A General Purpose I/O pin 1. This pin is programmable at power-up, through the MAD7 pin, to serve as the clock signal for the serial EEPROM interface. If bit 7 of the General Purpose Pin Control (GPCNTL) register is set, this pin drives low when the SYM53C1010 is the bus master.
A_GPIO2	AA16	I/O	8 mA	SCSI Function A General Purpose I/O pin 2. This pin powers up as an input.
A_GPIO3	AC17	I/O	8 mA	SCSI Function A General Purpose I/O pin 3. This pin powers up as an input.
A_GPIO4	AB17	I/O	8 mA	SCSI Function A General Purpose I/O pin 4. This pin powers up as an output. It can be used as the enable line for V _{PP} , the 12 V power supply to the external flash memory interface.

3.3.8 SCSI Function B GPIO Signals

Table 3.13 describes the SCSI Function B GPIO Signals group.

Table 3.13 SCSI Function B GPIO Signals

Name	Bump	Type	Strength	Description
B_GPIO0_FETCH/	AA14	I/O	8 mA	SCSI Function B General Purpose I/O pin 0. This pin is programmable at power-up through the MAD7 pin to serve as the data signal for the serial EEPROM interface. When GPIO_0 is not in the process of downloading EEPROM data, it can be used to drive a SCSI Activity LED if bit 5 in the General Purpose Pin Control (GPCNTL) register is set. Or, it can be used to indicate that the next bus request will be an opcode fetch if bit 6 in the GPCNTL register is set.
B_GPIO1_MASTER/	AC15	I/O	8 mA	SCSI Function B General Purpose I/O pin 1. This pin is programmable at power-up through the MAD7 pin to serve as the clock signal for the serial EEPROM interface. If bit 7 of the General Purpose Pin Control (GPCNTL) register is set, this pin is driven low when the SYM53C1010 is the bus master.
B_GPIO2	AB15	I/O	8 mA	SCSI Function B General Purpose I/O pin 2. This pin powers up as an input.
B_GPIO3	AA15	I/O	8 mA	SCSI Function B General Purpose I/O pin 3. This pin powers up as an input.
B_GPIO4	AC16	I/O	8 mA	SCSI Function B General Purpose I/O pin 4. This pin powers up as an output. It can be used as the enable line for V_{PP} , the 12 V power supply to the external flash memory interface.

3.4 SCSI Bus Interface Signals

The SCSI Bus Interface Signals section contains tables describing the signals for the following signal groups: [SCSI Bus Interface Signals](#), [SCSI Function A Signals](#), and [SCSI Function B Signals](#). SCSI Function A signals and SCSI Function B signals each have a subgroup: the [SCSI Function A Control Signals](#) and the [SCSI Function B Control Signals](#).

[Table 3.14](#) contains signals that are common to both SCSI buses.

Table 3.14 SCSI Bus Interface Signals

Name	Bump	Type	Strength	Description
SCLK	A21	I	N/A	SCSI Clock is used to derive all SCSI related timings. The speed of this clock must be 40 MHz. The clock frequency can be quadrupled to create the 160 MHz clock required internally by both SCSI functions.

3.4.1 SCSI Function A Signals

This section describes the signals for the SCSI Function A signals group. It is divided into two tables: [Table 3.15](#) describes SCSI Function A signals and [Table 3.16](#) describes SCSI Function A Control signals.

Table 3.15 SCSI Function A Signals

Name	Bump	Type	Strength	Description
A_SD[15:0]–	B5, C5, B4, C4, D19, A19, D18, A18, D11, A9, D9, A8, D8, A7, C7, B6.	I/O	SE: 48 mA SCSI LVD: 12 mA UniLVD	SCSI Function A Data. LVD Mode: Negative half of the LVD Link pair for the SCSI data lines. A_SD[15:0]– form the 16-bit SCSI data bus. SE Mode: A_SD[15:0]– form the 16-bit SCSI data bus.
A_SD[15:0]+	A5, D5, A4, A3, C19, B19, C18, B18, B10, C10, B9, C9, B8, C8, B7, A6.	I/O	SE: 48 mA SCSI LVD: 12 mA UniLVD	SCSI Function A Data. LVD Mode: Positive half of the LVD Link pair for the SCSI data lines. A_SD[15:0]+ form the 16-bit data bus. SE Mode: A_SD[15:0]+ are at 0 V.

Table 3.15 SCSI Function A Signals (Cont.)

Name	Bump	Type	Strength	Description
A_SDP[1:0]-	C6, A10.	I/O	SE: 48 mA SCSI LVD: 12 mA UniLVD	SCSI Function A Parity. LVD Mode: Negative half of the LVD Link pair for the SCSI parity lines. A_SDP[1:0]- are the SCSI data parity lines. SE Mode: A_SDP[1:0]- are the SCSI data parity lines.
A_SDP[1:0]+	D6, C11.	I/O	SE: 48 mA SCSI LVD: 12 mA UniLVD	SCSI Function A Parity. LVD Mode: Positive half of the LVD Link pair for the SCSI parity lines. A_SDP[1:0]+ are the SCSI data parity lines. SE Mode: A_SDP[1:0]+ are at 0 V.
A_DIFFSENS	A20	I	N/A	SCSI Function A Differential Sense pin detects the present mode of the SCSI bus when connected to the DIFFSENS signal on the physical SCSI bus. LVD Mode: If a voltage between 0.7 V and 1.9 V is present, SCSI Function A operates in the LVD mode. SE Mode: When this pin is driven low (below 0.5 V), SE operation is indicated. SCSI Function A operates in the SE mode. HVD Mode: When this pin is detected high (above 2.0 V), HVD operation is indicated. SCSI Function A is driven to the high impedance state. This pin is 5 V tolerant. HVD Mode is not supported.

Table 3.16 SCSI Function A Control Signals

Name ¹	Bump	Type	Strength	Description
SCSI Function A Control includes the following signals:				
A_SC_D- A_SC_D+	C15 A16	I/O	SE: 48 mA SCSI LVD: 12 mA UniLVD	SCSI phase line, command/data.
A_SI_O- A_SI_O+	B17 C17			SCSI phase line, input/output.
A_SMSG- A_SMSG+	C14 A15			SCSI phase line, message.
A_SREQ- A_SREQ+	C16 A17			Data handshake line from target device.
A_SACK- A_SACK+	C13 A14			Data handshake signal from the initiator device.
A_SBSY- A_SBSY+	C12 A12			SCSI bus arbitration signal, busy.
A_SATN- A_SATN+	B11 B12			SCSI Attention, the initiator is requesting a message out phase.
A_SRST- A_SRST+	B14 D13			SCSI bus reset.
A_SSEL- A_SSEL+	B15 D15			SCSI bus arbitration signal, select device.

1. LVD Mode: Negative and positive halves of the LVD Link signal pairs are shown for SCSI Function A Control. SE Mode: The SCSI Function A Control signals are shown. All the positive (+) signals are at 0 Volts.

3.4.2 SCSI Function B Signals

This section describes the SCSI Function B Signals group. It is divided into two tables: [Table 3.17](#) describes SCSI Function B Signals and [Table 3.18](#) describes SCSI Function B Control Signals.

Table 3.17 SCSI Function B Signals

Name	Bump	Type	Strength	Description
B_SD[15:0]–	F21, E22, E21, D22, Y22, W21, W22, V21, K23, L20, J23, J20, H23, H20, G23, G21.	I/O	SE: 48 mA SCSI LVD: 12 mA UniLVD	SCSI Function B Data. LVD Mode: Negative half of the LVD Link pair for the SCSI data lines. B_SD[15:0]– form the 16-bit SCSI data bus. SE Mode: B_SD[15:0]– form the 16-bit SCSI data bus.
B_SD[15:0]+	F20, E23, E20, D23, AA23, Y23, W20, W23, L21, K22, K21, J22, J21, H22, H21, G22.	I/O	SE: 48 mA SCSI LVD: 12 mA UniLVD	SCSI Function B Data. LVD Mode: Positive half of the LVD Link pair for the SCSI data lines. B_SD[15:0]+ form the 16-bit data bus. SE Mode: B_SD[15:0]+ are at 0 V.
B_SDP[1:0]–	F22, L23.	I/O	SE: 48 mA SCSI LVD: 12 mA UniLVD	SCSI Function B Parity. LVD Mode: Negative half of the LVD Link pair for the SCSI parity lines. B_SDP[1:0]– are the SCSI data parity lines. SE Mode: B_SDP[1:0]– are the SCSI data parity lines.

Table 3.17 SCSI Function B Signals (Cont.)

Name	Bump	Type	Strength	Description
B_SDP[1:0]+	F23, L22.	I/O	SE: 48 mA SCSI LVD: 12 mA UniLVD	<p>SCSI Function B Parity.</p> <p>LVD Mode: Positive half of the LVD Link pair for the SCSI parity lines. B_SDP[1:0]+ are the SCSI data parity lines.</p> <p>SE Mode: B_SDP[1:0]+ are at 0 V.</p>
B_DIFFSENS	Y21	I	N/A	<p>SCSI Function B Differential Sense pin detects the present mode of the SCSI bus when connected to the DIFFSENS signal on the physical SCSI bus.</p> <p>LVD Mode: If a voltage between 0.7 V and 1.9 V is present, SCSI Function B operates in the LVD mode.</p> <p>SE Mode: If a voltage below 0.5 V is present, SE operation is indicated. SCSI Function B operates in the SE mode.</p> <p>HVD Mode: When this pin is detected high (above 2.0 V) HVD operation is indicated. SCSI Function B is driven to the high impedance state. This pin is 5 V tolerant. HVD mode is not supported.</p>

Table 3.18 SCSI Function B Control Signals

Name ¹	Bump	Type	Strength	Description
SCSI Function B Control includes the following signals:				
B_SC_D- B_SD_D+	T20 T21	I/O	SE: 48 mA SCSI LVD: 12 mA UniLVD	SCSI phase line, command/data.
B_SI_O- B_SI_O+	V22 V20			SCSI phase line, input/output.
B_SMSG- B_SMSG+	R20 R21			SCSI phase line, message.
B_SREQ- B_SREQ+	U21 V23			Data handshake line from target device.
B_SACK- B_SACK+	N20 P21			Data handshake signal from the initiator device.
B_SBSY- B_SBSY+	N23 N21			SCSI bus arbitration signal, busy.
B_SATN- B_SATN+	M23 N22			SCSI Attention, the initiator is requesting a message out phase.
B_SRST- B_SRST+	R23 R22			SCSI bus reset.
B_SSEL- B_SSEL+	T23 T22			SCSI bus arbitration signal, select device.

1. LVD Mode: Negative and positive halves of the LVD Link signal pairs are shown for the SCSI Function B Control. SE Mode: The SCSI Function B Control signals are shown. All the positive (+) signals are at 0 Volts.

3.5 Flash ROM and Memory Interface Signals

Table 3.19 describes the signals for the Flash ROM and Memory Interface Signals group.

Table 3.19 Flash ROM and Memory Interface Signals

Name	Bump	Type	Strength	Description
MWE/	AC19	O	4 mA	Memory Write Enable. This pin is used as a write enable signal to an external flash memory.
MCE/	AA18	O	4 mA	Memory Chip Enable. This pin is used as a chip enable signal to an external EPROM or flash memory device.
MOE/_ TESTOUT	Y18	O	4 mA	Memory Output Enable. This pin is used as an output enable signal to an external EPROM or flash memory during read operations. It is also used to test the connectivity of the SYM53C1010 signals in the “AND-tree” test mode.
MAS0/	AC18	O	4 mA	Memory Address Strobe 0. This pin is used to latch in the least significant address byte (bits [7:0]) of an external EPROM or flash memory. Since the SYM53C1010 moves addresses eight bits at a time, this pin connects to the clock of an external bank of flip-flops that assemble up to a 20-bit address for the external memory.
MAS1/	AA17	O	4 mA	Memory Address Strobe 1. This pin is used to latch in the most significant address byte (bits [15:8]) of an external EPROM or flash memory. Since the SYM53C1010 moves addresses eight bits at a time, this pin connects to the clock of an external bank of flip-flops that assemble up to a 20-bit address for the external memory.
MAD[7:0]	Y19, AA19, AC20, AB20, AA20, AC22, AB21, AC23.	I/O	4 mA	Memory Address/Data Bus. This bus is used in conjunction with the memory address strobe pins and external address latches to assemble up to a 20-bit address for an external EPROM or flash memory. This bus first issues the least significant byte and finishes with the most significant bits. It is also used to write data to a flash memory or read data into the chip from external EPROM/flash memory. These pins have static pull-downs.

3.6 Test Interface Signals

Table 3.20 describes the Test Interface Signals group. Table 3.20 is divided into Internal Test Signals and JTAG Signals.

Table 3.20 Test Interface Signals

Name	Bump	Type	Strength	Description
Internal Test Signals:				
SCAN_MODE	C22	I	N/A	Scan Mode. For LSI Logic test purposes only. This pin has a static pull-down.
TEST_HSC	C23	I	N/A	Test Halt SCSI Clock. For LSI Logic test purposes only. Pulled LOW internally. This signal can also cause a full chip reset.
TEST_PD	A2	I	N/A	Test Power Down. For LSI Logic test purposes only. This pin has a static pull-down.
TEST_RST/	C1	I	N/A	Test Reset. For LSI Logic test purposes only. Pulled HIGH internally.
MOE/ TESTOUT	Y18	O	4 mA	Memory Output Enable. This pin is used as an output enable signal to an external EPROM or flash memory during read operations. It is also used to test the connectivity of the SYM53C1010 signals in the “AND-tree” test mode.
JTAG Signals:				
TCK	D1	I	N/A	Test Clock. This pin provides the clock for the JTAG test logic. This pin has a static pull-up.
TMS	E3	I	N/A	Test Mode Select. The signal received at TMS is decoded by the TAP controller to control JTAG test operations. This pin has a static pull-up.
TDI	E2	I	N/A	Test Data In. This pin receives the serial test instructions for the JTAG test logic. This pin has a static pull-up.
TDO	E1	O	4 mA	Test Data Out. This pin is the serial output for test instructions and data from the JTAG test logic.
Reserved	AB14			Reserved. Not Used.

3.7 Power and Ground Signals

Table 3.21 describes the Power and Ground Signals group.

Table 3.21 Power and Ground Signals

Name ¹	Bump	Type	Strength	Description
V _{SS_IO}	C3, C21, D4, D12, D20, K10–14, L10–14, M4, M10–14, M20, N10–14, P10–14, Y4, Y12, Y20, AA3, AA21.	G	N/A	Ground for PCI bus drivers/receivers, SCSI bus drivers, local memory interface drivers, and other I/O pins.
V _{DD_IO}	D7, D10, D14, D17, G4, G20, K4, K20, P4, P20, U4, U20, Y7, Y10, Y14, Y17.	P	N/A	Power for PCI bus drivers/receivers, SCSI bus drivers/receivers, local memory interface drivers/receivers, and other I/O pins.
V _{DD_CORE}	B22, B23, D3, E4, Y13, AB3, AB18, AB23, AC1.	P	N/A	Power for core logic.
V _{SS_CORE}	A22, D2, D21, F3, Y15, AB2, AA22, AB19, AC2, AC21.	G	N/A	Ground for core logic.
V _{DD_A} ²	B2, C20	P	N/A	Power for analog cells (clock quadrupler and DIFFSENS logic).
V _{SS_A} ²	B20, C2	G	N/A	Ground for analog cells (clock quadrupler and DIFFSENS logic).
V _{DD_Bias}	M22	P	N/A	Power for SCSI Function A RBIAS circuit.
V _{DD_Bias2}	A11	P	N/A	Power for SCSI Function B RBIAS circuit.
RBIAS	M21	I	N/A	Used to connect an external resistor to generate the LVD Link pad bias current. The resistor value should be 10 kΩ. Connect the other end of the resistor to V _{DD} .
NC	A1, A13, A23, B1, B3, B13, B16, B21, D16, P22, P23, U22, U23, AB22.	N/A	N/A	These pins are reserved or have no internal connection.

1. The I/O driver pad rows and digital core have isolated power supplies as indicated by the “I/O” and “CORE” extensions on their respective V_{SS} and V_{DD} names. Connect the power and ground pins directly to the primary power and ground planes of the circuit board. Apply bypass capacitors of 0.01 μF between adjacent V_{SS} and V_{DD} pairs wherever possible. Do not connect bypass capacitors between V_{SS} and V_{DD} pairs that cross power and ground bus boundaries.
2. To reduce signal noise that can affect FSN functionality, place a ferrite bead in series with the V_{DD-A} and V_{SS-A} pins. The recommended rating of the bead is 150 Ohms at 100 MHz.

3.8 MAD Bus Programming

The MAD[7:0] pins, in addition to serving as the address/data bus for the local memory interface, also are used to program power-up options for the chip. A particular option is programmed allowing the internal pull-down current sink to pull the pin LOW at reset or by connecting a 4.7 k Ω resistor between the appropriate MAD[x] pin and V_{DD}. The pull-down resistors require that HC or HCT external components are used for the memory interface. A description of the MAD bus pins follows:

- **MAD[7] Serial EEPROM programmable option** – When pulled LOW by the internal pull-down current sink, the automatic data download is enabled. When pulled HIGH by an external resistor, the automatic data download is disabled. See [Section 2.4, “Serial EEPROM Interface”](#) and the [Subsystem ID \(SID\)](#) and [Subsystem Vendor ID \(SVID\)](#) register descriptions.
- **MAD[6]** – Reserved.
- **MAD[5]** – Reserved.
- **MAD[4] INTA/ routing enable** – Placing a pull-up resistor on this pin causes SCSI Function B interrupt requests to appear on the INTA/ pin, along with SCSI Function A interrupt requests, instead of on INTB/. Placing a pull-up resistor on this pin also programs the SCSI Function B [Interrupt Pin \(IP\)](#) register in PCI configuration space to 0x01 instead of 0x02.

Placing no resistor on this pin causes SCSI Function B interrupt requests to appear on the INTB/ pin and programs the SCSI Function B [Interrupt Pin \(IP\)](#) register in PCI configuration space to 0x02.

- **MAD[3:1] pins** – These pins set the size of the external expansion ROM device attached. The encoding for these pins is listed in the following table. A “0” indicates a pull-down resistor is attached while a “1” indicates a pull-up resistor attached.

Table 3.22 MAD[3:1] Pin Decoding

MAD[3:1]	Available Memory Space
000	16 Kbytes
001	32 Kbytes
010	64 Kbytes
011	128 Kbytes
100	256 Kbytes
101	512 Kbytes
110	1024 Kbytes
111	no external memory present

- **MAD[0] slow ROM pin** – When pulled up, it enables use of slower memory devices by including two extra data access cycles.

Note: All MAD pins have internal pull-down resistors.

Chapter 4

Registers

This section contains descriptions of all SYM53C1010-33 registers. The term “set” refers to bits programmed to a binary one. Similarly, the term “cleared” refers to bits programmed to a binary zero. Do not access reserved bits. Reserved bit functions may change at any time. Unless otherwise indicated, all bits in the registers are active high; the feature is enabled by setting the bit. The bottom row of every register diagram presents the default register values, which are enabled after the chip is powered on or reset.

This chapter contains the following sections:

- [Section 4.1, “PCI Configuration Registers”](#)
 - [Section 4.2, “SCSI Registers”](#)
 - [Section 4.3, “SCSI Shadow Registers”](#)
-

4.1 PCI Configuration Registers

To access the PCI Configuration registers, perform a configuration read or write to a device with its IDSEL pin asserted. The appropriate address value is in AD[10:8] during the address phase of the transaction. SCSI Function A is identified by a binary value of 0b000, and SCSI Function B by a value of 0b001. Each SCSI function contains the same register set with identical default values, except the [Interrupt Pin \(IP\)](#) register. [Table 2.1](#) shows the PCI configuration registers implemented in the SYM53C1010.

All PCI-compliant devices, such as the SYM53C1010, support [Vendor ID](#), [Device ID](#), [Command](#), and [Status](#) registers. Support of other PCI-compliant registers is optional. In the SYM53C1010, registers that are not supported are not writable and return all zeros when read. Only

those registers and bits that are currently supported by the SYM53C1010 are described in this chapter. Do not access bits marked as Reserved.

Table 4.1 PCI Configuration Register Map

31		16 15		0	Address	Page
Device ID		Vendor ID		0x00		4-3
Status		Command		0x04		4-3
Class Code (CC)			Revision ID (RID)	0x08		4-7
Reserved	Header Type (HT)	Latency Timer (LT)	Cache Line Size (CLS)	0x0C		4-7
Base Address Register Zero (BAR0) (I/O)				0x10		4-9
Base Address Register One (BAR1) (MEMORY) bits [31:0]				0x14		4-10
Base Address Register Two (BAR2) (MEMORY) bits [31:0]				0x18		4-10
Base Address Register Three (BAR3) (SCRIPTS RAM) bits [31:0]				0x1C		4-11
Base Address Register Four (BAR4) (SCRIPTS RAM) bits [31:0]				0x20		4-11
Reserved				0x24		4-12
Reserved				0x28		4-12
Subsystem ID (SID)		Subsystem Vendor ID (SVID)		0x2C		4-12
Expansion ROM Base Address (ERBA)				0x30		4-14
Reserved			Capabilities Pointer (CP)	0x34		4-15
Reserved				0x38		4-15
Max_Lat (ML)	Min_Gnt (MG)	Interrupt Pin (IP)	Interrupt Line (IL)	0x3C		4-16
Power Management Capabilities (PMC)		Next Item Pointer (NIP)	Capability ID (CID)	0x40		4-18
Data	Bridge Support Extensions (PMCSR_BSE)	Power Management Control/Status (PMCSR)		0x44		4-20

Registers: 0x00–0x01

Vendor ID

Read Only

15															0
VID															
0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0

VID **Vendor ID** **[15:0]**

This 16-bit register identifies the manufacturer of the device. The Vendor ID is 0x1000.

Registers: 0x02–0x03

Device ID

Read Only

15															0
DID															
0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0

DID **Device ID** **[15:0]**

This 16-bit register identifies the particular device. The SYM53C1010-33 Device ID is 0x0020.

Registers: 0x04–0x05

Command

Read/Write

15							9	8	7	6	5	4	3	2	1	0
R							SE	R	EPER	R	WIE	R	EBM	EMS	EIS	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	

The SCSI Command register provides coarse control over a device's ability to generate and respond to PCI cycles. When a zero is written to this register, the SYM53C1010 is logically disconnected from the PCI bus for all accesses except configuration accesses.

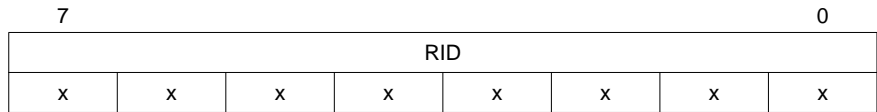
R	Reserved	[15:9]
SE	SERR/ Enable	8
	When this bit is set, the SYM53C1010 enables the SERR/ driver. SERR/ is disabled when this bit is cleared. The default value of this bit is zero. This bit and bit 6 must be set to report address parity errors.	
R	Reserved	7
EPER	Enable Parity Error Response	6
	When this bit is set, the SYM53C1010 detects parity errors on the PCI bus and reports these errors to the system. Only data parity checking is affected with this bit. The SYM53C1010 always generates parity for the PCI bus.	
R	Reserved	5
WIE	Write and Invalidate Enable	4
	When this bit is set, the SYM53C1010 can generate write and invalidate commands on the PCI bus. The WRIE bit in the Chip Test Three (CTEST3) register must also be set for the device to generate write and invalidate commands.	
R	Reserved	3
EBM	Enable Bus Mastering	2
	This bit controls the ability of the SYM53C1010 to act as a master on the PCI bus. A value of zero disables this device from generating PCI bus master accesses. A value of one allows the SYM53C1010 to behave as a bus master. The device must be a bus master to fetch SCRIPTS instructions and transfer data.	
EMS	Enable Memory Space	1
	This bit controls the ability of the SYM53C1010 to respond to Memory space accesses. A value of zero disables the device response. A value of one allows the SYM53C1010 to respond to Memory Space accesses at the address range specified by the Base Address Register One (BAR1) (MEMORY) , Base Address Register Two (BAR2) (MEMORY) , Base Address Register Three (BAR3) (SCRIPTS RAM) , and the Base Address Register	

R	Reserved	11								
DT[1:0]	DEVSEL/ Timing These bits encode the timing of DEVSEL/. The timings are encoded as:	[10:9]								
	<table border="0" style="width: 100%;"> <tr> <td style="width: 100px;">0b00</td> <td>fast</td> </tr> <tr> <td>0b01</td> <td>medium</td> </tr> <tr> <td>0b10</td> <td>slow</td> </tr> <tr> <td>0b11</td> <td>reserved.</td> </tr> </table>	0b00	fast	0b01	medium	0b10	slow	0b11	reserved.	
0b00	fast									
0b01	medium									
0b10	slow									
0b11	reserved.									
	These bits are read only and indicate the slowest time that a device asserts DEVSEL/ for any bus command except Configuration Read and Configuration Write. The SYM53C1010 supports a value of 0b01.									
DPR	Data Parity Error Reported This bit is set when the following conditions are met:	8								
	<ul style="list-style-type: none"> • The bus agent asserts PERR/ itself or observes PERR/ asserted and; • The agent setting this bit acted as the bus master for the errant operation and; • The Parity Error Response bit in the Command register is set. 									
FBBC	Fast Back-to-Back Capable This bit is zero.	7								
R	Reserved	6								
66C	Reserved This bit is always set to zero.	5								
NC	New Capabilities This bit is set to indicate a list of extended capabilities such as PCI Power Management. This bit is read only.	4								
R	Reserved	[3:0]								

Register: 0x08

Revision ID (RID)

Read Only



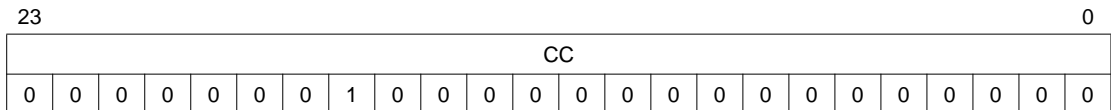
RID **Revision ID** **[7:0]**

This register indicates the current revision level of the device.

Registers: 0x09–0x0B

Class Code (CC)

Read Only



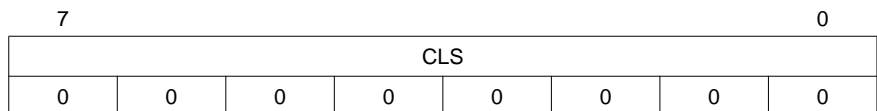
CC **Class Code** **[23:0]**

This 24-bit register identifies the generic function of the device. The upper byte of this register is a base class code, the middle byte is a subclass code, and the lower byte identifies a specific register-level programming interface. The value of this register is 0x010000, which identifies a SCSI controller.

Register: 0x0C

Cache Line Size (CLS)

Read/Write



CLS **Cache Line Size** **[7:0]**

This register specifies the system cache line size in units of 32-bit words. The value in this register is used by the device to determine whether to use Write and Invalidate or Write commands for performing write cycles, and whether to use Read, Read Line, or Read Multiple

commands for performing read cycles as a bus master. Devices participating in the caching protocol use this field to determine when to retry burst accesses at cache line boundaries. These devices can ignore the PCI cache support lines (SDONE and SB0/) if this register is set to 0. If this register is programmed to a number which is not a power of 2, the device does not use PCI performance commands to execute data transfers.

Register: 0x0D

Latency Timer (LT)

Read/Write

7							0
LT							
0	0	0	0	0	0	0	0

LT

Latency Timer

[7:0]

The Latency Timer register specifies, in units of PCI bus clocks, the value of the Latency Timer for this PCI bus master. The SCSI functions of the SYM53C1010 support this timer. All eight bits are writable, allowing latency values of 0–255 PCI clocks. Use the following equation to calculate an optimum latency value for the SCSI functions of the SYM53C1010.

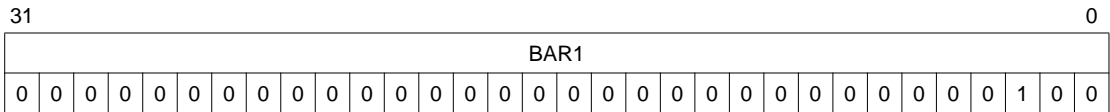
$$\text{Latency} = 2 + (\text{Burst Size} * (\text{typical wait states} + 1))$$

Values greater than optimum are also acceptable.

Registers: 0x14–0x17

Base Address Register One (BAR1) (MEMORY)

Read/Write



BAR1

Base Address Register One

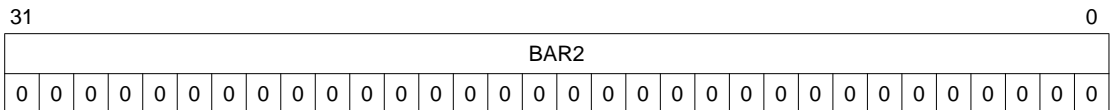
[31:0]

This base address register, in conjunction with [Base Address Register Two \(BAR2\) \(MEMORY\)](#), maps SCSI operating registers into memory space and represents the lower 32 bits of the memory address. Bits [9:0] are hardwired to 0b0000000100. The default value of this register is 0x00000004. The SYM53C1010 requires 1024 bytes of memory space. For detailed information on the operation of this register, refer to the PCI 2.2 specification.

Registers: 0x18–0x1B

Base Address Register Two (BAR2) (MEMORY)

Read/Write



BAR2

Base Address Register Two

[31:0]

This base address register, in conjunction with [Base Address Register One \(BAR1\) \(MEMORY\)](#), maps SCSI operating registers into memory space and represents the upper 32 bits of the memory address. The default value of this register is 0x00000000. The SYM53C1010 requires 1024 bytes of memory space. For detailed information on the operation of this register, refer to the PCI 2.2 specification.

the value downloaded from the serial EEPROM or, if the download fails, a value of 0x0000.

If the external serial EEPROM interface is disabled (MAD[7] HIGH), this register returns a value of 0x1000. The 16-bit value that should be stored in the external serial EEPROM for this register is the vendor's PCI Vendor ID. This value must be obtained from the PCI Special Interest Group (SIG). Please see [Section 2.4, "Serial EEPROM Interface"](#) for more information on downloading a value for this register.

Registers: 0x2E–0x2F

Subsystem ID (SID)

Read Only

15	SID														0
If MAD[7] is HIGH															
0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0
If MAD[7] is LOW															
x	x	x	x	x	x	x	x	x	x	x	x	x	x	x	x

SID

Subsystem ID

[15:0]

This 16-bit register is used to uniquely identify the add-in board or subsystem where this PCI device resides. It provides a mechanism for an add-in card vendor to distinguish its cards from one another even if the cards have the same PCI controller installed on them (and therefore the same Vendor ID and Device ID).

If the external serial EEPROM interface is enabled (MAD[7] is LOW), this register is automatically loaded at power-up from the external serial EEPROM and contains the value downloaded from the serial EEPROM or, if the download fails, a value of 0x0000.

If the external serial EEPROM is disabled (MAD[7] pulled HIGH), the register returns a value of 0x1000. The 16-bit value stored in the external serial EEPROM is vendor specific. Please see [Section 2.4, "Serial EEPROM Interface"](#) for additional information on downloading a value for this register.

Register: 0x3C
Interrupt Line (IL)
Read/Write

7								0
IL								
0	0	0	0	0	0	0	0	

IL **Interrupt Line** **[7:0]**

This register is used to communicate interrupt line routing information. POST software writes the routing information into this register as it configures the system. The value in this register tells which input of the system interrupt controller(s) the device's interrupt pin is connected to. Values in this register are specified by system architecture.

Register: 0x3D
Interrupt Pin (IP)
Read Only

7								0
IP								
SCSI Function A								
0	0	0	0	0	0	0	1	
SCSI Function B if MAD[4] pulled LOW								
0	0	0	0	0	0	1	0	
SCSI Function B if MAD[4] pulled HIGH								
0	0	0	0	0	0	0	1	

IP **Interrupt Pin** **[7:0]**

This register is unique to each SCSI function. It tells which interrupt pin the device uses. Its value is set to 0x01 for the Function A (INTA/) signal, and 0x02 for the Function B (INTB/) signal at power-up if MAD[4] is pulled LOW. The Function B value is set to 0x01 (INTA/) if MAD[4] is pulled HIGH.

Note: Please see [Section 3.8, "MAD Bus Programming"](#) for additional information.

Register: 0x3E**Min_Gnt (MG)****Read Only**

7							0
MG							
0	0	0	1	0	0	0	1

MG**Min_Gnt****[7:0]**

This register is used to specify the desired settings for latency timer values. Min_Gnt is used to specify how long a burst period the device needs. The value specified in these registers is in units of 0.25 microseconds. The SYM53C1010 sets this register to 0x11.

Register: 0x3F**Max_Lat (ML)****Read Only**

7							0
ML							
0	0	0	1	0	0	1	0

ML**Max_Lat****[7:0]**

This register is used to specify the desired settings for latency timer values. Max_Lat is used to specify how often the device needs to gain access to the PCI bus. The value specified in this register is in units of 0.25 microseconds. The SYM53C1010 SCSI function sets this register to 0x12 indicating it needs the bus every 4.5 μ s to maintain a data stream of 160 Mbytes/s.

Register: 0x40
Capability ID (CID)
 Read Only

7								0
CID								
0	0	0	0	0	0	0	1	

CID **Capability ID** **[7:0]**
 This register indicates the type of data structure currently being used. It is set to 0x01, indicating the Power Management Data Structure.

Register: 0x41
Next Item Pointer (NIP)
 Read Only

7								0
NIP								
0	0	0	0	0	0	0	0	

NIP **Next Item Pointer** **[7:0]**
 Bits [7:0] contain the offset location of the next item in the function's capabilities list. The SYM53C1010 has these bits set to zero indicating no further extended capabilities registers exist.

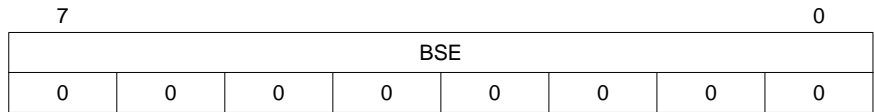
Registers: 0x42–0x43
Power Management Capabilities (PMC)
 Read Only

15					11	10	9	8				6	5	4	3	2	0
PMES				D2S	D1S	AUX_C			DSI	R	PMEC	VER[2:0]					
0	0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	1	0

PMES **PME_Support** **[15:11]**
 Bits [15:11] define the power management states in which the SYM53C1010 will assert the PME pin. These bits are all set to zero because the SYM53C1010 does not provide a PME signal.

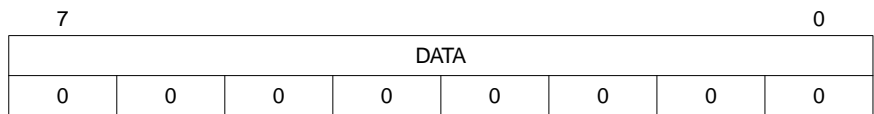
D2S	D2_Support	10
	The SYM53C1010 sets this bit to indicate support for power management state D2. Bits 9 and 10 are set to indicate support for the D1 and D2 power states.	
D1S	D1_Support	9
	The SYM53C1010 sets this bit to indicate support for power management state D1. Bits 9 and 10 are set to indicate support for the D1 and D2 power states.	
AUX_C	Aux_Current	[8:6]
	The SYM53C1010 always returns zeros. This feature is not supported.	
DSI	Device Specific Initialization	5
	This bit is cleared to indicate that the SYM53C1010 requires no special initialization before the generic class device driver is able to use it.	
R	Reserved	4
PMEC	PME Clock	3
	Bit 3 is cleared because the SYM53C1010 does not provide a PME pin.	
VER[2:0]	Version	[2:0]
	These three bits are set to 0b010 to indicate that the SYM53C1010 complies with Revision 1.1 of the PCI Power Management Interface Specification.	

Register: 0x46
Bridge Support Extensions (PMCSR_BSE)
Read Only



BSE **Bridge Support Extensions** **[7:0]**
 This register indicates PCI Bridge specific functionality.
 The SYM53C1010 always returns 0x00.

Register: 0x47
Data
Read Only



DATA **Data** **[7:0]**
 This register provides an optional mechanism for the
 function to report state-dependent operating data. The
 SYM53C1010 always returns 0x00.

4.2 SCSI Registers

The control registers for the SCSI core are directly accessible from the PCI bus using Memory or I/O mapping. SCSI Function A and SCSI Function B contain the same register set with identical default values, except the Interrupt Pin registers. The address map of the SCSI registers is shown in [Table 4.2](#).

The eight 32-bit phase mismatch registers contain the byte count and addressing information required to update the Direct, Indirect, or Table Indirect BMOV instructions with new byte counts and addresses. The phase mismatch registers are the [Phase Mismatch Jump Address One \(PMJAD1\)](#), [Phase Mismatch Jump Address Two \(PMJAD2\)](#), [Remaining Byte Count \(RBC\)](#), [Updated Address \(UA\)](#), [Entry Storage Address \(ESA\)](#), [Instruction Address \(IA\)](#), [SCSI Byte Count \(SBC\)](#), and the [Cumulative SCSI Byte Count \(CSBC\)](#). All the phase mismatch registers can be read/written using the Load and Store SCRIPTS instructions, Memory-to-Memory Moves, Read/Write SCRIPTS instructions, or the CPU with SCRIPTS not running.

Note: The only registers that the host CPU can access while the SYM53C1010 is executing SCRIPTS are the [Interrupt Status Zero \(ISTAT0\)](#), [Interrupt Status One \(ISTAT1\)](#), [Mailbox Zero \(MBOX0\)](#), and [Mailbox One \(MBOX1\)](#) registers; attempts to access other registers interfere with the operation of the chip. However, all operating registers are accessible with SCRIPTS. All read data is synchronized and stable when presented to the PCI bus.

Do not access reserved bits or registers.

Table 4.2 SCSI Register Map

31	24	23	16	15	8	7	0	Address	Page
SCNTL3		SCNTL2		SCNTL1		SCNTL0		0x00	4-24
GPREG		SDID		SXFER		SCID		0x04	4-33
SBCL		SSID		SOCL		SFBR		0x08	4-37
SSTAT2		SSTAT1		SSTAT0		DSTAT		0x0C	4-40
DSA								0x10	4-47
MBOX1		MBOX0		ISTAT1		ISTAT0		0x14	4-47
CTEST3		CTEST2		CTEST1		CTEST0		0x18	4-53
TEMP								0x1C	4-56
CTEST6		CTEST5		CTEST4		Reserved		0x20	4-57
DCMD		DBC						0x24	4-61
DNAD								0x28	4-62
DSP								0x2C	4-63
DSPS								0x30	4-63
SCRATCH A								0x34	4-64
DCNTL		SBR		DIEN		DMODE		0x38	4-64
ADDER								0x3C	4-71
SIST1		SIST0		SIEN1		SIEN0		0x40	4-71
GPCNTL		Reserved		SWIDE		Reserved		0x44	4-79
RESPID1		RESPID0		STIME1		STIME0		0x48	4-81
STEST3		STEST2		STEST1		STEST0		0x4C	4-85
CSO		STEST4		SIDL				0x50	4-90
CCNTL1		CCNTL0		SODL				0x54	4-92
CCNTL3		Reserved		SBDL				0x58	4-96
SCRATCH B								0x5C	4-98
SCRATCH C–SCRATCH R								0x60–0x9F	4-99
MMRS								0xA0	4-99
MMWS								0xA4	4-100
SFS								0xA8	4-100
DRS								0xAC	4-101
SBMS								0xB0	4-101
DBMS								0xB4	4-102
DNAD64								0xB8	4-102
AIPCNTL1		AIPCNTL0		Reserved		SCNTL4		0xBC	4-102
PMJAD1								0xC0	4-112
PMJAD2								0xC4	4-113
RBC								0xC8	4-113
UA								0xCC	4-114
ESA								0xD0	4-115
IA								0xD4	4-115
Reserved		SBC						0xD8	4-116
CSBC								0xDC	4-117
CRCNTL1		CRCNTL0		CRCPBV				0xE0	4-117
CRCD								0xE4	4-120
Reserved								0xE8–0xEF	4-121
Reserved				DFBC				0xF0	4-122
Reserved								0xF4–0xFF	4-122

Register: 0x00
SCSI Control Zero (SCNTL0)
 Read/Write

7	6	5	4	3	2	1	0
ARB[1:0]		START	WATN	EPC	CRCRP	AAP	TRG
1	1	0	0	0	x	0	0

ARB[1:0] Arbitration Mode Bits 1 and 0 [7:6]
 A combination of the ARB bits selects either Simple or Full arbitration.

ARB1	ARB0	Arbitration Mode
0	0	Simple arbitration
0	1	Reserved
1	0	Reserved
1	1	Full arbitration, selection/reselection

Simple Arbitration

1. The SYM53C1010 SCSI function waits for a bus free condition to occur.
2. It asserts SBSY/ and its SCSI ID, contained in the [SCSI Chip ID \(SCID\)](#) register, onto the SCSI bus. If the SSEL/ signal is asserted by another SCSI device, the SYM53C1010 SCSI function deasserts SBSY/, deasserts its ID, and sets the Lost Arbitration bit (bit 3) in the [SCSI Status Zero \(SSTAT0\)](#) register.
3. After an arbitration delay, the CPU should read the [SCSI Bus Data Lines \(SBDL\)](#) register to check if a higher priority SCSI ID is present. If no higher priority ID bit is set, and the Lost Arbitration bit is not set, the SYM53C1010 SCSI function wins arbitration.
4. Once the SYM53C1010 SCSI function wins arbitration, SSEL/ must be asserted using the [SCSI Output Control Latch \(SOCL\)](#) for a bus clear and a bus settle delay (1.2 μs). Then, a low level selection is performed.

Full Arbitration, Selection/Reselection

1. The SYM53C1010 SCSI function waits for a bus free condition.
2. It asserts SBSY/ and its SCSI ID onto the SCSI bus. The SCSI ID asserted is the highest priority ID stored in the [SCSI Chip ID \(SCID\)](#) register.
3. If the SSEL/ signal is asserted by another SCSI device or if the SYM53C1010 SCSI function detects a higher priority ID, the SYM53C1010 SCSI function deasserts SBSY/, deasserts its ID, sets the Lost Arbitration bit, bit 3 in the [SCSI Status Zero \(SSTAT0\)](#) register, and waits until the next bus free state to try arbitration again.
4. The SYM53C1010 SCSI function repeats arbitration until it wins control of the SCSI bus. When it wins, the Won Arbitration bit is set in the [SCSI Status Zero \(SSTAT0\)](#) register, bit 2.
5. The SYM53C1010 SCSI function performs selection by asserting SSEL/, the target's ID (stored in the [SCSI Destination ID \(SDID\)](#) register), and the SYM53C1010's ID (stored in the [SCSI Chip ID \(SCID\)](#) register) onto the SCSI bus.
6. After a selection is complete, the Function Complete bit is set in the [SCSI Interrupt Status Zero \(SIST0\)](#) register, bit 6.
7. If a selection time-out occurs, the Selection Time-Out bit is set in the [SCSI Interrupt Status One \(SIST1\)](#) register, bit 2.

START

Start Sequence

5

When this bit is set, the SYM53C1010 starts the arbitration sequence indicated by the Arbitration Mode bits. The Start Sequence bit is accessed directly in low level mode; during SCSI SCRIPTS operations, this bit is controlled by the SCRIPTS processor. Do not start an arbitration sequence if the connected (CON) bit in the [SCSI Control One \(SCNTL1\)](#) register, bit 4, is set. This bit indicates that the SYM53C1010 is already connected to the SCSI bus. This bit is automatically cleared when

the arbitration sequence is complete. If a sequence is aborted, check bit 4 in the [SCSI Control One \(SCNTL1\)](#) register to verify that the SYM53C1010 is not connected to the SCSI bus.

WATN	Select with SATN/ on a Start Sequence	4
	<p>When this bit is set and the SCSI function is in the initiator mode, the SATN/ signal is asserted during selection of a SCSI target device. This is to inform the target that the SYM53C1010 SCSI function has a message to send. If a selection time-out occurs while attempting to select a target device, SATN/ is deasserted at the same time SSEL/ is deasserted. When this bit is cleared, the SATN/ signal is not asserted during selection. When executing SCSI SCRIPTS, this bit is controlled by the SCRIPTS processor, but manual setting is possible in the low level mode.</p>	
EPC	Enable Parity/CRC/AIP Checking	3
	<p>When this bit is set and the SCSI transfers are asynchronous or ST synchronous, the SCSI data bus is checked for odd parity when data is received from the SCSI bus in either the initiator or the target mode. If a parity error is detected, bit 0 of the SCSI Interrupt Status Zero (SIST0) register is set and an interrupt may be generated.</p> <p>When this bit is set SCSI transfers are DT synchronous, the CRC is checked when the target requests a CRC transfer using the DP0 signal on the SCSI bus. If a CRC error is detected, bit 0 of the SCSI Interrupt Status Zero (SIST0) register is set and an interrupt may be generated.</p> <p>If the SYM53C1010 SCSI function is operating in the initiator mode and a parity error or CRC error is detected, SATN/ can optionally be asserted, but the transfer continues until the target changes phase or the block move in which the parity error was detected completes. When this bit is clear, parity and CRC errors are not reported.</p>	
CRCRP	CRC Request Pending	2
	<p>When this bit is set, the SYM53C1010 SCSI function has an outstanding CRC request pending. When this bit is set and the SYM53C1010 is in target mode, a Block Move of</p>	

zero should not be issued. If a Block Move of zero is issued, back-to-back CRC requests are issued. Back-to-back CRC requests are illegal.

AAP Assert SATN/ on Parity/CRC/AIP Error 1

When this bit is set, the SYM53C1010 SCSI function automatically asserts the SATN/ signal upon detection of a parity error or CRC error. SATN/ is only asserted in the initiator mode. The SATN/ signal is asserted before deasserting SACK/ during the byte transfer with the parity error. Also set the Enable Parity/CRC/AIP Checking bit for the SYM53C1010 SCSI function to assert SATN/ in this manner. A parity error or CRC error is detected on data received from the SCSI bus.

If the Assert SATN/ on Parity/CRC/AIP Error bit is cleared or the Enable Parity/CRC/AIP Checking bit is cleared, SATN/ is not automatically asserted on the SCSI bus when a Parity/CRC/AIP error is received.

TRG Target Mode 0

This bit determines the default operating mode of the SYM53C1010 SCSI function. The user must manually set the target or initiator mode. This is done using the SCRIPTS language (`SET TARGET` or `CLEAR TARGET`). When this bit is set, the chip is a target device. When this bit is cleared, the SYM53C1010 SCSI function is an initiator device.

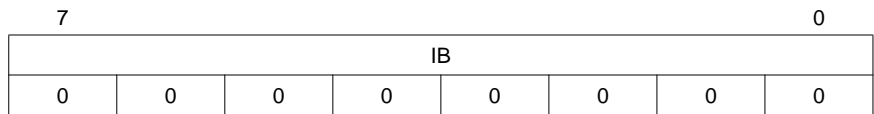
Caution: Writing this bit while not connected may cause the loss of a selection or reselection due to the changing of target or initiator modes.

CON	Connected	4
	<p>This bit is automatically set any time the SYM53C1010 SCSI function is connected to the SCSI bus as an initiator or as a target. It is set after the SYM53C1010 SCSI function successfully completes arbitration or when it has responded to a bus-initiated selection or reselection. This bit is also set after the chip wins simple arbitration when operating in low level mode. When this bit is cleared, the SYM53C1010 SCSI function is not connected to the SCSI bus.</p> <p>The CPU can force a connected or disconnected condition by setting or clearing this bit.</p>	
RST	Assert SCSI RST/ Signal	3
	<p>Setting this bit asserts the SRST/ signal. The SRST/ output remains asserted until this bit is cleared. The 25 μs minimum assertion time defined in the SCSI specification must be timed out by the controlling microprocessor or a SCRIPTS loop.</p>	
AESP	Assert Even SCSI Parity (force bad parity)	2
	<p>When this bit is set, the SYM53C1010 SCSI function asserts even parity. It forces a SCSI parity error on each byte sent to the SCSI bus from the chip. If parity checking is enabled, then the SYM53C1010 SCSI function checks data received for odd parity. This bit is used for diagnostics testing and is cleared for normal operation.</p>	
IARB	Immediate Arbitration	1
	<p>Setting this bit causes the SCSI core to immediately begin arbitration once a Bus Free phase is detected following an expected SCSI disconnect. This bit is useful for multithreaded applications. The ARB[1:0] bits in SCSI Control Zero (SCNTL0) are set for full arbitration and selection before setting this bit.</p> <p>Arbitration is retried until won. At that point, the SYM53C1010 SCSI function holds SBSY and SSEL asserted, and waits for a select or reselect sequence. The Immediate Arbitration bit is cleared automatically when the selection or reselection sequence is completed or times out.</p> <p>An unexpected disconnect condition clears IARB with it attempting arbitration. See the SCSI Disconnect</p>	

expects a disconnect to occur, normally prior to sending an Abort, Abort Tag, Bus Device Reset, Clear Queue or Release Recovery message, or before deasserting SACK/ after receiving a Disconnect command or Command Complete message.

CHM	Chained Mode	6
	This bit determines whether or not the SCSI core is programmed for chained SCSI mode. This bit is automatically set by the Chained Block Move (CHMOV) SCRIPTS instruction and is automatically cleared by the Block Move SCRIPTS instruction (MOVE). For more information, refer to Section 2.2.18, “Chained Block Moves.”	
R	Reserved	[5:4]
WSS	Wide SCSI Send	3
	When read, this bit returns the value of the Wide SCSI Send (WSS) flag. Asserting this bit clears the WSS flag. This clearing function is self-clearing. For more information refer to Section 2.2.18, “Chained Block Moves.”	
VUE0	Vendor Unique Enhancements, Bit 0	2
	This bit is a read only value indicating whether the group code field in the SCSI instruction is standard or vendor unique. If cleared, the bit indicates standard group codes; if set, the bit indicates vendor unique group codes. The value in this bit is reloaded at the beginning of all asynchronous target receives.	
VUE1	Vendor Unique Enhancement, Bit 1	1
	This bit is used to disable the automatic byte count reload during Block Move instructions in the Command phase. If this bit is cleared, the device reloads the Block Move byte count if the first byte received is one of the standard group codes. If this bit is set, the device does not reload the Block Move byte count, regardless of the group code.	
WSR	Wide SCSI Receive	0
	When read, this bit returns the value of the Wide SCSI Receive (WSR) flag. Setting this bit clears the WSR flag. This bit is self-clearing.	

Register: 0x08
SCSI First Byte Received (SFBR)
 Read/Write



SFBR **SCSI First Byte Received** **[7:0]**

This register contains the first byte received in any asynchronous information transfer phase. For example, when a SYM53C1010 SCSI function is operating in the initiator mode, this register contains the first byte received in the Message-In, Status, and Data-In phases.

When a Block Move instruction is executed for a particular phase, the first byte received is stored in this register – even if the present phase is the same as the last phase. The first byte received value for a particular input phase is not valid until after a MOVE instruction is executed.

This register is also the accumulator for register read-modify-writes with the [SCSI First Byte Received \(SFBR\)](#) as the destination. This allows bit testing after an operation.

The [SCSI First Byte Received \(SFBR\)](#) is not writable using the CPU, and therefore not by a Memory Move. However, it can be loaded using SCRIPTS Read/Write operations. To load the SFBR with a byte stored in system memory, the byte must first be moved to an intermediate SYM53C1010 SCSI function register (such as the SCRATCH register), and then to the SFBR.

This register also contains the state of the lower eight bits of the SCSI data bus during the Selection phase if the COM bit in the [DMA Control \(DCNTL\)](#) register is clear.

If the COM bit is cleared, do not access this register using SCRIPTS operations, as indeterminate operations may occur. (This includes SCRIPTS Read/Write operations and conditional transfer control instructions that initialize the [SCSI First Byte Received \(SFBR\)](#) register.)

Register: 0x09
SCSI Output Control Latch (SOCL)
Read/Write

7	6	5	4	3	2	1	0
REQ	ACK	BSY	SEL	ATN	MSG	C_D	I_O
0	0	0	0	0	0	0	0

This register is used primarily for diagnostics testing or programmed I/O operation. It is controlled by the SCRIPTS processor when executing SCSI SCRIPTS. [SCSI Output Control Latch \(SOCL\)](#) is used only when transferring data using programmed I/O. Some bits are set or cleared when executing SCSI SCRIPTS. Do not write to the register once the SYM53C1010 SCSI function starts executing normal SCSI SCRIPTS.

REQ	Assert SCSI REQ/ Signal	7
ACK	Assert SCSI ACK/ Signal	6
BSY	Assert SCSI BSY/ Signal	5
SEL	Assert SCSI SEL/ Signal	4
ATN	Assert SCSI ATN/ Signal	3
MSG	Assert SCSI MSG/ Signal	2
C_D	Assert SCSI C_D/ Signal	1
I_O	Assert SCSI I_O/ Signal	0

Register: 0x0B
SCSI Bus Control Lines (SBCL)
Read Only

7	6	5	4	3	2	1	0
REQ	ACK	BSY	SEL	ATN	MSG	C_D	I_O
x	x	x	x	x	x	x	x

This register returns the SCSI control line status. A bit is set when the corresponding SCSI control line is asserted. These bits are not latched; they are a true representation of what is on the SCSI bus at the time the register is read. The resulting read data is synchronized before being presented to the PCI bus to prevent parity errors from being passed to the system. This register is used for diagnostics testing or operation in the low level mode.

REQ	Assert SCSI REQ/ Signal	7
ACK	Assert SCSI ACK/ Signal	6
BSY	Assert SCSI BSY/ Signal	5
SEL	Assert SCSI SEL/ Signal	4
ATN	Assert SCSI ATN/ Signal	3
MSG	Assert SCSI MSG/ Signal	2
C_D	Assert SCSI C_D/ Signal	1
I_O	Assert SCSI I_O/ Signal	0

Register: 0x0C
DMA Status (DSTAT)
Read Only

7	6	5	4	3	2	1	0
DFE	MDPE	BF	ABRT	SSI	SIR	R	IID
1	0	0	0	0	0	x	0

Reading this register clears any bits that are set at the time the register is read, but does not necessarily clear the register in case additional interrupts are pending (the SYM53C1010 SCSI functions stack

interrupts). The DIP bit in the [Interrupt Status Zero \(ISTAT0\)](#) register is also cleared. It is possible to mask DMA interrupt conditions individually through the [DMA Interrupt Enable \(DIEN\)](#) register.

When performing consecutive 8-bit reads of the [DMA Status \(DSTAT\)](#), [SCSI Interrupt Status Zero \(SIST0\)](#) and [SCSI Interrupt Status One \(SIST1\)](#) registers (in any order), insert a delay equivalent to 12 CLK periods between the reads to ensure that the interrupts clear properly. See [Chapter 2, “Functional Description”](#) for more information on interrupts.

DFE	DMA FIFO Empty	7
	This status bit is set when the DMA FIFO is empty. It is possible to use it to determine if any data resides in the FIFO when an error occurs and an interrupt is generated. This bit is a pure status bit and does not cause an interrupt.	
MDPE	Master Data Parity Error	6
	This bit is set when the SYM53C1010 SCSI function, acting as a PCI master, detects a data parity error, or, acting as a target device, signals a parity error during a data phase. This bit is completely disabled by the Master Parity Error Enable bit (bit 3 of Chip Test Four (CTEST4)).	
BF	Bus Fault	5
	This bit is set when a PCI bus fault condition is detected. A PCI bus fault can only occur when the SYM53C1010 SCSI function is bus master, and is defined as a cycle that ends with a Bad Address or Target Abort Condition.	
ABRT	Aborted	4
	This bit is set when an abort condition occurs. An abort condition occurs when a software abort command is issued by setting bit 7 of the Interrupt Status Zero (ISTAT0) register.	
SSI	Single Step Interrupt	3
	If the Single-Step Mode bit in the DMA Control (DCNTL) register is set, this bit is set and an interrupt generated after successful execution of each SCRIPTS instruction.	
SIR	SCRIPTS Interrupt Instruction Received	2
	This status bit is set whenever an interrupt instruction is evaluated as true.	

R	Reserved	1
IID	Illegal Instruction Detected	0

This status bit is set any time an illegal or reserved instruction opcode is detected, whether the SYM53C1010 SCSI function is operating in single-step mode or automatically executing SCSI SCRIPTS.

Any of the following conditions during instruction execution also sets this bit:

- The SYM53C1010 SCSI function is executing a Wait Disconnect instruction and the SCSI REQ line is asserted without a disconnect occurring.
- A Block Move instruction is executed as an initiator with 0x000000 loaded into the [DMA Byte Counter \(DBC\)](#) register, indicating there are zero bytes to move.
- During a Transfer Control instruction, the Compare Data (bit 18) and Compare Phase (bit 17) bits are set in the [DMA Byte Counter \(DBC\)](#) register while the SYM53C1010 SCSI function is in target mode.
- During a Transfer Control instruction, the Carry Test bit (bit 21) is set and either the Compare Data (bit 18) or Compare Phase (bit 17) bit is set.
- A Transfer Control instruction is executed with the reserved bit 22 set.
- A Transfer Control instruction is executed with the Wait for Valid phase bit (bit 16) set while the chip is in the target mode.
- A Load and Store instruction is issued with the memory address mapped to the operating registers of the chip, not including ROM or RAM.
- A Load and Store instruction is issued when the register address is not aligned with the memory address.
- A Load and Store instruction is issued with bit 5 in the [DMA Command \(DCMD\)](#) register cleared or bits 3 or 2 set.
- A Load and Store instruction when the count value in the [DMA Byte Counter \(DBC\)](#) register is not set at 1 to 4.

- A Load and Store instruction attempts to cross a Dword boundary.
- A Memory Move instruction is executed with one of the reserved bits in the [DMA Command \(DCMD\)](#) register set.
- A Memory Move instruction is executed with the source and destination addresses not aligned.
- A 64-bit Table Indirect Block Move instruction is executed with a selector index value greater than 0x16.
- If the Select with ATN/ bit is set for any I/O instruction other than a select instruction.

Register: 0x0D
SCSI Status Zero (SSTAT0)
Read Only

7	6	5	4	3	2	1	0
ILF	R	OLF	ARBIP	LOA	WOA	RST	SDP0
0	0	0	0	0	0	0	0

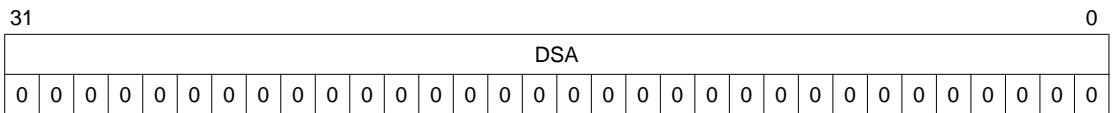
- ILF** **SIDL Least Significant Byte Full** **7**
This bit is set when the least significant byte in the [SCSI Input Data Latch \(SIDL\)](#) contains data. Data is transferred from the SCSI bus to the SCSI Input Data Latch register before being sent to the DMA FIFO and then to the host bus. The [SCSI Input Data Latch \(SIDL\)](#) register contains SCSI data received asynchronously. Synchronous data received does not flow through this register.
- R** **Reserved** **6**
- OLF** **SODL Least Significant Byte Full** **5**
This bit is set when the least significant byte in the [SCSI Output Data Latch \(SODL\)](#) contains data. The SODL register is the interface between the DMA logic and the SCSI bus for asynchronous send operations. In the asynchronous mode, data is transferred from the host bus to the SODL register, and then to the SCSI bus. It is possible to use this bit to determine how many bytes reside in the device when an error occurs.

ARBIP	Arbitration in Progress Arbitration in Progress (ARBIP = 1) indicates that the SYM53C1010 SCSI function has detected a Bus Free condition, asserted SBSY, and asserted its SCSI ID onto the SCSI bus.	4
LOA	Lost Arbitration When set, LOA indicates that the SYM53C1010 SCSI function has detected a bus free condition, arbitrated for the SCSI bus, and lost arbitration due to another SCSI device asserting the SSEL/ signal.	3
WOA	Won Arbitration When set, WOA indicates that the SYM53C1010 SCSI function has detected a Bus Free condition, arbitrated for the SCSI bus and won arbitration. The arbitration mode selected in the SCSI Control Zero (SCNTL0) register must be full arbitration and selection to set this bit.	2
RST	SCSI RST/ Signal This bit reports the current status of the SCSI RST/ signal, and the RST signal (bit 3) in the SCSI Control One (SCNTL1) register. This bit is not latched and may change as it is read.	1
SDP0	SCSI SDP0 Parity Signal This bit represents the present state of the SCSI SDP0/ parity signal. This signal is not latched and may change as it is read.	0

SYM53C1010 SCSI function. If the Connected bit and the LDSC bit are asserted, a disconnect is indicated. This bit is set when the Connected bit in SCNTL1 is off. This bit is cleared when a Block Move instruction is executed while the Connected bit in SCNTL1 is set.

SDP1 **SCSI SDP1 Parity Signal** **0**
 This bit represents the present state of the SCSI SDP1/parity signal. It is not latched and may change as it is read.

Registers: 0x10–0x13
Data Structure Address (DSA)
 Read/Write



DSA **Data Structure Address** **[31:0]**
 This 32-bit register contains the base address used for all Table Indirect calculations. The DSA register is usually loaded prior to starting an I/O, but it is possible for a SCRIPTS Memory Move to load the DSA during the I/O. During any Memory-to-Memory Move operation, the contents of this register are preserved. The power-up value of this register is indeterminate.

Register: 0x14
Interrupt Status Zero (ISTAT0)
 Read/Write

7	6	5	4	3	2	1	0
ABRT	SRST	SIGP	SEM	CON	INTF	SIP	DIP
0	0	0	0	0	0	0	0

This is the only register that is accessible by the host CPU while a SYM53C1010 SCSI function is executing SCRIPTS (without interfering in the operation of the function). It is used to poll for interrupts if hardware interrupts are disabled. Read this register after servicing an interrupt to check for stacked interrupts.

ABRT**Abort Operation****7**

Setting this bit aborts the current operation under execution by the SYM53C1010 SCSI function. If this bit is set and an interrupt is received, clear this bit before reading the [DMA Status \(DSTAT\)](#) register to prevent further aborted interrupts from being generated. The sequence to abort any operation is:

1. Set this bit.
2. Wait for an interrupt.
3. Read the [Interrupt Status Zero \(ISTAT0\)](#) register.
4. If the SCSI Interrupt Pending bit is set, read the [SCSI Interrupt Status Zero \(SIST0\)](#) or [SCSI Interrupt Status One \(SIST1\)](#) register to determine the cause of the SCSI Interrupt and return to Step 2.
5. If the SCSI Interrupt Pending bit is cleared and the DMA Interrupt Pending bit is set, write 0x00 to this register.
6. Read the [DMA Status \(DSTAT\)](#) register to verify the aborted interrupt and to determine if any other interrupting conditions have occurred.

SRST**Software Reset****6**

Setting this bit resets the SYM53C1010 SCSI function. All operating registers are cleared to their respective default values and all SCSI signals are deasserted. Setting this bit does not assert the SCSI RST/ signal. This reset does not clear the ID Mode bit or any of the PCI configuration registers. This bit is not self-clearing; it must be cleared to clear the reset condition. A hardware reset also clears this bit.

Note: If SCRIPTS are running, then the ABRT bit (bit 7) must be set prior to setting the SRST bit.

SIGP**Signal Process****5**

SIGP is a R/W bit that is writable at any time. It is polled and reset using [Chip Test Two \(CTEST2\)](#). The SIGP bit is used in various ways to pass a flag to or from a running SCRIPTS instruction.

The only SCRIPTS instruction directly affected by the SIGP bit is Wait for Selection/Reselection. Setting the

SIGP bit causes this instruction to jump to the alternate address immediately. The instructions at the alternate jump address should check the status of SIGP to determine the cause of the jump. The SIGP bit is usable at any time and is not restricted to the wait for selection/reselection condition.

SEM	Semaphore	4
	The SCRIPTS processor may set this bit using a SCRIPTS register write instruction. An external processor may also set it while the SYM53C1010 SCSI function is executing a SCRIPTS operation. This bit enables the SCSI function to notify an external processor of a predefined condition while SCRIPTS are running. The external processor may also notify the SYM53C1010 SCSI function of a predefined condition and the SCRIPTS processor may take action while SCRIPTS are executing.	
CON	Connected	3
	This bit is automatically set any time the SYM53C1010 SCSI function is connected to the SCSI bus as an initiator or as a target. It is set after successfully completing selection or when the SYM53C1010 SCSI function responds to a bus-initiated selection or reselection. It is also set after the SCSI function wins arbitration when operating in the low level mode. When this bit is cleared, the SYM53C1010 SCSI function is not connected to the SCSI bus.	
INTF	Interrupt-on-the-Fly	2
	This bit is asserted by an INTFLY instruction during SCRIPTS execution. SCRIPTS programs do not halt when the interrupt occurs. This bit can be used to notify a service routine, running on the main processor while the SCRIPTS processor is still executing a SCRIPTS program. If this bit is set, when the Interrupt Status Zero (ISTAT0) register is read it is not automatically cleared. To clear this bit, write a one to it. The reset operation is self-clearing.	

Note: If the INTF bit is set but SIP or DIP is not set, do not attempt to read the other chip status registers. An interrupt-

on-the-fly must be cleared before servicing any other interrupts indicated by SIP or DIP.

After it has been set, this bit must be written to one to clear it.

SIP **SCSI Interrupt Pending** **1**

This status bit is set when an interrupt condition is detected in the SCSI portion of the SYM53C1010 SCSI function. The following conditions cause a SCSI interrupt to occur:

- A phase mismatch (initiator mode) or SATN/ becomes active (target mode)
- An arbitration sequence completes
- A selection or reselection time-out occurs
- The SYM53C1010 SCSI function is selected
- The SYM53C1010 SCSI function is reselected
- A SCSI gross error occurs
- An unexpected disconnect occurs
- A SCSI reset occurs
- A parity error is detected
- The handshake-to-handshake timer expires
- The general purpose timer expires

To determine which condition(s) caused the interrupt, read the [SCSI Interrupt Status Zero \(SIST0\)](#) and [SCSI Interrupt Status One \(SIST1\)](#) registers.

DIP **DMA Interrupt Pending** **0**

This status bit is set when an interrupt condition is detected in the DMA portion of the SYM53C1010 SCSI function. The following conditions cause a DMA interrupt to occur:

- A PCI parity error is detected
- A bus fault is detected
- An abort condition is detected
- A SCRIPTS instruction is executed in the single-step mode
- A SCRIPTS interrupt instruction is executed

Register: 0x16
Mailbox Zero (MBOX0)
Read/Write

7								0
MBOX0								
0	0	0	0	0	0	0	0	

MBOX0 Mailbox Zero [7:0]

These are general purpose bits that may be read or written while SCRIPTS are running. They also may be read or written by the SCRIPTS processor.

Note: The host and the SCRIPTS processor code could access the same mailbox byte at the same time. Using one mailbox register as read only and the other as write only prevents this conflict.

Register: 0x17
Mailbox One (MBOX1)
Read/Write

7								0
MBOX1								
0	0	0	0	0	0	0	0	

MBOX1 Mailbox One [7:0]

These are general purpose bits that may be read or written while SCRIPTS are running. They also may be read or written by the SCRIPTS processor.

Note: The host and the SCRIPTS processor code could access the same mailbox byte at the same time. Using one mailbox register as read only and the other as write only prevents this conflict.

Register: 0x18
Chip Test Zero (CTEST0)
Read/Write

7								0
FMT								
1	1	1	1	1	1	1	1	

FMT **Byte Empty in DMA FIFO** **[7:0]**

These bits identify the lower bytes in the DMA FIFO that are empty. Each bit corresponds to a byte lane in the DMA FIFO. For example, if byte lane three is empty, then FMT bit 3 is set. The FMT flags indicate the status of bytes at the bottom of the FIFO. Therefore, if all FMT bits are set, the DMA FIFO is empty.

Register: 0x19
Chip Test One (CTEST1)
Read Only

7								0
FFL								
0	0	0	0	0	0	0	0	

FFL **Byte Full in DMA FIFO** **[7:0]**

These status bits identify the upper bytes in the DMA FIFO that are full. Each bit corresponds to a byte lane in the DMA FIFO. For example, if byte lane three is full then FFL bit 3 is set. The FFL flags indicate the status of bytes at the top of the FIFO. Therefore, if all FFL bits are set, the DMA FIFO is full.

Register: 0x1A
Chip Test Two (CTEST2)
Read Only (bit 3 write)

7	6	5	4	3	2	0	
R	SIGP	CIO	CM	PCICIE	R		
x	0	x	x	0	x	x	x

R **Reserved** **7**

SIGP **Signal Process** **6**
 This bit is a copy of the SIGP bit in the [Interrupt Status Zero \(ISTAT0\)](#) register (bit 5). The SIGP bit is used to signal a running SCRIPTS instruction. When this register is read, the SIGP bit in the [Interrupt Status Zero \(ISTAT0\)](#) register is cleared.

CIO **Configured as I/O** **5**
 This bit is defined as the Configuration I/O Enable Status bit. This read only bit indicates if the chip is currently enabled as I/O space.

CM **Configured as Memory** **4**
 This bit is defined as the configuration memory enable status bit. This read only bit indicates if the chip is currently enabled as memory space.

Note: Bits 4 and 5 may be set if the chip is mapped in both I/O and memory space. Also, bits 4 and 5 may be set if the chip is dual-mapped.

PCICIE **PCI Configuration Info Enable** **3**
 This bit controls the shadowing of the [PCI Base Address Register One \(BAR1\) \(MEMORY\)](#), [PCI Base Address Register Two \(BAR2\) \(MEMORY\)](#), [PCI Base Address Register Three \(BAR3\) \(SCRIPTS RAM\)](#), [PCI Base Address Register Four \(BAR4\) \(SCRIPTS RAM\)](#), [PCI Device ID](#), and [PCI Revision ID \(RID\)](#) into the [Scratch Register A \(SCRATCHA\)](#), [Memory Move Read Selector \(MMRS\)](#), [Scratch Register B \(SCRATCHB\)](#), [Memory Move Write Selector \(MMWS\)](#), and [SCRIPT Fetch Selector \(SFS\)](#) registers.

When it is set, MMWS contains bits [63:32] and SCRATCH B contains bits [31:0] of the RAM Base

Address value from the PCI Configuration [Base Address Register Three \(BAR3\) \(SCRIPTS RAM\)](#) and [Base Address Register Four \(BAR4\) \(SCRIPTS RAM\)](#). This is the base address for the 8 Kbytes of internal RAM.

[Memory Move Read Selector \(MMRS\)](#) contains bits [63:32] and [Scratch Register A \(SCRATCHA\)](#) contains bits [31:0] of the memory mapped operating register base address. Bits [23:16] of [SCRIPT Fetch Selector \(SFS\)](#) contain the PCI [Revision ID \(RID\)](#) register value and bits [15:0] contain the PCI [Device ID](#) register value. When this bit is set, only reads to the registers are affected, writes occur normally.

When this bit is cleared, the SCRATCH A, MMRS, SCRATCH B, MMWS, and SFS registers return to normal operation.

Note: Bit 3 is the only writable bit in this register. All other bits are read only. When modifying this register, all other bits must be written to zero. Do not execute a Read-Modify-Write to this register.

R **Reserved** **[2:0]**

Register: 0x1B
Chip Test Three (CTEST3)
Read/Write

7	4	3	2	1	0		
R				FLF	CLF	R	WRIE
0	0	0	0	0	0	0	0

R **Reserved** **[7:4]**

FLF **Flush DMA FIFO** **3**

When this bit is set, data residing in the DMA FIFO is transferred to memory, starting at the address in the [DMA Next Address \(DNAD\)](#) register. The internal DMAWR signal, controlled by the [Chip Test Five \(CTEST5\)](#) register, determines the direction of the transfer. This bit is not self-clearing; clear it once the data is successfully transferred by the SYM53C1010 SCSI function.

Note: Polling of FIFO flags is allowed during flush operations.

detected by the SYM53C1010 SCSI function. A parity error during a bus master write is detected by the target, and the SYM53C1010 SCSI function is informed of the error by the PERR/ pin being asserted by the target. When this bit is cleared, the SYM53C1010 SCSI function does not interrupt if a master parity error occurs. This bit is cleared at power-up.

FBL[2:0]

FIFO Byte Control

[2:0]

FBL3	FBL2	FBL1	FBL0	DMA FIFO Byte Lane	Pins
0	x	x	x	Disabled	N/A
1	0	0	0	0	D[7:0]
1	0	0	1	1	D[15:8]
1	0	1	0	2	D[23:16]
1	0	1	1	3	D[31:24]
1	1	0	0	4	D[39:32]
1	1	0	1	5	D[47:40]
1	1	1	0	6	D[53:48]
1	1	1	1	7	D[63:54]

These bits steer the contents of the [Chip Test Six \(CTEST6\)](#) register to the appropriate byte lane of the 64-bit DMA FIFO. If the FBL3 bit is set, then FBL2 through FBL0 determine which of eight byte lanes can be read or written. When cleared, the byte lane read or written is determined by the current contents of the [DMA Next Address \(DNAD\)](#) and [DMA Byte Counter \(DBC\)](#) registers. Each of the eight bytes that make up the 64-bit DMA FIFO is accessed by writing these bits to the proper value. For normal operation, FBL3 must equal zero.

Register: 0x23
Chip Test Six (CTEST6)
Read/Write

7								0
DF								
0	0	0	0	0	0	0	0	

DF **DMA FIFO** **[7:0]**

Writing to this register writes data to the appropriate byte lane of the DMA FIFO, as determined by the FBL bits in the [Chip Test Four \(CTEST4\)](#) register. Reading this register unloads data from the appropriate byte lane of the DMA FIFO, as determined by the FBL bits in the CTEST4 register. Data written to the FIFO is loaded into the top of the FIFO. Data read out of the FIFO is taken from the bottom. To prevent DMA data from being corrupted, this register should not be accessed before starting or restarting SCRIPTS operations. This register should be the last register read when performing register dumps because of its effects on other registers. Write to this register only when testing the DMA FIFO using the CTEST4 register. Writing to this register while the test mode is not enabled produces unexpected results.

data. Bus Request (PCIREQ/) is also asserted during start-of-transfer and end-of-transfer cleanup and alignment, even if less than a full burst of transfers is performed. The SYM53C1010 SCSI function inserts a “fairness delay” of four CLKs between burst transfers (set in BL[2:0]) during normal operation. The fairness delay is not inserted during PCI retry cycles. This gives the CPU and other bus master devices the opportunity to access the PCI bus between bursts.

BL2 (CTEST5 bit 2)	BL1	BL0	Number of 64-bit Transfers	Number of 32-bit Transfers
0	0	0	2	4
0	0	1	4	8
0	1	0	8	16
0	1	1	16	32
1	0	0	32	64
1	0	1	64	128
1	1	0	64	128
1	1	1	Reserved	Reserved

SIOM **Source I/O-Memory Enable** **5**

This bit is defined as an I/O Memory Enable bit for the source address of a Memory Move or Block Move Command. If this bit is set, then the source address is in I/O space; if cleared, the source address is in memory space.

This function is useful for register-to-memory operations using the Memory Move instruction when a SYM53C1010 SCSI function is I/O mapped. Bits 4 and 5 of the [Chip Test Two \(CTEST2\)](#) register are used to determine the configuration status of the SYM53C1010 SCSI function.

DIOM **Destination I/O-Memory Enable** **4**

This bit is defined as an I/O Memory Enable bit for the destination address of a Memory Move or Block Move Command. If this bit is set, then the destination address is in I/O space; if cleared, the destination address is in memory space.

This function is useful for memory-to-register operations using the Memory Move instruction when a SYM53C1010 SCSI function is I/O mapped. Bits 4 and 5

of the [Chip Test Two \(CTEST2\)](#) register are used to determine the configuration status of the SYM53C1010 SCSI function.

ERL	Enable Read Line	3
	This bit enables a PCI Read Line command. If this bit is set and the chip is about to execute a read cycle (other than an opcode fetch), the command is 0b1110.	
ERMP	Enable Read Multiple	2
	If this bit is set and cache mode is enabled, a Read Multiple command is used on all read cycles when it is legal.	
BOF	Burst Opcode Fetch Enable	1
	Setting this bit causes the SYM53C1010 SCSI function to fetch instructions in burst mode. Specifically, the chip bursts in the first two Dwords of all instructions using a single bus ownership. If the instruction is a Memory-to-Memory Move type, the third Dword is accessed in a subsequent bus ownership. If the instruction is an Indirect type, the additional Dword is accessed in a subsequent bus ownership. If the instruction is a Table Indirect Block Move type, the chip accesses the remaining two Dwords in a subsequent bus ownership, thereby fetching the four Dwords required in two bursts of two Dwords each. If prefetch is enabled, this bit has no affect. This bit also has no affect on fetches out of SCRIPTS RAM.	
MAN	Manual Start Mode	0
	Setting this bit prevents the SYM53C1010 SCSI function from automatically fetching and executing SCSI SCRIPTS when the DMA SCRIPTS Pointer (DSP) register is written. When this bit is set, the Start DMA bit in the DMA Control (DCNTL) register must be set to begin SCRIPTS execution. Clearing this bit causes the SYM53C1010 SCSI function to automatically begin fetching and executing SCSI SCRIPTS when the DMA SCRIPTS Pointer (DSP) register is written. This bit normally is not used for SCSI SCRIPTS operations.	

Register: 0x39
DMA Interrupt Enable (DIEN)
Read/Write

7	6	5	4	3	2	1	0
R	MDPE	BF	ABRT	SSI	SIR	R	IID
x	0	0	0	0	0	x	0

This register contains the interrupt mask bits corresponding to the interrupting conditions described in the [DMA Status \(DSTAT\)](#) register. An interrupt is masked by clearing the appropriate mask bit. Masking an interrupt prevents INTA/ (for Function A) or INTB/ (for Function B) from being asserted for the corresponding interrupt, but the status bit is still set in the [DMA Status \(DSTAT\)](#) register. Masking an interrupt does not prevent setting the [Interrupt Status Zero \(ISTAT0\)](#) DIP. All DMA interrupts are considered fatal. Therefore, SCRIPTS halts when this condition occurs, whether or not the interrupt is masked. Setting a mask bit enables the assertion of INTA/, or INTB/, for the corresponding interrupt. A masked nonfatal interrupt does not prevent unmasked or fatal interrupts from getting through; interrupt stacking begins when either the [Interrupt Status Zero \(ISTAT0\)](#) SIP or DIP bit is set.

The INTA/ and INTB/ outputs are latched. Once asserted, they remain asserted until the interrupt is cleared by reading the appropriate status register. Masking an interrupt after the INTA/, or INTB/, output is asserted does not cause deassertion of INTA/ or INTB/. For more information on interrupts, see [Chapter 2, “Functional Description”](#).

R	Reserved	7
MDPE	Master Data Parity Error	6
BF	Bus Fault	5
ABRT	Aborted	4
SSI	Single Step Interrupt	3
SIR	SCRIPTS Interrupt Instruction Received	2
R	Reserved	1
IID	Illegal Instruction Detected	0

Register: 0x3A
Scratch Byte Register (SBR)
Read/Write

7	SBR						0
0	0	0	0	0	0	0	0

SBR **Scratch Byte Register** **[7:0]**

This is a general purpose register. Apart from CPU access, only register Read/Write and Memory Moves into this register alter its contents. The default value of this register is zero. This register is called the DMA Watchdog Timer on previous SYM53C8XX family products.

Register: 0x3B
DMA Control (DCNTL)
Read/Write

7	6	5	4	3	2	1	0
CLSE	PFF	PFEN	SSM	IRQM	STD	R	COM
0	0	0	0	0	0	0	0

CLSE **Cache Line Size Enable** **7**

Setting this bit enables the SYM53C1010 SCSI function to sense and react to cache line boundaries set up by the [DMA Mode \(DMODE\)](#) or [PCI Cache Line Size \(CLS\)](#) register, whichever contains the smaller value. Clearing this bit disables the cache line size logic.

PFF **Prefetch Flush** **6**

Setting this bit causes the prefetch unit to flush its contents. This bit clears after the flush is complete.

PFEN **Prefetch Enable** **5**

Setting this bit enables an 8-Dword SCRIPTS instruction prefetch unit. The prefetch unit, when enabled, fetches 8 Dwords of instructions and instruction operands in bursts of 4 or 8 Dwords. Prefetching instructions allows the SYM53C1010 SCSI function to make more efficient use of the system PCI bus, thus improving overall system performance. A flush occurs whenever the PFF bit is set, on all transfer control instructions (when the transfer

conditions are met), on writes to the [DMA SCRIPTS Pointer \(DSP\)](#), on regular MMIO instructions, and when an interrupt is generated. Based on the burst length as determined by the values in the [DMA Mode \(DMODE\)](#) register, the unit automatically determines the maximum burst size that it is capable of performing. If the burst threshold is set to 8 Dwords, the prefetch unit fetches instructions in two bursts of 4 Dwords. If the burst threshold is set to 16 Dwords or greater, the prefetch unit fetches instructions in one burst of 8 Dwords. Burst thresholds of less than 8 Dwords cause the prefetch unit to be disabled. PCI Cache commands (Read Line and Read Multiple) are issued if PCI caching is enabled. Prefetching from SCRIPTS RAM is not supported and is unnecessary due to the speed of the fetches. When fetching from SCRIPTS RAM, the setting of this bit has no effect on the fetch mechanism from SCRIPTS RAM. The prefetch unit does not support 64-bit data instruction fetches across the PCI bus. Prefetches of SCRIPTS instructions are 32-bits in width.

SSM	<p>Single-Step Mode 4</p> <p>Setting this bit causes the SYM53C1010 SCSI function to stop after executing each SCRIPTS instruction and to generate a single step interrupt. When this bit is cleared the SYM53C1010 SCSI function does not stop after each instruction. It continues fetching and executing instructions until an interrupt condition occurs. For normal SCSI SCRIPTS operation, keep this bit cleared. To restart the SYM53C1010 SCSI function after it generates a SCRIPTS Step interrupt, read the Interrupt Status Zero (ISTAT0) and DMA Status (DSTAT) registers to recognize and clear the interrupt. Then set the START DMA bit in this register.</p>
IRQM	<p>IRQ Mode 3</p> <p>When set, this bit enables a totem pole driver for the INTA/, or INTB/ pin. When cleared, this bit enables an open drain driver for the INTA/, or INTB/, pin with an internal weak pull-up. The bit should remain cleared to retain full PCI compliance.</p>
STD	<p>Start DMA Operation 2</p> <p>The SYM53C1010 SCSI function fetches a SCSI SCRIPTS instruction from the address contained in the</p>

DMA SCRIPTS Pointer (DSP) register when this bit is set. This bit is required if the SYM53C1010 SCSI function is in one of the following modes:

- Manual start mode – Bit 0 in the **DMA Mode (DMODE)** register is set
- Single-step mode – Bit 4 in the **DMA Control (DCNTL)** register is set

When the SYM53C1010 SCSI function is executing SCRIPTS in manual start mode, the Start DMA bit must be set to start instruction fetches, but need not be set again until an interrupt occurs. When the SYM53C1010 SCSI function is in the single-step mode, set the Start DMA bit to restart execution of SCRIPTS after a single-step interrupt.

R	Reserved	1
COM	SYM53C700 Compatibility	0

When the COM bit is cleared, the SYM53C1010 SCSI function behaves in a manner compatible with the SYM53C700; selection/reselection IDs are stored in both the **SCSI Selector ID (SSID)** and **SCSI First Byte Received (SFBR)** registers. This bit is not affected by a software reset.

If the COM bit is cleared, do not access this register using SCRIPTS operation as indeterminate operations may occur. This includes SCRIPTS read/write operations and conditional transfer control instructions that initialize the **SCSI First Byte Received (SFBR)** register.

When the COM bit is set, the ID is stored only in the **SCSI Selector ID (SSID)** register, protecting the **SCSI First Byte Received (SFBR)** from being overwritten if a selection/reselection occurs during a DMA register-to-register operation.

SEL	Selected	5
	When set, this bit indicates the SYM53C1010 SCSI function is selected by a SCSI initiator device. For this to occur, set the Enable Response to Selection bit in the SCSI Chip ID (SCID) register.	
RSL	Reselected	4
	When set, this bit indicates the SYM53C1010 SCSI function is reselected by a SCSI target device. For this to occur, set the Enable Response to Reselection bit in the SCSI Chip ID (SCID) register.	
SGE	SCSI Gross Error	3
	The following conditions are considered SCSI Gross Errors:	
	<ul style="list-style-type: none"> • Offset Underflow occurs in target mode when a SACK/ signal is received before the corresponding SREQ/ signal has been sent. • Offset Overflow occurs in initiator mode when an SREQ/ signal is received and causes the maximum offset, as defined by the MO[5:0] bits in the SCSI Transfer (SXFER) register, to be exceeded. • In initiator mode, a phase change occurs with an outstanding SREQ/SACK offset. • Residual Data in SCSI FIFO occurs when a transfer other than Synchronous Data Received is started with data left in the SCSI Synchronous Receive FIFO. • Multiple CRC Requests occur when, during a synchronous DT transfer, multiple CRC requests are received within the same offset. • A request for a Pad CRC word is received without the subsequent CRC word requests. • A phase change occurs without a CRC Request. 	
	<u>Note:</u> Checking for this condition can be disabled by setting the DISCRC bit in the CRC Control Zero (CRCCNTL0) register.	
	<ul style="list-style-type: none"> • An illegal Force CRC Request Block Move is executed. • A SCRIPTS RAM parity error occurs. 	

R	Reserved	[7:5]
SBMC	SCSI Bus Mode Change	4
	Setting this bit allows the SYM53C1010 to generate an interrupt when the DIFFSENS pin detects a change in voltage level that indicates the SCSI bus has changed between SE, LVD, or HVD modes. For example, when this bit is cleared and the SCSI bus changes modes, IRQ/ does not assert and the SIP bit in the Interrupt Status Zero (ISTAT0) register is not set. However, bit 4 in the SCSI Interrupt Status One (SIST1) register is set. Setting this bit allows the interrupt to occur.	
R	Reserved	3
STO	Selection or Reselection Time-out	2
	This bit is set when the SCSI device which the SYM53C1010 SCSI function is attempting to select or reselect does not respond within the programmed time-out period. See the description of the SCSI Timer Zero (STIME0) register, bits [3:0], for more information on the time-out timer.	
GEN	General Purpose Timer Expired	1
	This bit is set when the general purpose timer is expired. The time measured is the time between enabling and disabling of the timer. See the description of the SCSI Timer One (STIME1) register, bits [3:0], for more information on the general purpose timer.	
HTH	Handshake-to-Handshake Timer Expired	0
	This bit is set when the handshake-to-handshake timer is expired. The time measured is the SCSI Request-to-Request (target) or Acknowledge-to-Acknowledge (initiator) period. See the description of the SCSI Timer Zero (STIME0) register, bits [7:4], for more information on the handshake-to-handshake timer.	

Register: 0x42
SCSI Interrupt Status Zero (SIST0)
Read Only

7	6	5	4	3	2	1	0
M/A	CMP	SEL	RSL	SGE	UDC	RST	PAR
0	0	0	0	0	0	0	0

Reading the [SCSI Interrupt Status Zero \(SIST0\)](#) register returns the status of the various interrupt conditions, whether they are enabled in the [SCSI Interrupt Enable Zero \(SIEN0\)](#) register or not. Each bit set indicates occurrence of the corresponding condition. Reading the SIST0 clears the interrupt status.

Reading this register clears any bits that are set at the time the register is read, but does not necessarily clear the register because additional interrupts may be pending; the SYM53C1010 SCSI functions stack interrupts. SCSI interrupt conditions are individually masked through the [SCSI Interrupt Enable Zero \(SIEN0\)](#) register.

When performing consecutive 8-bit reads of the [DMA Status \(DSTAT\)](#), [SCSI Interrupt Status Zero \(SIST0\)](#), and [SCSI Interrupt Status One \(SIST1\)](#) registers (in any order), insert a delay equivalent to 12 clock periods between the reads to ensure the interrupts clear properly. Also, if reading the registers when both the Interrupt Status Zero (ISTAT0) SIP and DIP bits may not be set, read the SIST0 and SIST1 registers before the DSTAT register to avoid missing a SCSI interrupt. For more information on interrupts refer to [Chapter 2, "Functional Description"](#).

- M/A** **Initiator Mode: Phase Mismatch; Target Mode: SATN/ Active** **7**
 In the initiator mode, this bit is set if the SCSI phase asserted by the target does not match the instruction. The phase is sampled when SREQ/ is asserted by the target. In the target mode, this bit is set when the SATN/ signal is asserted by the initiator.
- CMP** **Function Complete** **6**
 This bit is set when an arbitration only or full arbitration sequence is completed.

SEL	Selected	5
	<p>This bit is set when the SYM53C1010 SCSI function is selected by another SCSI device. For the SYM53C1010 SCSI function to respond to selection attempts, the Enable Response to Selection bit must be set in the SCSI Chip ID (SCID) register. The Response ID Zero (RESPID0) and Response ID One (RESPID1) registers must hold the chip's ID.</p>	
RSL	Reselected	4
	<p>This bit is set when the SYM53C1010 SCSI function is reselected by another SCSI device. The Enable Response to Reselection bit must be set in the SCSI Chip ID (SCID) register (and the Response ID Zero (RESPID0) and Response ID One (RESPID1) registers must hold the chip's ID) for the SYM53C1010 SCSI function to respond to reselection attempts.</p>	
SGE	SCSI Gross Error	3
	<p>This bit is set when the SYM53C1010 SCSI function encounters a SCSI Gross Error condition. The following conditions can result in a SCSI Gross Error:</p> <ul style="list-style-type: none"> • Offset Underflow occurs in target mode when a SACK/ signal is received before the corresponding SREQ/ signal has been sent. • Offset Overflow occurs in initiator mode when an SREQ/ signal is received and causes the maximum offset, as defined by the MO[5:0] bits in the SCSI Transfer (SXFER) register, to be exceeded. • In initiator mode, a phase change occurs with an outstanding SREQ/SACK offset. • Residual Data in SCSI FIFO occurs when a transfer other than Synchronous Data Received is started with data left in the SCSI Synchronous Receive FIFO. • Multiple CRC Requests occur when, during a synchronous DT transfer, multiple CRC requests are received within the same offset. • A request for a Pad CRC word is received without the subsequent CRC word requests. • A phase change occurs without a CRC Request. 	

Note: Checking for this condition can be disabled by setting the DISCRC bit in the [CRC Control Zero \(CRCCNTLO\)](#) register.

- An illegal Force CRC Request Block Move is executed.
- A SCRIPTS RAM parity error occurs.

UDC	Unexpected Disconnect	2
	This bit is set when the SYM53C1010 SCSI function is operating in the initiator mode and the target device unexpectedly disconnects from the SCSI bus. This bit is only valid when the SYM53C1010 SCSI function operates in the initiator mode. When the SCSI function operates in the low level mode, any disconnect causes an interrupt, even a valid SCSI disconnect. This bit is also set if a selection time-out occurs. Since a selection time-out is not considered an expected disconnect, an unexpected disconnect may occur before, at the same time, or stacked after the STO interrupt.	
RST	SCSI RST/ Received	1
	This bit is set when the SYM53C1010 SCSI function detects an active SRST/ signal, whether the reset is generated external to the chip or caused by the Assert SRST/ bit in the SCSI Control One (SCNTL1) register. This SCSI reset detection logic is edge-sensitive, so that multiple interrupts are not generated for a single assertion of the SRST/ signal.	
PAR	Parity/CRC/AIP Error	0
	This bit indicates the SYM53C1010 SCSI function detected a Parity/CRC/AIP error while receiving or sending SCSI data. See the Disable Halt on Parity/CRC/AIP error or SATN/ Condition bits in the SCSI Control One (SCNTL1) register for more information about when this condition will actually be raised.	

Register: 0x43
SCSI Interrupt Status One (SIST1)
Read Only

7			5	4	3	2	1	0
R				SBMC	R	STO	GEN	HTH
0	0	0		0	0	0	0	0

Reading the SIST1 register returns the status of the various interrupt conditions, whether they are enabled in the [SCSI Interrupt Enable One \(SIEN1\)](#) register or not. Each bit set indicates an occurrence of the corresponding condition. Reading the SIST1 clears the interrupt condition.

R	Reserved	[7:5]
SBMC	SCSI Bus Mode Change This bit is set when the DIFFSENS pin detects a change in voltage level indicating the SCSI bus has switched between SE, LVD, or HVD modes.	4
R	Reserved	3
STO	Selection or Reselection Time-Out This bit is set when the SCSI device which the SYM53C1010 SCSI function is attempting to select or reselect does not respond within the programmed time-out period. See the description of the SCSI Timer Zero (STIME0) register, bits [3:0], for more information on the time-out timer.	2
GEN	General Purpose Timer Expired This bit is set when the general purpose timer expires. The time measured is the time between enabling and disabling of the timer. See the description of the SCSI Timer One (STIME1) register, bits [3:0], for more information on the general purpose timer.	1
HTH	Handshake-to-Handshake Timer Expired This bit is set when the handshake-to-handshake timer expires. The time measured is the SCSI Request-to-Request (target) or Acknowledge-to-Acknowledge (initiator) period. See the description of the SCSI Timer	0

Zero (STIME0) register, bits [7:4], for more information on the handshake-to-handshake timer.

Register: 0x44

Reserved

7								0
R								
x	x	x	x	x	x	x	x	

This register is reserved.

Register: 0x45

SCSI Wide Residue (SWIDE)

Read/Write

7								0
SWIDE								
0	0	0	0	0	0	0	0	

SWIDE

SCSI Wide Residue

[7:0]

After an asynchronous wide SCSI data receive operation, this register contains a residual data byte if the last byte received was never sent across the DMA bus. It represents either the first data byte of a subsequent data transfer, a residue byte which should be cleared when an Ignore Wide Residue message is received, or an overrun data byte. The power-up value of this register is indeterminate.

Register: 0x46

Reserved

7								0
R								
x	x	x	x	x	x	x	x	

This register is reserved.

GPIO[1:0] GPIO Enable [1:0]
 These bits are set at power-up causing the GPIO1 and GPIO0 pins to become inputs. Clearing these bits cause GPIO[1:0] to become outputs.

Register: 0x48
SCSI Timer Zero (STIME0)
 Read/Write

7				4			3			0	
HTH[3:0]				SEL[3:0]							
0	0	0	0	0	0	0	0	0	0	0	

HTH[3:0] Handshake-to-Handshake Timer Period [7:4]
 These bits select the handshake-to-handshake time-out period, which is the maximum time between SCSI handshakes (SREQ/ to SREQ/ in target mode; or, SACK/ to SACK/ in initiator mode). When this timing is exceeded, an interrupt is generated and the HTH bit in the [SCSI Interrupt Status One \(SIST1\)](#) register is set. The following table contains time-out periods for the Handshake-to-Handshake Timer, the Selection/Reselection Timer (bits [3:0]), and the General Purpose Timer ([SCSI Timer One \(STIME1\)](#), bits [3:0]). For a more detailed explanation of interrupts, refer to [Chapter 2, “Functional Description”](#).

GENSF**General Purpose Timer Scale Factor****5**

Setting this bit causes this timer to shift by a factor of 16. Refer to the [SCSI Timer Zero \(STIME0\)](#) register description for details.

HTH[3:0], SEL[3:0], GEN [3:0]	Minimum Time-out	
	HTHSF = 0, GENSF = 0	HTHSF = 1, GENSF = 1
0000	Disabled	Disabled
0001	125 μ s	2 ms
0010	250 μ s	4 ms
0011	500 μ s	8 ms
0100	1 μ s	16 ms
0101	2 ms	32 ms
0110	4 ms	64 ms
0111	8 ms	128 ms
1000	16 ms	256 ms
1001	32 ms	512 ms
1010	64 ms	1 s
1011	128 ms	2 s
1100	256 ms	4.1 s
1101	512 ms	8.2 s
1110	1.024 s	16.4 s
1111	2.048 s	32.8 s

HTHSF**Handshake-to-Handshake Timer Scale Factor****4**

Setting this bit causes this timer to shift by a factor of 16. Refer to the [SCSI Timer Zero \(STIME0\)](#) register description for details.

GEN[3:0]**General Purpose Timer Period****[3:0]**

These bits select the period of the general purpose timer. The time measured is the time between enabling and disabling of the timer. When this timing is exceeded, the GEN bit in the [SCSI Interrupt Status One \(SIST1\)](#) register is set. Refer to the table under [SCSI Timer Zero \(STIME0\)](#), bits [3:0], for the available time-out periods.

Note:

To reset a timer before it expires and obtain repeatable delays, the time value must be written to zero first, and then written back to the desired value. This is also required when changing from one time value to another.

Register: 0x4A
Response ID Zero (RESPID0)
 Read/Write

7	RESPID0						0
x	x	x	x	x	x	x	x

RESPID0 **Response ID Zero** **[7:0]**
 RESPID0 and [Response ID One \(RESPID1\)](#) contain the selection or reselection IDs. These two 8-bit registers contain the SCSI ID that the chip responds to on the SCSI bus. Each bit represents one possible ID; the most significant bit of [Response ID One \(RESPID1\)](#) represents ID 15, and the least significant bit of RESPID0 represents ID 0. The [SCSI Chip ID \(SCID\)](#) register still contains the chip ID used during arbitration. The chip can respond to more than one ID because more than one bit can be set in the RESPID1 and RESPID0 registers. However, the chip can arbitrate with only one ID value in the [SCSI Chip ID \(SCID\)](#) register.

Register: 0x4B
Response ID One (RESPID1)
 Read/Write

7	RESPID1						0
x	x	x	x	x	x	x	x

RESPID1 **Response ID One** **[7:0]**
[Response ID Zero \(RESPID0\)](#) and RESPID1 contain the selection or reselection IDs. These two 8-bit registers contain the SCSI ID that the chip responds to on the SCSI bus. Each bit represents one possible ID; the most significant bit of RESPID1 represents ID 15, and the least significant bit of RESPID0 represents ID 0. The [SCSI Chip ID \(SCID\)](#) register still contains the chip ID used during arbitration. The chip can respond to more than one ID because more than one bit can be set in the RESPID1 and RESPID0 registers. However, the chip can arbitrate with only one ID value in the SCID register.

Register: 0x4C
SCSI Test Zero (STEST0)
Read Only

7	4	3	2	1	0		
SSAID[3:0]				SLT	ART	SOZ	SOM
0	0	0	0	0	x	1	1

SSAID[3:0] SCSI Selected As ID [7:4]

These bits contain the encoded value of the SCSI ID that the SYM53C1010 SCSI function is selected or reselected as during a SCSI Selection or Reselection phase. These bits are read only and contain the encoded value of 0–15 possible IDs that could be used to select the SYM53C1010 SCSI function. During a SCSI Selection or Reselection phase when a valid ID is put on the bus, and the SYM53C1010 SCSI function responds to that ID, the “selected as” ID is written into these bits. These bits are used with [Response ID Zero \(RESPID0\)](#) and [Response ID One \(RESPID1\)](#) registers to allow response to multiple IDs on the bus.

SLT Selection Response Logic Test 3

This bit is set when the SYM53C1010 SCSI function is ready to be selected or reselected. This does not take into account the bus settle delay of 400 ns. This bit is used for functional test and fault purposes.

ART Arbitration Priority Encoder Test 2

This bit is always set when the SYM53C1010 SCSI function exhibits the highest priority ID asserted on the SCSI bus during arbitration. It is primarily used for chip level testing. It may be used during low level mode operation to determine if the SYM53C1010 SCSI function won arbitration.

SOZ SCSI Synchronous Offset Zero 1

This bit indicates that the current synchronous SREQ/, SACK/ offset is zero. This bit is not latched and may change at any time. It is used in low level synchronous SCSI operations. When this bit is set and if the SYM53C1010 is functioning as an initiator, the device is waiting for the target to request data transfers. When this bit is set and if the SYM53C1010 is functioning as a

target, then the initiator has sent the offset number of acknowledges.

SOM **SCSI Synchronous Offset Maximum** **0**
 This bit indicates that the current synchronous SREQ/, SACK/ offset is the maximum specified by bits [5:0] in the [SCSI Transfer \(SXFER\)](#) register. This bit is not latched and may change at any time. It is used in low level synchronous SCSI operations. If this bit is set and if the SYM53C1010 is functioning as a target, it is waiting for the initiator to acknowledge the data transfers. If the SYM53C1010 SCSI is functioning as an initiator, the target has sent the offset number of requests.

Register: 0x4D
SCSI Test One (STEST1)
 Read/Write

7	6	5	4	3	2	1	0
R		DOSGE	DISGE	QEN	QSEL	IRM[1:0]	
0	0	0	0	0	0	0	0

R **Reserved** **[7:6]**

DOSGE **Disable Outbound SCSI Gross Errors** **5**
 When set, this bit disables all SCSI gross errors related to outbound data transfers.

DISGE **Disable Inbound SCSI Gross Errors** **4**
 When set, this bit disables all SCSI gross errors related to inbound data transfers.

QEN **SCLK Quadrupler Enable** **3**
 This bit, when set, powers up the internal clock quadrupler circuit, which quadruples the SCLK 40 MHz clock to the internal 160 MHz SCSI clock required for Ultra2 and Ultra3 SCSI operation. When cleared, this bit powers down the internal quadrupler circuit. Refer to [Chapter 2, “Functional Description”](#) for information concerning the operation of the quadrupler.

QSEL **SCLK Quadrupler Select** **2**
 This bit, when set, selects the output of the internal clock quadrupler as the internal SCSI clock. When cleared, this

bit selects the clock presented on SCLK as the internal SCSI clock. Refer to [Chapter 2, “Functional Description”](#) for information concerning the operation of the quadrupler.

IRM[1:0] Interrupt Routing Mode [1:0]

The SYM53C1010 supports four different interrupt routing modes. These modes are described in the following table. Each SCSI core within the chip can be configured independently. Mode 0, the default mode, is compatible with RAID upgrade products.

Mode	Bits [1:0]	Operation
0	00	If the INT_DIR/ input pin is low, interrupts are signaled on ALT_INTx/. Otherwise, interrupts are signaled on both INTx/ and ALT_INTx/.
1	01	Interrupts are only signaled on INTx/, not ALT_INTx/. The INT_DIR/ input pin is ignored.
2	10	Interrupts are only signaled on ALT_INTx/. The INT_DIR/ input pin is ignored.
3	11	Interrupts are signaled on both INTx/ and ALT_INTx/. The INT_DIR input pin is ignored.

**Register: 0x4E
SCSI Test Two (STEST2)
Read/Write**

7	6	5	4	3	2	1	0
SCE	ROF	R		SZM	R		LOW
0	0	0	0	0	0	0	0

SCE SCSI Control Enable 7

Setting this bit allows assertion of all SCSI control and data lines through the [SCSI Output Control Latch \(SOCL\)](#) and [SCSI Output Data Latch \(SODL\)](#) registers regardless of whether the SYM53C1010 SCSI function is configured as a target or initiator.

Note: Do not set this bit during normal operation, since it could cause contention on the SCSI bus. It is included for diagnostics purposes only.

ROF	Reset SCSI Offset	6
	Setting this bit clears any outstanding synchronous SREQ/SACK offset. If a SCSI gross error occurs, set this bit. This bit automatically clears itself after resetting the synchronous offset.	
R	Reserved	[5:4]
SZM	SCSI High Impedance Mode	3
	Setting this bit places all the open drain 48 mA SCSI drivers into a high impedance state.	
R	Reserved	[2:1]
LOW	SCSI Low Level Mode	0
	Setting this bit places the SYM53C1010 SCSI function in the low level mode. In this mode, no DMA operations occur and no SCRIPTS execute. Arbitration and selection may be performed by setting the start sequence bit as described in the SCSI Control Zero (SCNTL0) register. SCSI bus transfers are performed by manually asserting and polling SCSI signals. Clearing this bit allows instructions to be executed in the SCSI SCRIPTS mode.	

Note: It is not necessary to set this bit for access to the SCSI bit-level registers ([SCSI Output Data Latch \(SODL\)](#), [SCSI Bus Control Lines \(SBCL\)](#), and input registers).

Register: 0x4F
SCSI Test Three (STEST3)
Read/Write

7	6	5	4	3	2	1	0
TE	R	HSC	DSI	R	TTM	CSF	R
0	0	0	0	0	0	0	0

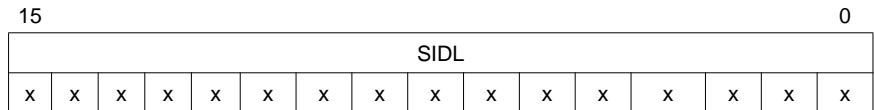
- TE** **TolerANT Enable** **7**
 Setting this bit enables the active negation portion of LSI Logic TolerANT technology. Active negation causes the SCSI Request, Acknowledge, Data, and Parity signals to be actively deasserted, instead of relying on external pull-ups, when the SYM53C1010 SCSI function is driving these signals. Active deassertion of these signals occurs only when the SYM53C1010 SCSI function is in an information transfer phase. When performing synchronous transfers, TolerANT should be enabled to improve setup and deassertion times. Active negation is disabled after reset or when this bit is cleared. For more information on LSI Logic TolerANT technology, see [Chapter 1, "Introduction"](#).
- R** **Reserved** **6**
- HSC** **Halt SCSI Clock** **5**
 Setting this bit causes the internal, divided SCSI clock to come to a stop in a glitchless manner. This bit is used for test purposes or to lower I_{DD} during a power-down mode. Refer to [Chapter 2, "Functional Description"](#) for operation of the SCSI clock quadrupler.
- DSI** **Disable Single Initiator Response** **4**
 If this bit is set, the SYM53C1010 SCSI function ignores all bus-initiated selection attempts that employ the single initiator option from SCSI-1. In order to select the SYM53C1010 SCSI function while this bit is set, the SYM53C1010 SCSI function's SCSI ID and the initiator's SCSI ID must both be asserted. Assert this bit in SCSI-2 systems so that a single bit error on the SCSI bus is not interpreted as a single initiator response.

R	Reserved	3
TTM	Timer Test Mode Setting this bit facilitates testing of the selection time-out, general purpose, and handshake-to-handshake timers by greatly reducing all three time-out periods. Setting this bit starts all three timers. If the respective bits in the SCSI Interrupt Enable One (SIEN1) register are asserted, the SYM53C1010 SCSI function generates interrupts at time-out. This bit is intended for internal manufacturing diagnosis and should not be used in normal operation.	2
CSF	Clear SCSI FIFO Setting this bit causes the “full flags” for the SCSI FIFO to be cleared. This empties the FIFO. This bit is self-clearing. In addition to the SCSI FIFO pointers, the SIDL, SODL, and SODR full bits in the SCSI Status Zero (SSTAT0) and SCSI Status Two (SSTAT2) are cleared.	1
R	Reserved	0

Registers: 0x50–0x51

SCSI Input Data Latch (SIDL)

Read Only



SIDL	SCSI Input Data Latch This register is used primarily for diagnostics testing, programmed I/O operation, or error recovery. Asynchronous Data received from the SCSI bus can be read from this register. When receiving asynchronous SCSI data, the data flows into this register and out to the host FIFO. This register differs from the SCSI Bus Data Lines (SBDL) register; the SCSI Input Data Latch (SIDL) contains latched data and the SCSI Bus Data Lines (SBDL) always contains exactly what is currently on the SCSI data bus. Reading this register causes the SCSI parity bit to be checked, and causes a parity error interrupt if the data is invalid. The power-up values are indeterminate.	[15:0]
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Register: 0x52
SCSI Test Four (STEST4)
Read Only

7	6	5						0
SMODE[1:0]		R						
x	x	0	0	0	0	0	0	

SMODE[1:0] SCSI Mode [7:6]

These bits contain the encoded value of the SCSI operating mode that is indicated by the voltage level sensed at the DIFFSENS pin. The incoming SCSI signal goes to a pair of analog comparators that determine the voltage window of the DIFFSENS signal. These voltage windows indicate LVD, SE, or HVD operation. The bit values are defined in the following table. When the HVD mode is detected, all of the SYM53C1010 3-state outputs go to the high impedance state.

SMODE [1:0]	Operating Mode
00	Reserved
01	High Impedance State
10	SE
11	LVD SCSI

R Reserved [5:0]

Register: 0x56
Chip Control Zero (CCNTL0)
Read/Write

7	6	5	4	3	2	1	0
ENPMJ	PMJCTL	ENNDJ	DISFC	R		DISRC	DPR
0	0	0	0	x	x	0	0

ENPMJ Enable Phase Mismatch Jump 7

Upon setting this bit, any phase mismatches do not interrupt but force a jump to an alternate location to handle the phase mismatch. Prior to actually taking the jump, the appropriate remaining byte counts and addresses are calculated to facilitate storage.

In the case of a SCSI send, any data in the part is automatically cleared after being accounted for. In the case of a SCSI receive, all data will be flushed out of the part and accounted for prior to taking the jump. This feature does not cover, however, the byte that may appear in [SCSI Wide Residue \(SWIDE\)](#). This byte must be flushed manually.

This bit also enables the flushing mechanism to flush data during a Data-In phase mismatch in a more efficient manner.

PMJCTL Jump Control 6

This bit controls which decision mechanism is used when jumping on phase mismatch. When this bit is cleared the SYM53C1010 will use [Phase Mismatch Jump Address One \(PMJAD1\)](#) when the WSR bit is cleared and [Phase Mismatch Jump Address Two \(PMJAD2\)](#) when the WSR bit is set. When this bit is set, the SYM53C1010 will use [Phase Mismatch Jump Address One \(PMJAD1\)](#) on Data-Out (Data-Out, Command, Message-Out) transfers and [Phase Mismatch Jump Address Two \(PMJAD2\)](#) on Data-In (Data-In, Status, Message-In) transfers. The phase referred to here is the phase encoded in the block move SCRIPTS instruction, not the phase on the SCSI bus that caused the phase mismatch.

ENNDJ Enable Jump On Nondata Phase Mismatches 5

This bit controls whether or not a jump is taken during a nondata phase mismatch (Message-In, Message-Out,

Status, or Command). When this bit is cleared, jumps will only be taken on Data-In or Data-Out phases, and a phase mismatch interrupt will be generated for all other phases. When this bit is set, jumps will be taken regardless of the phase in the block move. Note that the phase referred to here is the phase encoded in the block move SCRIPTS instruction, not the phase on the SCSI bus that caused the phase mismatch.

DISFC	Disable Auto FIFO Clear	4
	This bit controls whether or not the FIFO is automatically cleared during a Data-Out phase mismatch. When set, data in the DMA FIFO and in the SCSI Output Data Latch (SODL) and SODR (a hidden buffer register which is not accessible) registers are not cleared after calculations on them are complete. When cleared, the DMA FIFO, SODL, and SODR are automatically cleared. This bit also disables the enhanced flushing mechanism.	
R	Reserved	[3:2]
DISRC	Disable Internal SCRIPTS RAM Cycles	1
	This bit controls whether or not data transfers, for which the source/destination is located in SCRIPTS RAM, generate external PCI cycles. If cleared, data transfers of this type do NOT generate PCI cycles and stay internal to the chip. If set, data transfers of this type generate PCI cycles. This does not affect SCRIPTS Fetch operations from SCRIPTS RAM, including Table Indirect and Indirect opcode fetches.	
DPR	Disable Pipe Req	0
	This bit controls whether or not overlapped arbitration on the PCI bus occurs. Overlapped arbitration is performed by asserting PCI REQ/ for one SCSI function while the other SCSI function is executing a PCI cycle. If set, overlapped arbitration is disabled.	

Register: 0x57
Chip Control One (CCNTL1)
Read/Write

7	6	5	4	3	2	1	0
PULLDIS	PULLEN	DIS64MAS	DIS64SLV	DDAC	64TIMOD	EN64TIBMV	EN64DBMV
0	0	0	0	x	x	0	0

- PULLDIS** **Pull Disable** **7**
 Setting this bit causes all internal pulls to be disabled on all pins. This bit is intended for manufacturing test only and should NOT be set for normal operation. PULLDIS has precedence over PULLEN if both bits are set.
- PULLEN** **Pull Enable** **6**
 Setting this bit causes all internal pulls to be enabled on all pins. This bit is intended for manufacturing test only and should NOT be set for normal operation.
- DIS64MAS** **Disable 64-bit Master Operation** **5**
 Setting this bit causes the SYM53C1010 to no longer request 64-bit master data transfers. If this bit is set by either SCSI channel, 64-bit data transfers will be disabled for all master transactions.
- DIS64SLV** **Disable 64-bit Slave Cycles** **4**
 Setting this bit disables 64-bit slave data transfers to the SCRIPTS RAM. This causes only 32-bit data transfers to occur.
- DDAC** **Disable Dual Address Cycle** **3**
 When this bit is set, all 64-bit addressing as a master is disabled. No dual address cycles will be generated by the SYM53C1010.

 When this bit is cleared, the SYM53C1010 generates dual address cycles based on the master operation performed and the value of its associated selector register.
- 64TIMOD** **64-bit Table Indirect Indexing Mode** **2**
 When this bit is cleared, bits [28:24] of the first table entry Dword will select one of 22 possible selectors to be used in a BMOV operation. When this bit is set, bits [31:24] of the first table entry Dword will be copied directly into

[DMA Next Address 64 \(DNAD64\)](#) to provide 40-bit addressing capability. This bit will only function if the EN64TIBMV bit is set.

Index Mode 0 (64TIMOD clear) table entry format:

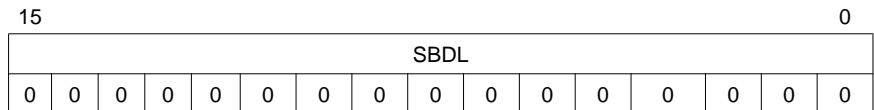
Bits [31:29]	Bits [28:24]	Bits [23:0]
Reserved	Sel Index	Byte Count
Source/Destination Address		

Index Mode 1 (64TIMOD set) table entry format:

Bits [31:24]	Bits [23:0]
Src/Dest Addr [39:32]	Byte Count
Source/Destination Address [31:0]	

- EN64TIBMV** **Enable 64-bit Table Indirect BMOV** **1**
 Setting this bit enables 64-bit addressing for Table Indirect BMOVs using the upper byte (bits [31:24]) of the first Dword of the table entry. When this bit is cleared, Table Indirect BMOVs use the [Static Block Move Selector \(SBMS\)](#) register to obtain the upper 32 bits of the data address.
- EN64DBMV** **Enable 64-bit Direct BMOV** **0**
 Setting this bit enables the 64-bit version of a direct BMOV. When this bit is cleared, direct BMOVs use the [Static Block Move Selector \(SBMS\)](#) register to obtain the upper 32 bits of the data address.

Registers: 0x58–0x59
SCSI Bus Data Lines (SBDL)
Read Only



SBDL **SCSI Bus Data Lines** **[15:0]**
 This register contains the SCSI data bus status. Even though the SCSI data bus is active low, these bits are active high. The signal status is not latched and is a true representation of exactly what is on the data bus at the

Note: These bits are used for Ultra3 SCSI Domain Validation only and should not be set during normal data transfer operations.

LVDDL[1:0] LVD Drive Strength Select [1:0]
 These bits control the drive level of the LVD pad drivers.

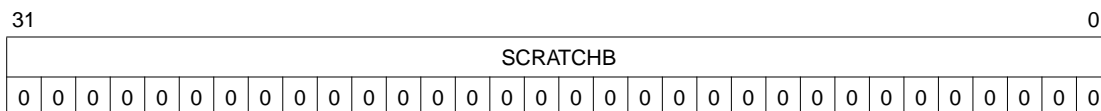
Note: This feature is for Ultra3 SCSI Domain Validation testing environments only and should not be set during normal data transfer operations.

The table below shows the relative strength increase or decrease based on the LVDDL values.

LVDDL	Drive Level
00	Nominal
01	-20% Nominal
10	+20% Nominal
11	Reserved

Note: If one of the LVDDL [1:0] bits are set on either channel, both channels are affected.

Registers: 0x5C–0x5F
Scratch Register B (SCRATCHB)
 Read/Write



SCRATCHB Scratch Register B [31:0]

This is a general purpose user-definable scratch pad register. Apart from CPU access, only register Read/Write and Memory Moves directed at the SCRATCH register will alter its contents. The power-up values are indeterminate. A special mode of this register can be enabled by setting the PCI Configuration Info Enable bit in the [Chip Test Two \(CTEST2\)](#) register. If this bit is set, bits [31:13] of the [Scratch Register B \(SCRATCHB\)](#) register return bits [31:13] of the [PCI Base Address Register Three \(BAR3\) \(SCRIPTS RAM\)](#). In this mode, bits [12:0] of SCRATCH B will always return zeros. Writes to the SCRATCH B register have no effect.

U3EN	Ultra3 Transfer Enable	7
	Setting this bit enables Ultra3 transfers. This bit will force all SCSI Block Move SCRIPTS instructions for ST Data-In or ST Data-Out phases to become DT Data-In or DT Data-Out phases.	
AIPEN	Asynchronous Information Protection Enable	6
	Setting this bit enables the AIP checking and generation of the upper byte lane of protection information during Command, Status, and Message phases.	
R	Reserved	[5:4]
XCLKH_DT	Extra Clock of Data Hold on DT Transfer Edge	3
	Setting this bit adds a clock of data hold to synchronous DT SCSI transfers on the DT edge. This bit only impacts DT transfers as it affects data hold to the DT edge. Setting this bit reduces the synchronous transfer send rate but does not reduce the transfer rate at which the SYM53C1010 can receive inbound REQs, ACKs or data. Refer to Table 4.4 and Table 4.5 for a summary of available transfer rates and to Figure 4.1 through Figure 4.3 for examples of how the XCLKH bits function.	
	<u>Note:</u> This bit does not affect CRC timings.	
XCLKH_ST	Extra Clock of Data Hold on ST Transfer Edge	2
	Setting this bit adds a clock of data hold to synchronous DT or ST SCSI transfers on the ST edge. This bit impacts both ST and DT transfers as it affects data hold to the ST edge. Setting this bit reduces the synchronous send transfer rate but does not reduce the transfer rate at which the SYM53C1010 can receive inbound REQs, ACKs or data. Refer to Table 4.4 and Table 4.5 for a summary of available transfer rates and to Figure 4.1 through Figure 4.3 for examples of how the XCLKH bits function.	
	<u>Note:</u> This bit does not affect CRC timings.	
XCLKS_DT	Extra Clock of Data Setup on DT Transfer Edge	1
	Setting this bit adds a clock of data setup to synchronous DT SCSI transfers on the DT edge. This bit only impacts DT transfers as it only affects data setup to the DT edge. Setting this bit reduces the synchronous transfer send rate but does not reduce the transfer rate at which the	

SYM53C1010 can receive inbound REQs, ACKs or data. Refer to [Table 4.4](#) and [Table 4.5](#) for a summary of available transfer rates and to [Figure 4.1](#) through [Figure 4.3](#) for examples of how the XCLKS bits function.

Note: This bit does not affect CRC timings.

XCLKS_ST Extra Clock of Data Setup on ST Transfer Edge 0

Setting this bit adds a clock of data setup to synchronous DT or ST SCSI transfers on the ST edge. This bit impacts both ST and DT transfers as it affects data setup to the ST edge. Setting this bit reduces the synchronous send transfer rate but does not reduce the transfer rate at which the SYM53C1010 can receive inbound REQs, ACKs or data. Refer to [Table 4.4](#) and [Table 4.5](#) for a summary of available transfer rates and to [Figure 4.1](#) through [Figure 4.3](#) for examples of how the XCLKS bits function.

Note: This bit does not affect CRC timings.

Synchronous Receive Rate Calculation

The synchronous receive rate, in megatransfers/s, can be calculated using the following formulas:

$$\text{Receive Rate (DT)} = \frac{\text{Input Clock Rate}}{\text{SCF Divisor} \times 2}$$

$$\text{Receive Rate (ST)} = \frac{\text{Input Clock Rate}}{\text{SCF Divisor} \times 4}$$

Note: The receive rate is independent of the settings of the XCLKS_DT, XCLKS_ST, XCLKH_DT, and XCLKH_ST bits.

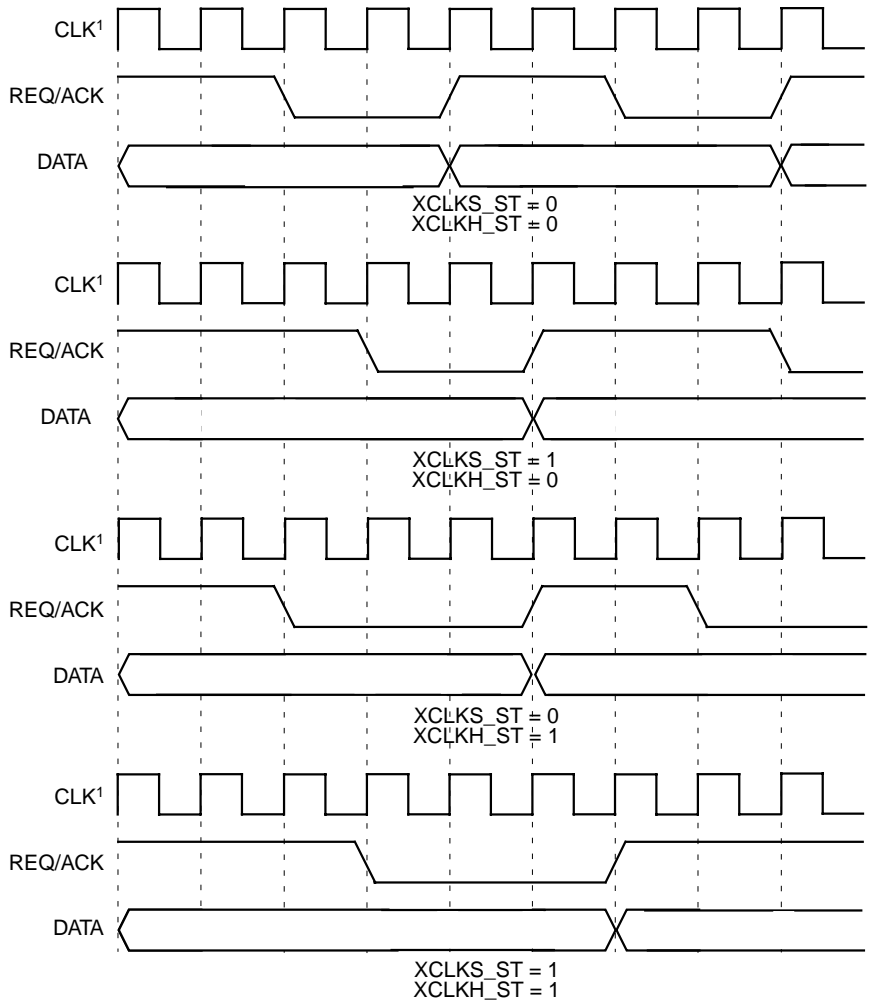
Synchronous Send Rate Calculation

The synchronous send rate, in megatransfers/s, can be calculated using the following formula:

$$\text{Send Rate (DT)} = \frac{\text{Input Clock Rate}}{\left(\text{SCF Divisor} \times \left(2 + \frac{\text{XCLKS_DT} + \text{XCLKS_ST} + \text{XCLKH_DT} + \text{XCLKH_ST}}{2} \right) \right)}$$

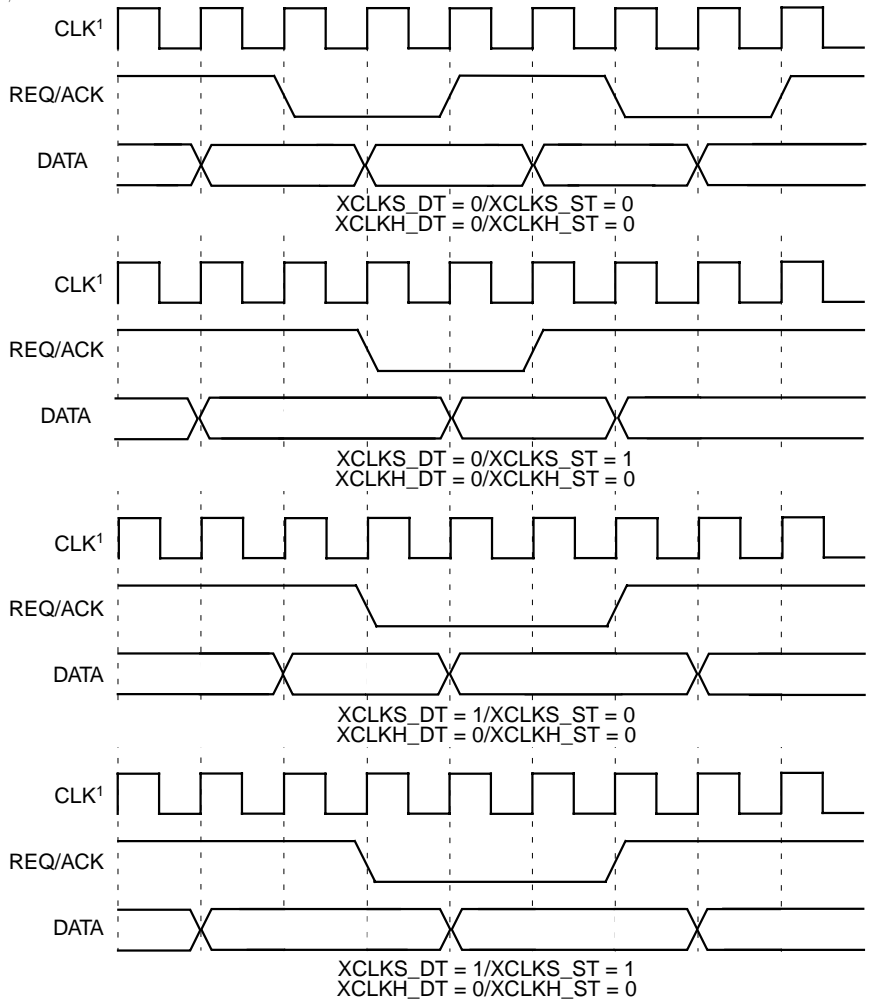
$$\text{Send Rate (ST)} = \frac{\text{Input Clock Rate}}{\left(\text{SCF Divisor} \times (4 + \text{XCLKS_ST} + \text{XCLKH_ST}) \right)}$$

Figure 4.1 Single Transition Transfer Waveforms



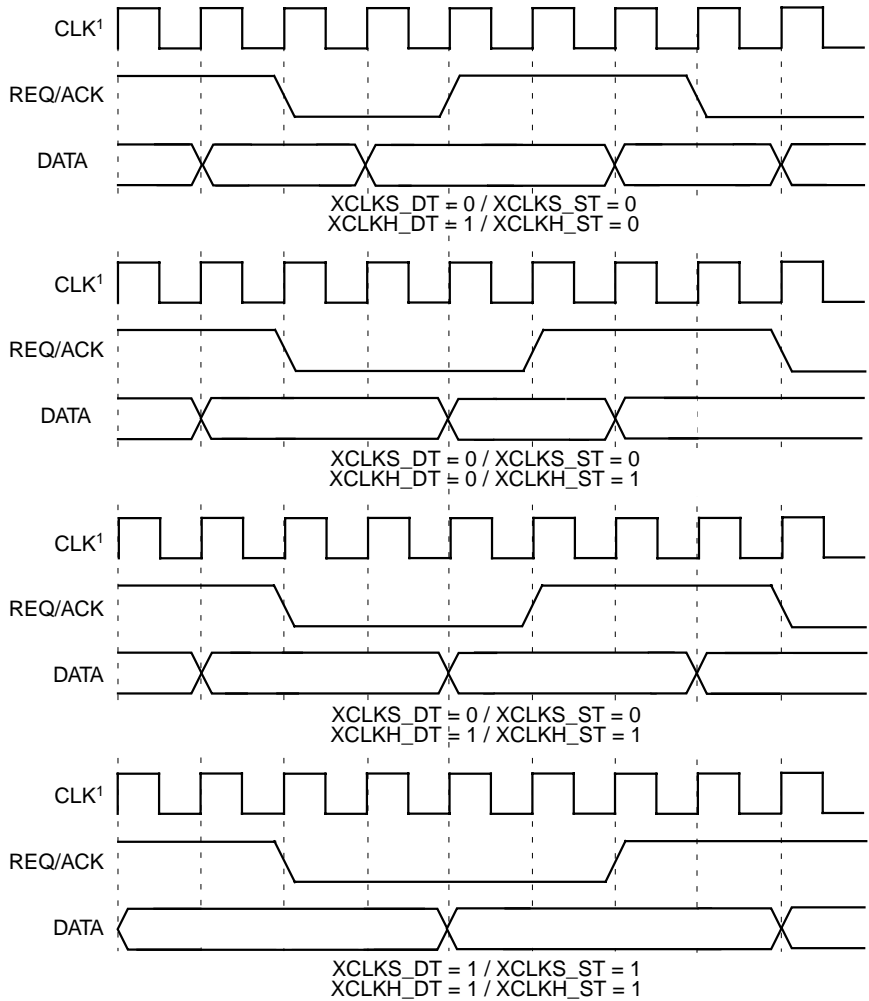
1. CLK = SCLK/SCF Divisor

Figure 4.2 Double Transition Transfer Waveforms (XCLKS Examples)



1. CLK = SCLK/SCF Divisor

Figure 4.3 Double Transition Transfer Waveforms (XCLKH Examples)



1. CLK = SCLK/SCF Divisor

Table 4.4 Double Transition Transfer Rates

Clock (MHz)	Divisor	Number Xclk's¹	Base Period (ns)	Receive Rate (Megatransfers/s)	Send Rate (Megatransfers/s)
160	1	0	6.25	80.00	80.00
160	1	1	6.25	80.00	64.00
160	1	2	6.25	80.00	53.33
160	1	3	6.25	80.00	45.71
160	1	4	6.25	80.00	40.00
160	1.5	0	9.38	53.33	53.33
160	1.5	1	9.38	53.33	42.67
160	1.5	2	9.38	53.33	35.56
160	1.5	3	9.38	53.33	30.48
160	1.5	4	9.38	53.33	26.67
160	2	0	12.50	40.00	40.00
160	2	1	12.50	40.00	32.00
160	2	2	12.50	40.00	26.67
160	2	3	12.50	40.00	22.86
160	2	4	12.50	40.00	20.00
160	3	0	18.75	26.67	26.67
160	3	1	18.75	26.67	21.33
160	3	2	18.75	26.67	17.78
160	3	3	18.75	26.67	15.24
160	3	4	18.75	26.67	13.33
160	4	0	25.00	20.00	20.00
160	4	1	25.00	20.00	16.00
160	4	2	25.00	20.00	13.33
160	4	3	25.00	20.00	11.43
160	4	4	25.00	20.00	10.00
160	6	0	37.50	13.33	13.33
160	6	1	37.50	13.33	10.67
160	6	2	37.50	13.33	8.89
160	6	3	37.50	13.33	7.62
160	6	4	37.50	13.33	6.67
160	8	0	50.00	10.00	10.00
160	8	1	50.00	10.00	8.00
160	8	2	50.00	10.00	6.67
160	8	3	50.00	10.00	5.71
160	8	4	50.00	10.00	5.00
40	1	0	25.00	20.00	20.00
40	1	1	25.00	20.00	16.00
40	1	2	25.00	20.00	13.33
40	1	3	25.00	20.00	11.43
40	1	4	25.00	20.00	10.00

Table 4.4 Double Transition Transfer Rates (Cont.)

Clock (MHz)	Divisor	Number Xclk's¹	Base Period (ns)	Receive Rate (Megatransfers/s)	Send Rate (Megatransfers/s)
40	1.5	0	37.50	13.33	13.33
40	1.5	1	37.50	13.33	10.67
40	1.5	2	37.50	13.33	8.89
40	1.5	3	37.50	13.33	7.62
40	1.5	4	37.50	13.33	6.67
40	2	0	50.00	10.00	10.00
40	2	1	50.00	10.00	8.00
40	2	2	50.00	10.00	6.67
40	2	3	50.00	10.00	5.71
40	2	4	50.00	10.00	5.00
40	3	0	75.00	6.67	6.67
40	3	1	75.00	6.67	5.33
40	3	2	75.00	6.67	4.44
40	3	3	75.00	6.67	3.81
40	3	4	75.00	6.67	3.33
40	4	0	100.00	5.00	5.00
40	4	1	100.00	5.00	4.00
40	4	2	100.00	5.00	3.33
40	4	3	100.00	5.00	2.86
40	4	4	100.00	5.00	2.50
40	8	0	200.00	2.50	2.50
40	8	1	200.00	2.50	2.00
40	8	2	200.00	2.50	1.67
40	8	3	200.00	2.50	1.43
40	8	4	200.00	2.50	1.25

1. Number Xclk's = XCLKS_DT + XCLKS_ST + XCLKH_DT + XCLKH_ST

Table 4.5 Single Transition Transfer Rates

Clock (MHz)	Divisor	Number Xclk's¹	Base Period (ns)	Receive Rate (Megatransfers/s)	Send Rate (Megatransfers/s)
160	1	0	6.25	40.00	40.00
160	1	1	6.25	40.00	32.00
160	1	2	6.25	40.00	26.67
160	1.5	0	9.38	26.67	26.67
160	1.5	1	9.38	26.67	21.33
160	1.5	2	9.38	26.67	17.78
160	2	0	12.50	20.00	20.00
160	2	1	12.50	20.00	16.00
160	2	2	12.50	20.00	13.33
160	3	0	18.75	13.33	13.33
160	3	1	18.75	13.33	10.67
160	3	2	18.75	13.33	8.89
160	4	0	25.00	10.00	10.00
160	4	1	25.00	10.00	8.00
160	4	2	25.00	10.00	6.67
160	6	0	37.50	6.67	6.67
160	6	1	37.50	6.67	5.33
160	6	2	37.50	6.67	4.44
160	8	0	50.00	5.00	5.00
160	8	1	50.00	5.00	4.00
160	8	2	50.00	5.00	3.33
40	1	0	25.00	10.00	10.00
40	1	1	25.00	10.00	8.00
40	1	2	25.00	10.00	6.67
40	1.5	0	37.50	6.67	6.67
40	1.5	1	37.50	6.67	5.33
40	1.5	2	37.50	6.67	4.44
40	2	0	50.00	5.00	5.00
40	2	1	50.00	5.00	4.00
40	2	2	50.00	5.00	3.33
40	3	0	75.00	3.33	3.33
40	3	1	75.00	3.33	2.67
40	3	2	75.00	3.33	2.22
40	4	0	100.00	2.50	2.50
40	4	1	100.00	2.50	2.00
40	4	2	100.00	2.50	1.67

Table 4.5 Single Transition Transfer Rates (Cont.)

Clock (MHz)	Divisor	Number Xclk's ¹	Base Period (ns)	Receive Rate (Megatransfers/s)	Send Rate (Megatransfers/s)
40	6	0	150.00	1.67	1.67
40	6	1	150.00	1.67	1.33
40	6	2	150.00	1.67	1.11
40	8	0	200.00	1.25	1.25
40	8	1	200.00	1.25	1.00
40	8	2	200.00	1.25	0.83

1. Number Xclk's = XCLKS_ST + XCLKH_ST

Register: 0xBD
Reserved

7	R							0
x	x	x	x	x	x	x	x	

This register is reserved.

Register: 0xBE
AIP Control Zero (AIPCNTL0)
Read/Write

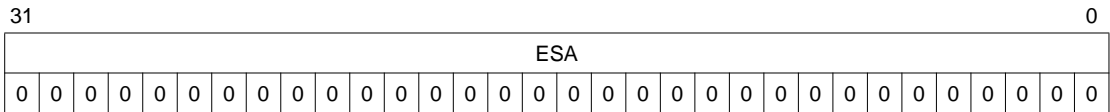
7	6	5	4	3	R			0
FBAIP	RSQAIP	SEQAIP						
0	0	0	0	0	0	0	0	

FBAIP **Force Bad AIP value** **7**
Setting this bit causes bad AIP values to be sent over the SCSI bus.

RSQAIP **Reset AIP Sequence value** **6**
Setting this bit causes the sequence value used in the calculation of the protection code to reset.

SEQAIP **AIP Sequence value** **[5:4]**
These two bits contain the current AIP sequence value. The SEQAIP bits are read only and should only be accessed for diagnostics purposes. The sequence value is automatically reset on every phase change.

Registers: 0xD0–0xD3
Entry Storage Address (ESA)
 Read/Write



ESA **Entry Storage Address** **[31:0]**

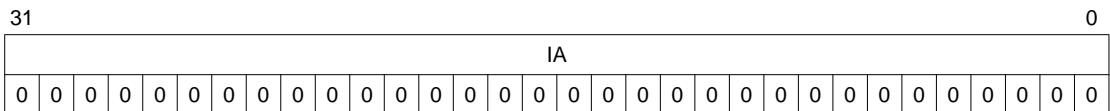
This register's value depends on the type of BMOV being executed. The three types of BMOVs are:

- Direct BMOV:** In the case of a direct BMOV, this register contains the address the BMOV was fetched from when the phase mismatch occurred.

- Indirect BMOV:** In the case of an indirect BMOV, this register contains the address the BMOV was fetched from when the phase mismatch occurred.

- Table Indirect BMOV:** In the case of a Table Indirect BMOV, this register contains the address of the Table Indirect entry being used when the phase mismatch occurred.

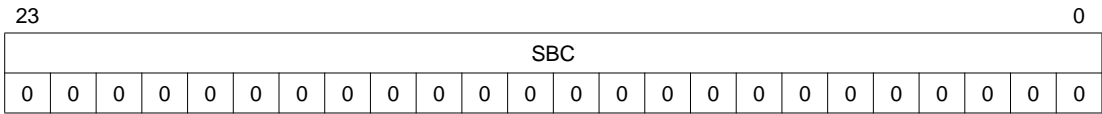
Registers: 0xD4–0xD7
Instruction Address (IA)
 Read/Write



IA **Instruction Address** **[31:0]**

This register always contains the address of the BMOV instruction that was executing when the phase mismatch occurred. This value will always match the value in the [Entry Storage Address \(ESA\)](#) except in the case of a Table Indirect BMOV in which case the ESA will have the address of the Table Indirect entry and this register points to the address of the BMOV instruction.

Registers: 0xD8–0xDA
SCSI Byte Count (SBC)
Read Only

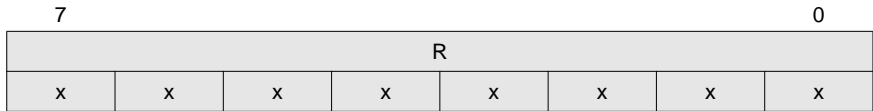


SBC **SCSI Byte Count** **[23:0]**

This register contains the count of the number of bytes transferred to or from the SCSI bus during any given BMOV. This value is used in calculating the information placed into the [Remaining Byte Count \(RBC\)](#) and [Updated Address \(UA\)](#) registers and should not need to be used in normal operations.

There are several conditions for which the byte count does not match the number of bytes transferred. If a BMOV transfers an odd number of bytes across a wide bus, the byte count at the end of the BMOV is one byte greater than the number of bytes sent. This also occurs in an odd byte count wide receive case. Lastly, when a wide send occurs and a chain byte from a previous transfer is present, the byte count does not reflect the chain byte sent across the bus during that BMOV. To determine the correct address to start fetching data from after a phase mismatch, this byte is not counted for this BMOV. It is included in the previous BMOV's byte count.

Register: 0xDB
Reserved



This register is reserved.

request a CRC by executing a force CRC Block Move instruction.

CRCRI	Interval (Bytes)
0x0	Disabled
0x1	128
0x2	256
0x3	512
0x4	1024
0x5	2048
0x6	4096
0x7	8192
0x8	16384
0x9	32768
0xA	65536
0xB	Reserved
0xC	Reserved
0xD	Reserved
0xE	Reserved
0xF	Reserved

Register: 0xE3
CRC Control One (CRCCTL1)
 Read/Write

7	6	5	4	3	2	1	0
CRCERR	R	ENAS	TSTSD	TSTCHK	TSTADD	CRCDSEL	
0	0	0	0	0	0	0	0

CRCERR

CRC Error

7

This bit indicates whether or not a CRC error has been detected during a DT Data-In SCSI transfer. This bit is set independent of the DISCRCCHK bit. To clear this condition, either write this bit to a 1 or read the [SCSI Interrupt Status Zero \(SIST0\)](#) and [SCSI Interrupt Status One \(SIST1\)](#) registers. When CRC Checking and the Parity/CRC/AIP Error Interrupt are enabled, this error condition is also indicated as a Parity/CRC/AIP error (bit 0 of the SIST0 register).

CRC

CRC Data

[31:0]

If CRCDSEL = 0b00, this register represents the current CRC value. After sending data during the DT Data-Out phase, this register contains the CRC calculation for that data, if no CRC request occurred during the transfer. In this mode, this register is read only.

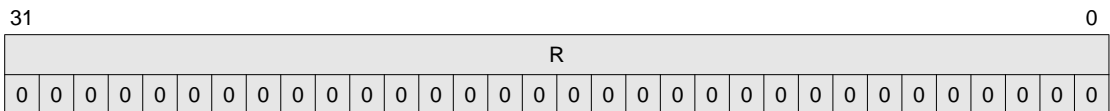
If CRCDSEL = 0b01, this register represents the CRC Input register and contains its current value. It normally contains the SCSI data transferred to or from the SCSI bus during a DT transfer phase. In this mode, this register can be written to in order to manually alter the input data used for CRC calculation. For normal operations, this register should never be written to.

If CRCDSEL = 0b10, this register represents the CRC Accumulator and contains its current value. In this mode, this register can be written to in order to manually modify the value in the accumulator. This register should not be written to during normal operation as corrupt CRC values result.

If CRCDSEL = 0b11, this register contains the saved bad CRC value that was calculated when a CRC error was detected. After a CRC error is detected, this register is not overwritten until the error condition is cleared.

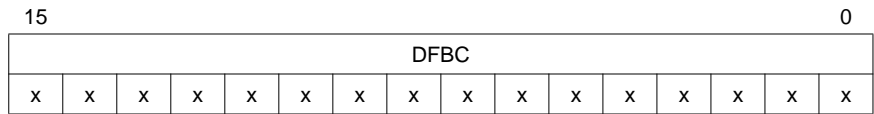
Registers: 0xE8–0xEF

Reserved



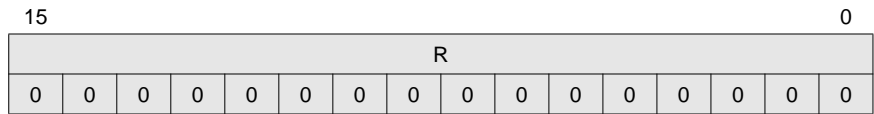
This register is reserved.

Registers: 0xF0–0xF1
DMA FIFO Byte Count (DFBC)
Read Only



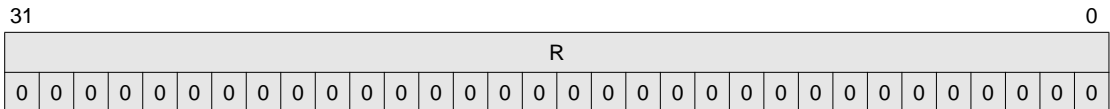
DFBC **DMA FIFO Byte Count** **[15:0]**
 This 16-bit read only register contains the actual number of bytes contained in the DMA FIFO. This register is not stable while data is actually being transferred. This register can be used during error recovery.

Registers: 0xF2–0xF3
Reserved



This register is reserved.

Registers: 0xF4–0xFF
Reserved



This register is reserved.

PCO	Phase Change with Outstanding Offset	4
OO	Offset Overflow	3
OU	Offset Underflow	2
DO	Data Overflow	1
DU	Data Underflow	0

Register: 0x43

Shadowed SCSI Interrupt Status One (SIST1)

Read Only

7	6	5	4	3	2	1	0
R		PNCRC	FCRC	DTST	NFCRC	MCRC	R
0	0	0	0	0	0	0	0

This register contains the individual status bits which cause a SGE SCSI interrupt. These bits correspond to the SGE conditions described in the [SCSI Interrupt Status Zero \(SIST0\)](#) register description. Unlike the other registers in the device, these bits must be set to one to clear the condition. This register is shadowed behind the SIST registers. Setting bit 4 (SRTM) in the [Chip Test Four \(CTEST4\)](#) register, enables access to this register.

R	Reserved	[7:6]
PNCRC	Pad Request with no CRC Request Following	5
FCRC	Force CRC	4
DTST	Switch from DT to ST Timings During a Transfer	3
NFCRC	Phase Change with No Final CRC Request	2
MCRC	Multiple CRC Requests with the Same Offset	1
R	Reserved	0

Chapter 5

SCSI SCRIPTS

Instruction Set

After power-up and initialization, the SYM53C1010-33 can operate in the low level register interface mode, or use SCSI SCRIPTS.

With the low level register interface, the user has access to the DMA control logic and the SCSI bus control logic. An external processor has access to the SCSI bus signals and the low level DMA signals, which allow creation of complicated board level test algorithms. The low level interface is useful for backward compatibility with SCSI devices that require certain unique timings or bus sequences to operate properly.

The following sections describe the benefits and use of SCSI SCRIPTS.

- [Section 5.1, “SCSI SCRIPTS”](#)
- [Section 5.2, “Block Move Instructions”](#)
- [Section 5.3, “I/O Instructions”](#)
- [Section 5.4, “Read/Write Instructions”](#)
- [Section 5.5, “Transfer Control Instructions”](#)
- [Section 5.6, “Memory Move Instructions”](#)
- [Section 5.7, “Load and Store Instructions”](#)

5.1 SCSI SCRIPTS

To operate in the SCSI SCRIPTS mode, the SYM53C1010-33 requires only a SCRIPTS start address. The start address must be at a Dword (four byte) boundary. This aligns all the following SCRIPTS at a Dword boundary since all SCRIPTS are 8 or 12 bytes long. Instructions are fetched until an interrupt instruction is encountered, or until an unexpected event (such as a hardware error) causes an interrupt to the external processor.

Once an interrupt is generated, the SYM53C1010-33 halts all operations until the interrupt is serviced. Then, the start address of the next SCRIPTS instruction is written to the [DMA SCRIPTS Pointer \(DSP\)](#) register to restart the automatic fetching and execution of instructions.

In the SCSI SCRIPTS mode the SYM53C1010-33 is allowed to make decisions based on the status of the SCSI bus, which frees the microprocessor from servicing the numerous interrupts inherent in I/O operations.

Given the rich set of SCSI-oriented features included in the instruction set, and the ability to re-enter the SCSI algorithm at any point, this high level interface is all that is required for both normal and exception conditions. Switching to the low level mode for error recovery is not required.

The following types of SCRIPTS instructions are implemented in the SYM53C1010-33:

Block Move – used to move data between the SCSI bus and memory.

I/O or Read/Write – causes the SYM53C1010-33 to trigger common SCSI hardware sequences, or to move registers.

Transfer Control – allows SCRIPTS instructions to make decisions based on real time SCSI bus conditions.

Memory Move – causes the SYM53C1010-33 to execute block moves between different parts of main memory.

Load/Store – provides a more efficient way to move data to/from memory from/to an internal register in the chip without using the Memory Move instruction.

Each instruction consists of two or three 32-bit words. The first 32-bit word is always loaded into the [DMA Command \(DCMD\)](#) and [DMA Byte Counter \(DBC\)](#) registers, the second into the [DMA SCRIPTS Pointer Save \(DSPS\)](#) register. The third word, used only by Memory Move instructions, is loaded into the [Temporary \(TEMP\)](#) shadow register. In an indirect I/O or Move instruction, the first two 32-bit opcode fetches are followed by one or two more 32-bit fetch cycles.

5.1.1 Sample Operation

The following example describes execution of a SCRIPTS Block Move instruction.

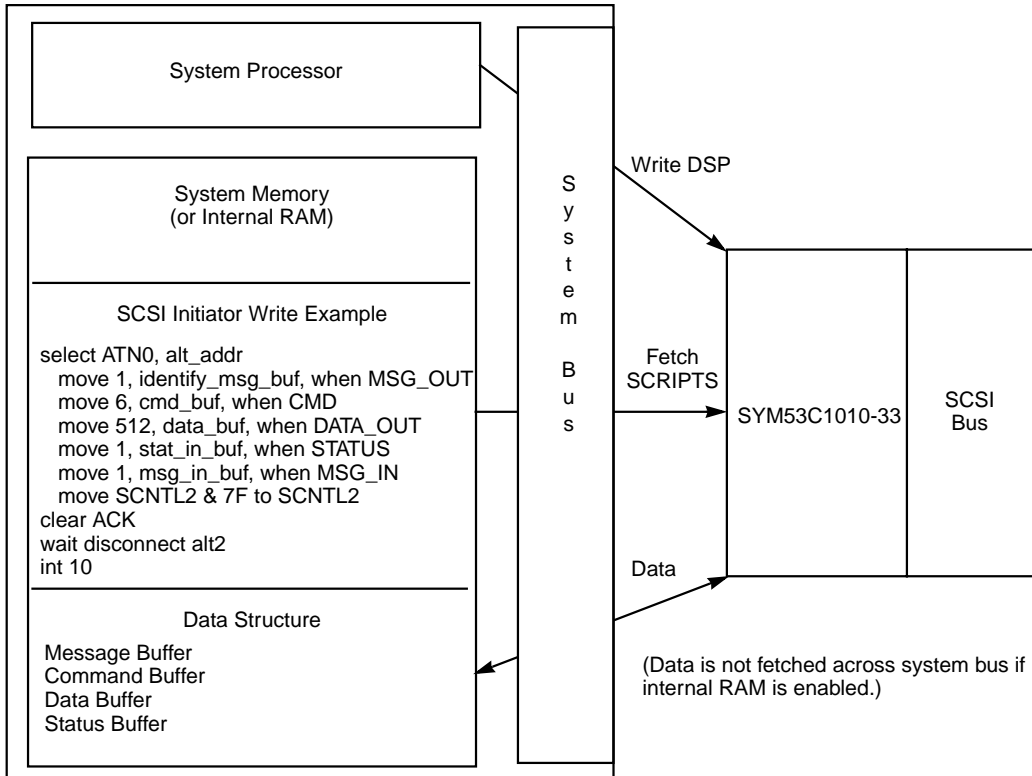
- The host CPU, through programmed I/O, gives the [DMA SCRIPTS Pointer \(DSP\)](#) register (in the Operating register file) the starting address in main memory that points to a SCSI SCRIPTS program for execution.
- Loading the [DMA SCRIPTS Pointer \(DSP\)](#) register causes the SYM53C1010-33 to fetch its first instruction at the address just loaded. This fetch is from main memory or the internal RAM, depending on the address.
- The SYM53C1010-33 typically fetches two Dwords (64 bits) and decodes the high-order byte of the first Dword as a SCRIPTS instruction. If the instruction is a Block Move, the lower three bytes of the first Dword are stored and interpreted as the number of bytes to move. The second Dword is stored and interpreted as the 32-bit beginning address in main memory to which the move is directed.
- For a SCSI send operation, the SYM53C1010-33 waits until there is enough space in the DMA FIFO to transfer a programmable size block of data. For a SCSI receive operation, it waits until enough data is collected in the DMA FIFO for transfer to memory. At this point, the SYM53C1010-33 requests use of the PCI bus again to transfer the data.
- When the SYM53C1010-33 is granted the PCI bus, it executes (as a bus master) a burst transfer (programmable size) of data, decrements the internally stored remaining byte count, increments the address pointer, and then releases the PCI bus. The SYM53C1010-33 stays off the PCI bus until the FIFO can again hold (for a write) or has collected (for a read) enough data to repeat the process.

The process repeats until the internally stored byte count has reached zero. The SYM53C1010-33 releases the PCI bus and then performs another SCRIPTS instruction fetch cycle, using the incremented stored address maintained in the [DMA SCRIPTS Pointer \(DSP\)](#) register. Execution of SCRIPTS instructions continues until an error condition occurs or an interrupt SCRIPTS instruction is received. At this point, the SYM53C1010-33 interrupts the host CPU and waits for further servicing

by the host system. It can execute independent Block Move instructions specifying new byte counts and starting locations in main memory. In this manner, the SYM53C1010-33 performs scatter/gather operations on data without requiring help from the host program, generating a host interrupt, or programming of an external DMA controller.

Figure 5.1 provides an overview of SCRIPTS operation.

Figure 5.1 SCRIPTS Overview



5.2 Block Move Instructions

For Block Move instructions, bits 5 and 4 (SIOM and DIOM) in the [DMA Mode \(DMODE\)](#) register determine whether the source/destination address resides in memory or I/O space. When data is moved onto the SCSI bus, SIOM controls whether that data comes from the I/O or memory space. When data is moved off of the SCSI bus, DIOM controls whether that data goes to the I/O or memory space.

5.2.1 First Dword

Figure 5.2 Block Move Instruction - First Dword

31	30	29	28	27	26	24	23	16	15	8	7	0
DCMD Register							DBC Register					
IT[1:0]		IA	TIA	OPC	SCSIP[2:0]			TC[23:0]				
x	x	x	x	x	x	x	x	x	x	x	x	x

IT[1:0] **Instruction Type - Block Move** **[31:30]**
 The configuration of these two bits define the SCRIPTS Instruction Type. The Block Move Instruction is bit configuration 0, 0.

IA **Indirect Addressing** **29**
 When this bit is cleared, user data is moved to or from the 32-bit data start address for the Block Move instruction. The value is loaded into the chip's address register and incremented as data is transferred. The address of the data to move is in the second Dword of this instruction.
 When the EN64DBMV bit in [Chip Control One \(CCNTL1\)](#) is set, a third Dword is fetched to provide the upper Dword of a 64-bit address. The upper Dword address is fetched along with the instruction and loaded into the [Dynamic Block Move Selector \(DBMS\)](#) register.
 If the EN64DBMV bit is cleared, the upper Dword address is copied from the [Static Block Move Selector \(SBMS\)](#) register.

Direct Addressing

The byte count and absolute address are as follows:

Command	Byte Count
	Lower Dword Address of Data
	Upper Dword address of data (EN64DBMV = 1)

Indirect

When set, the 32-bit user data start address for the Block Move is the address of a pointer to the actual data buffer address. The value at the 32-bit start address is loaded into the chip's [DMA Next Address \(DNAD\)](#) register using a third Dword fetch (4-byte transfer across the host computer bus).

Use the fetched byte count, but fetch the data address from the address in the instruction.

If 64-bit addressing is desired, the upper Dword of the address is stored in the [Static Block Move Selector \(SBMS\)](#) register. When the value in SBMS is 0x0, 32-bit addressing is assumed.

Command	Byte Count
	Address of Pointer to Data

Once the data pointer address is loaded, it is executed as when the chip operates in the direct mode. This indirect feature allows specification of a table of data buffer addresses. Using the SCSI SCRIPTS compiler, the table offset is placed in the SCRIPT at compile time. Then at the actual data transfer time, the offsets are added to the base address of the data address table by the external processor. The logical I/O driver builds a structure of addresses for an I/O rather than treating each address individually.

Note: Using indirect and table indirect addressing simultaneously is not permitted; use only one addressing method at a time.

When this bit is set, the 24-bit signed value in the start address of the move is treated as a relative displacement from the value in the [Data Structure Address \(DSA\)](#) register. Both the transfer count and the source/destination address are fetched from this location.

Use the signed integer offset in bits [23:0] of the second four bytes of the instruction, added to the value in the [Data Structure Address \(DSA\)](#) register, to fetch first the byte count and then the data address. The signed value is combined with the data structure base address to generate the physical address used to fetch values from the data structure. Sign-extended values of all ones for negative values are allowed, but bits [31:24] are ignored.

Command	Not Used
Don't Care	Table Offset

Note: Using indirect and table indirect addressing simultaneously is not permitted; use only one addressing method at a time.

Prior to the start of an I/O, load the [Data Structure Address \(DSA\)](#) register with the base address of the I/O data structure. Any address on a Dword boundary is allowed.

After a Table Indirect opcode is fetched, the [Data Structure Address \(DSA\)](#) is added to the 24-bit signed offset value from the opcode to generate the address of the required data; both positive and negative offsets are allowed. A subsequent fetch from that address brings the data values into the chip.

For a MOVE instruction, the 24-bit byte count is fetched from system memory. Then the 32-bit physical address is brought into the SYM53C1010-33. Execution of the move begins at this point.

SCRIPTS can directly execute operating system I/O data structures, saving time at the beginning of an I/O operation. The I/O data structure can begin on any Dword boundary and may cross system segment boundaries.

There are two restrictions on the placement of pointer data in system memory:

- The eight bytes of data in the MOVE instruction must be contiguous.
- Indirect data fetches are not available during execution of a Memory-to-Memory DMA operation.

00 Byte Count

Physical Data Address

64-bit Addressing

If the Enable 64-bit Table Indirect Block Move (EN64TIBMV) bit is cleared, table indirect block moves remain as two Dword opcodes plus a two Dword table entry. The upper 32 bits of the address are copied from the [Static Block Move Selector \(SBMS\)](#) when performing data transfers during block move operations. The SBMS register must be loaded manually.

If the Enable 64-bit Table Indirect Block Move (EN64TIBMV) bit is set and the 64-bit Table Indirect Index Mode (64TIMOD) bit is cleared, bits [28:24] of the first Dword of the table entry (where the byte count is located) select one of the 16 scratch registers or any of the six 64-bit selector registers as a selector for the upper 32-bit address. Please see the Table Indirect Index mode mapping table for a breakdown of index values and the corresponding registers selected. The selected address is automatically loaded into the [DMA Next Address 64 \(DNAD64\)](#) register.

Note: If EN64TIBMV is set and 64TIMOD is set, bits [31:24] of the first Dword of the table entry (where the byte count is located) are loaded directly into [DMA Next Address 64 \(DNAD64\)](#) to provide a 40-bit address.

The format for the table indirect entries for each mode is shown below. The table for Table Indirect block moves upper 32 bit address locations summarizes the available modes for table indirect block moves.

Index Mode 0 (64TIMOD clear) table entry format:

31	29 28	24 23	16 15	8 7	0
R	Sel Index	Byte Count			
Source/Destination Address [31:0]					
x x x	x x x x x	x x x x x x x x	x x x x x x x x	x x x x x x x x	x x x x x x x x

Index Mode 1 (64TIMOD set) table entry format:

31	24	16 15	8 7	0
Src/Dest Addr [39:32]		Byte Count		
Source/Destination Address [31:0]				
x x x x x x x x	x x x x x x x x	x x x x x x x x	x x x x x x x x	x x x x x x x x

Table Indirect block moves upper 32 bit address locations:

EN64TIBMV	64TIMOD	Upper 32-bit Data Address Comes From
0	0	SBMS
0	1	SBMS
1	0	ScratchC–J, MMWS, MMRS, SFS, DRS, SBMS, DBMS
1	1	1st Table Entry Dword bits [31:24] (40-bit addressing only)

Table Indirect Index mode mapping:

Index Value	Selector Used
0x00	Scratch C
0x01	Scratch D
0x02	Scratch E
0x03	Scratch F
0x04	Scratch G
0x05	Scratch H
0x06	Scratch I
0x07	Scratch J
0x08	Scratch K
0x09	Scratch L
0x0A	Scratch M
0x0B	Scratch N
0x0C	Scratch O
0x0D	Scratch P
0x0E	Scratch Q
0x0F	Scratch R
0x10	MMRS
0x11	MMWS
0x12	SFS
0x13	DRS
0x14	SBMS
0x15	SBMS
0x16–0x1F	Illegal (Results in an IID interrupt)

OPC

Opcode

27

This 1-bit field defines the instruction to execute as a block move (MOVE).

Target Mode

OPC	Instruction Defined
0	MOVE/MOVE64
1	CHMOV/CHMOV64

The SYM53C1010-33 verifies that it is connected to the SCSI bus as a target before executing this instruction.

The SYM53C1010-33 asserts the SCSI phase signals (SMSG/, SC_D/, and SI_O/) as defined by the Phase Field bits in the instruction.

If the instruction is for the command phase, the SYM53C1010-33 receives the first command byte and decodes its SCSI Group Code.

- If the SCSI Group Code is either Group 0, Group 1, Group 2, or Group 5, then the SYM53C1010-33 overwrites the [DMA Byte Counter \(DBC\)](#) register with the length of the Command Descriptor Block: 6, 10, or 12 bytes.
- If the Vendor Unique Enhancement 0 (VUE0) bit ([SCSI Control Two \(SCNTL2\)](#), bit 1) is cleared and the SCSI group code is a vendor unique code, the SYM53C1010-33 overwrites the [DMA Byte Counter \(DBC\)](#) register with the length of the Command Descriptor Block: 6, 10, or 12 bytes. If the VUE0 bit is set, the SYM53C1010-33 receives the number of bytes in the byte count regardless of the group code.
- If any other Group Code is received, the [DMA Byte Counter \(DBC\)](#) register is not modified and the SYM53C1010-33 requests the number of bytes specified in the [DMA Byte Counter \(DBC\)](#) register. If the DBC register contains 0x000000, an illegal instruction interrupt is generated.

The SYM53C1010-33 transfers the number of bytes specified in the [DMA Byte Counter \(DBC\)](#) register starting at the address specified in the [DMA Next Address \(DNAD\)](#) register. If the Opcode bit is set and a data transfer ends on an odd byte boundary, the SYM53C1010-33 stores the last byte in the [SCSI Wide Residue \(SWIDE\)](#) register during a receive operation. This byte is combined with the first byte from the subsequent transfer so that a wide transfer can complete.

If the SATN/ signal is asserted by the initiator or a parity error occurred during the transfer, it is possible to halt the transfer and generate an interrupt. The Disable Halt on Parity Error or ATN bit in the [SCSI Control One \(SCNTL1\)](#) register controls whether the SYM53C1010-33 halts on

these conditions immediately, or waits until completion of the current Move.

Initiator Mode

OPC	Instruction Defined
0	CHMOV/CHMOV64
1	MOVE/MOVE64

The SYM53C1010-33 verifies that it is connected to the SCSI bus as an initiator before executing this instruction.

The SYM53C1010-33 waits for an unserviced phase to occur. An unserviced phase is defined as any phase (with SREQ/ asserted) for which the SYM53C1010-33 has not yet transferred data by responding with a SACK/.

The SYM53C1010-33 compares the SCSI phase bits in the [DMA Command \(DCMD\)](#) register with the latched SCSI phase lines stored in the [SCSI Status One \(SSTAT1\)](#) register. These phase lines are latched when SREQ/ is asserted.

If the SCSI phase bits match the value stored in the [SCSI Status One \(SSTAT1\)](#) register, the SYM53C1010-33 transfers the number of bytes specified in the [DMA Byte Counter \(DBC\)](#) register starting at the address pointed to by the [DMA Next Address \(DNAD\)](#) register. If the opcode bit is cleared and a data transfer ends on an odd byte boundary, the SYM53C1010-33 stores the last byte in the [SCSI Wide Residue \(SWIDE\)](#) register during a receive operation, or in the [SCSI Output Data Latch \(SODL\)](#) register during a send operation. This byte is combined with the first byte from the subsequent transfer so that a wide transfer can complete.

If the SCSI phase bits do not match the value stored in the [SCSI Status One \(SSTAT1\)](#) register, the SYM53C1010-33 generates a phase mismatch interrupt and the instruction is not executed.

During a Message-Out phase, after the SYM53C1010-33 has performed a select with Attention (or SATN/ is manually asserted with a Set ATN instruction), the SYM53C1010-33 deasserts SATN/ during the final SREQ/SACK/ handshake.

When the SYM53C1010-33 is performing a block move for Message-In phase, it does not deassert the SACK/ signal for the last SREQ/SACK/ handshake. Clear the SACK/ signal using the Clear SACK I/O instruction.

SCSIP[2:0] SCSI Phase [26:24]

This field defines the desired SCSI information transfer phase. When the SYM53C1010-33 operates in the initiator mode, these bits are compared with the latched SCSI phase bits in the [SCSI Status One \(SSTAT1\)](#) register. When the SYM53C1010-33 operates in the target mode, it asserts the phase defined in this field. The following table describes the possible combinations and the corresponding SCSI phase.

MSG	C_D	I_O	SCSI Phase
0	0	0	ST Data-Out
0	0	1	ST Data-In
0	1	0	Command
0	1	1	Status
1	0	0	DT Data-Out
1	0	1	DT Data-In
1	1	0	Message-Out
1	1	1	Message-In

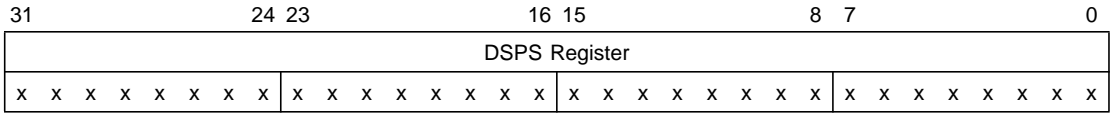
TC[23:0] Transfer Counter [23:0]

This 24-bit field specifies the number of data bytes to be moved between the SYM53C1010-33 and system memory. The field is stored in the [DMA Byte Counter \(DBC\)](#) register. When the SYM53C1010-33 transfers data to/from memory, the DBC register is decremented by the number of bytes transferred. In addition, the [DMA Next Address \(DNAD\)](#) register is incremented by the number of bytes transferred. This process is repeated until the DBC register is decremented to zero. At this time, the SYM53C1010-33 fetches the next instruction.

If bit 28 is set, indicating table indirect addressing, this field is not used. The byte count is instead fetched from a table pointed to by the [Data Structure Address \(DSA\)](#) register.

5.2.2 Second Dword

Figure 5.3 Block Move Instruction - Second Dword



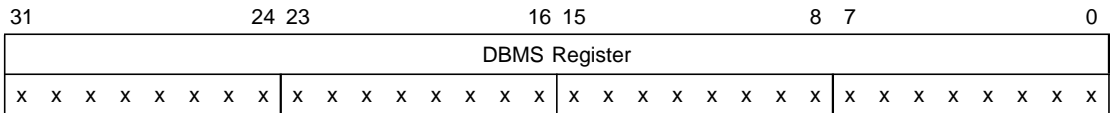
Start Address **[31:0]**

This 32-bit field specifies the starting address of the data to move to/from memory. This field is copied to the [DMA Next Address \(DNAD\)](#) register. When the SYM53C1010-33 transfers data to or from memory, the DNAD register is incremented by the number of bytes transferred.

When bit 29 is set, indicating indirect addressing, this address is a pointer to an address in memory that points to the data location. When bit 28 is set, indicating table indirect addressing, the value in this field is an offset into a table pointed to by the [Data Structure Address \(DSA\)](#). The table entry contains byte count and address information.

5.2.3 Third Dword

Figure 5.4 Block Move Instruction - Third Dword



Start Address **[63:32]**

This 32-bit field specifies the upper Dword of a 64-bit starting address of data to move to/from memory. This field is copied to the [Dynamic Block Move Selector \(DBMS\)](#) register. The EN64DBMV bit in the [Chip Control One \(CCNTL1\)](#) register must be set for this Dword to be fetched.

5.3 I/O Instructions

This section contains information about the I/O Instruction Register. It is divided into First Dword and Second Dword.

5.3.1 First Dword

Figure 5.5 First 32-bit Word of the I/O Instruction

31	30	29	27	26	25	24	23	20	19	16	15	11	10	9	8	7	6	5	4	3	2	0									
DCMD Register							DBC Register																								
IT[1:0]	OPC[2:0]			RA	TI	Sel	R				ENDID[3:0]			R		CA	TM	R	A	R	ATN	R									
0	1	x	x	x	x	x	x	0	0	0	0	x	x	x	x	0	0	0	0	0	x	x	0	0	x	0	0	x	0	0	0

IT[1:0] **Instruction Type - I/O Instruction** **[31:30]**

OPC[2:0] **Opcode** **[29:27]**

The following Opcode bits have different meanings, depending on whether the SYM53C1010-33 is operating in the initiator or target mode. Opcode selections 0b101–0b111 are considered Read/Write instructions, and are described in [Section 5.4, “Read/Write Instructions”](#).

Target Mode

OPC2	OPC1	OPC0	Instruction Defined
0	0	0	Reselect
0	0	1	Disconnect
0	1	0	Wait Select
0	1	1	Set
1	0	0	Clear

Reselect Instruction

The SYM53C1010-33 arbitrates for the SCSI bus by asserting the SCSI ID stored in the [SCSI Chip ID \(SCID\)](#) register. If it loses arbitration, it tries again during the next available arbitration cycle without reporting any lost arbitration status.

If the SYM53C1010-33 wins arbitration, it attempts to reselect the SCSI device whose ID is defined in the

destination ID field of the instruction. Once the SYM53C1010-33 wins arbitration, it fetches the next instruction from the address pointed to by the [DMA SCRIPTS Pointer \(DSP\)](#) register. This way the SCRIPTS can move on to the next instruction before the reselection completes. It continues executing SCRIPTS until a SCRIPT that requires a response from the initiator is encountered.

If the SYM53C1010-33 is selected or reselected before winning arbitration, it fetches the next instruction from the address pointed to by the 32-bit jump address field stored in the [DMA Next Address \(DNAD\)](#) register. Manually set the SYM53C1010-33 to the initiator mode if it is reselected, or to the target mode if it is selected.

Disconnect Instruction

The SYM53C1010-33 disconnects from the SCSI bus by deasserting all SCSI signal outputs.

Wait Select Instruction

If the SYM53C1010-33 is selected, it fetches the next instruction from the address pointed to by the [DMA SCRIPTS Pointer \(DSP\)](#) register.

If reselected, the SYM53C1010-33 fetches the next instruction from the address pointed to by the 32-bit jump address field stored in the [DMA Next Address \(DNAD\)](#) register. Manually set the SYM53C1010-33 to the initiator mode when it is reselected.

If the CPU sets the SIGP bit in the [Interrupt Status Zero \(ISTAT0\)](#) register, the SYM53C1010-33 aborts the Wait Select instruction and fetches the next instruction from the address pointed to by the 32-bit jump address field stored in the [DMA Next Address \(DNAD\)](#) register.

Set Instruction

When the SACK/ or SATN/ bits are set, the corresponding bits in the [SCSI Output Control Latch \(SOCL\)](#) register are set. Do not set SACK/ or SATN/ except for testing purposes. When the target bit is set, the corresponding bit in the [SCSI Control Zero \(SCNTL0\)](#) register is also set. When the carry bit is set, the corresponding bit in the Arithmetic Logic Unit (ALU) is set.

Note: None of the signals are set on the SCSI bus in target mode.

Clear Instruction

When the SACK/ or SATN/ bits are cleared, the corresponding bits are cleared in the [SCSI Output Control Latch \(SOCL\)](#) register. Do not set SACK/ or SATN/ except for testing purposes. When the target bit is cleared, the corresponding bit in the [SCSI Control Zero \(SCNTL0\)](#) register is cleared. When the carry bit is cleared, the corresponding bit in the ALU is cleared.

Note: None of the signals are cleared on the SCSI bus in the target mode.

Initiator Mode

OPC2	OPC1	OPC0	Instruction Defined
0	0	0	Select
0	0	1	Wait Disconnect
0	1	0	Wait Reselect
0	1	1	Set
1	0	0	Clear

Select Instruction

The SYM53C1010-33 arbitrates for the SCSI bus by asserting the SCSI ID stored in the [SCSI Chip ID \(SCID\)](#) register. If it loses arbitration, it tries again during the next available arbitration cycle without reporting any lost arbitration status.

If the SYM53C1010-33 wins arbitration, it attempts to select the SCSI device whose ID is defined in the destination ID field of the instruction. Once the SYM53C1010-33 wins arbitration, it fetches the next instruction from the address pointed to by the [DMA SCRIPTS Pointer \(DSP\)](#) register. This way the SCRIPTS can move to the next instruction before the selection completes. It continues executing SCRIPTS until a SCRIPT that requires a response from the target is encountered.

If the SYM53C1010-33 is selected or reselected before winning arbitration, it fetches the next instruction from the address pointed to by the 32-bit jump address field stored

in the [DMA Next Address \(DNAD\)](#) register. Manually set the SYM53C1010-33 to the initiator mode if it is reselected, or to the target mode if it is selected.

If the Select with SATN/ field is set, the SATN/ signal is asserted during the selection phase.

Wait Disconnect Instruction

The SYM53C1010-33 waits for the target to perform a “legal” disconnect from the SCSI bus. A “legal” disconnect occurs when SBSY/ and SSEL/ are inactive for a minimum of one Bus Free delay (400 ns), after the SYM53C1010-33 receives a Disconnect Message or a Command Complete Message.

Wait Reselect Instruction

If the SYM53C1010-33 is selected before being reselected, it fetches the next instruction from the address pointed to by the 32-bit jump address field stored in the [DMA Next Address \(DNAD\)](#) register. Manually set the SYM53C1010-33 to the target mode when it is selected.

If the SYM53C1010-33 is reselected, it fetches the next instruction from the address pointed to by the [DMA SCRIPTS Pointer \(DSP\)](#) register.

If the CPU sets the SIGP bit in the [Interrupt Status Zero \(ISTAT0\)](#) register, the SYM53C1010-33 aborts the Wait Reselect instruction and fetches the next instruction from the address pointed to by the 32-bit jump address field stored in the [DMA Next Address \(DNAD\)](#) register.

Set Instruction

When the SACK/ or SATN/ bits are set, the corresponding bits in the [SCSI Output Control Latch \(SOCL\)](#) register are set. When the target bit is set, the corresponding bit in the [SCSI Control Zero \(SCNTL0\)](#) register is also set. When the carry bit is set, the corresponding bit in the ALU is set.

Clear Instruction

When the SACK/ or SATN/ bits are cleared, the corresponding bits are cleared in the [SCSI Output Control Latch \(SOCL\)](#) register. When the target bit is cleared, the corresponding bit in the [SCSI Control Zero](#)

(SCNTL0) register is cleared. When the carry bit is cleared, the corresponding bit in the ALU is cleared.

RA **Relative Addressing Mode** **26**

When this bit is set, the 24-bit signed value in the **DMA Next Address (DNAD)** register is used as a relative displacement from the current **DMA SCRIPTS Pointer (DSP)** address. Use this bit only in conjunction with the Select, Reselect, Wait Select, and Wait Reselect instructions. The Select and Reselect instructions can contain an absolute alternate jump address or a relative transfer address.

TI **Table Indirect Mode** **25**

When this bit is set, the 24-bit signed value in the **DMA Byte Counter (DBC)** register is added to the value in the **Data Structure Address (DSA)** register, and used as an offset relative to the value in the Data Structure Address (DSA) register. The **SCSI Control Three (SCNTL3)** value, SCSI ID, synchronous offset and synchronous period are loaded from this address. Prior to the start of an I/O, load the **Data Structure Address (DSA)** with the base address of the I/O data structure. Any address on a Dword boundary is allowed. After a Table Indirect opcode is fetched, the **Data Structure Address (DSA)** is added to the 24-bit signed offset value from the opcode to generate the address of the required data. Both positive and negative offsets are allowed. A subsequent fetch from that address brings the data values into the chip.

SCRIPTS can directly execute operating system I/O data structures, saving time at the beginning of an I/O operation. The I/O data structure can begin on any Dword boundary and may cross system segment boundaries. There are two restrictions on the placement of data in system memory:

- The I/O data structure must lie within the 8 Mbytes above or below the base address.
- An I/O command structure must have all four bytes contiguous in system memory, as shown below. The offset/period bits are ordered as in the **SCSI Transfer (SXFER)** register. The configuration bits are ordered as in the **SCSI Control Three (SCNTL3)** register.

Config	ID	Offset/period	00
--------	----	---------------	----

Use this bit only in conjunction with the Select, Reselect, Wait Select, and Wait Reselect instructions. It is allowable to set bits 25 and 26 individually or in combination:

	Bit 25	Bit 26
Direct	0	0
Table Indirect	0	1
Relative	1	0
Table Relative	1	1

Direct

Uses the device ID and physical address in the instruction.

Command	ID	Not Used	Not Used
Absolute Alternate Address			

Table Indirect

Uses the physical jump address, but fetches data using the table indirect method.

Command	Table Offset
Absolute Alternate Address	

Relative

Uses the device ID in the instruction, but treats the alternate address as a relative jump.

Command	ID	Not Used	Not Used
Absolute Jump Offset			

Table Relative

Treats the alternate jump address as a relative jump and fetches the device ID, synchronous offset, and synchronous period indirectly. The value in bits [23:0] of the first four bytes of the SCRIPTS instruction is added

to the data structure base address to form the fetch address.

	Command	Table Offset
	Alternate Jump Offset	
Sel	Select with ATN/	24
	This bit specifies whether SATN/ is asserted during the selection phase when the SYM53C1010-33 is executing a Select instruction. When operating in the initiator mode, set this bit for the Select instruction. If this bit is set on any other I/O instruction, an illegal instruction interrupt is generated.	
R	Reserved	[23:20]
ENDID[3:0]	Encoded SCSI Destination ID	[19:16]
	This 4-bit field specifies the destination SCSI ID for an I/O instruction.	
R	Reserved	[15:11]
CA	Set/Clear Carry	10
	This bit is used in conjunction with a Set or Clear instruction to set or clear the Carry bit. Setting this bit with a Set instruction asserts the Carry bit in the ALU. Clearing this bit with a Clear instruction deasserts the Carry bit in the ALU.	
TM	Set/Clear Target Mode	9
	This bit is used in conjunction with a Set or Clear instruction to set or clear the target mode. Setting this bit with a Set instruction configures the SYM53C1010-33 as a target device (this sets bit 0 of the SCSI Control Zero (SCNTL0) register). Clearing this bit with a Clear instruction configures the SYM53C1010-33 as an initiator device (this clears bit 0 of the SCNTL0 register).	

R	Reserved	[8:7]
A	Set/Clear SACK/	6
R	Reserved	[5:4]
ATN	Set/Clear SATN/	3

These two bits are used in conjunction with a Set or Clear instruction to assert or deassert the corresponding SCSI control signal. Bit 6 controls the SCSI SACK/ signal. Bit 3 controls the SCSI SATN/ signal.

The Set instruction is used to assert SACK/ and/or SATN/ on the SCSI bus. The Clear instruction is used to deassert SACK/ and/or SATN/ on the SCSI bus. The corresponding bit in the [SCSI Output Control Latch \(SOCL\)](#) register will be set or cleared depending on the instruction used.

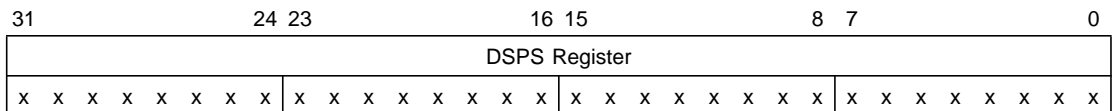
Since SACK/ and SATN/ are initiator signals, they are not asserted on the SCSI bus.

The Set/Clear SCSI ACK/, ATN/ instruction is used after message phase Block Move operations to give the initiator the opportunity to assert attention before acknowledging the last message byte. For example, if the initiator wishes to reject a message, it issues an Assert SCSI ATN instruction before a Clear SCSI ACK instruction.

R	Reserved	[2:0]
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5.3.2 Second Dword

Figure 5.6 Second 32-bit Word of the I/O Instruction



SA	Start Address	[31:0]
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This 32-bit field contains the memory address to fetch the next instruction if the selection or reselection fails.

If relative or table relative addressing is used, this value is a 24-bit signed offset relative to the current [DMA SCRIPTS Pointer \(DSP\)](#) register value.

5.4 Read/Write Instructions

The Read/Write instruction supports addition, subtraction, and comparison of two separate values within the chip. It performs the desired operation on the specified register and the [SCSI First Byte Received \(SFBR\)](#) register and stores the result back to the specified register or to the SFBR. If the COM bit ([DMA Control \(DCNTL\)](#), bit 0) is cleared, Read/Write instructions cannot be used.

5.4.1 First Dword

Figure 5.7 Read/Write Instruction - First Dword

31	30	29	27	26	24	23	22	16	15	8	7	0													
DCMD Register						DBC Register																			
IT[1:0]		OPC[2:0]			O[2:0]		D8	A[6:0]				IMMD			R - Must be 0										
0	1	x	x	x	x	x	x	x	x	x	x	x	x	x	x	x	x	0	0	0	0	0	0	0	0

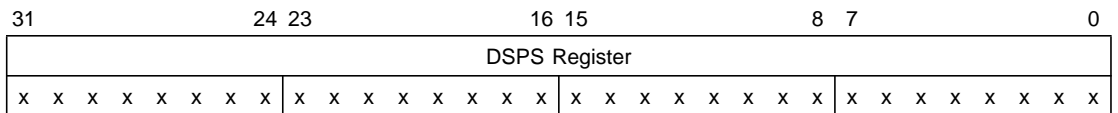
- IT[1:0]** **Instruction Type - Read/Write Instruction** **[31:30]**
 The Read/Write instruction uses operator bits [26:24] in conjunction with the opcode bits to determine which instruction is currently selected.
- OPC[2:0]** **Opcode** **[29:27]**
 These bits determine if the instruction is a Read/Write or an I/O instruction. Opcodes 0b000 through 0b100 are considered I/O instructions.
- O[2:0]** **Operator** **[26:24]**
 The Operator bits are used in conjunction with the opcode bits to determine which instruction is currently selected. Refer to [Table 5.1](#) for field definitions.
- D8** **Use data8/SFBR** **23**
 When this bit is set, [SCSI First Byte Received \(SFBR\)](#) is used, instead of the data8 value, during a Read-Modify-Write instruction (see [Table 5.1](#)). This allows the user to add two register values.
- A[6:0]** **Register Address - A[6:0]** **[22:16]**
 It is possible to change register values from SCRIPTS in read-modify-write cycles or move to/from [SCSI First Byte](#)

Received (SFBR) cycles. A[6:0] selects an 8-bit source/destination register within the SYM53C1010-33.

IMMD	Immediate Data	[15:8]
	This 8-bit value is used as a second operand in logical and arithmetic functions.	
A7	Upper Register Address Line (A7)	7
	This bit is used to access registers 0x80–0xFF.	
R	Reserved	[6:0]

5.4.2 Second Dword

Figure 5.8 Read/Write Instruction - Second Dword



DA	Destination Address	[31:0]
	This field contains the 32-bit destination address where the data is to move.	

5.4.3 Read-Modify-Write Cycles

During these cycles the register is read, the selected operation is performed, and the result is written back to the source register.

The Add operation is used to increment or decrement register values (or memory values if used in conjunction with a Memory-to-Register Move operation) for use as loop counters.

Subtraction is not available when [SCSI First Byte Received \(SFBR\)](#) is used instead of data8 in the instruction syntax. To subtract one value from another when using SFBR, first XOR the value to subtract (subtrahend) with 0xFF, and add 1 to the resulting value. This creates the 2's complement of the subtrahend. The two values are then added to obtain the difference.

5.4.4 Move To/From SFBR Cycles

All operations are read-modify-writes. However, two registers are involved, one of which is always the [SCSI First Byte Received \(SFBR\)](#). The possible functions of this instruction are:

- Write one byte (value contained within the SCRIPTS instruction) into any chip register.
- Move to/from the [SCSI First Byte Received \(SFBR\)](#) from/to any other register.
- Alter the value of a register with AND, OR, ADD, XOR, SHIFT LEFT, or SHIFT RIGHT operators.
- After moving values to the [SCSI First Byte Received \(SFBR\)](#), the compare and jump, call, or similar instructions are used to check the value.
- A Move-to-SFBR followed by a Move-from-SFBR is used to perform a register to register move.

Table 5.1 Read/Write Instructions¹

Operator	Opcode 111 Read Modify Write	Opcode 110 Move to SFBR	Opcode 101 Move from SFBR
000	Move data into register. Syntax: "Move data8 to RegA"	Move data into SCSI First Byte Received (SFBR) register. Syntax: "Move data8 to SFBR"	Move data into register. Syntax: "Move data8 to RegA"
001 ²	Shift register one bit to the left and place the result in the same register. Syntax: "Move RegA SHL RegA"	Shift register one bit to the left and place the result in the SCSI First Byte Received (SFBR) register. Syntax: "Move RegA SHL SFBR"	Shift the SFBR register one bit to the left and place the result in the register. Syntax: "Move SFBR SHL RegA"
010	OR data with register and place the result in the same register. Syntax: "Move RegA data8 to RegA"	OR data with register and place the result in the SCSI First Byte Received (SFBR) register. Syntax: "Move RegA data8 to SFBR"	OR data with SFBR and place the result in the register. Syntax: "Move SFBR data8 to RegA"

Table 5.1 Read/Write Instructions¹ (Cont.)

Operator	Opcode 111 Read Modify Write	Opcode 110 Move to SFBR	Opcode 101 Move from SFBR
011	XOR data with register and place the result in the same register. Syntax: "Move RegA XOR data8 to RegA"	XOR data with register and place the result in the SCSI First Byte Received (SFBR) register. Syntax: "Move RegA XOR data8 to SFBR"	XOR data with SFBR and place the result in the register. Syntax: "Move SFBR XOR data8 to RegA"
100	AND data with register and place the result in the same register. Syntax: "Move RegA & data8 to RegA"	AND data with register and place the result in the SCSI First Byte Received (SFBR) register. Syntax: "Move RegA & data8 to SFBR"	AND data with SFBR and place the result in the register. Syntax: "Move SFBR & data8 to RegA"
101 ²	Shift register one bit to the right and place the result in the same register. Syntax: "Move RegA SHR RegA"	Shift register one bit to the right and place the result in the SCSI First Byte Received (SFBR) register. Syntax: "Move RegA SHR SFBR"	Shift the SFBR register one bit to the right and place the result in the register. Syntax: "Move SFBR SHR RegA"
110	Add data to register without carry and place the result in the same register. Syntax: "Move RegA + data8 to RegA"	Add data to register without carry and place the result in the SCSI First Byte Received (SFBR) register. Syntax: "Move RegA + data8 to SFBR"	Add data to SFBR without carry and place the result in the register. Syntax: "Move SFBR + data8 to RegA"
111	Add data to register with carry and place the result in the same register. Syntax: "Move RegA + data8 to RegA with carry"	Add data to register with carry and place the result in the SCSI First Byte Received (SFBR) register. Syntax: "Move RegA + data8 to SFBR with carry"	Add data to SFBR with carry and place the result in the register. Syntax: "Move SFBR + data8 to RegA with carry"

1. Substitute the desired register name or address for "RegA" in the syntax examples. data8 indicates eight bits of data.
Use SFBR instead of data8 to add two register values.
2. Data is shifted through the Carry bit and the Carry bit is shifted into the data byte.

contents of the [DMA SCRIPTS Pointer Save \(DSPS\)](#) register. The DSP register now contains the address of the next instruction.

If the comparisons are false, the SYM53C1010-33 fetches the next instruction from the address pointed to by the [DMA SCRIPTS Pointer \(DSP\)](#) register, leaving the instruction pointer unchanged.

When the JUMP64 instruction is used, a third Dword is fetched and loaded into the [SCRIPT Fetch Selector \(SFS\)](#) register. Bit 22 indicates whether the jump is to a 32-bit address (0) or a 64-bit address (1). All combinations of jumps are still valid for JUMP64.

Call Instruction

The SYM53C1010-33 can do a true/false comparison of the ALU carry bit, or compare the phase and/or data as defined by the Phase Compare, Data Compare, and True/False bit fields. If the comparisons are true, it loads the [DMA SCRIPTS Pointer \(DSP\)](#) register with the contents of the [DMA SCRIPTS Pointer Save \(DSPS\)](#) register and that address value becomes the address of the next instruction.

When the SYM53C1010-33 executes a Call instruction, the instruction pointer contained in the [DMA SCRIPTS Pointer \(DSP\)](#) register is stored in the [Temporary \(TEMP\)](#) register. Since the TEMP register is not a stack and can only hold one Dword, nested call instructions are not allowed.

If the comparisons are false, the SYM53C1010-33 fetches the next instruction from the address pointed to by the [DMA SCRIPTS Pointer \(DSP\)](#) register and the instruction pointer is not modified.

Return Instruction

The SYM53C1010-33 can do a true/false comparison of the ALU carry bit, or compare the phase and/or data as defined by the Phase Compare, Data Compare, and True/False bit fields. If the comparisons are true, it loads the [DMA SCRIPTS Pointer \(DSP\)](#) register with the contents of the [DMA SCRIPTS Pointer Save \(DSPS\)](#) register. That address value becomes the address of the next instruction.

When a Return instruction is executed, the value stored in the [Temporary \(TEMP\)](#) register is returned to the [DMA SCRIPTS Pointer \(DSP\)](#) register. The SYM53C1010-33 does not check to see whether the Call instruction has already been executed. It does not generate an interrupt if a Return instruction is executed without previously executing a Call instruction.

If the comparisons are false, the SYM53C1010-33 fetches the next instruction from the address pointed to by the [DMA SCRIPTS Pointer \(DSP\)](#) register and the instruction pointer is not modified.

Interrupt Instruction

The SYM53C1010-33 can do a true/false comparison of the ALU carry bit, or compare the phase and/or data as defined by the Phase Compare, Data Compare, and True/False bit fields. If the comparisons are true, the SYM53C1010-33 generates an interrupt by asserting the IRQ/ signal.

The 32-bit address field stored in the [DMA SCRIPTS Pointer Save \(DSPS\)](#) register can contain a unique interrupt service vector. When servicing the interrupt, this unique status code allows the ISR to quickly identify the point at which the interrupt occurred.

The SYM53C1010-33 halts and the [DMA SCRIPTS Pointer \(DSP\)](#) register must be written to before starting any further operation.

Interrupt-on-the-Fly Instruction

The SYM53C1010-33 can do a true/false comparison of the ALU carry bit or compare the phase and/or data as defined by the Phase Compare, Data Compare, and True/False bit fields. If the comparisons are true, and the Interrupt-on-the-Fly bit [Interrupt Status Zero \(ISTAT0\)](#), bit 2) is set, the SYM53C1010-33 asserts the Interrupt-on-the-Fly bit.

SCSIP[2:0]

SCSI Phase

[26:24]

This 3-bit field corresponds to the three SCSI bus phase signals that are compared with the phase lines latched when SREQ/ is asserted. Comparisons can be performed to determine the SCSI phase actually being driven on the SCSI bus. The following table describes the possible

combinations and their corresponding SCSI phase. These bits are only valid when the SYM53C1010-33 is operating in the initiator mode. Clear these bits when the SYM53C1010-33 is operating in the target mode.

MSG	C/D	I/O	SCSI Phase
0	0	0	ST Data-Out
0	0	1	ST Data-In
0	1	0	Command
0	1	1	Status
1	0	0	DT Data-Out
1	0	1	DT Data-In
1	1	0	Message-Out
1	1	1	Message-In

RA

Relative Addressing Mode

23

When this bit is set, the 24-bit signed value in the [DMA SCRIPTS Pointer Save \(DPS\)](#) register is used as a relative offset from the current [DMA SCRIPTS Pointer \(DSP\)](#) address, which is pointing to the next instruction and not the one currently executing. The relative mode does not apply to Return and Interrupt SCRIPTS.

Jump/Call an Absolute Address

Start execution at the new absolute address.

Command	Condition Codes
Absolute Alternate Address	

Jump/Call a Relative Address

Start execution at the current address plus (or minus) the relative offset.

Command	Condition Codes
Don't Care	Alternate Jump Offset

The SCRIPTS program counter is a 32-bit value pointing to the SCRIPTS currently under execution by the SYM53C1010-33. The next address is formed by adding the 32-bit program counter to the 24-bit signed value of the last 24 bits of the Jump or Call instruction. Because

it is signed (2's complement), the jump can be forward or backward.

A relative transfer can be to any address within a 16 Mbyte segment. The program counter is combined with the 24-bit signed offset (using addition or subtraction) to form the new execution address.

SCRIPTS programs may contain a mixture of direct jumps and relative jumps to provide maximum versatility when writing SCRIPTS. For example, major sections of code can be accessed with far calls using the 32-bit physical address, then local labels can be called using relative transfers. If a SCRIPT is written using only relative transfers it does not require any run time alteration of physical addresses, and can be stored in and executed from a PROM.

J	32/64 Bit Jump	22
	When this bit is cleared, the jump address is 32 bits wide. When this bit is set, the jump address is 64 bits wide.	
CT	Carry Test	21
	When this bit is set, decisions based on the ALU carry bit can be made. True/False comparisons are legal, but Data Compare and Phase Compare are illegal.	
IF	Interrupt-on-the-Fly	20
	When this bit is set, the interrupt instruction does not halt the SCRIPTS processor. Once the interrupt occurs, the Interrupt-on-the-Fly bit (Interrupt Status Zero (ISTAT0) , bit 2) is asserted.	
TF	Jump If True/False	19
	This bit determines whether the SYM53C1010-33 branches when a comparison is true or when a comparison is false. This bit applies to phase compares, data compares, and carry tests. If both the Phase Compare and Data Compare bits are set, then both compares must be true to branch on a true condition. Both compares must be false to branch on a false condition.	

Bit 19	Result of Compare	Action
0	False	Jump Taken
0	True	No Jump
1	False	No Jump
1	True	Jump Taken

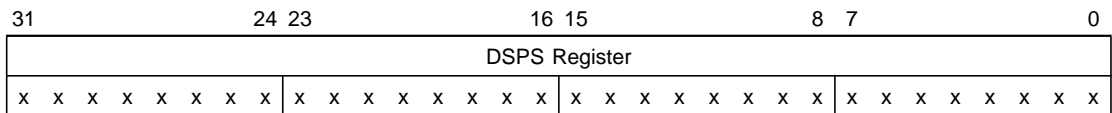
- CD Compare Data 18**
When this bit is set, the first byte received from the SCSI data bus (contained in the [SCSI First Byte Received \(SFBR\)](#) register) is compared with the Data to be Compared Field in the Transfer Control instruction. The Wait for Valid Phase bit controls when this compare occurs. The Jump if True/False bit determines the condition (true or false) to branch on.
- CP Compare Phase 17**
When the SYM53C1010-33 is in the initiator mode, this bit controls phase compare operations. When this bit is set, the SCSI phase signals (latched by SREQ/) are compared to the Phase Field in the Transfer Control instruction. If they match, the comparison is true. The Wait for Valid Phase bit controls when the compare occurs. When the SYM53C1010-33 is operating in the target mode and this bit is set it tests for an active SCSI SATN/ signal.
- VP Wait For Valid Phase 16**
If the Wait for Valid Phase bit is set, the SYM53C1010-33 waits for a previously unserved phase before comparing the SCSI phase and data.
If the Wait for Valid Phase bit is cleared, the SYM53C1010-33 compares the SCSI phase and data immediately.
- MC Data Compare Mask [15:8]**
The Data Compare Mask allows a SCRIPT to test certain bits within a data byte. During the data compare, if any mask bits are set, the corresponding bit in the [SCSI First Byte Received \(SFBR\)](#) data byte is ignored. For instance, a mask of 0b01111111 and data compare value of 0b1XXXXXXX allows the SCRIPTS processor to

determine whether or not the high-order bit is set while ignoring the remaining bits.

DC **Data Compare Value** [7:0]
 This 8-bit field is the data compared against the [SCSI First Byte Received \(SFBR\)](#) register. These bits are used in conjunction with the Data Compare Mask Field to test for a particular data value. If the COM bit ([DMA Control \(DCNTL\)](#), bit 0) is cleared, the value in the SFBR register may not be stable. In this case, do not use instructions using this data compare value.

5.5.2 Second Dword

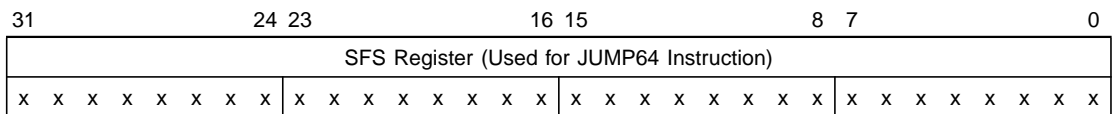
Figure 5.10 Transfer Control Instructions - Second Dword



Jump Address [31:0]
 This 32-bit field contains the address of the next instruction to fetch when a jump is taken. Once the SYM53C1010-33 fetches the instruction from the address pointed to by these 32 bits, this address is incremented by 4, loaded into the [DMA SCRIPTS Pointer \(DSP\)](#) register and becomes the current instruction pointer.

5.5.3 Third Dword

Figure 5.11 Transfer Control Instructions - Third Dword



JUMP64 Address [31:0]
 This 32-bit field contains the upper Dword of a 64-bit address of the next instruction to fetch when a JUMP64 is taken.

5.6 Memory Move Instructions

For Memory Move instructions, bits 5 and 4 (SIOM and DIOM) in the [DMA Mode \(DMODE\)](#) register determine whether the source or destination addresses reside in memory or I/O space. By setting these bits appropriately, data may be moved within memory space, within I/O space, or between the two address spaces.

The Memory Move instruction is used to copy the specified number of bytes from the source address to the destination address.

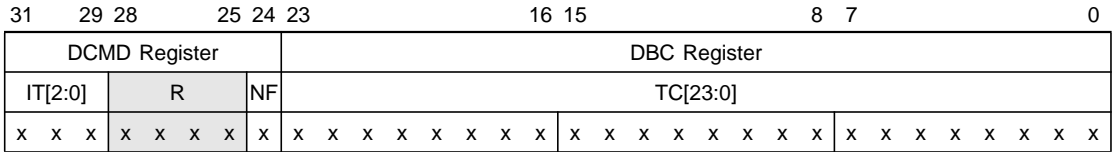
For memory moves where the data read is from the 64-bit address space, the upper Dword of the address resides in the [Memory Move Read Selector \(MMRS\)](#) register. For memory moves where the data is written to the 64-bit address space, the upper Dword of the address resides in the [Memory Move Write Selector \(MMWS\)](#) register.

Allowing the SYM53C1010-33 to perform memory moves frees the system processor for other tasks and moves data at higher speeds than available from current DMA controllers. Up to 16 Mbytes may be transferred with one instruction. There are two restrictions:

- Both the source and destination addresses must start with the same address alignment (A[1:0]) must be the same). If the source and destination are not aligned, then an illegal instruction interrupt occurs. For the PCI [Cache Line Size \(CLS\)](#) register setting to take effect, the source and destination must be the same distance from a cache line boundary.
- Indirect addresses are not allowed. A burst of data is fetched from the source address, put into the DMA FIFO and then written out to the destination address. The move continues until the byte count decrements to zero, then another SCRIPT is fetched from system memory.

The [DMA SCRIPTS Pointer Save \(DSPS\)](#) and [Data Structure Address \(DSA\)](#) registers are additional holding registers used during the Memory Move. However, the contents of the [Data Structure Address \(DSA\)](#) register are preserved.

Figure 5.12 Memory Move Instructions - First Dword



IT[2:0] Instruction Type - Memory Move [31:29]

R Reserved [28:25]

These bits are reserved and must be zero. If any of these bits are set, an illegal instruction interrupt occurs.

NF No Flush 24

When this bit is set, the SYM53C1010-33 performs a Memory Move without flushing the prefetch unit. When this bit is cleared, the Memory Move instruction automatically flushes the prefetch unit. Use the No Flush option if the source and destination are not within four instructions of the current Memory Move instruction.

Note: This bit has no effect unless the Prefetch Enable bit in the [DMA Control \(DCNTL\)](#) register is set. For information on SCRIPTS instruction prefetching, see [Chapter 2, "Functional Description"](#).

TC[23:0] Transfer Count [23:0]

The number of bytes to transfer is stored in the lower 24 bits of the first instruction word.

5.6.1 Read/Write System Memory from a SCRIPT

By using the Memory Move instruction, single or multiple register values are transferred to or from system memory.

Because the SYM53C1010-33 responds to addresses as defined in the [Base Address Register Zero \(BAR0\) \(I/O\)](#) or [Base Address Register One \(BAR1\) \(MEMORY\)](#) registers, the device can be accessed during a Memory Move operation if the source or destination address decodes to within the chip's register space. If this occurs, the register indicated by the lower seven bits of the address is taken as the data source or destination. In this way, register values are saved to system memory and

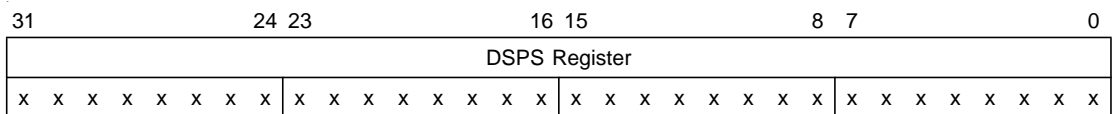
later restored, and SCRIPTS can make decisions based on data values in system memory.

The [SCSI First Byte Received \(SFBR\)](#) is not writable using the CPU, and therefore not by a Memory Move. However, it can be loaded using SCRIPTS Read/Write operations. To load the SFBR with a byte stored in system memory, first move the byte to an intermediate SYM53C1010-33 register (for example, a SCRATCH register), and then to the [SCSI First Byte Received \(SFBR\)](#).

The same address alignment restrictions apply to register access operations as to normal memory-to-memory transfers.

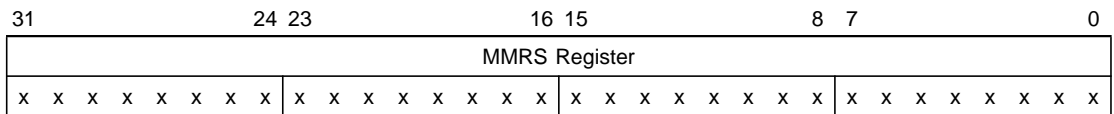
5.6.2 Second Dword

Figure 5.13 Memory Move Instructions - Second Dword



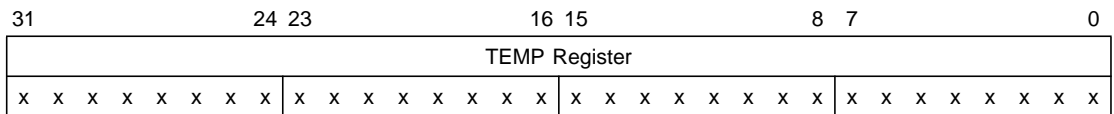
DSPS Register **[31:0]**
 These bits contain the source address of the Memory Move.

If the source address is in the 64-bit address space, the bits will be contained in the [Memory Move Read Selector \(MMRS\)](#) register.



5.6.3 Third Dword

Figure 5.14 Memory Move Instructions - Third Dword

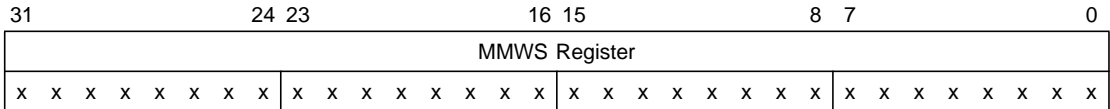


TEMP Register

[31:0]

These bits contain the destination address for the Memory Move.

If the destination address is in the 64-bit address space, the bits will be contained in the [Memory Move Write Selector \(MMWS\)](#) register.



5.7 Load and Store Instructions

The Load and Store instructions provide a more efficient way to move data from/to memory to/from an internal register in the chip without using the normal memory move instruction.

The load and store instructions are represented by two-Dword opcodes. The first Dword contains the [DMA Command \(DCMD\)](#) and [DMA Byte Counter \(DBC\)](#) register values. The second Dword contains the [DMA SCRIPTS Pointer Save \(DSPS\)](#) value. This is either the actual memory location of where to load/store, or the offset from the [Data Structure Address \(DSA\)](#), depending on the value of bit 28 (DSA Relative).

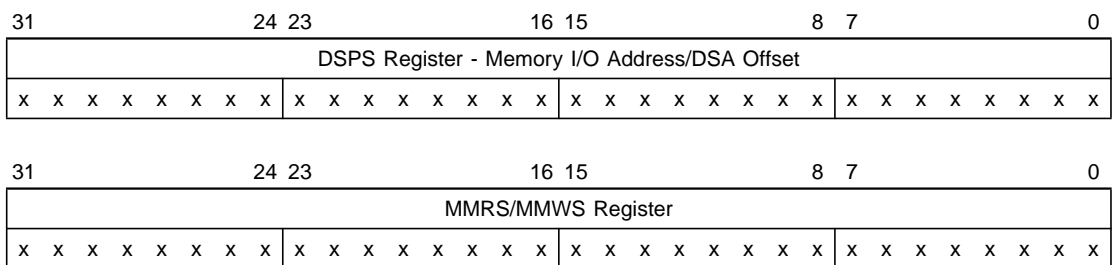
For load operations where the data is read from the 64-bit address space, the upper Dword of address resides in the [Memory Move Read Selector \(MMRS\)](#) register. For store operations where the data is written to the 64-bit address space, the upper Dword of address resides in the [Memory Move Write Selector \(MMWS\)](#) register.

A maximum of 4 bytes may be moved with these instructions. The register address and memory address must have the same byte alignment, and the count set such that it does not cross Dword boundaries. The memory address may not map back to the chip, excluding RAM and ROM. If it does, a PCI read/write cycle occurs (the data does not actually transfer to/from the chip), and the chip issues an interrupt (Illegal Instruction Detected) immediately following.

R	Reserved	[27:26]
NF	No Flush (Store instruction only) When this bit is set, the SYM53C1010-33 performs a Store without flushing the prefetch unit. When this bit is cleared, the Store instruction automatically flushes the prefetch unit. Use No Flush if the source and destination are not within four instructions of the current Store instruction. This bit has no effect on the Load instruction.	25
<u>Note:</u> This bit has no effect unless the Prefetch Enable bit in the DMA Control (DCNTL) register is set. For information on SCRIPTS instruction prefetching, see Chapter 2, "Functional Description" .		
LS	Load/Store When this bit is set, the instruction is a Load. When cleared, it is a Store.	24
A[7:0]	Register Address A[7:0] selects the register to load/store to/from within the SYM53C1010-33.	[23:16]
R	Reserved	[15:3]
BC	Byte Count This value is the number of bytes to load/store.	[2:0]

5.7.2 Second Dword

Figure 5.16 Load and Store Instructions - Second Dword



Memory I/O Address/DSA Offset **[31:0]**
This is the actual memory location of where to load/store, or the offset from the [Data Structure Address \(DSA\)](#) register value.

Chapter 6

Specifications

This chapter specifies the SYM53C1010-33 electrical and mechanical characteristics. It is divided into the following sections:

- [Section 6.1, “DC Characteristics”](#)
- [Section 6.2, “TolerANT Technology Electrical Characteristics”](#)
- [Section 6.3, “AC Characteristics”](#)
- [Section 6.4, “PCI and External Memory Interface Timing Diagrams”](#)
- [Section 6.5, “SCSI Timing Diagrams”](#)

6.1 DC Characteristics

Table 6.1 Absolute Maximum Stress Ratings

Symbol	Parameter	Min	Max ¹	Unit	Test Conditions
T _{STG}	Storage temperature	–55	150	°C	–
V _{DD}	Supply voltage	–0.5	4.5	V	–
V _{IN}	Input voltage	–0.3	5.55	V	–
V _{IN-PCI}	Input voltage PCI pins	–.5	11.0	V	–
I _{LP} ²	Latch-up current	±150	–	mA	–
T	Lead temperature	–	250	°C	< 10 seconds
ESD ³	Electrostatic discharge	–	2 K	V	MIL-STD 883C, Method 3015.7

1. Stresses beyond those listed above may cause permanent damage to the device. These are stress ratings only; functional operation of the device at these or any other conditions beyond those indicated in the Operating Conditions section of the manual is not implied.
2. –2 V < VPIN < 8 V.
3. SCSI pins only.

Table 6.2 Operating Conditions

Symbol	Parameter	Min	Max ¹	Unit	Test Conditions
V_{DD}	Supply voltage	3.13	3.47	V	–
I_{DD}	Supply current (dynamic) ²	–	800	mA	–
$I_{DD-SCSI}$	LVD Mode Supply Current (dynamic)	–	1	A	–
T_A	Operating free air	0	70	°C	–
θ_{JA}	Thermal resistance (junction to ambient air)	–	20	°C/W	–

1. Conditions that exceed the operating limits may cause the device to function incorrectly.
2. Core and analog supply only.

Table 6.3 LVD Driver SCSI Signals¹—SD[15:0], SDP[1:0], SREQ/, SACK/, SMSG/, SIO/, SCD/, SATN/, SBSY/, SSEL/, SRST/

Symbol	Parameter	Min	Max	Units	Test Conditions
$I_{O-ASSERT+}$	Source (+) current	–9.6	–14.4	mA	Asserted state
$I_{O-ASSERT-}$	Sink (–) current	9.6	14.4	mA	Asserted state
I_{O-NEG+}	Source (+) current	–6.4	–9.6	mA	Negated state
I_{O-NEG-}	Sink (–) current	6.4	9.6	mA	Negated state
I_{OZ}	3-state leakage	–	20	μ A	–

1. $V_{CM} = 0.7\text{--}1.8$ V (Common Mode, nominal ~ 1.2 V), $R_L = 0\text{--}110$ Ω , $R_{bias} = 10$ k Ω .

Figure 6.1 LVD Driver

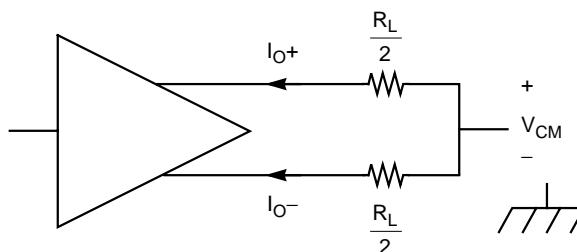


Table 6.4 LVD Receiver SCSI Signals¹—SD[15:0], SDP[1:0], SREQ/, SACK/, SMSG/, SIO/, SCD/, SATN/, SBSY/, SSEL/, SRST/

Symbol	Parameter	Min	Max	Units	Test Condition
V_I	LVD receiver voltage asserting	60	–	mV	Differential voltage
V_I	LVD receiver voltage negating	–60	–	mV	Differential voltage

1. $V_{CM} = 0.7\text{--}1.8$ V (Common Mode Voltage, nominal ~ 1.2 V.)

Figure 6.2 LVD Receiver

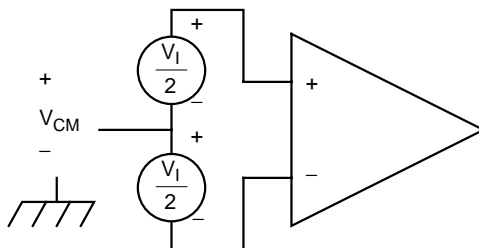


Table 6.5 A and B DIFFSENS SCSI Signals

Symbol	Parameter	Min	Max	Unit	Test Conditions
V_{IH}	HVD sense voltage	2.4	5.05	V	Note 1
V_S	LVD sense voltage	0.7	1.9	V	Note 1
V_{IL}	SE sense voltage	$V_{SS} - 0.35$	0.5	V	Note 1
I_{OZ}	3-state leakage	–10	10	μA	0 $V_{DD} = 3$ Max

1. Functional test specified V_{IH}/V_{IL} for each mode.

Table 6.6 Input Capacitance

Symbol	Parameter	Min	Max	Unit	Test Conditions
C_I	Input capacitance of input pads	–	7	pF	Guaranteed by design
C_{IO}	Input capacitance of I/O pads	–	15	pF	Guaranteed by design
C_{PCI}	Input capacitance of PCI pads	–	8	pF	Guaranteed by design
C_{LVD}	Input capacitance of LVD pads	–	8	pF	6.5 pF Pad 1.5 pF Package

Table 6.7 8 mA Bidirectional Signals—GPIO0_FETCH/, GPIO1_MASTER/, GPIO2, GPIO3, GPIO4¹

Symbol	Parameter	Min	Max	Unit	Test Conditions
V_{IH}	Input high voltage	2.0	5.55	V	–
V_{IL}	Input low voltage	–0.3	0.8	V	–
V_{OH}	Output high voltage	2.4	V_{DD}	V	–8 mA
V_{OL}	Output low voltage	V_{SS}	0.4	V	8 mA
I_{OZ}	3-state leakage	–10	10	μ A	–
I_{PULL}	Pull up current	25	–	μ A	–

1. For channels A and B (except MAD[7:0]).

Table 6.8 4 mA Bidirectional Signals—MAD[7:0]

Symbol	Parameter	Min	Max	Unit	Test Conditions
V_{IH}	Input high voltage	2.0	5.55	V	–
V_{IL}	Input low voltage	–0.3	0.8	V	–
V_{OH}	Output high voltage	2.4	V_{DD}	V	–4 mA
V_{OL}	Output low voltage	V_{SS}	0.4	V	4 mA
I_{OZ}	3-state leakage	–10	10	μ A	–
I_{PULL}	Pull down current	25	–	μ A	–

Table 6.9 4 mA Output Signals—MAS/[1:0], MCE/, MOE/_TESTOUT¹, MWE/, TDO

Symbol	Parameter	Min	Max	Unit	Test Conditions
V _{OH}	Output high voltage	2.4	V _{DD}	V	–4 mA
V _{OL}	Output low voltage	V _{SS}	0.4	V	4 mA
I _{OZ}	3-state leakage	–10	10	μA	–

1. MOE/_TESTOUT is not tested for 3-state leakage. It cannot be 3-stated.

Table 6.10 8 mA PCI Bidirectional Signals—AD[63:0], C_BE[7:0]/, FRAME/, IRDY/, TRDY/, DEVSEL/, STOP/, PERR/, PAR, PAR64, REQ64/, ACK64/

Symbol	Parameters	Min	Max	Unit	Test Conditions
V _{IH}	Input high voltage	0.5 V _{DD}	V _{DD} +0.5	V	–
V _{IL}	Input low voltage	–0.5	0.3 V _{DD}	V	–
V _{OH}	Output high voltage	0.9 V _{DD}	V _{DD}	V	–8 mA
V _{OL}	Output low voltage	V _{SS}	0.1 V _{DD}	V	8 mA
I _{OZ}	3-state leakage	–10	10	μA	–
I _{PULL-DOWN} ¹	Pull down current	25	–	μA	–

1. Pull-down text does not apply to AD[31:0] and C_BE[3:0]/.

Table 6.11 Input Signals—CLK, GNT/, IDSEL, INT_DIR, RST/, SCLK, TCK, TDI, TEST_HSC, TEST_RST/, TEST_PD, TMS

Symbol	Parameters	Min	Max	Unit	Test Conditions
V _{IH}	Input high voltage	2.0	5.55	V	–
V _{IL}	Input low voltage	–0.3	0.8	V	–
I _{IN}	3-state leakage	–10	10	μA	–
I _{PULL-UP} ¹	Pull current	25	–	μA	–

1. Pull-up text does not apply to CLK, GNT/, IDSEL, RST/, and SCLK.

Table 6.12 8 mA Output Signals—INTA, INTB, ALT_INTA, ALT_INTB, REQ/, SERR/

Symbol	Parameters	Min	Max	Unit	Test Conditions
V_{OH}	Output high voltage	$0.9 V_{DD}$	V_{DD}	V	–8 mA
V_{OL}	Output low voltage	V_{DD}	$0.1 V_{DD}$	V	8 mA
I_{OZ}	3-state leakage	–10	10	μA	–
$I_{PULL-UP}^1$	Pull current	25	–	μA	–

1. Pull-up text does not apply o REQ/, SERR/.

6.2 TolerANT Technology Electrical Characteristics

Table 6.13 TolerANT Technology Electrical Characteristics for SE SCSI Signals¹

Symbol	Parameter	Min	Max	Units	Test Conditions
V_{OH}^2	Output high voltage	2.2	3.7	V	$I_{OH} = 7 \text{ mA}$
V_{OL}	Output low voltage	0.0	0.5	V	$I_{OL} = 48 \text{ mA}$
V_{IH}	Input high voltage	1.9	–	V	–
V_{IL}	Input low voltage	–	1.0	V	Referenced to V_{SS}
V_{IK}	Input clamp voltage	–0.66	–0.77	V	$V_{PP} = 4.75 \text{ V};$ $I_1 = -20 \text{ mA}$
V_{TH}	Threshold, HIGH to LOW	1.15	1.25	V	–
V_{TL}	Threshold, LOW to HIGH	1.55	1.65	V	–
$V_{TH}-V_{TL}$	Hysteresis	300	500	mV	–
I_{OH}^2	Output high current	0	7	mA	$V_{OH} = 2.4 \text{ V}$
I_{OL}	Output low current	48	–	mA	$V_{OL} = 0.5 \text{ V}$
I_{OSH}^2	Short-circuit output high current	48	–	mA	Short to V_{DD}^3
I_{OSL}	Short-circuit output low current	22	–	mA	Short to V_{SS}
I_{LH}	Input high leakage	–	20	μA	$-0.5 < V_{DD} < 5.25$ $V_{PIN} = 2.7 \text{ V}$
I_{LL}	Input low leakage	–	20	μA	$-0.5 < V_{DD} < 5.25$ $V_{PIN} = 0.5 \text{ V}$
R_I	Input resistance	20	–	$\text{M}\Omega$	SCSI pins
C_P	Capacitance per pin	–	8	pF	PQFP
t_R^2	Rise time, 10% to 90%	6.7	14.7	ns	Figure 6.3
t_F	Fall time, 90% to 10%	5.7	17.2	ns	Figure 6.3
dV_H/dt	Slew rate LOW to HIGH	100	470	mV/ns	Figure 6.3
dV_L/dt	Slew rate HIGH to LOW	110	440	mV/ns	Figure 6.3

Table 6.13 TolerANT Technology Electrical Characteristics for SE SCSI Signals¹

Symbol	Parameter	Min	Max	Units	Test Conditions
ESD	Electrostatic discharge	2	–	kV	MIL-STD-883C; 3015-7
	Latch-up	100	–	mA	–
	Filter delay	20	30	ns	Figure 6.4
	Ultra filter delay	10	15	ns	Figure 6.4
	Ultra2 filter delay	5	8	ns	Figure 6.4
	Extended filter delay	40	60	ns	Figure 6.4

1. These values are guaranteed by periodic characterization; they are not 100% tested on every device.
2. Active negation outputs only: Data, Parity, SREQ/, SACK/. (Minus Pins) SCSI mode only.
3. Single pin only; irreversible damage may occur if sustained for one second.

Figure 6.3 Rise and Fall Time Test Condition

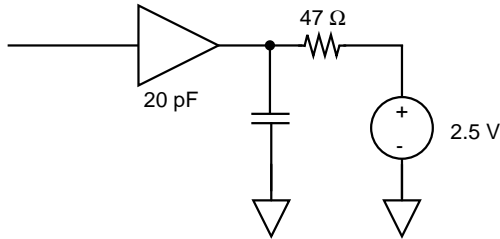
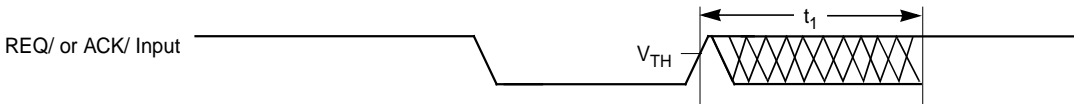


Figure 6.4 SCSI Input Filtering



Note: t_1 is the input filtering period.

Figure 6.5 Hysteresis of SCSI Receivers

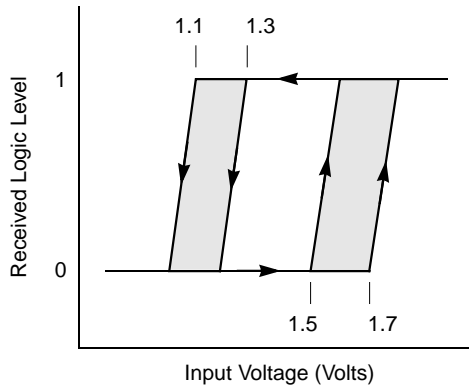


Figure 6.6 Input Current as a Function of Input Voltage

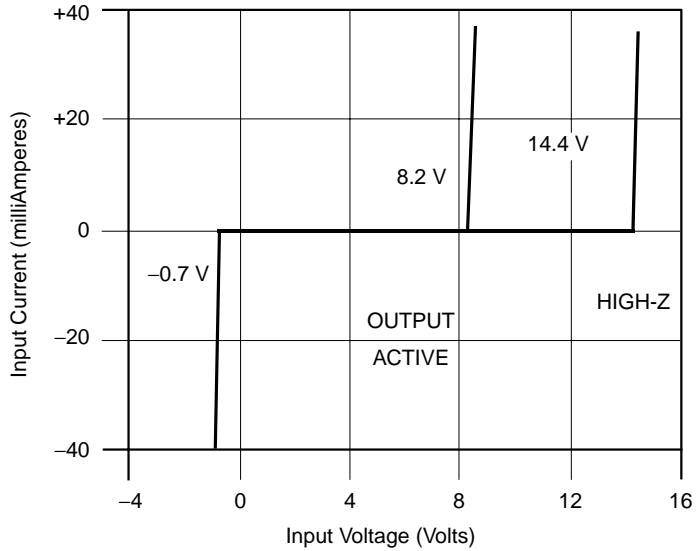
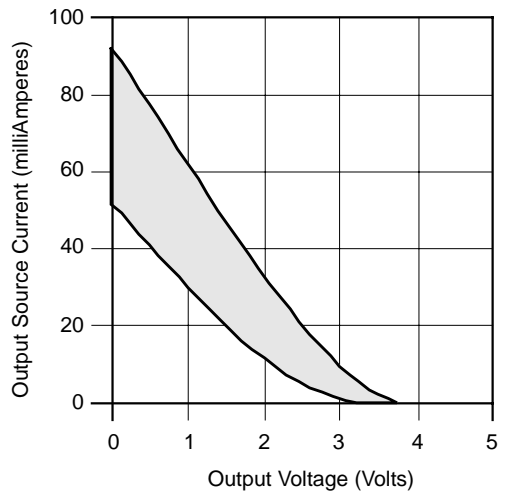
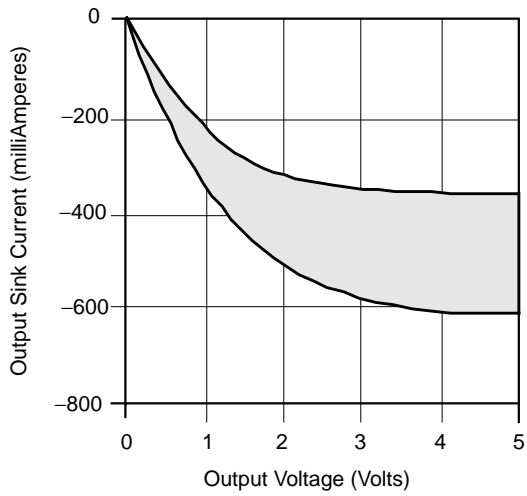


Figure 6.7 Output Current as a Function of Output Voltage



6.3 AC Characteristics

The AC characteristics described in this section apply over the entire range of operating conditions (refer to [Section 6.1, “DC Characteristics”](#)). Chip timing is based on simulation at worst case voltage, temperature, and processing. Timing was developed with a load capacitance of 50 pF.

Table 6.14 External Clock

Symbol	Parameter	Min	Max	Units
t_1	PCI Bus clock period	30	DC	ns
	SCSI clock period ¹	25	25	ns
t_2	PCI CLK LOW time ²	11	–	ns
	SCLK LOW time ²	10	15	ns
t_3	PCI CLK HIGH time ²	11	–	ns
	SCLK HIGH time ²	10	15	ns
t_4	PCI CLK slew rate	1	4	V/ns
	PCI Clock Spread Spectrum Modulation Frequency	30	33	kHz
	PCI Clock Spread Spectrum Frequency Spread	–1	9	%

1. Timing is for an external 40 MHz clock. A quadrupled 40 MHz clock is required for Ultra3 SCSI operation.
2. Duty cycle not to exceed 60/40.

Figure 6.8 External Clock

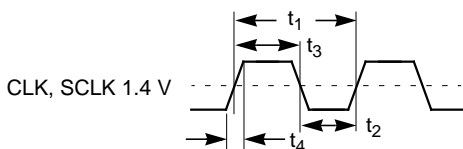


Table 6.15 Reset Input

Symbol	Parameter	Min	Max	Units
t_1	Reset pulse width	10	–	t_{CLK}
t_2	Reset deasserted setup to CLK HIGH	0	–	ns
t_3	MAD setup time to CLK HIGH (for configuring the MAD bus only)	20	–	ns
t_4	MAD hold time from CLK HIGH (for configuring the MAD bus only)	20	–	ns

Figure 6.9 Reset Input

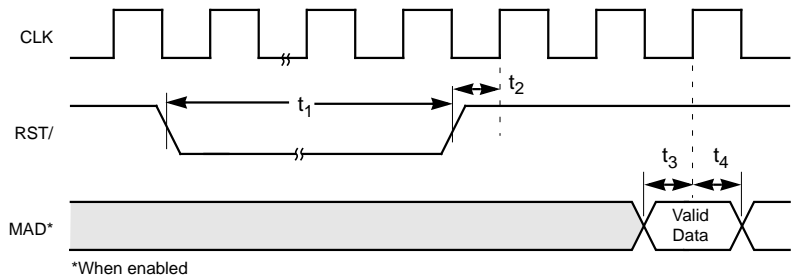
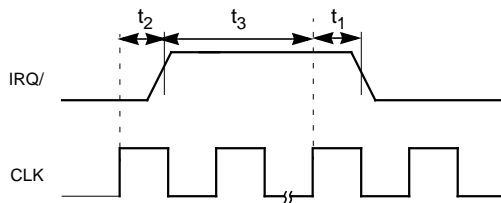


Table 6.16 Interrupt Output

Symbol	Parameter	Min	Max	Units
t_1	CLK HIGH to IRQ/ LOW	2	11	ns
t_2	CLK HIGH to IRQ/ HIGH	2	11	ns
t_3	IRQ/ deassertion time	3	–	CLK

Figure 6.10 Interrupt Output



6.4 PCI and External Memory Interface Timing Diagrams

Figure 6.11 through Figure 6.34 represent signal activity when the SYM53C1010-33 accesses the PCI bus. This section includes timing diagrams for access to three groups of memory configurations. The first group applies to [Target Timing](#). The second group applies to [Initiator Timing](#). The third group applies to [External Memory Timing](#).

Note: Multiple byte accesses to the external memory bus increase the read or write cycle by 11 clocks for each additional byte.

Timing diagrams included in this section are:

- [Target Timing](#)
 - [PCI Configuration Register Read](#)
 - [PCI Configuration Register Write](#)
 - [32-Bit Operating Registers/SCRIPTS RAM Read](#)
 - [64-Bit Operating Register/SCRIPTS RAM Read](#)
 - [32-Bit Operating Register/SCRIPTS RAM Write](#)
 - [64-Bit Operating Register/SCRIPTS RAM Write](#)
- [Initiator Timing](#)
 - [Nonburst Opcode Fetch, 32-Bit Address and Data](#)
 - [Burst Opcode Fetch, 32-Bit Address and Data](#)
 - [Back-to-Back Read, 32-Bit Address and Data](#)
 - [Back-to-Back Write, 32-Bit Address and Data](#)
 - [Burst Read, 32-Bit Address and Data](#)
 - [Burst Read, 64-Bit Address and Data](#)
 - [Burst Write, 32-Bit Address and Data](#)
 - [Burst Write, 64-Bit Address and Data](#)
- [External Memory Timing](#)
 - [External Memory Read](#)
 - [External Memory Write](#)

- Normal/Fast Memory (≥ 128 Kbytes) Single Byte Access Read Cycle
- Normal/Fast Memory (≥ 128 Kbytes) Single Byte Access Write Cycle
- Slow Memory (≥ 128 Kbytes) Read Cycle
- Slow Memory (≥ 128 Kbytes) Write Cycle
- ≤ 64 Kbytes ROM Read Cycle
- ≤ 64 Kbytes ROM Write Cycle

6.4.1 Target Timing

Table 6.17 PCI Configuration Register Read

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns

Figure 6.11 PCI Configuration Register Read

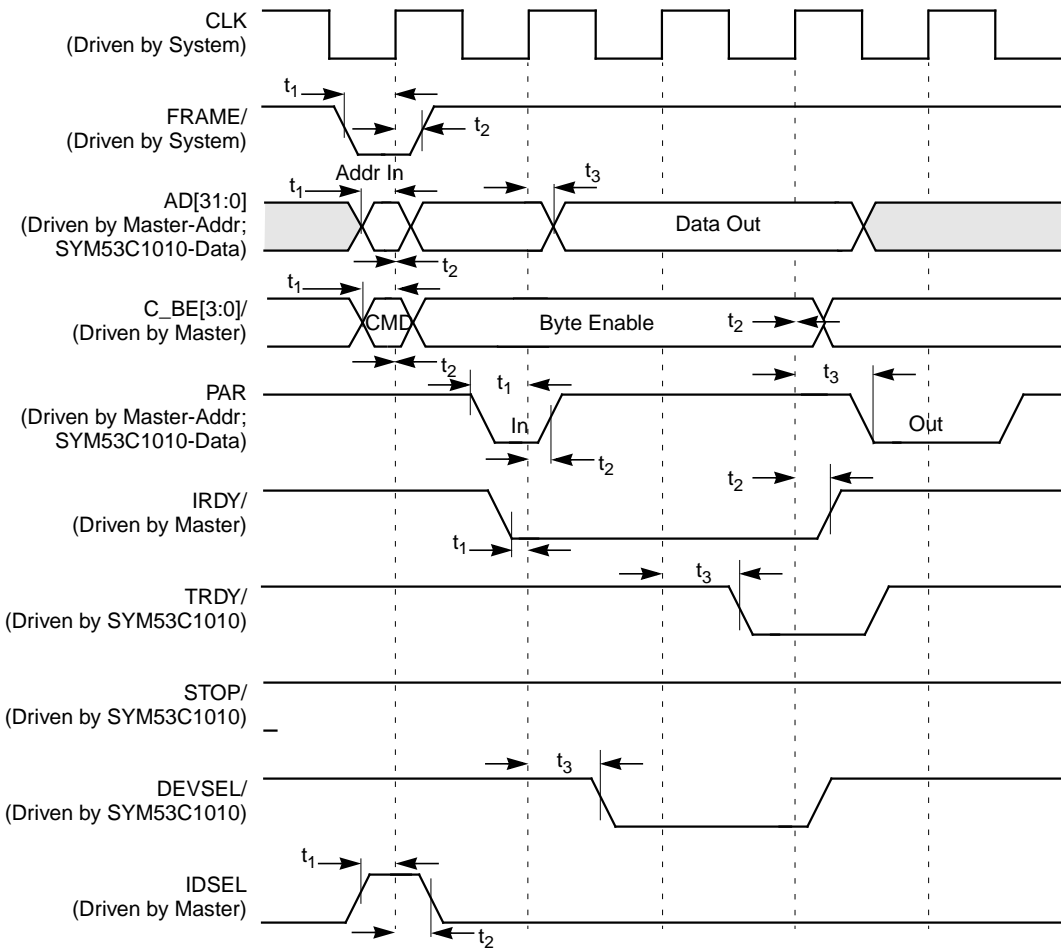


Table 6.18 PCI Configuration Register Write

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns

Figure 6.12 PCI Configuration Register Write

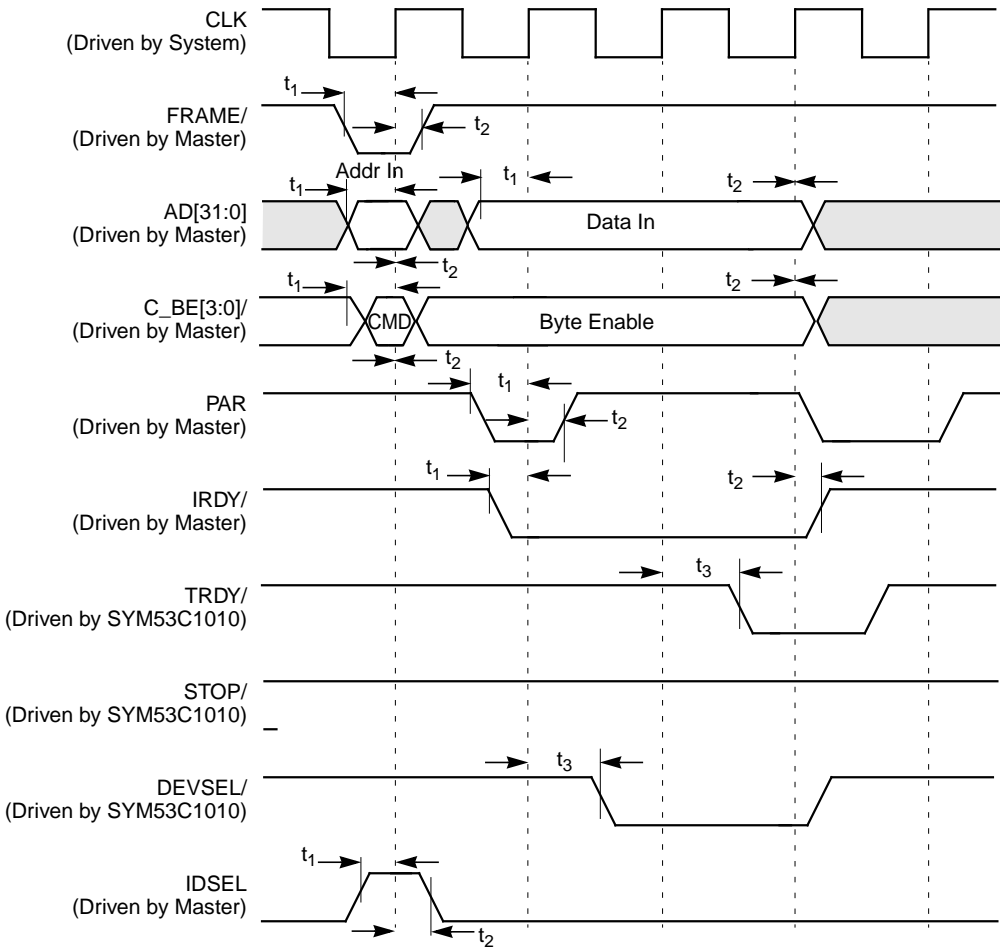


Table 6.19 32-Bit Operating Register/SCRIPTS RAM Read

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns

Figure 6.13 32-Bit Operating Registers/SCRIPTS RAM Read

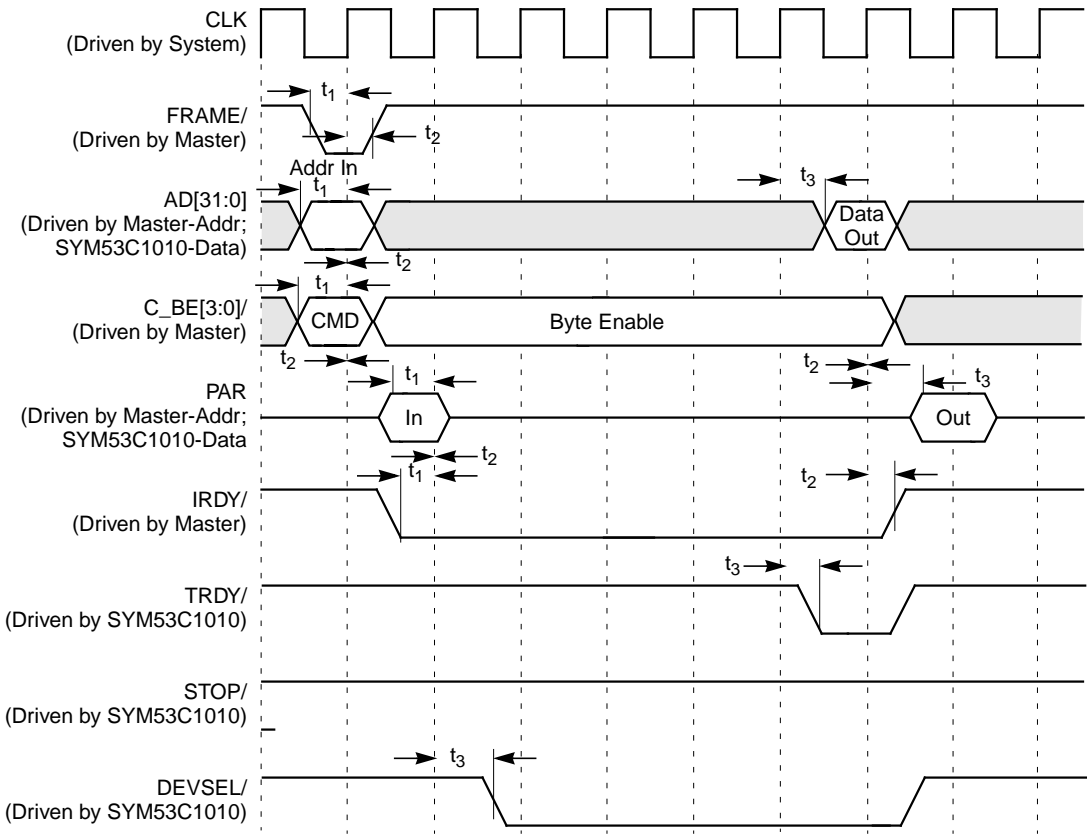


Table 6.20 64-Bit Operating Register/SCRIPTS RAM Read

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns

Figure 6.14 64-Bit Operating Register/SCRIPTS RAM Read

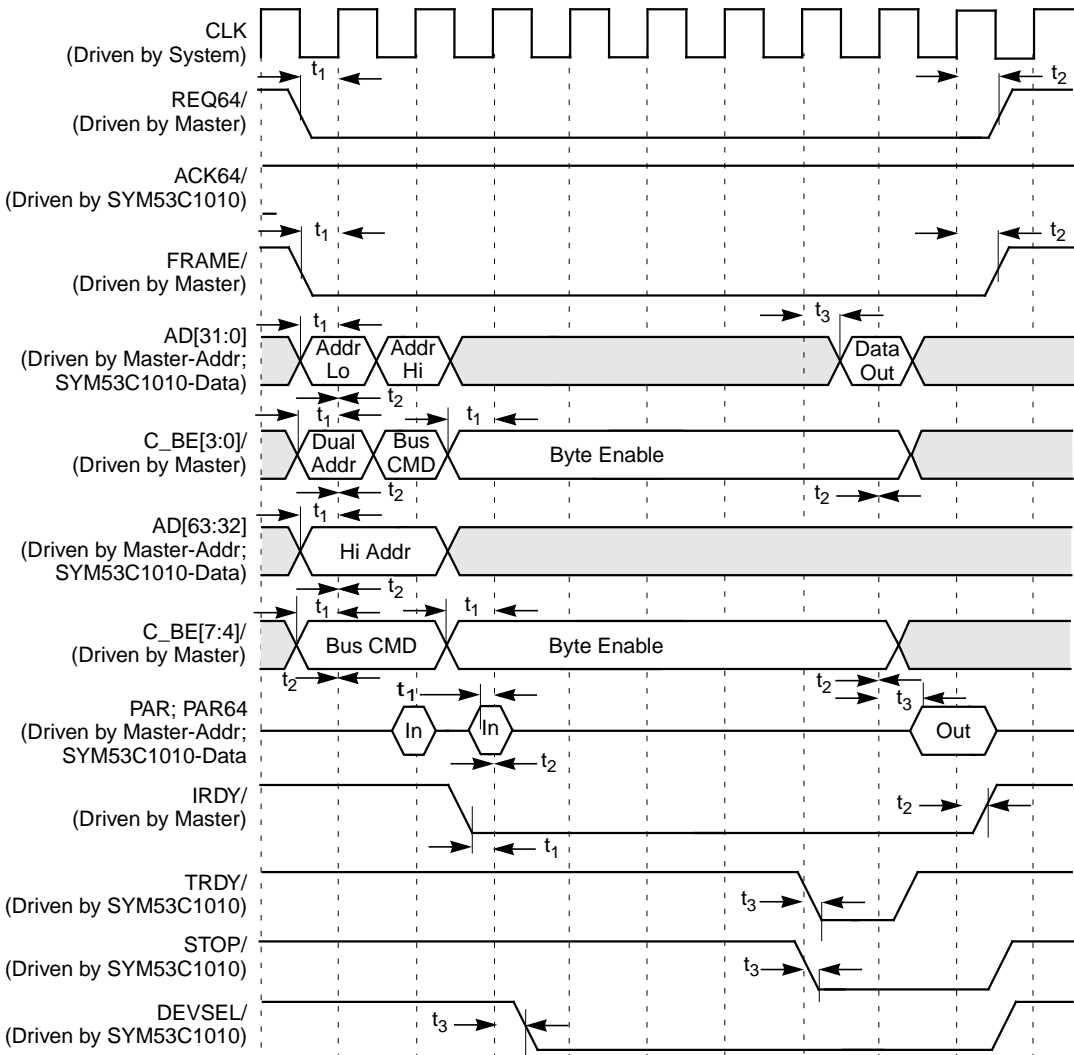


Table 6.21 32-Bit Operating Register/SCRIPTS RAM Write

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns

Figure 6.15 32-Bit Operating Register/SCRIPTS RAM Write

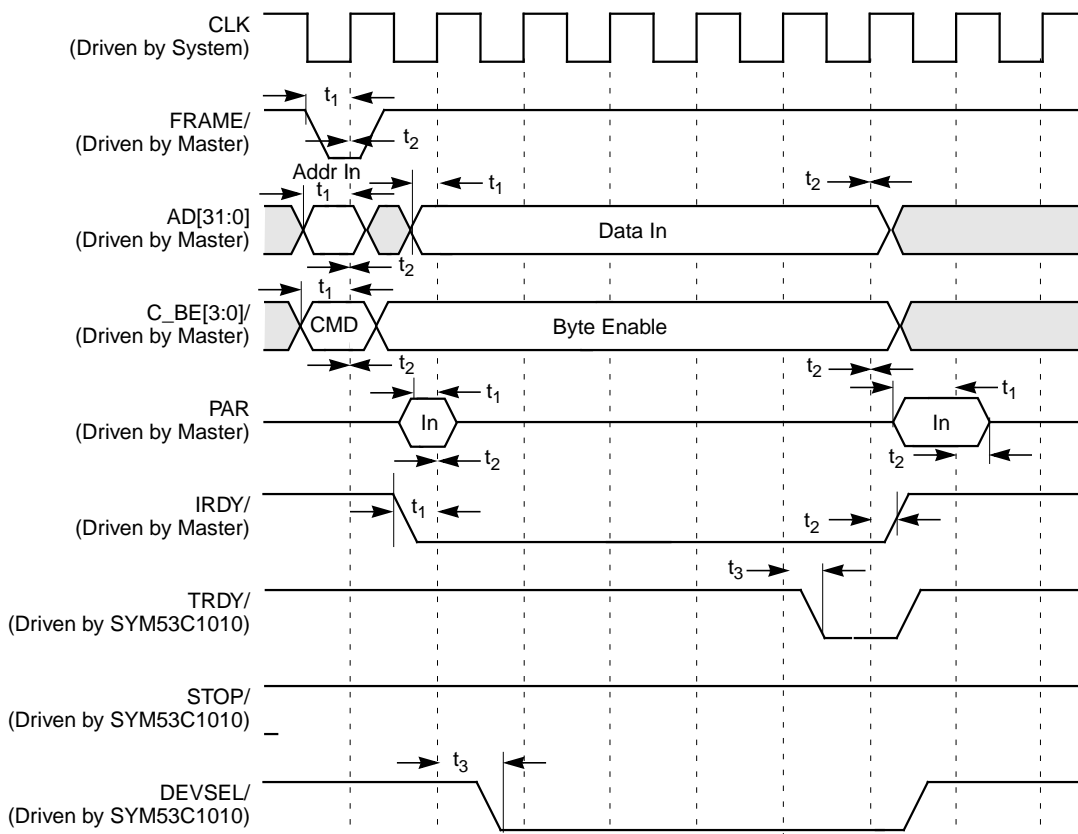
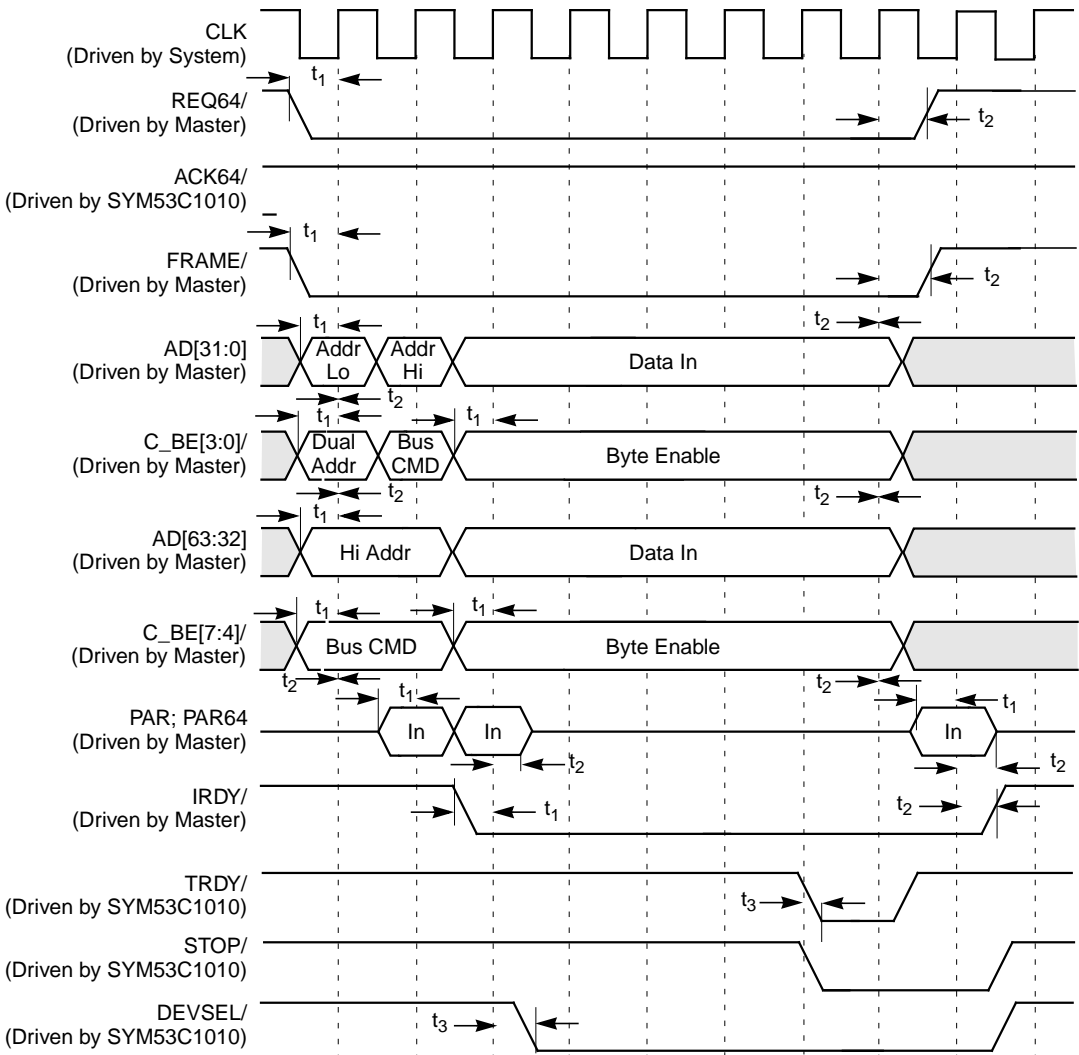


Table 6.22 64-Bit Operating Register/SCRIPTS RAM Write

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns

Figure 6.16 64-Bit Operating Register/SCRIPTS RAM Write



6.4.2 Initiator Timing

Table 6.23 Nonburst Opcode Fetch, 32-Bit Address and Data

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns
t_4	Side signal input setup time	10	–	ns
t_5	Side signal input hold time	0	–	ns
t_6	CLK to side signal output valid	2	12	ns

Figure 6.17 Nonburst Opcode Fetch, 32-Bit Address and Data

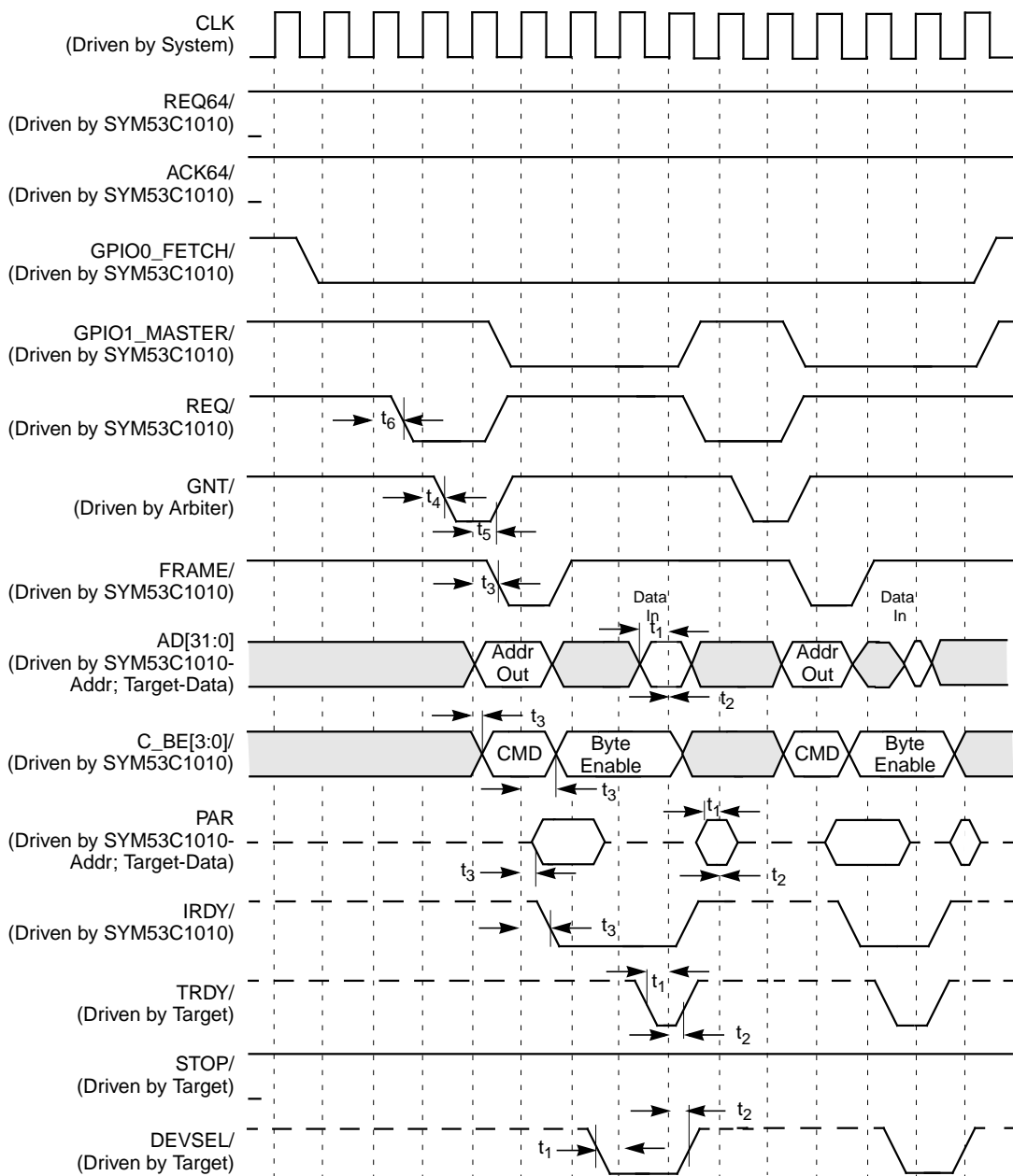


Table 6.24 Burst Opcode Fetch, 32-Bit Address and Data

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns
t_4	Side signal input setup time	10	–	ns
t_5	Side signal input hold time	0	–	ns
t_6	CLK to side signal output valid	2	12	ns

Figure 6.18 Burst Opcode Fetch, 32-Bit Address and Data

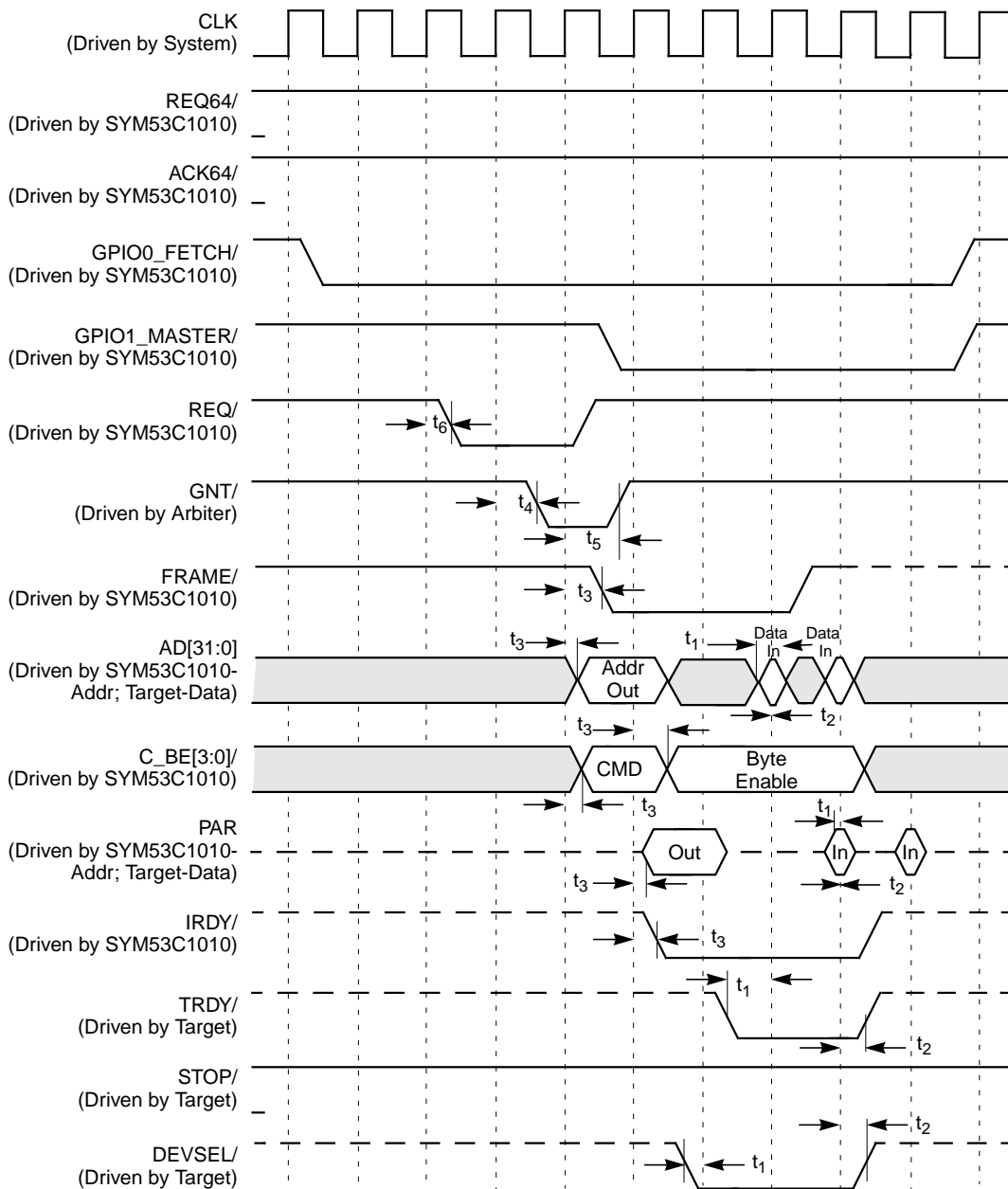


Table 6.25 Back-to-Back Read, 32-Bit Address and Data

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns
t_4	Side signal input setup time	10	–	ns
t_5	Side signal input hold time	0	–	ns
t_6	CLK to side signal output valid	2	12	ns

Figure 6.19 Back-to-Back Read, 32-Bit Address and Data

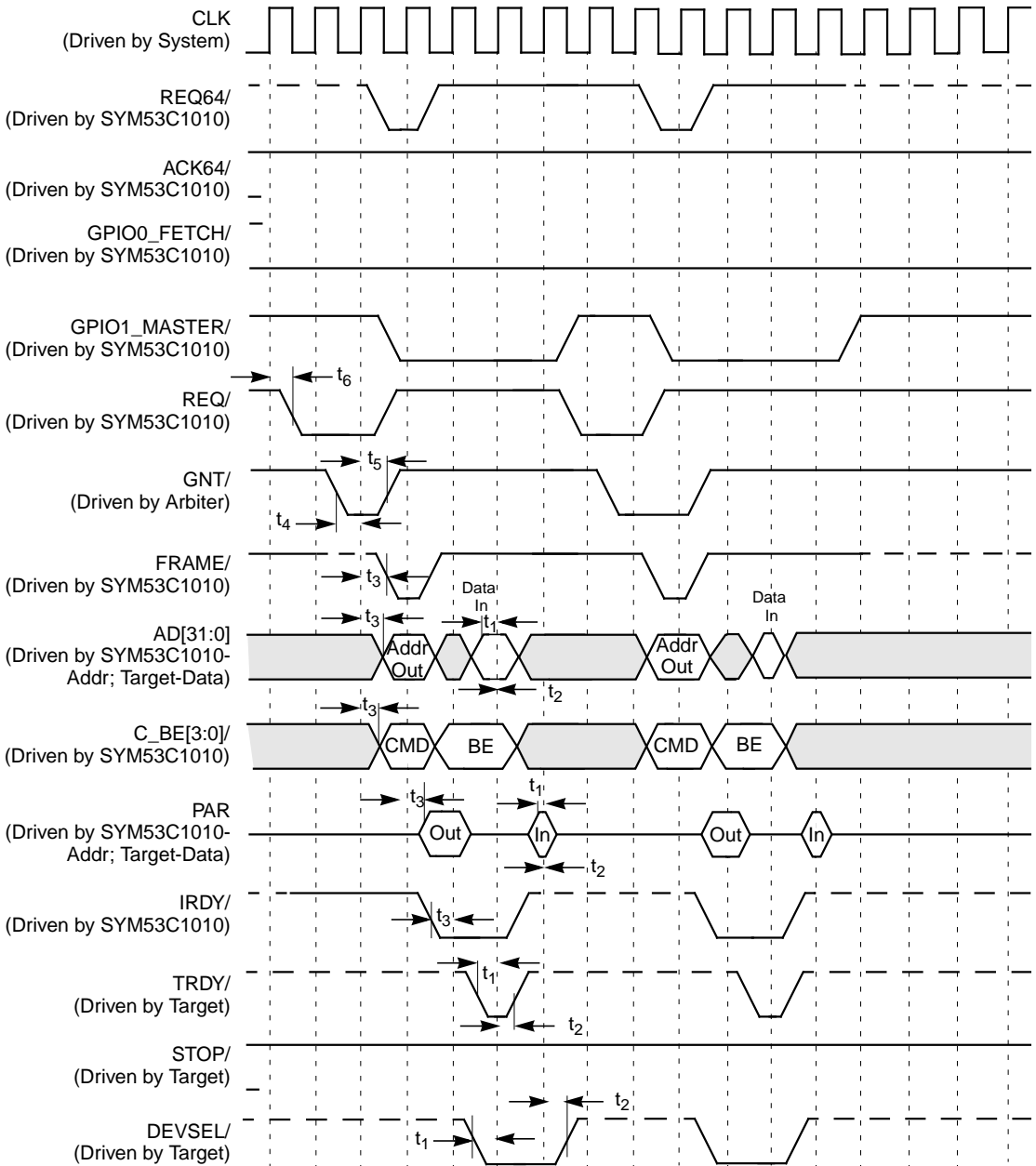


Table 6.26 Back-to-Back Write, 32-Bit Address and Data

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns
t_4	Side signal input setup time	10	–	ns
t_5	Side signal input hold time	0	–	ns
t_6	CLK to side signal output valid	2	12	ns

Figure 6.20 Back-to-Back Write, 32-Bit Address and Data

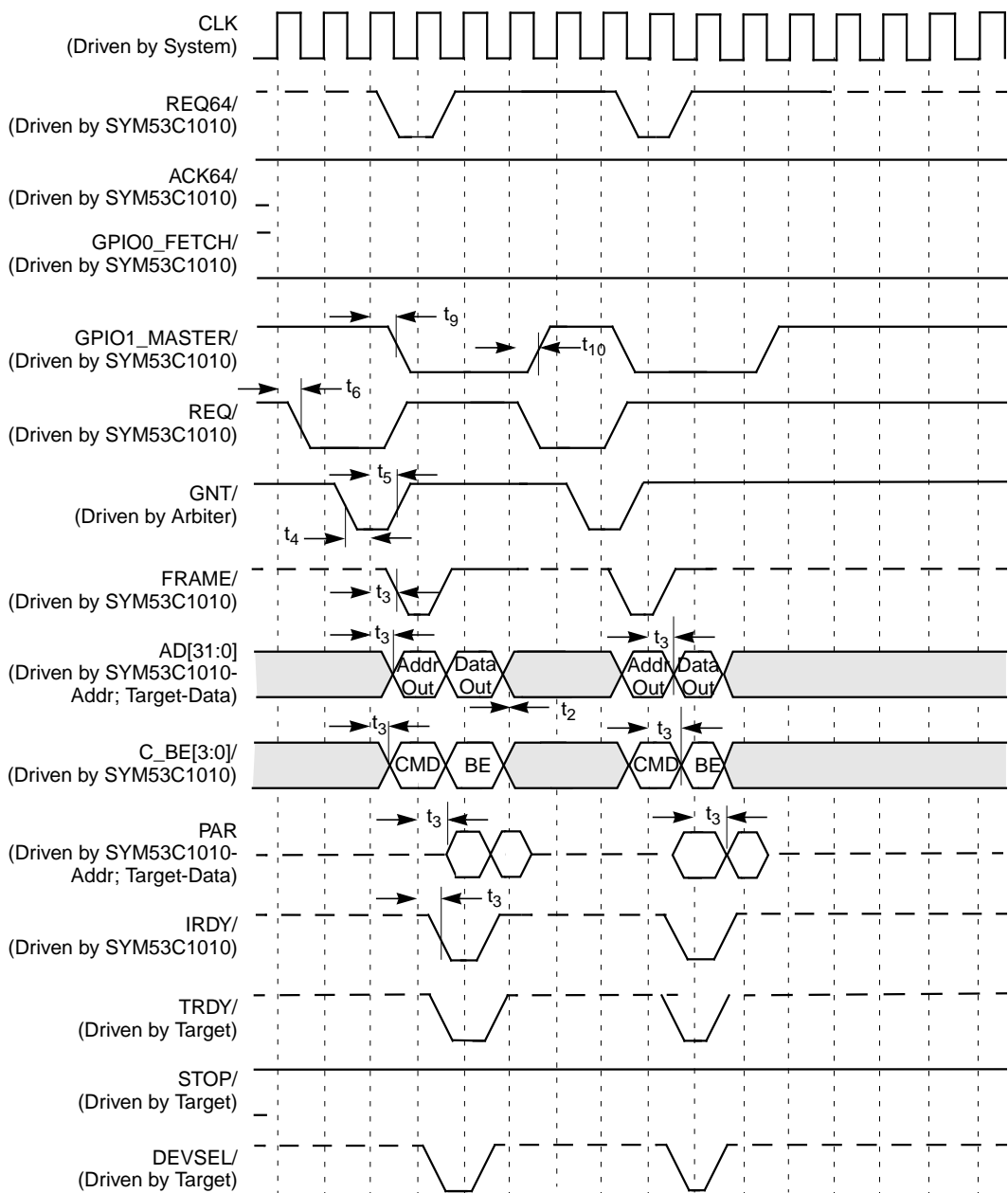


Table 6.27 Burst Read, 32-Bit Address and Data

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns

Figure 6.21 Burst Read, 32-Bit Address and Data

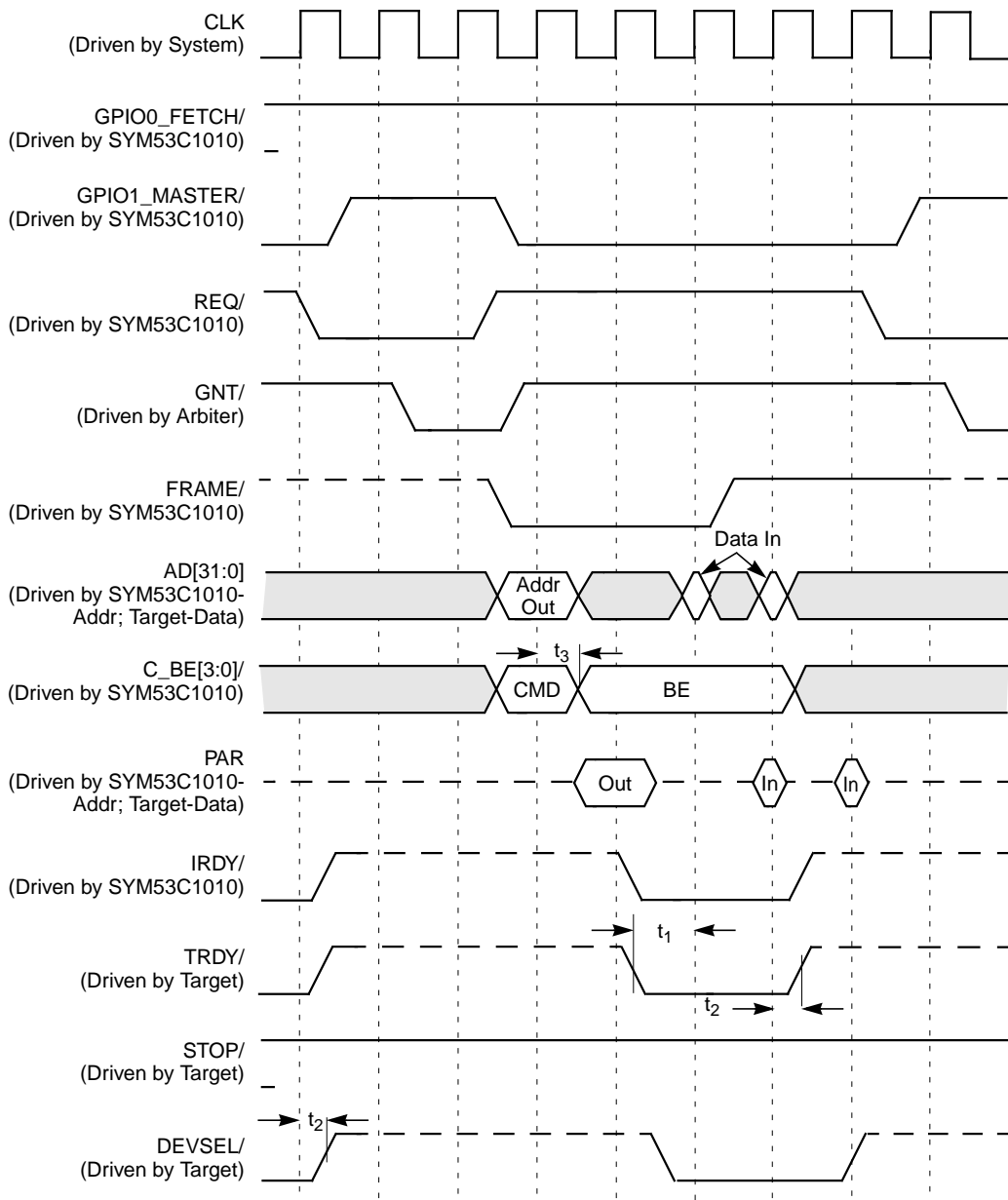


Table 6.28 Burst Read, 64-Bit Address and Data

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns

Figure 6.22 Burst Read, 64-Bit Address and Data

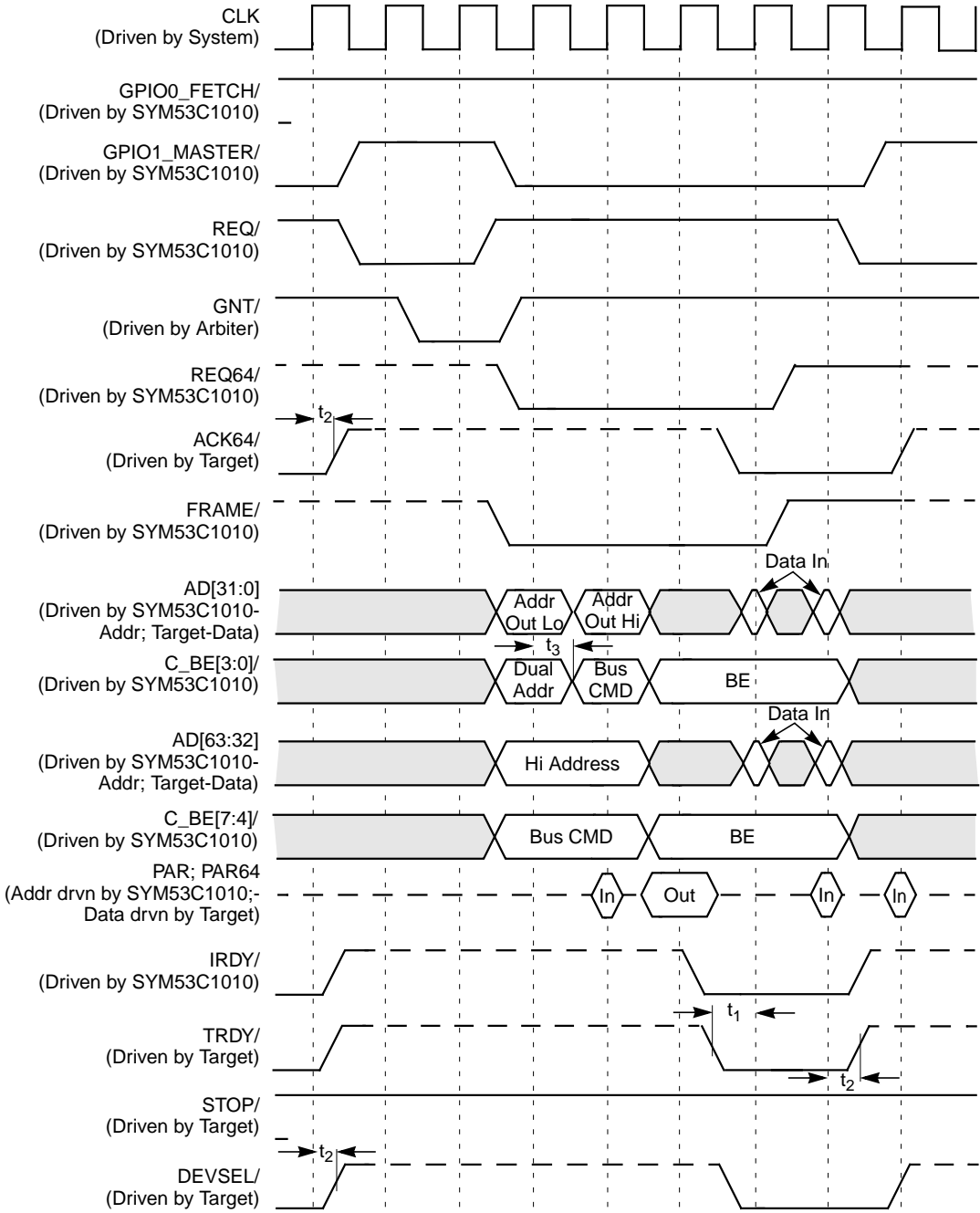


Table 6.29 Burst Write, 32-Bit Address and Data

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns

Figure 6.23 Burst Write, 32-Bit Address and Data

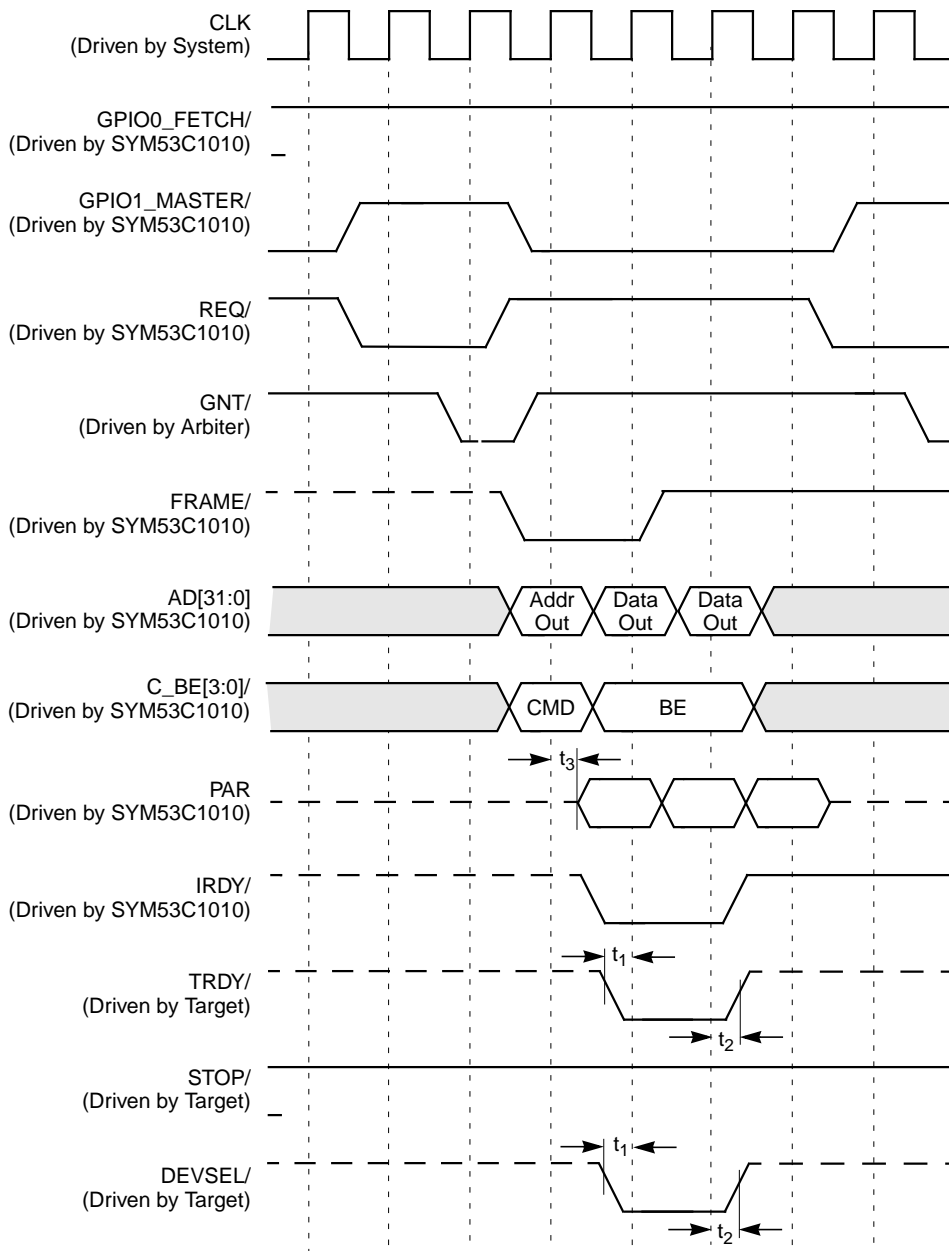
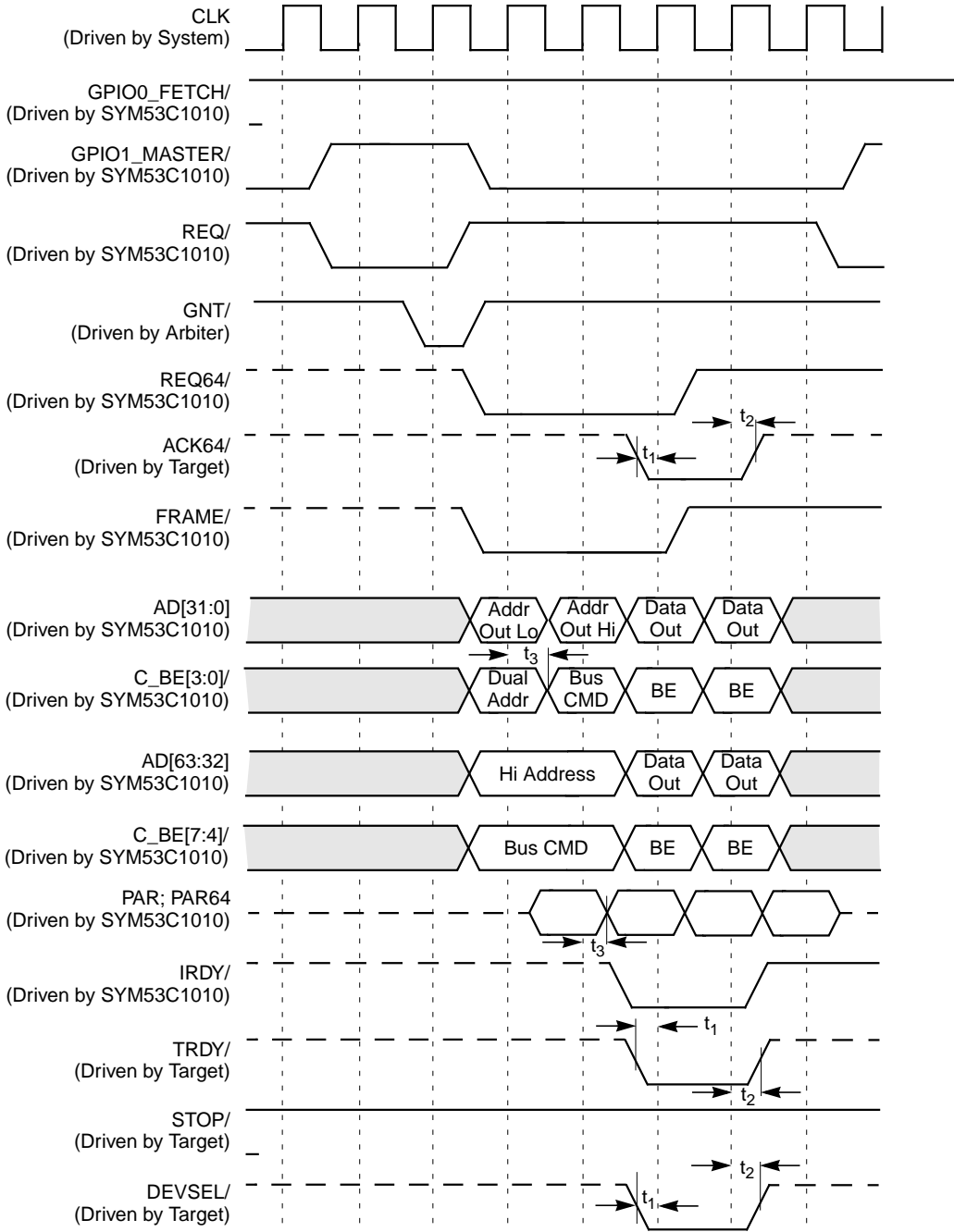


Table 6.30 Burst Write, 64-Bit Address and Data

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns

Figure 6.24 Burst Write, 64-Bit Address and Data



6.4.3 External Memory Timing

Table 6.31 External Memory Read

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns
t_{11}	Address setup to MAS/ HIGH	25	–	ns
t_{12}	Address hold from MAS/ HIGH	15	–	ns
t_{13}	MAS/ pulse width	25	–	ns
t_{14}	MCE/ LOW to data clocked in	150	–	ns
t_{15}	Address valid to data clocked in	205	–	ns
t_{16}	MOE/ LOW to data clocked in	100	–	ns
t_{17}	Data hold from address, MOE/, MCE/ change	0	–	ns
t_{19}	Data setup to CLK HIGH	5	–	ns

Figure 6.25 External Memory Read

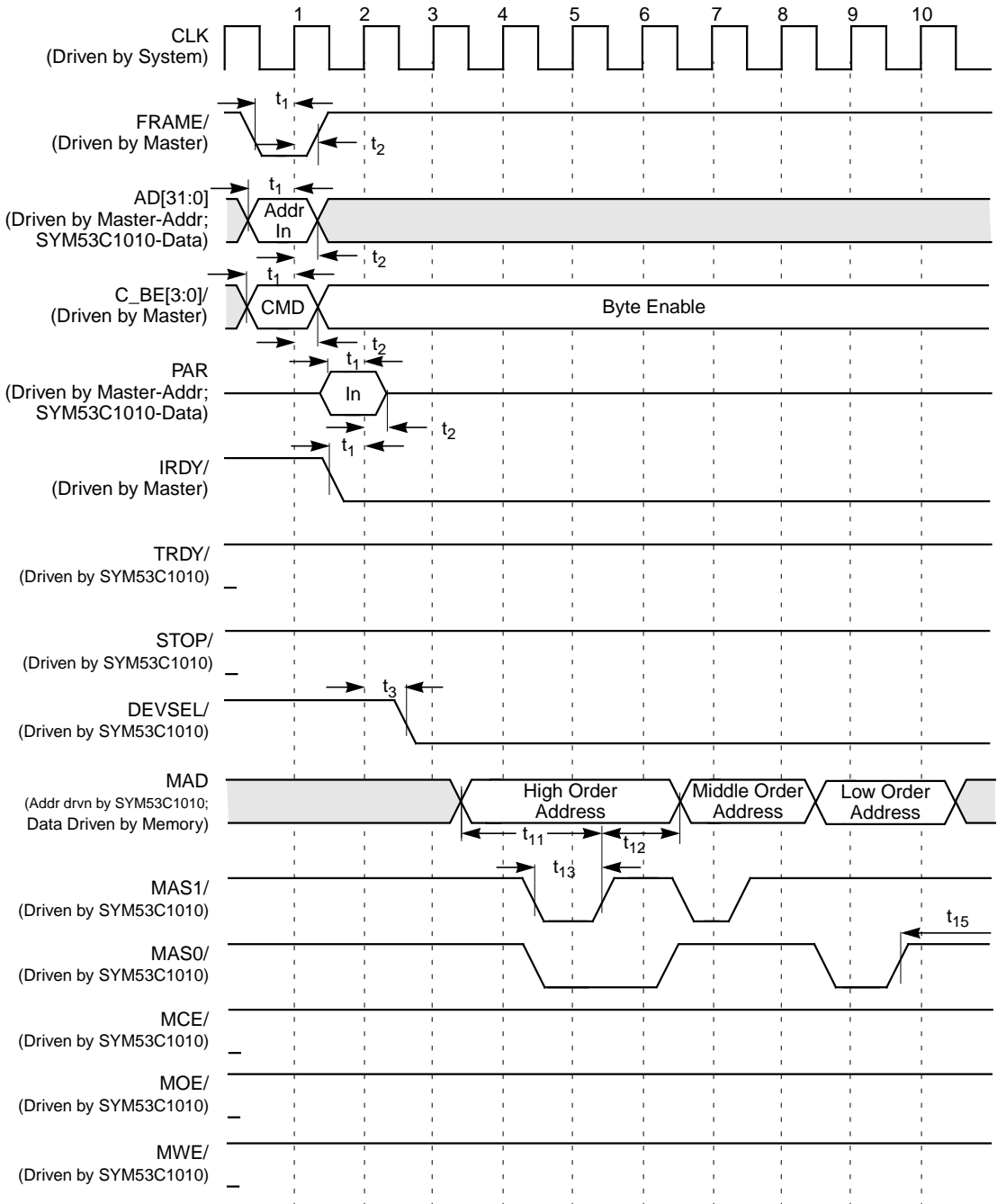


Figure 6.25 External Memory Read (Cont.)

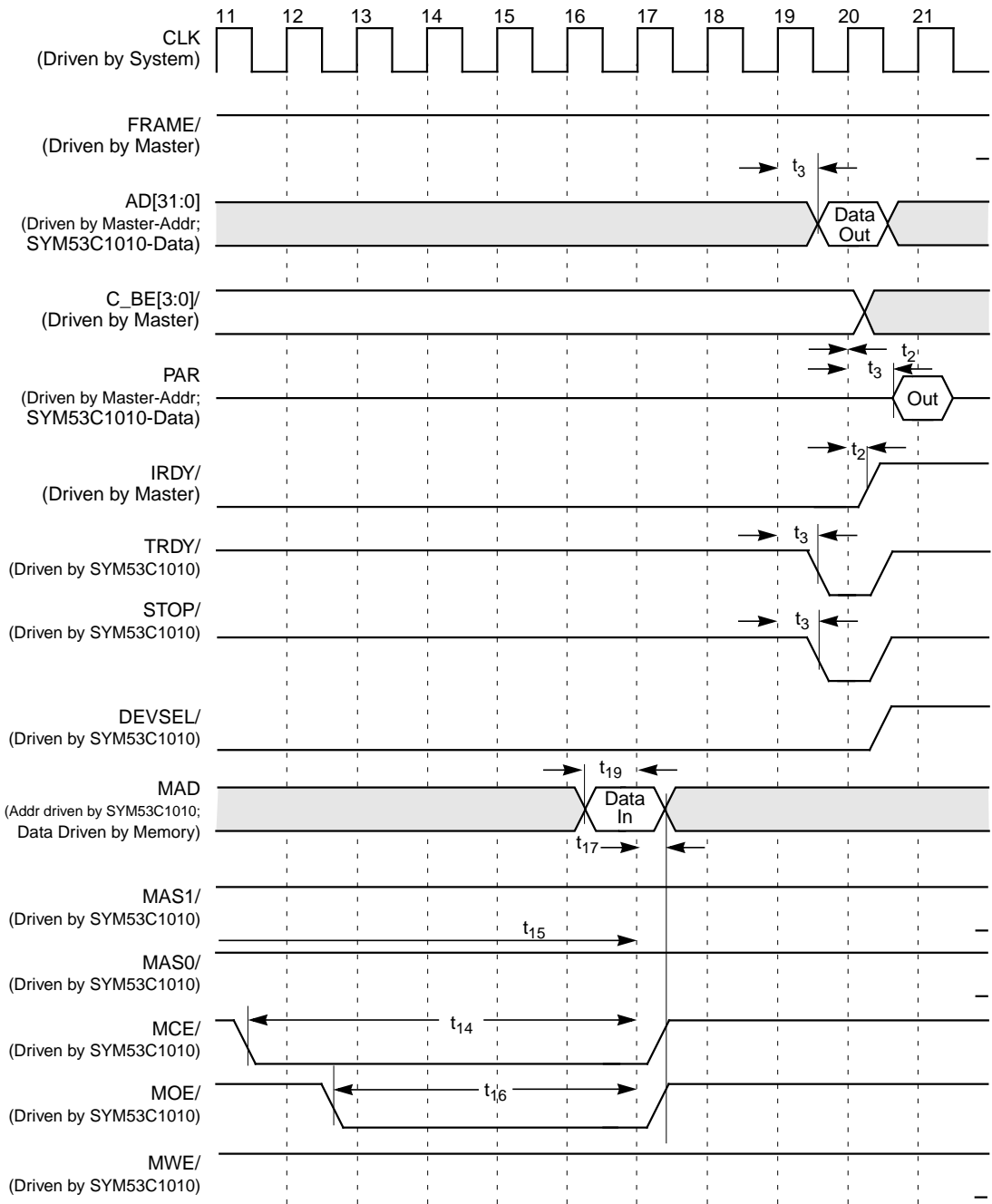


Table 6.32 External Memory Write

Symbol	Parameter	Min	Max	Unit
t_1	Shared signal input setup time	7	–	ns
t_2	Shared signal input hold time	0	–	ns
t_3	CLK to shared signal output valid	2	11	ns
t_{11}	Address setup to MAS/ HIGH	25	–	ns
t_{12}	Address hold from MAS/ HIGH	15	–	ns
t_{13}	MAS/ pulse width	25	–	ns
t_{20}	Data setup to MWE/ LOW	30	–	ns
t_{21}	Data hold from MWE/ HIGH	20	–	ns
t_{22}	MWE/ pulse width	100	–	ns
t_{23}	Address setup to MWE/ LOW	60	–	ns
t_{24}	MCE/ LOW to MWE/ HIGH	120	–	ns
t_{25}	MCE/ LOW to MWE/ LOW	25	–	ns
t_{26}	MWE/ HIGH to MCE/ HIGH	25	–	ns

Figure 6.26 External Memory Write

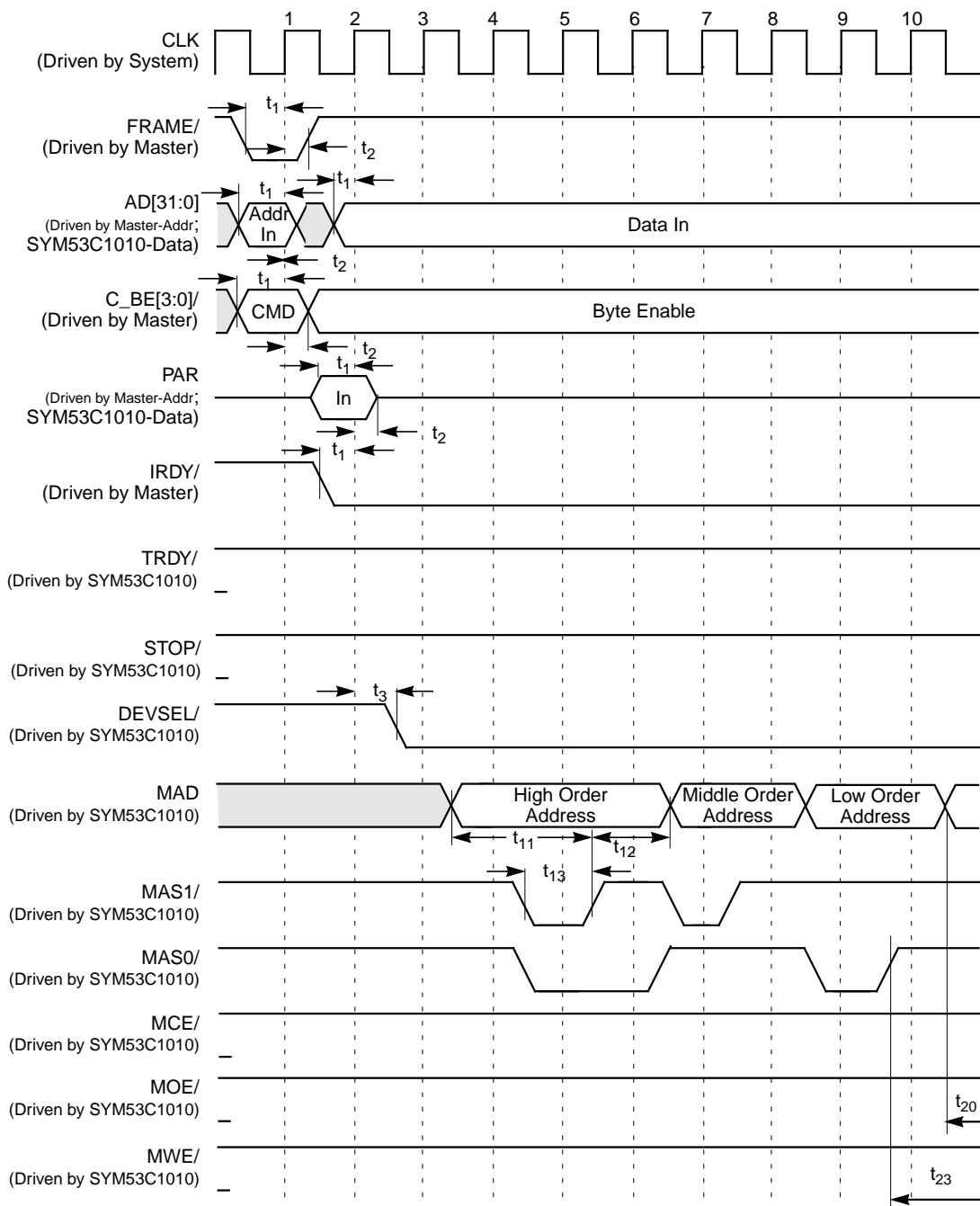


Figure 6.26 External Memory Write (Cont.)

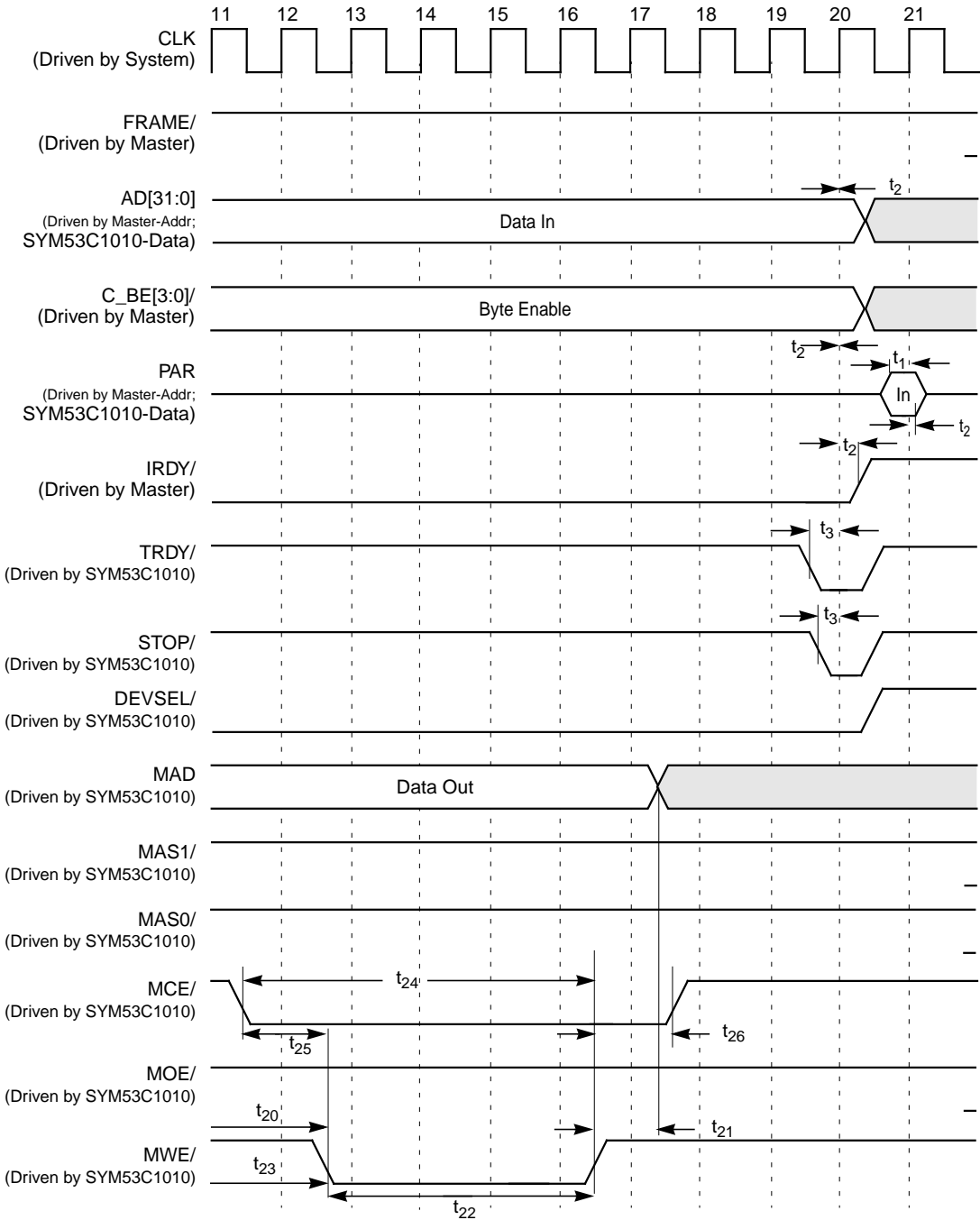


Table 6.33 Normal/Fast Memory (≥ 128 Kbytes) Single Byte Access Read Cycle

Symbol	Parameter	Min	Max	Unit
t_{11}	Address setup to MAS/ high	25	–	ns
t_{12}	Address hold from MAS/ high	15	–	ns
t_{13}	MAS/ pulse width	25	–	ns
t_{14}	MCE/ LOW to data clocked in	150	–	ns
t_{15}	Address valid to data clocked in	205	–	ns
t_{16}	MOE/ LOW to data clocked in	100	–	ns
t_{17}	Data hold from address, MOE/, MCE/ change	0	–	ns
t_{18}	Address out from MOE/, MCE/ HIGH	50	–	ns
t_{19}	Data setup to CLK HIGH	5	–	ns

Figure 6.27 Normal/Fast Memory (≥ 128 Kbytes) Single Byte Access Read Cycle

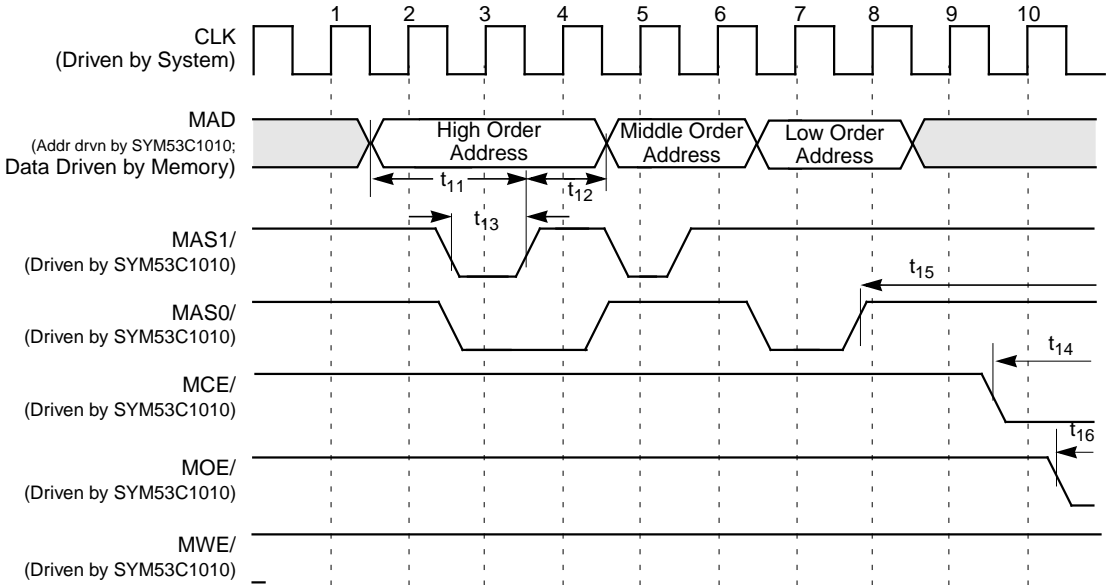


Figure 6.27 Normal/Fast Memory (≥ 128 Kbytes) Single Byte Access Read Cycle (Cont.)

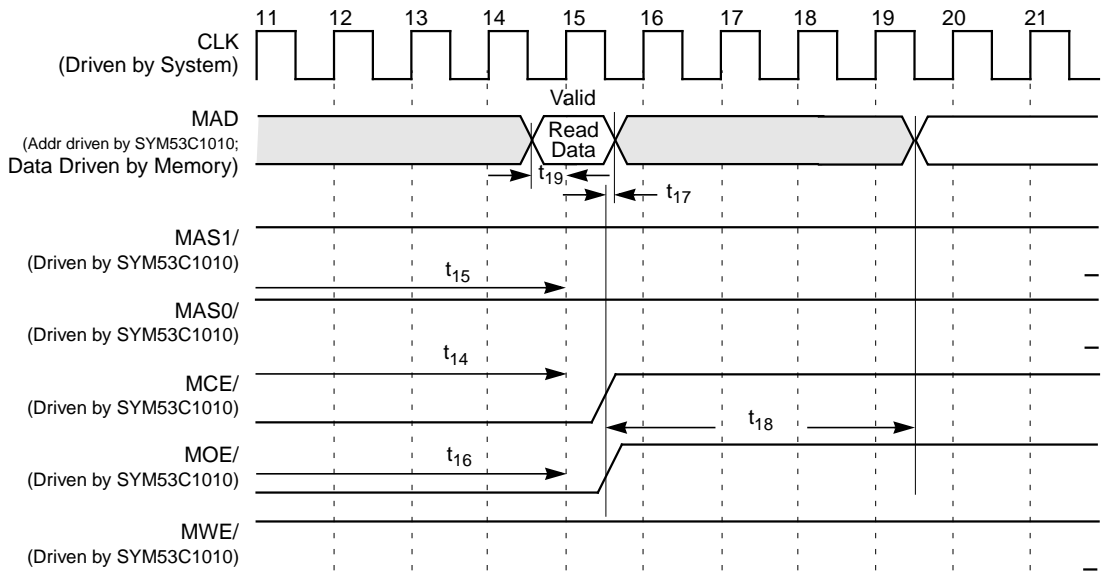


Table 6.34 Normal/Fast Memory (≥ 128 Kbytes) Single Byte Access Write Cycle

Symbol	Parameter	Min	Max	Unit
t_{11}	Address setup to MAS/ HIGH	25	–	ns
t_{12}	Address hold from MAS/ HIGH	15	–	ns
t_{13}	MAS/ pulse width	25	–	ns
t_{20}	Data setup to MWE/ LOW	30	–	ns
t_{21}	Data hold from MWE/ HIGH	20	–	ns
t_{22}	MWE/ pulse width	100	–	ns
t_{23}	Address setup to MWE/ LOW	60	–	ns
t_{24}	MCE/ LOW to MWE/ HIGH	120	–	ns
t_{25}	MCE/ LOW to MWE/ LOW	25	–	ns
t_{26}	MWE/ HIGH to MCE/ HIGH	25	–	ns

Figure 6.28 Normal/Fast Memory (≥ 128 Kbytes) Single Byte Access Write Cycle

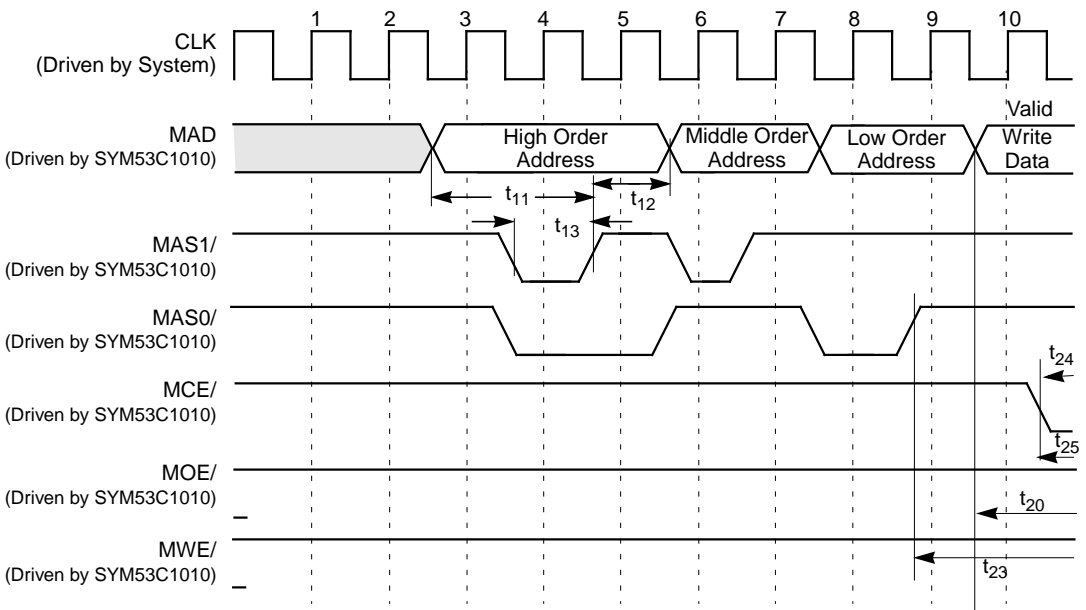


Figure 6.28 Normal/Fast Memory (≥ 128 Kbytes) Single Byte Access Write Cycle (Cont.)

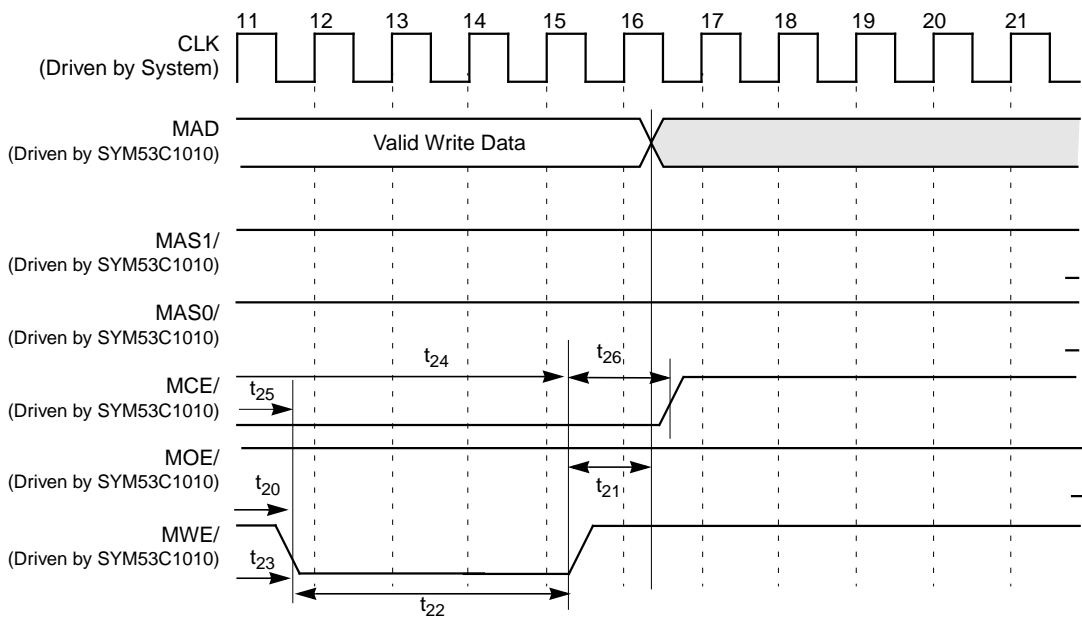


Figure 6.29 Normal/Fast Memory (≥ 128 Kbytes) Multiple Byte Access Read Cycle

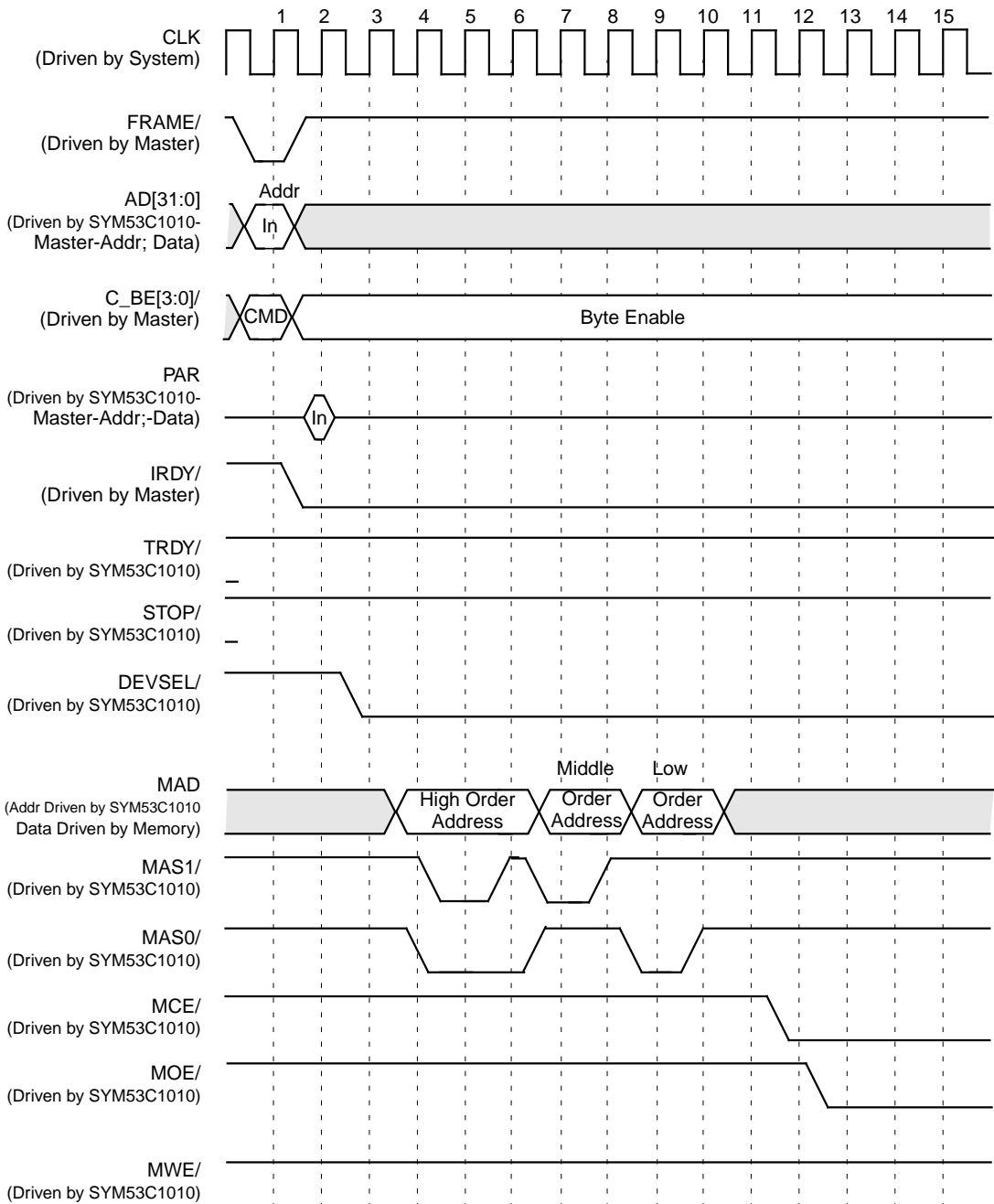


Figure 6.29 Normal/Fast Memory (≥ 128 Kbytes) Multiple Byte Access Read Cycle (Cont.)

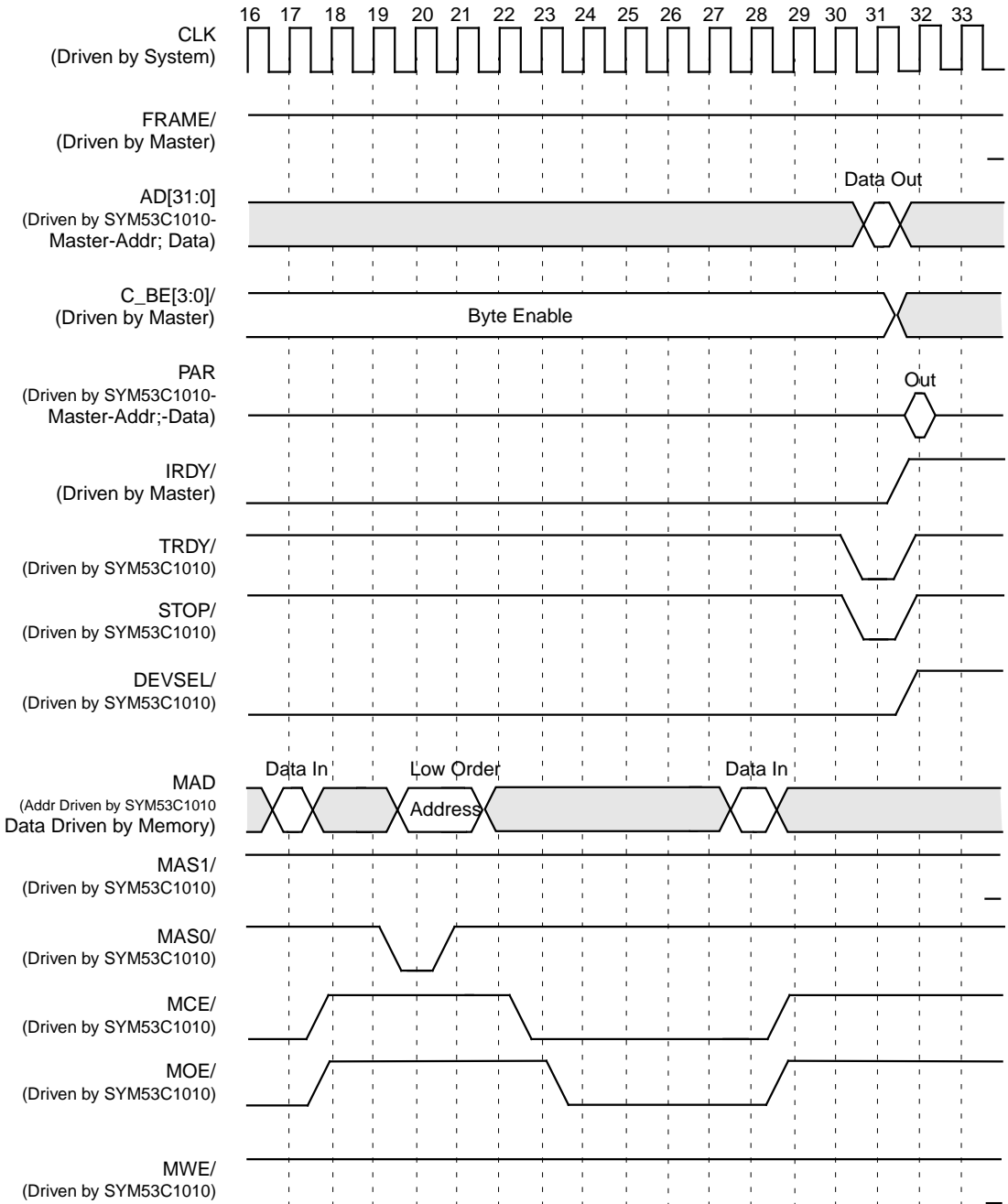


Figure 6.30 Normal/Fast Memory (≥ 128 Kbytes) Multiple Byte Access Write Cycle

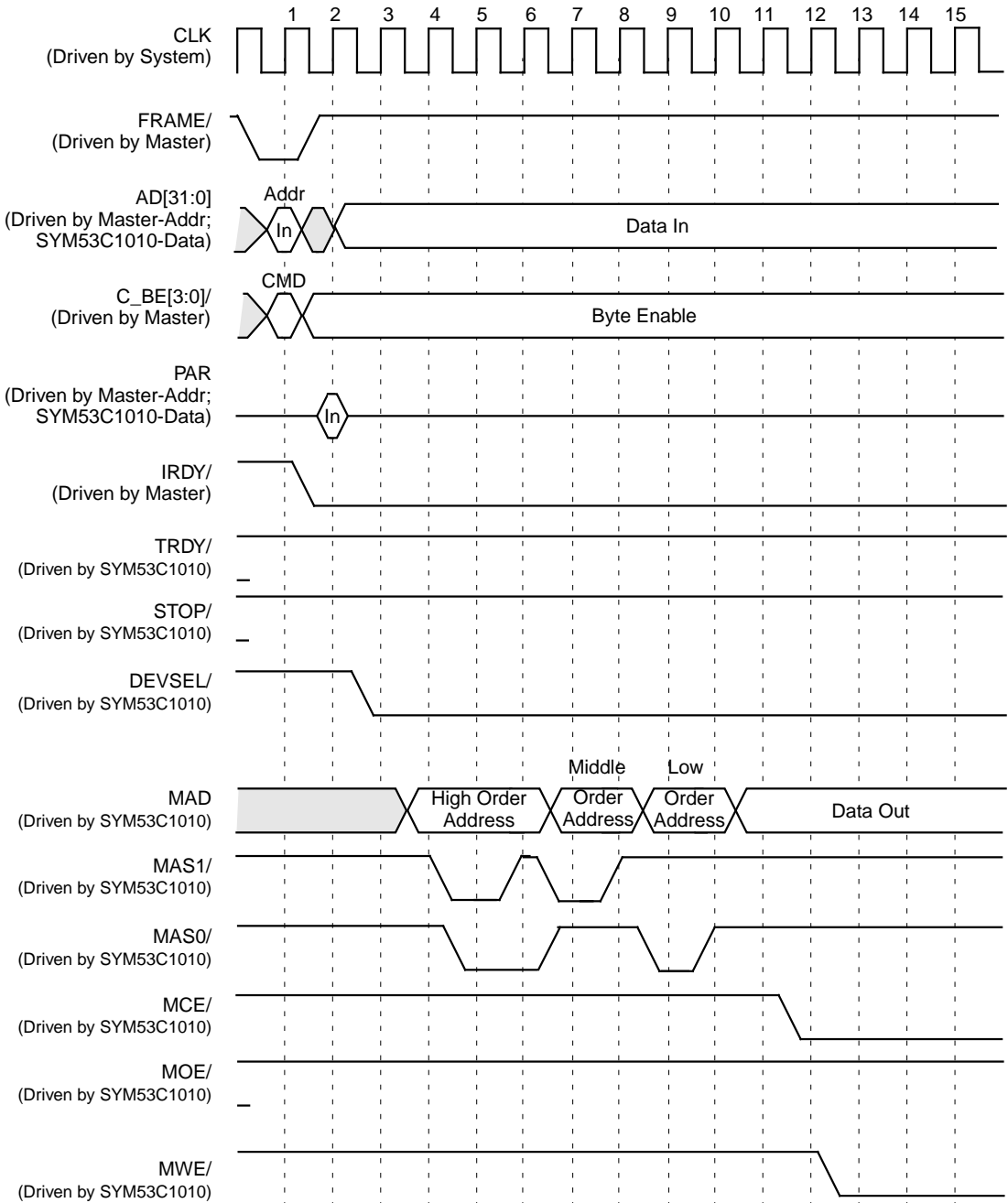


Figure 6.30 Normal/Fast Memory (≥ 128 Kbytes) Multiple Byte Access Write Cycle (Cont.)

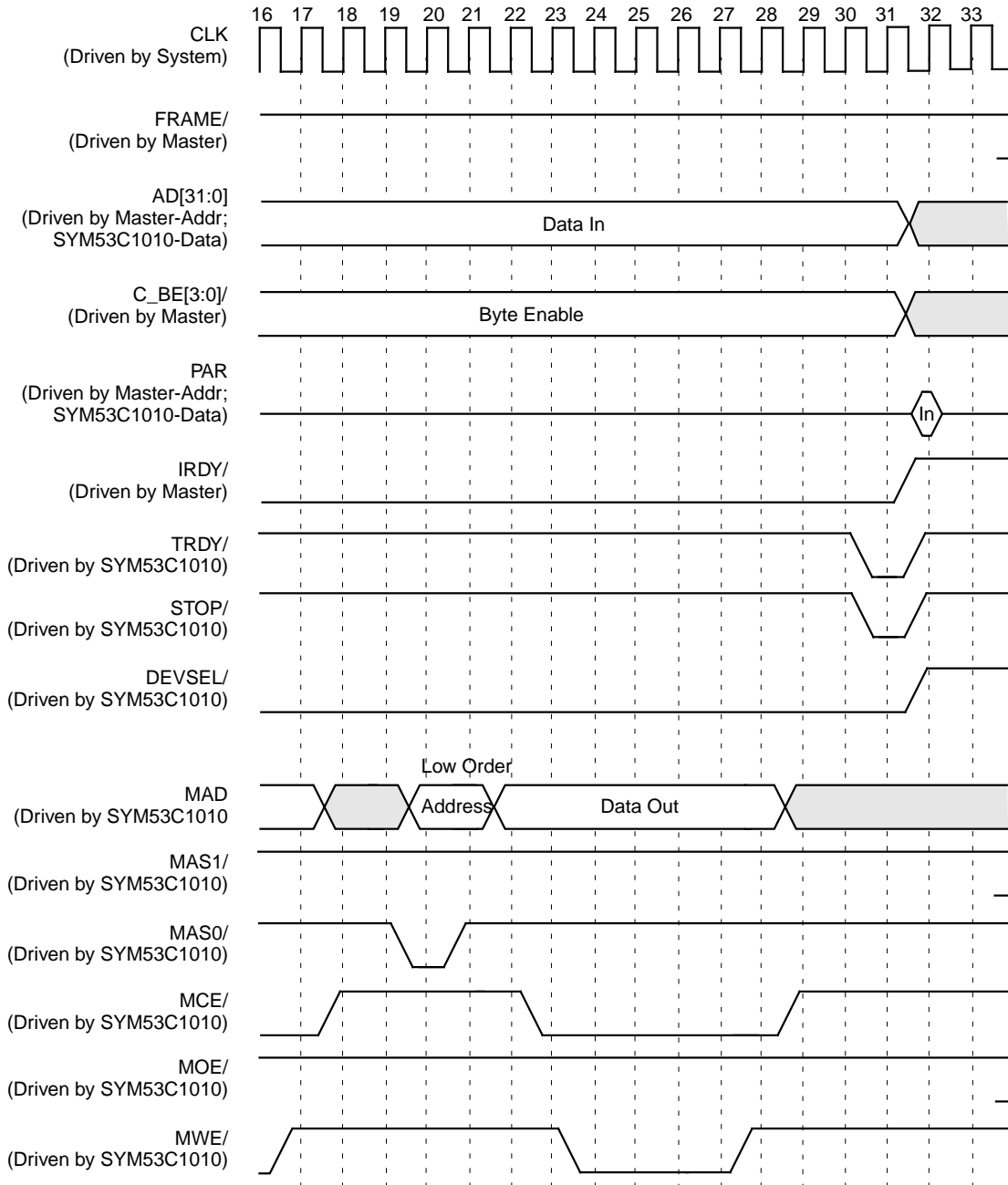


Table 6.35 Slow Memory (≥ 128 Kbytes) Read Cycle

Symbol	Parameter	Min	Max	Unit
t_{11}	Address setup to MAS/ HIGH	25	–	ns
t_{12}	Address hold from MAS/ HIGH	15	–	ns
t_{13}	MAS/ pulse width	25	–	ns
t_{14}	MCE/ LOW to data clocked in	150	–	ns
t_{15}	Address valid to data clocked in	205	–	ns
t_{16}	MOE/ LOW to data clocked in	100	–	ns
t_{17}	Data hold from address, MOE/, MCE/ change	0	–	ns
t_{18}	Address out from MOE/, MCE/ HIGH	50	–	ns
t_{19}	Data setup to CLK HIGH	5	–	ns

Figure 6.31 Slow Memory (≥ 128 Kbytes) Read Cycle

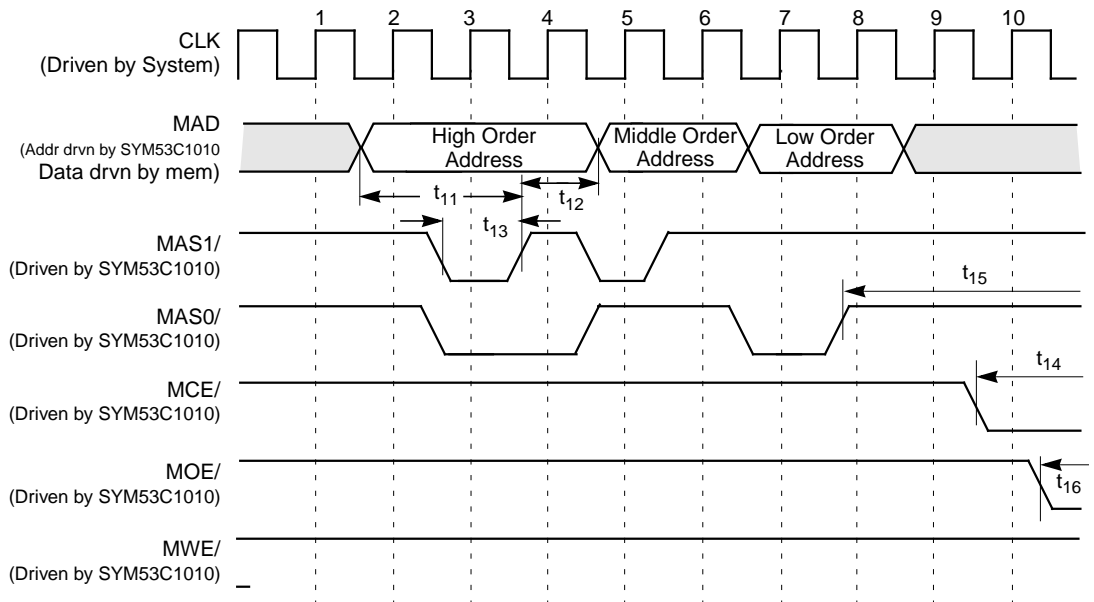


Figure 6.31 Slow Memory (≥ 128 Kbytes) Read Cycle (Cont.)

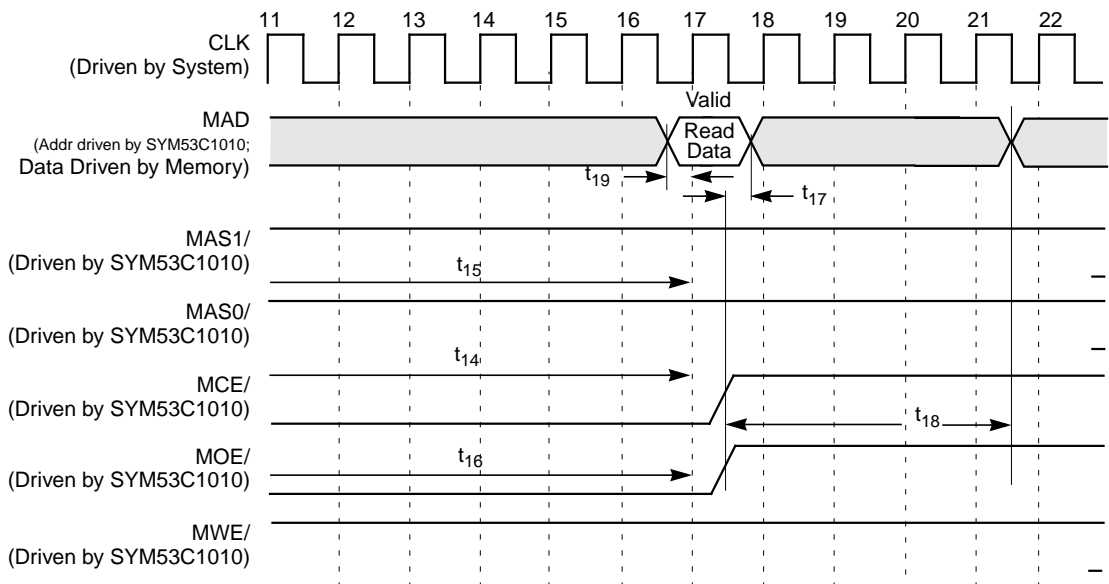


Table 6.36 Slow Memory (≥ 128 Kbytes) Write Cycle

Symbol	Parameter	Min	Max	Unit
t_{11}	Address setup to MAS/ HIGH	25	–	ns
t_{12}	Address hold from MAS/ HIGH	15	–	ns
t_{13}	MAS/ pulse width	25	–	ns
t_{20}	Data setup to MWE/ LOW	30	–	ns
t_{21}	Data hold from MWE/ HIGH	20	–	ns
t_{22}	MWE/ pulse width	100	–	ns
t_{23}	Address setup to MWE/ LOW	60	–	ns
t_{24}	MCE/ LOW to MWE/ HIGH	120	–	ns
t_{25}	MCE/ LOW to MWE/ LOW	25	–	ns
t_{26}	MWE/ HIGH to MCE/ HIGH	25	–	ns

Figure 6.32 Slow Memory (≥ 128 Kbytes) Write Cycle

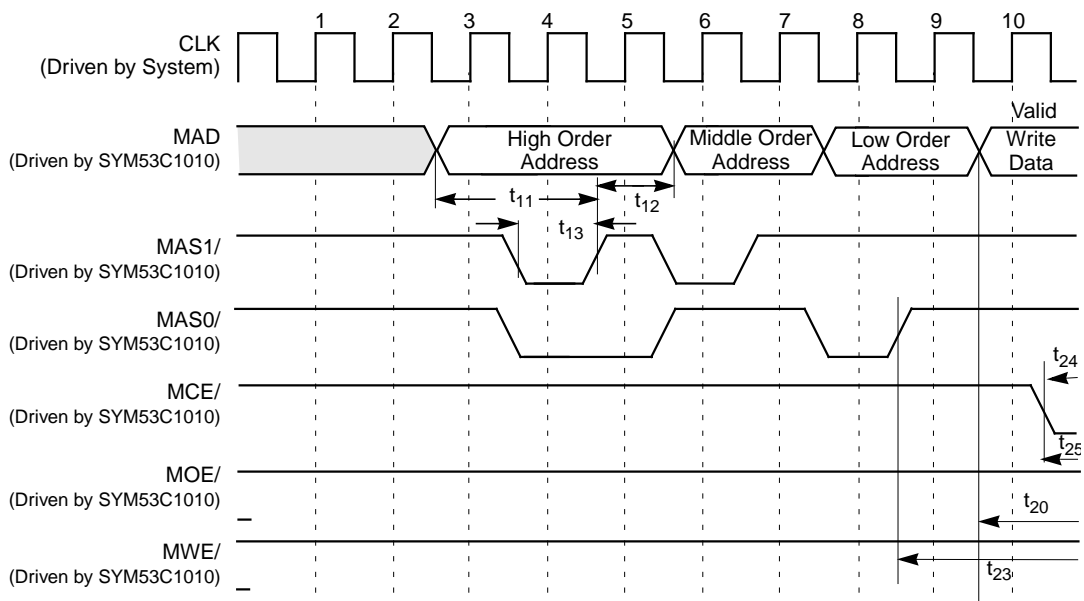


Figure 6.32 Slow Memory (≥ 128 Kbytes) Write Cycle (Cont.)

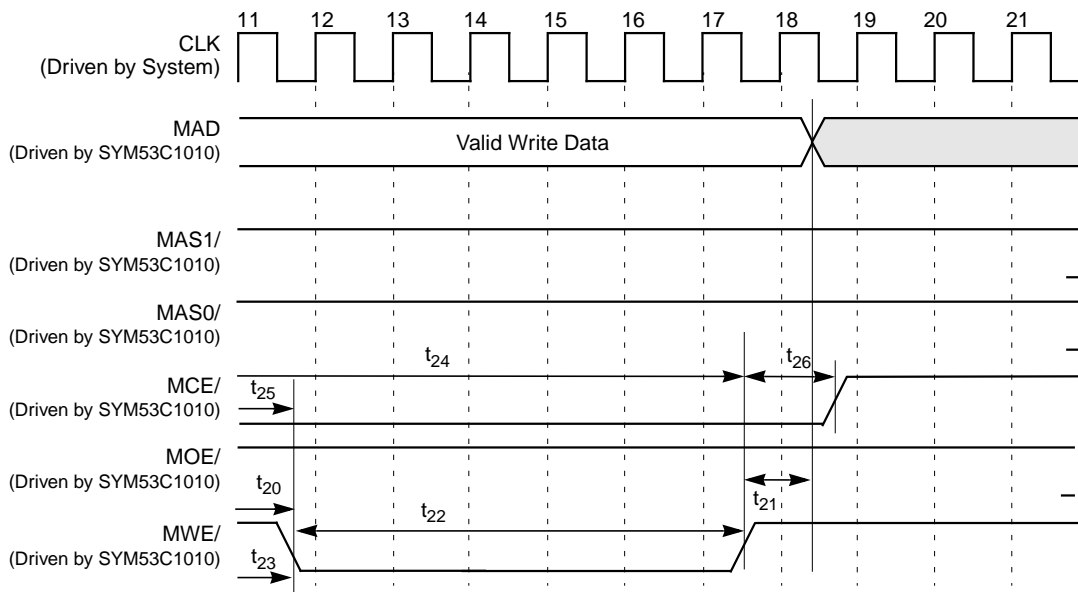


Table 6.37 ≤ 64 Kbytes ROM Read Cycle

Symbol	Parameter	Min	Max	Unit
t_{11}	Address setup to MAS/ HIGH	25	–	ns
t_{12}	Address hold from MAS/ HIGH	15	–	ns
t_{13}	MAS/ pulse width	25	–	ns
t_{14}	MCE/ LOW to data clocked in	150	–	ns
t_{15}	Address valid to data clocked in	205	–	ns
t_{16}	MOE/ LOW to data clocked in	100	–	ns
t_{17}	Data hold from address, MOE/, MCE/ change	0	–	ns
t_{18}	Address out from MOE/, MCE/ HIGH	50	–	ns
t_{19}	Data setup to CLK HIGH	5	–	ns

Figure 6.33 ≤ 64 Kbytes ROM Read Cycle

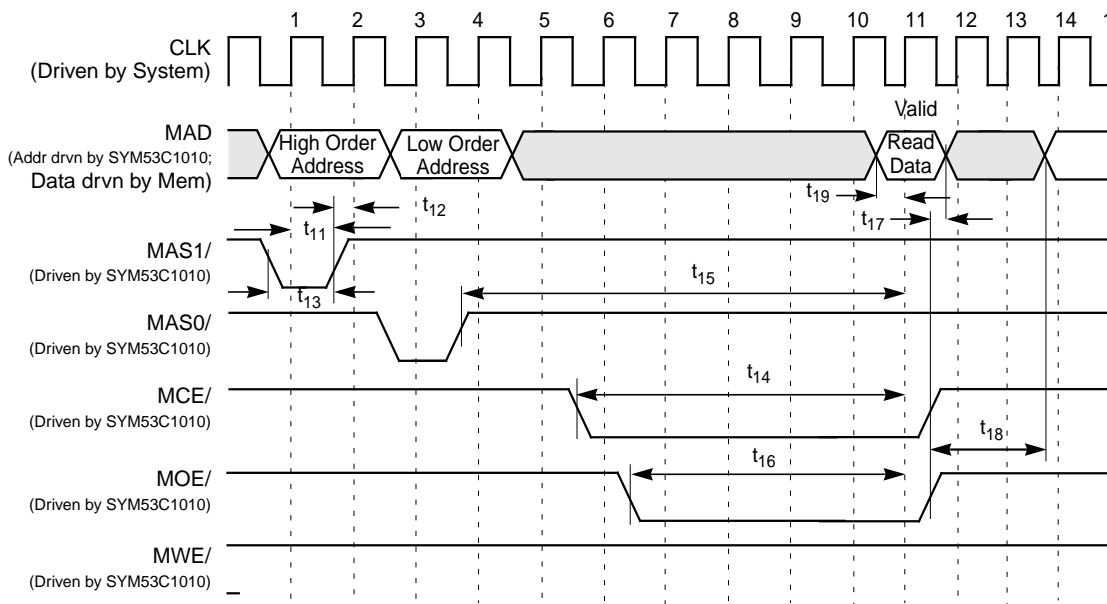
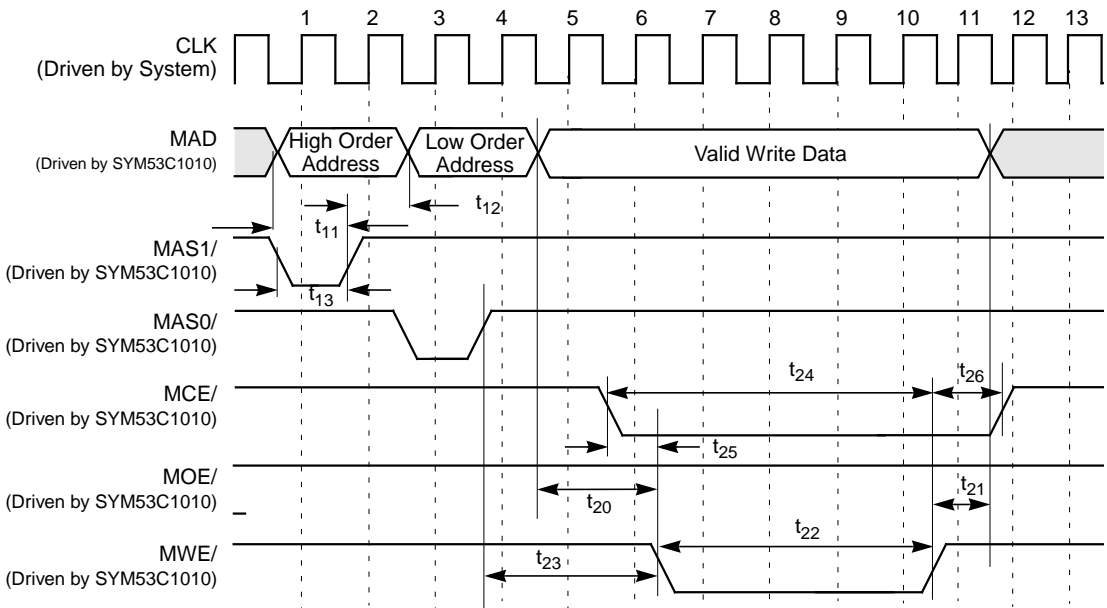


Table 6.38 ≤ 64 Kbytes ROM Write Cycle

Symbol	Parameter	Min	Max	Unit
t_{11}	Address setup to MAS/ HIGH	25	–	ns
t_{12}	Address hold from MAS/ HIGH	15	–	ns
t_{13}	MAS/ pulse width	25	–	ns
t_{20}	Data setup to MWE/ LOW	30	–	ns
t_{21}	Data hold from MWE/ HIGH	20	–	ns
t_{22}	MWE/ pulse width	100	–	ns
t_{23}	Address setup to MWE/ LOW	60	–	ns
t_{24}	MCE/ LOW to MWE/ HIGH	120	–	ns
t_{25}	MCE/ LOW to MWE/ LOW	25	–	ns
t_{26}	MWE/ HIGH to MCE/ HIGH	25	–	ns

Figure 6.34 ≤ 64 Kbytes ROM Write Cycle



6.5 SCSI Timing Diagrams

Figure 6.35 through Figure 6.40 represent signal activity on the SCSI bus. This section includes timing diagrams for asynchronous and synchronous access to the SCSI bus.

6.5.1 Asynchronous Timing

Table 6.39 Initiator Asynchronous Send

Symbol	Parameter	Min	Max	Units
t_1	SACK/ asserted from SREQ/ asserted	5	–	ns
t_2	SACK/ deasserted from SREQ/ deasserted	5	–	ns
t_3	Data setup to SACK/ asserted	55	–	ns
t_4	Data hold from SREQ/ deasserted	0	–	ns

Figure 6.35 Initiator Asynchronous Send

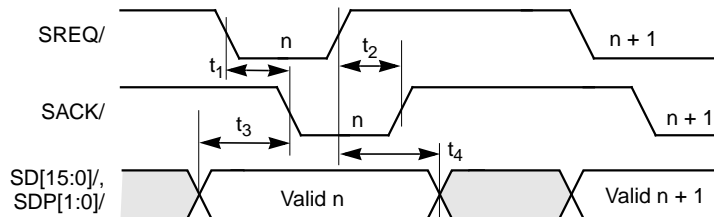


Table 6.40 Initiator Asynchronous Receive

Symbol	Parameter	Min	Max	Units
t_1	SACK/ asserted from SREQ/ asserted	5	–	ns
t_2	SACK/ deasserted from SREQ/ deasserted	5	–	ns
t_3	Data setup to SREQ/ asserted	0	–	ns
t_4	Data hold from SACK/ asserted	0	–	ns

Figure 6.36 Initiator Asynchronous Receive

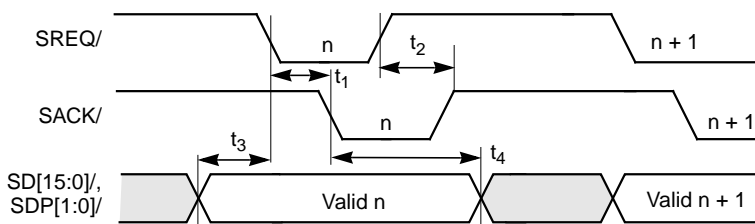


Table 6.41 Target Asynchronous Send

Symbol	Parameter	Min	Max	Units
t_1	SREQ/ deasserted from SACK/ asserted	5	–	ns
t_2	SREQ/ asserted from SACK/ deasserted	5	–	ns
t_3	Data setup to SREQ/ asserted	55	–	ns
t_4	Data hold from SACK/ asserted	0	–	ns

Figure 6.37 Target Asynchronous Send

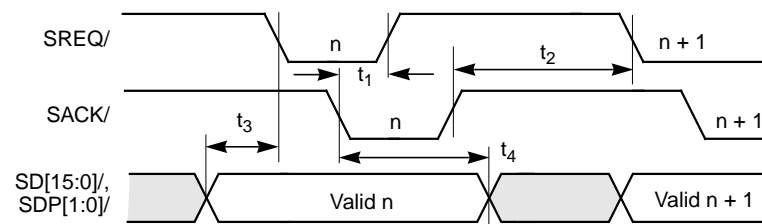
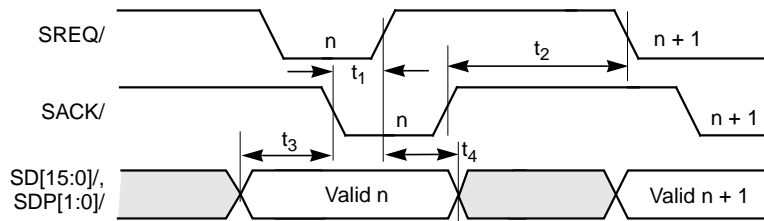


Table 6.42 Target Asynchronous Receive

Symbol	Parameter	Min	Max	Units
t_1	SREQ/ deasserted from SACK/ asserted	5	–	ns
t_2	SREQ/ asserted from SACK/ deasserted	5	–	ns
t_3	Data setup to SACK/ asserted	0	–	ns
t_4	Data hold from SREQ/ deasserted	0	–	ns

Figure 6.38 Target Asynchronous Receive



6.5.2 Synchronous Timing

6.5.2.1 Single Transition Data Clocking

Table 6.43 SCSI-1 Transfers (SE 5.0 Mbytes)

Symbol	Parameter	Min	Max	Units
t_{ST1}	Send SREQ/ or SACK/ assertion pulse width	80	–	ns
t_{ST2}	Send SREQ/ or SACK/ deassertion pulse width	80	–	ns
t_{ST1}	Receive SREQ/ or SACK/ assertion pulse width	70	–	ns
t_{ST2}	Receive SREQ/ or SACK/ deassertion pulse width	70	–	ns
t_{ST3}	Send data setup to SREQ/ or SACK/ asserted	24	–	ns
t_{ST4}	Send data hold from SREQ/ or SACK/ asserted	54	–	ns
t_{ST5}	Receive data setup to SREQ/ or SACK/ asserted	14	–	ns
t_{ST6}	Receive data hold from SREQ/ or SACK/ asserted	24	–	ns

Table 6.44 SCSI-2 Fast Transfers 10.0 Mbytes (8-Bit Transfers) or 20.0 Mbytes (16-Bit Transfers) 40 MHz Clock

Symbol	Parameter	Min	Max	Units
t_{ST1}	Send SREQ/ or SACK/ assertion pulse width	30	–	ns
t_{ST2}	Send SREQ/ or SACK/ deassertion pulse width	30	–	ns
t_{ST1}	Receive SREQ/ or SACK/ assertion pulse width	22	–	ns
t_{ST2}	Receive SREQ/ or SACK/ deassertion pulse width	22	–	ns
t_{ST3}	Send data setup to SREQ/ or SACK/ asserted	24	–	ns
t_{ST4}	Send data hold from SREQ/ or SACK/ asserted	34	–	ns
t_{ST5}	Receive data setup to SREQ/ or SACK/ asserted	14	–	ns
t_{ST6}	Receive data hold from SREQ/ or SACK/ asserted	24	–	ns

Table 6.45 Ultra SCSI SE Transfers 20.0 Mbytes (8-Bit Transfers) or 40.0 Mbytes (16-Bit Transfers) Quadrupled 40 MHz Clock¹

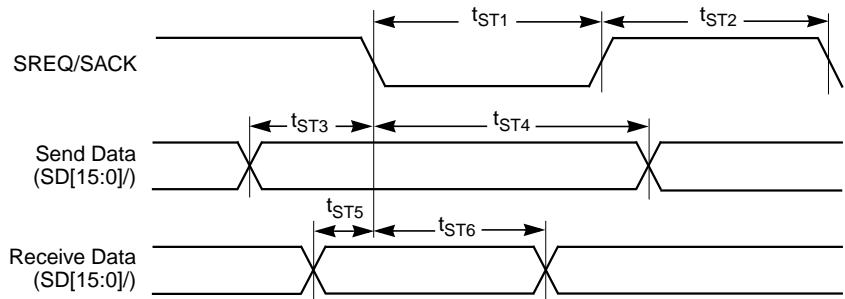
Symbol	Parameter	Min	Max	Unit
t _{ST1}	Send SREQ/ or SACK/ assertion pulse width	15	–	ns
t _{ST2}	Send SREQ/ or SACK/ deassertion pulse width	15	–	ns
t _{ST1}	Receive SREQ/ or SACK/ assertion pulse width	11	–	ns
t _{ST2}	Receive SREQ/ or SACK/ deassertion pulse width	11	–	ns
t _{ST3}	Send data setup to SREQ/ or SACK/ asserted	12	–	ns
t _{ST4}	Send data hold from SREQ/ or SACK/ asserted	17	–	ns
t _{ST5}	Receive data setup to SREQ/ or SACK/ asserted	6	–	ns
t _{ST6}	Receive data hold from SREQ/ or SACK/ asserted	11	–	ns

1. Note: for fast SCSI, set the TolerANT Enable bit (bit 7 in [SCSI Test Three \(STEST3\)](#)).

Table 6.46 Ultra2 SCSI Transfers 40.0 Mbyte (8-Bit Transfers) or 80.0 Mbyte (16-Bit Transfers) Quadrupled 40 MHz Clock

Symbol	Parameter	Min	Max	Unit
t _{ST1}	Send SREQ/ or SACK/ assertion pulse width	8	–	ns
t _{ST2}	Send SREQ/ or SACK/ deassertion pulse width	8	–	ns
t _{ST1}	Receive SREQ/ or SACK/ assertion pulse width	6.5	–	ns
t _{ST2}	Receive SREQ/ or SACK/ deassertion pulse width	6.5	–	ns
t _{ST3}	Send data setup to SREQ/ or SACK/ asserted	9.5	–	ns
t _{ST4}	Send data hold from SREQ/ or SACK/ asserted	9.5	–	ns
t _{ST5}	Receive data setup to SREQ/ or SACK/ asserted	4.5	–	ns
t _{ST6}	Receive data hold from SREQ/ or SACK/ asserted	4.5	–	ns

Figure 6.39 Initiator and Target ST Synchronous Transfer



6.5.2.2 Double Transition Data Clocking

Table 6.47 SCSI-2 Fast Transfers 10.0 Mbytes (8-Bit Transfers) or 20.0 Mbytes (16-Bit Transfers) 40 MHz Clock

Symbol	Parameter	Min	Max	Unit
t_{DT1}	Send SREQ/ or SACK/ assertion pulse width	92	–	ns
t_{DT2}	Send SREQ/ or SACK/ deassertion pulse width	92	–	ns
t_{DT1}	Receive SREQ/ or SACK/ assertion pulse width	80	–	ns
t_{DT2}	Receive SREQ/ or SACK/ deassertion pulse width	80	–	ns
t_{DT3}	Send data setup to SREQ/ or SACK/ transition	40	–	ns
t_{DT4}	Send data hold from SREQ/ or SACK/ transition	40	–	ns
t_{DT5}	Receive data setup to SREQ/ or SACK/ transition	10	–	ns
t_{DT6}	Receive data hold from SREQ/ or SACK/ transition	10	–	ns
t_{DT7}	Send CRC Request Setup to SREQ/ transition	50	–	ns
t_{DT8}	Send CRC Request Hold to SREQ/ transition	40	–	ns
t_{DT9}	Receive CRC Request Setup to SREQ/ transition	17	–	ns
t_{DT10}	Receive CRC Request Hold to SREQ/ transition	10	–	ns

Table 6.48 Ultra SCSI SE Transfers 20.0 Mbytes (8-Bit Transfers) or 40.0 Mbytes (16-Bit Transfers) Quadrupled 40 MHz Clock

Symbol	Parameter	Min	Max	Unit
t _{DT1}	Send SREQ/ or SACK/ assertion pulse width	46	–	ns
t _{DT2}	Send SREQ/ or SACK/ deassertion pulse width	46	–	ns
t _{DT1}	Receive SREQ/ or SACK/ assertion pulse width	40	–	ns
t _{DT2}	Receive SREQ/ or SACK/ deassertion pulse width	40	–	ns
t _{DT3}	Send data setup to SREQ/ or SACK/ transition	20	–	ns
t _{DT4}	Send data hold from SREQ/ or SACK/ transition	20	–	ns
t _{DT5}	Receive data setup to SREQ/ or SACK/ transition	5	–	ns
t _{DT6}	Receive data hold from SREQ/ or SACK/ transition	5	–	ns
t _{DT7}	Send CRC Request Setup to SREQ/ transition	30	–	ns
t _{DT8}	Send CRC Request Hold to SREQ/ transition	20	–	ns
t _{DT9}	Receive CRC Request Setup to SREQ/ transition	12	–	ns
t _{DT10}	Receive CRC Request Hold to SREQ/ transition	5	–	ns

Table 6.49 Ultra2 SCSI Transfers 40.0 Mbyte (8-Bit Transfers) or 80.0 Mbyte (16-Bit Transfers) Quadrupled 40 MHz Clock

Symbol	Parameter	Min	Max	Unit
t_{DT1}	Send SREQ/ or SACK/ assertion pulse width	23	–	ns
t_{DT2}	Send SREQ/ or SACK/ deassertion pulse width	23	–	ns
t_{DT1}	Receive SREQ/ or SACK/ assertion pulse width	20	–	ns
t_{DT2}	Receive SREQ/ or SACK/ deassertion pulse width	20	–	ns
t_{DT3}	Send data setup to SREQ/ or SACK/ transition	10	–	ns
t_{DT4}	Send data hold from SREQ/ or SACK/ transition	10	–	ns
t_{DT5}	Receive data setup to SREQ/ or SACK/ transition	2.5	–	ns
t_{DT6}	Receive data hold from SREQ/ or SACK/ transition	2.5	–	ns
t_{DT7}	Send CRC Request Setup to SREQ/ transition	20	–	ns
t_{DT8}	Send CRC Request Hold to SREQ/ transition	10	–	ns
t_{DT9}	Receive CRC Request Setup to SREQ/ transition	9.5	–	ns
t_{DT10}	Receive CRC Request Hold to SREQ/ transition	2.5	–	ns

**Table 6.50 Ultra3 SCSI Transfers 160.0 Mbyte (16-Bit Transfers)
Quadrupled 40 MHz Clock**

Symbol	Parameter	Min	Max	Unit
t_{DT1}	Send SREQ/ or SACK/ assertion pulse width	11.5	–	ns
t_{DT2}	Send SREQ/ or SACK/ deassertion pulse width	11.5	–	ns
t_{DT1}	Receive SREQ/ or SACK/ assertion pulse width	10	–	ns
t_{DT2}	Receive SREQ/ or SACK/ deassertion pulse width	10	–	ns
t_{DT3}	Send data setup to SREQ/ or SACK/ transition	5	–	ns
t_{DT4}	Send data hold from SREQ/ or SACK/ transition	5	–	ns
t_{DT5}	Receive data setup to SREQ/ or SACK/ transition	1.25	–	ns
t_{DT6}	Receive data hold from SREQ/ or SACK/ transition	1.25	–	ns
t_{DT7}	Send CRC Request Setup to SREQ/ transition	15	–	ns
t_{DT8}	Send CRC Request Hold to SREQ/ transition	5	–	ns
t_{DT9}	Receive CRC Request Setup to SREQ/ transition	8.25	–	ns
t_{DT10}	Receive CRC Request Hold to SREQ/ transition	1.25	–	ns

Figure 6.40 Initiator and Target DT Synchronous Transfer

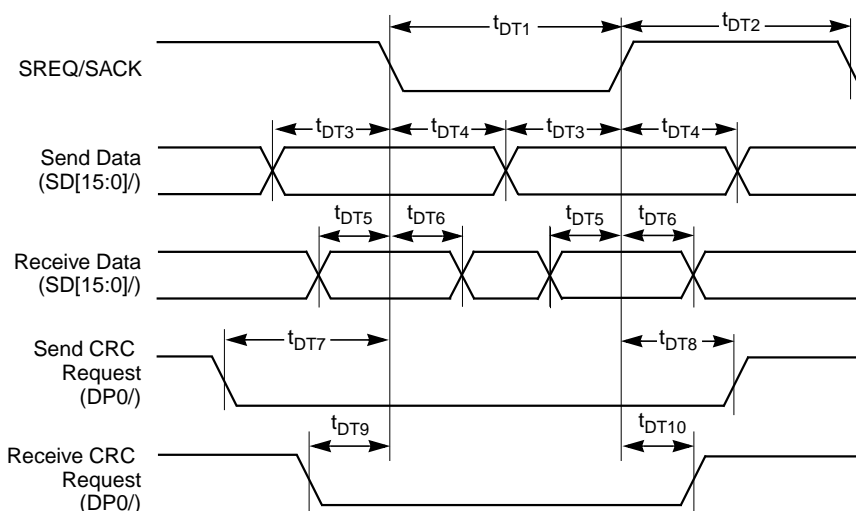


Figure 6.41 SYM53C1010-33 329 Ball Grid Array (Bottom View)

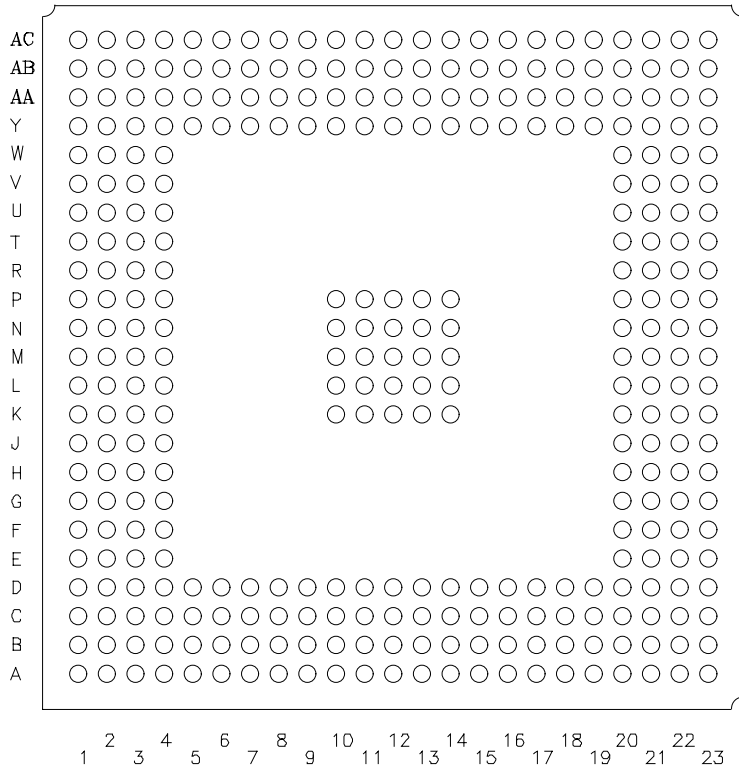
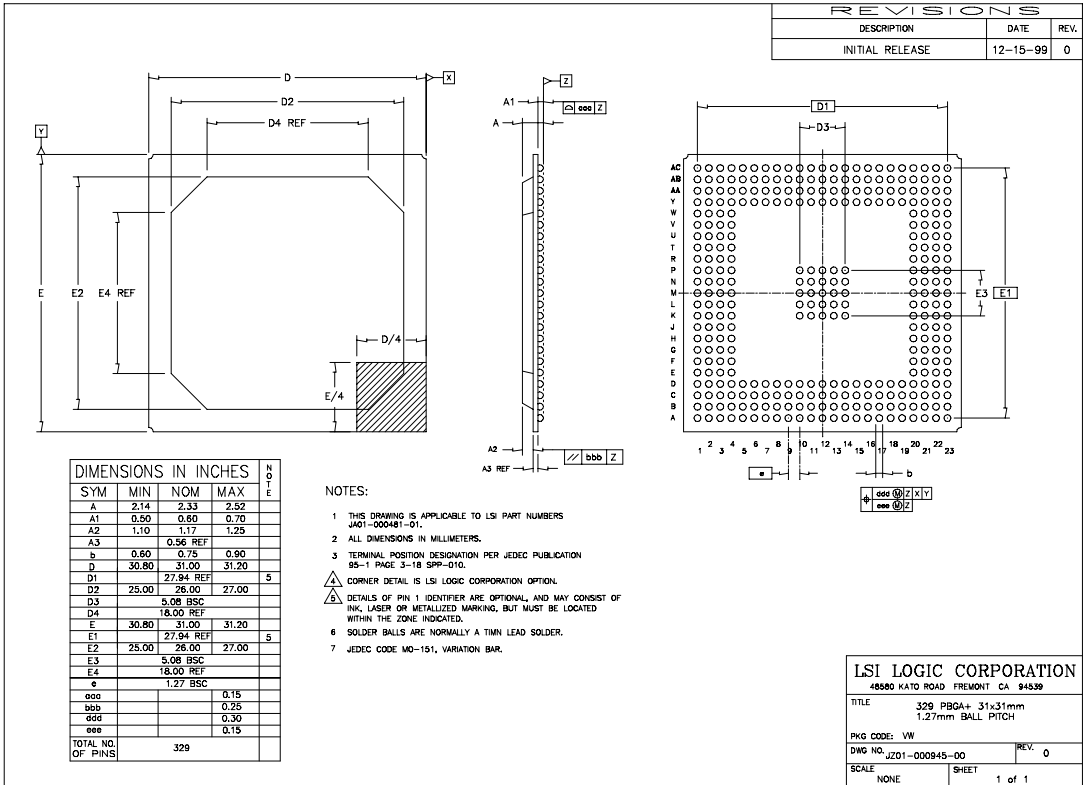


Figure 6.42 SYM53C1010-33 329 BGA Mechanical Drawing



Important: This drawing may not be the latest version. For board layout and manufacturing, obtain the most recent engineering drawings from your LSI Logic marketing representative by requesting the outline drawing for package code VW.

Appendix A

Register Summary

Table A.1 SYM53C1010-33 PCI Register Map

Register Name	Address	Read/Write	Page
PCI Registers			
Vendor ID	0x00–0x01	Read Only	4-3
Device ID	0x02–0x03	Read Only	4-3
Command	0x04–0x05	Read/Write	4-3
Status	0x06–0x07	Read/Write	4-5
Revision ID (RID)	0x08	Read Only	4-7
Class Code (CC)	0x09–0x0B	Read Only	4-7
Cache Line Size (CLS)	0x0C	Read/Write	4-7
Latency Timer (LT)	0x0D	Read/Write	4-8
Header Type (HT)	0x0E	Read Only	4-9
Reserved	0x0F	–	4-9
Base Address Register Zero (BAR0) (I/O)	0x10–0x13	Read/Write	4-9
Base Address Register One (BAR1) (MEMORY)	0x14–0x17	Read/Write	4-10
Base Address Register Two (BAR2) (MEMORY)	0x18–0x1B	Read/Write	4-10
Base Address Register Three (BAR3) (SCRIPTS RAM)	0x1C–0x1F	Read/Write	4-11
Base Address Register Four (BAR4) (SCRIPTS RAM)	0x20–0x23	Read/Write	4-11
Reserved	0x24–0x27	–	4-12
Reserved	0x28–0x2B	–	4-12
Subsystem Vendor ID (SVID)	0x2C–0x2D	Read Only	4-12

Table A.1 SYM53C1010-33 PCI Register Map (Cont.)

Register Name	Address	Read/Write	Page
Subsystem ID (SID)	0x2E–0x2F	Read Only	4-13
Expansion ROM Base Address (ERBA)	0x30–0x33	Read/Write	4-14
Capabilities Pointer (CP)	0x34	Read Only	4-15
Reserved	0x35–0x37	–	4-15
Reserved	0x38–0x3B	–	4-15
Interrupt Line (IL)	0x3C	Read/Write	4-16
Interrupt Pin (IP)	0x3D	Read Only	4-16
Min_Gnt (MG)	0x3E	Read Only	4-17
Max_Lat (ML)	0x3F	Read Only	4-17
Capability ID (CID)	0x40	Read Only	4-18
Next Item Pointer (NIP)	0x41	Read Only	4-18
Power Management Capabilities (PMC)	0x42–0x43	Read Only	4-18
Power Management Control/Status (PMCSR)	0x44–0x45	Read/Write	4-20
Bridge Support Extensions (PMCSR_BSE)	0x46	Read Only	4-21
Data	0x47	Read Only	4-21

Table A.2 SYM53C1010-33 SCSI Register Map

Register Name	Address	Read/Write	Page
SCSI Registers			
SCSI Control Zero (SCNTL0)	0x00	Read/Write	4-24
SCSI Control One (SCNTL1)	0x01	Read/Write	4-28
SCSI Control Two (SCNTL2)	0x02	Read/Write	4-30
SCSI Control Three (SCNTL3)	0x03	Read/Write	4-32
SCSI Chip ID (SCID)	0x04	Read/Write	4-33
SCSI Transfer (SXFER)	0x05	Read/Write	4-34

Table A.2 SYM53C1010-33 SCSI Register Map (Cont.)

Register Name	Address	Read/Write	Page
SCSI Destination ID (SDID)	0x06	Read/Write	4-35
General Purpose (GPREG)	0x07	Read/Write	4-36
SCSI First Byte Received (SFBR)	0x08	Read/Write	4-37
SCSI Output Control Latch (SOCL)	0x09	Read/Write	4-38
SCSI Selector ID (SSID)	0x0A	Read Only	4-39
SCSI Bus Control Lines (SBCL)	0x0B	Read Only	4-40
DMA Status (DSTAT)	0x0C	Read Only	4-40
SCSI Status Zero (SSTAT0)	0x0D	Read Only	4-43
SCSI Status One (SSTAT1)	0x0E	Read Only	4-45
SCSI Status Two (SSTAT2)	0x0F	Read Only	4-46
Data Structure Address (DSA)	0x10–0x13	Read/Write	4-47
Interrupt Status Zero (ISTAT0)	0x14	Read/Write	4-47
Interrupt Status One (ISTAT1)	0x15	Read/Write	4-51
Mailbox Zero (MBOX0)	0x16	Read/Write	4-52
Mailbox One (MBOX1)	0x17	Read/Write	4-52
Chip Test Zero (CTEST0)	0x18	Read/Write	4-53
Chip Test One (CTEST1)	0x19	Read Only	4-53
Chip Test Two (CTEST2)	0x1A	Read Only (bit 3 write)	4-54
Chip Test Three (CTEST3)	0x1B	Read/Write	4-55
Temporary (TEMP)	0x1C–0x1F	Read/Write	4-56
Reserved	0x20	–	4-57
Chip Test Four (CTEST4)	0x21	Read/Write	4-57
Chip Test Five (CTEST5)	0x22	Read/Write	4-59
Chip Test Six (CTEST6)	0x23	Read/Write	4-60
DMA Byte Counter (DBC)	0x24–0x26	Read/Write	4-61

Table A.2 SYM53C1010-33 SCSI Register Map (Cont.)

Register Name	Address	Read/Write	Page
DMA Command (DCMD)	0x27	Read/Write	4-62
DMA Next Address (DNAD)	0x28–0x2B	Read/Write	4-62
DMA SCRIPTS Pointer (DSP)	0x2C–0x2F	Read/Write	4-63
DMA SCRIPTS Pointer Save (DSPS)	0x30–0x33	Read/Write	4-63
Scratch Register A (SCRATCHA)	0x34–0x37	Read/Write	4-64
DMA Mode (DMODE)	0x38	Read/Write	4-64
DMA Interrupt Enable (DIEN)	0x39	Read/Write	4-67
Scratch Byte Register (SBR)	0x3A	Read/Write	4-68
DMA Control (DCNTL)	0x3B	Read/Write	4-68
Adder Sum Output (ADDER)	0x3C–0x3F	Read Only	4-71
SCSI Interrupt Enable Zero (SIEN0)	0x40	Read/Write	4-71
SCSI Interrupt Enable One (SIEN1)	0x41	Read/Write	4-73
SCSI Interrupt Status Zero (SIST0)	0x42	Read Only	4-75
SCSI Interrupt Status One (SIST1)	0x43	Read Only	4-78
Reserved	0x44	–	4-79
SCSI Wide Residue (SWIDE)	0x45	Read/Write	4-79
Reserved	0x46	–	4-79
General Purpose Pin Control (GPCNTL)	0x47	Read/Write	4-80
SCSI Timer Zero (STIME0)	0x48	Read/Write	4-81
SCSI Timer One (STIME1)	0x49	Read/Write	4-82
Response ID Zero (RESPID0)	0x4A	Read/Write	4-84
Response ID One (RESPID1)	0x4B	Read/Write	4-84
SCSI Test Zero (STEST0)	0x4C	Read Only	4-85
SCSI Test One (STEST1)	0x4D	Read/Write	4-86
SCSI Test Two (STEST2)	0x4E	Read/Write	4-87

Table A.2 SYM53C1010-33 SCSI Register Map (Cont.)

Register Name	Address	Read/Write	Page
SCSI Test Three (STEST3)	0x4F	Read/Write	4-89
SCSI Input Data Latch (SIDL)	0x50–0x51	Read Only	4-90
SCSI Test Four (STEST4)	0x52	Read Only	4-91
Current Inbound SCSI Offset (CSO)	0x53	Read Only	4-92
SCSI Output Data Latch (SODL)	0x54–0x55	Read/Write	4-92
Chip Control Zero (CCNTL0)	0x56	Read/Write	4-93
Chip Control One (CCNTL1)	0x57	Read/Write	4-95
SCSI Bus Data Lines (SBDL)	0x58–0x59	Read Only	4-96
Reserved	0x5A	–	4-97
Chip Control Three (CCNTL3)	0x5B	Read/Write	4-97
Scratch Register B (SCRATCHB)	0x5C–0x5F	Read/Write	4-98
Scratch Registers C–R (SCRATCHC–SCRATCHR)	0x60–0x9F	Read/Write	4-99
Memory Move Read Selector (MMRS)	0xA0–0xA3	Read/Write	4-99
Memory Move Write Selector (MMWS)	0xA4–0xA7	Read/Write	4-100
SCRIPT Fetch Selector (SFS)	0xA8–0xAB	Read/Write	4-100
DSA Relative Selector (DRS)	0xAC–0xAF	Read/Write	4-101
Static Block Move Selector (SBMS)	0xB0–0xB3	Read/Write	4-101
Dynamic Block Move Selector (DBMS)	0xB4–0xB7	Read/Write	4-102
DMA Next Address 64 (DNAD64)	0xB8–0xBB	Read/Write	4-102
SCSI Control Four (SCNTL4)	0xBC	Read/Write	4-102
Reserved	0xBD	–	4-111
AIP Control Zero (AIPCNTL0)	0xBE	Read/Write	4-111
AIP Control One (AIPCNTL1)	0xBF	Read/Write	4-112
Phase Mismatch Jump Registers			
Phase Mismatch Jump Address One (PMJAD1)	0xC0–0xC3	Read/Write	4-112

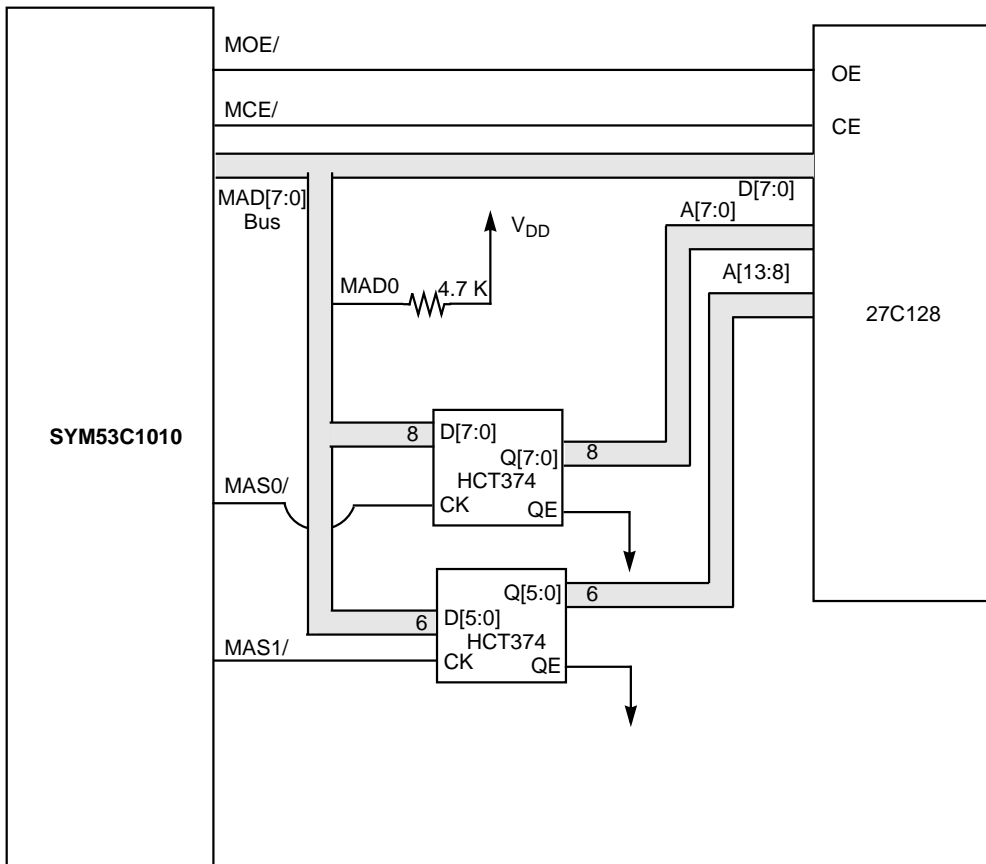
Table A.2 SYM53C1010-33 SCSI Register Map (Cont.)

Register Name	Address	Read/Write	Page
Phase Mismatch Jump Address Two (PMJAD2)	0xC4–0xC7	Read/Write	4-113
Remaining Byte Count (RBC)	0xC8–0xCB	Read/Write	4-113
Updated Address (UA)	0xCC–0xCF	Read/Write	4-114
Entry Storage Address (ESA)	0xD0–0xD3	Read/Write	4-115
Instruction Address (IA)	0xD4–0xD7	Read/Write	4-115
SCSI Byte Count (SBC)	0xD8–0xDA	Read Only	4-116
Reserved	0xDB	–	4-116
Cumulative SCSI Byte Count (CSBC)	0xDC–0xDF	Read/Write	4-117
CRC Pad Byte Value (CRCPAD)	0xE0–0xE1	Read/Write	4-117
CRC Control Zero (CRCCNTL0)	0xE2	Read/Write	4-118
CRC Control One (CRCCNTL1)	0xE3	Read/Write	4-119
CRC Data (CRCD)	0xE4–0xE7	Read/Write	4-120
Reserved	0xE8–0xEF	–	4-121
DMA FIFO Byte Count (DFBC)	0xF0–0xF1	Read Only	4-122
Reserved	0xF2–0xF3	–	4-122
Reserved	0xF4–0xFF	–	4-122
Shadow Registers			
Shadowed Scratch Register A (SCRATCHA)	0x34–0x37	Read/Write	4-123
Shadowed SCSI SGE Status 0	0x42	Read/Write	4-123
Shadowed SCSI Interrupt Status One (SIST1)	0x43	Read Only	4-124
Shadowed Scratch Register B (SCRATCHB)	0x5C–0x5F	Read/Write	4-125
Shadowed Scratch Registers C–R (SCRATCHC–SCRATCHR)	0x60–0x9F	Read/Write	4-125
Shadowed Memory Move Read Selector (MMRS)	0xA0–0xA3	Read/Write	4-125
Shadowed Memory Move Write Selector (MMWS)	0xA4–0xA7	Read/Write	4-126
Shadowed SCRIPT Fetch Selector (SFS)	0xA8–0xAB	Read/Write	4-126

Appendix B

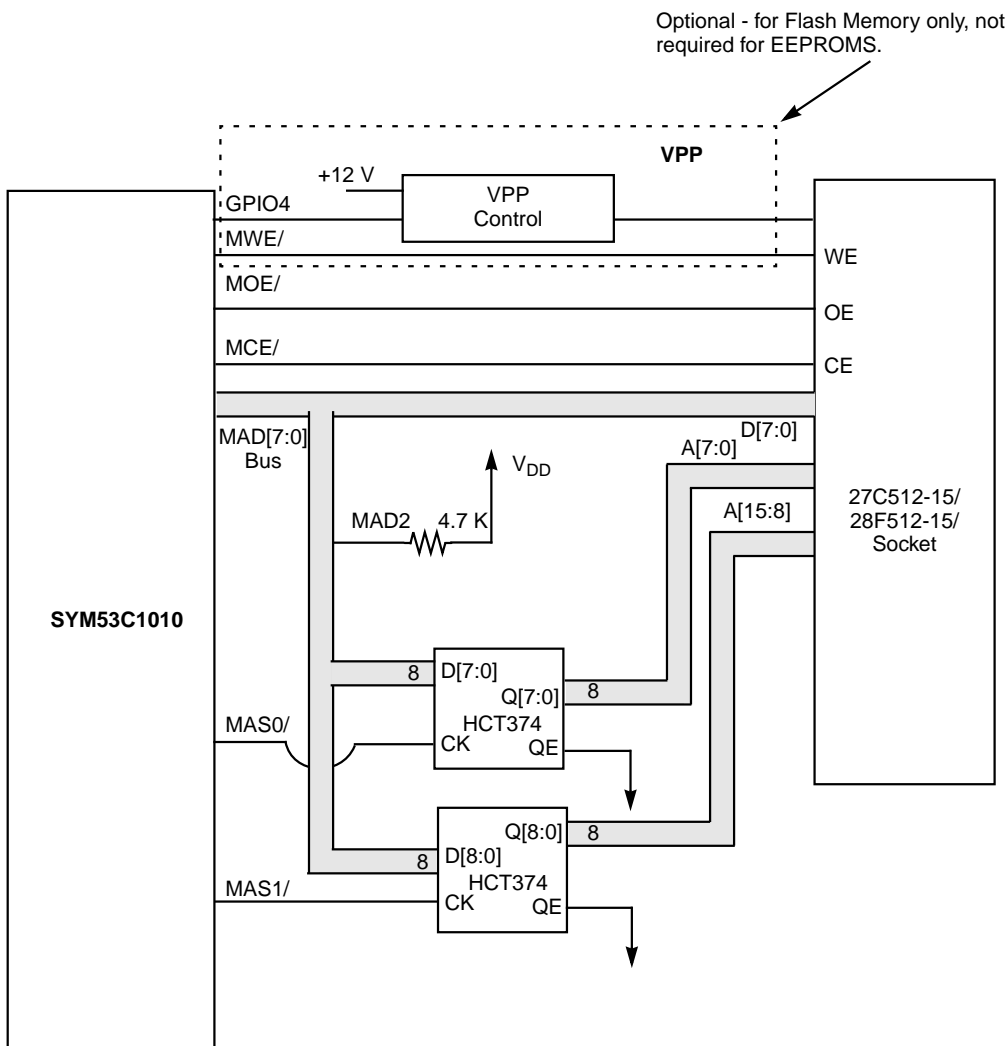
External Memory Interface Diagram Examples

Figure B.1 16 Kbyte Interface with 200 ns Memory



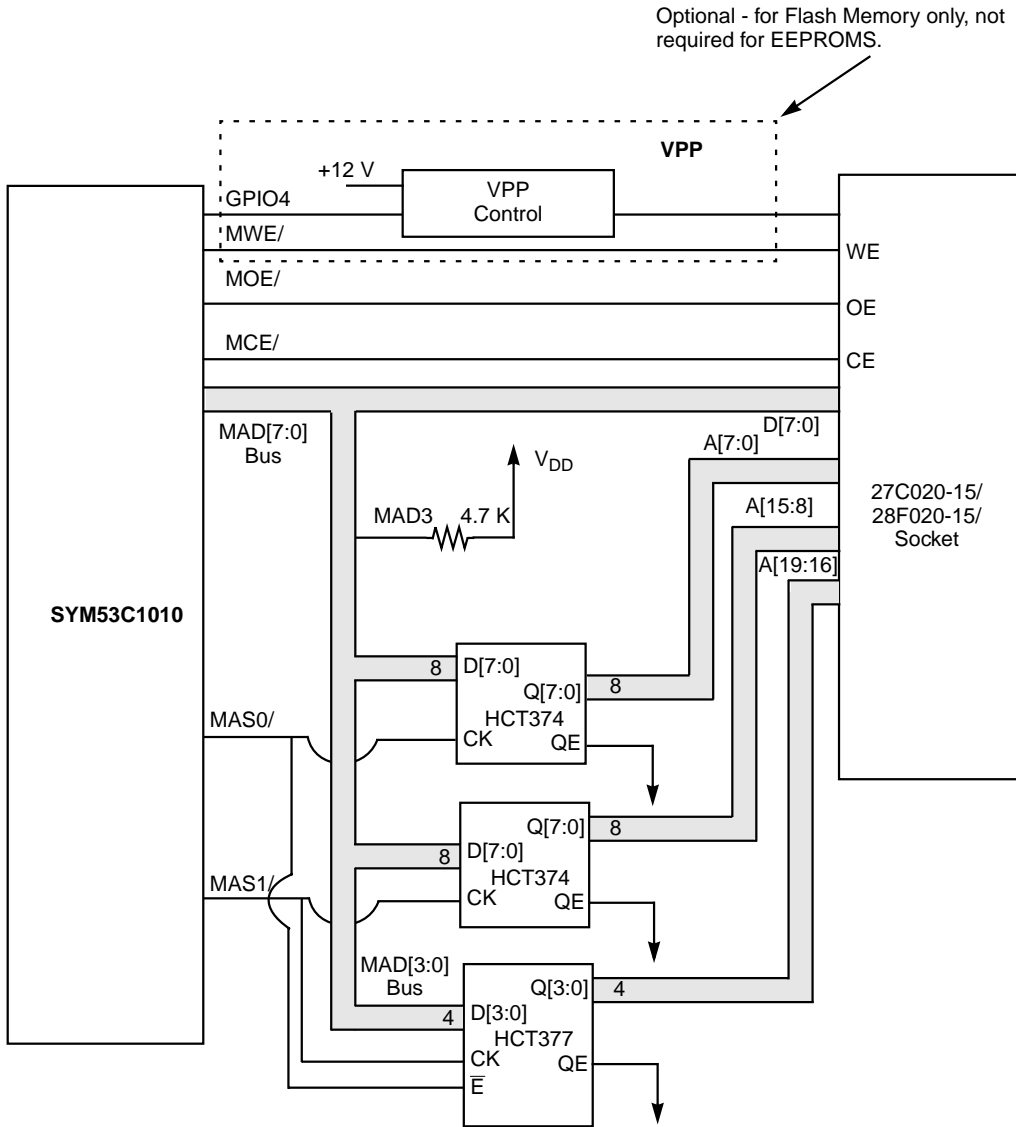
Note: MAD[3:1] pulled low internally. MAD bus sense logic enabled for 16 Kbyte of slow memory (200 ns devices @ 33 MHz).

Figure B.2 64 Kbyte Interface with 150 ns Memory



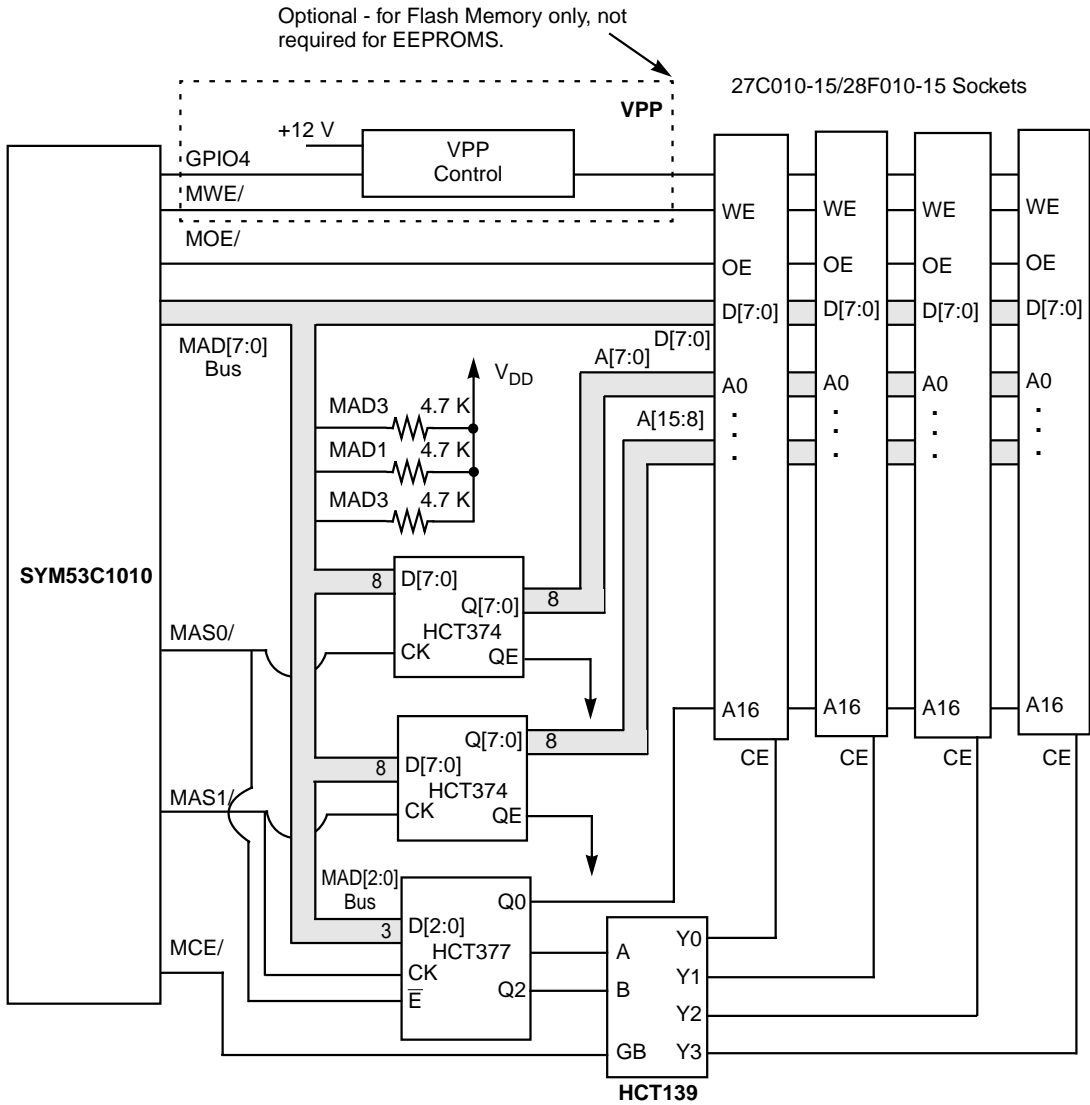
Note: MAD 3, 1, 0 pulled low internally. MAD bus sense logic enabled for 64 Kbyte of fast memory (150 ns devices @ 33 MHz).

Figure B.3 128, 256, 512 Kbyte or 1 Mbyte Interface with 150 ns Memory



Note: MAD[2:0] pulled low internally. MAD bus sense logic enabled for 128, 256, 512 Kbytes, or 1 Mbyte of fast memory (150 ns devices @ 33 MHz). The HCT374s may be replaced with HCT377s.

Figure B.4 512 Kbyte Interface with 150 ns Memory



Note: MAD2 pulled low internally. MAD bus sense logic enabled for 512 Kbytes of slow memory (150 ns devices, additional time required for HCT139 @ 33 MHz). The HCT374s may be replaced with HCT377s.

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B. M. Tel: 972.783.4191
W. E. Tel: 800.955.9953
El Paso
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Houston
A. E. Tel: 713.781.6100
B. M. Tel: 713.917.0663
W. E. Tel: 800.888.9953
Richardson
I. E. Tel: 972.783.0800
Rio Grande Valley
A. E. Tel: 210.412.2047
Stafford
I. E. Tel: 281.277.8200

Utah

Centerville
B. M. Tel: 801.295.3900
Murray
I. E. Tel: 801.288.9001
Salt Lake City
A. E. Tel: 801.365.3800
W. E. Tel: 800.477.9953

Vermont

A. E. Tel: 800.272.9255
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B. M. Tel: 703.754.3399
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A. E. Tel: 425.882.7000
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Wauwatosa
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E. A. Earle Associates
E. L. Electrodyne - UT
GRP Group 2000
I. S. Infinity Sales, Inc.
ION ION Associates, Inc.
R. A. Rathsburg Associates, Inc.
SGY Synergy Associates, Inc.

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I. S. Tel: 714.833.0300
San Diego
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Illinois

Elmhurst
R. A. Tel: 630.516.8400

Indiana

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Ligonier
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Plainfield
R. A. Tel: 317.838.0360

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Good Rich
R. A. Tel: 810.636.6060
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