

Objective Specification

Linear Products

DESCRIPTION

The TDA8432 is an I²C bus-controlled deflection processor (analog picture geometry processor) which contains the control and drive functions of the deflection circuits in a computer-controlled TV (CCTV) or monitor. This IC replaces all picture geometry settings which are performed manually during manufacturing. The alignment of 10 picture geometry parameters for the vertical and horizontal deflection is accomplished by means of a microcontroller via the I²C bus. Furthermore, it eliminates the external components needed for adjusting the horizontal frequency and phase position, vertical linearity, picture height, east-west parabola, and picture width. The east-west shaping circuit is also eliminated. Provisions have been incorporated to make several sync processor (TDA2579 and TDA2595) functions I²C bus-controllable.

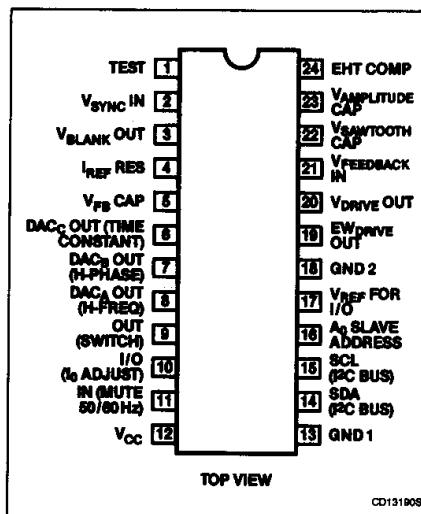
FEATURES

- I²C bus interface for all functions
- Input for vertical sync from sync processor
- Vertical sawtooth generator with frequency-independent amplitude
- Vertical output stage with feedback input for driving a vertical deflection amplifier
- East-west raster correction drive output
- EHT modulation input, providing optimum picture geometry compensation for static and dynamic EHT load variations
- I²C bus-controlled alignment of 10 deflection parameters
- Provisions for controlling a sync processing IC which does not have an I²C bus interface, including:
 - Two digital-to-analog converters for alignment of the free-running horizontal frequency and horizontal phase position
 - An I/O pin enabling computer alignment of the free-running horizontal frequency
 - A special purpose 4-level output for time constant switching of the horizontal phase-locked loop
 - A special purpose 3-level input for detection of the mute function and the 50Hz/60Hz state of the sync processor
- A switchable output (e.g., for controlling a video source selector)

APPLICATIONS

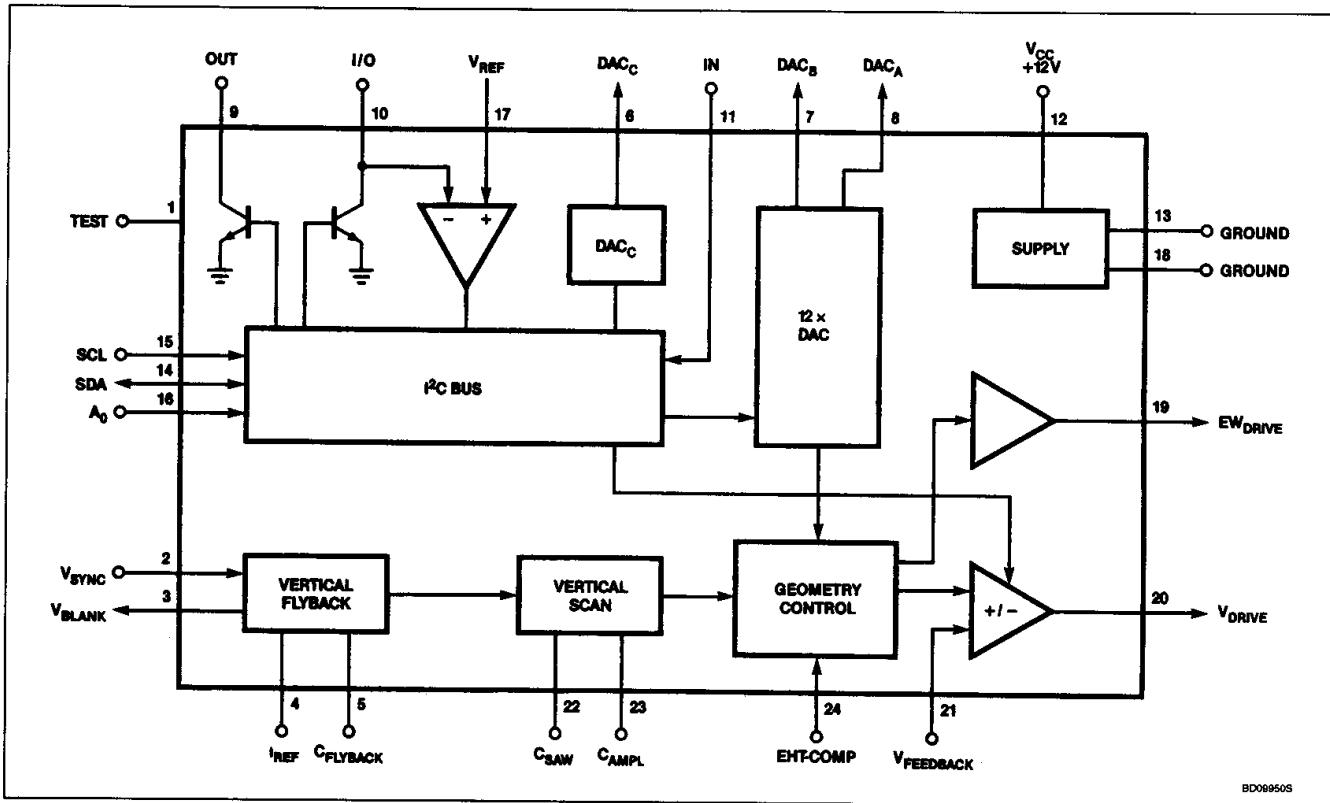
- Video monitors
- Color TV receivers

PIN CONFIGURATION



Computer-Controlled Deflection Processor for Video Displays TDA8432

BLOCK DIAGRAM



BD00950S

Computer-Controlled Deflection Processor for Video Displays TDA8432

ABSOLUTE MAXIMUM RATINGS

SYMBOL	PARAMETER	RATING	UNIT
V _{CC}	Supply voltage (Pin 17)	14	V
	Switching voltage (Pin 5)	8	V
	Output currents of each pin to ground (Pins 11 and 12)	-10	mA
	Maximum short-circuit time outputs	10	sec
T _{STG}	Storage temperature	-55 to +150	°C
T _A	Operating temperature	-25 to 80	°C
T _J	Junction temperature	+150	°C
θ _{JA}	Thermal resistance	75	°C/W

RECOMMENDED OPERATING CONDITIONS In application circuit Figure 1 at T_A = 25°C and V_{CC} = 12V, unless otherwise specified.

SYMBOL	PARAMETER	LIMITS			UNIT
		Min	Typ	Max	
V _{CC}	Supply voltage (Pins 17 – 20, 10)	10		13.2	V
I _{CC}	Supply current (Pin 17)		42	55	mA
	Switching voltage VHF (Pin 5)	0		1.5	V
	Switching voltage hyperband	2		3.5	V
	Switching voltage UHF (Pin 5)	4		5	V
	Switching current UHF (Pin 15)			0.2	mA

DC ELECTRICAL CHARACTERISTICS

SYMBOL	PARAMETER	LIMITS			UNIT
		Min	Typ	Max	
VHF mixer including IF, measurement in circuit of Figure 1					
f _R	Frequency range: printed circuit board	50		300	MHz
	Noise Figure 1 (Pin 23) 50MHz 225MHz 300MHz		7.5 9 10	9 10 12	dB dB dB
	Optimum source admittance (Pin 23) 50MHz 225MHz 300MHz		0.5 1.1 1.2		mmho mmho mmho
	Input conductance (Pin 23) 50MHz 225MHz 300MHz		0.23 0.5 0.67		mmho mmho mmho
C _{IN}	Input capacitance (Pin 23) 50MHz – 300MHz		2		pF
V _{IN}	Input voltage for 1% × mod in channel (Pin 23)	97	100		dBμV
V _{IN}	Input voltage for 10kHz pulling (in channel) (Pin 23)	100	108		dBμV
A _V	Voltage gain = 20log (V _{11 - 12} /V ₂₃) (Pins 11 – 12, 23)	22	24.5	27	dB
VHF mixer					
	Conversion transadmittance mixer = SC = I ₁₅ /V ₂₃ = -I ₁₆ /V ₂₃ (Pins 15, 16 – 23)		3.8		mmho
	Output admittance mixer (Pins 15 – 16)		0.1		mmho
	Output capacitance mixer (Pins 15 – 16)		2		pF

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DC ELECTRICAL CHARACTERISTICS (Continued)

SYMBOL	PARAMETER	LIMITS			UNIT
		Min	Typ	Max	
VHF oscillator					
f_R	Frequency range	70		330	MHz
	Shift $V_B = 10\%$; 70 to 330MHz			200	kHz
	Drift $T = 15^\circ$; 70 to 330MHz			250	kHz
	Drift from 5 seconds to 15 minutes after switching on			200	kHz
Hyperband mixer including IF (measured in circuit of Figure 1²) (measurements with hybrid)					
f_R	Frequency range	300		470	MHz
	Noise figure (Pins 21, 22) 300MHz 470MHz		8 8	10 10	dB dB
	Input reflection coefficient (Pins 21, 22) 300MHz S11 phase 470MHz S11 phase		-4.4 + 162 -4.7 + 151		dB deg dB deg
	Input available power P_{AV} for 1% X-mod 300MHz in-channel (Pins 21, 22) 470MHz		-19 -19		dBm dBm
	10kHz pulling (in-channel) (Pins 21, 22) 470MHz $N + 5 - 1$ MHz pulling ³ (Pins 21, 22) 470MHz		-11 -29		dBm dBm
	Gain = ⁴ 300MHz 470MHz	34 34	37 37	40 40	dB dB
Hyperband oscillator					
	Frequency range (MHz)	330		520	MHz
	Shift $\Delta V_B = 5\%$			400	kHz
	Drift $\Delta T = 15^\circ$			500	kHz
	Drift from 5 seconds to 15 minutes after switching on			600	kHz
	Input reflection coefficient (Pins 4 – 5) S11 at $f = 330$ MHz phase		TBD TBD		dB deg
UHF mixer including IF (Pins 18 and 19) (measured in circuit of Figure 1²) (measurements with hybrid)					
	Frequency range	470		860	MHz
	Noise figure 470MHz 860MHz		8 9	10 11	dB dB
	Input reflection coefficient 470MHz S11 phase 860MHz phase		-4 + 157 -4.2 + 138		deg deg
	Input available power P_{AV} for 470MHz 1% X-mod in-channel 860MHz		-19 -19		dBm dBm
	10kHz pulling (in-channel) 860MHz $N + 5 - 1$ MHz pulling ³ 820MHz	-42	-10 -35		dBm dBm
	Gain = ⁴ 470MHz 860MHz	34 34	37 37	40 40	dB dB

Computer-Controlled Deflection Processor for Video Displays TDA8432

DC ELECTRICAL CHARACTERISTICS (Continued)

SYMBOL	PARAMETER	LIMITS			UNIT
		Min	Typ	Max	
UHF oscillator					
f_R	Frequency range (MHz)	500		900	MHz
	Shift $\Delta V_B = 5\%$			400	kHz
	Drift $\Delta T = 25^\circ C$ to $40^\circ C$			500	kHz
	Drift from 5 seconds to 15 minutes after switching on			300	kHz
IF amplifier					
			Mod	Phase	
	S11 S21 S12 S22 } measured at 36MHz, differentially		-0.5 12 -41 -7.9	-1 160 -5.2 13.7	dB/deg dB/deg dB/deg dB/deg
LO output (Pin 2)					
	Output voltage into 75Ω $f \leq 330\text{MHz}$	14	37	100	mV
	Output reflection coefficient (VHF position) S22 (Hyperband and UHF) at 500MHz		TBD TBD		dB/deg dB/deg
	Spurious signal on LO output wrt LO output signal, measured in 75Ω with RF signal level at Pin 24 $1\text{V} \leq 225\text{MHz}$ $0.3\text{V} 225\text{MHz} - 300\text{MHz}$			-10	dB
	Harmonics of LO signal wrt LO signal, measured in 75Ω			-10	dB

NOTES:

1. The Pins 2, 5, 11, 12, 13, 14 withstand the ESD test.
2. Measured with an input circuit for optimum noise figure.
3. The values have been corrected for hybrid and cable losses. The symmetrical output impedance of the hybrid is 100Ω .
4. The input level of an N + 5 – 1MHz signal which is just visible (Amtsblatt 69).
5. The gain is defined as the transducer gain measured in Figure 1 + the voltage transformation ratio of L6-L7. The ratio is 6:1 (16dB).
6. All S parameters are referred to a 50Ω system.

