## **RF COMMUNICATIONS PRODUCTS**



Product specification Replaces data of 1997 June 28 IC17

1997 Nov 07

# **Philips Semiconductors**





### SA575

#### DESCRIPTION

The SA575 is a precision dual gain control circuit designed for low voltage applications. The SA575's channel 1 is an expandor, while channel 2 can be configured either for expandor, compressor, or automatic level controller (ALC) application.

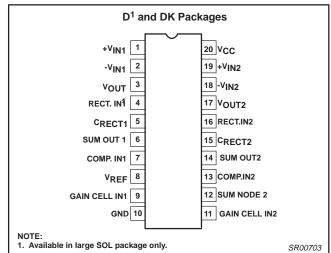
#### FEATURES

- Operating voltage range from 3V to 7V
- Reference voltage of 100mV<sub>RMS</sub> = 0dB
- One dedicated summing op amp per channel and two extra uncommitted op amps
- 600Ω drive capability
- Single or split supply operation
- Wide input/output swing capability
- 3000V ESD protection

#### **APPLICATIONS**

- Portable communications
- Cellular radio
- Cordless telephone
- Consumer audio

#### **PIN CONFIGURATION**





- Portable broadcast mixers
- Wireless microphones
- Modems
- Electric organs
- Hearing aids

#### **ORDERING INFORMATION**

DESCRIPTION	TEMPERATURE RANGE	ORDER CODE	DWG
20-Pin Plastic Small Outline Large	-40 to +85°C	SA575D	SOT163-1
20-Pin Plastic Shrink Small Outline Package (SSOP)	-40 to +85°C	SA575DK	SOT266-1

#### **ABSOLUTE MAXIMUM RATINGS**

SYMBOL	PARAMETER	RATING	UNITS	
STWBOL	FARAMETER	SA575	UNITS	
V <sub>CC</sub>	Single supply voltage	–0.3 to 8	V	
V <sub>IN</sub>	Voltage applied to any other pin	–0.3 to (V <sub>CC</sub> +0.3)	V	
T <sub>A</sub>	Operating ambient temperature range	-40 to +85	°C	
T <sub>STG</sub>	Storage temperature range	-65 to +150	°C	
$\theta_{JA}$	Thermal impedance SOL	112	°C/W	
	SSOP	117	°C/W	

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### **BLOCK DIAGRAM and TEST CIRCUIT**

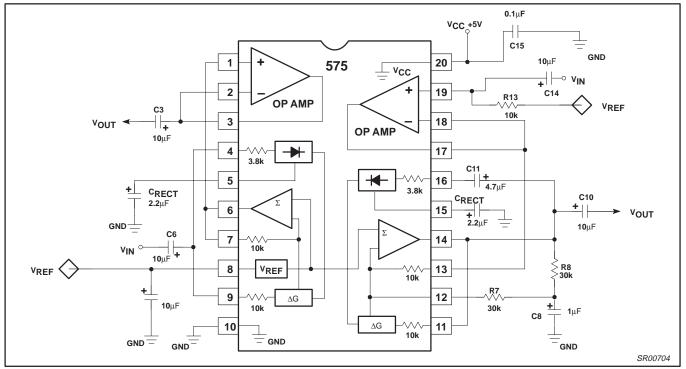


Figure 2. Block Diagram and Test Circuit

### DC ELECTRICAL CHARACTERISTICS

Typical values are at  $T_A = 25^{\circ}C$ . Minimum and Maximum values are for the full operating temperature range: -40 to +85°C for SA575, except SSOP package is tested at +25°C only. V<sub>CC</sub> = 5V, unless otherwise stated. Both channels are tested in the Expandor mode (see Test Circuit)

				LIMITS		
SYMBOL	PARAMETER	TEST CONDITIONS	SA575			UNITS
			MIN	TYP	MAX	
For compan	dor, including summing amplifier					
V <sub>CC</sub>	Supply voltage <sup>1</sup>		3	5	7	V
I <sub>CC</sub>	Supply current	No signal	3	4.2	5.5	mA
V <sub>REF</sub>	Reference voltage <sup>2</sup>	$V_{CC} = 5V$	2.4	2.5	2.6	V
RL	Summing amp output load		10			kΩ
THD	Total harmonic distortion	1kHz, 0dB BW = 3.5kHz		0.12	1.5	%
E <sub>NO</sub>	Output voltage noise	BW = 20kHz, $R_S = 0\Omega$		6	30	μV
0dB	Unity gain level	1kHz	-1.5		1.5	dB
V <sub>OS</sub>	Output voltage offset	No signal	-150		150	mV
	Output DC shift	No signal to 0dB	-100		100	mV
		Gain cell input = 0dB, 1kHz Rectifier input = 6dB, 1kHz	-1.0		1.0	dB
	Tracking error relative to 0dB	Gain cell input = 0dB, 1kHz Rectifier input = -30dB, 1kHz	-1.0		1.0	dB

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### DC ELECTRICAL CHARACTERISTICS (cont.)

	PARAMETER	TEST CONDITIONS	LIMITS SA575			UNITS
SYMBOL						
			MIN	TYP	MAX	1
	Crosstalk	1kHz, 0dB, C <sub>REF</sub> = 220μF		-80	-65	dB
For operatio	nal amplifier	•				
Vo	Output swing	$R_L = 10k\Omega$	V <sub>CC</sub> -0.4	V <sub>CC</sub>		V
RL	Output load	1kHz	600			Ω
CMR	Input common-mode range		0		V <sub>CC</sub>	V
CMRR	Common-mode rejection ratio		60	80		dB
Ι <sub>Β</sub>	Input bias current	V <sub>IN</sub> = 0.5V to 4.5V	-1		1	μΑ
V <sub>OS</sub>	Input offset voltage			3		mV
A <sub>VOL</sub>	Open-loop gain	$R_L = 10k\Omega$		80		dB
SR	Slew rate	Unity gain		1		V/µs
GBW	Bandwidth	Unity gain		3		MHz
E <sub>NI</sub>	Input voltage noise	BW = 20kHz		2.5		μV
PSRR	Power supply rejection ratio	1kHz, 250mV		60		dB

#### NOTES:

1. Operation down to V<sub>CC</sub> = 2V is possible, but performance is reduced. See curves in Figure 7a and 7b.

2. Reference voltage, V<sub>REF</sub>, is typically at 1/2V<sub>CC</sub>.

### FUNCTIONAL DESCRIPTION

This section describes the basic subsystems and applications of the SA575 Compandor. More theory of operation on compandors can be found in AN174 and AN176. The typical applications of the SA575 low voltage compandor in an Expandor (1:2), Compressor (2:1) and Automatic Level Control (ALC) function are explained. These three circuit configurations are shown in Figures 3, 4, 5 respectively.

The SA575 has two channels for a complete companding system. The left channel, A, can be configured as a 1:2 Expandor while the right channel, B, can be configured as either a 2:1 Compressor, a 1:2 Expandor or an ALC. Each channel consists of the basic companding building blocks of rectifier cell, variable gain cell, summing amplifier and  $V_{REF}$  cell. In addition, the SA575 has two additional high performance uncommitted op amps which can be utilized for application such as filtering, pre-emphasis/de-emphasis or buffering.

Figure 6 shows the complete schematic for the applications demo board. Channel A is configured as an expandor while channel B is configured so that it can be used either as a compressor or as an ALC circuit. The switch, S1, toggles the circuit between compressor and ALC mode. Jumpers J1 and J2 can be used to either include the additional op amps for signal conditioning or exclude them from the signal path. Bread boarding space is provided for R1, R2, C1, C2, R10, R11, C10 and C11 so that the response can be tailored for each individual need. The components as specified are suitable for the complete audio spectrum from 20Hz to 20kHz.

The most common configuration is as a unity gain non-inverting buffer where R1, C1, C2, R10, C10 and C11 are eliminated and R2 and R11 are shorted. Capacitors C3, C5, C8, and C12 are for DC blocking. In systems where the inputs and outputs are AC coupled, these capacitors and resistors can be eliminated. Capacitors C4 and C9 are for setting the attack and release time constant.

C6 is for decoupling and stabilizing the voltage reference circuit. The value of C6 should be such that it will offer a very low impedance to the lowest frequencies of interest. Too small a capacitor will allow supply ripple to modulate the audio path. The better filtered the power supply, the smaller this capacitor can be. R12 provides DC reference voltage to the amplifier of channel B. R6 and R7 provide a DC feedback path for the summing amp of channel B, while C7 is a short-circuit to ground for signals. C14 and C15 are for power supply decoupling. C14 can also be eliminated if the power supply is well regulated with very low noise and ripple.

### DEMONSTRATED PERFORMANCE

The applications demo board was built and tested for a frequency range of 20Hz to 20kHz with the component values as shown in Figure 6 and V<sub>CC</sub> = 5V. In the expandor mode, the typical input dynamic range was from -34dB to +12dB where 0dB is equal to 100mV<sub>RMS</sub>. The typical unity gain level measured at 0dB @ 1kHz input was  $\pm$ 0.5dB and the typical tracking error was  $\pm$ 0.1dB for input range of -30 to +10dB.

In the compressor mode, the typical input dynamic range was from -42dB to  $\pm$ 18dB with a tracking error +0.1dB and the typical unity gain level was  $\pm$ 0.5dB.

In the ALC mode, the typical input dynamic range was from -42dB to +8dB with typical output deviation of  $\pm 0.2$ dB about the nominal output of 0dB. For input greater than +9dB in ALC configuration, the summing amplifier sometimes exhibits high frequency oscillations. There are several solutions to this problem. The first is to lower the values of R6 and R7 to 20k $\Omega$  each. The second is to add a current limiting resistor in series with C12 at Pin 13. The third is to add a compensating capacitor of about 22 to 30pF between the input and output of summing amplifier (Pins 12 and 14). With any one of the above recommendations, the typical ALC mode input range increased to +18dB yielding a dynamic range of over 60dB.

### EXPANDOR

The typical expandor configuration is shown in Figure 3. The variable gain cell and the rectifier cell are in the signal input path. The  $V_{REF}$  is always 1/2  $V_{CC}$  to provide the maximum headroom without clipping. The 0dB ref is 100m $V_{RMS}$ . The input is AC coupled through C5, and the output is AC coupled through C3. If in a system the inputs and outputs are AC coupled, then C3 and C5 can be eliminated, thus requiring only one external component, C4. The variable gain cell and rectifier cell are DC coupled so any offset

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voltage between Pins 4 and 9 will cause small offset error current in the rectifier cell. This will affect the accuracy of the gain cell. This can be improved by using an extra capacitor from the input to Pin 4 and eliminating the DC connection between Pins 4 and 9. The expandor gain expression and the attack and release time constant is given by Equation 1 and Equation 2, respectively. Equation 1.

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Expandor gain =  $\frac{4 v_{IN}(avg)}{3.8k \times 100 \mu A}$ 

 $\tau_R = \tau_A = 10k \times C_{RFCT} = 10k \times C4$ 

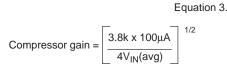
where  $V_{IN}(avg) = 0.95V_{IN(RMS)}$ 

Equation 2.

COMPRESSOR

The typical compressor configuration is shown in Figure 4. In this mode, the rectifier cell and variable gain cell are in the feedback path. R6 and R7 provide the DC feedback to the summing amplifier. The input is AC coupled through C12 and output is AC coupled through C8. In a system with inputs and outputs AC coupled, C8 and C12 could be eliminated and only R6, R7, C7, and C13 would be required. If the external components R6, R7 and C7 are eliminated, then the output of the summing amplifier will motor-boat in absence of signals or at extremely low signals. This is because there is no DC feedback path from the output to input. In the presence of an AC signal this phenomenon is not observed and the circuit will appear to function properly.

The compressor gain expression and the attack and release time constant is given by Equation 3 and Equation 4, respectively.



where  $V_{IN}(avg) = 0.95V_{IN(RMS)}$ 

Equation 4.

 $\tau_R = \tau_A = 10k \times C_{RECT} = 10k \times C4$ 

#### AUTOMATIC LEVEL CONTROL

The typical Automatic Level Control circuit configuration is shown in Figure 5. It can be seen that it is quite similar to the compressor schematic except that the input to the rectifier cell is from the input path and not from the feedback path. The input is AC coupled through C12 and C13 and the output is AC coupled through C8. Once again, as in the previous cases, if the system input and output signals are already AC coupled, then C12, C13 and C8 could be eliminated. Concerning the compressor, removing R6, R7 and C7 will cause motor-boating in absence of signals. C<sub>COMP</sub> is necessary to stabilize the summing amplifier at higher input levels. This circuit provides an input dynamic range greater than 60dB with the output within  $\pm 0.5$ dB typical. The necessary design expressions are given by Equation 5 and Equation 6, respectively.

Equation 5.

ALC gain = 
$$\frac{3.8k \times 100\mu A}{4V_{IN}(avg)}$$
Equation 6

 $\tau_R = \tau_A = 10k \times C_{RECT} = 10k \times C9$ 

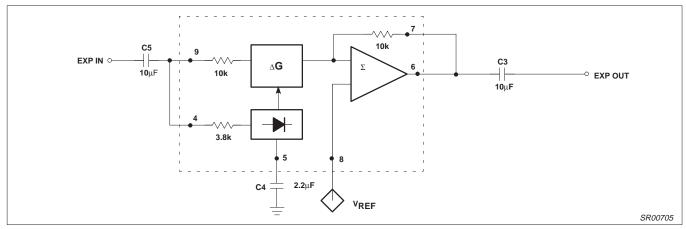
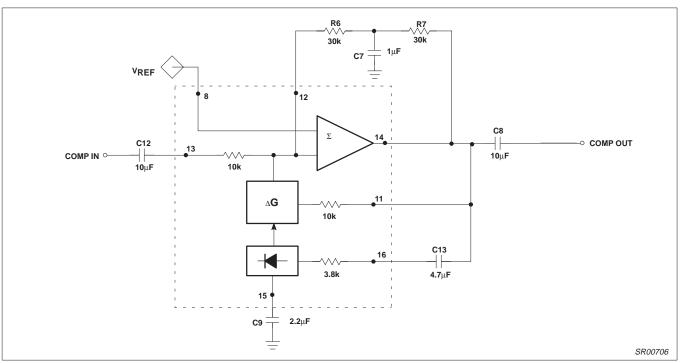


Figure 3. Typical Expandor Configuration





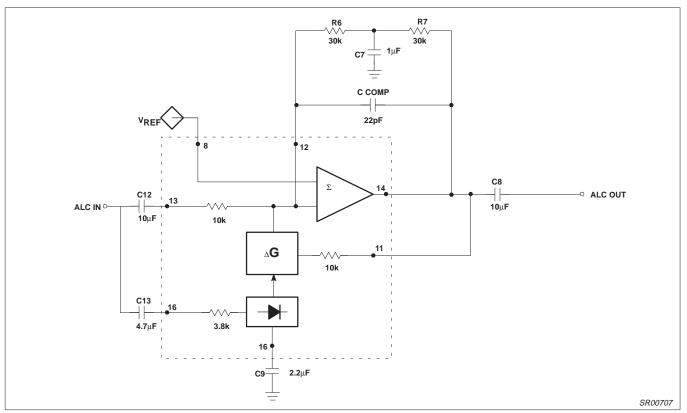


Figure 5. Typical ALC Configuration

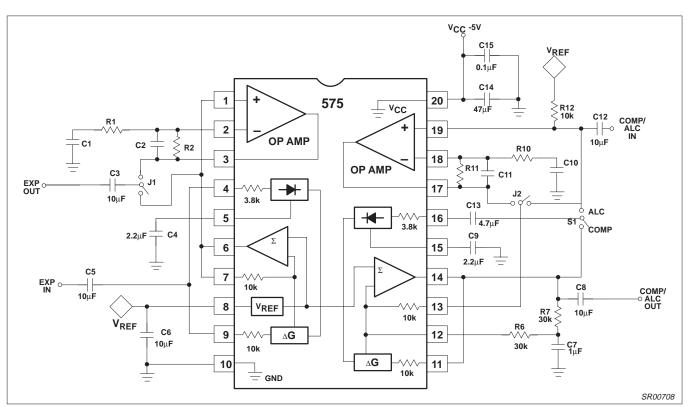


Figure 6. SA575 Low Voltage Expandor/Compressor/ALC Demo Board

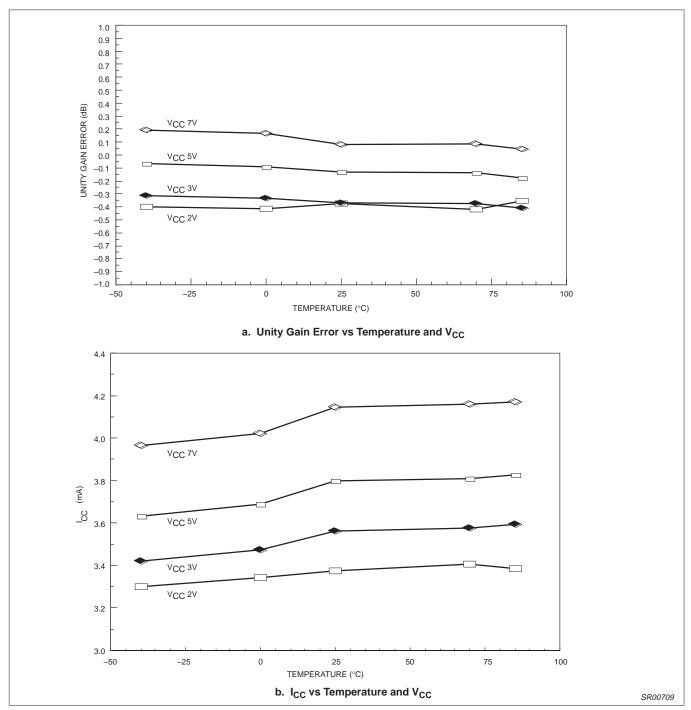


Figure 7. Temperature and  $V_{CC}$  Curves



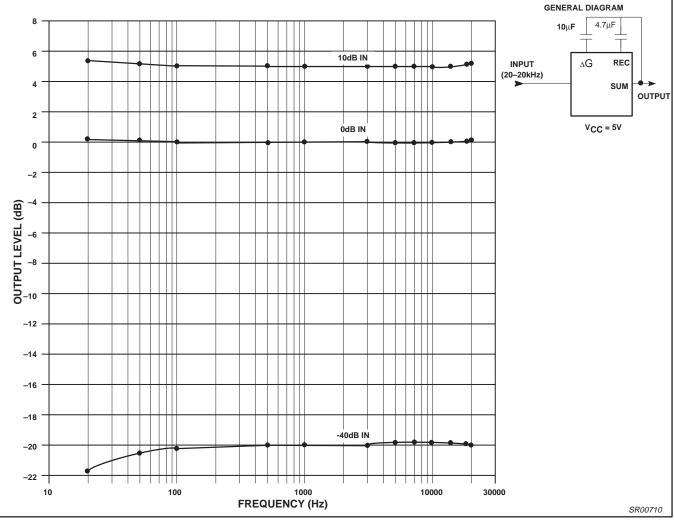


Figure 8. Compressor Output Frequency Response

Product specification



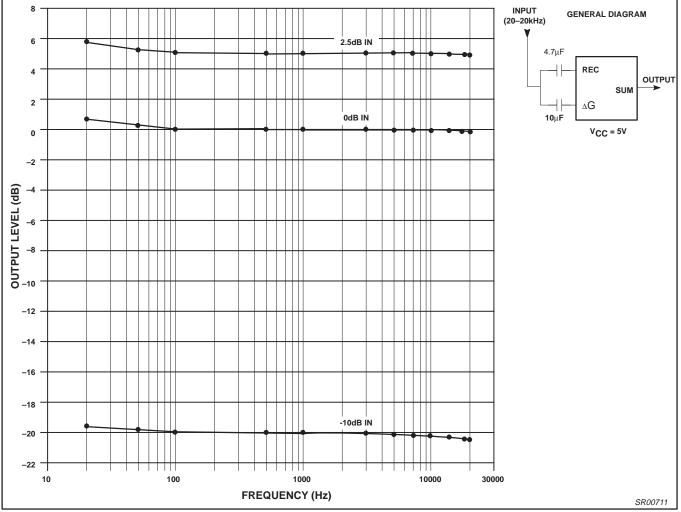


Figure 9. Expandor Output Frequency Response

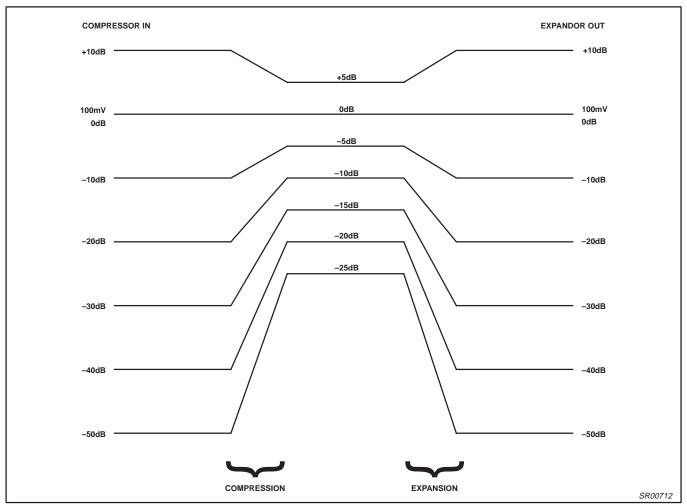
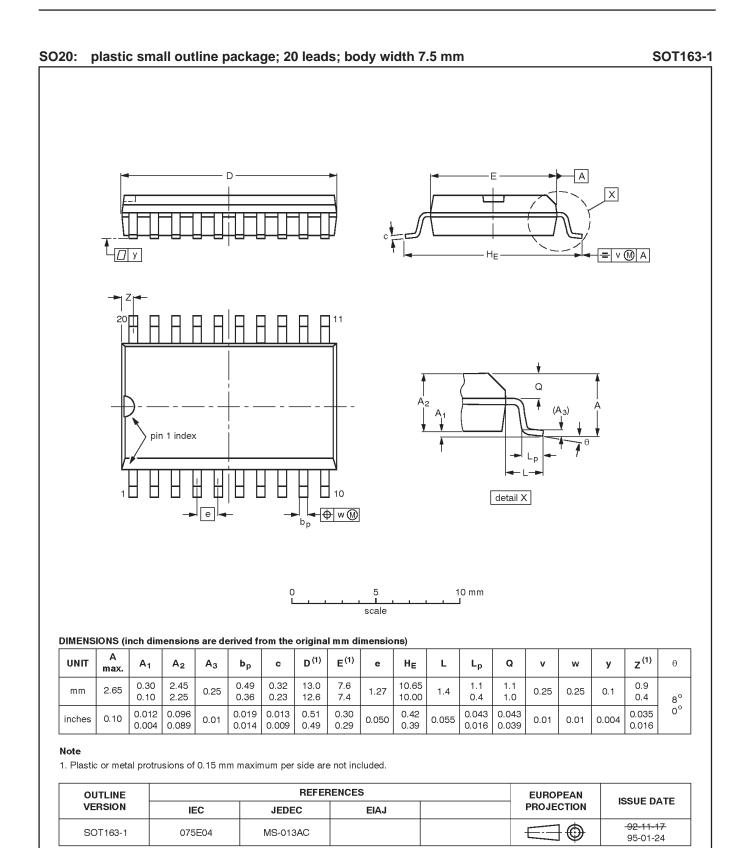
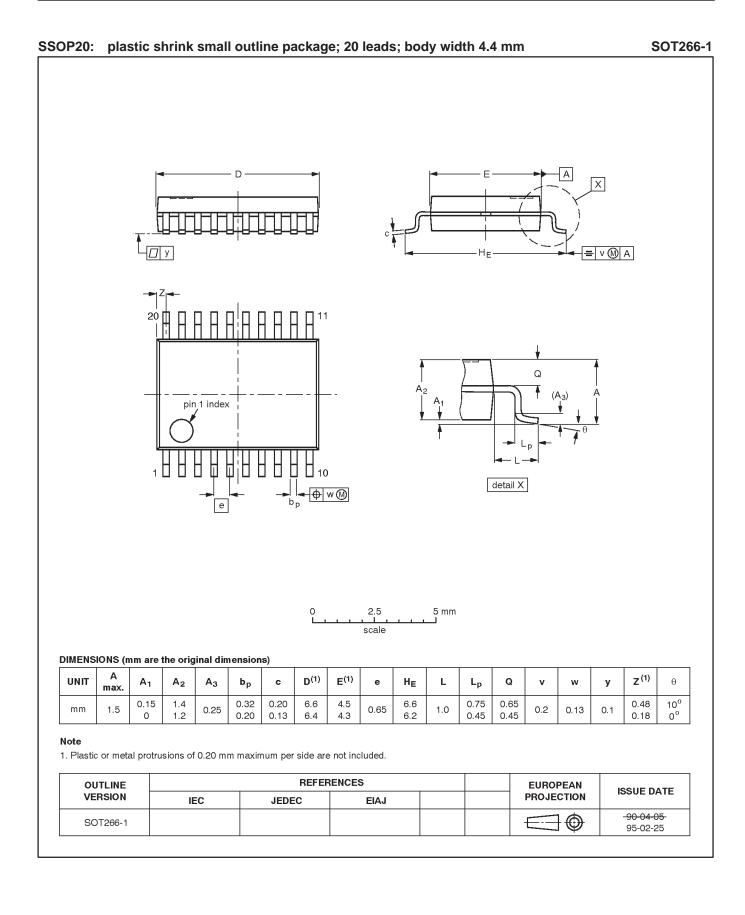


Figure 10. The Companding Function

Product specification





DEFINITIONS			
Data Sheet Identification Product Status Definition		Definition	
Objective Specification	Objective Specification Formative or in Design This data sheet contains the design target or goal specifications for product development.   may change in any manner without notice. This data sheet contains the design target or goal specifications for product development.		
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