

### **Description**

The  $\mu$ PD42102 is a 1,135-word by 8-bit line buffer fabricated with a CMOS silicon-gate process. The device helps to create a PAL flicker-free television picture (non-interlaced scan conversion) by providing intermediate storage and very high-speed read and write operation.

The  $\mu$ PD42102 can also be used as a digital delay line. The delay length is variable from 2 bits (at maximum clock speed) to 1,135 bits.

#### **Features**

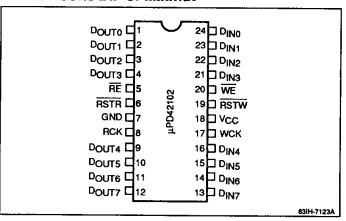
- □ 1,135-word x 8-bit organization
- □ Line buffer for PAL, 4f<sub>SC</sub> digital television systems
- Asynchronous, simultaneous read/write operation
- □ 1H (1,135-bit) delay line capability
- TTL-compatible inputs and outputs
- □ Three-state outputs
- □ Single +5-volt power supply
- 24-pin plastic DIP and miniflat packaging

### Ordering Information

Part Number	Read Cycle Time (min)	Write Cycle Time (min)	Package			
μPD42102C-5	25 ns	25 ns	24-pin plastic DIP			
C-3	34 ns	34 ns	-			
C-2	34 ns	69 ns	•			
C-1	69 ns	69 ns	•			
μPD42102G-5	25 ns	25 ns	24-pin plastic miniflat			
G-3	34 ns	34 ns	•			
G-2	34 ns	69 ns	•			
G-1	69 ns	69 ns	•			

### Pin Configuration

#### 24-Pin Plastic DIP or Miniflat



#### Pin Identification

Symbol	Function
D <sub>INO</sub> - D <sub>IN7</sub>	Write data inputs
D <sub>OUT0</sub> - D <sub>OUT7</sub>	Read data outputs
RSTW	Write address reset input
RSTR	Read address reset input
WE	Write enable input
RE	Read enable input
WCK	Write clock input
RCK	Read clock input
GND	Ground
Vcc	+5-volt power supply



#### **PIN FUNCTIONS**

## D<sub>INO</sub> - D<sub>IN7</sub> (Data Inputs)

In a digital television application, the digital composite signal, luminance, chrominance, etc. information is written into these inputs.

### D<sub>OUT0</sub> - D<sub>OUT7</sub> (Data Outputs)

The tri-state outputs are used to access the stored information. In a simple digital delay line application, a delay of one-half write clock cycle plus a maximum of 300 ns is required to move data from the data inputs to the data outputs.

### **RSTW** (Write Address Reset Input)

Bringing this signal low when WE is also low resets the internal write address to 0. If WE is at a high level when the RSTW input is brought low, the internal write address is set to 1,134. The state of this input is strobed by the rising edge of WCK.

### **RSTR** (Read Address Reset Input)

This signal is strobed by the rising edge of RCK and resets the internal read address to 0 if RE is also low. If RE is at a high level when the RSTR input is brought low, the internal read address is set to 1,134.

#### WE (Write Enable Input)

This input controls write operation. If  $\overline{WE}$  is low, all write cycles proceed. If  $\overline{WE}$  is at a high level, no data is written to storage cells and the write address stops increasing. The state of  $\overline{WE}$  is strobed by the rising edge of WCK.

#### RE (Read Enable Input)

This signal is similar to  $\overline{\text{WE}}$  but controls read operation. If  $\overline{\text{RE}}$  is at a high level, the data outpus become high impedance and the internal read address stops increasing. The state of  $\overline{\text{RE}}$  is strobed by the rising edge of RCK.

### WCK (Write Clock Input)

All write cycles are executed synchronously with WCK. The states of both RSTW and WE are strobed by the rising edge of WCK at the beginning of a cycle, and the data inputs are strobed by the rising edge of WCK at the end of a cycle. The internal write address increases with

each WCK cycle unless WE is at a high level to hold the write address constant. Unless inhibited by WE, the internal write address will automatically wrap around from 1,134 to 0 and begin increasing again.

### **RCK (Read Clock Input)**

All read cycles are executed synchronously with RCK. The states of both RSTR and RE are strobed by the rising edge of RCK at the beginning of a cycle. This same edge of RCK starts internal read operation, and access time is referenced to this edge. The internal read address increases with each RCK cycle unless RE is at a high level to hold the read address constant. Unless inhibited by RE, the internal read address will automatically wrap around from 1,134 to 0 and begin increasing again.

**Absolute Maximum Ratings** 

Supply voltage, V <sub>CC</sub>	– 1.5 to +7.0 V
Voltages on any input pin, V <sub>I</sub>	- 1.5 to + 7.0 V
Voltage on any output pin, V <sub>O</sub>	−1.5 to +7.0 V
Short-circuit output current, I <sub>OS</sub>	20 mA
Operating temperature, TOPR	- 20 to +70°C
Storage temperature, T <sub>STG</sub>	- 55 to +125°C

Exposure to Absolute Maximum Ratings for extended periods may affect device reliability; exceeding the ratings could cause permanent damage. The device should be operated within the limits specified under DC and AC Characteristics.

# **Recommended Operating Conditions**

Parameter	Symbol	Min	Тур	Max	Unit			
Supply voltage	Vcc	4.5	5.0	5.5	٧			
Input voltage, high	VIH	2.4		5.5	٧			
Input voltage, low	V <sub>IL</sub>	- 1.5		0.8	٧			
Operating temperature	TA	-20		70	.c			

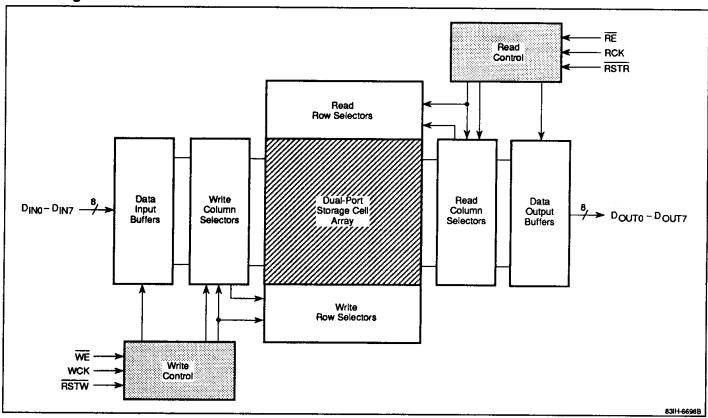
#### Capacitance

 $T_A = 25^{\circ}C; V_{CC} = +5.0 \text{ V} \pm 10\%; f = 1 \text{ MHz}$ 

Parameter	Symbol	Min	Max	Unit	WE, RE, WCK, RCK, RSTW, RSTR, D <sub>INO</sub> - D <sub>IN7</sub>				
Input capacitance	C <sub>I</sub>	-	5	рF					
Output capacitance	Co		7	рF	D <sub>OUT0</sub> - D <sub>OUT7</sub>				



## **Block Diagram**



#### **DC** Characteristics

 $T_A = -20 \text{ to } +70^{\circ}\text{C}; V_{CC} = +5.0 \text{ V} \pm 10\%$ 

Parameter	Symbol	Min	Тур	Max	Unit	Test Conditions
Input leakage current	Ŋ	-10	-	10	μА	V <sub>IN</sub> = 0 V to V <sub>CC</sub> ; all other pins not under test = 0 V
Output leakage current	lo	-10		10	μΑ	D <sub>OUT</sub> disabled; V <sub>O</sub> = 0 to 5.5 V
Output voltage, high	V <sub>OH</sub>	2.4			V	I <sub>OH</sub> = -1 mA
Output voltage, low	V <sub>OL</sub>			0.4	٧	I <sub>OL</sub> = 2.0 mA

### **AC Characteristics**

 $T_A = -20 \text{ to } +70^{\circ}\text{C}; V_{CC} = +5.0 \text{ V} \pm 10\%$ 

Parameter		μPD42102-5		μPD42102-3		μPD42102-2		μPD42102-1			
	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Unit	Test Conditions
Write/read cycle operating current	lcc		80		80		70		40	mA	twck = twck (min) trck = trck (min)
Write clock cycle time	twck	25	880	28	880	56	880	56	880	ns	
WCK pulse width	‡wcw	10		12		20		20		ns	
WCK precharge time	<b>™</b> CP	10		12		20		20		ns	
Read clock cycle time	<sup>t</sup> RCK	25	880	28	880	28	880	56	880	ns	
RCK pulse width	<sup>t</sup> RCW	10		12		12		20		ns	
RCK precharge time	†RCP	10		12		12		20		ns	
Access time	tAC		18		21		21		40	ns	<del></del>
Output hold time	<sup>t</sup> он	5		5		5	* "	5		ns	

# µPD42102



### **AC Characteristics (cont)**

		μPD42	2102-5	μPD42102-3		μPD42102-2		μPD42102-1			
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Min	Max	Unit	Test Conditions
Access time after a reset cycle	t <sub>ACR</sub>		18		21		21		40	ns	
Output hold time after a reset cycle	tOHR	5		5		5		5		ns	
Output active time	t <sub>LZ</sub>	5	18	5	21	5	21	5	40	ns	(Note 4)
Output disable time	t <sub>HZ</sub>	5	18	5	21	5	21	5	40	ns	(Note 4)
Data-in setup time	t <sub>DS</sub>	7		12		15		15		ns	
Data-in hold time	t <sub>DH</sub>	3		5		5		5		ns	
Reset active setup time	<sup>t</sup> RS	7		12		12		20		ns	(Note 7)
Reset active hold time	t <sub>RH</sub>	3		5		5		5		ns	(Note 7)
Reset inactive hold time	<sup>t</sup> RN1	3		5		5		5		ns	(Note 8)
Reset inactive setup time	t <sub>RN2</sub>	7		12		12		20		ns	(Note 8)
Write enable setup time	twes	7		12		20		20		ns	(Note 9)
Write enable hold time	tweH	3		5		5		5		ns	(Note 9)
Write enable high delay from WCK	twen1	3		5		5		5		ns	(Note 10)
Write enable low delay to WCK	twen2	7		12		20		20		ns	(Note 10)
Read enable setup time	t <sub>RES</sub>	7		12		12		20		ns	(Note 9)
Read enable hold time	t <sub>REH</sub>	3		5		5		5		ns	(Note 9)
Read enable high delay from RCK	t <sub>REN1</sub>	3		5		5		5		ns	(Note 10)
Read enable low delay to RCK	t <sub>REN2</sub>	7		12		12		20		ns	(Note 10)
Write disable pulse width	t <sub>WEW</sub>	0		0		0		0		ns	(Note 5)
Read disable pulse width	t <sub>REW</sub>	0		0		0		0		ns	(Note 5)
Write reset time	<sup>t</sup> astw	0		0		0		0		ns	(Note 5)
Read reset time	t <sub>RSTR</sub>	0		0		0		0		ns	(Note 5)
Transition time	t <sub>T</sub>	3	35	3	35	3	35	3	35	ns	

#### Notes:

- (1) All voltages are referenced to ground.
- (2) Input pulse rise and fall times assume  $t_T=5$  ns. Input pulse levels = GND to 3 V. Transition times are measured between 3 V and 0 V.

For the -5 version only,  $t_T=3\,\mathrm{ns}$ ; input pulse levels = 0.4 to 2.4 V; transition times are measured between 0.4 and 2.4 V. See figures 1 and 2.

- (3) Input timing reference levels = 1.5 V. Output timing reference levels are 0.8 and 2.0 V. See figure 3.
- (4) This delay is measured at 200 mV from the steady-state voltage with the load specified in figure 5. Under any conditions, t<sub>LZ</sub> ≥ t<sub>HZ</sub>.
- (5) t<sub>WEW</sub> (max) and t<sub>REW</sub> (max) must be satisfied by the following equations in 1-line cycle operation:

 $t_{WEW}$  +  $t_{RSTW}$  +1,135 ( $t_{WCK}$ )  $\leq$  1 ms  $t_{REW}$  +  $t_{RSTR}$  + 1,135 ( $t_{RCK}$ )  $\leq$  1 ms

- (6) This parameter applies when t<sub>RCK</sub> ≥ t<sub>ACR</sub> (max).
- (7) If either  $t_{\rm RS}$  or  $t_{\rm RH}$  is less than the specified value, reset operations are not guaranteed.
- (8) If either t<sub>RN1</sub> or t<sub>RN2</sub> is less than the specified value, internal reset operations may extend to cycles immediately preceding or following the period of desired reset operations.
- (9) If either twes or twen (tres or tren) is less than the specified value, write (read) disable operations are not guaranteed.
- (10) If either t<sub>WEN1</sub> or t<sub>WEN2</sub> (t<sub>REN1</sub> or t<sub>REN2</sub>) is less than the specified value, internal write (read) disable operations may extend to cycles immediately preceding or following the period of desired disable operations.
- (11) Data is guaranteed to remain valid for a minimum of 1 ms after it is written. After this time, the data stored may be invalid, since this device uses a dynamic storage element.



Figure 1. Input Timing

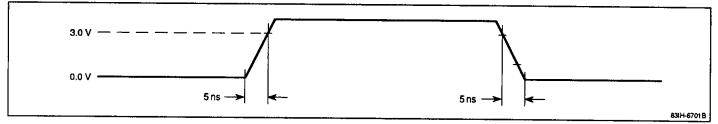


Figure 2. Input Timing for µPD42102-5

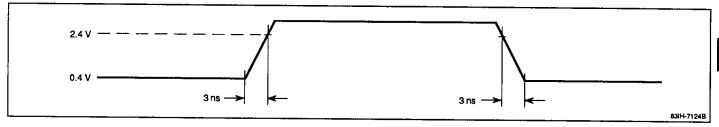


Figure 3. Output Timing

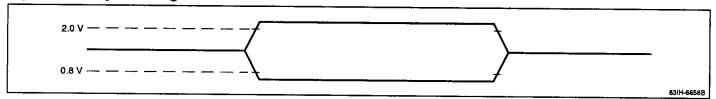


Figure 4. Output Load for tAC, tACR, tOH and tOHR

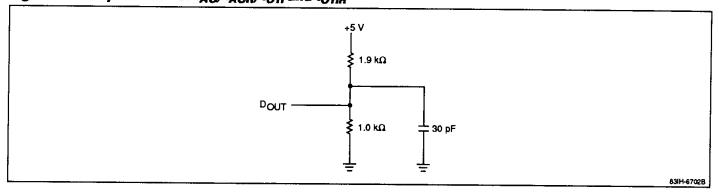
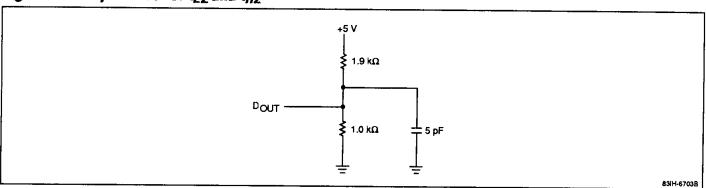


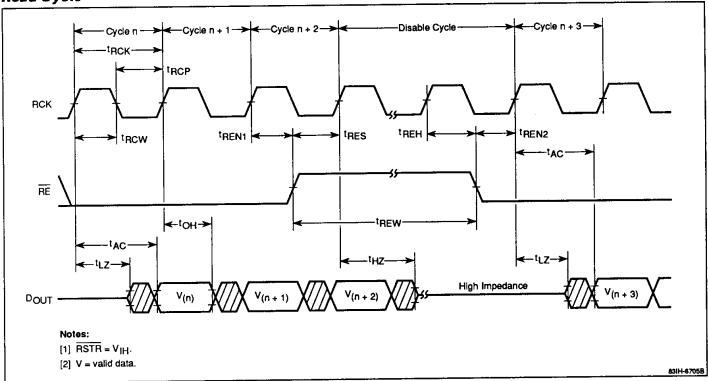
Figure 5. Output Load for  $t_{LZ}$  and  $t_{HZ}$ 



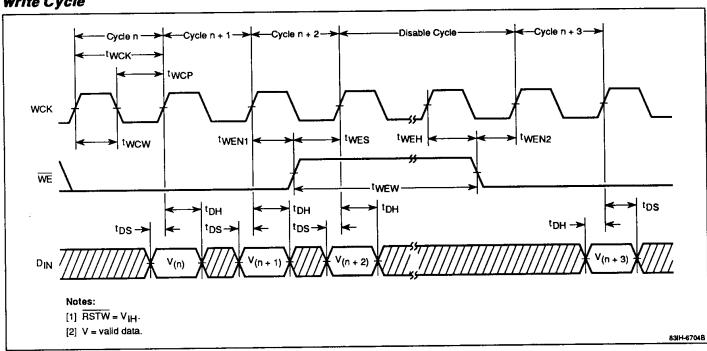


# **Timing Waveforms**

## Read Cycle



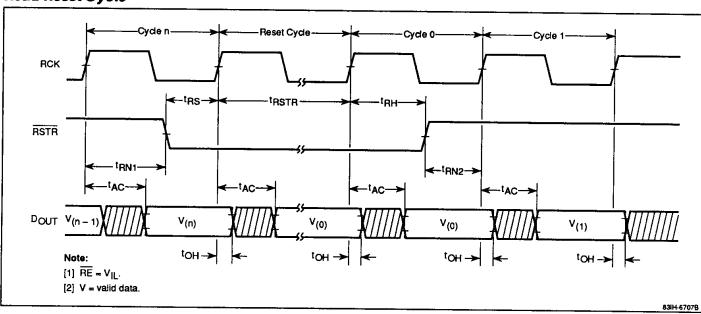
### Write Cycle



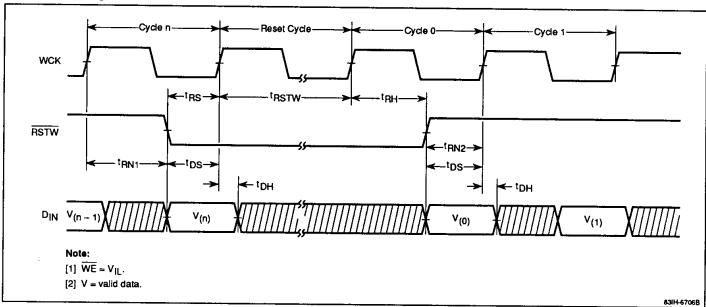


## **Timing Waveforms (cont)**

# Read Reset Cycle



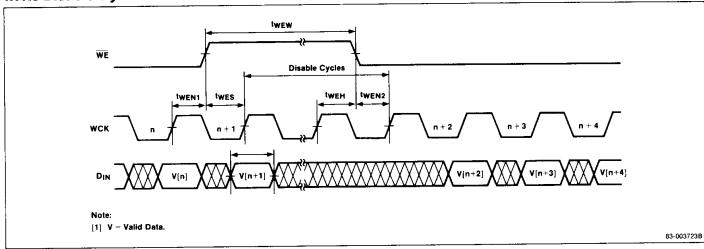
## Write Reset Cycle



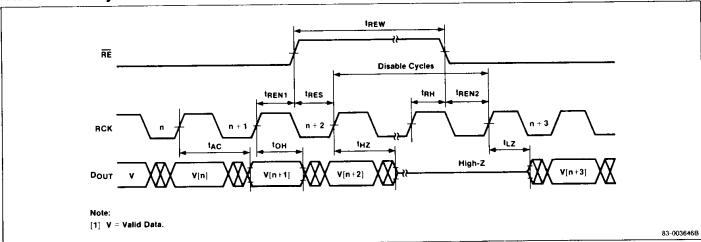


# **Timing Waveforms (cont)**

## Write Disable Cycle



## Read Disable Cycle





### Timing Waveforms (cont)

### Re-Read Cycle

