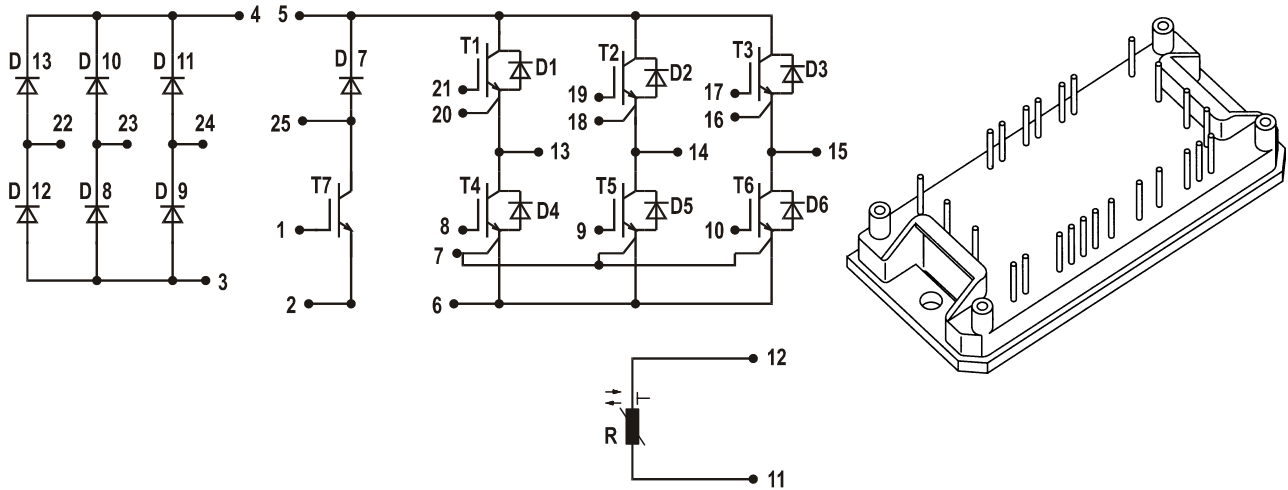


Converter - Brake - Inverter Module (CBI1)



Rectifier	Brake	Inverter
$V_{RRM} = 1600V$	$V_{CES} = 1200 V$	$V_{CES} = 1200 V$
$I_{FAVM} = 25 A$	$I_{C25} = 13 A$	$I_{C25} = 18 A$
$I_{FSM} = 370 A$	$V_{CE(sat)} = 2.8 V$	$V_{CE(sat)} = 2.8 V$

Input Rectifier Bridge D8 - D13

Symbol	Conditions	Maximum Ratings	
V_{RRM}		1600	V
I_F	$T_{VJ} = 25^{\circ}C$	55	A
I_{FAVM}	$T_{VJ} = 150^{\circ}C; T_K = 70^{\circ}C$	25	A
I_{FSM}	$T_{VJ} = 45^{\circ}C; t = 10 \text{ ms sine } 50 \text{ Hz}$	370	A
i^2t	$T_{VJ} = 125^{\circ}C$	680	A ² s
T_{VJ}		+150	$^{\circ}C$

Symbol	Conditions	Characteristic Values		
		(T _{VJ} = 25°C, unless otherwise specified)		
		min.	typ.	max.
I_R	$V_{RRM} = 1200 V; T_{VJ} = 25^{\circ}C$ $T_{VJ} = 125^{\circ}C$			20 μA 2 mA
V_F	$I_F = 55 A$		1.2	1.46 V
R_{thJC}	per die		1.05	$^{\circ}C/W$

Features

- NPT IGBT technology Square RBSOA, no latchup
- Free wheeling diodes with Hiperfast and soft recovery behaviour
- Isolation voltage 2500 V~
- Built in temperature sense
- High level of integration: one module for complete drive system
- **Direct Copper Bonded** Al₂O₃ ceramic base plate

Applications

- AC motor control
- AC servo and robot drives

Advantages

- No need of external isolation
- Easy to mount with two screws
- Package designed for wave soldering
- High temperature and power cycling capability

IXYS reserves the right to change limits, test conditions and dimensions.

Output Inverter T1 - T6, D1 - D6

Symbol	Conditions	Maximum Ratings	
V_{CES}	$T_{VJ} = 25^{\circ}\text{C}$	1200	V
V_{CGR}	$T_{VJ} = 25^{\circ}\text{C}; R_{GE} = 20\text{k}\Omega$	1200	V
V_{GE}	$T_{VJ} = 25^{\circ}\text{C}$	± 20	V
I_C	$T_C = 25^{\circ}\text{C}$	18	A
	$T_C = 90^{\circ}\text{C}$	11.5	A
I_{CM}	$t_p = 1 \text{ ms} = 1\% \text{ duty cycle};$ $T_C = 25^{\circ}\text{C}$ $T_C = 90^{\circ}\text{C}$	36	A
		23	A
t_{SC}	$V_{CE} = 600 \text{ V}; T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	μs
P_{tot}	$T_C = 25^{\circ}\text{C}$	70	W
T_{VJ}	Free-Wheeling Diode	+150	$^{\circ}\text{C}$
T_{VJ}	IGBT	+150	$^{\circ}\text{C}$

Symbol	Conditions	Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified)		
		min.	typ.	max.
I_{CES}	$V_{GE} = 0 \text{ V}; V_{CE} = 1000 \text{ V}$			500 μA
I_{GES}	$V_{CE} = 0 \text{ V}; V_{GE} = 25 \text{ V}$			100 nA
$V_{GE(th)}$	$V_{GE} = V_{CE}; I_C = 0.35 \text{ mA}$	4.5	5.5	6.5 V
$V_{(BR)CES}$	$V_{GE} = 0 \text{ V}; I_C = 10 \text{ mA}; T_{VJ} = -40^{\circ}\text{C}$	1200		V
V_{CESat}	$V_{GE} = 15 \text{ V}; I_C = 10 \text{ A};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 150^{\circ}\text{C}$			2.9 V
				3.4 V
t_f t_r	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$		350	ns
			40	ns
$t_{d(on)}$ $t_{d(off)}$	$V_{CC} = 600 \text{ V}; I_C = 8 \text{ A}$ $R_G = 100 \Omega; V_{GE} = \pm 15 \text{ V}$		80	ns
			420	ns
E_{off} E_{on}			0.9	mJ
			1.3	mJ
C_{iss} C_{oss} C_{rss}	$V_{GE} = 0 \text{ V}$ $V_{CE} = 25 \text{ V}$ $f = 1 \text{ MHz}$		850	nF
			98	nF
			60	nF
g_{fs}	$V_{CE} = 20 \text{ V}; I_C = 1.5 \text{ A}$	1.7		S
Q_g	$V_{CC} = 1000 \text{ V}; I_C = 8 \text{ A pulse}; V_{GE} = 15 \text{ V}$		58	nC
V_F	$I_F = 4 \text{ A}; V_{GE} = 0 \text{ V};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 100^{\circ}\text{C}$		2.3	3 V
			2	V
t_{rr}	$I_F = 4 \text{ A}; V_{GE} = 0 \text{ V}; T_{VJ} = 100^{\circ}\text{C}$ $V_R = -300 \text{ V}; di_F/dt = -800 \text{ A}/\mu\text{s}$		55	ns
Q_r	$I_F = 4 \text{ A}; V_{GE} = 0 \text{ V}; V_R = -300 \text{ V}$ $di_F/dt = -800 \text{ A}/\mu\text{s}$		0.8	μC
I_r				250 μA
R_{thJC}	IGBT (per die)		1.5	$^{\circ}\text{C}/\text{W}$
	Diode (per die)		2.25	$^{\circ}\text{C}/\text{W}$

Brake Chopper T7, D7

Symbol	Conditions	Maximum Ratings	
V_{CES}	$T_{VJ} = 25^{\circ}\text{C}$	1200	V
V_{CGR}	$T_{VJ} = 25^{\circ}\text{C}; R_{GE} = 20\text{k}\Omega$	1200	V
V_{GE}	$T_{VJ} = 25^{\circ}\text{C}$	± 20	V
I_C	$T_C = 25^{\circ}\text{C}$	13	A
	$T_C = 90^{\circ}\text{C}$	8	A
I_{CM}	$t_p = 1 \text{ ms} = 1\% \text{ duty cycle};$ $T_C = 25^{\circ}\text{C}$ $T_C = 90^{\circ}\text{C}$	26	A
		16	A
t_{SC}	$V_{CE} = 600 \text{ V}; T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	μs
P_{tot}	$T_C = 25^{\circ}\text{C}$	67	W
T_{VJ}	Free-Wheeling Diode	+150	$^{\circ}\text{C}$
T_{VJ}	IGBT	+150	$^{\circ}\text{C}$

Symbol	Conditions	Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified)			
		min.	typ.	max.	
I_{CES}	$V_{GE} = 0 \text{ V}; V_{CE} = 1000 \text{ V}$		1	100 μA	
I_{GES}	$V_{CE} = 0 \text{ V}; V_{GE} = 25 \text{ V}$		0.1	100 nA	
$V_{GE(th)}$	$V_{GE} = V_{CE}; I_C = 0.3 \text{ mA}$	4.5	5.5	6.5 V	
$V_{(BR)CES}$	$V_{GE} = 0 \text{ V}; I_C = 10 \text{ mA}; T_{VJ} = -40^{\circ}\text{C}$	1200		V	
V_{CESat}	$V_{GE} = 15 \text{ V}; I_C = 5 \text{ A};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 150^{\circ}\text{C}$		2.8	3.3 V	
			4	4.5 V	
t_f	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CC} = 600 \text{ V}; I_C = 5 \text{ A}$ $R_G = 100 \Omega; V_{GE} = \pm 15 \text{ V}$		200	ns	
		t_r	55	ns	
$t_{d(on)}$		65	ns		
$t_{d(off)}$		320	ns		
E_{off}		0.4	mJ		
E_{on}		0.8	mJ		
C_{iss}		$V_{GE} = 0 \text{ V}$ $V_{CE} = 25 \text{ V}$ $f = 1 \text{ MHz}$		650	pF
			C_{oss}	50	pF
			C_{rss}	20	pF
g_{fs}		$V_{CE} = 20 \text{ V}; I_C = 1.5 \text{ A}$	1.7	2.5	S
Q_g	$V_{CC} = 800 \text{ V}; I_C = 6 \text{ A pulse}; V_{GE} = 15 \text{ V}$		48	nC	
V_F	$I_F = 4 \text{ A}; V_{GE} = 0 \text{ V};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 100^{\circ}\text{C}$		2.3	3 V	
			2	V	
t_{rr}	$I_F = 4 \text{ A}; V_{GE} = 0 \text{ V}; T_{VJ} = 100^{\circ}\text{C}$ $V_R = -300 \text{ V}; di_F/dt = -800 \text{ A}/\mu\text{s}$		55	ns	
Q_{rr}	$I_F = 4 \text{ A}; V_R = -300 \text{ V}; V_{GE} = 0 \text{ V}$ $di_F/dt = -800 \text{ A}/\mu\text{s}$		0.8	μC	
I_r				250 μA	
R_{thJC}	IGBT (per die)		1.55	$^{\circ}\text{C}/\text{W}$	
	Diode (per die)		2.25	$^{\circ}\text{C}/\text{W}$	

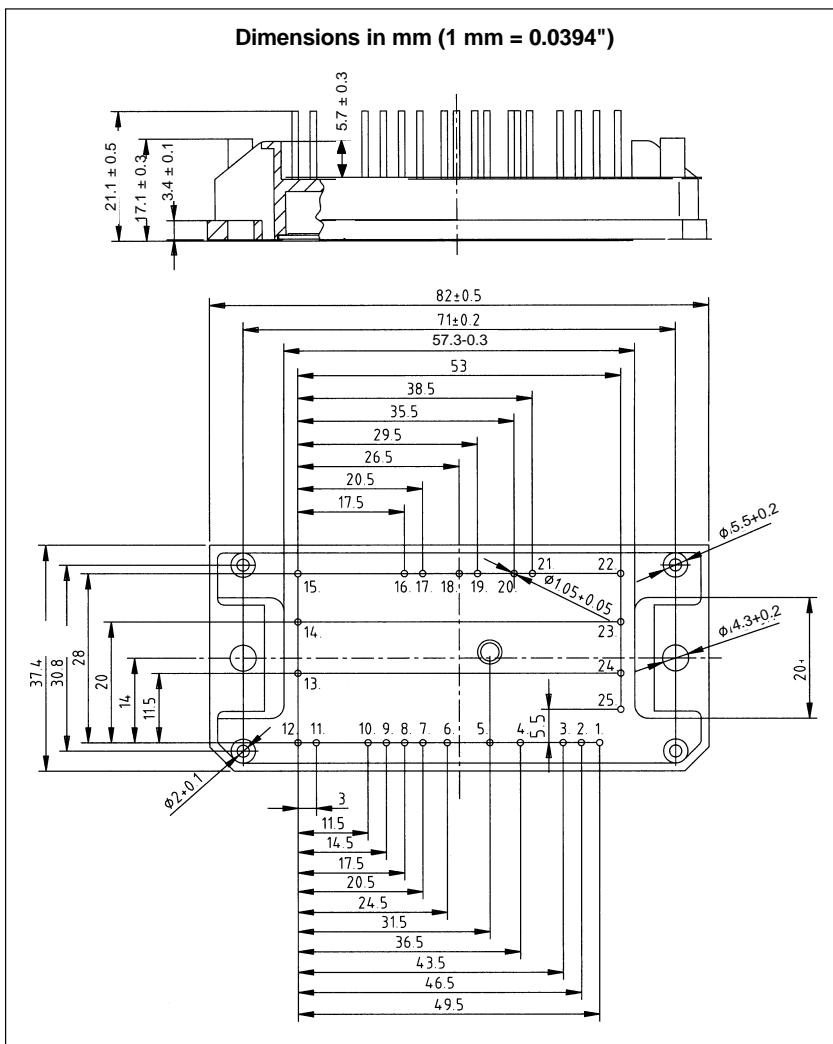
Module

Symbol	Conditions	Maximum Ratings	
T_{stg}		-40...+125	°C
V_{ISOL}	$I_{ISOL} \leq 1 \text{ mA}$; 50/60 Hz; $t = 1 \text{ min}$	2500	V~
M_d	Mounting torque (M4)	2.0 - 2.2 18 - 20	Nm lb.in.
d_s	Creepage distance on surface	12.7	mm
d_A	Strike distance in air	12.7	mm
Weight	typ.	42	g

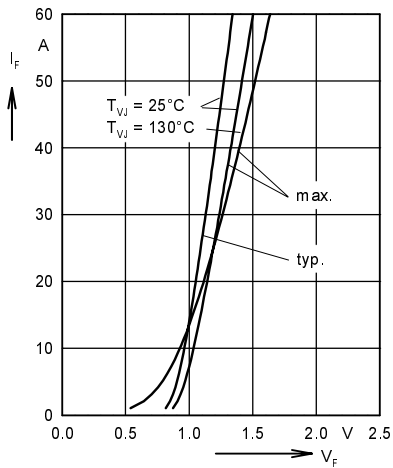
Temperature Sensor R

Symbol	Conditions	Maximum Ratings	
R	$T_{amb} = 20^\circ\text{C}$	4.7	k Ω

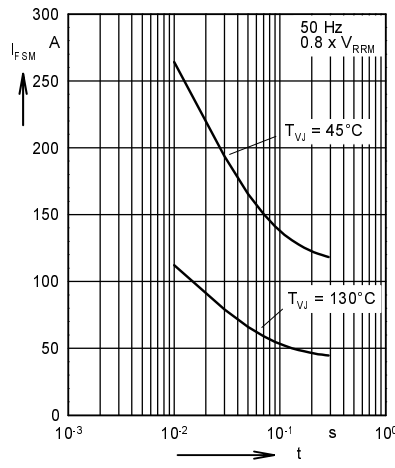
For additional data see C620/4.7k 5% S+M NTC thermistor catalog



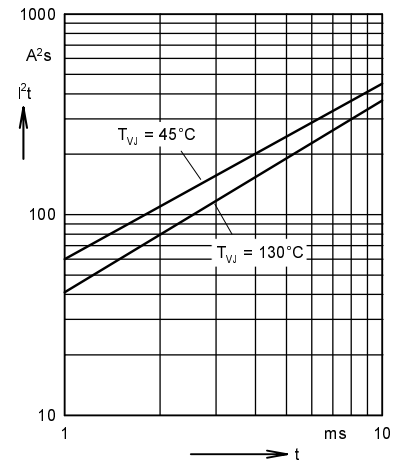
Input Rectifier Bridge D8 - D13



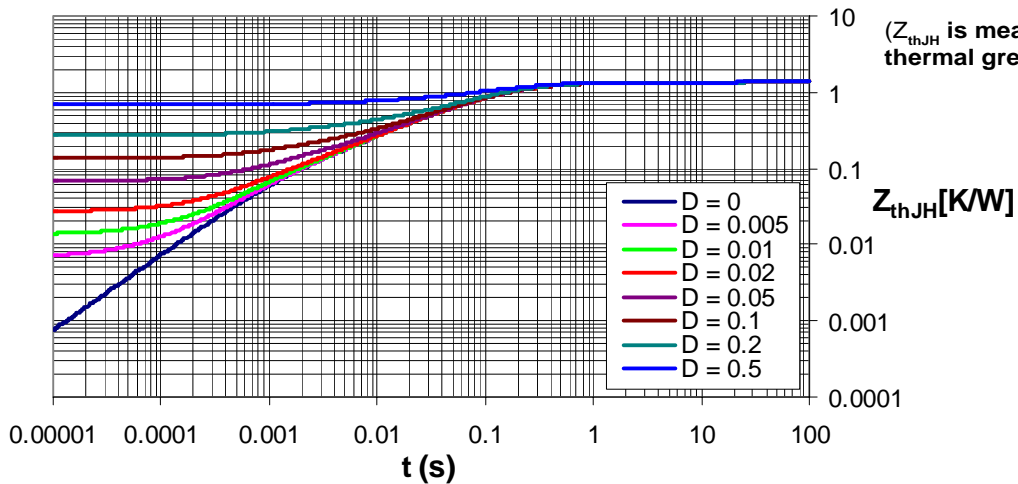
Forward characteristics



Surge overload current
 I_{FSM} : crest value, t : duration

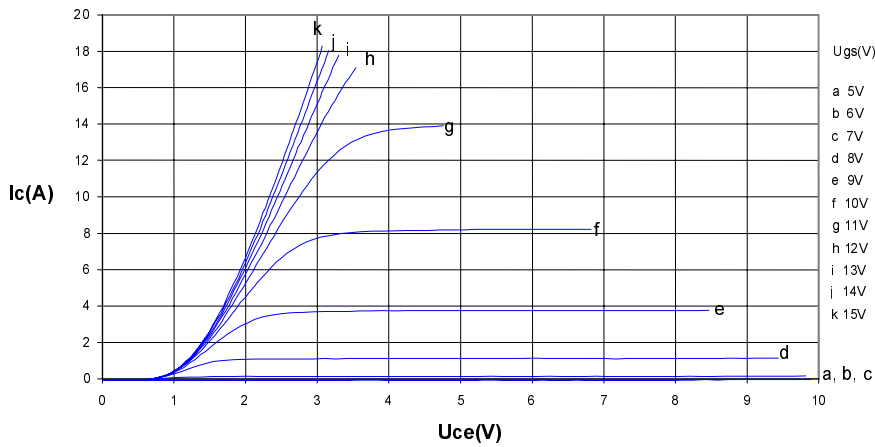
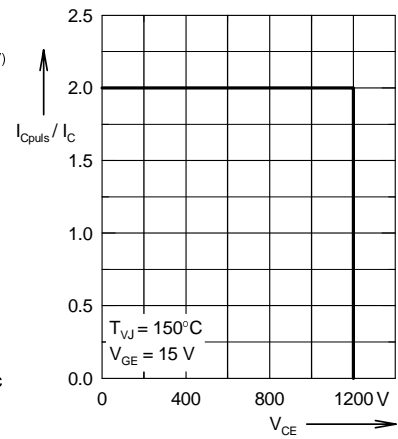
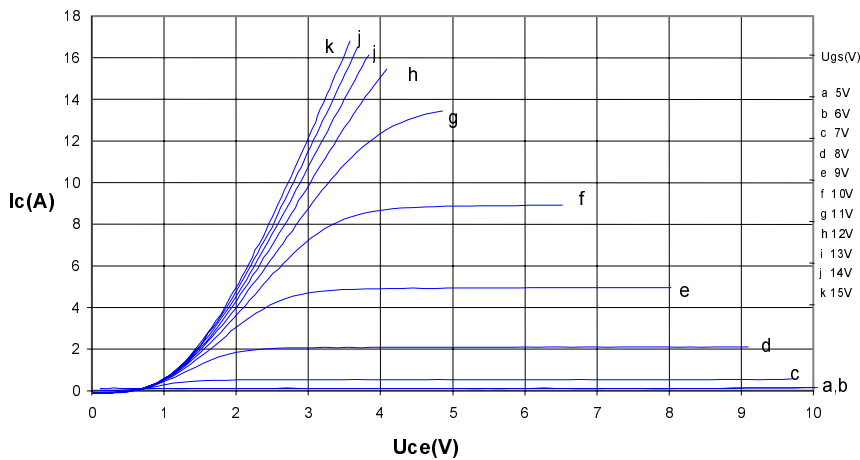
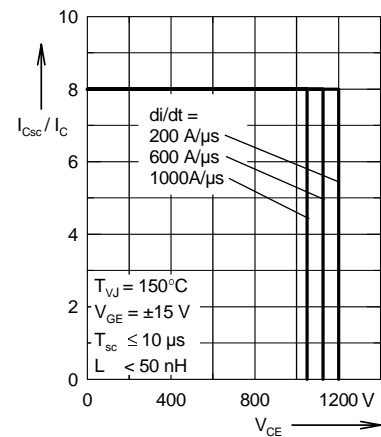
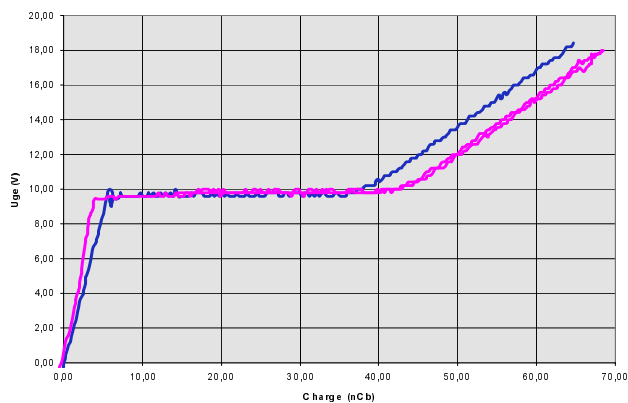
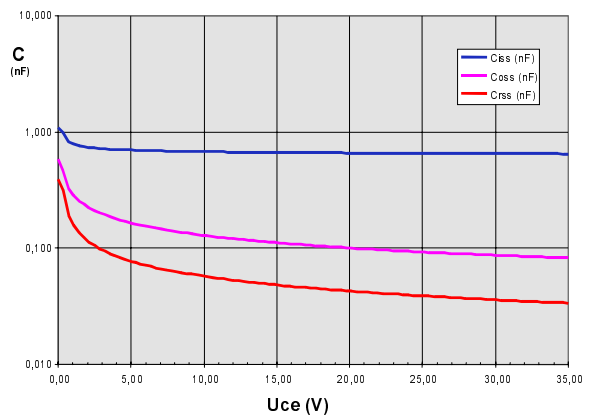


I^2t versus time (1-10 ms)



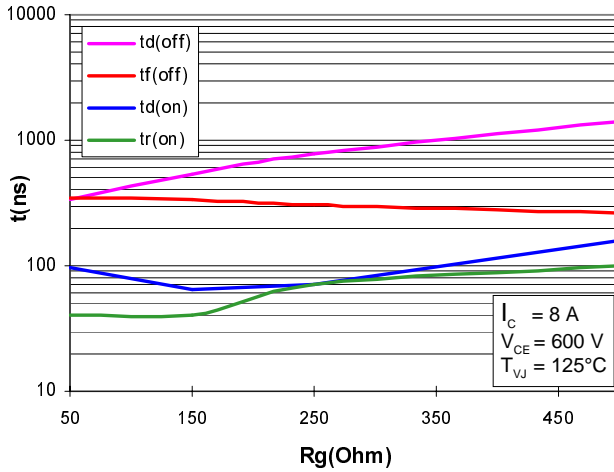
Transient thermal resistance junction to heatsink

(Z_{thJH} is measured using 50 μm thermal grease)

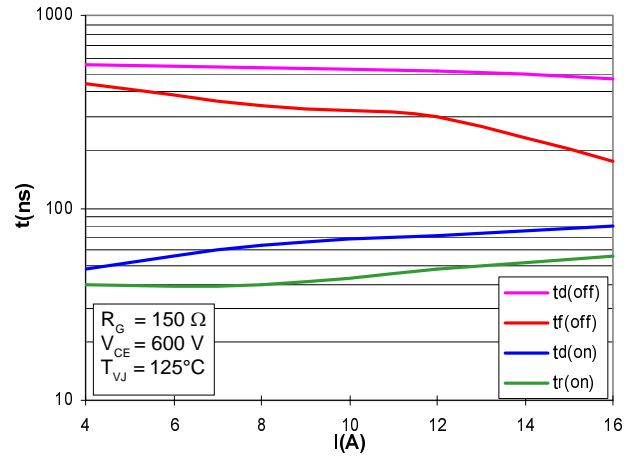
Output Inverter T1 - T6
Typ. output characteristics 25°C

Reverse biased safe operating area

Typ. output characteristics 125°C

Short circuit safe operating area

Typ. gate charge

Typ. capacitances


Output Inverter T1 - T6

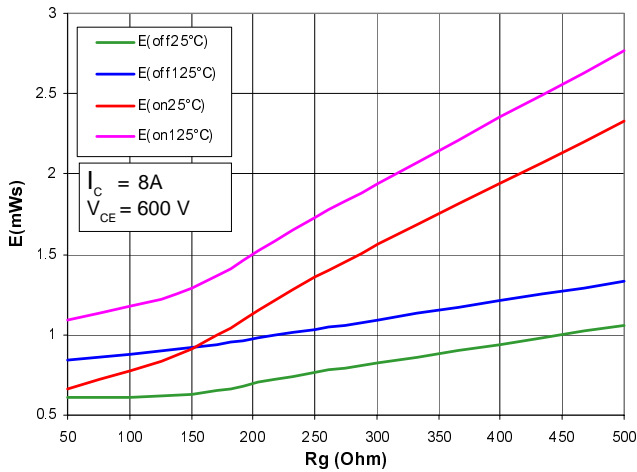
Typ. switching time



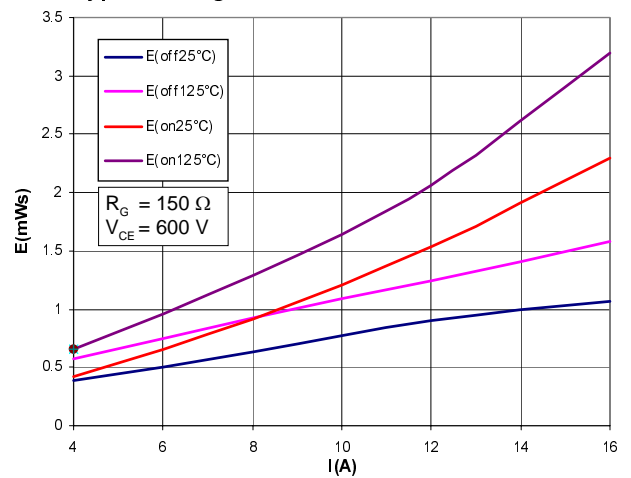
Typ. switching time



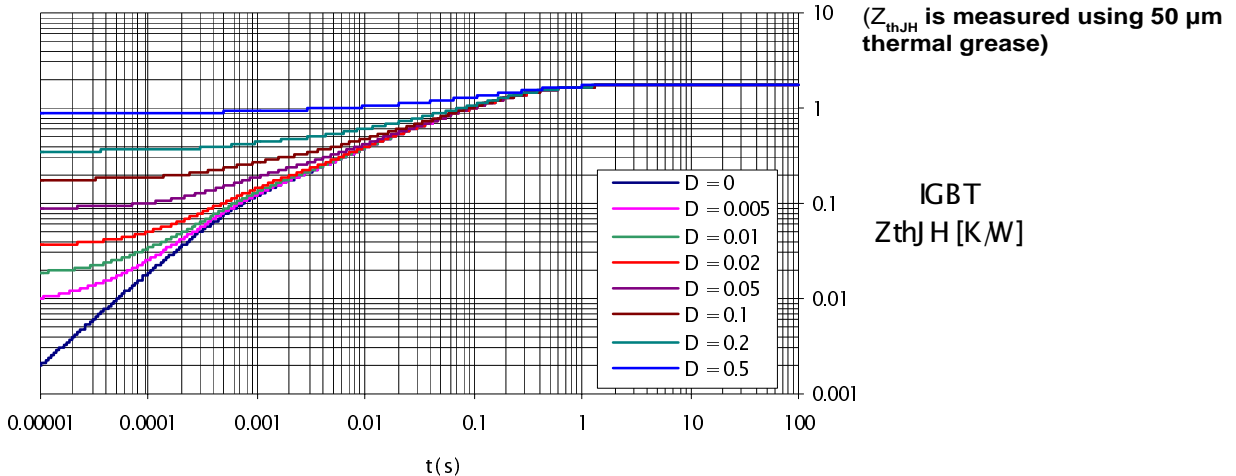
Typ. switching losses



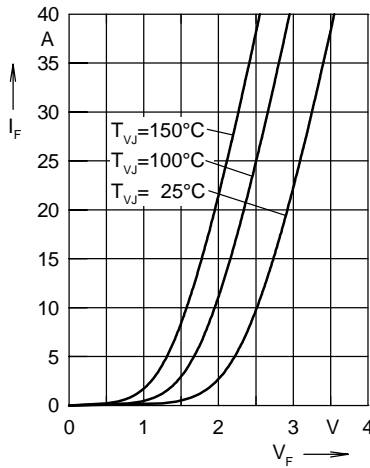
Typ. switching losses



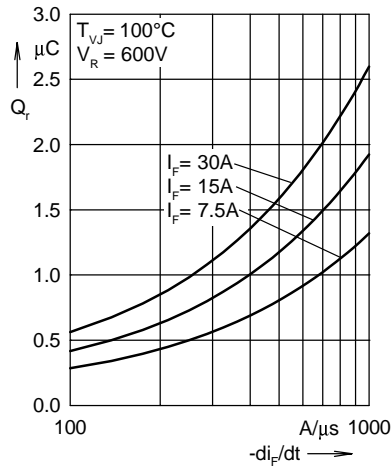
Transient thermal resistance junction to heatsink



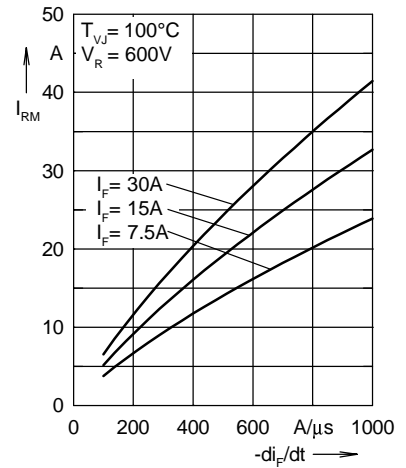
Output Inverter D1 - D6



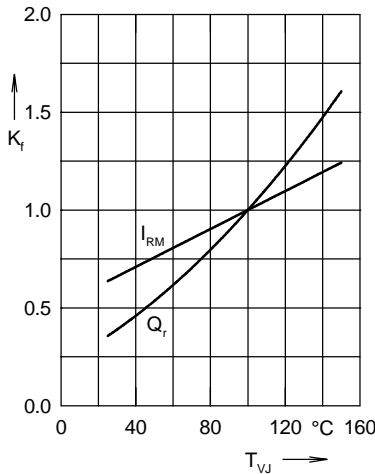
Forward current I_F versus V_F



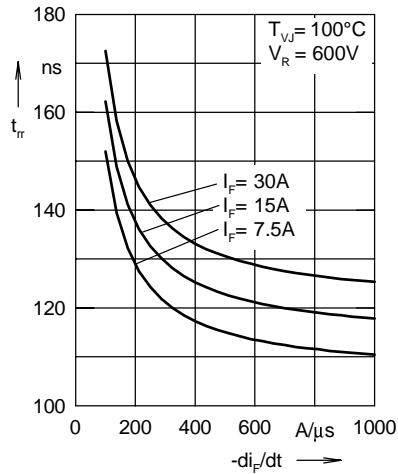
Reverse recovery charge Q_r versus $-di_F/dt$



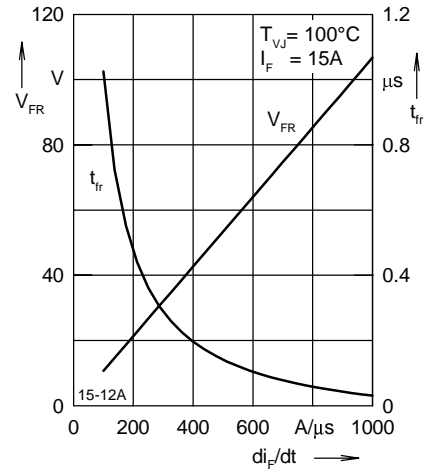
Peak reverse current I_{RM} versus $-di_F/dt$



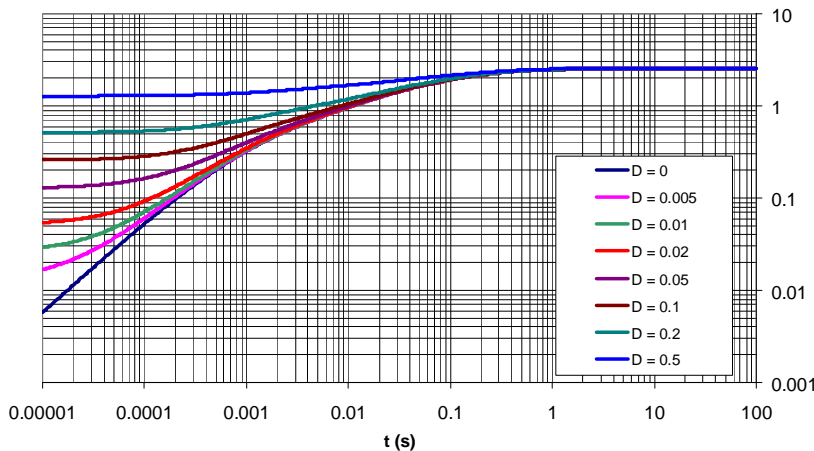
Dynamic parameters Q_r , I_{RM} versus T_{VJ}



Recovery time t_{tr} versus $-di_F/dt$



Peak forward voltage V_{FR} and t_{tr} versus di_F/dt



Transient thermal resistance junction to heatsink

(Z_{thJH} is measured using 50 μm thermal grease)

FRED
 Z_{thJH} [KW]