

# FPAL30SL60

# **Smart Power Module (SPM)**

## **General Description**

FPAL30SL60 is an advanced smart power module (SPM) that Fairchild has newly developed and designed to provide very compact and low cost, yet high performance ac motor drives mainly targeting low speed low-power inverter-driven application like air conditioners. It combines optimized circuit protection and drive matched to low-loss IGBTs. Highly effective short-circuit current detection/protection is realized through the use of advanced current sensing IGBT chips that allow continuous monitoring of the IGBTs current. System reliability is further enhanced by the built-in over-temperature and integrated under-voltage lock-out protection. The high speed built-in HVIC provides optocoupler-less IGBT gate driving capability that further reduce the overall size of the inverter system design. In addition the incorporated HVIC facilitates the use of single-supply drive topology enabling the FPAL30SL60 to be driven by only one drive supply voltage without negative bias.

## **Features**

- UL Certified No. E209204
- 600V-30A 3-phase IGBT inverter bridge including control ICs for gate driving and protection
- Single-grounded power supply due to built-in HVIC
- Typical switching frequency of 3kHz
- Built-in thermistor for over-temperature monitoring
- Inverter power rating of 2kW / 100~253 Vac
- Isolation rating of 2500Vrms/min.
- Very low leakage current due to using ceramic substrate
- Adjustable current protection level by varying series resistor value with sense-IGBTs

## **Applications**

- AC 100V ~ 253V three-phase inverter drive for small power (2kW) ac motor drives
- Home appliances applications requiring low switching frequency operation like air conditioners drive system
- · Application ratings:
  - Power: 2kW / 100~253 Vac
  - Switching frequency : Typical 3kHz (PWM Control)
  - 100% load current: 15A (Irms)

# Top View Bottom View 57 mm Device Name Version, Lot Code Fig. 1.

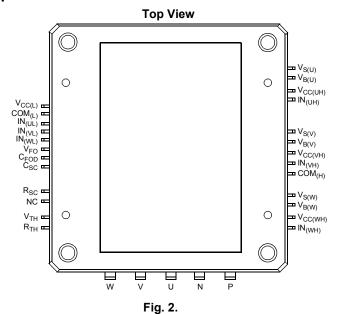
# **Integrated Power Functions**

• 600V-30A IGBT inverter for three-phase DC/AC power conversion (Please refer to Fig. 3)

## Integrated Drive, Protection and System Control Functions

- For inverter high-side IGBTs: Gate drive circuit, High voltage isolated high-speed level shifting
   Control circuit under-voltage (UV) protection
   Note) Available bootstrap circuit example is given in Figs. 11, 16 and 17.
- For inverter low-side IGBTs: Gate drive circuit, Short circuit protection (SC)
   Control supply circuit under-voltage (UV) protection
- Temperature Monitoring: System over-temperature monitoring using built-in thermistor
   Note) Available temperature monitoring circuit is given in Fig. 17.
- Fault signaling: Corresponding to a SC fault (Low-side IGBTs) or a UV fault (Low-side supply)
- Input interface: 5V CMOS/LSTTL compatible, Schmitt trigger input

# **Pin Configuration**



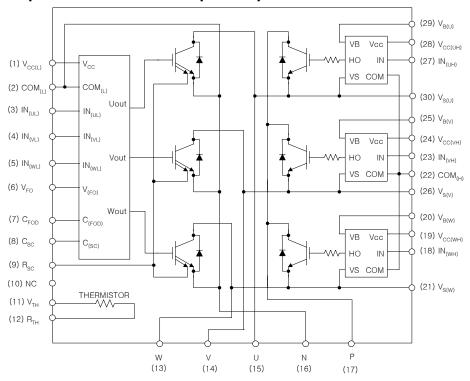
# **Pin Descriptions**

Pin Number	Pin Name	Pin Description
1	V <sub>CC(L)</sub>	Low-side Common Bias Voltage for IC and IGBTs Driving
2	COM <sub>(L)</sub>	Low-side Common Supply Ground
3	IN <sub>(UL)</sub>	Signal Input Terminal for Low-side U Phase
4	IN <sub>(VL)</sub>	Signal Input Terminal for Low-side V Phase
5	IN <sub>(WL)</sub>	Signal Input Terminal for Low-side W Phase
6	V <sub>FO</sub>	Fault Output Terminal
7	C <sub>FOD</sub>	Capacitor for Fault Output Duration Time Selection
8	C <sub>SC</sub>	Capacitor (Low-pass Filter) for Short-current Detection Input
9	R <sub>SC</sub>	Resistor for Short-circuit Current Detection
10	NC	NO Connection
11	V <sub>TH</sub>	Thermistor Bias Voltage
12	R <sub>TH</sub>	Series Resistor for the Use of Thermistor (Temperature Detection)
13	W	Output Terminal for W Phase
14	V	Output Terminal for V Phase
15	U	Output Terminal for U Phase

# Pin Descriptions (Continued)

Pin Number	Pin Name	Pin Description
16	N	Negative DC–Link Input
17	Р	Positive DC–Link Input
18	IN <sub>(WH)</sub>	Signal Input Terminal for High-side W Phase
19	V <sub>CC(WH)</sub>	High-side Bias Voltage for W Phase IC
20	V <sub>B(W)</sub>	High-side Bias Voltage for W Phase IGBT Driving
21	V <sub>S(W)</sub>	High-side Bias Voltage Ground for W Phase IGBT Driving
22	COM <sub>(H)</sub>	High-side Common Supply Ground
23	IN <sub>(VH)</sub>	Signal Input Terminal for High-side V Phase
24	V <sub>CC(VH)</sub>	High-side Bias Voltage for V Phase IC
25	V <sub>B(V)</sub>	High-side Bias Voltage for V Phase IGBT Driving
26	V <sub>S(V)</sub>	High-side Bias Voltage Ground for V Phase IGBT Driving
27	IN <sub>(UH)</sub>	Signal Input Terminal for High-side U Phase
28	V <sub>CC(UH)</sub>	High-side Bias Voltage for U Phase IC
29	$V_{B(U)}$	High-side Bias Voltage for U Phase IGBT Driving
30	$V_{S(U)}$	High-side Bias Voltage Ground for U Phase IGBT Driving

# **Internal Equivalent Circuit and Input/Output Pins**



- Note

  1. Inverter low-side ( (1) (12) pins) is composed of three sense-IGBTs including freewheeling diodes for each IGBT and one control IC which has gate driving, current sensing and protection functions.

  2. Inverter power side ( (13) – (17) pins) is composed of two inverter dc-link input terminals and three inverter output terminals.

  3. Inverter high-side ( (18) – (30) pins) is composed of three normal-IGBTs including freewheeling diodes and three drive ICs for each IGBT.

Fig. 3.

# **Absolute Maximum Ratings**

**Inverter Part** (T<sub>C</sub> = 25°C, Unless Otherwise Specified)

Item	Symbol	Condition	Rating	Unit
Supply Voltage	$V_{DC}$	Applied to DC - Link	450	V
Supply Voltage (Surge)	V <sub>PN(Surge)</sub>	Applied between P- N	500	V
Collector-emitter Voltage	V <sub>CES</sub>		600	V
Each IGBT Collector Current	± I <sub>C</sub>	T <sub>C</sub> = 25°C (Note Fig. 4)	30	Α
Each IGBT Collector Current (Peak)	± I <sub>CP</sub>	T <sub>C</sub> = 25°C (Note Fig. 4)	60	Α
Collector Dissipation	P <sub>C</sub>	T <sub>C</sub> = 25°C per One Chip	56	W
Operating Junction Temperature	TJ	(Note 1)	-55 ~ 150	°C

# Control Part (T<sub>C</sub> = 25°C, Unless Otherwise Specified)

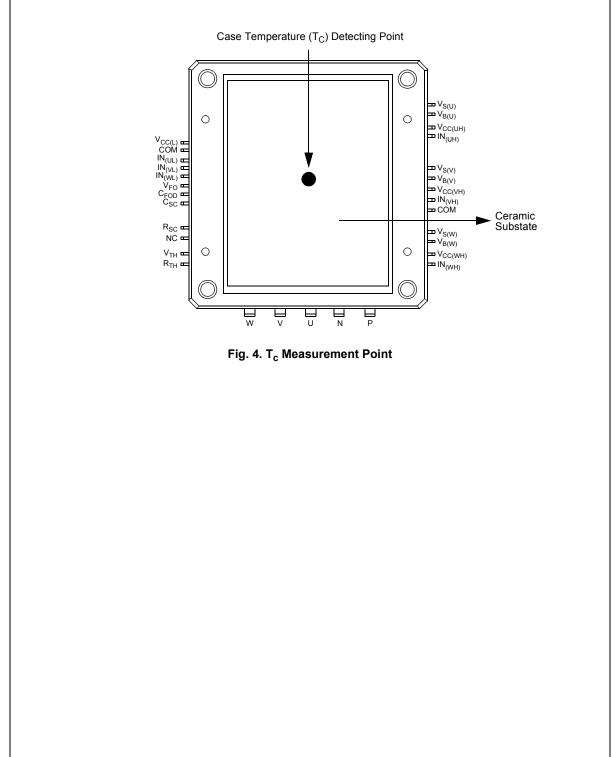
Item	Symbol	Condition	Rating	Unit
Control Supply Voltage	$V_{CC}$	Applied between $V_{CC(H)}$ - $COM_{(H)}$ , $V_{CC(L)}$ - $COM_{(L)}$	18	V
High-side Control Bias Voltage	V <sub>BS</sub>	Applied between $V_{B(U)}$ - $V_{S(U)}$ , $V_{B(V)}$ - $V_{S(V)}$ , $V_{B(W)}$ - $V_{S(W)}$	20	V
Input Signal Voltage	V <sub>IN</sub>	Applied between $IN_{(UH)}$ , $IN_{(VH)}$ , $IN_{(WH)}$ - $COM_{(H)}$ $IN_{(UL)}$ , $IN_{(VL)}$ , $IN_{(WL)}$ - $COM_{(L)}$	-0.3 ~ 6.0	٧
Fault Output Supply Voltage	$V_{FO}$	Applied between V <sub>FO</sub> - COM <sub>(L)</sub>	-0.3~V <sub>CC</sub> +0.5	V
Fault Output Current	I <sub>FO</sub>	Sink Current at V <sub>FO</sub> Pin	5	mA
Current Sensing Input Voltage	$V_{SC}$	Applied between C <sub>SC</sub> - COM <sub>(L)</sub>	-0.3~V <sub>CC</sub> +0.5	V

# **Total System**

Item	Symbol	Condition	Rating	Unit
Self Protection Supply Voltage Limit (Short Circuit Protection Capability)	V <sub>PN(PROT)</sub>	Applied to DC - Link, $V_{CC} = V_{BS} = 13.5 \sim 16.5V$ $T_{J} = 125^{\circ}C$ , Non-repetitive, less than 6 $\mu$ s	400	V
Module Case Operation Temperature	T <sub>C</sub>	Note Fig. 4	-20 ~ 100	°C
Storage Temperature	T <sub>STG</sub>		-55 ~ 150	°C
Isolation Voltage	V <sub>ISO</sub>	60Hz, Sinusoidal, AC 1 minute, Connection Pins to Heat-sink Plate	2500	V <sub>rms</sub>

Note

1. It would be recommended that the average junction temperature should be limited to  $T_J \le 125^{\circ}C$  (@ $T_C \le 100^{\circ}C$ ) in order to guarantee safe operation.



# **Absolute Maximum Ratings**

## **Thermal Resistance**

Item	Symbol	Condition		Тур.	Max.	Unit
Junction to Case Thermal Resistance	R <sub>th(j-c)Q</sub>	Each IGBT under Inverter Operating Condition (Note 2)		-	2.2	°C/W
	R <sub>th(j-c)F</sub>	Each FWDi under Inverter Operating Condition (Note 2)	-	-	3.18	°C/W
Contact Thermal Resistance	R <sub>th(c-f)</sub>	Ceramic Substrate (per 1 Module) Thermal Grease Applied		ı	0.06	°C/W

## **Electrical Characteristics**

**Inverter Part** (T<sub>j</sub> = 25°C, Unless Otherwise Specified)

Item	Symbol	Conditi	on	Min.	Тур.	Max.	Unit
Collector - emitter	V <sub>CE(SAT)</sub>	$V_{CC} = V_{BS} = 15V$ $V_{IN} = 0V$	$I_C = 30A, T_i = 25^{\circ}C$	-	-	2.5	V
Saturation Voltage	, ,	V <sub>IN</sub> = 0V	$I_C = 30A, T_i = 125^{\circ}C$	-	-	2.6	V
FWDi Forward Voltage	$V_{FM}$	V <sub>IN</sub> = 5V	$I_C = 30A, T_i = 25^{\circ}C$	-	-	2.6	V
			$I_C = 30A, T_i = 125^{\circ}C$	-	-	2.4	V
Switching Times	t <sub>ON</sub>	$V_{PN} = 300V, V_{CC} = V_{BS} = 15$	-	0.45	-	us	
	t <sub>C(ON)</sub>	$I_C = 30A, T_j = 25^{\circ}C$		-	0.18	-	us
	t <sub>OFF</sub>	$V_{IN} = 5V \leftrightarrow 0V$ , Inductive Lo	ad	-	0.9	-	us
	t <sub>C(OFF)</sub>	(High-Low Side)		-	0.36	-	us
	t <sub>rr</sub>	(Note 3)			0.1	-	us
Collector - emitter Leakage Current	I <sub>CES</sub>	$V_{CE} = V_{CES}, T_j = 25^{\circ}C$		-	-	250	uA

 $<sup>\</sup>label{eq:Note} \mbox{2. For the measurement point of case temperature ($T_c$), please refer to Fig. 4.}$ 

Note
3. toN and toFF include the propagation delay time of the internal drive IC. to(ON) and to(OFF) are the switching time of IGBT itself under the given gate driving condition internally. For the detailed information, please see Fig. 5.

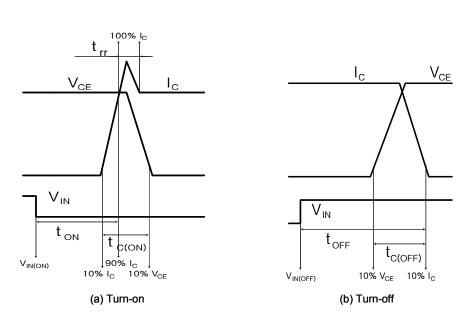
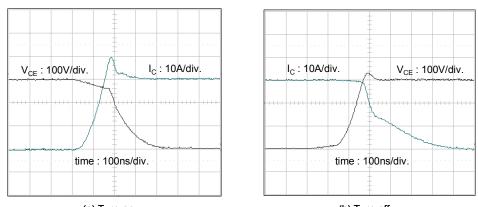


Fig. 5. Switching Time Definition



(a) Turn-on (b) Turn-off Fig. 6. Experimental Results of Switching Waveforms Test Condition: Vdc=300V, Vcc=15V, L=500uH (Inductive Load), T<sub>C</sub>=25°C

# **Electrical Characteristics**

Control Part (T<sub>i</sub> = 25°C, Unless Otherwise Specified)

Item	Symbol		Condition	Min.	Тур.	Max.	Unit
Control Supply Voltage	V <sub>CC</sub>	Applied between V <sub>CC</sub>	<sub>(H)</sub> ,V <sub>CC(L)</sub> - COM	13.5	15	16.5	V
High-side Bias Voltage	V <sub>BS</sub>			13.5	15	16.5	V
Quiescent V <sub>CC</sub> Supply Current	I <sub>QCCL</sub>	$V_{CC} = 15V$ $IN_{(UL, VL, WL)} = 5V$	V <sub>CC(L)</sub> - COM <sub>(L)</sub>	1	-	26	mA
	I <sub>QCCH</sub>	V <sub>CC</sub> = 15V IN <sub>(UH, VH, WH)</sub> = 5V	$V_{CC(U)}$ , $V_{CC(V)}$ , $V_{CC(W)}$ - $COM_{(H)}$	1	-	130	uA
Quiescent V <sub>BS</sub> Supply Current	I <sub>QBS</sub>		$egin{array}{l} V_{B(U)} - V_{S(U)}, \ V_{B(V)} - V_{S(V)}, \ V_{B(W)} - V_{S(W)} \end{array}$	1	-	420	uA
Fault Output Voltage	$V_{FOH}$	V <sub>SC</sub> = 0V, V <sub>FO</sub> Circuit:		4.5	-	-	V
	$V_{FOL}$	V <sub>SC</sub> = 1V, V <sub>FO</sub> Circuit:		ı	-	1.1	V
PWM Input Frequency	f <sub>PWM</sub>	$T_C \le 100^{\circ}C, T_J \le 125^{\circ}$	°C	1	3	-	kHz
Allowable Input Signal Blanking Time considering Leg Arm-short	t <sub>dead</sub>	-20°C ≤ T <sub>C</sub> ≤ 100°C		3	-	-	us
Short Circuit Trip Level	V <sub>SC(ref)</sub>	$T_J = 25^\circ$ , $V_{CC} = 15V$ (	Note 4)	0.45	0.51	0.56	V
Sensing Voltage of IGBT Current	V <sub>SEN</sub>	$-20^{\circ}\text{C} \le \text{T}_{\text{C}} \le 100^{\circ}\text{C}, \text{ (}$ $\text{I}_{\text{C}} = 30\text{A} \text{ (Note Fig. 8)}$		0.37	0.45	0.56	V
Supply Circuit Under-	UV <sub>CCD</sub>	T <sub>J</sub> ≤ 125°C	Detection Level	11.5	12	12.5	V
Voltage Protection	UV <sub>CCR</sub>		Reset Level	12	12.5	13	V
	UV <sub>BSD</sub>		Detection Level	7.3	9.0	10.8	V
	UV <sub>BSR</sub>		Reset Level	8.6	10.3	12	V
Fault-out Pulse Width	t <sub>FOD</sub>	V <sub>CC</sub> = 15V, C(sc) = 1V C <sub>FOD</sub> = 33nF (Note 5)		1.4	1.8	2.0	ms
ON Threshold Voltage	V <sub>IN(ON)</sub>	High-Side	Applied between IN <sub>(UH)</sub> , IN <sub>(VH)</sub> ,	ı	-	8.0	V
OFF Threshold Voltage	V <sub>IN(OFF)</sub>		IN <sub>(WH)</sub> - COM <sub>(H)</sub>	3.0	-	-	V
ON Threshold Voltage	V <sub>IN(ON)</sub>	Low-Side	Applied between IN <sub>(UL)</sub> , IN <sub>(VL)</sub> ,	-	-	8.0	V
OFF Threshold Voltage	V <sub>IN(OFF)</sub>	I aa. ` ' ` ' F		3.0	-	-	V
Resistance of Thermistor	R <sub>TH</sub>	@ T <sub>C</sub> = 25°C (Note Figs. 4 and 7)		ı	50	-	kΩ
		@ T <sub>C</sub> = 80°C (Note Fi	gs. 4 and 7)	-	6.3	-	kΩ

Note
4. Short-circuit current protection is functioning only at the low-sides. It would be recommended that the value of the external sensing resistor (R<sub>SC</sub>) should be selected around 56 Ω in order to make the SC trip-level of about 45A.

Please refer to Fig. 8 which shows the current sensing characteristics according to sensing resistor R<sub>SC</sub>.

5. The fault-out pulse width t<sub>FOD</sub> depends on the capacitance value of C<sub>FOD</sub> according to the following approximate equation: C<sub>FOD</sub> = 18.3 x 10<sup>-6</sup> x t<sub>FOD</sub>[F]

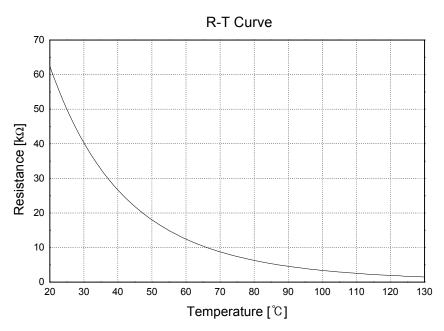


Fig. 7. R-T Curve of The Built-in Thermistor

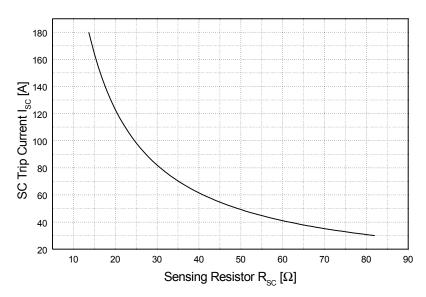


Fig. 8. Relationship between Sensing Resistor and SC Trip Current for Short-Circuit Protection ( $I_{SC}$  = 82 × Rating Current(30A) /  $R_{SC}$ )

# **Mechanical Characteristics and Ratings**

lto-m		Condition	Limits			Units	
Item		Condition	Min.	Тур.	Max.	Units	
Mounting Torque	Mounting Screw: M3	Recommended 10Kg•cm	8	10	12	Kg•cm	
	(Note 6 and 7)	Recommended 0.98N•m	0.78	0.98	1.17	N•m	
Ceramic Flatness		(Note Fig. 9)	0	_	+100	um	
Weight			-	56	-	g	

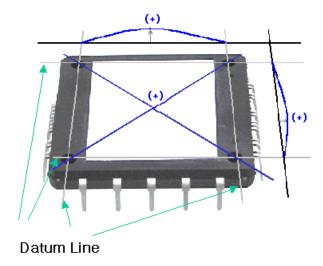


Fig. 9. Flatness Measurement Position of The Ceramic Substrate

- 6. Do not make over torque or mounting screws. Much mounting torque may cause ceramic cracks and bolts and AI heat-fin destruction.

  7. Avoid one side tightening stress. Fig.10 shows the recommended torque order for mounting screws. Uneven mounting can cause the SPM ceramic substrate to be damaged.

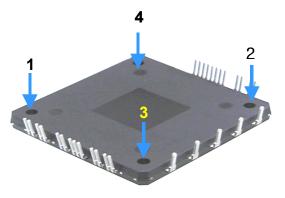
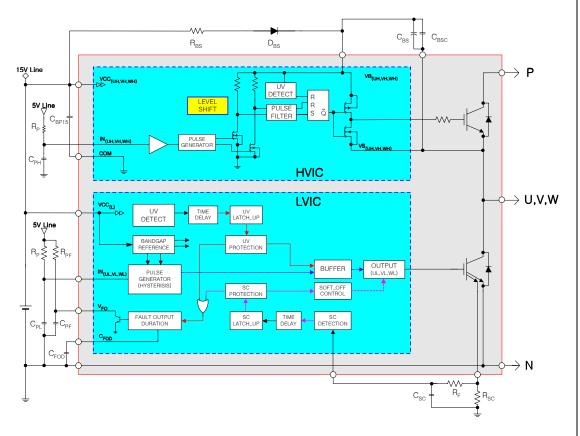


Fig. 10. Mounting Screws Torque Order  $(1 \rightarrow 2 \rightarrow 3 \rightarrow 4)$ 

# **Recommended Operating Conditions**

Itama	Cumbal	On an elistica an		Value		
Item	Symbol	Condition	Min.	Тур.	Max.	Unit
Supply Voltage	$V_{PN}$	Applied between P - N	-	300	400	V
Control Supply Voltage	V <sub>CC</sub>	Applied between V <sub>CC(H)</sub> - COM, V <sub>CC(L)</sub> - COM	13.5	15	16.5	V
High-side Bias Voltage	V <sub>BS</sub>	Applied between $V_{B(U)}$ - $V_{S(U)}$ , $V_{B(V)}$ - $V_{S(V)}$ , $V_{B(W)}$ - $V_{S(W)}$	13.5	15	16.5	V
Blanking Time for Preventing Arm-short	t <sub>dead</sub>	For Each Input Signal	3	-	-	us
PWM Input Signal	f <sub>PWM</sub>	$T_C \le 100^{\circ}C, T_J \le 125^{\circ}C$	-	3	-	kHz
Input ON Threshold Voltage	V <sub>IN(ON)</sub>	Applied between U <sub>IN</sub> ,V <sub>IN</sub> , W <sub>IN</sub> - COM		0 ~ 0.65	5	V
Input OFF Threshold Voltage	V <sub>IN(OFF)</sub>	Applied between U <sub>IN</sub> ,V <sub>IN</sub> , W <sub>IN</sub> - COM		4 ~ 5.5		V

## **ICs Internal Structure and Input/Output Conditions**



- Note
  1. One LVIC drives three Sense-IGBTs and can do short-circuit current protection also. Three sense emitters are commonly connected to R<sub>SC</sub> terminal to detect

- One EVIC direction that the desired bits and cannot solition that the desired bits are commonly connected to N<sub>SC</sub> terminal to detect short-circuit current. Low-side part of the inverter consists of three sense-IGBTs

  One HVIC drives one normal-IGBT. High-side part of the inverter consists of three normal-IGBTs

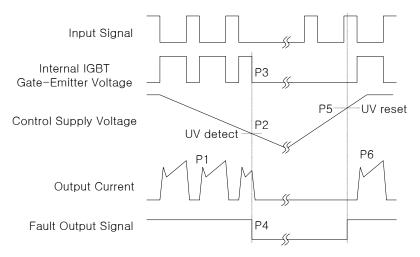
  Each IC has under voltage detection and protection function.

  The logic input is compatible with standard CMOS or LSTTL outputs.

  R<sub>P</sub>C<sub>P</sub> coupling at each input/output is recommended in order to prevent the gating input/output signals oscillation and it should be as close as possible to each SPM gating input pin.
- It would be recommended that the bootstrap diode, D<sub>BS</sub>, has soft and fast recovery characteristics.

Fig. 11.

# **Time Charts of SPMs Protective Function**

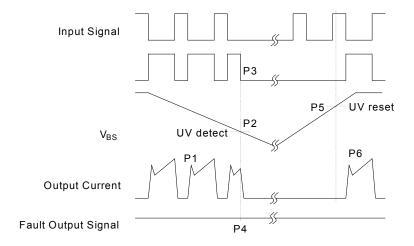


P1: Normal operation - IGBT ON and conducting current

P2 : Under voltage detection P3 : IGBT gate interrupt P4 : Fault signal generation P5 : Under voltage reset

P6: Normal operation - IGBT ON and conducting current

Fig. 12. Under-Voltage Protection (Low-side)

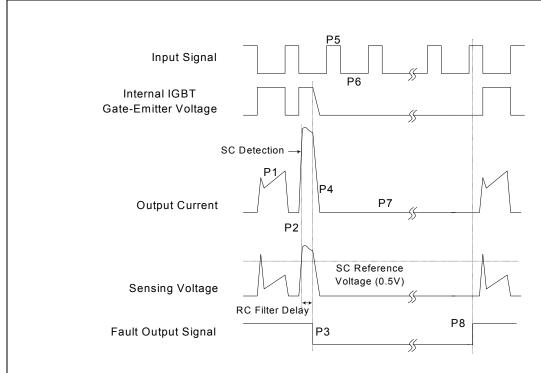


P1: Normal operation - IGBT ON and conducting current

P2 : Under voltage detection P3 : IGBT gate interrupt P4 : No fault signal P5 : Under voltage reset

P6: Normal operation - IGBT ON and conducting current

Fig. 13. Under-Voltage Protection (High-side)



P1: Normal operation - IGBT ON and conducting currents

P2 : Short-circuit current detection

P3: IGBT gate interrupt / Fault signal generation

P4: IGBT is slowly turned off

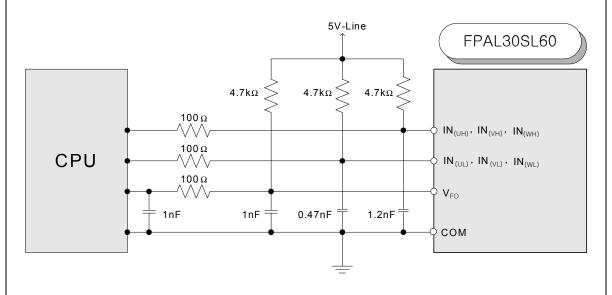
P5: IGBT OFF signal

P6: IGBT ON signal - but IGBT cannot be turned on during the fault-output activation

P7: IGBT OFF state

P8: Fault-output reset and normal operation start

Fig. 14. Short-circuit Current Protection (Low-side Operation only)



It would be recommended that by-pass capacitors for the gating input signals, IN(XX) should be placed on the SPM pins and on the both sides of CPU and SPM for the fault output signal, V<sub>FO</sub>, as close as possible.

Fig. 15. Recommended CPU I/O Interface Circuit

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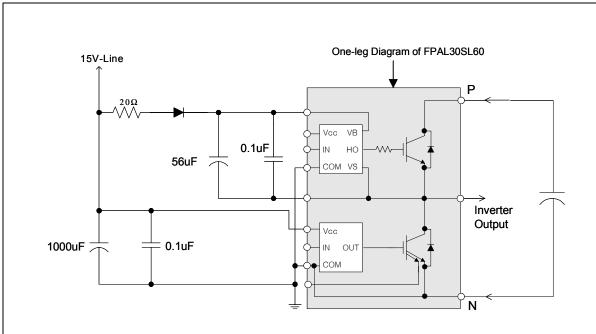
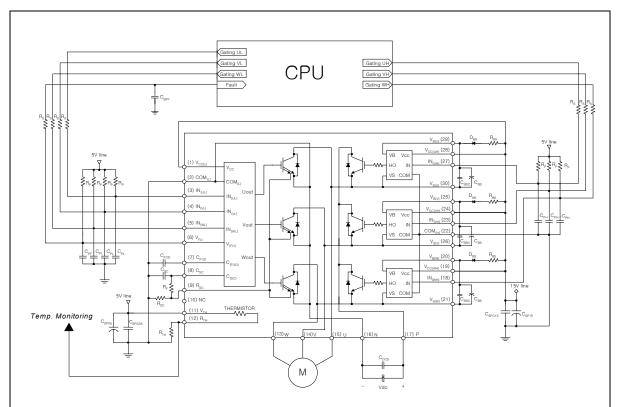


Fig. 16. Recommended Bootstrap Operation Circuit and Parameters

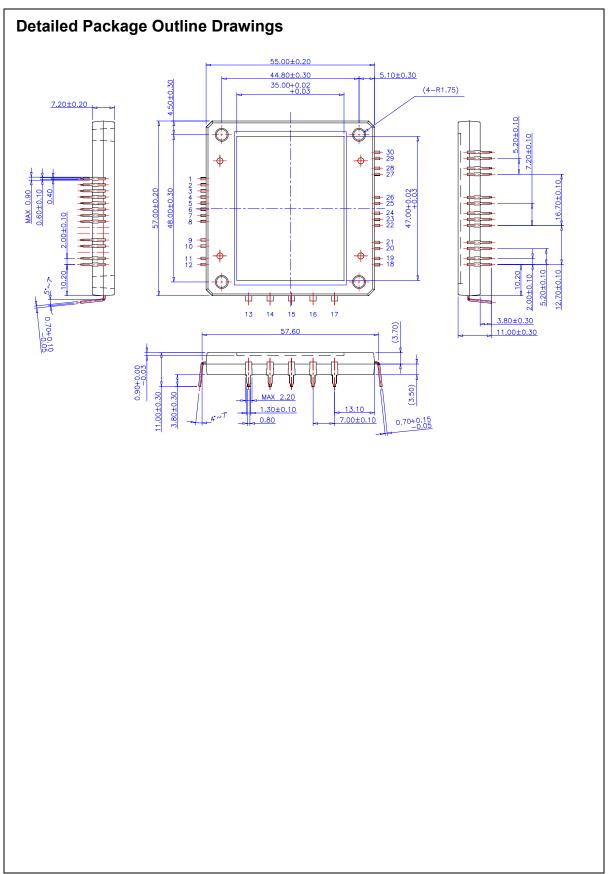


- 1. R<sub>P</sub>C<sub>PL</sub>/R<sub>P</sub>C<sub>PH</sub> coupling at each SPM input is recommended in order to prevent input signals' oscillation and it should be as close as possible to each SPM input
- 2. By virtue of integrating an application specific type HVIC inside the SPM, direct coupling to CPU terminals without any opto-coupler or transformer isolation is possible.
- V<sub>FO</sub> output is open collector type. This signal line should be pulled up to the positive side of the 5V power supply with approximately 4.7kΩ resistance. Please refer to Fig. 15.
- $C_{SP15}$  of around 7 times larger than bootstrap capacitor  $C_{BS}$  is recommended.  $V_{FO}$  output pulse width should be determined by connecting an external capacitor( $C_{FOD}$ ) between  $C_{FOD}$ (pin7) and  $COM_{(L)}$ (pin2). (Example : if  $C_{FOD}$  = 5.6 nF, then  $t_{FO}$  = 300  $\mu s$  (typ.)) Please refer to the note 5 for calculation method.
- 6. Each input signal line should be pulled up to the 5V power supply with approximately 4.7kΩ resistance (other RC coupling circuits at each input may be needed depending on the PWM control scheme used and on the wiring impedance of the system's printed circuit board). Approximately a 0.22~2nF by-pass capacitor should be used across each power supply connection terminals.

  7. To prevent errors of the protection function, the wiring around R<sub>SC</sub>, R<sub>F</sub> and C<sub>SC</sub> should be as short as possible.

  8. In the short-circuit protection circuit, please select the R<sub>F</sub>C<sub>SC</sub> time constant in the range 3~4 µs. R<sub>F</sub> should be at least 30 times larger than R<sub>SC</sub>. (Recommended
- Example:  $R_{SC}$  = 56  $\Omega$ ,  $R_{F}$  = 3.9k $\Omega$  and  $C_{SC}$  = 1nF) 9. Each capacitor should be mounted as close to the pins of the SPM as possible.
- 10. To prevent surge destruction, the wiring between the smoothing capacitor and the P&N pins should be as short as possible. The use of a high frequency non-inductive capacitor of around 0.1~0.22 uF between the P&N pins is recommended.
- 11.Relays are used at almost every systems of electrical equipments of home appliances. In these cases, there should be sufficient distance between the CPU and the relays. It is recommended that the distance be 5cm at least

Fig. 17. Application Circuit



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Bottomless™	FAST <sup>®</sup>	LittleFET™	Power247™	SuperSOT™-3
CoolFET™	FASTr™	MicroFET™	PowerTrench <sup>®</sup>	SuperSOT™-6
$CROSSVOLT^{\text{TM}}$	FRFET™	MicroPak™	QFET™	SuperSOT™-8
DOME™	GlobalOptoisolator™	MICROWIRE™	QS™	SyncFET™
EcoSPARK™	GTO™	MSX™	QT Optoelectronics™	TinyLogic <sup>®</sup>
E <sup>2</sup> CMOS™	HiSeC™	MSXPro™	Quiet Series™	TruTranslation™
EnSigna™	I <sup>2</sup> C™	OCX™	RapidConfigure™	UHC™
Across the board.	Around the world.™	OCXPro™	RapidConnect™	UltraFET <sup>®</sup>
The Power Franchise™		OPTOLOGIC <sup>®</sup>	SILENT SWITCHER®	VCX™
Programmable Ad	ctive Droop™	OPTOPLANAR™	SMART START™	

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As used herein:

- 1. Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, or (c) whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in significant injury to the user.
- 2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

## **PRODUCT STATUS DEFINITIONS**

## **Definition of Terms**

Datasheet Identification	Product Status	Definition
Advance Information	Formative or In Design	This datasheet contains the design specifications for product development. Specifications may change in any manner without notice.
Preliminary	First Production	This datasheet contains preliminary data, and supplementary data will be published at a later date. Fairchild Semiconductor reserves the right to make changes at any time without notice in order to improve design.
No Identification Needed	Full Production	This datasheet contains final specifications. Fairchild Semiconductor reserves the right to make changes at any time without notice in order to improve design.
Obsolete	Not In Production	This datasheet contains specifications on a product that has been discontinued by Fairchild semiconductor. The datasheet is printed for reference information only.