

# 128K x 9 Bit Separate I/O Synchronous Fast Static RAM

The MCM67Q709A is a 1,179,648-bit static random access memory, organized as 131,072 words of 9 bits. It features separate TTL input and output buffers, which drive 3.3 V output levels and incorporates input and output registers on-board with high speed SRAM. It also features transparent-write and data pass-through capabilities.

The synchronous design allows for precise cycle control with the use of an external single clock (K). The addresses (A0 – A16), data input (D0 – D8), data output (Q0 – Q8), write enable (W), chip enable (E), and output enable (G), are registered in on the rising edge of clock (K).

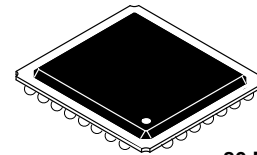
The control pins (E, W, G) function differently in comparison to most synchronous SRAMs. This device will not deselect with E high. The RAM remains active at all times. If E is registered high, the output pins (Q0 – Q8) will be driven if G is registered low. The transparent write feature allows the output data to track the input data. E, G, and W must be asserted to perform a transparent write (write and pass-through). The input data is available at the outputs on the next rising edge of clock (K).

The pass-through function is always enabled. E high disables the write to the array while allowing a pass-through cycle to occur on the next rising edge of clock (K). Only a registered G high will three-state the outputs.

The MCM67Q709A is available in an 86-bump surface mount PBGA (Plastic Ball Grid Array) package.

- Single 5 V ± 5% Power Supply
- Fast Cycle Time: 10 ns Max
- Single Clock Operation
- TTL Input and Output Levels (Outputs LVTTTL Compatible)
- Address, Data Input, E, W, G Registers On-Chip
- 100 MHz Maximum Clock Cycle Time
- Self-Timed Write
- Separate Data Input and Output Pins
- Transparent-Write and Pass-Through
- High Output Drive Capability: 50 pF/Output at Rated Access Time
- Boundary Scan Implementation
- PBGA Package for High Speed Operation

## MCM67Q709A



86 BUMP PBGA  
CASE 896A-02

### PIN NAMES

A0 – A16	.....	Address Input
E	.....	Chip Enable
W	.....	Write Enable
G	.....	Output Enable
D0 – D8	.....	Data Inputs
Q0 – Q8	.....	Data Outputs
K	.....	Clock Input
SCK	.....	Scan Clock Input
SE	.....	Scan Enable
SDI	.....	Scan Data Input
SDO	.....	Scan Data Output
VCC	.....	+ 5 V Power Supply
VSS	.....	Ground
NC	.....	No Connection

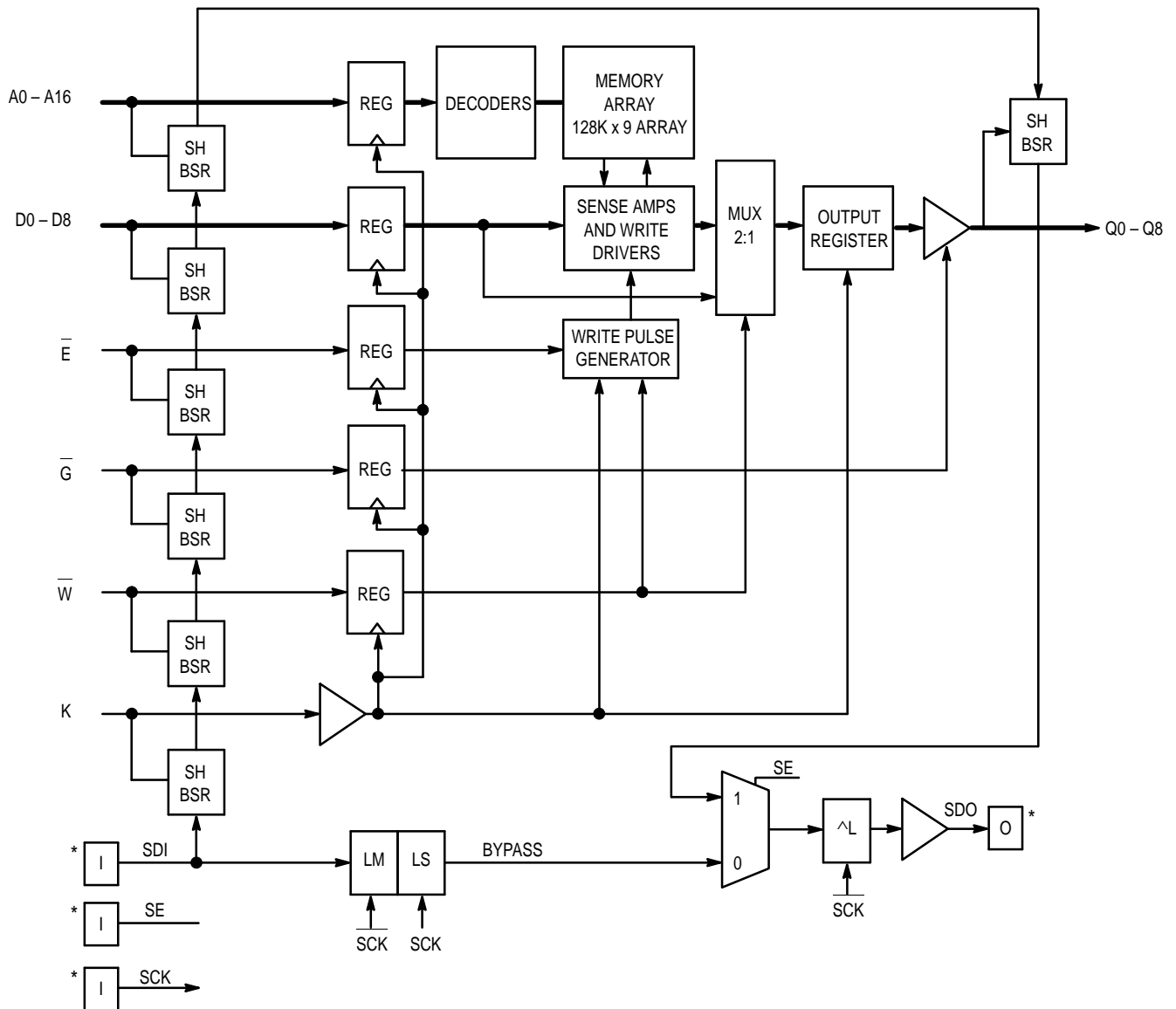
### PIN ASSIGNMENT

	1	2	3	4	5	6	7	8	9
A		Q	Q	○	○	○	○	○	
		E	W	VCC	SDI	SDO	A4	A0	
B	○	○	○	○	○	○	○	○	○
	A16	A14	G	K	VSS	A6	A2	VSS	D8
C	○	○	○	○	○	○	○	○	○
	D7	A15	NC	VSS	VSS	VSS	VSS	Q8	VSS
D	○	○	○	○	○	○	○	○	○
	VSS	Q7	VSS	VSS	VSS	VSS	VSS	Q6	D6
E	○	○	○	○	○	○	○	○	○
	D5	VSS	VSS	VSS	VSS	VSS	VSS	VSS	VCC
F	○	○	○	○	○	○	○	○	○
	VCC	Q5	VSS	VSS	VSS	VSS	VSS	D4	Q4
G	○	○	○	○	○	○	○	○	○
	D3	Q3	VSS	VSS	VSS	VSS	VSS	D2	Q2
H	○	○	○	○	○	○	○	○	○
	VSS	D1	NC	VSS	VSS	VSS	VSS	D0	VSS
J	○	○	○	○	○	○	○	○	○
	Q1	A12	A10	VSS	A9	A8	A5	A1	Q0
K	○	○	○	○	○	○	○	○	○
	A13	A11	SCK	VCC	SE	A7	A3		

TOP VIEW  
86-BUMP

Not to Scale

## BLOCK DIAGRAM



**NOTES:**

1. Bypass mode is entered with SE low and SCK cycled.
2. SH BSR = Shadow Bypass Scan Register.
3. 39 bumps used in Boundary Scan.  $V_{SS}$ ,  $V_{CC}$ , NC, SDI, SDO, SE, and SCK not used in Scan Path.
4. SDO Output Sequence A6, A4, A2, A0, D8, Q8, D6, Q6, D4, Q4, D2, Q2, D0, Q0, A1, A3, A5, A7, A8, A9, A10, A11, A12, A13, Q1, D1, Q3, D3, Q5, D5, Q7, D7, A15, A16, A14, E, G, W, K.

\* Four added test pins.

## TRUTH TABLE

E ( $t_n$ )	W ( $t_n$ )	G ( $t_n + 1$ )	Mode	D0 – D8 ( $t_n$ )	Q0 – Q8 ( $t_n + 1$ )	V <sub>CC</sub> Current
L	L	L	Write and Pass-Through	Valid	D0 – D8 ( $t_n$ )	I <sub>CC</sub>
		H	Write	Valid	High-Z	I <sub>CC</sub>
H	L	L	Pass-Through	Valid	D0 – D8 ( $t_n$ )	I <sub>CC</sub>
		H	Pass-Through	Don't Care	High-Z	I <sub>CC</sub>
X	H	L	Read	Don't Care	Q <sub>out</sub> ( $t_n$ )	I <sub>CC</sub>
		H	Read	Don't Care	High-Z	I <sub>CC</sub>

## ABSOLUTE MAXIMUM RATINGS (See Note)

Rating	Symbol	Value	Unit
Power Supply Voltage	V <sub>CC</sub>	- 0.5 to + 7.0	V
Voltage Relative to V <sub>SS</sub> for Any Pin Except V <sub>CC</sub>	V <sub>in</sub> , V <sub>out</sub>	- 0.5 to V <sub>CC</sub> + 0.5	V
Output Current	I <sub>out</sub>	± 30	mA
Power Dissipation	P <sub>D</sub>	1.5	W
Temperature Under Bias	T <sub>bias</sub>	- 10 to + 85	°C
Operating Temperature	T <sub>A</sub>	0 to + 70	°C
Storage Temperature — Plastic	T <sub>stg</sub>	- 55 to + 125	°C

NOTE: Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to RECOMMENDED OPERATING CONDITIONS. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.

This is a synchronous device. All synchronous inputs must meet specified setup and hold times with stable logic levels for **ALL** rising edges of clock (K) while the device is selected.

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to these high-impedance circuits.

## DC OPERATING CONDITIONS AND CHARACTERISTICS

(V<sub>CC</sub> = 5.0 V ± 5%, T<sub>A</sub> = 0 to + 70°C, Unless Otherwise Noted)

## RECOMMENDED OPERATING CONDITIONS AND SUPPLY CURRENTS

Parameter	Symbol	Min	Max	Unit
Supply Voltage (Operating Voltage Range)	V <sub>CC</sub>	4.75	5.25	V
Input High Voltage	V <sub>IH</sub>	2.2	V <sub>CC</sub> + 0.3**	V
Input Low Voltage	V <sub>IL</sub>	- 0.5*	0.8	V
Input Leakage Current (All Inputs, V <sub>in</sub> = 0 to V <sub>CC</sub> )	I <sub>lkg(I)</sub>	—	± 1.0	μA
Output Leakage Current (E = V <sub>IH</sub> , V <sub>out</sub> = 0 to V <sub>CC</sub> )	I <sub>lkg(O)</sub>	—	± 1.0	μA
AC Supply Current (I <sub>out</sub> = 0 mA) (V <sub>CC</sub> = max, f = f <sub>max</sub> )	I <sub>CCA</sub>	—	230	mA
Output Low Voltage (I <sub>OL</sub> = + 8.0 mA)	V <sub>OL</sub>	—	0.4	V
Output High Voltage (I <sub>OH</sub> = - 4.0 mA)	V <sub>OH</sub>	2.4	3.3	V

\* V<sub>IL</sub> (min) = - 0.5 V dc; V<sub>IL</sub> (min) = - 2.0 V ac (pulse width ≤ 20 ns) for I ≤ 20.0 mA.

\*\* V<sub>IH</sub> (max) = V<sub>CC</sub> + 0.3 V dc; V<sub>IH</sub> (max) = V<sub>CC</sub> + 2.0 V ac (pulse width ≤ 20 ns) for I ≤ 20.0 mA.

## CAPACITANCE (f = 1.0 MHz, dV = 3.0 V, T<sub>A</sub> = 25°C, Periodically Sampled Rather Than 100% Tested)

Parameter	Symbol	Max	Unit
Address and Data Input Capacitance	C <sub>in</sub>	6	pF
Control Pin Input Capacitance	C <sub>in</sub>	6	pF
Output Capacitance	C <sub>out</sub>	8	pF

## AC OPERATING CONDITIONS AND CHARACTERISTICS

( $V_{CC} = 5.0\text{ V} \pm 5\%$ ,  $T_A = 0\text{ to } +70^\circ\text{C}$ , Unless Otherwise Noted)

Input Timing Measurement Reference Level ..... 1.5 V  
 Input Pulse Levels ..... 0 to 3.0 V  
 Input Rise/Fall Time ..... 3 ns

Output Timing Reference Level ..... 1.5 V  
 Output Load ..... Figure 1a Unless Otherwise Noted

### READ/WRITE CYCLE TIMING (See Notes 1, 2, and 3)

Parameter	Symbol	MCM67Q709A-10		Unit	Notes	
		Min	Max			
Cycle Time	$t_{KHKH}$	10	—	ns	1	
Clock Access Time	$t_{KHQV}$	—	5	ns	2	
Clock Low Pulse Width	$t_{KLKH}$	4	—	ns		
Clock High Pulse Width	$t_{KHKL}$	4	—	ns		
Clock High to Data Output Invalid	$t_{KHQX}$	2	—	ns		
Clock High to Data Output High-Z	$t_{KHQZ}$	—	5	ns	3	
Setup Times:	$\begin{matrix} \underline{A} \\ \underline{W} \\ \underline{E} \\ \underline{G} \\ \text{D0 - D8} \end{matrix}$	$\begin{matrix} t_{AVKH} \\ t_{WVKH} \\ t_{EVKH} \\ t_{GVKH} \\ t_{DVKH} \end{matrix}$	2	—	ns	4
Hold Times:	$\begin{matrix} \underline{A} \\ \underline{W} \\ \underline{E} \\ \underline{G} \\ \text{D0 - D8} \end{matrix}$	$\begin{matrix} t_{KHAX} \\ t_{KH WX} \\ t_{KH EX} \\ t_{KH GX} \\ t_{KH DX} \end{matrix}$	1	—	ns	4

**NOTES:**

1. All read and write cycles are referenced from K.
2. Valid data from Clock High will be the data stored at the address or the last valid read cycle.
3. Measured at  $\pm 200\text{ mV}$  from steady state. Tested per High-Z Test Load (See Figure 1b).
4. This is a synchronous device. All synchronous inputs must meet the specified setup and hold times with stable logic levels for **ALL** rising edges of clock (K) while the device is selected.

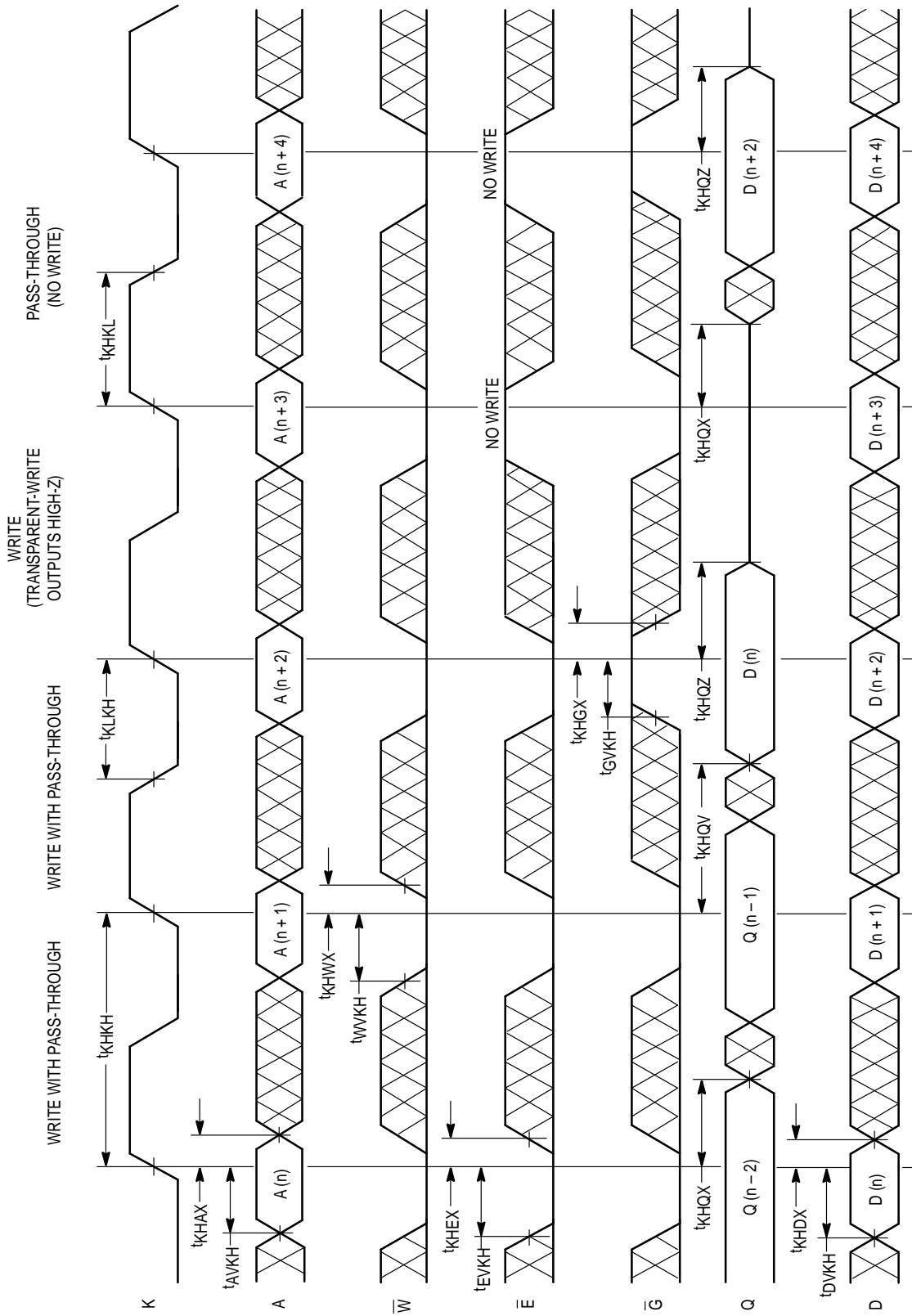


**Figure 1. Test Loads**





### TRANSPARENT-WRITE AND PASS-THROUGH CYCLE TIMING



## BOUNDARY SCAN CYCLE TIMING

Parameter	Symbol	MCM67Q709A–10		Unit	Notes
		Min	Max		
Cycle Time	t <sub>CHCH2</sub>	100	—	ns	
Clock High Pulse Width	t <sub>CHCL2</sub>	40	—	ns	
Clock Low Pulse Width	t <sub>CLCH2</sub>	40	—	ns	
Scan Mode Setup Time	t <sub>SS</sub>	10	—	ns	1
Bypass Mode Setup Time	t <sub>BS</sub>	10	—	ns	2
Scan Mode Recovery Time	t <sub>SR</sub>	100	—	ns	3
SCK Low to SE Hold High	t <sub>CLMH</sub>	10	—	ns	4
SE High to SCK High Setup	t <sub>MHCH</sub>	10	—	ns	5
SCK High to SE Low Hold Time	t <sub>CHML</sub>	10	—	ns	6
SDI Valid to SCK High Setup	t <sub>IVCH</sub>	10	—	ns	
SCK High to SDI Don't Care	t <sub>CHIX</sub>	10	—	ns	
SCK Low to SDO Valid	t <sub>CLOV</sub>	—	20	ns	

### NOTES:

1. The minimum delay required between ending normal operation and beginning scan operations.
2. The minimum delay required between ending Shift Mode and beginning Bypass Mode.
3. The minimum delay required before restarting normal RAM operation.
4. The minimum delay required before executing a Parallel Load operation.
5. The minimum delay required between a Parallel Load operation and a Shift.
6. Minimum Shift command hold time.

## BOUNDARY SCAN

### OVERVIEW

Boundary scan is a simple, non-intrusive scheme that allows verification of electrical continuity for each of a clocked RAMs logically active inputs and I/Os without adversely affecting RAM performance. Boundary scan allows the user to monitor the logic levels applied to each signal I/O on the RAM, and to shift them out in a serial bit stream.

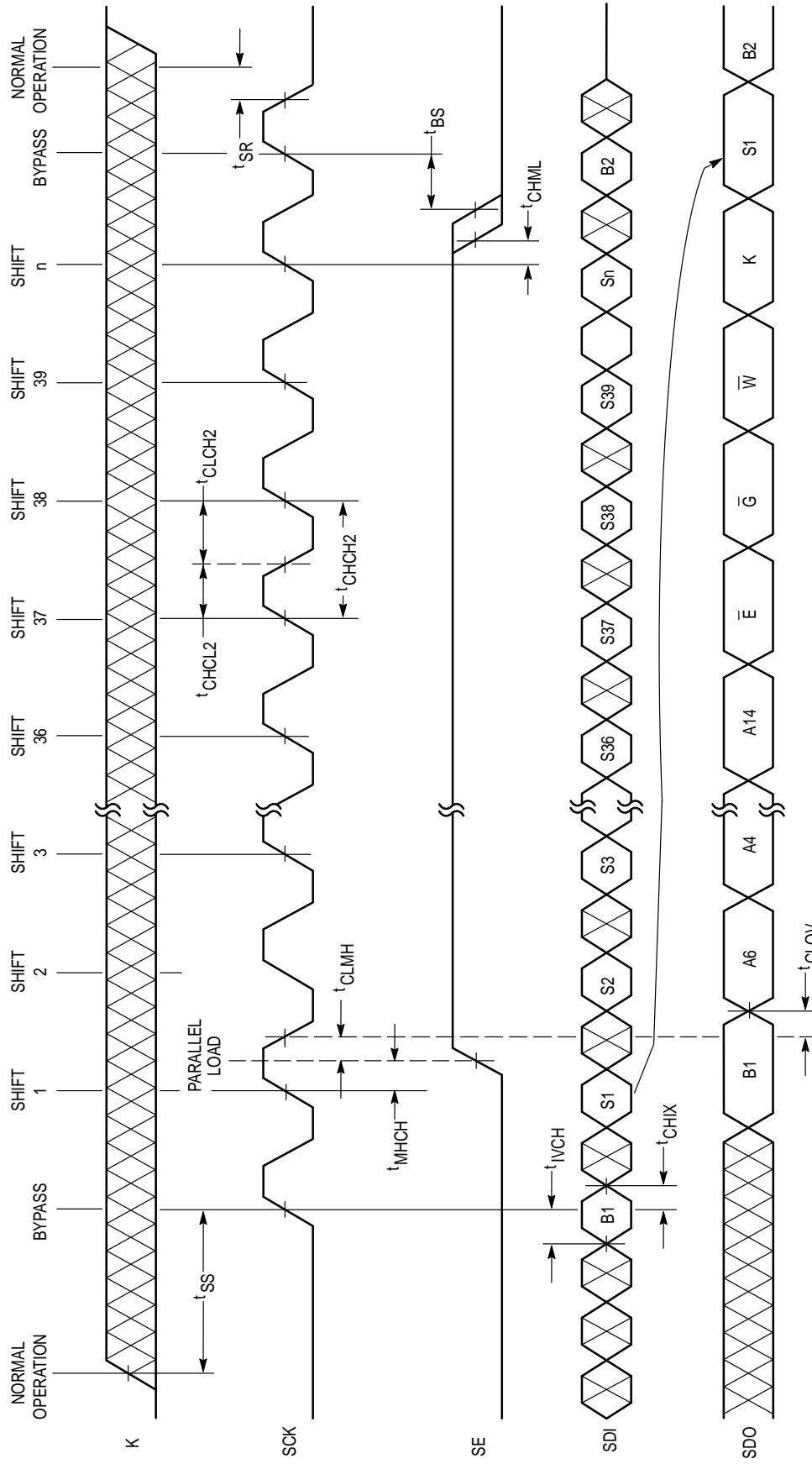
### OPERATION

Boundary scan requires four signal pins for implementation: Scan Data In (SDI), Scan Data Out (SDO), Scan Clock (SCK, active high), and Scan Enable (SE, active high).

Boundary scan provides three modes of operation: (1) normal RAM operation, (2) scan, and (3) bypass. For normal RAM operation, SCK and SE must be held low. The RAM will always return to normal operation immediately after the RAM receives a rising edge of the RAM input clock (K) with SCK and SE held low. To enter scan mode, SCK is activated. The first rising edge of SCK is used to latch in the data on the scan registers. SE is then driven high to disable additional input data from entering the scan registers. Every falling edge of SCK serially shifts data through the scan registers and onto the SDO pin. To enter bypass mode simply exercise SCK with SE held low. In this mode, SDI is sampled on the rising edge of SCK. The level found on SDI is then driven out on SDO on the next falling edge of SCK.



### BOUNDARY SCAN TIMING DIAGRAM

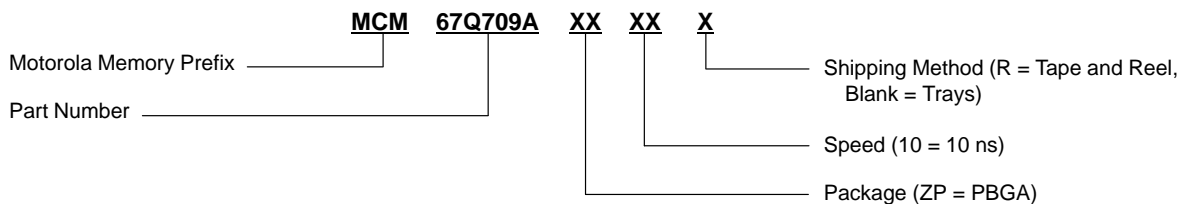


**NOTES:**

- B1 and B2 = Bypass Serial Data from outside source.
- S1 - Sn + 1 = Serial Scan Data from outside source.
- S1 - Sn = RAMs Input Register contents.
- Scan Order is "A6, A4, A2, A0, D8, D6, Q6, Q4, Q2, D0, Q0, A1, A3, A5, A7, A8, A9, A10, A11, A12, A13, Q1, D1, Q3, D3, Q5, D5, Q7, D7, A15, A16, A14, E-bar, G-bar, W-bar, K".

## ORDERING INFORMATION

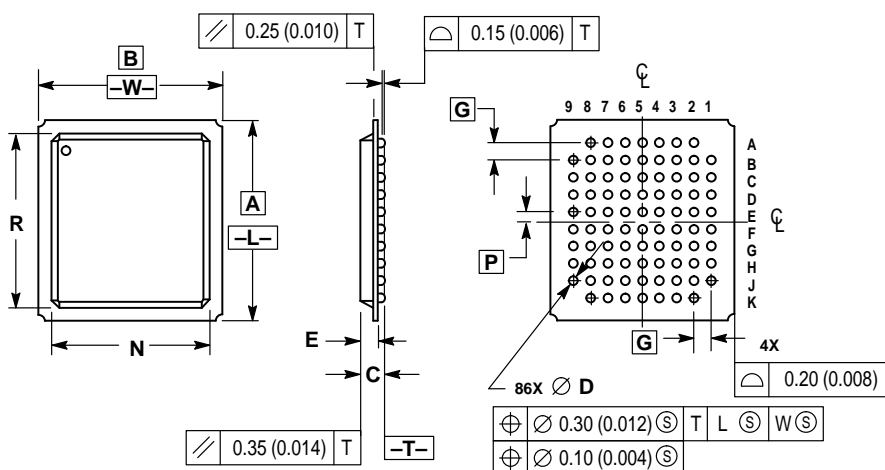
(Order by Full Part Number)



Full Part Numbers — MCM67Q709AZP10  
MCM67Q709AZP10R

## PACKAGE DIMENSIONS

ZP PACKAGE  
86 PBGA  
CASE 896A-02



- NOTES:  
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.  
2. CONTROLLING DIMENSION: MILLIMETER.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	17.78 BSC		0.700 BSC	
B	16.26 BSC		0.640 BSC	
C	1.84	2.44	0.073	0.096
D	0.69	0.81	0.028	0.031
E	1.33	1.73	0.053	0.068
G	1.524 BSC		0.060 BSC	
N	13.80	14.20	0.544	0.559
P	0.762 BSC		0.030 BSC	
R	15.29	15.69	0.602	0.617

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