

Double Data Rate (DDR) SDRAM

MT46V32M4 – 8 Meg x 4 x 4 Banks

MT46V16M8 – 4 Meg x 8 x 4 Banks

MT46V8M16 – 2 Meg x 16 x 4 Banks

Features

- $V_{DD} = +2.5V \pm 0.2V$, $V_{DDQ} = +2.5V \pm 0.2V$
- $V_{DD} = +2.6V \pm 0.1V$, $V_{DDQ} = +2.6V \pm 0.1V$ (DDR400)
- Bidirectional data strobe (DQS) transmitted/received with data, i.e., source-synchronous data capture (x16 has two – one per byte)
- Internal, pipelined double-data-rate (DDR) architecture; two data accesses per clock cycle
- Differential clock inputs (CK and CK#)
- Commands entered on each positive CK edge
- DQS edge-aligned with data for READs; center-aligned with data for WRITEs
- DLL to align DQ and DQS transitions with CK
- Four internal banks for concurrent operation
- Data mask (DM) for masking write data (x16 has two – one per byte)
- Programmable burst lengths: 2, 4, or 8
- Auto refresh and self refresh modes
- Longer lead TSOP for improved reliability (OCPL)
- 2.5V I/O (SSTL_2 compatible)
- Concurrent auto precharge option is supported
- t_{RAS} lockout supported ($t_{RAP} = t_{RCD}$)

Options

- Configuration
 - 32 Meg x 4 (8 Meg x 4 x 4 banks)
 - 16 Meg x 8 (4 Meg x 8 x 4 banks)
 - 8 Meg x 16 (2 Meg x 16 x 4 banks)
- Plastic package – OCPL
 - 66-pin TSOP
 - 66-pin TSOP (Pb-free)
- Timing – cycle time
 - 5ns @ CL = 3 (DDR400)
 - 6ns @ CL = 2.5 (DDR333) (TSOP only)
 - 7.5ns @ CL = 2 (DDR266)¹
 - 7.5ns @ CL = 2 (DDR266A)
 - 7.5ns @ CL = 2.5 (DDR266B)
- Self refresh
 - Standard
 - Low-power self refresh
- Temperature rating
 - Commercial (0°C to 70°C)
 - Industrial (–40°C to +85°C)
- Revision

Marking

32M4
16M8
8M16

TG
P

-5B
-6T

-75E
-75Z
-75

None
L

None
IT

:D

Notes: 1. Not recommended for new designs

Table 1: Key Timing Parameters

CL = CAS (READ) latency; MIN clock rate with 50% duty cycle at CL = 2 (-75E, -75Z), CL = 2.5 (-6, -6T, -75), and CL = 3 (-5B)

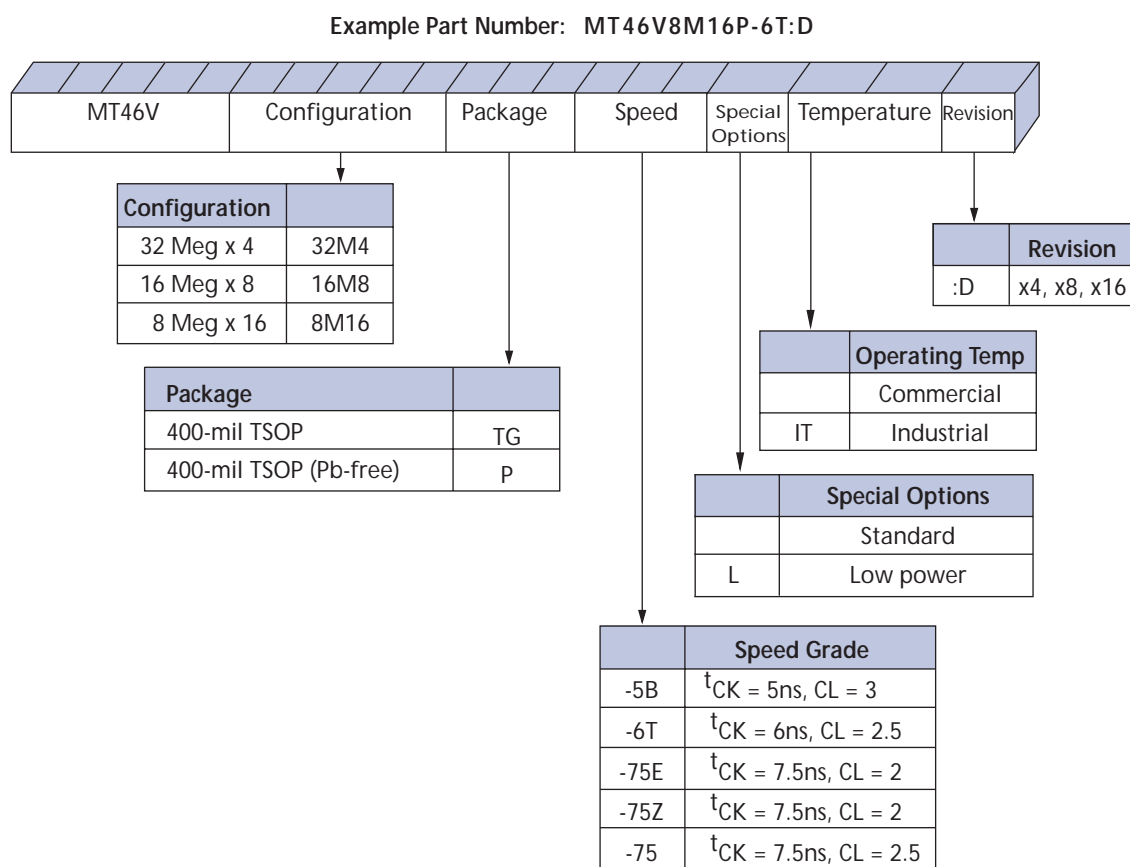
| Speed Grade | Clock Rate (MHz) | | | Data Out Window | Access Window | DQS-DQ Skew |
|-------------|------------------|----------|--------|-----------------|---------------|-------------|
| | CL = 2 | CL = 2.5 | CL = 3 | | | |
| -5B | 133 | 167 | 200 | 1.6ns | ±0.70ns | +0.40ns |
| -6T | 133 | 167 | n/a | 2.0ns | ±0.70ns | +0.45ns |
| -75E/-75Z | 133 | 133 | n/a | 2.5ns | ±0.75ns | +0.50ns |
| -75 | 100 | 133 | n/a | 2.5ns | ±0.75ns | +0.50ns |

Table 2: Addressing

| Parameter | 32 Meg x 4 | 16 Meg x 8 | 8 Meg x 16 |
|----------------|---------------------|---------------------|----------------------|
| Configuration | 8 Meg x 4 x 4 banks | 4 Meg x 8 x 4 banks | 2 Meg x 16 x 4 banks |
| Refresh count | 4K | 4K | 4K |
| Row address | 4K (A0–A11) | 4K (A0–A11) | 4K (A0–A11) |
| Bank address | 4 (BA0, BA1) | 4 (BA0, BA1) | 4 (BA0, BA1) |
| Column address | 2K (A0–A9, A11) | 1K (A0–A9) | 512 (A0–A8) |

Table 3: Speed Grade Compatibility

| Marking | PC3200 (3-3-3) | PC2700 (2.5-3-3) | PC2100 (2-2-2) | PC2100 (2-3-3) | PC2100 (2.5-3-3) | PC1600 (2-2-2) |
|---------|----------------|------------------|----------------|----------------|------------------|----------------|
| -5B | Yes | Yes | Yes | Yes | Yes | Yes |
| -6T | – | Yes | Yes | Yes | Yes | Yes |
| -75E | – | – | Yes | Yes | Yes | Yes |
| -75Z | – | – | – | Yes | Yes | Yes |
| -75 | – | – | – | – | Yes | Yes |
| | -5B | -6T | -75E | -75Z | -75 | -75 |

Figure 1: 128Mb DDR SDRAM Part Numbers


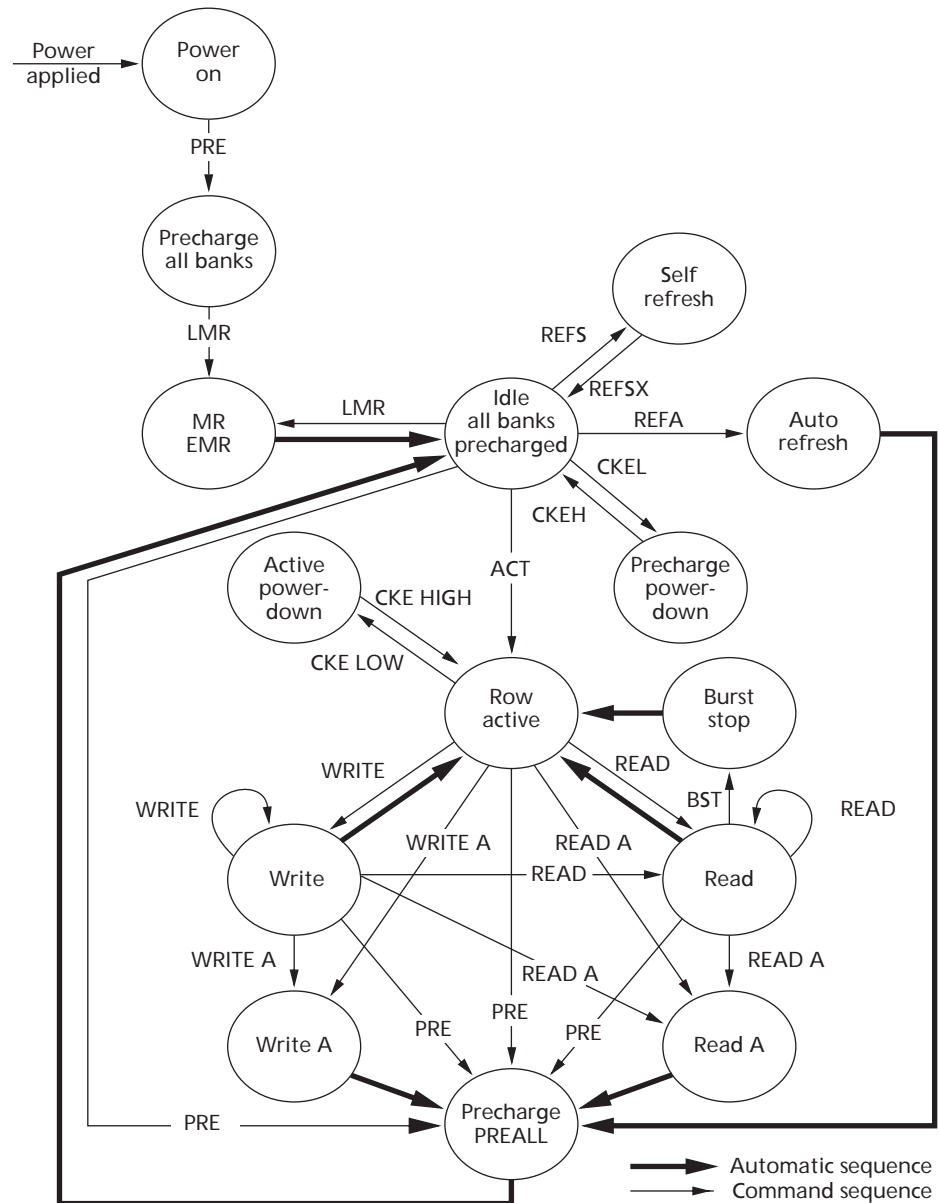
Note: Not all speeds and configurations are available in all packages.

Table of Contents

| | |
|---|----|
| State Diagram | 4 |
| Functional Description | 5 |
| General Notes | 5 |
| Functional Block Diagrams | 6 |
| Pin Assignments and Descriptions | 8 |
| Package Dimensions | 11 |
| Electrical Specifications – IDD | 12 |
| Electrical Specifications – DC and AC | 15 |
| Notes | 26 |
| Commands | 34 |
| DESELECT | 38 |
| NO OPERATION (NOP) | 38 |
| LOAD MODE REGISTER (LMR) | 38 |
| ACTIVE (ACT) | 39 |
| READ | 39 |
| WRITE | 40 |
| PRECHARGE (PRE) | 41 |
| BURST TERMINATE (BST) | 41 |
| AUTO REFRESH (AR) | 41 |
| SELF REFRESH | 41 |
| Operations | 42 |
| INITIALIZATION | 42 |
| REGISTER DEFINITION | 45 |
| ACTIVE | 49 |
| READ | 50 |
| WRITE | 62 |
| PRECHARGE | 75 |
| AUTO REFRESH | 77 |
| SELF REFRESH | 78 |
| POWER-DOWN (CKE Not Active) | 80 |

State Diagram

Figure 2: Simplified State Diagram



ACT = ACTIVE
 BST = BURST TERMINATE
 CKEH = Exit power down
 CKEL = Enter power down
 EMR = Extended mode register
 LMR = LOAD MODE REGISTER
 MR = Mode register

PRE = PRECHARGE
 PREALL = PRECHARGE all banks
 READ A = READ with auto precharge
 REFA = AUTO REFRESH
 REFS = Enter self refresh
 REFSX = Exit self refresh
 WRITE A = WRITE with auto precharge

Note: This diagram represents operations within a single bank only and does not capture concurrent operations in other banks.

Functional Description

The DDR SDRAM uses a double data rate architecture to achieve high-speed operation. The double data rate architecture is essentially a $2n$ -prefetch architecture with an interface designed to transfer two data words per clock cycle at the I/O pins. A single read or write access for the DDR SDRAM effectively consists of a single $2n$ -bit wide, one-clock-cycle data transfer at the internal DRAM core and two corresponding n -bit wide, one-half-clock-cycle data transfers at the I/O pins.

A bidirectional data strobe (DQS) is transmitted externally, along with data, for use in data capture at the receiver. DQS is a strobe transmitted by the DDR SDRAM during READs and by the memory controller during WRITEs. DQS is edge-aligned with data for READs and center-aligned with data for WRITEs. The x16 offering has two data strobes, one for the lower byte and one for the upper byte.

The DDR SDRAM operates from a differential clock (CK and CK#); the crossing of CK going HIGH and CK# going LOW will be referred to as the positive edge of CK. Commands (address and control signals) are registered at every positive edge of CK. Input data is registered on both edges of DQS, and output data is referenced to both edges of DQS, as well as to both edges of CK.

Read and write accesses to the DDR SDRAM are burst oriented; accesses start at a selected location and continue for a programmed number of locations in a programmed sequence. Accesses begin with the registration of an ACTIVE command, which may then be followed by a READ or WRITE command. The address bits registered coincident with the ACTIVE command are used to select the bank and row to be accessed. The address bits registered coincident with the READ or WRITE command are used to select the bank and the starting column location for the burst access.

The DDR SDRAM provides for programmable READ or WRITE burst lengths of 2, 4, or 8 locations. An AUTO PRECHARGE function may be enabled to provide a self-timed row precharge that is initiated at the end of the burst access.

As with standard SDR SDRAMs, the pipelined, multibank architecture of DDR SDRAMs allows for concurrent operation, thereby providing high effective bandwidth by hiding row precharge and activation time.

An auto refresh mode is provided, along with a power-saving power-down mode. All inputs are compatible with the JEDEC standard for SSTL_2. All full-drive option outputs are SSTL_2, Class II compatible.

General Notes

- The functionality and the timing specifications discussed in this data sheet are for the DLL-enabled mode of operation.
- Throughout the data sheet, the various figures and text refer to DQs as "DQ." The DQ term is to be interpreted as any and all DQ collectively, unless specifically stated otherwise. Additionally, the x16 is divided into two bytes, the lower byte and upper byte. For the lower byte (DQ0–DQ7) DM refers to LDM and DQS refers to LDQS. For the upper byte (DQ8–DQ15) DM refers to UDM and DQS refers to UDQS.
- Complete functionality is described throughout the document and any page or diagram may have been simplified to convey a topic and may not be inclusive of all requirements.
- Any specific requirement takes precedence over a general statement.

The 128Mb DDR SDRAM is a high-speed CMOS, dynamic random-access memory containing 134,217,728 bits. It is internally configured as a 4-bank DRAM.

The block diagram illustrates the memory architecture, showing the flow of data and control signals between various components. The architecture is divided into two main sections: the memory array and the I/O interface.

Memory Array Section:

- Control Logic:** Receives external control signals (CKE#, CK#, CK, CS#, WE#, CAS#, RAS#) and manages the internal state via **MODE REGISTERS**.
- Addressing:** An **ADDRESS REGISTER** (14 bits) receives address inputs (A0-A11, BA0, BA1). It provides a 12-bit **REFRESH COUNTER** signal to the **ROW-ADDRESS MUX** and a 11-bit **COLUMN-ADDRESS COUNTER/LATCH** signal to the **COLUMN DECODER**.
- Row Addressing:** The **ROW-ADDRESS MUX** (12 bits) selects the row address for the **BANK0 ROW-ADDRESS LATCH & DECODER** (12 bits). This decoder drives the **BANK0 MEMORY ARRAY** (4,096 x 1,024 x 8) and the **I/O GATING DM MASK LOGIC** (8 bits).
- Column Addressing:** The **COLUMN-ADDRESS COUNTER/LATCH** (11 bits) provides a 10-bit signal to the **COLUMN DECODER** (10 bits), which drives the **I/O GATING DM MASK LOGIC** (8 bits).
- Memory Array:** The **BANK0 MEMORY ARRAY** (4,096 x 1,024 x 8) is divided into **BANK1**, **BANK2**, and **BANK3**. It includes **SENSE AMPLIFIERS** and is connected to the **I/O GATING DM MASK LOGIC** (8 bits).

I/O Interface Section:

- Read Path:** Data from the memory array is sent to a **READ LATCH** (8 bits), which then passes through a **MUX** (4 bits) to the **DATA** output (4 bits). The **MUX** also receives a **COL0** signal (4 bits) from the **INPUT REGISTERS**.
- Write Path:** Data from the **DATA** input (4 bits) is sent to the **WRITE FIFO & DRIVERS** (8 bits), which then passes through a **MASK** (2 bits) to the **INPUT REGISTERS** (1 bit).
- Input Registers:** These registers (1 bit) receive data from the **DATA** input (4 bits) and the **WRITE FIFO & DRIVERS** (8 bits). They provide a **COL0** signal (4 bits) to the **MUX** and a **DATA** signal (4 bits) to the **WRITE FIFO & DRIVERS**.
- Output Drivers:** The **DATA** signal (4 bits) is sent to the **DRIVERS** (4 bits), which drive the **DATA** output (4 bits). The **DRIVERS** also receive a **CK** signal (1 bit) from the **DLL** and a **DM** signal (1 bit) from the **RCVRS**.
- RCVRS:** The **RCVRS** (1 bit) receive data from the **DATA** input (4 bits) and the **WRITE FIFO & DRIVERS** (8 bits). They provide a **DM** signal (1 bit) to the **DRIVERS**.
- DLL:** The **DLL** (1 bit) receives a **CK** signal (1 bit) and provides a **CK** signal (1 bit) to the **DRIVERS**.

Figure 4: 16 Meg x 8 Functional Block Diagram

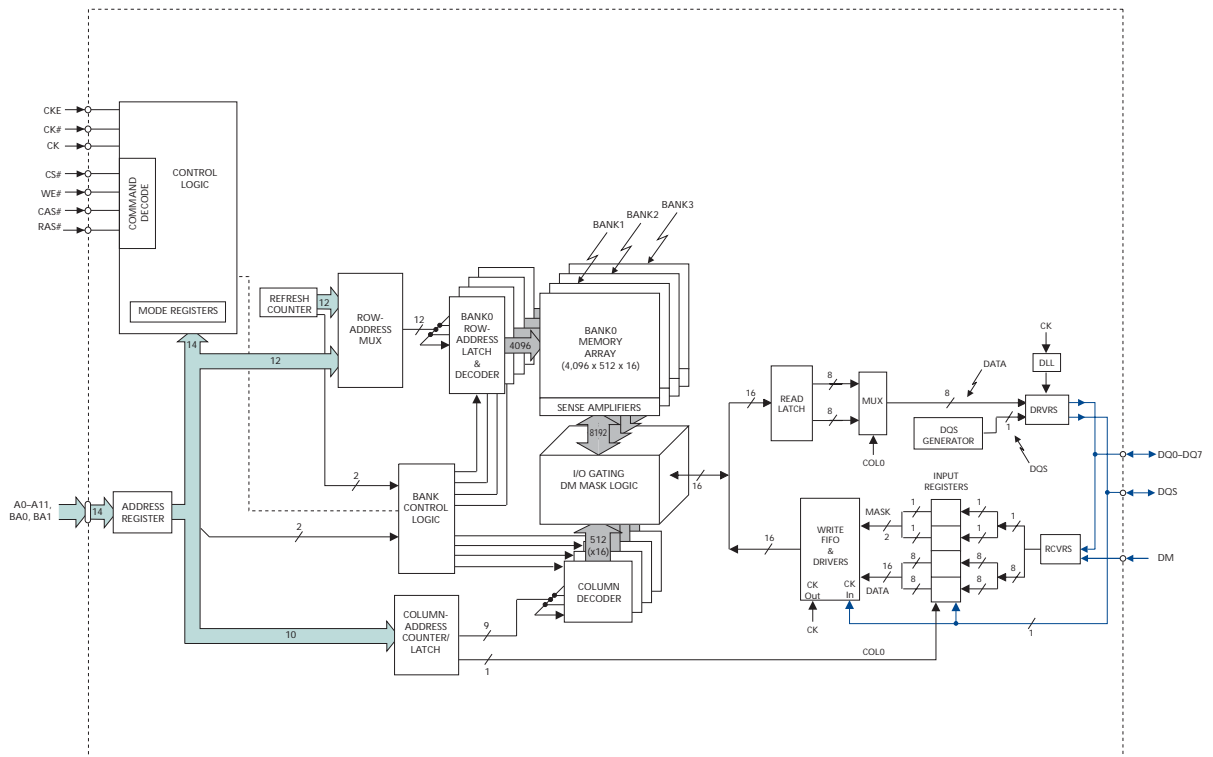


Figure 5: 8 Meg x 16 Functional Block Diagram

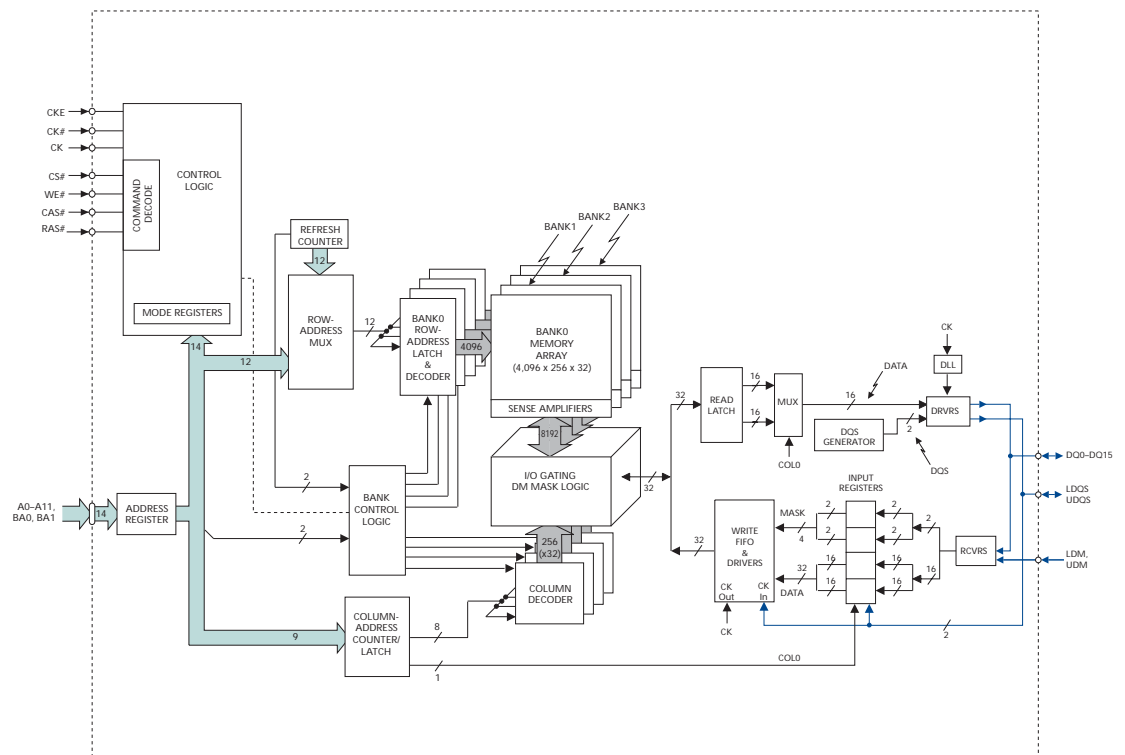


Figure 6: 66-Pin TSOP Pin Assignment (Top View)

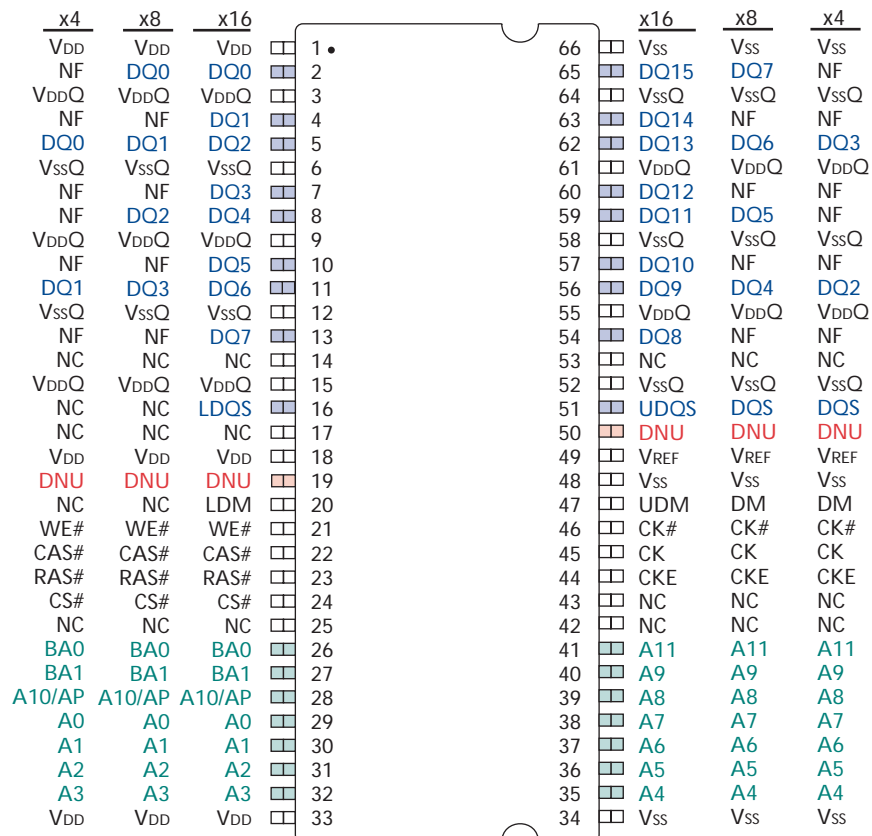


Table 4: Pin Descriptions

| TSOP Numbers | Symbol | Type | Description |
|--|---|--------|--|
| 29, 30, 31 32, 35, 36, 37, 38, 39, 40, 28, 41 | A0, A1, A2, A3, A4, A5, A6, A7, A8, A9, A10, A11 | Input | Address inputs: Provide the row address for ACTIVE commands, and the column address and auto precharge bit (A10) for READ/WRITE commands, to select one location out of the memory array in the respective bank. A10 sampled during a PRECHARGE command determines whether the PRECHARGE applies to one bank (A10 LOW, bank selected by BA0, BA1) or all banks (A10 HIGH). The address inputs also provide the op-code during a LOAD MODE REGISTER command. |
| 26, 27 | BA0, BA1 | Input | Bank address inputs: BA0 and BA1 define to which bank an ACTIVE, READ, WRITE, or PRECHARGE command is being applied. BA0 and BA1 also define which mode register (mode register or extended mode register) is loaded during the LOAD MODE REGISTER command. |
| 45, 46 | CK, CK# | Input | Clock: CK and CK# are differential clock inputs. All address and control input signals are sampled on the crossing of the positive edge of CK and negative edge of CK#. Output data (DQ and DQS) is referenced to the crossings of CK and CK#. |
| 44 | CKE | Input | Clock enable: CKE HIGH activates and CKE LOW deactivates the internal clock, input buffers, and output drivers. Taking CKE LOW provides PRECHARGE POWER-DOWN and SELF REFRESH operations (all banks idle), or ACTIVE POWER-DOWN (row ACTIVE in any bank). CKE is synchronous for POWER-DOWN entry and exit, and for SELF REFRESH entry. CKE is asynchronous for SELF REFRESH exit and for disabling the outputs. CKE must be maintained HIGH throughout read and write accesses. Input buffers (excluding CK, CK#, and CKE) are disabled during POWER-DOWN. Input buffers (excluding CKE) are disabled during SELF REFRESH. CKE is an SSTL_2 input but will detect an LVCMOS LOW level after VDD is applied and until CKE is first brought HIGH, after which it becomes an SSTL_2 input only. |
| 24 | CS# | Input | Chip select: CS# enables (registered LOW) and disables (registered HIGH) the command decoder. All commands are masked when CS# is registered HIGH. CS# provides for external bank selection on systems with multiple banks. CS# is considered part of the command code. |
| 47 20 47 | DM LDM UDM | Input | Input data mask: DM is an input mask signal for write data. Input data is masked when DM is sampled HIGH along with that input data during a write access. DM is sampled on both edges of DQS. Although DM pins are input-only, the DM loading is designed to match that of DQ and DQS pins. For the x16, LDM is DM for DQ0–DQ7 and UDM is DM for DQ8–DQ15. Pin 20 is a NC on x4 and x8. |
| 23, 22, 21 | RAS#, CAS#, WE# | Input | Command inputs: RAS#, CAS#, and WE# (along with CS#) define the command being entered. |
| 2, 4, 5, 7, 8, 10, 11, 13, 54, 56, 57, 59, 60, 62, 63, 65 | DQ0–DQ3 DQ4–DQ7 DQ8–DQ11 DQ12–DQ15 | I/O | Data input/output: Data bus for x16. |
| 2, 5, 8, 11, 56, 59, 62, 65 | DQ0–DQ3 DQ4–DQ7 | I/O | Data input/output: Data bus for x8. |
| 5, 11, 56, 62 | DQ0–DQ3 | I/O | Data input/output: Data bus for x4. |
| 51 16 51 | DQS LDQS UDQS | I/O | Data strobe: Output with read data, input with write data. DQS is edge-aligned with read data, centered in write data. It is used to capture data. For the x16, LDQS is DQS for DQ0–DQ7 and UDQS is DQS for DQ8–DQ15. Pin 16 is NC on x4 and x8. |
| 1, 18, 33 | VDD | Supply | Power supply. |
| 3, 9, 15, 55, 61 | VDDQ | Supply | DQ power supply: Isolated on the die for improved noise immunity. |

Table 4: Pin Descriptions (continued)

| TSOP Numbers | Symbol | Type | Description |
|--|--------|--------|--|
| 34, 48, 66 | Vss | Supply | Ground. |
| 6, 12, 52, 58, 64 | VssQ | Supply | DQ ground: Isolated on the die for improved noise immunity. |
| 49 | VREF | Supply | SSTL_2 reference voltage. |
| 14, 17, 25, 42, 43, 53 | NC | – | No connect for x16: These pins should be left unconnected. |
| 14, 16, 17, 20, 25, 42, 43, 53 | NC | – | No connect for x8: These pins should be left unconnected. |
| 14, 16, 17, 20, 25, 42, 43, 53 | NC | – | No connect for x4: These pins should be left unconnected. |
| 4, 7, 10, 13, 54, 57, 60, 63 | NF | – | No function for x8: These pins should be left unconnected. |
| 2, 4, 7, 8, 10, 13, 54, 57, 59, 60, 63, 65 | NF | – | No function for x4: These pins should be left unconnected. |
| 19, 50 | DNU | – | Do not use: Must float to minimize noise on VREF. |

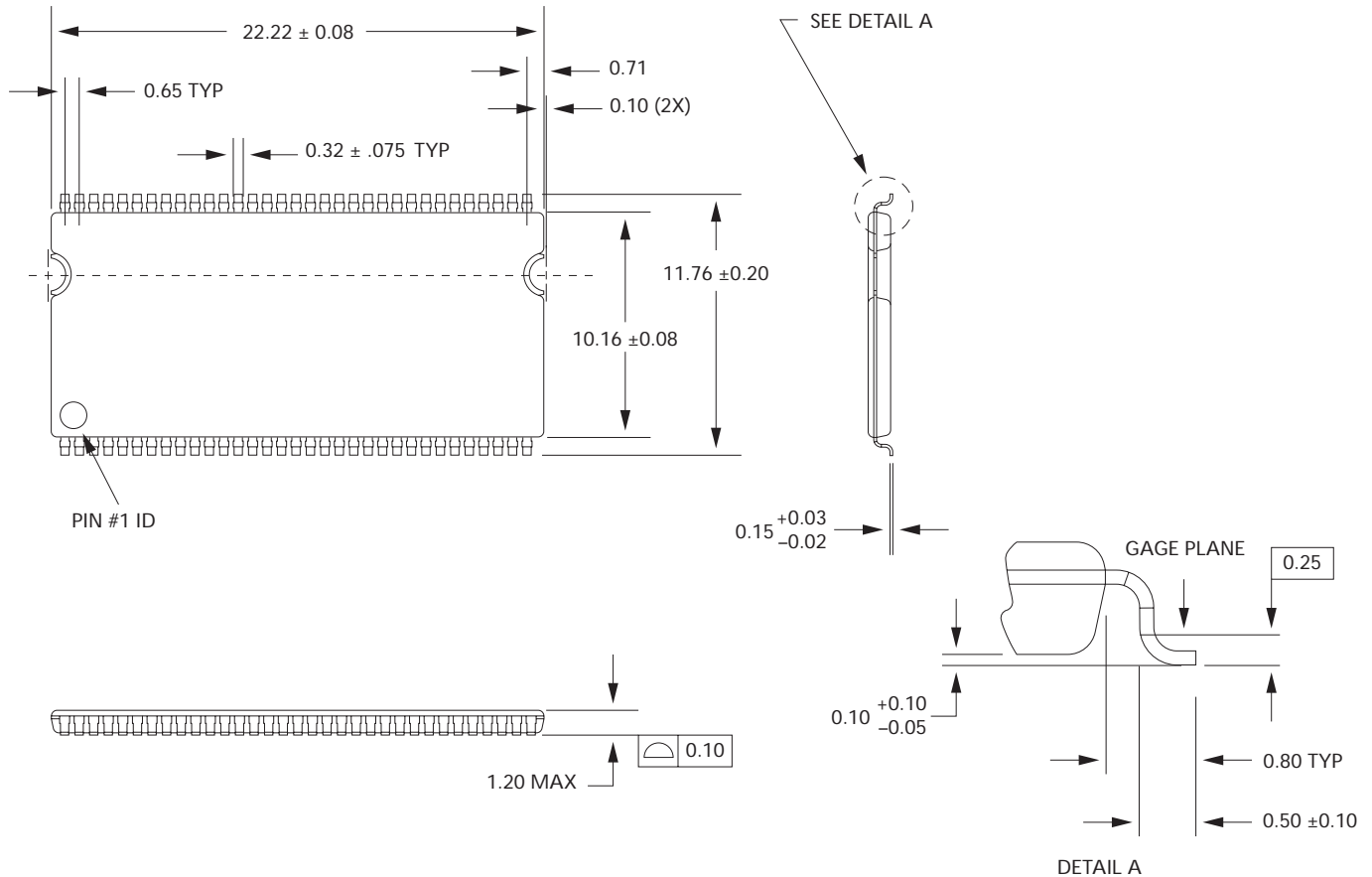
Table 5: Reserved NC Pin Descriptions

NC pins not listed may also be reserved for other uses; this table defines NC pins of importance

| TSOP Numbers | Symbol | Type | Description |
|--------------|----------|-------|---|
| 42, 17 | A12, A13 | Input | Address inputs A12 and A13 for 256Mb, 512Mb, and 1Gb devices. |

Package Dimensions

Figure 7: 66-Pin Plastic TSOP (400 mil)



- Notes:
1. All dimensions are in millimeters.
 2. Package width and length do not include mold protrusion; allowable mold protrusion is 0.25mm per side.

Electrical Specifications – IDD

Table 6: IDD Specifications and Conditions (x4, x8; -5B, -6T, -75E, -75Z, -75)

VDDQ = +2.6V ±0.1V, VDD = +2.6V ±0.1V (-5B); VDDQ = +2.5V ±0.2V, VDD = +2.5V ±0.2V (-6T, -75E, -75Z, -75);
0°C ≤ T_A ≤ +70°C; Notes: 1–5, 11, 13, 15, 47; Notes appear on pages 26–31; See also Table 8 on page 14

| Parameter/Condition | | Symbol | -5B | -6T | -75E | -75Z/-75 | Units | Notes |
|--|---|--------|-----|-----|------|----------|-------|--------|
| Operating one-bank active-precharge current: t _{RC} = t _{RC} (MIN); t _{CK} = t _{CK} (MIN); DQ, DM, and DQS inputs changing once per clock cycle; Address and control inputs changing once every two clock cycles | | IDD0 | 115 | 125 | 110 | 105 | mA | 23, 48 |
| Operating one-bank active-read-precharge current: Burst = 2; t _{RC} = t _{RC} (MIN); t _{CK} = t _{CK} (MIN); I _{OUT} = 0mA; Address and control inputs changing once per clock cycle | | IDD1 | 135 | 135 | 120 | 120 | mA | 23, 48 |
| Precharge power-down standby current: All banks idle; Power-down mode; t _{CK} = t _{CK} (MIN); CKE = (LOW) | | IDD2P | 3 | 3 | 3 | 3 | mA | 24, 33 |
| Idle standby current: CS# = HIGH; All banks are idle; t _{CK} = t _{CK} (MIN); CKE = HIGH; Address and other control inputs changing once per clock cycle. V _{IN} = V _{REF} for DQ, DQS, and DM | | IDD2F | 50 | 45 | 45 | 40 | mA | 51 |
| Active power-down standby current: One bank active; Power-down mode; t _{CK} = t _{CK} (MIN); CKE = LOW | | IDD3P | 30 | 25 | 25 | 25 | mA | 24, 33 |
| Active standby current: CS# = HIGH; CKE = HIGH; One bank active; t _{RC} = t _{RAS} (MAX); t _{CK} = t _{CK} (MIN); DQ, DM, and DQS inputs changing twice per clock cycle; Address and other control inputs changing once per clock cycle | | IDD3N | 50 | 50 | 50 | 45 | mA | 23 |
| Operating burst read current: Burst = 2; Continuous burst reads; One bank active; Address and control inputs changing once per clock cycle; t _{CK} = t _{CK} (MIN); I _{OUT} = 0mA | | IDD4R | 165 | 145 | 130 | 130 | mA | 23, 48 |
| Operating burst write current: Burst = 2; Continuous burst writes; One bank active; Address and control inputs changing once per clock cycle; t _{CK} = t _{CK} (MIN); DQ, DM, and DQS inputs changing twice per clock cycle | | IDD4W | 165 | 145 | 130 | 130 | mA | 23 |
| Auto refresh burst current: | t _{RFC} = t _{RFC} (MIN) | IDD5 | 240 | 265 | 220 | 220 | mA | 50 |
| | t _{RFC} = 15.6μs | IDD5A | 6 | 5 | 5 | 5 | mA | 28, 50 |
| Self refresh current: CKE ≤ 0.2V | Standard | IDD6 | 4 | 4 | 4 | 4 | mA | 12 |
| | Low power (L) | IDD6A | 1.3 | 1.3 | 1.3 | 1.3 | mA | 12 |
| Operating bank interleave read current: Four bank interleaving READs (Burst = 4) with auto precharge; t _{RC} = minimum t _{RC} allowed; t _{CK} = t _{CK} (MIN); Address and control inputs change only during ACTIVE, READ, or WRITE commands | | IDD7 | 355 | 355 | 330 | 325 | mA | 23, 49 |

Table 7: IDD Specifications and Conditions (x16; -5B, -6T, -75E -75Z -75)

VDDQ = +2.6V ±0.1V, VDD = +2.6V ±0.1V (-5B); VDDQ = +2.5V ±0.2V, VDD = +2.5V ±0.2V (-6T, -75E, -75Z, -75);
0°C ≤ T_A ≤ +70°C; Notes: 1–5, 11, 13, 15, 47; Notes appear on pages 26–31; See also Table 8 on page 14

| Parameter/Condition | Symbol | -5B | -6T | -75E | -75Z/-75 | Units | Notes | |
|--|---|-------|-----|------|----------|-------|--------|--------|
| Operating one-bank active-precharge current: t _{RC} = t _{RC} (MIN); t _{CK} = t _{CK} (MIN); DQ, DM, and DQS inputs changing once per clock cycle; Address and control inputs changing once every two clock cycles | IDD0 | 125 | 125 | 115 | 110 | mA | 23, 48 | |
| Operating one-bank active-read-precharge current: Burst = 2; t _{RC} = t _{RC} (MIN); t _{CK} = t _{CK} (MIN); I _{OUT} = 0mA; Address and control inputs changing once per clock cycle | IDD1 | 135 | 135 | 135 | 125 | mA | 23, 48 | |
| Precharge power-down standby current: All banks idle; Power-down mode; t _{CK} = t _{CK} (MIN); CKE = (LOW) | IDD2P | 3 | 3 | 3 | 3 | mA | 24, 33 | |
| Idle standby current: CS# = HIGH; All banks are idle; t _{CK} = t _{CK} (MIN); CKE = HIGH; Address and other control inputs changing once per clock cycle. V _{IN} = V _{REF} for DQ, DQS, and DM | IDD2F | 50 | 45 | 45 | 40 | mA | 51 | |
| Active power-down standby current: One bank active; Power-down mode; t _{CK} = t _{CK} (MIN); CKE = LOW | IDD3P | 30 | 25 | 25 | 25 | mA | 24, 33 | |
| Active standby current: CS# = HIGH; CKE = HIGH; One bank active; t _{RC} = t _{RAS} (MAX); t _{CK} = t _{CK} (MIN); DQ, DM, and DQS inputs changing twice per clock cycle; Address and other control inputs changing once per clock cycle | IDD3N | 50 | 50 | 50 | 45 | mA | 23 | |
| Operating burst read current: Burst = 2; Continuous burst reads; One bank active; Address and control inputs changing once per clock cycle; t _{CK} = t _{CK} (MIN); I _{OUT} = 0mA | IDD4R | 185 | 165 | 140 | 140 | mA | 23, 48 | |
| Operating burst write current: Burst = 2; Continuous burst writes; One bank active; Address and control inputs changing once per clock cycle; t _{CK} = t _{CK} (MIN); DQ, DM, and DQS inputs changing twice per clock cycle | IDD4W | 185 | 165 | 140 | 140 | mA | 23 | |
| Auto refresh burst current: | t _{RFC} = t _{RFC} (MIN) | IDD5 | 265 | 265 | 250 | 250 | mA | 50 |
| | t _{RFC} = 15.6μs | IDD5A | 10 | 5 | 5 | 5 | mA | 28, 50 |
| Self refresh current: CKE ≤ 0.2V | Standard | IDD6 | 4 | 4 | 4 | mA | 12 | |
| | Low power (L) | IDD6A | 1.3 | 1.3 | 1.3 | mA | 12 | |
| Operating bank interleave read current: Four bank interleaving READs (Burst = 4) with auto precharge; t _{RC} = minimum t _{RC} allowed; t _{CK} = t _{CK} (MIN); Address and control inputs change only during ACTIVE, READ, or WRITE commands | IDD7 | 385 | 385 | 375 | 375 | mA | 23, 49 | |

Table 8: IDD Test Cycle Times
Values reflect number of clock cycles for each test

| IDD Test | Speed Grade | Clock Cycle Time | t _{RRD} | t _{RCD} | t _{RAS} | t _{RP} | t _{RC} | t _{RFC} | t _{REFI} | CL |
|----------|-------------|------------------|------------------|------------------|------------------|-----------------|-----------------|------------------|-------------------|-----|
| IDD0 | –75/75Z | 7.5ns | n/a | n/a | 6 | 3 | 9 | n/a | n/a | n/a |
| | –75E | 7.5ns | n/a | n/a | 6 | 2 | 8 | n/a | n/a | n/a |
| | –6T | 6ns | n/a | n/a | 7 | 3 | 10 | n/a | n/a | n/a |
| | –5B | 5ns | n/a | n/a | 8 | 3 | 11 | n/a | n/a | n/a |
| IDD1 | –75 | 7.5ns | n/a | n/a | 6 | 3 | 9 | n/a | n/a | 2.5 |
| | –75Z | 7.5ns | n/a | n/a | 6 | 3 | 9 | n/a | n/a | 2 |
| | –75E | 7.5ns | n/a | n/a | 6 | 2 | 8 | n/a | n/a | 2 |
| | –6T | 6ns | n/a | n/a | 7 | 3 | 10 | n/a | n/a | 2.5 |
| | –5B | 5ns | n/a | n/a | n/a | n/a | n/a | n/a | n/a | 3 |
| IDD4R | –75 | 7.5ns | n/a | n/a | n/a | n/a | n/a | n/a | n/a | 2.5 |
| | –75Z | 7.5ns | n/a | n/a | n/a | n/a | n/a | n/a | n/a | 2 |
| | –75E | 7.5ns | n/a | n/a | n/a | n/a | n/a | n/a | n/a | 2 |
| | –6T | 6ns | n/a | n/a | n/a | n/a | n/a | n/a | n/a | 2.5 |
| | –5B | 5ns | n/a | n/a | n/a | n/a | n/a | n/a | n/a | 3 |
| IDD4W | –75 | 7.5ns | n/a | n/a | n/a | n/a | n/a | n/a | n/a | n/a |
| | –75Z | 7.5ns | n/a | n/a | n/a | n/a | n/a | n/a | n/a | n/a |
| | –75E | 7.5ns | n/a | n/a | n/a | n/a | n/a | n/a | n/a | n/a |
| | –6T | 6ns | n/a | n/a | n/a | n/a | n/a | n/a | n/a | n/a |
| | –5B | 5ns | n/a | n/a | n/a | n/a | n/a | n/a | n/a | n/a |
| IDD5 | –75/75Z | 7.5ns | n/a | n/a | n/a | n/a | n/a | 10 | 10 | n/a |
| | –75E | 7.5ns | n/a | n/a | n/a | n/a | n/a | 9 | 9 | n/a |
| | –6T | 6ns | n/a | n/a | n/a | n/a | n/a | 12 | 12 | n/a |
| | –5B | 5ns | n/a | n/a | n/a | n/a | n/a | 14 | 14 | n/a |
| IDD5A | –75/75Z | 7.5ns | n/a | n/a | n/a | n/a | n/a | 10 | 1,030 | n/a |
| | –75E | 7.5ns | n/a | n/a | n/a | n/a | n/a | 9 | 1,031 | n/a |
| | –6T | 6ns | n/a | n/a | n/a | n/a | n/a | 12 | 1,288 | n/a |
| | –5B | 5ns | n/a | n/a | n/a | n/a | n/a | 14 | 1,564 | n/a |
| IDD7 | –75 | 7.5ns | 2 | 3 | n/a | 3 | 10 | n/a | n/a | 2.5 |
| | –75Z | 7.5ns | 2 | 3 | n/a | 3 | 10 | n/a | n/a | 2 |
| | –75E | 7.5ns | 2 | 3 | n/a | 2 | 8 | n/a | n/a | 2 |
| | –6T | 6ns | 2 | 3 | n/a | 3 | 10 | n/a | n/a | 2.5 |
| | –5B | 5ns | 2 | 3 | n/a | 3 | 11 | n/a | n/a | 3 |

Electrical Specifications – DC and AC

Stresses greater than those listed in Table 9 may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

Table 9: Absolute Maximum Ratings

| Parameter | Absolute Maximum Value |
|---|------------------------|
| VDD supply voltage relative to VSS | –1V to +3.6V |
| VDDQ supply voltage relative to VSS | –1V to +3.6V |
| VREF and inputs voltage relative to VSS | –1V to +3.6V |
| I/O pins voltage relative to VSS | –0.5V to VDDQ +0.5V |
| Storage temperature (plastic) | –55°C to +150°C |
| Short circuit output current | 50mA |

Table 10: DC Electrical Characteristics and Operating Conditions (-5B)

Notes: 1–5 and 17 apply to entire table; Notes appear on pages 26–32;

VDDQ = +2.6V ±0.1V, VDD = +2.6V ±0.1V

| Parameter/Condition | | Symbol | Min | Max | Units | Notes |
|--|--|---------|-----------------------|-----------------------|-------|------------|
| Supply voltage | | VDD | +2.5 | +2.7 | V | 37, 42 |
| I/O supply voltage | | VDDQ | +2.5 | +2.7 | V | 37, 42, 45 |
| I/O reference voltage | | VREF | $0.49 \times V_{DDQ}$ | $0.51 \times V_{DDQ}$ | V | 7, 45 |
| I/O termination voltage (system) | | VTT | VREF - 0.04 | VREF + 0.04 | V | 8, 45 |
| Input high (logic 1) voltage | | VIH(DC) | VREF + 0.15 | VDD + 0.3 | V | 29 |
| Input low (logic 0) voltage | | VIL(DC) | −0.3 | VREF - 0.15 | V | 29 |
| Input leakage current: Any input $0V \leq V_{IN} \leq V_{DD}$, VREF pin $0V \leq V_{IN} \leq 1.35V$ (All other pins not under test = 0V) | | II | −2 | +2 | μA | |
| Output leakage current: (DQs are disabled; $0V \leq V_{OUT} \leq V_{DDQ}$) | | IOZ | −5 | +5 | μA | |
| Full-drive option output levels: (x4, x8, x16) | High current (VOUT = VDDQ - 0.373V, minimum VREF, minimum VTT) | IOH | −16.8 | − | mA | 38, 40 |
| | Low current (VOUT = 0.373V, maximum VREF, maximum VTT) | IOL | +16.8 | − | mA | |
| Reduced-drive option output levels: (x16 only) | High current (VOUT = VDDQ - 0.373V, minimum VREF, minimum VTT) | IOHR | −9 | − | mA | 39, 40 |
| | Low current (VOUT = 0.763V, maximum VREF, maximum VTT) | IOLR | +9 | − | mA | |
| Ambient operating temperatures | Commercial | TA | 0 | +70 | °C | |
| | Industrial | TA | −40 | +85 | °C | |

Table 11: DC Electrical Characteristics and Operating Conditions (-6, -6T, -75E, -75Z, -75)

Notes: 1–5, 17 apply to entire table; Notes appear on pages 26–32; $V_{DDQ} = +2.5V \pm 0.2V$, $V_{DD} = +2.5V \pm 0.2V$

| Parameter/Condition | | Symbol | Min | Max | Units | Notes |
|--|--|---------|-------------|-------------|-------|------------|
| Supply voltage | | VDD | +2.3 | +2.7 | V | 37, 42 |
| I/O supply voltage | | VDDQ | +2.3 | +2.7 | V | 37, 42, 45 |
| I/O reference voltage | | VREF | 0.49 x VDDQ | 0.51 x VDDQ | V | 7, 45 |
| I/O termination voltage (system) | | VTT | VREF - 0.04 | VREF + 0.04 | V | 8, 45 |
| Input high (logic 1) voltage | | VIH(DC) | VREF + 0.15 | VDD + 0.3 | V | 29 |
| Input low (logic 0) voltage | | VIL(DC) | −0.3 | VREF - 0.15 | V | 29 |
| Input leakage current: Any input 0V ≤ VIN ≤ VDD, VREF pin 0V ≤ VIN ≤ 1.35V (All other pins not under test = 0V) | | II | −2 | +2 | μA | |
| Output leakage current: (DQs are disabled; 0V ≤ VOUT ≤ VDDQ) | | IOZ | −5 | +5 | μA | |
| Full-drive option output levels: (x4, x8, x16) | High current (VOUT = VDDQ - 0.373V, minimum VREF, minimum VTT) | IOH | −16.8 | − | mA | 38, 40 |
| | Low current (VOUT = 0.373V, maximum VREF, maximum VTT) | IOL | +16.8 | − | mA | |
| Reduced-drive option output levels: (x16 only) | High current (VOUT = VDDQ - 0.763V, minimum VREF, minimum VTT) | IOHR | −9 | − | mA | 39, 40 |
| | Low current (VOUT = 0.763V, maximum VREF, maximum VTT) | IOLR | +9 | − | mA | |
| Ambient operating temperatures | Commercial | TA | 0 | +70 | °C | |
| | Industrial | TA | −40 | +85 | °C | |

Table 12: AC Input Operating Conditions

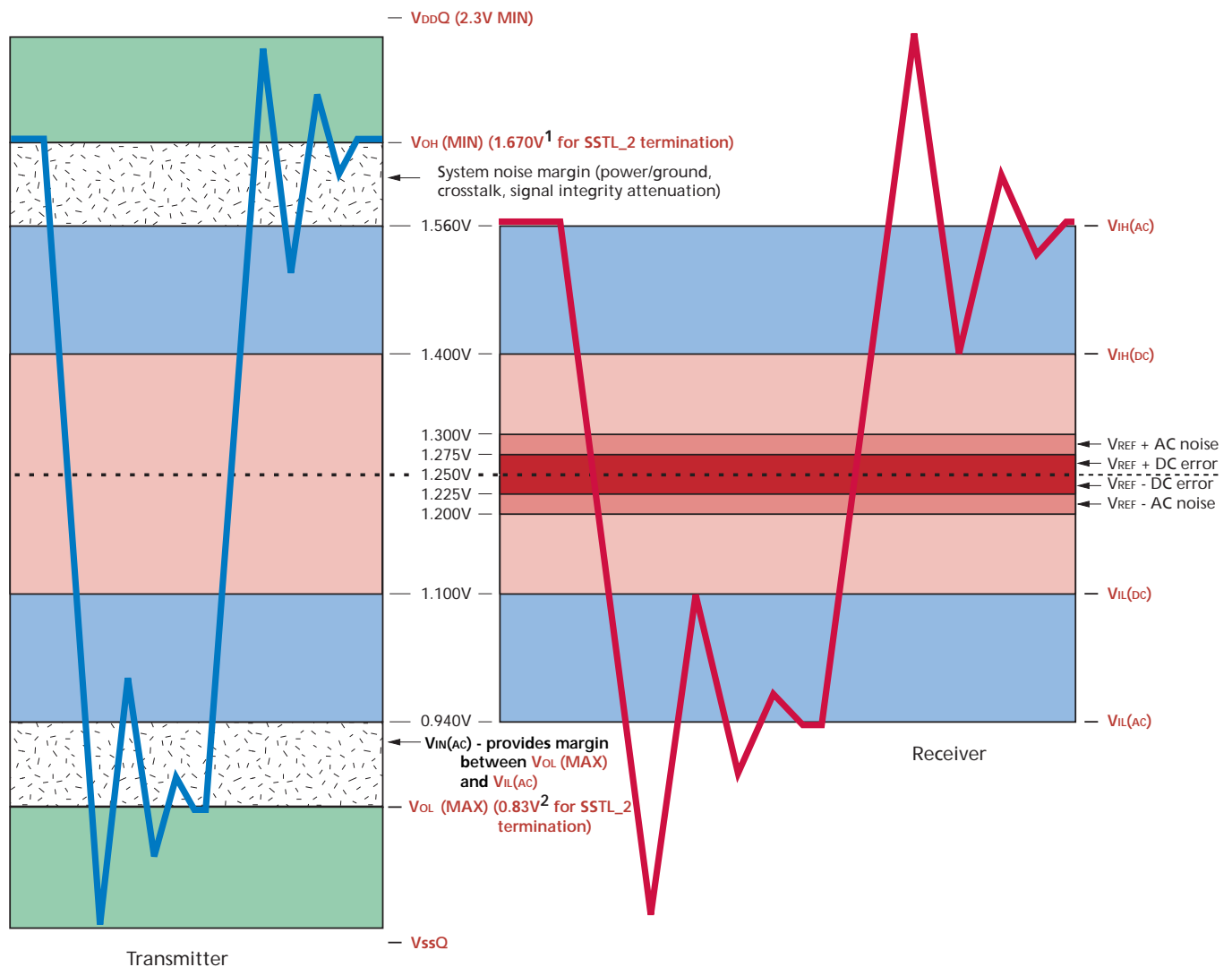
$0^{\circ}C \leq T_A \leq +70^{\circ}C$; $V_{DDQ} = +2.5V \pm 0.2V$, $V_{DD} = +2.5V \pm 0.2V$

($V_{DDQ} = +2.6V \pm 0.1V$, $V_{DD} = +2.6V \pm 0.1V$ for -5B)

Notes: 1–5, 15, 17 apply to entire table; Notes appear on pages 26–32

| Parameter/Condition | Symbol | Min | Max | Units | Notes |
|------------------------------|---------------|-----------------------|-----------------------|-------|------------|
| Input high (logic 1) voltage | $V_{IH}(AC)$ | $V_{REF} + 0.310$ | - | V | 15, 29, 41 |
| Input low (logic 0) voltage | $V_{IL}(AC)$ | - | $V_{REF} - 0.310$ | V | 15, 29, 41 |
| I/O reference voltage | $V_{REF}(AC)$ | $0.49 \times V_{DDQ}$ | $0.51 \times V_{DDQ}$ | V | 7 |

Figure 8: Input Voltage Waveform



- Notes:
1. V_{OH} (MIN) with test load is 1.927V.
 2. V_{OL} (MAX) with test load is 0.373V.
 3. Numbers in diagram reflect nominal values utilizing circuit below for all devices other than -5B.

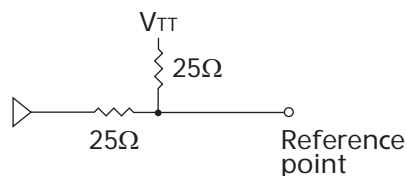


Table 13: Clock Input Operating Conditions

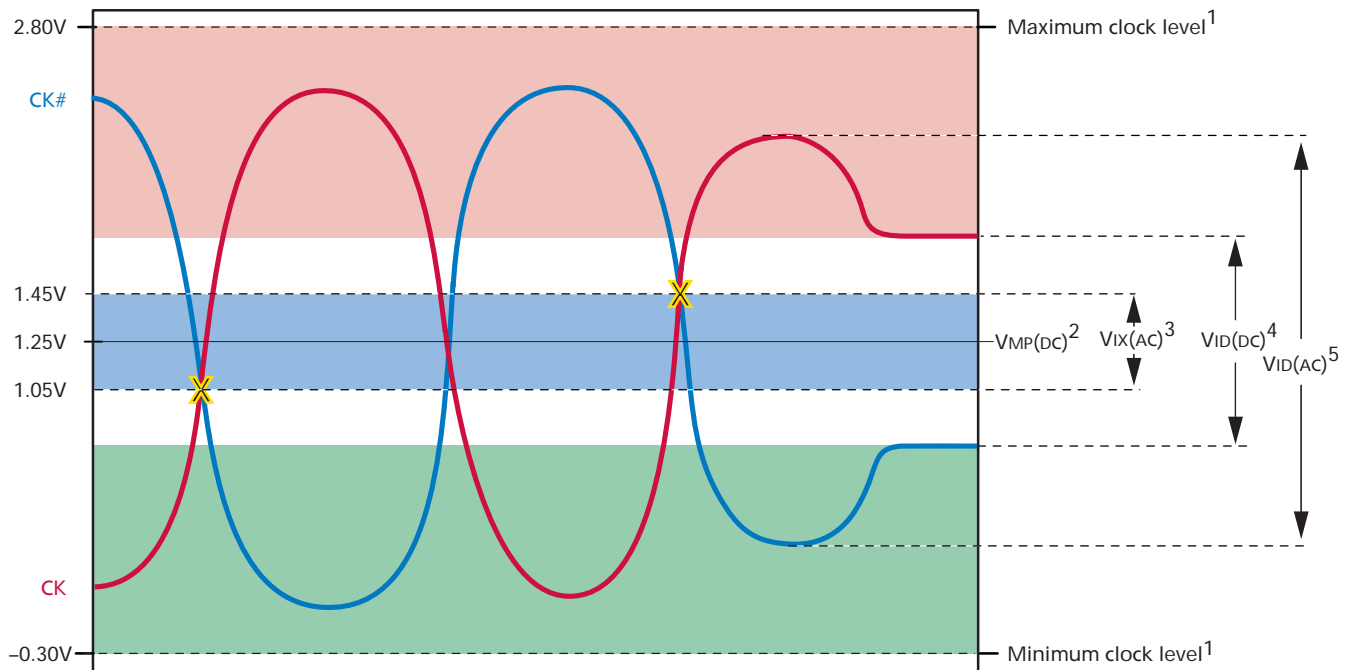
$0^{\circ}\text{C} \leq T_A \leq 70^{\circ}\text{C}$; $V_{DDQ} = +2.5\text{V} \pm 0.2\text{V}$, $V_{DD} = +2.5\text{V} \pm 0.2\text{V}$

($V_{DDQ} = +2.6\text{V} \pm 0.1\text{V}$, $V_{DD} = +2.6\text{V} \pm 0.1\text{V}$ for -5B)

Notes: 1–5, 16, 17, 31 apply to entire table; Notes appear on pages 26–32

| Parameter/Condition | Symbol | Min | Max | Units | Notes |
|--|---------|----------------------------|----------------------------|-------|-------|
| Clock input mid-point voltage: CK and CK# | VMP(DC) | 1.15 | 1.35 | V | 7, 10 |
| Clock input voltage level: CK and CK# | VIN(DC) | -0.3 | $V_{DDQ} + 0.3$ | V | 7 |
| Clock input differential voltage: CK and CK# | VID(DC) | 0.36 | $V_{DDQ} + 0.6$ | V | 7, 9 |
| Clock input differential voltage: CK and CK# | VID(AC) | 0.7 | $V_{DDQ} + 0.6$ | V | 9 |
| Clock input crossing point voltage: CK and CK# | VIX(AC) | $0.5 \times V_{DDQ} - 0.2$ | $0.5 \times V_{DDQ} + 0.2$ | V | 10 |

Figure 9: SSTL_2 Clock Input



- Notes:
1. CK or CK# may not be more positive than $V_{DDQ} + 0.3\text{V}$ or more negative than $V_{SS} - 0.3\text{V}$.
 2. This provides a minimum of 1.15V to a maximum of 1.35V and is always half of V_{DDQ} .
 3. CK and CK# must cross in this region.
 4. CK and CK# must meet at least VID(DC) MIN when static and is centered around VMP(DC).
 5. CK and CK# must have a minimum 700mV peak-to-peak swing.
 6. For AC operation, all DC clock requirements must also be satisfied.
 7. Numbers in diagram reflect nominal values for all devices other than -5B.

Table 14: Capacitance (x4, x8 TSOP – 128Mb, 256Mb, 512Mb, 1Gb)

Note: 14 applies to entire table; Notes appear on pages 26–32

| Parameter | Symbol | Min | Max | Units | Notes |
|--|------------------|-----|------|-------|-------|
| Delta input/output capacitance: DQ0–DQ3 (x4), DQ0–DQ7 (x8) | DC _{IO} | – | 0.50 | pF | 25 |
| Delta input capacitance: Command and address | DC _{I1} | – | 0.50 | pF | 30 |
| Delta input capacitance: CK, CK# | DC _{I2} | – | 0.25 | pF | 30 |
| Input/output capacitance: DQs, DQS, DM | C _{IO} | 4.0 | 5.0 | pF | |
| Input capacitance: Command and address | C _{I1} | 2.0 | 3.0 | pF | |
| Input capacitance: CK, CK# | C _{I2} | 2.0 | 3.0 | pF | |
| Input capacitance: CKE | C _{I3} | 2.0 | 3.0 | pF | |

Table 15: Capacitance (x4, x8 FBGA – 256Mb and 512Mb only)

Note: 14 applies to entire table; Notes appear on pages 26–32

| Parameter | Symbol | Min | Max | Units | Notes |
|--|------------------|-----|------|-------|-------|
| Delta input/output capacitance: DQs, DQS, DM | DC _{IO} | – | 0.50 | pF | 25 |
| Delta input capacitance: Command and address | DC _{I1} | – | 0.50 | pF | 30 |
| Delta input capacitance: CK, CK# | DC _{I2} | – | 0.25 | pF | 30 |
| Input/output capacitance: DQs, DQS, DM | C _{IO} | 3.5 | 4.5 | pF | |
| Input capacitance: Command and address | C _{I1} | 1.5 | 2.5 | pF | |
| Input capacitance: CK, CK# | C _{I2} | 1.5 | 2.5 | pF | |
| Input capacitance: CKE | C _{I3} | 1.5 | 2.5 | pF | |

Table 16: Capacitance (x16 TSOP – 128Mb, 256Mb, 512Mb, 1Gb)

Note: 14 applies to entire table; Notes appear on pages 26–32

| Parameter | Symbol | Min | Max | Units | Notes |
|---|------------------------------|-----|------|-------|-------|
| Delta input/output capacitance: DQ0–DQ7, LDQS, LDM | DC _{IO_L} | – | 0.50 | pF | 25 |
| Delta input/output capacitance: DQ8–DQ15, UDQS, UDM | DC _{IO_U} | – | 0.50 | pF | 25 |
| Delta input capacitance: Command and address | DC _{I1} | – | 0.50 | pF | 30 |
| Delta input capacitance: CK, CK# | DC _{I2} | – | 0.25 | pF | 30 |
| Input/output capacitance: DQ, LDQS, UDQS, LDM, UDM | C _{IO} | 4.0 | 5.0 | pF | |
| Input capacitance: Command and address | C _{I1} | 2.0 | 3.0 | pF | |
| Input capacitance: CK, CK# | C _{I2} | 2.0 | 3.0 | pF | |
| Input capacitance: CKE | C _{I3} | 2.0 | 3.0 | pF | |

Table 17: Capacitance (x16 FBGA – 256Mb and 512Mb only)

Note: 14 applies to entire table; Notes appear on pages 26–32

| Parameter | Symbol | Min | Max | Units | Notes |
|---|------------------------------|-----|------|-------|-------|
| Delta input/output capacitance: DQ0–DQ7, LDQS, LDM | DC _{IO_L} | – | 0.50 | pF | 25 |
| Delta input/output capacitance: DQ8–DQ15, UDQS, UDM | DC _{IO_U} | – | 0.50 | pF | 25 |
| Delta input capacitance: Command and address | DC _{I1} | – | 0.50 | pF | 30 |
| Delta input capacitance: CK, CK# | DC _{I2} | – | 0.25 | pF | 30 |
| Input/output capacitance: DQ, LDQS, UDQS, LDM, UDM | C _{IO} | 3.5 | 4.5 | pF | |
| Input capacitance: Command and address | C _{I1} | 1.5 | 2.5 | pF | |
| Input capacitance: CK, CK# | C _{I2} | 1.5 | 2.5 | pF | |
| Input capacitance: CKE | C _{I3} | 1.5 | 2.5 | pF | |

Table 18: Electrical Characteristics & Recommended AC Operating Conditions (-5B)

Notes: 1–6, 15–18, 34 apply to entire table; Notes appear on pages 26–32;
 $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$; $V_{DDQ} = +2.6\text{V} \pm 0.1\text{V}$, $V_{DD} = +2.6\text{V} \pm 0.1\text{V}$

| AC Characteristics | | | -5B | | | |
|--|---------------------|----------------|----------------------|--------|----------|--------|
| Parameter | | Symbol | Min | Max | Units | Notes |
| Access window of DQ from CK/CK# | | t_{AC} | −0.70 | +0.70 | ns | |
| CK high-level width | | t_{CH} | 0.45 | 0.55 | t_{CK} | 31 |
| Clock cycle time | CL = 3 | t_{CK} (3) | 5 | 7.5 | ns | 52 |
| | CL = 2.5 | t_{CK} (2.5) | 6 | 13 | ns | 46, 52 |
| | CL = 2 | t_{CK} (2) | 7.5 | 13 | ns | 46, 52 |
| CK low-level width | | t_{CL} | 0.45 | 0.55 | t_{CK} | 31 |
| DQ and DM input hold time relative to DQS | | t_{DH} | 0.40 | – | ns | 27, 32 |
| DQ and DM input pulse width (for each input) | | t_{DIPW} | 1.75 | – | ns | 32 |
| Access window of DQS from CK/CK# | | t_{DQSCK} | −0.60 | +0.60 | ns | |
| DQS input high pulse width | | t_{DQSH} | 0.35 | – | t_{CK} | |
| DQS input low pulse width | | t_{DQSL} | 0.35 | – | t_{CK} | |
| DQS–DQ skew, DQS to last DQ valid, per group, per access | | t_{DQSQ} | – | 0.40 | ns | 26, 27 |
| WRITE command to first DQS latching transition | | t_{DQSS} | 0.72 | 1.28 | t_{CK} | |
| DQ and DM input setup time relative to DQS | | t_{DS} | 0.40 | – | ns | 27, 32 |
| DQS falling edge from CK rising – hold time | | t_{DSH} | 0.2 | – | t_{CK} | |
| DQS falling edge to CK rising – setup time | | t_{DSS} | 0.2 | – | t_{CK} | |
| Half-clock period | | t_{HP} | t_{CH}, t_{CL} | – | ns | 35 |
| Data-out High-Z window from CK/CK# | | t_{HZ} | – | +0.70 | ns | 19, 43 |
| Address and control input hold time (slew rate ≥0.5 V/ns) | | t_{IH_F} | 0.60 | – | ns | 15 |
| Address and control input pulse width (for each input) | | t_{IPW} | 2.2 | – | ns | |
| Address and control input setup time (slew rate ≥0.5 V/ns) | | t_{IS_F} | 0.60 | – | ns | 15 |
| Data-out Low-Z window from CK/CK# | | t_{LZ} | −0.70 | – | ns | 19, 43 |
| LOAD MODE REGISTER command cycle time | | t_{MRD} | 10 | – | ns | |
| DQ–DQS hold, DQS to first DQ to go non-valid, per access | | t_{QH} | t_{HP} - t_{QHS} | – | ns | 26, 27 |
| Data hold skew factor | | t_{QHS} | – | 0.50 | ns | |
| ACTIVE-to-READ with auto precharge command | | t_{RAP} | 15 | – | ns | |
| ACTIVE-to-PRECHARGE command | | t_{RAS} | 40 | 70,000 | ns | 36 |
| ACTIVE-to-ACTIVE/AUTO REFRESH command period | | t_{RC} | 55 | – | ns | |
| ACTIVE-to-READ or WRITE delay | | t_{RCD} | 15 | – | ns | |
| REFRESH-to-REFRESH command interval | 128Mb | t_{REFC} | – | 140.6 | μs | 24 |
| | 256Mb, 512Mb, 1Gb | t_{REFC} | – | 70.3 | μs | 24 |
| AUTO REFRESH command period | 128Mb, 256Mb, 512Mb | t_{RFC} | 70 | – | ns | 50 |
| | 1Gb | t_{RFC} | 120 | – | ns | 50 |
| Average periodic refresh interval | 128Mb | t_{REFI} | – | 15.6 | μs | 24 |
| | 256Mb, 512Mb, 1Gb | t_{REFI} | – | 7.8 | μs | 24 |
| PRECHARGE command period | | t_{RP} | 15 | – | ns | |
| DQS read preamble | | t_{RPRE} | 0.9 | 1.1 | t_{CK} | 44 |
| DQS read postamble | | t_{RPST} | 0.4 | 0.6 | t_{CK} | 44 |
| ACTIVE bank <i>a</i> to ACTIVE bank <i>b</i> command | | t_{RRD} | 10 | – | ns | |
| Terminating voltage delay to VDD | | t_{VTD} | 0 | – | ns | |
| DQS write preamble | | t_{WPRE} | 0.25 | – | t_{CK} | |

Table 18: Electrical Characteristics & Recommended AC Operating Conditions (-5B) (continued)

Notes: 1–6, 15–18, 34 apply to entire table; Notes appear on pages 26–32;

 $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$; $V_{DDQ} = +2.6\text{V} \pm 0.1\text{V}$, $V_{DD} = +2.6\text{V} \pm 0.1\text{V}$

| AC Characteristics | | -5B | | Units | Notes |
|---------------------------------------|---------------------|---------------------|-----|----------|--------|
| Parameter | Symbol | Min | Max | | |
| DQS write preamble setup time | t_{WPRES} | 0 | – | ns | 21, 22 |
| DQS write postamble | t_{WPST} | 0.4 | 0.6 | t_{CK} | 20 |
| Write recovery time | t_{WR} | 15 | – | ns | |
| Internal WRITE-to-READ command delay | t_{WTR} | 2 | – | t_{CK} | |
| Exit SELF REFRESH-to-non-READ command | 128Mb, 256Mb, 512Mb | t_{XSNR} | 70 | – | ns |
| | 1Gb | t_{XSNR} | 126 | – | ns |
| Exit SELF REFRESH-to-READ command | t_{XSRD} | 200 | – | t_{CK} | |
| Data valid output window (DVW) | n/a | $t_{QH} - t_{DQSQ}$ | | ns | 26 |

Table 19: Electrical Characteristics and Recommended AC Operating Conditions (-6, -6T, -75E)

Notes: 1–6, 15–18, 34 apply to entire table; Notes appear on pages 26–32;

 $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$; $V_{DDQ} = +2.5\text{V} \pm 0.2\text{V}$, $V_{DD} = +2.5\text{V} \pm 0.2\text{V}$

| AC Characteristics | | | -6 (FBGA) ¹ | | -6T (TSOP) | | -75E | | Units | Notes |
|--|---------------------|------------------------------|---------------------------------------|--------|---------------------------------------|--------|---------------------------------------|---------|-----------------|--------|
| Parameter | | Symbol | Min | Max | Min | Max | Min | Max | | |
| Access window of DQ from CK/CK# | | ^t AC | −0.70 | +0.70 | −0.70 | +0.70 | −0.75 | +0.75 | ns | |
| CK high-level width | | ^t CH | 0.45 | 0.55 | 0.45 | 0.55 | 0.45 | 0.55 | ^t CK | 31 |
| Clock cycle time | CL = 2.5 | ^t CK (2.5) | 6 | 13 | 6 | 13 | 7.5 | 13 | ns | 46, 52 |
| | CL = 2 | ^t CK (2) | 7.5 | 13 | 7.5 | 13 | 7.5 | 13 | ns | 46, 52 |
| CK low-level width | | ^t CL | 0.45 | 0.55 | 0.45 | 0.55 | 0.45 | 0.55 | ^t CK | 31 |
| DQ and DM input hold time relative to DQS | | ^t DH | 0.45 | – | 0.45 | – | 0.5 | – | ns | 27, 32 |
| DQ and DM input pulse width (for each input) | | ^t DIPW | 1.75 | – | 1.75 | – | 1.75 | – | ns | 32 |
| Access window of DQS from CK/CK# | | ^t DQSCK | −0.6 | +0.6 | −0.6 | +0.6 | −0.75 | +0.75 | ns | |
| DQS input high pulse width | | ^t DQSH | 0.35 | – | 0.35 | – | 0.35 | – | ^t CK | |
| DQS input low pulse width | | ^t DQSL | 0.35 | – | 0.35 | – | 0.35 | – | ^t CK | |
| DQS–DQ skew, DQS to last DQ valid, per group, per access | | ^t DQSQ | – | 0.4 | – | 0.45 | – | 0.5 | ns | 26, 27 |
| WRITE command to first DQS latching transition | | ^t DOSS | 0.75 | 1.25 | 0.75 | 1.25 | 0.75 | 1.25 | ^t CK | |
| DQ and DM input setup time relative to DQS | | ^t DS | 0.45 | – | 0.45 | – | 0.5 | – | ns | 27, 32 |
| DQS falling edge from CK rising - hold time | | ^t DSH | 0.2 | – | 0.2 | – | 0.2 | – | ^t CK | |
| DQS falling edge to CK rising - setup time | | ^t DSS | 0.2 | – | 0.2 | – | 0.2 | – | ^t CK | |
| Half-clock period | | ^t HP | ^t CH, ^t CL | – | ^t CH, ^t CL | – | ^t CH, ^t CL | – | ns | 35 |
| Data-out High-Z window from CK/CK# | | ^t HZ | – | +0.7 | – | +0.7 | – | +0.75 | ns | 19, 43 |
| Address and control input hold time (fast slew rate) | | ^t IH _F | 0.75 | – | 0.75 | – | 0.90 | – | ns | |
| Address and control input hold time (slow slew rate) | | ^t IH _S | 0.8 | – | 0.8 | – | 1 | – | ns | 15 |
| Address and control input pulse width (for each input) | | ^t IPW | 2.2 | – | 2.2 | – | 2.2 | – | ns | |
| Address and control input setup time (fast slew rate) | | ^t IS _F | 0.75 | – | 0.75 | – | 0.90 | – | ns | |
| Address and control input setup time (slow slew rate) | | ^t IS _S | 0.8 | – | 0.8 | – | 1 | – | ns | 15 |
| Data-out Low-Z window from CK/CK# | | ^t LZ | −0.7 | – | −0.7 | – | −0.75 | – | ns | 19, 43 |
| LOAD MODE REGISTER command cycle time | | ^t MRD | 12 | – | 12 | – | 15 | – | ns | |
| DQ-DQS hold, DQS to first DQ to go non-valid, per access | | ^t QH | ^t HP - ^t QHS | – | ^t HP - ^t QHS | – | ^t HP - ^t QHS | – | ns | 26, 27 |
| Data hold skew factor | | ^t QHS | – | 0.50 | – | 0.55 | – | 0.75 | ns | |
| ACTIVE-to-READ with auto precharge command | | ^t RAP | 15 | – | 15 | – | 15 | – | ns | |
| ACTIVE-to-PRECHARGE command | | ^t RAS | 42 | 70,000 | 42 | 70,000 | 40 | 120,000 | ns | 36, 54 |
| ACTIVE-to-ACTIVE/AUTO REFRESH command period | | ^t RC | 60 | – | 60 | – | 60 | – | ns | |
| ACTIVE-to-READ or WRITE delay | | ^t RCD | 15 | – | 15 | – | 15 | – | ns | |
| REFRESH-to-REFRESH command interval | 128Mb | ^t REFC | – | 140.6 | – | 140.6 | – | 140.6 | μs | 24 |
| | 256Mb, 512Mb, 1Gb | ^t REFC | – | 70.3 | – | 70.3 | – | 70.3 | μs | 24 |
| Average periodic refresh interval | 128Mb | ^t REFI | – | 15.6 | – | 15.6 | – | 15.6 | μs | 24 |
| | 256Mb, 512Mb, 1Gb | ^t REFI | – | 7.8 | – | 7.8 | – | 7.8 | μs | 24 |
| AUTO REFRESH command period | 128Mb, 256Mb, 512Mb | ^t RFC | 72 | – | 72 | – | 75 | – | ns | 50 |
| | 1Gb | ^t RFC | – | – | 120 | – | – | – | ns | 50 |
| PRECHARGE command period | | ^t RP | 15 | – | 15 | – | 15 | – | ns | |
| DQS read preamble | | ^t RPRE | 0.9 | 1.1 | 0.9 | 1.1 | 0.9 | 1.1 | ^t CK | 44 |

Table 19: Electrical Characteristics and Recommended AC Operating Conditions (-6, -6T, -75E)
(continued)

Notes: 1–6, 15–18, 34 apply to entire table; Notes appear on pages 26–32;

| AC Characteristics | | -6 (FBGA) ¹ | | -6T (TSOP) | | -75E | | Units | Notes |
|--|---------------------|------------------------|---------------------|---------------------|---------------------|---------------------|---------------------|----------|--------|
| Parameter | Symbol | Min | Max | Min | Max | Min | Max | | |
| DQS read postamble | t_{RPST} | 0.4 | 0.6 | 0.4 | 0.6 | 0.4 | 0.6 | t_{CK} | 44 |
| ACTIVE bank <i>a</i> to ACTIVE bank <i>b</i> command | t_{RRD} | 12 | – | 12 | – | 15 | – | ns | |
| Terminating voltage delay to V _{ss} | t_{VTD} | 0 | – | 0 | – | 0 | – | ns | |
| DQS write preamble | t_{WPRE} | 0.25 | – | 0.25 | – | 0.25 | – | t_{CK} | |
| DQS write preamble setup time | t_{WPRES} | 0 | – | 0 | – | 0 | – | ns | 21, 22 |
| DQS write postamble | t_{WPST} | 0.4 | 0.6 | 0.4 | 0.6 | 0.4 | 0.6 | t_{CK} | 20 |
| Write recovery time | t_{WR} | 15 | – | 15 | – | 15 | – | ns | |
| Internal WRITE-to-READ command delay | t_{WTR} | 1 | – | 1 | – | 1 | – | t_{CK} | |
| Exit SELF REFRESH-to-non-READ command | 128Mb, 256Mb, 512Mb | t_{XSNR} | 75 | – | 75 | – | 75 | ns | |
| | 1Gb | t_{XSNR} | – | – | 126 | – | – | ns | |
| Exit SELF REFRESH-to-READ command | t_{XSRD} | 200 | – | 200 | – | 200 | – | t_{CK} | |
| Data valid output window (DVW) | n/a | $t_{QH} - t_{DQSQ}$ | $t_{QH} - t_{DQSQ}$ | $t_{QH} - t_{DQSQ}$ | $t_{QH} - t_{DQSQ}$ | $t_{QH} - t_{DQSQ}$ | $t_{QH} - t_{DQSQ}$ | ns | 26 |

Notes: 1. -6 (FBGA) available in 256Mb and 512Mb densities only.

Table 20: Electrical Characteristics and Recommended AC Operating Conditions (-75Z, -75)

Notes: 1–6, 15–18, 34 apply to entire table; Notes appear on pages 26–32;

 $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$; $V_{DDQ} = +2.5\text{V} \pm 0.2\text{V}$, $V_{DD} = +2.5\text{V} \pm 0.2\text{V}$

| AC Characteristics | | | -75Z | | -75 | | Units | Notes |
|--|---------------------|----------------|--------------------|---------|--------------------|---------|---------------|--------|
| Parameter | | Symbol | Min | Max | Min | Max | | |
| Access window of DQ from CK/CK# | | t_{AC} | -0.75 | +0.75 | -0.75 | +0.75 | ns | |
| CK high-level width | | t_{CH} | 0.45 | 0.55 | 0.45 | 0.55 | t_{CK} | 31 |
| Clock cycle time | CL = 2.5 | $t_{CK} (2.5)$ | 7.5 | 13 | 7.5 | 13 | ns | 46 |
| | CL = 2 | $t_{CK} (2)$ | 7.5 | 13 | 10 | 13 | ns | 46 |
| CK low-level width | | t_{CL} | 0.45 | 0.55 | 0.45 | 0.55 | t_{CK} | 31 |
| DQ and DM input hold time relative to DQS | | t_{DH} | 0.5 | – | 0.5 | – | ns | 27, 32 |
| DQ and DM input pulse width (for each input) | | t_{DIPW} | 1.75 | – | 1.75 | – | ns | 32 |
| Access window of DQS from CK/CK# | | t_{DQSCK} | -0.75 | +0.75 | -0.75 | +0.75 | ns | |
| DQS input high pulse width | | t_{DQSH} | 0.35 | – | 0.35 | – | t_{CK} | |
| DQS input low pulse width | | t_{DQSL} | 0.35 | – | 0.35 | – | t_{CK} | |
| DQS–DQ skew, DQS to last DQ valid, per group, per access | | t_{DQSQ} | – | 0.5 | – | 0.5 | ns | 26, 27 |
| WRITE command-to-first DQS latching transition | | t_{DQSS} | 0.75 | 1.25 | 0.75 | 1.25 | t_{CK} | |
| DQ and DM input setup time relative to DQS | | t_{DS} | 0.5 | – | 0.5 | – | ns | 27, 32 |
| DQS falling edge from CK rising – hold time | | t_{DSH} | 0.2 | – | 0.2 | – | t_{CK} | |
| DQS falling edge to CK rising – setup time | | t_{DSS} | 0.2 | – | 0.2 | – | t_{CK} | |
| Half-clock period | | t_{HP} | t_{CH}, t_{CL} | – | t_{CH}, t_{CL} | – | ns | 35 |
| Data-out High-Z window from CK/CK# | | t_{HZ} | – | +0.75 | – | +0.75 | ns | 19, 43 |
| Address and control input hold time (fast slew rate) | | t_{IH_F} | 0.90 | – | 0.90 | – | ns | |
| Address and control input hold time (slow slew rate) | | t_{IH_S} | 1 | – | 1 | – | ns | 15 |
| Address and control input pulse width (for each input) | | t_{IPW} | 2.2 | – | 2.2 | – | ns | |
| Address and control input setup time (fast slew rate) | | t_{IS_F} | 0.90 | – | 0.90 | – | ns | |
| Address and control input setup time (slow slew rate) | | t_{IS_S} | 1 | – | 1 | – | ns | 15 |
| Data-out Low-Z window from CK/CK# | | t_{LZ} | -0.75 | – | -0.75 | – | ns | 19, 43 |
| LOAD MODE REGISTER command cycle time | | t_{MRD} | 15 | – | 15 | – | ns | |
| DQ–DQS hold, DQS to first DQ to go non-valid, per access | | t_{QH} | $t_{HP} - t_{QHS}$ | – | $t_{HP} - t_{QHS}$ | – | ns | 26, 27 |
| Data hold skew factor | | t_{QHS} | – | 0.75 | – | 0.75 | ns | |
| ACTIVE-to-READ with auto precharge command | | t_{RAP} | 20 | – | 20 | – | ns | |
| ACTIVE-to-PRECHARGE command | | t_{RAS} | 40 | 120,000 | 40 | 120,000 | ns | 36 |
| ACTIVE-to-ACTIVE/AUTO REFRESH command period | | t_{RC} | 65 | – | 65 | – | ns | |
| ACTIVE-to-READ or WRITE delay | | t_{RCD} | 20 | – | 20 | – | ns | |
| REFRESH-to-REFRESH command interval | 128Mb | t_{REFC} | – | 140.6 | – | 140.6 | μs | 24 |
| | 256Mb, 512Mb, 1Gb | t_{REFC} | – | 70.3 | – | 70.3 | μs | 24 |
| Average periodic refresh interval | 128Mb | t_{REFI} | – | 15.6 | – | 15.6 | μs | 24 |
| | 256Mb, 512Mb, 1Gb | t_{REFI} | – | 7.8 | – | 7.8 | μs | 24 |
| AUTO REFRESH command period | 128Mb, 256Mb, 512Mb | t_{RFC} | 75 | – | 75 | – | ns | 50 |
| | 1Gb | t_{RFC} | – | – | 120 | – | ns | 50 |

Table 20: Electrical Characteristics and Recommended AC Operating Conditions (-75Z, -75)
(continued)

Notes: 1–6, 15–18, 34 apply to entire table; Notes appear on pages 26–32;

| AC Characteristics | | -75Z | | -75 | | Units | Notes |
|--|---------------------------|---------------------|-----|---------------------|-------|----------|--------|
| Parameter | Symbol | Min | Max | Min | Max | | |
| PRECHARGE command period | t_{RP} | 20 | – | 20 | – | ns | |
| DQS read preamble | t_{RPRE} | 0.9 | 1.1 | 0.9 | 1.1 | t_{CK} | 44 |
| DQS read postamble | t_{RPST} | 0.4 | 0.6 | 0.4 | 0.6 | t_{CK} | 44 |
| ACTIVE bank <i>a</i> to ACTIVE bank <i>b</i> command | t_{RRD} | 15 | – | 15 | – | ns | |
| Terminating voltage delay to VDD | t_{VTD} | 0 | – | 0 | – | ns | |
| DQS write preamble | t_{WPRE} | 0.25 | – | 0.25 | – | t_{CK} | |
| DQS write preamble setup time | t_{WPRES} | 0 | – | 0 | – | ns | 21, 22 |
| DQS write postamble | t_{WPST} | 0.4 | 0.6 | 0.4 | 0.6 | t_{CK} | 20 |
| Write recovery time | t_{WR} | 15 | – | 15 | – | ns | |
| Internal WRITE-to-READ command delay | t_{WTR} | 1 | – | 1 | – | t_{CK} | |
| Exit SELF REFRESH-to-non-READ command | 128Mb, 256Mb, 512Mb | t_{XSNR} | 75 | – | 75 | ns | |
| | 1Gb | t_{XSNR} | – | – | 127.5 | ns | |
| Exit SELF REFRESH-to-READ command | t_{XSRD} | 200 | – | 200 | – | t_{CK} | |
| Data valid output window (DVW) | n/a | $t_{QH} - t_{DQSQ}$ | | $t_{QH} - t_{DQSQ}$ | | ns | 26 |

Table 21: Input Slew Rate Derating Values for Addresses and Commands

Note: 15 applies to entire table; $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$; $V_{DDQ} = +2.5\text{V} \pm 0.2\text{V}$, $V_{DD} = +2.5\text{V} \pm 0.2\text{V}$

| Speed | Slew Rate | t_{IS} | t_{IH} | Units |
|---------------|------------|----------|----------|-------|
| -75/-75Z/-75E | 0.500 V/ns | 1.00 | 1 | ns |
| -75/-75Z/-75E | 0.400 V/ns | 1.05 | 1 | ns |
| -75/-75Z/-75E | 0.300 V/ns | 1.10 | 1 | ns |

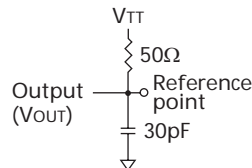
Table 22: Input Slew Rate Derating Values for DQ, DQS, and DM

Note: 32 apply to entire table; $0^{\circ}\text{C} \leq T_A \leq +70^{\circ}\text{C}$; $V_{DDQ} = +2.5\text{V} \pm 0.2\text{V}$, $V_{DD} = +2.5\text{V} \pm 0.2\text{V}$

| Speed | Slew Rate | t_{DS} | t_{DH} | Units |
|---------------|------------|----------|----------|-------|
| -75/-75Z/-75E | 0.500 V/ns | 0.50 | 0.50 | ns |
| -75/-75Z/-75E | 0.400 V/ns | 0.55 | 0.55 | ns |
| -75/-75Z/-75E | 0.300 V/ns | 0.60 | 0.60 | ns |

Notes

1. All voltages referenced to VSS.
2. Tests for AC timing, I_{DD} , and electrical AC and DC characteristics may be conducted at nominal reference/supply voltage levels, but the related specifications and the device operation are guaranteed for the full voltage range specified.
3. Outputs (except for I_{DD} measurements) measured with equivalent load:

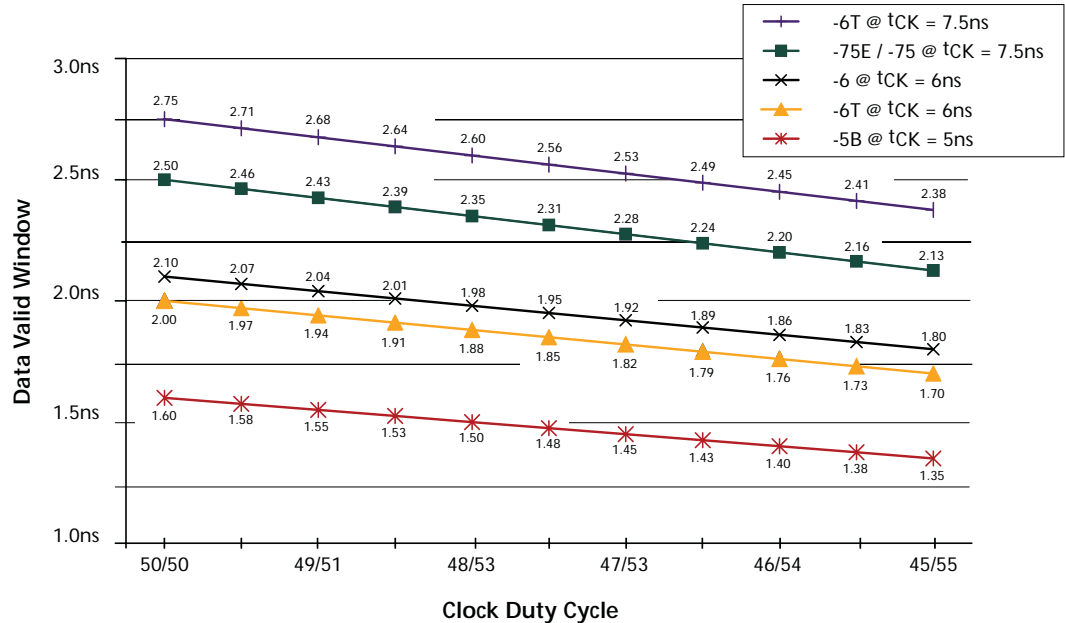


4. AC timing and I_{DD} tests may use a V_{IL} -to- V_{IH} swing of up to 1.5V in the test environment, but input timing is still referenced to V_{REF} (or to the crossing point for CK/CK#), and parameter specifications are guaranteed for the specified AC input levels under normal use conditions. The minimum slew rate for the input signals used to test the device is 1 V/ns in the range between $V_{IL(AC)}$ and $V_{IH(AC)}$.
5. The AC and DC input level specifications are as defined in the SSTL_2 standard (i.e., the receiver will effectively switch as a result of the signal crossing the AC input level and will remain in that state as long as the signal does not ring back above [below] the DC input LOW [HIGH] level).
6. All speed grades are not offered on all densities. Refer to page 1 for availability.
7. V_{REF} is expected to equal $V_{DDQ}/2$ of the transmitting device and to track variations in the DC level of the same. Peak-to-peak noise (noncommon mode) on V_{REF} may not exceed ± 2 percent of the DC value. Thus, from $V_{DDQ}/2$, V_{REF} is allowed ± 25 mV for DC error and an additional ± 25 mV for AC noise. This measurement is to be taken at the nearest V_{REF} bypass capacitor.
8. V_{TT} is not applied directly to the device. V_{TT} is a system supply for signal termination resistors, it is expected to be set equal to V_{REF} , and it must track variations in the DC level of V_{REF} .
9. V_{ID} is the magnitude of the difference between the input level on CK and the input level on CK#.
10. The value of V_{IX} and V_{MP} is expected to equal $V_{DDQ}/2$ of the transmitting device and must track variations in the DC level of the same.
11. I_{DD} is dependent on output loading and cycle rates. Specified values are obtained with minimum cycle times at CL = 3 for -5B; CL = 2.5, -6/-6T/-75; and CL = 2, -75E/-75Z speeds with the outputs open.
12. Enables on-chip refresh and address counters.
13. I_{DD} specifications are tested after the device is properly initialized and is averaged at the defined cycle rate.
14. This parameter is sampled. $V_{DD} = +2.5V \pm 0.2V$, $V_{DDQ} = +2.5V \pm 0.2V$, $V_{REF} = V_{SS}$, $f = 100$ MHz, $T_A = 25^\circ C$, $V_{OUT(DC)} = V_{DDQ}/2$, V_{OUT} (peak-to-peak) = 0.2V. DM input is grouped with I/O pins, reflecting the fact that they are matched in loading.
15. For slew rates less than 1 V/ns and greater than or equal to 0.5 V/ns. If the slew rate is less than 0.5 V/ns, timing must be derated: t_{IS} has an additional 50ps per each 100 mV/ns reduction in slew rate from the 500 mV/ns. t_{IH} has 0ps added, that is, it remains constant. If the slew rate exceeds 4.5 V/ns, functionality is uncertain. For -5B, -6, and -6T, slew rates must be greater than or equal to 0.5 V/ns.

16. The CK/CK# input reference level (for timing referenced to CK/CK#) is the point at which CK and CK# cross; the input reference level for signals other than CK/CK# is VREF.
17. Inputs are not recognized as valid until VREF stabilizes. Once initialized, including self refresh mode, VREF must be powered within specified range. Exception: during the period before VREF stabilizes, $CKE < 0.3 \times VDD$ is recognized as LOW.
18. The output timing reference level, as measured at the timing reference point (indicated in Note 3), is VTT.
19. t_{HZ} and t_{LZ} transitions occur in the same access time windows as data valid transitions. These parameters are not referenced to a specific voltage level, but specify when the device output is no longer driving (High-Z) or begins driving (Low-Z).
20. The intent of the “Don’t Care” state after completion of the postamble is the DQS-driven signal should either be HIGH, LOW, or High-Z, and that any signal transition within the input switching region must follow valid input requirements. That is, if DQS transitions HIGH (above $V_{IH}[DC]$ MIN) then it must not transition LOW (below $V_{IH}[DC]$ prior to t_{DQSH} [MIN]).
21. This is not a device limit. The device will operate with a negative value, but system performance could be degraded due to bus turnaround.
22. It is recommended that DQS be valid (HIGH or LOW) on or before the WRITE command. The case shown (DQS going from High-Z to logic LOW) applies when no WRITES were previously in progress on the bus. If a previous WRITE was in progress, DQS could be HIGH during this time, depending on t_{DQSS} .
23. MIN (t_{RC} or t_{RFC}) for IDD measurements is the smallest multiple of t_{CK} that meets the minimum absolute value for the respective parameter. t_{RAS} (MAX) for IDD measurements is the largest multiple of t_{CK} that meets the maximum absolute value for t_{RAS} .
24. The refresh period is 64ms. This equates to an average refresh rate of 7.8125 μ s (15.625 μ s for 128Mb DDR). However, an AUTO REFRESH command must be asserted at least once every 70.3 μ s (140.6 μ s for 128Mb DDR); burst refreshing or posting by the DRAM controller greater than 8 REFRESH cycles is not allowed.
25. The I/O capacitance per DQS and DQ byte/group will not differ by more than this maximum amount for any given device.
26. The data valid window is derived by achieving other specifications: t_{HP} ($t_{CK}/2$), t_{DQSQ} , and t_{QH} ($t_{QH} = t_{HP} - t_{QHS}$). The data valid window derates in direct proportion to the clock duty cycle and a practical data valid window can be derived. The clock is allowed a maximum duty cycle variation of 45/55, because functionality is uncertain when operating beyond a 45/55 ratio. The data valid window derating curves are provided in Figure 10 on page 28 for duty cycles ranging between 50/50 and 45/55.
27. Referenced to each output group: x4 = DQS with DQ0–DQ3; x8 = DQS with DQ0–DQ7; x16 = LDQS with DQ0–DQ7 and UDQS with DQ8–DQ15.
28. This limit is actually a nominal value and does not result in a fail value. CKE is HIGH during the REFRESH command period (t_{RFC} [MIN]) else CKE is LOW (i.e., during standby).
29. To maintain a valid level, the transitioning edge of the input must:
 - 29a. Sustain a constant slew rate from the current AC level through to the target AC level, $V_{IL}(AC)$ or $V_{IH}(AC)$.
 - 29b. Reach at least the target AC level.
 - 29c. After the AC target level is reached, continue to maintain at least the target DC level, $V_{IL}(DC)$ or $V_{IH}(DC)$.
30. The input capacitance per pin group will not differ by more than this maximum amount for any given device.

31. CK and CK# input slew rate must be ≥ 1 V/ns (≥ 2 V/ns if measured differentially).

Figure 10: Derating Data Valid Window ($t_{QH} - t_{DQSQ}$)



32. DQ and DM input slew rates must not deviate from DQS by more than 10 percent. If the DQ/DM/DQS slew rate is less than 0.5 V/ns, timing must be derated: 50ps must be added to t_{DS} and t_{DH} for each 100 mV/ns reduction in slew rate. For -5B, -6, and -6T speed grades, the slew rate must be ≥ 0.5 V/ns. If the slew rate exceeds 4 V/ns, functionality is uncertain.
33. VDD must not vary more than 4 percent if CKE is not active while any bank is active.
34. The clock is allowed up to ± 150 ps of jitter. Each timing parameter is allowed to vary by the same amount.
35. t_{HP} (MIN) is the lesser of t_{CL} (MIN) and t_{CH} (MIN) actually applied to the device CK and CK# inputs, collectively, during bank active.
36. READs and WRITEs with auto precharge are not allowed to be issued until t_{RAS} (MIN) can be satisfied prior to the internal PRECHARGE command being issued.
37. Any positive glitch must be less than 1/3 of the clock cycle and not more than +400mV or 2.9V (+300mV or 2.9V maximum for -5B), whichever is less. Any negative glitch must be less than 1/3 of the clock cycle and not exceed either -300mV or 2.2V (2.4V for -5B), whichever is more positive. The average cannot be below the +2.5V (2.6V for -5B) minimum.
38. Normal output drive curves:
- 38a. The full driver pull-down current variation from MIN to MAX process; temperature and voltage will lie within the outer bounding lines of the V-I curve of Figure 11 on page 29.
- 38b. The driver pull-down current variation, within nominal voltage and temperature limits, is expected, but not guaranteed, to lie within the inner bounding lines of the V-I curve of Figure 11 on page 29.
- 38c. The full driver pull-up current variation from MIN to MAX process; temperature and voltage will lie within the outer bounding lines of the V-I curve of Figure 12 on page 29.

- 38d. The driver pull-up current variation within nominal limits of voltage and temperature is expected, but not guaranteed, to lie within the inner bounding lines of the V-I curve of Figure 12 on page 29.
- 38e. The full ratio variation of MAX to MIN pull-up and pull-down current should be between 0.71 and 1.4 for drain-to-source voltages from 0.1V to 1.0V at the same voltage and temperature.
- 38f. The full ratio variation of the nominal pull-up to pull-down current should be unity ± 10 percent for device drain-to-source voltages from 0.1V to 1.0V.

Figure 11: Full Drive Pull-Down Characteristics

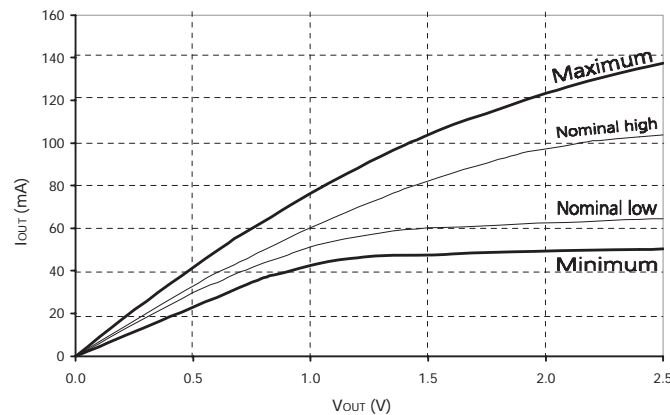
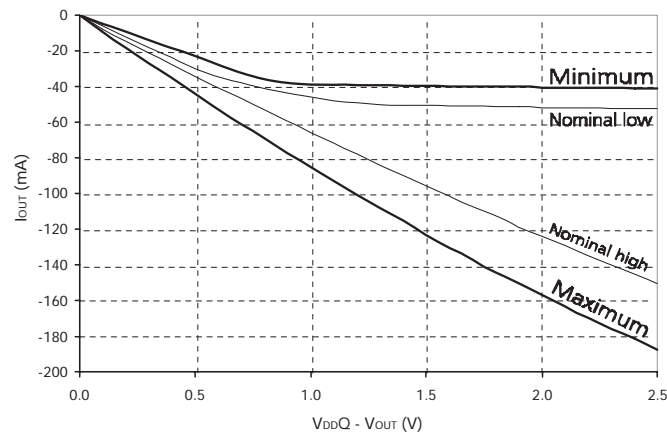


Figure 12: Full Drive Pull-Up Characteristics



39. Reduced output drive curves:

- 39a. The full driver pull-down current variation from MIN to MAX process; temperature and voltage will lie within the outer bounding lines of the V-I curve of Figure 13 on page 30.
- 39b. The driver pull-down current variation, within nominal voltage and temperature limits, is expected, but not guaranteed, to lie within the inner bounding lines of the V-I curve of Figure 13 on page 30.
- 39c. The full driver pull-up current variation from MIN to MAX process; temperature and voltage will lie within the outer bounding lines of the V-I curve of Figure 14.

- 39d. The driver pull-up current variation, within nominal voltage and temperature limits, is expected, but not guaranteed, to lie within the inner bounding lines of the V-I curve of Figure 14 on page 30.
- 39e. The full ratio variation of the MAX-to-MIN pull-up and pull-down current should be between 0.71 and 1.4 for device drain-to-source voltages from 0.1V to 1.0V at the same voltage and temperature.
- 39f. The full ratio variation of the nominal pull-up to pull-down current should be unity ± 10 percent, for device drain-to-source voltages from 0.1V to 1.0V.

Figure 13: Reduced Drive Pull-Down Characteristics

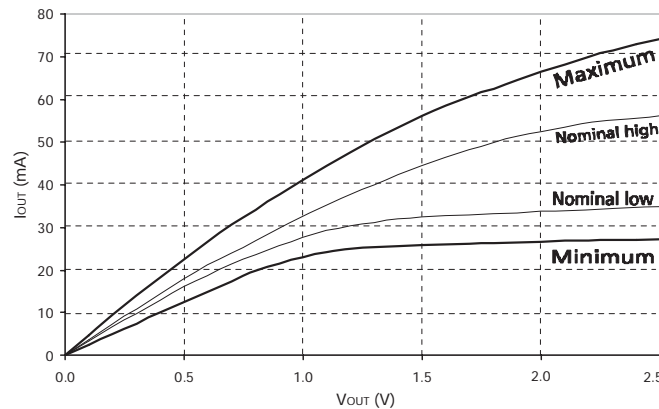
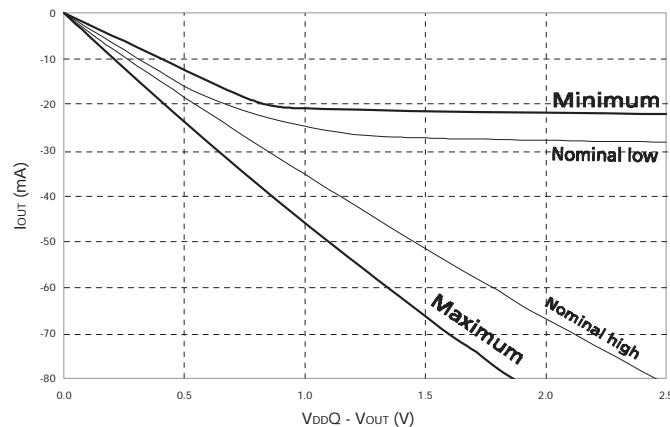


Figure 14: Reduced Drive Pull-Up Characteristics



- 40. The voltage levels used are derived from a minimum VDD level and the referenced test load. In practice, the voltage levels obtained from a properly terminated bus will provide significantly different voltage values.
- 41. VIH overshoot: $V_{IH} (MAX) = V_{DDQ} + 1.5V$ for a pulse width $\leq 3ns$, and the pulse width can not be greater than 1/3 of the cycle rate. VIL undershoot: $V_{IL} (MIN) = -1.5V$ for a pulse width $\leq 3ns$, and the pulse width can not be greater than 1/3 of the cycle rate.
- 42. VDD and VDDQ must track each other.
- 43. $t_{HZ} (MAX)$ will prevail over $t_{DQSCK} (MAX) + t_{RPST} (MAX)$ condition. $t_{LZ} (MIN)$ will prevail over $t_{DQSCK} (MIN) + t_{RPRE} (MAX)$ condition.

44. t_{RPST} end point and t_{RPRE} begin point are not referenced to a specific voltage level but specify when the device output is no longer driving (t_{RPST}) or begins driving (t_{RPRE}).
45. During initialization, V_{DDQ} , V_{TT} , and V_{REF} must be equal to or less than $V_{DD} + 0.3V$. Alternatively, V_{TT} may be 1.35V maximum during power up, even if V_{DD}/V_{DDQ} are 0V, provided a minimum of 42Ω of series resistance is used between the V_{TT} supply and the input pin.
46. The current Micron part operates below 83 MHz (slowest specified JEDEC operating frequency). As such, future die may not reflect this option.
47. When an input signal is HIGH or LOW, it is defined as a steady state logic HIGH or LOW.
48. Random address is changing; 50 percent of data is changing at every transfer.
49. Random address is changing; 100 percent of data is changing at every transfer.
50. CKE must be active (HIGH) during the entire time a REFRESH command is executed. That is, from the time the AUTO REFRESH command is registered, CKE must be active at each rising clock edge, until t_{RFC} has been satisfied.
51. $IDD2N$ specifies the DQ, DQS, and DM to be driven to a valid HIGH or LOW logic level. $IDD2Q$ is similar to $IDD2F$ except $IDD2Q$ specifies the address and control inputs to remain stable. Although $IDD2F$, $IDD2N$, and $IDD2Q$ are similar, $IDD2F$ is “worst case.”
52. Whenever the operating frequency is altered, not including jitter, the DLL is required to be reset followed by 200 clock cycles before any READ command.
53. This is the DC voltage supplied at the DRAM and is inclusive of all noise up to 20 MHz. Any noise above 20 MHz at the DRAM generated from any source other than that of the DRAM itself may not exceed the DC voltage range of $2.6V \pm 100mV$.
54. The -6/-6T speed grades will operate with $t_{RAS} (MIN) = 40ns$ and $t_{RAS} (MAX) = 120,000ns$ at any slower frequency.

Table 23: Normal Output Drive Characteristics

Characteristics are specified under best, worst, and nominal process variation/conditions

| Voltage (V) | Pull-Down Current (mA) | | | | Pull-Up Current (mA) | | | |
|-------------|------------------------|--------------|------|-------|----------------------|--------------|-------|--------|
| | Nominal Low | Nominal High | Min | Max | Nominal Low | Nominal High | Min | Max |
| 0.1 | 6.0 | 6.8 | 4.6 | 9.6 | -6.1 | -7.6 | -4.6 | -10.0 |
| 0.2 | 12.2 | 13.5 | 9.2 | 18.2 | -12.2 | -14.5 | -9.2 | -20.0 |
| 0.3 | 18.1 | 20.1 | 13.8 | 26.0 | -18.1 | -21.2 | -13.8 | -29.8 |
| 0.4 | 24.1 | 26.6 | 18.4 | 33.9 | -24.0 | -27.7 | -18.4 | -38.8 |
| 0.5 | 29.8 | 33.0 | 23.0 | 41.8 | -29.8 | -34.1 | -23.0 | -46.8 |
| 0.6 | 34.6 | 39.1 | 27.7 | 49.4 | -34.3 | -40.5 | -27.7 | -54.4 |
| 0.7 | 39.4 | 44.2 | 32.2 | 56.8 | -38.1 | -46.9 | -32.2 | -61.8 |
| 0.8 | 43.7 | 49.8 | 36.8 | 63.2 | -41.1 | -53.1 | -36.0 | -69.5 |
| 0.9 | 47.5 | 55.2 | 39.6 | 69.9 | -43.8 | -59.4 | -38.2 | -77.3 |
| 1.0 | 51.3 | 60.3 | 42.6 | 76.3 | -46.0 | -65.5 | -38.7 | -85.2 |
| 1.1 | 54.1 | 65.2 | 44.8 | 82.5 | -47.8 | -71.6 | -39.0 | -93.0 |
| 1.2 | 56.2 | 69.9 | 46.2 | 88.3 | -49.2 | -77.6 | -39.2 | -100.6 |
| 1.3 | 57.9 | 74.2 | 47.1 | 93.8 | -50.0 | -83.6 | -39.4 | -108.1 |
| 1.4 | 59.3 | 78.4 | 47.4 | 99.1 | -50.5 | -89.7 | -39.6 | -115.5 |
| 1.5 | 60.1 | 82.3 | 47.7 | 103.8 | -50.7 | -95.5 | -39.9 | -123.0 |
| 1.6 | 60.5 | 85.9 | 48.0 | 108.4 | -51.0 | -101.3 | -40.1 | -130.4 |
| 1.7 | 61.0 | 89.1 | 48.4 | 112.1 | -51.1 | -107.1 | -40.2 | -136.7 |
| 1.8 | 61.5 | 92.2 | 48.9 | 115.9 | -51.3 | -112.4 | -40.3 | -144.2 |
| 1.9 | 62.0 | 95.3 | 49.1 | 119.6 | -51.5 | -118.7 | -40.4 | -150.5 |
| 2.0 | 62.5 | 97.2 | 49.4 | 123.3 | -51.6 | -124.0 | -40.5 | -156.9 |
| 2.1 | 62.8 | 99.1 | 49.6 | 126.5 | -51.8 | -129.3 | -40.6 | -163.2 |
| 2.2 | 63.3 | 100.9 | 49.8 | 129.5 | -52.0 | -134.6 | -40.7 | -169.6 |
| 2.3 | 63.8 | 101.9 | 49.9 | 132.4 | -52.2 | -139.9 | -40.8 | -176.0 |
| 2.4 | 64.1 | 102.8 | 50.0 | 135.0 | -52.3 | -145.2 | -40.9 | -181.3 |
| 2.5 | 64.6 | 103.8 | 50.2 | 137.3 | -52.5 | -150.5 | -41.0 | -187.6 |
| 2.6 | 64.8 | 104.6 | 50.4 | 139.2 | -52.7 | -155.3 | -41.1 | -192.9 |
| 2.7 | 65.0 | 105.4 | 50.5 | 140.8 | -52.8 | -160.1 | -41.2 | -198.2 |

Table 24: Reduced Output Drive Characteristics

Characteristics are specified under best, worst, and nominal process variation/conditions

| Voltage (V) | Pull-Down Current (mA) | | | | Pull-Up Current (mA) | | | |
|-------------|------------------------|--------------|------|------|----------------------|--------------|-------|-------|
| | Nominal Low | Nominal High | Min | Max | Nominal Low | Nominal High | Min | Max |
| 0.1 | 3.4 | 3.8 | 2.6 | 5.0 | -3.5 | -4.3 | -2.6 | -5.0 |
| 0.2 | 6.9 | 7.6 | 5.2 | 9.9 | -6.9 | -7.8 | -5.2 | -9.9 |
| 0.3 | 10.3 | 11.4 | 7.8 | 14.6 | -10.3 | -12.0 | -7.8 | -14.6 |
| 0.4 | 13.6 | 15.1 | 10.4 | 19.2 | -13.6 | -15.7 | -10.4 | -19.2 |
| 0.5 | 16.9 | 18.7 | 13.0 | 23.6 | -16.9 | -19.3 | -13.0 | -23.6 |
| 0.6 | 19.9 | 22.1 | 15.7 | 28.0 | -19.4 | -22.9 | -15.7 | -28.0 |
| 0.7 | 22.3 | 25.0 | 18.2 | 32.2 | -21.5 | -26.5 | -18.2 | -32.2 |
| 0.8 | 24.7 | 28.2 | 20.8 | 35.8 | -23.3 | -30.1 | -20.4 | -35.8 |
| 0.9 | 26.9 | 31.3 | 22.4 | 39.5 | -24.8 | -33.6 | -21.6 | -39.5 |
| 1.0 | 29.0 | 34.1 | 24.1 | 43.2 | -26.0 | -37.1 | -21.9 | -43.2 |
| 1.1 | 30.6 | 36.9 | 25.4 | 46.7 | -27.1 | -40.3 | -22.1 | -46.7 |
| 1.2 | 31.8 | 39.5 | 26.2 | 50.0 | -27.8 | -43.1 | -22.2 | -50.0 |
| 1.3 | 32.8 | 42.0 | 26.6 | 53.1 | -28.3 | -45.8 | -22.3 | -53.1 |
| 1.4 | 33.5 | 44.4 | 26.8 | 56.1 | -28.6 | -48.4 | -22.4 | -56.1 |
| 1.5 | 34.0 | 46.6 | 27.0 | 58.7 | -28.7 | -50.7 | -22.6 | -58.7 |
| 1.6 | 34.3 | 48.6 | 27.2 | 61.4 | -28.9 | -52.9 | -22.7 | -61.4 |
| 1.7 | 34.5 | 50.5 | 27.4 | 63.5 | -28.9 | -55.0 | -22.7 | -63.5 |
| 1.8 | 34.8 | 52.2 | 27.7 | 65.6 | -29.0 | -56.8 | -22.8 | -65.6 |
| 1.9 | 35.1 | 53.9 | 27.8 | 67.7 | -29.2 | -58.7 | -22.9 | -67.7 |
| 2.0 | 35.4 | 55.0 | 28.0 | 69.8 | -29.2 | -60.0 | -22.9 | -69.8 |
| 2.1 | 35.6 | 56.1 | 28.1 | 71.6 | -29.3 | -61.2 | -23.0 | -71.6 |
| 2.2 | 35.8 | 57.1 | 28.2 | 73.3 | -29.5 | -62.4 | -23.0 | -73.3 |
| 2.3 | 36.1 | 57.7 | 28.3 | 74.9 | -29.5 | -63.1 | -23.1 | -74.9 |
| 2.4 | 36.3 | 58.2 | 28.3 | 76.4 | -29.6 | -63.8 | -23.2 | -76.4 |
| 2.5 | 36.5 | 58.7 | 28.4 | 77.7 | -29.7 | -64.4 | -23.2 | -77.7 |
| 2.6 | 36.7 | 59.2 | 28.5 | 78.8 | -29.8 | -65.1 | -23.3 | -78.8 |
| 2.7 | 36.8 | 59.6 | 28.6 | 79.7 | -29.9 | -65.8 | -23.3 | -79.7 |

Commands

Tables 25 and 26 provide a quick reference of available commands. Two additional Truth Tables—Table 27 on page 35, and Table 28 on page 36— provide current state/next state information.

Table 25: Truth Table 1 – Commands

CKE is HIGH for all commands shown except SELF REFRESH; All states and sequences not shown are illegal or reserved

| Name (Function) | CS# | RAS# | CAS# | WE# | Address | Notes |
|---|-----|------|------|-----|----------|-------|
| DESELECT (NOP) | H | X | X | X | X | 1 |
| NO OPERATION (NOP) | L | H | H | H | X | 1 |
| ACTIVE (select bank and activate row) | L | L | H | H | Bank/row | 2 |
| READ (select bank and column and start READ burst) | L | H | L | H | Bank/col | 3 |
| WRITE (select bank and column and start WRITE burst) | L | H | L | L | Bank/col | 3 |
| BURST TERMINATE | L | H | H | L | X | 4 |
| PRECHARGE (deactivate row in bank or banks) | L | L | H | L | Code | 5 |
| AUTO REFRESH or SELF REFRESH (enter self refresh mode) | L | L | L | H | X | 6, 7 |
| LOAD MODE REGISTER | L | L | L | L | Op-code | 8 |

- Notes:
1. Deselect and NOP are functionally interchangeable.
 2. BA0–BA1 provide bank address and A0–A_n (128Mb: $n = 11$; 256Mb and 512Mb: $n = 12$; 1Gb: $n = 13$) provide row address.
 3. BA0–BA1 provide bank address; A0–A_i provide column address, (where A_i is the most significant column address bit for a given density and configuration, see Table 2 on page 2) A10 HIGH enables the auto precharge feature (non persistent), and A10 LOW disables the auto precharge feature.
 4. Applies only to READ bursts with auto precharge disabled; this command is undefined (and should not be used) for READ bursts with auto precharge enabled and for WRITE bursts.
 5. A10 LOW: BA0–BA1 determine which bank is precharged. A10 HIGH: all banks are precharged and BA0–BA1 are “Don’t Care.”
 6. This command is AUTO REFRESH if CKE is HIGH; SELF REFRESH if CKE is LOW.
 7. Internal refresh counter controls row addressing while in self refresh mode, all inputs and I/Os are “Don’t Care” except for CKE.
 8. BA0–BA1 select either the mode register or the extended mode register (BA0 = 0, BA1 = 0 select the mode register; BA0 = 1, BA1 = 0 select extended mode register; other combinations of BA0–BA1 are reserved). A0–A_n provide the op-code to be written to the selected mode register.

Table 26: Truth Table 2 – DM Operation

Used to mask write data, provided coincident with the corresponding data

| Name (Function) | DM | DQ |
|-----------------|----|-------|
| Write enable | L | Valid |
| Write inhibit | H | X |

Table 27: Truth Table 3 – Current State Bank *n* – Command to Bank *n*

Notes: 1–6 apply to entire table; Notes appear below

| Current State | CS# | RAS# | CAS# | WE# | Command/Action | Notes |
|---------------------------------|-----|------|------|-----|---|--------|
| Any | H | X | X | X | DESELECT (NOP/continue previous operation) | |
| | L | H | H | H | NO OPERATION (NOP/continue previous operation) | |
| Idle | L | L | H | H | ACTIVE (select and activate row) | |
| | L | L | L | H | AUTO REFRESH | 7 |
| | L | L | L | L | LOAD MODE REGISTER | 7 |
| Row active | L | H | L | H | READ (select column and start READ burst) | 10 |
| | L | H | L | L | WRITE (select column and start WRITE burst) | 10 |
| | L | L | H | L | PRECHARGE (deactivate row in bank or banks) | 8 |
| Read (auto-precharge disabled) | L | H | L | H | READ (select column and start new READ burst) | 10 |
| | L | H | L | L | WRITE (select column and start WRITE burst) | 10, 12 |
| | L | L | H | L | PRECHARGE (truncate READ burst, start PRECHARGE) | 8 |
| | L | H | H | L | BURST TERMINATE | 9 |
| Write (auto-precharge disabled) | L | H | L | H | READ (select column and start READ burst) | 10, 11 |
| | L | H | L | L | WRITE (select column and start new WRITE burst) | 10 |
| | L | L | H | L | PRECHARGE (truncate WRITE burst, start PRECHARGE) | 8, 11 |

- Notes:
1. This table applies when CKE_{n-1} was HIGH and CKE_n is HIGH (see Table 30 on page 38) and after ^tXSNR has been met (if the previous state was self refresh).
 2. This table is bank-specific, except where noted (i.e., the current state is for a specific bank and the commands shown are those allowed to be issued to that bank when in that state). Exceptions are covered in the notes below.
 3. Current state definitions:
 - Idle: The bank has been precharged, and ^tRP has been met.
 - Row active: A row in the bank has been activated, and ^tRCD has been met. No data bursts/accesses and no register accesses are in progress.
 - Read: A READ burst has been initiated, with auto precharge disabled, and has not yet terminated or been terminated.
 - Write: A WRITE burst has been initiated, with auto precharge disabled, and has not yet terminated or been terminated.
 4. The following states must not be interrupted by a command issued to the same bank. COMMAND INHIBIT or NOP commands, or allowable commands to the other bank should be issued on any clock edge occurring during these states. Allowable commands to the other bank are determined by its current state and Table 27 and according to Table 28 on page 36.
 - Precharging: Starts with registration of a PRECHARGE command and ends when ^tRP is met. Once ^tRP is met, the bank will be in the idle state.
 - Row activating: Starts with registration of an ACTIVE command and ends when ^tRCD is met. Once ^tRCD is met, the bank will be in the “row active” state.
 - Read with auto-precharge enabled: Starts with registration of a READ command with auto precharge enabled and ends when ^tRP has been met. Once ^tRP is met, the bank will be in the idle state.
 - Write with auto-precharge enabled: Starts with registration of a WRITE command with auto precharge enabled and ends when ^tRP has been met. Once ^tRP is met, the bank will be in the idle state.
 5. The following states must not be interrupted by any executable command; COMMAND INHIBIT or NOP commands must be applied on each positive clock edge during these states.

- Refreshing: Starts with registration of an AUTO REFRESH command and ends when t_{RFC} is met. Once t_{RFC} is met, the DDR SDRAM will be in the all banks idle state.
 - Accessing mode register: Starts with registration of a LOAD MODE REGISTER command and ends when t_{MRD} has been met. Once t_{MRD} is met, the DDR SDRAM will be in the all banks idle state.
 - Precharging all: Starts with registration of a PRECHARGE ALL command and ends when t_{RP} is met. Once t_{RP} is met, all banks will be in the idle state.
6. All states and sequences not shown are illegal or reserved.
 7. Not bank-specific; requires that all banks are idle, and bursts are not in progress.
 8. May or may not be bank-specific; if multiple banks are to be precharged, each must be in a valid state for precharging.
 9. Not bank-specific; BURST TERMINATE affects the most recent READ burst, regardless of bank.
 10. READs or WRITEs listed in the Command/Action column include READs or WRITEs with auto precharge enabled and READs or WRITEs with auto precharge disabled.
 11. Requires appropriate DM masking.
 12. A WRITE command may be applied after the completion of the READ burst; otherwise, a BURST TERMINATE must be used to end the READ burst prior to asserting a WRITE command.

Table 28: Truth Table 4 – Current State Bank n – Command to Bank m

Notes: 1–6 apply to entire table; Notes appear below

| Current State | CS# | RAS# | CAS# | WE# | Command/Action | Notes |
|--|-----|------|------|-----|---|-------|
| Any | H | X | X | X | DESELECT (NOP/continue previous operation) | |
| | L | H | H | H | NO OPERATION (NOP/continue previous operation) | |
| Idle | X | X | X | X | Any command otherwise allowed to bank m | |
| Row activating, active, or precharging | L | L | H | H | ACTIVE (select and activate row) | |
| | L | H | L | H | READ (select column and start READ burst) | 7 |
| | L | H | L | L | WRITE (select column and start WRITE burst) | 7 |
| | L | L | H | L | PRECHARGE | |
| Read (auto-precharge disabled) | L | L | H | H | ACTIVE (select and activate row) | |
| | L | H | L | H | READ (select column and start new READ burst) | 7 |
| | L | H | L | L | WRITE (select column and start WRITE burst) | 7, 9 |
| | L | L | H | L | PRECHARGE | |
| Write (auto-precharge disabled) | L | L | H | H | ACTIVE (select and activate row) | |
| | L | H | L | H | READ (select column and start READ burst) | 7, 8 |
| | L | H | L | L | WRITE (select column and start new WRITE burst) | 7 |
| | L | L | H | L | PRECHARGE | |
| Read (with auto-precharge) | L | L | H | H | ACTIVE (select and activate row) | |
| | L | H | L | H | READ (select column and start new READ burst) | 7 |
| | L | H | L | L | WRITE (select column and start WRITE burst) | 7, 9 |
| | L | L | H | L | PRECHARGE | |
| Write (with auto-precharge) | L | L | H | H | ACTIVE (select and activate row) | |
| | L | H | L | H | READ (select column and start READ burst) | 7 |
| | L | H | L | L | WRITE (select column and start new WRITE burst) | 7 |
| | L | L | H | L | PRECHARGE | |

Notes: 1. This table applies when CKE_{n-1} was HIGH and CKE_n is HIGH (see Table 30 on page 38) and after t_{XSNR} has been met (if the previous state was self refresh).

2. This table describes alternate bank operation, except where noted (i.e., the current state is for bank n , and the commands shown are those allowed to be issued to bank m , assuming that bank m is in such a state that the given command is allowable). Exceptions are covered in the notes below.
3. Current state definitions:
 - Idle: The bank has been precharged, and t_{RP} has been met.
 - Row active: A row in the bank has been activated, and t_{RCD} has been met. No data bursts/accesses and no register accesses are in progress.
 - Read: A READ burst has been initiated, with auto precharge disabled, and has not yet terminated or been terminated.
 - Write: A WRITE burst has been initiated, with auto precharge disabled, and has not yet terminated or been terminated.
 - Read with auto precharge enabled: See note 3a below.
 - Write with auto precharge enabled: See note 3a below.
 - a. The read with auto precharge enabled or write with auto precharge enabled states can each be broken into two parts: the access period and the precharge period. For read with auto precharge, the precharge period is defined as if the same burst was executed with auto precharge disabled and then followed with the earliest possible PRECHARGE command that still accesses all of the data in the burst. For write with auto precharge, the precharge period begins when t_{WR} ends, with t_{WR} measured as if auto precharge was disabled. The access period starts with registration of the command and ends where the precharge period (or t_{RP}) begins. This device supports concurrent auto precharge such that when a read with auto precharge is enabled or a write with auto precharge is enabled, any command to other banks is allowed, as long as that command does not interrupt the read or write data transfer already in process. In either case, all other related limitations apply (e.g., contention between read data and write data must be avoided).
 - b. The minimum delay from a READ or WRITE command with auto precharge enabled, to a command to a different bank is summarized in Table 29.

Table 29: Command Delays
 CL_{RU} = CL rounded up to the next integer

| From Command | To Command | Minimum Delay (with Concurrent Auto Precharge) |
|---------------------------|------------------------------------|---|
| WRITE with auto precharge | READ or READ with auto precharge | $[1 + (BL/2)] \times t_{CK} + t_{WTR}$ |
| | WRITE or WRITE with auto precharge | $(BL/2) \times t_{CK}$ |
| | PRECHARGE | $1 t_{CK}$ |
| | ACTIVE | $1 t_{CK}$ |
| READ with auto precharge | READ or READ with auto precharge | $(BL/2) \times t_{CK}$ |
| | WRITE or WRITE with auto precharge | $[CL_{RU} + (BL/2)] \times t_{CK}$ |
| | PRECHARGE | $1 t_{CK}$ |
| | ACTIVE | $1 t_{CK}$ |

4. AUTO REFRESH and LOAD MODE REGISTER commands may only be issued when all banks are idle.
5. A BURST TERMINATE command cannot be issued to another bank; it applies to the bank represented by the current state only.
6. All states and sequences not shown are illegal or reserved.
7. READs or WRITEs listed in the "Command/Action" column include READs or WRITEs with auto precharge enabled and READs or WRITEs with auto precharge disabled.
8. Requires appropriate DM masking.

9. A WRITE command may be applied after the completion of the READ burst; otherwise, a BURST TERMINATE must be used to end the READ burst prior to asserting a WRITE command.

Table 30: Truth Table 5 – CKE

Notes 1–6 apply to entire table; Notes appear below

| CKE _{n-1} | CKE _n | Current State | Command _n | Action _n | Notes |
|--------------------|------------------|----------------|-------------------------|----------------------------|-------|
| L | L | Power-down | X | Maintain power-down | |
| | | Self refresh | X | Maintain self refresh | |
| L | H | Power-down | DESELECT or NOP | Exit power-down | |
| | | Self refresh | DESELECT or NOP | Exit self refresh | 7 |
| H | L | All banks idle | DESELECT or NOP | Precharge power-down entry | |
| | | Bank(s) active | DESELECT or NOP | Active power-down entry | |
| | | All banks idle | AUTO REFRESH | Self refresh entry | |
| H | H | | See Table 25 on page 34 | | |

- Notes:
1. CKE_n is the logic state of CKE at clock edge *n*; CKE_{n-1} was the state of CKE at the previous clock edge.
 2. Current state is the state of the DDR SDRAM immediately prior to clock edge *n*.
 3. COMMAND_n is the command registered at clock edge *n*, and ACTION_n is a result of COMMAND_n.
 4. All states and sequences not shown are illegal or reserved.
 5. CKE must not drop LOW during a column access. For a READ, this means CKE must stay HIGH until after the read postamble time (^tRPST); for a WRITE, CKE must stay HIGH until the write recovery time (^tWR) has been met.
 6. Once initialized, including during self refresh mode, VREF must be powered within the specified range.
 7. Upon exit of the self refresh mode, the DLL is automatically enabled. A minimum of 200 clock cycles is needed before applying a READ command for the DLL to lock. DESELECT or NOP commands should be issued on any clock edges occurring during the ^tXSNR period.

DESELECT

The DESELECT function (CS# HIGH) prevents new commands from being executed by the DDR SDRAM. The DDR SDRAM is effectively deselected. Operations already in progress are not affected.

NO OPERATION (NOP)

The NO OPERATION (NOP) command is used to instruct the selected DDR SDRAM to perform a NOP (CS# is LOW with RAS#, CAS#, and WE# are HIGH). This prevents unwanted commands from being registered during idle or wait states. Operations already in progress are not affected.

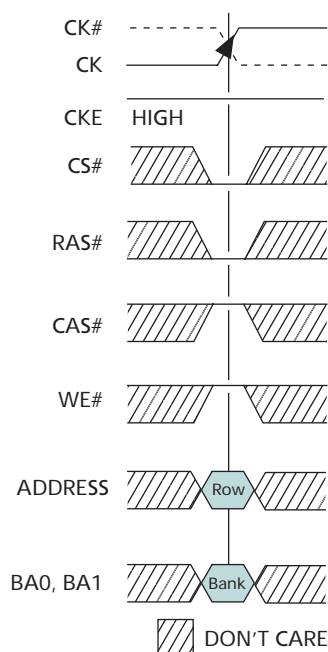
LOAD MODE REGISTER (LMR)

The mode registers are loaded via inputs A0–A_n (see "REGISTER DEFINITION" on page 45). The LOAD MODE REGISTER command can only be issued when all banks are idle, and a subsequent executable command cannot be issued until ^tMRD is met.

ACTIVE (ACT)

The ACTIVE command is used to open (or activate) a row in a particular bank for a subsequent access, like a read or a write, as shown in Figure 15. The value on the BA0, BA1 inputs selects the bank, and the address provided on inputs A0–An selects the row.

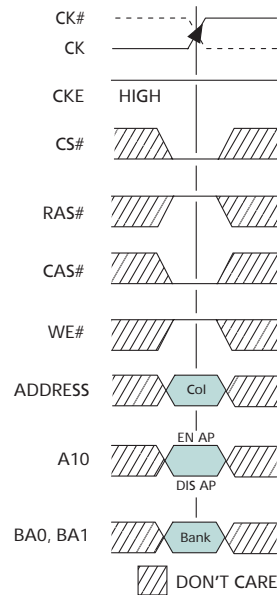
Figure 15: Activating a Specific Row in a Specific Bank



READ

The READ command is used to initiate a burst read access to an active row, as shown in Figure 16 on page 40. The value on the BA0, BA1 inputs selects the bank, and the address provided on inputs A0–Ai (where Ai is the most significant column address bit for a given density and configuration, see Table 2 on page 2) selects the starting column location.

Figure 16: READ Command

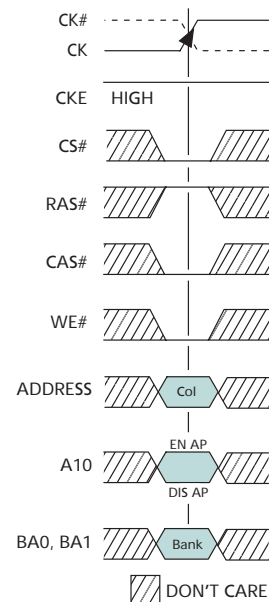


Note: EN AP = enable auto precharge; DIS AP = disable auto precharge.

WRITE

The WRITE command is used to initiate a burst write access to an active row as shown in Figure 17. The value on the BA0, BA1 inputs selects the bank, and the address provided on inputs A0–Ai (where Ai is the most significant column address bit for a given density and configuration, see Table 2 on page 2) selects the starting column location.

Figure 17: WRITE Command

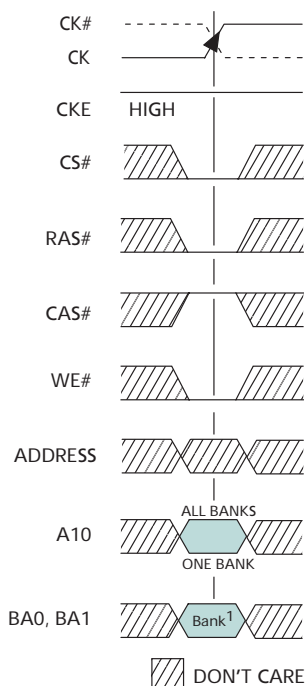


Note: EN AP = enable auto precharge; and DIS AP = disable auto precharge.

PRECHARGE (PRE)

The PRECHARGE command is used to deactivate the open row in a particular bank or the open row in all banks as shown in Figure 18. The value on the BA0, BA1 inputs selects the bank, and the A10 input selects whether a single bank is precharged or whether all banks are precharged.

Figure 18: PRECHARGE Command



Notes: 1. If A10 is HIGH, bank address becomes "Don't Care".

BURST TERMINATE (BST)

The BURST TERMINATE command is used to truncate READ bursts (with auto precharge disabled). The most recently registered READ command prior to the BURST TERMINATE command will be truncated, as shown in "Operations" on page 42. The open page from which the READ burst was terminated remains open.

AUTO REFRESH (AR)

AUTO REFRESH is used during normal operation of the DDR SDRAM and is analogous to CAS#-before-RAS# (CBR) refresh in FPM/EDO DRAMs. This command is nonpersistent, so it must be issued each time a refresh is required. All banks must be idle before an AUTO REFRESH command is issued.

SELF REFRESH

The SELF REFRESH command can be used to retain data in the DDR SDRAM, even if the rest of the system is powered down. The SELF REFRESH command is initiated like an AUTO REFRESH command except CKE is disabled (LOW).

Operations

INITIALIZATION

Prior to normal operation, DDR SDRAMs must be powered up and initialized in a predefined manner. Operational procedures, other than those specified, may result in undefined operation.

To ensure device operation, the DRAM must be initialized as described in the following steps:

1. Simultaneously apply power to VDD and VDDQ.
2. Apply VREF and then VTT power. VTT must be applied after VDDQ to avoid device latch-up, which may cause permanent damage to the device. Except for CKE, inputs are not recognized as valid until after VREF is applied.
3. Assert and hold CKE at a LVC MOS logic LOW. Maintaining an LVC MOS LOW level on CKE during power-up is required to ensure that the DQ and DQS outputs will be in the High-Z state, where they will remain until driven in normal operation (by a read access).
4. Provide stable clock signals.
5. Wait at least 200 μ s.
6. Bring CKE HIGH, and provide at least one NOP or DESELECT command. At this point, the CKE input changes from a LVC MOS input to a SSTL_2 input only and will remain a SSTL_2 input unless a power cycle occurs.
7. Perform a PRECHARGE ALL command.
8. Wait at least t_{RP} time; during this time NOPs or DESELECT commands must be given.
9. Using the LMR command, program the extended mode register (E0 = 0 to enable the DLL and E1 = 0 for normal drive; or E1 = 1 for reduced drive and E2–En must be set to 0 [where n = most significant bit]).
10. Wait at least t_{MRD} time; only NOPs or DESELECT commands are allowed.
11. Using the LMR command, program the mode register to set operating parameters and to reset the DLL. At least 200 clock cycles are required between a DLL reset and any READ command.
12. Wait at least t_{MRD} time; only NOPs or DESELECT commands are allowed.
13. Issue a PRECHARGE ALL command.
14. Wait at least t_{RP} time; only NOPs or DESELECT commands are allowed.
15. Issue an AUTO REFRESH command. This may be moved prior to step 13.
16. Wait at least t_{RFC} time; only NOPs or DESELECT commands are allowed.
17. Issue an AUTO REFRESH command. This may be moved prior to step 13.
18. Wait at least t_{RFC} time; only NOPs or DESELECT commands are allowed.
19. Although not required by the Micron device, JEDEC requires an LMR command to clear the DLL bit (set M8 = 0). If an LMR command is issued, the same operating parameters should be utilized as in step 11.
20. Wait at least t_{MRD} time; only NOPs or DESELECT commands are allowed.
21. At this point the DRAM is ready for any valid command. At least 200 clock cycles with CKE HIGH are required between step 11 (DLL RESET) and any READ command.

Figure 19: INITIALIZATION Flow Diagram

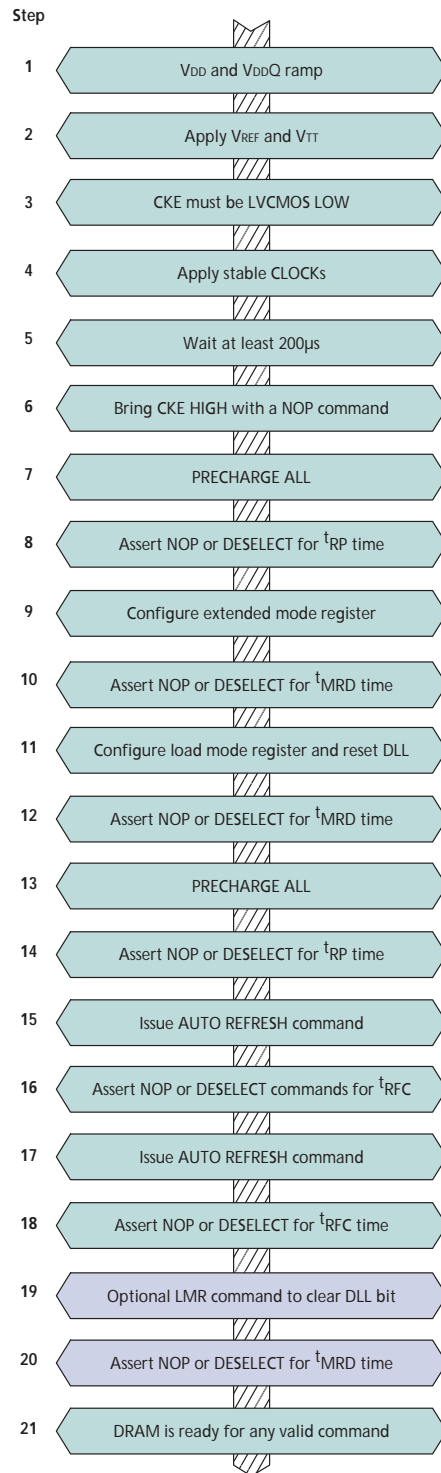
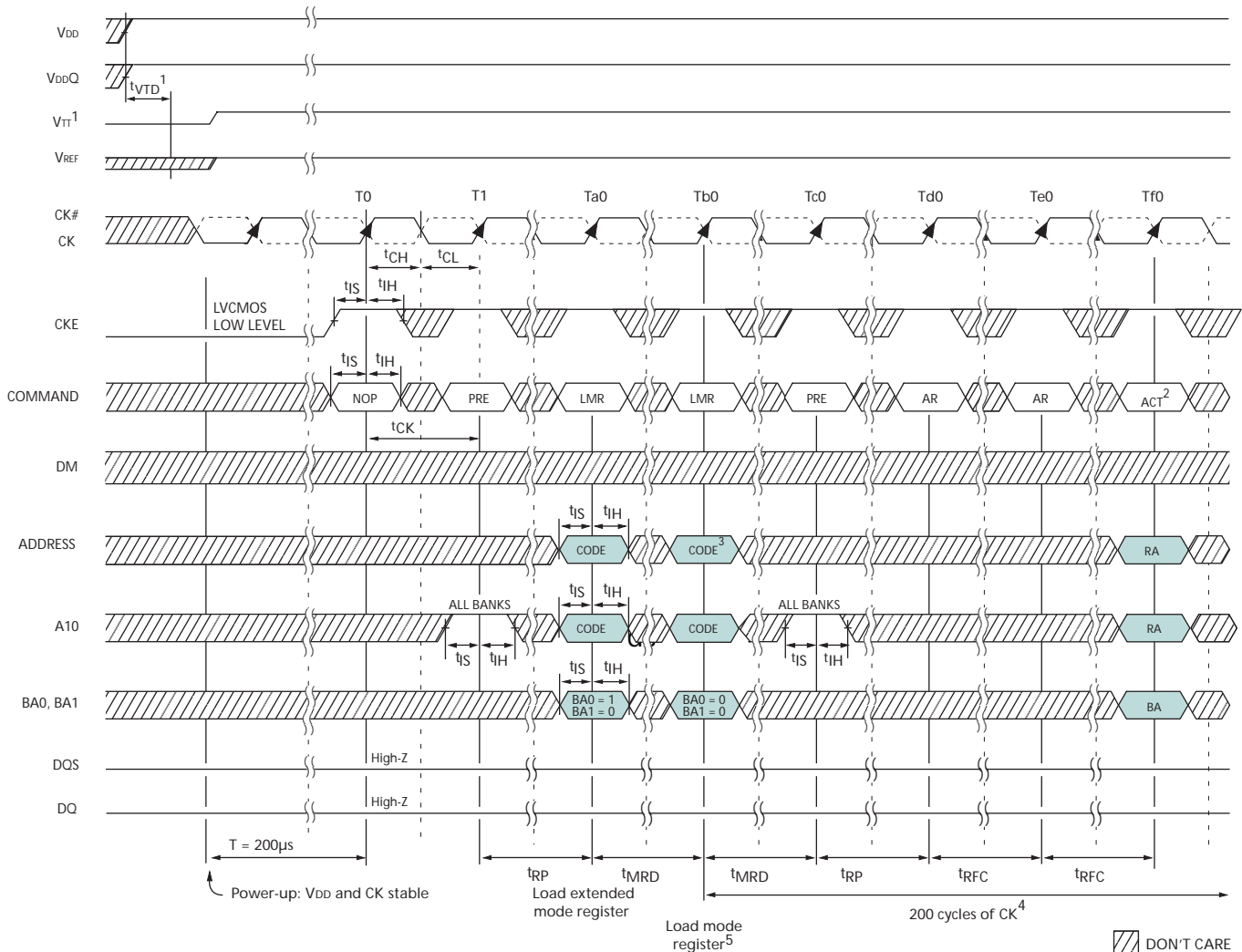


Figure 20: INITIALIZATION Timing Diagram


- Notes:
1. VTT is not applied directly to the device; however, $t_{VTD} \geq 0$ to avoid device latch-up. VDDQ, VTT, and VREF $\leq VDD + 0.3V$. Alternatively, VTT may be 1.35V maximum during power up, even if VDD/VDDQ are 0V, provided a minimum of 42 ohms of series resistance is used between the VTT supply and the input pin. Once initialized, VREF must always be powered within the specified range.
 2. Although not required by the Micron device, JEDEC specifies issuing another LMR command (A8 = 0) prior to activating any bank. If another LMR command is issued, the same, previously issued operating parameters must be used.
 3. The two AUTO REFRESH commands at Td0 and Te0 may be applied following the LOAD MODE REGISTER (LMR) command at Ta0.
 4. t_{MRD} is required before any command can be applied (during MRD time only NOPs or DESELECTs are allowed), and 200 cycles of CK are required before a READ command can be issued.
 5. While programming the operating parameters, reset the DLL with A8 = 1.

REGISTER DEFINITION

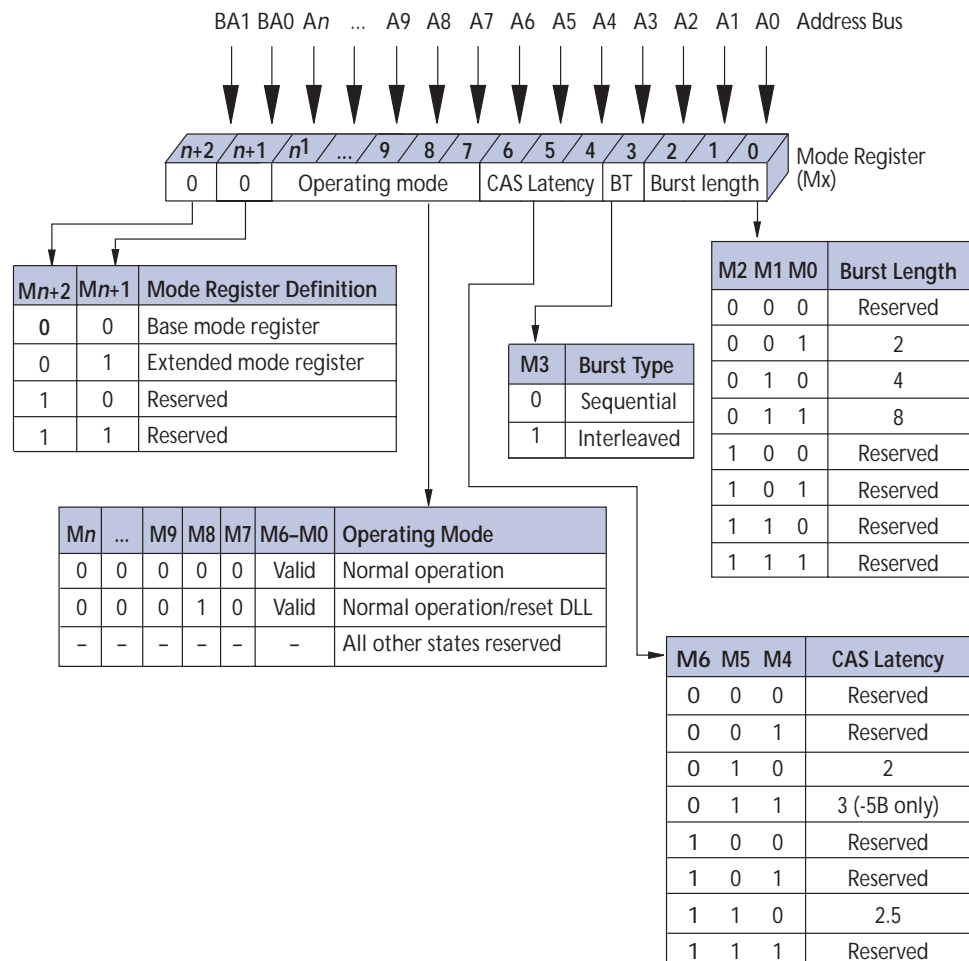
Mode Register

The mode register is used to define the specific DDR SDRAM mode of operation. This definition includes the selection of a burst length, a burst type, a CAS latency, and an operating mode, as shown in Figure 21. The mode register is programmed via the LMR command (with BA0 = 0 and BA1 = 0) and will retain the stored information until it is programmed again or until the device loses power (except for bit A8, which is self-clearing).

Reprogramming the mode register will not alter the contents of the memory, provided it is performed correctly. The mode register must be loaded (reloaded) when all banks are idle and no bursts are in progress, and the controller must wait the specified time before initiating the subsequent operation. Violating either of these requirements will result in unspecified operation.

Mode register bits A0–A2 specify the burst length, A3 specifies the type of burst (sequential or interleaved), A4–A6 specify the CAS latency, and A7–An specify the operating mode.

Figure 21: Mode Register Definition



Notes: 1. n is the most significant row address bit from Table 2 on page 2.

Burst Length (BL)

Read and write accesses to the DDR SDRAM are burst oriented, with the burst length being programmable for both READ and WRITE bursts, as shown in Figure 21 on page 45. The burst length determines the maximum number of column locations that can be accessed for a given READ or WRITE command. BL = 2, BL = 4, or BL = 8 locations are available for both the sequential and the interleaved burst types. Reserved states should not be used, as unknown operation or incompatibility with future versions may result.

When a READ or WRITE command is issued, a block of columns equal to the burst length is effectively selected. All accesses for that burst take place within this block—meaning that the burst will wrap within the block if a boundary is reached. The block is uniquely selected by A1–Ai when BL = 2, by A2–Ai when BL = 4, and by A3–Ai when BL = 8 (where Ai is the most significant column address bit for a given configuration). The remaining (least significant) address bit(s) is (are) used to select the starting location within the block. For example: for BL = 8, A3–Ai select the eight-data-element block; A0–A2 select the first access within the block.

Burst Type

Accesses within a given burst may be programmed to be either sequential or interleaved; this is referred to as the burst type and is selected via bit M3.

The ordering of accesses within a burst is determined by the burst length, the burst type, and the starting column address, as shown in Table 31.

Table 31: Burst Definition

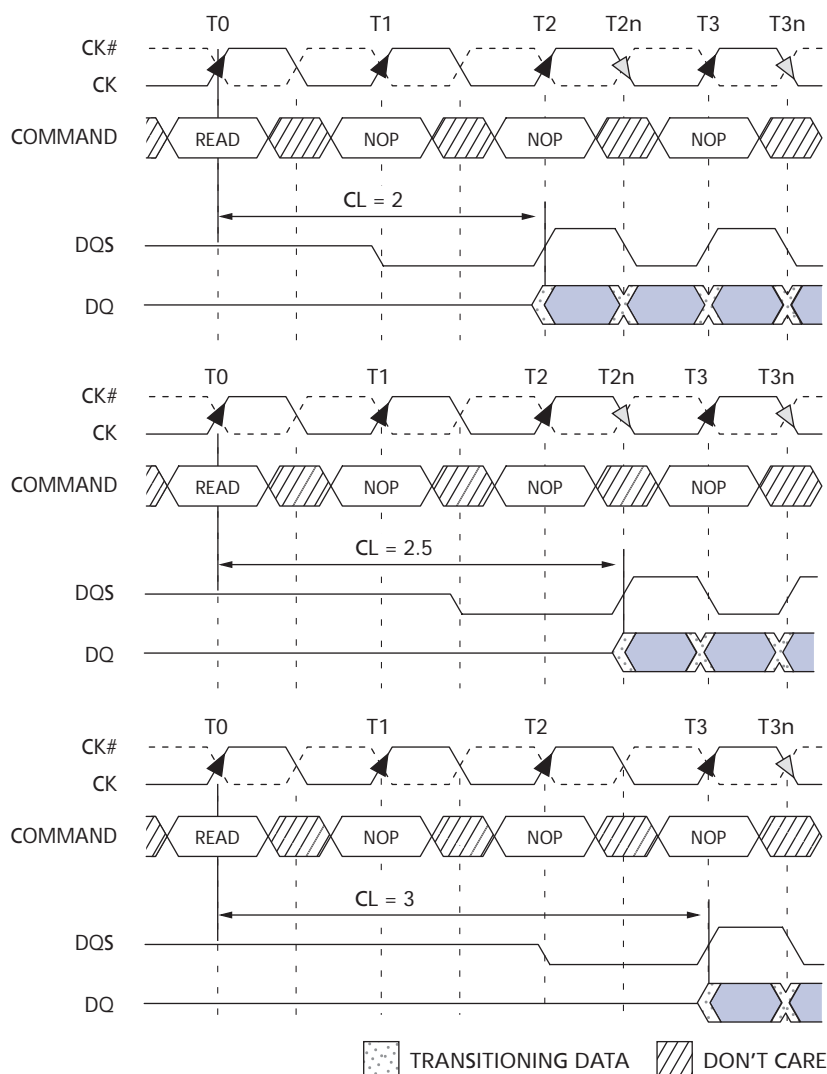
| Burst Length | Starting Column Address | | | Order of Accesses Within a Burst | |
|--------------|-------------------------|-----------|-----------|----------------------------------|--------------------|
| | | | | Type = Sequential | Type = Interleaved |
| 2 | – | – | A0 | – | – |
| | – | – | 0 | 0-1 | 0-1 |
| | – | – | 1 | 1-0 | 1-0 |
| 4 | – | A1 | A0 | – | – |
| | – | 0 | 0 | 0-1-2-3 | 0-1-2-3 |
| | – | 0 | 1 | 1-2-3-0 | 1-0-3-2 |
| | – | 1 | 0 | 2-3-0-1 | 2-3-0-1 |
| | – | 1 | 1 | 3-0-1-2 | 3-2-1-0 |
| 8 | A2 | A1 | A0 | – | – |
| | 0 | 0 | 0 | 0-1-2-3-4-5-6-7 | 0-1-2-3-4-5-6-7 |
| | 0 | 0 | 1 | 1-2-3-4-5-6-7-0 | 1-0-3-2-5-4-7-6 |
| | 0 | 1 | 0 | 2-3-4-5-6-7-0-1 | 2-3-0-1-6-7-4-5 |
| | 0 | 1 | 1 | 3-4-5-6-7-0-1-2 | 3-2-1-0-7-6-5-4 |
| | 1 | 0 | 0 | 4-5-6-7-0-1-2-3 | 4-5-6-7-0-1-2-3 |
| | 1 | 0 | 1 | 5-6-7-0-1-2-3-4 | 5-4-7-6-1-0-3-2 |
| | 1 | 1 | 0 | 6-7-0-1-2-3-4-5 | 6-7-4-5-2-3-0-1 |
| | 1 | 1 | 1 | 7-0-1-2-3-4-5-6 | 7-6-5-4-3-2-1-0 |

CAS Latency (CL)

The CL is the delay, in clock cycles, between the registration of a READ command and the availability of the first bit of output data. The latency can be set to 2, 2.5, or 3 (-5B only) clocks, as shown in Figure 22. Reserved states should not be used, as unknown operation or incompatibility with future versions may result.

If a READ command is registered at clock edge n , and the latency is m clocks, the data will be available nominally coincident with clock edge $n + m$. Table 32 on page 48 indicates the operating frequencies at which each CL setting can be used.

Figure 22: CAS Latency



Note: BL = 4 in the cases shown; shown with nominal t_{AC} , t_{DQCK} , and t_{DQSQ} .

Table 32: CAS Latency

| Speed | Allowable Operating Clock Frequency (MHz) | | |
|--------|---|----------------------|-----------------------|
| | CL = 2 | CL = 2.5 | CL = 3 |
| -5B | $75 \leq f \leq 133$ | $75 \leq f \leq 167$ | $133 \leq f \leq 200$ |
| -6/-6T | $75 \leq f \leq 133$ | $75 \leq f \leq 167$ | – |
| -75E | $75 \leq f \leq 133$ | $75 \leq f \leq 133$ | – |
| -75Z | $75 \leq f \leq 133$ | $75 \leq f \leq 133$ | – |
| -75 | $75 \leq f \leq 100$ | $75 \leq f \leq 133$ | – |

Operating Mode

The normal operating mode is selected by issuing a LOAD MODE REGISTER command with bits A7–An each set to zero and bits A0–A6 set to the desired values. A DLL reset is initiated by issuing an LMR command with bits A7 and A9–An each set to zero, bit A8 set to one, and bits A0–A6 set to the desired values. Although not required by the Micron device, JEDEC specifications recommend that a LOAD MODE REGISTER command resetting the DLL should always be followed by a LOAD MODE REGISTER command selecting normal operating mode.

All other combinations of values for A7–An are reserved for future use and/or test modes. Test modes and reserved states should not be used, as unknown operation or incompatibility with future versions may result.

Extended Mode Register

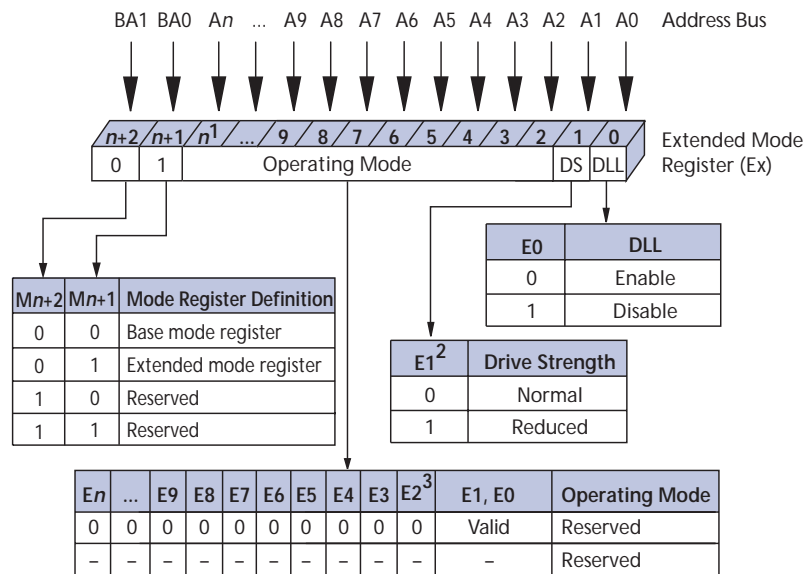
The extended mode register controls functions beyond those controlled by the mode register; these additional functions are DLL enable/disable and output drive strength. These functions are controlled via the bits shown in Figure 23 on page 49. The extended mode register is programmed via the LOAD MODE REGISTER command to the mode register (with BA0 = 1 and BA1 = 0) and will retain the stored information until it is programmed again or until the device loses power. The enabling of the DLL should always be followed by an LMR command to the mode register (BA0/BA1 = 0) to reset the DLL. The extended mode register must be loaded when all banks are idle and no bursts are in progress, and the controller must wait the specified time before initiating any subsequent operation. Violating either requirement could result in an unspecified operation.

Output Drive Strength

The normal drive strength for all outputs is specified to be SSTL_2, Class II. The x16 supports a programmable option for reduced drive. This option is intended for the support of the lighter load and/or point-to-point environments. The selection of the reduced drive strength will alter the DQ and DQS pins from SSTL_2, Class II drive strength to a reduced drive strength, which is approximately 54 percent of the SSTL_2, Class II drive strength.

DLL Enable/Disable

When the part is running without the DLL enabled, device functionality may be altered. The DLL must be enabled for normal operation. DLL enable is required during power-up initialization and upon returning to normal operation after having disabled the DLL for the purpose of debug or evaluation (when the device exits self refresh mode, the DLL is enabled automatically). Anytime the DLL is enabled, 200 clock cycles with CKE HIGH must occur before a READ command can be issued.

Figure 23: Extended Mode Register Definition


- Notes:
1. n is the most significant row address bit from Table 2 on page 2.
 2. The reduced drive strength option is available only on the x16 version. The reduced drive strength option is not supported on the x4 and x8 versions; contact Micron for future support of this feature.
 3. The QFC# option is not supported.

ACTIVE

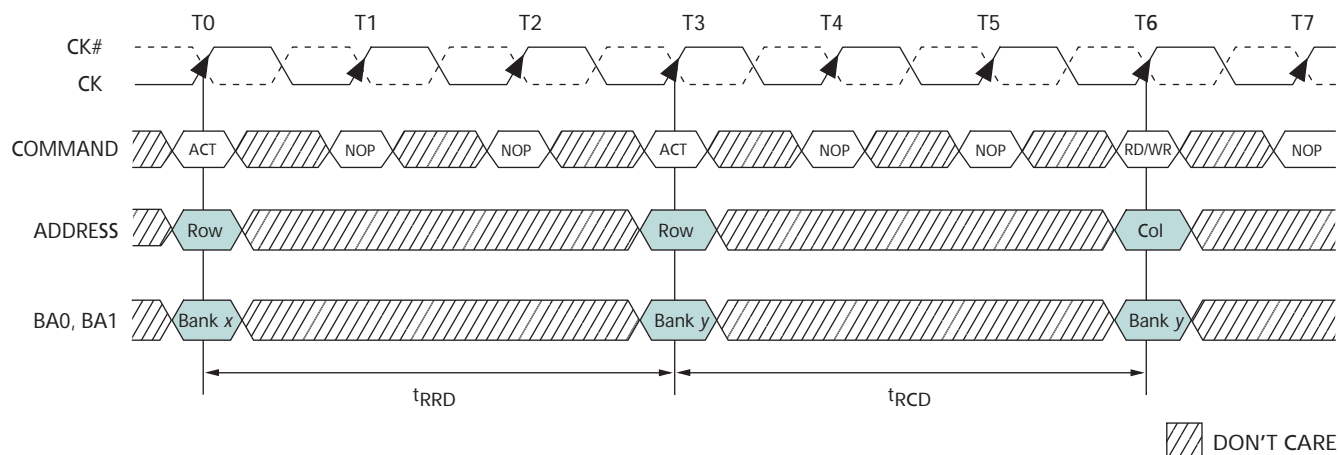
After a row is opened with an ACTIVE command, a READ or WRITE command may be issued to that row, subject to the t_{RCD} specification. t_{RCD} (MIN) should be divided by the clock period and rounded up to the next whole number to determine the earliest clock edge after the ACTIVE command on which a READ or WRITE command can be entered. For example, a t_{RCD} specification of 20ns with a 133 MHz clock (7.5ns period) results in 2.7 clocks rounded to 3. This is reflected in Figure 24 on page 50, which covers any case where $2 < t_{RCD} \text{ (MIN)} / t_{CK} \leq 3$ (Figure 24 also shows the same case for t_{RRD} ; the same procedure is used to convert other specification limits from time units to clock cycles).

A row remains active (or open) for accesses until a PRECHARGE command is issued to that bank. A PRECHARGE command must be issued before opening a different row in the same bank.

A subsequent ACTIVE command to a different row in the same bank can only be issued after the previous active row has been "closed" (precharged). The minimum time interval between successive ACTIVE commands to the same bank is defined by t_{RC} .

A subsequent ACTIVE command to another bank can be issued while the first bank is being accessed, which results in a reduction of total row-access overhead. The minimum time interval between successive ACTIVE commands to different banks is defined by t_{RRD} .

Figure 24: Example: Meeting t_{RCD} (t_{RRD}) MIN When $2 < t_{RCD}$ (t_{RRD}) MIN/ $t_{CK} \leq 3$



READ

During the READ command, the value on input A10 determines whether or not auto precharge is used. If auto precharge is selected, the row being accessed will be precharged at the end of the READ burst; if auto precharge is not selected, the row will remain open for subsequent accesses.

Note: For the READ commands used in the following illustrations, auto precharge is disabled.

During READ bursts, the valid data-out element from the starting column address will be available following the CL after the READ command. Each subsequent data-out element will be valid nominally at the next positive or negative clock edge (i.e., at the next crossing of CK and CK#). Figure 25 on page 52 shows the general timing for each possible CL setting. DQS is driven by the DDR SDRAM along with output data. The initial LOW state on DQS is known as the read preamble; the LOW state coincident with the last data-out element is known as the read postamble.

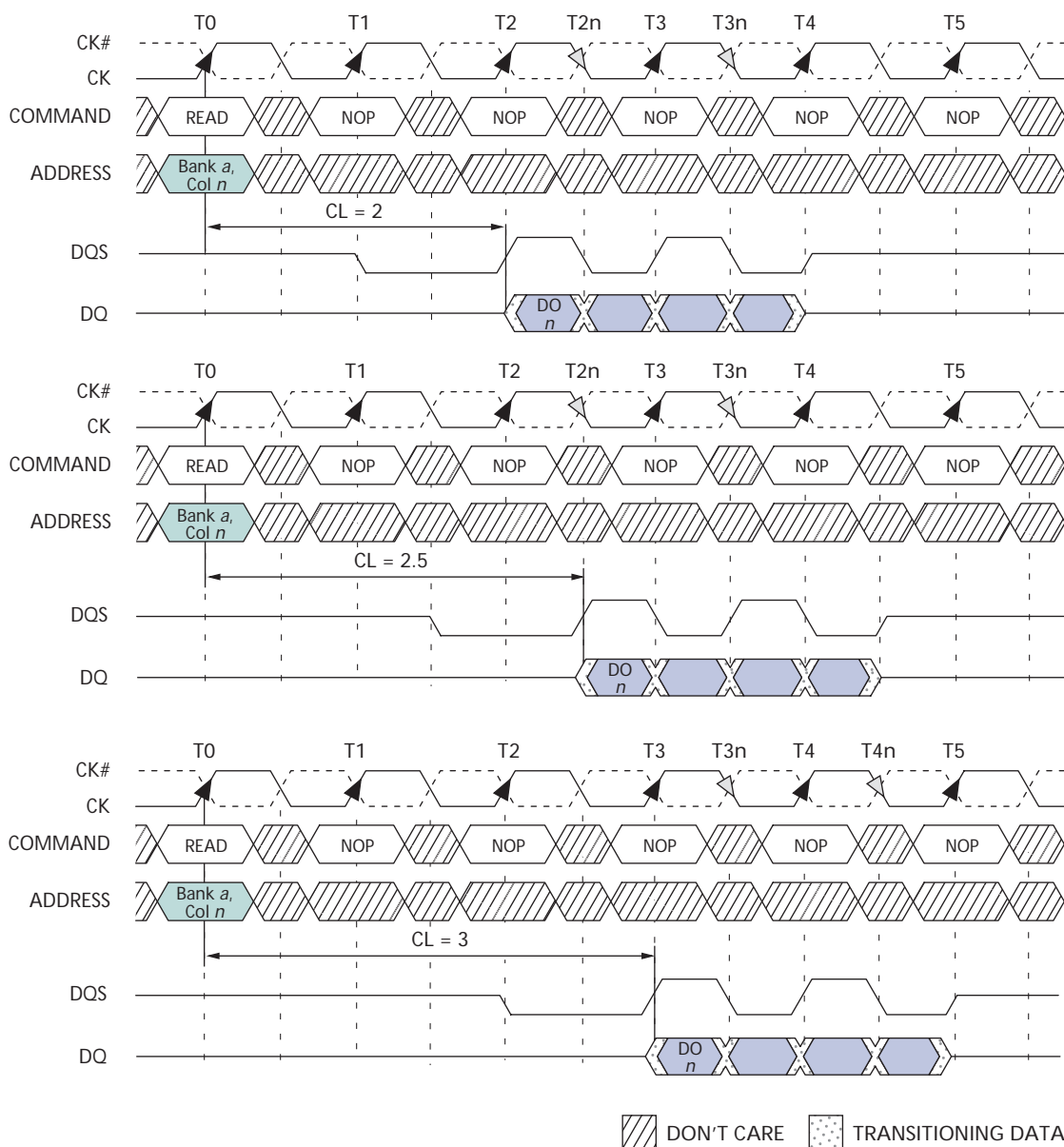
Upon completion of a burst, assuming no other commands have been initiated, the DQs will go High-Z. Detailed explanations of t_{DQSQ} (valid data-out skew), t_{QH} (data-out window hold), and the valid data window are depicted in Figure 33 on page 60 and Figure 34 on page 61. Detailed explanations of t_{DQSCK} (DQS transition skew to CK) and t_{AC} (data-out transition skew to CK) are depicted in Figure 35 on page 62.

Data from any READ burst may be concatenated or truncated with data from a subsequent READ command. In either case, a continuous flow of data can be maintained. The first data element from the new burst follows either the last element of a completed burst or the last desired data element of a longer burst which is being truncated. The new READ command should be issued x cycles after the first READ command, where x equals the number of desired data element pairs (pairs are required by the $2n$ -prefetch architecture). This is shown in Figure 26 on page 53. A READ command can be initiated on any clock cycle following a previous READ command. Nonconsecutive read data is illustrated in Figure 27 on page 54. Full-speed random read accesses within a page (or pages) can be performed, as shown in Figure 28 on page 55.

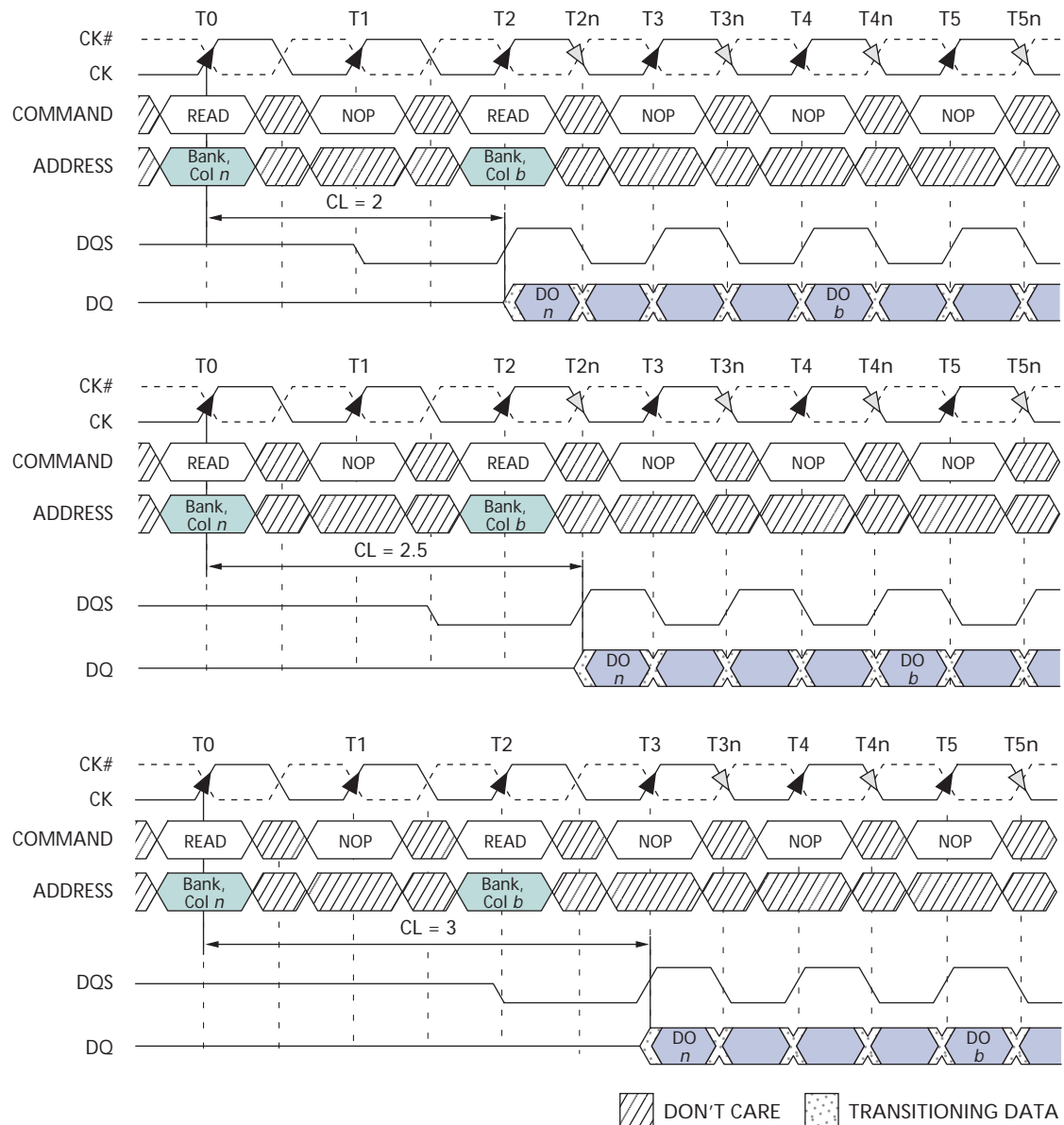
Data from any READ burst may be truncated with a BURST TERMINATE command, as shown in Figure 29 on page 56. The BURST TERMINATE latency is equal to the CL, that is, the BURST TERMINATE command should be issued x cycles after the READ command where x equals the number of desired data element pairs (pairs are required by the $2n$ -prefetch architecture).

Data from any READ burst must be completed or truncated before a subsequent WRITE command can be issued. If truncation is necessary, the BURST TERMINATE command must be used, as shown in Figure 30 on page 57. The t_{DQSS} (NOM) case is shown; the t_{DQSS} (MAX) case has a longer bus idle time. (t_{DQSS} [MIN] and t_{DQSS} [MAX] are defined in the section on WRITES.) A READ burst may be followed by, or truncated with, a PRECHARGE command to the same bank provided that auto precharge was not activated.

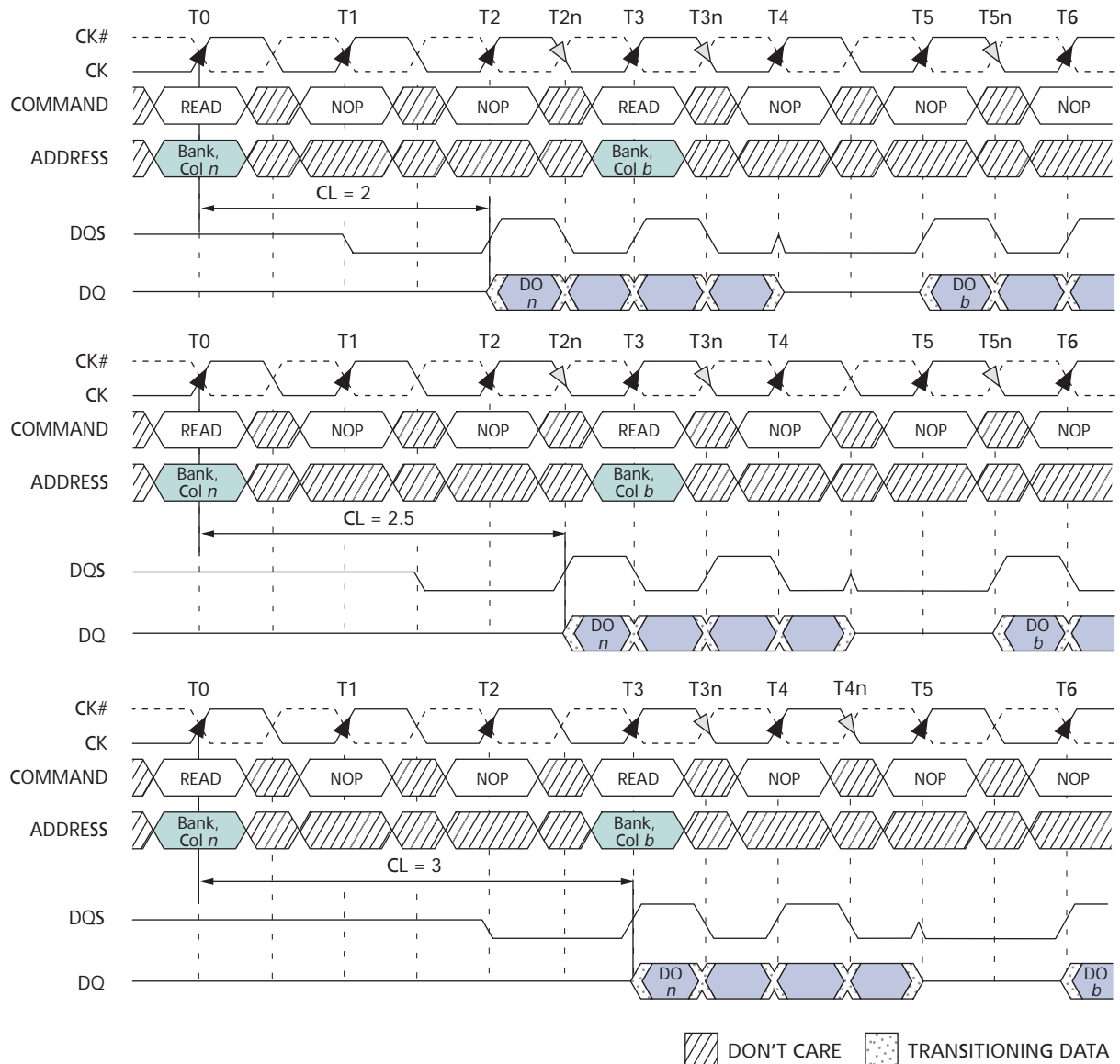
The PRECHARGE command should be issued x cycles after the READ command, where x equals the number of desired data element pairs (pairs are required by the $2n$ -prefetch architecture). This is shown in Figure 31 on page 58. Following the PRECHARGE command, a subsequent command to the same bank cannot be issued until both t_{RAS} and t_{RP} have been met. Part of the row precharge time is hidden during the access of the last data elements.

Figure 25: READ Burst


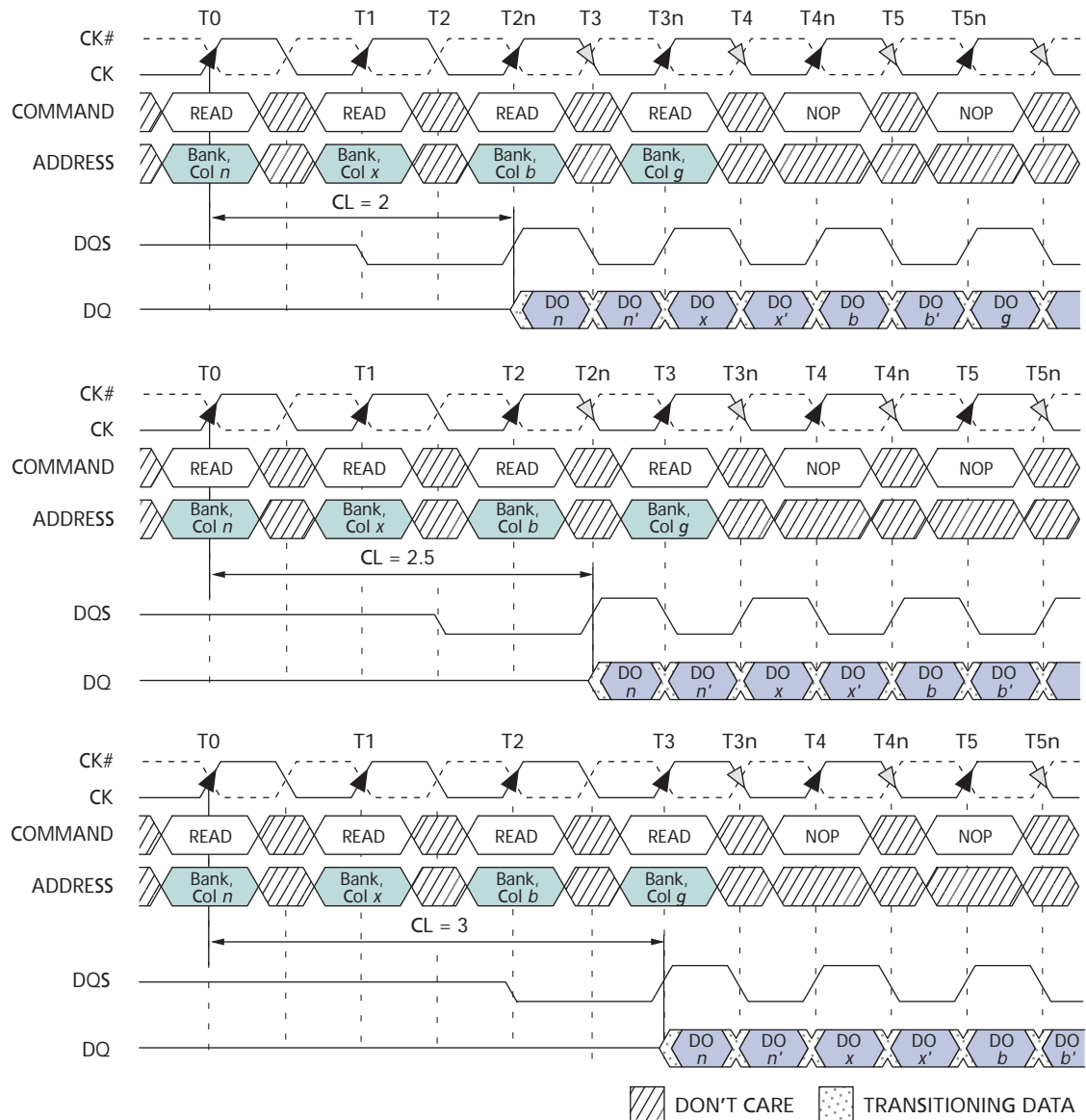
- Notes:
1. DO n = data-out from column n .
 2. BL = 4.
 3. Three subsequent elements of data-out appear in the programmed order following DO n .
 4. Shown with nominal t_{AC} , t_{DQSK} , and t_{DQSQ} .

Figure 26: Consecutive READ Bursts


- Notes:
1. DO *n* (or *b*) = data-out from column *n* (or column *b*).
 2. BL = 4 or BL = 8 (if BL = 4, the bursts are concatenated; if BL = 8, the second burst interrupts the first).
 3. Three subsequent elements of data-out appear in the programmed order following DO *n*.
 4. Three (or seven) subsequent elements of data-out appear in the programmed order following DO *b*.
 5. Shown with nominal t_{AC} , t_{DQSC} , and t_{DQSQ} .
 6. Example applies only when READ commands are issued to same device.

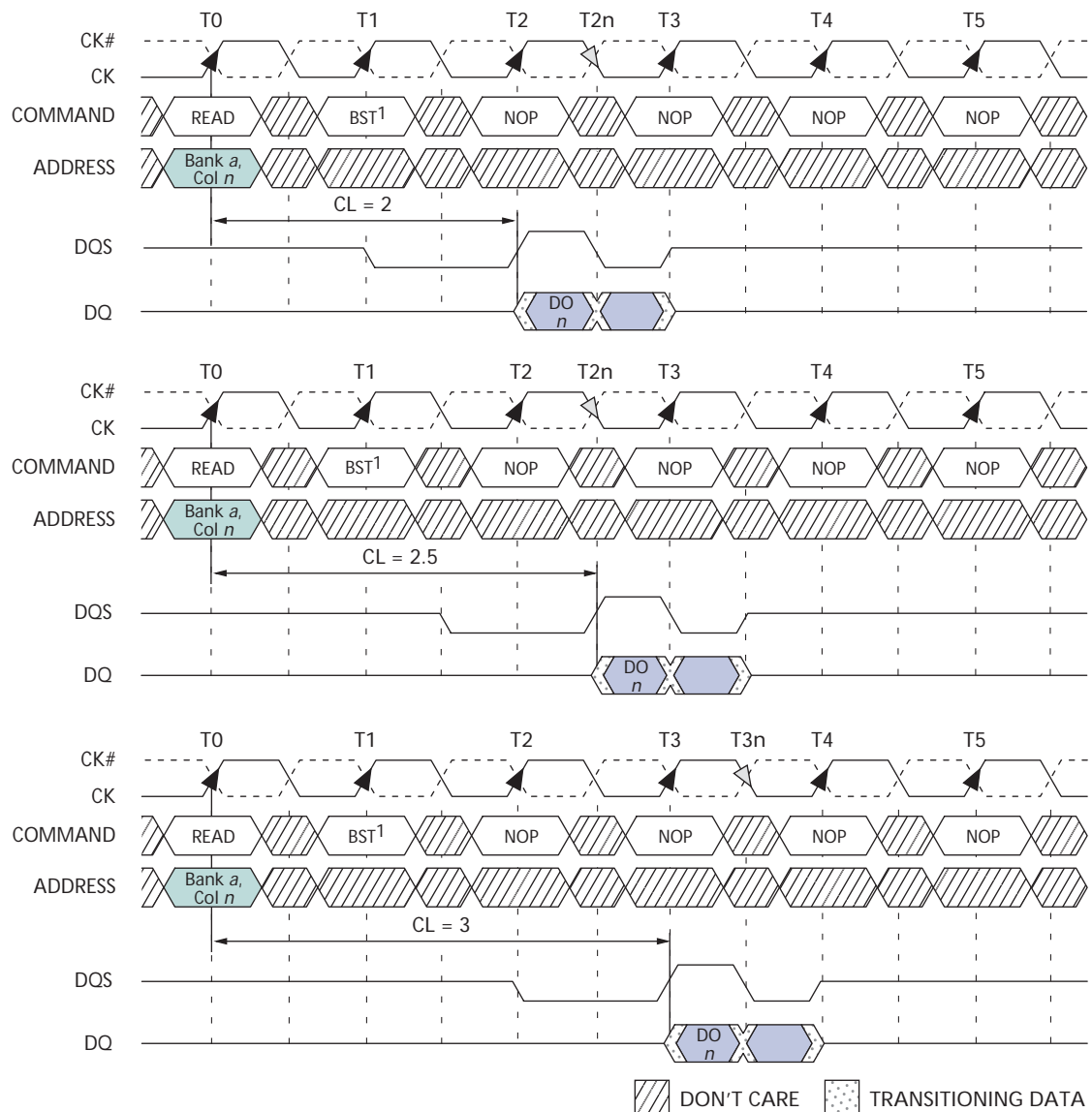
Figure 27: Nonconsecutive READ Bursts


- Notes:
1. DO *n* (or *b*) = data-out from column *n* (or column *b*).
 2. BL = 4 or BL = 8 (if BL = 4, the bursts are concatenated; if BL = 8, the second burst interrupts the first).
 3. Three subsequent elements of data-out appear in the programmed order following DO *n*.
 4. Three (or seven) subsequent elements of data-out appear in the programmed order following DO *b*.
 5. Shown with nominal t_{AC} , t_{DQSK} , and t_{DQSQ} .

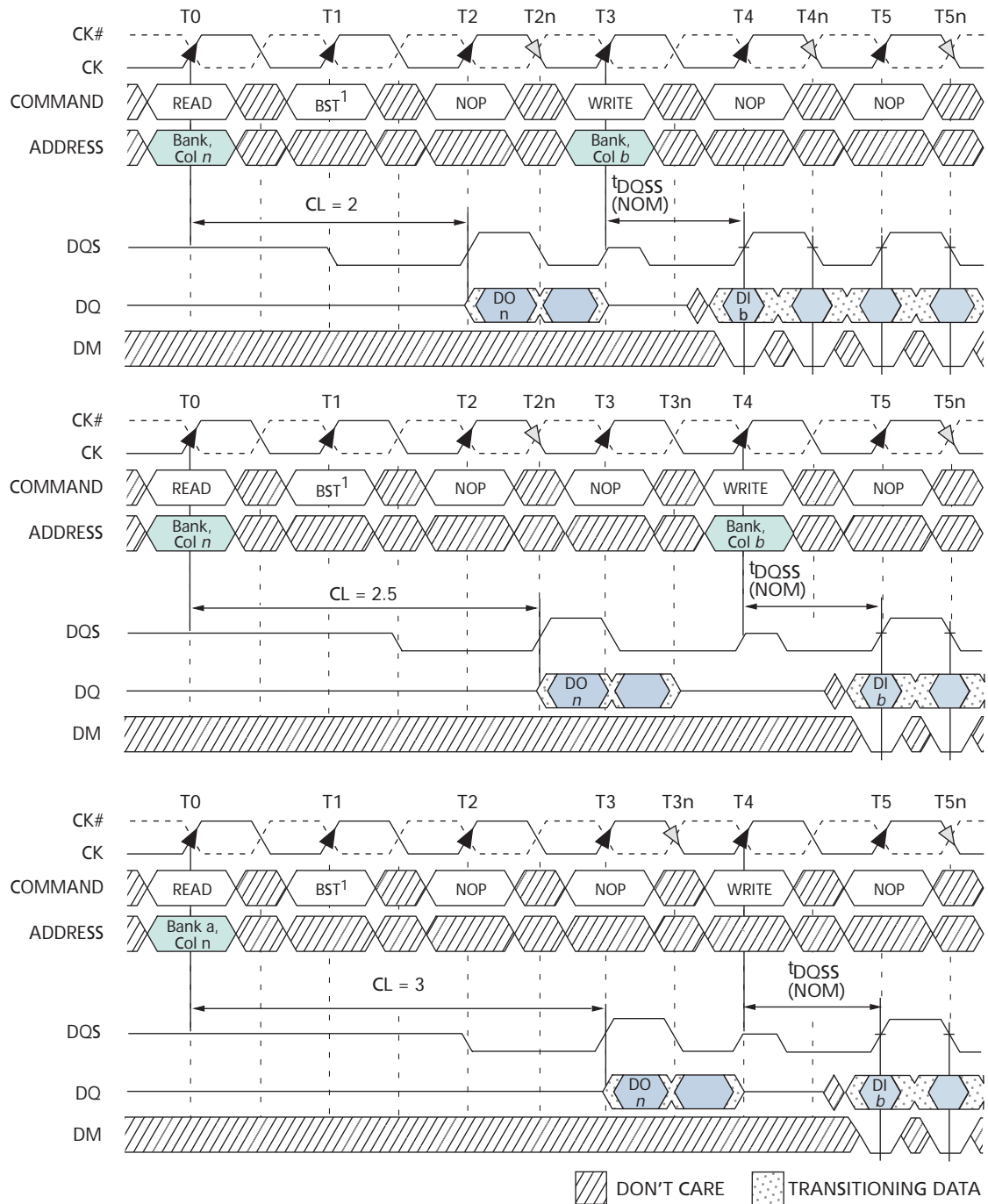
Figure 28: Random READ Accesses


- Notes:
1. DO_n (or x or b or g) = data-out from column n (or column x or column b or column g).
 2. BL = 2, BL = 4, or BL = 8 (if BL = 4 or BL = 8, the following burst interrupts the previous).
 3. n', x', b', or g' indicate the next data-out following DO_n, DO_x, DO_b, or DO_g, respectively.
 4. READs are to an active row in any bank.
 5. Shown with nominal t_{AC} , t_{DQSQ} , and t_{DQSQ} .

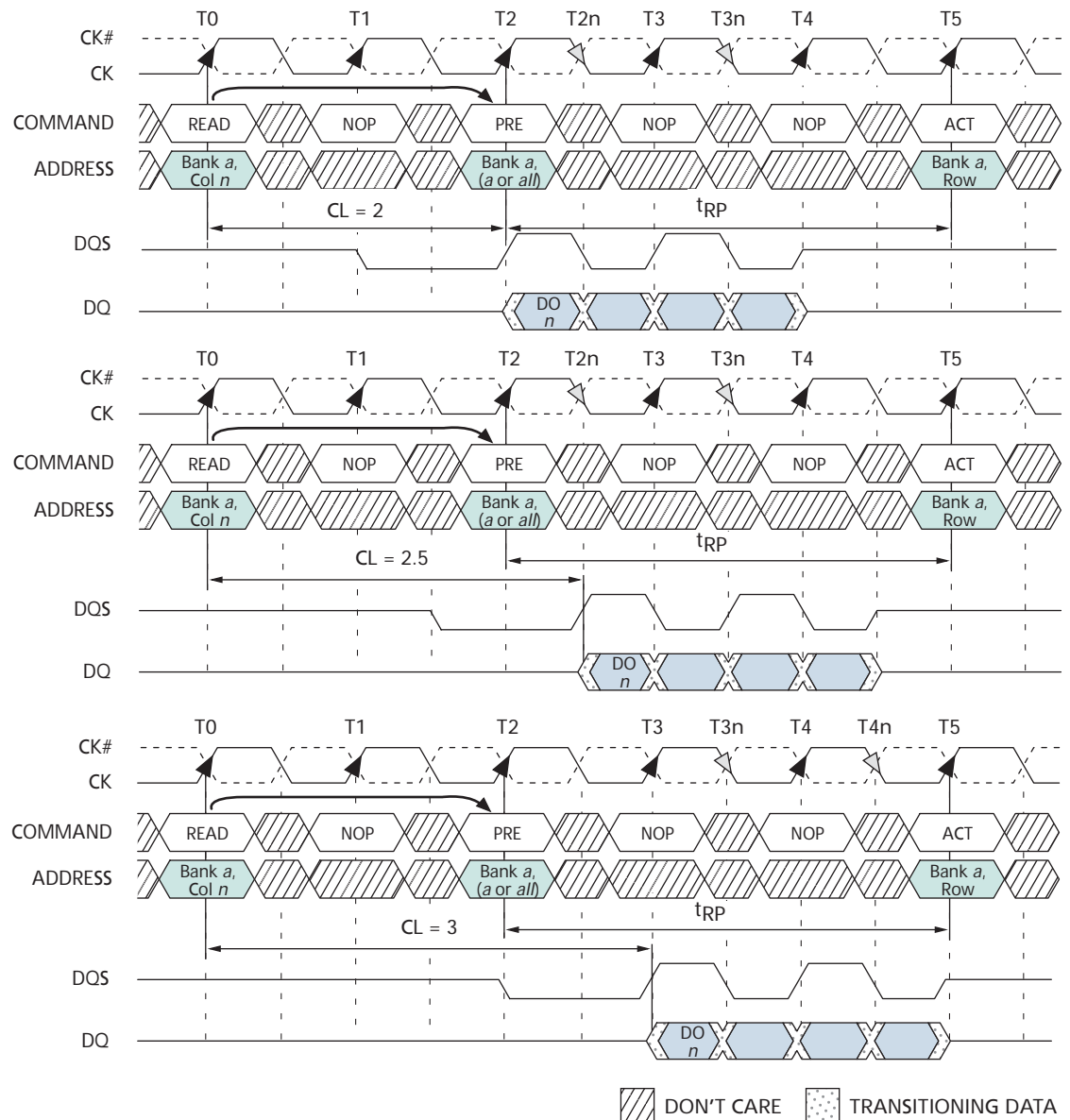
Figure 29: Terminating a READ Burst



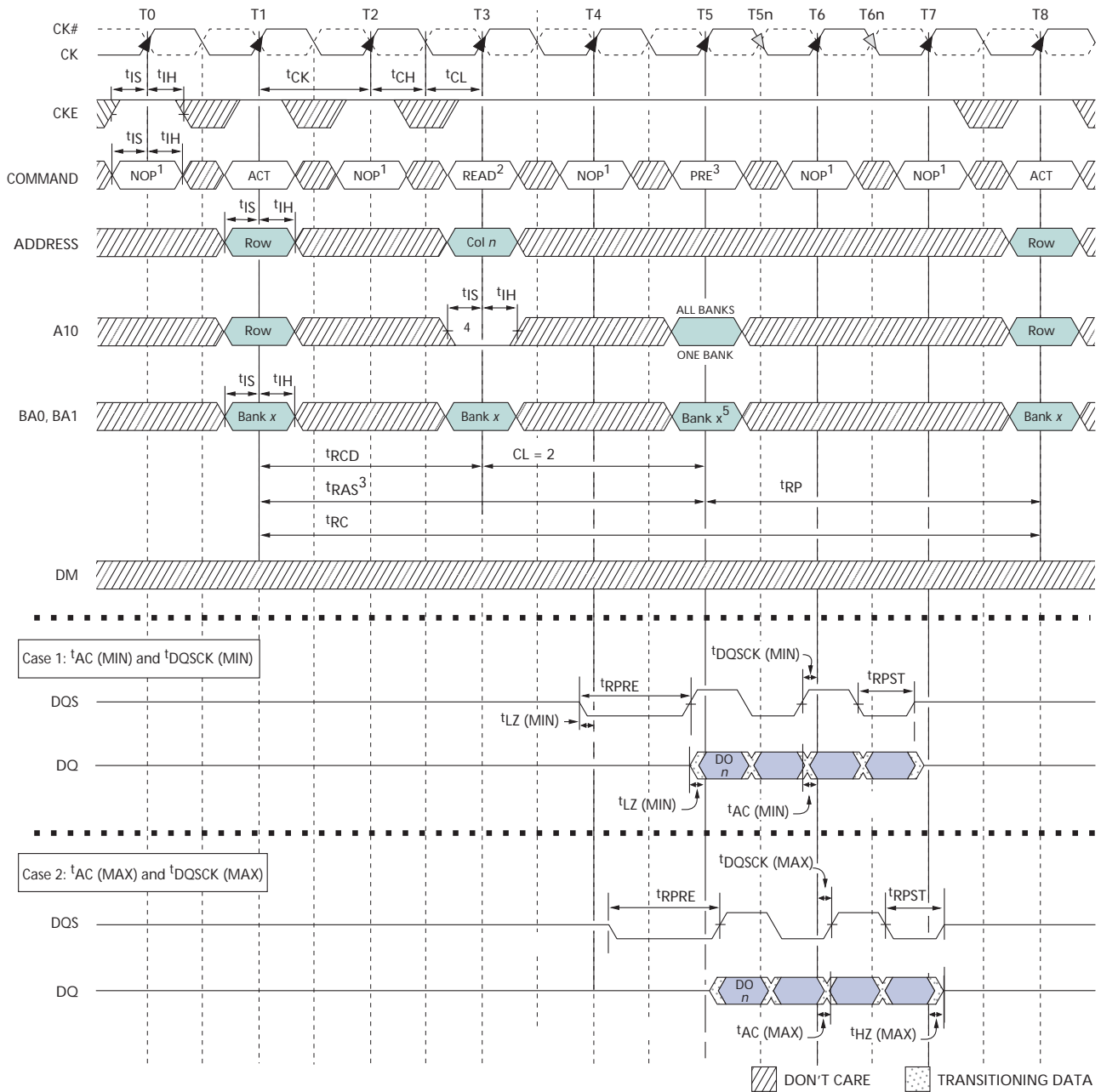
- Notes:
1. Page remains open.
 2. DO_n = data-out from column *n*.
 3. BL = 4.
 4. Subsequent element of data-out appears in the programmed order following DO_n.
 5. Shown with nominal t_{AC} , t_{DQCK} , and t_{DQSQ} .

Figure 30: READ-to-WRITE


- Notes:
1. Page remains open.
 2. DO n = data-out from column n ; DI b = data-in from column b .
 3. BL = 4 (applies for bursts of 8 as well; if BL = 2, the BURST command shown can be NOP).
 4. One subsequent element of data-out appears in the programmed order following DO n .
 5. Data-in elements are applied following DI b in the programmed order.
 6. Shown with nominal t_{AC} , t_{DQSK} , and t_{DQSQ} .

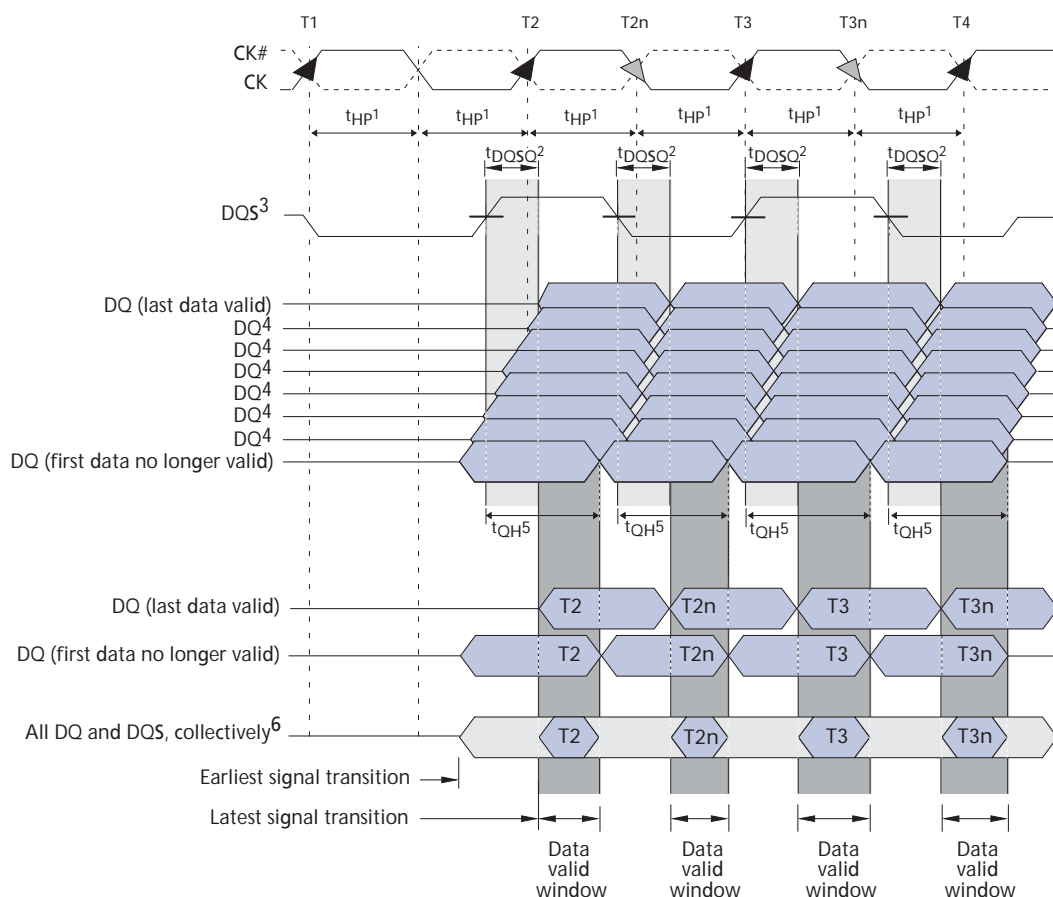
Figure 31: READ-to-PRECHARGE


- Notes:
1. Provided $t_{RAS} (MIN)$ is met, a READ command with auto precharge enabled would cause a precharge to be performed at x number of clock cycles after the READ command, where $x = BL/2$.
 2. $DO n$ = data-out from column n.
 3. $BL = 4$ or an interrupted burst of 8.
 4. Three subsequent elements of data-out appear in the programmed order following $DO n$.
 5. Shown with nominal t_{AC} , t_{DQSCk} , and t_{DQSQ} .
 6. READ-to-PRECHARGE equals two clocks, which allows two data pairs of data-out; it is also assumed that $t_{RAS} (MIN)$ is met.
 7. An ACTIVE command to the same bank is only allowed if $t_{RC} (MIN)$ is met.

Figure 32: Bank READ – Without Auto Precharge


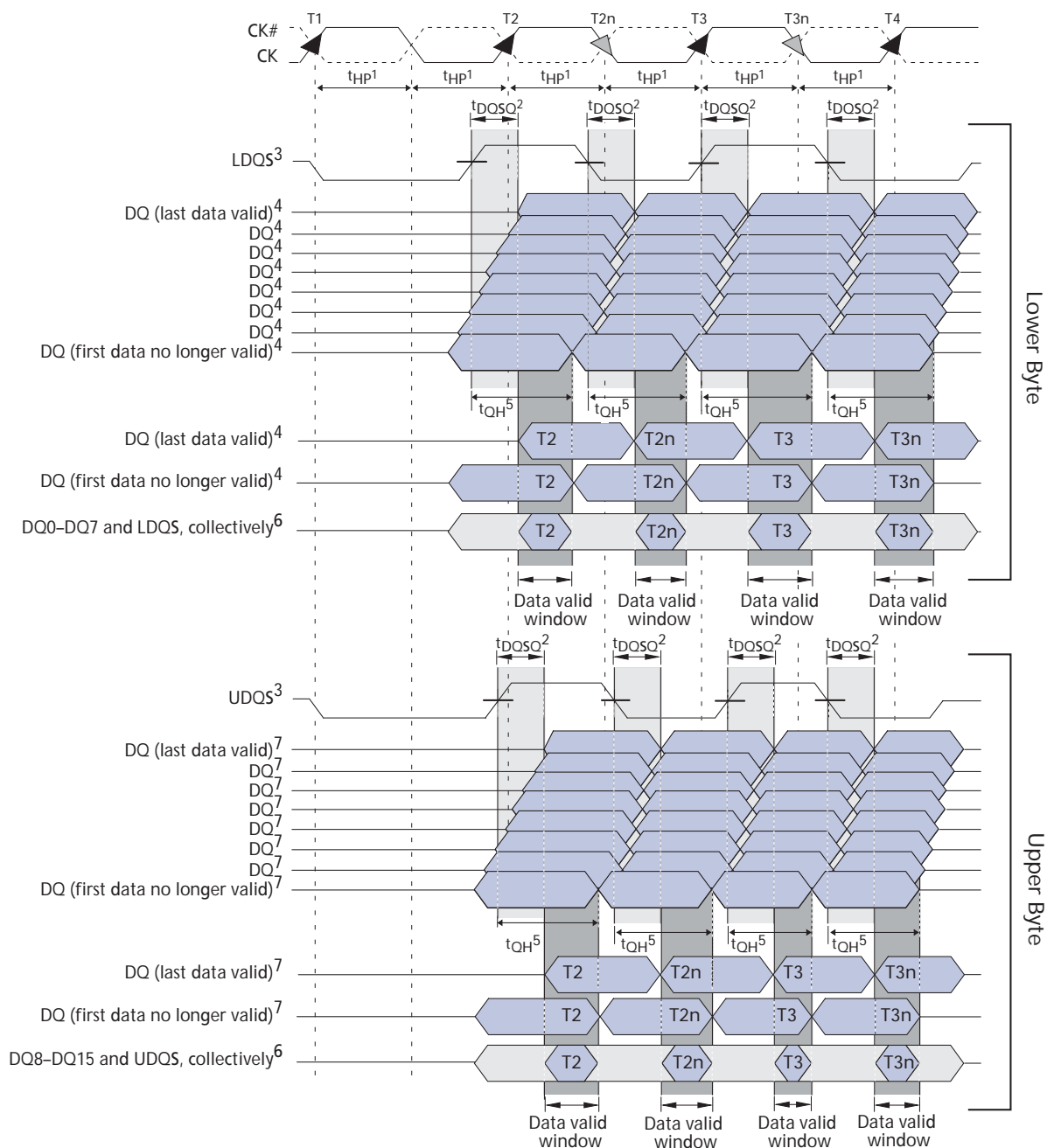
- Notes:
1. NOP commands are shown for ease of illustration; other commands may be valid at these times.
 2. BL = 4.
 3. The PRECHARGE command can only be applied at T5 if $t_{RAS}(\text{MIN})$ is met.
 4. Disable auto precharge.
 5. "Don't Care" if A10 is HIGH at T5.
 6. DO n (or b) = data-out from column n (or column b); subsequent elements are provided in the programmed order.
 7. Refer to Figure 33 on page 60, Figure 34 on page 61, and Figure 35 on page 62 for detailed DQS and DQ timing.

Figure 33: x4, x8 Data Output Timing – t_{DQSQ} , t_{QH} , and Data Valid Window

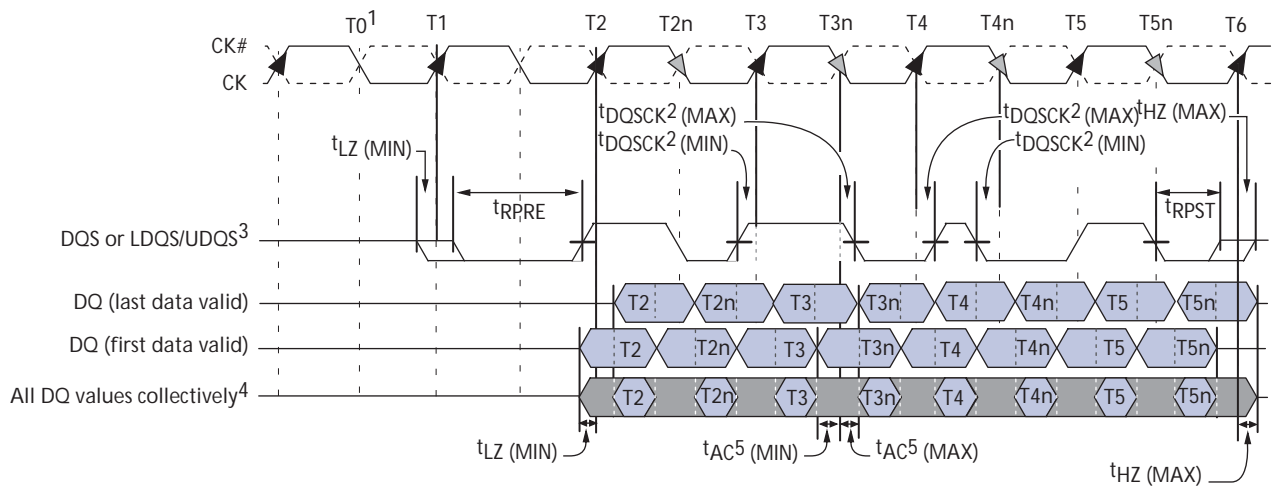


- Notes:
1. t_{HP} is the lesser of t_{CL} or t_{CH} clock transition collectively when a bank is active.
 2. t_{DQSQ} is derived at each DQS clock edge, is not cumulative over time, begins with DQS transition, and ends with the last valid DQ transition.
 3. DQs transitioning after DQS transition define the t_{DQSQ} window. DQS transitions at T2 and T2n are an "early DQS"; at T3, a "nominal DQS"; and at T3n, a "late DQS".
 4. For a x4, only two DQs apply.
 5. t_{QH} is derived from t_{HP} : $t_{QH} = t_{HP} - t_{QHS}$.
 6. The data valid window is derived for each DQS transitions and is defined as $t_{QH} - t_{DQSQ}$.

Figure 34: x16 Data Output Timing – t_{DQSQ} , t_{QH} , and Data Valid Window



- Notes:
- t_{HP} is the lesser of t_{CL} or t_{CH} clock transition collectively when a bank is active.
 - t_{DQSQ} is derived at each DQS clock edge, is not cumulative over time, begins with DQS transition, and ends with the last valid DQ transition.
 - DQs transitioning after DQS transition define the t_{DQSQ} window. LDQS defines the lower byte, and UDQS defines the upper byte.
 - DQ0, DQ1, DQ2, DQ3, DQ4, DQ5, DQ6, or DQ7.
 - t_{QH} is derived from t_{HP} : $t_{QH} = t_{HP} - t_{DQSQ}$.
 - The data valid window is derived for each DQS transition and is $t_{QH} - t_{DQSQ}$.
 - DQ8, DQ9, DQ10, DQ11, DQ12, DQ13, DQ14, or DQ15.

Figure 35: Data Output Timing – t_{AC} and t_{DQSK}


- Notes:
1. READ command with CL = 2 issued at T0.
 2. t_{DQSK2} is the DQS output window relative to CK and is the “long term” component of the DQS skew.
 3. DQs transitioning after DQS transition define the t_{DQSQ} window.
 4. All DQs must transition by t_{DQSQ} after DQS transitions, regardless of t_{AC} .
 5. t_{AC} is the DQ output window relative to CK and is the “long term” component of DQ skew.
 6. $t_{LZ} (MIN)$ and $t_{AC} (MIN)$ are the first valid signal transitions.
 7. $t_{HZ} (MAX)$ and $t_{AC} (MAX)$ are the latest valid signal transitions.

WRITE

During a WRITE command, the value on input A10 determines whether or not auto precharge is used. If auto precharge is selected, the row being accessed will be precharged at the end of the WRITE burst (after t_{WR} time); if auto precharge is not selected, the row will remain open for subsequent accesses.

Input data appearing on the DQ is written to the memory array subject to the DM input logic level appearing coincident with the data. If a given DM signal is registered LOW, the corresponding data will be written to memory. If the DM signal is registered HIGH, the corresponding data inputs will be ignored, and a WRITE will not be executed to that byte/column location.

Note: For the WRITE commands used in the following illustrations, auto precharge is disabled.

During WRITE bursts, the first valid data-in element will be registered on the first rising edge of DQS following the WRITE command, and subsequent data elements will be registered on successive edges of DQS. The LOW state on DQS between the WRITE command and the first rising edge is known as the write preamble; the LOW state on DQS following the last data-in element is known as the write postamble.

The time between the WRITE command and the first corresponding rising edge of DQS (t_{DQSS}) is specified with a relatively wide range (from 75 percent to 125 percent of one clock cycle). All of the WRITE diagrams show the nominal case, and where the two extreme cases (i.e., $t_{DQSS} [MIN]$ and $t_{DQSS} [MAX]$) might not be intuitive; they have

also been included. Figure 36 on page 64 shows the nominal case and the extremes of t_{DQSS} for BL = 4. Upon completion of a burst, assuming no other commands have been initiated, the DQ will remain High-Z and any additional input data will be ignored.

Data for any WRITE burst may be concatenated with or truncated with a subsequent WRITE command. In either case, a continuous flow of input data can be maintained. The new WRITE command can be issued on any positive edge of clock following the previous WRITE command. The first data element from the new burst is applied after either the last element of a completed burst or the last desired data element of a longer burst which is being truncated. The new WRITE command should be issued x cycles after the first WRITE command, where x equals the number of desired data element pairs (pairs are required by the $2n$ -prefetch architecture).

Figure 37 on page 65 shows concatenated bursts of 4. An example of nonconsecutive WRITES is shown in Figure 38 on page 66. Full-speed random write accesses within a page or pages can be performed as shown in Figure 39 on page 66.

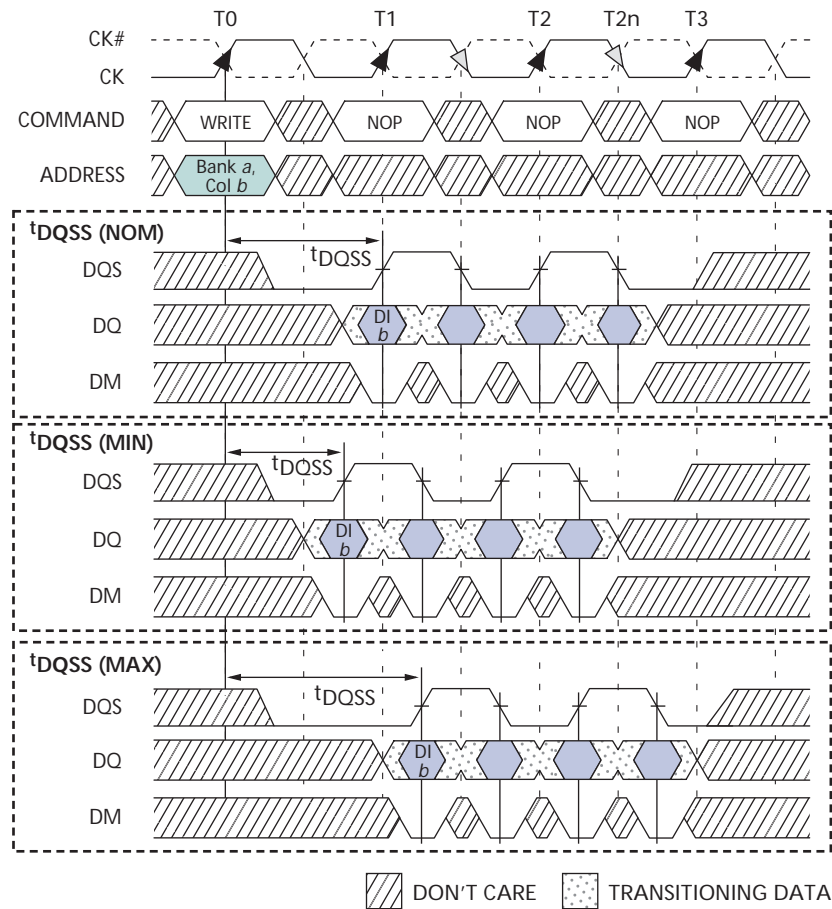
Data for any WRITE burst may be followed by a subsequent READ command. To follow a WRITE without truncating the WRITE burst, t_{WTR} should be met, as shown in Figure 40 on page 67.

Data for any WRITE burst may be truncated by a subsequent READ command, as shown in Figure 41 on page 68.

Note that only the data-in pairs that are registered prior to the t_{WTR} period are written to the internal array, and any subsequent data-in should be masked with DM, as shown in Figure 42 on page 69.

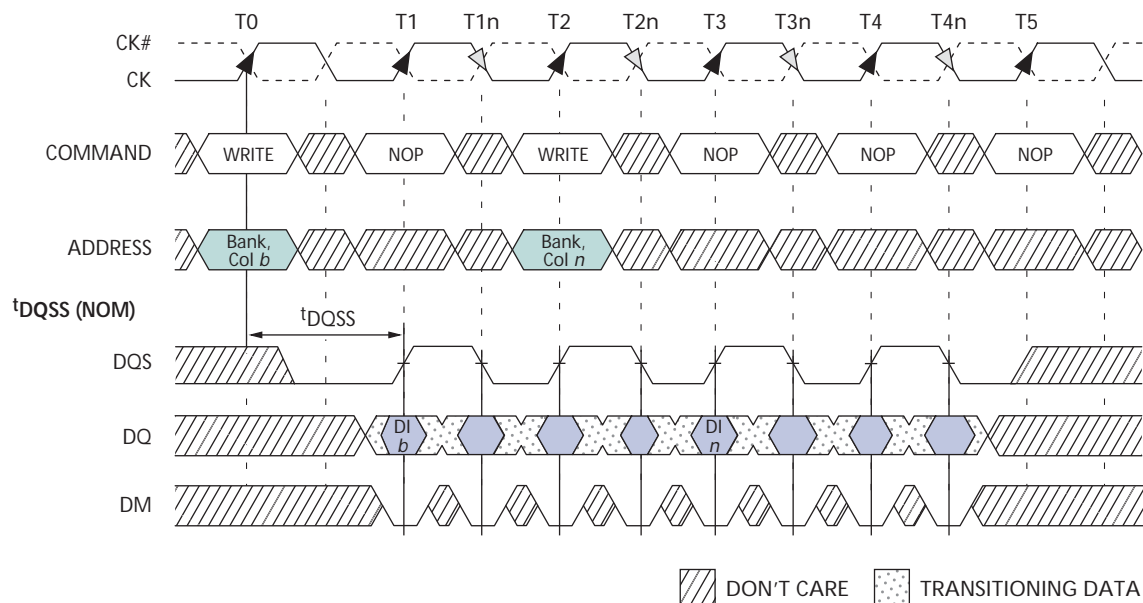
Data for any WRITE burst may be followed by a subsequent PRECHARGE command. To follow a WRITE without truncating the WRITE burst, t_{WR} should be met, as shown in Figure 43 on page 70.

Data for any WRITE burst may be truncated by a subsequent PRECHARGE command, as shown in Figure 44 on page 71 and Figure 45 on page 72. Only the data-in pairs registered prior to the t_{WR} period are written to the internal array; any subsequent data-in should be masked with DM, as shown in Figures 44 and 45. After the PRECHARGE command, a subsequent command to the same bank cannot be issued until t_{RP} is met.

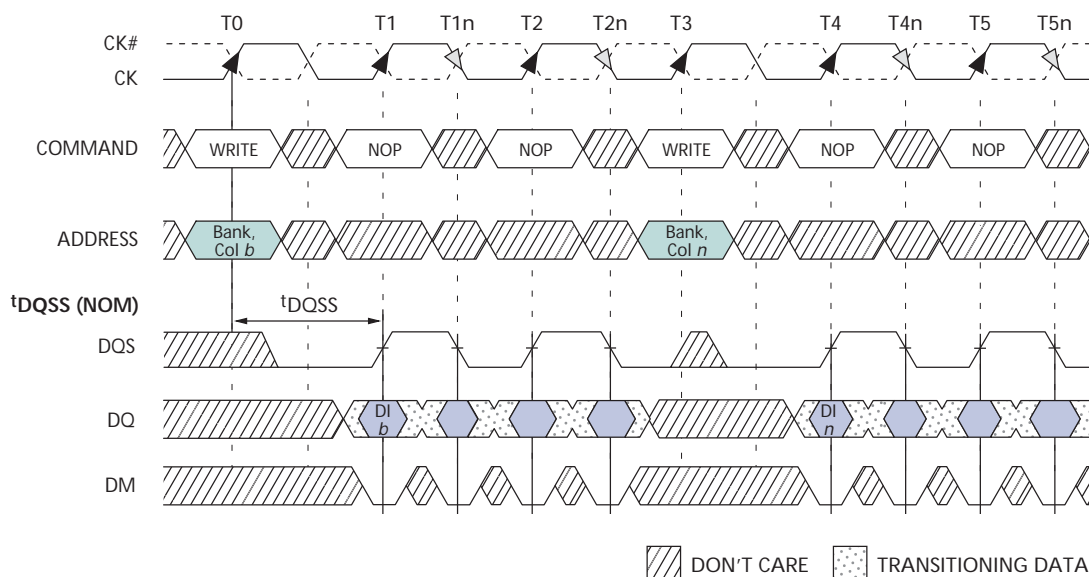
Figure 36: WRITE Burst


- Notes:
1. DI *b* = data-in for column *b*.
 2. Three subsequent elements of data-in are applied in the programmed order following DI *b*.
 3. An uninterrupted burst of 4 is shown.
 4. A10 is LOW with the WRITE command (auto precharge is disabled).

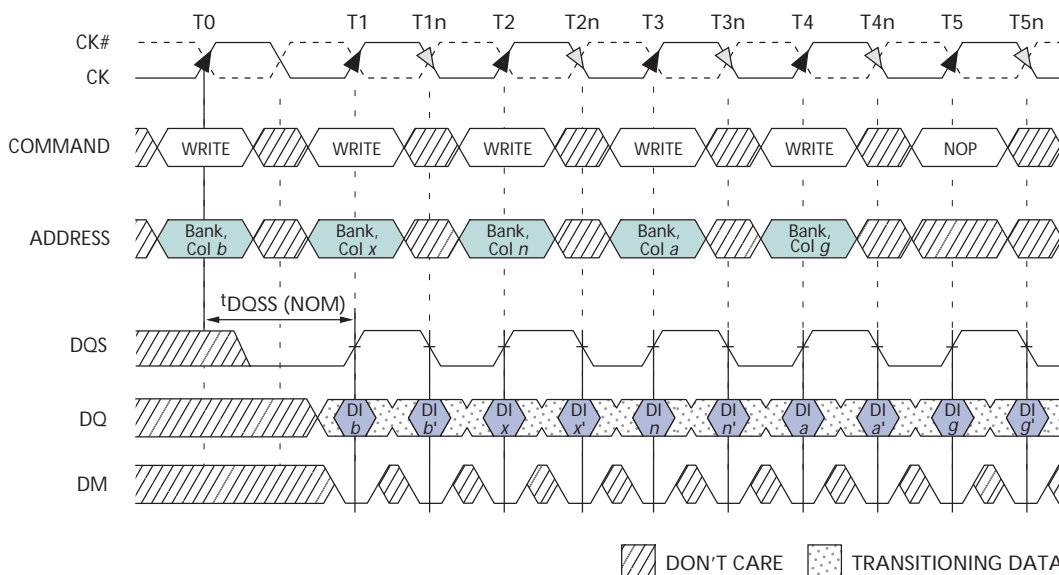
Figure 37: Consecutive WRITE-to-WRITE



- Notes:
1. DI b (or n) = data-in from column b (or column n).
 2. Three subsequent elements of data-in are applied in the programmed order following DI b .
 3. Three subsequent elements of data-in are applied in the programmed order following DI n .
 4. An uninterrupted burst of 4 is shown.
 5. Each WRITE command may be to any bank.

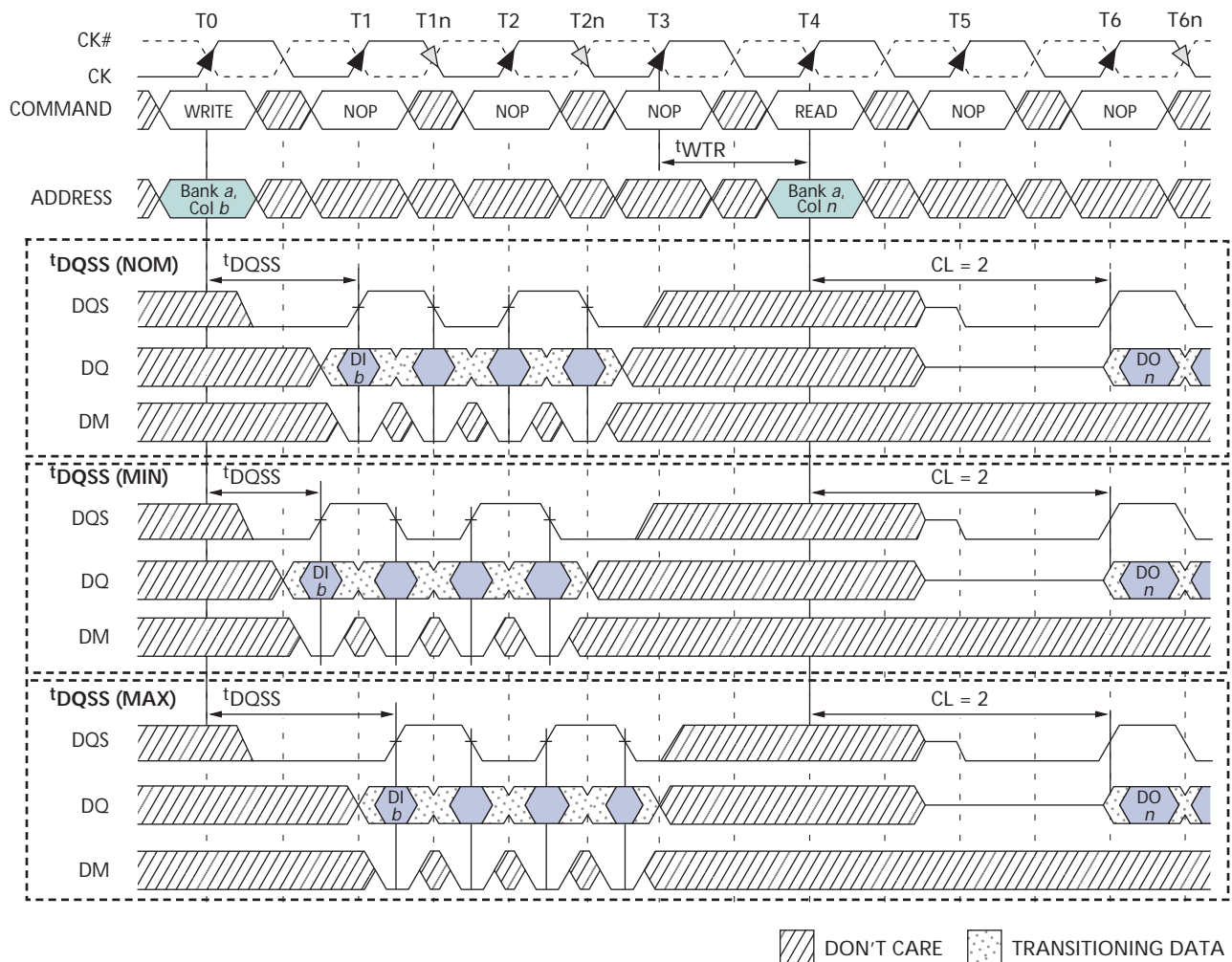
Figure 38: Nonconsecutive WRITE-to-WRITE


- Notes:
1. DI *b* (or *n*) = data-in from column *b* (or column *n*).
 2. Three subsequent elements of data-in are applied in the programmed order following DI *b*.
 3. Three subsequent elements of data-in are applied in the programmed order following DI *n*.
 4. An uninterrupted burst of 4 is shown.
 5. Each WRITE command may be to any bank.

Figure 39: Random WRITE Cycles


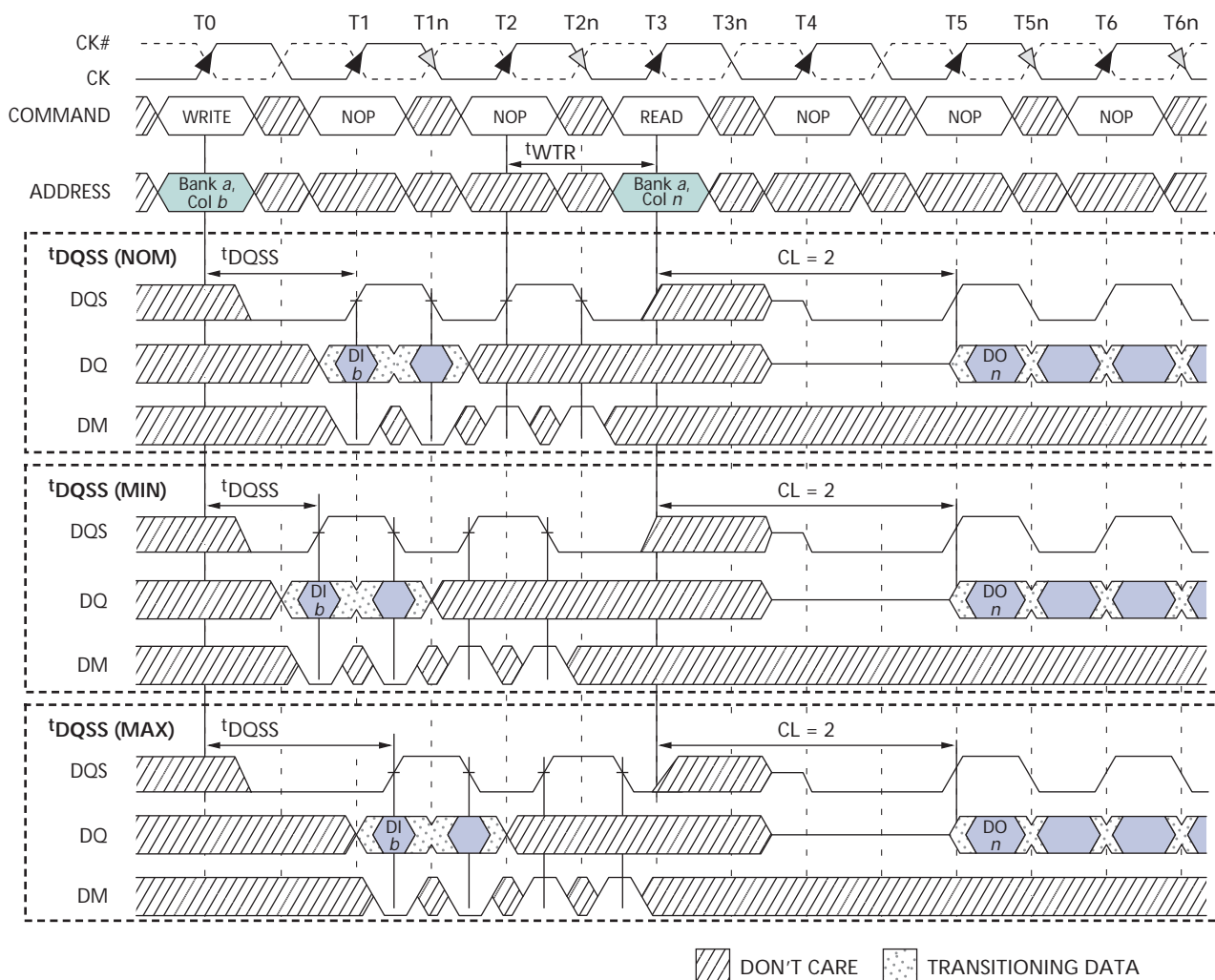
- Notes:
1. DI *b* (or *x* or *n* or *a* or *g*) = data-in from column *b* (or column *x*, or column *n*, or column *a*, or column *g*).
 2. *b'*, *x'*, *n'*, *a'* or *g'* indicate the next data-in following DO *b*, DO *x*, DO *n*, DO *a*, or DO *g*, respectively.
 3. Programmed BL = 2, BL = 4, or BL = 8 in cases shown.
 4. Each WRITE command may be to any bank.

Figure 40: WRITE-to-READ – Uninterrupting



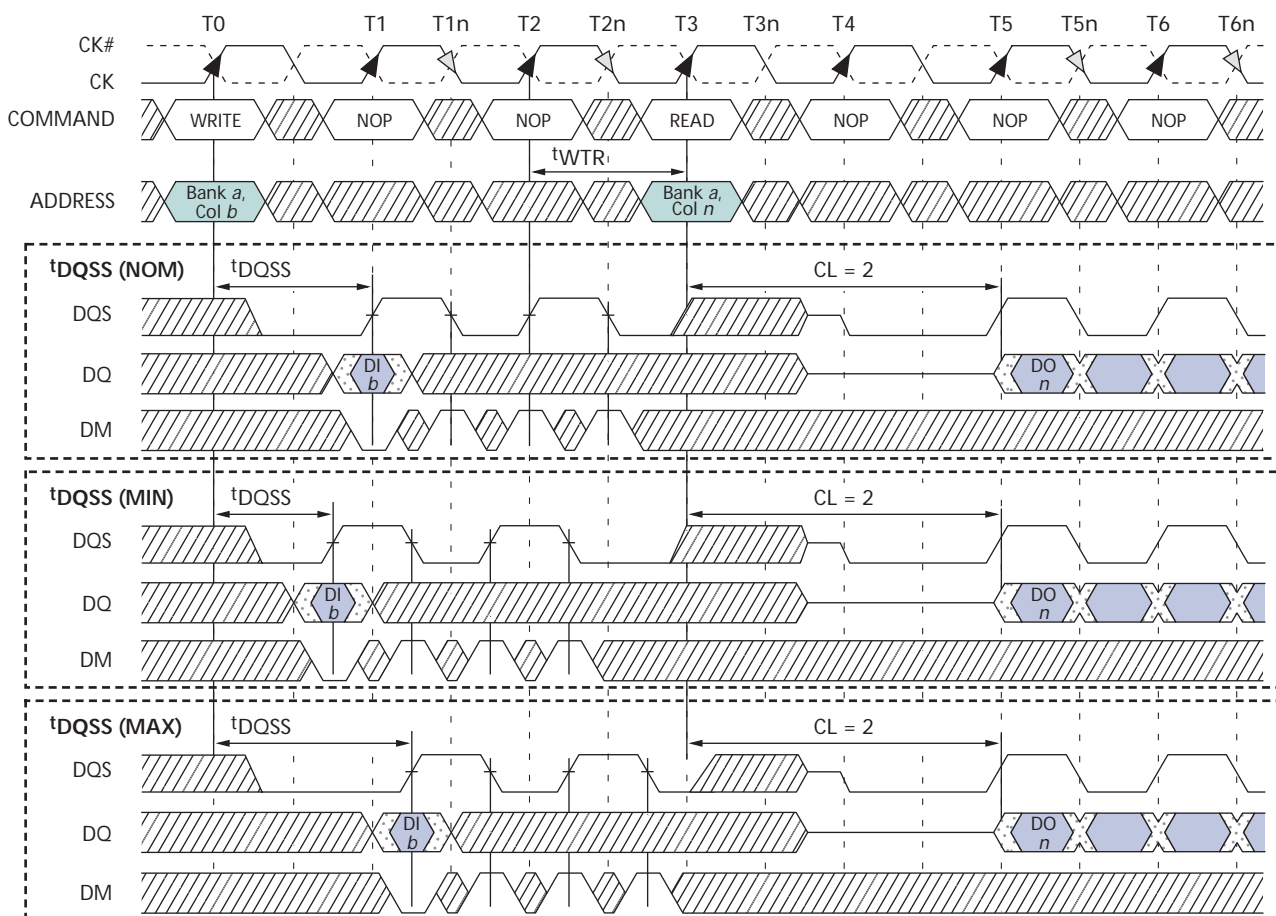
- Notes:
1. DI b = data-in for column b ; DO n = data-out for column n .
 2. Three subsequent elements of data-in are applied in the programmed order following DI b .
 3. An uninterrupted burst of 4 is shown.
 4. t_{WTR} is referenced from the first positive CK edge after the last data-in pair.
 5. The READ and WRITE commands are to the same device. However, the READ and WRITE commands may be to different devices, in which case t_{WTR} is not required, and the READ command could be applied earlier.
 6. A10 is LOW with the WRITE command (auto precharge is disabled).

Figure 41: WRITE-to-READ – Interrupting



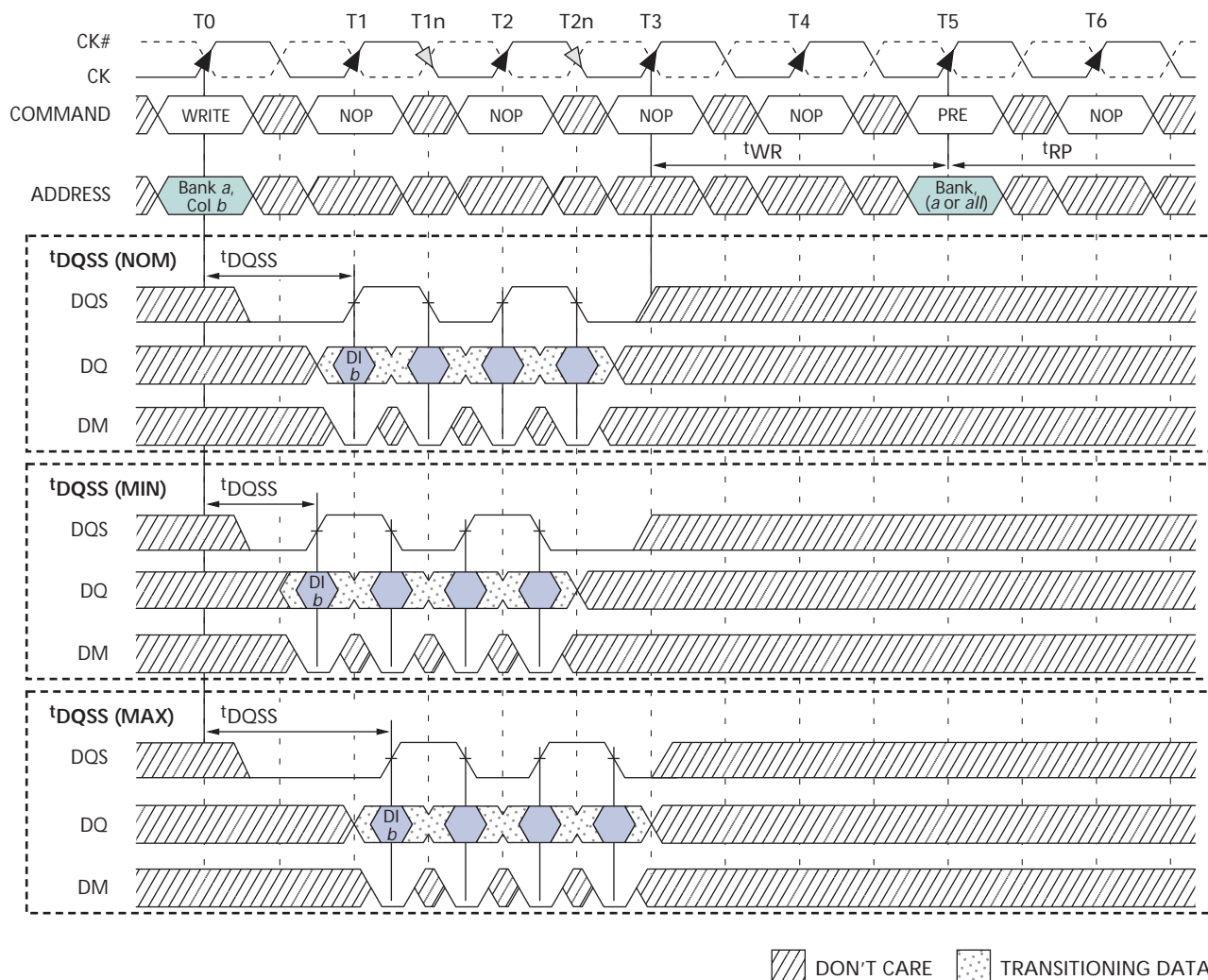
- Notes:
1. DI b = data-in for column b ; DO n = data-out for column n .
 2. An interrupted burst of 4 is shown; two data elements are written.
 3. One subsequent element of data-in is applied in the programmed order following DI b .
 4. t_{WTR} is referenced from the first positive CK edge after the last data-in pair.
 5. A10 is LOW with the WRITE command (auto precharge is disabled).
 6. DQS is required at T2 and T2n (nominal case) to register DM.
 7. If the burst of 8 is used, DM and DQS are required at T3 and T3n because the READ command will not mask these two data elements.

Figure 42: WRITE-to-READ – Odd Number of Data, Interrupting

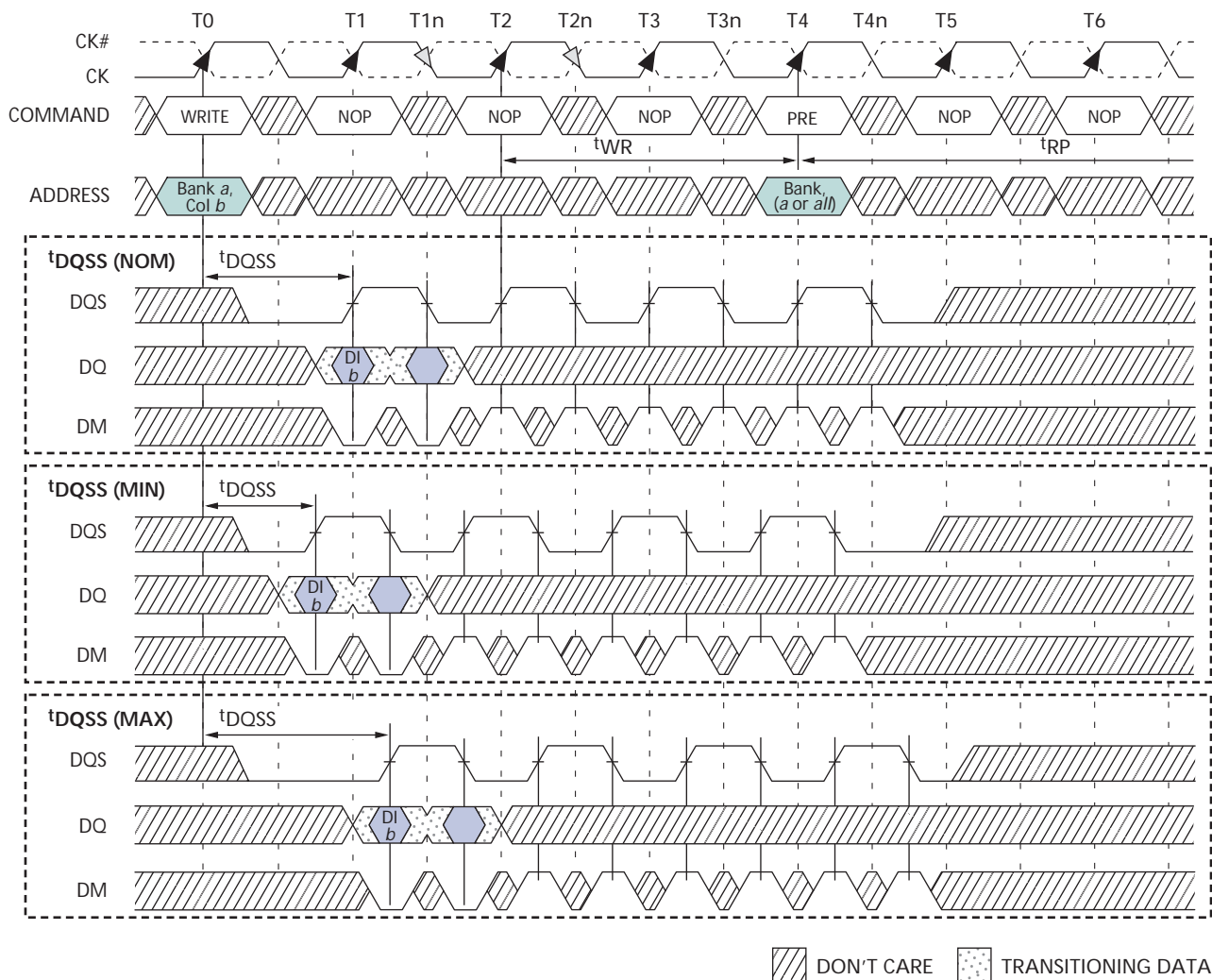


 DON'T CARE
  TRANSITIONING DATA

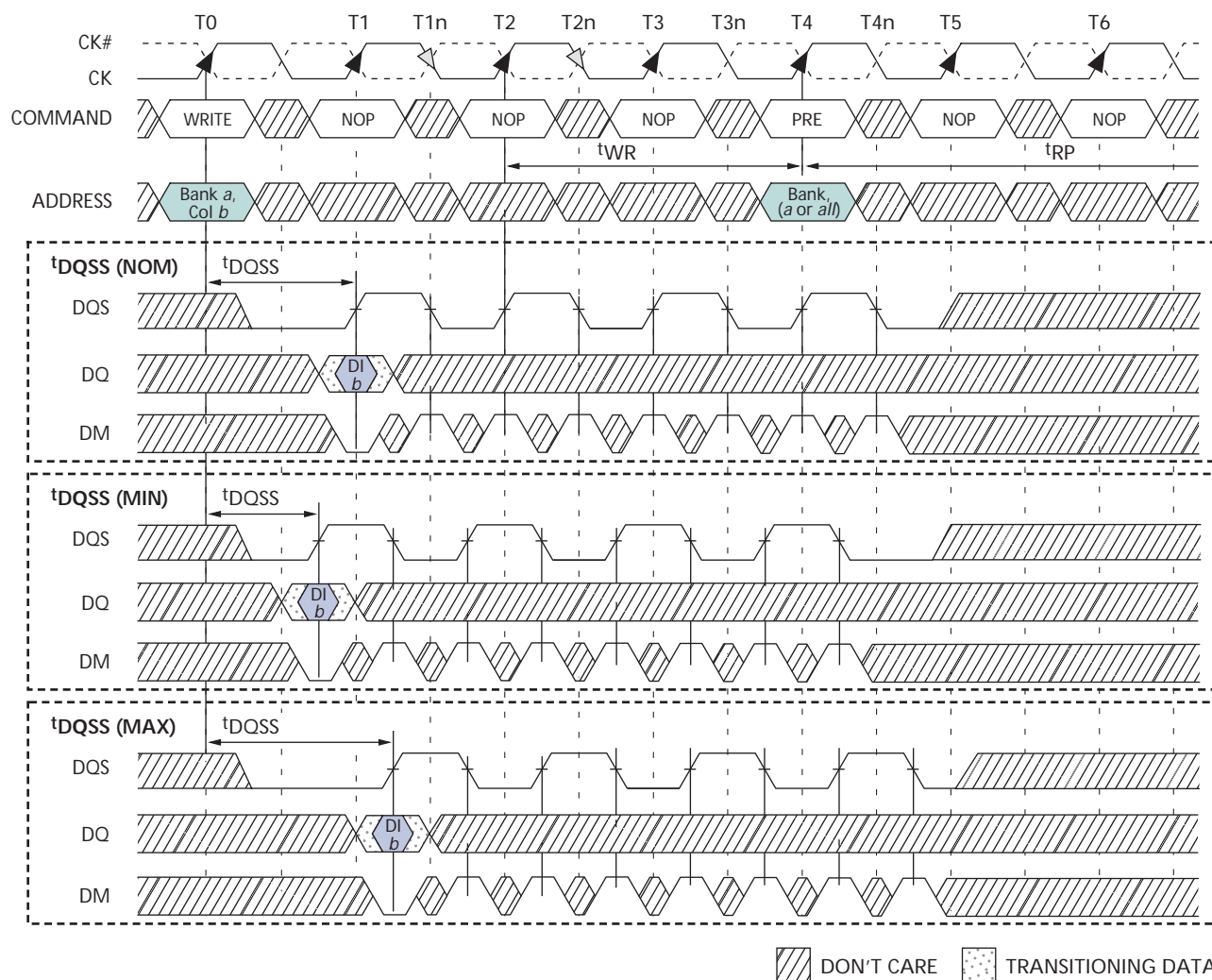
- Notes:
1. DI b = data-in for column b ; DO n = data-out for column n .
 2. An interrupted burst of 4 is shown; one data element is written.
 3. t_{WTR} is referenced from the first positive CK edge after the last desired data-in pair (not the last two data elements).
 4. A10 is LOW with the WRITE command (auto precharge is disabled).
 5. DQS is required at T1n, T2, and T2n (nominal case) to register DM.
 6. If the burst of 8 is used, DM and DQS are required at T3–T3n because the READ command will not mask these data elements.

Figure 43: WRITE-to-PRECHARGE – Uninterrupting


- Notes:
1. DI b = data-in for column b .
 2. Three subsequent elements of data-in are applied in the programmed order following DI b .
 3. An uninterrupted burst of 4 is shown.
 4. t_{WR} is referenced from the first positive CK edge after the last data-in pair.
 5. The PRECHARGE and WRITE commands are to the same device. However, the PRECHARGE and WRITE commands may be to different devices, in which case t_{WR} is not required, and the PRECHARGE command could be applied earlier.
 6. A10 is LOW with the WRITE command (auto precharge is disabled).

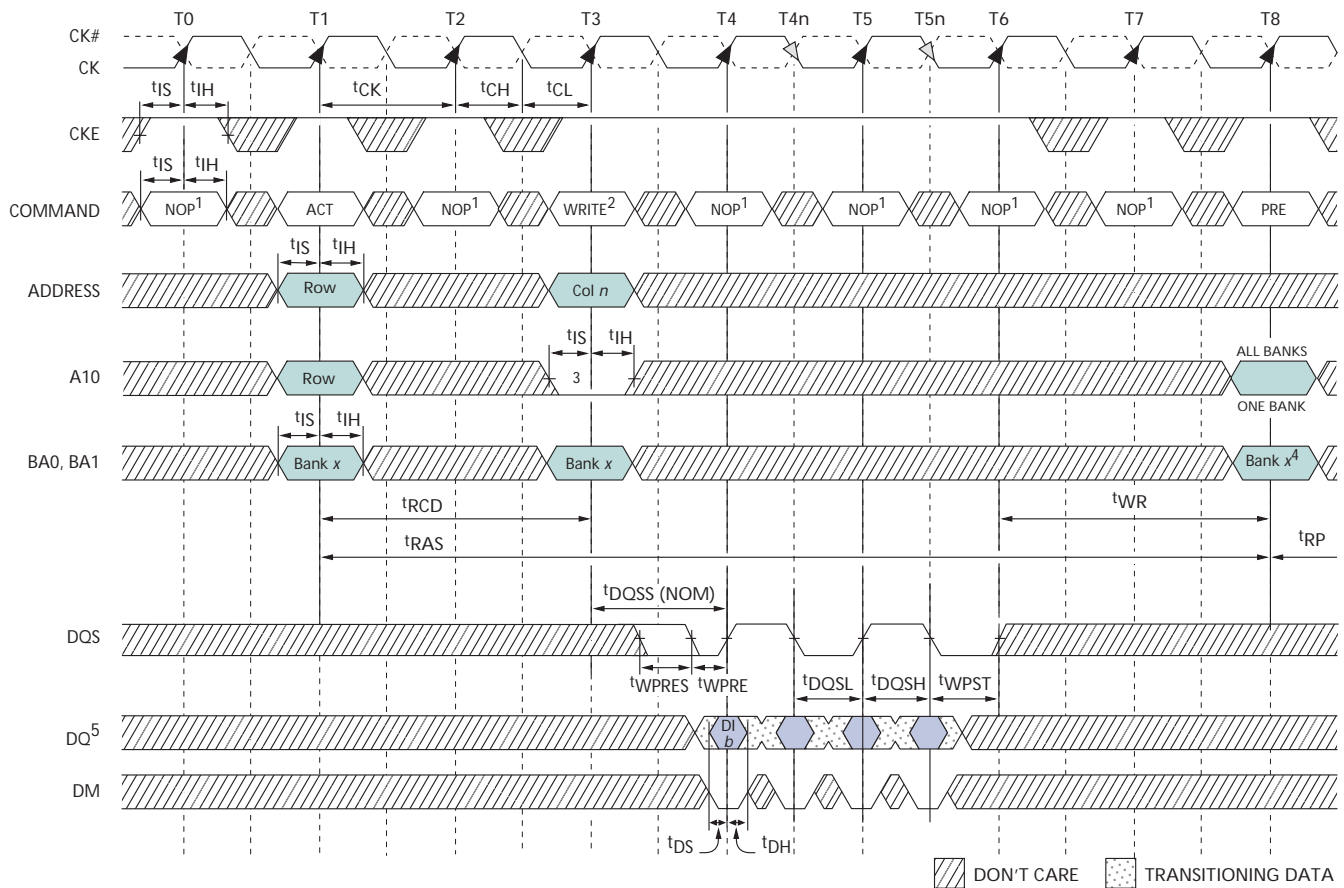
Figure 44: WRITE-to-PRECHARGE – Interrupting


- Notes:
1. DI b = data-in for column b .
 2. Subsequent element of data-in is applied in the programmed order following DI b .
 3. An interrupted burst of 8 is shown; two data elements are written.
 4. t_{WR} is referenced from the first positive CK edge after the last data-in pair.
 5. A10 is LOW with the WRITE command (auto precharge is disabled).
 6. DQS is required at T4 and T4n (nominal case) to register DM.
 7. If the burst of 4 is used, DQS and DM are not required at T3, T3n, T4, and T4n.

Figure 45: WRITE-to-PRECHARGE – Odd Number of Data, Interrupting


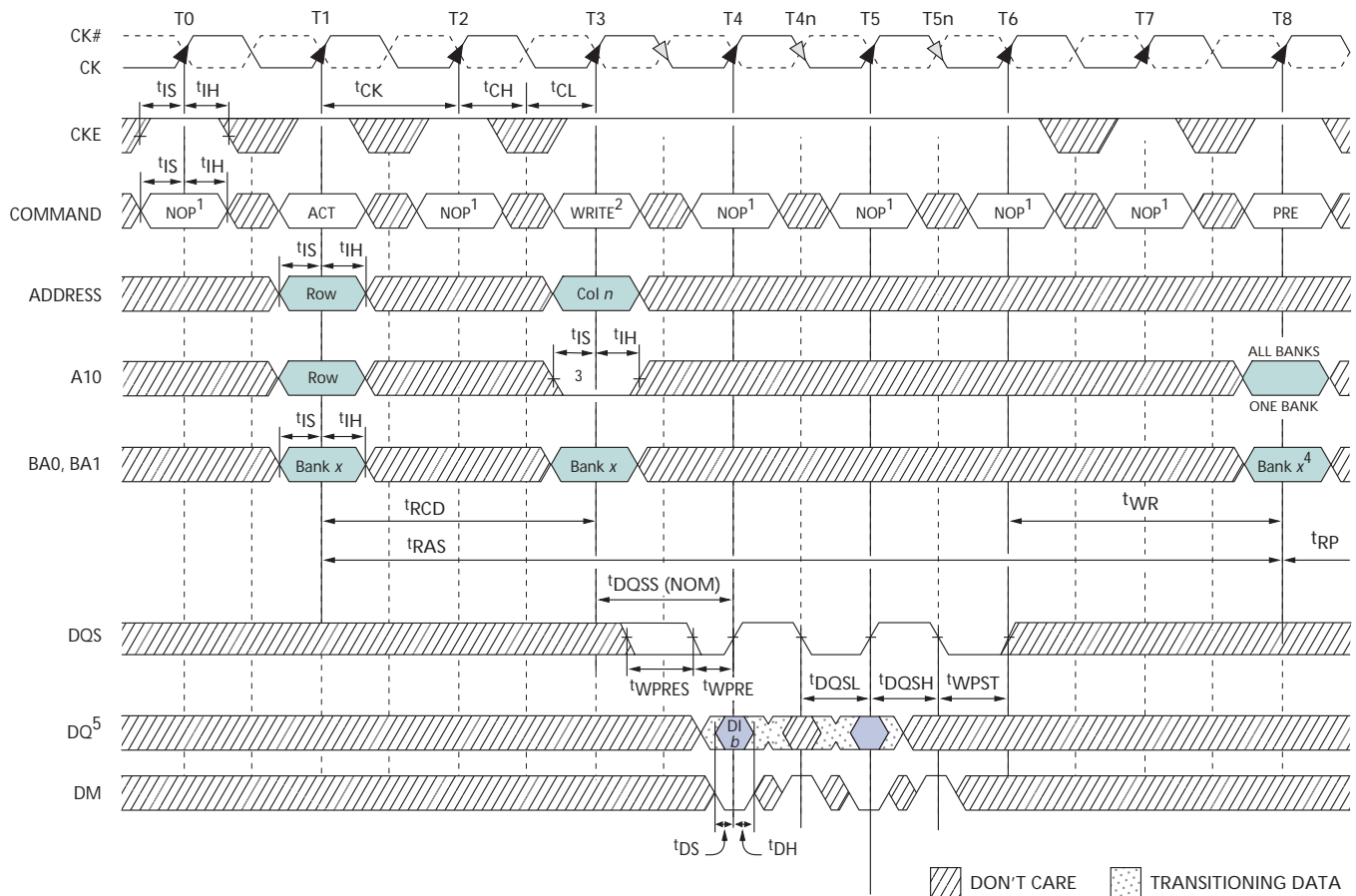
- Notes:
1. DI b = data-in for column b .
 2. An interrupted burst of 8 is shown; one data element is written.
 3. t_{WR} is referenced from the first positive CK edge after the last data-in pair.
 4. A10 is LOW with the WRITE command (auto precharge is disabled).
 5. DQS is required at T4 and T4n (nominal case) to register DM.
 6. If the burst of 4 is used, DQS and DM are not required at T3, T3n, T4, and T4n.

Figure 46: Bank WRITE – Without Auto Precharge

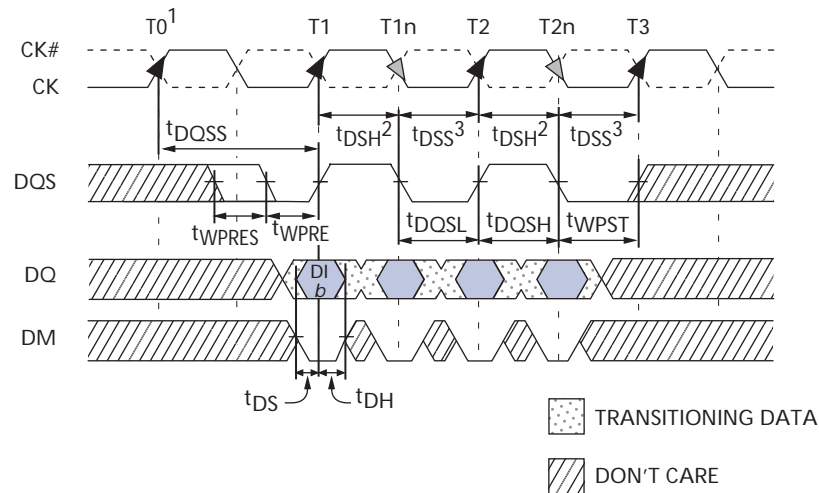


- Notes:
1. NOP commands are shown for ease of illustration; other commands may be valid at these times.
 2. BL = 4.
 3. Disable auto precharge.
 4. "Don't Care" if A10 is HIGH at T8.
 5. DI b = data-in from column b ; subsequent elements are provided in the programmed order.
 6. See Figure 48 on page 75 for detailed DQ timing.

Figure 47: WRITE – DM Operation



- Notes:
1. NOP commands are shown for ease of illustration; other commands may be valid at these times.
 2. BL = 4.
 3. Disable auto precharge.
 4. "Don't Care" if A10 is HIGH at T8.
 5. DI *b* = data-in from column *b*; subsequent elements are provided in the programmed order.
 6. See Figure 48 on page 75 for detailed DQ timing.

Figure 48: Data Input Timing


- Notes:
1. WRITE command issued at T0.
 2. t_{DSH} (MIN) generally occurs during t_{DQSS} (MIN).
 3. t_{DSS} (MIN) generally occurs during t_{DQSS} (MAX).
 4. For x16, LDQS controls the lower byte and UDQS controls the upper byte.
 5. DI b = data-in from column b

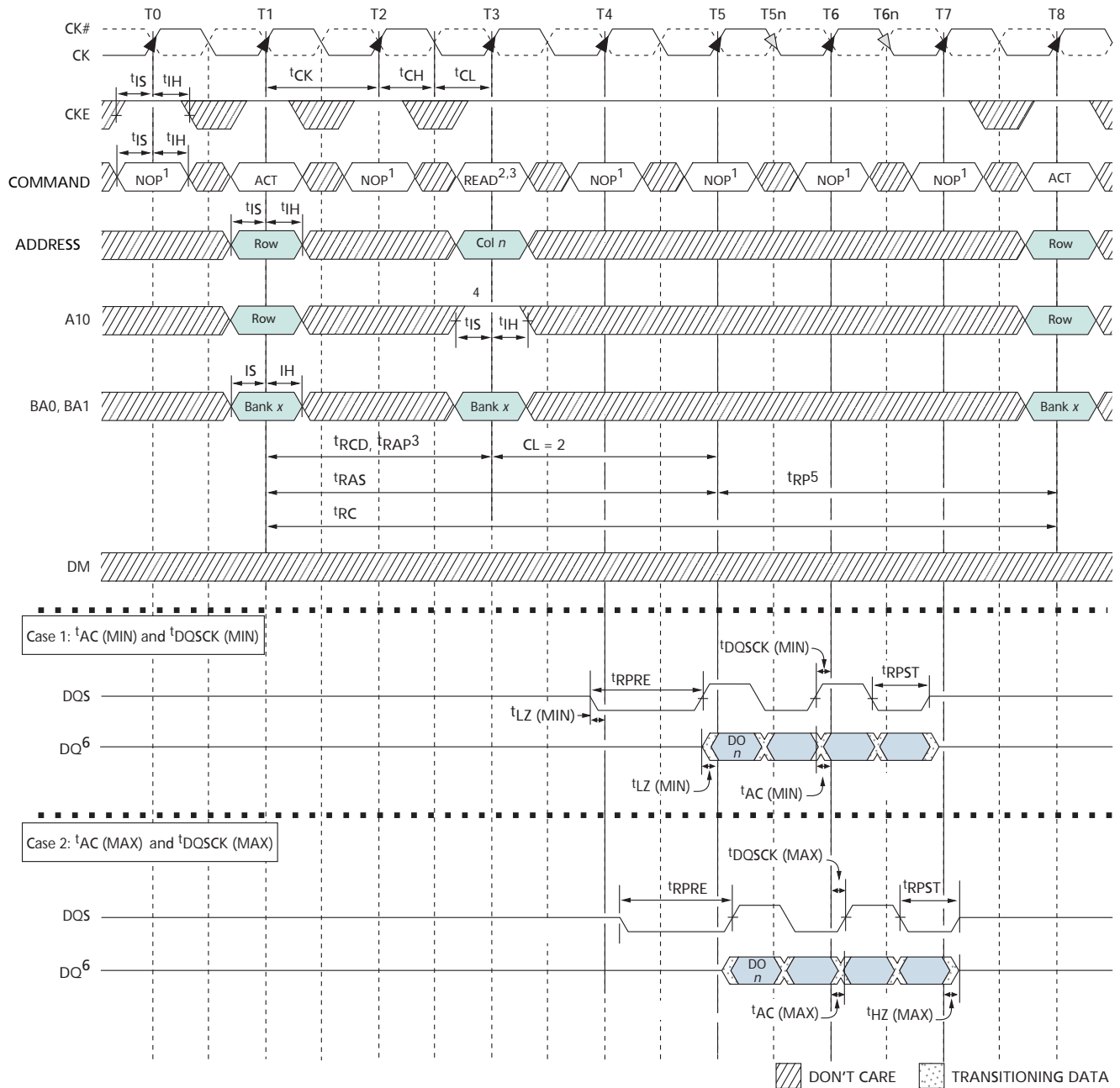
PRECHARGE

The bank(s) will be available for a subsequent row access a specified time (t_{RP}) after the PRECHARGE command is issued, except in the case of concurrent auto precharge. With concurrent auto precharge, a READ or WRITE command to a different bank is allowed as long as it does not interrupt the data transfer in the current bank and does not violate any other timing parameters. Input A10 determines whether one or all banks are to be precharged, and in the case where only one bank is to be precharged, inputs BA0, BA1 select the bank. When all banks are to be precharged, BA0, BA1 are treated as "Don't Care." Once a bank has been precharged, it is in the idle state and must be activated prior to any READ or WRITE commands being issued to that bank. A PRECHARGE command will be treated as a NOP if there is no open row in that bank (idle state), or if the previously open row is already in the process of precharging.

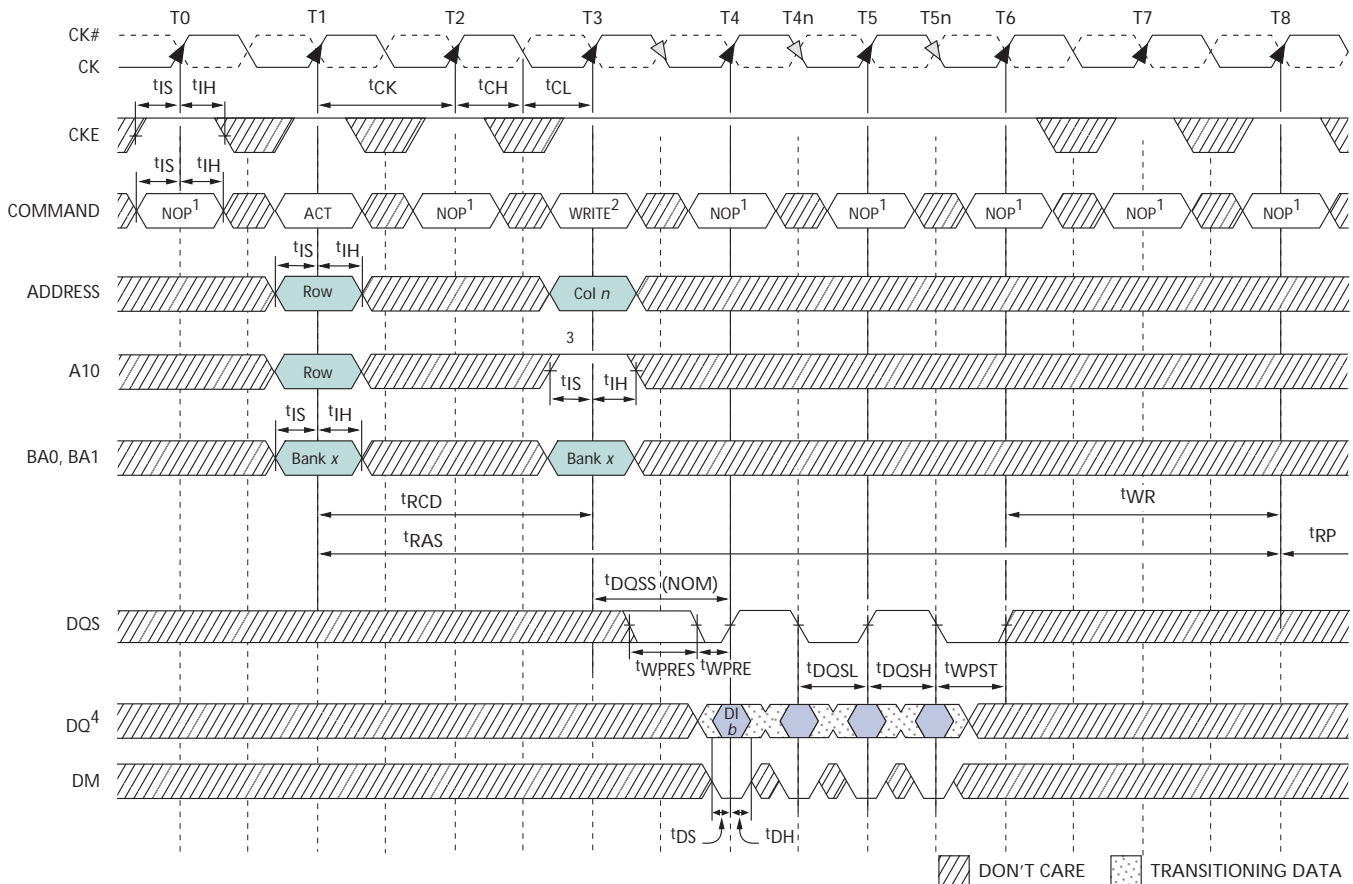
Auto Precharge

Auto precharge is a feature which performs the same individual-bank precharge function described above, but without requiring an explicit command. This is accomplished by using A10 to enable auto precharge in conjunction with a specific READ or WRITE command. A precharge of the bank/row that is addressed with the READ or WRITE command is automatically performed upon completion of the READ or WRITE burst. Auto precharge is either enabled or disabled for each individual READ or WRITE command. This device supports concurrent auto precharge if the command to the other bank does not interrupt the data transfer to the current bank.

Auto precharge ensures that the precharge is initiated at the earliest valid stage within a burst. This "earliest valid stage" is determined as if an explicit PRECHARGE command was issued at the earliest possible time, without violating t_{RAS} (MIN), as described for each burst type in "Operations" on page 42. The user must not issue another command to the same bank until the precharge time (t_{RP}) is completed.

Figure 49: Bank READ – with Auto Precharge


- Notes:
1. NOP commands are shown for ease of illustration; other commands may be valid at these times.
 2. BL = 4.
 3. The READ command can only be applied at T3 if t_{RAP} is satisfied at T3.
 4. Enable auto precharge.
 5. t_{RP} starts only after t_{RAS} has been satisfied.
 6. DO n = data-out from column n ; subsequent elements are provided in the programmed order.
 7. Refer to Figure 33 on page 60, Figure 34 on page 61, and Figure 35 on page 62 for detailed DQS and DQ timing.

Figure 50: Bank WRITE – with Auto Precharge


- Notes:
1. NOP commands are shown for ease of illustration; other commands may be valid at these times.
 2. BL = 4.
 3. Enable auto precharge.
 4. DI n = data-out from column n ; subsequent elements are provided in the programmed order.
 5. See Figure 48 on page 75 for detailed DQ timing.

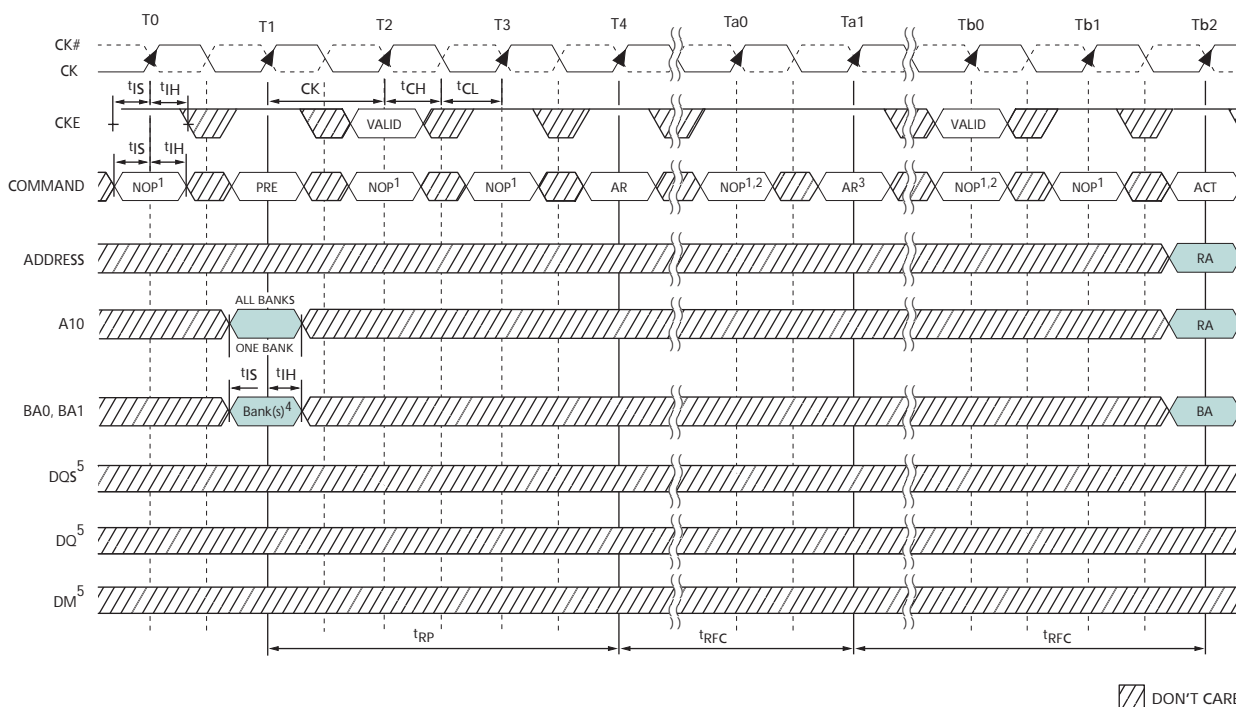
AUTO REFRESH

During auto refresh, the addressing is generated by the internal refresh controller. This makes the address bits a “Don’t Care” during an AUTO REFRESH command. The DDR SDRAM requires AUTO REFRESH cycles at an average interval of t_{REFI} (MAX).

To allow for improved efficiency in scheduling and switching between tasks, some flexibility in the absolute refresh interval is provided. A maximum of eight AUTO REFRESH commands can be posted to any given DDR SDRAM, meaning that the maximum absolute interval between any AUTO REFRESH command and the next AUTO REFRESH command is $9 \times t_{REFI}$ ($= t_{REFC}$). JEDEC specifications only allow $8 \times t_{REFI}$; Micron specifications exceed the JEDEC requirement by one clock. This maximum absolute interval is to allow future support for DLL updates, internal to the DDR SDRAM, to be restricted to AUTO REFRESH cycles, without allowing excessive drift in t_{AC} between updates.

Although not a JEDEC requirement, to provide for future functionality features, CKE must be active (HIGH) during the AUTO REFRESH period. The AUTO REFRESH period begins when the AUTO REFRESH command is registered and ends t_{RFC} later.

Figure 51: Auto Refresh Mode



- Notes:
1. NOP commands are shown for ease of illustration; other valid commands may be possible at these times. CKE must be active during clock-positive transitions.
 2. NOP or COMMAND INHIBIT are the only commands allowed until after t_{RFC} time; CKE must be active during clock-positive transitions.
 3. The second AUTO REFRESH is not required and is only shown as an example of two back-to-back AUTO REFRESH commands.
 4. "Don't Care" if A10 is HIGH at this point; A10 must be HIGH if more than one bank is active (i.e., must precharge all active banks).
 5. DM, DQ, and DQS signals are all "Don't Care"/High-Z for the operations shown.

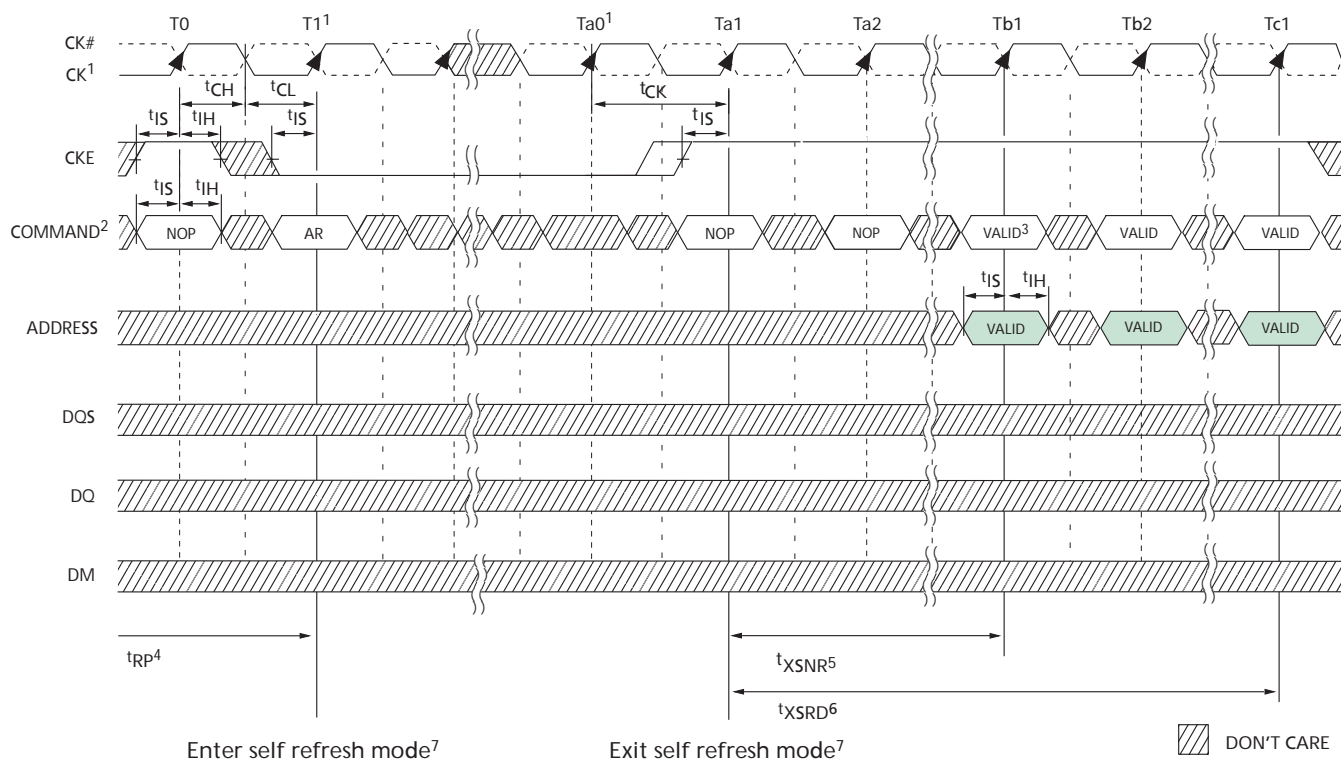
SELF REFRESH

When in the self refresh mode, the DDR SDRAM retains data without external clocking. The DLL is automatically disabled upon entering SELF REFRESH and is automatically enabled upon exiting SELF REFRESH (A DLL reset and 200 clock cycles must then occur before a READ command can be issued). Input signals except CKE are "Don't Care" during SELF REFRESH. VREF voltage is also required for the full duration of SELF REFRESH.

The procedure for exiting SELF REFRESH requires a sequence of commands. First, CK and CK# must be stable prior to CKE going back HIGH. Once CKE is HIGH, the DDR SDRAM must have NOP commands issued for t_{XSNR} because time is required for the completion of any internal refresh in progress. A simple algorithm for meeting both refresh and DLL requirements is to apply NOPs for t_{XSRD} time, then a DLL RESET (via

the extended mode register) and NOPs for 200 additional clock cycles before applying a READ. Any command other than a READ can be performed t_{XSNR} (MIN) after the DLL reset. NOP or DESELECT commands must be issued during the t_{XSNR} (MIN) time.

Figure 52: Self Refresh Mode



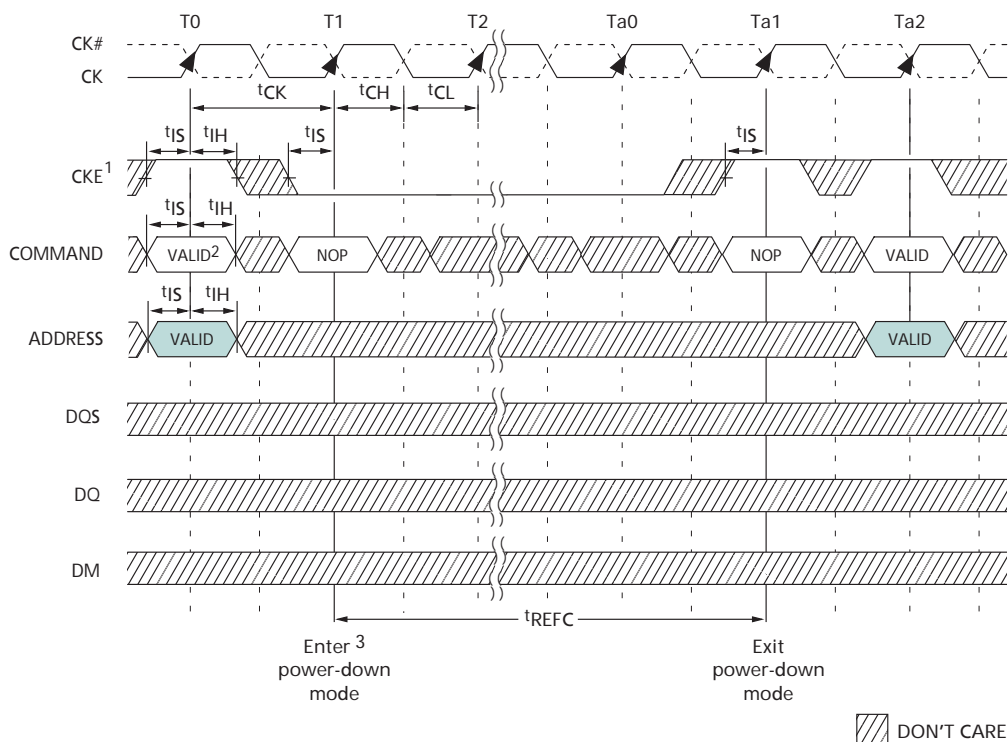
- Notes:
1. Clock must be stable until after the SELF REFRESH command has been registered. A change in clock frequency is allowed before $Ta0$, provided it is within the specified t_{CK} limits. Regardless, the clock must be stable before exiting self refresh mode—that is, the clock must be cycling within specifications by $Ta0$.
 2. NOPs are interchangeable with DESELECT commands.
 3. AUTO REFRESH is not required at this point but is highly recommended.
 4. Device must be in the all banks idle state prior to entering self refresh mode.
 5. t_{XSNR} is required before any non-READ command can be applied; that is only NOP or DESELECT commands are allowed until $Tb1$.
 6. t_{XSRD} (200 cycles of a valid clock with CKE = HIGH) is required before any READ command can be applied.
 7. As a general rule, any time self refresh mode is exited, the DRAM may not re-enter the self refresh mode until all rows have been refreshed via the AUTO REFRESH command at the distributed refresh rate, t_{REFI} , or faster. However, the self refresh mode may be re-entered anytime after exiting if each of the following conditions is met:
 - 7a. The DRAM had been in the self refresh mode for a minimum of 200ms prior to exiting.
 - 7b. t_{XSNR} and t_{XSRD} are not violated.
 - 7c. At least two AUTO REFRESH commands are performed during each t_{REFI} interval while the DRAM remains out of self refresh mode.
 8. If the clock frequency is changed during self refresh mode, a DLL reset is required upon exit.
 9. Once the device is initialized, VREF must always be powered within specified range.

POWER-DOWN (CKE Not Active)

Unlike SDR SDRAMs, DDR SDRAMs require CKE to be active at all times an access is in progress, from the issuing of a READ or WRITE command, until completion of the access. Thus a clock suspend is not supported. For READs, an access completion is defined when the read postamble is satisfied; for WRITEs, when the write recovery time (t_{WR}) is satisfied.

Power-down, as shown in Figure 53, is entered when CKE is registered LOW and all criteria in Table 30 on page 38 are met. If power-down occurs when all banks are idle, this mode is referred to as precharge power-down; if power-down occurs when a row is active in any bank, this mode is referred to as active power-down. Entering power-down deactivates the input and output buffers, excluding CK, CK#, and CKE. For maximum power savings, the DLL is frozen during precharge power-down mode. Exiting power-down requires the device to be at the same voltage and frequency as when it entered power-down. However, power-down duration is limited by the refresh requirements of the device (t_{REFC}).

While in power-down, CKE LOW and a stable clock signal must be maintained at the inputs of the DDR SDRAM, while all other input signals are "Don't Care." The power-down state is synchronously exited when CKE is registered HIGH (in conjunction with a NOP or DESELECT command). A valid executable command may be applied one clock cycle later.

Figure 53: Power-Down Mode


- Notes:
1. Once initialized, VREF must always be powered within the specified range.
 2. If this command is a PRECHARGE (or if the device is already in the idle state), then the power-down mode shown is precharge power-down. If this command is an ACTIVE (or if at least one row is already active), then the power-down mode shown is active power-down.
 3. No column accesses are allowed to be in progress at the time power-down is entered.



8000 S. Federal Way, P.O. Box 6, Boise, ID 83707-0006, Tel: 208-368-3900

prodmktg@micron.com www.micron.com Customer Comment Line: 800-932-4992

Micron, the M logo, and the Micron logo are trademarks of Micron Technology, Inc. All other trademarks are the property of their respective owners.

This data sheet contains minimum and maximum limits specified over the complete power supply and temperature range for production devices. Although considered final, these specifications are subject to change, as further product development and data characterization sometimes occur.