# 5817

## *ADDRESSABLE 28-LINE DECODER/DRIVER*

Intended for use in ink-jet printer applications, the A5817SEP addressable 28-line decoder/driver combines low-power CMOS inputs and logic with 28 high-current, high-voltage bipolar outputs. A 4-to-14 line decoder determines the selected output driver (n) in each 14-driver bank. Two independent output enable inputs (active low) then provide the final decoding to activate 1- or 2-of-28 outputs (OUT$_{An}$ and/or OUT$_{Bn}$). Special internal circuitry is programmed at the time of manufacture to adjust the output pulse timing and thereby the energy the device delivers to the ink-jet print head.

The CMOS inputs cause minimal loading and are compatible with standard CMOS, PMOS, and NMOS logic. Use with TTL or DTL circuits may require appropriate pull-up resistors to ensure an input logic high. The internal CMOS logic operates from a 5 V supply. A CHIP ENABLE function is provided to lock out the drivers during system power up. The 28 bipolar power outputs are open-collector 30 V Darlington drivers capable of sinking 500 mA at ambient temperatures up to 85°C.

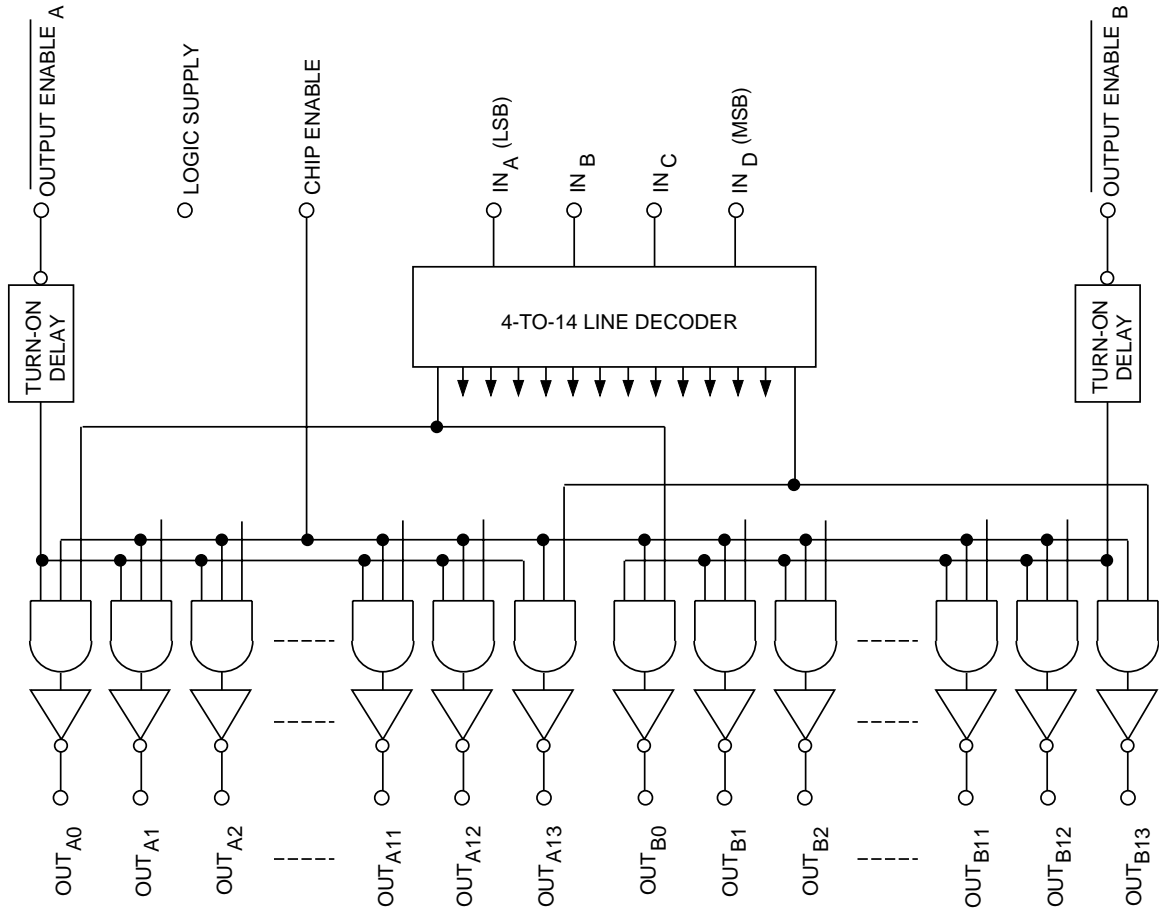The A5817SEP is furnished in a 44-lead plastic chip carrier (quad pack) for minimum-area, surface-mount applications.

## FEATURES

■ Controlled Characteristics for Ink-Jet Printers

■ Addressable Data Entry

■ 30 V Minimum V$_{(BR)CEX}$

■ CMOS, PMOS, NMOS Compatible Inputs

■ Low-Power CMOS Logic



Dwg. PP-050

## ABSOLUTE MAXIMUM RATINGS
### at T$_A$ = 25°C

Output Voltage, V$_{CE}$ ............................. **30 V**

Logic Supply Voltage, V$_{DD}$ .................. **7.0 V**

Input Voltage Range,
    V$_{IN}$ ....................... **-0.3 V to V$_{DD}$ + 0.3 V**

Output Current, I$_C$ ........................... **600 mA**

Package Power Dissipation, P$_D$ ..... **2.70 W\***

Operating Temperature Range,
    T$_A$ ................................. **-20°C to +85°C**

Storage Temperature Range,
    T$_S$ .............................. **-55°C to +150°C**

\*Derate at rate of 22 mW/°C above T$_A$ = 25°C.

*Caution: CMOS devices have input static protection but are susceptible to damage when exposed to extremely high static electrical charges.*

Always order by complete part number: **A5817SEP** .

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## FUNCTIONAL BLOCK DIAGRAM



OUTPUT ENABLE A · LOGIC SUPPLY · CHIP ENABLE · IN A (LSB) · IN B · IN C · IN D (MSB) · OUTPUT ENABLE B

TURN-ON DELAY

4-TO-14 LINE DECODER

TURN-ON DELAY

OUT A0 · OUT A1 · OUT A2 ------ OUT A11 · OUT A12 · OUT A13 · OUT B0 · OUT B1 · OUT B2 ------ OUT B11 · OUT B12 · OUT B13

Dwg. FP-032

## TYPICAL INPUT CIRCUIT



V_DD

IN
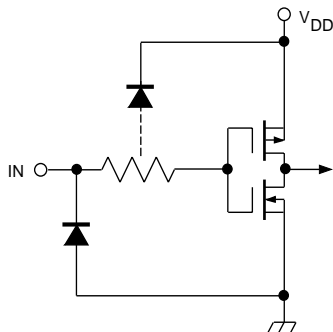
Dwg. EP-010-1

## TYPICAL OUTPUT DRIVER
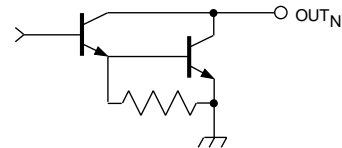


OUT_N

Dwg. EP-021-7



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MicroSystems, Inc.

115 Northeast Cutoff, Box 15036
Worcester, Massachusetts 01615-0036 (508) 853-5000
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# 5817
## *ADDRESSABLE*
## *28-LINE DECODER/DRIVER*

## ELECTRICAL CHARACTERISTICS at $T_A$ = +25$^\circ$C, $V_{DD}$ = 5.0 V.

| Characteristic | Symbol | Test Conditions | Limits | | | Units |
|---|---|---|---|---|---|---|
| | | | Min | Typ | Max | |
| **Output Drivers** | | | | | | |
| Output Leakage Current | $I_{CEX}$ | $V_{CE}$ = 30 V | — | <1.0 | 100 | µA |
| Output Saturation Voltage | $V_{CE(SAT)}$ | $I_{OUT}$ = 450 mA | 0.85 | 1.15 | 1.45 | V |
| | | $I_{OUT}$ = 400 mA | 0.8 | 1.1 | 1.4 | V |
| Output Breakdown Voltage | $V_{(BR)CEX}$ | $R_L$ = 56 Ω | 30 | — | — | V |
| Unclamped Inductive Load Current | — | $V_{CC}$ = 30 V, L = 3 µH, $R_L$ = 56 Ω, $I_L$ = 500 mA, Test Fig. | See Note | | | — |
| Turn-On Time | $t_{PHL}$ | $V_{CC}$ = 21 V, $R_L$ = 39 Ω | 125 | 225 | 475 | ns |
| Fall Time | $t_f$ | $V_{CC}$ = 21 V, $R_L$ = 39 Ω | — | 20 | — | ns |
| Turn-Off Time | $t_{PLH}$ | $V_{CC}$ = 21 V, $R_L$ = 39 Ω | 175 | 250 | 400 | ns |
| Rise Time | $t_r$ | $V_{CC}$ = 21 V, $R_L$ = 39 Ω | — | 50 | — | ns |
| **Control Logic** | | | | | | |
| Logic Input Voltage | $V_{IN(1)}$ | | 3.5 | — | — | V |
| | $V_{IN(0)}$ | | — | — | 0.8 | V |
| Logic Input Current | $I_{IN(1)}$ | $V_{IN}$ = 5.0 V | — | <1.0 | 100 | µA |
| | $I_{IN(0)}$ | $V_{IN}$ = 0 V | — | <-1.0 | -100 | µA |
| Input Resistance | $R_{IN}$ | | 50 | — | — | kΩ |
| Supply Current | $I_{DD(ON)}$ | Two Outputs ON | — | 6.0 | 10.0 | mA |
| | $I_{DD(OFF)}$ | All Drivers OFF, All Inputs = 0 V, $OE_A$ = $OE_B$ = $V_{DD}$ | — | — | 600 | µA |

Note: Device will turn off and meet all specifications after test.

Dwg. EP-044
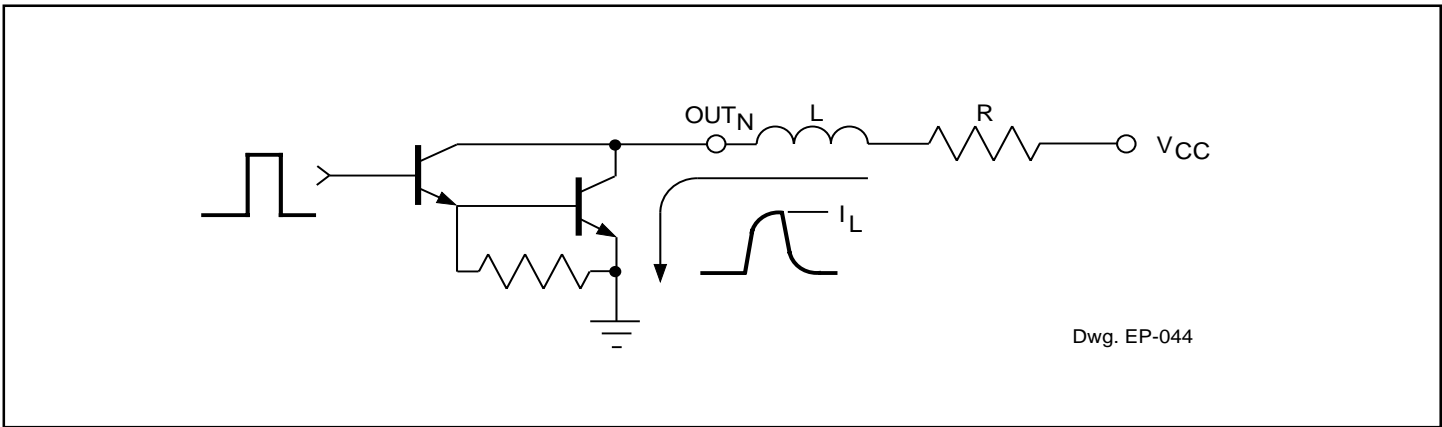
## UNCLAMPED INDUCTIVE LOAD CURRENT TEST FIGURE
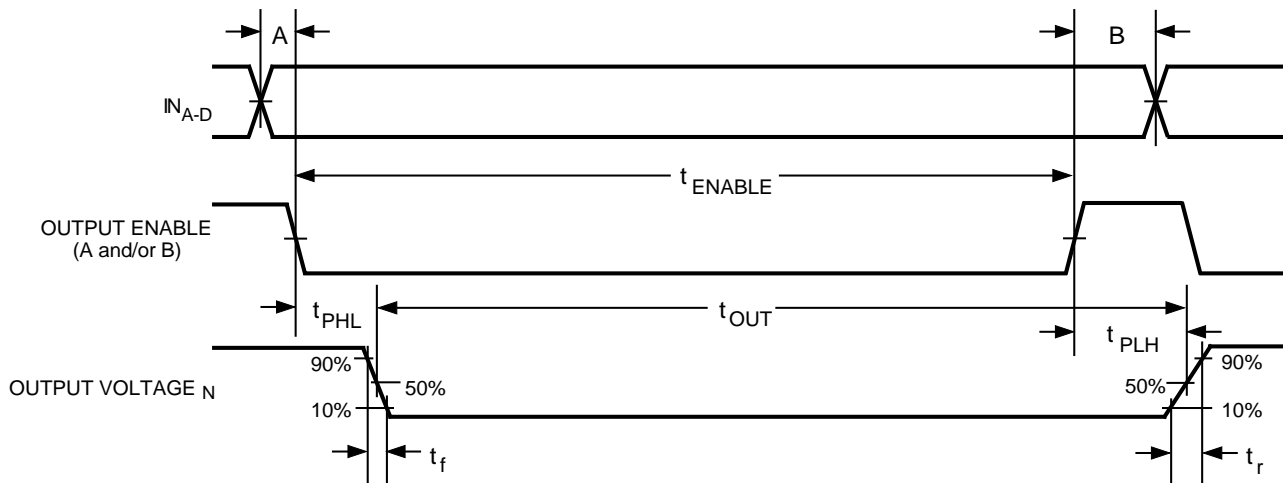


Dwg. WP-017

## TIMING CONDITIONS
(Logic Levels are $V_{DD}$ and Ground)

A. Minimum Data Active Time Before Output Enable (Data Set-Up Time) ............ 150 ns
B. Minimum Data Hold Time After Output Enable (Data Hold Time) .................... 250 ns

## APPLICATIONS INFORMATION

This device is intended specifically for, although certainly not limited to, driving ink-jet print heads. In this application, a certain minimum energy (a function of load voltage and output pulse duration) is required for proper operation, while excessive energy will degrade the life of the print head. The output pulse duration ($t_{OUT}$) is equal to $t_{ENABLE} + t_{PLH} - t_{PHL}$, where $t_{PHL}$ is adjusted during manufacture to compensate for variations in the output saturation voltage ($V_{CE(SAT)}$).

For the A5817SEP, the relationship between $t_{OUT}$ and $t_{ENABLE}$ at $T_A = 25°C$ is:

$$t_{OUT} = t_{ENABLE} ([V_{CE(SAT)}(actual) - V_{CE(SAT)}(typical)]_x \, 330 \text{ ns}) + 25 \text{ ns} + 110 \text{ ns}.$$

For most applications, this will result in a driver-contribution-to-energy-error of less than ±4%.

A logic low on the CHIP ENABLE input will prevent the drivers from turning ON, regardless of the state of other inputs or the logic supply voltage. The CHIP ENABLE input has a slow response time and should not be used as a high-speed control line. For proper operation, all ground terminals should be connected to a common ground on the printed wiring board. The IC (Internal Connection) terminals are used to program the turn-on time of the device and **MUST** be left electrically unconnected (floating) for proper operation.

## DECODER TRUTH TABLE

| $IN_D$ (MSB) | $IN_C$ | $IN_B$ | $IN_A$ (LSB) | N |
|---|---|---|---|---|
| 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 1 | 1 |
| 0 | 0 | 1 | 0 | 2 |
| 0 | 0 | 1 | 1 | 3 |
| 0 | 1 | 0 | 0 | 4 |
| 0 | 1 | 0 | 1 | 5 |
| 0 | 1 | 1 | 0 | 6 |
| 0 | 1 | 1 | 1 | 7 |
| 1 | 0 | 0 | 0 | 8 |
| 1 | 0 | 0 | 1 | 9 |
| 1 | 0 | 1 | 0 | 10 |
| 1 | 0 | 1 | 1 | 11 |
| 1 | 1 | 0 | 0 | 12 |
| 1 | 1 | 0 | 1 | 13 |
| 1 | 1 | 1 | 0 | ALL OFF |
| 1 | 1 | 1 | 1 | ALL OFF |

Depending on the four address inputs, the 4-to-14 line decoder selects one driver from each of the 14 output A and B banks of sink drivers according to the Decoder Truth Table. The state of the selected outputs is determined by the OUTPUT ENABLE inputs as shown in the Enable Truth Table.
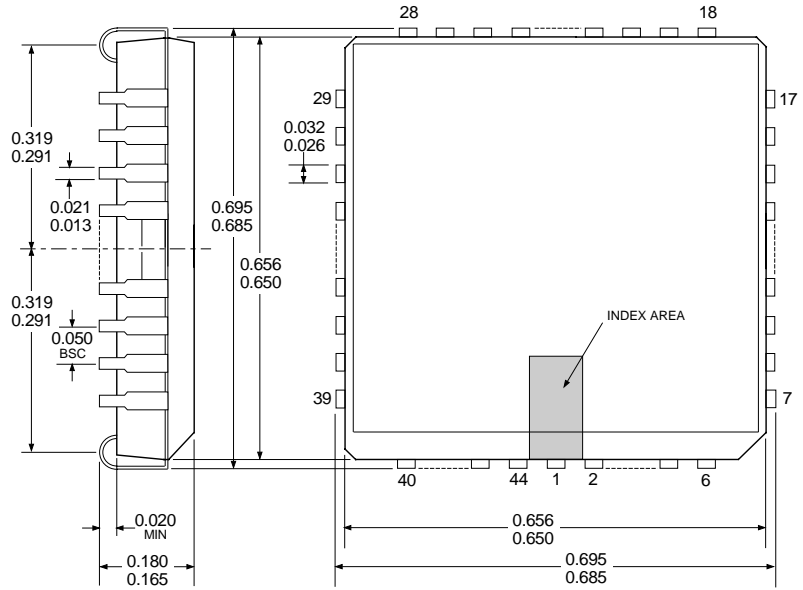
## ENABLE TRUTH TABLE

| CHIP ENABLE | OUTPUT ENABLE$_A$ | OUTPUT ENABLE$_B$ | OUTPUTS (OFF unless otherwise specified. For the value of N see the Decoder Truth Table) |
|---|---|---|---|
| 0 | X | X | ALL OFF |
| 1 | 1 | 1 | ALL OFF |
| 1 | 0 | 1 | OUT$_{AN}$ ON |
| 1 | 1 | 0 | OUT$_{BN}$ ON |
| 1 | 0 | 0 | OUT$_{AN}$ ON, OUT$_{BN}$ ON |

X = Irrelevant

**Dimensions in Inches**
(for reference only)



Dwg. MA-005-44A in

**Dimensions in Millimeters**
(controlling dimensions)
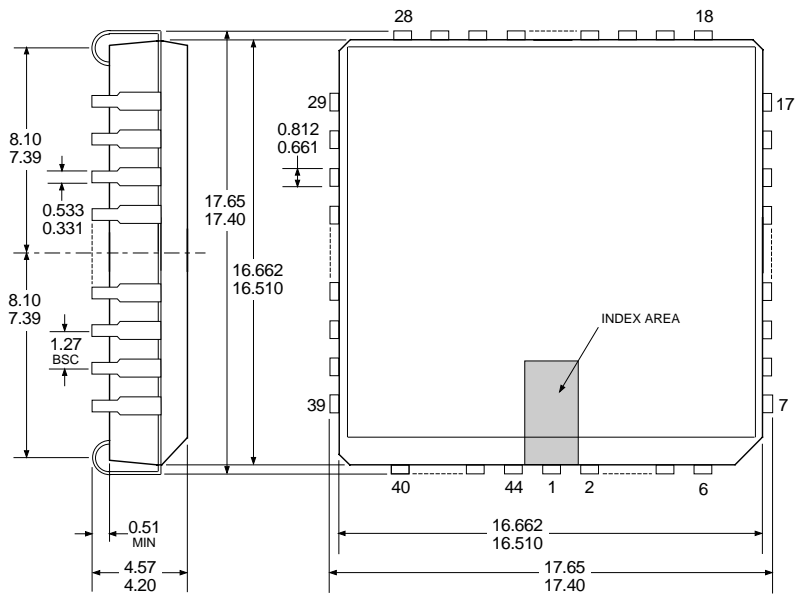


Dwg. MA-005-44A mm

NOTES: 1. Exact body and lead configuration at vendor's option within limits shown.
2. Lead spacing tolerance is non-cumulative.

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MicroSystems, Inc.

115 Northeast Cutoff, Box 15036
Worcester, Massachusetts 01615-0036  (508) 853-5000