

# WAN Multi-Mode Serial Transceiver

#### ■ +5V Only

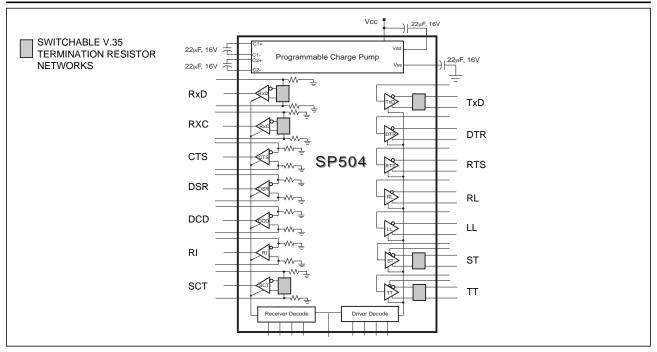
- Seven (7) Drivers and Seven (7) Receivers
- Driver and Receiver Tri-State Control
- Reduced V.35 Termination Network
- Pin Compatible with the SP503
- Software Selectable Interface Modes:
  - -RS-232E (V.28) -RS-422A (V.11, X.21) -RS-449 (V.11 & V.10) -RS-485 -V.35 -EIA-530 (V.11 & V.10) -EIA-530A (V.11 & V.10) -V.36



Now Available in Lead Free

## **DESCRIPTION...**

The **SP504** is a single chip device that supports eight (8) physical serial interface standards for Wide Area Network Connectivity. The **SP504** is fabricated using a low power BiCMOS process technology, and incorporates a **Sipex** patented (5,306,954) charge pump allowing +5V only operation. Seven (7) drivers and seven (7) receivers can be configured via software for any of the above interface modes at any time. The **SP504** is suited for DTE–DCE applications. The **SP504** requires only one external resistor per V.35 driver for compliant V.35 operation.



# **SPECIFICATIONS**

 $\rm T_{\scriptscriptstyle A}$  = +25°C and  $\rm V_{\scriptscriptstyle CC}$  = +5.0V unless otherwise noted.

MIN.	TYP.	MAX.	UNITS	CONDITIONS
2.0		0.8	Volts Volts	
24		0.4		I <sub>OUT</sub> = +3.2mA I <sub>OUT</sub> = –1.0mA
2.1			Volto	OUT TOTING
		0.8	Volts	
2.0			Volts	
			\/alta	
-0.3		+0.0		
±1.5		±5.0	Volts	$R_1 = 54\Omega$ , $C_1 = 50pF$
	±0.2		Volts	R <sub>L</sub> =54Ω, C <sub>L</sub> =50pF  V <sub>T</sub>   -  V <sub>T</sub>
	+2.5			
28.0		±6.0		$R_1 = 54\Omega$
20.0	±250			Terminated in –7V to +10V
	20	40	ns	Rise/fall time, 10%–90%
10			Mbps	$R_{L}=54\Omega$ ; Figure 3a
50	80	100	ne	$T_A^-$ @ 25°C & V <sub>CC</sub> = +5V only Figures 3a and 5; R <sub>1</sub> =54 $\Omega$
				$C_1 = 50 \text{pF}$
	20	40	ns	t <sub>PHL</sub> – t <sub>PLH</sub>  ; T <sub>A</sub> @ +25°C
24		0.4		
2.4			VOIIS	
+0.2		+12	Volts	(a)-(b)
-7.0		-0.2	Volts	(a)-(b)
-7.0		+12.0	Volts	Defer to Deal input graph
				Refer to Rec. input graph Refer to Rec. input graph
		±0.2	Volts	Over –7V to +12V common
				mode range
10			Maps	Figure 3a T <sub>A</sub> = 25°C & V <sub>CC</sub> = +5V only
80	110	180	ns	Figures 3a and 7; A is invert-
80	110	180	ns	ing and B is non-inverting.
	30		ns	t <sub>PHL</sub> – t <sub>PLH</sub>  ; T <sub>A</sub> @ +25°C
		0.8	Volts	All outputs measured w/ 150Ω termination resistor
2.0		0.0	Volts	connected to the non-
				inverting outputs as shown
.0.14		.0.00		in Figure 18.
	100			$R_L = 100\Omega$
135	150	165	$\Omega^{\Sigma^2}$	$V_{OUT} = -2V$ to +2V; A = B
-0.6		+0.6		001
	35	60	ns	48kbps data rate.; T <sub>A</sub> @ 25°C
4.0			R 41	
10			Mbps	$R_L = 100\Omega$
	2.0 2.4 2.0 $-0.3 \pm 1.5$ 28.0 10 50 2.4 +0.2 - 7.0 - 7.0 12 10 80 80 2.0 $\pm 0.44 \pm 50 \\ 135$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\begin{array}{c c c c c c c c c c c c c c c c c c c $

# SPECIFICATIONS (Continued)

 $\rm T_{_{A}}$  = +25°C and  $\rm V_{_{CC}}$  = +5.0V unless otherwise noted.

	MIN.	TYP.	MAX.	UNITS	CONDITIONS
V.35 DRIVER					
Propagation Delay					T <sub>A</sub> @ 25°C & V <sub>CC</sub> = +5V only
t <sub>PHL</sub>	50	80	100	ns	Figures 3b and 5
t <sub>PLH</sub>	50	80	100	ns	-
Differential Driver Skew		30	40	ns	t <sub>PHL</sub> − t <sub>PLH</sub>  ; T <sub>A</sub> @ +25°C
V.35 RECEIVER					
TTL Output Levels					
V <sub>OL</sub>			0.4	Volts	
V <sub>OH</sub>	2.4		_	Volts	
Input					
Differential Threshold		±80		mV	
Input Impedance	90	100	110	Ω	
Short-Circuit Impedance	135	150	165	Ω	$V_{IN} = +2V$ to $-2V$
Max. Transmission Rate	10			Mbps	IN
Propagation Delay	-			- 1 -	T, @ 25°C & V <sub>22</sub> = +5V only
t <sub>PHL</sub>	100	130	200	ns	$T_A @ 25^{\circ}C \& V_{CC} = +5V \text{ only}$ Figure 3b and 7; A is invert-
t <sub>PLH</sub>	100	130	200	ns	ing and B is non-inverting.
Differential Receiver Skew		30		ns	t <sub>PHL</sub> − t <sub>PLH</sub>  ; T <sub>A</sub> @ +25°Č
RS-422 DRIVER (V.11)					
TTL Input Levels					
V <sub>IL</sub>			0.8	Volts	
VIL	2.0		0.0	Volts	
V <sub>IH</sub> Outputs	2.0			VOIIS	
Open Circuit Voltage,Vo			±6.0	Volts	P -2 0k0
Differential Output, $V_{T}$	±2.0		±0.0 ±5.0	Volts	R <sub>L</sub> =3.9kΩ R <sub>I</sub> =100Ω
Differential Output, V <sub>T</sub>			0.67V <sub>0</sub>	Volts	$T_{\Delta} @ +25^{\circ}C$
Balance	0.5V <sub>0</sub>		±0.4	Volts	
Offset			±0.4 +3.0	Volts	$ \dot{V}_{T}  -  \overline{V}_{T} $
Short Circuit Current			±150	mA	$\lambda = 0 \lambda$
Power Off Current			±100		$V_{out} = 0V$ $V_{cc} = 0V, V_{out} = \pm 0.25V$
Transition Time		20	40	μΑ	$v_{cc} = 00$ , $v_{out} = \pm 0.25$ Rise/fall time, 10%-90%
Max. Transmission Rate	10	20	40	ns Mbps	P = 1000; Eiguro 32
Propagation Delay	10			Innha	$R_{L}=100\Omega$ ; Figure 3a
	50	80	100	ne	$T_A^-$ @ 25°C & V <sub>CC</sub> = +5V only Figure 3a and 5;
t <sub>PHL</sub>	50 50	80 80	100	ns	
τ <sub>PLH</sub> Differential Driver Skew	50	20	40	ns	R <sub>DIFF</sub> =100Ω
		20	40	ns	$ t_{PHL}^{-} - t_{PLH} ; T_A @ +25^{\circ}C$
RS-422 RECEIVER (V.11)					
TTL Output Levels					
V <sub>OL</sub>			0.4	Volts	
VOH	2.4			Volts	
input					
HIGH Threshold	+0.2		+6.0	Volts	(a)-(b)
LOW Threshold	-6.0		-0.2	Volts	(a)-(b)
Common Mode Range	-7.0		+7.0	Volts	
HIGH Input Current					Refer to Rec. input graph
LOW Input Current					Refer to Rec. input graph
Receiver Sensitivity			±0.3	Volts	$V_{CM} = +7V$ to $-7V$
Input Impedance	4			kΩ	$V_{IN}^{0.01} = +10V \text{ to } -10V$
Max. Transmission Rate	10			Mbps	
Propagation Delay					$T_{A} @ 25^{\circ}C \& V_{CC} = +5V \text{ only}$
t <sub>PHL</sub>	80	110	180	ns	Figure 3a and 7; A is invert-
t <sub>PLH</sub>	80	110	180	ns	ing and B is non-inverting.
Differential Receiver Skew		30		ns	t <sub>PHL</sub> – t <sub>PLH</sub>  ; T <sub>A</sub> @ +25°C
Differential Receiver Okew					
RS-232 DRIVER (V.28)				I	
RS-232 DRIVER (V.28) TTL Input Level					
RS-232 DRIVER (V.28)			0.8	Volts	

# SPECIFICATIONS (Continued)

 $T_{A} = +25^{\circ}C$  and  $V_{CC} = +5.0V$  unless otherwise noted.

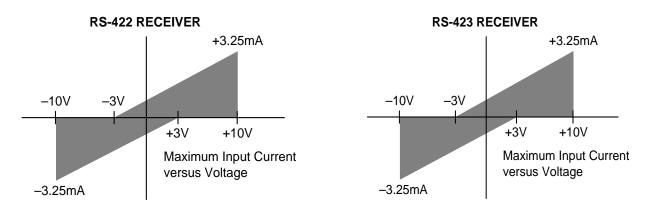
	MIN.	TYP.	MAX.	UNITS	CONDITIONS
RS-232 DRIVER (V.28)					
Outputs					
HIGH Level Output	+5.0		+15	Volts	$R_1 = 3k\Omega, V_{IN} = 0.8V$
LOW Level Output	-15.0		-5.0	Volts	R <sub>L</sub> =3kΩ, V <sub>IN</sub> =0.8V R <sub>L</sub> =3kΩ, V <sub>IN</sub> =2.0V
Open Circuit Voltage	-15		+15	Volts	
Short Circuit Current			±100	mA	$V_{OUT} = 0V$
Power Off Impedance	300			Ω	$V_{cc}^{o} = 0V, V_{out} = \pm 2.0V$ R <sub>L</sub> =3k $\Omega$ , C <sub>L</sub> = 50pF
Slew Rate			30	V/μs	$R_1 = 3k\Omega$ , $C_1 = 50pF$
					V <sub>CC</sub> = +5.0√, T <sub>A</sub> @ +25°C
Transition Time			1.56	μs	R <sub>1</sub> =3kΩ, C <sub>1</sub> =2500pF ;
					between ±3V, T <sub>A</sub> @ +25°C
Max. Transmission Rate	120	230.4		kbps	R <sub>L</sub> =3kΩ, C <sub>L</sub> =2500pF
Propagation Delay					$T_{A}^{-}$ @ 25°C & V <sub>CC</sub> = +5V onl
t <sub>PHL</sub>	0.5	1	4	μs	Measured from 1.5V of V <sub>IN</sub>
t <sub>PLH</sub>	0.5	1	4	μs	to 50% of $V_{OUT}$ ; $R_L=3k\Omega$
RS-232 RECEIVER (V.28)					
TTL Output Levels					
V <sub>OL</sub>			0.4	Volts	
V <sub>OH</sub>	2.4			Volts	
Input					
HIGH Threshold		1.7	3.0	Volts	
LOW Threshold	0.8	1.2		Volts	
Receiver Open Circuit Bias			+2.0	Volts	
Input Impedance	3	5	7	kΩ	V <sub>IN</sub> = +15V to -15V
Max. Transmission Rate	120	230.4		kbps	
Propagation Delay	0.05	0.05			$T_A @ 25^{\circ}C \& V_{CC} = +5V \text{ onl}$
t <sub>PHL</sub>	0.05	0.25	1	μS	Measured from 50% of V <sub>IN</sub>
	0.05	0.25	1	μS	to 1.5V of V <sub>OUT</sub> .
RS-423 DRIVER (V.10)					
TTL Input Levels					
V <sub>IL</sub>			0.8	Volts	
	2.0			Volts	
	.10		.60	Volta	
Open Circuit Voltage, Vo	±4.0 +3.6		±6.0 +6.0	Volts Volts	$R_{L}=3.9k\Omega$
HIGH Level Output, V	-6.0		+0.0 -3.6	Volts	$R_{L} = 450\Omega; V_{OUT} \ge 0.9V_{OC}$
LOW Level Output, V <sub>T</sub>	0.9V <sub>OC</sub>		-3.0	Volts	$R_{L}^{2}=450\Omega; V_{OUT} \ge 0.9V_{OC}^{2}$
Short Circuit Current	0.9 VOC		±150	mA	$T_{A}^{L} = +25^{\circ}C_{,,} V_{CC} = +5.0V$ $V_{OUT} = 0V, V_{CC} = +5.0V$
Power Off Current			±100 ±100	μA	$V_{OUT} = 0V, V_{CC} = +0.0V$ $V_{CC} = 0V, V_{OUT} = \pm 0.25V$
Transition Time			100	ns	Rise/fall time, between $\pm 3V$
Max. Transmission Rate	120		100	kbps	$R_1 = 450\Omega$
Propagation Delay				nope	$T_{A} @ 25^{\circ}C \& V_{CC} = +5V \text{ onl}$
t <sub>PHL</sub>	0.05	0.5	2	μS	Measured from 1.5V of V <sub>IN</sub>
	0.05	0.5	2	μS	to 50% of $V_{OUT}$ ; $R_L = 450 \Omega^{\parallel N}$
RS-423 RECEIVER (V.10)					
TTL Output Levels					
Vol			0.4	Volts	
	2.4			Volts	
Input					
HIGH Threshold	+0.3		+7.0	Volts	
LOW Threshold	-7.0		-0.3	Volts	
HIGH Input Current					Refer to Rec. input graph
LOW Input Current					Refer to Rec. input graph
			±0.3	Volts	$V_{CM} = +7V$ to $-7V$
Receiver Sensitivity					
Receiver Sensitivity Input Impedance	4			kΩ	$V_{IN}^{OM}$ = +10V to -10V
Receiver Sensitivity	4 120			kΩ kbps	$V_{IN}^{OM} = +10V \text{ to } -10V$

#### SPECIFICATIONS (Continued)

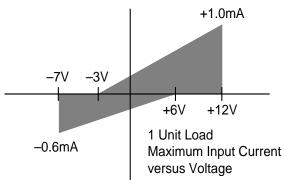
 $\rm T_{_{A}}$  = +25°C and  $\rm V_{_{CC}}$  = +5.0V unless otherwise noted.

	MIN.	TYP.	MAX.	UNITS	CONDITIONS
RS-423 RECEIVER (V.10)					
Propagation Delay					T <sub>A</sub> @ 25°C & V <sub>CC</sub> = +5V only
t <sub>PHL</sub>	0.05	0.2	1	μS	Measured from 50% of V <sub>IN</sub>
t <sub>PLH</sub>	0.05	0.2	1	μS	to 1.5V of V <sub>OUT</sub>
POWER REQUIREMENTS					
V <sub>cc</sub>	4.75	5.00	5.25	Volts	
I <sub>CC</sub> (no interface selected)		30		mA	V <sub>CC</sub> =5.0V
(RS-232 Mode)		140		mA	f <sub>IN</sub> = 120kbps. Drivers loaded.
(RS-422 Mode)		320		mA	$f_{IN} = 2Mbps.$ Drivers loaded.
(RS-449 Mode)		320		mA	$f_{IN} = 2Mbps.$ Drivers loaded.
(EIA-530 Mode)		320		mA	$f_{IN} = 2Mbps.$ Drivers loaded.
(EIA-530A Mode)		320		mA	$f_{IN} = 2Mbps.$ Drivers loaded.
(RS-485 Mode)		370		mA	$f_{IN} = 2Mbps.$ Drivers loaded.
(V.35 Mode)		210 310		mA mA	$f_{IN} = 2Mbps.$ Drivers loaded.
(V.36 Mode)		310		IIIA	$f_{IN} = 2Mbps.$ Drivers loaded.
ENVIRONMENTAL AND ME					
Operating Temperature Range			+70	°C	
Storage Temperature Range			+150	⊃°	
Package		, 30–pin QFI		Ũ	

# **RECEIVER INPUT GRAPHS**



**RS-485 RECEIVER** 



## **ABSOLUTE MAXIMUM RATINGS**

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

V <sub>cc</sub> +7V
Input Voltages:
Logic0.3V to (V <sub>cc</sub> +0.5V)
Drivers0.3V to (V <sub>cc</sub> +0.5V)
Receivers±15V
Output Voltages:
Logic0.3V to (V <sub>cc</sub> +0.5V)
Drivers±14V
Receivers0.3V to ( $V_{cc}$ +0.5V)
Storage Temperature65°C to +150°C
Power Dissipation2000mW

Package Derating:

Ø ,	46°C/W
	16 °C/W

#### STORAGE CONSIDERATIONS

Due to the relatively large package size of the 80-pin quad flat-pack, storage in a low humidity environment is preferred. Large high density plastic packages are moisture sensitive and should be stored in Dry Vapor Barrier Bags. Prior to usage, the parts should remain bagged and stored below 40°C and 60%RH. If the parts are removed from the bag, they should be used within 48 hours or stored in an environment at or below 20%RH. If the above conditions cannot be followed, the parts should be baked for four hours at 125°C in order remove moisture prior to soldering. Sipex ships the 80-pin QFP in Dry Vapor Barrier Bags with a humidity indicator card and desiccant pack. The humidity indicator should be below 30%RH.

# **OTHER AC CHARACTERISTICS**

 $T_A = +70^{\circ}C$  to 0°C and  $V_{cc} = +4.75V$  to +5.25V unless otherwise noted

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITIONS
DRIVER DELAY TIME BETWEE	N ACTIV	E MODE A	ND TRI-S	TATE MODE	
RS-232 MODE					
t <sub>PZL</sub> ; Tri-state to Output LOW		0.70	5.0	μs	C <sub>L</sub> = 100pF, Fig. 4 ; S <sub>2</sub> closed
t <sub>PZH</sub> ; Tri-state to Output HIGH		0.40	2.0	μs	$C_L = 100 pF$ , Fig. 4 ; $S_2$ closed
t <sub>PLZ</sub> ; Output LOW to Tri-state		0.20	2.0	μS	C <sub>L</sub> = 100pF, Fig. 4 ; S <sub>2</sub> closed
t <sub>PHZ</sub> ; Output HIGH to Tri-state		0.40	2.0	μs	$C_L = 100 pF$ , Fig. 4 ; $S_2$ closed
RS-423 MODE					
t <sub>PZL</sub> ; Tri-state to Output LOW		0.15	2.0	μs	$C_L = 100 pF$ , Fig. 4 ; $S_2$ closed
t <sub>PZH</sub> ; Tri-state to Output HIGH		0.20	2.0	μs	$C_L = 100 pF$ , Fig. 4 ; $S_2$ closed
t <sub>PLZ</sub> ; Output LOW to Tri-state		0.20	2.0	μS	$C_L = 100 pF$ , Fig. 4 ; $S_2$ closed
t <sub>PHZ</sub> ; Output HIGH to Tri-state		0.15	2.0	μS	C <sub>L</sub> = 100pF, Fig. 4 ; S <sub>2</sub> closed
RS-422, RS-485 MODES					
t <sub>PZL</sub> ; Tri-state to Output LOW		2.80	10.0	μS	C <sub>L</sub> = 100pF, Fig. 4 & 6; S <sub>1</sub> closed
t <sub>PZH</sub> ; Tri-state to Output HIGH		0.10	2.0	μS	C <sub>L</sub> = 100pF, Fig. 4 & 6; S <sub>2</sub> closed
t <sub>PLZ</sub> ; Output LOW to Tri-state		0.10	2.0	μS	C <sub>L</sub> = 15pF, Fig. 4 & 6; S <sub>1</sub> closed
t <sub>PHZ</sub> ; Output HIGH to Tri-state		0.10	2.0	μs	C <sub>L</sub> = 15pF, Fig. 4 & 6; S <sub>2</sub> closed
V.35 MODE					
t <sub>PZL</sub> ; Tri-state to Output LOW		2.60	10.0	μs	C <sub>L</sub> = 100pF, Fig. 4 & 6; S <sub>1</sub> closed
t <sub>PZH</sub> ; Tri-state to Output HIGH		0.10	2.0	μs	$C_L = 100 pF$ , Fig. 4 & 6; $S_2$ closed

# OTHER AC CHARACTERISTICS (Continued)

 $T_{*} = +70^{\circ}$ C to 0°C and  $V_{cc} = +4.75$ V to +5.25V unless otherwise noted.

PARAMETER	MIN.	TYP.	MAX.	UNITS	CONDITIONS
V.35 MODE					
t <sub>PLZ</sub> ; Output LOW to Tri-state		0.10	2.0	μS	C <sub>L</sub> = 15pF, Fig. 4 & 6; S <sub>1</sub> closed
$t_{PHZ}$ ; Output HIGH to Tri-state		0.15	2.0	μS	C <sub>L</sub> = 15pF, Fig. 4 & 6; S <sub>2</sub> closed
RECEIVER DELAY TIME BETW	EEN AC		E AND TR	I-STATE MOD	E
RS-232 MODE					
t <sub>PZL</sub> ; Tri-state to Output LOW		0.12	2.0	μs	C <sub>L</sub> = 100pF, Fig. 2 ; S <sub>1</sub> closed
t <sub>PZH</sub> ; Tri-state to Output HIGH		0.10	2.0	μs	$C_L = 100 pF$ , Fig. 2 ; $S_2$ closed
t <sub>PLZ</sub> ; Output LOW to Tri-state		0.10	2.0	μS	C <sub>L</sub> = 100pF, Fig. 2 ; S <sub>1</sub> closed
t <sub>PHZ</sub> ; Output HIGH to Tri-state		0.10	2.0	μS	C <sub>L</sub> = 100pF, Fig. 2 ; S <sub>2</sub> closed
RS-423 MODE					
t <sub>PZL</sub> ; Tri-state to Output LOW		0.10	2.0	μs	C <sub>L</sub> = 100pF, Fig. 2 ; S <sub>1</sub> closed
t <sub>PZH</sub> ; Tri-state to Output HIGH		0.10	2.0	μs	$C_L = 100 pF$ , Fig. 2 ; $S_2$ closed
t <sub>PLZ</sub> ; Output LOW to Tri-state		0.10	2.0	μs	C <sub>L</sub> = 100pF, Fig. 2 ; S <sub>1</sub> closed
t <sub>PHZ</sub> ; Output HIGH to Tri-state		0.10	2.0	μs	C <sub>L</sub> = 100pF, Fig. 2 ; S <sub>2</sub> closed
RS-422/RS-485 MODES					
t <sub>PZL</sub> ; Tri-state to Output LOW		0.10	2.0	μs	C <sub>L</sub> = 100pF, Fig. 2 & 8 ; S <sub>1</sub> closed
t <sub>PZH</sub> ; Tri-state to Output HIGH		0.10	2.0	μs	C <sub>L</sub> = 100pF, Fig. 2 & 8 ; S <sub>2</sub> closed
t <sub>PLZ</sub> ; Output LOW to Tri-state		0.10	2.0	μs	C <sub>L</sub> = 15pF, Fig. 2 & 8 ; S <sub>1</sub> closed
t <sub>PHZ</sub> ; Output HIGH to Tri-state		0.10	2.0	μs	$C_L = 15pF$ , Fig. 2 & 8; $S_2$ closed
V.35 MODE					
t <sub>PZL</sub> ; Tri-state to Output LOW		0.10	2.0	μS	C <sub>L</sub> = 100pF, Fig. 2 & 8; S <sub>1</sub> closed
t <sub>PZH</sub> ; Tri-state to Output HIGH		0.10	2.0	μs	C <sub>L</sub> = 100pF, Fig. 2 & 8; S <sub>2</sub> closed
t <sub>PLZ</sub> ; Output LOW to Tri-state		0.10	2.0	μs	C <sub>L</sub> = 15pF, Fig. 2 & 8; S <sub>1</sub> closed
t <sub>PHZ</sub> ; Output HIGH to Tri-state		0.10	2.0	μs	C <sub>L</sub> = 15pF, Fig. 2 & 8; S <sub>2</sub> closed
TRANSCEIVER TO TRANSCEI	VER SKE	W [(t	- t <sub>nib</sub> )-	– (t <sub>phl</sub> – t <sub>plh</sub> ) <sub>Trcvr</sub>	v]
RS-232 Driver		20	50		$V_{cc} = +5.0V, T_{A} @ +25^{\circ}C$
RS-232 Receiver		20		ns	
RS-422 Driver		20	50	ns	V <sub>CC</sub> = +5.0V, T <sub>A</sub> @ +25°C
RS-422 Receiver		20		ns	
RS-423 Driver		20	50	ns	V <sub>CC</sub> = +5.0V, T <sub>A</sub> @ +25°C
RS-423 Receiver		20		ns	
V.35 Driver		20	50	ns	V <sub>CC</sub> = +5.0V, T <sub>A</sub> @ +25°C
V.35 Receiver		20		ns	

Rev: A Date:1/27/04

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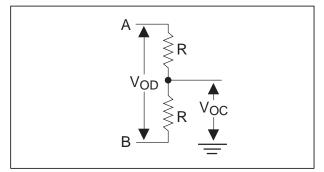


Figure 1. Driver DC Test Load Circuit

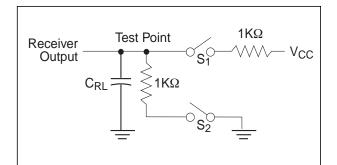


Figure 2. Receiver Timing Test Load Circuit

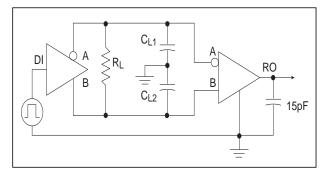


Figure 3a. Driver/Receiver Timing Test Circuit

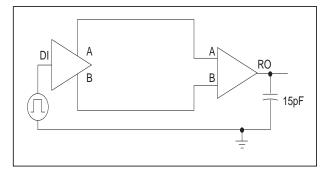


Figure 3b. Timing Test Ckt. (V.35 mode only for SP504)

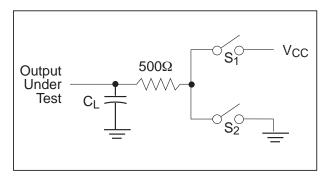


Figure 4. Driver Timing Test Load #2 Circuit

Note : Figures 3a and 3b shown above are used for evaluating maximum transmission rate. For 10Mbps transmission rate, an input signal of 5MHz is applied to the driver input. In order for a valid transmission rate, the driver output must adhere to the output electrical specifications (V<sub>OH</sub> & V<sub>OL</sub>) and an acceptable duty cycle for the protocol tested. The receiver outputs are checked for proper TTL/CMOS V<sub>OH</sub> & V<sub>OL</sub> levels and an acceptable output duty cycle.

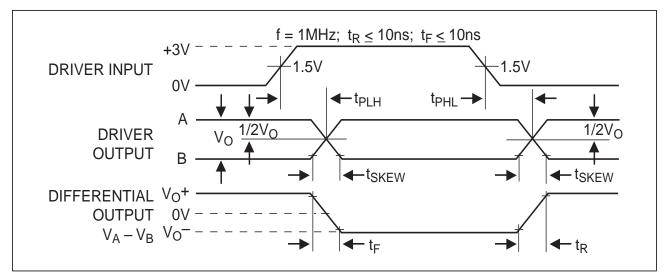


Figure 5. Driver Propagation Delays

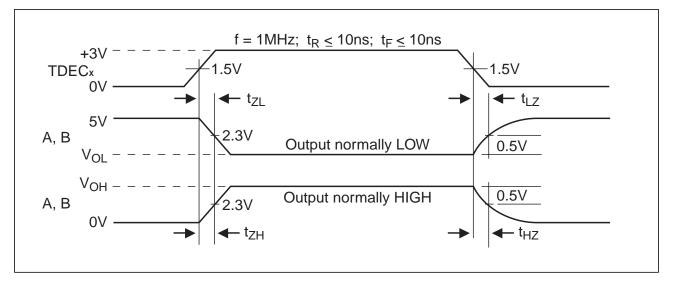
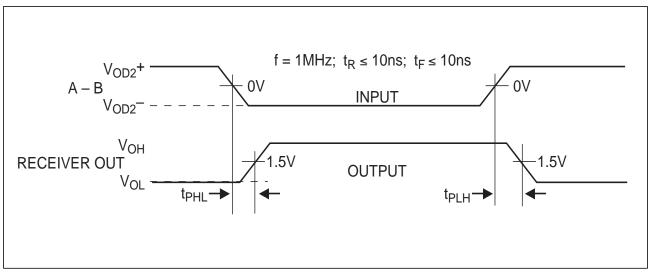


Figure 6. Driver Enable and Disable Times



#### Figure 7. Receiver Propagation Delays

Note : Figures 5 and 7 shown above are corrected from the original SP504 databaset. Both figures were incorrect on the original datasheet where the driver output from Figure 5 and the receiver output from Figure 7 are inverted signals.

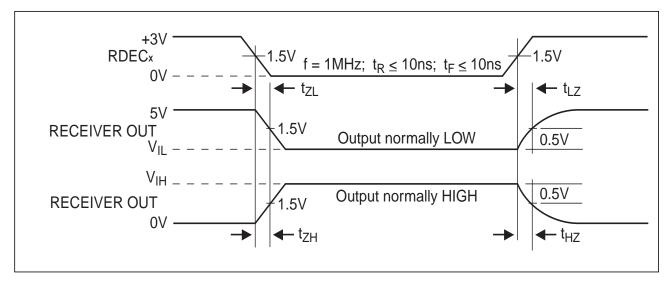


Figure 8. Receiver Enable and Disable Times

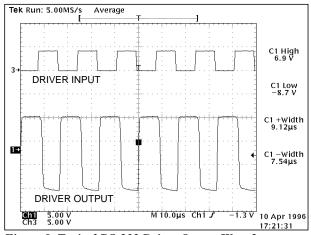


Figure 9. Typical RS-232 Driver Output Waveform

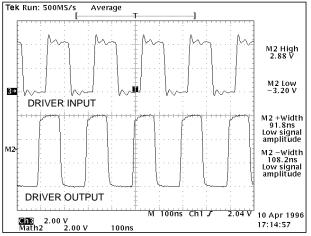


Figure 11. Typical RS-422/485 Driver Output Waveform

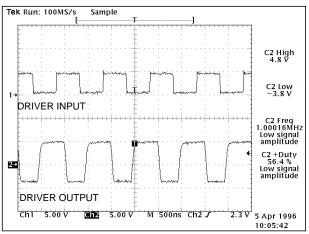
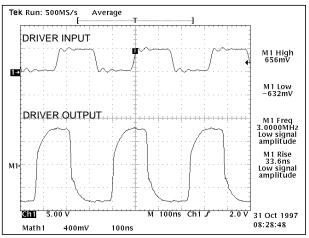
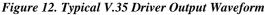
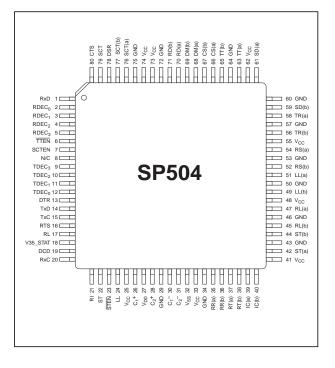


Figure 10. Typical RS-423 Driver Output Waveform







#### PIN ASSIGNMENTS... CLOCK AND DATA GROUP

Pin 1 — RxD — Receive Data; TTL output, sourced from RD(a) and RD(b) inputs.

Pin 14 — TxD — TTL input ; transmit data source for SD(a) and SD(b) outputs.

Pin 15 — TxC — Transmit Clock; TTL input for TT driver outputs.

Pin 20 — RxC — Receive Clock; TTL output sourced from RT(a) and RT(b) inputs.

Pin 22 — ST — Send Timing; TTL input; source for ST(a) and ST(b) outputs.

Pin 37 — RT(a) — Receive Timing; analog input, inverted; source for RxC.

Pin 38 — RT(b) — Receive Timing; analog input, non-inverted; source for RxC.

Pin 42 — ST(a) — Send Timing; analog output, inverted; sourced from ST.

Pin 44 — ST(b) — Send Timing; analog output, non-inverted; sourced from ST.

Pin 59 — SD(b) — Analog Out — Send data, non-inverted; sourced from TxD.

Pin 61 — SD(a) — Analog Out — Send data, inverted; sourced from TxD.

Pin 63 — TT(a) — Analog Out — Terminal Timing, inverted; sourced from TxC

Pin 65 — TT(b) — Analog Out — Terminal Timing, non–inverted; sourced from TxC.

Pin 70 — RD(a) — Receive Data, analog input; inverted; source for RxD.

Pin 71 — RD(b) — Receive Data; analog input; non-inverted; source for RxD.

Pin 76 — SCT(a) — Serial Clock Transmit; analog input, inverted; source for SCT.

Pin 77 — SCT(b) — Serial Clock Transmit: analog input, non–inverted; source for SCT

Pin 79 — SCT — Serial Clock Transmit; TTL output; sources from SCT(a) and SCT(b) inputs.

## **CONTROL LINE GROUP**

Pin 13 — DTR — Data Terminal Ready; TTL input; source for TR(a) and TR(b) outputs.

Pin 16 — RTS — Ready To Send; TTL input; source for RS(a) and RS(b) outputs.

Pin 17 — RL — Remote Loopback; TTL input; source for RL(a) and RL(b) outputs.

Pin 18 — V35\_STAT — V.35 Status; TTL output; outputs logic high when in V.35 mode.

Pin 19 — DCD— Data Carrier Detect; TTL output; sourced from RR(a) and RR(b) inputs.

Pin 21 — RI — Ring Indicate; TTL output; sourced from IC(a) and IC(b) inputs.

Pin 24 — LL — Local Loopback; TTL input; source for LL(a) and LL(b) outputs.

Pin 35 — RR(a)— Receiver Ready; analog input, inverted; source for DCD.

Pin 36 — RR(b)— Receiver Ready; analog input, non-inverted; source for DCD.

Pin 39 — IC(a)— Incoming Call; analog input, inverted; source for RI.

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Pin 40 — IC(b)— Incoming Call; analog input, non-inverted; source for RI.

Pin 45 — RL(b) — Remote Loopback; analog output, non-inverted; sourced from RL.

Pin 47 — RL(a) — Remote Loopback; analog output inverted; sourced from RL.

Pin 49— LL(b) — Local Loopback; analog output, non-inverted; sourced from LL.

Pin 51 — LL(a) — Local Loopback; analog output, inverted; sourced from LL.

Pin 52 — RS(b) — Ready To Send; analog output, non-inverted; sourced from RTS.

Pin 54 — RS(a) — Ready To Send; analog output, inverted; sourced from RTS.

Pin 56 — TR(b) — Terminal Ready; analog output, non-inverted; sourced from DTR.

Pin 58 — TR(a) — Terminal Ready; analog output, inverted; sourced from DTR.

Pin 66 — CS(a) — Clear To Send; analog input, inverted; source for CTS.

Pin 67 — CS(b)— Clear To Send; analog input, non-inverted; source for CTS.

Pin 68 — DM(a)— Data Mode; analog input, inverted; source for DSR.

Pin 69 — DM(b)— Data Mode; analog input, non-inverted; source for DSR

Pin 78 — DSR— Data Set Ready; TTL output; sourced from DM(a), DM(b) inputs.

Pin 80 — CTS— Clear To Send; TTL output; sourced from CS(a) and CS(b) inputs.

#### **CONTROL REGISTERS**

Pins  $2-5 - RDEC_0 - RDEC_3 - Receiver decode register; configures receiver modes; TTL inputs.$ 

Pin 6 — TTEN — Enables TT driver, active low; TTL input.

Pin 7 — SCTEN — Enables SCT receiver; active high; TTL input.

Pins 12-9 — TDEC<sub>0</sub> – TDEC<sub>3</sub> — Transmitter decode register; configures transmitter modes; TTL inputs.

Pin 23 — STEN — Enables ST driver; active low; TTL input.

#### **POWER SUPPLIES**

Pins 25, 33, 41, 48, 55, 62, 73, 74 — V<sub>CC</sub> — +5V input.

Pins 29, 34, 43, 46, 50, 53, 57, 60, 64, 72, 75 — GND — Ground.

Pin 27 —  $V_{DD}$  +10V Charge Pump Capacitor — Connects from  $V_{DD}$  to  $V_{CC}$ . Suggested capacitor size is 22 $\mu$ F, 16V.

Pin 32 —  $V_{SS}$  –10V Charge Pump Capacitor — Connects from ground to  $V_{SS}$ . Suggested capacitor size is 22µF, 16V.

Pins 26 and 30 —  $C_1^+$  and  $C_1^-$  — Charge Pump Capacitor — Connects from  $C_1^+$  to  $C_1^-$ . Suggested capacitor size is 22µF, 16V.

Pins 28 and 31 —  $C_2^+$  and  $C_2^-$  — Charge Pump Capacitor — Connects from  $C_2^+$  to  $C_2^-$ . Suggested capacitor size is 22µF, 16V.

NOTE: NC pins should be left floating; internal signals may be present.

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### FEATURES...

The **SP504** is a highly integrated serial transceiver that allows software control of its interface modes. Similar to the SP503, the **SP504** offers the same hardware interface modes for RS-232 (V.28), RS-422A (V.11), RS-449, RS-485, V.35, EIA-530 and includes V.36 and EIA-530A. The interface mode selection is done via an 8-bit switch; four (4) bits control the drivers and four (4) bits control the receivers. The **SP504** is fabricated using low power BiCMOS process technology, and incorporates a **Sipex** patented (5,306,954) charge pump allowing +5V only operation. Each device is packaged in an 80-pin JEDEC Quad FlatPack package.

The **SP504** is ideally suited for wide area network connectivity based on the interface modes offered and the driver and receiver configurations. The **SP504** has seven (7) independent drivers and seven (7) independent receivers. In V.35 mode, the **SP504** includes the necessary components and termination resistors internal within the device for compliant V.35 operation.

#### THEORY OF OPERATION

The **SP504** is made up of five separate circuit blocks — the charge pump, drivers, receivers, decoder and switching array. Each of these circuit blocks is described in more detail below.

#### Charge–Pump

The **SP504**'s charge pump design is based on the SP503 where **Sipex**'s patented charge pump design (5,306,954) uses a four–phase voltage shifting technique to attain symmetrical ±10V power supplies. In addition, the **SP504** charge pump incorporates a "programmable" feature that produces an output of ±10V or ±5V for V<sub>SS</sub> and V<sub>DD</sub> depending on the mode of operation. The charge pump still requires external capacitors to store the charge. *Figure 17a* shows the waveform found on the positive side of capacitor C2, and *Figure 17b* shows the negative side of capcitor C2. There is a free–running oscillator that controls the four phases of the voltage shifting. A description of each phase follows.

The **SP504** charge pump is used for RS-232 where the output voltage swing is typically  $\pm 10V$  and also used for RS-423. However, RS-

423 requires the voltage swing on the driver output be between  $\pm 4V$  to  $\pm 6V$  during an open circuit (no load). The charge pump would need to be regulated down from  $\pm 10V$  to  $\pm 5V$ . A typical  $\pm 10V$  charge pump would require external clamping such as 5V zener diodes on V<sub>DD</sub> and V<sub>SS</sub> to ground. The  $\pm 5V$  output has symmetrical levels as in the  $\pm 10V$  output. The  $\pm 5V$ is used in the following modes where RS-423 levels are used: RS-449, EIA-530, EIA-530A and V.36.

#### Phase 1 (±10V)

—  $V_{ss}$  charge storage — During this phase of the clock cycle, the positive side of capacitors  $C_1$  and  $C_2$  are initially charged to +5V. The  $C_1^+$ is then switched to ground and the charge on  $C_1^$ is transferred to  $C_2^-$ . Since  $C_2^+$  is connected to +5V, the voltage potential across capacitor  $C_2$  is now 10V.

#### Phase 1 (±5V)

—  $V_{SS} & V_{DD}$  charge storage and transfer — With the  $C_1$  and  $C_2$  capacitors initially charged to +5V,  $C_1^+$  is then switched to ground and the charge on  $C_1^-$  is transferred to the  $V_{SS}$  storage capacitor. Simultaneously the  $C_2^-$  is switched to ground and the 5V charge on  $C_2^+$  is transferred to the  $V_{DD}$  storage capacitor.

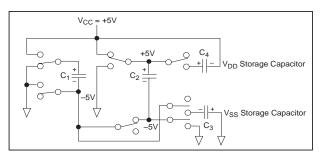


Figure 13a. Charge Pump Phase 1 for ±10V.

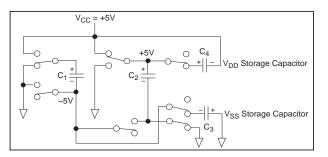


Figure 13b. Charge Pump Phase 1 for ±5V.

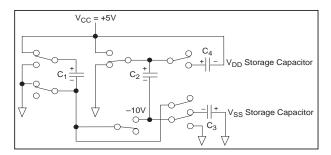


Figure 14a. Charge Pump Phase 2 for ±10V.

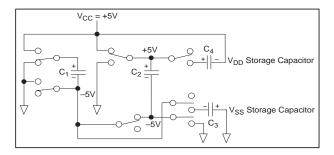


Figure 15. Charge Pump Phase 3.

#### Phase 2 (±10V)

—  $V_{SS}$  transfer — Phase two of the clock connects the negative terminal of  $C_2$  to the  $V_{SS}$  storage capacitor and the positive terminal of  $C_2$  to ground, and transfers the generated –10V or the generated –5V to  $C_3$ . Simultaneously, the positive side of capacitor  $C_1$  is switched to +5V and the negative side is connected to ground.

#### Phase 2 (±5V)

—  $V_{SS}$  &  $V_{DD}$  charge storage —  $C_1^+$  is reconnected to  $V_{CC}$  to recharge the  $C_1$  capacitor.  $C_2^+$  is switched to ground and  $C_2^-$  is connected to  $C_3$ . The 5V charge from Phase 1 is now transferred

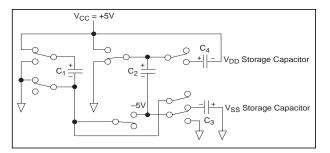


Figure 14b. Charge Pump Phase 2 for ±5V.

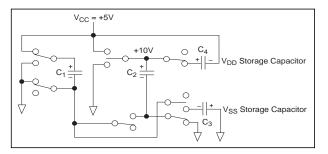


Figure 16. Charge Pump Phase 4.

to the  $V_{SS}$  storage capacitor.  $V_{SS}$  receives a continuous charge from either  $C_1$  or  $C_2$ . With the C1 capacitor charged to 5V, the cycle begins again.

#### Phase 3

—  $V_{DD}$  charge storage — The third phase of the clock is identical to the first phase — the charge transferred in C<sub>1</sub> produces –5V in the negative terminal of C<sub>1</sub>, which is applied to the negative side of capacitor C<sub>2</sub>. Since C<sub>2</sub><sup>+</sup> is at +5V, the voltage potential across C<sub>2</sub> is 10V. For the 5V output, C<sub>2</sub><sup>+</sup> is connected to ground so that the potential on C<sub>2</sub> is only +5V.

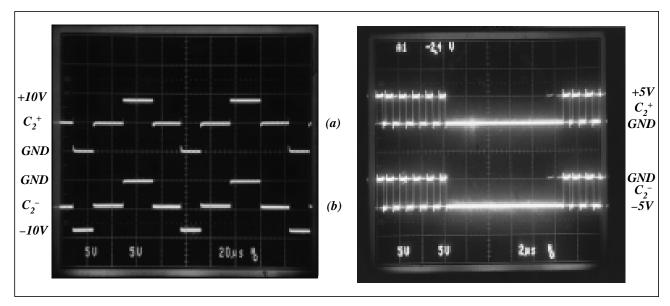


Figure 17. Charge Pump Waveforms

Since both  $V_{DD}$  and  $V_{SS}$  are separately generated from  $V_{CC}$  in a no-load condition,  $V_{DD}$  and  $V_{SS}$  will be symmetrical. Older charge pump approaches that generate V<sup>-</sup> from V<sup>+</sup> will show a decrease in the magnitude of V<sup>-</sup> compared to V<sup>+</sup> due to the inherent inefficiencies in the design.

The clock rate for the charge pump typically operates at 15kHz. The external capacitors must be a minimum of  $22\mu$ F with a 16V breakdown rating.

#### **External Power Supplies**

For applications that do not require +5V only, external supplies can be applied at the V+ and V<sup>-</sup> pins. The value of the external supply voltages must be no greater than  $\pm 10.5V$ . The tolerance should be  $\pm 5\%$  from  $\pm 10V$ . The current drain for the supplies is used for RS-232 and RS-423 drivers. For the RS-232 driver, the current requirement will be 3.5mA per driver. The RS-423 driver worst case current drain will be 11mA per driver. Power sequencing is required for the **SP504**. The supplies must be sequenced accordingly:  $\pm 10V$ ,  $\pm 5V$  and  $\pm 10V$ . An external circuit would be needed for proper power supply sequencing. Consult factory for application circuitry.

#### Drivers

The **SP504** has seven (7) enhanced independent drivers. Control for the mode selection is done via a four–bit control word. The drivers are prearranged such that for each mode of operation, the relative position and functionality of the drivers are set up to accommodate the selected interface mode. As the mode of the drivers is changed, the electrical characteristics will change to support the requirements of clock, data, and control line signal levels. *Table 1* shows the mode of each driver in the different interface modes that can be selected.

There are four basic types of driver circuits — RS-232, RS-423, RS-485 and V.35.

The RS-232 drivers output single–ended signals with a minimum of  $\pm 5V$  (with  $3k\Omega$  and 2500pF loading), and can operate up to 120kbps.

The RS-232 drivers are used in RS-232 mode for all signals, and also in V.35 mode where they are used as the control line signals such as DTR and RTS.

The RS-423 drivers are also single–ended signals with a minimum voltage output of  $\pm 3.6V$  (with 450 $\Omega$  loading) and can operate up to 120kbps. Open circuit V<sub>OL</sub> and V<sub>OH</sub> measurements are  $\pm 4.0V$  to  $\pm 6.0V$ . The RS-423 drivers are used in RS-449, EIA-530, EIA-530A and V.36 modes as Category II signals from each of their corresponding specifications.

The third type of driver produces a differential signal that can maintain RS-485,  $\pm 1.5$ V differential output levels with a worst case load of 54 $\Omega$ . The signal levels and drive capability of the RS-485 drivers allow the drivers to also support RS-422 (V.11) requirements of  $\pm 2$ V differential output levels with 100 $\Omega$  loads. The RS-422 drivers are used in RS-449, EIA-530, EIA-530A and V.36 modes as Category I signals which are used for clock and data.

The fourth type of driver is the V.35 driver. V.35 levels require ±0.55V driver output signals with a load of  $100\Omega$ . The **SP504** drivers simplify existing V.35 implementations that use external termination schemes. The drivers were specifically designed to comply with the requirements of V.35 as well as the driver output impedance values of V.35. The drivers achieve the 50 $\Omega$  to 150 $\Omega$  source impedance. However, an external 150 $\Omega$  resistor to ground must be connected to the non-inverting outputs; SD(b), ST(b), and TT(b), in order to comply with the  $135\Omega$  to  $165\Omega$  short-circuit impedance for V.35. The V.35 driver itself is disabled and transparent when the decoder is in all other modes. All of the differential drivers; RS-485, RS-422, and V.35, can operate up to 10Mbps.

The driver inputs are both TTL or CMOS compatible. Since there are no pull-up or pull-down resistors on the driver inputs, they should be tied to a known logic state in order to define the driver output.

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## Receivers

The **SP504** has seven (7) independent receivers which can be programmed for the different interface modes. Control for the mode selection is done via a 4-bit control word that is independent from the driver control word. The coding for the drivers and receivers is identical. Therefore, if the modes for the drivers and receivers are supposed to be identical in the application, the control lines can be tied together.

Like the drivers, the receivers are pre-arranged for the specific requirements of the interface. As the operating mode of the receivers is changed, the electrical characteristics will change to support the requirements of clock, data, and control line receivers. *Table 2* shows the mode of each receiver in the different interface modes that can be selected.

There are three basic types of receiver circuits — RS-232, RS-423, and RS-485.

The RS-232 receiver is a single–ended input with a threshold of 0.8V to 2.4V. The RS-232 receiver has an operating voltage range of  $\pm 15V$ and can receive signals up to 120kbps. The input sensitivity complies with EIA-RS-232 and V.28 at +3V to -3V. The input impedance is 3k $\Omega$  to 7k $\Omega$ . RS-232 receivers are used in RS-232 mode for all data, clock and control signals. They are also used in V.35 mode for control line signals such as CTS and DSR.

The RS-423 receivers are also single–ended but have an input threshold as low as  $\pm 200$ mV. The input impedance is guaranteed to be greater than 4k $\Omega$ , with an operating voltage range of  $\pm 7$ V. The RS-423 receivers can operate up to 120kbps. RS-423 receivers are used in RS-449, EIA-530, EIA-530A and V.36 modes as Category II signals as indicated by their corresponding specifications.

The third type of receiver is a differential which supports RS-485. The RS-485 receiver has an input impedance of  $15k\Omega$  and a differential threshold of  $\pm 200$ mV. Since the characteristics of an RS-422 (V.11) receiver are actually subsets of RS-485, the receivers for RS-422 requirements are covered by the RS-485 receivers. RS-422 receivers are used in RS-449, EIA-530, EIA-530A and V.36 as Category I signals for receiving clock, data, and some control line signals. The differential receivers can receive data up to 10Mbps.

The RS-485 receivers are also used for the V.35 mode. Unlike the older implementations of differential or V.35 receivers, the **SP504** contains an internal resistor termination network that ensures a V.35 input impedance of  $100\Omega$  (± $10\Omega$ ) and a short-circuit impedance of  $150\Omega$  (± $15\Omega$ ). The traditional V.35 implementations required external termination resistors to acheive the proper V.35 impedances. The internal network is connected via low on-resistance FET switches when the decoder is changed to V.35 mode. The termination network is transparent when all other modes are selected. The V.35 receivers can operate up to 10Mbps.

All receivers include a fail-safe feature that outputs a logic HIGH when the receiver inputs are open. For single-ended RS-232 receivers, there are internal  $5k\Omega$  pull-down resistors on the inputs which produces a logic HIGH ("1") at the receiver outputs. The single-ended RS-423 receivers produce a logic LOW ("0") on the output when the inputs are open. This is due to a pullup device connected to the input. The differential receivers have the same internal pull-up device on the non-inverting input which produces a logic HIGH ("1") at the receiver output. The three differential receivers when configured in V.35 mode (RxD, RxC & SCT) do not have fail-safe because the internal termination resistor network is connected.

#### Decoder

The **SP504** has the ability to change the interface mode of the drivers or receivers via an 8–bit switch. The decoder for the drivers and receivers is not latched; it is merely a combinational logic switch.

The control word can be externally latched either HIGH or LOW to write the appropriate code into the **SP504**. The codes shown in *Tables 1 and 2* are the only specified, valid modes for the **SP504**. Undefined codes may represent other interface modes not specified (consult the fac-

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tory for more information). The drivers are controlled with the data bits labeled  $\text{TDEC}_3$ -TDEC<sub>0</sub>. All of the drivers can be put into tristate mode by writing 0000 to the driver decode switch. The three drivers TxD, ST and TxC, have a 150 $\Omega$  pull-down resistor to ground connected at the (b) output. This resistor is part of the V.35 driver circuitry and should be connected when in V.35 mode. Tri-state is possible for all drivers in RS-232 mode. The receivers are controlled with data bits RDEC<sub>3</sub>-RDEC<sub>0</sub>; the code 0000 written to the receivers will place the outputs into tri-state mode. The 0000 decoder word will override the enable control line for the one receiver (SCT).

#### Using the V.35\_STAT Pin

The **SP504** includes a V.35 status pin where the V35\_STAT pin (pin 18) is a logic HIGH ("1") when the decoder is set to V.35 mode. The pin is a logic LOW ("0") when in all other modes including tri-state (decoder set at "0000"). Pin 18 allows the user to easily add FET switches or solid state relays to connect the external  $150\Omega$ resistor for V.35 operation. V35\_STAT can be connected to the gate of the FET switches or the control of the relays so that the  $150\Omega$  resistors are connected to the non-inverting output of the three V.35 drivers. The output current of the V35\_STAT pin is that of a typical TTL load of -3.2mA. The electrical specifications are similar to the **SP504** receiver outputs. This feature would reduce additional logic required by older traditional methods.

## NET1/NET2 Testing and Compliancy

Many system designers are required to certify their system for use in the European public network. Electrical testing is performed in adherence to the NET (Norme Européenne de Télécommunication) which specifies the ITU Series V specifications. The **SP504** adheres to all the required physical layer testing for NET1 and NET2. Consult factory for details.

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# **SP504 Driver Mode Selection**

Pin Label	Mode:	RS232	V.35	RS422	RS485	RS449	EIA530	EIA-530A	V.36
TDEC <sub>3</sub> -TDEC <sub>0</sub>	0000	0010	1110	0100	0101	1100	1101	1111	0110
SD(a)	tri-state	V.28	V.35-	V.11–	RS485–	V.11–	V.11-	V.11–	V.11–
SD(b)	tri-state	tri-state	V.35+	V.11+	RS485+	V.11+	V.11+	V.11+	V.11+
TR(a)	tri-state	V.28	V.28	V.11–	RS485–	V.11–	V.11-	V.10	V.10
TR(b)	tri-state	tri-state	tri-state	V.11+	RS485+	V.11+	V.11+	tri-state	tri-state
RS(a)	tri-state	V.28	V.28	V.11–	RS485–	V.11–	V.11-	V.11–	V.10
RS(b)	tri-state	tri-state	tri-state	V.11+	RS485+	V.11+	V.11+	V.11+	tri-state
RL(a)	tri-state	V.28	V.28	V.11–	RS485–	V.10	V.10	V.11–	V.10
RL(b)	tri-state	tri-state	tri-state	V.11+	RS485+	tri-state	tri-state	V.11+	tri-state
LL(a)	tri-state	V.28	V.28	V.11–	RS485–	V.10	V.10	V.10	V.10
LL(b)	tri-state	tri-state	tri-state	V.11+	RS485+	tri-state	tri-state	tri-state	tri-state
ST(a)	tri-state	V.28	V.35–	V.11–	RS485–	V.11-	V.11-	V.11–	V.11–
ST(b)	tri-state	tri-state	V.35+	V.11+	RS485+	V.11+	V.11+	V.11+	V.11+
TT(a)	tri-state	V.28	V.35–	V.11–	RS485–	V.11-	V.11-	V.11–	V.11–
TT(b)	tri-state	tri-state	V.35+	V.11+	RS485+	V.11+	V.11+	V.11+	V.11+

Table 1. Driver Mode Selection

# **SP504 Receiver Mode Selection**

Pin Label	Mode:	RS232	V.35	RS422	RS485	RS449	EIA530	EIA-530A	V.36
RDEC <sub>3</sub> -RDEC <sub>0</sub>	0000	0010	1110	0100	0101	1100	1101	1111	0110
RD(a)	>12k $\Omega$ to GND	V.28	V.35–	V.11-	RS485-	V.11-	V.11-	V.11-	V.11–
RD(b)	>12k $\Omega$ to GND	>12k $\Omega$ to GND	V.35+	V.11+	RS485+	V.11+	V.11+	V.11+	V.11+
RT(a)	>12k $\Omega$ to GND	V.28	V.35-	V.11-	RS485–	V.11–	V.11-	V.11-	V.11-
RT(b)	>12k $\Omega$ to GND	>12k $\Omega$ to GND	V.35+	V.11+	RS485+	V.11+	V.11+	V.11+	V.11+
CS(a)	>12k $\Omega$ to GND	V.28	V.28	V.11–	RS485–	V.11-	V.11-	V.11-	V.10
CS(b)	>12k $\Omega$ to GND	>12k $\Omega$ to GND	>12k $\Omega$ to GND	V.11+	RS485+	V.11+	V.11+	V.11+	>12k $\Omega$ to GND
DM(a)	>12k $\Omega$ to GND	V.28	V.28	V.11–	RS485–	V.11–	V.11-	V.10	V.10
DM(b)	>12k $\Omega$ to GND	>12k $\Omega$ to GND	>12k $\Omega$ to GND	V.11+	RS485+	V.11+	V.11+	>12k $\Omega$ to GND	>12k $\Omega$ to GND
RR(a)	>12k $\Omega$ to GND	V.28	V.28	V.11-	RS485-	V.11-	V.11-	V.11–	V.10
RR(b)	>12k $\Omega$ to GND	>12k $\Omega$ to GND	>12k $\Omega$ to GND	V.11+	RS485+	V.11+	V.11+	V.11+	>12k $\Omega$ to GND
IC(a)	>12k $\Omega$ to GND	V.28	V.28	V.11–	RS485-	V.10	V.10	V.10	V.10
IC(b)	>12k $\Omega$ to GND	>12k $\Omega$ to GND	>12k $\Omega$ to GND	V.11+	RS485+	>12k $\Omega$ to GND			
SCT(a)	>12k $\Omega$ to GND	V.28	V.35-	V.11–	RS485–	V.11-	V.11-	V.11-	V.11–
SCT(b)	>12k $\Omega$ to GND	>12k $\Omega$ to GND	V.35+	V.11+	RS485+	V.11+	V.11+	V.11+	V.11+

Table 2. Receiver Mode Selection

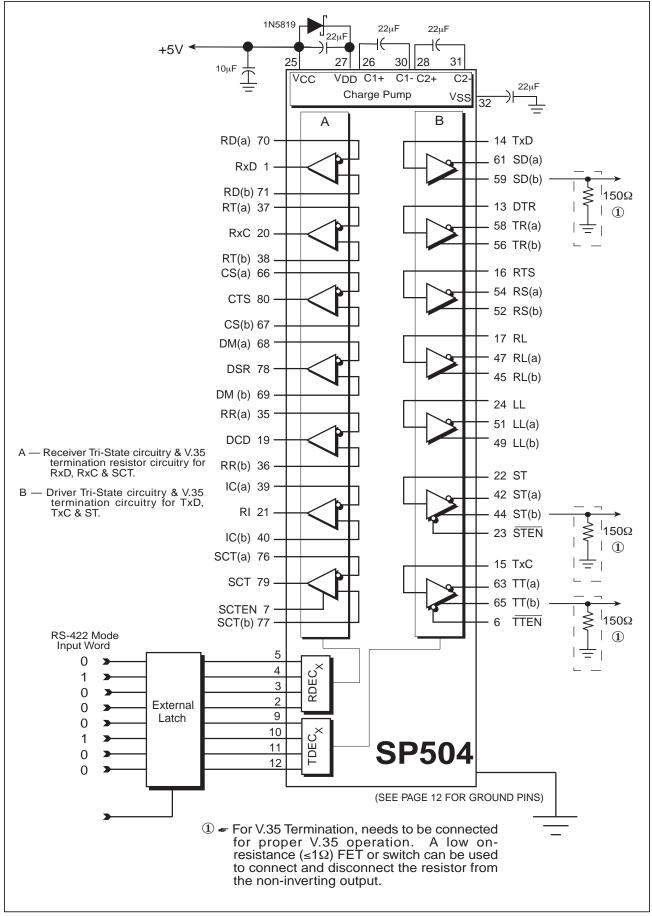


Figure 18. Typical Operation Circuit

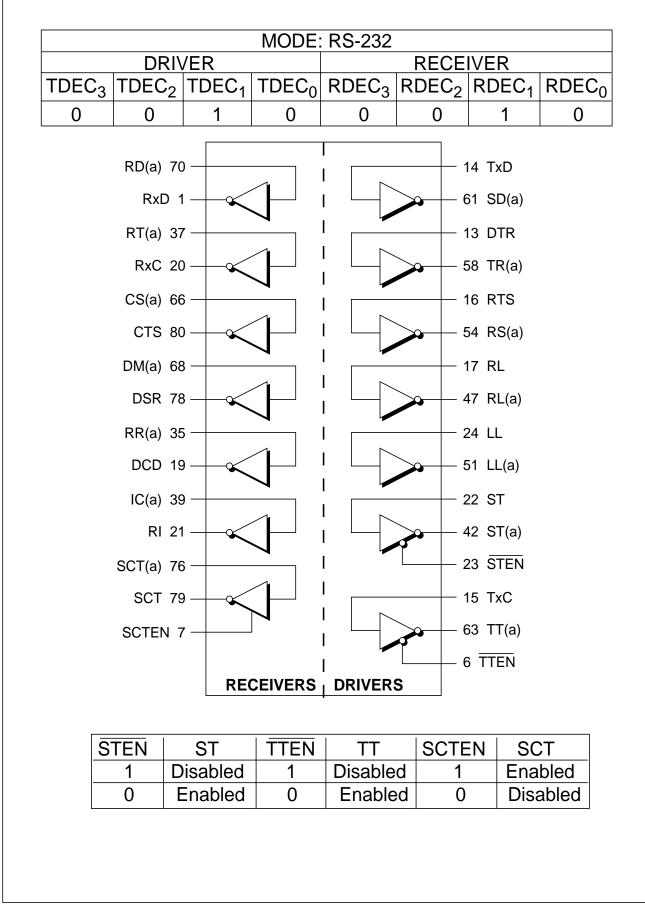


Figure 19. Mode Diagram — RS-232

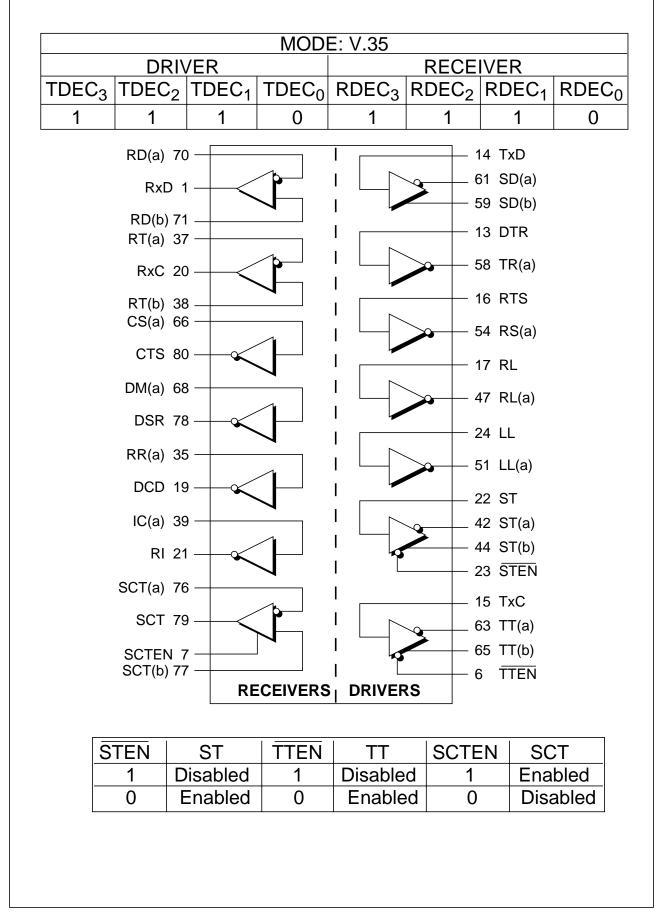


Figure 20. Mode Diagram – V.35

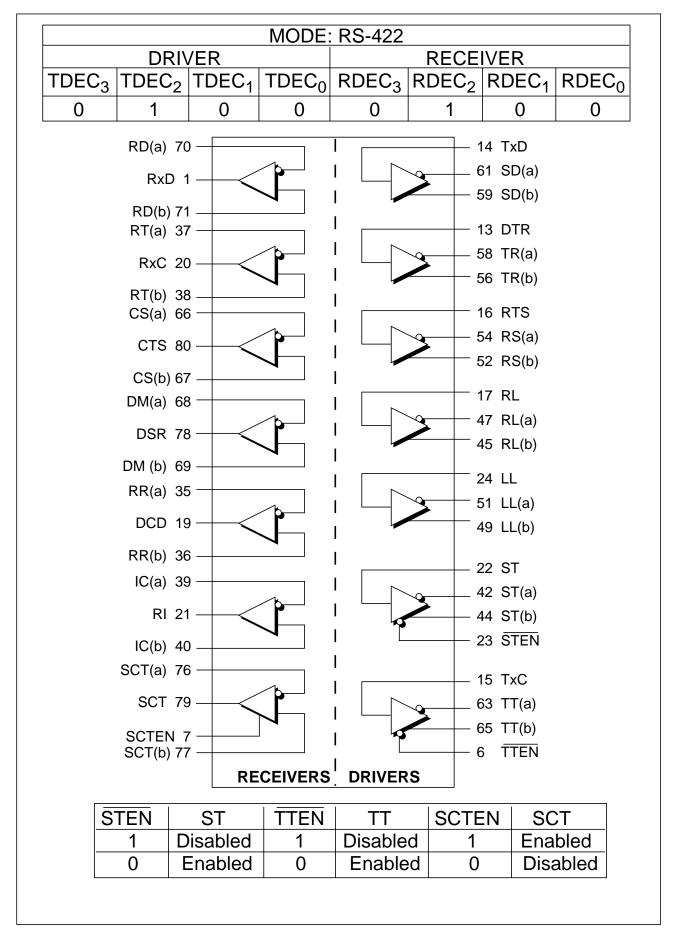


Figure 21. Mode Diagram – RS-422

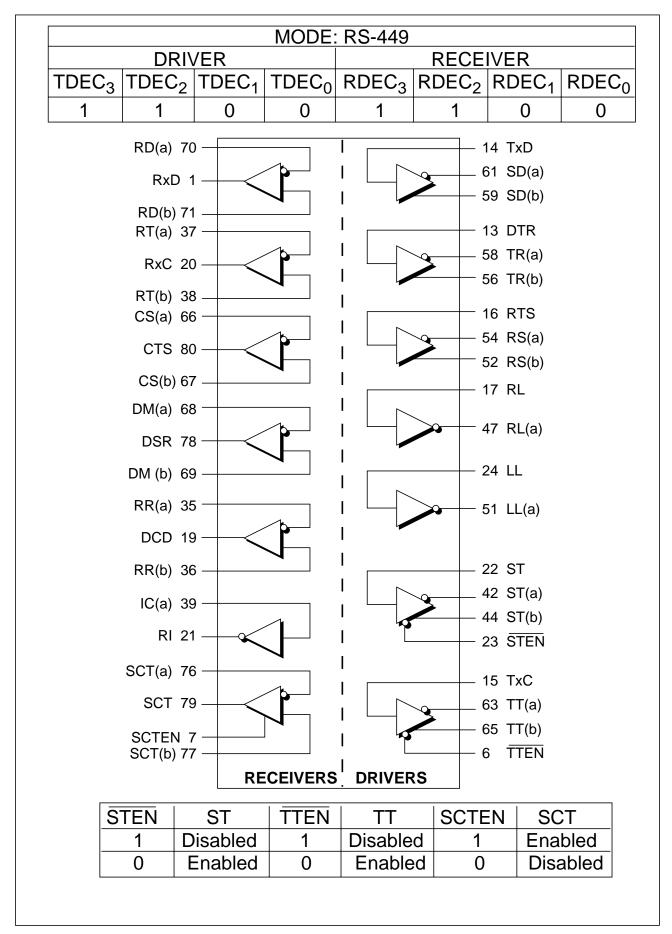


Figure 22. Mode Diagram — RS-449

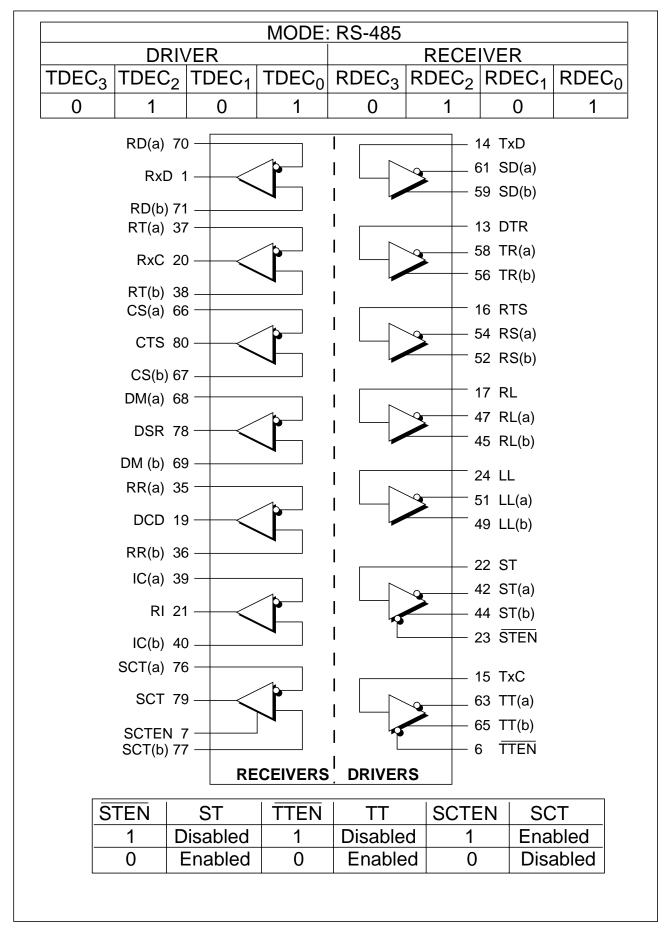


Figure 23. Mode Diagram – RS-485

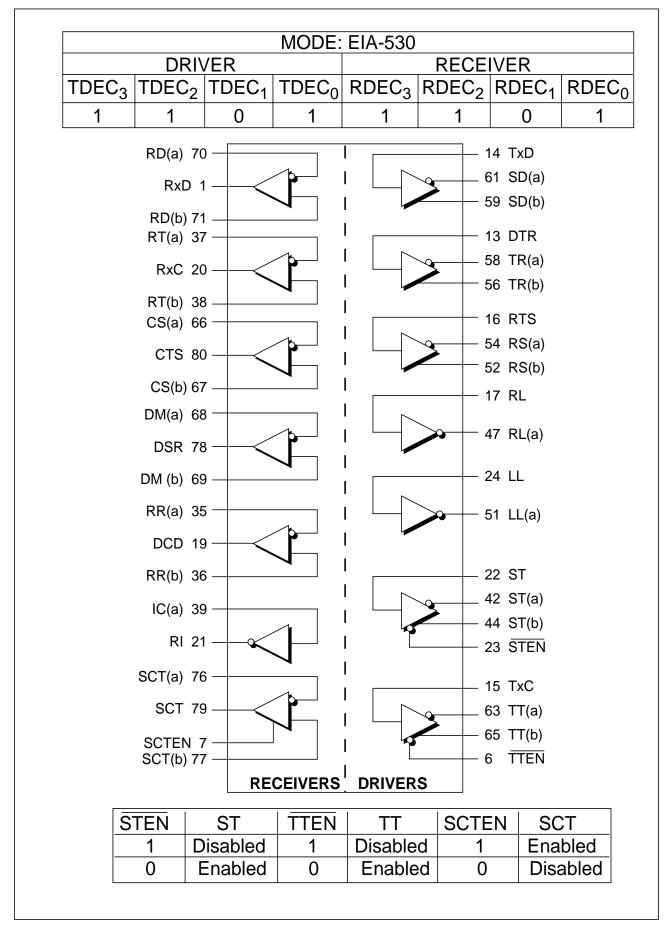


Figure 24. Mode Diagram — EIA-530

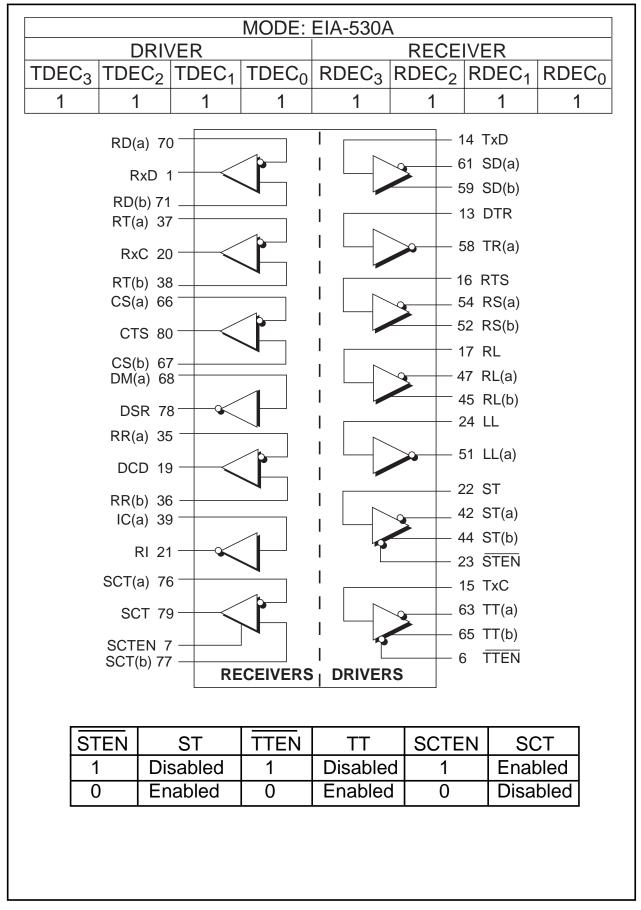


Figure 25. Mode Diagram — EIA-530A

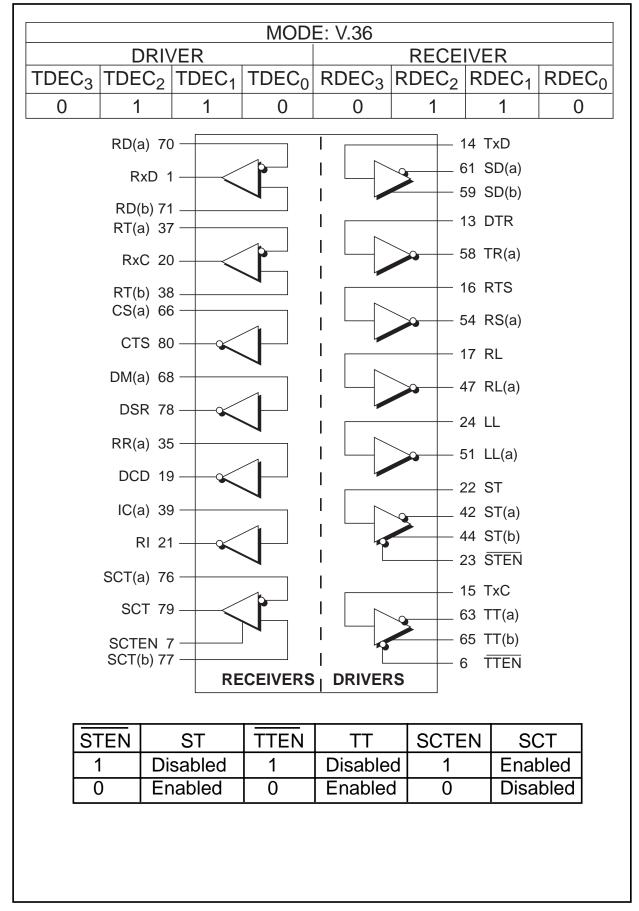


Figure 26. Mode Diagram — V.36

# ADDITIONAL TRANSCEIVERS WITH THE SP504

Serial ports usually can have two data signals (SD, RD), three clock signals (TT, ST, RT), and at least eight control signals (CS, RS, etc.). EIA-RS-449 contains twenty six signal types for a DB-37 connector. A DB-37 serial port design may require thirteen drivers and fourteen receivers<sup>1</sup>. Although many applications do not use all these signals, some applications may need to support extra functions such as diagnostics. The **SP504** supports enough transceivers for the primary channels of data, clock and control signals. Configuring LL, RL and TM would require two additional drivers and one receiver if designing for a DTE (one driver and two receivers for a DCE).

A programmable transceiver such as the SP332 is a convenient solution in a design that requires extra single ended or differential drivers/receivers. As shown in *Figure 28*, the SP332 can be configured to four different variations.

The SP332 in *Figure 29* is configured for two single-ended drivers and one differential receiver. For a DTE design, the two drivers are used for LL and RL signals and the receiver is used for the TM signal. This configuration was selected because the two RS-232 drivers can be

used for RS-423 by connecting a zener clamping diode to ground on the two driver outputs. The diodes will limit the voltage swing on the outputs so that the  $V_{OC} = \pm 4V$  to  $\pm 6V$  adheres to the RS-423 specification. The differential receiver can be easily configured to RS-423 by grounding the non-inverting input. The receiver will adhere to the RS-423 specifications.

CIRCUIT MNEMONIC	CIRCUITNAME	CIRCUIT	CIRCUIT	
SG SC	SIGNAL GROUND SEND COMMON	TO DCE	СОММС	DN
RC	RECEIVE COMMON	FROM DCE		
B	TERMINAL IN SERVICE	TO DCE		
r	INCOMING CALL	FROM DCE	CONTR	OL I
TR	TERMINAL READY	TO DCE		<u> </u>
DM	DATA MODE	FROM DCE		
SD	SEND DATA	TO DCE	DATA	
RD	RECEIVE DATA	FROM DCE	DAIN	
TT	TERMINAL TIMING	TO DCE		
ST	SEND TIMING	FROM DCE	TIMING	
RT	RECEIVE TIMING	FROM DCE		Ş
RS	REQUEST TO SEND	TO DCE		ĮĂ
CS	CLEAR TO SEND	FROM DCE		しつし
RR	RECEIVER READY	FROM DCE		PRIMARY CHANNEI
SQ	SIGNAL QUALITY	FROM DCE	CONTROL	
NS	NEW SIGNAL	TO DCE		Σ
SF	SELECT FREQUENCY	TO DCE		Ц К
SR	SIGNAL RATE SELECTOR	TO DCE		-
E	SIGNAL RATE INDICATOR	FROM DCE		
SSD	SECONDARY SEND DATA	TO DCE		$\succ$
SRD	SECONDARY RD	FROM DCE	DATA	ЧЧ
SRS	SECONDARY RS	TO DCE		ΡŻ
SCS	SECONDARY CS	FROM DCE	CONTROL	SECONDARY CHANNEL
SRR	SECONDARY RR	FROM DCE		Ч С К
IL	LOCAL LOOPBACK	TO DCE		
RL	REMOTE LOOPBACK	TO DCE		JL
TM	TEST MODE	FROM DCE		-
SS	SELECT STANDBY	TO DCE		2
SB	STANDBY INDICATOR	FROM DCE	CONTRO	JL

<sup>1</sup> RS-449 Interchange Circuits Table

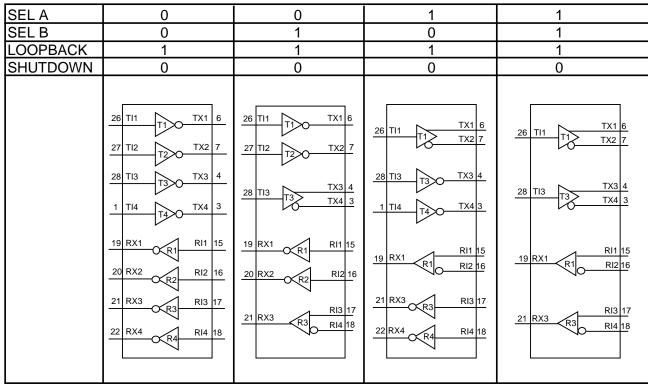


Figure 28. Mode selection for the SP332

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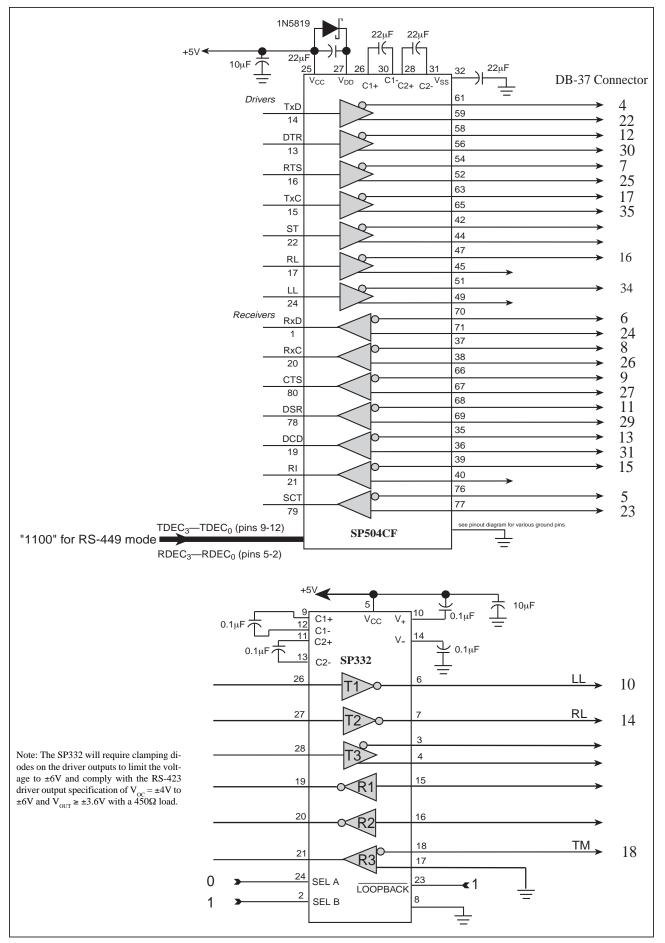
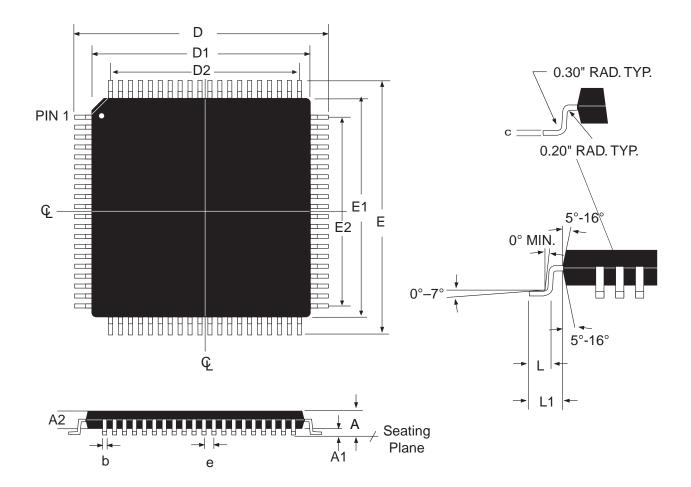


Figure 29. Adding extra differential and single-ended transceivers using the SP332



DIMENSIONS Minimum/Maximum (mm)	80–PIN MQFP JEDEC MS-22 (BEC) Variation				
SYMBOL	MIN	NOM	MAX		
Α			2.45		
A1	0.00	0.00			
A2	1.80	2.20			
b	0.22		0.40		
D	17	17.20 BSC			
D1	14	1.00 BSC	)		
D2	1:	2.35 REI	-		
E	17	7.20 BSC	)		
E1	14	1.00 BSC	:		
E2	12.35 REF				
е	0	).65 BSC	;		
N		80			

COMMON DIMENTIONS			
SYMBL	MIN	NOM	MAX
с	0.11		23.00
L	0.73	0.88	1.03
L1	1.60 BASIC		

# 80 PIN MQFP (MS-022 BC)

Rev: A Date:1/27/04

#### **ORDERING INFORMATION**

Model SP504MCF .....

Temperature Range Package Types 

#### **REVISION HISTORY**

DATE	REVISION	DESCRIPTION	
1/27/04	А	Implemented tracking revision.	

Available in Lead free packaging. To order add "-L" suffix to the part number. EXAMPLE: SP385EET/ER = standard, SP385EET/ER-L = lead free.



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