



PWM Current Control Type DC Motor Driver

Preliminary

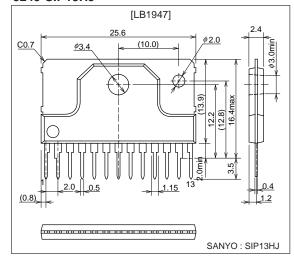
Features

- PWM current control (fixed OFF time)
- Selectable current decay pattern (FAST, SLOW, and MIX DECAY modes)
- Simultaneous ON prevention function (feedthrough current prevention)
- · Built-in thermal shutdown circuit
- · Built-in noise canceler

Package Dimensions

unit: mm

3249-SIP13HJ



Specifications

Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum motor supply voltage	Vвв max		50	V
Output peak current	I OPEAK	tw ≤ 20 μs	2.25	А
Output continuous current	I o max		2.0	А
Logic supply voltage	Vcc max		7.0	V
Logic input voltage range	VIN		-0.3 to Vcc	V
Emitter output voltage	VE max		1.1	V
Reference voltage	VREF		-0.3 to Vcc	V
Operating temperature	Topr		-20 to +85	°C
Storage temperature	Tstg		-55 to +150	°C
Allowable power dissipation	Pd max	Ta = 25°C	1.6	W

Allowable Operating Ranges at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Motor supply voltage	Vвв		10 to 45	V
Logic supply voltage	Vcc		4.75 to 5.25	V
Reference voltage	VREF		0 to (Vcc-2)	V

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LB1947

Electrical Characteristics at $Ta = 25^{\circ}C$, $V_{BB} = 42V$, $V_{CC} = 5V$, $V_{REF} = 1.0V$

Parameter		Symbol	Symbol Conditions		Ratings		
		Symbol			typ	max	Unit
Output stage supply currer		I BB ON	No-load state	0.4	0.6	1.0	mA
		I BB BR	No-load state	0.2	0.4	0.8	mA
		I BB OFF	No-load state	0.2	0.4	0.8	mA
¥		I BBWt	No-load state			0.1	mA
300	Output saturation voltage 1	V osat 1	lo = +1.0A sink		1.2	1.5	V
t H	2	V osat 2	lo = +2.0A sink		1.6	1.9	V
Output Block	3	V osat 3	lo = −1.0A source		1.8	2.2	V
0	4	V osat 4	lo = -2.0A source		2.1	2.4	V
	Output leak current	I o1(leak)	Vo = Vвв sink			50	μΑ
		I o2(leak)	Vo = 0V source	-50			μΑ
	Output sustain voltage	V sus	L = 3.9 mH lo = 2.0A *1	50			V
	Logic supply current	I CC ON	IN1 : High, IN2 : Low, ST = High	11	16	21	mA
		I CC BR	IN1 : Low, IN2 : High, ST = High	11	16	21	mA
		I CC OFF	IN1 : Low, IN2 : Low, ST = High	11	16	21	mA
		I ccwt	ST : Low	1.0	2	3.0	mA
	Input voltage	V INH		2			V
		V INL				0.8	V
	Input current	I INH	V IN = 5V	60	90	120	μΑ
		I INL	V IN = 0.8V	6	10	13	μΑ
	Sensing voltage	VE		0		1.1	V
	Sensing voltage 25H	VEH25	VI = High, V _{REF} = 2.5V	0.970	1.0	1.030	V
<u>80</u>	Sensing voltage 25L	VEL25	VI = Low, V _{REF} = 2.5V	0.483	0.5	0.513	V
Logic Block	Sensing voltage 10H	VEH25	VI = High, V _{REF} = 1.0V	0.385	0.4	0.410	V
igo-	Sensing voltage 10L	VEL25	VI = Low, V _{REF} = 1.0V	0.190	0.2	0.210	V
-	Sensing voltage 05H	VEH25	VI = High, V _{REF} = 0.5V	0.190	0.2	0.210	V
	Sensing voltage 05L	VEL25	VI = Low, V _{REF} = 0.5V	0.092	0.1	0.108	V
	Reference current	I ref	Vref = 1.0V	-0.5		0.5	μΑ
	CR pin current	I _{CR}	CR = 1.0V	-1.56	-1.3	-1.04	mA
	MD pin voltage	V _{MDH}		Vcc-0.3			V
		V _{MDM}		0.3Vcc		Vcc-1.0	V
		V _{MDL}				0.4	V
	MD pin current	I _{MDH}	MD = (Vcc-0.5)V, CR = 1.0V	-1.0		1.0	μΑ
		I _{MDL}	MD = 0.4V, CR = 2.0V	-5.0			μΑ
	Thermal shutdown temperature	T SD			170		°C

^{*1:} Guaranteed design

Truth Table

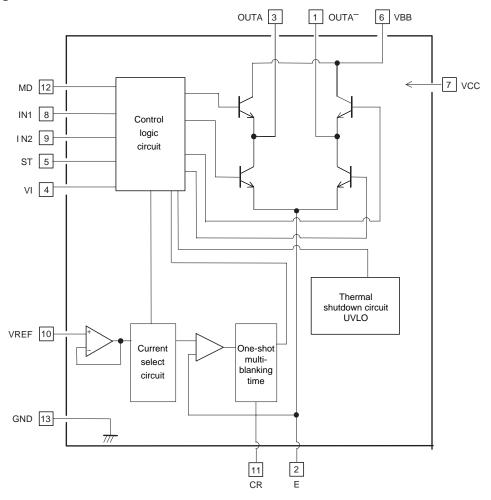
IN 1	IN 2	ST	VI	MD	OUT	OUT-	Operating mode
Н	L	Н	Н	L	Н	L	Forward, 2/5 times, FAST
Н	L	Н	Н	М	Н	L	Forward, 2/5 times, MIX
Н	L	Н	Н	Н	Н	L	Forward, 2/5 times, SLOW
Н	L	Н	L	L	Н	L	Forward, 1/5 times, FAST
Н	L	Н	L	М	Н	L	Forward, 1/5 times, MIX
Н	L	Н	L	Н	Н	L	Forward, 1/5 times, SLOW
Н	Н	Н	Н	L	L	Н	Reverse, 2/5 times, FAST
Н	Н	Н	Н	М	L	Н	Reverse, 2/5 times, MIX
Н	Н	Н	Н	Н	L	Н	Reverse, 2/5 times, SLOW
Н	Н	Н	L	L	L	Н	Reverse, 1/5 times, FAST
Н	Н	Н	L	М	L	Н	Reverse, 1/5 times, MIX
Н	Н	Н	L	Н	L	Н	Reverse, 1/5 times, SLOW
L	Н	Н	Н	L	L	L	Brake, 2/5 times, FAST
L	Н	Н	Н	М	L	L	Brake, 2/5 times, MIX
L	Н	Н	L	L	L	L	Brake, 1/5 times, FAST
L	Н	Н	L	М	L	L	Brake, 1/5 times, MIX
L	Н	Н	Х	Н	L	L	Brake, no current limiting
L	L	Н	Х	Х	OFF	OFF	Output OFF
Х	Х	L or OPEN	Х	Х	OFF	OFF	Standby mode (circuit OFF)

Except for MD pin, Low at input OPEN MD M: determined by external voltage

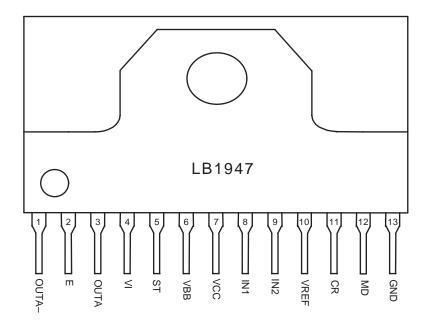
Pin Description

Pin number	Pin name	Equivalent circuit	Pin function
1	OUTA-		Output pin
3	OUTA		
2	Е		Sense voltage control pin
4	VI		VI
5	ST	Vcc —	High: sense voltage is 2/5 of V _{REF}
8	IN1	\downarrow \longrightarrow	Low: sense voltage is 1/5 of V _{REF}
9	IN2	(⇒) 100μΑ	
		Y	ST
			High: circuit operation ON
			Low: standby mode
		\$50kΩ	
			IN1
			High: rotation mode
		\$40kΩ	Low: brake mode
		(4) VI	
		VI	IN2
		A12583	High: reverse mode
		A12303	Low: forward mode
6	VBB		Motor power supply voltage
7	VCC		Logic power supply voltage
10	VREF	Vcc	Output current setting reference pin
			Setting range: 0 to (Vcc–2V)
		િ 5μΑ	
		[3s	
		§ 300Ω	
		Voca	
		VREF	
		A12584	
11	CR		Oscillator with self-excitation
12	MD		Current attenuation switching pin
			Low : FAST DECAY
			High : SLOW DECAY
			M : MIX DECAY
			M is set by external power supply voltage.
			Range : 1.1 to 4.0V
13	GND		Ground pin

Block Diagram

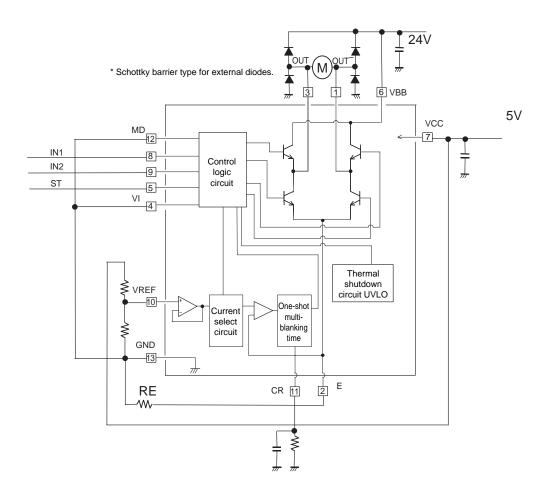


Pin Assignment



Sample Application Circuits

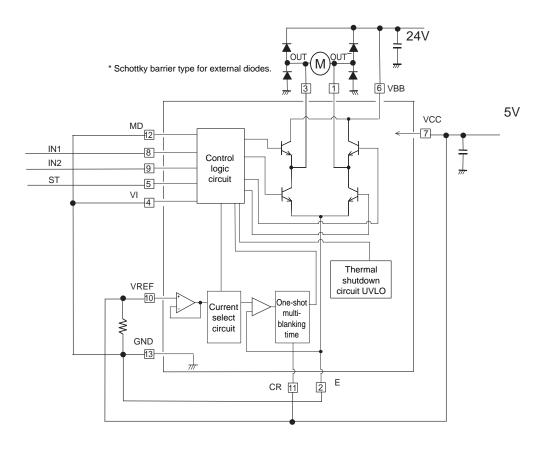
1. Forward/reverse motor with current limiter



 $Limiter \ current \ setting \ method \qquad I = V_{REF} / \ (5 \times RE)$

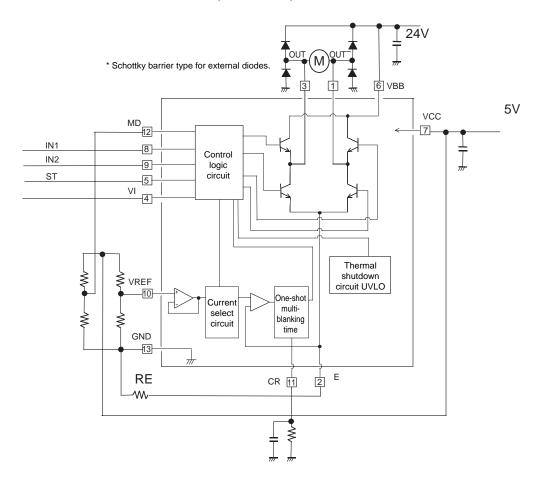
IN1	IN2	ST	OUT	OUT-	Mode
Н	Н	Н	L	Н	Reverse
Н	L	Н	Н	L	Forward
L	Н	Н	L	L	Brake
L	L	Н	OFF	OFF	Output OFF
_	_	L	OFF	OFF	Standby mode

2. Forward/reverse motor



	IN1	IN2	ST	OUT	OUT-	Mode
	Н	Н	Н	L	Н	Reverse
	Н	L	Н	Н	L	Forward
ı	L	Н	Н	L	L	Brake
I	L	L	Н	OFF	OFF	Output OFF
I	_	_	L	OFF	OFF	Standby mode





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