

**LB1641****Bidirectional Motor Driver****Overview**

The LB1641 is a bidirectional motor driver IC. Since it has a 2-input logic circuit and performs the functions of bidirectional driving and braking, it is capable of direct driving 6V, 9V, 12V motors. The output voltage can be varied by using an external zener diode.

Features

- 2-input logic can be used to exercise control of bidirectional driving and braking.
- On-chip elements to absorb dash current of motor.
- Input interfaceable to MOS LSI.
- Output voltage variable by use of external zener diode.

Specifications**Absolute Maximum Ratings at Ta = 25°C**

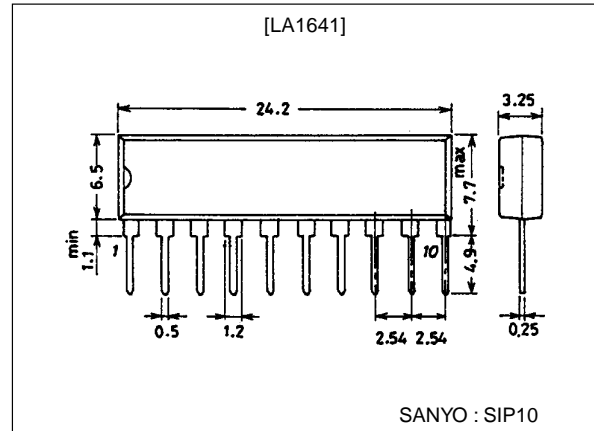
| Parameter | Symbol | Conditions | Ratings | Unit |
|-----------------------------|--------------|------------|------------------|------|
| Maximum supply voltage | V_{CC} max | | 18 | V |
| Input voltage | V_{IN} | | -0.3 to V_{CC} | V |
| Output current | I_{OUT} | | ± 1.6 | A |
| Allowable power dissipation | P_d max | | 1.2 | W |
| Operating temperature | T_{opr} | | -25 to +75 | °C |
| Storage temperature | T_{stg} | | -55 to +125 | °C |

Operating Conditions at Ta = 25°C

| Parameter | Symbol | Conditions | Ratings | Unit |
|----------------|-----------|------------|---------|------|
| Supply voltage | V_{CC1} | | 7 to 18 | V |
| | V_{CC2} | | 5 to 18 | V |

Package Dimensions

unit:mm

3043A-SIP10

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LB1641

Operating Characteristics at $T_a = 25^\circ\text{C}$

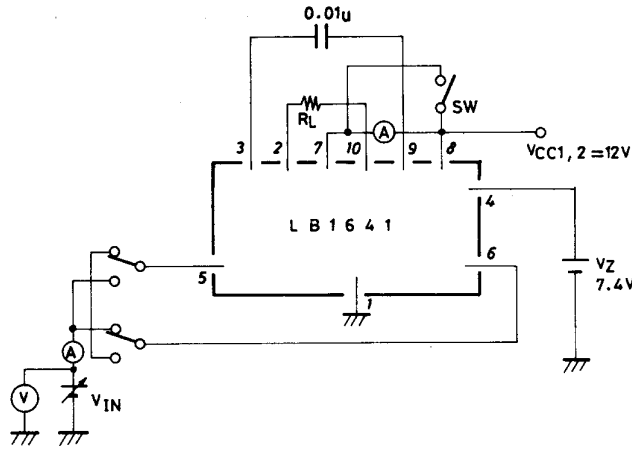
| Parameter | Symbol | Conditions | Ratings | | | Unit |
|--------------------------------|------------|---|---------|------|------|---------------|
| | | | min | typ | max | |
| Input threshold voltage | V_{th} | $R_L = \infty$ | 1.1 | 1.3 | 1.5 | V |
| Minimum input on-state current | I_{IN} | $R_L = \infty$ | | 10 | 15 | μA |
| Output voltage | V_O | $R_L = 60\Omega, V_Z = 7.4\text{V}$ | 6.6 | 7.2 | 7.4 | V |
| Output leakage current | I_{OL} | Pins 5, 6 GND, $R_L = \infty$ | | 0.01 | 1.0 | mA |
| Current drain | I_{CC} | Pins 5, 6 GND, $R_L = \infty$ | 3 | 6 | 10 | mA |
| Saturation voltage (upper) | V_{sat1} | $V_{CC} = 12\text{V}, I_{OUT} = 300\text{mA}$ | | 1.9 | 2.2 | V |
| | V_{sat1} | $V_{CC} = 12\text{V}, I_{OUT} = 500\text{mA}$ | | 1.9 | 2.3 | V |
| Saturation voltage (lower) | V_{sat2} | $V_{CC} = 12\text{V}, I_{OUT} = 300\text{mA}$ | | 0.25 | 0.5 | V |
| | V_{sat2} | $V_{CC} = 12\text{V}, I_{OUT} = 500\text{mA}$ | | 0.4 | 0.65 | V |

Truth Table

| Input | | Output | | Operation |
|-------|-----|--------|------|-------------------------|
| IN1 | IN2 | OUT1 | OUT2 | |
| 0 | 0 | 0 | 0 | Braking |
| 1 | 0 | 1 | 0 | Forward (reverse) drive |
| 0 | 1 | 0 | 1 | Reverse (forward) drive |
| 1 | 1 | 0 | 0 | Braking |

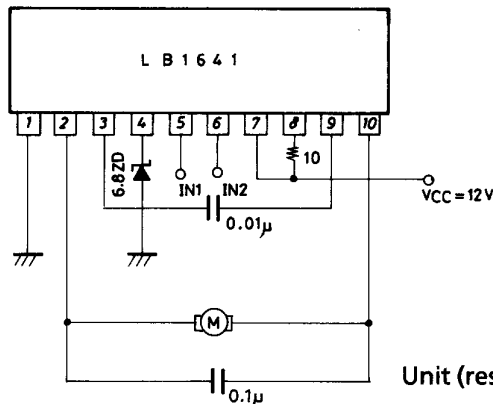
Input level 1 : 2.0V or greater
 0 : 0.7V or less

Test Circuit



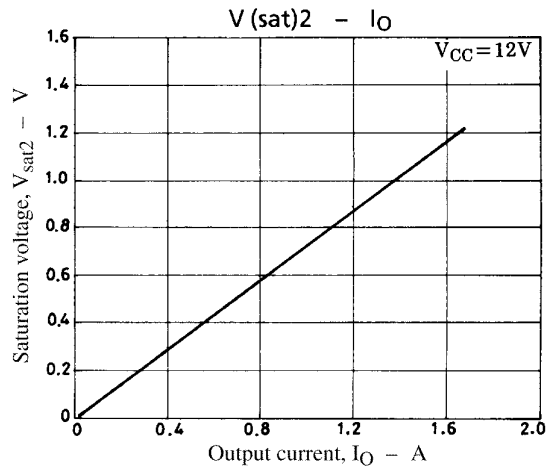
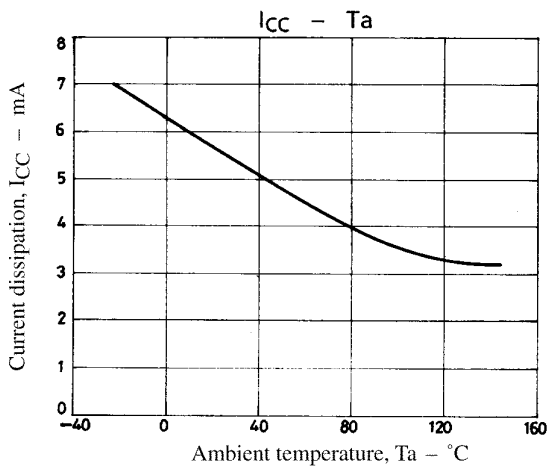
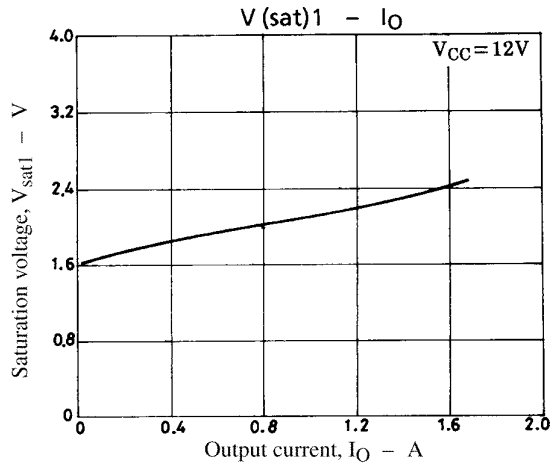
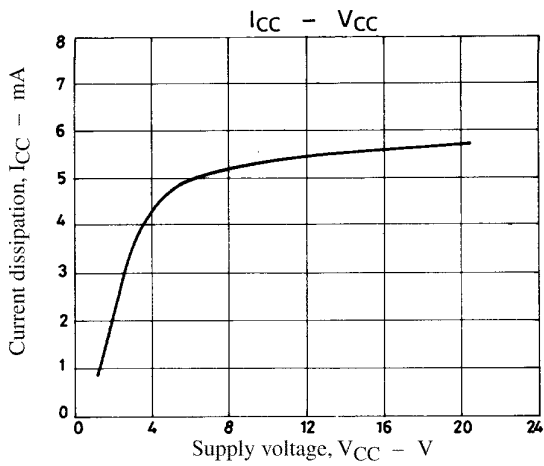
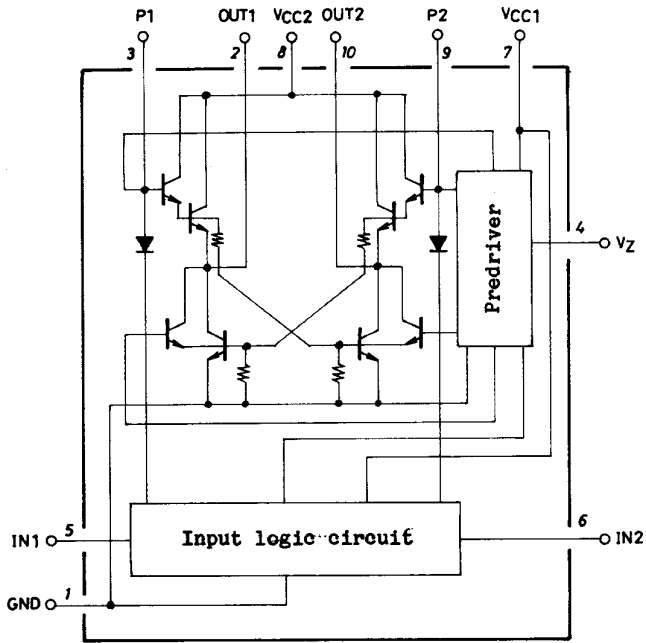
Unit (capacitance: F)

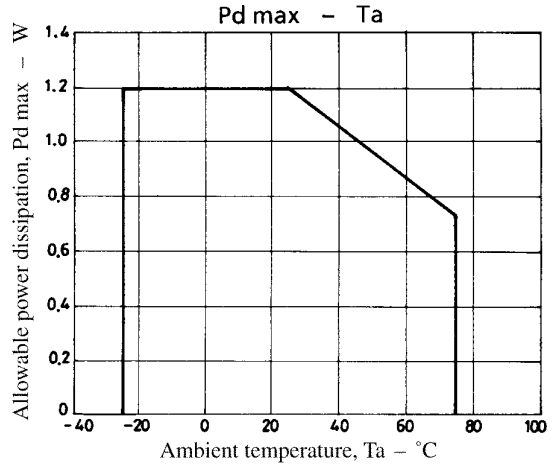
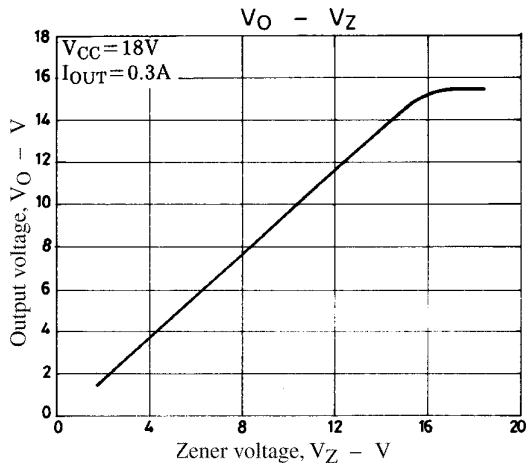
Sample Application Circuit : 6V motor circuit



Unit (resistance: Ω , capacitance: F)

Equivalent Circuit Block Diagram





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