

AMD Geode[™] SC3200 Processor Data Book

March 2004

Publication ID: Revision 5.1

© 2004 Advanced Micro Devices, Inc. All rights reserved.

The contents of this document are provided in connection with Advanced Micro Devices, Inc. ("AMD") products. AMD makes no representations or warranties with respect to the accuracy or completeness of the contents of this publication and reserves the right to make changes to specifications and product descriptions at any time without notice. No license, whether express, implied, arising by estoppel or otherwise, to any intellectual property rights is granted by this publication. Except as set forth in AMD's Standard Terms and Conditions of Sale, AMD assumes no liability whatsoever, and disclaims any express or implied warranty, relating to its products including, but not limited to, the implied warranty of merchantability, fitness for a particular purpose, or infringement of any intellectual property right.

AMD's products are not designed, intended, authorized or warranted for use as components in systems intended for surgical implant into the body, or in other applications intended to support or sustain life, or in any other application in which the failure of AMD's product could create a situation where personal injury, death, or severe property or environmental damage may occur. AMD reserves the right to discontinue or make changes to its products at any time without notice.

Contacts

www.amd.com pcs.support@amd.com

Trademarks

AMD, the AMD Arrow logo, and combinations thereof, and Geode, Virtual System Architecture, and WebPAD are trademarks of Advanced Micro Devices, Inc.

Microsoft and Windows are registered trademarks of Microsoft Corporation in the United States and other jurisdictions.

MMX is trademark of Intel Corporation.

Other product names used in this publication are for identification purposes only and may be trademarks of their respective companies.

Contents

List	of Fig	gures	5
List	of Ta	ıbles	9
1.0	AMI 1.1 1.2	D Geode™ SC3200 Processor	13
2.0	2.1 2.2 2.3 2.4 2.5	hitecture Overview GX1 Module Video Processor Module Core Logic Module Super I/O Module Clock, Timers, and Reset Logic	
3.0	3.1 3.2 3.3 3.4	nal Definitions Ball Assignments Strap Options Multiplexing Configuration Signal Descriptions	
4.0	Gen 4.1 4.2 4.3 4.4 4.5	Configuration Block Configuration Block Addresses Multiplexing, Interrupt Selection, and Base Address Registers WATCHDOG High-Resolution Timer Clock Generators and PLLs	
5.0	5.1 5.2 5.3 5.4 5.5 5.6 5.7	Features Module Architecture Configuration Structure / Access Standard Configuration Registers Real-Time Clock (RTC) System Wakeup Control (SWC) ACCESS.bus Interface	
	5 Q	Logacy Functional Blocks	115

6.0	Cor	e Logic Module	157
	6.1	Feature List	157
	6.2	Module Architecture	158
	6.3	Register Descriptions	191
	6.4	Chipset Register Space	
7.0	Vide	eo Processor Module	327
	7.1	Module Architecture	328
	7.2	Functional Description	
	7.3	Register Descriptions	
8.0	Deb	ougging and Monitoring	367
	8.1	Testability (JTAG)	367
9.0	Elec	ctrical Specifications	369
	9.1	General Specifications	369
	9.2	DC Characteristics	
	9.3	AC Characteristics	380
10.0	Pac	kage Specifications	439
	10.1	•	
	10.2		
Appe	endix	A Support Documentation	443
	A.1	Order Information	443
	A.2	Data Book Revision History	
		•	

List of Figures

Figure 1-1.	Block Diagram	13
Figure 3-1.	Signal Groups	25
Figure 3-2.	432-EBGA Ball Assignment Diagram	28
Figure 3-3.	481-TEPBGA Ball Assignment Diagram	42
Figure 4-1.	WATCHDOG Block Diagram	95
Figure 4-2.	Clock Generation Block Diagram	99
Figure 4-3.	Recommended Oscillator External Circuitry	100
Figure 5-1.	SIO Block Diagram	105
Figure 5-2.	Detailed SIO Block Diagram	107
Figure 5-3.	Structure of the Standard Configuration Register File	108
Figure 5-4.	Standard Configuration Registers Map	110
Figure 5-5.	Recommended Oscillator External Circuitry	121
Figure 5-6.	External Oscillator Connections	122
Figure 5-7.	Divider Chain Control	122
Figure 5-8.	Power Supply Connections	124
Figure 5-9.	Typical Battery Configuration	124
Figure 5-10.	Typical Battery Current: Battery Backed Power Mode @ T _C = 25°C	124
Figure 5-11.	Typical Battery Current: Normal Operation Mode	124
Figure 5-12.	Interrupt/Status Timing	126
Figure 5-13.	Bit Transfer	137
Figure 5-14.	Start and Stop Conditions	137
Figure 5-15.	ACCESS.bus Data Transaction	138
Figure 5-16.	ACCESS.bus Acknowledge Cycle	138
Figure 5-17.	A Complete ACCESS.bus Data Transaction	139
Figure 5-18.	UART Mode Register Bank Architecture	147
Figure 5-19.	IRCP/SP3 Register Bank Architecture	151
Figure 6-1.	Core Logic Module Block Diagram	158
Figure 6-2.	Non-Posted Fast-PCI to ISA Access	164
Figure 6-3.	PCI to ISA Cycles with Delayed Transaction Enabled	165
Figure 6-4.	ISA DMA Read from PCI Memory	166
Figure 6-5.	ISA DMA Write to PCI Memory	166
Figure 6-6.	PCI Change to Sub-ISA and Back	168
Figure 6-7.	PIT Timer	170
Figure 6-8.	PIC Interrupt Controllers	171
Figure 6-9.	PCI and IRQ Interrupt Mapping	172
Figure 6-10.	SMI Generation for NMI	
Figure 6-11.	General Purpose Timer and UDEF Trap SMI Tree Example	181
Figure 6-12.	PRD Table Example	
Figure 6-13.	AC97 V2.0 Codec Signal Connections	186
Figure 6-14.	Audio SMI Tree Example	188
Figure 6-15.	Typical Setup	189
Figure 7-1.	Video Processor Block Diagram	
Figure 7-2.	NTSC 525 Lines, 60 Hz, Odd Field	
Figure 7-3.	NTSC 525 Lines, 60 Hz, Even Field	330
Figure 7-4	VIP Block Diagram	331

Revision 5.1		List of Figures

Figure 7-5.	Capture Video Mode Bob Example Using One Video Frame Buffer	333
Figure 7-6.	Capture Video Mode Weave Example Using Two Video Frame Buffers	334
Figure 7-7.	Video Block Diagram	335
Figure 7-8.	Horizontal Downscaler Block Diagram	336
Figure 7-9.	Linear Interpolation Calculation	337
Figure 7-10.	Mixer/Blender Block Diagram	338
Figure 7-11.	Graphics/Video Frame with Alpha Windows	340
Figure 7-12.	Color Key and Alpha Blending Logic	342
Figure 7-13.	TFT Power Sequence	343
Figure 7-14.	PLL Block Diagram	344
Figure 9-1.	Differential Input Sensitivity for Common Mode Range	378
Figure 9-2.	Drive level and Measurement Points	380
Figure 9-3.	Memory Controller Drive Level and Measurement Points	381
Figure 9-4.	Memory Controller Output Valid Timing Diagram	383
Figure 9-5.	Read Data In Setup and Hold Timing Diagram	
Figure 9-6.	Video Input Port Timing Diagram	
Figure 9-7.	TFT Timing Diagram	
Figure 9-8.	ACB Signals: Rising Time and Falling Timing Diagram	387
Figure 9-9.	ACB Start and Stop Condition Timing Diagram	
Figure 9-10.	ACB Start Condition Timing Diagram	
Figure 9-11.	ACB Data Bit Timing Diagram	
Figure 9-12.	Testing Setup for Slew Rate and Minimum Timing	
Figure 9-13.	V/I Curves for PCI Output Signals	
Figure 9-14.	PCICLK Timing and Measurement Points	
Figure 9-15.	Load Circuits for Maximum Time Measurements	
Figure 9-16.	Output Timing Measurement Conditions	
Figure 9-17.	Input Timing Measurement Conditions	
Figure 9-18.	PCI Reset Timing	
Figure 9-19.	Sub-ISA Read Operation Timing Diagram	
Figure 9-20.	Sub-ISA Write Operation Timing Diagram	
Figure 9-21.	LPC Output Timing Diagram	
Figure 9-22.	LPC Input Timing Diagram	
Figure 9-23.	IDE Reset Timing Diagram	
Figure 9-24.	Register Transfer to/from Device Timing Diagram	
Figure 9-25.	PIO Data Transfer to/from Device Timing Diagram	
Figure 9-26.	Multiword DMA Data Transfer Timing Diagram	
Figure 9-27.	Initiating an UltraDMA Data in Burst Timing Diagram	
Figure 9-28.	Sustained UltraDMA Data In Burst Timing Diagram	
Figure 9-29.	Host Pausing an UltraDMA Data In Burst Timing Diagram	
Figure 9-30.	Device Terminating an UltraDMA Data In Burst Timing Diagram	
Figure 9-31.	Host Terminating an UltraDMA Data In Burst Timing Diagram	
Figure 9-32.	Initiating an UltraDMA Data Out Burst Timing Diagram	
Figure 9-33.	Sustained UltraDMA Data Out Burst Timing Diagram	
Figure 9-34.	Device Pausing an UltraDMA Data Out Burst Timing Diagram	
Figure 9-35.	Host Terminating an UltraDMA Data Out Burst Timing Diagram	
Figure 9-36.	Device Terminating an UltraDMA Data Out Burst Timing Diagram	
Figure 9-37.	Data Signal Rise and Fall Timing Diagram	
Figure 9-38.	Source Differential Data Jitter Timing Diagram	
Figure 9-39.	EOP Width Timing Diagram	
Figure 9-40.	Receiver Jitter Tolerance Timing Diagram	
Figure 9-41.	UART, Sharp-IR, SIR, and Consumer Remote Control Timing Diagram	
Figure 9-42.	Fast IR (MIR and FIR) Timing Diagram	
Figure 9-43.	Standard Parallel Port Typical Data Exchange Timing Diagram	
Figure 9-44.	Enhanced Parallel Port Timing Diagram	
Figure 9-45.	ECP Forward Mode Timing Diagram	
J	J	

List of Figures	Revision 5.1	AMDL
Figure 9-46.	ECP Reverse Mode Timing Diagram	427
Figure 9-47.	AC97 Reset Timing Diagram	428
Figure 9-48.	AC97 Sync Timing Diagram	428
Figure 9-49.	AC97 Clocks Diagram	429
Figure 9-50.	AC97 Data TIming Diagram	
Figure 9-51.	AC97 Rise and Fall Timing Diagram	431
Figure 9-52.	AC97 Low Power Mode Timing Diagram	432
Figure 9-53.	PWRBTN# Trigger and ONCTL# Timing Diagram	433
Figure 9-54.	GPWIO and ONCTL# Timing Diagram	433
Figure 9-55.	Power-Up Sequencing With PWRBTN# Timing Diagram	434
Figure 9-56.	Power-Up Sequencing Without PWRBTN# Timing Diagram	435
Figure 9-57.	TCK Measurement Points and Timing Diagram	436
Figure 9-58.	JTAG Test Timing Diagram	437
Figure 10-1.	Heatsink Example	440
Figure 10-2.	432-Terminal EBGA Package (Body Size: 40x40x1.72 mm; Pitch: 1.27 mm)	441
Figure 10-3.	481-Terminal TEPBGA Package (Body Size: 40x40x2.38 mm; Pitch: 1.27 mm)	442

Revision 5.1 List of Figures

List of Tables

Revision 5.1

Table 2-1.	SC3200 Memory Controller Register Summary	18
Table 2-2.	SC3200 Memory Controller Registers	18
Table 3-1.	Signal Definitions Legend	27
Table 3-2.	432-EBGA Ball Assignment - Sorted by Ball Number	
Table 3-3.	432-EBGA Ball Assignment - Sorted Alphabetically by Signal Name	38
Table 3-4.	481-TEPBGA Ball Assignment - Sorted by Ball Number	43
Table 3-5.	481-TEPBGA Ball Assignment - Sorted Alphabetically by Signal Name	54
Table 3-6.	Strap Options	58
Table 3-7.	Two-Signal/Group Multiplexing	59
Table 3-8.	Three-Signal/Group Multiplexing	60
Table 3-9.	Four-Signal/Group Multiplexing	62
Table 4-1.	General Configuration Block Register Summary	87
Table 4-2.	Multiplexing, Interrupt Selection, and Base Address Registers	88
Table 4-3.	WATCHDOG Registers	96
Table 4-4.	High-Resolution Timer Registers	98
Table 4-5.	Crystal Oscillator Circuit Components	100
Table 4-6.	Core Clock Frequency	101
Table 4-7.	Strapped Core Clock Frequency	101
Table 4-8.	Clock Generator Configuration	103
Table 5-1.	SIO Configuration Options	108
Table 5-2.	LDN Assignments	108
Table 5-3.	Standard Configuration Registers	111
Table 5-4.	SIO Control and Configuration Register Map	113
Table 5-5.	SIO Control and Configuration Registers	113
Table 5-6.	Relevant RTC Configuration Registers	114
Table 5-7.	RTC Configuration Registers	115
Table 5-8.	Relevant SWC Registers	116
Table 5-9.	Relevant IRCP/SP3 Registers	117
Table 5-10.	IRCP/SP3 Configuration Register	117
Table 5-11.	Relevant Serial Ports 1 and 2 Registers	118
Table 5-12.	Serial Ports 1 and 2 Configuration Register	118
Table 5-13.	Relevant ACB1 and ACB2 Registers	119
Table 5-14.	ACB1 and ACB2 Configuration Register	119
Table 5-15.	Relevant Parallel Port Registers	120
Table 5-16.	Parallel Port Configuration Register	120
Table 5-17.	Crystal Oscillator Circuit Components	121
Table 5-18.	System Power States	125
Table 5-19.	RTC Register Map	127
Table 5-20.	RTC Registers	127
Table 5-21.	Divider Chain Control / Test Selection	130
Table 5-22.	Periodic Interrupt Rate Encoding	130
Table 5-23.	BCD and Binary Formats	130
Table 5-24.	Standard RAM Map	131
Table 5-25.	Extended RAM Map	131
Table 5-26.	Time Range Limits for CEIR Protocols	132

Table 5-27.	Banks 0 and 1 - Common Control and Status Register Map	. 133
Table 5-28.	Bank 1 - CEIR Wakeup Configuration and Control Register Map	.133
Table 5-29.	Banks 0 and 1 - Common Control and Status Registers	.134
Table 5-30.	Bank 1 - CEIR Wakeup Configuration and Control Registers	. 135
Table 5-31.	ACB Register Map	
Table 5-32.	ACB Registers	
Table 5-33.	Parallel Port Register Map for First Level Offset	. 145
Table 5-34.	Parallel Port Register Map for Second Level Offset	
Table 5-35.	Parallel Port Bit Map for First Level Offset	
Table 5-36.	Parallel Port Bit Map for Second Level Offset	
Table 5-37.	Bank 0 Register Map	
Table 5-38.	Bank Selection Encoding	
Table 5-39.	Bank 1 Register Map	
Table 5-40.	Bank 2 Register Map	
Table 5-41.	Bank 3 Register Map	
Table 5-42.	Bank 0 Bit Map	
Table 5-43.	Bank 1 Bit Map	
Table 5-44.	Bank 2 Bit Map	
Table 5-45.	Bank 3 Bit Map	. 150
Table 5-46.	Bank 0 Register Map	
Table 5-47.	Bank Selection Encoding	
Table 5-48.	Bank 1 Register Map	. 152
Table 5-49.	Bank 2 Register Map	
Table 5-50.	Bank 3 Register Map	
Table 5-51.	Bank 4 Register Map	
Table 5-52.	Bank 5 Register Map	
Table 5-53.	Bank 6 Register Map	
Table 5-54.	Bank 7 Register Map	
Table 5-55.	Bank 0 Bit Map	
Table 5-56.	Bank 1 Bit Map	
Table 5-57.	Bank 2 Bit Map	
Table 5-58.	Bank 3 Bit Map	
Table 5-59.	Bank 4 Bit Map	
Table 5-60.	Bank 5 Bit Map	
Table 5-61.	Bank 6 Bit Map	
Table 5-62.	Bank 7 Bit Map	
Table 6-1.	Physical Region Descriptor Format	
Table 6-2.	UltraDMA/33 Signal Definitions	
Table 6-3.	Cycle Multiplexed PCI / Sub-ISA Balls	
Table 6-4.	PÍC Interrupt Mapping	
Table 6-5.	Wakeup Events Capability	
Table 6-6.	Power Planes Control Signals vs. Sleep States	
Table 6-7.	Power Planes vs. Sleep/Global States	
Table 6-8.	Power Management Events	
Table 6-9.	Device Power Management Programming Summary	
Table 6-10.	Bus Masters That Drive Specific Slots of the AC97 Interface	
Table 6-11.	Physical Region Descriptor Format	
Table 6-12.	Cycle Types	
Table 6-13.	PCI Configuration Address Register (0CF8h)	
Table 6-14.	F0: PCI Header/Bridge Configuration Registers for GPIO and LPC Support Summary	
Table 6-15.	F0BAR0: GPIO Support Registers Summary	
Table 6-16.	F0BAR1: LPC Support Registers Summary	
Table 6-17.	F1: PCI Header Registers for SMI Status and ACPI Support Summary	
Table 6-18.	F1BAR0: SMI Status Registers Summary	
Table 6-19.	F1BAR1: ACPI Support Registers Summary	

List of Tables	Revision 5.1	AMDL
Table 6-20.	F2: PCI Header Registers for IDE Controller Support Summary	198
Table 6-21.	F2BAR4: IDE Controller Support Registers Summary	
Table 6-22.	F3: PCI Header Registers for Audio Support Summary	
Table 6-23.	F3BAR0: Audio Support Registers Summary	
Table 6-24.	F5: PCI Header Registers for X-Bus Expansion Support Summary	
Table 6-25.	F5BAR0: I/O Control Support Registers Summary	20
Table 6-26.	PCIUSB: USB PCI Configuration Register Summary	
Table 6-27.	USB_BAR: USB Controller Registers Summary	
Table 6-28.	ISA Legacy I/O Register Summary	204
Table 6-29.	F0: PCI Header/Bridge Configuration Registers for GPIO and LPC Support	206
Table 6-30.	F0BAR0+I/O Offset: GPIO Configuration Registers	240
Table 6-31.	F0BAR1+I/O Offset: LPC Interface Configuration Registers	244
Table 6-32.	F1: PCI Header Registers for SMI Status and ACPI Support	252
Table 6-33.	F1BAR0+I/O Offset: SMI Status Registers	253
Table 6-34.	F1BAR1+I/O Offset: ACPI Support Registers	263
Table 6-35.	F2: PCI Header/Channels 0 and 1 Registers for IDE Controller Configuration	273
Table 6-36.	F2BAR4+I/O Offset: IDE Controller Configuration Registers	
Table 6-37.	F3: PCI Header Registers for Audio Configuration	279
Table 6-38.	F3BAR0+Memory Offset: Audio Configuration Registers	
Table 6-39.	F5: PCI Header Registers for X-Bus Expansion	
Table 6-40.	F5BAR0+I/O Offset: X-Bus Expansion Registers	
Table 6-41.	PCIUSB: USB PCI Configuration Registers	
Table 6-42.	USB_BAR+Memory Offset: USB Controller Registers	
Table 6-43.	DMA Channel Control Registers	
Table 6-44.	DMA Page Registers	
Table 6-45.	Programmable Interval Timer Registers	
Table 6-46.	Programmable Interrupt Controller Registers	
Table 6-47.	Keyboard Controller Registers	
Table 6-48.	Real-Time Clock Registers	
Table 6-49.	Miscellaneous Registers	
Table 7-1.	Valid Mixing/Blending Configurations	
Table 7-2.	Truth Table for Alpha Blending	
Table 7-3.	F4: PCI Header Registers for Video Processor Support Summary	
Table 7-4.	F4BAR0: Video Processor Configuration Registers Summary	
Table 7-5.	F4BAR2: VIP Support Registers Summary	
Table 7-6.	F4: PCI Header Registers for Video Processor Support Registers	
Table 7-7. Table 7-8.	F4BAR0+Memory Offset: Video Processor Configuration Registers	
Table 7-6. Table 8-1.	F4BAR2+Memory Offset: VIP Configuration Registers	
Table 6-1. Table 9-1.	JTAG Mode Instruction Support	
Table 9-1.	Electro Static Discharge (ESD) Absolute Maximum Ratings	
Table 9-2. Table 9-3.		
Table 9-3.	Operating Conditions	
Table 9-4.	System Conditions Used to Measure SC3200 Current During On State	
Table 9-5.	DC Characteristics for On State	
Table 9-0.	DC Characteristics for Active Idle, Sleep, and Off States	
Table 9-8.	Ball Capacitance and Inductance	
Table 9-9.	Balls with PU/PD Resistors	
Table 9-10.	Buffer Types	
Table 9-11.	Default Levels for Measurement of Switching Parameters	
Table 9-12.	Memory Controller Timing Parameters	
Table 9-13.	Video Input Port Timing Parameters	
Table 9-14.	TFT Timing Parameters	
Table 9-15.	ACCESS.bus Input Timing Parameters	
Table 0 16	ACCESS has Output Timing Parameters	206

	Revision 5.1	List of Tables
Table 9-17.	PCI AC Specifications	389
Table 9-18.	PCI Clock Parameters	391
Table 9-19.	PCI Timing Parameters	392
Table 9-20.	Measurement Condition Parameters	393
Table 9-21.	Sub-ISA Timing Parameters	395
Table 9-22.	LPC and SERIRQ Timing Parameters	399
Table 9-23.	IDE General Timing Parameters	400
Table 9-24.	IDE Register Transfer to/from Device Timing Parameters	401
Table 9-25.	IDE PIO Data Transfer to/from Device Timing Parameters	403
Table 9-26.	IDE Multiword DMA Data Transfer Timing Parameters	405
Table 9-27.	IDE UltraDMA Data Burst Timing Parameters	407
Table 9-28.	USB Timing Parameters	
Table 9-29.	UART, Sharp-IR, SIR, and Consumer Remote Control Timing Parameters	422
Table 9-30.	Fast IR Port Timing Parameters	
Table 9-31.	Standard Parallel Port Timing Parameters	424
Table 9-33.	ECP Forward Mode Timing Parameters	426
Table 9-34.	ECP Reverse Mode Timing Parameters	427
Table 9-35.	AC Reset Timing Parameters	428
Table 9-36.	AC97 Sync Timing Parameters	428
Table 9-37.	AC97 Clocks Parameters	429
Table 9-38.	AC97 I/O Timing Parameters	430
Table 9-39.	AC97 Signal Rise and Fall Timing Parameters	431
Table 9-40.	AC97 Low Power Mode Timing Parameters	432
Table 9-41.	PWRBTN# Timing Parameters	433
Table 9-42.	Power Management Event (GPWIO) and ONCTL# Timing Parameters	433
Table 9-43.	Power-Up Sequence Using the Power Button Timing Parameters	434
Table 9-44.	Power-Up Sequence Not Using the Power Button Timing Parameters	435
Table 9-45.	JTAG Timing Parameters	436
Table 10-1.	q _{JC} (×C/W)	
Table 10-2.	Case-to-Ambient Thermal Resistance Example @ 85xC	439
Table A-1.	Revision History	443
Table A-2	Edits to Current Revision	445

AMD Geode[™] SC3200 Processor

1.1 General Description

The AMD Geode[™] SC3200 processor is a member of the AMD Geode family of fully integrated x86 system chips. The SC3200 processor includes:

- The Geode GX1 processor module combines advanced CPU performance with MMXTM support, fully accelerated 2D graphics, a 64-bit synchronous DRAM (SDRAM) interface, a PCI bus controller, and a display controller.
- A low-power TFT Video Processor module with a Video Input Port (VIP), and a hardware video accelerator for scaling, filtering, and color space conversion.
- The Core Logic module includes: PC/AT functionality, a USB interface, an IDE interface, a PCI bus interface, an LPC bus interface, Advanced Configuration Power Interface (ACPI) version 1.0 compliant power management, and an audio codec interface.
- The SuperI/O module has: three serial ports (UART1, UART2, and UART3 with fast infrared), a parallel port, two ACCESS.bus (ACB) interfaces, and a real-time clock (RTC).

These features, combined with the device's low power consumption, enable a small form factor design making it ideal as the core for a WebPAD™ system application.

Figure 1-1 shows the relationships between the modules.

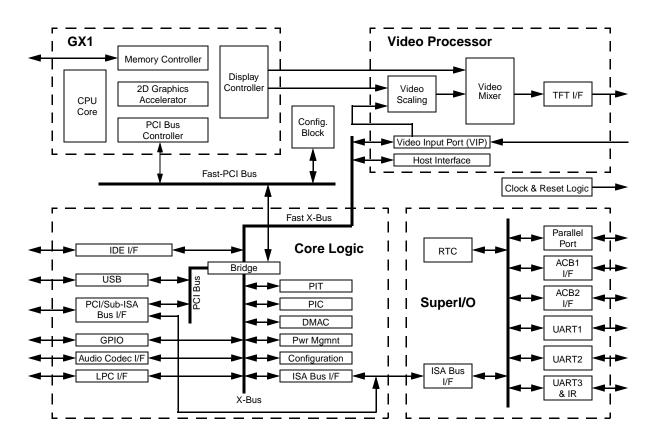


Figure 1-1. Block Diagram

1.2 Features

General Features

- 32-Bit x86 processor, up to 266 MHz, with MMX instruction set support
- Memory controller with 64-bit SDRAM interface
- 2D graphics accelerator
- CCIR-656 video input port with direct video for full screen display
- PC/AT functionality
- PCI bus controller
- IDE interface, two channels
- USB, three ports, OHCI (OpenHost Controller Interface) version 1.0 compliant
- Audio, AC97/AMC97 version 2.0 compliant
- Virtual System ArchitectureTM (VSA) technology support
- Power management, ACPI (Advanced Configuration Power Interface) version 1.0 compliant
- Package:
 - 432-Terminal EBGA (Enhanced Ball Grid Array)
 - 481-Terminal TEPBGA (Thermally Enhanced Plastic Ball Grid Array)

GX1 Processor Module

- CPU Core:
 - 32-Bit x86, 266 MHz, with MMX compatible instruction set support
 - 16 KB unified L1 cache
 - Integrated FPU (Floating Point Unit)
 - Re-entrant SMM (System Management Mode) enhanced for VSA
- 2D Graphics Accelerator:
 - Accelerates BitBLTs, line draw and text
 - Supports all 256 raster operations
 - Supports transparent BLTs
 - Runs at core clock frequency
- Memory Controller:
 - 64-Bit SDRAM interface
 - 66 MHz to 100 MHz frequency range
 - Direct interface with CPU/cache, display controller and 2D graphic accelerator
 - Supports clock suspend and power-down/ self-refresh
 - Up to two banks of SDRAM (8 devices total) or one SODIMM
- Display Controller:
 - Hardware graphics frame buffer compress/ decompress
 - Hardware cursor, 32x32 pixels

Video Processor Module

- Video Accelerator:
 - Flexible video scaling support of up to 800% (horizontally and vertically)
 - Bilinear interpolation filters (with two taps, and eight phases) to smooth output video
- Video/Graphics Mixer:
 - 8-bit value alpha blending
 - Three blending windows with constant alpha value
 - Color key
- Video Input Port (VIP):
 - Video capture or display
 - CCIR-656 and VESA Video Interface Port v1.1 compliant
 - Lock display timing to video input timing (GenLock)
 - Able to transfer video data into main memory
 - Direct video transfer for full screen display
 - Separate memory location for VBI
- TFT Interface:
 - Direct connection to TFT panels
 - 800x600 non-interlaced TFT @ 16 bpp graphics, up to 85 Hz
 - 1024x768 non-interlaced TFT @ 16 bpp graphics, up to 75 Hz
 - TFT on IDE: FPCLK max is 40 MHz
 - TFT on Parallel Port: FPCLK max is 80 MHz

Core Logic Module

- Audio Codec Interface:
 - AC97/AMC97 (Rev. 2.0) codec interface
 - Six DMA channels
- PC/AT Functionality:
 - Programmable Interrupt Controller (PIC), 8259A-equivalent
 - Programmable Interval Timer (PIT), 8254-equivalent
 - DMA Controller (DMAC), 8237-equivalent
- Power Management:
 - ACPI v1.0 compliant
 - Sx state control of three power planes
 - Cx/Sx state control of clocks and PLLs
 - Thermal event input
 - Wakeup event support:
 - Three general-purpose events
 - AC97 codec event
 - UART2 RI# signal
 - Infrared (IR) event
- General Purpose I/Os (GPIOs):
- 27 multiplexed GPIO signals
- Low Pin Count (LPC) Bus Interface:
 - Specification v1.0 compatible



■ PCI Bus Interface:

- PCI v2.1 compliant with wakeup capability
- 32-Bit data path, up to 33 MHz
- Glueless interface for an external PCI device
- Fixed priority
- 3.3V signal support only

■ Sub-ISA Bus Interface:

- Up to 16 MB addressing
- Supports a chip select for ROM or Flash EPROM boot device
- Supports either:
 - M-Systems DiskOnChip DOC2000 Flash file system
 - NAND EEPROM
- Supports up to two chip selects for external I/O devices
- 8-Bit (optional 16-bit) data bus width
- Shares balls with PCI signals
- Is not a subtractive agent

■ IDE Interface:

- Two IDE channels for up to four external IDE devices
- Supports ATA-33 synchronous DMA mode transfers, up to 33 MB/s
- Universal Serial Bus (USB):
 - USB OpenHCI v1.0 compliant
 - Three ports

SuperI/O Module

- Real-Time Clock (RTC):
 - DS1287, MC146818 and PC87911 compatible
 - Multi-century calendar
- ACCESS.bus (ACB) Interface:
 - Two ACB interface ports
- Parallel Port:
 - EPP 1.9 compliant
 - IEEE 1284 ECP compliant, including level 2
- Serial Port (UART):
 - UART1, 16550A compatible (SIN, SOUT, BOUT pins), used for SmartCard interface
 - UART2, 16550A compatible
 - Enhanced UART with fast Infrared (IR)

Other Features

- High-Resolution Timer:
 - 32-Bit counter with 1 μs count interval
- WATCHDOG Timer:
 - Interfaces to INTR, SMI, Reset

■ Clocks:

- Input (external crystals):
 - 32.768 KHz (internal clock oscillator)
 - 27 MHz (internal clock oscillator)
- Output:
 - AC97 clock (24.576 MHz)
 - Memory controller clock (66 MHz to 100 MHz)
 - PCI clock (33 MHz)
- JTAG Testability:
 - Bypass, Extest, Sample/Preload, IDcode, Clamp, HiZ

■ Voltages

- Internal logic: 266 or 233 MHz @ 1.8V
- Standby logic: 266 or 233 MHz @ 1.8V
- I/O: 3.3V
- Standby I/O: 3.3V
- Battery (if used): 3.0V

Revision 5.1 AMD

Architecture Overview Revision 5.1

Architecture Overview

As illustrated in Figure 1-1 on page 13, the SC3200 processor contains the following modules in one integrated device:

GX1 Module:

 Combines advanced CPU performance with MMX support, fully accelerated 2D graphics, a 64-bit synchronous DRAM (SDRAM) interface and a PCI bus controller. Integrates GX1 silicon revision 8.1.1.

• Video Processor Module:

 A low-power TFT support module with a video input port, and a hardware video accelerator for scaling, filtering and color space conversion.

· Core Logic Module:

 Includes PC/AT functionality, an IDE interface, a Universal Serial Bus (USB) interface, ACPI v1.0 compliant power management, and an audio codec interface.

SuperI/O Module:

 Includes two Serial Ports, an Infrared (IR) Port, a Parallel Port, two ACCESS.bus interfaces, and a Real-Time Clock (RTC).

2.1 GX1 Module

The GX1 processor (silicon revision 8.1.1) is the central module of the SC3200. For detailed information regarding the GX1 module, refer to the AMD Geode™ GX1 Processor Data Book and the AMD Geode™ GX1 Processor Silicon Revision 8.1.1 Specification Update documents.

The SC3200 processor's device ID is contained in the GX1 module. Software can detect the revision by reading the DIR0 and DIR1 Configuration registers (see Configuration registers in the AMD GeodeTM GX1 Processor Data Book). The AMD GeodeTM SC3200 Specification Update document contains the specific values.

2.1.1 Memory Controller

The GX1 module is connected to external SDRAM devices. For more information see Section 3.4.2 "Memory Interface Signals" on page 65, and the "Memory Controller" chapter in the *AMD Geode* GX1 Processor Data Book.

There are some differences in the SC3200 processor's memory controller and the stand-alone GX1 processor's memory controller:

- There is drive strength/slew control in the SC3200 that is not in the GX1. The bits that control this function are in the MC_MEM_CNTRL1 and MC_MEM_CNTRL2 registers. In the GX1 processor, these bits are marked as reserved.
- 2) The SC3200 supports two banks of memory. The GX1 supports four banks of memory. In addition, the SC3200 supports a maximum of eight devices and the GX1 supports up to 32 devices. With this difference, the MC_BANK_CFG register is different.

Table 2-1 summarizes the 32-bit registers contained in the SC3200 processor's memory controller. Table 2-2 gives detailed register/bit formats.

Table 2-1. SC3200 Memory Controller Register Summary

GX_BASE+ Memory Offset	Width (Bits)	Туре	Name/Function	Reset Value
8400h-8403h	32	R/W	MC_MEM_CNTRL1. Memory Controller Control Register 1	248C0040h
8404h-8407h	32	R/W	MC_MEM_CNTRL2. Memory Controller Control Register 2	00000801h
8408h-840Bh	32	R/W	MC_BANK_CFG. Memory Controller Bank Configuration	41104110h
840Ch-840Fh	32	R/W	MC_SYNC_TIM1. Memory Controller Synchronous Timing Register 1 2A733225h	
8414h-8417h	32	R/W	MC_GBASE_ADD. Memory Controller Graphics Base Address Register	00000000h
8418h-841Bh	32	R/W	MC_DR_ADD. Memory Controller Dirty RAM Address Register	00000000h
841Ch-841Fh	32	R/W	MC_DR_ACC. Memory Controller Dirty RAM Access Register	0000000xh

Table 2-2. SC3200 Memory Controller Registers

Bit	Description		
GX_BASE+	8400h-8403h	MC_MEM_CNTRL1 (R/W)	Reset Value: 248C0040h
31:30	MDCTL (MD[63:0] Driv	e Strength). 11 is strongest, 00 is weakest.	
29	RSVD (Reserved) Writ	e as 0.	
28:27	MABACTL (MA[12:0] a	nd BA[1:0] Drive Strength). 11 is strongest, 00 is weakest.	
26	RSVD (Reserved). Wri	te as 0.	
25:24	MEMCTL (RASA#, CAS	SA#, WEA#, CS[1:0]#, CKEA, DQM[7:0] Drive Strength). 11	is strongest, 00 is weakest.
23:22	RSVD (Reserved). Wri	te as 0.	
21	RSVD (Reserved). Mus	st be written as 0. Wait state on the X-Bus x_data during rea	ad cycles - for debug only.
20:18	SDCLKRATE (SDRAM	Clock Ratio). Selects SDRAM clock ratio.	
	000: Reserved 001: ÷ 2 010: ÷ 2.5 011: ÷ 3 (Default) Ratio does not take effe	100: ÷ 3.5 101: ÷ 4 110: ÷ 4.5 111: ÷ 5 ect until the SDCLKSTRT bit (bit 17 of this register) transition	ns from 0 to 1.
17	SDCLKSTRT (Start SE ister). 0: Clear. 1: Enable.	OCLK). Start operating SDCLK using the new ratio and shift	value (selected in bits [20:18] of this reg-
16:8		from zero (written to zero) to one (written to one) in order to a nterval). This field determines the number of processor core	
		default, the refresh interval is 00h. Refresh is turned off by	
7:6	RFSHSTAG (Refresh Stour banks during refresh	Staggering). This field determines number of clocks between sh cycles:	en the RFSH commands to each of the
	00: 0 SDRAM clocks 01: 1 SDRAM clocks (D 10: 2 SDRAM clocks 11: 4 SDRAM clocks	Default)	
	Staggering is used to he this field must be written	elp reduce power spikes during refresh by refreshing one ba n as 00.	nk at a time. If only one bank is installed,
5	2CLKADDR (Two Cloc	k Address Setup). Assert memory address for one extra c	lock before CS# is asserted.
	0: Disable. 1: Enable.		
	This can be used to cor	mpensate for address setup at high frequencies and/or high	loads.

Table 2-2. SC3200 Memory Controller Registers (Continued)

Bit	Description						
4	RFSHTST (Test Refresh). This bit, when se	t high, generates a refresh request. This I	bit is only used for testing purposes.				
3	troller requests are arbitrated at the same pri	XBUSARB (X-Bus Round Robin). When round robin is enabled, processor, graphics pipeline, and low priority display con troller requests are arbitrated at the same priority level. When disabled, processor requests are arbitrated at a higher priority level. High priority Display Controller requests always have the highest arbitration priority.					
	0: Disable.1: Enable round robin.						
2	SMM_MAP (SMM Region Mapping). Maps BFFFF in SDRAM.	the SMM memory region at GX_BASE+4	00000 to physical address A0000 to				
	0: Disable. 1: Enable.						
1	RSVD (Reserved). Write as 0.						
0	SDRAMPRG (Program SDRAM). When this LTMODE in MC_SYNC_TIM1.	s bit is set, the memory controller will prog	gram the SDRAM MRS register using				
	This bit must transition from zero (written to	zero) to one (written to one) in order to pro	ogram the SDRAM devices.				
GX_BASI	SE+8404h-8407h MC	_MEM_CNTRL2 (R/W)	Reset Value: 00000801h				
31:14	RSVD (Reserved). Write as 0.						
13:12	SDCLKCTL (SDCLK High Drive/Slew Con 11 is strongest, 00 is weakest.	trol). Controls the high drive and slew rate	e of SDCLK[3:0] and SDCLK_OUT.				
11	RSVD (Reserved). Write as 0.						
10	SDCLKOMSK# (Enable SDCLK_OUT). Tur	ns on the output.					
	0: Enable. 1: Disable.						
9	SDCLK3MSK# (Enable SDCLK3). Turns on	the output.					
	0: Enable.						
	1: Disable.						
8	SDCLK2MSK# (Enable SDCLK2). Turns or	the output.					
	0: Enable. 1: Disable.						
7	SDCLK1MSK# (Enable SDCLK1). Turns on	a the output. O					
,	0: Enable.	The output. o					
	1: Disable.						
6	SDCLK0MSK# (Enable SDCLK0). Turns or	the output.					
	0: Enable.						
	1: Disable.						
5:3	SHFTSDCLK (Shift SDCLK). This function shift function will not take effect until the SDC	CLKSTRT bit (bit 17 of MC_MEM_CNTRL					
	000: No shift 001: Shift 0.5 core clock	100: Shift 2 core clocks 101: Shift 2.5 core clocks					
	010: Shift 1 core clock 101: Shift 3 core clocks						
	011: Shift 1.5 core clock	111: Reserved					
2	RSVD (Reserved). Write as 0.						
1	RD (Read Data Phase). Selects if read data	is latched one or two core clock after the	rising edge of SDCLK.				
	0: 1 Core clock. 1: 2 Core clocks.						
0	FSTRDMSK (Fast Read Mask). Do not allow	w core reads to bypass the request FIFO.					
	0: Disable.						
	1: Enable.						

Revision 5.1 Architecture Overview

Table 2-2. SC3200 Memory Controller Registers (Continued)

Bit	Description									
GX_BASE	+8408h-840Bh		MC_BANK_CF	G (R/W)	Reset Value: 41104110h					
31:16	RSVD (Reserved	I). Write as 0070h								
15	RSVD (Reserved	I). Write as 0.								
14	SODIMM_MOD_I for SODIMM:	SODIMM_MOD_BNK (SODIMM Module Banks - Banks 0 and 1). Selects number of module banks installed per SODIMM for SODIMM:								
	0: 1 Module bank 1: 2 Module bank	` ,								
13	RSVD (Reserved	I). Write as 0.								
12	module bank for S	SODIMM:	omponent Banks - E	Banks 0 and 1). Selects the	e number of component banks per					
	0: 2 Component b	oanks								
	1		number of component	banks.						
11	RSVD (Reserved	•								
10:8	_ ,		ss 0 and 1). Selects th							
	000: 4 MB 001: 8 MB	010: 16 MB 011: 32 MB	100: 64 MB 101: 128 MB	110: 256 MB 111: 512 MB						
			and 1. Also, banks 0	and 1 must be the same si	ze.					
7	RSVD (Reserved	<u> </u>								
6:4	SODIMM_PG_SZ 000: 1 KB 001: 2 KB	2 (SODIMM Page S 010: 4 KB 011: 8 KB	ize - Banks 0 and 1) 1xx: 16 KB 111: SODIMM no	. Selects the page size of s	SODIMM:					
		1 must have the sa		i i i stalica						
3:0	RSVD (Reserved		arrie page size.							
	+840Ch-840Fh		MC_SYNC_TIM	11 (R/W)	Reset Value: 2A733225h					
31	RSVD (Reserved	I). Write as 0.		(- /						
30:28	and the availability	y of the first piece o	of output data. This pa	rameter significantly affect	n the registration of a read command s system performance. Optimal setting CCESS.bus interface to determine this					
	000: Reserved	010: 2 CLK	100: 4 CLK	110: 6 CLK						
	001: Reserved	011: 3 CLK	101: 5 CLK	111: 7 CLK						
			·	C_MEM_CNTRL1) transitio						
27:24	commands:		d Period, tRC). Minim	ium number of SDRAM clo	ck between RFSH and RFSH/ACT					
	0000: Reserved 0001: 2 CLK	0100: 5 CLK 0101: 6 CLK	1000: 9 CLK 1001: 10 CLK	1100: 13 CLK 1101: 14 CLK						
	0010: 3 CLK	0110: 7 CLK	1010: 11 CLK	1110: 14 CLK 1110: 15 CLK						
	0011: 4 CLK	0111: 8 CLK	1011: 12 CLK	1111: 16 CLK						
23:20	RAS (ACT to PR	E Command Perio	d, tRAS). Minimum n	umber of SDRAM clocks b	etween ACT and PRE commands:					
	0000: Reserved	0100: 5 CLK	1000: 9 CLK	1100: 13 CLK						
	0001: 2 CLK	0101: 6 CLK	1001: 10 CLK	1101: 14 CLK						
	0010: 3 CLK 0011: 4 CLK	0110: 7 CLK 0111: 8 CLK	1010: 11 CLK 1011: 12 CLK	1110: 15 CLK 1111: 16 CLK						
19	RSVD (Reserved									
18:16	` `	•	, tRP). Minimum num	ber of SDRAM clocks betw	veen PRE and ACT commands:					
	000: Reserved 001: 1 CLK	010: 2 CLK 011: 3 CLK	100: 4 CLK 101: 5 CLK	110: 6 CLK 111: 7 CLK						
15	RSVD (Reserved	I). Write as 0.			RSVD (Reserved). Write as 0. RCD (Delay Time ACT to READ/WRT Command, tRCD). Minimum number of SDRAM clock between ACT and READ/WRT commands. This parameter significantly affects system performance. Optimal setting should be used:					
15 14:12	RCD (Delay Time	ACT to READ/WI								



Table 2-2. SC3200 Memory Controller Registers (Continued)

Bit	Description				
11	RSVD (Reserve	d). Write as 0.			
10:8	to two different co	omponent banks with to two different comp	nin the same modu	le bank. The memory contr	clocks between ACT and ACT command oller does not perform back-to-back Actinand between them. Hence, this field
7	RSVD (Reserve	d). Write as 0.			
6:4	•	PRE command per ank is precharged:	iod, tDPL). Minimu	ım number of SDRAM cloc	ks from the time the last write datum is
	000: Reserved 001: 1 CLK	010: 2 CLK 011: 3 CLK	100: 4 CLK 101: 5 CLK	110: 6 CLK 111: 7 CLK	
3:0	RSVD (Reserve	d). Leave unchanged	d. Always returns a	101h.	
Note: R	efer to the SDRAM	1 manufacturer's spe	cification for more	information on component	banks.
GX_BASE	+8414h-8417h		MC_GBASE_A	ADD (R/W)	Reset Value: 00000000h
31:18	RSVD (Reserve	d). Write as 0.			
17	TE (Test Enable	TEST[3:0]).			
		driven low (normal of are used to output			
16	TECTL (Test En	able Shared Contro	ol Pins).		
		8#, CKEB, WEB# (no 8#, CKEB, WEB# are		st information	
15:12	SEL (Select). Th	is field is used for de	ebug purposes only	and should be left at zero	for normal operation.
11	RSVD (Reserve	d). Write as 0.			
10:0	` .	cs Base Address). This field correspond		0 1	address, which is programmable on 512
	Note that BC_DR	RAM_TOP must be s	et to a value lower	than the Graphics Base Ac	ddress.
GX_BASE	+8418h-841Bh		MC_DR_AD	D (R/W)	Reset Value: 00000000h
31:10	RSVD (Reserve	d). Write as 0.			
9:0		AM Address). This d does not auto incre		index that is used to acces	ss the Dirty RAM with the MC_DR_ACC
GX_BASE	+841Ch-841Fh		MC_DR_AC	C (R/W)	Reset Value: 0000000xh
31:2	RSVD (Reserve	d). Write as 0.			
1	D (Dirty Bit). Thi	s bit is read/write ac	cessible.		
0	V (Valid Bit). Thi	s bit is read/write ac	cessible.		

2.1.2 Fast-PCI Bus

The GX1 module communicates with the Core Logic module via a Fast-PCI bus that can work at up to 66 MHz. The Fast-PCI bus is internal for the SC3200 and is connected to the General Configuration Block (see Section 4.0 on page 87 for details on the General Configuration Block).

This bus supports seven bus masters. The requests (REQs) are fixed in priority. The seven bus masters in order of priority are:

- 1) VIP
- 2) IDE Channel 0
- 3) IDE Channel 1
- 4) Audio
- 5) USB
- 6) External REQ0#
- 7) External REQ1#

2.1.3 Display

The GX1 module generates display timing, and controls internal VSYNC and HSYNC signals of the Video Processor module.

The GX1 module interfaces with the Video Processor via a video data bus and a graphics data bus.

- Video data. The GX1 module uses the core clock, divided by 2 or 4 (typically 100 - 133 MHz). It drives the video data using this clock. Internal signals VID_VAL and VID_RDY are used as data-flow handshake signals between the GX1 module and the Video Processor.
- Graphics data. The GX1 module uses the internal signal DCLK, supplied by the PLL of the Video Processor, to drive the 18-bit graphics-data bus of the Video Processor. Each six bits of this bus define a different color. Each of these 6-bit color definitions is expanded (by adding two zero LSB lines) to form an 8bit bus, at the Video Processor.

For more information about the GX1 module's interface to the Video Processor, see the "Display Controller" chapter in the $AMD\ Geode^{TM}\ GX1\ Processor\ Data\ Book.$

2.2 Video Processor Module

The Video Processor provides high resolution and graphics for a TFT/DSTN interface. The following subsections provide a summary of how the Video Processor interfaces with the other modules of the SC3200. For detailed information about the Video Processor, see Section 7.0 "Video Processor Module" on page 327.

2.2.1 GX1 Module Interface

The Video Processor is connected to the GX1 module in the following way:

- The Video Processor's DOTCLK output signal is used as the GX1 module's DCLK input signal.
- The GX1 module's PCLK output signal is used as the GFXCLK input signal of the Video Processor.

2.2.2 Video Input Port

The Video Input Port (VIP) within the Video Processor contains a standard interface that is typically connected to a media processor or TV encoder. The clock is supplied by the externally connected device; typically at 27 MHz.

Video input can be sent to the GX1 module's video frame buffer (Capture Video mode) or can be used directly (Direct Video mode).

2.2.3 Core Logic Module Interface

The Video Processor interfaces to the Core Logic module for accessing PCI function configuration registers.

2.3 Core Logic Module

The Core Logic module is described in detail in Section 6.0 "Core Logic Module" on page 157.

The Core Logic module is connected to the Fast-PCI bus. It uses signal AD28 as the IDSEL for all PCI configuration functions except for USB which uses AD29.

2.3.1 Other Core Logic Module Interfaces

The following interfaces of the Core Logic module are implemented via external balls of the SC3200. Each interface is listed below with a reference to the descriptions of the relevant balls.

- IDE: See Section 3.4.9 "IDE Interface Signals" on page 75
- AC97: See Section 3.4.14 "AC97 Audio Interface Signals" on page 80.
- PCI: See Section 3.4.6 "PCI Bus Interface Signals" on page 68.
- USB: See Section 3.4.10 "Universal Serial Bus (USB) Interface Signals" on page 76. The USB function uses signal AD29 as the IDSEL for PCI configuration.
- LPC: See Section 3.4.8 "Low Pin Count (LPC) Bus Interface Signals" on page 74.

Architecture Overview Revision 5.1

- Sub-ISA: See Section 3.4.7 "Sub-ISA Interface Signals" on page 73, Section 6.2.5 "Sub-ISA Bus Interface" on page 163, and Section 4.2 "Multiplexing, Interrupt Selection, and Base Address Registers" on page 88
- GPIO: See Section 3.4.16 "GPIO Interface Signals" on page 82.
- More detailed information about each of these interfaces is provided in Section 6.2 "Module Architecture" on page 158.
- Super/IO Block Interfaces: See Section 4.2 "Multiplexing, Interrupt Selection, and Base Address Registers" on page 88, Section 3.4.5 "ACCESS.bus Interface Signals" on page 67, Section 3.4.13 "Fast Infrared (IR) Port Interface Signals" on page 79, and Section 3.4.12 "Parallel Port Interface Signals" on page 78.

The Core Logic module interface to the GX1 module consists of seven miscellaneous connections, the PCI bus interface signals, plus the display controller connections. Note that the PC/AT legacy signals NMI, WM_RST, and A20M are all virtual functions executed in SMM (System Management Mode) by the BIOS.

- PSERIAL is a one-way serial bus from the GX1 to the Core Logic module used to communicate powermanagement states and VSYNC information for VGA emulation.
- IRQ13 is an input from the GX1 module indicating that a floating point error was detected and that INTR should be asserted.
- INTR is the level output from the integrated 8259A PICs and is asserted if an unmasked interrupt request (IRQn) is sampled active.
- SMI# is a level-sensitive interrupt to the GX1 module that can be configured to assert on a number of different system events. After an SMI# assertion, SMM is entered and program execution begins at the base of the SMM address space. Once asserted, SMI# remains active until the SMI source is cleared.
- SUSP# and SUSPA# are handshake signals for implementing CPU Clock Stop and clock throttling.
- CPU_RST resets the CPU and is asserted for approximately 100 µs after the negation of POR#.
- PCI bus interface signals.

2.4 Super I/O Module

The SuperI/O (SIO) module is a PC98 and ACPI compliant SIO that offers a single-cell solution to the most commonly used ISA peripherals.

The SIO module incorporates: two Serial Ports, an Infrared Communication Port that supports FIR, MIR, HP-SIR, Sharp-IR, and Consumer Electronics-IR, a full IEEE 1284 Parallel Port, two ACCESS.bus Interface (ACB) ports, System Wakeup Control (SWC), and a Real-Time Clock (RTC) that provides RTC timekeeping.

2.5 Clock, Timers, and Reset Logic

In addition to the four main modules (i.e., GX1, Core Logic, Video Processor and SIO) that make up the SC3200, the following blocks of logic have also been integrated into the SC3200:

- Clock Generators as described in Section 4.5 "Clock Generators and PLLs" on page 99.
- Configuration Registers as described in Section 4.2 "Multiplexing, Interrupt Selection, and Base Address Registers" on page 88.
- A WATCHDOG timer as described in Section 4.3 "WATCHDOG" on page 95.
- A High-Resolution timer as described in Section 4.4 "High-Resolution Timer" on page 97.

2.5.1 Reset Logic

This section provides a description of the reset flow of the SC3200.

2.5.1.1 Power-On Reset

Power-on reset is triggered by assertion of the POR# signal. Upon power-on reset, the following things happen:

- · Strap balls are sampled.
- PLL4, PLL5, and PLL6 are reset, disabling their output. When the POR# signal is negated, the clocks lock and then each PLL outputs its clock. PLL6 is the last clock generator to output a clock. See Section 4.5 "Clock Generators and PLLs" on page 99.
- Certain WATCHDOG and High-Resolution Timer register bits are cleared.

2.5.1.2 System Reset

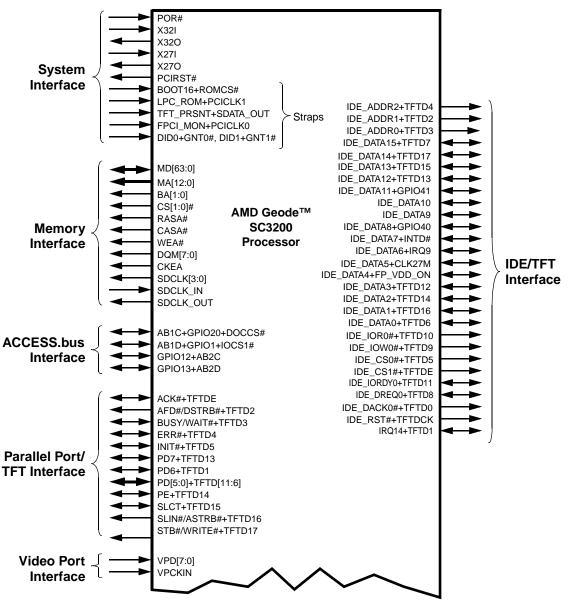
System reset causes signal PCIRST# to be issued, thus triggering a reset of all PCI and LPC agents. A system reset is triggered by any of the following events:

- Power-on, as indicated by POR# signal assertion.
- A WATCHDOG reset event (see Section 4.3.2 "WATCHDOG Registers" on page 96).
- Software initiated system reset.

Signal Definitions

This section defines the signals and describes the external interface of the SC3200. Figure 2-1 shows the signals organized by their functional groups. Where signals are multiplexed, the default signal name is listed first and is

separated by a plus sign (+). A slash (/) in a signal name means that the function is always enabled and available (i.e., cycle multiplexed).



Note: Straps are not the default signal, shown with system signals for reader convenience. However, also listed in figure with the appropriate functional group.

Figure 3-1. Signal Groups

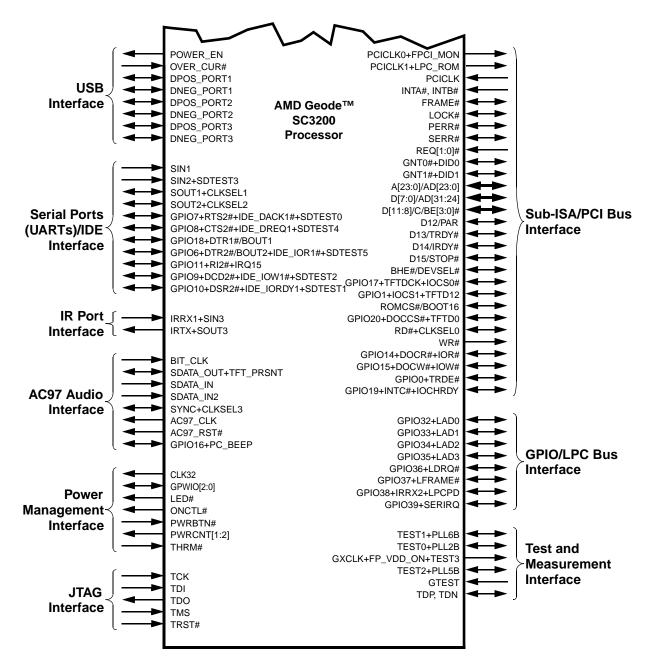


Figure 3-1. Signal Groups (Continued)

The remaining subsections of this chapter describe:

- Section 3.1 "Ball Assignments": Provides a ball assignment diagram and tables listing the signals sorted according to ball number and alphabetically by signal name.
- Section 3.2 "Strap Options": Several balls are read at power-up that set up the state of the SC3200. This section provides details regarding those balls.
- Section 3.3 "Multiplexing Configuration": Lists multiplexing options and their configurations.
- Section 3.4 "Signal Descriptions": Detailed descriptions of each signal according to functional group.

Signal Definitions Revision 5.1 AMD

3.1 Ball Assignments

The SC3200 is highly configurable as illustrated in Figure 3-1 on page 25. Strap options and register programming are used to set various modes of operation and specific signals on specific balls. This section describes which signals are available on which balls and provides configuration information:

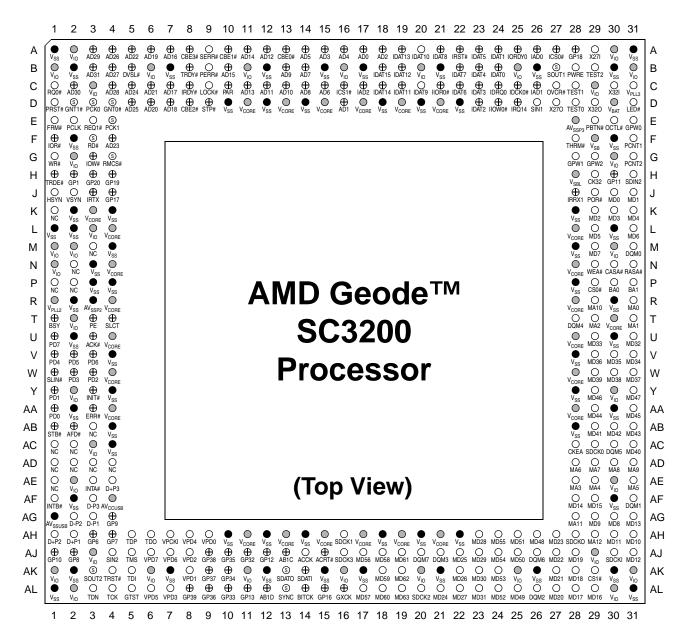
- Figure 3-2 on page 28 and Figure 3-3 on page 42: Illustrations of EBGA and TEPBGA ball assignments.
- Table 3-2 on page 29 and Table 3-4 on page 43: Lists signals according to ball number. Power Rail, Signal Type, Buffer Type and, where relevant, Pull-Up or Pull-Down resistors are indicated for each ball in this table. For multiplexed balls, the necessary configuration for each signal is listed as well.
- Table 3-3 on page 38 and Table 3-5 on page 54: Quick reference signal list sorted alphabetically - listing all signal names and ball numbers. The tables in this chapter use several common abbreviations. Table 3-1 lists the mnemonics and their meanings

Notes:

- For each GPIO signal, there is an optional pull-up resistor on the relevant ball. After system reset, the pull-up is present.
 - This pull-up resistor can be disabled via registers in the Core Logic module. The configuration is without regard to the selected ball function (except for GPIO12, GPIO13, and GPIO16). Alternate functions for GPIO12, GPIO13, and GPIO16 control pull-up resistors.
 - For more information, see Section 6.4.1 "Bridge, GPIO, and LPC Registers Function 0" on page 206.
- 2) Configuration settings listed in this table are with regard to the Pin Multiplexing Register (PMR). See Section 4.2 "Multiplexing, Interrupt Selection, and Base Address Registers" on page 88 for a detailed description of this register.

Table 3-1. Signal Definitions Legend

Mnemonic	Definition
Α	Analog
AV _{SS}	Ground ball: Analog
AV _{CC}	Power ball: Analog
GCB	General Configuration Block registers. Refer to Section 4.0 "General Configuration Block" on page 87. Location of the General Configuration
	Block cannot be determined by software. See the AMD Geode™ SC3200 Specification Update document.
1	Input ball
I/O	Bidirectional ball
MCR[x]	Miscellaneous Configuration Register Bit x: A register, located in the GCB. Refer to Section 4.1 "Configuration Block Addresses" on page 87 for further details.
0	Output ball
OD	Open-drain
PD	Pull-down
PMR[x]	Pin Multiplexing Register Bit x: A register, located in the GCB, used to configure balls with multiple functions. Refer to Section 4.1 "Configuration Block Addresses" on page 87 for further details.
PU	Pull-up
TS	TRI-STATE
V _{CORE}	Power ball: 1.2V
V _{IO}	Power ball: 3.3V
V _{SS}	Ground ball
#	The # symbol in a signal name indicates that the active or asserted state occurs when the signal is at a low voltage level. Otherwise, the signal is asserted when at a high voltage level.
/	A / in a signal name indicates both functions are always enabled (i.e., cycle multiplexed).
+	A + in signal name indicates the function is available on the ball, but that either strapping options or register programming is required to select the desired function.



Note: Signal names have been abbreviated in this figure due to space constraints.

- = GND Ball
- = PWR Ball
- Strap Option Ball
- ⊕ = Multiplexed Ball

Figure 3-2. 432-EBGA Ball Assignment Diagram



Table 3-2. 432-EBGA Ball Assignment - Sorted by Ball Number

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
A1	V _{SS}	GND			
A2	V _{IO}	PWR	-		
A3	AD29	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D5	I/O	IN _{PCI} , O _{PCI}		
A4	AD26	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D2	I/O	IN _{PCI} , O _{PCI}		
A5	AD22	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A22	0	O _{PCI}		
A6	AD19	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A19	0	O _{PCI}		
A7	AD16	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A16	0	O _{PCI}		
A8	C/BE3#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D11	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
A9	SERR#	I/O (PU _{22.5})	IN _{PCI} , OD _{PCI}	V _{IO}	
A10	C/BE1#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D9	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
A11	AD14	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A14	0	O _{PCI}		
A12	AD12	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A12	0	O _{PCI}		
A13	C/BE0#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D8	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
A14	AD5	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A5	0	O _{PCI}		
A15	AD3	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A3	0	O _{PCI}		
A16	AD4	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A4	0	O _{PCI}		
A17	AD0	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A0	0	O _{PCI}		

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
A18	AD2	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A2	0	O _{PCI}		
A19	IDE_DATA13	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD15	0	O _{1/4}		PMR[24] = 1
A20	IDE_DATA10	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
A21	IDE_DATA8	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	GPIO40	I/O	IN _{TS1} , O _{1/4}		PMR[24] = 1
A22	IDE_RST#	0	O _{1/4}	V_{IO}	PMR[24] = 0
	TFTDCK	0	O _{1/4}		PMR[24] = 1
A23	IDE_DATA5	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	CLK27M	0	O _{1/4}		PMR[24] = 1
A24	IDE_DATA1	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD16	0	O _{1/4}		PMR[24] = 1
A25	IDE_IORDY0	I	IN _{TS1}	V _{IO}	PMR[24] = 0
	TFTD11	0	O _{1/4}		PMR[24] = 1
A26	IDE_ADDR0	0	O _{1/4}	V _{IO}	PMR[24] = 0
	TFTD3	0	O _{1/4}		PMR[24] = 1
A27	IDE_CS0#	0	O _{1/4}	V_{IO}	PMR[24] = 0
	TFTD5	0	O _{1/4}		PMR[24] = 1
A28	GPIO18	I/O (PU _{22.5})	IN _{TS} , O _{8/8}	V _{IO}	PMR[16] = 0
	DTR1#/BOUT1	O (PU _{22.5})	O _{8/8}		PMR[16] =1
A29	X27I	I	WIRE	V _{IO}	
A30	V _{IO}	PWR			
A31	V _{SS}	GND			
B1	V _{IO}	PWR			
B2	V _{SS}	GND			
B3	AD31	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D7	I/O	IN _{PCI} , O _{PCI}		
B4	AD27	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D3	I/O	IN _{PCI} , O _{PCI}		
B5	DEVSEL#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	BHE#	0	O _{PCI}		
B6	V _{IO}	PWR			
B7	V _{SS}	GND			
B8	TRDY#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D13	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		

Table 3-2. 432-EBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
B9	PERR#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	
B10	AD15	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A15	0	O _{PCI}		
B11	V _{IO}	PWR			
B12	V_{SS}	GND			
B13	AD9	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A9	0	O _{PCI}		
B14	AD7	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A7	0	O _{PCI}		
B15	V _{SS}	GND			
B16	V _{IO}	PWR			
B17	V _{SS}	GND			
B18	IDE_DATA15	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD7	0	O _{1/4}		PMR[24] = 1
B19	IDE_DATA12	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD13	0	O _{1/4}		PMR[24] = 1
B20	V _{IO}	PWR			
B21	V _{SS}	GND			
B22	IDE_DATA7	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	INTD#	1	IN _{TS}		PMR[24] = 1
B23	IDE_DATA4	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	FP_VDD_ON	0	O _{1/4}		PMR[24] = 1
B24	IDE_DATA0	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD6	0	O _{1/4}		PMR[24] = 1
B25	V _{IO}	PWR			
B26	V_{SS}	GND			
B27	SOUT1	0	O _{8/8}	V_{IO}	
	CLKSEL1	(PD ₁₀₀)	IN _{STRP}		Strap (See Table 3-6 on page 58.)
B28	POWER_EN	0	O _{1/4}	V _{IO}	
B29	TEST2	0	O _{2/5}	V_{IO}	PMR[29] = 1
	PLL5B	I/O	IN _T , TS _{2/5}		PMR[29] = 0
B30	V _{SS}	GND			
B31	V _{IO}	PWR			
C1	REQ0#	(PU _{22.5})	INPCI	V _{IO}	
C2	AD30	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D6	I/O	IN _{PCI} , O _{PCI}		
C3	V _{IO}	PWR			

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
C4	AD28	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D4	I/O	IN _{PCI} , O _{PCI}		
C5	AD24	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D0	I/O	IN _{PCI} , O _{PCI}		
C6	AD21	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A21	0	O _{PCI}		
C7	AD17	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A17	0	O _{PCI}		
C8	IRDY#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D14	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
C9	LOCK#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	
C10	PAR	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D12	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
C11	AD13	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A13	0	O _{PCI}		
C12	AD11	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A11	0	O _{PCI}		
C13	AD10	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A10	0	O _{PCI}		
C14	AD8	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A8	0	O _{PCI}		
C15	AD6	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
0.10	A6	0	O _{PCI}	.,	D14D1241
C16	IDE_CS1#	0	O _{1/4}	V _{IO}	PMR[24] = 0
047	TFTDE	0	O _{1/4}		PMR[24] = 1
C17	IDE_ADDR2 TFTD4	0	O _{1/4}	V _{IO}	PMR[24] = 0
C19	IDE_DATA14	0	O _{1/4}	\/	PMR[24] = 1
C18		1/0	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
046	TFTD17	0	O _{1/4}	.,	PMR[24] = 1
C19	IDE_DATA11	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	GPIO41	I/O	IN _{TS1} , O _{1/4}		PMR[24] = 1
C20	IDE_DATA9	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0



Table 3-2. 432-EBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
C21	IDE_IOR0#	0	O _{1/4}	V _{IO}	PMR[24] = 0
	TFTD10	0	O _{1/4}		PMR[24] = 1
C22	IDE_DATA6	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	IRQ9	- 1	IN _{TS1}		PMR[24] = 1
C23	IDE_DATA3	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD12	0	O _{1/4}		PMR[24] = 1
C24	IDE_DREQ0	1	IN _{TS1}	V_{IO}	PMR[24] = 0
	TFTD8	0	O _{1/4}		PMR[24] = 1
C25	IDE_DACK0#	0	O _{1/4}	V _{IO}	PMR[24] = 0
	TFTD0	0	O _{1/4}		PMR[24] = 1
C26	IDE_ADDR1	0	O _{1/4}	V _{IO}	PMR[24] = 0
	TFTD2	0	O _{1/4}		PMR[24] = 1
C27	OVER_CUR#	I	IN _{TS}	V _{IO}	
C28	TEST1	0	O _{2/5}	V _{IO}	PMR[29] = 1
	PLL6B	I/O	IN _{TS} , TS _{2/5}		PMR[29] = 0
C29	V _{IO}	PWR			
C30	X32I	I	WIRE	V_{BAT}	
C31	V _{PLL3}	PWR			
D1	PCIRST#	0	O _{PCI}	V _{IO}	
D2	GNT1#	0	O _{PCI}	V _{IO}	
	DID1	(PD ₁₀₀)	IN _{STRP}		Strap (See Table 3-6 on page 58.)
D3	PCICLK0	0	O _{PCI}	V_{IO}	
	FPCI_MON	(PD ₁₀₀)	IN _{STRP}		Strap (See Table 3-6 on page 58.)
D4	GNT0#	0	O _{PCI}	V _{IO}	
	DID0	I (PD ₁₀₀)	IN _{STRP}		Strap (See Table 3-6 on page 58.)
D5	AD25	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D1	I/O	IN _{PCI} , O _{PCI}		
D6	AD20	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A20	0	O _{PCI}		
D7	AD18	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A18	0	O _{PCI}		
D8	C/BE2#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D10	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
D9	STOP#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D15	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
D10	V_{SS}	GND			

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
D11	V _{CORE}	PWR			
D12	V _{SS}	GND			
D13	V _{CORE}	PWR			
D14	V _{SS}	GND			
D15	V _{CORE}	PWR			
D16	AD1	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A1	0	O _{PCI}		
D17	V _{CORE}	PWR			
D18	V_{SS}	GND			
D19	V _{CORE}	PWR			
D20	V _{SS}	GND			
D21	V _{CORE}	PWR			
D22	V _{SS}	GND			
D23	IDE_DATA2	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD14	0	O _{1/4}		PMR[24] = 1
D24	IDE_IOW0#	0	O _{1/4}	V _{IO}	PMR[24] = 0
	TFTD9	0	O _{1/4}		PMR[24] = 1
D25	IRQ14	1	IN _{TS1}	V _{IO}	PMR[24] = 0
	TFTD1	0	O _{1/4}		PMR[24] = 1
D26	SIN1	ı	IN _{TS}	V _{IO}	
D27	X27O	0	WIRE	V _{IO}	
D28	TEST0	0	O _{2/5}	V _{IO}	PMR[29] = 1
	PLL2B	I/O	IN _T , TS _{2/5}		PMR[29] = 0
D29	X32O	0	WIRE	V _{BAT}	
D30	V _{BAT}	PWR			
D31	LED#	0	OD ₁₄	V _{SB}	
E1	FRAME#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	
E2	PCICLK	1	IN _T	V_{IO}	
E3	REQ1#	I (PU _{22.5})	IN _{PCI}	V _{IO}	
E4	PCICLK1	0	O _{PCI}	V_{IO}	
	LPC_ROM	(PD ₁₀₀₎	IN _{STRP}		Strap (See Table 3-6 on page 58.)
E28	AV _{SSPLL3}	GND			
E29	PWRBTN#	(PU ₁₀₀₎	IN _{BTN}	V _{SB}	
E30 ^{3, 4}	ONCTL#	0	OD ₁₄	V_{SB}	
E31	GPWIO0	I/O (PU ₁₀₀)	IN _{TS} , TS _{2/14}	V_{SB}	
F1	IOR#	0	O _{3/5}	V _{IO}	PMR[21] = 0 and PMR[2] = 0
	DOCR#	0	O _{3/5}		PMR[21] = 0 and PMR[2] = 1
	GPIO14	I/O (PU _{22.5})	IN _{TS} , O _{3/}		PMR[21] = 1 and PMR[2] = 1
F2	V_{SS}	GND			

Table 3-2. 432-EBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
F3	RD#	0	O _{3/5}	V _{IO}	
	CLKSEL0	(PD ₁₀₀)	IN _{STRP}		Strap (See Table 3-6 on page 58.)
F4	AD23	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A23	0	O _{PCI}		
F28	THRM#	I	IN _{TS}	V_{SB}	
F29	V_{SB}	PWR			
F30	V_{SS}	GND		-	
F31 ^{3, 4}	PWRCNT1	0	OD ₁₄	V_{SB}	
G1	WR#	0	O _{3/5}	V _{IO}	
G2	V _{IO}	PWR			
G3	IOW#	0	O _{3/5}	V _{IO}	PMR[21] = 0 and PMR[2] = 0
	DOCW#	0	O _{3/5}		PMR[21] = 0 and PMR[2] = 1
	GPIO15	I/O (PU _{22.5})	IN _{TS} , O _{3/}		PMR[21] = 1 and PMR[2] = 1
G4	ROMCS#	0	O _{3/5}	V _{IO}	
	BOOT16	I (PD ₁₀₀)	IN _{STRP}	V _{IO}	Strap (See Table 3-6 on page 58.)
G28	GPWIO1	I/O (PU ₁₀₀)	IN _{Ts} , TS _{2/14}	V_{SB}	
G29	GPWIO2	I/O (PU ₁₀₀)	IN _{TS} , TS _{2/14}	V_{SB}	
G30	V _{IO}	PWR			
G31 ^{3, 4}	PWRCNT2	0	OD ¹⁴	V _{SB}	
H1	TRDE#	0	O _{3/5}	V _{IO}	PMR[12] = 0
	GPIO0	I/O (PU _{22.5})	IN _{TS} , O _{3/}	V _{IO}	PMR[12] = 1
H2	GPIO1	I/O (PU _{22.5})	IN _T , O _{3/5}	V _{IO}	$PMR[23]^2 = 0$ and $PMR[13] = 0$
	IOCS1#	O (PU _{22.5})	O _{3/5}	V _{IO}	$PMR[23]^2 = 0$ and $PMR[13] = 1$
	TFTD12	O (PU _{22.5})	O _{1/4}	V _{IO}	$PMR[23]^2 = 1$
НЗ	GPIO20	I/O (PU _{22.5})	IN _T , O _{3/5}	V _{IO}	$PMR[23]^2 = 0$ and $PMR[7] = 0$
	DOCCS#	O (PU _{22.5})	O _{3/5}		$PMR[23]^2 = 0$ and $PMR[7] = 1$
	TFTD0	O (PU _{22.5})	O _{1/4}		$PMR[23]^2 = 1$
H4	GPIO19	I/O (PU _{22.5})	IN _{TS} , O _{3/}	V _{IO}	PMR[9] = 0 and PMR[4] = 0
	INTC#	(PU _{22.5})	IN _{TS}		PMR[9] = 0 and PMR[4] = 1
	IOCHRDY	I (PU _{22.5})	IN _{TS1}		PMR[9] = 1 and PMR[4] = 1
H28	V_{SBL}	PWR			
H29	CLK32	0	O _{2/5}	V _{SB}	

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
H30	GPIO11	I/O (PU _{22.5})	IN _{TS} , O _{8/8}	V _{IO}	PMR[18] = 0 and PMR[8] = 0
	RI2#	I (PU _{22.5})	IN _{TS}		PMR[18] = 1 and PMR[8] = 0
	IRQ15	I (PU _{22.5})	IN _{TS1}		PMR[18] = 0 and PMR[8] = 1
H31	SDATA_IN2	I	IN _{TS}	V_{SB}	F3BAR0+Memory Offset 08h[21] = 1
J1	HSYNC	0	O _{1/4}	V _{IO}	
J2	VSYNC	0	O _{1/4}	V _{IO}	
J3	IRTX	0	O _{8/8}	V _{IO}	PMR[6] = 0
	SOUT3	0	O _{8/8}		PMR[6] = 1
J4	GPIO17	I/O (PU _{22.5})	IN _{TS} , O _{3/}	V _{IO}	$PMR[23]^2 = 0$ and $PMR[5] = 0$
	IOCS0#	O (PU _{22.5})	O _{3/5}		$PMR[23]^2 = 0$ and $PMR[5] = 1$
	TFTDCK	O (PU _{22.5})	O _{1/4}		PMR[23] ² = 1
J28	IRRX1	I	IN _{TS}	V_{SB}	PMR[6] = 0
	SIN3	1	IN _{TS}	V _{IO}	PMR[6] =1
J29	POR#	I	IN _{TS}	V _{IO}	
J30 ³	MD0	I/O	IN _T , TS _{2/5}	V _{IO}	
J31 ³	MD1	I/O	IN _T , TS _{2/5}	V _{IO}	
K1	NC				
K2	V _{SS}	GND			
K3	V _{CORE}	PWR			
K4	V _{SS}	GND			
K28	V _{SS}	GND			
K29 ³	MD2	I/O	IN _T , TS _{2/5}	V _{IO}	
K30 ³	MD3	I/O	IN _T , TS _{2/5}	V _{IO}	
K31 ³	MD4	I/O	IN _T , TS _{2/5}	V _{IO}	
L1	V _{SS}	GND			
L2	V _{SS}	GND			
L3	V _{IO}	PWR			
L4	V _{CORE}	PWR			
L28	V _{CORE}	PWR			
L29 ³	MD5	I/O	IN _T , TS _{2/5}	V _{IO}	
L30	V _{SS}	GND			
L31 ³	MD6	I/O	IN _T , TS _{2/5}	V _{IO}	
M1	V _{IO}	PWR			
M2	V _{IO}	PWR			
M3	NC				
M4	V _{SS}	GND			
M28	V _{SS}	GND			
M29 ³	MD7	I/O	IN _T , TS _{2/5}	V _{IO}	
M30	V _{IO}	PWR			
M31	DQM0	0	O _{2/5}	V _{IO}	
N1	V _{IO}	PWR			
N2	NC				

Table 3-2. 432-EBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
N3	V _{SS}	GND			
N4	V _{CORE}	PWR			
N28	V _{CORE}	PWR			
N29	WEA#	0	O _{2/5}	V _{IO}	
N30	CASA#	0	O _{2/5}	V _{IO}	
N31	RASA#	0	O _{2/5}	V _{IO}	
P1	NC		-2/5		
P2	NC				
P3	V _{SS}	GND			
P4	V _{SS}	GND			
P28	V _{SS}	GND			
P29	CS0#	0	O _{2/5}	V _{IO}	
P30	BA0	0	O _{2/5}	V _{IO}	
P31	BA1	0	O _{2/5}	V _{IO}	
R1	V _{PLL2}	PWR		*10	
R2		GND			
R3	V _{SS}	GND			
	AV _{SSPLL2}	-			
R4	V _{CORE}	PWR			
R28	V _{CORE}	PWR			
R29	MA10	0	O _{2/5}	V _{IO}	
R30	V _{SS}	GND			
R31	MA0	0	O _{2/5}	V _{IO}	
T1 ^{3, 4}	BUSY/WAIT#	'	IN _T	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD3	0	O _{1/4}		$PMR[23]^2 = 1$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	F_C/BE1#	0	O _{1/4}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
T2	V _{IO}	PWR			
T3 ^{3, 4}	PE	I (PU _{22.5} PD _{22.5})	IN _T	V _{IO}	PMR[23] ² = 0 and (PMR[27] = 0 and FPCI_MON = 0) (PU/PD under soft- ware control.)
	TFTD14	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_C/BE2#	0	O _{1/4}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
T4 ^{3, 4}	SLCT	1	IN _T	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD15	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and } (PMR[27] = 0 \text{ and } FPCI_MON = 0)$
	F_C/BE3#	0	O _{1/4}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
T28	DQM4	0	O _{2/5}	V _{IO}	

Ball		I/O (PU/	Buffer ¹	Power	
No.	Signal Name	PD)	Туре	Rail	Configuration
T29	MA2	0	O _{2/5}	V _{IO}	
T30	V _{CORE}	PWR			
T31	MA1	0	O _{2/5}	V _{IO}	
U1 ^{3, 4}	PD7	I/O	IN _T , O _{14/}	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD13	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_AD7	0	O _{14/14}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
U2	V_{SS}	GND			
U3 ^{3, 4}	ACK#	I	IN _T	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTDE	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	FPCICLK	0	O _{1/4}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
U4	V_{CORE}	PWR		-	
U28	V _{CORE}	PWR			
U29 ³	MD33	I/O	IN _T , TS _{2/5}	V _{IO}	
U30	V _{SS}	GND			
U31 ³	MD32	I/O	IN _T , TS _{2/5}	V _{IO}	
V1 ^{3, 4}	PD4	I/O	IN _T , O _{14/}	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD10	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_AD4	0	O _{14/14}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
V2 ^{3, 4}	PD5	I/O	IN _T , O _{14/}	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD11	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_AD5	0	O _{14/14}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
V3 ^{3, 4}	PD6	1/0	IN _T , O _{14/}	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD1	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and } (PMR[27] = 0 \text{ and } FPCI_MON = 0$
	F_AD6	0	O _{14/14}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
V4	V _{SS}	GND			
V28	V _{SS}	GND			
V29 ³	MD36	I/O	IN _T , TS _{2/5}	V _{IO}	

Table 3-2. 432-EBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
V30 ³	MD35	I/O	${\sf IN_T}$, ${\sf TS}_{2/5}$	V_{IO}	
V31 ³	MD34	I/O	IN _T , TS _{2/5}	V _{IO}	
W1 ^{3, 4}	SLIN#/ASTRB#	0	O _{14/14}	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD16	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_IRDY#	0	O _{14/14}		PMR[23] ² = 0 and (PMR[27] = 1 or FPCI_MON = 1)
W2 ^{3, 4}	PD3	I/O	IN _T , O _{14/}	V _{IO}	PMR[23] ² = 0 and (PMR[27] = 0 and FPCI_MON = 0)
	TFTD9	0	O _{1/4}		PMR[23] ² = 1 and (PMR[27] = 0 and FPCI_MON = 0)
	F_AD3	0	O _{14/14}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
W3 ^{3, 4}	PD2	I/O	IN _T , O _{14/}	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD8	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_AD2	0	O _{14/14}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
W4	V_{CORE}	PWR		-	
W28	V_{CORE}	PWR			
W29 ³	MD39	I/O	${\sf IN_T}$, ${\sf TS}_{2/5}$	V_{IO}	
W30 ³	MD38	I/O	${\sf IN_T}$, ${\sf TS}_{2/5}$	V_{IO}	
W31 ³	MD37	I/O	IN _T , TS _{2/5}	V _{IO}	
Y1 ^{3, 4}	PD1	I/O	IN _T , O _{14/}	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD7	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_AD1	0	O _{14/14}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
Y2	V _{IO}	PWR		-	
Y3 ^{3, 4}	INIT#	0	O _{14/14}	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD5	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	SMI_O	0	O _{14/14}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
Y4	V _{SS}	GND			
Y28	V _{SS}	GND			
Y29 ³	MD46	I/O	IN _T , TS _{2/5}	V _{IO}	
Y30	V _{IO}	PWR			

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
AA1 ^{3, 4}	PD0	I/O	IN _T , O _{14/}	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD6	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and } (PMR[27] = 0 \text{ and } FPCI_MON = 0)$
	F_AD0	0	O _{14/14}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
AA2	V _{SS}	GND			
AA3 ^{3, 4}	ERR#	I	IN _T , O _{1/4}	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD4	0	O _{1/4}		PMR[23] ² = 1 and (PMR[27] = 0 and FPCI_MON = 0)
	F_C/BE0#	0	O _{1/4}		PMR[23] ² = 0 and (PMR[27] = 1 or FPCI_MON = 1)
AA4	V _{CORE}	PWR			
AA28	V _{CORE}	PWR			
AA29 ³	MD44	I/O	IN _T , TS _{2/5}	V_{IO}	
AA30	V _{SS}	GND			
AA31 ³	MD45	I/O	IN_T , $TS_{2/5}$	V_{IO}	
AB1 ^{3, 4}	STB#/WRITE#	0	O _{14/14}	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD17	0	O ^{1/4}		$PMR[23]^2 = 1 \text{ and } (PMR[27] = 0 \text{ and } FPCI_MON = 0)$
	F_FRAME#	0	O _{14/14}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
AB2 ^{3, 4}	AFD#/DSTRB#	0	O _{14/14}	V _{IO}	$PMR[23]^2 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD2	0	O _{1/4}		$PMR[23]^2 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	INTR_O	0	O _{14/14}		$PMR[23]^2 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
AB3	NC				
AB4	V _{SS}	GND			
AB28	V _{SS}	GND			
AB29 ³	MD41	I/O	IN _T , TS _{2/5}	V_{IO}	
AB30 ³	MD42	I/O	IN _T , TS _{2/5}	V_{IO}	
AB31 ³	MD43	I/O	IN _T , TS _{2/5}	V_{IO}	
AC1	NC				
AC2	NC				
AC3	V _{IO}	PWR			
AC4	V _{SS}	GND			
AC28	CKEA	0	O _{2/5}	V _{IO}	
AC29	SDCLK0	0	O _{2/5}	V _{IO}	
AC30	DQM5	0	O _{2/5}	V _{IO}	
AC31 ³	MD40	I/O	IN _T , TS _{2/5}	V _{IO}	



Table 3-2. 432-EBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
AD1	NC			-	
AD2	NC			-	
AD3	NC				
AD4	NC				
AD28	MA6	0	O _{2/5}	V_{IO}	
AD29	MA7	0	O _{2/5}	V_{IO}	
AD30	MA8	0	O _{2/5}	V_{IO}	
AD31	MA9	0	O _{2/5}	V _{IO}	
AE1	NC			-	
AE2	V _{IO}	PWR			
AE3	INTA#	I (PU _{22.5})	IN _{PCI}	V _{IO}	
AE4 ³	DPOS_PORT3	I/O	IN _{USB} , O _{USB}	AV _C - CUSB	
AE28	MA3	0	O _{2/5}	V _{IO}	
AE29	MA4	0	O _{2/5}	V _{IO}	
AE30	V _{IO}	PWR			
AE31	MA5	0	O _{2/5}	V _{IO}	
AF1	INTB#	I (PU _{22.5})	IN _{PCI}	V _{IO}	
AF2	V _{SS}	GND			
AF3 ³	DNEG_PORT3	I/O	IN _{USB} , O _{USB}	AV _C -	
AF4	AV _{CCUSB}	PWR			
AF28 ³	MD14	I/O	IN _T , TS _{2/5}	V _{IO}	
AF29 ³	MD15	I/O	IN _T , TS _{2/5}	V _{IO}	
AF30	V _{SS}	GND			
AF31	DQM1	0	O _{2/5}	V _{IO}	
AG1	AV _{SSUSB}	GND			
AG2 ³	DNEG_PORT2	I/O	IN _{USB} , O _{USB}	AV _C -	
AG3 ³	DNEG_PORT1	I/O	IN _{USB} , O _{USB}	AV _C -	
AG4	GPIO9	I/O (PU _{22.5})	IN _{TS} , O _{1/}	V _{IO}	PMR[18] = 0 and PMR[8] = 0
	DCD2#	I (PU _{22.5})	IN _{TS}		PMR[18] = 1 and PMR[8] = 0
	IDE_IOW1#	O (PU _{22.5})	O _{1/4}		PMR[18] = 0 and PMR[8] = 1
	SDTEST2	O (PU _{22.5})	O _{2/5}		PMR[18] = 1 and PMR[8] = 1
AG28	MA11	0	O _{2/5}	V _{IO}	
AG29 ³	MD9	I/O	IN _T , TS _{2/5}	V_{IO}	
AG30 ³	MD8	I/O	IN _T , TS _{2/5}	V_{IO}	
AG31 ³	MD13	I/O	IN _T , TS _{2/5}	V _{IO}	
AH1 ³	DPOS_PORT2	I/O	IN _{USB} , O _{USB}	AV _C -	
AH2 ³	DPOS_PORT1	I/O	IN _{USB} , O _{USB}	AV _C - CUSB	

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
AH3	GPIO6	I/O (PU _{22.5})	IN _{TS} , O _{1/}	V _{IO}	PMR[18] = 0 and PMR[8] = 0
	DTR2#/BOUT2	O (PU _{22.5})	O _{1/4}		PMR[18] = 1 and PMR[8] = 0
	IDE_IOR1#	O (PU _{22.5})	O _{1/4}		PMR[18] = 0 and PMR[8] = 1
	SDTEST5	O (PU _{22.5})	O _{2/5}		PMR[18] = 1 and PMR[8] = 1
AH4	GPIO7	I/O (PU _{22.5})	IN _{TS} , O _{1/}	V _{IO}	PMR[17] = 0 and PMR[8] = 0
	RTS2#	O (PU _{22.5})	O _{1/4}		PMR[17] = 1 and PMR[8] = 0
	IDE_DACK1#	O (PU _{22.5})	O _{1/4}		PMR[17] = 0 and PMR[8] = 1
	SDTEST0	O (PU _{22.5})	O _{2/5}		PMR[17] = 1 and PMR[8] = 1
AH5	TDP	I/O	Diode		
AH6	TDO	0	O _{PCI}	V _{IO}	
AH7	VPCKIN	I	IN _T	V_{IO}	
AH8	VPD4	I	IN _T	V_{IO}	
AH9	VPD0	I	IN_T	V_{IO}	
AH10	V _{SS}	GND			
AH11	V _{CORE}	PWR			
AH12	V _{SS}	GND		-	
AH13	V _{CORE}	PWR			
AH14	V _{SS}	GND			
AH15	V _{CORE}	PWR			
AH16	SDCLK1	0	O _{2/5}	V _{IO}	
AH17	V _{CORE}	PWR			
AH18	V _{SS}	GND			
AH19	V _{CORE}	PWR			
AH20	V _{SS}	GND			
AH21	V _{CORE}	PWR			
AH22	V _{SS}	GND			
AH23 ³	MD28	I/O	IN _T , TS _{2/5}	V _{IO}	
AH24 ³	MD55	I/O	IN _T , TS _{2/5}	V _{IO}	
AH25 ³	MD51	I/O	IN _T , TS _{2/5}	V _{IO}	
AH26 ³	MD48	I/O	IN _T , TS _{2/5}	V _{IO}	
AH27 ³	MD23	I/O	IN _T , TS _{2/5}	V _{IO}	
AH28	SDCLK_OUT	0	O _{2/5}	V _{IO}	
AH29	MA12	0	O _{2/5}	V _{IO}	
AH30 ³	MD11	1/0	IN _T , TS _{2/5}	V _{IO}	
AH31 ³	MD10	I/O	IN _T , TS _{2/5}	V _{IO}	
AH31° AJ1	GPIO10	I/O (PU _{22.5})	IN _{TS} , O _{8/8}	V _{IO}	PMR[18] = 0 and PMR[8] = 0
	DSR2#	I (PU _{22.5})	IN _{TS}		PMR[18] = 1 and PMR[8] = 0
	IDE_IORDY1	I (PU _{22.5})	IN _{TS1}		PMR[18] = 0 and PMR[8] = 1
	SDTEST1	O (PU _{22.5})	O _{2/5}		PMR[18] = 1 and PMR[8] = 1

Table 3-2. 432-EBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball		I/O (PU/	Buffer ¹	Power	Juli Assignin
No.	Signal Name	PD)	Type	Rail	Configuration
AJ2	GPIO8	I/O (PU _{22.5})	IN _{TS} , O _{8/8}	V_{IO}	PMR[17] = 0 and PMR[8] = 0
	CTS2#	I (PU _{22.5})	IN _{TS}		PMR[17] = 1 and PMR[8] = 0
	IDE_DREQ1	I (PU _{22.5})	IN _{TS1}		PMR[17] = 0 and PMR[8] = 1
	SDTEST4	O (PU _{22.5})	O _{2/5}		PMR[17] = 1 and PMR[8] = 1
AJ3	V _{IO}	PWR			
AJ4	SIN2	I	IN _{TS}	V _{IO}	PMR[28] = 0
	SDTEST3	0	O _{2/5}		PMR[28] = 1
AJ5	TMS	I (PU _{22.5})	IN _{PCI}	V _{IO}	
AJ6	VPD7	I	IN _T	V _{IO}	
AJ7	VPD6	I	IN _T	V _{IO}	
AJ8	VPD2	I	IN _T	V _{IO}	
AJ9	GPIO38/IRRX2	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	PMR[14] ⁵ = 0 and PMR[22] ⁵ = 0. The IRRX2 input is connected to the input path of GPIO38. There is no logic required to enable IRRX2, just a simple connec- tion. Hence, when GPIO38 is the selected function, IRRX2 is also selected.
	LPCPD#	0	O _{PCI}		$PMR[14]^5 = 1 \text{ and}$ $PMR[22]^5 = 1$
AJ10	GPIO35	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^5 = 0 \text{ and}$ $PMR[22]^5 = 0$
	LAD3	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		$PMR[14]^5 = 1 \text{ and}$ $PMR[22]^5 = 1$
AJ11	GPIO32	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^5 = 0 \text{ and}$ $PMR[22]^5 = 0$
	LAD0	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		$PMR[14]^5 = 1 \text{ and}$ $PMR[22]^5 = 1$
AJ12	GPIO12	I/O (PU _{22.5})	IN _{AB} , O _{8/8}	V _{IO}	PMR[19] = 0
	AB2C	I/O (PU _{22.5})	IN _{AB} , OD ₈		PMR[19] = 1
AJ13	AB1C	I/O (PU _{22.5})	IN _{AB} , OD ₈	V _{IO}	$PMR[23]^2 = 0$
	GPIO20	I/O (PU _{22.5})	IN _T , O _{3/5}		$PMR[23]^2 = 1 \text{ and } PMR[7] = 0$
	DOCCS#	0	O3/5		$PMR[23]^2 = 1 \text{ and } PMR[7] = 1$
AJ14	AC97_CLK	0	O _{2/5}	V _{IO}	PMR[25] = 1
AJ15	AC97_RST#	0	O _{2/5}	V _{IO}	FPCI_MON = 0
	F_STOP#	0	O _{2/5}		FPCI_MON = 1
AJ16	SDCLK3	0	O _{2/5}	V _{IO}	
_	MD56	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ17 ³	WIDOO				

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
AJ19 ³	MD61	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ20	DQM7	0	O _{2/5}	V _{IO}	
AJ21	DQM3	0	O _{2/5}	V _{IO}	
AJ22 ³	MD25	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ23 ³	MD29	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ24 ³	MD54	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ25 ³	MD50	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ26	DQM6	0	O _{2/5}	V _{IO}	
AJ27 ³	MD22	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ28 ³	MD19	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ29	V _{IO}	PWR			
AJ30	SDCLK_IN	I	IN _T	V _{IO}	
AJ31 ³	MD12	I/O	IN _T , TS _{2/5}	V _{IO}	
AK1	V _{IO}	PWR			
AK2	V _{SS}	GND			
AK3	SOUT2	0	O _{8/8}	V _{IO}	
	CLKSEL2	(PD ₁₀₀)	IN _{STRP}		Strap (See Table 3-6 on page 58.)
AK4	TRST#	I (PU _{22.5})	IN _{PCI}	V _{IO}	
AK5	TDI	I (PU _{22.5})	IN _{PCI}	V _{IO}	
AK6	V _{IO}	PWR			
AK7	V_{SS}	GND			
AK8	VPD1	I	IN _T	V_{IO}	
AK9	GPIO37	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^5 = 0$ and $PMR[22]^5 = 0$
	LFRAME#	0	O _{PCI}		$PMR[14]^5 = 1 \text{ and}$ $PMR[22]^5 = 1$
AK10	GPIO34	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^5 = 0 \text{ and}$ $PMR[22]^5 = 0$
	LAD2	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		$PMR[14]^5 = 1 \text{ and}$ $PMR[22]^5 = 1$
AK11	V _{IO}	PWR			
AK12	V _{SS}	GND			
AK13	SDATA_OUT	0	O _{AC97}	V _{IO}	
	TFT_PRSNT	I (PD ₁₀₀)	IN _{STRP}	V _{IO}	Strap (See Table 3-6 on page 58.)
AK14	SDATA_IN	1	IN_T	V_{IO}	FPCI_MON = 0
	F_GNT0#	0	O _{2/5}		FPCI_MON = 1
AK15	V_{SS}	GND			
AK16	V _{IO}	PWR			
AK17	V_{SS}	GND			
AK18 ³	MD59	I/O	IN _T , TS _{2/5}	V_{IO}	
AK19 ³	MD62	I/O	IN _T , TS _{2/5}	V _{IO}	
AK20	V _{IO}	PWR			
AK21	V _{SS}	GND			
AK22 ³	MD26	I/O	IN _T , TS _{2/5}	V _{IO}	

432-EBGA Ball Assignment - Sorted by Ball Number (Continued) Table 3-2.

Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
AK23 ³	MD30	I/O	IN _T , TS _{2/5}	V _{IO}	
AK24 ³	MD53	I/O	IN _T , TS _{2/5}	V _{IO}	
AK25	V _{IO}	PWR			
AK26	V _{SS}	GND			
AK27 ³	MD21	I/O	IN _T , TS _{2/5}	V _{IO}	
AK28 ³	MD18	I/O	IN _T , TS _{2/5}	V _{IO}	
AK29	CS1#	0	O _{2/5}	V _{IO}	
AK30	V _{SS}	GND			
AK31	V _{IO}	PWR			
AL1	V_{SS}	GND			
AL2	V _{IO}	PWR			
AL3	TDN	I/O	WIRE	V _{IO}	
AL4	тск	(PU _{22.5})	IN _{PCI}	V _{IO}	
AL5	GTEST	I (PD _{22.5})	IN _T	V _{IO}	
AL6	VPD5	1	IN_T	V_{IO}	
AL7	VPD3	- 1	IN_T	V_{IO}	
AL8	GPIO39	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^5 = 0 \text{ and}$ $PMR[22]^5 = 0$
	SERIRQ	I/O	IN _{PCI} , O _{PCI}		$PMR[14]^5 = 1 \text{ and}$ $PMR[22]^5 = 1$
AL9	GPIO36	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^5 = 0 \text{ and}$ $PMR[22]^5 = 0$
	LDRQ#	I	IN _{PCI}		$PMR[14]^5 = 1 \text{ and}$ $PMR[22]^5 = 1$
AL10	GPIO33	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^5 = 0$ and $PMR[22]^5 = 0$
	LAD1	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		$PMR[14]^5 = 1 \text{ and}$ $PMR[22]^5 = 1$
AL11	GPIO13	I/O (PU _{22.5})	IN _{AB} , O _{8/}	V _{IO}	PMR[19] = 0
	AB2D	I/O (PU _{22.5})	IN _{AB} , OD ₈	V _{IO}	PMR[19] = 1
AL12	AB1D	I/O (PU _{22.5})	IN _{AB} , OD ₈	V _{IO}	$PMR[23]^2 = 0$
	GPIO1	I/O (PU _{22.5})	IN _T , O _{3/5}		$PMR[23]^2 = 1$ and $PMR[13] = 0$
	IOCS1#	0	O _{3/5}		$PMR[23]^2 = 1 \text{ and } PMR[13] = 1$
AL13	SYNC	0	O _{AC97}	V_{IO}	
	CLKSEL3	(PD ₁₀₀)	IN _{STRP}		Strap (See Table 3-6 on page 58.)
AL14	BIT_CLK	I	IN _T	V_{IO}	FPCI_MON = 0
	F_TRDY#	0	O _{1/4}		FPCI_MON = 1
AL15	GPIO16	I/O (PU _{22.5})	IN _T , O _{2/5}	V _{IO}	PMR[0] = 0 and FPCI_MON = 0
	PC_BEEP	0	O _{2/5}		PMR[0] = 1 = 0 and FPCI_MON = 0
	F_DEVSEL#	0	O _{2/5}		FPCI_MON = 1

, ,					
Ball No.	Signal Name	I/O (PU/ PD)	Buffer ¹ Type	Power Rail	Configuration
AL16	GXCLK	0	O _{2/5}	V _{IO}	$PMR[23]^2 = 0$ and $PMR[29] = 0$
	FP_VDD_ON	0	O _{1/4}		$PMR[23]^2 = 1$
	TEST3	0	O _{2/5}		$PMR[23]^2 = 0$ and $PMR[29] = 1$ and
AL17 ³	MD57	I/O	IN _T , TS _{2/5}	V _{IO}	
AL18 ³	MD60	I/O	IN _T , TS _{2/5}	V _{IO}	
AL19 ³	MD63	I/O	IN _T , TS _{2/5}	V _{IO}	
AL20	SDCLK2	0	O _{2/5}	V _{IO}	
AL21 ³	MD24	I/O	IN _T , TS _{2/5}	V _{IO}	
AL22 ³	MD27	I/O	IN _T , TS _{2/5}	V _{IO}	
AL23 ³	MD31	I/O	IN _T , TS _{2/5}	V _{IO}	
AL24 ³	MD52	I/O	IN _T , TS _{2/5}	V _{IO}	
AL25 ³	MD49	I/O	IN _T , TS _{2/5}	V _{IO}	
AL26	DQM2	0	O _{2/5}	V _{IO}	
AL27 ³	MD20	I/O	IN _T , TS _{2/5}	V _{IO}	
AL28 ³	MD17	I/O	IN _T , TS _{2/5}	V _{IO}	
AL29 ³	MD16	I/O	IN _T , TS _{2/5}	V _{IO}	
AL30	V _{IO}	PWR			
AL31	V_{SS}	GND			

- For Buffer Type definitions, refer to Table 9-10 "Buffer Types" on page
- 375. The TFT_PRSNT strap determines the power-on reset (POR) state of 2.
- The TFT_PRSN1 strap determines the power consisting PMR[23]. Is back-drive protected (MD[63:0], DPOS_PORT1, DNEG_PORT1, DPOS_PORT2, DNEG_PORT2, DPOS_PORT3, DNEG_PORT3, ACK#, AFD#/DSTRB#, BUSY/WAIT#, ERR#, INIT#, PD[7:0], PE, SLCT, SLIN#/ASTRB#, STB#/WRITE#, ONCTL#, PWRCNT[2:1]). Is 5V tolerant (ACK#, AFD#/DSTRB#, BUSY/WAIT#, ERR#, INIT#, PD[7:0], PE, SLCT, SLIN#/ASTRB#, STB#/WRITE#, ONCTL#, PWRCNT[2:1]).
- PWRCNT[2:1]).
 The LPC_ROM strap determines the power-on reset (POR) state of PMR[14] and PMR[22].

Table 3-3. 432-EBGA Ball Assignment - Sorted Alphabetically by Signal Name

	+ 3-3. 432-EBG
Signal Name	Ball No.
A0	A17
A1	D16
A2	A18
A3	A15
A4	A16
A5	A14
A6	C15
A7	B14
A8	C14
A9	B13
A10	C13
A11	C12
A12	A12
A13	C11
A14	A11
A15	B10
A16	A7
A17	C7
A18	D7
A19	A6
A20	D6
A21	C6
A22	A5
A23	F4
AB1C	AJ13
AB1D	AL12
AB2C	AJ12
AB2D	AL11
AC97 CLK	AJ14
AC97 RST#	AJ15
ACK#	U3
AD0	A17
AD1	D16
AD2	A18
AD3	A15
AD4	A16
AD5	A14
AD6	C15
AD7	B14
AD8	C14
AD9	B13
AD10	C13
AD11	C12
AD12	A12
AD13	C11
AD14	A11
AD15	B10
AD16	A7
AD17	C7
	1

Signal Name	Ball No.
AD18	D7
AD19	A6
AD20	D6
AD21	C6
AD22	A5
AD23	F4
AD24	C5
AD25	D5
AD26	A4
AD27	B4
AD28	C4
AD29	A3
AD30	C2
AD31	B3
AFD#/DSTRB#	AB2
AV _{CCUSB}	AF4
AV _{SSPLL2}	R3
	E28
AV _{SSPLL3}	
AV _{SSUSB}	AG1
BA0	P30
BA1	P31
BHE#	B5
BIT_CLK	AL14
BOOT16	G4
BUSY/WAIT#	T1
C/BE0#	A13
C/BE1#	A10
C/BE2#	D8
C/BE3#	A8
CASA#	N30
CKEA	AC28
CLK27M	A23
CLK32	H29
CLKSEL0	F3
CLKSEL1	B27
CLKSEL2	AK3
CLKSEL3	AL13
CS0#	P29
CS1#	AK29
CTS2#	AJ2
D0	C5
D1	D5
D2	A4
D3	B4
D4	C4
D5	A3
D6	C2
D7	B3
D8	A13

Signal Name	Ball No.
D9	A10
D10	D8
D11	A8
D12	C10
D13	B8
D14	C8
D15	D9
DCD2#	AG4
DEVSEL#	B5
DID0	D4
DID1	D2
DNEG_PORT1	AG3
DNEG_PORT2	AG2
DNEG_PORT3	AF3
DOCCS#	H3, AJ13
DOCR#	F1
DOCW#	G3
DPOS_PORT1	AH2
DPOS_PORT2	AH1
DPOS_PORT3	AE4
DQM0	M31
DQM1	AF31
DQM2	AL26
DQM3	AJ21
DQM4	T28
DQM5	AC30
DQM6	AJ26
DQM7	AJ20
DSR2#	AJ1
DTR1#/BOUT1	A28
DTR2#/BOUT2	AH3
ERR#	AA3
F_AD0	AA1
F_AD1	Y1
F_AD2	W3
F_AD3	W2
F_AD4	V1
F_AD5	V2
F_AD6	V3
F_AD7	U1
F_C/BE0#	AA3
F_C/BE1#	T1
F_C/BE2#	T3
F_C/BE3#	T4
F_DEVSEL#	AL15
F_FRAME#	AB1
F_GNT0#	AK14
F_IRDY#	W1
F_STOP#	AJ15

Ball No.

Signal Name

Table 3-3. 432-EBGA Ball Assignment - Sorted Alphabetically by Signal Name (Continued)

Signal Name	Ball No.
F_TRDY#	AL14
FP_VDD_ON	B23, AL16
FPCI_MON	D3
FPCICLK	U3
FRAME#	E1
GNT0#	D4
GNT1#	D2
GPIO0	H1
GPIO1	H2, AL12
GPIO6	AH3
GPIO7	AH4
GPIO8	AJ2
GPIO9	AG4
GPIO10	AJ1
GPIO11	H30
GPIO12	AJ12
GPIO13	AL11
GPIO14	F1
GPIO15	G3
GPIO16	AL15
GPIO17	J4
GPIO18	A28
GPIO19	H4
GPIO20	H3, AJ13
GPIO32	AJ11
GPIO33	AL10
GPIO34	AK10
GPIO35	AJ10
GPIO36	AL9
GPIO37	AK9
GPIO38/IRRX2	AJ9
GPIO39	AL8
GPIO40	A21
GPIO41	C19
GPWIO0	E31
GPWIO1	G28
GPWIO2	G29
GTEST	AL5
GXCLK	AL16
HSYNC	J1
IDE ADDRO	A26
IDE_ADDR1	C26
IDE_ADDR1	C17
IDE CS0#	A27
IDE_CS0#	C16
IDE_CS1#	C16
IDE_DACK1#	AH4
IDE_DATA1	B24
IDE_DATA1	A24

Signal Name	Ball No.
IDE_DATA2	D23
IDE DATA3	C23
IDE DATA4	B23
IDE_DATA5	A23
IDE DATA6	C22
IDE DATA7	B22
IDE DATA8	A21
IDE DATA9	C20
IDE_DATA10	A20
IDE_DATA11	C19
IDE_DATA12	B19
IDE_DATA13	A19
IDE_DATA14	C18
IDE_DATA15	
	B18
IDE_DREQ0	C24
IDE_DREQ1	AJ2
IDE_IOR0#	C21
IDE_IOR1#	AH3
IDE_IORDY0	A25
IDE_IORDY1	AJ1
IDE_IOW0#	D24
IDE_IOW1#	AG4
IDE_RST#	A22
INIT#	Y3
INTA#	AE3
INTB#	AF1
INTC#	H4
INTD#	B22
INTR_O	AB2
IOCHRDY	H4
IOCS0#	J4
IOCS1#	H2, AL12
IOR#	F1
IOW#	G3
IRDY#	C8
IRQ14	D25
IRQ15	H30
IRQ9	C22
IRRX1	J28
IRTX	J3
LAD0	AJ11
LAD1	AL10
LAD2	AK10
LAD3	AJ10
LDRQ#	AL9
LED#	D31
LFRAME#	AK9
LOCK#	C9
LPC_ROM	E4
LI O_INOINI	∟4

Signal Name	Ball No.
LPCPD#	AJ9
MA0	R31
MA1	T31
MA2	T29
MA3	AE28
MA4	AE29
MA5	AE31
MA6	AD28
MA7	AD29
MA8	AD30
MA9	AD31
MA10	R29
MA11	AG28
MA12	AH29
MD0	J30
MD1	J31
MD2	K29
MD3	K30
MD4	K31
MD5	L29
MD6	L31
MD7	M29
MD8	AG30
MD9	AG29
MD10	AH31
MD10	AH30
MD12	AJ31
MD13	AG31
MD14	AF28
MD14 MD15	AF29
MD16	AL29
MD17	AL28
MD18	AK28
MD19	AJ28
MD20	AJ26 AL27
MD21	AK27
MD22	AJ27
MD23	AH27
MD24	AL21
MD25	AJ22
MD26	AK22
MD27	AL22
MD28	AH23
MD29	AJ23
MD30	AK23
MD31	AL23
MD32	U31
MD33	U29
MD34	V31

Table 3-3. 432-EBGA Ball Assignment - Sorted Alphabetically by Signal Name (Continued)

Signal Name	Ball No.
MD35	V30
MD36	V29
MD37	W31
	W30
MD38	
MD39	W29
MD40	AC31
MD41	AB29
MD42	AB30
MD43	AB31
MD44	AA29
MD45	AA31
MD46	Y29
MD47	Y31
MD48	AH26
MD49	AL25
MD50	AJ25
MD51	AH25
MD52	AL24
MD53	AK24
MD54	AJ24
MD55	AH24
MD56	AJ17
MD57	AL17
MD58	AJ18
MD59	AK18
MD60	AL18
MD61	AJ19
MD62	AK19
MD63	AL19
NC (Total of 13)	K1, M3, N2, P1,
INC (Total of 13)	P2, AB3, AC1,
	AC2, AD1, AD2,
	AD3, AD4, AE1
ONCTL#	E30
OVER_CUR#	C27
PAR	C10
PC_BEEP	AL15
PCICLK	E2
PCICLK0	D3
PCICLK1	E4
PCIRST#	D1
PD0	AA1
PD1	Y1
PD2	W3
PD3	W2
PD4	V/2
PD5	V2
PD6	V2 V3
PD7	V3 U1
FUI	UI

Signal Name	Ball No.
PE	Т3
PERR#	B9
PLL2B	D28
PLL5B	B29
PLL6B	C28
POR#	J29
POWER_EN	B28
PWRBTN#	E29
PWRCNT1	F31
PWRCNT2	G31
RASA#	N31
RD#	F3
REQ0#	C1
REQ1#	E3
RI2#	H30
ROMCS#	G4
RTS2#	AH4
SDATA IN	AK14
SDATA_IN2	H31
SDATA OUT	AK13
SDCLK_IN	AJ30
SDCLK_OUT	AH28
SDCLK0	AC29
SDCLK1	AH16
SDCLK2	AL20
SDCLK3	AJ16
SDTEST0	AH4
	+
SDTEST3	AJ1 AG4
SDTEST2	
SDTEST3	AJ4
SDTEST4	AJ2
SDTEST5	AH3
SERIRQ	AL8
SERR#	A9
SIN1	D26
SIN2	AJ4
SIN3	J28
SLCT	T4
SLIN#/ASTRB#	W1
SMI_O	Y3
SOUT1	B27
SOUT2	AK3
SOUT3	J3
STB#/WRITE#	AB1
STOP#	D9
SYNC	AL13
TCK	AL4

Signal Name	Ball No.
TDN	AL3
TDO	AH6
TDP	AH5
TEST0	D28
TEST1	C28
TEST2	B29
TEST3	AL16
TFT_PRSNT	AK13
TFTD0	C25, H3
TFTD1	D25, V3
TFTD10	C21, V1
TFTD11	A25, V2
TFTD12	C23, H2
TFTD13	B19, U1
TFTD14	D23, T3
TFTD15	A19, T4
TFTD16	A24, W1
TFTD17	C18, AB1
TFTD2	C26, AB2
TFTD3	A26, T1
TFTD4	C17, AA3
TFTD5	A27, Y3
TFTD6	B24, AA1
TFTD7	B18, Y1
TFTD8	C24, W3
TFTD9	D24, W2
TFTDCK	A22, J4
TFTDE	C16, U3
THRM#	F28
TMS	AJ5
TRDE#	H1
TRDY#	B8
TRST#	AK4
V _{BAT}	D30
V _{CORE} (Total of 26)	D11, D13, D15, D17, D19, D21, K3, L4, L28, N4, N28, R4, R28, T30, U4, U28, W4, W28, AA4, AA28, AH11, AH13, AH15, AH17, AH19, AH21

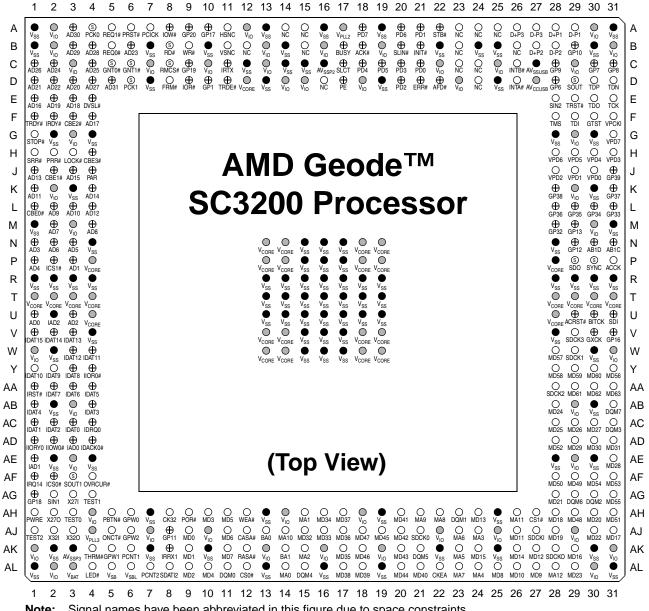
Signal Definitions Revision 5.1 AMD

Table 3-3. 432-EBGA Ball Assignment - Sorted Alphabetically by Signal Name (Continued)

Signal Name	Ball No.
V _{IO} (Total of 35)	A2, A30, B1, B6, B11, B16, B20, B25, B31, C3, C29, G2, G30, L3, M1, M2, M30, N1, T2, Y2, Y30, AC3, AE2, AE30, AJ3, AJ29, AK1, AK6, AK11, AK16, AK20, AK25, AK31, AL2, AL30
VPCKIN	AH7
VPD0	AH9
VPD1	AK8
VPD2	AJ8
VPD3	AL7
VPD4	AH8
VPD5	AL6
VPD6	AJ7
VPD7	AJ6
V _{PLL2}	R1

Signal Name	Ball No.
V _{PLL3}	C31
V _{SB}	F29
V _{SBL}	H28
V _{SS} (Total of 61)	A1, A31, B2, B7, B12, B15, B17, B21, B26, B30, D10, D12, D14, D18, D20, D22, F2, F30, K2, K4, K28, L1, L2, L30, M4, M28, N3, P3, P4, P28, R2, R30, U2, U30, V4, V28, Y4, Y28, AA30, AB4, AB28, AC4, AF2, AF30, AH10, AH12, AH14, AH18, AH20, AH22, AK2, AK17, AK12, AK15, AK17, AK21, AK26, AK30, AL1, AL31

Signal Name	Ball No.
VSYNC	J2
WEA#	N29
WR#	G1
X27I	A29
X27O	D27
X32I	C30
X32O	D29



Note: Signal names have been abbreviated in this figure due to space constraints.

- = GND Ball
- = PWR Ball
- Strap Option Ball
- ⊕ = Multiplexed Ball

Figure 3-3. 481-TEPBGA Ball Assignment Diagram

Table 3-4. 481-TEPBGA Ball Assignment - Sorted by Ball Number

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
A1	V _{SS}	GND			
A2	V _{IO}	PWR			
A3	AD30	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D6	I/O	IN _{PCI} , O _{PCI}		
A4	PCICLK0	0	O _{PCI}	V _{IO}	
	FPCI_MON	(PD ₁₀₀)	IN _{STRP}		Strap (See Table 3-6 on page 58.)
A5	REQ1#	I (PU _{22.5})	IN _{PCI}	V _{IO}	
A6	PCIRST#	0	O _{PCI}	V _{IO}	
A7	PCICLK	I	IN _T	V _{IO}	
A8	IOW#	0	O _{3/5}	V _{IO}	PMR[21] = 0 and PMR[2] = 0
	DOCW#	0	O _{3/5}		PMR[21] = 0 and PMR[2] = 1
	GPIO15	I/O (PU _{22.5})	IN _{TS} , O _{3/5}		PMR[21] = 1 and PMR[2] = 1
A9	GPIO20	I/O (PU _{22.5})	IN _T , O _{3/}	V _{IO}	$PMR[23]^3 = 0$ and $PMR[7] = 0$
	DOCCS#	O (PU _{22.5})	O _{3/5}		$PMR[23]^3 = 0 \text{ and } PMR[7] = 1$
	TFTD0	O (PU _{22.5})	O _{1/4}		PMR[23] ³ = 1
A10	GPIO17	I/O (PU _{22.5})	IN _{TS} , O _{3/5}	V _{IO}	$PMR[23]^3 = 0$ and $PMR[5] = 0$
	IOCS0#	O (PU _{22.5})	O _{3/5}		$PMR[23]^3 = 0 \text{ and } PMR[5] = 1$
	TFTDCK	O (PU _{22.5})	O _{1/4}		PMR[23] ³ = 1
A11	HSYNC	0	O _{1/4}	V _{IO}	
A12	V _{IO}	PWR			
A13	V _{SS}	GND			
A14	NC				
A15	NC				
A16	V _{SS}	GND			
A17	V _{PLL2}	PWR			
A18 ^{5, 2}	PD7	I/O	IN _T , O _{14/14}	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD13	0	O _{1/4}		PMR[23] ³ = 1 and (PMR[27] = 0 and FPCI_MON = 0)
	F_AD7	0	O _{14/14}		$PMR[23]^3 = 0 \text{ and}$ (PMR[27] = 1 or $FPCI_MON = 1)$
A19	V _{SS}	GND			

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
A20 ^{5, 2}	PD6	I/O	IN _T , O _{14/14}	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD1	0	O _{1/4}		$PMR[23]^3 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0$
	F_AD6	0	O _{14/14}		$PMR[23]^3 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
A21 ^{5, 2}	PD1	I/O	IN _T , O _{14/14}	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD7	0	O _{1/4}		$PMR[23]^3 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_AD1	0	O _{14/14}		$PMR[23]^3 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
A22 ^{5, 2}	STB#/WRITE#	0	O _{14/14}	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD17	0	O ^{1/4}		$PMR[23]^3 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_FRAME#	0	O _{14/14}		$PMR[23]^3 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
A23	NC				
A24	NC				
A25	NC				
A26 ⁵	DPOS_PORT3	I/O	$\begin{array}{c} \text{IN}_{\text{USB}}, \\ \text{O}_{\text{USB}} \end{array}$	AV _C - CUSB	
A27 ⁵	DNEG_PORT3	I/O	$\begin{array}{c} {\sf IN_{USB}}, \\ {\sf O_{USB}} \end{array}$	AV _C - CUSB	
A28 ⁵	DPOS_PORT1	I/O	$\begin{array}{c} {\sf IN_{USB}}, \\ {\sf O_{USB}} \end{array}$	AV _C - CUSB	
A29 ⁵	DNEG_PORT1	I/O	$\begin{array}{c} \text{IN}_{\text{USB}}, \\ \text{O}_{\text{USB}} \end{array}$	AV _C - CUSB	
A30	V _{IO}	PWR			
A31	V _{SS}	GND			
B1	V _{SS}	GND			
B2	V _{IO}	PWR			
В3	AD29	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D5	I/O	IN _{PCI} , O _{PCI}		
B4	AD28	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D4	I/O	IN _{PCI} , O _{PCI}		
B5	REQ0#	I (PU _{22.5})	INPCI	V _{IO}	

Table 3-4. 481-TEPBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
B6	AD23	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A23	0	O _{PCI}		
B7	V _{SS}	GND			
B8	RD#	0	O _{3/5}	V _{IO}	
	CLKSEL0	(PD ₁₀₀)	IN _{STRP}		Strap (See Table 3-6 on page 58.)
В9	WR#	0	O _{3/5}	V _{IO}	
B10	V _{SS}	GND			
B11	VSYNC	0	O _{1/4}	V _{IO}	
B12	NC				
B13	V _{IO}	PWR			
B14	V _{SS}	GND			
B15	NC				
B16	V _{IO}	PWR			
B17 ^{5, 2}	BUSY/WAIT#	I	IN _T	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD3	0	O _{1/4}		$PMR[23]^3 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_C/BE1#	0	O _{1/4}		PMR[23] ³ = 0 and (PMR[27] = 1 or FPCI_MON = 1)
B18 ^{5, 2}	ACK#	I	IN _T	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTDE	0	O _{1/4}		$PMR[23]^3 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	FPCICLK	0	O _{1/4}		$PMR[23]^3 = 0 \text{ and}$ (PMR[27] = 1 or $FPCI_MON = 1)$
B19	V _{IO}	PWR			
B20 ^{5,2}	SLIN#/ASTRB#	0	O _{14/14}	V _{IO}	$PMR[23]^3 = 0 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	TFTD16	0	O _{1/4}		$PMR[23]^3 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_IRDY#	0	O _{14/14}		$PMR[23]^3 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
B21 ^{5,2}	INIT#	0	O _{14/14}	V _{IO}	$PMR[23]^3 = 0 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	TFTD5	0	O _{1/4}		PMR[23] ³ = 1 and (PMR[27] = 0 and FPCI_MON = 0)
	SMI_O	0	O _{14/14}		PMR[23] ³ = 0 and (PMR[27] = 1 or FPCI_MON = 1)
B22	V _{SS}	GND			
B23	NC				
B24	V _{SS}	GND			

Ball		I/O	Buffer ¹	Power	
No.	Signal Name	(PU/PD)	Туре	Rail	Configuration
B25	V _{SS}	GND			
B26	NC				
B27 ⁵	DPOS_PORT2	I/O	IN _{USB} , O _{USB}	AV _C - CUSB	
B28 ⁵	DNEG_PORT2	I/O	IN _{USB} , O _{USB}	AV _C - CUSB	
B29	GPIO10	I/O (PU _{22.5})	IN _{TS} , O _{8/8}	V _{IO}	PMR[18] = 0 and PMR[8] = 0
	DSR2#	I (PU _{22.5})	IN _{TS}		PMR[18] = 1 and PMR[8] = 0
	IDE_IORDY1	I (PU _{22.5})	IN _{TS1}		PMR[18] = 0 and PMR[8] = 1
	SDTEST1	O (PU _{22.5})	O _{2/5}		PMR[18] = 1 and PMR[8] = 1
B30	V _{SS}	GND			
B31	V _{IO}	PWR			
C1	AD26	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D2	I/O	IN _{PCI} , O _{PCI}		
C2	AD24	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D0	I/O	IN _{PCI} , O _{PCI}		
C3	V _{IO}	PWR			
C4	AD25	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D1	I/O	IN _{PCI} , O _{PCI}		
C5	GNT0#	0	O _{PCI}	V _{IO}	
	DID0	I (PD ₁₀₀)	IN _{STRP}		Strap (See Table 3-6 on page 58.)
C6	GNT1#	0	O _{PCI}	V _{IO}	
	DID1	I (PD ₁₀₀)	IN _{STRP}		Strap (See Table 3- 6 on page 58.)
C7	V _{IO}	PWR			
C8	ROMCS#	0	O _{3/5}	V _{IO}	
	BOOT16	I (PD ₁₀₀)	IN _{STRP}	V _{IO}	Strap (See Table 3- 6 on page 58.)
C9	GPIO19	I/O (PU _{22.5})	IN _{TS} , O _{3/5}	V _{IO}	PMR[9] = 0 and PMR[4] = 0
	INTC#	I (PU _{22.5})	IN _{TS}		PMR[9] = 0 and PMR[4] = 1
	IOCHRDY	I (PU _{22.5})	IN _{TS1}		PMR[9] = 1 and PMR[4] = 1
C10	V _{IO}	PWR			
C11	IRTX	0	O _{8/8}	V _{IO}	PMR[6] = 0
	SOUT3	0	O _{8/8}		PMR[6] = 1
C12	V_{SS}	GND			
C13	V _{IO}	PWR			
C14	V _{SS}	GND			

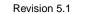




Table 3-4. 481-TEPBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
C15	V _{SS}	GND			
C16	AV _{SSPLL2}	GND			
C17 ^{5,2}	SLCT	I	IN _T	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD15	0	O _{1/4}		PMR[23] ³ = 1 and (PMR[27] = 0 and FPCI_MON = 0)
	F_C/BE3#	0	O _{1/4}		$PMR[23]^3 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
C18	PD4	I/O	IN _T , O _{14/14}	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD10	0	O _{1/4}		$PMR[23]^3 = 1$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	F_AD4	0	O _{14/14}		PMR[23] ³ = 0 and (PMR[27] = 1 or FPCI_MON = 1)
C19 ^{5,2}	PD5	I/O	IN _T , O _{14/14}	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD11	0	O _{1/4}		$PMR[23]^3 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_AD5	0	O _{14/14}		$PMR[23]^3 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
C20 ^{5,2}	PD3	I/O	IN _T , O _{14/14}	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD9	0	O _{1/4}		$PMR[23]^3 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_AD3	0	O _{14/14}		$PMR[23]^3 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
C21 ^{5,2}	PD0	I/O	IN _T , O _{14/14}	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD6	0	O _{1/4}		$PMR[23]^3 = 1$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	F_AD0	0	O _{14/14}		$PMR[23]^3 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
C22	V _{IO}	PWR			
C23	NC				
C24	NC				
C25	V _{IO}	PWR			
C26	INTB#	I (PU _{22.5})	IN _{PCI}	V _{IO}	
C27	AV _{SSUSB}	GND			

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
C28	GPIO9	I/O (PU _{22.5})	IN _{TS} , O _{1/4}	V _{IO}	PMR[18] = 0 and PMR[8] = 0
	DCD2#	(PU _{22.5})	IN _{TS}		PMR[18] = 1 and PMR[8] = 0
	IDE_IOW1#	O (PU _{22.5})	O _{1/4}		PMR[18] = 0 and PMR[8] = 1
	SDTEST2	O (PU _{22.5})	O _{2/5}		PMR[18] = 1 and PMR[8] = 1
C29	V _{IO}	PWR			
C30	GPIO7	I/O (PU _{22.5})	IN _{TS} , O _{1/4}	V _{IO}	PMR[17] = 0 and PMR[8] = 0
	RTS2#	O (PU _{22.5})	O _{1/4}		PMR[17] = 1 and PMR[8] = 0
	IDE_DACK1#	O (PU _{22.5})	O _{1/4}		PMR[17] = 0 and PMR[8] = 1
	SDTEST0	O (PU _{22.5})	O _{2/5}		PMR[17] = 1 and PMR[8] = 1
C31	GPIO8	I/O (PU _{22.5})	IN _{TS} , O _{8/8}	V _{IO}	PMR[17] = 0 and PMR[8] = 0
	CTS2#	(PU _{22.5})	IN _{TS}		PMR[17] = 1 and PMR[8] = 0
	IDE_DREQ1	I (PU _{22.5})	IN _{TS1}		PMR[17] = 0 and PMR[8] = 1
	SDTEST4	O (PU _{22.5})	O _{2/5}		PMR[17] = 1 and PMR[8] = 1
D1	AD21	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A21	0	O _{PCI}		
D2	AD22	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A22	0	O _{PCI}		
D3	AD20	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A20	0	O _{PCI}		
D4	AD27	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D3	I/O	IN _{PCI} , O _{PCI}		
D5	AD31	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D7	I/O	IN _{PCI} , O _{PCI}		
D6	PCICLK1	0	O _{PCI}	V _{IO}	
	LPC_ROM	I (PD ₁₀₀)	IN _{STRP}		Strap (See Table 3- 6 on page 58.)
D7	V _{SS}	GND			
D8	FRAME#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	
D9	IOR#	0	O _{3/5}	V _{IO}	PMR[21] = 0 and PMR[2] = 0
	DOCR#	0	O _{3/5}		PMR[21] = 0 and PMR[2] = 1
	GPIO14	I/O (PU _{22.5})	IN _{TS} , O _{3/5}		PMR[21] = 1 and PMR[2] = 1

Table 3-4. 481-TEPBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
D10	GPIO1	I/O (PU _{22.5})	IN _T , O _{3/}	V _{IO}	$PMR[23]^3 = 0$ and $PMR[13] = 0$
	IOCS1#	O (PU _{22.5})	O _{3/5}	V _{IO}	$PMR[23]^3 = 0$ and $PMR[13] = 1$
	TFTD12	O (PU _{22.5})	O _{1/4}	V _{IO}	PMR[23] ³ = 1
D11	TRDE#	0	O _{3/5}	V_{IO}	PMR[12] = 0
	GPIO0	I/O (PU _{22.5})	IN _{TS} , O _{3/5}	V _{IO}	PMR[12] = 1
D12	V _{CORE}	PWR			
D13	V _{SS}	GND			
D14	V _{IO}	PWR			
D15	V _{IO}	PWR			
D16	NC				
D17 ^{5, 2}	PE	I (PU _{22.5} PD _{22.5})	IN _T	V _{IO}	PMR[23] ³ = 0 and (PMR[27] = 0 and FPCI_MON = 0) (PU/PD under soft- ware control.)
	TFTD14	0	O _{1/4}		$PMR[23]^3 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_C/BE2#	0	O _{1/4}		$PMR[23]^3 = 0$ and $(PMR[27] = 1$ or $FPCI_MON = 1)$
D18	V _{IO}	PWR			
D19	V _{SS}	GND			
D20 ^{5, 2}	PD2	I/O	IN _T , O _{14/14}	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD8	0	O _{1/4}		$PMR[23]^3 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_AD2	0	O _{14/14}		PMR[23] ³ = 0 and (PMR[27] = 1 or FPCI_MON = 1)
D21 ^{5, 2}	ERR#	I	IN _T , O _{1/}	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD4	0	O _{1/4}		$PMR[23]^3 = 1 \text{ and}$ (PMR[27] = 0 and $FPCI_MON = 0)$
	F_C/BE0#	0	O _{1/4}		PMR[23] ³ = 0 and (PMR[27] = 1 or FPCI_MON = 1)
D22 ^{5, 2}	AFD#/DSTRB#	0	O _{14/14}	V _{IO}	$PMR[23]^3 = 0$ and $(PMR[27] = 0$ and $FPCI_MON = 0)$
	TFTD2	0	O _{1/4}		PMR[23] ³ = 1 and (PMR[27] = 0 and FPCI_MON = 0)
	INTR_O	0	O _{14/14}		PMR[23] ³ = 0 and (PMR[27] = 1 or FPCI_MON = 1)
D23	V _{IO}	PWR			
D24	NC				
D25	V_{SS}	GND			

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
D26	INTA#	I (PU _{22.5})	IN _{PCI}	V _{IO}	
D27	AV _{CCUSB}	PWR			
D28	GPIO6	I/O (PU _{22.5})	IN _{TS} , O _{1/4}	V _{IO}	PMR[18] = 0 and PMR[8] = 0
	DTR2#/BOUT2	O (PU _{22.5})	O _{1/4}		PMR[18] = 1 and PMR[8] = 0
	IDE_IOR1#	O (PU _{22.5})	O _{1/4}		PMR[18] = 0 and PMR[8] = 1
	SDTEST5	O (PU _{22.5})	O _{2/5}		PMR[18] = 1 and PMR[8] = 1
D29	SOUT2	0	O _{8/8}	V_{IO}	
	CLKSEL2	I (PD ₁₀₀)	IN _{STRP}		Strap (See Table 3- 6 on page 58.)
D30	TDP	I/O	Diode		
D31	TDN	I/O	WIRE	V _{IO}	
E1	AD16	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A16	0	O _{PCI}		
E2	AD19	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A19	0	O _{PCI}		
E3	AD18	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A18	0	O _{PCI}		
E4	DEVSEL#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	BHE#	0	O _{PCI}		
E28	SIN2	I	IN _{TS}	V _{IO}	PMR[28] = 0
	SDTEST3	0	O _{2/5}		PMR[28] = 1
E29	TRST#	I (PU _{22.5})	IN _{PCI}	V _{IO}	
E30	TDO	0	O _{PCI}	V_{IO}	
E31	TCK	I (PU _{22.5})	IN _{PCI}	V _{IO}	
F1	TRDY#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D13	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
F2	IRDY#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D14	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
F3	C/BE2#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D10	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
F4	AD17	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A17	0	O _{PCI}		
F28	TMS	I (PU _{22.5})	IN _{PCI}	V _{IO}	

Table 3-4. 481-TEPBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
F29	TDI	(PU _{22.5})	IN _{PCI}	V _{IO}	
F30	GTEST	I (PD _{22.5})	IN _T	V _{IO}	
F31	VPCKIN	1	IN_T	V _{IO}	
G1	STOP#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D15	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
G2	V _{SS}	GND			
G3	V _{IO}	PWR			
G4	V _{SS}	GND			
G28	V _{SS}	GND			
G29	V _{IO}	PWR			
G30	V _{SS}	GND			
G31	VPD7	I	IN _T	V _{IO}	
H1	SERR#	I/O (PU _{22.5})	IN _{PCI} , OD _{PCI}	V _{IO}	
H2	PERR#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	
НЗ	LOCK#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	
H4	C/BE3#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D11	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
H28	VPD6	I	IN _T	V _{IO}	
H29	VPD5	I	IN _T	V _{IO}	
H30	VPD4	I	IN _T	V _{IO}	
H31	VPD3	I	IN _T	V _{IO}	
J1	AD13	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A13	0	O _{PCI}		
J2	C/BE1#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D9	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
J3	AD15	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A15	0	O _{PCI}		
J4	PAR	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D12	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
J28	VPD2	1	IN _T	V _{IO}	
J29	VPD1	1	IN _T	V _{IO}	
J30	VPD0	I	IN _T	V _{IO}	

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
J31	GPIO39	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^4 = 0 \text{ and}$ $PMR[22]^4 = 0$
	SERIRQ	I/O	IN _{PCI} , O _{PCI}		$PMR[14]^4 = 1 \text{ and}$ $PMR[22]^4 = 1$
K1	AD11	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A11	0	O _{PCI}		
K2	V _{IO}	PWR			
K3	V _{SS}	GND			
K4	AD14	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A14	0	O _{PCI}		
K28	GPIO38/IRRX2	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	PMR[14] ⁴ = 0 and PMR[22] ⁴ = 0. The IRRX2 input is con- nected to the input path of GPIO38. There is no logic required to enable IRRX2, just a sim- ple connection. Hence, when GPIO38 is the selected function, IRRX2 is also selected.
	LPCPD#	0	O _{PCI}		$PMR[14]^4 = 1 \text{ and}$ $PMR[22]^4 = 1$
K29	V _{IO}	PWR			
K30	V _{SS}	GND			
K31	GPIO37	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^4 = 0 \text{ and}$ $PMR[22]^4 = 0$
	LFRAME#	0	O _{PCI}		$PMR[14]^4 = 1 \text{ and}$ $PMR[22]^4 = 1$
L1	C/BE0#	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	D8	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		
L2	AD9	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A9	0	O _{PCI}		
L3	AD10	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A10	0	O _{PCI}		
L4	AD12	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A12	0	O _{PCI}		
L28	GPIO36	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^4 = 0 \text{ and}$ $PMR[22]^4 = 0$
	LDRQ#	I	IN _{PCI}		$PMR[14]^4 = 1 \text{ and}$ $PMR[22]^4 = 1$

Table 3-4. 481-TEPBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
L29	GPIO35	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^4 = 0$ and $PMR[22]^4 = 0$
	LAD3	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		$PMR[14]^4 = 1 \text{ and}$ $PMR[22]^4 = 1$
L30	GPIO34	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^4 = 0$ and $PMR[22]^4 = 0$
	LAD2	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		$PMR[14]^4 = 1 \text{ and}$ $PMR[22]^4 = 1$
L31	GPIO33	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^4 = 0$ and $PMR[22]^4 = 0$
	LAD1	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		$PMR[14]^4 = 1 \text{ and}$ $PMR[22]^4 = 1$
M1	V_{SS}	GND			
M2	AD7	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A7	0	O _{PCI}		
МЗ	V _{IO}	PWR			
M4	AD8	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A8	0	O _{PCI}		
M28	GPIO32	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}	V _{IO}	$PMR[14]^4 = 0$ and $PMR[22]^4 = 0$
	LAD0	I/O (PU _{22.5})	IN _{PCI} , O _{PCI}		$PMR[14]^4 = 1 \text{ and}$ $PMR[22]^4 = 1$
M29	GPIO13	I/O (PU _{22.5})	IN _{AB} , O _{8/8}	V _{IO}	PMR[19] = 0
	AB2D	I/O (PU _{22.5})	IN _{AB} , OD ₈	V _{IO}	PMR[19] = 1
M30	V _{IO}	PWR			
M31	V_{SS}	GND			
N1	AD3	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	А3	0	O _{PCI}		
N2	AD6	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A6	0	OPCI		
N3	AD5	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A5	0	O _{PCI}		
N4	V _{SS}	GND			
N13	V _{CORE}	PWR			
N14	V _{CORE}	PWR			
N15	V _{SS}	GND			
N16	V _{SS}	GND			
N17	V _{SS}	GND			
N18	V _{CORE}	PWR			
N19	V _{CORE}	PWR			
N28	V _{SS}	GND			

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
N29	GPIO12	I/O (PU _{22.5})	IN _{AB} , O _{8/8}	V _{IO}	PMR[19] = 0
	AB2C	I/O (PU _{22.5})	IN _{AB} , OD ₈		PMR[19] = 1
N30	AB1D	I/O (PU _{22.5})	IN _{AB} , OD ₈	V _{IO}	$PMR[23]^3 = 0$
	GPIO1	I/O (PU _{22.5})	IN _T , O _{3/}		$PMR[23]^3 = 1 \text{ and } PMR[13] = 0$
	IOCS1#	0	O _{3/5}		PMR[23] ³ = 1 and PMR[13] = 1
N31	AB1C	I/O (PU _{22.5})	IN _{AB} , OD ₈	V _{IO}	$PMR[23]^3 = 0$
	GPIO20	I/O (PU _{22.5})	IN _T , O _{3/}		$PMR[23]^3 = 1 \text{ and } PMR[7] = 0$
	DOCCS#	0	O3/5		PMR[23] ³ = 1 and PMR[7] = 1
P1	AD4	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A4	0	O _{PCI}		
P2	IDE_CS1#	0	O _{1/4}	V_{IO}	PMR[24] = 0
	TFTDE	0	O _{1/4}		PMR[24] = 1
P3	AD1	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A1	0	O _{PCI}		
P4	V _{CORE}	PWR			
P13	V _{CORE}	PWR			
P14	V _{CORE}	PWR			
P15	V _{SS}	GND			
P16	V _{SS}	GND			
P17	V _{SS}	GND			
P18	V _{CORE}	PWR			
P19	V _{CORE}	PWR			
P28	V _{CORE}	PWR			
P29	SDATA_OUT	0	O _{AC97}	V _{IO}	
	TFT_PRSNT	(PD ₁₀₀)	IN _{STRP}	V _{IO}	Strap (See Table 3- 6 on page 58.)
P30	SYNC	0	O _{AC97}	V _{IO}	
	CLKSEL3	I (PD ₁₀₀)	IN _{STRP}		Strap (See Table 3- 6 on page 58.)
P31	AC97_CLK	0	O _{2/5}	V _{IO}	PMR[25] = 1
R1	V _{SS}	GND			
R2	V _{SS}	GND			
R3	V _{SS}	GND			
R4	V _{SS}	GND			
R13	V _{SS}	GND			
R14	V _{SS}	GND			
R15	V _{SS}	GND			
	V _{SS}	GND			
R16	. 22	_			



Table 3-4. 481-TEPBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
R18	V _{SS}	GND			
R19	V _{SS}	GND			
R28	V _{SS}	GND			
R29	V _{SS}	GND			
R30	V _{SS}	GND			
R31	V _{SS}	GND			
T1	V _{CORE}	PWR			
T2	V _{CORE}	PWR			
T3	V _{CORE}	PWR			
T4	V _{CORE}	PWR			
T13	V _{SS}	GND			
T14	V _{SS}	GND			
T15	V _{SS}	GND			
T16	V _{SS}	GND			
T17	V _{SS}	GND			
T18	V _{SS}	GND			
T19	V _{SS}	GND			
T28	V _{CORE}	PWR			
T29	V _{CORE}	PWR			
T30	V _{CORE}	PWR			
T31	V _{CORE}	PWR			
U1	AD0	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A0	0	O _{PCI}		
U2	IDE_ADDR2	0	O _{1/4}	V _{IO}	PMR[24] = 0
	TFTD4	0	O _{1/4}		PMR[24] = 1
U3	AD2	I/O	IN _{PCI} , O _{PCI}	V _{IO}	Cycle Multiplexed
	A2	0	O _{PCI}		
U4	V _{CORE}	PWR			
U13	V _{SS}	GND			
U14	V _{SS}	GND			
U15	V _{SS}	GND			
U16	V _{SS}	GND			
U17	V _{SS}	GND			
U18	V _{SS}	GND			
U19	V _{SS}	GND			
U28	V _{CORE}	PWR			
U29	AC97_RST#	0	O _{2/5}	V _{IO}	FPCI_MON = 0
	F_STOP#	0	O _{2/5}		FPCI_MON = 1
U30	BIT_CLK	ı	IN _T	V _{IO}	FPCI_MON = 0
	F_TRDY#	0	O _{1/4}		FPCI_MON = 1
U31	SDATA_IN	I	IN _T	V _{IO}	FPCI_MON = 0
	F_GNT0#	0	O _{2/5}		FPCI_MON = 1

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
V1	IDE_DATA15	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD7	0	O _{1/4}		PMR[24] = 1
V2	IDE_DATA14	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD17	0	O _{1/4}		PMR[24] = 1
V3	IDE_DATA13	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD15	0	O _{1/4}		PMR[24] = 1
V4	V _{SS}	GND			
V13	V _{CORE}	PWR			
V14	V _{CORE}	PWR			
V15	V _{SS}	GND			
V16	V _{SS}	GND			
V17	V _{SS}	GND			
V18	V _{CORE}	PWR			
V19	V _{CORE}	PWR			
V28	V _{SS}	GND			
V29	SDCLK3	0	O _{2/5}	V _{IO}	
V30	GXCLK	0	O _{2/5}	V _{IO}	$PMR[23]^3 = 0$ and $PMR[29] = 0$
	FP_VDD_ON	0	O _{1/4}		$PMR[23]^3 = 1$
	TEST3	0	O _{2/5}		PMR[23] ³ = 0 and PMR[29] = 1
V31	GPIO16	I/O (PU _{22.5})	IN _T , O _{2/}	V _{IO}	PMR[0] = 0 and FPCI_MON = 0
	PC_BEEP	0	O _{2/5}		PMR[0] = 1 = 0 and FPCI_MON = 0
	F_DEVSEL#	0	O _{2/5}		FPCI_MON = 1
W1	V _{IO}	PWR			
W2	V _{SS}	GND			
W3	IDE_DATA12	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD13	0	O _{1/4}		PMR[24] = 1
W4	IDE_DATA11	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	GPIO41	I/O	IN _{TS1} , O _{1/4}		PMR[24] = 1
W13	V _{CORE}	PWR			
W14	V _{CORE}	PWR			
W15	V _{SS}	GND			
W16	V _{SS}	GND			
W17	V _{SS}	GND			
W18	V _{CORE}	PWR			
W19	V _{CORE}	PWR			
W28 ⁵	MD57	I/O	IN _T , TS _{2/5}	V _{IO}	
W29	SDCLK1	0	O _{2/5}	V _{IO}	

Table 3-4. 481-TEPBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball		1/0	Buffer ¹	Power	A Ball Assign
No.	Signal Name	(PU/PD)		Rail	Configuration
W30	V _{SS}	GND			
W31	V _{IO}	PWR			
Y1	IDE_DATA10	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
Y2	IDE_DATA9	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
Y3	IDE_DATA8	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	GPIO40	I/O	IN _{TS1} , O _{1/4}		PMR[24] = 1
Y4	IDE_IOR0#	0	O _{1/4}	V _{IO}	PMR[24] = 0
	TFTD10	0	O _{1/4}		PMR[24] = 1
Y28 ⁵	MD58	I/O	IN _T , TS _{2/5}	V _{IO}	
Y29 ⁵	MD59	I/O	IN _T , TS _{2/5}	V _{IO}	
Y30 ⁵	MD60	I/O	IN _T , TS _{2/5}	V _{IO}	
Y31 ⁵	MD56	I/O	IN _T , TS _{2/5}	V _{IO}	
AA1	IDE_RST#	0	O _{1/4}	V _{IO}	PMR[24] = 0
	TFTDCK	0	O _{1/4}		PMR[24] = 1
AA2	IDE_DATA7	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	INTD#	I	IN _{TS}		PMR[24] = 1
AA3	IDE_DATA6	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	IRQ9	I	IN _{TS1}		PMR[24] = 1
AA4	IDE_DATA5	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	CLK27M	0	O _{1/4}		PMR[24] = 1
AA28	SDCLK2	0	O _{2/5}	V_{IO}	
AA29 ⁵	MD61	I/O	IN _T , TS _{2/5}	V _{IO}	
AA30 ⁵	MD62	I/O	IN _T , TS _{2/5}	V _{IO}	
AA31 ⁵	MD63	I/O	IN _T , TS _{2/5}	V _{IO}	
AB1	IDE_DATA4	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	FP_VDD_ON	0	O _{1/4}		PMR[24] = 1
AB2	V _{SS}	GND			
AB3	V _{IO}	PWR			
AB4	IDE_DATA3	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD12	0	O _{1/4}		PMR[24] = 1
AB28 ⁵	MD24	I/O	IN _T , TS _{2/5}	V _{IO}	
AB29	V _{IO}	PWR			
AB30	V_{SS}	GND			

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
AB31	DQM7	0	O _{2/5}	V _{IO}	
AC1	IDE_DATA1	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD16	0	O _{1/4}		PMR[24] = 1
AC2	IDE_DATA2	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD14	0	O _{1/4}		PMR[24] = 1
AC3	IDE_DATA0	I/O	IN _{TS1} , TS _{1/4}	V _{IO}	PMR[24] = 0
	TFTD6	0	O _{1/4}		PMR[24] = 1
AC4	IDE_DREQ0	I	IN _{TS1}	V_{IO}	PMR[24] = 0
	TFTD8	0	O _{1/4}		PMR[24] = 1
AC28 ⁵	MD25	I/O	IN _T , TS _{2/5}	V _{IO}	
AC29 ⁵	MD26	I/O	IN _T , TS _{2/5}	V _{IO}	
AC30 ⁵	MD27	I/O	IN _T , TS _{2/5}	V _{IO}	
AC31	DQM3	0	O _{2/5}	V _{IO}	
AD1	IDE_IORDY0	I	IN _{TS1}	V_{IO}	PMR[24] = 0
	TFTD11	0	O _{1/4}		PMR[24] = 1
AD2	IDE_IOW0#	0	O _{1/4}	V_{IO}	PMR[24] = 0
	TFTD9	0	O _{1/4}		PMR[24] = 1
AD3	IDE_ADDR0	0	O _{1/4}	V_{IO}	PMR[24] = 0
	TFTD3	0	O _{1/4}		PMR[24] = 1
AD4	IDE_DACK0#	0	O _{1/4}	V_{IO}	PMR[24] = 0
	TFTD0	0	O _{1/4}		PMR[24] = 1
AD28 ⁵	MD52	I/O	IN _T , TS _{2/5}	V _{IO}	
AD29 ⁵	MD29	I/O	IN _T , TS _{2/5}	V _{IO}	
AD30 ⁵	MD30	I/O	IN _T , TS _{2/5}	V _{IO}	
AD31 ⁵	MD31	I/O	IN _T , TS _{2/5}	V _{IO}	
AE1	IDE_ADDR1	0	O _{1/4}	V_{IO}	PMR[24] = 0
	TFTD2	0	O _{1/4}		PMR[24] = 1
AE2	V _{SS}	GND			
AE3	V _{IO}	PWR			
AE4	V _{SS}	GND			
AE28	V_{SS}	GND			
AE29	V _{IO}	PWR			
AE30	V _{SS}	GND			
AE31 ⁵	MD28	I/O	IN _T , TS _{2/5}	V _{IO}	
AF1	IRQ14	ı	IN _{TS1}	V _{IO}	PMR[24] = 0
	TFTD1	0	O _{1/4}		PMR[24] = 1



Table 3-4. 481-TEPBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
AF2	IDE_CS0#	0	O _{1/4}	V _{IO}	PMR[24] = 0
	TFTD5	0	O _{1/4}		PMR[24] = 1
AF3	SOUT1	0	O _{8/8}	V _{IO}	
	CLKSEL1	(PD ₁₀₀)	IN _{STRP}		Strap (See Table 3-6 on page 58.)
AF4	OVER_CUR#	I	IN_TS	V _{IO}	
AF28 ⁵	MD50	I/O	IN _T , TS _{2/5}	V _{IO}	
AF29 ⁵	MD49	I/O	IN _T , TS _{2/5}	V _{IO}	
AF30 ⁵	MD54	I/O	IN _T , TS _{2/5}	V _{IO}	
AF31 ⁵	MD53	I/O	IN _T , TS _{2/5}	V _{IO}	
AG1	GPIO18	I/O (PU _{22.5})	IN _{TS} , O _{8/8}	V _{IO}	PMR[16] = 0
	DTR1#/BOUT1	O (PU _{22.5})	O _{8/8}		PMR[16] =1
AG2	SIN1	I	IN _{TS}	V _{IO}	
AG3	X27I	I	WIRE	V _{IO}	
AG4	TEST1	0	O _{2/5}	V _{IO}	PMR[29] = 1
	PLL6B	I/O	IN _{TS} , TS _{2/5}		PMR[29] = 0
AG28 ⁵	MD21	I/O	IN _T , TS _{2/5}	V _{IO}	
AG29	DQM6	0	O _{2/5}	V _{IO}	
AG30	DQM2	0	O _{2/5}	V _{IO}	
AG31 ⁵	MD55	I/O	IN _T , TS _{2/5}	V _{IO}	
AH1	POWER_EN	0	O _{1/4}	V _{IO}	
AH2	X27O	0	WIRE	V _{IO}	
АН3	TEST0	0	O _{2/5}	V _{IO}	PMR[29] = 1
	PLL2B	I/O	IN _T , TS _{2/5}		PMR[29] = 0
AH4	V_{IO}	PWR			
AH5	PWRBTN#	I (PU ₁₀₀)	IN _{BTN}	V _{SB}	
AH6	GPWIO0	I/O (PU ₁₀₀)	IN _{TS} , TS _{2/14}	V _{SB}	
AH7	V _{SS}	GND			
AH8	CLK32	0	O _{2/5}	V _{SB}	
AH9	POR#	I	IN _{TS}	V _{IO}	
AH10 ⁵	MD3	I/O	IN _T , TS _{2/5}	V _{IO}	
AH11 ⁵	MD5	I/O	IN _T , TS _{2/5}	V _{IO}	
AH12	WEA#	0	O _{2/5}	V _{IO}	
AH13	V _{SS}	GND			
AH14	V _{IO}	PWR			

Ball		I/O	Buffer ¹	Power	
No.	Signal Name	(PU/PD)		Rail	Configuration
AH15	MA1	0	O _{2/5}	V _{IO}	
AH16 ⁵	MD34	I/O	IN _T , TS _{2/5}	V _{IO}	
AH17 ⁵	MD37	I/O	IN _T , TS _{2/5}	V _{IO}	
AH18	V _{IO}	PWR			
AH19	V_{SS}	GND			
AH20 ⁵	MD41	I/O	IN _T , TS _{2/5}	V _{IO}	
AH21	MA9	0	O _{2/5}	V_{IO}	
AH22	MA8	0	O _{2/5}	V _{IO}	
AH23	DQM1	0	O _{2/5}	V _{IO}	
AH24 ⁵	MD13	I/O	IN _T , TS _{2/5}	V _{IO}	
AH25	V _{SS}	GND			
AH26	MA11	0	O _{2/5}	V _{IO}	
AH27	CS1#	0	O _{2/5}	V _{IO}	
AH28 ⁵	MD18	I/O	IN _T , TS _{2/5}	V _{IO}	
AH29 ⁵	MD48	I/O	IN _T , TS _{2/5}	V _{IO}	
AH30 ⁵	MD20	I/O	IN _T , TS _{2/5}	V _{IO}	
AH31 ⁵	MD51	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ1	TEST2	0	O _{2/5}	V _{IO}	PMR[29] = 1
	PLL5B	I/O	IN _T , TS _{2/5}		PMR[29] = 0
AJ2	X32I	I	WIRE	V_{BAT}	
AJ3	X32O	0	WIRE	V_{BAT}	
AJ4	V _{PLL3}	PWR			
AJ5 ^{5, 2}	ONCTL#	0	OD ₁₄	V_{SB}	
AJ6	GPWIO2	I/O (PU ₁₀₀)	IN _{TS} , TS _{2/14}	V _{SB}	
AJ7	V _{IO}	PWR			
AJ8	GPIO11	I/O (PU _{22.5})	IN _{TS} , O _{8/8}	V _{IO}	PMR[18] = 0 and PMR[8] = 0
	RI2#	I (PU _{22.5})	IN _{TS}		PMR[18] = 1 and PMR[8] = 0
	IRQ15	I (PU _{22.5})	IN _{TS1}		PMR[18] = 0 and PMR[8] = 1
AJ9 ⁵	MD0	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ10	V _{IO}	PWR			
AJ11 ⁵	MD6	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ12	CASA#	0	O _{2/5}	V _{IO}	
AJ13	BA0	0	O _{2/5}	V _{IO}	
AJ14	MA10	0	O _{2/5}	V _{IO}	

Table 3-4. 481-TEPBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
AJ15 ⁵	MD32	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ16 ⁵	MD33	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ17 ⁵	MD36	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ18 ⁵	MD47	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ19 ⁵	MD45	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ20 ⁵	MD42	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ21	SDCLK0	0	O _{2/5}	V _{IO}	
AJ22	V _{IO}	PWR			
AJ23	MA6	0	O _{2/5}	V _{IO}	
AJ24	MA3	0	O _{2/5}	V _{IO}	
AJ25	V _{IO}	PWR			
AJ26 ⁵	MD11	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ27	SDCLK_IN	I	IN _T	V _{IO}	
AJ28 ⁵	MD19	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ29	V _{IO}	PWR			
AJ30 ⁵	MD22	I/O	IN _T , TS _{2/5}	V _{IO}	
AJ31 ⁵	MD17	I/O	IN _T , TS _{2/5}	V _{IO}	
AK1	V _{IO}	PWR			
AK2	V _{SS}	GND			
AK3	AV _{SSPLL3}	GND			
AK4	THRM#	I	IN _{TS}	V_{SB}	
AK5	GPWIO1	I/O (PU ₁₀₀)	IN _{Ts} , TS _{2/14}	V _{SB}	
AK6 ^{5, 2}	PWRCNT1	0	OD ₁₄	V_{SB}	
AK7	V _{SS}	GND			
AK8	IRRX1	I	IN _{TS}	V_{SB}	PMR[6] = 0
	SIN3	I	IN _{TS}	V _{IO}	PMR[6] =1
AK9 ⁵	MD1	I/O	IN _T , TS _{2/5}	V _{IO}	
AK10	V _{SS}	GND			
AK11 ⁵	MD7	I/O	IN _T , TS _{2/5}	V _{IO}	
AK12	RASA#	0	O _{2/5}	V _{IO}	
AK13	V _{IO}	PWR			
AK14	BA1	0	O _{2/5}	V _{IO}	
AK15	MA2	0	O _{2/5}	V _{IO}	
AK16	V _{IO}	PWR			

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
AK17 ⁵	MD35	I/O	IN _T , TS _{2/5}	V _{IO}	
AK18 ⁵	MD46	I/O	IN _T , TS _{2/5}	V _{IO}	
AK19	V _{IO}	PWR			
AK20 ⁵	MD43	I/O	IN _T , TS _{2/5}	V _{IO}	
AK21	DQM5	0	O _{2/5}	V _{IO}	
AK22	V _{SS}	GND			
AK23	MA5	0	O _{2/5}	V _{IO}	
AK24 ⁵	MD15	I/O	IN _T , TS _{2/5}	V _{IO}	
AK25	V _{SS}	GND			
AK26 ⁵	MD14	I/O	IN _T , TS _{2/5}	V _{IO}	
AK27 ⁵	MD12	I/O	IN _T , TS _{2/5}	V _{IO}	
AK28	SDCLK_OUT	0	O _{2/5}	V _{IO}	
AK29 ⁵	MD16	I/O	IN _T , TS _{2/5}	V _{IO}	
AK30	V _{SS}	GND			
AK31	V _{IO}	PWR			
AL1	V _{SS}	GND			
AL2	V _{IO}	PWR			
AL3	V_{BAT}	PWR			
AL4	LED#	0	OD ₁₄	V_{SB}	
AL5	V _{SB}	PWR			
AL6	V_{SBL}	PWR			
AL7 ^{5, 2}	PWRCNT2	0	OD ¹⁴	V_{SB}	
AL8	SDATA_IN2	I	IN _{TS}	V _{SB}	F3BAR0+Memory Offset 08h[21] = 1
AL9 ⁵	MD2	I/O	IN _T , TS _{2/5}	V _{IO}	
AL10 ⁵	MD4	I/O	IN _T , TS _{2/5}	V _{IO}	
AL11	DQM0	0	O _{2/5}	V_{IO}	
AL12	CS0#	0	O _{2/5}	V_{IO}	
AL13	V_{SS}	GND			
AL14	MA0	0	O _{2/5}	V _{IO}	
AL15	DQM4	0	O _{2/5}	V _{IO}	
AL16	V _{SS}	GND			
AL17 ⁵	MD38	I/O	IN _T , TS _{2/5}	V _{IO}	
AL18 ⁵	MD39	I/O	IN _T , TS _{2/5}	V _{IO}	
AL19	V _{SS}	GND			
AL20 ⁵	MD44	I/O	IN _T , TS _{2/5}	V _{IO}	

Signal Definitions Revision 5.1

Table 3-4. 481-TEPBGA Ball Assignment - Sorted by Ball Number (Continued)

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
AL21 ⁵	MD40	I/O	IN _T , TS _{2/5}	V _{IO}	
AL22	CKEA	0	O _{2/5}	V _{IO}	
AL23	MA7	0	O _{2/5}	V _{IO}	
AL24	MA4	0	O _{2/5}	V _{IO}	
AL25 ⁵	MD8	I/O	IN _T , TS _{2/5}	V _{IO}	
AL26 ⁵	MD10	I/O	IN _T , TS _{2/5}	V _{IO}	
AL27 ⁵	MD9	I/O	IN _T , TS _{2/5}	V _{IO}	
AL28	MA12	0	O _{2/5}	V _{IO}	

Ball No.	Signal Name	I/O (PU/PD)	Buffer ¹ Type	Power Rail	Configuration
AL29 ⁵	MD23	I/O	IN _T , TS _{2/5}	V _{IO}	
AL30	V _{IO}	PWR			
AL31	V _{SS}	GND			

- For Buffer Type definitions, refer to Table 9-10 "Buffer Types" on page 1. 375.
- Is 5V tolerant (ACK#, AFD#/DSTRB#, BUSY/WAIT#, ERR#, INIT#, PD[7:0], PE, SLCT, SLIN#/ASTRB#, STB#/WRITE#, ONCTL#, PWRCNT[2:1]). 2.
- The TFT_PRSNT strap determines the power-on reset (POR) state of 3.
- PMR[23].
 The LPC_ROM strap determines the power-on reset (POR) state of PMR[14] and PMR[22].
- Is back-drive protected (MD[63:0], DPOS_PORT1, DNEG_PORT1, DPOS_PORT2, DNEG_PORT2, DPOS_PORT3, DNEG_PORT3, ACK#, AFD#/DSTRB#, BUSY/WAIT#, ERR#, INIT#, PD[7:0], PE, SLCT, SLIN#/ASTRB#, STB#/WRITE#, ONCTL#, PWRCNT[2:1]).

Table 3-5. 481-TEPBGA Ball Assignment - Sorted Alphabetically by Signal Name

	; 3-3. 401-1EFD
Signal Name	Ball No.
A0	U1
A1	P3
A2	U3
A3	N1
A4	P1
A5	N3
A6	N2
A7	M2
A8	M4
A9	L2
A10	L3
A11	K1
A12	L4
A13	J1
A14	K4
A15	J3
A16	E1
A17	F4
A18	E3
A19	E2
A20	D3
A21	D1
A22	D2
A23	B6
AB1C	N31
AB1D	N30
AB2C	N29
AB2D	M29
AC97_CLK	P31
AC97_RST#	U29
ACK#	B18
AD0	U1
AD1	P3
AD2	U3
AD3	N1
AD4	P1
AD5	N3
AD6	N2
AD7	M2
AD8	M4
AD9	L2
AD10	L3
AD11	K1
AD12	L4
AD13	J1
AD14	K4
AD15	J3
AD16	E1
AD17	F4
L	1

Signal Name	Ball No.
AD18	E3
AD19	E2
AD20	D3
AD21	D1
AD22	D2
AD23	B6
AD24	C2
AD25	C4
AD26	C1
AD27	D4
AD28	B4
AD29	В3
AD30	A3
AD31	D5
AFD#/DSTRB#	D22
AV _{CCUSB}	D27
AV _{SSPLL2}	C16
AV _{SSPLL3}	AK3
AV _{SSUSB}	C27
BA0	AJ13
BA1	AK14
BHE#	E4
BIT_CLK	U30
BOOT16	C8
BUSY/WAIT#	B17
C/BE0#	L1
C/BE1#	J2
C/BE2#	F3
C/BE3#	H4
CASA#	AJ12
CKEA	AL22
CLK27M	AA4
CLK32	AH8
CLKSEL0	B8
CLKSEL1	AF3
CLKSEL2	D29
CLKSEL3	P30
CS0#	AL12
CS1#	AH27
CTS2#	C31
D0	C2
D1	C4
D2	C1
D3	D4
D4	B4
D5	B3
D6	A3
D7	D5
יטן	טט

Signal Name	Ball No.
D8	L1
D9	J2
D10	F3
D11	H4
D12	J4
D13	F1
D14	F2
D15	G1
DCD2#	C28
DEVSEL#	E4
DID0	C5
DID1	C6
DNEG_PORT1	A29
DNEG_PORT2	B28
DNEG_PORT3	A27
DOCCS#	A9, N31
DOCR#	D9
DOCW#	A8
DPOS_PORT1	A28
DPOS_PORT2	B27
DPOS_PORT3	A26
DQM0	AL11
DQM1	AH23
DQM2	AG30
DQM3	AC31
DQM4	AL15
DQM5	AK21
DQM6	AG29
DQM7	AB31
DSR2#	B29
DTR1#/BOUT1	AG1
DTR2#/BOUT2	D28
ERR#	D21
F_AD0	C21
F_AD1	A21
F_AD2	D20
F_AD3	C20
F_AD4	C18
F_AD5	C19
F_AD6	A20
F_AD7	A18
F_C/BE0#	D21
F_C/BE1#	B17
F_C/BE2#	D17
F_C/BE3#	C17
F_DEVSEL#	V31
F_FRAME#	A22
F_GNT0#	U31
F_IRDY#	B20

Table 3-5.	481-TEPBGA Ba	all A	ssignment - Sort	ed Alphabetica	lly l	oy Signal Name (Continued)
gnal Name	Ball No.		Signal Name	Ball No.		Signal Name	Ball No.

Signal Name	Ball No.
F_STOP#	U29
F_TRDY#	U30
FP_VDD_ON	V30, AB1
FPCI_MON	A4
FPCICLK	B18
FRAME#	D8
GNT0#	C5
GNT1#	C6
GPIO0	D11
GPIO1	D10, N30
GPIO6	D28
GPIO7	C30
GPIO8	C31
GPIO9	C28
GPIO10	B29
GPIO11	AJ8
GPIO12	N29
GPIO13	M29
GPIO14	D9
GPIO15	A8
GPIO16	V31
GPIO17	A10
GPIO18	AG1
GPIO19	C9
GPIO20	A9, N31
GPIO32	M28
GPIO33	L31
GPIO34	L30
GPIO35	L29
GPIO36	L28
GPIO37	K31
GPIO38/IRRX2	K28
GPIO39	J31
GPIO40	Y3
GPIO41	W4
GPWIO0	AH6
GPWIO1	AK5
GPWIO2	AJ6
GTEST	F30
GXCLK	V30
HSYNC	A11
IDE_ADDR0	AD3
IDE_ADDR1	AE1
IDE_ADDR2	U2
IDE_CS0#	AF2
IDE_CS1#	P2
IDE_DACK0#	AD4
IDE DACK1#	C30
IDE DATA0	AC3

Signal Name	Ball No.
IDE_DATA1	AC1
IDE DATA2	AC2
IDE DATA3	AB4
IDE DATA4	AB1
IDE DATA5	AA4
IDE_DATA6	AA3
IDE_DATA7	AA2
IDE DATA8	Y3
IDE DATA9	Y2
IDE DATA10	Y1
IDE_DATA11	W4
IDE_DATA12	W3
IDE_DATA13	V3
	V2
IDE_DATA16	
IDE_DATA15	V1
IDE_DREQ0	AC4
IDE_DREQ1	C31
IDE_IOR0#	Y4
IDE_IOR1#	D28
IDE_IORDY0	AD1
IDE_IORDY1	B29
IDE_IOW0#	AD2
IDE_IOW1#	C28
IDE_RST#	AA1
INIT#	B21
INTA#	D26
INTB#	C26
INTC#	C9
INTD#	AA2
INTR_O	D22
IOCHRDY	C9
IOCS0#	A10
IOCS1#	D10
IOCS1#	N30
IOR#	D9
IOW#	A8
IRDY#	F2
IRQ9	AA3
IRQ14	AF1
IRQ15	AJ8
IRRX1	AK8
IRTX	C11
LAD0	M28
LAD1	L31
LAD2	L30
LAD3	L29
LDRQ#	L28
LED#	AL4
LFRAME#	K31
LI IV WILT	101

Signal Name	Ball No.
LOCK#	H3
LPC_ROM	D6
LPCPD#	K28
MA0	AL14
MA1	AH15
MA2	AK15
MA3	AJ24
MA4	AL24
MA5	AK23
MA6	AJ23
MA7	AL23
MA8	AH22
MA9	AH21
MA10	AJ14
MA11	AH26
MA12	AL28
MD0	AJ9
MD1	AK9
MD2	AL9
MD3	AH10
MD4	AL10
MD5	AH11
MD6	AJ11
MD7	AK11
MD8	AL25
MD9	AL27
MD10	AL26
MD11	AJ26
MD12	AK27
MD13	AH24
MD14	AK26
MD15	AK24
MD16	AK29
MD17	AJ31
MD18	AH28
MD19	AJ28
MD20	AH30
MD21	AG28
MD22	AJ30
MD23	AL29
MD24	AB28
MD25	AC28
MD26	AC29
MD27	AC30
MD28	AE31
MD29	AD29
MD30	AD30
MD31	AD31
MD32	AJ15
111202	7.010

Table 3-5. 481-TEPBGA Ball Assignment - Sorted Alphabetically by Signal Name (Continued)

Signal Name Ball No. MD33 AJ16 MD34 AH16 MD35 AK17 MD36 AJ17 MD37 AH17 MD38 AL17 MD39 AL18 MD40 AL21 MD41 AH20 MD42 AJ20 MD43 AK20 MD44 AL20 MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD34 AH16 MD35 AK17 MD36 AJ17 MD37 AH17 MD38 AL17 MD39 AL18 MD40 AL21 MD41 AH20 MD42 AJ20 MD43 AK20 MD44 AL20 MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD50 AF28
MD35 AK17 MD36 AJ17 MD37 AH17 MD38 AL17 MD39 AL18 MD40 AL21 MD41 AH20 MD42 AJ20 MD43 AK20 MD44 AL20 MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD36 AJ17 MD37 AH17 MD38 AL17 MD39 AL18 MD40 AL21 MD41 AH20 MD42 AJ20 MD43 AK20 MD44 AL20 MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD37 AH17 MD38 AL17 MD39 AL18 MD40 AL21 MD41 AH20 MD42 AJ20 MD43 AK20 MD44 AL20 MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD38 AL17 MD39 AL18 MD40 AL21 MD41 AH20 MD42 AJ20 MD43 AK20 MD44 AL20 MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD39 AL18 MD40 AL21 MD41 AH20 MD42 AJ20 MD43 AK20 MD44 AL20 MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD40 AL21 MD41 AH20 MD42 AJ20 MD43 AK20 MD44 AL20 MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD41 AH20 MD42 AJ20 MD43 AK20 MD44 AL20 MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD42 AJ20 MD43 AK20 MD44 AL20 MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD43 AK20 MD44 AL20 MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD44 AL20 MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD45 AJ19 MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD46 AK18 MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD47 AJ18 MD48 AH29 MD49 AF29 MD50 AF28
MD48 AH29 MD49 AF29 MD50 AF28
MD49 AF29 MD50 AF28
MD50 AF28
MD51 AH31
MD52 AD28
MD53 AF31
MD54 AF30
MD55 AG31
MD56 Y31
MD57 W28
MD58 Y28
MD59 Y29
MD60 Y30
MD61 AA29
MD62 AA30
MD63 AA31
NC (Total of 13) A14, A15, A23, A24, A25, B12, B15, B23, B26, C23, C24, D16, D24
ONCTL# AJ5
OVER_CUR# AF4
PAR J4
PC_BEEP V31
PCICLK A7
PCICLK0 A4
PCICLK1 D6
PCIRST# A6
PD0 C21
PD1 A21
PD2 D20
PD3 C20

Signal Name	Ball No.
PD4	C18
PD5	C19
PD6	A20
PD7	A18
PE	D17
PERR#	H2
PLL2B	AH3
PLL5B	AJ1
PLL6B	AG4
POR#	AH9
POWER_EN	AH1
PWRBTN#	AH5
PWRCNT1	AK6
PWRCNT2	AL7
RASA#	AK12
RD#	B8
REQ0#	B5
REQ1#	A5
RI2#	AJ8
ROMCS#	C8
RTS2#	C30
SDATA_IN	U31
SDATA_IN2	AL8
SDATA OUT	P29
SDCLK IN	AJ27
SDCLK OUT	AK28
SDCLK0	AJ21
SDCLK1	W29
SDCLK2	AA28
SDCLK3	V29
SDTEST0	C30
SDTEST1	B29
SDTEST2	C28
SDTEST3	E28
SDTEST4	C31
SDTEST5	D28
SERIRQ	J31
SERR#	H1
SIN1	AG2
SIN2	E28
SIN3	AK8
SLCT	C17
SLIN#/ASTRB#	B20
SMI O	B21
SOUT1	AF3
SOUT2	D29
SOUT3	C11
230.0	011

Signal Name	Ball No.
STB#/WRITE#	A22
STOP#	G1
SYNC	P30
TCK	E31
TDI	F29
TDN	D31
TDO	E30
TDP	D30
TEST0	AH3
TEST1	AG4
TEST2	AJ1
TEST3	V30
TFT_PRSNT	P29
TFTD0	A9, AD4
TFTD1	A20, AF1
TFTD2	D22, AE1
TFTD3	B17, AD3
TFTD4	D21, U2
TFTD5	B21, AF2
TFTD6	C21, AC3
TFTD7	A21, V1
TFTD8	D20, AC4
TFTD9	C20, AD2
TFTD10	C18, Y4
TFTD11	C19, AD1
TFTD12	D10, AB4
TFTD13	A18, W3
TFTD14	D17, AC2
TFTD15	C17, V3
TFTD16	B20, AC1
TFTD17	A22, V2
TFTDCK	A10, AA1
TFTDE	B18, P2
THRM#	AK4
TMS	F28
TRDE#	D11
TRDY#	F1
TRST#	E29
V _{BAT}	AL3
V _{CORE} (Total of 29)	D12, N13, N14, N18, N19, P4, P13, P14, P18, P19, P28, T1, T2, T3, T4, T28, T29, T30, T31, U4, U28, V13, V14, V18, V19, W13,
	W14, W18, W19

Signal Definitions Revision 5.1 AMD

Table 3-5. 481-TEPBGA Ball Assignment - Sorted Alphabetically by Signal Name (Continued)

Signal Name	Ball No.
V _{IO} (Total of 46)	A2, A12, A30, B2, B13, B16, B19, B31, C3, C7, C10, C13, C22, C25, C29, D14, D15, D18, D23, G3, G29, K2, K29, M3, M30, W1, W31, AB3, AB29, AE3, AE29, AH4, AH14, AH18, AJ7, AJ10, AJ22, AJ25, AJ29, AK1, AK13, AK16, AK19, AK31, AL2, AL30
VPCKIN	F31
VPD0	J30
VPD1	J29
VPD2	J28
VPD3	H31
VPD4	H30
VPD5	H29
VPD6	H28
VPD7	G31
V _{PLL2}	A17
V _{PLL3}	AJ4
V_{SB}	AL5
V _{SBL}	AL6

Signal Name	Ball No.
V _{SS} (Total of 96)	A1, A13, A16, A19, A31, B1, B7, B10, B14, B22, B24, B25, B30, C12, C14, C15, D7, D13, D19, D25, G2, G4, G28, G30, K3, K30, M1, M31, N4, N15, N16, N17, N28, P15, P16, P17, R1, R2, R3, R4, R13, R14, R15, R16, R17, R18, R19, R28, R29, R30, R31, T13, T14, T15, T16, T17, T18, T19, U13, U14, U15, U16, U17, U18, U19, V4, V15, V16, V17, V28, W2, W15, W16, W17, W30, AB2, AB30, AE2, AE4, AE28, AE30, AH7, AH13, AH19, AH25, AK2, AK7, AK10, AK22, AK25, AK30, AL1, AL13, AL16, AL19, AL31
VSYNC	B11

	-
Signal Name	Ball No.
WEA#	AH12
WR#	B9
X27I	AG3
X27O	AH2
X32I	AJ2
X32O	AJ3

3.2 Strap Options

Several balls are read at power-up that set up the state of the SC3200. These balls are typically multiplexed with other functions that are outputs after the power-up sequence is complete. The SC3200 must read the state of the balls at power-up and the internal PU or PD resistors do not guarantee the correct state will be read. Therefore, it is required that an external PU or PD resistor with a value

of 1.5 $K\Omega$ be placed on the balls listed in Table 3-6. The value of the resistor is important to ensure that the proper state is read during the power-up sequence. If the ball is not read correctly at power-up, the SC3200 may default to a state that causes it to function improperly, possibly resulting in application failure.

Table 3-6. Strap Options

		Bal	ll No.	Nominal	External PU/PD	Strap Settings	
Strap Option	Muxed With	EBGA	TEPBGA	Internal PU or PD	Strap = 0 (PD)	Strap = 1 (PU)	Register References
CLKSEL0	RD#	F3	B8	PD ₁₀₀	See Table 4-7 or		GCB+I/O Offset 1Eh[9:8] (aka
CLKSEL1	SOUT1	B27	AF3	PD ₁₀₀	CLKSEL strap o	ptions.	CCFC register bits [9:8]) (RO): Value programmed at reset by
CLKSEL2	SOUT2	AK3	D29	PD ₁₀₀			CLKSEL[1:0].
CLKSEL3	SYNC	AL13	P30	PD ₁₀₀			GCB+I/O Offset 10h[3:0] (aka MCCM register bits [3:0]) (RO): Value programmed at reset by CLKSEL[3:0].
							GCB+I/O Offset 1Eh[3:0] (aka CCFC register bits [3:0]) (R/W, but write not recommended): Value programmed at reset by CLKSEL[3:0].
							Note: Values for GCB+I/O Offset 10h[3:0] and 1Eh[3:0] are not the same.
BOOT16	ROMCS#	G4	C8	PD ₁₀₀	Enable boot from 8-bit ROM	Enable boot from 16-bit ROM	GCB+I/O Offset 34h[3] (aka MCR register bit 3) (RO): Reads back strap setting.
							GCB+I/O Offset 34h[14] (R/W): Used to allow the ROMCS# width to be changed under program control.
TFT_PRSNT	SDATA_OU T	AK13	P29	PD ₁₀₀	TFT not muxed onto Parallel Port	TFT muxed onto Parallel Port	GCB+I/O Offset 30h[23] (aka PMR register bit 23) (R/W): Reads back strap setting.
LPC_ROM	PCICLK1	E4	D6	PD ₁₀₀	Disable boot from ROM on LPC bus	Enable boot from ROM on LPC bus	F0BAR1+I/O Offset 10h[15] (R/W): Reads back strap setting and allows LPC ROM to be changed under program control.
FPCI_MON	PCICLK0	D3	A4	PD ₁₀₀	Disable Fast- PCI, INTR_O, and SMI_O monitoring sig- nals.	Enable Fast- PCI, INTR_O, and SMI_O monitoring sig- nals. (Useful during debug.)	GCB+I/O Offset 34h[30] (aka MCR register bit 30) (RO): Reads back strap setting. Note: For normal operation, strap this signal low using a 1.5 KΩ resistor.
DID0	GNT0#	D4	C5	PD ₁₀₀	Defines the syste	em-level chip ID.	GCB+I/O Offset 34h[31,29] (aka
DID1	GNT1#	D2	C6	PD ₁₀₀			MCR register bits 31 and 29) (RO): Reads back strap setting.
							Note: GNT0# must have a PU resistor of 1.5 K Ω and GNT1# must have a PU resistor of 1.5 K Ω

Note: Accuracy of internal PU/PD resistors: 80K to 250K.

Location of the GCB (General Configuration Block) cannot be determined by software. See the AMD Geode™ SC3200 Specification Update document.

Revision 5.1

Signal Definitions

3.3 **Multiplexing Configuration**

The tables that follow list multiplexing options and their configurations. Certain multiplexing options may be chosen per signal; others are available only for a group of signals.

Where ever a GPIO pin is multiplexed with another function, there is an optional pull-up resistor on this pin; after system reset, the pull-up is present. This pull-up resistor can be disabled by writing Core Logic registers. The configuration is without regard to the selected ball function. The above applies to all pins multiplexed with GPIO, except GPIO12, GPIO13, and GPIO16.

Table 3-7. Two-Signal/Group Multiplexing

			Default		Alternate		
EBGA	TEPBGA	Signal Configuration		Signal	Configuration		
Bal	l No.		IDE	TFT, P	TFT, PCI, GPIO, System		
A26	AD3	IDE_ADDR0	PMR[24] = 0	TFTD3	PMR[24] = 1		
C26	AE1	IDE_ADDR1		TFTD2			
C17	U2	IDE_ADDR2		TFTD4			
B24	AC3	IDE_DATA0		TFTD6			
A24	AC1	IDE_DATA1		TFTD16			
D23	AC2	IDE_DATA2		TFTD14			
C23	AB4	IDE_DATA3		TFTD12			
B23	AB1	IDE_DATA4		FP_VDD_ON			
A23	AA4	IDE_DATA5		CLK27M			
C22	AA3	IDE_DATA6		IRQ9			
B22	AA2	IDE_DATA7		INTD#			
A21	Y3	IDE_DATA8		GPIO40			
C20	Y2	IDE_DATA9		DDC_SDA			
A20	Y1	IDE_DATA10		DDC_SCL			
C19	W4	IDE_DATA11		GPIO41			
B19	W3	IDE_DATA12		TFTD13			
A19	V3	IDE_DATA13		TFTD15			
C18	V2	IDE_DATA14		TFTD17			
B18	V1	IDE_DATA15		TFTD7			
C21	Y4	IDE_IOR0#		TFTD10			
A25	AD1	IDE_IORDY0		TFTD11			
C24	AC4	IDE_DREQ0		TFTD8			
D24	AD2	IDE_IOW0#		TFTD9			
A27	AF2	IDE_CS0#		TFTD5			
C16	P2	IDE_CS1#		TFTDE			
C25	AD4	IDE_DACK0#		TFTD0			
A22	AA1	IDE_RST#		TFTDCK			
D25	AF1	IRQ14		TFTD1			
Bal	l No.		Sub-ISA		GPIO		
H1	D11	TRDE#	PMR[12] = 0	GPIO0	PMR[12] = 1		

Table 3-7. Two-Signal/Group Multiplexing (Continued)

			Default		Alternate		
EBGA	TEPBGA	Signal	Configuration	Signal	Configuration		
Bal	l No.		GPIO	A	ACCESS.bus		
AJ12	N29	GPIO12	PMR[19] = 0	AB2C	PMR[19] = 1		
AL11	M29	GPIO13		AB2D			
Bal	l No.		GPIO		UART		
A28	AG1	GPIO18	PMR[16] = 0	DTR1#/BOUT1	PMR[16] = 1		
Bal	l No.		Infrared		UART		
J3	C11	IRTX	PMR[6] = 0	SOUT3	PMR[6] = 1		
J28	AK8	IRRX1		SIN3			
Bal	l No.		GPIO		LPC		
AJ11	M28	GPIO32	PMR[14] = 0 and	LAD0	PMR[14] = 1 and		
AL10	L31	GPIO33	PMR[22] = 0	LAD1	PMR[22] = 1		
AK10	L30	GPIO34		LAD2			
AJ10	L29	GPIO35		LAD3			
AL9	L28	GPIO36		LDRQ#			
AK9	K31	GPIO37		LFRAME#			
AJ9	K28	GPIO38/IRRX2		LPCPD#			
AL8	J31	GPIO39		SERIRQ			
Bal	l No.		UART	Ir	ternal Test		
AJ4	E28	SIN2	PMR[28] = 0	SDTEST3	PMR[28] = 1		
Bal	l No.		AC97	FPC	CI Monitoring		
AJ15	U29	AC97_RST#	FPCI_MON = 0	F_STOP#	FPCI_MON = 1		
AK14	U31	SDATA_IN		F_GNT0#			
AL14	U30	BIT_CLK		F_TRDY#			
Bal	Ball No. Inter		ternal Test	Ir	ternal Test		
C28	AG4	PLL6B	PMR[29] = 0	TEST1	PMR[29] = 1		
B29	AJ1	PLL5B		TEST2			
D28	AH3	PLL2B		TEST0			

Table 3-8. Three-Signal/Group Multiplexing

		De	efault	ault Alternate1			Alternate2		
EBGA	GA TEPBGA Signal		Configuration	Signal	Configuration	Signal	Configuration		
Ball	Ball No.		b-ISA	Sub-ISA ¹		GPIO			
F1	D9	IOR#	PMR[21] = 0 and	DOCR#	PMR[21] = 0 and	GPIO14	PMR[21] = 1 and		
G3	A8	IOW#	W# PMR[2] = 0		DOCW# PMR[2] = 1		GPIO15 PMR[2] = 1		
Ball No.		GPIO		AC97		FPCI Monitoring			



Table 3-8. Three-Signal/Group Multiplexing (Continued)

		De	efault	Α	Iternate1	Alte	ernate2	
EBGA	TEPBGA	Signal	Configuration	Signal	Configuration	Signal	Configuration	
AL15	V31	GPIO16	PMR[0] = 0 and FPCI_MON = 0	PC_BEEP PMR[0] = 1 = 0 and FPCI_MON = 0		F_DEVSEL	FPCI_MON = 1	
Ball	No.	GPIO		PCI ²		Su	ıb-ISA	
H4	C9	GPIO19	PMR[9] = 0 and PMR[4] = 0	INTC#	PMR[9] = 0 and PMR[4] = 1	IOCHRDY	PMR[9] = 1 and PMR[4] = 1	
Ball	No.	Para	llel Port		TFT ³	FPCI N	l onitoring	
U3	B18	ACK#	PMR[23] = 0 and	TFTDE	PMR[23] = 1 and	FPCI_CLK	PMR[23] = 0 and	
AB2	D22	AFD#/DSTRB#	(PMR[27] = 0 and	TFTD2	(PMR[27] = 0 and	INTR_O	(PMR[27] = 1 or FPCI_MON = 1)	
T1	B17	BUSY/WAIT#	FPCI_MON = 0)	TFTD3	FPCI_MON = 0)	F_C/BE1#	FPCI_WON = 1)	
AA3	D21	ERR#		TFTD4		F_C/BE0#		
Y3	B21	INIT#		TFTD5		SMI_O		
AA1	C21	PD0		TFTD6		F_AD0		
Y1	A21	PD1		TFTD7		F_AD1		
W3	D20	PD2		TFTD8		F_AD2		
W2	C20	PD3		TFTD9		F_AD3		
V1	C18	PD4		TFTD10		F_AD4		
V2	C19	PD5		TFTD11		F_AD5		
V3	A20	PD6		TFTD1		F_AD6		
U1	A18	PD7		TFTD13		F_AD7		
T3	D17	PE		TFTD14		F_C/BE2#		
T4	C17	SLCT		TFTD15		F_C/BE3#		
W1	B20	SLIN# /ASTRB#		TFTD16		F_IRDY		
AB1	A22	STB#/WRITE#		TFTD17		F_FRAME#		
Ball	No.	G	PIO	Sub-ISA		TFT ³		
J4	A10	GPIO17	PMR[23] = 0 and PMR[5] = 0	IOCS0#	PMR[23] = 0 and PMR[5] = 1	TFTDCK	PMR[23] = 1	
Н3	A9	GPIO20	PMR[23] = 0 and PMR[7] = 0	DOCCS#	PMR[23] = 0 and PMR[7] = 1	TFTD0	PMR[23] = 1	
H2	D10	GPIO1	PMR[23] = 0 and PMR[13] = 0	IOCS1#	PMR[23] = 0 and PMR[13] = 1	TFTD12	PMR[23] = 1	
Ball	No.	,	AB1		GPIO	Su	ıb-ISA	
AJ13	N31	AB1C	PMR[23] = 0	GPIO20	PMR[23] = 1 and PMR[7] = 0	DOCCS#	PMR[23] = 1 and PMR[7] = 1	
AL12	N30	AB1D	PMR[23] = 0	GPIO1	PMR[23] = 1 and PMR[13] = 0	IOCS1#	PMR[23] = 1 and PMR[13] = 1	
Ball	No.	G	PIO		UART2	I	DE2	
H30	AJ8	GPIO11	PMR[18] = 0 and PMR[8] = 0	RI2# PMR[18] = 1 and PMR[8] = 0		IRQ15	PMR[18] = 0 and PMR[8] = 1	
Ball	No.	Inter	nal Test	Int	ernal Test		TFT	
AL16	V30	GXCLK	PMR[23] = 0 and PMR[29] = 0	TEST3	PMR[23] = 0 and PMR[29] = 1	FP_VDD_ON	PMR[23] = 1	

^{1.} The combination of PMR[21] = 1 and PMR[2] = 0 is undefined and should not be used.

^{2.} The combination of PMR[9] = 1 and PMR[4] = 0 is undefined and should not be used.

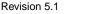
^{3.} These TFT outputs are reset to 0 by POR# if the TFT_PRSNT strap is pulled high or PMR[10] = 0. This relates to signals TFTD[17:0], TFTDE, TFTDCK.

Table 3-9. Four-Signal/Group Multiplexing

3A	Default		Alternate1		Alter	nate2	Alternate3		
EBGA	TEPB	Signal	Configuration	Signal	Configuration	Signal	Configuration	Signal	Configuration
Ball	II No. GPIO		GPIO	UART2		IDE2		Internal Test	
AH4	C30	GPIO7	PMR[17] = 0	RTS2#	PMR[17] = 1	IDE_DACK1#	PMR[17] = 0	SDTEST0	PMR[17] = 1
AJ2	C31	GPIO8	and PMR[8] = 0	CTS2#	and PMR[8] = 0	IIDE DREWI	and PMR[8] = 1	SDTEST4	and PMR[8] = 1
AH3	D28	GPIO6	PMR[18] = 0	DTR2#/BOUT2	PMR[18] = 1	IDE_IOR1#	PMR[18] = 0	SDTEST5	PMR[18] = 1
AG4	C28	GPIO9	and	DCD2#	and	IDE_IOW1#	and	SDTEST2	and PMR[8] = 1
AJ1	B29	GPIO10	PMR[8] = 0	DSR2#	PMR[8] = 0	IDE_IORDY1	PMR[8] = 1	SDTEST1	

Revision 5.1

Signal Definitions



Signal Descriptions 3.4

Information in the tables that follow may have duplicate information in multiple tables. Multiple references all contain identical information.

3.4.1 **System Interface**

	Bal	l No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
CLKSEL1	B27	AF3	I	Fast-PCI Clock Selects. These strap signals	SOUT1
CLKSEL0	F3	B8		are used to set the internal Fast-PCI clock. 00 = 33.3 MHz 01 = 48 MHz 10 = 66.7 MHz 11 = 33.3 MHz	RD#
				During system reset, an internal pull-down resistor of 100 K Ω exists on these balls. An external pull-up or pull-down resistor of 1.5 K Ω must be used.	
CLKSEL3	AL13	P30	Ι	Maximum Core Clock Multiplier. These	SYNC
CLKSEL2	AK3	D29		strap signals are used to set the maximum allowed multiplier value for the core clock.	SOUT2
				During system reset, an internal pull-down resistor of 100 K Ω exists on these balls. An external pull-up or pull-down resistor of 1.5 K Ω must be used.	
BOOT16	G4	C8	I	Boot ROM is 16 Bits Wide. This strap signal enables the optional 16-bit wide Sub-ISA bus.	ROMCS#
				During system reset, an internal pull-down resistor of 100 K Ω exists on these balls. An external pull-up or pull-down resistor of 1.5 K Ω must be used.	
LPC_ROM	E4	D6	I	LPC_ROM. This strap signal forces selecting of the LPC bus and sets bit F0BAR1+I/O Offset 10h[15], LPC ROM Addressing Enable. It enables the SC3200 to boot from a ROM connected to the LPC bus.	PCICLK1
				During system reset, an internal pull-down resistor of 100 K Ω exists on these balls. An external pull-up or pull-down resistor of 1.5 K Ω must be used.	
TFT_PRSNT	AK13	P29	I	TFT Present. A strap used to select multiplexing of TFT signals at power-up. Enables using TFT instead of Parallel Port, ACB1, and GPIO17.	SDATA_OUT
				During system reset, an internal pull-down resistor of 100 K Ω exists on these balls. An external pull-up or pull-down resistor of 1.5 K Ω must be used.	

3.4.1 System Interface (Continued)

	Bal	l No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
FPCI_MON	D3	A4	l	Fast-PCI Monitoring. The strap on this ball forces selection of Fast-PCI monitoring signals. For normal operation, strap this signal low using a 1.5 $K\Omega$ resistor. The value of this strap can be read on the MCR[30].	PCICLK0
DID1	D2	C6	ı	Device ID. Together, the straps on these sig-	GNT1#
DID0	D4	C5	I	nals define the system-level chip ID. The value of DID1 can be read in the MCR[29]. The value of DID0 can be read in the MCR[31].	GNT0#
				DID0 and DID1 must have a pull-up resistor of 1.5 $K\Omega$	
POR#	J29	AH9	I	Power On Reset. POR# is the system reset signal generated from the power supply to indicate that the system should be reset.	
X32I	C30	AJ2	I/O	Crystal Connections. Connected directly to	
X32O	D29	AJ3		a 32.768 KHz crystal. This clock input is required even if the internal RTC is not being used. Some of the internal clocks are derived from this clock. If an external clock is used, it should be connected to X32I, using a voltage level of 0 volts to V _{CORE} +10% maximum. X32O should remain unconnected.	
X27I	A29	AG3	I/O	Crystal Connections. Connected directly to	
X27O	D27	AH2		a 27.000 MHz crystal. Some of the internal clocks are derived from this clock. If an external clock is used, it should be connected to X27I, using a voltage level of 0 volts to V_{IO} and X27O should be remain unconnected.	
CLK27M	A23	AA4	0	27 MHz Output Clock. Output of crystal oscillator.	IDE_DATA5
PCIRST#	D1	A6	0	PCI and System Reset. PCIRST# is the reset signal for the PCI bus and system. It is asserted for approximately 100 µs after POR# is negated.	

3.4.2 Memory Interface Signals

	Ball	No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
MD[63:0]	See Table 3-3 on page 38.	See Table 3-5 on page 54.	I/O	Memory Data Bus. The data bus lines driven to/from system memory.	
MA[12:0]	See Table 3-3 on page 38.	See Table 3-5 on page 54.	0	Memory Address Bus. The multiplexed row/column address lines driven to the system memory. Supports 256-Mbit SDRAM.	
BA1	P31	AK14	0	Bank Address Bits. These bits are used to	
BA0	P30	AJ13		select the component bank within the SDRAM.	
CS1#	AK29	AH27	0	Chip Selects. These bits are used to select	
CS0#	P29	AL12		the module bank within system memory. Each chip select corresponds to a specific module bank. If CS# is high, the bank(s) do not respond to RAS#, CAS#, and WE# until the bank is selected again.	
RASA#	N31	AK12	0	Row Address Strobe. RAS#, CAS#, WE# and CKE are encoded to support the different SDRAM commands. RASA# is used with CS[1:0]#.	
CASA#	N30	AJ12	0	Column Address Strobe. RAS#, CAS#, WE# and CKE are encoded to support the different SDRAM commands. CASA# is used with CS[1:0]#.	
WEA#	N29	AH12	0	Write Enable. RAS#, CAS#, WE# and CKE are encoded to support the different SDRAM commands. WEA# is used with CS[1:0]#.	
DQM7	AJ20	AB31	0	Data Mask Control Bits. During memory	
DQM6	AJ26	AG29		read cycles, these outputs control whether SDRAM output buffers are driven on the MD	
DQM5	AC30	AK21		bus or not. All DQM signals are asserted dur-	
DQM4	T28	AL15		ing read cycles.	
DQM3	AJ21	AC31		During memory write cycles, these outputs control whether or not MD data is written into	
DQM2	AL26	AG30		SDRAM.	
DQM1	AF31	AH23		DQM[7:0] connect directly to the [DQM7:0]	
DQM0	M31	AL11		pins of each DIMM connector.	
CKEA	AC28	AL22	0	Clock Enable. These signals are used to enter Suspend/power-down mode. CKEA is used with CS[1:0]#.	
				If CKE goes low when no read or write cycle is in progress, the SDRAM enters power-down mode. To ensure that SDRAM data remains valid, the self-refresh command is executed. To exit this mode, and return to normal operation, drive CKE high.	
				These signals should have an external pull-down resistor of 33 K $\!\Omega$	

3.4.2 Memory Interface Signals (Continued)

	Ball	No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
SDCLK3	AJ16	V29	0	SDRAM Clocks. SDRAM uses these clocks	
SDCLK2	AL20	AA28		to sample all control, address, and data lines. To ensure that the Suspend mode functions	
SDCLK1	AH16	W29		correctly, SDCLK3 and SDCLK1 should be	
SDCLK0	AC29	AJ21		used with CS1#. SDCLK2 and SDCLK0 should be used together with CS0#.	
SDCLK_IN	AJ30	AJ27	I	SDRAM Clock Input. The SC3200 samples the memory read data on this clock. Works in conjunction with the SDCLK_OUT signal.	
SDCLK_OUT	AH28	AK28	0	SDRAM Clock Output. This output is routed back to SDCLK_IN. The board designer should vary the length of the board trace to control skew between SDCLK_IN and SDCLK.	

3.4.3 Video Port Interface Signals

	Ball No.				Mux
Signal Name	EBGA	TEPBGA	Туре	Description	Wux
VPD7	AJ6	G31	I	Video Port Data. The data is input from the	
VPD6	AJ7	H28		CCIR-656 video decoder.	
VPD5	AL6	H29			
VPD4	AH8	H30			
VPD3	AL7	H31			
VPD2	AJ8	J28			
VPD1	AK8	J29			
VPD0	AH9	J30			
VPCKIN	AH7	F31	I	Video Port Clock Input. The clock input from the video decoder.	

3.4.4 TFT Interface Signals

	Ball	No.			Maria
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
HSYNC	J1	A11	0	Horizontal Sync	
VSYNC	J2	B11	0	Vertical Sync	
TFTDCK	A22	AA1	0	TFT Clock.	IDE_RST#
	J4	A10			GPIO17+ IOCS0#
TFTDE	C16	P2	0	TFT Data Enable.	IDE_CS1#
	U3	B18			ACK#+FPCICLK
FP_VDD_ON	B23	AB1	0	TFT Power Control. Used to enable power	IDE_DATA4
	AL16	V30		to the flat panel display, with power sequence timing.	GXCLK+TEST3
TFTD[17:0]	See Table 3-3 on page 38.	See Table 3-5 on page 54.	0	Digital RGB Data to TFT. TFTD[5:0] - Connect to the BLUE TFT inputs. TFTD[11:6] - Connect to GREEN TFT inputs. TFTD[17:12] - Connect to RED TFT inputs.	The TFT interface is muxed with the IDE interface or the Par- allel Port. See Table 3-7 on page 59 and Table 3-8 on page 60 for details.

3.4.5 ACCESS.bus Interface Signals

	Ball	No.	Туре		
Signal Name	EBGA	TEPBGA		Description	Mux
AB1C	AJ13	N31	I/O	ACCESS.bus 1 Serial Clock. This is the serial clock for the interface.	GPIO20+DOCCS#
				Note: If selected as AB1C function but not used, tie AB1C high.	
AB1D	AL12	N30	I/O	ACCESS.bus 1 Serial Data. This is the bidirectional serial data signal for the interface.	GPIO1+IOCS1#
				Note: If AB1D function is selected but not used, tie AB1D high.	
AB2C	AJ12	N29	I/O	ACCESS.bus 2 Serial Clock. This is the serial clock for the interface.	GPIO12
				Note: If AB2C function is selected but not used, tie AB2C high.	
AB2D	AL11	M29	I/O	ACCESS.bus 2 Serial Data. This is the bidirectional serial data signal for the interface.	GPIO13
				Note: If AB2D function is selected but not used, tie AB2D high.	

3.4.6 PCI Bus Interface Signals

	Ball	No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
PCICLK	E2	A7	I	PCI Clock. PCICLK provides timing for all transactions on the PCI bus. All other PCI signals are sampled on the rising edge of PCICLK, and all timing parameters are defined with respect to this edge.	
PCICLK0	D3	A4	0	PCI Clock Outputs. PCICLK0 and PCICLK1	FPCI_MON (Strap)
PCICLK1	E4	D6	0	provide clock drives for the system at 33 MHz. These clocks are asynchronous to PCI signals. There is low skew between all outputs. One of these clock signals should be connected to the PCICLK input. All PCI clock users in the system (including PCICLK) should receive the clock with as low a skew as possible.	LPC_ROM (Strap)
AD[31:24]	See	See	I/O	Multiplexed Address and Data. A bus	D[7:0]
AD[23:0]	Table 3-3 on page 38.	Table 3-5 on page 54.		transaction consists of an address phase in the cycle in which FRAME# is asserted followed by one or more data phases. During the address phase, AD[31:0] contain a physical 32-bit address. For I/O, this is a byte address. For configuration and memory, it is a DWORD address. During data phases, AD[7:0] contain the least significant byte (LSB) and AD[31:24] contain the most significant byte (MSB).	A[23:0]
C/BE3#	A8	H4	I/O	Multiplexed Command and Byte Enables.	D11
C/BE2#	D8	F3		During the address phase of a transaction when FRAME# is active, C/BE[3:0]# define the bus command. During the data phase, C/	D10
C/BE1#	A10	J2			D9
C/BE0#	A13	L1		BE[3:0]# are used as byte enables. The byte enables are valid for the entire data phase and determine which byte lanes carry meaningful data. C/BE0# applies to byte 0 (LSB) and C/BE3# applies to byte 3 (MSB).	D8
INTA#	AE3	D26	I	PCI Interrupts. The SC3200 provides inputs for the optional "level-sensitive" PCI interrupts (also known in industry terms as PIRQx#). These interrupts can be mapped to	
INTB#	AF1	C26			
INTC#	H4	C9			GPIO19+IOCHRDY
INTD#	B22	AA2		IRQs of the internal 8259A interrupt controllers using PCI Interrupt Steering Registers 1 and 2 (F0 Index 5Ch and 5Dh). Note: If selected as INTC# or INTD# func-	IDE_DATA7
				tion(s) but not used, tie INTC# and INTD# high.	



Signal Name	BalL No.				
	EBGA	TEPBGA	Туре	Description	Mux
PAR	C10	J4	I/O	Parity. Parity generation is required by all PCI agents. The master drives PAR for address- and write-data phases. The target drives PAR for read-data phases. Parity is even across AD[31:0] and C/BE[3:0]#.	D12
				For address phases, PAR is stable and valid one PCI clock after the address phase. It has the same timing as AD[31:0] but is delayed by one PCI clock.	
				For data phases, PAR is stable and valid one PCI clock after either IRDY# is asserted on a write transaction or after TRDY# is asserted on a read transaction.	
				Once PAR is valid, it remains valid until one PCI clock after the completion of the data phase. (Also see PERR#.)	
FRAME#	E1	D8	I/O	Frame Cycle. Frame is driven by the current master to indicate the beginning and duration of an access. FRAME# is asserted to indicate the beginning of a bus transaction. While FRAME# is asserted, data transfers continue. FRAME# is de-asserted when the transaction is in the final data phase.	
				This signal is internally connected to a pull-up resistor.	
IRDY#	C8	F2	I/O	Initiator Ready. IRDY# is asserted to indicate that the bus master is able to complete the current data phase of the transaction. IRDY# is used in conjunction with TRDY#. A data phase is completed on any PCI clock in which both IRDY# and TRDY# are sampled as asserted. During a write, IRDY# indicates that valid data is present on AD[31:0]. During a read, it indicates that the master is prepared to accept data. Wait cycles are inserted until both IRDY# and TRDY# are asserted together.	D14
				This signal is internally connected to a pull-up resistor.	

	Ball	_ No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
TRDY#	B8	F1	I/O	Target Ready. TRDY# is asserted to indicate that the target agent is able to complete the current data phase of the transaction. TRDY# is used in conjunction with IRDY#. A data phase is complete on any PCI clock in which both TRDY# and IRDY# are sampled as asserted. During a read, TRDY# indicates that valid data is present on AD[31:0]. During a write, it indicates that the target is prepared to accept data. Wait cycles are inserted until both IRDY# and TRDY# are asserted together. This signal is internally connected to a pull-	D13
				up resistor.	
STOP#	D9	G1	I/O	Target Stop. STOP# is asserted to indicate that the current target is requesting that the master stop the current transaction. This signal is used with DEVSEL# to indicate retry, disconnect, or target abort. If STOP# is sampled active by the master, FRAME# is deasserted and the cycle is stopped within three PCI clock cycles. As an input, STOP# can be asserted in the following cases: 1) If a PCI master tries to access memory that has been locked by another master.	D15
				This condition is detected if FRAME# and LOCK# are asserted during an address phase.	
				If the PCI write buffers are full or if a previously buffered cycle has not completed.	
				3) On read cycles that cross cache line boundaries. This is conditional based upon the programming of GX1 module's PCI Configuration Register, Index 41h[1].	
				This signal is internally connected to a pull-up resistor.	



	Ball	L No.	Туре	Description	Mux
Signal Name	EBGA	TEPBGA			
LOCK#	C9	НЗ	I/O	Lock Operation. LOCK# indicates an atomic operation that may require multiple transactions to complete. When LOCK# is asserted, non-exclusive transactions may proceed to an address that is not currently locked (at least 16 bytes must be locked). A grant to start a transaction on PCI does not guarantee control of LOCK#. Control of LOCK# is obtained under its own protocol in conjunction with GNT#.	
				It is possible for different agents to use PCI while a single master retains ownership of LOCK#. The arbiter can implement a complete system lock. In this mode, if LOCK# is active, no other master can gain access to the system until the LOCK# is de-asserted.	
				This signal is internally connected to a pull-up resistor.	
DEVSEL#	B5	E4	I/O	Device Select. DEVSEL# indicates that the driving device has decoded its address as the target of the current access. As an input, DEVSEL# indicates whether any device on the bus has been selected. DEVSEL# is also driven by any agent that has the ability to accept cycles on a subtractive decode basis. As a master, if no DEVSEL# is detected within and up to the subtractive decode clock, a master abort cycle is initiated (except for special cycles which do not expect a DEVSEL# returned).	BHE#
				This signal is internally connected to a pull-up resistor.	
PERR#	В9	H2	I/O	Parity Error. PERR# is used for reporting data parity errors during all PCI transactions except a Special Cycle. The PERR# line is driven two PCI clocks after the data in which the error was detected. This is one PCI clock after the PAR that is attached to the data. The minimum duration of PERR# is one PCI clock for each data phase in which a data parity error is detected. PERR# must be driven high for one PCI clock before being placed in TRI-STATE. A target asserts PERR# on write cycles if it has claimed the cycle with DEVSEL#. The master asserts PERR# on read cycles.	
				This signal is internally connected to a pull-up resistor.	

	Ball	No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
SERR#	A9	H1	I/O	System Error. SERR# can be asserted by any agent for reporting errors other than PCI parity. When the PFS bit is enabled in the GX1 module's PCI Control Function 2 register (Index 41h[5]), SERR# is asserted upon assertion of PERR#.	
				This signal is internally connected to a pull-up resistor.	
REQ1#	E3	A5	I	Request Lines. REQ[1:0]# indicate to the	
REQ0#	C1	B5		arbiter that an agent requires the bus. Each master has its own REQ# line. REQ# priorities (in order) are: 1) VIP 2) IDE Channel 0 3) IDE Channel 1 4) Audio	
				5) USB	
				6) External REQ0#	
				7) External REQ1#.	
				Each REQ# is internally connected to a pull-up resistor.	
GNT1#	D2	C6	0	Grant Lines. GNT[1:0]# indicate to the	DID1 (Strap)
GNT0#	D4	C5		requesting master that it has been granted access to the bus. Each master has its own GNT# line. GNT# can be retracted at any time a higher REQ# is received or if the master does not begin a cycle within a minimum period of time (16 PCI clocks). Each of these signals is internally connected to a pull-up resistor. GNT0# must have a pull-up resistor of 1.5 $\rm K\Omega$ and GNT1# must have a pull-up resistor of 1.5 $\rm K\Omega$	DID0 (Strap)

3.4.7 Sub-ISA Interface Signals

	Ball	No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
A[23:0]	See Table 3-3 on page 38.	See Table 3-5 on page 54.	0	Address Lines	AD[23:0]
D15	See	See	I/O	Data Bus	STOP#
D14	Table 3-3 on page	Table 3-5 on page			IRDY#
D13	38.	54.			TRDY#
D12					PAR
D11					C/BE3#
D10					C/BE2#
D9					C/BE1#
D8					C/BE0#
D[7:0]					AD[31:24]
BHE#	B5	E4	0	Byte High Enable. With A0, defines byte accessed for 16 bit wide bus cycles.	DEVSEL#
IOCS1#	H2	D10	0	I/O Chip Selects	GPIO1+TFTD12
	AL12	N30			AB1D+GPIO1
IOCS0#	J4	A10			GPIO17+TFTDCK
ROMCS#	G4	C30	0	ROM or Flash ROM Chip Select	BOOT16 (Strap)
DOCCS#	H3	A9	0	DiskOnChip or NAND Flash Chip Select	GPIO20+TFTD0
	AJ13	N31			AB1C+GPIO20
TRDE#	H1	D11	0	Transceiver Data Enable Control. Active low for Sub-ISA data transfers. The signal timing is as follows:	GPIO0
				In a read cycle, TRDE# has the same timing as RD#.	
				In a write cycle, TRDE# is asserted (to active low) at the time WR# is asserted. It continues being asserted for one PCI clock cycle after WR# has been negated, then it is negated.	
RD#	F3	В8	0	Memory or I/O Read. Active on any read cycle.	CLKSEL0 (Strap)
WR#	G1	В9	0	Memory or I/O Write. Active on any write cycle.	
IOR#	F1	D9	0	I/O Read. Active on any I/O read cycle.	DOCR#+GPIO14
IOW#	G3	A8	0	I/O Write. Active on any I/O write cycle.	DOCW#+GPIO15
DOCR#	F1	D9	0	DiskOnChip or NAND Flash Read. Active on any memory read cycle to DiskOnChip.	IOR#+GPIO14
DOCW#	G3	A8	0	DiskOnChip or NAND Flash Write. Active on any memory write cycle to DiskOnChip.	IOW#+GPIO15

Revision 5.1 Signal Definitions

3.4.7 Sub-ISA Interface Signals (Continued)

	Ball	No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
IRQ9	C22	AA3	I	Interrupt 9 Request Input. Active high.	IDE_DATA6
				Note: If IRQ9 function is selected but not used, tie IRQ9 low.	
IOCHRDY	H4	C9	I	I/O Channel Ready	GPIO19+INTC#
				Note: If IOCHRDY function is selected but not used, tie IOCHRDY high.	

3.4.8 Low Pin Count (LPC) Bus Interface Signals

	Ball	No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
LAD3	AJ10	L29	I/O	LPC Address-Data. Multiplexed command,	GPIO35
LAD2	AK10	L30		address, bidirectional data, and cycle status.	GPIO34
LAD1	AL10	L31			GPIO33
LAD0	AJ11	M28			GPIO32
LDRQ#	AL9	L28	I	LPC DMA Request. Encoded DMA request for LPC interface.	GPIO36
				Note: If LDRQ# function is selected but not used, tie LDRQ# high.	
LFRAME#	AK9	K31	0	LPC Frame. A low pulse indicates the beginning of a new LPC cycle or termination of a broken cycle.	GPIO37
LPCPD#	AJ9	K28	0	LPC Power-Down. Signals the LPC device to prepare for power shut-down on the LPC interface.	GPIO38/IRRX2
SERIRQ	AL8	J31	I/O	Serial IRQ. The interrupt requests are serialized over a single signal, where each IRQ level is delivered during a designated time slot.	GPIO39
				Note: If SERIRQ function is selected but not used, tie SERIRQ high.	

3.4.9 IDE Interface Signals

	Ball	No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
IDE_RST#	A22	AA1	0	IDE Reset. This signal resets all the devices that are attached to the IDE interface.	TFTDCK
IDE_ADDR2	C17	U2	0	IDE Address Bits. These address bits are	TFTD4
IDE_ADDR1	C26	AE1		used to access a register or data port in a device on the IDE bus.	TFTD2
IDE_ADDR0	A26	AD3		dovide on the IBE sad.	TFTD3
IDE_DATA[15:0]	See Table 3-3 on page 38.	See Table 3-5 on page 54.	I/O	IDE Data Lines. IDE_DATA[15:0] transfers data to/from the IDE devices.	The IDE interface is muxed with the TFT interface. See Table 3-7 on page 59 for details.
IDE_IOR0#	C21	Y4	0	IDE I/O Read Channels 0 and 1.	TFTD10
IDE_IOR1#	AH3	D28	0	IDE_IOR0# is the read signal for Channel 0 and IDE_IOR1# is the read signal for Channel 1. Each signal is asserted at read accesses to the corresponding IDE port addresses.	GPIO6+DTR2#/ BOUT2+SDTEST5#
IDE_IOW0#	D24	AD2	0	IDE I/O Write Channels 0 and 1.	TFTD9
IDE_IOW1#	AG4	C28	0	IDE_IOW0# is the write signal for Channel 0. IDE_IOW1# is the write signal for Channel 1. Each signal is asserted at write accesses to corresponding IDE port addresses.	GPIO9+DCD2#+ SDTEST2
IDE_CS0#	A27	AF2	0	IDE Chip Selects 0 and 1. These signals are	TFTD5
IDE_CS1#	C16	P2	0	used to select the command block registers in an IDE device.	TFTDE
IDE_IORDY0	A25	AD1	I	I/O Ready Channels 0 and 1. When de-	TFTD11
IDE_IORDY1	AJ1	B29	I	asserted, these signals extend the transfer cycle of any host register access if the required device is not ready to respond to the data transfer request. Note: If selected as IDE_IORDY0 or IDE_IORDY1 function(s) but not used, then signal(s) should be tied high.	GPIO10+DSR2#+ SDTEST1
IDE_DREQ0	C24	AC4	ı	DMA Request Channels 0 and 1. The	TFTD8
IDE_DREQ1	AJ2	C31	I	IDE_DREQ signals are used to request a DMA transfer from the SC3200. The direction of transfer is determined by the IDE_IOR/ IOW signals. Note: If selected as IDE_DREQ0/	GPIO8+CTS2# +SDTEST5
				IDE_DREQ1 function but not used, tie IDE_DREQ0/IDE_DREQ1 low.	
IDE_DACK0#	C25	AD4	0	DMA Acknowledge Channels 0 and 1. The	TFTD0
IDE_DACK1#	AH4	C30	0	IDE_DACK# signals acknowledge the DREQ request to initiate DMA transfers.	GPIO7+RTS2# +SDTEST0

3.4.9 IDE Interface Signals (Continued)

	Ball No.				
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
IRQ14	D25	AF1	I	Interrupt Request Channels 0 and 1.	TFTD1
IRQ15	H30	AJ8	I	These input signals are edge-sensitive interrupts that indicate when the IDE device is requesting a CPU interrupt service.	GPIO11+RI2#
				Note: If selected as IRQ14/IRQ15 function but not used, tie IRQ14/IRQ15 low.	

3.4.10 Universal Serial Bus (USB) Interface Signals

	Ball No.				
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
POWER_EN	B28	AH1	0	Power Enable. This signal enables the power to a self-powered USB hub.	
OVER_CUR#	C27	AF4	I	Overcurrent. This signal indicates that the USB hub has detected an overcurrent on the USB.	
DPOS_PORT1	AH2	A28	I/O	USB Port 1 Data Positive for Port 1.1	
DNEG_PORT1	AG3	A29	I/O	USB Port 1 Data Negative for port 1.1	
DPOS_PORT2	AH1	B27	I/O	USB Port 2 Data Positive for Port 2.1	
DNEG_PORT2	AG2	B28	I/O	USB Port 2 Data Negative for Port 2.1	
DPOS_PORT3	AE4	A26	I/O	USB Port 3 Data Positive for Port 3.1	
DNEG_PORT3	AF3	A27	I/O	USB Port 3 Data Negative for Port 3.1	

^{1.} A 15K ohm pull-down resistor is required on all ports (even if unused).

3.4.11 Serial Ports (UARTs) Interface Signals

	Ball No.				
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
SIN1	D26	AG2	I	Serial Inputs. Receive composite serial data	
SIN2	AJ4	E28		from the communications link (peripheral device, modem or other data transfer	SDTEST3
SIN3	J28	AK8		device).	IRRX1
				Note: If selected as SIN2 or SIN3 function(s) but not used, then signal(s) should be tied high.	
SOUT1	B27	AF3	0	Serial Outputs. Send composite serial data	CLKSEL1 (Strap)
SOUT2	AK3	D29		to the communications link (peripheral device, modem or other data transfer device). These signals are set active high after a system reset.	CLKSEL2 (Strap)
SOUT3	J3	C11			IRTX



3.4.11 Serial Ports (UARTs) Interface Signals (Continued)

	Bal	l No.	Туре		
Signal Name	EBGA	TEPBGA		Description	Mux
RTS2#	AH4	C30	0	Request to Send. When low, indicates to the modem or other data transfer device that the corresponding UART is ready to exchange data. A system reset sets these signals to inactive high, and loopback operation holds them inactive.	GPIO7+ IDE_DACK1#
CTS2#	AJ2	C31	I	Clear to Send. When low, indicates that the modem or other data transfer device is ready to exchange data.	GPIO8+ IDE_DREQ1
				Note: If selected as CTS2# function but not used, tie CTS2# low.	
DTR1#/BOUT1	A28	AG1	0	Data Terminal Ready Outputs. When low,	GPIO18
DTR2#/BOUT2	AH3	D28		indicate to the modem or other data transfer device that the UART is ready to establish a communications link. After a system reset, these balls provide the DTR# function and set these signals to inactive high. Loopback operation drive them inactive.	GPIO6+IDE_IOR1#
				Baud Outputs. Provide the associated serial channel baud rate generator output signal if test mode is selected (i.e., bit 7 of the EXCR1 Register is set).	
RI2#	H30	AJ8	I	Ring Indicator. When low, indicates to the modem that a telephone ring signal has been received by the modem. They are monitored during power-off for wakeup event detection.	GPIO11+IRQ15
				Note: If selected as RI2# function but not used, tie RI2# high.	
DCD2#	AG4	C28	I	Data Carrier Detected. When low, indicates that the data transfer device (e.g., modem) is ready to establish a communications link.	GPIO9+IDE_IOW1# +SDTEST2
				Note: If selected as DCD2# function but not used, tie DCD2# high.	
DSR2#	AJ1	B29	I	Data Set Ready. When low, indicates that the data transfer device (e.g., modem) is ready to establish a communications link.	GPIO10+ IDE_IORDY1
				Note: If selected as DSR2# function but not used, tie DSR2# low.	

3.4.12 Parallel Port Interface Signals

	Bal	l No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
ACK#	U3	B18	I	Acknowledge. Pulsed low by the printer to indicate that it has received data from the Parallel Port.	TFTDE+FPCICLK
AFD#/DSTRB#	AB2	D22	0	Automatic Feed. When low, instructs the printer to automatically feed a line after printing each line. This signal is in TRI-STATE after a 0 is loaded into the corresponding control register bit. An external 4.7 K Ω pullup resistor should be attached to this ball.	TFTD2+INTR_O
				Data Strobe (EPP). Active low, used in EPP mode to denote a data cycle. When the cycle is aborted, DSTRB# becomes inactive (high).	
BUSY/WAIT#	T1	B17	I	Busy. Set high by the printer when it cannot accept another character.	TFTD3+F_C/BE1#
				Wait. In EPP mode, the Parallel Port device uses this active low signal to extend its access cycle.	
ERR#	AA3	D21	I	Error. Set active low by the printer when it detects an error.	TFTD4+F_C/BE0#
INIT#	Y3	B21	0	Initialize. When low, initializes the printer. This signal is in TRI-STATE after a 1 is loaded into the corresponding control register bit. Use an external 4.7 K Ω pull-up resistor.	TFTD5+SMI_O
PD7	U1	A18	I/O	Parallel Port Data. Transfer data to and from the peripheral data bus and the appropriate Parallel Port data register. These signals have a high current drive capability.	TFTD13+F_AD7
PD6	V3	A20			TFTD1+F_AD6
PD5	V2	C19			TFTD11+F_AD5
PD4	V1	C18			TFTD10+F_AD4
PD3	W2	C20			TFTD9+F_AD3
PD2	W3	D20			TFTD8+F_AD2
PD1	Y1	A21			TFTD7+F_AD1
PD0	AA1	C21			TFTD6+F_AD0
PE	Т3	D17	I	Paper End. Set high by the printer when it is out of paper. This ball has an internal weak pull-up or pull-down resistor that is programmed by soft-	TFTD14+F_C/BE2#
SLCT	T4	C17	I	Select. Set active high by the printer when the printer is selected.	TFTD15+F_C/BE3#
SLIN#/ASTRB#	W1	B20	0	Select Input. When low, selects the printer. This signal is in TRI-STATE after a 0 is loaded into the corresponding control register bit. Uses an external 4.7 $K\Omega$ pull-up resistor.	TFTD16+ F_IRDY#
				Address Strobe (EPP). Active low, used in EPP mode to denote an address or data cycle. When the cycle is aborted, ASTRB# becomes inactive (high).	

Signal Definitions Revision 5.1

3.4.12 Parallel Port Interface Signals (Continued)

	Ball No.				
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
STB#/WRITE#	AB1	A22	0	Data Strobe. When low, indicates to the printer that valid data is available at the printer port. This signal is in TRI-STATE after a 0 is loaded into the corresponding control register bit. An external 4.7 K Ω pull-up resistor should be employed.	TFTD17+ F_FRAME#
				Write Strobe. Active low, used in EPP mode to denote an address or data cycle. When the cycle is aborted, WRITE# becomes inactive (high).	

3.4.13 Fast Infrared (IR) Port Interface Signals

	Ball No.				
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
IRRX1	J28	AK8	I	IR Receive. Primary input to receive serial data from the IR transceiver. Monitored during power-off for wakeup event detection.	SIN3
				Note: If selected as IRRX1 function but not used, tie IRRX1 high.	
IRRX2/GPIO38	AJ9	K28	I	IR Receive 2. Auxiliary IR receiver input to support a second transceiver. This input signal can be used when GPIO38 is selected using PMR[14], and when AUX_IRRX bit in register IRCR2 of the IR module in internal SuperI/O is set.	LPCPD#
IRTX	J3	C11	0	IR Transmit. IR serial output data.	SOUT3

3.4.14 AC97 Audio Interface Signals

	Ball	No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
BIT_CLK	AL14	U30	I	Audio Bit Clock. The serial bit clock from the codec.	F_TRDY#
				Note: If selected as BIT_CLK function but not used, tie BIT_CLK low.	
SDATA_OUT	AK13	P29	0	Serial Data Output. This output transmits audio serial data to the codec.	TFT_PRSNT (Strap)
SDATA_IN	AK14	U31	I	Serial Data Input. This input receives serial data from the primary codec.	F_GNT0#
				Note: If selected as SDATA_IN function but not used, tie SDATA_IN low.	
SDATA_IN2	H31	AL8	I	Serial Data Input 2. This input receives serial data from the secondary codec. This signal has wakeup capability.	
SYNC	AL13	P30	0	Serial Bus Synchronization. This bit is asserted to synchronize the transfer of data between the SC3200 and the AC97 codec.	CLKSEL3 (Strap)
AC97_CLK	AJ14	P31	0	Codec Clock. It is twice the frequency of the Audio Bit Clock.	
AC97_RST#	AJ15	U29	0	Codec Reset. S3 to S5 wakeup is not supported because AC97_RST# is powered by V _{IO} . If wakeup from states S3 to S5 are needed, a circuit in the system board should be used to reset the AC97 codec.	F_STOP#
PC_BEEP	AL15	V31	0	PC Beep. Legacy PC/AT speaker output.	GPIO16+ F_DEVSEL#

3.4.15 Power Management Interface Signals

	Ball	No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
CLK32	H29	AH8	0	32.768 KHz Output Clock	
GPWIO0	E31	AH6	I/O	General Purpose Wakeup I/Os. These sig-	
GPWIO1	G28	AK5		nals each have an internal pull-up of 100 K Ω .	
GPWIO2	G29	AJ6			
LED#	D31	AL4	0	LED Control. Drives an externally connected LED (on, off or a 1 Hz blink). Sleeping / Working indicator. This signal is an opendrain output.	
ONCTL#	E30	AJ5	0	On / Off Control. This signal indicates to the main power supply that power should be turned on. This signal is an open-drain output.	



3.4.15 Power Management Interface Signals (Continued)

	Ba	II No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
PWRBTN#	E29	AH5	I	Power Button. Input used by the power management logic to monitor external system events, most typically a system on/off button or switch.	
				The signal has an internal pull-up of 100 K Ω , a Schmitt-trigger input buffer and debounce protection of at least 16 ms.	
				ACPI is non-functional and all ACPI outputs are undefined when the power-up sequence does not include using the power button. SUSP# is an internal signal generated from the ACPI block. Without an ACPI reset, SUSP# can be permanently asserted. If the USE_SUSP bit in CCR2 of GX1 module is enabled (Index C2h[7] = 1), the CPU will stop.	
				If ACPI functionality is desired, or the situation described above avoided, the power button must be toggled. This can be done externally or internally. GPIO63 is internally connected to PWRBTN#. To toggle the power button with software, GPIO63 must be programmed as an output using the normal GPIO programming protocol (see Section 6.4.1.1 "GPIO Support Registers" on page 240). GPIO63 must be pulsed low for at least 16 ms and not more than 4 sec.	
				Asserting POR# has no effect on ACPI. If POR# is asserted and ACPI was active prior to POR#, then ACPI will remain active after POR#. Therefore, BIOS must ensure that ACPI is inactive before GPIO63 is pulsed low.	
PWRCNT1	F31	AK6	0	Suspend Power Plane Control 1 and 2.	
PWRCNT2	G31	AL7	0	Control signal asserted during power management Suspend states. These signals are open-drain outputs.	
THRM#	F28	AK4	I	Thermal Event. Active low signal generated by external hardware indicating that the system temperature is too high.	

3.4.16 GPIO Interface Signals

	Bal	l No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
GPIO0	H1	D11	I/O	GPIO Port 0. Each signal is configured independently as an input or I/O, with or without static pull-up, and with either open-drain or	TRDE#
GPIO1	H2	D10			IOCS1#+TFTD12
	AL12	N30		totem-pole output type.	AB1D+IOCS1#
GPIO6	AH3	D28		A debouncer and an interrupt can be enabled or masked for each of signals GPIO[00:01] and [06:15] independently.	DTR2#/BOUT2+ IDE_IOR1#+ SDTEST5
GPIO7	AH4	C30		Note: GPIO12, GPIO13, GPIO16 inputs: If GPIOx function is selected but not	RTS2#+IDE_DACK1# +SDTEST0
GPIO8	AJ2	C31		used, tie GPIOx low.	CTS2#+IDE_DREQ1 +SDTEST4
GPIO9	AG4	C28			DCD2#+IDE_IOW1#+ SDTEST2
GPIO10	AJ1	B29			DSR2#+IDE_IORDY1 +SDTEST1
GPIO11	H30	AJ8			RI2#+IRQ15
GPIO12	AJ12	N29			AB2C
GPIO13	AL11	M29			AB2D
GPIO14	F1	D9			IOR#+DOCR#
GPIO15	G3	A8			IOW#+DOCW#
GPIO16	AL15	V31			PC_BEEP+ F_DEVSEL#
GPIO17	J4	A10			IOCS0#+TFTDCK
GPIO18	A28	AG1			DTR1#/BOUT1
GPIO19	H4	C9			INTC#+IOCHRDY
GPIO20	НЗ	A9			DOCCS#+TFTD0
	AJ13	N31			AB1C+DOCCS#
GPIO32	AJ11	M28	I/O	GPIO Port 1. Each signal is configured inde-	LAD0
GPIO33	AL10	L31		pendently as an input or I/O, with or without static pull-up, and with either open-drain or	LAD1
GPIO34	AK10	L30		totem-pole output type.	LAD2
GPIO35	AJ10	L29		A debouncer and an interrupt can be enabled	LAD3
GPIO36	AL9	L28		or masked for each of signals GPIO[32:41] independently.	LDRQ#
GPIO37	AK9	K31		пиоропиониу.	LFRAME#
GPIO38/IRRX2	AJ9	K28			LPCPD#
GPIO39	AL8	J31			SERIRQ
GPIO40	A21	Y3			IDE_DATA8
GPIO41	C19	W4			IDE_DATA11

3.4.17 Debug Monitoring Interface Signals

	Ball	No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
FPCICLK	U3	B18	0	Fast-PCI Bus Monitoring Signals. When	ACK#+TFTDE
F_AD7	U1	A18	0	enabled, this group of signals provides for monitoring of the internal Fast-PCI bus for	PD7+TFTD13
F_AD6	V3	A20	0	debug purposes. To enable, pull up	PD6+TFTD1
F_AD5	V2	C19	0	FPCI_MON (EBGA ball D3 / TEPBGA ball	PD5+TFTD11
F_AD4	V1	C18	0	A4).	PD4+TFTD10
F_AD3	W2	C20	0		PD3+TFTD9
F_AD2	W3	D20	0		PD2+TFTD8
F_AD1	Y1	A21	0		PD1+TFTD7
F_AD0	AA1	C21	0		PD0+TFTD6
F_C/BE3#	T4	C17	0		SLCT+TFTD15
F_C/BE2#	T3	D17	0		PE+TFTD14
F_C/BE1#	T1	B17	0		BUSY/WAIT#+ TFTD3
F_C/BE0#	AA3	D21	0		ERR#+TFTD4+
F_FRAME#	AB1	A22	0		STB#/WRITE#+ TFTD17
F_IRDY#	W1	B20	0		SLIN#/ASTRB#+ TFTD16
F_STOP#	AJ15	U29	0		AC97_RST#
F_DEVSEL#	AL15	V31	0		GPIO16+ PC_BEEP
F_GNT0#	AK14	U31	0		SDATA_IN
F_TRDY#	AL14	U30	0		BIT_CLK
INTR_O	AB2	D22	0	CPU Core Interrupt. When enabled, this signal provides for monitoring of the internal GX1 core INTR signal for debug purposes. To enable, pull up FPCI_MON (EBGA ball D3 / TEPBGA ball A4).	AFD#/DSTRB#+ TFTD2
SMI_O	Y3	B21	0	System Management Interrupt. This is the input to the GX1 core. When enabled, this signal provides for monitoring of the internal GX1 core SMI# signal for debug purposes. To enable, pull up FPCI_MON (EBGA ball D3 / TEPBGA ball A4).	INIT#+TFTD5+

3.4.18 JTAG Interface Signals

Ball No.					
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
TCK	AL4	E31	I	JTAG Test Clock. This signal has an internal weak pull-up resistor.	
TDI	AK5	F29	I	JTAG Test Data Input. This signal has an internal weak pull-up resistor.	
TDO	AH6	E30	0	JTAG Test Data Output	
TMS	AJ5	F28	I	JTAG Test Mode Select. This signal has an internal weak pull-up resistor.	
TRST#	AK4	E29	I	JTAG Test Reset. This signal has an internal weak pull-up resistor.	
				For normal JTAG operation, this signal should be active at power-up.	
				If the JTAG interface is not being used, this signal can be tied low.	

3.4.19 Test and Measurement Interface Signals

	Ball	No.			
Signal Name	EBGA	TEPBGA	Type	Description	Mux
GXCLK	AL16	V30	0	GX Clock. This signal is for internal testing only. For normal operation either program as FP_VDD_ON or leave unconnected.	FP_VDD_ON+ TEST3
TEST3	AL16	V30	0	Internal Test Signal. This signal is used for internal testing only. For normal operation leave unconnected, unless programmed as FP_VDD_ON.	FP_VDD_ON+ GXCLK
TEST2	B29	AJ1	0	Internal Test Signals. These signals are	PLL5B
TEST1	C28	AG4	0	used for internal testing only. For normal operation, leave unconnected unless pro-	PLL6B
TEST0	D28	AH3	0	grammed as one of their muxed options.	PLL2B
GTEST	AL5	F30	I	Global Test. This signal is used for internal testing only. For normal operation this signal should be pulled down with 1.5 K Ω .	
PLL6B	C28	AG4	I/O	PLL6, PLL5 and PLL2 Bypass. These sig-	TEST1
PLL5B	B29	AJ1	I/O	nals are used for internal testing only. For	TEST2
PLL2B	D28	AH3	I/O	normal opolation loave allocalloctu.	TEST0



3.4.19 Test and Measurement Interface Signals (Continued)

	Ball	No.			
Signal Name	EBGA	TEPBGA	Туре	Description	Mux
SDTEST5	AH3	D28	0	Memory Internal Test Signals. These signals are used for internal testing only. For normal operation, these signals should be	GPIO6+ DTR2#/BOUT2+ IDE_IOR1#
SDTEST4	AJ2	C31	0	programmed as one of their muxed options.	GPIO8+CTS2#+ IDE_DREQ1
SDTEST3	AJ4	E28	0		SIN2
SDTEST2	AG4	C28	0		GPIO9+DCD2#+ IDE_IOW1#
SDTEST1	AJ1	B29	0		GPIO10+DSR2# +IDE_IORDY1
SDTEST0	AH4	C30	0		GPIO7+RTS2#+ IDE_DACK1#
TDP	AH5	D30	I/O	Thermal Diode Positive / Negative. These	
TDN	AL3	D31	I/O	signals are for internal testing only. For normal operation leave unconnected.	

3.4.20 Power, Ground and No Connections¹

	Ball	No.				
Signal Name	EBGA	TEPBGA	Туре	Description		
AV _{SSPLL2}	R3	C16	GND	Analog PLL2 Ground Connection.		
AV _{SSPLL3}	E28	AK3	GND	Analog PLL3 Ground Connection.		
V _{PLL2}	R1	A17	PWR	3.3V PLL2 Analog Power Connection. Low noise power for PLL2 and PLL5.		
V _{PLL3}	C31	AJ4	PWR	3.3V PLL3 Analog Power Connection. Low noise power for PLL3, PLL4, and PLL6.		
AV _{CCUSB}	AF4	D27	PWR	3.3V Analog USB Power Connection. Low noise power.		
AV _{SSUSB}	AG1	C27	GND	Analog USB Ground Connection.		
V _{BAT}	D30	AL3	PWR	Battery. Provides battery back-up to the RTC and ACPI registers, when V_{SB} is lower than the minimum value (see Table 9-3 on page 370). The ball is connected to the internal logic through a series resistor for UL protection. If battery backup is not desired, connect V_{BAT} to V_{SS} .		
V_{SB}	F29	AL5	PWR	3.3V Standby Power Supply. Provides power to the Real-Time Clock (RTC) and ACPI circuitry while the main power supply is turned off.		
V _{SBL}	H28	AL6	PWR	1.8V Standby Power Supply. Provides power to the internal logic while the main power supply is turned off. This signal requires a 0.1 μ F bypass capacitor to V _{SS} . This supply must be present when V _{SB} is present.		
V _{CORE}	SeeTable 3-3 on page 38. (Total of 26)	See Table 3-5 on page 54. (Total of 29)	PWR	1.8V Core Processor Power Connections.		
V _{IO}	See Table 3-3 on page 38. (Total of 35)	See Table 3-5 on page 54. (Total of 46)	PWR	3.3V I/O Power Connections.		
V _{SS}	See Table 3-3 on page 38. (Total of 61)	See Table 3-5 on page 54. (Total of 96)	GND	Ground Connections.		
NC	See Table 3-3 on page 38. (Total of 13)	See Table 3-5 on page 54. (Total of 13)		No Connections. These lines should be left disconnected. Connecting a pull-up/-down resistor or to an active signal could cause unexpected results and possible malfunctions.		

^{1.} All power sources except V_{BAT} must be connected, even if the function is not used.

General Configuration Block

The General Configuration block includes registers for:

- · Pin Multiplexing and Miscellaneous Configuration
- WATCHDOG Timer
- · High-Resolution Timer
- · Clock Generators

A selectable interrupt is shared by all these functions.

4.1 Configuration Block Addresses

Registers of the General Configuration block are I/O mapped in a 64-byte address range. These registers are physically connected to the internal Fast-PCI bus, but do

not have a register block in PCI configuration space (i.e., they do not appear to software as PCI registers).

After system reset, the Base Address register is located at I/O address 02EAh. This address can be used only once. Before accessing any PCI registers, the BOOT code must program this 16-bit register to the I/O base address for the General Configuration block registers. All subsequent writes to this address, are ignored until system reset.

Note: Location of the General Configuration Block cannot be determined by software. See the AMD $Geode^{TM}$ SC3200 Specification Update document.

Reserved bits in the General Configuration block should read as written unless otherwise specified.

Table 4-1. General Configuration Block Register Summary

Offset	Width (Bits)	Туре	Name	Reset Value	Reference
00h-01h	16	R/W	WDTO. WATCHDOG Timeout	0000h	Page 96
02h-03h	16	R/W	WDCNFG. WATCHDOG Configuration	0000h	Page 96
04h	8	R/WC	WDSTS. WATCHDOG Status	00h	Page 97
05h-07h			RSVD. Reserved		
08h-0Bh	32	RO	TMVALUE. TIMER Value	xxxxxxxxh	Page 98
0Ch	8	R/W	TMSTS. TIMER Status	00h	Page 98
0Dh	8	R/W	TMCNFG. TIMER Configuration	00h	Page 98
0Eh-0Fh			RSVD. Reserved		
10h	8	RO	MCCM. Maximum Core Clock Multiplier	Strapped Value	Page 103
11h			RSVD. Reserved		
12h	8	R/W	PPCR. PLL Power Control	2Fh	Page 103
13h-17h			RSVD. Reserved		
18h-1Bh	32	R/W	PLL3C. PLL3 Configuration	E1040005h	Page 103
1Ch-1Dh			RSVD. Reserved		
1Eh-1Fh	16	R/W	CCFC. Core Clock Frequency Control	Strapped Value	Page 104
20h-2Fh			RSVD. Reserved		
30h-33h	32	R/W	PMR. Pin Multiplexing Register	00000000h	Page 88
34h-37h	32	R/W	MCR. Miscellaneous Configuration Register	0000001h	Page 92
38h	8	R/W	INTSEL. Interrupt Selection	00h	Page 94
39h-3Bh			RSVD. Reserved		
3Ch	8	RO	ID. Device ID	xxh	Page 94
3Dh	8	RO	REV. Revision	xxh	Page 94
3Eh-3Fh	16	RO	CBA. Configuration Base Address	xxxxh	Page 94

4.2 Multiplexing, Interrupt Selection, and Base Address Registers

The registers described inTable 4-2 are used to determine general configuration for the SC3200. These registers also indicate which multiplexed signals are issued via balls from which more than one signal may be output. For more infor-

mation about multiplexed signals and the appropriate configurations, see Section 3.1 "Ball Assignments" on page 27.

Table 4-2. Multiplexing, Interrupt Selection, and Base Address Registers

	Description				
Offset 30h This regist			ultiplexing Register - PMR See Section 3.1 on page 27		Reset Value: 00000000h tion about multiplexing information.
31:30	Reserved: Always	write 0.			
29	Test Signals. Sele	cts ball functions.			
	Ball #	0: Internal Test Sig	nals	1: Internal Te	st Signals
	EBGA / TEPBGA	Name	Add'l Dependencies	Name	Add'l Dependencies
	D28 / AH3	PLL2B	None	TEST0	None
	C28 / AG4	PLL6B	None	TEST1	None
	B29 / AJ1	PLL5B	None	TEST2	None
	AL16 / V30	GXCLK	See PMR[23]	TEST3	PMR[23] = 0
28	Test Signals. Sele	cts ball function.			
	Ball #	0: AC97 Signal		1: Internal Te	_
	EBGA / TEPBGA		Add'l Dependencies	Name	Add'l Dependencies
	AJ4 / E28	SIN2	None	SDTEST3	See Note.
	Note: If this bit is	s set, PMR[8] and PN	MR[18] must be set by software	are.	
27	FPCI_MON (Fast-I	PCI Monitoring). Sel	ects Fast-PCI monitoring ou	tput signals instea	ad of Parallel Port signals.
	PMR[27] F 0 0 1 1	0 Disable at 1 Enable at 0 Enable Fa	III Fast-PCI monitoring signa II Fast-PCI monitoring signal ast-PCI monitoring signals n	s	
		i Lilabie ai	II Fast-PCI monitoring signal	s	el Port signals only
	Ball #	i Lilable ai	II Fast-PCI monitoring signal	s	l Port signals only
	Ball # EBGA / TEPBGA	FPCI_MON Signal	0 0		al Port signals only
		FPCI_MON Signal FPCICLK	0 0	Add See	d'I Dependencies PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18	FPCI_MON Signal FPCICLK F_AD7	Other Signal ACK#+TFTDE PD7+TFTD13	Add See See	d'I Dependencies PMR[23] PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20	FPCI_MON Signal FPCICLK F_AD7 F_AD6	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1	Add See See See	d'I Dependencies PMR[23] PMR[23] PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11	Add See See See See	d'I Dependencies PMR[23] PMR[23] PMR[23] PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10	Add See See See See	d'I Dependencies PMR[23] PMR[23] PMR[23] PMR[23] PMR[23] PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11	Add See See See See See	d'I Dependencies PMR[23] PMR[23] PMR[23] PMR[23] PMR[23] PMR[23] PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18 W2 / C20	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4 F_AD3	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10 PD3+TFTD9	Add See See See See See See	d'I Dependencies PMR[23] PMR[23] PMR[23] PMR[23] PMR[23] PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18 W2 / C20 W3 / D20 Y1 / A21 AA1 / C21	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4 F_AD3 F_AD2 F_AD1 F_AD0	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10 PD3+TFTD9 PD2+TFTD8 PD1+TFTD7 PD0_TFTD5	Add See See See See See See See See	d'I Dependencies PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18 W2 / C20 W3 / D20 Y1 / A21 AA1 / C21 T4 / C17	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4 F_AD3 F_AD2 F_AD1 F_AD0 F_C/BE3#	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10 PD3+TFTD9 PD2+TFTD8 PD1+TFTD7 PD0_TFTD5 SLCT+TFTD15	Add See See See See See See See See See	d'I Dependencies PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18 W2 / C20 W3 / D20 Y1 / A21 AA1 / C21 T4 / C17 T3 / D17	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4 F_AD3 F_AD2 F_AD1 F_AD0 F_C/BE3# F_C/BE2#	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10 PD3+TFTD9 PD2+TFTD8 PD1+TFTD7 PD0_TFTD5 SLCT+TFTD15 PE+TFTD14	Add See See See See See See See See See S	d'I Dependencies PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18 W2 / C20 W3 / D20 Y1 / A21 AA1 / C21 T4 / C17 T3 / D17 T1 / B17	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4 F_AD3 F_AD2 F_AD1 F_AD0 F_C/BE3# F_C/BE2# F_C/BE1#	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10 PD3+TFTD9 PD2+TFTD8 PD1+TFTD7 PD0_TFTD5 SLCT+TFTD15 PE+TFTD14 BUSY/WAIT#+TFTD3	Add See See See See See See See See See S	d'I Dependencies PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18 W2 / C20 W3 / D20 Y1 / A21 AA1 / C21 T4 / C17 T3 / D17 T1 / B17 AA3 / D21	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4 F_AD3 F_AD2 F_AD1 F_AD0 F_C/BE3# F_C/BE2# F_C/BE0#	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10 PD3+TFTD9 PD2+TFTD8 PD1+TFTD7 PD0_TFTD5 SLCT+TFTD15 PE+TFTD14 BUSY/WAIT#+TFTD3 ERR#+TFTD4	Add See See See See See See See See See S	d'I Dependencies PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18 W2 / C20 W3 / D20 Y1 / A21 AA1 / C21 T4 / C17 T3 / D17 T1 / B17	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4 F_AD3 F_AD2 F_AD1 F_AD0 F_C/BE3# F_C/BE2# F_C/BE1#	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10 PD3+TFTD9 PD2+TFTD8 PD1+TFTD7 PD0_TFTD5 SLCT+TFTD15 PE+TFTD14 BUSY/WAIT#+TFTD3	Addenotes Addeno	d'I Dependencies PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18 W2 / C20 W3 / D20 Y1 / A21 AA1 / C21 T4 / C17 T3 / D17 T1 / B17 AA3 / D21 AB1 / A22 W1 / B20 AB2 / D22	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4 F_AD3 F_AD2 F_AD1 F_AD0 F_C/BE3# F_C/BE2# F_C/BE2# F_C/BE0# F_FC/BE0# F_FRAME#	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10 PD3+TFTD9 PD2+TFTD8 PD1+TFTD7 PD0_TFTD5 SLCT+TFTD15 PE+TFTD14 BUSY/WAIT#+TFTD3 ERR#+TFTD4 STB#/WRITE#+TFTD7	Addenotes Addeno	d'I Dependencies PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18 W2 / C20 W3 / D20 Y1 / A21 AA1 / C21 T4 / C17 T3 / D17 T1 / B17 AA3 / D21 AB1 / A22 W1 / B20	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4 F_AD3 F_AD2 F_AD1 F_AD0 F_C/BE3# F_C/BE2# F_C/BE2# F_C/BE0# F_FRAME# F_IRDY#	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10 PD3+TFTD9 PD2+TFTD8 PD1+TFTD7 PD0_TFTD5 SLCT+TFTD15 PE+TFTD14 BUSY/WAIT#+TFTD3 ERR#+TFTD4 STB#/WRITE#+TFTD7 SLIN#/ASTRB#+TFTD16	Addenotes Addeno	d'I Dependencies PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18 W2 / C20 W3 / D20 Y1 / A21 AA1 / C21 T4 / C17 T3 / D17 T1 / B17 AA3 / D21 AB1 / A22 W1 / B20 AB2 / D22	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4 F_AD3 F_AD2 F_AD1 F_AD0 F_C/BE3# F_C/BE2# F_C/BE2# F_C/BE0# F_FRAME# F_IRDY# INTR_O	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10 PD3+TFTD9 PD2+TFTD8 PD1+TFTD7 PD0_TFTD5 SLCT+TFTD15 PE+TFTD14 BUSY/WAIT#+TFTD3 ERR#+TFTD4 STB#/WRITE#+TFTD7 SLIN#/ASTRB#+TFTD16 AFD#/DSTRB#+TFTD2	Add See See See See See See See See See S	d'I Dependencies PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18 W2 / C20 W3 / D20 Y1 / A21 AA1 / C21 T4 / C17 T3 / D17 T1 / B17 AA3 / D21 AB1 / A22 W1 / B20 AB2 / D22 Y3 / B21 AL15 / V31 AJ15 / U29	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4 F_AD3 F_AD2 F_AD1 F_AD0 F_C/BE3# F_C/BE2# F_C/BE1# F_C/BE0# F_FRAME# F_IRDY# INTR_O SMI_O F_DEVSEL# F_STOP#	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10 PD3+TFTD9 PD2+TFTD8 PD1+TFTD7 PD0_TFTD5 SLCT+TFTD15 SLCT+TFTD14 BUSY/WAIT#+TFTD3 ER#+TFTD4 STB#/WRITE#+TFTD7 SLIN#/ASTRB#+TFTD16 AFD#/DSTRB#+TFTD2 INIT#+TFTD5 GPIO16+PC_BEEP AC97_RST#	Add See See See See See See See See See S	d'I Dependencies PMR[23]
	EBGA / TEPBGA U3 / B18 U1 / A18 V3 / A20 V2 / C19 V1 / C18 W2 / C20 W3 / D20 Y1 / A21 AA1 / C21 T4 / C17 T3 / D17 T1 / B17 AA3 / D21 AB1 / A22 W1 / B20 AB2 / D22 Y3 / B21 AL15 / V31	FPCI_MON Signal FPCICLK F_AD7 F_AD6 F_AD5 F_AD4 F_AD3 F_AD2 F_AD1 F_AD0 F_C/BE3# F_C/BE2# F_C/BE1# F_C/BE0# F_FRAME# F_IRDY# INTR_O SMI_O F_DEVSEL#	Other Signal ACK#+TFTDE PD7+TFTD13 PD6+TFTD1 PD5+TFT11 PD4+TFTD10 PD3+TFTD9 PD2+TFTD8 PD1+TFTD7 PD0_TFTD5 SLCT+TFTD15 SLCT+TFTD14 BUSY/WAIT#+TFTD3 ERR#+TFTD4 STB#/WRITE#+TFTD7 SLIN#/ASTRB#+TFTD16 AFD#/DSTRB#+TFTD2 INIT#+TFTD5 GPIO16+PC_BEEP	Add See See See See See See See See See S	d'I Dependencies PMR[23]

Table 4-2. Multiplexing, Interrupt Selection, and Base Address Registers (Continued)

Bit	Description							
26	Reserved. Always	Reserved. Always write 0.						
25	AC97CKEN (Enab	le AC97_CLK Output). This	s bit enables the output drive of AC97_CLK (EBGA ball AJ14 / TEPBGA ball					
	0: AC97_CLK outp	ut is HiZ.						
	1: AC97_CLK outp	ut is enabled.						
24	TFTIDE (TFT/IDE) additional depende		n balls are used for TFT signals or for IDE signals. Note that there are no					
	Ball # EBGA / TEPBGA A26 / AD3	0: IDE Signals Name IDE_ADDR0	1: GPIO and TFT Signals Name TFTD3					
	C26 / AE1	IDE_ADDR1	TFTD2					
	C17 / U2	IDE_ADDR2	TFTD4					
	B24 / AC3	IDE_DATA0	TFTD6					
	A24 / AC1	IDE_DATA1	TFTD16					
	D23 / AC2	IDE_DATA2	TFTD14					
	C23 / AB4	IDE_DATA3	TFTD12					
	B23 / AB1	IDE_DATA4	FP_VDD_ON					
	A23 / AA4	IDE_DATA5	CLK27M					
	C22 / AA3	IDE_DATA6	IRQ9					
	B22 / AA2	IDE_DATA7	INTD#					
	A21 / Y3	IDE_DATA8	GPIO40					
	C20 / Y2	IDE_DATA9	DDC_SDA					
	A20 / Y1	IDE_DATA10	DDC_SCL					
	C19 / W4	IDE_DATA11	GPIO41					
	B19 / W3	IDE_DATA12	TFTD13					
	A19 / V3	IDE_DATA13	TFTD15					
	C18 / V2	IDE_DATA14	TFTD17					
	B18 / V1	IDE_DATA15	TFTD7					
	A27 / AF2	IDE_CS0#	TFTD5					
	C16 / P2	IDE_CS1#	TFTDE					
	C21 / Y4	IDE_IOR0#	TFTD10					
	D24 / AD2	IDE_IOW0#	TFTD9					
	C24 / AC4	IDE_DREQ0	TFTD8					
	C25 / AD4	IDE_DACK0#	TFTD0					
	A22 / AA1	IDE_RST#	TFTDCK					
	A25 / AD1	IDE_IORDY0	TFTD11					
	D25 / AF1	IRQ14	TFTD1					

Table 4-2. Multiplexing, Interrupt Selection, and Base Address Registers (Continued)

t	Description									
	•	•	s whether certain balls are u GA ball AK13 / TEPBGA bal		CB1/FPCI. This bit is set to 1					
	Ball # EBGA / TEPBGA	0: PP/ACB1/FPCI Name	Add'l Dependencies	1: TFT Name	Add'l Dependencies					
	H2 / D10	GPIO1 IOCS1#	PMR[13] = 0 PMR[13] = 1	TFTD12	None					
	H3 / A9	GPIO20 DOCCS#	PMR[7] = 0 PMR[7] = 1	TFTD0	None					
	J4 / A10	GPIO17 IOCS0#	PMR[5] = 0 PMR[5] = 1	TFTDCK	None					
	T1 / B17	BUSY/WAIT# F_C/BE1#	Note 1 Note 2	TFTD3	None					
	T3 / D17	PE F_C/BE2#	Note 1 Note 2	TFTD14	Note 1					
	T4 / C17	SLCT F_C/BE3#	Note 1 Note 2	TFTD15	Note 1					
	U1 / A18	PD7 F_AD7	Note 1 Note 2	TFTD13	Note 1					
	U3 / B18	ACK# FPCICLK	Note 1 Note 2	TFTDE	Note 1					
	V1 / C18	PD4 F_AD4	Note 1 Note 2	TFTD10	Note 1					
	V2 / C19	PD5 F_AD5	Note 1 Note 2	TFTD11	Note 1					
	V3 / A20	PD6 F_AD6	Note 1 Note 2	TFTD1	Note 1					
	W1 / B20	SLIN#/ASTRB# F_IRDY#	Note 1 Note 2	TFTD16	Note 1					
	W2 / C20	PD3 F_AD3	Note 1 Note 2	TFTD9	Note 1					
	W3 / D20	PD2 F_AD2	Note 1 Note 2	TFTD8	Note 1					
	Y1 / A21	PD1 F_AD1	Note 1 Note 2	TFTD7	Note 1					
	Y3 / B21	INIT# SMI_O	Note 1 Note 2	TFTD5	Note 1					
	AA1 / C21	PD0 F_AD0	Note 1 Note 2	TFTD6	Note 1					
	AA3 / D21	ERR# F_C/BE0#	Note 1 Note 2	TFTD4	Note 1					
	AB1 / A22	STB#/WRITE# F_FRAME#	Note 1 Note 2	TFTD17	None					
	AB2 / D22	AFD#/DSTRB# INTR_O	Note 1 Note 2	TFTD2	Note 1					
	AJ13 / N31	AB1C	None	GPIO20 DOCCS#	PMR[7] = 0 $PMR[7] = 1$					
	AL12 / N30	AB1D	None	GPIO1 IOCS1#	PMR[13] = 0 PMR[13] = 1					
	AL16 / V30	GXCLK TEST3	PMR[29] = 0 PMR[29] = 1	FP_VDD_ON	None					
	-	7] = 0 and FPCI_MO 7] = 1 or FPCI_MON								
	3. ACCES	S.bus interface 1 is r	not available if PMR[23] = 1							
	4. If FPCI	_MON strap is enable	ed, the TFT_PRSNT strap s	should pulled low. .PC_ROM strap (EBG						



Table 4-2. Multiplexing, Interrupt Selection, and Base Address Registers (Continued)

Ball: EBG	# A / TEPBGA D9 A8 erved. Must be SEL (Select A # A / TEPBGA 2 / N29 1 / M29 SEL (Select S # A / TEPBGA / D28 / C28 / B29 / AJ8 CRSEL (Select	0: I/O Command Name IOR# DOCR# IOW# DOCW# e set to 0. ACCESS.bus 2). Se 0: GPIO Signals Name GPIO12 GPIO13 SP2 Additional Pin 0: GPIO, IDE Sig Name GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15	Add'I Dependencies PMR[2] = 0 PMR[2] = 1 PMR[2] = 0 PMR[2] = 1 elects ball functions. Add'I Dependencies None None None S. Selects ball functions.	1: GPIO Signals Name GPIO14 Undefined GPIO15 Undefined 1: ACCESS.bus 2 Name AB2C AB2D 1: Serial Port Sig Name DTR2#/BOUT2 SDTEST5 DCD2# SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2# Undefined	Add'I Dependencies None None	
EBG F1 / I G3 / G3 / P0 Rese P1 AB2: Ball: EBG AJ12 AL11 SP25 Ball: EBG AH3 AG4 AJ1 / H30 / C7 SP20 Ball: EBG AH4 AJ2 / G SP15 Ball: EBG	A / TEPBGA D9 A8 erved. Must be SEL (Select A # A / TEPBGA 2 / N29 I / M29 SEL (Select S # A / TEPBGA / D28 / C28 / B29 / AJ8 CRSEL (Select #	Name IOR# DOCR# IOW# DOCW# e set to 0. ACCESS.bus 2). Se 0: GPIO Signals Name GPIO12 GPIO13 BP2 Additional Pin 0: GPIO, IDE Sig Name GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Control	Add'I Dependencies PMR[2] = 0 PMR[2] = 1 PMR[2] = 0 PMR[2] = 1 PMR[2] = 1 PMR[2] = 1 Pelects ball functions. Add'I Dependencies None None None Is). Selects ball functions. Inals Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1	Name GPIO14 Undefined GPIO15 Undefined 1: ACCESS.bus 2 Name AB2C AB2D 1: Serial Port Sig Name DTR2#/BOUT2 SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	PMR[2] = 1 PMR[2] = 0 PMR[2] = 1 PMR[2] = 0 PMR[2] = 0 2 Signals Add'I Dependencies None None Mals Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0	
G3 / Rese 9 AB23 Ball EBG AJ12 AL11 8 SP23 Ball EBG AH3 AG4 AJ1 / H30 / H30 / CONTRACTOR	A8 erved. Must be SEL (Select A # A / TEPBGA 2 / N29 I / M29 SEL (Select S # A / TEPBGA / D28 / C28 / B29 / AJ8 CRSEL (Select #	DOCR# IOW# DOCW# e set to 0. ACCESS.bus 2). Se 0: GPIO Signals Name GPIO12 GPIO13 BP2 Additional Pin 0: GPIO, IDE Sig Name GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Control	PMR[2] = 1 PMR[2] = 0 PMR[2] = 1 PMR[2] = 1 elects ball functions. Add'I Dependencies None None Is). Selects ball functions. Ignals Add'I Dependencies PMR[8] = 0 PMR[8] = 1	Undefined GPIO15 Undefined 1: ACCESS.bus 2 Name AB2C AB2D 1: Serial Port Sig Name DTR2#/BOUT2 SDTEST5 DCD2# SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	PMR[2] = 0 PMR[2] = 1 PMR[2] = 0 PMR[2] = 0 2 Signals Add'I Dependencies None None Mals Add'I Dependencies PMR[8] = 0 PMR[8] = 1	
PO Rese PO Res PO Rese PO Rese PO Rese PO Rese PO Rese PO Rese PO Res P	erved. Must be SEL (Select A # SA / TEPBGA 2 / N29 1 / M29 SEL (Select S # SA / TEPBGA / D28 / C28 / B29 / AJ8 CRSEL (Select #	DOCW# e set to 0. CCESS.bus 2). Set 0: GPIO Signals Name GPIO12 GPIO13 SP2 Additional Pin 0: GPIO, IDE Sig Name GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Control	PMR[2] = 1 elects ball functions. Add'I Dependencies None None Is). Selects ball functions. Ignals Add'I Dependencies PMR[8] = 0 PMR[8] = 1	1: ACCESS.bus 2 Name AB2C AB2D 1: Serial Port Sig Name DTR2#/BOUT2 SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	PMR[2] = 0 2 Signals Add'l Dependencies None None Mals Add'l Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0	
9 AB23 Ball: EBG AJ12 AL11 8 SP25 Ball: EBG AH3 AG4 AJ1 / H30 . 7 SP20 Ball: EBG AH4 AJ2 / 6 SP15 Ball: EBG	##A / TEPBGA 2 / N29 1 / M29 SEL (Select S #A / TEPBGA / D28 / C28 / B29 / AJ8 CRSEL (Select #	O: GPIO Signals Name GPIO12 GPIO13 GP2 Additional Pin O: GPIO, IDE Sig Name GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Contro	Add'I Dependencies None None Is). Selects ball functions. Ignals Add'I Dependencies PMR[8] = 0 PMR[8] = 1	Name AB2C AB2D 1: Serial Port Sig Name DTR2#/BOUT2 SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	Add'I Dependencies None None nals Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 0 PMR[8] = 0	
Ball: EBG AJ12 AL11 8 SP28 Ball: EBG AH3 AG4 AJ1 / H30 . 7 SP20 Ball: EBG AH4 AJ2 / 6 SP18 Ball: EBG	# A / TEPBGA 2 / N29 I / M29 SEL (Select S # A / TEPBGA / D28 / C28 / B29 / AJ8 CRSEL (Select Select	O: GPIO Signals Name GPIO12 GPIO13 GP2 Additional Pin O: GPIO, IDE Sig Name GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Control	Add'I Dependencies None None Is). Selects ball functions. Ignals Add'I Dependencies PMR[8] = 0 PMR[8] = 1	Name AB2C AB2D 1: Serial Port Sig Name DTR2#/BOUT2 SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	Add'I Dependencies None None nals Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 0 PMR[8] = 0	
BBG AJ12 AL11 8 SP28 Ball: EBG AH3 AG4 AJ1 / H30 / H30 / 7 SP20 Ball: EBG AH4 AJ2 / 6 SP18 Ball: EBG	A / TEPBGA 2 / N29 1 / M29 SEL (Select S # A / TEPBGA / D28 / C28 / B29 / AJ8 CRSEL (Select #	Name GPIO12 GPIO13 SP2 Additional Pin 0: GPIO, IDE Sig Name GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Control	Add'I Dependencies None None Is). Selects ball functions. Ignals Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 1 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1	Name AB2C AB2D 1: Serial Port Sig Name DTR2#/BOUT2 SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	Add'I Dependencies None None nals Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 0 PMR[8] = 0	
AJ12 AL11 8 SP28 Ball: EBG AH3 AG4 AJ1 / H30 / H30 / 7 SP20 Ball: EBG AH4 AJ2 / 6 SP18 Ball: EBG	2 / N29 1 / M29 SEL (Select S # A / TEPBGA / D28 / C28 / B29 / AJ8 CRSEL (Select	GPIO12 GPIO13 FP2 Additional Pin 0: GPIO, IDE Sig Name GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Control	None None None S.). Selects ball functions. Spals Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 1 PMR[8] = 0 PMR[8] = 0 PMR[8] = 1 PMR[8] = 1	AB2C AB2D 1: Serial Port Sig Name DTR2#/BOUT2 SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	None None nals Add'l Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0	
AL11 8 SP28 Ball: EBG AH3 AG4 AJ1 / H30 / 7 SP20 Ball: EBG AH4 AJ2 / 6 SP18 Ball: EBG	I / M29 SEL (Select S # A / TEPBGA / D28 / C28 / B29 / AJ8 CRSEL (Select #	GPIO13 IP2 Additional Pin 0: GPIO, IDE Sig Name GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Control	None Is). Selects ball functions. Ignals Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 0 PMR[8] = 1	AB2D 1: Serial Port Sig Name DTR2#/BOUT2 SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	None nals Add'l Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0	
8 SP2S Ball: EBG AH3 AG4 AJ1 / H30. 7 SP2C Ball: EBG AH4 AJ2 / 6 SP1S Ball: EBG	# A / TEPBGA / D28 / C28 / B29 / AJ8 CRSEL (Select	O: GPIO, IDE Sig Name GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15	sy). Selects ball functions. gnals Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 1	1: Serial Port Sig Name DTR2#/BOUT2 SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	nals Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0	
Ball EBG AH3 AG4 AJ1 / H30 / SP20 Ball EBG AH4 AJ2 / 6 SP1S Ball EBG	# A / TEPBGA / D28 / C28 / B29 / AJ8 CRSEL (Select	0: GPIO, IDE Sig Name GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15	pnals Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 1	Name DTR2#/BOUT2 SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0	
FBG AH3 AG4 AJ1 / H30 / FSP20 Balli EBG AH4 AJ2 / 6 SP13 Balli EBG	A / TEPBGA / D28 / C28 / B29 / AJ8 CRSEL (Select	Name GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Control	Add'l Dependencies PMR[8] = 0 PMR[8] = 1	Name DTR2#/BOUT2 SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	Add'I Dependencies PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0	
AH3 AG4 AJ1 / H30 / FSP20 Balli EBG AH4 AJ2 / 6 SP1S Balli EBG	/ D28 / C28 / B29 / AJ8 CRSEL (Select	GPIO6 IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Control	PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1	DTR2#/BOUT2 SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0	
AG4 AJ1 / H30 / 7 SP20 Ball : EBG AH4 AJ2 / 6 SP13 Ball : EBG	/ C28 / B29 / AJ8 CRSEL (Select	IDE_IOR1# GPIO9 IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Control	PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1	SDTEST5 DCD2# SDTEST2 DSR2# SDTEST1 RI2#	PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0	
7 SP20 Ball: EBG AH4 AJ2 / 6 SP13 Ball: EBG	/ B29 / AJ8 CRSEL (Select	IDE_IOW1# GPIO10 IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Contro	PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0 PMR[8] = 1	SDTEST2 DSR2# SDTEST1 RI2#	PMR[8] = 1 PMR[8] = 0 PMR[8] = 1 PMR[8] = 0	
7 SP20 Ball: EBG AH4 AJ2 / 6 SP13 Ball: EBG	/ AJ8 CRSEL (Selec	IDE_IORDY1 GPIO11 IRQ15 ct SP2 Flow Control	PMR[8] = 1 PMR[8] = 0 PMR[8] = 1	SDTEST1 RI2#	PMR[8] = 1 PMR[8] = 0	
7 SP20 Ball: EBG AH4 AJ2 / 6 SP13 Ball: EBG	CRSEL (Selec	IRQ15 ct SP2 Flow Contro	PMR[8] = 1			
Ball : EBG AH4 AJ2 / 6 SP13 Ball : EBG	#		ol). Selects ball functions.			
EBG AH4 AJ2 / 6 SP15 Ball EBG	==	U. GPIO IDE SIA				
AH4 AJ2 / 6 SP15 Ball EBG	A / TEPBGA	J. OI IO, IDE SIG	gnals	1: Serial Port Sig	nals	
AJ2 / 6 SP1S Ball		Name	Add'l Dependencies	Name	Add'l Dependencies	
6 SP18 Ball	/ C30	GPIO7 IDE_DACK1#	PMR[8] = 0 $PMR[8] = 1$	RTS2# SDTEST0	PMR[8] = 0 $PMR[8] = 1$	
Ball EBG	/ C31	GPIO8 IDE_DREQ1	PMR[8] = 0 $PMR[8] = 1$	CTS2# SDTEST4	PMR[8] = 0 PMR[8] = 1	
EBG	SP1SEL (Select SP1 Additional Pin). Selects ball function.					
A28	# A / TEPBGA	0: GPIO Signal Name	Add'l Dependencies	1: Serial Port Sig Name	nal Add'l Dependencies	
	/ AG1	GPIO18	None	DTR1#/BOUT1	None	
5 RSV	D (Reserved)	. Write to 0.				
	•	.PC Bus). Selects to DR) state of PMR[1	ball functions. The LPC_ROM	1 strap (EBGA ball E4 /	TEPBGA ball D6) determines	
Ball		0: GPIO Signals Name		1: LPC Signals Name	Add'l Dependencies	
	/ M28	GPIO32	PMR[22] = 0	LAD0	PMR[22] = 1	
) / L31	GPIO33	PMR[22] = 0	LAD1	PMR[22] = 1	
	0 / L30	GPIO34	PMR[22] = 0	LAD2	PMR[22] = 1	
) / L29	GPIO35	PMR[22] = 0	LAD3	PMR[22] = 1	
	/ L28	GPIO36	PMR[22] = 0	LDRQ#	PMR[22] = 1	
	/ K31	GPIO37	PMR[22] = 0	LFRAME#	PMR[22] = 1	
	/ K28	GPIO38/IRRX2	PMR[22] = 0	LPCPD#	PMR[22] = 1	
AL8		GPIO39	PMR[22] = 0	SERIRQ	PMR[22] = 1	



Table 4-2. Multiplexing, Interrupt Selection, and Base Address Registers (Continued)

Bit	Description						
12	TRDESEL (Select	TRDESEL (Select TRDE#). Selects ball function.					
	Ball # EBGA / TEPBGA	0: Sub-ISA Signa Name	al Add'l Dependencies	1: GPIO Signal Name	Add'l Dependencies		
	H1 / D11	TRDE#	None	GPIO0	None		
11	EIDE (Enable IDE	Outputs). This bit	enables IDE output signals.				
	this register). The	nis bit does not con	multiplexed on the same ball- trol IDE channel 1 control sig		s set. (without regard to bit 24 of f this register.		
	•	are enabled.					
10	by PMR[23].			that are multiplexed wit	th the Parallel Port and controlled		
		•	FTDCK are set to 0.				
			FTDCK are enabled.	. / =======			
		•	on IDE_RST# (EBGA ball A22	2 / TEPBGA ball AA1) i	is also enabled by this bit.		
9	IOCHRDY (Select	•					
	Ball # EBGA / TEPBGA		Add'l Dependencies	1: Sub-ISA Signa Name	Add'l Dependencies		
	H4 / C9	GPIO19 INTC#	PMR[4] = 0 $PMR[4] = 1$	IOCHRDY Undefined	PMR[4] = 1 $PMR[4] = 0$		
8	IDE1SEL (Select II PMR[17], see PMR	DE Channel 1). Se	lects IDE Channel 1 or GPIO		n conjunction with PMR[18] and		
7	DOCCSSEL (Selection PMR[23] for definition	•	ts DOCCS# or GPIO20 ball f	unctions. Works in con	junction with PMR[23], see		
6	SP3SEL (Select U	ART3). Selects ball	functions.				
	Ball # EBGA / TEPBGA	0: IR Signals Name	Add'l Dependencies	1: Serial Port Sig Name	nals Add'l Dependencies		
	J28 / AK8	IRRX1	None	SIN3	None		
	J3 / C11	IRTX	None	SOUT3	None		
5	IOCS0SEL (Select	IOCS0#). Selects	ball function. Works in conjur	nction with PMR[23], se	ee PMR[23] for definition.		
4	INTCSEL (Select I	NTC#). Selects bal	I function. Works in conjunction	on with PMR[9], see PI	MR[9] for definition.		
3	Reserved. Write as	s read.					
2	DOCWRSEL (Sele PMR[21], see PMR		d NAND Flash Command L	ines). Selects ball fund	ctions. Works in conjunction with		
1	Reserved. Write as						
0	PCBEEPSEL (Sele	- ,	ects ball function.				
	Ball # EBGA / TEPBGA		Add'l Dependencies	1: Audio Signal Name	Add'l Dependencies		
	AL15 / V31	GPIO16 F_DEVSEL#	FPCI_MON = 0 FPCI_MON = 1	PC_BEEP F_DEVSEL#	FPCI_MON] = 0 FPCI_MON = 1		
Offset 34 Power-on			ous Configuration Register cts "Enable 16-Bit Wide Boot	` '	Reset Value: 0000001h		
31	DID0 (EBGA Ball I			ly) Represents the valu	e of the strap that is latched after		
30	latched after power	on reset. Indicates	.	t signals (instead of Pa	the value of the strap that is arallel Port and some audio sigfunction. See PMR[27] definition.		
29	DID1 (EBGA Ball I		, , ,	ly) Represents the valu	ie of the strap that is latched after		
28:20	Reserved.	-					
19:18	Reserved. Write as	s 0.					
17	HSYNC Timing. H	SYNC timing contro	ol for TFT.				
	0: Reserved.						
	i .	uited for TFT.					



Table 4-2. Multiplexing, Interrupt Selection, and Base Address Registers (Continued)

Bit	Description
16	Delay HSYNC. HSYNC delay by two TFT clock cycles.
	0: There is no delay on HSYNC.
	1: HYSNC is delayed twice by rising edge of TFT clock. Enables delay between VSYNC and HSYNC suited for TFT display.
15	Reserved. Write as read.
14	IBUS16 (Invert BUS16). This bit inverts the meaning of MCR[3] (bit 3 of this register).
	0: BUS16 is as described for MCR[3].
	1: BUS16 meaning is inverted: if MCR[3] = 0, ROMCS# access is 16 bits wide; if MCR[3] = 1, ROMCS# access is 8 bits wide.
13	Reserved. Must be set to 0.
12	IO1ZWS (Enable ZWS# for IOCS1# Access). This bit enables internal activation of ZWS# (Zero Wait States) control for IOCS1# access.
	0: ZWS# is not active for IOCS1# access.
	1: ZWS# is active for IOCS1# access.
11	IOOZWS (Enable ZWS# for IOCS0# Access). This bit enables internal activation of ZWS# (Zero Wait States) control for IOCS0# access.
	0: ZWS# is not active for IOCS0# access.
	1: ZWS# is active for IOCS0# access.
10	DOCZWS (Enable ZWS# for DOCCS# Access). This bit enables internal activation of ZWS# (Zero Wait States) control for DOCCS# access.
	0: ZWS# is not active for DOCCS# access.
	1: ZWS# is active for DOCCS# access.
9	ROMZWS (Enable ZWS# for ROMCS# Access). This bit enables internal activation of ZWS# (Zero Wait States) control for ROMCS# access.
	0: ZWS# is not active for ROMCS# access.
	1: ZWS# is active for ROMCS# access.
8	IO1_16 (Enable 16-Bit Wide IOCS1# Access). This bit enables the16-line access to IOCS1# in the Sub-ISA interface.
	0: 8-bit wide IOCS1# access is used.
	1: 16-bit wide IOCS1# access is used.
7	IO0_16 (Enable 16-Bit Wide IOCS0# Access). This bit enables the 16-line access to IOCS0# in the Sub-ISA interface.
	0: 8-bit wide IOCS0# access is used.
	1: 16-bit wide IOCS0# access is used.
6	DOC16 (Enable 16-Bit Wide DOCCS# Access). This bit enables the 16-line access to DOCCS# in the Sub-ISA interface.
	0: 8-bit wide DOCCS# access is used.
	1: 16-bit wide DOCCS# access is used.
5	Reserved. Write as read.
4	IRTXEN (Infrared Transmitter Enable). This bit enables drive of Infrared transmitter output.
	0: IRTX+SOUT3 line (EBGA ball J3 / TEPBGA ball C11) is HiZ.
	1: IRTX+SOUT3 line (EBGA ball J3 / TEPBGA ball C11) is enabled.
3	BUS16 (16-Bit Wide Boot Memory). (Read Only) This bit reports the status of the BOOT16 strap (EBGA ball G4 / TEP-BGA ball C8). If the BOOT16 strap is pulled high, at reset 16-bit access to ROM in the Sub-ISA interface is enabled. MCR[14] = 1 inverts the meaning of this register.
	0: 8-bit wide ROM.
	1: 16-bit wide ROM.
2:1	Reserved. Write as read.



Table 4-2. Multiplexing, Interrupt Selection, and Base Address Registers (Continued)

Bit	Description						
0		SDBE0 (Slave Disconnect Boundary Enable). Works in conjunction with the GX1 module's PCI Control Function 2 Register (Index 41h), bit 1 (SDBE1). Sets boundaries for when the GX1 module is a PCI slave.					
	SDBE[1:0]						
	00: Read and Write di 41h).	sconnect on boundaries set l	by bits [3:2] of the GX1 module's	s PCI Control Function 2 register (Index			
		on boundaries set by bits [3: e boundary of 16 bytes.	2] of the GX1 module's PCI Cor	ntrol Function 2 register. Read discon-			
	1x: Read and Write di	sconnect on cache line boun	dary of 16 bytes.				
	This bit is reset to 1.						
		All PCI bus masters (including SC3200's on-chip PCI bus masters, e.g., the USB Controller) must be disabled while modifying this bit. When accessing this register while any PCI bus master is enabled, use read-modify-write to ensure these bit					
			Register - INTSEL (R/W) G and High-Resolution timer inf	Reset Value: 00h terrupt. This interrupt is shareable with			
7:4	Reserved. Write as rea	ad.					
7:4 3:0	Reserved. Write as real CBIRQ. Configuration						
			1000: IRQ8#	1100: IRQ12			
	CBIRQ. Configuration	Block Interrupt.	1000: IRQ8# 1001: IRQ9	1100: IRQ12 1101: Reserved			
	CBIRQ. Configuration 0000: Disable	Block Interrupt. 0100: IRQ4					
	CBIRQ. Configuration 0000: Disable 0001: IRQ1	Block Interrupt. 0100: IRQ4 0101: IRQ5	1001: IRQ9	1101: Reserved			
3:0	CBIRQ. Configuration 0000: Disable 0001: IRQ1 0010: Reserved 0011: IRQ3	0100: IRQ4 0101: IRQ5 0110: IRQ6 0111: IRQ7	1001: IRQ9 1010: IRQ10	1101: Reserved 1110: IRQ14			
3:0 Offset 39 Offset 30	CBIRQ. Configuration 0000: Disable 0001: IRQ1 0010: Reserved 0011: IRQ3	Block Interrupt. 0100: IRQ4 0101: IRQ5 0110: IRQ6 0111: IRQ7 Reserv	1001: IRQ9 1010: IRQ10 1011: IRQ11	1101: Reserved 1110: IRQ14			
3:0 Offset 30 Offset 30 This region	CBIRQ. Configuration 0000: Disable 0001: IRQ1 0010: Reserved 0011: IRQ3 9h-3Bh Ch ister identifies the device. S	Block Interrupt. 0100: IRQ4 0101: IRQ5 0110: IRQ6 0111: IRQ7 Reserv Device Identification I	1001: IRQ9 1010: IRQ10 1011: IRQ11	1101: Reserved 1110: IRQ14 1111: IRQ15 Reset Value: xxh			
3:0 Offset 30 Offset 30 This regis Offset 31 This regis	CBIRQ. Configuration 0000: Disable 0001: IRQ1 0010: Reserved 0011: IRQ3 9h-3Bh Ch ister identifies the device. S Dh ister identifies the device re	Block Interrupt. 0100: IRQ4 0101: IRQ5 0110: IRQ6 0111: IRQ7 Reserve Device Identification Interpretation	1001: IRQ9 1010: IRQ10 1011: IRQ11 red - RSVD Number Register - ID (RO)	1101: Reserved 1110: IRQ14 1111: IRQ15 Reset Value: xxh			
3:0 Offset 30 This regist Offset 31 This regist Offset 31	CBIRQ. Configuration 0000: Disable 0001: IRQ1 0010: Reserved 0011: IRQ3 9h-3Bh Ch ister identifies the device. Significant of the device reserved device reserved device reserved.	Block Interrupt. 0100: IRQ4 0101: IRQ5 0110: IRQ6 0111: IRQ7 Reserve Device Identification It is in the configuration Base Add of the Configuration block.	1001: IRQ9 1010: IRQ10 1011: IRQ11 red - RSVD Number Register - ID (RO) gister - REV (RO) ™ SC3200 Specification Update	1101: Reserved 1110: IRQ14 1111: IRQ15 Reset Value: xxh Reset Value: xxh e document for value. Reset Value: xxh			

4.3 WATCHDOG

General Configuration Block

The SC3200 includes a WATCHDOG function to serve as a fail-safe mechanism in case the system becomes hung. When triggered, the WATCHDOG mechanism returns the system to a known state by generating an interrupt, an SMI, or a system reset (depending on configuration).

4.3.1 Functional Description

WATCHDOG is enabled when the WATCHDOG Timeout (WDTO) register (Offset 00h) is set to a non-zero value. The WATCHDOG timer starts with this value and counts down until either the count reaches 0, or a trigger event restarts the count (with the WDTO register value).

The WATCHDOG timer is restarted in any of the following cases:

- · The WDTO register is set with a non-zero value.
- The WATCHDOG timer reaches 0 and the WATCHDOG Overflow bit, WDOVF (Offset 04h[0]), is 0.

The WATCHDOG function is disabled in any of the following cases:

- · System reset occurs.
- The WDTO register is set to 0.
- The WDOVF bit is already 1 when the timer reaches 0.

4.3.1.1 WATCHDOG Timer

The WATCHDOG timer is a 16-bit down counter. Its input clock is a 32 KHz clock divided by a predefined value (see WDPRES field, Offset 02h[3:0]). The 32 KHz input clock is enabled when either:

• The GX1 module's internal SUSPA# signal is 1.

or

 The GX1 module's internal SUSPA# signal is 0 and the WD32KPD bit (Offset 02h[8]) is 0.

The 32 KHz input clock is disabled, when:

 The GX1 module's internal SUSPA# signal is 0 and the WD32KPD bit is 1.

For more information about signal SUSPA#, refer to the $AMD\ Geode^{TM}\ GX1\ Processor\ Data\ Book.$

When the WATCHDOG timer reaches 0:

- If the WDOVF bit in the WDSTS register (Offset 04h[0]) is 0, an interrupt, an SMI or a system reset is generated, depending on the value of the WDTYPE1 field in the WDCNFG register (Offset 02h[5:4]).
- If the WDOVF bit in the WDSTS register is already 1
 when the WATCHDOG timer reaches 0, an interrupt, an
 SMI or a system reset is generated according to the
 WDTYPE2 field (Offset 02h[7:6]), and the timer is
 disabled. The WATCHDOG timer is re-enabled when a
 non-zero value is written to the WDTO register (Offset
 00h).

The interrupt or SMI is de-asserted when the WDOVF bit is set to 0. The reset generated by the WATCHDOG function is used to trigger a system reset via the Core Logic module. The value of the WDOVF bit, the WDTYPE1 field, and the WDTYPE2 field are not affected by a system reset (except when generated by power-on reset).

The SC3200 also allows no action to be taken when the timer reaches 0 (according to WDTYPE1 field and WDTYPE2 field). In this case only the WDOVF bit is set to 1.

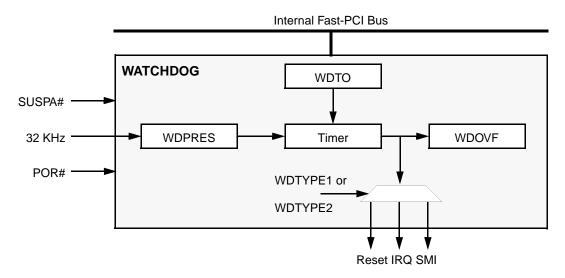


Figure 4-1. WATCHDOG Block Diagram



WATCHDOG Interrupt

The WATCHDOG interrupt (if configured and enabled) is routed to an IRQ signal. The IRQ signal is programmable via the INTSEL register (Offset 38h, described in Table 4-2 "Multiplexing, Interrupt Selection, and Base Address Registers" on page 88). The WATCHDOG interrupt is a shareable, active low, level interrupt.

WATCHDOG SMI

The WATCHDOG SMI is recognized by the Core Logic module as internal input signal EXT_SMI0#. To use the WATCHDOG SMI, Core Logic registers must be configured appropriately.

4.3.2 **WATCHDOG Registers**

Table 4-3 describes the WATCHDOG registers.

4.3.2.1 **Usage Hints**

- · SMM code should set bit 8 of the WDCNFG register to 1 when entering ACPI C3 state, if the WATCHDOG timer is to be suspended. If this is not done, the WATCHDOG timer is functional during C3 state.
- · SMM code should set bit 8 of the WDCNFG register to 1, when entering ACPI S1 and S2 states if the WATCHDOG timer is to be suspended. If this is not done, the WATCHDOG timer is functional during S1 and S2 states.

Table 4-3. WATCHDOG Registers

		10	ible 4-3. WATC	1DOO Registers		
Bit	Description					
Offset 00I This regist	-		CHDOG Timeout Re DOG timeout period.	gister - WDTO (R/W)	Reset Value: 0000h	
15:0	Programmed tin	neout period.				
		I to be generated	when the timer reach	egister - WDCNFG (R/W) es 0, whether or not to disable the	Reset Value: 0000h e 32 KHz input clock during low	
15:9	Reserved. Write as read.					
8	WD32KPD (WAT	CHDOG 32 KHz F	Power Down).			
	0: 32 KHz clock	is enabled.				
	1: 32 KHz clock	is disabled, when	the GX1 module ass	serts its internal SUSPA# signal.		
			is asserted or when 4.3.2.1 "Usage Hints	the GX1 module de-asserts its in on page 96.	ternal SUSPA# signal (i.e., on	
7:6	WDTYPE2 (WAT	CHDOG Event Ty	pe 2).			
	00: No action					
	01: Interrupt					
	10: SMI					
	11: System rese	t				
	This field is reset	to 0 when POR# i	s asserted. Other sys	stem resets do not affect this field	•	
5:4	WDTYPE1 (WAT	CHDOG Event Ty	pe 1).			
	00: No action					
	01: Interrupt					
	10: SMI					
	11: System rese					
				stem resets do not affect this field	•	
3:0	WDPRES (WATO	CHDOG Timer Pre	escaler). Divide 32 K	Hz by:		
	0000: 1	0100: 16	1000: 256	1100: 4096		
	0001: 2	0101: 32	1001: 512	1101: 8192		
	0010: 4	0110: 64	1010: 1024	1110: Reserved		
	0011: 8	0111: 128	1011: 2048	1111: Reserved		

General Configuration Block

Table 4-3. WATCHDOG Registers (Continued)

Bit	Description	
Offset 04h This registe	WATCHDOG Status Register - WDSTS (R/WC) er contains WATCHDOG status information.	Reset Value: 00h
7:4	Reserved. Write as read.	
3	WDRST (WATCHDOG Reset Asserted). (Read Only) This bit is set to 1 when WATCHDOG Re 0 when POR# is asserted, or when the WDOVF bit is set to 0.	set is asserted. It is set to
2	WDSMI (WATCHDOG SMI Asserted). (Read Only) This bit is set to 1 when WATCHDOG SMI is when POR# is asserted, or when the WDOVF bit is set to 0.	s asserted. It is set to 0
1	WDINT (WATCHDOG Interrupt Asserted. (Read Only) This bit is set to 1 when the WATCHDO is set to 0 when POR# is asserted, or when the WDOVF bit is set to 0.	G Interrupt is asserted. It
0	WDOVF (WATCHDOG Overflow) . This bit is set to 1 when the WATCHDOG Timer reaches 0. It asserted, or when a 1 is written to this bit by software. Other system reset sources do not affect to	
Offset 05h	-07h Reserved - RSVD	

4.4 **High-Resolution Timer**

The SC3200 provides an accurate time value that can be used as a time stamp by system software. This time is called the High-Resolution Timer. The length of the timer value can be extended via software. It is normally enabled while the system is in the C0 and C1 states. Optionally, software can be programmed to enable use of the High-Resolution Timer during C3 state and/or S1 state as well. In all other power states the High-Resolution Timer is disabled.

4.4.1 **Functional Description**

The High-Resolution Timer is a 32-bit free-running countup timer that uses the oscillator clock or the oscillator clock divided by 27. Bit TMCLKSEL of the TMCNFG register (Offset 0Dh[1]) can be set via software to determine which clock should be used for the High-Resolution Timer.

When the most significant bit (bit 31) of the timer changes from 1 to 0, bit TMSTS of the TMSTS register (Offset 0Ch[0]) is set to 1. When both bit TMSTS and bit TMEN (Offset 0Dh[0]) are 1, an interrupt is asserted. Otherwise, the interrupt is de-asserted. This interrupt enables software emulation of a larger timer.

The High-Resolution Timer interrupt is routed to an IRQ signal. The IRQ signal is programmable via the INTSEL register (Offset 38h). For more information about this register, see section Section 4.2 "Multiplexing, Interrupt Selection, and Base Address Registers" on page 88.

System software uses the read-only TMVALUE register (Offset 08h[31:0]) to read the current value of the timer. The TMVALUE register has no default value.

The input clock (derived from the 27 MHz crystal oscillator) is enabled when:

The GX1 module's internal SUSPA# signal is 1.

or

• The GX1 module's internal SUSPA# signal is 0 and bit TM27MPD (Offset 0Dh[2]) is 0.

The input clock is disabled, when the GX1 module's internal SUSPA# signal is 0 and the TM27MPD bit is 1.

For more information about signal SUSPA# see Section 4.4.2.1 "Usage Hints" on page 97 and the AMD Geode™ GX1 Processor Data Book.

The High-Resolution Timer function resides on the internal Fast-PCI bus and its registers are in General Configuration Block address space. Only one complete register should be accessed at-a-time (e.g., DWORD access should be used for DWORD wide registers and byte access should be used for byte-wide registers).

4.4.2 **High-Resolution Timer Registers**

Table 4-4 on page 98 describes the registers for the High-Resolution Timer (TIMER).

4.4.2.1 **Usage Hints**

- · SMM code should set bit 2 of the TMCNFG register to 1 when entering ACPI C3 state if the High-Resolution Timer should be disabled. If this is not done, the High-Resolution Timer is functional during C3 state.
- SMM code should set bit 2 of the TMCNFG register to 1 when entering ACPI S1 state if the High-Resolution Timer should be disabled. If this is not done, the High-Resolution Timer is functional during S1 state.



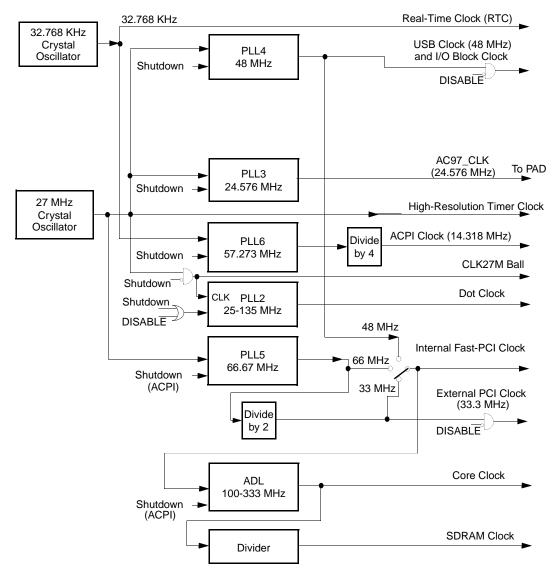
Table 4-4. High-Resolution Timer Registers

	Description	
Offset 08 This regis	Sh-0Bh TIMER Value Register - TMVALUE (RO) ster contains the current value of the High-Resolution Timer.	Reset Value: xxxxxxxxh
31:0	Current Timer Value.	
Offset 00 This regis	TIMER Status Register - TMSTS (R/W) ster supplies the High-Resolution Timer status information.	Reset Value: 00h
7:1	Reserved.	
0	TMSTS (TIMER Status). This bit is set to 1 when the most significant bit (bit 31) of the cleared to 0 upon system reset or when 1 is written by software to this bit.	timer changes from 1 to 0. It is
Offset 01 This regis power sta	ster enables the High-Resolution Timer interrupt; selects the Timer clock; and disables the	Reset Value: 00h e 27 MHz internal clock during low
	·	
7:3	Reserved.	
7:3 2	Reserved. TM27MPD (TIMER 27 MHz Power Down). This bit is cleared to 0 when POR# is asse asserts its internal SUSPA# signal (i.e., on SUSPA# rising edge). See Section 4.4.2.1 "	
	TM27MPD (TIMER 27 MHz Power Down). This bit is cleared to 0 when POR# is asse	
	TM27MPD (TIMER 27 MHz Power Down). This bit is cleared to 0 when POR# is asset asserts its internal SUSPA# signal (i.e., on SUSPA# rising edge). See Section 4.4.2.1 "	'Usage Hints" on page 97.
	TM27MPD (TIMER 27 MHz Power Down). This bit is cleared to 0 when POR# is asset asserts its internal SUSPA# signal (i.e., on SUSPA# rising edge). See Section 4.4.2.1 " 0: 27 MHz input clock is enabled.	'Usage Hints" on page 97.
2	TM27MPD (TIMER 27 MHz Power Down). This bit is cleared to 0 when POR# is asset asserts its internal SUSPA# signal (i.e., on SUSPA# rising edge). See Section 4.4.2.1 " 0: 27 MHz input clock is enabled. 1: 27 MHz input clock is disabled when the GX1 module asserts its internal SUSPA# signal (i.e., on SUSPA# rising edge). See Section 4.4.2.1 "	'Usage Hints" on page 97.
2	TM27MPD (TIMER 27 MHz Power Down). This bit is cleared to 0 when POR# is asset asserts its internal SUSPA# signal (i.e., on SUSPA# rising edge). See Section 4.4.2.1 " 0: 27 MHz input clock is enabled. 1: 27 MHz input clock is disabled when the GX1 module asserts its internal SUSPA# see TMCLKSEL (TIMER Clock Select).	'Usage Hints" on page 97.
2	TM27MPD (TIMER 27 MHz Power Down). This bit is cleared to 0 when POR# is assert asserts its internal SUSPA# signal (i.e., on SUSPA# rising edge). See Section 4.4.2.1 " 0: 27 MHz input clock is enabled. 1: 27 MHz input clock is disabled when the GX1 module asserts its internal SUSPA# see TMCLKSEL (TIMER Clock Select). 0: Count-up timer uses the oscillator clock divided by 27.	'Usage Hints" on page 97.
1	TM27MPD (TIMER 27 MHz Power Down). This bit is cleared to 0 when POR# is asserts asserts its internal SUSPA# signal (i.e., on SUSPA# rising edge). See Section 4.4.2.1 " 0: 27 MHz input clock is enabled. 1: 27 MHz input clock is disabled when the GX1 module asserts its internal SUSPA# s TMCLKSEL (TIMER Clock Select). 0: Count-up timer uses the oscillator clock divided by 27. 1: Count-up timer uses the oscillator clock, 27 MHz clock.	'Usage Hints" on page 97.
1	TM27MPD (TIMER 27 MHz Power Down). This bit is cleared to 0 when POR# is asse asserts its internal SUSPA# signal (i.e., on SUSPA# rising edge). See Section 4.4.2.1 " 0: 27 MHz input clock is enabled. 1: 27 MHz input clock is disabled when the GX1 module asserts its internal SUSPA# s TMCLKSEL (TIMER Clock Select). 0: Count-up timer uses the oscillator clock divided by 27. 1: Count-up timer uses the oscillator clock, 27 MHz clock. TMEN (TIMER Interrupt Enable).	'Usage Hints" on page 97.

4.5 Clock Generators and PLLs

General Configuration Block

This section describes the registers for the clocks required by the GX1 module, Core Logic module, and the Video Processor, and how these clocks are generated. See Figure 4-2 for a clock generation diagram. The clock generators are based on 32.768 KHz and 27.000 MHz crystal oscillators. The 32.768 KHz crystal oscillator is described in Section 5.5.2 "RTC Clock Generation" on page 121 (functional description of the RTC).



Note: V_{PLL2} powers PLL2 and PLL5. V_{PLL3} powers PLL3, PLL4, and PLL6.

Figure 4-2. Clock Generation Block Diagram

4.5.1 27 MHz Crystal Oscillator

The internal oscillator employs an external crystal connected to the on-chip amplifier. The on-chip amplifier is accessible on the X27I input and X27O output signals. See Figure 4-3 for the recommended external circuit and Table 4-5 for a list of the circuit components.

Choose C₁ and C₂ capacitors to match the crystal's load capacitance. The load capacitance C_L "seen" by crystal Y is comprised of C_1 in series with C_2 and in parallel with the parasitic capacitance of the circuit. The parasitic capacitance is caused by the chip package, board layout and socket (if any), and can vary from 0 to 10 pF. The rule of thumb in choosing these capacitors is:

$$C_L = (C_1 * C_2) / (C_1 + C_2) + C_{PARASITIC}$$

mple 1:

Crystal
$$C_L$$
 = 10 pF, $C_{PARASITIC}$ = 8.2 pF C_1 = 3.6 pF, C_2 = 3.6 pF

Example 2:

Crystal
$$C_L = 20 \text{ pF}$$
, $C_{PARASITIC} = 8 \text{ pF}$
 $C_1 = 24 \text{ pF}$, $C_2 = 24 \text{ pF}$

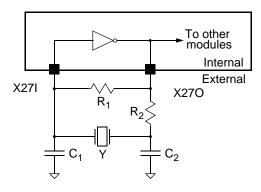


Figure 4-3. Recommended Oscillator External Circuitry

Table 4-5. Crystal Oscillator Circuit Components

Component	Parameters	Values	Tolerance
Crystal	Resonance Frequency	27.00 MHz Parallel mode	50 PPM or better
	Туре	AT-cut or BT-cut	
	Serial Resistance	40 Ω	Max
	Shunt Capacitance	7 pF	Max
	Load Capacitance, C _L	10-20 pF	
	Temperature Coefficient	User-defined	
Resistor R ₁	Resistance	20 ΜΩ	5%
Resistor R ₂ ¹	Resistance	100 Ω	5%
Capacitor C ₁ ¹	Capacitance	3-24 pF	5%
Capacitor C ₂ ¹	Capacitance	3-24 pF	5%

The value of these components is recommended. It should be tuned according to crystal and board parameters.

General Configuration Block Revision 5.1 AMD

4.5.2 GX1 Module Core Clock

The core clock is generated by an Analog Delay Loop (ADL) clock generator from the internal Fast-PCI clock. The clock can be any whole-number multiple of the input clock between 4 and 10. Possible values are listed in Table 4-6.

At power-on reset, the core clock multiplier value is set according to the value of four strapped balls - CLKSEL[3:0] (EBGA balls AL13, AK3, B27, F3 / TEPBGA balls P30, D29, AF3, B8). These balls also select the clock which is used as input to the multiplier, as shown in Table 4-7.

4.5.3 Internal Fast-PCI Clock

The internal Fast-PCI clock can be configured to 33, 48, or 66 MHz via strap options on the CLKSEL1 and CLKSEL0 balls. These can be read in the internal Fast-PCI Clock field in the CCFC register (GCB+I/O Offset 1Eh[9:8]). (See Table 4-8 on page 103 details on the CCFC register.)

Table 4-6. Core Clock Frequency

ADL	Internal Fast-PCI Clock Freq. (MHz)				
Multiplier Value	33.33	48	66.67		
4	133.3	192	266.7		
5	166.7	240			
6	200	288			
7	233.3				
8	266.7				
9					
10					

Table 4-7. Strapped Core Clock Frequency

	Default ADL Multiplier			
CLKSEL[3:0] Straps	Freq. (MHz) (GCB+I/O Offset 1Eh[9:8])	Multiply By	Multiplier Value (GCB+I/O Offset 1Eh[3:0])	Maximum Core Clock Freq. (MHz)
0111	33.33	4	0100	133
1011		5	0101	167
1111		6	0110	200
0000		7	0111	233
0100		8	1000	266
1000		9	1001	Reserved
1100		10	1010	Reserved
0001	48	4	0100	192
0101		5	0101	240
1001		6	0110	288
1101		7	0111	Reserved
0110	66.67	4	0100	266
1010		5	0101	Reserved

Note: Not all speeds are supported. For information on supported speeds, see Section A.1 "Order Information" on page 443.

4.5.4 SuperI/O Clocks

The SuperI/O module requires a 48 MHz input for Fast infrared (FIR), UART, and other functions. This clock is supplied by PLL4 using a multiplier value of 576/(108x3) to generate 48 MHz.

4.5.5 Core Logic Module Clocks

The Core Logic module requires the following clock sources:

Real-Time Clock (RTC)

RTC requires a 32.768 KHz clock which is supplied directly from an internal low-power crystal oscillator. This oscillator uses battery power and has very low current consumption.

USB

The USB requires a 48 MHz input which is supplied by PLL4. The required total frequency accuracy and slow jitter for USB is 500 PPM; edge to edge jitter is $\pm 1.2\%$.

ACPI

The ACPI logic block uses a 14.32 MHz clock supplied by PLL6. PLL6 creates this clock from the 32.768 KHz clock, with a multiplier value of 6992/4 to output a 57.278 MHz clock that is divided by 4.

External PCI

The PCI Interface uses a 33.3 MHz clock that is created by PLL5 and divided by 2. PLL5 uses the 27 MHz clock, to output a 66.67 MHz clock. PLL5 has a frequency accuracy of \pm 0.1%.

AC97

The SC3200 generates the 24.576 MHz clock required by the audio codec. Therefore, no crystal need be included for the audio codec on the system board.

PLL3 uses the crystal oscillator clock, to generate a 24.576 MHz clock. This clock is driven on the AC97_CLK ball. The accuracy of the clock supplied by the SC3200 is 50 PPM.

4.5.6 Video Processor Clocks

The Video processor requires the following clock sources:

Dot

The Dot clock is generated by PLL2. It is supplied to the Display Controller in the GX1 module (DCLK) that creates the pixel information, and is returned to the Graphics block (PCLK) with this information. PLL2 uses the 27 MHz clock to generate the Dot clock.

Video

The Video clock source depends on the source of the video data.

- If the video data is coming from the GX1 module (Capture Video mode), the video clock is generated by the Display Controller.
- If the video data is coming directly from the VIP block (Direct Video mode), the Video Clock is generated by the VIP block.



4.5.7 Clock Registers

Table 4-8 describes the registers of the clock generator and PLL.

Table 4-8. Clock Generator Configuration

Bit	Description	
•	Maximum Core Clock Multiplier Register - MCCM (RO) Reserved to the maximum core clock multiplier value. The maximum clock frequency allowed by the by this value.	set Value: Strapped Value core, is the Fast-PCI clock
7:4	Reserved.	
3:0	MCM (Maximum Clock Multiplier). This 4-bit value is the maximum multiplier value allowed for is derived from strap pins CLKSEL[3:0] based on the multiplier value in Table 4-7 on page 101	
Offset 11h	Reserved - RSVD	
Offset 12h This registe	PLL Power Control Register - PPCR (R/W) er controls operation of the PLLs.	Reset Value: 2Fh
7	Reserved.	
6	EXPCID (Disable External PCI Clock).	
	0: External PCI clock is enabled.	
	1: External PCI clock is disabled.	
5	GPD (Disable Graphic Pixel Reference Clock).	
-	0: PLL2 input clock is enabled.	
	1: PLL2 input clock is disabled.	
4	Reserved.	
3	PLL3SD (Shut Down PLL3). AC97 codec clock.	
	0: PLL3 is enabled.	
	1: PLL3 is shutdown.	
2	FM1SD (Shut Down PLL4).	
	0: PLL4 is enabled.	
	1: PLL4 is shutdown, unless internal Fast-PCI clock is strapped to 48 MHz.	
1	C48MD (Disable SuperI/O and USB Clock).	
	0: USB and SuperI/O clock is enabled.	
	1: USB and SuperI/O clock is disabled.	
0	Reserved. Write as read.	
Offset 13h	-17h Reserved - RSVD	
Offset 18h	-1Bh PLL3 Configuration Register - PLL3C (R/W)	Reset Value: E1040005h
31:24	MFFC (MFF Counter Value).	
	Fvco = OSCCLK * MFBC / (MFFC * MOC) OSCCLK = 27 MHz	
23:19	Reserved. Write as read.	
18:8	MFBC (MFB Counter Value).	
	Fvco = OSCCLK * MFBC / (MFFC * MOC) OSCCLK = 27 MHz	
	Note: Bits 18, 9, and 8 cannot be changed. Bit 18 is always a 1; bits 9 and 8 are always 0.	
7	Reserved. Write as read.	
6	Reserved. Must be set to 0.	
5:0	MOC (MO Counter Value).	
	Fvco = OSCCLK * MFBC / (MFFC * MOC) OSCCLK = 27 MHz	



Table 4-8. Clock Generator Configuration (Continued)

Bit	Description				
Offset 1E This regis	h-1Fh Core Clock Frequency Control Register - CCFC (R/W) Reset Value: Strapped Value er controls the configuration of the core clock multiplier and the reference clocks.				
15:14	Reserved.				
13	Reserved. Must be set to 0.				
12	Reserved. Must be set to 0.				
11:10	Reserved.				
9:8	FPCICK (Internal Fast-PCI Clock). (Read Only) Reflects the internal Fast-PCI clock and is the input to the GX1 module that is used to generate the core clock. These bits reflect the value of strap pins CLKSEL[1:0].				
	00: 33.3 MHz				
	01: 48 MHz				
	10: 66.7 MHz				
	11: 33.3 MHz				
7:4	Reserved.				
3:0	MVAL (Multiplier Value). This 4-bit value controls the multiplier in ADL. The value is set according to the Maximum Clock Multiplier bits of the MCCM register (Offset 10h). The multiplier value should never be written with a multiplier which is different from the multiplier indicated in the MCCM register.				
	0100: Multiply by 4				
	0101: Multiply by 5				
	0110: Multiply by 6				
	0111: Multiply by 7				
	1000: Multiply by 8				
	1001: Multiply by 9				
	1010: Multiply by 10				
	Other: Reserved				

SuperI/O Module Revision 5.1

SuperI/O Module

The SuperI/O (SIO) module is a PC98 and ACPI compliant SIO that offers a single-cell solution to the most commonly used ISA peripherals.

The SIO module incorporates: two Serial Ports, an Infrared Communication Port that supports FIR, MIR, HP-SIR, Sharp-IR, and Consumer Electronics-IR, a full IEEE 1284 Parallel Port, two ACCESS.bus Interface (ACB) ports, System Wakeup Control (SWC), and a Real-Time Clock (RTC) that provides RTC timekeeping.

Outstanding Features

- Full compatibility with ACPI Revision 1.0 requirements.
- System Wakeup Control powered by V_{SB}, generates power-up request and a PME (power management event) in response to SDATA_IN2 (an audio codec), IRRX1 (a pre-programmed CEIR), or a RI2# (serial port ring indicate) event.
- Advanced RTC, Y2K compliant.

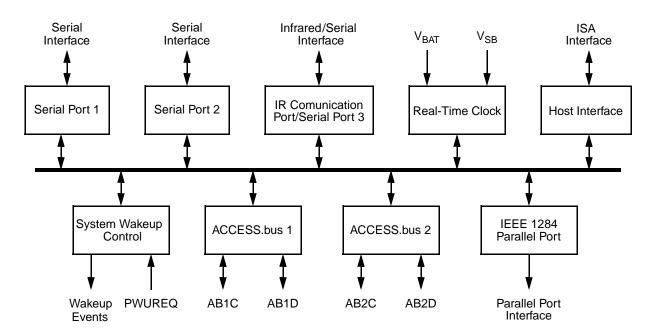


Figure 5-1. SIO Block Diagram

5.1 Features

PC98 and ACPI Compliant

- PnP Configuration Register structure
- · Flexible resource allocation for all logical devices:
 - Relocatable base address
 - 9 Parallel IRQ routing options
 - 3 optional 8-bit DMA channels (where applicable)

Parallel Port

- · Software or hardware control
- Enhanced Parallel Port (EPP) compatible with version EPP 1.9 and IEEE 1284 compliant
- EPP support for version EPP 1.7 of the Xircom specification
- EPP support as mode 4 of the Extended Capabilities Port (ECP)
- IEEE 1284 compliant ECP, including level 2
- Selection of internal pull-up or pull-down resistor for Paper End (PE) pin
- PCI bus utilization reduction by supporting a demand DMA mode mechanism and a DMA fairness mechanism
- Protection circuit that prevents damage to the parallel port when a printer connected to it powers up or is operated at high voltages, even if the device is in powerdown
- · Output buffers that can sink and source 14 mA

Serial Port 1

16550A compatible (SIN1, SOUT1, DTR1#/BOUT1 signals only)

Serial Port 2

• 16550A compatible

Serial Port 3 / Infrared (IR) Communication Port

- Serial Port 3
 - SIN and SOUT signals only
 - Data rate of up to 1.5-Mbps
 - Software compatible with the 16550A and the 16450
 - Shadow register support for write-only bit monitoring
 - DMA support
- IR Communication Port
 - IrDA 1.1 and 1.0 compatible
 - Data rate of up to 115.2 Kbps (HP-SIR)
 - Data rate of 1.152 Mbps (MIR)
 - Data rate of 4.0 Mbps (FIR)
 - Selectable internal or external modulation/demodulation (ASK-IR and DASK-IR options of SHARP-IR)
 - Consumer-IR (TV-Remote) mode
 - Consumer Remote Control supports RC-5, RC-6, NEC, RCA and RECS 80
 - DMA support

System Wakeup Control (SWC)

- Power-up request upon detection of RI2#, CEIR, or SDATA_IN2 activity:
 - Optional routing of power-up request on IRQ line
- Pre-programmed CEIR address in a pre-selected standard (any NEC, RCA or RC-5)
- Powered by V_{SB}
- Battery-backed wakeup setup
- Power-fail recovery support

Real-Time Clock

- A modifiable address that is referenced by a 16-bit programmable register
- DS1287, MC146818 and PC87911 compatibility
- 242 bytes of battery backed up CMOS RAM in two banks
- Selective lock mechanisms for the CMOS RAM
- Battery backed up century calendar in days, day of the week, date of month, months, years and century, with automatic leap-year adjustment
- Battery backed-up time of day in seconds, minutes and hours that allows a 12 or 24 hour format and adjustments for daylight savings time
- · BCD or binary format for time keeping
- Three different maskable interrupt flags:
 - Periodic interrupts At intervals from 122 ms to 500 ms
 - Time-of-Month alarm At intervals from once per second to once per month
 - Update Ended Interrupt Once per second upon completion of update
- Separate battery pin, 3.0V operation that includes an internal UL protection resistor
- 7 μA typical power consumption during power down
- Double-buffer time registers
- Y2K Compliant

Clock Sources

- 48 MHz clock input
- On-chip low frequency clock generator for wakeup
- 32.768 KHz crystal with an internal frequency multiplier to generate all required internal frequencies

SuperI/O Module Revision 5.1

5.2 **Module Architecture**

The SIO module comprises a collection of generic functional blocks. Each functional block is described in detail later in this chapter. The beginning of this chapter describes the SIO structure and provides all device specific information, including special implementation of generic blocks, system interface and device configuration.

The SIO module is based on eight logical devices, the host interface, and a central configuration register set, all built around a central, internal 8-bit bus.

The host interface serves as a bridge between the external ISA interface and the internal bus. It supports 8-bit I/O read, 8-bit I/O write and 8-bit DMA transactions, as defined in Personal Computer Bus Standard P996.

The central configuration register set supports ACPI compliant PnP configuration. The configuration registers are structured as a subset of the Plug and Play Standard Registers, defined in Appendix A of the Plug and Play ISA Specification Version 1.0a by Intel and Microsoft®. All system resources assigned to the functional blocks (I/O address space, DMA channels and IRQ lines) are configured in, and managed by, the central configuration register set. In addition, some function-specific parameters are configurable through this unit and distributed to the functional blocks through special control signals.

The source of the device internal clocks is the 48 MHz clock signal or through the 32.768 KHz crystal with an internal frequency multiplier. RTC operates on a 32 KHz clock.

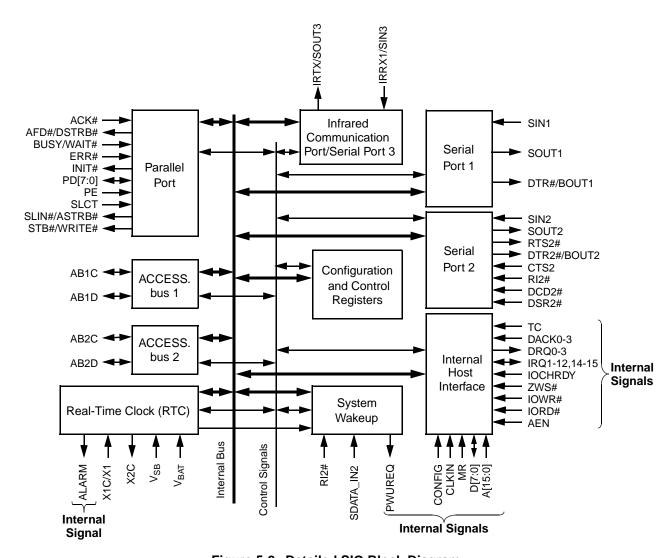


Figure 5-2. Detailed SIO Block Diagram

Revision 5.1 SuperI/O Module

5.3 Configuration Structure / Access

This section describes the structure of the configuration register file, and the method of accessing the configuration registers.

5.3.1 Index-Data Register Pair

The SIO configuration access is performed via an Index-Data register pair, using only two system I/O byte locations. The base address of this register pair is determined according to the state of the IO_SIOCFG_IN bit field of the Core Logic module (F5BAR0+I/O Offset 00h[26:25]). Table 5-1 shows the selected base addresses as a function of the IO_SIOCFG_IN bit field.

Table 5-1. SIO Configuration Options

	I/O Address		
IO_SIOCFG_IN Settings	Index Register	Data Register	Description
00	-	-	SIO disabled
01	-	-	Configuration access disabled
10	002Eh	002Fh	Base address 1 selected
11	015Ch	015Dh	Base address 2 selected

The Index Register is an 8-bit R/W register located at the selected base address (Base+0). It is used as a pointer to the configuration register file, and holds the index of the configuration register that is currently accessible via the Data Register. Reading the Index Register returns the last value written to it (or the default of 00h after reset).

The Data Register is an 8-bit virtual register, used as a data path to any configuration register. Accessing the data register results with physically accessing the configuration register that is currently pointed by the Index Register.

5.3.2 Banked Logical Device Registers

Each functional block is associated with a Logical Device Number (LDN). The configuration registers are grouped into banks, where each bank holds the standard configuration registers of the corresponding logical device. Table 5-2 shows the LDNs of the device functional blocks.

Table 5-2. LDN Assignments

LDN	Functional Block	Reference
00h	Real-Time Clock (RTC)	Page 114
01h	System Wakeup Control (SWC)	Page 116
02h	Infrared Communication Port (IRCP) or Serial Port 3 (SP3)	Page 117
03h	Serial Port 1 (SP1)	Page 118
05h	ACCESS.bus 1 (ACB1)	Page 119
06h	ACCESS.bus 2 (ACB2)	
07h	Parallel Port (PP)	Page 120
08h	Serial Port 2 (SP2)	Page 118

Figure 5-3 shows the structure of the standard PnP configuration register file. The SIO Control And Configuration registers are not banked and are accessed by the Index-Data register pair only (as described above). However, the Logical Device Control and Configuration registers are duplicated over eight banks for eight logical devices. Therefore, accessing a specific register in a specific bank is performed by two-dimensional indexing, where the LDN register selects the bank (or logical device), and the Index register selects the register within the bank. Accessing the Data register while the Index register holds a value of 30h or higher results in a physical access to the Logical Device Configuration registers currently pointed to by the Index register, within the logical device bank currently selected by the LDN register.

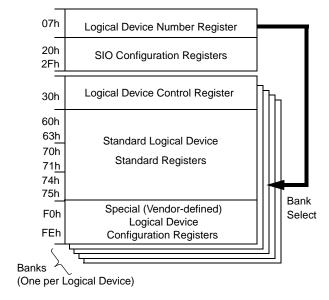


Figure 5-3. Structure of the Standard Configuration Register File

Write accesses to unimplemented registers (i.e., accessing the Data register while the Index register points to a non-existing register or the LDN is 07h or higher than 08h), are ignored and a read returns 00h on all addresses except for 74h and 75h (DMA configuration registers) which returns 04h (indicating no DMA channel is active). The configuration registers are accessible immediately after reset.

5.3.3 Default Configuration Setup

The device has four reset types:

Software Reset

This reset is generated by bit 1 of the SIOCF1 register, which resets all logical devices. A software reset also resets most bits in the SIO Configuration and Control registers (see Section 5.4.1 on page 113 for the bits not affected). This reset does not affect register bits that are locked for write access.

Hardware Reset

This reset is activated by the system reset signal. This resets all logical devices, with the exception of the RTC and the SWC, and all SIO Configuration and Control registers, with the exception of the SIOCF2 register. It also resets all SuperI/O control and configuration registers, except for those that are battery-backed.

VPP Power-Up Reset

This reset is activated when either V_{SB} or V_{BAT} is powered on after both have been off. V_{PP} is an internal voltage which is a combination of V_{SB} and V_{BAT} . V_{PP} is taken from V_{SB} if V_{SB} is greater than the minimum (Min) value defined in Section 9.1.4 "Operating Conditions" on page 370; otherwise, V_{BAT} is used as the V_{PP} source. This reset resets all registers whose values are retained by V_{PP}

V_{SR} Power-Up Reset

This is an internally generated reset that resets the SWC, excluding those SWC registers whose values are retained by V_{PP} This reset is activated after V_{SB} is powered up.

The SIO module wakes up with the default setup, as follows:

- · When a hardware reset occurs:
 - The configuration base address is 2Eh, 15Ch or None, according to the IO_SIOCFG_IN bit values, as shown in Table 5-1 on page 108.
 - All Logical devices are disabled, with the exception of the RTC and the SWC, which remains functional but whose registers cannot be accessed.
- When either a hardware or a software reset occurs:
 - The legacy devices are assigned with their legacy system resource allocation.
 - The AMD proprietary functions are not assigned with any default resources and the default values of their base addresses are all 00h.

5.3.4 Address Decoding

A full 16-bit address decoding is applied when accessing the configuration I/O space, as well as the registers of the functional blocks. However, the number of configurable bits in the base address registers vary for each device.

The lower 1, 2, 3 or 4 address bits are decoded within the functional block to determine the offset of the accessed register, within the device's I/O range of 2, 4, 8 or 16 bytes, respectively. The rest of the bits are matched with the base address register to decode the entire I/O range allocated to the device. Therefore the lower bits of the base address register are forced to 0 (RO), and the base address is forced to be 2, 4, 8 or 16 byte aligned, according to the size of the I/O range.

The base address of the RTC, Serial Port 1, Serial Port 2, and the Infrared Communication Port are limited to the I/O address range of 00h to 7Fxh only (bits [15:11] are forced to 0). The Parallel Port base address is limited to the I/O address range of 00h to 3F8h. The addresses of the non-legacy devices are configurable within the full 16-bit address range (up to FFFxh).

In some special cases, other address bits are used for internal decoding (such as 10 in the Parallel Port). For more details, please see the detailed description of the base address register for each specific logical device.

5.4 Standard Configuration Registers

As illustrated in Figure 5-4, the Standard Configuration registers are broadly divided into two categories: SIO Control and Configuration registers and Logical Device Control and Configuration registers (one per logical device, some are optional).

SIO Control and Configuration Registers

The only PnP control register in the SIO module is the Logical Device Number register at Index 07h. All other standard PnP control registers are associated with PnP protocol for ISA add-in cards, and are not supported by the SIO module.

The SIO Configuration registers at Index 20h-27h are mainly used for part identification. (See Section 5.4.1 "SIO Control and Configuration Registers" on page 113 for further details.)

Logical Device Control and Configuration Registers

A subset of these registers is implemented for each logical device. (See Table 5-2 on page 108 for LDN assignment and Section 5.4.2 "Logical Device Control and Configuration" on page 114 for register details.)

Logical Device Control Register (Index 30h): The only implemented Logical Device Control register is the Activate register at Index 30. Bit 0 of the Activate register and bit 0 of the SIO Configuration 1 register (Global Device Enable bit) control the activation of the associated function block

(except for the RTC and the SWC). Activation of the block enables access to the block's registers, and attaches its system resources, which are unused as long as the block is not activated. Activation of the block may also result in other effects (e.g., clock enable and active signaling), for certain functions.

Standard Logical Device Configuration Registers (Index 60h-75h): These registers are used to manage the resource allocation to the functional blocks. The I/O port base address descriptor 0 is a pair of registers at Index 60h-61h, holding the (first or only) 16-bit base address for the register set of the functional block. An optional second base-address (descriptor 1) at Index 62h-63h is used for devices with more than one continuous register set. Interrupt Number Select (Index 70h) and Interrupt Type Select (Index 71h) allocate an IRQ line to the block and control its type. DMA Channel Select 0 (Index 74h) allocates a DMA channel to the block, where applicable. DMA Channel, where applicable.

Special Logical Device Configuration Registers (F0h-F3h): The vendor-defined registers, starting at Index F0h are used to control function-specific parameters such as operation modes, power saving modes, pin TRI-STATE, clock rate selection, and non-standard extensions to generic functions.

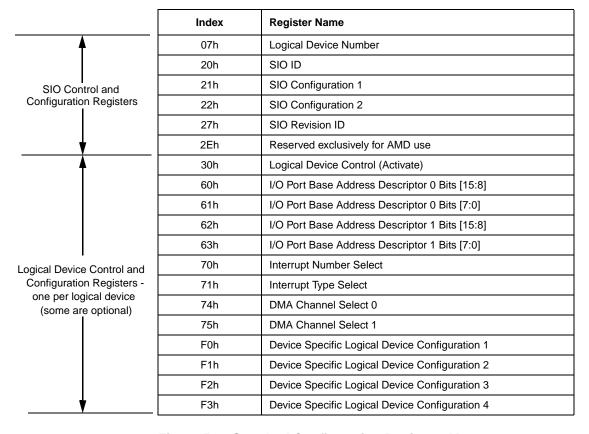


Figure 5-4. Standard Configuration Registers Map

Table 5-3 provides the bit definitions for the Standard Conwrite to prevent the values of reserved bits from being

 All reserved bits return 0 on reads, except where noted otherwise. They must not be modified as such modification may cause unpredictable results. Use read-modify-

figuration registers.

- write to prevent the values of reserved bits from being changed during write.
- Write only registers should not use read-modify-write during updates.

Table 5-3. Standard Configuration Registers

Bit	Description				
Index 07h	Index 07h Logical Device Number (R/W)				
This regist	er selects the current logical device. See Table 5-2 for valid numbers. All other values are reserved.				
7:0	Logical Device number.				
Index 20h	2Fh SIO Configuration (R/W)				
SIO config	uration and ID registers. See Section 5.4.1 "SIO Control and Configuration Registers" on page 113 for register/bit details.				
Index 30h	Activate (R/W)				
7:1	Reserved.				
0	Logical Device Activation Control.				
	0: Disable				
	1: Enable				
Index 60h	I/O Port Base Address Bits [15:8] Descriptor 0 (R/W)				
7:0	Descriptor 0 A[15:8]. Selects I/O lower limit address bits [15:8] for I/O Descriptor 0.				
Index 61h	I/O Port Base Address Bits [7:0] Descriptor 0 (R/W)				
7:0	Descriptor 0 A[7:0]. Selects I/O lower limit address bits [7:0] for I/O Descriptor 0.				
Index 62h	I/O Port Base Address Bits [15:8] Descriptor 1 (R/W)				
7:0	Descriptor 1 A[15:8]. Selects I/O lower limit address bits [15:8] for I/O Descriptor 1.				
Index 63h	I/O Port Base Address Bits [7:0] Descriptor 1 (R/W)				
7:0	Descriptor 1 A[7:0]. Selects I/O lower limit address bits [7:0] for I/O Descriptor 1.				
Index 70h	Interrupt Number (R/W)				
7:4	Reserved.				
3:0	Interrupt Number. These bits select the interrupt number. A value of 1 selects IRQ1, a value of 2 selects IRQ2, etc. (up to IRQ12).				
	Note: IRQ0 is not a valid interrupt selection.				
Index 71h	Interrupt Request Type Select (R/W)				
Selects the	type and level of the interrupt request number selected in the previous register.				
7:2	Reserved.				
1	Interrupt Level Requested. Level of interrupt request selected in previous register.				
	0: Low polarity.				
	1: High polarity.				
	This bit must be set to 1 (high polarity), except for IRQ8#, that must be low polarity.				
0	Interrupt Type Requested. Type of interrupt request selected in previous register.				
	0: Edge.				
	1: Level.				
Index 74h	DMA Channel Select 0 (R/W)				
Selects sel	ected DMA channel for DMA 0 of the logical device (0 - the first DMA channel in case of using more than one DMA channel).				
7:3	Reserved.				
2:0	DMA 0 Channel Select. This bit field selects the DMA channel for DMA 0.				
	The valid choices are 0-3, where a value of 0 selects DMA channel 0, 1 selects channel 1, etc.				
	A value of 4 indicates that no DMA channel is active.				
	Values 5-7 are reserved.				

Table 5-3. Standard Configuration Registers (Continued)

Bit	Description			
Index 75h Indicates s channel).	DMA Channel Select 1 (R/W) elected DMA channel for DMA 1 of the logical device (1 - the second DMA channel in case of using more than one DMA			
7:3	Reserved.			
2:0	DMA 1 Channel Select: This bit field selects the DMA channel for DMA 1.			
	The valid choices are 0-3, where a value of 0 selects DMA channel 0, 1 selects channel 1, etc.			
	A value of 4 indicates that no DMA channel is active.			
	Values 5-7 are reserved.			
Index F0h	-FEh Logical Device Configuration (R/W) endor-defined) configuration options.			

5.4.1 SIO Control and Configuration Registers

Table 5-4 lists the SIO Control and Configuration registers and Table 5-5 provides their bit formats.

Table 5-4. SIO Control and Configuration Register Map

Index	Туре	Name	Power Rail	Reset Value
20h	RO	SID. SIO ID	V _{CORE}	F5h
21h	R/W	SIOCF1. SIO Configuration 1	V_{CORE}	01h
22h	R/W	SIOCF2. SIO Configuration 2	V_{PP}	02h
27h	RO	SRID. SIO Revision ID	V _{CORE}	01h
2Eh		RSVD. Reserved exclusively for AMD use.		

Table 5-5. SIO Control and Configuration Registers

	Table 3-3. SIO Control and Configuration Registers			
Bit	Description			
Index 20h	SIO ID Register - SID (RO)	Reset Value: F5h		
7:0	Chip ID. Contains the identity number of the module. The SIO module is identified by the value F5h.			
Index 21h	1h SIO Configuration 1 Register - SIOCF1 (RW) Reset Valu			
7:6	General Purpose Scratch. When bit 5 is set to 1, these bits are RO. After reset, these bits can be read or write. Once changed to RO, the bits can be changed back to R/W only by a hardware reset.			
5	Lock Scratch. This bit controls bits 7 and 6 of this register. Once this bit is set to 1 by software, it can by a hardware reset.	n be cleared to 0 only		
	0: Bits 7 and 6 of this register are R/W bits. (Default)			
	1: Bits 7 and 6 of this register are RO bits.			
4:2	Reserved.			
1	SW Reset. Read always returns 0.			
	0: Ignored. (Default)			
	1: Resets all devices that are reset by MR (with the exception of the lock bits) and the registers of the	e SWC.		
0	Global Device Enable. This bit controls the function enable of all the logical devices in the SIO mode and the RTC. It allows them to be disabled simultaneously by writing to a single bit.	ule, except the SWC		
	0: All logical devices in the SIO module are disabled, except the SWC and the RTC.			
	1: Each logical device is enabled according to its Activate register at Index 30h. (Default)			
Index 22h Note: Th	SIO Configuration 2 Register - SIOCF2 (R/W) his register is reset only when V_{PP} is first applied.	Reset Value: 02h		
7	Reserved.			
6:4	General Purpose Scratch. Battery-backed.			
3:2	Reserved.			
1	Reserved.			
0	Reserved. (RO)			
Index 27h	SIO Revision ID Register - SRID (RO)	Reset Value: 01h		
7:0	SIO Revision ID. (RO) This RO register contains the identity number of the chip revision. SRID is including.	remented on each rev		

5.4.2 Logical Device Control and Configuration

As described in Section 5.3.2 "Banked Logical Device Registers" on page 108, each functional block is associated with a Logical Device Number (LDN). This section provides the register descriptions for each LDN.

The register descriptions in this subsection use the following abbreviations for Type:

• R/W = Read/Write

 R = Read from a specific address returns the value of a specific register. Write to the same address is to a different register.

W = WriteRO = Read Only

 R/W1C = Read/Write 1 to Clear. Writing 1 to a bit clears it to 0. Writing 0 has no effect.

5.4.2.1 LDN 00h - Real-Time Clock

Table 5-6 lists the registers which are relevant to configuration of the Real-Time Clock (RTC). Only the last registers (F0h-F3h) are described here (Table 5-7). See Table 5-3 "Standard Configuration Registers" on page 111 for descriptions of the other registers.

Table 5-6. Relevant RTC Configuration Registers

Index	Туре	Configuration Register or Action	Reset Value
30h	R/W	Activate. When bit 0 is cleared, the registers of this logical device are not accessible. ¹	00h
60h	R/W	Standard Base Address MSB register. Bits [7:3] (for A[15:11]) are RO, 00000b.	00h
61h	R/W	Standard Base Address LSB register. Bit 0 (for A0) is RO, 0b.	70h
62h	R/W	Extended Base Address MSB register. Bits [7:3] (for A[15:11]) are RO, 00000b.	00h
63h	R/W	Extended Base Address LSB register. Bit 0 (for A0) is RO, 0b.	72h
70h	R/W	Interrupt Number.	08h
71h	R/W	Interrupt Type. Bit 1 is R/W; other bits are RO.	00h
74h	RO	Report no DMA assignment.	04h
75h	RO	Report no DMA assignment.	
F0h	R/W	RAM Lock register (RLR).	
F1h	R/W	Date of Month Alarm Offset register (DOMAO). Sets index of Date of Month Alarm register in the standard base address.	
F2h	R/W	Month Alarm Offset register (MONAO). Sets index of Month Alarm register in the standard base address.	00h
F3h	R/W	Century Offset register (CENO). Sets index of Century register in the standard base address.	00h

^{1.} The logical device registers are maintained, and all RTC mechanisms are functional.



Table 5-7. RTC Configuration Registers

Bit	Description			
Index F0h	ndex F0h RAM Lock Register - RLR (R/W)			
When any	non-reserved bit in this register is set to 1, it can be cleared only by hardware reset.			
7	Block Standard RAM.			
	0: No effect on Standard RAM access. (Default)			
	1: Read and write to locations 38h-3Fh of the Standard RAM are blocked, writes ignored, and reads return FFh.			
6	Block RAM Write.			
	0: No effect on RAM access. (Default)			
	1: Writes to RAM (Standard and Extended) are ignored.			
5	Block Extended RAM Write. This bit controls writes to bytes 00h-1Fh of the Extended RAM.			
	0: No effect on the Extended RAM access. (Default)			
	1: Writes to bytes 00h-1Fh of the Extended RAM are ignored.			
4	Block Extended RAM Read. This bit controls read from bytes 00h-1Fh of the Extended RAM.			
	0: No effect on Extended RAM access. (Default)			
	1: Reads to bytes 00h-1Fh of the Extended RAM are ignored.			
3	Block Extended RAM. This bit controls access to the Extended RAM 128 bytes.			
	0: No effect on Extended RAM access. (Default)			
	1: Read and write to the Extended RAM are blocked: writes are ignored and reads return FFh.			
2:0	Reserved.			
Index F1h	Date Of Month Alarm Register Offset Register - DOMAO (R/W)			
7	Reserved.			
6:0	Date of Month Alarm Register Offset Value.			
Index F2h	Month Alarm Register Offset Register - MANAO (R/W)			
7	Reserved.			
6:0	Month Alarm Register Offset Value.			
Index F3h	Century Register Offset Register - CENO (R/W)			
7	Reserved.			
6:0	Century Register Offset Value.			

5.4.2.2 LDN 01h - System Wakeup Control

Table 5-8 lists registers that are relevant to the configuration of System Wakeup Control (SWC). These registers are

described earlier in Table 5-3 "Standard Configuration Registers" on page 111.

Table 5-8. Relevant SWC Registers

Index	Туре	Configuration Register or Action	Reset Value
30h	R/W	Activate. When bit 0 is cleared, the registers of this logical device are not accessible. ¹	00h
60h	R/W	Base Address MSB register.	00h
61h	R/W	Base Address LSB register. Bits [3:0] (for A[3:0]) are RO, 0000b.	00h
70h	R/W	Interrupt Number. (For routing the internal PWUREQ signal.)	00h
71h	R/W	Interrupt Type. Bit 1 is R/W. Other bits are RO.	03h
74h	RO	Report no DMA assignment.	04h
75h	RO	Report no DMA assignment.	04h

^{1.} The logical device registers are maintained, and all wakeup detection mechanisms are functional.

5.4.2.3 LDN 02h - Infrared Communication Port or Serial Port 3

Table 5-9 lists the configuration registers which affect the Infrared Communication Port or Serial Port 3 (IRCP/SP3).

Only the last register (F0h) is described here (Table 5-10). See Table 5-3 "Standard Configuration Registers" on page 111 for descriptions of the other registers listed.

Table 5-9. Relevant IRCP/SP3 Registers

Index	Туре	Configuration Register or Action	Reset Value
30h	R/W	Activate. See also bit 0 of the SIOCF1 register.	00h
60h	R/W	Base Address MSB register. Bits [7:3] (for A[15:11]) are RO, 00000b.	03h
61h	R/W	Base Address LSB register. Bit [2:0] (for A[2:0]) are RO, 000b.	E8h
70h	R/W	Interrupt Number.	00h
71h	R/W	Interrupt Type. Bit 1 is R/W; other bits are RO.	03h
74h	R/W	DMA Channel Select 0 (RX_DMA).	04h
75h	R/W	DMA Channel Select 1 (TX_DMA).	04h
F0h	R/W	Infrared Communication Port/Serial Port 3 Configuration register.	02h

Table 5-10. IRCP/SP3 Configuration Register

Bit	Description			
Index F0h	Infrared Communication Port/Serial Port 3 Configuration Register (R/W) Reset Value: 02h			
7	Bank Select Enable. Enables bank switching.			
	0: All attempts to access the extended registers are ignored. (Default)			
	1: Enables bank switching.			
6:3	Reserved.			
2	Busy Indicator. (RO) This bit can be used by power management software to decide when to power-down the device.			
	0: No transfer in progress. (Default)			
	1: Transfer in progress.			
1	Power Mode Control. When the logical device is active in:			
	Low power mode - Clock disabled. The output signals are set to their default states. Registers are maintained. (Unlike Active bit in Index 30h that also prevents access to device registers.)			
	1: Normal power mode - Clock enabled. The device is functional when the logical device is active. (Default)			
0	TRI-STATE Control . When enabled and the device is inactive, the logical device output pins are in TRI-STATE. One exception is the IRTX/SOUT3 pin, which is driven to 0 when the Infrared Communication Port or Serial Port 3 is inactive and is not affected by this bit.			
	0: Disabled. (Default)			
	1: Enabled (when the device is inactive).			

5.4.2.4 LDN 03h and 08h - Serial Ports 1 and 2

Serial Ports 1 and 2 are identical, except for their reset values.

Serial Port 1 is designated as LDN 03h and Serial Port 2 as LDN 08h. Table 5-11 lists the configuration registers which

affect Serial Ports 1 and 2. Only the last register (F0h) is described here (Table 5-12). See Table 5-3 "Standard Configuration Registers" on page 111 for descriptions of the others.

Table 5-11. Relevant Serial Ports 1 and 2 Registers

			Reset Value	
Index	Туре	Configuration Register or Action	Port 1	Port 2
30h	R/W	Activate. See also bit 0 of the SIOCF1 register.	00h	00h
60h	R/W	Base Address MSB register. Bits [7:3] (for A[15:11]) are RO, 00000b.	03h	02h
61h	R/W	Base Address LSB register. Bit [2:0] (for A[2:0]) are RO, 000b.	F8h	F8h
70h	R/W	Interrupt Number.	04h	03h
71h	R/W	Interrupt Type. Bit 1 is R/W; other bits are RO.	03h	03h
74h	RO	Report no DMA assignment.	04h	04h
75h	RO	Report no DMA assignment.	04h	04h
F0h	R/W	Serial Ports 1 and 2 Configuration register.	02h	02h

Table 5-12. Serial Ports 1 and 2 Configuration Register

Bit	Description
Index F0h	Serial Ports 1 and 2 Configuration Register (R/W) Reset Value: 02h
7	Bank Select Enable. Enables bank switching for Serial Ports 1 and 2.
	0: Disabled. (Default)
	1: Enabled.
6:3	Reserved.
2	Busy Indicator. (RO) This bit can be used by power management software to decide when to power-down Serial Ports 1 and 2 logical devices.
	0: No transfer in progress. (Default)
	1: Transfer in progress.
1	Power Mode Control. When the logical device is active in:
	0: Low power mode - Serial Ports 1 and 2 Clock disabled. The output signals are set to their default states. Registers are maintained. (Unlike Active bit in Index 30h that also prevents access to Serial Ports 1 or 2 registers.)
	1: Normal power mode - Serial Ports 1 and 2 clock enabled. Serial Ports 1 and 2 are functional when the respective logical devices are active. (Default)
0	TRI-STATE Control. This bit controls the TRI-STATE status of the device output pins when it is inactive (disabled).
	0: Disabled. (Default)
	1: Enabled when device inactive.

5.4.2.5 LDN 05h and 06h - ACCESS.bus Ports 1 and 2

ACCESS.bus ports 1 and 2 (ACB1 and ACB2) are identical. Each ACB is a two-wire synchronous serial interface compatible with the ACCESS.bus physical layer. ACB1 and ACB2 use a 24 MHz internal clock. Six runtime registers for each ACCESS.bus are described in Section 5.7 "ACCESS.bus Interface" on page 137.

ACB1 is designated as LDN 05h and ACB2 as LDN 06h. Table 5-13 lists the configuration registers which affect the ACCESS.bus ports. Only the last register (F0h) is described here (Table 5-14). See Table 5-3 "Standard Configuration Registers" on page 111 for descriptions of the others.

Table 5-13. Relevant ACB1 and ACB2 Registers

Index	Туре	Configuration Register or Action	Reset Value
30h	R/W	Activate. See also bit 0 of the SIOCF1 register	00h
60h	R/W	Base Address MSB register.	00h
61h	R/W	Base Address LSB register. Bits [2:0] (for A[2:0]) are RO, 000b.	00h
70h	R/W	Interrupt Number.	00h
71h	R/W	Interrupt Type. Bit 1 is R/W. Other bits are RO.	03h
74h	RO	Report no DMA assignment.	04h
75h	RO	Report no DMA assignment.	04h
F0h	R/W	ACB1 and ACB2 Configuration register.	00h

Table 5-14. ACB1 and ACB2 Configuration Register

Bit	Description			
Index F0h This registe	Index F0h ACB1 and ACB2 Configuration Register (R/W) This register is reset by hardware to 00h.			
7:3	Reserved.			
2	Internal Pull-Up Enable.			
	0: No internal pull-up resistors on AB1C/AB2C and AB1D/AB2D. (Default)			
	1: Internal pull-up resistors on AB1C/AB2C and AB1D/AB2D.			
1:0	Reserved.			



5.4.2.6 LDN 07h - Parallel Port

The Parallel Port supports all IEEE 1284 standard communication modes: Compatibility (known also as Standard or SPP), Bidirectional (known also as PS/2), FIFO, EPP (known also as Mode 4) and ECP (with an optional Extended ECP mode).

The Parallel Port includes two groups of runtime registers, as follows:

 A group of 21 registers at first level offset, sharing 14 entries. Three of these registers (at Offset 403h, 404h, and 405h) are used only in the Extended ECP mode. A group of four registers, used only in the Extended ECP mode, accessed by a second level offset.

The desired mode is selected by the ECR runtime register (Offset 402h). The selected mode determines which runtime registers are used and which address bits are used for the base address. (See Section 5.8.1 on page 145 for further details regarding the runtime registers.)

Table 5-15 lists the configuration registers which affect the Parallel Port. Only the last register (F0h) is described here (Table 5-16). See Table 5-3 "Standard Configuration Registers" on page 111 for descriptions of the others.

Table 5-15. Relevant Parallel Port Registers

Index	Туре	Configuration Register or Action	Reset Value
30h	R/W	Activate. See also bit 0 of the SIOCF1 register.	00h
60h	R/W	Base Address MSB register. Bits [7:3] (for A[15:11]) are RO, 00000b. Bit 2 (for A10) should be 0b.	02h
61h	R/W	Base Address LSB register. Bits 1 and 0 (A1 and A0) are RO, 00b. For ECP Mode 4 (EPP) or when using the Extended registers, bit 2 (A2) should also be 0b.	78h
70h	R/W	Interrupt Number.	07h
71h	R/W	Interrupt Type.	02h
		Bits [7:2] are RO.	
		Bit 1 is R/W.	
		Bit 0 is RO. It reflects the interrupt type dictated by the Parallel Port operation mode. This bit is set to 1 (level interrupt) in Extended Mode and cleared (edge interrupt) in all other modes.	
74h	R/W	DMA Channel Select.	04h
75h	RO	Report no second DMA assignment.	04h
F0h	R/W	Parallel Port Configuration register. (See Table 5-16.)	F2h

Table 5-16. Parallel Port Configuration Register

Bit	Description
Index F0h	3 (. ,
This registe	er is reset by hardware to F2h.
7:5	Reserved. Must be 11.
4	Extended Register Access.
	0: Registers at base (address)+403h, base+404h and base+405h are not accessible (reads and writes are ignored).
	1: Registers at base (address)+403h, base+404h and base+405h are accessible. This option supports run-time configuration within the Parallel Port address space.
3:2	Reserved.
1	Power Mode Control. When the logical device is active:
	0: Parallel port clock disabled. ECP modes and EPP timeout are not functional when the logical device is active. Registers are maintained.
	1: Parallel port clock enabled. All operation modes are functional when the logical device is active. (Default)
0	TRI-STATE Control. When enabled and the device is inactive, the logical device output pins are in TRI-STATE.
	0: Disable. (Default)
	1: Enable.

5.5 Real-Time Clock (RTC)

The RTC provides timekeeping and calendar management capabilities. The RTC uses a 32.768 KHz signal as the basic clock for timekeeping. It also includes 242 bytes of battery-backed RAM for general-purpose use.

The RTC provides the following functions:

- · Accurate timekeeping and calendar management
- · Alarm at a predetermined time and/or date
- · Three programmable interrupt sources
- Valid timekeeping during power-down, by utilizing external battery backup
- · 242 bytes of battery-backed RAM
- · RAM lock schemes to protect its content
- Internal oscillator circuit (the crystal itself is off-chip), or external clock supply for the 32.768 KHz clock
- · A century counter
- PnP support:
 - Relocatable Index and Data registers
 - Module access enable/disable option
 - Host interrupt enable/disable option
- Additional low-power features such as:
 - Automatic switching from battery to V_{SB}
 - Internal power monitoring on the VRT bit
 - Oscillator disabling to save battery during storage
- Software compatible with the DS1287 and MC146818

5.5.1 Bus Interface

The RTC function is initially mapped to the default SuperI/O locations at Indexes 70h to 73h (two Index/Data pairs). These locations may be reassigned, in compliance with Plug and Play requirements.

5.5.2 RTC Clock Generation

The RTC uses a 32.768 KHz clock signal as the basic clock for timekeeping. The 32.768 KHz clock can be supplied by the internal oscillator circuit, or by an external oscillator (see Section 5.5.2.2 "External Oscillator" on page 122).

5.5.2.1 Internal Oscillator

The internal oscillator employs an external crystal connected to the on-chip amplifier. The on-chip amplifier is accessible on the X32l input and X32O output. See Figure 5-5 for the recommended external circuit and Table 5-17 for a listing of the circuit components. The oscillator may be disabled in certain conditions. See Section 5.5.2.8 "Oscillator Activity" on page 125 for more details.

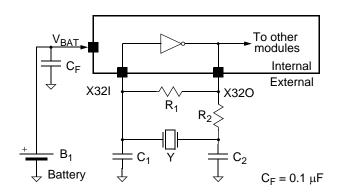


Figure 5-5. Recommended Oscillator External Circuitry

Table 5-17. Crystal Oscillator Circuit Components

Component	Parameters	Values	Tolerance
Crystal	Resonance Frequency	32.768 KHz Parallel mode	User-defined
	Туре	N-cut or XY-bar	
	Serial Resistance	40 ΚΩ	Max
	Quality Factor, Q	35000	Min
	Shunt Capacitance	2 pF	Max
	Load Capacitance, C _L	9-13 pF	
	Temperature Coefficient	User-defined	
Resistor R ₁	Resistance	20 ΜΩ	5%
Resistor R ₂	Resistance	120 ΚΩ	5%
Capacitor C ₁	Capacitance	3 to 10 pF	5%
Capacitor C ₂	Capacitance	3 to 10 pF	5%

External Elements

Choose C_1 and C_2 capacitors (see Figure 5-5 on page 121) to match the crystal's load capacitance. The load capacitance C_L "seen" by crystal Y is comprised of C₁ in series with C₂ and in parallel with the parasitic capacitance of the circuit. The parasitic capacitance is caused by the chip package, board layout and socket (if any), and can vary from 0 to 10 pF. The rule of thumb in choosing these capacitors is:

$$C_L = (C_1 * C_2) / (C_1 + C_2) + C_{PARASITIC}$$

Example:

Crystal
$$C_L$$
 = 10 pF, $C_{PARASITIC}$ = 8.2 pF
 C_1 = 3.6 pF, C_2 = 3.6 pF

Oscillator Startup

The oscillator starts to generate 32.768 KHz pulses to the RTC after about 100 ms from when V_{RAT} is higher than V_{BATMIN} (2.4V) or V_{SB} is higher than V_{SBMIN} (3.0V). The oscillation amplitude on the X32O pin stabilizes to its final value (approximately 0.4V peak-to-peak around 0.7V DC) in about 1 s.

C₁ can be trimmed to achieve precisely 32.768 KHz. To achieve a high time accuracy, use crystal and capacitors with low tolerance and temperature coefficients.

External Oscillator 5.5.2.2

32.768 KHz can be applied from an external clock source. as shown in Figure 5-6.

Connections

Connect the clock to the X32I ball, leaving the oscillator output, X32O, unconnected.

Signal Parameters

The signal levels should conform to the voltage level requirements for X32I, of square or sine wave of 0.0V to V_{CORF} amplitude. The signal should have a duty cycle of approximately 50%. It should be sourced from a batterybacked source in order to oscillate during power-down. This assures that the RTC delivers updated time/calendar information.

Timing Generation 5.5.2.3

The timing generation function divides the 32.768 KHz clock by 2¹⁵ to derive a 1 Hz signal, which serves as the input for the seconds counter. This is performed by a divider chain composed of 15 divide-by-two latches, as shown in Figure 5-7.

Bits [6:4] (DV[2:0]) of the CRA Register control the following functions:

- Normal operation of the divider chain (counting).
- Divider chain reset to 0.
- Oscillator activity when only V_{BAT} power is present (backup state).

The divider chain can be activated by setting normal operational mode (bits [6:4] of CRA = 01x or 100). The first update occurs 500 ms after divider chain activation.

Bits [3:0] of CRA select one the of fifteen taps from the divider chain to be used as a periodic interrupt. The periodic flag becomes active after half of the programmed period has elapsed, following divider chain activation.

See Table 5-20 on page 127 for more details.

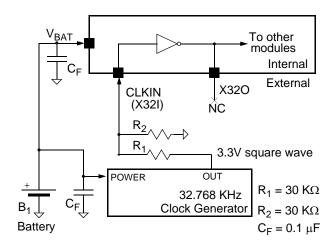


Figure 5-6. External Oscillator Connections

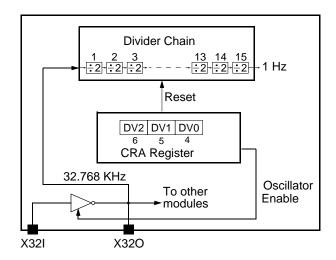


Figure 5-7. Divider Chain Control

5.5.2.4 Timekeeping

Data Format

Time is kept in BCD or binary format, as determined by bit 2 (DM) of Control Register B (CRB), and in either 12 or 24-hour format, as determined by bit 1 of this register.

Note: When changing the above formats, re-initialize all the time registers.

Daylight Saving

Daylight saving time exceptions are handled automatically, as described in Table 5-20 on page 127.

Leap Years

Leap year exceptions are handled automatically by the internal calendar function. Every four years, February is extended to 29 days.

Updating

The time and calendar registers are updated once per second regardless of bit 7 (SET) of CRB. Since the time and calendar registers are updated serially, unpredictable results may occur if they are accessed during the update. Therefore, you must ensure that reading or writing to the time storage locations does not coincide with a system update of these locations. There are several methods to avoid this contention.

Method 1

- Set bit 7 of CRB to 1. This takes a "snapshot" of the internal time registers and loads them into the user copy registers. The user copy registers are seen when accessing the RTC from outside, and are part of the double buffering mechanism. You may keep this bit set for up to 1 second, since the time/calendar chain continue to be updated once per second.
- 2) Read or write the required registers (since bit 1 is set, you are accessing the user copy registers). If you perform a read operation, the information you read is correct from the time when bit 1 was set. If you perform a write operation, you write only to the user copy registers.
- 3) Reset bit 1 to 0. During the transition, the user copy registers update the internal registers, using the double buffering mechanism to ensure that the update is performed between two time updates. This mechanism enables new time parameters to be loaded in the RTC.

Method 2

- Access the RTC registers after detection of an Update Ended interrupt. This implies that an update has just been completed and 999 ms remain until the next update.
- 2) To detect an Update Ended interrupt, you may either:
 - Poll bit 4 of CRC.
 - Use the following interrupt routine:
 - Set bit 4 of CRB.
 - Wait for an interrupt from interrupt pin.
 - Clear the IRQF flag of CRC before exiting the interrupt routine.

Method 3

Poll bit 7 of CRA. The update occurs 244 μs after this bit goes high. Therefore, if a 0 is read, the time registers remain stable for at least 244 μs .

Method 4

Use a periodic interrupt routine to determine if an update cycle is in progress, as follows:

- 1) Set the periodic interrupt to the desired period.
- Set bit 6 of CRB to enable the interrupt from periodic interrupt.
- 3) Wait for the periodic interrupt appearance. This indicates that the period represented by the following expression remains until another update occurs: [(Period of periodic interrupt / 2) + 244 μs]

5.5.2.5 Alarms

The timekeeping function can be set to generate an alarm when the current time reaches a stored alarm time. After each RTC time update (every 1 second), the seconds, minutes, hours, date of month and month counters are compared with their corresponding registers in the alarm settings. If equal, bit 5 of CRC is set. If the Alarm Interrupt Enable bit was previously set (CRB bit 5), interrupt request pin is also active.

Any alarm register may be set to "Unconditional Match" by setting bits [7:6] to 11. This combination, not used by any BCD or binary time codes, results in a periodic alarm. The rate of this periodic alarm is determined by the registers that were set to "Unconditional Match".

For example, if all but the seconds and minutes alarm registers are set to "Unconditional Match", an interrupt is generated every hour at the specified minute and second. If all but the seconds, minutes and hours alarm registers are set to "Unconditional Match", an interrupt is generated every day at the specified hour, minute and second.

5.5.2.6 Power Supply

The device is supplied from two supply voltages, as shown in Figure 5-8:

- System standby power supply voltage, V_{SB}
- · Backup voltage, from low capacity Lithium battery

A standby voltage, V_{SB} , from the external AC/DC power supply powers the RTC under normal conditions.

Figure 5-9 represents a typical battery configuration. No external diode is required to meet the UL standard, due to the internal switch and internal serial resistor $R_{\rm H\,I}$.

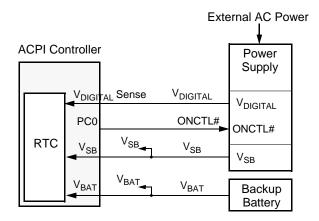
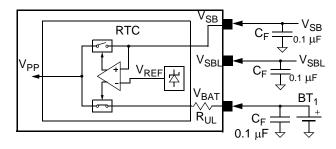


Figure 5-8. Power Supply Connections



Note: Place a 0.1 μ F capacitor on each V_{SB} , V_{SBL} power supply pin as close as possible to the pin, and also on V_{BAT} .

Figure 5-9. Typical Battery Configuration

The RTC is supplied from one of two power supplies, V_{SB} or V_{BAT} , according to their levels. An internal voltage comparator delivers the control signals to a pair of switches. Battery backup voltage V_{BAT} maintains the correct time and saves the CMOS memory when the V_{SB} voltage is absent, due to power failure or disconnection of the external AC/DC input power supply or V_{SB} main battery.

To assure that the module uses power from V_{SB} and not from V_{BAT} , the V_{SB} voltage should be maintained above its minimum, as detailed in Section 9.0 "Electrical Specifications" on page 369.

The actual voltage point where the module switches from V_{BAT} to V_{SB} is lower than the minimum workable battery voltage, but high enough to guarantee the correct functionality of the oscillator and the CMOS RAM.

Figure 5-10 shows typical battery current consumption during battery-backed operation, and Figure 5-11 during normal operation.

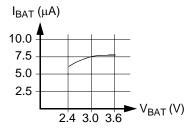
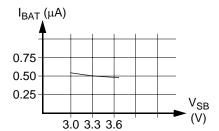


Figure 5-10. Typical Battery Current: Battery Backed Power Mode @ T_C = 25°C



Note: Battery voltage in this test is 3.0V.

Figure 5-11. Typical Battery Current: Normal Operation Mode

5.5.2.7 System Power States

The system power state may be No Power, Power On, Power Off or Power Failure. Table 5-18 indicates the power-source combinations for each state. No other power-source combinations are valid.

In addition, the power sources and distribution for the entire system are illustrated in Figure 5-8 on page 124.

Table 5-18. System Power States

V _{DIGITAL}	V _{SB}	V _{BAT}	Power State
-	-	_	No Power
_	-	+	Power Failure
_	+	+ or -	Power Off
+	+	+ or -	Power On

No Power

This state exists when no external or battery power is connected to the device. This condition does not occur once a backup battery has been connected, except in the case of a malfunction.

Power On

This is the normal state when the system is active. This state may be initiated by various events in addition to the normal physical switching on of the system. In this state, the system power supply is powered by external AC power and produces $V_{\mbox{\footnotesize DIGITAL}}$ and $V_{\mbox{\footnotesize SB}}.$ The system and the part are powered by $V_{\mbox{\footnotesize DIGITAL}},$ with the exception of the RTC logical device, which is powered by $V_{\mbox{\footnotesize SB}}.$

Power Off (Suspended)

This is the normal state when the system has been switched off and is not required to be active, but is still connected to a live external AC input power source. This state may be initiated directly or by software. The system is powered down. The RTC logical device remains active, powered by V_{SB} .

Power Failure

This state occurs when the external power source to the system stops supplying power, due to disconnection or power failure on the external AC input power source. The RTC continues to maintain timekeeping and RAM data under battery power (V_{BAT}), unless the oscillator stop bit was set in the RTC. In this case, the oscillator stops functioning if the system goes to battery power, and timekeeping data becomes invalid.

System Bus Lockout

During power on or power off, spurious bus transactions from the host may occur. To protect the RTC internal registers from corruption, all inputs are automatically locked out. The lockout condition is asserted when $V_{\mbox{\footnotesize{SBON}}}.$

Power-Up Detection

When system power is restored after a power failure or power off state ($V_{SB} = 0$), the lockout condition continues for a delay of 62 ms (minimum) to 125 ms (maximum) after the RTC switches from battery to system power.

The lockout condition is switched off immediately in the following situations:

- If the Divider Chain Control bits, DV[2:0], (CRA bits [6:4]) specify a normal operation mode (01x or 100), all input signals are enabled immediately upon detection of system voltage above V_{SBON}.
- When battery voltage is below V_{BATDCT} and HMR is 1, all input signals are enabled immediately upon detection of system voltage above V_{SBON}. This also initializes registers at offsets 00h through 0Dh.
- If bit 7 (VRT) of CRD is 0, all input signals are enabled immediately upon detection of system voltage above V_{SBON}.

5.5.2.8 Oscillator Activity

The RTC oscillator is active if:

 V_{SB} power supply is higher than V_{SBON}, independent of the battery voltage, V_{BAT}

-or-

 V_{BAT} power supply is higher than V_{BATMIN}, regardless if V_{SB} is present or not.

The RTC oscillator is disabled if:

 During power-down (V_{BAT} only), the battery voltage drops below V_{BATMIN}. When this occurs, the oscillator may be disabled and its functionality cannot be guaranteed.

-or-

 Software wrote 00x to DV[2:0] bits of the CRA Register and V_{SB} is removed. This disables the oscillator and decreases the power consumption from the battery connected to V_{BAT}. When disabling the oscillator, the CMOS RAM is not affected as long as the battery is present at a correct voltage level.

If the RTC oscillator becomes inactive, the following features are dysfunctional/disabled:

- Timekeeping.
- · Periodic interrupt.
- Alarm.

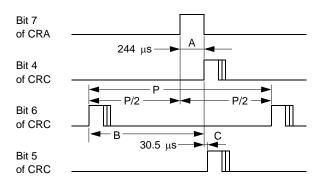
5.5.2.9 Interrupt Handling

The RTC has a single Interrupt Request line which handles the following three interrupt conditions:

- Periodic interrupt.
- · Alarm interrupt.
- Update end interrupt.

The interrupts are generated if the respective enable bits in the CRB register are set prior to an interrupt event occurrence. Reading the CRC register clears all interrupt flags. Thus, when multiple interrupts are enabled, the interrupt service routine should first read and store the CRC register, and then deal with all pending interrupts by referring to this stored status.

If an interrupt is not serviced before a second occurrence of the same interrupt condition, the second interrupt event is lost. Figure 5-12 illustrates the interrupt timing in the RTC.



Flags (and IRQ) are reset at the conclusion of CRC read or by reset.

A = Update In Progress bit high before update occurs = 244 μ s

B = Periodic interrupt to update = Period (periodic int) / 2 + $244 \mu s$

 $C = Update to Alarm Interrupt = 30.5 \mu s$

P = Period is programmed by RS[3:0] of CRA

Figure 5-12. Interrupt/Status Timing

5.5.2.10 Battery-Backed RAMs and Registers

The RTC has two battery-backed RAMs and 17 registers, used by the logical units themselves. Battery-backup power enables information retention during system power down.

The RAMs are:

- Standard RAM
- Extended RAM

The memory maps and register content of the RAMs is provided in Section 5.5.4 "RTC General-Purpose RAM Map" on page 131.

The first 14 bytes and 3 programmable bytes of the Standard RAM are overlaid by time, alarm data and control registers. The remaining 111 bytes are general-purpose memory.

Registers with reserved bits should be written using the read-modify-write method.

All register locations within the device are accessed by the RTC Index and Data registers (at base address and base address+1). The Index register points to the register location being accessed, and the Data register contains the data to be transferred to or from the location. An additional 128 bytes of battery-backed RAM (also called Extended RAM) may be accessed via a second pair of Index and Data registers.

Access to the two RAMs may be locked. For details see Table 5-7 on page 115.

5.5.3 RTC Registers

The RTC registers can be accessed (see Section 5.4.2.1 "LDN 00h - Real-Time Clock" on page 114) at any time during normal operation mode (i.e.,when V_{SB} is within the recommended operation range). This access is disabled during battery-backed operation. The write operation to these registers is also disabled if bit 7 of the CRD Register is 0.

Note: Before attempting to perform any start-up procedures, read about bit 7 (VRT) of the CRD Register.

This section describes the RTC Timing and Control Registers that control basic RTC functionality.

Table 5-19. RTC Register Map

Index	Туре	Name	Reset Type
00h	R/W	SEC. Seconds Register	V _{PP} PUR
01h	R/W	SECA. Seconds Alarm Register	V _{PP} PUR
02h	R/W	MIN. Minutes Register	V _{PP} PUR
03h	R/W	MINA. Minutes Alarm Register	V _{PP} PUR
04h	R/W	HOR. Hours Register	V _{PP} PUR
05h	R/W	HORA. Hours Alarm Register	V _{PP} PUR
06h	R/W	DOW. Day Of Week Register	V _{PP} PUR
07h	R/W	DOM. Date Of Month Register	V _{PP} PUR
08h	R/W	MON. Month Register	V _{PP} PUR
09h	R/W	YER. Year Register	V _{PP} PUR
0Ah	R/W	CRA. RTC Control Register A	Bit specific
0Bh	R/W	CRB. RTC Control Register B	Bit specific
0Ch	RO	CRC. RTC Control Register C	Bit specific
0Dh	RO	CRD. RTC Control Register D	V _{PP} PUR
Programmable ¹	R/W	DOMA. Date of Month Alarm Register	V _{PP} PUR
Programmable ¹	R/W	MONA. Month Alarm Register	V _{PP} PUR
Programmable ¹	R/W	CEN. Century Register	V _{PP} PUR

^{1.} Overlaid on RAM bytes in range 0Eh-7Fh. See Section 5.4.2.1 "LDN 00h - Real-Time Clock" on page 114.

Table 5-20. RTC Registers

Bit	Description	
Index 00h	Seconds Register - SEC (R/W)	Reset Type: V _{PP} PUR
7:0	Seconds Data. Values may be 00 to 59 in BCD format or 00 to 3B in binary format.	
Index 01h	Seconds Alarm Register - SECA (R/W)	Reset Type: V _{PP} PUR
7:0	Seconds Alarm Data. Values may be 00 to 59 in BCD format or 00 to 3B in binary format.	
	When bits 7 and 6 are both set to one ("11"), unconditional match is selected.	
Index 02h	Minutes Register - MIN (R/W)	Reset Type: V _{PP} PUR
7:0	Minutes Data. Values can be 00 to 59 in BCD format, or 00 to 3B in binary format.	



Table 5-20. RTC Registers (Continued)

Bit	Description	
Index 03h	Minutes Alarm Register - MINA (R/W)	Reset Type: V _{PP} PUR
7:0	Minutes Alarm Data. Values can be 00 to 59 in BCD format, or 00 to 3B in binary format.	
	When bits 7 and 6 are both set to 1, unconditional match is selected. See Section 5.5.2.5 information about "unconditional" matches.	"Alarms" on page 123 for more
Index 04h	Hours Register - HOR (R/W)	Reset Type: V _{PP} PUR
7:0	Hours Data. For 12-hour mode, values can be 01 to 12 (AM) and 81 to 92 (PM) in BCD fo 8C (PM) in binary format. For 24-hour mode, values can be 0- to 23 in BCD format or 00 to	. ,
Index 05h	Hours Alarm Register - HORA (R/W)	Reset Type: V _{PP} PUR
7:0	Hours Alarm Data. For 12-hour mode, values may be 01 to 12 (AM) and 81 to 92 (PM) in 81 to 8C (PM) in Binary format. For 24-hour mode, values may be 0- to 23 in BCD format of	
	When bits 7 and 6 are both set to one ("11"), unconditional match is selected.	
Index 06h	Day of Week Register - DOW (R/W)	Reset Type: V _{PP} PUR
7:0	Day Of Week Data. Values may be 01 to 07 in BCD format or 01 to 07 in binary format.	
Index 07h	Date of Month Register - DOM (R/W)	Reset Type: V _{PP} PUR
7:0	Date Of Month Data. Values may be 01 to 31 in BCD format or 01 to 1F in binary format.	
Index 08h	Month Register - MON (R/W)	Reset Type: V _{PP} PUR
Width: Byte		
7-0	Month Data. Values may be 01 to 12 in BCD format or 01 to 0C in binary format.	
Index 09h	Year Register - YER (R/W)	Reset Type: V _{PP} PUR
7:0	Year Data. Values may be 00 to 99 in BCD format or 00 to 63 in binary format.	
Index 0Ah This registe	RTC Control Register A - CRA (R/W) er controls test selection, among other functions. This register cannot be written before read	Reset Type: Bit Specific ing bit 7 of CRD.
7	Update in Progress. (RO) This bit is not affected by reset. This bit reads 0 when bit 7 of the	ne CRB Register is 1.
	0: Timing registers not updated within 244 μ s.	
	1: Timing registers updated within 244 μs.	
6:4	Divider Chain Control. These bits control the configuration of the divider chain for timing selection. See Table 5-21 on page 130. They are cleared to 000 as long as bit 7 of CRD is	
3:0	Periodic Interrupt Rate Select. These bits select one of fifteen output taps from the clock the periodic interrupt. See Table 5-22 on page 130 and Figure 5-7 on page 122. They are CRD is 0.	
Index 0Bh	RTC Control Register B - CRB (R/W)	Reset Type: Bit Specific
7	Set Mode. This bit is reset at V _{PP} power-up reset only.	
	0: Timing updates occur normally.	
	1: User copy of time is "frozen", allowing the time registers to be accessed whether or not	an update occurs.
6	Periodic Interrupt. Bits [3:0] of the CRA Register determine the rate at which this interrupt RTC reset (i.e., hardware or software reset) or when RTC is disable.	is generated. It is cleared to 0 on
	0: Disable.	
	1: Enable.	
5	Alarm Interrupt. This interrupt is generated immediately after a time update in which the someth time equal their respective alarm counterparts. It is cleared to 0 as long as bit 7 of the something of the counterparts in the counterparts are considered to 0.	
5		
5	month time equal their respective alarm counterparts. It is cleared to 0 as long as bit 7 of t 0: Disable. 1: Enable.	he CRD Register is reads 0.
5	month time equal their respective alarm counterparts. It is cleared to 0 as long as bit 7 of t 0: Disable.	he CRD Register is reads 0.
	 month time equal their respective alarm counterparts. It is cleared to 0 as long as bit 7 of t 0: Disable. 1: Enable. Update Ended Interrupt. This interrupt is generated when an update occurs. It is cleared 	he CRD Register is reads 0.



Table 5-20. RTC Registers (Continued)

Bit	Description Table 5-20. RTC Registers (Continued)	
3	Reserved. This bit is defined as "Square Wave Enable" by the MC146818 and is not supported	by the RTC. This bit is
	always read as 0.	•
2	Data Mode. This bit is reset at V _{PP} power-up reset only.	
	0: Enable BCD format.	
	1: Enable Binary format.	
1	Hour Mode. This bit is reset at V _{PP} power-up reset only.	
	0: Enable 12-hour format.	
	1: Enable 24-hour format.	
0	Daylight Saving. This bit is reset at V _{PP} power-up reset only.	
	0: Disable.	
	1: Enable: In the spring, time advances from 1:50:50 AM to 2:00:00 AM on the first Sunday in April	
	 In the spring, time advances from 1:59:59 AM to 3:00:00 AM on the first Sunday in April. In the fall, time returns from 1:59:59 AM to 1:00:00 AM on the last Sunday in October. 	
Index 0Ch	RTC Control Register C - CRC (RO)	Reset Type: Bit Specific
7	IRQ Flag. Mirrors the value on the interrupt output signal. When interrupt is active, IRQF is 1. To vate the interrupt pin), read the CRC Register as the flag bits UF, AF and PF are cleared after re	
	0: IRQ inactive.	
_	1: Logic equation is true: ((UIE and UF) or (AIE and AF) or (PIE and PF)).	
6	Periodic Interrupt Flag. Cleared to 0 on RTC reset (i.e., hardware or software reset) or the RTC bit is cleared to 0 when this register is read.	C disabled. In addition, this
	0: No transition occurred on the selected tap since the last read.	
	1: Transition occurred on the selected tap of the divider chain.	
5	Alarm Interrupt Flag. Cleared to 0 as long as bit 7 of the CRD Register is reads 0. In addition, this register is read.	his bit is cleared to 0 when
	1: Alarm condition detected.	
4	Update Ended Interrupt Flag. Cleared to 0 on RTC reset (i.e., hardware or software reset) or the tion, this bit is cleared to 0 when this register is read.	ne RTC disabled. In addi-
	0: No update occurred since the last read.	
	1: Time registers updated.	
3:0	Reserved.	
Index 0Dh	RTC Control Register D - CRD (RO)	Reset Type: V _{PP} PUR
7	Valid RAM and Time. This bit senses the voltage that feeds the RTC (VSB or VBAT) and indicat too low since the last time this bit was read. If it was too low, the RTC contents (time/calendar recont valid.	
	0: The voltage that feeds the RTC was too low.	
	1: RTC contents (time/calendar registers and CMOS RAM) are valid.	
6:0	Reserved.	
Index Prog	rammable Date of Month Alarm Register - DOMA (R/W)	Reset Type: V _{PP} PUR
7:0	Date of Month Alarm Data. Values may be 01 to 31 in BCD format or 01 to 1F in Binary format.	
	When bits 7 and 6 are both set to one ("11"), unconditional match is selected. (Default)	
Index Prog	rammable Month Alarm Register - MONA (R/W)	Reset Type: V _{PP} PUR
7:0	Month Alarm Data. Values may be 01 to 12 in BCD format or 01 to 0C in Binary format.	
	When bits 7 and 6 are both set to one ("11"), unconditional match is selected. (Default)	
Index Prog	rammable Century Register - CEN (R/W)	Reset Type: V _{PP} PUR
7:0	Century Data. Values may be 00 to 99 in BCD format or 00 to 63 in Binary format.	

Table 5-21. Divider Chain Control / Test Selection

DV2	DV1	DV0	
CRA6	CRA5	CRA4	Configuration
0	0	Х	Oscillator Disabled
0	1	0	Normal Operation
0	1	1	Test
1	0	Х	
1	1	Х	Divider Chain Reset

Table 5-22. Periodic Interrupt Rate Encoding

Rate Select 3 2 1 0	Periodic Interrupt Rate (ms)	Divider Chain Output
0000	No interrupts	
0 0 0 1	3.906250	7
0010	7.812500	8
0 0 1 1	0.122070	2
0100	0.244141	3
0101	0.488281	4
0110	0.976562	5
0111	1.953125	6
1000	3.906250	7
1001	7.812500	8
1010	15.625000	9
1011	31.250000	10
1100	62.500000	11
1101	125.000000	12
1110	250.000000	13
1111	500.000000	14

Table 5-23. BCD and Binary Formats

Parameter	BCD Format	Binary Format
Seconds	00 to 59	00 to 3B
Minutes	00 to 59	00 to 3B
Hours	12-hour mode: 01 to 12 (AM)	12-hour mode: 01 to 0C (AM)
	81 to 92 (PM)	81 to 8C (PM)
	24-hour mode: 00 to 23	24-hour mode: 00 to 17
Day	01 to 07 (Sunday = 01)	01 to 07
Date	01 to 31	01 to 1F
Month	01 to 12 (January = 01)	01 to 0C
Year	00 to 99	00 to 63
Century	00 to 99	00 to 63

5.5.3.1 Usage Hints

- 1) Read bit 7 of CRD at each system power-up to validate the contents of the RTC registers and the CMOS RAM. When this bit is 0, the contents of these registers and the CMOS RAM are questionable. This bit is reset when the backup battery voltage is too low. The voltage level at which this bit is reset is below the minimum recommended battery voltage, 2.4V. Although the RTC oscillator may function properly and the register contents may be correct at lower than 2.4V, this bit is reset since correct functionality cannot be guaranteed. System BIOS may use a checksum method to revalidate the contents of the CMOS-RAM. The checksum byte should be stored in the same CMOS RAM.
- 2) Change the backup battery while normal operating power is present, and not in backup mode, to maintain valid time and register information. If a low leakage capacitor is connected to V_{BAT}, the battery may be changed in backup mode.
- A rechargeable NiCd battery may be used instead of a non-rechargeable Lithium battery. This is a preferred solution for portable systems, where small size components is essential.
- 4) A supercap capacitor may be used instead of the normal Lithium battery. In a portable system usually the V_{SB} voltage is always present since the power management stops the system before its voltage falls to low. The supercap capacitor in the range of 0.047-0.47 F should supply the power during the battery replacement.

5.5.4 RTC General-Purpose RAM Map

Table 5-24. Standard RAM Map

Index	Description
0Eh - 7Fh	Battery-backed general-purpose 111- byte RAM.

Table 5-25. Extended RAM Map

Index	Description
00h - 7Fh	Battery-backed general-purpose 128-byte RAM.

5.6 System Wakeup Control (SWC)

The SWC wakes up the system by sending a power-up request to the ACPI controller in response to the following maskable system events:

- Modem ring (RI2#)
- Audio Codec event (SDATA_IN2)
- Programmable Consumer Electronics IR (CEIR) address

Each system event that is monitored by the SWC is fed into a dedicated detector that decides when the event is active, according to predetermined (either fixed or programmable) criteria. A set of dedicated registers is used to determine the wakeup criteria, including the CEIR address.

A Wakeup Events Status Register (WKSR) and a Wakeup Events Control Register (WKCR) hold a Status bit and Enable bit, respectively, for each possible wakeup event.

Upon detection of an active event, the corresponding Status bit is set to 1. If the event is enabled (the corresponding Enable bit is set to 1), a power-up request is issued to the ACPI controller. In addition, detection of an active wakeup event may be also routed to an arbitrary IRQ.

Disabling an event prevents it from issuing power-up requests, but does not affect the Status bits. A power-up reset is issued to the ACPI controller when both the Status and Enable bits are set to 1 for at least one event type.

SWC logic is powered by V_{SB} . The SWC control and configuration registers are battery backed, powered by V_{PP} The setup of the wakeup events, including programmable sequences, is retained throughout power failures (no V_{SB}) as long as the battery is connected. V_{PP} is taken from V_{SB} if $V_{SB} > 2.0$; otherwise, V_{BAT} is used as the V_{PP} source.

Hardware reset does not affect the SWC registers. They are reset only by a SIO software reset or power-up of V_{PP}

5.6.1 Event Detection

5.6.1.1 Audio Codec Event

A low-to-high transition on SDATA_IN2 indicates the detection of an Audio Codec event and can be used as a wakeup event.

5.6.1.2 CEIR Address

A CEIR transmission received on IRRX1 in a pre-selected standard (NEC, RCA or RC-5) is matched against a programmable CEIR address. Detection of matching can be used as a wakeup event. The CEIR address detection operates independently of the serial port with the IR (which is powered down with the rest of the system).

Whenever an IR signal is detected, the receiver immediately enters the Active state. When this happens, the receiver keeps sampling the IR input signal and generates a bit string where a logic 1 indicates an idle condition and a logic 0 indicates the presence of IR energy. The received bit string is de-serialized and assembled into 8-bit characters

The expected CEIR protocol of the received signal should be configured through bits [5:4] of the CEIR Wakeup Control register (IRWCR) (see Table 5-30 on page 135).

The CEIR Wakeup Address register (IRWAD) holds the unique address to be compared with the address contained in the incoming CEIR message. If CEIR is enabled (IRWCR[0] = 1) and an address match occurs, then the CEIR Event Status bit of WKSR is set to 1.

The CEIR Address Shift register (ADSR) holds the received address which is compared with the address contained in the IRWAD. The comparison is affected also by the CEIR Wakeup Address Mask register (IRWAM) in which each bit determines whether to ignore the corresponding bit in the IRWAD.

If CEIR routing to interrupt request is enabled, the assigned SWC interrupt request can be used to indicate that a complete address has been received. To get this interrupt when the address is completely received, IRWAM should be written with FFh. Once the interrupt is received, the value of the address can be read from ADSR.

Another parameter that is used to determine whether a CEIR signal is to be considered valid is the bit cell time width. There are four time ranges for the different protocols and carrier frequencies. Four pairs of registers (IRWTRxL and IRWTRxH) define the low and high limits of each time range. Table 5-26 lists the recommended time ranges limits for the different protocols and their applicable ranges. The values are represented in hexadecimal code where the units are of 0.1 ms.

Table 5-26. Time Range Limits for CEIR Protocols

Time	RO	RC-5		NEC		RCA	
Range	Low Limit	High Limit	Low Limit	High Limit	Low Limit	High Limit	
0	10h	14h	09h	0Dh	0Ch	12h	
1	07h	0Bh	14h	19h	16h	1Ch	
2	-	-	50h	64h	B4h	DCh	
3	-	-	28h	32h	23h	2Dh	

5.6.2 SWC Registers

The SWC registers are organized in two banks. The offsets are related to a base address that is determined by the SWC Base Address Register in the logical device configuration. The lower three registers are common to the two banks while the upper registers (03h-0Fh) are divided as follows:

- · Bank 0 holds reserved registers.
- · Bank 1 holds the CEIR Control Registers.

The active bank is selected through the Configuration Bank Select field (bits [1:0]) in the Wakeup Configuration Register (WKCFG). See Table 5-29 on page 134.

The tables that follow provide register maps and bit definitions for Banks 0 and 1.

Table 5-27. Banks 0 and 1 - Common Control and Status Register Map

Offset	Туре	Name	Reset Value
00h	R/W1C	WKSR. Wakeup Events Status Register	00h
01h	R/W	WKCR. Wakeup Events Control Register	03h
02h	R/W	WKCFG. Wakeup Configuration Register	00h

Table 5-28. Bank 1 - CEIR Wakeup Configuration and Control Register Map

Offset	Туре	Name	Reset Value
03h	R/W	IRWCR. CEIR Wakeup Control Register	00h
04h		RSVD. Reserved	
05h	R/W	IRWAD. CEIR Wakeup Address Register	00h
06h	R/W	IRWAM. CEIR Wakeup Address Mask Register	E0h
07h	RO	ADSR. CEIR Address Shift Register	00h
08h	R/W	IRWTR0L. CEIR Wakeup, Range 0, Low Limit Register	10h
09h	R/W	IRWTR0H. CEIR Wakeup, Range 0, High Limit Register	14h
0Ah	R/W	IRWTR1L. CEIR Wakeup, Range 1, Low Limit Register	07h
0Bh	R/W	IRWTR1H. CEIR Wakeup, Range 1, High Limit Register	0Bh
0Ch	R/W	IRWTR2L. CEIR Wakeup, Range 2, Low Limit Register	50h
0Dh	R/W	IRWTR2H. CEIR Wakeup, Range 2, High Limit Register	64h
0Eh	R/W	IRWTR3L. CEIR Wakeup, Range 3, Low Limit Register	28h
0Fh	R/W	IRWTR3H. CEIR Wakeup, Range 3, High Limit Register	32h

Table 5-29. Banks 0 and 1 - Common Control and Status Registers

Bit	Description
Offset 00	h Wakeup Events Status Register - WKSR (R/W1C) Reset Value: 00h
	ter is set to 00h on power-up of V _{PP} or software reset. It indicates which wakeup event and/or PME occurred. (See Section
6.2.9.4 "P	ower Management Events" on page 176.)
7	Reserved.
6	Reserved. Must be set to 0.
5	IRRX1 (CEIR) Event Status. This sticky bit shows the status of the CEIR event detection.
	0: Event not detected. (Default)
	1: Event detected.
4:2	Reserved.
1	RI2# Event Status. This sticky bit shows the status of RI2# event detection.
	0: Event not detected. (Default)
	1: Event detected.
0	SDATA_IN2 Event Status. This sticky bit shows the status of Audio Codec event detection.
	0: Event not detected. (Default)
	1: Event detected.
Offset 01	h Wakeup Events Control Register - WKCR (R/W) Reset Value: 03h
_	ter is set to 03h on power-up of V _{PP} or software reset. Detected wakeup events that are enabled issue a power-up request the troller and/or a PME to the Core Logic module. (See Section 6.2.9.4 "Power Management Events" on page 176.)
7	Reserved.
6	Reserved. Must be set to 0.
5	IRRX1 (CEIR) Event Enable.
	0: Disable. (Default)
	1: Enable.
4:2	Reserved.
1	RI2# Event Enable.
	0: Disable.
	1: Enable. (Default)
0	SDATA_IN2 Event Enable.
	0: Disable.
	1: Enable. (Default)
Offset 02 This regis	h Wakeup Configuration Register - WKCFG (R/W) Reset Value: 00h ter is set to 00h on power-up of V _{PP} or software reset. It enables access to CEIR registers.
7:5	Reserved.
4	Reserved. Must be set to 0.
3	Reserved. Must be set to 0.
2	Reserved.
1:0	Configuration Bank Select Bits.
-	00: Only shared registers are accessible.
	01: Shared registers and Bank 1 (CEIR) registers are accessible.
	10: Bank selected.

Table 5-30. Bank 1 - CEIR Wakeup Configuration and Control Registers

Bit	Description				
-	Bank 1, Offset 03h CEIR Wakeup Control Register - IRWCR (R/W) Reset Value: 00h This register is set to 00h on power-up of V _{PP} or software reset.				
7:6	Reserved.	5 4F 5. 1FF 5. 55			
5:4	CEIR Protocol Sele	et.			
	00: RC5				
	01: NEC/RCA				
	1x: Reserved				
3	Reserved.				
2	Invert IRRX Input.				
	0: Not inverted. (De	fault)			
	1: Inverted.				
1	Reserved.				
0	CEIR Enable.				
	0: Disable. (Default)				
	1: Enable.				

Bank 1, Offset 04h Reserved

Bank 1, Offset 05h CEIR Wakeup Address Register - IRWAD (R/W)

This register defines the station address to be compared with the address contained in the incoming CEIR message. If CEIR is enabled (bit 0 of the IRWCR register is 1) and an address match occurs, then bit 5 of the WKSR register is set to 1.

This register is set to 00h on power-up of $V_{\mbox{\footnotesize{PP}}}$ or software reset.

7:0 CEIR Wakeup Address

Bank 1, Offset 06h CEIR Wakeup Mask Register - IRWAM (R/W)

Reset Value: E0h

Reset Value: 00h

Each bit in this register determines whether the corresponding bit in the IRWAD register takes part in the address comparison. Bits 5, 6, and 7 must be set to 1 if the RC-5 protocol is selected.

This register is set to E0h on power-up of $V_{\mbox{\footnotesize{PP}}}$ or software reset.

7:0 CEIR Wakeup Address Mask.

- If the corresponding bit is 0, the address bit is not masked (enabled for compare).
- If the corresponding bit is 1, the address bit is masked (ignored during compare).

Bank 1, Offset 07h

CEIR Address Shift Register - ADSR (RO)

Reset Value: 00h

This register holds the received address to be compared with the address contained in the IRWAD register.

This register is set to 00h on power-up of $V_{\mbox{\footnotesize{PP}}}$ or software reset.

7:0 CEIR Address.

CEIR Wakeup Range 0 Registers

These two registers (IRWTR0L and IRWTR0H) define the low and high limits of time range 0 (see Table 5-26 on page 132). The values are represented in units of 0.1 ms.

- RC-5 protocol: The bit cell width must fall within this range for the cell to be considered valid. The nominal cell width is 1.778 ms for a 36 KHz carrier. IRWTR0L and IRWTR0H should be set to 10h and 14h, respectively. (Default)
- NEC protocol: The time distance between two consecutive CEIR pulses that encodes a bit value of 0 must fall within this range. The
 nominal distance for a 0 is 1.125 ms for a 38 KHz carrier. IRWTR0L and IRWTR0H should be set to 09h and 0Dh, respectively.

Bank 1, Offset 08h IRWTR0L Register (R/W)		IRWTR0L Register (R/W)	Reset Value: 10h
This regist	ter is set to 10h on power-up	o of V _{PP} or software reset.	
7:5	Reserved.		
4:0	CEIR Pulse Change, Ran	nge 0, Low Limit.	
Bank 1, O	ffset 09h	IRWTR0H Register (R/W)	Reset Value: 14h
1	offset 09h ter is set to 14h on power-up	3	Reset Value: 14h
1		3	Reset Value: 14h

Table 5-30. Bank 1 - CEIR Wakeup Configuration and Control Registers (Continued)

Bit	Description

CEIR Wakeup Range 1 Registers

These two registers (IRWTR1L and IRWTR1H) define the low and high limits of time range 1 (see Table 5-26 on page 132). The values are represented in units of 0.1 ms.

- RC-5 protocol: The pulse width defining a half-bit cell must fall within this range in order for the cell to be considered valid. The nominal pulse width is 0.889 for a 38 KHz carrier. IRWTR1L and IRWTR1H should be set to 07h and 0Bh, respectively. (Default)
- NEC protocol: The time between two consecutive CEIR pulses that encodes a bit value of 1 must fall within this range. The nominal time for a 1 is 2.25 ms for a 36 KHz carrier. IRWTR1L and IRWTR1H should be set to 14h and 19h, respectively.

Bank 1, Offset 0Ah		IRWTR1L Register (R/W)	Reset Value: 07h
This regist	er is set to 07h on power-u	p of V _{PP} or software reset.	
7:5	Reserved.		
4:0	CEIR Pulse Change, Ra	nge 1, Low Limit.	
Bank 1, O	ffset 0Bh	IRWTR1H Register (R/W)	Reset Value: 0Bh
This regist	er is set to 0Bh on power-u	p of V _{PP} or software reset.	
7:5	Reserved.		
4:0	CEIR Pulse Change, Ra	nge 1, High Limit.	

CEIR Wakeup Range 2 Registers

These two registers (IRWTR2L and IRWTR2H) define the low and high limits of time range 2 (see Table 5-26 on page 132). The values are represented in units of 0.1 ms.

- RC-5 protocol: These registers are not used when the RC-5 protocol is selected.
- NEC protocol: The header pulse width must fall within this range in order for the header to be considered valid. The nominal value is 9 ms for a 38 KHz carrier. IRWTR2L and IRWTR2H should be set to 50h and 64h, respectively. (Default)

Bank 1, Offset 0Ch IRWTR2L Register (R/W) Reset Value: 50h This register is set to 50h on power-up of V_{PP} or software reset. CEIR Pulse Change, Range 2, Low Limit.

Bank 1, Offset 0Dh IRWTR2H Register (R/W) Reset Value: 64h

This register is set to 64h on power-up of V_{PP} or software reset.

CEIR Pulse Change, Range 2, High Limit.

CEIR Wakeup Range 3 Registers

These two registers (IRWTR3L and IRWTR3H) define the low and high limits of time range 3 (see Table 5-26 on page 132). The values are represented in units of 0.1 ms.

- RC-5 protocol: These registers are not used when the RC-5 protocol is selected.
- NEC protocol: The post header gap width must fall within this range in order for the gap to be considered valid. The nominal value is 4.5 ms for a 36 KHz carrier. IRWTR3L and IRWTR3H should be set to 28h and 32h, respectively. (Default)

Bank 1, Offset 0Eh IRWTR3L Register (R/W) This register is set to 28h on power-up of V _{PP} or software reset.		Reset Value: 28h	
7:0	7:0 CEIR Pulse Change, Range 3, Low Limit.		
Bank 1, Offset 0Fh IRWTR3H Register (R/W) This register is set to 32h on power-up of V _{PP} or software reset.		Reset Value: 32h	
7:0	CEIR Pulse Change, Rang	o 2 High Limit	

5.7 ACCESS.bus Interface

The SC3200 has two ACCESS.bus (ACB) controllers. ACB is a two-wire synchronous serial interface compatible with the ACCESS.bus physical layer, Intel's SMBus, and Philips' I^2C^{TM} . The ACB can be configured as a bus master or slave, and can maintain bidirectional communication with both multiple master and slave devices. As a slave device, the ACB may issue a request to become the bus master.

The ACB allows easy interfacing to a wide range of low-cost memories and I/O devices, including: EEPROMs, SRAMs, timers, ADC, DAC, clock chips and peripheral drivers.

The ACCESS.bus protocol uses a two-wire interface for bidirectional communication between the ICs connected to the bus. The two interface lines are the Serial Data Line (AB1D and AB2D) and the Serial Clock Line (AB1C and AB2C). (Here after referred to as ABD and ABC unless otherwise specified.) These lines should be connected to a positive supply via an internal or external pull-up resistor, and remain high even when the bus is idle.

Each IC has a unique address and can operate as a transmitter or a receiver (though some peripherals are only receivers).

During data transactions, the master device initiates the transaction, generates the clock signal and terminates the transaction. For example, when the ACB initiates a data transaction with an attached ACCESS.bus compliant peripheral, the ACB becomes the master. When the peripheral responds and transmits data to the ACB, their master/slave (data transaction initiator and clock generator) relationship is unchanged, even though their transmitter/receiver functions are reversed.

This section describes the general ACB functional block. A device may include a different implementation. For device specific implementation, see Section 5.4.2.5 "LDN 05h and 06h - ACCESS.bus Ports 1 and 2" on page 119.

5.7.1 Data Transactions

One data bit is transferred during each clock pulse. Data is sampled during the high state of the serial clock (ABC). Consequently, throughout the clock's high period, the data should remain stable (see Figure 5-13). Any changes on the ABD line during the high state of the ABC and in the middle of a transaction aborts the current transaction. New data should be sent during the low ABC state. This protocol permits a single data line to transfer both command/control information and data, using the synchronous serial clock.

Each data transaction is composed of a Start Condition, a number of byte transfers (set by the software) and a Stop Condition to terminate the transaction. Each byte is transferred with the most significant bit first, and after each byte (8 bits), an Acknowledge signal must follow. The following sections provide further details of this process.

During each clock cycle, the slave can stall the master while it handles the previous data or prepares new data. This can be done for each bit transferred, or on a byte boundary, by the slave holding ABC low to extend the clock-low period. Typically, slaves extend the first clock cycle of a transfer if a byte read has not yet been stored, or if the next byte to be transmitted is not yet ready. Some microcontrollers, with limited hardware support for ACCESS.bus, extend the access after each bit, thus allowing the software to handle this bit.

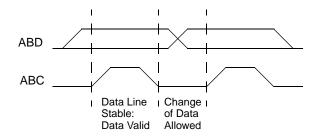


Figure 5-13. Bit Transfer

5.7.2 Start and Stop Conditions

The ACCESS.bus master generates Start and Stop Conditions (control codes). After a Start Condition is generated, the bus is considered busy and retains this status for a certain time after a Stop Condition is generated. A high-to-low transition of the data line (ABD) while the clock (ABC) is high indicates a Start Condition. A low-to-high transition of the ABD line while the ABC is high indicates a Stop Condition (Figure 5-14).

In addition to the first Start Condition, a repeated Start Condition can be generated in the middle of a transaction. This allows another device to be accessed, or a change in the direction of data transfer.

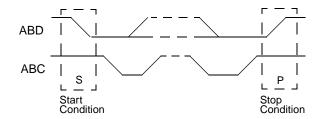


Figure 5-14. Start and Stop Conditions

5.7.3 Acknowledge (ACK) Cycle

The ACK cycle consists of two signals: the ACK clock pulse sent by the master with each byte transferred, and the ACK signal sent by the receiving device (see Figure 5-15).

The master generates the ACK clock pulse on the ninth clock pulse of the byte transfer. The transmitter releases

the ABD line (permits it to go high) to allow the receiver to send the ACK signal. The receiver must pull down the ABD line during the ACK clock pulse, signalling that it has correctly received the last data byte and is ready to receive the next byte. Figure 5-16 illustrates the ACK cycle.

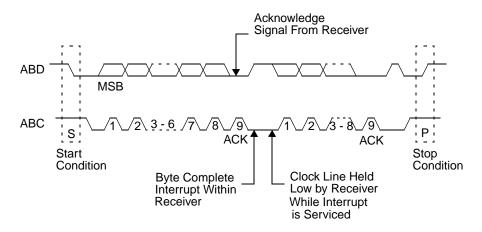


Figure 5-15. ACCESS.bus Data Transaction

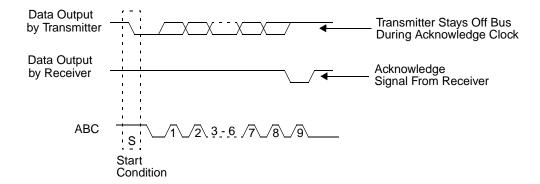


Figure 5-16. ACCESS.bus Acknowledge Cycle

5.7.4 Acknowledge After Every Byte Rule

According to this rule, the master generates an acknowledge clock pulse after each byte transfer, and the receiver sends an acknowledge signal after every byte received. There are two exceptions to this rule:

- When the master is the receiver, it must indicate to the transmitter the end of data by not acknowledging (negative acknowledge) the last byte clocked out of the slave. This negative acknowledge still includes the acknowledge clock pulse (generated by the master), but the ABD line is not pulled down.
- When the receiver is full, otherwise occupied, or a problem has occurred, it sends a negative acknowledge to indicate that it cannot accept additional data bytes.

5.7.5 Addressing Transfer Formats

Each device on the bus has a unique address. Before any data is transmitted, the master transmits the address of the slave being addressed. The slave device should send an acknowledge signal on the ABD line, once it recognizes its address.

The address consists of the first 7 bits after a Start Condition. The direction of the data transfer (R/W#) depends on the bit sent after the address, the eighth bit. A low-to-high transition during a ABC high period indicates the Stop Condition, and ends the transaction of ABD (see Figure 5-17).

When the address is sent, each device in the system compares this address with its own. If there is a match, the device considers itself addressed and sends an acknowledge signal. Depending on the state of the R/W# bit (1 = Read, 0 = Write), the device acts either as a transmitter or a receiver.

The I²C bus protocol allows a general call address to be sent to all slaves connected to the bus. The first byte sent specifies the general call address (00h) and the second byte specifies the meaning of the general call (for example, write slave address by software only). Those slaves that require data acknowledge the call, and become slave receivers; other slaves ignore the call.

5.7.6 Arbitration on the Bus

Multiple master devices on the bus require arbitration between their conflicting bus access demands. Control of the bus is initially determined according to address bits and clock cycle. If the masters are trying to address the same slave, data comparisons determine the outcome of this arbitration. In master mode, the device immediately aborts a transaction if the value sampled on the ABD line differs from the value driven by the device. (An exception to this rule is ABD while receiving data. The lines may be driven low by the slave without causing an abort.)

The ABC signal is monitored for clock synchronization and to allow the slave to stall the bus. The actual clock period is set by the master with the longest clock period, or by the slave stall period. The clock high period is determined by the master with the shortest clock high period.

When an abort occurs during the address transmission, a master that identifies the conflict should give up the bus, switch to slave mode and continue to sample ABD to check if it is being addressed by the winning master on the bus.

5.7.7 Master Mode

Requesting Bus Mastership

An ACCESS.bus transaction starts with a master device requesting bus mastership. It asserts a Start Condition, followed by the address of the device it wants to access. If this transaction is successfully completed, the software may assume that the device has become the bus master.

For the device to become the bus master, the software should perform the following steps:

- Configure ACBCTL1[2] to the desired operation mode. (Polling or Interrupt) and set the ACBCTL1[0]. This causes the ACB to issue a Start Condition on the ACCESS.bus when the ACCESS.bus becomes free (ACBCST[1] is cleared, or other conditions that can delay start). It then stalls the bus by holding ABC low.
- If a bus conflict is detected (i.e., another device pulls down the ABC signal), the ACBST[5] is set.
- If there is no bus conflict, ACBST[1] and ACBST[6] are set.
- 4) If the ACBCTL1[2] is set and either ACBST[5] or ACBST[6] is set, an interrupt is issued.

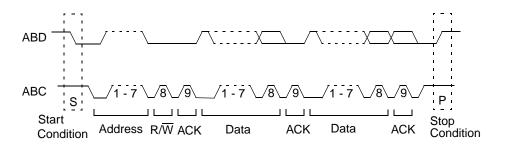


Figure 5-17. A Complete ACCESS.bus Data Transaction

Sending the Address Byte

When the device is the active master of the ACCESS.bus (ACBST[1] is set), it can send the address on the bus.

The address sent should not be the device's own address, as defined by ACBADDR[6:0] if ACBADDR[7] is set, nor should it be the global call address if ACBST[3] is set.

To send the address byte, use the following sequence:

- For a receive transaction where the software wants only one byte of data, it should set ACBCTL1[4]. If only an address needs to be sent or if the device requires stall for some other reason, set ACBCTL1[7].
- Write the address byte (7-bit target device address) and the direction bit to the ACBSDA register. This causes the ACB to generate a transaction. At the end of this transaction, the acknowledge bit received is copied to ACBST[4]. During the transaction, the ABD and ABC lines are continuously checked for conflict with other devices. If a conflict is detected, the transaction is aborted, ACBST[5] is set and ACBST[1] is cleared.
- 3) If ACBCTL1[7] is set and the transaction was successfully completed (i.e., both ACBST[5] and ACBST[4] are cleared), ACBST[3] is set. In this case, the ACB stalls any further ACCESS.bus operations (i.e., holds ABC low). If ACBCTL1[2] is set, it also sends an interrupt request to the host.
- 4) If the requested direction is transmit and the start transaction was completed successfully (i.e., neither ACBST[5] nor ACBST[4] is set, and no other master has accessed the device), ACBST[6] is set to indicate that the ACB awaits attention.
- 5) If the requested direction is receive, the start transaction was completed successfully and ACBCTL1[7] is cleared, the ACB starts receiving the first byte automatically.
- 6) Check that both ACBST[5] and ACBST[4] are cleared. If ACBCTL1[2] is set, an interrupt is generated when ACBST[5] or ACBST[4] is set.

Master Transmit

After becoming the bus master, the device can start transmitting data on the ACCESS.bus.

To transmit a byte in an interrupt or polling controlled operation, the software should:

- Check that both ACBST[5] and ACBST[4] are cleared, and that ACBST[6] is set. If ACBCTL1[7] is set, also check that ACBST[3] is cleared (and clear it if required).
- 2) Write the data byte to be transmitted to the ACBSDA.

When either ACBST[5] or ACBST[4] is set, an interrupt is generated. When the slave responds with a negative acknowledge, ACBST[4] Register is set and ACBST[6] remains cleared. In this case, if ACBCTL1[2] Register is set, an interrupt is issued.

Master Receive

After becoming the bus master, the device can start receiving data on the ACCESS.bus.

To receive a byte in an interrupt or polling operation, the software should:

- 1) Check that ACBST[6] is set and that ACBST[5] is cleared. If ACBCTL1[7] is set, also check that the ACBST[3] is cleared (and clear it if required).
- Set ACBCTL1[4] to 1, if the next byte is the last byte that should be read. This causes a negative acknowledge to be sent.
- 3) Read the data byte from the ACBSDA.

Before receiving the last byte of data, set ACBCTL1[4].

5.7.7.1 Master Stop

To end a transaction, set the ACBCTL1[1] before clearing the current stall flag (i.e., ACBST[6], ACBST[4], or ACBST[3]). This causes the ACB to send a Stop Condition immediately, and to clear ACBCTL1[1]. A Stop Condition may be issued only when the device is the active bus master (i.e., ACBST[1] is set).

Master Bus Stall

The ACB can stall the ACCESS.bus between transfers while waiting for the host response. The ACCESS.bus is stalled by holding the AB1C signal low after the acknowledge cycle. Note that this is interpreted as the beginning of the following bus operation. The user must make sure that the next operation is prepared before the flag that causes the bus stall is cleared.

The flags that can cause a bus stall in master mode are:

- Negative acknowledge after sending a byte (ACBST[4] = 1).
- ACBST[6] bit is set.
- ACBCTL1[7] = 1, after a successful start (ACBST[3] = 1).

Repeated Start

A repeated start is performed when the device is already the bus master (ACBST[1] is set). In this case, the ACCESS.bus is stalled and the ACB awaits host handling due to: negative acknowledge (ACBST[4] = 1), empty buffer (ACBST[6] = 1) and/or a stall after start (ACBST[3] 1).

For a repeated start:

- Set \ACBCTL1[0] to 1.
- In master receive mode, read the last data item from ACBSDA.
- Follow the address send sequence, as described previously in "Sending the Address Byte". If the ACB was awaiting handling due to ACBST[3] = 1, clear it only after writing the requested address and direction to ACBSDA.

Master Error Detection

The ACB detects illegal Start or Stop Conditions (i.e., a Start or Stop Condition within the data transfer, or the acknowledge cycle) and a conflict on the data lines of the ACCESS.bus. If an illegal condition is detected, ACBST[5] is set, and master mode is exited (ACBST[1] is cleared).

Bus Idle Error Recovery

When a request to become the active bus master or a restart operation fails, ACBST[5] is set to indicate the error. In some cases, both the device and the other device may identify the failure and leave the bus idle. In this case, the start sequence may be incomplete and the ACCESS.bus may remain deadlocked.

To recover from deadlock, use the following sequence:

- 1) Clear ACBST[5] and ACBCST[1].
- Wait for a timeout period to check that there is no other active master on the bus (i.e., ACBCST[1] remains cleared).
- Disable, and re-enable the ACB to put it in the nonaddressed slave mode. This completely resets the functional block.

At this point, some of the slaves may not identify the bus error. To recover, the ACB becomes the bus master: it asserts a Start Condition, sends an address byte, then asserts a Stop Condition which synchronizes all the slaves.

5.7.8 Slave Mode

A slave device waits in idle mode for a master to initiate a bus transaction. Whenever the ACB is enabled and it is not acting as a master (i.e., ACBST[1] is cleared), it acts as a slave device.

Once a Start Condition on the bus is detected, the device checks whether the address sent by the current master matches either:

• The ACBADDR[6:0] value if ACBADDR[7] = 1.

or

• The general call address if ACBCTL1[5] 1.

This match is checked even when ACBST[1] is set. If a bus conflict (on ABD or ABC) is detected, ACBST[5] is set, ACBST[1] is cleared and the device continues to search the received message for a match.

If an address match or a global match is detected:

- The device asserts its ABD pin during the acknowledge cycle.
- ACBCST[2] and ACBST[2] are set. If ACBST[0] = 1 (i.e., slave transmit mode) ACBST[6] is set to indicate that the buffer is empty.

- If ACBCTL1[2] is set, an interrupt is generated if both ACBCTL1[2] and ACBCTL16 are set.
- 4) The software then reads ACBST[0] to identify the direction requested by the master device. It clears ACBST[2] so future byte transfers are identified as data bytes.

Slave Receive and Transmit

Slave receive and transmit are performed after a match is detected and the data transfer direction is identified. After a byte transfer, the ACB extends the acknowledge clock until the software reads or writes ACBSDA. The receive and transmit sequences are identical to those used in the master routine.

Slave Bus Stall

When operating as a slave, the device stalls the ACCESS.bus by extending the first clock cycle of a transaction in the following cases:

- · ACBST[6] is set.
- · ACBST[2] and ACBCTL1[6] are set.

Slave Error Detection

The ACB detects illegal Start and Stop Conditions on the ACCESS.bus (i.e., a Start or Stop Condition within the data transfer or the acknowledge cycle). When this occurs, ACBST[5] is set and ACBCST[3:2] are cleared, setting the ACB as an unaddressed slave.

5.7.9 Configuration

ABD and ABC Signals

The ABD and ABC are open-drain signals. The device permits the user to define whether to enable or disable the internal pull-up of each of these signals.

ACB Clock Frequency

The ACB permits the user to set the clock frequency for the ACCESS.bus clock. The clock is set by the ACBCTL2[7:1], which determines the ABC clock period used by the device. This clock low period may be extended by stall periods initiated by the ACB or by another ACCESS.bus device. In case of a conflict with another bus master, a shorter clock high period may be forced by the other bus master until the conflict is resolved.

5.7.10 ACB Registers

Each functional block is associated with a Logical Device Number (LDN) (see Section 5.3.2 "Banked Logical Device Registers" on page 108). ACCESS.Bus Port 1 is assigned as LDN 05h and ACCESS.bus Port 2 as LDN 06h. In addition to the registers listed here, there are additional configuration registers listed in Section 5.4.2.5 "LDN 05h and 06h - ACCESS.bus Ports 1 and 2" on page 119.

Table 5-31. ACB Register Map

Offset	Туре	Name	Reset Value
00h	R/W	ACBSDA. ACB Serial Data	xxh
01h	R/W	ACBST. ACB Status	00h
02h	R/W	ACBCST. ACB Control Status	00h
03h	R/W	ACBCTL1. ACB Control 1	00h
04h	R/W	ACBADDR. ACB Own Address	xxh
05h	R/W	ACBCTL2. ACB Control 2	00h

Table 5-32. ACB Registers

Bit	Description	
Offset 00h	ACB Serial Data Register - ACBSDA (R/W)	Reset Value: xxh
7:0	ACB Serial Data. This shift register is used to transmit and receive data. The most significant bit is transmitted (received) first, and the least significant bit is transmitted last. Reading or writing to ACBSDA is allowed only when ACBST[6] is set, or for repeated starts after setting the ACBCTL1[0]. An attempt to access the register in other cases may produce unpredictable results.	
Offset 01h	ACB Status Register - ACBST (R/W)	Reset Value: 00h
	ad register with a special clear. Some of its bits may be cleared by software, as described below. This rastatus. On reset, and when the ACB is disabled, ACBST is cleared (00h).	egister maintains the
7	SLVSTP (Slave Stop). (R/W1C) Writing 0 to SLVSTP is ignored.	
	0: Writing 1 or ACB disabled.	
	1: Stop Condition detected after a slave transfer in which ACBCST[2] or ACBCST[3] was set.	
6	SDAST (SDA Status). (RO)	
	0: Reading from ACBSDA during a receive, or when writing to it during a transmit. When ACBCTL1[0 SDA does not clear SDAST. This enables ACB to send a repeated start in master receive mode.] is set, reading ACB-
	1: SDA Data Register awaiting data (transmit - master or slave) or holds data that should be read (red slave).	ceive - master or
5	BER (Bus Error). (R/W1C) Writing 0 to this bit is ignored.	
	0: Writing 1 or ACB disabled.	
	1: Start or Stop Condition detected during data transfer (i.e., Start or Stop Condition during the transf acknowledge cycle), or when an arbitration problem detected.	er of bits [8:2] and
4	NEGACK (Negative Acknowledge). (R/W1C) Writing 0 to this bit is ignored.	
	0: Writing 1 or ACB disabled.	
	1: Transmission not acknowledged on the ninth clock (In this case, SDAST (bit 6) is not set).	
3	STASTR (Stall After Start). (R/W1C) Writing 0 to this bit is ignored.	
	0: Writing 1 or ACB disabled.	
	1: Address sent successfully (i.e., a Start Condition sent without a bus error, or Negative Acknowledg set. This bit is ignored in slave mode. When STASTR is set, it stalls the ACCESS.bus by pulling do suspends any further action on the bus (e.g., receive of first byte in master receive mode). In additiset, it also causes the ACB to send an interrupt.	wn the ABC line, and



Table 5-32. ACB Registers (Continued)

Bit	Description Table 5-32. ACB Registers (Continued)	
	7	
2	NMATCH (New Match). (R/W1C) Writing 0 to this bit is ignored. If ACBCTL1[2] is set, an interrupt is sent when this bit is set.	
	0: Software writes 1 to this bit.	
	1: Address byte follows a Start Condition or a repeated start, causing a match or a global-call match.	
1	MASTER. (RO)	
	0: Arbitration loss (BER, bit 5, is set) or recognition of a Stop Condition.	
	1: Bus master request succeeded and master mode active.	
0	XMIT (Transmit). (RO) Direction bit.	
	0: Master/slave transmit mode not active.	
	1: Master/slave transmit mode active.	
-	ACB Control Status Register - ACBCST (R/W) Reset Value: 00h er configures and controls the ACB functional block. It maintains the current ACB status and controls several ACB functions. and when the ACB is disabled, the non-reserved bits of ACBCST are cleared.	
7:6	Reserved.	
5	TGABC (Toggle ABC Line). (R/W) Enables toggling the ABC line during error recovery.	
	0: Clock toggle completed.	
	1: When the ABD line is low, writing 1 to this bit toggles the ABC line for one cycle. Writing 1 to TGABC while ABD is high is ignored.	
4	TSDA (Test ABD Line). (RO) Reads the current value of the ABD line. It can be used while recovering from an error condition in which the ABD line is constantly pulled low by an out-of-sync slave. Data written to this bit is ignored.	
3	GCMTCH (Global Call Match). (RO)	
	0: Start Condition or repeated Start and a Stop Condition (including illegal Start or Stop Condition).	
	1: In slave mode, ACBCTL1.GCMEN is set and the address byte (the first byte transferred after a Start Condition) is 00h.	
2	MATCH (Address Match). (RO)	
	0: Start Condition or repeated Start and a Stop Condition (including illegal Start or Stop Condition).	
	1: ACBADDR[7] is set and the first 7 bits of the address byte (the first byte transferred after a Start Condition) match the 7-bit address in ACBADDR.	
1	BB (Bus Busy). (R/W1C)	
	0: Writing 1, ACB disabled, or Stop Condition detected.	
	1: Bus active (a low level on either ABD or ABC), or Start Condition.	
0	BUSY. (RO) This bit should always be written 0. This bit indicates the period between detecting a Start Condition and completing receipt of the address byte. After this, the ACB is either free or enters slave mode.	
	0: Completion of any state below or ACB disabled.	
	ACB is in one of the following states: -Generating a Start Condition	
	-Master mode (ACBST[1] is set) -Slave mode (ACBCST[2] or ACBCST[3] set).	
Offset 03l		
7	STASTRE (Stall After Start Enable).	
	0: When cleared, ACBST[3] can not be set. However, if ACBST[3] is set, clearing STASTRE does not clear ACBST[3].	
	1: Stall after start mechanism enabled, and ACB stalls the bus after the address byte.	
6	NMINTE (New Match Interrupt Enable).	
	0: No interrupt issued on a new match.	
	1: Interrupt issued on a new match only if ACBCTL1[2] set.	
5	GCMEN (Global Call Match Enable).	
	0: Global call match disabled.	
	1: Global call match enabled.	

Table 5-32. ACB Registers (Continued)

Bit	Description	
4	ACK (Acknowledge). This bit is ignored in transmit mode. When the device acts as a receiver (slave or master), this bit holds the stop transmitting instruction that is transmitted during the next acknowledge cycle.	
	0: Cleared after acknowledge cycle.	
	1: Negative acknowledge issued on next received byte.	
3	eserved.	
2	INTEN (Interrupt Enable).	
	0: ACB interrupt disabled.	
	1: ACB interrupt enabled. An interrupt is generated in response to one of the following events: -Detection of an address match (ACBST[2] = 1) and ACBCTL1[6] = 1. -Receipt of Bus Error (ACBST[5] = 1). -Receipt of Negative Acknowledge after sending a byte (ACBST[4] = 1). -Acknowledge of each transaction (same as the hardware set of the ACBST[6]). -In master mode if ACBCTL1[7] = 1, after a successful start (ACBST[3] = 1). -Detection of a Stop Condition while in slave mode (ACBST[7] = 1).	
1	STOP (Stop).	
	0: Automatically cleared after Stop issued.	
	1: Setting this bit in master mode generates a Stop Condition to complete or abort current message transfer.	
0	START (Start). Set this bit only when in master mode or when requesting master mode.	
	0: Cleared after Start Condition sent or Bus Error (ACBST[5] = 1) detected.	
	Single or repeated Start Condition generated on the ACCESS.bus. If the device is not the active master of the bus (ACBST[1] = 0), setting START generates a Start Condition when the ACCESS.bus becomes free (ACBCST[1] = 0). An address transmission sequence should then be performed.	
	If the device is the active master of the bus (ACBST[1] = 1), setting START and then writing to ACBSDA generates a Start Condition. If a transmission is already in progress, a repeated Start Condition is generated. This condition can be used to switch the direction of the data flow between the master and the slave, or to choose another slave device without separating them with a Stop Condition.	
Offset 04h	ACB Own Address Register - ACBADDR (R/W) Reset Value: xxh	
7	SAEN (Slave Address Enable).	
	0: ACB does not check for an address match with ACBADDR[6:0].	
	1: ACBADDR[6:0] holds a valid address and enables the match of ADDR to an incoming address byte.	
6:0	ADDR (Address). These bits hold the 7-bit device address of the SC3200. When in slave mode, the first 7 bits received after a Start Condition are compared with this field (first bit received is compared with bit 6, and the last bit with bit 0). If the address field matches the received data and ACBADDR[7] is 1, a match is declared.	
Offset 05h	ACB Control Register 2 - ACBCTL2 (R/W) er enables/disables the functional block and determines the ACB clock rate.	
7:1	ABCFRQ (ABC Frequency). This field defines the ABC period (low and high time) when the device serves as a bus master. The clock low and high times are defined as follows:	
	tABCI = tABCh = 2*ABCFRQ*tCLK	
	where tCLK is the module input clock cycle, as defined in the Section 5.2 "Module Architecture" on page 107.	
	ABCFRQ can be programmed to values in the range of 0001000b through 1111111b. Using any other value has unpredictable results.	
0	EN (Enable).	
0		
0	0: ACB is disabled, ACBCTL1, ACBST and ACBCST registers are cleared, and clocks are halted.	

SuperI/O Module Revision 5.1 AMD

5.8 Legacy Functional Blocks

This section briefly describes the following blocks that provide legacy device functions:

- Parallel Port. (Similar to Parallel Port in the National Semiconductor PC87338.)
- Serial Port 1 and Serial Port 2 (SP1 and SP2), UART functionality for both SP1 and SP2. (Similar to SCC1 in the National Semiconductor PC87338.)
- Infrared Communications Port / Serial Port 3 functionality. (Similar to SCC2 in the National Semiconductor PC87338.)

The description of each Legacy block includes a general description, register maps, and bit maps.

5.8.1 Parallel Port

The Parallel Port supports all IEEE1284 standard communication modes: Compatibility (known also as Standard or SPP), Bidirectional (known also as PS/2), FIFO, EPP (known also as Mode 4) and ECP (with an optional Extended ECP mode).

5.8.1.1 Parallel Port Register and Bit Maps

The Parallel Port register maps (Table 5-33 and Table 5-34) are grouped according to first and second level offsets. EPP and second level offset registers are available only when the base address is 8-byte aligned.

Parallel Port functional block bit maps are shown in Table 5-35 and Table 5-36.

Table 5-33. Parallel Port Register Map for First Level Offset

First Level Offset	Туре	Name	Modes (ECR Bits) 7 6 5
000h	R/W	DATAR. PP Data	000 or 001
000h	W	AFIFO. ECP Address FIFO	011
001h	RO	DSR. Status	All Modes
002h	R/W	DCR. Control	All Modes
003h	R/W	ADDR. EPP Address	100
004h	R/W	DATA0. EPP Data Port 0	100
005h	R/W	DATA1. EPP Data Port 1	100
006h	R/W	DATA2. EPP Data Port 2	100
007h	R/W	DATA3. EPP Data Port 3	100
400h	W	CFIFO. PP Data FIFO	010
400h	R/W	DFIFO. ECP Data FIFO	011
400h	R/W	TFIFO. Test FIFO	110
400h	RO	CNFGA. Configuration A	111
401h	RO	CNFGB. Configuration B	111
402h	R/W	ECR. Extended Control	All Modes
403h	R/W	EIR. Extended Index	All Modes
404h	R/W	EDR. Extended Data	All Modes
405h	R/W	EAR. Extended Auxiliary Status	All Modes

Table 5-34. Parallel Port Register Map for Second Level Offset

Second Level Offset	Туре	Name
00h	R/W	Control0. Control Register 0
02h	R/W	Control2. Control Register 2
04h	R/W	Control4. Control Register 4
05h	R/W	PP Confg0. Parallel Port Configuration Register 0

Table 5-35. Parallel Port Bit Map for First Level Offset

					В	its					
Offset	Name	7	6	5	4	3	2	1	0		
000h	DATAR		Data Bits								
	AFIFO				Addre	ess Bits					
001h	DSR	Printer Status	ACK# Status	PE Status	SLCT Status	ERR# Status	RS	RSVD			
002h	DCR	RS	RSVD		Interrupt Enable	PP Input Control	Printer Initialization Control	Automatic Line Feed Control	Data Strobe Control		
003h	ADDR			EPP Dev	ice or Registe	r Selection Ad	dress Bits				
004h	DATA0				EPP Device	or R/W Data					
005h	DATA1				EPP Device	or R/W Data					
006h	DATA2				EPP Device	or R/W Data					
007h	DATA3				EPP Device	or R/W Data					
400h	CFIFO				Data	a Bits					
400h	DFIFO				Data	a Bits					
400h	TFIFO				Data	a Bits					
400h	CNFGA		RS	SVD		Bit 7 of PP Confg0		RSVD			
401h	CNFGB	RSVD	Interrupt Request Value		Interrupt Seled	ct	RSVD	DMA Char	nnel Select		
402h	ECR	EC						FIFO Full	FIFO Empty		
403h	EIR			RSVD			Sec	cond Level Off	fset		
404h	EDR				Data	a Bits					
405h	EAR	FIFO Tag				RSVD					

Table 5-36. Parallel Port Bit Map for Second Level Offset

			Bits							
Offset	Name	7	6	5	4	3	2	1	0	
00h	Control0	RS	VD	DCR Reg- ister Live	Freeze Bit		RSVD	EPP Time- out Inter- rupt Mask		
02h	Control2	SPP Compatibility	Channel Address Enable	RSVD	Revision 1.7 or 1.9 Select		RSVD			
04h	Control4	RSVD	PP DMA	Request Inac	tive Time	RSVD	PP DMA	Request Act	ive Time	
05h	PP Confg0	Bit 3 of CNFGA	Demand DMA Enable	ECP IRQ Channel Number PE Internal PU or Number PD						

SuperI/O Module Revision 5.1 AMD

5.8.2 UART Functionality (SP1 and SP2)

Both SP1 and SP2 provide UART functionality. The generic SP1 and SP2 support serial data communication with remote peripheral device or modem using a wired interface. The functional blocks can function as a standard 16450, 16550, or as an Extended UART.

5.8.2.1 UART Mode Register Bank Overview

Four register banks, each containing eight registers, control UART operation. All registers use the same 8-byte address space to indicate offsets 00h through 07h. The BSR register selects the active bank and is common to all banks. See Figure 5-18.

5.8.2.2 SP1 and SP2 Register and Bit Maps for UART Functionality

The tables in this subsection provide register and bit maps for Banks 0 through 3.

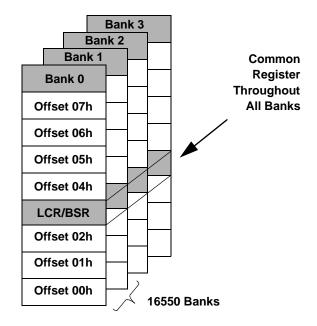


Figure 5-18. UART Mode Register Bank Architecture

Offset	Туре	Name
00h	RO	RXD. Receiver Data Port
	W	TXD. Transmitter Data Port
01h	R/W	IER. Interrupt Enable
02h	RO	EIR. Event Identification (Read Cycles)
	R/W	FCR. FIFO Control (Write Cycles)
03h	W	LCR ¹ . Line Control
	R/W	BSR ¹ .Bank Select
04h	R/W	MCR. Modem/Mode Control
05h	R/W	LSR. Link Status
06h	R/W	MSR. Modem Status
07h	R/W	SPR. Scratchpad
	R/W	ASCR. Auxiliary Status and Control

Table 5-37. Bank 0 Register Map

^{1.} When bit 7 of this register is set to 1, bits [6:0] of BSR select the bank, as shown in Table 5-38.

Table 5-38. Bank Selection Encoding

			BSR	Bits				
7	6	5	Bank Selected					
0	х	х	х	х	х	х	х	0
1	0	х	х	Х	х	х	х	1
1	1	х	х	Х	х	1	х	1
1	1	х	х	х	х	х	1	1
1	1	1	0	0	0	0	0	2
1	1	1	0	0	1	0	0	3

Table 5-39. Bank 1 Register Map

Offset	Туре	Name
00h	R/W	LBGD(L). Legacy Baud Generator Divisor Port (Low Byte)
01h	R/W	LBGD(H). Legacy Baud Generator Divisor Port (High Byte)
02h		RSVD. Reserved
03h	W	LCR ¹ . Line Control
	R/W	BSR ¹ . Bank Select
04h-07h		RSVD. Reserved

^{1.} When bit 7 of this register is set to 1, bits [6:0] of BSR select the bank, as shown in Table 5-38 on page 148.

Table 5-40. Bank 2 Register Map

Offset	Туре	Name
00h	R/W	BGD(L). Baud Generator Divisor Port (Low Byte)
01h	R/W	BGD(H). Baud Generator Divisor Port (High Byte)
02h	R/W	EXCR1. Extended Control1
03h	R/W	BSR. Bank Select
04h	R/W	EXCR2. Extended Control 2
05h		RSVD. Reserved
06h	RO	RXFLV. RX_FIFO Level
07h	RO	TXFLV. TX_FIFO Level

Table 5-41. Bank 3 Register Map

Offset	Туре	Name
00h	RO	MRID. Module and Revision ID
01h	RO	SH_LCR. Shadow of LCR
02h	RO	SH_FCR. Shadow of FIFO Control
03h	R/W	BSR. Bank Select
04h-07h		RSVD. Reserved

Revision 5.1 AMD

Table 5-42. Bank 0 Bit Map

Re	gister				Ві	its				
Offset	Name	7	6	5	4	3	2	1	0	
00h	RXD			R	XD[7:0] (Rece	eiver Data Bits)				
	TXD			T	(D[7:0] (Trans	mitter Data Bi	ts)			
01h	IER ¹		RS	SVD		MS_IE	LS_IE	TXLDL_IE	RXHDL_IE	
	IER ²	RS	VD	TXEMP_IE	RSVD ³ /	MS_IE	LS_IE	TXLDL_IE	RXHDL_IE	
					DMA_IE ⁴					
02h	EIR ¹	FEN	FEN[1:0]		VD	RXFT	IPR1	IPR0	IPF	
	EIR ²	RSVD		TXEMP_EV	RSVD 3/	MS_EV	LS_EV or	TXLDL_EV	RXHDL_EV	
					DMA_EV 4		TXHLT_EV			
	FCR	RXFT	H[1:0]	TXFTI	H[1:0]	RSVD	TXSR	RXSR	FIFO_EN	
03h	LCR ⁵	BKSE	SBRK	STKP	EPS	PEN	STB	WLS	[1:0]	
	BSR ⁵	BKSE			BSR	[6:0] (Bank Select)				
04h	MCR ¹		RSVD		LOOP	ISEN or DCDLP	RILP	RTS	DTR	
	MCR ²		RS	SVD		TX_DFR	RSVD	RTS	DTR	
05h	LSR	ER_INF	TXEMP	TXRDY	BRK	FE	PE	OE	RXDA	
06h	MSR	DCD	RI	DSR	CTS	DDCD	TERI	DDSR	DCTS	
07h	SPR ¹				Scratc	h Data				
	ASCR ²	RSVD	TXUR ⁴	RXACT ⁴	RXWDG ⁴	RSVD	S_OET ⁴	RSVD	RXF_TOUT	

- 1. Non-Extended Mode.
- 2. Extended Mode.
- 3. In SP1 only.

SuperI/O Module

- 4. In SP2 only.
- 5. When bit 7 of this register is set to 1, bits [6:0] of BSR select the bank, as shown in Table 5-38 on page 148.

Table 5-43. Bank 1 Bit Map

Re	gister				Ві	its						
Offset	Name	7	6	6 5 4 3 2 1 0								
00h	LBGD(L)				LBGD[7:0]	(Low Byte)		•				
01h	LBGD(H)		LBGD[15:8] (High Byte)									
02h	RSVD				Rese	erved						
03h	LCR ¹	BKSE	SBRK	STKP	EPS	PEN	STB	WLS	6[1:0]			
	BSR ¹	BKSE		BSR[6:0] (Bank Select)								
04h-07h	RSVD				Rese	erved						

1. When bit 7 of this register is set to 1, bits [6:0] of BSR select the bank, as shown in Table 5-38 on page 148.

Table 5-44. Bank 2 Bit Map

			<u> </u>								
Re	gister		Bits								
Offset	Name	7	6 5 4 3 2 1 (
00h	BGD(L)				BGD[7:0]	(Low Byte)					
01h	BGD(H)				BGD [15:8]] (High Byte)					
02h	EXCR1	BTEST	RSVD	ETDLBK	LOOP		RSVD		EXT_SL		
03h	BSR	BKSE			BSF	R[6:0] (Bank S	elect)				
04h	EXCR2	LOCK	RSVD	PRES	SL[1:0]		RS	SVD			
05h	RSVD				Res	erved					
06h	RXFLV		RSVD RFL[4:0]								
07h	TXFLV		RSVD TFL[4:0]								

Table 5-45. Bank 3 Bit Map

Re	gister	Bits							
Offset	Name	7	6	5	4	3	2	1	0
00h	MRID		MID	[3:0]	•	RID[3:0]			
01h	SH_LCR	BKSE	SBRK	STKP	EPS	PEN	STB	WLS	S[1:0]
02h	SH_FCR	RXFT	H[1:0]	TXFH	IT[1:0]	RSVD	TXSR	RXSR	FIFO_EN
03h	BSR	BKSE	BSR[6:0] (Bank Select)						
04h-07h	RSVD				RS	SVD			

SuperI/O Module Revision 5.1 AMD

5.8.3 IR Communications Port (IRCP) / Serial Port 3 (SP3) Functionality

This section describes the IRCP/SP3 support registers. The IRCP/SP3 functional block provides advanced, versatile serial communications features with IR capabilities.

The IRCP/SP3 also supports two DMA channels; the functional block can use either one or both of them. One channel is required for IR-based applications, since IR communication works in half duplex fashion. Two channels would normally be needed to handle high-speed full duplex IR based applications.

The IRCP or Serial Port 3 is chosen via bit 6 of the PMR Register (see Section 4.2 "Multiplexing, Interrupt Selection, and Base Address Registers" on page 88).

5.8.3.1 IR/SP3 Mode Register Bank Overview

Eight register banks, each containing eight registers, control IR/SP3 operation. All registers use the same 8-byte address space to indicate offsets 00h through 07h. The BSR register selects the active bank and is common to all banks. See Figure 5-19.

5.8.3.2 IRCP/SP3 Register and Bit Maps

The tables in this subsection provide register and bit maps for Banks 0 through 7.

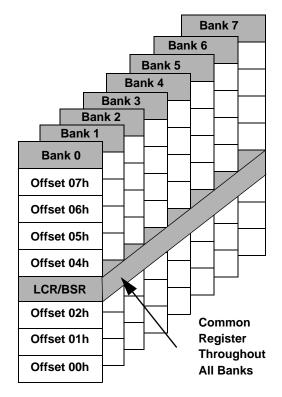


Figure 5-19. IRCP/SP3 Register Bank Architecture

Offset	Туре	Name		
00h	RO	RXD. Receive Data Port		
	W	TXD. Transmit Data Port		
01h	R/W	IER. Interrupt Enable		
02h	RO	EIR. Event Identification		
	R/W	FCR. FIFO Control		
03h	W	LCR ¹ . Link Control		
	R/W	BSR ¹ . Bank Select		
04h	R/W	MCR. Modem/Mode Control		
05h	R/W	LSR. Link Status		
06h	R/W	MSR. Modem Status		
07h	R/W	SPR. Scratchpad		
	R/W	ASCR. Auxiliary Status and Control		

Table 5-46. Bank 0 Register Map

^{1.} When bit 7 of this register is set to 1, bits [6:0] of BSR select the bank, as shown in Table 5-47.

Table 5-47. Bank Selection Encoding

			BSR	Bits					
7	6	5	4	3	2	1	0	Bank Selected	Functionality
0	Х	Х	Х	Х	Х	Х	Х	0	UART + IR
1	0	х	х	х	х	х	х	1	
1	1	х	х	х	х	1	х	1	
1	1	х	х	х	х	х	1	1	
1	1	1	0	0	0	0	0	2	
1	1	1	0	0	1	0	0	3	
1	1	1	0	1	0	0	0	4	IR Only
1	1	1	0	1	1	0	0	5	
1	1	1	1	0	0	0	0	6	
1	1	1	1	0	1	0	0	7	

Table 5-48. Bank 1 Register Map

Offset	Туре	Name
00h	R/W	LBGD(L). Legacy Baud Generator Divisor Port (Low Byte)
01h	R/W	LBGD(H). Legacy Baud Generator Divisor Port (High Byte)
02h		RSVD. Reserved
03h	W	LCR ¹ . Link Control
	R/W	BSR ¹ . Bank Select
04h-07h		RSVD. Reserved

^{1.} When bit 7 of this register is set to 1, bits [6:0] of BSR select the bank, as shown in Table 5-47.

Table 5-49. Bank 2 Register Map

Offset	Туре	Name
00h	R/W	BGD(L). Baud Generator Divisor Port (Low Byte)
01h	R/W	BGD(H). Baud Generator Divisor Port (High Byte)
02h	R/W	EXCR1. Extended Control 1
03h	R/W	BSR. Bank Select
04h	R/W	EXCR2. Extended Control 2
05h		RSVD. Reserved
06h	RO	TXFLV. TX FIFO Level
07h	RO	RXFLV. RX FIFO Level

SuperI/O Module Revision 5.1

Table 5-50. Bank 3 Register Map

Offset	Туре	Name
00h	RO	MID. Module and Revision Identification
01h	RO	SH_LCR. Link Control Shadow
02h	RO	SH_FCR. FIFO Control Shadow
03h	R/W	BSR. Bank Select
04h-07h		RSVD. Reserved

Table 5-51. Bank 4 Register Map

Offset	Туре	Name
00h	RO	TMR(L). TImer (Low Byte)
01h	RO	TMR(H). Timer (High Byte)
02h	R/W	IRCR1. IR Control 1
03h	R/W	BSR. Bank Select
04h	R/W	TFRL(L). Transmission Frame Length (Low Byte)
	RO	TFRCC(L). Transmission Current Count (Low Byte)
05h	R/W	TFRL(H). Transmission Frame Length (High Byte)
	RO	TFRCC(H). Transmission Current Count (High Byte)
06h	R/W	RFRML(L). Reception Frame Maximum Length (Low Byte)
	RO	RFRCC(L). Reception Frame Current Count (Low Byte)
07h	R/W	RFRML(H). Reception Frame Maximum Length (High Byte)
	RO	RFRCC(H). Reception Frame Current Count (High Byte)

Table 5-52. Bank 5 Register Map

Offset	Туре	Name
00h	R/W	SPR3. Scratchpad 2
01h	R/W	SPR3. Scratchpad 3
02h	R/W	RSVD. Reserved
03h	R/W	BSR. Bank Select
04h	R/W	IRCR2. IR Control 2
05h	RO	FRM_ST. Frame Status
06h	RO	RFRL(L). Received Frame Length (Low Byte)
	RO	LSTFRC. Lost Frame Count
07h	RO	RFRL(H). Received Frame Length (High Byte)



Table 5-53. Bank 6 Register Map

Offset	Туре	Name
00h	R/W	IRCR3. IR Control 3
01h	R/W	MIR_PW. MIR Pulse Width
02h	R/W	SIR_PW. SIR Pulse Width
03h	R/W	BSR. Bank Select
04h	R/W	BFPL. Beginning Flags/Preamble Length
05h-07h		RSVD. Reserved

Table 5-54. Bank 7 Register Map

Offset	Туре	Name
00h	R/W	IRRXDC. IR Receiver Demodulator Control
01h	R/W	IRTXMC. IR Transmitter Modulator Control
02h	R/W	RCCFG. Consumer IR (CEIR) Configuration
03h	R/W	BSR. Bank Select
04h	R/W	IRCFG1. IR Interface Configuration 1
05h-06h		RSVD. Reserved
07h	R/W	IRCFG4. IR Interface Configuration 4

Table 5-55. Bank 0 Bit Map

Re	gister	Bits								
Offset	Name	7	6	5	4	3	2	1	0	
00h	RXD				RXD[7:0] (R	eceive Data)				
	TXD				TXD[7:0] (Tr	ansmit Data)				
01h	IER ¹		RS	SVD		MS_IE	LS_IE	TXLDL_IE	RXHDL_IE	
	IER ²	TMR_IE	SFIF_IE	TXEMP_ IE/PLD_IE	DMA_IE	MS_IE	LS_IE	TXLDL_IE	RXHDL_IE	
02h	EIR ¹	FEN	[1:0]	RS	VD	RXFT	IPR	[1:0]	IPF	
	EIR ²	TMR_EV	SFIF_EV	TXEMP_EV/ PLD_EV	DMA_EV	MS_EV	LS_EV/ TXHLT_EV	TXLDL_EV	RXHDL_EV	
	FCR	RXFT	H[1:0]	TXFT	H[1:0]	RSVD	TXSR	RXSR	FIFO_EN	
03h	LCR	BKSE	SBRK	STKP	EPS	PEN	STB	WLS	3[1:0]	
	BSR	BKSE			BSR	[6:0] (Bank Se	elect)			
04h	MCR ¹		RSVD		LOOP	ISEN/ DCDLP	RILP	RTS	DTR	
	MCR ²		MDSL[2:0]		IR_PLS	TX_DFR	DMA_EN	RTS	DTR	
05h	LSR	ER_INF/ FR_END	TXEMP	TXRDY	BRK/ MAX_LEN	FE/ PHY_ERR	PE/ BAD_CRC	OE	RXDA	
06h	MSR	DCD	RI	DSR	CTS	DDCD	TERI	DDSR	DCTS	
07h	SPR ¹				Scratc	h Data	•	,		
	ASCR ²	CTE/PLD	TXUR	RXACT/ RXBSY	RXWDG/ LOST_FR	TXHFE	S_EOT	FEND_INF	RXF_TOUT	

^{1.} Non-extended mode.

^{2.} Extended mode.

SuperI/O Module Revision 5.1

Table 5-56. Bank 1 Bit Map

Re	gister	Bits								
Offset	Name	7	6	5	4	3	2	1	0	
00h	LBGD(L)		LBGD[7:0] (Low Byte Data)							
01h	LBGD(H)		LBGD[15:8] (High Byte Data)							
02h	RSVD				RS	VD				
03h	LCR	BKSE	SBRK	STKP	EPS	PEN	STB	WLS	[1:0]	
	BSR	BKSE		BSR[6:0] (Bank Select)						
04h-07h	RSVD				RS	VD				

Table 5-57. Bank 2 Bit Map

Re	gister	Bits											
Offset	Name	7	6	5	4	3	2	1	0				
00h	BGD(L)				BGD[7:0] (Lc	ow Byte Data)							
01h	BGD(H)		BGD[15:8] (High Byte Data)										
02h	EXCR1	BTEST	RSVD ETDLBK LOOP DMASWP DMATH DMANF EXT_SL										
03h	BSR	BKSE			BSR	R[6:0] (Bank Se	lect)						
04h	EXCR2	LOCK	RSVD	PRES	SL[1:0]	RF_SI	Z[1:0]	TF_S	IZ[1:0]				
05h	RSVD				RS	SVD							
06h	TXFLV	RS	RSVD TFL[5:0]										
07h	RXFLV	RS	VD			RFL	5:0]						

Table 5-58. Bank 3 Bit Map

Re	gister	Bits										
Offset	Name	7	6	5	4	3	2	1	0			
00h	MID		MID	[3:0]			RID	[3:0]				
01h	SH_LCR ¹	RSVD	SBRK	STKP	EPS	PEN	STB	WLS	6[1:0]			
02h	SH_FCR ²	RXFT	H[1:0]	TXFT	H[1:0]	RSVD	TXSR	RXSR	FIFO_EN			
03h	BSR	BKSE	BKSE BSR[6:0] (Bank Select)									
04h-07h	RSVD				Rese	erved						

- LCR Register Value
 FCR Register Value

Table 5-59. Bank 4 Bit Map

Re	egister	Bits											
Offset	Name	7	6	5	4	3	2	1	0				
00h	TMR(L)		TMR[7:0] (Low Byte Data)										
01h	TMR(H)		RSVD TMR[11:8] (High Byte Data)										
02h	IRCR1		RS	SVD		IR_S	CTEST	TMR_EN					
03h	BSR	BKSE			BSR	[6:0] (Bank Se	elect)						
04h	TFRL(L)/ TFRCC(L)			TFRL	[7:0] / TFRCC[7:0] (Low Byte	e Data)						
05h	TFRL(H)/ TFRCC(H)		RSVD TFRL[12:8] / TFRCC[12:8] (High Byte Data)										

Revision 5.1 SuperI/O Module

Table 5-59. Bank 4 Bit Map (Continued)

Re	gister	Bits										
Offset	Name	7	7 6 5 4 3 2 1 0									
06h	RFRML(L)/ RFRCC(L)			RFRML	[7:0] / RFRCC	[7:0] (Low Byt	e Data)					
07h	RFRML(H)/ RFRCC(H)		RSVD RFRML[12:8] / RFRCC[12:8] (High Byte Data)									

Table 5-60. Bank 5 Bit Map

Re	gister	Bits											
Offset	Name	7	6	5	4	3	2	1	0				
00h	SPR2				Scratc	hpad 2							
01h	SPR3				Scratc	hpad 2							
02h	RSVD				RS	VD							
03h	BSR	BKSE			BSR	[6:0] (Bank Se	elect)						
04h	IRCR2	RSVD	SFTSL	FEND_MD	AUX_IRRX	TX_MS	MDRS	IRMSSL	IR_FDPLX				
05h	FRM_ST	VLD	LOST_FR	RSVD	MAX_LEN	PHY_ERR	BAD_CRC	OVR1	OVR2				
06h	RFRL(L)/ LSTFRC			RFRL[7:0] (Low Byte	Data) / LSTF	RC[7:0]						
07h	RFRL(H)	RFRL[15:8] (High Byte Data)											

Table 5-61. Bank 6 Bit Map

<u> </u>													
Re	gister	Bits											
Offset	Name	7	6	5	4	3	2	1	0				
00h	IRCR3	SHDM_DS	SHMD_DS	FIR_CRC	MIR_CRC	RSVD	TXCRC_INV	TXCRC_DS	RSVD				
01h	MIR_PW		RS	VD			MPW	V[3:0]					
02h	SIR_PW		RS	VD		SPW[3:0]							
03h	BSR	BKSE			BSR	SR[6:0] (Bank Select)							
04h	BFPL		MBF	[3:0]		FPL[3:0]							
05h-07h	RSVD	RSVD											

Table 5-62. Bank 7 Bit Map

Re	gister	Bits											
Offset	Name	7	6	5	4	3	2	1	0				
00h	IRRXDC		DBW[2:0] DFR[4:0]										
01h	IRTXMC		MCPW[2:0] MCFR[4:0]										
02h	RCCFG	R_LEN	T_OV	RXHSC	RCDM_DS	RSVD	TXHSC	RC_M	ИD[1:0]				
03h	BSR	BKSE			BSR	[6:0] (Bank Se	elect)						
04h	IRCFG1	STRV_MS		SIRC[2:0]		IRID3		IRIC[2:0]					
05h-06h	RSVD		RSVD										
07h	IRCFG4	RSVD	IRRX_MD	IRSL0_DS	RXINV	IRSL21_DS		RSVD					

Core Logic Module Revision 5.1

Core Logic Module

The Core Logic module is an enhanced PCI-to-Sub-ISA bridge (South Bridge), this module is ACPI-compliant, and provides AT/Sub-ISA functionality. The Core Logic module also contains state-of-the-art power management. Two bus mastering IDE controllers are included for support of up to four ATA-compliant devices. A three-port Universal Serial Bus (USB) provides high speed, and Plug & Play expansion for a variety of new consumer peripheral devices.

6.1 Feature List

Internal Fast-PCI Interface

The internal Fast-PCI bus interface is used to connect the Core Logic and GX1 modules of the SC3200. This interface includes the following features:

- · PCI protocol for transfers on Fast-PCI bus
- Up to 66 MHz operation
- Subtractive decode handled internally in conjunction with external PCI bus

Bus Mastering IDE Controllers

- · Two controllers with support for up to four IDE devices
- Independent timing for master and slave devices for both channels
- PCI bus master burst reads and writes
- Multiword DMA support
- Programmed I/O (PIO) Modes 0-4 support

Universal Serial Bus

- Three independent USB interfaces
- Open Host Controller Interface (OpenHCI) specification compliant

PCI Interface

- PCI 2.1 compliant
- · PCI master for AC97 and IDE controllers
- · Subtractive agent for unclaimed transactions
- Supports PCI initiator-to-Sub-ISA cycle translations

- PCI-to-Sub-ISA interrupt mapper/translator
- · External PCI bus
 - Devices internal to the Core Logic module (IDE, Audio, USB, Sub-ISA, etc.) cannot master to memory through the external PCI bus.
 - Legacy DMA is not supported to memory located on external PCI bus.
 - The Core Logic module does not transfer subtractively decoded I/O cycles originating from the external PCI bus.

AT Compatibility

- 8259A-equivalent interrupt controllers
- 8254-equivalent timer
- 8237-equivalent DMA controllers
- Port A, B, and NMI logic
- Positive decode for AT I/O space

Sub-ISA Interface

- · Boot ROM chip select
- Extended ROM to 16 MB
- Two general-purpose chip selects
- · NAND Flash support
- M-Systems DiskOnChip support
- Is not the subtractive decode agent

Power Management

- Automated CPU 0V Suspend modulation
- I/O Traps and Idle Timers for peripheral power management
- · Software SMI and Stop Clock for APM support
- · ACPI-compliant timer and register set
- Up to 22 GPIOs of which all can generate Power Management Interrupts (PMEs)
- Three Dedicated GPWIOs powered by V_{SBL} and V_{SB}
- Shadow register support for legacy controllers for 0V Suspend

Integrated Audio

- AC97 Version 2.0 compliant interface to audio codecs
- · Secondary codec support
- AMC97 codec support

Video Processor Interface

- · Synchronous serial interface to the Video Processor
- Translates video and clock control register accesses from PCI to serial interface
- Supports both reads and writes of Video Processor registers
- Retries Fast-PCI bus accesses until Core Logic completes the transfer over the serial interface

Low Pin Count (LPC) Interface

- Based on Intel LPC Interface Specification Revision 1.0
- Serial IRQ support

6.2 Module Architecture

The Core Logic architecture provides the internal functional blocks shown in Figure 6-1.

- · Fast-PCI interface to external PCI bus
- IDE controllers (UDMA-33)
- · USB controllers
- · Sub-ISA bus interface
- AT compatibility logic (legacy)
- ACPI compliant power management (includes GPIO interfaces, such as joystick)
- · Integrated audio controller
- · Low Pin Count (LPC) Interface

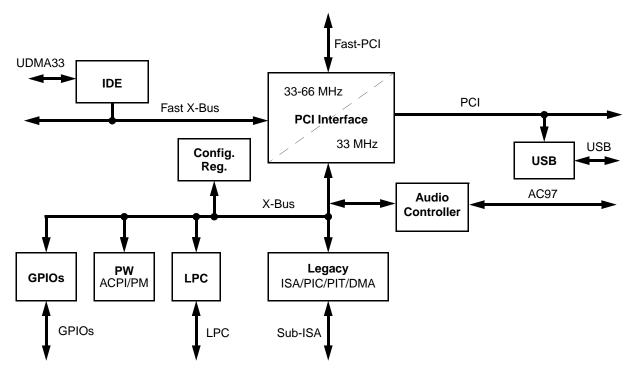


Figure 6-1. Core Logic Module Block Diagram

Core Logic Module Revision 5.1

6.2.1 Fast-PCI Interface to External PCI Bus

The Core Logic module provides a PCI bus interface that is both a slave for PCI cycles initiated by the GX1 module or other PCI master devices, and a non-preemptive master for DMA transfer cycles. It is also a standard PCI master for the IDE controllers and audio I/O logic. The Core Logic supports positive decode for configurable memory and I/O regions, and implements a subtractive decode option for unclaimed PCI accesses. It also generates address and data parity, and performs parity checking. The arbiter for the Fast-PCI interface is located in the GX1 module.

Configuration registers are accessed through the PCI interface using the PCI Bus Type 1 configuration mechanism as described in the PCI Specification.

6.2.1.1 Processor Mastered Cycles

The Core Logic module acts on all processor initiated cycles according to PCI rules for active/subtractive decode using DEVSEL#. Memory writes are automatically posted. Reads are retried if they are *not* destined for actively decoded (i.e., positive decode) devices on the high speed X-Bus or the 33 MHz X-Bus. This means that reads to external PCI, LPC, or Sub-ISA devices are automatically treated as delayed transactions through the PCI retry mechanism. This allows the high bandwidth devices access to the Fast-PCI interface while the response from a slow device is accumulated.

Bursting from the host is not supported.

All types of configuration cycles are supported and handled appropriately according to the PCI specification.

6.2.1.2 External PCI Mastered Cycles

Memory cycles mastered by external PCI devices on the external PCI bus are actively taken if they are to the system memory address range. Memory cycles to system memory are forwarded to the Fast-PCI interface. Burst transfers are stopped on every cache line boundary to allow efficient buffering in the Fast-PCI interface block.

I/O and configuration cycles mastered by external PCI devices which are subtractively decoded by the Core Logic module, are not handled.

6.2.1.3 Core Logic Internal or Sub-ISA Mastered Cycles

Only memory cycles (not I/O cycles) are supported by the internal Sub-ISA or legacy DMA masters. These memory cycles are always forwarded to the Fast-PCI interface.

6.2.1.4 External PCI Bus

The external PCI bus is a fully-compliant PCI bus. PCI slots are connected to this bus. Support for up to two bus masters is provided. The arbiter is in the Core Logic module.

6.2.1.5 Bus Master Request Priority

The Fast-PCI bus supports seven bus masters. The requests (REQs) are fixed in priority. The seven bus masters in order of priority are:

- 1) VIF
- 2) IDE Channel 0
- 3) IDE Channel 1
- 4) Audio
- 5) USB
- 6) External REQ0#
- 7) External REQ1#

6.2.2 PSERIAL Interface

The majority of the system power management logic is implemented in the Core Logic module, but a minimal amount of logic is contained within the GX1 module to provide information that is not externally visible (e.g., graphics controller).

The GX1 module implements a simple serial communications mechanism to transmit the CPU status to the Core Logic module via internal signal PSERIAL. The GX1 module accumulates CPU events in an 8-bit register which it transmits serially every 1 to 10 μ s.

The packet transmitter holds the serial output internal signal (PSERIAL) low until the transmission interval counter has elapsed. Once the counter has elapsed, the PSERIAL signal is held high for two clocks to indicate the start of packet transmission. The contents of the Serial Packet register are then shifted out starting from bit 7 down to bit 0. The PSERIAL signal is held high for one clock to indicate the end of packet transmission and then remains low until the next transmission interval. After the packet transmission is complete, the GX1 module's Serial Packet register's contents are cleared.

The GX1 module's input clock is used as the clock reference for the serial packet transmitter.

Once a bit in the register is set, it remains set until the completion of the next packet transmission. Successive events of the same type that occur between packet transmissions are ignored. Multiple unique events between packet transmissions accumulate in this register. The GX1 module transmits the contents of the serial packet only when a bit in the Serial Packet register is set and the interval counter has elapsed.

The Core Logic module decodes the serial packet after each transmission and performs the power management tasks related to video retrace.

For more information on the Serial Packet register refer to the AMD GeodeTM GX1 Processor Data Book.

6.2.2.1 Video Retrace Interrupt

Bit 7 of the "Serial Packet" can be used to generate an SMI whenever a video retrace occurs within the GX1 module. This function is normally not used for power management but for SoftVGA routines. Setting F0 Index 83h[2] = 1 enables this function. A read only status register located at F1BAR0+I/O Offset 00h[5] can be read to see if the SMI was caused by a video retrace event.

6.2.3 IDE Controller

The Core Logic module integrates a PCI bus mastering, ATA-4 compatible IDE controller. This controller supports UltraDMA, Multiword DMA and Programmed I/O (PIO) modes. Two devices are supported on the IDE controller. The data-transfer speed for each device can be independently programmed. This allows high-speed IDE peripherals to coexist on the same channel as lower speed devices.

The Core Logic module supports two IDE channels, a primary channel and a secondary channel.

The IDE interface provides a variety of features to optimize system performance, including 32-bit disk access, post write buffers, bus master, Multiword DMA, look-ahead read buffer, and prefetch mechanism for each channel respectively.

The IDE interface timing is completely programmable. Timing control covers the command active and recover pulse widths, and command block register accesses. The IDE data-transfer speed for each device on each channel can be independently programmed allowing high-speed IDE peripherals to coexist on the same channel as older, compatible devices.

The Core Logic module also provides a software accessible buffered reset signal to the IDE drive, F0 Index 44h[2]. The IDE_RST# signal can be driven low or high as needed for device-power-off conditions. IDE_RST# is not driven low by POR# (Power-On Reset).

6.2.3.1 IDE Configuration Registers

Registers for configuring Channels 0 and 1 are located in the PCI register space designated as Function 2 (F2 Index 40h-5Ch). Table 6-35 on page 273 provides the bit formats for these registers. The IDE bus master configuration registers are accessed via F2 Index 20h which is Base Address Register 4 in Function 2 (F2BAR4). See Table 6-36 on page 277 for register/bit formats.

The following subsections discuss Core Logic operational/programming details concerning PIO, Bus Master, and UltraDMA/33 modes.

6.2.3.2 PIO Mode

The IDE data port transaction latency consists of address latency, asserted latency and recovery latency. Address latency occurs when a PCI master cycle targeting the IDE data port is decoded, and the IDE_ADDR[2:0] and IDE_CS# lines are not set up. Address latency provides the setup time for the IDE_ADDR[2:0] and IDE_CS# lines prior to IDE_IOR# and IDE_IOW#.

Asserted latency consists of the I/O command strobe assertion length and recovery time. Recovery time is provided so that transactions may occur back-to-back on the IDE interface without violating minimum cycle periods for the IDE interface.

If IDE_IORDY is asserted when the initial sample point is reached, no wait states are added to the command strobe assertion length. If IDE_IORDY is negated when the initial sample point is reached, additional wait states are added.

Recovery latency occurs after the IDE data port transactions have completed. It provides hold time on the IDE_ADDR[2:0] and IDE_CS# lines with respect to the read and write strobes (IDE_IOR# and IDE_IOW#).

The PIO portion of the IDE registers is enabled through:

- Channel 0 Drive 0 Programmed I/O Register (F2 Index 40h)
- Channel 0 Drive 1 Programmed I/O Register (F2 Index 48h)
- Channel 1 Drive 0 Programmed I/O Register (F2 Index 50h)
- Channel 1 Drive 1 Programmed I/O Register (F2 Index 58h)

The IDE channels and devices can be individually programmed to select the proper address setup time, asserted time, and recovery time.

The bit formats for these registers are shown in Table 6-35 on page 273. Note that there are different bit formats for each of the PIO programming registers depending on the operating format selected: Format 0 or Format 1:

- F2 Index 44h[31] (Channel 0 Drive 0 DMA Control Register) sets the format of the PIO register.
 - If bit 31 = 0, Format 0 is used and it selects the slowest PIO mode (bits [19:16]) per channel for commands.
 - If bit 31 = 1, Format 1 is used and it allows independent control of command and data.

Also listed in the bit formats are recommended values for the different PIO modes. Note that these are only recommended settings and are not 100% tested.

When using independent control of command and data cycles the following algorithm should be used when two IDE devices are sharing the same channel:

- The PIO data cycle timing for a particular device can be the timing value for the maximum PIO mode which that device reports it supports.
- The PIO command cycle timing for a particular device must be the timing value for the lowest PIO mode for both devices on the channel.

Core Logic Module Revision 5.1 AMD

For example, if a channel had one Mode 4 device and one Mode 0 device, then the Mode 4 device would have command timings for Mode 0 and data timing for Mode 4. The Mode 0 device would have both command and data timings for Mode 0. Note that for the Mode 0 case, the 32-bit timing value is listed because both data and command timings are the same mode. However, the actual timing value for the Mode 4 device would be constructed out of the Mode 4 data timing 16-bit value and the Mode 0 16-bit command timing value. Both 16-bit values are shown in the register description but not assembled together as they are mixed modes.

6.2.3.3 Bus Master Mode

Two IDE bus masters are provided to perform the data transfers for the primary and secondary channels. The IDE controller of the Core Logic module off-loads the CPU and improves system performance in multitasking environments.

The bus master mode programming interface is an extension of the standard IDE programming model. This means that devices can always be dealt with using the standard IDE programming model, with the master mode functionality used when the appropriate driver and devices are present. Master operation is designed to work with any IDE device that supports DMA transfers on the IDE bus. Devices that work in PIO mode can only use the standard IDE programming model.

The IDE bus masters use a simple scatter/gather mechanism allowing large transfer blocks to be scattered to or gathered from memory. This cuts down on the number of interrupts to and interactions with the CPU.

Physical Region Descriptor Table Address

Before the controller starts a master transfer it is given a pointer to a Physical Region Descriptor Table. This pointer sets the starting memory location of the Physical Region Descriptors (PRDs). The PRDs describe the areas of memory that are used in the data transfer. The PRDs must be aligned on a 4-byte boundary and the table cannot cross a 64 KB boundary in memory.

Primary and Secondary IDE Bus Master Registers

The IDE Bus Master Registers for each channel (primary and secondary) have an IDE Bus Master Command register and Bus Master Status register. These registers and bit formats are described in Table 6-36 on page 277.

Physical Region Descriptor Format

Each physical memory region to be transferred is described by a Physical Region Descriptor (PRD) as illustrated in Table 6-1. When the bus master is enabled (Command register bit 0=1), data transfer proceeds until each PRD in the PRD table has been transferred. The bus master does not cache PRDs.

The PRD table consists of two DWORDs. The first DWORD contains a 32-bit pointer to a buffer to be transferred. The second DWORD contains the size (16 bits) of the buffer and the EOT flag. The EOT bit (bit 31) must be set to indicate the last PRD in the PRD table.

Programming Model

The following steps explain how to initiate and maintain a bus master transfer between memory and an IDE device.

- Software creates a PRD table in system memory. Each PRD entry is 8 bytes long, consisting of a base address pointer and buffer size. The maximum data that can be transferred from a PRD entry is 64 KB. A PRD table must be aligned on a 4-byte boundary. The last PRD in a PRD table must have the EOT bit set.
- Software loads the starting address of the PRD table by programming the PRD Table Address register.
- Software must fill the buffers pointed to by the PRDs with IDE data.
- 4) Write 1 to the Bus Master Interrupt bit and Bus Master Error (Status register bits 2 and 1) to clear the bits.
- 5) Set the correct direction to the Read or Write Control bit (Command register bit 3).

Engage the bus master by writing a "1" to the Bus Master Control bit (Command register bit 0).

The bus master reads the PRD entry pointed to by the PRD Table Address register and increments the address by 08h to point to the next PRD. The transfer begins.

6) The bus master transfers data to/from memory responding to bus master requests from the IDE device. At the completion of each PRD, the bus master's next response depends on the settings of the EOT flag in the PRD. If the EOT bit is set, then the IDE bus master clears the Bus Master Active bit (Status register bit 0) and stop. If any errors occurred during the transfer, the bus master sets the Bus Master Error bit Status register bit 1).

Table 6-1. Physical Region Descriptor Format

				Byt	te 3							Byt	te 2	2						Ву	te 1							Byt	e 0			
DWORD	31	31	29	28	27	26	25	24	23	22	21	20	19	9 18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0								Ме	emo	ry R	egio	on P	hy	sical	Bas	e A	ddre	ss [3	31:1] (ID	E D	ata l	3uffe	er)								0
1	E O T							Re	serv	ed.													Siz	e [1	5:1]							0

6.2.3.4 UltraDMA/33 Mode

The IDE controller of the Core Logic module supports UltraDMA/33. It utilizes the standard IDE Bus Master functionality to interface, initiate and control the transfer. UltraDMA/33 definition also incorporates a Cyclic Redundancy Checking (CRC) error checking protocol to detect errors.

The UltraDMA/33 protocol requires no extra signal pins on the IDE connector. The IDE controller redefines three standard IDE control signals when in UltraDMA/33 mode. These definitions are shown in Table 6-2.

Table 6-2. UltraDMA/33 Signal Definitions

IDE Controller Channel Signal	UltraDMA/33 Read Cycle	UltraDMA/33 Write Cycle
IDE_IOW#	STOP	STOP
IDE_IOR#	DMARDY#	STROBE
IDE_IORDY	STROBE	DMARDY#

All other signals on the IDE connector retain their functional definitions during the UltraDMA/33 operation.

IDE_IOW# is defined as STOP for both read and write transfers to request to stop a transaction.

IDE_IOR# is redefined as DMARDY# for transferring data from the IDE device to the IDE controller. It is used by the IDE controller to signal when it is ready to transfer data and to add wait states to the current transaction. IDE_IOR# signal is defined as STROBE for transferring data from the IDE controller to the IDE device. It is the data strobe signal driven by the IDE controller on which data is transferred during each rising and falling edge transition.

IDE_IORDY is redefined as STROBE for transferring data from the IDE device to the IDE controller during a read cycle. It is the data strobe signal driven by the IDE device on which data is transferred during each rising and falling edge transition. IDE_IORDY is defined as DMARDY# during a write cycle for transferring data from the IDE controller to the IDE device. It is used by the IDE device to signal when it is ready to transfer data and to add wait states to the current transaction.

UltraDMA/33 data transfer consists of three phases, a startup phase, a data transfer phase and a burst termination phase.

The IDE device begins the startup phase by asserting IDE_DREQ. When ready to begin the transfer, the IDE controller asserts IDE_DACK#. When IDE_DACK# is asserted, the IDE controller drives IDE_CS0# and IDE_CS1# asserted, and IDE_ADDR[2:0] low. For write cycles, the IDE controller negates STOP, waits for the IDE device to assert DMARDY#, and then drives the first data WORD and STROBE signal. For read cycles, the IDE controller negates STOP, and asserts DMARDY#. The IDE device then sends the first data WORD and asserts STROBE.

The data transfer phase continues the burst transfers with the Core Logic and the IDE via providing data, toggling STROBE and DMARDY#. The IDE_DATA[15:0] is latched by receiver on each rising and falling edge of STROBE. The transmitter can pause the burst cycle by holding STROBE high or low, and resume the burst cycle by again toggling STROBE. The receiver can pause the burst cycle by negating DMARDY# and resumes the burst cycle by asserting DMARDY#.

The current burst cycle can be terminated by either the transmitter or the receiver. A burst cycle must first be paused as described above before it can be terminated. The IDE controller can then stop the burst cycle by asserting STOP, with the IDE device acknowledging by negating IDE_DREQ. The IDE device then stops the burst cycle by negating IDE_DREQ and the IDE controller acknowledges by asserting STOP. The transmitter then drives the STROBE signal to a high level. The IDE controller then puts the result of the CRC calculation onto the IDE_DATA[15:0] while de-asserting IDE_DACK#. The IDE device latches the CRC value on the rising edge of IDE_DACK#.

The CRC value is used for error checking on UltraDMA/33 transfers. The CRC value is calculated for all data by both the IDE controller and the IDE device during the UltraDMA/33 burst transfer cycles. This result of the CRC calculation is defined as all data transferred with a valid STROBE edge while IDE_DACK# is asserted. At the end of the burst transfer, the IDE controller drives the result of the CRC calculation onto IDE_DATA[15:0] which is then strobed by the de-assertion of IDE_DACK#. The IDE device compares the CRC result of the IDE controller to its own and reports an error if there is a mismatch.

The timings for UltraDMA/33 are programmed into the DMA control registers:

- Channel 0 Drive 0 DMA Control Register (F2 Index 44h)
- Channel 0 Drive 1 DMA Control Register (F2 Index 4Ch)
- Channel 1 Drive 0 DMA Control Register (F2 Index 54h)
- Channel 1 Drive 1 DMA Control Register (F2 Index 5Ch)

The bit formats for these registers are described in Table 6-35 on page 273. Note that F2 Index 44h[20] is used to select either Multiword or UltraDMA mode. Bit 20 = 0 selects Multiword DMA mode. If bit 20 = 1, then UltraDMA/33 mode is selected. Once mode selection is made using this bit, the remaining DMA Control registers also operate in the selected mode.

Also listed in the bit formats are recommended values for both Multiword DMA Modes 0-2 and UltraDMA/33 Modes 0-2. Note that these are only recommended settings and are not 100% tested.

Core Logic Module Revision 5.1

6.2.4 Universal Serial Bus

The Core Logic module provides three complete, independent USB ports. Each port has a Data "Negative" and a Data "Positive" signal.

The USB ports are Open Host Controller Interface (Open-HCI) compliant. The OpenHCI specification provides a register-level description for a host controller, as well as common industry hardware/software interface and drivers.

6.2.5 Sub-ISA Bus Interface

The Sub-ISA interface of the Core Logic module is an ISA-like bus interface that is used by SC3200 to interface with Boot Flash, M-Systems DiskOnChip or NAND EEPROM and other I/O devices. The Core Logic module is the default subtractive decoding agent and forwards all unclaimed memory and I/O cycles to the ISA bus. However, the Core Logic module can be configured to ignore either I/O, memory, or all unclaimed cycles (subtractive decode disabled).

Note: The external Sub-ISA bus is a positive decode bus. Unclaimed memory and I/O cycles will not appear on the Sub-ISA interface.

The Core Logic module does not support Sub-ISA refresh cycles. The refresh toggle bit in Port B still exists for software compatibility reasons.

The Sub-ISA interface includes the followings signals in addition to the signals used for an ISA interface:

IOCS0#/IOCS1#

 Asserted on I/O read/write transactions from/to a programmable address range.

DOCCS#

 Asserted on memory read/write transactions from/to a programmable window.

• ROMCS#

 Asserted on memory read/write to upper 16 MB of address space. Configurable via the ROM Mask register (F0 Index 6Ch).

DOCR#

 DOCR# is asserted on memory read transactions from DOCCS# window (i.e., when both DOCCS# and MEMR# are active, DOCR# is active; otherwise, it is inactive).

DOCW

 DOCW# is asserted on memory write transactions to DOCCS# window (i.e., when both DOCCS# and MEMW# are active, DOCW# is active; otherwise, it is inactive).

• RD#, WR#

 The signals IOR#, IOW#, MEMR#, and MEMW# are combined into two signals: RD# is asserted on I/O read or memory read; WR# is asserted on I/O write or memory write.

Memory devices that use ROMCS# or DOCCS# as their chip select signal can be configured to support an 8-bit or 16-bit data bus via bits 3 and 6 of the MCR register. Such devices can also be configured as zero wait states devices (regardless of the data bus width) via bits 9 and 10 of the MCR register. For MCR register bit descriptions, see Table 4-2 on page 88.

I/O peripherals that use IOCS0# or IOCS1# as their chip select signal can be configured to support an 8-bit or 16-bit data bus via bits 7 and 8 of the MCR register. Such devices can also be configured as zero wait state devices (for 8-bit peripherals) via bits 11 and 12 of the MCR register. For MCR register bit descriptions, see Table 4-2 on page 88.

Other memory devices and I/O peripherals must be 8-bit devices; their transactions can not be with zero wait states

The Boot Flash supported by the SC3200 can be up to 16 MB. It is supported with the ROMCS# signal.

All unclaimed memory and I/O cycles are forwarded to the Internal ISA bus if subtractive decode is enabled.

The DiskOnChip chip select signal (DOCCS#) is asserted on any memory read or memory write transaction from/to a programmable address range. The address range is programmable via the DOCCS# Base Address and Control registers (F0 Index 78h and 7Ch). The base address must be on an address boundary, the size of the range.

Signal DOCCS# can also be used to interface to NAND Flash devices together with signals DOCW# and DOCR#. See application note AMD Geode™ SC1200/SC2200/SC3200 Processors: External NAND Flash Memory Circuit for details.

6.2.5.1 Sub-ISA Bus Cycles

The ISA bus controller issues multiple ISA cycles to satisfy PCI transactions that are larger than 16 bits. A full 32-bit read or write results in two 16-bit ISA transactions or four 8-bit ISA transactions. The ISA controller gathers the data from multiple ISA read cycles and returns TRDY# to the PCI bus.

SA[23:0] are a concatenation of ISA LA[23:17] and SA[19:0] and perform equivalent functionality at a reduced pin count.

Figure 6-2 shows the relationship between a PCI cycle and the corresponding ISA cycle generated.

Note: Not all signals described in Figure 6-2 are available externally. See Section 3.4.7 "Sub-ISA Interface Signals" on page 73 for more information about which Sub-ISA signals are externally available on the SC3200.

6.2.5.2 Sub-ISA Support of Delayed PCI Transactions

Multiple PCI cycles occur for every slower ISA cycle. This prevents slow PCI cycles from occupying too much bandwidth and allows access to other PCI traffic. Figure 6-3 on page 165 shows the relationship of PCI cycles to an ISA cycle with PCI delayed transactions enabled.

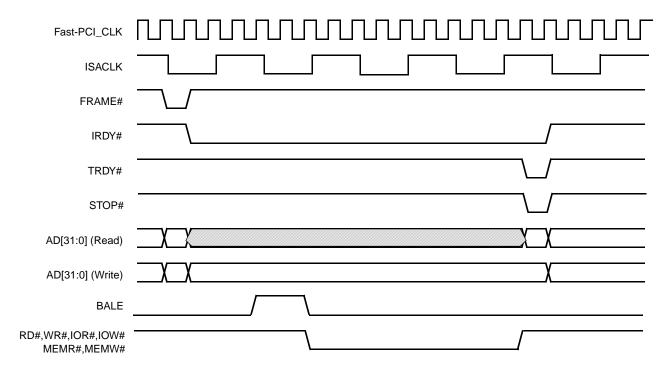


Figure 6-2. Non-Posted Fast-PCI to ISA Access

Revision 5.1 **Core Logic Module**

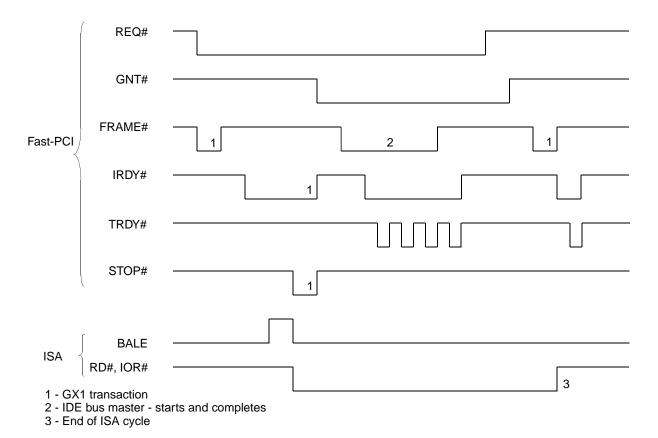


Figure 6-3. PCI to ISA Cycles with Delayed Transaction Enabled

6.2.5.3 **Sub-ISA Bus Data Steering**

The Core Logic module performs all of the required data steering from SD[7:0] to SD[15:0] during normal 8-bit ISA cycles, as well as during DMA and ISA master cycles. It handles data transfers between the 32-bit PCI data bus and the ISA bus. 8/16-bit devices can reside on the ISA bus. Various PC-compatible I/O registers, DMA controller registers, interrupt controller registers, and counter/timer registers lie on the on-chip I/O data bus. Either the PCI bus master or the DMA controllers can become the bus owner.

When the PCI bus master is the bus owner, the Core Logic module data steering logic provides data conversion necessary for 8/16/32-bit transfers to and from 8/16-bit devices on either the Sub-ISA bus or the 8-bit registers on the onchip I/O data bus. When PCI data bus drivers of the Core Logic module are in TRI-STATE, data transfers between the PCI bus master and PCI bus devices are handled directly via the PCI data bus.

When the DMA requestor is the bus owner, the Core Logic module allows 8/16-bit data transfer between the Sub-ISA bus and the PCI data bus.

I/O Recovery Delays 6.2.5.4

In normal operation, the Core Logic module inserts a delay between back-to-back ISA I/O cycles that originate on the PCI bus. The default delay is four ISACLK cycles. Thus, the second of consecutive I/O cycles is held in the ISA bus controller until this delay count has expired. The delay is measured between the rising edge of IOR#/IOW# and the falling edge of BALE. This delay can be adjusted to a greater delay through the ISA I/O Recovery Control register (F0 Index 51h).

Note: This delay is not inserted for a 16-bit Sub-ISA I/O access that is split into two 8-bit I/O accesses.

6.2.5.5 ISA DMA

DMA transfers occur between ISA I/O peripherals and system memory (i.e., not available externally). The data width can be either 8 or 16 bits. Out of the seven DMA channels available, four are used for 8-bit transfers while the remaining three are used for 16-bit transfers. One byte or WORD is transferred in each DMA cycle.

Note: The Core Logic module does not support DMA transfers to ISA memory.

The ISA DMA device initiates a DMA request by asserting one of the DRQ[7:5, 3:0] signals. When the Core Logic module receives this request, it sends a bus grant request

to the PCI arbiter. After the PCI bus has been granted, the respective DACK# is driven active.

The Core Logic module generates PCI memory read or write cycles in response to a DMA cycle. Figure 6-4 and Figure 6-5 are examples of DMA memory read and memory write cycles. Upon detection of the DMA controller's MEMR# or MEMW# active, the Core Logic module starts the PCI cycle, asserts FRAME#, and negates an internal IOCHRDY. This assures the DMA cycle does not complete before the PCI cycle has provided or accepted the data. IOCHRDY is internally asserted when IRDY# and TRDY# are sampled active.

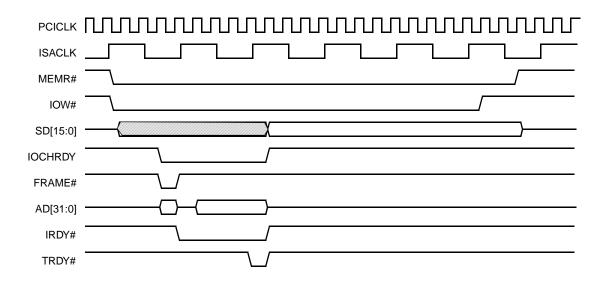


Figure 6-4. ISA DMA Read from PCI Memory

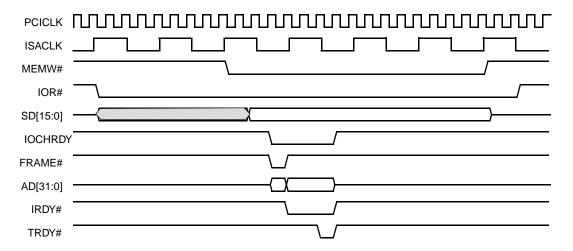


Figure 6-5. ISA DMA Write to PCI Memory

Core Logic Module Revision 5.1 AMD

6.2.5.6 ROM Interface

The Core Logic module positively decodes memory addresses 000F0000h-000FFFFh (64 KB) and FFFC0000h-FFFFFFFh (256 KB) at reset. These memory cycles cause the Core Logic module to claim the cycle, and generate an ISA bus memory cycle with ROMCS# asserted. The Core Logic module can also be configured to respond to memory addresses FF000000h-FFFFFFFh (16 MB) and 000E0000h-000FFFFFh (128 KB).

8- or 16-bit wide ROM is supported. BOOT16 strap determines the width after reset. MCR[14,3] (Offset 34h) in the General Configuration Block (see Table 4-2 on page 88 for bit details) allows program control of the width.

Flash ROM is supported in the Core Logic module by enabling the ROMCS# signal on write accesses to the ROM region. Normally only read cycles are passed to the ISA bus, and the ROMCS# signal is suppressed for write cycles. When the ROM Write Enable bit (F0 Index 52h[1]) is set, a write access to the ROM address region causes a write cycle to occur with MEMW#, WR# and ROMCS# asserted.

6.2.5.7 PCI and Sub-ISA Signal Cycle Multiplexing

The SC3200 multiplexes most PCI and Sub-ISA signals on the balls listed in Table 6-3, in order to reduce the number of balls on the device. Cycle multiplexing is on a bus-cycle by bus-cycle basis (see Figure 6-6 on page 168), where the internal Core Logic PCI bridge arbitrates between PCI cycles and Sub-ISA cycles. Other PCI and Sub-ISA signals remain non-shared, however, some Sub-ISA signals may be muxed with GPIO.

Sub-ISA cycles are only generated as a result of GX1 module accesses to the following addresses or conditions:

- · ROMCS# address range.
- DOCCS# address range.
- · IOCS0# address range.
- IOCS1# address range.
- An I/O write to address 80h or to 84h.
- Internal ISA is programmed to be the subtractive decode agent and no other agents claim the cycle.

If the Sub-ISA and PCI bus have more than four components, the Sub-ISA components can be buffered using 74HCT245 or 74FCT245 type transceivers. The RD# (an AND of IOR#, MEMR#) signal can be used as DIR control while TRDE# is used as enable control.

Table 6-3. Cycle Multiplexed PCI / Sub-ISA Balls

		Ва	II No.
PCI	Sub-ISA	EBGA	TEPBGA
AD0	A0	A17	U1
AD1	A1	D16	P3
AD2	A2	A18	U3
AD3	A3	A15	N1
AD4	A4	A16	P1
AD5	A5	A14	N3
AD6	A6	C15	N2
AD7	A7	B14	M2
AD8	A8	C14	M4
AD9	A9	B13	L2
AD10	A10	C13	L3
AD11	A11	C12	K1
AD12	A12	A12	L4
AD13	A13	C11	J1
AD14	A14	A11	K4
AD15	A15	B10	J3
AD16	A16	A7	E1
AD17	A17	C7	F4
AD18	A18	D7	E3
AD19	A19	A6	E2
AD20	A20	D6	D3
AD21	A21	C6	D1
AD22	A22	A5	D2
AD23	A23	F4	B6
AD24	D0	C5	C2
AD25	D1	D5	C4
AD26	D2	A4	C1
AD27	D3	B4	D4
AD28	D4	C4	B4
AD29	D5	A3	В3
AD30	D6	C2	A3
AD31	D7	В3	D5
C/BE0#	D8	A13	L1
C/BE1#	D9	A10	J2
C/BE2#	D10	D8	F3
C/BE3#	D11	A8	H4
PAR	D12	C10	J4
TRDY#	D13	B8	F1
IRDY#	D14	C8	F2
STOP#	D15	D9	G1

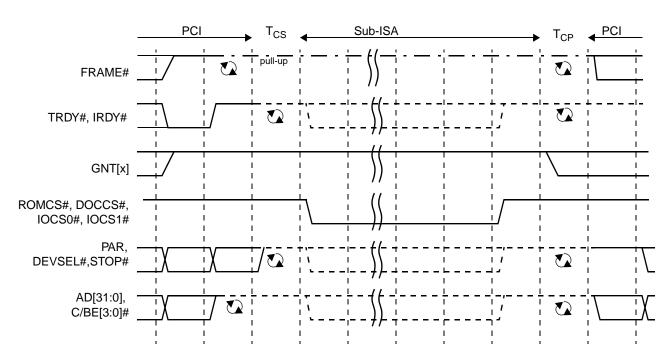


Figure 6-6. PCI Change to Sub-ISA and Back

6.2.6 AT Compatibility Logic

The Core Logic module integrates:

- Two 8237-equivalent DMA controllers with full 32-bit addressing
- Two 8259A-equivalent interrupt controllers providing 13 individually programmable external interrupts
- An 8254-equivalent timer for refresh, timer, and speaker logic
- NMI control and generation for PCI system errors and all parity errors
- Support for standard AT keyboard controllers
- Positive decode for the AT I/O register space
- Reset control

6.2.6.1 DMA Controller

The Core Logic module supports industry standard DMA architecture using two 8237-compatible DMA controllers in cascaded configuration. The DMA functions supported by the Core Logic module include:

- Standard seven-channel DMA support (Channels 5 through 7 are not supported)
- · 32-bit address range support via high page registers
- IOCHRDY extended cycles for compatible timing transfers
- Internal Sub-ISA bus master device support using cascade mode

 NMI control and generation for PCI system errors and all parity errors.

Note: DMA interface signals are not available externally.

DMA Channels

The Core Logic module supports seven DMA channels using two standard 8237-equivalent controllers. DMA Controller 1 contains Channels 0 through 3 and supports 8-bit I/O adapters. These channels are used to transfer data between 8-bit peripherals and PCI memory or 8/16-bit ISA memory. Using the high and low page address registers, a full 32-bit PCI address is output for each channel so they can all transfer data throughout the entire 4 GB system address space. Each channel can transfer data in 64 KB pages. Software initiated DMA requests are not supported.

DMA Controller 2 contains Channels 4 through 7. Channel 4 is used to cascade DMA Controller 1, so it is not available externally. Channels 5 through 7 support 16-bit I/O adapters to transfer data between 16-bit I/O adapters and 16-bit system memory. Using the high and low page address registers, a full 32-bit PCI address is output for each channel so they can all transfer data throughout the entire 4 GB system address space. Each channel can transfer data in 128 KB pages. Channels 5, 6, and 7 transfer 16-bit WORDs on even byte boundaries only. Channels 5 through 7 are not supported.

Core Logic Module Revision 5.1 AMD

DMA Transfer Modes

Each DMA channel can be programmed for *single, block, demand* or *cascade* transfer modes. In the most commonly used mode, *single* transfer mode, one DMA cycle occurs per DRQ and the PCI bus is released after every cycle. This allows the Core Logic module to timeshare the PCI bus with the GX1 module. This is imperative, especially in cases involving large data transfers, because the GX1 module gets locked out for too long.

In block transfer mode, the DMA controller executes all of its transfers consecutively without releasing the PCI bus.

In *demand* transfer mode, DMA transfer cycles continue to occur as long as DRQ is high or terminal count is not reached. In this mode, the DMA controller continues to execute transfer cycles until the I/O device drops DRQ to indicate its inability to continue providing data. For this case, the PCI bus is held by the Core Logic module until a break in the transfers occurs.

In cascade mode, the channel is connected to another DMA controller or to an ISA bus master, rather than to an I/O device. In the Core Logic module, one of the 8237 controllers is designated as the master and the other as the slave. The HOLD output of the slave is tied to the DRQ0 input of the master (Channel 4), and the master's DACK0# output is tied to the slave's HLDA input.

In each of these modes, the DMA controller can be programmed for *read*, *write*, or *verify* transfers.

Both DMA controllers are reset at power-on reset (POR) to fixed priority. Since master Channel 0 is actually connected to the slave DMA controller, the slave's four DMA channels have the highest priority, with Channel 0 as highest and Channel 3 as the lowest. Immediately following slave Channel 3, master Channel 1 (Channel 5) is the next highest, followed by Channels 6 and 7.

DMA Controller Registers

The DMA controller can be programmed with standard I/O cycles to the standard register space for DMA. The I/O addresses for the DMA controller registers are listed Table 6-43 on page 313.

When writing to a channel's address or WORD Count register, the data is written into both the base register and the current register simultaneously. When reading a channel address or WORD Count register, only the current address or WORD Count can be read. The base address and base WORD Count are not accessible for reading.

DMA Transfer Types

Each of the seven DMA channels may be programmed to perform one of three types of transfers: *read, write, or verify.* The transfer type selected defines the method used to transfer a byte or WORD during one DMA bus cycle.

For *read* transfer types, the Core Logic module reads data from memory and write it to the I/O device associated with the DMA channel.

For write transfer types, the Core Logic module reads data from the I/O device associated with the DMA channel and write to the memory.

The *verify* transfer type causes the Core Logic module to execute DMA transfer bus cycles, including generation of memory addresses, but neither the READ nor WRITE command lines are activated. This transfer type was used by DMA Channel 0 to implement DRAM refresh in the original IBM PC and XT.

DMA Priority

The DMA controller may be programmed for two types of priority schemes: *fixed* and *rotate* (I/O Ports 008h[4] and 0D0h[4] - see Table 6-43 on page 313).

In *fixed* priority, the channels are fixed in priority order based on the descending values of their numbers. Thus, Channel 0 has the highest priority. In *rotate* priority, the last channel to get service becomes the lowest-priority channel with the priority of the others rotating accordingly. This prevents a channel from dominating the system.

The address and WORD Count registers for each channel are 16-bit registers. The value on the data bus is written into the upper byte or lower byte, depending on the state of the internal addressing byte pointer. This pointer can be cleared by the Clear Byte Pointer command. After this command, the first read/write to an address or WORD-count register reads or writes to the low byte of the 16-bit register and the byte pointer points to the high byte. The next read/write to an address or WORD-count register reads or writes to the high byte of the 16-bit register and the byte pointer points back to the low byte.

When programming the 16-bit channels (Channels 5, 6, and 7), the address which is written to the base address register must be the real address divided by two. Also, the base WORD Count for the 16-bit channels is the number of 16-bit WORDs to be transferred, not the number of bytes as is the case for the 8-bit channels.

The DMA controller allows the user to program the active level (low or high) of the DRQ and DACK# signals. Since the two controllers are cascaded together internally on the chip, these signals should always be programmed with the DRQ signal active high and the DACK# signal active low.

DMA Shadow Registers

The Core Logic module contains a shadow register located at F0 Index B8h (Table 6-29 on page 206) for reading the configuration of the DMA controllers. This read only register can sequence to read through all of the DMA registers.

DMA Addressing Capability

DMA transfers occur over the entire 32-bit address range of the PCI bus. This is accomplished by using the DMA controller's 16-bit memory address registers in conjunction with an 8-bit DMA Low Page register and an 8-bit DMA High Page register. These registers, associated with each channel, provide the 32-bit memory address capability. A write to the Low Page register clears the High Page register, for backward compatibility with the PC/AT standard. The starting address for the DMA transfer must be programmed into the DMA controller registers and the channel's respective Low and High Page registers prior to beginning the DMA transfer.

DMA Page Registers and Extended Addressing

The DMA Page registers provide the upper address bits during DMA cycles. DMA addresses do not increment or decrement across page boundaries. Page boundaries for the 8-bit channels (Channels 0 through 3) are every 64 KB and page boundaries for the 16-bit channels (Channels 5, 6, and 7) are every 128 KB.

Before any DMA operations are performed, the Page registers must be written at the I/O Port addresses in the DMA controller registers to select the correct page for each DMA channel. The other address locations between 080h and 08Fh and 480h and 48Fh are not used by the DMA channels, but can be read or written by a PCI bus master. These registers are reset to zero at POR. A write to the Low Page register clears the High Page register, for backward compatibility with the PC/AT standard.

For most DMA transfers, the High Page register is set to zeros and is driven onto PCI address bits AD[31:24] during DMA cycles. This mode is backward compatible with the PC/AT standard. For DMA extended transfers, the High Page register is programmed and the values are driven onto the PCI addresses AD[31:24] during DMA cycles to allow access to the full 4 GB PCI address space.

DMA Address Generation

The DMA addresses are formed such that there is an upper address, a middle address, and a lower address portion.

The upper address portion, which selects a specific page, is generated by the Page registers. The Page registers for each channel must be set up by the system before a DMA operation. The DMA Page register values are driven on PCI address bits AD[31:16] for 8-bit channels and AD[31:17] for 16-bit channels.

The middle address portion, which selects a block within the page, is generated by the DMA controller at the beginning of a DMA operation and any time the DMA address increments or decrements through a block boundary. Block sizes are 256 bytes for 8-bit channels (Channels 0 through 3) and 512 bytes for 16-bit channels (Channels 5, 6, and 7). The middle address bits are is driven on PCI address bits AD[15:8] for 8-bit channels and AD[16:9] for 16-bit channels.

The lower address portion is generated directly by the DMA controller during DMA operations. The lower address bits are output on PCI address bits AD[7:0] for 8-bit channels and AD[8:1] for 16-bit channels.

BHE# is configured as an output during all DMA operations. It is driven as the inversion of AD0 during 8-bit DMA cycles and forced low for all 16-bit DMA cycles.

6.2.6.2 Programmable Interval Timer

The Core Logic module contains an 8254-equivalent Programmable Interval Timer (PIT) configured as shown in Figure 6-7. The PIT has three timers/counters, each with an input frequency of 1.19318 MHz (OSC divided by 12), and individually programmable to different modes.

The gates of Counter 0 and 1 are usually enabled, however, they can be controlled via F0 Index 50h. The gate of Counter 2 is connected to I/O Port 061h[0]. The output of Counter 0 is connected internally to IRQ0. This timer is typically configured in Mode 3 (square wave output), and used to generate IRQ0 at a periodic rate to be used as a system timer function. The output of Counter 1 is connected to I/O Port 061h[4]. The reset state of I/O Port 061h[4] is 0 and every falling edge of Counter 1 output causes I/O Port 061h[4] to flip states. The output of Counter 2 is brought out to the PC_BEEP output. This output is gated with I/O Port 061h[1].

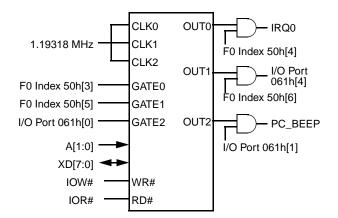


Figure 6-7. PIT Timer

PIT Shadow Register

The PIT registers are shadowed to allow for 0V Suspend to save/restore the PIT state by reading the PIT's counter and write only registers. The read sequence for the shadow register is listed in F0 Index BAh (see Table 6-29 on page 206).

Core Logic Module Revision 5.1 AMD

6.2.6.3 Programmable Interrupt Controller

The Core Logic module contains two 8259A-equivalent programmable interrupt controllers, with eight interrupt request lines each, for a total of 16 interrupts. The PCI device supports all x86 modes of operation except Special Fully Nested mode. The two controllers are cascaded internally, and two of the interrupt request inputs are connected to the internal circuitry. This allows a total of 13 externally available interrupt requests. See Figure 6-9.

Each Core Logic IRQ signal can be individually selected to as edge- or level-sensitive. The four PCI interrupt signals may be routed internally to any PIC IRQ.

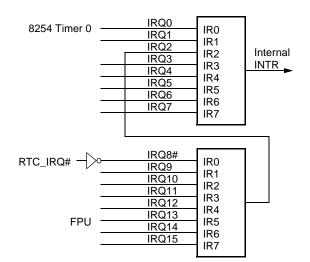


Figure 6-8. PIC Interrupt Controllers

Three interrupts are available externally depending upon selected ball multiplexing:

- 1) IRQ15 (muxed with GPIO11+RI2#),
- 2) IRQ14 (muxed with TFTD1), and
- IRQ9 (muxed with IDE_DATA6)

More of the IRQs are available through the use of SERIRQ (muxed with GPIO39) function. See Table 6-4.

Table 6-4. PIC Interrupt Mapping

Master IRQ	Mapping
IRQ0	Connected to the OUT0 (system timer) of the internal 8254 PIT.
IRQ2	Connected to the slave's INTR for a cascaded configuration.
IRQ8#	Connected to internal RTC.
IRQ13	Connected to the FPU interface of the GX1 module.
IRQ15	Interrupts available to other functions
IRQ14	
IRQ12	
IRQ11	
IRQ10	
IRQ9	
IRQ7	
IRQ6	
IRQ5	
IRQ4	
IRQ3	
IRQ1	

The Core Logic module allows PCI interrupt signals INTA#, INTB#, INTC# (muxed with GPIO19+IOCHRDY) and INTD# (muxed with IDE_DATA7) to be routed internally to any IRQ signal. The routing can be modified through Core Logic module's configuration registers. If this is done, the IRQ input must be configured to be level- rather than edge-sensitive. IRQ inputs may be individually programmed to be level-sensitive with the Interrupt Sensitivity configuration registers at I/O address space 4D0h and 4D1h. PCI interrupt configuration is discussed in further detail in "PCI Compatible Interrupts" on page 172.

PIC Interrupt Sequence

A typical AT-compatible interrupt sequence is as follows. Any unmasked interrupt generates the internal INTR signal to the CPU. The interrupt controller then responds to the interrupt acknowledge (INTA) cycles from the CPU. On the first INTA cycle the cascading priority is resolved to determine which of the two 8259A controllers output the interrupt vector onto the data bus. On the second INTA cycle the appropriate 8259A controller drives the data bus with the correct interrupt vector for the highest priority interrupt.

By default, the Core Logic module responds to PCI INTA cycles because the system interrupt controller is located within the Core Logic module. This may be disabled with F0 Index 40h[0]. When the Core Logic module responds to a PCI INTA cycle, it holds the PCI bus and internally generates the two INTA cycles to obtain the correct interrupt vector. It then asserts TRDY# and returns the interrupt vector.

PIC I/O Registers

Each PIC contains registers located in the standard I/O address locations, as shown in Table 6-46 "Programmable Interrupt Controller Registers" on page 321.

An initialization sequence must be followed to program the interrupt controllers. The sequence is started by writing Initialization Command Word 1 (ICW1). After ICW1 has been written, the controller expects the next writes to follow in the sequence ICW2, ICW3, and ICW4 if it is needed. The Operation Control Words (OCW) can be written after initialization. The PIC must be programmed before operation begins.

Since the controllers are operating in cascade mode, ICW3 of the master controller should be programmed with a value indicating that the IRQ2 input of the master interrupt controller is connected to the slave interrupt controller rather than an I/O device as part of the system initialization code. In addition, ICW3 of the slave interrupt controller should be programmed with the value 02h (slave ID) and corresponds to the input on the master controller.

PIC Shadow Register

The PIC registers are shadowed to allow for 0V Suspend to save/restore the PIC state by reading the PICs *write only* registers. A write to this register resets the read sequence to the first register. The read sequence for the shadow register is listed in F0 Index B9h.

PCI Compatible Interrupts

The Core Logic module allows the PCI interrupt signals INTA#, INTB#, INTC#, and INTD# (also known in industry terms as PIRQx#) to be mapped internally to any IRQ signal with the PCI Interrupt Steering registers 1 and 2, F0 Index 5Ch and 5Dh.

PCI interrupts are low-level sensitive, whereas PC/AT interrupts are positive-edge sensitive; therefore, the PCI interrupts are inverted before being connected to the 8259A.

Although the controllers default to the PC/AT-compatible mode (positive-edge sensitive), each IRQ may be individually programmed to be edge or level sensitive using the Interrupt Edge/Level Sensitivity registers in I/O Port 4D0h and 4D1h. However, if the controllers are programmed to be level-sensitive via ICW1, all interrupts must be level-sensitive. Figure 6-9 shows the PCI interrupt mapping for the master/slave 8259A interrupt controller.

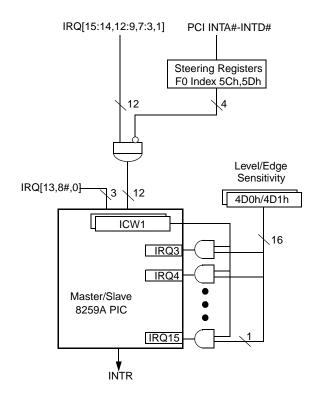


Figure 6-9. PCI and IRQ Interrupt Mapping

6.2.7 I/O Ports 092h and 061h System Control

The Core Logic module supports control functions of I/O Ports 092h (Port A) and 061h (Port B) for PS/2 compatibility. I/O Port 092h allows a fast assertion of the A20M# or CPU_RST. (CPU_RST is an internal signal that resets the CPU. It is asserted for 100 µs after the negation of POR#.) I/O Port 061h controls NMI generation and reports system status. The Core Logic module generates an SMI for every internal change of the A20M# state and the SMI handler sets the A20M# state inside the GX1 module. This method is used for both the Port 092h (PS/2) and Port 061h (keyboard) methods of controlling A20M#.

Core Logic Module Revision 5.1 AMD

6.2.7.1 I/O Port 092h System Control

I/O Port 092h allows for a fast keyboard assertion of an A20# SMI and a fast keyboard CPU reset. Decoding for this register may be disabled via F0 Index 52h[3].

The assertion of a fast keyboard A20# SMI is controlled by either I/O Port 092h or by monitoring for the keyboard command sequence (see Section 6.2.8.1 "Fast Keyboard Gate Address 20 and CPU Reset" on page 173). If bit 1 of I/O Port 092h is cleared, the Core Logic module internally asserts an A20M#, which in turn causes an SMI to the GX1 module. If bit 1 is set, A20M# is internally deasserted, again causing an SMI.

The assertion of a fast keyboard reset (WM_RST SMI) is controlled by bit 0 in I/O Port 092h or by monitoring for the keyboard command sequence (write data = FEh to I/O port 64h). If bit 0 is changed from 0 to 1, the Core Logic module generates a reset to the GX1 module by generating a WM_RST SMI. When the WM_RST SMI occurs, the BIOS jumps to the Warm Reset vector. Note that Warm Reset is not a pin, it is under SMI control.

6.2.7.2 I/O Port 061h System Control

Through I/O Port 061h, the speaker output can be enabled, the status of IOCHK# and SERR# can be read, and the state of the speaker data (Timer2 output) and refresh toggle (Timer1 output) can be read back. Note that NMI is under SMI control. Even though the hardware is present, the IOCHK# ball does not exist. Therefore, an NMI from IOCHK# can not happen.

6.2.7.3 SMI Generation for NMI

Figure 6-10 shows how the Core Logic module can generate an SMI for an NMI. Note that NMI is not a ball.

6.2.8 Keyboard Support

The Core Logic module can actively decode the keyboard controller I/O Ports 060h, 062h, 064h and 066h, and generate an LPC bus cycle. Keyboard positive decoding can be disabled if F0 Index 5Ah[1] is cleared (i.e., subtractive decoding enabled).

6.2.8.1 Fast Keyboard Gate Address 20 and CPU Reset

The Core Logic module monitors the keyboard I/O Ports 064h and 060h for the fast keyboard A20M# and CPU reset control sequences. If a write to I/O Port 060h[1] = 1 after a write takes place to I/O Port 064h with data of D1h, then the Core Logic module asserts the A20M# signal. A20M# remains asserted until cleared by any one of the following:

- A write to bit 1 of I/O Port 092h.
- · A CPU reset of some kind.
- A write to I/O Port 060h[1] = 0 following a write to I/O Port 064h with data of D1h.

The fast keyboard A20M# and CPU reset can be disabled through F0 Index 52h[7]. By default, bit 7 is set, and the fast keyboard A20M# and CPU reset monitor logic is active. If bit 7 is clear, the Core Logic module forwards the commands to the keyboard controller.

By default, the Core Logic module forces the de-assertion of A20M# during a warm reset. This action may be disabled if F0 Index 52h[4] is cleared.

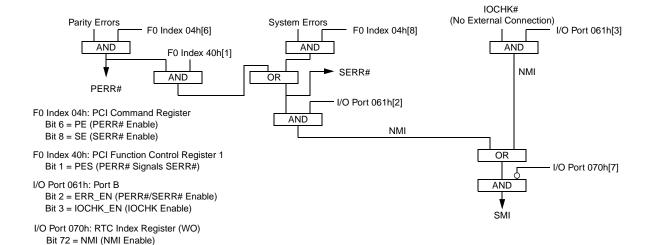


Figure 6-10. SMI Generation for NMI

6.2.9 Power Management Logic

The Core Logic module integrates advanced power management features including idle timers for common system peripherals, address trap registers for programmable address ranges for I/O or memory accesses, four programmable general purpose external inputs, clock throttling with automatic speedup for the GX1 clock, software GX1 stop clock, OV Suspend/Resume with peripheral shadow registers, and a dedicated serial bus to/from the GX1 module providing power management status.

The Core Logic module is ACPI (Advanced Configuration Power Interface) compliant. An ACPI-compliant system is one whose underlying BIOS, device drivers, chipset and peripherals conform to revision 1.0 of the ACPI specification. The Core Logic also supports Advanced Power Management (APM).

The SC3200 provides the following support of ACPI states:

- CPU States: C0, C1, and C3.
- Sleep States:
 - SL1/SL2 ACPI S1 equivalent.
 - SL3 ACPI S3 equivalent.
 - SL4 ACPI S4 equivalent.
 - SL5 ACPI S5 equivalent.
- General Purpose Events: Fully programmable GPE0 Event Block registers.
- Wakeup Events: Supported through GPWIO[2:0] which are powered by standby voltage and generate SMIs.
 See registers at F1BAR1+I/O Offset 0Ah and F1BAR1+I/O Offset 12h. Also see Section 5.6 "System Wakeup Control (SWC)" on page 132 and Table 6-5 "Wakeup Events Capability" on page 175.

SC3200 device power management is highly tuned for low power systems. It allows the system designer to implement a wide range of power saving modes using a wide range of capabilities and configuration options.

SC3200 controls the following functions directly:

- · The system clocks.
- · Core processor power states.
- Wakeup/resume event detection, including general purpose events.
- · Power supply and power planes.

It also supports systems with an external micro controller that is used as a power management controller.

6.2.9.1 CPU States

The SC3200 supports three CPU states: C0, C1 and C3 (the Core Logic C2 CPU state is not supported). These states are fully compliant with the ACPI specification, revision 1.0. These states occur in the Working state only (S0/G0). They have no meaning when the system transitions into a Sleep state. For details on the various Sleep states, see Section 6.2.9.2 "Sleep States" on page 175.

C0 Power State - On

In this state the GX1 module executes code. This state has two sub-states: Full Speed or Throttling; selected via the THT_EN bit (F1BAR1+I/O Offset 00h[4]).

C1 Power State - Active Idle

The SC3200 enters the C1 state, when the Halt Instruction (HLT) is executed. It exits this state back to the C0 state upon an NMI, an unmasked interrupt, or an SMI. The Halt instruction stops program execution and generates a special Halt bus cycle. (See "Usage Hints" on page 177.)

Bus masters are supported in the C1 state and the SC3200 will temporarily exit C1 to perform a bus master transaction.

C2 Power State

The SC3200 does not support the C2 power state. All relevant registers and bit fields in the Core Logic are reserved.

C3 Power State

The SC3200 enters the C3 state, when the P_LVL3 register (F1BAR1+I/O Offset 05h) is read. It exits this state back to the C0 state (Full Speed or Throttling, depending on the THT_EN bit) upon:

- An NMI, an unmasked interrupt, or an SMI.
- A bus master request, if enabled via the BM_RLD bit (F1BAR1+I/O Offset 0Ch[1]).

In this state, the GX1 module is in Suspend Refresh mode (for details, see the Power Management section of the *AMD GeodeTM GX1 Processor Data Book*, and Section 6.2.9.5 "Usage Hints" on page 177).

PCI arbitration should be disabled prior entering the C3 state via the ARB_DIS bit in the PM2_CNT register (F1BAR1+I/O Offset 20h[0]) because a PCI arbitration event could start after P_LVL3 has been read. After wakeup ARB_DIS needs to be cleared.

Core Logic Module Revision 5.1 AMD

6.2.9.2 Sleep States

The SC3200 supports four Sleep states (SL1-SL3) and the Soft Off state (G2/S5). These states are fully compliant with the ACPI specification, revision 1.0.

When the SLP_EN bit (F1BAR1+I/O Offset 0Ch[13]) is set to 1, the SC3200 enters an SLx state according to the SLP_TYPx field (F1BAR1+I/O Offset 0Ch[12:10]). It exits the Sleep state back to the S0 state (C0 state - Full Speed or Throttling, depending on the THT_EN bit) upon an enabled power management event. Table 6-5 on page 175 lists wakeup events from the various Sleep states.

SL1 Sleep State (ACPI S1)

In this state the core processor is in 3V Suspend mode (all its clocks are stopped, including the memory controller and the display controller). The SDRAM is placed in self-refresh mode. All other SC3200 system clocks and PLLs are running. All devices are powered up (PWRCNT[2:1] and ONCTL# are all asserted). See Section 6.2.9.5 "Usage Hints" on page 177.

No reset is performed, when exiting this state. The SC3200 keeps all context in this state. This state corresponds to ACPI Sleep state S1.

SL2 Sleep State (ACPI S1)

In this state, all of the SC3200 clocks are stopped including the PLLs. Selected clocks from the PLLs can be kept running under program control (F0 Index 60h). An exception to this is the CLK32 output signal which keeps toggling and the 32 KHz oscillator itself. The SDRAM is placed in self-refresh mode. The PWRCNT1 pin is de-asserted. The SC3200 itself is powered up. The system designer can

decide which other system devices to power off with the PWRCNT1 pin.

No reset is performed, when exiting this state. The SC3200 keeps all context in this state. This state corresponds to ACPI sleep state S1, with lower power and longer wake time than in SL1.

SL3 Sleep State (ACPI S3)

In this state, the SDRAM is placed in self-refresh mode, and PWRCNT[2:1] are de-asserted. PWRCNT[2:1] should be used to power off most of the system (except for the SDRAM). If the Save-to-RAM feature is used, external circuitry in the SDRAM interface is required to guarantee data integrity. All SC3200 signals powered by $V_{SB},\ V_{SBL}$ or V_{BAT} are still functional to allow wakeup and to keep the RTC.

The power-up sequence is performed, when exiting this state. This state corresponds to ACPI Sleep state S3.

SL4 and SL5 Sleep States (ACPI S4 and S5)

The SL4 and SL5 states are similar from the hardware perspective. In these states, the SC3200 de-asserts PWRCNT[2:1] and ONCTL#. PWRCNT[2:1] and ONCTL# should be used to power off the system. All signals powered by $\rm V_{SB}, \ V_{SBL}$ or $\rm V_{BAT}$ are still functional to allow wakeup and to keep the RTC.

While in this state, LED# can be toggled to give visual notification of this state. ACPI Function Control register (F1BAR1+I/O Offset 07h[7:6]) is used to control LED#.

The power-up sequence is performed when exiting this state. This state corresponds to ACPI Sleep states S4 and S5.

Event	S0/C1	S0/C3	SL1	SL2	SL3	SL4, SL5
Enabled Interrupts	Yes	Yes	Yes	-	-	-
SMI according to Table 6-8	Yes	Yes	Yes	-	-	-
SCI according to Table 6-8	Yes	Yes	Yes	-	-	-
GPIO[47:32], GPIO[15:0]	Yes	Yes	Yes	-	-	-
Power Button	Yes	Yes	Yes	Yes	Yes	Yes
Power Button Override	Yes	Yes	Yes	Yes	Yes	Yes
Bus Master Request	Yes ¹	Yes	Yes	-	-	-
Thermal Monitoring	Yes	Yes	Yes	Yes	Yes	Yes
USB	Yes	Yes	Yes	Yes	-	-
SDATA_IN2 (AC97)	Yes	Yes	Yes	Yes	-	-
IRRX1 (Infrared)	Yes	Yes	Yes	Yes	-	-
GPWIO[2:0]	Yes	Yes	Yes	Yes	Yes	Yes
RI2# (UART2)	Yes	Yes	Yes	Yes	-	-
RTC	Yes	Yes	Yes	Yes	Yes	Yes

Table 6-5. Wakeup Events Capability

^{1.} Temporarily exits state.

6.2.9.3 Power Planes Control

The SC3200 supports up to three power planes. Three signals are used to control these power planes. Table 6-6 describes the signals and when each is asserted.

Table 6-6. Power Planes Control Signals vs. Sleep States

Signal	S0	SL1	SL2	SL3	SL4 and SL5
PWRCNT1	1	1	0	0	0
PWRCNT2	1	1	1	0	0
ONCTL#	0	0	0	0	1

These signals allow control of the power of system devices and the SC3200 itself. Table 6-7 describes the SC3200 power planes with respect to the different Sleep and Global states.

Table 6-7. Power Planes vs. Sleep/Global States

Sleep/ Global State	V _{CORE} , V _{I/O,} V _{PLL}	V _{SB} , V _{SBL}	V _{BAT}
S0, SL1 and SL2	On	On	On or Off
SL3, SL4 and SL5	Off	On	On or Off
G3	Off	Off	On
No Power	Off	Off	Off
Illegal	On	Off	On or Off

The SC3200 power planes are controlled externally by the three signals (i.e., the system designer should make sure the system design is such that Table 6-7 is met) for all supported Sleep states.

 $\rm V_{SB}$ and $\rm V_{BAT}$ are not controlled by any control signal. $\rm V_{SB}$ exists as long as the AC power is plugged in (for desktop systems) or the main battery is charged (for mobile systems). $\rm V_{BAT}$ exists as long as the RTC battery is charged.

The case in which V_{SB} does not exist is called Mechanical Off (G3).

6.2.9.4 Power Management Events

The SC3200 supports power management events that can manage:

- Transition of the system from a Sleep state to a Work state. This is done by the hardware. These events are defined as wakeup events.
- Enabled wakeup events to set the WAK_STS bit (F1BAR1+I/O Offset 08h[15]) to 1, when transitioning the system back to the working state.
- Generation of an interrupt. This invokes the relevant software driver. The interrupt can either be an SMI or SCI (selected by the SCI_EN bit, F1BAR1+I/O Offset 0Ch[0]). These events are defined as interrupt events.

Table 6-8 lists the power management events that can generate an SCI or SMI.

Table 6-8. Power Management Events

Event	SCI	SMI
Power Button	Yes	Yes
Power Button Override	Yes	-
Bus Master Request	Yes	-
Thermal Monitoring	Yes	Yes
USB	Yes	Yes
RTC	Yes	Yes
ACPI Timer	Yes	Yes
GPIO	Yes	Yes
SDATA_IN2 (AC97)	Yes	Yes
IRRX1	Yes	Yes
RI2#	Yes	Yes
GPWIO	Yes	Yes
Internal SMI signal	Yes	-

Core Logic Module Revision 5.1

Power Button

The power button (PWRBTN#) input provides two events: a wake request, and a sleep request. For both these events, the PWRBTN# signal is debounced (i.e., the signal state is transferred only after 14 to 16 ms without transitions, to ensure that the signal is no longer bouncing).

ACPI is non-functional and all ACPI outputs are undefined when the power-up sequence does not include using the power button. SUSP# is an internal signal generated from the ACPI block. Without an ACPI reset, SUSP# can be permanently asserted. If the USE_SUSP bit in CCR2 of GX1 module is enabled (Index C2h[7] = 1), the CPU will stop.

If ACPI functionality is desired, or the situation described above avoided, the power button must be toggled. This can be done externally or internally. GPIO63 is internally connected to PWRBTN#. To toggle the power button with software, GPIO63 must be programmed as an output using the normal GPIO programming protocol (see Section 6.4.1.1 "GPIO Support Registers" on page 240). GPIO63 must be pulsed low for at least 16 ms and not more than 4 sec.

Asserting POR# has no effect on ACPI. If POR# is asserted and ACPI was active prior to POR#, then ACPI will remain active after POR#. Therefore, BIOS must ensure that ACPI is inactive before GPIO63 is pulsed low.

Power Button Wake Event - Detection of a high-to-low transition on the debounced PWRBTN# input signal when in SL1 to SL5 Sleep states. The system is considered in the Sleep state, only after it actually transitioned into the state and not only according to the SLP_TYP field.

In reaction to this event, the PWRBTN_STS bit (F1BAR1+I/O Offset 08h[8]) is set to 1 and a wakeup event or an interrupt is generated (note that this is regardless of the PWRBTN_EN bit, F1BAR1+I/O Offset 0Ah[8]).

Power Button Sleep Event - Detection of a high-to-low transition on the debounced PWRBTN# input signal, when in the Working state (S0).

In reaction to this event, the PWRBTN_STS bit is set to 1.

- When both the PWRBTN_STS bit and the PWRBTN_EN bit are set to 1, an SCI interrupt is generated.
- When SCI_EN bit is 0, ONCTL# and PWRCNT[2:1] are de-asserted immediately regardless of the PWRBTN_EN bit.

Power Button Override

When PWRBTN# is 0 for more than four seconds, ONCTL# and PWRCNT[2:1] are de-asserted (i.e., the system transitions to the SL5 state, "Soft Off"). This power management event is called the power button override event.

In reaction to this event, the PWRBTN_STS bit is cleared to 0 and the PWRBTNOR_STS bit (F1BAR1+I/O Offset 08h[11]) is set to 1.

Thermal Monitoring

The thermal monitoring event (THRM#) enables control of ACPI-OS Control.

When the THRM# signal transitions from high-to-low, the THRM_STS bit (F1BAR1+I/O Offset 10h[5]) is set to 1. If the THRM_EN bit (F1BAR1+I/O Offset 12h[5]) is also set to 1, an interrupt is generated.

SDATA_IN2, IRRX1, RI2#

Section 5.4.1 "SIO Control and Configuration Registers" on page 113 for control and operation.

6.2.9.5 Usage Hints

- · During initialization, the BIOS should:
 - Clear the SUSP_HLT bit in CCR2 (GX1 module, Index C2h[3]) to 0. This is needed for compliance with C0 definition of ACPI, when the Halt Instruction (HLT) is executed.
 - Disable the SUSP_3V option in C3 power state (F0 Index 60h[2]).
 - Disable the SUSP_3V option in SL1 sleep state (F0 Index 60h[1]).
- SMM code should clear the CLK_STP bit in the PM Clock Stop Control register (GX_BASE+Memory Offset 8500h[0]) to 0 when entering C3 state.
- SMM code should correctly set the CLK_STP bit in the PM Clock Stop Control register (GX_BASE+Memory Offset 8500h[0]) when entering the SL1, SL2, and SL3 states.

6.2.10 Power Management Programming

The power management resources provided by a combined GX1 module and Core Logic module based system supports a high efficiency power management implementation. The following explanations pertain to a full-featured "notebook" power management system. The extent to which these resources are employed depends on the application and on the discretion of the system designer.

Power management resources can be grouped according to the function they enable or support. The major functions are as follows:

- APM Support
- CPU Power Management
 - Suspend Modulation
 - 3V Suspend
 - Save-to-Disk
- · Peripheral Power Management
 - Device Idle Timers and Traps
 - General Purpose Timers
 - ACPI Timer Register
 - Power Management SMI Status Reporting Registers

Included in the following subsections are details regarding the registers used for configuring power management features. The majority of these registers are directly accessed through the PCI configuration register space designated as Function 0 (F0). However, included in the discussions are references to F1BARx+I/O Offset xxh. This refers to registers accessed through base address registers in Function 1 (F1) at Index 10h (F1BAR0) and Index 40h (F1BAR1).

6.2.10.1 APM Support

Many notebook computers rely solely on an Advanced Power Management (APM) driver for enabling the operating system to power-manage the CPU. APM provides several services which enhance the system power management; but in its current form, APM is imperfect for the following reasons:

- APM is an OS-specific driver, and may not be available for some operating systems.
- Application support is inconsistent. Some applications in foreground may prevent Idle calls.
- APM does not help with Suspend determination or peripheral power management.

The Core Logic module provides two entry points for APM support:

- Software CPU Suspend control via the CPU Suspend Command register (F0 Index AEh)
- Software SMI entry via the Software SMI register (F0 Index D0h). This allows the APM BIOS to be part of the SMI handler.

6.2.10.2 CPU Power Management

The three greatest power consumers in a system are the display, the hard drive, and the CPU. The power management of the first two is relatively straightforward and is discussed in Section 6.2.10.3 "Peripheral Power Management" on page 180.

APM, if available, is used primarily by CPU power management since the operating system is most capable of reporting the Idle condition. Additional resources provided by the Core Logic module supplement APM by monitoring external activity and power managing the CPU based on the system demands. The two processes for power managing the CPU are Suspend Modulation and 3V Suspend.

Suspend Modulation

Suspend Modulation works by asserting and de-asserting the internal SUSP# signal to the GX1 module for configurable durations. When SUSP# is asserted to the GX1 module, it enters an Idle state during which time the power consumption is significantly reduced. Even though the PCI clock is still running, the GX1 module stops the clocks to its core when SUSP# is asserted. By modulating SUSP# a reduced frequency of operation is achieved.

The Suspend Modulation feature works by assuming that the GX1 module is Idle unless external activity indicates otherwise. This approach effectively slows down the GX1 module until external activity indicates a need to run at full speed, thereby reducing power consumption. This approach is the opposite of that taken by most power management schemes in the industry, which run the system at full speed until a period of inactivity is detected, and then slows down. Suspend Modulation, the more aggressive approach, yields lower power consumption.

Suspend Modulation serves as the primary CPU power management mechanism when APM is not present. It also acts as a backup for situations where APM does not correctly detect an Idle condition in the system.

To provide high-speed performance when needed, SUSP# modulation is temporarily disabled any time system activity is detected. When this happens, the GX1 module is "instantly" converted to full speed for a programmed duration. System activities in the Core Logic module are asserted as: any unmasked IRQ, accessing Port 061h, any asserted SMI, and/or accessing the Video Processor module interface.

The graphics controller is integrated in the GX1 module. Therefore, the indication of video activity is sent to the Core Logic module via the serial link (see Section 6.2.2 "PSE-RIAL Interface" on page 159 for more information on serial link) and is automatically decoded. Video activity is defined as any access to the VGA register space, the VGA frame buffer, the graphics accelerator control registers and the configured graphics frame buffer.

Core Logic Module Revision 5.1

The automatic speedup events (video and IRQ) for Suspend Modulation should be used together with software-controlled speedup registers for major I/O events such as any access to the FDC, HDD, or parallel/serial ports, since these are indications of major system activities. When major I/O events occur, Suspend Modulation should be temporarily disabled using the procedures described in the Power Management registers in the following subsections.

If a bus master (UltraDMA/33, Audio, USB) request occurs, the GX1 module automatically de-asserts SUSPA# and grants the bus to the requesting bus master. When the bus master de-asserts REQ#, SUSPA# reasserts. This does not directly affect the Suspend Modulation programming.

Configuring Suspend Modulation: Control of the Suspend Modulation feature is accomplished using the Suspend Modulation and Suspend Configuration registers (F0 Index 94h and 96h, respectively).

The Suspend Configuration register contains the global power management enable bit, as well as the enables for the individual activity speedup timers. The global power management bit must be enabled for Suspend Modulation and all other power management resources to function.

Bit 0 of the Suspend Configuration register enables Suspend Modulation. Bit 1 controls how SMI events affect Suspend Modulation. In general this bit should be set to 1, which causes SMIs to disable Suspend Modulation until it is re-enabled by the SMI handler.

The Suspend Modulation register controls two 8-bit counters that represent the number of 32 µs intervals that the internal SUSP# signal is asserted and then deasserted to the GX1 module. These counters define a ratio which is the effective frequency of operation of the system while Suspend Modulation is enabled.

$$F_{eff} = F_{GX1} \ \ \, x \ \ \, \frac{\text{Asserted Count}}{\text{Asserted Count + De-asserted Count}}$$

The IRQ and Video Speedup Timer Count registers (F0 Index 8Ch and 8Dh) configure the amount of time which Suspend Modulation is disabled when the respective events occur.

SMI Speedup Disable: If the Suspend Modulation feature is being used for CPU power management, the occurrence of an SMI disables Suspend Modulation so that the system operates at full speed while in SMM. There are two methods used to invoke this via bit 1 of the Suspend Configuration register.

- If F0 Index 96h[1] = 0: Use the IRQ Speedup Timer (F0 Index 8Ch) to temporarily disable Suspend Modulation when an SMI occurs.
- If F0 Index 96h[1] = 1: Disable Suspend Modulation when an SMI occurs until a read to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h).

The SMI Speedup Disable register prevents VSA software from entering Suspend Modulation while operating in SMM. The data read from this register can be ignored. If the Suspend Modulation feature is disabled, reading this I/O location has no effect.

3 Volt Suspend

The Core Logic module supports the stopping of the CPU and system clocks for a 3V Suspend state. If appropriately configured, via the Clock Stop Control register (F0 Index BCh), the Core Logic module asserts internal SUSP_3V after it has gone through the SUSP#/SUSPA# handshake. SUSP_3V is a state indicator, indicating that the system is in a low-activity state and Suspend Modulation is active. This indicator can be used to put the system into a low-power state (the system clock can be turned off).

Internal SUSP_3V is connected to the enable control of the clock generators, so that the clocks to the CPU and the Core Logic module (and most other system devices) are stopped. The Core Logic module continues to decrement all of its device timers and respond to external SMI interrupts after the input clock has been stopped, as long as the 32 KHz clock continues to oscillate. Any SMI event or unmasked interrupt causes the Core Logic module to deassert SUSP 3V, restarting the system clocks. As the CPU or other device might include a PLL, the Core Logic module holds SUSP# active for a pre-programmed period of delay (the PLL re-sync delay) that varies from 0 to 15 ms. After this period has expired, the Core Logic module de-asserts SUSP#, stopping Suspend. SMI# is held active for the entire period, so that the CPU reenters SMM when the clocks are restarted.

Save-to-Disk

Save-to-Disk is supported by the Core Logic module. In this state, the power is typically removed from the Core Logic module and from the entire SC3200, causing the state of the legacy peripheral devices to be lost. Shadow registers are provided for devices which allow their state to be saved prior to removing power. This is necessary because the legacy AT peripheral devices used several write only registers. To restore the exact state of these devices on resume, the write only register values are "shadowed" so that the values can be saved by the power management software.

The PC/AT compatible keyboard controller (KBC) and floppy port (FDC) do not exist in the SC3200. However, it is possible that one is attached on the ISA bus or the LPC bus (e.g., in a Superl/O device). Some of the KBC and FDC registers are shadowed because they cannot be safely read. Additional shadow registers for other functions are described in Table 6-29 "FO: PCI Header/Bridge Configuration Registers for GPIO and LPC Support" on page 206.

6.2.10.3 Peripheral Power Management

The Core Logic module provides peripheral power management using a combination of device idle timers, address traps, and general purpose I/O pins. Idle timers are used in conjunction with traps to support powering down peripheral devices.

Device Idle Timers and Traps

Idle timers are used to power manage a peripheral by determining when the peripheral has been inactive for a specified period of time, and removing power from the peripheral at the end of that time period.

Idle timers are provided for the commonly-used peripherals (FDC, IDE, Parallel/Serial Ports, and Mouse/Keyboard). In addition, there are three user-defined timers that can be configured for either I/O or memory ranges.

The idle timers are 16-bit countdown timers with a one second timebase or prescaler, providing a timeout range of 1 to 65536 seconds (1092 minutes) (18 hours). The input clock is 32 KHz. Very small count values have some error since the prescaler is free-running. (See the next subsection "General Purpose Timers" for further discussion on prescaler value limitations.)

When the idle timer count registers are loaded with a nonzero value and enabled, the timers decrement until one of two possibilities happens: a bus cycle occurs at that I/O or memory range, or the timer decrements to zero.

If a bus cycle occurs, the timer is reloaded and begins decrementing again. If the timer decrements to zero, and power management is enabled (F0 Index 80h[0] = 1), the timer generates an SMI.

When an idle timer generates an SMI, the SMI handler manages the peripheral power, disables the timer, and enables the trap. The next time an event occurs, the trap generates an SMI. This time, the SMI handler applies power to the peripheral, resets the timer, and disables the

Relevant registers for controlling Device Idle Timers are: F0 Index 80h, 81h, 82h, 93h, 98h-9Eh, and ACh.

Relevant registers for controlling User Defined Device Idle Timers are: F0 Index 81h, 82h, A0h, A2h, A4h, C0h, C4h, C8h, CCh, CDh, and CEh.

Although not considered as device idle timers, two additional timers are provided by the Core Logic module. The Video Idle Timer used for Suspend-determination and the VGA Timer used for SoftVGA.

The programming bits for these timers are:

- F0 Index 81h[7], Video Access Idle Timer Enable
- F0 Index 82h[7], Video Access Trap Enable
- F0 Index A6h[15:0], Video Timer Count
- F0 Index 83h[3], VGA Timer Enable
- F0 Index 8Bh[6], VGA Timer Base F0 Index 8Eh[7:0], VGA Timer Count

General Purpose Timers

The Core Logic module contains two general purpose idle timers, General Purpose Timer 1 (F0 Index 88h) and General Purpose Timer 2 (F0 Index 8Ah). These two timers are similar to the Device Idle Timers in that they count down to zero unless re-triggered, and generate an SMI when they reach zero. However, these are 8-bit timers instead of 16 bits, they have a programmable timebase, and the events which reload these timers are configurable. These timers are typically used for an indication of system inactivity for Suspend determination.

General Purpose Timer 1 can be re-triggered by activity to any of the configured User Defined Devices, Keyboard and Mouse, Parallel and Serial, Floppy disk, or Hard disk.

General Purpose Timer 2 can be re-triggered by a transition on the GPIO7 signal (if GPIO7 is properly configured).

When a General Purpose Timer is enabled or when an event reloads the timer, the timer is loaded with the configured count value. Upon expiration of the timer an SMI is generated and a status flag is set. Once expired, this counter must be re-initialized by disabling and enabling it.

The timebase or prescaler for both General Purpose Timers can be configured as either 1 second (default) or 1 millisecond. The 32 KHz clock feeds the prescaler. The registers at F0 Index 89h and 8Bh are the control registers for the General Purpose Timers.

The prescaler (1 millisecond or 1 second) that feeds the timers is free-running; meaning that the first count decrement will not be correct. The decrement time can be as short as 0 or as long as the prescaler. The actual time for the decrement to occur can not be determined since the current prescaler value can not be read. A periodic timer can be achieved after the first timer SMI, because when retriggered, the prescaler will be at or very nearly at the maximum value. Any software using these timers must understand this limitation. Small count values have the most error with a value of 1having the largest error.

ACPI Timer Register

The ACPI Timer register (F1BAR0+I/O Offset 1Ch or at F1BAR1+I/O Offset 1Ch) provides the ACPI counter. The counter counts at 14.31818/4 MHz (3.579545 MHz). If SMI generation is enabled (F0 Index 83h[5] = 1), an SMI or SCI is generated when bit 23 toggles.

Core Logic Module Revision 5.1 AMD

Power Management SMI Status Reporting Registers

The Core Logic module updates status registers to reflect the SMI sources. Power management SMI sources are the device idle timers, address traps, and general purpose I/O pins.

Power management events are reported to the GX1 module through the active low SMI# signal. When an SMI is initiated, the SMI# signal is asserted low and is held low until all SMI sources are cleared. At that time, SMI# is deasserted.

All SMI sources report to the Top Level SMI Status register (F1BAR0+I/O Offset 02h) and the Top Level SMI Status Mirror register (F1BAR0+I/O Offset 00h). The Top SMI Status and Status Mirror registers are the top level of hierarchy for the SMI Handler in determining the source of an SMI.

These two registers are identical except that reading the register at F1BAR0+I/O Offset 02h clears the status.

Since all SMI sources report to the Top Level SMI Status register, many of its bits combine a large number of events requiring a second level of SMI status reporting. The second level of SMI status reporting is set up very much like the top level. There are two status reporting registers, one "read only" (mirror) and one "read to clear". The data returned by reading either offset is the same, the difference between the two being that the SMI can not be cleared by reading the mirror register.

Figure 6-11 on page 181 shows an example SMI tree for checking and clearing the source of General Purpose Timers and the User Defined Trap generated SMI.

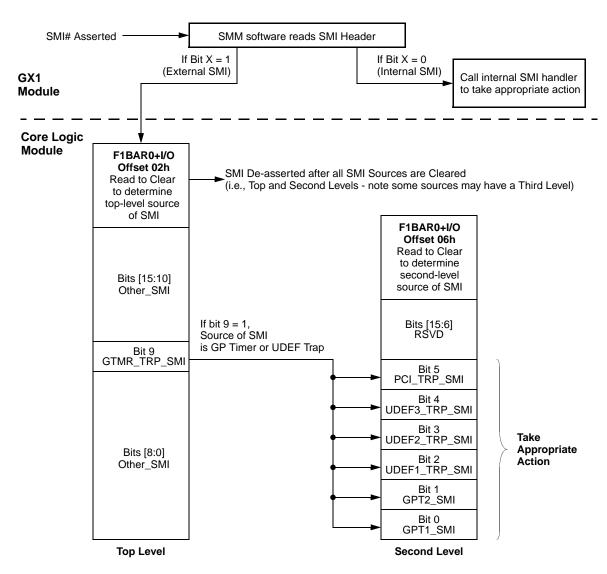


Figure 6-11. General Purpose Timer and UDEF Trap SMI Tree Example

Revision 5.1 Core Logic Module

6.2.10.4 Power Management Programming Summary

Table 6-9 provides a programming register summary for the power management timers, traps, and functions. For

complete bit information regarding the registers listed in Table 6-9, refer to Section 6.4.1 "Bridge, GPIO, and LPC Registers - Function 0" on page 206.

Table 6-9. Device Power Management Programming Summary

	Located at F0 Index xxh Unless Otherwise Noted								
Device Power Management Resource	Enable	Configuration	Second Level SMI Status/No Clear	Second Level SMI Status/With Clear					
Global Timer Enable	80h[0]	N/A	N/A	N/A					
Keyboard / Mouse Idle Timer	81h[3]	93h[1:0]	85h[3]	F5h[3]					
Parallel / Serial Idle Timer	81h[2]	93h[1:0]	85h[2]	F5h[2]					
Floppy Disk Idle Timer	81h[1]	9Ah[15:0], 93h[7]	85h[1]	F5h[1]					
Video Idle Timer ¹	81h[7]	A6h[15:0]	85h[7]	F5h[7]					
VGA Timer ²	83h[3]	8Eh[7:0]	F1BAR0+I/O Offset 00h[6]	F1BAR0+I/O Offset 02h[6]					
Primary Hard Disk Idle Timer	81h[0]	98h[15:0], 93h[5]	85h[0]	F5h[0]					
Secondary Hard Disk Idle Timer	83h[7]	ACh[15:0], 93h[4]	86h[4]	F6h[4]					
User Defined Device 1 Idle Timer	81h[4]	A0h[15:0], C0h[31:0], CCh[7:0]	85h[4]	F5h[4]					
User Defined Device 2 Idle Timer	81h[5]	A2h[15:0], C4h[31:0], CDh[7:0]	85h[5]	F5h[5]					
User Defined Device 3 Idle Timer	81h[6]	A4h[15:0], C8h[31:0], CEh[7:0]	85h[6]	F5h[6]					
Global Trap Enable	80h[2]	N/A	N/A	N/A					
Keyboard / Mouse Trap	82h[3]	9Eh[15:0] 93h[1:0]	86h[3]	F6h[3]					
Parallel / Serial Trap	82h[2]	9Ch[15:0], 93h[1:0]	86h[2]	F6h[2]					
Floppy Disk Trap	82h[1]	93h[7]	86h[1]	F6h[1]					
Video Access Trap	82h[7]	N/A	86h[7]	F6h[7]					
Primary Hard Disk Trap	82h[0]	93h[5]	86h[0]	F6h[0]					
Secondary Hard Disk Trap	83h[6]	93h[4]	86h[5]	F6h[5]					
User Defined Device 1 Trap	82h[4]	C0h[31:0], CCh[7:0]	F1BAR0+I/O Offset 04h[2]	F1BAR0+I/O Offset 06h[2]					
User Defined Device 2 Trap	82h[5]	C4h[31:0], CDh[7:0]	F1BAR0+I/O Offset 04h[3]	F1BAR0+I/O Offset 06h[3]					
User Defined Device 3 Trap	82h[6]	C8h[31:0], CEh[7:0]	F1BAR0+I/O Offset 04h[4]	F1BAR0+I/O Offset 06h[4]					
General Purpose Timer 1	83h[0]	88h[7:0], 89h[7:0], 8Bh[4]	F1BAR0+I/O Offset 04h[0]	F1BAR0+I/O Offset 06h[0]					
General Purpose Timer 2	83h[1]	8Ah[7:0], 8Bh[5,3,2]	F1BAR0+I/O Offset 04h[1]	F1BAR0+I/O Offset 06h[1]					
Suspend Modulation	96h[0]	94h[15:0], 96h[2:0]	N/A	N/A					
Video Speedup	80h[4]	8Dh[7:0], A8h[15:0]	N/A	N/A					
IRQ Speedup	80h[3]	8Ch[7:0]	N/A	N/A					

^{1.} This function is used for Suspend determination.

^{2.} This function is used for SoftVGA.

Core Logic Module Revision 5.1 AMD

6.2.11 GPIO Interface

Up to 64 GPIOs in the in the Core Logic module are provided for system control. For further information, see Section 4.2 "Multiplexing, Interrupt Selection, and Base Address Registers" on page 88 and Table 6-30 "F0BAR0+I/O Offset: GPIO Configuration Registers" on page 240.

Note: Not all GPIOs are available on SC3200 balls. GPIOs [63:42], [31:21], and [5:2] are reserved.

6.2.12 Integrated Audio

The Core Logic module provides hardware support for the Virtual (soft) Audio subsystem as part of the Virtual System Architecture[®] (VSA[™]) technology for capture and playback of audio using an external codec. This eliminates much of the hardware traditionally associated with audio functions.

This hardware support includes:

- Six-channel buffered PCI bus mastering interface.
- AC97 version 2.0 compatible interface to the codec. Any codec, which supports an independent input and output sample rate conversion interface, can be used with the Core Logic module.

Additional hardware provides the necessary functionality for VSA. This hardware includes the ability to:

- Generate an SMI to alert software to update required data. An SMI is generated when either audio buffer is half empty or full. If the buffers become completely empty or full, the Empty bit is asserted.
- Generate an SMI on I/O traps.
- Trap accesses for sound card compatibility at either I/O Port 220h-22Fh, 240h-24Fh, 260h-26Fh, or 280h-28Fh.
- Trap accesses for FM compatibility at I/O Port 388h-38Bh.

- Trap accesses for MIDI UART interface at I/O Port 300h-301h or 330h-331h.
- Trap accesses for serial input and output at COM2 (I/O Port 2F8h-2FFh) or COM4 (I/O Port 2E8h-2EFh).
- Support trapping for low (I/O Port 00h-0Fh) and/or high (I/O Port C0h-DFh) DMA accesses.
- Support hardware status register reads in Core Logic module, minimizing SMI overhead.
- Support is provided for software-generated IRQs on IRQ 2, 3, 5, 7, 10, 11, 12, 13, 14, and 15.

The following subsections include details of the registers used for configuring the audio interface. The registers are accessed through F3 Index 10h, the Base Address Register (F3BAR0) in Function 3. F3BAR0 sets the base address for the audio support registers as shown in Table 6-37 "F3: PCI Header Registers for Audio Configuration" on page 279.

6.2.12.1 Data Transport Hardware

The data transport hardware can be broadly divided into two sections: bus mastering and the codec interface.

Audio Bus Masters

The Core Logic module audio hardware includes six PCI bus masters (three for input and three for output) for transferring digitized audio between memory and the external codec. With these bus master engines, the Core Logic module off-loads the CPU and improves system performance.

The programming interface defines a simple scatter/gather mechanism allowing large transfer blocks to be scattered to or gathered from memory. This cuts down on the number of interrupts to and interactions with the CPU.

The six bus masters that directly drive specific slots on the AC97 interface are described in Table 6-10.

Table 6-10. Bus Masters That Drive Specific Slots of the AC97 Interface

Audio Bus Master #	Slots	Description
0	3 and 4	32-Bit output to codec. Left and right channels.
1	3 and 4	32-Bit input from codec. Left and right channels.
2	5	16-Bit output to codec.
3	5	16-Bit input from codec.
4	6 or 11	16-Bit output to codec. Slot in use is determined by F3BAR0+Memory Offset 08h[19].
5	6 or 11	16-Bit input from codec. Slot in use is determined by F3BAR0+Memory Offset 08h[20].

Revision 5.1 Core Logic Module

Physical Region Descriptor Table Address

Before the bus master starts a master transfer it must be programmed with a pointer (PRD Table Address register) to a Physical Region Descriptor Table. This pointer sets the starting memory location of the Physical Region Descriptors (PRDs). The PRDs describe the areas of memory that are used in the data transfer. The descriptor table entries must be aligned on a 32-byte boundary and the table cannot cross a 64 KB boundary in memory.

Physical Region Descriptor Format

Each physical memory region to be transferred is described by a Physical Region Descriptor (PRD) as illustrated in Table 6-11. When the bus master is enabled (Command register bit 0 = 1), data transfer proceeds until each PRD in the PRD table has been transferred. The bus master does not cache PRDs.

The PRD table consists of two DWORDs. The first DWORD contains a 32-bit pointer to a buffer to be transferred. The second DWORD contains the size (16 bits) of the buffer and flags (EOT, EOP, JMP). The description of the flags are as follows:

- EOT bit If set in a PRD, this bit indicates the last entry in the PRD table (bit 31). The last entry in a PRD table must have either the EOT bit or the JMP bit set. A PRD can not have both the JMP and EOT bits set.
- EOP bit If set in a PRD and the bus master has completed the PRD's transfer, the End of Page bit is set (Status register bit 0 = 1) and an SMI is generated. If a second EOP is reached due to the completion of another PRD before the End of Page bit is cleared, the Bus Master Error bit is set (Status register bit 1 = 1) and the bus master pauses. In this paused condition, reading the Status register clears both the Bus Master Error and the End of Page bits and the bus master continues.
- JMP bit This PRD is special. If set, the Memory Region Physical Base Address is now the target address of the JMP. The target address must be on a 32-byte boundary so bits[4:0] must be written to 0. There is no data transfer with this PRD. This PRD allows the creation of a

looping mechanism. If a PRD table is created with the JMP bit set in the last PRD, the PRD table does not need a PRD with the EOT bit set. A PRD can not have both the JMP and EOT bits set.

Programming Model

The following discussion explains, in steps, how to initiate and maintain a bus master transfer between memory and an audio slave device.

In the steps listed below, the reference to "Example" refers to Figure 6-12 "PRD Table Example" on page 185.

- Software creates a PRD table in system memory. Each PRD entry is 8 bytes long; consisting of a base address pointer and buffer size. The maximum data that can be transferred from a PRD entry is 64 KB. A PRD table must be aligned on a 32-byte boundary. The last PRD in a PRD table must have the EOT or JMP bit set.
 - **Example** Assume the data is outbound. There are three PRDs in the example PRD table. The first two PRDs (PRD_1, PRD_2) have only the EOP bit set. The last PRD (PRD_3) has only the JMP bit set. This example creates a PRD loop.
- Software loads the starting address of the PRD table by programming the PRD Table Address register.
 - **Example** Program the PRD Table Address register with Address_3.
- 3) Software must fill the buffers pointed to by the PRDs with audio data. It is not absolutely necessary to fill the buffers; however, the buffer filling process must stay ahead of the buffer emptying. The simplest way to do this is by using the EOP flags to generate an SMI when a PRD is empty.

Example - Fill Audio Buffer_1 and Audio Buffer_2. The SMI generated by the EOP from the first PRD allows the software to refill Audio Buffer_1. The second SMI refills Audio Buffer_2. The third SMI refills Audio Buffer_1 and so on.

Table 6-11. Pl	nysical Region	Descriptor	Format
----------------	----------------	------------	--------

	Byte 3							By	te 2				Byte 1					Byte 0													
DWORD	31 30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0		Memory Region Base Address [31:1] (Audio Data Buffer) 0									0																				
1	E E O O T P	E E J Reserved Size [15:1] 0								0																					

Core Logic Module Revision 5.1 AMD

 Read the SMI Status register to clear the Bus Master Error and End of Page bits (bits 1 and 0).

Set the correct direction to the Read or Write Control bit (Command register bit 3). Note that the direction of the data transfer of a particular bus master is fixed and therefore the direction bit must be programmed accordingly. It is assumed that the codec has been properly programmed to receive the audio data.

Engage the bus master by writing a "1" to the Bus Master Control bit (Command register bit 0).

The bus master reads the PRD entry pointed to by the PRD Table Address register and increments the address by 08h to point to the next PRD. The transfer begins.

Example - The bus master is now properly programmed to transfer Audio Buffer_1 to a specific slot(s) in the AC97 interface.

5) The bus master transfers data to/from memory responding to bus master requests from the AC97 interface. At the completion of each PRD, the bus master's next response depends on the settings of the flags in the PRD.

Example - At the completion of PRD_1 an SMI is generated because the EOP bit is set while the bus master continues on to PRD_2. The address in the PRD

Table Address register is incremented by 08h and is now pointing to PRD_3. The SMI Status register is read to clear the End of Page status flag. Since Audio Buffer_1 is now empty, the software can refill it.

At the completion of PRD_2 an SMI is generated because the EOP bit is set. The bus master then continues on to PRD_3. The address in the PRD Table Address register is incremented by 08h. The DMA SMI Status register is read to clear the End of Page status flag. Since Audio Buffer_2 is now empty, the software can refill it. Audio Buffer_1 has been refilled from the previous SMI.

PRD_3 has the JMP bit set. This means the bus master uses the address stored in PRD_3 (Address_3) to locate the next PRD. It does not use the address in the PRD Table Address register to get the next PRD. Since Address_3 is the location of PRD_1, the bus master has looped the PRD table.

Stopping the bus master can be accomplished by not reading the SMI Status register End of Page status flag. This leads to a second EOP which causes a Bus Master Error and pauses the bus master. In effect, once a bus master has been enabled it never has to be disabled, just paused. The bus master cannot be disabled unless the bus master has been paused or has reached an EOT.

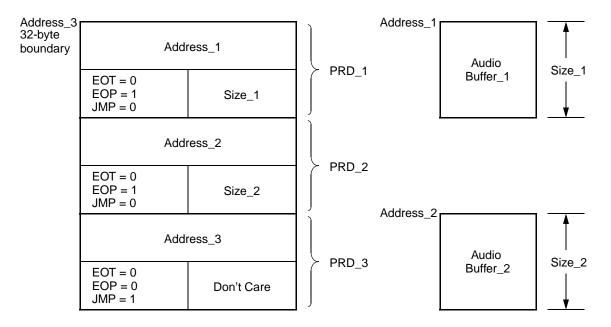


Figure 6-12. PRD Table Example

Revision 5.1 Core Logic Module

6.2.12.2 AC97 Codec Interface

The AC97 codec (e.g., LM4548) is the master of the serial interface and generates the clocks to Core Logic module. Figure 6-13 shows the signal connections between two codecs and the SC3200:

- Codec1 can be AC97 Rev. 1.3 or higher compliant.
- Codec2 is optional, but must be compliant with AC97 2.0 or higher. (For specifics on the serial interface, refer to the appropriate codec manufacturer's data book.)
 - SDATA_IN2 has wakeup capability. (See Section 5.6 "System Wakeup Control (SWC)" on page 132.)
 - If SDATA_IN2 is not used it must be connected to V_{SS}.
 - If an AMC97 codec is used (as Codec2), it should be connected to SDATA_IN2 and SDATA_IN should be connected to V_{SS}.
- For PC speaker synthesis, the Core Logic module outputs the PC speaker signal on the PC_BEEP pin which is connected to the PC_BEEP input of the AC97 codec. Note that PC_BEEP is muxed with GPIO16 and must be programmed via PMR[0] (see Table 4-2 on page 88.)

Codec Configuration/Control Registers

The codec 32-bit related registers:

- · GPIO Status and Control Registers
 - Codec GPIO Status Register (F3BAR0+Memory Offset 00h)
 - Codec GPIO Control Register (F3BAR0+Memory Offset 04h)
- Codec Status Register (F3BAR0+Memory Offset 08h)
- Codec Command Register (F3BAR0+Memory Offset 0Ch)

Codec GPIO Status and Control Registers:

The Codec GPIO Status and Control registers are used for codec GPIO related tasks such as enabling a codec GPIO interrupt to cause an SMI.

Codec Status Register:

The Codec Status register stores the codec status WORD. It is updated every valid Status Word slot.

Codec Command Register:

The Codec Command register writes the control WORD to the codec. By writing the appropriate control WORDs to this port, the features of the codec can be controlled. The contents of this register are written to the codec during the Control Word slot.

The bit formats for these registers are given in Table 6-38 "F3BAR0+Memory Offset: Audio Configuration Registers" on page 280.

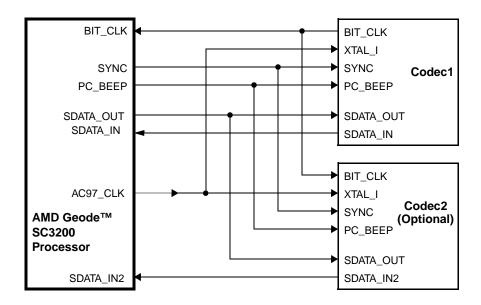


Figure 6-13. AC97 V2.0 Codec Signal Connections

Core Logic Module Revision 5.1 AMD

6.2.12.3 VSA Technology Support Hardware

The Core Logic module incorporates the required hardware in order to support the Virtual System Architecture[®] (VSA) technology for capture and playback of audio using an external codec. This eliminates much of the hardware traditionally associated with industry standard audio functions.

VSA Technology

VSA technology provides a framework to enable software implementation of traditionally hardware-only components. VSA software executes in System Management Mode (SMM), enabling it to execute transparently to the operating system, drivers and applications.

The VSA design is based upon a simple model for replacing hardware components with software. Hardware to be virtualized is merely replaced with simple access detection circuitry which asserts the SMI# (System Management Interrupt) internal signal when hardware accesses are detected. The current execution stream is immediately preempted, and the processor enters SMM. The SMM system software then saves the processor state, initializes the VSA execution environment, decodes the SMI source and dispatches handler routines which have registered requests to service the decoded SMI source. Once all handler routines have completed, the processor state is restored and normal execution resumes. In this manner, hardware accesses are transparently replaced with the execution of SMM handler software.

Historically, SMM software was used primarily for the single purpose of facilitating active power management for note-book designs. That software's only function was to manage the power up and down of devices to save power. With high performance processors now available, it is feasible to implement, primarily in SMM software, PC capabilities traditionally provided by hardware. In contrast to power management code, this virtualization software generally has strict performance requirements to prevent application performance from being significantly impacted.

Audio SMI Related Registers

The SMI related registers consist of:

- Audio SMI Status Reporting Registers:
 - Top Level SMI Mirror and Status Registers (F1BAR0+Memory Offset 00h/02h)
 - Second Level SMI Status Registers (F3BAR0+Memory Offset 10h/12h)
- I/O Trap SMI and Fast Write Status Register (F3BAR0+Memory Offset 14h)
- I/O Trap SMI Enable Register (F3BAR0+Memory Offset 18h)

Audio SMI Status Reporting Registers:

The Top SMI Status Mirror and Status registers are the top level of hierarchy for the SMI Handler in determining the source of an SMI. These two registers are at F1BAR0+Memory Offset 00h (Status Mirror) and 02h (Status). The registers are identical except that reading the register at F1BAR0+Memory Offset 02h clears the status.

The second level of audio SMI status reporting is set up very much like the top level. There are two status reporting registers, one "read only" (mirror) and one "read to clear". The data returned by reading either offset is the same (i.e., SMI was caused by an audio related event). The difference between F3BAR0+Memory Offset 10h (Status Mirror) and 12h (Status) is in the ability to clear the SMI source at 12h.

Figure 6-14 on page 188 shows an SMI tree for checking and clearing the source of an audio SMI. Only the audio SMI bit is detailed here. For details regarding the remaining bits in the Top SMI Status Mirror and Status registers refer to Table 6-33 "F1BAR0+I/O Offset: SMI Status Registers" on page 253.

I/O Trap SMI and Fast Write Status Register:

This 32-bit read-only register (F3BAR0+Memory Offset 14h) not only indicates if the enabled I/O trap generated an SMI, but also contains Fast Path Write related bits.

I/O Trap SMI Enable Register:

The I/O Trap SMI Enable register (F3BAR0+Memory Offset 18h) allows traps for specified I/O addresses and configures generation for I/O events. It also contains the enabling bit for Fast Path Read/Write features.

Status Fast Path Read/Write

Status Fast Path Read – If enabled, the Core Logic module intercepts and responds to reads to several status registers. This speeds up operations, and prevents SMI generation for reads to these registers. This process is called Status Fast Path Read. Status Fast Path Read is enabled via F3BAR0+Memory Offset 18h[4].

In Status Fast Path Read the Core Logic module responds to reads of the following addresses:

388h-38Bh, 2x0h, 2x1h, 2x2h, 2x3h, 2x8h and 2x9h

Note that if neither sound card or FM I/O mapping is enabled, then status read trapping is not possible.

Fast Path Write – If enabled, the Core Logic module captures certain writes to several I/O locations. This feature prevents two SMIs from being asserted for write operations that are known to take two accesses (the first access is an index and the second is data). This process is called Fast Path Write. Fast Path Write is enabled in via F3BAR0+Memory Offset 18h[11].

Fast Path Write captures the data and address bit 1 (A1) of the first access, but does not generate an SMI. A1 is stored in F3BAR0+Memory Offset 14h[15]. The second access causes an SMI, and the data and address are captured as in a normal trapped I/O. Revision 5.1 Core Logic Module

In Fast Path Write, the Core Logic module responds to writes to the following addresses: 388h, 38Ah, 38Bh, 2x0h, 2x2h, and 2x8h.

Table 6-38 on page 280 shows the bit formats of the second level SMI status reporting registers and the Fast Path Read/Write programming bits.

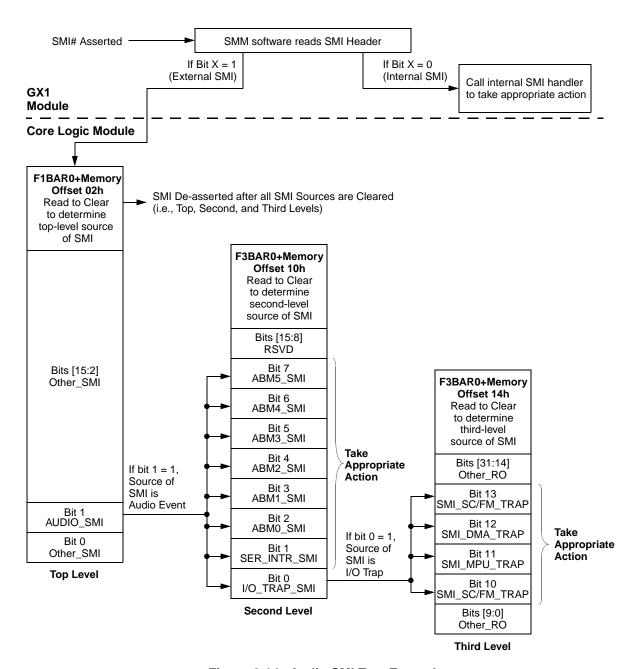


Figure 6-14. Audio SMI Tree Example

Core Logic Module Revision 5.1

6.2.12.4 IRQ Configuration Registers

The Core Logic module provides the ability to set and clear IRQs internally through software control. If the IRQs are configured for software control, they do not respond to external hardware. There are two registers provided for this feature:

- Internal IRQ Enable Register (F3BAR0+Memory Offset 1Ah)
- Internal IRQ Control Register (F3BAR0+Memory Offset 1Ch)

Internal IRQ Enable Register

The Internal IRQ Enable register configures the IRQs as internal (software) interrupts or external (hardware) interrupts. Any IRQ used as an internal software driven source must be configured as internal.

Internal IRQ Control Register

The Internal IRQ Control register allows individual software assertion/de-assertion of the IRQs that are enabled as internal. These bits are used as masks when attempting to write a particular IRQ bit. If the mask bit is set, it can then be asserted/de-asserted according to the value in the low-order 16 bits. Otherwise the assertion/de-assertion values of the particular IRQ can not be changed.

6.2.12.5 LPC Interface

The LPC interface of the Core Logic module is based on the Intel® Low Pin Count (LPC) Interface specification, revision 1.0. In addition to the requirement pins that are specified in the Intel LPC Interface specification, the Core Logic module also supports three optional pins: LDRQ#, SERIRQ, and LPCPD#.

The following subsections briefly describe some sections of the specification. However, for full details refer to the LPC specification directly.

The goals of the LPC interface are to:

- · Enable a system without an ISA bus.
- Reduce the cost of traditional ISA bus devices.
- · Use on a motherboard only.
- Perform the same cycle types as the ISA bus: memory, I/ O, DMA, and Bus Master.
- Increase the memory space from 16 MB to 4 GB to allow BIOS sizes much greater.
- Provide synchronous design. Much of the challenge of an ISA design is meeting the different, and in some cases conflicting, ISA timings. Make the timings synchronous to a reference well known to component designers, such as PCI.
- Support software transparency: do not require special drivers or configuration for this interface. The motherboard BIOS should be able to configure all devices at boot.

- · Support desktop and mobile implementations.
- Enable support of a variable number of wait states.
- Enable I/O memory cycle retries in SMM handler.
- Enable support of wakeup and other power state transitions.

Assumptions and functionality requirements of the LPC interface are:

- Only the following class of devices may be connected to the LPC interface:
 - SuperI/O (FDC, SP, PP, IR, KBC) I/O slave, DMA, bus master (for IR, PP).
 - Audio, including AC97 style design I/O slave, DMA, bus master.
 - Generic Memory, including BIOS Memory slave.
 - System Management Controller I/O slave, bus master.
- Interrupts are communicated with the serial interrupt (SERIRQ) protocol.
- The LPC interface does not need to support high-speed buses (such as CardBus, 1394, etc.) downstream, nor does it need to support low-latency buses such as USB.

Figure 6-15 shows a typical setup. In this setup, the LPC is connected through the Core Logic module to a PCI or host bus.

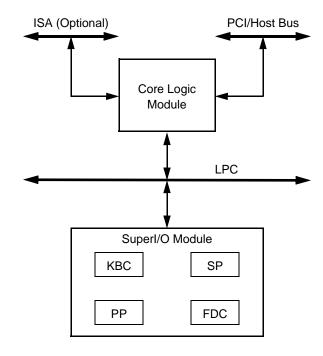


Figure 6-15. Typical Setup

Revision 5.1 Core Logic Module

6.2.12.6 LPC Interface Signal Definitions

The LPC specification lists seven required and six optional signals for supporting the LPC interface. Many of the signals are the same signals found on the PCI interface and do not require any new pins on the host. Required signals must be implemented by both hosts and peripherals. Optional signals may or may not be present on particular hosts or peripherals.

The Core Logic module incorporates all the required LPC interface signals and two of the optional signals:

- · Required LPC signals:
 - LAD[3:0] Multiplexed Command, Address and Data.
 - LFRAME# Frame: Indicates start of a new cycle, termination of broken cycle.
 - LRESET# Reset: This signal is not available. Use PCI Reset signal PCIRST# instead.
 - LCLK Clock: This signal is not available. Use PCI 33 MHz clock signal PCICLK instead.
- Core Logic module optional LPC signals:
 - LDRQ# Encoded DMA/Bus Master Request: Only needed by peripheral that need DMA or bus mastering. Peripherals may not share the LDRQ# signal.
 - SERIRQ Serialized IRQ: Only needed by peripherals that need interrupt support.
 - LPCPD# Power Down: Indicates that the peripheral should prepare for power to the LPC interface to be shut down. Optional for the host.

6.2.12.7 Cycle Types

Table 6-12 shows the various types of cycles that are supported by the Core Logic module.

Table 6-12. Cycle Types

Cycle Type	Supported Sizes (Bytes)
Memory Read	1
Memory Write	1
I/O Read	1
I/O Write	1
DMA Read	1 or 2
DMA Write	1 or 2
Bus Master Memory Read	1, 2, or 4
Bus Master Memory Write	1, 2, or 4

6.2.12.8 LPC Interface Support

The LPC interface supports all the features described in the LPC Bus Interface specification, revision 1.0, with the following exceptions:

- Only 8- or 16-bit DMA, depending on channel number. Does not support the optional larger transfer sizes.
- Only one external DRQ pin.



6.3 Register Descriptions

The Core Logic module is a multi-function module. Its register space can be broadly divided into three categories in which specific types of registers are located:

 Chipset Register Space (F0-F5) (Note that F4 is for Video Processor support, see Section 7.3.1 on page 345 for register descriptions): Comprised of six separate functions, each with its own register space, consisting of PCI header registers and configuration registers.

The PCI header is a 256-byte region used for configuring a PCI device or function. The first 64 bytes are the same for all PCI devices and are predefined by the PCI specification. These registers are used to configure the PCI for the device. The rest of the 256-byte region is used to configure the device or function itself.

- USB Controller Register Space (PCIUSB): Consists of the standard PCI header registers. The USB controller supports three ports and is OpenHCI compliant.
- ISA Legacy Register Space (I/O Ports): Contains all the legacy compatibility I/O ports that are internal, trapped, shadowed, or snooped.

The following subsections provide:

- A brief discussion on how to access the registers located in PCI Configuration Space.
- · Core Logic module register summaries.
- Bit formats for Core Logic module registers.

6.3.1 PCI Configuration Space and Access Methods

Configuration cycles are generated in the processor. All configuration registers in the Core Logic module are accessed through the PCI interface using the PCI Type One Configuration Mechanism. This mechanism uses two DWORD I/O locations at 0CF8h and 0CFCh. The first location (0CF8h) references the Configuration Address register. The second location (0CFCh) references the Configuration Data Register (CDR).

To access PCI configuration space, write the Configuration Address (0CF8h) Register with data that specifies the Core Logic module as the device on PCI being accessed, along with the configuration register offset. On the following cycle, a read or write to the Configuration Data Register (CDR) causes a PCI configuration cycle to the Core Logic module. Byte, WORD, or DWORD accesses are allowed to CDR at 0CFCh, 0CFDh, 0CFEh, or 0CFFh.

The Core Logic module has seven PCI configuration register sets, one for each function (F0-F5) and USB (PCIUSB). Base Address Registers (BARx) in F0-F5 and PCIUSB set the base addresses for additional I/O or memory mapped configuration registers for each function.

Table 6-13 shows the PCI Configuration Address Register (0CF8h) and how to access the PCI header registers.

Table 6-13. PCI Configuration Address Regist
--

31	30 24	23 16	15 11	10 8	7 2	1 0			
Configuration Space Mapping	Reserved	Bus Number	Device Number	Function	Index	DWORD 00			
1 (Enable)	000 000	0000 0000	xxxx x (Note)	XXX	xxxx xx	00 (Always)			
Function 0 (F0): Bridge Configuration, GPIO and LPC Configuration Register Space									
80)h	0000 0000	1001 0 or 1000 0	000	Inc	lex			
Function 1 (F1): S	SMI Status and ACI	PI Timer Configura	tion Register Spac	e					
80	Oh	0000 0000	1001 0 or 1000 0	001	Inc	lex			
Function 2 (F2): II	DE Controller Conf	iguration Register	Space						
80)h	0000 0000 1001 0 or 1000 0 010				Index			
Function 3 (F3): A	Audio Configuratio	n Register Space							
80)h	0000 0000	1001 0 or 1000 0	Index					
Function 4 (F4): V	/ideo Processor Co	onfiguration Regis	ter Space						
80	Oh	0000 0000	1001 0 or 1000 0	100	Inc	lex			
Function 5 (F5): X	(-Bus Expansion C	onfiguration Regis	ster Space						
80	Oh	0000 0000	1001 0 or 1000 0	101	Inc	lex			
PCIUSB: USB Co	ntroller Configurat	ion Register Space	9						
80	Oh	0000 0000	1001 1 or 1000 1	000	Inc	lex			
	ce number depends ines to be used as t		trap Override bit (F5						

6.3.2 Register Summary

The tables in this subsection summarize the registers of the Core Logic module. Included in the tables are the register's reset values and page references where the bit formats are found. Note: Function 4 (F4) is for Video Processor support (although accessed through the Core Logic PCI configuration registers). Refer to Section 7.3.1 "Register Summary" on page 345 for details.

Table 6-14. F0: PCI Header/Bridge Configuration Registers for GPIO and LPC Support Summary

F0 Index	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-29)
00h-01h	16	RO	Vendor Identification Register	100Bh	Page 206
02h-03h	16	RO	Device Identification Register	0500h	Page 206
04h-05h	16	R/W	PCI Command Register	000Fh	Page 206
06h-07h	16	R/W	PCI Status Register	0280h	Page 207
08h	8	RO	Device Revision ID Register	00h	Page 208
09h-0Bh	24	RO	PCI Class Code Register	060100h	Page 208
0Ch	8	R/W	PCI Cache Line Size Register	00h	Page 208
0Dh	8	R/W	PCI Latency Timer Register	00h	Page 208
0Eh	8	RO	PCI Header Type Register	80h	Page 208
0Fh	8	RO	PCI BIST Register	00h	Page 208
10h-13h	32	R/W	Base Address Register 0 (F0BAR0) — Sets the base address for the I/O mapped GPIO Runtime and Configuration Registers (summarized in Table 6-15).	0000001h	Page 208
14h-17h	32	R/W	Base Address Register 1 (F0BAR1) — Sets the base address for the I/O mapped LPC Configuration Registers (summarized in Table 6-16)	00000001h	Page 208
18h-2Bh			Reserved	00h	Page 208
2Ch-2Dh	16	RO	Subsystem Vendor ID	100Bh	Page 208
2Eh-2Fh	16	RO	Subsystem ID	0500h	Page 208
30h-3Fh			Reserved	00h	Page 208
40h	8	R/W	PCI Function Control Register 1	39h	Page 209
41h	8	R/W	PCI Function Control Register 2	00h	Page 209
42h			Reserved	00h	Page 210
43h	8	R/W	PIT Delayed Transactions Register	02h	Page 210
44h	8	R/W	Reset Control Register	01h	Page 210
45h			Reserved	00h	Page 211
46h	8	R/W	PCI Functions Enable Register	FEh	Page 211
47h	8	R/W	Miscellaneous Enable Register	00h	Page 211
48h-4Bh			Reserved	00h	Page 211
4Ch-4Fh	32	R/W	Top of System Memory	FFFFFFFh	Page 212
50h	8	R/W	PIT Control/ISA CLK Divider	7Bh	Page 212
51h	8	R/W	ISA I/O Recovery Control Register	40h	Page 212
52h	8	R/W	ROM/AT Logic Control Register	98h	Page 213
53h	8	R/W	Alternate CPU Support Register	00h	Page 213
54h-59h			Reserved	00h	Page 214
5Ah	8	R/W	Decode Control Register 1	01h	Page 214
5Bh	8	R/W	Decode Control Register 2	20h	Page 214
5Ch	8	R/W	PCI Interrupt Steering Register 1	00h	Page 215
5Dh	8	R/W	PCI Interrupt Steering Register 2	00h	Page 215
5Eh-5Fh			Reserved	00h	Page 215
60h-63h	32	R/W	ACPI Control Register	00000000h	Page 216
64h-6Bh			Reserved	00h	Page 216

F0 Index	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-29)
6Ch-6Fh	32	R/W	ROM Mask Register	0000FFF0h	Page 216
70h-71h	16	R/W	IOCS1# Base Address Register	0000h	Page 217
72h	8	R/W	IOCS1# Control Register	00h	Page 217
73h	8		Reserved	00h	Page 217
74h-75h	16	R/W	IOCS0 Base Address Register	0000h	Page 217
76h	8	R/W	IOCS0 Control Register	00h	Page 217
77h			Reserved	00h	Page 217
78h-7Bh	32	R/W	DOCCS Base Address Register	00000000h	Page 218
7Ch-7Fh	32	R/W	DOCCS Control Register	00000000h	Page 218
80h	8	R/W	Power Management Enable Register 1	00h	Page 218
81h	8	R/W	Power Management Enable Register 2	00h	Page 219
82h	8	R/W	Power Management Enable Register 3	00h	Page 221
83h	8	R/W	Power Management Enable Register 4	00h	Page 222
84h	8	RO	Second Level PME/SMI Status Mirror Register 1	00h	Page 223
85h	8	RO	Second Level PME/SMI Status Mirror Register 2	00h	Page 224
86h	8	RO	Second Level PME/SMI Status Mirror Register 3	00h	Page 225
87h	8	RO	Second Level PME/SMI Status Mirror Register 4	00h	Page 226
88h	8	R/W	General Purpose Timer 1 Count Register	00h	Page 226
89h	8	R/W	General Purpose Timer 1 Control Register	00h	Page 227
8Ah	8	R/W	General Purpose Timer 2 Count Register	00h	Page 228
8Bh	8	R/W	General Purpose Timer 2 Control Register	00h	Page 228
8Ch	8	R/W	IRQ Speedup Timer Count Register	00h	Page 228
8Dh	8	R/W	Video Speedup Timer Count Register	00h	Page 228
8Eh	8	R/W	VGA Timer Count Register	00h	Page 229
8Fh-92h			Reserved	00h	Page 229
93h	8	R/W	Miscellaneous Device Control Register	00h	Page 229
94h-95h	16	R/W	Suspend Modulation Register	0000h	Page 229
96h	8	R/W	Suspend Configuration Register	00h	Page 230
97h			Reserved	00h	Page 230
98h-99h	16	R/W	Hard Disk Idle Timer Count Register — Primary Channel	0000h	Page 230
9Ah-9Bh	16	R/W	Floppy Disk Idle Timer Count Register	0000h	Page 230
9Ch-9Dh	16	R/W	Parallel / Serial Idle Timer Count Register	0000h	Page 230
9Eh-9Fh	16	R/W	Keyboard / Mouse Idle Timer Count Register	0000h	Page 231
A0h-A1h	16	R/W	User Defined Device 1 Idle Timer Count Register	0000h	Page 231
A2h-A3h	16	R/W	User Defined Device 2 Idle Timer Count Register	0000h	Page 231
A4h-A5h	16	R/W	User Defined Device 3 Idle Timer Count Register	0000h	Page 231
A6h-A7h	16	R/W	Video Idle Timer Count Register	0000h	Page 231
A8h-A9h	16	R/W	Video Overflow Count Register	0000h	Page 231
AAh-ABh			Reserved	00h	Page 231
ACh-ADh	16	R/W	Hard Disk Idle Timer Count Register — Secondary Channel	0000h	Page 232
AEh	8	WO	CPU Suspend Command Register	00h	Page 232
AFh	8	WO	Suspend Notebook Command Register	00h	Page 232
B0h-B3h			Reserved	00h	Page 232
B4h	8	RO	Floppy Port 3F2h Shadow Register	xxh	Page 232
B5h	8	RO	Floppy Port 3F7h Shadow Register	xxh	Page 232
B6h	8	RO	Floppy Port 1F2h Shadow Register	xxh	Page 232
B7h	8	RO	Floppy Port 1F7h Shadow Register	xxh	Page 232
					. ~50 _0_



F0 Index	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-29)
B8h	8	RO	DMA Shadow Register	xxh	Page 233
B9h	8	RO	PIC Shadow Register	xxh	Page 233
BAh	8	RO	PIT Shadow Register	xxh	Page 233
BBh	8	RO	RTC Index Shadow Register	xxh	Page 234
BCh	8	R/W	Clock Stop Control Register	00h	Page 234
BDh-BFh			Reserved	00h	Page 234
C0h-C3h	32	R/W	User Defined Device 1 Base Address Register	00000000h	Page 234
C4h-C7h	32	R/W	User Defined Device 2 Base Address Register	00000000h	Page 234
C8h-CBh	32	R/W	User Defined Device 3 Base Address Register	00000000h	Page 234
CCh	8	R/W	User Defined Device 1 Control Register	00h	Page 235
CDh	8	R/W	User Defined Device 2 Control Register	00h	Page 235
CEh	8	R/W	User Defined Device 3 Control Register	00h	Page 235
CFh			Reserved	00h	Page 235
D0h	8	WO	Software SMI Register	00h	Page 235
D1h-EBh	16		Reserved	00h	Page 235
ECh	8	R/W	Timer Test Register	00h	Page 236
EDh-F3h			Reserved	00h	Page 236
F4h	8	RC	Second Level PME/SMI Status Register 1	00h	Page 236
F5h	8	RC	Second Level PME/SMI Status Register 2	00h	Page 236
F6h	8	RC	Second Level PME/SMI Status Register 3	00h	Page 237
F7h	8	RC	Second Level PME/SMI Status Register 4	00h	Page 238
F8h-FFh			Reserved	00h	Page 239



Table 6-15. F0BAR0: GPIO Support Registers Summary

F0BAR0+ I/O Offset	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-30)
00h-03h	32	R/W	GPDO0 — GPIO Data Out 0 Register	FFFFFFFh	Page 240
04h-07h	32	RO	GPDI0 — GPIO Data In 0 Register	FFFFFFFh	Page 240
08h-0Bh	32	R/W	GPIEN0 — GPIO Interrupt Enable 0 Register	00000000h	Page 240
0Ch-0Fh	32	R/W1C	GPST0 — GPIO Status 0 Register	00000000h	Page 240
10h-13h	32	R/W	GPDO1 — GPIO Data Out 1 Register	FFFFFFFh	Page 241
14h-17h	32	RO	GPDI1 — GPIO Data In 1 Register	FFFFFFFh	Page 241
18h-1Bh	32	R/W	GPIEN1 — GPIO Interrupt Enable 1 Register	00000000h	Page 241
1Ch-1Fh	32	R/W1C	GPST1 — GPIO Status 1 Register	00000000h	Page 241
20h-23h	32	R/W	GPIO Signal Configuration Select Register	00000000h	Page 241
24h-27h	32	R/W	GPIO Signal Configuration Access Register	00000044h	Page 242
28h-2Bh	32	R/W	GPIO Reset Control Register	00000000h	Page 243

Table 6-16. F0BAR1: LPC Support Registers Summary

F0BAR1+ I/O Offset	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-31)
00h-03h	32	R/W	SERIRQ_SRC — Serial IRQ Source Register	00000000h	Page 244
04h-07h	32	R/W	SERIRQ_LVL — Serial IRQ Level Control Register	00000000h	Page 245
08h-0Bh	32	R/W	SERIRQ_CNT — Serial IRQ Control Register	00000000h	Page 247
0Ch-0Fh	32	R/W	DRQ_SRC — DRQ Source Register	00000000h	Page 247
10h-13h	32	R/W	LAD_EN — LPC Address Enable Register	00000000h	Page 248
14h-17h	32	R/W	LAD_D0 — LPC Address Decode 0 Register	00080020h	Page 249
18h-1Bh	32	R/W	LAD_D1 — LPC Address Decode 1 Register	00000000h	Page 250
1Ch-1Fh	32	R/W	LPC_ERR_SMI — LPC Error SMI Register	00000080h	Page 250
20h-23h	32	RO	LPC_ERR_ADD — LPC Error Address Register	00000000h	Page 251



Table 6-17. F1: PCI Header Registers for SMI Status and ACPI Support Summary

F1 Index	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-32)
00h-01h	16	RO	Vendor Identification Register	100Bh	Page 252
02h-03h	16	RO	Device Identification Register	0501h	Page 252
04h-05h	16	R/W	PCI Command Register	0000h	Page 252
06h-07h	16	RO	PCI Status Register	0280h	Page 252
08h	8	RO	Device Revision ID Register	00h	Page 252
09h-0Bh	24	RO	PCI Class Code Register	068000h	Page 252
0Ch	8	RO	PCI Cache Line Size Register	00h	Page 252
0Dh	8	RO	PCI Latency Timer Register	00h	Page 252
0Eh	8	RO	PCI Header Type Register	00h	Page 252
0Fh	8	RO	PCI BIST Register	00h	Page 252
10h-13h	32	R/W	Base Address Register 0 (F1BAR0) — Sets the base address for the I/O mapped SMI Status Registers (summarized in Table 6-18).	0000001h	Page 252
14h-2Bh			Reserved	00h	Page 252
2Ch-2Dh	16	RO	Subsystem Vendor ID	100Bh	Page 252
2Eh-2Fh	16	RO	Subsystem ID	0501h	Page 252
30h-3Fh			Reserved	00h	Page 252
40h-43h	32	R/W	Base Address Register 1 (F1BAR1) — Sets the base address for the I/O mapped ACPI Support Registers (summarized in Table 6-19)	0000001h	Page 252
44h-FFh			Reserved	00h	Page 252

Table 6-18. F1BAR0: SMI Status Registers Summary

F1BAR0+ I/O Offset	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-33)
00h-01h	16	RO	Top Level PME/SMI Status Mirror Register	0000h	Page 253
02h-03h	16	RO/RC	Top Level PME/SMI Status Register	0000h	Page 254
04h-05h	16	RO	Second Level General Traps & Timers PME/SMI Status Mirror Register	0000h	Page 256
06h-07h	16	RC	Second Level General Traps & Timers PME/SMI Status Register	0000h	Page 257
08h-09h	16	Read to Enable	SMI Speedup Disable Register	0000h	Page 258
0Ah-1Bh			Reserved	00h	Page 258
1Ch-1Fh	32	RO	ACPI Timer Register	xxxxxxxxh	Page 258
20h-21h	16	RO	Second Level ACPI PME/SMI Status Mirror Register	0000h	Page 258
22h-23h	16	RC	Second Level ACPI PME/SMI Status Register	0000h	Page 259
24h-27h	32	R/W	External SMI Register	00000000h	Page 259
28h-4Fh			Not Used	00h	Page 262
50h-FFh			The I/O mapped registers located here (F1BAR0+I/O Offset 50h-FF Index 50h-FFh. The preferred method is to program these registers	,	



Table 6-19. F1BAR1: ACPI Support Registers Summary

F1BAR1+ I/O Offset	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-34)
00h-03h	32	R/W	P_CNT — Processor Control Register	00000000h	Page 263
04h	8	RO	Reserved, do not read	00h	Page 263
05h	8	RO	P_LVL3 — Enter C3 Power State Register	xxh	Page 263
06h	8	R/W	SMI_CMD — OS/BIOS Requests Register	00h	Page 263
07h	8	R/W	ACPI_FUN_CNT — ACPI Function Control Register	00h	Page 263
08h-09h	16	R/W	PM1A_STS — PM1A Status Register	0000h	Page 264
0Ah-0Bh	16	R/W	PM1A_EN — PM1A Enable Register	0000h	Page 265
0Ch-0Dh	16	R/W	PM1A_CNT — PM1A Control Register	0000h	Page 265
0Eh	8	R/W	ACPI_BIOS_STS Register	00h	Page 266
0Fh	8	R/W	ACPI_BIOS_EN Register	00h	Page 267
10h-11h	16	R/W	GPE0_STS — General Purpose Event 0 Status Register	xxxxh	Page 267
12h-13h	16	R/W	GPE0_EN — General Purpose Event 0 Enable Register	0000h	Page 269
14h	8	R/W	GPWIO Control Register 1	00h	Page 270
15h	8	R/W	GPWIO Control Register 2	00h	Page 270
16h	8	R/W	GPWIO Data Register	00h	Page 271
17h			Reserved	00h	Page 271
18h-1Bh	32	R/W	ACPI SCI_ROUTING Register	00000F00h	Page 271
1Ch-1Fh	32	RO	PM_TMR — PM Timer Register	xxxxxxxxh	Page 272
20h	8	R/W	PM2_CNT — PM2 Control Register	00h	Page 272
21h-FFh			Not Used	00h	Page 272



Table 6-20. F2: PCI Header Registers for IDE Controller Support Summary

F2 Index	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-35)
00h-01h	16	RO	Vendor Identification Register	100Bh	Page 273
02h-03h	16	RO	Device Identification Register	0502h	Page 273
04h-05h	16	R/W	PCI Command Register	0000h	Page 273
06h-07h	16	RO	PCI Status Register	0280h	Page 273
08h	8	RO	Device Revision ID Register	01h	Page 273
09h-0Bh	24	RO	PCI Class Code Register	010180h	Page 273
0Ch	8	RO	PCI Cache Line Size Register	00h	Page 273
0Dh	8	RO	PCI Latency Timer Register	00h	Page 273
0Eh	8	RO	PCI Header Type Register	00h	Page 273
0Fh	8	RO	PCI BIST Register	00h	Page 273
10h-13h	32	RO	Base Address Register 0 (F2BAR0) — Reserved for possible future use by the Core Logic module.	00000000h	Page 273
14h-17h	32	RO	Base Address Register 1 (F2BAR1) — Reserved for possible future use by the Core Logic module.	00000000h	Page 273
18h-1Bh	32	RO	Base Address Register 2 (F2BAR2) — Reserved for possible future use by the Core Logic module.	00000000h	Page 273
1Ch-1Fh	32	RO	Base Address Register 3 (F2BAR3) — Reserved for possible future use by the Core Logic module.	00000000h	Page 273
20h-23h	32	R/W	Base Address Register 4 (F2BAR4) — Sets the base address for the I/O mapped Bus Master IDE Registers (summarized in Table 6-21)	0000001h	Page 273
24h-2Bh			Reserved	00h	Page 273
2Ch-2Dh	16	RO	Subsystem Vendor ID	100Bh	Page 273
2Eh-2Fh	16	RO	Subsystem ID	0502h	Page 273
30h-3Fh			Reserved	00h	Page 274
40h-43h	32	R/W	Channel 0 Drive 0 PIO Register	00009172h	Page 274
44h-47h	32	R/W	Channel 0 Drive 0 DMA Control Register	00077771h	Page 275
48h-4Bh	32	R/W	Channel 0 Drive 1 PIO Register	00009172h	Page 275
4Ch-4Fh	32	R/W	Channel 0 Drive 1 DMA Control Register	00077771h	Page 275
50h-53h	32	R/W	Channel 1 Drive 0 PIO Register	00009172h	Page 276
54h-57h	32	R/W	Channel 1 Drive 0 DMA Control Register	00077771h	Page 276
58h-5Bh	32	R/W	Channel 1 Drive 1 PIO Register	00009172h	Page 276
5Ch-5Fh	32	R/W	Channel 1 Drive 1 DMA Control Register	00077771h	Page 276
60h-FFh			Reserved	00h	Page 276



Table 6-21. F2BAR4: IDE Controller Support Registers Summary

F2BAR4+ I/O Offset	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-36)
00h	8	R/W	IDE Bus Master 0 Command Register — Primary	00h	Page 277
01h			Not Used		Page 277
02h	8	R/W	IDE Bus Master 0 Status Register — Primary	00h	Page 277
03h			Not Used		Page 277
04h-07h	32	R/W	IDE Bus Master 0 PRD Table Address — Primary	00000000h	Page 277
08h	8	R/W	IDE Bus Master 1 Command Register — Secondary	00h	Page 278
09h			Not Used		Page 278
0Ah	8	R/W	IDE Bus Master 1 Status Register — Secondary	00h	Page 278
0Bh			Not Used		Page 278
0Ch-0Fh	32	R/W	IDE Bus Master 1 PRD Table Address — Secondary	00000000h	Page 278

Table 6-22. F3: PCI Header Registers for Audio Support Summary

F3 Index	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-37)
00h-01h	16	RO	Vendor Identification Register	100Bh	Page 279
02h-03h	16	RO	Device Identification Register	0503h	Page 279
04h-05h	16	R/W	PCI Command Register	0000h	Page 279
06h-07h	16	RO	PCI Status Register	0280h	Page 279
08h	8	RO	Device Revision ID Register	00h	Page 279
09h-0Bh	24	RO	PCI Class Code Register	040100h	Page 279
0Ch	8	RO	PCI Cache Line Size Register	00h	Page 279
0Dh	8	RO	PCI Latency Timer Register	00h	Page 279
0Eh	8	RO	PCI Header Type Register	00h	Page 279
0Fh	8	RO	PCI BIST Register	00h	Page 279
10h-13h	32	R/W	Base Address Register 0 (F3BAR0) — Sets the base address for the memory mapped VSA audio interface control register block (summarized in Table 6-23).	00000000h	Page 279
14h-2Bh			Reserved	00h	Page 279
2Ch-2Dh	16	RO	Subsystem Vendor ID	100Bh	Page 279
2Eh-2Fh	16	RO	Subsystem ID	0503h	Page 279
30h-FFh			Reserved	00h	Page 279



Table 6-23. F3BAR0: Audio Support Registers Summary

F3BAR0+ Memory Offset	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-38)
00h-03h	32	R/W	Codec GPIO Status Register	00000000h	Page 280
04h-07h	32	R/W	Codec GPIO Control Register	00000000h	Page 280
08h-0Bh	32	R/W	Codec Status Register	00000000h	Page 280
0Ch-0Fh	32	R/W	Codec Command Register	00000000h	Page 281
10h-11h	16	RC	Second Level Audio SMI Status Register	0000h	Page 281
12h-13h	16	RO	Second Level Audio SMI Status Mirror Register	0000h	Page 282
14h-17h	32	RO	I/O Trap SMI and Fast Write Status Register	0000000h	Page 283
18h-19h	16	R/W	I/O Trap SMI Enable Register	0000h	Page 284
1Ah-1Bh	16	R/W	Internal IRQ Enable Register	0000h	Page 285
1Ch-1Fh	32	R/W	Internal IRQ Control Register	00000000h	Page 286
20h	8	R/W	Audio Bus Master 0 Command Register	00h	Page 288
21h	8	RC	Audio Bus Master 0 SMI Status Register	00h	Page 288
22h-23h			Not Used		Page 288
24h-27h	32	R/W	Audio Bus Master 0 PRD Table Address	00000000h	Page 288
28h	8	R/W	Audio Bus Master 1 Command Register	00h	Page 289
29h	8	RC	Audio Bus Master 1 SMI Status Register	00h	Page 289
2Ah-2Bh			Not Used		Page 289
2Ch-2Fh	32	R/W	Audio Bus Master 1 PRD Table Address	00000000h	Page 289
30h	8	R/W	Audio Bus Master 2 Command Register	00h	Page 290
31h	8	RC	Audio Bus Master 2 SMI Status Register	00h	Page 290
32h-33h			Not Used	00h	Page 290
34h-37h	32	R/W	Audio Bus Master 2 PRD Table Address	00000000h	Page 290
38h	8	R/W	Audio Bus Master 3 Command Register	00h	Page 291
39h	8	RC	Audio Bus Master 3 SMI Status Register	00h	Page 291
3Ah-3Bh			Not Used		Page 291
3Ch-3Fh	32	R/W	Audio Bus Master 3 PRD Table Address	00000000h	Page 291
40h	8	R/W	Audio Bus Master 4 Command Register	00h	Page 292
41h	8	RC	Audio Bus Master 4 SMI Status Register	00h	Page 292
42h-43h			Not Used		Page 292
44h-47h	32	R/W	Audio Bus Master 4 PRD Table Address	00000000h	Page 292
48h	8	R/W	Audio Bus Master 5 Command Register	00h	Page 293
49h	8	RC	Audio Bus Master 5 SMI Status Register	00h	Page 293
4Ah-4Bh			Not Used		Page 293
4Ch-4Fh	32	R/W	Audio Bus Master 5 PRD Table Address	00000000h	Page 293



Table 6-24. F5: PCI Header Registers for X-Bus Expansion Support Summary

F5 Index	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-39)
00h-01h	16	RO	Vendor Identification Register	100Bh	Page 294
02h-03h	16	RO	Device Identification Register	0505h	Page 294
04h-05h	16	R/W	PCI Command Register	0000h	Page 294
06h-07h	16	RO	PCI Status Register	0280h	Page 294
08h	8	RO	Device Revision ID Register	00h	Page 294
09h-0Bh	24	RO	PCI Class Code Register	068000h	Page 294
0Ch	8	RO	PCI Cache Line Size Register	00h	Page 294
0Dh	8	RO	PCI Latency Timer Register	00h	Page 294
0Eh	8	RO	PCI Header Type Register	00h	Page 294
0Fh	8	RO	PCI BIST Register	00h	Page 294
10h-13h	32	R/W	Base Address Register 0 (F5BAR0) — Sets the base address for the X-Bus Expansion support registers (summarized in Table 6-25.)	00000000h	Page 294
14h-17h	32	R/W	Base Address Register 1 (F5BAR1) — Reserved for possible future use by the Core Logic module.	00000000h	Page 294
18h-1Bh	32	R/W	Base Address Register 2 (F5BAR2) — Reserved for possible future use by the Core Logic module.	00000000h	Page 294
1Ch-1Fh	32	R/W	Base Address Register 3 (F5BAR3) — Reserved for possible future use by the Core Logic module.	00000000h	Page 295
20h-23h	32	R/W	Base Address Register 4 (F5BAR4) — Reserved for possible future use by the Core Logic module.	00000000h	Page 295
24h-27h	32	R/W	Base Address Register 5 (F5BAR5) — Reserved for possible future use by the Core Logic module.	00000000h	Page 295
28h-2Bh			Reserved	00h	Page 295
2Ch-2Dh	16	RO	Subsystem Vendor ID	100Bh	Page 295
2Eh-2Fh	16	RO	Subsystem ID	0505h	Page 295
30h-3Fh			Reserved	00h	Page 295
40h-43h	32	R/W	F5BAR0 Base Address Register Mask	FFFFFC1h	Page 295
44h-47h	32	R/W	F5BAR1 Base Address Register Mask	00000000h	Page 296
48h-4Bh	32	R/W	F5BAR2 Base Address Register Mask	00000000h	Page 296
4Ch-4Fh	32	R/W	F5BAR3 Base Address Register Mask	00000000h	Page 296
50h-53h	32	R/W	F5BAR4 Base Address Register Mask	00000000h	Page 296
54h-57h	32	R/W	F5BAR5 Base Address Register Mask	00000000h	Page 296
58h	8	R/W	F5BARx Initialized Register	00h	Page 296
59h-FFh			Reserved	xxh	Page 296
60h-63h	32	R/W	Scratchpad for Chip Number	00000000h	Page 296
64h-67h	32	R/W	Scratchpad for Configuration Block Address	00000000h	Page 297
68h-FFh			Reserved	00h	Page 297

Table 6-25. F5BAR0: I/O Control Support Registers Summary

F5BAR0+ I/O Offset	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-40)
00h-03h	32	R/W	I/O Control Register 1	010C0007h	Page 298
04h-07h	32	R/W	I/O Control Register 2	00000002h	Page 299
08h-0Bh	32	R/W	I/O Control Register 3	00009000h	Page 299



Table 6-26. PCIUSB: USB PCI Configuration Register Summary

PCIUSB Index	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-41)
00h-01h	16	RO	Vendor Identification	0E11h	Page 300
02h-03h	16	RO	Device Identification	A0F8h	Page 300
04h-05h	16	R/W	Command Register	00h	Page 300
06h-07h	16	R/W	Status Register	0280h	Page 301
08h	8	RO	Device Revision ID	08h	Page 301
09h-0Bh	24	RO	Class Code	0C0310h	Page 301
0Ch	8	R/W	Cache Line Size	00h	Page 301
0Dh	8	R/W	Latency Timer	00h	Page 301
0Eh	8	RO	Header Type	00h	Page 301
0Fh	8	RO	BIST Register	00h	Page 301
10h-13h	32	R/W	Base Address 0	00000000h	Page 301
14h-2Bh			Reserved	00h	Page 302
2Ch-2Dh	16	RO	Subsystem Vendor ID	0E11h	Page 302
2Eh-2Fh	16	RO	Subsystem ID	A0F8h	Page 302
30h-3Bh			Reserved	00h	Page 302
3Ch	8	R/W	Interrupt Line Register	00h	Page 302
3Dh	8	R/W	Interrupt Pin Register	01h	Page 302
3Eh	8	RO	Min. Grant Register	00h	Page 302
3Fh	8	RO	Max. Latency Register	50h	Page 302
40h-43h	32	R/W	ASIC Test Mode Enable Register	000F0000h	Page 302
44h	8	R/W	ASIC Operational Mode Enable	00h	Page 302
45h-FFh			Reserved	00h	Page 302



Table 6-27. USB_BAR: USB Controller Registers Summary

USB_BAR0 +Memory Offset	Width (Bits)	Туре	Name	Reset Value	Reference (Table 6-42)
00h-03h	32	R/W	HcRevision	00000110h	Page 303
04h-07h	32	R/W	HcControl	00000000h	Page 303
08h-0Bh	32	R/W	HcCommandStatus	00000000h	Page 303
0Ch-0Fh	32	R/W	HcInterruptStatus	00000000h	Page 303
10h-13h	32	R/W	HcInterruptEnable	00000000h	Page 304
14h-17h	32	R/W	HcInterruptDisable	00000000h	Page 304
18h-1Bh	32	R/W	HcHCCA	00000000h	Page 305
1Ch-1Fh	32	R/W	HcPeriodCurrentED	00000000h	Page 305
20h-23h	32	R/W	HcControlHeadED	00000000h	Page 305
24h-27h	32	R/W	HcControlCurrentED	00000000h	Page 305
28h-2Bh	32	R/W	HcBulkHeadED	00000000h	Page 305
2Ch-2Fh	32	R/W	HcBulkCurrentED	00000000h	Page 305
30h-33h	32	R/W	HcDoneHead	00000000h	Page 305
34h-37h	32	R/W	HcFmInterval	00002EDFh	Page 306
38h-3Bh	32	RO	HcFrameRemaining	00000000h	Page 306
3Ch-3Fh	32	RO	HcFmNumber	00000000h	Page 306
40h-43h	32	R/W	HcPeriodicStart	00000000h	Page 306
44h-47h	32	R/W	HcLSThreshold	00000628h	Page 306
48h-4Bh	32	R/W	HcRhDescriptorA	01000003h	Page 306
4Ch-4Fh	32	R/W	HcRhDescriptorB	00000000h	Page 307
50h-53h	32	R/W	HcRhStatus	00000000h	Page 307
54h-57h	32	R/W	HcRhPortStatus[1]	00000000h	Page 308
58h-5Bh	32	R/W	HcRhPortStatus[2]	00000000h	Page 309
5Ch-5Fh	32	R/W	HcRhPortStatus[3]	00000000h	Page 310
60h-9Fh			Reserved	xxxxxxxxh	Page 311
100h-103h	32	R/W	HceControl	00000000h	Page 311
104h-107h	32	R/W	HceInput	000000xxh	Page 312
108h-10Dh	32	R/W	HceOutput	000000xxh	Page 312
10Ch-10Fh	32	R/W	HceStatus	00000000h	Page 312



Table 6-28. ISA Legacy I/O Register Summary

I/O Port	Туре	Name	Reference
DMA Channel	Control Regis	ters (Table 6-43)	
000h	R/W	DMA Channel 0 Address Register	Page 313
001h	R/W	DMA Channel 0 Transfer Count Register	Page 313
002h	R/W	DMA Channel 1 Address Register	Page 313
003h	R/W	DMA Channel 1 Transfer Count Register	Page 313
004h	R/W	DMA Channel 2 Address Register	Page 313
005h	R/W	DMA Channel 2 Transfer Count Register	Page 313
006h	R/W	DMA Channel 3 Address Register	Page 313
007h	R/W	DMA Channel 3 Transfer Count Register	Page 313
008h	Read	DMA Status Register, Channels 3:0	Page 313
	Write	DMA Command Register, Channels 3:0	Page 314
009h	WO	Software DMA Request Register, Channels 3:0	Page 314
00Ah	W	DMA Channel Mask Register, Channels 3:0	Page 314
00Bh	WO	DMA Channel Mode Register, Channels 3:0	Page 315
00Ch	WO	DMA Clear Byte Pointer Command, Channels 3:0	Page 315
00Dh	WO	DMA Master Clear Command, Channels 3:0	Page 315
00Eh	WO	DMA Clear Mask Register Command, Channels 3:0	Page 315
00Fh	WO	DMA Write Mask Register Command, Channels 3:0	Page 315
0C0h	R/W	DMA Channel 4 Address Register (Not used)	Page 315
0C2h	R/W	DMA Channel 4 Transfer Count Register (Not Used)	Page 315
0C4h	R/W	DMA Channel 5 Address Register	Page 315
0C6h	R/W	DMA Channel 5 Transfer Count Register	Page 315
0C8h	R/W	DMA Channel 6 Address Register	Page 315
0CAh	R/W	DMA Channel 6 Transfer Count Register	Page 315
0CCh	R/W	DMA Channel 7 Address Register	Page 315
0CEh	R/W	DMA Channel 7 Transfer Count Register	Page 315
0D0h	Read	DMA Status Register, Channels 7:4	Page 316
	Write	DMA Command Register, Channels 7:4	Page 316
0D2h	WO	Software DMA Request Register, Channels 7:4	Page 317
0D4h	W	DMA Channel Mask Register, Channels 7:4	Page 317
0D6h	WO	DMA Channel Mode Register, Channels 7:4	Page 317
0D8h	WO	DMA Clear Byte Pointer Command, Channels 7:4	Page 317
0DAh	WO	DMA Master Clear Command, Channels 7:4	Page 317
0DCh	WO	DMA Clear Mask Register Command, Channels 7:4	Page 317
0DEh	WO	DMA Write Mask Register Command, Channels 7:4	Page 318
DMA Page Reg	gisters (Table (6-44)	
081h	R/W	DMA Channel 2 Low Page Register	Page 318
082h	R/W	DMA Channel 3 Low Page Register	Page 318
083h	R/W	DMA Channel 1 Low Page Register	Page 318
087h	R/W	DMA Channel 0 Low Page Register	Page 318
089h	R/W	DMA Channel 6 Low Page Register	Page 318
08Ah	R/W	DMA Channel 7 Low Page Register	Page 318
08Bh	R/W	DMA Channel 5 Low Page Register	Page 318
08Fh	R/W	Sub-ISA Refresh Low Page Register	Page 318
481h	R/W	DMA Channel 2 High Page Register	Page 318
482h	R/W	DMA Channel 3 High Page Register	Page 318
483h	R/W	DMA Channel 1 High Page Register	Page 318



Table 6-28. ISA Legacy I/O Register Summary (Continued)

I/O Port	Туре	Name	Reference	
487h	R/W	DMA Channel 0 High Page Register	Page 318	
489h	R/W	DMA Channel 6 High Page Register	Page 318	
48Ah	R/W	DMA Channel 7 High Page Register	Page 318	
48Bh	R/W	DMA Channel 5 High Page Register	Page 318	
Programmable	Interval Time	r Registers (Table 6-45)		
040h	W	PIT Timer 0 Counter	Page 319	
	R	PIT Timer 0 Status	Page 319	
041h	W	PIT Timer 1 Counter (Refresh)	Page 319	
	R	PIT Timer 1 Status (Refresh)	Page 319	
042h	W	PIT Timer 2 Counter (Speaker)	Page 320	
	R	PIT Timer 2 Status (Speaker)	Page 320	
043h	R/W	PIT Mode Control Word Register	Page 320	
		Read Status Command		
		Counter Latch Command		
Programmable	Interrupt Con	troller Registers (Table 6-46)		
020h / 0A0h	WO	Master / Slave PCI ICW1	Page 321	
021h / 0A1h	WO	Master / Slave PIC ICW2	Page 321	
021h / 0A1h	WO	Master / Slave PIC ICW3	Page 321	
021h / 0A1h	WO	Master / Slave PIC ICW4	Page 321	
021h / 0A1h	R/W	Master / Slave PIC OCW1	Page 321	
020h / 0A0h	WO	Master / Slave PIC OCW2	Page 322	
020h / 0A0h	WO	Master / Slave PIC OCW3	Page 322	
020h / 0A0h	RO	Master / Slave PIC Interrupt Request and Service Registers for OCW3 Commands	Page 322	
Keyboard Con	troller Registe	ers (Table 6-47)		
060h	R/W	External Keyboard Controller Data Register	Page 324	
061h	R/W	Port B Control Register	Page 324	
062h	R/W	External Keyboard Controller Mailbox Register	Page 324	
064h	R/W	External Keyboard Controller Command Register	Page 324	
066h	R/W	External Keyboard Controller Mailbox Register	Page 324	
092h	R/W	Port A Control Register	Page 324	
Real-Time Clo	ck Registers (Table 6-48)		
070h	WO	RTC Address Register	Page 325	
071h	R/W	RTC Data Register	Page 325	
072h	WO	RTC Extended Address Register	Page 325	
073h	R/W	RTC Extended Data Register	Page 325	
Miscellaneous	Registers (Ta	ble 6-49)		
0F0h, 0F1h	WO	Coprocessor Error Register	Page 325	
170h-177h/ 376h-377h	R/W	Secondary IDE Registers	Page 325	
1F0-1F7h/ 3F6h-3F7h	R/W	Primary IDE Registers	Page 325	
4D0h	R/W	Interrupt Edge/Level Select Register 1	Page 325	
4D1h	R/W	Interrupt Edge/Level Select Register 2	Page 326	

6.4 Chipset Register Space

The Chipset Register Space of the Core Logic module is comprised of six separate functions (F0-F5), each with its own register space. Base Address Registers (BARs) in each PCI header register space set the base address for the configuration registers for each respective function. The configuration registers accessed through BARs are I/O or memory mapped. The PCI header registers in all functions are very similar.

- Function 0 (F0): PCI Header/Bridge Configuration Registers for GPIO, and LPC Support (see Section 6.4.1).
- Function 1 (F1): PCI Header Registers for SMI Status and ACPI Support (see Section 6.4.2 on page 252).
- Function 2 (F2): PCI Header/Channel 0 and 1 Configuration Registers for IDE Controller Support (see Section 6.4.3 on page 273).
- Function 3 (F3): PCI Header Registers for audio support (see Section 6.4.4 on page 279).
- Function 4 (F4): PCI Header Registers Video Processor Support (see Section 7.3 on page 345).
- 6) Function 5 (F5): PCI Header Registers for X-Bus Expansion Support (see Section 6.4.5 on page 294).

Function 5 contain six BARs in their standard PCI header locations (i.e., Index 10h, 14h, 18h, 1Ch, 20h, and 24h). In addition there are six mask registers that allow the six BARs to be fully programmable from 4 GB to 16 bytes for memory and from 4 GB to 4 bytes for I/O

General Remarks:

- Reserved bits that are defined as "must be set to 0 or 1" should be written with that value.
- Reserved bits that are not defined as "must be set to 0 or 1" should be written with a value that is read from them.
- "Read to Clear" registers that are wider than one byte should be read in one read operation. If they are read a byte at a time, status bits may be lost, or not cleared.

6.4.1 Bridge, GPIO, and LPC Registers - Function 0

The register space designated as Function 0 (F0) is used to configure Bridge features and functionality unique to the Core Logic module. In addition, it configures the PCI portion of support hardware for the GPIO and LPC support registers. The bit formats for the PCI Header and Bridge Configuration registers are given in Table 6-29.

Note: The registers at F0 Index 50h-FFh can also be accessed at F1BAR0+I/O Offset 50h-FFh. However, the preferred method is to program these registers through the F0 register space.

Located in the PCI Header registers of F0, are two Base Address Registers (F0BARx) used for pointing to the register spaces designated for GPIO and LPC configuration (described in Section 6.4.1.1 "GPIO Support Registers" on page 240 and Section 6.4.1.2 "LPC Support Registers" on page 244).

Table 6-29. F0: PCI Header/Bridge Configuration Registers for GPIO and LPC Support

Bit	Description			
Index 00h	-01h Vendor Identification Register (RO)	Reset Value: 100Bh		
Index 02h	-03h Device Identification Register (RO)	Reset Value: 0500h		
Index 04h-05h PCI Command Register (R/W)		Reset Value: 000Fh		
15:10	Reserved. Must be set to 0.			
9	Fast Back-to-Back Enable. This function is not supported when the Core Logic module is a master. It must always be abled (i.e., must be set to 0).			
8	SERR#. Allow SERR# assertion on detection of special errors.			
	0: Disable. (Default)			
	1: Enable.			
7	Wait Cycle Control (Read Only). This function is not supported in the Core Logic module. It is always disabled (always reads 0, hardwired).			
Parity Error. Allow the Core Logic module to check for parity errors on PCI cycles for which it is a target of PERR# when a parity error is detected.		h it is a target and to assert		
	0: Disable. (Default)			
	1: Enable.			
5	VGA Palette Snoop Enable. (Read Only) This function is not supported in the Core Logic module. It is always disabled (always reads 0, hardwired).			



Bit	Description		
4	Memory Write and Invalidate. Allow the Core Logic module to do memory write and invalidate cycles, if the PCI Cache Line register (F0 Index 0Ch) is set to 32 bytes (08h).		
	0: Disable. (Default)		
	1: Enable.		
3	Special Cycles. Allow the Core Logic module to respond to special cycles.		
· ·	0: Disable.		
	1: Enable. (Default)		
2	This bit must be enabled to allow an SMI to be generated from a CPU Shutdown cycle.		
2	Bus Master. Allow the Core Logic module bus mastering capabilities. 0: Disable.		
	1: Enable. (Default)		
	This bit must be set to 1.		
1	Memory Space. Allow the Core Logic module to respond to memory cycles from the PCI bus.		
	0: Disable.		
	1: Enable. (Default)		
0	I/O Space. Allow the Core Logic module to respond to I/O cycles from the PCI bus:		
	0: Disable.		
	1: Enable. (Default)		
	This bit must be set to 1 to access I/O offsets through F0BAR0 and F0BAR1 (see F0 Index 10h and 14h).		
Index 06	n-07h PCI Status Register (R/W) Reset Value: 0280h		
15	Detected Parity Error. This bit is set whenever a parity error is detected. Write 1 to clear.		
14	Signaled System Error. This bit is set whenever the Core Logic module asserts SERR# active. Write 1 to clear.		
13	Received Master Abort. This bit is set whenever a master abort cycle occurs. A master abort occurs when a PCI cycle is not claimed, except for special cycles.		
	Write 1 to clear.		
12	Received Target Abort. This bit is set whenever a target abort is received while the Core Logic module is the master for the PCI cycle.		
	Write 1 to clear.		
11	Signaled Target Abort. This bit is set whenever the Core Logic module signals a target abort. This occurs when an address parity error occurs for an address that hits in the active address decode space of the Core Logic module.		
	Write 1 to clear.		
10:9	DEVSEL# Timing. (Read Only) These bits are always 01, as the Core Logic module always responds to cycles for which it is an active target with medium DEVSEL# timing.		
	00: Fast		
	01: Medium		
	10: Slow		
	11: Reserved.		
8	Data Parity Detected. This bit is set when:		
	1) The Core Logic module asserts PERR# or observed PERR# asserted.		
	2) The Core Logic module is the master for the cycle in which the PERR# occurred, and PE is set (F0 Index 04h[6] = 1).		
	Write 1 to clear.		
7	Fast Back-to-Back Capable. (Read Only) Enables the Core Logic module, as a target, to accept fast back-to-back transactions.		
	0: Disable.		
	1: Enable.		
	This bit is always set to 1.		
6:0	Reserved. (Read Only) Must be set to 0 for future use.		



Bit	Description	
Index 08h	Device Revision ID Register (RO)	Reset Value: 00h
Index 09h	-0Bh PCI Class Code Register (RO)	Reset Value: 060100h
Index 0Ch	PCI Cache Line Size Register (R/W)	Reset Value: 00h
7:0	PCI Cache Line Size Register. This register sets the size of the PCI cache line, in increwrite and invalidate cycles, the PCI cache line size must be set to 32 bytes (08h) and the (F0 Index 04h[4]) must be set to 1.	
Index 0Dh	PCI Latency Timer Register (R/W)	Reset Value: 00h
7:4	Reserved. Must be set to 0.	
3:0	PCI Latency Timer Value. The PCI Latency Timer register prevents system lockup whe cycle that the Core Logic module masters.	n a slave does not respond to a
	If the value is set to 00h (default), the timer is disabled.	
	If the timer is written with any other value, bits [3:0] become the four most significant bits slave response.	in a timer that counts PCI clocks for
	The timer is reset on each valid data transfer. If the counter expires before the next asse Core Logic module stops the transaction with a master abort and asserts SERR#, if ena	•
Index 0Eh	PCI Header Type (RO)	Reset Value: 80h
7:0	PCI Header Type Register. This register defines the format of this header. This header information about this format, see the PCI Local Bus specification, revision 2.2.)	has a format of type 0. (For more
	Additionally, bit 7 of this register defines whether this PCI device is a multifunction device	e (bit $7 = 1$) or not (bit $7 = 0$).
Index 0Fh	PCI BIST Register (RO)	Reset Value: 00h
This regist	er indicates various information about the PCI Built-In Self-Test (BIST) mechanism.	
Note: T	his mechanism is not supported in the Core Logic module in the SC3200.	
7	BIST Capable. Indicates if the device can run a Built-In Self-Test (BIST).	
	0: The device has no BIST functionality.	
	1: The device can run a BIST.	
6	Start BIST. Setting this bit to 1 starts up a BIST on the device. The device resets this bit supported.)	when the BIST is completed. (Not
5:4	Reserved.	
3:0	BIST Completion Code. Upon completion of the BIST, the completion code is stored in these bits. A completion code of 0000 indicates that the BIST was successfully completed. Any other value indicates a BIST failure.	
Index 10h	-13h Base Address Register 0 - F0BAR0 (R/W)	Reset Value: 00000001h
	er allows access to I/O mapped GPIO runtime and configuration Registers. Bits [5:0] are red I/O address space. Refer to Table 6-30 on page 240 for the GPIO register bit formats are	
31:6	GPIO Base Address.	
5:0	Address Range. (Read Only)	
Index 14h	-17h Base Address Register 1 - F0BAR1 (R/W)	Reset Value: 00000001h
-	er allows access to I/O mapped LPC configuration registers. Bits [5:0] are read only (00000 pace. Refer to Table 6-31 on page 244 for the bit formats and reset values of the LPC regis	, , , , , , , , , , , , , , , , , , , ,
31:6	LPC Base Address.	
5:0	Address Range. (Read Only)	
Index 18h	-2Bh Reserved	Reset Value: 00h
Index 2Ch	-2Dh Subsystem Vendor ID (RO)	Reset Value: 100Bh
Index 2Eh	-2Fh Subsystem ID (RO)	Reset Value: 0500h
Index 30h	-3Fh Reserved	Reset Value: 00h



Bit	Description	
Index 40h	PCI Function Control Register 1 (R/W)	Reset Value: 39h
7:6	Reserved. Must be set to 0.	
5	Reserved. Must be set to 0.	
4	PCI Subtractive Decode.	
	0: Disable transfer of subtractive decode address to external PCI bus. External PCI bus is not	usable.
	1: Enable transfer of subtractive decode address to external PCI bus. Recommended setting.	
3	Reserved. Must be set to 1.	
2	Reserved. Must be set to 0.	
1	PERR# Signals SERR#. Assert SERR# when PERR# is asserted or detected as active by the PERR# assertion to be cascaded to NMI (SMI) generation in the system).	Core Logic module (allows
	0: Disable.	
	1: Enable.	
0	PCI Interrupt Acknowledge Cycle Response. The Core Logic module responds to PCI interru	upt acknowledge cycles.
	0: Disable.	
	1: Enable.	
Index 41h	PCI Function Control Register 2 (R/W)	Reset Value: 00h
7:6	Reserved. Must be set to 0.	
5	X-Bus Configuration Trap. If this bit is set to 1 and an access occurs to one of the configuration 5 (F5) register space, an SMI is generated. Writes are trapped; access to the register is denied. It to the register is allowed.	•
	0: Disable.	
	1: Enable.	
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[9]. Second level SMI status is reported at F1BAR0+I/O Offset 04h/06h[5].	
4	Video Configuration Trap. If this bit is set to 1 and an access occurs to one of the configuration (F4) register space, an SMI is generated. Writes are trapped; access to the register is denied. F to the register is allowed.	•
	0: Disable.	
	1: Enable.	
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[9]. Second level SMI status is reported at F1BAR0+I/O Offset 04h/06h[5].	
3	Audio Configuration Trap. If this bit is set to 1 and an access occurs to one of the configuration 3 (F3) register space, an SMI is generated. Writes are trapped; access to the register is denied. It to the register is allowed.	
	0: Disable.	
	1: Enable.	
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[9]. Second level SMI status is reported at F1BAR0+I/O Offset 04h/06h[5].	
2	IDE Configuration Trap. If this bit is set to 1 and an access occurs to one of the configuration r (F2) register space, an SMI is generated. Writes are trapped; access to the register is denied. F to the register is allowed.	_
	0: Disable.	
	1: Enable.	
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[9]. Second level SMI status is reported at F1BAR0+I/O Offset 04h/06h[5].	



Bit	Description		
1	Power Management Configuration Trap. If this bit is set to 1 and an access occurs to one of the configuration registers in PCI Function 1 (F1) register space, an SMI is generated. Writes are trapped; access to the register is denied. Reads are snooped; access to the register is allowed.		
	0: Disable.		
	1: Enable.		
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[9]. Second level SMI status is reported at F1BAR0+I/O Offset 04h/06h[5].		
0	Legacy Configuration Trap. If this bit is set to 1 and an access occurs to one of the configuration registers in PCI Functi 0 (F0), an SMI is generated. Reads and writes are snooped; access to the register is allowed.		
	0: Disable.		
	1: Enable.		
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[9]. Second level SMI status is reported at F1BAR0+I/O Offset 04h/06h[5].		
Index 42h	Reserved Reset Value: 00		
Index 43h	Delayed Transactions Register (R/W) Reset Value: 02l		
7:6	Reserved. Must be set to 0.		
5	Reserved. Must be set to 1.		
4	Enable PCI Delayed Transactions for Access to I/O Address 170h-177h (Secondary IDE Channel). PIO mode uses repeated I/O transactions that are faster when non-delayed transactions are used.		
	0: I/O addresses complete as fast as possible on PCI. (Default)		
	1: Accesses to Secondary IDE channel I/O addresses are delayed transactions on PCI.		
	For best performance of VIP, this bit should be set to 1 unless PIO mode 3 or 4 are used.		
3	Enable PCI Delayed Transactions for Access to I/O Address 1F0h-1F7h (Primary IDE Channel). PIO mode uses repeated I/O transactions that are faster when non-delayed transactions are used.		
	0: I/O addresses complete as fast as possible on PCI. (Default)		
	1: Accesses to Primary IDE channel I/O addresses are delayed transactions on PCI.		
	For best performance of VIP, this bit should be set to 1 unless PIO mode 3 or 4 are used.		
2	Enable PCI Delayed Transactions for AT Legacy PIC I/O Addresses. Some PIC status reads are long. Enabling delay transactions help reduce DMA latency for high bandwidth devices like VIP.		
	0: PIC I/O addresses complete as fast as possible on PCI. (Default)		
	1: Accesses to PIC I/O addresses are delayed transactions on PCI.		
	For best performance of VIP, this bit should be set to 1.		
1	Enable PCI Delayed Transactions for AT Legacy PIT I/O Addresses. Some x86 programs (certain benchmarks/diagnetics) assume a particular latency for PIT accesses; this bit allows that code to work.		
	0: PIT I/O addresses complete as fast as possible on PCI.		
	1: Accesses to PIT I/O addresses are delayed transactions on PCI. (Default)		
	For best performance (e.g., when running Microsoft Windows®), this bit should be set to 0.		
0	Reserved. Must be set to 0.		
Index 44h	Reset Control Register (R/W) Reset Value: 01		
7	AC97 Soft Reset. Active low reset for the AC97 codec interface.		
	0: AC97_RST# is driven high. (Default)		
	1: AC97_RST# is driven low.		
6:4	Reserved. Must be set to 0.		
3	IDE Controller Reset. Reset the IDE controller.		
	0: Disable.		
	1: Enable.		
	Write 0 to clear. This bit is level-sensitive and must be cleared after the reset is enabled.		



Bit	Description
2	IDE Reset. Reset IDE bus.
	0: Disable.
	1: Enable (drive IDE_RST# low).
	Write 0 to clear. This bit is level-sensitive and must be cleared after the reset is enabled.
	Note: When X-Bus Warm Start is enabled (bit 0 = 1) or during POR#, IDE_RST# is put into TRI-STATE mode. To properly reset the IDE bus, after POR# the boot code must cause IDE_RST# to activate.
1	PCI Reset. Reset PCI bus.
	0: Disable.
	1: Enable.
	When this bit is set to 1, the Core Logic module output signal PCIRST# is asserted and all devices on the PCI bus (including PCIUSB) are reset. No other function within the Core Logic module is affected by this bit.
	Write 0 to clear this bit. This bit is level-sensitive and must be cleared after the reset is enabled.
0	X-Bus Warm Start. Writing and reading this bit each have different meanings.
	When reading this bit, it indicates whether or not a warm start occurred since power-up:
	0: A warm start occurred.
	1: No warm start has occurred.
	When writing this bit, it can be used to trigger a system-wide reset:
	0: No effect.
	1: Execute system-wide reset (used only for clock configuration at power-up).

Index 45h	Reserved	Reset Value: 00h
Index 46h	PCI Functions Enable Register (R/W)	Reset Value: FEh
7:6	Reserved. Resets to 11.	
5	F5 (PCI Function 5). When asserted (set to 1), enables the register space designated as F5.	
	This bit must always be set to 1. (Default)	
4	F4 (PCI Function 4). When asserted (set to 1), enables the register space designated as F4.	
	This bit must always be set to 1. (Default)	
3	F3 (PCI Function 3). When asserted (set to 1), enables the register space designated as F3.	
	This bit must always be set to 1. (Default)	
2	F2 (PCI Function 2). When asserted (set to 1), enables the register space designated as F2.	
	This bit must always be set to 1. (Default)	
1	F1 (PCI Function 1). When asserted (set to 1), enables the register space designated as F1.	
	This bit must always be set to 1. (Default)	
0	Reserved. Must be set to 0.	
Index 47h	Miscellaneous Enable Register (R/W)	Reset Value: 00h
7:3	Reserved. Must be set to 0.	
2	F0BAR1 (PCI Function 0, Base Address Register 1). F0BAR1, pointer to I/O mapped LPC confi	guration registers.
	0: Disable.	
	1: Enable.	
1	F0BAR0 (PCI Function 0, Base Address Register 0). F0BAR0, pointer to I/O mapped GPIO con	figuration registers.
	0: Disable.	
	1: Enable.	
0	Reserved. Must be set to 0.	
Index 48h-	4Bh Reserved	Reset Value: 00h



Bit	Description	
Index 4Ch	-4Fh Top of System Memory (R	(/W) Reset Value: FFFFFFFh
31:0	Top of System Memory. Highest address in system used to detect cycles.	rmine active decode for external PCI mastered memory
	If an external PCI master requests a memory address below the value from the external PCI bus interface to the Fast-PCI interface for se	
	Note: The four least significant bits must be set to 1100.	
Index 50h	PIT Control/ISA CLK Divider	(R/W) Reset Value: 7Bh
7	PIT Software Reset.	
	0: Disable.	
	1: Enable.	
6	PIT Counter 1.	
	0: Forces Counter 1 output (OUT1) to zero.	
	1: Allows Counter 1 output (OUT1) to pass to the Port 061h[4].	
5	PIT Counter 1 Enable.	
	0: Sets GATE1 input low.	
	1: Sets GATE1 input high.	
4	PIT Counter 0.	
	0: Forces Counter 0 output (OUT0) to zero.	
	1: Allows Counter 0 output (OUT0) to pass to IRQ0.	
3	PIT Counter 0 Enable.	
	0: Sets GATE0 input low.	
	1: Sets GATE0 input high.	
2:0	ISA Clock Divisor. Determines the divisor of the PCI clock used approximately 8 MHz:	to make the ISA clock, which is typically programmed for
	000: Divide by 1 100: Divide by 5	
	001: Divide by 2 101: Divide by 6	
	010: Divide by 3 110: Divide by 7 011: Divide by 4 111: Divide by 8	
	If PCI clock = 25 MHz, use setting of 010 (divide by 3).	
	If PCI clock = 30 or 33 MHz, use a setting of 011 (divide by 4).	
Index 51h	ISA I/O Recovery Control Regis	ster (R/W) Reset Value: 40h
7:4	<u> </u>	
7.4	8-Bit I/O Recovery. These bits determine the number of ISA bus count is in addition to a preset one-clock delay built into the control.	•
	0000: 1 PCI clock	
	0001: 2 PCI clocks	
	:::	
	:::	
	:::	
	1111: 16 PCI clocks	
3:0	16-Bit I/O Recovery. These bits determine the number of ISA but count is in addition to a preset one-clock delay built into the control.	•
	0000: 1 PCI clock	
	0001: 2 PCI clocks	
	:::	
	:::	
	1111: 16 PCI clocks	



Table 6-29. F0: PCI Header/Bridge Configuration Registers for GPIO and LPC Support (Continued)

Bit	Description	
Index 52h	ROM/AT Logic Control Register (R/W)	Reset Value: 98h
7	Snoop Fast Keyboard Gate A20 and Fast Reset. Enables the snoop logic associated with key	board commands for A20
	Mask and Reset.	
	Disable snooping. The keyboard controller handles the commands. Finally snooping.	
C-F	1: Enable snooping.	
6:5 4	Reserved. Must be set to 0. Enable A20M# De-assertion on Warm Reset. Force A20M# high during a Warm Reset (guara	ntage that A20M# is do-
7	asserted regardless of the state of A20).	THE COUNTY TO UC
	0: Disable.	
	1: Enable.	
3	Enable Port 092h (Port A). Port 092h decode and the logical functions.	
	0: Disable.	
	1: Enable.	
2	Upper ROM Size. Selects upper ROM addressing size.	
	0: 256K (FFFC0000h-FFFFFFFh).	
	1: Use ROM Mask register (F0 Index 6Ch).	
	ROMCS# goes active for the above ranges whether strapped for ISA or LPC. (Refer to F0BAR1-ther strapping/programming details.)	+I/O Offset 10h[15] for fur-
	The selected range can then be either positively or subtractively decoded through F0 Index 5Bh	[5].
1	ROM Write Enable. When asserted, enables writes to ROM space, allowing Flash programming].
	If strapped for ISA and this bit is set to 1, writes to the configured ROM space asserts ROMCS#, the Flash device on the ISA bus. Otherwise, ROMCS# is inhibited for writes.	enabling the write cycle to
	If strapped for LPC and this bit is set to 1, the cycle runs on the LPC bus. Otherwise, the LPC bus writes.	is cycle is inhibited for
	Refer to F0BAR1+I/O Offset 10h[15] for further strapping/programming details.	
0	Lower ROM Size. Selects lower ROM addressing size in which ROMCS# goes active.	
	0: Lower ROM access are 000F0000h-000FFFFFh (64 KB). (Default)	
	1: Lower ROM accesses are 000E0000h-000FFFFFh (128 KB).	
	ROMCS# goes active for the above ranges whether strapped for ISA or LPC. (Refer to F0BAR1-ther strapping/programming details.)	+I/O Offset 10h[15] for fur-
	The selected range can then be either positively or subtractively decoded through F0 Index 5Bh	[5].
	Alternate CPU Support Register (R/W)	
ındex 53h	Alternate CFO Support Register (R/W)	Reset Value: 00h
7:6	Reserved. Must be set to 0.	Reset Value: 00h
		Reset Value: 00h
7:6	Reserved. Must be set to 0.	Reset Value: 00h
7:6	Reserved. Must be set to 0. Bidirectional SMI Enable.	Reset Value: 00h
7:6	Reserved. Must be set to 0. Bidirectional SMI Enable. 0: Disable.	Reset Value: 00h
7:6	Reserved. Must be set to 0. Bidirectional SMI Enable. 0: Disable. 1: Enable.	Reset Value: 00h
7:6 5 4:3 2	Reserved. Must be set to 0. Bidirectional SMI Enable. 0: Disable. 1: Enable. This bit must be set to 0. Reserved. Must be set to 0. Reserved. Must be set to 0.	Reset Value: 00h
4:3	Reserved. Must be set to 0. Bidirectional SMI Enable. 0: Disable. 1: Enable. This bit must be set to 0. Reserved. Must be set to 0. Reserved. Must be set to 0. IRQ13 Function Selection. Selects function of the internal IRQ13/FERR# signal.	Reset Value: 00h
7:6 5 4:3 2	Reserved. Must be set to 0. Bidirectional SMI Enable. 0: Disable. 1: Enable. This bit must be set to 0. Reserved. Must be set to 0. Reserved. Must be set to 0. IRQ13 Function Selection. Selects function of the internal IRQ13/FERR# signal. 0: FERR#.	Reset Value: 00h
7:6 5 4:3 2	Reserved. Must be set to 0. Bidirectional SMI Enable. 0: Disable. 1: Enable. This bit must be set to 0. Reserved. Must be set to 0. Reserved. Must be set to 0. IRQ13 Function Selection. Selects function of the internal IRQ13/FERR# signal. 0: FERR#. 1: IRQ13.	Reset Value: 00h
7:6 5 4:3 2 1	Reserved. Must be set to 0. Bidirectional SMI Enable. 0: Disable. 1: Enable. This bit must be set to 0. Reserved. Must be set to 0. Reserved. Must be set to 0. IRQ13 Function Selection. Selects function of the internal IRQ13/FERR# signal. 0: FERR#. 1: IRQ13. This bit must be set to 1.	Reset Value: 00h
7:6 5 4:3 2	Reserved. Must be set to 0. Bidirectional SMI Enable. 0: Disable. 1: Enable. This bit must be set to 0. Reserved. Must be set to 0. Reserved. Must be set to 0. IRQ13 Function Selection. Selects function of the internal IRQ13/FERR# signal. 0: FERR#. 1: IRQ13. This bit must be set to 1. Generate SMI on A20M# Toggle.	Reset Value: 00h
7:6 5 4:3 2 1	Reserved. Must be set to 0. Bidirectional SMI Enable. 0: Disable. 1: Enable. This bit must be set to 0. Reserved. Must be set to 0. Reserved. Must be set to 0. IRQ13 Function Selection. Selects function of the internal IRQ13/FERR# signal. 0: FERR#. 1: IRQ13. This bit must be set to 1. Generate SMI on A20M# Toggle. 0: Disable.	Reset Value: 00h
7:6 5 4:3 2 1	Reserved. Must be set to 0. Bidirectional SMI Enable. 0: Disable. 1: Enable. This bit must be set to 0. Reserved. Must be set to 0. Reserved. Must be set to 0. IRQ13 Function Selection. Selects function of the internal IRQ13/FERR# signal. 0: FERR#. 1: IRQ13. This bit must be set to 1. Generate SMI on A20M# Toggle.	Reset Value: 00h



Bit	Description	
Index 54l	h-59h Reserved	Reset Value: 00h
Index 5A	h Decode Control Register	1 (R/W) Reset Value: 01h
Indicates	PCI positive or negative decoding for various I/O ports on the ISA	bus.
	Positive decoding by the Core Logic module speeds up I/O cycle tirnot exist in the Core Logic module. It is assumed that if positive de	·
7	Secondary Floppy Positive Decode. Selects PCI positive or s and 377h.	ubtractive decoding for accesses to I/O ports 372h-375h
	0: Subtractive.	
	1: Positive.	
6	Primary Floppy Positive Decode. Selects PCI positive or subt 3F7h.	ractive decoding for accesses to I/O ports 3F2h-3F5h and
	0: Subtractive.	
	1: Positive.	
5	COM4 Positive Decode. Selects PCI positive or subtractive de-	coding for accesses to I/O ports 2E8h-2EFh.
	0: Subtractive.	
	1: Positive.	
4	COM3 Positive Decode. Selects PCI positive or subtractive de	coding for accesses to I/O ports 3E8h-3EFh.
	0: Subtractive.	
	1: Positive.	
3	COM2 Positive Decode. Selects PCI positive or subtractive de	coding for accesses to I/O ports 2F8h-2FFh.
	0: Subtractive.	ů i
	1: Positive.	
2	COM1 Positive Decode. Selects PCI positive or subtractive de	coding for accesses to I/O ports 3F8h-3FFh.
	0: Subtractive.	у по
	1: Positive.	
1	Keyboard Controller Positive Decode. Selects PCI positive or	subtractive decoding for accesses to I/O Ports 060h and
•	064h (as well as 062h and 066h, if enabled - F4 Index 5Bh[7] =	
	0: Subtractive.	
	1: Positive.	
	Note: If F0BAR1+I/O Offset 10h bits 10 = 0 and 16 = 1, then	this bit must be written 0.
0	Real-Time Clock Positive Decode. Selects PCI positive or sub	tractive decoding for accesses to I/O Ports 070h-073h.
	0: Subtractive.	
	1: Positive.	
Index 5B	h Decode Control Register	2 (R/W) Reset Value: 20h
1	Positive decoding by the Core Logic module speeds up the I/O cycnot exist in the Core Logic module. It is assumed that if positive dethe ISA bus.	ele time. The Keyboard, LPT3, LPT2, and LPT1 I/O ports do
7	Keyboard I/O Port 062h/066h Positive Decode. This alternate power management features.	port to the keyboard controller is provided in support of
	0: Disable.	
	1: Enable.	
6	Reserved. Must be set to 0.	
5	BIOS ROM Positive Decode. Selects PCI positive or subtractive	e decoding for accesses to the configured ROM space.
	0: Subtractive.	
	1: Positive.	
	ROM configuration is at F0 Index 52h[2:0].	



Table 6-29. F0: PCI Header/Bridge Configuration Registers for GPIO and LPC Support (Continued)

Bit	Description					
4	Secondary IDE Controller Positive Decode. Selects PCI positive or subtractive decoding for accesses to I/O ports 170h-177h and 376h-377h (excluding writes to 377h).					
	0: Subtractive. Subtractive then forwarded to IS	,	es are forwarded to the PCI slot b	ous. If a master abort occurs, they are		
	1: Positive. Positively	decoded IDE addresses are f	orwarded to the internal IDE cont	troller and then to the IDE bus.		
3	-	Primary IDE Controller Positive Decode. Selects PCI positive or subtractive decoding for accesses to I/O ports 1F0h-1F7h and 3F6h-3F7h (excluding writes to 3F7h).				
	0: Subtractive. Subtractive then forwarded to IS	-	es are forwarded to the PCI slot b	ous. If a master abort occurs, they are		
	1: Positive. Positively	decoded IDE addresses are f	orwarded to the internal IDE conf	troller and then to the IDE bus.		
2	LPT3 Positive Decode	. Selects PCI positive or sub	tractive decoding for accesses to	I/O ports 278h-27Fh.		
	0: Subtractive.					
	1: Positive.					
1	LPT2 Positive Decode	. Selects PCI positive or sub	tractive decoding for accesses to	I/O ports 378h-37Fh.		
	0: Subtractive.					
	1: Positive.					
0	LPT1 Positive Decode	. Selects PCI positive or sub	tractive decoding for accesses to	I/O ports 3BCh-3BFh		
	0: Subtractive.					
	1: Positive.					
ndex 5C	:h	PCI Interrupt Stee	ring Register 1 (R/W)	Reset Value: 00h		
ndicates	target interrupts for signal	•	- , ,			
	The target interrupt must to compatibility.	first be configured as level se	ensitive via I/O Ports 4D0h and 4	D1h in order to maintain PCI interrupt		
7:4	INTB# (EBGA Ball AF	1 / TEPBGA Ball C26) Targe	et Interrupt.			
	0000: Disable	0100: IRQ4	1000: Reserved	1100: IRQ12		
	0001: IRQ1 0010: Reserved	0101: IRQ5 0110: IRQ6	1001: IRQ9 1010: IRQ10	1101: Reserved 1110: IRQ14		
	0010: Reserved 0011: IRQ3	0110: IRQ0 0111: IRQ7	1011: IRQ11	1111: IRQ15		
3:0	INTA# (EBGA Ball AE	3 / TEPBGA Ball D26) Targe	et Interrupt.			
	0000: Disable	0100: IRQ4	1000: Reserved	1100: IRQ12		
	0001: IRQ1	0101: IRQ5	1001: IRQ9	1101: Reserved		
	0010: Reserved	0110: IRQ6	1010: IRQ10	1110: IRQ14		
	0011: IRQ3	0111: IRQ7	1011: IRQ11	1111: IRQ15		
ndex 5D	h	PCI Interrupt Stee	ring Register 2 (R/W)	Reset Value: 00h		
	muxed with GPIO19+IOCI	HRDY (selection made via PN	MR[9,4]). See Table 4-2 on page	•		
	The target interrupt must to compatibility.	irst be configured as level se		D1h in order to maintain PCI interrupt		
	Compatibility.					
		2 / TEPBGA Ball AA2) Targe	et Interrupt.			
(INTD# (EBGA Ball B2:	0100: IRQ4	1000: Reserved	1100: IRQ12		
(INTD# (EBGA Ball B2: 0000: Disable 0001: IRQ1	0100: IRQ4 0101: IRQ5	1000: Reserved 1001: IRQ9	1101: Reserved		
(INTD# (EBGA Ball B2:	0100: IRQ4	1000: Reserved			
(INTD# (EBGA Ball B2: 0000: Disable 0001: IRQ1 0010: Reserved 0011: IRQ3	0100: IRQ4 0101: IRQ5 0110: IRQ6	1000: Reserved 1001: IRQ9 1010: IRQ10 1011: IRQ11	1101: Reserved 1110: IRQ14		
7:4	INTD# (EBGA Ball B2: 0000: Disable 0001: IRQ1 0010: Reserved 0011: IRQ3	0100: IRQ4 0101: IRQ5 0110: IRQ6 0111: IRQ7	1000: Reserved 1001: IRQ9 1010: IRQ10 1011: IRQ11	1101: Reserved 1110: IRQ14		
7:4	INTD# (EBGA Ball B2: 0000: Disable 0001: IRQ1 0010: Reserved 0011: IRQ3 INTC# (EBGA Ball H4	0100: IRQ4 0101: IRQ5 0110: IRQ6 0111: IRQ7 / TEPBGA Ball C9) Target I	1000: Reserved 1001: IRQ9 1010: IRQ10 1011: IRQ11	1101: Reserved 1110: IRQ14 1111: IRQ15		
7:4	INTD# (EBGA Ball B2: 0000: Disable 0001: IRQ1 0010: Reserved 0011: IRQ3 INTC# (EBGA Ball H4 0000: Disable 0001: IRQ1 0010: Reserved	0100: IRQ4 0101: IRQ5 0110: IRQ6 0111: IRQ7 / TEPBGA Ball C9) Target II 0100: IRQ4 0101: IRQ5 0110: IRQ6	1000: Reserved 1001: IRQ9 1010: IRQ10 1011: IRQ11 nterrupt. 1000: Reserved 1001: IRQ9 1010: IRQ10	1101: Reserved 1110: IRQ14 1111: IRQ15 1100: IRQ12 1101: Reserved 1110: IRQ14		
7:4	INTD# (EBGA Ball B2: 0000: Disable 0001: IRQ1 0010: Reserved 0011: IRQ3 INTC# (EBGA Ball H4 0000: Disable 0001: IRQ1	0100: IRQ4 0101: IRQ5 0110: IRQ6 0111: IRQ7 / TEPBGA Ball C9) Target II 0100: IRQ4 0101: IRQ5	1000: Reserved 1001: IRQ9 1010: IRQ10 1011: IRQ11 nterrupt. 1000: Reserved 1001: IRQ9	1101: Reserved 1110: IRQ14 1111: IRQ15 1100: IRQ12 1101: Reserved		

Revision 5.1

Bit	Description	
Index 60h-63h ACPI Control Register (R/W)		Reset Value: 00000000h
31:8	Reserved. Must be set to 0.	
7	SUSP_3V Shut Down PLL5. Allow internal SUSP_3V to shut down PLL5.	
	0: Clock generator is stopped when internal SUSP_3V is active.	
	1: Clock generator continues working when internal SUSP_3V is active.	
6	SUSP_3V Shut Down PLL4. Allow internal SUSP_3V to shut down PLL4	
	0: Clock generator is stopped when internal SUSP_3V is active.	
	1: Clock generator continues working when internal SUSP_3V is active.	
5	SUSP_3V Shut Down PLL3. Allow internal SUSP_3V to shut down PLL3.	
	0: Clock generator is stopped when internal SUSP_3V is active.	
	1: Clock generator continues working when internal SUSP_3V is active.	
4	SUSP_3V Shut Down PLL2. Allow internal SUSP_3V to shut down PLL2.	
	0: Clock generator is stopped when internal SUSP_3V is active.	
	1: Clock generator continues working when internal SUSP_3V is active.	
3	SUSP_3V Shut Down PLL6. Allow internal SUSP_3V to shut down PLL6.	
	0: Clock generator is stopped when internal SUSP_3V is active.	
	1: Clock generator continues working when internal SUSP_3V is active.	
2	ACPI C3 SUSP_3V Enable. Allow internal SUSP_3V to be active during C3 state.	
	0: Disable.	
	1: Enable.	
1	ACPI SL1 SUSP_3V Enable. Allow internal SUSP_3V to be active during SL1 sleep state.	
	0: Disable.	
	1: Enable.	
0	ACPI C3 Support Enable. Allow support of C3 states.	
	0: Disable.	
	1: Enable.	
Index 64h-6Bh Reserved		Reset Value: 00h
Index 6Ch	-6Fh ROM Mask Register (R/W)	Reset Value: 0000FFF0h
Note: F	egister must be read/written as a DWORD.	
31:16	Reserved. Must be written to 0.	
15:8	Reserved. Must be written to FFh.	
7:4	ROM Size. If F0 Index 52h[2] = 1:	
	0000: 16 MB = FF000000h-FFFFFFFh	
	1000: 8 MB = FF800000h-FFFFFFFh	
	1100: 4 MB = FFC00000h-FFFFFFFh	
	1110: 2 MB = FFE00000h-FFFFFFFh	
	1111: 1 MB = FFF00000h-FFFFFFFh	
	All other settings for these bits are reserved.	
3:0	Reserved. Must be set to 0.	



Table 6-29. F0: PCI Header/Bridge Configuration Registers for GPIO and LPC Support (Continued)

Bit	Description			
Index 70h-	71h IOCS1# Base Address Register (R/W)	Reset Value: 0000h		
15:0	I/O Chip Select 1 Base Address. This 16-bit value represents the I/O base address used to e (EBGA ball H2 or AL12 / TEPBGA ball D10 or N30 - see PMR[23] in Table 4-2 on page 88).	enable assertion of IOCS1#		
	This register is used in conjunction with F0 Index 72h (IOCS1# Control register).			
Index 72h	Index 72h IOCS1# Control Register (R/W) Reset Value: 00			
This registe	er is used in conjunction with F0 Index 70h (IOCS1# Base Address register).			
7	I/O Chip Select 1 Positive Decode (IOCS1#).			
	0: Disable.			
	1: Enable.			
6	Writes Result in Chip Select. When this bit is set to 1, writes to configured I/O address (base Index 70h; range configured in bits [4:0]) cause IOCS1# to be asserted. 0: Disable.	e address configured in F0		
	1: Enable.			
5	Reads Result in Chip Select. When this bit is set to 1, reads from configured I/O address (ballndex 70h; range configured in bits [4:0]) cause IOCS1# to be asserted. 0: Disable. 1: Enable.	ase address configured in F0		
4:0	IOCS1# I/O Address Range. This 5-bit field is used to select the range of IOCS1#.			
	000000: 1 Byte 01111: 16 Bytes 00001: 2 Bytes 11111: 32 Bytes 00011: 4 Bytes All other combinations are reserved. 00111: 8 Bytes			
Index 73h	Reserved	Reset Value: 00h		
Index 74h-	75h IOCS0# Base Address Register (R/W)	Reset Value: 0000h		
15:0	I/O Chip Select 0 Base Address. This 16-bit value represents the I/O base address used to e	and the things are and an art		
	IOCS0# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88).	enable the assertion of		
	·	enable the assertion of		
Index 76h	IOCS0# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88).	Reset Value: 00h		
	IOCS0# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCS0# Control register).			
	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#).			
This registe	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#). 0: Disable.			
This registe	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#).			
This registe	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#). 0: Disable. 1: Enable. Writes Result in Chip Select. When this bit is set to 1, writes to configured I/O address (base Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted.	Reset Value: 00h		
This registe 7	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#). 0: Disable. 1: Enable. Writes Result in Chip Select. When this bit is set to 1, writes to configured I/O address (base Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. 0: Disable.	Reset Value: 00h		
This registe 7 6	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#). 0: Disable. 1: Enable. Writes Result in Chip Select. When this bit is set to 1, writes to configured I/O address (base Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. 0: Disable. 1: Enable.	Reset Value: 00h		
This registe 7	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#). Disable. Enable. Writes Result in Chip Select. When this bit is set to 1, writes to configured I/O address (base Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. Disable. Enable. Reads Result in Chip Select. When this bit is set to 1, reads from configured I/O address (base Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted.	Reset Value: 00h		
This registe 7 6	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#). O: Disable. 1: Enable. Writes Result in Chip Select. When this bit is set to 1, writes to configured I/O address (base Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. O: Disable. 1: Enable. Reads Result in Chip Select. When this bit is set to 1, reads from configured I/O address (ball Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. O: Disable.	Reset Value: 00h		
This register 7 6	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#). O: Disable. 1: Enable. Writes Result in Chip Select. When this bit is set to 1, writes to configured I/O address (base Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. O: Disable. 1: Enable. Reads Result in Chip Select. When this bit is set to 1, reads from configured I/O address (ball Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. O: Disable. 1: Enable.	Reset Value: 00h		
This registe 7 6	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#). Disable. Enable. Writes Result in Chip Select. When this bit is set to 1, writes to configured I/O address (base Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. Disable. Enable. Reads Result in Chip Select. When this bit is set to 1, reads from configured I/O address (ball Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. Disable. Enable. ICCSO# I/O Address Range. This 5-bit field is used to select the range of IOCSO#.	Reset Value: 00h		
This register 7 6	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#). O: Disable. 1: Enable. Writes Result in Chip Select. When this bit is set to 1, writes to configured I/O address (base Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. O: Disable. 1: Enable. Reads Result in Chip Select. When this bit is set to 1, reads from configured I/O address (ball Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. O: Disable. 1: Enable.	Reset Value: 00h		
This register 7 6	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#). O: Disable. 1: Enable. Writes Result in Chip Select. When this bit is set to 1, writes to configured I/O address (base Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. O: Disable. 1: Enable. Reads Result in Chip Select. When this bit is set to 1, reads from configured I/O address (ball Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. O: Disable. 1: Enable. IOCSO# I/O Address Range. This 5-bit field is used to select the range of IOCSO#. 00000: 1 Byte 0011: 16 Bytes 0011: 4 Bytes All other combinations are reserved.	Reset Value: 00h		
This register 7 6	IOCSO# (EBGA ball J4 / TEPBGA ball A10 - see PMR[23] in Table 4-2 on page 88). This register is used in conjunction with F0 Index 76h (IOCSO# Control register). IOCSO# Control Register (R/W) er is used in conjunction with F0 Index 74h (IOCSO# Base Address register). I/O Chip Select 0 Positive Decode (IOCSO#). O: Disable. 1: Enable. Writes Result in Chip Select. When this bit is set to 1, writes to configured I/O address (base Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. O: Disable. 1: Enable. Reads Result in Chip Select. When this bit is set to 1, reads from configured I/O address (ball Index 74h; range configured in bits [4:0]) cause IOCSO# to be asserted. O: Disable. 1: Enable. IOCSO# I/O Address Range. This 5-bit field is used to select the range of IOCSO#. 00000: 1 Byte 01111: 16 Bytes 00001: 2 Bytes 11111: 32 Bytes	Reset Value: 00h		



Bit	Description		
Index 78h	7Bh DOCCS# Base Address Register (R/W)	Reset Value: 00000000h	
31:0	DiskOnChip Chip Select Base Address. This 32-bit value represents the memory base of DOCCS# (EBGA ball H3 or AJ13 / TEPBGA ball A9 or N31, see PMR[23] in Table 4		
	This register is used in conjunction with F0 Index 7Ch (DOCCS# Control register).		
Index 7Ch	dex 7Ch-7Fh DOCCS# Control Register (R/W) Reset Value: 00000000		
This regist	er is used in conjunction with F0 Index 78h (DOCCS# Base Address register).		
31:27	Reserved. Must be set to 0.		
26	DiskOnChip Chip Select Positive Decode (DOCCS#).		
	0: Disable.		
	1: Enable.		
25	Writes Result in Chip Select. When this bit is set to 1, writes to configured memory a F0 Index 78h; range configured in bits [18:0]) cause DOCCS# to be asserted.	ddress (base address configured in	
	0: Disable.		
	1: Enable.		
24	Reads Result in Chip Select. When this bit is set to 1, reads from configured memory a F0 Index 78h; range configured in bits [18:0]) cause DOCCS# to be asserted.	address (base address configured in	
	0: Disable.		
	1: Enable.		
23:19	Reserved. Must be set to 0.		
18:0	DOCCS# Memory Address Range. This 19-bit mask is used to qualify accesses on wing the upper 19 bits of the incoming PCI address (AD[31:13]).	which DOCCS# is asserted by mask-	
Index 80h	Power Management Enable Register 1 (R/W)	Reset Value: 00h	
7:6	Reserved. Must be set to 0.		
5	Codec SDATA_IN SMI. When set to 1, this bit allows an SMI to be generated in resport positive edge on SDATA_IN.	nse to an AC97 codec producing a	
	0: Disable.		
	1: Enable.		
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 87h/F7h[2].		
4	Video Speedup. Any video activity, as decoded from the serial connection (PSERIAL) throttling (via internal SUSP#/SUSPA# handshake) for a configurable duration when sy Suspend modulation.		
	0: Disable.		
	1: Enable.		
	1: Enable. The duration of the speedup is configured in the Video Speedup Timer Count Register external VGA access (3Bx, 3Cx, 3Dx and A000h-B7FFh) on the PCI bus is also support dard, but it does allow the power management routines to support an external VGA chi	rted. This configuration is non-stan-	
3	The duration of the speedup is configured in the Video Speedup Timer Count Register external VGA access (3Bx, 3Cx, 3Dx and A000h-B7FFh) on the PCI bus is also support dard, but it does allow the power management routines to support an external VGA chi IRQ Speedup. Any unmasked IRQ (per I/O Ports 021h/0A1h) or SMI disables clock the handshake) for a configurable duration when system is power-managed using CPU Su	rted. This configuration is non-stan- p. rottling (via internal SUSP#/SUSPA#	
3	The duration of the speedup is configured in the Video Speedup Timer Count Register external VGA access (3Bx, 3Cx, 3Dx and A000h-B7FFh) on the PCI bus is also support dard, but it does allow the power management routines to support an external VGA chi IRQ Speedup. Any unmasked IRQ (per I/O Ports 021h/0A1h) or SMI disables clock thr handshake) for a configurable duration when system is power-managed using CPU Su 0: Disable.	rted. This configuration is non-stan- p. rottling (via internal SUSP#/SUSPA#	
3	The duration of the speedup is configured in the Video Speedup Timer Count Register external VGA access (3Bx, 3Cx, 3Dx and A000h-B7FFh) on the PCI bus is also support dard, but it does allow the power management routines to support an external VGA chi IRQ Speedup. Any unmasked IRQ (per I/O Ports 021h/0A1h) or SMI disables clock the handshake) for a configurable duration when system is power-managed using CPU Su	rted. This configuration is non-stan- p. rottling (via internal SUSP#/SUSPA# spend modulation.	
	The duration of the speedup is configured in the Video Speedup Timer Count Register external VGA access (3Bx, 3Cx, 3Dx and A000h-B7FFh) on the PCI bus is also support dard, but it does allow the power management routines to support an external VGA chi IRQ Speedup. Any unmasked IRQ (per I/O Ports 021h/0A1h) or SMI disables clock thr handshake) for a configurable duration when system is power-managed using CPU Su 0: Disable. 1: Enable. The duration of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer	rted. This configuration is non-stan- p. rottling (via internal SUSP#/SUSPA# spend modulation.	
3	The duration of the speedup is configured in the Video Speedup Timer Count Register external VGA access (3Bx, 3Cx, 3Dx and A000h-B7FFh) on the PCI bus is also support dard, but it does allow the power management routines to support an external VGA chi IRQ Speedup. Any unmasked IRQ (per I/O Ports 021h/0A1h) or SMI disables clock the handshake) for a configurable duration when system is power-managed using CPU Su 0: Disable. 1: Enable. The duration of the speedup is configured in the IRQ Speedup Timer Count Register (Formula Count Register). Traps. Globally enable all power management I/O traps.	rted. This configuration is non-stan- p. rottling (via internal SUSP#/SUSPA# spend modulation.	
	The duration of the speedup is configured in the Video Speedup Timer Count Register external VGA access (3Bx, 3Cx, 3Dx and A000h-B7FFh) on the PCI bus is also support dard, but it does allow the power management routines to support an external VGA chi IRQ Speedup. Any unmasked IRQ (per I/O Ports 021h/0A1h) or SMI disables clock thr handshake) for a configurable duration when system is power-managed using CPU Su 0: Disable. 1: Enable. The duration of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer Count Register (Foundation of the speedup is configured in the IRQ Speedup Timer	rted. This configuration is non-stan- p. rottling (via internal SUSP#/SUSPA# spend modulation.	



Bit	Description
1	Idle Timers. Device idle timers.
	0: Disable.
	1: Enable.
	Note: Disable at this level does not reload the timers on the enable. The timers are disabled at their current counts. This bit has no affect on the Suspend Modulation register (F0 Index 94h). Only applicable when in APM mode (F1BAR1+I/O Offset 0Ch[0] = 0) and not ACPI mode.
0	Power Management. Global power management.
	0: Disable.
	1: Enable.
	This bit must be set to 1 immediately after POST for power management resources to function.
Index 81h	Power Management Enable Register 2 (R/W) Reset Value: 00h
7	Video Access Idle Timer Enable. Turn on Video Idle Timer Count Register (F0 Index A6h) and generate an SMI when the
	timer expires.
	0: Disable.
	1: Enable.
	If an access occurs in the video address range (sets bit 0 of the GX1 module's PSERIAL register) the timer is reloaded with the programmed count.
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[7].
6	User Defined Device 3 (UDEF3) Idle Timer Enable. Turn on UDEF3 Idle Timer Count Register (F0 Index A4h) and generate an SMI when the timer expires. 0: Disable.
	1: Enable.
	If an access occurs in the programmed address range, the timer is reloaded with the programmed count.
	UDEF3 address programming is at F0 Index C8h (base address register) and CEh (control register).
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[6].
5	User Defined Device 2 (UDEF2) Idle Timer Enable. Turn on UDEF2 Idle Timer Count Register (F0 Index A2h) and generate an SMI when the timer expires.
	0: Disable.
	1: Enable.
	If an access occurs in the programmed address range, the timer is reloaded with the programmed count.
	UDEF2 address programming is at F0 Index C4h (base address register) and CDh (control register).
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0].
	Second level SMI status is reported at F0 Index 85h/F5h[5].
4	User Defined Device 1 (UDEF1) Idle Timer Enable. Turn on UDEF1 Idle Timer Count Register (F0 Index A0h) and generate an SMI when the timer expires.
	0: Disable.
	1: Enable.
	If an access occurs in the programmed address range, the timer is reloaded with the programmed count.
	UDEF1 address programming is at F0 Index C0h (base address register) and CCh (control register).
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0].
	Second level SMI status is reported at F0 Index 85h/F5h[4].

Bit	Description
3	Keyboard/Mouse Idle Timer Enable. Turn on Keyboard/Mouse Idle Timer Count Register (F0 Index 9Eh) and generate an SMI when the timer expires.
	0: Disable.
	1: Enable.
	If an access occurs in the address ranges listed below, the timer is reloaded with the programmed count: — Keyboard Controller: I/O Ports 060h/064h. — COM1: I/O Port 3F8h-3FFh (if F0 Index 93h[1:0] = 10 this range is included). — COM2: I/O Port 2F8h-2FFh (if F0 Index 93h[1:0] = 11 this range is included).
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[3].
2	Parallel/Serial Idle Timer Enable. Turn on Parallel/Serial Port Idle Timer Count Register (F0 Index 9Ch) and generate an SMI when the timer expires.
	0: Disable.
	1: Enable.
	If an access occurs in the address ranges listed below, the timer is reloaded with the programmed count. — LPT1: I/O Port 3BCh-3BEh. — LPT2: I/O Port 378h-37Fh. — COM1: I/O Port 3F8h-3FFh (if F0 Index 93h[1:0] = 10 this range is excluded). — COM2: I/O Port 2F8h-2FFh (if F0 Index 93h[1:0] = 11 this range is excluded). — COM3: I/O Port 3E8h-3EFh. — COM4: I/O Port 2E8h-2EFh.
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[2].
1	Floppy Disk Idle Timer Enable. Turn on Floppy Disk Idle Timer Count Register (F0 Index 9Ah) and generate an SMI when the timer expires.
	0: Disable.
	1: Enable.
	If an access occurs in the address ranges (listed below, the timer is reloaded with the programmed count. — Primary floppy disk: I/O Port 3F2h-3F5h, 3F7h. — Secondary floppy disk: I/O Port 372h-375h, 377h.
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[1].
0	Primary Hard Disk Idle Timer Enable. Turn on Primary Hard Disk Idle Timer Count Register (F0 Index 98h) and generate an SMI when the timer expires.
	0: Disable.
	1: Enable.
	If an access occurs in the address ranges selected in F0 Index 93h[5], the timer is reloaded with the programmed count.
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[0].



Bit	Description	
Index 82h	Power Management Enable Register 3 (R/W)	Reset Value: 00h
7	Video Access Trap. If this bit is enabled and an access occurs in the video address range (sets bit PSERIAL register), an SMI is generated. 0: Disable. 1: Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 86h/F6h[7].	it 0 of the GX1 module's
6	User Defined Device 3 (UDEF3) Access Trap. If this bit is enabled and an access occurs in the programmed address range, an SMI is generated. UDEF3 address programming is at F0 Index C8h (Base Address register) and CEh (Conti register). 0: Disable. 1: Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[9]. Second level SMI status is reported at F1BAR0+I/O Offset 04h/06h[4].	
5	User Defined Device 2 (UDEF2) Access Trap. If this bit is enabled and an access occurs in the prange, an SMI is generated. UDEF2 address programming is at F0 Index C4h (Base Address registregister). 0: Disable. 1: Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[9]. Second level SMI status is reported at F1BAR0+I/O Offset 04h/06h[3].	
4	User Defined Device 1 (UDEF1) Access Trap. If this bit is enabled and an access occurs in the prange, an SMI is generated. UDEF1 address programming is at F0 Index C0h (base address regist register). 0: Disable. 1: Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[9]. Second level SMI status is reported at F1BAR0+I/O Offset 04h/06h[2].	
3	Keyboard/Mouse Access Trap. 0: Disable. 1: Enable. If this bit is enabled and an access occurs in the address ranges listed below, an SMI is generated — Keyboard Controller: I/O Ports 060h/064h. — COM1: I/O Port 3F8h-3FFh (if F0 Index 93h[1:0] = 10 this range is included). — COM2: I/O Port 2F8h-2FFh (if F0 Index 93h[1:0] = 11 this range is included). Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 86h/F6h[3].	
2	Parallel/Serial Access Trap. 0: Disable. 1: Enable. If this bit is enabled and an access occurs in the address ranges listed below, an SMI is generated — LPT1: I/O Port 3BCh-3BEh. — LPT2: I/O Port 378h-37Fh. — COM1: I/O Port 378h-3FFh (if F0 Index 93h[1:0] = 10 this range is excluded). — COM2: I/O Port 2F8h-2FFh (if F0 Index 93h[1:0] = 11 this range is excluded). — COM3: I/O Port 3E8h-3EFh. — COM4: I/O Port 2E8h-2EFh. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 86h/F6h[2].	

Revision 5.1

Bit	Description
1	Floppy Disk Access Trap.
	0: Disable.
	1: Enable.
	If this bit is enabled and an access occurs in the address ranges listed below, an SMI is generated. — Primary floppy disk: I/O Port 3F2h-3F5h, 3F7h. — Secondary floppy disk: I/O Port 372h-375h, 377h.
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 86h/F6h[1].
0	Primary Hard Disk Access Trap.
	0: Disable.
	1: Enable.
	If this bit is enabled and an access occurs in the address ranges selected in F0 Index 93h[5], an SMI is generated.
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 86h/F6h[0].
Index 83h	Power Management Enable Register 4 (R/W) Reset Value: 00h
7	Secondary Hard Disk Idle Timer Enable. Turn on Secondary Hard Disk Idle Timer Count Register (F0 Index ACh) and generate an SMI when the timer expires.
	0: Disable.
	1: Enable.
	If an access occurs in the address ranges selected in F0 Index 93h[4], the timer is reloaded with the programmed count.
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 86h/F6h[4].
6	Secondary Hard Disk Access Trap. If this bit is enabled and an access occurs in the address ranges selected in F0 Index 93h[4], an SMI is generated.
	0: Disable.
	1: Enable.
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 86h/F6h[5].
5	ACPI Timer SMI. Allow SMI generation for MSB toggles on the ACPI Timer (F1BAR0+I/O Offset 1Ch or F1BAR1+I/O Offset 1Ch).
	0: Disable.
	1: Enable.
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 87h/F7h[0].
4	THRM# SMI. Allow SMI generation on assertion of THRM#.
	0: Disable.
	1: Enable.
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 87h/F7h[6].
3	VGA Timer Enable. Turn on VGA Timer Count Register (F0 Index 8Eh) and generate an SMI when the timer reaches 0.
	0: Disable.
	1: Enable.
	If an access occurs in the programmed address range, the timer is reloaded with the programmed count. F0 Index 8Bh[6]
	selects the timebase for the VGA Timer.



Bit	Description
2	Video Retrace Interrupt SMI. Allow SMI generation whenever video retrace occurs.
	0: Disable.
	1: Enable.
	This information is decoded from the serial connection (PSERIAL register, bit 7) from the GX1 module. This function is normally not used for power management but for soft (VSA) VGA routines.
	SMI status reporting is at F1BAR0+I/O Offset 00h/02h[5] (top level only).
1	General Purpose Timer 2 Enable. Turn on GP Timer 2 Count Register (F0 Index 8Ah) and generate an SMI when the timer expires.
	0: Disable.
	1: Enable.
	This idle timer is reloaded from the assertion of GPIO7 (if programmed to do so). GP Timer 2 programming is at F0 Index 8Bh[5,3,2].
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[9].
	Second level SMI status is reported at F1BAR0+I/O Offset 04h/06h[1].
0	General Purpose Timer 1 Enable. Turn on GP Timer 1 Count Register (F0 Index 88h) and generate an SMI when the timer expires.
	0: Disable.
	1: Enable.
	This idle timer's load is multi-sourced and gets reloaded any time an enabled event (F0 Index 89h[6:0]) occurs. GP Timer 1 programming is at F0 Index 8Bh[4].
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[9]. Second level SMI status is reported at F1BAR0+I/O Offset 04h/06h[0].

Index 84h

Second Level PME/SMI Status Mirror Register 1 (RO)

Reset Value: 00h

The bits in this register are used for the second level of status reporting. The top level is reported at F1BAR0+I/O Offset 00h/02h[0]. This register is called a "mirror" register since an identical register exists at F0 Index F4h. Reading this register does not clear the status, while reading its counterpart at F0 Index F4h clears the status at both the second and the top levels.

7:3	Reserved. Reads as 0.
2	GPWIO2 SMI Status. Indicates whether or not an SMI was caused by a transition on the GPWIO2 pin.
	0: No.
	1: Yes.
	To enable SMI generation: 1) Ensure that GPWIO2 is enabled as an input: F1BAR1+I/O Offset 15h[2] = 0. 2) Set F1BAR1+I/O Offset 15h[6] to 1.
1	GPWIO1 SMI Status. Indicates whether or not an SMI was caused by a transition on the GPWIO1 pin.
	0: No.
	1: Yes.
	To enable SMI generation: 1) Ensure that GPWIO1 is enabled as an input: F1BAR1+I/O Offset 15h[1] = 0.
	2) Set F1BAR1+I/O Offset 15h[5] to 1.
0	GPWIO0 SMI Status. Indicates whether or not an SMI was caused by a transition on the GPWIO0 pin.
	0: No.
	1: Yes.
	To enable SMI generation: 1) Ensure that GPWIO0 is enabled as an input: F1BAR1+I/O Offset 15h[0] = 0. 2) Set F1BAR1+I/O Offset 15h[4] to 1.

Bit	Description
Index 85h	Second Level PME/SMI Status Mirror Register 2 (RO) Reset Value: 00h
The bits in	this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0].
	er is called a "Mirror" register since an identical register exists at F0 Index F5h. Reading this register does not clear the status, ng its counterpart at F0 Index F5h clears the status at both the second and top levels.
7	Video Idle Timer Timeout. Indicates whether or not an SMI was caused by expiration of Video Idle Timer Count Register (F0 Index A6h). 0: No. 1: Yes.
	To enable SMI generation, set F0 Index 81h[7] to 1.
6	User Defined Device Idle Timer 3 Timeout. Indicates whether or not an SMI was caused by expiration of User Defined Device 3 Idle Timer Count Register (F0 Index A4h). 0: No 1: Yes To enable SMI generation, set F0 Index 81h[6] to 1.
5	User Defined Device Idle Timer 2 Timeout. Indicates whether or not an SMI was caused by expiration of User Defined Device 2 Idle Timer Count Register (F0 Index A2h). 0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[5] to 1.
4	User Defined Device Idle Timer 1 Timeout. Indicates whether or not an SMI was caused by expiration of User Defined Device 1 Idle Timer Count Register (F0 Index A0h). 0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[4] to 1.
3	Keyboard/Mouse Idle Timer Timeout. Indicates whether or not an SMI was caused by expiration of Keyboard/Mouse Idle Timer Count Register (F0 Index 9Eh). 0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[3] to 1.
2	Parallel/Serial Idle Timer Timeout. Indicates whether or not an SMI was caused by expiration of Parallel/Serial Port Idle Timer Count Register (F0 Index 9Ch). 0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[2] to 1.
1	Floppy Disk Idle Timer Timeout. Indicates whether or not an SMI was caused by expiration of Floppy Disk Idle Timer Count Register (F0 Index 9Ah). 0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[1] to 1.
0	Primary Hard Disk Idle Timer Timeout. Indicates whether or not an SMI was caused by expiration of Primary Hard Disk Idle Timer Count Register (F0 Index 98h). 0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] to 1.



Bit	Description
Index 86h	Second Level PME/SMI Status Mirror Register 3 (RO) Reset Value: 00h
The bits in	this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0].
	er is called a "Mirror" register since an identical register exists at F0 Index F6h. Reading this register does not clear the status, ing its counterpart at F0 Index F6h clears the status at both the second and top levels.
7	Video Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the Video I/O Trap.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 82h[7] to 1.
6	Reserved.
5	Secondary Hard Disk Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the secondary hard disk.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 83h[6] to 1.
4	Secondary Hard Disk Idle Timer SMI Status. Indicates whether or not an SMI was caused by expiration of Secondary Hard Disk Idle Timer Count register (F0 Index ACh).
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 83h[7] to 1.
3	Keyboard/Mouse Access Trap SMI Status. Indicates whether or not an SMI was caused by an trapped I/O access to the keyboard or mouse.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 82h[3] to 1.
2	Parallel/Serial Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to either the serial or parallel ports.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 82h[2] to 1.
1	Floppy Disk Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the floppy disk.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 82h[1] to 1.
0	Primary Hard Disk Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the primary hard disk.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 82h[0] to 1.

Revision 5.1

Bit	Description
Index 87h	Second Level PME/SMI Status Mirror Register 4 (RO) Reset Value: 00h
The bits in	this register contain second level status reporting. Top level status is reported at F1BAR0+I/O Offset 00h/02h[0].
while readi	er is called a "Mirror" register since an identical register exists at F0 Index F7h. Reading this register does not clear the status, ng its counterpart at F0 Index F7h clears the status at both the second and top levels except for bit 7 which has a third level us reporting at F0BAR0+I/O 0Ch/1Ch.
7	GPIO Event SMI Status. Indicates whether or not an SMI was caused by a transition of any of the GPIOs (GPIO47-GPIO32 and GPIO15-GPIO0). 0: No.
	1: Yes.
	To enable SMI generation, set F1BAR1+I/O Offset 0Ch[0] to 0.
	F0BAR0+I/O Offset 08h/18h selects which GPIOs are enabled to generate a PME and setting F1BAR1+I/O Offset 0Ch[0] = 0 enables the PME to generate an SMI. In addition, the selected GPIO must be enabled as an input (F0BAR0+I/O Offset 20h and 24h).
	The next level (third level) of SMI status is at F0BAR0+I/O 0Ch/1Ch[15:0].
6	Thermal Override SMI Status. Indicates whether or not an SMI was caused by the assertion of THRM#.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 83h[4] to 1.
5:4	Reserved. Always reads 0.
3	SIO PWUREQ SMI Status. Indicates whether or not an SMI was caused by a power-up event from the SIO.
	0: No.
	1: Yes.
	A power-up event is defined as any of the following events/activities: — RI2# — SDATA_IN2 — IRRX1 (CEIR)
	To enable SMI generation, set F1BAR1+I/O Offset 0Ch[0] to 0.
2	Codec SDATA_IN SMI Status. Indicates whether or not an SMI was caused by AC97 Codec producing a positive edge on SDATA_IN.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 80h[5] to 1.
1	RTC Alarm (IRQ8#) SMI Status. Indicates whether or not an SMI was caused by an RTC interrupt. 0: No.
	1: Yes.
	This SMI event can only occur while in 3V Suspend and an RTC interrupt occurs with F1BAR1+I/O Offset 0Ch[0] = 0.
0	ACPI Timer SMI Status. Indicates whether or not an SMI was caused by an ACPI Timer (F1BAR0+I/O Offset 1Ch or F1BAR1+I/O Offset 1Ch) MSB toggle.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 83h[5] to 1.
Index 88h	General Purpose Timer 1 Count Register (R/W) Reset Value: 00h
7:0	GPT1_COUNT. This field represents the load value for General Purpose Timer 1. This value can represent either an 8-bit counter or a 16-bit counter (selected in F0 Index 8Bh[4]). It is loaded into the counter when the timer is enabled (F0 Index 83h[0] = 1). Once enabled, an enabled event (configured in F0 Index 89h[6:0]) reloads the timer.
	The counter is decremented with each clock of the configured timebase (1 ms or 1 sec selected at F0 Index 89h[7]). Upon expiration of the counter, an SMI is generated, and the top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[9]. The second level SMI status is reported at F1BAR0+I/O Offset 04h/06h[0]. Once expired, this counter must be re-initialized by either disabling and enabling it, or writing a new count value in this register. See Section 6.2.10.3 "Peripheral Power Management" on page 180 for a discussion on the limitations of producing count error with small values.



Bit	Description	
Index 89h	General Purpose Timer 1 Control Register (R/W)	Reset Value: 00h
7	General Purpose Timer 1 Timebase. Selects timebase for General Purpose Timer 1 (F0 Index 88h 0: 1 second. 1: 1 millisecond.).
6	Re-trigger General Purpose Timer 1 on User Defined Device 3 (UDEF3) Activity. 0: Disable. 1: Enable. Any access to the configured (memory or I/O) address range for UDEF3 (configured in F0 Index C8h and CEh) reloads General Purpose Timer 1.	
5	Re-trigger General Purpose Timer 1 on User Defined Device 2 (UDEF2) Activity. 0: Disable. 1: Enable. Any access to the configured (memory or I/O) address range for UDEF2 (configured in F0 Index C4h and CDh) reloads General Purpose Timer 1.	
4	Re-trigger General Purpose Timer 1 on User Defined Device 1 (UDEF1) Activity. 0: Disable. 1: Enable. Any access to the configured (memory or I/O) address range for UDEF1 (configured in F0 Index C0h and CCh) reloads General Purpose Timer 1.	
3	Re-trigger General Purpose Timer 1 on Keyboard or Mouse Activity. 0: Disable. 1: Enable. Any access to the keyboard or mouse I/O address range listed below reloads General Purpose Timer 1:	
2	Re-trigger General Purpose Timer 1 on Parallel/Serial Port Activity. 0: Disable. 1: Enable. Any access to the parallel or serial port I/O address range listed below reloads the General Purpose — LPT1: I/O Port 3BCh-3BEh. — LPT2: I/O Port 378h-37Fh. — COM1: I/O Port 3F8h-3FFh (if F0 Index 93h[1:0] = 10 this range is excluded). — COM2: I/O Port 2F8h-2FFh (if F0 Index 93h[1:0] = 11 this range is excluded). — COM3: I/O Port 3E8h-3EFh. — COM4: I/O Port 2E8h-2EFh.	Timer 1:
1	Re-trigger General Purpose Timer 1 on Floppy Disk Activity. 0: Disable. 1: Enable. Any access to the floppy disk drive address ranges listed below reloads General Purpose Timer 1: — Primary floppy disk: I/O Port 3F2h-3F5h, 3F7h — Secondary floppy disk: I/O Port 372h-375h, 377h The active floppy disk drive is configured via F0 Index 93h[7].	
0	Re-trigger General Purpose Timer 1 on Primary Hard Disk Activity. 0: Disable. 1: Enable. Any access to the primary hard disk address range selected in F0 Index 93h[5], reloads General Pur	pose Timer 1.



Bit	Description	
Index 8Ah	General Purpose Timer 2 Count Register (R/W)	Reset Value: 00h
7:0	GPT2_COUNT. This field represents the load value for General Purpose Timer 2. This value can re 16-bit counter (configured in F0 Index 8Bh[5]). It is loaded into the counter when the timer is enable Once the timer is enabled and a transition occurs on GPIO7, the timer is re-loaded.	
	The counter is decremented with each clock of the configured timebase (1 ms or 1 sec selected at expiration of the counter, an SMI is generated and the top level of status is F1BAR0+I/O Offset 00 level of status is reported at F1BAR0+I/O Offset 04h/06h[1]). Once expired, this counter must be rabling and enabling it, or by writing a new count value in this register. Section 6.2.10.3 "Peripheral page 180 for a discussion on the limitations of producing count error with small values.	n/02h[9]. The second e-initialized by either dis-
	For GPIO7 to act as the reload for this counter, it must be enabled as such (F0 Index 8Bh[2]) and b (GPIO pin programming is at F0BAR0+I/O Offset 20h and 24h.)	e configured as an input
Index 8Bh	General Purpose Timer 2 Control Register (R/W)	Reset Value: 00h
7	Re-trigger General Purpose Timer 1 (GP Timer 1) on Secondary Hard Disk Activity.	
	0: Disable.	
	1: Enable.	
	Any access to the secondary hard disk address range selected in F0 Index 93h[4] reloads GP Time	er 1.
6	VGA Timer Base. Selects timebase for VGA Timer Register (F0 Index 8Eh).	
	0: 1 millisecond.	
	1: 32 microseconds.	
5	General Purpose Timer 2 (GP Timer 2) Shift. GP Timer 2 is treated as an 8-bit or 16-bit timer.	
	0: 8-bit. The count value is loaded into GP Timer 2 Count Register (F0 Index 8Ah).	
	 1: 16-bit. The value loaded into GP Timer 2 Count Register is shifted left by eight bits, the lower eand this 16-bit value is used as the count for GP Timer 2. 	eight bits become zero,
4	General Purpose Timer 1 (GP Timer 1) Shift. GP Timer 1 is treated as an 8-bit or 16-bit timer.	
	0: 8-bit. The count value is that loaded into GP Timer 1 Count Register (F0 Index 88h).	
	1: 16-bit. The value loaded into GP Timer 1 Count Register is shifted left by eight bit, the lower eight this 16-bit value is used as the count for GP Timer 1.	ht bits become zero, and
3	General Purpose Timer 2 (GP Timer 2) Timebase. Selects timebase for GP Timer 2 (F0 Index 8	Ah).
	0: 1 second.	
	1: 1 millisecond.	
2	Re-trigger Timer on GPIO7 Pin Transition. A rising-edge transition on the GPIO7 pin reloads GF	P Timer 2 (F0 Index 8Ah)
	0: Disable.	
	1: Enable.	
	For GPIO7 to work here, it must first be configured as an input. (GPIO pin programming is at F0BA 24h.)	AR0+I/O Offset 20h and
1:0	Reserved. Set to 0.	
Index 8Ch	IRQ Speedup Timer Count Register (R/W)	Reset Value: 00h
7:0	IRQ Speedup Timer Load Value. This field represents the load value for the IRQ speedup timer. counter when Suspend Modulation is enabled (F0 Index 96h[0] = 1) and an INTR or an access to When the event occurs, the Suspend Modulation logic is inhibited, permitting full performance oper Upon expiration, no SMI is generated; the Suspend Modulation begins again. The IRQ speedup tire	I/O Port 061h occurs. ation of the GX1 module
	This speedup mechanism allows instantaneous response to system interrupts for full-speed interrupts also a 4 ms .	upt processing. A typical
Index 8Dh	Video Speedup Timer Count Register (R/W)	Reset Value: 00h
7:0	Video Speedup Timer Load Value. This field represents the load value for the Video speedup time counter when Suspend Modulation is enabled (F0 Index 96[0] = 1) and any access to the graphics a video access occurs, the Suspend Modulation logic is inhibited, permitting full-performance operation, no SMI is generated, and Suspend Modulation begins again. The video speedup	controller occurs. When ation of the GX1 module
	This speedup mechanism allows instantaneous response to video activity for full speed during vide tions. A typical value here would be 50 ms to 100 ms.	



Table 6-29. F0: PCI Header/Bridge Configuration Registers for GPIO and LPC Support (Continued)

Bit	Description	
Index 8Eh	VGA Timer Count Register (R/W)	Reset Value: 00h
7:0	VGA Timer Load Value. This field represents the load value for VGA Timer. It is loaded into tenabled (F0 Index 83h[3] = 1). The counter is decremented with each clock of the configured Upon expiration of the counter, an SMI is generated and the status is reported at F1BAR0+I/C Once expired, this counter must be re-initialized by either disabling and enabling it, or by writing register. Note: Although grouped with the power management Idle Timers, the VGA Timer is not a	timebase (F0 Index 8Bh[6]). O Offset 00h/02h[6] (only). ng a new count value in this
Index 8Fh-	It is not affected by the Global Power Management Enable setting at F0 Index 80h[0] Reserved]. Reset Value: 00h
	Miscellaneous Device Control Register (R/W)	
Index 93h	Floppy Drive Port Select. Indicates whether all system resources used to power manage the or secondary FDC addresses for decode.	Reset Value: 00h e floppy drive use the primary,
	O: Secondary. 1: Primary.	
6	Reserved. Must be set to 1.	
5	Partial Primary Hard Disk Decode. This bit is used to restrict the addresses which are decoaccesses.	ded as primary hard disk
	0: Power management monitors all reads and writes to I/O Port 1F0h-1F7h, 3F6h-3F7h (excludes writes to 377h).	ludes writes to 3F7h), and
	1: Power management monitors only writes to I/O Port 1F6h and 1F7h.	
4	Partial Secondary Hard Disk Decode. This bit is used to restrict the addresses which are decacesses.	coded as secondary hard disk
	0: Power management monitors all reads and writes to I/O Port 170h-177h, 376h-377h (exclusive property of the property of	udes writes to 377h).
	1: Power management monitors only writes to I/O Port 176h and 177h.	
3:2	Reserved. Must be set to 0.	
1	Mouse on Serial Enable. Mouse is present on a Serial Port.	
	0: No.	
	1: Yes. If a mouse is attached to a serial port (i.e., this bit is set to 1), that port is removed from the semonitor serial port access for power management purposes and added to the keyboard/mous because a mouse, along with the keyboard, is considered an input device and is used only to screen. This bit and bit 0 of this register determine the decode used for the Keyboard/Mouse Idle Time	e decode. This is done determine when to blank the
	9Eh) as well as the Parallel/Serial Port Idle Timer Count Register (F0 Index 9Ch).	or Count Regiotor (1 o maox
0	Mouse Port Select. Selects which serial port the mouse is attached to:	
	0: COM1	
	1: COM2.	
	For more information see the description of bit 1 in this register (above).	
Index 94h-		Reset Value: 0000h
15:8	Suspend Signal Asserted Counter. This 8-bit counter represents the number of 32 µs intervisignal is asserted to the GX1 module. Together with bits [7:0], perform the Suspend Modulation management. The ratio of SUSP# asserted-to-de-asserted sets up an effective (emulated) clopower manager to reduce GX1 module power consumption.	on function for CPU power ock frequency, allowing the
7.0	This counter is prematurely reset if an enabled speedup event occurs (i.e., IRQ and video spe	
7:0	Suspend Signal De-asserted Counter. This 8-bit counter represents the number of 32 µs into signal is de-asserted to the GX1 module. Together with bits [15:8], perform the Suspend Modu management. The ratio of SUSP# asserted-to-de-asserted sets up an effective (emulated) clopower manager to reduce GX1 module power consumption.	lation function for CPU power
	This counter is prematurely reset if an enabled speedup event occurs (i.e., IRQ and video spe	eedups).



Bit	Description	
Index 96h	Suspend Configuration Register (R/W)	Reset Value: 00h
7:3	Reserved. Must be set to 0.	
2	Suspend Mode Configuration. Special 3V Suspend mode to support powering down the GX1	module during Suspend.
	0: Disable.	
	1: Enable.	
1	SMI Speedup Configuration. Selects how the Suspend Modulation function should react when	an SMI occurs.
	0: Use the IRQ Speedup Timer Count Register (F0 Index 8Ch) to temporarily disable Suspend occurs.	Modulation when an SMI
	 Disable Suspend Modulation when an SMI occurs until a read to the SMI Speedup Disable Re 08h). 	egister (F1BAR0+I/O Offset
	The purpose of this bit is to disable Suspend Modulation while the GX1 module is in the System VSA and Power Management operations occur at full speed. Two methods for accomplishing this	•
	Map the SMI into the IRQ Speedup Timer Count Register (F0 Index 8Ch).	
	- or -	
	Have the SMI disable Suspend Modulation until the SMI handler reads the SMI Speedup Disable Offset 08h). This the preferred method.	e Register (F1BAR0+I/O
	This bit has no affect if the Suspend Modulation feature is disabled (bit $0 = 0$).	
0	Suspend Modulation Feature Enable. This bit is used to enable/disable the Suspend Modulation	on feature.
	0: Disable.	
	1: Enable.	
	When enabled, the internal SUSP# signal is asserted and de-asserted for the durations programmed in the Suspend Modulation register (F0 Index 94h).	
	The setting of this bit is mirrored in the Top Level PME/SMI Status register (F1BAR0+I/O Offset the SMI handler to determine if the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting of this bit is mirrored in the Top Level PME/SMI Status register (F1BAR0+I/O Offset 08h) must be setting of this bit is mirrored in the Top Level PME/SMI Status register (F1BAR0+I/O Offset 08h) must be setting of this bit is mirrored in the Top Level PME/SMI Status register (F1BAR0+I/O Offset 08h) must be setting of this bit is mirrored in the Top Level PME/SMI Status register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08h) must be setting to the SMI Speedup Disable register (F1BAR0+I/O Offset 08	
Index 97h	Reserved	
		Reset Value: 00h
Index 98h-	99h Primary Hard Disk Idle Timer Count Register (Primary Channel) (R/W)	Reset Value: 000h
15:0	Primary Hard Disk Idle Timer Count. This idle timer is used to determine when the primary ha it can be powered down. The 16-bit value programmed here represents the period of hard disk ir tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever an analysis of the count value whenever and the count value whenever and the count value whenever are considered.	Reset Value: 0000h and disk is not in use so that nactivity after which the sys-
	Primary Hard Disk Idle Timer Count. This idle timer is used to determine when the primary har it can be powered down. The 16-bit value programmed here represents the period of hard disk in	Reset Value: 0000h and disk is not in use so that nactivity after which the sys-
	Primary Hard Disk Idle Timer Count. This idle timer is used to determine when the primary has it can be powered down. The 16-bit value programmed here represents the period of hard disk in tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever an aured hard disk's data port (I/O port 1F0h or 3F6h). This counter uses a 1 second timebase. To enable this timer, set F0 Index 81h[0] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0].	Reset Value: 0000h and disk is not in use so that nactivity after which the sys-
	Primary Hard Disk Idle Timer Count. This idle timer is used to determine when the primary has it can be powered down. The 16-bit value programmed here represents the period of hard disk in tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever an ured hard disk's data port (I/O port 1F0h or 3F6h). This counter uses a 1 second timebase. To enable this timer, set F0 Index 81h[0] = 1.	Reset Value: 0000h and disk is not in use so that nactivity after which the sys-
	Primary Hard Disk Idle Timer Count. This idle timer is used to determine when the primary had it can be powered down. The 16-bit value programmed here represents the period of hard disk in tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever and ured hard disk's data port (I/O port 1F0h or 3F6h). This counter uses a 1 second timebase. To enable this timer, set F0 Index 81h[0] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[0].	Reset Value: 0000h and disk is not in use so that nactivity after which the sys-
15:0	Primary Hard Disk Idle Timer Count. This idle timer is used to determine when the primary has it can be powered down. The 16-bit value programmed here represents the period of hard disk in tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever an aured hard disk's data port (I/O port 1F0h or 3F6h). This counter uses a 1 second timebase. To enable this timer, set F0 Index 81h[0] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[0].	Reset Value: 0000h Ind disk is not in use so that hactivity after which the sysaccess occurs to the configuration. Reset Value: 0000h In not in use so that it can be ctivity after which the sysacces.
15:0	Primary Hard Disk Idle Timer Count. This idle timer is used to determine when the primary har it can be powered down. The 16-bit value programmed here represents the period of hard disk in tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever an aured hard disk's data port (I/O port 1F0h or 3F6h). This counter uses a 1 second timebase. To enable this timer, set F0 Index 81h[0] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[0]. PBh Floppy Disk Idle Timer Count Register (R/W) Floppy Disk Idle Timer Count. This idle timer is used to determine when the floppy disk drive is powered down. The 16-bit value programmed here represents the period of floppy disk drive inatem is alerted via an SMI. The timer is automatically reloaded with the count value whenever an account of the power of the provided with the count value whenever and the	Reset Value: 0000h Ind disk is not in use so that hactivity after which the system access occurs to the configuration. Reset Value: 0000h In not in use so that it can be ctivity after which the sys-
15:0	Primary Hard Disk Idle Timer Count. This idle timer is used to determine when the primary had it can be powered down. The 16-bit value programmed here represents the period of hard disk in tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever and ured hard disk's data port (I/O port 1F0h or 3F6h). This counter uses a 1 second timebase. To enable this timer, set F0 Index 81h[0] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[0]. PBh Floppy Disk Idle Timer Count Register (R/W) Floppy Disk Idle Timer Count. This idle timer is used to determine when the floppy disk drive is powered down. The 16-bit value programmed here represents the period of floppy disk drive in a tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever and ured floppy drive's data port (I/O port 3F5h or 375h).	Reset Value: 0000h Ind disk is not in use so that hactivity after which the sysaccess occurs to the configuration. Reset Value: 0000h In not in use so that it can be ctivity after which the sysacces.
15:0	Primary Hard Disk Idle Timer Count. This idle timer is used to determine when the primary hard it can be powered down. The 16-bit value programmed here represents the period of hard disk in tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever an aured hard disk's data port (I/O port 1F0h or 3F6h). This counter uses a 1 second timebase. To enable this timer, set F0 Index 81h[0] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[0]. PBh Floppy Disk Idle Timer Count Register (R/W) Floppy Disk Idle Timer Count. This idle timer is used to determine when the floppy disk drive is powered down. The 16-bit value programmed here represents the period of floppy disk drive in a tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever an aured floppy drive's data port (I/O port 3F5h or 375h). This counter uses a 1 second time base. To enable this timer, set F0 Index 81h[1] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[1].	Reset Value: 0000h Ind disk is not in use so that hactivity after which the sysaccess occurs to the configuration. Reset Value: 0000h In not in use so that it can be ctivity after which the sysacces.
15:0 Index 9Ah 15:0	Primary Hard Disk Idle Timer Count. This idle timer is used to determine when the primary hard it can be powered down. The 16-bit value programmed here represents the period of hard disk in tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever an aured hard disk's data port (I/O port 1F0h or 3F6h). This counter uses a 1 second timebase. To enable this timer, set F0 Index 81h[0] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[0]. PBh Floppy Disk Idle Timer Count Register (R/W) Floppy Disk Idle Timer Count. This idle timer is used to determine when the floppy disk drive is powered down. The 16-bit value programmed here represents the period of floppy disk drive in a tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever an aured floppy drive's data port (I/O port 3F5h or 375h). This counter uses a 1 second time base. To enable this timer, set F0 Index 81h[1] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[1].	Reset Value: 0000h Ind disk is not in use so that hactivity after which the system of the configuration of the count value whenever in the count value in
15:0 Index 9Ah- 15:0 Index 9Ch-	Primary Hard Disk Idle Timer Count. This idle timer is used to determine when the primary ha it can be powered down. The 16-bit value programmed here represents the period of hard disk in tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever an aured hard disk's data port (I/O port 1F0h or 3F6h). This counter uses a 1 second timebase. To enable this timer, set F0 Index 81h[0] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[0]. Ploppy Disk Idle Timer Count Register (R/W) Floppy Disk Idle Timer Count. This idle timer is used to determine when the floppy disk drive is powered down. The 16-bit value programmed here represents the period of floppy disk drive in a tem is alerted via an SMI. The timer is automatically reloaded with the count value whenever an aured floppy drive's data port (I/O port 3F5h or 375h). This counter uses a 1 second time base. To enable this timer, set F0 Index 81h[1] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[1]. Parallel / Serial Idle Timer Count. Register (R/W) Parallel / Serial Idle Timer Count. This idle timer is used to determine when the parallel and set that the ports can be power managed. The 16-bit value programmed in this register represents these ports after which the system is alerted via an SMI. The timer is automatically reloaded with an access occurs to the parallel (LPT) or serial (COM) I/O address spaces. If the mouse is enabled the mouse is enabled the parallel (LPT) or serial (COM) I/O address spaces. If the mouse is enabled the parallel (LPT) or serial (COM) I/O address spaces.	Reset Value: 0000h Ind disk is not in use so that hactivity after which the system of the configuration of the count value whenever in the count value in



Bit	Description	
Index 9Eh	9Fh Keyboard / Mouse Idle Timer Count Register (R/W)	Reset Value: 0000h
15:0	Keyboard / Mouse Idle Timer Count. This idle timer determines when the keyboard and mouse LCD screen can be blanked. The 16-bit value programmed in this register represents the per after which the system is alerted via an SMI. The timer is automatically reloaded with the counoccurs to either the keyboard or mouse I/O address spaces (including the mouse serial port is enabled on a serial port.)	riod of inactivity for these ports unt value whenever an access
	This counter uses a 1 second time base. To enable this timer, set F0 Index $81h[3] = 1$.	
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[3].	
Index A0h	-A1h User Defined Device 1 Idle Timer Count Register (R/W)	Reset Value: 0000h
15:0	User Defined Device 1 (UDEF1) Idle Timer Count. This idle timer determines when the device 1 (UDEF1) is not in use so that it can be power managed. The 16-bit value programm the period of inactivity for this device after which the system is alerted via an SMI. The timer the count value whenever an access occurs to memory or I/O address space configured in the register) and F0 Index CCh (Control register).	ned in this register represents is automatically reloaded with
	This counter uses a 1 second time base. To enable this timer, set F0 Index 81h[4] = 1.	
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[4].	
Index A2h	-A3h User Defined Device 2 Idle Timer Count Register (R/W)	Reset Value: 0000h
15:0	User Defined Device 2 (UDEF2) Idle Timer Count. This idle timer determines when the devi in use so that it can be power managed. The 16-bit value programmed in this register repres this device after which the system is alerted via an SMI. The timer is automatically reloaded an access occurs to memory or I/O address space configured in the F0 Index C4h (Base Ad CDh (Control register). This counter uses a 1 second timebase. To enable this timer, set F0 Index 81h[5] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[5].	ents the period of inactivity for with the count value wheneve
Index A4h	,	Reset Value: 0000h
15:0	User Defined Device 3 (UDEF3) Idle Timer Count. This idle timer determines when the devi in use so that it can be power managed. The 16-bit value programmed in this register repres this device after which the system is alerted via an SMI. The timer is automatically reloaded an access occurs to memory or I/O address space configured in the UDEF3 Base Address FUDEF3 Control Register (F0 Index CEh). This counter uses a 1 second timebase. To enable this timer, set F0 Index 81h[6] = 1. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0].	ice configured as UDEF3 is no ents the period of inactivity fo with the count value wheneve
	Second level SMI status is reported at F0 Index 85h/F5h[6].	
Index A6h	<u> </u>	Reset Value: 0000h
15:0	Video Idle Timer Count. This idle timer determines when the graphics subsystem has been determination algorithm. The 16-bit value programmed in this register represents the period the system is alerted via an SMI. The count in this timer is automatically reset at any access space.	of video inactivity after which
	This counter uses a 1 second timebase. To enable this timer, set F0 Index 81h[7] = 1.	
	Since the graphics controller is embedded in the GX1 module, video activity is communicated the serial connection (PSERIAL register, bit 0). The Core Logic module also detects accesse PCI (3Bxh, 3Cxh, 3Dxh and A000h-B7FFh) if an external VGA controller is being used.	
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 85h/F5h[7].	
Index A8h	A9h Video Overflow Count Register (R/W)	Reset Value: 0000h
15:0	Video Overflow Count. Each time the video speedup counter is triggered, a 100 ms timer is expires before the video speedup counter lapses, the Video Overflow Count register increme gers. Software clears the overflow register when new evaluations are to begin. The count countercombined with other data to determine the type of video accesses present in the system.	nts and the 100 ms timer retrig

Reserved

Reset Value: 00h

Index AAh-ABh



Bit	Description	
Index ACh	ADh Secondary Hard Disk Idle Timer Count Register (R/W)	Reset Value: 0000h
15:0	Secondary Hard Disk Idle Timer Count. This idle timer is used to determine when the secondary hard disk is that it can be powered down. The 16-bit value programmed in this register represents the period of hard disk which the system is alerted via an SMI. The timer is automatically reloaded with the count value whenever an to the configured hard disk's data port (I/O port 1F0h or 170h).	
	This counter uses a 1 second timebase. To enable this timer, set F0 Index 83h[7] = 1.	
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[0]. Second level SMI status is reported at F0 Index 86h/F6h[4].	
Index AEh	CPU Suspend Command Register (WO)	Reset Value: 00h
7:0	Software CPU Suspend Command. If bit 0 in the Clock Stop Control register is set low (F0 Index BCh[0] = 0), a write this register causes an internal SUSP#/SUSPA# handshake with the GX1 module, placing the GX1 module in a low-por state. The actual data written is irrelevant. Once in this state, any unmasked IRQ or SMI releases the GX1 module halt dition.	
	If F0 Index BCh[0] = 1, writing to this register invokes a full system Suspend. In this case, the ir asserted after the SUSP#/SUSPA# halt. Upon a Resume event, the PLL delay programmed in invoked, allowing the clock chip and GX1 module PLL to stabilize before de-asserting SUSP#.	
Index AFh	Suspend Notebook Command Register (WO)	Reset Value: 00h
7:0	Software CPU Stop Clock Suspend. A write to this register causes a SUSP#/SUSPA# handshake with the CPU the GX1 module in a low-power state. Following this handshake, the SUSP_3V signal is asserted. The SUSP_3V intended to be used to stop all system clocks.	
	Upon a Resume event, the internal SUSP_3V signal is de-asserted. After a slight delay, the Cothe SUSP# signal. Once the clocks are stable, the GX1 module de-asserts SUSPA# and system	•
Index B0h-	B3h Reserved	Reset Value: 00h
Index B4h	Floppy Port 3F2h Shadow Register (RO)	Reset Value: xxh
7:0	Floppy Port 3F2h Shadow. Last written value of I/O Port 3F2h. Required for support of FDC power On/Off and 0V S pend/Resume coherency.	
	This register is a copy of an I/O register which cannot safely be directly read. The value in this rewhen the register is being read. It is provided here to assist in a Suspend-to-Disk operation.	egister is not deterministic of
Index B5h	Floppy Port 3F7h Shadow Register (RO)	Reset Value: xxh
7:0	Floppy Port 3F7h Shadow. Last written value of I/O Port 3F7h. Required for support of FDC p pend/Resume coherency.	ower On/Off and 0V Sus-
	This register is a copy of an I/O register which cannot safely be directly read. The value in this rewhen the register is being read. It is provided here to assist in a Suspend-to-Disk operation.	egister is not deterministic of
Index B6h	Floppy Port 372h Shadow Register (RO)	Reset Value: xxh
7:0	Floppy Port 372h Shadow. Last written value of I/O Port 372h. Required for support of FDC p pend/Resume coherency.	ower On/Off and 0V Sus-
	This register is a copy of an I/O register which cannot safely be directly read. The value in this rewhen the register is being read. It is provided here to assist in a Suspend-to-Disk operation.	egister is not deterministic of
Index B7h	Floppy Port 377h Shadow Register (RO)	Reset Value: xxh
7:0	Floppy Port 377h Shadow. Last written value of I/O Port 377h. Required for support of FDC p pend/Resume coherency.	ower On/Off and 0V Sus-
	This register is a copy of an I/O register which cannot safely be directly read. The value in this re	egister is not deterministic of



DMA Shadow Register (RO)	Reset Value: xxh
DMA Shadow. This 8-bit port sequences through the following list of shadowed DMA Controller pointer starts at the first register in the list and continuing through the other registers in subsequence sequence. A write to this register resets the read sequence to the first register. Each shado contains the last data written to that location.	ent reads according to the
The read sequence for this register is: 1. DMA Channel 0 Mode Register 2. DMA Channel 1 Mode Register 3. DMA Channel 2 Mode Register 4. DMA Channel 3 Mode Register 5. DMA Channel 4 Mode Register 6. DMA Channel 5 Mode Register	
8. DMA Channel 7 Mode Register 9. DMA Channel Mask Register (bit 0 is channel 0 mask, etc.)	
	Reset Value: xxh
PIC Shadow. This 8-bit port sequences through the following list of shadowed Interrupt Controll pointer starts at the first register in the list and continuing through the other registers in subsequence sequence. A write to this register resets the read sequence to the first register. Each shado contains the last data written to that location.	ler registers. At power on, a lent reads according to the
The read sequence for this register is: 1. PIC1 ICW1 2. PIC1 ICW2 3. PIC1 ICW3 4. PIC1 ICW4 - Bits [7:5] of ICW4 are always 0. 5. PIC1 OCW2 - Bits [6:3] of OCW2 are always 0 (See Note). 6. PIC1 OCW3 - Bits [7:4] are 0 and bits [6:3] are 1. 7. PIC2 ICW1 8. PIC2 ICW2 9. PIC2 ICW2 10. PIC2 ICW4 - Bits [7:5] of ICW4 are always 0. 11. PIC2 OCW2 - Bits [6:3] of OCW2 are always 0 (See Note). 12. PIC2 OCW3 - Bits [7:4] are 0 and bits [6:3] are 1.	
Note: To restore OCW2 to the shadow register value, write the appropriate address twice. Fix value, then with the shadow register value ORed with C0h.	irst with the shadow registe
PIT Shadow Register (RO)	Reset Value: xxh
PIT Shadow. This 8-bit port sequences through the following list of shadowed Programmable Ir power on, a pointer starts at the first register in the list and continuing through the other register according to the read sequence. A write to this register resets the read sequence to the first reg in the sequence contains the last data written to that location.	s in subsequent reads
The read sequence for this register is: 1. Counter 0 LSB (least significant byte) 2. Counter 0 MSB 3. Counter 1 LSB 4. Counter 1 MSB 5. Counter 2 LSB 6. Counter 2 MSB 7. Counter 0 Command Word 8. Counter 1 Command Word 9. Counter 2 Command Word	
n h	DMA Shadow. This 8-bit port sequences through the following list of shadowed DMA Controller pointer starts at the first register in the list and continuing through the other registers in subsequence. A write to this register resets the read sequence to the first register. Each shad contains the last data written to that location. The read sequence for this register is: 1. DMA Channel 0 Mode Register 2. DMA Channel 1 Mode Register 3. DMA Channel 3 Mode Register 4. DMA Channel 3 Mode Register 5. DMA Channel 4 Mode Register 6. DMA Channel 5 Mode Register 7. DMA Channel 6 Mode Register 8. DMA Channel 7 Mode Register 8. DMA Channel 7 Mode Register 8. DMA Channel 7 Mode Register 8. DMA Channel 8 Mode Register 9. DMA Channel

Bits [7:6] of the command words are not used.



0001: 1 ms 0101: 5 ms 1001: 9 ms 1 0010: 2 ms 0110: 6 ms 1010: 10 ms 1	Reset Value: 00h vent occurs before the internal ip and CPU PLL to stabilize 100: 12 ms 101: 13 ms 110: 14 ms 111: 15 ms
The 4-bit field allows values from 0 to 15 ms. O000: 0 ms O110: 5 ms O110: 6 ms O110: 2 ms O110: 3 ms O110: 3 ms O110: 3 ms O110: 7 ms O110: 7 ms O110: 1 ms O110: 1 ms O110: 2 ms O110: 6 ms O110: 1 ms O110: 7 ms O110: 1 ms O110: 7 ms O110: 1 ms O110: 1 ms O110: 5 ms O110: 1 ms O110:	Reset Value: 00h vent occurs before the internal ip and CPU PLL to stabilize 100: 12 ms 101: 13 ms 110: 14 ms 111: 15 ms
7:4 PLL Delay. The programmed value in this field sets the delay (in milliseconds) after a break ex SUSP# signal is de-asserted to the GX1 module. This delay is designed to allow the clock chi before starting execution. This delay is only invoked if the STP_CLK bit was set. The 4-bit field allows values from 0 to 15 ms. 0000: 0 ms 0100: 4 ms 1000: 8 ms 1 0001: 1 ms 0101: 5 ms 1001: 9 ms 1 0010: 2 ms 0110: 6 ms 1010: 10 ms 1 0011: 3 ms 0111: 7 ms 1011: 11 ms 1 3:1 Reserved. Set to 0. CPU Clock Stop. 0: Normal internal SUSP#/SUSPA# handshake. 1: Full system Suspend. Note: This register configures the Core Logic module to support a 3V Suspend mode. Setting bit 0 cassert after the appropriate conditions, stopping the system clocks. A delay of 0-15 ms is program.	rent occurs before the internal ip and CPU PLL to stabilize 100: 12 ms 101: 13 ms 110: 14 ms 111: 15 ms
SUSP# signal is de-asserted to the GX1 module. This delay is designed to allow the clock chi before starting execution. This delay is only invoked if the STP_CLK bit was set. The 4-bit field allows values from 0 to 15 ms. 0000: 0 ms	p and CPU PLL to stabilize 100: 12 ms 101: 13 ms 110: 14 ms 111: 15 ms
0000: 0 ms	101: 13 ms 110: 14 ms 111: 15 ms
0010: 2 ms 0110: 6 ms 1010: 10 ms 1 0011: 3 ms 0111: 7 ms 1011: 11 ms 1 3:1 Reserved. Set to 0. CPU Clock Stop. 0: Normal internal SUSP#/SUSPA# handshake. 1: Full system Suspend. Note: This register configures the Core Logic module to support a 3V Suspend mode. Setting bit 0 cassert after the appropriate conditions, stopping the system clocks. A delay of 0-15 ms is program	110: 14 ms 111: 15 ms
0011: 3 ms 0111: 7 ms 1011: 11 ms 1 3:1 Reserved. Set to 0. CPU Clock Stop. 0: Normal internal SUSP#/SUSPA# handshake. 1: Full system Suspend. Note: This register configures the Core Logic module to support a 3V Suspend mode. Setting bit 0 cassert after the appropriate conditions, stopping the system clocks. A delay of 0-15 ms is program	111: 15 ms
3:1 Reserved. Set to 0. O CPU Clock Stop. O: Normal internal SUSP#/SUSPA# handshake. 1: Full system Suspend. Note: This register configures the Core Logic module to support a 3V Suspend mode. Setting bit 0 cassert after the appropriate conditions, stopping the system clocks. A delay of 0-15 ms is program	
O CPU Clock Stop. 0: Normal internal SUSP#/SUSPA# handshake. 1: Full system Suspend. Note: This register configures the Core Logic module to support a 3V Suspend mode. Setting bit 0 cassert after the appropriate conditions, stopping the system clocks. A delay of 0-15 ms is program	auses the SUSP_3V signal to
O: Normal internal SUSP#/SUSPA# handshake. 1: Full system Suspend. Note: This register configures the Core Logic module to support a 3V Suspend mode. Setting bit 0 cassert after the appropriate conditions, stopping the system clocks. A delay of 0-15 ms is program.	auses the SUSP_3V signal to
Note: This register configures the Core Logic module to support a 3V Suspend mode. Setting bit 0 cases assert after the appropriate conditions, stopping the system clocks. A delay of 0-15 ms is program	auses the SUSP_3V signal to
Note: This register configures the Core Logic module to support a 3V Suspend mode. Setting bit 0 cases assert after the appropriate conditions, stopping the system clocks. A delay of 0-15 ms is program	auses the SUSP_3V signal to
	mmable (bits [7:4]) to allow for
A write to the CPU Suspend Command register (F0 Index AEh) with bit 0 written as:	
0: Internal SUSP#/SUSPA# handshake occurs. The GX1 module is put into a low-power state, a stopped. When a break/resume event occurs, it releases the CPU halt condition.	and the system clocks are not
Internal SUSP#/SUSPA# handshake occurs and the SUSP_3V signal is asserted, thus invokin GX1 module and system clocks are stopped). When a break event occurs, the SUSP_3V signal programmed in bits [7:4] are invoked which allows the clock chip and GX1 module PLL to statinternal SUSP# signal. Page PRI	is de-asserted, the PLL delay bilize before de-asserting the
Index BDh-BFh Reserved	Reset Value: 00h
Index C0h-C3h User Defined Device 1 Base Address Register (R/W)	Reset Value: 00000000h
31:0 User Defined Device 1 Base Address. This 32-bit register supports power management (Traffor a PCMCIA slot or some other device in the system. The value in this register is used as the device trap/timer logic. The device can be memory or I/O mapped (configured in F0 Index CC)	e address comparator for the
The Core Logic module cannot snoop addresses on the Fast-PCI bus unless it actually claims and Idle timers cannot support power management of devices on the Fast-PCI bus.	s the cycle. Therefore, Traps
Index C4h-C7h User Defined Device 2 Base Address Register (R/W)	Reset Value: 00000000h
31:0 User Defined Device 2 Base Address. This 32-bit register supports power management (Traffor a PCMCIA slot or some other device in the system. The value in this register is used as the device trap/timer logic. The device can be memory or I/O mapped (configured in F0 Index CD	e address comparator for the
The Core Logic module cannot snoop addresses on the Fast-PCI bus unless it actually claims and Idle timers cannot support power management of devices on the Fast-PCI bus.	s the cycle. Therefore, Traps
Index C8h-CBh User Defined Device 3 Base Address Register (R/W)	Reset Value: 00000000h
31:0 User Defined Device 3 Base Address. This 32-bit register supports power management (Trafor a PCMCIA slot or some other device in the system. The value in this register is used as the device trap/timer logic. The device can be memory or I/O mapped (configured in F0 Index CE	e address comparator for the
The Core Logic module cannot snoop addresses on the Fast-PCI bus unless the it actually clarates and Idle timers cannot support power management of devices on the Fast-PCI bus.	aims the cycle. Therefore,



Table 6-29. F0: PCI Header/Bridge Configuration Registers for GPIO and LPC Support (Continued)

Index CCh	Description		
IIIuex CCII		User Defined Device 1 Control Register (R/W)	Reset Value: 00h
7	Memory or I/O Map	pped. Determines how User Defined Device 1 is mapped.	
	0: I/O.		
	1: Memory.		
6:0	Mask.		
	If bit $7 = 0 (I/O)$:		
		Disable write cycle tracking Enable write cycle tracking	
		Disable read cycle tracking Enable read cycle tracking	
		Mask for address bits A[4:0]	
	If bit 7 = 1 (Memory)		
		Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at	re ignored.
		nask bit means that the address bit is ignored for comparison.	
ndex CDh		User Defined Device 2 Control Register (R/W)	Reset Value: 00h
7	Memory or I/O Map 0: I/O	pped. determines how User Defined Device 2 is mapped.	
	1: Memory		
6:0	Mask.		
	If bit $7 = 0 (I/O)$:		
		Disable write cycle tracking Enable write cycle tracking	
		Disable read cycle tracking Enable read cycle tracking	
	Bits [4:0]	Mask for address bits A[4:0]	
	If bit 7 = 1 (Memory)):	
	Bits [6:0]	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at	re ignored.
	Bits [6:0]		re ignored.
ndex CEh	Bits [6:0] Note: A "1" in a m	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at	
ndex CEh	Bits [6:0] Note: A "1" in a m	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] an nask bit means that the address bit is ignored for comparison.	
	Bits [6:0] Note: A "1" in a m	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W)	
	Bits [6:0] Note: A "1" in a m Memory or I/O Map	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W)	
	Bits [6:0] Note: A "1" in a m Memory or I/O Map 0: I/O. 1: Memory. Mask.	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W)	
7	Bits [6:0] Note: A "1" in a m Memory or I/O Map 0: I/O. 1: Memory. Mask. If bit 7 = 0 (I/O):	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W) sped. Determines how User Defined Device 3 is mapped.	
7	Bits [6:0] Note: A "1" in a m Memory or I/O Map 0: I/O. 1: Memory. Mask. If bit 7 = 0 (I/O): Bit 6	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W) Oped. Determines how User Defined Device 3 is mapped. 0: Disable write cycle tracking 1: Enable write cycle tracking	
7	Bits [6:0] Note: A "1" in a m Memory or I/O Map 0: I/O. 1: Memory. Mask. If bit 7 = 0 (I/O): Bit 6 Bit 5	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W) oped. Determines how User Defined Device 3 is mapped. 0: Disable write cycle tracking 1: Enable write cycle tracking 0: Disable read cycle tracking 1: Enable read cycle tracking	
7	Bits [6:0] Note: A "1" in a m Memory or I/O Map 0: I/O. 1: Memory. Mask. If bit 7 = 0 (I/O): Bit 6 Bit 5 Bits [4:0]	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W) oped. Determines how User Defined Device 3 is mapped. 0: Disable write cycle tracking 1: Enable write cycle tracking 0: Disable read cycle tracking 1: Enable read cycle tracking Mask for address bits A[4:0]	
7	Bits [6:0] Note: A "1" in a m Memory or I/O Map 0: I/O. 1: Memory. Mask. If bit 7 = 0 (I/O): Bit 6 Bit 5 Bits [4:0] If bit 7 = 1 (Memory)	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W) ped. Determines how User Defined Device 3 is mapped. 0: Disable write cycle tracking 1: Enable write cycle tracking 0: Disable read cycle tracking 1: Enable read cycle tracking Mask for address bits A[4:0]	Reset Value: 00h
7	Bits [6:0] Note: A "1" in a m Memory or I/O Map 0: I/O. 1: Memory. Mask. If bit 7 = 0 (I/O): Bit 6 Bit 5 Bits [4:0] If bit 7 = 1 (Memory) Bits [6:0]	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W) Oped. Determines how User Defined Device 3 is mapped. O: Disable write cycle tracking 1: Enable write cycle tracking 0: Disable read cycle tracking 1: Enable read cycle tracking 1: Enable read cycle tracking Mask for address bits A[4:0] Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] and address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] and address memory bits A[15:9] (512 bytes min. and 64 KB max.)	Reset Value: 00h
6:0	Bits [6:0] Note: A "1" in a m Memory or I/O Map 0: I/O. 1: Memory. Mask. If bit 7 = 0 (I/O): Bit 6 Bit 5 Bits [4:0] If bit 7 = 1 (Memory) Bits [6:0]	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W) oped. Determines how User Defined Device 3 is mapped. 0: Disable write cycle tracking 1: Enable write cycle tracking 0: Disable read cycle tracking 1: Enable read cycle tracking Mask for address bits A[4:0] b: Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison.	Reset Value: 00h
7 6:0	Bits [6:0] Note: A "1" in a m Memory or I/O Map 0: I/O. 1: Memory. Mask. If bit 7 = 0 (I/O): Bit 6 Bit 5 Bits [4:0] If bit 7 = 1 (Memory) Bits [6:0]	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W) Oped. Determines how User Defined Device 3 is mapped. O: Disable write cycle tracking 1: Enable write cycle tracking 0: Disable read cycle tracking 1: Enable read cycle tracking Mask for address bits A[4:0] D: Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. Reserved	Reset Value: 00h
	Bits [6:0] Note: A "1" in a m Memory or I/O Map 0: I/O. 1: Memory. Mask. If bit 7 = 0 (I/O): Bit 6 Bit 5 Bits [4:0] If bit 7 = 1 (Memory) Bits [6:0] Note: A "1" in a m	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W) oped. Determines how User Defined Device 3 is mapped. 0: Disable write cycle tracking 1: Enable write cycle tracking 0: Disable read cycle tracking 1: Enable read cycle tracking 1: Enable read cycle tracking 1: Enable read cycle tracking 1: Mask for address bits A[4:0] 2: Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. Reserved Software SMI Register (WO)	re ignored. Reset Value: 00h Reset Value: 00h
7 6:0	Bits [6:0] Note: A "1" in a m Memory or I/O Map 0: I/O. 1: Memory. Mask. If bit 7 = 0 (I/O): Bit 6 Bit 5 Bits [4:0] If bit 7 = 1 (Memory) Bits [6:0] Note: A "1" in a m	Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. User Defined Device 3 Control Register (R/W) Oped. Determines how User Defined Device 3 is mapped. O: Disable write cycle tracking 1: Enable write cycle tracking 0: Disable read cycle tracking 1: Enable read cycle tracking Mask for address bits A[4:0] D: Mask for address memory bits A[15:9] (512 bytes min. and 64 KB max.) A[8:0] at mask bit means that the address bit is ignored for comparison. Reserved	re ignored. Reset Value: 00h Reset Value: 00h



Bit	Description	
Index ECh	Timer Test Register (R/W)	Reset Value: 00h
7:0	Timer Test Value. The Timer Test register is intended only for test and debug purposes. It is not intended tional timebases. For normal operation, never write to this register.	ended for setting opera
Index EDh	-F3h Reserved	Reset Value: 00h
Index F4h	Second Level PME/SMI Status Register 1 (RC)	Reset Value: 00h
The bits in	this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset	00h/02h[0].
Reading th	is register clears the status at both the second and top levels.	
	"Mirror" version of this register exists at F0 Index 84h. If the value of the register must be read withod consequently de-asserting SMI), F0 Index 84h can be read instead.	ut clearing the SMI
7:3	Reserved. Reads as 0.	
2	$\textbf{GPWIO2 SMI Status.} \ \textbf{Indicates whether or not an SMI was caused by a transition on the GPWIO2} \ \textbf{g}$	oin.
	0: No.	
	1: Yes.	
	To enable SMI generation:	
	 Ensure that GPWIO2 is enabled as an input: F1BAR1+I/O Offset 15h[2] = 0. Set F1BAR1+I/O Offset 15h[6] = 1 to allow SMI generation. 	
1	GPWIO1 SMI Status. Indicates whether or not an SMI was caused by a transition on the GPWIO1 p	oin.
	0: No.	
	1: Yes.	
	To enable SMI generation:	
	 Ensure that GPWIO1 is enabled as an input: F1BAR1+I/O Offset 15h[1] = 0. Set F1BAR1+I/O Offset 15h[5] to 1 to allow SMI generation. 	
0	GPWIO0 SMI Status. Indicates whether or not an SMI was caused by a transition on the GPWIO0 p	oin.
	0: No	
	1: Yes	
	To enable SMI generation:	
	 Ensure that GPWIO0 is enabled as an input: F1BAR1+I/O Offset 15h[0] = 0. Set F1BAR1+I/O Offset 15h[4] to 1 to allow SMI generation. 	
Index F5h	Second Level PME/SMI Status Register 2 (RC)	Reset Value: 00h
The bits in	this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset	00h/02h[0].
Reading th	is register clears the status at both the second and top levels.	
	"Mirror" version of this register exists at F0 Index 85h. If the value of the register must be read withod consequently de-asserting SMI), F0 Index 85h can be read instead.	ut clearing the SMI
7	Video Idle Timer SMI Status. Indicates whether or not an SMI was caused by expiration of Video Idle ter, (F0 Index A6h).	dle Timer Count Regis-
	0: No.	
	1: Yes.	
	To enable SMI generation, set F0 Index 81h[7] = 1.	
6	User Defined Device Idle Timer 3 (UDEF3) SMI Status. Indicates whether or not an SMI was cause Defined Device 3 (UDEF3) Idle Timer Count Register (F0 Index A4h).	ed by expiration of Use
	0: No.	
	1: Yes.	
	To enable SMI generation, set F0 Index 81h[6] = 1.	
5	User Defined Device Idle Timer 2 (UDEF2) SMI Status. Indicates whether or not an SMI was cause Defined Device 2 (UDEF2) Idle Timer Count Register (F0 Index A2h).	ed by expiration of Use
	0: No.	
	4. 77	
	1: Yes.	



Bit	Description
4	User Defined Device Idle Timer 1 (UDEF1) SMI Status. Indicates whether or not an SMI was caused by expiration of User Defined Device 1 (UDEF1) Idle Timer Count Register (F0 Index A0h).
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 81h[4] = 1.
3	Keyboard/Mouse Idle Timer SMI Status. Indicates whether or not an SMI was caused by expiration of Keyboard/ Mouse Idle Timer Count Register (F0 Index 9Eh).
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 81h[3] = 1.
2	Parallel/Serial Idle Timer SMI Status. Indicates whether or not an SMI was caused by expiration of Parallel/Serial Port Idle Timer Count Register (F0 Index 9Ch).
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 81h[2] = 1.
1	Floppy Disk Idle Timer SMI Status. Indicates whether or not an SMI was caused by expiration of Floppy Disk Idle Timer Count Register (F0 Index 9Ah).
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 81h[1] = 1.
0	Hard Disk Idle Timer SMI Status. Indicates whether or not an SMI was caused by expiration of Hard Disk Idle Timer Count
	Register (F0 Index 98h).
	Register (F0 Index 98h). 0: No.
	0: No.
Index F6h	0: No. 1: Yes.
	0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1.
The bits in	0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h
The bits in Reading th A read-only	0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0].
The bits in Reading th A read-only	0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0]. is register clears the status at both the second and top levels. y "Mirror" version of this register exists at F0 Index 86h. If the value of the register must be read without clearing the SMI
The bits in Reading th A read-only source (and	0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0]. is register clears the status at both the second and top levels. y "Mirror" version of this register exists at F0 Index 86h. If the value of the register must be read without clearing the SMI d consequently de-asserting SMI), F0 Index 86h can be read instead. Video Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the Video I/O
The bits in Reading th A read-only source (and	0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0]. is register clears the status at both the second and top levels. y "Mirror" version of this register exists at F0 Index 86h. If the value of the register must be read without clearing the SMI d consequently de-asserting SMI), F0 Index 86h can be read instead. Video Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the Video I/O Trap.
The bits in Reading th A read-only source (and	0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0]. is register clears the status at both the second and top levels. / "Mirror" version of this register exists at F0 Index 86h. If the value of the register must be read without clearing the SMI d consequently de-asserting SMI), F0 Index 86h can be read instead. Video Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the Video I/O Trap. 0: No.
The bits in Reading th A read-only source (and	0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0]. is register clears the status at both the second and top levels. "Mirror" version of this register exists at F0 Index 86h. If the value of the register must be read without clearing the SMI d consequently de-asserting SMI), F0 Index 86h can be read instead. Video Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the Video I/O Trap. 0: No. 1: Yes.
The bits in Reading th A read-only source (and	0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0]. is register clears the status at both the second and top levels. y "Mirror" version of this register exists at F0 Index 86h. If the value of the register must be read without clearing the SMI d consequently de-asserting SMI), F0 Index 86h can be read instead. Video Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the Video I/O Trap. 0: No. 1: Yes. To enable SMI generation, set F0 Index 82h[7] = 1.
The bits in Reading th A read-only source (and 7	0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0]. is register clears the status at both the second and top levels. "Mirror" version of this register exists at F0 Index 86h. If the value of the register must be read without clearing the SMI d consequently de-asserting SMI), F0 Index 86h can be read instead. Video Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the Video I/O Trap. 0: No. 1: Yes. To enable SMI generation, set F0 Index 82h[7] = 1. Reserved. Reads as 0. Secondary Hard Disk Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to
The bits in Reading th A read-only source (and	0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0]. is register clears the status at both the second and top levels. "Mirror" version of this register exists at F0 Index 86h. If the value of the register must be read without clearing the SMI d consequently de-asserting SMI), F0 Index 86h can be read instead. Video Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the Video I/O Trap. 0: No. 1: Yes. To enable SMI generation, set F0 Index 82h[7] = 1. Reserved. Reads as 0. Secondary Hard Disk Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the secondary hard disk.
The bits in Reading th A read-only source (and	O: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0]. is register clears the status at both the second and top levels. / "Mirror" version of this register exists at F0 Index 86h. If the value of the register must be read without clearing the SMI deconsequently de-asserting SMI), F0 Index 86h can be read instead. Video Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the Video I/O Trap. O: No. 1: Yes. To enable SMI generation, set F0 Index 82h[7] = 1. Reserved. Reads as 0. Secondary Hard Disk Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the secondary hard disk. O: No.
The bits in Reading th A read-only source (and 7	O: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0]. is register clears the status at both the second and top levels. "Mirror" version of this register exists at F0 Index 86h. If the value of the register must be read without clearing the SMI d consequently de-asserting SMI), F0 Index 86h can be read instead. Video Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the Video I/O Trap. O: No. 1: Yes. To enable SMI generation, set F0 Index 82h[7] = 1. Reserved. Reads as 0. Secondary Hard Disk Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the secondary hard disk. O: No. 1: Yes.
The bits in Reading th A read-only source (and 7	O: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0]. is register clears the status at both the second and top levels. / "Mirror" version of this register exists at F0 Index 86h. If the value of the register must be read without clearing the SMI d consequently de-asserting SMI), F0 Index 86h can be read instead. Video Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the Video I/O Trap. 0: No. 1: Yes. To enable SMI generation, set F0 Index 82h[7] = 1. Reserved. Reads as 0. Secondary Hard Disk Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the secondary hard disk. 0: No. 1: Yes. To enable SMI generation, set F0 Index 83h[6] = 1. Secondary Hard Disk Idle Timer SMI Status. Indicates whether or not an SMI was caused by expiration of Secondary
The bits in Reading th A read-only source (and 7	0: No. 1: Yes. To enable SMI generation, set F0 Index 81h[0] = 1. Second Level PME/SMI Status Register 3 (RC) Reset Value: 00h this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0]. is register clears the status at both the second and top levels. / "Mirror" version of this register exists at F0 Index 86h. If the value of the register must be read without clearing the SMI dconsequently de-asserting SMI), F0 Index 86h can be read instead. Video Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the Video I/O Trap. 0: No. 1: Yes. To enable SMI generation, set F0 Index 82h[7] = 1. Reserved. Reads as 0. Secondary Hard Disk Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the secondary hard disk. 0: No. 1: Yes. To enable SMI generation, set F0 Index 83h[6] = 1. Secondary Hard Disk Idle Timer SMI Status. Indicates whether or not an SMI was caused by expiration of Secondary Hard Disk Idle Timer Count register (F0 Index ACh).

Revision 5.1

Table 6-29. F0: PCI Header/Bridge Configuration Registers for GPIO and LPC Support (Continued)

Bit	Description
3	Keyboard/Mouse Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the keyboard or mouse.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 82h[3] = 1.
2	Parallel/Serial Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to either the serial or parallel ports.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 82h[2] =1.
1	Floppy Disk Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the floppy disk.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 82h[1] = 1.
0	Primary Hard Disk Access Trap SMI Status. Indicates whether or not an SMI was caused by a trapped I/O access to the primary hard disk.
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 82h[0] = 1.

Index F7h

Second Level PME/SMI Status Register 4 (RC)

Reset Value: 00h

The bits in this register contain second level status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[0].

Reading this register clears the status at both the second and top levels except for bit 7 which has a third level of status reporting at F0BAR0+I/O 0Ch/1Ch.

A read-only "Mirror" version of this register exists at F0 Index 87h. If the value of the register must be read without clearing the SMI source (and consequently de-asserting SMI), F0 Index 87h can be read instead.

- GPIO Event SMI Status (Read Only, Read does not Clear). Indicates whether or not an SMI was caused by a transition of any of the GPIOs (GPIO47-GPIO32 and GPIO15-GPIO0).
 0: No.
 1: Yes.
 To enable SMI generation, set F1BAR1+I/O Offset 0Ch[0] = 0.
 F0BAR0+I/O Offset 08h/18h selects which GPIOs are enabled to generate a PME and setting F1BAR1+I/O Offset 0Ch[0] = 0 enables the PME to generate an SMI. In addition, the selected GPIO must be enabled as an input (F0BAR0+I/O Offset 20h and 24h).
 The next level (third level) of SMI status is at F0BAR0+I/O 0Ch/1Ch.
 Thermal Override SMI Status. Indicates whether or not an SMI was caused by an assertion of the THRM#.
 0: No.
 - 5:4 **Reserved.** Read as 0.

1: Yes.

- 3 SIO PWUREQ SMI Status. Indicates whether or not an SMI was caused by a power-up event from the SIO.
 - 0: No.
 - 1: Yes.

A power-up event is defined as any of the following events/activities:

- RI2#
- SDATA_IN2
- IRRX1 (CEIR)
- To enable SMI generation, set F1BAR1+I/O Offset 0Ch[0] = 0.

To enable SMI generation set F0 Index 83h[4] = 1.



Bit	Description	
2	Codec SDATA_IN SMI Status. Indicates whether or not an SMI was caused by AC97 Codec SDATA_IN.	producing a positive edge on
	0: No.	
	1: Yes.	
	To enable SMI generation, set F0 Index 80h[5] = 1.	
1	RTC Alarm (IRQ8#) SMI Status. Indicates whether or not an SMI was caused by an RTC inte	errupt.
	0: No.	
	1: Yes.	
	This SMI event can only occur while in 3V Suspend and an RTC interrupt occurs and F1BAR1	+I/O Offset $0Ch[0] = 0$.
0	ACPI Timer SMI Status. Indicates whether or not an SMI was caused by an ACPI Timer (F1B F1BAR1+I/O Offset 1Ch) MSB toggle.	BAR0+I/O Offset 1Ch or
	0: No.	
	1: Yes.	
	To enable SMI generation, set F0 Index 83h[5] = 1.	
dex F8h	n-FFh Reserved	Reset Value: 00h



6.4.1.1 GPIO Support Registers

F0 Index 10h, Base Address Register 0 (F0BAR0) points to the base address of where the GPIO runtime and configu-

ration registers are located. Table 6-29 gives the bit formats of I/O mapped registers accessed through F0BAR0.

Table 6-30. F0BAR0+I/O Offset: GPIO Configuration Registers

Bit	Description	1			
Offset 00h	h-03h GPD00 — GPIO Data Out 0 Register (R/W) Reset Value: FFFFFFFh				
31:0	mines the va written data	Out. Bits [31:0] of this register correspond to GPIO31-GPIO0 signals, respalue driven on the corresponding GPIO signal when its output buffer is ena unless the bit is locked by the GPIO Configuration register Lock bit (F0BAI ne value, regardless of the signal value and configuration.	bled. Writing to the bit latches the		
	0: Correspo	onding GPIO signal is driven to low when output enabled.			
	1: Correspo	onding GPIO signal is driven or released to high (according to buffer type a abled.	nd static pull-up selection) when out-		
Offset 04h	-07h	GPDI0 — GPIO Data In 0 Register (RO)	Reset Value: FFFFFFFh		
31:0		In. Bits [31:0] of this register correspond to GPIO31-GPIO0 signals, respectorresponding GPIO signal, regardless of the signal configuration and the C			
	Writes to thi	s register are ignored.			
	0: Correspo	onding GPIO signal level is low.			
	1: Correspo	onding GPIO signal level is high.			
Offset 08h	-0Bh	GPIEN0 — GPIO Interrupt Enable 0 Register (R/W)	Reset Value: 00000000h		
31:16	Reserved.	Must be set to 0.			
15:0	allows PME	r Management Event (PME) Enable. Bits [15:0] correspond to GPIO15-G generation by the corresponding GPIO signal.	PIO0 signals, respectively. Each bit		
		PME generation.			
		PME generation.			
	,	All of the enabled GPIO PMEs are always reported at F1BAR1+I/O Offse	• •		
	2)	Any enabled GPIO PME can be selected to generate an SCI or SMI at F1	BAR1+I/O Offset 0Ch[0].		
		If SCI is selected, then the individually selected GPIO PMEs are globally F1BAR1+I/O Offset 12h[3] and the status is reported at F1BAR1+I/O Offset			
		If SMI is selected, the individually selected GPIO PMEs generate an SMI F1BAR0+I/O Offset 00h/02h[0].	and the status is reported at		
Offset 0Ch	-0Fh	GPST0 — GPIO Status 0 Register (R/W1C)	Reset Value: 00000000h		
31:16	Reserved.	Must be set to 0.			
15:0	the edge (ris	s. Bits [15:0] correspond to GPIO15-GPIO0 signals, respectively. Each bit sing/falling on the GPIO signal) that is programmed in F0BAR0+I/O Offset 2 Offset 08h is set, this edge generates a PME.			
	0: No active edge detected since the bit was last cleared.				
	1: Active edge detected.				
	Writing 1 to the a Status bit clears it to 0.				
		nird level of SMI status reporting to the second level at F0 Index 87h/F7h[7)2h[0]. Clearing the third level also clears the second and top levels.	and the top level at F1BAR0+I/O		
		second level of SCI status reporting to the top level at F1BAR1+Offset 10h[s level and the top level (i.e., the top level is not automatically cleared when			



Table 6-30. F0BAR0+I/O Offset: GPIO Configuration Registers (Continued)

Bit	Description				
Offset 10h	n-13h	GPDO1 — GPIO Data Out 1 Register (R/W)	Reset Value: FFFFFFFh		
31:0	determines the written	Out. Bits [31:0] of this register correspond to GPIO63-GPIO32 signals, respective value driven on the corresponding GPIO signal when its output buffer is data unless the bit is locked by the GPIO Configuration register Lock bit (FOE rns the value, regardless of the signal value and configuration.	enabled. Writing to the bit latches		
	0: Corresp	onding GPIO signal driven to low when output enabled.			
	1: Corresp enabled	onding GPIO signal driven or released to high (according to buffer type and s l.	tatic pull-up selection) when outpu		
Offset 14h	n-17h	GPDI1 — GPIO Data In 1 Register (RO)	Reset Value: FFFFFFFh		
31:0	value of the	In. Bits [31:0] of this register correspond to GPIO63-GPIO32 signals, respect corresponding GPIO signal, regardless of the signal configuration and the GI Writes to this register are ignored.			
	0: Corresp	onding GPIO signal level low.			
	1: Corresp	onding GPIO signal level high.			
Offset 18h	n-1Bh	GPIEN1 — GPIO Interrupt Enable 1 Register (R/W)	Reset Value: 00000000h		
31:16	Reserved.	Must be set to 0.			
15:0		er Management Event (PME) Enable. Bits [15:0] of this register correspond . Each bit allows PME generation by the corresponding GPIO signal.	to GPIO47-GPIO32 signals,		
	0: Disable	PME generation.			
	1: Enable	PME generation.			
	Notes: 1)	All of the enabled GPIO PMEs are always reported at F1BAR1+I/O Offset	10h[3].		
	2)	Any enabled GPIO PME can be selected to generate an SCI or SMI at F1E	BAR1+I/O Offset 0Ch[0].		
		If SCI is selected, the individually selected GPIO PMEs are globally enable O Offset 12h[3] and the status is reported at F1BAR1+I/O Offset 10h[3].	ed for SCI generation at F1BAR1+		
		If SMI is selected, the individually selected GPIO PMEs generate an SMI a F1BAR0+I/O Offset 00h/02h[0].	and the status is reported at		
Offset 1CI	h-1Fh	GPST1 — GPIO Status 1 Register (R/W1C)	Reset Value: 00000000h		
31:16	Reserved.	Must be set to 0.			
15:0	GPIO Status . Bits [15:0] correspond to GPIO47-GPIO32 signals, respectively. Each bit reports a 1 when hardware detects the edge (rising/falling on the GPIO signal) that is programmed in F0BAR0+I/O Offset 24h[5]. If the corresponding bit in F0BAR0+I/O Offset 18h is set, this edge generates a PME.				
	0: No activ	ve edge detected since the bit was last cleared.			
	1: Active edge detected.				
	Writing 1 to the a Status bit clears it to 0.				
	This is the third level of SMI status reporting to the second level at F0 Index 87h/F7h[7] and the top level at F1BAR0+I/O Offset 00h/02h[0]. Clearing the third level also clears the second and top levels.				
		second level of SCI status reporting to the top level at F1BAR1+Offset 10h[3] s level and the top level (i.e., the top level is not automatically cleared when a	•		
Offset 20h	n-23h	GPIO Signal Configuration Select Register (R/W)	Reset Value: 00000000h		
31:6	Decembed	Must be set to 0.			



Table 6-30. F0BAR0+I/O Offset: GPIO Configuration Registers (Continued)

Bit	Description			
5:0	Signal Select. Selects the GPIO signal to be configured in the Bank selected via bit 5 setting (i.e., Bank 0 or Bank 1). See Table 4-2 on page 88 for GPIO ball muxing options. GPIOs without an associated ball number are not available externally.			
	Bank 0 000000 = GPIO0 (EBGA: H1 / TEPBGA: D11) 000001 = GPIO1 (EBGA: H2, AL12 / TEPBGA: D10, N30) 000010 = GPIO2 000011 = GPIO3 000100 = GPIO4 000101 = GPIO5 000110 = GPIO6 (EBGA: AH3 / TEPBGA: D28) 000111 = GPIO7 (EBGA: AH4 / TEPBGA: C30) 001000 = GPIO8 (EBGA: AJ2 / TEPBGA: C31)	010000 = GPIO16 (EBGA: AL15 / TEPBGA: V31) 010001 = GPIO17 (EBGA: J4 / TEPBGA: A10) 010010 = GPIO18 (EBGA: A28 / TEPBGA: AG1) 010011 = GPIO19 (EBGA: H4 / TEPBGA: C9) 010100 = GPIO20 (EBGA: H3, AJ13 / TEPBGA: A9, N31) 010101 = GPIO21 010110 = GPIO22 010111 = GPIO23 011000 = GPIO24		
	001001 = GPIO9 (EBGA: AG4 / TEPBGA: C28) 001010 = GPIO10 (EBGA: AJ1 / TEPBGA: B29) 001011 = GPIO11 (EBGA: H30 / TEPBGA: AJ8) 001100 = GPIO12 (EBGA: AJ12 / TEPBGA: N29) 001101 = GPIO13 (EBGA: AL11 / TEPBGA: M29) 001110 = GPIO14 (EBGA: F1 / TEPBGA: D9) 001111 = GPIO15 (EBGA: G3 / TEPBGA: A8)	011001 = GPIO25 011010 = GPIO26 011011 = GPIO27 011100 = GPIO28 011101 = GPIO29 011110 = GPIO30 011111 = GPIO31		
	Bank 1 100000 = GPIO32 (EBGA: AJ11 / TEPBGA: M28) 100001 = GPIO33 (EBGA: AL10 / TEPBGA: L31) 100010 = GPIO34 (EBGA: AK10 / TEPBGA: L30) 100011 = GPIO35 (EBGA: AJ10 / TEPBGA: L29) 100100 = GPIO36 (EBGA: AJ9 / TEPBGA: L28) 100101 = GPIO37 (EBGA: AK9 / TEPBGA: K31) 100110 = GPIO38 (EBGA: AJ9 / TEPBGA: K28) 100111 = GPIO39 (EBGA: AJ9 / TEPBGA: K28) 100101 = GPIO40 (EBGA: AL8 / TEPBGA: Y3) 101000 = GPIO40 (EBGA: A21 / TEPBGA: Y3) 101001 = GPIO41 (EBGA: C19 / TEPBGA: W4) 101010 = GPIO42 101011 = GPIO43 101100 = GPIO44 101101 = GPIO45 101111 = GPIO46 101111 = GPIO47	110000 = GPIO48 110001 = GPIO49 110010 = GPIO50 110011 = GPIO51 110100 = GPIO52 110101 = GPIO53 110110 = GPIO54 110111 = GPIO55 111000 = GPIO56 111001 = GPIO57 111010 = GPIO58 111011 = GPIO59 111101 = GPIO60 111101 = GPIO60 111111 = GPIO62 111111 = GPIO63 (Note)		
	Note: GPIO63 can be used to generate the PWRBTN# ir "Power Management Interface Signals" on page 80	nput signal. See PWRBTN# signal description in Section 3.4.15		
Offset 24h				
This registe (above).	er is used to indicate configuration for the GPIO signal that is s	selected in the GPIO Signal Configuration Select Register		
01		ly applicable on GPIO0-GPIO15 signals (Bank $0=00000$ to 0000 to 01111). The remaining GPIOs (GPIO16-GPIO31 and have no function and read 0 .		
31:7	Reserved. Must be set to 0.			
6	PME Debounce Enable. Enables/disables IRQ debounce (0: Disable.1: Enable. (Default).			
	See the note in the description of this register for more infor			
5	0: Falling edge or low level input. (Default)	PME from the selected GPIO signal (falling/low or rising/high).		
	Rising edge or high level input. See the note in the description of this register for more information about the default value of this bit.			



Table 6-30. F0BAR0+I/O Offset: GPIO Configuration Registers (Continued)

Bit	Description
4	PME Edge/Level Select. Selects the type (edge or level) of the signal that issues a PME from the selected GPIO signal.
	0: Edge input. (Default)
	1: Level input.
	For normal operation, always set this bit to 0 (edge input). Erratic system behavior results if this bit is set to 1.
	See the note in the description of this register for more information about the default value of this bit.
3	Lock. This bit locks the selected GPIO signal. Once this bit is set to 1 by software, it can only be cleared to 0 by power on reset or by WATCHDOG reset.
	0: No effect. (Default)
	1: Direction, output type, pull-up and output value locked.
2	Pull-Up Control. Enables/disables the internal pull-up capability of the selected GPIO signal. It supports open-drain output signals with internal pull-ups and TTL input signals.
	0: Disable.
	1: Enable. (Default)
	Bits [1:0] of this register must = 01 for this bit to have effect.
1	Output Type. Controls the output buffer type (open-drain or push-pull) of the selected GPIO signal.
	0: Open-drain. (Default)
	1: Push-pull.
	Bit 0 of this register must be set to 1 for this bit to have effect.
0	Output Enable. Indicates the GPIO signal output state. It has no effect on input.
	0: TRI-STATE - Setting for GPIO to function as an input only. (Default)
	1: Output enabled.
Offset 28I	n-2Bh GPIO Reset Control Register (R/W) Reset Value: 00000000h
31:1	Reserved. Must be set to 0.
0	GPIO Reset. Reset the GPIO logic.
	0: Disable.
	1: Enable.
	Write 0 to clear.
	This bit is level-sensitive and must be cleared after the reset is enabled (normal operation requires this bit to be 0).



6.4.1.2 LPC Support Registers

F0 Index 14h, Base Address Register 1 (F0BAR1) points to the base address of the register space that contains the configuration registers for LPC support. Table 6-31 gives the bit formats of the I/O mapped registers accessed through F0BAR1.

Revision 5.1

The LPC Interface supports all features described in the LPC bus specification 1.0, with the following exceptions:

- Only 8- or 16-bit DMA, depending on channel number. Does not support the optional larger transfer sizes.
- Only one external DRQ pin.

Table 6-31. F0BAR1+I/O Offset: LPC Interface Configuration Registers

Bit	Description	
Offset 00	Dh-03h SERIRQ_SRC — Serial IRQ Source Register (R/W) Resc	et Value: 00000000h
ti	Some signals require additional programming to make them externally accessible. See Table 4-2 "Multiption, and Base Address Registers" on page 88 for pin multiplexing details and Table 3-6 "Strap Open LPC_ROM strap information.	
31:21	Reserved.	
20	INTD Source. Selects the interface source of the INTD# signal.	
	0: PCI - INTD# (EBGA ball B22; TEPBGA ball AA2).	
	1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31).	
19	INTC Source. Selects the interface source of the INTC# signal.	
	0: PCI - INTC# (EBGA ball H4; TEPBGA ball C9).	
	1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31).	
18	INTB Source. Selects the interface source of the INTB# signal.	
	0: PCI - INTB# (EBGA ball AF1; TEPBGA ball C26).	
	1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31).	
17	INTA Source. Selects the interface source of the INTA# signal.	
	0: PCI - INTA# (EBGA ball AE3; TEPBGA ball D26).	
	1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31).	
16	Reserved. Set to 0.	
15	IRQ15 Source. Selects the interface source of the IRQ15 signal.	
	0: ISA - IRQ15 (EBGA ball H30; TEPBGA ball AJ8).	
	1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31).	
14	IRQ14 Source. Selects the interface source of the IRQ14 signal.	
	0: ISA - IRQ14 (EBGA ball D25; TEPBGA ball AF1).	
	1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31).	
13	IRQ13 Source. Selects the interface source of the internal IRQ13 signal.	
	0: ISA - IRQ13 internal signal. (An input from the CPU indicating that a floating point error has been nal INTR should be asserted.)	detected and that inter-
	1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31).	
12	IRQ12 Source. Selects the interface source of the IRQ12 signal.	
	0: ISA - IRQ12 (unavailable externally).	
	1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31).	
11	IRQ11 Source. Selects the interface source of the IRQ11 signal.	
	0: ISA - IRQ11 (unavailable externally).	
	1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31).	
10	IRQ10 Source. Selects the interface source of the IRQ10 signal.	
	0: ISA - IRQ10 (unavailable externally).	
	1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31).	
9	IRQ9 Source. Selects the interface source of the IRQ9 signal.	
	0: ISA - IRQ9 (EBGA ball C22; TEPBGA ball AA3).	
	1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31).	



8 IRQ8# Source. Selects the interface source of the IRQ8# signal. 0: ISA - IRQ8# internal signal. (Connected to internal RTC.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 7 IRQ7 Source. Selects the interface source of the IRQ7 signal. 0: ISA - IRQ7 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 6 IRQ6 Source. Selects the interface source of the IRQ6 signal. 0: ISA - IRQ6 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 5 IRQ5 Source. Selects the interface source of the IRQ5 signal. 0: ISA - IRQ6 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 4 IRQ4 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ3 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball	
1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 7 IRQ7 Source. Selects the interface source of the IRQ7 signal. 0: ISA - IRQ7 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 6 IRQ6 Source. Selects the interface source of the IRQ6 signal. 0: ISA - IRQ6 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 5 IRQ5 Source. Selects the interface source of the IRQ5 signal. 0: ISA - IRQ5 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 4 IRQ4 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). O IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). O IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ (LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 spolarity selection. 0: Active high. 1: Active low. 19 INTC# Polarity, If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
Texas Texa	
0: ISA - IRQ7 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 6: IRQ6 Source. Selects the interface source of the IRQ6 signal. 0: ISA - IRQ6 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 5: IRQ6 Source. Selects the interface source of the IRQ6 signal. 0: ISA - IRQ5 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 4: IRQ4 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3: IRQ3 Source. Selects the interface source of the IRQ3 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2: Reserved. Must be set to 0. 1: IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 1: LPC - SERIRQ (EBG	
1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 6 IRQ6 Source. Selects the interface source of the IRQ6 signal. 0: ISA - IRQ6 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 5 IRQ5 Source. Selects the interface source of the IRQ5 signal. 0: ISA - IRQ6 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 4 IRQ4 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offiset 04h-07h IRQ1 Selects the interface source of the IRQ0 signal. 0: ISA - IRQ1 (EBGA ball AL8; TEPBGA ball J31). Offiset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 10 IRQ1 Source. Selects the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 6 IRQ6 Source. Selects the interface source of the IRQ6 signal. 0: ISA - IRQ6 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 5 IRQ5 Source. Selects the interface source of the IRQ5 signal. 0: ISA - IRQ6 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 4 IRQ4 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offiset 04h-07h IRQ1 Selects the interface source of the IRQ0 signal. 0: ISA - IRQ1 (EBGA ball AL8; TEPBGA ball J31). Offiset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 10 IRQ1 Source. Selects the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
0: ISA - IRQ6 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 5 IRQ5 Source. Selects the interface source of the IRQ5 signal. 0: ISA - IRQ5 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 4 IRQ4 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ3 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUT0, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 5 IRQ5 Source. Selects the interface source of the IRQ5 signal. 0: ISA - IRQ5 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 4 IRQ4 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ3 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Office IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUT0, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offiset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 10 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
IRQ5 Source. Selects the interface source of the IRQ5 signal. O: ISA - IRQ5 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 4	
5 IRQ5 Source. Selects the interface source of the IRQ5 signal. 0: ISA - IRQ5 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 4 IRQ4 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ3 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ0 Internal signal. (Connected to OUTO, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 20 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 4 IRQ4 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ3 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ0 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: ISA - IRQ0 Internal signal. (Connected to OUT0, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 10 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows sepolarity selection. 0: Active high. 1: Active low.	
4 IRQ4 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ3 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUTO, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 10 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low. 19 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
4 IRQ4 Source. Selects the interface source of the IRQ4 signal. 0: ISA - IRQ4 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ3 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUTO, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 10 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low. 19 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ3 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUT0, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 20 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low. 19 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 3 IRQ3 Source. Selects the interface source of the IRQ3 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUT0, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 20 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low. 19 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
IRQ3 Source. Selects the interface source of the IRQ3 signal. 0: ISA - IRQ3 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUTo, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 20 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows sopolarity selection. 0: Active high. 1: Active low. 19 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows sopolarity selection. 0: Active high. 1: Active low.	
1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUT0, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (RW) Reset Value: 000000 31:21 Reserved. 20 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low. INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUT0, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 1NTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows selection. 0: Active high. 1: Active low. 19 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows selection. 0: Active high. 1: Active low.	
2 Reserved. Must be set to 0. 1 IRQ1 Source. Selects the interface source of the IRQ1 signal. 0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUT0, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 1NTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows selection. 0: Active high. 1: Active low. 19 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows selection. 0: Active high. 1: Active low.	
0: ISA - IRQ1 (unavailable externally). 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0: IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUT0, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 20 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low. 19 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). 0 IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUT0, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 20 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows selection. 0: Active high. 1: Active low. INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows selection. 0: Active high. 1: Active low.	
IRQ0 Source. Selects the interface source of the IRQ0 signal. 0: ISA - IRQ0 Internal signal. (Connected to OUT0, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 20 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low. INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
0: ISA - IRQ0 Internal signal. (Connected to OUT0, System Timer, of the internal 8254 PIT.) 1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 20 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low. INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
1: LPC - SERIRQ (EBGA ball AL8; TEPBGA ball J31). Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 20 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low. 19 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
Offset 04h-07h SERIRQ_LVL — Serial IRQ Level Control Register (R/W) Reset Value: 000000 31:21 Reserved. 20 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low. 19 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
31:21 Reserved. 20 INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low. 19 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
INTD# Polarity. If LPC is selected as the interface source for INTD# (F0BAR1+I/O Offset 00h[20] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low. INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	00000h
polarity selection. 0: Active high. 1: Active low. INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	
1: Active low. 19 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. 0: Active high. 1: Active low.	ws signal
 INTC# Polarity. If LPC is selected as the interface source for INTC# (F0BAR1+I/O Offset 00h[19] = 1), this bit allows spolarity selection. O: Active high. 1: Active low. 	
polarity selection. 0: Active high. 1: Active low.	
1: Active low.	ws signal
40 INTO # Delevity, If I DO is selected as the interference for INTO # (FOR ADA 1/0 Off a collision of the interference for IN	
18 INTB# Polarity. If LPC is selected as the interface source for INTB# (F0BAR1+I/O Offset 00h[18] = 1), this bit allows s polarity selection.	ws signal
0: Active high. 1: Active low.	
17 INTA# Polarity. If LPC is selected as the interface source for INTA# (F0BAR1+I/O Offset 00h[17] = 1), this bit allows s polarity selection.	ws signal
0: Active high.	
1: Active low.	
16 Reserved. Must be set to 0.	
15 IRQ15 Polarity. If LPC is selected as the interface source for IRQ15 (F0BAR1+I/O Offset 00h[15] = 1), this bit allows spolarity selection.	
0: Active high.	ows signal
1: Active low.	ows signal

Bit	Description
14	IRQ14 Polarity. If LPC is selected as the interface source for IRQ14 (F0BAR1+I/O Offset 00h[14] = 1), this bit allows signal polarity selection.
	0: Active high.
	1: Active low.
13	IRQ13 Polarity. If LPC is selected as the interface source for IRQ13 (F0BAR1+I/O Offset 00h[13] = 1), this bit allows signal polarity selection.
	0: Active high.
	1: Active low.
12	IRQ12 Polarity. If LPC is selected as the interface source for IRQ12 (F0BAR1+I/O Offset 00h[12] = 1), this bit allows signal polarity selection.
	0: Active high.
	1: Active low.
11	IRQ11 Polarity. If LPC is selected as the interface source for IRQ11 (F0BAR1+I/O Offset 00h[11] = 1), this bit allows signal polarity selection.
	0: Active high.
	1: Active low.
10	IRQ10 Polarity. If LPC is selected as the interface source for IRQ10 (F0BAR1+I/O Offset 00h[10] = 1), this bit allows signal polarity selection.
	0: Active high.
	1: Active low.
9	IRQ9 Polarity. If LPC is selected as the interface source for IRQ9 (F0BAR1+I/O Offset 00h[9] = 1), this bit allows signal polarity selection.
	0: Active high.
	1: Active low.
8	IRQ8# Polarity. If LPC is selected as the interface source for IRQ8# (F0BAR1+I/O Offset 00h[8] = 1), this bit allows signal polarity selection.
	0: Active high.
	1: Active low.
7	IRQ7 Polarity. If LPC is selected as the interface source for IRQ7 (F0BAR1+I/O Offset 00h[7] = 1), this bit allows signal polarity selection.
	0: Active high.
	1: Active low.
6	IRQ6 Polarity. If LPC is selected as the interface source for IRQ6 (F0BAR1+I/O Offset 00h[6] = 1), this bit allows signal polarity selection.
	0: Active high.
	1: Active low.
5	IRQ5 Polarity. If LPC is selected as the interface source for IRQ5 (F0BAR1+I/O Offset 00h[5] = 1), this bit allows signal polarity selection.
	0: Active high.
	1: Active low.
4	IRQ4 Polarity. If LPC is selected as the interface source for IRQ4 (F0BAR1+I/O Offset 00h[4] = 1), this bit allows signal polarity selection.
	0: Active high.
	1: Active low.
3	IRQ3 Polarity. If LPC is selected as the interface source for IRQ3 (F0BAR1+I/O Offset 00h[3] = 1), this bit allows signal polarity selection.
	0: Active high.
	1: Active low.



Bit	Description				
2	SMI# Polarity. This bit allows signal polarity selection of the SMI# generated from LPC.				
	0: Active high.				
	1: Active low.				
1	IRQ1 Polarity. If LPC is polarity selection.	selected as the interface source for IR	Q1 (F0BAR1+I/O Offse	et 00h[1] = 1), this bit allows signal	
	0: Active high.				
	1: Active low.				
0	IRQ0 Polarity. If LPC is polarity selection.	selected as the interface source for IR	Q0 (F0BAR1+I/O Offse	et 00h[0] = 1), this bit allows signal	
	0: Active high.				
	1: Active low.				
Offset 08	Bh-0Bh	SERIRQ_CNT — Serial IRQ Conti	rol Register (R/W)	Reset Value: 00000000h	
31:8	Reserved.				
7	Serial IRQ Enable.				
	0: Disable.				
	1: Enable.				
6	Serial IRQ Interface M	ode.			
	0: Continuous.				
	1: Quiet.				
5:2	Number of IRQ Data F	rames.			
	0000: 17 frames		000: 25 frames	1100: 29 frames	
	0001: 18 frames 0010: 19 frames		001: 26 frames 010: 27 frames	1101: 30 frames 1110: 31 frames	
	0011: 20 frames		011: 28 frames	1111: 32 frames	
1:0	Start Frame Pulse Wid	th.			
	00: 4 Clocks				
	01: 6 Clocks				
	10: 8 Clocks				
	11: Reserved				
Offset 00	Ch-0Fh	DRQ_SRC — DRQ Source Re	egister (R/W)	Reset Value: 00000000h	
1	make them externally acce		errupt Selection, and Ba	als require additional programming to ase Address Registers" on page 88 for formation.	
31:8	Reserved.				
7		the interface source of the DRQ7 signs	al.		
	0: ISA - DRQ7 (unavai	• •			
	,	A ball AL9; TEPBGA ball L28).			
6		the interface source of the DRQ6 signa	al.		
	0: ISA - DRQ6 (unavai	**			
	,	A ball AL9; TEPBGA ball L28).	-1		
5		the interface source of the DRQ5 signa	aı.		
	0: ISA - DRQ5 (unavai				
4	·	A ball AL9; TEPBGA ball L28). v LPC Bus Master 0 Cycles.			
4	0: Enable.	LI O Dus Masiei O Cycles.			
	1: Disable.				
3		the interface source of the DRQ3 signal	al		
3	0: ISA - DRQ3 (unavai	· ·	aı.		
		A ball AL9; TEPBGA ball L28).			
	1. LI U - LDNQ# (EBU	A Dali ALD, TET DOA Dali LZOJ.			



31:18 Reserved. 17 LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode. 16 LPC/ISA Default Mapping. Works in conjunction with bits 17 and [14:0] of this register to enable mapping of specific peripherals to LPC or internal ISA interfaces. 1f bit [x] = 0 and bit 16 = 0 then: Transaction routed to internal ISA bus. 1f bit [x] = 0 and bit 16 = 0 then: Transaction routed to LPC interface. 1f bit [x] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. 1f bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 1f bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. Bit [x] is defined as bits 17 and [14:0]. 15 LPC ROM Addressing. Depends upon F0 Index 52h[2,0]. 16 0: Disable. 17 1: Enable. 18 14 LPC Alternate SuperI/O Addressing. Alternate SuperI/O control addresses 4Eh-4Fh. See bit 16 for decode. 19 16 LPC Ad-Lib Addressing. Ad-Lib addresses I/O Ports 388h-389h. See bit 16 for decode. 10 LPC ACPI Addressing. ACPI microcontroller addresses I/O Ports 62h and 66h. See bit 16 for decode. 10 LPC Keyboard Controller Addressing. KBC addresses I/O Ports 60h and 64h. 11 Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. 12 LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. 15 LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode.		Table 6-31. F0BAR1+I/O Offset: LPC Interface Configuration Registers (Continued)
0: ISA - DRQ2 (unavailable externally). 1: LPC - LDRQ# (EBGA ball ALS; TEPBGA ball L28). 1 DRQ1 Source, Selects the interface source of the DRQ1 signal. 0: ISA - DRQ1 (unavailable externally). 1: LPC - LDRQ# (EBGA ball ALS; TEPBGA ball L28). 0 DRQ0 Source, Selects the interface source of the DRQ0 signal. 0: ISA - DRQ1 (unavailable externally). 1: LPC - LDRQ# (EBGA ball ALS; TEPBGA ball L28). Offset 10h-13b LQ_TEPBGA ball L28). Offset 10h-13b	Bit	Description
1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28). 1 DRQ1 Source. Selects the interface source of the DRQ1 signal. 0: ISA - DRQ1 (Long-waitable externally). 1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28). 0 DRQ0 Source. Selects the interface source of the DRQ0 signal. 0: ISA - DRQ0 (Lonavaitable externally). 1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28). 0: ISA - DRQ0 (Lonavaitable externally). 1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28). Offset 10h-13h LAD_EN — LPC Address Enable Register (R/W) Reset Value: 00000000h 31:18 Reserved. 17 LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode. 18 LPC/ISA Default Mapping. Works in conjunction with bits 17 and [14-0] of this register to enable mapping of specific peripherals to LPC or internal ISA interfaces. 19 bit [x] = 0 and bit 16 = 0 then: Transaction routed to internal ISA bus. 19 bit [x] = 0 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 10 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 11 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 12 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 13 bit [x] is defined as bits 17 and [14-0]. 14 LPC Alternate Superl/O Addressing. Alternate Superl/O control addresses 4Eh-4Fh. See bit 16 for decode. 15 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 16 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 17 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 18 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 10 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 11 bit [x] = 1 and bit 16 = 1 then: Transaction route	2	DRQ2 Source. Selects the interface source of the DRQ2 signal.
DRQ1 Source. Selects the interface source of the DRQ1 signal. 0: ISA - DRQ1 (unavailable externally). 1: LPC - LDRQ# (EBGA ball AL; TEPBGA ball L28). DR00 Source. Selects the interface source of the DRQ0 signal. 0: ISA - DRQ0 (unavailable externally). 1: LPC - LDRQ# (EBGA ball AL; TEPBGA ball L28). Offset 10h-13h LAD_EN — LPC Address Enable Register (R/W) Reset Value: 0000000001 31:18 Reserved. LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode. LPC/ISA Default Mapping. Works in conjunction with bits 17 and [14:0] of this register to enable mapping of specific peripherals to LPC or internal ISA interfaces. If bit [X] = 0 and bit 16 = 0 then: Transaction routed to internal ISA bus. If bit [X] = 0 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [X] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [X] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [X] = 1 and bit 16 = 1 then: Transaction routed to Internal ISA bus. Bit [X] is defined as bits 17 and [14:0]. 15 LPC ROM Addressing. Depends upon F0 Index 52h[2,0]. 0. Disable. 14 LPC Alternate Superl/O Addressing. Alternate Superl/O control addresses 4Eh-4Fh. See bit 16 for decode. 15 LPC Superl/O Addressing. Superl/O control addresses I/O Ports 2Eh-2Fh. See bit 16 for decode. Note: This bit should not be routed to LPC when using the internal Superl/O module and if IO_SIOCFG_IN (F5BAR0+)/Offset 00it[26:25] = 10. LPC Keyboard Controller Addressing. ABC addresses I/O Ports 88h-389h. See bit 16 for decode. 10 LPC Keyboard Controller Addressing. ABC addresses I/O Ports 80h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index SAh[1] must be written 0. LPC Keyboard Controller Addressing. BC addresses See Dit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 14h[12:19] LPC Game Port 1 Addressing. Boll Port 1 Addresses. See bit 16 for decode.		0: ISA - DRQ2 (unavailable externally).
0: ISA - DRQ1 (unavailable externally). 1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28). 0 DRQ0 Source. Selects the interface source of the DRQ0 signal. 0: ISA - DRQ0 (unavailable externally). 1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28). Offset 10h-13h LAD_EN — LPC Address Enable Register (R/W) Reset Value: 00000000h 31:18 Reserved. 17 LPC RTC: RTC addresses I/O Ports 070h-073h. See bit 16 for decode. 18 LPC/ISA Default Mapping. Works in conjunction with bits 17 and [14:0] of this register to enable mapping of specific peripherals to LPC or internal ISA interfaces. If bit [X] = 0 and bit 16 = 0 then. Transaction routed to internal ISA bus. If bit [X] = 0 and bit 16 = 1 then: Transaction routed to LPC interface. If bit [X] = 1 and bit 16 = 0 then. Transaction routed to LPC interface. If bit [X] = 1 and bit 16 = 0 then: Transaction routed to IPC interface. If bit [X] = 1 and bit 17 and [14:0]. 15 LPC ROM Addressing. Depends upon F0 Index 52h[2,0]. 0: Disable. 1: Enable. 14 LPC Alternate Supert/O Addressing. Alternate Supert/O control addresses 4Eh-4Fh. See bit 16 for decode. Note: This bit should not be routed to LPC when using the internal Supert/O module and if IO_SIOCFG_IN (FSBAR0+V) Offset 00h[26:25] = 10. 12 LPC Ad-Lib Addressing. AG-Ib addresses I/O Ports 388h-389h. See bit 16 for decode. 10 LPC Keyboard Controller Addressing. KBC addresses I/O Ports 62h and 66h. See bit 16 for decode. 10 LPC Wide Generic Addressing. AGPI microcontroller addresses I/O Ports 60h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written o. 10 LPC Wide Generic Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14:15] 10 LPC Game Port 1 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 11 LPC Microsoft Sound System (MSS) Addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14:10]. 12 LPC Microsoft Sound Sys		1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28).
1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28). 0 DR00 Source. Selects the interface source of the DR00 signal. 0: ISA - DR00 (unavailable externally). 1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28). 1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28). 1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28). 1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28). 1: LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode. 1: LPC/ISA Default Mapping. Works in conjunction with bits 17 and [14:0] of this register to enable mapping of specific peripherals to LPC or internal ISA interfaces. 1: bit [x] = 0 and bit 16 = 0 then: Transaction routed to internal ISA bus. 1: bit [x] = 0 and bit 16 = 0 then: Transaction routed to LPC interface. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 15 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 15 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 15 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 16 for decode. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. 1: bit [x] = 1 and bit 16 then:	1	DRQ1 Source. Selects the interface source of the DRQ1 signal.
DRQ0 Source. Selects the interface source of the DRQ0 signal. 0: ISA - DRQ0 (unavailable externally). 1: LPC - LDRQ# (EBGA ball AL9, TEPBGA ball L28). Offset 10h-13h LAD_EN — LPC Address Enable Register (R/W) Reset Value: 00000000h 31:18 Reserved. 17 LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode. 16 LPC/ISA Dafault Mapping. Works in conjunction with bits 17 and [14:0] of this register to enable mapping of specific peripherals to LPC or internal ISA interfaces. 17 bit [9] = 0 and bit 16 = 0 then: Transaction routed to internal ISA bus. 17 bit [9] = 0 and bit 16 = 0 then: Transaction routed to LPC interface. 18 bit [9] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 18 bit [9] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 18 bit [9] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [9] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [9] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [9] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [9] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [9] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 10 bit [9] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 11 LPC Addressing. Depends upon F0 Index 52h[2,0]. 12 LPC Addressing. Addressing. Addressing. Alternate Superl/O control addresses 4Eh-4Fh. See bit 16 for decode. Note: This bit should not be routed to LPC when using the internal Superl/O module and if IO_SIOCFG_IN (F5BAR0+)/Offset 00h[26:25] = 10. 12 LPC Addressing. Add-lib addresses I/O Ports 388h-389h. See bit 16 for decode. 14 LPC AGPI Addressing. Addressing. AGE addresses I/O Ports 80h and 66h. See bit 16 for decode. 15 LPC AGPI Addressing. Addressing. AGE addresses I/O Ports 80h and 66h. See bit 16 for decode. 16 LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. 17 Address selection made via F0BAR1+I/O Offset 14h[13-12]. 18 LPC Auddressin		0: ISA - DRQ1 (unavailable externally).
0: ISA - DRQ0 (unavailable externally). 1: LPC - LDRQ# (EBGA bail AL9, TEPBGA bail L28). Offset 10h-13h LAD_EN — LPC Address Enable Register (R/W) Reserved. 17 LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode. LPC/ISA Default Mapping, Works in conjunction with bits 17 and [14:0] of this register to enable mapping of specific peripherals to LPC or internal ISA interfaces. If bit [x] = 0 and bit 16 = 0 them: Transaction routed to internal ISA bus. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them: Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them Transaction routed to IPC interface. If bit [x] = 1 and bit 16 = 1 them Transaction routed to IPC when using the internal Superi/O module and if IO_SIOCFG_IN (F5BAR0+I/O) offset 0h)[2 = 25] = 10. IPC Ad-Lib Addressing, Ad-Lib addresses I/O Ports 388h-389h, See bit 16 for decode. Address selection made via F0BAR1+I/O offset 18h[15:9] Note: This bi		1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28).
1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28). Offset 10h-13h LAD_EN — LPC Address Enable Register (R/W) Reset Value: 00000000h 31:18 Reserved. 16 LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode. 17 LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode. 18 LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode. 19 LPC RTG. RTC and bit 16 = 0 then: Transaction routed to internal ISA bus. 19 bit [x] = 0 and bit 16 = 0 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 10 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 10 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 11 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 12 bit [x] is defined as bits 17 and [14:0]. 13 bit [x] is defined as bits 17 and [14:0]. 14 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 15 bit [x] = 1 and bit 16 for decode. 16 bit [x] = 1 and bit 16 for decode. 17 bit is thould not be routed to LPC when using the internal Superf/O module and if 10_SIOCFG_IN (F5BAR0+I/Offset 00h)[26:25] = 10. 18 bit [x] = 1 and bit 16 for decode. 19 bit [x] = 1 and bit 16 for decode. 10 bit [x] = 1 and bit 16 for decode. 11 bit [x] = 1 and bit 16 for decode. 12 bit [x] = 1 and bit 16 for decode. 13 bit [x] = 1 and bit 16 for decode. 14 bit [x] = 1 and bit 16 for decode. 15 bit [x] = 1 and bit 16 for decode. 16 bit [x] = 1 and bit 16 for decode. 17 bit [x] = 1 and bit 16 for decode. 18 bit [x] = 1 and bit 16 for decode. 19 bit [x] = 1 and bit 16 for decode. 10 bit [x] = 1 and bit 16 for decode. 11 bit [x] = 1 and bit 16 for decode. 12 bit [x] = 1 an	0	DRQ0 Source. Selects the interface source of the DRQ0 signal.
Offset 10h-13h LAD_EN — LPC Address Enable Register (R/W) Reset Value: 00000000h 31:18 Reserved. 17 LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode. LPC/ISA Default Mapping. Works in conjunction with bits 17 and [14:0] of this register to enable mapping of specific peripherals to LPC or internal ISA interfaces. If bit [x] = 0 and bit 16 = 0 then: Transaction routed to internal ISA bus. If bit [x] = 0 and bit 16 = 1 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC bit 16 then then then then then then then then		0: ISA - DRQ0 (unavailable externally).
31:18 Reserved. 17 LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode. 18 LPC/RSA Default Mapping. Works in conjunction with bits 17 and [14:0] of this register to enable mapping of specific peripherals to LPC or internal ISA interfaces. 18 bit [x] = 0 and bit 16 = 0 then: Transaction routed to internal ISA bus. 18 bit [x] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 10 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 11 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 12 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 13 bit [x] is defined as bits 17 and [14:0]. 14 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 15 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 16 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 17 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 18 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC interface. 10 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC when using the internal Superi/O module and if IO_SIOCFG_IN (F5BAR0+I/O interface). 19 bit [x] = 1 and bit 16 = 1 then: Transaction routed to LPC when using the internal Superi/O module and if IO_SIOCFG_IN (F5BAR0+I/O interface). 10 bit [x] = 1 and bit 16 = 1 then: Dit and bit 16 = 1 then: Dit and bit 16 internal Superi/O module and if IO_SIOCFG_IN (F5BAR0+I/O interface). 10 bit [x] = 1 and bit 16 = 1 then: Dit and bit 16 = 1 then: Dit and bit 16 internal Superi/O module and if IO_SIOCFG_IN (F5BAR0+I/O interface). 11 bit 16 bit 16 bit 16 bit 16 bit 16 bit 16		1: LPC - LDRQ# (EBGA ball AL9; TEPBGA ball L28).
17 LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode. LPC/ISA Default Mapping, Works in conjunction with bits 17 and [14:0] of this register to enable mapping of specific peripherals to LPC or internal ISA interfaces. If bit [x] = 0 and bit 16 = 0 then: Transaction routed to internal ISA bus. If bit [x] = 0 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [x] is defined as bits 17 and [14:0]. PC ROM Addressing. Depends upon F0 Index 52h[2,0]. O: Disable. 1: Enable. 1: Enable. LPC Alternate Superl/O Addressing. Alternate Superl/O control addresses 4Eh-4Fh. See bit 16 for decode. Note: This bit should not be routed to LPC when using the internal Superl/O module and if IO_SIOCFG_IN (F5BAR0+l/Offset 00h]26:25] = 10. LPC Ad-Lib Addressing. ACPI microcontroller addresses I/O Ports 38th-389h. See bit 16 for decode. LPC Keyboard Controller Addressing, KBC addresses I/O Ports 60h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index 54h[1] must be written 0. LPC Wide Generic Addressing, Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit [17, 14:14:10], and [8:0]. LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. LPC Game Port 1 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address s	Offset 10	h-13h LAD_EN — LPC Address Enable Register (R/W) Reset Value: 00000000h
LPC/ISA Default Mapping. Works in conjunction with bits 17 and [14:0] of this register to enable mapping of specific peripherals to LPC or internal ISA interfaces. If bit x = 0 and bit 16 = 0 then: Transaction routed to Internal ISA bus. If bit x = 0 and bit 16 = 1 then: Transaction routed to LPC interface. If bit x = 1 and bit 16 = 1 then: Transaction routed to LPC interface. If bit x = 1 and bit 16 = 1 then: Transaction routed to LPC interface. If bit x = 1 and bit 16 = 1 then: Transaction routed to LPC interface. If bit x = 1 and bit 16 = 1 then: Transaction routed to Internal ISA bus. Bit x is defined as bits 17 and [14:0]. 15 LPC ROM Addressing. Depends upon F0 Index 52h[2,0]. 0: Disable. 1: Enable. 14 LPC Alternate SuperI/O Addressing. Alternate SuperI/O control addresses 4Eh-4Fh. See bit 16 for decode. 15 LPC SuperI/O Addressing. SuperI/O control addresses I/O Ports 2Eh-2Fh. See bit 16 for decode. Note: This bit should not be routed to LPC when using the internal SuperI/O module and if IO_SIOCFG_IN (F5BAR0+I/Offset 00h)[26:25] = 10. 12 LPC Ad-Lib Addressing. ACPL microcontroller addresses I/O Ports 52h and 66h. See bit 16 for decode. 14 LPC ACPI Addressing. ACPI microcontroller addresses I/O Ports 60h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index 54h[1] must be written 0. 15 LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit [17], [14:10], and [8:0]. 16 LPC Game Port 1 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14:15]. 17 LPC Game Port 1 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 18 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 19 LPC MIDI Addressing. Audi	31:18	Reserved.
peripherals to LPC or internal ISA interfaces. If bit [x] = 0 and bit 16 = 0 then: Transaction routed to internal ISA bus. If bit [x] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 0 then: Transaction routed to Internal ISA bus. Bit [x] is defined as bits 17 and [14:0]. 15	17	LPC RTC. RTC addresses I/O Ports 070h-073h. See bit 16 for decode.
If bit [x] = 0 and bit 16 = 1 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 0 then: Transaction routed to LPC interface. If bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. Bit [x] is defined as bits 17 and [14:0]. 15 LPC ROM Addressing. Depends upon F0 Index 52h[2,0]. □: Disable. □: Enable. 14 LPC Alternate SuperI/O Addressing. Alternate SuperI/O control addresses 4Eh-4Fh. See bit 16 for decode. 15 LPC SuperI/O Addressing. SuperI/O control addresses I/O Ports 2Eh-2Fh. See bit 16 for decode. 16 LPC SuperI/O Addressing. SuperI/O control addresses I/O Ports 2Eh-2Fh. See bit 16 for decode. 17 LPC Ad-Lib Addressing. Ad-Lib addresses I/O Ports 388h-389h. See bit 16 for decode. 18 LPC Ad-Lib Addressing. Ad-Lib addresses I/O Ports 388h-389h. See bit 16 for decode. 19 LPC Keyboard Controller Addressing. KBC addresses I/O Ports 60h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. 19 LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit [17], [14:10], and [8:0]. 10 LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 10 LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 11 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 12 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 13 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15].	16	
If bit [x] = 1 and bit 16 = 1 then: Transaction routed to internal ISA bus. Bit [x] is defined as bits 17 and [14:0]. 15 LPC ROM Addressing. Depends upon F0 Index 52h[2,0]. 0: Disable. 1: Enable. 14 LPC Alternate Superl/O Addressing. Alternate Superl/O control addresses 4Eh-4Fh. See bit 16 for decode. 15 LPC Superl/O Addressing. Superl/O control addresses I/O Ports 2Eh-2Fh. See bit 16 for decode. 16 Note: This bit should not be routed to LPC when using the internal Superl/O module and if IO_SIOCFG_IN (F5BAR0+l/Offset 00h]26:25) = 10. 17 LPC Ad-Lib Addressing. Ad-Lib addresses I/O Ports 388h-389h. See bit 16 for decode. 18 LPC Ad-Lib Addressing. ACPI microcontroller addresses I/O Ports 62h and 66h. See bit 16 for decode. 19 LPC Keyboard Controller Addressing. KBC addresses I/O Ports 60h and 64h. 10 Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. 19 LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. 10 Address selection made via F0BAR1+I/O Offset 18h[15:9] 11 Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit [17], [14:10], and [8:0]. 11 LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. 12 Address selection made via F0BAR1+I/O Offset 14h[12:19] 13 LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. 14 Address selection made via F0BAR1+I/O Offset 14h[18:15]. 15 LPC Hiorpoy Disk Controller Addressing. MSS addresses. See bit 16 for decode. 15 Address selection made via F0BAR1+I/O Offset 14h[13:12]. 16 LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. 16 Address selection made via F0BAR1+I/O Offset 14h[13:12]. 17 LPC Audio Addressing. MIDI addresses. See bit 16 for decode. 16 Address selection made via F0BAR1+I/O Offset 14h[13:12].		1.1
15 LPC ROM Addressing. Depends upon F0 Index 52h[2,0]. 0: Disable. 1: Enable. 1: Enable. 14 LPC Alternate SuperI/O Addressing. Alternate SuperI/O control addresses 4Eh-4Fh. See bit 16 for decode. 15 LPC SuperI/O Addressing. SuperI/O control addresses I/O Ports 2Eh-2Fh. See bit 16 for decode. 16 Note: This bit should not be routed to LPC when using the internal SuperI/O module and if IO_SIOCFG_IN (FSBAR0+I/Offset 00h[26:25]) = 10. 17 LPC Ad-Lib Addressing. Ad-Lib addresses I/O Ports 388h-389h. See bit 16 for decode. 18 LPC Ad-Lib Addressing. ACPI microcontroller addresses I/O Ports 62h and 66h. See bit 16 for decode. 19 LPC Wide Generic Addressing. KBC addresses I/O Ports 60h and 64h. 10 Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. 19 LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. 19 Address selection made via F0BAR1+I/O Offset 18h[15:9] 10 Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit [17], [14:10], and [8:0]. 10 LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. 10 Address selection made via F0BAR1+I/O offset 14h[22:19] 11 LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. 12 Address selection made via F0BAR1+I/O offset 14h[18:15]. 13 LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. 14 Address selection made via F0BAR1+I/O Offset 14h[13:12]. 24 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. 25 Address selection made via F0BAR1+I/O Offset 14h[13:12]. 26 LPC MIDI Addressing. Audio addresses. See bit 16 for decode. 26 Address selection made via F0BAR1+I/O Offset 14h[13:10]. 27 LPC Audio Addressing. Audio addresses. See bit 16 for decode. 27 Address selection made via F0BAR1+I/O Offset 14h[13:10].		
0: Disable. 1: Enable. 1: EPC Alternate Supert/O Addressing. Alternate Supert/O control addresses 4Eh-4Fh. See bit 16 for decode. 1: LPC Supert/O Addressing. Supert/O control addresses I/O Ports 2Eh-2Fh. See bit 16 for decode. Note: This bit should not be routed to LPC when using the internal Supert/O module and if IO_SIOCFG_IN (F5BAR0+I/O ffset 00h[26:25]) = 10. 1: LPC Ad-Lib Addressing. Ad-Lib addresses I/O Ports 388h-389h. See bit 16 for decode. 1: LPC ACPI Addressing. ACPI microcontroller addresses I/O Ports 62h and 66h. See bit 16 for decode. 1: LPC Keyboard Controller Addressing, KBC addresses I/O Ports 60h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. 9: LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit [17], [14:10], and [8:0]. 8: LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] 7: LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 6: LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 6: LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. 4: LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 3: LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. 2: LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.		
1: Enable. 14 LPC Alternate SuperI/O Addressing. Alternate SuperI/O control addresses 4Eh-4Fh. See bit 16 for decode. 13 LPC SuperI/O Addressing. SuperI/O control addresses I/O Ports 2Eh-2Fh. See bit 16 for decode. Note: This bit should not be routed to LPC when using the internal SuperI/O module and if IO_SIOCFG_IN (F5BAR0+I/O ffiset 00h[26:25]) = 10. 12 LPC Ad-Lib Addressing. Ad-Lib addresses I/O Ports 388h-389h. See bit 16 for decode. 11 LPC ACPI Addressing. ACPI microcontroller addresses I/O Ports 62h and 66h. See bit 16 for decode. 10 LPC Keyboard Controller Addressing. KBC addresses I/O Ports 60h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. 9 LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit[17], [14:10], and [8:0]. 8 LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] 7 LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 6 LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 5 LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. 4 LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. 4 LPC Microsoft Sound System (MSS) Addressing. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:10]. 5 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:10].	15	LPC ROM Addressing. Depends upon F0 Index 52h[2,0].
LPC Alternate SuperI/O Addressing. Alternate SuperI/O control addresses 4Eh-4Fh. See bit 16 for decode. LPC SuperI/O Addressing. SuperI/O control addresses I/O Ports 2Eh-2Fh. See bit 16 for decode. Note: This bit should not be routed to LPC when using the internal SuperI/O module and if IO_SIOCFG_IN (F5BAR0+I/Offset 00h[26:25]) = 10. LPC Ad-Lib Addressing. Ad-Lib addresses I/O Ports 388h-389h. See bit 16 for decode. LPC ACPI Addressing. ACPI microcontroller addresses I/O Ports 62h and 66h. See bit 16 for decode. LPC Keyboard Controller Addressing. KBC addresses I/O Ports 60h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit[17], [14:10], and [8:0]. LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:10].		0: Disable.
LPC SuperI/O Addressing. SuperI/O control addresses I/O Ports 2Eh-2Fh. See bit 16 for decode. Note: This bit should not be routed to LPC when using the internal SuperI/O module and if IO_SIOCFG_IN (F5BAR0+I/Offset 00h[26:25]) = 10. LPC Ad-Lib Addressing. Ad-Lib addresses I/O Ports 388h-389h. See bit 16 for decode. LPC ACPI Addressing. ACPI microcontroller addresses I/O Ports 62h and 66h. See bit 16 for decode. LPC Keyboard Controller Addressing. KBC addresses I/O Ports 60h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit [17], [14:10], and [8:0]. LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14] LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.		1: Enable.
Note: This bit should not be routed to LPC when using the internal SuperI/O module and if IO_SIOCFG_IN (F5BAR0+I/Offset 00h[26:25]) = 10. LPC Ad-Lib Addressing. Ad-Lib addresses I/O Ports 388h-389h. See bit 16 for decode. LPC ACPI Addressing. ACPI microcontroller addresses I/O Ports 62h and 66h. See bit 16 for decode. LPC Keyboard Controller Addressing. KBC addresses I/O Ports 60h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit [17], [14:10], and [8:0]. LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14] LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8].	14	LPC Alternate SuperI/O Addressing. Alternate SuperI/O control addresses 4Eh-4Fh. See bit 16 for decode.
Offset 00h[26:25]) = 10. LPC Ad-Lib Addressing. Ad-Lib addresses I/O Ports 388h-389h. See bit 16 for decode. LPC ACPI Addressing. ACPI microcontroller addresses I/O Ports 62h and 66h. See bit 16 for decode. LPC Keyboard Controller Addressing. KBC addresses I/O Ports 60h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bin [17], [14:10], and [8:0]. LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14] LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. LPC MiDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.	13	LPC SuperI/O Addressing. SuperI/O control addresses I/O Ports 2Eh-2Fh. See bit 16 for decode.
11 LPC ACPI Addressing. ACPI microcontroller addresses I/O Ports 62h and 66h. See bit 16 for decode. 10 LPC Keyboard Controller Addressing. KBC addresses I/O Ports 60h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. 9 LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bi [17], [14:10], and [8:0]. 8 LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] 7 LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 6 LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14] 5 LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. 4 LPC MiDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 3 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.		_ · · · · · · · · · · · · · · · · · · ·
10 LPC Keyboard Controller Addressing. KBC addresses I/O Ports 60h and 64h. Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. 9 LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit [17], [14:10], and [8:0]. 8 LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] 7 LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 6 LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14] 5 LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. 4 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 3 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. 4 LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.	12	LPC Ad-Lib Addressing. Ad-Lib addresses I/O Ports 388h-389h. See bit 16 for decode.
Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0. PC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit [17], [14:10], and [8:0]. LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14] LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.	11	
PC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bin [17], [14:10], and [8:0]. LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14] LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.	10	LPC Keyboard Controller Addressing. KBC addresses I/O Ports 60h and 64h.
Address selection made via F0BAR1+I/O Offset 18h[15:9] Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bi [17], [14:10], and [8:0]. 8 LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] 7 LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 6 LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14] 5 LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. 4 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 3 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. 2 LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.		Note: If this bit = 0 and bit 16 = 1, then F0 Index 5Ah[1] must be written 0.
Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bi [17], [14:10], and [8:0]. LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14] LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.	9	LPC Wide Generic Addressing. Wide generic addresses. See bit 16 for decode.
[17], [14:10], and [8:0]. 8 LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[22:19] 7 LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[18:15]. 6 LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14] 5 LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. 4 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 3 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. 2 LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.		Address selection made via F0BAR1+I/O Offset 18h[15:9]
Address selection made via F0BAR1+I/O Offset 14h[22:19] 7		
The control of the co	8	LPC Game Port 1 Addressing. Game Port 1 addresses. See bit 16 for decode.
Address selection made via F0BAR1+I/O Offset 14h[18:15]. 6 LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14] 5 LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. 4 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 3 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. 2 LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.		Address selection made via F0BAR1+I/O Offset 14h[22:19]
6 LPC Floppy Disk Controller Addressing. FDC addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[14] 5 LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. 4 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 3 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. 2 LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.	7	LPC Game Port 0 Addressing. Game Port 0 addresses. See bit 16 for decode.
Address selection made via F0BAR1+I/O Offset 14h[14] 5 LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. 4 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 3 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. 2 LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.		Address selection made via F0BAR1+I/O Offset 14h[18:15].
5 LPC Microsoft Sound System (MSS) Addressing. MSS addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[13:12]. 4 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 3 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. 2 LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.	6	1
Address selection made via F0BAR1+I/O Offset 14h[13:12]. 4 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 3 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. 2 LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.		
4 LPC MIDI Addressing. MIDI addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[11:10]. 3 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. 2 LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.	5	
Address selection made via F0BAR1+I/O Offset 14h[11:10]. 3 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. 2 LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.		• •
3 LPC Audio Addressing. Audio addresses. See bit 16 for decode. Address selection made via F0BAR1+I/O Offset 14h[9:8]. 2 LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.	4	
Address selection made via F0BAR1+I/O Offset 14h[9:8]. 2 LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.		• •
LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.	3	LPC Audio Addressing. Audio addresses. See bit 16 for decode.
		Address selection made via F0BAR1+I/O Offset 14h[9:8].
Address selection made via F0BAR1+I/O Offset 14h[7:5].	2	LPC Serial Port 1 Addressing. Serial Port 1 addresses. See bit 16 for decode.
		Address selection made via F0BAR1+I/O Offset 14h[7:5].



Table 6-31. F0BAR1+I/O Offset: LPC Interface Configuration Registers (Continued)

Bit	Description					
1	LPC Serial Port 0 Addressing. Serial Port 0 addresses. See bit 16 for decode.					
	Address selection mad	e via F0BAR1+I/O Offset 14h[[4:2].			
0	LPC Parallel Port Add	Iressing. Parallel Port address	ses. See bit 16 for decode.			
	Address selection mad	e via F0BAR1+I/O Offset 14h	[1:0].			
Offset 14	h-17h	LAD D0 — LPC Address	s Decode 0 Register (R/W)	Reset Value: 00080020h		
31:23	Reserved.					
22:19	LPC Game Port 1 Add	dress Select. Selects I/O Port				
	0000: 200h	0100: 204h	1000: 208h	1100: 20Ch		
	0001: 201h	0101: 205h	1001: 209h	1101: 20Dh		
	0010: 202h	0110: 206h	1010: 20Ah	1110: 20Eh		
	0011: 203h	0111: 207h	1011: 20Bh	1111: 20Fh		
		e is enabled via F0BAR1+I/O				
18:15	LPC Game Port 0 Add	dress Select. Selects I/O Port	:			
	0000: 200h	0100: 204h	1000: 208h	1100: 20Ch		
	0001: 201h 0010: 202h	0101: 205h 0110: 206h	1001: 209h 1010: 20Ah	1101: 20Dh 1110: 20Eh		
	0010: 202h 0011: 203h	0111: 207h	1011: 20Bh	1111: 20Fh		
	Selected address rang	e is enabled via F0BAR1+I/O	Offset 10h[7].			
14	Selected address range is enabled via F0BAR1+I/O Offset 10h[7]. LPC Floppy Disk Controller Address Select. Selects I/O Port:					
	0: 3F0h-3F7h.					
	1: 370h-377h.					
13:12	Selected address range is enabled via F0BAR1+I/O Offset 10h[6]. LPC Microsoft Sound System (MSS) Address Select. Selects I/O Port:					
10.12	00: 530h-537h	10: E80h-E87h	con ociocis i/o i ori.			
	01: 604h-60Bh	11: F40h-F47h				
	Selected address range is enabled via F0BAR1+I/O Offset 10h[5].					
11:10	LPC MIDI Address Select. Selects I/O Port:					
	00: 300h-301h	10: 320h-321h				
	01: 310h-311h	11: 330h-331h				
	Selected address rang	e is enabled via F0BAR1+I/O	Offset 10h[4].			
9:8	LPC Audio Address S	Select. Selects I/O Port:				
	00: 220h-233h	10: 260h-273h				
	01: 240h-253h	11: 280h-293h				
	Selected address rang	e is enabled via F0BAR1+I/O	Offset 10h[3].			
7:5	LPC Serial Port 1 Add	Iress Select. Selects I/O Port:	:			
	000: 3F8h-3FFh	010: 220h-227h	100: 238h-23Fh	110: 338h-33Fh		
	001: 2F8h-2FFh	011: 228h-22Fh	101: 2E8h-2EFh	111: 3E8h-3EFh		
	<u> </u>	e is enabled via F0BAR1+I/O	• •			
4:2	LPC Serial Port 0 Add	Iress Select. Selects I/O Port:				
	000: 3F8h-3FFh 001: 2F8h-2FFh	010: 220h-227h 011: 228h-22Fh	100: 238h-23Fh 101: 2E8h-2EFh	110: 338h-33Fh 111: 3E8h-3EFh		
	Selected address range is enabled via F0BAR1+I/O Offset 10h[1].					
1:0	LPC Parallel Port Add	Iress Select. Selects I/O Port:				
	00: 378h-37Fh (+778h 10: 3BCh-3BFh (+7BC		01: 278h-27Fh (+678h-6 11: Reserved	7Fh for ECP) (Note)		
	Selected address rang	e is enabled via F0BAR1+I/O	Offset 10h[0].			
	Note: 279h is read	only, writes are forwarded to IS	SA for PnP.			

Revision 5.1

Table 6-31. F0BAR1+I/O Offset: LPC Interface Configuration Registers (Continued)

Bit	Table 6-31. F0BAR1+I/O Offset: LPC Interface Configuration Registers (Continued) Description				
	·				
Offset 18h					
31:16	Reserved. Must be set to 0.				
15:9	Wide Generic Base Address Select. Defines a 512 byte space. Can be mapped anywhere in the 64 KB I/O space. AC97 and other configuration registers are expected to be mapped to this range. It is wide enough to allow many unforeseen devices to be supported. Enabled at F0BAR1+I/O Offset 10h[9].				
	Note: The selected range must not overlap any address range that is positively decoded by F0BAR1+I/O Offset 10h bit [17], [14:10], and [8:0].				
8:0	Reserved. Must be set to 0.				
Offset 1Ch	n-1Fh LPC_ERR_SMI — LPC Error SMI Register (R/W) Reset Value: 00000080h				
31:12	Reserved. Must be set to 0.				
11	LPCPD# Override Enable. Determines how LPCPD# output is controlled.				
	0: ACPI logic.				
	1: LPCPD# Override Value bit (bit 10 of this register).				
10	LPCPD# Override Value. Selects value of LPCPD# output if bit 11 of this register is set to 1.				
	0: Power down sequence.				
	1: Normal power.				
9	SMI Serial IRQ Enable. Allows serial IRQ to generate an SMI.				
	0: Disable.				
	1: Enable.				
	Top Level SMI status is reported at F1BAR0+I/O Offset 02h[3].				
	Second level status is reported at bit 6 of this register.				
8	SMI Configuration for LPC Error Enable. Allows LPC errors to generate an SMI.				
	0: Disable.				
	1: Enable.				
	Top Level SMI status is reported at F1BAR0+I/O Offset 02h[3]. Second level status is reported at bit 5 of this register.				
7	LPCPD# Pin Status. (Read Only) Reflects the current value of the LPCPD# output signal.				
6	SMI Source is Serial IRQ. Indicates whether or not an SMI was generated by an SERIRQ.				
	0: No.				
	1: Yes.				
	Write 1 to clear.				
	To enable SMI generation, set bit 9 of this register to 1.				
	This is the second level of status reporting. The top level status is reported in F1BAR0+I/O Offset 02h[3].				
	Writing a 1 to this bit also clears the top level status bit as long as bit 5 of this register is cleared.				
5	LPC Error Status. Indicates whether or not an SMI was generated by an error that occurred on LPC.				
	0: No.				
	1: Yes.				
	Write 1 to clear.				
	To enable SMI generation, set bit 8 of this register to 1.				
	This is the second level of status reporting. The top level status is reported in F1BAR0+I/O Offset 02h[3].				
	Writing a 1 to this bit also clears the top level status bit as long as bit 6 of this register is cleared.				
4	LPC Multiple Errors Status. Indicates whether or not multiple errors have occurred on LPC.				
•	0: No.				
	1: Yes.				
	Write 1 to clear.				
	while i to deal.				



Bit	Description
3	LPC Timeout Error Status. Indicates whether or not an error was generated by a timeout on LPC.
	0: No.
	1: Yes.
	Write 1 to clear.
2	LPC Error Write Status. Indicates whether or not an error was generated during a write operation on LPC.
	0: No.
	1: Yes.
	Write 1 to clear.
1	LPC Error DMA Status. Indicates whether or not an error was generated during a DMA operation on LPC.
	0: No.
	1: Yes.
	Write 1 to clear.
0	LPC Error Memory Status. Indicates whether or not an error was generated during a memory operation on LPC.
	0: No.
	1: Yes.
	Write 1 to clear.
Offset 20	h-23h LPC_ERR_ADD — LPC Error Address Register (RO) Reset Value: 00000000h
31:0	LPC Error Address.



6.4.2 SMI Status and ACPI Registers - Function 1

The register space designated as Function 1 (F1) is used to configure the PCI portion of support hardware for the SMI Status and ACPI Support registers. The bit formats for the PCI Header registers are given in Table 6-32.

Located in the PCI Header registers of F1 are two Base Address Registers (F1BARx) used for pointing to the register spaces designated for SMI status and ACPI support, described later in this section.

Table 6-32. F1: PCI Header Registers for SMI Status and ACPI Support

Bit	Description		
Index 00h-0	1h Ve	ndor Identification Register (RO)	Reset Value: 100Bh
Index 02h-0	3h De	vice Identification Register (RO)	Reset Value: 0501h
Index 04h-0	95h	PCI Command Register (R/W)	Reset Value: 0000h
15:1	Reserved. (Read Only)		
	I/O Space. Allow the Core Logic mode0: Disable.1: Enable.	ule to respond to I/O cycles from the PCI bus.	
	This bit must be enabled to access I/C	offsets through F1BAR0 and F1BAR1 (see F1 Inc	dex 10h and 40h).
Index 06h-0	7h	PCI Status Register (RO)	Reset Value: 0280h
Index 08h	D	evice Revision ID Register (RO)	Reset Value: 00h
Index 09h-0	Bh	PCI Class Code Register (RO)	Reset Value: 068000h
Index 0Ch	PC	CI Cache Line Size Register (RO)	Reset Value: 00h
Index 0Dh	Р	CI Latency Timer Register (RO)	Reset Value: 00h
Index 0Eh		PCI Header Type (RO)	Reset Value: 00h
Index 0Fh		PCI BIST Register (RO)	Reset Value: 00h
Index 10h-13h		Address Register 0 - F1BAR0 (R/W)	Reset Value: 00000001h
•	• • • • • • • • • • • • • • • • • • • •	tus related registers. Bits [7:0] are read only (0000 or bit formats and reset values of the SMI status re	,.
31:8	MI Status Base Address.		
7:0	Address Range. (Read Only)		
Index 14h-2	Bh	Reserved	Reset Value: 00h
Index 2Ch-2	2Dh	Subsystem Vendor ID (RO)	Reset Value: 100Bh
Index 2Eh-2Fh		Subsystem ID (RO)	Reset Value: 0501h
Index 30h-3Fh		Reserved	Reset Value: 00h
Index 40h-43h		Address Register 1 - F1BAR1 (R/W)	Reset Value: 00000001h
-		elated registers. Bits [7:0] are read only (0000 0001 nats and reset values of the ACPI registers.), indicating a 256 byte address
	Base Address register moved from its normal PCI Header Space (F1 Index 14h) to prevent plug and play software frocating it after an FACP table is built.		
31:8	ACPI Base Address.		
7:1	Address Range. (Read Only)		
0	Enable. (Write Only) This bit must be	set to 1 to enable access to ACPI Support Regist	ers.
Index 44h-F	Fh .	Reserved	Reset Value: 00h



6.4.2.1 SMI Status Support Registers

F1 Index 10h, Base Address Register 0 (F1BAR0), points to the base address for SMI Status register locations. Table 6-33 gives the bit formats of I/O mapped SMI Status registers accessed through F1BAR0.

The registers at F1BAR0+I/O Offset 50h-FFh can also be accessed F0 Index 50h-FFh. The preferred method is to program these registers through the F0 register space.

Table 6-33. F1BAR0+I/O Offset: SMI Status Registers

Bit	Description	
Offset 00	h-01h Top Level PME/SMI Status Mirror Register (RO) Reset Value: 0000h	
Note:	Reading this register does not clear the status bits. For more information, see F1BAR0+I/O Offset 02h.	
15	Suspend Modulation Enable Mirror. This bit mirrors the Suspend Mode Configuration bit (F0 Index 96h[0]). It is used by the SMI handler to determine if the SMI Speedup Disable Register (F1BAR0+I/O Offset 08h) must be cleared on exit.	
14	SMI Source is USB. Indicates whether or not an SMI was caused by USB activity	
	0: No.	
	1: Yes.	
	To enable SMI generation, set F5BAR0+I/O Offset 00h[20:19] to 11.	
13	SMI Source is Warm Reset Command. Indicates whether or not an SMI was caused by a Warm Reset command.	
	0: No.	
	1: Yes.	
12	SMI Source is NMI. Indicates whether or not an SMI was caused by NMI activity.	
	0: No.	
	1: Yes.	
11	SMI Source is IRQ2 of SIO Module. Indicates whether or not an SMI was caused by IRQ2 of the SIO module.	
	0: No.	
	1: Yes.	
	The next level (second level) of SMI status is reported in the SuperI/O module. For more information, see Table 5-29 "Banks 0 and 1 - Common Control and Status Registers" on page 134, Offset 00h.	
10	SMI Source is EXT_SMI[7:0]. Indicates whether or not an SMI was caused by a negative-edge event on EXT_SMI[7:0].	
	0: No.	
	1: Yes.	
	The next level (second level) of SMI status is at F1BAR0+I/O Offset 24h[23:8].	
9	SMI Source is GP Timers/UDEF/PCI/ISA Function Trap. Indicates if an SMI was caused by:	
	— Expiration of GP Timer 1 or 2.— Trapped access to UDEF1, 2, or 3.	
	Trapped access to ODEP1, 2, or 3. Trapped access to F1-F5 or ISA Legacy register space.	
	0: No.	
	1: Yes.	
	The next level (second level) of SMI status is at F1BAR0+I/O Offset 04h/06h.	
8	SMI Source is Software Generated. Indicates whether or not an SMI was caused by software.	
	0: No.	
	1: Yes.	
7	SMI on an A20M# Toggle. Indicates whether or not an SMI was caused by a write access to either Port 92h or the keyboard command which initiates an A20M# SMI.	
	0: No.	
	1: Yes.	
	This method of controlling the internal A20M# in the GX1 module is used instead of a pin.	
	To enable SMI generation, set F0 Index 53h[0] to 1.	



Bit	Description	
6	SMI Source is a VGA Timer Event. Indicates whether or not an SMI was caused by the expiration of the VGA Timer (F0 Index 8Eh).	
	0: No.	
	1: Yes.	
	To enable SMI generation, set F0 Index 83h[3] to 1.	
5	SMI Source is Video Retrace. Indicates whether or not an SMI was caused by a video retrace event as decoded from the internal serial connection (PSERIAL register, bit 7) from the GX1 module.	
	0: No.	
	1: Yes.	
	To enable SMI generation, set F0 Index 83h[2] to 1.	
4	Reserved. Reads as 0.	
3	SMI Source is LPC. Indicates whether or not an SMI was caused by the LPC interface.	
	0: No.	
	1: Yes.	
	The next level (second level) of SMI status is at F0BAR1+I/O Offset 1Ch[6:5].	
2	SMI Source is ACPI. Indicates whether or not an SMI was caused by an access (read or write) to one of the ACPI registers (F1BAR1).	
	0: No.	
	1: Yes.	
	The next level (second level) of SMI status is at F1BAR0+I/O Offset 20h.	
1	SMI Source is Audio Subsystem. Indicates whether or not an SMI was caused by the audio subsystem.	
	0: No.	
	1: Yes.	
	The next level (second level) of SMI status is at F3BAR0+Memory Offset 10h/12h.	
0	SMI Source is Power Management Event. Indicates whether or not an SMI was caused by one of the power management resources (except for GP timers, UDEFx and PCI/ISA function traps that are reported in bit 9).	
	0: No.	
	1: Yes.	
	The next level (second level) of SMI status is at F0 Index 84h-F4h/87h-F7h.	
Offset 02	th-03h Top Level PME/SMI Status Register (RO/RC) Reset Value: 0000h	
	Reading this register clears all the SMI status bits except for the "read only" bits, because they have a second level of status reporting. Clearing the second level status bits also clears the top level (except for GPIOs).	
	GPIO SMIs have third level of SMI status reporting at F0BAR0+I/O Offset 0Ch/1Ch. Clearing the third level GPIO status bits also clears the second and top levels.	
	A read-only "Mirror" version of this register exists at F1BAR0+I/O Offset 00h. If the value of the register must be read without clearing the SMI source (and consequently de-asserting SMI), F1BAR0+I/O Offset 00h can be read instead.	
15	Suspend Modulation Enable Mirror. (Read to Clear)	
	This bit mirrors the Suspend Mode Configuration bit (F0 Index 96h[0]). It is used by the SMI handler to determine if the SMI Speedup Disable Register (F1BAR0+I/O Offset 08h) must be cleared on exit.	
14	SMI Source is USB. (Read to Clear) Indicates whether or not an SMI was caused by USB activity.	
	0: No.	
	1: Yes.	
	1. 100.	
	To enable SMI generation, set F5BAR0+I/O Offset 00h[20:19] to 11.	
13		
13	To enable SMI generation, set F5BAR0+I/O Offset 00h[20:19] to 11. SMI Source is Warm Reset Command. (Read to Clear) Indicates whether or not an SMI was caused by Warm Reset	



Bit	Description		
12	SMI Source is NMI. (Read to Clear) Indicates whether or not an SMI was caused by NMI activity.		
	0: No.		
	1: Yes.		
11	SMI Source is IRQ2 of SIO Module. (Read to Clear) Indicates whether or not an SMI was caused by IRQ2 of the SIO module.		
	0: No.		
	1: Yes.		
	The next level (second level) of SMI status is reported in the SuperI/O module. See Table 5-29 "Banks 0 and 1 - Common Control and Status Registers" on page 134 for details.		
10	SMI Source is EXT_SMI[7:0]. (Read Only. Read Does Not Clear) Indicates whether or not an SMI was caused by a negative-edge event on EXT_SMI[7:0].		
	0: No.		
	1: Yes.		
	The next level (second level) of SMI status is at F1BAR0+I/O Offset 24h[23:8].		
9	SMI Source is General Timers/Traps. (Read Only, Read Does Not Clear) Indicates whether or not an SMI was caused by the expiration of one of the General Purpose Timers or one of the User Defined Traps.		
	0: No.		
	1: Yes.		
	The next level (second level) of SMI status is at F1BAR0+I/O Offset 04h/06h.		
8	8 SMI Source is Software Generated. (Read to Clear) Indicates whether or not an SMI was caused by software.		
	0: No.		
	1: Yes.		
7	SMI on an A20M# Toggle. (Read to Clear) Indicates whether or not an SMI was caused by an access to either Port 92h or the keyboard command which initiates an A20M# SMI		
	0: No.		
	1: Yes.		
	This method of controlling the internal A20M# in the GX1 module is used instead of a pin. To enable SMI generation, act F0 lader F2h[0] to 1		
	To enable SMI generation, set F0 Index 53h[0] to 1.		
6	SMI Source is a VGA Timer Event. (Read to Clear) Indicates whether or not an SMI was caused by expiration of the VGA Timer (F0 Index 8Eh).		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F0 Index 83h[3] to 1.		
5	SMI Source is Video Retrace. (Read to Clear) Indicates whether or not an SMI was caused by a video retrace event as decoded from the internal serial connection (PSERIAL register, bit 7) from the GX1 module.		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F0 Index 83h[2] to 1.		
4	Reserved. Reads as 0.		
3	SMI Source is LPC. (Read Only, Read Does Not Clear) Indicates whether or not an SMI was caused by the LPC interface.		
	0: No.		
	1: Yes.		
	The next level (second level) of SMI status is at F0BAR1+I/O Offset 1Ch[6:5].		
2	SMI Source is ACPI. (Read Only, Read Does Not Clear) Indicates whether or not an SMI was caused by an access (read or write) to one of the ACPI registers (F1BAR1).		
	0: No.		
	1: Yes. The part level (second level) of SMI status is at E1BAROLI/O Offset 20h		
	The next level (second level) of SMI status is at F1BAR0+I/O Offset 20h.		



Bit	Description	
1	SMI Source is Audio Subsystem. (Read Only, Read Does Not Clear) Indicates whether or not an SMI was caused by audio subsystem.	
	0: No.	
	1: Yes.	
	The second level of status is found in F3BAR0+Memory Offset 10h/12h.	
0	SMI Source is Power Management Event. (Read Only, Read Does Not Clear) Indicates whether or not an SMI was caused by one of the power management resources (except for GP timers, UDEFx and PCI/ISA function traps which are reported in bit 9).	
	0: No.	
	1: Yes.	
	The next level (second level) of SMI status is at F0 Index 84h/F4h-87h/F7h.	

Offset 04h-05h

Second Level General Traps & Timers PME/SMI Status Mirror Register (RO)

Reset Value: 0000h

The bits in this register contain second level status reporting. Top level status is reported at F1BAR0+I/O Offset 00h/02h[9]. Reading this register does not clear the SMI. For more information, see F1BAR0+I/O Offset 06h.

15:6	Reserved.		
5	PCI/ISA Function Trap. Indicates whether or not an SMI was caused by a trapped PCI/ISA configuration cycle.		
	0: No.		
	1: Yes.		
	To enable SMI generation for:		
	Trapped access to ISA Legacy I/O register space set F0 Index 41h[0] = 1.		
	 Trapped access to F1 register space set F0 Index 41h[1] = 1. Trapped access to F2 register space set F0 Index 41h[2] = 1. 		
	Trapped access to F2 register space set F0 Index 41h[2] = 1. Trapped access to F3 register space set F0 Index 41h[3] = 1.		
	 Trapped access to F4 register space set F0 Index 41h[4] = 1. 		
	Trapped access to F5 register space set F0 Index 41h[5] = 1.		
4	SMI Source is Trapped Access to User Defined Device 3. Indicates whether or not an SMI was caused by a trapped I/O or memory access to the User Defined Device 3 (F0 Index C8h).		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F0 Index 82h[6] = 1.		
3	SMI Source is Trapped Access to User Defined Device 2. Indicates whether or not an SMI was caused by a trapped I/O or memory access to the User Defined Device 2 (F0 Index C4h).		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F0 Index 82h[5] = 1.		
2	SMI Source is Trapped Access to User Defined Device 1. Indicates whether or not an SMI was caused by a trapped I/O or memory access to the User Defined Device 1 (F0 Index C0h).		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F0 Index 82h[4] = 1.		
1	SMI Source is Expired General Purpose Timer 2. Indicates whether or not an SMI was caused by the expiration of General Purpose Timer 2 (F0 Index 8Ah).		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F0 Index 83h[1] = 1.		



Bit	Description
0	SMI Source is Expired General Purpose Timer 1. Indicates whether or not an SMI was caused by the expiration of General Purpose Timer 1 (F0 Index 88h).
	0: No.
	1: Yes.
	To enable SMI generation, set F0 Index 83h[0] = 1.

Offset 06h-07h

Second Level General Traps & Timers Status Register (RC)

Reset Value: 0000h

The bits in this register contain second level of status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/02h[9]. Reading this register clears the status at both the second and top levels.

A read-only "Mirror" version of this register exists at F1BAR0+I/O Offset 04h. If the value of this register must be read without clearing the SMI source (and consequently de-asserting SMI), F1BAR0+I/O Offset 04h can be read instead.

15:6	Reserved.		
5	PCI/ISA Function Trap. Indicates whether or not an SMI was caused by a trapped PCI/ISA configuration cycle		
	0: No.		
	1: Yes.		
	To enable SMI generation for:		
	Trapped access to ISA Legacy I/O register space set F0 Index 41h[0] = 1.		
	 Trapped access to F1 register space set F0 Index 41h[1] = 1. Trapped access to F2 register space set F0 Index 41h[2] = 1. 		
	Trapped access to F2 register space set F0 Index 41h[2] = 1. Trapped access to F3 register space set F0 Index 41h[3] = 1.		
	 Trapped access to F4 register space set F0 Index 41h[4] = 1. 		
	— Trapped access to F5 register space set F0 Index 41h[5] = 1.		
4	SMI Source is Trapped Access to User Defined Device 3 (UDEF3). Indicates whether or not an SMI was caused by a		
	trapped I/O or memory access to User Defined Device 3 (F0 Index C8h).		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F0 Index 82h[6] = 1.		
3	SMI Source is Trapped Access to User Defined Device 2 (UDEF2). Indicates whether or not an SMI was caused by a		
	trapped I/O or memory access to User Defined Device 2 (F0 Index C4h).		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F0 Index 82h[5] = 1.		
2	SMI Source is Trapped Access to User Defined Device 1 (UDEF1). Indicates whether or not an SMI was caused by a trapped I/O or memory access to User Defined Device 1 (F0 Index C0h).		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F0 Index 82h[4] = 1.		
1	SMI Source is Expired General Purpose Timer 2. Indicates whether or not an SMI was caused by the expiration of Gereral Purpose Timer 2 (F0 Index 8Ah).		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F0 Index 83h[1] = 1.		
0	SMI Source is Expired General Purpose Timer 1. Indicates whether or not an SMI was caused by the expiration of Gereral Purpose Timer 1 (F0 Index 88h).		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F0 Index 83h[0] = 1.		



Bit	Description Table 6-33. F1BARU+I/O Offset: SMI Status Registers (Co	, , , , , , , , , , , , , , , , , , ,
Offset 08h	-09h SMI Speedup Disable Register (Read to Enable)	Reset Value: 0000h
15:0	SMI Speedup Disable. If bit 1 in the Suspend Configuration Register is set (F0 Index 9 invokes the SMI handler to re-enable Suspend Modulation.	6h[1] = 1), a read of this register
	The data read from this register can be ignored. If the Suspend Modulation feature is dis no effect.	sabled, reading this I/O location has
Offset 0Al	n-1Bh Reserved	Reset Value: 00h
These add	resses should not be written.	
Offset 1CI	n-1Fh ACPI Timer Register (RO)	Reset Value: xxxxxxxxh
Note: T	nis register can also be read at F1BAR1+I/O Offset 1Ch.	
31:24	Reserved.	
23:0	TMR_VAL. This field returns the running count of the power management timer.	
Offset 20h	-21h Second Level ACPI PME/SMI Status Mirror Register (RO)	Reset Value: 0000h
	this register contain second level SMI status reporting. Top level status is reported in F1E	BAR0+I/O Offset 00h/02h[2].
Reading th	is register does not clear the SMI. For more information, see F1BAR0+I/O Offset 22h.	
15:6	Reserved. Always reads 0.	
5	ACPI BIOS SMI Status. Indicates whether or not an SMI was caused by ACPI software	raising an event to BIOS software.
	0: No.	
	1: Yes.	
	To enable SMI generation, set F1BAR1+I/O Offset 0Ch[2] to 1, and F1BAR1+I/O Offset	0Fh[0] to 1.
4	PLVL3 SMI Status. Indicates whether or not an SMI was caused by a read of the ACPI 05h).	PLVL3 register (F1BAR1+I/O Offset
	0: No.	
	1: Yes.	
	To enable SMI generation, set F1BAR1+I/O Offset 18h[11] to 1 (default).	
3	Reserved.	
2	SLP_EN SMI Status. Indicates whether or not an SMI was caused by a write of 1 to the Offset 0Ch[13]).	e ACPI SLP_EN bit (F1BAR1+I/O
	0: No.	
	1: Yes.	
	To enable SMI generation, set F1BAR1+I/O Offset 18h[9] to 1 (default).	
1	THT_EN SMI Status. Indicates whether or not an SMI was caused by a write of 1 to the Offset 00h[4]).	e ACPI THT_EN bit (F1BAR1+I/O
	0: No.	
	1: Yes.	
	To enable SMI generation, set F1BAR1+I/O Offset 18h[8] to 1 (default).	
0	SMI_CMD SMI Status. Indicates whether or not an SMI was caused by a write to the A O Offset 06h).	CPI SMI_CMD register (F1BAR1+I/
	0: No.	
	1: Yes.	
	A write to the ACPI SMI_CMD register always generates an SMI.	



Bit	Description		
Offset 22h	-23h Second Level ACPI PME/SMI Status Register (RC) Reset Value: 0000h		
The bits in	this register contain second level of SMI status reporting. Top level is reported in F1BAR0+I/O Offset 00h/02h[2].		
Reading th	Reading this register clears the status at both the second and top levels.		
	A read-only "Mirror" version of this register exists at F1BAR0+I/O Offset 20h. If the value of the register must be read without clearing the SMI source (and consequently de-asserting SMI), F1BAR0+I/O Offset 20h can be read instead.		
15:6	Reserved. Always reads 0.		
5	ACPI BIOS SMI Status. Indicates whether or not an SMI was caused by ACPI software raising an event to BIOS software.		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F1BAR1+I/O Offset 0Ch[2] to 1, and F1BAR1+I/O Offset 0Fh[0] to 1.		
4	PLVL3 SMI Status. Indicates whether or not an SMI was caused by a read of the ACPI PLVL3 register (F1BAR1+I/O Offset		
	05h).		
	0: No.		
	1: Yes. To enable SMI generation, set E1BAB1 I/O Offset 19b[14] to 1 (default)		
	To enable SMI generation, set F1BAR1+I/O Offset 18h[11] to 1 (default).		
3	Reserved.		
2	SLP_EN SMI Status. Indicates whether or not an SMI was caused by a write of 1 to the ACPI SLP_EN bit (F1BAR1+I/O Offset 0Ch[13]).		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F1BAR1+I/O Offset 18h[9] to 1 (default).		
1	THT_EN SMI Status. Indicates whether or not an SMI was caused by a write of 1 to the ACPI THT_EN bit (F1BAR1+I/O Offset 00h[4])		
	0: No.		
	1: Yes.		
	To enable SMI generation, set F1BAR1+I/O Offset 18h[8] to 1 (default).		
0	SMI_CMD SMI Status. Indicates whether or not an SMI was caused by a write to the ACPI SMI_CMD register (F1BAR1+I/O Offset 06h).		
	0: No.		
	1: Yes.		
	A write to the ACPI SMI_CMD register always generates an SMI.		
Offset 24h	-27h External SMI Register (R/W) Reset Value: 00000000h		
Note: E	XT_SMI[7:0] are external SMIs, meaning external to the Core Logic module.		
	ts [23:8] of this register contain second level of SMI status reporting. Top level status is reported in F1BAR0+I/O Offset 00h/		
	02h[10]. Reading bits [23:16] clears the second and top levels. If the value of the status bits must be read without clearing the SMI source (and consequently de-asserting SMI), bits [15:8] can be read instead.		
31:24	Reserved. Must be set to 0.		
23	EXT_SMI7 SMI Status. (Read to Clear) Indicates whether or not an SMI was caused by assertion of EXT_SMI7.		
	0: No.		
	1: Yes.		
	To enable SMI generation, set bit 7 to 1.		
22	EXT_SMI6 SMI Status. (Read to Clear) Indicates whether or not an SMI was caused by an assertion of EXT_SMI6		
	0: No.		
	1: Yes.		
	To enable SMI generation, set bit 6 to 1.		



Bit	Description			
21	EXT_SMI5 SMI Status. (Read to Clear) Indicates whether or not an SMI was caused by an assertion of EXT_SMI5.			
	0: No.			
	1: Yes.			
	To enable SMI generation, set bit 5 to 1.			
20	EXT_SMI4 SMI Status. (Read to Clear) Indicates whether or not an SMI was caused by an assertion of EXT_SMI4.			
	0: No.			
	1: Yes.			
	To enable SMI generation, set bit 4 to 1.			
19	EXT_SMI3 SMI Status. (Read to Clear) Indicates whether or not an SMI was caused by an assertion of EXT_SMI3.			
	0: No.			
	1: Yes.			
	To enable SMI generation, set bit 3 to 1.			
18	EXT_SMI2 SMI Status. (Read to Clear) Indicates whether or not an SMI was caused by an assertion of EXT_SMI2.			
	0: No.			
	1: Yes.			
	To enable SMI generation, set bit 2 to 1.			
17	EXT_SMI1 SMI Status. (Read to Clear) Indicates whether or not an SMI was caused by an assertion of EXT_SMI1.			
	0: No.			
	1: Yes.			
	To enable SMI generation, set bit 1 to 1.			
16	EXT_SMI0 SMI Status. (Read to Clear) Indicates whether or not an SMI was caused by an assertion of EXT_SMI0.			
	0: No.			
	1: Yes.			
	To enable SMI generation, set bit 0 to 1.			
15	EXT_SMI7 SMI Status. (Read Only) Indicates whether or not an SMI was caused by an assertion of EXT_SMI7.			
	0: No.			
	1: Yes.			
	To enable SMI generation, set bit 7 to 1.			
14	EXT_SMI6 SMI Status. (Read Only) Indicates whether or not an SMI was caused by an assertion of EXT_SMI6.			
	0: No.			
	1: Yes.			
	To enable SMI generation, set bit 6 to 1.			
13	EXT_SMI5 SMI Status. (Read Only) Indicates whether or not an SMI was caused by an assertion of EXT_SMI5.			
	0: No.			
	1: Yes.			
	To enable SMI generation, set bit 5 to 1.			
12	EXT_SMI4 SMI Status. (Read Only) Indicates whether or not an SMI was caused by an assertion of EXT_SMI4.			
	0: No. 1: Yes.			
	To enable SMI generation, set bit 4 to 1.			
44				
11	EXT_SMI3 SMI Status. (Read Only) Indicates whether or not an SMI was caused by an assertion of EXT_SMI3.			
	0: No. 1: Yes.			
	To enable SMI generation, set bit 3 to 1.			
	10 Shable Shiri generation, oct bit o to 1.			



Bit	Description
10	EXT_SMI2 SMI Status. (Read Only) Indicates whether or not an SMI was caused by an assertion of EXT_SMI2.
	0: No.
	1: Yes.
	To enable SMI generation, set bit 2 to 1.
9	EXT_SMI1 SMI Status. (Read Only) Indicates whether or not an SMI was caused by an assertion of EXT_SMI1.
	0: No.
	1: Yes.
	To enable SMI generation, set bit 1 to 1.
8	EXT_SMI0 SMI Status. (Read Only) Indicates whether or not an SMI was caused by an assertion of EXT_SMI0.
	0: No.
	1: Yes.
	To enable SMI generation, set bit 0 to 1.
7	EXT_SMI7 SMI Enable. When this bit is asserted, allow EXT_SMI7 to generate an SMI on negative-edge events.
	0: Disable.
	1: Enable.
	Top level SMI status is reported at F1BAR0+00h/02h[10]. Second level SMI status is reported at bits 23 (RC) and 15 (RO).
6	EXT_SMI6 SMI Enable. When this bit is asserted, allow EXT_SMI6 to generate an SMI on negative-edge events.
	0: Disable. 1: Enable.
	Top level SMI status is reported at F1BAR0+00h/02h[10].
	Second level SMI status is reported at http://doi.org/10.101/10.1
5	EXT_SMI5 SMI Enable. When this bit is asserted, allow EXT_SMI5 to generate an SMI on negative-edge events.
	0: Disable.
	1: Enable.
	Top level SMI status is reported at F1BAR0+00h/02h[10]. Second level SMI status is reported at bits 21 (RC) and 13 (RO).
4	EXT_SMI4 SMI Enable. When this bit is asserted, allows EXT_SMI4 to generate an SMI on negative-edge events.
	0: Disable.
	1: Enable.
	Top level SMI status is reported at F1BAR0+00h/02h[10].
	Second level SMI status is reported at bits 20 (RC) and 12 (RO).
3	EXT_SMI3 SMI Enable. When this bit is asserted, allow EXT_SMI3 to generate an SMI on negative-edge events.
	0: Disable.
	1: Enable.
	Top level SMI status is reported at F1BAR0+00h/02h[10]. Second level SMI status is reported at bits 19 (RC) and 11 (RO).
2	EXT_SMI2 SMI Enable. When this bit is asserted, allow EXT_SMI2 to generate an SMI on negative-edge events.
	0: Disable.
	1: Enable.
	Top level SMI status is reported at F1BAR0+00h/02h[10]. Second level SMI status is reported at bits 18 (RC) and 10 (RO).
1	EXT_SMI1 SMI Enable. When this bit is asserted, allow EXT_SMI1 to generate an SMI on negative-edge events.
	0: Disable.
	1: Enable.
	Top level SMI status is reported at F1BAR0+00h/02h[10].
	Second level SMI status is reported at bits 17 (RC) and 9 (RO).



Bit	Description		
0	EXT_SMI0 SMI Enable. When this bit is asserted, allow EXT_SMI0 to generate an SMI on negative-edge events.		
	0: Disable.		
	1: Enable. Top level SMI status is reported at F1BAR0+00h/02h[10]. Second level SMI status is reported at bits 16 (RC) and 8 (RO).		
Offset 28h	-4Fh Not Used	Reset Value: 00h	
Offset 50h-FFh	The I/O mapped registers located here (F1BAR0+I/O Offset 50h-FFh) can also be accessed at F0 Index 50h-FFh. The preferred method is to program these registers through the F0 register space. Refer to Table 6-29 "F0: PCI Header/Bridge Configuration Registers for GPIO and LPC Support" on page 206 for more information about these registers.		



6.4.2.2 ACPI Support Registers

F1 Index 40h, Base Address Register 1 (F1BAR1), points to the base address of where the ACPI Support registers

are located. Table 6-34 shows the I/O mapped ACPI Support registers accessed through F1BAR1.

Table 6-34. F1BAR1+I/O Offset: ACPI Support Registers

Bit	Description		
Offset 00h	-03h P_CNT — Processor Control Register (R/N	N) Reset Value: 00000000h	
31:5	Reserved. Always reads 0.		
4	THT_EN (Throttle Enable). When this bit is asserted, it enables throttling of [2:0] of this register). 0: Disable. 1: Enable. If F1BAR1+I/O Offset 18h[8] =1, an SMI is generated when this bit is set. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[2]. Second level SMI status is reported at F1BAR0+I/O Offset 20h/22h[1].	of the clock based on the CLK_VAL field (bits	
3	Reserved. Always reads 0.		
2:0	CLK_VAL (Clock Throttling Value). CPU duty cycle:		
	000: Reserved 010: 25% 100: 50% 001: 12.5% 011: 37.5% 101: 62.5%	110: 75% 111: 87.5%	
Offset 04h	Reserved	Reset Value: 00h	
Note: TI	nis register should not be read. It controls a reserved function of power ma	anagement logic.	
Offset 05h	P_LVL3 — Enter C3 Power State Register (F	RO) Reset Value: xxh	
7:0	P_LVL3 (Power Level 3). Reading this 8-bit read only register causes the processor to enter the C3 power state. Reads of P_LVL3 return 0. Writes have no effect.		
	The ACPI state machine always waits for an SMI (any SMI) to be generated and serviced before transfer into C3 power state.		
	A read of this register causes an SMI if enabled: F1BAR1+I/O Offset 18h[1	1] = 1 (default).	
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[2]. Second level SMI status is reported at F1BAR0+I/O Offset 20h/22h[4].		
Offset 06h	SMI_CMD — OS/BIOS Requests Register (R	(/W) Reset Value: 00h	
7:0	SMI_CMD (SMI Command and OS / BIOS Requests). A write to this register stores data and a read returns the last data written. In addition, a write to this register always generates an SMI. A read of this register does not generate an SMI.		
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[2]. Second level SMI status is reported at F1BAR0+I/O Offset 20h/22h[0].		
Offset 07h	ACPI_FUN_CNT — ACPI Function Control Regis	ter (R/W) Reset Value: 00h	
7:6	LED_CNT (LED Output Control). Controls the blinking of an LED when in	the SL4 or SL5 sleep state	
	00: Disable (LED# signal, is HiZ).		
	01: Zero (LED# signal is HiZ).		
	10: Blink @ 1 Hz rate, when in SL4 and SL5 sleep states. Duty cycle: LED# is 10% pulled low, 90% HiZ.		
	11: One (LED# is pulled low, when in SL4 and SL5 sleep states)		
5	Reserved. Must be set to 0.		
4	INTR_WU_SL1. Enables wakeup on enabled interrupts in sleep state SL1.		
	0: Disable wakeup from SL1, when an enabled interrupt is active.		
	Enable wakeup from SL1, when an enabled interrupt is active.		
3	GPWIO_DBNC_DIS (GPWIO0 and GPWIO1 Debounce). When enabled, than 15.8 ms is required for GPWIO0 and GPWIO1 to be recognized.	a high-to-low or low-to-high transition of greater	
	0: Enable. (Default)		
	1: Disable. (No debounce)		
	GPWIO2 pin does not have debounce capability.		
2:1	Reserved. Must be set to 0.		



Bit	Table 6-34. F1BAR1+I/O Offset: ACPI Support Registers (Continued) Description		
0	PWRBTN_DBNC_DIS (Power Button Debounce). When enabled, a high-to-low or low-to-high transition of greater to		
U	15.8 ms is required on PWRBTN# before it is recognized.		
	0: Enable. (Default)		
	1: Disable. (No debounce)		
Offset 08h	n-09h PM1A_STS — PM1A Top Level PME/SCI Status Register (R/W) Reset Value: 0000h		
Notes: 1	. This is the top level of PME/SCI status reporting for these events. There is no second level.		
2	. If SCI generation is not desired, the status bits are still set by the described conditions and can be used for monitoring purposes.		
15	WAK_STS (Wakeup Status). Indicates whether or not an SCI was caused by the occurrence of an enabled wakeup event.		
	0: No.		
	1: Yes.		
	This bit is set when the system is in any Sleep state and an enabled wakeup event occurs (wakeup events are configured at F1BAR1+I/O Offset 0Ah and 12h). After this bit is set, the system transitions to a Working state.		
	SCI generation is always enabled.		
	Write 1 to clear.		
14:12	Reserved. Must be set to 0.		
11	PWRBTNOR_STS (Power Button Override Status). Indicates whether or not an SCI was caused by the power button being active for greater than 4 seconds.		
	0: No.		
	1: Yes.		
	SCI generation is always enabled.		
	Write 1 to clear.		
10	RTC_STS (Real-Time Clock Status). Indicates if a Power Management Event (PME) was caused by the RTC generating an alarm (RTC IRQ signal is asserted).		
	0: No.		
	1: Yes.		
	For the PME to generate an SCI, set F1BAR1+I/O Offset 0Ah[10] to 1 and F1BAR1+I/O Offset 0Ch[0] to 1. (See Note 2 in the general description of this register.)		
	Write 1 to clear.		
9	Reserved. Must be set to 0.		
8	PWRBTN_STS (Power Button Status). Indicates if PME was caused by the PWRBTN# going low while the system is in a Working state.		
	0: No.		
	1: Yes.		
	For the PME to generate an SCI, set F1BAR1+I/O Offset 0Ah[8] = 1 and F1BAR1+I/O Offset 0Ch[0] = 1. (See Note 2 in the general description of this register.)		
	In a Sleep state or the Soft-Off state, a wakeup event is generated when the power button is pressed (regardless of the PWRBTN_EN bit, F1BAR1+I/O Offset 0Ah[8], setting).		
	Write 1 to clear.		
7:6	Reserved. Must be set to 0.		
5	GBL_STS (Global Lock Status). Indicates if PME was caused by the BIOS releasing control of the global lock.		
	0: No. 1: Yes.		
	This bit is used by the BIOS to generate an SCI. BIOS writes the BIOS_RLS bit (F1BAR1+I/O Offset 0Fh[1]) which in turns sets the GBL_STS bit and raises a PME.		
	For the PME to generate an SCI, set F1BAR1+I/O Offset 0Ah[5] to 1 and F1BAR1+I/O Offset 0Ch[0] to 1. (See Note 2 in the general description of this register.)		
	Write 1 to clear.		



Bit	Description		
4	BM_STS (Bus Master Status). Indicates if PME was caused by a system bus master requesting the system bus.		
	0: No.		
	1: Yes.		
	For the PME to generate an SCI, set F1BAR1+I/O Offset 0Ch[1] = 1 and F1BAR1+I/O Offset 0C general description of this register.)	Ch[0] = 1. (See Note 2 in the	
	Write 1 to clear.		
3:1	Reserved. Must be set to 0.		
0	TMR_STS (Timer Carry Status). Indicates if SCI was caused by an MSB toggle (MSB change low) on the ACPI Timer (F1BAR0+I/O Offset 1Ch or F1BAR1+I/O Offset 1Ch).	s from low-to-high or high-to	
	0: No.		
	1: Yes.		
	For the PME to generate an SCI, set F1BAR1+I/O Offset 0Ah[0] = 1 and F1BAR1+I/O Offset 00 general description of this register.)	Ch[0] = 1. (See Note 2 in the	
	Write 1 to clear.		
Offset 0A	h-0Bh PM1A_EN — PM1A PME/SCI Enable Register (R/W)	Reset Value: 0000h	
	r the ACPI events described below to generate an SCI, the SCI_EN bit must also be set (F1BAR		
	enabled via this register are globally enabled by setting F1BAR1+I/O Offset 08h. There is no seco		
15:11	Reserved. Must be set to 0.		
10	RTC_EN (Real-Time Clock Enable). Allow SCI generation when the RTC generates an alarm asserted).	(RTC IRQ signal is	
	0: Disable.		
	1: Enable		
9	Reserved. Must be set to 0.		
8	PWRBTN_EN (Power Button Enable). Allow SCI generation when PWRBTN# goes low while	the system is in a Working	
	state.		
	0: Disable.		
	1: Enable		
7:6	Reserved. Must be set to 0.		
5	GBL_EN (Global Lock Enable). Allow SCI generation when the BIOS releases control of the g (F1BAR1+I/O Offset 0Fh[1] and GBL_STS (F1BAR1+I/O Offset 08h[5]) bits.	lobal lock via the BIOS_RL	
	0: Disable.		
	1: Enable		
4:1	Reserved. Must be set to 0.		
0	TMR_EN (ACPI Timer Enable). Allow SCI generation for MSB toggles (MSB changes from low the ACPI Timer (F1BAR0+I/O Offset 1Ch or F1BAR1+I/O Offset 1Ch).	v-to-high or high-to-low) on	
	0: Disable. 1: Enable		
		Reset Value: 0000h	



Bit	Description		
13	SLP_EN (Sleep Enable). (Write Only) Allow the system to sequence into the sleeping state associated with the SLP_TYPx (bits [12:10]).		
	0: Disable.		
	1: Enable.		
	This is a write only bit and reads of this bit always return a 0.		
	The ACPI state machine always waits for an SMI (any SMI) to be generated and serviced before transitioning into a Sleep state.		
	If F1BAR1+I/O Offset 18h[9] = 1, an SMI is generated when SLP_EN is set.		
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[2]. Second level SMI status is reported at F1BAR0+I/O Offset 20h/22h[2].		
12:10	SLP_TYPx (Sleep Type). Defines the type of Sleep state the system enters when SLP_EN (bit 13) is set.		
	000: Sleep State S0 (Full on) 100: Sleep State SL4 001: Sleep State SL1 101: Sleep State SL5 (Soft off) 010: Sleep State SL2 110: Reserved 011: Sleep State SL3 111: Reserved		
9:3	Reserved. Set to 0.		
2	GBL_RLS (Global Release). (Write Only) This write only bit is used by ACPI software to raise an event to the BIOS software (i.e., it generates an SMI to pass execution control to the BIOS).		
	0: Disable.		
	1: Enable.		
	This is a write only bit and reads of this bit always return a 0.		
	To generate an SMI, ACPI software writes the GBL_RLS bit which in turn sets the BIOS_STS bit (F1BAR1+I/O Offset 0Eh[0]) and raises a PME. For the PME to generate an SMI, set BIOS_EN (F1BAR1+I/O Offset 0Fh[0] to 1).		
	The top level SMI status is reported at F1BAR0+I/O offset 00h/02h. Second level status is at F1BAR0+I/O Offset 22h[5].		
1	BM_RLD (Bus Master RLD). If the processor is in the C3 state and a bus master request is generated, force the processor to transition to the C0 state.		
	0: Disable.		
	1: Enable		
0	SCI_EN (System Control Interrupt Enable). Globally selects power management events (PMEs) reported in PM1A_STS and GPE0_STS (F1BAR1+I/O Offset 08h and 10h) to be either an SCI or SMI type of interrupt.		
	0: APM Mode, generates an SMI and status is reported at F1BAR0+I/O Offset 00h/02h[0].		
	1: ACPI Mode, generates an SCI if the corresponding PME enable bit is set and status is reported at F1BAR1+I/O Offset 08h and 10h.		
	Note: This bit enables the ACPI state machine.		
Offset 0Eh	ACPI_BIOS_STS Register (R/W) Reset Value: 00h		
7:1	Reserved. Must be set to 0.		
0	BIOS_STS (BIOS Status Release). When 1 is written to the GLB_RLS bit (F1BAR1+I/O Offset 0Ch[2]), this bit is also set to 1.		
	Write 1 to clear.		



Bit	t Description		
Offset 0Fh ACPI_BIOS_EN Register (R/W)			
7:2	Reserved. Must be set to 0.		
1	BIOS_RLS (BIOS Release). (Write Only) When this bit is asserted, allow the BIOS to release co	ontrol of the global lock.	
	0: Disable.		
	1: Enable.		
	This is a write only bit and reads of this bit always return a 0.		
	To generate an SCI, the BIOS writes the BIOS_RLS bit which in turn sets the GBL_STS bit (F1BA raises a PME. For the PME to generate an SCI, set GBL_EN (F1BAR1+I/O Offset 0Ah[5] to 1).	R1+I/O Offset 08h[5]) and	
0	BIOS_EN (BIOS Enable). When this bit is asserted, allow SMI generation by ACPI software via v (F1BAR1+I/O Offset 0Ch[2]).	writes to GBL_RLS	
	0: Disable.		
	1: Enable		
Offset 10h	-11h GPE0_STS — General Purpose Event 0 PME/SCI Status Register (R/W)	Reset Value: xxxxh	
Notes: 1)	This is the top level of PME/SCI status reporting. There is no second level except for bit 3 (GPIC status is reported at F0BAR0+I/O Offset 0Ch/1Ch.	Os) where the next level of	
2)	If SCI generation is not desired, the status bits are still set by the described conditions and can be poses.	pe used for monitoring pur-	
15:12	Reserved. Must be set to 0.		
11	Reserved.		
10	GPWIO2_STS. Indicates if PME was caused by activity on GPWIO2.		
	0: No.		
	1: Yes.		
	Write 1 to clear.		
	For the PME to generate an SCI:		
	1) Ensure that GPWIO2 is enabled as an input (F1BAR1+I/O Offset 15h[2] = 0)		
	2) Set F1BAR1+I/O Offset 12h[10] = 1 and F1BAR1+I/O Offset 0Ch[0] = 1. (See Note 2 in the gregister above.)	general description of this	
	If F1BAR1+I/O Offset $15h[6] = 1$ it overrides these settings and GPWIO2 generates an SMI and tF1BAR0+00h/02h[0].	the status is reported in	
9	GPWIO1_STS. Indicates if PME was caused by activity on GPWIO1.		
	0: No.		
	1: Yes.		
	Write 1 to clear.		
	For the PME to generate an SCI:		
	1) Ensure that GPWIO1 is enabled as an input (F1BAR1+I/O Offset 15h[1] = 0)		
	2) Set F1BAR1+I/O Offset 12h[9] = 1 and F1BAR1+I/O Offset 0Ch[0] = 1. (See Note 2 in the garegister above.)	eneral description of this	
	If F1BAR1+I/O Offset $15h[5] = 1$ it overrides these settings and GPWIO1 generates an SMI and tF1BAR0+00h/02h[0].	the status is reported in	
8	GPWIO0_STS. Indicates if PME was caused by activity on GPWIO0.		
	0: No.		
	1: Yes.		
	Write 1 to clear.		
	For the PME to generate an SCI:		
	1) Ensure that GPWIO0 is enabled as an input (F1BAR1+I/O Offset 15h[0] = 0)		
	2) Set F1BAR1+I/O Offset 12h[8] = 1 and F1BAR1+I/O Offset 0Ch[0] = 1. (See Note 2 in the go register above).	eneral description of this	
	If F1BAR1+I/O Offset $15h[4] = 1$ it overrides these settings and GPWIO0 generates an SMI and tF1BAR0+00h/02h[0].	the status is reported in	



Bit	Description
7	Reserved. Must be set to 0.
6	USB_STS. Indicates if PME was caused by a USB interrupt event.
	0: No.
	1: Yes.
	Write 1 to clear.
	For the PME to generate an SCI, set F1BAR1+I/O Offset 12h[6] = 1 and F1BAR1+I/O Offset 0Ch[0] = 1. (See Note 2 in the general description of this register above.)
5	THRM_STS. Indicates if PME was caused by activity on THRM#.
	0: No.
	1: Yes.
	Write 1 to clear.
	For the PME to generate an SCI, set F1BAR1+I/O Offset 12h[5] = 1 and F1BAR1+I/O Offset 0Ch[0] = 1, (See Note 2 in the general description of this register above,)
4	SMI_STS. Indicates if PME was caused by activity on the internal SMI# signal.
	0: No.
	1: Yes.
	Write 1 to clear.
	For the PME to generate an SCI, set F1BAR1+I/O Offset 12h[4] = 1 and F1BAR1+I/O Offset 0Ch[0] = 1. (See Note 2 in the general description of this register above.)
3	GPIO_STS. Indicates if PME was caused by activity on any of the GPIOs (GPIO47-GPIO32 and GPIO15-GPIO0).
	0: No.
	1: Yes.
	Write 1 to clear.
	For the PME to generate an SCI, set F1BAR1+I/O Offset 12h[3] = 1 and F1BAR1+I/O Offset 0Ch[0] = 1. (See Note 2 in the general description of this register above).
	F0BAR0+I/O Offset 08h/18h selects which GPIOs are enabled to generate a PME. In addition, the selected GPIO must be enabled as an input (F0BAR0+I/O Offset 20h and 24h).
2:1	Reserved. Reads as 0.
0	PWR_U_REQ_STS. Indicates if PME was caused by a power-up request event from the SuperI/O module.
	0: No.
	1: Yes.
	Write 1 to clear.
	For the PME to generate an SCI, set F1BAR1+I/O Offset 12h[0] = 1 and F1BAR1+I/O Offset 0Ch[0] = 1. (See Note 2 in the general description of this register above.)



Bit	Description	
Offset 12h	n-13h GPE0_EN — General Purpose Event 0 Enable Register (R/W) Reset Value: 0000h	
In order fo	r the ACPI events described below to generate an SCI, the SCI_EN bit must also be set (F1BAR1+I/O Offset 0Ch[0] = 1).	
	enabled in this register are globally enabled by setting F1BAR1+I/O Offset 0Ch[0] to 1. The status of the SCIs is reported in /O Offset 10h.	
15:12	Reserved.	
11	Reserved.	
10	GPWIO2_EN. Allow GPWIO2 to generate an SCI.	
	0: Disable.	
	1: Enable.	
	A fixed high-to-low or low-to-high transition (debounce period) of 31 µs exists in order for GPWIO2 to be recognized.	
	The setting of this bit can be overridden via F1BAR1+I/O Offset 15h[6] to force an SMI.	
9	GPWIO1_EN. Allow GPWIO1 to generate an SCI.	
	0: Disable.	
	1: Enable.	
	See F1BAR1+I/O Offset 07h[3] for debounce information.	
	The setting of this bit can be overridden via F1BAR1+I/O Offset 15h[5] to force an SMI.	
8	GPWIO0_EN. Allow GPWIO0 to generate an SCI.	
	0: Disable.	
	1: Enable.	
	See F1BAR1+I/O Offset 07h[3] for debounce information.	
	The setting of this bit can be overridden via F1BAR1+I/O Offset 15h[4] to force an SMI.	
7	Reserved. Must be set to 0	
6	USB_EN. Allow USB events to generate a SCI.	
	0: Disable.	
	1: Enable	
5	THRM_EN. Allow THRM# to generate an SCI.	
	0: Disable.	
	1: Enable	
4	SMI_EN. Allow SMI events to generate an SCI.	
	0: Disable.	
	1: Enable	
3	GPIO_EN. Allow GPIOs (GPIO47-GPIO32 and GPIO15-GPIO0) to generate an SCI.	
	0: Disable.	
	1: Enable.	
	F0BAR0+I/O Offset 08h/18h selects which GPIOs are enabled for PME generation. This bit (GPIO_EN) globally enables	
	those selected GPIOs for generation of an SCI.	
2:1	Reserved. Must be set to 0.	
0	PWR_U_REQ_EN. Allow power-up request events from the SuperI/O module to generate an SCI.	
	0: Disable.	
	1: Enable.	
	A power-up request event is defined as any of the following events/activities: Modem, Telephone, Keyboard, Mouse, CEIR (Consumer Electronic Infrared)	



Bit	Description	
Offset 14h	h GPWIO Control Register 1 (R/W) Re	eset Value: 00h
7:4	Reserved. Must be set to 0.	
3	Reserved.	
2	GPWIO2_POL. Select GPWIO2 polarity.	
	0: Active high	
	1: Active low	
1	GPWIO1_POL. Select GPWIO1 polarity.	
	0: Active high	
	1: Active low	
0	GPWIO0_POL. Select GPWIO0 polarity.	
	0: Active high	
	1: Active low	
Offset 15h	h GPWIO Control Register 2 (R/W) Re	eset Value: 00h
7	Reserved.	
6	GPWIO_SMIEN2. Allow GPWIO2 to generate an SMI.	
	0: Disable. (Default)	
	1: Enable.	
	A fixed high-to-low or low-to-high transition (debounce period) of 31 µs exists in order for GPWIO2 to be re-	ecognized.
	Bit 2 of this register must be set to 0 (input) for GPWIO2 to be able to generate an SMI.	
	If asserted, this bit overrides the setting of F1BAR1+I/O Offset 12h[10] and its status is reported in F1BAR 02h[0].	0+I/O Offset 00h/
5	GPWIO_SMIEN1. Allow GPWIO1 to generate an SMI.	
	0: Disable. (Default)	
	1: Enable.	
	See F1BAR1+I/O Offset 07h[3] for debounce information.	
	Bit 1 of this register must be set to 0 (input) for GPWIO1 to be able to generate an SMI.	
	If asserted, this bit overrides the setting of F1BAR1+I/O Offset 12h[9] and its status is reported in F1BAR0 02h[0].	0+I/O Offset 00h/
4	GPWIO_SMIEN0. Allow GPWIO0 to generate an SMI.	
	0: Disable. (Default)	
	1: Enable.	
	See F1BAR1+I/O Offset 07h[3] for debounce information.	
	Bit 0 of this register must be set to 0 (input) for GPWIO0 to be able to generate an SMI.	
	If enabled, this bit overrides the setting of F1BAR1+I/O Offset 12h[8] and its status is reported in F1BAR0-02h[0].	+I/O Offset 00h/
3	Reserved.	
2	GPWIO2_DIR. Selects the direction of GPWIO2.	
	0: Input.	
	1: Output.	
1	GPWIO1_DIR. Selects the direction of GPWIO1.	
	0: Input.	
	1: Output.	
0	GPWIO0_DIR. Selects the direction of the GPWIO0.	
	0: Input.	
	1: Output.	



Bit	Description	
Offset 16	6h GPWIO Data Register (R/W)	Reset Value: 00h
	ster contains the direct values of the GPWIO2-GPWIO0 pins. Write operatio register read the last written value if the pin is an output. The pins are config	
7:4	Reserved. Must be set to 0.	
3	Reserved.	
2	GPWIO2_DATA. Reflects the level of GPWIO2. 0: Low.	
	1: High. A fixed high-to-low or low-to-high transition (debounce period) of 31 μs e	exists in order for GPWIO2 to be recognized.
1	GPWIO1_DATA. Reflects the level of GPWIO1.0: Low.1: High.See F1BAR1+I/O Offset 07h[3] for debounce information.	
0	GPWIO0_DATA. Reflects the level of GPWIO0.0: Low.1: High.See F1BAR1+I/O Offset 07h[3] for debounce information.	
Offset 17	7h Reserved	Reset Value: 00h
Offset 18	8h-1Bh ACPI SCI_ROUTING Register (R/W)	Reset Value: 00000F00h
31:17	Reserved.	
16	PCTL_DELAYEN. Allow staggered delays on the activation and deactivation PWRCNT2, and ONCTL# by 2 ms each.	ation of the power control pins PWRCNT1,
	0: Disable. (Default) 1: Enable.	
15:12	Reserved. Must be set to 0.	
11	 PLVL3_SMIEN. Allow SMI generation when the PLVL3 Register (F1BAR 0: Disable. 1: Enable. (Default) Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[2]. Second level SMI status is reported at F1BAR0+I/O Offset 20h/22h[4]. 	R1+I/O Offset 05h) is read.
10	Reserved. Must be set to 0.	
9	SLP_SMIEN. Allow SMI generation when the SLP_EN bit (F1BAR1+I/O 0: Disable. 1: Enable. (Default) Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[2]. Second level SMI status is reported at F1BAR0+I/O Offset 20h/22h[2].	Offset 0Ch[13]) is set.
8	THT_SMIEN. Allow SMI generation when the THT_EN bit (F1BAR1+I/O	Offset 00h[4]) is set.
7:4	0: Disable. 1: Enable. (Default) Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[2]. Second level SMI status is reported at F1BAR0+I/O Offset 20h/22h[1].	



Bit	Description			
3:0	SCI_IRQ_ROUTE. SCI is routed to:			
	0000: Disable	0100: IRQ4	1000: IRQ8	1100: IRQ12
	0001: IRQ1	0101: IRQ5	1001: IRQ9	1101: IRQ13
	0010: Reserved	0010: IRQ6	1010: IRQ10	1110: IRQ14
	0011: IRQ3	0011: IRQ7	1011: IRQ11	1111: IRQ15
	For more details see S	ection 6.2.6.3 "Programmable	e Interrupt Controller" on page	171.
Offset 1CI	h-1Fh	ACPI Timer	Register (RO)	Reset Value: xxxxxxxxh
Note: T	his register can also be i	ead at F1BAR0+I/O Offset 1	Ch.	
31:24	Reserved.			
23:0	TMR_VAL. (Read Only	y) This bit field contains the r	unning count of the power man	agement timer.
Offset 20h PM2_CNT — PM2 Control Register (R/W) Reset Value: 00				Reset Value: 00h
7:1	Reserved.			
0	Arbiter Disable. Disab	oles the PCI arbiter when set	by the OS. Used during C3 trar	nsition.
	0: Arbiter not disabled. (Default)			
	1: Disable arbiter.			
Offset 21h-FFh Reserved		Reset Value: 00h		
T I	alue for these registers i			



6.4.3 IDE Controller Registers - Function 2

The register space designated as Function 2 (F2) is used to configure Channels 0 and 1 and the PCI portion of support hardware for the IDE controllers. The bit formats for the PCI Header/Channels 0 and 1 Registers are given in Table 6-35.

Located in the PCI Header Registers of F2 is a Base Address Register (F2BAR4) used for pointing to the register space designated for support of the IDE controllers, described later in this section.

Table 6-35. F2: PCI Header/Channels 0 and 1 Registers for IDE Controller Configuration

Bit	Description	
Index 00h	01h Vendor Identification Register (RO)	Reset Value: 100Bh
Index 02h-03h Device Identification Register (RO)		Reset Value: 0502h
Index 04h	05h PCI Command Register (R/W)	Reset Value: 0000h
15:3	Reserved. (Read Only)	
2	Bus Master. Allow the Core Logic module bus mastering capabilities.	
	0: Disable.	
	1: Enable. (Default)	
	This bit must be set to 1.	
1	Reserved. (Read Only)	
0	I/O Space. Allow the Core Logic module to respond to I/O cycles from the PCI bus.	
	0: Disable.	
	1: Enable.	
	This bit must be enabled, in order to access I/O offsets through F2BAR4 (for more information)	·
Index 06h	07h PCI Status Register (RO)	Reset Value: 0280h
Index 08h	Device Revision ID Register (RO)	Reset Value: 01h
Index 09h	0Bh PCI Class Code Register (RO)	Reset Value: 010180h
Index 0Ch	PCI Cache Line Size Register (RO)	Reset Value: 00h
Index 0Dh	PCI Latency Timer Register (RO)	Reset Value: 00h
Index 0Eh	PCI Header Type (RO)	Reset Value: 00h
Index 0Fh	PCI BIST Register (RO)	Reset Value: 00h
Index 10h	13h Base Address Register 0 - F2BAR0 (RO)	Reset Value: 00000000h
Reserved.	Reserved for possible future use by the Core Logic module.	
Index 14h	17h Base Address Register 1 - F2BAR1 (RO)	Reset Value: 00000000h
Reserved.	Reserved for possible future use by the Core Logic module.	
Index 18h	1Bh Base Address Register 2 - F2BAR2 (RO)	Reset Value: 00000000h
Reserved.	Reserved for possible future use by the Core Logic module.	
Index 1Ch	1Fh Base Address Register 3 - F2BAR3 (RO)	Reset Value: 00000000h
Reserved.	Reserved for possible future use by the Core Logic module.	
Index 20h	23h Base Address Register 4 - F2BAR4 (R/W)	Reset Value: 00000001h
	ess 0 Register. This register allows access to I/O mapped Bus Mastering IDE registers. Bit be byte I/O address range. Refer to Table 6-36 on page 277 for the IDE controller register bit for	
31:4	Bus Mastering IDE Base Address.	
3:0	Address Range. (Read Only)	
Index 24h	2Bh Reserved	Reset Value: 00h
Index 2Ch	2Dh Subsystem Vendor ID (RO)	Reset Value: 100Bh
Index 2Eh	2Fh Subsystem ID (RO)	Reset Value: 0502h



Table 6-35. F2: PCI Header/Channels 0 and 1 Registers for IDE Controller Configuration (Continued)

Bit	Description	
Index 30h-	3Fh Reserved	Reset Value: 00h
Index 40h-	43h Channel 0 Drive 0 PIO Register (R/W)	Reset Value: 00009172h
If Index 44h	o[31] = 0, Format 0. Bits [15:0] configure the same timing control for both command and data.	
	ettings for a Fast-PCI clock frequency of 33.3 MHz:	
	Mode 0 = 00009172h	
	Mode 1 = 00012171h Mode 2 = 00020080h	
	Mode 3 = 0002008011 Mode 3 = 00032010h	
	Mode 4 = 00040010h	
Format 0 s	ettings for a Fast-PCI clock frequency of 66.7 MHz:	
	Mode 0 = 0000FFF4h	
	Mode 1 = 0001F353h	
	Mode 2 = 00028141h Mode 3 = 00034231h	
	Mode 4 = 00041131h	
Note: Al 31:20	I references to "cycle" in the following bit descriptions are to a Fast-PCI clock cycle. Reserved. Must be set to 0.	
19:16	PIOMODE. PIO mode.	
15:12	t2l. Recovery time (value + 1 cycle).	
11:8	t3. IDE_IOW# data setup time (value + 1 cycle).	
7:4	t2W. IDE_IOW# width minus t3 (value + 1 cycle).	
3:0	t1. Address Setup Time (value + 1 cycle).	
If Index 44h	n[31] = 1, Format 1. Bits [31:0] allow independent timing control for both command and data.	
Format 1 s	ettings for a Fast-PCI clock frequency of 33.3 MHz:	
— PIO	Mode 0 = 9172D132h	
	Mode 1 = 21717121h	
	Mode 2 = 00803020h	
	Mode 3 = 20102010h Mode 4 = 00100010h	
	ettings for a Fast-PCI clock frequency of 66.7 MHz:	
	Mode 0 = F8E4F8E4h	
	Mode 1 = 53F3F353h	
— PIO	Mode 2 = 13F18141h	
	Mode 3 = 42314231h	
— PIO	Mode 4 = 11311131h	
Note: Al	I references to "cycle" in the following bit descriptions are to a Fast-PCI clock cycle.	
31:28	t2IC. Command cycle recovery time (value + 1 cycle).	
27:24	t3C. Command cycle IDE_IOW# data setup (value + 1 cycle).	
23:20	t2WC. Command cycle IDE_IOW# pulse width minus t3 (value + 1 cycle).	
19:16	t1C. Command cycle address setup time (value + 1 cycle).	
15:12	t2ID. Data cycle recovery time (value + 1 cycle).	
11:8	t3D. Data cycle IDE_IOW# data setup (value + 1 cycle).	
7:4	t2WD. Data cycle IDE_IOW# pulse width minus t3 (value + 1 cycle).	
3:0	t1D. Data cycle address Setup Time (value + 1 cycle).	



Table 6-35. F2: PCI Header/Channels 0 and 1 Registers for IDE Controller Configuration (Continued)

Bit	Description
Index 44h-	47h Channel 0 Drive 0 DMA Control Register (R/W) Reset Value: 00077771h
The structu	re of this register depends on the value of bit 20.
If bit 20 = 0	, Multiword DMA
— Mult — Mult	r a Fast-PCI clock frequency of 33.3 MHz: iword DMA Mode 0 = 00077771h iword DMA Mode 1 = 00012121h iword DMA Mode 2 = 00002020h
— Mult — Mult	r a Fast-PCI clock frequency of 66.7 MHz: iword DMA Mode 0 = 000FFFF3h iword DMA Mode 1 = 00035352h iword DMA Mode 2 = 00015151h
Note: A	I references to "cycle" in the following bit descriptions are to a Fast-PCI clock cycle.
31	PIO Mode Format. This bit sets the PIO mode format for all channels and drives. Bit 31 of Offsets 2Ch, 34h, and 3Ch are R/W, but have no function so are defined as reserved.
	0: Format 0.
	1 Format 1.
30:21	Reserved. Must be set to 0.
20	DMA Select. Selects type of DMA operation. 0: Multiword DMA
19:16	tKR. IDE_IOR# recovery time (4-bit) (value + 1 cycle).
15:12	tDR. IDE_IOR# pulse width (value + 1 cycle).
11:8	tKW. IDE_IOW# recovery time (4-bit) (value + 1 cycle).
7:4	tDW. IDE_IOW# pulse width (value + 1 cycle).
3:0	tM. IDE_CS[1:0]# to IDE_IOR#/IOW# setup; IDE_CS[1:0]# setup to IDE_DACK0#/DACK1#.
Settings for — Ultra — Ultra	, UltraDMA r a Fast-PCI clock frequency of 33.3 MHz: aDMA Mode 0 = 00921250h aDMA Mode 1 = 00911140h aDMA Mode 2 = 00911030h
— Ultra — Ultra	r a Fast-PCI clock frequency of 66.7 MHz: DMA Mode 0 = 009436A1h DMA Mode 1 = 00933481h DMA Mode 2 = 00923261h
	I references to "cycle" in the following bit descriptions are to a Fast-PCI clock cycle.
31	PIO Mode Format. This bit sets the PIO mode format for all channels and drives. Bit 31 of Offsets 2Ch, 34h, and 3Ch are R/W, but have no function so are defined as reserved.
	0: Format 0
	1: Format 1
30:24	Reserved. Must be set to 0.
23:21	BSIZE. Input buffer threshold.
20	DMA Select. Selects type of DMA operation. 1: UltraDMA.
19:16	tCRC. CRC setup UDMA in IDE_DACK# (value + 1 cycle) (for host terminate CRC setup = tMLI + tSS).
15:12	tSS. UDMA out (value + 1 cycle).
11:8	tCYC. Data setup and cycle time UDMA out (value + 2 cycles).
7:4	tRP. Ready to pause time (value + 1 cycle). Note: tRFS + 1 tRP on next clock.
3:0	tACK. IDE_CS[1:0]# setup to IDE_DACK0#/DACK1# (value + 1 cycle).

Table 6-35. F2: PCI Header/Channels 0 and 1 Registers for IDE Controller Configuration (Continued)

Bit	Description	
Index 48h- Channel 0	4Bh Channel 0 Drive 1 PIO Register (R/W) Drive 1 Programmed I/O Control Register. See F2 Index 40h for bit descriptions.	Reset Value: 00009172h
	4Fh Channel 0 Drive 1 DMA Control Register (R/W) Drive 1 MDMA/UDMA Control Register. See F2 Index 44h for bit descriptions. The PIO Mode format is selected in F2 Index 44h[31], bit 31 of this register is defined as reserved.	Reset Value: 00077771h
Index 50h- Channel 1	Channel 1 Drive 0 PIO Register (R/W) Drive 0 Programmed I/O Control Register. See F2 Index 40h for bit descriptions.	Reset Value: 00009172h
	Channel 1 Drive 0 DMA Control Register (R/W) Drive 0 MDMA/UDMA Control Register. See F2 Index 44h for bit descriptions. The PIO Mode format is selected in F2 Index 44h[31], bit 31 of this register is defined as reserved.	Reset Value: 00077771h
Index 58h- Channel 1	Channel 1 Drive 1 PIO Register (R/W) Drive 1 Programmed I/O Control Register. See F2 Index 40h for bit descriptions.	Reset Value: 00009172h
	Channel 1 Drive 1 DMA Control Register (R/W) Drive 1 MDMA/UDMA Control Register. See F2 Index 44h for bit descriptions. The PIO Mode format is selected in F2 Index 44h[31], bit 31 of this register is defined as reserved.	Reset Value: 00077771h
Index 60h-	FFh Reserved	Reset Value: 00h



6.4.3.1 IDE Controller Support Registers

F2 Index 20h, Base Address Register 4 (F2BAR4), points to the base address of where the registers for IDE controller configuration are located. Table 6-36 gives the bit for-

mats of the I/O mapped IDE Controller Configuration registers that are accessed through F2BAR4.

Table 6-36. F2BAR4+I/O Offset: IDE Controller Configuration Registers

Bit	Description	
Offset 00h	IDE Bus Master 0 Command Register — Primary (R/W)	Reset Value: 00h
7:4	Reserved. Must be set to 0. Must return 0 on reads.	
3	Read or Write Control. Sets the direction of bus master transfers.	
	0: PCI reads performed.	
	1: PCI writes performed.	
	This bit should not be changed when the bus master is active.	
2:1	Reserved. Must be set to 0. Must return 0 on reads.	
0	Bus Master Control. Controls the state of the bus master.	
	0: Disable master.	
	1: Enable master.	
	Bus master operations can be halted by setting this bit to 0. Once an operation has been halte bit is set to 0 while a bus master operation is active, the command is aborted and the data tracarded. This bit should be reset after completion of data transfer.	
Offset 01h	Not Used	
Offset 02h	IDE Bus Master 0 Status Register — Primary (R/W)	Reset Value: 00h
7	Simplex Mode. (Read Only) Indicates if both the primary and secondary channel operate in	dependently.
	0: Yes.	
	1: No (simplex mode).	
6	Drive 1 DMA Enable. When asserted, allows Drive 1 to perform DMA transfers.	
	0: Disable.	
	1: Enable.	
5	Drive 0 DMA Enable. When asserted, allows Drive 0 to perform DMA transfers.	
	0: Disable.	
	1: Enable.	
4:3	Reserved. Must be set to 0. Must return 0 on reads.	
2	Bus Master Interrupt. Indicates if the bus master detected an interrupt.	
	0: No.	
	1: Yes. Write 1 to clear.	
1	Bus Master Error. Indicates if the bus master detected an error during data transfer.	
	0: No.	
	1: Yes. Write 1 to clear.	
0	Bus Master Active. Indicates if the bus master is active.	
	0: No.	
	1: Yes.	
Offset 03h	Not Used	
Offset 04h-		Reset Value: 00000000h
31:2	Pointer to the Physical Region Descriptor Table. This bit field contains a PRD table pointed	er for IDE Bus Master 0.
	When written, this field points to the first entry in a PRD table. Once IDE Bus Master 0 is ena = 1), it loads the pointer and updates this field (by adding 08h) so that is points to the next PR	
	When read, this register points to the next PRD.	
	,	

Revision 5.1

Table 6-36. F2BAR4+I/O Offset: IDE Controller Configuration Registers (Continued)

Bit	Description	
Offset 08h	IDE Bus Master 1 Command Register — Secondary (R/W)	Reset Value: 00h
7:4	Reserved. Must be set to 0. Must return 0 on reads.	
3	Read or Write Control. Sets the direction of bus master transfers.	
	0: PCI reads are performed.	
	1: PCI writes are performed.	
	This bit should not be changed when the bus master is active.	
2:1	Reserved. Must be set to 0. Must return 0 on reads.	
0	Bus Master Control. Controls the state of the bus master.	
	0: Disable master.	
	1: Enable master.	
	Bus master operations can be halted by setting this bit to 0. Once an operation has been habit is set to 0 while a bus master operation is active, the command is aborted and the data carded. This bit should be reset after completion of data transfer.	
Offset 09h	Not Used	
Offset 0Ah	IDE Bus Master 1 Status Register — Secondary (R/W)	Reset Value: 00h
7	Reserved. (Read Only)	
6	Drive 1 DMA Capable. Allow Drive 1 to perform DMA transfers.	
	0: Disable.	
	1: Enable.	
5	Drive 0 DMA Capable. Allow Drive 0 to perform DMA transfers.	
	0: Disable.	
	1: Enable.	
4:3	Reserved. Must be set to 0. Must return 0 on reads.	
2	Bus Master Interrupt. Indicates if the bus master detected an interrupt.	
	0: No.	
	1: Yes. Write 1 to clear.	
1	Bus Master Error. Indicates if the bus master detected an error during data transfer.	
	0: No.	
	1: Yes. Write 1 to clear.	
0	Bus Master Active. Indicates if the bus master is active.	
	0: No.	
	1: Yes.	
Offset 0Bh		
Offset 0Ch	-0Fh IDE Bus Master 1 PRD Table Address — Secondary (R/W)	Reset Value: 00000000h
31:2	Pointer to the Physical Region Descriptor Table. This bit field contains a PRD table points.	
	When written, this field points to the first entry in a PRD table. Once IDE Bus Master 1 is e = 1), it loads the pointer and updates this field (by adding 08h) so that is points to the next	
	When read, this register points to the next PRD.	
1:0	Reserved. Must be set to 0.	



6.4.4 Audio Registers - Function 3

The register designated as Function 3 (F3) is used to configure the PCI portion of support hardware for the audio registers. The bit formats for the PCI Header registers are given in Table 6-37.

A Base Address register (F3BAR0), located in the PCI Header registers of F3, is used for pointing to the register space designated for support of audio, described later in this section.

Table 6-37. F3: PCI Header Registers for Audio Configuration

Bit	Description	
Index 00h	01h Vendor Identification Register (RO)	Reset Value: 100Bh
Index 02h	03h Device Identification Register (RO)	Reset Value: 0503h
Index 04h	05h PCI Command Register (R/W)	Reset Value: 0000h
15:3	Reserved. (Read Only)	
2	Bus Master. Allow the Core Logic module bus mastering capabilities.	
	0: Disable.	
	1: Enable. (Default)	
	This bit must be set to 1.	
1 Memory Space. Allow the Core Logic module to respond to memory cycles from the PCI bus		JS.
	0: Disable.	
	1: Enable.	
	This bit must be enabled to access memory offsets through F3BAR0 (See F3 Index 10h).	
0	Reserved. (Read Only)	
Index 06h	07h PCI Status Register (RO)	Reset Value: 0280h
Index 08h	Device Revision ID Register (RO)	Reset Value: 00h
Index 09h	0Bh PCI Class Code Register (RO)	Reset Value: 040100h
Index 0Ch	PCI Cache Line Size Register (RO)	Reset Value: 00h
Index 0Dh	PCI Latency Timer Register (RO)	Reset Value: 00h
Index 0Eh	PCI Header Type (RO)	Reset Value: 00h
Index 0Fh	PCI BIST Register (RO)	Reset Value: 00h
Index 10h	13h Base Address Register - F3BAR0 (R/W)	Reset Value: 00000000h
used to co	er sets the base address of the memory mapped audio interface control register block. This is ntrol the audio FIFO and codec interface, as well as to support VSA SMIs. Bits [11:0] are read memory address range. Refer to Table 6-38 on page 280 for the audio configuration register l	only (0000 0000 0000), indicat-
31:12	Audio Interface Base Address	
11:0	Address Range. (Read Only)	
Index 14h	2Bh Reserved	Reset Value: 00h
Index 2Ch	-2Dh Subsystem Vendor ID (RO)	Reset Value: 100Bh
Index 2Eh	-2Fh Subsystem ID (RO)	Reset Value: 0503h
Index 30h	FFh Reserved	Reset Value: 00h
	1.555.155	



6.4.4.1 Audio Support Registers

F3 Index 10h, Base Address Register 0 (F3BAR0), points to the base address of where the registers for audio support are located. Table 6-38 gives the bit formats of the

memory mapped audio configuration registers that are accessed through F3BAR0.

Table 6-38. F3BAR0+Memory Offset: Audio Configuration Registers

Bit	Description	
Offset 00	n-03h Codec GPIO Status Register (R/W)	Reset Value: 00000000h
31	Codec GPIO Interface.	
	0: Disable.	
	1: Enable.	
30	Codec GPIO SMI. When asserted, allows codec GPIO interrupt to generate an SMI.	
	0: Disable.	
	1: Enable.	
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[1].	
29:21	Reserved. Must be set to 0.	
20	Codec GPIO Status Valid. (Read Only) Indicates if the status read is valid.	
	0: Yes.	
	1: No.	
19:0	Codec GPIO Pin Status. (Read Only) This field indicates the GPIO pin status that is rethe SDATA_IN signal.	eceived from the codec in slot 12 on
Offset 04	n-07h Codec GPIO Control Register (R/W)	Reset Value: 00000000h
31:20	Reserved. Must be set to 0.	
19:0	Codec GPIO Pin Data. This field indicates the GPIO pin data that is sent to the codec i	n slot 12 on the SDATA_OUT signal.
Offset 08	n-0Bh Codec Status Register (R/W)	Reset Value: 00000000h
31:24	Codec Status Address. (Read Only) Address of the register for which status is being slot 1 bits [19:12].	returned. This address comes from
23	Codec Serial INT Enable. When asserted, allows codec serial interrupt to cause an SM	MI.
	0: Disable.	
	1: Enable.	
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[1].	
22	SYNC Pin. Sets SYNC high or low.	
	0: Low.	
	1: High.	
21	SDATA_IN2_EN. When enabled, allows use of SDATA_IN2 input.	
	0: Disable.	
	1: Enable.	
20	Audio Bus Master 5 AC97 Slot Select. Selects slot for Audio Bus Master 5 to receive	data.
	0: Slot 6.	
	1: Slot 11.	
19	Audio Bus Master 4 AC97 Slot Select. Selects slot for Audio Bus Master 4 to transmit	data.
	0: Slot 6.	
	1: Slot 11.	
18	Reserved. Must be set to 0.	
17	Status Tag. (Read Only) The codec status data in bits [15:0] of this register is updated ready, slot1 and slot2 bits in tag slot are all set in current AC97 frame).	in the current AC97 frame. (codec
	0: Not new.	
	1: New, updated in current frame.	



Bit	Description		
16	Codec Status Valid. (Read Only) Indicates if the status in bits [15:0] of this register is valid. This bit is high during slots 3 to 11 of the AC97 frame (i.e., for approximately 14.5 μs), for every frame.		
	0: No.		
	1: Yes.		
15:0	Codec Status. (Read Only) This is the codec status data that is received from the codec in slot 2 on SDATA_IN. Only bits [19:4] are used from slot 2. If this register is read with both bits 16 and 17 of this register set to 1, this field is updated in the current AC97 frame, and codec status data is valid. This bit field is updated only if the codec sent status data.		
Offset 0C	h-0Fh Codec Command Register (R/W) Reset Value: 00000000h		
31:24	Codec Command Address. Address of the codec control register for which the command is being sent. This address goes in slot 1 bits [19:12] on SDATA_OUT.		
23:22	Codec Communication. Indicates the codec that the Core Logic module is communicating with.		
	00: Primary codec		
	01: Secondary codec		
	10: Third codec		
	11: Fourth codec		
	Only 00 and 01 are valid settings for this bit field.		
21:17	Reserved. Must be set to 0.		
16	Codec Command Valid. (Read Only) Indicates if the command in bits [15:0] of this register is valid.		
	0: No.		
	1: Yes.		
	This bit is set by hardware when a codec command is written to the Codec Command register. It remains set until the command has been sent to the codec.		
15:0	Codec Command. This is the command being sent to the codec in bits [19:4] of slot 2 on SDATA_OUT.		
Offset 10h	n-11h Second Level Audio SMI Status Register (RC) Reset Value: 0000h		
	this register contain second level SMI status reporting. Top level is reported at F1BAR0+I/O Offset 00h/02h[1]. Reading this ears the status bits at both the second and top levels. Note that bit 0 has a third level of status reporting which also must be ear".		
	y "Mirror" version of this register exists at F3BAR0+I/O Memory Offset 12h. If the value of the register must be read without e SMI source (and consequently de-asserting SMI), F3BAR0+Memory Offset 12h can be read instead.		
15:8	Reserved. Must be set to 0.		
7	Audio Bus Master 5 SMI Status. Indicates if an SMI was caused by an event occurring on Audio Bus Master 5.		
	0: No.		
	1: Yes.		
	SMI generation is enabled when Audio Bus Master 5 is enabled (F3BAR0+Memory Offset 48h[0] = 1). An SMI is then generated when the End of Page bit is set in the Audio Bus Master 5 SMI Status Register (F3BAR0+Memory).		

Audio Bus Master 4 SMI Status. Indicates if an SMI was caused by an event occurring on Audio Bus Master 4. 0: No.

U. INU

1: Yes

SMI generation is enabled when Audio Bus Master 4 is enabled (F3BAR0+Memory Offset 40h[0] = 1). An SMI is then generated when the End of Page bit is set in the Audio Bus Master 4 SMI Status Register (F3BAR0+Memory Offset 41h[0] = 1).

5 Audio Bus Master 3 SMI Status. Indicates if an SMI was caused by an event occurring on Audio Bus Master 3.

0: No.

1: Yes.

SMI generation is enabled when Audio Bus Master 3 is enabled (F3BAR0+Memory Offset 38h[0] = 1). An SMI is then generated when the End of Page bit is set in the Audio Bus Master 3 SMI Status Register (F3BAR0+Memory Offset 39h[0] = 1).



Description
Audio Bus Master 2 SMI Status. Indicates if an SMI was caused by an event occurring on Audio Bus Master 2.
0: No.
1: Yes.
SMI generation is enabled when Audio Bus Master 2 is enabled (F3BAR0+Memory Offset 30h[0] = 1). An SMI is then generated when the End of Page bit is set in the Audio Bus Master 2 SMI Status Register (F3BAR0+Memory Offset 31h[0] = 1).
Audio Bus Master 1 SMI Status. Indicates if an SMI was caused by an event occurring on Audio Bus Master 1.
0: No.
1: Yes.
SMI generation is enabled when Audio Bus Master 1 is enabled (F3BAR0+Memory Offset 28h[0] = 1). An SMI is then generated when the End of Page bit is set in the Audio Bus Master 1 SMI Status Register (F3BAR0+Memory Offset 29h[0] = 1).
Audio Bus Master 0 SMI Status. Indicates if an SMI was caused by an event occurring on Audio Bus Master 0.
0: No.
1: Yes.
SMI generation is enabled when Audio Bus Master 0 is enabled (F3BAR0+Memory Offset 20h[0] = 1). An SMI is then generated when the End of Page bit is set in the Audio Bus Master 0 SMI Status Register (F3BAR0+Memory Offset 21h[0] = 1).
Codec Serial or GPIO Interrupt SMI Status. Indicates if an SMI was caused by a serial or GPIO interrupt from codec.
0: No.
1: Yes.
SMI generation enabling for codec serial interrupt: F3BAR0+Memory Offset 08h[23] = 1. SMI generation enabling for codec GPIO interrupt: F3BAR0+Memory Offset 00h[30] = 1.
I/O Trap SMI Status. Indicates if an SMI was caused by an I/O trap.
0: No.
1: Yes.
The next level (third level) of SMI status reporting is at F3BAR0+Memory Offset 14h.
n-13h Second Level Audio SMI Status Mirror Register (RO) Reset Value: 0000h
the bits in this register contain second level SMI status reporting. Top level is reported at F1BAR0+I/O Offset 00h/02h[1]. Reading this register does not clear the status bits. See F3BAR0+Memory Offset 10h.
Reserved. Must be set to 0.
Audio Bus Master 5 SMI Status. Indicates if an SMI was caused by an event occurring on Audio Bus Master 5.
0: No.
1: Yes.
SMI generation is enabled when Audio Bus Master 5 is enabled (F3BAR0+Memory Offset 48h[0] = 1). An SMI is then generated when the End of Page bit is set in the SMI Status Register (F3BAR0+Memory Offset 49h[0] = 1). The End of Page bit must be cleared before this bit can be cleared.
Audio Bus Master 4 SMI Status. Indicates if an SMI was caused by an event occurring on Audio Bus Master 4.
0: No.
1: Yes.
SMI generation is enabled when Audio Bus Master 4 is enabled (F3BAR0+Memory Offset 40h[0] = 1). An SMI is then generated when the End of Page bit is set in the SMI Status Register (F3BAR0+Memory Offset 41h[0] = 1). The End of Page bit must be cleared before this bit can be cleared.
Audio Bus Master 3 SMI Status. Indicates if an SMI was caused by an event occurring on Audio Bus Master 3.
0: No.
1: Yes.
SMI generation is enabled when Audio Bus Master 3 is enabled (F3BAR0+Memory Offset 38h[0] = 1). An SMI is then gen-



Bit	Description Description	
4	Audio Bus Master 2 SMI Status. Indicates if an SMI was caused by an event occurring on Audio Bus Master 2.	
	0: No.	
	1: Yes.	
	SMI generation is enabled when Audio Bus Master 2 is enabled (F3BAR0+Memory Offset 30h[0] = 1). An SMI is then generated when the End of Page bit is set in the SMI Status Register (F3BAR0+Memory Offset 31h[0] = 1). The End of Page bit must be cleared before this bit can be cleared.	
3	Audio Bus Master 1 SMI Status. Indicates if an SMI was caused by an event occurring on Audio Bus Master 1.	
	0: No.	
	1: Yes.	
	SMI generation is enabled when Audio Bus Master 1 is enabled (F3BAR0+Memory Offset 28h[0] = 1). An SMI is then generated when the End of Page bit is set in the SMI Status Register (F3BAR0+Memory Offset 29h[0] = 1). The End of Page bit must be cleared before this bit can be cleared.	
2	Audio Bus Master 0 SMI Status. Indicates if an SMI was caused by an event occurring on Audio Bus Master 0.	
	0: No.	
	1: Yes.	
	SMI generation is enabled when Audio Bus Master 0 is enabled (F3BAR0+Memory Offset 20h[0] = 1). An SMI is then generated when the End of Page bit is set in the SMI Status Register (F3BAR0+Memory Offset 21h[0] = 1). The End of Page bit must be cleared before this bit can be cleared.	
1	Codec Serial or GPIO Interrupt SMI Status. Indicates if an SMI was caused by a serial or GPIO interrupt from codec.	
	0: No.	
	1: Yes.	
	SMI generation enabling for codec serial interrupt: F3BAR0+Memory Offset 08h[23] = 1. SMI generation enabling for codec GPIO interrupt: F3BAR0+Memory Offset 00h[30] = 1.	
0	I/O Trap SMI Status. Indicates if an SMI was caused by an I/O trap.	
	0: No.	
	1: Yes.	
	The next level (third level) of SMI status reporting is at F3BAR0+Memory Offset 14h.	
Offset 14h	-17h I/O Trap SMI and Fast Write Status Register (RO/RC) Reset Value: 00000000h	
th	or the four SMI status bits (bits [13:10]), if the activity was a fast write to an even address, no SMI is generated regardless of the DMA, MPU, or Sound Card status. If the activity was a fast write to an odd address, an SMI is generated but bit 13 is set to 1.	
31:24	Fast Path Write Even Access Data. (Read Only) This bit field contains the data from the last Fast Path Write Even access. These bits change only on a fast write to an even address.	
23:16	Fast Path Write Odd Access Data. (Read Only) This bit field contains the data from the last Fast Path Write Odd access. These bits change on a fast write to an odd address, and also on any non-fast write.	
15	Fast Write A1. (Read Only) This bit contains the A1 value for the last Fast Write access.	
14	Read or Write I/O Access. (Read Only) Indicates if the last trapped I/O access was a read or a write.	
	0: Read.	
	1: Write.	
13	Sound Card or FM Trap SMI Status. (Read to Clear) Indicates if an SMI was caused by a trapped I/O access to the Sound Card or FM I/O Trap.	
	0: No.	
	1: Yes. (See the note included in the general description of this register above.)	
	Fast Path Write must be enabled, F3BAR0+Memory Offset 18h[11] = 1, for the SMI to be reported here. If Fast Path Write is disabled, the SMI is reported in bit 10 of this register.	
	This is the third level of SMI status reporting.	
	Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0]. Top level is reported at F1BAR0+I/O Offset 00h/02h[1].	
	SMI generation enabling is at F3BAR0+Memory Offset 18h[2].	



Bit	Description	
12	DMA Trap SMI Status. (Read to Clear) Indicates if an SMI was caused by a trapped I/O access to the DMA I/O Trap.	
	0: No.	
	1: Yes. (See the note included in the general description of this register above.)	
	This is the third level of SMI status reporting.	
	Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0]. Top level is reported at F1BAR0+I/O Offset 00h/02h[1].	
	SMI generation enabling is at F3BAR0+Memory Offset 18h[8:7].	
11	MPU Trap SMI Status. (Read to Clear) Indicates if an SMI was caused by a trapped I/O access to the MPU I/O Trap.	
	No. Yes. (See the note included in the general description of this register above.)	
	This is the third level of SMI status reporting.	
	Second level of SMI status is reported at F3BAR0+Memory Offset 10h/12h[0]. Top level is reported at F1BAR0+I/O Offset 00h/02h[1].	
	SMI generation enabling is at F3BAR0+Memory Offset 18h[6:5].	
10	Sound Card or FM Trap SMI Status. (Read to Clear) Indicates if an SMI was caused by a trapped I/O access to the Sound Card or FM I/O Trap.	
	0: No.	
	1: Yes. (See the note included in the general description of this register above.)	
	Fast Path Write must be disabled, F3BAR0+Memory Offset 18h[11] = 0, for the SMI to be reported here. If Fast Path Write is enabled, the SMI is reported in bit 13 of this register.	
	This is the third level of SMI status reporting. Second level of SMI status is reported at F3BAR0+Memory Offset 10h/12h[0]. Top level is reported at F1BAR0+I/O Offset 00h/02h[1].	
	SMI generation enabling is at F3BAR0+Memory Offset 18h[2].	
9:0	X-Bus Address (Read Only). This bit field] contains the captured ten bits of X-Bus address.	
9:0 Offset 18h		
Offset 18h	n-19h I/O Trap SMI Enable Register (R/W)Reset Value: 0000h	
Offset 18h	h-19h I/O Trap SMI Enable Register (R/W)Reset Value: 0000h Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). 0: Disable.	
Offset 18h	h-19h I/O Trap SMI Enable Register (R/W)Reset Value: 0000h Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). 0: Disable. 1: Enable.	
Offset 18h	h-19h I/O Trap SMI Enable Register (R/W)Reset Value: 0000h Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). 0: Disable.	
Offset 18h	h-19h I/O Trap SMI Enable Register (R/W)Reset Value: 0000h Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). 0: Disable. 1: Enable.	
Offset 18h 15:12 11	Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). 0: Disable. 1: Enable. In Fast Path Write, the Core Logic module responds to writes to addresses: 388h, 38Ah, 38B, 2x0h, 2x2h, and 2x8h. Fast Read. These two bits hold part of the response that the Core Logic module returns for reads to several I/O locations. High DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port C0h-DFh, an SMI is generated.	
0ffset 18h 15:12 11 10:9	Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). 0: Disable. 1: Enable. In Fast Path Write, the Core Logic module responds to writes to addresses: 388h, 38Ah, 38B, 2x0h, 2x2h, and 2x8h. Fast Read. These two bits hold part of the response that the Core Logic module returns for reads to several I/O locations. High DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port C0h-DFh, an SMI is generated. 0: Disable.	
0ffset 18h 15:12 11 10:9	Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). Disable. In Fast Path Write, the Core Logic module responds to writes to addresses: 388h, 38Ah, 38B, 2x0h, 2x2h, and 2x8h. Fast Read. These two bits hold part of the response that the Core Logic module returns for reads to several I/O locations. High DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port C0h-DFh, an SMI is generated. Disable. Enable.	
0ffset 18h 15:12 11 10:9	Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). Disable. In Fast Path Write, the Core Logic module responds to writes to addresses: 388h, 38Ah, 38B, 2x0h, 2x2h, and 2x8h. Fast Read. These two bits hold part of the response that the Core Logic module returns for reads to several I/O locations. High DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port Coh-DFh, an SMI is generated. Disable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1].	
0ffset 18h 15:12 11 10:9	Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). Disable. In Fast Path Write, the Core Logic module responds to writes to addresses: 388h, 38Ah, 38B, 2x0h, 2x2h, and 2x8h. Fast Read. These two bits hold part of the response that the Core Logic module returns for reads to several I/O locations. High DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port C0h-DFh, an SMI is generated. Disable. Enable.	
0ffset 18h 15:12 11 10:9	Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). Disable. I: Enable. In Fast Path Write, the Core Logic module responds to writes to addresses: 388h, 38Ah, 38B, 2x0h, 2x2h, and 2x8h. Fast Read. These two bits hold part of the response that the Core Logic module returns for reads to several I/O locations. High DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port Coh-DFh, an SMI is generated. Disable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0].	
15:12 11 10:9 8	Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). 0: Disable. 1: Enable. In Fast Path Write, the Core Logic module responds to writes to addresses: 388h, 38Ah, 38B, 2x0h, 2x2h, and 2x8h. Fast Read. These two bits hold part of the response that the Core Logic module returns for reads to several I/O locations. High DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port Coh-DFh, an SMI is generated. 0: Disable. 1: Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0]. Third level SMI status is reported at F3BAR0+Memory Offset 14h[12].	
15:12 11 10:9 8	Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). 0: Disable. 1: Enable. In Fast Path Write, the Core Logic module responds to writes to addresses: 388h, 38Ah, 38B, 2x0h, 2x2h, and 2x8h. Fast Read. These two bits hold part of the response that the Core Logic module returns for reads to several I/O locations. High DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port Coh-DFh, an SMI is generated. 0: Disable. 1: Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0]. Third level SMI status is reported at F3BAR0+Memory Offset 14h[12]. Low DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port 00h-0Fh, an SMI is generated.	
15:12 11 10:9 8	Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). 0: Disable. 1: Enable. In Fast Path Write, the Core Logic module responds to writes to addresses: 388h, 38Ah, 38B, 2x0h, 2x2h, and 2x8h. Fast Read. These two bits hold part of the response that the Core Logic module returns for reads to several I/O locations. High DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port Coh-DFh, an SMI is generated. 0: Disable. 1: Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0]. Third level SMI status is reported at F3BAR0+Memory Offset 14h[12]. Low DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port 00h-0Fh, an SMI is generated. 0: Disable.	
15:12 11 10:9 8	Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). Disable. In Fast Path Write, the Core Logic module responds to writes to addresses: 388h, 38Ah, 38B, 2x0h, 2x2h, and 2x8h. Fast Read. These two bits hold part of the response that the Core Logic module returns for reads to several I/O locations. High DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port C0h-DFh, an SMI is generated. Disable. Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0]. Third level SMI status is reported at F3BAR0+Memory Offset 14h[12]. Low DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port 00h-0Fh, an SMI is generated. Disable. Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0].	
0ffset 18h 15:12 11 10:9 8	Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). 0: Disable. 1: Enable. In Fast Path Write, the Core Logic module responds to writes to addresses: 388h, 38Ah, 38B, 2x0h, 2x2h, and 2x8h. Fast Read. These two bits hold part of the response that the Core Logic module returns for reads to several I/O locations. High DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port C0h-DFh, an SMI is generated. 0: Disable. 1: Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0]. Third level SMI status is reported at F3BAR0+Memory Offset 14h[12]. Low DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port 00h-0Fh, an SMI is generated. 0: Disable. 1: Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F1BAR0+I/O Offset 10h/12h[0]. Third level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0]. Third level SMI status is reported at F3BAR0+Memory Offset 14h[12].	
0ffset 18h 15:12 11 10:9 8	Reserved. Must be set to 0. Fast Path Write Enable. Fast Path Write (an SMI is not generated on certain writes to specified addresses). 0: Disable. 1: Enable. In Fast Path Write, the Core Logic module responds to writes to addresses: 388h, 38Ah, 38B, 2x0h, 2x2h, and 2x8h. Fast Read. These two bits hold part of the response that the Core Logic module returns for reads to several I/O locations. High DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port C0h-DFh, an SMI is generated. 0: Disable. 1: Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0]. Third level SMI status is reported at F3BAR0+Memory Offset 14h[12]. Low DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port 00h-0Fh, an SMI is generated. 0: Disable. 1: Enable. Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1]. Second level SMI status is reported at F3BAR0+Memory Offset 14h[12]. Low DMA I/O Trap. If this bit is enabled and an access occurs at I/O Port 330h-331h, an SMI is generated. High MPU I/O Trap. If this bit is enabled and an access occurs at I/O Port 330h-331h, an SMI is generated.	



Bit	Description		
5	Low MPU I/O Trap. If this bit is enabled and an access occurs at I/O Port 300h-301h, an SMI is generated.		
	0: Disable.		
	1: Enable.		
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1].		
	Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0].		
	Third level SMI status is reported at F3BAR0+Memory Offset 14h[11].		
4	Fast Path Read Enable/SMI Disable. When asserted, read Fast Path (an SMI is not generated on reads from specified		
	addresses).		
	0: Disable.		
	1: Enable.		
	In Fast Path Read the Core Logic module responds to reads of addresses: 388h-38Bh; 2x0h, 2x1, 2x2h, 2x3, 2x8 and 2x9h.		
	If neither sound card nor FM I/O mapping is enabled, then status read trapping is not possible.		
3	FM I/O Trap. If this bit is enabled and an access occurs at I/O Port 388h-38Bh, an SMI is generated.		
	0: Disable.		
	1: Enable.		
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1].		
	Second level SMI status is reported at F3BAR0+Memory Offset 10h/12h[0].		
2	Sound Card I/O Trap. If this bit is enabled and an access occurs in the address ranges selected by bits [1:0], an SMI is		
	generated. 0: Disable.		
	1: Enable.		
	Top level SMI status is reported at F1BAR0+I/O Offset 00h/02h[1].		
	Second level SMI status is reported at F1BAR0+Memory Offset 10h/12h[0].		
	Third level SMI status is reported at F3BAR0+Memory Offset 14h[10].		
1:0	Sound Card Address Range Select. These bits select the address range for the sound card I/O trap.		
	00: I/O Port 220h-22Fh 10: I/O Port 260h-26Fh		
	01: I/O Port 240h-24Fh 11: I/O Port 280h-28Fh		
Offset 1Ah			
	n-1Bh Internal IRQ Enable Register (R/W) Reset Value: 0000h		
15	n-1Bh Internal IRQ Enable Register (R/W) Reset Value: 0000h IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use.		
15			
15	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use.		
15	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External.		
	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal.		
	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use.		
	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External.		
14	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal.		
14	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal. Reserved. Must be set to 0.		
14	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal. Reserved. Must be set to 0. IRQ12 Internal. Configures IRQ12 for internal (software) or external (hardware) use.		
14	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal. Reserved. Must be set to 0. IRQ12 Internal. Configures IRQ12 for internal (software) or external (hardware) use. 0: External.		
14 13 12	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal. Reserved. Must be set to 0. IRQ12 Internal. Configures IRQ12 for internal (software) or external (hardware) use. 0: External. 1: Internal.		
14 13 12	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal. Reserved. Must be set to 0. IRQ12 Internal. Configures IRQ12 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ11 Internal. Configures IRQ11 for internal (software) or external (hardware) use.		
14 13 12	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal. Reserved. Must be set to 0. IRQ12 Internal. Configures IRQ12 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ11 Internal. Configures IRQ11 for internal (software) or external (hardware) use. 0: External.		
14 13 12	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal. Reserved. Must be set to 0. IRQ12 Internal. Configures IRQ12 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ11 Internal. Configures IRQ11 for internal (software) or external (hardware) use. 0: External. IRQ11 Internal. Configures IRQ11 for internal (software) or external (hardware) use. 1: Internal.		
14 13 12	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal. Reserved. Must be set to 0. IRQ12 Internal. Configures IRQ12 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ11 Internal. Configures IRQ11 for internal (software) or external (hardware) use. 0: External. IRQ10 Internal. Configures IRQ10 for internal (software) or external (hardware) use.		
14 13 12	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal. Reserved. Must be set to 0. IRQ12 Internal. Configures IRQ12 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ11 Internal. Configures IRQ11 for internal (software) or external (hardware) use. 0: External. IRQ11 Internal. Configures IRQ11 for internal (software) or external (hardware) use. 0: External. IRQ10 Internal. Configures IRQ10 for internal (software) or external (hardware) use. 0: External.		
14 13 12 11	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal. Reserved. Must be set to 0. IRQ12 Internal. Configures IRQ12 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ11 Internal. Configures IRQ11 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ10 Internal. Configures IRQ10 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ10 Internal. Configures IRQ10 for internal (software) or external (hardware) use. 0: External. 1: Internal.		
14 13 12 11	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal. Reserved. Must be set to 0. IRQ12 Internal. Configures IRQ12 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ11 Internal. Configures IRQ11 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ10 Internal. Configures IRQ10 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ10 Internal. Configures IRQ10 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ9 Internal. Configures IRQ9 for internal (software) or external (hardware) use.		
14 13 12 11	IRQ15 Internal. Configures IRQ15 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ14 Internal. Configures IRQ14 for internal (software) or external (hardware) use. 0: External. 1: Internal. Reserved. Must be set to 0. IRQ12 Internal. Configures IRQ12 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ11 Internal. Configures IRQ11 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ10 Internal. Configures IRQ10 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ10 Internal. Configures IRQ10 for internal (software) or external (hardware) use. 0: External. 1: Internal. IRQ9 Internal. Configures IRQ9 for internal (software) or external (hardware) use. 0: External.		



Bit	Description	
7	IRQ7 Internal. Configures IRQ7 for internal (software) or external (hardware) use.	
	0: External.	
	1: Internal.	
6	Reserved. Must be set to 0.	
5	IRQ5 Internal. Configures IRQ5 for internal (software) or external (hardware) use.	
-	0: External.	
	1: Internal.	
4	IRQ4 Internal. Configures IRQ4 for internal (software) or external (hardware) use.	
	0: External.	
	1: Internal.	
3	IRQ3 Internal. Configures IRQ3 for internal (software) or external (hardware) use.	
-	0: External.	
	1: Internal.	
2	Reserved. Must be set to 0.	
1	IRQ1 Internal. Configures IRQ1 for internal (software) or external (hardware) use.	
	0: External.	
	1: Internal.	
0	Reserved. Must be set to 0.	
Offset 10		Reset Value: 00000000h
	Bits 31:16 of this register are Write Only. Reads to these bits always return a value of 0.	Neset value. 00000001
31	Mask Internal IRQ15. (Write Only)	
31	0: Disable.	
	1: Enable.	
30	Mask Internal IRQ14. (Write Only)	
00	0: Disable.	
	1: Enable.	
29	Reserved. (Write Only) Must be set to 0.	
28	Mask Internal IRQ12. (Write Only)	
	0: Disable.	
	1: Enable.	
27	Mask Internal IRQ11. (Write Only)	
	0: Disable.	
	1: Enable.	
	Mask Internal IRQ10. (Write Only)	
26		
26		
26	0: Disable. 1: Enable.	
	0: Disable. 1: Enable.	
26	0: Disable.	
	0: Disable. 1: Enable. Mask Internal IRQ9. (Write Only)	
25	0: Disable. 1: Enable. Mask Internal IRQ9. (Write Only) 0: Disable. 1: Enable.	
	0: Disable. 1: Enable. Mask Internal IRQ9. (Write Only) 0: Disable. 1: Enable. Reserved. (Write Only) Must be set to 0.	
25	0: Disable. 1: Enable. Mask Internal IRQ9. (Write Only) 0: Disable. 1: Enable.	
25	0: Disable. 1: Enable. Mask Internal IRQ9. (Write Only) 0: Disable. 1: Enable. Reserved. (Write Only) Must be set to 0. Mask Internal IRQ7. (Write Only)	
25 24 23	0: Disable. 1: Enable. Mask Internal IRQ9. (Write Only) 0: Disable. 1: Enable. Reserved. (Write Only) Must be set to 0. Mask Internal IRQ7. (Write Only) 0: Disable. 1: Enable.	
25	0: Disable. 1: Enable. Mask Internal IRQ9. (Write Only) 0: Disable. 1: Enable. Reserved. (Write Only) Must be set to 0. Mask Internal IRQ7. (Write Only) 0: Disable. 1: Enable. Reserved. (Write Only) Must be set to 0.	
25 24 23	0: Disable. 1: Enable. Mask Internal IRQ9. (Write Only) 0: Disable. 1: Enable. Reserved. (Write Only) Must be set to 0. Mask Internal IRQ7. (Write Only) 0: Disable. 1: Enable.	



Bit	Description			
20	Mask Internal IRQ4. (Write Only)			
20	0: Disable.			
	1: Enable.			
10	Mask Internal IRQ3. (Write Only)			
19	0: Disable.			
	1: Enable.			
18				
17				
''	0: Disable.			
	1: Enable.			
16	Reserved. (Write Only) Must be set to 0.			
15	Assert Masked Internal IRQ15.			
	0: Disable.			
	1: Enable.			
14	Assert Masked Internal IRQ14.			
	0: Disable.			
	1: Enable.			
13	Reserved. Set to 0.			
12	Assert Masked Internal IRQ12.			
	0: Disable.			
	1: Enable.			
11	Assert masked internal IRQ11.			
	0: Disable.			
	1: Enable.			
10	Assert Masked Internal IRQ10.			
	0: Disable.			
	1: Enable.			
9	Assert Masked Internal IRQ9.			
	0: Disable.			
	1: Enable.			
8	Reserved. Set to 0.			
7	Assert Masked Internal IRQ7.			
	0: Disable.			
	1: Enable.			
6	Reserved. Set to 0.			
5	Assert Masked Internal IRQ5.			
	0: Disable.			
	1: Enable.			
4	Assert Masked Internal IRQ4.			
	0: Disable.			
	1: Enable.			
3	Assert Masked Internal IRQ3.			
	0: Disable.			
	1: Enable.			
2	Reserved. Must be set to 0.			



Bit	Description				
1	Assert Masked Internal IRQ1.				
	0: Disable.				
	1: Enable.				
0	Reserved. Must be set to	0.			
Offset 20	h	Audio Bus Master 0 Command Register (R/W)	Reset Value: 00h		
Audio Bus	Master 0: Output to codec;	32-bit; Left and Right Channels; Slots 3 and 4.			
7:4	Reserved. Must be set to	0. Must return 0 on reads.			
3	Read or Write Control. Sets the transfer direction of the Audio Bus Master.				
	0: PCI reads are performed.				
	1: PCI writes are performed.				
	This bit must be set to 0 (read), and should not be changed when the bus master is active.				
2:1	Reserved. Must be set to 0. Must return 0 on reads.				
0	Bus Master Control. Controls the state of the Audio Bus Master.				
	0: Disable.				
	1: Enable.				
	Setting this bit to 1 enables the bus master to begin data transfers.				
		the bus master must either be paused, or reach EOT. Writing 0 to predictable behavior (and may crash the bus master state machina PCI recet			
065-4-041	'		Deart Value, 00h		
Offset 21		Audio Bus Master 0 SMI Status Register (RC)	Reset Value: 00h		
	1	32-bit; Left and Right Channels; Slots 3 and 4.			
7:2	Reserved.				
1	Bus Master Error. Indicates if hardware encountered a second EOP before software has cleared the first. 0: No.				
	1: Yes.				
	If hardware encounters a second EOP (end of page) before software has cleared the first, it causes the bus master to pause until this register is read to clear the error.				
0	End of Page. Indicates if the bus master transferred data which is marked by EOP bit in the PRD table (bit 30).				
	0: No.				
	1: Yes.				
Offset 22	h-23h	Not Used			
			D ()/- 00000000 -		
Offset 24		Audio Bus Master 0 PRD Table Address (R/W)	Reset Value: 00000000h		
	<u>, </u>	32-bit; Left and Right Channels; Slots 3 and 4.			
31:2	Pointer to the Physical Region Descriptor Table. This bit field contains a PRD table pointer for Audio Bus Master 0.				
	When written, this register points to the first entry in a PRD table. Once Audio Bus Master 0 is enabled (Command Register bit 0 = 1), it loads the pointer and updates this register (by adding 08h) so that it points to the next PRD.				
	When read, this register p	oints to the next PRD.			
1:0	Reserved. Must be set to				
		otor (PRD) table consists of one or more entries - each describ d. Each entry consists of two DWORDs.	ing a memory region to or from		
	DWORD 0: DWORD 1:	[31:0] = Memory Region Physical Base Address 31 = End of Table Flag 30 = End of Page Flag 29 = Loop Flag (JMP) [28:16] = Reserved (0) [15:0] = Byte Count of the Region (Size)			



Table 6-38. F3BAR0+Memory Offset: Audio Configuration Registers (Continued)

Bit	Description		· · · · · · · · · · · · · · · · · · ·		
Offset 28	Bh	Audio Bus Master 1 Command Register (R/W)	Reset Value: 00h		
Audio Bus	s Master 1: Input from code	c; 32-Bit; Left and Right Channels; Slots 3 and 4.			
7:4	Reserved. Must be set to 0. Must return 0 on reads.				
3	Read or Write Control.	Set the transfer direction of Audio Bus Master 1.			
	0: PCI reads are perform	ned.			
	1: PCI writes are perform	med.			
	This bit must be set to 1	(write) and should not be changed when the bus master is active.			
2:1	Reserved. Must be set to	0. Must return 0 on reads.			
0	Bus Master Control. Co	ntrols the state of the Audio Bus Master 1.			
	0: Disable.				
	1: Enable.				
	paused or reached EOT.	es the bus master to begin data transfers. When writing this bit to Writing this bit to 0 while the bus master is operating results in un master state machine). The only recovery from this condition is a	predictable behavior (and may		
Offset 29)h	Audio Bus Master 1 SMI Status Register (RC)	Reset Value: 00h		
Audio Bus	s Master 1: Input from code	c; 32-Bit; Left and Right Channels; Slots 3 and 4.			
7:2	Reserved.				
1	Bus Master Error. Indicates if hardware encountered a second EOP before software has cleared the first.				
	0: No.				
	1: Yes.				
If hardware encounters a second EOP (end of page) before software has clear until this register is read to clear the error.			t causes the bus master to pause		
0	End of Page. Indicates i	the bus master transferred data which is marked by EOP bit in th	ne PRD table (bit 30).		
	0: No.				
	1: Yes.				
Offset 2A	Ah-2Bh	Not Used			
Offset 20	Ch-2Fh	Audio Bus Master 1 PRD Table Address (R/W)	Reset Value: 00000000h		
Audio Bus	s Master 1: Input from code	c; 32-Bit; Left and Right Channels; Slots 3 and 4.			
31:2	Pointer to the Physical Region Descriptor Table. This bit field is a PRD table pointer for Audio Bus Master 1.				
	When written, this register points to the first entry in a PRD table. Once Audio Bus Master 1 is enabled (Command Register				
	bit 0 = 1), it loads the pointer and updates this register (by adding 08h) so that it points to the next PRD.				
	When read, this register points to the next PRD.				
1:0	Reserved. Must be set to	o 0.			
		iptor (PRD) table consists of one or more entries - each described. Each entry consists of two DWORDs.	oing a memory region to or from		
	DWORD 0:	[31:0] = Memory Region Physical Base Address			
	DWORD 1:	31 = End of Table Flag			
		30 = End of Page Flag 29 = Loop Flag (JMP)			
		[28:16] = Reserved (0)			
		[15:0] = Byte Count of the Region (Size)			



Table 6-38. F3BAR0+Memory Offset: Audio Configuration Registers (Continued)

Bit	Description		
Offset 30)h	Audio Bus Master 2 Command Register (R/W)	Reset Value: 00h
Audio Bus	s Master 2: Output to coded	; 16-Bit; Slot 5.	
7:4	Reserved. Must be set t	0 0. Must return 0 on reads.	
3	Read or Write Control.	Sets the transfer direction of Audio Bus Master 2.	
	0: PCI reads are perform	med.	
	1: PCI writes are perfor	med.	
	This bit must be set to 0	(read) and should not be changed when the bus master is active.	
2:1	Reserved. Must be set t	0 0. Must return 0 on reads.	
0	Bus Master Control. Co	ntrols the state of the Audio Bus Master 2.	
	0: Disable.		
	1: Enable.		
	paused or reached EOT.	es the bus master to begin data transfers. When writing 0 to this bit Writing 0 to this bit while the bus master is operating results in unpute machine). The only recovery from this condition is a PCI reset.	
Offset 31	h	Audio Bus Master 2 SMI Status Register (RC)	Reset Value: 00h
Audio Bus	s Master 2: Output to coded	; 16-Bit; Slot 5.	
7:2	Reserved.		
			la a sa al da a Carat
1	Bus Master Error. Indica	ates if hardware encountered a second EOP before software has c	leared the first.
1	Bus Master Error. Indicators O: No.	ates if hardware encountered a second EOP before software has c	leared the first.
1		ates if hardware encountered a second EOP before software has c	leared the first.
1	0: No. 1: Yes.	second EOP (end of page) before software has cleared the first, it	
0	O: No. Head of the second of	second EOP (end of page) before software has cleared the first, it	causes the bus master to pause
·	O: No. Head of the second of	second EOP (end of page) before software has cleared the first, it to clear the error.	causes the bus master to pause
·	O: No. I: Yes. If hardware encounters a until this register is read End of Page. Indicates i	second EOP (end of page) before software has cleared the first, it to clear the error.	causes the bus master to pause
·	O: No. I: Yes. If hardware encounters a until this register is read End of Page. Indicates i O: No. I: Yes.	second EOP (end of page) before software has cleared the first, it to clear the error.	causes the bus master to pause
0	0: No. 1: Yes. If hardware encounters a until this register is read End of Page. Indicates i 0: No. 1: Yes.	second EOP (end of page) before software has cleared the first, it to clear the error. If the Bus master transferred data which is marked by the EOP bit in	causes the bus master to pause n the PRD table (bit 30).
0 Offset 32 Offset 34	0: No. 1: Yes. If hardware encounters a until this register is read End of Page. Indicates i 0: No. 1: Yes.	second EOP (end of page) before software has cleared the first, it to clear the error. If the Bus master transferred data which is marked by the EOP bit in Not Used Audio Bus Master 2 PRD Table Address (R/W)	causes the bus master to pause in the PRD table (bit 30). Reset Value: 00h
0 Offset 32 Offset 34	0: No. 1: Yes. If hardware encounters a until this register is read End of Page. Indicates i 0: No. 1: Yes. 2h-33h 4h-37h 5 Master 2: Output to coded	second EOP (end of page) before software has cleared the first, it to clear the error. If the Bus master transferred data which is marked by the EOP bit in Not Used Audio Bus Master 2 PRD Table Address (R/W)	causes the bus master to pause n the PRD table (bit 30). Reset Value: 00h Reset Value: 00000000h
0 Offset 32 Offset 34 Audio Bus	0: No. 1: Yes. If hardware encounters a until this register is read End of Page. Indicates i 0: No. 1: Yes. Ith-33h Ith-37h Is Master 2: Output to coded Pointer to the Physical When written, this field p	second EOP (end of page) before software has cleared the first, it to clear the error. If the Bus master transferred data which is marked by the EOP bit in Not Used Audio Bus Master 2 PRD Table Address (R/W); 16-Bit; Slot 5.	causes the bus master to pause In the PRD table (bit 30). Reset Value: 00h Reset Value: 00000000h Iter for Audio Bus Master 2. enabled (Command Register bit
0 Offset 32 Offset 34 Audio Bus	0: No. 1: Yes. If hardware encounters a until this register is read End of Page. Indicates i 0: No. 1: Yes. Ith-33h Ith-37h Is Master 2: Output to coded Pointer to the Physical When written, this field p	second EOP (end of page) before software has cleared the first, it to clear the error. If the Bus master transferred data which is marked by the EOP bit in Not Used Not Used Audio Bus Master 2 PRD Table Address (R/W) ; 16-Bit; Slot 5. Region Descriptor Table. This bit field contains a PRD table point oints to the first entry in a PRD table. Once Audio Bus Master 2 is a rand updates this register (by adding 08h) so that it points to the r	causes the bus master to pause In the PRD table (bit 30). Reset Value: 00h Reset Value: 00000000h Iter for Audio Bus Master 2. enabled (Command Register bit
0 Offset 32 Offset 34 Audio Bus	0: No. 1: Yes. If hardware encounters a until this register is read End of Page. Indicates i 0: No. 1: Yes. Ph-33h Ph-37h S Master 2: Output to coded When written, this field p 0 = 1), it loads the pointer	second EOP (end of page) before software has cleared the first, it to clear the error. If the Bus master transferred data which is marked by the EOP bit in Not Used Not Used Audio Bus Master 2 PRD Table Address (R/W) ; 16-Bit; Slot 5. Region Descriptor Table. This bit field contains a PRD table point oints to the first entry in a PRD table. Once Audio Bus Master 2 is a rand updates this register (by adding 08h) so that it points to the repoints to the next PRD.	causes the bus master to pause In the PRD table (bit 30). Reset Value: 00h Reset Value: 00000000h Iter for Audio Bus Master 2. enabled (Command Register bit
Offset 32 Offset 34 Audio Bus 31:2	0: No. 1: Yes. If hardware encounters a until this register is read End of Page. Indicates i 0: No. 1: Yes. 2h-33h 3h-37h 5 Master 2: Output to coded Pointer to the Physical When written, this field p 0 = 1), it loads the pointe When read, this register Reserved. Must be set to	second EOP (end of page) before software has cleared the first, it to clear the error. If the Bus master transferred data which is marked by the EOP bit in Not Used Not Used Audio Bus Master 2 PRD Table Address (R/W) ; 16-Bit; Slot 5. Region Descriptor Table. This bit field contains a PRD table point oints to the first entry in a PRD table. Once Audio Bus Master 2 is a rand updates this register (by adding 08h) so that it points to the repoints to the next PRD.	causes the bus master to pause In the PRD table (bit 30). Reset Value: 00h Reset Value: 0000000h Iter for Audio Bus Master 2. enabled (Command Register bit next PRD.
Offset 32 Offset 34 Audio Bus 31:2	0: No. 1: Yes. If hardware encounters a until this register is read End of Page. Indicates i 0: No. 1: Yes. 2h-33h 3h-37h 5 Master 2: Output to coded Pointer to the Physical When written, this field p 0 = 1), it loads the pointe When read, this register Reserved. Must be set to	second EOP (end of page) before software has cleared the first, it to clear the error. If the Bus master transferred data which is marked by the EOP bit in the Bus master transferred data which is marked by the EOP bit in the Bus master transferred data which is marked by the EOP bit in the Bus master transferred data which is marked by the EOP bit in the Bus master 2 PRD Table Address (R/W); 16-Bit; Slot 5. Region Descriptor Table. This bit field contains a PRD table point oints to the first entry in a PRD table. Once Audio Bus Master 2 is a rand updates this register (by adding 08h) so that it points to the repoints to the next PRD. Do 0. iptor (PRD) table consists of one or more entries - each describing to the property of the proper	causes the bus master to pause In the PRD table (bit 30). Reset Value: 00h Reset Value: 0000000h Iter for Audio Bus Master 2. enabled (Command Register bit next PRD.
Offset 32 Offset 34 Audio Bus 31:2	0: No. 1: Yes. If hardware encounters a until this register is read End of Page. Indicates i 0: No. 1: Yes. Ph-33h Ph-37h In Shaster 2: Output to coded Pointer to the Physical When written, this field p 0 = 1), it loads the pointer When read, this register Reserved. Must be set to the Physical Region Description of the Physi	second EOP (end of page) before software has cleared the first, it to clear the error. If the Bus master transferred data which is marked by the EOP bit in Not Used Not Used Audio Bus Master 2 PRD Table Address (R/W) 16-Bit; Slot 5. Region Descriptor Table. This bit field contains a PRD table point oints to the first entry in a PRD table. Once Audio Bus Master 2 is or and updates this register (by adding 08h) so that it points to the repoints to the next PRD. 10 0. 10 0. 11 iptor (PRD) table consists of one or more entries - each describing ed. Each entry consists of two DWORDs. 13 1:0] = Memory Region Physical Base Address 31 = End of Table Flag	causes the bus master to pause In the PRD table (bit 30). Reset Value: 00h Reset Value: 0000000h Iter for Audio Bus Master 2. enabled (Command Register bit next PRD.
Offset 32 Offset 34 Audio Bus 31:2	0: No. 1: Yes. If hardware encounters a until this register is read End of Page. Indicates i 0: No. 1: Yes. Ch-33h Ch-37h Is Master 2: Output to coded Pointer to the Physical When written, this field p 0 = 1), it loads the pointe When read, this register Reserved. Must be set to the Physical Region Description of the Physica	second EOP (end of page) before software has cleared the first, it to clear the error. If the Bus master transferred data which is marked by the EOP bit in Not Used Not Used Audio Bus Master 2 PRD Table Address (R/W) ; 16-Bit; Slot 5. Region Descriptor Table. This bit field contains a PRD table point oints to the first entry in a PRD table. Once Audio Bus Master 2 is a rand updates this register (by adding 08h) so that it points to the repoints to the next PRD. 5 0. iptor (PRD) table consists of one or more entries - each describined. Each entry consists of two DWORDs. [31:0] = Memory Region Physical Base Address 31 = End of Table Flag 30 = End of Page Flag	causes the bus master to pause In the PRD table (bit 30). Reset Value: 00h Reset Value: 0000000h Iter for Audio Bus Master 2. enabled (Command Register bit next PRD.
Offset 32 Offset 34 Audio Bus 31:2	0: No. 1: Yes. If hardware encounters a until this register is read End of Page. Indicates i 0: No. 1: Yes. Ch-33h Ch-37h Is Master 2: Output to coded Pointer to the Physical When written, this field p 0 = 1), it loads the pointe When read, this register Reserved. Must be set to the Physical Region Description of the Physica	second EOP (end of page) before software has cleared the first, it to clear the error. If the Bus master transferred data which is marked by the EOP bit in Not Used Not Used Audio Bus Master 2 PRD Table Address (R/W) 16-Bit; Slot 5. Region Descriptor Table. This bit field contains a PRD table point oints to the first entry in a PRD table. Once Audio Bus Master 2 is or and updates this register (by adding 08h) so that it points to the repoints to the next PRD. 10 0. 10 0. 11 iptor (PRD) table consists of one or more entries - each describing ed. Each entry consists of two DWORDs. 13 1:0] = Memory Region Physical Base Address 31 = End of Table Flag	causes the bus master to pause In the PRD table (bit 30). Reset Value: 00h Reset Value: 00000000h Iter for Audio Bus Master 2. enabled (Command Register bit next PRD.



Table 6-38. F3BAR0+Memory Offset: Audio Configuration Registers (Continued)

Bit	Description					
Offset 38	Bh	Audio Bus Master 3 Command Register (R/W)	Reset Value: 00h			
Audio Bu	s Master 3: Input from code	c; 16-Bit; Slot 5.				
7:4	Reserved. Must be set t	0. Must return 0 on reads.				
3	Read or Write Control.	Sets the transfer direction of Audio Bus Master 3.				
	0: PCI reads are perform	med.				
	1: PCI writes are perfor	med.				
	This bit must be set to 1	(write) and should not be changed when the bus master is active				
2:1	Reserved. Must be set t	0 0. Must return 0 on reads.				
0	Bus Master Control. Co	ntrols the state of the Audio Bus Master 3.				
	0: Disable.					
	1: Enable.					
	paused or have reached	es the bus master to begin data transfers. When writing 0 to this I EOT. Writing 0 to this bit while the bus master is operating results er state machine). The only recovery from this condition is a PCI re-	s in unpredictable behavior (and			
Offset 39)h	Audio Bus Master 3 SMI Status Register (RC)	Reset Value: 00h			
Audio Bu	s Master 3: Input from code	c; 16-Bit; Slot 5.				
7:2	Reserved.					
1	Bus Master Error. Indicates if hardware encountered a second EOP before software cleared the first.					
	0: No.					
	1: Yes.	1: Yes.				
If hardware encounters a second EOP (end of page) before software cleared the first, it causes the bus mauntil this register is read to clear the error.						
0	End of Page. Indicates i	f the bus master transferred data which is marked by the EOP bit	in the PRD table (bit 30).			
	0: No.					
	1: Yes.					
Offset 3A	Ah-3Bh	Not Used				
Offset 30	Ch-3Fh	Audio Bus Master 3 PRD Table Address (R/W)	Reset Value: 00000000h			
Audio Bu	s Master 3: Input from code	• • •				
31:2	Pointer to the Physical	Region Descriptor Table. This bit field contains is a PRD table	pointer for Audio Bus Master 3.			
	When written, this field points to the first entry in a PRD table. Once Audio Bus Master 3 is enabled (Command Register bit					
	0 = 1), it loads the pointer and updates this register (by adding 08h) so that it points to the next PRD.					
When read, this register points to the next PRD.						
1:0	Reserved. Must be set t	o 0.				
		iptor (PRD) table consists of one or more entries - each descried. Each entry consists of two DWORDs.	bing a memory region to or from			
	DWORD 0:	[31:0] = Memory Region Physical Base Address				
	DWORD 1:	31 = End of Table Flag				
		30 = End of Page Flag 29 = Loop Flag (JMP)				
		[28:16] = Reserved (0)				
		[15:0] = Byte Count of the Region (Size)				



Table 6-38. F3BAR0+Memory Offset: Audio Configuration Registers (Continued)

Bit	Description		
Offset 40I	1	Audio Bus Master 4 Command Register (R/W)	Reset Value: 00h
Audio Bus	Master 4: Output to codec;	16-Bit; Slot 6 or 11 (F3BAR0+Memory Offset 08h[19] selects slot).	
7:4	Reserved. Must be set to 0. Must return 0 on reads.		
3	Read or Write Control. Set the transfer direction of Audio Bus Master 4.		
	0: PCI reads are performe	ed.	
	1: PCI writes are perform	ed.	
	This bit must be set to 0 (r	ead) and should not be changed when the bus master is active.	
2:1	Reserved. Must be set to	0. Must return 0 on reads.	
0	Bus Master Control. Con	trols the state of the Audio Bus Master 4.	
	0: Disable.		
	1: Enable.		
	paused or have reached E	s the bus master to begin data transfers. When writing 0 to this bit, the OT. Writing 0 to this bit while the bus master is operating, results in ustate machine). The only recovery from this condition is a PCI reset.	unpredictable behavior (and
Offset 41I	1	Audio Bus Master 4 SMI Status Register (RC)	Reset Value: 00h
Audio Bus	Master 4: Output to codec;	16-Bit; Slot 6 or 11 (F3BAR0+Memory Offset 08h[19] selects slot).	
7:2	Reserved.		
1	Bus Master Error. Indicate	es if hardware encountered a second EOP before software cleared t	he first.
	0: No.		
	1: Yes.		
	If hardware encounters a suntil this register is read to	second EOP (end of page) before software cleared the first, it causes clear the error.	s the bus master to pause
0	End of Page. Bus master	transferred data which is marked by the EOP bit in the PRD table (b	t 30).
	0: No.		
	1: Yes.		
Offset 42I	n-43h	Not Used	
Offset 44I	n-47h	Audio Bus Master 4 PRD Table Address (R/W)	Reset Value: 00000000h
Audio Bus	Master 4: Output to codec;	16-Bit; Slot 6 or 11 (F3BAR0+Memory Offset 08h[19] selects slot).	
31:2	Pointer to the Physical R	egion Descriptor Table. This register is a PRD table pointer for Aud	dio Bus Master 4.
		points to the first entry in a PRD table. Once Audio Bus Master 4 is eter and updates this register (by adding 08h) so that it points to the n	
	When read, this register points to the next PRD.		
1:0	Reserved. Must be set to	0.	
		otor (PRD) table consists of one or more entries - each describing d. Each entry consists of two DWORDs.	a memory region to or from
	DWORD 0: DWORD 1:	[31:0] = Memory Region Physical Base Address 31 = End of Table Flag 30 = End of Page Flag 29 = Loop Flag (JMP) [28:16] = Reserved (0) [15:0] = Byte Count of the Region (Size)	



Table 6-38. F3BAR0+Memory Offset: Audio Configuration Registers (Continued)

Bit	Description				
Offset 48	h	Audio Bus Master 5 Command Register (R/W)	Reset Value: 00h		
Audio Bus	Master 5: Input from codec;	16-Bit; Slot 6 or 11 (F3BAR0+Memory Offset 08h[20] selects slot).			
7:4	Reserved. Must be set to 0	D. Must return 0 on reads.			
3	Read or Write Control. Se	et the transfer direction of Audio Bus Master 5.			
	0: PCI reads are performe	ed.			
	1: PCI writes are performe	ed.			
	This bit must be set to 1 (w	rite) and should not be changed when the bus master is active.			
2:1	Reserved. Must be set to 0	D. Must return 0 on reads.			
0	Bus Master Control. Cont	rols the state of the Audio Bus Master 5.			
	0: Disable.				
	1: Enable.				
	paused or have reached E	the bus master to begin data transfers. When writing 0 to this bit, t OT. Writing 0 to this bit while the bus master is operating, results in state machine). The only recovery from this condition is a PCI reset	unpredictable behavior (and		
Offset 49	h	Audio Bus Master 5 SMI Status Register (RC)	Reset Value: 00h		
Audio Bus	Master 5: Input from codec;	16-Bit; Slot 6 or 11 (F3BAR0+Memory Offset 08h[20] selects slot).			
7:2	Reserved.				
1	Bus Master Error. Indicates if hardware encountered a second EOP before software cleared the first.				
	0: No.				
	1: Yes.				
	If hardware encounters a second EOP (end of page) before software cleared the first, it causes the bus master to pause until this register is read to clear the error.				
0	End of Page. Indicates if the Bus master transferred data which is marked by the EOP bit in the PRD table (bit 30).				
	0: No.				
	1: Yes.				
Offset 4A	h-4Bh	Not Used			
Offset 4C	h-4Fh	Audio Bus Master 5 PRD Table Address (R/W)	Reset Value: 00000000h		
Audio Bus	Master 5: Input from codec;	16-Bit; Slot 6 or 11 (F3BAR0+Memory Offset 08h[20] selects slot).			
31:2	Pointer to the Physical Region Descriptor Table. This bit field contains a PRD table pointer for Audio Bus Master 5.				
	When written, this register points to the first entry in a PRD table. Once Audio Bus Master 5 is enabled (Command Register				
	bit 0 = 1), it loads the pointer and updates this register (by adding 08h) so that it points to the next PRD.				
	When read, this register points to the next PRD.				
1:0	Reserved. Must be set to).			
		tor (PRD) table consists of one or more entries - each describing I. Each entry consists of two DWORDs.	a memory region to or from		
	DWORD 0:	[31:0] = Memory Region Physical Base Address			
	DWORD 1:	31 = End of Table Flag			
		30 = End of Page Flag 29 = Loop Flag (JMP)			
		[28:16] = Reserved (0)			
		[15:0] = Byte Count of the Region (Size)			

6.4.5 X-Bus Expansion Interface - Function 5

The register space designated as Function 5 (F5) is used to configure the PCI portion of support hardware for accessing the X-Bus Expansion support registers. The bit formats for the PCI Header Registers are given in Table 6-39.

Located in the PCI Header Registers of F5 are six Base Address Registers (F5BARx) used for pointing to the register spaces designated for X-Bus Expansion support, described later in this section.

Table 6-39. F5: PCI Header Registers for X-Bus Expansion

Bit	Description	
Index 00h	-01h Vendor Identification Register (RO)	Reset Value: 100Bh
Index 02h	-03h Device Identification Register (RO)	Reset Value: 0505h
Index 04h	-05h PCI Command Register (R/W)	Reset Value: 0000h
15:2	Reserved. (Read Only)	
1	Memory Space. Allow the Core Logic module to respond to memory cycles from the F	PCI bus.
	0: Disable.	
	1: Enable.	
	If F5BAR0, F5BAR1, F5BAR2, F5BAR3, F5BAR4, and F5BAR5 (F5 Index 10h, 14h, 18 allowing access to memory mapped registers, this bit must be set to 1. BAR configurati sponding mask register (see F5 Index 40h, 44h, 48h, 4Ch, 50h, and 54h)	
0	I/O Space. Allow the Core Logic module to respond to I/O cycle from the PCI bus.	
	0: Disable.	
	1: Enable.	
	If F5BAR0, F5BAR1, F5BAR2, F5BAR3, F5BAR4, and F5BAR5 (F5 Index 10h, 14h, 18 allowing access to I/O mapped registers, this bit must be set to 1. BAR configuration is sponding mask register (see F5 Index 40h, 44h, 48h, 4Ch, 50h, and 54h)	
Index 06h	-07h PCI Status Register (RO)	Reset Value: 0280h
Index 08h	Device Revision ID Register (RO)	Reset Value: 00h
Index 09h	-0Bh PCI Class Code Register (RO)	Reset Value: 068000h
Index 0Cl	PCI Cache Line Size Register (RO)	Reset Value: 00h
Index 0DI	PCI Latency Timer Register (RO)	Reset Value: 00h
Index 0El	PCI Header Type (RO)	Reset Value: 00h
Index 0Fh	PCI BIST Register (RO)	Reset Value: 00h
Index 10h	-13h Base Address Register 0 - F5BAR0 (R/W)	Reset Value: 00000000h
be set to (Dansion Address Space. This register allows PCI access to I/O mapped X-Bus Expansi 00001, indicating a 64-byte aligned I/O address space. Refer to Table 6-40 on page 298 or bit formats and reset values.	
Note: The size and type of accessed offsets can be reprogrammed through F5BAR0 Mask Register (F5 Index 40h).		ster (F5 Index 40h).
31:6	X-Bus Expansion Base Address.	
5:0	Address Range. This bit field must be set to 000001 for this register to operate correct	tly.
Index 14h	-17h Base Address Register 1 - F5BAR1 (R/W)	Reset Value: 00000000h
Reserved. Reserved for possible future use by the Core Logic module.		
Configura	tion of this register is programmed through the F5BAR1 Mask Register (F5 Index 44h)	
Index 18h	-1Bh Base Address Register 2 - F5BAR2 (R/W)	Reset Value: 00000000h
Reserved	. Reserved for possible future use by the Core Logic module.	
Configuration of this register is programmed through the F5BAR1 Mask Register (F5 Index 48h)		



Table 6-39. F5: PCI Header Registers for X-Bus Expansion (Continued)

	Table 6-39. F5: PCI Header Registers for X-Bus Expansion (C	Jontinuea)
Bit	Description	
Index 1Ch	-1Fh Base Address Register 3 - F5BAR3 (R/W)	Reset Value: 00000000h
Reserved.	Reserved for possible future use by the Core Logic module.	
Configurat	on of this register is programmed through the F5BAR3 Mask Register (F5 Index 4Ch).	
Index 20h	23h Base Address Register 4 - F5BAR4 (R/W)	Reset Value: 00000000h
	Reserved for possible future use by the Core Logic module.	Noset Value. 000000011
	on of this register is programmed through the F5BAR4 Mask Register (F5 Index 50h).	
Index 24h	27h Base Address Register 5 - F5BAR5 (R/W)	Reset Value: 00000000h
	Reserved for possible future use by the Core Logic module.	Reset Value. 000000011
	on of this register is programmed through the F5BAR5 Mask Register (F5 Index 54h).	
Index 28h		Reset Value: 00h
Index 2Ch		Reset Value: 100Bh
Index 2Eh	• • • • • • • • • • • • • • • • • • • •	Reset Value: 0505h
Index 30h		Reset Value: 00h
Index 40h	, and the same of	Reset Value: FFFFFC1h
	BARO, the mask register should be programmed first. The mask register defines the size of laftest registers are memory or I/O mapped.	F5BARU and whether the
Note: V	henever a value is written to this mask register, F5BAR0 must also be written (even in hanged).	f the value for F5BAR0 has not
Memory B	ase Address Register (Bit 0 = 0)	
31:4	Address Mask. Determines the size of the BAR.	
	Every bit that is a 1 is programmable in the BAR.Every bit that is a 0 is fixed 0 in the BAR.	
	Since the address mask goes down to bit 4, the smallest memory region is 16 bytes, howe gests not using less than a 4 KB address range.	ever, the PCI specification sug-
3	Prefetchable. Indicates whether or not the data in memory is prefetchable. This bit should are true:	be set to 1 only if all the following
	 There are no side-effects from reads (i.e., the data at the location is not changed as 	s a result of the read).
	 The device returns all bytes regardless of the byte enables. Host bridges can merge processor writes into this range without causing errors. 	
	— The memory is not cached from the host processor. — The memory is not cached from the host processor.	
	Data is not prefetchable. This value is recommended if one or more of the above listed	conditions is not true.
	1: Data is prefetchable.	
2:1	Type.	
	00: Located anywhere in the 32-bit address space	
	01: Located below 1 MB	
	10: Located anywhere in the 64-bit address space	
	11: Reserved	
0	This bit must be set to 0, to indicate memory base address register.	
I/O Base A	ddress Register (Bit 0 = 1)	
31:2	Address Mask. Determines the size of the BAR.	
	 Every bit that is a 1 is programmable in the BAR. Every bit that is a 0 is fixed 0 in the BAR. 	
	Since the address mask goes down to bit 2, the smallest I/O region is 4 bytes, however, thusing less than a 4 KB address range.	e PCI Specification suggests not
1	Reserved. Must be set to 0.	
0	This bit must be set to 1, to indicate an I/O base address register.	

Reset Value: 00000000h



Bit

Table 6-39. F5: PCI Header Registers for X-Bus Expansion (Continued)

table 0-03. 10. 10 Theader Registers for X-bas Expansion (Oontinuea)
Description

Index 44h-47h F5BAR1 Mask Address Register (R/W)

To use F5BAR1, the mask register should be programmed first. The mask register defines the size of F5BAR1 and whether the accessed offset registers are memory or I/O mapped. See F5 Index 40h (F5BAR0 Mask Address Register) above for bit descriptions.

Note: Whenever a value is written to this mask register, F5BAR1 must also be written (even if the value for F5BAR1 has not changed).

Index 48h-4Bh F5BAR2 Mask Address Register (R/W) Reset Value: 00000000h

To use F5BAR2, the mask register should be programmed first. The mask register defines the size of F5BAR2 and whether the accessed offset registers are memory or I/O mapped. See F5 Index 40h (F5BAR0 Mask Address Register) above for bit descriptions.

Note: Whenever a value is written to this mask register, F5BAR2 must also be written (even if the value for F5BAR2 has not changed).

Index 4Ch-4Fh F5BAR3 Mask Address Register (R/W) Reset Value: 00000000h

To use F5BAR3, the mask register should be programmed first. The mask register defines the size of F5BAR3 and whether the accessed offset registers are memory or I/O mapped. See F5 Index 40h (F5BAR0 Mask Address Register) above for bit descriptions.

Note: Whenever a value is written to this mask register, F5BAR3 must also be written (even if the value for F5BAR3 has not changed).

Index 50h-53h F5BAR4 Mask Address Register (R/W) Reset Value: 00000000h

To use F5BAR4, the mask register should be programmed first. The mask register defines the size of F5BAR4 and whether the accessed offset registers are memory or I/O mapped. See F5 Index 40h (F5BAR0 Mask Address Register) above for bit descriptions.

Note: Whenever a value is written to this mask register, F5BAR4 must also be written (even if the value for F5BAR4 has not changed).

Index 54h-57h F5BAR5 Mask Address Register (R/W) Reset Value: 00000000h

To use F5BAR5, the mask register should be programmed first. The mask register defines the size of F5BAR5 and whether the accessed offset registers are memory or I/O mapped. See F5 Index 40h (F5BAR0 Mask Address Register) above for bit descriptions.

Note: Whenever a value is written to this mask register, F5BAR5 must also be written (even if the value for F5BAR5 has not changed).

Index 58h	F5BARx Initialized Register (R/W)	Reset Value: 00h
7:6	Reserved. Must be set to 0.	
5	F5BAR5 Initialized. This bit indicates if F5BAR5 (F5 Index 24h) has been initialized.	
	At reset this bit is cleared (0). Writing F5BAR5 sets this bit to 1. If this bit programmed to 0, the decoabled until either this bit is set to 1 or F5BAR5 is written (which causes this bit to be set to 1).	oding of F5BAR5 is dis-
4	F5BAR4 Initialized. This bit indicates if F5BAR4 (F5 Index 28h) has been initialized.	
	At reset this bit is cleared (0). Writing F5BAR4 sets this bit to 1. If this bit programmed to 0, the decoabled until either this bit is set to 1 or F5BAR4 is written (which causes this bit to be set to 1).	oding of F5BAR4 is dis-
3	F5BAR3 Initialized. This bit indicates if F5BAR3 (F5 Index 1Ch) has been initialized.	
	At reset this bit is cleared (0). Writing F5BAR3 sets this bit to 1. If this bit programmed to 0, the decoabled until either this bit is set to 1 or F5BAR3 is written (which causes this bit to be set to 1).	oding of F5BAR3 is dis-
2	F5BAR2 Initialized. This bit indicates if F5BAR2 (F5 Index 18h) has been initialized.	
	At reset this bit is cleared (0). Writing F5BAR2 sets this bit to 1. If this bit programmed to 0, the decoabled until either this bit is set to 1 or F5BAR2 is written (which causes this bit to be set to 1).	oding of F5BAR2 is dis-
1	F5BAR1 Initialized. This bit indicates if F5BAR1 (F5 Index 14h) has been initialized.	
	At reset this bit is cleared (0). Writing F5BAR1 sets this bit to 1. If this bit programmed to 0, the decoabled until either this bit is set to 1 or F5BAR1 is written (which causes this bit to be set to 1).	oding of F5BAR1 is dis-
0	F5BAR0 Initialized. This bit indicates if F5BAR0 (F5 Index 10h) has been initialized.	
	At reset this bit is cleared (0). Writing F5BAR0 sets this bit to 1. If this bit programmed to 0, the decoabled until either this bit is set to 1 or F5BAR0 is written (which causes this bit to be set to 1).	oding of F5BAR0 is dis-

 Index 59h-5Fh
 Reserved
 Reset Value: xxh

 Index 60h-63h
 Scratchpad: Usually used for Device Number (R/W)
 Reset Value: 00000000h

BIOS writes a value, of the Device number. Expected value: 00003200h.



Table 6-39. F5: PCI Header Registers for X-Bus Expansion (Continued)

Bit	Description	
Index 64h- BIOS write	67h Scratchpad: Usually used for Configuration Block Address (R/W) Reset Value: 00000000h es a value, of the Configuration Block Address.	
Index 68h-FFh Reserved		



6.4.5.1 X-Bus Expansion Support Registers

F5 Index 10h, Base Address Register 0 (F5BAR0) set the base address that allows PCI access to additional I/O Con-

trol support registers. Table 6-40 shows the support registers accessed through F5BAR0.

Table 6-40. F5BAR0+I/O Offset: X-Bus Expansion Registers

Bit	Description		
Offset 00h	n-03h	I/O Control Register 1 (R/W)	Reset Value: 010C0007h
31:28	Reserved.		
27	IO_ENABLE_SIO_IR (Enable Integ	grated SIO Infrared).	
	0: Disable.		
	1: Enable.		
26:25	IO_SIOCFG_IN (Integrated SIO In limit/control the base address.	put Configuration). These two bits can be us	sed to disable the integrated SIO totally or
	00: Integrated SIO disable.		
	01: Integrated SIO configuration ac	cess disable.	
	10: Integrated SIO base address 0	2Eh/02Fh enable.	
	11: Integrated SIO base address 0	15Ch/015Dh enable.	
24	IO_ENABLE_SIO_DRIVING_ISA_I internal ISA bus.	BUS (Enable Integrated SIO ISA Bus Contro	ol). Allow the integrated SIO to drive the
	0: Disable.		
	1: Enable. (Default)		
23:21	Reserved. Set to 0.		
20	IO_USB_SMI_PWM_EN (USB Inte 00h/02h[14].	rnal SMI). Route USB-generated SMI to SMI	Status Register in F1BAR0+I/O Offset
	0: Disable.		
	1: Enable.		
19	IO_USB_SMI_EN (USB SMI Confi	guration). Allow USB-generated SMIs.	
	0: Disable		
	1: Enable.		
	If bits 19 and 20 are enabled, the SI O Offset 00h/02h[14].	MI generated by the USB is reported via the To	op Level SMI status register at F1BAR0+I/
	If only bit 19 is enabled, the USB ca	n generate an SMI but there is no status repo	rting.
18	IO_USB_PCI_EN (USB). Enables l	JSB ports.	
	0: Disable.		
	1: Enable.		
17:0	Reserved.		



Table 6-40. F5BAR0+I/O Offset: X-Bus Expansion Registers (Continued)

Bit	Description
Offset 04h	h-07h I/O Control Register 2 (R/W) Reset Value: 00000002h
31:2	Reserved. Write as read.
1	Video Processor Access Enable. Allows access to video processor using F4BAR0.
	0: Disable.
	1: Enable. (Default)
	Note: This bit is readable after the register (F5BAR0+Offset 04h) has been written once.
0	IO_STRAP_IDSEL_SELECT (IDSEL Strap Override).
	0: IDSEL: AD28 for Chipset Register Space (F0-F5), AD29 for USB Register Space (PCIUSB).
	1: IDSEL: AD26 for Chipset Register Space (F0-F5), AD27 for USB Register Space (PCIUSB).
Offset 08h	h-0Bh I/O Control Register 3 (R/W) Reset Value: 00009000h
31:16	Reserved. Write as read.
15:13	IO_USB_XCVR_VADJ (USB Voltage Adjustment Connection). These bits connect to the voltage adjustment interface on the three USB transceivers. Default = 100.
12:8	IO_USB_XCVT_CADJ (USB Current Adjustment). These bits connect to the current adjustment interface on the three USB transceivers. Default = 10000.
7	IO_TEST_PORT_EN (Debug Test Port Enable).
	0: Disable
	1: Enable
6:0	IO_TEST_PORT_REG (Debug Port Pointer). These bits are used to point to the 16-bit slice of the test port bus.

6.4.6 USB Controller Registers - PCIUSB

The registers designated as PCIUSB are 32-bit registers decoded from the PCI address bits [7:2] and C/BE[3:0]#, when IDSEL is high, AD[10:8] select the appropriate function, and AD[1:0] are 00.

The PCI Configuration registers are listed in Table 6-41. They can be accessed as any number of bytes within a single 32-bit aligned unit. They are selected by the PCI-standard Index and Byte-Enable method.

In the PCI Configuration space, there is one Base Address Register (BAR), at Index 10h, which is used to map the USB Host Controller's operational register set into a 4K memory space. Once the BAR register has been initialized, and the PCI Command register at Index 04h has been set to enable the Memory space decoder, these "USB Controller" registers are accessible.

The memory-mapped USB Controller registers are listed in Table 6-42. They follow the Open Host Controller Interface (OHCI) specification. Registers marked as "Reserved", and reserved bits within a register, should not be changed by software.

Table 6-41. PCIUSB: USB PCI Configuration Registers

Bit	Description	
Index 00h	h-01h Vendor Identification Register (RO)	Reset Value: 0E11h
Index 02l	h-03h Device Identification Register (RO)	Reset Value: A0F8h
Index 04	h-05h Command Register (R/W)	Reset Value: 00h
15:10	Reserved. Must be set to 0.	
9	Fast Back-to-Back Enable. (Read Only) USB only acts as a master to a single dev It is always disabled (i.e., this bit must always be set to 0).	vice, so this functionality is not needed.
8	SERR#. When this bit is enabled, USB asserts SERR# when it detects an address	parity error.
	0: Disable.	
	1: Enable.	
7	Wait Cycle Control. USB does not need to insert a wait state between the address disabled (i.e., this bit is set to 0).	and data on the AD lines. It is always
6	Parity Error. USB asserts PERR# when it is the agent receiving data and it detects	a data parity error.
	0: Disable.	
	1: Enable.	
5	VGA Palette Snoop Enable. (Read Only) USB does not support this function. It is 0).	always disabled (i.e., this bit is set to
4	Memory Write and Invalidate. Allow USB to run Memory Write and Invalidate com	nmands.
	0: Disable.	
	1: Enable.	
	The Memory Write and Invalidate Command only occurs if the cache-line size is set exactly one cache line.	t to 32 bytes and the memory write is
	This bit must be set to 0.	
3	Special Cycles. USB does not run special cycles on PCI. It is always disabled (i.e.,	, this bit is set to 0).
2	PCI Master Enable. Allow the USB to run PCI master cycles.	
	0: Disable.	
	1: Enable.	
1	Memory Space. Allow the USB to respond as a target to memory cycles from the F	PCI bus.
	0: Disable.	
	1: Enable.	
0	I/O Space. Allow the USB to respond as a target to I/O cycles from the PCI bus.	
	0 Disable.	
	1: Enable.	



Table 6-41. PCIUSB: USB PCI Configuration Registers (Continued)

Bit	Description	
Index 06	h-07h Status Register (R/W)	Reset Value: 0280h
	specification defines this register to record status information for PCI related even nonly reset bits. A bit is reset whenever the register is written and the data in the	
15	Detected Parity Error. This bit is set to 1 whenever the USB detects a parity Detection Enable Bit (Command Register, bit 6) is disabled.	verror, even if the Parity Error (Response)
	Write 1 to clear.	
14	SERR# Status. This bit is set whenever the USB detects a PCI address erro	r.
	Write 1 to clear.	
13	Received Master Abort Status. This bit is set when the USB, acting as a Power of the USB.	CI master, aborts a PCI bus memory cycle.
12	Received Target Abort Status. This bit is set when a USB generated PCI con PCI target.	ycle (USB is the PCI master) is aborted by a
	Write 1 to clear.	
11	Signaled Target Abort Status. This bit is set whenever the USB signals a ta	arget abort.
	Write 1 to clear.	
10:9	DEVSEL# Timing. (Read Only) These bits indicate the DEVSEL# timing wh DEVSEL# is asserted to meet the medium timing, these bits are encoded as	. • .
8	Data Parity Reported. (Read Only) This bit is set to 1 if the Parity Error Res and the USB detects PERR# asserted while acting as PCI master (whether of	, , ,
7	Fast Back-to-Back Capable. The USB supports fast back-to-back transaction agent.	ons when the transactions are not to the same
	This bit is always 1.	
6:0	Reserved. Must be set to 0.	

Index 08h Device Revision ID Register (RO)

Reset Value: 08h

Index 09h-0Bh

PCI Class Code Register (RO)

Reset Value: 0C0310h

This register identifies the generic function of the USB the specific register level programming interface. The Base Class is 0Ch (Serial Bus Controller). The Sub Class is 03h (Universal Serial Bus). The Programming Interface is 10h (OpenHCI).

Index 0Ch

Cache Line Size Register (R/W)

Reset Value: 00h

This register identifies the system cache-line size in units of 32-bit WORDs. The USB only stores the value of bit 3 in this register since the cache-line size of 32 bytes is the only value applicable to the design. Any value other than 08h written to this register is read back as 00h.

Index 0Dh

Latency Timer Register (R/W)

Reset Value: 00h

This register identifies the value of the latency timer in PCI clocks for PCI bus master cycles. Bits [2:0] of this register are always set to 0.

Index 0Eh

Header Type Register (RO)

Reset Value: 00h

This register identifies the type of the predefined header in the configuration space. Since the USB is a single function device and not a PCI-to-PCI bridge, this byte should be read as 00h.

Index 0Fh

BIST Register (RO)

Reset Value: 00h

This register identifies the control and status of Built-In Self-Test (BIST). The USB does not implement BIST, so this register is read only

Index 10h	-13h Base Address Register - USB_BAR0 (R/W)	Reset Value: 00000000h
31:12	Base Address. POST writes the value of the memory base address to this register.	
11:4	Always 0. Indicates that a 4 KB address range is requested.	
3	Always 0. Indicates that there is no support for prefetchable memory.	
2:1	Always 0. Indicates that the base register is 32-bits wide and can be placed anywhere in	32-bit memory space.
0	Always 0. Indicates that the operational registers are mapped into memory space.	



Table 6-41. PCIUSB: USB PCI Configuration Registers (Continued)

Bit	Description		
Index 14h	-2Bh	Reserved	Reset Value: 00h
Index 2CI	n-2Dh	Subsystem Vendor ID (RO)	Reset Value: 0E11h
Index 2El	n-2Fh	Subsystem ID (RO)	Reset Value: A0F8h
Index 30h	-3Bh	Reserved	Reset Value: 00h
		Interrupt Line Register (R/W) errupt controllers to which the device's interrupt pin is connected. neaning to USB.	Reset Value: 00h The value of this register is used
_		Interrupt Pin Register (R/W) oin the device uses. USB uses INTA# after reset. INTB#, INTC# o	Reset Value: 01h r INTD# can be selected by writ-
	-	Min. Grant Register (RO) rst is needed by the USB, assuming a clock rate of 33 MHz. The cond.	Reset Value: 00h value in this register specifies a
Index 3Fh This regis		Max. Latency Register (RO) units of 1/4 microsecond) the USB needs access to the PCI bus a	Reset Value: 50h ssuming a clock rate of 33 MHz.
Index 40h Used for i	n-43h nternal debug and test purp	ASIC Test Mode Enable Register (R/W) poses only.	Reset Value: 000F0000h
Index 44h	1	ASIC Operational Mode Enable Register (R/W)	Reset Value: 00h
7:1	Write Only. Read as 0s.		
0		n for the data buffer is 32 bytes. n for the data buffer is 16 bytes.	
Index 45h	EEb	Reserved	Reset Value: 00h



Table 6-42. USB_BAR+Memory Offset: USB Controller Registers

Bit	Description	
Offset 00l	h-03h HcRevision Register (RO)	Reset Value = 00000110h
31:8	Reserved. Read/Write 0s.	
7:0	Revision (Read Only). Indicates the Open HCI Specification revision numb ports 1.0 specification. (X.Y = XYh).	er implemented by the Hardware. USB sup-
Offset 04I	h-07h HcControl Register (R/W)	Reset Value = 00000000h
31:11	Reserved. Read/Write 0s.	
10	RemoteWakeupConnectedEnable. If a remote wakeup signal is supported no remote wakeup signal supported, this bit is ignored.	, this bit enables that operation. Since there is
9	RemoteWakeupConnected (Read Only). This bit indicated whether the HC mentation does not support any such signal. The bit is hard-coded to 0.	supports a remote wakeup signal. This imple-
8	InterruptRouting. This bit is used for interrupt routing:	
	0: Interrupts routed to normal interrupt mechanism (INT).	
	1: Interrupts routed to SMI.	
7:6	HostControllerFunctionalState. This field sets the HC state. The HC may UsbResume after detecting resume signaling from a downstream port. State 00: UsbReset	· ·
	01: UsbResume	
	10: UsbOperational	
	11: UsbSuspend	
5	BulkListEnable. When set, this bit enables processing of the Bulk list.	
4	ControlListEnable. When set, this bit enables processing of the Control list	
3	IsochronousEnable. When clear, this bit disables the Isochronous List when may be serviced). While processing the Periodic List, the HC will check this	` .
2	PeriodicListEnable. When set, this bit enables processing of the Periodic (i this bit prior to attempting any periodic transfers in a frame.	nterrupt and isochronous) list. The HC checks
1:0	ControlBulkServiceRatio. Specifies the number of Control Endpoints servi where N is the number of Control Endpoints (i.e., 00: 1 Control Endpoint; 11	,
Offset 08I	n-0Bh HcCommandStatus Register (R/W)	Reset Value = 00000000h
31:18	Reserved. Read/Write 0s.	
17:16	ScheduleOverrunCount. This field increments every time the SchedulingO count wraps from 11 to 00.	verrun bit in HcInterruptStatus is set. The
15:4	Reserved. Read/Write 0s.	
3	OwnershipChangeRequest. When set by software, this bit sets the Owners is cleared by software.	shipChange field in HcInterruptStatus. The bit
2	BulkListFilled. Set to indicate there is an active ED on the Bulk List. The bi cleared by the HC each time it begins processing the head of the Bulk List.	t may be set by either software or the HC and
1	ControlListFilled. Set to indicate there is an active ED on the Control List. I cleared by the HC each time it begins processing the head of the Control List.	•
0	HostControllerReset. This bit is set to initiate a software reset. This bit is cloperation.	eared by the HC upon completion of the reset
Offset 0C	h-0Fh HcInterruptStatus Register (R/W)	Reset Value = 00000000h
31	Reserved. Read/Write 0s.	
30	OwnershipChange. This bit is set when the OwnershipChangeRequest bit	of HcCommandStatus is set.
29:7	Reserved. Read/Write 0s.	



RootHubStatusChange. This bit is set when the content of HcRhStatus or the content of any HcRhPortStatus register has hanged. FrameNumberOverflow. Set when bit 15 of FrameNumber changes value. For IntercoverableError (Read Only). This event is not implemented and is hard-coded to 0. Writes are ignored. ResumeDetected. Set when HC detects resume signaling on a downstream port. For Intercoverable Error (Read Only). This event is not implemented and is hard-coded to 0. Writes are ignored. ResumeDetected. Set when HC detects resume signaling on a downstream port. For Intercoverable Error (Read Only). This event is not implemented and is hard-coded to 0. Writes are ignored. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream port. ResumeDetected. Set when HC detects resume signaling on a downstream
InrecoverableError (Read Only). This event is not implemented and is hard-coded to 0. Writes are ignored. ResumeDetected. Set when HC detects resume signaling on a downstream port. RestrOfFrame. Set when the Frame Management block signals a Start of Frame event. WritebackDoneHead. Set after the HC has written HcDoneHead to HccaDoneHead. SchedulingOverrun. Set when the List Processor determines a Schedule Overrun has occurred. Sits are set by hardware and cleared by software. 3h HcInterruptEnable Register (R/W) Reset Value = 00000000h MasterInterruptEnable. This bit is a global interrupt enable. A write of 1 allows interrupts to be enabled via the specific mable bits listed above. DwnershipChangeEnable. : Ignore. : Enable interrupt generation due to Ownership Change. Reserved. Read/Write 0s.
ResumeDetected. Set when HC detects resume signaling on a downstream port. StartOfFrame. Set when the Frame Management block signals a Start of Frame event. WritebackDoneHead. Set after the HC has written HcDoneHead to HccaDoneHead. SchedulingOverrun. Set when the List Processor determines a Schedule Overrun has occurred. Sits are set by hardware and cleared by software. Sh HcInterruptEnable Register (R/W) Reset Value = 00000000h MasterInterruptEnable. This bit is a global interrupt enable. A write of 1 allows interrupts to be enabled via the specific mable bits listed above. DwnershipChangeEnable. It Ignore. Enable interrupt generation due to Ownership Change. Reserved. Read/Write 0s.
Activities are set by hardware and cleared by software. The Interrupt Enable. This bit is a global interrupt enable. A write of 1 allows interrupts to be enabled via the specific mable bits listed above. The Interrupt Generation due to Ownership Change.
WritebackDoneHead. Set after the HC has written HcDoneHead to HccaDoneHead. SchedulingOverrun. Set when the List Processor determines a Schedule Overrun has occurred. Sits are set by hardware and cleared by software. Sh HcInterruptEnable Register (R/W) Reset Value = 00000000h MasterInterruptEnable. This bit is a global interrupt enable. A write of 1 allows interrupts to be enabled via the specific mable bits listed above. OwnershipChangeEnable. It Ignore. Enable interrupt generation due to Ownership Change. Reserved. Read/Write 0s.
its are set by hardware and cleared by software. The hardware and cleared by software and cleared by software and cleared by software. The hardware and cleared by software and cleared by softwa
HcInterruptEnable Register (R/W) Reset Value = 00000000h MasterInterruptEnable. This bit is a global interrupt enable. A write of 1 allows interrupts to be enabled via the specific mable bits listed above. DwnershipChangeEnable. I Ignore. Enable interrupt generation due to Ownership Change. Reserved. Read/Write 0s.
HcInterruptEnable Register (R/W) Reset Value = 00000000h MasterInterruptEnable. This bit is a global interrupt enable. A write of 1 allows interrupts to be enabled via the specific mable bits listed above. DwnershipChangeEnable. I gnore. Enable interrupt generation due to Ownership Change. Reserved. Read/Write 0s.
MasterInterruptEnable. This bit is a global interrupt enable. A write of 1 allows interrupts to be enabled via the specific mable bits listed above. DwnershipChangeEnable. I gnore. Enable interrupt generation due to Ownership Change. Reserved. Read/Write 0s.
DwnershipChangeEnable. I Ignore. Enable interrupt generation due to Ownership Change. Reserved. Read/Write 0s.
: Ignore. : Enable interrupt generation due to Ownership Change. Reserved. Read/Write 0s.
Enable interrupt generation due to Ownership Change. Reserved. Read/Write 0s.
Reserved. Read/Write 0s.
RootHubStatusChangeEnable.
G
: Ignore.
: Enable interrupt generation due to Root Hub Status Change.
rameNumberOverflowEnable.
: Ignore.
: Enable interrupt generation due to Frame Number Overflow.
InrecoverableErrorEnable. This event is not implemented. All writes to this bit are ignored.
ResumeDetectedEnable.
: Ignore.
: Enable interrupt generation due to Resume Detected.
StartOfFrameEnable.
: Ignore. : Enable interrupt generation due to Start of Frame.
VritebackDoneHeadEnable. : Ignore.
: Enable interrupt generation due to Writeback Done Head.
SchedulingOverrunEnable.
: Ignore.
: Enable interrupt generation due to Scheduling Overrun.
ing a 1 to a bit in this register sets the corresponding bit, while writing a 0 leaves the bit unchanged.
7h HcInterruptDisable Register (R/W) Reset Value = 00000000h
MasterInterruptEnable. Global interrupt disable. A write of 1 disables all interrupts.
OwnershipChangeEnable.
: Ignore.
: Disable interrupt generation due to Ownership Change.
Reserved. Read/Write 0s.
::



Table 6-42. USB_BAR+Memory Offset: USB Controller Registers (Continued)

Bit	Description	,
6	RootHubStatusChangeEnable.	
	0: Ignore.	
	1: Disable interrupt generation due to Root Hub Status Change.	
5	FrameNumberOverflowEnable.	
	0: Ignore.	
	1: Disable interrupt generation due to Frame Number Overflow.	
4	UnrecoverableErrorEnable. This event is not implemented. All writes to this bit will be	pe ignored.
3	ResumeDetectedEnable.	
	0: Ignore.	
	1: Disable interrupt generation due to Resume Detected.	
2	StartOfFrameEnable.	
	0: Ignore.	
	1: Disable interrupt generation due to Start of Frame.	
1	WritebackDoneHeadEnable.	
	0: Ignore.	
	Disable interrupt generation due to Writeback Done Head.	
0	SchedulingOverrunEnable.	
	0: Ignore.	
	Disable interrupt generation due to Scheduling Overrun.	
Note: V	Vriting a 1 to a bit in this register clears the corresponding bit, while writing a 0 to a bit le	eaves the bit unchanged.
Offset 18I	n-1Bh HcHCCA Register (R/W)	Reset Value = 00000000h
31:8	HCCA. Pointer to HCCA base address.	
7:0	Reserved. Read/Write 0s.	
Offset 1C	h-1Fh HcPeriodCurrentED Register (R/W)	Reset Value = 00000000h
31:4	PeriodCurrentED. Pointer to the current Periodic List ED.	
3:0	Reserved. Read/Write 0s.	
Offset 20I	n-23h HcControlHeadED Register (R/W)	Reset Value = 00000000h
31:4	ControlHeadED. Pointer to the Control List Head ED.	
3:0	Reserved. Read/Write 0s.	
Offset 24l	OZI	
	n-27h HcControlCurrentED Register (R/W)	Reset Value = 00000000h
31:4	ControlCurrentED. Pointer to the current Control List ED.	Reset Value = 00000000h
31:4 3:0		Reset Value = 00000000h
	ControlCurrentED. Pointer to the current Control List ED. Reserved. Read/Write 0s.	Reset Value = 00000000h Reset Value = 00000000h
3:0	ControlCurrentED. Pointer to the current Control List ED. Reserved. Read/Write 0s.	
3:0 Offset 28l	ControlCurrentED. Pointer to the current Control List ED. Reserved. Read/Write 0s. HcBulkHeadED Register (R/W)	
3:0 Offset 28l	ControlCurrentED. Pointer to the current Control List ED. Reserved. Read/Write 0s. h-2Bh HcBulkHeadED Register (R/W) BulkHeadED. Pointer to the Bulk List Head ED. Reserved. Read/Write 0s.	
3:0 Offset 28l 31:4 3:0	ControlCurrentED. Pointer to the current Control List ED. Reserved. Read/Write 0s. h-2Bh HcBulkHeadED Register (R/W) BulkHeadED. Pointer to the Bulk List Head ED. Reserved. Read/Write 0s.	Reset Value = 00000000h
3:0 Offset 28l 31:4 3:0 Offset 2C	ControlCurrentED. Pointer to the current Control List ED. Reserved. Read/Write 0s. h-2Bh	Reset Value = 00000000h
3:0 Offset 28l 31:4 3:0 Offset 2C 31:4	ControlCurrentED. Pointer to the current Control List ED. Reserved. Read/Write 0s. h-2Bh HcBulkHeadED Register (R/W) BulkHeadED. Pointer to the Bulk List Head ED. Reserved. Read/Write 0s. h-2Fh HcBulkCurrentED Register (R/W) BulkCurrentED. Pointer to the current Bulk List ED. Reserved. Read/Write 0s.	Reset Value = 00000000h
3:0 Offset 28l 31:4 3:0 Offset 2C 31:4 3:0	ControlCurrentED. Pointer to the current Control List ED. Reserved. Read/Write 0s. h-2Bh HcBulkHeadED Register (R/W) BulkHeadED. Pointer to the Bulk List Head ED. Reserved. Read/Write 0s. h-2Fh HcBulkCurrentED Register (R/W) BulkCurrentED. Pointer to the current Bulk List ED. Reserved. Read/Write 0s.	Reset Value = 00000000h Reset Value = 00000000h



Bit	Description	
Offset 34	h-37h HcFmInterval Register (R/W)	Reset Value = 00002EDFh
31	FrameIntervalToggle (Read Only). This bit is toggled by HCD when it loads	s a new value into FrameInterval.
30:16	FSLargestDataPacket (Read Only). This field specifies a value which is loat the beginning of each frame.	ded into the Largest Data Packet Counter at
15:14	Reserved. Read/Write 0s.	
13:0	FrameInterval. This field specifies the length of a frame as (bit times - 1). For is stored here.	12,000 bit times in a frame, a value of 11,999
Offset 38	h-3Bh HcFrameRemaining Register (RO)	Reset Value = 00000000h
31	FrameRemainingToggle (Read Only). Loaded with FrameIntervalToggle when the state of	nen FrameRemaining is loaded.
30:14	Reserved. Read 0s.	
13:0	FrameRemaining (Read Only). When the HC is in the UsbOperational state clock period. When the count reaches 0, (end of frame) the counter reloads to loads when the HC transitions into UsbOperational.	
Offset 30	h-3Fh HcFmNumber Register (RO)	Reset Value = 00000000h
31:16	Reserved. Read 0s.	
15:0	FrameNumber (Read Only). This 16-bit incrementing counter field is incrementating. The count rolls over from FFFFh to 0h.	nented coincident with the loading of FrameR-
Offset 40	h-43h HcPeriodicStart Register (R/W)	Reset Value = 00000000h
31:14	Reserved. Read/Write 0s.	
13:0	PeriodicStart. This field contains a value used by the List Processor to dete cessing must begin.	rmine where in a frame the Periodic List pro-
Offset 44	h-47h HcLSThreshold Register (R/W)	Reset Value = 00000628h
31:12	Reserved. Read/Write 0s.	
11:0	LSThreshold. This field contains a value used by the Frame Management b transaction can be started in the current frame.	lock to determine whether or not a low speed
Offset 48	h-4Bh HcRhDescriptorA Register (R/W)	Reset Value = 01000003h
31:24	PowerOnToPowerGoodTime. This field value is represented as the number switching is effective within 2 ms. Only bits [25:24] are implemented as R/W. expected that these bits be written to anything other than 1h, but limited adjust to support system implementation. This field should always be written to a new field should al	The remaining bits are read only as 0. It is not stment is provided. This field should be written
23:13	Reserved. Read/Write 0s.	
12	NoOverCurrentProtection. This bit should be written to support the external 0: Over-current status is reported. 1: Over-current status is not reported.	al system port over-current implementation.
11	OverCurrentProtectionMode. This bit should be written 0 and is only valid 0: Global Over-Current. 1: Individual Over-Current	when NoOverCurrentProtection is cleared.
10	DeviceType (Read Only). USB is not a compound device.	
9	NoPowerSwitching. This bit should be written to support the external system 0: Ports are power switched. 1: Ports are always powered on.	m port power switching implementation.
8	PowerSwitchingMode. This bit is only valid when NoPowerSwitching is clear 0: Global Switching. 1: Individual Switching	ared. This bit should be written 0.



Bit	Description	
7:0	NumberDownstreamPorts (Read Only). USB supports three downstream ports.	
Note:	This register is only reset by a power-on reset (PCIRST#). It is written during system in These bit should not be written during normal operation.	nitialization to configure the Root Hub
Offset 4	Ch-4Fh HcRhDescriptorB Register (R/W)	Reset Value = 00000000h
31:16	PortPowerControlMask. Global-power switching. This field is only valid if NoPowerS SwitchingMode is set (individual port switching). When set, the port only responds to mands (Set/ClearPortPower). When cleared, the port only responds to global power ClearGlobalPower). 0: Device not removable. 1: Global-power mask. Port Bit relationship - Unimplemented ports are reserved, read/write 0. 0 = Reserved 1 = Port 1 2 = Port 2 15 = Port 15	individual port power switching com-
15:0	DeviceRemoveable. USB ports default to removable devices.	
	 0: Device not removable. 1: Device removable. Port Bit relationship 0 = Reserved 1 = Port 1 2 = Port 2 	
	15 = Port 15 Unimplemented ports are reserved, read/write 0.	
Note:	This register is only reset by a power-on reset (PCIRST#). It is written during system in These bit should not be written during normal operation.	itialization to configure the Root Hub
Offset 5	h-53h HcRhStatus Register (R/W)	Reset Value = 00000000h
31	ClearRemoteWakeupEnable (Write Only). Writing a 1 to this bit clears DeviceRemote effect.	oteWakeupEnable. Writing a 0 has no
	Reserved. Read/Write 0s.	
30:18		
30:18 17	OverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. No effect.	Writing a 1 clears this bit. Writing a 0
	has no effect. Read: LocalPowerStatusChange. Not supported. Always read 0.	
17	has no effect.	Writing a 0 has no effect. e as a remote wakeup event.
17 16	has no effect. Read: LocalPowerStatusChange. Not supported. Always read 0. Write: SetGlobalPower. Write a 1 issues a SetGlobalPower command to the ports. Read: DeviceRemoteWakeupEnable. This bit enables ports' ConnectStatusChange 0: Disabled. 1: Enabled.	Writing a 0 has no effect. e as a remote wakeup event.
17 16 15	has no effect. Read: LocalPowerStatusChange. Not supported. Always read 0. Write: SetGlobalPower. Write a 1 issues a SetGlobalPower command to the ports. Read: DeviceRemoteWakeupEnable. This bit enables ports' ConnectStatusChange 0: Disabled. 1: Enabled. Write: SetRemoteWakeupEnable. Writing a 1 sets DeviceRemoteWakeupEnable. Reserved. Read/Write 0s. OverCurrentIndicator. This bit reflects the state of the OVRCUR pin. This field is on and OverCurrentProtectionMode are cleared. 0: No over-current condition.	Writing a 0 has no effect. e as a remote wakeup event. Writing a 0 has no effect.
17 16 15	has no effect. Read: LocalPowerStatusChange. Not supported. Always read 0. Write: SetGlobalPower. Write a 1 issues a SetGlobalPower command to the ports. Read: DeviceRemoteWakeupEnable. This bit enables ports' ConnectStatusChange 0: Disabled. 1: Enabled. Write: SetRemoteWakeupEnable. Writing a 1 sets DeviceRemoteWakeupEnable. Reserved. Read/Write 0s. OverCurrentIndicator. This bit reflects the state of the OVRCUR pin. This field is on and OverCurrentProtectionMode are cleared.	Writing a 0 has no effect. e as a remote wakeup event. Writing a 0 has no effect.

This register is reset by the UsbReset state.

Note:



Bit	Description	
Offset 54	h-57h HcRhPortStatus[1] Register (R/W)	Reset Value = 00000000h
31:21	Reserved. Read/Write 0s.	
20	PortResetStatusChange. This bit indicates that the port reset signal has completed	l.
	0: Port reset is not complete.	
	1: Port reset is complete.	
19	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator change a 0 has no effect.	ges. Writing a 1 clears this bit. Writing
18	PortSuspendStatusChange. This bit indicates the completion of the selective resur	me sequence for the port.
	0: Port is not resumed.	
	1: Port resume is complete.	
17	PortEnableStatusChange. This bit indicates that the port has been disabled due to bleStatus).	a hardware event (cleared PortEna-
	0: Port has not been disabled.	
	1: PortEnableStatus has been cleared.	
16	ConnectStatusChange. This bit indicates a connect or disconnect event has been of Writing a 0 has no effect.	detected. Writing a 1 clears this bit.
	0: No connect/disconnect event.	
	Hardware detection of connect/disconnect event.	
	If DeviceRemoveable is set, this bit resets to 1.	
15:10	Reserved. Read/Write 0s.	
9	Read: LowSpeedDeviceAttached. This bit defines the speed (and bud idle) of the a CurrentConnectStatus is set.	attached device. It is only valid when
	0: Full Speed device.	
	1: Low Speed device.	
	Write: ClearPortPower. Writing a 1 clears PortPowerStatus. Writing a 0 has no effect	ct.
8	Read: PortPowerStatus. This bit reflects the power state of the port regardless of the	ne power switching mode.
	0: Port power is off.	
	1: Port power is on.	
	If NoPowerSwitching is set, this bit is always read as 1.	
	Write: SetPortPower. Writing a 1 sets PortPowerStatus. Writing a 0 has no effect.	
7:5	Reserved. Read/Write 0s.	
4	Read: PortResetStatus.	
	0: Port reset signal is not active.	
	1: Port reset signal is active.	
	Write: SetPortReset. Writing a 1 sets PortResetStatus. Writing a 0 has no effect.	
3	Read: PortOverCurrentIndicator. This bit reflects the state of the OVRCUR pin ded valid if NoOverCurrentProtection is cleared and OverCurrentProtectionMode is set.	dicated to this port. This field is only
	0: No over-current condition.	
	1: Over-current condition.	
	Write: ClearPortSuspend. Writing a 1 initiates the selective resume sequence for the	ne port. Writing a 0 has no effect.
2	Read: PortSuspendStatus.	
	0: Port is not suspended.	
	1: Port is selectively suspended.	



Bit	Description
1	Read: PortEnableStatus.
	0: Port disabled.
	1: Port enabled.
	Write: SetPortEnable. Writing a 1 sets PortEnableStatus. Writing a 0 has no effect.
0	Read: CurrentConnectStatus.
	0: No device connected.
	1: Device connected.
	If DeviceRemoveable is set (not removable) this bit is always 1.
	Write: ClearPortEnable. Writing 1 a clears PortEnableStatus. Writing a 0 has no effect.
Note:	This register is reset by the UsbReset state.
Offset 58	h-5Bh HcRhPortStatus[2] Register (R/W) Reset Value = 00000000h
31:21	Reserved. Read/Write 0s.
20	PortResetStatusChange. This bit indicates that the port reset signal has completed.
	0: Port reset is not complete.
	1: Port reset is complete.
19	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect.
18	PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port.
	0: Port is not resumed.
	1: Port resume is complete.
17	PortEnableStatusChange. This bit indicates that the port has been disabled due to a hardware event (cleared PortEnableStatus).
	0: Port has not been disabled.
	1: PortEnableStatus has been cleared.
16	ConnectStatusChange. This bit indicates a connect or disconnect event has been detected. Writing a 1 clears this bit. Writing a 0 has no effect.
	0: No connect/disconnect event.
	1: Hardware detection of connect/disconnect event.
	If DeviceRemoveable is set, this bit resets to 1.
15:10	Reserved. Read/Write 0s.
9	Read: LowSpeedDeviceAttached. This bit defines the speed (and bud idle) of the attached device. It is only valid when CurrentConnectStatus is set.
	0: Full speed device.
	1: Low speed device.
	Write: ClearPortPower. Writing a 1 clears PortPowerStatus. Writing a 0 has no effect.
8	Read: PortPowerStatus. This bit reflects the power state of the port regardless of the power switching mode.
	0: Port power is off.
	1: Port power is on.
	If NoPowerSwitching is set, this bit is always read as 1.
	Write: SetPortPower. Writing a 1 sets PortPowerStatus. Writing a 0 has no effect.
7:5	Reserved. Read/Write 0s.
4	Read: PortResetStatus.
	0: Port reset signal is not active.
	1: Port reset signal is active.
	Write: SetPortReset. Writing a 1 sets PortResetStatus. Writing a 0 has no effect.



Bit	Description
3	Read: PortOverCurrentIndicator. This bit reflects the state of the OVRCUR pin dedicated to this port. This field is only valid if NoOverCurrentProtection is cleared and OverCurrentProtectionMode is set.
	0: No over-current condition.
	1: Over-current condition.
	Write: ClearPortSuspend. Writing a 1 initiates the selective resume sequence for the port. Writing a 0 has no effect.
2	Read: PortSuspendStatus.
	0: Port is not suspended.
	1: Port is selectively suspended.
	Write: SetPortSuspend. Writing a 1 sets PortSuspendStatus. Writing a 0 has no effect.
1	Read: PortEnableStatus.
	0: Port disabled.
	1: Port enabled.
	Write: SetPortEnable. Writing a 1 sets PortEnableStatus. Writing a 0 has no effect.
0	Read: CurrentConnectStatus.
	0: No device connected.
	1: Device connected.
	If DeviceRemoveable is set (not removable) this bit is always 1.
	Write: ClearPortEnable. Writing 1 a clears PortEnableStatus. Writing a 0 has no effect.
Note:	This register is reset by the UsbReset state.
Offset 50	Ch-5Fh HcRhPortStatus[3] Register (R/W) Reset Value = 00000000h
31:21	Reserved. Read/Write 0s.
20	PortResetStatusChange. This bit indicates that the port reset signal has completed.
	0: Port reset is not complete.
	· ·
	1: Port reset is complete.
19	Port reset is complete. PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect.
19	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing
	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect.
	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect. PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port.
	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect. PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port. 0: Port is not resumed.
18	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect. PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port. O: Port is not resumed. 1: Port resume is complete. PortEnableStatusChange. This bit indicates that the port has been disabled due to a hardware event (cleared PortEna-
18	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect. PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port. O: Port is not resumed. 1: Port resume is complete. PortEnableStatusChange. This bit indicates that the port has been disabled due to a hardware event (cleared PortEnableStatus).
18	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect. PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port. O: Port is not resumed. 1: Port resume is complete. PortEnableStatusChange. This bit indicates that the port has been disabled due to a hardware event (cleared PortEnableStatus). O: Port has not been disabled.
18	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect. PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port. O: Port is not resumed. 1: Port resume is complete. PortEnableStatusChange. This bit indicates that the port has been disabled due to a hardware event (cleared PortEnableStatus). O: Port has not been disabled. 1: PortEnableStatus has been cleared. ConnectStatusChange. This bit indicates a connect or disconnect event has been detected. Writing a 1 clears this bit.
18	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect. PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port. O: Port is not resumed. 1: Port resume is complete. PortEnableStatusChange. This bit indicates that the port has been disabled due to a hardware event (cleared PortEnableStatus). O: Port has not been disabled. 1: PortEnableStatus has been cleared. ConnectStatusChange. This bit indicates a connect or disconnect event has been detected. Writing a 1 clears this bit. Writing a 0 has no effect.
18	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect. PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port. 0: Port is not resumed. 1: Port resume is complete. PortEnableStatusChange. This bit indicates that the port has been disabled due to a hardware event (cleared PortEnableStatus). 0: Port has not been disabled. 1: PortEnableStatus has been cleared. ConnectStatusChange. This bit indicates a connect or disconnect event has been detected. Writing a 1 clears this bit. Writing a 0 has no effect. 0: No connect/disconnect event.
18	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect. PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port. 0: Port is not resumed. 1: Port resume is complete. PortEnableStatusChange. This bit indicates that the port has been disabled due to a hardware event (cleared PortEnableStatus). 0: Port has not been disabled. 1: PortEnableStatus has been cleared. ConnectStatusChange. This bit indicates a connect or disconnect event has been detected. Writing a 1 clears this bit. Writing a 0 has no effect. 0: No connect/disconnect event. 1: Hardware detection of connect/disconnect event.
18	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect. PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port. Port is not resumed. PortEnableStatusChange. This bit indicates that the port has been disabled due to a hardware event (cleared PortEnableStatus). Port has not been disabled. PortEnableStatus has been cleared. ConnectStatusChange. This bit indicates a connect or disconnect event has been detected. Writing a 1 clears this bit. Writing a 0 has no effect. No connect/disconnect event. Hardware detection of connect/disconnect event. If DeviceRemoveable is set, this bit resets to 1.
18 17 16	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect. PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port. O: Port is not resumed. 1: Port resume is complete. PortEnableStatusChange. This bit indicates that the port has been disabled due to a hardware event (cleared PortEnableStatus). O: Port has not been disabled. 1: PortEnableStatus has been cleared. ConnectStatusChange. This bit indicates a connect or disconnect event has been detected. Writing a 1 clears this bit. Writing a 0 has no effect. O: No connect/disconnect event. 1: Hardware detection of connect/disconnect event. If DeviceRemoveable is set, this bit resets to 1. Reserved. Read/Write 0s. Read: LowSpeedDeviceAttached. This bit defines the speed (and bud idle) of the attached device. It is only valid when
18 17 16	PortOverCurrentIndicatorChange. This bit is set when OverCurrentIndicator changes. Writing a 1 clears this bit. Writing a 0 has no effect. PortSuspendStatusChange. This bit indicates the completion of the selective resume sequence for the port. 0: Port is not resumed. 1: Port resume is complete. PortEnableStatusChange. This bit indicates that the port has been disabled due to a hardware event (cleared PortEnableStatus). 0: Port has not been disabled. 1: PortEnableStatus has been cleared. ConnectStatusChange. This bit indicates a connect or disconnect event has been detected. Writing a 1 clears this bit. Writing a 0 has no effect. 0: No connect/disconnect event. 1: Hardware detection of connect/disconnect event. If DeviceRemoveable is set, this bit resets to 1. Reserved. Read/Write 0s. Read: LowSpeedDeviceAttached. This bit defines the speed (and bud idle) of the attached device. It is only valid when CurrentConnectStatus is set.



Bit	Description
8	Read: PortPowerStatus. This bit reflects the power state of the port regardless of the power switching mode.
	0: Port power is off.
	1: Port power is on.
	If NoPowerSwitching is set, this bit is always read as 1.
	Write: SetPortPower. Writing a 1 sets PortPowerStatus. Writing a 0 has no effect.
7:5	Reserved. Read/Write 0s.
4	Read: PortResetStatus.
	0: Port reset signal is not active.
	1: Port reset signal is active.
	Write: SetPortReset. Writing a 1 sets PortResetStatus. Writing a 0 has no effect.
3	Read: PortOverCurrentIndicator. This bit reflects the state of the OVRCUR pin dedicated to this port. This field is only valid if NoOverCurrentProtection is cleared and OverCurrentProtectionMode is set.
	0: No over-current condition.
	1: Over-current condition.
	Write: ClearPortSuspend. Writing a 1 initiates the selective resume sequence for the port. Writing a 0 has no effect.
2	Read: PortSuspendStatus.
	0: Port is not suspended.
	1: Port is selectively suspended.
	Write: SetPortSuspend. Writing a 1 sets PortSuspendStatus. Writing a 0 has no effect.
1	Read: PortEnableStatus.
	0: Port disabled.
	1: Port enabled.
	Write: SetPortEnable. Writing a 1 sets PortEnableStatus. Writing a 0 has no effect.
0	Read: CurrentConnectStatus.
	0: No device connected.
	1: Device connected.
	If DeviceRemoveable is set (not removable) this bit is always 1.
	Write: ClearPortEnable. Writing 1 a clears PortEnableStatus. Writing a 0 has no effect.

Note: This register is reset by the UsbReset state.

Offset 60	h-9Fh	Reserved	Reset Value = xxh
Offset 100h-103h HceControl Register (R/W) Reset Value = 0		Reset Value = 00000000h	
31:9	Reserved. Read/Write 0s.		
8	A20State. Indicates curren GateA20Sequence is active	t state of Gate A20 on keyboard controller. Compared e.	against value written to 60h when
7	IRQ12Active. Indicates a p	ositive transition on IRQ12 from keyboard controller or	ccurred. Software writes this bit to 1 to
6	IRQ1Active. Indicates a point (set it to 0); a 0 write has	sitive transition on IRQ1 from keyboard controller occu no effect.	urred. Software writes this bit to 1 to clear
5	GateA20Sequence. Set by of any value other than D1h	HC when a data value of D1h is written to I/O port 64h	h. Cleared by HC on write to I/O port 64h
4		to 1, IRQ1 and IRQ12 from the keyboard controller capendent of the setting of the EmulationEnable bit in thi	•
3	· · · · · · · · · · · · · · · · · · ·	generates IRQ1 or IRQ12 as long as the OutputFull bit , IRQ1 is generated: if 1, then an IRQ12 is generated.	
2	CharacterPending. When set to 0.	set, an emulation interrupt will be generated when the 0	OutputFull bit of the HceStatus register is



Bit	Description		
1	EmulationInterrupt (Read Only). This bit is a static of	decode of the emulation in	terrupt condition.
0	EmulationEnable. When set to 1 the HC is enabled for legacy emulation and will decode accesses to I/O registers 60h and 64h and generate IRQ1 and/or IRQ12 when appropriate. The HC also generates an emulation interrupt at appropriate times to invoke the emulation software.		
Note:	This register is used to enable and control the emulation	hardware and report vario	us status information.
Offset 10	94h-107h HceInput Re	egister (R/W)	Reset Value = 000000xxh
31:8	Reserved. Read/Write 0s.		
7:0	InputData. This register holds data written to I/O port	s 60h and 64h.	
Note:	This register is the emulation side of the legacy Input But	ffer register.	
Offset 10	98h-10Bh HceOutput R	egister (R/W)	Reset Value = 000000xxh
31:8	Reserved. Read/Write 0s.		
7:0	OutputData. This register hosts data that is returned	when an I/O read of port 6	60h is performed by application software.
	This register is the emulation side of the legacy Output Boware.	uffer register where keyboa	ard and mouse data is to be written by soft-
Offset 10	OCh-10Fh HceStatus R	egister (R/W)	Reset Value = 00000000h
31:8	Reserved. Read/Write 0s.		
7	Parity. Indicates parity error on keyboard/mouse data		
6	Timeout. Used to indicate a time-out		
5	AuxOutputFull. IRQ12 is asserted whenever this bit	is set to 1 and OutputFull i	s set to 1 and the IRQEn bit is set.
4	Inhibit Switch. This bit reflects the state of the keybo	ard inhibit switch and is se	t if the keyboard is NOT inhibited.
3	CmdData. The HC will set this bit to 0 on an I/O write	to port 60h and on an I/O v	write to port 64h the HC will set this bit to 1.
2	Flag. Nominally used as a system flag by software to	indicate a warm or cold bo	pot.
		o this hit is set to 1 on an	I/O write to address 60h or 64h. While this
1	InputFull. Except for the case of a Gate A20 sequence bit is set to 1 and emulation is enabled, an emulation		
0	1	interrupt condition exists. /O port 60h. If IRQEn is se REn is set and AuxOutputF	et and AuxOutputFull is set to 0 then an full is set to 1 then and IRQ12 will be gen-



6.4.7 ISA Legacy Register Space

The ISA Legacy registers reside in the ISA I/O address space in the address range from 000h to FFFh and are accessed through typical input/output instructions (i.e., CPU direct R/W) with the designated I/O port address and 8-bit data.

The bit formats for the ISA Legacy I/O Registers plus two chipset-specific configuration registers used for interrupt mapping in the Core Logic module are given in this section. The ISA Legacy registers are separated into the following DMA Channel Control Registers, see Table 6-43

- DMA Page Registers, see Table 6-44
- Programmable Interval Timer Registers, see Table 6-45
- Programmable Interrupt Controller Registers, see Table 6-46
- · Keyboard Controller Registers, see Table 6-47
- Real-Time Clock Registers, see Table 6-48
- Miscellaneous Registers, see Table 6-49 (includes 4D0h and 4D1h Interrupt Edge/Level Select Registers)

Table 6-43. DMA Channel Control Registers

Bit	Description
I/O Port (DMA Channel 0 Address Register (R/W) s two successive bytes, byte 0, 1.
I/O Port 0	DO1h DMA Channel 0 Transfer Count Register (R/W) s two successive bytes, byte 0, 1.
I/O Port 0	DMA Channel 1 Address Register (R/W) s two successive bytes, byte 0, 1.
I/O Port (DMA Channel 1 Transfer Count Register (R/W) s two successive bytes, byte 0, 1.
I/O Port 0	DMA Channel 2 Address Register (R/W) s two successive bytes, byte 0, 1.
I/O Port (DMA Channel 2 Transfer Count Register (R/W) s two successive bytes, byte 0, 1.
I/O Port (DMA Channel 3 Address Register (R/W) s two successive bytes, byte 0, 1.
I/O Port 0	DMA Channel 3 Transfer Count Register (R/W) s two successive bytes, byte 0, 1.
	008h (R/W)
Read 7	DMA Status Register, Channels 3:0
,	Channel 3 Request. Indicates if a request is pending.0: No.1: Yes.
6	Channel 2 Request. Indicates if a request is pending. 0: No. 1: Yes.
5	Channel 1 Request. Indicates if a request is pending. 0: No. 1: Yes.
4	Channel 0 Request. Indicates if a request is pending. 0: No. 1: Yes.
3	Channel 3 Terminal Count. Indicates if TC was reached. 0: No. 1: Yes.



Table 6-43. DMA Channel Control Registers (Continued)

Bit	Description
2	Channel 2 Terminal Count. Indicates if TC was reached.
	0: No.
1	1: Yes. Channel 1 Terminal Count. Indicates if TC was reached.
1	0: No.
	1: Yes.
0	Channel 0 Terminal Count. Indicates if TC was reached.
	0: No. 1: Yes.
Write	DMA Command Register, Channels 3:0
7	DACK Sense.
	0: Active low.
	1: Active high.
6	DREQ Sense.
	0: Active high. 1: Active low.
5	Write Selection.
	0: Late write.
	1: Extended write.
4	Priority Mode.
	0: Fixed. 1: Rotating.
3	Timing Mode.
	0: Normal.
	1: Compressed.
2	Channels 3:0.
	0: Disable. 1: Enable.
1:0	Reserved. Must be set to 0.
I/O Port 0	99h Software DMA Request Register, Channels 3:0 (W)
7:3	Reserved. Must be set to 0.
2	Request Type.
	0: Reset. 1: Set.
1:0	Channel Number Request Select
	00: Channel 0.
	01: Channel 1.
	10: Channel 2. 11: Channel 3.
I/O Port 0	
7:3	Reserved. Must be set to 0.
2	Channel Mask.
	0: Not masked.
1.0	1: Masked. Channel Number Mask Select
1:0	Channel Number Mask Select. 00: Channel 0.
	01: Channel 1.
	10: Channel 2.
	11: Channel 3.



Table 6-43. DMA Channel Control Registers (Continued)

Bit	Description
I/O Port 00Bh DMA Channel Mode Register, Channels 3:0 (WO)	
7:6	Transfer Mode. 00: Demand. 01: Single. 10: Block. 11: Cascade.
5	Address Direction. 0: Increment. 1: Decrement.
4	Auto-initialize. 0: Disable. 1: Enable.
3:2	Transfer Type. 00: Verify. 01: Write transfer (I/O to memory). 10: Read transfer (memory to I/O). 11: Reserved.
1:0	Channel Number Mode Select. 00: Channel 0. 01: Channel 1. 10: Channel 2. 11: Channel 3.
I/O Port 0	DMA Clear Byte Pointer Command, Channels 3:0 (W)
I/O Port 0	DDh DMA Master Clear Command, Channels 3:0 (W)
I/O Port 0	DEh DMA Clear Mask Register Command, Channels 3:0 (W)
I/O Port 0	0Fh DMA Write Mask Register Command, Channels 3:0 (W)
I/O Port 0C0h DMA Channel 4 Address Register (R/W) Not used.	
I/O Port 0 Not used.	C2h DMA Channel 4 Transfer Count Register (R/W)
I/O Port 0C4h Not supported. DMA Channel 5 Address Register (R/W)	
I/O Port 0	
I/O Port 0C8h Not supported. DMA Channel 6 Address Register (R/W)	
I/O Port 0	
I/O Port 0	• ,
I/O Port 0	



Table 6-43. DMA Channel Control Registers (Continued)

Bit	Description
I/O Port	0D0h (R/W)
Read	DMA Status Register, Channels 7:4
Note:	Channels 5, 6, and 7 are not supported.
7	Channel 7 Request. Indicates if a request is pending.
	0: No.
	1: Yes.
6	Channel 6 Request. Indicates if a request is pending.
	0: No. 1: Yes.
5	Channel 5 Request. Indicates if a request is pending.
	0: No.
	1: Yes.
4	Undefined.
3	Channel 7 Terminal Count. Indicates if TC was reached.
	0: No.
	1: Yes.
2	Channel 6 Terminal Count. Indicates if TC was reached.
	0: No. 1: Yes.
1	Channel 5 Terminal Count. Indicates if TC was reached.
'	0: No.
	1: Yes.
0	Undefined.
Write	DMA Command Register, Channels 7:4
Note:	Channels 5, 6, and 7 are not supported.
7	DACK Sense.
	0: Active low.
	1: Active high.
6	DREQ Sense.
	0: Active high. 1: Active low.
5	Write Selection.
	0: Late write.
	1: Extended write.
4	Priority Mode.
	0: Fixed.
	1: Rotating.
3	Timing Mode.
	0: Normal. 1: Compressed.
2	Channels 7:4.
_	0: Disable.
	1: Enable.
1:0	Reserved. Must be set to 0.



Table 6-43. DMA Channel Control Registers (Continued)

//O Port 0 Note: (7:3 2	Reserved. Must be set to 0. Request Type. 0: Reset. 1: Set. Channel Number Request Select. 00: Illegal. 01: Channel 5. 10: Channel 6. 11: Channel 7.
7:3	Reserved. Must be set to 0. Request Type. 0: Reset. 1: Set. Channel Number Request Select. 00: Illegal. 01: Channel 5. 10: Channel 6. 11: Channel 7. DMA Channel Mask Register, Channels 7:4 (WO)
2	Request Type. 0: Reset. 1: Set. Channel Number Request Select. 00: Illegal. 01: Channel 5. 10: Channel 6. 11: Channel 7. DMA Channel Mask Register, Channels 7:4 (WO)
	0: Reset. 1: Set. Channel Number Request Select. 00: Illegal. 01: Channel 5. 10: Channel 6. 11: Channel 7. DMA Channel Mask Register, Channels 7:4 (WO)
1:0	1: Set. Channel Number Request Select. 00: Illegal. 01: Channel 5. 10: Channel 6. 11: Channel 7. DMA Channel Mask Register, Channels 7:4 (WO)
1:0	00: Illegal. 01: Channel 5. 10: Channel 6. 11: Channel 7. DMA Channel Mask Register, Channels 7:4 (WO)
	01: Channel 5. 10: Channel 6. 11: Channel 7. DMA Channel Mask Register, Channels 7:4 (WO)
	10: Channel 6. 11: Channel 7. DMA Channel Mask Register, Channels 7:4 (WO)
	D4h DMA Channel Mask Register, Channels 7:4 (WO)
	3 ,
/O Port 0	Channels 5, 6, and 7 are not supported.
Note: (
7:3	Reserved. Must be set to 0.
2	Channel Mask.
	0: Not masked. 1: Masked.
1:0	Channel Number Mask Select.
	00: Channel 4.
	01: Channel 5.
	10: Channel 6. 11: Channel 7.
/O Port 0	
	Channels 5, 6, and 7 are not supported.
7:6	Transfer Mode.
7.0	00: Demand.
	01: Single.
	10: Block.
5	11: Cascade. Address Direction.
3	0: Increment.
	1: Decrement.
4	Auto-initialize.
	0: Disabled
	1: Enable
3:2	Transfer Type.
	00: Verify. 01: Write transfer (I/O to memory).
	10: Read transfer (memory to I/O).
4.0	11: Reserved.
1:0	Channel Number Mode Select.
	00: Channel 4. 01: Channel 5.
	10: Channel 6.
	11: Channel 7. Channel 4 must be programmed in cascade mode. This mode is not the default.
/O Port 0	
	Channels 5, 6, and 7 are not supported.
/O Port 0	
	Channels 5, 6, and 7 are not supported.
/O Port 0	
	Channels 5, 6, and 7 are not supported.

Table 6-43. DMA Channel Control Registers (Continued)

Bit	Description	
I/O Port 0DEh DMA Write Mask Register Command, Channels 7:4 (W)		
Note:	ote: Channels 5, 6, and 7 are not supported.	

Table 6-44. DMA Page Registers

Bit Description	
I/O Port 081h	DMA Channel 2 Low Page Register (R/W)
Address bits [23:16] (byte 2).	
I/O Port 082h	DMA Channel 3 Low Page Register (R/W)
Address bits [23:16] (byte 2).	
I/O Port 083h	DMA Channel 1 Low Page Register (R/W)
Address bits [23:16] (byte 2).	
I/O Port 087h Address bits [23:16] (byte 2).	DMA Channel 0 Low Page Register (R/W)
I/O Port 089h	DMA Channel 6 Low Page Register (R/W)
Nor supported.	
I/O Port 08Ah	DMA Channel 7 Low Page Register (R/W)
Not supported.	
I/O Port 08Bh	DMA Channel 5 Low Page Register (R/W)
Not supported.	
I/O Port 08Fh Refresh address.	ISA Refresh Low Page Register (R/W)
I/O Port 481h	DMA Channel 2 High Page Register (R/W)
Address bits [31:24] (byte 3).	
Note: This register is reset to 00h on a	ny access to Port 081h.
I/O Port 482h	DMA Channel 3 High Page Register (R/W)
Address bits [31:24] (byte 3).	ay access to Part 000k
Note: This register is reset to 00h on a	
I/O Port 483h Address bits [31:24] (byte 3).	DMA Channel 1 High Page Register (R/W)
Note: This register is reset to 00h on a	ny access to Port 083h.
I/O Port 487h	DMA Channel 0 High Page Register (R/W)
Address bits [31:24] (byte 3).	
Note: This register is reset to 00h on a	ny access to Port 087h.
I/O Port 489h	DMA Channel 6 High Page Register (R/W)
Not supported	
I/O Port 48Ah	DMA Channel 7 High Page Register (R/W)
Not spported	
I/O Port 48Bh	DMA Channel 5 High Page Register (R/W)
Not supported	



Table 6-45. Programmable Interval Timer Registers

	rable 0-43. Frogrammable interval rimer Registers
Bit	Description
I/O Port	040h
Write	PIT Timer 0 Counter
7:0	Counter Value.
Read	PIT Timer 0 Status
7	Counter Output. State of counter output signal.
6	Counter Loaded. Indicates if the last count written is loaded.
	0: Yes. 1: No.
5:4	Current Read/Write Mode.
	00: Counter latch command.01: R/W LSB only.10: R/W MSB only.11: R/W LSB, followed by MSB.
3:1	Current Counter Mode. 0-5.
0	BCD Mode.
	0: Binary. 1: BCD (Binary Coded Decimal).
I/O Port	041h
Write	PIT Timer 1 Counter (Refresh)
7:0	Counter Value.
Read	PIT Timer 1 Status (Refresh)
7	Counter Output. State of counter output signal.
6	Counter Loaded. Indicates if the last count written is loaded.
	0: Yes. 1: No.
5:4	Current Read/Write Mode.
	 00: Counter latch command. 01: R/W LSB only. 10: R/W MSB only. 11: R/W LSB, followed by MSB.
3:1	Current Counter Mode. 0-5.
0	BCD Mode.
	0: Binary. 1: BCD (Binary Coded Decimal).



Revision 5.1

Table 6-45. Programmable Interval Timer Registers (Continued)

Bit	Description		
I/O Port 0	I/O Port 042h		
Write	PIT Timer 2 Counter (Speaker)		
7:0	Counter Value.		
Read	PIT Timer 2 Status (Speaker)		
7	Counter Output. State of counter output signal.		
6	Counter Loaded. Indicates if the last count written is loaded.		
	0: Yes. 1: No.		
5:4	Current Read/Write Mode.		
	00: Counter latch command. 01: R/W LSB only. 10: R/W MSB only. 11: R/W LSB, followed by MSB.		
3:1	Current Counter Mode. 0-5.		
0	BCD Mode.		
	0: Binary. 1: BCD (Binary Coded Decimal).		
I/O Port 0	943h (R/W) PIT Mode Control Word Register		
notes:	1. If bits [7:6] = 11: Register functions as Read Status Command and: Bit 5 = Latch Count Bit 4 = Latch Status Bit 3 = Select Counter 2 Bit 2 = Select Counter 1 Bit 1 = Select Counter 0 Bit 0 = Reserved		
2	 If bits [5:4] = 00: Register functions as Counter Latch Command and: Bits [7:6] = Selects Counter Bits [3:0] = Don't care 		
7:6	Counter Select.		
	00: Counter 0.01: Counter 1.10: Counter 2.11: Read-back command (Note 1).		
5:4	Current Read/Write Mode.		
	00: Counter latch command.01: R/W LSB only.10: R/W MSB only.11: R/W LSB, followed by MSB.		
3:1	Current Counter Mode. 0-5.		
0	BCD Mode. 0: Binary. 1: BCD (Binary Coded Decimal).		



Table 6-46. Programmable Interrupt Controller Registers

D:4	Pagarintian		
Bit	Description		
I/O Port 02	Port 020h / 0A0h Master / Slave PIC ICW1 (WO)		
7:5	Reserved. Must be set to 0.		
4	Reserved. Must be set to 1.		
3	Trigger Mode.		
	0: Edge. 1: Level.		
2	Vector Address Interval		
	0: 8 byte intervals.		
	1: 4 byte intervals.		
1	Reserved. Must be set to 0 (cascade mode).		
0	Reserved. Must be set to 1 (ICW4 must be programmed).		
I/O Port 02	21h / 0A1h Master / Slave PIC ICW2 (after ICW1 is written) (WO)		
7:3	A[7:3]. Address lines [7:3] for base vector for interrupt controller.		
2:0	Reserved. Must be set to 0.		
I/O Port 02	21h / 0A1h Master / Slave PIC ICW3 (after ICW2 is written) (WO)		
Master Pl	C ICW3		
7:0	Cascade IRQ. Must be 04h.		
Slave PIC	ICW3		
7:0	Slave ID. Must be 02h.		
I/O Port 02	21h / 0A1h Master / Slave PIC ICW4 (after ICW3 is written) (WO)		
7:5	Reserved. Must be set to 0.		
4	Special Fully Nested Mode.		
	0: Disable.		
	1: Enable.		
3:2	Reserved. Must be set to 0.		
1	Auto EOI.		
	0: Normal EOI. 1: Auto EOI.		
0	Reserved. Must be set to 1 (8086/8088 mode).		
I/O Port 02	21h / 0A1h (R/W) Master / Slave PIC OCW1		
	(except immediately after ICW1 is written)		
7	IRQ7 / IRQ15 Mask.		
	0: Not Masked.		
	1: Mask.		
6	IRQ6 / IRQ14 Mask.		
	0: Not Masked. 1: Mask.		
5	IRQ5 / IRQ13 Mask.		
	0: Not Masked.		
	1: Mask.		
4	IRQ4 / IRQ12 Mask.		
	0: Not Masked. 1: Mask.		
3	IRQ3 / IRQ11 Mask.		
	0: Not Masked.		
	1: Mask.		



Table 6-46. Programmable Interrupt Controller Registers (Continued)

	Table 0-40. Flogrammable inte	errupt Controller Registers (Continued)
Bit	Description	
2	IRQ2 / IRQ10 Mask.	
	0: Not Masked. 1: Mask.	
1	IRQ1 / IRQ9 Mask.	
	0: Not Masked. 1: Mask.	
0	IRQ0 / IRQ8 Mask.	
	0: Not Masked.	
	1: Mask.	
I/O Port 0	020h / 0A0h Master / Sla	ave PIC OCW2 (WO)
7:5	Rotate/EOI Codes.	
	000: Clear rotate in Auto EOI mode 001: Non-specific EOI 010: No operation 011: Specific EOI (bits [2:0] must be valid)	100: Set rotate in Auto EOI mode101: Rotate on non-specific EOI command110: Set priority command (bits [2:0] must be valid)111: Rotate on specific EOI command
4:3	Reserved. Must be set to 0.	
2:0	IRQ Number (000-111).	
I/O Port 0	020h / 0A0h Master / Sla	ave PIC OCW3 (WO)
7	Reserved. Must be set to 0.	
6:5	Special Mask Mode.	
	00: No operation.01: No operation.10: Reset Special Mask Mode.11: Set Special Mask Mode.	
4	Reserved. Must be set to 0.	
3	Reserved. Must be set to 1.	
2	Poll Command.	
	0: Disable.1: Enable.	
1:0	Register Read Mode.	
	00: No operation.01: No operation.10: Read interrupt request register on next read11: Read interrupt service register on next read	
I/O Port 0	020h / 0A0h Master / Slave PIC Interru	pt Request and Service Registers Commands (RO)
	020h / 0A0h Master / Slave PIC Interru	pt Request and Service Registers c Commands (RO)
The functi	020h / 0A0h Master / Slave PIC Interru for OCW3	pt Request and Service Registers c Commands (RO)
The functi	Master / Slave PIC Interrul for OCW3 ion of this register is set with bits [1:0] in a write to 0.	pt Request and Service Registers c Commands (RO)
The functi	Master / Slave PIC Interruptor OCW3 ion of this register is set with bits [1:0] in a write to 0: Request Register IRQ7 / IRQ15 Pending. 0: Yes.	pt Request and Service Registers c Commands (RO)
The functi	Master / Slave PIC Interruptor OCW3 ion of this register is set with bits [1:0] in a write to 0. Request Register IRQ7 / IRQ15 Pending. 0: Yes. 1: No.	pt Request and Service Registers c Commands (RO)
The functi	Master / Slave PIC Interruptor OCW3 ion of this register is set with bits [1:0] in a write to 0: Request Register IRQ7 / IRQ15 Pending. 0: Yes. 1: No. IRQ6 / IRQ14 Pending.	pt Request and Service Registers c Commands (RO)
The functi	Master / Slave PIC Interruptor OCW3 ion of this register is set with bits [1:0] in a write to 0: Request Register IRQ7 / IRQ15 Pending. 0: Yes. 1: No. IRQ6 / IRQ14 Pending. 0: Yes.	pt Request and Service Registers c Commands (RO)
The function Interrupt 7	Master / Slave PIC Interruptor OCW3 ion of this register is set with bits [1:0] in a write to 0: Request Register IRQ7 / IRQ15 Pending. 0: Yes. 1: No. IRQ6 / IRQ14 Pending. 0: Yes. 1: No.	pt Request and Service Registers c Commands (RO)
The functi	Master / Slave PIC Interruptor OCW3 ion of this register is set with bits [1:0] in a write to 0: Request Register IRQ7 / IRQ15 Pending. 0: Yes. 1: No. IRQ6 / IRQ14 Pending. 0: Yes. 1: No. IRQ5 / IRQ13 Pending.	pt Request and Service Registers 5 Commands (RO)
The function Interrupt 7	Master / Slave PIC Interruptor OCW3 ion of this register is set with bits [1:0] in a write to 0: Request Register IRQ7 / IRQ15 Pending. 0: Yes. 1: No. IRQ6 / IRQ14 Pending. 0: Yes. 1: No.	pt Request and Service Registers 5 Commands (RO)
The function Interrupt 7	Master / Slave PIC Interruptor OCW3 ion of this register is set with bits [1:0] in a write to 0: Request Register IRQ7 / IRQ15 Pending. 0: Yes. 1: No. IRQ6 / IRQ14 Pending. 0: Yes. 1: No. IRQ5 / IRQ13 Pending. 0: Yes.	pt Request and Service Registers 5 Commands (RO)



Table 6-46. Programmable Interrupt Controller Registers (Continued)

Bit	Description
3	IRQ3 / IRQ11 Pending.
	0: Yes.
	1: No.
2	IRQ2 / IRQ10 Pending.
	0: Yes.
	1: No.
1	IRQ1 / IRQ9 Pending.
	0: Yes.
	1: No.
0	IRQ0 / IRQ8 Pending.
	0: Yes.
	1: No.
Interrupt	Service Register
7	IRQ7 / IRQ15 In-Service.
	0: No.
	1: Yes.
6	IRQ6 / IRQ14 In-Service.
	0: No.
	1: Yes.
5	IRQ5 / IRQ13 In-Service.
	0: No.
	1: Yes.
4	IRQ4 / IRQ12 In-Service.
	0: No.
	1: Yes.
3	IRQ3 / IRQ11 In-Service.
	0: No.
	1: Yes.
2	IRQ2 / IRQ10 In-Service.
	0: No.
	1: Yes.
1	IRQ1 / IRQ9 In-Service.
	0: No. 1: Yes.
0	IRQ0 / IRQ8 In-Service.
	0: No. 1: Yes.
	1. TES.

Description



Table 6-47. Keyboard Controller Registers

DIL	Description	
I/O Port 06	0h	External Keyboard Controller Data Register (R/W)

Keyboard Controller Data Register. All accesses to this port are passed to the ISA bus. If the fast keyboard gate A20 and reset features are enabled through bit 7 of the ROM/AT Logic Control Register (F0 Index 52h[7]), the respective sequences of writes to this port assert the A20M# signal or cause a warm CPU reset.

I/O Port 06	h Port B Control Register (R/W)	Reset Value: 00x01100b	
7	PERR#/SERR# Status. (Read Only) Indicates if a PCI bus error (PERR#/SERR#) was assess3200.	erted by a PCI device or by the	
	0: No. 1: Yes. This bit can only be set if ERR_EN (bit 2) is set 0. This bit is set 0 after a write to ERR_EN v	with a 1 or after reset	
6	IOCHK# Status. (Read Only) Indicates if an I/O device is reporting an error to the SC3200.		
	0: No. 1: Yes. This bit can only be set if IOCHK_EN (bit 3) is set 0. This bit is set 0 after a write to IOCHK_	EN with a 1 or after reset.	
5 PIT OUT2 State. (Read Only) This bit reflects the current status of the of the PIT Counter 2 (OUT2). 4 Toggle. (Read Only) This bit toggles on every falling edge of Counter 1 (OUT1).		(OUT2).	
3 IOCHK# Enable.			
	0: Generates an NMI if IOCHK# is driven low by an I/O device to report an error. Note that1: Ignores the IOCHK# input signal and does not generate NMI.	NMI is under SMI control.	
2	PERR/ SERR Enable. Generate an NMI if PERR#/SERR# is driven active to report an error	ſ.	
	0: Enable. 1: Disable.		
1 PIT Counter2 (SPKR).			
	0: Forces Counter 2 output (OUT2) to zero.1: Allows Counter 2 output (OUT2) to pass to the speaker.		
0	PIT Counter2 Enable.		
	O: Sets GATE2 input low. 1: Sets GATE2 input high.		

I/O Port 062h

External Keyboard Controller Mailbox Register (R/W)

Keyboard Controller Mailbox Register.

I/O Port 064h

External Keyboard Controller Command Register (R/W)

Keyboard Controller Command Register. All accesses to this port are passed to the ISA bus. If the fast keyboard gate A20 and reset features are enabled through bit 7 of the ROM/AT Logic Control Register (F0 Index 52h[7]), the respective sequences of writes to this port assert the A20M# signal or cause a warm CPU reset.

I/O Port 066h External Keyboard Controller Mailbox Register (R/W)

Keyboard Controller Mailbox Register.

I/O Port 09	2h Port A Control Register (R/W)	Reset Value: 02h
7:2	Reserved. Must be set to 0.	
1	A20M# Assertion. Assert A20# (internally).	
	0: Enable.1: Disable.This bit reflects A20# status and can be changed by keyboard command monitoring.	
	An SMI event is generated when this bit is changed, if enabled by F0 index $53h[0]$. The SMI state O Offset $00h/02h[7]$.	us is reported in F1BAR0+I/
0	Fast CPU Reset. WM_RST SMI is asserted to the BIOS.	
	0: Disable.1: Enable.This bit must be cleared before the generation of another reset.	



Table 6-48. Real-Time Clock Registers

Bit	Description					
I/O Port 0	O Port 070h RTC Address Register (WO)					
This regis	ter is shadowed within the Core Logic module and is read through the RTC Shadow Register (F0 Index BBh).					
7	NMI Mask.					
	0: Enable. 1: Mask.					
6:0 RTC Register Index. A write of this register sends the data out on the ISA bus and also causes RTCALE to be trigger (RTCALE is an internal signal between the Core Logic module and the internal RTC controller.)						
I/O Port 0	771h RTC Data Register (R/W)					
A read of	this register returns the value of the register indexed by the RTC Address Register.					
A write of	this register sets the value into the register indexed by the RTC Address Register					
I/O Port 0	72h RTC Extended Address Register (WO)					
7	Reserved.					
6:0	RTC Register Index. A write of this register sends the data out on the ISA bus and also causes RTCALE to be triggered. (RTCALE is an internal signal between the Core Logic module and the internal RTC controller.)					
I/O Port 0	73h RTC Data Register (R/W)					
AA read o	of this register returns the value of the register indexed by the RTC Extended Address Register.					
A write of	this register sets the value into the register indexed by the RTC Extended Address Register					

Table 6-49. Miscellaneous Registers

		Table 6-49. Miscellaneous Registers	
Bit	Description		
I/O Port 0	,	Coprocessor Error Register (W)	Reset Value: F0h
	either port when the interna sserted until the FERR# de-	FERR# signal is asserted causes the Core Logic Module to asseasserts.	ert internal IGNNE#. IGNNE#
I/O Ports	170h-177h/376h-377h	Secondary IDE Registers (R/W)	
		led, reads or writes to these registers cause the local IDE interface ng standard ISA bus cycles.	e signals to operate according to
I/O Ports	IF0h-1F7h/3F6h-3F7h	Primary IDE Registers (R/W)	
		ed, reads or writes to these registers cause the local IDE interface ng standard ISA bus cycles.	e signals to operate according to
I/O Port 4	O0h	Interrupt Edge/Level Select Register 1 (R/W)	Reset Value: 00h
Notes: 1	. If ICW1 - bit 3 in the PIC	is set as level, it overrides the setting for bits [7:3] in this register.	
2	. Bits [7:3] in this register a	are used to configure a PCI interrupt mapped to IRQ[x] on the PIC	C as level-sensitive (shared).
7	IRQ7 Edge or Level Sen	sitive Select. Selects PIC IRQ7 sensitivity configuration.	
	0: Edge. 1: Level.		
6	IRQ6 Edge or Level Sen	sitive Select. Selects PIC IRQ6 sensitivity configuration.	
	0: Edge. 1: Level.		
5	IRQ5 Edge or Level Sen	sitive Select. Selects PIC IRQ5 sensitivity configuration.	
	0: Edge. 1: Level.		
4	IRQ4 Edge or Level Sen	sitive Select. Selects PIC IRQ4 sensitivity configuration.	
	0: Edge. 1: Level.		



Table 6-49. Miscellaneous Registers (Continued)

	Table 6-49. Miscellatieous Registers (Continued)						
Bit	Description						
3	IRQ3 Edge or Level Sensitive Select. Selects PIC IRQ3 sensitivity configuration.						
	0: Edge. 1: Level.						
2:0	Reserved. Must be set to 0.						
I/O Port	4D1h Interrupt Edge/Level Select Register 2 (R/W) Reset Value: 00h						
Notes:	1. If ICW1 - bit 3 in the PIC is set as level, it overrides the setting for bits 7:6 and 4:1 in this register.						
	2. Bits [7:6] and [4:1] in this register are used to configure a PCI interrupt mapped to IRQ[x] on the PIC as level-sensitive (shared).						
7	IRQ15 Edge or Level Sensitive Select. Selects PIC IRQ15 sensitivity configuration.						
	0: Edge. 1: Level.						
6	IRQ14 Edge or Level Sensitive Select. Selects PIC IRQ14 sensitivity configuration.						
	0: Edge. 1: Level.						
5	Reserved. Must be set to 0.						
4	IRQ12 Edge or Level Sensitive Select. Selects PIC IRQ12 sensitivity configuration.						
	0: Edge. 1: Level.						
3	IRQ11 Edge or Level Sensitive Select. Selects PIC IRQ11 sensitivity configuration.						
	0: Edge. 1: Level.						
2	IRQ10 Edge or Level Sensitive Select. Selects PIC IRQ10 sensitivity configuration.						
	0: Edge. 1: Level.						
1	IRQ9 Edge or Level Sensitive Select. Selects PIC IRQ9 sensitivity configuration.						
	0: Edge. 1: Level.						
0	Reserved. Must be set to 0.						

Video Processor Module Revision 5.1

Video Processor Module

The Video Processor module contains a high performance video back-end accelerator, a video/graphics Mixer/Blender, a Video Input Port (VIP), supporting a TFT interface. The back-end accelerator functions include horizontal and vertical scaling and filtering of the video stream. The Mixer/Blender function includes color space conversion, gamma correction, and mixing or alpha blending the video and graphics streams.

General Features

- · Hardware video acceleration
- Graphics/video overlay and blending
- · Integrated PLL programmable up to 135 MHz
- Selection of interlaced and progressive video from the GX1 module and the Direct Video Port

Video Input Port (VIP)

- · CCIR-656 compatible
- · Capture Video/VBI modes
- · Direct Video/VBI modes

Hardware Video Acceleration

- · Arbitrary X and Y interpolation using three line-buffers
- · YUV-to-RGB color space conversion
- · Horizontal filtering and downscaling
- Supports 4:2:2, 4:2:0 YUV formats and RGB 5:6:5 format

Graphics-Video Overlay and Blending

- · Overlay of video up to 16 bpp
- Supports chroma key and color key for both graphics and video streams
- Supports alpha-blending with up to three alpha windows that can overlap one another
- 8-Bit alpha values with automatic increment or decrement on each frame
- · Optional Gamma Correction for video or graphics

Compatibility

- Supports Microsoft's DirectDraw®/Direct Video and Display Control Interface (DCI) Version 2.0 for full motion playback acceleration
- Compliant with PC98 and PC99 V0.7
- Compatible with VESA, VGA, DPMS, and DDC2 standards for enhanced display control and power management

TFT Interface

- TFT modes:
 - TFT on IDE: FPCLK max is 40 MHz
 - TFT on Parallel Port: FPCLK max is 80 MHz
 - 640x480x16 bpp at 60-85 Hz vertical refresh rates
 - 800x600x16 bpp at 60-85 Hz vertical refresh rates
 - 1024x768x16 bpp at 60-75 Hz vertical refresh rates
 - 1280x1024x8 bpp at 60 Hz vertical refresh rate

Revision 5.1 Video Processor Module

7.1 Module Architecture

Figure 7-1 shows a top-level block diagram of the Video Processor. For information about the relationship between the Video Processor and the other modules of the SC3200, see Section 2.2 on page 22. The Video Processor module includes the following functions:

- Video Input Port
 - CCIR-656 decoder
 - Capture Video/VBI modes
 - Direct Video mode
- Video Formatter
 - Asynchronous video interface
 - Horizontal/vertical scalers
 - Filters
 - **GX1 Graphics Data**

- Mixer/Blender
 - Overlay with color/chroma key
 - Gamma correction
 - Color space converters
 - Alpha blender
- · TFT interface
- · Dot Clock PLL

The following subsections describe each block in detail.

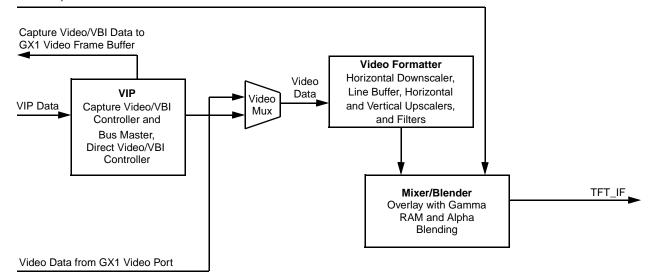


Figure 7-1. Video Processor Block Diagram



7.2 Functional Description

To understand why the Video Processor functions as it does, it is first important to understand the difference between video and graphics. Video is pictures in motion, which usually starts out in an encoded format (i.e., MPEG2, AVI, MPEG4) or is a TV broadcast. These pictures or frames are generally dynamic and are drawn 24 to 30 frames per second. Conversely, graphic data is relatively static and is drawn - usually using hardware accelerators. Most IA devices need to support both video and graphics displayed at the same time. For some IA devices, such as set-top boxes, video is dominant. While for other devices, such as consumer access devices and thin clients, graphics is dominant. What this means for the Video Processor is that for video centric devices, graphics overlays the video; and for graphics centric devices, video overlays the graphics.

Video Support

The SC3200 gets video from two sources, either the VIP block or the GX1 module's video frame buffer. The VIP block supports the CCIR-656 data protocol. The CCIR-656 protocol supports TV data (NTSC or PAL) and defines the format for active video data and vertical blanking interval (VBI) data. Conforming CCIR-656 data matches exactly what is needed for a TV: full frame, interlaced, 27 MHz pixel clock, and 50 or 60 Hz refresh rate. Full frame pixel resolution and the refresh rate depends on the TV standard: NTSC, PAL, or SECAM.

If the VIP input data is full frame (conforming data), the data can go directly from the VIP block to the Video Formatter. This is known as Direct Video mode. In this mode, the data never leaves the Video Processor module. Direct Video mode can only be used under very specific conditions which will be explained later. If the VIP data is less than full frame (non conforming data), the VIP block will bus master the video data to the GX1 module's video frame buffer. The GX1 module's display controller then moves the video data out of the video frame buffer and sends it to the Video Formatter. Using this method the temporal (refresh rate) and/or spatial (image less then full screen) differences between the VIP data and the output device are reconciled. This method is known as Capture Video mode. How each mode is setup and operates is explained further in Section 7.2.1 on page 331.

VBI Support

VBI (vertical blanking interval) data is placed in the video data stream during a portion of the vertical retrace period. The vertical retrace period physically consists of several horizontal lines (24 for NTSC and 25 for PAL systems) of non-active video. Data can be placed on some of these lines for other uses.

The active video and vertical retrace period horizontal lines are logically defined into 23 types: logical line 2 through logical line 24 (no logical line 1). Logical lines 2 through 23 occur during the vertical retrace period and logical line 24 represents all the active video lines. Logical lines 10 through 21 for NTSC and 6 through 23 for PAL are the nominal VBI lines. The rest of the logical lines, 2 through 9, 22, and 23 for NTSC and 2 through 6 for PAL occur during the vertical retrace period but do not normally carry user data. An example of VBI usage is Closed Captioning, which occupies VBI logical line 21 for NTSC. Figure 7-2 and Figure 7-3 on page 330 show the (relationship between the) physical scan lines and logical scan lines for the odd and even fields in the NTSC format.

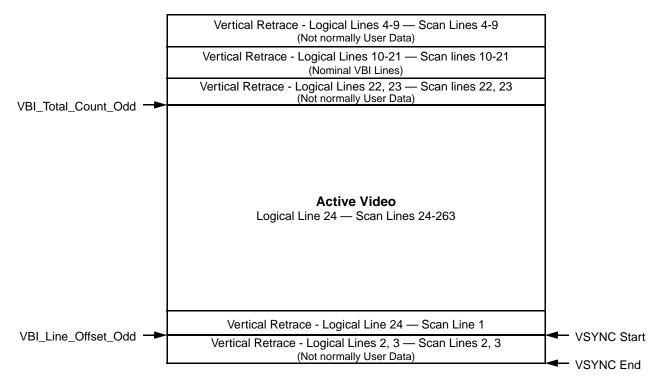


Figure 7-2. NTSC 525 Lines, 60 Hz, Odd Field

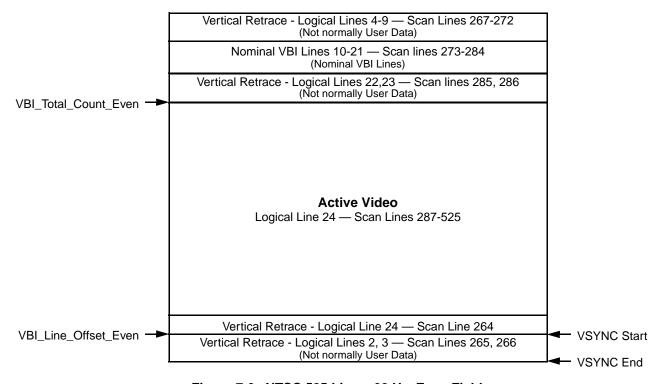


Figure 7-3. NTSC 525 Lines, 60 Hz, Even Field

Video Processor Module Revision 5.1 AMD

7.2.1 Video Input Port (VIP)

The VIP block is designed to interface the SC3200 with external video processors (e.g., Philips PNX1300 or Sigma Designs EM8400) or external TV decoders (e.g., Philips SAA7114). It inputs CCIR-656 Video and raw VBI data sourced by those devices, decodes the data, and delivers the data directly to the Video Formatter (Direct Video mode) or to the GX1 module's video frame buffer (Capture Video/VBI modes). Figure 7-4 shows a diagram of the VIP block.

From the VIP block's perspective, Direct Video mode is always on. There are no registers that enable/disable Direct Video mode. The data source selected at the video mux (F4BAR0+Memory Offset 400h[1:0]) determines if the data from the VIP interface is moved directly or must be captured.

Two FIFOs in the VIP block support the efficient movement of Video and VBI data. For Capture Video/VBI modes, a 128-byte FIFO buffers both Video and raw VBI data processed by the CCIR-656 decoder. For Direct Video mode, there is a 2048-byte FIFO that buffer the CCIR-656 decoder's video data. The FIFOs are also used to provide clock domain changes. The VIP interface clock (nominally 27 MHz) is the input clock domain for both FIFOs. For the Capture Video/VBI FIFO, the data is clocked out using the FPCI clock (33 or 66 MHz). For the Direct Video FIFO, the

Video data is clocked out using the GX1's Video port clock (75, 116, or 133 MHz GX1 core clock divided by 2 or 4).

7.2.1.1 Direct Video Mode

As stated previously, Direct Video mode is on by default so no registers need to be programmed to support this mode other than to select the direct video data at the video mux. The video mux control register is located at F4BAR0+Memory Offset 400h[1:0].

Direct Video mode while supported is not an optimal mode of operation. This mode supports only one vertical resolution and refresh rate, which is that of the incoming data. Horizontal resolution can be scaled if desired. Since the incoming data has odd and even fields, incoming line must be doubled for it to display properly. This is equivalent to the Bob technique which is explained later in this section.

GenLock

Because video input data from the VIP is sent directly, without significant buffering frame-to-field synchronization is required with the GX1 module's graphics data. This synchronization is known as GenLock. The GenLock registers are located at F4BAR0+Memory Offset 420h and 424h.

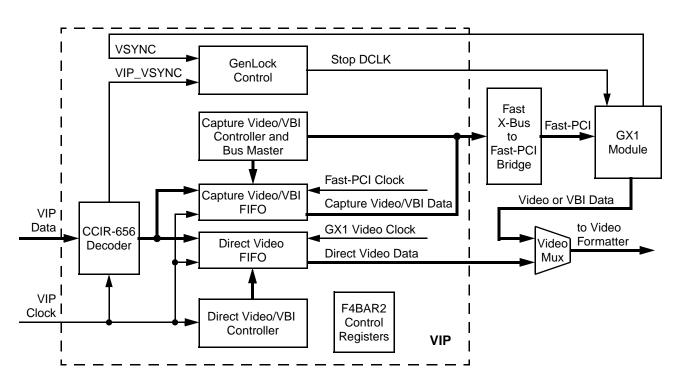


Figure 7-4. VIP Block Diagram

The GenLock control hardware is used to synchronize the video input's field with the GX1 module's graphics frame. The graphics data is always sent full frame. For the GenLock function to perform correctly, the GX1 module's Display Controller must be programmed to have a slightly faster frame time then the video input's field time. This is best accomplished by programming the GX1 module's Display Controller with a few less (three to five) horizontal lines then the VIP interface. GenLock is accomplished by stopping the clock driving the GX1 module's graphics frame until the VIP vertical sync occurs (plus some additional delay, via F4BAR0+Memory Offset 424h).

The GenLock function provides a timeout feature (GENLOCK_TOUT_EN, F4BAR0+Memory Offset 420h[4]) in case the video port input clock stops due to a problem with incoming video.

7.2.1.2 Capture Video Mode

Capture Video mode is a process for bus mastering Video data received from the VIP block to the GX1 module's Video Frame Buffer. The GX1 module's Display Controller then moves the data from the Video Frame Buffer to the Video Formatter. Usually Capture Video mode is used because the data coming in from the VIP block is interlaced and has a 30 Hz refresh rate (NTSC format) and the TFT panel, is progressive and has a 60 to 85 Hz refresh rate. The Capture Video mode process must convert the interlaced data to progressive data and change the frames per second. There are two methods to perform the interlaced to progressive conversion; Bob and Weave. Each method uses a different mechanism to up the refresh rate

Bob

The Bob method displays the odd frame followed by the even frame. If a full-scale image is displayed, each line in the odd and even field must be vertically doubled (see Section 7.2.2.5 "2-Tap Vertical and Horizontal Upscalers" on page 337) because each odd and each even field only contain one-half a frames worth of data. This means that the Bob method reduces the video image resolution, but has a higher effective refresh rate. If there is a change of refresh rate from the VIP block to the display device, then a field will sometimes be displayed twice. The advantage of this method is that the process is simple as only half the data is transmitted from the GX1 module's Video Frame Buffer to the Video Processor per a given amount of time, therefore reducing the memory bandwidth requirement. The disadvantage is that there are some observable visual effects due to the reduction in resolution.

Figure 7-5 on page 333 is an example of how the Bob method is performed. The example assumes that the display device is a TFT at 85 Hz refresh and single buffering is used for the data. The example does not assume anything regarding scaling that may be performed in the Video Processor. The example is only presented to allow for a general understanding of how the SC3200's video support hardware works and not as an all-inclusive statement of operation.

The following procedure is an example of how to create a Bob method. This example assumes single buffering in the GX1 module's video frame buffer. The Video Processor registers that control the VIP bus master only need to be initialized.

1) Program the VIP bus master address registers.

Three registers control where the VIP video data is stored in the GX1 module's frame buffer:

- F4BAR2+Memory Offset 20h Video Data Odd Base Address
- F4BAR2+Memory Offset 24h Video Data Even Base Address
- F4BAR2+Memory Offset 28h Video Data Pitch

The Video Data Even Base Address must be separated from the Video Data Odd Base Address by at least the field data size. The Video Data Pitch register must be programmed to 00000000h.

2) Program other VIP bus master support registers.

In F4BAR2+Memory Offset 00h, make sure that the VIP FIFO bus request threshold is set to 32 bytes (bit 22 = 1) and that the Video Input Port mode is set to CCIR-656. An interrupt needs to be generated so that the GX1 module's video frame buffer pointer can flip to the field that has completed transfer to the video frame buffer. So in F4BAR2+Memory Offset 04h, enable the Field Interrupt bit. Auto-Flip is normally set to allow the CCIR-656 Decoder to identify which field is being processed. Capture video data needs to be enabled and Run Mode Capture is set to Start Capture at beginning of next field. Data is now being captured to the frame buffer.

3) Field Interrupt.

When the field interrupt occurs, the interrupt handler must program the GX1 module's video buffer start off-set value (GX_BASE+Memory Offset 8320h) with the address of the field that was just received from the VIP interface. This action will cause the display controller to ping-pong between the two fields. The new address will not take affect until the start of a new display controller frame. The field that was just received can be known by reading the Current Field bit at F4BAR2+Memory Offset 08h[24].

Video Processor Module

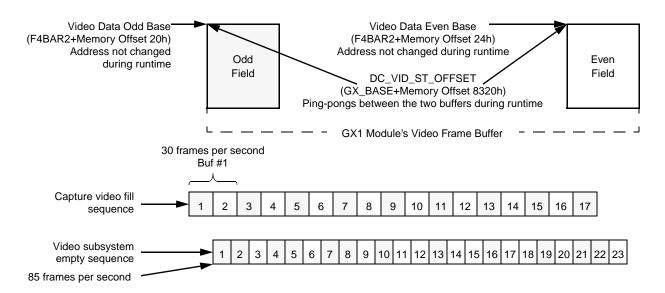


Figure 7-5. Capture Video Mode Bob Example Using One Video Frame Buffer

Weave

The Weave method assembles the odd field and even field together to form the complete frame, and then renders the "weaved" frames to the display device. The Video data is converted from interlaced to progressive. Since both fields are rendered simultaneously, the GX1 module's video frame buffer must be at least double buffered. The Weave method has the advantage of not creating the temporal effects that Bob does. The disadvantage of Weave is twice as much data is transferred from the video frame buffer to the Video Processor; meaning that Weave uses more memory bandwidth.

Figure 7-6 on page 334 is an example of the Weave method in action. As in the Bob example (Figure 7-5), a TPT panel at 85 Hz refresh is assumed. Double buffering of the incoming data is also assumed. The example does not assume anything about any scaling that may be done in the Video Processor. No attempt has been made to assure that this example is absolutely workable. The example is only presented to allow for a general understanding of how the SC3200's video support hardware works.

The following procedure is an example of how to create the Weave method. Since at least double buffering is required, more of the VIP's control registers are used for Weave than required for Bob during video runtime.

1) Program the VIP bus master address registers.

Three registers control where the VIP video data is stored in the GX1 module's frame buffer:

- F4BAR2+Memory Offset 20h Video Data Odd Base Address
- F4BAR2+Memory Offset 24h Video Data Even **Base Address**
- F4BAR2+Memory Offset 28h Video Data Pitch

The Video Data Even Base Address must be separated from the Video Data Odd Base Address by one horizontal line. The Video Data Pitch register must be programmed to one horizontal line.

Program other VIP bus master support registers.

Ensure the VIP FIFO Bus Request Threshold is set to 32 bytes (F4BAR2+Memory Offset 00h[22] = 1) and the Video Input Port mode is set to CCIR-656 (F4BAR2+Memory Offset 00h[1:0] = 10). An interrupt needs to be generated so that the GX1 module's video frame buffer pointer can flip to the field that has completed transfer to the video frame buffer. So the Field Interrupt bit (F4BAR2+Memory Offset 04h[16] = 1). must be enabled. Auto-Flip is normally set (F4BAR2+Memory Offset 04h[10] = 0) to allow the CCIR-656 decoder to identify which field is being processed. Capture video data needs to be enabled (F4BAR2+Memory Offset 04h[10] = 1) and Run Mode Capture is set to Start Capture (F4BAR2+Memory Offset 04h[1:0] = 11) at beginning of next field. Data is now being captured to the frame buffer.

Revision 5.1 Video Processor Module

3) Field Interrupt.

When the field interrupt occurs on the completion of an odd field, the interrupt must program the Video Data Odd Base Address with the other buffer's address. The odd field will ping-pong between the two buffers. When the interrupt is due to the completion of an even field, the interrupt handler must program the GX1 module's video buffer start offset value (GX_BASE+Memory Offset 8320h) with the address of the frame (both odd and even fields) that was just received from the VIP block. This new address will not take affect until the start of a new frame. It must also program the Video Data Even Base Address with the other buffer so that the even field will ping-pong just like the odd field. The field just received can be known by reading the Current Field bit (F4BAR2+Memory Offset 08h[24]).

7.2.1.3 Capture VBI Mode

There are three types of VBI data defined by the CCIR-656 protocol: Task A data, Task B data, and Ancillary data. The VIP block supports the capture for each data type. Generally Task A data is the data type captured. Just as in Capture Video mode, there are three registers that tell the bus master where to put the raw VBI data in the GX1 module's frame buffer. Once the raw VBI data has been captured, the data can be manipulated or decoded. The data can also be used by an application. An example of this would be an Internet address that is encoded on one or more of the VBI lines, or have an application decode the Closed Captioning information put in the graphics frame buffer.

The registers, F4BAR2+Memory Offset 40h, 44h, and 48h, tell the bus master the destination addresses for the VBI data in the GX1 module's frame buffer. Five bits (F4BAR2+Memory Offset 00h[21:17]) are used to tell the bus master the data types to store. Capture VBI mode needs to be enabled at F4BAR2+Memory Offset 04h[9,1:0]. The Field Interrupt bit (F4BAR2+Memory Offset 04h[16]) should be used by the software driver to know when the captured VBI data has been completed for a field.

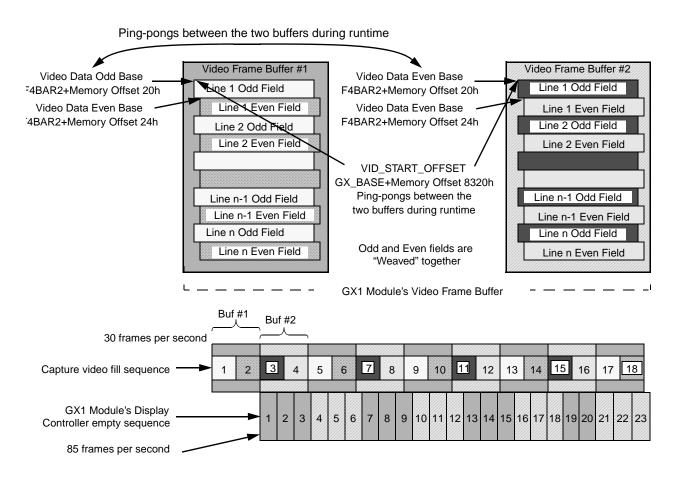


Figure 7-6. Capture Video Mode Weave Example Using Two Video Frame Buffers

Video Processor Module Revision 5.1 AMD

7.2.2 Video Block

The Video block receives video data from the VIP block or the GX1 module's video frame buffer. The video data is formatted and scaled and then sent to the Mixer/Blender. The video data also changes clock domains while in the Video block. It is clocked in with the GX1 module's video clock and it is clocked out with the GX1 module's graphics clock. A diagram of the Video block is shown in Figure 7-7.

7.2.2.1 Video Input Formatter

The Video Input Formatter accepts video data 8 bits at a time in YUV 4:2:2, YUV 4:2:0, or RGB 6:5:6 format. The GX1 module's video clock is the source clock. The data can be interlaced or progressive. When the data comes directly from the VIP block it is usually interlaced. The video format is configured via the EN_42X bit (F4BAR0+Memory Offset 00h[28] and the GV_SEL bit (F4BAR0+Memory Offset 4Ch[13]). The byte order for each format is configured in the VID FMT bits (F4BAR0+Offset 00h[3:21).

RGB 5:6:5 – For this format each pixel is described as a 16-bit value:

Bits [15:11] = Red Bits [10:5] = Green Bits [4:0] = Blue

YUV 4:2:0 – This format is not supported by the GX1 module. The Horizontal Downscaler in the Video block cannot be used if the video data is in this format. In this format, 4 bytes of data are used to describe two pixels. The 4 bytes contain two Y values one for each pixel; one U and one V for both pixels. For each horizontal line, all the Y values are received first. The U values are received next and the V values are received last. For example for a horizontal line that has 720 pixels, there are 720 bytes of Y, followed by 360 bytes of U, followed by 360 bytes of V.

YUV 4:2:2 – In this format each DWORD in the horizontal line represent two pixels. There are two Y values and one each U and V in a DWORD. Just as in the YUV 4:2:0 format, each U and V value describes the two pixels.

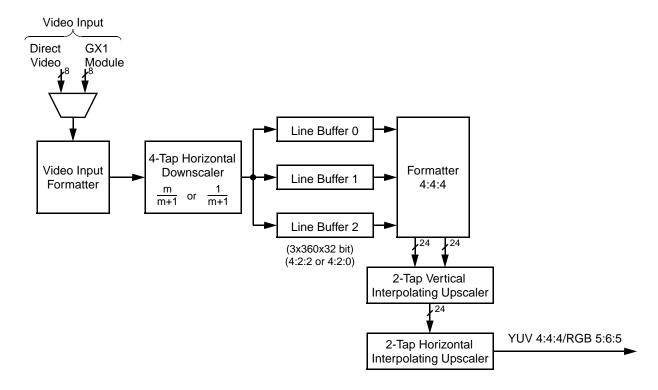


Figure 7-7. Video Block Diagram

Revision 5.1 Video Processor Module

7.2.2.2 Horizontal Downscaler with 4-Tap Filtering

The Video Processor implements up to 8:1 horizontal downscaling with 4-tap filtering for horizontal interpolation. Filtering is performed on video data input to the Video Processor. This data is fed to the filter and then to the downscaler. There is a bypass path for both filtering and downscaling logic. If this bypass is enabled, video data is written directly into the line buffers. (See Figure 7-8.)

Filtering

There are four 4-bit coefficients which can have programmed values of 0 to 15. The filter coefficients can be programmed via the Video Downscaler Coefficient register (F4BAR0+Memory Offset 40h) to increase picture quality.

Horizontal Downscaler

The Video Processor supports horizontal downscaling. The downscaler can be implemented in the Video Processor to shrink the video window by a factor of up to 8:1, in 1-pixel increments. The downscaler factor (m) is programmed in the Video Downscaler Control register (F4BAR0+Memory Offset 3Ch[4:1]). If bit 0 of this register is set to 0, the downscaler logic is bypassed.

The horizontal downscaler supports downscaling of video data input format YUV 4:2:2 only.

The downscaler supports up to 29 downscaler factors. There are two types of factors:

- Type A is (1/m+1). One pixel is retained, and m pixels are dropped. This enables downscaling factors of 1/16, 1/15, 1/14, 1/13, 1/12, 1/11, 1/10, 1/9,1/8, 1/7, 1/6, 1/5, 1/4, 1/3, and 1/2.
- Type B is (m/m+1). m pixels are retained, and one pixel is dropped. This enables downscaling factors of 2/3, 3/4, 4/5, 5/6, 6/7, 7/8, 8/9, 9/10, 10/11, 11/12, 12/13, 13/14, 14/15, and 15/16.

Bit 6 of the Video Downscaler Control register (F4BAR0+Memory Offset 3Ch) selects the type of downscaling factor to be used.

Note: There is no vertical downscaling in the Video Processor.

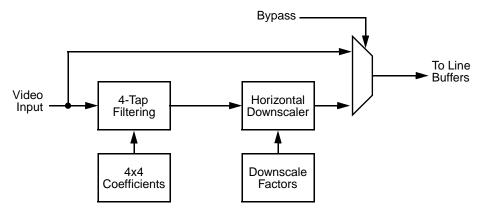


Figure 7-8. Horizontal Downscaler Block Diagram

7.2.2.3 Line Buffers

After the data has been optionally horizontally downscaled the video data is stored in a 3-line buffer. Each line is 360 DWORDs, which means a line width of up to 720 pixels can be stored. This buffer supports two functions. First, the clock domain of the video data changes from the GX1 module's video clock to the GX1 module's graphics clock. This clock domain change is required because the video data and graphics data can only be mixed/blended in the same clock domain. The second function the line buffer performs is to provide the necessary look ahead and look behind data in the vertical direction for the vertical upscaler. There is no direct program control of the line buffer.

7.2.2.4 Formatter

Video data in YUV 4:2:2 or YUV 4:2:0 format is converted to YUV 4:4:4 format. RGB data is not translated. There is no direct program control of the Formatter.

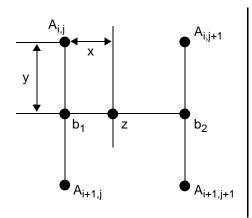
7.2.2.5 2-Tap Vertical and Horizontal Upscalers

Revision 5.1

After the video data has been buffered, the upscaling algorithm can be applied. The Video Processor employs a Digital Differential Analyzer-style (DDA) algorithm for both horizontal and vertical upscaling. The scaling parameters are programmed via the Video Upscale register (F4BAR0+Memory Offset 10h). The scalers support up to 8x factors for both horizontal and vertical scaling. The scaled video pixel stream is then passed through bi-linear interpolating filters (2-tap, 8-phase) to smooth the output video, significantly enhancing the quality of the displayed image.

The X and Y Upscaler uses the DDA and linear interpolating filter to calculate (via interpolation) the values of the pixels to be generated. The interpolation formula uses $\mathsf{A}_{i,j}$, $\mathsf{A}_{i+1,j}$, and $\mathsf{A}_{i+1,j+1}$ values to calculate the value of intermediate points. The actual location of calculated points is determined by the DDA algorithm.

The location of each intermediate point is one of eight phases between the original pixels (see Figure 7-9).



Notes

x and y are 0 - 7

$$b_1 = (A_{i,j}) \frac{8-y}{8} + (A_{i+1,j}) \frac{y}{8}$$

$$b_2 = (A_{i,j+1}) \frac{8-y}{8} + (A_{i+1,j+1}) \frac{y}{8}$$

$$z = (b_1) \frac{8-x}{8} + (b_2) \frac{x}{8}$$

Figure 7-9. Linear Interpolation Calculation

7.2.3 Mixer/Blender Block

The Mixer/Blender block of the Video Processor module performs all the necessary functions to properly mix/blend the video data and the graphics data. These functions include Color Space Conversion (CSC), optional Gamma correction, color/chroma key, and the mixing/blending logic. See Figure 7-10 for block diagram of the Mixer/Blender Block.

Video/Graphics mixing/blending must be performed in the RGB format. The YUV to RGB CSC (Section 7.2.3.1 on page 339) must be used on the video data if it is in YUV format. There is not a post mix/blend YUV to RGB CSC to support the TFT output. If Gamma Correction (see Section 7.2.3.2) on the video data is desired, it must be done in the color space of the input video data, which can be either YUV or RGB. If Gamma Correction on the graphics data is

desired, it must be done in the color space of the input graphics data, which is RGB.

The video data can be in progressive or interlaced format, while the graphics data is always in the progressive format. The Mixer/Blender can mix/blend either format of video data with graphics data. F4BAR0+Memory Offset 4Ch[9] programs the mix/blend format. Considering the color space and the data format, the Mixer/Blender supports five types of mixing/blending. Some of the mixing/blending types have additional programming considerations to enable them to work optimally. The valid mixing/blending configurations are listed in see Table 7-1 on page 339 along with any additional programming requirements.

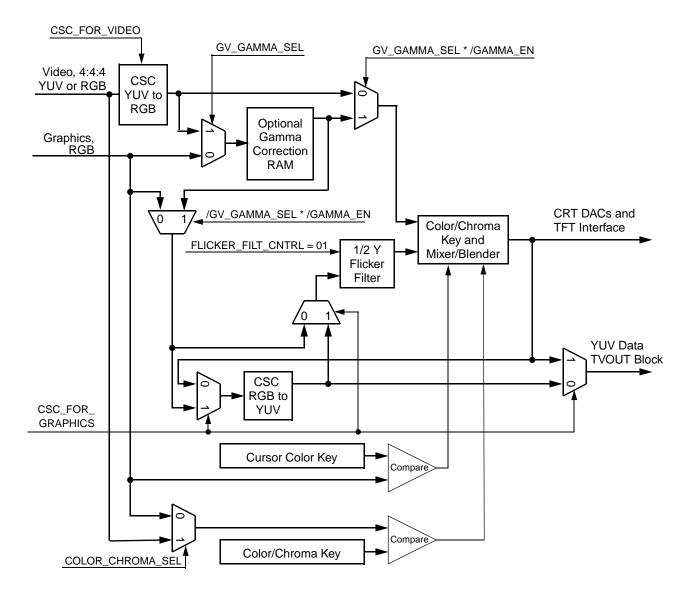


Figure 7-10. Mixer/Blender Block Diagram

Video Processor Module

М	Mixing/Blending ¹ Flicker Filter ² (Bit)						
13	11	10	9	30	29	Mode	Comment
0	0	1	0	0	0	Input: YUV Progressive Video Mixing: RGB	Produces highest quality RGB output (see Section 7.2.1.2 "Capture Video Mode", Weave subsection on page 333).
1	0	0	0	0	0	Input: RGB Progressive Video Mixing: RGB	Produces highest quality RGB output (see Section 7.2.1.2 "Capture Video Mode", Weave subsection on page 333).
0	1	0	1	0	1	Input: YUV Interlaced Video Mixing: YUV	Not supported.
0	1	0	0	0	0	Input: YUV Progressive Video Mixing: YUV	Not supported.
0	0	1	0	0	0	Input: YUV Interlaced Video upscaled by 2 Mixing: RGB	Typically Direct Video mode. Must be vertically upscaled by a factor of 2 (see Section 7.2.2.5 "2-Tap Vertical and Horizontal Upscalers" on page 337).

Table 7-1. Valid Mixing/Blending Configurations

- F4BAR0+Memory Offset 4Ch[13, 11:9].
- F4BAR0+Memory Offset 814h[30:29].

7.2.3.1 YUV to RGB CSC in Video Data Path

This CSC must be enabled if the video data is in the YUV color space. The CSC_FOR_VIDEO bit, F4BAR0+Memory Offset 4Ch[10], controls this CSC.

YUV video data is passed through this CSC to obtain 24-bit RGB data using the following CCIR-601-1 recommended formula:

- R = 1.1640625(Y 16) + 1.59375(V 128)
- G = 1.1640625(Y 16) 0.8125(V 128) -0.390625(U - 128)
- B = 1.1640625(Y 16) + 2.015625(U 128)

The CSC clamps inputs to prevent them from exceeding acceptable limits.

7.2.3.2 Gamma Correction

Either the video or graphics data can be routed through an integrated palette RAM for Gamma correction. There are three 256-byte RAMs, one for each color component value. Gamma correction supported in the YUV or RGB color space for the video data and RGB color space for the graphics data. Gamma correction is accomplished by treating each color component as an address into each RAM. The output of the RAM is the new color. A simple RGB Gamma correction example is to increase each color component by one. The address 00h in the RAMs would contain the data 01h. The address 01h would contain the data 02h and so on. This would have the effect of increasing each original Red, Green, and Blue value by one.

 G_V_GAMMA, F4BAR0+Memory Offset 04h[21] selects which data path (video or graphics) to send to the Gamma correction block. GAMMA_EN, F4BAR0+Memory Offset 28h[0] enables the Gamma correction function. To load the Gamma correction palette RAM, use F4BAR0+Memory Offset 1Ch and 20h.

7.2.3.3 Color/Chroma Key

A color/chroma key mechanism is used to support the Mixer/Blender logic. There are two keys: key1 is for the cursor and key2 is for graphics or video data. Key1, the cursor key, is always a color key. The cursor color key registers are located at, F4BAR0+Memory Offset 50h-5CF. How the cursor key mechanism works with the Mixer/Blender is explained in Section 7.2.3.4. COLOR_CHROMA_KEY (F4BAR0+Memory Offset 04h[20]) determines whether key2 is a color key or a chroma key. The Video Color Key Register (F4BAR0+Memory Offset 14h) stores the key. Color keying is used when video is overlaid on the graphics (GFX_INS_VIDEO, F4BAR0+Memory Offset 4Ch[8] = 0). Chroma keying is used when graphics is overlaid on the video (GFX INS VIDEO = 1). How the color/chroma key mechanism works with the Mixer/Blender is explained in Section 7.2.3.4.

7.2.3.4 Color/Chroma Key and Mixer/Blender

The Mixer/Blender takes each pixel of the graphics and video data streams and mixes or blends them together. Mixing is simply choosing the graphics pixel or the video pixel. Blending takes a percentage of a graphics pixel (Alpha_value * Graphics_pixel_value) and percentage of the video pixel (1 - Alpha_Value * Video_pixel_value) and adds them together. The percentages of each add up to 100%. The actual formula is:

 Blended Pixel = (Alpha_value * Graphics_pixel_value) / 256 + ((256 - Alpha value) * Video pixel value) / 256

Where: Alpha_value = 0 to 255

Mixing and blending are supported simultaneously for every rendered frame, however, each pixel can only be mixed or blended. The mix or blend question is decided by the pixel position, whether video is overlaid on the graphics or visa versa (GFX_INS_VIDEO, F4BAR0+Memory Offset 4Ch[8]), and several programmed "windows". Figure 7-11 illustrates and example frame.

Graphics Window

The graphics window is defined in the GX1 module's display controller and is always the full screen resolution.

Video Window

The video window tells the Mixer/Blender where the video window is and its size. If Direct Video mode is enabled (see Section 7.2.1.1 "Direct Video Mode" on page 331), the video window must be defined as the resolution of the video port data resolution (720x480 for NTSC, 720x576 for

PAL). Vertical scaling is not allowed. Horizontal scaling is allowed. If the video source is from the GX1 module's video frame buffer (which includes Capture Video mode, see Section 7.2.1.2 "Capture Video Mode" on page 332) then the video data can be scaled both horizontally and vertically. The video data size, scaled or unscaled, must equal the video window size. The Video X Position (horizontal) and Video Y Position (vertical) registers (F4BAR0+Memory Offset 08h and 0Ch) define the video window.

Cursor Window

The cursor window can be managed two ways: with the GX1 module's hardware cursor or a software cursor. When using the hardware cursor, the displayed colors of the hardware cursor must be the cursor color keys (see Section 5.5.3 "Hardware Cursor" in the *AMD GeodeTM GX1 Processor Data Book*). When the software cursor is used, the cursor size and position are not defined using registers. The cursor size, position, and image are determined through the use of the cursor color key colors in the graphics frame buffer. When the cursor is described in this manner, the cursor can be of any size and shape.

Alpha Windows

Up to three alpha windows can be defined. They are used only for blending. They can be of any size up to the graphics window size and they may overlap. To support overlapping of the alpha windows they can be prioritized as to which one is on top (F4BAR0+Memory Offset 4Ch[20:16]). The alpha windows are programmed at F4BAR0+Memory Offset 60h-88h.

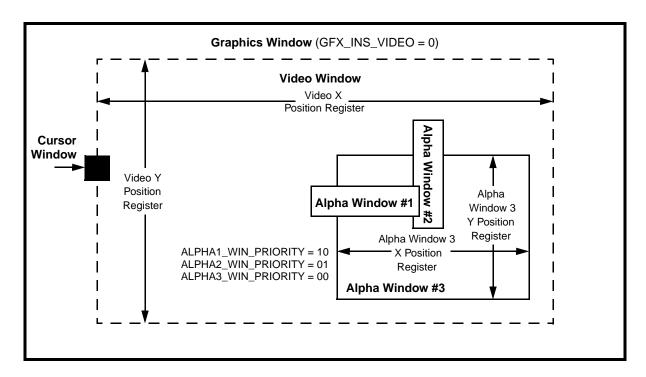


Figure 7-11. Graphics/Video Frame with Alpha Windows

Video Processor Module Revision 5.1

Mixing/Blending Operation

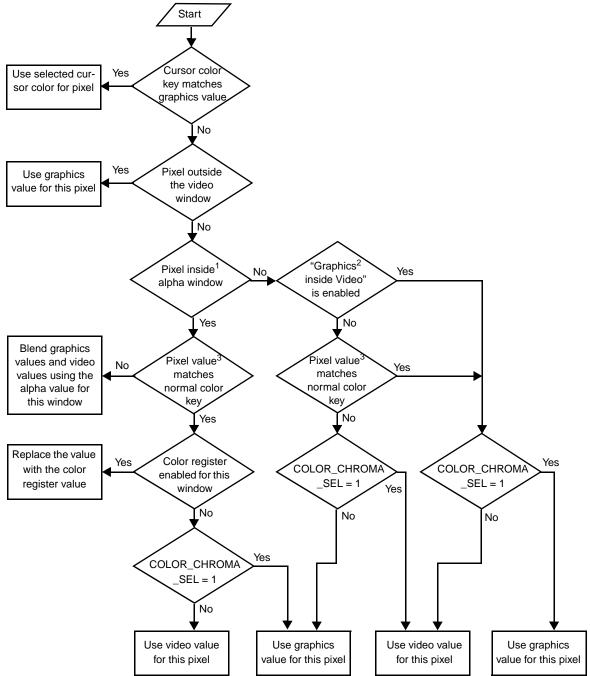
Table 7-2 on page 341 shows the truth table used to create the flow diagram, Figure 7-12 on page 342, that the Mixer/Blender logic uses to determine each pixels disposition.

Table 7-2. Truth Table for Alpha Blending

COLOR_ CHROMA_SEL ¹	Windows	Configuration ²	Graphics Data Match Cursor Color Key	Graphics Data Match Normal Color Key	Video Data Match Normal Color Key	Mixer Output
х	х	x	Yes	х	х	Cursor Color
х	Not in Video Window	х	No	х	х	Graphics Data
Graphics Color	Not in an Alpha	GFX_INS_VIDEO = 0	No	Yes	х	Video Data
Key	Window		No	No	х	Graphics Data
(COLOR_		GFX_INS_VIDEO = 1	No	х	х	Video Data
CHROMA_SEL = 0)	Inside Alpha Window x	ALPHAx_COLOR_REG_EN = 1	No	Yes	х	Color from Color Register
		ALPHAx_COLOR_REG_EN = 0	No	Yes	х	Video Data
		х	No	No	х	Alpha-blended Data
Video Chroma	Not in an Alpha	GFX_INS_VIDEO = 0	No	х	Yes	Graphics Data
Key	Window		No	х	No	Video Data
(COLOR_		GFX_INS_VIDEO = 1	No	х	х	Graphics Data
CHROMA_SEL = 1)	Inside Alpha Window x	ALPHAx_COLOR_REG_EN = 1	No	х	Yes	Color from Color Register
		ALPHAx_COLOR_REG_EN = 0	No	Х	Yes	Graphics Data
		х	No	х	No	Alpha-blended Data

^{1.} COLOR_CHROMA_SEL: F4BAR0+Memory Offset 04h[20].

GFX_INS_VIDEO: F4BAR0+Memory Offset 4Ch[8].
 ALPHAx_COLOR_REG_EN: F4BAR0+Memory Offsets 68h[24], 78h[24], and 88h[24].



Notes:

- 1) Alpha window should not be placed outside of the video window.
- 2) "Graphics inside Video" is enabled via bit GFX_INS_VIDEO in the Video De-interlacing and Alpha Control register (F4BAR0+Memory Offset 4Ch[8]).
- 3) The "Pixel Value" refers to either the Video value or the Graphics value, depending on the setting of bit COLOR_CHROMA_SEL in the Display Configuration register (F4BAR0+Memory Offset 04h[20]).

Figure 7-12. Color Key and Alpha Blending Logic

Video Processor Module Revision 5.1 AMD

7.2.4 TFT Interface

The TFT interface can be programmed to one of two sets of balls: IDE balls or Parallel Port balls. PMR[23] of the General Configuration registers program where the TFT interface exists (see Table 4-2 on page 88).

Note: If the TFT interface is on the IDE balls, the maximum FPCLK supported is 40 MHz. If the TFT interface is on the Parallel Port balls the maximum FPCLK supported is 80 MHz.

Support for a TFT panel requires power sequencing and an 18-bit (6-bit RGB), digital output. The relevant digital output signals are available from the SC3200.

TFT output signals are:

- TFTD[5:0] for blue signals
- TFTD[11:6] for green signals
- TFTD[17:12] for red signals
- HSYNC and VSYNC sync signals

- TFTDCK data clock signal.
- TFTDE data enable signal.
- FP_VDD_ON power control signal

Power Sequence

Power sequence is used to control assertion of FP_VDD_ON and TFTD signals.

All bits related to power sequence configuration are located in the Display Configuration register (F4BAR0+Memory Offset 04h).

After enabling TFT_EN (bit 0), and FP_PWR_EN (bit 6), the state machine waits until the next VSYNC to switch on the FP_VDD_ON signal. The state machine then asserts the TFTD[17:0] signals after the delay programmed via PWR_SEQ_DLY (bits [19:17]) When FP_PWR_EN (bit 6) is set to 0, the reverse sequence happens for powering down the TFT.

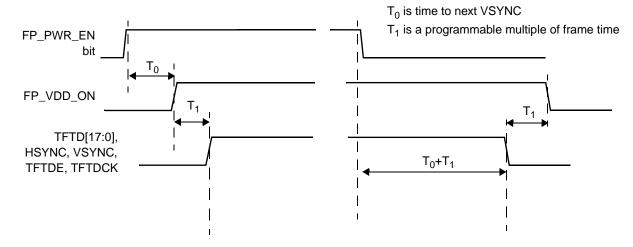


Figure 7-13. TFT Power Sequence

Revision 5.1 Video Processor Module

7.2.5 Integrated PLL

The integrated PLL can generate frequencies up to 135 MHz from a single 27 MHz source. The clock frequency is programmable using two registers. Figure 7-14 shows the block diagram of the Video Processor integrated PLL.

 F_{REF} is 27 MHz, generated by an external crystal and an integrated oscillator. F_{OLIT} is calculated from:

$$F_{OUT} = (m + 1) / (n + 1) x F_{REF}$$

The integrated PLL can generate any frequency by writing into the "m" and "n" bit fields (FBAR0+Memory Offset 2Ch, m = bits [14:8] and n = bits [3:0]). Additionally, 16 preprogrammed VGA frequencies can be selected via the PLL Clock Select register (F4BAR0+Memory Offset 2Ch[19:16]), if the crystal oscillator has a frequency of 27 MHz. This PLL can be powered down via the Miscellaneous register (F4BAR0+Memory Offset 28h[12]).

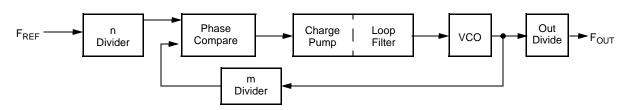


Figure 7-14. PLL Block Diagram



7.3 Register Descriptions

The register space for accessing and configuring the Video Processor is located in the Core Logic Chipset Register Space (F0-F5). The Chipset Register Space is accessed via the PCI interface using the PCI Type One Configuration Mechanism (see Section 6.3.1 "PCI Configuration Space and Access Methods" on page 191).

7.3.1 Register Summary

The tables in this subsection summarize the registers of the Video Processor. Included in the tables are the register's reset values and page references where the bit formats are found.

Table 7-3. F4: PCI Header Registers for Video Processor Support Summary

F4 Index	Width (Bits)	Туре	Name	Reset Value	Reference (Table 7-6)
00h-01h	16	RO	Vendor Identification Register	100Bh	Page 348
02h-03h	16	RO	Device Identification Register	0504h	Page 348
04h-05h	16	R/W	PCI Command Register	0000h	Page 348
06h-07h	16	RO	PCI Status Register	0280h	Page 348
08h	8	RO	Device Revision ID Register	01h	Page 348
09h-0Bh	24	RO	PCI Class Code Register	030000h	Page 348
0Ch	8	RO	PCI Cache Line Size Register	00h	Page 348
0Dh	8	RO	PCI Latency Timer Register	00h	Page 348
0Eh	8	RO	PCI Header Type Register	00h	Page 348
0Fh	8	RO	PCI BIST Register	00h	Page 348
10h-13h	32	R/W	Base Address Register 0 (F4BAR0). Sets the base address for the memory-mapped Video Configuration Registers within the Video Processor. Refer to Table 7-7 on page 350 for programming information regarding the register offsets accessed through this register.	00000000h	Page 348
14h-17h	32	R/W	Base Address Register 1 (F4BAR1). Reserved.	00000000h	Page 348
18h-1Bh			00000000h	Page 348	
1Ch-2Bh			Reserved	00h	Page 348
2Ch-2Dh	16	RO	Subsystem Vendor ID	100Bh	Page 348
2Eh-2Fh	16	RO	Subsystem ID	0504h	Page 348
30h-3Bh			Reserved	00h	Page 348
3Ch	8	R/W	Interrupt Line Register	00h	Page 348
3Dh	8	R/W	Interrupt Pin Register	03h	Page 349
3Eh-FFh			Reserved	00h	Page 349

Table 7-4. F4BAR0: Video Processor Configuration Registers Summary

F4BAR0+ Memory Offset	Width (Bits)	Туре	Name	Reset Value	Reference (Table 7-7)
00h-03h	32	R/W	Video Configuration Register	00000000h	Page 350
04h-07h	32	R/W	Display Configuration Register	x0000000h	Page 351
08h-0Bh	32	R/W	Video X Position Register	00000000h	Page 352
0Ch-0Fh	32	R/W	Video Y Position Register	00000000h	Page 352
10h-13h	32	R/W	Video Upscaler Register	00000000h	Page 352
14h-17h	32	R/W	Video Color Key Register	00000000h	Page 353
18h-1Bh	32	R/W	Video Color Mask Register	00000000h	Page 353
1Ch-1Fh	32	R/W	Palette Address Register	xxxxxxxxh	Page 353
20h-23h	32	R/W	Palette Data Register	xxxxxxxxh	Page 353
24h-27h	32	RO	Reserved		Page 353



Table 7-4. F4BAR0: Video Processor Configuration Registers Summary (Continued)

F4BAR0+ Memory Offset	Width (Bits)	Туре	Name	Reset Value	Reference (Table 7-7)
28h-2Bh	32	R/W	Miscellaneous Register	00001400h	Page 354
2Ch-2Fh	32	R/W	PLL2 Clock Select Register	00000000h	Page 354
30h-33h	32		Reserved	00000000h	Page 354
34h-37h	32	RO	Reserved	00000000h	Page 354
38h-3Bh	32	RO	Reserved	00000000h	Page 354
3Ch-3Fh	32	R/W	Video Downscaler Control Register	00000000h	Page 355
40h-43h	32	R/W	Video Downscaler Coefficient Register	00000000h	Page 355
44h-47h	32	R/W	CRC Signature Register	xxxxx100h	Page 355
48h-4Bh	32	RO	Device and Revision Identification	0000015xh	Page 355
4Ch-4Fh	32	R/W	Video De-Interlacing and Alpha Control Register	00060000h	Page 356
50h-53h	32	R/W	Cursor Color Key Register	00000000h	Page 357
54h-57h	32	R/W	Cursor Color Mask Register	00000000h	Page 357
58h-5Bh	32	R/W	Cursor Color Register 1	00000000h	Page 357
5Ch-5Fh	32	R/W	Cursor Color Register 2	00000000h	Page 357
60h-63h	32	R/W	Alpha Window 1 X Position Register	00000000h	Page 358
64h-67h	32	R/W	Alpha Window 1 Y Position Register	00000000h	Page 358
68h-6Bh	32	R/W	Alpha Window 1 Color Register	00000000h	Page 358
6Ch-6Fh	32	R/W	Alpha Window 1 Control Register	00000000h	Page 358
70h-73h	32	R/W	Alpha Window 2 X Position Register	00000000h	Page 359
74h-77h	32	R/W	Alpha Window 2 Y Position Register	00000000h	Page 359
78h-7Bh	32	R/W	Alpha Window 2 Color Register	00000000h	Page 359
7Ch-7Fh	32	R/W	Alpha Window 2 Control Register	00000000h	Page 359
80h-83h	32	R/W	Alpha Window 3 X Position Register	00000000h	Page 360
84h-87h	32	R/W	Alpha Window 3 Y Position Register	00000000h	Page 360
88h-8Bh	32	R/W	Alpha Window 3 Color Register	00000000h	Page 360
8Ch-8Fh	32	R/W	Alpha Window 3 Control Register	00000000h	Page 360
90h-93h	32	R/W	Video Request Register	001B0017h	Page 361
94h-97h	32	RO	Alpha Watch Register	00000000h	Page 361
98h-3FFh			Reserved		Page 361
400h-403h	32	R/W	Video Processor Display Mode Register	00000000h	Page 361
404h-407h	32		Reserved	00000000h	Page 361
408h-40Bh	32	R/W	Video Processor Test Mode Register	00000000h	Page 361
40Ch-41Fh			Reserved	00000000h	Page 361
420h-423h	32	R/W	GenLock Register	0000000h	Page 362
424h-427h	32	R/W	GenLock Delay Register	00000000h	Page 362
428h-43Bh			Reserved		Page 362
43Ch-43Fh	32	R/W	Continuous GenLock Time-out Register	1FFF1FFFh	Page 362



Table 7-5. F4BAR2: VIP Support Registers Summary

			<u> </u>		
F4BAR2+ Memory Offset	Width (Bits)	Туре	Name	Reset Value	Reference (Table 7-8)
00h-03h	32	R/W	Video Interface Port Configuration Register	00000000h	Page 363
04h-07h	32	R/W	Video Interface Control Register	00000000h	Page 363
08h-0Bh	32	R/W	Video Interface Status Register	xxxxxxxxh	Page 364
0Ch-0Fh			Reserved	00000000h	Page 365
10h-13h	32	RO	Video Current Line Register	xxxxxxxxh	Page 365
14h-17h	32	R/W	Video Line Target Register	00000000h	Page 365
18h-1Fh			Reserved	0000000h	Page 365
20h-23h	32	R/W	Video Data Odd Base Register	0000000h	Page 365
24h-27h	32	R/W	Video Data Even Base Register	00000000h	Page 365
28h-2Bh	32	R/W	Video Data Pitch Register	00000000h	Page 365
2Ch-3Fh			Reserved	0000000h	Page 365
40h-43h	32	R/W	VBI Data Odd Base Register	00000000h	Page 366
44h-47h	32	R/W	VBI Data Even Base Register	00000000h	Page 366
48h-4Bh	32	R/W	VBI Data Pitch Register	00000000h	Page 366
4Ch-1FFh			Reserved	00000000h	Page 366



7.3.2 Video Processor Registers - Function 4

The register space designated as Function 4 (F4) is used to configure the PCI portion of support hardware for accessing the Video Processor support registers, including VIP (separate BAR). The bit formats for the PCI Header registers are given in Table 7-6.

Located in the PCI Header Registers of F4 are three Base Address Registers (F4BARx) used for pointing to the register spaces designated for Video Processor support. F4BAR0 is for Video Processor Configuration, F4BAR1 is reserved, and F4BAR2 is for VIP configuration.

Table 7-6. F4: PCI Header Registers for Video Processor Support Registers

Bit	Description		
Index 00h-01h		Vendor Identification Register (RO)	Reset Value: 100Bh
Index 02	h-03h	Device Identification Register (RO)	Reset Value: 0504h
Index 04	h-05h	PCI Command Register (R/W)	Reset Value: 0000h
15:2	Reserved. (Read O	nly)	
1	0: Disable. 1: Enable.	ow the Core Logic module to respond to memory cycles from the P	
0	Reserved. (Read O	nly)	
Index 06	h-07h	PCI Status Register (RO)	Reset Value: 0280h
Index 08	h	Device Revision ID Register (RO)	Reset Value: 01h
Index 09	h-0Bh	PCI Class Code Register (RO)	Reset Value: 030000h
Index 0C	h	PCI Cache Line Size Register (RO)	Reset Value: 00h
Index 0D	h	PCI Latency Timer Register (RO)	Reset Value: 00h
Index 0E	h	PCI Header Type (RO)	Reset Value: 00h
Index 0F	h	PCI BIST Register (RO)	Reset Value: 00h
tion regis	ters. Bits [11:0] are read and reset values of the r	ry Address Space. This register allows PCI access to the memory d only (0000 0000 0000) indicating a 4 KB memory address range. egisters accessed through this base address register. ideo Memory Base Address.	
11:0	Address Range. (R	ead Only)	
Index 14 Reserve		Base Address Register 1 - F4BAR1 (R/W)	Reset Value: 00000000h
Index 18	h-1Bh	Base Address Register 2 - F4BAR2 (R/W)	Reset Value: 00000000h
		er allows access to memory mapped VIP (Video Interface Port) relag a 4 KB I/O address range. Refer to Table 7-8 for the VIP register	
31:12	VIP Base Address.		
11:0	Address Range. (R	ead Only)	·
Index 1C	h-2Bh	Reserved	Reset Value: 00h
Index 2C	h-2Dh	Subsystem Vendor ID (RO)	Reset Value: 100Bh
Index 2E	h-2Fh	Subsystem ID (RO)	Reset Value: 0504h
Index 30	h-3Bh	Reserved	Reset Value: 00h
Index 3C	:h	Interrupt Line Register (R/W)	Reset Value: 00h



Table 7-6. F4: PCI Header Registers for Video Processor Support Registers (Continued)

Bit	Description	
Index 3Dh	Interrupt Pin Register (R/W)	Reset Value: 03h
This registed 1, 2 or 4, re	r selects which interrupt pin the device uses. VIP uses INTC# after reset. INTA#, INTB# or INTD# car spectively.	n be selected by writing
Index 3Eh	FFh Reserved	Reset Value: 00h



7.3.2.1 Video Processor Support Registers - F4BAR0

F4 Index 10h, Base Address Register 0 (F4BAR0) sets the base address that allows PCI access to the Video Processor support registers, not including VIP. A separate base address register (F4BAR2) is used to access VIP support registers (see Section 7.3.2.2 on page 363).

Note: Reserved bits that are not defined as "must be set to 0 or 1" should be written with a value that is read from them.

Table 7-7. F4BAR0+Memory Offset: Video Processor Configuration Registers

Bit	Description						
Offset 00	h-03h Vide	eo Configuration Register (R/W)	Reset Value: 00000000h				
Configura	tion register for options of the motion vide	eo acceleration hardware.					
31:29	Reserved. Must be set to 0.						
28	EN_42X (Enable 4:2:x Format). Allow	s format selection.					
	0: 4:2:2 format.						
	1: 4:2:0 format.						
	Note: When input video stream is RGE	B (i.e., F4BAR0+Memory Offset 4Ch[13] = 1), t	this bit must be set to 0.				
27	BIT_8_LINE_SIZE. When enabled, this DWORDs.	s bit increases line size from VID_LIN_SIZ (bit	s [15:8]) DWORDs by adding 256				
	0: Disable.						
	1: Enable.						
26:25	Reserved. Must be set to 0.						
24:16	beginning of each display line. It is use	INIT_RD_ADDR (Initial Buffer Read Address). This field preloads the starting read address for the line buffers at the beginning of each display line. It is used for hardware clipping of the video window at the left edge of the active display. It represents the DWORD address of the source pixel which is to be displayed first.					
	For an unclipped window, this value sh	ould be 0. For 4:2:0 format, set bits [17:16] to	00.				
15:8	VID_LIN_SIZ (Video Line Size). Represents the number of DWORDs that make up the horizontal size of the source video data.						
7	YFILT_EN (Y Filter Enable). Enables/disables the vertical filter.						
	0: Disable. Upscaling done by repeating pixels.						
	1: Enable. Upscaling done by interpolating pixels.						
	Note: This bit is used with Y upscaling	logic. Reset to 0 when not required.					
6	XFILT_EN (X Filter Enable). Enables/	XFILT_EN (X Filter Enable). Enables/disables the horizontal filter.					
	0: Disable. Upscaling done by repeati	0: Disable. Upscaling done by repeating pixels.					
	1: Enable. Upscaling done by interpolating pixels.						
	Note: This bit is used with X upscaling logic. Reset to 0 when not required.						
5:4	Reserved.						
3:2	VID_FMT (Video Format). Byte ordering of video data on the Video Input bus (VPD[7:0]). The interpretation of these bits depends on the settings of bit 13 (GV_SEL) in the Video De-Interlacing and Alpha Control register (F4BAR0+Memory Offse 4Ch) and bit 28 (EN_42X) of this register.						
	If GV_SEL = 0 and EN_42X = 0:						
	00: Cb Y0 Cr Y1 01: Y1 Cr Y0 Cb	10: Y0 Cb Y1 Cr 11: Y0 Cr Y1 Cb					
	If GV_SEL = 0 and EN_42X = 1:	11. 10 Ci 11 Ob					
	00: Y0 Y1 Y2 Y3	10: Y1 Y0 Y3 Y2					
	01: Y3 Y2 Y1 Y0	11: Y1 Y2 Y3 Y0					
	If GV_SEL = 1 and EN_42X = 0:	40: DAM DAL DOM DOL					
	00: P1L P1M P2L P2M 01: P2M P2L P1M P1L	10: P1M P1L P2M P2L 11: P1M P2L P2M P1L					
	If GV_SEL = 1 and EN_42X = 1: Rese						
		:2 contain two pixels in each 32-bit DWORD.	YUV 4:2:0 contains a stream of Y da				
	for each line, followed by U ar						
1	Reserved.						



Bit	Description	
0	VID_EN (Video Enable). Enables video acceleration hardware.	
	0: Disable (reset) video module.	
	1: Enable.	
Offset 04h	-07h Display Configuration Register (R/W) Reset Value: x0000000h	
General co	infiguration register for display control. This register is also used to determine how graphics and video data are to be com-	
bined in the	e display on the output device.	
31	Reserved. Write as read.	
30:28	Reserved.	
27	FP_ON_STATUS (Flat Panel On Status). (Read Only) Shows whether power to the attached flat panel is on or off. This bit transitions at the end of the power-up or power-down sequence.	
	0: Power to the flat panel is off.	
	1: Power to the flat panel is on.	
26	Reserved. Set to 0.	
25	Reserved. Must be set to 0.	
24:22	Reserved. Set to 0.	
21	GV_GAMMA_SEL (Graphics or Video Gamma Source Data). Selects whether the graphics or video data goes to the Gamma Correction RAM. GAMMA_EN (F4BAR0+Memory Offset 28h[0]) must be enabled for the selected data source to pass through the Gamma Correction RAM.	
	0: Graphics data to Gamma Correction RAM.	
	1: Video data to Gamma Correction RAM.	
	Note: Gamma Correction is always in the RGB domain for graphics data. Gamma Correction can be in the YUV or RGB domain for video data.	
20	COLOR_CHROMA_SEL (Color or Chroma Key Select). Selects whether the graphics is used for color keying or the video data stream is used for chroma keying.	
	0: Graphics data is compared to the color key.	
	1: Video data is compared to the chroma key.	
19:17	PWR_SEQ_DLY (Power Sequence Delay). Selects the number of frame periods that transpire between successive transitions of the power sequence control lines.	
16:14	Reserved. Write as read.	
13:8	Reserved. Write as read.	
7	FP_DATA_EN (Flat Panel Output Enable). Controls the data, data-enable, clock and sync output signals.	
	0: Flat panel data outputs are forced to zero depending on the value of bit 3 (BL_EN). Bit 6 (FP_PWR_EN) is ignored.	
	1: Flat panel outputs are forced to zero until power-up, and later, data outputs are subject to the value of bit 3 (BL_EN).	
6	FP_PWR_EN (Flat Panel Power Enable). Changing this bit initiates a flat panel power-up or power-down.	
	0-to-1: Power-up flat panel.	
	1-to-0: Power-down flat panel.	
5:4	Reserved.	
3	BL_EN (Blank Enable). Controls blanking of TFT data.	
	0: TFT data is constantly blanked.	
	1: TFT data is blanked normally (i.e., during horizontal and vertical blank).	
2	VSYNC_EN (Vertical Sync Enable). Enables/disables display vertical sync (used for VESA DPMS support).	
	0: Disable.	
	1: Enable.	
1	HSYNC_EN (Horizontal Sync Enable). Enables/disables display horizontal sync (used for VESA DPMS support).	
	0: Disable.	
	1: Enable.	
0	TFT_EN (TFT Enable). Enables the TFT control logic and is also used to reset the TFT control logic.	
Ĭ	0: Reset TFT control logic.	
	1: Enable TFT control logic.	
	· · · · · · · · · · · · · · · · · · ·	

Bit	Description
Offset 08h	-0Bh Video X Position Register (R/W) Reset Value: 00000000h
	e window X position. This register is programmed relative to CRT horizontal sync input (not physical screen position).
Note: H	_TOTAL and H_SYNC_END are values programmed in the GX1 module's Display Controller Timing registers 6X_BASE+Memory Offset 8330h[26:19] and 8338h[10:3], respectively). The value of (H_TOTAL – H_SYNC_END) is somenes referred to as "horizontal back porch". For more information, see the AMD Geode™ GX1 Processor Data Book.
31:28	Reserved.
27:16	VID_X_END (Video X End Position). Represents the horizontal end position of the video window (not inclusive). This value is calculated according to the following formula:
	Value = Desired screen position + (H_TOTAL – H_SYNC_END) – 13.
15:12	Reserved.
11:0	VID_X_START (Video X Start Position). Represents the horizontal start position of the video window. This value is calculated according to the following formula:
	Value = Desired screen position + (H_TOTAL – H_SYNC_END) – 14.
Offset 0Ch	-0Fh Video Y Position Register (R/W) Reset Value: 00000000h
Provides th	e window Y position. This register is programmed relative to CRT vertical sync input (not physical screen position).
(0	_TOTAL and V_SYNC_END are values programmed in the GX1 module's Display Controller Timing registers GX_BASE+Memory Offset 8340h[26:16] and 8348h[26:16], respectively). The value of (V_TOTAL – V_SYNC_END) is somenes referred to as "vertical back porch". For more information, see the <i>AMD GeodeTM GX1 Processor Data Book</i> .
31:27	Reserved.
26:16	VID_Y_END (Video Y End Position). Represents the vertical end position of the video window (not inclusive). This value is calculated according to the following formula:
	Value = Desired screen position + (V_TOTAL - V_SYNC_END) + 2.
15:11	Reserved
10:0	VID_Y_START (Video Y Start Position). Represents the vertical start position of the video window. This value is calculated according to the following formula:
	Value = Desired screen position + (V_TOTAL - V_SYNC_END) + 1.
Offset 10h	-13h Video Upscale Register (R/W) Reset Value: 00000000h
Provides h	orizontal and vertical upscale factors of the window.
31:30	Reserved.
29:16	VID_Y_SCL (Video Y Scale Factor). Represents the vertical upscale factor of the video window according to the following formula:
	VID_Y_SCL = 8192 * (Ys - 1) / (Yd - 1)
	where:
	Ys = Video source vertical size in pixels
	Yd = Video destination vertical size in pixels
	Note: Upscale factor must be used. Yd is equal or bigger than Ys. If no scaling is intended, set to 2000h. The actual scale factor used is VID_Y_SCL/8192, but the formula above fits a given source number of lines into a destination window size.
	Note: When progressive mixing/blending is programmed (F4BAR0+Memory Offset 4Ch[9] = 0) and the video data is interlaced, this register should be programmed to 1000h to double the vertical lines,
15:14	Reserved.
13:0	VID_X_SCL (Video X Scale Factor). Represents horizontal upscale factor of the video window according to the following formula:
	VID_X_SCL = 8192 * (Xs - 1) / (Xd - 1)
	where:
	Xs = Video source horizontal size in pixels
	Xd = Video destination vertical size in pixels
	Note: Upscale factor must be used. Xd is equal or bigger than Xs. If no scaling is intended, set to 2000h. The actual scale factor used is VID_X_SCL/8192, but the formula above fits a given source number of pixels into a destination window size.



Bit	Description		
Offset 14h	1-17h Video Color Key Register (R/W) Reset Value: 00000000h		
	ne video color key. The color key can be used to allow irregular shaped overlays of graphics onto video, or video onto grapha scaled video window.		
31:24	Reserved.		
23:0	VID_CLR_KEY (Video Color Key). The video color key is a 24-bit RGB or YUV value.		
	If the COLOR_CHROMA_SEL bit (F4BAR0+Memory Offset 04h[20]) = 0: The video pixel is selected within the target window if the corresponding graphics pixel matches the color key. The color key in an RGB value.		
	If the COLOR_CHROMA_SEL bit (F4BAR0+Memory Offset 04h[20]) = 1: The video pixel is selected within the target window only if it (the video pixel) does not match the color key. The color key is usually an RGB value. However, if both the CSC_for VIDEO and GV_SEL bits (F4BAR0+Memory Offset 4Ch bits 10 and 13, respectively) are programmed to 0, the color key is a YUV value (i.e., video is not converted to RGB).		
	The graphics or video data being compared can be masked prior to the compare via the Video Color Mask register (described in F4BAR0+Memory Offset 18h).		
Offset 18h	n-1Bh Video Color Mask Register (R/W) Reset Value: 00000000h		
	ne video color mask. This value is used to mask bits of the graphics or video stream being compared to the video color key in F4BAR0+Memory Offset 14h). It can be used to allow a range of values to serve as the color key.		
31:24	Reserved.		
23:0	VID_CLR_MASK (Video Color Mask). This mask is a 24-bit value. Zeros in the mask cause the corresponding bits in the graphics or video stream to be ignored.		
Offset 1Cl	n-1Fh Palette (Gamma Correction RAM) Address Register (R/W) Reset Value: xxxxxxxxh		
31:8	Reserved.		
7:0	PAL_ADDR (Palette Address). Specifies the address to be used for the next access to the Palette Data register (F4BAR0+Memory Offset 20h[31:8]). Each access to the data register automatically increments the Palette Address register. If non-sequential access is made to the palette, the address register must be loaded between each non-sequential data block.		
Offset 20h	1-23h Palette (Gamma Correction RAM) Data Register (R/W) Reset Value: xxxxxxxxxh		
accessing	ne video palette data. The data can be read or written to the Gamma Correction RAM (palette) via this register. Prior to this register, an appropriate address should be loaded to the Palette Address register (F4BAR0+Memory Offset 1Ch[7:0]). In accesses to the Palette Data register cause the internal address counter to be incremented for the next cycle.		
31:8	PAL_DATA (Palette Data). Contains the read or write data for a Gamma Correction RAM (palette).		
	Blue[7:0] = Bits [31:24] Green[7:0] = Bits [23:16] Red[7:0] = Bits [15:8]		
	Note: When a read or write to the Gamma Correction RAM occurs, the previous output value is held for one additional DOTCLK period. This effect should go unnoticed during normal operation.		
7:0	Reserved.		
Offset 24h	n-27h Reserved		

Table 7-7. F4BAR0+Memory Offset: Video Processor Configuration Registers (Continued)

Bit	Description				
Offset 28	h-2Bh	ľ	Miscellaneous Register (R/W)		Reset Value: 00001400h
Configurat	tion and control reg	ister for miscellaneou	s characteristics of the Video P	rocessor.	
31:13	Reserved.				
12	PLL2_PWR_EN	(PLL2 Power-Down	Enable).		
	0: Power-down.				
	1: Normal.				
11:10	Reserved. Set to	1.			
9:1	Reserved.				
0	_ ,	mma Correction RA ma Correction RAM.	.M Enable). Allows video or gra	phics (selected by F4BA	R0+Memory Offset 04h[21])
	0: Enable.				
	1: Disable.				
Offset 2C	h-2Fh	PL	L2 Clock Select Register (R/V	/)	Reset Value: 00000000h
Determine	es the characteristic	s of the integrated PL	L2.		
31:23	Reserved. Must	be set to 0.			
22:21	CLK_DIV_SEL (Clock Divider Select).		
	00: No division				
	01: Divide by 2				
	10: Divide by 4				
	11: Divide by 8				
	Divides the clock generated by the PLL2, using the programmed m (bits [14:8]) and n (bits [3:0]) values.				
20	SEL_REG_CAL. Selects specific or previously-calculated values.				
	0: Values previously calculated from the CLK_SEL bits (bits [19:16]).				
	1: Values according to the m (bits [14:8]), n (bits [3:0]), and CLK_DIV_SEL (bits [22:21]) fields.				
19:16			quency (in MHz) of the display of		
	0000: 25.175 0001: 31.5	0100: 50 0101: 49.5	1000: 65 1100: 10 1001: 75 1101: 13		
	0010: 36	0110: 56.25	1010: 78.5		
	0011: 40	0111: 44.9	1011: 94.5 1111: 24	1.923052	
15	LFTC (Loop Filt	er Time Constant). ⊺	his bit should be set when m (b	oits [14:8]) value is higher	than 30.
14:8	frequency using	,	when SEL_REG_CAL (bit 20) =	= 1. The following formula	a is used for calculating the
	Km = m + 1 Kn = n + 1 OSCCLK = 27 M				
7:4	Reserved				
3:0		•	hen SEL_REG_CAL (bit 20) =	1. The following formula i	s used for calculating the fre-
	Fvco = OSC Km = m + 1 Kn = n + 1 OSCCL = 27 M				
Offset 30	h-33h		Reserved		Reset Value: 00000000h
Offset 34	h-37h		Reserved		Reset Value: 00000000h
	h-3Bh		Reserved		Reset Value: 00000000h



Bit	Description	
Offset 3C	n-3Fh Video Downscaler Control Register (R/W)	Reset Value: 00000000h
Controls th	e characteristics of the integrated video downscaler.	
31:7	Reserved	
6	DTS (Downscale Type Select).	
	0: Type A (Downscale formula is 1/m+1, m pixels are dropped, 1 pixel is kept).	
	1: Type B (Downscale formula is m/m+1, m pixels are kept, 1 pixel is dropped).	
5	Reserved.	
4:1	DFS (Downscale Factor Select). Determines the downscale factor to be programmed in derive the desired downscale factor depending on bit 6 (DTS).	nto these bits, where m is used to
0	DCF (Downscaler and Filtering). Enables/disables downscaler and filtering logic.	
	0: Disable.	
	1: Enable.	
	Note: No downscaling support for RGB 5:6:5 and YUV 4:2:0 video formats.	
Offset 40I	-43h Video Downscaler Coefficient Register (R/W)	Reset Value: 00000000h
Valid value	Iter coefficients. The filters can be programmed independently to increase video quality when some some solution of the filter coefficient are 0-15. The sum of coefficients must be 16. FLT_CO_4 is used with the latest. Only luminance values of pixels are filtered.	
31:28	Reserved	
27:24	FLT_CO_4 (Filter Coefficient 4). For the tap-4 filter.	
23:20	Reserved	
19:16	FLT_CO_3 (Filter Coefficient 3). For the tap-3 filter.	
15:12	Reserved	
11:8	FLT_CO_2 (Filter Coefficient 2). For the tap-2 filter.	
7:4	Reserved	
3:0	FLT_CO_1 (Filter Coefficient 1). For the tap-1 filter.	
Offset 44I	-47h CRC Signature Register (R/W)	Reset Value: xxxxx100h
Signature	values stored in this register can be read by the host. This register is used for test purpose	es.
31:8	SIG_VALUE (Signature Value). (Read Only) A 24-bit signature value is stored in this bi The signature is produced from the RGB data output of the mixer. This bit field is used for	t field and can be read at any time
		•
	See SIGN_EN (bit 0) description for more information.	•
7:3	See SIGN_EN (bit 0) description for more information. Reserved	•
7:3		•
	Reserved	or test purpose only.
	Reserved SIGN_FREE (Signature Free Run). 0: Disable. (Default) If this bit was previously set to 1, the signature process stops at the	e end of the current frame (i.e., at
	Reserved SIGN_FREE (Signature Free Run). 0: Disable. (Default) If this bit was previously set to 1, the signature process stops at the the next falling edge of VSYNC).	e end of the current frame (i.e., at
2	Reserved SIGN_FREE (Signature Free Run). 0: Disable. (Default) If this bit was previously set to 1, the signature process stops at the the next falling edge of VSYNC). 1: Enable. If SIGN_EN (bit 0) = 1, the signature register captures data continuously acres.	e end of the current frame (i.e., at
2	Reserved SIGN_FREE (Signature Free Run). 0: Disable. (Default) If this bit was previously set to 1, the signature process stops at the the next falling edge of VSYNC). 1: Enable. If SIGN_EN (bit 0) = 1, the signature register captures data continuously acre Reserved.	e end of the current frame (i.e., at
2	Reserved SIGN_FREE (Signature Free Run). 0: Disable. (Default) If this bit was previously set to 1, the signature process stops at the the next falling edge of VSYNC). 1: Enable. If SIGN_EN (bit 0) = 1, the signature register captures data continuously acre Reserved. SIGN_EN (Signature Enable).	e end of the current frame (i.e., at oss multiple frames.
2	Reserved SIGN_FREE (Signature Free Run). 0: Disable. (Default) If this bit was previously set to 1, the signature process stops at the the next falling edge of VSYNC). 1: Enable. If SIGN_EN (bit 0) = 1, the signature register captures data continuously acre Reserved. SIGN_EN (Signature Enable). 0: Disable. (Default) The SIG_VALUE (bits [31:8]) is reset to 000001h and held (no captor of the signature start of the frame to be use	e end of the current frame (i.e., at coss multiple frames. ture). d for CRC checking with each pixe
2	Reserved SIGN_FREE (Signature Free Run). 0: Disable. (Default) If this bit was previously set to 1, the signature process stops at the the next falling edge of VSYNC). 1: Enable. If SIGN_EN (bit 0) = 1, the signature register captures data continuously acre Reserved. SIGN_EN (Signature Enable). 0: Disable. (Default) The SIG_VALUE (bits [31:8]) is reset to 000001h and held (no capture captures). 1: Enable. The next falling edge of VSYNC is counted as the start of the frame to be use clock beginning with the next VSYNC.	e end of the current frame (i.e., at coss multiple frames. ture). d for CRC checking with each pixentinuously across multiple frames.
2	Reserved SIGN_FREE (Signature Free Run). 0: Disable. (Default) If this bit was previously set to 1, the signature process stops at the the next falling edge of VSYNC). 1: Enable. If SIGN_EN (bit 0) = 1, the signature register captures data continuously acre Reserved. SIGN_EN (Signature Enable). 0: Disable. (Default) The SIG_VALUE (bits [31:8]) is reset to 000001h and held (no capture Enable). 1: Enable. The next falling edge of VSYNC is counted as the start of the frame to be use clock beginning with the next VSYNC. If SIGN_FREE (bit 2) = 1, the signature register captures the pixel data signature cor	e end of the current frame (i.e., at oss multiple frames. ture). d for CRC checking with each pixentinuously across multiple frames. m the next falling VSYNC.
1 0	Reserved SIGN_FREE (Signature Free Run). 0: Disable. (Default) If this bit was previously set to 1, the signature process stops at the the next falling edge of VSYNC). 1: Enable. If SIGN_EN (bit 0) = 1, the signature register captures data continuously acre. Reserved. SIGN_EN (Signature Enable). 0: Disable. (Default) The SIG_VALUE (bits [31:8]) is reset to 000001h and held (no capter the continuously acre. 1: Enable. The next falling edge of VSYNC is counted as the start of the frame to be use clock beginning with the next VSYNC. If SIGN_FREE (bit 2) = 1, the signature register captures the pixel data signature continuously acre. After a signature capture, the SIG_VALUE can be read to determine the CRC check state initialize the SIG_VALUE as an essential preparation for the next round of CRC check.	e end of the current frame (i.e., at oss multiple frames. ture). d for CRC checking with each pixe on the next falling VSYNC.
2	Reserved SIGN_FREE (Signature Free Run). 0: Disable. (Default) If this bit was previously set to 1, the signature process stops at the the next falling edge of VSYNC). 1: Enable. If SIGN_EN (bit 0) = 1, the signature register captures data continuously acres Reserved. SIGN_EN (Signature Enable). 0: Disable. (Default) The SIG_VALUE (bits [31:8]) is reset to 000001h and held (no captable). 1: Enable. The next falling edge of VSYNC is counted as the start of the frame to be use clock beginning with the next VSYNC. If SIGN_FREE (bit 2) = 1, the signature register captures the pixel data signature control of SIGN_FREE (bit 2) = 0, a signature is captured for one frame at a time, starting from After a signature capture, the SIG_VALUE can be read to determine the CRC check state initialize the SIG_VALUE as an essential preparation for the next round of CRC check.	e end of the current frame (i.e., at coss multiple frames. ture). d for CRC checking with each pixe entinuously across multiple frames. m the next falling VSYNC. us. SIGN_EN can then be reset to
1 0	Reserved SIGN_FREE (Signature Free Run). 0: Disable. (Default) If this bit was previously set to 1, the signature process stops at the the next falling edge of VSYNC). 1: Enable. If SIGN_EN (bit 0) = 1, the signature register captures data continuously acres Reserved. SIGN_EN (Signature Enable). 0: Disable. (Default) The SIG_VALUE (bits [31:8]) is reset to 000001h and held (no captall the continuously acres and the start of the frame to be used clock beginning with the next VSYNC. If SIGN_FREE (bit 2) = 1, the signature register captures the pixel data signature continuously acres and the start of the frame to be used clock beginning with the next VSYNC. If SIGN_FREE (bit 2) = 0, a signature register captures the pixel data signature continuously acres are signature captured to the frame to be used clock beginning with the next VSYNC. If SIGN_FREE (bit 2) = 0, a signature is captured for one frame at a time, starting from the After a signature capture, the SIG_VALUE can be read to determine the CRC check start initialize the SIG_VALUE as an essential preparation for the next round of CRC check.	e end of the current frame (i.e., at oss multiple frames. ture). d for CRC checking with each pixe on the next falling VSYNC. us. SIGN_EN can then be reset to Reset Value: 0000xxxxh

Table 7-7. F4BAR0+Memory Offset: Video Processor Configuration Registers (Continued)

Bit	Description
Offset 4Ch	1-4Fh Video De-Interlacing and Alpha Control Register (R/W) Reset Value: 00060000h
31:22	Reserved.
21:20	ALPHA3_WIN_PRIORITY (Alpha Window 3 Priority). Determines the priority of Alpha Window 3. A higher number indicates a higher priority. Priority is used to determine display order for overlapping alpha windows. 00: Lowest priority (default).
	01: Medium priority.
	10: Highest priority.
	11: Illegal.
	Note: Priority of enabled alpha windows must be different.
19:18	ALPHA2_WIN_PRIORITY (Alpha Window 2 Priority). Determines the priority of Alpha Window 2. A higher number indicates a higher priority. Priority is used to determine display order for overlapping alpha windows.
	00: Lowest priority (default).
	01: Medium priority.
	10: Highest priority.
	11: Illegal.
	Note: Priority of enabled alpha windows must be different.
17:16	ALPHA1_WIN_PRIORITY (Alpha Window 1 Priority). Determines the priority of Alpha Window 1. A higher number indicates a higher priority. Priority is used to determine display order for overlapping alpha windows.
	00: Lowest priority (default).
	01: Medium priority.
	10: Highest priority.
	11: Illegal.
	Note: Priority of enabled alpha windows must be different.
15:14	Reserved
13	GV_SEL (GV Select). Selects input video format.
	0: YUV format.
	1: RGB format.
	Note: Mixing and blending configurations are created using bits [13, 11:9] of this register. See Table 7-1 "Valid Mixing/Blending Configurations" on page 339.
	If this bit is set to 1, EN_42X (F4BAR0+Memory Offset 00h[28]) must be programmed to 0.
12	VID_LIN_INV (Video Line Invert). When this bit is set, it allows the video window to be positioned at odd offsets with respect to the first line. The values below are recommended if VID_Y_START (F4BAR0+Memory Offset 0Ch[10:0]) is an odd (set to 1) or even (set to 0) number of lines from the start of the active display.
	0: Even.
	1: Odd.
11	Reserved: Set to 0.
10	CSC_FOR_VIDEO (Color Space Converter for Video). Determines whether or not the video stream from the video module is passed through the CSC.
	0: Disable. The video stream is sent "as is" to the video Mixer/Blender.
	1: Enable. The video stream is passed through the CSC (for YUV to RGB conversion).
	Note: Mixing and blending configurations are created using bits [13,11:9] of this register. See Table 7-1 "Valid Mixing/Blending Configurations" on page 339.
9	VIDEO_BLEND_MODE (Video Blending Mode). Allows selection of the type of video (i.e., interlaced or progressive) used for blending.
	0: Progressive video used for blending.
	1: Interlaced video used for blending.
	Note: Mixing and blending configurations are created using bits [13,11:9] of this register. See Table 7-1 "Valid Mixing/Blending Configurations" on page 339.



Bit	Description			
8	GFX_INS_VIDEO (Graphics Inside Video). This bit works in conjunction with bit ory Offset 4Ch[20]). COLOR_CHROMA_SEL selects whether the graphics is used for chroma keying. If COLOR_CHROMA_SEL = 0, graphics data is compact COLOR_CHROMA_SEL = 1, video data is compared to the chroma key.	d for color keying or the video data stream		
	0: Outside the alpha windows, graphics or video is displayed depending on the re	esult of the color key comparison.		
	Outside the alpha windows, only video is displayed (if COLOR_CHROMA_SEL COLOR_CHROMA_SEL = 1) color key comparison is not performed outside the color of the	, , , , , , , , , , , , , , , , , , , ,		
7	VID_WIN_PUSH_EN (Video Window Push Enable). Video window repositioning grammed value. Facilitates line rate matching in both fields.	g at an offset of 1 line below the pro-		
	0: Disable. (Default)			
	1: Enable.			
6	TOP_LINE_IN_ODD (Top Line in Odd Field). Allows selection of what field the to	op line is in.		
	0: Top line is in even field. (Default)			
	1: Top line is in odd field.			
5	Reserved.			
4	INSERT_EN (Insert Enable). When this bit is set, the odd frame is shifted with re	spect to the even frame.		
	0: No shifting occurs.			
	1: The odd frame is shifted according to the offset specified in bits [2:0].			
3	Reserved.			
2:0	OFFSET (Vertical Scaler Offset). For a non-interlaced video stream and when bo	bb de-interlacing is used, program a value		
	of 100 (i.e., shift one line); otherwise, leave at 000.			
Offset 50h	-53h Cursor Color Key Register (R/W)	Reset Value: 00000000h		
31:29	Reserved.			
28:24	COLOR_REG_OFFSET (Cursor Color Register Offset). This field indicates a bi used to indicate which of the two possible cursor color registers should be used for graphics stream.			
23:0	CUR_COLOR_KEY (Cursor Color Key). Specifies the 24-bit RGB value of the constream is compared with this value. If a match is detected, the pixel is replaced by Color registers.			
Offset 54h	-57h Cursor Color Mask Register (R/W)	Reset Value: 00000000h		
31:24	Reserved			
23:0	CUR_COLOR_MASK (Cursor Color Mask). This mask is a 24-bit value. Zeroes in the incoming graphics stream to be ignored.	in the mask cause the corresponding bits		
Offset 58h	-5Bh Cursor Color Register 1 (R/W)	Reset Value: 00000000h		
31:24	Reserved			
23:0	CUR_COLOR_REG1 (Cursor Color Register 1). Specifies a 24-bit cursor color blending) or a YUV value (for YUV blending). In interlaced YUV blending mode, Y.	,		
	This is one of two possible cursor color values. The COLOR_REG_OFFSET bits (determine a bit of the graphics data that if even, selects this color to be used.	(F4BAR0+Memory Offset 50h[28:24])		
Offset 5C	n-5Fh Cursor Color Register 2 (R/W)	Reset Value: 00000000h		
31:24	Reserved			
23:0	CUR_COLOR_REG2 (Cursor Color Register 2). Specifies a 24-bit cursor color viblending) or a YUV value (for YUV blending). In interlaced YUV blending mode, Yu			
	This is one of two possible cursor color values. The COLOR_REG_OFFSET bits (determine a bit of the graphics data that if even, selects this color to be used.	(F4BAR0+Memory Offset 50h[28:24])		

	Description
Offset 60	h-63h Alpha Window 1 X Position Register (R/W) Reset Value: 00000000h
	H_TOTAL and H_SYNC_END are values programmed in the GX1 module's Display Controller Timing registers (GX_BASE+Memory Offset 8330h[26:19] and 8338h[10:3], respectively). The value of (H_TOTAL – H_SYNC_END) is sometimes referred to as "horizontal back porch". For more information, see the <i>AMD Geode™ GX1 Processor Data Book</i> .
	Desired screen position should not be outside a video window (F4BAR0+Memory Offset 08h and 0Ch).
31:27	Reserved.
26:16	ALPHA1_X_END (Alpha Window 1 Horizontal End). Determines the horizontal end position of Alpha Window 1 (not inclusive). This value is calculated according to the following formula: Value = Desired screen position + (H_TOTAL - H_SYNC_END) - 1.
15:11	Reserved.
10:0	ALPHA1_X_START (Alpha Window 1 Horizontal Start). Determines the horizontal start position of Alpha Window 1. This value is calculated according to the following formula:
	Value = Desired screen position + (H_TOTAL – H_SYNC_END) – 2.
Offset 64	h-67h Alpha Window 1 Y Position Register (R/W) Reset Value: 00000000h
	V_TOTAL and V_SYNC_END are values programmed in the GX1 module's Display Controller Timing registers (GX_BASE+Memory Offset 8340h[26:16] and 8348h[26:16], respectively). The value of (V_TOTAL – V_SYNC_END) is sometimes referred to as "vertical back porch". For more information, see the AMD Geode™ GX1 Processor Data Book.
	Desired screen position should not be outside a video window (F4BAR0+Memory Offset 08h and 0Ch).
31:27	Reserved.
26:16	ALPHA1_Y_END (Alpha Window 1 Vertical End). Determines the vertical end position of Alpha Window 1 (not inclusive). This value is calculated according to the following formula:
	Value = Desired screen position + (V_TOTAL - V_SYNC_END) + 2.
15:11	Reserved.
10:0	ALPHA1_Y_START (Alpha Window 1 Vertical Start). Determines the vertical start position of Alpha Window 1. This value is calculated according to the following formula:
	Value = Desired screen position + (V_TOTAL - V_SYNC_END) + 1.
Offset 68	th-6Bh Alpha Window 1 Color Register (R/W) Reset Value: 00000000h
31:25	Reserved.
24	ALPHA1_COLOR_REG_EN (Alpha Window 1 Color Register Enable). Enable bit for the color key matching in Alpha
	Window 1.
	Window 1.1: Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match. The color value (in bits [23:0], ALPHA1_COLOR_REG) is displayed.
	Window 1. 1: Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match. The color value (in
23:0	Window 1.1: Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match. The color value (in bits [23:0], ALPHA1_COLOR_REG) is displayed.
23:0	 Window 1. Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match. The color value (in bits [23:0], ALPHA1_COLOR_REG) is displayed. Disable. Where there is a color key match, no blending is performed. ALPHA1_COLOR_REG (Alpha Window 1 Color Register). Specifies the color to be displayed inside Alpha Window 1 when there is a color key match in the alpha window. This is an RGB value (for RGB blending) or a YUV value (for YUV)
23:0 Offset 60	 Window 1. Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match. The color value (in bits [23:0], ALPHA1_COLOR_REG) is displayed. Disable. Where there is a color key match, no blending is performed. ALPHA1_COLOR_REG (Alpha Window 1 Color Register). Specifies the color to be displayed inside Alpha Window 1 when there is a color key match in the alpha window. This is an RGB value (for RGB blending) or a YUV value (for YUV blending). In interlaced YUV blending mode, Y/2 value should be used. This color is only displayed if the alpha window is enabled and bit 24 (ALPHA1_COLOR_REG_EN) is enabled.
	 Window 1. Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match. The color value (in bits [23:0], ALPHA1_COLOR_REG) is displayed. Disable. Where there is a color key match, no blending is performed. ALPHA1_COLOR_REG (Alpha Window 1 Color Register). Specifies the color to be displayed inside Alpha Window 1 when there is a color key match in the alpha window. This is an RGB value (for RGB blending) or a YUV value (for YUV blending). In interlaced YUV blending mode, Y/2 value should be used. This color is only displayed if the alpha window is enabled and bit 24 (ALPHA1_COLOR_REG_EN) is enabled.
Offset 60	 Window 1. Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match. The color value (in bits [23:0], ALPHA1_COLOR_REG) is displayed. Disable. Where there is a color key match, no blending is performed. ALPHA1_COLOR_REG (Alpha Window 1 Color Register). Specifies the color to be displayed inside Alpha Window 1 when there is a color key match in the alpha window. This is an RGB value (for RGB blending) or a YUV value (for YUV blending). In interlaced YUV blending mode, Y/2 value should be used. This color is only displayed if the alpha window is enabled and bit 24 (ALPHA1_COLOR_REG_EN) is enabled. Ch-6Fh Alpha Window 1 Control Register (R/W) Reset Value: 000000000h
Offset 60	 Window 1. 1: Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match. The color value (in bits [23:0], ALPHA1_COLOR_REG) is displayed. 0: Disable. Where there is a color key match, no blending is performed. ALPHA1_COLOR_REG (Alpha Window 1 Color Register). Specifies the color to be displayed inside Alpha Window 1 when there is a color key match in the alpha window. This is an RGB value (for RGB blending) or a YUV value (for YUV blending). In interlaced YUV blending mode, Y/2 value should be used. This color is only displayed if the alpha window is enabled and bit 24 (ALPHA1_COLOR_REG_EN) is enabled. Ch-6Fh Alpha Window 1 Control Register (R/W) Reset Value: 000000000h Reserved. LOAD_ALPHA (Load Alpha Value). (Write Only) When set to 1, this bit causes the Video Processor to load the alpha
Offset 60 31:18 17	 Window 1. 1: Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match. The color value (in bits [23:0], ALPHA1_COLOR_REG) is displayed. 0: Disable. Where there is a color key match, no blending is performed. ALPHA1_COLOR_REG (Alpha Window 1 Color Register). Specifies the color to be displayed inside Alpha Window 1 when there is a color key match in the alpha window. This is an RGB value (for RGB blending) or a YUV value (for YUV blending). In interlaced YUV blending mode, Y/2 value should be used. This color is only displayed if the alpha window is enabled and bit 24 (ALPHA1_COLOR_REG_EN) is enabled. Ch-6Fh Alpha Window 1 Control Register (R/W) Reset Value: 00000000h Reserved. LOAD_ALPHA (Load Alpha Value). (Write Only) When set to 1, this bit causes the Video Processor to load the alpha value (in bits [7:0], ALPHA_VAL) at the start of the next frame.
Offset 60 31:18 17	Window 1. 1: Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match. The color value (in bits [23:0], ALPHA1_COLOR_REG) is displayed. 0: Disable. Where there is a color key match, no blending is performed. ALPHA1_COLOR_REG (Alpha Window 1 Color Register). Specifies the color to be displayed inside Alpha Window 1 when there is a color key match in the alpha window. This is an RGB value (for RGB blending) or a YUV value (for YUV blending). In interlaced YUV blending mode, Y/2 value should be used. This color is only displayed if the alpha window is enabled and bit 24 (ALPHA1_COLOR_REG_EN) is enabled. Ch-6Fh Alpha Window 1 Control Register (R/W) Reset Value: 00000000h Reserved. LOAD_ALPHA (Load Alpha Value). (Write Only) When set to 1, this bit causes the Video Processor to load the alpha value (in bits [7:0], ALPHA_VAL) at the start of the next frame. ALPHA1_WIN_EN (Alpha Window 1 Enable). Enable bit for Alpha Window 1.
Offset 60 31:18 17	Window 1. 1: Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match. The color value (in bits [23:0], ALPHA1_COLOR_REG) is displayed. 0: Disable. Where there is a color key match, no blending is performed. ALPHA1_COLOR_REG (Alpha Window 1 Color Register). Specifies the color to be displayed inside Alpha Window 1 when there is a color key match in the alpha window. This is an RGB value (for RGB blending) or a YUV value (for YUV blending). In interlaced YUV blending mode, Y/2 value should be used. This color is only displayed if the alpha window is enabled and bit 24 (ALPHA1_COLOR_REG_EN) is enabled. Ch-6Fh Alpha Window 1 Control Register (R/W) Reset Value: 00000000h Reserved. LOAD_ALPHA (Load Alpha Value). (Write Only) When set to 1, this bit causes the Video Processor to load the alpha value (in bits [7:0], ALPHA_VAL) at the start of the next frame. ALPHA1_WIN_EN (Alpha Window 1 Enable). Enable bit for Alpha Window 1. 1: Enable Alpha Window 1.
Offset 60 31:18 17	Window 1. 1: Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match. The color value (in bits [23:0], ALPHA1_COLOR_REG) is displayed. 0: Disable. Where there is a color key match, no blending is performed. ALPHA1_COLOR_REG (Alpha Window 1 Color Register). Specifies the color to be displayed inside Alpha Window 1 when there is a color key match in the alpha window. This is an RGB value (for RGB blending) or a YUV value (for YUV blending). In interlaced YUV blending mode, Y/2 value should be used. This color is only displayed if the alpha window is enabled and bit 24 (ALPHA1_COLOR_REG_EN) is enabled. Ch-6Fh Alpha Window 1 Control Register (R/W) Reset Value: 00000000h Reserved. LOAD_ALPHA (Load Alpha Value). (Write Only) When set to 1, this bit causes the Video Processor to load the alpha value (in bits [7:0], ALPHA_VAL) at the start of the next frame. ALPHA1_WIN_EN (Alpha Window 1 Enable). Enable bit for Alpha Window 1. 1: Enable Alpha Window 1. O: Disable Alpha Window 1.



Table 7-7. F4BAR0+Memory Offset: Video Processor Configuration Registers (Continued)

Bit	Description
Offset 70h	n-73h Alpha Window 2 X Position Register (R/W) Reset Value: 00000000h
(0	_TOTAL and H_SYNC_END are values programmed in the GX1 module's Display Controller Timing registers GX_BASE+Memory Offset 8330h[26:19] and 8338h[10:3], respectively). The value of (H_TOTAL – H_SYNC_END) is somemes referred to as "horizontal back porch". For more information, see the <i>AMD Geode™ GX1 Processor Data Book</i> .
D	esired screen position should not be outside a video window (F4BAR0+Memory Offset 08h and 0Ch).
31:27	Reserved.
26:16	ALPHA2_X_END (Alpha Window 2 Horizontal End). Determines the horizontal end position of Alpha Window 2 (not inclusive). This value is calculated according to the following formula: Value = Desired screen position + (H_TOTAL - H_SYNC_END) - 1.
15:11	Reserved
10:0	ALPHA2_X_START (Alpha Window 2 Horizontal Start). Determines the horizontal start position of Alpha Window 2. This value is calculated according to the following formula:
	Value = Desired screen position + (H_TOTAL - H_SYNC_END) - 2.
Offset 74h	n-77h Alpha Window 2 Y Position Register (R/W) Reset Value: 00000000h
(0	_TOTAL and V_SYNC_END are values programmed in the GX1 module's Display Controller Timing registers GX_BASE+Memory Offset 8340h[26:16] and 8348h[26:16], respectively). The value of (V_TOTAL – V_SYNC_END) is somemes referred to as "vertical back porch". For more information, see the AMD Geode TM GX1 Processor Data Book.
D	esired screen position should not be outside a video window (F4BAR0+Memory Offset 08h and 0Ch).
31:27	Reserved.
26:16	ALPHA2_Y_END (Alpha Window 2 Vertical End). Determines the vertical end position of Alpha Window 2 (not inclusive). This value is calculated according to the following formula:
	Value = Desired screen position + (V_TOTAL – V_SYNC_END) + 2.
15:11	Reserved.
10:0	ALPHA2_Y_START (Alpha Window 2 Vertical Start). Determines the vertical start position of Alpha Window 2. This value is calculated according to the following formula:
	Value = Desired screen position + (V_TOTAL - V_SYNC_END) + 1.
Offset 78h	1-7Bh Alpha Window 2 Color Register (R/W) Reset Value: 00000000h
31:25	Reserved.
24	ALPHA2_COLOR_REG_EN (Alpha Window 2 Color Register Enable). Enable bit for the color key matching in Alpha Window 2.
	0: Disable. Where there is a color key match, graphics and video are alpha-blended.
	1: Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match, the color value (in bits [23:0], ALPHA2_COLOR_REG) is displayed.
23:0	ALPHA2_COLOR_REG (Alpha Window 1 Color Register). Specifies the color to be displayed inside Alpha Window 2 when there is a color key match in the alpha window. This is an RGB value (for RGB blending) or a YUV value (for YUV blending). In Interlaced YUV blending mode, Y/2 value should be used.
	This color is only displayed if the alpha window is enabled and bit 24 (ALPHA2_COLOR_REG_EN) is enabled.
Offset 7Ch	n-7Fh Alpha Window 2 Control Register (R/W) Reset Value: 00000000h
21.40	Reserved.
31:18	
17	LOAD_ALPHA (Load Alpha Value). (Write Only) When set to 1, this bit causes the Video Processor to load the alpha value (in bits [7:0], ALPHA2_VAL) at the start of the next frame.
17	value (in bits [7:0], ALPHA2_VAL) at the start of the next frame.
17	value (in bits [7:0], ALPHA2_VAL) at the start of the next frame. ALPHA2_WIN_EN (Alpha Window 2 Enable). Enable bit for Alpha Window 2. 0: Disable Alpha Window 2. 1: Enable Alpha Window 2.
17 16	value (in bits [7:0], ALPHA2_VAL) at the start of the next frame. ALPHA2_WIN_EN (Alpha Window 2 Enable). Enable bit for Alpha Window 2. 0: Disable Alpha Window 2. 1: Enable Alpha Window 2. Note: Valid only if video window is enabled (F4BAR0+Memory Offset 00h[0] = 1).
17	value (in bits [7:0], ALPHA2_VAL) at the start of the next frame. ALPHA2_WIN_EN (Alpha Window 2 Enable). Enable bit for Alpha Window 2. 0: Disable Alpha Window 2. 1: Enable Alpha Window 2. Note: Valid only if video window is enabled (F4BAR0+Memory Offset 00h[0] = 1). ALPHA2_INCR (Alpha Window 2 Increment). Specifies the alpha value increment/decrement.
17 16	value (in bits [7:0], ALPHA2_VAL) at the start of the next frame. ALPHA2_WIN_EN (Alpha Window 2 Enable). Enable bit for Alpha Window 2. 0: Disable Alpha Window 2. 1: Enable Alpha Window 2. Note: Valid only if video window is enabled (F4BAR0+Memory Offset 00h[0] = 1).

Bit	Description	
Offset 80	n-83h Alpha Window 3 X Position Register (R/W) Reset Value: 00000000h	
(H_TOTAL and H_SYNC_END are values programmed in the GX1 module's Display Controller Timing registers GX_BASE+Memory Offset 8330h[26:19] and 8338h[10:3], respectively). The value of (H_TOTAL – H_SYNC_END) is sometimes referred to as "horizontal back porch". For more information, see the AMD Geode TM GX1 Processor Data Book.	
Note:	Desired screen position should not be outside a video window (F4BAR0+Memory Offset 08h and 0Ch).	
31:27	Reserved.	
26:16	ALPHA3_X_END (Alpha Window 3 Horizontal End). Determines the horizontal end position of Alpha Window 3 (not inclusive). This value is calculated according to the following formula: Value = Desired screen position + (H_TOTAL - H_SYNC_END) - 1.	
15:11	Reserved.	
10:0	ALPHA3_X_START (Alpha Window 3 Horizontal Start). Determines the horizontal start position of Alpha Window 3. This value is calculated according to the following formula:	
	Value = Desired screen position + (H_TOTAL - H_SYNC_END) - 2.	
Offset 84I	h-87h Alpha Window 3 Y Position Register (R/W) Reset Value: 00000000h	
(/_TOTAL and V_SYNC_END are values programmed in the GX1 module's Display Controller Timing registers GX_BASE+Memory Offset 8340h[26:16] and 8348h[26:16], respectively). The value of (V_TOTAL − V_SYNC_END) is somemes referred to as "vertical back porch". For more information, see the <i>AMD Geode™ GX1 Processor Data Book</i> .	
	Desired screen position should not be outside a video window (F4BAR0+Memory Offset 08h and 0Ch).	
31:27	Reserved	
26:16	ALPHA3_Y_END (Alpha Window 3 Vertical End). Determines the vertical end position of Alpha Window 3 (not inclusive). This value is calculated according to the following formula:	
	Value = Desired screen position + (V_TOTAL - V_SYNC_END) + 2.	
15:11	Reserved	
10:0	ALPHA3_Y_START (Alpha Window 3 Vertical End). Determines the vertical start position of Alpha Window 3. This value is calculated according to the following formula:	
	Value = Desired screen position + (V_TOTAL - V_SYNC_END) + 1.	
Offset 88I	n-8Bh Alpha Window 3 Color Register (R/W) Reset Value: 00000000h	
31:25 24	Reserved. ALPHA3_COLOR_REG_EN (Alpha Window 3 Color Register Enable). Enable bit for the color key matching in Alpha Window 3.	
	0: Disable. Where there is a color key match, graphics and video are alpha-blended.	
	1: Enable. If this bit is enabled and the alpha window is enabled, then where there is a color key match, the color value (in bits [23:0], ALPHA3_COLOR_REG) is displayed.	
23:0	ALPHA3_COLOR_REG (Alpha Window 3 Color Register). Specifies the color to be displayed inside Alpha Window 3 when there is a color key match in the alpha window. This is an RGB value (for RGB blending) or a YUV value (for YUV blending). In Interlaced YUV blending mode, Y/2 value should be used.	
	This color is only displayed if the alpha window is enabled and the bit 24 (ALPHA3_COLOR_REG_EN) is enabled.	
Offset 8C	h-8Fh Alpha Window 3 Control Register (R/W) Reset Value: 00000000h	
31:18	Reserved	
17	LOAD_ALPHA (Load Alpha Value). (Write Only) When set to 1, this bit causes the Video Processor to load the alpha value (in bits [7:0], ALPHA3_VAL) at the start of the next frame.	
16	ALPHA3_WIN_EN (Alpha Window 3 Enable). Enable bit for Alpha Window 3.	
16		
16	0: Disable Alpha Window 3.	
16	1: Enable Alpha Window 3.	
16	·	
15:8	1: Enable Alpha Window 3.	



Table 7-7. F4BAR0+Memory Offset: Video Processor Configuration Registers (Continued)

Bit	Description				
Offset 90I	n-93h	Video Request Register (R/W)	Reset Value: 001B0017h		
31:28	Reserved. Set to 0.				
27:16	-	Iorizontal Request). Determines the horizontal (pixel) loca D. This value is calculated according to the following formula			
	Value = Desired screen p	osition + (H_TOTAL - H_SYNC_END) - 2.			
15:11	Reserved				
10:0	10:0 VIDEO_Y_REQ (Video Vertical Request). Determines the line number at which to start reques video FIFO. This value is calculated according to the following formula:				
	Value = Desired screen p	osition + (V_TOTAL - V_SYNC_END) + 1.			
Offset 94I	n-97h	Alpha Watch Register (RO)	Reset Value: 00000000h		
	es may be automatically inc eing used in the current fran	cremented/decremented for successive frames. This registene.	r can be used to read the alpha values		
31:24	Reserved.				
23:16	ALPHA3_VAL (Value for	Alpha Window 3).			
15:8	ALPHA2_VAL (Value fo	Alpha Window 2).			
7:0	ALPHA1_VAL (Value fo	Alpha Window 1).			
Offset 98I	n-3FFh	Reserved			
Offset 400)h-403h	Video Processor Display Mode Register (R/W)	Reset Value: 00000000h		
Selects va	rious Video Processor mod	es.			
31	Video FIFO Underflow (Empty).			
	0: No underflow has occ	urred.			
	1: Underflow has occurr	ed.			
	Write 1 to reset this bit.				
30	Video FIFO OverFlow (F	- rull).			
	0: No overflow has occu	rred.			
	1: Overflow has occurre	d.			
	Write 1 to reset this bit.				
29	Reserved. Write as read				
28	Reserved. Write as read				
27:4	Reserved. Set to 0.				
3	Reserved. Write as read				
2	Note: Reserved. Write	e as read.			
1:0	VID_SEL (Video Select)	. Selects the source of the video data.			
	00: GX1 module.				
	10: VIP block.				
	01: Reserved.				
	11: Reserved.				
	The GX1 module's video	clock must be active at all times, regardless of the source of	f video input.		
Offset 404	1h-407h	Reserved	Reset Value: 00000000h		
Offset 408	Bh-40Bh	Video Processor Test Mode Register (R/W)	Reset Value: 00000000h		
31:0	Reserved.				
Offset 400	2h 44Eh	Reserved			



Table 7-7. F4BAR0+Memory Offset: Video Processor Configuration Registers (Continued)

Bit	Description					
Offset 420	h-423h	GenLock Register (R/W)	Reset Value: 00000000h			
31:24	Reserved. Must be set to 0.					
23	ODD_TO (Odd Field Time Out). Indicate reset by writing 1 to it.	tes CGENTO0 (F4BAR0+Memory Offset 4	(3Ch[15:0]) has expired. This bit can be			
22	EVEN_TO (Even Field Time Out). Indicates CGENTO1 (F4BAR0+Memory Offset 43Ch[31:16]) has expired. This bit can be reset by writing 1 to it.					
21:9	Reserved.					
8	Reserved. Set to 0.					
7	Reserved. Set to 0.					
6	Reserved. Set to 0.					
5	Reserved. Set to 0.					
4	GENLOCK_TOUT_EN (GenLock Time	out Enable).				
	0: Disable.					
	1: Enable timeout.					
3	VIP_VSYNC_EDGE_SEL (VIP VSYNC with VIP.	Edge Select). Selects which edge of the	VSYNC signal should be synchronized			
	0: Rising edge.					
	1: Falling edge.					
2	GX1_VSYNC_EDGE_SEL (GX1 VSYNowith the GX1 module.	C Edge Select). Selects which edge of the	e VSYNC signal should be synchronized			
	0: Rising edge.					
	1: Falling edge.					
1	CT_GENLOCK_EN (Enable Continuou	us GenLock Function).				
	0: The continuous GenLock function is	disabled.				
	Enable locking (i.e., synchronization) ing).	of the GX1 VSYNC with the VIP VSYNC	on every VSYNC (i.e., continuous lock-			
	Note: If bit 0 (SG_GENLOCK_EN) =	1, it overrides the value of this bit.				
0	Reserved. Set to 0.					
Offset 424	h-427h Ge	enLock Delay Register (R/W)	Reset Value: 00000000h			
31:21	Reserved.					
20:0	GENLOCK_DEL (GenLock Delay). Indi Display Controller VSYNC.	icates the delay (in 27 MHz clocks) betwee	en the VIP VSYNC and the GX1 module's			
Offset 428	h-43Bh	Reserved				
Offset 430	h-43Fh Continuou	us GenLock Timeout Register (R/W)	Reset Value: 1FFF1FFFh			
31:16	CGENTO1 (Even Field Continuous Ge	enLock Timeout).				
15:0	CGENTO0 (Odd Field Continuous Ger	·				



7.3.2.2 VIP Support Registers - F4BAR2

F4 Index 18h, Base Address Register 2 (F4BAR2) points to the base address of where the VIP Configuration registers

are located. Table 7-8 shows the memory mapped VIP support registers accessed through F4BAR2.

Table 7-8. F4BAR2+Memory Offset: VIP Configuration Registers

Bit	Description				
Offset 00h	-03h Video Interface Port Configuration Register (R/W)	Reset Value: 00000000h			
31:23	Reserved. Must be set to 0.				
22	VIP FIFO Bus Request Threshold. VIP FIFO issues a bus request when it is filled with	32 or 64 bytes.			
	0: 64 bytes.				
	1: 32 bytes				
21	VBI Task B Store to Memory. When this bit is enabled, raw VBI task B data is stored to	memory.			
	0: Disable.				
	1: Enable.				
	This bit is relevant only if bit 18 (VBI Configuration Override) = 1 (enabled).				
20	VBI Task A Store to Memory. When this bit is enabled, raw VBI task A data is stored to	memory.			
	0: Disable.				
	1: Enable.				
	This bit is relevant only if bit 18 (VBI Configuration Override) = 1 (enabled).				
19	VBI Ancillary Store to Memory. When this bit is enabled, raw VBI Ancillary data is store	ed to memory.			
	0: Disable.				
	1: Enable.				
	This bit is relevant only if bit 18 (VBI Configuration Override) = 1 (enabled).				
18	VBI Configuration Override. When this bit is enabled, bits [21:19] override the setup sp	pecified in bits 17 and 16.			
	0: Disable.				
	1: Enable.				
17	VBI Data Task. Specifies the CCIR656 video stream task used to store raw VBI data to memory.				
	0: Task B.				
	1: Task A. This hit is relevant only if hit 45 (V/DI Made for COIDSES) A and hit 40 (V/DI Configuration)	(
16	This bit is relevant only if bit 16 (VBI Mode for CCIR656) = 1 and bit 18 (VBI Configuration)	on Override) = 0 (disabled).			
16	VBI Mode for CCIR656. Specifies the mode in which to store VBI data to memory.				
	0: Use CCIR656 ancillary data to store VBI data to memory.1: Use CCIR656 video task A or B to store VBI data to memory, depending on the value	e of hit 17 (VRI Data Task)			
	This bit is only used if bit 18 (VBI Configuration Override) = 0 (disabled).	e of bit 17 (VBI Data Task).			
45.0					
15:2 1:0	Reserved. Set to 0. Video Input Port Mode. Selects VIP operating mode.				
1.0	10: CCIR656 mode.				
	All other decodes: Reserved.				
Offset 04h		Reset Value: 00000000h			
31:18	Reserved. Must be set to 0.	TOOCE FAIRE. 000000011			
17	Line Interrupt. When asserted, allows interrupt (INTC#) generation when the Video Cur	rrent Line register (F4BAR2+ Mem-			
	ory Offset 10h) contents equal the Video Line Target Register (F4BAR2+ Memory Offset				
	0: Disable.				
	1: Enable.				
16	Field Interrupt. When asserted, allows interrupt (INTC#) generation at the end of a field current field). Interrupt generation can be enabled regardless of whether or not video cal				
	0: Disable.				
	1: Enable.				
15:11	Reserved. Must be set to 0.				



Table 7-8. F4BAR2+Memory Offset: VIP Configuration Registers (Continued)

Bit	Description Description
10	Auto-Flip. Video port operation mode.
10	O: The video port operation mode. CCIR656 control codes. O: The video port automatically detects the even and odd fields based on the VP_HREF and VP_VSYNC_IN signals or the CCIR656 control codes.
	1: The even/odd field detect logic is disabled and the video port automatically toggles between the even and odd buffers during capture. The odd buffer is the first to be filled in this mode.
	This bit must be programmed to 0 when Direct Video mode is used. Direct Video mode is used when VID_SEL = 10 (F4BAR0+Memory Offset 400h[1:0]). Otherwise the video select from the GX1 module. VID_SEL indicates the source of the video data.)
9	Capture (Store to Memory) VBI Data.
	0: Disable.
	1: Enable.
8	Capture (Store to Memory) Video Data.
	0: Disable.
	1: Enable.
7:2	Reserved. Must be set to 0.
1:0	Run Mode Capture. Selects capture run mode.
	00: Stop capture at end of current line.
	01: Stop capture at end of current field.
	10 Reserved.
	11: Start capture at beginning of next field.
Offset 08h	n-0Bh Video Interface Status Register (R/W) Reset Value: xxxxxxxxxh
31:25	Reserved. (Read Only)
24	Current Field. (Read Only)
	0: Even field is being processed.
	1: Odd field is being processed.
23:22	Reserved. (Read Only)
21	Base Register Not Updated. (Read Only) When set to 1, this bit indicates that one of the base registers (at F4BAR2+Memory Offset 20h, 24h, 40h, and 44h) has been written but has not yet been updated.
	0: All base registers are updated.
	1: One or more of the base registers has not been updated.
20	FIFO Overflow Status Indication.
	0: No overflow occurred.
	1: An overflow occurred for the FIFO between the VIP and the Fast X-Bus.
	Writing a 1 to this bit clears the status.
19:18	Reserved. (Read Only)
17	Line Interrupt (INTC#) Pending Status.
	0: Interrupt not pending.
	1: Interrupt pending.
	Writing a 1 to this bit clears the status.
16	Field Interrupt (INTC) Pending Status.
	0: Interrupt not pending.
	1: Interrupt pending.
	Writing a 1 to this bit clears the status.
15:10	Reserved. (Read Only)
9	VBI Data Capture Active. (Read Only)
	0: VBI data is not being stored to memory.
	VBI data is not being stored to memory. 1: VBI data is now being stored to memory.



Table 7-8. F4BAR2+Memory Offset: VIP Configuration Registers (Continued)

Bit	Description		
8	Video Data Capture Active	. (Read Only)	
	0: Video data is not being s	tored to memory.	
	1: Video data is now being	stored to memory.	
7:1	Reserved. (Read Only)		
0	Run Status. (Read Only)		
	0: Video port capture is not	active.	
	1: Video port capture is in p	rogress.	
Offset 0C	h-0Fh	Reserved	Reset Value: 00h
Offset 10	1-13h	Video Current Line Register (RO)	Reset Value: xxxxxxxxh
31:10	Reserved.		
9:0	Current Line. Indicates the start of each field.	video line currently being stored to memory. The count in	ndicated in this field is reset to 0 at the
Offset 14	n-17h	Video Line Target Register (R/W)	Reset Value: 00000000h
31:10	Reserved. Must be set to 0.		
9:0	Line Target. Indicates the vi	deo line to generate an interrupt on.	
Offset 18	n-1Bh	Reserved	Reset Value: 00000000h
Offset 1C	h-1Fh	Reserved	Reset Value: 00000000h
Offset 20	1-23h	Video Data Odd Base Register (R/W)	Reset Value: 00000000h
_	•	in graphics memory where odd video field data are store ue in this register is 16-byte aligned.	ed. Changes to this register take effect
is († b	ster, and the "Base Register No this register) is not updated at	When a new value is written to this register, the new value tupdated bit (F4BAR2+MemoryOffset 08h[21]) is set to this point. When the first data of the next field is stored ne) are written to the appropriate base registers, and the	o 1. The Video Data Odd Base register d to memory, the pending values of all
31:0	Video Odd Base Address. define the required address	Base address where odd video data are stored in graphic space.	es memory. Bits [3:0] are always 0, and
Offset 24	n-27h	Video Data Even Base Register (R/W)	Reset Value: 00000000h
-	•	n graphics memory where even video field data are store ue in this register is 16-byte aligned.	ed. Changes to this register take effect
is ti b	ster, and the "Base Register No er (this register) is not updated	When a new value is written to this register, the new value of Updated" bit (F4BAR2+MemoryOffset 08h[21]) is set at this point. When the first data of the next field is store ne) are written to the appropriate base registers, and the	to 1. The Video Data Even Base regised to memory, the pending values of all
31:0	Video Even Base Address. and define the required addr	Base address where even video data are stored in grap ess space.	hics memory. Bits [3:0] are always 0,
Offset 28	n-2Bh	Video Data Pitch Register (R/W)	Reset Value: 00000000h
•		f the video data buffer. This value is added to the start of to memory. This value must be an integral number of DN	•
31:16	Reserved.		
15:0	Wide Bata Bitala Constitue	the logical width of the video data buffer. Bits [1:0] are a	lwove 0
10.0	video Data Pitch. Specifies	the logical width of the video data buller. bits [1.0] are a	Iways o.

Revision 5.1



Table 7-8 F4BAR2+Memory Offset: VIP Configuration Registers (Continued)

	Table 7-8. F4BAR2+Memory Offset: VIP Configuration Registers (Continued)						
Bit	Description						
Offset 4	0h-43h	VBI Data Odd Base Register (R/W)	Reset Value: 00000000h				
•		e base address in graphics memory where VBI data for odd fields are stored. the next field. The value in this register is 16-byte aligned.	Changes to this register take				
Note:	This register is double-buffered. When a new value is written this register, the new value is placed in a special "pending" register, and the "Base Register Not Updated" bit (F4BAR2+MemoryOffset 08h[21]) is set to 1. The VBI Data Odd Base Register (this register) is not updated at this point. When the first data of the next field is stored to memory, the pending values of a base registers (including this one) are written to the appropriate base registers, and the "Base Register Not Updated" bit is cleared.						
31:0		se Address. Base address where VBI data for odd fields is stored in graphics ne required address space.	memory. Bits [3:0] are always 0				
Offset 4	4h-47h	VBI Data Even Base Register (R/W)	Reset Value: 00000000h				
		e base address in graphics memory where VBI data for even fields is stored. C ext field. The value in this register is 16-byte aligned.	hanges to this register take effect				
Note:	Iote: This register is double-buffered. When a new value is written to this register, the new value is placed in a special "pending" register, and the "Base Register Not Updated" bit (F4BAR2+MemoryOffset 08h[21]) is set to 1. The VBI Data Even Base Register (this register) is not updated at this point. When the first data of the next field is stored to memory, the pending values of a base registers (including this one) are written to the appropriate base registers, and the "Base Register Not Updated" bit cleared.						
31:0		ase Address. Base address where VBI data for even fields is stored in graphi the required address space.	cs memory. Bits [3:0] are always				
Offset 4	8h-4Bh	VBI Data Pitch Register (R/W)	Reset Value: 00000000h				
	This register specifies the logical width of the VBI data buffer. This value is added to the start of the line address to get the address of the next line where VBI data are stored to memory. This value must be an integral number of DWORDs.						
31:16	Reserved.						
15:0	VBI Data Pit	ch. Specifies the logical width of the video data buffer. Bits [1:0] are always 0					
Offset 4	Ch-1FFh	Reserved	Reset Value: 00h				

Debugging and Monitoring Revision 5.1

Debugging and Monitoring

8.1 Testability (JTAG)

The Test Access Port (TAP) allows board level interconnection verification and chip production tests. An IEEE-1149.1a compliant test interface, TAP supports all IEEE mandatory instructions as well as several optional instructions for added functionality. See Table 8-1 • for a summary of all instructions support. For further information on JTAG, refer to IEEE Standard 1149.1a-1993 Test Access Port and Boundary-Scan Architecture.

8.1.1 Mandatory Instruction Support

The TAP supports all IEEE mandatory instructions, including:

· BYPASS.

Presents the shortest path through a given chip (a 1-bit shift register).

EXTEST

Drives data loaded into the JTAG path (possibly with a SAMPLE/PRELOAD instruction) to output pins.

SAMPLE/PRELOAD
 Captures chip inputs and outputs.

8.1.2 Optional Instruction Support

The TAP supports the following IEEE optional instructions:

IDCODE

Presents the contents of the Device Identification register in serial format.

CLAMP

Ensures that the Bypass register is connected between TDI and TDO, and then drives data that was loaded into the Boundary Scan register (e.g., via SAMPLE-PRELOAD instruction) to output signals. These signals do not change while the CLAMP instruction is selected.

HiZ

Puts all chip outputs in inactive (floating) state (including all pins that do not require a TRI-STATE output for normal functionality). Note that not all pull-up resistors are disabled in this state.

8.1.3 JTAG Chain

Balls that are not part of the JTAG chain:

• USB I/Os

Table 8-1. JTAG Mode Instruction Support

Code	Instruction	Activity	
000	EXTEST	Drives shifted data to output pins.	
001	SAMPLE/PRELOAD	Captures inputs and system outputs.	
010	IDCODE	Scans out device identifier.	
011	HIZ	Puts all output and bidirectional pins in TRI-STATE.	
100	CLAMP	Drives fixed data from Boundary Scan register.	
101	Reserved		
110	Reserved		
111	BYPASS	Presents shortest external path through device.	

Electrical Specifications

This chapter provides information about:

- · General electrical specifications
- · DC characteristics
- AC characteristics

All voltage values in this chapter are with respect to $V_{\mbox{\scriptsize SS}}$ unless otherwise noted.

9.1 General Specifications

9.1.1 Electro Static Discharge (ESD)

This device is a high performance integrated circuit and is ESD sensitive. Handling and assembly of this device should be performed at ESD free workstations. Table 9-1 lists the ESD ratings of the SC3200.

Table 9-1. Electro Static Discharge (ESD)

Parameter	Units
Human Body Model (HBM)	2000V ESD
Machine Model (MM)	200V ESD

9.1.2 Power/Ground Connections and Decoupling

When testing and operating the SC3200, use standard high frequency techniques to reduce parasitic effects. For example:

- Filter the DC power leads with low-inductance decoupling capacitors.
- · Use low-impedance wiring.
- · Utilizing the PWR and GND pins.

9.1.3 Absolute Maximum Ratings

Stresses beyond those indicated in the following table may cause permanent damage to the SC3200, reduce device reliability and result in premature failure, even when there is no immediately apparent sign of failure. Prolonged exposure to conditions at or near the absolute maximum ratings may also result in reduced device life span and reduced reliability.

Note: The values in the following table are stress ratings only. They do not imply that operation under other conditions is impossible.

Table 9-2. Absolute Maximum Ratings

Symbol	Parameter	Min	Max	Unit	Comments
T _{CASE}	Operating case temperature	-10	110	°C	Note 1
T _{STORAGE}	Storage temperature	-45	125	°C	Note 2
V _{CC}	Supply voltage		See Table 9-3	V	
V _{MAX}	Voltage on				
	5V tolerant balls	-0.5	6.0	V	Note 3
	Others	-0.5	3.6	V	Note 3, Note 4
I _{IK}	Input clamp current	-0.5	10	mA	Note 1
I _{OK}	Output clamp current		25	mA	Note 1

- Note 1. Power applied no clocks.
- Note 2. No bias.
- Note 3. Voltage min is -0.8V with a transient voltage of 20 ns or less.
- Note 4. Voltage max is 4.0V with a transient voltage of 20 ns or less.



9.1.4 **Operating Conditions**

Table 9-3 lists the various power supplies of the SC3200 and provides the device operating conditions.

Table 9-3. Operating Conditions

Symbol (Note 1)	Parameter	Min	Тур	Max	Unit	Comments
T _C	Operating case temperature	0	-	85	οС	
AV _{CCUSB}	Analog power supply. Powers internal analog circuits and some external signals (see Table 9-4).	3.14	3.3	3.46	V	
V _{BAT}	Battery supply voltage. Powers RTC and ACPI when V_{BAT} is greater than V_{SB} (by at least 0.5V), and some external signals (see Table 9-4).	2.4	3.0	3.46	V	
V _{IO}	I/O buffer power supply. Powers most of the external signals (see Table 9-4); certain signals within this power plane are 5V tolerant.	3.14	3.3	3.46	V	
V _{CORE}	Core processor and internal digital power supply. Powers internal digital logic, including internal frequency multipliers.	1.71	1.8	1.89	V	
V _{PLL2} V _{PLL3}	PLL. Internal Phase Locked Loops (PLL) power supply.	3.14	3.3	3.46	V	
V _{SB}	Standby power supply. Powers RTC and ACPI when $V_{\rm SB}$ is greater than $V_{\rm BAT}$ 0.5V, and some external signals (see Table 9-4).	3.14	3.3	3.46	V	
V_{SBL}	Standby logic. Powers internal logic needed to support Standby V _{SB} .	1.71	1.8	1.89	V	
	V_{SBL} requires a 0.1 μF bypass capacitor to V_{SS} .					

Note 1. For V_{IH} (Input High Voltage), V_{IL} (Input Low Voltage), I_{OH} (Output High Current), and I_{OL} (Output Low Current) operating conditions refer to Section 9.2 "DC Characteristics" on page 375.

Notes:

- 1) All power sources except V_{BAT} must be connected, even if the function is not used.
- V_{SB}, and V_{SBL} must be on if any other voltage is applied. V_{SB} and V_{BAT} voltages can be applied separately. See Section 9.3.15 "Power-Up Sequencing" on page 434.
- The power planes of the SC3200 can be turned on or off. For more information, see Section 6.2.9 "Power Management Logic" on page 174.
- It is recommended that the voltage difference between V_{CORE} and V_{SBL} be less than 0.25V, in order to reduce leakage current. If the voltage difference exceeds 0.25V, excessive leakage current is used in gates that are connected on the boundary between voltage
- It is recommended that the voltage difference between V_{IO} and V_{SB} be less than 0.25V, in order to reduce leakage current. If the voltage difference exceeds 0.25V, excessive leakage current is used in gates that are connected on the boundary between voltage domains.

Table 9-4 indicates which power rails are used for each signal of the SC3200 external interface. Power planes not listed in this table are internal, and are not related to signals of the external interface.

Power Plane	Signal Names	V _{CC} Balls	V _{SS} Balls
Standby	GPWIO[0:2], LED#, ONCTL#, PWRBTN#, PWRCNT[1:2], THRM#, CLK32, IRRX1, RI2#, SDATA_IN2	V _{SB}	V _{SS}
Battery	X32I, X32O	V_{BAT}	V _{SS}
USB	DPOS_PORT1, DNEG_PORT1, DPOS_PORT2, DNEG_PORT2, DPOS_PORT3, DNEG_PORT3	AV _{CCUSB}	AV _{SSUSB}
I/O	All other external interface signals	V _{IO}	V_{SS}

Table 9-4. Power Planes of External Interface Signals

9.1.5 DC Current

DC current is not a simple measurement. Three of the SC3200 power states (On, Active Idle, Sleep) were selected for measurement. For each power state measured, two functional characteristics (Typical Average, Absolute Maximum) are used to determine how much current the SC3200 uses.

9.1.5.1 Power State Parameter Definitions

The DC characteristics tables in this section list Core and I/O current for three of the power states. For more explanation on the SC3200 power states see Section 6.2.9 "Power Management Logic" on page 174.

- On (C0): All internal and external clocks with respect to the SC3200 are running and all functional blocks inside the GX1 module (CPU Core, Memory Controller, Display Controller, etc.) are actively generating cycles. This is equivalent to the ACPI specification's "S0,C0" state.
- Active Idle (C1): The CPU Core has been halted, all
 other functional blocks (including the Display Controller
 for refreshing the display) are actively generating cycles.
 This state is entered when a HLT instruction is executed
 by the CPU Core. From a user's perspective, this state is
 indistinguishable from the On state and is equivalent to
 the ACPI specification's "S0,C1" state.
- Sleep (SL2): This is the lowest power state the SC3200 can be in with voltage still applied to the device's core and I/O supply pins. This is equivalent to the ACPI specification's "S1" state.

9.1.5.2 Definition and Measurement Techniques of SC3200 Current Parameters

These parameters describe the current while the SC3200 is in the On state:

• Typical Average: Indicates the average current used by the SC3200 while in the On state. This is measured by running typical Windows applications in a typical display mode. In this case, 800x600x8 bpp at 75 Hz, 50 MHz DCLK using a background image of vertical stripes (4pixel wide) alternating between black and white with power management disabled (to guarantee that the SC3200 never goes into the Active Idle state). This number is provided for reference only since it can vary greatly depending on the usage model of the system.

Note: This typical average should not be confused with the typical power numbers. Typical power is based on a combination of On (Typical Average) and Active Idle states.

Absolute Maximum: Indicates the maximum instantaneous current used by the SC3200. CPU Core current is measured by running the Landmark Speed 200 benchmark test (with power management disabled) and measuring the peak current at any given instant during the test. I/O current is measured by running Microsoft Windows 98® and using a background image of vertical stripes (1-pixel wide) alternating between black and white at the maximum display resolution.

Revision 5.1 Electrical Specifications

9.1.5.3 Definition of System Conditions for Measuring On Parameters

The SC3200's current is highly dependent on two functional characteristics, DCLK (DOT clock) and SDRAM frequency. Table 9-5 shows how these factors are controlled when measuring the typical average and absolute maximum processor current parameters.

9.1.5.4 DC Current Measurements

Table 9-6 and Table 9-7 show the DC current measurements of the SC3200.

Table 9-5. System Conditions Used to Measure SC3200 Current During On State

	System Conditions				
CPU Current Measurement	V _{CORE} (Note 1_	V _{IO} (Note 1)	DCLK Frequency	SDRAM Frequency	
Typical Average	Nominal	Nominal	50 MHz (Note 2)	Nominal	
Absolute Maximum	Max	Max	135 MHz (Note 3)	Max	

- Note 1. See Table 9-3 on page 370 for nominal and maximum voltages.
- Note 2. A DCLK frequency of 50 MHz is derived by setting the display mode to 800x600x8 bpp at 75 Hz, using a display image of vertical stripes (4-pixel wide) alternating between black and white with power management disabled.
- Note 3. A DCLK frequency of 135 MHz is derived by setting the display mode to 1280x1024x8 bpp at 75 Hz, using a display image of vertical stripes (1-pixel wide) alternating between black and white with power management disabled.

Table 9-6. DC Characteristics for On State

Symbol	Parameter (Note 1)	Typ Avg	Abs Max	Unit	Comments
I _{CC3ON}	f _{CLK} = 233 MHz, I/O Current @ V _{IO} = 3.3V (Nominal); CPU state = On	260	300	mA	I _{CC} for V _{IO}
	f _{CLK} = 266 MHz, I/O Current @ V _{IO} = 3.3V (Nominal); CPU state = On	270	310		
I _{COREON}	f _{CLK} = 233 MHz, Core Current @ V _{CORE} = 1.8V (Nominal); CPU state = On	820	990	mA	I _{CC} for V _{CORE}
	f _{CLK} = 266 MHz, Core Current @ V _{CORE} = 1.8V (Nominal); CPU state = On	900	1090		
I _{SBON}	SB Current @ V _{SB} = 3.3V (Nominal); CPU state = On	1	2	mA	
I _{SBLON}	SBL Current @ V _{SBL} = 1.8V (Nominal); CPU state = On	10	20	mA	
	SBL Current @ V _{SBL} = 2.0V (Nominal); CPU state = On	10	20		

Note 1. f_{CLK} ratings refer to internal clock frequency.

Table 9-7. DC Characteristics for Active Idle, Sleep, and Off States

Symbol	ParameterNote 1	Min	Тур	Max	Unit	Comments
I _{CC3IDLE}	f _{CLK} = 233 MHz, I/O Current @ V _{IO} = 3.3V (Nominal); CPU state = Active Idle		260		mA	I _{CC} for V _{IO}
	f _{CLK} = 266 MHz, I/O Current @ V _{IO} = 3.3V (Nominal); CPU state = Active Idle		270			
I _{CC3SLP}	I/O Current @ V _{IO} = 3.3V (Nominal); CPU state = Sleep		20	30	mA	I _{CC} for V _{IO} , Note 2
I _{COREIDLE}	f _{CLK} = 233 MHz, Core Current @ V _{CORE} = 1.8V (Nominal); CPU state = Active Idle		360		mA	I _{CC} for V _{CORE}
	f _{CLK} = 266 MHz, Core Current @ V _{CORE} = 1.8V (Nominal); CPU state = Active Idle		380			
I _{CORESLP}	Core Current @ V _{CORE} = 1.8V (Nominal); CPU state = Sleep		20	30	mA	I _{CC} for V _{CORE} , Note 2
I _{SBOFF}	SB Current @ V _{SB} = 3.3V (Nominal); CPU state = Off		<1		mA	
I _{SBLOFF}	SBL Current @ V _{SBL} = 1.8V (Nominal); CPU state = Off		<1		mA	I _{CC} for V _{SBL} , Note 3
I _{BAT}	BAT Current @ V _{BAT} = 3.0 (Nominal); CPU state = Off		7	50	μA	

- Note 1. f_{CLK} ratings refer to internal clock frequency.
- Note 2. All inputs are at 0.2V or V_{IO} 0.2 (CMOS levels). All inputs are held static, and all outputs are unloaded (static I_{OUT} = 0 mA).
- Note 3. All V_{SBL} supplied inputs are at 0.2V or V_{SBL} 0.2 (CMOS levels). All inputs are held static, and all outputs are unloaded (static I_{OUT} = 0 mA).

9.1.6 Ball Capacitance and Inductance

Table 9-8 gives ball capacitance and inductance values.

Table 9-8. Ball Capacitance and Inductance

Symbol	Parameter	Min	Тур	Max	Unit	Comments
C _{IN}	Input Pin Capacitance		4	7	pF	Note 1
C _{IN}	Clock Input Capacitance	5	8	12	pF	Note 1
C _{IO}	I/O Pin Capacitance		10	12	pF	Note 1
C _O	Output Pin Capacitance		6	8	pF	Note 1
L _{PIN}	Pin Inductance			20	nΗ	Note 2

Note 1. $T_A = 25$ °C, f = 1 MHz. All capacitances are not 100% tested.

Note 2. Not 100% tested.

AMD Revision 5.1 Electrical Specifications

9.1.7 Pull-Up and Pull-Down Resistors

The following table lists input balls that are internally connected to a pull-up (PU) or pull-down (PD) resistor. If these balls are not used, they do not require connection to an external PU or PD resistor.

Note: The resistors described in this table are implemented as transistors. The resistance for PUs assumes $V_{IN} = V_{SS}$ and for PDs assumes $V_{IN} = V_{IO}$.

Table 9-9. Balls with PU/PD Resistors

Ball No.				Тур			
Signal Name	I Name EBGA TEPBGA		PU/ PD	(Note 1) Value [Ω]			
PCI							
FRAME#	E1	D8	PU	22.5K			
C/BE[3:0]#	A8, D8, A10, A13	H4, F3, J2, L1	PU	22.5K			
PAR	C10	J4	PU	22.5K			
IRDY#	C8	F2	PU	22.5K			
TRDY#	B8	F1	PU	22.5K			
STOP#	D9	G1	PU	22.5K			
LOCK#	C9	H3	PU	22.5K			
DEVSEL#	B5	E4	PU	22.5K			
PERR#	В9	H2	PU	22.5K			
SERR#	A9	H1	PU	22.5K			
REQ[1:0]#	E3, C1	A5, B5	PU	22.5K			
INTA#	AE3	D26	PU	22.5K			
INTB#	AF1	C26	PU	22.5K			
INTC#	H4	C9	PU	22.5K			
INTD#	B22	AA2	PU	22.5K			
Low Pin Count (LPC)						
LAD[3:0]	AJ10, AK10, AL10, AJ11	L29, L30, L31, M28	PU	22.5K			
LDRQ	AL9	L28	PU	22.5K			
SERIRQ	AL8	J31	PU	22.5K			
System (Straps)							
CLKSEL[3:0]	AL13, AK3, B27, F3	P30, D29, AF3, B8	PD	100K			
BOOT16	G4	C8	PD	100K			
TFT_PRSNT	AK13	P29	PD	100K			
LPC_ROM	E4	D6	PD	100K			
FPCI_MON	D3	A4	PD	100K			
DID[1:0]	D2, D4	C6, C5	PD	100K			
ACCESS.bus (No	ote 2)						
AB1C	AJ13	N31	PU	22.5K			
AB1D	AL12	N30	PU	22.5K			
AB2C	AJ12	N29	PU	22.5K			
AB2D	AL11	M29	PU	22.5K			
Parallel Port							
AFD#/DSTRB#	AB2	D22	PU	22.5K			
PE	Т3	D17	PUNot e 2	22.5K			
			PDNot e 2	22.5K			
SLIN#/ASTRB#	W1	B20	PU	22.5K			
STB#/WRITE#	AB1	A22	PU	22.5K			

	Ball No.		D	Typ
Signal Name	EBGA	TEPBGA	PU/ PD	(Note 1) Value $[\Omega]$
INIT#	Y3	B21	PU	22.5K
JTAG				
TCK	AL4	E31	PU	22.5K
TMS	AJ5	F28	PU	22.5K
TDI	AK5	F29	PU	22.5K
TRST#	AK4	E29	PU	22.5K
GPIO (Note 2)				
GPIO1	H2, AL12	D10, N30	PU	22.5K
GPIO6	AH3	D28	PU	22.5K
GPIO7	AH4	C30	PU	22.5K
GPIO8	AJ2	C31	PU	22.5K
GPIO9	AG4	C28	PU	22.5K
GPIO10	AJ1	B29	PU	22.5K
GPIO11	H30	AJ8	PU	22.5K
GPIO12	AJ12	N29	PU	22.5K
GPIO13	AL11	M29	PU	22.5K
GPIO14	F1	D9	PU	22.5K
GPIO15	G3	A8	PU	22.5K
GPIO16	AL15	V31	PU	22.5K
GPIO17	J4	A10	PU	22.5K
GPIO18	A28	AG1	PU	22.5K
GPIO19	H4	C9	PU	22.5K
GPIO20	H3, AJ13	A9, N31	PU	22.5K
GPIO32	AJ11	M28	PU	22.5K
GPIO33	AL10	L31	PU	22.5K
GPIO34	AK10	L30	PU	22.5K
GPIO35	AJ10	L29	PU	22.5K
GPIO36	AL9	L28	PU	22.5K
GPIO37	AK9	K31	PU	22.5K
GPIO38	AJ9	K28	PU	22.5K
GPIO39	AL8	J31	PU	22.5K
Power Managen	nent			
PWRBTN#	E29	AH5	PU	100K
GPWIO[2:0]	G29, G28, E31	AJ6, AK5, AH6	PU	100K
Test and Measu	rement			
GTEST	AL5	F30	PD	22.5K

Note 1. Accuracy is: 22.5 $K\Omega$ resistors are within a range of 20 $K\Omega$ to 50 $K\Omega$. 100 $K\Omega$ resistors are within a range of 90 $K\Omega$ to 250 $K\Omega$.

Note 2. Controlled by software.

9.2 DC Characteristics

Table 9-10 describes the signal buffer types of the SC3200. (See Table 3-2 "432-EBGA Ball Assignment - Sorted by Ball Number" on page 29 and Table 3-4 "481-TEPBGA Ball Assignment - Sorted by Ball Number" on page 43) for each signal's buffer type.)

The subsections that follows provide detailed DC characteristics according to buffer type.

Table 9-10. Buffer Types

Symbol	Description	Reference
Diode	Diodes only, no buffer	
IN _{AB}	Input, ACCESS.bus compatible with Schmitt Trigger	Section 9.2.1
IN _{BTN}	Input, TTL compatible with Schmitt Trigger, low leakage	Section 9.2.2
IN _{PCI}	Input, PCI compatible	Section 9.2.3
IN _{STRP}	Input, Strap ball (min V _{IH} is 0.6V _{IO}) with weak pull-down	Section 9.2.4
IN _T	Input, TTL compatible	Section 9.2.5
IN _{TS}	Input, TTL compatible with Schmitt Trigger type 200 mV	Section 9.2.6
IN _{TS1}	Input, with Schmitt Trigger type 200 mV	Section 9.2.7
IN _{USB}	Input, USB compatible	Section 9.2.8
O _{AC97}	Output, Totem-Pole, AC97 compatible	Section 9.2.9
OD_n	Output, Open-Drain, capable of sinking <i>n</i> mA.Note 1	Section 9.2.10
OD _{PCI}	Output, Open-Drain, PCI compatible	Section 9.2.11
O _{p/n}	Output, Totem-Pole, capable of sourcing <i>p</i> mA and sinking <i>n</i> mA	Section 9.2.12
O _{PCI}	Output, PCI compatible, TRI-STATE	Section 9.2.13
O _{USB}	Output, USB compatible	Section 9.2.14
TS _{p/n}	Output, TRI-STATE, capable of sourcing <i>p</i> mA and sinking <i>n</i> mA	Section 9.2.15
WIRE	Wire, no buffer	

Note 1.Output from these signals is open-drain and cannot be forced high.



9.2.1 IN_{AB} DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{IH}	Input High Voltage	1.4		V	
V _{IL}	Input Low Voltage	-0.5 (Note 1)	0.8	V	
I _{IL}	Input Leakage Current		10	μΑ	$V_{IN} = V_{IO}$
			-10	μΑ	$V_{IN} = V_{SS}$
V _{HIS}	Input hysteresis	150		mV	

Note 1. Not 100% tested.

9.2.2 IN_{BTN} DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{IH}	Input High Voltage	2.0	V _{SB} +0.3 (Note 1)	V	
V _{IL}	Input Low Voltage	-0.5 (Note 1)	0.8	V	
I _{IL}	Input Leakage Current		5	μΑ	V _{IN} = V _{SB}
			-36	μΑ	$V_{IN} = V_{SS}$
V _{HIS}	Input HysteresisNote 1	250		mV	

Note 1. Not 100% tested.

9.2.3 IN_{PCI} DC Characteristics

Note that the buffer type for PCICLK (EBGA ball E2 / TEPBGA ball A7) is $\rm IN_T$ - not $\rm IN_{PCI}$.

Symbol	Parameter	Min	Max	Unit	Comments
V _{IH}	Input High Voltage	0.5V _{IO}	V _{IO} +0.3 (Note 1)	V	
V _{IL}	Input Low Voltage	-0.5 (Note 1)	0.3V _{IO}	V	
V _{IPU}	Input Pull-up Voltage	0.7V _{IO}		V	Note 2
I _{IL}	Input Leakage Current		+/-10	μΑ	0 < V _{IN} < V _{IO} , Note 3, Note 4

Note 1. Not 100% tested.

- Note 2. Not 100% tested. This parameter indicates the minimum voltage to which pull-up resistors are calculated in order to pull a floated network.
- Note 3. Input leakage currents include HiZ output leakage for all bidirectional buffers with TRI-STATE outputs.
- Note 4. See Exceptions 2 and 3 in Section 9.2.15.1 on page 379.

9.2.4 IN_{STRP} DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{IH}	Input High Voltage	0.6V _{IO}	V _{IO} +0.3 (Note 1)	V	
V _{IL}	Input Low Voltage		0.3V _{IO}	V	
I _{IL}	Input Leakage Current		36	μΑ	During Reset: V _{IN} = V _{IO}
			-10	μΑ	$V_{IN} = V_{SS}$

Note 1. Not 100% tested.

9.2.5 IN_T DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{IH}	Input High Voltage	2.0	V _{IO} +0.3 (Note 1)	V	
V _{IL}	Input Low Voltage	-0.5 (Note 1)	0.8	V	
I _{IL}	Input Leakage Current		10	μΑ	$V_{IN} = V_{IO}$
			-10	μΑ	$V_{IN} = V_{SS}$

Note 1. Not 100% tested.

9.2.6 IN_{TS} DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{IH}	Input High Voltage	2.0	V _{IO} +0.3 (Note 1)	V	
V _{IL}	Input Low Voltage	-0.5 (Note 1)	0.8	V	
I _{IL}	Input Leakage Current		10	μΑ	$V_{IN} = V_{IO}$
			-10	μΑ	$V_{IN} = V_{SS}$
V _H	Input Hysteresis	200		mV	

Note 1. Not 100% tested.

9.2.7 IN_{TS1} DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{IH}	Input High Voltage	0.5V _{IO}	V _{IO} +0.3 (Note 1)	V	
V _{IL}	Input Low Voltage	-0.5 (Note 1)	0.3V _{IO}	V	
I _{IL}	Input Leakage Current		10	μΑ	$V_{IN} = V_{IO}$
			-10	μΑ	V _{IN} = V _{SS}
V _{HIS}	Input Hysteresis	200		mV	Note 1

Note 1. Not 100% tested.

9.2.8 IN_{USB} DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{IH}	Input High Voltage	2.0	V _{IO} +0.3 (Note 1)	V	
V _{IL}	Input Low Voltage	-0.5 (Note 1)	0.8	V	
I _{IL}	Input Leakage Current		10	μΑ	$V_{IN} = V_{IO}$
			-10	μΑ	V _{IN} = V _{SS}
V _{DI}	Differential Input Sensitivity	0.2		V	(D+)-(D-) and Figure 9-1
V_{CM}	Differential Common Mode Range	0.8	2.5	V	Includes V _{DI} Range
V _{SE}	Single Ended Receiver Threshold	0.8	2.0	V	

Note 1. Not 100% tested.

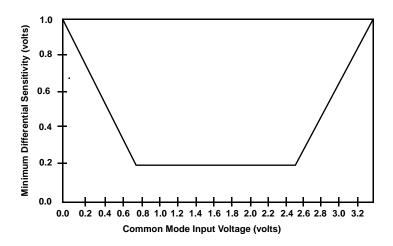


Figure 9-1. Differential Input Sensitivity for Common Mode Range

9.2.9 O_{AC97} DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{OH}	Output High Voltage	0.9V _{IO}		V	I _{OH} = -5 mA
V _{OL}	Output Low Voltage		0.1V _{IO}	V	I _{OL} = 5 mA

9.2.10 OD_n DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{OL}	Output Low Voltage		0.4	V	$I_{OL} = n \text{ mA}$

9.2.11 OD_{PCI} DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{OL}	Output Low Voltage		0.1V _{IO}	V	l _{OL} = 1500 μA

9.2.12 $O_{p/n}$ DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{OH}	Output High Voltage	2.4		V	$I_{OH} = -p \text{ mA}$
V _{OL}	Output Low Voltage		0.4	V	$I_{OL} = n \text{ mA}$

9.2.13 O_{PCI} DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{OH}	Output High Voltage	0.9V _{IO}		V	I _{OH} = -500 μA
V _{OL}	Output Low Voltage		0.1V _{IO}	V	I _{OL} =1500 μA

9.2.14 O_{USB} DC Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{USB_OH}	High-level Output Voltage	2.8	3.6 (Note 1)	V	I_{OH} = -0.25 mA R _L = 15 K Ω to GND
V _{USB_OL}	Low-level Output Voltage		0.3	V	I_{OL} = 2.5 mA R _L = 1.5 K Ω to 3.6V
t _{USB_CRS}	Output Signal Crossover Voltage	1.3	2.0	V	

Note 1. Tested by characterization.

9.2.15 $TS_{p/n}DC$ Characteristics

Symbol	Parameter	Min	Max	Unit	Comments
V _{OH}	Output High Voltage	2.4		V	$I_{OH} = -p \text{ mA}$
V _{OL}	Output Low Voltage		0.4	V	$I_{OL} = n \text{ mA}$

9.2.15.1 Exceptions

- 1) I_{OH} is valid for a GPIO pin only when it is not configured as open-drain.
- Signals with internal pull-ups have a maximum input leakage current of: -(\frac{V_{power} V_{IN}}{R(pull up)})

 Where V_{power} is V_{IO}, or V_{SB}.
- 3) Signals with internal pull-downs have a maximum input leakage current of: $+\left(\frac{V_{IN}-V_{SS}}{R(pull-down)}\right)$

AMD Revision 5.1 Electrical Specifications

9.3 AC Characteristics

The tables in this section list the following AC characteristics:

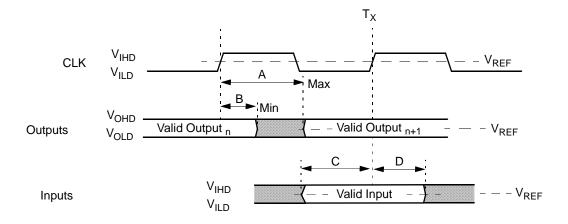
- · Output delays
- · Input setup requirements
- · Input hold requirements
- · Output float delays
- · Power-up sequencing requirements

The default levels for measurement of the rising clock edge reference voltage (V_{REF}), and other voltages are shown in Table 9-11. Input or output signals must cross these levels during testing. Unless otherwise specified, all measurement points in this section conform to these default levels.

Table 9-11. Default Levels for Measurement of Switching Parameters

Symbol	Parameter	Value (V)
V _{REF}	Reference Voltage	1.5
V_{IHD}	Input High Drive Voltage	2.0
V _{ILD}	Input Low Drive Voltage	0.8
V _{OHD}	Output High Drive Voltage	2.4
V _{OLD}	Output Low Drive Voltage	0.4

All AC tests are at V_{IO} = 3.14V to 3.46V (3.3V nominal), T_{C} = 0 o C to 85 o C, C_{L} = 50 pF, unless otherwise specified.



Legend: A = Maximum Output or Float Delay Specification

B = Minimum Output or Float Delay Specification

C = Minimum Input Setup Specification

D = Minimum Input Hold Specification

Figure 9-2. Drive level and Measurement Points

9.3.1 Memory Controller Interface

The minimum input setup and hold times described in Figure 9-3 (legend C and D) define the smallest acceptable sampling window during which a synchronous input signal must be stable to ensure correct operation.

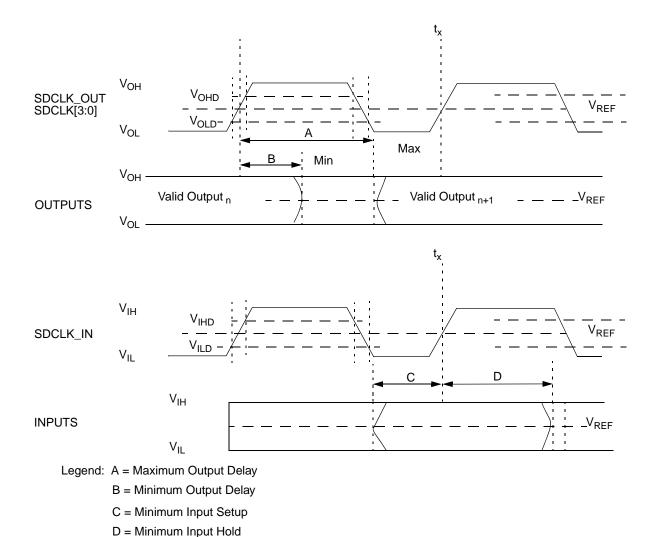


Figure 9-3. Memory Controller Drive Level and Measurement Points

Table 9-12. Memory Controller Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t ₁	Control output valid from SDCLK[3:0]	-3.0 + (x * y)	0.1 + (x × y)	ns	Note 1, Note 2
t ₂	MA[12:0], BA[1.0] output valid from SDCLK[3:0]	-3.2 + (x * y)	0.1 + (x × y)	ns	Note 2
t ₃	MD[63.0] output valid from SDCLK[3:0]	-2.2 + (x * y)	0.7 + (x * y)	ns	Note 2
t ₄	MD[63.0] read data in setup to SDCLK_IN	1.3		ns	
t ₅	MD[63:0] read data hold to SDCLK_IN	2.0		ns	
t ₆	SDCLK[3:0], SDCLK_OUT cycle time				
	233 MHz	10	14	ns	
	266 MHz	8.3	13.5		
t ₇	SDCLK[3:0], SDCLK_OUT fall/rise time between (V _{OLD} -V _{OHD})		2	ns	
t ₉	SDCLK_IN fall/rise time between (V _{ILD} -V _{IHD})		2	ns	
t ₁₀	SDCLK[3:0], SDCLK_OUT high time	•			
	233 MHz	4.0		ns	
	266 MHz	3.0			
t ₁₁	SDCLK[3:0], SDCLK_OUT low time				
	233 MHz	4.0		ns	
	266 MHz	2.5			

- Note 1. Control output includes all the following signals: RASA#, CASA#, WEA#, CKEA, DQM[7:0], and CS[1:0]#. Load = 50 pF, V_{CORE} = 1.8 V_{CORE} = 233/266 MHz, V_{IO} = 3.3 V_{CORE} = 0.3 V_{CORE} = 1.8 V_{CORE}
- Note 2. Use the Min/Max equations [value+(x * y)] to calculate the actual output value.

 x is the shift value which is applied to the SHFTSDCLK field, and y is 0.45 the core clock period.

 Note that the SHFTSDCLK field = GX_BASE+Memory Offset 8404h[5:3]. Refer to the AMD GeodeTM GX1 Processor Data Book for more information.

For example, for a 266 MHz SC3200 running a 88.7 MHz SDRAM clock, with a shift value of 3:

t1 Min = -3 + (3 * (3.76 * 0.45)) = 2.08 ns

t1 Max = 0.1 + (3 * (3.76 * 0.45)) = 5.18 ns

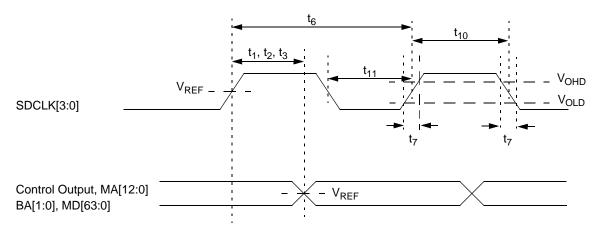


Figure 9-4. Memory Controller Output Valid Timing Diagram

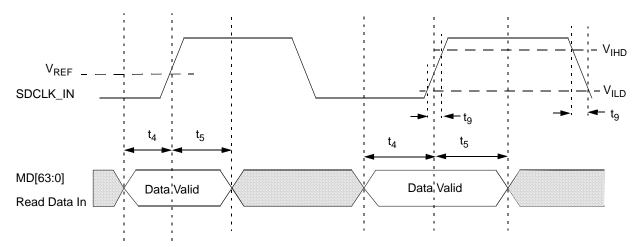


Figure 9-5. Read Data In Setup and Hold Timing Diagram

9.3.2 Video Port

Table 9-13. Video Input Port Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t _{VP_C}	VPCKIN cycle time	18		ns	
t _{VP_S}	Video Port input setup time before VPCKIN rising edge	6		ns	
t _{VP_H}	Video Port input hold time after VPCKIN rising edge	0		ns	
t _{VPCK_FR}	VPCKIN fall/rise time	-	2	ns	Note 1
t _{VPCK_D}	VPCKIN duty cycle	35/65		%	

Note 1. Guaranteed by characterization.

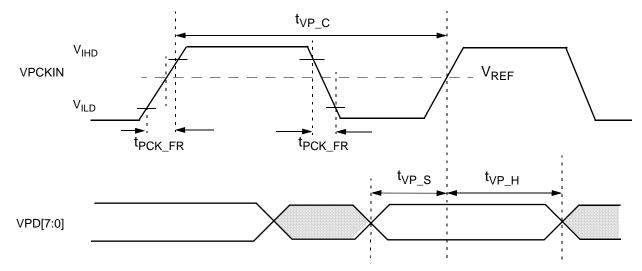


Figure 9-6. Video Input Port Timing Diagram

9.3.3 TFT Interface

Table 9-14. TFT Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t _{OV}	TFTD[17:0], TFTDE valid time after TFTDCK rising edge (multiplexed on IDE)	0	8	ns	
t _{OV}	TFTD[17:0], TFTDE valid time after TFTDCK rising edge (multiplexed on Parallel Port)	0	4	ns	
t _{CLK_RF}	TFTDCK rise/fall time between 0.8V and 2.0V		3	ns	Note 1
t _{CLK_P}	TFTDCK period time (multiplexed on IDE)	25		ns	
t _{CLK_P}	TFTDCK period time (multiplexed on Parallel Port)	12.5		ns	
t _{CLK_D}	TFTDCK duty cycle	40.	/60	%	

Note 1. Guaranteed by characterization

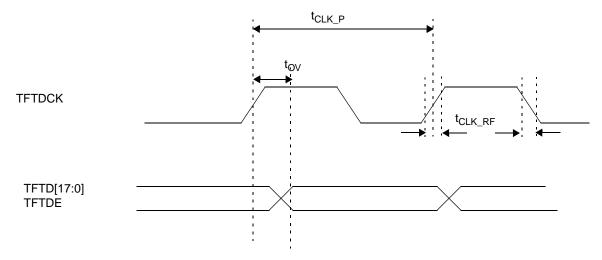


Figure 9-7. TFT Timing Diagram

9.3.4 ACCESS.bus Interface

The following tables describe the timing for the ACCESS.bus signals.

Notes: 1) All ACCESS.bus timing is not 100% tested.

2) In this table $t_{CLK} = 1/24MHz = 41.7$ ns.

Table 9-15. ACCESS.bus Input Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t _{BUFi}	Bus free time between Stop and Start condition	t _{SCLhigho}			
t _{CSTOsi}	AB1C/AB2C setup time	8 * t _{CLK} - t _{SCLri}			Before Stop condition
t _{CSTRhi}	AB1C/AB2C hold time	8 * t _{CLK} - t _{SCLri}			After Start condition
t _{CSTRsi}	AB1C/AB2C setup time	8 * t _{CLK} - t _{SCLri}			Before Start condition
t _{DHCsi}	Data high setup time	2 * t _{CLK}			Before AB1C/AB2C rising edge
t _{DLCsi}	Data low setup time	2 * t _{CLK}			Before AB1C/AB2C rising edge
t _{SCLfi}	AB1D/AB2D fall time		300	ns	
t _{SCLri}	AB1D/AB2D rise time		1	μS	
t _{SCLlowi}	AB1C/AB2C low time	16 * t _{CLK}			After AB1C/AB2C falling edge
t _{SCLhighi}	AB1C/AB2C high time	16 * t _{CLK}			After AB1C/AB2C rising edge
t _{SDAfi}	AB1D/AB2D fall time		300	ns	
t _{SDAri}	AB1D/AB2D rise time		1	μS	
t _{SDAhi}	AB1D/AB2D hold time	0			After AB1C/AB2C falling edge
t _{SDAsi}	AB1D/AB2D setup time	2 * t _{CLK}			Before AB1C/AB2C rising edge

Table 9-16. ACCESS.bus Output Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t _{SCLhigho}	AB1C/AB2C high time	K ∗ t _{CLK} - 1 μs			After AB1C/AB2C rising edge, Note 1
t _{SCLlowo}	AB1C/AB2C low time	K ∗ t _{CLK} - 1 μs			After AB1C/AB2C falling edge
t _{BUFo}	Bus free time between Stop and Start condition	t _{SCLhigho}	1	μS	Note 2
t _{CSTOso}	AB1C/AB2C setup time	t _{SCLhigho}	1	μS	Before Stop condition, Note 2
t _{CSTRho}	AB1C/AB2C hold time	t _{SCLhigho}	1	μS	After Start condition, Note 2
t _{CSTRso}	AB1C/AB2C setup time	t _{SCLhigho}	1	μS	Before Start condition, Note 2
t _{DHCso}	Data high setup time	t _{SCLhigho} - t _{SDAro}	1	μS	Before AB1C/AB2C rising edge, Note 2
t _{DLCso}	Data low setup time	t _{SCLhigho} - t _{SDAfo}	1	μS	Before AB1C/AB2C rising edge, Note 2
t _{SCLfo}	AB1D/AB2D signal fall time		300	ns	
t _{SCLro}	AB1D/AB2D signal rise time		1	μS	

Table 9-16.	ACCESS.bus	Output 1	Γiming Par	ameters	(Continued))
-------------	------------	----------	------------	---------	-------------	---

Symbol	Parameter	Min	Max	Unit	Comments
t _{SDAfo}	AB1D/AB2D signal fall time		300	ns	
t _{SDAro}	AB1D/AB2D signal rise time		1	μS	
t _{SDAho}	AB1D/AB2D hold time	7 * t _{CLK} - t _{SCLfo}			After AB1C/AB2C falling edge
t _{SDAvo}	AB1D/AB2D valid time		7 * t _{CLK} + t _{RD}		After AB1C/AB2C falling edge

- Note 1. K is determined by bits [7:1] of the ACBCTL2 register (LDN 05h/06h, Offset 05h).
- Note 2. $t_{SCLhigho}$ value depends on the signal capacitance and the pull-up value of the relevant pin.

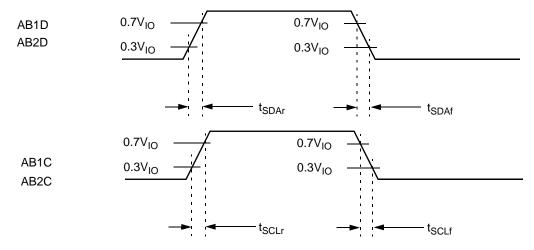


Figure 9-8. ACB Signals: Rising Time and Falling Timing Diagram

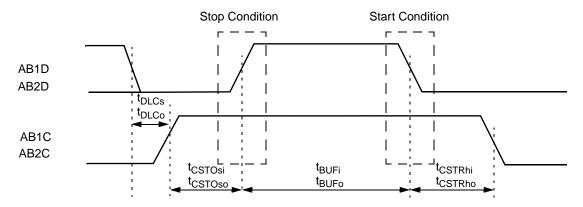


Figure 9-9. ACB Start and Stop Condition Timing Diagram

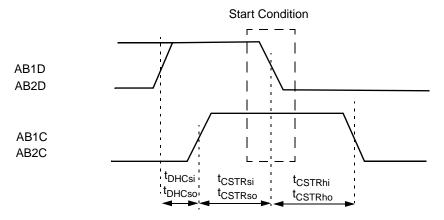


Figure 9-10. ACB Start Condition Timing Diagram

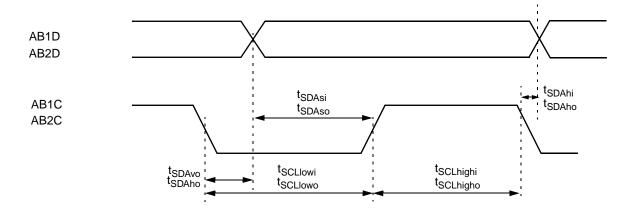


Figure 9-11. ACB Data Bit Timing Diagram

9.3.5 PCI Bus Interface

The SC3200 is compliant with PCI Bus Rev. 2.1 specifications. Relevant information from the PCI Bus specifications is provided below.

All parameters in Table 9-17 are not 100% tested. The parameters in this table are further described in Figure 9-13.

Symbol	Parameter	Min	Max	Unit	Comments
I _{OH} (AC)	Switching current high	-12V _{IO}		mA	0 < V _{OUT} ≤ 0.3V _{IO} ,
(Note 1)		-17.1(V _{IO} -V _{OUT})		mA	0.3V _{IO} < V _{OUT} < 0.9V _{IO}
			Equation A (Figure 9-13)		0.7V _{IO} < V _{OUT} < V _{IO}
	Test point (Note 2)		-32V _{IO}	mA	$V_{OUT} = 0.7V_{IO}$
I _{OL} (AC)	Switching current low	16V _{IO}		mA	$V_{IO} > V_{OUT} \ge 0.6 V_{IO}$
(Note 1)		26.7V _{OUT}		mA	$0.6V_{IO} > V_{OUT} > 0.1V_{IO}$
			Equation B (Figure 9-13)		0.18V _{IO} >V _{OUT} >0
	Test point (Note 2)		38V _{IO}	mA	V _{OUT} = 0.18V _{IO}
I _{CL}	Low clamp current	-25+(V _{IN} +1)/0.015		mA	-3 < V _{IN} <u><</u> -1
I _{CH}	High clamp current	25+(V _{IN} -V _{IO} -1)/0.015		mA	$V_{IO} + 4 > V_{IN} > V_{IO} + 1$
SLEW _R (Note 3)	Output rise slew rate	1	4	V/ns	0.2V _{IO} - 0.6V _{IO} Load
SLEW _F	Output fall slew rate	1	4	V/ns	0.6V _{IO} - 0.2V _{IO} Load

Table 9-17. PCI AC Specifications

- Note 1. Refer to the V/I curves in Figure 9-13. This specification does not apply to PCICLK0, PCICLK1, and PCIRST# which are system outputs.
- Note 2. Maximum current requirements are met when drivers pull beyond the first step voltage. Equations which define these maximum values (A and B) are provided with relevant diagrams in Figure 9-13. These maximum values are quaranteed by design.
- Note 3. Rise slew rate does not apply to open-drain outputs. This parameter is interpreted as the cumulative edge rate across the specified range, according to the test circuit in Figure 9-12.

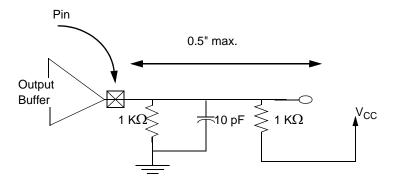


Figure 9-12. Testing Setup for Slew Rate and Minimum Timing

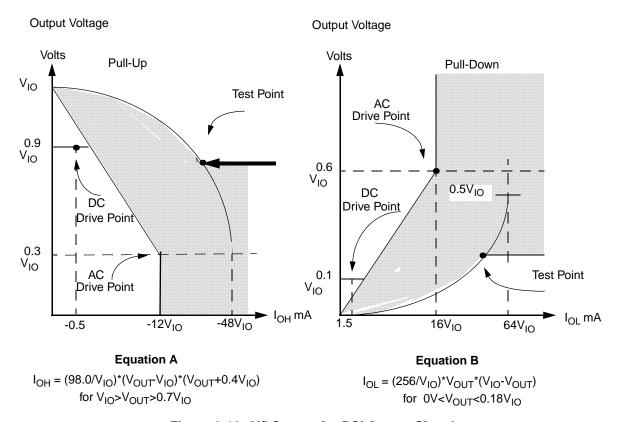


Figure 9-13. V/I Curves for PCI Output Signals

Symbol	Parameter	Min	Max	Unit	Comments
t _{CYC}	PCICLK cycle time	30		ns	Note 1
t _{HIGH}	PCICLK high time	11		ns	Note 2
t _{LOW}	PCICLK low time	11		ns	Note 2
PCICLK _{sr}	PCICLK slew Rate	1	4	V/ns	Note 3
PCIRST _{sr}	PCIRST# slew Rate	50	-	mV/ns	Note 4

Table 9-18. PCI Clock Parameters

- Note 1. Clock frequency is between nominal DC and 33 MHz. Device operational parameters at frequencies under 16 MHz are not 100% tested. The clock can only be stopped in a low state.
- Note 2. Guaranteed by characterization.
- Note 3. Slew rate must be met across the minimum peak-to-peak portion of the clock waveform (see Figure 9-14).
- Note 4. The minimum PCIRST# slew rate applies only to the rising (de-assertion) edge of the reset signal. See Figure 9-18 for PCIRST# timing.

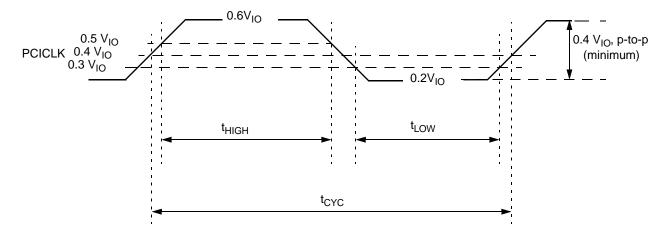


Figure 9-14. PCICLK Timing and Measurement Points

Symbol	Parameter	Min	Max	Unit	Comments
t _{VAL}	PCICLK to signal valid delay (on the bus)	2	11	ns	Note 1, Note 2
t _{VAL} (ptp)	PCICLK to signal valid delay (GNT#)	2	9	ns	Note 1, Note 2
t _{ON}	Float to active delay	2		ns	Note 1, Note 3,
t _{OFF}	Active to float delay		28	ns	Note 1, Note 3,
t _{SU}	Input setup time to PCICLK (on the bus)	7		ns	Note 4
t _{SU} (ptp)	Input setup time to PCICLK (REQ#)	6		ns	Note 4
t _H	Input hold time from PCICLK	0		ns	Note 4
t _{RST}	PCIRST# active time after power stable	1		ms	Note 3, Note 5
t _{RST-CLK}	PCIRST# active time after PCICLK stable	100		μs	Note 3, Note 5
t _{RST-OFF}	PCIRST# active to output float delay		40	ns	Note 3, Note 5, Note 6

Table 9-19. PCI Timing Parameters

- Note 1. See the timing measurement conditions in Figure 9-16.
- Note 2. Minimum times are evaluated with same load used for slew rate measurement (as shown in note 3 of Table); maximum times are evaluated with the load circuits shown in Figure 9-15, for high-going and low-going edges respectively.
- Note 3. Not 100% tested.
- Note 4. See the timing measurement conditions in Figure 9-17.
- Note 5. PCIRST# is asserted and de-asserted asynchronously with respect to PCICLK (see Figure 9-18).
- Note 6. All output drivers are asynchronously floated when PCIRST# is active.

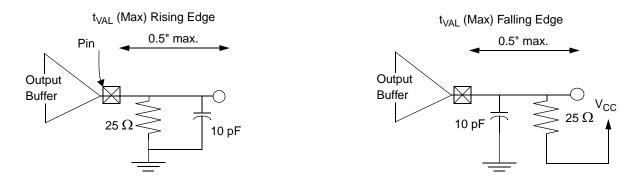


Figure 9-15. Load Circuits for Maximum Time Measurements

9.3.5.1 **Measurement and Test Conditions**

Table 9-20. Measurement Condition Parameters

Symbol	Value	Unit	Comments
V _{TH}	0.6 V _{IO}	V	Note 1
V _{TL}	0.2 V _{IO}	V	Note 1
V _{TEST}	0.4 V _{IO}	V	
V _{STEP} (rising edge)	0.285 V _{IO}	V	
V _{STEP} (falling edge)	0.615 V _{IO}	V	
V _{MAX}	0.4 V _{IO}	V	Note 2
Input signal edge rate	1	V/ns	

Note 1. The input test is performed with 0.1 V_{IO} of overdrive. Timing parameters must not exceed this overdrive. Note 2. V_{MAX} specifies the maximum peak-to-peak waveform allowed for measuring input timing.

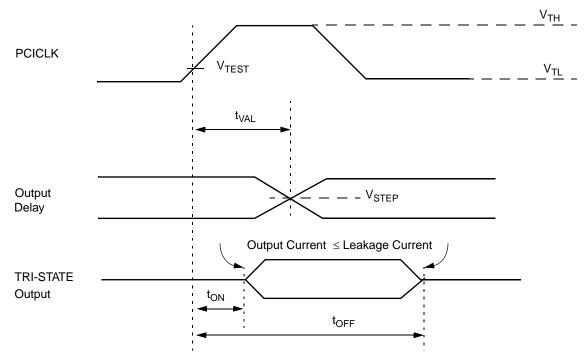


Figure 9-16. Output Timing Measurement Conditions

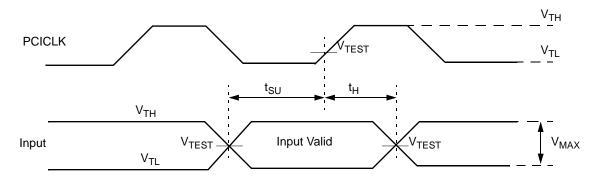
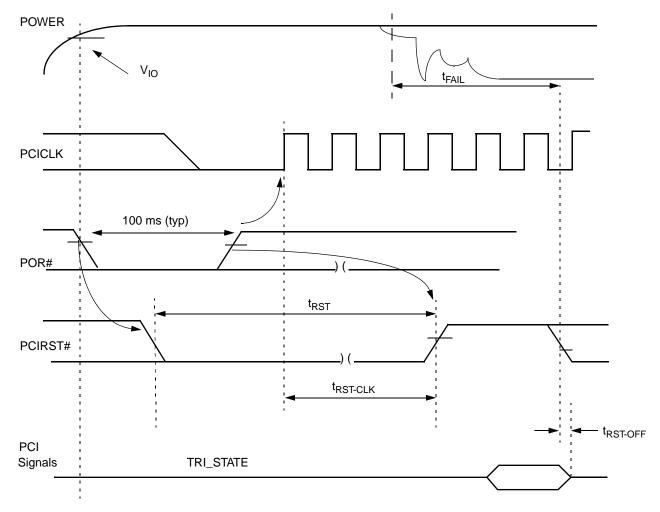


Figure 9-17. Input Timing Measurement Conditions



Note: The value of t_{FAIL} is 500 ns (maximum) from the power rail which exceeds specified tolerance by more than 500 mV.

Figure 9-18. PCI Reset Timing

9.3.6 Sub-ISA Interface

All output timing is guaranteed for 50 pF load, unless otherwise specified.

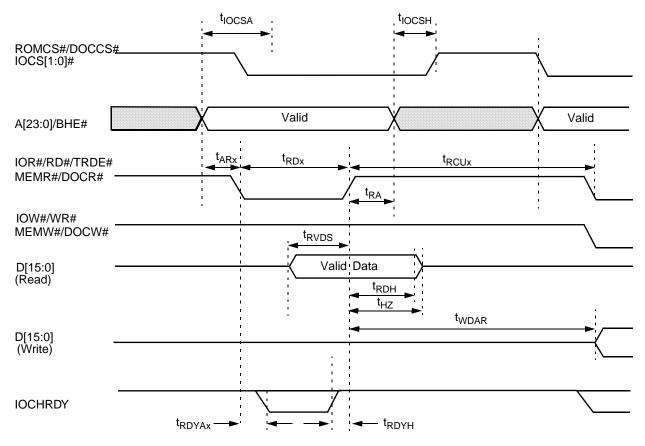
The ISA Clock divisor (defined in F0 Index 50h[2:0] of the Core Logic module) is 011.

Table 9-21. Sub-ISA Timing Parameters

Symbol	Parameter	Bus Width (Bits)	Туре	Min (ns)	Max (ns)	Figure	Comments
t _{RD1}	MEMR#/DOCR#/RD#/TRDE# read active pulse width FE to RE	16	М	225		9-19	Standard
t _{RD2}	MEMR#/DOCR#/RD#/TRDE# read active pulse width FE to RE	16	М	105		9-19	Zero wait state
t _{RD3}	IOR#/RD#/TRDE# read active pulse width FE to RE	16	I/O	160		9-19	Standard
t _{RD4}	IOR#/MEMR#/DOCR#/RD#/TRDE# read active pulse width FE to RE	8	M, I/O	520		9-19	Standard
t _{RD5}	IOR#/MEMR#/DOCR#/RD#/TRDE# read active pulse width FE to RE	8	M, I/O	160		9-19	Zero wait state
t _{RCU1}	MEMR#/DOCR#/RD#/TRDE# inactive pulse width	16	М	103		9-19	
t _{RCU2}	MEMR#/DOCR#/RD#/TRDE# inactive pulse width	8	М	163		9-19	
t _{RCU3}	IOR#/RD#/TRDE# inactive pulse width	8, 16	I/O	163		9-19	
t _{WR1}	MEMW#/WR# write active pulse width FE to RE	16	М	225		9-20	Standard
t _{WR2}	MEMW#/DOCW#/WR# write active pulse width FE to RE	16	М	105		9-20	Zero wait state
t _{WR3}	IOW#/WR# write active pulse width FE to RE	16	I/O	160		9-20	Standard
t _{WR4}	IOW#/MEMW#/DOCW#/WR# write active pulse width FE to RE	8	M, I/O	520		9-20	Standard
t _{WR5}	IOW#/MEMW#/DOCW#/WR# write active pulse width FE to RE	8	M, I/O	160		9-20	Zero wait state
t _{WCU1}	MEMW#/WR#/DOCW# inactive pulse width	16	М	103		9-20	
t _{WCU2}	MEMW#/WR#/DOCW# inactive pulse width	8	М	163		9-20	
t _{WCU3}	IOW#/WR# inactive pulse width	8, 16	I/O	163		9-20	
t _{RDYH}	IOR#/MEMR#/RD#/DOCR#/IOW#/ MEMW#/WR#/DOCW# hold after IOCHRDY RE	8, 16	M, I/O	120		9-19 9-20	
t _{RDYA1}	IOCHRDY valid after IOR#/MEMR#/ RD#/DOCR#/IOW#/MEMW#/WR#/ DOCW# FE	16	M, I/O		78	9-19 9-20	

Table 9-21. Sub-ISA Timing Parameters (Continued)

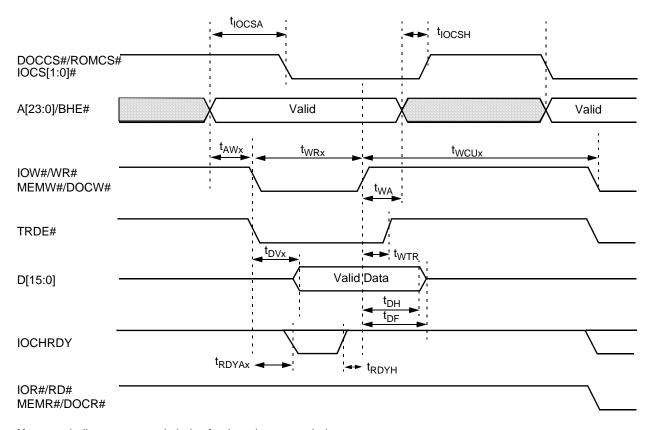
		Ī	<u> </u>		<u>′</u>	
Parameter	Bus Width (Bits)	Туре	Min (ns)	Max (ns)	Figure	Comments
IOCHRDY valid after IOR#/MEMR#/ RD#/DOCR#/IOW#/MEMW#/WR#/ DOCW# FE	8	M, I/O		366	9-19 9-20	
IOCS[1:0]#/DOCS#/ROMCS# driven active from A[23:0] valid	8, 16	M, I/O		34	9-19 9-20	
IOCS[1:0]#/DOCS#/ROMCS# valid hold after A[23:0] invalid	8, 16	M, I/O	0		9-19 9-20	
A[23:0]/BHE# valid before MEMR#/ DOCR# active	16	М	34		9-19	
A[23:0]/BHE# valid before IOR# active	16	I/O	100		9-19	
A[23:0]/BHE# valid before MEMR#/ DOCR#/IOR# active	8	M, I/O	100		9-19	
A[23:0]/BHE# valid hold after MEMR#/DOCR#/IOR# inactive	8, 16	M, I/O	25		9-19	
Read data D[15:0] valid setup before MEMR#/DOCR#/IOR# inactive	8, 16	M, I/O	24		9-19	
Read data D[15:0] valid hold after MEMR#/DOCR#/IOR# inactive	8, 16	M, I/O	0		9-19	
Read data floating after MEMR#/ DOCR#/IOR# inactive	8, 16	M, I/O		41	9-19	
A[23:0]/BHE# valid before MEMW#/ DOCW# active	16	М	34		9-20	
A[23:0]/BHE# valid before IOW# active	16	I/O	100		9-20	
A[23:0]/BHE# valid before MEMW#/ DOCW#/IOW# active	8	M, I/O	100		9-20	
A[23:0]/BHE# valid hold after MEMW#/DOCW#/IOW# invalid	8, 16	M, I/O	25		9-20	
Write data D[15:0] valid after MEMW#/DOCW# active	8, 16	М	40		9-20	
Write data D[15:0] valid after IOW# active	8	I/O	40		9-20	
Write data D[15:0] valid after IOW# active	16	I/O	-23		9-20	
TRDE# inactive after MEMW#/ DOCW#/IOW# inactive	8, 16	M, I/O	20		9-20	
Write data D[15:0] after MEMW#/ DOCW#/IOW# inactive	8, 16	M, I/O	45		9-20	
Write data D[15:0] goes TRI-STATE after MEMW#/DOCW#/IOW# inactive	8, 16	M, I/O		105	9-20	
Write data D[15:0] after read MEMR#/ DOCR#/IOR#	8, 16	M, I/O	41		9-19	
	Parameter IOCHRDY valid after IOR#/MEMR#/ RD#/DOCR#/IOW#/MEMW#/WR#/ DOCW# FE IOCS[1:0]#/DOCS#/ROMCS# driven active from A[23:0] valid IOCS[1:0]#/DOCS#/ROMCS# valid hold after A[23:0] invalid A[23:0]/BHE# valid before MEMR#/ DOCR# active A[23:0]/BHE# valid before MEMR#/ DOCR#/IOR# active A[23:0]/BHE# valid hold after MEMR#/DOCR#/IOR# inactive Read data D[15:0] valid setup before MEMR#/DOCR#/IOR# inactive Read data D[15:0] valid hold after MEMR#/DOCR#/IOR# inactive Read data floating after MEMR#/DOCR#/IOR# inactive A[23:0]/BHE# valid before MEMW#/DOCR#/IOR# inactive A[23:0]/BHE# valid before MEMW#/DOCW#/IOW# active A[23:0]/BHE# valid before MEMW#/DOCW#/IOW# active A[23:0]/BHE# valid hold after MEMW#/DOCW#/IOW# active A[23:0]/BHE# valid hold after MEMW#/DOCW#/IOW# active Write data D[15:0] valid after IOW# active Write data D[15:0] opes TRI-STATE after MEMW#/DOCW#/IOW# inactive Write data D[15:0] after read MEMR#/ Write data D[15:0] after read MEMR#/	Parameter IOCHRDY valid after IOR#/MEMR#/ RD#/DOCR#/IOW#/MEMW#/WR#/ DOCW# FE IOCS[1:0]#/DOCS#/ROMCS# driven active from A[23:0] valid IOCS[1:0]#/DOCS#/ROMCS# valid hold after A[23:0] invalid A[23:0]/BHE# valid before MEMR#/ DOCR# active A[23:0]/BHE# valid before MEMR#/ DOCR#/IOR# active A[23:0]/BHE# valid before MEMR#/ DOCR#/IOR# inactive Read data D[15:0] valid setup before MEMR#/DOCR#/IOR# inactive Read data D[15:0] valid hold after MEMR#/DOCR#/IOR# inactive Read data floating after MEMR#/ DOCR#/IOR# inactive A[23:0]/BHE# valid before MEMW#/ DOCR#/IOR# inactive A[23:0]/BHE# valid before MEMW#/ DOCW# active A[23:0]/BHE# valid before MEMW#/ DOCW# active A[23:0]/BHE# valid before MEMW#/ DOCW# active A[23:0]/BHE# valid hold after MEMW#/ DOCW#/IOW# active Write data D[15:0] valid after IOW# active Write data D[15:0] after MEMW#/ DOCW#/IOW# inactive Write data D[15:0] after MEMW#/ DOCW#/IOW# inactive Write data D[15:0] after read MEMR#/ B, 16	Parameter	Parameter	Parameter	Parameter



Note: x indicates a numeric index for the relevant symbol.

Figure 9-19. Sub-ISA Read Operation Timing Diagram

AMD Revision 5.1 Electrical Specifications



Note: x indicates a numeric index for the relevant symbol.

Figure 9-20. Sub-ISA Write Operation Timing Diagram

9.3.7 LPC Interface

Table 9-22. LPC and SERIRQ Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t _{VAL}	Output Valid delay	0	17	ns	After PCICLK rising edge
t _{ON}	Float to Active delay	2		ns	After PCICLK rising edge
t _{OFF}	Active to Float delay		28	ns	After PCICLK rising edge
t _{SU}	Input Setup time	7		ns	Before PCICLK rising edge
t _{HI}	Input Hold time	0		ns	After PCICLK rising edge

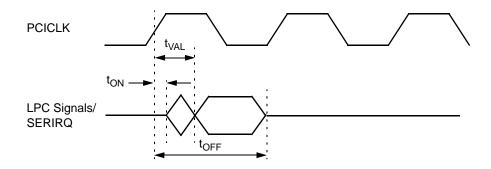


Figure 9-21. LPC Output Timing Diagram

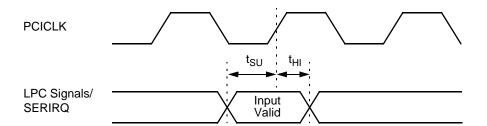


Figure 9-22. LPC Input Timing Diagram

AMD Revision 5.1 Electrical Specifications

9.3.8 IDE Interface

Table 9-23. IDE General Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t _{IDE_FALL}	$_{\rm DE_FALL}$ IDE signals fall time (from $0.9V_{\rm IO}$ to $0.1V_{\rm IO}$)			ns	C _L = 40 pF
t _{IDE_RISE}	E_RISE IDE signals rise time (from 0.1V _{IO} to 0.9V _{IO})			ns	C _L = 40 pF
t _{IDE_RST_PW}	IDE_RST# pulse width	25		μs	

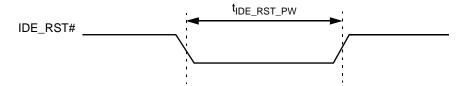
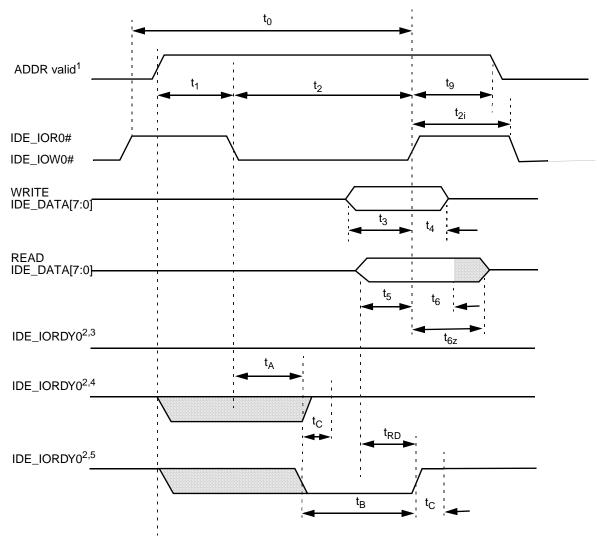


Figure 9-23. IDE Reset Timing Diagram

Table 9-24. IDE Register Transfer to/from Device Timing Parameters

				Mode				
Symbol	Parameter	0	1	2	3	5	Unit	Comments
t _O	Cycle time (min)	600	383	240	180	120	ns	Note 1
t ₁	Address valid to IDE_IOR[0:1]#/ IDE_IOW[0:1]# setup (min)	70	50	30	30	25	ns	
t ₂	IDE_IOR[0:1]#/IDE_IOW[0:1]# pulse width 8-bit (min)	290	290	290	80	70	ns	Note 1
t _{2i}	IDE_IOR[0:1]#/IDE_IOW[0:1]# recovery time (min)	-	-	-	70	25	ns	Note 1
t ₃	IDE_IOW[0:1]# data setup (min)	60	45	30	30	20	ns	
t ₄	IDE_IOW[0:1]# data hold (min)	30	20	15	10	10	ns	
t ₅	IDE_IOR[0:1]# data setup (min)	50	35	20	20	20	ns	
t ₆	IDE_IOR[0:1]# data hold (min)	5	5	5	5	5	ns	
t _{6Z}	IDE_IOR[0:1]# data TRI-STATE (max)	30	30	30	30	30	ns	Note 2
t ₉	IDE_IOR[0:1]#/IDE_IOW[0:1]# to address valid hold (min)	20	15	10	10	10	ns	
t _{RD}	Read data valid to IDE_IORDY[0:1] active (if IDE_IORDY[0:1] initially low after t _A (min)	0	0	0	0	0	ns	
t _A	IDE_IORDY[0:1] setup time	35	35	35	35	35	ns	Note 3
t _B	IDE_IORDY[0:1] pulse width (max)	1250	1250	1250	1250	1250	ns	
t _C	IDE_IORDY[0:1] assertion to release (max)	5	5	5	5	5	ns	

- Note 1. t₀ is the minimum total cycle time, t₂ is the minimum command active time, and t_{2i} is the minimum command recovery time or command inactive time. The actual cycle time equals the sum of the command active time and the command inactive time. The three timing requirements of t₀, t₂, and t_{2i} are met. The minimum total cycle time requirements is greater than the sum of t₂ and t_{2i}. (This means that a host implementation can lengthen t₂ and/or t_{2i} to ensure that t₀ is equal to or greater than the value reported in the device's IDENTIFY DEVICE data.)
- Note 2. This parameter specifies the time from the rising edge of IDE_IOR[0:1]# to the time that the data bus is no longer driven by the device (TRI-STATE).
- Note 3. The delay from the activation of IDE_IOR[0:1]# or IDE_IOW[0:1]# until the state of IDE_IORDY[0,1] is first sampled. If IDE_IORDY[0:1] is inactive, then the host waits until IDE_IORDY[0:1] is active before the PIO cycle is completed. If the device is not driving IDE_IORDY[0:1] negated after activation (t_A) of IDE_IOR[0:1]# or IDE_IOW[0:1]#, then t₅ is met and t_{RD} is not applicable. If the device is driving IDE_IORDY[0:1] negated after activation (t_A) of IDE_IOR[0:1]# or IDE_IOW[0:1]#, then t_{RD} is met and t₅ is not applicable.



Notes:

- 1) Device address consists of signals IDE_CS[0:1]# and IDE_ADDR[2:0].
- 2) Negation of IDE_IORDY0,1 is used to extend the PIO cycle. The determination of whether or not the cycle is to be extended is made by the host after t_A from the assertion of IDE_IOR[0:1]# or IDE_IOW[0:1]#.
- 3) Device never negates IDE_IORDY[0:1]. Device keeps IDE_IORDY[0:1] released, and no wait is generated.
- 4) Device negates IDE_IORDY[0:1] before t_A but causes IDE_IORDY[0:1] to be asserted before t_A. IDE_IORDY[0:1] is released, and no wait is generated.
- 5) Device negates IDE_IORDY[0:1] before t_A. IDE_IORDY[0:1] is released prior to negation and may be asserted for no more than 5 ns before release. A wait is generated.
- 6) The cycle completes after IDE_IORDY[0:1] is reasserted. For cycles where a wait is generated and IDE_IOR[0:1] is asserted, the device places read data on IDE_DATA[15:0] for t_{RD} before asserting IDE_IORDY[0:1].

Figure 9-24. Register Transfer to/from Device Timing Diagram

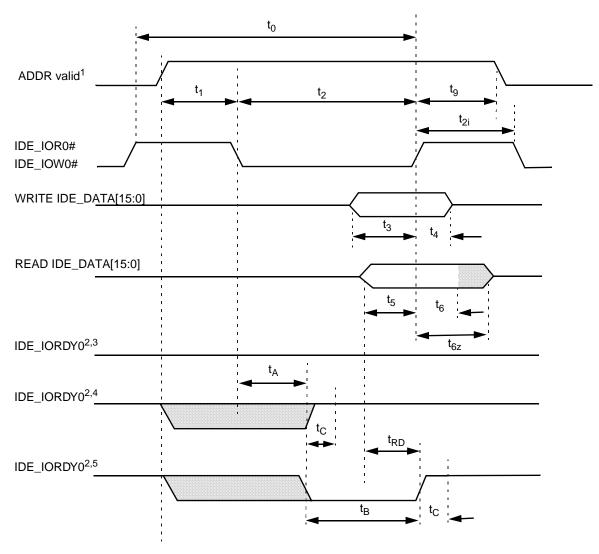


Table 9-25. IDE PIO Data Transfer to/from Device Timing Parameters

				Mode				
Symbol	Parameter	0	1	2	3	4	Unit	Comments
t _O	Cycle time (min)	600	383	240	180	120	ns	Note 1
t ₁	Address valid to IDE_IOR[0:1]#/ IDE_IOW[0:1]# setup (min)	70	50	30	30	25	ns	
t ₂	IDE_IOR[0:1]#/IDE_IOW[0:1]# 16-bit (min)	165	125	100	80	70	ns	Note 1
t _{2i}	IDE_IOR[0:1]#/IDE_IOW[0:1]# recovery time (min)	-	-	-	70	25	ns	Note 1
t ₃	IDE_IOW[0:1]# data setup (min)	60	45	30	30	20	ns	
t ₄	IDE_IOW[0:1]# data hold (min)	30	20	15	10	10	ns	
t ₅	IDE_IOR[0:1]# data setup (min)	50	35	20	20	20	ns	
t ₆	IDE_IOR[0:1]# data hold (min)	5	5	5	5	5	ns	
t _{6Z}	IDE_IOR[0:1]# data TRI-STATE (max)	30	30	30	30	30	ns	Note 2
t ₉	IDE_IOR[0:1]#/IDE_IOW[0:1]# to address valid hold (min)	20	15	10	10	10	ns	
t _{RD}	Read Data Valid to IDE_IORDY[0,1] active (if IDE_IORDY[0:1] initially low after t _A) (min)	0	0	0	0	0	ns	
t _A	IDE_IORDY[0:1] Setup time	35	35	35	35	35	ns	Note 3
t _B	IDE_IORDY[0:1] Pulse Width (max)	1250	1250	1250	1250	1250	ns	
t _C	IDE_IORDY[0:1] assertion to release (max)	5	5	5	5	5	ns	

- Note 1. t₀ is the minimum total cycle time, t₂ is the minimum command active time, and t_{2i} is the minimum command recovery time or command inactive time. The actual cycle time equals the sum of the command active time and the command inactive time. The three timing requirements of t₀, t₂, and t_{2i} are met. The minimum total cycle time requirement is greater than the sum of t₂ and t_{2i}. (This means that a host implementation may lengthen t₂ and/or t_{2i} to ensure that t₀ is equal to or greater than the value reported in the device's IDENTIFY DEVICE data.)
- Note 2. This parameter specifies the time from the rising edge of IDE_IOR[0:1]# to the time that the data bus is no longer driven by the device (TRI-STATE).
- Note 3. The delay from the activation of IDE_IOR[0:1]# or IDE_IOW[0:1]# until the state of IDE_IORDY[0:1] is first sampled. If IDE_IORDY[0:1] is inactive, then the host waits until IDE_IORDY[0:1] is active before the PIO cycle is completed. If the device is not driving IDE_IORDY[0:1] negated after the activation (t_A) of IDE_IOR[0:1]# or IDE_IOW[0:1]#, then t_5 is met and t_{RD} is not applicable. If the device is driving IDE_IORDY[0:1] negated after the activation (t_A) of IDE_IOR[0:1]# or IDE_IOW[0:1]#, then t_{RD} is met and t_5 is not applicable.

Revision 5.1



Notes:

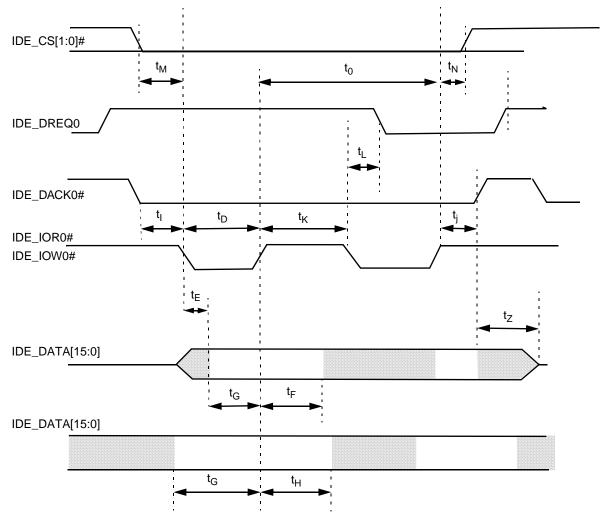
- 1) Device address consists of signals IDE_CS[0:1]# and IDE_ADDR[2:0].
- 2) Negation of IDE_IORDY[0:1] is used to extend the PIO cycle. The determination of whether or not the cycle is to be extended is made by the host after t_A from the assertion of IDE_IOR[0:1]# or IDE_IOW[0:1]#.
- 3) Device never negates IDE_IORDY[0:1]. Devices keep IDE_IORDY[0:1] released, and no wait is generated.
- 4) Device negates IDE_IORDY[0:1] before t_A but causes IDE_IORDY[0:1] to be asserted before t_A. IDE_IORDY[0:1] is released, and no wait is generated.
- 5) Device negates IDE_IORDY[0:1] before t_A. IDE_IORDY[0:1] is released prior to negation and may be asserted for no more than 5 ns before release. A wait is generated.
- 6) The cycle completes after IDE_IORDY[0:1] is reasserted. For cycles where a wait is generated and IDE_IOR[0:1]# is asserted, the device places read data on IDE_DATA[15:0] for t_{RD} before asserting IDE_IORDY[0:1].

Figure 9-25. PIO Data Transfer to/from Device Timing Diagram

Table 9-26. IDE Multiword DMA Data Transfer Timing Parameters

			Mode			
Symbol	Parameter	0	1	2	Unit	Comments
t ₀	Cycle time (min)	480	150	120	ns	Note 1
t _D	IDE_IOR[0:1]#/IDE_IOW[0:1]# (min)	215	80	70	ns	
t _E	IDE_IOR[0:1]# data access (max)	150	60	50	ns	
t _F	IDE_IOR[0:1]# data hold (min)	5	5	5	ns	
t _G	IDE_IOW[0:1]#/IDE_IOW[0:1]# data setup (min)	100	30	20	ns	
t _H	IDE_IOW[0:1]# data hold (min)	20	15	10	ns	
t _l	IDE_DACK[0:1]# to IDE_IOR[0:1]#/ IDE_IOW[0:1]# setup (min)	0	0	0	ns	
tu	IDE_IOR[0:1]#/IDE_IOW[0:1]# to IDE_DACK[0:1]# hold (min)	20	5	5	ns	
t _{KR}	IDE_IOR[0:1]# negated pulse width (min)	50	50	25	ns	
t _{KW}	IDE_IOW[0:1]# negated pulse width (min)	215	50	25	ns	
t _{LR}	IDE_IOR[0:1]# to IDE_DREQ[0:1] delay (max)	120	40	35	ns	
t _{LW}	IDE_IOW[0:1]# to IDE_DREQ0,1 delay (max)	40	40	35	ns	
t _M	IDE_CS[0:1]# valid to IDE_IOR[0:1]#/ IDE_IOW[0:1]# (min)	50	30	25	ns	
t _N	IDE_CS[0:1]# hold	15	10	10	ns	
t _Z	IDE_DACK[0:1]# to TRI-STATE	20	25	25	ns	

Note 1. t₀ is the minimum total cycle time, t_D is the minimum command active time, and t_{KR} or t_{KW} is the minimum command recovery time or command inactive time. The actual cycle time equals the sum of the command active time and the command inactive time. The three timing requirements of t₀, t_D and t_{KR/KW}, are met. The minimum total cycle time requirement t₀ is greater than the sum of t_D and t_{KR/KW}. (This means that a host implementation can lengthen t_D and/or t_{KR/KW} to ensure that t₀ is equal to or greater than the value reported in the device's IDENTIFY DEVICE data.)



Notes:

- 1) For Multiword DMA transfers, the Device may negate IDE_DREQ[0:1] within the tL specified time once IDE_DACK[0:1 is asserted, and reassert it again at a later time to resume the DMA operation. Alternatively, if the device is able to co tinue the transfer of data, the device may leave IDE_DREQ[0:1] asserted and wait for the host to reasse IDE_DACK[0:1]#.
- 2) This signal can be negated by the host to Suspend the DMA transfer in process.

Figure 9-26. Multiword DMA Data Transfer Timing Diagram

Table 9-27. IDE UltraDMA Data Burst Timing Parameters

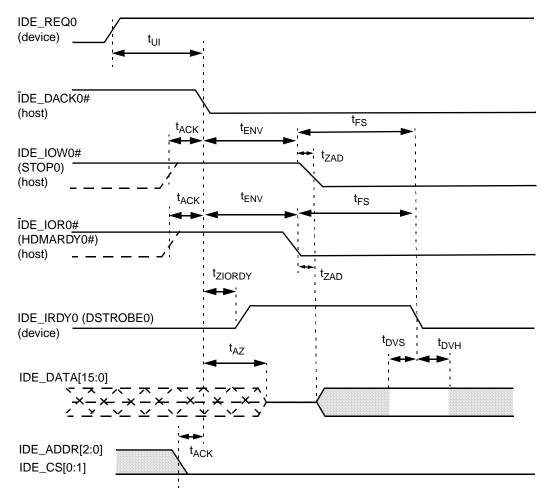
		Мо	de 0	Мо	de 1	Мо	de 2		
Symbol	Parameter	Min	Max	Min	Max	Min	Max	Unit	Comments
t _{2CYC}	Typical sustained average two cycle time	240		160		120		ns	
2010	Two cycle time allowing for clock variations (from rising edge to next rising edge or from falling edge to next falling edge of STROBE)	235		156		117		ns	
t _{CYC}	Cycle time allowing for asymmetry and clock variations (from STROBE edge to STROBE edge)	114		75		55		ns	
t _{DS}	Data setup time (at recipient)	15		10		7		ns	
t _{DH}	Data hold time (at recipient)	5		5		5		ns	
t _{DVS}	Data valid setup time at sender (from data bus being valid until STROBE edge)	70		48		34		ns	
t _{DVH}	Data valid hold time at sender (from STROBE edge until data may become invalid)	6		6		6		ns	
t _{FS}	First STROBE time (for device to first negate IDE_IRDY[0:1] (DSTROBE[0:1]) from IDE_IOW[0:1]# (STOP[0:1]) during a data in burst)	0	230	0	200	0	170	ns	
t _{LI}	Limited interlock time	0	150	0	150	0	150	ns	Note 1
t _{MLI}	Interlock time with minimum	20		20		20		ns	Note 1
t _{UI}	Unlimited interlock time	0		0		0		ns	Note 1
t _{AZ}	Maximum time allowed for output drivers to release (from being asserted or negated)		10		10		10	ns	
t _{ZAH}	Minimum delay time required for output driv-	20		20		20		ns	
t _{ZAD}	ers to assert or negate (from released state)	0		0		0		ns	
t _{ENV}	Envelope time (from IDE_DACK[0:1]# to IDE_IOW[0:1]# (STOP[0:1]) and IDE_IOR[0:1]# (HDMARDY[0:1]#) during data out burst initiation)	20	70	20	70	20	70	ns	
t _{SR}	STROBE to DMARDY time (if DMARDY# is negated before this long after STROBE edge, the recipient receives no more than one additional data WORD)		50		30		20	ns	
t _{RFS}	Ready-to-final-STROBE time (no STROBE edges are sent this long after negation of DMARDY#)		75		60		50	ns	
t _{RP}	Ready-to-pause time (time that recipient waits to initiate pause after negating DMARDY#)	160		125		100		ns	
t _{IORDYZ}	Pull-up time before allowing IDE_IORDY[0:1] to be released		20		20		20	ns	
t _{ZIORDY}	Minimum time device waits before driving IDE_IORDY[0:1]	0		0		0		ns	
t _{ACK}	Setup and hold times for IDE_DACK[0:1]# (before assertion or negation)	20		20		20		ns	
t _{SS}	Time from STROBE edge to negation of IDE_DREQ[0:1] or assertion of IDE_IOW[0:1]# (STOP[0:1]) (when sender terminates a burst)	50		50		50		ns	

Note 1. t_{UI} , t_{MLI} , and t_{LI} indicate sender-to-recipient or recipient-to-sender interlocks, that is, one agent (either sender or recipient) is waiting for the other agent to respond with a signal before proceeding. t_{UI} is an unlimited interlock with no maximum time value. t_{MLI} is a limited timeout with a defined minimum. t_{LI} is a limited time-out with a defined maximum.

Revision 5.1 Electrical Specifications

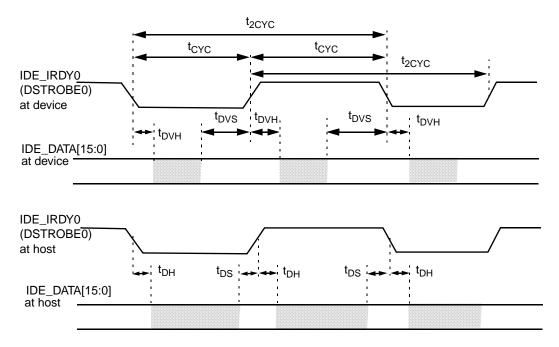
All timing parameters are measured at the connector of the device to which the parameter applies. For example, the sender stops generating STROBE edges $t_{\rm RFS}$ after the

negation of DMARDY. Both STROBE and DMARDY timing measurements are taken at the connector of the sender.



Note: The definitions for the IDE_IOW[0:1]# (STOP[0:1]), IDE_IOR[0:1]# (HDMARDY[0:1]#) and IDE_IRDY[0:1] (DSTROBE[0:1]) signal lines are not in effect until IDE_REQ[0:1] and IDE_DACK[0:1]# are asserted.

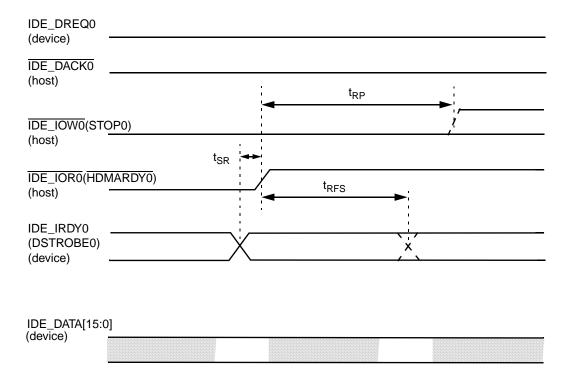
Figure 9-27. Initiating an UltraDMA Data in Burst Timing Diagram



Note: IDE_DATA[15:0] and IDE_IRDY[0:1] (DSTROBE[0:1]) signals are shown at both the host and the device to emphasize that cable settling time and cable propagation delay do not allow the data signals to be considered stable at the host until a certain amount of time after they are driven by the device.

Figure 9-28. Sustained UltraDMA Data In Burst Timing Diagram

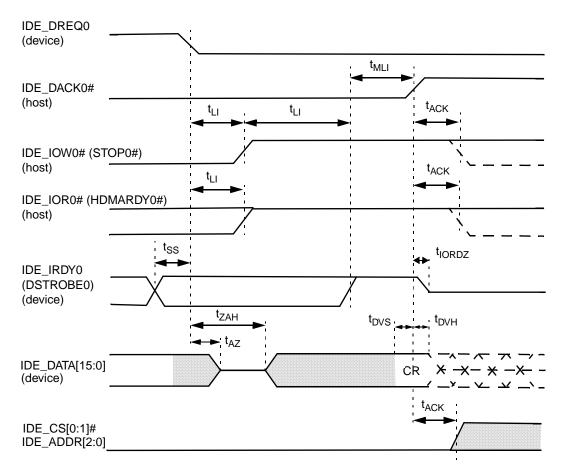
Revision 5.1



Notes:

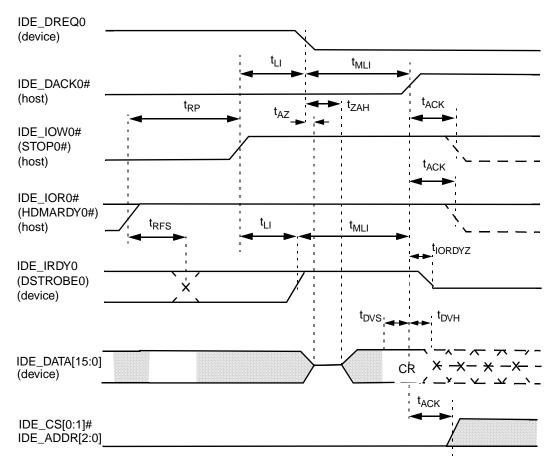
- 1) The host can assert IDE_IOW[0:1]# (STOP[0:1]#) to request termination of the UltraDMA burst no sooner than t_{RP} after IDE_IOR[0:1]# (HDMARDY[0:1]#) is de-asserted.
- 2) If the t_{SR} timing is not satisfied, the host may receive up to two additional data WORDs from the device.

Figure 9-29. Host Pausing an UltraDMA Data In Burst Timing Diagram



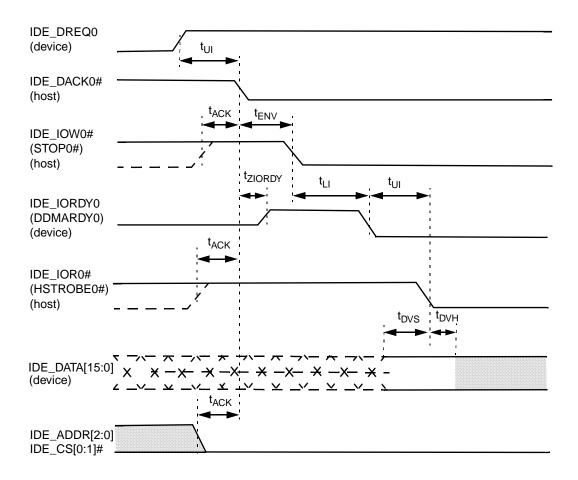
Note: The definitions for the IDE_IOW[0:1]# (STOP[0:1]#), IDE_IOR[0:1]# (HDMARDY[0:1]#), and IDE_IRDY[0:1] (DSTROBE[0:1]) signal lines are no longer in effect after IDE_DREQ[0:1] and IDE_DACK[0:1]# are de-asserted.

Figure 9-30. Device Terminating an UltraDMA Data In Burst Timing Diagram



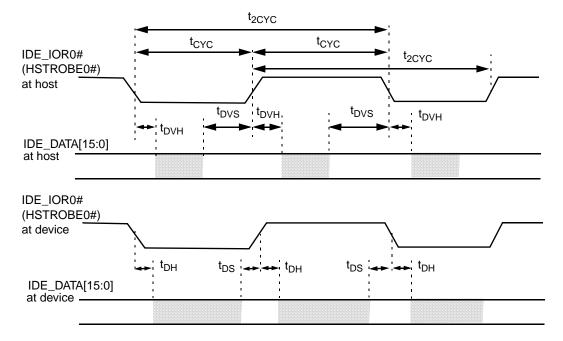
Note: The definitions for the IDE_IOW[0:1]# (STOP[0:1]#), IDE_IOR[0:1]# (HDMARDY[0:1]#), and IDE_IRDY[0:1] (DSTROBE[0:1]) signal lines are no longer in effect after IDE_DREQ[0:1] and IDE_DACK[0:1] are de-asserted.

Figure 9-31. Host Terminating an UltraDMA Data In Burst Timing Diagram



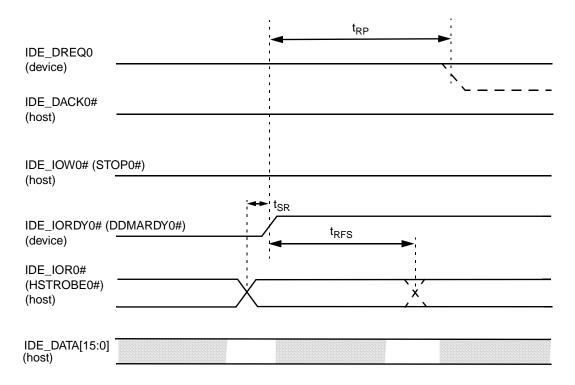
Note: The definitions for the IDE_IOW[0:1]# (STOP[0:1]#), IDE_IORDY[0:1]# (DDMARDY[0:1]) and IDE_IOR[0:1]# (HSTROBE[0:1]#) signal lines are not in effect until IDE_DREQ[0:1] and IDE_DACK[0:1]# are asserted.

Figure 9-32. Initiating an UltraDMA Data Out Burst Timing Diagram



Note: IDE_DATA[15:0] and IDE_IOR[0:1]# (HSTROBE[0:1]#) signals are shown at both the device and the host to emphasize that cable settling time and cable propagation delay do not allow the data signals to be considered stable at the device until a certain amount of time after they are driven by the device.

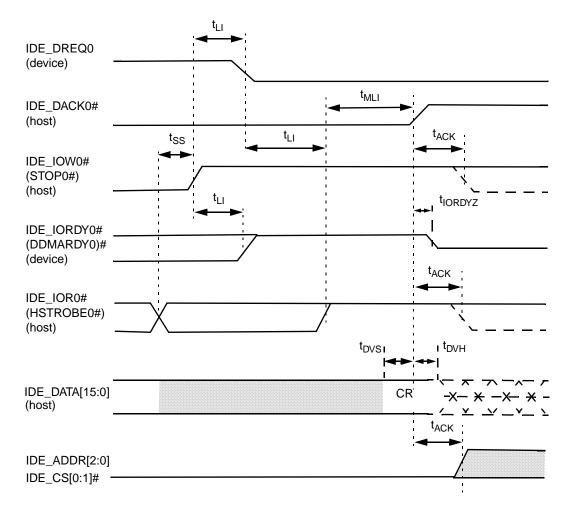
Figure 9-33. Sustained UltraDMA Data Out Burst Timing Diagram



Notes:

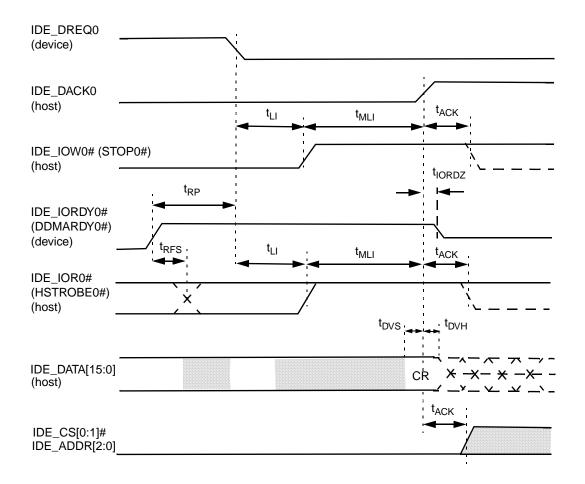
- 1) The device can de-assert IDE_DREQ[0:1] to request termination of the UltraDMA burst no sooner than t_{RP} after IDE_IORDY[0:1]# (DDMARDY[0:1]#) is de-asserted.
- 2) If the t_{SR} timing is not satisfied, the device may receive up to two additional datawords from the host.

Figure 9-34. Device Pausing an UltraDMA Data Out Burst Timing Diagram



Note: The definitions for the IDE_IOW[0:1]# (STOP[0:1]#), IDE_IORDY[0,1]# (DDMARDY[0:1]#) and IDE_IOR[0:1]# (HSTROBE[0:1]#) signal lines are no longer in effect after IDE_DREQ[0:1] and IDE_DACK[0:1]# are de-asserted.

Figure 9-35. Host Terminating an UltraDMA Data Out Burst Timing Diagram



Note: The definitions for the IDE_IOW[0:1]# (STOP[0:1]#), IDE_IORDY[0:1]# (DDMARDY[0:1]#) and IDE_IOR[0:1]# (HSTROBE[0:1]#) signal lines are no longer in effect after IDE_DREQ[0:1] and IDE_DACK[0:1]# are de-asserted.

Figure 9-36. Device Terminating an UltraDMA Data Out Burst Timing Diagram



9.3.9 Universal Serial Bus (USB) Interface

Table 9-28. USB Timing Parameters

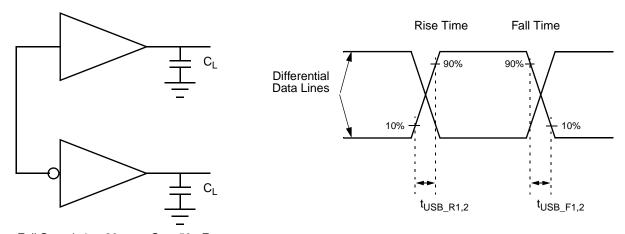
Symbol	Parameter	Min	Max	Unit	Figure	Comments
Full Speed	Source (Note 1, Note 2)				I	
t _{USB_R1}	DPOS_Port1,2,3, DNEG_Port1,2,3 Driver Rise Time	4	20	ns	9-37	(Monotonic) from 10% to 90% of the D_Port lines
t _{USB_F1}	DPOS_Port1,2,3, DNEG_Port1,2,3 Driver Fall Time	4	20	ns	9-37	(Monotonic) from 90% to 10% of the D_Port lines
t _{USB_FRFM}	Rise/Fall time matching	90	110	%		
t _{USB_FSDR}	Full-speed data rate	11.97	12.03	Mbps		Average bit rate 12 Mbps ± 0.25%
t _{USB_FSF}	Full-speed frame interval	0.9995	1.0005	ms		1.0 ms \pm 0.05%
t _{period_F}	Full-speed period between data bits	83.1	83.5	ns		Average bit rate 12 Mbps
t _{USB DOR}	Driver-output resistance	28	43	W		Steady-state drive
t _{USB_DJ11}	Source differential driver jitter for consecutive transition	-3.5	3.5	ns	9-38	Note 3, Note 4
t _{USB_DJ12}	Source differential driver jitter for paired transitions	-4.0	4.0	ns	9-38	Note 3, Note 4
t _{USB_SE1}	Source EOP width	160	175	ns	9-38	Note 4, Note 5
t _{USB_DE1}	Differential to EOP transition skew	-2	5	ns	9-39	Note 4, Note 5
t _{USB_RJ11}	Receiver data jitter tolerance for consecutive transition	-18.5	18.5	ns	9-40	Note 4
t _{USB_RJ12}	Receiver data jitter tolerance for paired transitions	- 9	9	ns	9-40	Note 4
Full Speed	Receiver EOP Width (Note 4)				•	
t _{USB_RE11}	Must reject as EOP		40	ns	9-39	Note 5
t _{USB_RE12}	Must accept as EOP	82		ns	9-39	Note 5
Low Speed	Source (Note 1)		1			
t _{USB_R2}	DPOS_Port1,2,3, DNEG_Port1,2,3 Driver Rise Time	75	300 (Note 6)	ns	9-37	(Monotonic) from 10% to 90% of the D_Port lines
t _{USB_F2}	DPOS_Port1,2,3, DNEG_Port1,2,3 Driver Fall Time	75	300 (Note 6)	ns	9-37	(Monotonic) from 90% to 10% of the D_Port lines
t _{USB_LRFM}	Low-speed Rise/Fall time matching	80	120	%		
t _{USB_LSDR}	Low-speed data rate	1.4775	1.5225	Mbps		Average bit rate 1.5 Mbps ± 1.5%
t _{PERIOD_L}	Low-speed period	0.657	0.677	μS		at 1.5 Mbps
t _{USB_DJD21}	Source differential driver jitter for consecutive transactions	- 75	75	ns		Host (downstream), Note 4
t _{USB_DJD22}	Source differential driver jitter for paired transactions	– 45	45	ns	9-38	Host (downstream), Note 4
t _{USB_DJU21}	Source differential driver jitter for consecutive transaction	-95	95	ns	9-38	Function (downstream), Note 4

Table 9-28. USB Timing Parameters (Continued)

Symbol	Parameter	Min	Max	Unit	Figure	Comments		
t _{USB_DJU22}	Source differential driver jitter for paired transactions	-150	150	ns	9-38	Function (downstream), Note 4		
t _{USB_SE2}	Source EOP width	1.25	1.5	μS	9-39	Note 4, Note 5		
t _{USB_DE2}	Differential to EOP transition skew	-40	100	ns	9-39	Note 5		
t _{USB_RJD21}	Receiver data jitter tolerance for consecutive transactions	-152	152	ns	9-40	Host (upstream), Note 4		
t _{USB_RJD22}	Receiver data jitter tolerance for paired transactions	-200	200	ns	9-40	Host (upstream), Note 4		
t _{USB_RJU21}	Receiver data jitter tolerance for consecutive transactions	-75	75	ns	9-40	Function (downstream), Note 4		
t _{USB_RJU22}	Receiver data jitter tolerance for paired transactions	-4 5	45	ns	9-40	Function (downstream), Note 4		
Low Speed Receiver EOP Width (Note 5)								
t _{USB_RE21}	Must reject as EOP		330	ns	9-38			
t _{USB_RE22}	Must accept as EOP	675		ns	9-38			

- Note 1. Unless otherwise specified, all timings use a 50 pF capacitive load (C_L) to ground.
- Note 2. Full-speed timing has a 1.5 K Ω pull-up to 2.8 V on the DPOS_Port1,2,3 lines.
- Note 3. Timing difference between the differential data signals (DPOS_PORT1,2,3 and DNEG_PORT1,2,3).
- Note 4. Measured at the crossover point of differential data signals (DPOS_PORT1,2,3 and DNEG_PORT1,2,3).
- Note 5. EOP is the End of Packet where DPOS_PORT^t = DNEG_PORT = SE0. SE0 occurs when output level voltage \leq V_{SE} (Min).

Note 6. $C_L = 350 \text{ pF}.$



Full Speed: 4 to 20 ns at C_L = 50 pF Low Speed: 75 ns at C_L = 50 pF, 300 ns at C_L = 350 pF

Figure 9-37. Data Signal Rise and Fall Timing Diagram

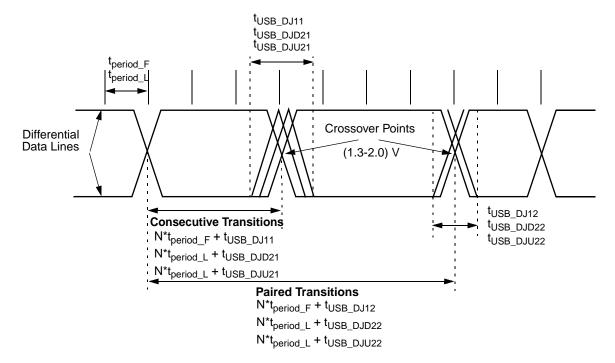


Figure 9-38. Source Differential Data Jitter Timing Diagram

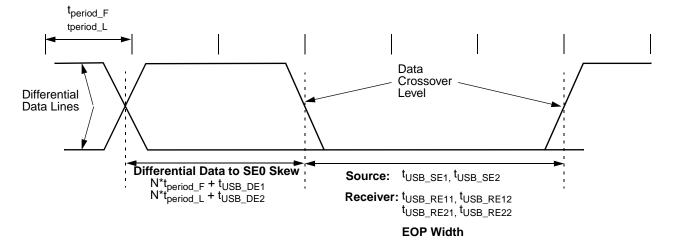


Figure 9-39. EOP Width Timing Diagram

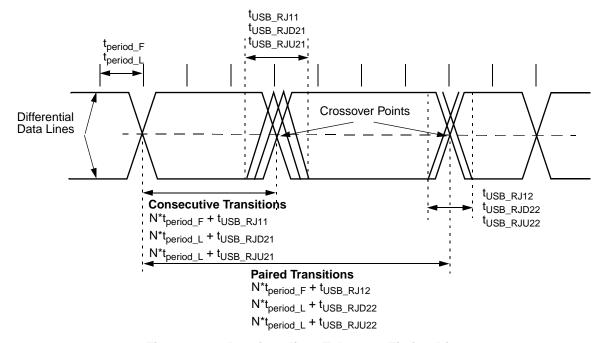


Figure 9-40. Receiver Jitter Tolerance Timing Diagram

9.3.10 Serial Port (UART)

Table 9-29. UART, Sharp-IR, SIR, and Consumer Remote Control Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t _{BT}	Single bit time in UART and Sharp-IR	t _{BTN} - 25 (Note 1)	t _{BTN} + 25	ns	Transmitter
		t _{BTN} - 2%	t _{BTN} + 2%	ns	Receiver
t _{CMW}	Modulation signal pulse width in Sharp-IR and Consumer	t _{CWN} - 25 (Note 2)	t _{CWN} + 25	ns	Transmitter
	Remote Control	500		ns	Receiver
Sharp-IR and Consumer (No		t _{CPN} - 25 (Note 3)	t _{CPN} + 25	ns	Transmitter
	Remote Control	t _{MMIN} (Note 4)	t _{MMAX} (Note 4)	ns	Receiver
t _{SPW}	SIR signal pulse width	(³ / ₁₆) x t _{BTN} - 15 (Note 1)	(³ / ₁₆) x t _{BTN} + 15 (Note 1)	ns	Transmitter, Variable
		1.48	1.78	μs	Transmitter, Fixed
		1		μs	Receiver
S _{DRT}	SIR data rate tolerance % of		± 0.87%		Transmitter
	nominal data rate		± 2.0%		Receiver
t _{SJT}	SIR leading edge jitter % of		± 2.5%		Transmitter
	nominal bit duration		± 6.5%		Receiver

- Note 1. t_{BTN} is the nominal bit time in UART, Sharp-IR, SIR and Consumer Remote Control modes. It is determined by the setting of the Baud Generator Divisor registers.
- Note 2. t_{CWN} is the nominal pulse width of the modulation signal for Sharp-IR and Consumer Remote Control modes. It is determined by the MCPW field (bits [7:5]) of the IRTXMC register and the TXHSC bit (bit 2) of the RCCFG register.
- Note 3. t_{CPN} is the nominal period of the modulation signal for Sharp-IR and Consumer Remote Control modes. It is determined by the MCFR field (bits [4:0]) of the IRTXMC registerand the TXHSC bit (bit 2) of the RCCFG register.
- Note 4. t_{MMIN} and t_{MMAX} define the time range within which the period of the incoming subcarrier signal has to fall in order for the signal to be accepted by the receiver. These time values are determined by the contents of register IRRXDC and the setting of the RXHSC bit (bit 5) of the RCCFG register.

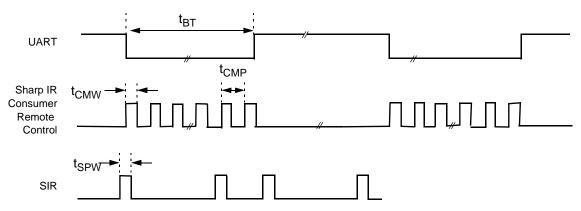


Figure 9-41. UART, Sharp-IR, SIR, and Consumer Remote Control Timing Diagram

9.3.11 Fast IR Port

Table 9-30. Fast IR Port Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t _{MPW}	MIR signal pulse width	t _{MWN} -25 (Note 1)	t _{MWN} +25	ns	Transmitter
		60		ns	Receiver
M _{DRT}	MIR transmitter data rate tolerance		± 0.1%		
t _{MJT}	MIR receiver edge jitter, % of nominal bit duration		± 2.9%		
t _{FPW}	FIR signal pulse width	120	130	ns	Transmitter
		90	160	ns	Receiver
t _{FDPW}	FIR signal double pulse width	245	255	ns	Transmitter
		215	285	ns	Receiver
F _{DRT}	FIR transmitter data rate tolerance		± 0.01%		
t _{FJT}	FIR receiver edge jitter, % of nominal bit duration		± 4.0%		

Note 1. t_{MWN} is the nominal pulse width for MIR mode. It is determined by the M_PWID field (bits [4:0]) in the MIR_PW register at offset 01h in bank 6 of logical device 5.

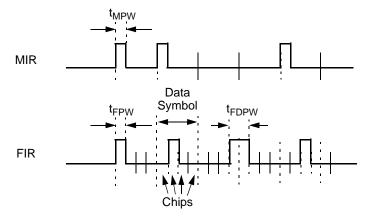


Figure 9-42. Fast IR (MIR and FIR) Timing Diagram

AMD Revision 5.1 Electrical Specifications

9.3.12 Parallel Port Interface

Table 9-31. Standard Parallel Port Timing Parameters

Symbol	Parameter	Min	Тур	Max	Unit	Comments
t _{PDH}	Port data hold		500		ns	Note 1
t _{PDS}	Port data setup		500		ns	Note 1
t _{SW}	Strobe width		500		ns	Note 1

Note 1. Times are system dependent and are therefore not tested.

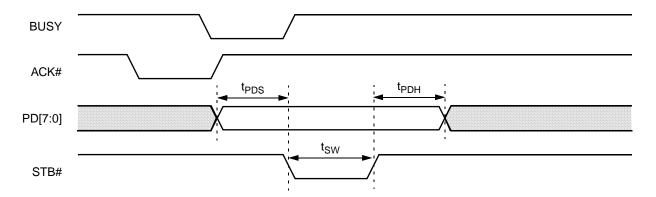


Figure 9-43. Standard Parallel Port Typical Data Exchange Timing Diagram

Table 9-32. Enhanced Parallel Port Timing Parameters

Symbol	Parameter	Min	Max	EPP 1.7	EPP 1.9	Unit	Comments
t _{WW19a}	WRITE# active from WAIT# low		45		Х	ns	
t _{WW19ia}	WRITE# inactive from WAIT# low		45		Х	ns	
t _{WST19a}	DSTRB# or ASTRB# active from WAIT# low		65		х	ns	
t _{WEST}	DSTRB# or ASTRB# active after WRITE# active	10		х	х	ns	
t _{WPDH}	PD[7:0] hold after WRITE# inactive	0		х	х	ns	
t _{WPDS}	PD[7:0] valid after WRITE# active		15	х	х	ns	
t _{EPDW}	PD[7:0] valid width	80		Х	Х	ns	
t _{EPDH}	PD[7:0] hold after DSTRB# or ASTRB# inactive	0		х	х	ns	

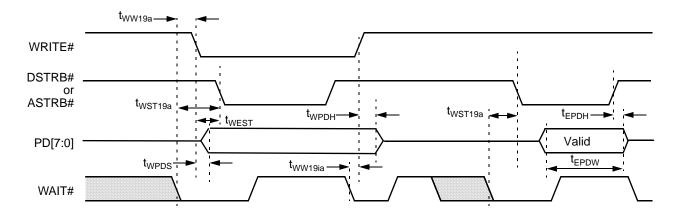


Figure 9-44. Enhanced Parallel Port Timing Diagram

AMD Revision 5.1 Electrical Specifications

9.3.12.1 Extended Capabilities Port (ECP)

Table 9-33. ECP Forward Mode Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t _{ECDSF}	Data setup before STB# active	0		ns	
t _{ECDHF}	Data hold after BUSY inactive	0		ns	
t _{ECLHF}	BUSY active after STB# active	75		ns	
t _{ECHHF}	STB# inactive after BUSY active	0	1	s	
t _{ECHLF}	BUSY inactive after STB# active	0	35	ms	
t _{ECLLF}	STB# active after BUSY inactive	0		ns	

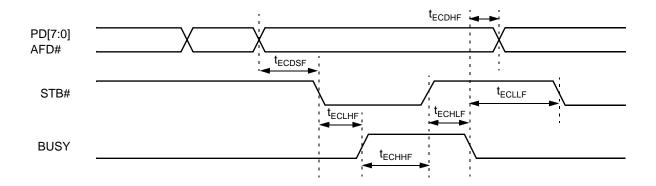


Figure 9-45. ECP Forward Mode Timing Diagram

Table 9-34.	ECP	Reverse	Mode	Timing	Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t _{ECDSR}	Data setup before ACK# active	0		ns	
t _{ECDHR}	Data hold after AFD# active	0		ns	
t _{ECLHR}	AFD# inactive after ACK# active	75		ns	
t _{ECHHR}	ACK# inactive after AFD# inactive	0	35	ms	
t _{ECHLR}	AFD# active after ACK# inactive	0	1	s	
t _{ECLLR}	ACK# active after AFD# active	0		ns	

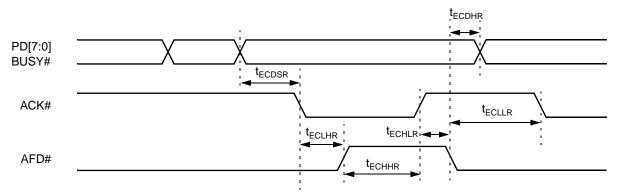


Figure 9-46. ECP Reverse Mode Timing Diagram

9.3.13 Audio Interface (AC97)

Table 9-35. AC Reset Timing Parameters

Symbol	Parameter	Min	Тур	Max	Unit	Comments
t _{RST_LOW}	AC97_RST# active low pulse width	1.0			μs	
t _{RST2CLK}	AC97_RST# inactive to BIT_CLK startup delay	162.8			ns	

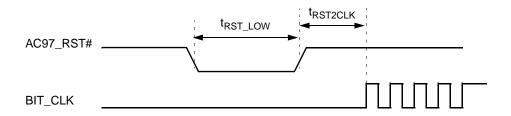


Figure 9-47. AC97 Reset Timing Diagram

Table 9-36. AC97 Sync Timing Parameters

Symbol	Parameter	Min	Тур	Max	Unit	Comments
t _{SYNC_HIGH}	SYNC active high pulse width		1.3		μs	
t _{SYNC_IA}	SYNC inactive to BIT_CLK startup delay	162.8			ns	

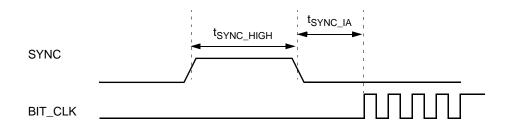


Figure 9-48. AC97 Sync Timing Diagram

Table 9-37.	AC97	Clocks	Parameters
-------------	------	--------	-------------------

Symbol	Parameter	Min	Тур	Max	Unit	Comments
F _{BIT_CLK}	BIT_CLK frequency		12.288		MHz	
t _{CLK_PD}	BIT_CLK period		81.4		ns	
t _{CLK_J}	BIT_CLK output jitter			750	ps	
t _{CLK_H}	BIT_CLK high pulse width	32.56	40.7	48.84	ns	Note 1
t _{CLK_L}	BIT_CLK low pulse width	32.56	40.7	48.84	ns	Note 1
F _{SYNC}	SYNC frequency		48.0		KHz	
t _{SYNC_PD}	SYNC period		20.8		μs	
t _{SYNC_H}	SYNC high pulse width		1.3		μs	
t _{SYNC_L}	SYNC low pulse width		19.5		μs	
F _{AC97_CLK}	AC97_CLK frequency		24.576		MHz	
t _{AC97_CLK_PD}	AC97_CLK period		40.7		ns	
t _{AC97_CLK_D}	AC97_CLK duty cycle	45		55	%	
t _{AC97_CLK_FR}	AC97_CLK fall/rise time	2		5	ns	
t _{AC97_CLK_} J	AC97_CLK output edge-to- edge jitter			100	ps	Measured from edge to edge

Note 1. Worst case duty cycle restricted to 40/60.

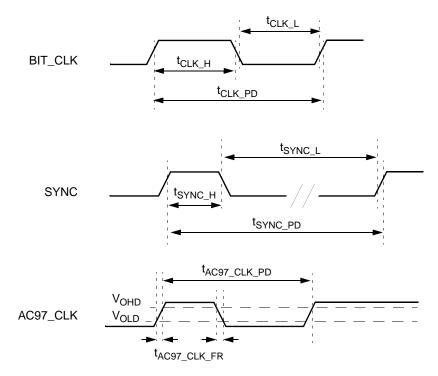


Figure 9-49. AC97 Clocks Diagram

Table 9-38. AC97 I/O Timing Parameters

Symbol	Parameter	Min	Тур	Max	Unit	Comments
t _{AC97_S}	Input setup to falling edge of BIT_CLK	15.0			ns	
t _{AC97_H}	Hold from falling edge of BIT_CLK	10.0			ns	
t _{AC97_OV}	SDATA_OUT or SYNC valid after rising edge of BIT_CLK			15	ns	
t _{AC97_OH}	SDATA_OUT or SYNC hold time after falling edge of BIT_CLK	5			ns	
t _{AC97_SV}	Sync out valid after rising edge of BIT_CLK			15	ns	
t _{AC97_SH}	Sync out hold after falling edge of BIT_CLK	5			ns	

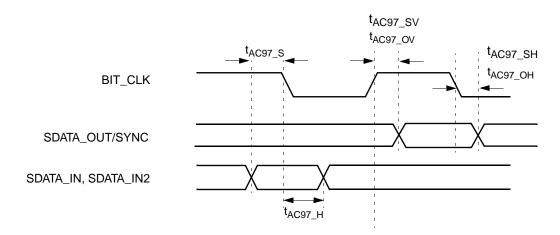


Figure 9-50. AC97 Data TIming Diagram

Symbol	Parameter	Min	Тур	Max	Unit	Comments
trise _{CLK}	BIT_CLK rise time	2		6	ns	
tfall _{CLK}	BIT_CLK fall time	2		6	ns	
trise _{SYNC}	SYNC rise time	2		6	ns	C _L = 50 pF
tfall _{SYNC}	SYNC fall time	2		6	ns	C _L = 50 pF
trise _{DIN}	SDATA_IN rise time	2		6	ns	
tfall _{DIN}	SDATA_IN fall time	2		6	ns	
trise _{DOUT}	SDATA_OUT rise time	2		6	ns	C _L = 50 pF
tfall _{DOUT}	SDATA_OUT fall time	2		6	ns	C _L = 50 pF

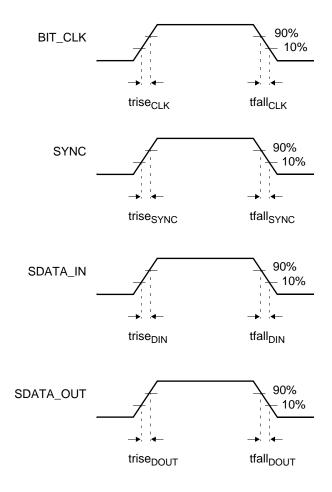
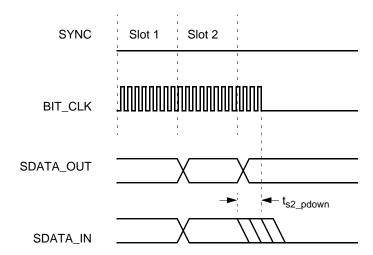


Figure 9-51. AC97 Rise and Fall Timing Diagram

AMD7 Revision 5.1 Electrical Specifications

Table 9-40. AC97 Low Power Mode Timing Parameters

Symbol	Parameter	Min	Тур	Max	Unit	Comments
t _{s2_pdown}	End of Slot 2 to BIT_CLK, SDATA_IN low			1.0	μs	



Note: BIT_CLK is not to scale

Figure 9-52. AC97 Low Power Mode Timing Diagram

Electrical Specifications Revision 5.1

9.3.14 Power Management Interface

LED# Cycle time: 1 s \pm 0.1 s, 40%-60% duty cycle.

Table 9-41. PWRBTN# Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t _{PBTNP}	PWRBTN# pulse width	16		ms	Note 1
t _{PBTNE}	Delay from PWRBTN# events to ONCTL#	14	16	ms	

Note 1. Not 100% tested.

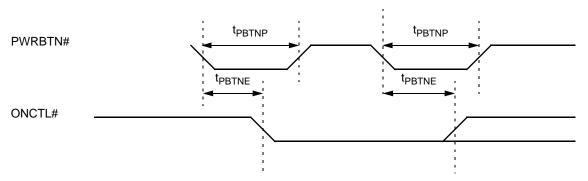


Figure 9-53. PWRBTN# Trigger and ONCTL# Timing Diagram

Table 9-42. Power Management Event (GPWIO) and ONCTL# Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t _{PM}	Power management event to ONCTL# assertion		45	ns	

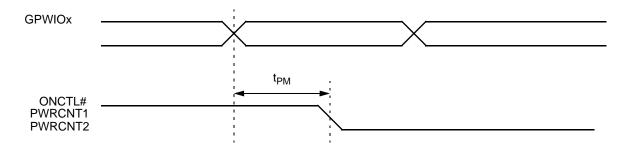


Figure 9-54. GPWIO and ONCTL# Timing Diagram



9.3.15 Power-Up Sequencing

Table 9-43. Power-Up Sequence Using the Power Button Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
t ₁	Voltage sequence	-100	100	ms	Optimum power-up results with $t_1 = 0$.
t ₂	PWRBTN# inactive after V _{SB} or V _{SBL} applied, whichever is applied last	0	1	μs	PWRBTN# is an input and must be powered by V _{SB} .
t ₃	PWRBTN# active pulse width	16	4000	ms	If PWRBTN# max is exceeded, ONCTL# will go inactive.
t ₄	ONCTL# inactive after V _{SB} applied	0	1	ms	
t ₅	Signal active after PWRBTN active	14	16	ms	
t ₆	V _{CORE} and V _{IO} applied after ONCTL# active	0		ms	System determines when V _{CORE} and V _{IO} are applied, hence there is no maximum constraint.
t ₇	POR# inactive after V _{CORE} and V _{IO} applied	50		ms	POR# must not glitch during active time.

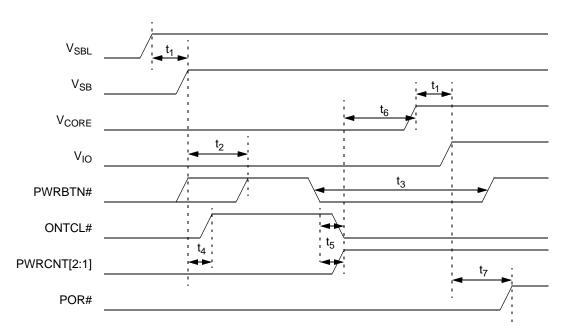
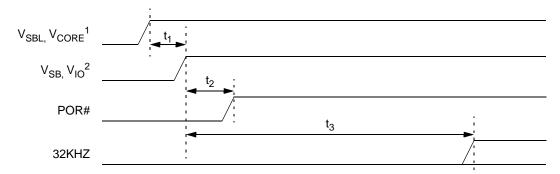


Figure 9-55. Power-Up Sequencing With PWRBTN# Timing Diagram

Electrical Specifications Revision 5.1

Symbol	Parameter	Min	Max	Unit	Comments
t ₁	Voltage sequence	-100	100	ms	Optimum power-up results with $t_1 = 0$.
t ₂	POR# inactive after V_{SBL} , V_{CORE} , V_{SB} , and V_{IO} applied	50		ms	POR# must not glitch during active time.
t ₃	32KHZ startup time		1	S	Time required for 32 KHz oscillator and 14.318 MHz derived from PLL6 to become stable at which time the RTC can reliably count.



- 1) V_{SBL} and V_{CORE} should be tied together.
- 2) V_{SB} and V_{IO} should be tied together.

Figure 9-56. Power-Up Sequencing Without PWRBTN# Timing Diagram

ACPI is non-functional and all ACPI outputs are undefined when the power-up sequence does not include using the power button. SUSP# is an internal signal generated from the ACPI block. Without an ACPI reset, SUSP# can be permanently asserted. If the USE_SUSP bit in CCR2 of GX1 module is enabled (Index C2h[7] = 1), the CPU will stop.

If ACPI functionality is desired, or the situation described above avoided, the power button must be toggled. This can be done externally or internally. GPIO63 is internally connected to PWRBTN#. To toggle the power button with software, GPIO63 must be programmed as an output using the normal GPIO programming protocol (see Section 6.4.1.1 "GPIO Support Registers" on page 240). GPIO63 must be pulsed low for at least 16 ms and not more than 4 sec.

Asserting POR# has no effect on ACPI. If POR# is asserted and ACPI was active prior to POR#, then ACPI will remain active after POR#. Therefore, BIOS must ensure that ACPI is inactive before GPIO63 is pulsed low.

9.3.16 JTAG Interface

Table 9-45. JTAG Timing Parameters

Symbol	Parameter	Min	Max	Unit	Comments
	TCK frequency		25	MHz	
t ₁	TCK period	40		ns	
t ₂	TCK high time	10		ns	
t ₃	TCK low time	10		ns	
t ₄	TCK rise time		4	ns	
t ₅	TCK fall time		4	ns	
t ₆	TDO valid delay	3	25	ns	
t ₇	Non-test outputs valid delay	3	25	ns	50 pF load
t ₈	TDO float delay		30	ns	
t ₉	Non-test outputs float delay		36	ns	
t ₁₀	TDI, TMS setup time	8		ns	
t ₁₁	Non-test inputs setup time	8		ns	
t ₁₂	TDI, TMS hold time	7		ns	
t ₁₃	Non-test inputs hold time	7		ns	

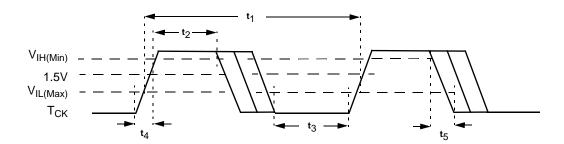


Figure 9-57. TCK Measurement Points and Timing Diagram

Electrical Specifications Revision 5.1

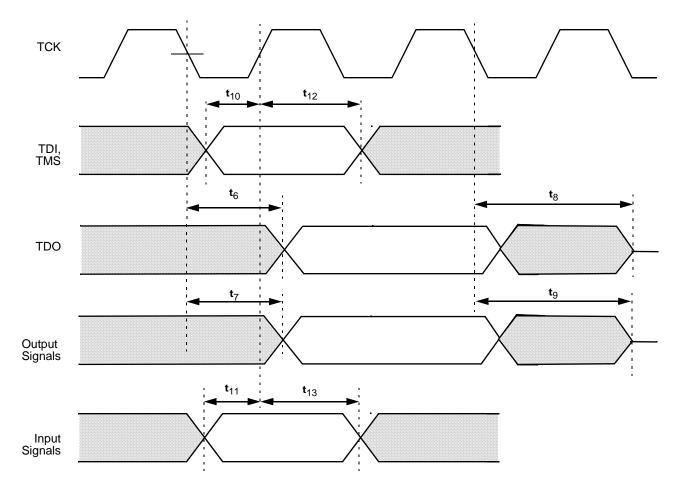


Figure 9-58. JTAG Test Timing Diagram

Package Specifications Revision 5.1 AMD

Package Specifications

10.1 Thermal Characteristics

The junction-to-case thermal resistance (θ_{JC}) of the packages shown in Table 10-1 can be used to calculate the junction (die) temperature under any given circumstance.

Table 10-1. θ_{JC} (xC/W)

Package	Max (°C/W)
EBGA	1
TEPBGA	5

Note that there is no specification for maximum junction temperature given since the operation of the device is guaranteed to a case temperature range of 0°C to 85°C (see Table 9-3 on page 370). As long as the case temperature of the device is maintained within this range, the junction temperature of the die will also be maintained within its allowable operating range. However, the die (junction) temperature under a given operating condition can be calculated by using the following equation:

$$T_{J} = T_{C} + (P * \theta_{JC})$$

where:

 $T_{.I}$ = Junction temperature (°C)

T_C = Case temperature at top center of package (°C)

P = Maximum power dissipation (W)

 θ_{JC} = Junction-to-case thermal resistance (°C/W)

These examples are given for reference only. The actual value used for maximum power (P) and ambient temperature (T_A) is determined by the system designer based on system configuration, extremes of the operating environment, and whether active thermal management (via Suspend Modulation) of the GX1 module is employed.

A maximum junction temperature is not specified since a maximum case temperature is. Therefore, the following equation can be used to calculate the maximum thermal resistance required of the thermal solution for a given maximum ambient temperature:

$$\theta_{CS} + \theta_{SA} = \frac{T_C - T_A}{P}$$

where:

 θ_{CS} = Max case-to-heatsink thermal resistance (°C/W) allowed for thermal solution

 θ_{SA} = Max heatsink-to-ambient thermal resistance (°C/W) allowed for thermal solution

 $T_A = Max ambient temperature (°C)$

T_C = Max case temperature at top center of package (°C)

P = Maximum power dissipation (W)

If thermal grease is used between the case and heatsink, θ_{CS} will reduce to about 0.01 °C/W. Therefore, the above equation can be simplified to:

$$\theta_{CA} = \frac{T_C - T_A}{P}$$

where:

 $\theta_{CA}=\theta_{SA}=$ Max heatsink-to-ambient thermal resistance (°C/W) allowed for thermal solution

The calculated θ_{CA} value (examples shown in Table 10-2) represents the maximum allowed thermal resistance of the selected cooling solution which is required to maintain the maximum T_{CASE} (shown in Table 9-3 on page 370) for the application in which the device is used.

Table 10-2. Case-to-Ambient Thermal Resistance Example @ 85°C

Core Voltage (V _{CORE})	Coro	Marrimorra	θся	for Different	Ambient Tem	peratures (°C	/W)
(Nominal)	Core Frequency	Maximum Power (W)	20°C	25°C	30°C	35°C	40°C
1.8V	266 MHz	3.32	19.58	18.07	16.57	15.06	13.55

10.1.1 Heatsink Considerations

Table 10-2 on page 439 shows the maximum allowed thermal resistance of a heatsink for particular operating environments. The calculated values, defined as θ_{CA} , represent the required ability of a particular heatsink to transfer heat generated by the SC3200 processor from its case into the air, thereby maintaining the case temperature at or below 85°C. Because θ_{CA} is a measure of thermal resistivity, it is inversely proportional to the heatsinks ability to dissipate heat or its thermal conductivity.

Note: A "perfect" heatsink would be able to maintain a case temperature equal to that of the ambient air inside the system chassis.

Looking at Table 10-2, it can be seen that as ambient temperature (T_A) increases, θ_{CA} decreases, and that as power consumption of the processor (P) increases, θ_{CA} decreases. Thus, the ability of the heatsink to dissipate thermal energy must increase as the processor power increases and as the temperature inside the enclosure increases.

While θ_{CA} is a useful parameter to calculate, heatsinks are not typically specified in terms of a single θ_{CA} . This is because the thermal resistivity of a heatsink is not constant across power or temperature. In fact, heatsinks become slightly less efficient as the amount of heat they are trying to dissipate increases. For this reason, heatsinks are typically specified by graphs that plot heat dissipation (in watts) vs. mounting surface (case) temperature rise above ambient (in °C). This method is necessary because ambient and case temperatures fluctuate constantly during normal operation of the system. The system designer must be careful to choose the proper heatsink by matching the required θ_{CA} with the thermal dissipation curve of the device under the entire range of operating conditions in order to make sure that the maximum case temperature (from Table 9-3 on page 370) is never exceeded. To choose the proper heatsink, the system designer must make sure that the calculated θ_{CA} falls above the curve (shaded area). The curve itself defines the minimum temperature rise above ambient that the heatsink can main-

Figure 10-1 is an example of a particular heatsink under consideration

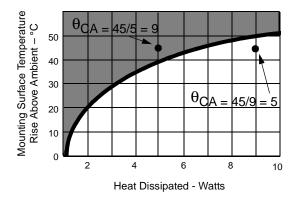


Figure 10-1. Heatsink Example

Example 1

Assume P (max) = 5W and T_A (max) = 40°C.

Therefore:

$$\theta_{CA} = \frac{T_C - T_A}{P}$$

$$\theta_{CA} = \frac{85 - 40}{5}$$

$$\theta_{CA} = 9$$

 $\theta_{CA} = 5$

The heatsink must provide a thermal resistance below 9°C/W . In this case, the heatsink under consideration is more than adequate since at 5W worst case, it can limit the case temperature rise above ambient to 40°C (θ_{CA} =8).

Example 2

Assume P (max) = 9W and T_A (max) = 40°C.

Therefore:

$$\theta_{CA} = \frac{T_C - T_A}{P}$$

$$\theta_{CA} = \frac{85 - 40}{9}$$

In this case, the heatsink under consideration is NOT adequate to limit the case temperature rise above ambient to 45°C for a 9W processor.

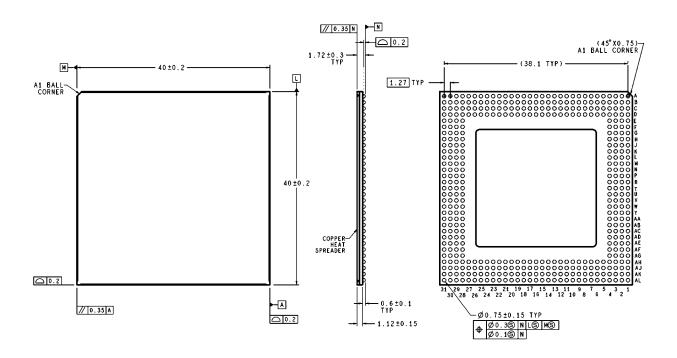
For more information on thermal design considerations or heatsink properties, refer to the Product Selection Guide of any leading vendor of thermal engineering solutions.

Note: The power dissipations P used in these examples are not representative of the power dissipation of the SC3200 processor, which is always less than 4 Watts.

Package Specifications Revision 5.1 AMD

10.2 Physical Dimensions

The figures in this section provide the mechanical package outlines for the 432-Terminal EBGA (Enhanced Ball Grid Array) and 481-Terminal TEPBGA (Thermally Enhanced Ball Grid Array) packages.



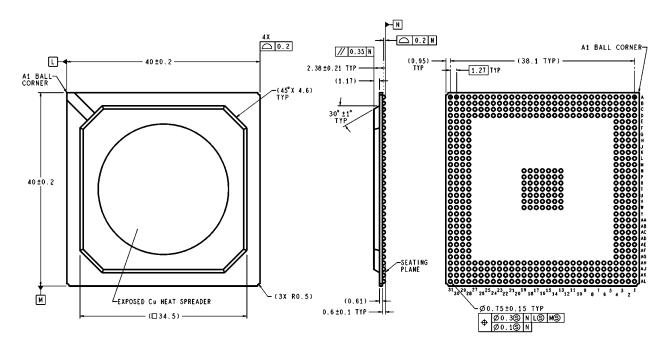
DIMENSIONS ARE IN MILLIMETERS

UCL432A (Rev 8)

NOTES: UNLESS OTHERWISE SPECIFIED.

- 1) EBGA WITH LEAD (PB):
 - a) SOLDER BALL COMPOSITION: SN 63%, PB 37%.
 - b) SOLDERING PROFILE: 220° C.
- 2) EBGA LEAD (PB) FREE:
 - a) SOLDER BALL COMPOSITION: SN 96.5%, AG 3.5%.
 - b) SOLDERING PROFILE: 260° C
- 3) DIMENSION IS MEASURED AT THE MAXIMUM SOLDER BALL DIAMETER, PARALLEL TO PRIMARY DATUM N.
- 4) REFERENCE JEDEC REGISTRATION MO-151, VARIATION -1.00, DATED JUNE 1997.
- 5) THETA JUNCTION TO CASE $(T_{JC}) = 1$ °C/WATT.

Figure 10-2. 432-Terminal EBGA Package (Body Size: 40x40x1.72 mm; Pitch: 1.27 mm)



DIMENSIONS ARE IN MILLIMETERS

UFH481A (Rev A)

NOTES: UNLESS OTHERWISE SPECIFIED.

- 1) TEPBGA WITH LEAD (PB):
 - a) SOLDER BALL COMPOSITION: SN 63%, PB 37%.
 - b) SOLDERING PROFILE: 220° C.
- 2) TEPBGA LEAD (PB) FREE:
 - a) SOLDER BALL COMPOSITION: SN 96.5%, AG 3.5%.
 - b) SOLDERING PROFILE: 260° C
- 3) DIMENSION IS MEASURED AT THE MAXIMUM SOLDER BALL DIAMETER, PARALLEL TO PRIMARY DATUM N.
- 4) THE MOLD SURFACE AREA MAY INCLUDE DIMPLE FOR A1 BALL CORNER IDENTIFICATION.
- 5) REFERENCE JEDEC REGISTRATION MS-034, VARIATION BAU-1.
- 6) THETA JUNCTION TO CASE $(T_{JC}) = 5$ °C/WATT.

Figure 10-3. 481-Terminal TEPBGA Package (Body Size: 40x40x2.38 mm; Pitch: 1.27 mm)

Support Documentation

A.1 Order Information

Order Number (AMD OPN) ¹	Core Frequency (MHz)	Core Voltage (V _{CORE})	Temp. (Degree C)	Package ²
SC3200UCL-266	266	1.8V	0 - 85	EBGA
SC3200UCL-266F				Lead Free EBGA
SC3200UFH-233	233	1.8V	0 - 85	TEPBGA
SC3200UFH-233F				Lead Free TEPBGA
SC3200UFH-266	266	1.8V	0 - 85	TEPBGA
SC3200UFH-266F				Lead Free TEPBGA

- 1. The "F" suffix denotes the lead free package.
- 2. As of this publication date, a lead free package version may not be available. Check with your local AMD Sales Representative for availability. See Section 10.0 "Package Specifications" on page 439 for details on the lead free part.

A.2 Data Book Revision History

This document is a report of the revision/creation process of the data book for the Geode SC3200. Any revisions (i.e., additions, deletions, parameter corrections, etc.) are recorded in the table below.

Table A-1. Revision History

Revision # (PDF Date)	Revisions / Comments
0.1 (August 1999)	First draft of data book. (For internal review only)
0.2 (October 1999)	Second draft.
0.5 (January 2000)	Draft.
0.8 (March 2000)	Draft
1.0 (July 2000)	Preliminary data book.
1.1 (August 2000)	Corrected typos, removed umimplemented features.
1.32 (February 2001)	Preliminary data book. GNT[1:0]# strapping functions changed. Minor modifications and corrections. Video Input Port (VIP) added.
2.0 (April 2002)	The entire data book has been reformatted and several sections re-written. Strap information and TEPBGA ball assignments have been added. Additionally, internal test signals and multiplexing have been included. This data book should be viewed as a new document.



Table A-1. Revision History (Continued)

Revision # (PDF Date)	Revisions / Comments
2.1 (June 2002)	Release for posting on external web site. Changes made to the Architecture Overview, Signal Definitions, Core Logic Module, Video Processor Module, Electrical Specifications, and Package Specifications chapters. See Revision 2.1 for details.
2.2 (July 2002)	Corrected pin definitions for ball K3 on EBGA package and ball D12 on TEPBGA package. Were incorrectly called out as VIO, changed to VCORE. Effected: Figure 2-2 "432-EBGA Ball Assignment Diagram" Table 2-2 "432-EBGA Ball Assignment - Sorted by Ball Number" Table 2-3 "432-EBGA Ball Assignment - Sorted Alphabetically by Signal Name" Figure 2-3 "481-TEPBGA Ball Assignment Diagram" Table 2-4 "481-TEPBGA Ball Assignment - Sorted by Ball Number" Table 2-5 "481-TEPBGA Ball Assignment - Sorted Alphabetically by Signal Name" Section 2.4.20 "Power, Ground and No Connections"
3.0 (August 2002)	Major corrections include fixing TEPBGA ball numbers in "Two-Signal/Group Multiplexing" table (Table 2-7) and GPIO signal descriptions (Table 2.4.16).
3.1 (February 2002)	Many minor changes mostly to the Video Processor and Electrical sections. Expounded on the notes in the Mechanical section.
4.0 (March 2003)	Many changes. Changed all references to XpressAUDIO to audio. See revision 4.0 for details.
5.0 (November 2003)	Numerous minor changes/corrections made based upon user inputs. See revision 5.0 for details.
5.1 (March 2004)	Minor changes/corrections made based upon user inputs. See Table A-2 "Edits to Current Revision" for details.



Table A-2. Edits to Current Revision

	Table A-2. Edits to Current Revision
Section	Revision
Section 1.0 "AMD Geode™ SC3200 Processor"	Section 1.2 "Features" on page 14: — Other Features: Modified Voltages sub-bullets for clarification purposes.
Section 2.0 "Architecture Overview"	No changes.
Section 3.0 "Signal Definitions"	 Section 3.4.6 "PCI Bus Interface Signals" on page 68: Rewrote SERR# description, was wrong. Section 3.4.10 "Universal Serial Bus (USB) Interface Signals" on page 76: Changed footnote to say "A 15 KΩ pull-down resistor is required on all ports (even if unused)."
Section 4.0 "General Configuration Block"	 Table 4-7 "Strapped Core Clock Frequency" on page 101: — Added note: "Note: Not all speeds are supported. For information on supported speeds, see Section A.1 "Order Information" on page 443."
Section 5.0 "SuperI/O Module"	No changes.
Section 6.0 "Core Logic Module"	 Section 6.2.6.1 "DMA Controller" on page 168: Added text in parenthesis to first bullet. Now reads as "Standard seven-channel DMA support (Channels 5 through 7 are not supported)." DMA Channels subsection: Added last sentence to last paragraph "DMA Channels 5 through 7 are not supported." Section 6.2.6.3 "Programmable Interrupt Controller" on page 171: Added second sentence to first paragraph, "The PIC devices support all x86 modes of operation except Special Fully Nested mode." Section 6.4.1 "Bridge, GPIO, and LPC Registers - Function 0" on page 206:
	 F0 Index 6Ch (ROM Mask Register): Corrected reset value to 0000FFF0h (was listed as FFF0h). Added note, "Note: Register must be read/written as a DWORD." Also corrected reset value and "Width" column in Table 6-14 on page 192 (register summary table). F0BAR1+I/O Offset 00h: Rewrote bit descriptions and added note for clarification purposes. F0BAR1+Offset 0Ch: Rewrote bit descriptions and added note for clarification purposes. F0BAR1+Offset 10h[13]: Changed note. Did say "This bit should not be enabled when using the internal SuperI/O module and if IO_SIOCFG_IN (F5BAR0+I/O Offset 00h[26:25]) = 11." Now says "This bit should not be routed to LPC when using the internal SuperI/O module and if IO_SIOCFG_IN (F5BAR0+I/O Offset 00h[26:25]) = 10."
	Section 6.4.2 "SMI Status and ACPI Registers - Function 1" on page 252: — F1BAR0+I/O Offset 00h[11] and Offset 02h[11]: Clarified that the IRQ2 is from the SIO module and not an external SIO.
	Section 6.4.3 "IDE Controller Registers - Function 2" on page 273: — F2 Index 40h and 44h: Removed Format 0 and Format 1 settings for a Fast-PCI clock frequency of 48 MHz since it is not supported.
	Section 6.4.7 "ISA Legacy Register Space" on page 313: — Changed register descriptions in Table 6-43 and Table 6-44 to emphasize that DMA Channels 5 through 7 are not supported.
Section 7.0 "Video Processor Module"	No changes.



Table A-2. Edits to Current Revision (Continued)

Section	Revision
Section 8.0 "Debugging and Monitoring"	No changes.
Section 9.0 "Electrical Specifications"	Table 9-2 "Absolute Maximum Ratings" on page 369: — Changed T _{CASE} Min value from -45°C to -10°C.
Section 10.0 "Package Specifications"	 Section 10.1 "Thermal Characteristics" on page 439: New section. Figure 10-3 "481-Terminal TEPBGA Package (Body Size: 40x40x2.38 mm; Pitch: 1.27 mm)" on page 442: Removed lot code example from figure.
Appendix A "Support Documentation"	Updated edits to reflect current revision.



www.amd.com

One AMD Place P.O. Box 3453, Sunnyvale, CA 94088-3453 USA Tel: 408-732-2400 or 800-538-8450 TWX: 910-339-9280 TELEX: 34-6306 TECHNICAL SUPPORT
USA & Canada: 800-222-9323 or 408-749-5703
USA & Canada: PC Microprocessor: 408-749-3060
USA & Canada Email: pcs.support@amd.com

Latin America Email: spanish.support@amd.com Argentina: 001-800-200-1111, after tone 800-859-4478 Chile: 800-532-853

Mexico: 95-800-222-9323

Europe & UK: +44-0-1276-803299 Fax: +44-0-1276-803298 France: 0800-908-621 Germany: +49-89-450-53199 Italy: 800-877224 Europe Email: euro.tech@amd.com

Far East Fax: 852-2956-0588 Japan Fax: 81-3-3346-7848