



ST24LC21B, ST24LW21 ST24FC21, ST24FC21B, ST24FW21

1 Kbit (x8) Dual Mode Serial EEPROM
for VESA PLUG & PLAY

- 1 MILLION ERASE/WRITE CYCLES
- 40 YEARS DATA RETENTION
- 3.6V to 5.5V or 2.5V to 5.5V SINGLE SUPPLY VOLTAGE
- HARDWARE WRITE CONTROL (ST24LW21 and ST24FW21)
- TTL SCHMITT-TRIGGER on VCLK INPUT
- 100k / 400k Hz COMPATIBILITY with the I²C BUS BIT TRANSFER RANGE
- TWO WIRE SERIAL INTERFACE I²C BUS COMPATIBLE
- I²C PAGE WRITE (up to 8 Bytes)
- I²C BYTE, RANDOM and SEQUENTIAL READ MODES
- SELF TIMED PROGRAMMING CYCLE
- AUTOMATIC ADDRESS INCREMENTING
- ENHANCED ESD/LATCH UP PERFORMANCES
- ERROR RECOVERY MECHANISM (ST24FC21 and ST24FW21) VESA 2 COMPATIBLE

DESCRIPTION

The ST24LC21B, ST24LW21, ST24FC21, ST24FC21B and ST24FW21 are 1K bit electrically erasable programmable memory (EEPROM), organized in 128x8 bits. In the text, products are referred as ST24xy21, where "x" is either "L" for VESA 1 or "F" for VESA 2 compatible memories and where "y" indicates the Write Control pin connection: "C" means WC on pin 7 and "W" means WC on pin 3.

Table 1. Signal Names

| | |
|-----------------|--------------------------------------|
| SDA | Serial Data Address Input/Output |
| SCL | Serial Clock (I ² C mode) |
| V _{CC} | Supply Voltage |
| V _{SS} | Ground |
| VCLK | Clock Transmit only mode |
| WC | Write Control |

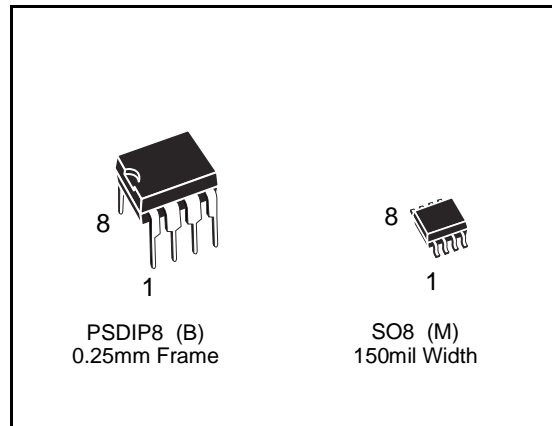
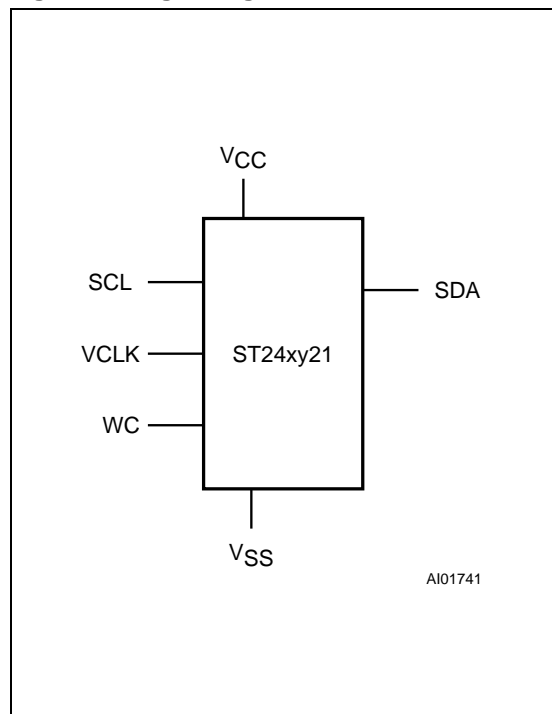


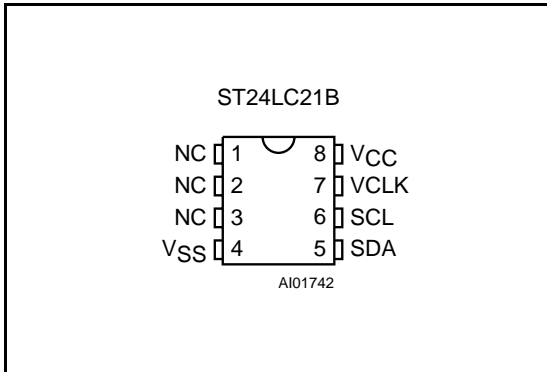
Figure 1. Logic Diagram



Note: WC signal is only available for ST24LW21 and ST24FW21 products.

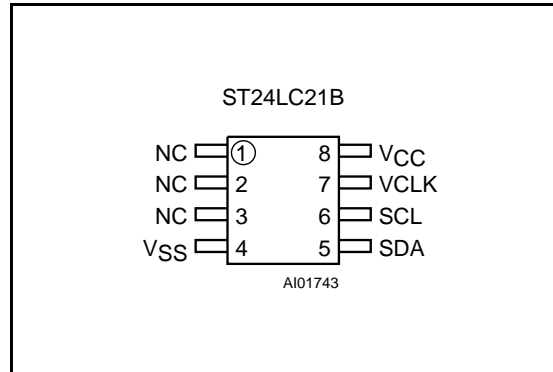
ST24LC21B, ST24LW21, ST24FC21, ST24FC21B, ST24FW21

Figure 2A. DIP Pin Connections



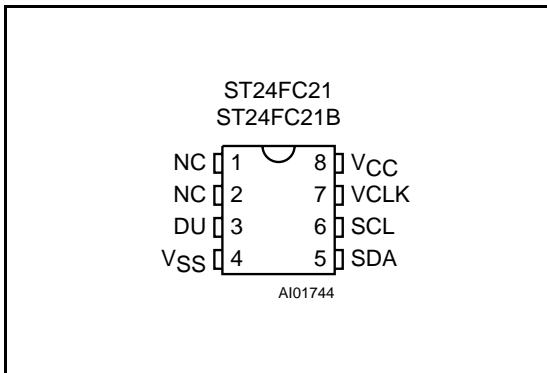
Warning: NC = Not Connected.

Figure 2B. SO Pin Connections



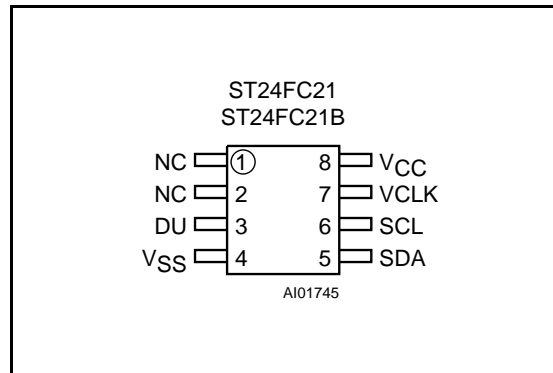
Warning: NC = Not Connected.

Figure 2C. DIP Pin Connections



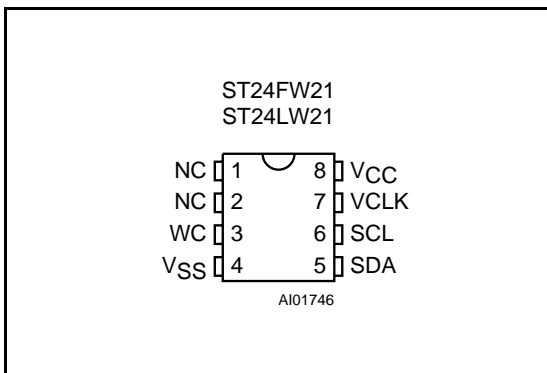
Warning: NC = Not Connected. DU = Don't Use, must be left open or connected to VCC or VSS.

Figure 2D. SO Pin Connections



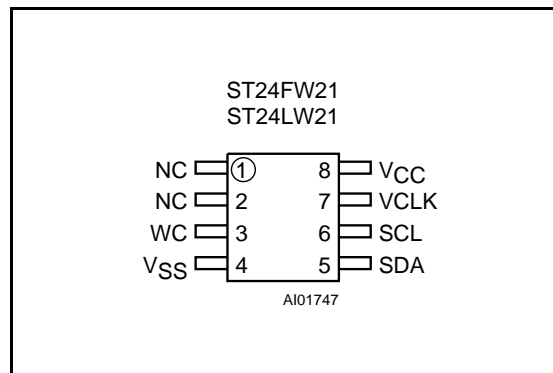
Warning: NC = Not Connected. DU = Don't Use, must be left open or connected to VCC or VSS.

Figure 2E. DIP Pin Connections



Warning: NC = Not Connected.

Figure 2F. SO Pin Connections



Warning: NC = Not Connected.

ST24LC21B, ST24LW21, ST24FC21, ST24FC21B, ST24FW21

Table 2. Absolute Maximum Ratings ⁽¹⁾

| Symbol | Parameter | Value | Unit |
|-------------------|--|-------------|------|
| T _A | Ambient Operating Temperature | -40 to 85 | °C |
| T _{STG} | Storage Temperature | -65 to 150 | °C |
| T _{LEAD} | Lead Temperature, Soldering (SO8 package) 40 sec (PSDIP8 package) 10 sec | 215 260 | °C |
| V _{IO} | Input or Output Voltages | -0.3 to 6.5 | V |
| V _{CC} | Supply Voltage | -0.3 to 6.5 | V |
| V _{ESD} | Electrostatic Discharge Voltage (Human Body model) ⁽²⁾ | 4000 | V |
| | Electrostatic Discharge Voltage (Machine model) ⁽³⁾ | 500 | V |

Notes: 1. Except for the rating "Operating Temperature Range", stresses above those listed in the Table "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the Operating sections of this specification is not implied. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability. Refer also to the STMicroelectronics SURE Program and other relevant quality documents.

2. MIL-STD-883C, 3015.7 (100pF, 1500 Ω).
3. EIAJ IC-121 (Condition C) (200pF, 0 Ω).

Table 3A. Device Select Code (ST24LC21B, ST24LW21, ST24FC21 and ST24FW21)

| Bit | Device Code | | | | Chip Enable | | | R \bar{W} |
|---------------|-------------|----|----|----|-------------|----|----|-------------|
| | b7 | b6 | b5 | b4 | b3 | b2 | b1 | b0 |
| Device Select | 1 | 0 | 1 | 0 | X | X | X | R \bar{W} |

Note: The MSB b7 is sent first.
X = 0 or 1.

Table 3B. Device Select Code (ST24FC21B)

| Bit | Device Code | | | | Chip Enable | | | R \bar{W} |
|---------------|-------------|----|----|----|-------------|----|----|-------------|
| | b7 | b6 | b5 | b4 | b3 | b2 | b1 | b0 |
| Device Select | 1 | 0 | 1 | 0 | 0 | 0 | 0 | R \bar{W} |

Note: The MSB b7 is sent first.
X = 0 or 1.

DESCRIPTION (cont'd)

The ST24xy21 can operate in two modes: Transmit-Only mode and I²C bidirectional mode. When powered, the device is in Transmit-Only mode with EEPROM data clocked out from the rising edge of the signal applied on VCLK.

The device will switch to the I²C bidirectional mode upon the falling edge of the signal applied on SCL pin. When in I²C mode, the ST24LC21B (or the ST24LW21) cannot switch back to the Transmit Only mode (except when the power supply is removed). For the ST24FC21, ST24FC21B (or the ST24FW21), after the falling edge of SCL, the memory enter in a transition state which allowed to

switch back to the Transmit-Only mode if no valid I²C activity is observed. Both Plastic Dual-in-Line and Plastic Small Outline packages are available.

Transmit Only Mode

After a Power-up, the ST24xy21 is in the Transmit Only mode. A proper initialization sequence (see Figure 3) must supply nine clock pulses on the VCLK pin (in order to internally synchronize the device). During this initialization sequence, the SDA pin is in high impedance. On the rising edge of the tenth pulse applied on VCLK pin, the device will output the first bit of byte located at address 00h (most significant bit first).

Figure 3. Transmit Only Mode Waveforms

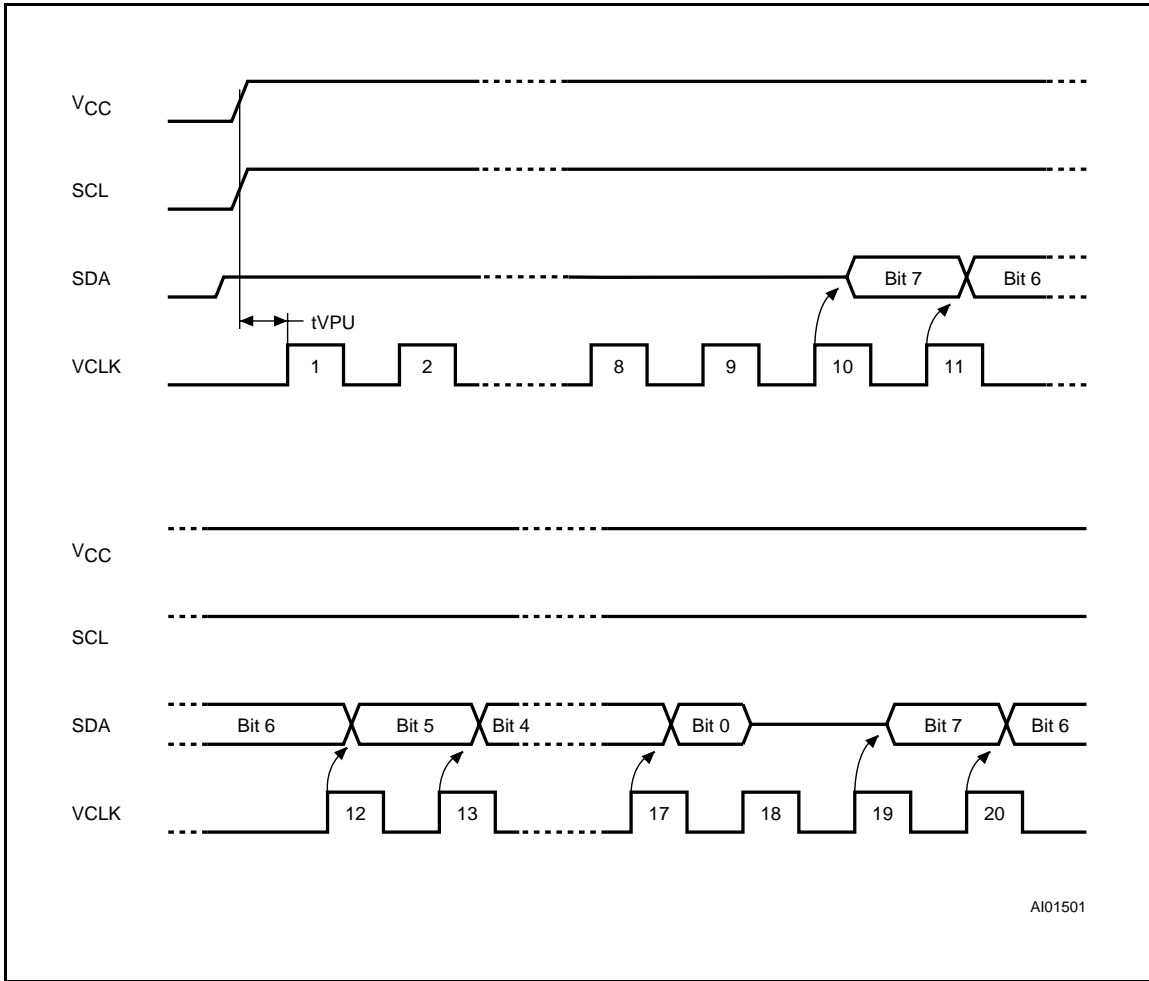
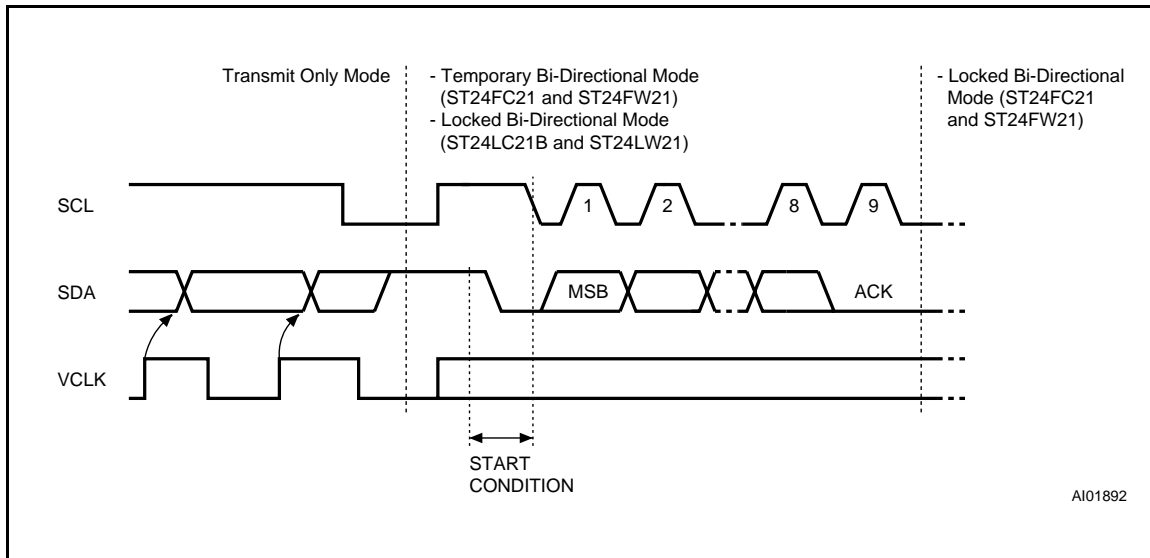


Table 4. I²C Operating Modes

| Mode | R \bar{W} bit | ST24LC21B ST24FC21 ST24FC21B VCLK | ST24LW21 ST24FW21 WC | Bytes | Initial Sequence |
|----------------------|-----------------|--|----------------------------|----------|---|
| Current Address Read | '1' | X | X | 1 | START, Device Select, R \bar{W} = '1' |
| Random Address Read | '0' | X | X | 1 | START, Device Select, R \bar{W} = '0', Address, |
| | '1' | X | X | | reSTART, Device Select, R \bar{W} = '1' |
| Sequential Read | '1' | X | X | 1 to 128 | Similar to Current or Random Mode |
| Byte Write | '0' | V _{IH} | V _{IH} | 1 | START, Device Select, R \bar{W} = '0' |
| Page Write | '0' | V _{IH} | V _{IH} | 8 | START, Device Select, R \bar{W} = '0' |

Note: X = V_{IH} or V_{IL}

Figure 4. Transition from Transmit Only (DCC1) to Bi-directional (DCC2B) Mode Waveforms



A byte is clocked out (on SDA pin) with nine clock pulses on VCLK: 8 clock pulses for the data byte and one extra clock pulse for a Don't Care bit.

As long as the SCL pin is held high, each byte of the memory array is transmitted serially on the SDA pin with an automatic address increment.

When the last byte is transmitted, the address counter will roll-over to location 00h.

I²C Bidirectional Mode

The ST24xy21 can be switched from Transmit Only mode to I²C Bidirectional mode by applying a valid high to low transition on the SCL pin (see Figure 4).

- When the ST24LC21B (or the ST24FC21 or the ST24FC21B) is in the I²C Bidirectional mode, the VCLK input (pin 7) enables (or inhibits) the execution of any write instruction: if VCLK = 1, write instructions are executed; if VCLK = 0, write instructions are not executed.
- When the ST24LW21 (or the ST24FW21) is in the I²C Bidirectional mode, the Write Control (WC on pin 3) input enables (or inhibits) the execution of any write instruction: if WC = 1, write instructions are executed; if WC = 0, write instructions are not executed.

The ST24xy21 is compatible with the I²C standard, two wire serial interface which uses a bidirectional data bus and serial clock. The ST24xy21 carries a built-in 4 bit, unique device identification code (1010) named Device Select code corresponding to the I²C bus definition. The ST24LC21B carries a unique device identification code (1010.0000 RW)

named Device Select code corresponding to the I²C bus definition.

The ST24xy21 behaves as a slave device in the I²C protocol with all memory operations synchronized by the serial clock SCL. Read and write operations are initiated by a START condition generated by the bus master. The START condition is followed by a stream of 7 bits, plus one read/write bit and terminated by an acknowledge bit.

When data is written into the memory, the ST24xy21 responds to the 8 bits received by asserting an acknowledge bit during the 9th bit time. When data is read by the bus master, it must acknowledge the receipt of the data bytes in the same way. Data transfers are terminated with a STOP condition (see READ and WRITE descriptions in the following pages).

Power On Reset: V_{CC} lock out write protect

In order to prevent data corruption and inadvertent write operations during power up, a Power On Reset (POR) circuit is implemented. Until the V_{CC} voltage has reached the POR threshold value, the internal reset is active, all operations are disabled and the device will not respond to any command. In the same way, when V_{CC} drops down from the operating voltage to below the POR threshold value, all operations are disabled and the device will not respond to any command. A stable V_{CC} must be applied before applying any logic signal.

Error Recovery Modes available in the ST24FC21, ST24FC21B and the ST24FW21

Figure 5. Error Recovery Mechanism Flowchart for the ST24FC21, ST24FC21B and ST24FW21 products

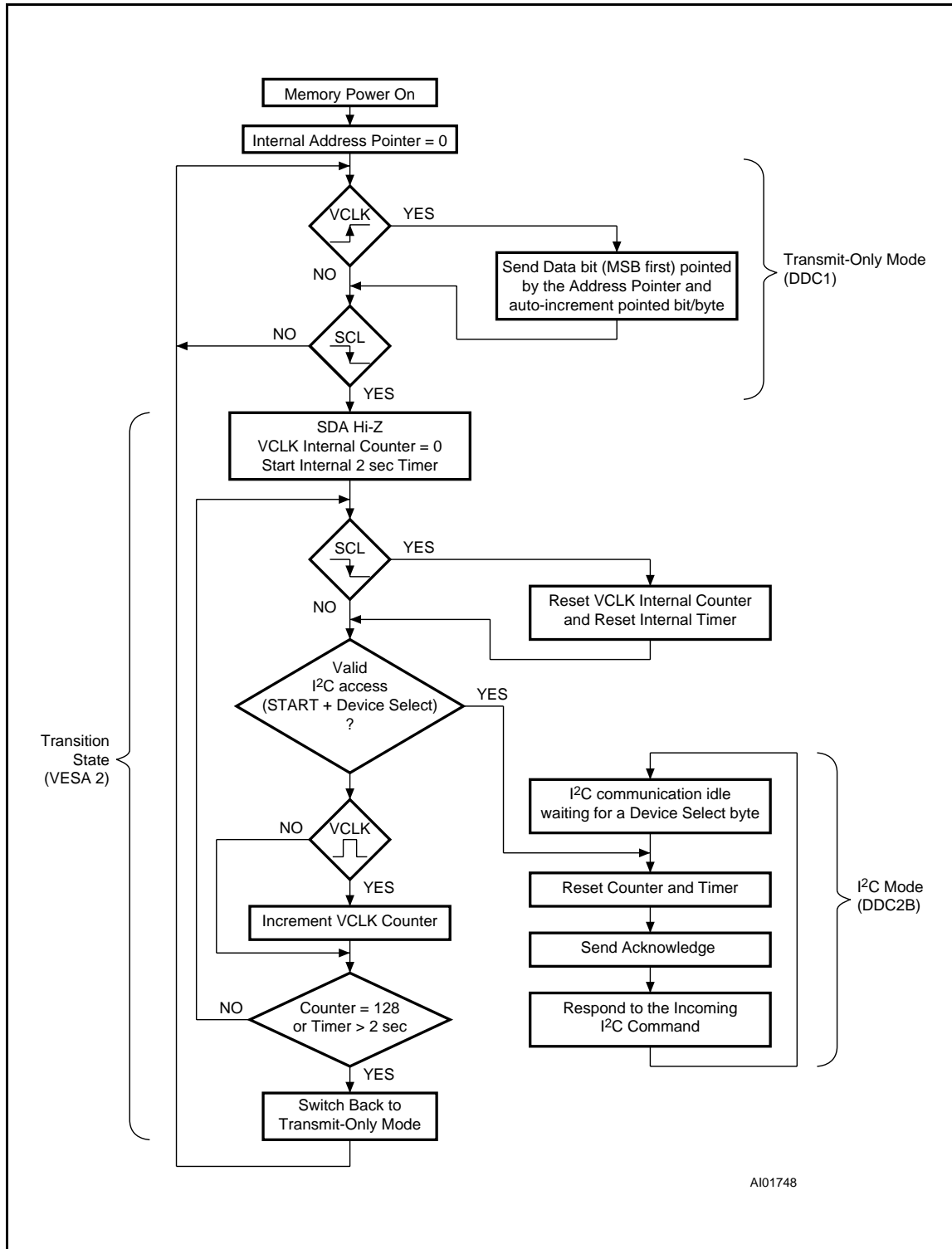
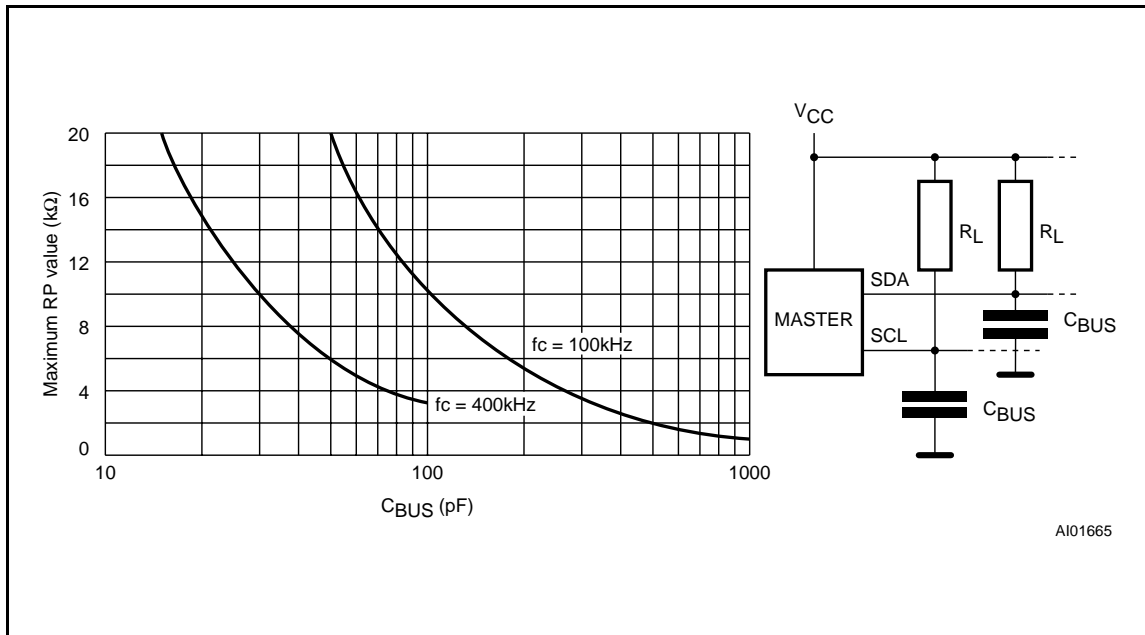


Figure 6. Maximum R_L Value versus Bus Capacitance (C_{BUS}) for an I²C Bus



When the ST24FC21 (or the ST24FC21B or the ST24FW21) first switches to the I²C mode (VESA DDC2B mode), it enters a transition state which is functionally identical to I²C operation. But, if the ST24FC21 (or the ST24FC21B or the ST24FW21) does not receive a valid I²C sequence, that is a START condition followed by a valid Device Select code (1010XXX $R\bar{W}$ for ST24FC21 and ST24FW21; 1010000 $R\bar{W}$ for ST24FC21B), within either 128 VCLK periods or a period of time of $t_{RECOVERY}$ (approximately 2 seconds), the ST24FC21 (or the ST24FC21B or the ST24FW21) will revert to the Transmit-Only mode (VESA DDC1 mode).

If the ST24FC21 (or the ST24FC21B or the ST24FW21) decodes a valid I²C Device Select code, it will lock into I²C mode. Under this condition, signals applied on the VCLK input will not disturb READ access from the ST24FC21 (or the ST24FC21B or the ST24FW21). For WRITE access, refer to the Signal Description paragraph.

When in the transition state, the count of VCLK pulses and the internal 2 seconds timer are reset by any activity on the SCL line. This means that, after each high to low transition on SCL, the memory will re-initialise its transition state and will switch back to Transmit-Only mode only after 128 more VCLK pulses or after a new $t_{RECOVERY}$ delay.

SIGNAL DESCRIPTIONS

I²C Serial Clock (SCL). The SCL input pin is used to synchronize all data in and out of the memory. A resistor can be connected from the SCL line to V_{CC} to act as a pull up (see Figure 6).

Serial Data (SDA). The SDA pin is bi-directional and is used to transfer data in or out of the memory. It is an open drain output that may be wire-OR'ed with other open drain or open collector signals on the bus. A resistor must be connected from the SDA bus line to V_{CC} to act as pull up (see Figure 6).

Transmit Only Clock (VCLK). The VCLK input pin is used to synchronize data out when the ST24xy21 is in Transmit Only mode.

For the ST24LC21B and the ST24FC21 or ST24FC21B Only, the VCLK offers also a Write Enable (active high) function when the ST24LC21B and the ST24FC21 or ST24FC21B are in I²C bi-directional mode.

Write Control (WC). An hardware Write Control feature (WC) is offered only on ST24LW21 and ST24FW21 on pin 3. This feature is useful to protect the contents of the memory from any erroneous erase/write cycle. The Write Control signal is used to enable ($WC = V_{IL}$) or disable ($WC = V_{IH}$) the internal write protection. When unconnected, the WC input is internally tied to V_{SS} by a 100k ohm pull-down resistor and the memory is write protected.

DEVICE OPERATION

ST24LC21B, ST24LW21, ST24FC21, ST24FC21B, ST24FW21

Table 5. Input Parameters ⁽¹⁾ ($T_A = 25\text{ }^\circ\text{C}$, $f = 100\text{ kHz}$)

| Symbol | Parameter | Test Condition | Min | Max | Unit |
|----------|---|----------------|-----|-----|------|
| C_{IN} | Input Capacitance (SDA) | | | 8 | pF |
| C_{IN} | Input Capacitance (other pins) | | | 6 | pF |
| t_{LP} | Low-pass filter input time constant (SDA and SCL) | | 200 | 500 | ns |

Note: 1. Sampled only, not 100% tested.

Table 6A. DC Characteristics (ST24LC21B, ST24LW21, ST24FC21 and ST24FW21)
($T_A = -40\text{ to }85\text{ }^\circ\text{C}$; $V_{CC} = 3.6\text{V to }5.5\text{V}$)

| Symbol | Parameter | Test Condition | Min | Max | Unit |
|-----------|--|--|--------------|--------------|---------------|
| I_{LI} | Input Leakage Current | $0V \leq V_{IN} \leq V_{CC}$ | | ± 2 | μA |
| I_{LO} | Output Leakage Current | $0V \leq V_{OUT} \leq V_{CC}$ SDA in Hi-Z | | ± 2 | μA |
| I_{CC} | Supply Current | $V_{CC} = 5V$, $f_c = 400\text{kHz}$ (Rise/Fall time < 10ns) | | 2 | mA |
| | Supply Current | $V_{CC} = 3.6V$, $f_c = 400\text{kHz}$ | | 1 | mA |
| I_{CC1} | Supply Current (Standby) | $V_{IN} = V_{SS}$ or V_{CC} , $V_{CC} = 5V$, $f_c = 0$ | | 100 | μA |
| | | $V_{IN} = V_{SS}$ or V_{CC} , $V_{CC} = 5V$, $f_c = 400\text{kHz}$ | | 300 | μA |
| I_{CC2} | Supply Current (Standby) | $V_{IN} = V_{SS}$ or V_{CC} , $V_{CC} = 3.6V$, $f_c = 0$ | | 30 | μA |
| | | $V_{IN} = V_{SS}$ or V_{CC} , $V_{CC} = 3.6V$, $f_c = 400\text{kHz}$ | | 100 | μA |
| V_{IL} | Input Low Voltage (SCL, SDA, WC) | | -0.3 | $0.3 V_{CC}$ | V |
| V_{IH} | Input High Voltage (SCL, SDA, WC) | | $0.7 V_{CC}$ | $V_{CC} + 1$ | V |
| V_P | High Level Threshold Voltage (Schmitt Trigger on VLCK) | $V_{CC} = 5.5V$ | 1.4 | 2.1 | V |
| | | $V_{CC} = 4.5V$ | 1.2 | 1.9 | V |
| | | $V_{CC} = 3.6V$ | 1 | 1.7 | V |
| V_N | Low Level Threshold Voltage (Schmitt Trigger on VLCK) | $V_{CC} = 5.5V$ | 0.6 | 1.4 | V |
| | | $V_{CC} = 4.5V$ | 0.5 | 1.2 | V |
| | | $V_{CC} = 3.6V$ | 0.4 | 1 | V |
| V_H | Hysteresis Voltage (Schmitt Trigger on VLCK) | $V_{CC} = 5.5V$ | 0.4 | 1.5 | V |
| | | $V_{CC} = 4.5V$ | 0.4 | 1.4 | V |
| | | $V_{CC} = 3.6V$ | 0.35 | 1.3 | V |
| V_{OL} | Output Low Voltage | $I_{OL} = 3\text{mA}$, $V_{CC} = 3.6V$ | | 0.4 | V |
| | | $I_{OL} = 6\text{mA}$, $V_{CC} = 5V$ | | 0.6 | V |

Table 6B. DC Characteristics (ST24FC21B)
($T_A = -40$ to 85 °C; $V_{CC} = 2.5$ to $5.5V$)

| Symbol | Parameter | Test Condition | Min ⁽¹⁾ | Max ⁽¹⁾ | Unit |
|-----------|---|---|--------------------|--------------------|---------|
| I_{LI} | Input Leakage Current | $0V \leq V_{IN} \leq V_{CC}$ | | ± 2 | μA |
| I_{LO} | Output Leakage Current | $0V \leq V_{OUT} \leq V_{CC}$ SDA in Hi-Z | | ± 2 | μA |
| I_{CC} | Supply Current | $V_{CC} = 5V, f_C = 400kHz$ (Rise/Fall time < 10ns) | | 2 | mA |
| | Supply Current | $V_{CC} = 2.5V, f_C = 400kHz$ | | 1 | mA |
| I_{CC1} | Supply Current (Standby) | $V_{IN} = V_{SS}$ or $V_{CC},$ $V_{CC} = 5V, f_C = 0$ | | 100 | μA |
| | | $V_{IN} = V_{SS}$ or $V_{CC},$ $V_{CC} = 5V, f_C = 400kHz$ | | 300 | μA |
| I_{CC2} | Supply Current (Standby) | $V_{IN} = V_{SS}$ or $V_{CC},$ $V_{CC} = 2.5V, f_C = 0$ | | 30 | μA |
| | | $V_{IN} = V_{SS}$ or $V_{CC},$ $V_{CC} = 2.5V, f_C = 400kHz$ | | 100 | μA |
| V_{IL} | Input Low Voltage (SCL, SDA, WC) | | -0.3 | $0.3 V_{CC}$ | V |
| V_{IH} | Input High Voltage (SCL, SDA, WC) | | $0.7 V_{CC}$ | $V_{CC} + 1$ | V |
| V_P | High Level Threshold Voltage (Schmitt Trigger on VLCK) | $V_{CC} = 5.0V$ | 1.2 | 1.9 | V |
| | | $V_{CC} = 2.5V$ | 0.8 | 1.4 | V |
| V_N | Low Level Threshold Voltage (Schmitt Trigger on VLCK) | $V_{CC} = 5.0V$ | 0.6 | 1.7 | V |
| | | $V_{CC} = 2.5V$ | 0.5 | 1.1 | V |
| V_{OL} | Output Low Voltage | $I_{OL} = 2.1mA, V_{CC} = 2.5V$ | | 0.4 | V |
| | | $I_{OL} = 6mA, V_{CC} = 5V$ | | 0.6 | V |

Note 1: Preliminary results.

ST24LC21B, ST24LW21, ST24FC21, ST24FC21B, ST24FW21

Table 7. AC Characteristics, I²C Bidirectional Mode for Clock Frequency = 400kHz
(T_A = -40 to 85 °C; V_{CC} = 3.6 to 5.5V or V_{CC} = 2.5 to 5.5V)

| Symbol | Alt | Parameter | Min | Max | Unit |
|------------------------------------|---------------------|--------------------------------------|-----|-----|------|
| t _{CH1CH2} ⁽¹⁾ | t _R | Clock Rise Time | | 300 | ns |
| t _{CL1CL2} ⁽¹⁾ | t _F | Clock Fall Time | | 300 | ns |
| t _{DH1DH2} ⁽¹⁾ | t _R | SDA Rise Time | 20 | 300 | ns |
| t _{DL1DL2} ⁽¹⁾ | t _F | SDA Fall Time | 20 | 300 | ns |
| t _{CHDX} ⁽²⁾ | t _{SU:STA} | Clock High to Input Transition | 600 | | ns |
| t _{CHCL} | t _{HIGH} | Clock Pulse Width High | 600 | | ns |
| t _{DLCL} | t _{HD:STA} | Input Low to Clock Low (START) | 600 | | ns |
| t _{CLDX} | t _{HD:DAT} | Clock Low to Input Transition | 0 | | µs |
| t _{CLCH} | t _{LOW} | Clock Pulse Width Low | 1.3 | | µs |
| t _{DXCX} | t _{SU:DAT} | Input Transition to Clock Transition | 100 | | ns |
| t _{CHDH} | t _{SU:STO} | Clock High to Input High (STOP) | 600 | | ns |
| t _{DHDL} | t _{BUF} | Input High to Input Low (Bus Free) | 1.3 | | µs |
| t _{CLQV} | t _{AA} | Clock Low to Data Out Valid | 200 | 900 | ns |
| t _{CLQX} | t _{DH} | Clock Low to Data Out Transition | 200 | | ns |
| f _C | f _{SCL} | Clock Frequency | | 400 | kHz |
| t _W | t _{WR} | Write Time | | 10 | ms |

Notes: 1. Sampled only, not 100% tested.
2. For a reSTART condition, or following a write cycle.

I²C Bus Background

The ST24xy21 supports the I²C protocol. This protocol defines any device that sends data onto the bus as a transmitter and any device that reads the data as a receiver. The device that controls the data transfer is known as the master and the other as the slave. The master will always initiate a data transfer and will provide the serial clock for synchronisation. The ST24xy21 are always slave devices in all communications.

Start Condition. START is identified by a high to low transition of the SDA line while the clock SCL is stable in the high state. A START condition must precede any command for data transfer. Except during a programming cycle, the ST24xy21 continuously monitor the SDA and SCL signals for a START condition and will not respond unless one is given.

The ST24LC21B, ST24LW21, ST24FC21 and ST24FW21 are not executing a START condition if this START condition happens at any time inside a byte. The ST24FC21B executes a START condition when this START condition happens at any time inside a byte.

Stop Condition. STOP is identified by a low to high transition of the SDA line while the clock SCL is stable in the high state. A STOP condition terminates communication between the ST24xy21 and the bus master. A STOP condition at the end of a Read command (after the No ACK) forces the standby state. A STOP condition at the end of a Write command triggers the internal EEPROM write cycle.

The ST24LC21B, ST24LW21, ST24FC21 and ST24FW21 are not executing a STOP condition if this STOP condition happens at any time inside a byte. The ST24FC21B executes a STOP condition when this STOP condition happens at any time inside a byte.

Acknowledge Bit (ACK). An acknowledge signal is used to indicate a successful data transfer. The bus transmitter, either master or slave, will release the SDA bus after sending 8 bits of data. During the 9th clock pulse period the receiver pulls the SDA bus low to acknowledge the receipt of the 8 bits of data.

Data Input. During data input, the ST24xy21 sample the SDA bus signal on the rising edge of the clock SCL. Note that for correct device operation

Table 8. AC Characteristics, I²C Bidirectional Mode for Clock Frequency = 100kHz
(T_A = -40 to 85 °C; V_{CC} = 3.6V to 5.5V)

| Symbol | Alt | Parameter | Min | Max | Unit |
|----------------------------------|---------------------|--------------------------------------|-----|-----|------|
| t _{CH1CH2} | t _R | Clock Rise Time | | 1 | μs |
| t _{CL1CL2} | t _F | Clock Fall Time | | 300 | ns |
| t _{DH1DH2} | t _R | Input Rise Time | | 1 | μs |
| t _{DL1DL1} | t _F | Input Fall Time | | 300 | ns |
| t _{CHDX} ⁽¹⁾ | t _{SU:STA} | Clock High to Input Transition | 4.7 | | μs |
| t _{CHCL} | t _{HIGH} | Clock Pulse Width High | 4 | | μs |
| t _{DLCL} | t _{HD:STA} | Input Low to Clock Low (START) | 4 | | μs |
| t _{CLDX} | t _{HD:DAT} | Clock Low to Input Transition | 0 | | μs |
| t _{CLCH} | t _{LOW} | Clock Pulse Width Low | 4.7 | | μs |
| t _{DXCX} | t _{SU:DAT} | Input Transition to Clock Transition | 250 | | ns |
| t _{CHDH} | t _{SU:STO} | Clock High to Input High (STOP) | 4.7 | | μs |
| t _{DHDL} | t _{BUF} | Input High to Input Low (Bus Free) | 4.7 | | μs |
| t _{CLQV} ⁽²⁾ | t _{AA} | Clock Low to Next Data Out Valid | 0.2 | 3.5 | μs |
| t _{CLQX} | t _{DH} | Data Out Hold Time | 200 | | ns |
| f _C | f _{SCL} | Clock Frequency | | 100 | kHz |
| t _W | t _{WR} | Write Time | | 10 | ms |

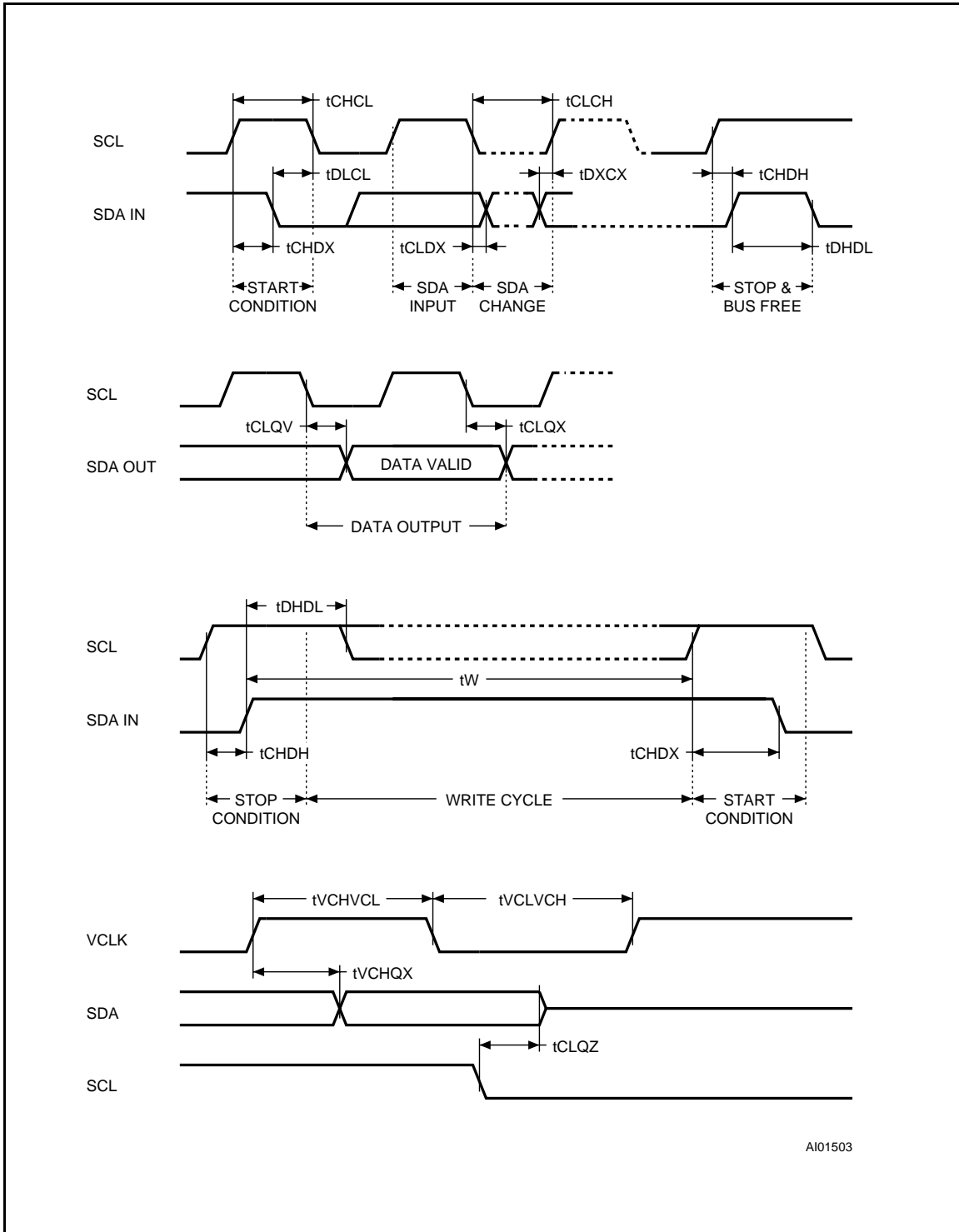
Notes: 1. For a reSTART condition, or following a write cycle.
2. The minimum value delays the falling/rising edge of SDA away from SCL = 1 in order to avoid unwanted START and/or STOP conditions.

Table 9. AC Characteristics, Transmit-only Mode
(T_A = -40 to 85 °C; V_{CC} = 3.6V to 5.5V)

| Symbol | Alt | Parameter | Min | Max | Unit |
|--------------------------------------|--------------------|-----------------------------|-----|-----|------|
| t _{VCHQX} | t _{VAA} | Output Valid from VCLK | | 500 | ns |
| t _{VCHVCL} | t _{VHIGH} | VCLK High Time | 600 | | ns |
| t _{VCLVCH} | t _{VLOW} | VCLK Low Time | 1.3 | | μs |
| t _{CLQZ} | t _{VHZ} | Mode Transition Time | | 500 | ns |
| t _{VPU} ^(1,2) | | Transmit-only Power-up Time | 0 | | ns |
| t _{VH1VH2} ⁽²⁾ | t _R | VCLK Rise Time | | 1 | μs |
| t _{VL1VL2} ⁽²⁾ | t _F | VCLK Fall Time | | 1 | μs |
| t _{RECOVERY} ⁽²⁾ | | Recovery Time | 1.5 | 3.5 | sec |

Notes: 1. Refer to Figure 3.
2. Sampled only, not 100% tested.

Figure 7. AC Waveforms



A101503

Table 10. AC Measurement Conditions

| | |
|---------------------------------------|----------------------------|
| Input Rise and Fall Times | $\leq 50\text{ns}$ |
| Input Pulse Voltages SDA, SCL | $0.2V_{CC}$ to $0.8V_{CC}$ |
| Input Pulse Voltages V_{CLK} | 0.4V to 2.4V |
| Input and Output Timing Ref. Voltages | $0.3V_{CC}$ to $0.7V_{CC}$ |

Figure 8. AC Testing Input Output Waveforms

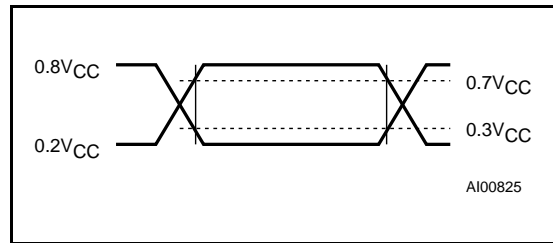


Figure 9. I²C Bus Protocol

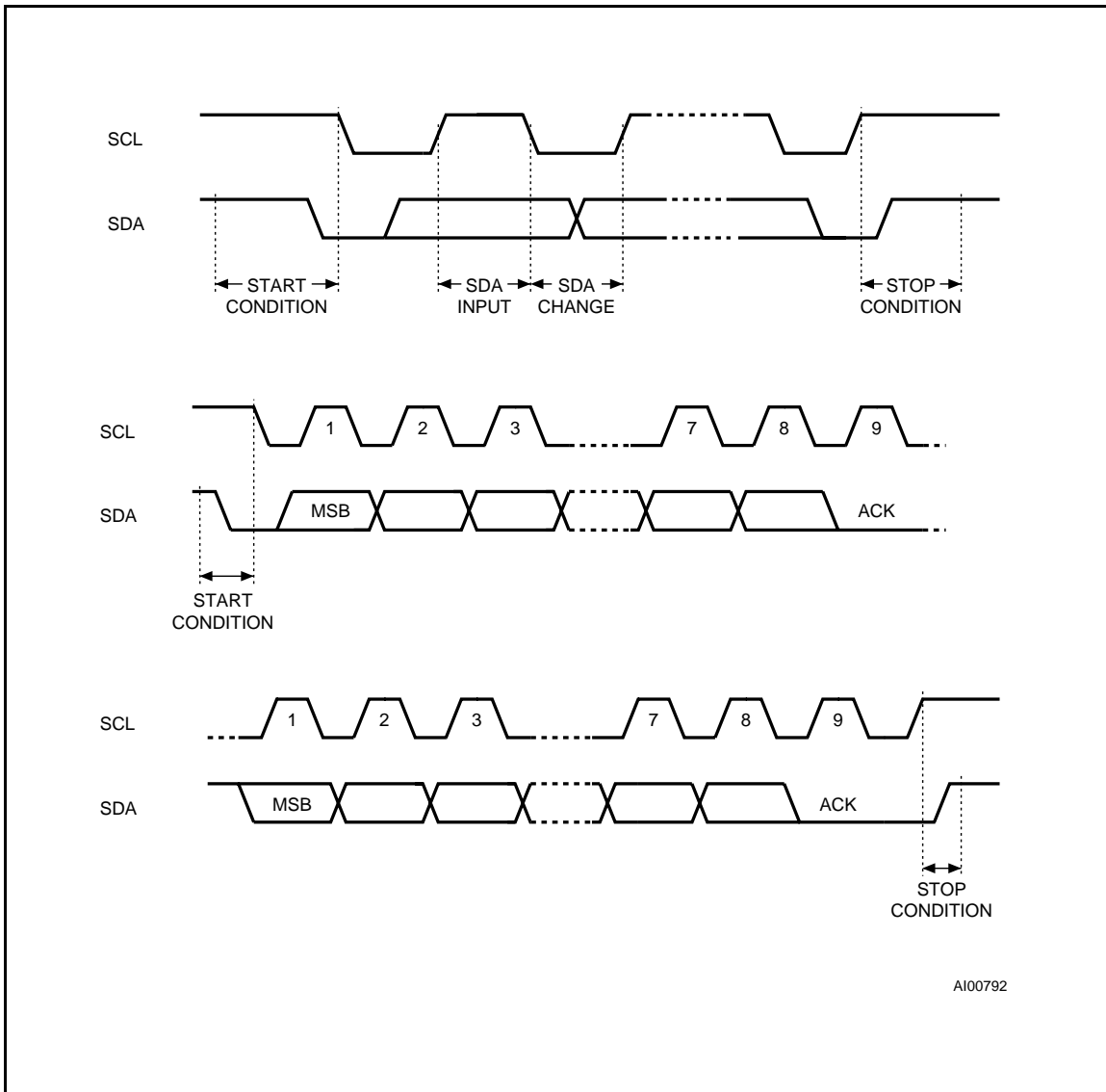
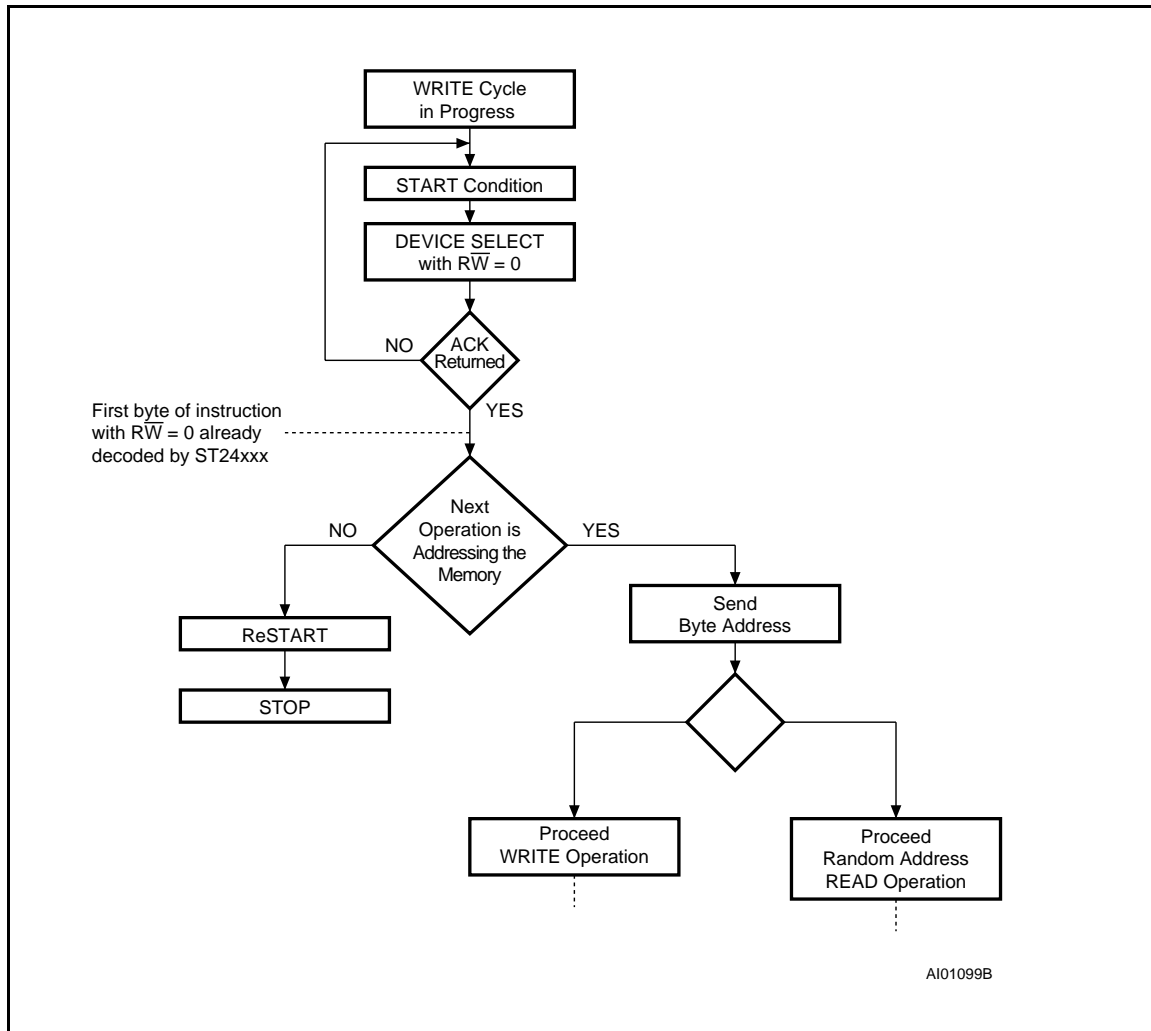


Figure 10. Write Cycle Polling using ACK



the SDA signal must be stable during the clock low to high transition and the data must change ONLY when the SCL line is low.

Memory Addressing. To start communication between the bus master and the slave ST24xy21, the master must initiate a START condition. Following this, the master sends onto the SDA bus line 8 bits (MSB first) corresponding to the Device Select code (7 bits) and a READ or WRITE bit. The 4 most significant bits of the Device Select code are the device type identifier, corresponding to the I²C bus definition. For these memories the 4 bits are fixed as 1010b. The 8th bit sent is the read or write bit (RW), this bit is set to '1' for read and '0' for write operations. If a match is found, the corresponding

memory will acknowledge the identification on the SDA bus during the 9th bit time.

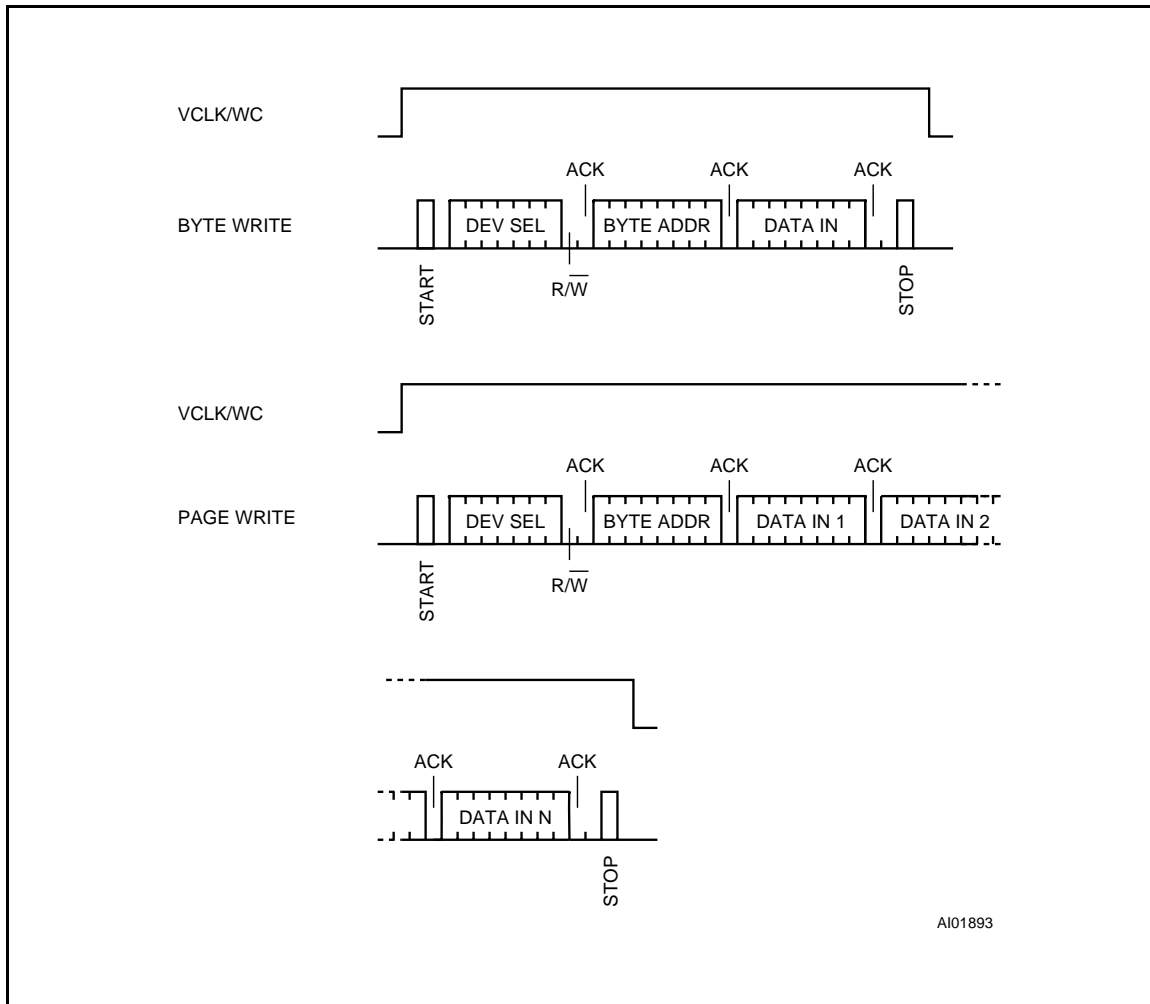
Write Operations

Following a START condition the master sends a Device Select code with the RW bit set to '0'. The memory acknowledges this and waits for a byte address. After receipt of the byte address the device again responds with an acknowledge.

In I²C bidirectional mode, any write command with VCLK=0 (for the ST24LC21B and ST24FC21, ST24FC21B) or with WC=0 (for the ST24LW21 and ST24FW21) will not modify data and will be acknowledged on data bytes, as shown in Figure 12.

Byte Write. In the Byte Write mode the master sends one data byte, which is acknowledged by the

Figure 11. Write Modes Sequence



memory. The master then terminates the transfer by generating a STOP condition.

Page Write. The Page Write mode allows up to 8 bytes to be written in a single write cycle, provided that they are all located in the same 'row' in the memory; that is the most significant memory address bits are the same. The master sends from one up to 8 bytes of data, which are each acknowledged by the memory.

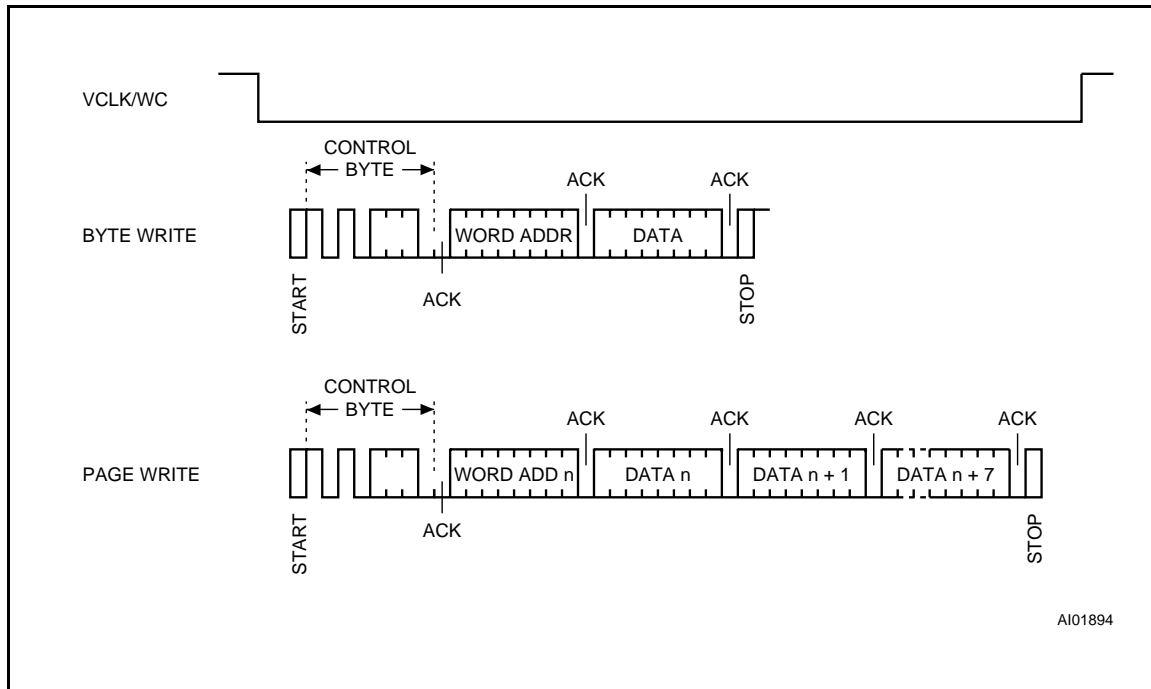
After each byte is transferred, the internal byte address counter (3 least significant bits only) is incremented. The transfer is terminated by the master generating a STOP condition. Care must be taken to avoid address counter 'roll-over' which could result in data being overwritten. Note that, for any write mode, the generation by the master of the

STOP condition starts the internal memory program cycle. All inputs are disabled until the completion of this cycle and the memory will not respond to any request.

Minimizing System Delays by Polling On ACK. During the internal write cycle, the memory disconnects itself from the bus in order to copy the data from the internal latches to the memory cells. The maximum value of the write time (t_w) is given in the AC Characteristics table, since the typical time is shorter, the time seen by the system may be reduced by an ACK polling sequence issued by the master. The sequence is as follows:

- Initial condition: a Write is in progress (see Figure 10).

Figure 12. Inhibited Write when VCLK/WC = 0



- Step 1: the Master issues a START condition followed by a Device Select byte (1st byte of the new instruction).
- Step 2: if the memory is busy with the internal write cycle, no ACK will be returned and the master goes back to Step 1. If the memory has terminated the internal write cycle, it will respond with an ACK, indicating that the memory is ready to receive the second part of the instruction (the first byte of this instruction was already sent during Step 1).

Read Operations

On delivery, the memory content is set at all "1's" (or FFh).

Current Address Read. The memory has an internal byte address counter. Each time a byte is read, this counter is incremented. For the Current Address Read mode, following a START condition, the master sends the Device Select code with the RW bit set to '1'. The memory acknowledges this and outputs the data byte addressed by the internal byte address counter. This counter is then incremented. The master must NOT acknowledge the data byte output and terminates the transfer with a STOP condition.

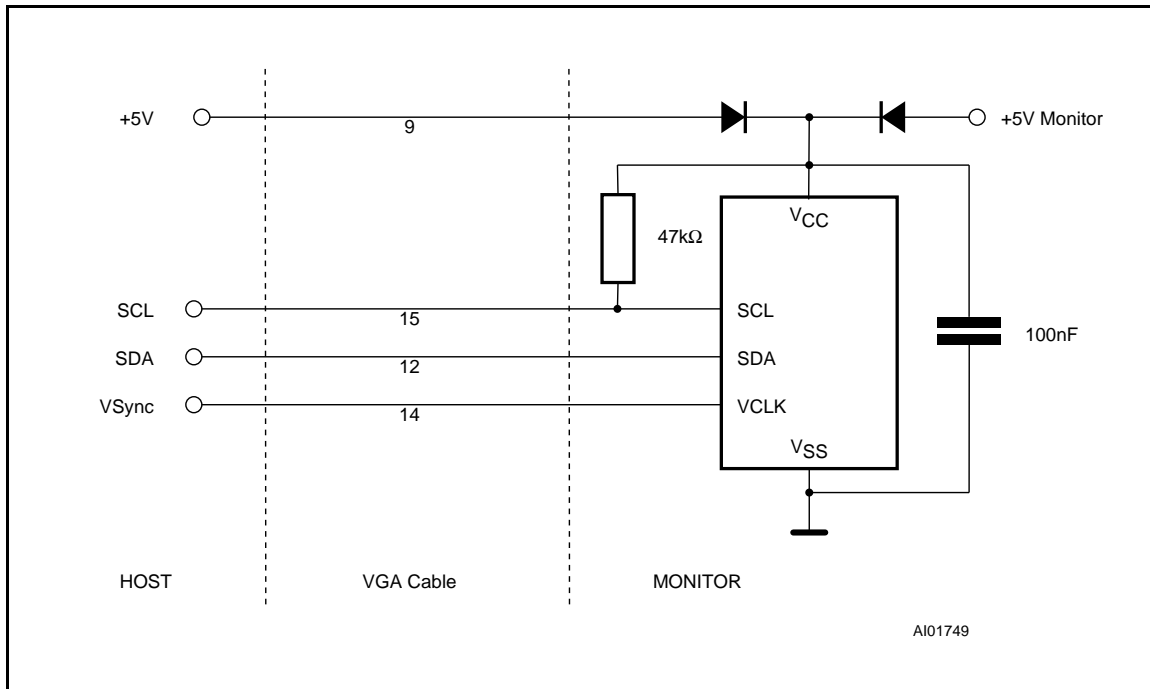
Random Address Read. A dummy write is performed to load the address into the address counter, see Figure 14. This is followed by a Re-START condition send by the master and the Device Select code is repeated with the RW bit set to '1'. The memory acknowledges this and outputs the addressed data byte. The master must NOT acknowledge the data byte output and terminates the transfer with a STOP condition.

Sequential Read. This mode can be initiated with either a Current Address Read or a Random Address Read. However, in this case the master DOES acknowledge the data byte output and the memory continues to output the next byte in sequence. To terminate the stream of bytes, the master must NOT acknowledge the last data byte output, and MUST generate a STOP condition.

The output data is from consecutive byte addresses, with the internal byte address counter automatically incremented after each byte output. After a count of the last memory address, the address counter will 'roll-over' and the memory will continue to output data.

Acknowledge in Read Mode. In all read modes the ST24xy21 wait for an acknowledge during the 9th bit time. If the master does not pull the SDA line

Figure 13. Recommended Schematic for VESA 2.0 Specification



low during this time, the ST24xy21 terminate the data transfer and switches to a standby state.

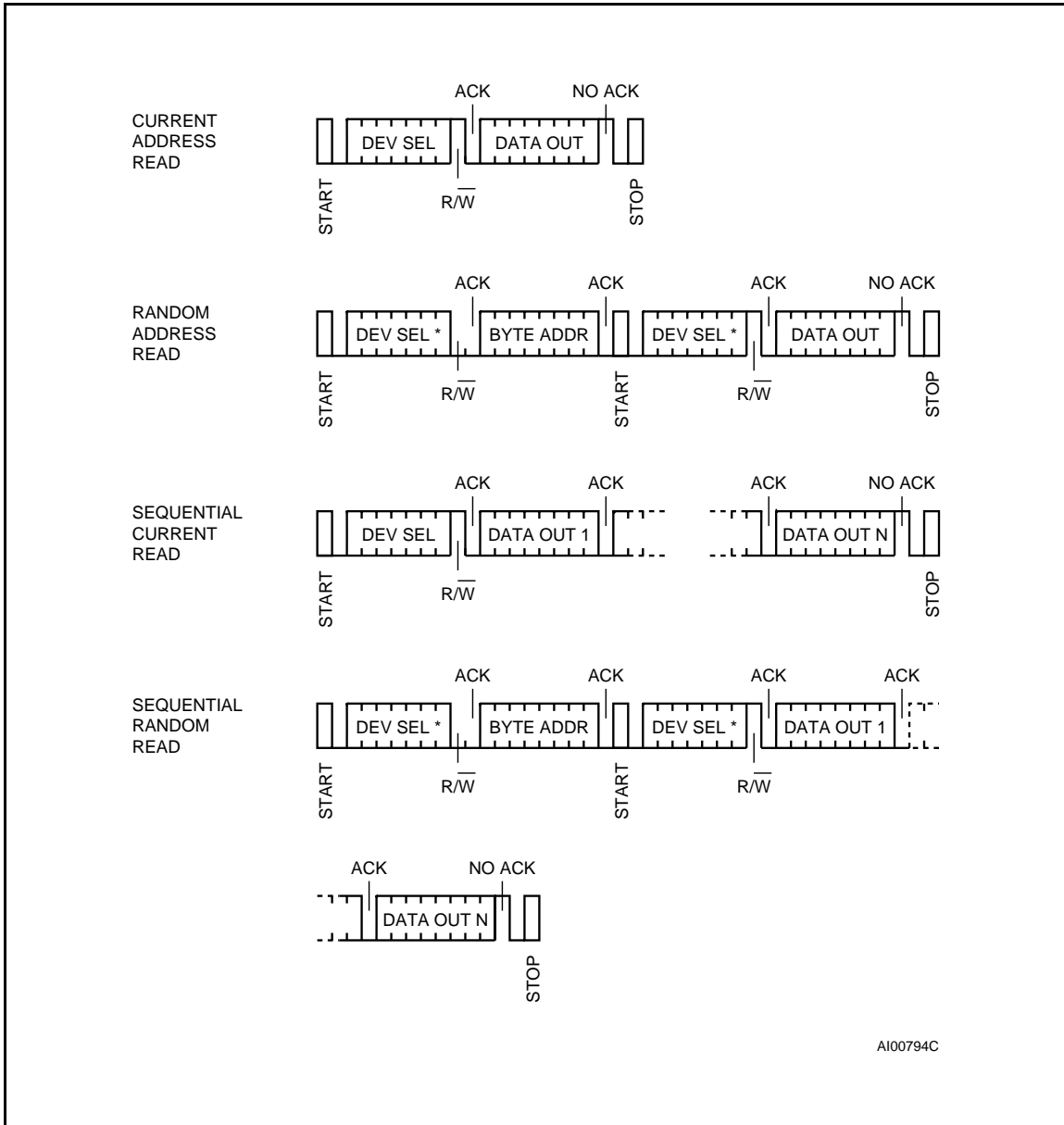
NOTE CONCERNING THE POWER SUPPLY VOLTAGE IN THE VESA 2.0 SPECIFICATION

According to the VESA 2.0 specification, the ST24xy21 can be supplied by either the MONITOR or by the HOST (using +5V on the VGA cable pin 9) power supply. The easiest way to implement this is to use 2 diodes as described in the following

schematic. The ST24xy21 supply voltage will be decreased by 0.6V, which is the diode forward voltage drop, and will be below 4.5V. Nevertheless, the ST24xy21 remains operational and no input will be damaged if the applied voltage on any input complies with the Absolute Maximum Ratings values.

Under this condition, the threshold voltage of the Schmitt-Trigger (pin 7) will be decreased (as in Table 6).

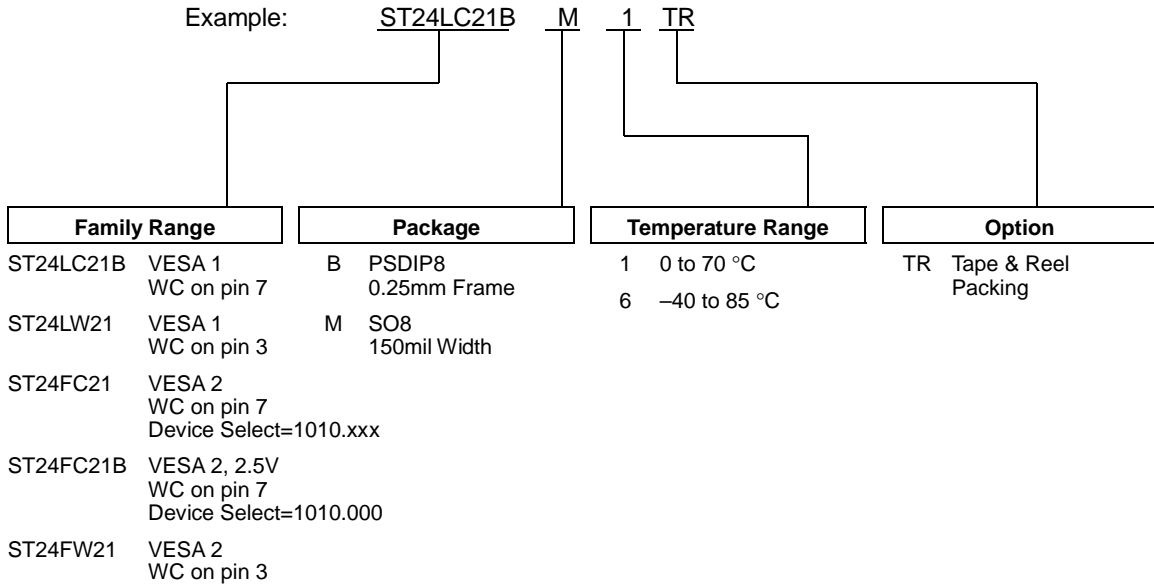
Figure 14. Read Modes Sequence



Note: * The 7 Most Significant bits of DEV SEL bytes of a Random Read (1st byte and 3rd byte) must be identical.

ST24LC21B, ST24LW21, ST24FC21, ST24FC21B, ST24FW21

ORDERING INFORMATION SCHEME



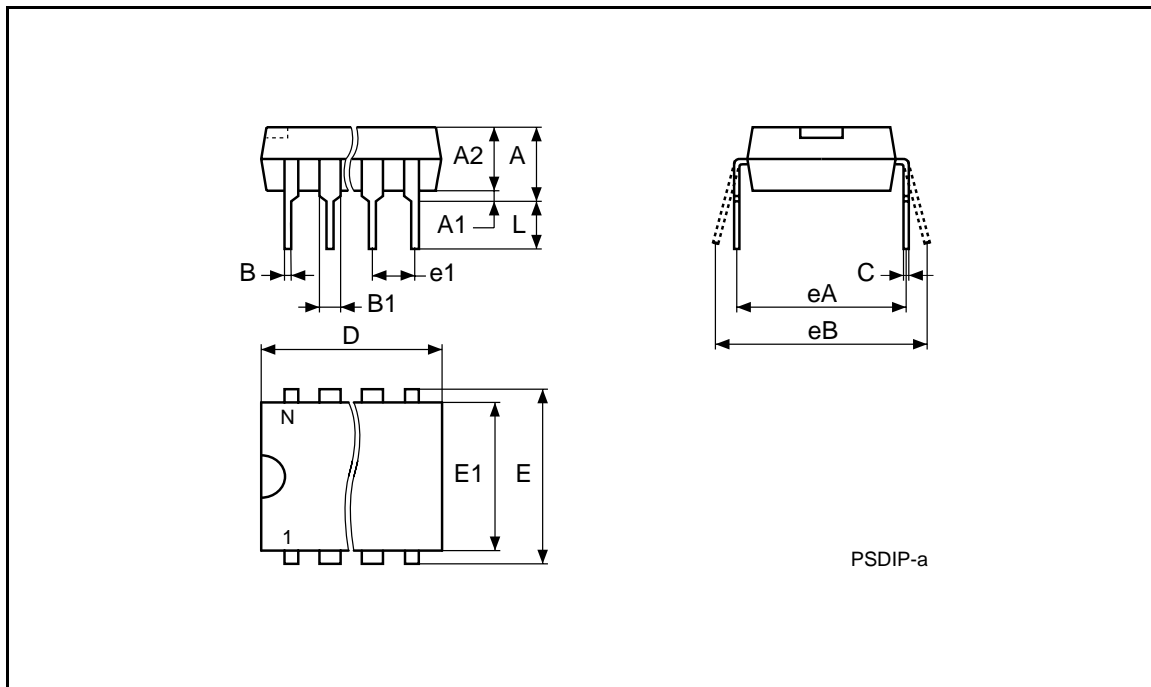
Devices are shipped from the factory with the memory content set at all "1's" (FFh).

For a list of available options (Package, etc...) or for further information on any aspect of this device, please contact the STMicroelectronics Sales Office nearest to you.

PSDIP8 - 8 pin Plastic Skinny DIP, 0.25mm lead frame

| Symb | mm | | | inches | | |
|------|------|------|-------|--------|-------|-------|
| | Typ | Min | Max | Typ | Min | Max |
| A | | 3.90 | 5.90 | | 0.154 | 0.232 |
| A1 | | 0.49 | – | | 0.019 | – |
| A2 | | 3.30 | 5.30 | | 0.130 | 0.209 |
| B | | 0.36 | 0.56 | | 0.014 | 0.022 |
| B1 | | 1.15 | 1.65 | | 0.045 | 0.065 |
| C | | 0.20 | 0.36 | | 0.008 | 0.014 |
| D | | 9.20 | 9.90 | | 0.362 | 0.390 |
| E | 7.62 | – | – | 0.300 | – | – |
| E1 | | 6.00 | 6.70 | | 0.236 | 0.264 |
| e1 | 2.54 | – | – | 0.100 | – | – |
| eA | | 7.80 | – | | 0.307 | – |
| eB | | | 10.00 | | | 0.394 |
| L | | 3.00 | 3.80 | | 0.118 | 0.150 |
| N | | 8 | | | 8 | |

PSDIP8

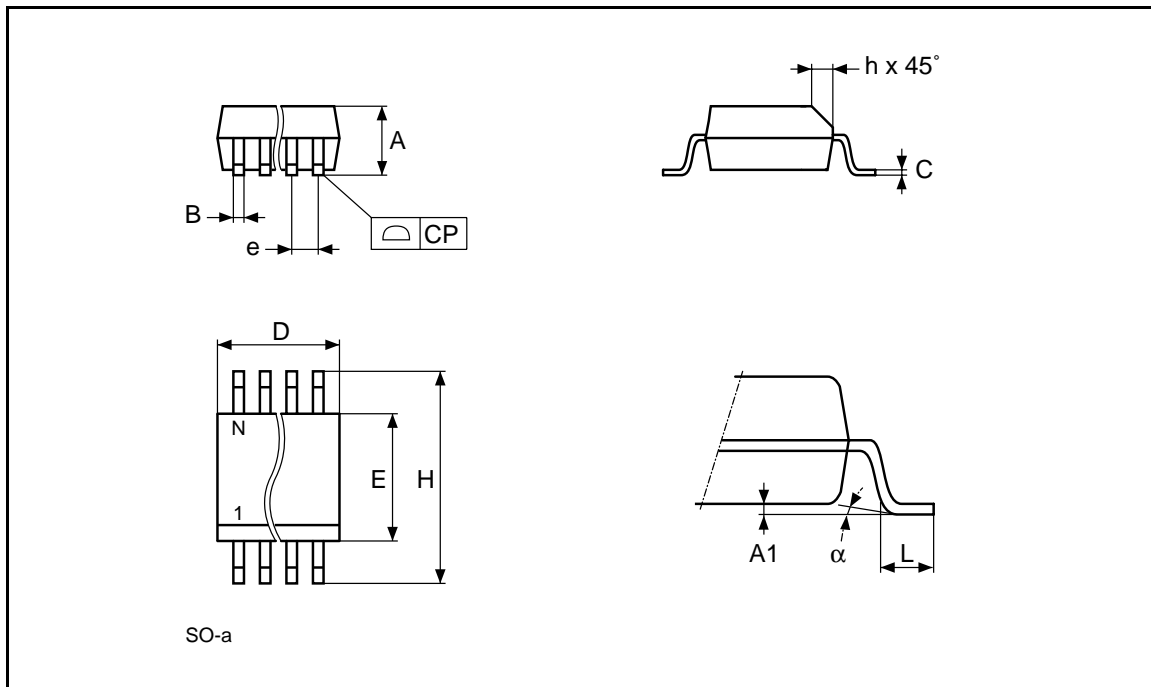


Drawing is not to scale.

SO8 - 8 lead Plastic Small Outline, 150 mils body width

| Symb | mm | | | inches | | |
|----------|------|------|------|--------|-------|-------|
| | Typ | Min | Max | Typ | Min | Max |
| A | | 1.35 | 1.75 | | 0.053 | 0.069 |
| A1 | | 0.10 | 0.25 | | 0.004 | 0.010 |
| B | | 0.33 | 0.51 | | 0.013 | 0.020 |
| C | | 0.19 | 0.25 | | 0.007 | 0.010 |
| D | | 4.80 | 5.00 | | 0.189 | 0.197 |
| E | | 3.80 | 4.00 | | 0.150 | 0.157 |
| e | 1.27 | - | - | 0.050 | - | - |
| H | | 5.80 | 6.20 | | 0.228 | 0.244 |
| h | | 0.25 | 0.50 | | 0.010 | 0.020 |
| L | | 0.40 | 0.90 | | 0.016 | 0.035 |
| α | | 0° | 8° | | 0° | 8° |
| N | | 8 | | | 8 | |
| CP | | | 0.10 | | | 0.004 |

SO8



Drawing is not to scale.

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