# **BA6149LS**

## **Regulator, switching, 6 outputs**

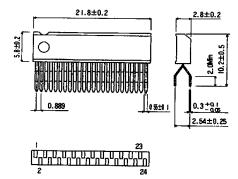
The BA6149LS is an IC that consists of six switching regulator circuits

### **Features**

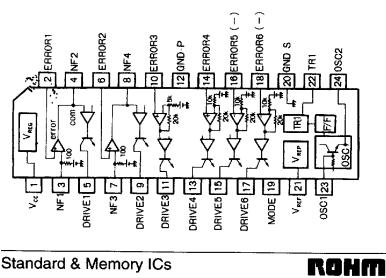
- ۰ available in an SZIP24 package
- control circuits for all regulator circuits . are contained in the IC
- high efficiency pulse width modulation ٠ system is used
- triangular wave generator produces a very clean stable output
- six output voltages
- output voltages can be switched on • and off (except 5 V output)

## Dimensions (Units : mm)

#### BA6149LS (SZIP24)



## Block diagram



| Parameter               | Symbol           | Limits     | Unit | Conditions  |
|-------------------------|------------------|------------|------|---|
| Power supply voltage    | V <sub>cc</sub>  | 20         | V    |   |
| Power dissipation       | Pd               | 500        | mW   | Reduce power by 5 mW/°C for each degree above 25°C. |
| Drive current           | ld               | 30         | mA   |   |
| Operational temperature | T <sub>opr</sub> | -10 ~ +70  | °C   |   |
| Storage temperature     | T <sub>stg</sub> | -25 ~ +125 | °C   |   |

## Absolute maximum ratings ( $T_a = 25^{\circ}C$ )

## Electrical characteristics (T<sub>a</sub> = 25°C, V<sub>CC</sub> = 12 V) (Sheet 1 of 2)

| Parameter                                 | Symbol           | Min    | Typical | Max    | Unit                | Conditions   |
|---|------------------|--------|---------|--------|---------------------|--|
| Power supply voltage                      | V <sub>CC</sub>  | 8      |         | 18     | V                   |  |
| Circuit current                           | I <sub>CC</sub>  |        | 7       | 11     | mA                  |  |
| Reference voltage                         | V <sub>ref</sub> | 2.38   | 2.53    | 2.68   | V                   |  |
| Triangular wave<br>oscillation frequency  | f <sub>T</sub>   | 100.88 | 101.88  | 102.88 | kHz                 | f <sub>0</sub> = 815 kHz                                 |
| 5 V system output voltage                 | V <sub>05</sub>  | 4.7    | 5.0     | 5.3    | V                   | $I_{L} = 227 \text{ mA}$                                 |
| 9 V system output voltage                 | V <sub>09</sub>  | 8.60   | 9.15    | 9.70   | V                   | $I_{L} = 100 \text{ mA}$                                 |
| M1 system output voltage                  | V <sub>CY</sub>  | 4.5    | 5       | 5.5    | V                   | I <sub>L</sub> = 100 mA                                  |
| M2 system output voltage                  | V <sub>CA</sub>  | 3.0    | 3.5     | 4.0    | V                   | I <sub>L</sub> = 50 mA                                   |
| M3 system output voltage                  | V <sub>SR</sub>  | 3.0    | 3.5     | 4.0    | V                   | I <sub>L</sub> = 55 mA                                   |
| M4 system output voltage                  | V <sub>TR</sub>  | 3.0    | 3.5     | 4.0    | V                   | I <sub>L</sub> = 200 mA                                  |
| M1 input regulation                       | V <sub>r1</sub>  | 40     | 80      | 160    | mV                  | $I_L = 100 \text{ mA}, \ 10 \le V_{CC} \le 16$           |
| M2 input regulation                       | V <sub>r2</sub>  | 30     | 60      | 120    | mV                  | $I_{L} = 50 \text{ mA}, \ 10 \le V_{CC} \le 16$          |
| M3 input regulation                       | V <sub>r3</sub>  | 30     | 60      | 120    | mV                  | $I_{L} = 55 \text{ mA}, \ 10 \le V_{CC} \le 16$          |
| M4 input regulation                       | V <sub>r4</sub>  | 30     | 60      | 120    | mV                  | $I_L = 200 \text{ mA}, \ 10 \le V_{CC} \le 16$           |
| Low level power-saving mode               | VL               | 0      |         | 1.5    | v                   |  |
| High level power-saving mode              | V <sub>H</sub>   | 3.5    |         | 6      | v                   | All output voltage < 0.5 V<br>except for V <sub>O5</sub> |
| 9 V system error amplifier open loop gain | G <sub>O9</sub>  | 70     |         |        | dB                  |  |
| 5 V system error amplifier open loop gain | V <sub>O5</sub>  | 70     |         |        | dB                  |  |
| 9 V system ripple                         | R <sub>P9</sub>  |        | 2       | 5      | mV <sub>pk-pk</sub> | $I_L = 100 \text{ mA}$                                   |
| 5 V system ripple                         | R <sub>P5</sub>  |        | 2       | 5      | mV <sub>pk-pk</sub> | I <sub>L</sub> = 227 mA                                  |
| M system ripple                           | R <sub>PM</sub>  | 1      | 30      | 50     | mV <sub>pk-pk</sub> | $I_L = 100 \text{ mA}$                                   |

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| Parameter   | Symbol          | Min  | Typical | Max  | Unit | Conditions                               |
|---|-----------------|------|---------|------|------|--|
| 9 V system error amplifier<br>closed loop gain      | G <sub>V9</sub> | 35   | 38      | 41   | dB   | $R_N = 10 \text{ k}\Omega$ , f = 100 kHz |
| 5 V system error amplifier<br>closed loop gain      | G <sub>V5</sub> | 34.5 | 37.5    | 40.5 | dB   | $R_N = 10 \text{ k}\Omega$ , f = 100 kHz |
| 9 V system error amplifier phase characteristics    | ф9              |      | 55      | 70   | deg  | f = 100 kHz                              |
| 5 V system error amplifier<br>phase characteristics | <b>ф</b> 5      |      | 55      | 70   | deg  | f = 100 kHz                              |

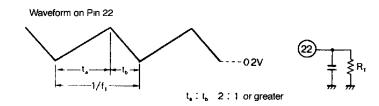
## Electrical characteristics ( $T_a = 25^{\circ}C$ , $V_{CC} = 12$ V) (Sheet 2 of 2)

### **Precautions for use**

#### **Oscillation frequency**

The maximum oscillation frequency ( $f_{OMax}$ ) is about 850 kHz. The actual triangular frequency ( $f_T$ ) is  $f_O/8$ .

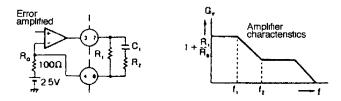
Make sure to set the resistance  $R_T$  such that in the triangular wave,  $t_a \geq 67\%$ , as shown in the figure below.



### DC gain

The 5 V and 9 V system error amplifier DC gain is determined by the feedback resistor (R1).

Make sure to use a resistor such that  $10 \text{ k}\Omega \leq R_1 \leq 100 \text{ k}\Omega$ .



#### **Error amplifier**

The motor system error amplifier DC gain is set internally as follows:

 $G_{OM1} \cong 14 \text{ dB}, G_{OM2} \cong 10 \text{ dB}, G_{OM3} = G_{OM4} \cong 10 \text{ dB},$ 

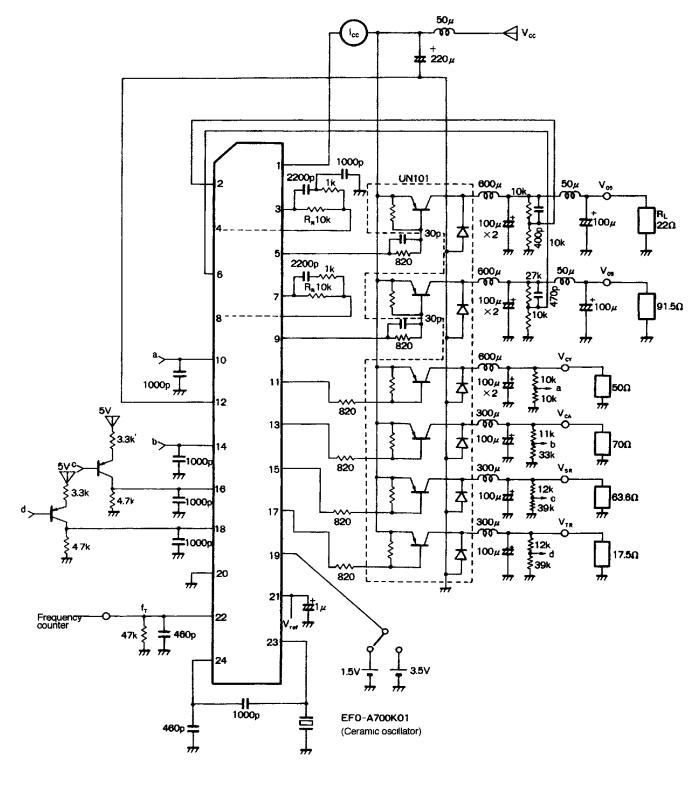
For the M3 and M4 systems, the input/output phase characteristics run in reverse.

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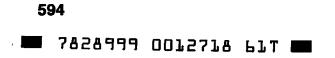
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## Figure 1 Test circuit



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