



4-MBIT (256K X 16, 512K X 8) SmartVoltage BOOT BLOCK FLASH MEMORY FAMILY

28F400BV-T/B, 28F400CV-T/B, 28F004BV-T/B

28F400CE-T/B, 28F004BE-T/B

- Intel SmartVoltage Technology
 - 5V or 12V Program/Erase
 - 2.7V, 3.3V or 5V Read Operation
 - Increased Programming Throughput at 12V V_{PP}
 - Very High-Performance Read
 - 5V: 60/80/120 ns Max. Access Time, 30/40 ns Max. Output Enable Time
 - 3V: 110/150/180 ns Max Access 65/90 ns Max. Output Enable Time
 - 2.7V: 120 ns Max Access 65 ns Max. Output Enable Time
 - Low Power Consumption
 - Max 60 mA Read Current at 5V
 - Max 30 mA Read Current at 2.7V–3.6V
 - x8/x16-Selectable Input/Output Bus
 - 28F400 for High Performance 16- or 32-bit CPUs
 - x8-Only Input/Output Architecture
 - 28F004B for Space-Constrained 8-bit Applications
 - Optimized Array Blocking Architecture
 - One 16-KB Protected Boot Block
 - Two 8-KB Parameter Blocks
 - One 96-KB Main Block
 - Three 128-KB Main Blocks
 - Top or Bottom Boot Locations
 - Absolute Hardware-Protection for Boot Block
 - Software EEPROM Emulation with Parameter Blocks
 - Extended Temperature Operation
 - -40°C to $+85^{\circ}\text{C}$
 - Extended Cycling Capability
 - 100,000 Block Erase Cycles (Commercial Temperature)
 - 10,000 Block Erase Cycles (Extended Temperature)
 - Automated Word/Byte Program and Block Erase
 - Industry-Standard Command User Interface
 - Status Registers
 - Erase Suspend Capability
 - SRAM-Compatible Write Interface
 - Automatic Power Savings Feature
 - 1 mA Typical I_{CC} Active Current in Static Operation
 - Reset/Deep Power-Down Input
 - 0.2 μA I_{CC} Typical
 - Provides Reset for Boot Operations
 - Hardware Data Protection Feature
 - Write Lockout during Power Transitions
 - Industry-Standard Surface Mount Packaging
 - 40-Lead TSOP
 - 44-Lead PSOP: JEDEC ROM Compatible
 - 48-Lead TSOP
 - 56-Lead TSOP
 - Footprint Upgradeable from 2-Mbit and to 8-Mbit Boot Block Flash Memories
 - ETOX™ IV Flash Technology
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REVISION HISTORY

| Number | Description |
|--------|---|
| -001 | Initial release of datasheet. |
| -002 | <p>Status changed from Product Preview to Preliminary 28F400CV/CE/BE references and information added throughout. 2.7V CE/BE specs added throughout.</p> <p>The following sections have been changed or rewritten: 1.1, 3.0, 3.2.1, 3.2.2, 3.3.1, 3.3.1.1, 3.3.2, 3.3.2.1, 3.3.3, 3.3.4, 3.6.2.</p> <p>Note 2 added to Figure 3 to clarify 28F008B pinout vs. 28F008SA.</p> <p>Sentence about program and erase WSM timeout deleted from Section 3.3.3, 3.3.4.</p> <p>Erroneous arrows leading out of error states deleted from flowcharts in Figs. 9, 10.</p> <p>Sections 5.1, 6.1 changed to "Applying V_{CC} Voltages." These sections completely changed to clarify V_{CC} ramp requirements.</p> <p>I_{PPD} 3.3V Commercial spec changed from 10 to 5 μA.</p> <p>Capacitance tables added after commercial and extended DC Characteristics tables.</p> <p>Test and slew rate notes added to Figs. 12, 13, 19, 20, 21.</p> <p>Test configuration drawings (Fig. 14, 22) consolidated into one, with component values in table. (Component values also rounded off).</p> <p>t_{ELFL}, t_{ELFH}, t_{AVFL} changed from 7 to 5 ns for 3.3V BV-60 commercial and 3.3V TBV-80 extended, 10 to 5 ns for 3.3V BV-80 and BV-120 commercial.</p> <p>t_{WHAX} and t_{EHAX} changed from 10 to 0 ns.</p> <p>t_{PHWL} changed from 1000 ns to 800 ns for 3.3V BV-80, BV-120 commercial.</p> <p>t_{PHL} changed from 1000 ns to 800 ns for 3.3V BV-60, BV-80, and BV-120 commercial.</p> |
| -003 | <p>28F400BE row removed from Table 1</p> <p>Applying V_{CC} voltages (Sections 5.1 and 6.1) rewritten for clarity.</p> <p>Minor cosmetic changes/edits.</p> |
| -004 | <p>Corrections: Spec typographical error "t_{QWL}" corrected to read "t_{QVVL}."</p> <p>Intel386™ EX Microprocessor block diagram updated because latest Intel386 CPU specs require less glue logic.</p> <p>Spec t_{ELFL} and t_{ELFH} changed from 5 ns (max) to 0 ns (min).</p> <p>New specs t_{PLPH} and t_{PLQX} added from Specification Update document (297595).</p> <p>Specs t_{EHQZ} and t_{GHQZ} improved on most voltage/speed combinations.</p> |
| -005 | <p>Correction: Appendix A, Ordering information fixed order numbers from TE27F400BVT80 to TE28F400BVT80 and TE27F400BVB80 to TE28F400BVB80.</p> <p>Updated disclaimer.</p> |

1.0 PRODUCT FAMILY OVERVIEW

This datasheet contains the specifications for the two branches of products in the SmartVoltage 4-Mbit boot block flash memory family: the -BE/CE suffix products feature a low V_{CC} operating range of 2.7V–3.6V; the -BV/CV suffix products offer 3.0V–3.6V operation. Both BE/CE and BV/CV products also operate at 5V for high-speed access times. Throughout this datasheet, the 28F400 refers to all x8/x16 4-Mbit products, while 28F004B refers to all x8 4-Mbit boot block products. Also, the term “2.7V” generally refers to the full voltage range 2.7V–3.6V. Section 1 provides an overview of the flash memory family including applications, pinouts and pin descriptions. Sections 2 and 3 describe the memory organization and operation for these products. Finally, Sections 4 and 5 contain the family’s operating specifications.

1.1 New Features in the SmartVoltage Products

The SmartVoltage boot block flash memory family offers identical operation with the BX/BL 12V program products, except for the differences listed below. All other functions are equivalent to current products, including signatures, write commands, and pinouts.

- WP# pin has replaced a DU (Don’t Use) pin. Connect the WP# pin to control signal or to V_{CC} or GND (in this case, a logic-level signal can be placed on DU pin). See Tables 2 and 9 to see how the WP# pin works.

- 5V program/erase operation has been added. If switching V_{PP} for write protection, switch to GND (not 5V) for complete write protection. To take advantage of 5V write-capability, allow for connecting 5V to V_{PP} and disconnecting 12V from V_{PP} line.
- Enhanced circuits optimize low V_{CC} performance, allowing operation down to $V_{CC} = 2.7V$ (using the BE product).

If you are using BX/BL 12V V_{PP} boot block products today, you should account for the differences listed above and also allow for connecting 5V to V_{PP} and disconnecting 12V from V_{PP} line, if 5V writes are desired.

1.2 Main Features

Intel’s SmartVoltage technology is the most flexible voltage solution in the flash industry, providing two discrete voltage supply pins: V_{CC} for read operation, and V_{PP} for program and erase operation. Discrete supply pins allow system designers to use the optimal voltage levels for their design. The 28F400BV/CV, 28F004BV, 28F400CE and 28F004BE provide program/erase capability at 5V or 12V. The 28F400BV/CV and 28F004BV allow reads with V_{CC} at $3.3 \pm 0.3V$ or 5V, while the 28F400CE and 28F004BE allow reads with V_{CC} at 2.7V–3.6V or 5V. Since many designs read from the flash memory a large percentage of the time, read operation using the 2.7V or 3.3V ranges can provide great power savings. If read performance is an issue, however, 5V V_{CC} provides faster read access times.

Table 1. SmartVoltage Provides Total Voltage Flexibility

| Product Name | Bus Width | V_{CC} | | | V_{PP} | |
|--------------|-----------|-----------|----------------|-------------------------------|---------------|---------------|
| | | 2.7V–3.6V | $3.3 \pm 0.3V$ | $5V \pm 5\%$ $5V \pm 10\%$ | $5V \pm 10\%$ | $12V \pm 5\%$ |
| 28F004BV-T/B | x8 | | √ | √ | √ | √ |
| 28F400BV-T/B | x8 or x16 | | √ | √ | √ | √ |
| 28F400CV-T/B | x8 or x16 | | √ | √ | √ | √ |
| 28F004BE-T/B | x8 | √ | | √ | √ | √ |
| 28F400CE-T/B | x8 or x16 | √ | | √ | √ | √ |

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For program and erase operations, 5V V_{PP} operation eliminates the need for in-system voltage converters, while 12V V_{PP} operation provides faster program and erase for situations where 12V is available, such as manufacturing or designs where 12V is in-system. For design simplicity, however, just hook up V_{CC} and V_{PP} to the same 5V \pm 10% source.

The 28F400/28F004B boot block flash memory family is a high-performance, 4-Mbit (4,194,304 bit) flash memory family organized as either 256 Kwords of 16 bits each (28F400 only) or 512 Kbytes of 8 bits each (28F400 and 28F004B).

Separately erasable blocks, including a hardware-lockable boot block (16,384 bytes), two parameter blocks (8,192 bytes each) and main blocks (one block of 98,304 bytes and three blocks of 131,072 bytes), define the boot block flash family architecture. See Figures 7 and 8 for memory maps. Each block can be independently erased and programmed 100,000 times at commercial temperature or 10,000 times at extended temperature.

The boot block is located at either the top (denoted by **-T** suffix) or the bottom (**-B** suffix) of the address map in order to accommodate different microprocessor protocols for boot code location. The hardware-lockable boot block provides complete code security for the kernel code required for system initialization. Locking and unlocking of the boot block is controlled by $WP\#$ and/or $RP\#$ (see Section 3.4 for details).

The Command User Interface (CUI) serves as the interface between the microprocessor or microcontroller and the internal operation of the boot block flash memory products. The internal Write State Machine (WSM) automatically executes the algorithms and timings necessary for program and erase operations, including verifications, thereby unburdening the microprocessor or microcontroller of these tasks. The Status Register (SR) indicates the status of the WSM and whether it successfully completed the desired program or erase operation.

Program and Erase Automation allows program and erase operations to be executed using an industry-standard two-write command sequence to the CUI. Data writes are performed in word (28F400 family) or byte (28F400 or 28F004B families) increments.

Each byte or word in the flash memory can be programmed independently of other memory locations, unlike erases, which erase all locations within a block simultaneously.

The 4-Mbit SmartVoltage boot block flash memory family is also designed with an Automatic Power Savings (APS) feature which minimizes system battery current drain, allowing for very low power designs. To provide even greater power savings, the boot block family includes a deep power-down mode which minimizes power consumption by turning most of the flash memory's circuitry off. This mode is controlled by the $RP\#$ pin and its usage is discussed in Section 3.5, along with other power consumption issues.

Additionally, the $RP\#$ pin provides protection against unwanted command writes due to invalid system bus conditions that may occur during system reset and power-up/down sequences. For example, when the flash memory powers-up, it automatically defaults to the read array mode, but during a warm system reset, where power continues uninterrupted to the system components, the flash memory could remain in a non-read mode, such as erase. Consequently, the system Reset signal should be tied to $RP\#$ to reset the memory to normal read mode upon activation of the Reset signal. See Section 3.6.

The 28F400 provides both byte-wide or word-wide input/output, which is controlled by the $BYTE\#$ pin. Please see Table 2 and Figure 16 for a detailed description of $BYTE\#$ operations, especially the usage of the DQ_{15}/A_{-1} pin.

The 28F400 products are available in a ROM/EPROM-compatible pinout and housed in the 44-lead PSOP (Plastic Small Outline) package, the 48-lead TSOP (Thin Small Outline, 1.2 mm thick) package and the 56-lead TSOP as shown in Figures 4, 5 and 6, respectively. The 28F004 products are available in the 40-lead TSOP package as shown in Figure 3.

Refer to the DC Characteristics Table, Section 5.2 (commercial temperature) and Section 6.2 (extended temperature), for complete current and voltage specifications. Refer to the AC Characteristics Table, Section 5.3 (commercial temperature) and Section 6.3 (extended temperature), for read, write and erase performance specifications.

1.3 Applications

The 4-Mbit boot block flash memory family combines high-density, low-power, high-performance, cost-effective flash memories with blocking and hardware protection capabilities. Their flexibility and versatility reduce costs throughout the product life cycle. Flash memory is ideal for Just-In-Time production flow, reducing system inventory and costs, and eliminating component handling during the production phase.

When your product is in the end-user's hands, and updates or feature enhancements become necessary, flash memory reduces the update costs by allowing user-performed code changes instead of costly product returns or technician calls.

The 4-Mbit boot block flash memory family provides full-function, blocked flash memories suitable for a wide range of applications. These applications include extended PC BIOS and ROM-able applications storage, digital cellular phone program and data storage, telecommunication boot/firmware, printer firmware/font storage and various other embedded applications where program and data storage are required.

Reprogrammable systems, such as personal computers, are ideal applications for the 4-Mbit flash memory products. Increasing software sophistication greatens the probability that a code update will be required after the PC is shipped. For example, the emerging of "plug and play" standard in desktop and portable PCs enables auto-configuration of ISA and PCI add-in cards. However, since the "plug and play" specification continues to evolve, a flash BIOS provides a cost-effective capability to update existing PCs. In addition, the parameter blocks are ideal for storing the required auto-configuration parameters, allowing you to integrate the BIOS PROM and parameter storage EEPROM into a single component, reducing parts costs while increasing functionality.

The 4-Mbit flash memory products are also excellent design solutions for digital cellular phone and telecommunication switching applications requiring very low power consumption, high-performance, high-density storage capability, modular software designs, and a small form factor package. The 4-Mbit's blocking scheme allows for easy segmentation of the embedded code with 16 Kbytes of hardware-protected boot code, four main blocks of program code and two parameter blocks of 8 Kbytes each for frequently updated data storage and diagnostic messages (e.g., phone numbers, authorization codes).

Intel's boot block architecture provides a flexible voltage solution for the different design needs of various applications. The asymmetrically-blocked memory map allows the integration of several memory components into a single flash device. The boot block provides a secure boot PROM; the parameter blocks can emulate EEPROM functionality for parameter store with proper software techniques; and the main blocks provide code and data storage with access times fast enough to execute code in place, decreasing RAM requirements.

1.4 Pinouts

Intel's SmartVoltage Boot Block architecture provides upgrade paths in every package pinout to the 8-Mbit density. The 28F004B 40-lead TSOP pinout for space-constrained designs is shown in Figure 3. The 28F400 44-lead PSOP pinout follows the industry-standard ROM/EPROM pinout, as shown in Figure 4. For designs that require x16 operation but have space concerns, refer to the 48-lead pinout in Figure 5. Furthermore, the 28F400 56-lead TSOP pinout shown in Figure 6 provides density upgrades to future higher density boot block memories.

Pinouts for the corresponding 2-Mbit and 8-Mbit components are also provided for convenient reference. 4-Mbit pinouts are given on the chip illustration in the center, with 2-Mbit and 8-Mbit pinouts going outward from the center.

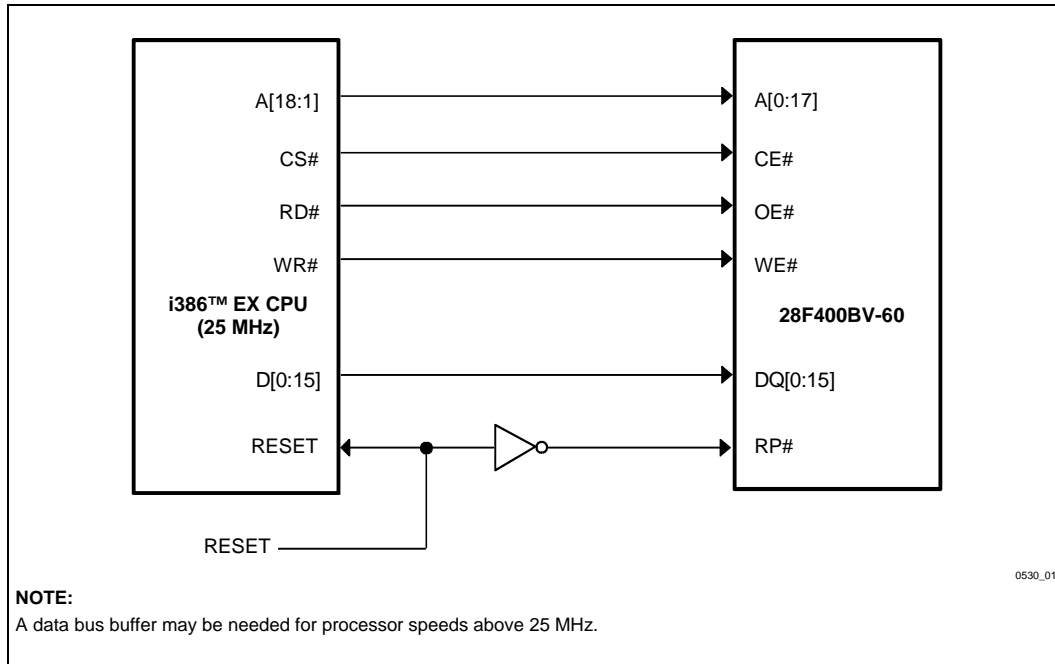


Figure 1. 28F400 Interface to Intel386™ EX Microprocessor

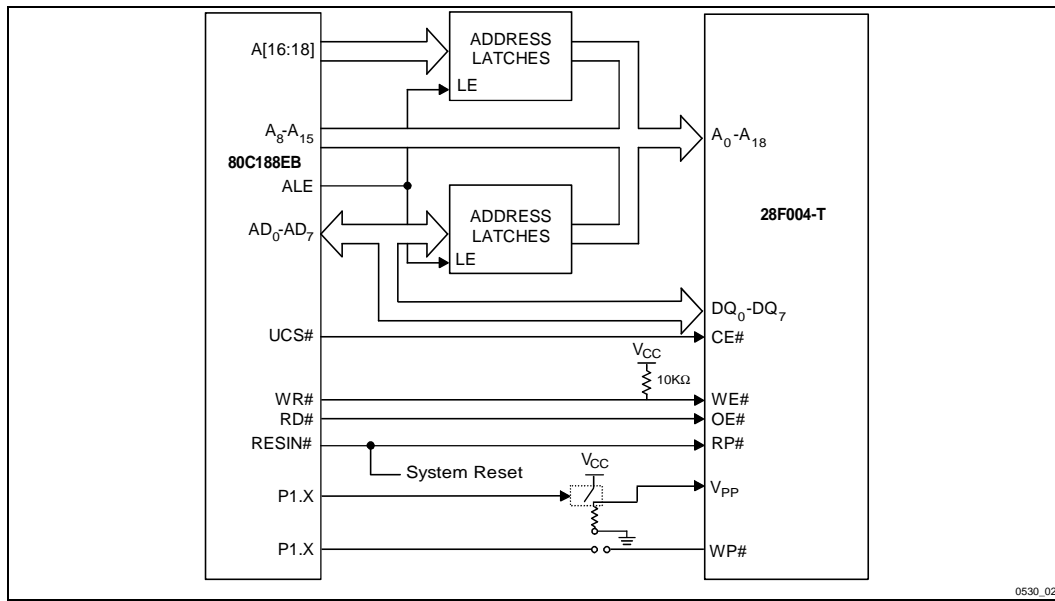


Figure 2. 28F004B Interface to Intel80C188EB 8-Bit Embedded Microprocessor

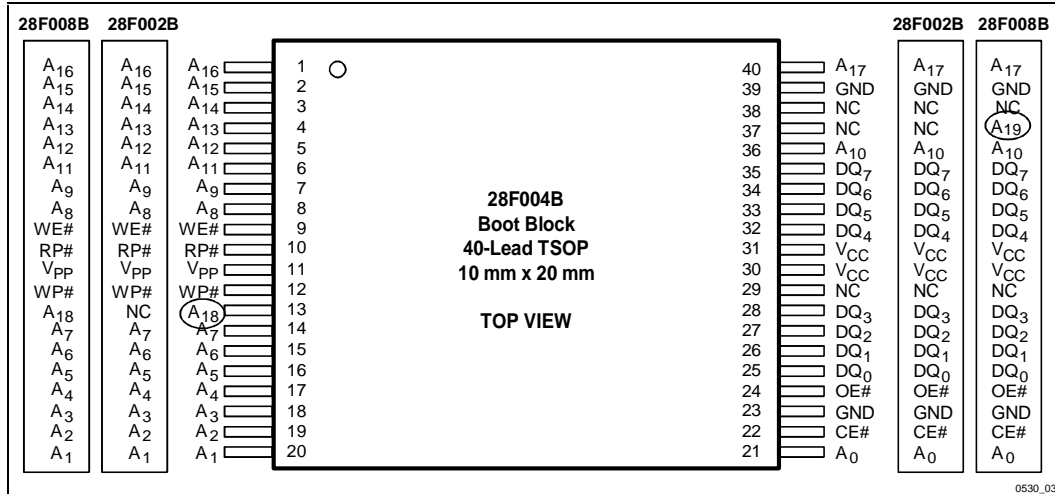
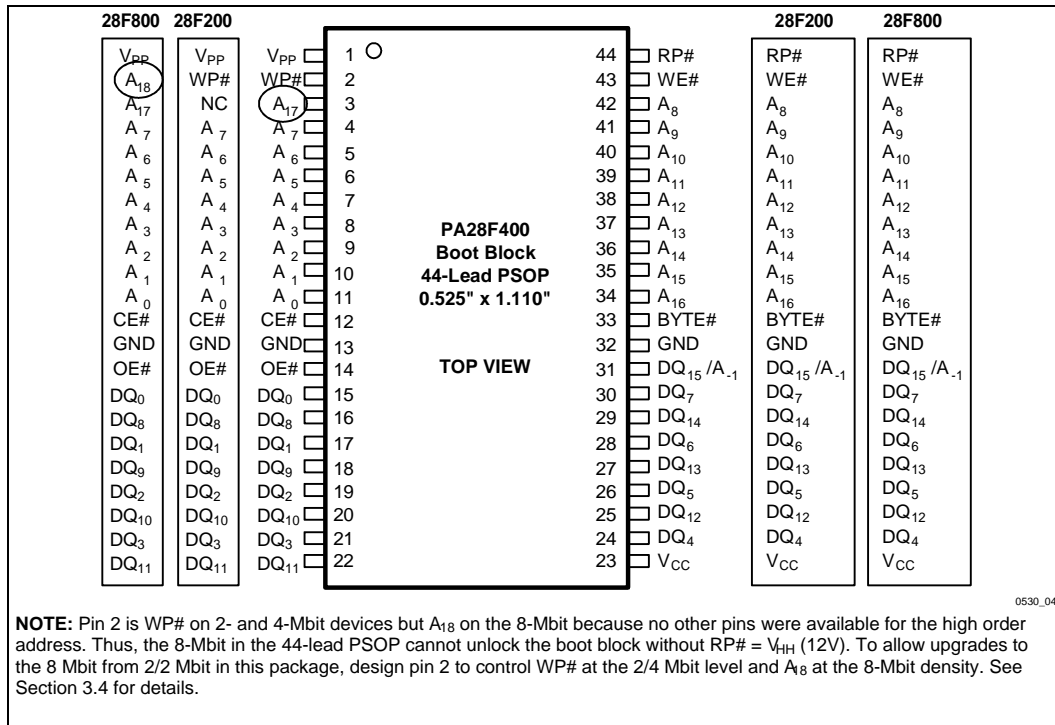


Figure 3. The 40-Lead TSOP Offers the Smallest Form Factor for Space-Constrained Applications



NOTE: Pin 2 is WP# on 2- and 4-Mbit devices but A₁₈ on the 8-Mbit because no other pins were available for the high order address. Thus, the 8-Mbit in the 44-lead PSOP cannot unlock the boot block without RP# = V_{HH} (12V). To allow upgrades to the 8 Mbit from 2/2 Mbit in this package, design pin 2 to control WP# at the 2/4 Mbit level and A₈ at the 8-Mbit density. See Section 3.4 for details.

Figure 4. The 44-Lead PSOP Offers a Convenient Upgrade from JEDEC ROM Standards

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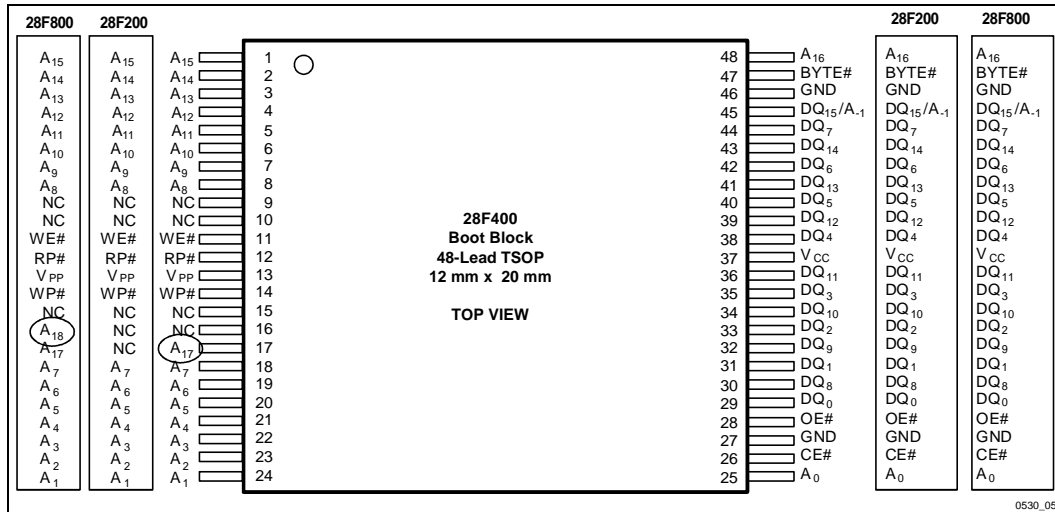


Figure 5. The 48-Lead TSOP Offers the Smallest Form Factor for x16 Operation

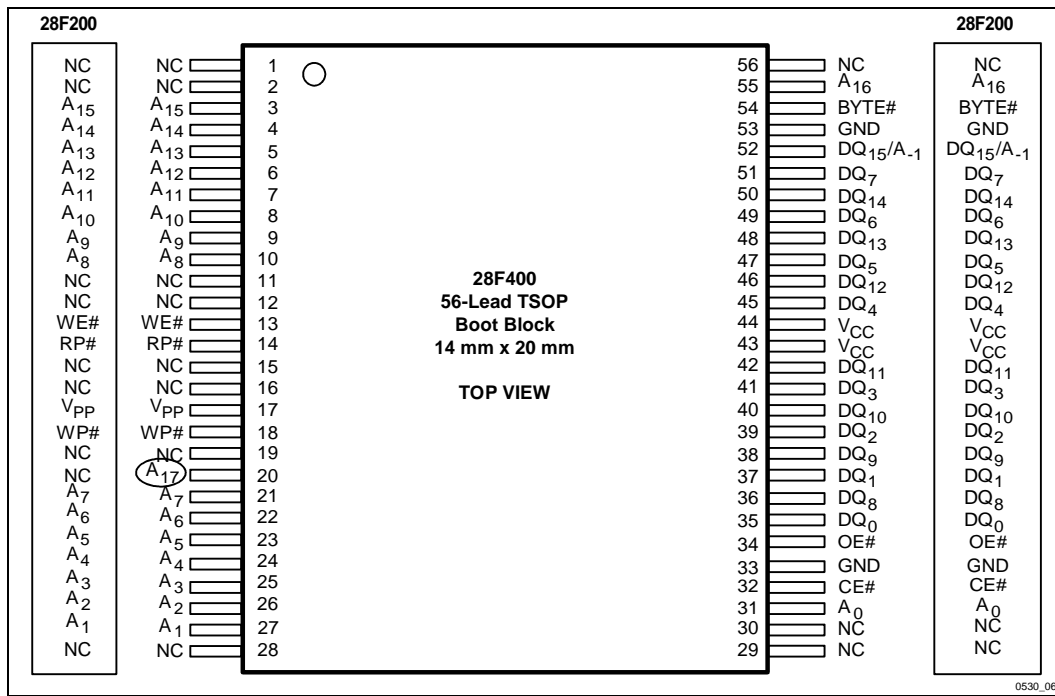


Figure 6. The 56-Lead TSOP Offers Compatibility between 2 and 4 Mbits

1.5 Pin Descriptions

Table 2. 28F400/004 Pin Descriptions

| Symbol | Type | Name and Function |
|-----------------------------------|------------------|--|
| A ₀ –A ₁₈ | INPUT | ADDRESS INPUTS for memory addresses. Addresses are internally latched during a write cycle. The 28F400 only has A₀– A₁₇ pins, while the 28F004B has A₀– A₁₈. |
| A ₉ | INPUT | ADDRESS INPUT: When A ₉ is at V _{HH} the signature mode is accessed. During this mode, A ₀ decodes between the manufacturer and device IDs. When BYTE# is at a logic low, only the lower byte of the signatures are read. DQ ₁₅ /A _{–1} is a don't care in the signature mode when BYTE# is low. |
| DQ ₀ –DQ ₇ | INPUT/ OUTPUT | DATA INPUTS/OUTPUTS: Inputs array data on the second CE# and WE# cycle during a Program command. Inputs commands to the Command User Interface when CE# and WE# are active. Data is internally latched during the write cycle. Outputs array, Intelligent Identifier and Status Register data. The data pins float to tri-state when the chip is de-selected or the outputs are disabled. |
| DQ ₈ –DQ ₁₅ | INPUT/ OUTPUT | DATA INPUTS/OUTPUTS: Inputs array data on the second CE# and WE# cycle during a Program command. Data is internally latched during the write cycle. Outputs array data. The data pins float to tri-state when the chip is de-selected or the outputs are disabled as in the byte-wide mode (BYTE# = "0"). In the byte-wide mode DQ ₁₅ /A _{–1} becomes the lowest order address for data output on DQ ₀ –DQ ₇ . The 28F004B does not include these DQ₈–DQ₁₅ pins. |
| CE# | INPUT | CHIP ENABLE: Activates the device's control logic, input buffers, decoders and sense amplifiers. CE# is active low. CE# high de-selects the memory device and reduces power consumption to standby levels. If CE# and RP# are high, but not at a CMOS high level, the standby current will increase due to current flow through the CE# and RP# input stages. |
| OE# | INPUT | OUTPUT ENABLE: Enables the device's outputs through the data buffers during a read cycle. OE# is active low. |
| WE# | INPUT | WRITE ENABLE: Controls writes to the Command Register and array blocks. WE# is active low. Addresses and data are latched on the rising edge of the WE# pulse. |
| RP# | INPUT | <p>RESET/DEEP POWER-DOWN: Uses three voltage levels (V_{IL}, V_{IH}, and V_{HH}) to control two different functions: reset/deep power-down mode and boot block unlocking. It is backwards-compatible with the BX/BL/BV products.</p> <p>When RP# is at logic low, the device is in reset/deep power-down mode, which puts the outputs at High-Z, resets the Write State Machine, and draws minimum current.</p> <p>When RP# is at logic high, the device is in standard operation. When RP# transitions from logic-low to logic-high, the device defaults to the read array mode.</p> <p>When RP# is at V_{HH}, the boot block is unlocked and can be programmed or erased. This overrides any control from the WP# input.</p> |

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Table 2. 28F400/004 Pin Descriptions (Continued)

| Symbol | Type | Name and Function |
|-----------------|-------|---|
| WP# | INPUT | <p>WRITE PROTECT: Provides a method for unlocking the boot block in a system without a 12V supply.</p> <p>When WP# is at logic low, the boot block is locked, preventing program and erase operations to the boot block. If a program or erase operation is attempted on the boot block when WP# is low, the corresponding status bit (bit 4 for program, bit 5 for erase) will be set in the Status Register to indicate the operation failed.</p> <p>When WP# is at logic high, the boot block is unlocked and can be programmed or erased.</p> <p>NOTE: This feature is overridden and the boot block unlocked when RP# is at V_{HH}. See Section 3.4 for details on write protection.</p> |
| BYTE# | INPUT | <p>BYTE# ENABLE: Not available on 28F004B. Controls whether the device operates in the byte-wide mode (x8) or the word-wide mode (x16). BYTE# pin must be controlled at CMOS levels to meet the CMOS current specification in the standby mode.</p> <p>When BYTE# is at logic low, the byte-wide mode is enabled, where data is read and programmed on DQ₀–DQ₇ and DQ₁₅/A_{–1} becomes the lowest order address that decodes between the upper and lower byte. DQ₈–DQ₁₄ are tri-stated during the byte-wide mode.</p> <p>When BYTE# is at logic high, the word-wide mode is enabled, where data is read and programmed on DQ₀–DQ₁₅.</p> |
| V _{CC} | | DEVICE POWER SUPPLY: 5.0V ± 10%, 3.3 ± 0.3V, 2.7V–3.6V (BE/CE only) |
| V _{PP} | | PROGRAM/ERASE POWER SUPPLY: For erasing memory array blocks or programming data in each block, a voltage either of 5V ± 10% or 12V ± 5% must be applied to this pin. When $V_{PP} < V_{PPLK}$ all blocks are locked and protected against Program and Erase commands. |
| GND | | GROUND: For all internal circuitry. |
| NC | | NO CONNECT: Pin may be driven or left floating. |

2.0 PRODUCT DESCRIPTION

2.1 Memory Blocking Organization

This product family features an asymmetrically-blocked architecture providing system memory integration. Each erase block can be erased independently of the others up to 100,000 times for commercial temperature or up to 10,000 times for extended temperature. The block sizes have been chosen to optimize their functionality for common applications of nonvolatile storage. The combination of block sizes in the boot block architecture allow the integration of several memories into a single chip. For the address locations of the blocks, see the memory maps in Figures 4 and 5.

2.1.1 ONE 16-KB BOOT BLOCK

The boot block is intended to replace a dedicated boot PROM in a microprocessor or microcontroller-based system. The 16-Kbyte (16,384 bytes) boot block is located at either the top (denoted by -T suffix) or the bottom (-B suffix) of the address map to accommodate different microprocessor protocols for boot code location. This boot block features hardware controllable write-protection to protect the crucial microprocessor boot code from accidental modification. The protection of the boot block is controlled using a combination of the V_{PP} , RP#, and WP# pins, as is detailed in Section 3.4.

2.1.2 TWO 8-KB PARAMETER BLOCKS

The boot block architecture includes parameter blocks to facilitate storage of frequently updated small parameters that would normally require an EEPROM. By using software techniques, the byte-rewrite functionality of EEPROMs can be emulated. These techniques are detailed in Intel's application note, *AP-604 Using Intel's Boot Block Flash Memory Parameter Blocks to Replace EEPROM*. Each boot block component contains two parameter blocks of 8 Kbytes (8,192 bytes) each. The parameter blocks are not write-protectable.

2.1.3 ONE 96-KB + THREE 128-KB MAIN BLOCKS

After the allocation of address space to the boot and parameter blocks, the remainder is divided into main blocks for data or code storage. Each 4-Mbit device contains one 96-Kbyte (98,304 byte) block and three 128-Kbyte (131,072 byte) blocks. See the memory maps for each device for more information.

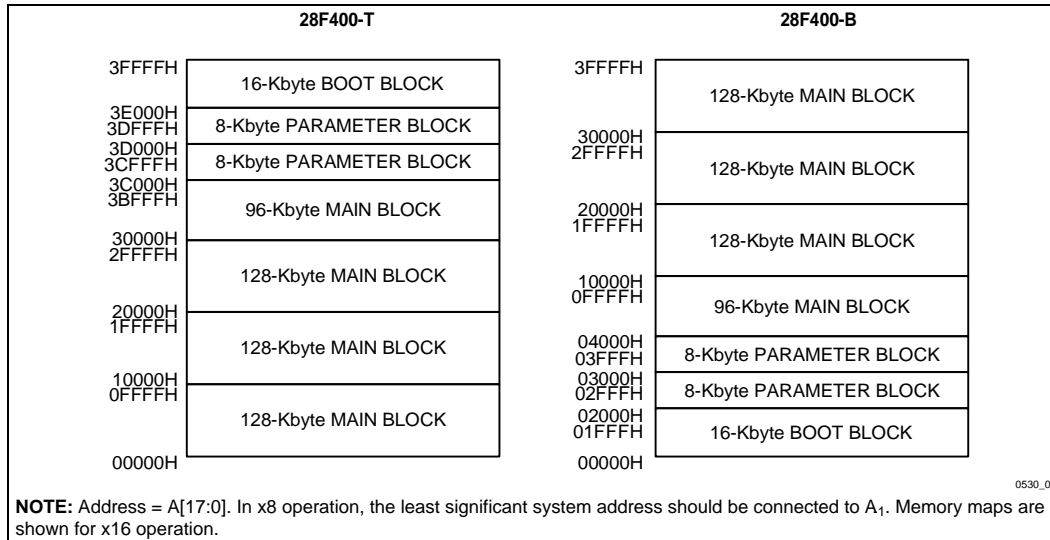


Figure 7. Word-Wide x16-Mode Memory Maps

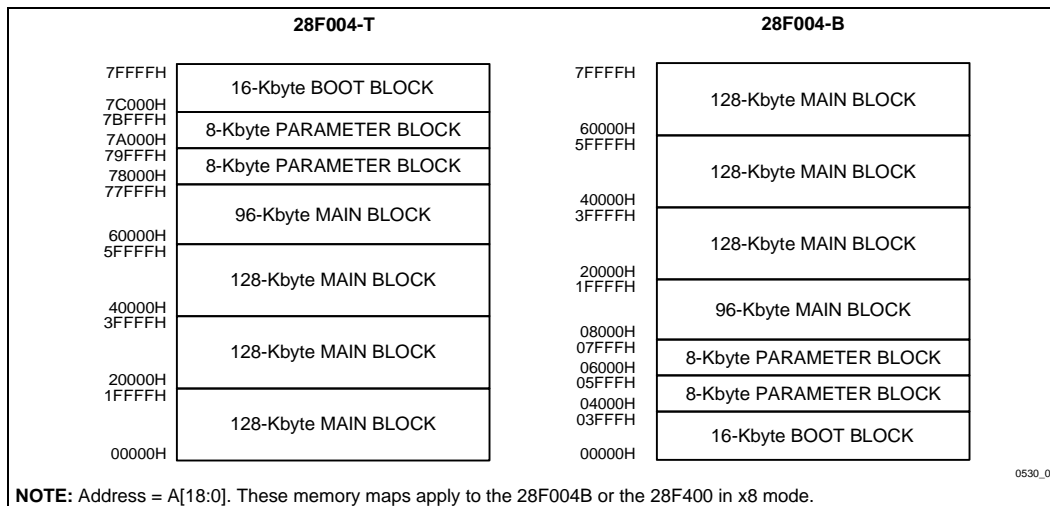


Figure 8. Byte-Wide x8-Mode Memory Maps

3.0 PRODUCT FAMILY PRINCIPLES OF OPERATION

Flash memory combines EPROM functionality with in-circuit electrical write and erase. The boot block flash family utilizes a Command User Interface (CUI) and automated algorithms to simplify write and erase operations. The CUI allows for 100% TTL-level control inputs, fixed power supplies during erasure and programming, and maximum EPROM compatibility.

When $V_{PP} < V_{PPLK}$, the device will only successfully execute the following commands: Read Array, Read Status Register, Clear Status Register and intelligent identifier mode. The device provides standard EPROM read, standby and output disable operations. Manufacturer identification and device identification data can be accessed through the CUI or through the standard EPROM A_9 high voltage access (V_{ID}) for PROM programming equipment.

The same EPROM read, standby and output disable functions are available when 5V or 12V is applied to the V_{PP} pin. In addition, 5V or 12V on V_{PP} allows write and erase of the device. All functions associated with altering memory contents: Program and Erase, Intelligent Identifier Read, and Read Status are accessed via the CUI.

The internal Write State Machine (WSM) completely automates program and erase, beginning operation signaled by the CUI and reporting status through the Status Register. The CUI handles the $WE\#$ interface to the data and address latches, as well as system status requests during WSM operation.

3.1 Bus Operations

Flash memory reads, erases and writes in-system via the local CPU. All bus cycles to or from the flash memory conform to standard microprocessor bus cycles. These bus operations are summarized in Tables 3 and 4.

3.2 Read Operations

3.2.1 READ ARRAY

When $RP\#$ transitions from V_{IL} (reset) to V_{IH} , the device will be in the read array mode and will respond to the read control inputs ($CE\#$, address inputs, and $OE\#$) without any commands being written to the CUI.

When the device is in the read array mode, five control signals must be controlled to obtain data at the outputs.

- $RP\#$ must be logic high (V_{IH})
- $WE\#$ must be logic high (V_{IH})
- $BYTE\#$ must be logic high or logic low
- $CE\#$ must be logic low (V_{IL})
- OE must be logic low (V_{IL})

In addition, the address of the desired location must be applied to the address pins. Refer to Figures 15 and 16 for the exact sequence and timing of these signals.

If the device is not in read array mode, as would be the case after a program or erase operation, the Read Mode command (FFH) must be written to the CUI before reads can take place.

During system design, consideration should be taken to ensure address and control inputs meet required input slew rates of <10 ns as defined in Figures 12 and 13.

Table 3. Bus Operations for Word-Wide Mode (BYTE# = V_{IH})

| Mode | Notes | RP# | CE# | OE# | WE# | A ₉ | A ₀ | V _{PP} | DQ ₀₋₁₅ |
|---------------------------------|-------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|--------------------|
| Read | 1,2,3 | V _{IH} | V _{IL} | V _{IL} | V _{IH} | X | X | X | D _{OUT} |
| Output Disable | | V _{IH} | V _{IL} | V _{IH} | V _{IH} | X | X | X | High Z |
| Standby | | V _{IH} | V _{IH} | X | X | X | X | X | High Z |
| Deep Power-Down | 9 | V _{IL} | X | X | X | X | X | X | High Z |
| Intelligent Identifier (Mfr) | 4 | V _{IH} | V _{IL} | V _{IL} | V _{IH} | V _{ID} | V _{IL} | X | 0089 H |
| Intelligent Identifier (Device) | 4,5 | V _{IH} | V _{IL} | V _{IL} | V _{IH} | V _{ID} | V _{IH} | X | See Table 5 |
| Write | 6,7,8 | V _{IH} | V _{IL} | V _{IH} | V _{IL} | X | X | X | D _{IN} |

Table 4. Bus Operations for Byte-Wide Mode (BYTE# = V_{IL})

| Mode | Notes | RP# | CE# | OE# | WE# | A ₉ | A ₀ | A ₋₁ | V _{PP} | DQ ₀₋₇ | DQ ₈₋₁₄ |
|---------------------------------|-------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-------------------|--------------------|
| Read | 1,2,3 | V _{IH} | V _{IL} | V _{IL} | V _{IH} | X | X | X | X | D _{OUT} | High Z |
| Output Disable | | V _{IH} | V _{IL} | V _{IH} | V _{IH} | X | X | X | X | High Z | High Z |
| Standby | | V _{IH} | V _{IH} | X | X | X | X | X | X | High Z | High Z |
| Deep Power-Down | 9 | V _{IL} | X | X | X | X | X | X | X | High Z | High Z |
| Intelligent Identifier (Mfr) | 4 | V _{IH} | V _{IL} | V _{IL} | V _{IH} | V _{ID} | V _{IL} | X | X | 89H | High Z |
| Intelligent Identifier (Device) | 4,5 | V _{IH} | V _{IL} | V _{IL} | V _{IH} | V _{ID} | V _{IH} | X | X | See Table 5 | High Z |
| Write | 6,7,8 | V _{IH} | V _{IL} | V _{IH} | V _{IL} | X | X | X | X | D _{IN} | High Z |

NOTES:

1. Refer to DC Characteristics.
2. X can be V_{IL}, V_{IH} for control pins and addresses, V_{PPLK} or V_{PPH} for V_{PP}.
3. See DC Characteristics for V_{PPLK}, V_{PPH1}, V_{PPH2}, V_{HH}, V_{ID} voltages.
4. Manufacturer and device codes may also be accessed via a CUI write sequence, A_{1-A17} = X, A_{1-A18} = X.
5. See Table 5 for device IDs.
6. Refer to Table 7 for valid D_{IN} during a write operation.
7. Command writes for block erase or word/byte program are only executed when V_{PP} = V_{PPH1} or V_{PPH2}.
8. To write or erase the boot block, hold RP# at V_{HH} or WP# at V_{IH}. See Section 3.4.
9. RP# must be at GND ± 0.2V to meet the maximum deep power-down current specified.

3.2.2 INTELLIGENT IDENTIFIERS

To read the manufacturer and device codes, the device must be in intelligent identifier read mode, which can be reached using two methods: by writing the intelligent identifier command (90H) or by taking the A₉ pin to V_{DD}. Once in intelligent identifier read mode, A₀ = 0 outputs the manufacturer's identification code and A₀ = 1 outputs the device code. In byte-wide mode, only the lower byte of the above signatures is read (DQ₁₅/A₋₁ is a "don't care" in this mode). See Table 5 for product signatures. To return to read array mode, write a Read Array command (FFH).

Table 5. Intelligent Identifier Table

| Product | Mfr. ID | Device ID | |
|---------|---------|------------------|---------------------|
| | | -T (Top Boot) | -B (Bottom Boot) |
| 28F400 | 0089 H | 4470 H | 4471 H |
| 28F004 | 89 H | 78 H | 79 H |

3.3 Write Operations
3.3.1 COMMAND USER INTERFACE (CUI)

The Command User Interface (CUI) is the interface between the microprocessor and the internal chip controller. Commands are written to the CUI using standard microprocessor write timings. The available commands are Read Array, Read Intelligent Identifier, Read Status Register, Clear Status Register, Erase and Program (summarized in Tables 6 and 7). The three read modes are read array, intelligent identifier read, and status register read. For Program or Erase commands, the CUI informs the Write State Machine (WSM) that a write or erase has been requested. During the execution of a Program command, the WSM will control the programming sequences and the CUI will only respond to status reads. During an erase cycle, the CUI will respond to status reads and erase suspend. After the WSM has completed its task, it will set the WSM Status bit to a "1" (ready), which indicates that the CUI can respond to its full command set. Note that after the WSM has returned control to the CUI, the CUI will stay in the current command state until it receives another command.

3.3.1.1 Command Function Description

Device operations are selected by writing specific commands into the CUI. Tables 6 and 7 define the available commands.

Table 6. Command Codes and Descriptions

| Code | Device Mode | Description |
|------|--------------------------------|--|
| 00 | Invalid/ Reserved | Unassigned commands that should not be used. Intel reserves the right to redefine these codes for future functions. |
| FF | Read Array | Places the device in read array mode, so that array data will be output on the data pins. |
| 40 | Program Set-Up | <p>Sets the CUI into a state such that the next write will latch the Address and Data registers on the rising edge and begin the program algorithm. The device then defaults to the read status mode, where the device outputs Status Register data when OE# is enabled. To read the array, issue a Read Array command.</p> <p>To cancel a program operation after issuing a Program Set-Up command, write all 1's (FFH for x8, FFFFH for x16) to the CUI. This will return to read status register mode after a standard program time without modifying array contents. If a program operation has already been initiated to the WSM this command can not cancel that operation in progress.</p> |
| 10 | Alternate Prog Set-Up | (See 40H/Program Set-Up) |
| 20 | Erase Set-Up | Prepares the CUI for the Erase Confirm command. If the next command is not an Erase Confirm command, then the CUI will set both the Program Status (SR.4) and Erase Status (SR.5) bits of the Status Register to a "1," place the device into the read Status Register state, and wait for another command without modifying array contents. This can be used to cancel an erase operation after the Erase Setup command has been issued. If an operation has already been initiated to the WSM this can not cancel that operation in progress. |
| D0 | Erase Resume/ Erase Confirm | If the previous command was an Erase Set-Up command, then the CUI will latch address and data, and begin erasing the block indicated on the address pins. During erase, the device will respond only to the Read Status Register and Erase Suspend commands and will output Status Register data when OE# is toggled low. Status Register data is updated by toggling either OE# or CE# low. |
| B0 | Erase Suspend | Valid only while an erase operation is in progress and will be ignored in any other circumstance. Issuing this command will begin to suspend erase operation. The Status Register will indicate when the device reaches erase suspend mode. In this mode, the CUI will respond only to the Read Array, Read Status Register, and Erase Resume commands and the WSM will also set the WSM Status bit to a "1" (ready). The WSM will continue to idle in the SUSPEND state, regardless of the state of all input control pins except RP#, which will immediately shut down the WSM and the remainder of the chip, if it is made active. During a suspend operation, the data and address latches will remain closed, but the address pads are able to drive the address into the read path. See Section 3.3.4.1. |
| 70 | Read Status Register | Puts the device into the read Status Register mode, so that reading the device outputs Status Register data, regardless of the address presented to the device. The device automatically enters this mode after program or erase has completed. This is one of the two commands that is executable while the WSM is operating. See Section 3.3.2. |

Table 6. Command Codes and Descriptions (Continued)

| Code | Device Mode | Description |
|------|------------------------|---|
| 50 | Clear Status Register | The WSM can only set the Program Status and Erase Status bits in the Status Register to "1;" it cannot clear them to "0." The Status Register operates in this fashion for two reasons. The first is to give the host CPU the flexibility to read the status bits at any time. Second, when programming a string of bytes, a single Status Register query after programming the string may be more efficient, since it will return the accumulated error status of the entire string. See Section 3.3.2.1. |
| 90 | Intelligent Identifier | Puts the device into the intelligent identifier read mode, so that reading the device will output the manufacturer and device codes. ($A_0 = 0$ for manufacturer, $A_0 = 1$ for device, all other address inputs are ignored). See Section 3.2.2. |

Table 7. Command Bus Definitions

| Command | Note | First Bus Cycle | | | Second Bus Cycle | | |
|-----------------------------|------|-----------------|------|------|------------------|------|------|
| | | Oper | Addr | Data | Oper | Addr | Data |
| Read Array | 8 | Write | X | FFH | | | |
| Intelligent Identifier | 1 | Write | X | 90H | Read | IA | IID |
| Read Status Register | 2,4 | Write | X | 70H | Read | X | SRD |
| Clear Status Register | 3 | Write | X | 50H | | | |
| Word/Byte Program | | Write | PA | 40H | Write | PA | PD |
| Alternate Word/Byte Program | 6,7 | Write | PA | 10H | Write | PA | PD |
| Block Erase/Confirm | 6,7 | Write | BA | 20H | Write | BA | D0H |
| Erase Suspend | 5 | Write | X | B0H | | | |
| Erase Resume | | Write | X | D0H | | | |

ADDRESS

BA = Block Address
 IA = Identifier Address
 PA = Program Address
 X = Don't Care

DATA

SRD = Status Register Data
 IID = Identifier Data
 PD = Program Data

NOTES:

1. Bus operations are defined in Tables 3 and 4.
2. IA = Identifier Address: $A_0 = 0$ for manufacturer code, $A_0 = 1$ for device code.
3. SRD - Data read from Status Register.
4. IID = Intelligent Identifier Data. Following the Intelligent Identifier command, two read operations access manufacturer and device codes.
5. BA = Address within the block being erased.
6. PA = Address to be programmed. PD = Data to be programmed at location PA.
7. Either 40H or 10H commands is valid.
8. When writing commands to the device, the upper data bus $[DQ_8-DQ_{15}] = X$ (28F400 only) which is either V_{IL} or V_{IH} , to minimize current draw.

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Table 8. Status Register Bit Definition

| WSMS | ESS | ES | DWS | VPPS | R | R | R |
|---|-----|----|-----|--|---|---|---|
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| NOTES: | | | | | | | |
| SR.7 = WRITE STATE MACHINE STATUS 1 = Ready (WSMS) 0 = Busy | | | | Check Write State Machine bit first to determine Word/Byte program or Block Erase completion, before checking Program or Erase Status bits. | | | |
| SR.6 = ERASE-SUSPEND STATUS (ESS) 1 = Erase Suspended 0 = Erase In Progress/Completed | | | | When Erase Suspend is issued, WSM halts execution and sets both WSMS and ESS bits to "1." ESS bit remains set to "1" until an Erase Resume command is issued. | | | |
| SR.5 = ERASE STATUS (ES) 1 = Error In Block Erasure 0 = Successful Block Erase | | | | When this bit is set to "1," WSM has applied the max number of erase pulses to the block and is still unable to verify successful block erasure. | | | |
| SR.4 = PROGRAM STATUS (DWS) 1 = Error in Byte/Word Program 0 = Successful Byte/Word Program | | | | When this bit is set to "1," WSM has attempted but failed to program a byte or word. | | | |
| SR.3 = V _{PP} STATUS (VPPS) 1 = V _{PP} Low Detect, Operation Abort 0 = V _{PP} OK | | | | The V _{PP} Status bit does not provide continuous indication of V _{PP} level. The WSM interrogates V _{PP} level only after the Byte Write or Erase command sequences have been entered, and informs the system if V _{PP} has not been switched on. The V _{PP} Status bit is not guaranteed to report accurate feedback between V _{PP} and V _{PPH} . | | | |
| SR.2-SR.0 = RESERVED FOR FUTURE ENHANCEMENTS (R) | | | | These bits are reserved for future use and should be masked out when polling the Status Register. | | | |

3.3.2 STATUS REGISTER

The device Status Register indicates when a program or erase operation is complete, and the success or failure of that operation. To read the Status Register write the Read Status (70H) command to the CUI. This causes all subsequent read operations to output data from the Status Register until another command is written to the CUI. To return to reading from the array, issue a Read Array (FFH) command.

The Status Register bits are output on DQ₀–DQ₇, in both byte-wide (x8) or word-wide (x16) mode. In the word-wide mode the upper byte, DQ₈–DQ₁₅, outputs 00H during a Read Status command. In the byte-wide mode, DQ₈–DQ₁₄ are tri-stated and DQ₁₅/A_{–1} retains the low order address function.

Important: The contents of the Status Register are latched on the falling edge of OE# or CE#, whichever occurs last in the read cycle. This prevents possible bus errors which might occur if Status Register contents change while being read. CE# or OE# must be toggled with each subsequent status read, or the Status Register will not indicate completion of a program or erase operation.

When the WSM is active, the SR.7 register will indicate the status of the WSM, and will also hold the bits indicating whether or not the WSM was successful in performing the desired operation.

3.3.2.1 Clearing the Status Register

The WSM sets status bits 3 through 7 to “1,” and clears bits 6 and 7 to “0,” but cannot clear status bits 3 through 5 to “0.” Bits 3 through 5 can only be cleared by the controlling CPU through the use of the Clear Status Register (50H) command, because these bits indicate various error conditions. By allowing the system software to control the resetting of these bits, several operations may be performed (such as cumulatively programming several bytes or erasing multiple blocks in sequence) before reading the Status Register to determine if an error occurred during that series. Clear the Status Register before beginning another command or sequence. Note, again, that a Read Array command must be issued before data can be read from the memory or intelligent identifier.

3.3.3 PROGRAM MODE

Programming is executed using a two-write sequence. The Program Setup command is written to the CUI followed by a second write which specifies the address and data to be programmed. The WSM will execute a sequence of internally timed events to:

1. Program the desired bits of the addressed memory word or byte.
2. Verify that the desired bits are sufficiently programmed.

Programming of the memory results in specific bits within a byte or word being changed to a “0.”

If the user attempts to program “1”s, there will be no change of the memory cell content and no error occurs.

The Status Register indicates programming status: while the program sequence is executing, bit 7 of the Status Register is a “0.” The Status Register can be polled by toggling either CE# or OE#. While programming, the only valid command is Read Status Register.

When programming is complete, the Program Status bits should be checked. If the programming operation was unsuccessful, bit 4 of the Status Register is set to a “1” to indicate a Program Failure. If bit 3 is set to a “1,” then V_{PP} was not within acceptable limits, and the WSM did not execute the programming sequence.

The Status Register should be cleared before attempting the next operation. Any CUI instruction can follow after programming is completed; however, reads from the Memory Array or Intelligent Identifier cannot be accomplished until the CUI is given the appropriate command.

3.3.4 ERASE MODE

To erase a block, write the Erase Set-Up and Erase Confirm commands to the CUI, along with the addresses identifying the block to be erased. These addresses are latched internally when the Erase Confirm command is issued. Block erasure results in all bits within the block being set to “1.” Only one block can be erased at a time.

The WSM will execute a sequence of internally timed events to:

1. Program all bits within the block to “0.”
2. Verify that all bits within the block are sufficiently programmed to “0.”
3. Erase all bits within the block to “1.”
4. Verify that all bits within the block are sufficiently erased.

While the erase sequence is executing, bit 7 of the Status Register is a “0.”

When the Status Register indicates that erasure is complete, check the Erase Status bit to verify that the erase operation was successful. If the Erase operation was unsuccessful, bit 5 of the Status Register will be set to a “1,” indicating an Erase Failure. If V_{PP} was not within acceptable limits after the Erase Confirm command is issued, the WSM will not execute an erase sequence; instead, bit 5 of the Status Register is set to a “1” to indicate an Erase Failure, and bit 3 is set to a “1” to identify that V_{PP} supply voltage was not within acceptable limits.

Clear the Status Register before attempting the next operation. Any CUI instruction can follow after erasure is completed; however, reads from the Memory Array, Status Register, or Intelligent Identifier cannot be accomplished until the CUI is given the Read Array command.

3.3.4.1 Suspending and Resuming Erase

Since an erase operation requires on the order of seconds to complete, an Erase Suspend command is provided to allow erase-sequence interruption in order to read data from another block of the memory. Once the erase sequence is started, writing the Erase Suspend command to the CUI requests that the WSM pause the erase sequence at a predetermined point in the erase algorithm. The Status Register will indicate if/when the erase operation has been suspended.

At this point, a Read Array command can be written to the CUI in order to read data from blocks other than that which is being suspended. The only other valid command at this time is the Erase Resume command or Read Status Register command.

During erase suspend mode, the chip can go into a pseudo-standby mode by taking CE# to V_{IH}, which reduces active current draw.

To resume the erase operation, enable the chip by taking CE# to V_{IL}, then issuing the Erase Resume command, which continues the erase sequence to completion. As with the end of a standard erase operation, the Status Register must be read, cleared, and the next instruction issued in order to continue.

3.4 Boot Block Locking

The boot block family architecture features a hardware-lockable boot block so that the kernel code for the system can be kept secure while the parameter and main blocks are programmed and erased independently as necessary. Only the boot block can be locked independently from the other blocks. The truth table, Table 9, clearly defines the write protection methods.

3.4.1 V_{PP} = V_{IL} FOR COMPLETE PROTECTION

For complete write protection of all blocks in the flash device, the V_{PP} programming voltage can be held low. When V_{PP} is below V_{PPLK}, any program or erase operation will result in a error in the Status Register.

3.4.2 WP# = V_{IL} FOR BOOT BLOCK LOCKING

When WP# = V_{IL}, the boot block is locked and any program or erase operation to the boot block will result in an error in the Status Register. All other blocks remain unlocked in this condition and can be programmed or erased normally. Note that this feature is overridden and the boot block unlocked when RP# = V_{HH}.

3.4.3 RP# = V_{HH} OR WP# = V_{IH} FOR BOOT BLOCK UNLOCKING

Two methods can be used to unlock the boot block:

1. WP# = V_{IH}
2. RP# = V_{HH}

If both or either of these two conditions are met, the boot block will be unlocked and can be programmed or erased.

3.4.4 UPGRADE NOTE FOR 8-MBIT 44-PSOP PACKAGE

If upgradability to 8M is required, note that the 8-Mbit in the 44-PSOP does not have a WP# because no pins were available for the 8-Mbit upgrade address. Thus, in this density-package combination only, V_{HH} (12V) on RP# is required to unlock the boot block. Unlocking with a logic-level signal is not possible. If this functionality is required, and 12V is not available, consider using the 48-TSOP package, which has a WP# pin and can be unlocked with a logic-level signal. All other density-package combinations have WP# pins.

Table 9. Write Protection Truth Table

| V _{PP} | RP# | WP# | Write Protection Provided |
|---------------------|-----------------|-----------------|---------------------------|
| V _{IL} | X | X | All Blocks Locked |
| ≥ V _{PPLK} | V _{IL} | X | All Blocks Locked (Reset) |
| ≥ V _{PPLK} | V _{HH} | X | All Blocks Unlocked |
| ≥ V _{PPLK} | V _{IH} | V _{IL} | Boot Block Locked |
| ≥ V _{PPLK} | V _{IH} | V _{IH} | All Blocks Unlocked |



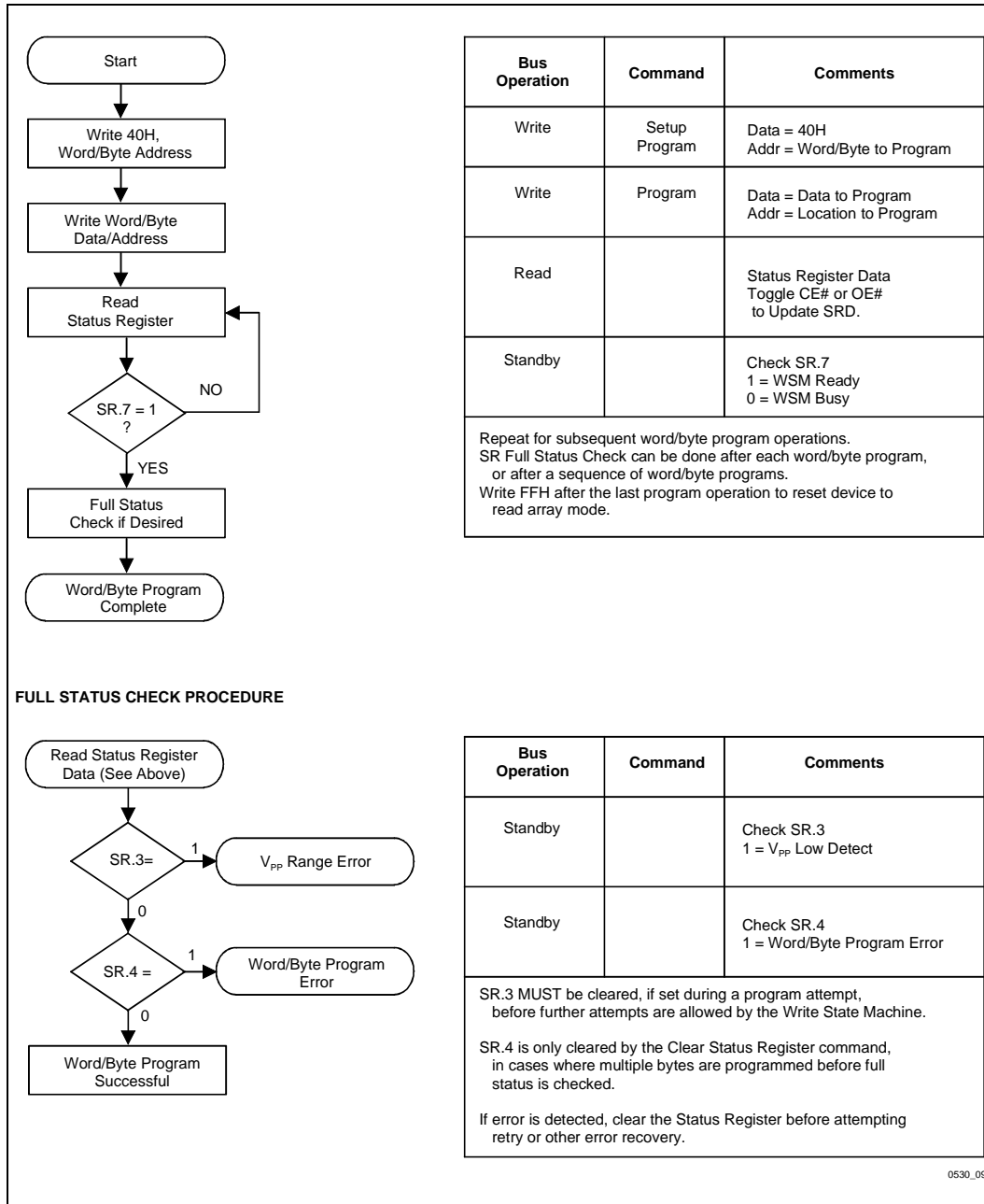


Figure 9. Automated Word/Byte Programming Flowchart

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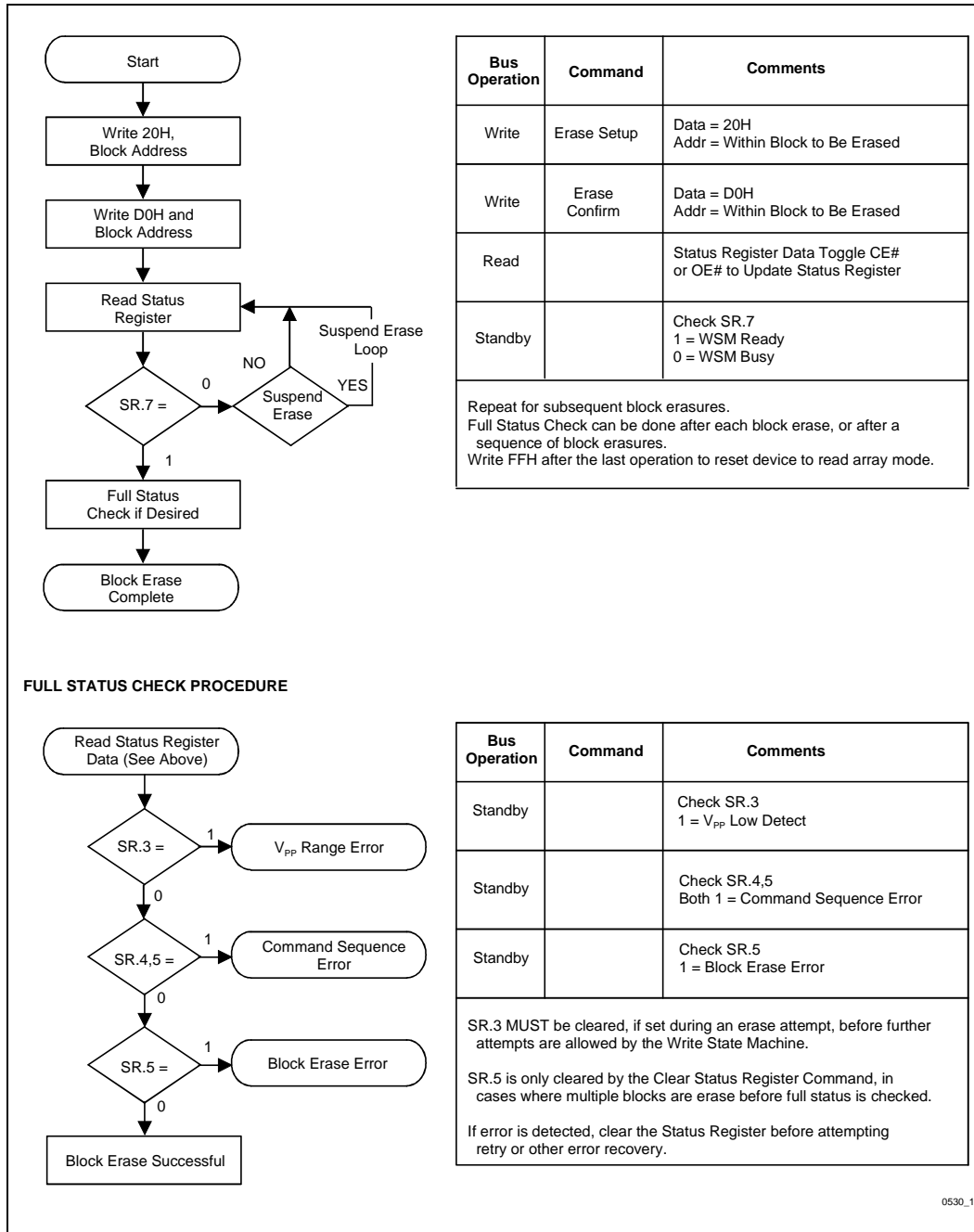


Figure 10. Automated Block Erase Flowchart

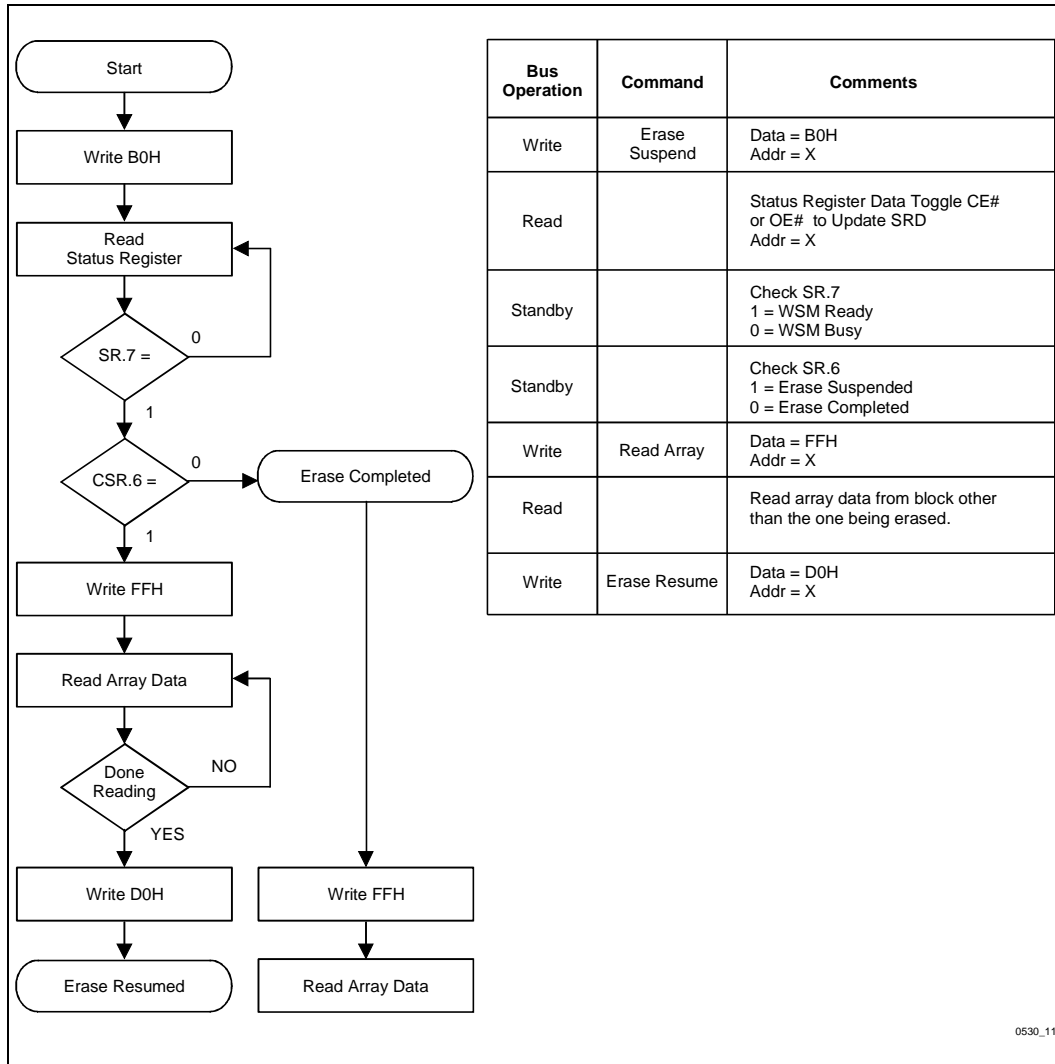


Figure 11. Erase Suspend/Resume Flowchart

3.5 Power Consumption

3.5.1 ACTIVE POWER

With CE# at a logic-low level and RP# at a logic-high level, the device is placed in the active mode. Refer to the DC Characteristics table for I_{CC} current values.

3.5.2 AUTOMATIC POWER SAVINGS (APS)

Automatic Power Savings (APS) provides low-power operation during active mode. Power Reduction Control (PRC) circuitry allows the device to put itself into a low current state when not being accessed. After data is read from the memory array, PRC logic controls the device's power consumption by entering the APS mode where typical I_{CC} current is less than 1 mA. The device stays in this static state with outputs valid until a new location is read.

3.5.3 STANDBY POWER

With CE# at a logic-high level (V_{IH}), and the CUI in read mode, the memory is placed in standby mode, which disables much of the device's circuitry and substantially reduces power consumption. Outputs (DQ₀–DQ₁₅ or DQ₀–DQ₇) are placed in a high-impedance state independent of the status of the OE# signal. When CE# is at logic-high level during erase or program operations, the device will continue to perform the operation and consume corresponding active power until the operation is completed.

3.5.4 DEEP POWER-DOWN MODE

The SmartVoltage boot block family supports a low typical I_{CC} in deep power-down mode, which turns off all circuits to save power. This mode is activated by the RP# pin when it is at a logic-low (GND ± 0.2V). Note: BYTE# pin must be at CMOS levels to meet the I_{CCD} specification.

During read modes, the RP# pin going low de-selects the memory and places the output drivers in a high impedance state. Recovery from the deep power-down state, requires a minimum access time of t_{PHQV} (see AC Characteristics table).

During erase or program modes, RP# low will abort either erase or program operations, but the memory contents are no longer valid as the data has been corrupted by the RP# function. As in the read mode above, all internal circuitry is turned off to achieve the power savings.

RP# transitions to V_{IL}, or turning power off to the device will clear the Status Register.

3.6 Power-Up/Down Operation

The device is protected against accidental block erasure or programming during power transitions. Power supply sequencing is not required, since the device is indifferent as to which power supply, V_{PP} or V_{CC}, powers-up first. The CUI is reset to the read mode after power-up, but the system must drop CE# low or present a new address to ensure valid data at the outputs.

A system designer must guard against spurious writes when V_{CC} voltages are above V_{LKO} and V_{PP} is active. Since both WE# and CE# must be low for a command write, driving either signal to V_{IH} will inhibit writes to the device. The CUI architecture provides additional protection since alteration of memory contents can only occur after successful completion of the two-step command sequences. The device is also disabled until RP# is brought to V_{IH}, regardless of the state of its control inputs. By holding the device in reset (RP# connected to system PowerGood) during power-up/down, invalid bus conditions during power-up can be masked, providing yet another level of memory protection.

3.6.1 RP# CONNECTED TO SYSTEM RESET

The use of RP# during system reset is important with automated write/erase devices because the system expects to read from the flash memory when it comes out of reset. If a CPU reset occurs without a flash memory reset, proper CPU initialization would not occur because the flash memory may be providing status information instead of array data. Intel's Flash memories allow proper CPU initialization following a system reset by connecting the RP# pin to the same RESET# signal that resets the system CPU.

3.6.2 V_{CC}, V_{PP} AND RP# TRANSITIONS

The CUI latches commands as issued by system software and is not altered by V_{PP} or CE# transitions or WSM actions. Its default state upon power-up, after exit from deep power-down mode, or after V_{CC} transitions above V_{LKO} (Lockout voltage), is read array mode.

After any word/byte write or block erase operation is complete and even after V_{PP} transitions down to V_{PPLK}, the CUI must be reset to read array mode via the Read Array command if accesses to the flash memory are desired.

Please refer to Intel's application note *AP-617 Additional Flash Data Protection Using V_{PP}, RP#, and WP#*, for a circuit-level description of how to implement the protection discussed in Section 3.6.

3.7 Power Supply Decoupling

Flash memory's power switching characteristics require careful device decoupling methods. System designers should consider three supply current issues:

1. Standby current levels (I_{CCS})
2. Active current levels (I_{CCR})
3. Transient peaks produced by falling and rising edges of CE#.

Transient current magnitudes depend on the device outputs' capacitive and inductive loading. Two-line control and proper decoupling capacitor selection will suppress these transient voltage peaks. Each flash device should have a 0.1 μF ceramic capacitor connected between each V_{CC} and GND, and between its V_{PP} and GND. These high-frequency, inherently low-inductance capacitors should be placed as close as possible to the package leads.

3.7.1 V_{PP} TRACE ON PRINTED CIRCUIT BOARDS

Designing for in-system writes to the flash memory requires special consideration of the V_{PP} power supply trace by the printed circuit board designer. The V_{PP} pin supplies the flash memory cells current for programming and erasing. One should use similar trace widths and layout considerations given to the V_{CC} power supply trace. Adequate V_{PP} supply traces, and decoupling capacitors placed adjacent to the component, will decrease spikes and overshoots.

NOTE:

Table headings in Sections 5 and 6 (i.e., BV-60, BV-80, BV-120, TBV-80, TBE-120) refer to the specific products listed below. See Appendix A for more information on product naming and line items.

| Abbreviation | Applicable Product Names |
|--------------|--|
| BV-60 | E28F004BV-T60, E28F004BV-B60, PA28F400BV-T60, PA28F400BV-B60, E28F400CV-T60, E28F400CV-B60, E28F400BV-T60, E28F400BV-B60 |
| BV-80 | E28F004BV-T80, E28F004BV-B80, PA28F400BV-T80, PA28F400BV-B80, E28F400CV-T80, E28F400CV-B80, E28F400BV-T80, E28F400BV-B80 |
| BV-120 | E28F004BV-T120, E28F004BV-B120, PA28F400BV-T120, PA28F400BV-B120 |
| TBV-80 | TE28F004BV-T80, TE28F004BV-B80, TB28F400BV-T80, TB28F400BV-B80, TE28F400CV-T80, TE28F400CV-B80, TE28F400BV-T80, TE28F400BV-B80 |
| TBE-120 | TE28F004BE-T120, TE28F004BE-B120, TE28F400CE-T120, TE28F400CE-B120 |

4.0 ABSOLUTE MAXIMUM RATINGS*

Commercial Operating Temperature

During Read0°C to +70°C

During Block Erase
and Word/Byte Program0°C to +70°C

Temperature Bias-10°C to +80°C

Extended Operating Temperature

During Read-40°C to +85°C

During Block Erase
and Word/Byte Program-40°C to +85°C

Temperature Under Bias-40°C to +85°C

Storage Temperature.....-65°C to +125°C

Voltage on Any Pin

(except V_{CC} , V_{PP} , A_9 and RP#)
with Respect to GND-2.0V to +7.0V⁽²⁾

Voltage on Pin RP# or Pin A_9
with Respect to GND -2.0V to +13.5V^(2,3)

V_{PP} Program Voltage with Respect
to GND during Block Erase
and Word/Byte Program -2.0V to +14.0V^(2,3)

V_{CC} Supply Voltage
with Respect to GND-2.0V to +7.0V⁽²⁾

Output Short Circuit Current 100 mA ⁽⁴⁾

NOTICE: This datasheet contains preliminary information on new products in production. Do not finalize a design with this information. Revised information will be published when the product is available. Verify with your local Intel Sales office that you have the latest datasheet before finalizing a design.

* **WARNING:** *Stressing the device beyond the "Absolute Maximum Ratings" may cause permanent damage. These are stress ratings only. Operation beyond the "Operating Conditions" is not recommended and extended exposure beyond the "Operating Conditions" may effect device reliability.*

NOTES:

1. Operating temperature is for commercial product defined by this specification.
2. Minimum DC voltage is -0.5V on input/output pins. During transitions, this level may undershoot to -2.0V for periods <20 ns. Maximum DC voltage on input/output pins is $V_{CC} + 0.5V$ which, during transitions, may overshoot to $V_{CC} + 2.0V$ for periods <20 ns.
3. Maximum DC voltage on V_{PP} may overshoot to +14.0V for periods <20 ns. Maximum DC voltage on RP# or A_9 may overshoot to 13.5V for periods <20 ns.
4. Output shorted for no more than one second. No more than one output shorted at a time.



5.0 COMMERCIAL OPERATING CONDITIONS

Table 10. Commercial Temperature and V_{CC} Operating Conditions

| Symbol | Parameter | Notes | Min | Max | Units |
|-----------------|--|-------|------|------|-------|
| T _A | Operating Temperature | | 0 | +70 | °C |
| V _{CC} | 3.3V V _{CC} Supply Voltage (± 0.3V) | | 3.0 | 3.6 | Volts |
| | 5V V _{CC} Supply Voltage (10%) | 1 | 4.50 | 5.50 | Volts |
| | 5V V _{CC} Supply Voltage (5%) | 2 | 4.75 | 5.25 | Volts |

NOTES:

1. 10% V_{CC} specifications apply to the 60 ns, 80 ns and 120 ns product versions in their standard test configuration.
2. 5% V_{CC} specifications apply to the 60 ns version in its high-speed test configuration.

5.1 Applying V_{CC} Voltages

When applying V_{CC} voltage to the device, a delay may be required before initiating device operation, depending on the V_{CC} ramp rate. If V_{CC} ramps slower than 1V/100 μs (0.01 V/μs) then no delay is

required. If V_{CC} ramps faster than 1V/100 μs (0.01 V/μs), then a delay of 2 μs is required before initiating device operation. RP# = GND is recommended during power-up to protect against spurious write signals when V_{CC} is between V_{LKO} and V_{CCMIN}.

| V _{CC} Ramp Rate | Required Timing |
|---------------------------|---|
| ≤ 1V/100 μs | No delay required. |
| > 1V/100 μs | A delay time of 2 μs is required before any device operation is initiated, including read operations, command writes, program operations, and erase operations. This delay is measured beginning from the time V _{CC} reaches V _{CCMIN} (3.0V for 3.3 ± 0.3V operation; and 4.5V for 5V operation). |

NOTES:

1. These requirements must be strictly followed to guarantee all other read and write specifications.
2. To switch between 3.3V and 5V operation, the system should first transition V_{CC} from the existing voltage range to GND, and then to the new voltage. Any time the V_{CC} supply drops below V_{CCMIN}, the chip may be reset, aborting any operations pending or in progress.
3. These guidelines must be followed for any V_{CC} transition from GND.

PRELIMINARY

5.2 DC Characteristics

Table 11. DC Characteristics (Commercial)

| Sym | Parameter | Prod | BV-60 BV-80 BV-120 | | | | Unit | Test Conditions |
|------------------|--|-----------------|--------------------------|-------|----------|-------|------|---|
| | | V _{CC} | 3.3 ± 0.3V | | 5V ± 10% | | | |
| | | Note | Typ | Max | Typ | Max | | |
| I _{IL} | Input Load Current | 1 | | ± 1.0 | | ± 1.0 | µA | V _{CC} = V _{CC} Max V _{IN} = V _{CC} or GND |
| I _{LO} | Output Leakage Current | 1 | | ± 10 | | ± 10 | µA | V _{CC} = V _{CC} Max V _{IN} = V _{CC} or GND |
| I _{CCS} | V _{CC} Standby Current | 1,3 | 0.4 | 1.5 | 0.8 | 2.0 | mA | V _{CC} = V _{CC} Max CE# = RP# = BYTE# = WP# = V _{IH} |
| | | | 60 | 110 | 50 | 130 | µA | V _{CC} = V _{CC} Max CE# = RP# = V _{CC} ± 0.2V |
| I _{CCD} | V _{CC} Deep Power-Down Current | 1 | 0.2 | 8 | 0.2 | 8 | µA | V _{CC} = V _{CC} Max V _{IN} = V _{CC} or GND RP# = GND ± 0.2V |
| I _{CCR} | V _{CC} Read Current for Word or Byte | 1,5,6 | 15 | 30 | 50 | 60 | mA | CMOS INPUTS V _{CC} = V _{CC} Max CE# = GND, OE# = V _{CC} f = 10 MHz (5V) 5 MHz (3.3V) I _{OUT} = 0 mA, Inputs = GND ± 0.2V or V _{CC} ± 0.2V |
| | | | 15 | 30 | 55 | 65 | mA | TTL INPUTS V _{CC} = V _{CC} Max CE# = V _{IL} , OE# = V _{IH} f = 10 MHz (5V) 5 MHz (3.3V) I _{OUT} = 0 mA, Inputs = V _{IL} or V _{IH} |
| I _{CCW} | V _{CC} Program Current for Word or Byte | 1,4 | 13 | 30 | 30 | 50 | mA | V _{PP} = V _{PPH1} (at 5V) Program in Progress |
| | | | 10 | 25 | 30 | 45 | mA | V _{PP} = V _{PPH2} (at 12V) Program in Progress |
| I _{CCE} | V _{CC} Erase Current | 1,4 | 13 | 30 | 18 | 35 | mA | V _{PP} = V _{PPH1} (at 5V) Block Erase in Progress |
| | | | 10 | 25 | 18 | 30 | mA | V _{PP} = V _{PPH2} (at 12V) Block Erase in Progress |

Table 11. DC Characteristics (Commercial) (Continued)

| Sym | Parameter | Prod | BV-60 BV-80 BV-120 | | | | Unit | Test Conditions |
|-------------------|--|-----------------|--------------------------|------|----------|------|------|---|
| | | V _{CC} | 3.3 ± 0.3V | | 5V ± 10% | | | |
| | | Note | Typ | Max | Typ | Max | | |
| I _{CCES} | V _{CC} Erase Suspend Current | 1,2 | 3 | 8.0 | 5 | 10 | mA | CE# = V _{IH} Block Erase Suspend |
| I _{PPS} | V _{PP} Standby Current | 1 | ± 0.5 | ± 15 | ± 0.5 | ± 10 | μA | V _{PP} < V _{PPH2} |
| I _{PPD} | V _{PP} Deep Power-Down Current | 1 | 0.2 | 5.0 | 0.2 | 5.0 | μA | RP# = GND ± 0.2V |
| I _{PPR} | V _{PP} Read Current | 1 | 50 | 200 | 30 | 200 | μA | V _{PP} ≥ V _{PPH2} |
| I _{PPW} | V _{PP} Program Current for Word or Byte | 1,4 | 13 | 30 | 13 | 25 | mA | V _{PP} = V _{PPH1} (at 5V) Program in Progress |
| | | | 8 | 25 | 8 | 20 | | V _{PP} = V _{PPH2} (at 12V) Program in Progress |
| I _{PPE} | V _{PP} Erase Current | 1,4 | 13 | 30 | 10 | 20 | mA | V _{PP} = V _{PPH1} (at 5V) Block Erase in Progress |
| | | | 8 | 25 | 5 | 15 | | V _{PP} = V _{PPH2} (at 12V) Block Erase in Progress |
| I _{PPES} | V _{PP} Erase Suspend Current | 1 | 50 | 200 | 30 | 200 | μA | V _{PP} = V _{PPH} Block Erase Suspend in Progress |
| I _{RP#} | RP# Boot Block Unlock Current | 1,4 | | 500 | | 500 | μA | RP# = V _{HH} |
| I _{ID} | A ₉ Intelligent Identifier Current | 1,4 | | 500 | | 500 | μA | A ₉ = V _{ID} |

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Table 11. DC Characteristics (Commercial) (Continued)

| Sym | Parameter | Prod | BV-60 BV-80 BV-120 | | | | Unit | Test Conditions |
|-------------------|---|-----------------|--------------------------|------------------------|------------------------|------------------------|------|--|
| | | V _{CC} | 3.3 ± 0.3V | | 5V ± 10% | | | |
| | | Note | Min | Max | Min | Max | | |
| V _{ID} | A ₉ Intelligent Identifier Voltage | | 11.4 | 12.6 | 11.4 | 12.6 | V | |
| V _{IL} | Input Low Voltage | | -0.5 | 0.8 | -0.5 | 0.8 | V | |
| V _{IH} | Input High Voltage | | 2.0 | V _{CC} + 0.5V | 2.0 | V _{CC} + 0.5V | V | |
| V _{OL} | Output Low Voltage | | | 0.45 | | 0.45 | V | V _{CC} = V _{CC} Min I _{OL} = 5.8 mA |
| V _{OH1} | Output High Voltage (TTL) | | 2.4 | | 2.4 | | V | V _{CC} = V _{CC} Min I _{OH} = -2.5 mA |
| V _{OH2} | Output High Voltage (CMOS) | | 0.85 × V _{CC} | | 0.85 × V _{CC} | | V | V _{CC} = V _{CC} Min I _{OH} = -2.5 mA |
| | | | V _{CC} - 0.4V | | V _{CC} - 0.4V | | V | V _{CC} = V _{CC} Min I _{OH} = -100 μA |
| V _{PPLK} | V _{PP} Lock-Out Voltage | 3 | 0.0 | 1.5 | 0.0 | 1.5 | V | Total Write Protect |
| V _{PPH1} | V _{PP} (Prog/Erase Operations) | | 4.5 | 5.5 | 4.5 | 5.5 | V | V _{PP} at 5V |
| V _{PPH2} | V _{PP} (Prog/Erase Operations) | | 11.4 | 12.6 | 11.4 | 12.6 | V | V _{PP} at 12V |
| V _{LKO} | V _{CC} Erase/Prog Lock Voltage | 8 | 2.0 | | 2.0 | | V | |
| V _{HH} | RP# Unlock Voltage | | 11.4 | 12.6 | 11.4 | 12.6 | V | Boot Block Unlock |

Table 12. Capacitance (T_A = 25°C, f = 1 MHz)

| Symbol | Parameter | Note | Typ | Max | Unit | Conditions |
|------------------|--------------------|------|-----|-----|------|-----------------------|
| C _{IN} | Input Capacitance | 4 | 6 | 8 | pF | V _{IN} = 0V |
| C _{OUT} | Output Capacitance | 4, 7 | 10 | 12 | pF | V _{OUT} = 0V |

NOTES:

- All currents are in RMS unless otherwise noted. Typical values at V_{CC} = 5.0V, T = +25°C. These currents are valid for all product versions (packages and speeds).
- I_{CCES} is specified with the device deselected. If the device is read while in erase suspend mode, current draw is the sum of I_{CCES} and I_{CCR}.
- Block erases and word/byte writes are inhibited when V_{PP} = V_{PPLK}, and not guaranteed in the range between V_{PPH1} and V_{PPLK}.
- Sampled, not 100% tested.
- Automatic Power Savings (APS) reduces I_{CCR} to less than 1 mA typical, in static operation.
- CMOS Inputs are either V_{CC} ± 0.2V or GND ± 0.2V. TTL Inputs are either V_{IL} or V_{IH}.
- For the 28F004B, address pin A₁₀ follows the C_{OUT} capacitance numbers.
- For all BV/CV parts, V_{LKO} = 2.0V for both 3.3V and 5V operations.

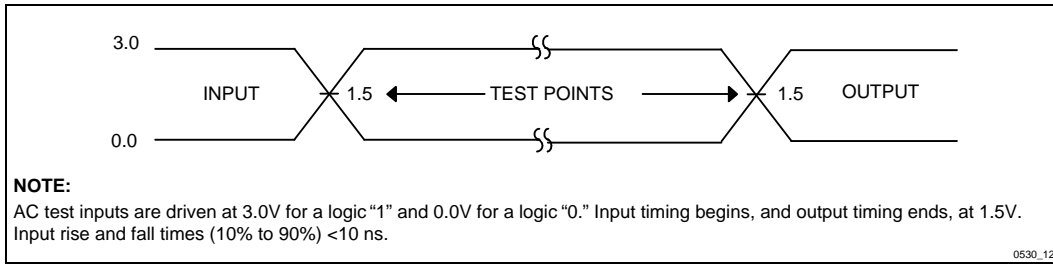


Figure 12. 3.3V Inputs and Measurement Points

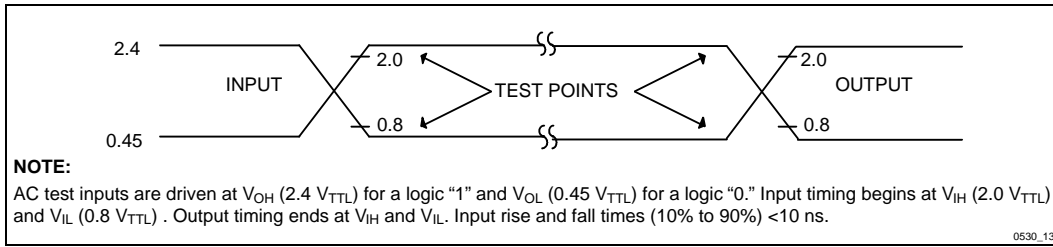


Figure 13. 5V Inputs and Measurement Points

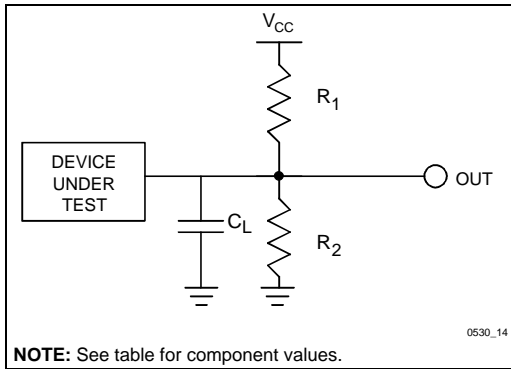


Figure 14. Test Configuration

Test Configuration Component Values

| Test Configuration | C_L (pF) | R_1 (Ω) | R_2 (Ω) |
|--------------------|------------|--------------------|--------------------|
| 3.3V Standard Test | 50 | 990 | 770 |
| 5V Standard Test | 100 | 580 | 390 |
| 5V High-Speed Test | 30 | 580 | 390 |

NOTE: C_L includes jig capacitance.

5.3 AC Characteristics

Table 13. AC Characteristics: Read Only Operations (Commercial)

| Sym | Parameter | Prod | BV-60 | | | | | | Unit |
|--|--|-----------------|---------------------------|-----|------------------------|------|-------------------------|------|------|
| | | V _{CC} | 3.3 ± 0.3V ⁽⁵⁾ | | 5V ± 5% ⁽⁶⁾ | | 5V ± 10% ⁽⁷⁾ | | |
| | | Load | 50 pF | | 30 pF | | 100 pF | | |
| | | Note | Min | Max | Min | Max | Min | Max | |
| t _{AVAV} | Read Cycle Time | | 110 | | 60 | | 70 | | ns |
| t _{AVQV} | Address to Output Delay | | | 110 | | 60 | | 70 | ns |
| t _{ELQV} | CE# to Output Delay | 2 | | 110 | | 60 | | 70 | ns |
| t _{PHQV} | RP# to Output Delay | | | 0.8 | | 0.45 | | 0.45 | μs |
| t _{GLQV} | OE# to Output Delay | 2 | | 65 | | 30 | | 35 | ns |
| t _{ELQX} | CE# to Output in Low Z | 3 | 0 | | 0 | | 0 | | ns |
| t _{EHQZ} | CE# to Output in High Z | 3 | | 25 | | 20 | | 20 | ns |
| t _{GLQX} | OE# to Output in Low Z | 3 | 0 | | 0 | | 0 | | ns |
| t _{GHQZ} | OE# to Output in High Z | 3 | | 25 | | 20 | | 20 | ns |
| t _{OH} | Output Hold from Address, CE#, or OE# Change, Whichever Occurs First | 3 | 0 | | 0 | | 0 | | ns |
| t _{ELFL} t _{ELFH} | CE# Low to BYTE# High or Low | 3 | 0 | | 0 | | 0 | | ns |
| t _{AVFL} | Address to BYTE# High or Low | 3 | | 5 | | 5 | | 5 | ns |
| t _{FLQV} t _{FHQV} | BYTE# to Output Delay | 3,4 | | 110 | | 60 | | 70 | ns |
| t _{FLQZ} | BYTE# Low to Output in High Z | 3 | | 45 | | 20 | | 25 | ns |
| t _{PLPH} | Reset Pulse Width Low | 8 | 150 | | 60 | | 60 | | ns |
| t _{PLQZ} | RP# Low to Output High Z | | | 150 | | 60 | | 60 | ns |

Table 13. AC Characteristics: Read Only Operations (Commercial) (Continued)

| Sym | Parameter | V _{CC} | BV-80 | | | | BV-120 | | | | Unit | | |
|--|--|-----------------|---------------------------|-----|-------------------------|------|---------------------------|-----|-------------------------|------|------|--------|--|
| | | | 3.3 ± 0.3V ⁽⁵⁾ | | 5V ± 10% ⁽⁷⁾ | | 3.3 ± 0.3V ⁽⁵⁾ | | 5V ± 10% ⁽⁷⁾ | | | | |
| | | | Load | | 50 pF | | 100 pF | | 50 pF | | | 100 pF | |
| | | | Notes | Min | Max | Min | Max | Min | Max | Min | | Max | |
| t _{AVAV} | Read Cycle Time | | 150 | | 80 | | 180 | | 120 | ns | | | |
| t _{AVQV} | Address to Output Delay | | | 150 | | 80 | | 180 | | 120 | ns | | |
| t _{ELQV} | CE# to Output Delay | 2 | | 150 | | 80 | | 180 | | 120 | ns | | |
| t _{PHQV} | RP# to Output Delay | | | 0.8 | | 0.45 | | 0.8 | | 0.45 | μs | | |
| t _{GLQV} | OE# to Output Delay | 2 | | 90 | | 40 | | 90 | | 40 | ns | | |
| t _{ELQX} | CE# to Output in Low Z | 3 | 0 | | 0 | | 0 | | 0 | | ns | | |
| t _{EHQZ} | CE# to Output in High Z | 3 | | 25 | | 20 | | 25 | | 20 | ns | | |
| t _{GLQX} | OE# to Output in Low Z | 3 | 0 | | 0 | | 0 | | 0 | | ns | | |
| t _{GHQZ} | OE# to Output in High Z | 3 | | 25 | | 20 | | 25 | | 20 | ns | | |
| t _{OH} | Output Hold from Address, CE#, or OE# Change, Whichever Occurs First | 3 | 0 | | 0 | | 0 | | 0 | | ns | | |
| t _{ELFL} t _{ELFH} | CE# Low to BYTE# High or Low | 3 | 0 | | 0 | | 0 | | 0 | | ns | | |
| t _{AVFL} | Address to BYTE# High or Low | 3 | | 5 | | 5 | | 5 | | 5 | ns | | |
| t _{FLQV} t _{FHQV} | BYTE# to Output Delay | 3,4 | | 150 | | 80 | | 180 | | 120 | ns | | |
| t _{FLQZ} | BYTE# Low to Output in High Z | 3 | | 60 | | 30 | | 60 | | 30 | ns | | |
| t _{PLPH} | Reset Pulse Width Low | 8 | 150 | | 60 | | 150 | | 60 | | ns | | |
| t _{PLQZ} | RP# Low to Output High Z | | | 150 | | 60 | | 150 | | 60 | | | |

NOTES:

1. See AC Input/Output Reference Waveform for timing measurements.
2. OE# may be delayed up to t_{CE-to-E} after the falling edge of CE# without impact on t_{CE}.
3. Sampled, but not 100% tested.
4. t_{FLQV}, BYTE# switching low to valid output delay will be equal to t_{AVQV}, measured from the time DQ₁₅/A₋₁ becomes valid.
5. See Test Configurations (Figure 14), 3.3V Standard Test component values.
6. See Test Configurations (Figure 14), 5V High-Speed Test component values.
7. See Test Configurations (Figure 14), 5V Standard Test component values.
8. The specification t_{PLPH} is the minimum time RP# must be held low to produce a valid reset of the device.

PRELIMINARY

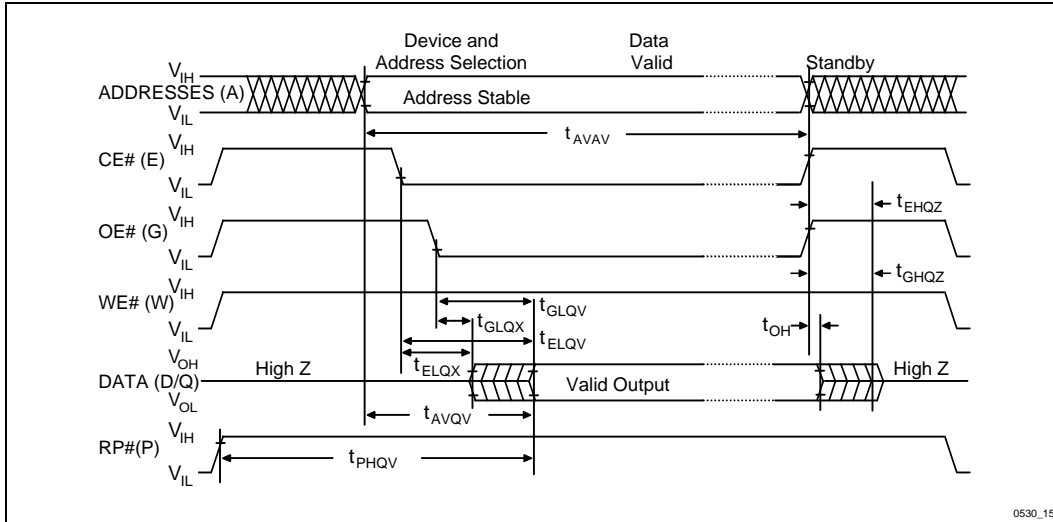


Figure 15. AC Waveforms for Read Operations

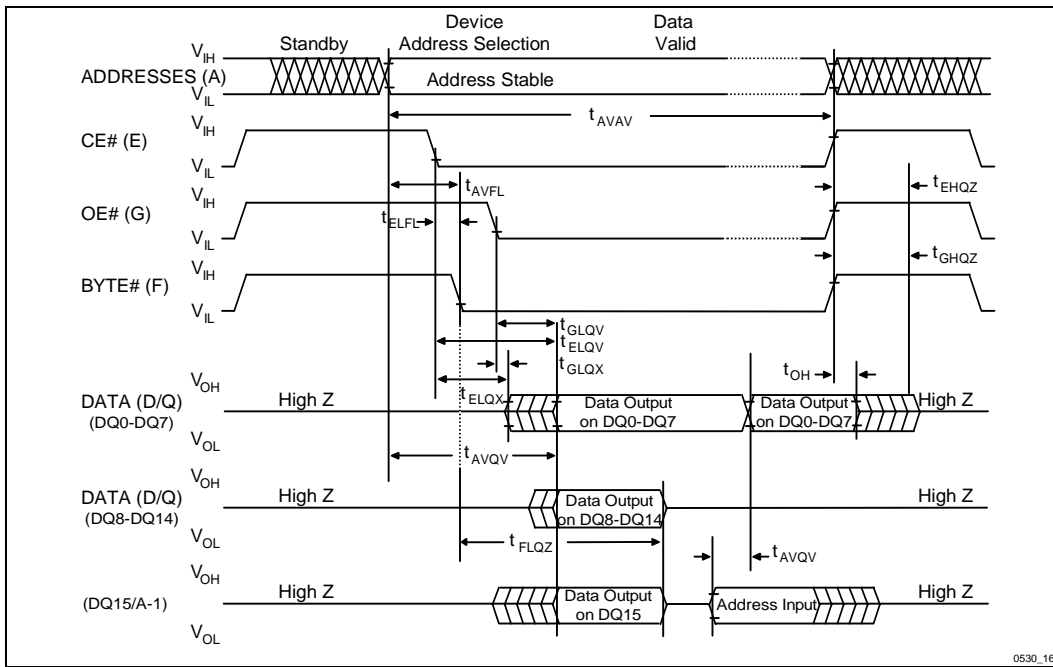


Figure 16. BYTE# Timing Diagram for Read Operations

Table 14. AC Characteristics: WE#-Controlled Write Operations ⁽¹⁾ (Commercial)

| Sym | Parameter | Prod | BV-60 | | | | | | Unit |
|--------------------|---|-----------------|---------------------------|-----|-------------------------|-----|--------------------------|-----|------|
| | | V _{CC} | 3.3 ± 0.3V ⁽⁹⁾ | | 5V ± 5% ⁽¹⁰⁾ | | 5V ± 10% ⁽¹⁰⁾ | | |
| | | Load | 50 pF | | 30 pF | | 100 pF | | |
| | | Note | Min | Max | Min | Max | Min | Max | |
| t _{AVAV} | Write Cycle Time | | 110 | | 60 | | 70 | | ns |
| t _{PHWL} | RP# Setup to WE# Going Low | | 0.8 | | 0.45 | | 0.45 | | μs |
| t _{ELWL} | CE# Setup to WE# Going Low | | 0 | | 0 | | 0 | | ns |
| t _{PHHWH} | Boot Block Lock Setup to WE# Going High | 6,8 | 200 | | 100 | | 100 | | ns |
| t _{VPWH} | V _{PP} Setup to WE# Going High | 5,8 | 200 | | 100 | | 100 | | ns |
| t _{AVWH} | Address Setup to WE# Going High | 3 | 90 | | 50 | | 50 | | ns |
| t _{DVWH} | Data Setup to WE# Going High | 4 | 90 | | 50 | | 50 | | ns |
| t _{WLWH} | WE# Pulse Width | | 90 | | 50 | | 50 | | ns |
| t _{WHDX} | Data Hold Time from WE# High | 4 | 0 | | 0 | | 0 | | ns |
| t _{WHAX} | Address Hold Time from WE# High | 3 | 0 | | 0 | | 0 | | ns |
| t _{WHEH} | CE# Hold Time from WE# High | | 0 | | 0 | | 0 | | ns |
| t _{WHWL} | WE# Pulse Width High | | 20 | | 10 | | 20 | | ns |
| t _{WHQV1} | Duration of Word/Byte Program | 2,5 | 6 | | 6 | | 6 | | μs |
| t _{WHQV2} | Duration of Erase (Boot) | 2,5,6 | 0.3 | | 0.3 | | 0.3 | | s |
| t _{WHQV3} | Duration of Erase (Parameter) | 2,5 | 0.3 | | 0.3 | | 0.3 | | s |
| t _{WHQV4} | Duration of Erase (Main) | 2,5 | 0.6 | | 0.6 | | 0.6 | | s |
| t _{QVVL} | V _{PP} Hold from Valid SRD | 5,8 | 0 | | 0 | | 0 | | ns |
| t _{QVPH} | RP# V _{HH} Hold from Valid SRD | 6,8 | 0 | | 0 | | 0 | | ns |
| t _{PHBR} | Boot-Block Lock Delay | 7,8 | | 200 | | 100 | | 100 | ns |

PRELIMINARY

Table 14. AC Characteristics: WE#-Controlled Write Operations ⁽¹⁾ (Commercial) (Continued)

| Sym | Parameter | Prod | BV-80 | | | | BV-120 | | | | Unit |
|--------------------|---|-----------------|--------------------------|-----|------------------------|-----|---------------------------|-----|------------------------|-----|------|
| | | V _{CC} | 3.3 ±0.3V ⁽⁹⁾ | | 5V±10% ⁽¹¹⁾ | | 3.3 ± 0.3V ⁽⁹⁾ | | 5V±10% ⁽¹¹⁾ | | |
| | | Load | 50 pF | | 100 pF | | 50 pF | | 100 pF | | |
| | | Notes | Min | Max | Min | Max | Min | Max | Min | Max | |
| t _{AVAV} | Write Cycle Time | | 150 | | 80 | | 180 | | 120 | | ns |
| t _{PHWL} | RP# Setup to WE# Going Low | | 0.8 | | 0.45 | | 0.8 | | 0.45 | | µs |
| t _{ELWL} | CE# Setup to WE# Going Low | | 0 | | 0 | | 0 | | 0 | | ns |
| t _{PHWH} | Boot Block Lock Setup to WE# Going High | 6,8 | 200 | | 100 | | 200 | | 100 | | ns |
| t _{VPWH} | V _{PP} Setup to WE# Going High | 5,8 | 200 | | 100 | | 200 | | 100 | | ns |
| t _{AVWH} | Address Setup to WE# Going High | 3 | 120 | | 50 | | 150 | | 50 | | ns |
| t _{DVWH} | Data Setup to WE# Going High | 4 | 120 | | 50 | | 150 | | 50 | | ns |
| t _{WLWH} | WE# Pulse Width | | 120 | | 50 | | 150 | | 50 | | ns |
| t _{WHDX} | Data Hold Time from WE# High | 4 | 0 | | 0 | | 0 | | 0 | | ns |
| t _{WHAX} | Address Hold Time from WE# High | 3 | 0 | | 0 | | 0 | | 0 | | ns |
| t _{WHEH} | CE# Hold Time from WE# High | | 0 | | 0 | | 0 | | 0 | | ns |
| t _{WHWL} | WE# Pulse Width High | | 30 | | 30 | | 30 | | 30 | | ns |
| t _{WHQV1} | Word/Byte Program Time | 2,5 | 6 | | 6 | | 6 | | 6 | | µs |
| t _{WHQV2} | Erase Duration (Boot) | 2,5,6 | 0.3 | | 0.3 | | 0.3 | | 0.3 | | s |
| t _{WHQV3} | Erase Duration (Param) | 2,5 | 0.3 | | 0.3 | | 0.3 | | 0.3 | | s |
| t _{WHQV4} | Erase Duration (Main) | 2,5 | 0.6 | | 0.6 | | 0.6 | | 0.6 | | s |
| t _{QVVL} | V _{PP} Hold from Valid SRD | 5,8 | 0 | | 0 | | 0 | | 0 | | ns |
| t _{QVPH} | RP# V _{HH} Hold from Valid SRD | 6,8 | 0 | | 0 | | 0 | | 0 | | ns |
| t _{PHBR} | Boot-Block Lock Delay | 7,8 | | 200 | | 100 | | 200 | | 100 | ns |

NOTES:

1. Read timing characteristics during write and erase operations are the same as during read-only operations. Refer to AC characteristics during read mode.
2. The on-chip WSM completely automates program/erase operations; program/erase algorithms are now controlled internally which includes verify and margining operations.
3. Refer to command definition table for valid A_{IN} . (Table 7)
4. Refer to command definition table for valid D_{IN} . (Table 7)
5. Program/erase durations are measured to valid SRD data (successful operation, SR.7 = 1).
6. For boot block program/erase, RP# should be held at V_{IH} or WP# should be held at V_{IH} until operation completes successfully.
7. Time t_{PHBR} is required for successful locking of the boot block.
8. Sampled, but not 100% tested.
9. See Test Configurations (Figure 14), 3.3V Standard Test component values.
10. See Test Configurations (Figure 14), 5V High-Speed Test component values.
11. See Test Configurations (Figure 14), 5V Standard Test component values.

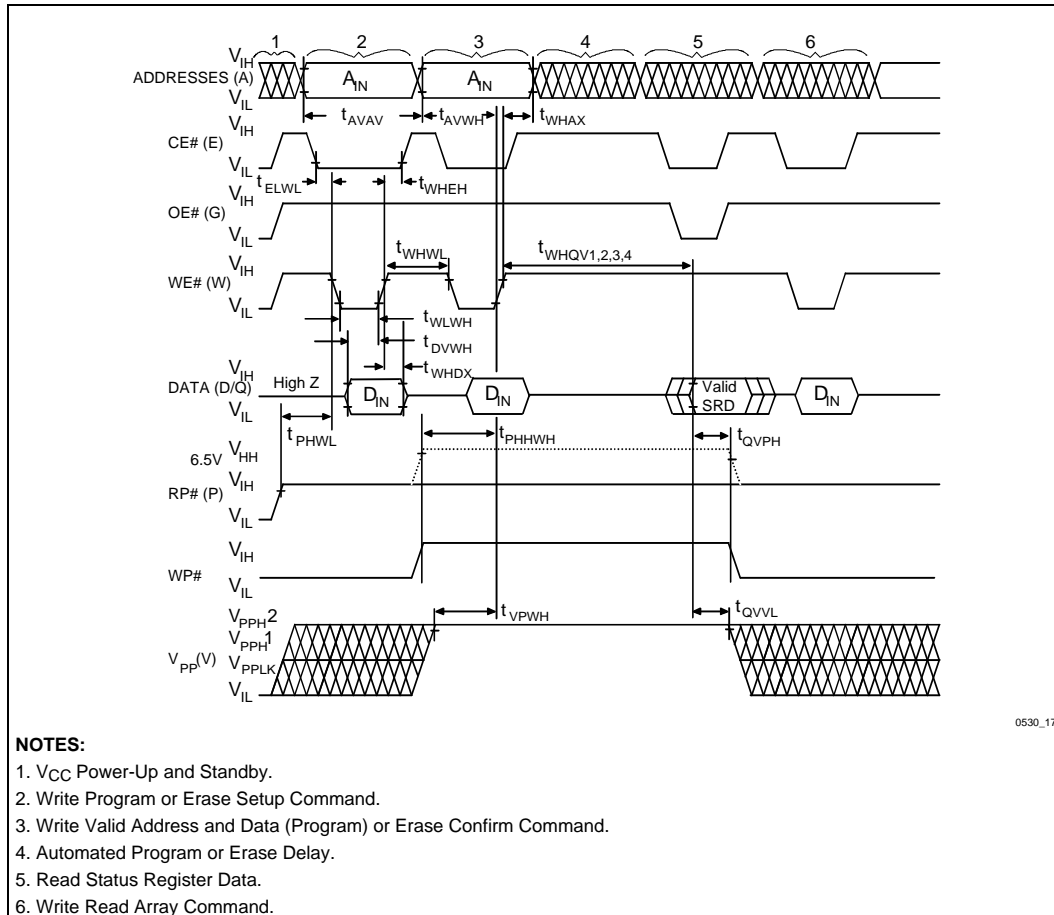


Figure 17. AC Waveforms for Write Operations (WE#-Controlled Writes)

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Table 15. AC Characteristics: CE#-Controlled Write Operations ^(1,12) (Commercial)

| Sym | Parameter | Prod | BV-60 | | | | | | Unit |
|--------------------|---|-----------------|---------------------------|-----|-------------------------|-----|--------------------------|-----|------|
| | | V _{CC} | 3.3 ± 0.3V ⁽⁹⁾ | | 5V ± 5% ⁽¹⁰⁾ | | 5V ± 10% ⁽¹¹⁾ | | |
| | | Load | 50 pF | | 30 pF | | 100 pF | | |
| | | Note | Min | Max | Min | Max | Min | Max | |
| t _{AVAV} | Write Cycle Time | | 110 | | 60 | | 70 | | ns |
| t _{PHEL} | RP# High Recovery to CE# Going Low | | 0.8 | | 0.45 | | 0.45 | | µs |
| t _{WLEL} | WE# Setup to CE# Going Low | | 0 | | 0 | | 0 | | ns |
| t _{PHHEH} | Boot Block Lock Setup to CE# Going High | 6,8 | 200 | | 100 | | 100 | | ns |
| t _{VPEH} | V _{PP} Setup to CE# Going High | 5,8 | 200 | | 100 | | 100 | | ns |
| t _{AVEH} | Address Setup to CE# Going High | 3 | 90 | | 50 | | 50 | | ns |
| t _{DVEH} | Data Setup to CE# Going High | 4 | 90 | | 50 | | 50 | | ns |
| t _{ELEH} | CE# Pulse Width | | 90 | | 50 | | 50 | | ns |
| t _{EHDX} | Data Hold Time from CE# High | 4 | 0 | | 0 | | 0 | | ns |
| t _{EHAX} | Address Hold Time from CE# High | 3 | 0 | | 0 | | 0 | | ns |
| t _{EHWH} | WE # Hold Time from CE# High | | 0 | | 0 | | 0 | | ns |
| t _{EHEL} | CE# Pulse Width High | | 20 | | 10 | | 20 | | ns |
| t _{EHQV1} | Duration of Word/Byte Programming Operation | 2,5 | 6 | | 6 | | 6 | | µs |
| t _{EHQV2} | Erase Duration (Boot) | 2,5,6 | 0.3 | | 0.3 | | 0.3 | | s |
| t _{EHQV3} | Erase Duration (Param) | 2,5 | 0.3 | | 0.3 | | 0.3 | | s |
| t _{EHQV4} | Erase Duration(Main) | 2,5 | 0.6 | | 0.6 | | 0.6 | | s |
| t _{QVVL} | V _{PP} Hold from Valid SRD | 5,8 | 0 | | 0 | | 0 | | ns |
| t _{QVPH} | RP# V _{HH} Hold from Valid SRD | 6,8 | 0 | | 0 | | 0 | | ns |
| t _{PHBR} | Boot-Block Lock Delay | 7,8 | | 200 | | 100 | | 100 | ns |

Table 15. AC Characteristics: CE#–Controlled Write Operations ^(1,12) (Commercial) (Continued)

| Sym | Parameter | Prod | BV-80 | | | | BV-120 | | | | Unit |
|--------------------|---|-----------------|---------------------------|-----|------------------------|-----|---------------------------|-----|------------------------|-----|------|
| | | V _{CC} | 3.3 ± 0.3V ⁽⁹⁾ | | 5V±10% ⁽¹¹⁾ | | 3.3 ± 0.3V ⁽⁹⁾ | | 5V±10% ⁽¹¹⁾ | | |
| | | Load | 50 pF | | 100 pF | | 50 pF | | 100 pF | | |
| | | Notes | Min | Max | Min | Max | Min | Max | Min | Max | |
| t _{AVAV} | Write Cycle Time | | 150 | | 80 | | 180 | | 120 | | ns |
| t _{PHEL} | RP# High Recovery to CE# Going Low | | 0.8 | | 0.45 | | 0.8 | | 0.45 | | µs |
| t _{WLEL} | WE# Setup to CE# Going Low | | 0 | | 0 | | 0 | | 0 | | ns |
| t _{PHHEH} | Boot Block Lock Setup to CE# Going High | 6,8 | 200 | | 100 | | 200 | | 100 | | ns |
| t _{VPEH} | V _{PP} Setup to CE# Going High | 5,8 | 200 | | 100 | | 200 | | 100 | | ns |
| t _{AVEH} | Address Setup to CE# Going High | 3 | 120 | | 50 | | 150 | | 50 | | ns |
| t _{DVEH} | Data Setup to CE# Going High | 4 | 120 | | 50 | | 150 | | 50 | | ns |
| t _{ELEH} | CE# Pulse Width | | 120 | | 50 | | 150 | | 50 | | ns |
| t _{EHDx} | Data Hold Time from CE# High | 4 | 0 | | 0 | | 0 | | 0 | | ns |
| t _{EHAX} | Address Hold Time from CE# High | 3 | 0 | | 0 | | 0 | | 0 | | ns |
| t _{EHWH} | WE # Hold Time from CE# High | | 0 | | 0 | | 0 | | 0 | | ns |
| t _{EHEL} | CE# Pulse Width High | | 30 | | 30 | | 30 | | 30 | | ns |
| t _{EHQV1} | Duration of Word/Byte Programming Operation | 2,5 | 6 | | 6 | | 6 | | 6 | | µs |
| t _{EHQV2} | Erase Duration (Boot) | 2,5,6 | 0.3 | | 0.3 | | 0.3 | | 0.3 | | s |
| t _{EHQV3} | Erase Duration (Param) | 2,5 | 0.3 | | 0.3 | | 0.3 | | 0.3 | | s |
| t _{EHQV4} | Erase Duration(Main) | 2,5 | 0.6 | | 0.6 | | 0.6 | | 0.6 | | s |
| t _{QVVL} | V _{PP} Hold from Valid SRD | 5,8 | 0 | | 0 | | 0 | | 0 | | ns |
| t _{QVPH} | RP# V _{HH} Hold from Valid SRD | 6,8 | 0 | | 0 | | 0 | | 0 | | ns |
| t _{PHBR} | Boot-Block Lock Delay | 7,8 | | 200 | | 100 | | 200 | | 100 | ns |

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NOTES:

See WE# Controlled Write Operations for notes 1 through 11.

12. Chip-Enable controlled writes: write operations are driven by the valid combination of CE# and WE# in systems where CE# defines the write pulse-width (within a longer WE# timing waveform), all set-up, hold and inactive WE# times should be measured relative to the CE# waveform.

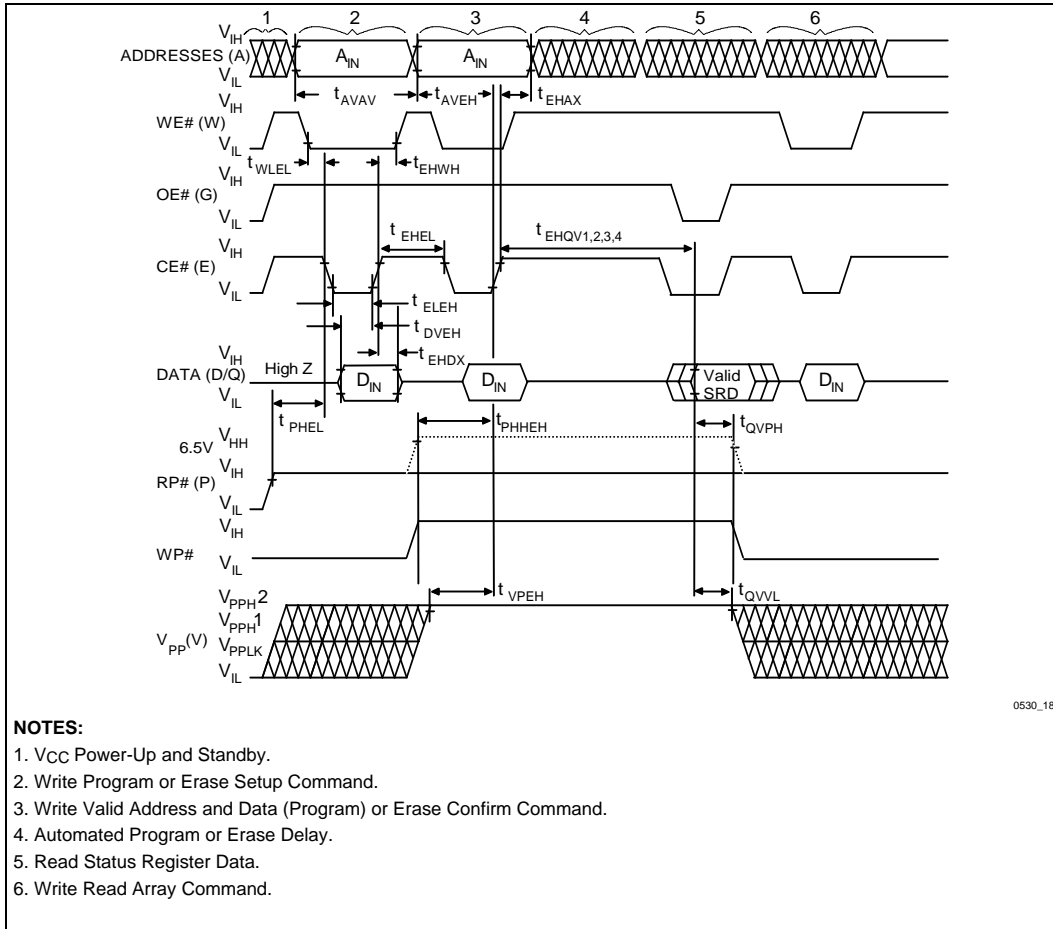


Figure 18. Alternate AC Waveforms for Write Operations (CE#-Controlled Writes)

Table 16. Erase and Program Timings (Commercial T_A = 0°C to +70°C)

| V _{PP} | 5V ± 10% | | | | 12V ± 5% | | | | Unit |
|----------------------------------|------------|-----|----------|-----|------------|-----|----------|-----|------|
| | 3.3 ± 0.3V | | 5V ± 10% | | 3.3 ± 0.3V | | 5V ± 10% | | |
| V _{CC} | 3.3 ± 0.3V | | 5V ± 10% | | 3.3 ± 0.3V | | 5V ± 10% | | Unit |
| Parameter | Typ | Max | Typ | Max | Typ | Max | Typ | Max | |
| Boot/Parameter Block Erase Time | 0.84 | 7 | 0.8 | 7 | 0.44 | 7 | 0.34 | 7 | s |
| Main Block Erase Time | 2.4 | 14 | 1.9 | 14 | 1.3 | 14 | 1.1 | 14 | s |
| Main Block Program Time (Byte) | 1.7 | | 1.8 | | 1.6 | | 1.2 | | s |
| Main Block Program Time (Word) | 1.1 | | 0.9 | | 0.8 | | 0.6 | | s |
| Byte Program Time ⁽⁴⁾ | 10 | | 10 | | 8 | | 8 | | µs |
| Word Program Time ⁽⁴⁾ | 13 | | 13 | | 8 | | 8 | | µs |

NOTES:

1. All numbers are sampled, not 100% tested.
2. Max erase times are specified under worst case conditions. The max erase times are tested at the same value independent of V_{CC} and V_{PP}. See Note 3 for typical conditions.
3. Typical conditions are +25°C with V_{CC} and V_{PP} at the center of the specified voltage range. Production programming using V_{CC} = 5.0V, V_{PP} = 12.0V typically results in a 60% reduction in programming time.
4. Contact your Intel field representative for more information.

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6.0 EXTENDED OPERATING CONDITIONS

Table 17. Extended Temperature and V_{CC} Operating Conditions

| Symbol | Parameter | Notes | Min | Max | Units |
|----------|---|-------|------|------|-------|
| T_A | Operating Temperature | | -40 | +85 | °C |
| V_{CC} | 2.7V–3.6V V_{CC} Supply Voltage | 1 | 2.7 | 3.6 | Volts |
| | 3.3V V_{CC} Supply Voltage ($\pm 0.3V$) | 1 | 3.0 | 3.6 | Volts |
| | 5V V_{CC} Supply Voltage (10%) | 2 | 4.50 | 5.50 | Volts |

NOTES:

1. AC specifications are valid at both voltage ranges. See DC Characteristics tables for voltage range-specific specifications.
2. 10% V_{CC} specifications apply to 80 ns and 120 ns versions in their standard test configuration.

6.1 Applying V_{CC} Voltages

When applying V_{CC} voltage to the device, a delay may be required before initiating device operation, depending on the V_{CC} ramp rate. If V_{CC} ramps slower than $1V/100 \mu s$ ($0.01 V/\mu s$) then no delay is

required. If V_{CC} ramps faster than $1V/100 \mu s$ ($0.01 V/\mu s$), then a delay of $2 \mu s$ is required before initiating device operation. $RP\# = GND$ is recommended during power-up to protect against spurious write signals when V_{CC} is between V_{LKO} and V_{CCMIN} .

| V_{CC} Ramp Rate | Required Timing |
|---------------------|---|
| $\leq 1V/100 \mu s$ | No delay required. |
| $> 1V/100 \mu s$ | A delay time of $2 \mu s$ is required before any device operation is initiated, including read operations, command writes, program operations, and erase operations. This delay is measured beginning from the time V_{CC} reaches V_{CCMIN} ($2.7V$ for $2.7V$ – $3.6V$ operation, $3.0V$ for $3.3 \pm 0.3V$ operation; and $4.5V$ for $5V$ operation). |

NOTES:

1. These requirements must be strictly followed to guarantee all other read and write specifications.
2. To switch between $3.3V$ and $5V$ operation, the system should first transition V_{CC} from the existing voltage range to GND, and then to the new voltage. Any time the V_{CC} supply drops below V_{CCMIN} , the chip may be reset, aborting any operations pending or in progress.
3. These guidelines must be followed for any V_{CC} transition from GND.

6.2 DC Characteristics

Table 18. DC Characteristics: Extended Temperature Operation

| Sym | Parameter | Prod | TBE-120 | | TBV-80 | | TBV-80 TBE-120 | | Unit | Test Conditions |
|------------------|---|-----------------|-----------|-------|------------|-------|-------------------|-------|------|---|
| | | V _{CC} | 2.7V–3.6V | | 3.3 ± 0.3V | | 5V ± 10% | | | |
| | | Notes | Typ | Max | Typ | Max | Typ | Max | | |
| I _{IL} | Input Load Current | 1 | | ± 1.0 | | ± 1.0 | | ± 1.0 | μA | V _{CC} = V _{CC} Max V _{IN} = V _{CC} or GND |
| I _{LO} | Output Leakage Current | 1 | | ± 10 | | ± 10 | | ± 10 | μA | V _{CC} = V _{CC} Max V _{IN} = V _{CC} or GND |
| I _{CCS} | V _{CC} Standby Current | 1,3 | 50 | 110 | 60 | 110 | 70 | 150 | μA | CMOS Levels V _{CC} = V _{CC} Max CE# = RP# = WP# = V _{CC} ± 0.2V |
| | | | 0.4 | 1.5 | 0.4 | 1.5 | 0.8 | 2.5 | mA | TTL Levels V _{CC} = V _{CC} Max CE# = RP# = BYTE# = V _{IH} |
| I _{CCD} | V _{CC} Deep Power-Down Current | 1 | 0.2 | 8 | 0.2 | 8 | 0.2 | 8 | μA | V _{CC} = V _{CC} Max V _{IN} = V _{CC} or GND RP# = GND ± 0.2V |
| I _{CCR} | V _{CC} Read Current for Word or Byte | 1,5,6 | 14 | 30 | 15 | 30 | 50 | 65 | mA | CMOS INPUTS V _{CC} = V _{CC} Max CE = V _{IL} f = 10 MHz (5V) 5 MHz (3.3V) I _{OUT} = 0 mA Inputs = GND ± 0.2V or V _{CC} ± 0.2V |
| | | | 14 | 30 | 15 | 30 | 55 | 70 | mA | TTL INPUTS V _{CC} = V _{CC} Max CE# = V _{IL} f = 10 MHz (5V), 5 MHz (3.3V) I _{OUT} = 0 mA Inputs = V _{IL} or V _{IH} |

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Table 18. DC Characteristics: Extended Temperature Operation (Continued)

| Sym | Parameter | Prod | TBE-120 | | TBV-80 | | TBV-80 TBE-120 | | Unit | Test Conditions |
|-------------------|--|-----------------|-----------|------|------------|------|-------------------|------|------|---|
| | | V _{CC} | 2.7V–3.6V | | 3.3 ± 0.3V | | 5V ± 10% | | | |
| | | Notes | Typ | Max | Typ | Max | Typ | Max | | |
| I _{CCW} | V _{CC} Program Current for Word or Byte | 1,4 | 8 | 30 | 13 | 30 | 30 | 50 | mA | V _{PP} = V _{PPH1} (at 5V) Program in Progress |
| | | | 9 | 25 | 10 | 25 | 30 | 45 | | V _{PP} = V _{PPH2} (at 12V) Program in Progress |
| I _{CCE} | V _{CC} Erase Current | 1,4 | 12 | 30 | 13 | 30 | 22 | 45 | mA | V _{PP} = V _{PPH1} (at 5V) Erase in Progress |
| | | | 9 | 25 | 10 | 25 | 18 | 40 | | V _{PP} = V _{PPH2} (at 12V) Erase in Progress |
| I _{CCES} | V _{CC} Erase Suspend Current | 1,2 | 2.5 | 8.0 | 3 | 8.0 | 5 | 12.0 | mA | CE# = V _{IH} V _{PP} = V _{PPH1} (at 5V) Block Erase Suspend |
| I _{PPS} | V _{PP} Standby Current | 1 | ± 5 | ± 15 | ± 5 | ± 15 | ± 5 | ± 15 | | V _{PP} < V _{PPH2} |
| I _{PPD} | V _{PP} Deep Power-Down Current | 1 | 0.2 | 10 | 0.2 | 10 | 0.2 | 10 | μA | RP# = GND ± 0.2V |
| I _{PPR} | V _{PP} Read Current | 1 | 50 | 200 | 50 | 200 | 50 | 200 | | V _{PP} ≥ V _{PPH2} |
| I _{PPW} | V _{PP} Program Current for Word/Byte | 1,4 | 13 | 30 | 13 | 30 | 13 | 30 | mA | V _{PP} = V _{PPH1} (at 5V) Program in Progress |
| | | | 8 | 25 | 8 | 25 | 8 | 25 | | V _{PP} = V _{PPH2} (at 12V) Program in Progress |

Table 18. DC Characteristics: Extended Temperature Operation (Continued)

| Sym | Parameter | Prod | TBE-120 | | TBV-80 | | TBV-80 TBE-120 | | Unit | Test Conditions |
|-------------------|---|-----------------|-----------|-----|------------|-----|-------------------|-----|------|---|
| | | V _{CC} | 2.7V–3.6V | | 3.3 ± 0.3V | | 5V ± 10% | | | |
| | | Notes | Typ | Max | Typ | Max | Typ | Max | | |
| I _{PPE} | V _{PP} Erase Current | 1,4 | 13 | 30 | 13 | 30 | 15 | 25 | mA | V _{PP} = V _{PPH1} (at 5V) Block Erase in Progress |
| | | | 8 | 25 | 8 | 25 | 10 | 20 | mA | V _{PP} = V _{PPH2} (at 12V) Block Erase in Progress |
| I _{PPES} | V _{PP} Erase Suspend Current | 1 | 50 | 200 | 50 | 200 | 50 | 200 | μA | V _{PP} = V _{PPH} Block Erase Suspend in Progress |
| I _{RP#} | RP# Boot Block Unlock Current | 1,4 | | 500 | | 500 | | 500 | μA | RP# = V _{HH} V _{PP} = 12V |
| I _{ID} | A ₉ Intelligent Identifier Current | 1,4 | | 500 | | 500 | | 500 | μA | A ₉ = V _{ID} |

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Table 18. DC Characteristics: Extended Temperature Operation (Continued)

| Sym | Parameter | Prod | TBE-120 | | TBV-80 | | TBV-80 TBE-120 | | Unit | Test Conditions |
|-------------------|--|-----------------|------------------------|------------------------|------------------------|------------------------|------------------------|------------------------|------|--|
| | | V _{CC} | 2.7V–3.6V | | 3.3 ± 0.3V | | 5V ± 10% | | | |
| | | Notes | Min | Max | Min | Max | Min | Max | | |
| V _{ID} | A ₉ Intelligent Identifier Voltage | | 11.4 | 12.6 | 11.4 | 12.6 | 11.4 | 12.6 | V | |
| V _{IL} | Input Low Voltage | | −0.5 | 0.8 | −0.5 | 0.8 | −0.5 | 0.8 | V | |
| V _{IH} | Input High Voltage | | 2.0 | V _{CC} ± 0.5V | 2.0 | V _{CC} ± 0.5V | 2.0 | V _{CC} ± 0.5V | V | |
| V _{OL} | Output Low Voltage | | | 0.45 | | 0.45 | | 0.45 | V | V _{CC} = V _{CC} Min I _{OL} = 5.8 mA (5V) 2 mA (3.3V) V _{PP} = 12V |
| V _{OH1} | Output High Voltage (TTL) | | 2.4 | | 2.4 | | 2.4 | | V | V _{CC} = V _{CC} Min I _{OH} = −2.5 mA |
| V _{OH2} | Output High Voltage (CMOS) | | 0.85 × V _{CC} | | 0.85 × V _{CC} | | 0.85 × V _{CC} | | V | V _{CC} = V _{CC} Min I _{OH} = −2.5 mA |
| | | | V _{CC} −0.4V | | V _{CC} −0.4V | | V _{CC} −0.4V | | V | V _{CC} = V _{CC} Min I _{OH} = −100 μA |
| V _{PPLK} | V _{PP} Lock-Out Voltage | 3 | 0.0 | 1.5 | 0.0 | 1.5 | 0.0 | 1.5 | V | Complete Write Protection |
| V _{PPH1} | V _{PP} during Prog/Erase | | 4.5 | 5.5 | 4.5 | 5.5 | 4.5 | 5.5 | V | V _{PP} at 5V |
| V _{PPH2} | Operations | | 11.4 | 12.6 | 11.4 | 12.6 | 11.4 | 12.6 | V | V _{PP} at 12V |
| V _{LKO} | V _{CC} Erase/Write Lock Voltage | 8 | 2.0 | | 2.0 | | 2.0 | | V | |
| V _{HH} | RP# Unlock Voltage | | 11.4 | 12.6 | 11.4 | 12.6 | 11.4 | 12.6 | V | V _{PP} = 12V Boot Block Write/ Erase |

Table 19. Capacitance ($T_A = 25^\circ\text{C}$, $f = 1\text{ MHz}$)

| Symbol | Parameter | Note | Typ | Max | Unit | Conditions |
|-----------|--------------------|------|-----|-----|------|----------------|
| C_{IN} | Input Capacitance | 4 | 6 | 8 | pF | $V_{IN} = 0V$ |
| C_{OUT} | Output Capacitance | 4 | 10 | 12 | pF | $V_{OUT} = 0V$ |

NOTES:

1. All currents are in RMS unless otherwise noted. Typical values at $V_{CC} = 5.0V$, $T = +25^\circ\text{C}$. These currents are valid for all product versions (packages and speeds).
2. I_{CCES} is specified with device de-selected. If device is read while in erase suspend, current draw is sum of I_{CCES} and I_{CCR} .
3. Block erases and word/byte programs inhibited when $V_{PP} = V_{PPLK}$, and not guaranteed in the range between V_{PPH1} and V_{PPLK} .
4. Sampled, not 100% tested.
5. Automatic Power Savings (APS) reduces I_{CCR} to less than 1 mA typical, in static operation.
6. CMOS Inputs are either $V_{CC} \pm 0.2V$ or $GND \pm 0.2V$. TTL Inputs are either V_{IL} or V_{IH} .
7. For the 28F004B address pin A_{10} follows the C_{OUT} capacitance numbers.
8. For all BV/CV/BE/CE parts, $V_{LKO} = 2.0V$ for 2.7V, 3.3V and 5.0V operations.


PRELIMINARY

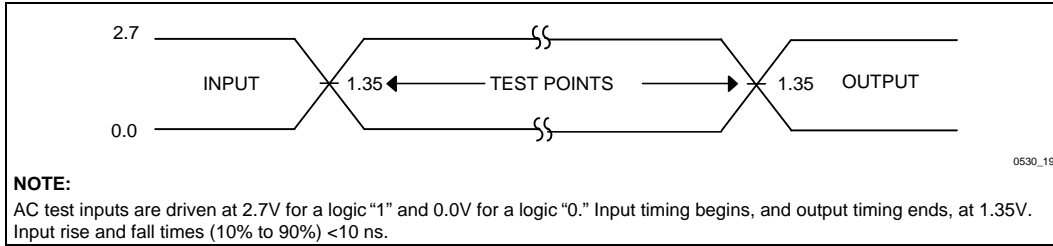


Figure 19. 2.7V–3.6V Input Range and Measurement Points

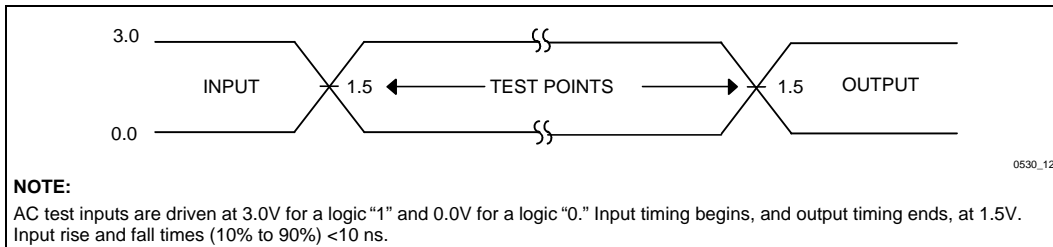


Figure 20. 3.3V Input Range and Measurement Points

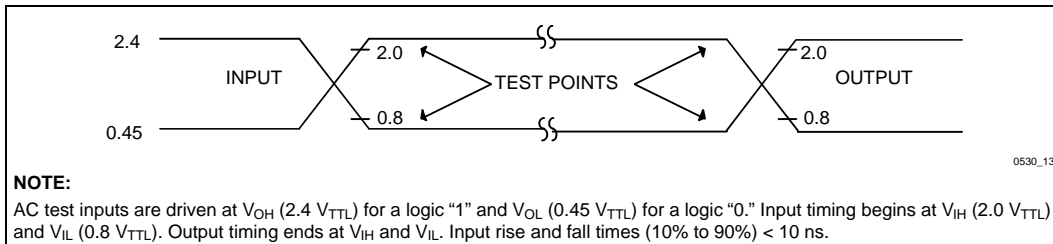


Figure 21. 5V Input Range and Measurement Points

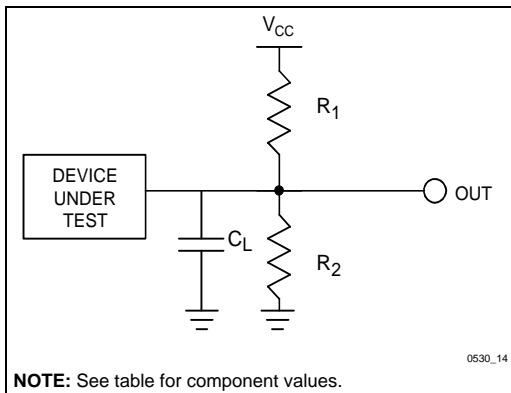


Figure 22. Test Configuration

Test Configuration Component Values

| Test Configuration | C_L (pF) | R_1 (Ω) | R_2 (Ω) |
|-----------------------------|------------|--------------------|--------------------|
| 2.7V and 3.3V Standard Test | 50 | 990 | 770 |
| 5V Standard Test | 100 | 580 | 390 |

NOTE: C_L includes jig capacitance.

6.3 AC Characteristics

 Table 20. AC Characteristics: Read Only Operations⁽¹⁾ (Extended Temperature)

| Sym | Parameter | Prod | TBE-120 | | TBV-80 | | TBV-80 TBE-120 | | Unit |
|--|--|-----------------|--------------------------|-----|--------------------------|-----|-----------------------|------|------|
| | | V _{CC} | 2.7V–3.6V ⁽⁵⁾ | | 3.3 ±0.3V ⁽⁵⁾ | | 5V±10% ⁽⁶⁾ | | |
| | | Load | 50 pF | | 50 pF | | 100 pF | | |
| | | Notes | Min | Max | Min | Max | Min | Max | |
| t _{AVAV} | Read Cycle Time | | 120 | | 110 | | 80 | | ns |
| t _{AVQV} | Address to Output Delay | | | 120 | | 110 | | 80 | ns |
| t _{ELQV} | CE# to Output Delay | 2 | | 120 | | 110 | | 80 | ns |
| t _{PHQV} | RP# to Output Delay | | | 0.8 | | 0.8 | | 0.45 | µs |
| t _{GLQV} | OE# to Output Delay | 2 | | 65 | | 65 | | 40 | ns |
| t _{ELQX} | CE# to Output in Low Z | 3 | 0 | | 0 | | 0 | | ns |
| t _{EHQZ} | CE# to Output in High Z | 3 | | 25 | | 25 | | 20 | ns |
| t _{GLQX} | OE# to Output in Low Z | 3 | 0 | | 0 | | 0 | | ns |
| t _{GHQZ} | OE# to Output in High Z | 3 | | 25 | | 25 | | 20 | ns |
| t _{OH} | Output Hold from Address, CE#, or OE# Change, Whichever Occurs First | 3 | 0 | | 0 | | 0 | | ns |
| t _{ELFL} t _{ELFH} | CE# Low to BYTE# High or Low | 3 | | 5 | | 5 | | 5 | ns |
| t _{AVFL} | Address to BYTE# High or Low | 3 | 0 | | 0 | | 0 | | ns |
| t _{FLQV} t _{FHQV} | BYTE# to Output Delay | 3,4 | | 120 | | 110 | | 80 | ns |
| t _{FLQZ} | BYTE# Low to Output in High Z | 3 | | 45 | | 45 | | 30 | ns |
| t _{PLPH} | Reset Pulse Width Low | 7 | 150 | | 150 | | 60 | | ns |
| t _{PLQZ} | RP# Low to Output High Z | | | 150 | | 150 | | 60 | ns |

NOTES:

1. See AC Input/Output Reference Waveform for timing measurements.
2. OE# may be delayed up to t_{CE}–t_{OE} after the falling edge of CE# without impact on t_{CE}.
3. Sampled, but not 100% tested.
4. t_{FLQV}, BYTE# switching low to valid output delay will be equal to t_{AVQV}, measured from the time DQ₁₅/A_{–1} becomes valid.
5. See Test Configurations (Figure 22), 2.7V–3.6V and 3.3 ± 0.3V Standard Test component values.
6. See Test Configurations (Figure 22), 5V Standard Test component values.
7. The specification t_{PLPH} is the minimum time RP# must be held low to produce a valid reset of the device.

PRELIMINARY

Table 21. AC Characteristics: WE#-Controlled Write Operations⁽¹⁾ (Extended Temperature)

| Sym | Parameter | Prod | TBE-120 | | TBV-80 | | TBV-80 TBE-120 | | Unit |
|--------------------|--|-----------------|--------------------------|-----|-------------------------|-----|------------------------|-----|------|
| | | V _{CC} | 2.7V–3.6V ⁽⁹⁾ | | 3.3±0.3V ⁽⁹⁾ | | 5V±10% ⁽¹⁰⁾ | | |
| | | Load | 50 pF | | 50 pF | | 100 pF | | |
| | | Notes | Min | Max | Min | Max | Min | Max | |
| t _{AVAV} | Write Cycle Time | | 120 | | 110 | | 80 | | ns |
| t _{PHWL} | RP# High Recovery to WE# Going Low | | 0.8 | | 0.8 | | 0.45 | | μs |
| t _{ELWL} | CE# Setup to WE# Going Low | | 0 | | 0 | | 0 | | ns |
| t _{PHHWH} | Boot Block Lock Setup to WE# Going High | 6,8 | 200 | | 200 | | 100 | | ns |
| t _{VPWH} | V _{PP} Setup to WE# Going High | 5,8 | 200 | | 200 | | 100 | | ns |
| t _{AVWH} | Address Setup to WE# Going High | 3 | 90 | | 90 | | 60 | | ns |
| t _{DVWH} | Data Setup to WE# Going High | 4 | 70 | | 70 | | 60 | | ns |
| t _{WLWH} | WE# Pulse Width | | 90 | | 90 | | 60 | | ns |
| t _{WHDX} | Data Hold Time from WE# High | 4 | 0 | | 0 | | 0 | | ns |
| t _{WHAX} | Address Hold Time from WE# High | 3 | 0 | | 0 | | 0 | | ns |
| t _{WHEH} | CE# Hold Time from WE# High | | 0 | | 0 | | 0 | | ns |
| t _{WHWL} | WE# Pulse Width High | | 30 | | 20 | | 20 | | ns |
| t _{WHQV1} | Word/Byte Program Time | 2,5,8 | 6 | | 6 | | 6 | | μs |
| t _{WHQV2} | Erase Duration (Boot) | 2,5, 6, 8 | 0.3 | | 0.3 | | 0.3 | | s |
| t _{WHQV3} | Erase Duration (Param) | 2,5,8 | 0.3 | | 0.3 | | 0.3 | | s |
| t _{WHQV4} | Erase Duration (Main) | 2,5,8 | 0.6 | | 0.6 | | 0.6 | | s |
| t _{QVVL} | V _{PP} Hold from Valid SRD | 5,8 | 0 | | 0 | | 0 | | ns |
| t _{QVPH} | RP# V _{HH} Hold from Valid SRD | 6,8 | 0 | | 0 | | 0 | | ns |
| t _{PHBR} | Boot-Block Lock Delay | 7,8 | | 200 | | 200 | | 100 | ns |

NOTES:

1. Read timing characteristics during program and erase operations are the same as during read-only operations. Refer to AC Characteristics during read mode.
2. The on-chip WSM completely automates program/erase operations; program/erase algorithms are now controlled internally which includes verify and margining operations.
3. Refer to command definition table for valid A_{IN} . (Table 7)
4. Refer to command definition table for valid D_{IN} . (Table 7)
5. Program/erase durations are measured to valid SRD data (successful operation, SR.7 = 1)
6. For boot block program/erase, RP# should be held at V_{IH} or WP# should be held at V_{IH} until operation completes successfully.
7. Time t_{PHBR} is required for successful locking of the boot block.
8. Sampled, but not 100% tested.
9. See Test Configurations (Figure 22), 2.7V–3.6V and $3.3 \pm 0.3V$ Standard Test component values.
10. See Test Configurations (Figure 22), 5V Standard Test component values.

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Table 22. AC Characteristics: CE#-Controlled Write Operations ^(1,11) (Extended Temperature)

| Sym | Parameter | Prod | TBE-120 | | TBV-80 | | TBV-80 TBE-120 | | Unit |
|--------------------|--|-----------------|--------------------------|-----|--------------------------|-----|------------------------|-----|------|
| | | V _{CC} | 2.7V–3.6V ⁽⁹⁾ | | 3.3 ±0.3V ⁽⁹⁾ | | 5V±10% ⁽¹⁰⁾ | | |
| | | Load | 50 pF | | 50 pF | | 100 pF | | |
| | | Notes | Min | Max | Min | Max | Min | Max | |
| t _{AVAV} | Write Cycle Time | | 120 | | 110 | | 80 | | ns |
| t _{PHEL} | RP# High Recovery to CE# Going Low | | 0.8 | | 0.8 | | 0.45 | | µs |
| t _{WLEL} | WE# Setup to CE# Going Low | | 0 | | 0 | | 0 | | ns |
| t _{PHHEH} | Boot Block Lock Setup to CE# Going High | 6,8 | 200 | | 200 | | 100 | | ns |
| t _{VPEH} | V _{PP} Setup to CE# Going High | 5,8 | 200 | | 200 | | 100 | | ns |
| t _{AVEH} | Address Setup to CE# Going High | | 90 | | 90 | | 60 | | ns |
| t _{DVEH} | Data Setup to CE# Going High | 3 | 70 | | 70 | | 60 | | ns |
| t _{ELEH} | CE# Pulse Width | 4 | 90 | | 90 | | 60 | | ns |
| t _{EHDX} | Data Hold Time from CE# High | | 0 | | 0 | | 0 | | ns |
| t _{EHAX} | Address Hold Time from CE# High | 4 | 0 | | 0 | | 0 | | ns |
| t _{EHWH} | WE# Hold Time from CE# High | 3 | 0 | | 0 | | 0 | | ns |
| t _{EHEL} | CE# Pulse Width High | | 20 | | 20 | | 20 | | ns |
| t _{EHQV1} | Word/Byte Program Time | 2,5 | 6 | | 6 | | 6 | | µs |
| t _{EHQV2} | Erase Duration (Boot) | 2,5,6 | 0.3 | | 0.3 | | 0.3 | | s |
| t _{EHQV3} | Erase Duration (Param) | 2,5 | 0.3 | | 0.3 | | 0.3 | | s |
| t _{EHQV4} | Erase Duration (Main) | 2,5 | 0.6 | | 0.6 | | 0.6 | | s |
| t _{QVVL} | V _{PP} Hold from Valid SRD | 5,8 | 0 | | 0 | | 0 | | ns |
| t _{QVPH} | RP# V _{HH} Hold from Valid SRD | 6,8 | 0 | | 0 | | 0 | | ns |
| t _{PHBR} | Boot-Block Lock Delay | 7,8 | | 200 | | 200 | | 100 | ns |

NOTES:

See WE# Controlled Write Operations for notes 1 through 10.

11. Chip-Enable controlled writes: write operations are driven by the valid combination of CE# and WE# in systems where CE# defines the write pulse-width (within a longer WE# timing waveform), all set-up, hold and inactive WE# times should be measured relative to the CE# waveform.

Table 23. Erase and Program Timings (Extended $T_A = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$)

| | V_{PP} | $5V \pm 10\%$ | | | | | | $12V \pm 5\%$ | | | | | | Unit |
|-------------------------------------|----------|---------------|-----|----------------|-----|---------------|-----|---------------|-----|----------------|-----|---------------|-----|---------------|
| | V_{CC} | 2.7V–3.6V | | $3.3 \pm 0.3V$ | | $5V \pm 10\%$ | | 2.7V–3.6V | | $3.3 \pm 0.3V$ | | $5V \pm 10\%$ | | |
| Parameter | | Typ | Max | Typ | Max | Typ | Max | Typ | Max | Typ | Max | Typ | Max | |
| Boot/Parameter Block Erase Time | | 0.88 | 7 | 0.84 | 7 | 0.8 | 7 | 0.46 | 7 | 0.44 | 7 | 0.34 | 7 | s |
| Main Block Erase Time | | 2.5 | 14 | 2.4 | 14 | 1.9 | 14 | 1.36 | 14 | 1.3 | 14 | 1.1 | 14 | s |
| Main Block Program Time (Byte Mode) | | 1.87 | | 1.7 | | 1.4 | | 1.76 | | 1.6 | | 1.2 | | s |
| Main Block Program Time (Word Mode) | | 1.21 | | 1.1 | | 0.9 | | 0.88 | | 0.8 | | 0.6 | | s |
| Byte Program Time ⁽⁴⁾ | | 11 | | 10 | | 10 | | 8.8 | | 8 | | 8 | | μs |
| Word Program Time ⁽⁴⁾ | | 14.3 | | 13 | | 13 | | 8.8 | | 8 | | 8 | | μs |

NOTES:

1. All numbers are sampled, not 100% tested.
2. Max erase times are specified under worst case conditions. The max erase times are tested at the same value independent of V_{CC} and V_{PP} . See Note 3 for typical conditions.
3. Typical conditions are $+25^{\circ}\text{C}$ with V_{CC} and V_{PP} at the center of the specified voltage range. Production programming using $V_{CC} = 5.0V$, $V_{PP} = 12.0V$ typically results in a 60% reduction in programming time.
4. Contact your Intel field representative for more information.

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APPENDIX A ORDERING INFORMATION

TE28F400CV - T80

Operating Temperature
T = Extended Temp
Blank = Commercial Temp

Package
E = TSOP
PA = 44-Lead PSOP
TB = Ext. Temp 44-Lead PSOP

Product line designator
 for all Intel Flash products

Density / Organization
00X = x8-only (X = 1, 2, 4, 8)
X00 = x8/x16 Selectable (X = 2, 4, 8)

Access Speed(ns)
BV/CV: $V_{CC} = 5V$
BE/CE: $V_{CC} = 2.7V$

T = Top Boot
B = Bottom Boot

Voltage Options (V_{PP}/V_{CC})
V = (5 or 12 / 3.3 or 5)
E = (5 or 12 / 2.7 or 5)

Architecture
B = Boot Block
C = Compact 48-Lead TSOP Boot Block

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VALID COMBINATIONS:

| | 40-Lead TSOP | 44-Lead PSOP | 48-Lead TSOP | 56-Lead TSOP |
|-------------------|--|--|--|--|
| Commercial | E28F004BVT60 E28F004BVB60 E28F004BVT80 E28F004BVB80 E28F004BVT120 E28F004BVB120 | PA28F400BVT60 PA28F400BVB60 PA28F400BVT80 PA28F400BVB80 PA28F400BVT120 PA28F400BVB120 | E28F400CVT60 E28F400CVB60 E28F400CVT80 E28F400CVB80 | E28F400BVT60 E28F400BVB60 E28F400BVT80 E28F400BVB80 |
| Extended | TE28F004BVT80 TE28F004BVB80 TE28F004BET120 TE28F004BEB120 | TB28F400BVT80 TB28F400BVB80 | TE28F400CVT80 TE28F400CVB80 TE28F400CET120 TE28F400CEB120 | TE28F400BVT80 TE28F400BVB80 |

Table 24. Summary of Line Items

| Name | V _{CC} | | | V _{PP} | | 40-Ld | 44-Ld | 48-Ld | 56-Ld | 0°C – | –40°C – |
|----------|-----------------|------|----|-----------------|-----|-------|-------|-------|-------|-------|---------|
| | 2.7V | 3.3V | 5V | 5V | 12V | TSOP | PSOP | TSOP | TSOP | +70°C | +85°C |
| 28F004BV | | √ | √ | √ | √ | √ | | | | √ | √ |
| 28F400BV | | √ | √ | √ | √ | | √ | | √ | √ | √ |
| 28F400CV | | √ | √ | √ | √ | | | √ | | √ | √ |
| 28F004BE | √ | | √ | √ | √ | √ | | | | | √ |
| 28F400CE | √ | | √ | √ | √ | | | √ | | | √ |

APPENDIX B ADDITIONAL INFORMATION

RELATED INTEL INFORMATION(1,2)

| Order Number | Document |
|--------------|---|
| 290599 | <i>Smart 5 Boot Block Flash Memory Family 2, 4, 8 Mbit Datasheet</i> |
| 292194 | <i>AB-65 Migrating Designs from SmartVoltage Boot Block to Smart 5 Flash</i> |
| 292154 | <i>AB-60 2/4/8-Mbit SmartVoltage Boot Block Flash Memory Family</i> |
| 290531 | <i>2-Mbit SmartVoltage Boot Block Flash Memory Family Datasheet</i> |
| 290539 | <i>8-Mbit SmartVoltage Boot Block Flash Memory Family Datasheet</i> |
| 292164 | <i>AP-611 2/4M Boot Block Compatibility with 2/4/8-M SmartVoltage Boot Block Flash Memories</i> |
| 290448 | <i>28F002/200BX-T/B 2-Mbit Boot Block Flash Memory Datasheet</i> |
| 290449 | <i>28F002/200BL-T/B 2-Mbit Low Power Boot Block Flash Memory Datasheet</i> |
| 290451 | <i>28F004/400BX-T/B 4-Mbit Boot Block Flash Memory Datasheet</i> |
| 290450 | <i>28F004/400BL-T/B 4-Mbit Low Power Boot Block Flash Memory Datasheet</i> |
| 292148 | <i>AP-604 Using Intel's Boot Block Flash Memory Parameter Blocks to Replace EEPROM</i> |
| 292172 | <i>AP-617 Additional Flash Data Protection Using V_{PP}, RP#, and WP#</i> |
| 292130 | <i>AB-57 Boot Block Architecture for Safe Firmware Updates</i> |

NOTES:

1. Please call the Intel Literature Center at (800) 548-4725 to request Intel documentation. International customers should contact their local Intel or distribution sales office.
2. Visit Intel's World Wide Web home page at <http://www.Intel.com> for technical documentation and tools.

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