## 8 x 16 Analog Switch Array



**Data Sheet** 

February 2005

- Internal control latches and address decoder
- Short set-up and hold times
- Wide operating voltage: 4.5 V to 13.2 V
- 12Vpp analog signal capability
- R<sub>ON</sub> 65 Ω max. @ V<sub>DD</sub> = 12 V, 25°C
- $\Delta R_{ON} \le 10 \Omega @ V_{DD} = 12 V, 25^{\circ}C$
- · Full CMOS switch for low distortion
- · Minimum feedthrough and crosstalk
- Separate analog and digital reference supplies
- Low power consumption ISO-CMOS technology

#### **Applications**

**Features** 

- Key systems
- · PBX systems
- Mobile radio
- Test equipment/instrumentation
- Analog/digital multiplexers
- · Audio/Video switching

#### **Ordering Information** MT8816AE 40 Pin PDIP Tubes MT8816AP 44 Pin PLCC Tubes MT8816APR 44 Pin PLCC Tape & Reel MT8816AP1 44 Pin PLCC' Tubes MT8816APR1 44 Pin PLCC\* Tape & Reel 40 Pin PDIP\* MT8816AE1 Tubes \* Pb Free Matte Tin -40°C to +85°C

#### **Description**

The Zarlink MT8816 is fabricated in Zarlink's ISO-CMOS technology providing low power dissipation and high reliability. The device contains a 8 x 16 array of crosspoint switches along with a 7 to 128 line decoder and latch circuits. Any one of the 128 switches can be addressed by selecting the appropriate seven address bits. The selected switch can be turned on or off by applying a logical one or zero to the DATA input.  $V_{SS}$  is the ground reference of the digital inputs. The range of the analog signal is from  $V_{DD}$  to  $V_{EE}$ . Chip Select (CS) allows the crosspoint array to be cascaded for matrix expansion.

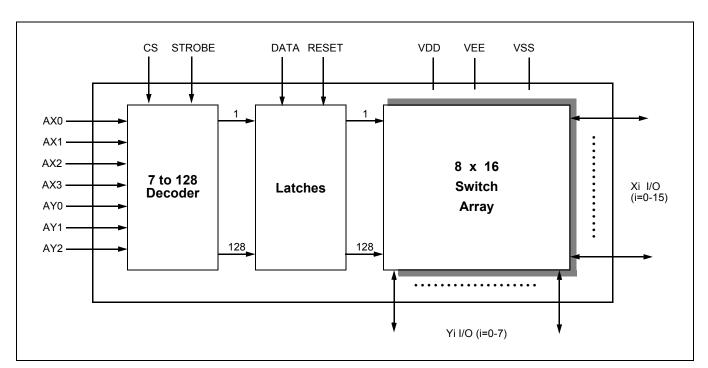


Figure 1 - Functional Block Diagram

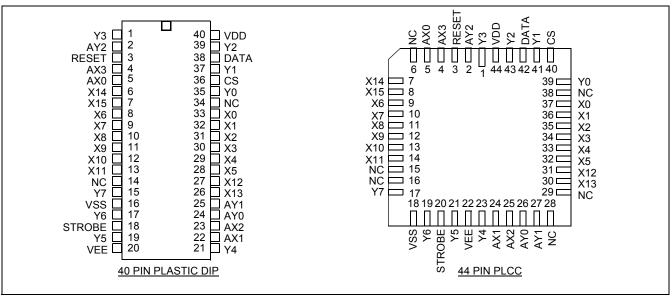


Figure 2 - Pin Connections

#### **Pin Description**

Pi	n #	Nome	Description				
PDIP	PLCC	Name	Description				
1	1	Y3	Y3 Analog (Input/Output): this is connected to the Y3 column of the switch array.				
2	2	AY2	Y2 Address Line (Input).				
3	3	RESET	Master RESET (Input): this is used to turn off all switches regardless of the condition of CS. Active High.				
4,5	4,5	AX3,AX0	X3 and X0 Address Lines (Inputs).				
6,7	7,8	X14, X15	(14 and X15 Analog (Inputs/Outputs): these are connected to the X14 and X15 lows of the switch array.				
8-13	9-14	X6-X11	<b>X6-X11 Analog (Inputs/Outputs):</b> these are connected to the X6-X11 rows of the switch array.				
14	6,15,16	NC	No Connection				
15	17	Y7	Y7 Analog (Input/Output): this is connected to the Y7 column of the switch array.				
16	18	$V_{SS}$	Digital Ground Reference.				
17	19	Y6	Y6 Analog (Input/Output): this is connected to the Y6 column of the switch array.				
18	20	STROBE	STROBE (Input): enables function selected by address and data. Address must be stable before STROBE goes high and DATA must be stable on the falling edge of the STROBE. Active High.				
19	21	Y5	Y5 Analog (Input/Output): this is connected to the Y5 column of the switch array.				
20	22	V <sub>EE</sub>	Negative Power Supply.				
21	23	Y4	Y4 Analog (Input/Output): this is connected to the Y4 column of the switch array.				
22, 23	24,25	AX1,AX2	X1 and X2 Address Lines (Inputs).				

## Pin Description (continued)

Piı	n #	Nome	Description			
PDIP	PLCC	Name	Description			
24, 25	26,27	AY0,AY1	Y0 and Y1 Address Lines (Inputs).			
26, 27	30,31	X13, X12	X13 and X12 Analog (Inputs/Outputs): these are connected to the X13 and X12 rows of the switch array.			
28 - 33	32-37	X5-X0	<b>X5-X0 Analog (Inputs/Outputs):</b> these are connected to the X5-X0 rows of the switch array.			
34	28,29, 38	NC	No Connection.			
35	39	Y0	Y0 Analog (Input/Output): this is connected to the Y0 column of the switch array.			
36	40	CS	Chip Select (Input): this is used to select the device. Active High.			
37	41	Y1	Y1 Analog (Input/Output): this is connected to the Y1 column of the switch array.			
38	42	DATA	<b>DATA (Input)</b> : a logic high input will turn on the selected switch and a logic low will turn off the selected switch. Active High.			
39	43	Y2	Y2 Analog (Input/Output): this is connected to the Y2 column of the switch array.			
40	44	V <sub>DD</sub>	Positive Power Supply.			

#### **Functional Description**

The MT8816 is an analog switch matrix with an array size of 8 x 16. The switch array is arranged such that there are 8 columns by 16 rows. The columns are referred to as the Y inputs/outputs and the rows are the X inputs/outputs. The crosspoint analog switch array will interconnect any X I/O with any Y I/O when turned on and provide a high degree of isolation when turned off. The control memory consists of a 128 bit write only RAM in which the bits are selected by the address inputs (AY0-AY2, AX0-AX3). Data is presented to the memory on the DATA input. Data is asynchronously written into memory whenever both the CS (Chip Select) and STROBE inputs are high and are latched on the falling edge of STROBE. A logical "1" written into a memory cell turns the corresponding crosspoint switch on and a logical "0" turns the crosspoint off. Only the crosspoint switches corresponding to the addressed memory location are altered when data is written into memory. The remaining switches retain their previous states. Any combination of X and Y inputs/outputs can be interconnected by establishing appropriate patterns in the control memory. A logical "1" on the RESET input will asynchronously return all memory locations to logical "0" turning off all crosspoint switches regardless of whether CS is high or low. Two voltage reference pins ( $V_{SS}$  and  $V_{EE}$ ) are provided for the MT8816 to enable switching of negative analog signals. The range for digital signals is from  $V_{DD}$  to  $V_{SS}$  while the range for analog signals is from  $V_{DD}$  to  $V_{EE}$ .  $V_{SS}$  and  $V_{EF}$  pins can be tied together if a single voltage reference is needed.

#### **Address Decode**

The seven address inputs along with the STROBE and CS (Chip Select) are logically ANDed to form an enable signal for the resettable transparent latches. The DATA input is buffered and is used as the input to all latches. To write to a location, RESET must be low and CS must go high while the address and data are set up. Then the STROBE input is set high and then low causing the data to be latched. The data can be changed while STROBE is high, however, the corresponding switch will turn on and off in accordance with the DATA input. DATA must be stable on the falling edge of STROBE in order for correct data to be written to the latch.

#### $\textbf{Absolute Maximum Ratings*-} \ \textit{Voltages are with respect to V}_{\textit{EE}} \ \textit{unless otherwise stated}.$

	Parameter	Symbol	Min.	Max.	Units
1	Supply Voltage	$V_{DD}$ $V_{SS}$	-0.3 -0.3	16.0 V <sub>DD</sub> +0.3	V V
2	Analog Input Voltage	V <sub>INA</sub>	-0.3	V <sub>DD</sub> +0.3	V
3	Digital Input Voltage	V <sub>IN</sub>	V <sub>SS</sub> -0.3	V <sub>DD</sub> +0.3	V
4	Current on any I/O Pin	I		±15	mA
5	Storage Temperature	T <sub>S</sub>	-65	+150	°C
6	Package Power Dissipation PLASTIC DIP	$P_{D}$		0.6	W

<sup>\*</sup> Exceeding these values may cause permanent damage. Functional operation under these conditions is not implied.

#### $\textbf{Recommended Operating Conditions} \text{ - Voltages are with respect to V}_{\text{EE}} \text{ unless otherwise stated}.$

	Characteristics	Sym.	Min.	Тур.	Max.	Units	Test Conditions
1	Operating Temperature	T <sub>O</sub>	-40	25	85	°C	
2	Supply Voltage	$V_{DD}$	4.5		13.2	V	
		$V_{SS}$	$V_{EE}$		V <sub>DD</sub> -4.5	V	
3	Analog Input Voltage	V <sub>INA</sub>	$V_{EE}$		$V_{DD}$	V	
4	Digital Input Voltage	V <sub>IN</sub>	V <sub>SS</sub>		$V_{DD}$	V	

## **DC Electrical Characteristics**<sup>†</sup>- Voltages are with respect to $V_{EE} = V_{SS} = 0$ V, $V_{DD} = 12$ V unless otherwise stated.

	Characteristics	Sym.	Min.	Typ. <sup>‡</sup>	Max.	Units	Test Conditions
1	Quiescent Supply Current	I <sub>DD</sub>		1	100	μА	All digital inputs at $V_{IN}$ = $V_{SS}$ or $V_{DD}$
				0.4	1.5	mA	All digital inputs at $V_{IN}$ =2.4V + $V_{SS}$ ; $V_{SS}$ =7.0 V
				5	15	mA	All digital inputs at V <sub>IN</sub> =3.4 V
2	Off-state Leakage Current (See G.9 in Appendix)	I <sub>OFF</sub>		±1	±500	nA	$IV_{Xi}$ - $V_{Yj}I = V_{DD}$ - $V_{EE}$ See Appendix, Fig. A.1
3	Input Logic "0" level	V <sub>IL</sub>			0.8+V <sub>S</sub> S	V	V <sub>SS</sub> =7.5V; V <sub>EE</sub> =0 V
4	Input Logic "1" level	V <sub>IH</sub>	2.0+V <sub>SS</sub>			V	$V_{SS}$ =6.5V; $V_{EE}$ =0 V
5	Input Logic "1" level	V <sub>IH</sub>	3.3			V	
6	Input Leakage (digital pins)	I <sub>LEAK</sub>		0.1	10	μΑ	All digital inputs at $V_{IN} = V_{SS}$ or $V_{DD}$

<sup>†</sup> DC Electrical Characteristics are over recommended temperature range. ‡ Typical figures are at 25°C and are for design aid only; not guaranteed and not subject to production testing.

#### DC Electrical Characteristics- Switch Resistance - V<sub>DC</sub> is the external DC offset applied at the analog I/O pins.

	Characteristics	Sym.	25	25°C		70°C		85°C		Test Conditions
			Тур.	Max.	Тур.	Max.	Тур.	Max.		
1	On-state $V_{DD}$ =12V Resistance $V_{DD}$ =10V $V_{DD}$ = 5V (See G.1, G.2, G.3 in Appendix)	R <sub>ON</sub>	45 55 120	65 75 185		75 85 215		80 90 225	Ω Ω Ω	$V_{SS}=V_{EE}=0 \text{ V,V}_{DC}=V_{DD}/2,$ $IV_{Xi}-V_{Yj}I=0.4 \text{ V}$ See Appendix, Fig. A.2
2	Difference in on-state resistance between two switches (See G.4 in Appendix)	ΔR <sub>ON</sub>	5	10		10		10	Ω	$\begin{split} & V_{DD}\text{=}12V,  V_{SS}\text{=}V_{EE}\text{=}0, \\ & V_{DC}\text{=}V_{DD}\text{/}2, \\ & IV_{Xi}\text{-}V_{Yj}I \text{=} 0.4  V \\ & See \; Appendix,  Fig. \; A.2 \end{split}$

#### $\textbf{AC Electrical Characteristics}^{\dagger} \textbf{- Crosspoint Performance} \textbf{-} \textbf{Voltages are with respect to V}_{DD} \textbf{= 5 V, V}_{SS} \textbf{= 0 V, V}_{EE} \textbf{= -7 V, unless}$ otherwise stated.

	Characteristics	Sym.	Min.	Typ. <sup>‡</sup>	Max.	Units	Test Conditions
1	Switch I/O Capacitance	C <sub>S</sub>		20		pF	f=1 MHz
2	Feedthrough Capacitance	C <sub>F</sub>		0.2		pF	f=1 MHz
3	Frequency Response Channel "ON" 20LOG(V <sub>OUT</sub> /V <sub>Xi</sub> )=-3 dB	F <sub>3dB</sub>		45		MHz	Switch is "ON"; $V_{INA}$ = 2Vpp sinewave; $R_L$ = 1 k $\Omega$ See Appendix, Fig. A.3
4	Total Harmonic Distortion (See G.5, G.6 in Appendix)	THD		0.01		%	Switch is "ON"; $V_{INA}$ = 2Vpp sinewave f= 1 kHz; $R_L$ =1 k $\Omega$
5	Feedthrough Channel "OFF" Feed.=20LOG (V <sub>OUT</sub> /V <sub>Xi</sub> ) (See G.8 in Appendix)	FDT		-95		dB	All Switches "OFF"; $V_{INA}$ = 2Vpp sinewave f= 1 kHz; $R_L$ = 1 k $\Omega$ . See Appendix, Fig. A.4
6	Crosstalk between any two channels for switches Xi-Yi and	X <sub>talk</sub>		-45		dB	$V_{INA}$ =2Vpp sinewave f= 10 MHz; R <sub>L</sub> = 75 Ω.
	Xj-Yj.			-90		dB	$V_{INA}$ =2Vpp sinewave f= 10 kHz; $R_L$ = 600 $\Omega$ .
	Xtalk=20LOG (V <sub>Yj</sub> /V <sub>Xi</sub> ). (See G.7 in Appendix).			-85		dB	$V_{INA}$ =2Vpp sinewave f= 10 kHz; R <sub>L</sub> = 1 kΩ.
	,			-80		dB	$V_{INA}$ =2Vpp sinewave f= 1 kHz; R <sub>L</sub> = 10 k $\Omega$ . Refer to Appendix, Fig. A.5 for test circuit.
7	Propagation delay through switch	t <sub>PS</sub>			30	ns	R <sub>L</sub> =1 kΩ; C <sub>L</sub> =50 pF

<sup>†</sup> Timing is over recommended temperature range. See Fig. 3 for control and I/O timing details.

‡ Typical figures are at 25°C and are for design aid only; not guaranteed and not subject to production testing.

Crosstalk measurements are for Plastic DIPS only, crosstalk values for PLCC packages are approximately 5 dB better.

AC Electrical Characteristics  $^{\dagger}$  - Control and I/O Timings- Voltages are with respect to  $V_{DD}$  = 5 V,  $V_{SS}$  = 0 V,  $V_{EE}$  = -7V, unless otherwise stated.

	Characteristics	Sym.	Min.	Typ.‡	Max.	Units	Test Conditions
1	Control Input crosstalk to switch (for CS, DATA, STROBE, Address)	CX <sub>talk</sub>		30		mVpp	$V_{IN}$ =3 V squarewave; $R_{IN}$ =1 kΩ, $R_{L}$ =10 kΩ. See Appendix, Fig. A.6
2	Digital Input Capacitance	C <sub>DI</sub>		10		pF	f=1 MHz
3	Switching Frequency	F <sub>O</sub>			20	MHz	
4	Setup Time DATA to STROBE	t <sub>DS</sub>	10			ns	$R_L$ = 1 kΩ, $C_L$ =50 pF <sup>δ</sup>
5	Hold Time DATA to STROBE	t <sub>DH</sub>	10			ns	R <sub>L</sub> = 1 kΩ, C <sub>L</sub> =50 pF <sup>(i)</sup>
6	Setup Time Address to STROBE	t <sub>AS</sub>	10			ns	$R_L$ = 1 k $\Omega$ , $C_L$ = 50pF $^{\&}$
7	Hold Time Address to STROBE	t <sub>AH</sub>	10			ns	$R_L$ = 1 kΩ, $C_L$ =50 pF $^{i}$
8	Setup Time CS to STROBE	t <sub>CSS</sub>	10			ns	$R_L$ = 1 kΩ, $C_L$ =50 pF $^{i}$
9	Hold Time CS to STROBE	t <sub>CSH</sub>	10			ns	R <sub>L</sub> = 1 kΩ, C <sub>L</sub> =50 pF <sup>δ</sup>
10	STROBE Pulse Width	t <sub>SPW</sub>	20			ns	$R_L$ = 1 kΩ, $C_L$ =50 pF $^{i}$
11	RESET Pulse Width	t <sub>RPW</sub>	40			ns	$R_L$ = 1 kΩ, $C_L$ =50 pF $^{i}$
12	STROBE to Switch Status Delay	t <sub>S</sub>		40	100	ns	R <sub>L</sub> = 1 kΩ, C <sub>L</sub> =50 pF <sup>δ</sup>
13	DATA to Switch Status Delay	t <sub>D</sub>		50	100	ns	$R_L$ = 1 kΩ, $C_L$ =50 pF $^{i}$
14	RESET to Switch Status Delay	t <sub>R</sub>		35	100	ns	R <sub>L</sub> = 1 kΩ, C <sub>L</sub> =50 pF <sup>¿</sup>

<sup>†</sup> Timing is over recommended temperature range. See Fig. 3 for control and I/O timing details.

Digital Input rise time (tr) and fall time (tf) = 5 ns.

‡ Typical figures are at 25°C and are for design aid only; not guaranteed and not subject to production testing.

¿ Refer to Appendix, Fig. A.7 for test circuit.

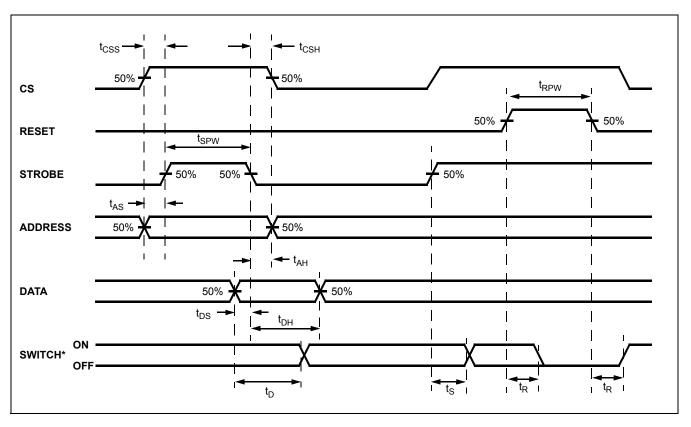


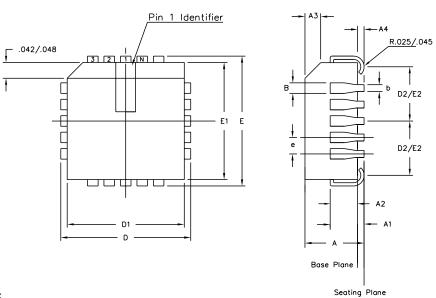
Figure 3 - Control Memory Timing Diagram

<sup>\*</sup> See Appendix, Fig. A.7 for switching waveform

AX0	AX1	AX2	AX3	AY0	AY1	AY2	Connection*
0	0	0	0	0	0	0	X0-Y0
1	0	0	0	0	0	0	X1-Y0
0	1	0	0	0	0	0	X2-Y0
1	1	0	0	0	0	0	X3-Y0
0	0	1	0	0	0	0	X4-Y0
1	0	1	0	0	0	0	X5-Y0
0	1	1	0	0	0	0	X12-Y0
1	1	1	0	0	0	0	X13-Y0
0	0	0	1	0	0	0	X6-Y0
1	0	0	1	0	0	0	X7-Y0
0	1	0	1	0	0	0	X8-Y0
1	1	0	1	0	0	0	X9-Y0
0	0	1	1	0	0	0	X10-Y0
1	0	1	1	0	0	0	X11-Y0
0	1	1	1	0	0	0	X14-Y0
1	1	1	1	0	0	0	X15-Y0
0	0	0	0	1	0	0	X0-Y1 ↓ ↓
1	1	1	1	1	0	0	X15-Y1
0	0	0	0	0	1	0	X0-Y2 ↓↓
1	1	1	1	0	1	0	X15-Y2
0	0	0	0	1	1	0	X0-Y3 ↓↓
1	1	1	1	1	1	0	X15-Y3
0	0	0	0	0	0	1	X0-Y4 ↓ ↓
1	1	1	1	0	0	1	X15-Y4
0	0	0	0	1	0	1	X0-Y5 ↓ ↓
1	1	1	1	1	0	1	X15-Y5
0	0	0	0	0	1	1	X0-Y6 ↓ ↓
1	1	1	1	0	1	1	X15-Y6
0	0	0	0	1	1	1	X0-Y7 ↓↓
1	1	1	1	1	1	1	X15-Y7

Table 1 - Address Decode Truth Table

<sup>\*</sup> Switch connections are not in ascending order



	Control Di	imensions	Altern. Di	mensions			
Symbol	in inc	hes	in millimetres				
	MIN	MAX	MIN	MAX			
Α	0.165	0.180	4.19	4.57			
A1	0.090	0.120	2.29	3.05			
A2	0.062	0.083	1.57	2.11			
А3	0.042	0.056	1.07	1.42			
Α4	0.020	-	0.51	_			
D	0.685	0.695	17.40	17.65			
D1	0.650	0.656	16.51	16.66			
D2	0.291	0.319	7.39	8.10			
Ε	0.685	0.695	17.40	17.65			
E1	0.650	0.656	16.51	16.66			
E2	0.291	0.319	7.39	8.10			
В	0.026	0.032	0.66	0.81			
b	0.013	0.021	0.33	0.53			
е	0.050	BSC	1.27	BSC			
		Pin fed	atures				
ND	11						
NE	11						
N	44						
Note		Squo	are				
Confor	ms to J	EDEC MS	-018AC	Iss. A			

- Notes:

  1. All dimensions and tolerances conform to ANSI Y14.5M—1982
  2. Dimensions D1 and E1 do not include mould protrusions.
  Allowable mould protrusion is 0.010" per side. Dimensions D1 and E1 include mould protrusion mismatch and are determined at the parting line, that is D1 and E1 are measured at the extreme material condition at the upper or lower parting line.

  3. Controlling dimensions in Inches.

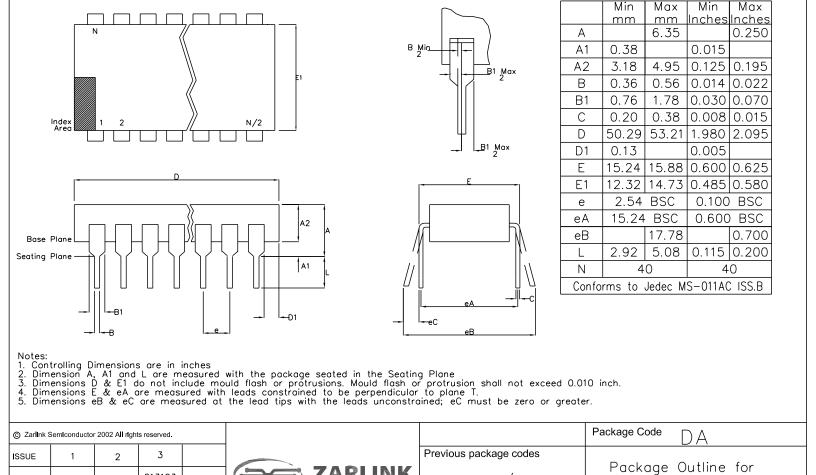
  4. "N" is the number of terminals.

  5. Not To Scale

  6. Dimension R required for 120" minimum bend.

- 6. Dimension R required for 120° minimum bend.

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ISSUE	1	2	3			Previous package codes	Package Outline for
ACN	5958	207470	213094		ZARLINK SEMICONDUCTOR	HP / P	44 lead PLCC
DATE	15Aug94	10Sep99	15Jul02			,	
APPRD.							GPD00003



40 lead PDIP

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