MCM67M518

FN PACKAGE

PLASTIC

CASE 778-02

PIN ASSIGNMENT

32K x 18 Bit BurstRAM[™] Synchronous Fast Static RAM With Burst Counter and Self–Timed Write

The MCM67M518 is a 589,824 bit synchronous static random access memory designed to provide a burstable, high–performance, secondary cache for the MC68040 and PowerPC[™] microprocessors. It is organized as 32,768 words of 18 bits, fabricated using Motorola's high–performance silicon–gate BiCMOS technology. The device integrates input registers, a 2–bit counter, high speed SRAM, and high drive capability outputs onto a single monolithic circuit for reduced parts count implementation of cache data RAM applications. Synchronous design allows precise cycle control with the use of an external clock (K). BiCMOS circuitry reduces the overall power consumption of the integrated functions for greater reliability.

Addresses (A0 – A14), data inputs (DQ0 – DQ17), and all control signals, except output enable (\overline{G}), are clock (K) controlled through positive–edge–triggered noninverting registers.

Bursts can be initiated with either transfer start processor ($\overline{\text{TSP}}$) or transfer start cache controller ($\overline{\text{TSC}}$) input pins. Subsequent burst addresses are generated internally by the MCM67M518 (burst sequence imitates that of the MC68040 and PowerPC) and controlled by the burst address advance ($\overline{\text{BAA}}$) input pin. The following pages provide more detailed information on burst controls.

Write cycles are internally self-timed and are initiated by the rising edge of the clock (K) input. This feature eliminates complex off-chip write pulse generation and provides increased flexibility for incoming signals.

Dual write enables (\overline{LW} and \overline{UW}) are provided to allow individually writeable bytes. \overline{LW} controls DQ0 – DQ8 (the lower bits), while \overline{UW} controls DQ9 – DQ17 (the upper bits).

This device is ideally suited for systems that require wide data bus widths and cache memory.

- Single 5 V \pm 5% Power Supply
- Fast Access Times: 9/11/14 ns Max and Cycle Times: 12.5/15/20 ns Min
- Byte Writeable via Dual Write Strobes
- Internal Input Registers (Address, Data, Control)
- Internally Self-Timed Write Cycle
- TSP, TSC, and BAA Burst Control Pins
- Asynchronous Output Enable Controlled Three-State Outputs
- · Common Data Inputs and Data Outputs
- High Board Density 52–PLCC Package
- 3.3 V I/O Compatible

54 32 1 52 51 50 49 48 47 46 DQ8 dq9 [8 DQ10 0 9 DQ7 45 H V_{CC} [10 44 DO6 43 🛛 V_{CC} VSS [11 DQ11 12 42 Vss DQ12 13 41 DQ5 DQ13 14 40 DQ4 ,3 ,Q14 L VSS [] ,7C [] 17 ,5C [] 18 ,5C [] 17 ,17 DQ14 39 DQ3 38 DQ2 37 Vss DQ15 36 VCC DQ16 🛛 19 35 D DQ1 DQ17 34 D DQ0 20 22 23 24 25 26 27 28 29 30 31 32 A3 A5 Я

All power supply and ground pins must be connected for proper operation of the device.

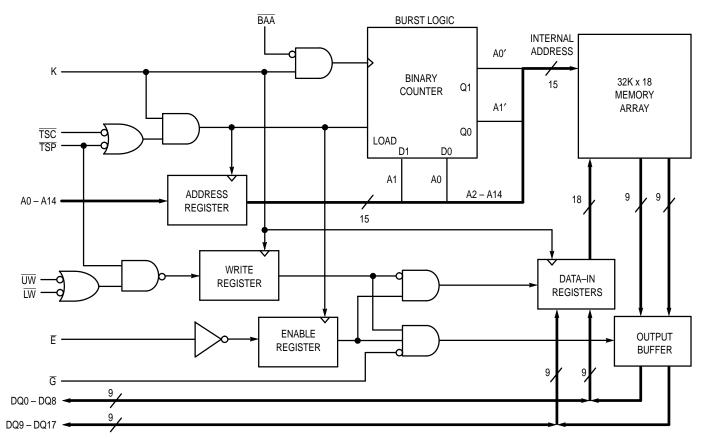
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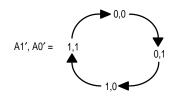
BLOCK DIAGRAM (See Note)



NOTE: All registers are positive–edge triggered. The TSC or TSP signals control the duration of the burst and the start of the next burst. When TSP is sampled low, any ongoing burst is interrupted and a read (independent of W and TSC) is performed using the new external address. Alternatively, a TSP–initiated two cycle WRITE can be performed by asserting TSP and a valid address on the first cycle, then negating both TSP and TSC and asserting LW and/or UW with valid data on the second cycle (see Single Write Cycle in WRITE CYCLES timing diagram).

When $\overline{\mathsf{TSC}}$ is sampled low (and $\overline{\mathsf{TSP}}$ is sampled high), any ongoing burst is interrupted and a read or write (dependent on $\overline{\mathsf{W}}$) is performed using the new external address. Chip enable ($\overline{\mathsf{E}}$) is sampled only when a new base address is loaded. After the first cycle of the burst, $\overline{\mathsf{BAA}}$ controls subsequent burst cycles. When $\overline{\mathsf{BAA}}$ is sampled low, the internal address is advanced prior to the operation. When $\overline{\mathsf{BAA}}$ is sampled high, the internal address is not advanced, thus inserting a wait state into the burst sequence accesses. Upon completion of a burst, the address will wrap around to its initial state. See **BURST SEQUENCE TABLE**. Write refers to either or both byte write enables ($\overline{\mathsf{LW}}$, $\overline{\mathsf{LW}}$).

BURST SEQUENCE GRAPH (See Note)



NOTE: The external two values for A1 and A0 provide the starting point for the burst sequence graph. The burst logic advances A1 and A0 as shown above.

SYNCHRONOUS TRUTH TABLE (See Notes 1, 2, and 3)

Ē	TSP	TSC	BAA	LW or UW	к	Address	Operation
Н	L	Х	Х	Х	L–H	N/A	Deselected
Н	Х	L	Х	Х	L–H	N/A	Deselected
L	L	Х	Х	Х	L–H	External Address	Read Cycle, Begin Burst
L	Н	L	Х	L	L–H	External Address	Write Cycle, Begin Burst
L	Н	L	Х	Н	L–H	External Address	Read Cycle, Begin Burst
Х	Н	Н	L	L	L–H	Next Address	Write Cycle, Continue Burst
Х	н	Н	L	Н	L–H	Next Address	Read Cycle, Continue Burst
Х	Н	Н	Н	L	L–H	Current Address	Write Cycle, Suspend Burst
Х	Н	Н	н	Н	L–H	Current Address	Read Cycle, Suspend Burst

NOTES:

1. X means Don't Care.

2. All inputs except \overline{G} must meet setup and hold times for the low-to-high transition of clock (K).

3. Wait states are inserted by suspending burst.

ASYNCHRONOUS TRUTH TABLE (See Notes 1 and 2)

Operation	G	I/O Status		
Read	L	Data Out		
Read	Н	High–Z		
Write	Х	High–Z — Data In		
Deselected	Х	High–Z		

NOTES:

1. X means Don't Care.

2. For a write operation following a read operation, G must be high before the input data required setup time and held high through the input data hold time.

ABSOLUTE MAXIMUM RATINGS (Voltages Referenced to V_{SS} = 0 V)

Rating	Symbol	Value	Unit
Power Supply Voltage	VCC	– 0.5 to + 7.0	V
Voltage Relative to V_{SS} for Any Pin Except V_{CC}	V _{in} , V _{out}	– 0.5 to V _{CC} + 0.5	V
Output Current (per I/O)	lout	± 30	mA
Power Dissipation	PD	1.6	W
Temperature Under Bias	T _{bias}	– 10 to + 85	°C
Operating Temperature	TA	0 to +70	°C
Storage Temperature	T _{stg}	– 55 to + 125	°C

NOTE: Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to RECOMMENDED OPER-ATING CONDITIONS. Exposure to higher than recommended voltages for extended periods of time could affect device reliability. This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to this high–impedance circuit.

This BiCMOS memory circuit has been designed to meet the dc and ac specifications shown in the tables, after thermal equilibrium has been established.

This device contains circuitry that will ensure the output devices are in High–Z at power up.

DC OPERATING CONDITIONS AND CHARACTERISTICS

(V_{CC} = 5.0 V \pm 5%, T_A = 0 to + 70°C, Unless Otherwise Noted)

RECOMMENDED OPERATING CONDITIONS (Voltages referenced to $V_{SS} = 0 V$)

Parameter	Symbol	Min	Max	Unit
Supply Voltage (Operating Voltage Range)	VCC	4.75	5.25	V
Input High Voltage	VIH	2.2	V _{CC} + 0.3**	V
Input Low Voltage	VIL	- 0.5*	0.8	V

* V_{IL} (min) = -0.5 V dc; V_{IL} (min) = -2.0 V ac (pulse width ≤ 20.0 ns) for I ≤ 20.0 mA.

** V_{IH} (max) = V_{CC} + 0.3 V dc; V_{IH} (max) = V_{CC} + 2.0 V ac (pulse width \leq 20.0 ns) for I \leq 20.0 mA.

DC CHARACTERISTICS AND SUPPLY CURRENTS

Parameter	Symbol	Min	Max	Unit
Input Leakage Current (All Inputs, V _{in} = 0 to V _{CC})	I _{lkg(I)}	—	± 1.0	μΑ
Output Leakage Current ($\overline{G} = V_{IH}$)	I _{lkg(O)}	—	± 1.0	μΑ
AC Supply Current ($\overline{G} = V_{IH}$, $\overline{E} = V_{IL}$, $I_{out} = 0$ mA, All Inputs = V_{IL} or V_{IH} , $V_{IL} = 0.0$ V and $V_{IH} \ge 3.0$ V, Cycle Time $\ge t_{KHKH}$ min)	ICCA9 ICCA11 ICCA14	_	290 275 250	mA
AC Standby Current (\overline{E} = V _{IH} , I _{Out} = 0 mA, All Inputs = V _{IL} and V _{IH} , V _{IL} = 0.0 V and V _{IH} ≥ 3.0 V, Cycle Time ≥ t _{KHKH} min)	ISB1	_	75	mA
Output Low Voltage (I _{OL} = + 8.0 mA)	VOL	—	0.4	V
Output High Voltage (I _{OH} = - 4.0 mA)	VOH	2.4	3.3	V

NOTE: Good decoupling of the local power supply should always be used. DC characteristics are guaranteed for all possible MC68040 and PowerPC bus cycles.

CAPACITANCE (f = 1.0 MHz, dV = 3.0 V, T_A = 25°C, Periodically Sampled Rather Than 100% Tested)

Parameter	Symbol	Тур	Max	Unit
Input Capacitance (All Pins Except DQ0 – DQ17)	C _{in}	4	5	pF
Input/Output Capacitance (DQ0 – DQ17)	C _{I/O}	6	8	pF

AC OPERATING CONDITIONS AND CHARACTERISTICS

(V_{CC} = 5.0 V \pm 5% T_A = 0 to + 70°C, Unless Otherwise Noted)

Input Timing Measurement Reference Level	. 1.5 V
Input Pulse Levels 0 t	o 3.0 V
Input Rise/Fall Time	3 ns

READ/WRITE CYCLE TIMING (See Notes 1, 2, 3, a	and 4)
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			MCM67	'M518–9	MCM67	M518–11	MCM67	M518–14		
Pa	rameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Cycle Time		^t КНКН	12.5	—	15	—	20	—	ns	
Clock Access Time	9	^t KHQV	_	9	—	11	—	14	ns	5
Output Enable to C	Dutput Valid	^t GLQV	_	5	—	5	—	6	ns	
Clock High to Outp	out Active	^t KHQX1	6	—	6	—	6	—	ns	
Clock High to Outp	out Change	^t KHQX2	3	—	3	—	3	—	ns	
Output Enable to C	Dutput Active	^t GLQX	0	—	0	—	0	—	ns	
Output Disable to 0	Output Disable to Q High-Z		_	6	—	7	—	7	ns	6
Clock High to Q High-Z		^t KHQZ	3	6	3	7	3	7	ns	6
Clock High Pulse V	Clock High Pulse Width		5	—	5	—	6	—	ns	
Clock Low Pulse W	Vidth	^t KLKH	5	—	5	—	6	—	ns	
Setup Times:	Address Address Status Data In Write Address Advance Chip Select	^t avkh ^t TSVKH ^t DVKH ^t WVKH ^t BAVKH ^t EVKH	2.5	_	2.5	_	2.5	_	ns	7
Hold Times:	Address Address Status Data In Write Address Advance Chip Select	^t KHAX ^t KHTSX ^t KHDX ^t KHWX ^t KHBAX ^t KHEX	0.5	_	0.5	_	0.5	_	ns	7

NOTES:

1. In setup and hold times, W (write) refers to either one or both byte write enables LW and UW.

2. A read cycle is defined by UW and LW high or TSP low for the setup and hold times. A write cycle is defined by LW or UW low and TSP high for the setup and hold times.

3. All read and write cycle timings are referenced from K or \overline{G} .

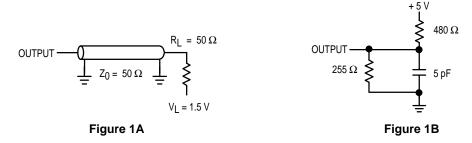
4. \overline{G} is a don't care when \overline{UW} or \overline{LW} is sampled low.

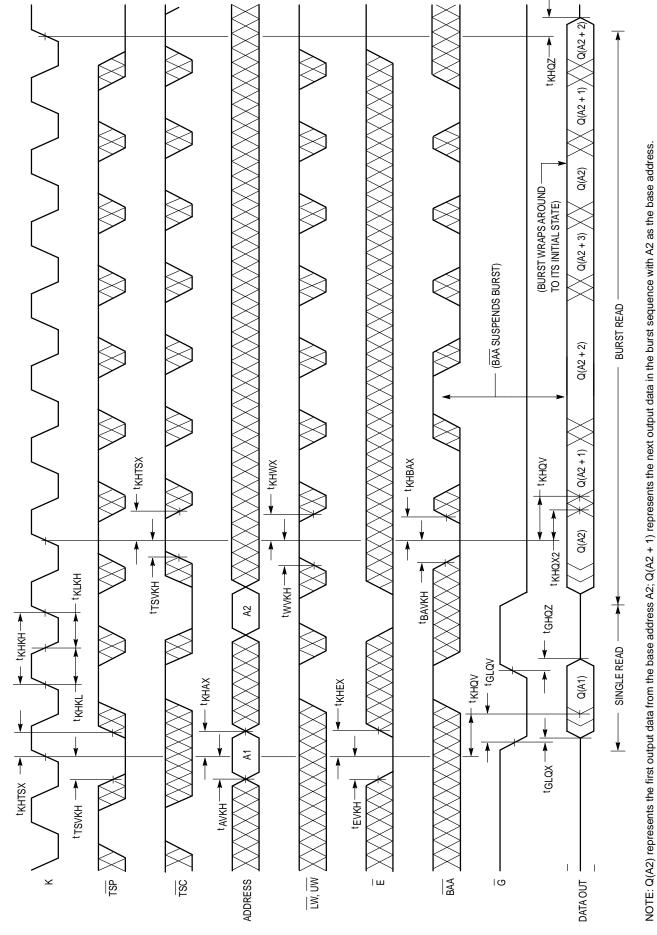
5. Maximum access times are guaranteed for all possible MC68040 and PowerPC external bus cycles.

6. Transition is measured ± 500 mV from steady–state voltage with load of Figure 1B. This parameter is sampled and not 100% tested. At any given voltage and temperature, t_{KHQZ} max is less than t_{KHQX1} min for a given device and from device to device.

7. This is a synchronous device. All addresses must meet the specified setup and hold times for *ALL* rising edges of clock (K) whenever TSP or TSC are low and the chip is selected. All other synchronous inputs must meet the specified setup and hold times for *ALL* rising edges of K when the chip is selected. Chip enable must be valid at each rising edge of clock for the device (when TSP or TSC is low) to remain enabled.

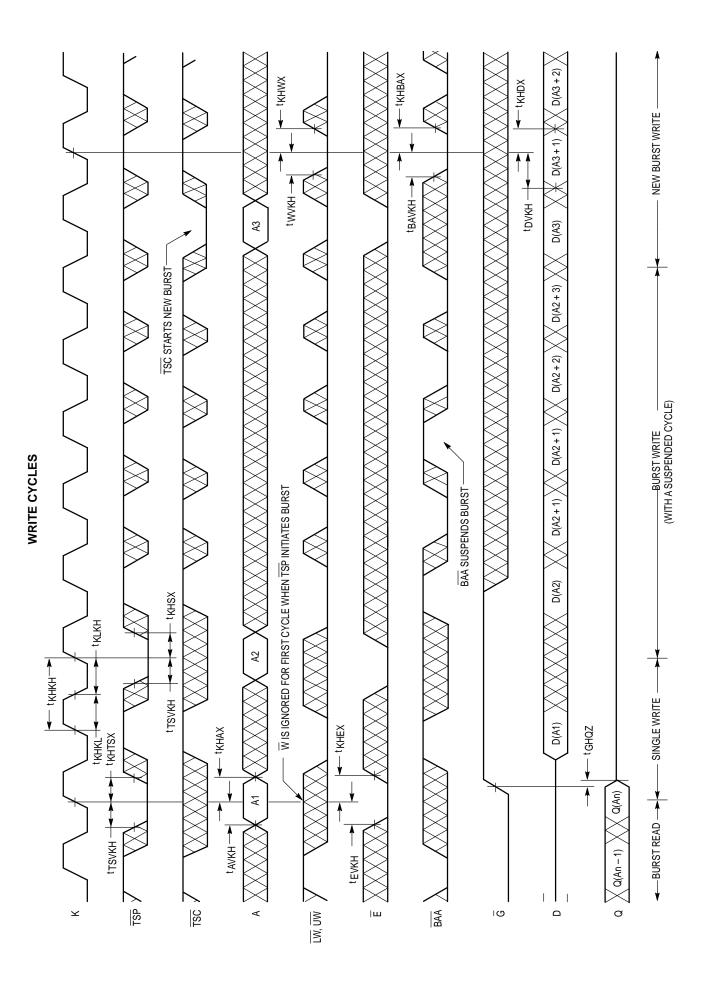
AC TEST LOADS



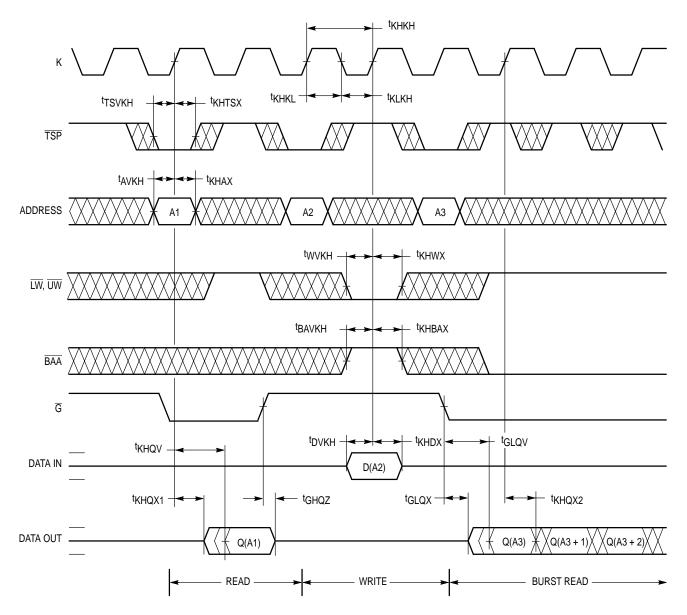


READ CYCLES

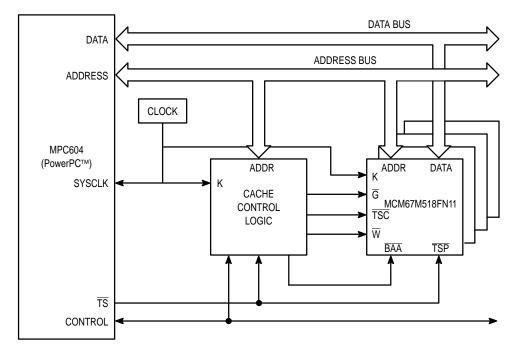
MOTOROLA FAST SRAM



COMBINATION READ/WRITE CYCLE (E low, TSC high)



APPLICATION EXAMPLE



256K Byte Burstable, Secondary Cache Using Four MCM67M518FN11s with a 66 MHz (bus speed) MPC604 PowerPC[™]

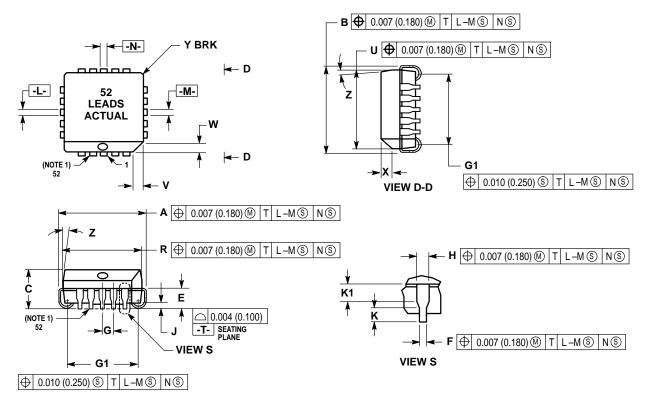
ORDERING INFORMATION (Order by Full Part Number)

	I	<u>исм</u>	<u>67M518</u>	<u>xx</u>	<u>xx</u>	
Motorola Men	nory Prefix					Speed (9 = 9 ns, 11 = 11 ns, 14 = 14 ns)
Part Number						Package (FN = PLCC)
	Full Part Numbers -	- MCM6	7M518FN9	MCI	M67M518FN	11 MCM67M518FN14

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NOTES:

- DUE TO SPACE LIMITATION, CASE 778-02 SHALL BE 1. REPRESENTED BY A GENERAL (SMALLER) CASE OUTLINE DRAWING RATHER THAN SHOWING ALL 52 LEADS.
- DATUMS -L-, -M-, AND -N- DETERMINED WHERE TOP OF LEAD SHOULDER EXITS PLASTIC BODY AT MOLD 2.
- PARTING LINE. DIM G1, TRUE POSITION TO BE MEASURED AT DATUM -T-, 3.
- 4.
- 5.
- 1982. 6. CONTROLLING DIMENSION: INCH.
- CONTROLLING DIMENSION: INCH. THE PACKAGE TOP MAY BE SMALLER THAN THE PACKAGE BOTTOM BY UP TO 0.012 (0.300). DIMENSIONS R AND U ARE DETERMINED AT THE OUTERMOST EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD FLASH, TIE BAR BURRS, GATE BURRS AND INTERLEAD FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE TOP AND BOTTOM OF THE PLASTIC BODY. DIMENSION H DOES NOT INCLUDE DAMBAR PROTRUSION OR INTRUSION. THE DAMBAR PROTRUSION (S) SHALL NOT CAUSE THE H DIMENSION TO BE GREATER THAN 0.337 (0.940). THE DAMBAR
- 8 INTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE SMALLER THAN 0.025 (0.635).

	INC	HES	MILLIN	METERS	
DIM	DIM MIN MAX		MIN	MAX	
Α	0.785	0.795	19.94	20.19	
В	0.785	0.795	19.94	20.19	
С	0.165	0.180	4.20	4.57	
E	0.090	0.110	2.29	2.79	
F	0.013	0.019	0.33	0.48	
G	0.05	0 BSC	1.27 BSC		
н	0.026	0.032	0.66	0.81	
J	0.020	-	0.51	-	
ĸ	0.025	-	0.64	-	
R	0.750	0.756	19.05	19.20	
U	0.750	0.756	19.05	19.20	
V	0.042	0.048	1.07	1.21	
w	0.042	0.048	1.07	1.21	
Х	0.042	0.056	1.07	1.42	
Y	_	0.020	-	0.50	
Z	2°	10°	2°	10°	
G1	0.710	0.730	18.04	18.54	
K1	0.040	-	1.02	_	

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