

# HA1666P/FP

600kHz PWM Controlled Switching Regulator

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## Description

The HA1666P/FP is a voltage mode PWM (pulse width modulation) control IC for switching regulator control. It can drive a power MOS FET efficiently on 600 kHz. Its stanby current is 0.3 mA (max), and it is used as the primary control power supply.

## Functions

- +5 V reference voltage circuit
- Triangular waveform oscillator
- PWM comparator
- Output circuit (Totem pole output)
- Overcurrent protection circuit (with one-pulse latch mode)
- Undervoltage lockout protection circuit
- Soft start and quick shutdown function
- Remote control function
- Comparator with internal 1.3 V reference voltage

## Features

- High-speed switching;  
 $t_r = 80 \text{ ns}$  (15 V amplitude)  
 $t_f = 40 \text{ ns}$  (15 V amplitude)
- Low power dissipation;  
0.3 mA max in standby state  
12 mA max in operation state ( $V_{IN} = 15 \text{ V}$ )
- Dual-slope highly accurate dead-band duty setup circuit; Setup accuracy  $D_u = \pm 3\% \text{ (max)}$
- Wide output pulse width control range; 0 to 75%



# **HA1666P/FP**

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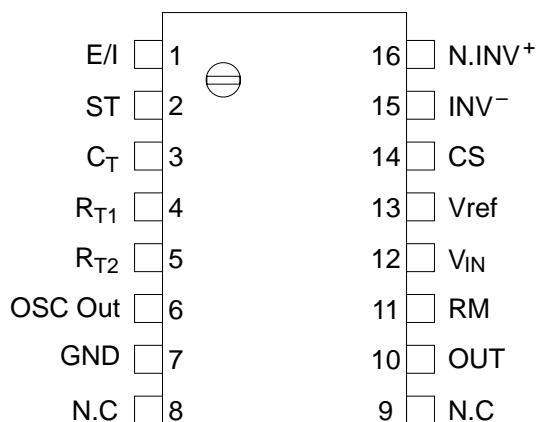
- Undervoltage lockout protection;  
     $V_{IN}$  high threshold voltage 10 V typ  
     $V_{IN}$  low threshold voltage 8 V typ
- Two input threshold voltage for overcurrent protection comparator;  
    fixed voltage (1.3 V)  
    variable voltage
- Double pulse output protection by overcurrent protection circuit with one-pulse latch mode
- Wide input supply voltage range;  $V_{CC} = 11$  to 40 V

## **Ordering Information**

| Type     | Package |
|----------|---------|
| HA1666P  | DP-16   |
| HA1666FP | FP-16DA |

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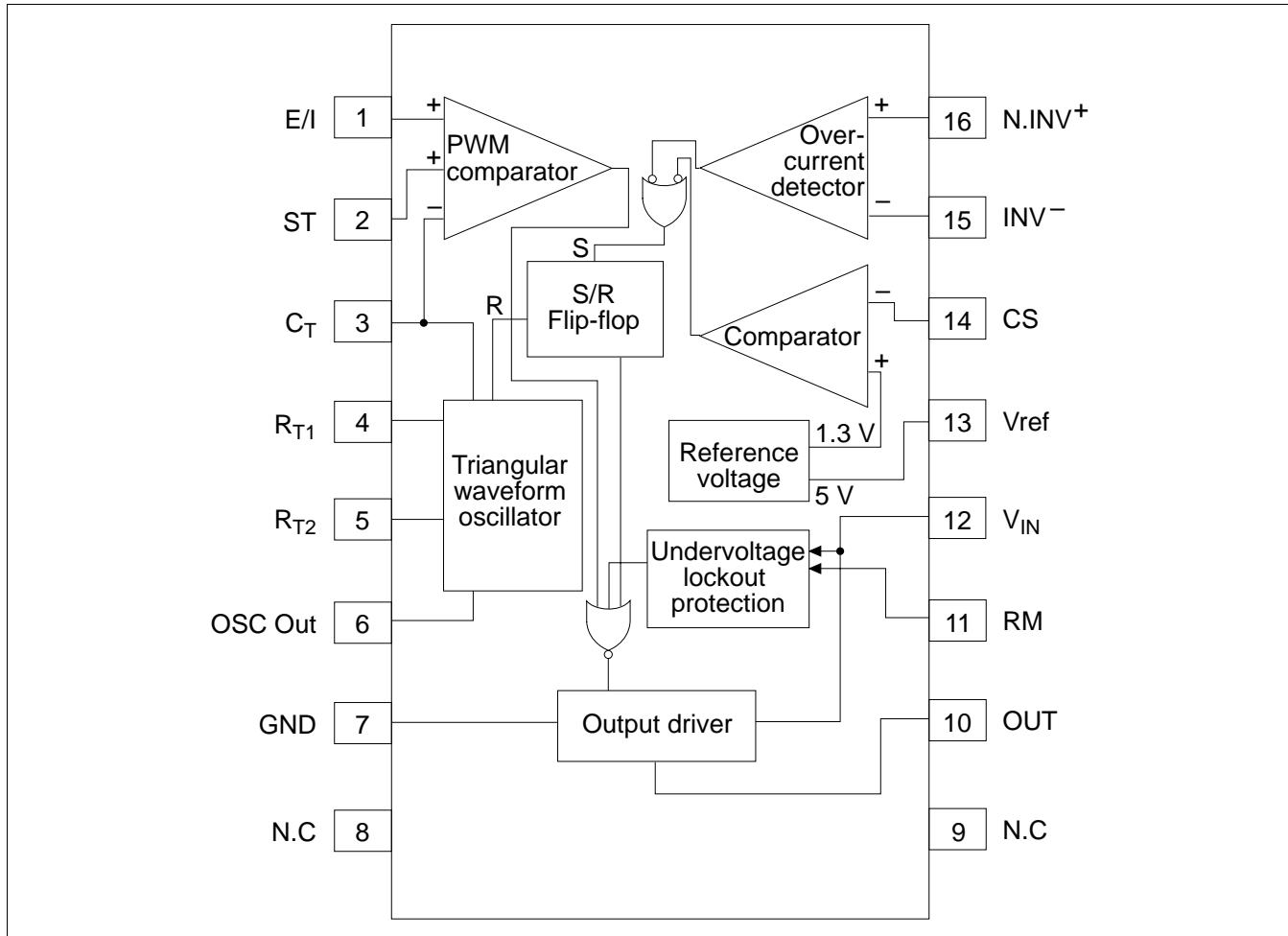
## Pin Arrangement



(Top View)

## Pin Functions

| Pin No. | Symbol             | Description   |
|---------|--------------------|---|
| 1       | E/I                | Error input   |
| 2       | ST                 | Soft start  |
| 3       | C <sub>T</sub>     | Timing capacitance                                  |
| 4       | R <sub>T1</sub>    | Timing resistor (rise section)                      |
| 5       | R <sub>T2</sub>    | Timing resistor (fall section)                      |
| 6       | OSC Out            | Triangular waveform oscillator                      |
| 7       | GND                | Ground  |
| 8       | N.C.               | No connect  |
| 9       | N.C.               | No connect  |
| 10      | OUT                | Pulse output  |
| 11      | RM                 | Remote control                                      |
| 12      | V <sub>IN</sub>    | Power supply voltage                                |
| 13      | Vref               | Reference voltage (5 V) output                      |
| 14      | CS                 | Comparator input (-) with reference voltage (1.3 V) |
| 15      | INV <sup>-</sup>   | Comparator input (-) for overcurrent protection     |
| 16      | N.INV <sup>+</sup> | Comparator input (+) for overcurrent protection     |

**Block Diagram****HITACHI**

**Absolute Maximum Ratings (Ta = 25°C)**

| Item                          | Symbol           | Rating                             |                                    | Unit |
|-------------------------------|------------------|------------------------------------|------------------------------------|------|
|                               |                  | HA1666P                            | HA1666FP                           |      |
| Power supply voltage          | V <sub>IN</sub>  | +40                                | +40                                | V    |
| Output current<br>(Push-pull) | DC               | I <sub>O(DC)</sub>                 | 100                                | mA   |
|                               | Peak             | I <sub>O(peak)</sub>               | 500*1                              | mA   |
| Error input                   | V <sub>EI</sub>  | Vref                               | Vref                               | V    |
| OSC input voltage             | V <sub>OSC</sub> | V <sub>IN</sub> – 3V <sub>BE</sub> | V <sub>IN</sub> – 3V <sub>BE</sub> | V    |
| CS input voltage              | V <sub>CS</sub>  | Vref                               | Vref                               | V    |
| RM input voltage              | V <sub>RM</sub>  | V <sub>IN</sub>                    | V <sub>IN</sub>                    | V    |
| RT2 input current             | I <sub>R2</sub>  | 1                                  | 1                                  | mA   |
| RT1 input current             | I <sub>R1</sub>  | 1                                  | 1                                  | mA   |
| Power dissipation             | P <sub>T</sub>   | 680*2                              | 680*3                              | mW   |
| Operation temperature         | To <sub>pr</sub> | –20 to +85                         | –20 to +85                         | °C   |
| Storage temperature           | T <sub>stg</sub> | –55 to +125                        | –55 to +125                        | °C   |

Notes: 1. Value at 300 ns of switching time

2. Value at Ta ≤ 45°C. If Ta > 45°C, derated by 8.3 mW/°C

3. Value under the condition of 40 mm × 40 mm × 0.8 t ceramics board epoxy board

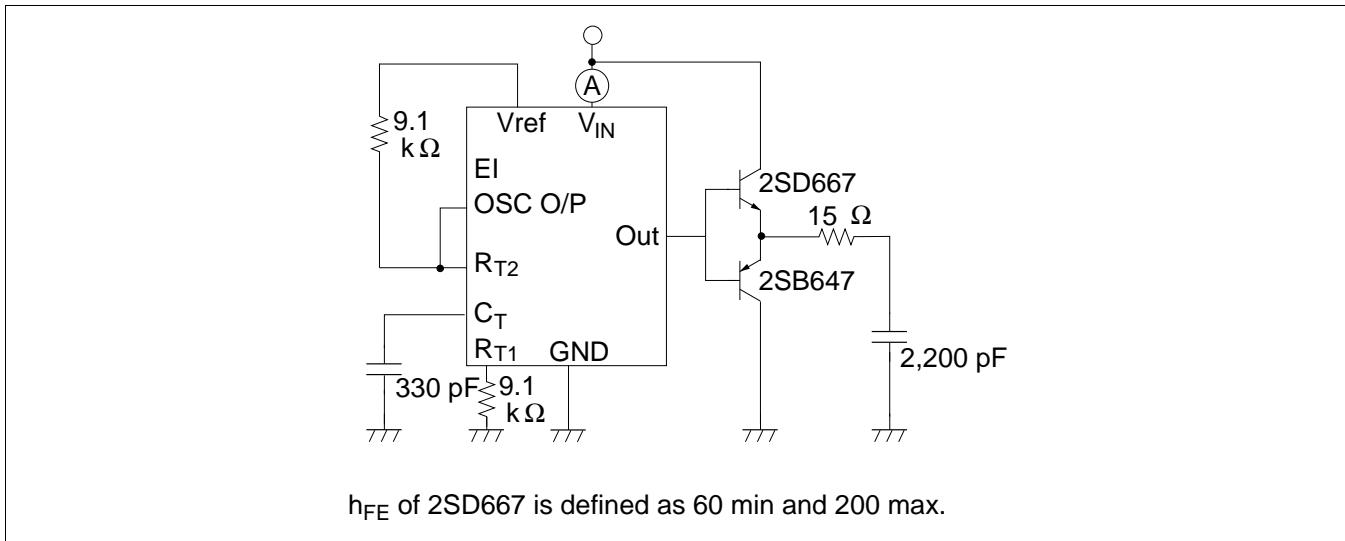
**Electrical Characteristics (V<sub>IN</sub> = 15 V, Ta = 25°C, fosc = 300 kHz)**

| Item                           | Symbol                               | Min              | Typ  | Max  | Unit | Test Condition                  |
|--------------------------------|--------------------------------------|------------------|------|------|------|---------------------------------|
| Voltage reference              | Output voltage                       | Vref             | 4.75 | 5.00 | 5.25 | V no load                       |
|                                | Line regulation                      | Line             | —    | 50   | 100  | mV V <sub>IN</sub> = 11 to 40 V |
|                                | Load regulation                      | Load             | —    | 9    | 20   | mV I <sub>O</sub> = 0 to 10 mA  |
|                                | Temperature stability                | V <sub>RTC</sub> | —    | +60  | —    | ppm/°C no load                  |
|                                | Short circuit current                | I <sub>OS</sub>  | 10   | 35   | —    | mA Vref = 0 V                   |
| Triangular waveform oscillator | Maximum frequency                    | f <sub>max</sub> | 600  | —    | —    | kHz C <sub>T</sub> = 150 pF     |
|                                | Minimum frequency                    | f <sub>min</sub> | —    | —    | 1    | kHz C <sub>T</sub> = 0.15 μF    |
|                                | Frequency accuracy                   | f <sub>der</sub> | –10  | 0    | +10  | %                               |
|                                | Voltage stability                    | f <sub>T</sub>   | —    | 1    | —    | % 11 V ≤ V <sub>IN</sub> ≤ 40 V |
|                                | Temperature coefficient of frequency | f <sub>i</sub>   | —    | 2    | —    | % –20°C ≤ Ta ≤ +85°C            |

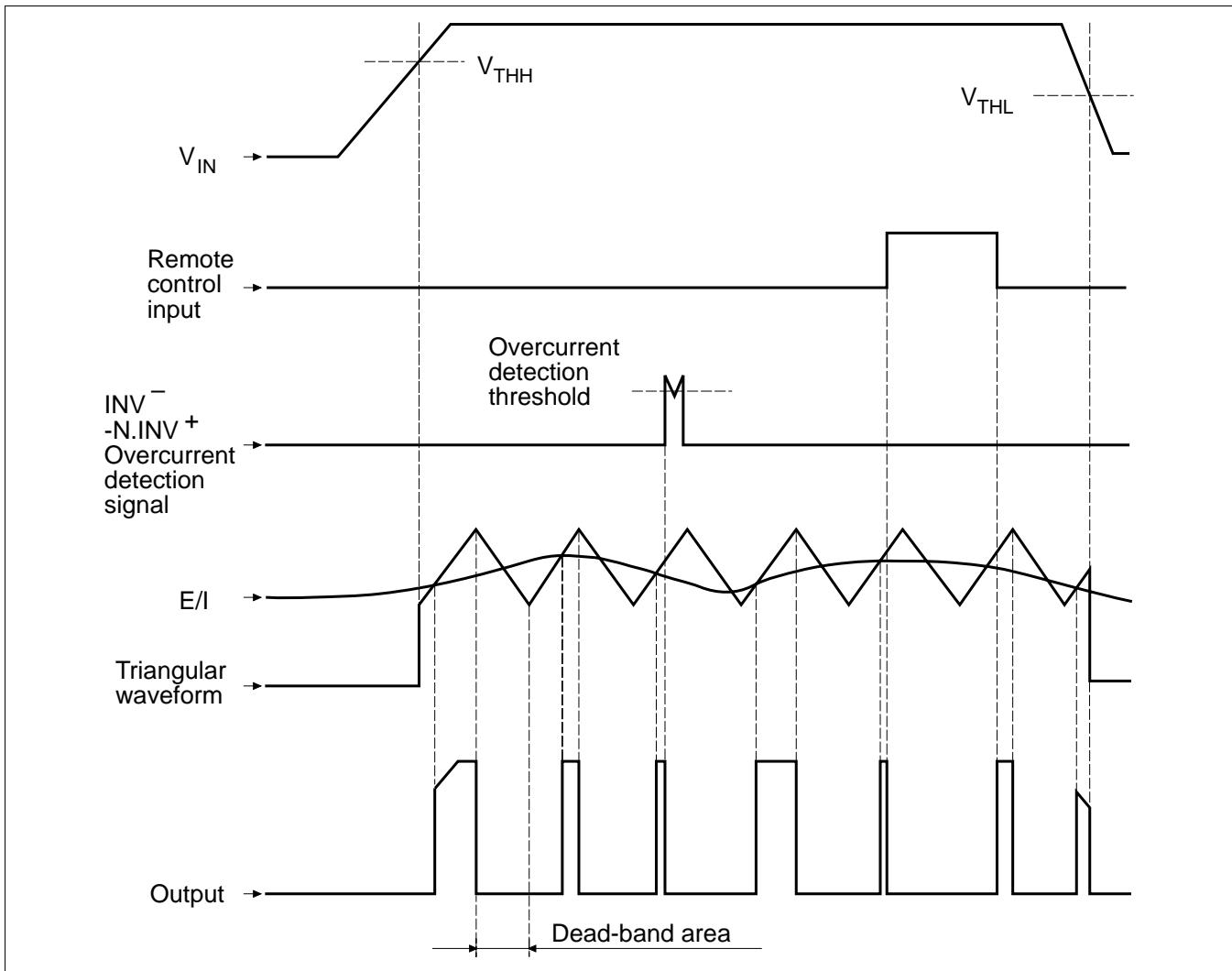
**Electrical Characteristics (V<sub>IN</sub> = 15 V, Ta = 25°C, fosc = 300 kHz) (cont)**

| Item                                 |   | Symbol            | Min                      | Typ  | Max              | Unit | Test Condition                  |
|--------------------------------------|---|-------------------|--------------------------|------|------------------|------|---------------------------------|
| PWM<br>comparator                    | Maximum duty cycle                        | D <sub>U</sub>    | 75                       | —    | —                | %    |                                 |
|                                      | Input bias current                        | I <sub>B</sub>    | -2                       | —    | —                | μA   | Pin 1                           |
|                                      | Low-level threshold voltage               | V <sub>OSCL</sub> | —                        | 1.5  | —                | V    | Pin 1                           |
|                                      | High-level threshold voltage              | V <sub>OSCH</sub> | —                        | 2.5  | —                | V    | Pin 1                           |
|                                      | Dead-band duty accuracy                   | Δ D <sub>U</sub>  | —                        | ±1   | ±3               | %    |                                 |
|                                      | Dead-band duty input voltage stability    | D <sub>T</sub>    | —                        | 1    | —                | %    | 11 V ≤ V <sub>IN</sub> ≤ 40 V   |
| Overcurrent<br>detector              | Temperature coefficient of dead-band duty | D <sub>uT</sub>   | —                        | 1    | —                | %    | -20°C ≤ Ta ≤ +85°C              |
|                                      | Input bias current                        | I <sub>B1</sub>   | -2                       | —    | —                | μA   | Pin 15, 16                      |
|                                      | Common-mode input voltage range           | V <sub>CM1</sub>  | 0 to V <sub>IN</sub> - 3 | —    | —                | V    | Pin 15, 16                      |
| Comparator                           | Input bias current                        | I <sub>B2</sub>   | —                        | 5    | 13               | μA   | V <sub>CS</sub> = 5 V           |
|                                      | Input threshold voltage                   | V <sub>TH</sub>   | 1.2                      | 1.3  | 1.4              | V    |                                 |
|                                      | Input voltage range                       | V <sub>CS</sub>   | 0                        | —    | V <sub>ref</sub> | V    |                                 |
| Remote<br>controller                 | Input current to remote control pin       | I <sub>RM</sub>   | —                        | —    | 1.5              | mA   | V <sub>RM</sub> = 5 V           |
|                                      | Input high-voltage                        | V <sub>INH</sub>  | 1                        | —    | —                | V    |                                 |
|                                      | Input low-voltage                         | V <sub>INL</sub>  | —                        | —    | 0.4              | V    |                                 |
| Undervoltage<br>lockout<br>protector | High-level threshold voltage              | V <sub>THH</sub>  | 9                        | 10   | 11               | V    |                                 |
|                                      | Low-level threshold voltage               | V <sub>THL</sub>  | 7                        | 8    | 9                | V    |                                 |
|                                      | Hysteresis width                          | Hys               | 1.5                      | 2.0  | 2.8              | V    |                                 |
| Output driver                        | Output low-level                          | V <sub>L</sub>    | —                        | 0.7  | 1.4              | V    | I <sub>O (SINK)</sub> = 10 mA   |
|                                      | Output high-level                         | V <sub>H</sub>    | V <sub>IN</sub> - 2.2    | —    | —                | V    | I <sub>O (SOURCE)</sub> = 10 mA |
|                                      | Output rise time                          | t <sub>r</sub>    | —                        | 80   | 150              | ns   | Note 1                          |
|                                      | Output fall time                          | t <sub>f</sub>    | —                        | 40   | 100              | ns   | Note 1                          |
| Total current                        | Standby current                           | I <sub>CS</sub>   | —                        | 0.15 | 0.3              | mA   | Note 1                          |
|                                      | Operation current                         | I <sub>CL</sub>   | —                        | 8    | 12               | mA   | Note 1                          |

Note: 1. Measurement conditions of I<sub>CS</sub>, I<sub>CL</sub>, t<sub>r</sub>, t<sub>f</sub> are defined as following diagram.

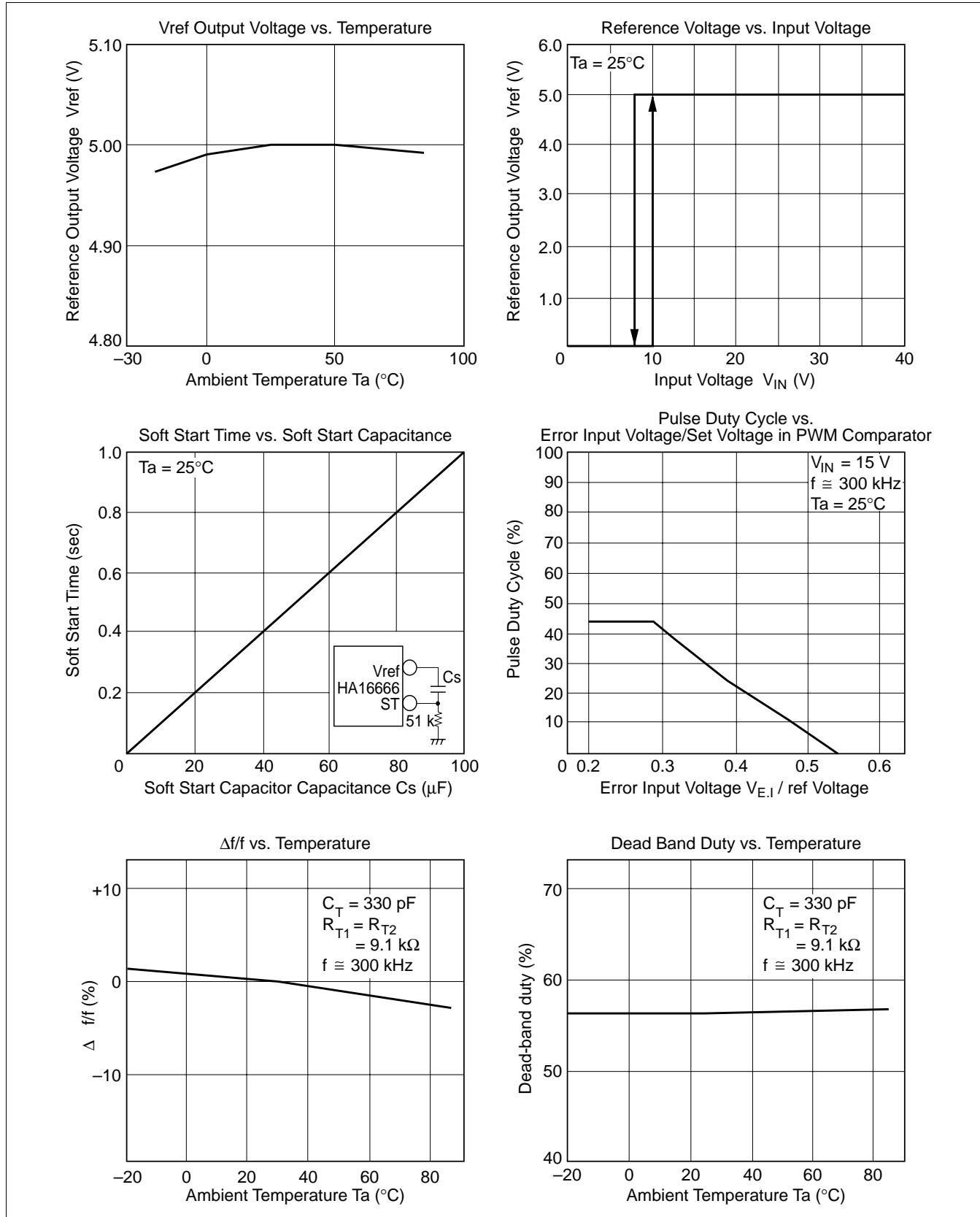


## Waveform Timing

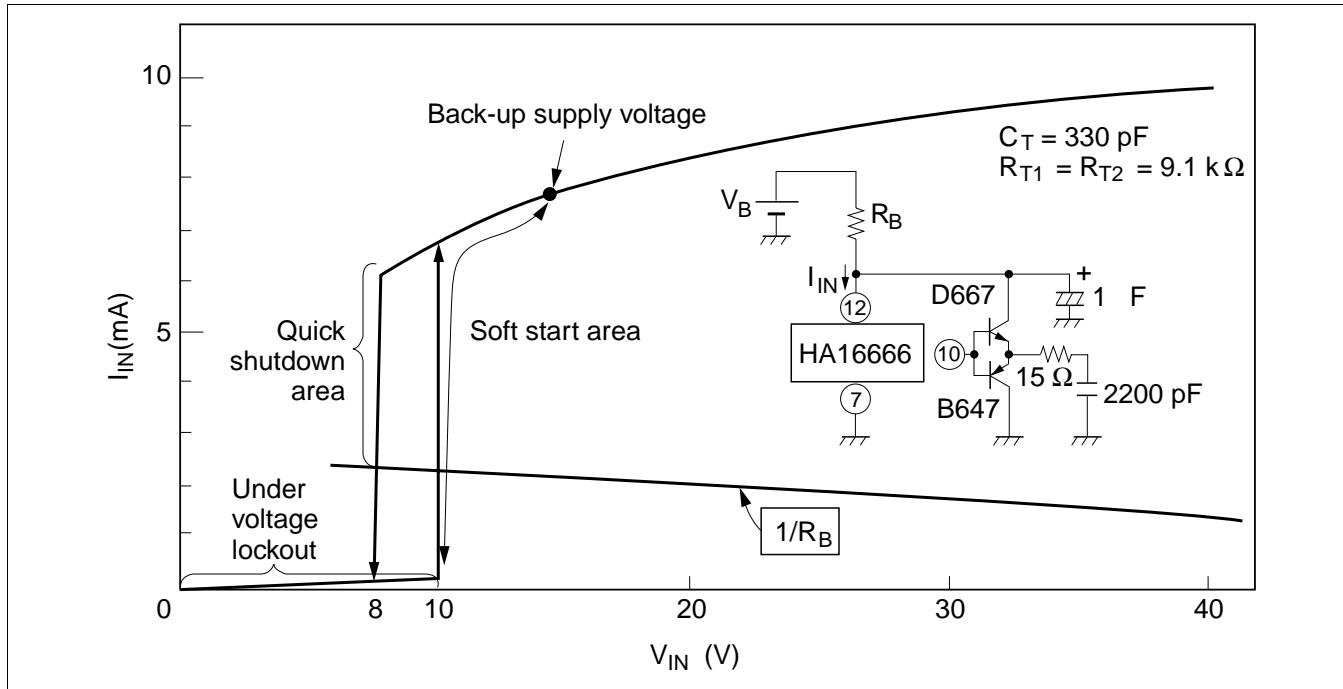


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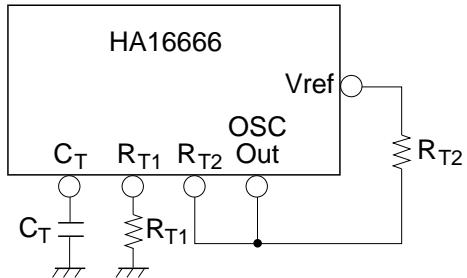
## Characteristic Curves



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**V<sub>IN</sub> Bias Point**

Formula for the oscillation frequency



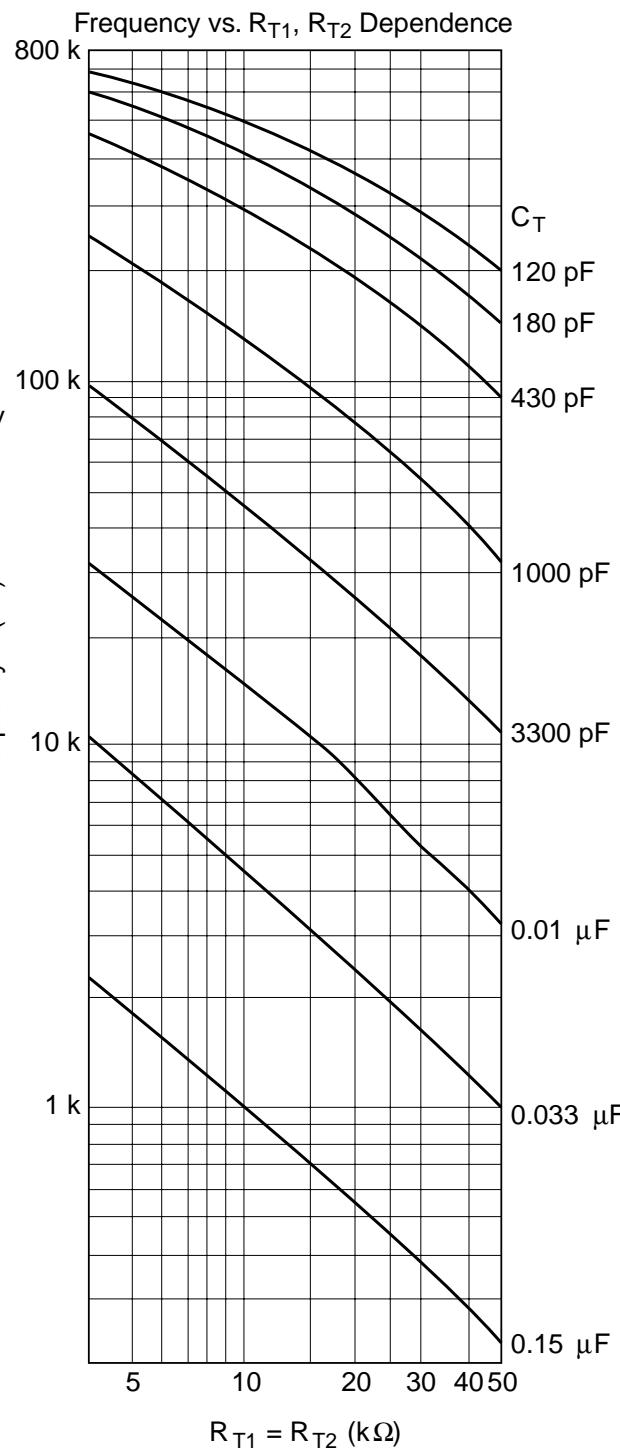
HA1666 summary formula of the oscillation frequency

$$\log(f) \approx a \times \log(R_{T1}) + b$$

↑  
 $(= R_{T2})$

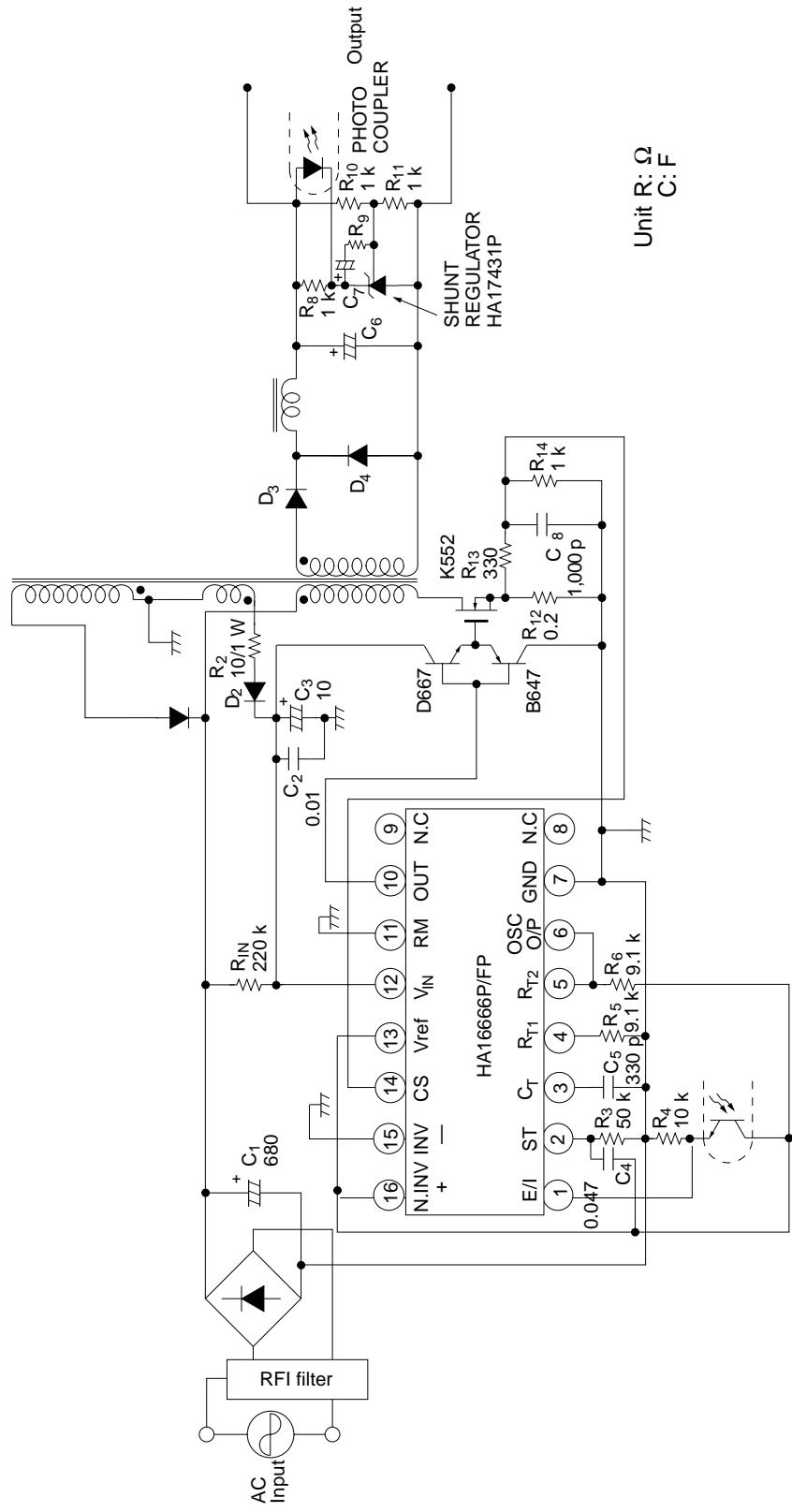
The following table show empirical values of  $a$  and  $b$  for different values of  $C_T$ .

| $C_T$  | $a$   | $b$  |
|--------|-------|------|
| 180pF  | -0.50 | 7.58 |
| 330pF  | -0.61 | 7.86 |
| 1000pF | -0.75 | 8.09 |
| 0.01μF | -0.86 | 7.57 |
| 0.15μF | -0.86 | 6.45 |

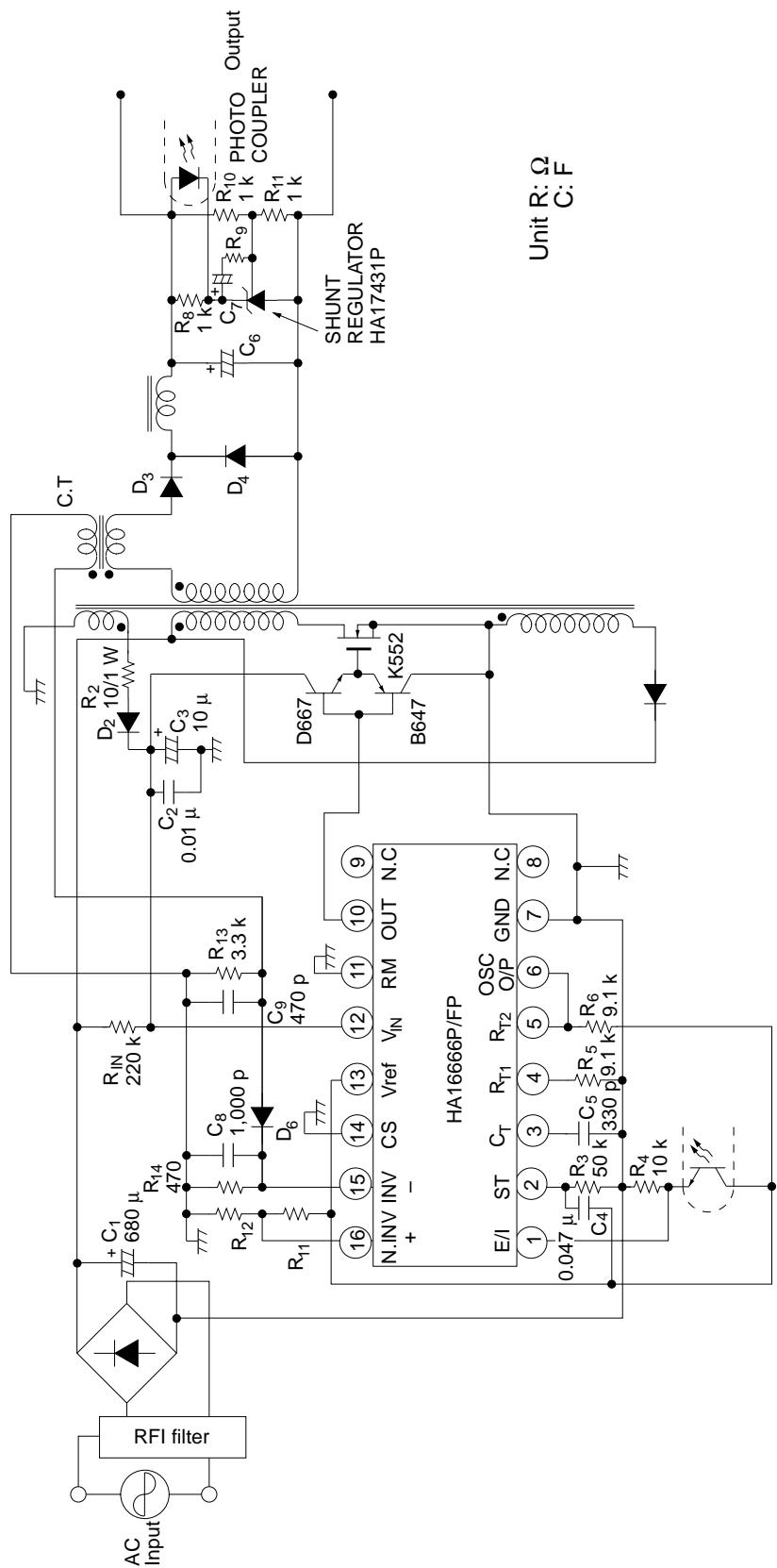


## System Connection Example

Over current protection; Resistance sensing method

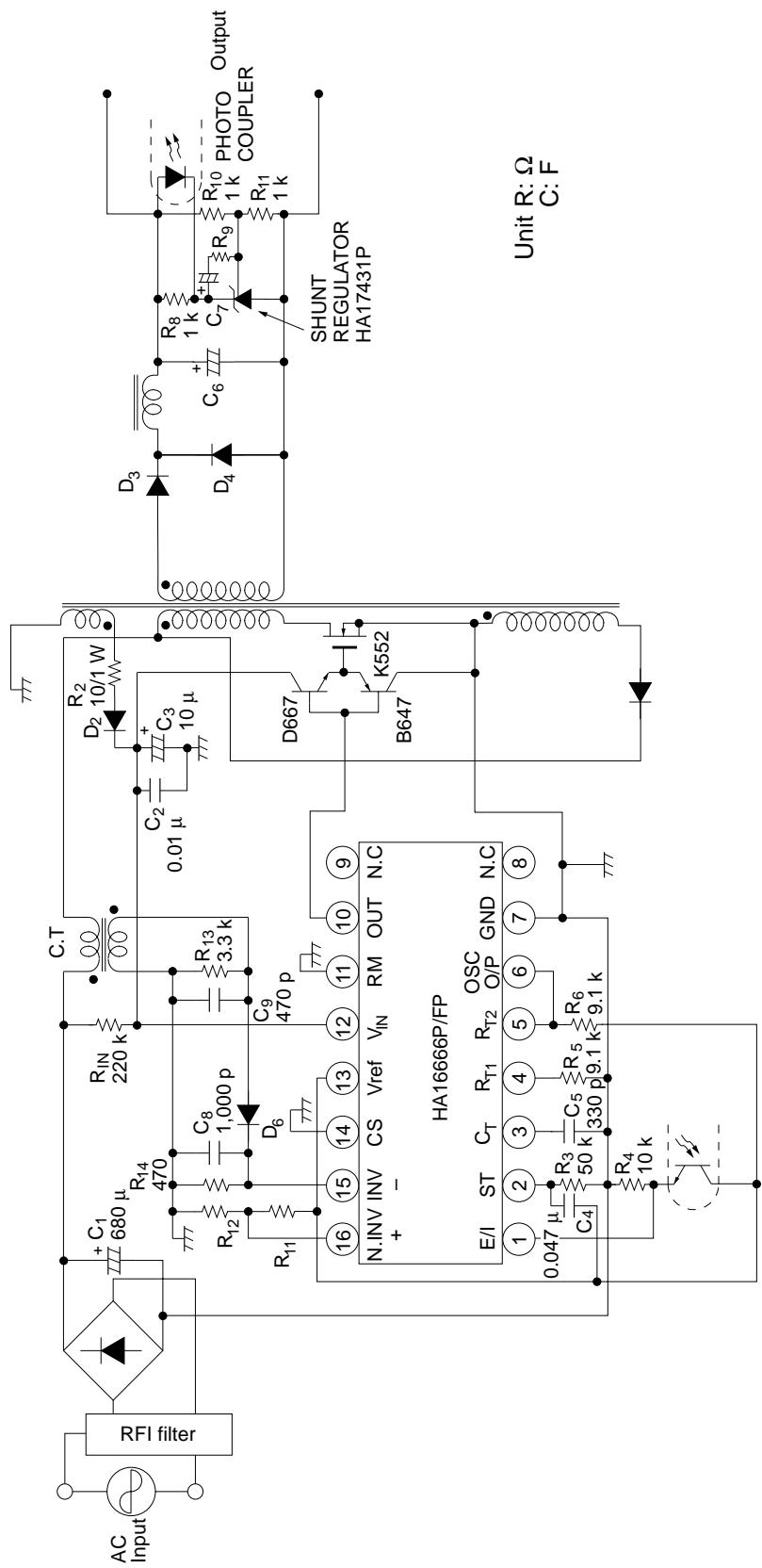
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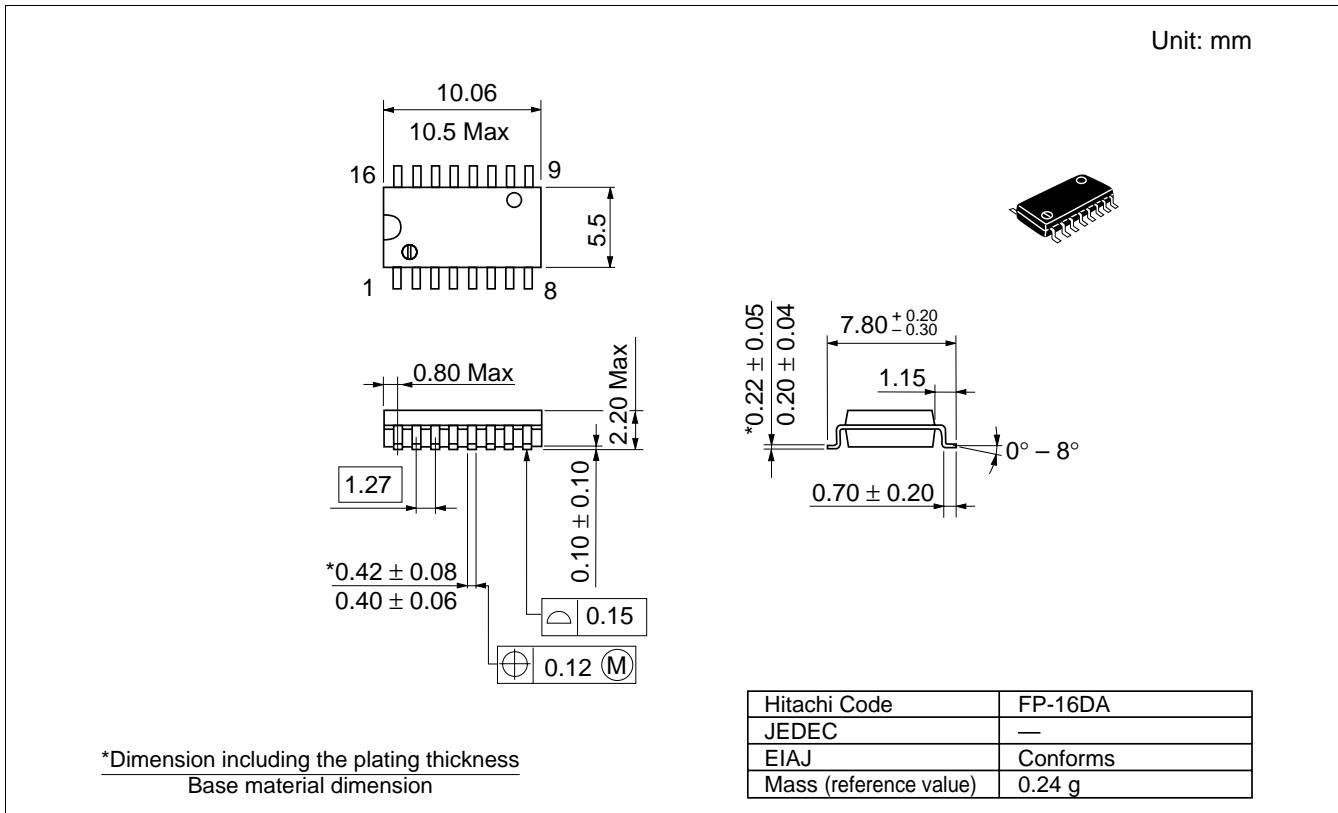
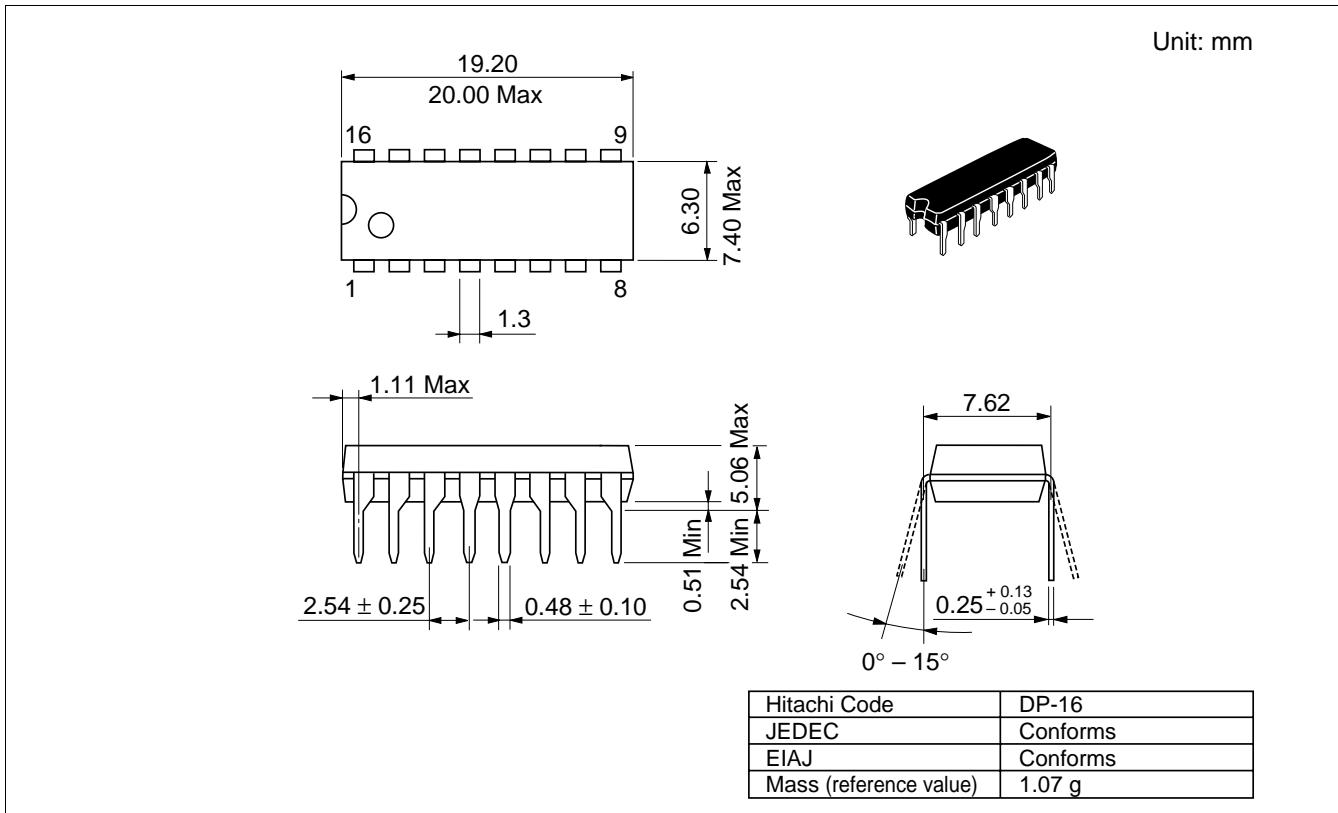
Over current protection; Current transformer method



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Over current protection; Current transformer method



**Package Dimensions****HITACHI**

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