

# MOS INTEGRATED CIRCUIT $\mu PD3768$

#### 7500 PIXELS × 3 COLOR CCD LINEAR IMAGE SENSOR

#### **DESCRIPTION**

The  $\mu$ PD3768 is a high-speed and high sensitive color CCD (Charge Coupled Device) linear image sensor which changes optical images to electrical signal and has the function of color separation.

The  $\mu$ PD3768 has 3 rows of 7500 pixels, and it is a 2-output/color type CCD sensor with 2 rows/color of charge transfer register, which transfers the photo signal electrons of 7500 pixels separately in odd and even pixels. Therefore, it is suitable for 600 dpi/A3 high-speed color digital copiers, color scanners and so on.

#### **FEATURES**

• Valid photocell : 7500 pixels  $\times$  3 • Photocell pitch : 9.325  $\mu$ m

• Line spacing : 37.3  $\mu$ m (4 lines) Red line - Green line, Green line - Blue line

• Color filter : Primary colors (red, green and blue), pigment filter (with light resistance 10<sup>7</sup> lx•hour)

• Resolution : 24 dot/mm A3 (297 × 420 mm) size (shorter side)

Drive clock level : CMOS output under 5 V operation
 Data rate : 44 MHz MAX. (22 MHz/1 output)

• Output type : 2 outputs in phase/color

• Power supply : +10 V

• On-chip circuits : Reset feed-through level clamp circuits

Voltage amplifiers

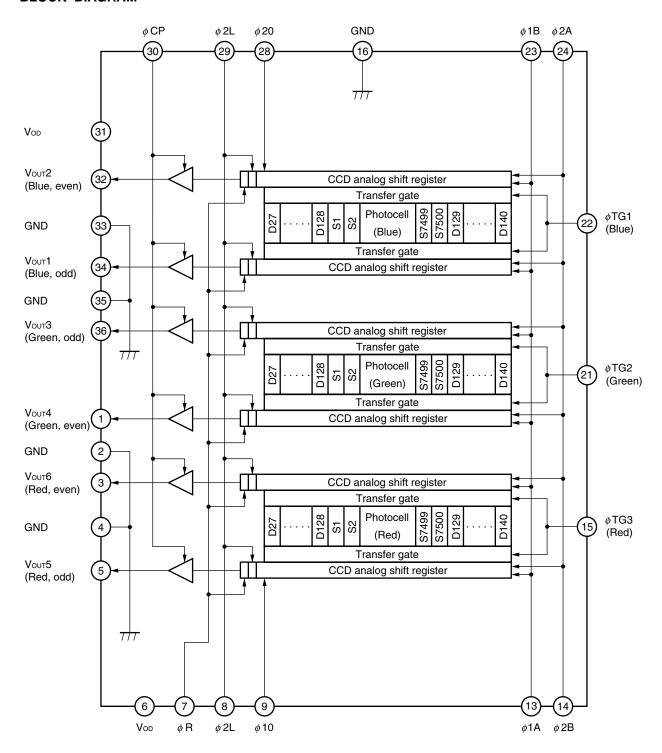
#### ORDERING INFORMATION

Part Number	Package
μPD3768D	CCD linear image sensor 36-pin ceramic DIP (CERDIP) (15.24 mm (600))

The information in this document is subject to change without notice. Before using this document, please confirm that this is the latest version. Not all devices/types available in every country. Please check with local NEC representative for availability and additional information.



#### **BLOCK DIAGRAM**

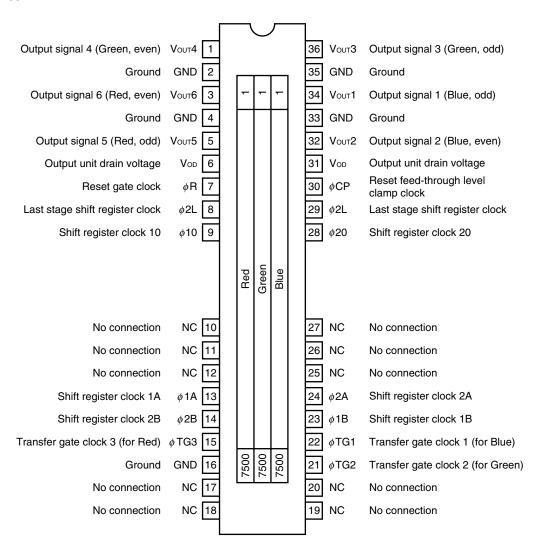




#### **★ PIN CONFIGURATION (Top View)**

#### CCD linear image sensor 36-pin ceramic DIP (CERDIP) (15.24 mm (600))

• μPD3768D

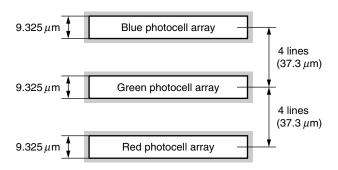


Caution Connect the No connection pins (NC) to GND.

#### PHOTOCELL STRUCTURE DIAGRAM

# 6.325 µm E GS SS GS GS Channel stopper Shield

# PHOTOCELL ARRAY STRUCTURE DIAGRAM (Line spacing)





#### ABSOLUTE MAXIMUM RATINGS ( $T_A = +25^{\circ}C$ )

Parameter	Symbol	Ratings	Unit
Output drain voltage	Vod	−0.3 to +12	V
Shift register clock voltage	V <sub>\phi</sub> 1, V <sub>\phi</sub> 2	-0.3 to +8	V
Last gate shift register clock voltage	V <sub>Ø</sub> 2L	-0.3 to +8	V
Reset gate clock voltage	V <sub>Ø</sub> R	-0.3 to +8	V
Clamp clock voltage	V <sub>Ø</sub> CP	-0.3 to +8	V
Transfer gate clock voltage	V <sub>φ</sub> TG1 to V <sub>φ</sub> TG3	-0.3 to +8	V
Operating ambient temperature Note	Та	−25 to +60	°C
Storage temperature	T <sub>stg</sub>	-40 to +100	°C

<sup>★</sup> Note Use at the condition without dew condensation.

Caution Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

#### RECOMMENDED OPERATING CONDITIONS ( $T_A = +25$ °C)

Parameter	Symbol	Min.	Тур.	Max.	Unit
Output drain voltage	Vod	9.5	10.0	10.5	V
Shift register clock high level	V <sub>φ</sub> 1H, V <sub>φ</sub> 2H	4.5	5.0	5.5	V
Shift register clock low level	Vφ1L, Vφ2L	-0.3	0	+0.5	V
Last gate shift register clock high level	V <sub>\$\phi\$</sub> 2LH	4.5	5.0	5.5	V
Last gate shift register clock low level	V <sub>\$\phi\$</sub> 2LL	-0.3	0	+0.5	V
Reset gate clock high level	V <sub>Ø</sub> RH	4.5	5.0	5.5	V
Reset gate clock low level	V <sub>Ø</sub> RL	-0.3	0	+0.5	V
Clamp clock high level	$V_{\phi}$ CPH	4.5	5.0	5.5	V
Clamp clock low level	V <sub><math>\phi</math></sub> CPL	-0.3	0	+0.5	V
Transfer gate clock high level	$V_{\phi}$ тg1н to $V_{\phi}$ тg3н	4.5	V <sub>φ1H</sub> Note	V <sub>φ1H</sub> Note	V
Transfer gate clock low level	V <sub>φ</sub> TG1L to V <sub>φ</sub> TG3L	-0.3	0	+0.5	V
Data rate	2føR	1	2	44	MHz

Note When Transfer gate clock high level ( $V_{\phi TG1H}$  to  $V_{\phi TG3H}$ ) is higher than Shift register clock high level ( $V_{\phi 1H}$ ), Image lag can increase.



#### **ELECTRICAL CHARACTERISTICS**

 $T_A = +25$ °C,  $V_{OD} = 10$  V,  $f_{\phi R} = 1$  MHz, data rate = 2 MHz, storage time = 10 ms, input signal clock = 5  $V_{p-p}$ , light source (except Response1) : 2950 K halogen lamp + CM-500S (infrared cut filter, t = 1 mm)

Parameter		Symbol	Test Conditions	Min.	Тур.	Max.	Unit
Saturation voltage		Vsat		1.5	2.0	-	V
Saturation exposure	Saturation exposure Red		2950 K halogen lamp + CM-500S	-	0.14	-	lx•s
	Green	SEG		_	0.13	-	lx•s
	Blue	SEB		_	0.26	-	lx•s
Photo response non-unifor	rmity	PRNU	Vουτ = 1.0 V	-	6.0	18.0	%
Photo response non-unifor at low illumination	rmity	PRNU2	Vоит = 0.1 V	_	6.0	18.0	%
Average dark signal		ADS	Light shielding, data rate = 2 MHz, storage time = 10 ms	_	1.0	5.0	mV
Dark signal non-uniformity		DSNU	Light shielding, data rate = 2 MHz, storage time = 10 ms	_	3.0	12.0	mV
Power consumption		Pw		-	700	900	mW
Output impedance		Zo		-	0.2	0.4	kΩ
Response1	Red	RR	3200 K halogen lamp + C-500S	15.4	22.0	28.6	V/lx•s
	Green	Rg	+ HA-50	12.6	18.0	23.4	V/lx•s
•	Blue	Rв		5.6	8.0	10.4	V/lx•s
Response2	Red	RR	2950 K halogen lamp + CM-500S	9.8	14.0	18.2	V/lx•s
	Green	Rg		10.7	15.3	19.9	V/lx•s
	Blue	Rв		5.3	7.6	9.9	V/lx•s
Image lag		IL	Vоит = 500 mV	-	40	80	mV
Image lag color difference		IL-DIF	Vоит = 500 mV	-	5	20	mV
Image lag O/E		IL-O/E	Vоит = 500 mV	-	10	30	mV
Offset level Note 1		Vos		3.8	4.5	5.2	V
Output fall delay time Note 2		<b>t</b> d		-	14	-	ns
Register imbalance		RI	Vоит = 1.0 V	-	0	5	%
Total transfer efficiency		TTE	Vουτ = 1.0 V, fφR = 22 MHz	94	98	-	%
Response peak	Red			-	630	-	nm
	Green			_	540	_	nm
Blue				-	445	_	nm
Dynamic range		DR1	V <sub>sat</sub> /DSNU	-	666	_	times
		DR2	V <sub>sat</sub> / $\sigma$ dark	_	870		times
Reset feed-through noise		RFTN	Light shielding	-1000	-200	+500	mV
Light shielding random no	se	$\sigma$ dark	Bit clamp, t17 = 10 ns		2.3		mV

Notes 1. Refer to TIMING CHART 2 and TIMING CHART 4.

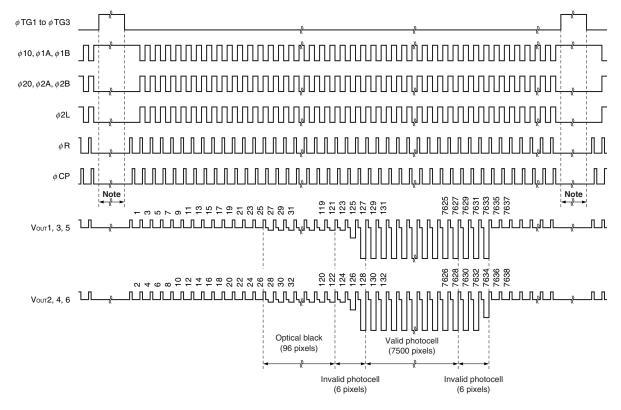
2.  $t_d$  is defined as periods from 10% of  $\phi$ 2L to 10% of Vout1 to Vout6 (refer to **APPLICATION CURCUIT EXAMPLE**).



#### INPUT PIN CAPACITANCE (TA = +25°C, Vod = 10 V)

Parameter	Symbol	Pin	Pin No.	Min.	Тур.	Max.	Unit
Shift register clock pin capacitance	C <sub>0</sub> 1	φ 10	9	-	330	450	pF
		φ1A	13	-	330	450	pF
		φ1B	23	-	330	450	pF
	C <sub>\$\phi\$2</sub>	φ2B	14	-	330	450	pF
		φ2A	24	-	330	450	pF
		φ 20	28	-	330	450	pF
Last stage shift register clock pin capacitance	C <sub>∅</sub> L	φ 2L	8	-	10	20	pF
			29	-	10	20	pF
Reset gate clock pin capacitance	CøR	φR	7	-	10	20	pF
Clamp clock pin capacitance	C <sub>Ø</sub> CP	φCP	30	-	10	20	pF
Transfer gate clock pin capacitance	СøтG	φTG1	22	-	100	150	pF
		φTG2	21	_	100	150	pF
		φTG3	15	_	100	150	pF

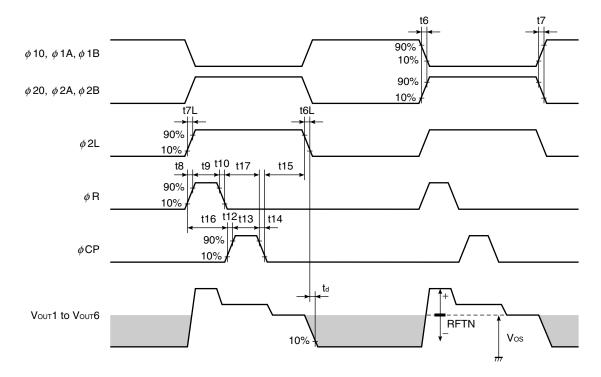
#### ★ TIMING CHART 1 (Bit clamp mode, for each color)



**Note** Set the  $\phi$ R and  $\phi$ CP pulse to low level during this period.

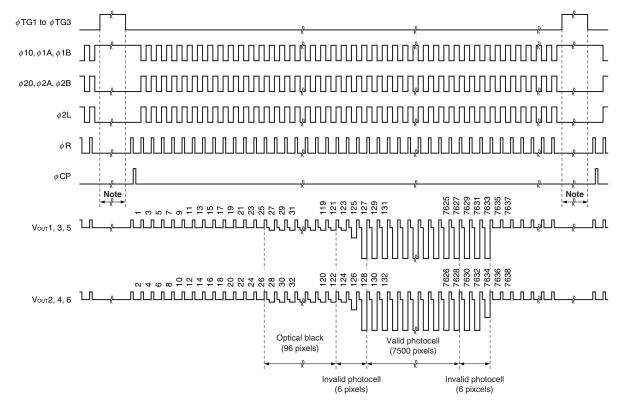


#### TIMING CHART 2 (Bit clamp mode, for each color)



Symbol	Min.	Тур.	Max.	Unit
t6, t7	0	50	-	ns
t6L, t7L	0	5	-	ns
t8, t10	0	5	-	ns
t9	10	125	-	ns
t12, t14	0	5	-	ns
t13	10	125	-	ns
t15	0	250	-	ns
t16	8	125	-	ns
t17	8	125	_	ns

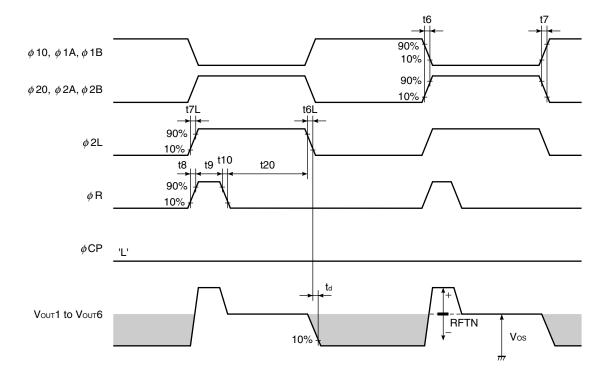
#### ★ TIMING CHART 3 (Line clamp mode, for each color)



**Note** Set the  $\phi$ R and  $\phi$ CP pulse to low level during this period.



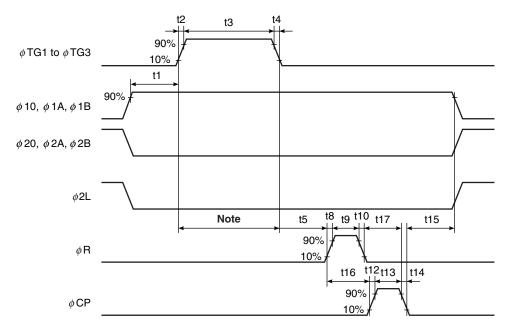
#### ★ TIMING CHART 4 (Line clamp mode, for each color)



Symbol	Min.	Тур.	Max.	Unit
t6, t7	0	50	ı	ns
t6L, t7L	0	5	-	ns
t8, t10	0	5	-	ns
t9	10	125	-	ns
t20	5	250	_	ns



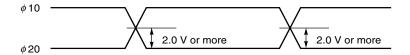
#### TIMING CHART 5 (Bit clamp mode, line clamp mode, for each color)



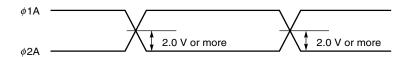
Symbol	Min.	Тур.	Max.	Unit
t1, t5	200	300	=	ns
t2, t4	0	50	-	ns
t3	3000	5000	-	ns
t8, t10	0	5	-	ns
t9	10	125	-	ns
t12, t14	0	5	-	ns
t13	10	125	-	ns
t15	0	250	=	ns
t16	8	125	=	ns
t17	8	125	_	ns

**Note** Set the  $\phi$ R and  $\phi$ CP pulse to low level during this period.

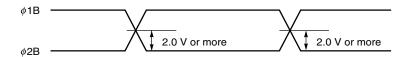
#### $\phi$ 10, $\phi$ 20 cross points



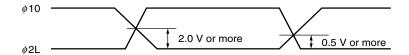
#### $\phi$ 1A, $\phi$ 2A cross points



#### $\phi$ 1B, $\phi$ 2B cross points



#### $\phi$ 10, $\phi$ 2L cross points



**Remark** Adjust cross points ( $\phi$ 10,  $\phi$ 20), ( $\phi$ 1A,  $\phi$ 2A), ( $\phi$ 1B,  $\phi$ 2B) and ( $\phi$ 10,  $\phi$ 2L) with input resistance of each pin.



#### **DEFINITIONS OF CHARACTERISTIC ITEMS**

1. Saturation voltage: Vsat

Output signal voltage at which the response linearity is lost.

2. Saturation exposure : SE

Product of intensity of illumination (lx) and storage time (s) when saturation of output voltage occurs.

3. Photo response non-uniformity: PRNU

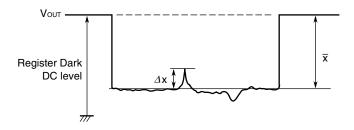
The output signal non-uniformity of all the valid pixels when the photosensitive surface is applied with the light of uniform illumination. This is calculated by the following formula, and it is defined by each six of them.

PRNU (%) = 
$$\frac{\Delta x}{\overline{x}} \times 100$$

 $\Delta x$ : maximum of  $|x_j - \overline{x}|$ 

$$\overline{x} = \frac{\sum_{j=1}^{7500} x_j}{7500}$$

x<sub>j</sub>: Output voltage of valid pixel number j



4. Average dark signal: ADS

Average output signal voltage of all the valid pixels at light shielding. This is calculated by the following formula, and it is defined by each six of them.

ADS (mV) = 
$$\frac{\sum_{j=1}^{7500} d_j}{7500}$$

dj: Dark signal of valid pixel number j

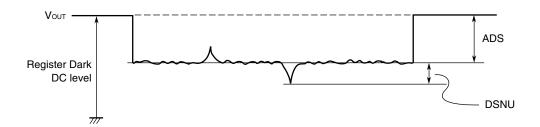


#### 5. Dark signal non-uniformity: DSNU

Absolute maximum of the difference between ADS and voltage of the highest or lowest output pixel of all the valid pixels at light shielding. This is calculated by the following formula, and it is defined by each six of them.

DSNU (mV): maximum of 
$$|d_j - ADS|_{j=1 \text{ to } 7500}$$

dj: Dark signal of valid pixel number j



#### 6. Output impedance: Zo

Impedance of the output pins viewed from outside.

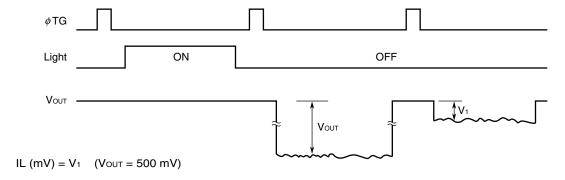
#### 7. Response: R

Output voltage divided by exposure (lx•s).

Note that the response varies with a light source (spectral characteristic).

#### 8. Image lag: IL

The rate between the last output voltage and the next one after read out the data of a line.



#### 9. Image lag color difference : IL-DIF

It is defined as a difference between colors of the average of image lag.

It is expressed with the next expression to be concrete.

| (average of image lag of blue output) - (average of image lag of green output) |

| (average of image lag of green output) - (average of image lag of red output) |

| (average of image lag of red output) - (average of image lag of blue output) |

**NEC** 

10. Image lag O/E: IL-O/E

It is defined as a difference of the average of image lag of odd and even pixels for each color.

11. Register imbalance: RI

The rate of the difference between the averages of the output voltage of Odd and Even pixels, against the average output voltage of all the valid pixels.

RI (%) = 
$$\frac{\frac{2}{n} \left| \sum_{j=1}^{\frac{n}{2}} (V_{2j-1} - V_{2j}) \right|}{\frac{1}{n} \sum_{j=1}^{n} V_{j}} \times 100$$

n : Number of valid pixels

 $V_{j}\,:\,$  Output voltage of each pixel

★ 12. Total transfer efficiency : TTE

The total transfer rate of CCD analog shift register. This is calculated by the following formula, it is difined by each output.

TTE (%) =  $(1 - V_b / average output of all the valid pixels) \times 100$ 



V<sub>b</sub> V<sub>a-1</sub>: The last pixel output – 1 (Odd pixel: 7631th pixel)

 $V_{\text{a}}$ : The last pixel output (Odd pixel: 7633th pixel)

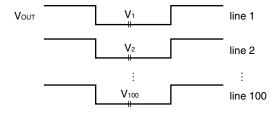
 $V_b$ : The spilt pixel output (Odd pixel: 7635th pixel)

13. Light shielding random noise : σdark

Light shielding random noise  $\sigma$ dark is defined as the standard deviation of a valid pixel output signal with 100 times (=100 lines) data sampling at dark (light shielding).

$$\sigma \, dark \, (mV) = \sqrt{\frac{\displaystyle \sum_{i=1}^{100} \, (V_i - \overline{V})^2}{100}} \quad , \ \overline{V} = \frac{1}{100} \sum_{i=1}^{100} V_i$$

Vi: A valid pixel output signal among all of the valid pixels for each color

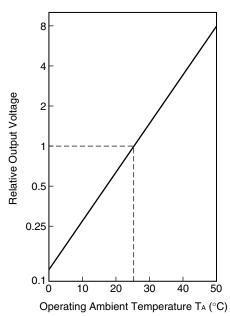


This is measured by the DC level sampling of only the signal level, not by CDS (Correlated Double Sampling).

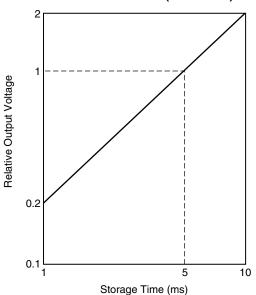


#### STANDARD CHARACTERISTIC CURVES (Reference Value)

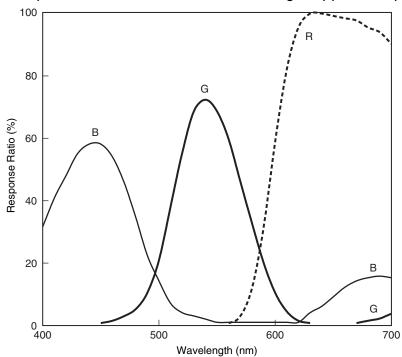
# DARK OUTPUT TEMPERATURE CHARACTERISTIC



# STORAGE TIME OUTPUT VOLTAGE CHARACTERISTIC (T<sub>A</sub> = +25°C)

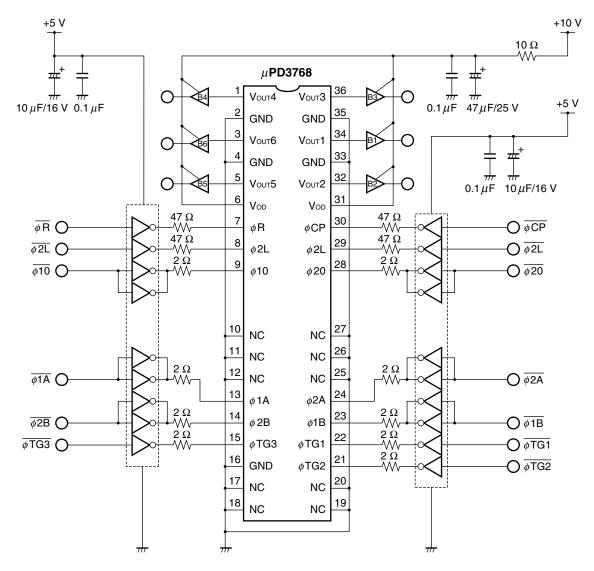


# TOTAL SPECTRAL RESPONSE CHARACTERISTICS (without infrared cut filter and heat absorbing filter) (T<sub>A</sub> = +25°C)





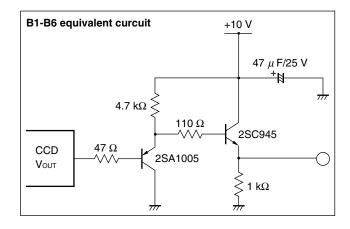
#### **APPLICATION CIRCUIT EXAMPLE**



Caution Connect the No connection pins (NC) to GND.

**Remarks 1.** Connect two inverters (74AC04) to each  $\phi$  10,  $\phi$  1A,  $\phi$  1B,  $\phi$  20,  $\phi$  2A,  $\phi$  2B pin.

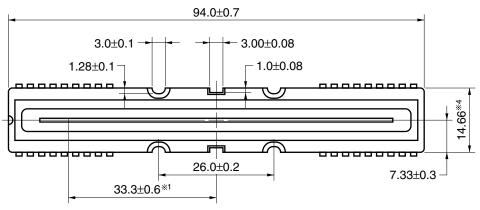
- 2. Inverters shown in the above application circuit example are the 74AC04.
- 3. B1 to B6 in the application circuit example are shown in the figure below.

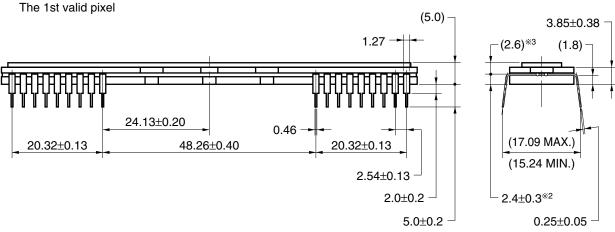




#### **PACKAGE DRAWING**

#### CCD LINEAR IMAGE SENSOR 36-PIN CERAMIC DIP (15.24 mm (600))





Name	Dimension	Refractive index
Glass cap	91.0×9.0×1.1	1.5

- ★2 The bottom of package 
   The surface of the chip
- ★3 The surface of the chip 

  The surface of the glass cap
- # 4 The tolerance of packge dimension  $\pm 0.25$ : less than 10 mm from W/F edge  $\pm 0.50$ : equal or more than 10 mm from W/F edge

36D-1CCD-PKG3-1



#### RECOMMENDED SOLDERING CONDITIONS

When soldering this product, it is highly recommended to observe the conditions as shown below.

If other soldering processes are used, or if the soldering is performed under different conditions, please make sure to consult with our sales offices.

#### Type of Through-hole Device

#### μPD3768D: CCD linear image sensor 36-pin ceramic DIP (CERDIP) (15.24 mm (600))

Process	Conditions
Partial heating method	Pin temperature: 300 °C or below, Heat time: 3 seconds or less (per pin)

- ★ Cautions 1. During assembly care should be taken to prevent solder or flux from contacting the glass cap.

  The optical characteristics could be degraded by such contact.
  - 2. Soldering by the solder flow method may have deleterious effects on prevention of glass cap soiling and heat resistance. So the method cannot be guaranteed.



#### NOTES ON HANDLING THE PACKAGES

#### 1) MOUNTING OF THE PACKAGE

The application of an excessive load to the package may cause the package to warp or break, or cause chips to come off internally. Particular care should be taken when mounting the package on the circuit board. Don't have any object come in contact with glass cap. You should not reform the lead frame. We recommended to use a IC-inserter when you assemble to PCB.

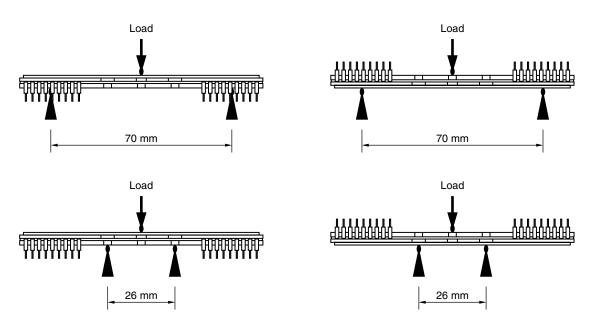
Also, be care that the any of the following can cause the package to crack or dust to be generated.

- 1. Applying heat to the external leads for an extended period of time with soldering iron.
- 2. Applying repetitive bending stress to the external leads.
- 3. Rapid cooling or heating

For this product, the reference value for the three-point bending strength <sup>Note</sup> is 180 [N] (at distance between supports: 70 mm), is 500 [N] (at distance between supports: 26 mm). Avoid imposing a load, however, on the inside portion as viewed from the face on which the window (glass) is bonded to the package body (ceramic).

Note Three-point bending strength test

Distance between supports: 70 mm or 26 mm, Support R: R 2 mm, Loading rate: 0.5 mm/min.



#### ② GLASS CAP

Don't either touch glass cap surface by hand or have any object come in contact with glass cap surface. Care should be taken to avoid mechanical or thermal shock because the glass cap is easily to damage. For dirt stuck through electricity ionized air is recommended.



#### NOTES ON HANDLING THE PACKAGES

#### **③ OPERATE AND STORAGE ENVIRONMENTS**

Operate in clean environments. CCD image sensors are precise optical equipment that should not be subject to mechanical shocks. Exposure to high temperatures or humidity will affect the characteristics. So avoid storage or usage in such conditions.

Keep in a case to protect from dust and dirt. Dew condensation may occur on CCD image sensors when the devices are transported from a low-temperature environment to a high-temperature environment. Avoid such rapid temperature changes.

For more details, refer to our document "Review of Quality and Reliability Handbook" (C12769E)

#### **4** ELECTROSTATIC BREAKDOWN

CCD image sensor is protected against static electricity, but destruction due to static electricity is sometimes detected. Before handling be sure to take the following protective measures.

- 1. Ground the tools such as soldering iron, radio cutting pliers of or pincer.
- 2. Install a conductive mat or on the floor or working table to prevent the generation of static electricity.
- 3. Either handle bare handed or use non-chargeable gloves, clothes or material.
- 4. Ionized air is recommended for discharge when handling CCD image sensor.
- 5. For the shipment of mounted substrates, use box treated for prevention of static charges.
- 6. Anyone who is handling CCD image sensors, mounting them on PCBs or testing or inspecting PCBs on which CCD image sensors have been mounted must wear anti-static bands such as wrist straps and ankle straps which are grounded via a series resistance connection of about 1  $M\Omega$ .

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[MEMO]



#### NOTES FOR CMOS DEVICES -

#### 1) PRECAUTION AGAINST ESD FOR SEMICONDUCTORS

Note:

Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.

#### ② HANDLING OF UNUSED INPUT PINS FOR CMOS

Note:

No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.

#### (3) STATUS BEFORE INITIALIZATION OF MOS DEVICES

Note:

Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee out-pin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function.

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