

SANYO Semiconductors **DATA SHEET**

LB11885 — Monolithic Digital IC Three-in-One Motor Driver for Portable VCR

Overview

LB11885 is a three-in-one motor driver for portable VCR.

Features

• Capstan motor drive unit

3-phase, 120 degrees full conducting, direct PWM drive

Built in PWM oscillator

Current limiter (It is fixed internally and setup externally.)

Forward/reverse rotation

2 levels FG amplifier (Built-in gain resistor)

Control amplifier output pin

• Drum motor drive unit

3-phase, 120 degrees full conducting soft switching sensorless drive

FG sensorless function

2 levels PG amplifier

FG and PG mixing output (Separated output is also possible.)

• Loading motor drive unit

H-bridge forward/reverse rotation

Motor voltage switch

Short brake

Input control for 3 values

• Common unit

Over-heat protection function (Thermal Shut Down)

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Maximum Ratings at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
IC power source voltage	VREG max		6.5	V
Motor power source 1	C_V _{CC} max		30.0	V
Motor power source 2	D_V _{CC} max		30.0	V
Motor power source 3	L_V _{CC} max		30.0	V
Applied input voltage	VI1 max		-0.3 to V _{CC} +0.3	V
Motor output current	IC_V _{CC} max		1.2	А
Motor output current	ID_V _{CC} max		0.75	А
Motor output current	IL_V _{CC} max		0.8	А
Allowable internal power dissipation	Pd max1	IC alone	0.85	W
	Pd max2			W
Pin voltage range 1	VPIN max1	CRSS, CRSP, CUOUT, CVOUT, CWOUT	CMGND-VF to CV _{CC} +VF	V
Pin voltage range 2	VPIN max2	DRS, DCOM, DUOUT, DVOUT, DWOUT	DMGND-VF to DV _{CC} +VF	V
Pin voltage range 3	VPIN max3	LOUT1, LOUT2	LGND-VF to LV _{CC} +VF	V
Operating temperature	Topr		-20 to +75	°C
Storage temperature	Tstg		-55 to +150	°C

Allowable Operating Range at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Power source voltage 1	VREG		4 to 6	٧
Power source voltage 2	C_VCC		8 to 28	V
Power source voltage 3	D_V _{CC}		8 to 28	V
Power source voltage 4	L_V _{CC}		8 to 28	V
Electric potential difference between MGND and SGND	ΔGND	(MGND)-(SGND)	-0.3 to +0.4	٧

Electrical Characteristics

-	0 11								
Parameter	Symbol Conditions		min	typ	max	Unit			
Common Unit at Ta = 25°C, VREG = 5V	Common Unit at Ta = 25°C, VREG = 5V, C_V _{CC} = D_V _{CC} = L_V _{CC} = 12V								
Power source current 1	IVREG			17	25	mA			
Power source current 2	IC_VCC			0.3	2	mA			
Power source current 3	ID_V _{CC}			0.6	1	mA			
Power source current 4	IL_V _{CC}			2	3	mA			
Power source current 5	IV _{CC} Q	VREG = 0V, IC_V _{CC} +ID_V _{CC} +IL_V _{CC}			100	μΑ			
Thermal shutdown temperature	TSD	*Design Target Value	140	160	180	°C			
Thermal shutdown hysteresis	ΔTSD	*Design Target Value		15		°C			
Capstan Motor Unit at Ta = 25°C, VREG	G = 5V, C_V _{CC}	= 12V							
Output saturation voltage 1	VOSAT	I _O = 1.0A, Source+Sink		2.6	4.0	V			
Hall signal input level	VHALL		60			mVp-p			
Hall in-phase input voltage	VCM		1.0		V _{CC} -	V			
C_ILM pin input voltage range	VCLIM		0		VREG	V			
C_ILM pin input current	ICLIM	C_LIM = 3V			2.0	μΑ			
C_LIM control start voltage	VCLIMST	$C_RF = 0.5\Omega$	2.4	2.5	2.6	V			
C_LIM gain	GCLIM	$C_{CNT} = 5V$, $C_{RF} = 0.5\Omega$	0.49	0.53	0.57	V/V			
C_LIM pin short brake release voltage	BROFF1		1.1		1.4	V			
C_CNT input voltage range	VCCNT		0		VREG	V			

^{*} Note: Thermal design must be set for a junction temperature of 140°C.

^{*} It is a design target value and measurement is not carried out.

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Parameter	Symbol	Conditions		Ratings			
- Gramotol	Cymbol	Conditions	min	min typ		Unit	
C_CNT input current	ICCTL	C_CNT = 3V			2.0	μΑ	
C_CNT control start voltage	VCCNTST	$C_RF = 0.5\Omega$	2.4	2.5	2.6	V	
C_CNT gain	GCCNT	$C_RF = 0.5\Omega$	0.49	0.53	0.57	V/V	
C_CNT pin short brake release voltage	BROFF2		1.1		1.4	V	
F/R forward voltage	VFW		1.5		VREG	V	
F/R reverse voltage	VRW		0		1	V	
F/R input current	IFR	C_FR = 3V		100	200	μΑ	
FG amplifier reference voltage	VFGR		2.40	2.50	2.60	V	
Linear amplifier gain DC	GDC		47	50	53	fold	
Hysteresis amplifier output voltage	VHO	I _{HO} = 4mA		0.2	0.4	V	
Hysteresis of hysteresis amplifier	VHS	Both hysteresis	60	75	90	mV	
Hysteresis amplifier output duty ratio	FGDT	360Hz Fgin = 40mVp-p	49	50	51	%	
PWM carrier frequency	FOSC	C_PWM = 680pF	18.5	21.7	25.0	kHz	
Internal current limiter setup voltage	CLIM	RF = 100Ω	0.60	0.675	0.75	V	
Drum Motor Unit at Ta = 25°C, VREG =	5V, DV _{CC} = 12	V					
Output saturation voltage 2	DVSAT2	0.6A, Source+Sink		1.8	2.6	V	
D_CNT input voltage range	VD_CNT		0		VREG	V	
D_CNT input current	IC_CNT	D_CNT = 3V			0.5	μΑ	
D_CNT control start voltage	D_CNTST		2.40	2.50	2.60	V	
D_CNT gain	GD_CNT		0.40	0.50	0.60	V/V	
PCOUT output current 1	IPCOU	Source side	20	45		μΑ	
PCOUT output current 2	IPCOD	Sink side	20	45		μΑ	
VCOIN input current	IVCOIN	VCOIN = 3V, sink current			1	μΑ	
Minimum VCO frequency	FVCO min	$CX = 0.022\mu F$, VCOINN = Open	330	410	500	Hz	
Maximum VCO frequency	FVCO max	$CX = 0.022 \mu F, VCOIN = 5V$	18.3	22.8	27.4	kHz	
C1/C2 source current ratio	RSOURCE	1-(IC1SOURCE/IC2SOURCE)	-12	0	12	%	
C1/C2 sink current ratio	RSINK	1-(IC1SINK/IC2SINK)	-12	0	12	%	
C1 source/sink current ratio	RC1	IC1SOURCE/IC1SINK	40	50	60	%	
C2 source/sink current ratio	RC2	IC2SOURCE/IC2SINK	40	50	60	%	
FGO output high level voltage	VFGH		4.7			V	
FGO output low level voltage	VFGL				0.4	V	
PG amplifier reference voltage	VPGREF		2.8	3.0	3.2	V	
PG amplifier input offset	OPG		-5		+5	mV	
PG amplifier input bias	IPG	PG- = 2.5V, source current			0.25	μΑ	
Linear amplifier gain	GAMP	Freq = 1kHz	50			dB	
Hysteresis amplifier threshold level 1	VHYS1		70	100	130	mV	
Hysteresis amplifier threshold level 2	VHYS2		140	200	260	mV	
PG output high level voltage	VPH		4.7			V	
PG output low level voltage	VPL				0.2	V	
FG/PG mix MID voltage	Vmid		2.4	2.5	2.6	V	
Internal current limiter setup voltage	DLIM	RF = 100Ω	0.30	0.33	0.36	V	
Loading Unit at Ta = 25°C, VREG = 5V,	LV _{CC} = 12V						
Input voltage	1 (HIGH)	V _{IN} H		4		5	
	2 (Middle)	V _{IN} M		2		3	
	3 (LOW)	VINL		0		1	

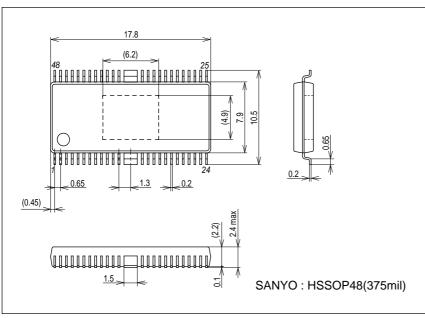
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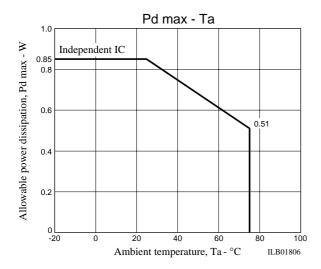
Dorometer	Cyma	hal	Conditions		1.1-24			
Parameter	Sym	DOI	Conditions	min	typ	max	Unit	
Input current	IL _{IN} 0		L _{IN} = 0V, source side		130	200	μΑ	
	I _{LIN} 5		L _{IN} = 5V, sink side		130	200	μΑ	
Saturation voltage	VSAT U-1		$L_VREF = LV_{CC}$ Between output and LV_{CC} $I_O = 0.6A$, CW/CCW mode		1.9	2.4	٧	
	VSAT L-1		$L_VREF = LV_{CC}$ Between output and LV_{CC} $I_O = 0.6A$, CW/CCW mode		1.2	1.7	٧	
	VSATII	_	L_VREF = LV _{CC} SINK+SOURCE I _O = 0.4A, CW/CCW mode		2.8	3.5	V	
Residual voltage of upper side	VSAT U-1		L_VREF = 8V Between output and L_MGND IO = 0.6A, CW/CCW mode	7.2	8.0	8.8	V	
Output transistor leak current	Upper	ILU	V _{CC} = 0V			50	μΑ	
	Lower	Lower ILL V _{CC} = 0V				50	μА	
L_VREF current	IVREF		L_VREF = LV _{CC} , source side L _{IN} = 0.5V		2	5	μΑ	

Package Dimensions

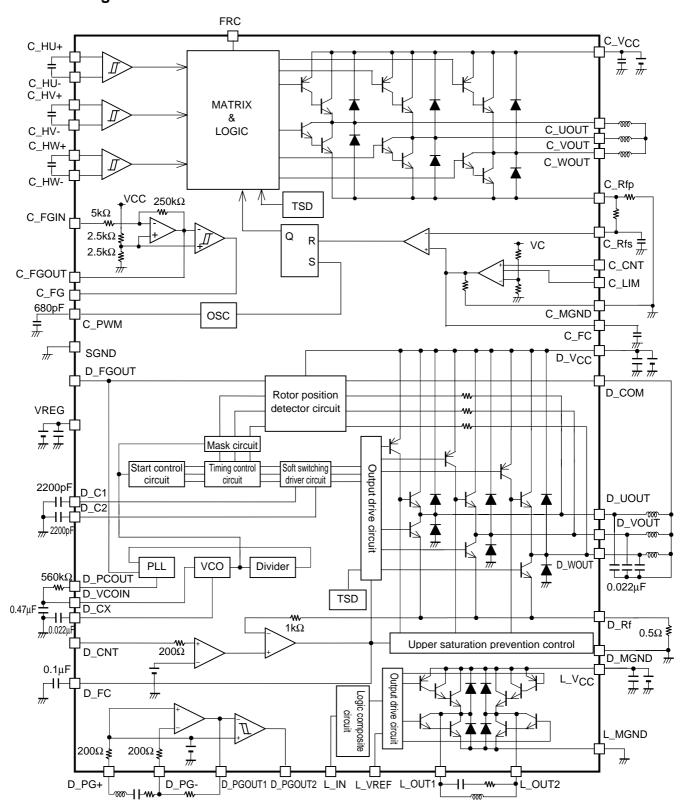
unit: mm (typ)

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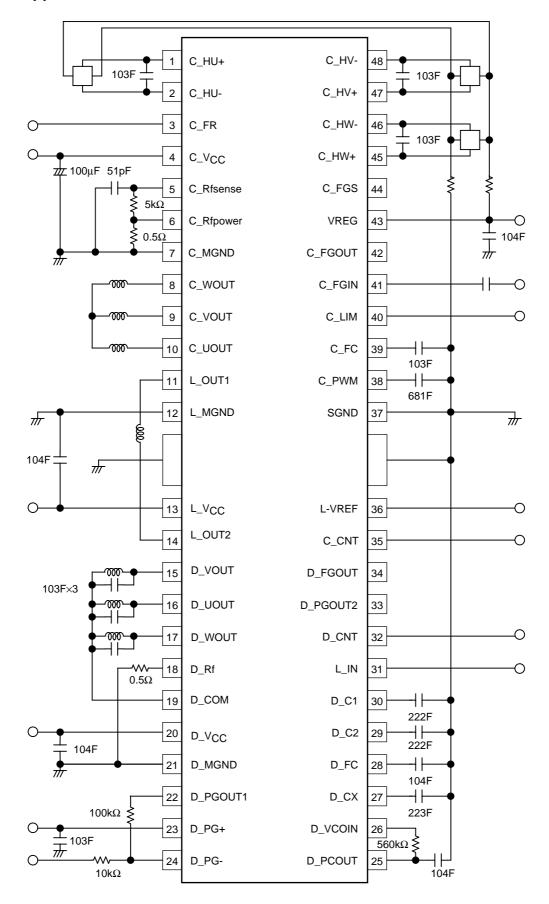




Block Diagram



Sample Application Circuit



Pin Assignment

C_HU+ 1	-	48	C_HV-	
C_HU- 2		47	C_HV+	
C_FR 3		46	C_HW-	
C_V _{CC} 4		45	C_HW+	
C_Rfsense 5		44	C_FGS	
C_Rfpower 6		43	VREG	
C_MGND 7	_	42	C_FGOUT	
C_WOUT 8	_	41	C_FGIN	
C_VOUT 9	_	40	C_LIM	
C_UOUT 10		39	C_FC	
L_OUT1 11	-	38	C_PWM	
L_MGND 12	- ? -	37	SGND	
	1.005			
	LB11885			
L_V _{CC} 13	3	36	L_VREF	
L_OUT2 14		35	C_CNT	
D_VOUT 15	- 5 -	34	D_FGOUT	
D_UOUT 16	- 5 -	33	D_PGOUT2	
D_WOUT 17	, -	32	D_CNT	
D_Rf 18	3	31	L_IN	
D_COM 19	-) -	30	D_C1	
D_V _{CC} 20		29	D_C2	
D_MGND 21	- -	28	D_FC	
D_RGOUT1 22		27	D_CX	
D_PG+ 23	3	26	D_VCOIN	
D_PG- 24		25	D_PCOUT	Top view

Pin Description

FIII D	escription	1		
Pin No	Symbol	Pin voltage	Pin Description	Equivalent Circuit
4	C-V _{CC}	8V to 28V	Power pin of capstan motor driver	
20	D-V _{CC}	8V to 28V	Power pin of drum motor driver	
13	L-V _{CC}	8V to 28V	Power pin of loading motor driver	
43	VREG	4V to 6V	Power pin to provide all voltages other than the output transistor and pre-drive	
7	C-MGND		Capstan motor GND	
37	SGND		GND for all other than output	
1	C-HU+		U-phase Hall element input pin HU+>HU- state for logic H	→ → Vcc
2	C-HU-	1.5V to V _{CC} -1.5V		* • • • • • • • • • • • • • • • • • • •
47	C-HV+		V-phase Hall element input pin. HV+>HV- state for logic H	(1) (2) (47) (48)
48	C-HV-			45 46
45	C-HW+		W-phase Hall element input pin. HW+>HW- state for logic H	* *
46	C-HW-			<i>m</i>
41	C-FGIN	1V to V _{CC} -1.5V	Capstan FGAMP reverse input pin	Vcc 5kΩ ≥ 300Ω
42	C-FGOUT		Capstan FGMP linear output pin Return resistor is incorporated with the amplification degree of about 50-fold.	250kΩ (41) (42) (42)
44	C-FGS		FG Schmidt amp output pin of capstan block	VCC 20kΩ \$5kΩ 44
3	C-FR	0V to VCC	Capstan forward/reverse control pin	VCC 300Ω 1.2V

Continued from preceding page. Symbol Pin voltage Pin Description **Equivalent Circuit** No 39 C-FC Capstan control loop frequency Vcc characteristics compensation pin 5 C-RFS Capstan current detection filter pin Connect the current detected at C-₄300Ω 300Ω∠ RFP to this pin after passing through the CR filter. 38 C-PWM Capacitor connection pin for PWM oscillation at capstan **(V)** 300Ω (38) $3k\Omega$ 40 C-LIM 0V to $V_{\mbox{\footnotesize{CC}}}$ Capstan current limit setting pin Vcc (35) 35 C-CNT Capstan speed control voltage 0V to $V_{\mbox{\footnotesize CC}}$ 300Ω 300Ω application pin C-WOUT 8 Capstan W-phase output pin CVCO C-VOUT 9 Capstan V-phase output pin 2kΩ ₹ 10 C-UOUT Capstan U-phase output pin 6 C-RFP PWRTR GND and current return resistor connection pin (6)

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Pin No	Symbol	Pin voltage	Pin Description	Equivalent Circuit
28	D-FC		Drum frequency characteristics compensation pin. Insertion of a capacitor to GND stops oscillation of the closed loop of current control system	VCC VCC
32	D-CNT	0V to V _{CC}	Drum speed control pin. Control is the constant current control to which current return is applied from DRS.	32 w Vcc w 300Ω
21	D-MGND		Drum current control sensing GND pin. Connect this pin to GND of the current detection resistor.	21 w-18
23	D-PG+		Drum PG amplifier non-inverted input pin Biased internally to (3/5)×V _{CC}	VCC ↓ 10kΩ 300Ω
24	D-PG-		Drum PG amplifier inverted input pin	300Ω2 300Ω2 \$ 15kΩ

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Pin No	Symbol	Pin voltage	Pin Description	Equivalent Circuit
22	D-PGOUT1		Drum PG amplifier linear output pin	Vcc 5kΩ ₹ 300Ω 500Ω ₹ 22
33	D-PGOUT2		Drum PG Schmidt amplifier output pin	V _{CC} 333
34	D-FGOUT		Drum motor reverse counter- electromotive voltage detection output pin (three-phase synthesizing)	VCC \$5kΩ \$34
26	D-VCOIN		VCO circuit voltage input pin of drum block. The PCOUT pin voltage is input via CR filter.	26 VCC 4.7kΩ
25	D-PCOUT		VCO circuit PLL output pin of drum block.	Vcc

Pin No	Symbol	Pin voltage	Pin Description	Equivalent Circuit
16	D-UOUT		Drum motor driver output pin	DLVCO
15	D-VOUT			
17	D-WOUT			
18	D-RF		Minimum potential of drum motor driver output transistor. Constant-current control is made through detection of this voltage. The current limiter also functions by detecting this potential.	17 16 18 15
19	D-COM		Motor coil neutral point input pin. The coil voltage waveform is detected with reference to this voltage.	DVCO 17/16/15 Ψ Ψ 200Ω 2kΩ \$\frac{200Ω}{m} \frac{200Ω}{m} \frac{19}{m} \frac{19}{m} \frac{1}{m} \f
30	D-C1		Triangular wave generating capacitor connection pin of drum block. This triangular wave performs soft- switching of the coil output waveform.	Vcc (29)
29	D-C2			1/2V _{CC} -VF
27	D-CX		In the VCO circuit, the operation frequency range and minimum operation frequency are determined by means of the capacitor value connected to this pin and GND.	300Ω W 27

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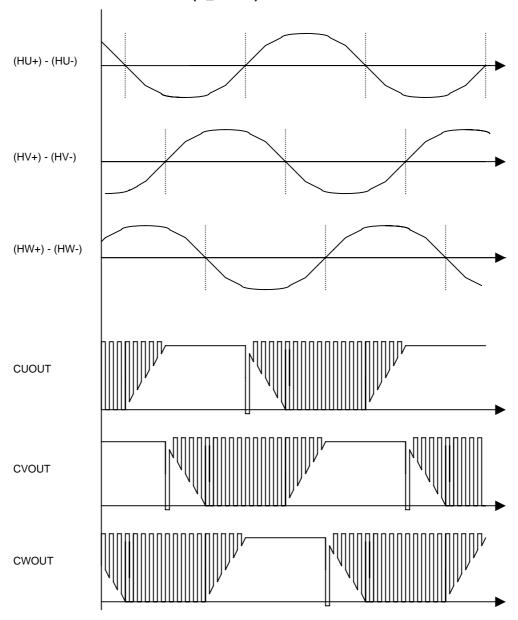
L-MGND

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Pin No	Symbol	Pin voltage	Pin Description	Equivalent Circuit
36	L-VREF	0 to LVCO	Loading output voltage setting pin	11) 14) 30kΩ Ψ Ψ 30kΩ \$ 30kΩ
31	L-IN	0V to V _{CC}	Loading logic input pin	20kΩ 10kΩ 20kΩ 10kΩ 10kΩ 10kΩ 10kΩ
11	L-OUT1		Loading motor driver output pin	(13)
14	L-OUT2			→ (1) (14)

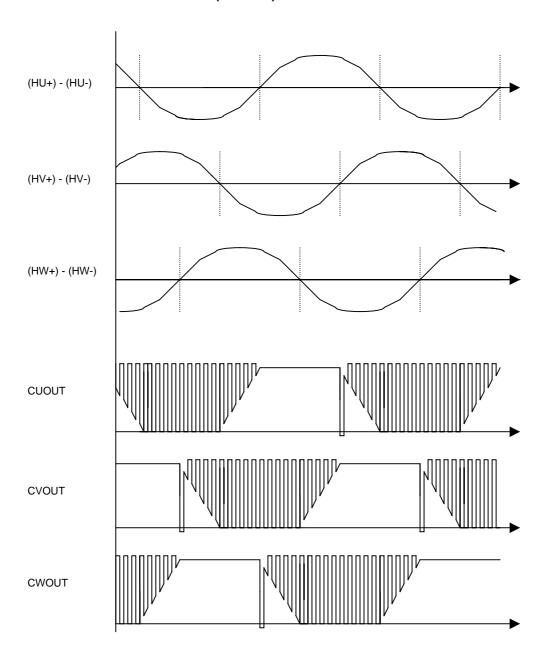
Loading output transistor GND pin

Timing Chart and Truth Table

1. Capstan Motor Driver Drive waveform (C_FR = L)



2. Capstan Motor Driver Drive waveform (FRC = H)

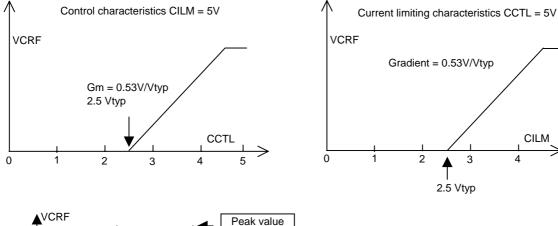


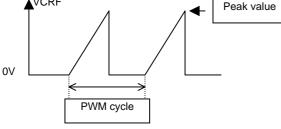
3. Capstan Motor Driver Truth Table & Control Functions

	Carrage Cials	Hall input		EDO	
	Source→Sink	U	V	W	FRC
1	$V\toW$	Н	н	L	Н
	$W\toV$				L
2	$U\toW$	Н	L	L	Н
	$W\toU$				L
3	$U\toV$	Н	L	Н	Н
	$V\toU$				L
4	$W \to V$	L	L	Н	Н
	$V\toW$				L
5	$W\toU$	L	н	Н	H
	$U\toW$				L
6	$V\toU$	L	Н	L	Н
	$U\toV$				L

Note) H of FRC means the voltage of 1.5V or more while L means the voltage of 1.0V or less. (At $V_{CC} = 5V$) Note) For the Hall input, the input H means the condition in which (+) relative to each phase input (-) is higher by 0.1V. The input L means the condition in which (+) relative to (-) is lower by 0.1V or more.

Control function & control limiting function

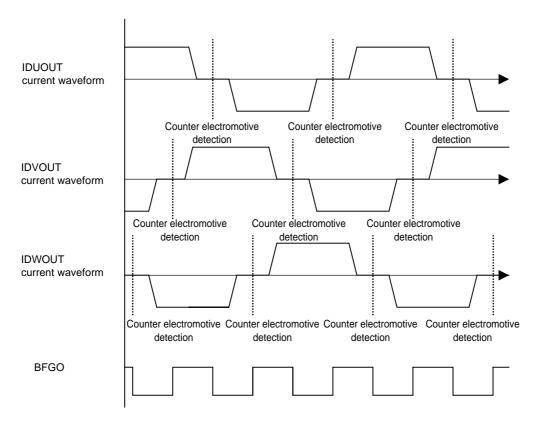




Caution: For the VCRF voltage of control characteristics, the peak value is to be measured. Cautions for use)

- When the direct reversion brake is to be used, keep the voltage at the C_LIM terminal 3.1kV or less so that IOMAX is not exceeded.
- The capacitor to be used between power supply and GND should be an electrolytic capacitor of 47µF or more.

4. Drum Motor Driver Drive current waveform



5. Loading Motor Truth table

Input	Output		Mada	
LIN	LOUT1	LOUT2	Mode	
L	L	Н	Reverse	
M (or OPEN)	L	L	Brake	
Н	Н	L	Forward	

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