

### General Description

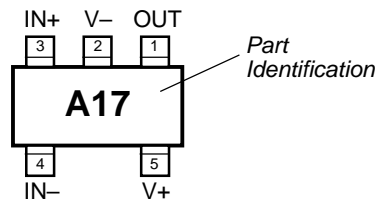
The MIC7300 is a high-performance CMOS operational amplifier featuring rail-to-rail input and output with strong output drive capability. It is able to source and sink in excess of 80mA into large capacitive loads.

The input common-mode range extends beyond the rails by 300mV, and the output voltage typically swings to within 150µV of both rails when driving a 100kΩ load.

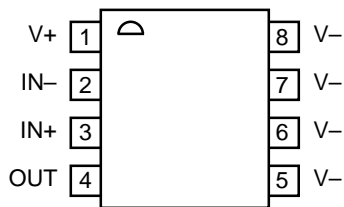
The amplifier operates from 2.2V to 10V and is fully specified at 2.2V, 3V, 5V, and 10V. Gain bandwidth and slew rate are 500kHz and 0.5V/µs, respectively.

The MIC7300 is available in Micrel's IttyBitty™ SOT-23-5 package for space-conscious circuits and in high-power MM8™ 8-lead MSOP for improved heat dissipation in higher power applications.

### Pin Configurations



SOT-23-5 (M5)



MSOP-8 (MM)

### Features

- Small footprint SOT-23-5 and power MSOP-8 packages
- >80mA peak output sink and source with 5V supply
- Drives large capacitive loads (6000pF with 10V supply)
- Guaranteed 2.2V, 3V, 5V, and 10V performance
- 500kHz gain-bandwidth product
- 0.01% total harmonic distortion at 1kHz (10V, 2kΩ)
- 1mA typical power supply current at 5V

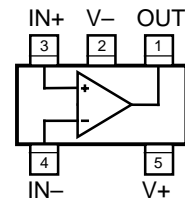
### Applications

- Battery-powered instrumentation
- PCMCIA, USB peripherals
- Portable computers and PDAs

### Ordering Information

Part Number			
Standard	Pb-free	Temp. Range	Package
MIC7300BM5	MIC7300YM5	-40°C to +85°C	SOT-23-5
MIC7300BMM	MIC7300YMM	-40°C to +85°C	MSOP-8

### Functional Configuration



SOT-23-5 (M5)

### Pin Description

Pin Number SOT-23-5	Pin Number MSOP-8	Pin Name	Pin Function
1	4	OUT	Amplifier Output
2	5-8	V-	Negative Supply: Negative supply for split supply application or ground for single supply application.
3	3	IN+	Noninverting Input
4	2	IN-	Inverting Input
5	1	V+	Positive Supply

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**Absolute Maximum Ratings (Note 1)**

Supply Voltage ( $V_{V+} - V_{V-}$ )	12V
Differential Input Voltage ( $V_{IN+} - V_{IN-}$ )	$\pm 12V$
I/O Pin Voltage ( $V_{IN}, V_{OUT}$ ), <b>Note 3</b>	$V_{V+} + 0.3V$ to $V_{V-} - 0.3V$
Junction Temperature ( $T_J$ )	$+150^\circ C$
Storage Temperature	$-65^\circ C$ to $+150^\circ C$
Lead Temperature (soldering, 10 sec.)	$260^\circ C$
ESD, <b>Note 6</b>	

**Operating Ratings (Note 2)**

Supply Voltage ( $V_{V+} - V_{V-}$ )	2.2V to 10V
Junction Temperature ( $T_J$ )	$-40^\circ C$ to $+85^\circ C$
Package Thermal Resistance, <b>Note 5</b>	
SOT-23-5 ( $\theta_{JA}$ )	$260^\circ C/W$
MSOP-8 ( $\theta_{JA}$ )	$85^\circ C/W$
Max. Power Dissipation	<b>Note 4</b>

**DC Electrical Characteristics (2.2V)**

$V_{V+} = +2.2V$ ,  $V_{V-} = 0V$ ,  $V_{CM} = V_{OUT} = V_{V+}/2$ ;  $R_L = 1M\Omega$ ;  $T_J = 25^\circ C$ , **bold** values indicate  $-40^\circ C \leq T_J \leq +85^\circ C$ ; **Note 7**; unless noted

Symbol	Parameter	Condition	Min	Typ	Max	Units	
$V_{OS}$	Input Offset Voltage			1.0	9	mV	
$TCV_{OS}$	Input Offset Voltage Average Drift			1.0		$\mu V/^\circ C$	
$I_B$	Input Bias Current			0.5		pA	
$I_{OS}$	Input Offset Current			0.25		pA	
$R_{IN}$	Input Resistance			>1		$T\Omega$	
CMRR	Common-Mode Rejection Ratio	$0V \leq V_{CM} \leq 2.2V$ , <b>Note 9</b>	45	65		dB	
$V_{CM}$	Input Common-Mode Voltage	input low, CMRR $\geq 45dB$		-0.3	0.0	V	
		input high, CMRR $\geq 45dB$	2.2	2.5		V	
$\pm PSRR$	Power Supply Rejection Ratio	$V_{V+} =  V_{V-}  = 1.1V$ to $2.5V$ , $V_{CM} = 0$	55	75		dB	
$C_{IN}$	Common-Mode Input Capacitance			3		pF	
$V_O$	Output Swing	output high, $R_L = 100k$ , specified as $V_{V+} - V_{OUT}$		0.15	<b>1</b>	mV	
		output low, $R_L = 100k$		0.15	<b>1</b>	mV	
		output high, $R_L = 2k$ specified as $V_{V+} - V_{OUT}$		10	33	<b>50</b>	mV
		output low, $R_L = 2k$		10	33	<b>50</b>	mV
		output high, $R_L = 600\Omega$ specified as $V_{V+} - V_{OUT}$		33	110	<b>165</b>	mV
		output low, $R_L = 600\Omega$		33	110	<b>165</b>	mV
$I_{SC}$	Output Short Circuit Current	sinking or sourcing, <b>Note 8</b>	20	40		mA	
$I_S$	Supply Current	$V_{OUT} = V_{V+}/2$		0.7	2.0	mA	

**AC Electrical Characteristics (2.2V)**

$V_{V+} = 2.2V$ ,  $V_{V-} = 0V$ ,  $V_{CM} = V_{OUT} = V_{V+}/2$ ;  $R_L = 1M\Omega$ ;  $T_J = 25^\circ C$ , **bold** values indicate  $-40^\circ C \leq T_J \leq +85^\circ C$ ; **Note 7**; unless noted

Symbol	Parameter	Condition	Min	Typ	Max	Units
SR	Slew Rate			0.5		V/ $\mu s$
GBW	Gain-Bandwidth Product			0.55		MHz
$\phi_m$	Phase Margin	$C_L = 0pF$		80		$^\circ$
		$C_L = 2500pF$		40		$^\circ$
$G_m$	Gain Margin			10		dB

## DC Electrical Characteristics (3.0V)

$V_{V+} = +3.0V$ ,  $V_{V-} = 0V$ ,  $V_{CM} = V_{OUT} = V_{V+}/2$ ;  $R_L = 1M\Omega$ ;  $T_J = 25^\circ C$ , **bold** values indicate  $-40^\circ C \leq T_J \leq +85^\circ C$ ; **Note 7**; unless noted

Symbol	Parameter	Condition	Min	Typ	Max	Units
$V_{OS}$	Input Offset Voltage			1.0	9	mV
$TCV_{OS}$	Input Offset Voltage Average Drift			1.0		$\mu V/^\circ C$
$I_B$	Input Bias Current			0.5		pA
$I_{OS}$	Input Offset Current			0.25		pA
$R_{IN}$	Input Resistance			>1		$T\Omega$
CMRR	Common-Mode Rejection Ratio	$0V \leq V_{CM} \leq 3.0V$ , <b>Note 9</b>	50	70		dB
$V_{CM}$	Input Common-Mode Voltage	input low, CMRR $\geq 50$ dB		-0.3	0	V
		input high, CMRR $\geq 50$ dB	3.0	3.3		V
$\pm PSRR$	Power Supply Rejection Ratio	$V_{V+} =  V_{V-}  = 1.5V$ to $5.0V$ , $V_{CM} = 0$	55	75		dB
$C_{IN}$	Common-Mode Input Capacitance			3		pF
$V_{OUT}$	Output Swing	output high, $R_L = 100k$ specified as $V_{V+} - V_{OUT}$		0.2	<b>1</b>	mV mV
		output low, $R_L = 100k$		0.2	<b>1</b>	mV mV
		output high, $R_L = 2k$ specified as $V_{V+} - V_{OUT}$		10	33 <b>50</b>	mV mV
		output low, $R_L = 2k$		10	33 <b>50</b>	mV mV
		output high, $R_L = 600\Omega$ specified as $V_{V+} - V_{OUT}$		33	110 <b>165</b>	mV mV
		output low, $R_L = 600\Omega$		33	110 <b>165</b>	mV mV
$I_{SC}$	Output Short Circuit Current	sinking or sourcing, <b>Note 8</b>	60	95		mA
$I_S$	Supply Current			0.8	2.2	mA

## AC Electrical Characteristics (3V)

$V_{V+} = 3V$ ,  $V_{V-} = 0V$ ,  $V_{CM} = 1.5V$ ,  $V_{OUT} = V_{V+}/2$ ;  $R_L = 1M\Omega$ ;  $T_J = 25^\circ C$ , **bold** values indicate  $-40^\circ C \leq T_J \leq +85^\circ C$ ; **Note 7**; unless noted

Symbol	Parameter	Condition	Min	Typ	Max	Units
SR	Slew Rate			0.5		V/ $\mu s$
GBW	Gain-Bandwidth Product			0.45		MHz
$\phi_m$	Phase Margin	$C_L = 0pF$		85		$^\circ$
		$C_L = 3500pF$		40		$^\circ$
$G_m$	Gain Margin			10		dB

## DC Electrical Characteristics (5V)

$V_{V+} = +5.0V$ ,  $V_{V-} = 0V$ ,  $V_{CM} = 1.5V$ ,  $V_{OUT} = V_{V+}/2$ ;  $R_L = 1M\Omega$ ;  $T_J = 25^\circ C$ , **bold** values indicate  $-40^\circ C \leq T_J \leq +85^\circ C$ ; **Note 7**; unless noted

Symbol	Parameter	Condition	Min	Typ	Max	Units
$V_{OS}$	Input Offset Voltage			1.0	9	mV
$TCV_{OS}$	Input Offset Voltage Average Drift			1.0		$\mu V/^\circ C$
$I_B$	Input Bias Current			0.5		pA
$I_{OS}$	Input Offset Current			0.25		pA
$R_{IN}$	Input Resistance			>1		$T\Omega$
CMRR	Common-Mode Rejection Ratio	$0V \leq V_{CM} \leq 5V$ , <b>Note 9</b>	55	80		dB
$V_{CM}$	Input Common-Mode Voltage	input low, CMRR $\geq 55$ dB		-0.3	-0.0	V
		input high, CMRR $\geq 55$ dB	5.0	5.3		V
$\pm PSRR$	Power Supply Rejection Ratio	$V_{V+} =  V_{V-}  = 2.5V$ to $5.0V$ , $V_{CM} = 0$	55	75		dB
$C_{IN}$	Common-Mode Input Capacitance			3		pF
$V_{OUT}$	Output Swing	output high, $R_L = 100k$ specified as $V_{V+} - V_{OUT}$		0.3	1.0 <b>1.5</b>	mV mV
		output low, $R_L = 100k$		0.3	1.0 <b>1.5</b>	mV mV
		output high, $R_L = 2k$ specified as $V_{V+} - V_{OUT}$		15	50 <b>75</b>	mV mV
		output low, $R_L = 2k$		15	50 <b>75</b>	mV mV
		output high, $R_L = 600\Omega$ specified as $V_{V+} - V_{OUT}$		50	165 <b>250</b>	mV mV
		output low, $R_L = 600\Omega$		50	165 <b>250</b>	mV mV
$I_{SC}$	Output Short Circuit Current	sinking or sourcing, <b>Note 8</b>	85	105		mA
$I_S$	Supply Current	$V_{OUT} = V+/2$		1.0	2.8	mA

## AC Electrical Characteristics (5V)

$V_{V+} = 5V$ ,  $V_{V-} = 0V$ ,  $V_{CM} = 1.5V$ ,  $V_{OUT} = V_{V+}/2$ ;  $R_L = 1M\Omega$ ;  $T_J = 25^\circ C$ , **bold** values indicate  $-40^\circ C \leq T_J \leq +85^\circ C$ ; **Note 7**; unless noted

Symbol	Parameter	Condition	Min	Typ	Max	Units
THD	Total Harmonic Distortion	$f = 1kHz$ , $A_V = -2$ , $R_L = 2k\Omega$ , $V_{OUT} = 4.0 V_{PP}$		0.05		%
SR	Slew Rate			0.5		$V/\mu s$
GBW	Gain-Bandwidth Product			0.4		MHz
$\phi_m$	Phase Margin	$C_L = 0pF$		85		$^\circ$
		$C_L = 4500pF$		40		$^\circ$
$G_m$	Gain Margin			10		dB

## DC Electrical Characteristics (10V)

$V_{V+} = +10V$ ,  $V_{V-} = 0V$ ,  $V_{CM} = 1.5V$ ,  $V_{OUT} = V_{V+}/2$ ;  $R_L = 1M\Omega$ ;  $T_J = 25^\circ C$ , **bold** values indicate  $-40^\circ C \leq T_J \leq +85^\circ C$ ; **Note 7**; unless noted

Symbol	Parameter	Condition	Min	Typ	Max	Units
$V_{OS}$	Input Offset Voltage			1.0	9	mV
$TCV_{OS}$	Input Offset Voltage Average Drift			1.0		$\mu V/^\circ C$
$I_B$	Input Bias Current			0.5		pA
$I_{OS}$	Input Offset Current			0.25		pA
$R_{IN}$	Input Resistance			>1		$T\Omega$
CMRR	Common-Mode Rejection Ratio	$0V \leq V_{CM} \leq 10V$ , <b>Note 9</b>	60	85		dB
$V_{CM}$	Input Common-Mode Voltage	input low, $V_+ = 10V$ , CMRR $\geq 60dB$		-0.3	-0.0	V
		input high, $V_+ = 10V$ , CMRR $\geq 60dB$	10.0	10.3		V
$\pm PSRR$	Power Supply Rejection Ratio	$V_{V+} =  V_{V-}  = 2.5V$ to $5.0V$ , $V_{CM} = 0$	55	75		dB
$A_V$	Large Signal Voltage Gain	sourcing or sinking, $R_L = 2k$ , <b>Note 10</b>	80	340		V/mV
		sourcing or sinking, $R_L = 600\Omega$ , <b>Note 10</b>	15	300		V/mV
$C_{IN}$	Common-Mode Input Capacitance			3		pF
$V_{OUT}$	Output Swing	output high, $R_L = 100k$ specified as $V_{V+} - V_{OUT}$		0.5	1.5 <b>2.5</b>	mV mV
		output low, $R_L = 100k$		0.5	1.5 <b>2.5</b>	mV mV
		output high, $R_L = 2k$ specified as $V_{V+} - V_{OUT}$		24	80 <b>120</b>	mV mV
		output low, $R_L = 2k$		24	80 <b>120</b>	mV mV
		output high, $R_L = 600\Omega$ specified as $V_{V+} - V_{OUT}$		80	270 <b>400</b>	mV mV
		output low, $R_L = 600\Omega$		80	270 <b>400</b>	mV mV
$I_{SC}$	Output Short Circuit Current	sinking or sourcing, <b>Notes 8</b>	90	115		mA
$I_S$	Supply Current	$V_{OUT} = V_+/2$		1.5	4.0	mA

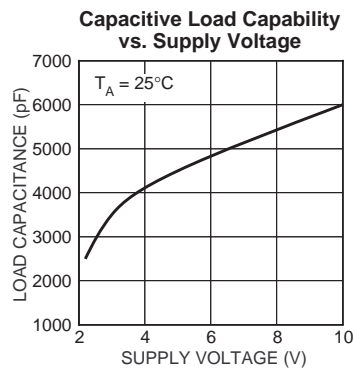
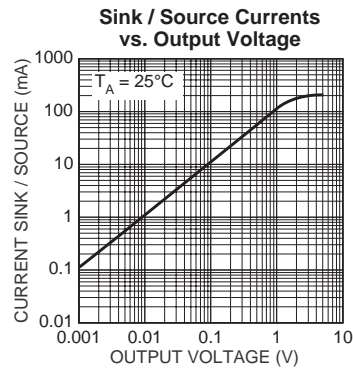
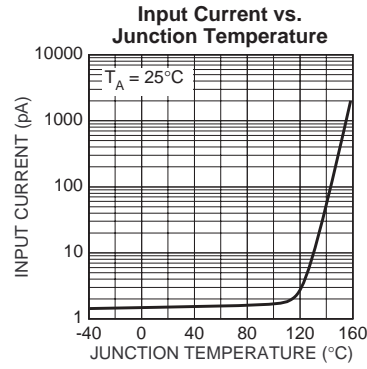
## AC Electrical Characteristics (10V)

$V_{V+} = 10V$ ,  $V_{V-} = 0V$ ,  $V_{CM} = 1.5V$ ,  $V_{OUT} = V_{V+}/2$ ;  $R_L = 1M\Omega$ ;  $T_J = 25^\circ C$ , **bold** values indicate  $-40^\circ C \leq T_J \leq +85^\circ C$ ; **Note 7**; unless noted

Symbol	Parameter	Condition	Min	Typ	Max	Units
THD	Total Harmonic Distortion	$f = 1kHz$ , $A_V = -2$ , $R_L = 2k$ , $V_{OUT} = 8.5 V_{PP}$		0.01		%
SR	Slew Rate	$V_+ = 10V$ , <b>Note 11</b>		0.5		V/ $\mu s$ V/ $\mu s$
GBW	Gain-Bandwidth Product			0.37		MHz
$\phi_m$	Phase Margin	$C_L = 0pF$		85		$^\circ$
		$C_L = 6000pF$		40		$^\circ$
$G_m$	Gain Margin			10		dB
$e_n$	Input-Referred Voltage Noise	$f = 1kHz$ , $V_{CM} = 1V$		37		$nV/\sqrt{Hz}$
$i_n$	Input-Referred Current Noise	$f = 1kHz$		1.5		$fA/\sqrt{Hz}$

- Note 1.** Exceeding the absolute maximum rating may damage the device.
- Note 2.** The device is not guaranteed to function outside its operating rating.
- Note 3.** I/O Pin Voltage is any external voltage to which an input or output is referenced.
- Note 4.** The maximum allowable power dissipation is a function of the maximum junction temperature,  $T_{J(max)}$ ; the junction-to-ambient thermal resistance,  $\theta_{JA}$ ; and the ambient temperature,  $T_A$ . The maximum allowable power dissipation at any ambient temperature is calculated using:  $P_D = (T_{J(max)} - T_A) \div \theta_{JA}$ . Exceeding the maximum allowable power dissipation will result in excessive die temperature.
- Note 5.** Thermal resistance,  $\theta_{JA}$ , applies to a part soldered on a printed-circuit board.
- Note 6.** Devices are ESD protected; however, handling precautions are recommended.
- Note 7.** All limits guaranteed by testing or statistical analysis.
- Note 8.** Continuous short circuit may exceed absolute maximum  $T_J$  under some conditions.
- Note 9.** CMRR is determined as follows: The maximum  $\Delta V_{OS}$  over the  $V_{CM}$  range is divided by the magnitude of the  $V_{CM}$  range. The measurement points are:  $V_{V-}$ ,  $(V_{V+} - V_{V-})/2$ , and  $V_{V+}$ .
- Note 10.**  $R_L$  connected to 5V. Sourcing:  $5V \leq V_{OUT} \leq 10V$ . Sinking:  $2.5V \leq V_{OUT} \leq 5V$ .
- Note 11.** Device connected as a voltage follower with a 10V step input. The value is the positive or negative slew rate, whichever is slower.

# Typical Characteristics



## Application Information

### Input Common-Mode Voltage

The MIC7300 tolerates input overdrive by at least 300mV beyond either rail without producing phase inversion.

If the absolute maximum input voltage is exceeded, the input current should be limited to  $\pm 5\text{mA}$  maximum to prevent reducing reliability. A  $10\text{k}\Omega$  series input resistor, used as a current limiter, will protect the input structure from voltages as large as 50V above the supply or below ground. See Figure 1.

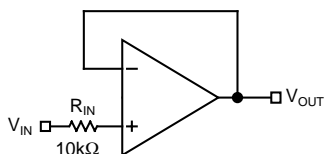


Figure 1. Input Current-Limit Protection

### Output Voltage Swing

Sink and source output resistances of the MIC7300 are equal. Maximum output voltage swing is determined by the load and the approximate output resistance. The output resistance is:

$$R_{\text{OUT}} = \frac{V_{\text{DROP}}}{I_{\text{LOAD}}}$$

$V_{\text{DROP}}$  is the voltage dropped within the amplifier output stage.  $V_{\text{DROP}}$  and  $I_{\text{LOAD}}$  can be determined from the  $V_{\text{O}}$  (output swing) portion of the appropriate Electrical Characteristics table.  $I_{\text{LOAD}}$  is equal to the typical output high voltage minus  $V_{+}/2$  and divided by  $R_{\text{LOAD}}$ . For example, using the Electrical Characteristics DC (5V) table, the typical output high voltage using a  $2\text{k}\Omega$  load (connected to  $V_{+}/2$ ) is 4.985V, which produces an  $I_{\text{LOAD}}$  of:

$$\left( \frac{4.985\text{V} - 2.5\text{V}}{2\text{k}\Omega} \right) = 1.243\text{mA}$$

Voltage drop in the amplifier output stage is:

$$V_{\text{DROP}} = 5.0\text{V} - 4.985\text{V}$$

$$V_{\text{DROP}} = 0.015\text{V}$$

Because of output stage symmetry, the corresponding typical output low voltage (0.015V) also equals  $V_{\text{DROP}}$ . Then:

$$R_{\text{OUT}} = \frac{0.015\text{V}}{0.001243\text{A}} = 12\Omega$$

### Power Dissipation

The MIC7300 output drive capability requires considering power dissipation. If the load impedance is low, it is possible to damage the device by exceeding the  $125^{\circ}\text{C}$  junction temperature rating.

On-chip power consists of two components: supply power and output stage power. Supply power ( $P_{\text{S}}$ ) is the product of the supply voltage ( $V_{\text{S}} = V_{\text{V}+} - V_{\text{V}-}$ ) and supply current ( $I_{\text{S}}$ ).

Output stage power ( $P_{\text{O}}$ ) is the product of the output stage voltage drop ( $V_{\text{DROP}}$ ) and the output (load) current ( $I_{\text{OUT}}$ ). Total on-chip power dissipation is:

$$P_{\text{D}} = P_{\text{S}} + P_{\text{O}}$$

$$P_{\text{D}} = V_{\text{S}} I_{\text{S}} + V_{\text{DROP}} I_{\text{OUT}}$$

where:

$P_{\text{D}}$  = total on-chip power

$P_{\text{S}}$  = supply power dissipation

$P_{\text{O}}$  = output power dissipation

$V_{\text{S}} = V_{\text{V}+} - V_{\text{V}-}$

$I_{\text{S}}$  = power supply current

$V_{\text{DROP}} = V_{\text{V}+} - V_{\text{OUT}}$  (sourcing current)

$V_{\text{DROP}} = V_{\text{OUT}} - V_{\text{V}-}$  (sinking current)

The above addresses only steady state (dc) conditions. For non-dc conditions the user must estimate power dissipation based on rms value of the signal.

The task is one of determining the allowable on-chip power dissipation for operation at a given ambient temperature and power supply voltage. From this determination, one may calculate the maximum allowable power dissipation and, after subtracting  $P_{\text{S}}$ , determine the maximum allowable load current, which in turn can be used to determine the minimum load impedance that may safely be driven. The calculation is summarized below.

$$P_{\text{D(max)}} = \frac{T_{\text{J(max)}} - T_{\text{A}}}{\theta_{\text{JA}}}$$

$$\theta_{\text{JA(SOT-23-5)}} = 260^{\circ}\text{C/W}$$

$$\theta_{\text{JA(MSOP-8)}} = 85^{\circ}\text{C/W}$$

### Driving Capacitive Loads

Driving a capacitive load introduces phase-lag into the output signal, and this in turn reduces op-amp system phase margin. The application that is least forgiving of reduced phase margin is a unity gain amplifier. The MIC7300 can typically drive a  $2500\text{pF}$  capacitive load connected directly to the output when configured as a unity-gain amplifier and powered with a 2.2V supply. At 10V operation the circuit typically drives  $6000\text{pF}$ . Phase margin is typically  $40^{\circ}$ .

### Using Large-Value Feedback Resistors

A large-value feedback resistor ( $> 500\text{k}\Omega$ ) can reduce the phase margin of a system. This occurs when the feedback resistor acts in conjunction with input capacitance to create phase lag in the feedback signal. Input capacitance is usually a combination of input circuit components and other parasitic capacitance, such as amplifier input capacitance and stray printed circuit board capacitance.

Figure 2 illustrates a method of compensating phase lag caused by using a large-value feedback resistor. Feedback capacitor  $C_{\text{FB}}$  introduces sufficient phase lead to overcome



the phase lag caused by feedback resistor  $R_{FB}$  and input capacitance  $C_{IN}$ . The value of  $C_{FB}$  is determined by first estimating  $C_{IN}$  and then applying the following formula:

$$R_{IN} \times C_{IN} \leq R_{FB} \times C_{FB}$$

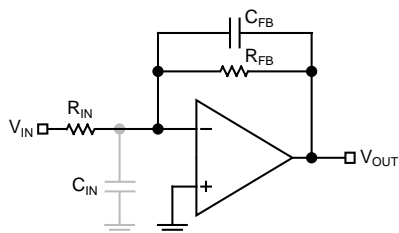


Figure 2. Cancelling Feedback Phase Lag

Since a significant percentage of  $C_{IN}$  may be caused by board layout, it is important to note that the correct value of  $C_{FB}$  may change when changing from a breadboard to the final circuit layout.

Typical Circuits

Some single-supply, rail-to-rail applications for which the MIC7300 is well suited are shown in the circuit diagrams of Figures 3 through 7.

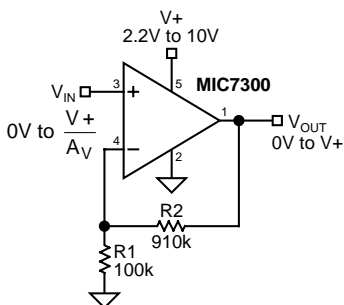


Figure 3a. Noninverting Amplifier

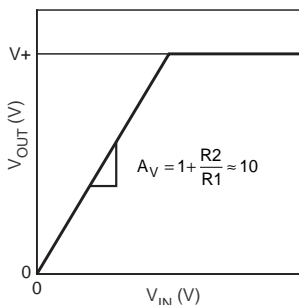


Figure 3b. Noninverting Amplifier Behavior

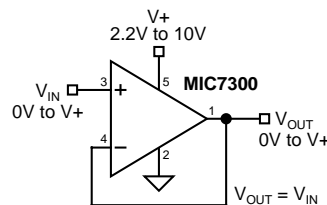


Figure 4. Voltage Follower/Buffer

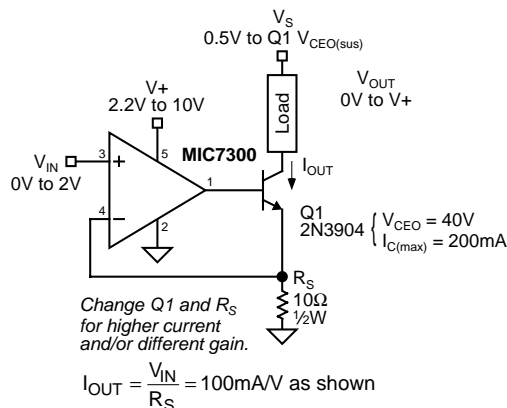


Figure 5. Voltage-Controlled Current Sink

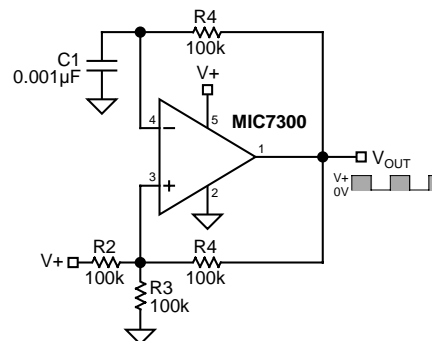


Figure 6. Square Wave Oscillator

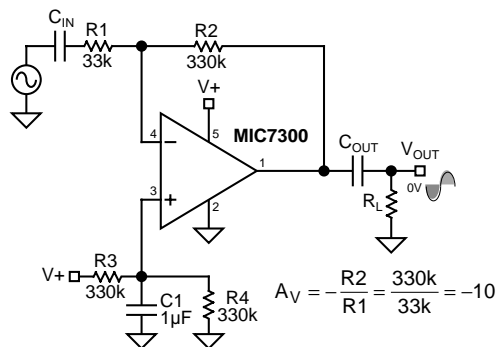
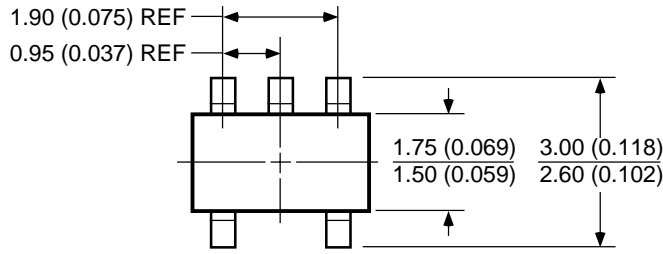
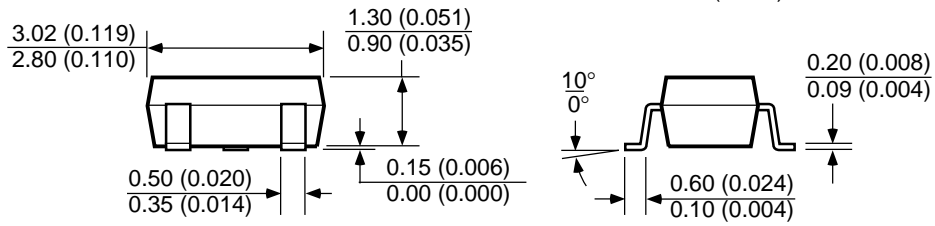


Figure 7. AC-Coupled Inverting Amplifier

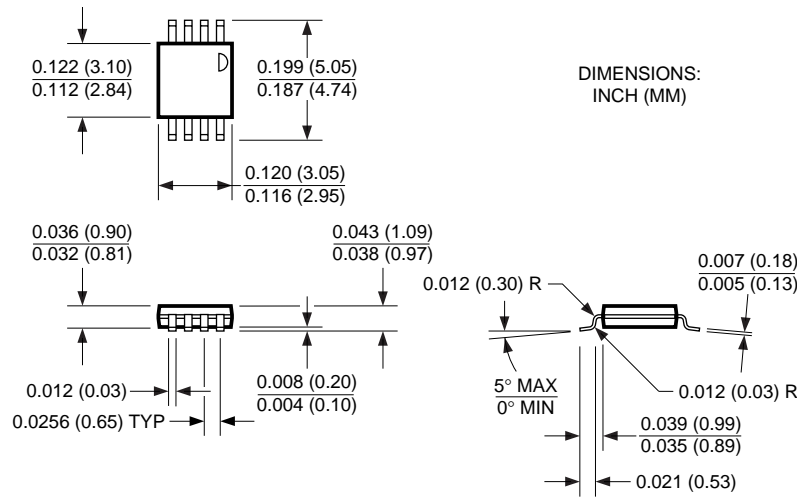
Package Information



DIMENSIONS:  
MM (INCH)



SOT-23-5 (M5)



DIMENSIONS:  
INCH (MM)

8-Pin MSOP (MM)



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