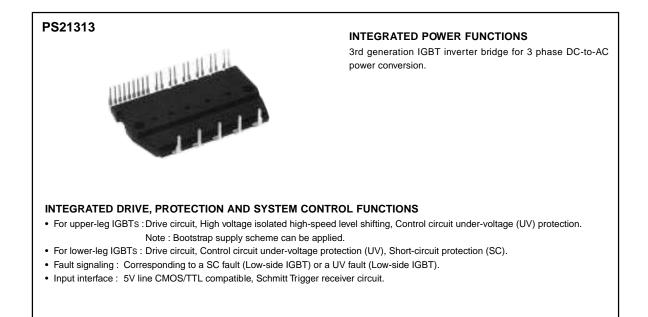
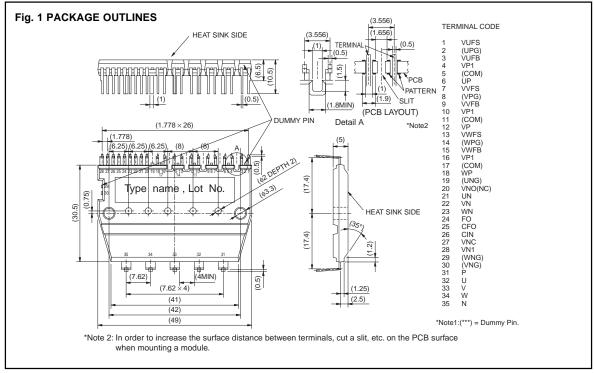
MITSUBISHI SEMICONDUCTOR < Dual-In-Line Package Intelligent Power Module>

PS21313 TRANSFER-MOLD TYPE INSULATED TYPE



APPLICATION

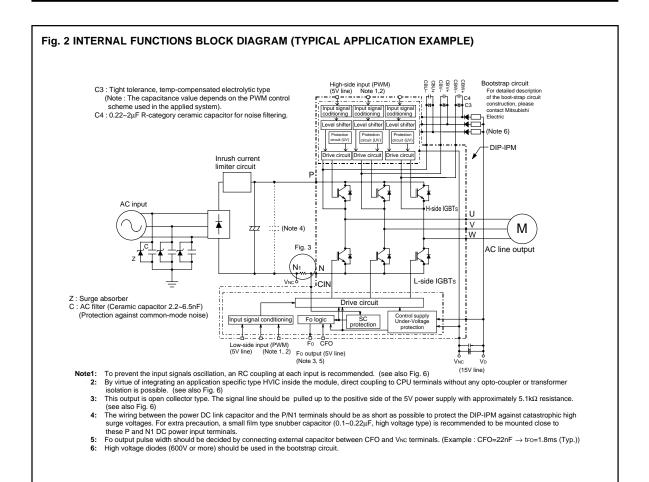
AC200V three-phase inverter drive for small power motor control.

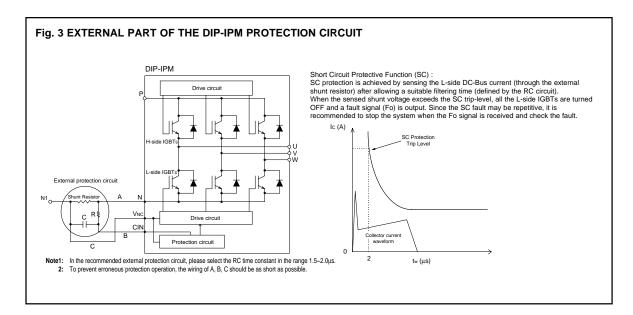


^{*} **Note:** The values used in the above figure are tentative.



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MAXIMUM RATINGS (T_j = 25°C, unless otherwise noted)

INVERTER PART

Symbol	Parameter	Condition	Ratings	Unit
Vcc	Supply voltage	Applied between P-N	450	V
VCC(surge)	Supply voltage (surge)	Applied between P-N	500	V
VCES	Collector-emitter voltage		600	V
±IC	Each IGBT collector current	Tc = 25°C	10	A
±ICP	Each IGBT collector current (peak)	Tc = 25°C, instantaneous value (pulse)	20	A
Pc	Collector dissipation	Tc = 25°C, per 1 chip	25	W
Tj	Junction temperature	(Note 1)	-20~+150	°C

Note 1 : The maximum junction temperature rating of the power chips integrated within the DIP-IPM is 150°C (@ Tf ≤ 100°C). However, to ensure safe operation of the DIP-IPM, the average junction temperature should be limited to T_j(ave) ≤ 125°C (@ Tf ≤ 100°C).

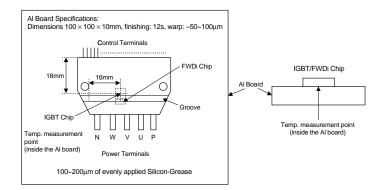
CONTROL (PROTECTION) PART

Symbol	Parameter	Condition	Ratings	Unit
Vd	Control supply voltage	Applied between VP1-VNC, VN1-VNC	20	V
Vdb	Control supply voltage	Applied between VUFB-VUFS, VVFB-VVFS, VWFB-VWFS	20	V
VCIN	Input voltage	Applied between UP, VP, WP-VNC, UN, VN, WN-VNC	-0.5~+5.5	V
Vfo	Fault output supply voltage	Applied between FO-VNC	-0.5~VD+0.5	V
IFO	Fault output current	Sink current at Fo terminal	15	mA
Vsc	Current sensing input voltage	Applied between CIN-VNC	-0.5~VD+0.5	V

TOTAL SYSTEM

Symbol	Parameter	Condition	Ratings	Unit
VCC(PROT)	Self protection supply voltage limit (short-circuit protection capability)	$V_D = 13.5 \sim 16.5 V$, Inverter part T _j = 125°C, non-repetitive, less than 2 μ s	400	V
Tf	Heat-fin operation temperature	(Note 2)	-20~+100	°C
Tstg	Storage temperature		-40~+125	°C
Viso	Isolation voltage	60Hz, Sinusoidal, AC 1 minute, connection pins to heat-sink plate	1500	Vrms

Note 2 : Tf MEASUREMENT POINT





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THERMAL RESISTANCE

Cumbal	Parameter	Condition	Limits			Linit
Symbol	Parameter	Condition	Min.	Тур.	Max.	Unit
Rth(j-f)Q	Junction-to-heat sink thermal	Inverter IGBT part (per 1/6 module)	—	—	5.0	
Rth(j-f)F	resistance	Inverter FWDi part (per 1/6 module)	_	_	6.0	°C/W

ELECTRICAL CHARACTERISTICS (Tj = 25°C, unless otherwise noted) **INVERTER PART**

Ourseland.	Deremeter Condition			Limits			
Symbol Parameter			Condition		Тур.	Max.	Unit
VCE(sat)	Collector-emitter saturation	VD = VDB = 15V	IC = 10A, Tj = 25°C	—	2.1	2.9	
voltage	VCIN = 0V	Ic = 10A, Tj = 125°C	—	2.2	3.2	V	
VEC	FWDi forward voltage	Tj = 25°C, –IC = 10A, VCIN = 5V		-	1.7	2.9	V
ton		VCC = 300V, VD = 15	0.1	0.6	1.1		
trr		IC = 10A, Tj = 125°C	IC = 10A. Ti = 125°C			-	
tc(on)	Switching times	Inductive load (upper-lower arm)		—	0.2	0.6	μs
toff	-	VCIN = $5 \leftrightarrow 0V$,	—	1.1	2.2	
tc(off)				—	0.35	1.25	
ICES	ES Collector-emitter cut-off		Tj = 25°C	—	_	1.0	mA
current	VCE = VCES	Tj = 125°C	_	-	10	IIIA	

CONTROL (PROTECTION) PART

Symbol	Parameter	Condition		Limits			Unit
Symbol		Condition		Min.	Тур.	Max.	Unit
Vd	Control supply voltage	Applied between	VP1-VNC, VN1-VNC	13.5	15.0	16.5	V
Vdb	Control supply voltage	Applied between	VUFB-VUFS, VVFB-VVFS, VWFB-VWFS	13.5	15.0	16.5	V
ID		VD = 15V, VCIN = 5V	Total of VP1-VNC, VN1-VNC		4.25	8.50	mA
	Circuit current	VDB = 15V, VCIN = 5V	VUFB-VUFS, VVFB-VVFS, VWFB-VWFS		0.50	1.00	mA
	Circuit current	VD = 15V, VCIN = 0V	VP1-VNC, VN1-VNC		4.95	9.70	mA
		VDB = 15V, VCIN = 0V	VUFB-VUFS, VVFB-VVFS, VWFB-VWFS		0.50	1.00	mA
VFOH		Vsc = 0V, Fo circu	uit : 10k Ω to 5V pull-up	4.9	—	—	V
VFOL	Fault output voltage	Vsc = 1V, Fo circu	uit : 10kΩ to 5V pull-up	_	0.8	1.2	V
VFOsat]	VSC = 1V, IFO = 15mA		0.8	1.2	1.8	V
fpwm	PWM input frequency	Tj ≤ 125°C, Tf ≤ 100°C			15	-	kHz
tdead	Allowable deadtime	Relates to corresponding input signal for blocking arm shoot-through. $(Tf \le 100^{\circ}C)$		3.0	_	_	μs
VSC(ref)	Short-circuit trip level	Tj = 25°C, VD = 15	5V (Note 3)	0.45	0.5	0.55	V
UVDBt			Trip level	10.0	_	12.0	V
UVDBr	Supply circuit under-voltage	Ti ≤ 125°C	Reset level	10.5	—	12.5	V
UVDt	protection	1) 2 120 0	Trip level	10.3	—	12.5	V
UVDr	1		Reset level	10.8	-	13.0	V
tFO	Fault output pulse width	CFO = 22nF	(Note 4)	1.0	1.8	-	ms
Vth(on)	ON threshold voltage		Applied between:	0.8	1.4	2.0	v
Vth(off)	OFF threshold voltage	- H-side	UP, VP, WP-VNC	2.5	3.0	4.0	1 V
Vth(on)	ON threshold voltage	Laida	Applied between:	0.8	1.4	2.0	v
Vth(off)	OFF threshold voltage	L-side	UN, VN, WN-VNC	2.5	3.0	4.0	1 ^v

Note 3: Short-circuit protection operates only at the low-arms. Please select the value of the external shunt resistor such that the SC trip level

3 Short-circuit protection operates only at the low-arms. Flease select the value of the external short-circuit at a cool approximation operate. The fault output is less than 17A
4 Fault signal is outputted when the low-arm short-circuit or control supply under-voltage protective functions operate. The fault output pulse-width tFO depends on the capacitance value of CFO according to the following approximate equation. : CFO = (12.2 × 10⁻⁶) × tFO [F]



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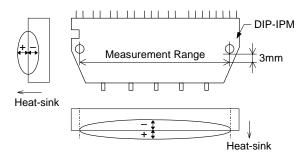
MECHANICAL CHARACTERISTICS AND RATINGS

Deveryotes	Condition		Limits			1.1
Parameter			Min.	Тур.	Max.	Unit
Mounting torque	Mounting coroury M2	Recommended 8kg-cm	—	8	—	kg∙cm
	Mounting screw : M3	Recommended 0.78N·m	—	0.78	—	N∙m
Weight			—	20	—	g
Heat-sink flatness	(Note 5)		-50	—	100	μm

RECOMMENDED OPERATION CONDITIONS

Quarkal	Descenter	Ora dition	Limits			11.2
Symbol	Parameter	Condition	Min.	Тур.	Max.	Unit
Vcc	Supply voltage	Applied between P-N	0	300	400	V
Vd	Control supply voltage	Applied between VP1-VNC, VN1-VNC	13.5	15.0	16.5	V
Vdb	Control supply voltage	Applied between VUFB-VUFS, VVFB-VVFS, VWFB-VWFS	13.5	15.0	16.5	V
$\Delta VD, \Delta VDB$	Control supply variation		-1	_	1.0	V/µs
tdead	Arm shoot-through blocking time	For each input signal	3	—	—	μs
fpwm	PWM input frequency	Tj ≤ 125°C, Tf ≤ 100°C	—	15	_	kHz
VCIN(ON)	Input ON voltage	Applied between UP, VP, WP-VNC		0~0.65		V
VCIN(OFF)	Input OFF voltage	Applied between UN, VN, WN-VNC		4.0~5.5		V

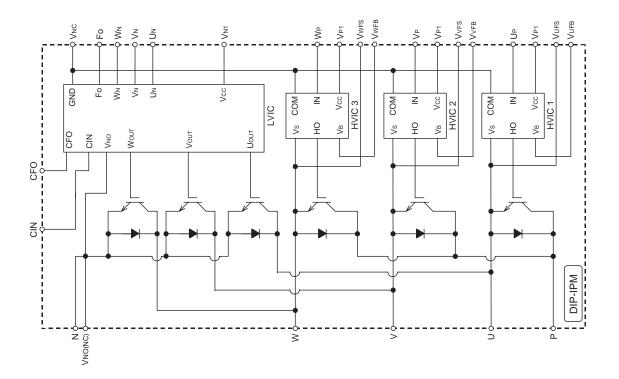
Note 5:





PS21313 TRANSFER-MOLD TYPE INSULATED TYPE

Fig. 4 THE DIP-IPM INTERNAL CIRCUIT



* Note: The IGBTs gates and the HVICs COM terminals are connected to the dummy pins (not shown in Figure 4).

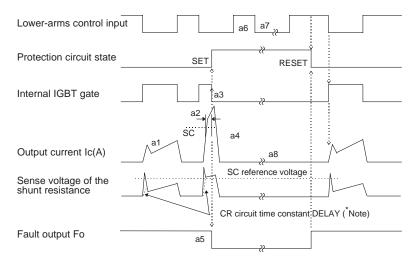


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Fig. 5 TIMING CHARTS OF THE DIP-IPM PROTECTIVE FUNCTIONS

[A] Short-Circuit Protection (Lower-arms only)

- (For the external shunt resistance and CR connection, please refer to Fig. 3.)
- a1. Normal operation : IGBT ON and carrying current.
- a2. Short-circuit current detection (SC trigger).
- a3. IGBT gate interrupt.
- a4. IGBT turns OFF.
- a5. Fo timer operation starts : The pulse width of the Fo signal is set by the external capacitor CFO.
- a6. Input "H" : IGBT OFF state.
- a7. Input "L" : IGBT ON state, but during the Fo active signal the IGBT doesn't turn ON.
- a8. IGBT OFF state.



Note : The CR time constant safe guards against erroneous SC fault signals resulting from di/dt generated voltages when the IGBT turns ON. The optimum setting for the CR circuit time constant is 1.5~2.0μs.

[B] Under-Voltage Protection (N-side, UVD)

- a1. Normal operation : IGBT ON and carrying current.
- a2. Under-voltage trip (UVDt).
- a3. IGBT OFF inspite of control input condition.
- a4. Fo timer operation starts : The pulse width of the Fo signal is set by the external capacitor CFo.
- a5. Under-voltage reset (UVDr).
- a6. Normal operation : IGBT ON and carrying current.

Control input	
Protection circuit state	
Control supply voltage VD UVDr UV	/Dt·····a2 a5
Output current Ic(A)	a3a6
Fault output Fo (N-side only)	a4



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[C] Under-Voltage Protection (P-side, UVDB)

a1. Control supply voltage rises : After the voltage level reachs UVDBr, the circuits start to operate when the next input is applied.
a2. Normal operation : IGBT ON and carrying current.
a3. Under-voltage trip (UVDBI).
a4. IGBT OFF inspite of control input condition (there is no FO signal output).

- a5. Under-voltage reset (UVDBr).
- a6. Normal operation : IGBT ON and carrying current.

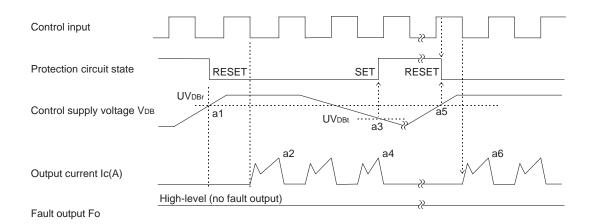
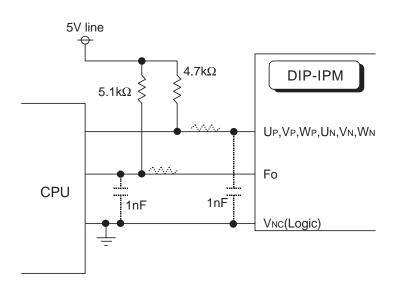


Fig. 6 RECOMMENDED CPU I/O INTERFACE CIRCUIT

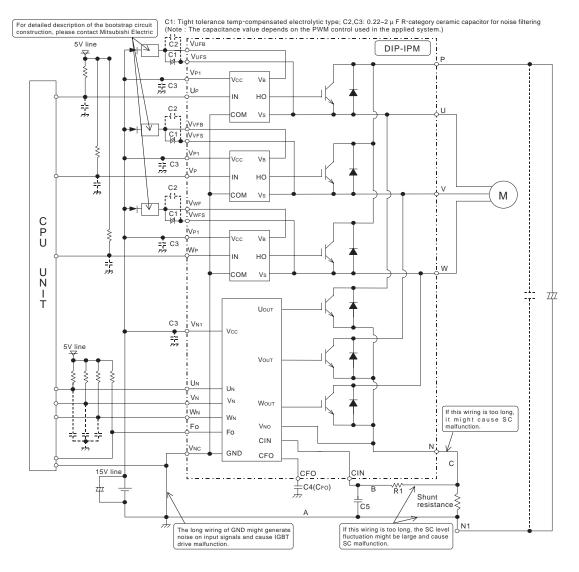


Note : RC coupling at each input (parts shown dotted) may change depending on the PWM control scheme used in the application and on the wiring impedance of the application's printed circuit board.



TRANSFER-MOLD TYPE INSULATED TYPE

Fig. 7 TYPICAL DIP-IPM APPLICATION CIRCUIT EXAMPLE



- Note 1: To prevent the input signals oscillation, an RC coupling at each input is recommended, and the wiring of each input should be as short as possible. (Less than 2cm)
 - 2: By virtue of integrating an application specific type HVIC inside the module, direct coupling to CPU terminals without any opto-coupler or transformer isolation is possible.
 - 3: Fo output is open collector type. This signal line should be pulled up to the positive side of the 5V power supply with approximately 5.1kΩ resistance.
 - 4: Fo output pulse width should be decided by connecting an external capacitor between CFO and VNc terminals (CFO). (Example : CFO = 22 nF \rightarrow tFO = 1.8 ms (typ.))
 - 5: Each input signal line should be pulled up to the positive side of the 5V power supply with approximately 4.7kΩ resistance (other RC coupling circuits at each input may be needed depending on the PWM control scheme used and on the wiring impedances of the system's printed circuit board). Approximately a 0.22~2µF by-pass capacitor should be used across each power supply connection terminals
 - 6: To prevent errors of the protection function, the wiring of A, B, C should be as short as possible.
 7: In the recommended protection circuit, please select the R1C5 time constant in the range of 1.5~2μs.
 8: Each capacitor should be put as nearby the terminals of the DIP-IPM as possible.

 - 9 To prevent surge destruction, the wiring between the smoothing capacitor and the P&N1 terminals should be as short as possible. Approximately a 0.1~0.22μF snubber capacitor between the P&N1 terminals is recommended.

