Special I/O Selection

This section describes the CS1 modules that are specially designed to handle analog, multiple-loop temperature control, Heat/Cool control, PID control, Fuzzy Logic control, single- and multiple-axis position control, multiple-axis motion control, high-speed counting, ID sensor control and voice notification module right on the PLC. All of these modules have independent co-processors to handle the specialized functions to reduce the load on the CPU and keep cycle times extremely fast.

Analog I/O Modules

| Classification | Model | I/O Capacity | I/O Isolation* | I/O Ranges/types | Conversion Time | Remarks | See page |
|------------------------|---------------|------------------------------|-------------------|---|--------------------|---|-------------|
| Analog input units | CS1W-AD041-V1 | 8 inputs | No | 1 to 5 V, 0 to 5 V, 0 to 10 V, ±10 V, 4 to 20 mA | 1 ms/pt | - | C-76 |
| | CS1W-AD081-V1 | 8 inputs | No | 1 to 5 V, 0 to 5 V, 0 to 10 V, ±10 V, 4 to 20 mA | 1 ms/pt | - | C-76 |
| | CS1W-PTW01 | 4 inputs | Yes | 1 to 5 V, 4 to 20 mA | 100 ms/4 pts | Built-in power supply for 2-wire transmission device, measured value alarms (HH, H, L, LL), other features | C-83 |
| | CS1W-PDC01 | 4 inputs | Yes | 1 to 5 V, 0 to 5 V, 0 to 10 V, ±10 V, 4 to 20 mA, 0 to 20 mA | 100 ms/4 pts | Measured value alarms (HH, H, L, LL), other features | C-84 |
| | CS1W-PPS01 | 4 inputs | Yes | No-voltage semiconductor input: 0 to 20,000 pulses/s, Voltage input: 0 to 20,000 pulses/s, Contact input: 0 to 20 pulses/s | 100 ms/4 pts | Built-in power supply, contact bounce filter, 4 instantaneous value alarms | C-84 |
| | CS1W-PTR01 | 8 inputs | No | -1 mA to 1 mA, 0 to 1 mA | 200 ms/8 pts | Motor overdrive prevention, measured value alarms (H, L), other features | C-84 |
| | CS1W-PTR02 | 8 inputs | No | -100 mA to 100 mA, 0 to 100 mV | 200 ms/8 pts | Measured value alarms (H, L), other features | C-82 |
| Analog output units | CS1W-DA041 | 4 outputs | No | 1 to 5 V, 0 to 5 V, 0 to 10 V, ±10 V, 4 to 20 mA | 1 ms/pt | - | C-78 |
| | CS1W-DA08V | 4 outputs | No | 1 to 5 V, 0 to 5 V, 0 to 10 V, ±10 V | 1 ms/pt | - | C-78 |
| | CS1W-DA08C | 4 outputs | No | 4 to 20 mA | 1 ms/pt | _ | C-78 |
| | CS1W-PMV01 | 4 outputs | Yes | 1 to 5 V, 4 to 20 mA | 100 ms/4 pts | Output disconnection alarm, control output answerback input, other features | C-84 |
| Analog I/O unit | CS1W-PMV02 | 4 outputs | Yes | 0 to 10 V, ±10 V, 0 to 5 V, ±5 V, 0 to 1 V, ±1 V | 100 ms/4 pts | - | C-84 |
| | CS1W-MAD44 | 4 inputs and 4 outputs | No | Inputs: 1 to 5 V, 0 to 5 V, to 10 V, ±10 V, 4 to 20 mA Outputs: 1 to 5 V, 0 to 5 V, 0 to 10 V, ±10 V | 1 ms/pt | - | C-80 |
| sensor input units | CS1W-PTS01-V1 | 4 inputs | Yes | B, E, J, K, N, R, S, T, ±80 mVDC auto range | 150 ms/4 pts | Automatic range setting, measured value alarms | C-83 |
| | CS1W-PTS02 | 4 inputs | Yes | Pt100 (JIS, DIN, ISO) JPt100 | 100 ms/4 pts | (HH, H, L, LL), other features | |
| | CS1W-PTS03 | 4 inputs | Yes | Ni508Ω | 100 ms/4 pts | | |
| | C200H-TS001 | 4 inputs | No | K, J | 4.8 s max. | - | C-85 |
| | C200H-TS002 | 4 inputs | No | K, L | 4.8 s max. | - | C-85 |
| | C200H-TS101 | 4 inputs | No | JPt100 | 4.8 s max. | - | C-85 |
| | C200H-TS102 | 4 inputs | No | Pt100 | 4.8 s max. | - | C-85 |

High-resolution Analog I/O Modules

| Classification | Model | I/O Capacity | I/O Isolation* | I/O Convers Ranges/types Time | | Remarks | See page |
|-----------------------|------------|-----------------|-------------------|--|----------------------------|--|-------------|
| Analog input units | CS1W-PTS11 | 4 inputs | Yes | B, E, J, K, L, N, R, S, T, U, WRe5-26, PLII, ±100 mV | 2 ms/4 pts, 10 ms/2 pts | Scaling (±32,000), process value alarms (HH, H, L, LL), other features | C-83 |
| | CS1W-PTS12 | 4 inputs | Yes | Pt100Ω (JIS, IEC), JPt100Ω, Pt50Ω, Ni508.4Ω | 2 ms/4 pts, 10 ms/2 pts | Scaling (±32,000), process value alarms (HH, H, L, LL), other features | C-83 |
| | CS1W-PDC11 | 4 inputs | Yes | 4 to 20 mA, 0 to 20 mA, 0 to 10 V, ±10 V, 0 to 5 V, ±5, 1 to 5 V, 0 to 1.25 V, ±1.25 V | 2 ms/4 pts, 10 ms/2 pts | Scaling (±32,000), process value alarms (HH, H, L, LL), other features | C-83 |

*Note: Inputs are isolated from PLC signals for all units.

Multiple-loop Temperature Control Modules

The temperature control modules are designed for various temperature control applications. The C200H-TC modules have one actuator (heating) and the C200H-TV modules have two actuators (heating/cooling).

Performs complete temperature control and reports results right from the CS1.

- · 2-loop control offers independent settings for each loop.
- · Ideal for zone control in extrusion and heat-treating applications as well as reliable temperature control for multiple processes.
- · Heater burnout detection function for effective diagnostics in critical processes.

| Temperature Control Application | Module | Temperature Sensor Input | Control Output Type | See page |
|------------------------------------|-------------|-------------------------------|------------------------|-------------|
| Heating control | C200H-TC001 | Thermocouples (R, S, K, J, T, | Open-collector (pulse) | C-87 |
| | C200H-TC002 | E, B, N, L or U) | Voltage (pulse) | C-87 |
| | C200H-TC003 | | Current (linear) | C-87 |
| | C200H-TC101 | Platinum resistance | Open-collector (pulse) | C-87 |
| | C200H-TC102 | thermometer (JPt100 and | Voltage (pulse) | C-87 |
| | C200H-TC103 | Pt100) | Current (linear) | C-87 |
| Heating/cooling | C200H-TV001 | Thermocouples (R, S, K, J, T, | Open-collector (pulse) | C-89 |
| control | C200H-TV002 | E, B, N, L or U) | Voltage (pulse) | C-89 |
| | C200H-TV003 | | Current (linear) | C-89 |
| | C200H-TV101 | Platinum resistance | Open-collector (pulse) | C-89 |
| | C200H-TV102 | thermometer (JPt100 and | Voltage (pulse) | C-89 |
| | C200H-TV103 | Pt100) | Current (linear) | C-89 |

PID Control Modules

The PID Control Modules can read analog input variables such as pressure or speed and control them via a 2-channel process controller with a PID (self-tuning) or two-point (ON/OFF) control response.

The Modules have multiple-range inputs (Voltage or Current) and are available with three different types of output.

Scaling and extensive monitoring functions (10 alarm modes) are integrated.

| Module | Analog Input Type | Control Output Type | See page |
|-------------|-----------------------|------------------------|----------|
| C200H-PID01 | 4 to 20 mA, 1 to 5 V, | Open-collector (pulse) | C-91 |
| C200H-PID02 | 0 to 5 V or 0 to 10 V | Voltage (pulse) | C-91 |
| C200H-PID03 | | Current (linear) | C-91 |

Single- and Multiple-axis Position Control Modules

The position control modules for the CS1 series have been developed for precise positioning on pick and place machines and for the use of cutting equipment and positioning systems.

Servo or stepper systems that accept pulse-train inputs can be controlled with these modules.

Configure a complete system by combining these parts:

- Position control module (CS1W-NC□□□)
- Omron SMARTSTEP or W-Series servo drive or any manufacturer's servo/stepper drive.

| Module | Output | Controlled Axes | See page |
|------------|----------------|-----------------|----------|
| CS1W-NC113 | Open collector | 1 Axis | C-97 |
| CS1W-NC213 | | 2 Axis | C-97 |
| CS1W-NC413 | | 4 Axis | C-97 |
| CS1W-NC133 | Line driver | 1 Axis | C-97 |
| CS1W-NC233 | | 2 Axis | C-97 |
| CS1W-NC433 | | 4 Axis | C-97 |

Motion Control Modules

The motion control modules for the CS1 series have been developed for precise positioning, as is necessary in pick and place machines and positioning systems. Up to four axes can be controlled dependently or independently of one another.

The new high-performance motion controller CS1W-MCH71 can also handle up to 30 axes over an electronic high-speed 10 Mbps bus and also perform electronic gear functions.

| Module | Controlled Axes | Electronic Gear Functions | See page |
|------------|-----------------|---------------------------|---|
| CS1W-MC221 | 2 max. | No | C-99 |
| CS1W-MC421 | 4 max. | No | C-99 |
| CS1W-MCH71 | 30 max. | Yes | Go to www.omron.com/oei, type CS1W-MCH71 in "Site Search" for more information. |

High-Speed Counter Modules

The high-speed counter modules count pulse signal inputs that are too fast to be detected by normal input units.

| Module | Max. Input Frequency | Input Voltage | Number of Counters | Remarks |
|------------|--|---------------------------------------|--------------------|---|
| CS1W-CT021 | 50 kHz - 500 kHz with line driver input | 5, 12 , 24 VDC and RS-422 line driver | 2 | - |
| CS1W-CT041 | 50 kHz - 500 kHz with line driver input | 5, 12 , 24 VDC and RS-422 line driver | 4 | - |
| CS1W-HCP22 | 50 kHz - 200 kHz with line driver input | 5, 12 , 24 VDC and RS-422 line driver | 2 | Programmable unit with PLC functionality and 2 pulse outputs |
| CS1W-HCA22 | 50 kHz - 200 kHz with line driver input | 5, 12 , 24 VDC and RS-422 line driver | 2 | Programmable unit with PLC functionality and 2 analog outputs |
| CS1W-CTS21 | 1.5 MHz | RS-422/485 | 2 | SSI (Synchronous Serial Interface) encoder inputs |

Cam Positioner Module

The cam positioner module is an electronic high-speed drum counter operating like 48 mechanical cams. Angles are detected with an externally connected resolver.

| Module Number of Cam Outputs | | Resolver Response Speed | See page |
|------------------------------|----|-------------------------|----------|
| C200H-CP114 | 48 | 800 r/min max. | C-95 |

ID Sensor Modules

The ID sensor modules interface with the V600-series RFID (Radio Frequency Identification) system for high-speed communications between the CPU unit and data carriers (Radio Frequency Tags).

| Module | Number of R/W Heads | See page |
|--------------|---------------------|----------|
| CS1W-V600C11 | 1 | C-107 |
| CS1W-V600C12 | 2 | C-107 |

Voice Module

The voice module provides audible message notification of system condition or alarms.

| Module | Message Capacity | See page | |
|-------------|------------------|----------|--|
| C200H-OV001 | 60 messages | C-110 | |

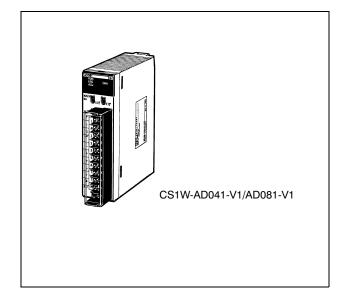
Configuration Guidelines

Remember to add all the current consumptions of basic I/O, special I/O modules, and CPU bus units to determine which power supply is appropriate.

Please refer to the System Configuration section for current consumption of individual modules.

For more I/O options, see the Industrial Networks and Communication section for DeviceNet I/O on page C-123 and CompoBus/S I/O on page C-138.

Analog Input Modules

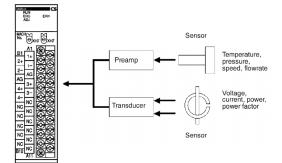


Convert input signals such as 1 to 5 V or 4 to 20 mA to binary values between 0000 and 0FA0 Hex and store the results in the allocated words each cycle. The ladder diagram can be used to transfer the data to the DM Area or the Scaling instructions (e.g, SCL(194)) can be used to scale the data to the desired range.

Features

- Wire burnout detection.
- Peak-hold function.
- Mean function.
- Offset gain setting.
- **Note:** Analog Input Terminals are also available as DeviceNet Slaves and for Multiple I/O Terminals. Find more information in the Industrial Networking and Communications section of this catalog.

System Configuration



Terminal Arrangement

CS1W-AD041-V1 CS1W-AD041

CS1W-AD08 CS1W-AD08

| | | A1 | Input 1 (+) |
|-------------|-------------|------|-------------|
| Input 2 (+) | B1 | | , |
| Input 2 () | B2 | A2 | Input 1 (-) |
| AG | B3 | A3 | AG |
| | | A4 | Input 3 (+) |
| Input 4 (+) | B4 | A5 | Input 3 () |
| Input 4 (-) | B5 | A6 | N.C. |
| N.C. | B6 | | |
| N.C. | B7 | A7 | N.C. |
| | B8 | A8 | N.C. |
| N.C. | | A9 | N.C. |
| N.C. | B9 | A10 | N.C. |
| N.C. | B 10 | 7.10 | |
| | | A11 | N.C. |

| 1-V1 | | | | |
|------|-------------|-----|-----|-------------|
| 1 | land 0 (a) | | A1 | Input 1 (+) |
| | Input 2 (+) | B1 | A2 | Input 1 () |
| | Input 2 (-) | B2 | | |
| | AG | B3 | A3 | AG |
| | | | A4 | Input 3 (+) |
| | Inpul 4 (+) | B4 | A5 | Input 3 (-) |
| | Input 4 (-) | B5 | A6 | |
| | Input 6 (+) | B6 | | Input 5 (+) |
| | Imput C () | B7 | A7 | Input 5 () |
| | Input 6 () | _ | A8 | AG |
| | AG | B8 | A9 | Input 7 (+) |
| | Input 8 (+) | B9 | | |
| | Input 9 () | B10 | A10 | Input 7 (–) |
| | Input 8 (-) | BIU | A11 | N.C. |
| | | | ~~~ | 11.0. |

Analog Input Modules

Specifications

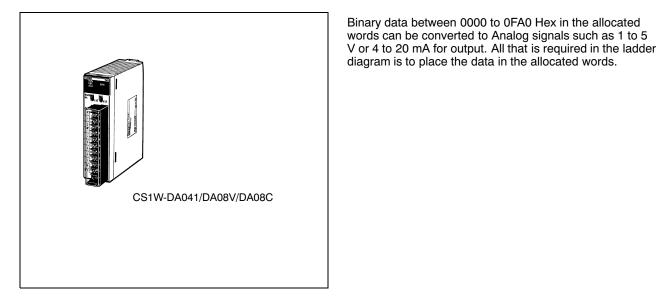
| Model | | | CS1W-AD041-V1 | CS1W-AD081-V1 | | |
|----------------------------|-------------|----------------------------------|---------------------------------|---------------------------------|--|--|
| Classification | | | CS1 Special Modules | CS1 Special Modules | | |
| Module number | | | 0 to 95 | 0 to 95 | | |
| Inputs | | | 4 pts | 8 pts | | |
| Signal range | Voltages | 1 to 5 V | Yes | | | |
| | | 0 to 10 V | Yes | | | |
| | | 0 to 5 V | Yes | | | |
| | | -10 to 10 V | Yes | | | |
| | Currents | | Yes | | | |
| | | 0 to 20 mA | | | | |
| Signal range setting | gs | 1 | 4 settings (one for each point) | 8 settings (one for each point) | | |
| Resolution | | | 1/4000 (1/8000) | | | |
| Conversion speed | | | 1 ms/pt max. (0.25 ms/pt max.) | 1 ms/pt max. (0.25 ms/pt max.) | | |
| Overall accuracy (at 25°C) | | Voltage: ±0.2% Current: ±0.4% | | | | |
| Connections | | | Terminal block | Terminal block | | |
| Features | Wire burnou | ut detection | Yes | Yes | | |
| | Peak-hold f | unction | Yes | Yes | | |
| | Mean functi | on | Yes | Yes | | |

Note: 1. The C200H-AD001/AD002/AD003 can also be used with the CS1.

2. Process I/O Modules are also available for analog I/O.

3. For more details and information refer to manual no. W345.

Analog Output Modules



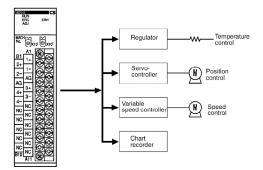
Features

- Output limit.
- Upper/lower limit alarms.
- Offset gain adjustment.

Note: 1. The functions provided depend on the model used.

 Analog Output Terminals are also available as DeviceNet Slaves and for Multiple I/O Terminals. You can find more information in the Industrial Networking and Communication section of this catalog.

System Configuration



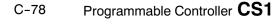
Terminal Arrangement

CS1W-DA08V/08C

| 31 32 33 34 | A2 A3 A4 | Output 1 (+) Output 1 (–) |
|----------------------|----------------------|--|
| 33 | A3 | , |
| | | Output 1 (-) |
| | Δ.4 | |
| | 114 | Output 3 (+) |
| | A5 | Output 3 (-) |
| 35 | | , |
| 36 | | Output 5 (+) |
| 27 | A7 | Output 5 (-) |
| | A8 | Output 7 (+) |
| 38 | A9 | Output 7 (-) |
| 39 | | |
| B10 | A10 | N.C. |
| 510 | A11 | N.C. |
| | 35 36 37 38 | A5 36 36 37 37 38 48 A7 38 A9 39 A10 310 |

CS1W-DA041

| | | A1 | N.C. |
|----------------------|-----|-----|----------------------|
| N.C. | B1 | A2 | |
| Output voltage 2 (+) | B2 | AZ | Output voltage 1 (+) |
| Output 2 (-) | B3 | A3 | Output 1 (–) |
| 1 () | | A4 | Output current 1 (+) |
| Output current 2 (+) | B4 | A5 | N.C. |
| N.C. | B5 | | |
| NC | B6 | A6 | N.C. |
| | | A7 | Output voltage 3 (+) |
| Output voltage 4 (-) | B7 | A8 | Output 3 () |
| Output 4 (-) | B8 | | , |
| 0.1.1.1 | В9 | A9 | Output current 3 (+) |
| Output current 4 (+) | | A10 | N.C. |
| N.C. | B10 | | |
| - | | A11 | N.C. |



Analog Output Modules

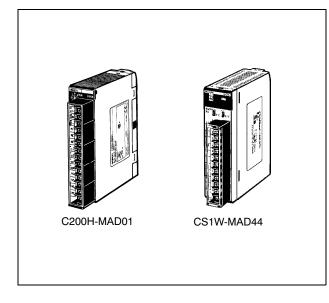
Specifications

| Model | | CS1W-DA041 | CS1W-DA08V | CS1W-DA08C | | | | |
|----------------------------|-------------------------|--|---------------------------------|----------------|-----|--|--|--|
| Classification | | CS1 Special I/O Modules | CS1 Special I/O Modules | | | | | |
| Module numbers | | | 0 to 95 | 0 to 95 | | | | |
| Outputs | | 4 pts | 4 pts 8 pts | | | | | |
| Signal | Voltages | 1 to 5 V | Yes | | | | | |
| range | | 0 to 10 V | Yes | | | | | |
| | 0 to 5 V -10 to 10 V | | Yes | Yes | | | | |
| | | | Yes | Yes | | | | |
| Currents | 4 to 20 mA | Yes | Yes | | | | | |
| | | 0 to 20 mA | | | | | | |
| Signal rar | nge settings | | 4 settings (one for each point) | | | | | |
| Resolutio | n | | 1/4000 | 1/4000 | | | | |
| Conversio | on speed | | 1.0 ms/pt max. | 1.0 ms/pt max. | | | | |
| Overall accuracy (at 25°C) | | Voltage: ±0.3% FS Current: ±0.5% FS | ±0.3% FS | ±0.5%FS | | | | |
| Connections | | Terminal block | Terminal block | | | | | |
| Features | Output hole | d function | | Yes | Yes | | | |

Note: 1. The C200H-DA001/DA002/DA003/DA004can also be used with the CS1.

2. Process I/O Modules are also available for analog I/O.

Analog I/O Modules

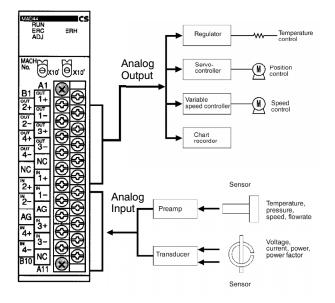


One Module performs both analog input and analog output operations. The Module can also be used for ratio and bias processing, which can be performed on analog inputs to output the results as analog outputs.

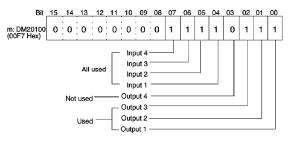
Features

- Mean Function.
- Peak hold function.
- Wire burnout detection.
- Output hold function.
- Ratio conversions.

System Configuration



Terminal Arrangement



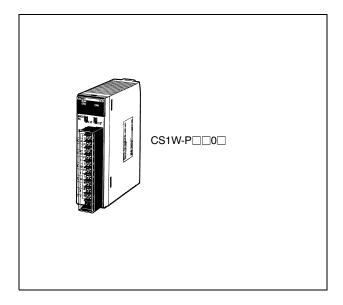
Note: For Terminal arrangement of C200H-MAD01 refer to manual W325.

Analog I/O Modules

Specifications

| Model | | | C200H-MAD01 | CS1W-MAD44 | | | |
|------------------------|-------------|---------------|----------------------------------|---------------------------------------|--|--|--|
| Classificat | ion | | C200H Special I/O Modules | CS1 Special I/O Modules | | | |
| Module numbers | | | 0 to F | 0 to 95 | | | |
| Inputs | | | 2 pts | 4 pts | | | |
| Outputs | | | 2 pts | 4 pts | | | |
| Input | | | Yes | Yes | | | |
| signal range | | 0 to 5 V | | Yes | | | |
| - | | 0 to 10 V | Yes | · · · · · · · · · · · · · · · · · · · | | | |
| | | -10 to 10 V | Yes | | | | |
| | | 4 to 20 mA | Yes | | | | |
| Output | Currents | 1 to 5 V | Yes | | | | |
| signal range | | 0 to 5 V | | Yes | | | |
| - | | 0 to 10 V | Yes | | | | |
| | | -10 to 10 V | Yes | | | | |
| | | 4 to 20 mA | Yes | | | | |
| Resolution | | | 1/4000 (inputs/outputs) | | | | |
| Conversion | n speed | | 1.0 ms/pt max. (Inputs/ouputs) | | | | |
| Overall accuracy | Inputs | | Voltage: ±0.2% Current: ±0.4% | | | | |
| | Outputs | | Voltage: ±0.3% Current: ±0.5% | | | | |
| Connectio | ns | | Terminal block | | | | |
| Features Mean function | | tion | Yes | | | | |
| Peak hold | | | Yes | Yes | | | |
| | Wire burnc | out detection | Yes | Yes | | | |
| | Output hole | d | Yes | | | | |
| | Ratio conv | ersion | Yes | | | | |

Process I/O Modules



Features

Process Modules

- External converters and transducers not required: greatly reduces costs, space requirements, and labor.
- Input temperatures and use measured value alarms and disconnection alarms.
- Input analog currents and voltages and output square root and input error detection.
- Input pulse signals from capacitive flow sensors and output either accumulated or instantaneous values.
- For control outputs, use output disconnected detection, output rate-of-change limits, and high/low output limits.

Temperature Sensor Modules

- Input directly from up to four temperature sensors with one Module. The types of temperature sensor and temperature ranges can be set separately for each input.
- Models available with isolated inputs to prevent unwanted current flow between temperature sensor inputs.
- Provided with measured value alarms (4 points each).
- Line disconnection detection provided.

Choose from a total of 13 models, including 11 isolatedtype models, to handle essentially all nornal processing applications. Meet a wide variety of monitoring needs with variable range setting, output scaling, rate-of-change operation and alarm, and many other features.

Process I/O Modules

Specifications

| Module name | Model | I/O capacity | Field I/O isolation | I/O range/type | Accuracy/effective resolution | Main features |
|--|---------------|-----------------|----------------------|---|---|--|
| Isolated-type Thermocouple Input Module (high-resolution) | CS1W-PTS11 | 4 inputs | All inputs isolated. | B, E, J, K, L, N, R, S, T, U, WRe5-26, PLII, ±100 mV | Standard accuracy: ±0.05% full scale Temp coefficient: ±0.005%/°C Resolution: 1/64,000 Conversion cycle: 20 ms/4 pts, 10 ms/2 pts | Scaling (±32,000), Process value alarms (HH, H, L, LL), rate-of-change calculation and alarms, input discon- nection alarms, top, bottom, valley hold, variable range zero- span adjustment |
| Isolated-type Temperature Resistance Thermometer Input Module (high-resolution) | CS1W-PTS12 | 4 inputs | All inputs isolated. | Pt100 Ω (JIS, IEC), JPt100 Ω, Pt50 Ω, Ni508.4 Ω | Standard accuracy: The larger of $\pm 0.05\%$ full scale or $\pm 0.01\%^{\circ}$ C Temp coefficient: $\pm 0.001\%'^{\circ}$ C Resolution: 1/64,000 Conversion cycle: 20 ms/4 pts, 10 ms/2 pts | Scaling (±32,000), Process value alarms (HH, H, L, LL), rate-of-change calculation and alarms, input discon- nection alarms, top, bottom, valley hold, Variable range zero- span adjustment |
| Isolated-type Analog Input Module (high-resolution) | CS1W-PDC11 | 4 inputs | All inputs isolated. | 4 to 20 mA, 0 to 20 mA, 0 to 10 V, ±10 V, 0 to 5 V, ±5 V, 1 to 5 V, 0 to 1.25 V, ±1.25 V | Standard accuracy: ±0.05% full scale Temp coefficient: ±0.005%/°C Resolution: 1/64,000 Conversion cycle: 20 ms/4 pts, 10 ms/2 pts | Scaling (±32,000), Process value alarms (HH, H, L, LL), rate-of-change calculation and alarms, input discon- nection alarms, top, bottom, valley hold, accumulated value output variable range zero-span ad- justment |
| Isolated-type Thermocouple Input Module | CS1W-PTS01-V1 | 4 inputs | All inputs isolated. | B, E, J, K, N, R, S, T, ±80 mVDC variable range | Standard accuracy: ±0.1% full scale Temp coefficient: ±0.015%/°C Resolution: 1/4,096 | Variable range set- ting, output scaling (±32,000), measured value alarms (HH, H, L, LL), rate-of- change operation and alarms, input disconnection alarms |
| Isolated-type Temperature- resistance Thermometer Input Module (Pt100) | CS1W-PTS02 | 4 inputs | All inputs isolated. | Pt100 (JIS, IEC) JPt100 | Standard accuracy: Larger of ±0.1% or ±0.1°C full scale Temp coefficient: ±0.015%/°C Resolution: 1/4,096 | Variable range set- ting, output scaling (±32,000), measured value alarms (HH, H, L, LL), rate-of- change operation |
| Isolated-type Temperature- resistance Thermometer Input Module (Ni508.4 Ω) | CS1W-PTS03 | 4 inputs | All inputs isolated. | Ni508.4Ω | Standard accuracy: Larger of ±0.2% or ±0.2°C full scale Temp coefficient: ±0.015%/°C Resolution: 1/4,096 | and alarms, input disconnection alarms |
| Isolated-type Two-wire Transmission Device Input Module | CS1W-PTW01 | 4 inputs | All inputs isolated. | 4 to 20 mA, 1 to 5 V | Standard accuracy: ±0.2% full scale Temp coefficient: ±0.015%/°C Resolution: 1/4,096 | Built-in power supply for 2-wire transmis- sion device output scaling (±32,000), measured value alarms (HH, H, L, LL), rate-of-change operation and alarms, input discon- nection alarms |

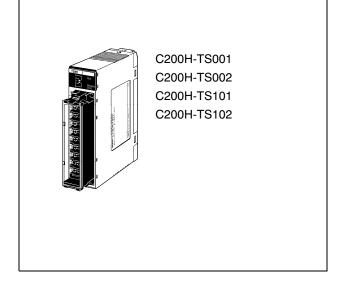
(This table continues on the next page.)

Special I/O Modules Process I/O Modules

Specifications (continued)

| Module name | Model | I/O capacity | Field I/O isolation | I/O range/type | Accuracy/effective resolution | Main features |
|---|------------|-----------------|---|---|---|--|
| Isolated-type Analog Input Module | CS1W-PDC01 | 4 inputs | All inputs isolated. | ±10 V, 0 to 10 V, ± 5 V, 0 to 5 V, 1 to 5 V, ±10 VDC variable range, 4 to 20 mA, 0 to 20 mA | Standard accuracy: ±0.1% full scale Temp coefficient: ±0.015%/°C Resolution: 1/4,096 | Output scaling (±32,000), measured value alarms (HH, H, L, LL), rate-of- change operation and alarms, square root, input error alarms |
| Isolated-type Pulse Input Module | CS1W-PPS01 | 4 inputs | All inputs isolated. | Max. counting speed: 20 K pulses/s (voltage input or no- voltage semi-con- ductor input) or 20 pulses/s (contact input) | | Built-in sensor power supply, con- tact bounce filter, Module pulse con- version, accumula- tive and instanta- neous value output, 4 instantaneous value alarms. |
| Isolated-type Control Output Module | CS1W-PMV01 | 4 outputs | All outputs isolated. | 4 to 20 mA, 1 to 5 V | Standard accuracy: 4 to 20 mA: ±0.1% full scale 1 to 5 V: ±0.2% full scale Temp coefficient: ±0.015%/°C 4,000 (outputs) | Output disconnec- tion alarms, control output answerback input, output rate-of- change limit, output high/low limits |
| Isolated-type Power Voltage Output Module | CS1W-PMV02 | 4 outputs | All outputs isolated | 0 to 10 V, ±10 V, 0 to 5 V, ±5 V, 0 to 1 V, ±1 V | | |
| Power Transducer Input Module | CS1W-PTR01 | 8 inputs | No isola- tion between inputs. | ±1 mA, 0 to 1 mA | Standard accuracy: ±0.2% full scale Temp coefficient: ±0.015%/°C Resolution: 1/4,096 | Motor overdrive pre- vention at startup, output scaling (±32,000), measured value alarms (H, L) |
| Analog Input Module | CS1W-PTR02 | 8 inputs | No isola- tion between inputs. | ±100 mV, 0 to 100 mV | Standard accuracy: ±0.2% full scale Temp coefficient: ±0.015%/°C Resolution: 1/4,096 | Output scaling (±32,000), measured value alarms (H, L) |

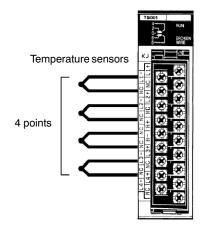
Temperature Sensor Modules



Features

- Input directly from up to four temperature sensors of the same kind with one range setting.
- Analog-digital conversion speed ideal for slower processes: 4.8 seconds max. for 4 points.
- Line disconnection detection provided.
- **Note:** Temperature sensor terminals are also available on DeviceNet slave. Further information is available on these in the CS1 Industrial Networking and communications section of this catalog.

System Configuration



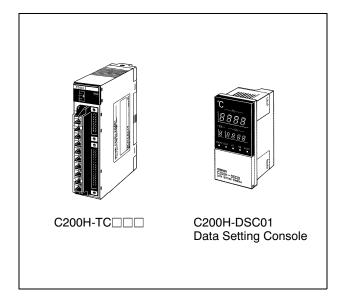
Using Input from thermocouples or resistance thermometers (up to 4 inputs) the Module converts the measured temperatures into BCD or binary data and stores them in the allocated relay area every cycle. The data can be transerred to the DM area or other memory locations using the ladder program.

Special I/O Modules Temperature Sensor Modules

Specifications

| Model | | | C200H- TS001 | C200H- TS002 | C200H- TS101 | C200H- TS102 | |
|------------------|---------------------|---------------------------|--|-----------------|-----------------|-----------------|--|
| Classification | | C200H Special I/O Modules | | | | | |
| Module numbers | | 0 to 9 | 0 to 9 | 0 to 9 | 0 to 9 | | |
| Inputs | | | 4 pts | 1 | | | |
| Input signals | Input Thermocouples | К | Yes | Yes | | | |
| signals | | J | Yes | | | | |
| | | L | | Yes | | | |
| | | R | | | | | |
| | | S | | | | | |
| | | Т | | | | | |
| | | E | | | | | |
| | | В | | | | | |
| | | Ν | | | | | |
| | | W | | | | | |
| | | U | | | | | |
| | | PLII | | | | | |
| | | ±80 mV | | | | | |
| | Resistance | JPt100 | | | Yes | | |
| | thermometers | PT100 | | | | Yes | |
| | | Ni508.4Ω | | | | | |
| Input sign | nal range settings | | One setting for all 4 pts | | | | |
| A/D conv | ersion output data | | 4-digit BCD | | | | |
| Conversi | on speed | | 4.8 s max. (when 4 pts are set for Module) | | | | |
| Overall a | | | ±1% + 1°C | | | | |
| Connecti | ons | | Terminal block | | | | |

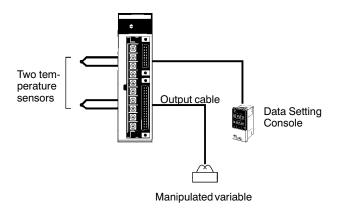
Temperature Control Modules



Features

- Supports 2-loop PID control (two degrees of freedom) or ON/OFF control.
- Input directly from two temperature sensors (thermocouples: R, S, K, J, T, E, B, N, L, or U) or platinum resistance thermometers (JPt00, Pt100).
- Open-collector, voltage, or current outputs .
- Sampling period: 500 ms.
- Run/start control.
- Two internal alarms per loop.
- Detects heater burnout through current detectors for both loops.
- Record up to eight sets of target values, alarm values and PID parameters.
- Connects to Data Setting Console.

System Configuration



Perform 2-loop PID control (two degrees of freedom) based on inputs from thermocouples or platinum resistance thermometers to control a transistor, voltage or current output. Words allocated to the Module in memory can be maipulated from the ladder diagram to start/stop operation, set the target value, read the process value, or perform other operations.

Special I/O Modules Temperature Control Modules

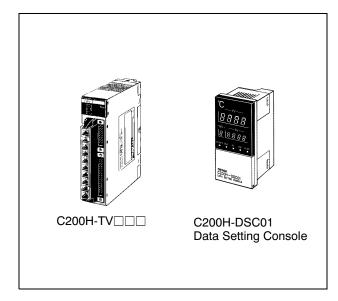
Specifications

| Classification | Temperature sensor inputs | Control outputs | Module numbers | Model |
|--------------------------|---------------------------|------------------------|-------------------|-------------|
| C200H Special I/O Module | | Open-collector (pulse) | 0 to 9 | C200H-TC001 |
| | T, E, B, N, L, or U) | Voltage (pulse) | | C200H-TC002 |
| | | Current (linear) | | C200H-TC003 |
| | Platinum resistance ther- | Open-collector (pulse) | | C200H-TC101 |
| | mometers (JPt00, Pt100) | Voltage (pulse) | | C200H-TC102 |
| | | Current (linear) | | C200H-TC103 |

Data Setting Console

| Specifications | Model |
|--|-------------|
| Monitoring, setting, and changing present values, set points, alarm values, PID parameters, bank numbers, etc. | C200H-DSC01 |

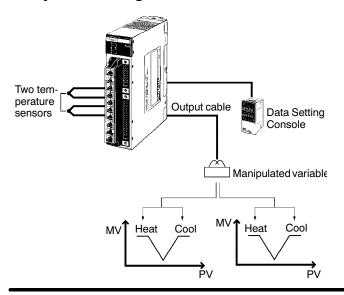
Heat/Cool Control Module



Features

- Supports 2-loop PID control (two degrees of freedom) or ON/OFF control.
- Input directly from two temperature sensors (thermocouples: R, S, K, J, T, E, B, N, L, or U) or platinum resistance thermometers (JPt00, Pt100).
- Open-collector, voltage, or current outputs.
- Sampling period: 500 ms.
- Run/start control.
- Two internal alarms per loop.
- Detects heater burnout through current detectors for both loops.
- Record up to eight sets of set points, alarm values and PID parameters.
- Connects to Data Setting Console.

System Configuration



Perform 2-loop PID control (two degrees of freedom) based on inputs from thermocouples or platinum resistance thermometers to control a transistor, voltage or current output. Words allocated to the Module in memory can be manipulated from the ladder diagram to start/stop operation, set the target value, read the process value, or perform other operations.

Special I/O Modules Heat/Cool Control Module

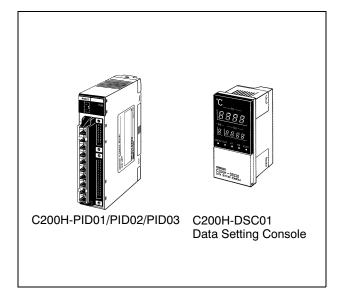
Specifications

| Classification | Temperature sensor inputs | Heating control output | Cooling control output | Module numbers | Model |
|--|--|---------------------------|---------------------------|----------------|-------------|
| C200H Special I/O Module | Thermocouples (R, S, K, J, T, E, B, N, L, | Open-collector (pulse) | Open-collector (pulse) | 0 to 9 | C200H-TV001 |
| | or U) | Voltage (pulse) | | | C200H-TV002 |
| | | Current (linear) | | C200H-TV003 | |
| Platinum resistance thermometers (JPt00, Pt100) | resistance | Open-collector (pulse) | | | C200H-TV101 |
| | | Voltage (pulse) | | | C200H-TV102 |
| | | Current (linear) | | | C200H-TV103 |

Data Setting Console

| Specifications | Model |
|--|-------------|
| Monitoring, setting, and changing present values, set points, alarm values, PID parameters, bank numbers, etc. | C200H-DSC01 |

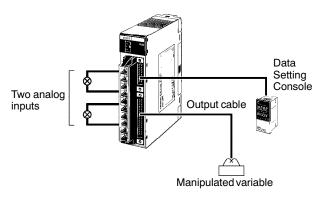
PID Control Modules



Features

- Supports 2-loop PID control (two degrees of freedom) or ON/OFF control.
- Directly input analog signal.
- Open-collector, voltage, or current outputs.
- Sampling period: 100 ms.
- · Run/start control.
- Manual outputs supported.
- Set two internal alarms per loop.
- Record up to eight sets of target values, alarm values and PID parameters.
- Digital filters can be set to dampen rapid changes in inputs.
- Connects to Data Setting Console.

System Configuration



Perform 2-loop PID control (two degrees of freedom) based on input ranges such as 4 to 20 mA or 1 to 5 V to control transistor, voltage, or current outputs. Words allocated to the Module in memory can be manipulated from the ladder diagram to start/stop operation, set the set point, read the process value, or perform other operations.

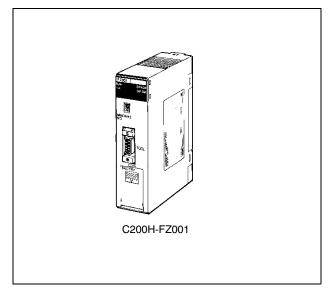
Specifications

| Classifications | Temperature sensor input | Control output | Module numbers | Model |
|-------------------|--------------------------|------------------------|----------------|-------------|
| C200H Special I/O | 4 to 20 mA, 1 to 5 V, | Open-collector (pulse) | 0 to 9 | C200H-PID01 |
| Module | 0 to 5 V or 0 to 10 V | Voltage (pulse) | | C200H-PID02 |
| | | Current (linear) | | C200H-PID03 |

Data Setting Console

| Specifications | Model |
|--|-------------|
| Monitoring, setting, and changing present values, set | C200H-DSC01 |
| points, alarm values, PID parameters, bank numbers, etc. | |

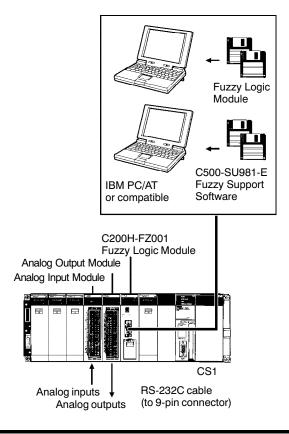
Fuzzy Logic Module



Features

- Contains a high-performance fuzzy logic processor for high-speed fuzzy processing.
- Handles jobs that used to be performed by using the experience of skilled operators.
- Eight inputs and 4 ouputs .
- 8 conditions and 2 conclusions per rule, 128 rules total.

System Configuration



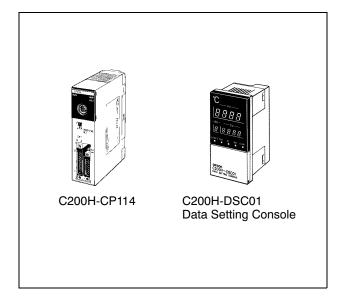
Use the Fuzzy Support software to create rules, membership functions, and other fuzzy data and transfer them to the Module after checking the knowledge. The ladder program in the CPU can be used to set fuzzy inputs for processing by the Fuzzy Logic Module and then the results can be read using the ladder program.

Special I/O Modules Fuzzy Logic Module

Specifications

| Classific | Model | Fuzzy logic | | Inputs | | Outputs | | Module | Processin |
|-----------------------------------|-------------|--------------------------------|-------|-----------------|-----------|-----------------|-----------|---------|---|
| ation | | Rule form | Rules | Data | FS range | Data | FS range | numbers | g time |
| C200H Special I/O Module | C200H-FZ001 | 8 conditions and 2 conclusions | 128 | 8 words max. | 0 to 4095 | 4 words max. | 0 to 4095 | 0 to 9 | 6 ms max. for Mod- ule, 3 to 4 times the cycle time for system |

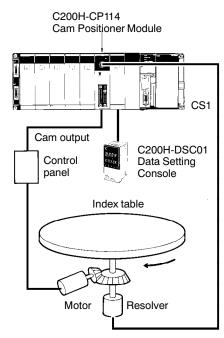
Cam Positioner Module



Features

- Supports 16 external ouputs and 32 internal outputs for a total of 48 cam ouputs.
- Set up to seven ON/OFF data points for each cam.
- The data setting console allows easy monitoring of cam data settings, preset cam angles, or etc.
- An adjustment operation function enables setting cam outputs while actually operating the controlled machine.

System Configuration



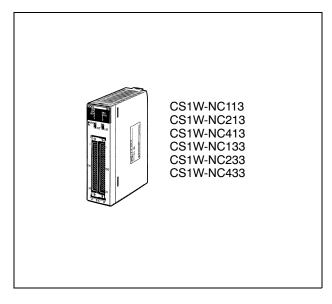
Simulate the control functions of 48 mechanical cams to increase machine reliability and simplify setup. Angles are detected through an externally connected resolver (3F88L-RSDD angle detector) and cam ouputs are produced for preset ON/OFF angle data.

Special I/O Modules Cam Positioner Module

Specifications

| Classification | Model | No. of cam outputs | Control Module | Resolver response speed | Module numbers | Resolver response time |
|-----------------------------|-------------|--|-------------------|----------------------------|-------------------|---------------------------------------|
| C200H Special I/O Module | C200H-CP114 | 48 (16 external out- puts, 32 internal outputs) | 1° | 800 r/min max. | 0 to 9 | 200 μs (sampling frequency: 5 kHz) |

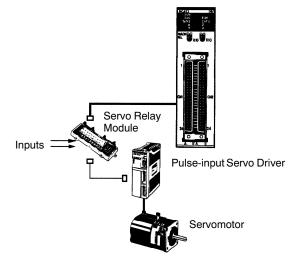
Position Control Modules



Features

- Simple positioning systems can be created by directly specifying operation from the CPU when required.
- Positioning data is saved in interal flash memory, eliminating the need to maintain a back up battery.
- Use CX-Position Windows-based support software to easily create positioning data and store data and parameters in files.
- Interrupt feeding, forced starting, and other features also supported.

System Configuration



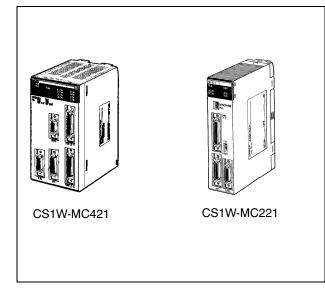
These position control Modules support open-loop control with pulse-train ouputs. Position using automatic trapezoid or S-curve acceleration and deceleration. Models available with 1, 2, or 4 axes. Use in combination with servomotors or stepping motors that accept pulse-train inputs.

Special I/O Modules Position Control Modules

Specifications

| Model | CS1W-NC113 CS1W-NC133 | CS1W-NC213 CS1W-NC233 | CS1W-NC413 CS1W-NC433 | | |
|--------------------------------------|--|--------------------------------------|--------------------------|--|--|
| Module name | Position Control Module | Position Control Module | | | |
| Classification | CS1 Special I/O Modules | | | | |
| Module numbers | 0 to 95 | | | | |
| Control method | Open-loop, automatic trape | ezoid acceleration/deceleration | | | |
| Control output signals | CS1W-NC□13: Open-colle CS1W-NC□33: Line-drive | | | | |
| Controlled axes | 1 | 2 | 4 | | |
| Operating modes | Direct operation or memory | Direct operation or memory operation | | | |
| Data format | Binary (hexadecimal) | Binary (hexadecimal) | | | |
| Affect on scan time for end refresh | 0.29 to 0.41 ms max./Modu | le | | | |
| Affect on scan time for IOWR/IORD | 0.6 to 0.7 ms max./instruct | 0.6 to 0.7 ms max./instructions | | | |
| Startup time | 2 ms min. (Refer to operati | on manual for conditions.) | | | |
| Position data | -1,073,741,823to +1,073,7 | 741,823 pulses | | | |
| No. of positions | 100 per axis | | | | |
| Speed data | 1 to 500 kpps (in 1-pps Mo | dules) | | | |
| No. of speeds | 100 per axis | | | | |
| Acceleration/ deceleration times | 0 to 250 s (time to max. speed) | | | | |
| Acceleration/ deceleration curves | Trapezoidal or S-curve | | | | |
| Saving data in CPU | Flash memory | | | | |
| Windows-based Support Software | CX-Position | | | | |

Motion Control Module



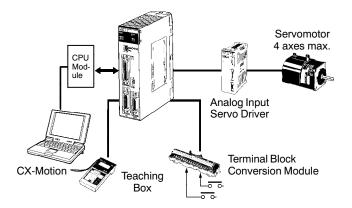
Features

- High-speed control of up to 4 axes with one Module and up to 76 axes with one PLC (19 Modules x 4 axes. Assumes that power supply Module capacity is not exceeded.).
- Winding operations easily controlled at high-speed using traverse positioning control.
- High-speed response to commands from CPU (8 ms for 2 axes, 13 ms for 4 axes).
- Encoder response of 2 Mpps possible with 4x frequency multiplication for applications with high-speed, high-precision servomotors.
- D interrupt code outputs to CPU at end of positioniong or at specified positions (D code output time: 3.3 ms max.)
- CX-Motion Windows-based support software: Define user mnemonics to use in place of G codes to simplify motion control program development and analysis.
- Servo trace function from CX-Motion to trace error counter changes or motor speeds.
- Automatic loading function: Motion control programs and positioning data can be automatically downloaded from computer memory when required by the MC Module.

The motion controller provides semiclosed-loop control with analog ouputs for up to 4 axes, and supports the G language for advanced, high-speed, high precision position control, such as traverse operations. Multi-tasking allows you to run the two axes independently for a wider range of applications.

Motion Control Module

System Configuration



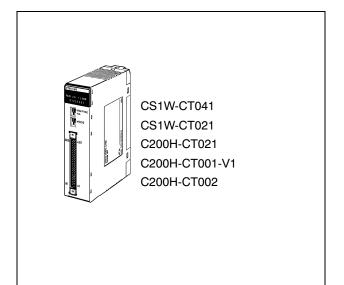
Specifications

| | Model | CS1W-MC421 | CS1W-MC221 | | | |
|----------------------------------|-----------------------|---|--|--|--|--|
| Classification | | CS1 Special I/O Module | | | | |
| Control method | b | Semiclosed loop with automatic trapezoid or S-curve acceleration/deceleration | | | | |
| Control output | signals | Analog | | | | |
| Internal progra | mming language | G language (Program started by command ser | nt from CPU Module's ladder program.) | | | |
| Controlled axe | S | 4 axes max. | 2 axes max. | | | |
| Maximum posi | tion value | -39,999,999 to 39,999,999 (for minimum settin | g Module of 1) | | | |
| Synchronous axis control | | 4 axes max. | 2 axes max. | | | |
| Positioning Linear interpolation | Linear interpolation | 4 axes max. | 2 axes max. | | | |
| | Arc interpolation | 2 axes max. in a plane | | | | |
| | Helical interpolation | 2-axis arc interpolation in a plane + feed axis | | | | |
| | Traverse | 2-axis traverse feeding | | | | |
| | Infinite feed | Infinite feeding of one or more axes | | | | |
| Interrupt feed | | Interrupt feeding for specified axes (Positioning can be specified for when there is no interrupt.) | | | | |
| Task Number of tasks | | 4 tasks max. | 2 tasks max. | | | |
| programming capacity | Number of programs | 25 programs when using 4 tasks | 50 programs when using 2 tasks | | | |
| capacity | Program capacity | 500 blocks per task when using 4 tasks | 1,000 blocks per task when using 2 tasks | | | |

CX-Motion: Windows-based Support Software

| Model | WS02-MCTC1-EV2 |
|-------------------------|--|
| Supported MC Modules | CS1W-MC221/421, C200H-MC221, and CV500-MC221/421 |
| Applicable computer | DOS, OS: Windows 95/98 or Windows NT Version 4.0 |
| Functions | Functions required for MC Module control: Creating/editing/saving/printingsystem parameters, positioning data, and MC programs; monitoring MC Module operation |

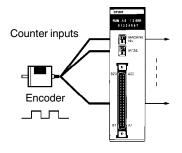
High Speed Counter Modules



Features

- Max. input frequency = 500 kHz (see note 1). Output turns ON less than 0.5 ms after set value is reached (see note 2).
- 32 bit counting range.
- 2 and 4 axis operation available.
- 5, 12, and 24 V line driver inputs available (5 and 12 V line driver input is only available for 1 axis with the CS1W-CT021 and 2 axes with the CS1W-CT041).
- Supports simple, ring, and linear counting modes.
- Supports offset phase input, up and down pulse input, and pulse + direction input.
- Supports 4 external control outputs and a total of 16 functions can be set including open gate, close gate, preset, reset, capture, stop/capture/resetcombinations, and reset enable.
- One Module supports 4 external outputs and 28 internal outputs with counter value zone comparisons, target comparisons, delays, holds, programable outputs, and hysteresis settings.
- Pulse rate measurement function and data logging.
- Counter outputs and external control inputs can be used to trigger interrupt tasks in the CPU.
- Settings can be changed during Module operation.

System Configuration



The high-speed counter modules count pulse signal inputs that are too fast to be detected by normal input Modules. The Modules can be programmed to produce outputs accordding to counter values for specified conditions, and many other functions are supported.

Special I/O Modules High-speed Counter Modules

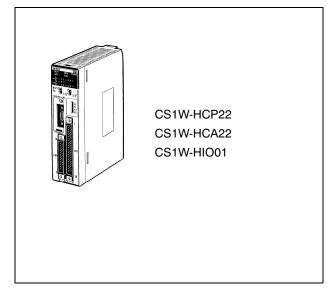
Specifications

| Classification | Number of counters | Encoder A and B input, pulse input, Z signal | Maximum counting speed | Module numbers | Model |
|-------------------------------|-----------------------|--|---------------------------|---|----------------|
| C200H Special 1 I/O Module | | Open-collector 50 kcps Input voltage: 5 VDC, 12 VDC, or 24 VDC | | 0 to 9 | C200H-CT001-V1 |
| | | RS-422 line driver | 75 kcps | | C200H-CT002 |
| | 2 | Open-collector Input voltage: 12 VDC or 24 VDC | 50 kcps | 0 to F | C200H-CT021 |
| | | RS-422 line driver | 75 kcps | | |
| CS1 Special I/O 2 Module | 2 | Open-collector Input voltage: 5 VDC, 12 VDC, or 24 VDC (5- and 12-VDC input only possible for 1 axis.) | 50 kcps | 0 to 92 (4 Module num- bers per Module) | CS1W-CT021 |
| | | RS-422 line driver | 500 kcps | | |
| | 4 | Open-collector Input voltage: 5 VDC, 12 VDC, or 24 VDC (5- and 12-VDC input only possible up to 2 axes.) | 50 kcps | | CS1W-CT041 |
| | | RS-422 line driver | 500 kcps | | |

Note: 1. This figure is for when line driver input is used.

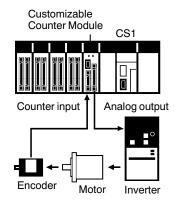
2. The time may exceed 0.5 ms in some cases, such as during execution of IORD/IOWR instructions.

Customizable Counter Modules



In addition to counter input, pulse input and analog output which are indispensable for mechanical control (inputs and outputs vary with the model) PLC functionality and 20 points of basic I/O are available with just 1 Module. There are also models that just have PLC functionality. Highspeed PLC functionality, with an overhead of 0.1 ms, allows the Modules to be used as "sub PLCs" that contribute to greater responsiveness and system perfomance, as well as function distribution and modularization.

System Configuration



Available Models

| Model number | Program | I/O points | s (built-in) | | Special I/O | | Built-in |
|--------------|----------|--------------------------------|--------------------------------|---|---------------|-------------------|------------------------------|
| | capacity | Contact input | Contact output | Pulse input (high-speed counters) | Pulse outputs | Analog outputs | peripheral port |
| CS1W-HIO01 | 4 Kwords | 12 inputs (24 VDC) (4 in- | 8 transistor outputs (sink- | None | None | None | For Program- ming Console |
| CS1W-HCP22 | - | puts can be | ing) | 2 pts | 2 pts | None | or CX-Program- |
| CS1W-HCA22 | 1 | used as inter- rupt inputs) | | 2 pts | None | 2 pts | mer |

Special I/O Modules Customizable Counter Modules

Specifications

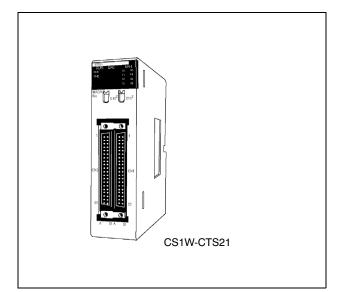
| Model | I/O | Contents |
|--|---------------------------------------|---|
| All Modules: CS1W-HIO01, CS1W-HCP22, and CS1W-HCA22 | Contact inputs | 12 inputs (24-VDC; bits IR 00000 to IR 00011) <u>Details:</u> 4 interrupt inputs in Input Interrupt Mode or Counter Mode. Can also be used as normal inputs (bits IR 00000 to IR 00003) |
| | | 8 normal inputs (bits IR 00004 to IR 00011) |
| | | Note It is possible to specify ON, OFF, or both for the timing of interrupts in Input Interrupt Mode. |
| | Contact outputs | 8 outputs (transistor NPN outputs; bits IR 00100 to IR 00107) |
| CS1W-HCP22 (pulse I/O) | Pulse inputs (high-speed counters) | 2 inputs Each input can be set to either single-phase or differential-phase (multiplication factor of 1, 2, or 4) at 50 or 200 kHz (switchable). |
| | | Note Target value interrupts or range comparison bit pattern outputs for high-speed counter present values can be programmed. Measurement of the rate of change in high-speed counter present values and measurement of the frequency from the high-speed counter present values is also possible. |
| | Pulse outputs | 2 outputs Each output can be set to any one of the following: |
| | | 1. Pulse output: 6 Hz to 200 kHz |
| | | 2. One-shot pulse output: Output can be set to turn ON for a time specified by the user. (Set in range 0.01 to 9,999 ms in 0.01-ms Modules.) |
| | | Pulse output counter timer (time measurement): High-precision timer measurement in 0.01-ms Modules is possible using one-shot pulse output. (In this case, external pulse output is not possible.) |
| CS1W-HCA22 (pulse inputs and analog outputs) | Pulse inputs (high-speed counters) | 2 inputs Each input can be set to either single-phase or differential-phase (multiplication factor of 1, 2, or 4) at 50 or 200 kHz (switchable). |
| | | Note Target value interrupts or range comparison bit pattern outputs for high-speed counter present values can be programmed. Measurement of the rate of change in high-speed counter present values and measurement of the frequency from the high-speed counter present values is also possible. |
| | Analog outputs | 2 outputs Each output can be set to any one of the following: 1 to 5 V, 0 to 5 V, 0 to 10 V, or -10 to 10 V |
| | | Accuracy: ±0.3%; Resolution: 4,000 (1 to 5 V, 0 to 5 V, 0 to 10 V) or 10,000 (-10 to 10 V), D/A conversion time: 0.5 ms max. |
| | | Outputs the output values set in the AR Area. Also, for each point, using the SPED instruction and ACC instruction (combined use possible), output at a fixed analog value, or output at values rising or falling at a fixed rate, is possible. |
| | | It is possible to select either immediate refreshing when instructions are executed or refreshing of output values in the AR Area after execution of the END instruction as the refreshing method for analog output. |
| | | Analog output values can be held. (Analog values can be output at their peak, held, or cleared values when the Conversion Enable Flag is OFF, a fatal error occurs, or an analog output error occurs.) |
| | | Note It is also possible to produce trapezoidal output of analog values according to the time elapsed by combining the SPED instruction, the ACC instruction, timer instructions, and scheduled interrupts. |

Customizable Counter Modules

Specifications

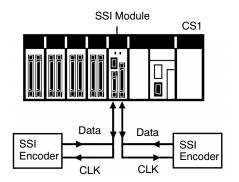
| | Item | Specifications |
|----------------|-----------------------|--|
| Contact inputs | Number of inputs | 12 inputs4 inputs (input bits IR 00000 to IR 00003) can be used either as interrupt inputs or normal inputs. |
| | | Note Each of these 4 inputs can be set to be used as either interrupt inputs or normal inputs in the Module Setup Area (DM 6620). It is also possible to specify the ON, OFF, or both for the interrupt timing for each point (Input Interrupt Mode or Counter Mode) in the Module Setup Area (DM 6620). |
| | | 8 inputs (input bits IR 00004 to IR 00011) can be used as normal inputs only. |
| | Input voltage/current | 24 V ^{+10%} / _{-15%} , 5 mA typical |
| | Min. ON voltage | 15.2 V |
| | Max. OFF voltage | 4.8 V |
| | Input response | Inputs for interrupt input or normal input (4 points with one common): ON delay time: 50 μs OFF delay time: 200 μs max. |
| | | Inputs for normal input (8 points with one common): ON delay time: 100 μs OFF delay time: 1 ms max. |
| | Circuit configuration | Interrupt inputs Interrupt inputs Internal circuit Normal inputs Internal circuit To Q Internal circuit To Q T |

Programmable Synchronous Serial Interface (SSI) Counter Module



In addition to 2 SSI inputs with flexible SSI settings, 4 digital inputs with interrupts to the PLC and 4 digital outputs both NPN and PNP are available in the same Module. Encoder count values and status bits are stored in the PLC's memory (CIO). Default switch for "plug and play".

System Configuration

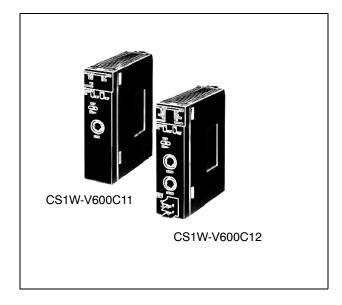


Specifications

| Classification | CS1 special I/O Module | |
|--|---|--|
| SSI connection | RS-422/485, galvanically isolated | |
| SSI data format - Gray/binary/tannenbaum/raw - Parity check - Status bit freely configurable | | |
| Number of encoder data bits | Phase difference (×1, ×2, or ×4), up/down, or pulse with direction | |
| Clock frequency | 100, 200, 300, 400 & 500 kHz 1.0 and 1.5 MHz | |
| One-shot setting range | 10 μs to 99 ms | |
| Digital inputs | 4 DC inputs, 24 VDC with interrupt function, individually isolated, 10 kHz noise filter | |
| Digital outputs | 4 transistor, NPN/PNP selectable, 2 circuits 24 VDC, 0.1 A | |
| Status display | LED | |

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ID Sensor Module



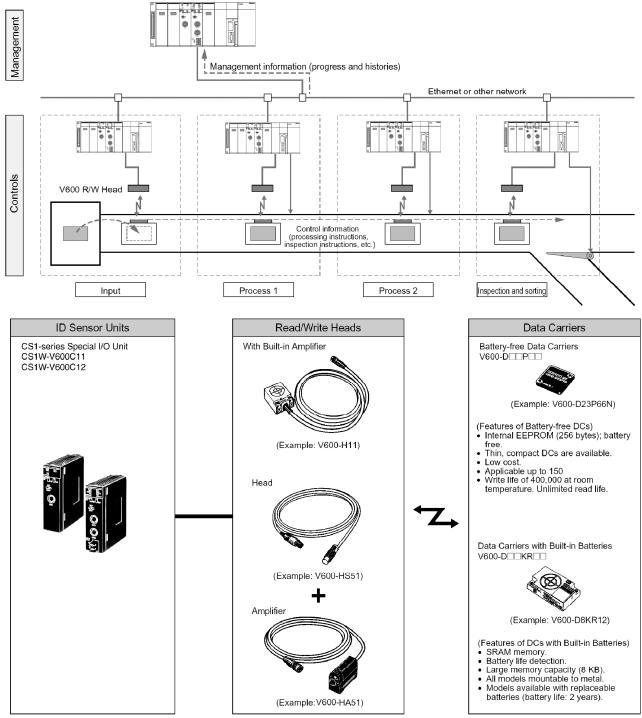
Feature

- Models available to connect to either one or two R/W heads.
- High-data communications with the CPU (160 bytes/ scan) greatly reduce processing time from communications with Data carriers to results.
- Efficient programming with control bits and data located in different interface areas.
- Common operating methods for both single-head and double head Modules to effictively apply programming resources through modularization.
- Status confirmation function without CPU program for faster system setup.
- Power supply error flags and processing results monitor data (communications TAT and error codes) for easier maintenance.

Control RFID-based data tracking directly from the CS1 PLC. An ID sensor module interfaces with a V600-series ID system (an electronic magnetic-coupling RFID system) and is used together with Read/Write (R/W) heads and data carriers.

ID Sensor Modules

System Configuration



Note: Refer to the Auto-Identification Components Group Catalog (Cat. No. Q132) for details on the V600 Series.

ID Sensor Module

Specifications

| Item | CS1W-V600C11 | | CS1W-V600C12 | | |
|--|--|----------------------------------|--------------|--|--|
| Data transfer speed | 160 bytes/scan (between CPU and ID sensor Module) | | | | |
| Applicable RFID system | V600 series | | | | |
| Number of connectable R/W heads | 1 | | 2 | | |
| Commands (The number of bytes that can be specified is given in brackets) | Read/write [1 to 2,048] Data fill (clear) [1 to 2,048 or through end address] Copy (for double-head Modules only) [1 to 2,048] Calculation write [1 to 4] Bit set/bit clear [1 to 4] Masked bit write [2] Memory check [2] Number of writes control [2] | | | | |
| Communications processing time (See note.) | Command | Data carriers with bui batteries | | Battery free data carriers in time priority mode | |
| | Read | 1.8 x N + 48.4 ms | | 1.8 x N + 79.0 ms | |
| | Write with verify | 4.2 x N + 86.5 ms | | 7.1 x N + 180.4 ms | |
| | Write without verify | 2.2 x N + 72.8 ms | | 4.3 x N + 132 ms | |
| | N = the number of bytes being read or written. | | | | |
| Maintenance features | Communications test, processing results monitor data (communications TAT and error codes) | | | | |
| Error detection | CPU errors, communications errors with Data carriers, R/W head power supply check. | | | | |

Note: Add the data transfer time to the communications processing time for the command processing time.

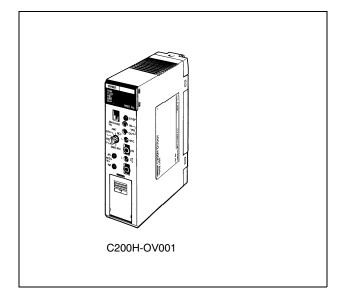
Alert machine operators with audible notification of system conditions or alarms. Use the Voice Module for operator interface messages. Record up to 60 voice messages on site, or use a tape recorder and transfer the

Messages can also be uploaded or downloaded through the RS-232C port on the front panel. The built-in speaker enables immediate message verification. Message length

message to the module.

and sound quality are selectable.

Voice Module



Feature

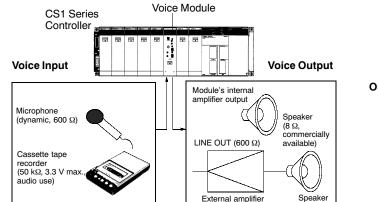
Input Devices

- Microphone jack enables live message broadcast.
- Flexible message length.
- Messages can be interrupted to start another message.
- Messages can be recorded in phrase and word combination formats.
- Status confirmation function without CPU program for faster system setup.
- Upload or download messages through the RS-232C port on the front panel.
- System Configuration

Computer

Microphone

Tape recorder



Output Devices

- Computer
 - Printer
 - Speaker

C-110 Programmable Controller CS1

Voice Module

Specifications

| Classification | | C200H Special I/O Module | | |
|--|----------------------------------|---|--|--|
| Model | | C200H-OV001 | | |
| Voice synthesis method | | Adaptive differential pulse-coded modulation (ADPCM) | | |
| Message | Recording time | 32, 48, or 64 s (switch-selectable) | | |
| | Capacity (sentences and phrases) | 60 max. | | |
| Message input (switch-selectable) | MIC IN | Microphone input: Unbalanced dynamic microphone (600 Ω) | | |
| | LINE IN | Tape input: Input impedance: 50 k Ω , unbalanced; Maximum input voltage: 3.3 V | | |
| Message output (switch-selectable) | SPEAKER OUT | Built-in amplifier output: 0.14 W (8 Ω speaker) | | |
| | LINE OUT | External amplifier output: 600Ω unbalanced transformer output Maximum output voltage: $0.5 V$ rms (effective value) Balanced and unbalanced external amplifiers are connectable | | |
| Built-in monitor speaker | | Diameter 27 mm, 0.1 W (8 Ω) | | |
| Input frequency | | 32-second recordings: 8 kHz 48-second recordings: 5.3 kHz 64-second recordings: 4 kHz | | |
| Output frequency characteristics | | 32-second recordings: 100 Hz to 3.2 kHz 48/64-second recordings: 100 Hz to 2.2 kHz | | |
| Low-pass filter (LPF) selector function (see note) | | Cutoff frequency: 3.2 kHz for 32-second recordings, 2.2 kHz for 48/64-second recordings | | |
| Message memory | | 128K bytes RAM (battery powered) | | |
| External communication function (save recorded messages) | | RS-232C (Baud rate: 19,200/9,600/4,800/2,400bps. XON/XOFF: yes/no, CTS/RTS: yes/no) | | |
| Self-diagnosis function | | CPU watchdog timer, LOW battery voltage detection | | |
| Battery life | | 5 years at 25°C (battery life is shorter for higher temperatures) | | |
| I/O words required | | 10 (Special I/O area) | | |
| Internal current consumption | | 5 VDC, 0.3 A max. | | |
| Weight | | 400 g max. | | |

Note: The recording time of the Voice Module is varied by changing the module's input frequency. For improved sound quality, the cutoff frequency of the low-pass filter is automatically changed to a lower frequency when the recording time is increased from 32 to either 48 or 64 seconds. (The output frequency is set to 100 Hz to 2.2 kHz when the recording time is set to 48 or 64 seconds.)