# SYSMAC CJ-series CJ2H (Built-in EtherNet/IP) CPU Units

# CJ2H-CPU6□-EIP

CSM CJ2H-CPU-FIP DS F 1 1

# Flagship PLCs with Built-in Multifunctional Ethernet Port

• Small, Fast, Flexible:

The CJ2 CPU Units inherit and improve CJ1 features while also adding EtherNet/IP as a standard feature for high-speed, high-capacity Ethernet-based networking.



CJ2H-CPU6□-EIP

#### **Features**

- High-speed, high-capacity EtherNet/IP is built into every model.
- The CIP communications protocol is supported for direct access to multivendor devices.
- Tag memory provided for easy access from host PCs and PTs.
- Even more program memory and data memory.
- Superior high-speed control performance: LOAD instructions execute in 16 ns, SINE instructions in 0.59 µs.

## **Ordering Information**

		Specifications						
Product name	I/O capacity/Mountable Units (Expansion Racks)	Program capacity  Data memory capacity		LD instruction execution time	5 V 24 V		Model	Standards
	2,560 points / 40 Units (3 Expansion Racks max.)	400K steps	832K words DM: 32K words EM: 32K words × 25 banks		0.82 (See note.)		CJ2H-CPU68-EIP	
CJ2 CPU Units		250K steps	512K words DM: 32K words EM: 32K words × 15 banks	0.016 μs			CJ2H-CPU67-EIP	
		150K steps	352K words DM: 32K words EM: 32K words × 10 banks			_	CJ2H-CPU66-EIP	UC1, N, L, CE
		100K steps	160K words DM: 32K words EM: 32K words × 4 banks				CJ2H-CPU65-EIP	
		50K steps	160K words DM: 32K words EM: 32K words × 4 banks				CJ2H-CPU64-EIP	

Note: Add 0.15 A per Adapter when using NT-AL001 RS-232C/RS-232A Adapters. Add 0.04 A per Adapter when using CJ1W-CIF11 RS-422A Adapters.

#### International Standards

- The standards indicated in the "Standards" column are those current for UL, CSA, cULus, NK, and Lloyd standards and EC Directives as of the end of April 2008. The standards are abbreviated as follows: U: UL, U1: UL (Class I Division 2 Products for Hazardous Locations), C: CSA, UC: cULus, UC1: cULus (Class I Division 2 Products for Hazardous Locations), CU: cUL, N: NK, L: Lloyd, and CE: EC Directives
- Ask your OMRON representative for the conditions under which the standards were met.

#### **Accessories**

The following accessories come with CPU Unit:

Item	Specification				
Battery	CJ1W-BAT01				
End Cover	CJ1W-TER01 (necessary to be mouned at the right end of CPU Rack)				
End Plate	PFP-M (2 pcs)				
Serial Port (RS-232C) Connector	Connector set for serial port connection (D-SUB 9-pin male connector)				

# **General Specifications**

	liane		CJ2H-					
	Item	CPU64-EIP	CPU65-EIP	CPU66-EIP	CPU67-EIP	CPU68-EIP		
Enclosure		Mounted in a pane	el					
Grounding		Less than 100 Ω						
CPU Rack Dimensio	ns	90 mm × 65 mm ×	80 mm (W × H × I	0)				
Weight		280 g or less						
Current Consumption	on	5 VDC, 0.82 A						
	Ambient Operating Temperature	0 to 55°C						
	Ambient Operating Humidity	10% to 90%						
	Atmosphere	Must be free from	corrosive gases.					
	Ambient Storage Temperature	−20 to 70°C (excluding battery)						
	Altitude	2,000 m or less						
	Pollution Degree	2 or less: Conforms to JIS B3502 and IEC 61131-2.						
Use Environment	Noise Immunity	2 kV on power supply line (Conforms to IEC 61000-4-4.)						
Ose Environment	Overvoltage Category	Category II: Confo	Category II: Conforms to JIS B3502 and IEC 61131-2.					
	EMC Immunity Level	Zone B	Zone B					
	Vibration Resistance	Conforms to JIS C60068-2-6. 5 to 8.4 Hz with 3.5-mm amplitude, 8.4 to 150 Hz Acceleration of 9.8 m/s² for 100 min in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total)						
	Shock Resistance	Conforms to JIS C60068-2-27. 147 m/s², 3 times in X, Y, and Z directions (100 m/s² for Relay Output Units)						
Dottory	Life	5 years at 25°C						
Battery	Model	CJ1W-BAT01						
Applicable Standard	Is	Conforms to cULu	Conforms to cULus and EC Directives.					

# **Performance Specifications**

	Items				CJ2H-				
none			CPU64-EIP	CPU65-EIP	CPU66-EIP	CPU67-EIP	CPU68-EIP		
User Memory			50K steps	100K steps	150K steps	250K steps	400K steps		
I/O Bits	-		2,560 bits						
Overhead Processing Time			Normal Mode: 200 $\mu$ s (If tag data links are used with EtherNet/IP, add the following to the above time: 100 $\mu$ s + Number of transferred words $\times$ 0.33 $\mu$ s)						
Speed	<b>Execution Time</b>		Basic Instructions: 0 Special Instructions:						
	Interrupt Task S	tart Time	30 μs						
Maximum Num	ber of Connectabl	e Units	Total per CPU Rack Total per PLC: 40 Ur	or Expansion Rack: 1 nits max.	0 Units max.;				
Maximum Num	ber of Expansion	Racks	3 max.						
	I/O Area		2,560 bits (160 word	ls): Words CIO 0000 t	o CIO 0159				
	Link Area		3,200 bits (200 word	ls): Words CIO 1000 t	o CIO 1199				
	CPU Bus Unit A	rea	6,400 bits (400 word	ls): Words CIO 1500 t	o CIO 1899				
CIO Area	Special I/O Unit	Area	,	rds): Words CIO 2000					
CIO Area	DeviceNet Area	7.100	,	ls): Words CIO 3200 t					
	Internal I/O Area	1	3,200 bits (200 word	ls): Words CIO 1300 t ords): Words CIO 380	o CIO 1499				
Work Area			8,192 bits (512 word Cannot be used for 6	ls): Words W000 to Wexternal I/O.	511				
Holding Area			Bits in this area main Words H512 to H153	35: These words can b	atus when PLC is turn		mode is changed. e used only for function		
Auxiliary Area			Read-only: 31,744 bits (1,984 words)  • 7,168 bits (448 words): Words A0 to A447  • 24,576 bits (1,536 words): Words A10000 to A11535  Read/write: 16,384 bits (1,024 words) in words A448 to A1471						
Temporary Are	a		16 bits: TR0 to TR15						
Timer Area			4,096 timer numbers	s (T0000 to T4095 (se	parate from counters)	)			
Counter Area			4,096 counter numbers (C0000 to C4095 (separate from timers))						
DM Area			32k words (Bits in the DM Area can be addressed either by bit or by word.) DM Area words for Special I/O Units: D20000 to D29599 (100 words × 96 Units) DM Area words for CPU Bus Units: D30000 to D31599 (100 words × 16 Units)						
EM Area			32k words/bank × 25 banks max.: E00_00000 to E18_32767 max. (Bits in the EM Area can be addressed either by bit or by word.)						
			32K words × 4 banks	32K words × 4 banks	32K words × 10 banks	32K words × 15 banks	32K words × 25 banks		
		Force-set/reset	EM3	EM3	EM6 to EM9	EM7 to EME	EM11 to EM18		
		Enabled Banks	Force-setting/resetting	ng is enabled only for	areas specified for au	itomatic address alloc	ation.		
Index Registers	s		IR0 to IR15 These are special registers for storing PLC memory addresses for indirect addressing. (Index Registers can be set so that they are unique in each task or so that they are shared by all tasks.)						
Cyclic Task Fla	ıq Area		128 flags						
Memory Card	<u> </u>		128 MB, 256 MB, or	512 MB					
					cuted Preparations of	in be executed prior to	program execution in		
			PROGRAM Mode: Programs are not executed. Preparations can be executed prior to program execution in this mode.						
Operating Mod	es					ns, such as online edit	ing, and changes to		
			present values in I/O memory, are enabled in this mode.  RUN Mode: Programs are executed. This is the normal operating mode.						
Execution Mode			Normal Mode  Normal Mode						
Execution wode			Ladder Logic (LD),						
Programming Languages		Sequential Function Charts (SFC), Structured Text (ST), and Instruction Lists (IL)							
Function Maximum number of definitions		er of definitions	2,048						
Blocks	Maximum numb	er of instances	2,048						
	Type of Tasks		Cyclic tasks	er OFF interrupt tasks	scheduled interrupt to	asks, I/O interrupt task	s, and external interrup		
Tasks	Number of Task	s	Cyclic tasks: 128 Interrupt tasks: 256 (Interrupt tasks can be tasks is actually 384		sks to create extra cyc	lic tasks. Therefore, th	e total number of cycli		

Itams				CJ2H-					
	Items	CPU64-EIP	CPU65-EIP	CPU66-EIP	CPU67-EIP	CPU68-EIP			
	Type of Symbols	Local symbols: Can be used only within a single task in the PLC.     Global symbols: Can be used in all tasks in the PLC.     Network symbols (tags): I/O memory in the CPU Unit can be externally accessed using symbols, depending on parameter settings.							
Symbols (Variables)	Data Type of Symbols	BOOL (bit) UINT (one-word ur UDINT (two-word u ULINT (four-word u ULINT (four-word u UNT BCD (one-w INT (one-word sig DINT (two-word sig UNT BCD (two-u ULINT BCD (four-v REAL (two-word fic LREAL (four-word LREAL (four-word NUMBER (constan WORD (one-word DWORD (two-word LWORD (four-word TIMER COUNTER	unsigned binary) unsigned binary) unsigned BCD) und unsigned BCD) und binary) uned binary) to runsigned BCD) uned binary uned binary) to runsigned BCD) uned binary uned binary uned binary) to runsigned BCD) uned binary) to runsigned BCD) uned binary) to runsigned binary to runsigned binar						
	Maximum Size of Symbol	32k words							
	Array Symbols (Array Variables)	One-dimensional arrays							
	Number of Array Elements	32,000 elements max.							
	Number of Registrable Network Symbols (Tags)	20,000 max.							
	Length of Network Symbol (Tag) Name	255 bytes max.							
	Encoding of Network Symbols (Tags)	UTF-8							
	Momory Consoit:	8,000 words		16,000 words	32,000 words				
	Memory Capacity	(Up to 32k words × 2	5 banks when EM is s	pecified in CX-Progra	mmer)				
	Number of Samplings	Bits = 31, one-word data = 16, two-word data = 8, four-word data = 4							
	Sampling Cycle	1 to 2,550 ms (Unit:	1 ms)						
Data Tracing	Trigger Conditions	ON/OFF of specified bit Data comparison of specified word Data size: 1 word, 2 words, 4 words Comparison Method: Equals (=), Greater Than (>), Greater Than or Equals (≥), Less Than (<), Less Than or Equals (≤), Not Equal (≠)							
	Delay Value	-32,768 to +32,767 ms							
File Memory		Memory Card (128, 256, or 512 Mbytes) (Use the Memory Cards provided by OMRON.) EM file memory (Part of the EM Area can be converted for use as file memory.)							
Source/ Comment Memory	Function block program memory, comment file, program index file, symbol tables	Capacity: 3.5 Mbytes							

					CJ2H-			
			Item		CPU64-EIP CPU65-EIP CPU66-EIP CPU67-EIP CPU68-EIP			
	_			Logical Ports	8 ports (Used for SEND, RECV, CMND, PMCR, TXDU, and RXDU instructions.)			
		Logical Ports for Extended Logical Ports			64 ports (Used for SEND2, RECV2, CMND2, and PMCR2 instructions.)			
	_	CIP Communications Specification CIPS Class 3 (Number of Connections) UCMM (Non-connection Type)			Number of connections: 64			
				UCMM (Non- connection Type)	Maximum number of clients that can communicate at the same time: 32  Maximum number of servers that can communicate at the same time: 40			
	Peripheral (USB) Port			•••	USB 2.0-compliant B-type connector			
	Baud Rate				12 Mbps max.			
		Trai	nsmission Dist	ance	5 m max.			
	Ser	Serial Port			Interface: Conforms to EIA RS-232C.			
		Con	nmunications N	/lethod	Half-duplex			
	:	Syn	chronization M	ethod	Start-stop			
	Ī	Bau	ıd Rate		0.3, 0.6, 1.2, 2.4, 4.8, 9.6, 19.2, 38.4, 57.6, or 115.2 (kbps)			
	-	Trai	nsmission Dista	ance	15 m max.			
	Eth	erN	et/IP Port		-			
		S	Media Access	Method	CSMA/CD			
		⊱ተ	Modulation		Baseband			
		fica	Transmission I	Paths	Star			
		<u>ë</u> -	Baud Rate		100 Mbps (100Base-TX)			
			Transmission I	Media	Shielded twisted-pair (STP) cable; Categories: 5, 5e			
		<u>ۊ</u>	Transmission I		100 m (between hub and node)			
		smis	Number of Cascade Connections		No restrictions if switching hub is used.			
		Ë						
			CIP Communic	ations: Tag Data Links	-			
			Number of C	Connections	256			
Commu- nications			Packet Inter	val (Refresh period)	0.5 to 10,000 ms (Unit: 0.5 ms) Can be set for each connection. (Data will be refreshed at the set interval, regardless of the number of nodes.)			
			Permissible	Communications Band	6,000 pps <b>*</b> 1			
			Number of T	ag Sets	256			
			Type of Tag	s	CIO, DM, EM, HR, and WR			
			Number of T	ags per Connection	8 (Seven tags if PLC status is included in the segment.)			
			Maximum Li	ink Data Size per Node	184,832 words			
			Maximum D	ata Size per Connection	252 or 722 words *2 (Data is synchronized within each connection.)			
		tions	Number of F	Registrable Tag Set	256 (1 connection = 1 segment)			
		cat	Maximum Ta	ag Set Size	722 words (One word is used when PLC status is included in the segment.)			
		Specifica		umber of Tags in a Single Cycle of	Output/send (CPU Unit to EtherNet/IP): 256 Input/receive (EtherNet/IP to CPU Unit): 256			
		Communications	Data Size Re Cycle of CP	efreshable in a Single U Unit *3	Output/send (CPU to EtherNet/IP): 6,432 words Input/receive (EtherNet/IP to CPU): 6,432 words			
		munic		ag Data Link Parameter ring Operation	OK *4			
		ĕ	Multi-cast P	acket Filter *5	ОК			
			CIP Communic Messages	ations: Explicit	_			
			Class 3 (Nur	mber of Connections)	Number of connections: 128			
			UCMM (Non	-connection Type)	Maximum number of clients that can communicate at the same time: 32 Maximum number of servers that can communicate at the same time: 32			
			CIP Routing		OK (CIP routing is enabled for the following remote Units: CJ1W-EIP21 and CJ2H-CPU6□-EIP.)			
			FINS Communi	ications	-			
			FINS/UDP		ОК			
			FINS/TCP		16 connections max.			
			EtherNet/IP Co	nformance Test	Conforms to A5.			
		İ	EtherNet/IP Inte	erface	10Base-T/100Base-TX Auto Negotiation/Fixed Setting			

- \*1. "Packets per second" is the number of communications packets that can be processed per second.
- \*2. Large Forward Open (CIP optional specification) must be supported in order for 505 to 1,444 bytes to be used as the data size. Application is supported between CS/CJ-series PLCs. When connecting to devices from other manufacturers, make sure that the devices support the Large Forward Open specification.
- \*3. If the maximum number is exceeded, refreshing will require more than one CPU Unit cycle.
- \*4. When changing parameters, however, the EtherNet/IP port where the change is made will be restarted. In addition, a timeout will temporarily occur at the other node that was communicating with that port, and it will then recover automatically.

  \*5. The EtherNet/IP port supports an IGMP client, so unnecessary multicast packets are filtered by using a switching hub that supports IGMP

## **Function Specifications**

	I	Functions		Description		
				A minimum cycle time can be set. (0.2 to 32,000 ms; Unit: 0.1 ms)		
Cycle Time Management	Cycle Time Mo	nitoring		The cycle time is monitored. (0.01 to 40,000 ms; Unit: 0.01 ms)		
	Background Pi	rocessing		Instructions with long execution times can be executed over multiple cycles to prevent fluctuations in the cycle time.		
	Basic I/O		Cyclic Refreshing	Cyclic refreshing of Basic I/O Units, Special I/O Units, and CPU Bus Units		
	Units, Special	I/O Refreshing	Immediate Refreshing	I/O refreshing by immediate refreshing instructions		
	I/O Units, and CPU Bus	ricircaning	Refreshing by IORF	I/O refreshing by IORF instruction		
	Units	Unit Recogn	ition at Startup	The number of units recognized when the power is turned ON is displayed.		
	D 1/0	Input Response Time Setting		The input response times can be set for Basic I/O Units. The response time can be increased to reduce the effects of chattering and noise at input contacts. The response time can be decreased to enable detecting shorter input pulses.		
	Basic I/O Units	Load OFF Function		All of the outputs on Basic I/O Units can be turned OFF when an error occurs in RUN or MONITOR mode.		
Unit (I/O) Management		Basic I/O Unit Status Monitoring		Alarm information can be read from Basic I/O Units and the number of Units recognized can be read.		
	Special I/O Units and CPU Bus Units	Unit Restart Bits to Restart Units		A Special I/O Unit or CPU Bus Unit can be restarted.		
	Configuration Management	Automatic I/O Allocation at Startup		I/O words can be automatically allocated to the Basic I/O Units that are connected in the PLC to start operation automatically without registering Units into I/O tables.		
				The current unit configuration can be registered in I/O tables to prevent it from being changed, to reserve words, and to set words.		
		Rack/Slot First Word Settings		The first words allocated to a Units on the Racks can be set.		
	Holding I/O Memory when Changing Operating Modes			The status of I/O memory can be held when the operating mode is changed or power it turned ON. The forced-set/reset status can be held when the operating mode is change or power is turned ON.		
	File Memory			Files (such as program files, data files, and symbol table files) can be stored in Memory Card, EM File Memory, or Comment Memory.		
Memory Management	Built-in Flash N	Memory		The user program and Parameter Area can be backed up to an internal flash memory when they are transferred to the CPU Unit.		
	EM File Function	on		Parts of the EM Area can be treated as file memory.		
	Storing Comments			I/O comments can be stored as symbol table files in a Memory Card, EM file memory, or comment memory.		
	EM Configuration			EM Area can be set as trace memory or EM file memory.		
	Automatic File	Transfer at S	tartup	A program file and parameter files can be read from a Memory Card when the power is turned ON.		
Memory Cards	Program Repla	cement durin	g PLC Operation	The whole user program can be read from a Memory Card to CPU Unit during operation.		
Carus	Function for Re	eading and W	riting Data from a Memory	Data in I/O memory in the CPU Unit can be written to a Memory Card in CSV/TXT format.  Data in CSV/TXT format in the Memory Card can be read to I/O memory in the CPU Unit.		

Peripheral IUSB   Peripheral Bus   Disc for communications with vestinace kinds of Support Schlower number on a personal computer. High-speed communications are supported.		Funct	ion	Description			
Port   Perspectations   Serial Port   1-   1-   1-   1-   1-   1-   1-   1	Communication	ons	<u> </u>	-			
Host Link (SYSWAY) Communications  No-protocol Communicati			Peripheral Bus				
Host Link (SYSWAY) Communications		Serial Port		-			
the Protection Communications  at a transfer with perployeral devices such as bar code readers and printers.  In Communications  Peripheral Bus  Bus by Communications  Peripheral Bus  Bus by Communications with various kinds of Support Software running on a personal of the devices of the Composition of the Communications  Bus by Communications  Peripheral Bus  Bus by Communications  Bus by Communications  Peripheral Bus  Bus by Communications  Programmed Society Programs and automatically converting FINS to the Composition of Programmed Society Programmes with the devices on the EtherNetiP Proteonic Total Proposition (STPP, UDP, ASP), SMTP, SMTP, DNS (Client), FTP (Server)  Any FINS Communications  Programmed Society Programmes with the devices on the EtherNetiP network.  Programmed Society Programmes with the devices on the EtherNetiP network.  Programmes society and the devices on the EtherNetiP network.  Programmes and the executed at a specified interval (2.0 ms min., Unit 0.1 ms).  Associate the executed with enterrupts are requested from the devices on the EtherNetiP network.  Programmed Programmes and the executed with enterrupts are requested from a Special I/O Unit or a CPU Blus Units o		Host Link (SYS	WAY) Communications	can be sent from a host computer or PT to read/write I/O memory, read/control the operating			
status control areas, status notification areas, touch switches, lamps, memory tables, and other objects.  Bus for communications with various kinds of Support Software running on a personal computer. High-speed communications are supported.  Sertial Gateway  This gateway enables receiving and automatically convening FIRS to the CompoWay/F.  10058ser-EXT/08as-FT  Protocols: TCP/IR LIDP: ARP   ICMP (ping only), BOOTP  Applications FIRS, CIP, POR3, SMFP, SMFP, DNS (Cibert), FTP (Server)  Programmessor Soft data exchanges with the devices on the EthenNetif Pinework.  Any FIRS communications  Service  Message Communications  Service  FIRS  Communications  Message Communications Service  Tips  Tasks can be executed at a specified interval (0.2 ms min., Unit: 0.1 ms).  A task can be executed with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with the devices on the EthenNetif Pinework.  Any FIRS commands can be transferred with		No-protocol Co	mmunications				
Ferripheral Disas		NT Link Commi	unications	status control areas, status notification areas, touch switches, lamps, memory tables, and			
EtherNet/IP Port Protocols: TCPRP_UDP, ARP, ICMP (ping only), BOOTP Applications: FINS, CIP, POPS, SMTP, SMTP, DNS (Client), FTP (Server)  CIP Communications Service Message Communications Service FINS Communications Service Any CIP commands can be received from the devices on the EtherNet/IP network.  Any CIP commands can be received from the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the devices on the EtherNet/IP network.  Any FINS commands can be transferred with the network of the properties the command ca		Peripheral Bus					
EthenNet/IP Port		Serial Gateway		This gateway enables receiving and automatically converting FINS to the CompoWay/F.			
Programless cyclic data exchanges with the devices on the EtherNet/IP network.		EtherNet/IP Port		Protocols: TCP/IP, UDP, ARP, ICMP (ping only), BOOTP			
Service   PINS   Communications   Any CIP commands can be received from the devices on the EtherNet/IP network.		CIP	Tag Data Links				
Communications   Message Communications   Service   Service   Service   Service   Tasks can be executed at a specified interval (0.2 ms min., Unit. 0.1 ms).			Message Communications	Any CIP commands can be received from the devices on the EtherNet/IP network.			
Power OFF Interrupts   A task can be executed when CPU Unit's power turns OFF.		Communications	Message Communications	Any FINS commands can be transferred with the devices on the EtherNet/IP network.			
Interrupt    WO Interrupt Tasks		Scheduled Interrup	ots	Tasks can be executed at a specified interval (0.2 ms min., Unit: 0.1 ms).			
External Interrupt Tasks  A task can be executed when interrupts are requested from a Special I/O Unit or a CPU Bus Unit.  Cock data is stored in memory. Accuracy (Accuracy depends on the temperature.) Ambient temperature of 25°C; -3.5 to +0.5 min error per month Ambient temperature of 25°C; -3.5 to +1.5 to 4.5 the min error per month Ambient temperature of 25°C; -3.5 to +1.5 the premature of 25°C; -3.5 to +1.5 to 4.5 the second of 25°C; the second of 25°C; the second of 25°C; the second of		Power OFF Interru	pts	A task can be executed when CPU Unit's power turns OFF.			
Clock Function   Interrupt	I/O Interrupt Tasks		A task can be executed when an input signal is input to an Interrupt Input Unit.				
Clock Function  Another temperature of 25°C: -3.5 to -4.5 in miceror per month Ambient temperature of 25°C: -3.5 to +1.5 in miceror per month Ambient temperature of 25°C: -3.5 to +1.5 in miceror per month Ambient temperature of 25°C: -3.5 to +1.5 in miceror per month Ambient temperature of 25°C: -3.5 to +1.5 in miceror per month Ambient temperature of 25°C: -3.5 to +1.5 in miceror per month Ambient temperature of 25°C: -3.5 to +1.5 in miceror per month Ambient temperature of 25°C: -3.5 to +1.5 in miceror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in micror per month Ambient temperature of 25°C: -3.5 to +1.5 in temperature of 10°C: Another Ambient temperature of 10°C: Another Amb		External Interrupt	Tasks				
Clock   Startup Time Storage   The last time a fatal error occurred or the last time the operating mode was changed to PROGRAM mode is stored.		Clock Function		Accuracy (Accuracy depends on the temperature.) Ambient temperature of 55°C: -3.5 to +0.5 min error per month Ambient temperature of 25°C: -1.5 to +1.5 min error per month			
Clock    Startup Time Storage		Operation Start Tin	ne Storage	The time when operating mode was last changed to RUN mode or MONITOR mode is stored.			
Startup Time Storage	Clock	Operation Stop Tin	ne Storage				
Total Power ON Time Calculation Power ON Clock Data Storage User Program Overwritten Time Storage The time that the PLC has been ON is stored in increments of 10 hours.  A history of the times when the power was turned ON is stored.  The time that the user program was last overwritten is stored.  The time when the Parameter Area was overwritten is stored.  Holding Area data, DM Area data, EM Area data, Counter Completion Flags, and counter present values are held even when power is turned OFF. Clo Area, Work Area, some Auxiliany Area data, and Timer Completion Flags, timer present values, index registers, and data registers can be protected by turning ON the IOM Hold Bit in the Auxiliary Area, and by also setting the IOM Hold Bit to "Hold Bit to "Ho		Startup Time Stora	ge	The time when the power was turned ON is stored.			
Power ON Clock Data Storage User Program Overwritten Time Storage The time that the user program was last overwritten is stored.  The time that the user program was last overwritten is stored.  The time when the Parameter Area was overwritten is stored.  The time when the Parameter Area was overwritten is stored.  Holding Area data, EM Area data, Counter Completion Flags, and counter present values are held even when power is turned OFF. Clo Area, Work Area, some Auxiliary Area data, and Timer Completion Flags, timer present values, index registers, and data registers can be protected by turning ON the IoM Hold Bit in the Auxiliary Area, and by also setting the IOM Hold Bit to "Hold" in the PLC Setup.  Power OFF Detection Time Setting  Power OFF Detection Time Setting  Power OFF Detection Delay Time  Number of Power Interruptions Counter  The detection time for power interruptions can be set.  AC power supply: 10 to 25 ms (CJ1W-PD022) or 2 to 20 ms (CJ1W-PD025)  Power OFF Detection Delay Time  Number of Power Interruptions Counter  The detection of power interruptions are be delayed: 0 to 10 ms (Not supported by the CJ1W-PD022).  Standard programming can be encapsualed as function blocks.  Languages in Function Block Definitions  Ladder programming or structured text  The program can be changed during operation (in MONITOR or PROGRAM mode), except for block programming areas.  Force-Set/Reset  Differentiate Monitoring  Data Tracing  Data Tracing  Data Tracing  Data Tracing  Storing Location of Error when an Error Occurs  The programs can be checked for items such as no END instruction and FALS/FAL errors at The programs can be checked for items such as no END instruction and FALS/FAL errors at The programs can be checked for items such as no END instruction and FALS/FAL errors at		Power Interruption	Time Storage	The time when the power is turned OFF is stored.			
User Program Overwritten Time Storage   The time that the user program was last overwritten is stored.							
Parameter Date Storage  The time when the Parameter Area was overwritten is stored.  Holding Area data, DM Area data, EM Area data, Counter Completion Flags, and counter present values are held even when power is turned OFF. CIO Area, Work Area, some Auxiliary Area data, and Timer Completion Flags, timer present values, index registers, and data registers can be protected by turning ON the IOM Hold Bit in the Auxiliary Area, and by also setting the IOM Hold Bit to "Hold" in the PLC Setup.  Power OFF Detection Time Setting  Power OFF Detection Time Setting  Power OFF Detection Delay Time  Number of Power Interruptions Counter  The detection of power interruptions can be set. AC power supply: 10 to 25 ms (CJ1W-PD022) or 2 to 20 ms (CJ1W-PD025)  The detection of power interruptions can be delayed: 0 to 10 ms (Not supported by the CJ1W-PD022.)  The unmber of Power Interruptions Counter  Function Blocks  Standard programming can be encapsulated as function blocks.  Languages in Function Block Definitions  Ladder programming or structured text  The program can be changed during operation (in MONITOR or PROGRAM mode), except for block programming areas.  Specified bits can be set or reset.  Differentiate Monitoring  Debugging  Data Tracing  The specified I/O memory data can be stored in the trace memory in the CPU Unit. The triggers can be set.  The specified I/O memory data can be stored in the trace memory in the CPU Unit. The triggers can be set.  The trace data can be uploaded during data tracing using CX-Programmer, which enables continuously logging the data by constantly uploading the trace data (i.e., when the operating mode is changed from PROGRAM mode to MONITOR or RUN mode).  Storing Location of Error when an Error Occurs  The location and task number where execution stopped for a program error is recorded.  The programs can be checked for items such as no END instruction and FALS/FAL errors at							
Holding Area data, DM Area data, Counter Completion Flags, and counter present values are held even when power is turned OFF. CIO Area, Work Area, some Auxiliary Area data, and Timer Completion Flags, timer present values, index registers, and data registers can be protected by turning ON the IOM Hold Bit in the Auxiliary Area, and by also setting the IOM Hold Bit to "Hold" in the PLC Setup.    Power OFF Detection Time Setting							
Power OFF Detection Time Setting  The detection time for power interruptions can be set. AC power supply: 10 to 25 ms (Variable) DC power supply: 2 to 5 ms (Variable) Determined of power interruptions can be delayed: 0 to 10 ms (volution) No 10 ms (No			-	Holding Area data, DM Area data, EM Area data, Counter Completion Flags, and counter present values are held even when power is turned OFF. CIO Area, Work Area, some Auxiliary Area data, and Timer Completion Flags, timer present values, index registers, and data registers can be protected by turning ON the IOM Hold Bit in the Auxiliary Area, and by also			
Power OFF Detection Delay Time  The detection of power interruptions can be delayed: 0 to 10 ms (Not supported by the CJ1W-PD022.)  Number of Power Interruptions Counter  The number of times power has been interrupted is counted.  Standard programming can be encapsulated as function blocks.  Languages in Function Block Definitions  Ladder programming or structured text  The program can be changed during operation (in MONITOR or PROGRAM mode), except for block programming areas.  Force-Set/Reset  Differentiate Monitoring  Debugging  Data Tracing  Data Traci	Supply	Power OFF Detecti	on Time Setting	The detection time for power interruptions can be set. AC power supply: 10 to 25 ms (variable)			
Number of Power Interruptions Counter   The number of times power has been interrupted is counted.		Power OFF Detecti	on Delay Time	The detection of power interruptions can be delayed: 0 to 10 ms			
Languages in Function Block Definitions  Ladder programming or structured text  The program can be changed during operation (in MONITOR or PROGRAM mode), except for block programming areas.  Force-Set/Reset  Differentiate Monitoring  Data Tracing  an be automatically started when operation is started (i.e., when the operating mode is changed from PROGRAM mode to MONITOR or RUN mode).  Storing Location of Error when an Error Occurs  The location and task number where execution stopped for a program error is recorded.  The programs can be checked for items such as no END instruction and FALS/FAL errors at		Number of Power I	nterruptions Counter				
Debugging  Debugging  Data Tracing  Data Tra	Function Bloc	ks		Standard programming can be encapsulated as function blocks.			
Debugging  Debugging  Data Tracing  Data Tra		Languages in Fund	ction Block Definitions	Ladder programming or structured text			
Debugging  Data Tracing  sing CX-Programmer, which enables continuously logging the data by constantly uploading the trace data (trace data uploading during tracing).  Data Tracing  sing CX-Programmer, which enables continuously logging the data by constantly uploading the trace data (trace data uploading during tracing).  Data Tracing  sing CX-Programmer, which enables continuously logging the data by constantly uploading the trace data (trace data uploading during tracing).  Data Tracing  Data Traci		Online Editing					
Debugging  Data Tracing  sing CX-Programmer, which enables continuously logging the data by constantly uploading the trace data (trace data uploading during tracing).  Data Tracing  sing CX-Programmer, which enables continuously logging the data by constantly uploading the trace data (trace data uploading during tracing).  Data Tracing  Data Tracing  Data Tracing  Data Tracing  Data Tracing  Data Tracing using CX-Programmer, which enables continuously logging the data by constantly uploading the trace data (trace data uploading during tracing).  Data Tracing  sing CX-Programmer, which enables continuously logging the data by constantly uploading during tracing using CX-Program extoring using CX-Program exto		Force-Set/Reset		Specified bits can be set or reset.			
Storing Location of Error when an Error Occurs  The location and task number where execution stopped for a program error is recorded.  Program Check  The programs can be checked for items such as no END instruction and FALS/FAL errors at	Debugging		oring	The specified I/O memory data can be stored in the trace memory in the CPU Unit. The triggers can be set.  The trace data can be uploaded during data tracing using CX-Programmer, which enables continuously logging the data by constantly uploading the trace data (trace data uploading during tracing).  Data tracing can be automatically started when operation is started (i.e., when the operating			
Program Check		Storing Location o	f Error when an Error Occurs	· · · · · · · · · · · · · · · · · · ·			
				The programs can be checked for items such as no END instruction and FALS/FAL errors at			

	Funct	ion		Description		
	Error Log			A function is provided to store predefined error codes in CPU Unit, error information, and time at which the error occurred.		
	CPU Error Detection	on		CPU Unit WDT errors are detected.		
Self-	User-defined Failu	re D	iagnosis	Errors can be generated for user-specified conditions: Non-fatal errors (FAL) and fatal errors (FALS).  Program section time diagnosis and program section logic diagnosis are supported (FPD instruction).		
diagnosis and	Load OFF Function			This function turns OFF all outputs from Output Units when an error occurs.		
Restoration	RUN Output			The RUN output from the CJ1W-PA205R turns ON while CPU Unit is in RUN mode or MONITOR mode.		
	Basic I/O Load Sho	ort-c	ircuit Detection	This function provides alarm information from Basic I/O Units that have load short-circuit protection.		
	Failure Point Detec	ction		The time and logic of an instruction block can be analyzes using the FPD instruction.		
	CPU Standby Dete	ctio	n	This function indicates when the CPU Unit is on standby because all Special I/O Units and CPU Bus Units have not been recognized at the startup in RUN or MONITOR mode.		
			stem FAL Error Detection ser-defined non-fatal error)	This function generates a non-fatal (FAL) error when the user-defined conditions are met in program.		
		Du	plicate Refreshing Error tection	This function detects an error when an immediate refreshing Instruction in an interrupt task is competing with I/O refreshing of a cyclic task.		
		Ва	sic I/O Unit Error Detection	This function detects the errors in Basic I/O Units.		
			ckup Memory Error tection	This function detects errors in the memory backup of the user programs and parameter area (backup memory).		
		PL	C Setup Error Detection	This function detects setting errors in the PLC Setup.		
		CPU Bus Unit Error Detection		This function detects an error when there is an error in data exchange between the CPU Unit and a CPU Bus Unit.		
		Special I/O Unit Error Detection		This function detects an error when there is an error in data exchange between the CPU L and a Special I/O Unit.		
	Non-fatal Error Detection	Та	g Memory Error Detection	This function detects errors in tag memory.		
		Ва	ttery Error Detection	This function detects an error when a battery is not connected to the CPU Unit or when the battery voltage drops.		
			U Bus Unit Setting Error tection	This function detects an error when the model of a CPU Bus Unit in the registered I/O tables does not agree with the model that is actually mounted in the PLC.		
			ecial I/O Unit Setting Error tection	This function detects an error when the model of a Special I/O Unit in the registered I/O tables does not agree with the model of Unit that is actually mounted.		
		Me	mory Error Detection	This function detects errors that occur in memory of the CPU Unit.		
Self- diagnosis		I/O	Bus Error Detection	This function detects when an error occurs in data transfers between the Units mounted in Rack slots and the CPU Unit and detects when the End Cover is not connected to the CPU Rack or an Expansion Rack.		
and Restoration (Continued			it/Rack Number plication Error	This function detects an error when the same unit number is set for two or more Units, the same word is allocated to two or more Basic I/O Units, or the same rack number is set for two or more Racks.		
from previous page)		Too Many I/O Points Error Detection		This function detects an error when the total number of I/O points set in the I/O tables or the number of Units per Rack exceeds the specified range.		
		I/O Setting Error Detection		This function detects an error when the number of Units in the registered I/O tables does not agree with the actual number of Units that is mounted, or an Interrupt Unit has been connected in the wrong position, i.e., not in slot 0 to 3.		
		Pro	ogram Error Detection	This function detects errors in programs.		
			Instruction Processing Error Detection	This function detects an error when the given data value is invalid when executing an instruction, or execution of instruction between tasks was attempted.		
			Indirect DM/EM BCD Error Detection	This function detects an error when an indirect DM/EM address in BCD mode is not BCD.		
			Illegal Area Access Error Detection	This function detects an error when an attempt is made to access an illegal area with an instruction operand.		
			No END Error Detection	This function detects an error when there is no END instruction at the end of the program.		
	Fatal Error Detection		Task Error Detection	This function detects an error when there are no tasks that can be executed in a cycle, there is no program for a task, or the execution condition for an interrupt task was met but there is no interrupt task with the specified number.		
			Differentiation Overflow Error Detection	This function detects an error when too many differentiated instructions are entered or deleted during online editing (131,072 times or more).		
			Invalid Instruction Error Detection	This function detects an error when an attempt is made to execute an instruction that is not defined in the system.		
			User Program Area Overflow Error Detection	This function detects an error when instruction data is stored after the last address in user program area.		
			cle Time Exceeded Error tection	This function monitors the cycle time (10 to 40,000 ms) and stops the operation when the set value is exceeded.		

	Funct	ion		Description
Self- diagnosis	System FALS Error Detection (User-defined Fatal Error)			This function generates a fatal (FALS) error when the user-defined conditions are met in program.
and Restoration	Detection (Continued from	Version Error De	etection	This function detects an error when a user program includes a function that is not supported by the current unit version.
(Continued from previous	previous page)	Memory Card Er	ror Detection	This function detects an error when the automatic file transfer from Memory Card fails at startup.
page)	Memory Self-resto	ration Function		This function performs a parity check on the user program area and self-restoration data.
	Simple Backup Fu	nction		This function collectively backs up the data in CPU Unit (user programs, parameters, and I/O memory) and internal backup data in the I/O Units.
	Unsolicited Communications			A function that allows the PLC to use Network Communications Instruction to send required FINS commands to a computer connected via a Host Link
Maintenance	Remote Programming and Monitoring			Host Link communications can be used for remote programming and remote monitoring through a Controller Link, Ethernet, DeviceNet, or SYSMAC LINK Network. Communications across network layers can be performed.  Controller Link or Ethernet: 8 layers  DeviceNet or SYSMAC LINK: 3 layers
		Automatic Online Connection via  Direct Serial Connection		This function enables automatically connecting to the PLC online when the CX-Programmer is directly connected by a serial connection (peripheral (USB) port or serial port).
	Network Via Networks			This function enables connecting the CX-Programmer online to a PLC that is connected via an EtherNet/IP network.
	Read Protection using Password			This function protects reading and displaying programs and tasks using passwords. Write protection: Set using the DIP switch. Read protection: Set a password using the CX-Programmer.
Casuritu	FINS Write Protect	ion		This function prohibits writing by using FINS commands sent over the network.
Security	Unit Name Function			This function allows the users to give any names to the Units. Names are verified at online connection to prevent wrong connection
	Hardware ID Using Lot Numbers			This function sets operation protection by identifying hardware using the user programs according to lot numbers stored in the Auxiliary Area.

## **Unit Versions**

Units	Models	Unit version
CJ2H CPU Units		CPU: Unit version 1.0 EIP: Unit version 2.0

## **Unit Versions and Programming Devices**

The following tables show the relationship between unit versions and CX-Programmer versions.

#### **Unit Versions and Programming Devices**

CPU Unit	Functions	CX-Prog	Programming		
CPO UIIII	Functions	Ver. 7.1 or lower	Ver. 8.0 or higher	Console	
CJ2H-CPU□□-EIP CPU: Unit Ver. 1.0	Functions for unit version 1.0	-	OK (See note 1.)	(See note 2.)	

Note: 1. CX-Programmer version 8.0 or higher is required to use CJ2H CPU Units.

2. The Programming Console cannot be used for CJ2H CPU Units.

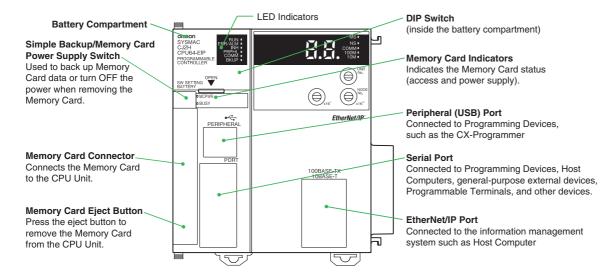
#### **Device Type Setting**

The unit version does not affect the setting made for the device type on the CX-Programmer. Select the device type as shown in the following table regardless of the unit version of the CPU Unit.

Series	CPU Unit group	CPU Unit model	Device type setting on CX-Programmer Ver. 4.0 or higher
CJ Series	CJ2H CPU Units	CJ2H-CPU□□-EIP	CJ2H

#### **External Interface**

A CJ2H CPU Unit provides three communications ports for external interfaces: a peripheral (USB) port, a sirial port and an EtherNet/IP port.



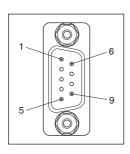
#### Peripheral (USB) Port

Item	Specification	
Baud Rate	12 Mbps max.	
Transmission Distance	5 m max.	
Interface	USB 2.0-compliant B-type connector	
Protocol	Peripheral Bus	

#### **Serial Port**

Item	Specification	
Communications method	Half duplex	
Synchronization	Start-stop	
Baud rate	0.3/0.6/1.2/2.4/4.8/9.6/19.2/38.4/57.6/115.2 kbps *	
Transmission distance 15 m max.		
Interface EIA RS-232C		
Protocol	rotocol Host Link, NT Link, 1:N, No-protocol, or Peripheral Bus	

<sup>\*</sup>Baud rates for the RS-232C are specified only up to 19.2 kbps. The CJ Series supports serial communications from 38.4 kbps to 115.2 kbps, but some computers cannot support these speeds. Lower the baud rate if necessary.



Pin No.	Signal	Name	Direction
1	FG	Protection earth	-
2	SD (TXD)	Send data	Output
3	RD (RXD)	Receive data	Input
4	RS (RTS)	Request to send	Output
5	CS (CTS)	Clear to send	Input
6	5 V	Power supply	_
7	DR (DSR)	Data set ready	Input
8	ER (DTR)	Data terminal ready	Output
9	SG (0 V)	Signal ground	
Connector hood	FG	Protection earth	-

Note: Do not use the 5-V power from pin 6 of the RS-232C port on the CPU Unit for anything but the NT-AL001-E Link Adapter. The external device or the CPU Unit may be damaged.

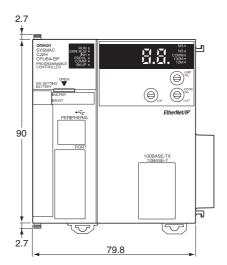
#### EtherNet/IP Port

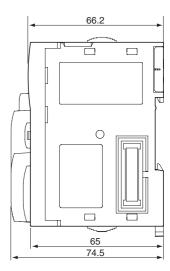
Item	Specification	
Media Access Method	CSMA/CD	
Modulation	Baseband	
Transmission Paths	Star	
Baud Rate	100 Mbps (100Base-TX)	
Fransmission Media Shielded twisted-pair (STP) cable; Categories: 5, 5e		
Transmission Distance	100 m (between hub and node)	
Number of Cascade Connections	No restrictions if switching hub is used.	
Communications	CIP Communications (tag data links, Explicit Messages). FINS communications	

Dimensions (Unit: mm)

### **CJ2H CPU Unit**







# **Related Manuals**

Cat. No.	Model	Manual	Application	Description	
W472	CJ2H-CPU□□-EIP	CJ-series CJ2 CPU Unit Hardware User's Manual	Hardware specifications for CJ2 CPU Units	Describes the following for CJ2 CPU Units:  Overview and features  Basic system configuration  Part nomenclature and functions  Mounting and setting procedure  Remedies for errors  Also refer to the Software User's Manual (W473).	
W473	CJ2H-CPU□□-EIP	CJ-series CJ2 CPU Unit Software User's Manual	Software specifications for CJ2 CPU Units	Describes the following for CJ2 CPU Units:  • CPU Unit operation  • Internal memory  • Programming  • Settings  • Functions built into the CPU Unit  Also refer to the Hardware User's Manual (W472)	
W474	CJ2H-CPU EIP CS1G/H-CPU H CS1G/H-CPU V1 CJ1G/H-CPU H CJ1G-CPU CJ1M-CPU NSU (B)-G5D NSU (B)-M3D	CS/CJ/NSJ-series Instructions Reference Manual	Information on instructions	Describes each programming instruction in detail. Also refer to the <i>Software User's Manual</i> (W473) when you do programming.	
W342	CS1G/H-CPU H CS1G/H-CPU H CS1D-CPU H CS1D-CPU H CS1D-CPU S CS1W-SCU V1 CJ1H-CPU H-R CJ1G-CPU P CJ1M-CPU CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC	CS/CJ/CP/NSJ-series Communications Command Reference Manual	Information on communications for CS/CJ/CP-series CPU Units and NSJ-series Controllers	Describes C-mode commands and FINS commands Refer to this manual for a detailed description of commands for communications with the CPU Unit using C mode commands or FINS commands.  Note: This manual describes the communications commands that are addressed to CPU Units. The communications path that is used is not relevant and can include any of the following: serial ports on CPU Units, communications ports on Serial Communications Units/Boards, and Communications Units. For communications commands addressed to Special I/O Units or CPU Bus Units, refer to the operation manual for the related Unit.	
W446		CX-Programmer Operation Manual		Describes operating procedures for the CX-Programmer. Also refer to the Software User's Manual (W473) and Instructions Reference Manual (W474) when you do	
W447	WS02-CX□□-V□	CX-Programmer Operation Manual Functions Blocks	Support Software for Windows computers  CX-Programmer operating		
W469		CX-Programmer Operation Manual SFC Programming	procedure	programming.	
W366	WS02-SIMC1-E	CS/CJ/CP/NSJ-series CX-Simulator Operation Manual	Operating procedures for CX-Simulator Simulation Support Software for Windows computers Using simulation in the CX-Programmer with CX-Programmer version 6.1 or higher	Describes the operating procedures for the CX-Simulator. When you do simulation, also refer to the CX-Programmer Operation Manual (W446), Software User's Manual (W473), and Instructions Reference Manual (W474).	
W464	CXONE-AL C-V3/CXONE-AL C-V3	CS/CJ/CP/NSJ-series CX-Integrator Network Configuration Software Operation Manual	Network setup and monitoring	Describes the operating procedures for the CX-Integrator.	
W463	CXONE-AL C-V3/	CX-One Setup Manual	Installing software from the CX- One	Provides an overview of the CX-One FA Integrated Tool Package and describes the installation procedure.	

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#### **CHANGE IN SPECIFICATIONS**

Product specifications and accessories may be changed at any time based on improvements and other reasons.

It is our practice to change model numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the products may be changed without any notice. When in doubt, special model numbers may be assigned to fix or establish key specifications for your application on your request. Please consult with your OMRON representative at any time to confirm actual specifications of purchased products.

#### **DIMENSIONS AND WEIGHTS**

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

#### PERFORMANCE DATA

Performance data given in this catalog is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of OMRON's test conditions, and the users must correlate it to actual application requirements. Actual performance is subject to the OMRON Warranty and Limitations of Liability.

#### **ERRORS AND OMISSIONS**

The information in this document has been carefully checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical, or proofreading errors, or omissions.

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In the interest of product improvement, specifications are subject to change without notice.

