GPS Evaluation Kit EVA2035-H

**A Description of the Evaluation Board
for Maestro's GPS Antenna Receiver Module A2035-H**

User's Manual

Version 0.3

Revision History

Rev.	Date	Description
0.1	07-08-11	Initial Draft
0.2	09-13-11	Updated EVA2035-H pictures
0.3	06-21-12	Add description of the Port Selection& terminal block
	mm-dd-yy	

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1 Introduction

1.1 Purpose

The GPS Evaluation Kit EVA2035-H allows an easy evaluation of Maestro's GPS antenna receiver module A2035-H by offering quick access to the ports of the module.

The EVA2035-H serves three major purposes:

- As a demonstration package of the module's capabilities
  Powering the A2035-H GPS receiver module via the USB connector with sufficient view to the sky will result in an NMEA output with position information.

- As an example how to integrate the module into a system
  The schematic in chapter "10 Board Schematics" is a basic example of how to integrate the GPS module into an application or system.

- To support an easy temporary design in
  The signals provided on the Evaluation Kit allow direct integration into a surrounding system making it an ideal development tool.

The firmware provided on the A2035-H delivered with the EVA2035-H is identical to the standard firmware delivered on single A2035-H GPS antenna receiver modules.

1.2 Contents

The EVA2035-H includes the following components:

- Demonstration board (labeled EVA2035-H)
- USB cable to connect to your PC
- CD with complete documentation and Maestro's GPS Cockpit software

Please check your package for completeness and connect the components properly.

2 Handling Precautions

The EVA2035-H contains components that are sensitive to electrostatic discharge (ESD). Please handle with appropriate care.

3 Quick Start (using USB connection)

(1) Connect the EVA2035-H with your PC using the included USB cable.

(2) When the PC asks for drivers select the folder "Tools\Drivers" on the included CD ROM. Note that two drivers need to be installed, the EVA2035-H FTDI driver and the USB serial driver.

> **Note**: During the driver installation process your Windows system will probably notify you, that the driver did not pass Windows logo testing with a warning:
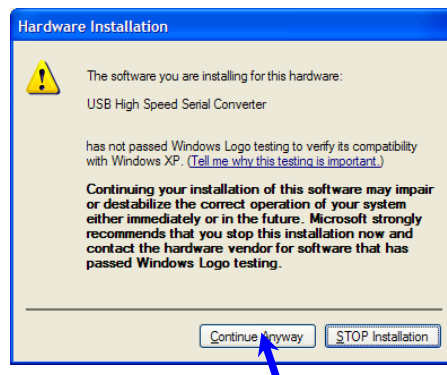

Figure 1: Windows driver installation warning

> **Note**: After successful driver installation Windows might interpret the data coming over the serial interface as a serial ballpoint mouse! Your mouse pointer can start jumping around. To stop this, disable the according device using your device manager. Leave the EVA2035-H kit connected and press and keep pressing the reset button. You will find the device under "Mice and other pointing devices". Use a right click to open the sub-menu and disable the device.
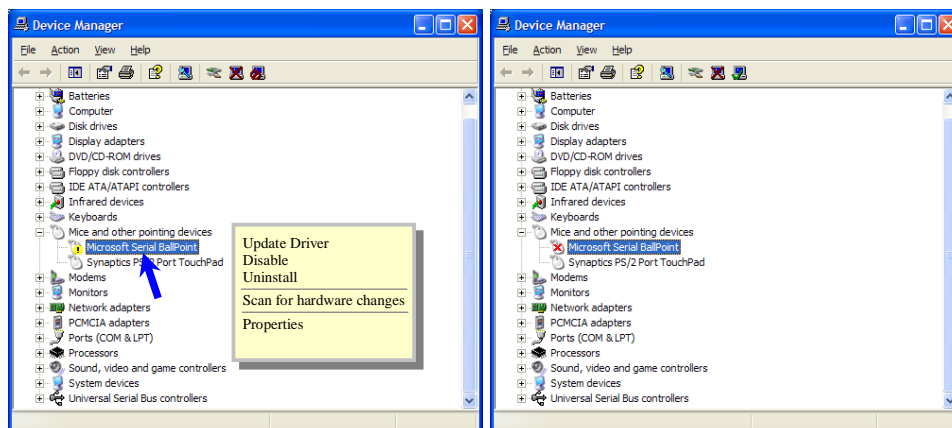

Figure 2: Disabling of Microsoft Serial BallPoint

(3) Assure that the on-module GPS antenna has a good view to the sky!

(4) To start the GPS Cockpit software which visualizes the NMEA output data coming from the GPS receiver, copy all files from the included CD ROM "Tools/GPS Cockpit" to a folder of you choice on your PC. Then double click the GPSC.exe file. The GPS cockpit software starts without additional software installation.

(5) Now you need to activate the correct port within GPS Cockpit. You can do this by selecting "COM port connection". A detailed description of the GPS Cockpit software is included on the CD ROM. In any case, the following window will appear:
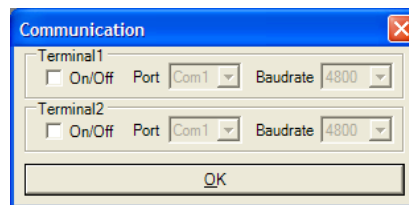
Figure 3: GPS Cockpit communication window - blank

Activate "Terminal 1", choose the COM port to which the GPS receiver is connected (verify in your system settings - device manager, which communication port is used for this USB serial connection), in our example COM2 at 4800 baud (default setting for the EVA2035-H), and click on "OK":
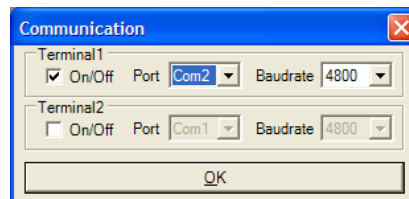
Figure 4: GPS Cockpit communication window – COM2

The connection is established now.

(6) Open a terminal window to see NMEA sentences by using the "NMEA Terminal" window button. You should then see messages like this:
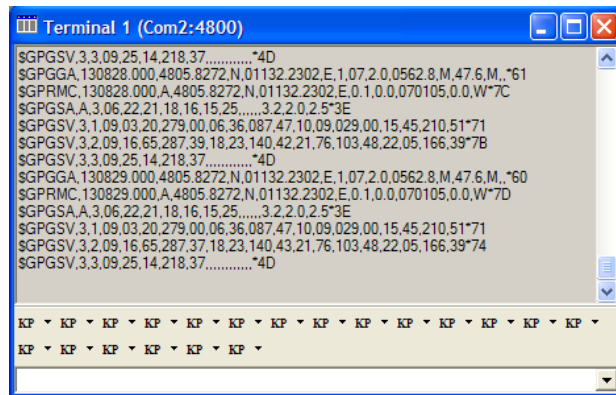
Figure 5: GPS Cockpit NMEA terminal with NMEA data

Now you can start using all the other windows and features of GPS Cockpit. Please refer also to the GPS Cockpit manual and the online help within GPS Cockpit.

4 On-Board Peripherals

4.1 RESET and ON_OFF Push-Button

The EVA2035-H holds two push-buttons:

- nRST (RESET)
- ON_OFF

After power on by pushing the "ON" button will start the A2035-H module. This is absolutely necessary to get the module going. The "ON" button must be used as well in other cases, e.g. in order to request a position when in SiRFawareTM state or to go to hibernate mode and wake up again.
The "nRST" button is used to get a full reset of the GPS module. All parameters are stored in non-volatile memory. After pushing this button the module starts again from the beginning.

4.2 Antenna

The A2035-H supports one antenna input:
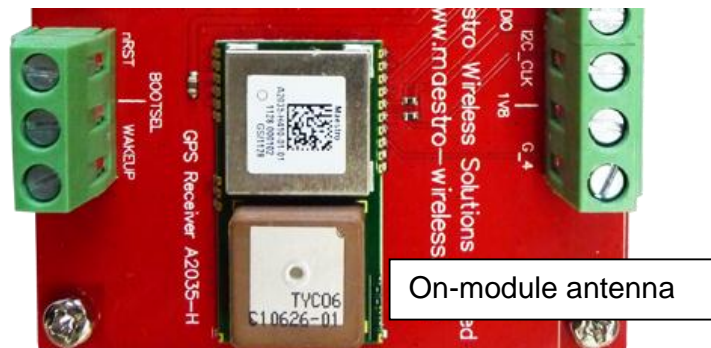
- The on-module antenna.

On-module antenna

Figure 6: On-module antenna

Further information is given in

- Maestro's GPS Receiver A2035-H User Manual

5 LED's

There are 6 LEDs on the EVA2035-H that indicate different signals from the GPS receiver (order of LED's on EVA2035-H from left to right):

LED	Name	Function	Description
LD2	RX	Receive	Serial data traffic (into GPS receiver)
LD1	TX	Transmit	Serial data traffic (from GPS receiver)
LD4	ON_OFF	Hibernate	Toggle hibernate mode / position request during PTF cycle (the LED visualizes the ON_OFF pulse)
LD3	1PPS	Timing	1PPS signal at rising edge (1 pulse per second, duration 500ms typ.)
LD4	WAKEUP	Operational state	HIGH: Full operation LOW: Module in a low power mode
LD6	Power / VCC	POWER	Power on LED

Table 1: LED's function and description

Figure 7: EVA2035-H LED's

6 Design-in Support

The EVA2035-H demo board offers the possibility to implement the A2035-H GPS receiver module temporarily into your design by using the terminal block with 15 connections & a pad of 3V3. To operate the EVA2035-H via this terminal block, please check "Table 3: Switch settings".

Please note:
- VCC power input is **not** protected against reversed polarity
- External supply has to be within the range of 3.3 to 3.6 VDC

6.1 Terminal Block

The terminal block offers direct access to the A2035-H GPS receiver pins.

Pin	Port
1	GND
2	TX, SPI data out pin when module works in SPI mode
3	RX, SPI data in pin when module works in SPI mode
4	ON_OFF
5	1PPS (Pulse Per Second)
6	G_6 (GPIO6), SPI clock pin when module works in SPI mode
7	G_7 (GPIO7), SPI chip select pin when module works in SPI mode
8	EXTint
9	I2C_DIO
10	I2C_CLK
11	1V8(Output)
12	G_4
13	nRST (reset)
14	BOOTSEL
15	WAKEUP(operational mode)

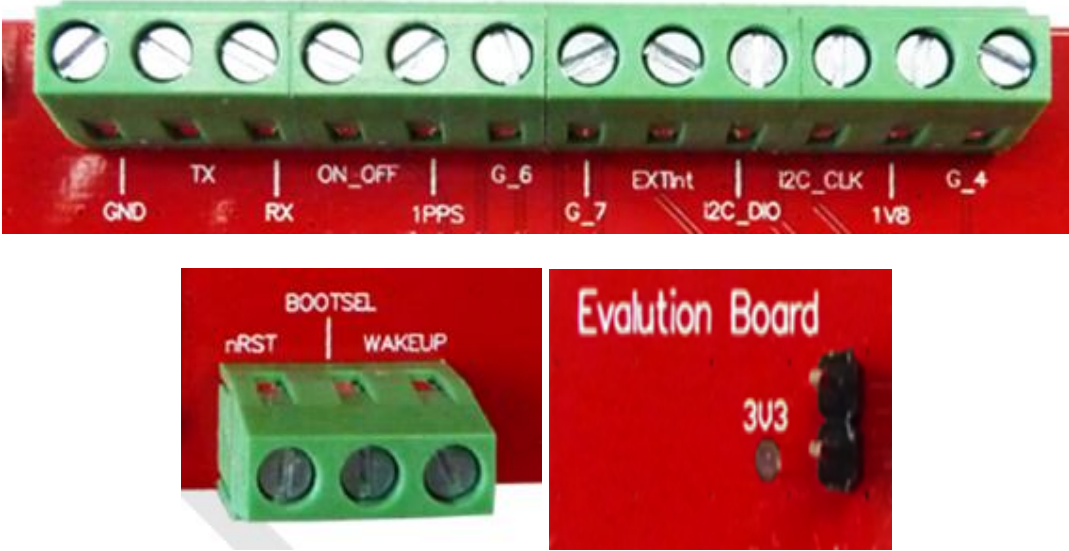Table 2: Terminal block description

Figure 8: Terminal block

6.2 DIP Switch Settings

The following picture shows the DIP switches of the EVA2035-H.

Figure 9: DIP switches

Switch	Function	Operation via USB connector (default settings)	Operation via terminal block
S1	VCC	ON	OFF
S2	TX	ON	OFF
S3	RX	ON	OFF
S4	ON_OFF	ON	OFF
S5	1PPS	ON	OFF
S6	GPIO6	ON	ON(*2)
S7	GPIO7	OFF	OFF(*2)
S8	BOOTSEL	OFF	OFF (*1)

Table 3: Switch settings

*1: The BOOT switch can be set to flash Firmware to the A2035-H GPS receiver. Switch the BOOTSEL switch to "ON", press and release the nRST button. The A2035-H is now waiting to receive new firmware data via UART. For the detail description &Firmware upgrade procedure,please refer to" Firmware up- grading for GPS Modules"application note.
After upgrading the firmware switch the BOOTSEL switch to "OFF" and press and release the nRST button for restarting normal GPS receiver operation.
Related software tool and documentation: SIRF_Flash

*2: Port Selection, Table 4 shows GPIO strapping for port selection.

Host Interface Type	GPIO7 Level	GPIO7 Pull	GPIO6 Level	GPIO6 Pull
Slave SPI	High	OPEN Weak in- ternal pull up	LOW	OPEN Weak in- ternal pull down
UART	High	OPEN Weak in- ternal pull up	HIGH	Strong external pull-up

Table 4: Switch settings

6.3 ICC Jumper

Figure 10: ICC jumper

As long as the VCC DIP switch is "ON" the ICC jumper is bridged. By putting the VCC DIP switch to the OFF position the current draw of the A2035-H GPS receiver can be measured directly by connecting a low resistance measurement device to the ICC jumper.

The low resistance measurement device should be connected before VCC is switched off!

7 NMEA Port

- Default setting: 4800 baud, 8 data bits, no parity, 1 stop bit, no flow control!
- Standard NMEA-0183 output on NMEA, baud rate selectable.
- Standard USB connectors

8 EVA2035-H Firmware and NMEA Sentences

See separate document **GPS Firmware** for a detailed description of the standard firmware loaded onto the modules delivered with the EVA2035-H.

9 Board Overview
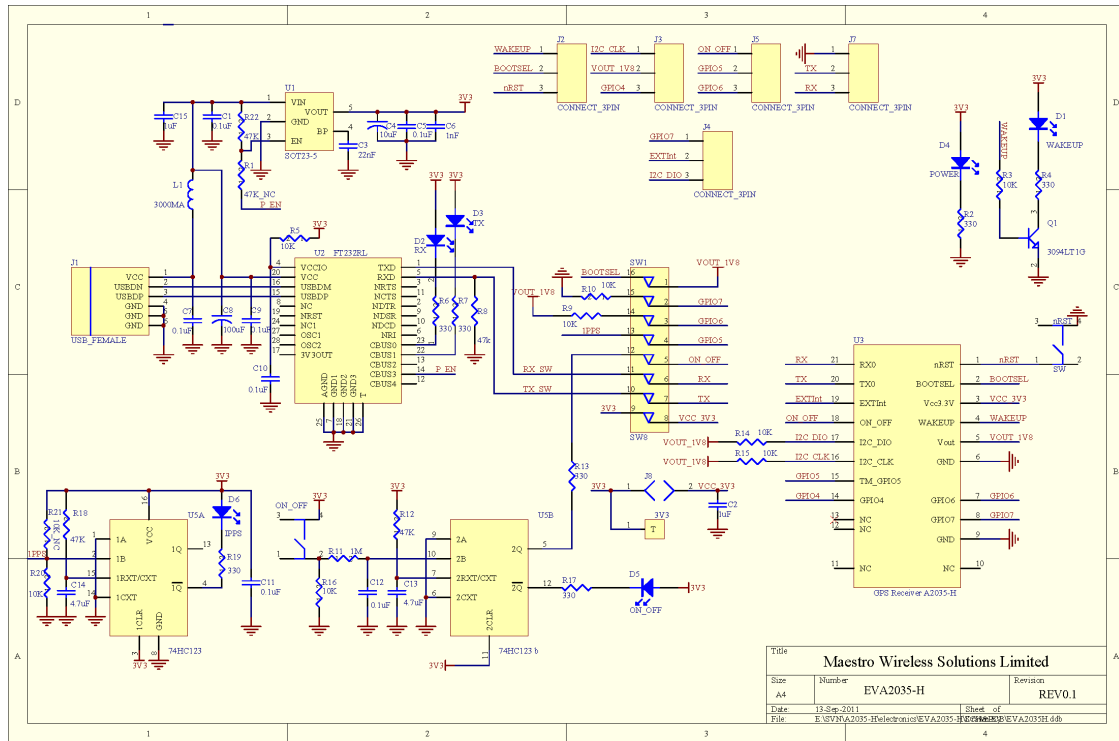

Figure 11: Board overview

10 Board Schematics

Figure 12: EVA2035-H board schematics

11 Related Information

11.1 Contact

This manual was created with due diligence. We hope that it will be helpful to the user to get the most out of the GPS module.

Inputs regarding errors or mistaken verbalizations and comments or proposals to Maestro, HongKong, for further improvements are highly appreciated.

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11.2 Related Documents

- GPS Receiver A2035-H (Maestro)
- Firmware upgrading for GPS Modules (Maestro)

11.3 Related Tools

- GPS Cockpit (Maestro)
- SiRFLive (SiRF)
- SiRF Flash(SiRF)

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