

# Ready™ for XMEGA®

Best solution for fast and simple development of applications using ATxmega128A1 device. With special white plastic casing you can quickly turn your Ready for XMEGA project into a final product.



**MikroElektronika**  
DEVELOPMENT TOOLS | COMPILERS | BOOKS



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Nebojsa Matic  
General Manager

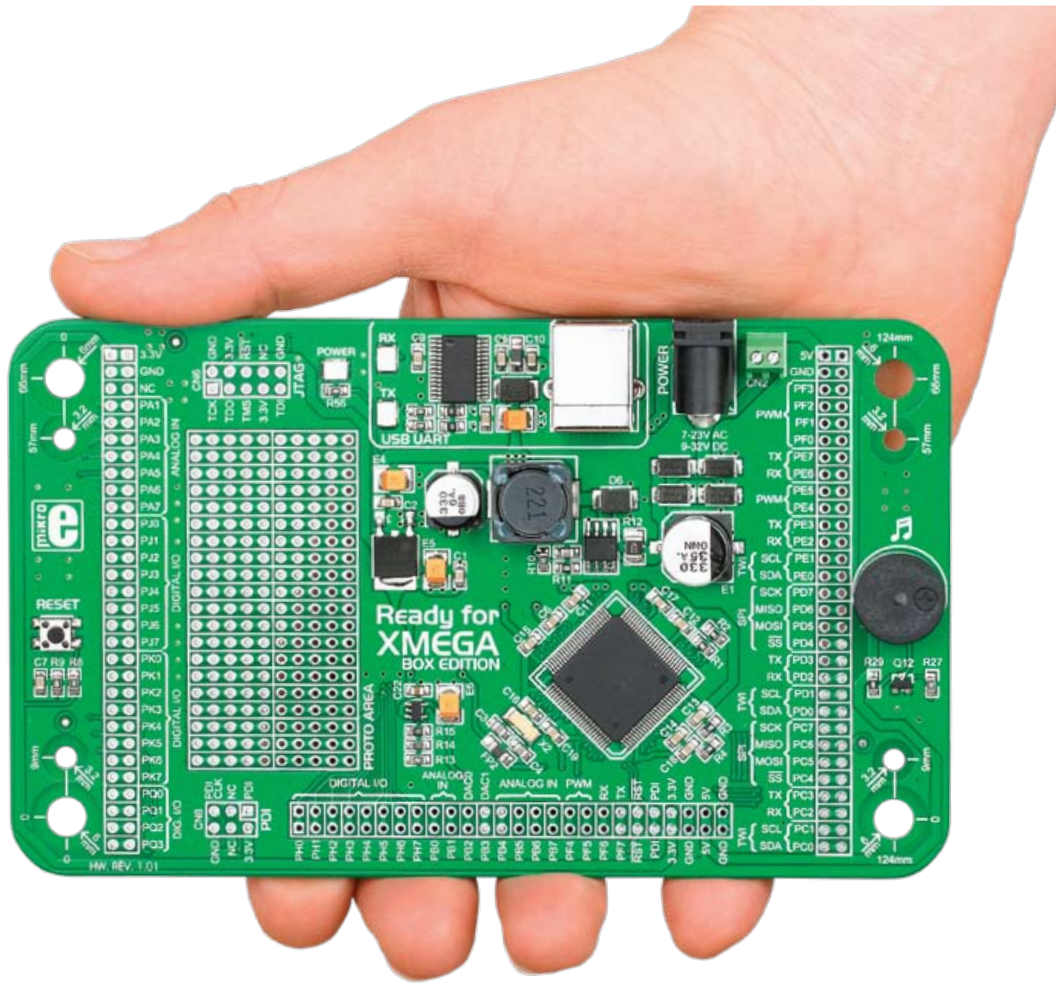
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# Introduction

Ready for XMEGA Board is the best solution for fast and simple development of various microcontroller applications. It comes with **ATxmega128A1**, and contains double-row smart headers for all available microcontroller ports. We have grouped pins according to their functions, so you have everything on the silkscreen. You don't even have to browse through the datasheet. Board also contains USB-UART module, prototyping area and a power supply circuit. Board is specially designed to fit into special white plastic casing so you can turn your XMEGA project into a final product.



# Package Contains



01 Damage resistant protective box



02 Ready for XMEGA board with double row male pin headers



03 DVD with documentation and examples



04 Ready for XMEGA user's guide



05 Ready for XMEGA schematic



06 USB cable

# Key Features

## System Specification



### power supply

Via AC/DC connector 7-23V AC or 9-32V DC



### power consumption

50mA in idle state  
(when on-board modules are off)



### board dimensions

141 x 84mm (5.55 x 3.3 inch)

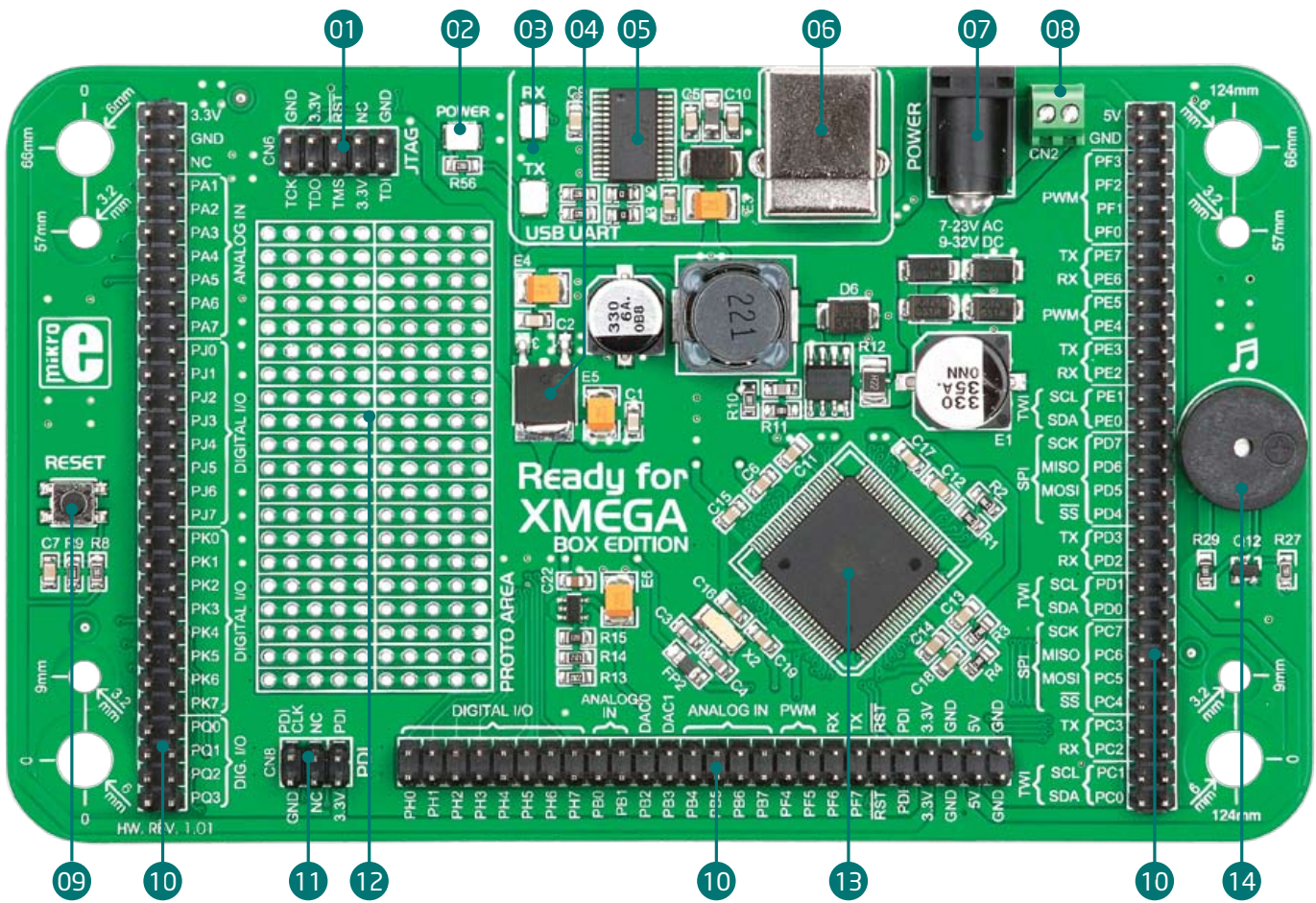


### weight

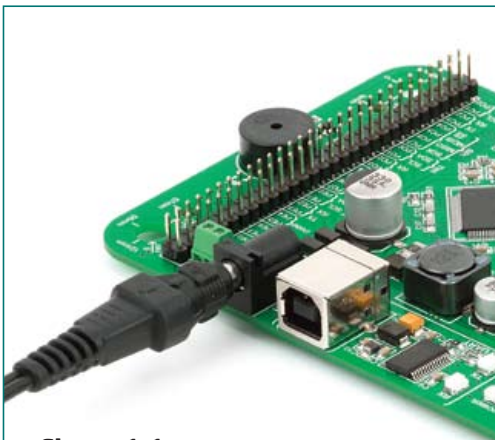
~67g (0.15 lbs)

- JTAG connector 01
- Power LED indicator 02
- UART communication LEDs (RX, TX) 03
- Power regulator 04
- FTDI chip 05
- USB UART connector 06
- Power connector 07
- Power screw terminals 08
- Reset button 09
- Double-row pin headers 10
- PDI connection 11
- Prototyping area 12
- ATxmega128A1 microcontroller 13
- Piezo Buzzer 14

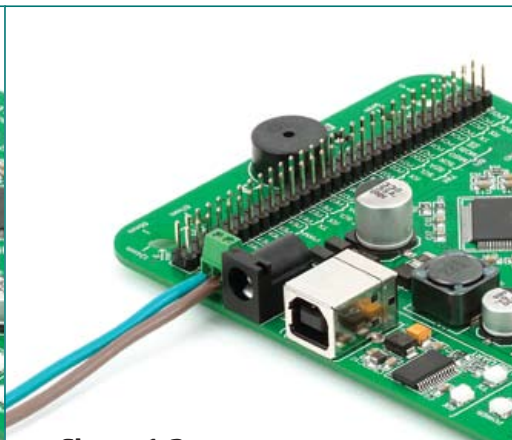




# 1. Power supply



**Figure 1-1:**  
AC/DC adapter power supply  
connected



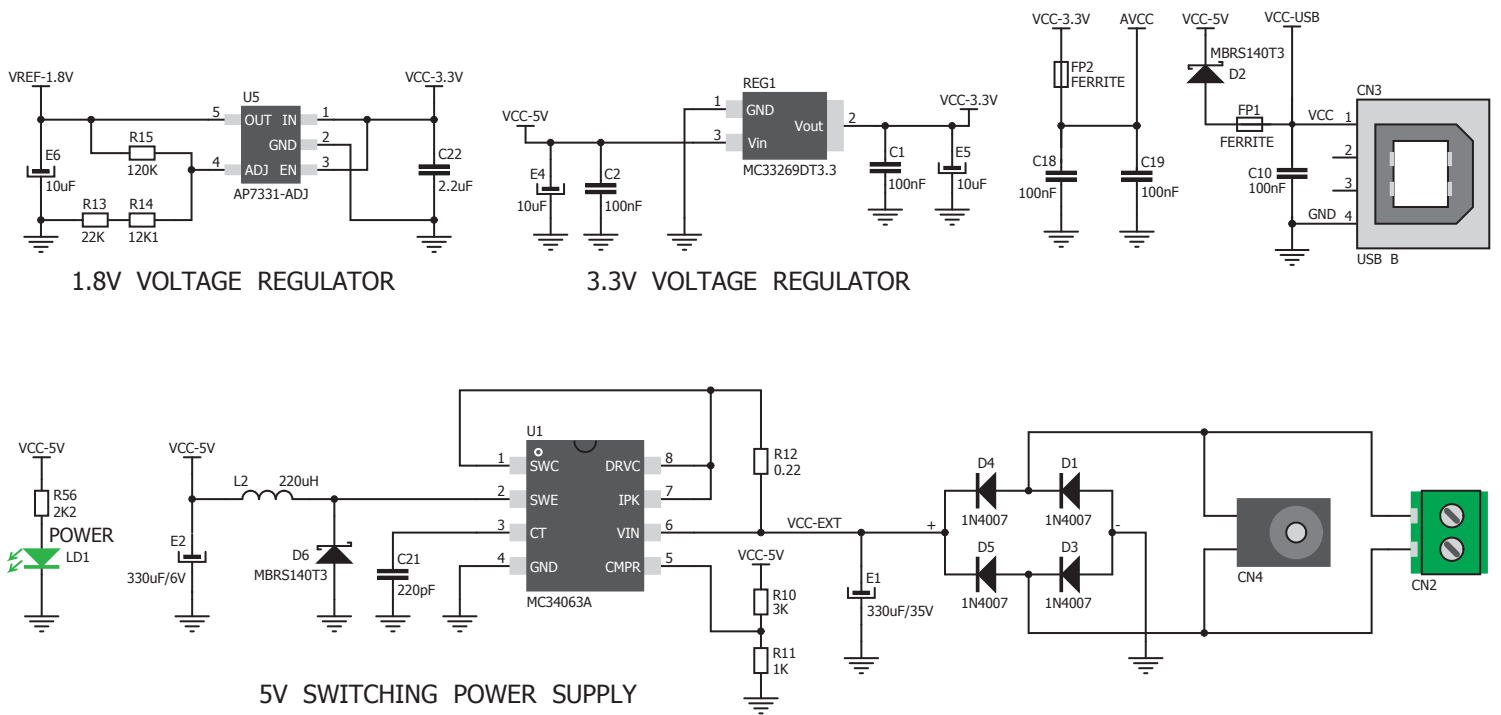
**Figure 1-2:**  
laboratory power supply  
connected to screw terminals



**Figure 1-3:**  
USB power  
supply connected

Ready for XMEGA board can be powered in two ways: via USB connection, or using external power sources such as adapters and laboratory power supplies. USB connection can provide up to 500mA of current which is more than enough for every on-board module and for operation of the microcontroller. If you decide to use external power supply, you can choose between AC/DC adapter connector or power screw terminals. Voltage values must be within **7-23V AC** or **9-32V DC** ranges. **Power LED (GREEN)** will indicate the presence of power supply. Use only one of suggested methods for powering the board.





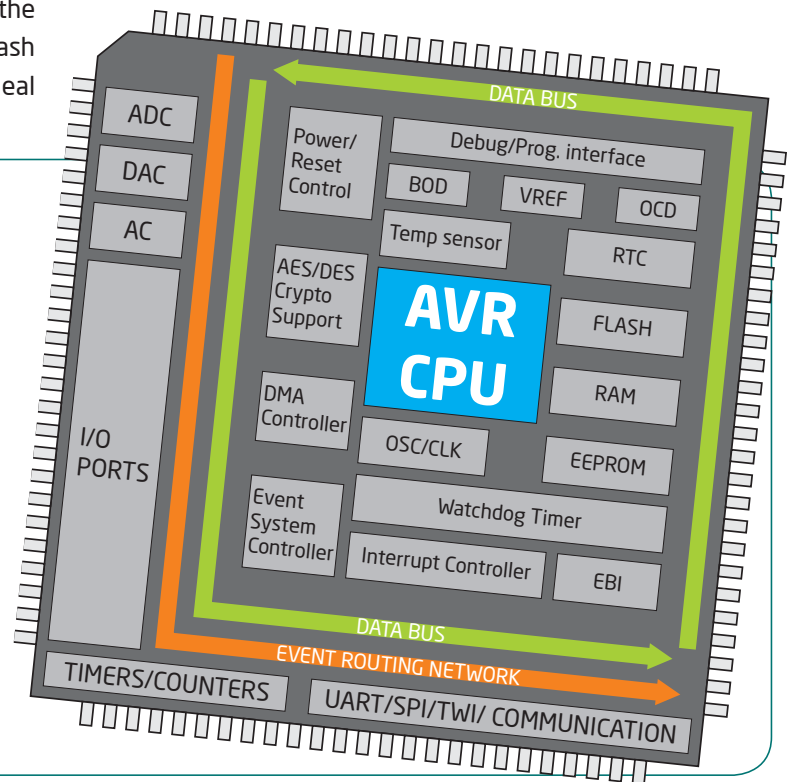
**Figure 1-4: Power supply schematics**

## 2. ATxmega128A1 microcontroller

Ready for XMEGA development system comes with the **ATxmega128A1** microcontroller. Having lots of MIPS power, flash and RAM, and rich set of integrated modules, ATxmega128A1 is ideal choice for both beginners and professionals.

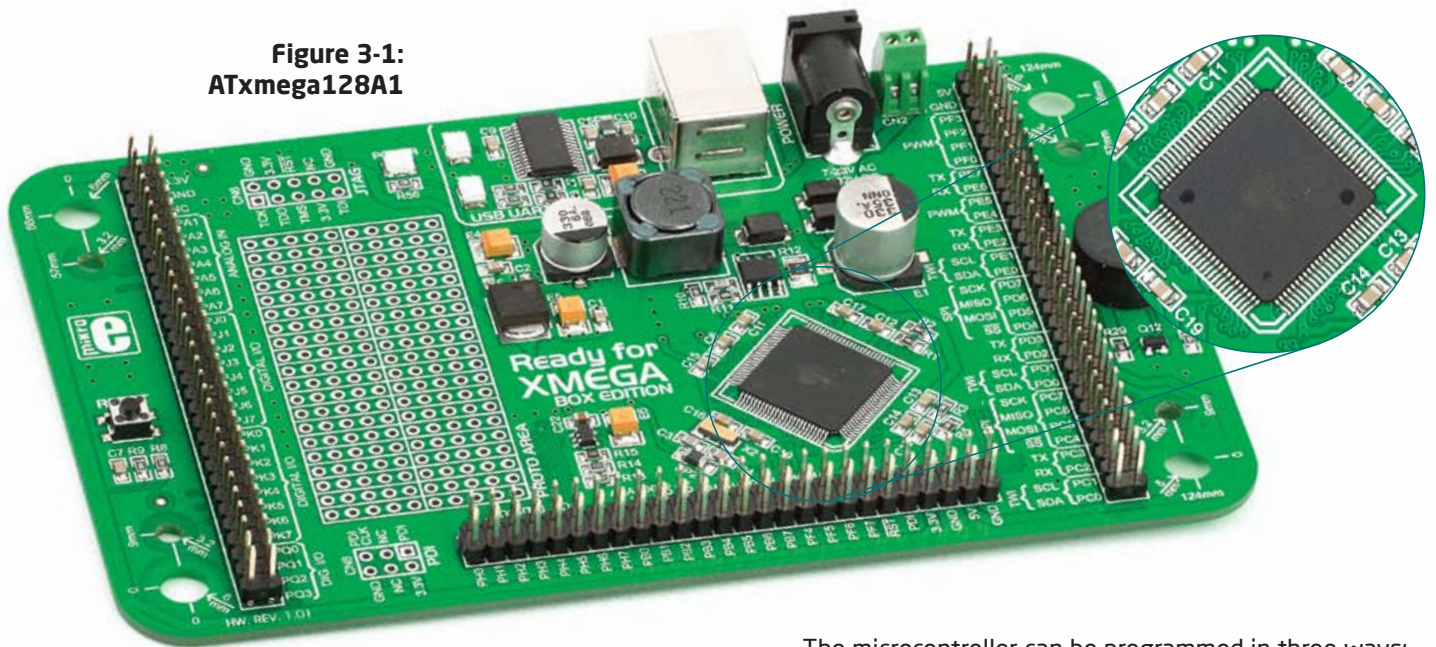
### Key microcontroller features

- Up to **32 MIPS** Operation;
- 8/16-bit architecture;
- 128KB of Flash memory;
- 8KB of SRAM memory;
- 2048Bytes of EEPROM;
- 78 I/O pins;
- 32kHz RTC;
- 1.6V to 3.6V Operating Voltage (VCC);
- UART, SPI, TWI;
- ADC, DAC, AC; etc.



## 3. Programming the microcontroller

Figure 3-1:  
ATxmega128A1




The microcontroller can be programmed in three ways:

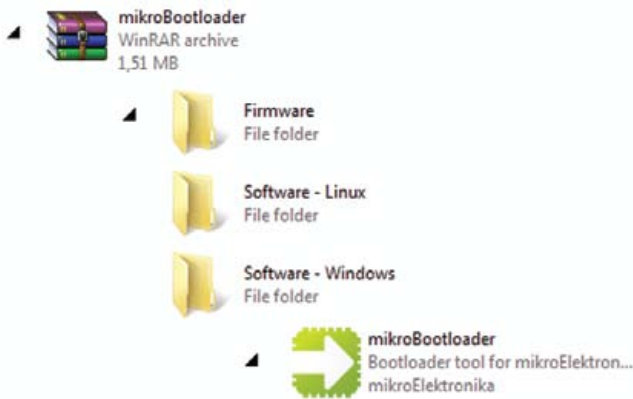
- 01 Via USB-UART mikroBootloader
- 02 Using JTAG external programmer
- 03 Using PDI external programmer

# Programming with mikroBootloader

You can program the microcontroller with bootloader which is preprogrammed into the device by default. To transfer .hex file from a PC to MCU you need bootloader software (**mikroBootloader USB HID**) which can be downloaded from:

 [http://www.mikroe.com/eng/downloads/get/1271/mikrobootloader\\_xmega\\_v101.zip](http://www.mikroe.com/eng/downloads/get/1271/mikrobootloader_xmega_v101.zip)

After software is downloaded, unrar it to a desired location, and start mikroBootloader USB HID software.



**note** This version of mikroBootloader is specialized for ATxmega128A1 chip.

## mikroBootloader software

**note** Before starting mikroBootloader software, connect Ready for XMEGA with a PC using USB cable provided with the package

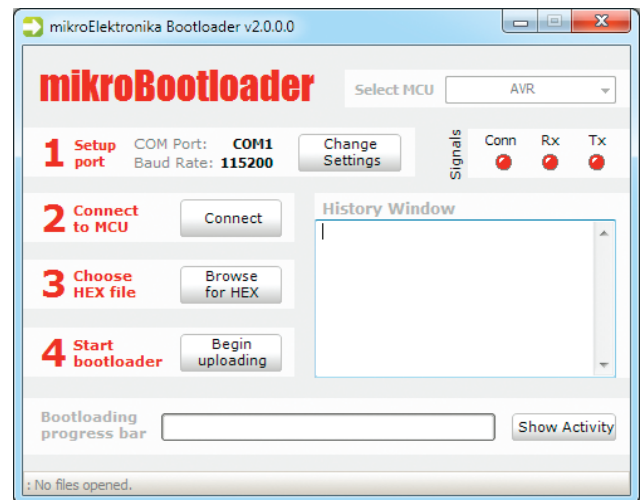


Figure 3-2: mikroBootloader window

01 When you start mikroBootloader software, a window shown on **Figure 3-2** should appear.

## Identifying device COM port

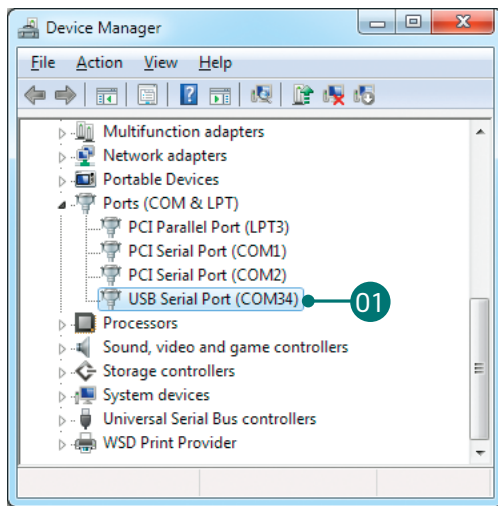


Figure 3-3: Identifying COM port

- 01 Open **Device Manager** window and expand **Ports section** to see which COM port is assigned to Ready for XMEGA board (in this case COM34)

## step 1 - Choosing COM port



Figure 3-4: Choosing COM port

- 01 Click the **"Change Settings"** button.
- 02 From the drop down list, select appropriate COM **port** which is used for communication with a PC
- 03 Click **OK**.



## step 2 - Establishing Connection

**note:** Baud rate is set to 115200bps by default.

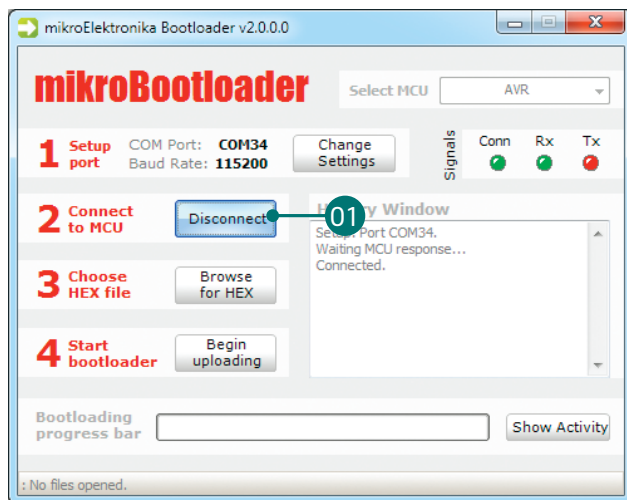


Figure 3-5: Connecting with mikroBootloader

- 01 Press **“Reset”** button on Ready for XMEGA board and click **“Connect”** button within 5s, otherwise existing microcontroller program will execute. If connected, caption on a button will be changed to **“Disconnect”**.

## step 3 - Browsing for .HEX file

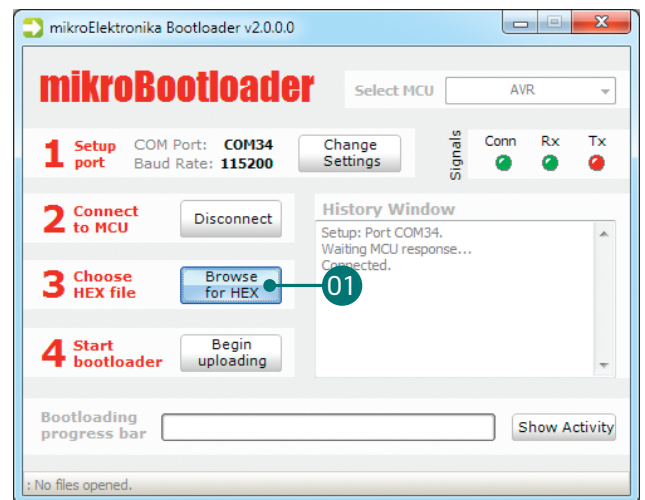


Figure 3-6: Browse for HEX

- 01 Click the **“Browse for HEX”** button and from a pop-up window (Figure 3.7) choose .HEX file which will be uploaded to MCU memory

## step 4 - Selecting .HEX file

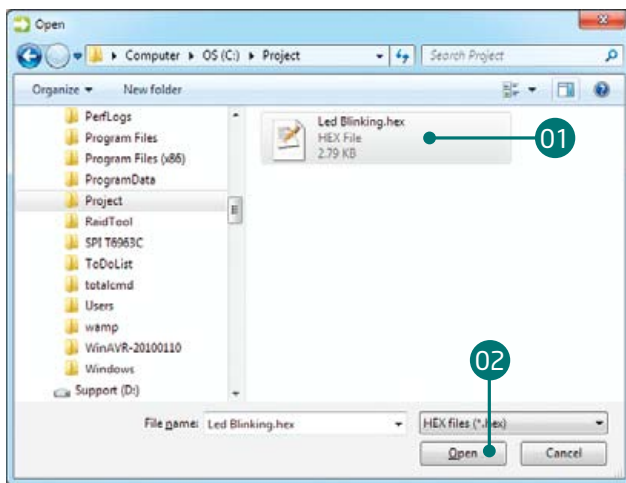


Figure 3-7: Locating and Selecting .hex file

- 01 Select .HEX file using open dialog window.
- 02 Click the "Open" button.

## step 5 - Uploading .HEX file

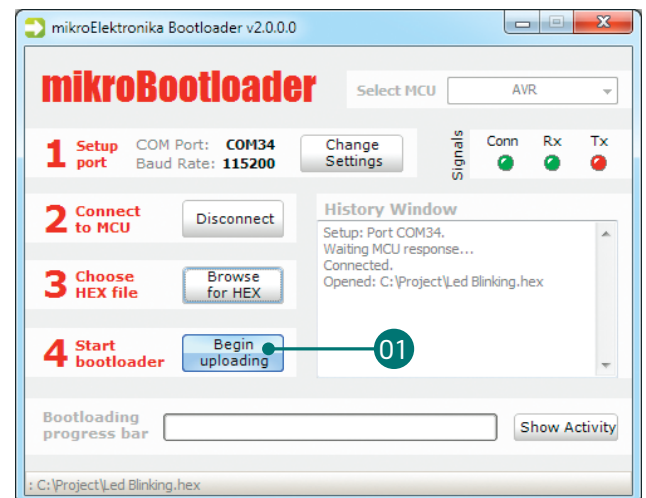


Figure 3-8: Begin uploading

- 01 To start .HEX file bootlodng click the "Begin uploading" button.

## step 6 - Progress bar

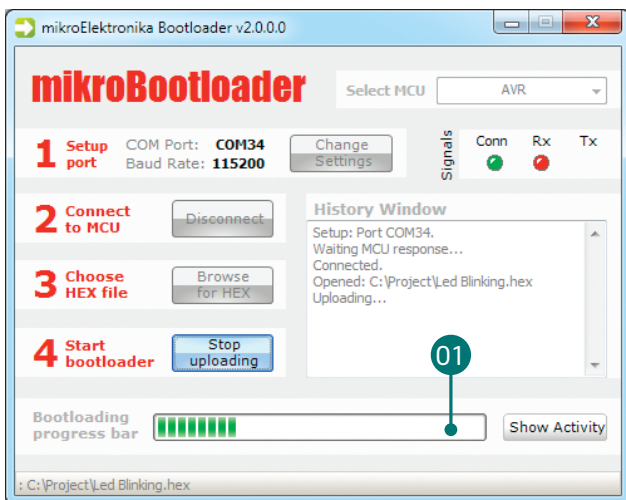


Figure 3-9: Progress bar

- 01 You can monitor .HEX file uploading via progress bar.

## step 7 - Finish upload

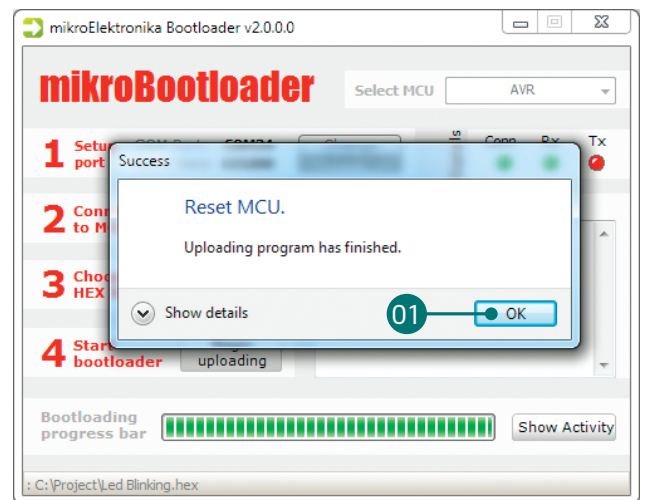


Figure 3-10: Restarting MCU

- 01 Click "OK" button after uploading is finished.
- 02 Press "Reset" button on Ready for XMEGA board and wait for 5 seconds. Your program will execute automatically.

# Programming with JTAG programmer

Figure 3-11:  
placing 10 pin header

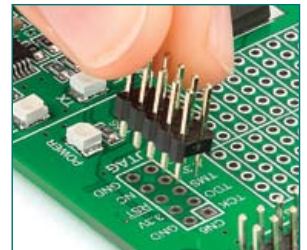


Figure 3-12:  
connecting JTAG  
programmer



Ready for XMEGA board contains **JTAG connector pads** so you can program the board and debug your code using external programmer/debugger. Before connecting the programmer you have to solder the provided **IDC10 2x5 male header** onto the board's JTAG connector pads. If bootloader program is accidentally erased, you can upload it again via AVR JTAG or PDI programmer. Ready for XMEGA Bootloader **Firmware.hex** can be found under Firmware folder (see page 12).

## Programming with PDI programmer

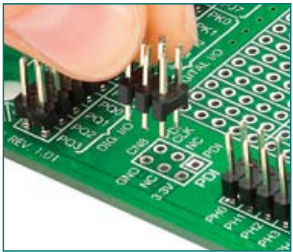


Figure 3-13:  
placing 6 pin header

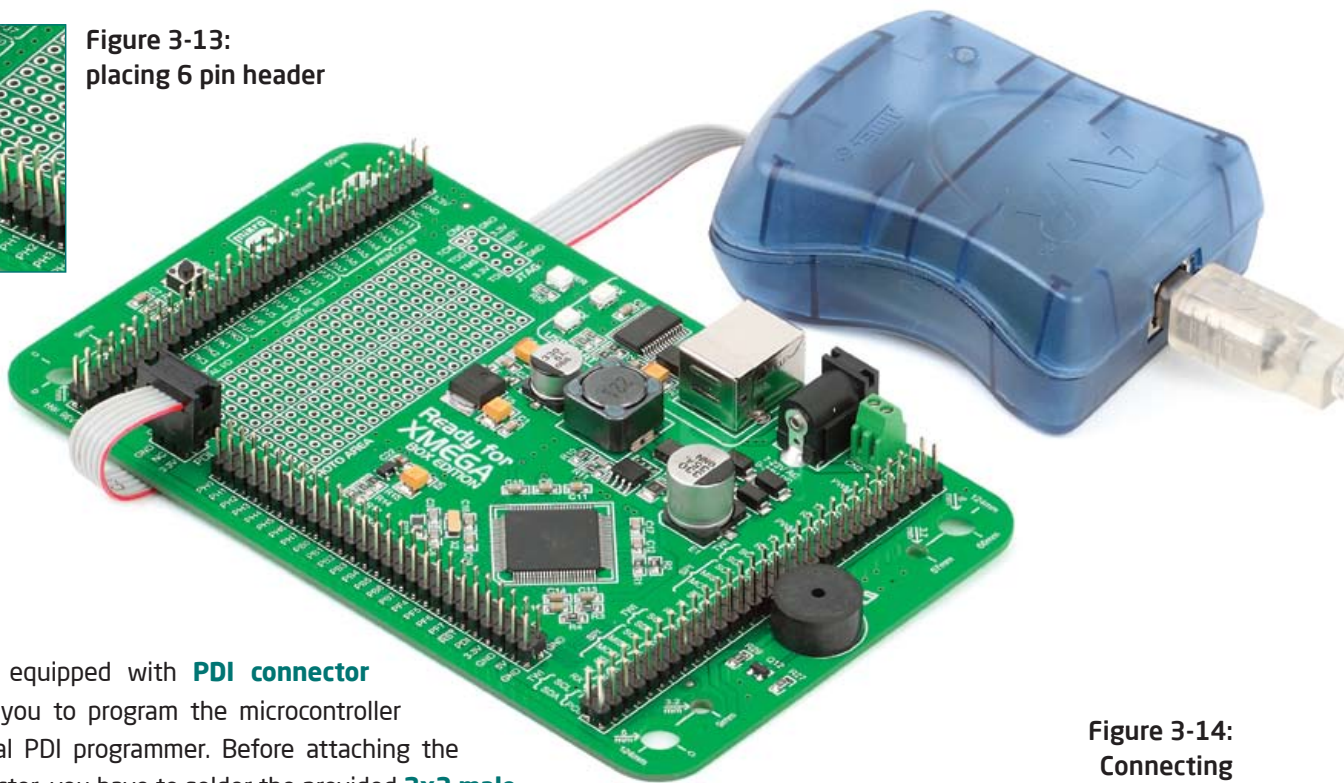


Figure 3-14:  
Connecting  
PDI programmer

The board is also equipped with **PDI connector pads**, which allow you to program the microcontroller using external serial PDI programmer. Before attaching the programming connector, you have to solder the provided **2x3 male header** to the board's PDI connector pads.



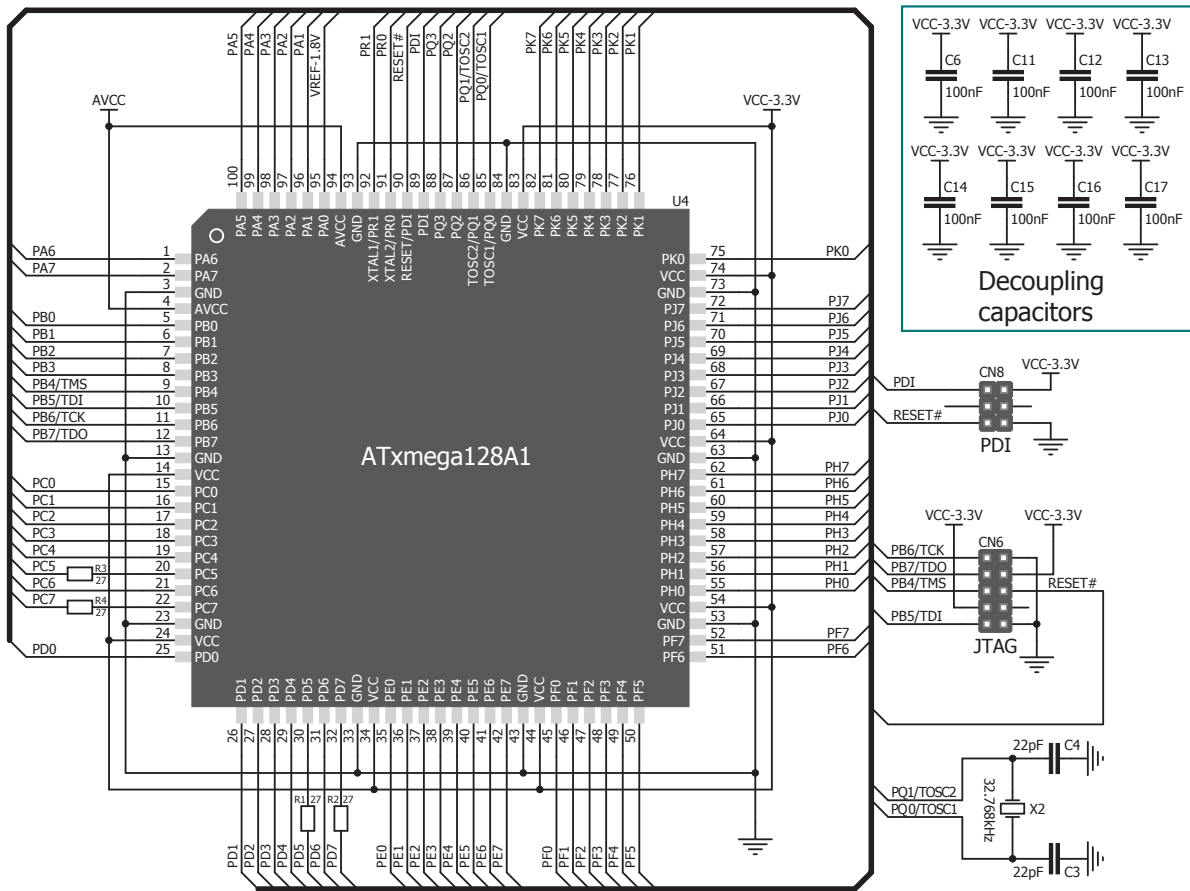


Figure 3-15: PDI & JTAG programmer connection schematics

## 4. USB-UART

Fast on-board **FTDI® chip** allows you to communicate with a PC or other UART devices using USB-UART connection. USB-B connector (**CN3**) is used for connecting the USB cable. RX (receive) and TX (transmit) LEDs will indicate communication status. Before connecting the board with the PC, make sure to have the appropriate **FTDI drivers** installed on your operating system. Drivers can be found at following URL:

<http://www.ftdichip.com/Drivers/VCP.htm>

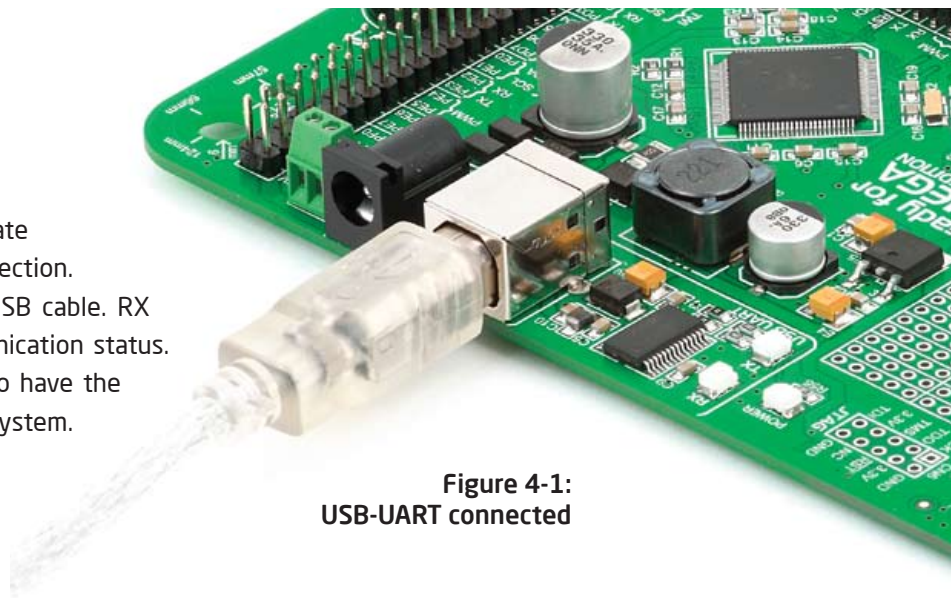


Figure 4-1:  
USB-UART connected

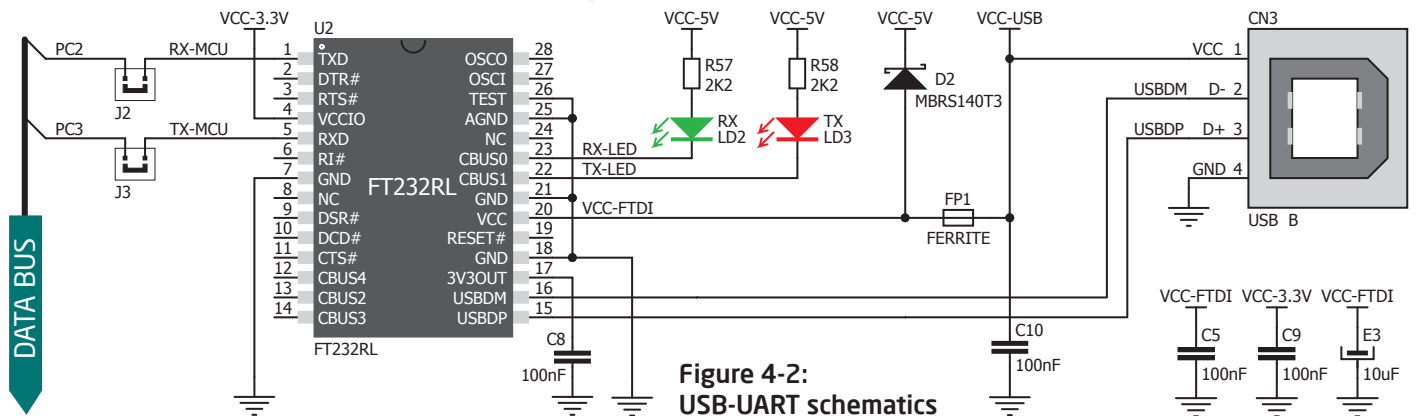
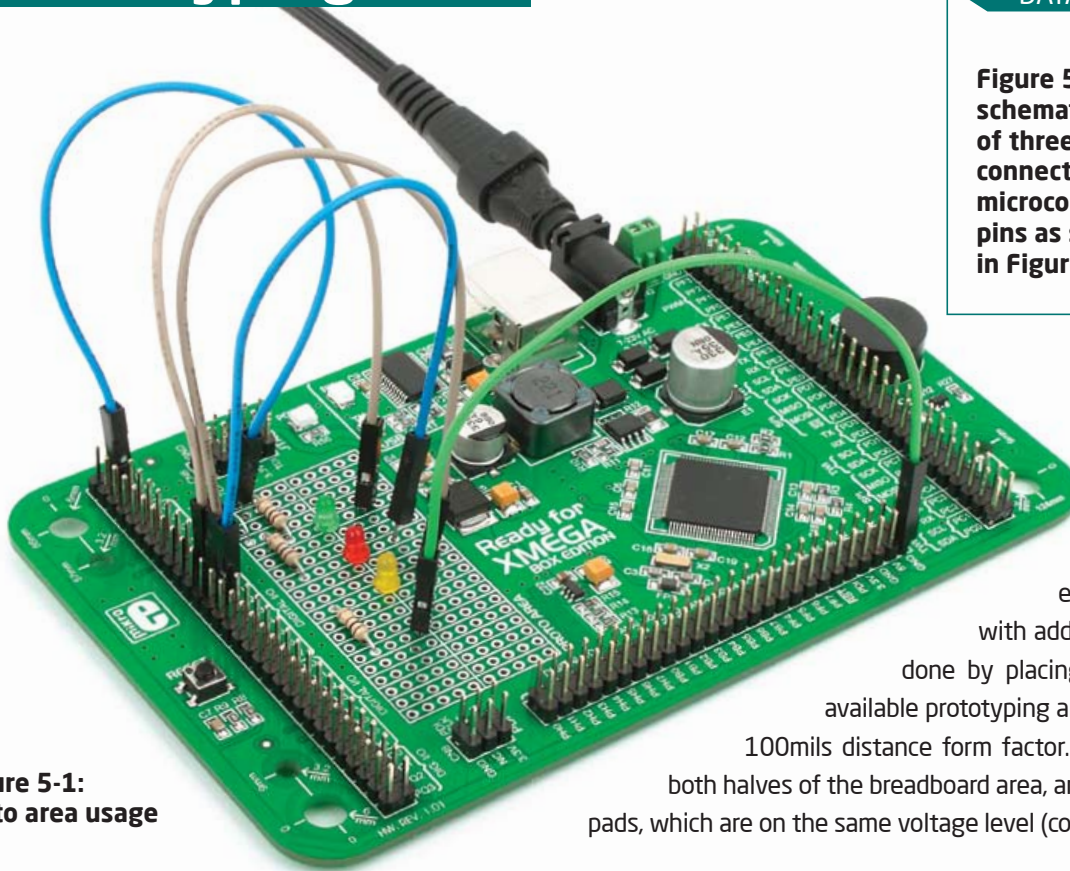
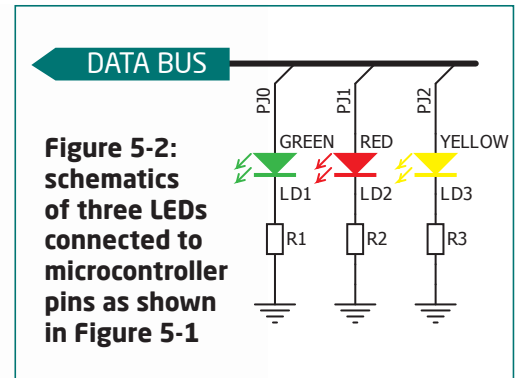


Figure 4-2:  
USB-UART schematics

## 5. Prototyping area

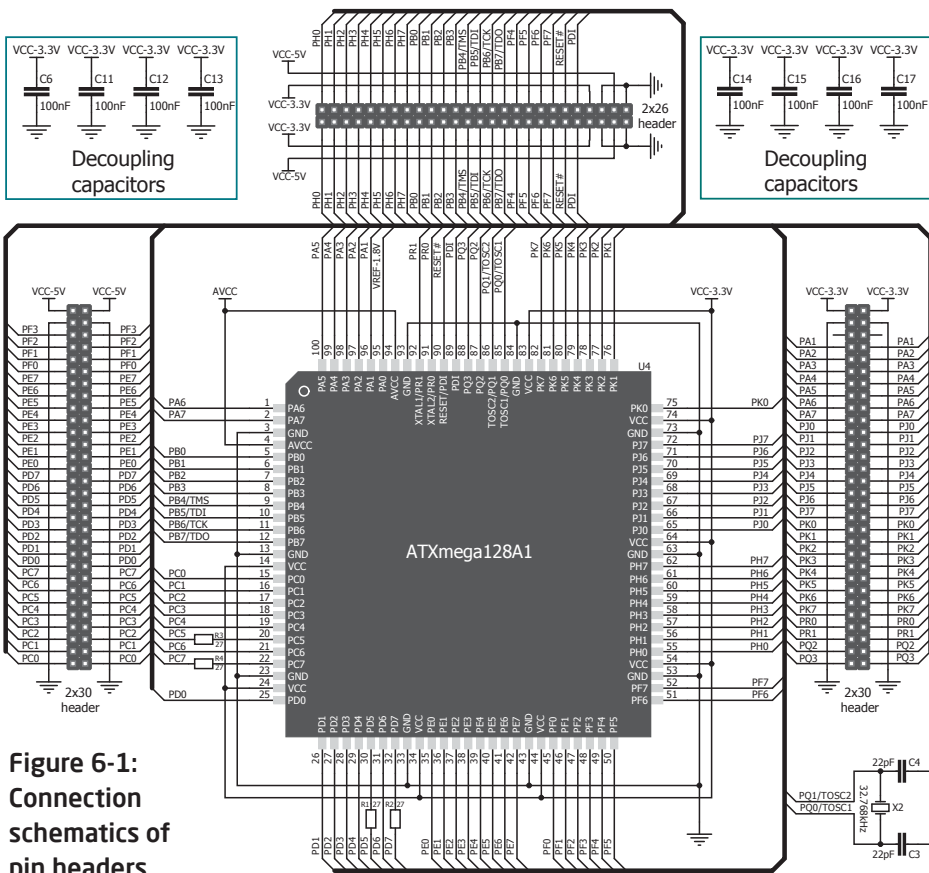


**Figure 5-1:**  
Proto area usage



**Proto area** allows you to expand your Ready for XMEGA board with additional functionalities. That can be done by placing your additional components on available prototyping area. Pads are arranged in standard 100mils distance form factor. There are 20 connected lines on both halves of the breadboard area, and each line consists of 5 soldering pads, which are on the same voltage level (connected to each other).

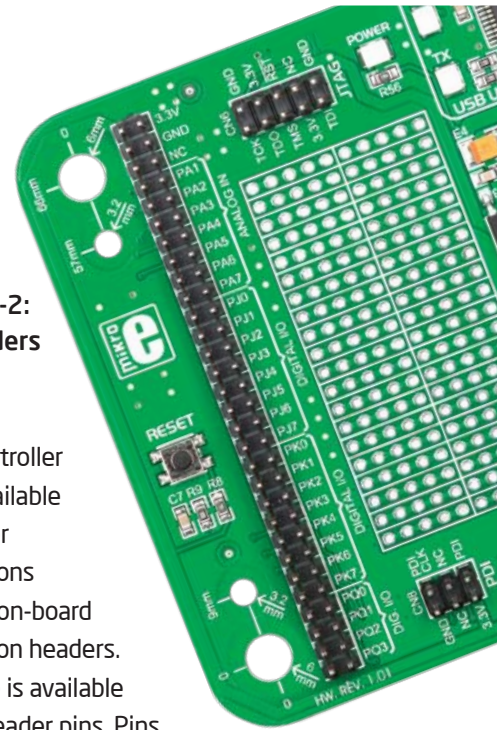
# 6. Pin headers



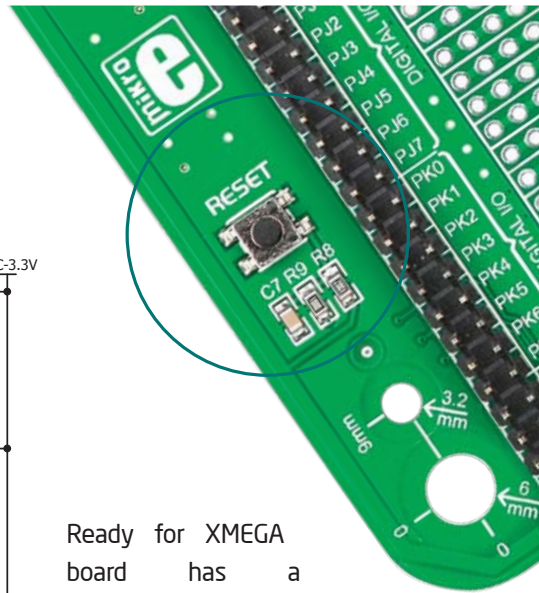
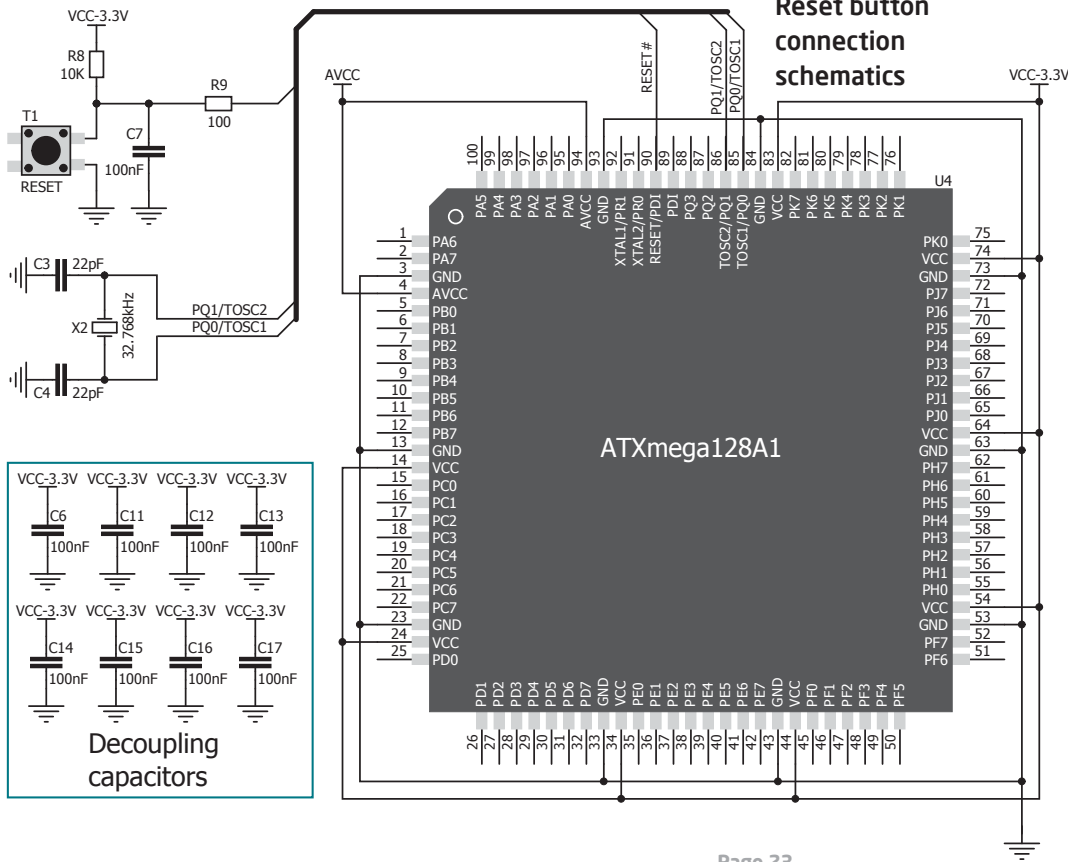
**Figure 6-1:**  
Connection  
schematics of  
pin headers

**Figure 6-2:**  
Pin headers

Each microcontroller pin is available for further connections through on-board connection headers. Each line is available in two header pins. Pins are grouped according to their functions, which makes development and connections much easier. Everything is printed on the silkscreen, so you won't even have to open the microcontroller datasheet while developing. Before using the pins, you have to solder the provided **2x30 and 2x26 male headers** onto the board's pads.



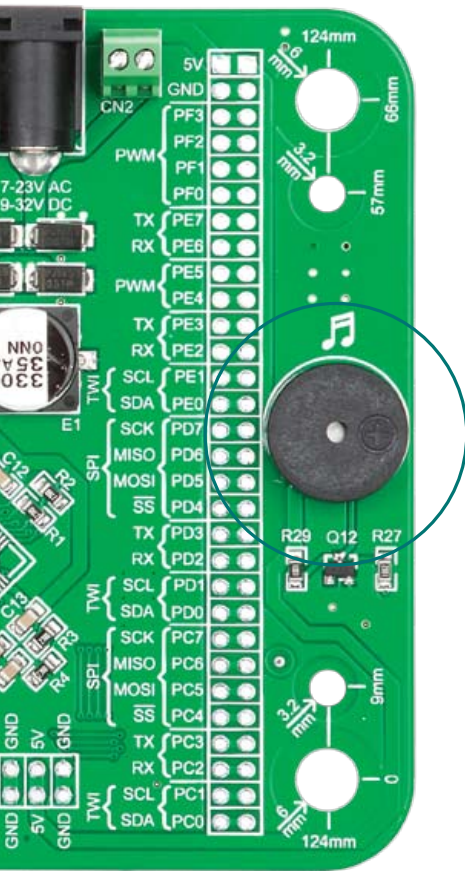
# 7. Reset button



Ready for XMEGA board has a specialized reset circuit with high-quality reset button, which can be used to reset the program execution of the microcontroller. If you want to reset the circuit, press on-board RESET button. It will generate low voltage level on microcontroller reset pin (input). In addition, a reset can be externally provided through **RST pin** on 2x26 header (**Figure 6-1**).



# 8. Piezo buzzer



On-board piezo buzzer is a very useful module which can be used in debugging your code, or to have audio signalization feature when board is integrated as a final product. Piezo buzzer's resonant frequency is 3.8kHz. In addition, other frequencies in the range between 20Hz and 20.000Hz can be used, but the best performance is provided by frequencies ranging between 2kHz and 4kHz.

Figure 8-1: Piezo buzzer

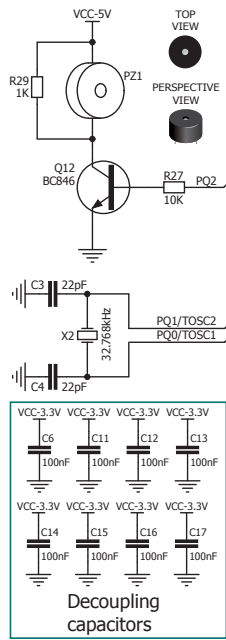
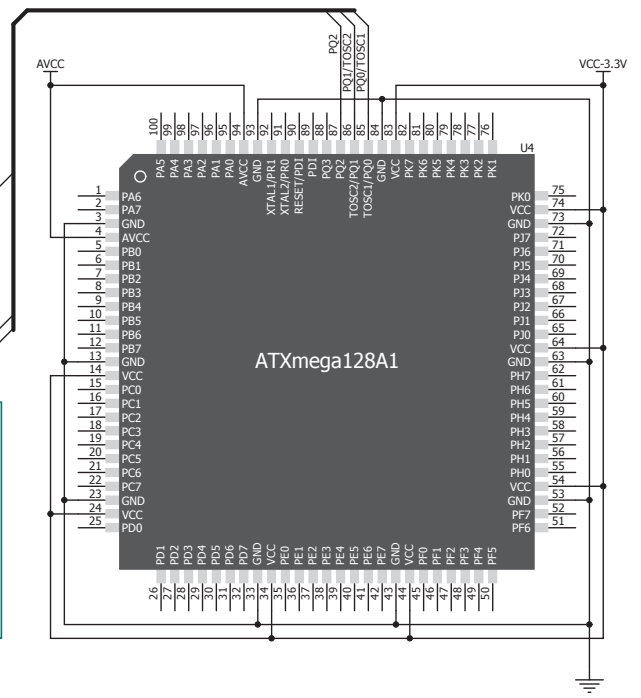
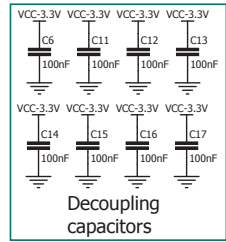


Figure 8-2: Piezo buzzer connection schematics



## 9. Integrating with the casing



**Figure 9-1:**  
Place the board into the bottom part of the casing. Make sure to align the connectors with the square openings



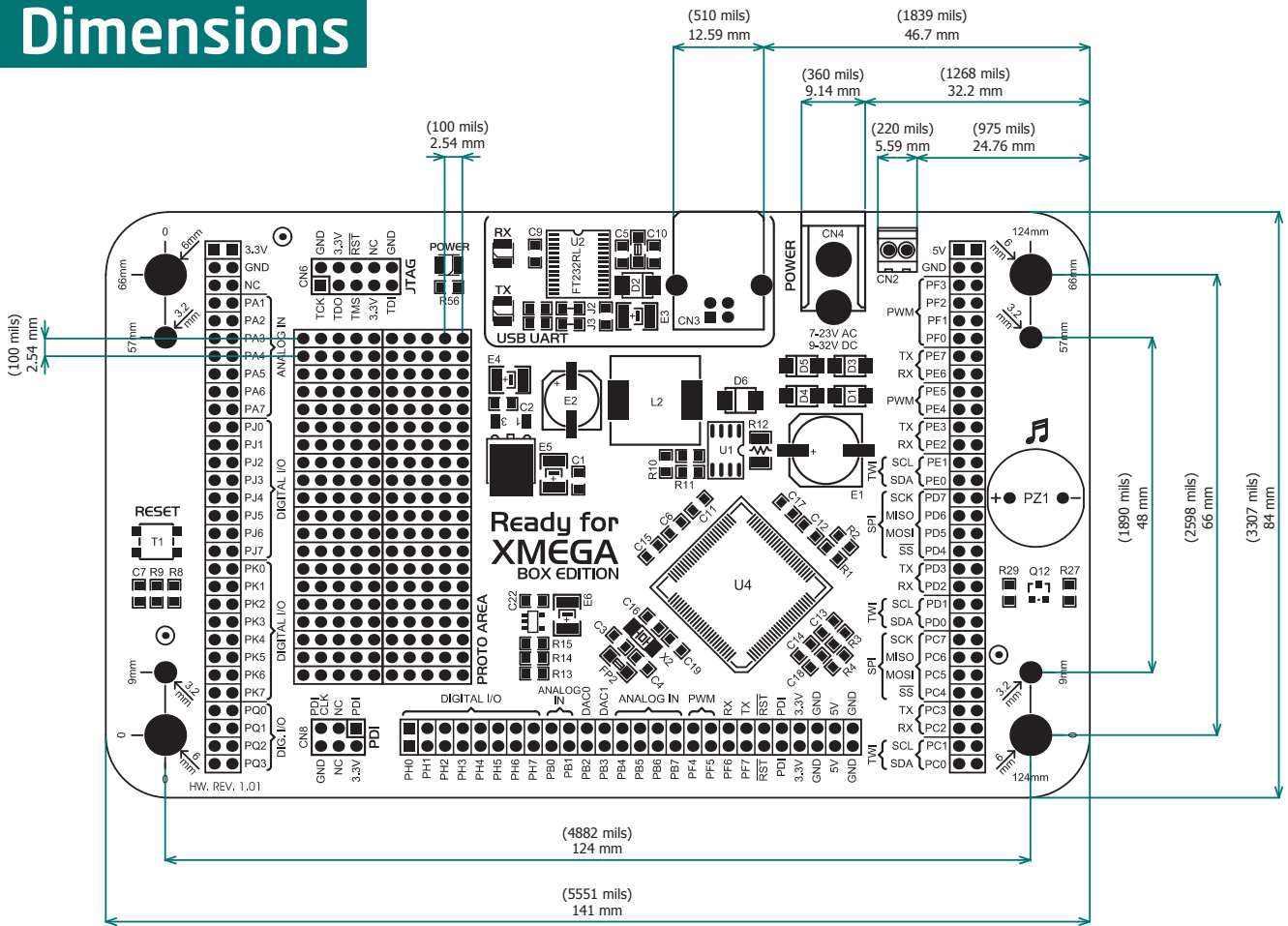
**Figure 9-2:**  
Wind screws into inner screw holes to mount the board to the bottom casing plastic



**Figure 9-2:**  
Place cover casing plastic and wind screws into outer screw holes for connecting it with bottom plastics

Ready for XMEGA can easily be integrated into the specialized white plastic casing. This feature is very convenient for turning the board into a final product. The white plastic casing contains inner and outer screw holes. Inner are used for attaching the board to the casing and outer are used for connecting the top part of the casing, and enclosing the board. Casing comes with holes for USB and power adapter connector, but you can customize it by drilling and cutting holes in specific areas, depending on the target application.

# 10. Dimensions



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