# 74AUP1Z04

# Low-power X-tal driver with enable and internal resistor

Rev. 5 — 9 August 2012

**Product data sheet** 

### 1. General description

The 74AUP1Z04 combines the functions of the 74AUP1GU04 and 74AUP1G04 with enable circuitry and an internal bias resistor to provide a device optimized for use in crystal oscillator applications.

When not in use the  $\overline{EN}$  input can be driven HIGH, putting the device in a low power disable mode with X1 pulled HIGH via R<sub>PU</sub>, X2 set LOW and Y set HIGH. Schmitt trigger action at the  $\overline{EN}$  input makes the circuit tolerant to slower input rise and fall times across the entire V<sub>CC</sub> range from 0.8 V to 3.6 V.

This device is fully specified for partial power-down applications using  $I_{OFF}$  at output Y. The  $I_{OFF}$  circuitry disables the output Y, preventing the damaging backflow current through the device when it is powered down.

The integration of the two devices into the 74AUP1Z04 produces the benefits of a compact footprint, lower power dissipation and stable operation over a wide range of frequency and temperature.

#### 2. Features and benefits

- Wide supply voltage range from 0.8 V to 3.6 V
- High noise immunity
- ESD protection:
  - ♦ HBM JESD22-A114F Class 3A exceeds 5000 V
  - ◆ MM JESD22-A115-A exceeds 200 V
  - ◆ CDM JESD22-C101E exceeds 1000 V
- Latch-up performance exceeds 100 mA per JESD78B Class II
- Inputs accept voltages up to 3.6 V
- Low noise overshoot and undershoot < 10 % of V<sub>CC</sub>
- I<sub>OFF</sub> circuitry provides partial Power-down mode operation at output Y
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C



#### Low-power X-tal driver with enable and internal resistor

# 3. Ordering information

Table 1. Ordering information

Type number	Package						
	Temperature range	Name	Description	Version			
74AUP1Z04GW	-40 °C to +125 °C	SC-88	plastic surface-mounted package; 6 leads	SOT363			
74AUP1Z04GM	–40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 $\times$ 1.45 $\times$ 0.5 mm	SOT886			
74AUP1Z04GF	–40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 $\times$ 1 $\times$ 0.5 mm	SOT891			
74AUP1Z04GN	–40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body $0.9 \times 1.0 \times 0.35$ mm	SOT1115			
74AUP1Z04GS	–40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body $1.0 \times 1.0 \times 0.35$ mm	SOT1202			

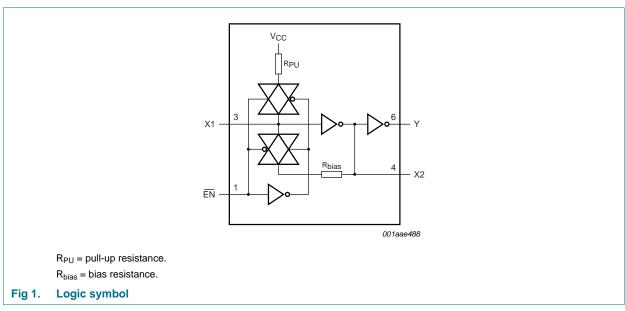
# 4. Marking

Table 2. Marking

Type number	Marking code <sup>[1]</sup>
74AUP1Z04GW	a4
74AUP1Z04GM	a4
74AUP1Z04GF	a4
74AUP1Z04GN	a4
74AUP1Z04GS	a4

<sup>[1]</sup> The pin 1 indicator is located on the lower left corner of the device, below the marking code.

# 5. Functional diagram



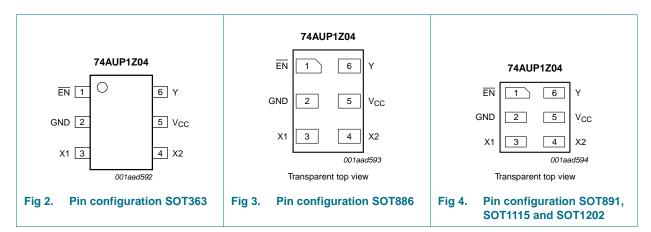
74AUP1Z04

All information provided in this document is subject to legal disclaimers.

Low-power X-tal driver with enable and internal resistor

# 6. Pinning information

### 6.1 Pinning



### 6.2 Pin description

Table 3. Pin description

Symbol	Pin	Description
EN	1	enable input (active LOW)
GND	2	ground (0 V)
X1	3	data input
X2	4	data output
V <sub>CC</sub>	5	supply voltage
Υ	6	data output

# 7. Functional description

Table 4. Function table[1]

Input X1		Output		
EN	X1	X2	Υ	
L	L	Н	L	
L	Н	L	Н	
Н	L	Н	L	
Н	Н	L	Н	

<sup>[1]</sup> H = HIGH voltage level; L = LOW voltage level.

#### Low-power X-tal driver with enable and internal resistor

# 8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC}$	supply voltage		-0.5	+4.6	V
I <sub>IK</sub>	input clamping current	$V_I < 0 V$	-50	-	mA
$V_{I}$	input voltage		<u>[1]</u> –0.5	+4.6	V
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V	-50	-	mA
Vo	output voltage		<u>[1]</u> –0.5	$V_{CC} + 0.5$	V
Io	output current	$V_O = 0 V \text{ to } V_{CC}$	-	±20	mA
I <sub>CC</sub>	supply current		-	50	mA
$I_{GND}$	ground current		-50	-	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$	[2] _	250	mW

<sup>[1]</sup> The minimum input and output voltage ratings may be exceeded if the input and output current ratings are observed.

## 9. Recommended operating conditions

Table 6. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC}$	supply voltage		8.0	3.6	V
VI	input voltage		0	3.6	V
Vo	output voltage		0	$V_{CC}$	V
T <sub>amb</sub>	ambient temperature		-40	+125	°C
Δt/ΔV	input transition rise and fall rate	V <sub>CC</sub> = 0.8 V to 3.6 V	-	200	ns/V

<sup>[2]</sup> For SC-88 packages: above 87.5 °C the value of P<sub>tot</sub> derates linearly with 4.0 mW/K. For XSON6 packages: above 118 °C the value of P<sub>tot</sub> derates linearly with 7.8 mW/K.

### Low-power X-tal driver with enable and internal resistor

### 10. Static characteristics

Table 7. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
<b>T</b> <sub>amb</sub> = 2	5 °C					
$V_{IH}$	HIGH-level input voltage	X1 input				
		$V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	$0.75 \times V_{CC}$	-	-	V
		EN input				
		V <sub>CC</sub> = 0.8 V	$0.70 \times V_{CC}$	-	-	V
		V <sub>CC</sub> = 0.9 V to 1.95 V	$0.65 \times V_{CC}$	-	-	V
		V <sub>CC</sub> = 2.3 V to 2.7 V	1.6	-	-	V
		V <sub>CC</sub> = 3.0 V to 3.6 V	2.0	-	-	V
V <sub>IL</sub>	LOW-level input voltage	X1 input				
		$V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	$0.25 \times V_{CC}$	V
		EN input				
		V <sub>CC</sub> = 0.8 V	-	-	$0.30 \times V_{CC}$	V
		$V_{CC} = 0.9 \text{ V to } 1.95 \text{ V}$	-	-	$0.35 \times V_{CC}$	V
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	-	-	0.7	V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	-	-	0.9	V
V <sub>OH</sub>	HIGH-level output voltage	Y output; $V_I$ at X1 input = $V_{IH}$ or $V_{IL}$				
		$I_{O} = -20 \mu A$ ; $V_{CC} = 0.8 \text{ V}$ to 3.6 V	$V_{CC}-0.1$	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.75 \times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.11	-	-	V
		$I_O = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.32	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	2.05	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.9	-	-	V
		$I_{O} = -2.7 \text{ mA}$ ; $V_{CC} = 3.0 \text{ V}$	2.72	-	-	V
		$I_O = -4.0 \text{ mA}$ ; $V_{CC} = 3.0 \text{ V}$	2.6	-	-	V
		X2 output; $V_I = GND$ or $V_{CC}$				
		$I_O = -20 \mu A$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	V <sub>CC</sub> – 0.1	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.75 \times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.11	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.32	-	-	V
		$I_{O} = -2.3 \text{ mA}$ ; $V_{CC} = 2.3 \text{ V}$	2.05	-	-	V
		$I_O = -3.1 \text{ mA}$ ; $V_{CC} = 2.3 \text{ V}$	1.9	-	-	V
		$I_{O} = -2.7 \text{ mA}$ ; $V_{CC} = 3.0 \text{ V}$	2.72	-	-	V
		$I_O = -4.0 \text{ mA}$ ; $V_{CC} = 3.0 \text{ V}$	2.6	-	-	V

### Low-power X-tal driver with enable and internal resistor

**Table 7. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$V_{OL}$	LOW-level output voltage	Y output; $V_I$ at X1 input = $V_{IH}$ or $V_{IL}$				
		$I_O = 20 \mu A$ ; $V_{CC} = 0.8 \text{ V}$ to 3.6 V	-	-	0.1	V
		$I_{O} = 1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	-	-	$0.3 \times V_{\text{CC}}$	V
		$I_O = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.31	V
		I <sub>O</sub> = 1.9 mA; V <sub>CC</sub> = 1.65 V	-	-	0.31	V
		$I_O = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.31	V
		$I_O = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.44	V
		$I_O = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.31	V
		$I_O = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.44	V
		X2 output; $V_I = GND$ or $V_{CC}$				
		$I_O = 20 \mu A$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	0.1	V
		$I_O = 1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	-	-	$0.3 \times V_{CC}$	V
		$I_O = 1.7 \text{ mA}$ ; $V_{CC} = 1.4 \text{ V}$	-	-	0.31	V
		$I_O = 1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	-	-	0.31	V
		$I_O = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.31	V
		$I_O = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.44	V
		$I_O = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.31	V
		$I_O = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.44	V
l <sub>l</sub>	input leakage current	X1 input				
		$V_I = \overline{EN} = V_{CC}$ ; $V_{CC} = 0 \text{ V to } 3.6 \text{ V}$	-	-	±0.1	μΑ
		EN input				
		$V_I = GND \text{ to } 3.6 \text{ V};$ $V_{CC} = 0 \text{ V to } 3.6 \text{ V}$	-	-	±0.1	μΑ
pu	pull-up current	X1 input; EN = V <sub>CC</sub>				
		$V_{I} = GND; V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	15	μΑ
OFF	power-off leakage current	$V_{I}$ or $V_{O} = 0 \text{ V}$ to 3.6 V; $V_{CC} = 0 \text{ V}$	<u>[1]</u> _	-	±0.2	μΑ
Δl <sub>OFF</sub>	additional power-off leakage current	$V_1$ or $V_0 = 0$ V to 3.6 V; $V_{CC} = 0$ V to 0.2 V	[1] -	-	±0.2	μΑ
СС	supply current	$\underline{V_1}$ = GND or $V_{CC}$ ; $I_O$ = 0 A; EN = GND; $V_{CC}$ = 0.8 V to 3.6 V	-	-	75	μΑ
Δl <sub>CC</sub>	additional supply current	EN input				
		$V_{I} = V_{CC} - 0.6 \text{ V}; I_{O} = 0 \text{ A};$ $V_{CC} = 3.3 \text{ V}$	-	-	40	μΑ
Cı	input capacitance	X1 input				
		$V_{CC} = 0 \text{ V to } 3.6 \text{ V};$ $V_I = \text{GND or } V_{CC}$	-	1.3	-	pF
		EN input				
		$V_{CC} = 0 \text{ V to } 3.6 \text{ V};$ $V_I = \text{GND or } V_{CC}$	-	0.8	-	pF

74AUP1Z04

All information provided in this document is subject to legal disclaimers.

### Low-power X-tal driver with enable and internal resistor

**Table 7. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Co	output capacitance	X2 output				
		$V_O = GND; V_{CC} = 0 V$	-	1.5	-	pF
		Y output				
	forward transconductance	$V_O = GND; V_{CC} = 0 V$	-	1.7	-	pF
9 <sub>fs</sub>	forward transconductance	see Figure 10 and Figure 11				
		V <sub>CC</sub> = 0.8 V	-	-	-	mA/V
		V <sub>CC</sub> = 1.1 V to 1.3 V	0.2	-	9.9	mA/V
		V <sub>CC</sub> = 1.4 V to 1.6 V	3.9	-	17.7	mA/V
		V <sub>CC</sub> = 1.65 V to 1.95 V	7.9	-	24.3	mA/V
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	18	-	30.7	mA/V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	20.5	-	32.4	mA/V
R <sub>bias</sub>	bias resistance	$\overline{\text{EN}}$ = GND; f <sub>i</sub> = 0 Hz; V <sub>I</sub> = 0 V or V <sub>CC</sub> ; see Figure 5; for frequency behavior see Figure 6	1.08	1.62	3.08	ΜΩ
T <sub>amb</sub> = -	40 °C to +85 °C					
V <sub>IH</sub>	HIGH-level input voltage	X1 input				
		$V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	$0.75 \times V_{CC}$	-	-	V
		EN input				
		$V_{CC} = 0.8 \text{ V}$	$0.70 \times V_{CC}$	-	-	V
		V <sub>CC</sub> = 0.9 V to 1.95 V	$0.65 \times V_{CC}$	-	-	V
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	1.6	-	-	V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	2.0	-	-	V
V <sub>IL</sub>	LOW-level input voltage	X1 input				
		$V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	$0.25 \times V_{CC}$	V
		EN input				
		$V_{CC} = 0.8 \text{ V}$	-	-	$0.30 \times V_{CC}$	V
		V <sub>CC</sub> = 0.9 V to 1.95 V	-	-	$0.35 \times V_{CC}$	V
		$V_{CC}$ = 2.3 V to 2.7 V	-	-	0.7	V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	-	-	0.9	V

### Low-power X-tal driver with enable and internal resistor

**Table 7. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>OH</sub>	HIGH-level output voltage	Y output; $V_I$ at X1 input = $V_{IH}$ or $V_{IL}$				
VON TIME		$I_O = -20~\mu A;~V_{CC} = 0.8~V$ to 3.6 $V$	$V_{CC}-0.1$	-	-	V
		$I_O = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.7 \times V_{CC}$	1.1 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	V	
		$I_O = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.03	-	-	V
		$I_O = -1.9 \text{ mA}$ ; $V_{CC} = 1.65 \text{ V}$	1.30	-	-	V
		$I_O = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.97	-	-	V
		$I_O = -3.1 \text{ mA}$ ; $V_{CC} = 2.3 \text{ V}$	1.85	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.67	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.55	-	-	V
		$V_I$ at X1 input = $V_{IH}$ or $V_{IL}$			- - - - - -	
		$I_O = -20 \mu A$ ; $V_{CC} = 0.8 \text{ V}$ to 3.6 V	V <sub>CC</sub> - 0.1	-		V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.7 \times V_{CC}$	-		V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	1.03	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.30	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.97	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.85	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.67	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.55	-	-	V
V <sub>OL</sub>	LOW-level output voltage	Y output; $V_I$ at X1 input = $V_{IH}$ or $V_{IL}$				
		$I_O = 20 \mu A$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	0.1	V
		I <sub>O</sub> = 1.1 mA; V <sub>CC</sub> = 1.1 V	-	-	$0.3 \times V_{CC}$	V
		I <sub>O</sub> = 1.7 mA; V <sub>CC</sub> = 1.4 V	-	-	0.37	V
		I <sub>O</sub> = 1.9 mA; V <sub>CC</sub> = 1.65 V	-	-	0.35	V
		$I_O = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.33	V
		$I_O = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.45	V
		$I_O = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.33	V
		I <sub>O</sub> = 4.0 mA; V <sub>CC</sub> = 3.0 V	-	-	0.45	V
		X2 output; $V_I = GND$ or $V_{CC}$				
		$I_O = 20 \mu A$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	0.1	V
		I <sub>O</sub> = 1.1 mA; V <sub>CC</sub> = 1.1 V	-	-	$0.3 \times V_{CC}$	V
		$I_O = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$		0.37	V	
		I <sub>O</sub> = 1.9 mA; V <sub>CC</sub> = 1.65 V	-	-	0.35	V
		I <sub>O</sub> = 2.3 mA; V <sub>CC</sub> = 2.3 V	-	-	0.33	V
		$I_0 = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.45	V
		$I_O = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$ $I_O = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.45	V

Downloaded from Elcodis.com electronic components distributor

### Low-power X-tal driver with enable and internal resistor

**Table 7. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
lı	input leakage current	X1 input				
		$V_I = \overline{EN} = V_{CC}$ ; $V_{CC} = 0 \text{ V to } 3.6 \text{ V}$	-	-	±0.5	μΑ
		EN input				
		$V_1 = GND \text{ to } 3.6 \text{ V};$ $V_{CC} = 0 \text{ V to } 3.6 \text{ V}$	-	-	±0.5	μΑ
I <sub>pu</sub>	pull-up current  power-off leakage current additional power-off leakage current supply current additional supply current	X1 input; $\overline{EN} = V_{CC}$				
		$V_I = GND$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	15	μΑ
I <sub>OFF</sub>	power-off leakage current	$V_I$ or $V_O = 0$ V to 3.6 V; $V_{CC} = 0$ V	<u>[1]</u> _	-	±0.5	μΑ
$\Delta I_{OFF}$		$V_1$ or $V_0 = 0$ V to 3.6 V; $V_{CC} = 0$ V to 0.2 V	[1] -	-	±0.6	μΑ
I <sub>CC</sub>	supply current	$V_1$ = GND or $V_{CC}$ ; $I_0$ = 0 A; EN = GND; $V_{CC}$ = 0.8 V to 3.6 V	-	-	75	μΑ
$\Delta I_{CC}$	additional supply current	EN input				
		$V_1 = V_{CC} - 0.6 \text{ V}; I_O = 0 \text{ A};$ $V_{CC} = 3.3 \text{ V}$	-	-	50	μΑ
g <sub>fs</sub>	forward transconductance	see Figure 10 and Figure 11				
		V <sub>CC</sub> = 0.8 V	-	-	-	mA/\
		V <sub>CC</sub> = 1.1 V to 1.3 V	-	-	10.8	mA/
		V <sub>CC</sub> = 1.4 V to 1.6 V	1.8	-	21.2	mA/\
		V <sub>CC</sub> = 1.65 V to 1.95 V	7.5	-	29.9	mA/\
		V <sub>CC</sub> = 2.3 V to 2.7 V	15.0	-	38.0	mA/
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	17.8	-	39.2	mA/\
R <sub>bias</sub>	bias resistance	$\overline{\text{EN}}$ = GND; f <sub>i</sub> = 0 Hz; V <sub>I</sub> = 0 V or V <sub>CC</sub> ; see <u>Figure 5</u> ; for frequency behavior see <u>Figure 6</u>	1.07	-	3.11	ΜΩ
T <sub>amb</sub> = -	40 °C to +125 °C					
V <sub>IH</sub>	HIGH-level input voltage	X1 input				
		$V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$ $\overline{\text{EN}} \text{ input}$	$0.75 \times V_{CC}$	-	-	V
		V <sub>CC</sub> = 0.8 V	0.75 × V <sub>CC</sub>	-	-	V
		V <sub>CC</sub> = 0.9 V to 1.95 V	0.70 × V <sub>CC</sub>	-	-	V
		V <sub>CC</sub> = 2.3 V to 2.7 V	1.6	-	-	V
		V <sub>CC</sub> = 3.0 V to 3.6 V	2.0	-	-	V
V <sub>IL</sub>	LOW-level input voltage	X1 input				
		V <sub>CC</sub> = 0.8 V to 3.6 V	-	-	$0.25 \times V_{CC}$	V
		EN input				
		V <sub>CC</sub> = 0.8 V	-	-	$0.25 \times V_{CC}$	V
		V <sub>CC</sub> = 0.9 V to 1.95 V	-	-	$0.30 \times V_{CC}$	
		V <sub>CC</sub> = 2.3 V to 2.7 V	-	-	0.7	٧
		V <sub>CC</sub> = 3.0 V to 3.6 V	-	-	0.9	V

74AUP1Z04 All information provided in this document is subject to legal disclaimers. © NXP B.V. 2012. All rights reserved.

### Low-power X-tal driver with enable and internal resistor

**Table 7. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

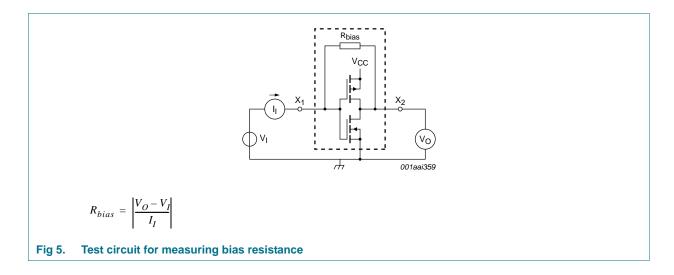
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$V_{OH}$	HIGH-level output voltage	Y output; $V_I$ at X1 input = $V_{IH}$ or $V_{IL}$				V
VOH TIIG		$I_O = -20 \mu A$ ; $V_{CC} = 0.8 \text{ V}$ to 3.6 V	$V_{CC}-0.11$	-	-	V
	nign-ievel output voltage	$I_O = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.6 \times V_{CC}$	-	-	V
		$I_O = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	0.93	-	-	V
		$I_O = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.17	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.77	-	-	V
		$I_O = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.67	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.40	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.30	-	-	V
		X2 output; $V_I = GND$ or $V_{CC}$				V
		$I_{O} = -20 \mu A$ ; $V_{CC} = 0.8 \text{ V}$ to 3.6 V	V <sub>CC</sub> - 0.11	-	-	V
		$I_{O} = -1.1 \text{ mA}; V_{CC} = 1.1 \text{ V}$	$0.6 \times V_{CC}$	-	-	V
		$I_{O} = -1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	0.93	-	-	V
		$I_{O} = -1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	1.17	-	-	V
		$I_{O} = -2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.77	-	-	V
		$I_{O} = -3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	1.67	-	-	V
		$I_{O} = -2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.40	-	-	V
		$I_{O} = -4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	2.30	-	-	V
V <sub>OL</sub>	LOW-level output voltage	Y output; V <sub>I</sub> at X1 input = V <sub>IH</sub> or V <sub>IL</sub>				
		$I_O = 20 \mu A$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	0.11	V
		I <sub>O</sub> = 1.1 mA; V <sub>CC</sub> = 1.1 V	-	-	$0.33 \times V_{CC}$	V
		$I_O = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.41	V
		$I_O = 1.9 \text{ mA}; V_{CC} = 1.65 \text{ V}$	-	-	0.39	V
		$I_O = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.36	V
		$I_O = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.50	V
		$I_O = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.36	V
		$I_O = 4.0 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.50	V
		X2 output; $V_I = GND \text{ or } V_{CC}$				
		$I_O = 20 \mu A$ ; $V_{CC} = 0.8 \text{ V to } 3.6 \text{ V}$	-	-	0.11	V
		I <sub>O</sub> = 1.1 mA; V <sub>CC</sub> = 1.1 V	-	-	$0.33 \times V_{CC}$	V
		$I_O = 1.7 \text{ mA}; V_{CC} = 1.4 \text{ V}$	-	-	0.41	V
		I <sub>O</sub> = 1.9 mA; V <sub>CC</sub> = 1.65 V	-	-	0.39	V
		$I_{O} = 2.3 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.36	V
		$I_O = 3.1 \text{ mA}; V_{CC} = 2.3 \text{ V}$	-	-	0.50	V
		$I_O = 2.7 \text{ mA}; V_{CC} = 3.0 \text{ V}$	-	-	0.36	V
		$I_O = 4.0 \text{ mA}$ ; $V_{CC} = 3.0 \text{ V}$	-	-	0.50	V

### Low-power X-tal driver with enable and internal resistor

**Table 7. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
l <sub>l</sub>	input leakage current	X1 input				
		$V_I = \overline{EN} = V_{CC}$ ; $V_{CC} = 0 \text{ V to } 3.6 \text{ V}$	-	-	±0.75	μΑ
		EN input				
		$V_I = GND \text{ to } 3.6 \text{ V};$ $V_{CC} = 0 \text{ V to } 3.6 \text{ V}$	-	-	±0.75	μА
I <sub>pu</sub>	pull-up current	X1 input; $\overline{EN} = V_{CC}$				
		$V_I = GND$ ; $V_{CC} = 0.8 \text{ V}$ to 3.6 V	-	-	15	μΑ
I <sub>OFF</sub>	power-off leakage current	$V_I$ or $V_O = 0$ V to 3.6 V; $V_{CC} = 0$ V	[1] _	-	±0.75	μΑ
$\Delta I_{OFF}$	additional power-off leakage current	$V_1$ or $V_0 = 0$ V to 3.6 V; $V_{CC} = 0$ V to 0.2 V	[1] _	-	±0.75	μА
I <sub>CC</sub>	supply current	$V_L$ = GND or $V_{CC}$ ; $I_O$ = 0 A; EN = GND; $V_{CC}$ = 0.8 V to 3.6 V	-	-	75	μА
$\Delta I_{CC}$	additional supply current	EN input				
		$V_{I} = V_{CC} - 0.6 \text{ V}; I_{O} = 0 \text{ A};$ $V_{CC} = 3.3 \text{ V}$	-	-	75	μА
g <sub>fs</sub>	forward transconductance	see Figure 10 and Figure 11				
		$V_{CC} = 0.8 \text{ V}$	-	-	-	mA/V
		V <sub>CC</sub> = 1.1 V to 1.3 V	-	-	10.8	mA/V
		V <sub>CC</sub> = 1.4 V to 1.6 V	1.8	-	21.2	mA/V
		V <sub>CC</sub> = 1.65 V to 1.95 V	6.9	-	29.9	mA/V
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	13.4	-	38.0	mA/V
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	15.8	-	39.2	mA/V
R <sub>bias</sub>	bias resistance	$\overline{\text{EN}} = \text{GND}$ ; $f_i = 0 \text{ Hz}$ ; $V_l = 0 \text{ V or } V_{\text{CC}}$ ; see Figure 5; for frequency behavior see Figure 6	1.07	-	3.11	МΩ

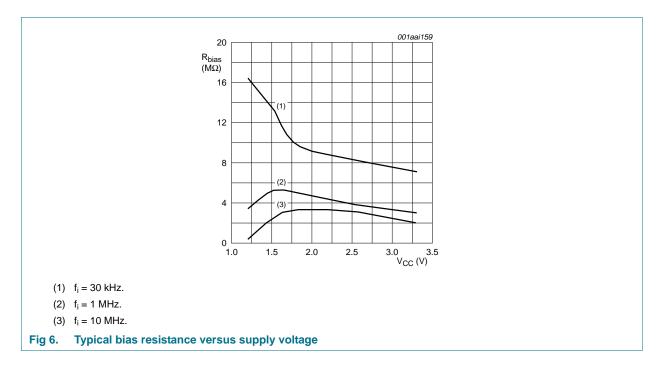
#### [1] Only for output Y and input $\overline{EN}$ .



74AUP1Z04

All information provided in this document is subject to legal disclaimers.

Low-power X-tal driver with enable and internal resistor



# 11. Dynamic characteristics

Table 8. Dynamic characteristics

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 9.

Symbol $C_L = 5 p$ $t_{pd}$	Parameter	Conditions		T <sub>amb</sub> =25 °C		$T_{amb} = -40$ °C to +125 °C			Unit	
				Min Typ[1] Max		Min	Max (85 °C)	Max (125 °C)		
<b>C</b> <sub>L</sub> = 5 pl	F		'		'		'	1		
t <sub>pd</sub> propa	propagation delay	X1 to X2; see Figure 7	[2]							
		$V_{CC} = 0.8 \text{ V}$		-	12.8	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$		1.2	3.0	3.9	1.2	3.9	3.9	ns
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$		1.0	2.2	2.6	1.0	2.7	2.7	ns
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$		0.8	1.9	2.3	8.0	2.4	2.5	ns
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$		0.7	1.6	1.9	0.7	2.0	2.0	ns
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$		0.7	1.4	1.6	0.7	1.7	1.7	ns
		X1 to Y; see Figure 8	[2]							
		$V_{CC} = 0.8 \text{ V}$		-	39.2	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$		2.5	8.0	10.7	2.3	10.8	10.9	ns
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$		2.2	5.5	6.6	2.0	7.0	7.0	ns
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$		1.8	4.4	5.5	1.7	5.9	6.0	ns
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$		1.5	3.5	4.1	1.4	4.4	4.5	ns
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$		1.5	3.1	3.5	1.4	3.8	3.8	ns

74AUP1Z04

All information provided in this document is subject to legal disclaimers.

### Low-power X-tal driver with enable and internal resistor

**Table 8. Dynamic characteristics** ...continued Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 9</u>.

Symbol	Parameter	Conditions	Т	T <sub>amb</sub> =25 °C			$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$		
			Min	Typ[1]	Max	Min	Max (85 °C)	Max (125 °C)	
C <sub>L</sub> = 10	ρF				'		'		
t <sub>pd</sub>	propagation delay	X1 to X2; see Figure 7							
		$V_{CC} = 0.8 \text{ V}$	-	20.9	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	1.4	4.1	5.4	1.3	5.6	5.6	ns
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	1.3	2.9	3.6	1.2	3.8	3.8	ns
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	1.2	2.5	3.0	1.1	3.2	3.2	ns
		$V_{CC}$ = 2.3 V to 2.7 V	0.9	2.0	2.4	8.0	2.5	2.5	ns
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	0.9	1.8	2.1	8.0	2.3	2.3	ns
		X1 to Y; see Figure 8 [2]							
		$V_{CC} = 0.8 \text{ V}$	-	46.6	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	2.7	9.2	12.4	2.5	12.7	12.7	ns
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	2.5	6.3	7.8	2.2	8.2	8.2	ns
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	2.3	5.0	6.2	2.2	6.7	6.7	ns
		$V_{CC}$ = 2.3 V to 2.7 V	1.8	4.0	4.7	1.7	5.0	5.1	ns
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	1.9	3.6	4.2	1.8	4.5	4.5	ns
C <sub>L</sub> = 15	pF								
$t_{pd}$	propagation delay	X1 to X2; see Figure 7							
		$V_{CC} = 0.8 \text{ V}$	-	28.9	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	1.7	5.2	7.1	1.6	7.2	7.3	ns
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	1.6	3.6	4.4	1.6	4.7	4.8	ns
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	1.3	3.0	3.7	1.3	3.9	4.0	ns
		$V_{CC}$ = 2.3 V to 2.7 V	1.0	2.4	2.9	1.0	3.1	3.1	ns
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	1.1	2.2	2.5	1.0	2.7	2.7	ns
		X1 to Y; see Figure 8 [2]							
		$V_{CC} = 0.8 \text{ V}$	-	53.9	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	3.1	10.4	14.2	2.8	14.6	14.7	ns
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	2.9	7.0	8.5	2.7	9.2	9.3	ns
		V <sub>CC</sub> = 1.65 V to 1.95 V	2.5	5.6	6.9	2.3	7.4	7.5	ns
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	2.1	4.5	5.4	2.0	5.7	5.7	ns
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	2.3	4.1	4.7	2.1	5.1	5.1	ns

#### Low-power X-tal driver with enable and internal resistor

**Table 8. Dynamic characteristics** ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 9</u>.

Symbol Parameter	Parameter	Conditions		T <sub>amb</sub> =25 °C		$T_{amb} = -40$ °C to +125 °C			Unit
			Min Typ[1] Ma		Max	Min	Max (85 °C)	Max (125 °C)	
C <sub>L</sub> = 30	pF								
t <sub>pd</sub>	propagation delay	X1 to X2; see Figure 7							
		$V_{CC} = 0.8 \text{ V}$	-	52.8	-	-	-	-	ns
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	2.4	8.5	11.8	2.3	12.2	12.4	ns
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	2.2	5.6	6.8	2.0	7.5	7.6	ns
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	2.0	4.5	5.6	1.9	6.2	6.2	ns
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	1.5	3.7	4.2	1.4	4.6	4.6	ns
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	1.7	3.3	3.7	1.6	4.0	4.2	ns
		X1 to Y; see Figure 8							
		V <sub>CC</sub> = 0.8 V	-	77.6	-	-	-	-	ns
		V <sub>CC</sub> = 1.1 V to 1.3 V	3.7	13.8	19.2	3.3	19.8	20.1	ns
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	3.4	9.2	11.2	3.1	12.2	12.3	ns
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	3.4	7.4	8.8	3.1	9.7	9.7	ns
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	2.6	5.9	6.7	2.4	7.4	7.4	ns
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	3.2	5.4	6.2	2.9	6.7	6.9	ns
$C_L = 5 p$	F, 10 pF, 15 pF and	30 pF							
$C_{PD}$	power dissipation capacitance	$f_i = 1 \text{ MHz}; \overline{EN} = GND;$ [3][4][5] $V_I = GND \text{ to } V_{CC}$							
		$V_{CC} = 0.8 \text{ V}$	-	6.8	-	-	-	-	pF
		$V_{CC} = 1.1 \text{ V to } 1.3 \text{ V}$	-	12.0	-	-	-	-	pF
		$V_{CC} = 1.4 \text{ V to } 1.6 \text{ V}$	-	18.2	-	-	-	-	pF
		$V_{CC} = 1.65 \text{ V to } 1.95 \text{ V}$	-	19.2	-	-	-	-	pF
		$V_{CC} = 2.3 \text{ V to } 2.7 \text{ V}$	-	21.9	-	-	-	-	pF
		$V_{CC} = 3.0 \text{ V to } 3.6 \text{ V}$	-	24.9	-	-	-	-	pF

<sup>[1]</sup> All typical values are measured at nominal  $V_{CC}$ .

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o) \text{ where:}$ 

 $f_i$  = input frequency in MHz;

f<sub>o</sub> = output frequency in MHz;

C<sub>L</sub> = output load capacitance in pF;

 $V_{CC}$  = supply voltage in V;

N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}{}^2 \times f_o) = sum \ of \ the \ outputs.$ 

[5] Feedback current is included in the C<sub>PD</sub>.

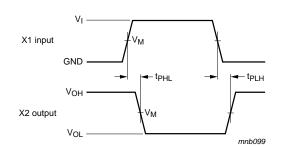
<sup>[2]</sup>  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

<sup>[3]</sup> All specified values are the average typical values over all stated loads.

<sup>[4]</sup>  $C_{PD}$  is used to determine the dynamic power dissipation ( $P_D$  in  $\mu W$ ).

Low-power X-tal driver with enable and internal resistor

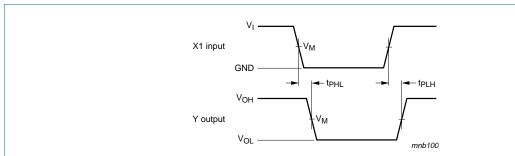
### 12. Waveforms



Measurement points are given in Table 9.

Logic levels:  $V_{OL}$  and  $V_{OH}$  are typical output voltage drop that occur with the output load.

Fig 7. The input (X1) to output (X2) propagation delays



Measurement points are given in Table 9.

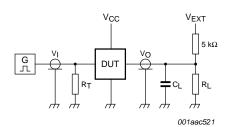
Logic levels:  $V_{\text{OL}}$  and  $V_{\text{OH}}$  are typical output voltage drop that occur with the output load.

Fig 8. The input (X1) to output (Y) propagation delays

Table 9. Measurement points

Supply voltage	Output	Input		
V <sub>CC</sub>	V <sub>M</sub>	V <sub>M</sub>	VI	$t_r = t_f$
0.8 V to 3.6 V	$0.5 \times V_{CC}$	$0.5 \times V_{CC}$	V <sub>CC</sub>	≤ 3.0 ns

#### Low-power X-tal driver with enable and internal resistor



Test data is given in Table 10.

Definitions for test circuit:

R<sub>L</sub> = Load resistance.

 $C_L$  = Load capacitance including jig and probe capacitance.

 $R_T$  = Termination resistance should be equal to the output impedance  $Z_0$  of the pulse generator.

 $V_{\mathsf{EXT}}$  = External voltage for measuring switching times.

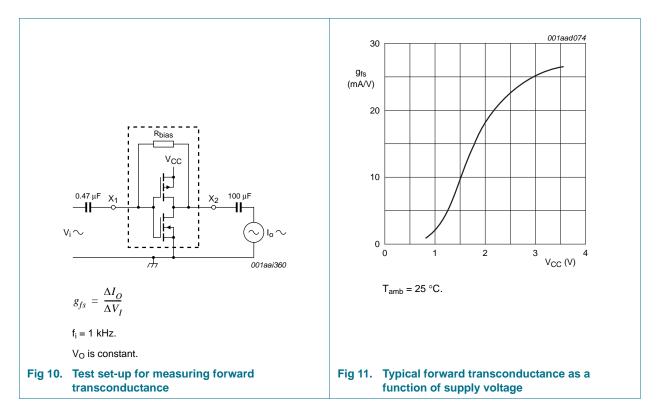
Fig 9. Test circuit for measuring switching times

#### Table 10. Test data

Supply voltage	Load	V <sub>EXT</sub>			
V <sub>CC</sub>	CL	R <sub>L</sub> [1]	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ</sub>
0.8 V to 3.6 V	5 pF, 10 pF, 15 pF and 30 pF	5 k $\Omega$ or 1 M $\Omega$	open	GND	$2\times V_{CC}$

[1] For measuring enable and disable times  $R_L$  = 5  $k\Omega$ , for measuring propagation delays, setup and hold times and pulse width  $R_L$  = 1  $M\Omega$ .

Low-power X-tal driver with enable and internal resistor



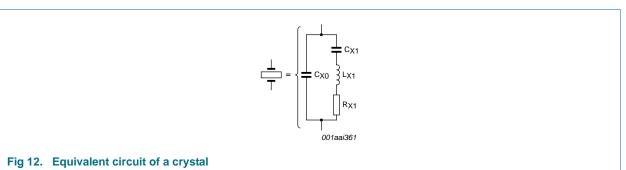
# 13. Application information

Crystal controlled oscillator circuits are widely used in clock pulse generators because of their excellent frequency stability and wide operating frequency range. The use of the 74AUP1Z04 provides the additional advantages of low power dissipation, stable operation over a wide range of frequency and temperature and a very small footprint. This application information describes crystal characteristics, design and testing of crystal oscillator circuits based on the 74AUP1Z04.

#### 13.1 Crystal characteristics

Figure 12 is the equivalent circuit of a quartz crystal.

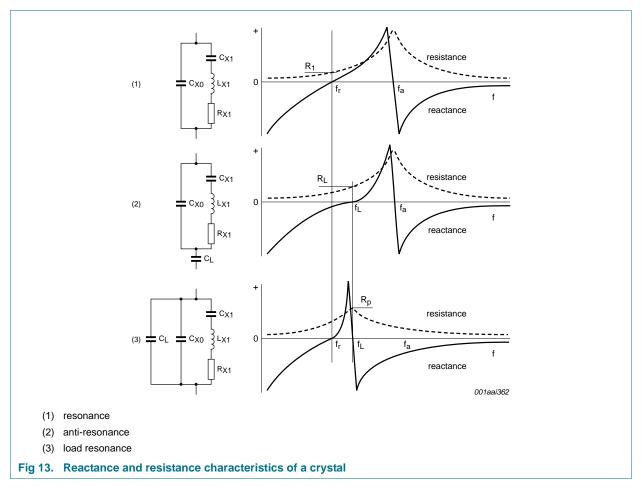
The reactive and resistive component of the impedance of the crystal alone and the crystal with a series and a parallel capacitance is shown in Figure 13.



74AUP1Z04

All information provided in this document is subject to legal disclaimers.

Low-power X-tal driver with enable and internal resistor



#### 13.1.1 **Design**

Figure 14 shows the recommended way to connect a crystal to the 74AUP1Z04. This circuit is basically a Pierce oscillator circuit in which the crystal is operating at its fundamental frequency and is tuned by the parallel load capacitance of  $C_1$  and  $C_2$ .  $C_1$  and  $C_2$  are in series with the crystal. They should be approximately equal.  $R_1$  is the drive-limiting resistor and is set to approximately the same value as the reactance of  $C_1$  at the crystal frequency ( $R_1 = X_{C_1}$ ). This will result in an input to the crystal of 50 % of the rail-to-rail output of X2. This keeps the drive level into the crystal within drive specifications (the designer should verify this). Overdriving the crystal can cause damage.

The internal bias resistor provides negative feedback and sets a bias point of the inverter near mid-supply, operating the 74AUP1GU04 portion in the high gain linear region.

To calculate the values of  $C_1$  and  $C_2$ , the designer can use the formula:

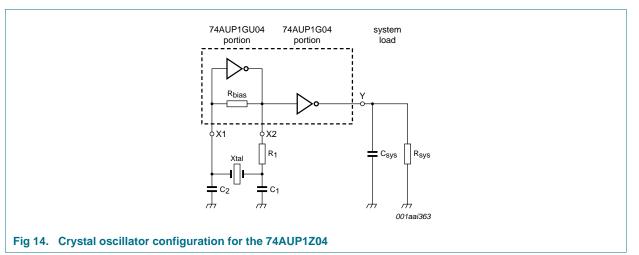
$$C_L = \frac{C_1 \times C_2}{C_1 + C_2} + C_s$$

 $C_L$  is the load capacitance as specified by the crystal manufacturer,  $C_s$  is the stray capacitance of the circuit (for the 74AUP1Z04 this is equal to an input capacitance of 1.5 pF).

74AUP1Z04

All information provided in this document is subject to legal disclaimers

#### Low-power X-tal driver with enable and internal resistor



# 13.1.2 Testing

After the calculations are performed for a particular crystal, the oscillator circuit should be tested. The following simple checks will verify the prototype design of a crystal controlled oscillator circuit. Perform them after laying out the board:

- Test the oscillator over worst-case conditions (lowest supply voltage, worst-case crystal and highest operating temperature). Adding series and parallel resistors can simulate a worst-case crystal.
- Insure that the circuit does not oscillate without the crystal.
- Check the frequency stability over a supply range greater than that which is likely to occur during normal operation.
- · Check that the start-up time is within system requirements.

As the 74AUP1Z04 isolates the system loading, once the design is optimized, the single layout may work in multiple applications for any given crystal.

# 14. Package outline

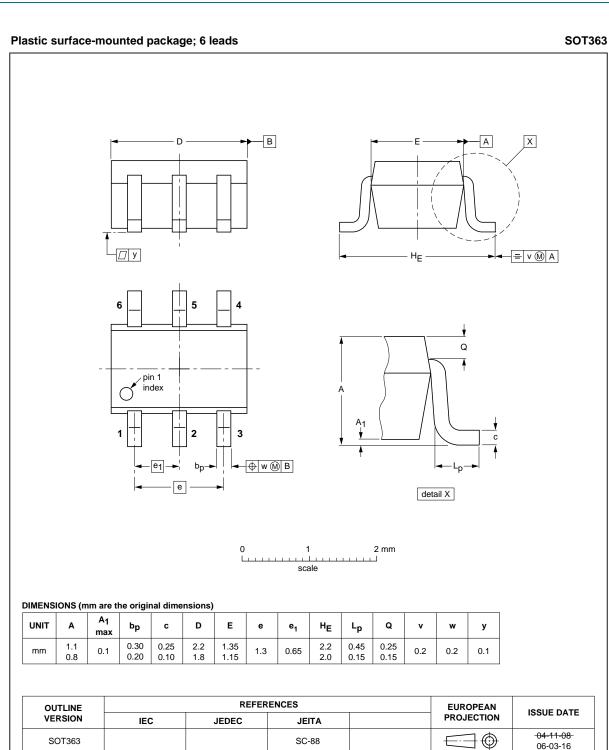


Fig 15. Package outline SOT363 (SC-88)

74AUP1204 All information provided in this document is subject to legal disclaimers. © NX

#### Low-power X-tal driver with enable and internal resistor

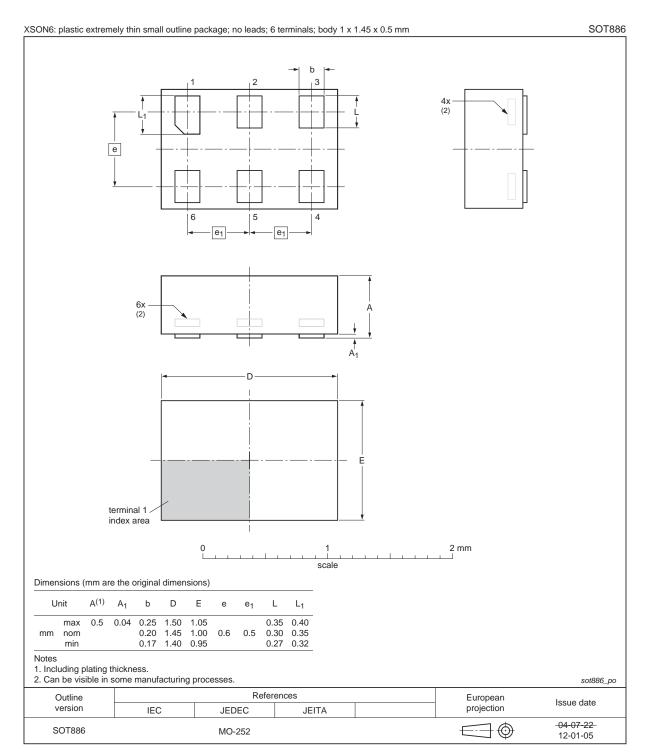


Fig 16. Package outline SOT886 (XSON6)

74AUP1204 All information provided in this document is subject to legal disclaimers. © NXP B.V. 2012. All rights reserved.

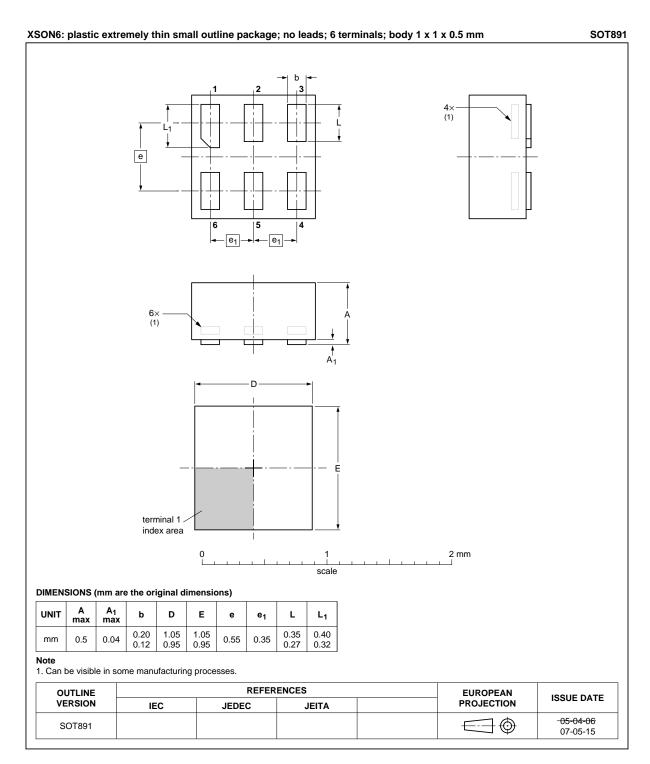


Fig 17. Package outline SOT891 (XSON6)

74AUP1Z04 All information provided in this document is subject to legal disclaimers. © NXP B.V. 2012. All rights reserved.

Low-power X-tal driver with enable and internal resistor

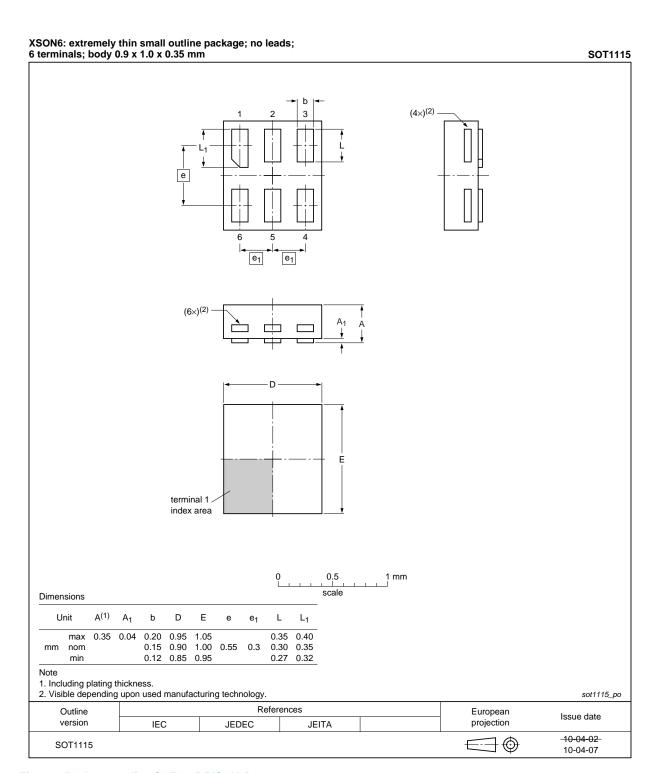


Fig 18. Package outline SOT1115 (XSON6)

74AUP1204 All information provided in this document is subject to legal disclaimers. © NXP B.V. 2012. All rights reserved.

Low-power X-tal driver with enable and internal resistor

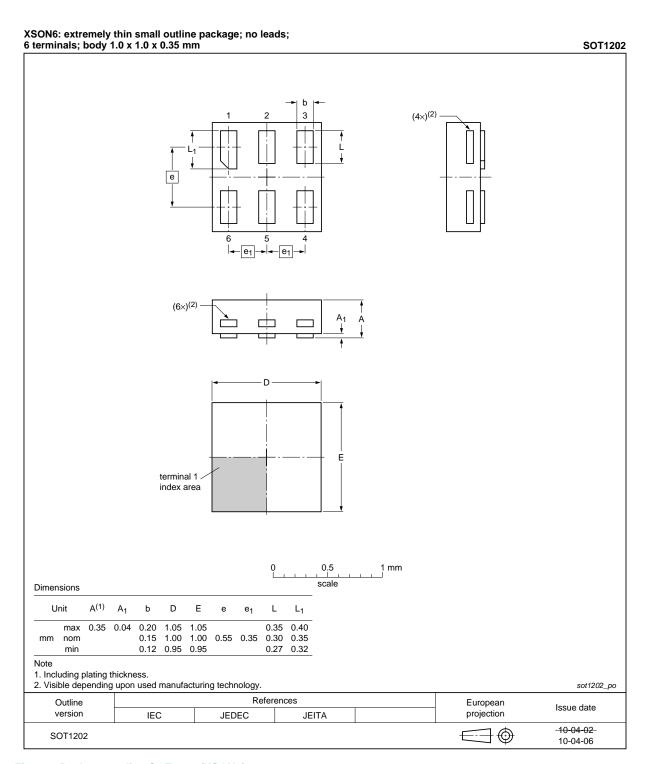


Fig 19. Package outline SOT1202 (XSON6)

74AUP1204 All information provided in this document is subject to legal disclaimers. © NXP B.V. 2012. All rights reserved.

### Low-power X-tal driver with enable and internal resistor

## 15. Abbreviations

#### Table 11. Abbreviations

Acronym	Description
CDM	Charged Device Model
DUT	Device Under Test
ESD	ElectroStatic Discharge
НВМ	Human Body Model
MM	Machine Model

# 16. Revision history

#### Table 12. Revision history

	•			
Document ID	Release date	Data sheet status	Change notice	Supersedes
74AUP1Z04 v.5	20120809	Product data sheet	-	74AUP1Z04 v.4
Modifications:	<ul> <li>Package ou</li> </ul>	tline drawing of SOT886 (F	igure 16) modified.	
74AUP1Z04 v.4	20111201	Product data sheet	-	74AUP1Z04 v.3
Modifications:	<ul> <li>Legal pages</li> </ul>	s updated.		
74AUP1Z04 v.3	20100722	Product data sheet	-	74AUP1Z04 v.2
74AUP1Z04 v.2	20080703	Product data sheet	-	74AUP1Z04 v.1
74AUP1Z04 v.1	20061212	Product data sheet	-	-

#### Low-power X-tal driver with enable and internal resistor

## 17. Legal information

#### 17.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <a href="http://www.nxp.com">http://www.nxp.com</a>.

#### 17.2 Definitions

**Draft** — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

Short data sheet — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local NXP Semiconductors sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

Product specification — The information and data provided in a Product data sheet shall define the specification of the product as agreed between NXP Semiconductors and its customer, unless NXP Semiconductors and customer have explicitly agreed otherwise in writing. In no event however, shall an agreement be valid in which the NXP Semiconductors product is deemed to offer functions and qualities beyond those described in the Product data sheet.

#### 17.3 Disclaimers

Limited warranty and liability — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. NXP Semiconductors takes no responsibility for the content in this document if provided by an information source outside of NXP Semiconductors.

In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the *Terms and conditions of commercial sale* of NXP Semiconductors.

Right to make changes — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use — NXP Semiconductors products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors and its suppliers accept no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

**Applications** — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

NXP Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). NXP does not accept any liability in this respect.

Limiting values — Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) will cause permanent damage to the device. Limiting values are stress ratings only and (proper) operation of the device at these or any other conditions above those given in the Recommended operating conditions section (if present) or the Characteristics sections of this document is not warranted. Constant or repeated exposure to limiting values will permanently and irreversibly affect the quality and reliability of the device.

Terms and conditions of commercial sale — NXP Semiconductors products are sold subject to the general terms and conditions of commercial sale, as published at <a href="http://www.nxp.com/profile/terms">http://www.nxp.com/profile/terms</a>, unless otherwise agreed in a valid written individual agreement. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. NXP Semiconductors hereby expressly objects to applying the customer's general terms and conditions with regard to the purchase of NXP Semiconductors products by customer.

No offer to sell or license — Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

74AUP1Z04

All information provided in this document is subject to legal disclaimers.

#### Low-power X-tal driver with enable and internal resistor

**Export control** — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

Non-automotive qualified products — Unless this data sheet expressly states that this specific NXP Semiconductors product is automotive qualified, the product is not suitable for automotive use. It is neither qualified nor tested in accordance with automotive testing or application requirements. NXP Semiconductors accepts no liability for inclusion and/or use of non-automotive qualified products in automotive equipment or applications.

In the event that customer uses the product for design-in and use in automotive applications to automotive specifications and standards, customer (a) shall use the product without NXP Semiconductors' warranty of the product for such automotive applications, use and specifications, and (b) whenever customer uses the product for automotive applications beyond

NXP Semiconductors' specifications such use shall be solely at customer's own risk, and (c) customer fully indemnifies NXP Semiconductors for any liability, damages or failed product claims resulting from customer design and use of the product for automotive applications beyond NXP Semiconductors' standard warranty and NXP Semiconductors' product specifications.

**Translations** — A non-English (translated) version of a document is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

#### 17.4 Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

#### 18. Contact information

For more information, please visit: http://www.nxp.com

For sales office addresses, please send an email to: salesaddresses@nxp.com

#### Low-power X-tal driver with enable and internal resistor

## 19. Contents

1	General description	1
2	Features and benefits	1
3	Ordering information	2
4	Marking	2
5	Functional diagram	2
6	Pinning information	3
6.1	Pinning	
6.2	Pin description	
7	Functional description	3
8	Limiting values	4
9	Recommended operating conditions	4
10	Static characteristics	5
11	Dynamic characteristics	12
12	Waveforms	15
13	Application information	17
13.1	Crystal characteristics	17
13.1.1	Design	
13.1.2	Testing	19
14	Package outline	20
15	Abbreviations	25
16	Revision history	25
17	Legal information	26
17.1	Data sheet status	26
17.2	Definitions	
17.3	Disclaimers	
17.4	Trademarks	
18	Contact information	27
19	Contents	28

Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

© NXP B.V. 2012.

All rights reserved.

For more information, please visit: http://www.nxp.com For sales office addresses, please send an email to: salesaddresses@nxp.com

Date of release: 9 August 2012
Document identifier: 74AUP1Z04