10MHz.

Serially Controlled, 4-Channel Audio/Video Multiplexers

Features

- + +2.7V to +5.5V Single-Supply Operation
- 4-to-1 Channel Multiplexer
- 65 Ω (max) RoN with +5V Supply
- Audio Performance
 -83dB Off-Isolation at 20kHz
 -84dB Crosstalk at 20kHz
- Video Performance

 -48dB Off-Isolation at 10MHz
 -60dB Crosstalk at 10MHz
- Serial Interface
 2-Wire, I²C Compatible (MAX4586)
 3-Wire, SPI/QSPI/MICROWIRE Compatible (MAX4587)

Applications

General Description

The MAX4586/MAX4587 serial-interface, programmable,

4-to-1 channel multiplexers are ideal for multimedia

applications. They feature 65Ω on-resistance, 4Ω onresistance matching between channels, and 5Ω on-

resistance flatness. Additionally, they feature -83dB

off-isolation at 20kHz and -48dB off-isolation at 10MHz, with -84dB crosstalk at 20kHz and -60dB crosstalk at

The MAX4586 uses a 2-wire, I²C[™]-compatible serial

interface; the MAX4587 uses a 3-wire, SPI™/QSPI™/

MICROWIRE[™]-compatible interface. Both devices are

available in 10-pin µMAX packages and are specified

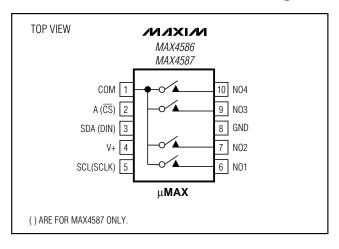
for the extended -40°C to +85°C temperature range.

Cellular Phones and Accessories Private Mobile Radios (PMRs) PC Multimedia Audio/Video Routing Industrial Equipment Set-Top Boxes Video Conferencing High-End Audio Equipment

Ordering Information

PART	TEMP. RANGE	PIN-PACKAGE
MAX4586EUB	-40°C to +85°C	10 µMAX
MAX4587EUB	-40°C to +85°C	10 µMAX

Pin Configuration/ Functional Diagram



I²C is a trademark of Philips Corp. SPI/QSPI are trademarks of Motorola, Inc. MICROWIRE is a trademark of National Semiconductor Corp.

M/X/W

_ Maxim Integrated Products 1

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ABSOLUTE MAXIMUM RATINGS

V+ to GND0.3V to +6V COM and NO_ to GND (Note 1)0.3V to (V+ + 0.3V)	
A, \overline{CS} , SDA, DIN, SCL, and SCLK to GND0.3V to +6V	
Continuous Current into Any Terminal±20mA	
Peak Current into Any Terminal	
(pulsed at 1ms, 10% duty cycle)±40mA	
ESD per Method 3015.7>2kV	

Continuous Power Dissipation ($T_A = +70^{\circ}C$)

10-Pin µMAX (derate 4.1mW/°C above +70°C)	330mW
Operating Temperature Range40°C	to +85°C
Storage Temperature Range65°C t	o +150°C
Lead Temperature (soldering, 10sec)	+300°C

Note 1: Signals on NO_ or COM exceeding V+ or ground are clamped by internal diodes. Limit forward-diode current to maximum current rating.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS—Single +5V Supply

(V+ = +5V ±5%, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
ANALOG SWITCHES							
Analog Signal Range (Note 3)	V _{NO_} , V _{COM}			0		V+	V
On-Resistance	Ron	V+ = 4.75V, V _{NO} = 3V,	$T_A = +25^{\circ}C$		45	65	Ω
Orresistance	NON	$\begin{array}{c} T_{\text{NOM}} = 50, \\ I_{\text{COM}} = 4\text{mA} \end{array} \qquad T_{\text{A}} = T_{\text{MIN}} \text{ to } T_{\text{MAX}} \end{array}$			80	52	
On-Resistance Match Between Channels	ΔR _{ON}	$V_{+} = 4.75V,$	$T_A = +25^{\circ}C$		2	4	Ω
(Note 4)	ANON	$V_{NO_} = 3V,$ $I_{COM} = 4mA$	$T_A = T_{MIN}$ to T_{MAX}			5	Ω
On-Resistance Flatness	Relat	,	$T_A = +25^{\circ}C$		2	5	Ω
(Note 5)	TFLAT	V _{NO} = 1V, 2V, 3V; I _{COM} = 4mA	$T_A = T_{MIN}$ to T_{MAX}			6.5	52
NO_ Off-Leakage Current	I _{NO_(OFF)}	V+ = 5.25V; V _{NO} = 1V, 4.5V;	$T_A = +25^{\circ}C$	-1	0.001	1	nA
(Note 6)		$V_{\rm NO} = 10, 4.5V, V_{\rm COM} = 4.5V, 1V$	$T_A = T_{MIN}$ to T_{MAX}	-10		10	
COM Off-Leakage Current		V+ = 5.25V; V _{NO} = 1V, 4.5V;	$T_A = +25^{\circ}C$	-1	0.001	1	nA
(Note 6)	ICOM(OFF)	$V_{\rm NO} = 10, 4.5V, V_{\rm COM} = 4.5V, 1V$	$T_A = T_{MIN}$ to T_{MAX}	-10		10	
COM On-Leakage Current		V+ = 5.25V; V _{NO} = 1V, 4.5V, or floating;	$T_A = +25^{\circ}C$	-1	0.002	1	nA
(Note 6)	ICOM(ON)	$V_{COM} = 1V, 4.5V$	$T_A = T_{MIN}$ to T_{MAX}	-10		10	
AUDIO PERFORMANCE							
Off-Isolation (Note 7)	VISO(A)	$V_A = 1.0V_{RMS}$, $f_{IN} = 20$ Figure 8	$V_A = 1.0V_{RMS}$, $f_{IN} = 20kHz$, $R_L = 600\Omega$, Figure 8		-83		dB
Channel-to-Channel Crosstalk	V _{CT(A)}	$V_A = 1.0V_{RMS}$, $f_{IN} = 20$ Figure 8	DkHz, $R_S = 600\Omega$,		-84		dB

ELECTRICAL CHARACTERISTICS—Single +5V Supply (continued)

(V+ = +5V ±5%, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
VIDEO PERFORMANCE				1			
Off-Isolation (Note 7)	VISO(V)	$V_A = 1.0V_{RMS}$, $f_{IN} = 10$ Figure 8	MHz, $R_L = 50\Omega$,		-48		dB
Channel-to-Channel Crosstalk	V _{CT(V)}	$V_A = 1.0V_{RMS}$, $f_{IN} = 10$ Figure 8	$V_A = 1.0V_{RMS}$, $f_{IN} = 10MHz$, $R_S = 50\Omega$, Figure 8		-60		dB
-0.1dB Bandwidth	BW	$R_{S} = 75\Omega, R_{L} = 1k\Omega$			5		MHz
-3dB Bandwidth	BW	$R_S = 50\Omega$, $R_L = 50\Omega$			300		MHz
NO_ Off-Capacitance	COFF	f _{IN} = 1MHz			5		pF
DYNAMIC TIMING (Notes 8, 9, a	and Figure 5))					
Turn-On Time	tou	V _{NO_} = 2.5V,	$T_A = +25^{\circ}C$		275	400	ns
Tum-On Time	ton	$R_L = 5k\Omega$, $C_L = 35pF$	$T_A = T_{MIN}$ to T_{MAX}			500	115
Turn-Off Time	torr	V _{NO} _ = 2.5V,	$T_A = +25^{\circ}C$		125	200	ns
Tum-On Time	toff	$R_{L} = 300\Omega, C_{L} = 35pF$	$T_A = T_{MIN}$ to T_{MAX}			250	115
Break-Before-Make Time	t _{BBM}	$V_{NO_}$ = 2.5V, Figure 6		10	50		ns
Charge Injection	Q	$C_L = 1.0nF, V_S = 0, R_S = 0, Figure 7$			3		рС
POWER SUPPLY	•			·			
Power-Supply Voltage Range	V+			2.7		5.5	V
Supply Current	l+	All logic inputs = 0 or \	/+		5	10	μA

MAX4586/MAX4587

ELECTRICAL CHARACTERISTICS—Single +3V Supply

 $(V + = +3V \pm 10\%, T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)

PARAMETER	SYMBOL	CONDITIONS		MIN	ТҮР	MAX	UNITS
ANALOG SWITCHES	1						
Analog Signal Range (Note 3)	V _{NO_} , V _{COM}			0		V+	V
On-Resistance	Ron	V+ = 2.7V, V _{NO_} = 1V,	$T_A = +25^{\circ}C$		65	110	Ω
		$I_{COM} = 4mA$	$T_A = T_{MIN}$ to T_{MAX}			130	
On-Resistance Match Between Channels	ΔR _{ON}	V+ = 2.7V, V _{NO} = 1V,	$T_A = +25^{\circ}C$		3	5	Ω
(Note 4)		$I_{COM} = 4mA$	$T_A = T_{MIN}$ to T_{MAX}			6	
On-Resistance Flatness	R _{FLAT}	V+ = 2.7V; V _{NO} = 1V, 1.5V, 2V;	$T_A = +25^{\circ}C$		3	10	Ω
(Note 5)	TIFLAT	$I_{COM} = 4mA$	$T_A = T_{MIN}$ to T_{MAX}			12	
NO_Off-Leakage Current	I _{NO_(OFF)}	V+ = 3.6V; V _{NO} = 0.5V, 3V;	$T_A = +25^{\circ}C$	-1	0.001	1	nA
(Notes 6, 10)	INO_(OFF)	$V_{COM} = 3V, 0.5V$	$T_A = T_{MIN}$ to T_{MAX}	-10		10	
COM Off-Leakage Current	ICOM(OFF)	V+ = 3.6V; V _{NO} = 0.5V, 3V;	$T_A = +25^{\circ}C$	-1	0.001	1	nA
(Notes 6, 10)		$V_{COM} = 3V, 0.5V$	$T_A = T_{MIN}$ to T_{MAX}	-10		10	
COM On-Leakage Current	ICOM(ON)	V+ = 3.6V; V _{NO} = 0.5V, 3V, or floating;	$T_{A} = +25^{\circ}C$	-1	0.002	1	nA
(Notes 6, 10)	. ,	V _{COM} = 0.5V, 3V	$T_A = T_{MIN}$ to T_{MAX}	-10		10	
AUDIO PERFORMANCE	1	I		- I			[
Off-Isolation (Note 7)	V _{ISO(A)}	$V_A = 0.5V_{RMS}$, $f_{IN} = 2$ Figure 8	20 kHz, R _L = 600 Ω ,		-83		dB
Channel-to-Channel Crosstalk	V _{CT(A)}	$V_A = 0.5V_{RMS}$, $f_{IN} = 2$ Figure 8	20 kHz, R _S = 600 Ω ,		-84		dB
VIDEO PERFORMANCE							
Off-Isolation (Note 7)	V _{ISO(V)}	$V_A = 0.5V_{RMS}$, $f_{IN} = 1$ Figure 8	$OMHz, R_L = 50\Omega,$		-48		dB
Channel-to-Channel Crosstalk	V _{CT(V)}	$V_A = 0.5V_{RMS}$, $f_{IN} = 1$ Figure 8	$V_A = 0.5V_{RMS}$, $f_{IN} = 10MHz$, $R_S = 50\Omega$, Figure 8		-60		dB
-3dB Bandwidth	BW	$R_{\rm S} = 50\Omega, R_{\rm L} = 50\Omega$	•		200		MHz
NO_ Off-Capacitance	COFF	f _{IN} = 1MHz			5		рF
DYNAMIC TIMING (Notes 8, 9,	and Figure 5)					
Turn-On Time	t _{ON}	V _{NO} _ = 1.5V, R _L = 5kΩ, C _L = 35pF	$T_A = +25^{\circ}C$ $T_A = T_{MIN}$ to T_{MAX}		400	800 1000	ns
Turn-Off Time	toff	$V_{NO_{-}} = 1.5V,$ $R_{L} = 300\Omega, C_{L} = 35pl$	$T_A = +25^{\circ}C$		200	350	ns
Dreak Defere Males Times	-			10	100	500	
Break-Before-Make Time	tввм	V_{NO} = 1.5V, Figure 6)	10	100		ns

4

M/IXI/M

I/O INTERFACE CHARACTERISTICS

(V+ = +2.7V to +5.25V, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
DIGITAL INPUTS (SCLK, DIN	, CS , SCL, SD	A, A)					
Input Low Voltage	Mu	V+ = 5V			0.8	V	
	VIL	V+ = 3V			0.6] `	
Input High Voltage		V+ = 5V	3			- V	
input high voltage	VIH	V+ = 3V	2				
Input Hysteresis	VHYST			0.2		V	
Input Leakage Current	ILEAK	Digital inputs = 0 or V+	-1	0.01	1	μA	
Input Capacitance	CIN	f = 1MHz		5		pF	
DIGITAL OUTPUT (SDA)			•				
Output Low Voltage	Vol	Isink = 6mA			0.4	V	

2-WIRE TIMING CHARACTERISTICS

(Figures 1 and 2, V+ = +2.7V to +5.25V, f_{SCL} = 100kHz, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at T_A = +25°C.)

SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
face	V+ = 2.7V to 5.25V	0		100	kHz
ISCL	V+ = 4.75V to 5.25V			400	
tBUF		4.7			μs
thd:sta	The first clock is generated after this period.	4.0			μs
tsu:sto		4.0			μs
thd:dat		0			μs
tsu:dat		250			ns
tlow		4.7			μs
thigh		4.0			μs
t _R		20 + 0.1C _B		300	ns
tF		20 + 0.1C _B		300	ns
	fscl tBUF thD:STA tsU:STO thD:DAT tSU:DAT tLOW tHIGH tR	fscl V+ = 2.7V to 5.25V fscl V+ = 4.75V to 5.25V tBUF Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto Image: The first clock is generated after this period. tsu:sto	$f_{SCL} = \frac{V + = 2.7V \text{ to } 5.25V}{V + = 4.75V \text{ to } 5.25V} 0$ $f_{BUF} = \frac{4.7}{4.7}$ $f_{HD:STA} = \frac{The first clock is generated after this period.}{100} 4.0$ $f_{HD:DAT} = \frac{4.0}{00}$ $f_{HD:DAT} = \frac{00}{100}$ $f_{LOW} = \frac{100}{100} 4.0$ $f_{HGH} = \frac{100}{100} 4.0$ $f_{R} = \frac{20 + 0.1CB}{20 + 0.1CB}$	Image: state of the second state of the se	f_{SCL} V+ = 2.7V to 5.25V 0 100 f_{SCL} V+ = 4.75V to 5.25V 400 t_{BUF} 4.7 400 t_{HD:STA} The first clock is generated after this period. 4.0 t_{US:STO} 4.0 4.0 t_{HD:DAT} 0 250 t_LOW 4.7 4.0 t_HIGH 4.0 300 t_R 20 + 0.1C_B 300

MAX4586/MAX4587

3-WIRE TIMING CHARACTERISTICS

(Figures 3 and 4, V+ = +2.7V to +5.25V, f_{OP} = 2.1MHz, T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
Operating Frequency	for	V+ = 2.7V to 5.25V	0		2.1	MHz
Operating Frequency	fop	V+ = 4.75V to 5.25V			10	
DIN to SCLK Setup	tDS		100			ns
DIN to SCLK Hold	tDH		0			ns
CS Fall to SCLK Rise Setup	tcss		100			ns
CS Rise to SCLK Hold	tcsh		0			ns
SCLK Pulse Width Low	tCL		200			ns
SCLK Pulse Width High	tсн		200			ns
Rise Time (SCLK, DIN, CS)	t _R				2	μs
Fall Time (SCLK, DIN, CS)	tF				2	μs
CS Pulse Width High	tcsw			40		ns

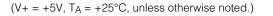
Note 2: Algebraic convention is used in this data sheet; the most negative value is shown in the minimum column.

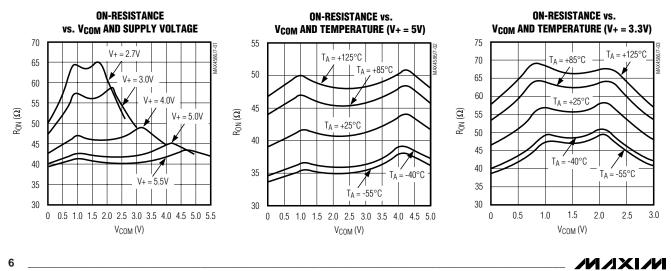
- Note 3: Guaranteed by design. Not subject to production testing.
- Note 4: $\Delta R_{ON} = R_{ON}(MAX) R_{ON}(MIN)$.
- **Note 5:** Resistance flatness is defined as the difference between the maximum and minimum on-resistance values, as measured over the specified analog signal range.
- Note 6: Leakage parameters are 100% tested at maximum rated temperature and guaranteed by correlation at $T_A = +25^{\circ}C$.
- Note 7: Off-isolation = 20log (V_{COM} / V_{NO}), V_{COM} = output, V_{NO} = input to off switch.

Note 8: All timing is measured from the clock's falling edge preceding the ACK signal for 2-wire and from the rising edge of \overline{CS} for 3-wire. Turn-off time is defined at the output of the switch for a 0.5V change, tested with a 300 Ω load to ground. Turn-on time is defined at the output of the switch for a 0.5V change and measured with a 5k Ω load resistor to GND. All timing is shown with respect to 20% V+ and 70% V+, unless otherwise noted.

Note 9: Typical values are for MAX4586 devices.

- **Note 10:** Leakage testing is guaranteed by testing with a +5.25V supply.
- Note 11: C_B = capacitance of one bus line in pF. Tested with C_B = 400pF.



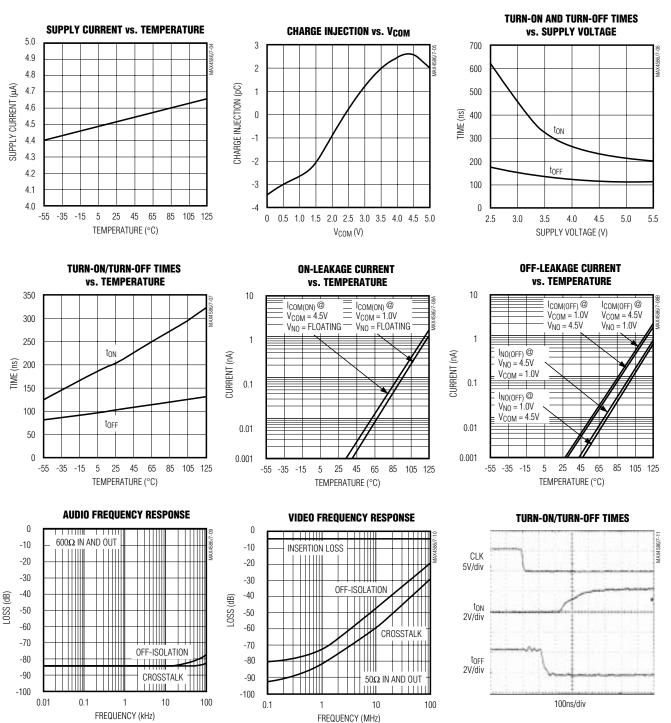


Typical Operating Characteristics

/N/IXI/N

Serially Controlled, 4-Channel Audio/Video Multiplexers

Typical Operating Characteristics (continued) (V+ = +5V, T_A = +25°C, unless otherwise noted.)



7

Pin Description

Р	IN		FUNCTION
MAX4586	MAX4587	NAME	FUNCTION
1	1	COM	Analog Switch Common Terminal
2	—	А	LSB + 2 of the 2-Wire Serial-Interface Address Field
_	2	CS	Chip Select of the 3-Wire Serial Interface
3	—	SDA	Data Input of 2-Wire Serial Interface
	3	DIN	Data Input of 3-Wire Serial Interface
4	4	V+	Supply Voltage
5	—	SCL	Clock Input of the 2-Wire Serial Interface
—	5	SCLK	Clock Input of the 3-Wire Serial Interface
6	6	NO1	Mux Normally Open Output 1
7	7	NO2	Mux Normally Open Output 2
8	8	GND	Ground
9	9	NO3	Mux Normally Open Output 3
10	10	NO4	Mux Normally Open Output 4

Detailed Description

The MAX4586/MAX4587 are serial-interface, programmable multiplexers. Each device contains a 4-to-1 normally open (NO) multiplexer. Each switch is independently controlled through the on-chip serial interface. The MAX4586 uses a 2-wire, I²C-compatible serial communications protocol, and the MAX4587 uses a 3-wire, SPI/QSPI/ MICROWIRE-compatible serial communications protocol.

These devices operate from a single +2.7V to +5.5V supply and are optimized for use with an audio frequency at 20kHz and video frequencies up to 10MHz. They feature 65 Ω on-resistance, 4Ω on-resistance matching between channels, and 5Ω on-resistance flatness. Audio off-isolation is -83dB at 20kHz and crosstalk is at least -84dB at 20kHz, while video off-isolation is -48dB at 10MHz and crosstalk is at least -60dB at 10MHz.

Applications Information

Multiplexer Control

The MAX4586/MAX4587 have a common command-bit structure; the only difference between them is the interface type (2-wire or 3-wire, respectively).

The command controls the open/closed states of the various switches. Table 1 shows the configuration of the data bits and their related switches. After a command is issued, a logic "1" in any data-bit location closes the associated switch, while a logic "0" opens it (Table 2).

2-Wire Serial Interface

/N/IXI/N

The MAX4586 uses a 2-wire, I²C-compatible serial interface. The COM_ register uses the "SendByte" protocol that consists of an address byte followed by a command byte (Table 1).

To address a given chip, the A bit in the address byte must duplicate the value present at the A pin of that chip. The rest of the address bits must match those shown in Table 3. The command byte details are described in the *Switch Control* section.

The 2-wire serial interface requires only two I/O lines of a standard microprocessor (μ P) port. Figures 1 and 2 detail the timing diagram for signals on the 2-wire bus, and Tables 1 and 3 detail the format of the signals. The MAX4586 is a receive-only device and must be controlled by the bus master device. A bus master device communicates by transmitting the address byte of the slave device over the bus and then transmitting the desired information. Each transmission consists of a start condition, an address byte, a command byte, and finally a stop condition. The slave device acknowledges the recognition of its address by pulling the SDA line low for one clock period after the address byte is transmitted. The slave device also issues a similar acknowledgment after the command byte.

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Table 1. Command-Bit Mapping

COMMAND BIT	SWITCH	TERMINALS	POWER-UP STATE					
D7 (MSB)	х		х					
D6	х		х					
D5	х		х					
D4	х		х					
D3	NO4 to COM	10, 1	0 (Open)					
D2	NO3 to COM	9, 1	0 (Open)					
D1	NO2 to COM	7, 1	0 (Open)					
D0 (LSB)	NO1 to COM	6, 1	0 (Open)					
V Deniteer								

Table 2. Truth Table

LOGIC	NO_ SWITCH
0	OPEN
1	CLOSED

Table 3. Address Bit Map

ADDRESS BIT (A)	ADDRESS
0	0110 1010
1	0110 1110

X = Don't care

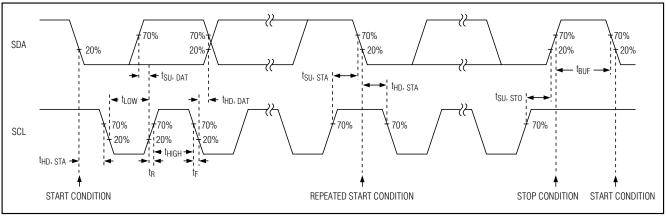


Figure 1. 2-Wire Serial-Interface Timing Diagram

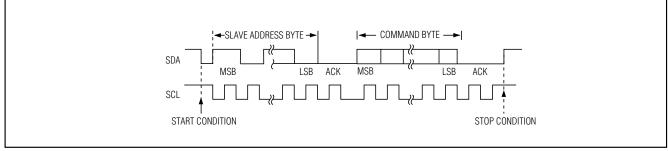


Figure 2. Complete 2-Wire Serial-Interface Transmission

Start and Stop Conditions

The bus master signals the beginning of a transmission with a start condition by transitioning SDA from high to low while SCL is high. When the bus master has finished communicating with the slave device, it issues a stop condition by transitioning SDA from low to high while SCL is high. The bus master is then free for another transmission.

Slave Address (Address Byte)

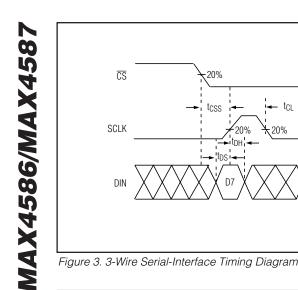
The MAX4586 uses an 8-bit-long slave address. To select a slave address, connect A to V+ or GND. The MAX4586 has two possible slave addresses, so a maximum of two of these devices may share the same address line. The slave device MAX4586 monitors the serial bus continuously, waiting for a start condition followed by an address byte. When a slave device recog-

tсн

20% 209

70%

D.



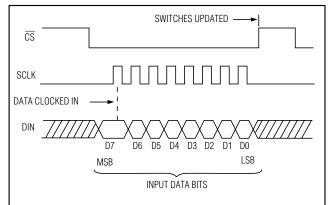


Figure 4. Complete 3-Wire Serial Transmission

nizes its address (01101A10), it acknowledges that it is ready for further communication by pulling the SDA line low for one clock period.

3-Wire Serial Interface

The MAX4587 3-wire serial interface is SPI/QSPI/ MICROWIRE compatible. An active-low chip-select (\overline{CS}) input enables the device to receive data for the serial input (DIN). Data is clocked in on the rising edge of the serial-clock (SCLK) signal. A total of 8 bits is needed in each write cycle. The first bit clocked into the MAX4587 is the command byte's MSB, and the last bit clocked in is the data byte's LSB. The first four bits of the command byte are "don't care." While shifting data, the device remains in its original configuration. After all eight bits are clocked into the input shift register, a rising edge on \overline{CS} latches the data into the MAX4587 internal registers, initiating the device's change of state. Figures 3 and 4 detail the 3-wire protocol, and Table 1 details the command byte format.

20° tosh

20%

D0

70%

Addressable Serial Interface

To program several MAX4587s individually using a single processor, connect DIN of each MAX4587 together and control \overline{CS} on each MAX4587 separately. To select a particular device, drive the corresponding \overline{CS} low, clock in the 8-bit command, then drive \overline{CS} high to execute the command. Typically, only one MAX4587 is addressed at a time.

Power-Up State

The MAX4586/MAX4587 feature a preset power-up state. See Table 1 to determine the power-up state of the devices.

Chip Information

TRANSISTOR COUNT: 2259

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Test Circuits/Timing Diagrams

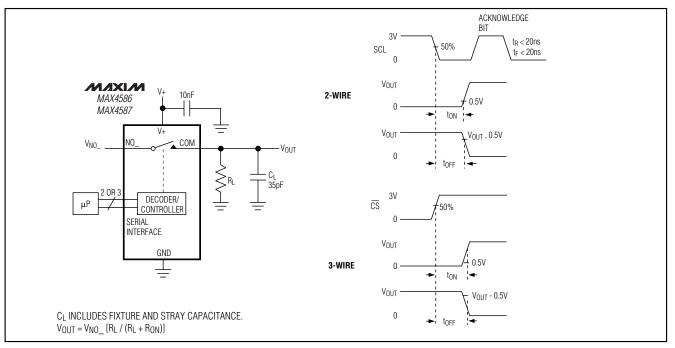


Figure 5. Switching Time

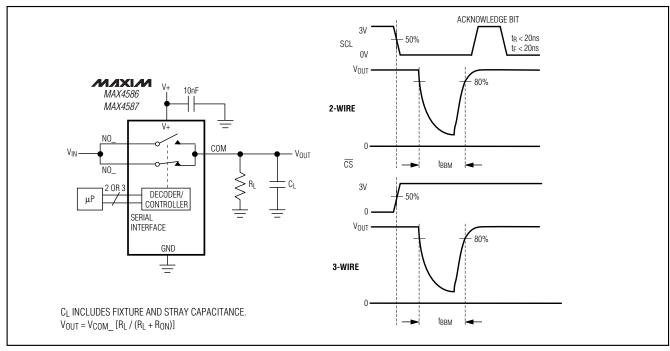
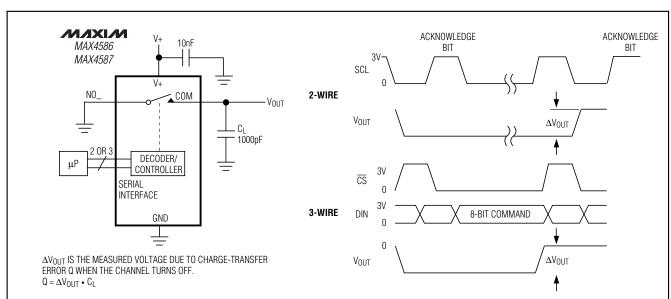


Figure 6. Break-Before-Make Interval

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Test Circuits/Timing Diagrams (continued)

Figure 7. Charge Injection

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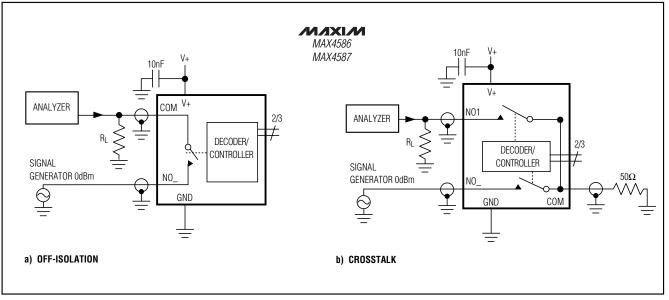


Figure 8. Off-Isolation and Crosstalk

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