



### **General Description**

The MAX9242/MAX9244/MAX9246/MAX9254 deserialize three LVDS serial-data inputs into 21 single-ended LVC-MOS/LVTTL outputs. A separate parallel-rate LVDS clock provides the timing for deserialization. The MAX9242/ MAX9244/MAX9246/MAX9254 feature spread-spectrum capability, allowing the output data and clock frequency to spread over a specified range to reduce EMI. The single-ended data and clock outputs are programmable for a frequency spread of ±2%, ±4%, or no spread. The spread-spectrum function is also available when the MAX9242/MAX9244/MAX9246/MAX9254 operate in non-DC-balanced mode. The modulation rate of the spread is 32kHz for a 33MHz LVDS clock input and scales linearly with frequency. The single-ended outputs have a separate supply, allowing +1.8V to +5V output logic levels.

The MAX9254 features high output drive current for both data and clock outputs for faster transition times in the presence of heavy capacitive loads.

The MAX9242/MAX9244/MAX9246/MAX9254 feature programmable DC balance, allowing isolation between a serializer and deserializer using AC-coupling. The MAX9242/MAX9244/MAX9246/MAX9254 operate with the MAX9209/MAX9213 serializers and are available with a rising-edge strobe (MAX9242) or falling-edge strobe (MAX9244/MAX9246/MAX9254). The LVDS inputs meet ISO 10605 ESD specifications with ±30kV Air-Gap Discharge and ±6kV Contact Discharge ratings.

#### **Applications**

Automotive Navigation Systems Automotive DVD Entertainment Systems **Digital Copiers** Laser Printers

#### **Selector Guide**

			FREQUEN	CY RANGE
PART	STROBE EDGE	-		DC BALANCE (MHz)
MAX9242	Rising	Yes	20 to 40	16 to 34
MAX9244	Falling	Yes	20 to 40	16 to 34
MAX9246	Falling	No	8 to 20	6 to 18
MAX9254	Falling	Yes	20 to 40	16 to 34

Pin Configuration appears at end of data sheet.

#### **Features**

- Programmable ±4%, ±2%, or OFF Spread-Spectrum Output for Reduced EMI
- ♦ Programmable DC-Balanced or Non-DC-Balanced Modes
- ◆ DC Balance Allows AC-Coupling for Wider Input Common-Mode Voltage Range
- Spread Spectrum Operates in DC-Balanced or Non-DC-Balanced Mode
- High Output Drive (MAX9254)
- ♦ π/4 Deskew by Oversampling (MAX9242/MAX9244/MAX9254)
- ◆ 16MHz-to-34MHz (DC-Balanced) and 20MHz-to-40MHz (Non-DC-Balanced) Operation (MAX9242/MAX9244/MAX9254)
- ♦ 6MHz-to-18MHz (DC-Balanced) and 8MHz-to-20MHz (Non-DC-Balanced) Operation (MAX9246)
- ♦ Rising-Edge (MAX9242) or Falling-Edge (MAX9244/MAX9246/MAX9254) Output Strobe
- ♦ High-Impedance Outputs when PWRDWN is Low Allow Output Busing
- ♦ Separate Output Supply Allows Interface to +1.8V, +2.5V, +3.3V, and +5V Logic
- ♦ LVDS Inputs Meet ISO 10605 ESD Protection at ±30kV Air-Gap Discharge and ±6kV Contact
- ◆ LVDS Inputs Meet IEC 61000-4-2 Level 4 ESD Protection at ±15kV Air-Gap Discharge and ±8kV **Contact Discharge**
- **♦ LVDS Inputs Conform to ANSI TIA/EIA-644 Standard**
- ♦ +3.3V Main Power Supply

## **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
MAX9242EUM	-40°C to +85°C	48 TSSOP
MAX9242EUM/V+	-40°C to +85°C	48 TSSOP
MAX9242GUM	-40°C to +105°C	48 TSSOP
MAX9242GUM/V+	-40°C to +105°C	48 TSSOP
MAX9244EUM	-40°C to +85°C	48 TSSOP
MAX9244EUM/V+	-40°C to +85°C	48 TSSOP
MAX9244GUM	-40°C to +105°C	48 TSSOP
MAX9244GUM/V+	-40°C to +105°C	48 TSSOP

+Denotes a lead(Pb)-free/RoHS-compliant package. /V denotes an automotive qualified part.

Note: All devices are available in lead(Pb)-free/RoHS-compliant packaging. Specify lead(Pb)-free/RoHS compliant by adding a + symbol at the end of the part number when ordering.

Ordering Information continued at end of data sheet.

Maxim Integrated Products 1

#### **ABSOLUTE MAXIMUM RATINGS**

(All voltages referenced to GND.)
Vcc, LVDSVcc, PLLVcc0.5V to +4.0V
V <sub>CCO</sub> 0.5V to +6.0V
RxIN, RxCLKIN0.5V to +4.0V
PWRDWN0.5V to +6.0V
SSG, DCB0.5V to (V <sub>CC</sub> + 0.5V)
RxOUT_, RxCLKOUT0.5V to (Vcco + 0.5V)
Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )
48-Pin TSSOP (derate 16mW/°C above +70°C)1282mW
ESD Protection
Human Body Model (R <sub>D</sub> = 1.5k $\Omega$ , C <sub>S</sub> = 100pF)
All Pine to GND +2.5kV

IEC 61000-4-2 ( $R_D = 330\Omega$ , $C_S = 150pF$ )	
LVDS Inputs to GND (Air-Gap Discharge)	±15kV
LVDS Inputs to GND (Contact Discharge)	±8kV
ISO 10605 ( $R_D = 2.0k\Omega$ , $C_S = 330pF$ )	
LVDS Inputs to GND (Air-Gap Discharge)	±30kV
LVDS Inputs to GND (Contact Discharge)	±6kV
Operating Temperature Range	40°C to +105°C
Storage Temperature Range	65°C to +150°C
Junction Temperature	+150°C
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### DC ELECTRICAL CHARACTERISTICS

 $(V_{CC} = LVDSV_{CC} = PLLV_{CC} = +3.0V \text{ to } +3.6V, V_{CCO} = +3.0V \text{ to } +5.5V, \overline{PWRDWN} = \text{high; SSG} = \text{high, open, or low; DCB} = \text{high or low, differential input voltage } |V_{ID}| = 0.05V \text{ to } 1.2V, \text{input common-mode voltage } |V_{CM}| = |V_{ID}| / 2| \text{ to } 2.4V - |V_{ID}| / 2|, \text{ unless otherwise noted. Typical values are at } |V_{CC}| = |V_{CC}$ 

PARAMETER	SYMBOL	CONDITIONS			MIN	TYP	MAX	UNITS
POWER SUPPLY								
Power-Supply Range	V <sub>CC</sub> , LVDSV <sub>CC</sub> , PLLV <sub>CC</sub>				3.0		3.6	V
Output-Supply Range	Vcco				1.8		5.5	V
			DC-balanced	16MHz		50	68	
		C <sub>L</sub> = 8pF, worst-case pattern, V <sub>CC</sub> = V <sub>CCO</sub> = 3.0V	mode (SSG = low)	34MHz		81	108	
			Non-DC-balanced mode (SSG = low)	20MHz		55	73	
				33MHz		75	97	
Worst Cose Cumply Current				40MHz		83	110	m ^
Worst-Case Supply Current	ICCW	to 3.6V, Figure 2 (MAX9242,	DC-balanced mode	16MHz		62	85	mA
		MAX9244,	(SSG = high or open)	34MHz		101	135	
		MAX9254)	Non-DC-balanced	20MHz		67	91	
			mode	33MHz		93	123	
			(SSG = high or open)	40MHz		107	134	

#### DC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = LVDSV_{CC} = PLLV_{CC} = +3.0V \ to \ +3.6V, \ V_{CCO} = +3.0V \ to \ +5.5V, \ \overline{PWRDWN} = high; \ SSG = high, \ open, \ or \ low; \ DCB = high \ or \ low, \ differential input voltage \ |V_{ID}| = 0.05V \ to \ 1.2V, \ input \ common-mode \ voltage \ V_{CM} = |V_{ID}| / 2l \ to \ 2.4V - |V_{ID}| / 2l, \ unless \ otherwise \ noted. \ Typical values are at \ V_{CC} = V_{CCO} = LVDSV_{CC} = PLLV_{CC} = +3.3V, \ |V_{ID}| = 0.2V, \ V_{CM} = +1.25V, \ T_A = +25^{\circ}C.) \ (Notes \ 1, 2)$ 

PARAMETER	SYMBOL	CONDITIONS			MIN	TYP	MAX	UNITS	
			5011	6MHz		29	45		
			DC-balanced mode (SSG = low)	<sub>()</sub> 8MHz		33	49	1	
			1110de (33d = 10v	18MHz		48	69		
			N. DOLL	. 8MHz		33	47		
		$C_L = 8pF,$	Non-DC-balance mode (SSG = lov	1/11/11		37	52		
Worst-Case Supply Current	Iccw	worst-case pattern, VCC = VCCO = 3.0V	111000 (000 = 101	20MHz		52	73	mA	
Worst-Case Supply Current	ICCVV	to 3.6V, Figure 2	DO le element de mande	6MHz		37	54	IIIA	
		(MAX9246)	DC-balanced mod (SSG = high or ope	1 8MHz		41	62		
			(OOG = Hightor ope	18MHz		65	91		
			Non-DC-balanced	8MHz		41	58		
			mode	10MHz		46	65		
			(SSG = high or ope	en) 20MHz		66	92		
Power-Down Supply Current	Iccz	PWRDWN = low					50	μΑ	
5V-TOLERANT LOGIC INPUT (P	WRDWN)								
High-Level Input Voltage	V <sub>IH</sub>				2.0		5.5	V	
Low-Level Input Voltage	VIL				-0.3		+0.8	V	
Input Current	I <sub>IN</sub>	$\overline{PWRDWN}$ = high or	low level		-20		+20	μΑ	
Input Clamp Voltage	V <sub>C</sub> L	I <sub>CL</sub> = -18mA			-1.5			V	
THREE-LEVEL LOGIC INPUTS (	DCB, SSG)								
High-Level Input Voltage	VIH				2.5		V <sub>CC</sub> + 0.3	V	
Mid-Level Input Current	I <sub>IM</sub>	DCB, SSG open or connected to a driver with output in high-impedance state (Note 3)			-10		+10	μΑ	
Low-Level Input Voltage	V <sub>IL</sub>				-0.3		+0.8	V	
Input Current	I <sub>IN</sub>	DCB, SSG = high or $\overline{PWRDWN}$ = high or			-20		+20	μΑ	
Input Clamp Voltage	V <sub>CL</sub>	I <sub>CL</sub> = -18mA			-1.5			V	
SINGLE-ENDED OUTPUTS (RxC	OUT_, RxCL	(OUT)						ı	
		I <sub>OH</sub> = -100μA			Vcco - 0.1				
High Loyal Output Valtage	Vari		RxCLKOUT (N	ote 4)	V <sub>C</sub> CO - 0.25			V	
High-Level Output Voltage	Voн	I <sub>OH</sub> = -2mA	DVOLIT		V <sub>CCO</sub> - 0.43			V	
			RxOUT_ MA	MAX9254	V <sub>C</sub> CO - 0.25				
		I <sub>OL</sub> = 100μA		$I_{OL} = 100\mu A$			0.1		
Low-Level Output Voltage	V <sub>OL</sub>	I <sub>OL</sub> = 2mA	RxCLKOUT (Note 4)				0.2	] <sub>v</sub>	
25.1 25.0. Calput Voltago	VOL		RxOUT_				0.26	1	
				MAX9254			0.2		

### DC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = LVDSV_{CC} = PLLV_{CC} = +3.0V \ to \ +3.6V, \ V_{CCO} = +3.0V \ to \ +5.5V, \ \overline{PWRDWN} = high; \ SSG = high, \ open, \ or \ low; \ DCB = high \ or \ low, \ differential input voltage \ IV_{ID} = 0.05V \ to \ 1.2V, \ input \ common-mode \ voltage \ V_{CM} = IV_{ID} \ / \ 2I \ to \ 2.4V \ - IV_{ID} \ / \ 2I, \ unless \ otherwise \ noted. \ Typical \ values \ are \ at \ V_{CC} = V_{CCO} = LVDSV_{CC} = PLLV_{CC} = +3.3V, \ |V_{ID}| = 0.2V, \ V_{CM} = +1.25V, \ T_A = +25^{\circ}C.) \ (Notes \ 1, \ 2)$ 

PARAMETER	SYMBOL	CONDITIO	DNS	MIN	TYP	MAX	UNITS
High-Impedance Output Current	loz	$\overline{PWRDWN}$ = low, $V_{OUT}$ = -0.3V to ( $V_{CCO}$ + 0.3V)		-30		+30	μΑ
		$V_{CCO} = 3.0V \text{ to } 3.6V,$	RxCLKOUT (Note 4)	-10		-40	
Output Short-Circuit Current	loo	V <sub>OUT</sub> = 0V	RxOUT_	-5		-20	mA
(Note 5)	los	$V_{CCO} = 4.5V \text{ to } 5.5V,$	RxCLKOUT (Note 4)	-28		-75	IIIA
		V <sub>OUT</sub> = 0V	RxOUT_	-13		-37	
		$V_{CCO} = 3.0V \text{ to } 3.6V,$	RxOUT_	-16		-51	
Output Short-Circuit Current	loo	$V_{OUT} = 0V$	RxCLKOUT (Note 4)	-10		-31	mA
(MAX9254) (Note 5)	los	$V_{CCO} = 4.5V \text{ to } 5.5V,$	RxOUT_	0.4	-	-93	IIIA
		V <sub>OUT</sub> = 0V	RxCLKOUT (Note 4)	-34			
LVDS INPUTS (RxIN, RxCLKI	N_)						
Differential Input High Threshold	V <sub>TH</sub>	(Note 6)				50	mV
Differential Input Low Threshold	V <sub>TL</sub>	(Note 6)		-50			mV
Input Current	I <sub>IN+</sub> , I <sub>IN-</sub>	PWRDWN = high or low		-25		+25	μΑ
Power-Off Input Current	I <sub>INO+</sub> , I <sub>INO-</sub>	V <sub>CC</sub> = V <sub>CCO</sub> = 0V or open		-40		+40	μΑ
Input Resistor 1	R <sub>IN1</sub>	PWRDWN = high or low,	-40°C to +85°C	42		78	kΩ
input nesistor i	UlV1	V <sub>CC</sub> = V <sub>CCO</sub> = 0V or open, Figure 1	-40°C to +105°C	42		85	K32
Input Posistor 2	Pivio	PWRDWN = high or low,	-40°C to +85°C	246		410	1.0
Input Resistor 2	R <sub>IN2</sub>	V <sub>CC</sub> = V <sub>CCO</sub> = 0V or open, Figure 1	-40°C to +105°C	246		440	kΩ

#### **AC ELECTRICAL CHARACTERISTICS**

 $(\text{VCC} = \text{LVDSV}_{\text{CC}} = \text{PLLV}_{\text{CC}} = +3.0 \text{V to } +3.6 \text{V}, \text{V}_{\text{CCO}} = +3.0 \text{V to } +3.6 \text{V}, \text{C}_{\text{L}} = 8 \text{pF}, \overline{\text{PWRDWN}} = \text{high}; \text{SSG} = \text{high}, \text{open, or low}; \text{DCB} = \text{high or low}, \text{differential input voltage } |V_{\text{ID}}| = 0.1 \text{V to } 1.2 \text{V}, \text{input common-mode voltage } |V_{\text{CM}}| = |V_{\text{ID}}| / 2 \text{I to } 2.4 \text{V} - |V_{\text{ID}}| / 2 \text{I, unless otherwise noted.} \text{Typical values are at } |V_{\text{CC}}| = \text{LVDSV}_{\text{CC}} = \text{PLLV}_{\text{CC}} = +3.3 \text{V}, \text{V}_{\text{ID}}| = 0.2 \text{V}, \text{V}_{\text{CM}} = +1.25 \text{V}, \text{T}_{\text{A}} = +25 \text{°C.} ) \text{ (Notes 6, 7, 8)}$ 

PARAMETER	SYMBOL	CONDITION	IS	MIN	TYP	MAX	UNITS
Output Rise Time	CLHT	0.1 x V <sub>CCO</sub> to 0.9 x V <sub>CCO</sub> ,	RxOUT_	2.9	4.7	6.5	no
Output Rise Time	CLHI	Figure 3	RxCLKOUT	2.0	3.3	4.1	ns
Output Fall Time	CHLT	0.9 x V <sub>CCO</sub> to 0.1 x V <sub>CCO</sub> ,	RxOUT_	2.1	3.0	4.2	200
Output Fall Time	CHLI	Figure 3	RxCLKOUT	1.10	1.94	2.70	ns
Output Rise Time (MAX9254)	CLHT	0.1 x V <sub>CCO</sub> to 0.9 x V <sub>CCO</sub> , Figure 3	RxOUT_	1.4	2.2	3.3	ns
Output Fall Time (MAX9254)	CHLT	0.9 x V <sub>CCO</sub> to 0.1 x V <sub>CCO</sub> , Figure 3	RxCLKOUT	1.1	1.8	2.8	ns
		DC-balanced mode,	16MHz	2560	3142		
RxIN Skew Margin (Note 9)	RSKM	Figure 4	34MHz	900	1386		no
HXIII_ Skew Margill (Note 9)	nonivi	Non-DC-balanced mode,	20MHz	2500	3164		ps
		Figure 4	40MHz	960	1371	•	

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#### AC ELECTRICAL CHARACTERISTICS (continued)

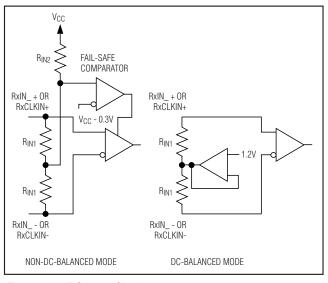
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PARAMETER	SYMBOL	CONDITIO	CONDITIONS		TYP	MAX	UNITS
RxCLKOUT High Time	RCOH	Figures 5a, 5b		0.35 x RCOP			ns
RxCLKOUT Low Time	RCOL	Figures 5a, 5b		0.35 x RCOP			ns
RxOUT_ Setup to RxCLKOUT	RSRC	Figures 5a, 5b		0.3 x RCOP			ns
RxOUT_ Hold from RxCLKOUT	RHRC	Figures 5a, 5b		0.45 x RCOP			ns
RxCLKIN_ to RxCLKOUT Delay	RCCD	SSG = low, Figures 6a, 6b		4.5 + (RCIP / 2)	6.5 + (RCIP / 2)	8.2 + (RCIP / 2)	ns
Deserializer Phase-Locked- Loop Set	RPLLS	Figure 7				65,600 x RCIP	ns
Deserializer Power-Down Delay	RPDD	Figure 8				100	ns
Deserializer Phase-Locked- Loop Set from SSG Change	RPLLS2	Figure 9				32,800 x RCIP	ns
		SSG = high,	Maximum output frequency	fRxCLKIN_ + 3.6%	fRxCLKIN_ + 4.0%	f <sub>RxCLKIN</sub> _ + 4.4%	
Caracad Carachaura Cutaut		Figure 10	Minimum output frequency	f <sub>RxCLKIN</sub> _ - 4.4%	fRxCLKIN_ - 4.0%	f <sub>RxCLKIN</sub> _ - 3.6%	
Spread-Spectrum Output Frequency  fRxCLKC		SSG = open,	Maximum output frequency	fRxCLKIN_ + 1.8%	fRxCLKIN_ + 2.0%	f <sub>RxCLKIN</sub> _ + 2.2%	MHz
		Figure 10	Minimum output frequency	fRxCLKIN_ - 2.2%	fRxCLKIN_ - 2.0%	f <sub>RxCLKIN</sub> _ - 1.8%	
		SSG = low		fRxCLKIN_		fRxCLKIN_	
Spread-Spectrum Modulation Frequency	f <sub>SSM</sub>	Figure 10			f <sub>RxCLKIN_</sub> / 1016		Hz

- Note 1: Current into a pin is defined as positive. Current out of a pin is defined as negative. All voltages are referenced to ground, except V<sub>TH</sub> and V<sub>TL</sub>.
- **Note 2:** Maximum and minimum limits over temperature are guaranteed by design and characterization. Devices are production tested at T<sub>A</sub> = +25°C.
- Note 3: To provide a mid level, leave the input open, or, if driven, put driver in high impedance. High-impedance leakage current must be less than ±10µA.
- Note 4: RxCLKOUT limits are scaled based on RxOUT\_measurements, design, and characterization data.
- Note 5: One output shorted at a time. Current out of the pin.
- **Note 6:** V<sub>TH</sub>, V<sub>TL</sub>, and AC parameters are guaranteed by design and characterization, and are not production tested. Limits are set at ±6 sigma.
- Note 7: C<sub>L</sub> includes probe and test jig capacitance.
- Note 8: RCIP is the period of RxCLKIN\_. RCOP is the period of RxCLKOUT.
- Note 9: RSKM is measured with less than 150ps cycle-to-cycle jitter on RxCLKIN\_.



### **Test Circuits/Timing Diagrams**



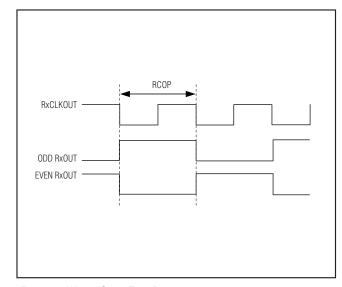


Figure 1. LVDS Input Circuits

Figure 2. Worst-Case Test Pattern

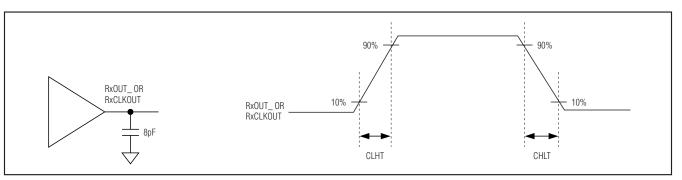


Figure 3. Output Load and Transition Times

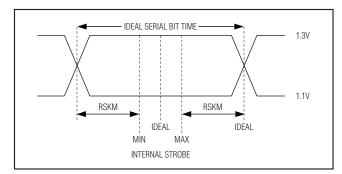


Figure 4. LVDS Receiver Input Skew Margin

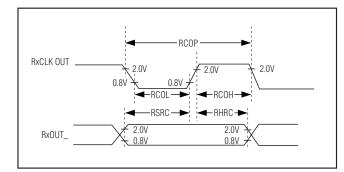


Figure 5a. Rising-Edge Output Setup/Hold and High/Low Times

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## Test Circuits/Timing Diagrams (continued)

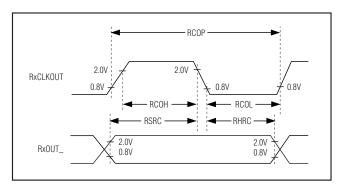
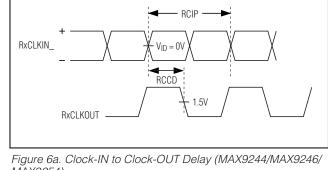


Figure 5b. Falling-Edge Output Setup/Hold and High/Low Times



MAX9254)

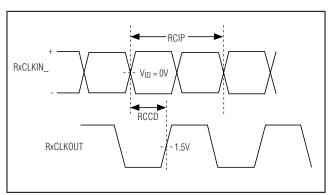


Figure 6b. Clock-IN to Clock-OUT Delay (MAX9242)

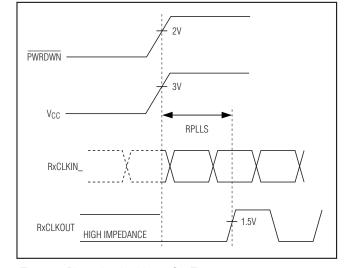


Figure 7. Phase-Locked-Loop Set Time

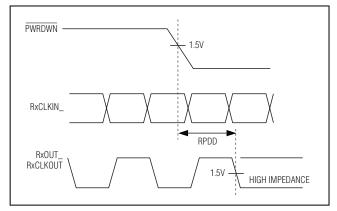


Figure 8. Power-Down Delay

### Test Circuits/Timing Diagrams (continued)

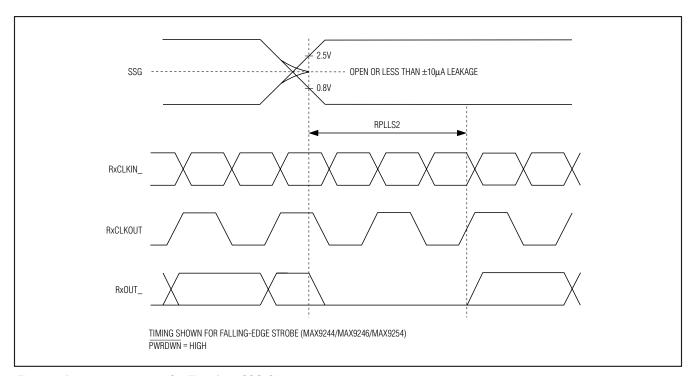


Figure 9. Phase-Locked-Loop Set Time from SSG Change

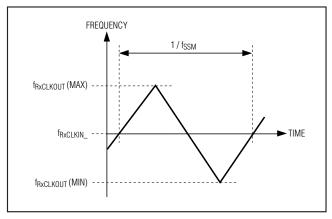
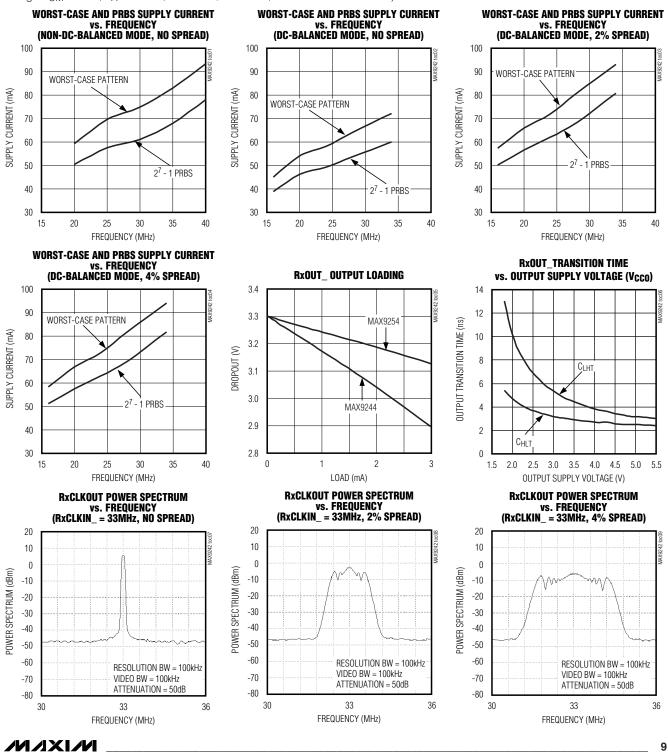


Figure 10. Simplified Modulation Profile

### **Typical Operating Characteristics**

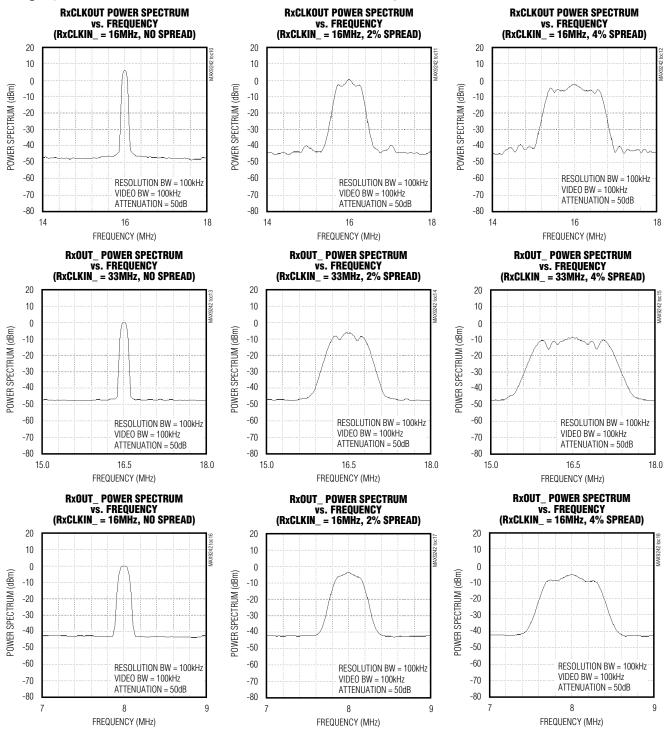
 $(V_{CC} = PLLV_{CC} = LVDSV_{CC} = V_{CCO} = +3.3V, C_L = 8pF, \overline{PWRDWN} = high, differential input voltage |V_{ID}| = 0.2V, input common-mode voltage |V_{CM}| = 1.2V, T_A = +25°C, MAX9244/MAX9254, unless otherwise noted.)$ 



### Typical Operating Characteristics (continued)

/U/IXI/U

 $(V_{CC} = PLLV_{CC} = LVDSV_{CC} = V_{CCO} = +3.3V, C_L = 8pF, \overline{PWRDWN} = high, differential input voltage <math>|V_{ID}| = 0.2V$ , input common-mode voltage  $V_{CM} = 1.2V, T_A = +25$ °C, MAX9244/MAX9254, unless otherwise noted.)



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## **Pin Description**

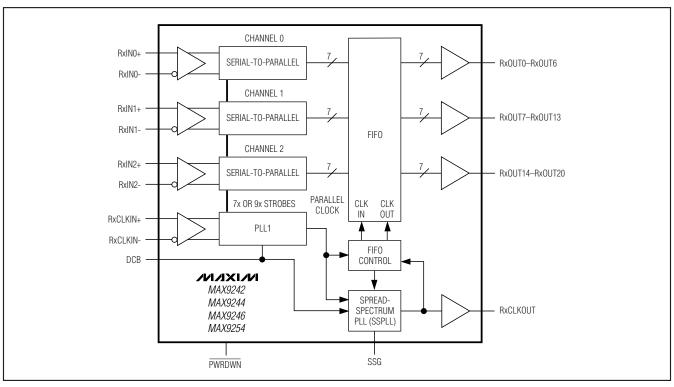
PIN	NAME	FUNCTION						
1	RxOUT17	i enamen						
2	RxOUT18	Channel 2 Single-Ended Outputs						
3, 25, 32, 38, 44	GND	ound						
4	RxOUT19	Observation Circula Foods of Outstands						
5	RxOUT20	Channel 2 Single-Ended Outputs						
6	SSG	Three-Level-Logic, Spread-Spectrum Generator Control Input. SSG selects the frequency spread of RxCLKOUT relative to RxCLKIN_ (see Table 3).						
7	DCB	Three-Level-Logic, DC-Balance Control Input. DCB selects DC-balanced, non-DC-balanced, or reserved operation (see Table 1).						
8	RxIN0-	Inverting Channel 0 LVDS Serial-Data Input						
9	RxIN0+	Noninverting Channel 0 LVDS Serial-Data Input						
10	RxIN1-	Inverting Channel 1 LVDS Serial-Data Input						
11	RxIN1+	Noninverting Channel 1 LVDS Serial-Data Input						
12	LVDSV <sub>CC</sub>	LVDS Supply Voltage. Bypass LVDSV <sub>CC</sub> to GND with 0.1µF and 0.001µF capacitors in parallel as close to the pin as possible.						
13, 18	LVDSGND	LVDS Ground						
14	RxIN2-	Inverting Channel 2 LVDS Serial-Data Input						
15	RxIN2+	Noninverting Channel 2 LVDS Serial-Data Input						
16	RxCLKIN-	Inverting LVDS Parallel-Rate Clock Input						
17	RxCLKIN+	Noninverting LVDS Parallel-Rate Clock Input						
19, 21	PLLGND	PLL Ground						
20	PLLV <sub>CC</sub>	PLL Supply Voltage. Bypass PLLV <sub>CC</sub> to GND with 0.1µF and 0.001µF capacitors in parallel as close to the pin as possible.						
22	PWRDWN	5V-Tolerant LVTTL/LVCMOS Power-Down Input. PWRDWN is internally pulled down to GND. Outputs are high impedance when PWRDWN = low or open.						
23	RxCLKOUT	Parallel-Rate Clock Single-Ended Output. The MAX9242 has a rising-edge strobe. The MAX9244/MAX9246/MAX9254 have a falling-edge strobe.						
24	RxOUT0							
26	RxOUT1	Channel 0 Single-Ended Outputs						
27	RxOUT2							
28, 36, 48	Vcco	Output Supply Voltage. Bypass each V <sub>CCO</sub> to GND with 0.1µF and 0.001µF capacitors in parallel as close to the pin as possible.						
29	RxOUT3							
30	RxOUT4	Observation Circula Faula d Outrotta						
31	RxOUT5	Channel 0 Single-Ended Outputs						
33	RxOUT6							



## Pin Description (continued)

PIN	NAME	FUNCTION
34	RxOUT7	
35	RxOUT8	
37	RxOUT9	Channel 1 Single-Ended Outputs
39	RxOUT10	Chamer i Single-Ended Outputs
40	RxOUT11	
41	RxOUT12	
42	V <sub>CC</sub>	Digital Supply Voltage. Bypass V <sub>CC</sub> to GND with 0.1µF and 0.001µF capacitors in parallel as close to the pin as possible.
43	RxOUT13	Channel 1 Single-Ended Output
45	RxOUT14	
46	RxOUT15	Channel 2 Single-Ended Outputs
47	RxOUT16	

## Functional Diagram



### **Detailed Description**

The MAX9242/MAX9244/MAX9246/MAX9254 deserialize three LVDS serial-data inputs into 21 single-ended LVC-MOS/LVTTL outputs. The outputs are programmable for no spread or for a spread of ±2% or ±4%, relative to the LVDS input clock frequency. The MAX9242/MAX9244/MAX9254 operate at a parallel clock frequency of 16MHz to 34MHz in DC-balanced mode and 20MHz to 40MHz in non-DC-balanced mode. The MAX9246 operates at a 6MHz-to-18MHz parallel clock frequency in DC-balanced mode and 8MHz-to-20MHz parallel clock frequency in non-DC-balanced operation is controlled by the DCB input. The MAX9246/MAX9254 have a falling-edge strobe.

#### **DC Balance (DCB)**

DC-balanced or non-DC-balanced operation is controlled by the DCB input (see Table 1). In the non-DC-balanced mode, each channel deserializes 7 bits every cycle of the parallel clock. In DC-balanced mode, 9 bits are deserialized every clock cycle (7 data bits + 2 DC-balanced bits). The highest serial-data rate on each channel in DC-balanced mode is  $34MHz \times 9 = 306Mbps$ . In non-DC-balanced mode, the maximum data rate is  $40MHz \times 7 = 280Mbps$ .

**Table 1. DCB Function** 

DCB INPUT LEVEL	FUNCTION
High	Non-DC-balanced mode
Mid	Reserved
Low	DC-balanced mode

Data coding by the MAX9209/MAX9213 serializers (that are companion devices to the MAX9242/MAX9244/MAX9246/MAX9254 deserializers) limits the imbalance of ones and zeros transmitted on each channel. If +1 is assigned to each binary 1 transmitted and -1 is assigned to each binary 0 transmitted, the variation in the running sum of assigned values is called the digital sum variation (DSV). The maximum DSV for the data channels is 10. At most, 10 more zeros than ones, or 10 more ones than zeros, are ever transmitted. The maximum DSV for the clock channel is 5. Limiting the DSV and choosing the correct coupling capacitors maintain differential signal amplitude and reduces jitter due to droop on AC-coupled links.

To obtain DC balance on the data channels, the serializer parallel data is inverted or not inverted, depending on the sign of the digital sum at the word boundary. Two complementary bits are appended to each group of 7 parallel-input data bits to indicate to the MAX9242/MAX9244/MAX9246/MAX9254 deserializer whether the data bits are inverted (see Figures 11 and 12). The deserializer restores the original state of the parallel data. The LVDS clock signal alternates duty cycles of 4/9 and 5/9 to maintain DC balance.

#### Spread-Spectrum Generator (SSG)

The MAX9242/MAX9244/MAX9246/MAX9254 single-ended data and clock outputs are programmable for a variation of ±2% or ±4% around the LVDS input clock frequency. The modulation rate of the frequency variation is 32.48kHz for a 33MHz LVDS clock input and scales linearly with the input clock frequency (see Table 2). The spread spectrum can also be turned off. The output spread is controlled through the SSG input (see Table 3).

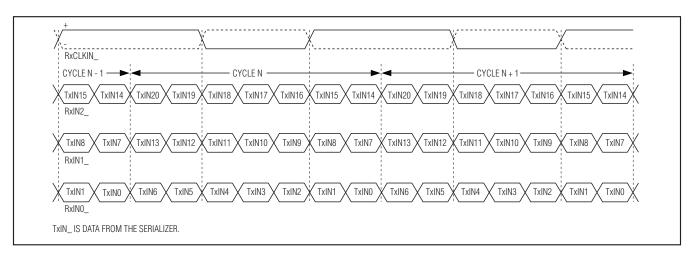


Figure 11. Deserializer Serial Input in Non-DC-Balanced Mode

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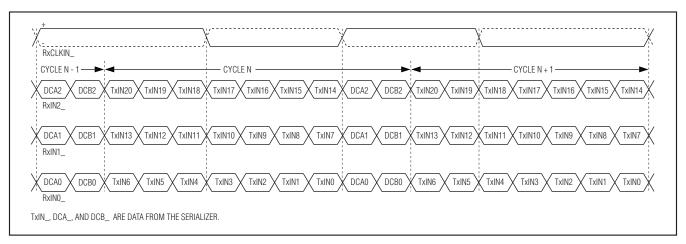


Figure 12. Deserializer Serial Input in DC-Balanced Mode

**Table 2. Modulation Rate** 

f <sub>RxCLKIN_</sub> (MHz)	f <sub>M</sub> (kHz) = f <sub>RxCLKIN</sub> _ / 1016	
6	5.91	
8	7.87	
10	9.84	
16	15.75	
18	17.72	
20	19.68	
33	32.48	
34	33.46	
40	39.37	

Table 3. SSG Function

SSG INPUT LEVEL	FUNCTION
High	RxCLKOUT frequency spread ±4% relative to RxCLKIN_
Mid	RxCLKOUT frequency spread ±2% relative to RxCLKIN_
Low	No spread on RxCLKOUT relative to RxCLKIN_

**Note:** RxOUT\_ data outputs are spread because RxCLKOUT strobes the output of the FIFO.

To select the mid level, leave the input open, or if driven, put the driver output in high impedance. The driver high-impedance leakage current must be less than  $\pm 10\mu A$ .

Any spread change causes a maximum delay time of  $32,800 \times RCIP$  before output data is valid. When the spread amount is changed from  $\pm 2\%$  to  $\pm 4\%$  or viceversa, the data outputs go low for one delay time (see Figure 13). Similarly, when the spread is changed from no spread to  $\pm 2\%$  or  $\pm 4\%$ , the data outputs go low for one delay time (see Figure 14). The data outputs continue to switch but are not valid when the spread amount is changed from  $\pm 2\%$  or  $\pm 4\%$  to no spread (see Figure 15). The spread-spectrum function is also available when the MAX9242/MAX9244/MAX9246/MAX9254 operate in non-DC-balanced mode.

#### **Hot Swap**

When the MAX9242/MAX9244/MAX9246/MAX9254 are connected to an active serializer, they synchronize correctly. The PLL control voltage does not saturate in response to high-frequency glitches that may occur during a hot swap. The PWRDWN input on the MAX9242/MAX9244/MAX9246/MAX9254 does not need to be cycled when these devices are connected to an active serializer.

#### **PLL Lock Time**

The MAX9242/MAX9244/MAX9246/MAX9254 use two PLLs. The first PLL (PLL1) generates a 7x clock (non-DC-balanced mode) or a 9x clock (DC-balanced mode) from RxCLKIN\_ for deserializing the LVDS inputs. The second PLL (SSPLL) is used for spread-spectrum modulation. During initial power-up, the PLL1 locks, and SSPLL locks immediately after. The PLL lock times are set by an internal counter. The maximum time to lock for each PLL is 32,800 clock periods. Power and clock should be stable to meet the lock time specification. After initialization, if the first PLL loses lock, it locks again and then the

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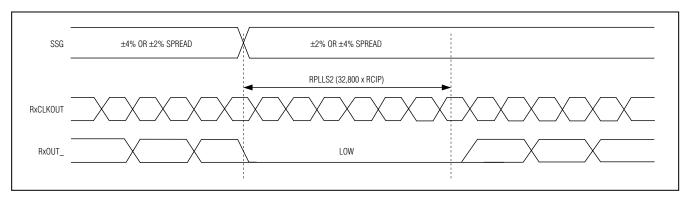


Figure 13. Output Waveforms when Spread Amount is Changed

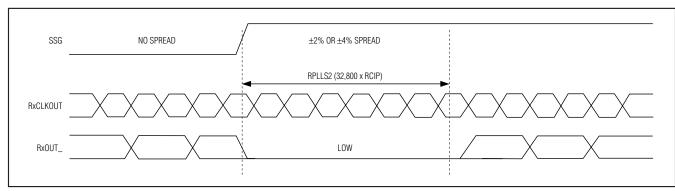


Figure 14. Output Waveforms when Spread is Added

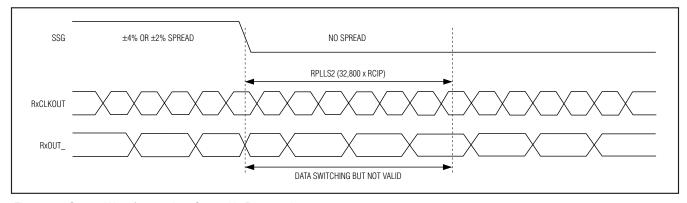


Figure 15. Output Waveforms when Spread is Removed

spread-spectrum PLL locks immediately after (see Figure 16). If the spread-spectrum PLL loses lock, it locks again with only one PLL lock delay (see Figure 17).

#### **AC-Coupling Benefits**

Bit errors experienced with DC-coupling (Figure 18) can be eliminated by increasing the receiver common-mode voltage range through AC-coupling. AC-coupling

increases the common-mode voltage range of an LVDS receiver to nearly the voltage rating of the capacitor. The typical LVDS driver output is 350mV centered on a 1.25V offset voltage, making single-ended output voltages of 1.425V and 1.075V. An LVDS receiver accepts signals from 0V to 2.4V, allowing approximately ±1V common-mode difference between the driver and receiver on a

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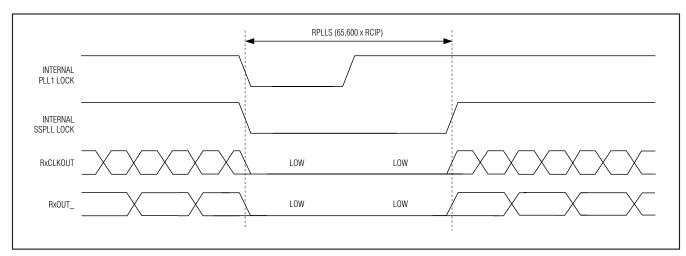


Figure 16. Output Waveforms when PLL1 Loses Lock and Locks Again

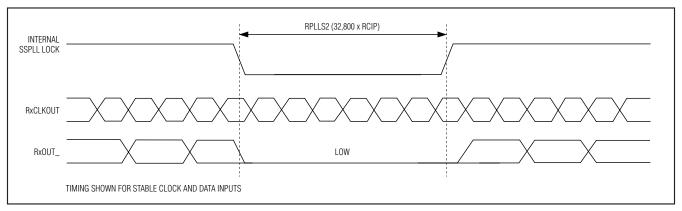


Figure 17. Output Waveforms if Spread-Spectrum PLL Loses Lock and Locks Again

DC-coupled link (2.4V - 1.425V = 0.975V) and 1.075V -0V = 1.075V). Common-mode voltage differences may be due to ground potential variation or common-mode noise. If there is more than ±1V of difference, the receiver is not guaranteed to read the input signal correctly and may cause bit errors. AC-coupling filters low-frequency ground shifts and common-mode noise and passes high-frequency data. A common-mode voltage difference up to the voltage rating of the coupling capacitor (minus half the differential swing) is tolerated. DC-balanced coding of the data is required to maintain the differential signal amplitude and limit jitter on an AC-coupled link. A capacitor in series with each output of the LVDS driver is sufficient for AC-coupling. However. two capacitors—one at the serializer output and one at the deserializer input—provide protection in case either end of the cable is shorted to a high voltage.

## Applications Information

### **Selection of AC-Coupling Capacitors**

Voltage droop and the DSV of transmitted symbols cause signal transitions to start from different voltage levels. Because the transition time is finite, starting the signal transition from different voltage levels causes timing jitter. The time constant for an AC-coupled link needs to be chosen to reduce droop and jitter to an acceptable level.

The RC network for an AC-coupled link consists of the LVDS receiver termination resistor (R<sub>T</sub>), the LVDS driver output resistor (R<sub>O</sub>), and the series AC-coupling capacitors (C). The RC time constant for two equal-value series capacitors is (C x (R<sub>T</sub> + R<sub>O</sub>)) / 2 (Figure 19). The RC time constant for four equal-value series capacitors is (C x (R<sub>T</sub> + R<sub>O</sub>)) / 4 (Figure 20).

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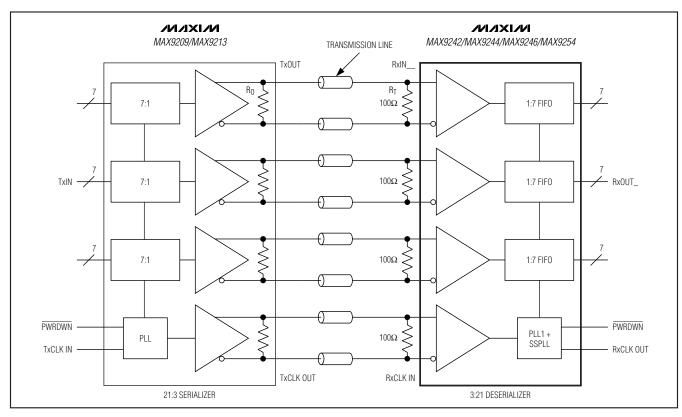


Figure 18. DC-Coupled Link, Non-DC-Balanced Mode

RT is required to match the transmission line impedance (usually 100 $\Omega$ ) and RO is determined by the LVDS driver design (the minimum differential output resistance of 78 $\Omega$  for the MAX9209/MAX9213 serializers is used in the following example). This condition leaves the capacitor selection to change the system time constant.

In the following example, the capacitor value for a 2% droop is calculated. Jitter due to this droop is then calculated assuming a 1ns transition time:

$$C = -(2 \times t_B \times DSV) / (ln (1 - D) \times (R_T + R_O)) (Eq 1)$$

where:

C = AC-coupling capacitor (F)

 $t_B = bit time (s)$ 

DSV = digital sum variation (integer)

In = natural log

D = droop (% of signal amplitude)

 $R_T$  = termination resistor ( $\Omega$ )

 $R_O$  = output resistance ( $\Omega$ )

Equation 1 is for two series capacitors (Figure 19). The bit time (t<sub>B</sub>) is the period of the parallel clock divided by 9.

The DSV is 10. See equation 3 for four series capacitors (Figure 20).

The capacitor for 2% maximum droop at 16MHz parallel rate clock is:

 $C = -(2 \times t_B \times DSV) / (In (1 - D) \times (R_T + R_O))$ 

 $C = -(2 \times 6.95 \text{ns} \times 10) / (\ln (1 - 0.02) \times (100\Omega + 78\Omega))$ 

 $C = 0.038 \mu F$ 

Jitter due to droop is proportional to the droop and transition time:

$$t_J = t_T \times D (Eq 2)$$

where:

 $t_{J} = jitter(s)$ 

 $t_T$  = transition time (s) (0 to 100%)

D = droop (% of signal amplitude)

Jitter due to 2% droop and assumed 1ns transition time is:

$$t_J = 1 \text{ns} \times 0.02$$

$$t_{\rm J} = 20 ps$$

The transition time in a real system depends on the frequency response of the cable driven by the serializer.

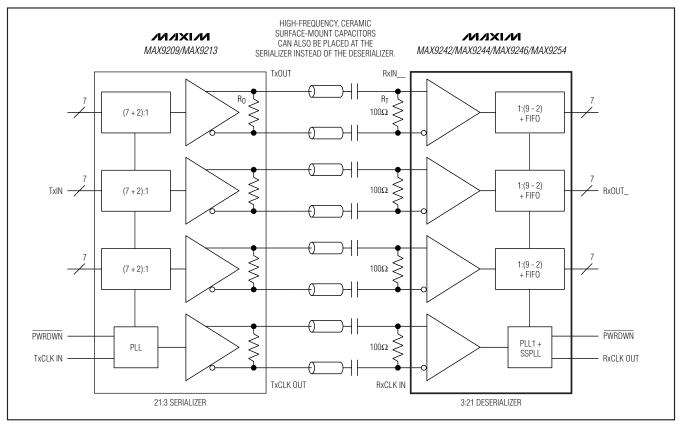


Figure 19. Two Capacitors per Link, AC-Coupled, DC-Balanced Mode

The capacitor value decreases for a higher frequency parallel clock and for higher levels of droop and jitter. Use high-frequency, surface-mount ceramic capacitors. Equation 1 altered for four series capacitors (Figure 20) is:

$$C = -(4 \times t_B \times DSV) / (ln (1 - D) \times (R_T + R_O)) (Eq 3)$$

#### Fail-Safe

The MAX9242/MAX9244/MAX9246/MAX9254 have fail-safe LVDS inputs in non-DC-balanced mode (Figure 1). Fail-safe drives the outputs low when the corresponding LVDS input is open, undriven and shorted, or undriven and parallel terminated. The fail-safe on the LVDS clock input drives all outputs low when power is stable. Fail-safe does not operate in DC-balanced mode.

#### **Input Bias and Frequency Detection**

In DC-balanced mode, the inverting and noninverting LVDS inputs are internally connected to +1.2V through  $42k\Omega$  (min) to provide biasing for AC-coupling (Figure 1). To prevent switching due to noise when the clock input is not driven, bias the clock inputs (RxCLKIN+,

RxCLKIN-) to differential +15mV by connecting a 10k $\Omega$  ±1% pullup resistor between the noninverting input and LVDSVCC, and a 10k $\Omega$  ±1% pulldown resistor between the inverting input and ground. These bias resistors, along with the 100 $\Omega$  ±1% tolerant termination resistor, provide +15mV of differential input. The +15mV bias causes some small degradation of RSKM proportional to the slew rate of the clock input. For example, if the clock transitions 250mV in 500ps, the slew rate of 0.5mV/ps reduces RSKM by 30ps.

#### **Unused LVDS Data Inputs**

In non-DC-balanced mode, leave unused LVDS data inputs open. In non-DC-balanced mode, the input failsafe circuit drives the corresponding outputs low, and no pullup or pulldown resistors are needed. In DC-balanced mode, at each unused LVDS data input, pull the inverting input up to LVDSVCC using a  $10k\Omega$  resistor, and pull the noninverting input down to ground using a  $10k\Omega$  resistor. Do not connect a termination resistor. The pullup and pulldown resistors drive the corresponding outputs low and prevent switching due to noise.

18 \_\_\_\_\_\_\_ /V|/X|/V|

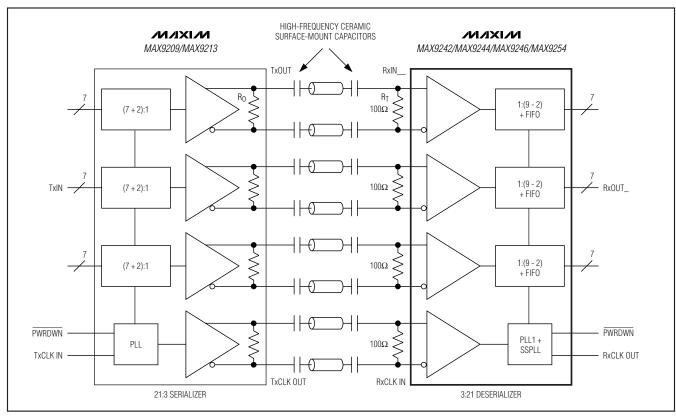


Figure 20. Four Capacitors per Link, AC-Coupled, DC-Balanced Mode

#### **Link Power-Up Sequence**

The recommended link power-up sequence is to power up the serializer, wait until the serializer PLL locks, and then power up the deserializer. This sequence prevents the deserializer from seeing an undriven or unstable input when powering up.

#### **PWRDWN**

Driving PWRDWN low puts the outputs in high impedance, stops the PLL, and reduces supply current to 50µA or less. Driving PWRDWN high drives the outputs low until the PLL locks. The outputs of two deserializers can be bused to form a 2:1 mux with the outputs controlled by PWRDWN. Wait 100ns between disabling one deserializer (driving PWRDWN low) and enabling the second one (driving PWRDWN high) to avoid contention of the bused outputs.

#### **Power-Supply Bypassing**

There are separate on-chip power domains for digital circuits, outputs, PLL, and LVDS inputs. Bypass each VCC, VCCO, PLLVCC, and LVDSVCC with high-frequency,

surface-mount ceramic 0.1µF and 0.001µF capacitors in parallel as close to the device as possible, with the smallest value capacitor closest to the supply pin.

#### **Cables and Connectors**

Interconnect for LVDS typically has a differential impedance of  $100\Omega$ . Use cables and connectors that have matched differential impedance to minimize impedance discontinuities.

Twisted-pair and shielded twisted-pair cables offer superior signal quality compared to ribbon cable and tend to generate less EMI due to magnetic field canceling effects. Balanced cables pick up noise as common mode, which is rejected by the LVDS receiver.

#### **Board Layout**

Keep the LVTTL/LVCMOS outputs and LVDS input signals separated to prevent crosstalk. A four-layer PC board with separate layers for power, ground, LVDS inputs, and digital signals is recommended. Layout PC board traces for  $100\Omega$  differential characteristic impedance. The trace dimensions depend on the type of

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trace used (microstrip or stripline). Note that two  $50\Omega$  PC board traces do not have  $100\Omega$  differential impedance when brought close together—the impedance goes down when the traces are brought closer.

Route the PC board traces for an LVDS channel (there are two conductors per LVDS channel) in parallel to maintain the differential characteristic impedance. Place the termination resistor at the end of the PC board traces within a 1/4 inch of the LVDS receiver input. Avoid vias. If vias must be used, use only one pair per LVDS channel and place the via for each line at the same point along the length of the PC board traces. This way, any reflections will occur at the same time. Do not make vias into test points for ATE. Make LVDS clock and data pairs the same length on the PC board to avoid pair-to-pair skew. Make the PC board traces that make up a differential pair the same length to avoid skew within the differential pair.

#### **5V-Tolerant Input**

PWRDWN is 5V tolerant and is internally pulled down to GND. SSG and DCB are not 5V tolerant. The input voltage range for SSG and DCB is nominally ground to VCC.

#### Skew Margin (RSKM)

Skew margin (RSKM) is the time allowed for degradation of the serial-data sampling setup and hold times by sources other than the deserializer. The deserializer sampling uncertainty is accounted for and does not need to be subtracted from RSKM. The main outside contributors of jitter and skew that subtract from RSKM are interconnect intersymbol interference, serializer pulse position uncertainty, and pair-to-pair path skew.

#### **Vcco Output Supply and Power Dissipation**

The outputs have a separate supply (VCCO) for interfacing to systems with 1.8V to 5V nominal input logic levels. The *DC Electrical Characteristics* table gives the maximum supply current for VCCO = 3.6V with 8pF load at several switching frequencies with all outputs switching in the worst-case switching pattern. The approximate incremental supply current for VCCO other than 3.6V with the same 8pF load and worst-case pattern can be calculated using:

$$I_I = C_T V_I 0.5 f_C \times 21$$
 (data outputs)  
+  $C_T V_I f_C \times 1$  (clock output)

where:

I<sub>I</sub> = incremental supply current

 $\text{C}_{\text{T}} = \text{total internal (C}_{\text{INT}})$  and external (CL) load capacitance

 $V_I$  = incremental supply voltage

f<sub>C</sub> = output clock switching frequency

The incremental current is added to (for  $V_{CCO} > 3.6V$ ) or subtracted from (for  $V_{CCO} < 3.6V$ ) the *DC Electrical Characteristics* table maximum supply current. The internal output buffer capacitance is  $C_{INT} = 6pF$ . The worst-case pattern switching frequency of the data outputs is half the switching frequency of the output clock.

In the following example, the incremental supply current of the MAX9244 in spread and DC-balanced mode is calculated for  $V_{CCO} = 5.5V$ ,  $f_{C} = 34MHz$ , and  $C_{L} = 8pF$ :

$$V_I = 5.5V - 3.6V = 1.9V$$
  
 $C_T = C_{INT} + C_L = 6pF + 8pF = 14pF$ 

where:

 $I_I = C_TV_I0.5f_C \times 21$  (data outputs) +  $C_TV_If_C \times 1$  (clock output)

 $I_I = (14pF \times 1.9V \times 0.5 \times 34MHz \times 21) + (14pF \times 1.9V \times 34MHz)$ 

 $I_1 = 9.5 \text{mA} + 0.9 \text{mA} = 10.4 \text{mA}.$ 

The maximum supply current in DC-balanced mode for  $V_{CC} = V_{CCO} = 3.6V$  at  $f_{C} = 34MHz$  is 125mA (from the DC Electrical Characteristics table). Add 10.4mA to get the total approximate maximum supply current at  $V_{CCO} = 5.5V$  and  $V_{CC} = 3.6V$ .

If the output supply voltage is less than  $V_{\rm CCO}=3.6V$ , the reduced supply current can be calculated using the same formula and method.

At high switching frequency, high supply voltage, and high capacitive loading, power dissipation can exceed the package power dissipation rating. Do not exceed the maximum package power dissipation rating. See the *Absolute Maximum Ratings* for maximum package power dissipation capacity and temperature derating.

#### Rising- or Falling-Edge Output Strobe

The MAX9242 has a rising-edge output strobe, which latches the parallel output data into the next chip on the rising edge of RxCLKOUT. The MAX9244/MAX9246/MAX9254 have a falling-edge output strobe, which latches the parallel output data into the next chip on the falling edge of RxCLKOUT. The deserializer output strobe polarity does not need to match the serializer input strobe polarity.

#### **Three-Level Logic Inputs**

SSG and DCB (DCB mid level is reserved) are three-level-logic inputs. A logic-high input voltage must be greater than +2.5V and a logic-low input voltage must be less than +0.8V. A mid-level logic is recognized by the MAX9242/MAX9244/MAX9246/MAX9254 when the input is left open or connected to a driver in a high-impedance state. A weak inverter on the input stage of

SSG and DCB provides the proper mid-level voltage under conditions of low input current. The mid-level input current must not be greater than ±10µA, and the mid-level logic state cannot be driven with an external voltage source.

#### IEC 61000-4-2 Level 4 and ISO 10605 ESD Protection

The MAX9242/MAX9244/MAX9246/MAX9254 ESD tolerance is rated for Human Body Model, IEC 61000-4-2 and ISO 10605. The ISO 10605 and IEC 61000-4-2 standards specify ESD tolerance for electronic systems. All LVDS inputs on the MAX9242/MAX9244/MAX9246/MAX9254 meet ISO 10605 ESD protection at  $\pm 30 \text{kV}$  Air-Gap Discharge and  $\pm 6 \text{kV}$  Contact Discharge and IEC 61000-4-2 ESD protection at  $\pm 15 \text{kV}$  Air-Gap Discharge and  $\pm 8 \text{kV}$  Contact Discharge. All other pins meet the Human Body Model ESD tolerance of  $\pm 2.5 \text{kV}$ . The Human Body Model discharge components are Cs = 100pF and RD = 1.5k $\Omega$  (Figure 21). The IEC 61000-4-2 discharge components are Cs = 150pF and RD =  $330\Omega$  (see Figure 22). The ISO 10605 discharge components are Cs = 330pF and RD = 2k $\Omega$  (Figure 23).

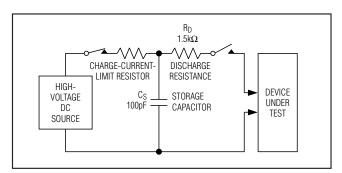


Figure 21. Human Body ESD Test Circuit

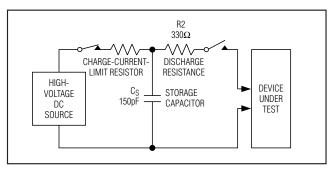


Figure 22. IEC 61000-4-2 Contact Discharge ESD Test Circuit

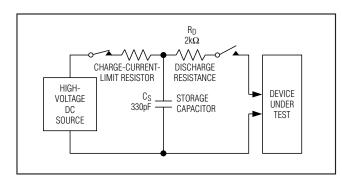
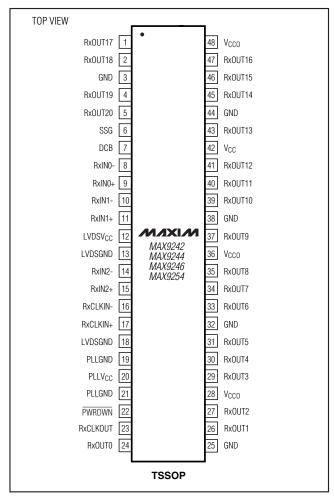


Figure 23. ISO 10605 Contact Discharge ESD Test Circuit

## Pin Configuration



Chip Information

PROCESS: CMOS

MIXIM

### Ordering Information (continued)

PART	TEMP RANGE	PIN-PACKAGE	
MAX9246EUM	-40°C to +85°C	48 TSSOP	
MAX9246EUM/V+	-40°C to +85°C	48 TSSOP	
MAX9246GUM	-40°C to +105°C	48 TSSOP	
MAX9246GUM/V+	-40°C to +105°C	48 TSSOP	
MAX9254EUM	-40°C to +85°C	48 TSSOP	
MAX9254EUM/V+	-40°C to +85°C	48 TSSOP	

<sup>+</sup>Denotes a lead(Pb)-free/RoHS-compliant package. /V denotes an automotive qualified part.

**Note:** All devices are available in lead(Pb)-free/RoHS-compliant packaging. Specify lead(Pb)-free/RoHS compliant by adding a + symbol at the end of the part number when ordering.

#### \_Package Information

For the latest package outline information and land patterns, go to <a href="www.maxim-ic.com/packages">www.maxim-ic.com/packages</a>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	DOCUMENT NO.	
48 TSSOP	U48-1	<u>21-0155</u>	

### **Revision History**

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
3	2/09	Supply currents measured before the deserializers were fully locked to incoming serial data. <i>DC Electrical Characteristic</i> s updated	2, 3
4	7/09	Added automotive qualified parts to Ordering Information table	1

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Maxim Integrated Products, 120 San Gabriel Drive, Sunnyvale, CA 94086 408-737-7600

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