19-3488; Rev 2; 1/07



# 

## Multichannel, True-Differential, Serial, 14-Bit ADCs

## **General Description**

The MAX1146–MAX1149 low-power, 14-bit, multichannel, analog-to-digital converters (ADCs) feature an internal track/hold (T/H), voltage reference, and clock. The MAX1146/MAX1148 operate from a single +4.75V to +5.25V supply, and the MAX1147/MAX1149 operate from a single +2.7V to +3.6V supply. All analog inputs are software configurable for unipolar/bipolar and single-ended/differential operation.

The 4-wire serial interface connects directly to SPI™/QSPI™/MICROWIRE™ devices without external logic. The serial strobe output (SSTRB) allows convenient connection to digital signal processors. The MAX1146–MAX1149 use an internal clock or an external serial-interface clock to perform successive-approximation analog-to-digital conversions.

The MAX1146/MAX1148 include an internal +4.096V reference, while the MAX1147/MAX1149 include an internal +2.500V reference. All devices accept an external reference from 1.5V to V<sub>DD</sub>.

The MAX1146–MAX1149 provide a hardware shutdown and two software power-down modes. Using the software power-down modes allows the devices to be powered down between conversions. When powered down, accessing the serial interface automatically powers up the devices. The quick turn-on time allows power-down between all conversions. This technique reduces supply current to under 120µA for quick turn-on.

The MAX1146-MAX1149 are available in a 20-pin TSSOP package.

## **Applications**

- \_Features
- 8-Channel Single-Ended or 4-Channel Differential Inputs (MAX1148/MAX1149)
- 4-Channel Single-Ended or 2-Channel Differential Inputs (MAX1146/MAX1147)
- Internal Multiplexer and T/H
- Single-Supply Operation
   4.75V to 5.25V Supply (MAX1146/MAX1148)
   2.7V to 3.6V Supply (MAX1147/MAX1149)
- Internal Reference
   +4.096V (MAX1146/MAX1148)
   +2.500V (MAX1147/MAX1149)
- 116ksps Sampling Rate
- Low Power
  - 1.1mA (116ksps) 120μΑ (10ksps) 12μΑ (1ksps) 300nA (Power-Down Mode)
- ♦ SPI-/QSPI-/MICROWIRE Compatible
- 20-Pin TSSOP

- Portable Data Logging Data Acquisition Medical Instruments Battery-Powered Instruments
- Process Control

#### Pin Configurations appear at end of data sheet.

SPI/QSPI are trademarks of Motorola, Inc. MICROWIRE is a trademark of National Semiconductor Corp.

## **Ordering Information/Selector Guide**

PART	TEMP RANGE	PIN- PACKAGE	INL (LSB)	INPUT CHANNELS	INTERNAL REFERENCE (V)	PKG CODE
MAX1146BCUP	0°C to +70°C	20 TSSOP	±2	4	+4.096	U20-3
MAX1146BEUP	-40°C to +85°C	20 TSSOP	±2	4	+4.096	U20-3
MAX1147BCUP	0°C to +70°C	20 TSSOP	±2	4	+2.500	U20-3
MAX1147BEUP	-40°C to +85°C	20 TSSOP	±2	4	+2.500	U20-3
MAX1148BCUP	0°C to +70°C	20 TSSOP	±2	8	+4.096	U20-3
MAX1148BEUP	-40°C to +85°C	20 TSSOP	±2	8	+4.096	U20-3
MAX1149BCUP	0°C to +70°C	20 TSSOP	±2	8	+2.500	U20-3
MAX1149BEUP	-40°C to +85°C	20 TSSOP	±2	8	+2.500	U20-3

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Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

## **ABSOLUTE MAXIMUM RATINGS**

V <sub>DD</sub> to AGND, DGND	Continuous Power Dissipation (T <sub>A</sub> = +70°C) 20 TSSOP (derate 10.9mW/°C above +70°C)879mW Operating Temperature Ranges
REF, REFADJ to AGND0.3V to $(V_{DD} + 0.3V)$ Digital Inputs to DGND0.3V to $(V_{DD} + 0.3V)$ Digital Outputs to DGND0.3V to $(V_{DD} + 0.3V)$	MAX114_BC0°C to +70°C MAX114_BE40°C to +85°C Storage Temperature Range60°C to +150°C
Digital Output Sink Current	Lead Temperature (soldering, 10s)+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## **ELECTRICAL CHARACTERISTICS**

(VDD = 5V (MAX1146/MAX1148), VDD = 3.3V (MAX1147/MAX1149),  $\overline{SHDN} = V_{DD}$ ,  $V_{COM} = 0$ ,  $f_{SCLK} = 2.1$ MHz, external clock (50% duty cycle), 18 clocks/conversion (116ksps),  $V_{REFADJ} = V_{DD}$ ,  $C_{REF} = 2.2\mu$ F, external +4.096V reference at REF (MAX1146/MAX1148), external 2.500V reference at REF (MAX1147/MAX1149),  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}$ C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS
DC ACCURACY (Note 1)	1	1				1
Resolution			14			Bits
Relative Accuracy (Note 2)	INL			±0.7	±2	LSB
Differential Nonlinearity	DNL	No missing codes over temperature	-1.0	±0.5	+1.5	LSB
Offset Error					±10	LSB
Offset Temperature Coefficient				0.3		ppm/°C
Gain Error		(Note 3)			±20	LSB
Gain Temperature Coefficient				±0.8		ppm/°C
Channel-to-Channel Offset Matching				±1		LSB
Channel-to-Channel Gain Matching				±1		LSB
DYNAMIC SPECIFICATIONS (1)	Hz sine-wav	e input, 2.5VP-P, full-scale analog input, 11	6ksps, 2.1	MHz exte	rnal cloc	k)
Signal-to-Noise Plus Distortion Ratio	SINAD		77	81		dB
Total Harmonic Distortion	THD	Up to the 5th harmonic		-96	-88	dB
Spurious-Free Dynamic Range	SFDR		84	98		dB
Channel-to-Channel Crosstalk		(Note 4)		-85		dB
Small-Signal Bandwidth	SSBW	-3dB point		3.0		MHz
Full-Power Bandwidth	FPBW	SINAD > 68dB		2.0		MHz
CONVERSION RATE						
Conversion Time (Neta 5)	toonur	External clock, 2.1MHz 15 SCLK cycles	7.2			
Conversion Time (Note 5)	tCONV	Internal clock	6		8	μs

## **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = 5V (MAX1146/MAX1148), V_{DD} = 3.3V (MAX1147/MAX1149), SHDN = V_{DD}, V_{COM} = 0, f_{SCLK} = 2.1MHz, external clock (50% duty cycle), 18 clocks/conversion (116ksps), V_{REFADJ} = V_{DD}, C_{REF} = 2.2\mu$ F, external +4.096V reference at REF (MAX1146/MAX1148), external 2.500V reference at REF (MAX1147/MAX1149), T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.)

PARAMETER	PARAMETER SYMBOL CONDITIONS			MIN	ТҮР	МАХ	UNITS
		Internal clock mode,	18 clocks/conversion			60.3	
	6	fSCLK = 2.1MHz	24 clocks/conversion			51.5	1
Throughput Rate	fSAMPLE	External clock mode,	18 clocks/conversion			116.66	ksps
		fSCLK = 2.1MHz	24 clocks/conversion			87.50	1
T/H Acquisition Time	tACQ			1.4			μs
Aperture Delay	tad				20		ns
Aperture Jitter	tAJ				<50		ps
	600114	External clock mode		0.1		2.1	
Serial Clock Frequency	fSCLK	Internal clock mode		0		2.1	MHz
Internal Clock Frequency					2.1		MHz
ANALOG INPUTS (CH0-CH7, C	OM)	·					
Input Voltage Range, Single-		Unipolar, COM = 0	0		VREF	V	
Ended and Differential (Note 6)		Bipolar, COM = VRE		±	VREF/2	V	
Multiplexer Leakage Current		On/off-leakage curre		±0.01	±1	μA	
Input Capacitance					18		pF
INTERNAL REFERENCE (CREF =	2.2µF, C <sub>REF</sub>	ADJ = 0.01μF)					
	MAX1147/MAX1149, T <sub>A</sub> = +25°C		2.480	2.500	2.520	V	
REF Output Voltage	VREF	MAX1146/MAX1148,	4.076	4.096	4.116	V	
REF Short-Circuit Current	IREFSC	REF = DGND				20	mA
		MAX114_BC			±30	±50	
V <sub>REF</sub> Tempco (Note 7)		MAX114_BE			±40	±60	ppm/°C
Load Regulation		0 to 0.2mA output load	d (Note 8)		2.0		mV
Capacitive Bypass at REF				2			μF
Capacitive Bypass at REFADJ				0.01			μF
REFADJ Output Voltage					1.250		V
REFADJ Input Range					±18		mV
		Pull REFADJ high to d	V <sub>DD</sub> -			N	
REFADJ Logic High bandgap reference and			0.25V			V	
		MAX1147/MAX1149		2.000		11/1	
Reference Buffer Voltage Gain		MAX1146/MAX1148			3.277		V/V

## **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = 5V (MAX1146/MAX1148), V_{DD} = 3.3V (MAX1147/MAX1149), \overline{SHDN} = V_{DD}, V_{COM} = 0, f_{SCLK} = 2.1MHz, external clock (50% duty cycle), 18 clocks/conversion (116ksps), V_{REFADJ} = V_{DD}, C_{REF} = 2.2\mu$ F, external +4.096V reference at REF (MAX1146/MAX1148), external 2.500V reference at REF (MAX1147/MAX1149), T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.)

PARAMETER	SYMBOL	С		MIN	TYP	MAX	UNITS	
EXTERNAL REFERENCE AT R	EF	•			•			
REF Input Voltage Range	VREF				1.5		V <sub>DD</sub> + 50mV	V
	lass					125	450	
REF Input Current	IREF	Shutdown		0.01	10	μA		
REF Input Resistance					6	8		kΩ
DIGITAL INPUTS (DIN, SCLK, C	S, SHDN)							
Input High Voltage	VIH	$V_{DD} < 3.6V$			2.0			V
input high voltage	VIH	$V_{DD} > 3.6V$		3.0			v	
Input Low Voltage	VIL						0.8	V
Input Hysteresis	V <sub>HYST</sub>					0.2		V
Input Leakage	lin						±1	μΑ
Input Capacitance	CIN					10		pF
DIGITAL OUTPUT (DOUT, SST	RB)							
Output-Voltage Low	Vol	I <sub>SINK</sub> = 2mA					0.4	V
Output-Voltage High	VOH	$I_{SOURCE} = 2mA$			V <sub>DD</sub> - 0.5			V
Tri-State Leakage Current	١L	$\overline{\text{CS}} = \text{V}_{\text{DD}}$					±10	μA
Tri-State Output Capacitance	Соит	$\overline{\text{CS}} = \text{V}_{\text{DD}}$				10		pF
POWER REQUIREMENTS								
Desitive Cuerchy Veltage	)/	MAX1147/MAX1	2.7		3.6	V		
Positive Supply Voltage	V <sub>DD</sub>	MAX1146/MAX1	148		4.75		5.25	v
			External	116ksps		1.1	1.5	
		Normal	reference	10ksps		0.12		mA
Supply Current (Note 8)	IDD	operation, full-		1ksps		0.012		
		scale input	Internal refere 116ksps	ence at		1.9	2.4	mA
		Fast power-dowr	<u>ו</u>			120		
Shutdown Supply Current (Note 8)		Full power-down			0.3		μA	
		SHDN = DGND		0.3	10			
Power-Supply Rejection (Note 9)	PSR	External reference	e			±0.2		mV

## TIMING CHARACTERISTICS

 $(V_{DD} = 4.75V \text{ to } 5.25V \text{ (MAX1146/MAX1148)}, V_{DD} = 2.7V \text{ to } 3.6V \text{ (MAX1147/MAX1149)}, \overline{SHDN} = V_{DD}, V_{COM} = 0, f_{SCLK} = 2.1MHz$ , external clock (50% duty cycle), 18 clocks/conversion (116ksps), V\_{REFADJ} = V\_{DD}, C\_{REF} = 2.2\muF, external +4.096V reference at REF for the MAX1146/MAX1148, external 2.500V reference at REF for the MAX1147/MAX1149, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.) (Figures 1, 2, and 3)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DIN to SCLK Setup Time	tDS		50			ns
DIN to SCLK Hold Time	tDH		0			ns
SCLK Fall to Output Data Valid	tdov	$C_{LOAD} = 50 pF$	10		80	ns
CS Fall to DOUT Enable	<b>t</b> DOE	$C_{LOAD} = 50 pF$			120	ns
CS Rise to DOUT Disable	tDOD	$C_{LOAD} = 50 pF$			120	ns
SHDN Rise CS Fall to SCLK Rise Time	tCSS		50			ns
SHDN Rise CS Fall to SCLK Rise Hold Time	tCSH		50			ns
	fa a	External clock mode	0.1		2.1	
SCLK Clock Frequency	<b>f</b> SCLK	Internal clock mode	0		2.1	MHz
SCLK Pulse-Width High	tсн	Internal clock mode	100			ns
SCLK Pulse-Width Low	tCL	Internal clock mode	100			ns
CS Fall to SSTRB Output Enable	<b>t</b> STE	External clock mode only			120	ns
CS Rise to SSTRB Output Disable	<b>t</b> STD	External clock mode only			120	ns
SSTRB Rise to SCLK Rise	tsck	Internal clock mode only		0		ns
SCLK Fall to SSTRB Edge	tSCST				80	ns
CS Pulse Width	tcsw		100			ns

**Note 1:** Tested at  $V_{DD} = 3.0V$  (MAX1147/MAX1149) or 5.0V(MAX1146/MAX1148);  $V_{COM} = 0$ ; unipolar single-ended input mode. **Note 2:** Relative accuracy is the deviation of the analog value at any code from its theoretical value after the full-scale range has

been calibrated.

**Note 3:** Offset nulled. Measured with external reference.

**Note 4:** "On" channel grounded; full-scale 1kHz sine wave applied to all "off" channels.

Note 5: Conversion time defined as the number of clock cycles multiplied by the clock period; clock has 50% duty cycle. (See Figures 8–11.)

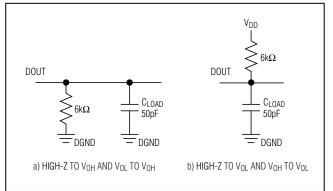
**Note 6:** The common-mode range for the analog inputs is from AGND to  $V_{DD}$ .

Note 7: Digital inputs equal V<sub>DD</sub> or DGND.

**Note 8:** External load should not change during conversion for specified accuracy.

Note 9: Measured as  $(V_{FS} \times 3.6V) - (V_{FS} \times 2.7V)$  for the MAX1147/MAX1149 and  $(V_{FS} \times 5.25V) - (V_{FS} \times 4.75V)$  for the MAX1146/MAX1148.  $V_{DD} = 3.6V$  to 2.7V for MAX1147/MAX1149 and  $V_{DD} = 5.25V$  to 4.75V for the MAX1146/MAX1148.





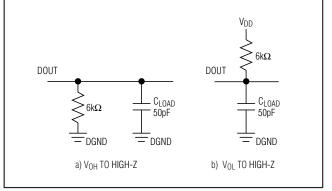
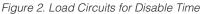


Figure 1. Load Circuits for Enable Time



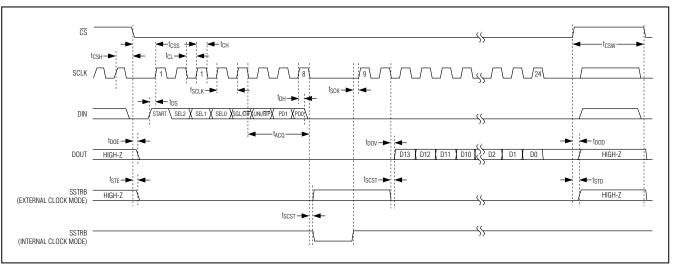


Figure 3. Detailed Operating Characteristics

#### **DNL vs. OUTPUT CODE INL vs. OUTPUT CODE** (MAX1147/MAX1149) 1.5 2.0 1.5 1.8 INTERNAL REFERENCE 1.0 1.0 1.6 SUPPLY CURRENT (mA) 1.4 0.5 0.5 1.2 DNL (LSB) INL (LSB) EXTERNAL REFERENCE 0 1.0 0 0.8 -0.5 -0.5 0.6 0.4 -1.0 -1.0 0.2 -1.5 -15 0 0 4096 8192 12288 16384 3.6 16384 2.7 3.0 3.3 0 4096 8192 12288 OUTPUT CODE SUPPLY VOLTAGE (V) OUTPUT CODE **SUPPLY CURRENT vs. SUPPLY VOLTAGE** SHUTDOWN SUPPLY CURRENT SHUTDOWN SUPPLY CURRENT (MAX1146/MAX1148) vs. SUPPLY VOLTAGE (MAX1147/MAX1149) vs. SUPPLY VOLTAGE (MAX1146/MAX1148) 0.45 2.0 1.8 1.8 1.6 0.40 INTERNAL REFERENCE SHUTDOWN SUPPLY CURRENT (µA) SUPPLY CURRENT (µA) 1.6 1.4 0.35 SUPPLY CURRENT (mA) 1.4 1.2 0.30 1.2 1.0 0.25 EXTERNAL REFERENCE 1.0 0.8 0.20 0.8 SHUTDOWN 0.6 0.15 0.6 0.4 0.10 0.4 0.2 0.05 0.2 0 0 0 4.75 4.80 4.85 4.90 4.95 5.00 5.05 5.10 5.15 5.20 5.25 2.8 2.9 3.0 3.1 3.2 3.3 3.4 3.5 3.6 4.75 4.85 4.95 5.05 5.15 5.25 2.7 SUPPLY VOLTAGE (V) SUPPLY VOLTAGE (V) SUPPLY VOLTAGE (V) SUPPLY CURRENT SHUTDOWN SUPPLY CURRENT vs. CONVERSION RATE **SUPPLY CURRENT vs. TEMPERATURE** vs. TEMPERATURE 4.5 1200 2.5 4.0 SHUTDOWN SUPPLY CURRENT (µA) 1000 MAX1146/MAX1148 INTERNAL REFERENCE 2.0 3.5 SUPPLY CURRENT (MA) SUPPLY CURRENT (mA) MAX1147/MAX1149 INTERNAL REFERENCE 800 3.0 MAX1146/MAX1148 1.5 2.5 600 MAX1146/MAX1148 EXTERNAL REFERENCE FAST POWER-DOWN 2.0 1.0 MAX1147/MAX1149 EXTERNAL REFERENCE 400 1.5 1.0 0.5 MAX1147/MAX1149 200 FULL 0.5 POWER-DOWN 0 0 0 0.01 0.1 1000 -40 85 1 10 100 -40 -15 10 35 60 85 -15 10 35 60 CONVERSION RATE (ksps) TEMPERATURE (°C) TEMPERATURE (°C)

## **Typical Operating Characteristics**

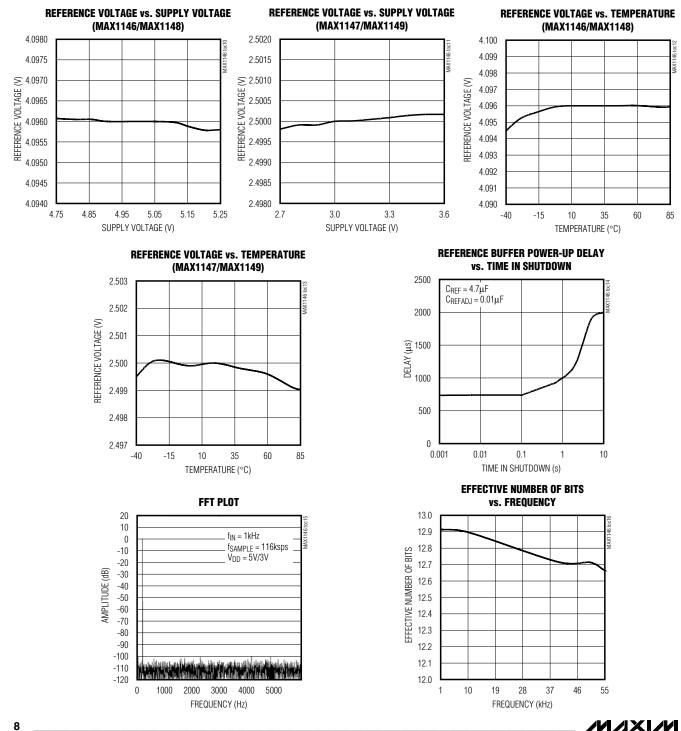
**SUPPLY CURRENT vs. SUPPLY VOLTAGE** 

 $(V_{DD} = +5.0V (MAX1146/MAX1148), V_{DD} = +3.3V (MAX1147/MAX1149), SHDN = V_{DD}, V_{COM} = 0, f_{SCLK} = 2.1MHz, external clock (50% duty cycle), 18 clocks/conversion (116ksps), V_{REFADJ} = V_{DD}, external +4.096V reference at REF (MAX1146/MAX1148), external +2.500V reference at REF (MAX1147/MAX1149), C_{REF} = 2.2\muF, C_{LOAD} = 50pF, T_A = +25^{\circ}C, unless otherwise noted.)$ 

M/X/M

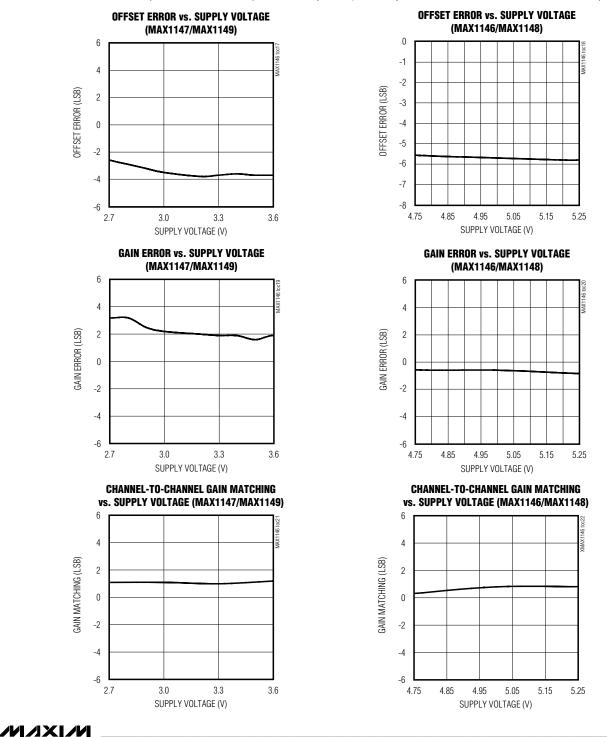
## **Typical Operating Characteristics (continued)**

 $(V_{DD} = +5.0V (MAX1146/MAX1148), V_{DD} = +3.3V (MAX1147/MAX1149), SHDN = V_{DD}, V_{COM} = 0, f_{SCLK} = 2.1MHz, external clock (50% duty cycle), 18 clocks/conversion (116ksps), V_{REFADJ} = V_{DD}, external +4.096V reference at REF (MAX1146/MAX1148), external +2.500V reference at REF (MAX1147/MAX1149), C_{REF} = 2.2\muF, C_{LOAD} = 50pF, T_A = +25^{\circ}C, unless otherwise noted.)$ 



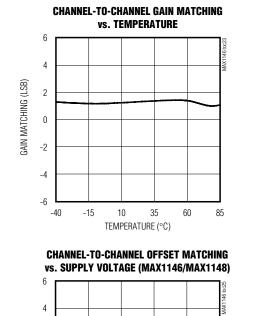
## **Typical Operating Characteristics (continued)**

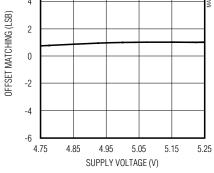
 $(V_{DD} = +5.0V (MAX1146/MAX1148), V_{DD} = +3.3V (MAX1147/MAX1149), \overline{SHDN} = V_{DD}, V_{COM} = 0, f_{SCLK} = 2.1MHz, external clock (50% duty cycle), 18 clocks/conversion (116ksps), V_{REFADJ} = V_{DD}, external +4.096V reference at REF (MAX1146/MAX1148), external +2.500V reference at REF (MAX1147/MAX1149), C_{REF} = 2.2\muF, C_{LOAD} = 50pF, T_A = +25^{\circ}C, unless otherwise noted.)$ 



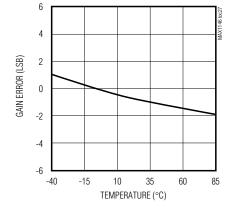
## **Typical Operating Characteristics (continued)**

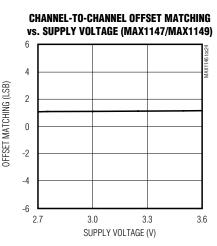
 $(V_{DD} = +5.0V (MAX1146/MAX1148), V_{DD} = +3.3V (MAX1147/MAX1149), SHDN = V_{DD}, V_{COM} = 0, f_{SCLK} = 2.1MHz, external clock (50% duty cycle), 18 clocks/conversion (116ksps), V_{REFADJ} = V_{DD}, external +4.096V reference at REF (MAX1146/MAX1148), external +2.500V reference at REF (MAX1147/MAX1149), C_{REF} = 2.2\muF, C_{LOAD} = 50pF, T_A = +25^{\circ}C, unless otherwise noted.)$ 



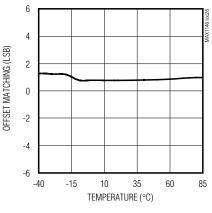




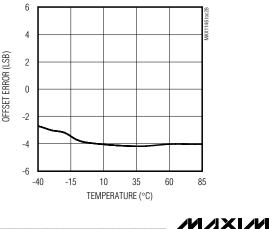




CHANNEL-TO-CHANNEL OFFSET MATCHING vs. TEMPERATURE



**OFFSET ERROR vs. TEMPERATURE** 





10

MAX1146-MAX1149

## Pin Description

P	N		
MAX1148 MAX1149	MAX1146 MAX1147	NAME	FUNCTION
1	1	CH0	
2	2	CH1	
3	3	CH2	
4	4	CH3	Analog Inputs
5		CH4	
6	_	CH5	
7	_	CH6	
8	_	CH7	
9	9	СОМ	Common Input. Negative analog input in single-ended mode. COM sets zero-code voltage in unipolar and bipolar mode.
10	10	SHDN	Active-Low Shutdown Input. Pulling SHDN low shuts down the device reducing supply current to 0.2µA. Driving shutdown high enables the devices.
11	11	REF	Reference-Buffer Output/ADC Reference Input. Reference voltage for analog-to-digital conversion. In internal reference mode, the MAX1146/MAX1148 $V_{REF}$ is +4.096V, and the MAX1147/MAX1149 $V_{REF}$ is +2.500V.
12	12	REFADJ	Bandgap Reference Output and Reference Buffer Input. Bypass to AGND with a $0.01\mu$ F capacitor. Connect REFADJ to V <sub>DD</sub> to disable the internal bandgap reference and reference-buffer amplifier.
13	13	AGND	Analog Ground
14	14	DGND	Digital Ground
15	15	DOUT	Serial Data Output. Data is clocked out at the falling edge of SCLK when $\overline{CS}$ is low. DOUT is high impedance when $\overline{CS}$ is high.
16	16	SSTRB	Serial Strobe Output. In internal clock mode, SSTRB goes low when the ADC conversion begins, and goes high when the conversion is finished. In external clock mode, SSTRB pulses high for two clock periods before the MSB decision. SSTRB is high impedance when $\overline{CS}$ is high (external clock mode).
17	17	DIN	Serial Data Input. Data is clocked in at the rising edge of SCLK when $\overline{\text{CS}}$ is low. DIN is high impedance when $\overline{\text{CS}}$ is high.
18	18	CS	Active-Low Chip Select. Data is not clocked into DIN unless $\overline{CS}$ is low. When $\overline{CS}$ is high, DOUT is high impedance.
19	19	SCLK	Serial Clock Input. Clocks data in and out of the serial interface and sets the conversion speed in external clock mode. (Duty cycle must be 40% to 60%.)
20	20	V <sub>DD</sub>	Positive Supply Voltage. Bypass to AGND with a $0.1\mu$ F capacitor.
_	5–8	N.C.	No Connection. Not internally connected.

MAX1146-MAX1149

# MAX1146-MAX1149

## \_Detailed Description

The MAX1146–MAX1149 ADCs use a successiveapproximation conversion technique and input T/H circuitry to convert an analog signal to a 14-bit digital output. A flexible serial interface provides easy interface to microprocessors ( $\mu$ Ps). Figure 4 shows the typical application circuit and Figure 5 shows a functional diagram of the MAX1148/MAX1149.

#### True-Differential Analog Input and Track/Hold

The MAX1146–MAX1149 analog input architecture contains an analog input multiplexer (MUX), two T/H capacitors, T/H switches, a comparator, and two switched capacitor digital-to-analog converters (DACs) (Figure 6).

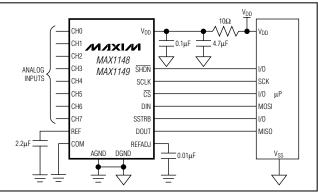


Figure 4. Typical Application Circuit

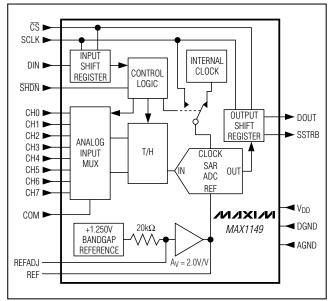


Figure 5. Functional Diagram

In single-ended mode, the analog input MUX connects IN+ to the selected input channel and IN- to COM. In differential mode, IN+ and IN- are connected to the selected analog input pairs such as CH0/CH1. Select the analog input channels according to Tables 1–5.

The analog input multiplexer switches to the selected channel on the control byte's fifth SCLK falling edge. At this time, the T/H switches are in the track position and CT/H+ and CT/H- track the analog input signal. At the control byte's eighth SCLK falling edge, the MUX opens and the T/H switches move to the hold position, retaining the charge on CT/H+ and CT/H- as a sample of the input signal. See Figures 8–11 for input MUX and T/H switch positioning.

During the conversion interval, the switched capacitive DAC adjusts to restore the comparator-input voltage to 0 within the limits of 14-bit resolution. This action requires 15 conversion clock cycles and is equivalent to transferring a charge of  $18pF \times (V_{IN+} - V_{IN-})$  from  $C_{T/H+}$  and  $C_{T/H-}$  to the binary-weighted capacitive DAC, forming a digital representation of the analog input signal.

After conversion, the T/H switches move from the hold position to the track position and the MUX switches back to the last specified position. In internal clock mode, the conversion is complete on the rising edge of SSTRB. In external clock mode, the conversion is complete on the eighteenth SCLK falling edge.

The time required for the T/H to acquire an input signal is a function of the analog input source impedance. If the input signal source impedance is high, the acquisition time lengthens. The MAX1146–MAX1149 provide three SCLK cycles ( $t_{ACQ}$ ) in which the T/H capacitance must acquire a charge representing the input signal, typically the last three SCLKs of the control word. The input source impedance ( $R_{SOURCE}$ ) should be minimized to allow the T/H capacitance to charge within this allotted time.

#### $t_{ACQ} = 11.5 \times (R_{SOURCE} + R_{IN}) \times C_{IN}$

where  $\mathsf{R}_{SOURCE}$  is the analog input source impedance,  $\mathsf{R}_{IN}$  is 2.6k $\Omega$  (which is the sum of the analog input MUX and T/H switch resistances), and  $\mathsf{C}_{IN}$  is 18pF (which is the sum of  $\mathsf{C}_{T/H+}, \mathsf{C}_{T/H-}$ , and input stray capacitance).

To minimize sampling errors with higher source impedances, connect a 100pF capacitor from the analog input to AGND. This input capacitor reduces the input's AC impedance but forms an RC filter with the source impedance, limiting the analog input bandwidth. For larger source impedance, use a buffer amplifier such as the MAX4430 to maintain analog input signal integrity.



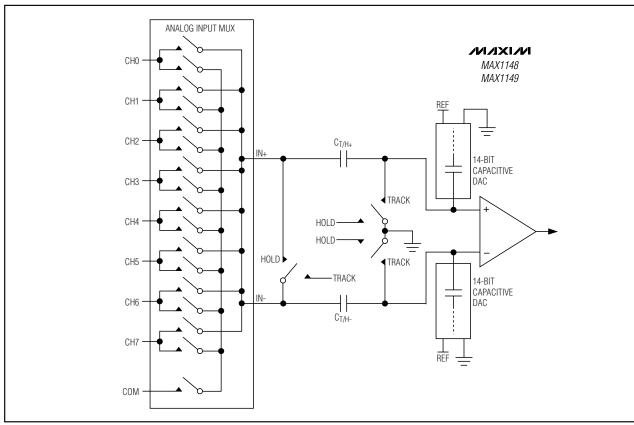


Figure 6. Equivalent Input Circuit

#### Input Bandwidth

The MAX1146–MAX1149 feature input tracking circuitry with a 3.0MHz small-signal bandwidth. The 3.0MHz input bandwidth makes it possible to digitize highspeed transient events and measure periodic signals with bandwidths exceeding the ADC's sampling rate by using undersampling techniques. To avoid high frequency signals being aliased into the frequency band of interest, anti-alias filtering is recommended.

#### **Analog Input Protection**

Internal protection diodes clamp the analog input to V<sub>DD</sub> and AGND. These diodes allow the analog inputs to swing from (AGND - 0.3V) to (V<sub>DD</sub> + 0.3V) without causing damage to the device. For accurate conversions, the inputs must not go more than 50mV below AGND or above V<sub>DD</sub>.

**Note:** If the analog input exceeds 50mV beyond the supply rails, limit the current to 2mA.

#### **Quick Look**

MAX1146-MAX1149

Use the circuit of Figure 7 to quickly evaluate the MAX1148/MAX1149. The MAX1148/MAX1149 require a control byte to be written to DIN using SCLK before each conversion. Connecting DIN to V<sub>DD</sub> and clocking SCLK feeds in a control byte of \$FF HEX (see Table 1). Trigger single-ended unipolar conversions on CH7 in external clock mode without powering down between conversions. In external clock mode, the SSTRB output pulses high for two clock periods before the MSB of the 14-bit conversion result is shifted out of DOUT. Varying the analog input to CH7 alters the sequence of bits from DOUT. A total of 18 clock cycles are required per conversion (Figure 10). All transitions of the SSTRB and DOUT outputs occur on the falling edge of SCLK.

MAX1146-MAX1149

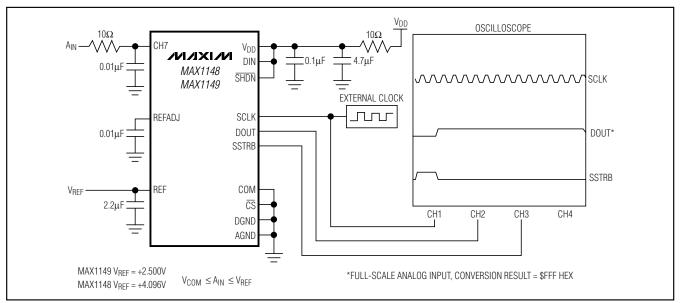


Figure 7. Quick-Look Circuit

## Table 1. Control Byte Format

BIT	NAME	DESCRIPTION		
7 (MSB)	START	Start bit. The first logic 1 bit after $\overline{\text{CS}}$ goes low defines the beginning of the control byte.		
6	SEL2			
5	SEL1	Channel-select bits. The channel-select bits select which of the eight channels are used for the conversion (Tables 2, 3, 4, and 5).		
4	SEL0	(Tables 2, 0, 4, and 0).		
3	SGL/DIF	1 = single ended, 0 = differential. Selects single-ended or differential conversions. In single-ended mode, input signal voltages are referred to COM. In differential mode, the voltage difference between two channels is measured.		
2	UNI/BIP	1 = unipolar, 0 = bipolar. Selects unipolar or bipolar conversion mode. In unipolar mode, connect COM to AGND to perform conversion from 0 to $V_{REF}$ . In bipolar mode, connect COM to $V_{REF}/2$ to perform conversion from 0 to $V_{REF}$ . See Table 7.		
1	PD1	Selects clock and power-down modes. PD1 = 0 and PD0 = 0 selects full power-down mode*.		
0 (LSB)	PD0	PD1 = 0 and PD0 = 1 selects fast power-down mode*. PD1 = 1 and PD0 = 0 selects internal clock mode. PD1 = 1 and PD0 = 1 selects external clock mode.		

\*The start bit resets power-down modes.

## Table 2. MAX1148/MAX1149 Channel Selection in Single-Ended Mode (SGL/DIF = 1)

							-		•		
SEL2	SEL1	SEL0	CH0	CH1	CH2	CH3	CH4	CH5	CH6	CH7	СОМ
0	0	0	+								-
1	0	0		+							-
0	0	1			+						-
1	0	1				+					-
0	1	0					+				-
1	1	0						+			-
0	1	1							+		-
1	1	1								+	-
-											

## Table 3. MAX1148/MAX1149 Channel Selection in Differential Mode (SGL/DIF = 0)

SEL2	SEL1	SEL0	CH0	CH1	CH2	СНЗ	CH4	CH5	CH6	CH7
0	0	0	+	-						
0	0	1			+	-				
0	1	0					+	-		
0	1	1							+	-
1	0	0	-	+						
1	0	1			-	+				
1	1	0					-	+		
1	1	1							-	+

## Table 4. MAX1146/MAX1147 Channel Selection in Single-Ended Mode (SGL/DIF = 1)

SEL2	SEL1	SEL0	CH0	CH1	CH2	CH3	СОМ
0	0	0	+				-
1	0	0		+			-
0	0	1			+		-
1	0	1				+	-

#### **Power-On Reset**

When power is first applied, internal power-on reset circuitry activates the MAX1146–MAX1149 in internal clock mode, making the MAX1146–MAX1149 ready to convert with SSTRB high. No conversions should be performed until the power supply is stable. The first logical 1 on DIN with CS low is interpreted as a start bit. Until a conversion takes place, DOUT shifts out zeros.

#### **Starting a Conversion**

Start a conversion by clocking a control byte into DIN. With  $\overline{\text{CS}}$  low, a rising edge on SCLK latches a bit from DIN into the MAX1146–MAX1149 internal shift register. After  $\overline{\text{CS}}$  falls, the first logic 1 bit defines the control

## Table 5. MAX1146/MAX1147 Channel Selection in Differential Mode (SGL/DIF = 0)

SEL2	SEL1	SEL0	CH0	CH1	CH2	СНЗ
0	0	0	+	-		
0	0	1			+	-
1	0	0	-	+		
1	0	1			-	+

byte's MSB. Until this start bit arrives, any number of logic 0 bits can be clocked into DIN with no effect. Table 1 shows the control-byte format.

The MAX1146–MAX1149 are compatible with SPI/QSPI and MICROWIRE devices. For SPI, select the correct clock polarity and sampling edge in the SPI control registers. Set CPOL = 0 and CPHA = 0. MICROWIRE, SPI, and QSPI transmit a byte and receive a byte at the same time. Using the *Typical Application Circuit* (Figure 4), the simplest software interface requires only three 8-bit transfers to perform a conversion (one 8-bit transfer to configure the ADC, and two more 8-bit transfers to clock out the 14-bit conversion result).

#### Digital Output

In unipolar input mode, the digital output is straight binary (Figure 14). For bipolar input mode, the digital output is two's complement binary (Figure 15). Data is clocked out on the falling edge of SCLK in MSB-first format.

#### **Clock Modes**

The MAX1146–MAX1149 can use either the external serial clock or the internal clock to drive the successive-approximation conversion. The external clock shifts data in and out of the MAX1146–MAX1149.

External clock mode allows the fastest throughput rate (116ksps) and serial clock frequencies from 0.1MHz to 2.1MHz. Internal clock mode provides the best noise performance because the digital interface can be idle during conversion. The internal clock mode serial clock frequency can range from 0 to 2.1MHz. Internal clock mode allows the CPU to request a conversion and clock back the results.

Bits PD1 and PD0 of the control byte program the clock and power-down modes. The MAX1146–MAX1149 power up in internal clock mode with all circuits activated. Figures 8–11 illustrate the available clocking modes.

#### External Clock

In external clock mode, the external clock not only shifts data in and out, but it also drives the analog-todigital conversion. SSTRB pulses high for two clock periods after the last bit of the control byte. Successiveapproximation bit decisions are made and the results appear at DOUT on each of the next 14 SCLK falling edges (Figures 8 and10). SSTRB and DOUT go into a high-impedance state when CS is high. Use internal clock mode if the serial clock frequency is less than 100kHz or if serial clock interruptions could cause the conversion interval to exceed 140 $\mu$ s. The conversion must complete in 140 $\mu$ s, or droop on the T/H capacitors can degrade conversion results.

#### Internal Clock

When configured for internal clock mode, the MAX1146–MAX1149 generate an internal conversion clock. This frees the  $\mu$ P from the burden of running the SAR conversion clock and allows the conversion results to be read back at the processor's convenience, at any clock rate up to 2.1MHz. SSTRB goes low at the start of the conversion and then goes high when the conversion is complete. SSTRB is low for a maximum of 8.0µs, during which time SCLK should remain low for best noise performance.

An internal register stores data when the conversion is in progress. SCLK clocks the data out of this register at any time after the conversion is complete. After SSTRB goes high, the second falling SCLK clock edge produces the MSB of the conversion at DOUT, followed by the remaining bits in MSB-first format (Figures 9 and 11).

For the most accurate conversion, the MAX1146–MAX1149 digital I/O should remain inactive during the internal clock conversion interval (t<sub>CONV</sub>). Do not pull  $\overline{\text{CS}}$  high during conversion. Pulling  $\overline{\text{CS}}$  high aborts the current conversion. To ensure that the next start bit is recognized, clock in 18 zeros at DIN. When internal clock mode is selected, SSTRB does not go into a high-impedance state when  $\overline{\text{CS}}$  goes high. A rising edge on SSTRB indicates that the MAX1146–MAX1149 have finished the conversion. The  $\mu$ P can then read the conversion results at its convenience.

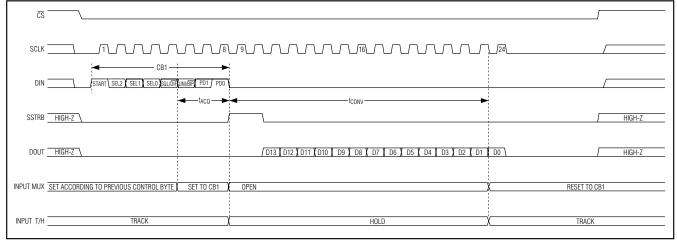


Figure 8. External Clock Mode—24 Clocks/Conversion Timing

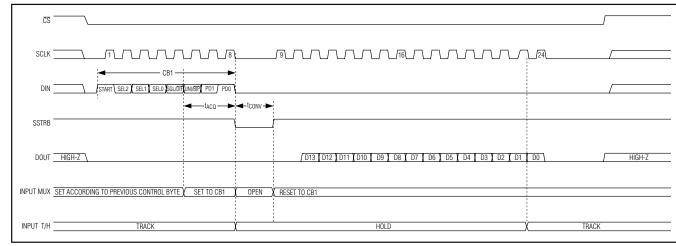


Figure 9. Internal Clock Mode Timing—24 Clocks/Conversion Timing

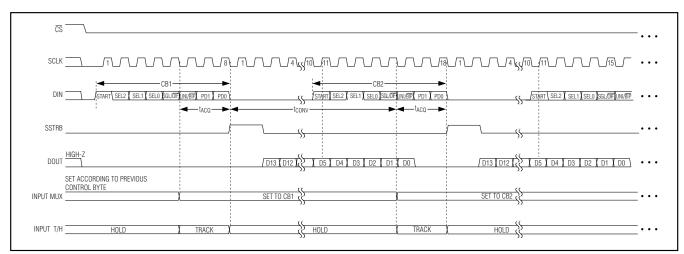


Figure 10. External Clock Mode—18 Clocks/Conversion Timing

## \_Applications Information

#### Idle Mode

The device is considered idle when all the bits have been clocked out or 18 zeros have been clocked in on DIN.

#### Start Bit

The falling edge of  $\overline{CS}$  alone does not start a conversion. The first logic high clocked into DIN with  $\overline{CS}$  low is interpreted as a start bit and defines the first bit of the control byte. The device begins to track on the fifth falling edge of SCLK after a start bit has been recognized. A conversion starts on the eighth falling edge of SCLK as the last bit of the control byte is being clocked in. The start bit is defined as follows:

///XI///

1) The first high bit clocked into DIN with  $\overline{\text{CS}}$  low any time the converter is idle.

or

 The first high bit clocked into DIN after bit 5 of a conversion in progress is clocked onto DOUT (Figures 10 and 11).

Toggling  $\overline{\text{CS}}$  before the current conversion is complete aborts the conversion and clears the output register.

The fastest the MAX1146–MAX1149 can run with  $\overline{\text{CS}}$  held low between conversions is 18 clocks per conversion. Figures 10 and 11 show the serial-interface timing necessary to perform a conversion every 18 SCLK cycles.

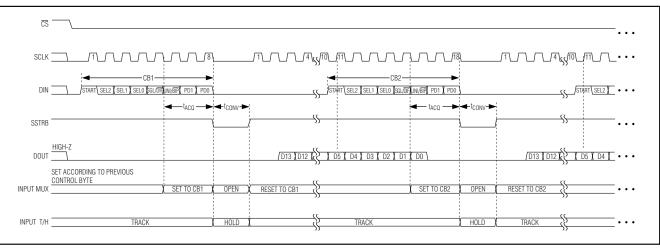


Figure 11. Internal Clock Mode—18 Clocks/Conversion Timing

#### **Shutdown and Power-Down Modes**

The MAX1146–MAX1149 provide a hardware shutdown and two software power-down modes.

Pulling SHDN low places the converter in hardware shutdown. The conversion is immediately terminated and the supply current is reduced to 300nA. Allow 2ms for the device to power-up when the internal reference buffer is used with CREFADJ =  $0.01\mu$ F and CREF =  $2.2\mu$ F. Larger capacitors on CREFADJ and CREF increase the power-up time (Table 6). No wake-up time is needed for the device to power-up from fast power-down when using an external reference.

Select a software power-down mode through the PD1 and PD0 bits of the control byte (Table 1). When the conversion in progress is complete, software powerdown is initiated. The serial interface remains active and the last conversion result can be clocked out. In full power-down mode, only the serial interface remains operational and the supply current is reduced to 300nA. In fast power-down mode, only the bandgap reference and the serial interface remain operational, and the supply current is reduced to 600µA.

# Table 6. Internal Reference Buffer Power-Up Times vs. Bypass Capacitors

CREFADJ*	CREF	POWER-UP TIMES FROM AN EXTENDED POWER-DOWN
0.01µF	4.7µF	2ms
0.1µF	10µF	25ms

\*Power-up times are dominated by CREFADJ.

18

The MAX1146–MAX1149 automatically wake up from software power-down when they receive the control byte's start bit (Table 1). Allow 2ms for the device to power-up when the internal reference buffer is used with CREFADJ =  $0.01\mu$ F and CREF =  $2.2\mu$ F. Larger capacitors on CREFADJ and CREF increase the power-up time (Table 6). No wake-up time is needed for the device to power-up from fast power-down when using an external reference.

#### **Reference Voltage**

The MAX1146–MAX1149 can be used with an internal or external reference voltage. The reference voltage determines the ADC input range. The reference determines the full-scale output value (Table 7).

#### Internal Reference

The MAX1146–MAX1149 contain an internal 1.250V bandgap reference. This bandgap reference is connected to REFADJ through a 20k $\Omega$  resistor. Bypass REFADJ with a 0.01 $\mu$ F capacitor to AGND. The MAX1146/MAX1148 reference buffer has a 3.277V/V gain to provide +4.096V at REF. The MAX1147/MAX1149 reference buffer has a 2.000V/V gain to provide +2.500V at REF. Bypass REF with a minimum 2.2 $\mu$ F capacitor to AGND when using the internal reference.

#### External Reference

An external reference can be applied to the MAX1146-MAX1149 in two ways:

- Disable the internal reference buffer by connecting REFADJ to V<sub>DD</sub> and apply the external reference to REF (Figure 12).
- 2) Utilize the internal reference buffer by applying an external reference to REFADJ (Figure 13).



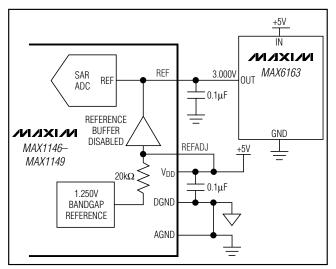


Figure 12. External Reference Applied to REF

Method 1 allows the direct application of an external reference from 1.5V to V<sub>DD</sub> + 50mV. The REF input impedance is typically 10k $\Omega$ . During conversion, an external reference at REF must deliver up to 210µA and have an output impedance less than 10 $\Omega$ . Bypass REF with a 0.1µF capacitor to AGND to improve its output impedance.

Method 2 utilizes the internal reference buffer to reduce the external reference load. The REFADJ input impedance is typically  $20k\Omega$ . During a conversion, an external reference at REFADJ must deliver at least  $100\mu$ A and have an output impedance less than  $100\Omega$ . The MAX1146/MAX1148 reference buffer has a 3.277V/Vgain and the MAX1147/MAX1149 has a gain of 2.000V/V. The external reference voltage at REFADJ multiplied by the reference buffer gain is the SAR ADC reference voltage. This reference appears at REF and must be from 1.5V to V<sub>DD</sub> + 50mV. Bypass REFADJ

 Table 7. Full Scale and Zero Scale

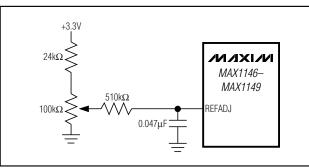


Figure 13. Reference Adjust Circuit

with a 0.01 $\mu$ F capacitor and bypass REF with a 2.2 $\mu$ F capacitor to AGND.

#### **Transfer Function**

MAX1146-MAX1149

Table 7 shows the full-scale voltage ranges for unipolar and bipolar modes.

Output data coding for the MAX1146–MAX1149 is binary in unipolar mode and two's complement binary in bipolar mode with 1 LSB = ( $V_{REF}/2^N$ ), where N is the number of bits (14). Code transitions occur halfway between successive-integer LSB values. Figure 14 and Figure 15 show the input/output (I/O) transfer functions for unipolar and bipolar operations, respectively.

#### **Serial Interfaces**

The MAX1146–MAX1149 feature a serial interface that is fully compatible with SPI, QSPI, and MICROWIRE. If a serial interface is available, establish the CPU's serial interface as a master, so that the CPU generates the serial clock for the ADCs. Select a clock frequency up to 2.1MHz.

#### SPI and MICROWIRE Interface

When using an SPI (Figure 16a) or MICROWIRE interface (Figure 16b), set CPOL = CPHA = 0. Two 8-bit readings are necessary to obtain the entire 14-bit result from the ADC. DOUT data transitions on the serial clock's falling

INPUT AND OUTPUT MODES	UNIPOLAR MODE		BIPOLAR MODE		
	ZERO SCALE	FULL SCALE	NEGATIVE FULL SCALE	ZERO SCALE	POSITIVE FULL SCALE
Single-Ended Mode	Vcom	VREF + VCOM	$\frac{-V_{\text{REF}}}{2} + V_{\text{COM}}$	VCOM	$\frac{+V_{REF}}{2}+V_{COM}$
Differential Mode	VIN-	$V_{REF} + V_{IN-}$	$\frac{-V_{REF}}{2} + V_{IN}$	V <sub>IN-</sub>	$\frac{+V_{REF}}{2}+V_{IN}$

*Note:* The common mode range for the analog inputs is from AGND to V<sub>DD</sub>.

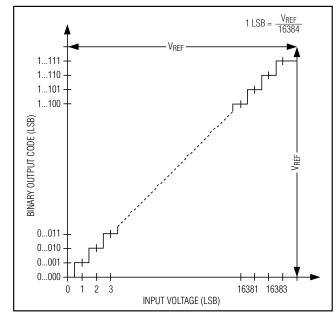


Figure 14. Unipolar Transfer Function

edge and is clocked into the  $\mu$ P on SCLK's rising edge. The first 8-bit data stream contains the first 8-bits of DOUT starting with the MSB. The second 8-bit data stream contains the remaining 6 result bits.

#### **QSPI** Interface

Using the high-speed QSPI interface (Figure 17) with CPOL = 0 and CPHA = 0, the MAX1146–MAX1149 support a maximum f<sub>SCLK</sub> of 2.1MHz. One 16-bit reading is necessary to obtain the entire 14-bit result from the ADC. DOUT data transitions on the serial clock's falling edge and is clocked into the  $\mu$ P on SCLK's rising edge. The first 14 bits are the data.

#### PIC16/PIC17 SSP Module Interface

The MAX1146-MAX1149 are compatible with a PIC16/PIC17 microcontroller ( $\mu$ C), using the synchronous serial-port (SSP) module. To establish SPI com-

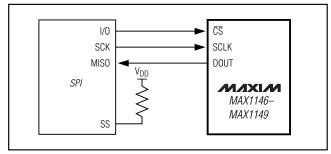


Figure 16a. SPI Connections

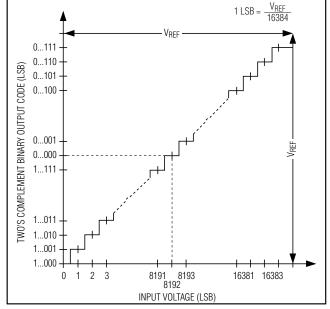


Figure 15. Bipolar Transfer Function

munication, connect the controller as shown in Figure 18 and configure the PIC16/PIC17 as system master. Initialize the synchronous serial-port control register (SSPCON) and synchronous serial-port status register (SSPSTAT) to the bit patterns shown in Tables 8 and 9. In SPI mode, the PIC16/PIC17  $\mu$ Cs allow 8 bits of data to be synchronously transmitted and received simultaneously. Two consecutive 8-bit readings are necessary to obtain the entire 14-bit result from the ADC. DOUT data transitions on the serial clock's falling edge and is clocked into the  $\mu$ C on SCLK's rising edge. The first 8-bit data stream contains the first 8 data bits starting with the MSB. The second data stream contains the remaining bits, D5 through D0.

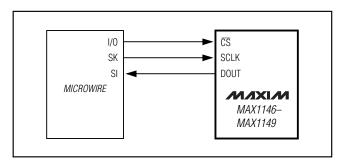
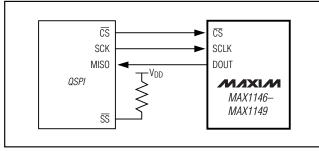


Figure 16b. MICROWIRE Connections







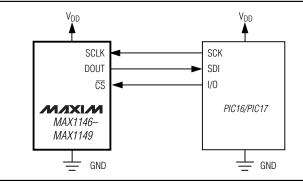


Figure 18. SPI Interface Connection for a PIC16/PIC17 Controller

CONTR	OL BIT	PICI6/PICI7 SETTINGS	SYNCHRONOUS SERIAL-PORT CONTROL REGISTER (SSPCON)	
WCOL	Bit 7	Х	Write collision detection bit.	
SSPOV	Bit 6	Х	Receive overflow detect bit.	
SSPEN	Bit 5	1	Synchronous serial port enable bit: 0: Disables serial port and configures these pins as I/O port pins. 1: Enables serial port and configures SCK, SDO, and SCI pins as serial-port pins.	
CKP	Bit 4	0	Clock polarity select bit. CKP = 0 for SPI master mode selection.	
SSPM3	Bit 3	0	Synchronous serial port mode select bit. Sets SPI master mode and selects $F_{CLK} = f_{OSC} / 16$ .	
SSPM2	Bit 2	0		
SSPM1	Bit 1	0		
SSPM0	Bit 0	1		

## **Table 8. Detailed SSPCON Register Content**

## Table 9. Detailed SSPSTAT Register Content

CONTROL BIT MAX1146-MAX1149 SETTINGS SYNCHRONOUS SEI			SYNCHRONOUS SERIAL-PORT STATUS REGISTER (SSPSTAT)
SMP	Bit 7	0	SPI data input sample phase. Input data is sampled at the middle of the data output time.
CKE	Bit 6	1	SPI clock edge select bit. Data is transmitted on the rising edge of the serial clock.
D/A	Bit 5	Х	Data address bit.
Р	Bit 4	Х	Stop bit.
S	Bit 3	Х	Start bit.
R/W	Bit 2	Х	Read/write bit information.
UA	Bit 1	Х	Update address.
BF	Bit 0	Х	Buffer full status bit.

MAX1146-MAX1149

#### TMS32OLC3x Interface

Figure 19 shows an application circuit to interface the MAX1146–MAX1149 to the TMS320 in external clock mode. The timing diagram for this interface circuit is shown in Figure 20. Use the following steps to initiate a conversion in the MAX1146–MAX1149 and to read the results:

- The TMS320 should be configured with CLKX (transmit clock) as an active-high output clock and CLKR (TMS320 receive clock) as an active-high input clock. CLKX and CLKR on the TMS320 are connected together with the MAX1146–MAX1149 SCLK input.
- 2) Drive the  $\overline{CS}$  of the MAX1146–MAX1149 low through the XF\_ I/O port of the TMS320 to clock data into the MAX1146–MAX1149 DIN.
- 3) Write an 8-bit word (1XXXXX11) to the MAX1146–MAX1149 to initiate a conversion and place the device into external clock mode. Refer to Table 1 to select the proper XXXXX bit values for your specific application.
- 4) The MAX1146–MAX1149 SSTRB output is monitored by the FSR input of the TMS320. A falling edge on the SSTRB output indicates that the conversion is in progress and data is ready to be received from the MAX1146–MAX1149.
- 5) The TMS320 reads in one data bit on each of the next 16 rising edges of SCLK. These data bits represent the 14-bit conversion result followed by 2 trailing bits, which should be ignored.
- 6) Pull CS high to disable the MAX1146–MAX1149 until the next conversion is initiated.

#### Layout, Grounding, and Bypassing

Careful PC board layout is essential for best system performance. Boards should have separate analog and digital ground planes. Ensure that digital and analog signals are separated from each other. Do not run analog and digital (especially clock) lines parallel to one another, or digital lines underneath the device package.

Figure 4 shows the recommended system ground connections. Establish an analog ground point at AGND and a digital ground point at DGND. Connect all analog grounds to the star analog ground. Connect the digital ground point to the analog ground point directly at the device. For lowest noise operation, the ground return to the star ground's power supply should be low impedance and as short as possible.

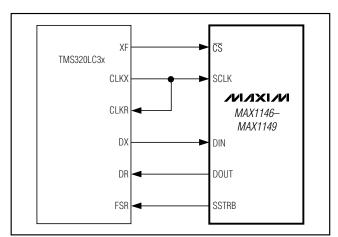


Figure 19. MAX1146–MAX1149-to-TMS320 Serial Interface

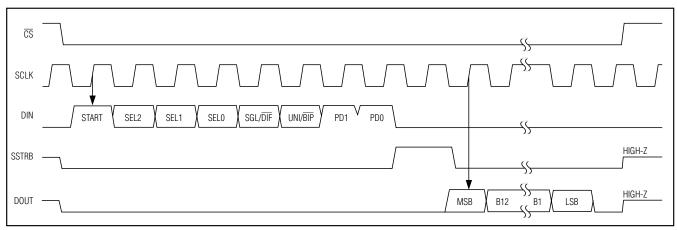


Figure 20. TMS320 Serial-Interface Timing Diagram

M \|X| \M

High-frequency noise in the VDD power supply degrades the device's high-speed performance. Bypass the supply to the digital ground with 0.1µF and 4.7µF capacitors. Minimize capacitor lead lengths for best supply-noise rejection. Connect a 10 $\Omega$  resistor in series with the 0.1µF capacitor to form a lowpass filter when the power supply is noisy.

## \_Definitions

#### **Integral Nonlinearity**

Integral nonlinearity (INL) is the deviation of the values on an actual transfer function from a straight line. This straight line can be either a best-straight-line fit or a line drawn between the end points of the transfer function, once offset and gain errors have been nullified. The static linearity parameters for the MAX1146–MAX1149 are measured using the end-point method.

#### **Differential Nonlinearity**

Differential nonlinearity (DNL) is the difference between an actual step width and the ideal value of 1 LSB. A DNL error specification of less than 1 LSB guarantees no missing codes and a monotonic transfer function.

#### **Aperture Definitions**

Aperture jitter  $(t_{AJ})$  is the sample-to-sample variation in the time between the samples. Aperture delay  $(t_{AD})$  is the time between the rising edge of the sampling clock and the instant when an actual sample is taken.

#### Signal-to-Noise Ratio

For a waveform perfectly reconstructed from digital samples, signal-to-noise ratio (SNR) is the ratio of full-scale analog input (RMS value) to the RMS quantization error (residual error). The ideal, theoretical minimum analog-to-digital noise is caused by quantization error only and results directly from the ADC's resolution (N bits):

#### $SNR = (6.02 \times N + 1.76) dB$

In reality, there are other noise sources besides quantization noise: thermal noise, reference noise, clock jitter, etc. SNR is computed by taking the ratio of the RMS signal to the RMS noise, which includes all spectral components minus the fundamental, the first five harmonics, and the DC offset.

#### Signal-to-Noise Plus Distortion

Signal-to-noise plus distortion (SINAD) is the ratio of the fundamental input frequency's RMS amplitude to RMS equivalent of all other ADC output signals.

 $SINAD(dB) = 20 \times log (SignalRMS / NoiseRMS)$ 

#### **Effective Number of Bits**

Effective number of bits (ENOB) indicates the global accuracy of an ADC at a specific input frequency and sampling rate. An ideal ADC's error consists of quantization noise only. With an input range equal to the full-scale range of the ADC, calculate the ENOB as follows:

ENOB = (SINAD - 1.76) / 6.02

#### **Total Harmonic Distortion**

Total harmonic distortion (THD) is the ratio of the RMS sum of the first five harmonics of the input signal to the fundamental itself. This is expressed as:

THD = 
$$20 \times \log \left( \sqrt{\frac{V_2^2 + V_3^2 + V_4^2 + V_5^2}{V_1}} \right)$$

where  $V_1$  is the fundamental amplitude, and  $V_2$  through  $V_5$  are the amplitudes of the 2nd- through 5th-order harmonics.

#### **Spurious-Free Dynamic Range**

Spurious-free dynamic range (SFDR) is the ratio of RMS amplitude of the fundamental (maximum signal component) to the RMS value of the next-largest distortion component.

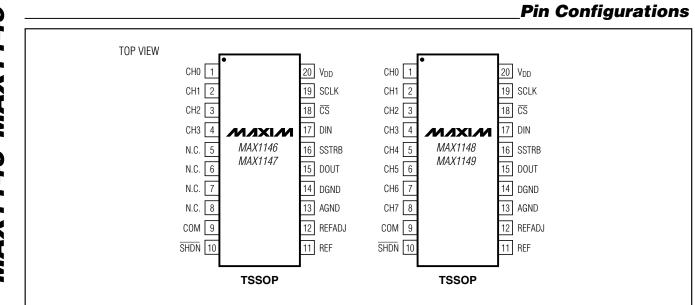
## **Chip Information**

TRANSISTOR COUNT: 5589 PROCESS: BICMOS

## **Revision History**

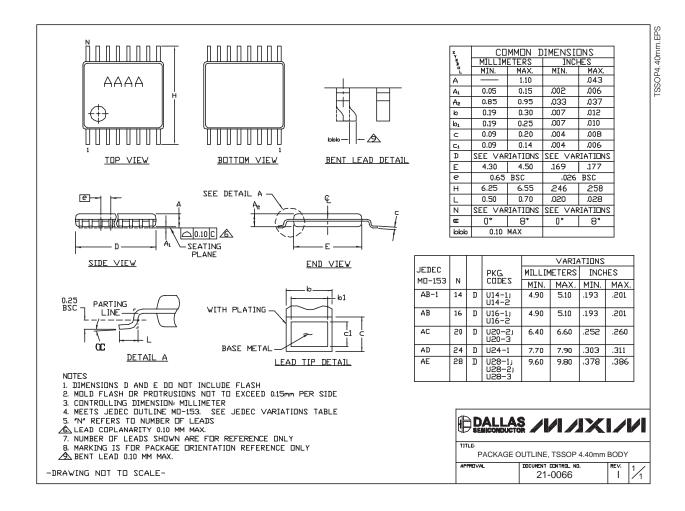
Pages changed at Rev 2: 1, 20, 23, 25.





## \_Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)



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