Embedded Power for **Business-Critical Continuity**

> Rev. 05.26.08 MTC600 Series 1 of 19

µTG

MicroTCA MTC600 Series 600 Watts

Total Power:

600 Watts # of Channels: 16



Product Description

General

The MTC600 series of Power Modules are designed for use in MicroTCA systems and can support shelves, cube and other implementations and is compliant to PICMG MicroTCA .0 Revision 1.0 specification.

The MTC600 Power Modules implement the functionality necessary to power, manage and protect a MicroTCA system comprising up to:

- 12x AdvancedMCs
- 2x MicroTCA Carrier Hubs
- 2x Cooling Units

The MTC600 Power Modules will:

- On system bring-up, provide the power necessary for MCH and CU system elements.
- Support redundant IPMI (IPMB-0) communication with the MCH/ Carrier-Manager
- Under the command of the carrier manager, enable and provide power to AMCs, CUs and additional MCHs
- Monitor and Report power system status and conditions of operation
- Manage and isolate faults affecting the power system



Special Features

- 600 W output power
- 16 Channels of
 - 12 V @ 7.6 A max
 - 3.3 V @ 150 mA max
- Supports:
 - 12x AMC's
 - 2x MCH's • 2x CU's
- Supports N+1 output redundancy, N≤3
- Supports 1+1 input redundancy

Compliance

- PICMG MicroTCA.0 (Revision 1.0)
- PICMG HPM.1 Firmware Upgrade (Revision 1.0)

Safety

UL, cUL	60950-1
CSA	60950-1
VDE	60950-1

Product Description (continued)

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Embedded Power for Business-Critical Continuity

Electrical Specifications

Input		
-48 Vdc Models		
Input Range (Operating)	-39.5 to -72 Vdc	Supports -48 V and -60 V battery plants
Input Range (Non-operating)	0 to -39.5 Vdc -72 to -75 Vdc	Power Module may or may not operate in part of this range, but will not be damaged
Input Fusing	Internal 24 A Fuses	In both A & B feeds and A & B return lines
Input ORing	Internal	In both A & B feeds and A & B return lines
Inrush Current	≤80 A	For t < 1 ms
Input Current	12.8 A 18.2 A	Typical with 600 W out, -54.0 Vin Maximum with 600 W out, -39.5 Vin
Holdup Time	5 ms 7 ms 10 ms 10 ms	Minimum at 600 W with one PM Typical at 600 W with one PM Typical at 400 W with one PM Minimum at 600 W with two PMs
UnderVoltage Lockout	39.5 ±1.0 V 37.0 ±1.0 V	Turn-On voltage Turn-Off voltage
Reverse Polarity Protection	Included	Protected against reverse polarity over magnitude of specified input range
AC Models		
Input Range (Operating)	90 to 264 Vac	Supports typical worldwide single-phase inputs
Input Range (Non-operating)	0 to 90 Vac 264 to 282 Vac	Power Module may or may not be operating in part of this range, but will not be damaged
Frequency	47 to 63 Hz	
Input Fusing	Internal 15 A Fuses	
Inrush Current	≤45 A	I ² t integral compatible with 15 A fast-blow fuse
Power Factor	0.99 typical	Meets EN61000-3-2
Harmonics	<2.30 Arms (odd) <1.08 Arms (even)	
Input Current	2.95 A 6.6 A	Typical with 600 W out, 230 Vac Maximum with 600 W out, 110 Vac
Holdup Time	16.7 ms 20 ms	At 110 Vac, 60 Hz At 230 Vac, 50 Hz
UnderVoltage Lockout	87 ± 2.5 V 83 ± 2.5 V	Turn-On voltage Turn-off voltage
OverVoltage Lockout	282 Vac	Power Module will turn-off if input voltage exceeds this voltage and not turn on until input voltage is reduced below this level

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Output - All Models (continued)

12 V Outputs (Payload Power)^{1,2}

Management Power Interdependence

Setpoint

Total Regulation Range

Rated Load

Minimum Load Output Rise TIme (per channel) Output Noise (PARD)³

Output Voltage Overshoot Transient Response

Voltage Sag

Short Circuit Protection

Channel Fault Operation (Output to Return)

Channel Fault Operation (Output to Output)

PS1# Extraction Delay

Reflected Ripple Tolerance on Cooling Unit Outputs⁴

12 V will not be applied without 3.3 V applied to a load

> 12.6 Vdc typical 11.8 Vdc typical

12.25 to 12.95 Vdc 11.60 to 12.00 Vdc

600 W maximum 80 W / 7.6 A maximum

No load

25 ms maximum

75 mV maximum 100 mV maximum

2% maximum

3% maximum deviation 2 ms recovery time

1.00 V maximum

9.7 A maximum 10 ms maximum

12V Payload Power Output under fault is shutdown. 3V3 MP on the same channel is not affected. The other channels are not affected

No damage to Power Module

100 µs maximum

100 mV pk-pk 0.8 A pk-pk Rev. 05.26.08 MTC600 Series 4 of 19

Removal of 3.3 V also removes 12 V and de-asserts ENABLE#

> Configured as Primary PM Configured as Redundant PM

Configured as Rrimary PM Configured as Redundant PM

Per Power Module, input voltage ≥110 Vac Per load channel

No loss of regulation ≥110 Vrms

With 1600 µF on output under test

0 to 30 MHz 0 to 100 MHz

Referenced to setpoint

2 A loadstep @ 1 A/μs Referenced to load current and setpoint at onset of transient. Recovery time to within 1% of setpoint at onset of transient

Primary PM to redundant PM transition with maximum of 80 W load per output or 600 W load per PM

Output to return

After removal of fault, the output channel is available again under control of the Carrier Manager. PM_OK# is not de-asserted and redundant failover is not initiated

Either or both outputs may shut down until fault is removed

Time from de-assertion of PS1# to disabling of the channel outputs and de-assertion of the ENABLE# signal

Tolerance of Power Module to ripple generated by fans or motors connected to Payload Power on Cooling Units

- **Note 1:** All channels and outputs must be configued by the carrier manager with the exception of MCH and CU channels and outputs which are configured during Startup and/or autonomous operation,
- Note 2: All measurements are made at the output connector of the Power Module. Unless otherwise specified, specs apply to all AMC, MCH, and CU outputs.
- Note 3: Measured with a 0.1 µF ceramic and 10 µF tantalum capacitor on any output and oscilloscope bandwidth set for 200 MHz.
- Note 4: Consult with the factory if other outputs are expected to product significant ripple current.

Output - All Models (continued)

3.3 V Outputs (Management Power) ^{5,6} Payload Power Interdependence

Setpoint Total Regulation Range Rated Load

Minimum Load Output Rise TIme (per channel) Output Noise (PARD)³

Output Voltage Overshoot Transient Response

Voltage Sag

Short Circuit Protection

Channel Fault Operation (Output to Return)

Channel Fault Operation (Output to Output)

PS1# Extraction Delay

3.3 V must be applied before 12 V

3.3 Vdc typical 3.16 to 3.63 Vdc

8 W maximum 0.5 W / 150 mA maximum

No load

25 ms maximum

50 mV maximum 75 mV maximum

2% maximum

3% maximum deviation 2 ms recovery time

150 mV maximum

225 mA maximum 12 ms maximum

Output channel under fault is shutdown. Both 3.3V and 12V are removed and ENABLE# is de-asserted. The other channels are not affected

No damage to Power Module

100 µs maximum

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Removal of 3.3 V also removes 12 V and de-asserts ENABLE#

> Per Power Module Per load channel

No loss of regulation With 150 $\,\mu\text{F}$ on output under test

0 to 30 MHz 0 to 100 MHz

Referenced to setpoint

37.5 mA loadstep @ 1 A/µs Referenced to load current and setpoint at onset of transient. Recovery time to within 1% of setpoint at onset of transient

Primary PM to redundant PM transition with max of 80 W load per output or 600 W load per PM

Output to return

After removal of fault, the output channel is available again under control of the Carrier Manager. PM_OK# is not de-asserted and redundant failover is not initiated

Either or both channels may shut down until fault is removed

Time from de-assertion of PS1# to disabling of the channel outputs and de-assertion of the ENABLE# signal

- **Note 5:** All channels and outputs must be configued by the carrier manager with the exception of MCH and CU channels and outputs which are configured during Startup and/or autonomous operation.
- **Note 6:** All measurements are made at the output connector of the Power Module. Unless otherwise specified, specs apply to all AMC, MCH, and CU outputs.

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Output - All Models (continued)		
General		
Turn-on Time	4 seconds maximum	After power-on of the PM, the time for autonomous outputs to reach regulation band
Early Power	Supported	PM supports Early Power requirements refer- enced in MicroTCA.0 Rev 1.0 Section 4.4.11.1
Normal Power	Supported	PM supports Normal Power requirements refer- enced in MicroTCA.0 Rev 1.0 Section 4.4.11.2
Autonomous Operation	Supported	PM supports Autonomous Operation require- ments referenced in MicroTCA.0 Rev 1.0 Section 4.4.11.3
Diagnostic Mode	Supported [GA2,GA1,GA0] = 101, or [GA2,GA1,GA0] = 110 LED1 displays yellow	In Diagnostic Mode PM disables the IPMI con- trols and slots are powered up based only on PSI# signals
Redundancy ⁷		
Hot-Swap Operation (controlled)	Supported	Removal or addition of a PM will not cause a fault or out-of-regulation condition
Hot-Swap Operation (uncontrolled)	Supported	Removal or addition of a PM will not cause a fault or out-of-regulation condition
Power Module Failover	Supported	When configured as a redundant PM, the PM is capable of accepting the load of a failed PM within specified voltage magnitude and timing parameters
Fault Isolation	Supported	A fault in one PM will not cause the shutdown of another PM

Note 7: All specifications in the redundancy sub-section assume the system is populated with Power Modules with the same manufacturer's model numbers or otherwise compatible Power Modules. At the time of print, PICMG does not have a formal methodology for verifying compatibility.

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Input Signals - All models

Geographic Address: GA0, GA1, GA2

Internal pull ups to 3.3 V. Source current limited by 11 Kohm (300 μA with GAx at 0.0 V)

	MIN	MAX
Logic Level Low - V _{IL}		0.5 V
Logic Level High- V _{IH}	1.63 V	

PS1_[SLOT]#: PS1_M1, PS1_M2, PS1_CU1, PS1_CU2, PS1_1, ...PS_12

Internal pull ups to 3.3 V. Source current limited by 10 Kohm (330 uA with PS1_[SLOT]# at 0.0 V)

	MIN	MAX
Logic Level Low Voltage - V _{IL}		1.1 V
Logic Level High Voltage - V _{IH}	2.6 V	

PWRON_[MCH]: PWRON_MI, PWRON_M2

Internal 10 Kohm pull down. Compatible with MicroTCA.0 R1.0 Section A.5.4

	MIN	MAX
Logic Level Low - V _{IL}		0.5 V
Logic Level High - V _{IH}	1.63 V	

RST_PM_IN#: RST_PM_IN#

	MIN	MAX
Logic Level Low - V _{IL}		0.6 V
Logic Level High - V _{IH}	2.4 V	

PMP_[x]#: PMP_A#, PMP_B#, PMP_C#

Internal pull up to 3.3 V. Source current limited by 10 Kohm (330 uA with $PMP_[x]$ # at 0.0 V)

	MIN	MAX
Logic Level Low Voltage - V _{IL}		0.5 V
Logic Level High Voltage - V _{IH}	1.63 V	

PS_PM#: PS_PM#

Internal pull up to 3.3 V.	Source current l	limited by 10 Kohm
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	MIN	MAX
Logic Level Low Voltage - V _{IL}		0.6 V
Logic Level High Voltage - V _{IH}	2.4 V	

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utput Signals - All Models		
EN1_[SLOT]#: EN1_M1, EN1_M2, EN1_CU1, EN1_CU2, EN1_1, EN1_2EN1_12 Open collector output. Isink, max=10 mA. No internal current limit		
	MIN	MAX
Logic Level Low Voltage - V _{OL}		0.8 V
/oltage Withstand - V _{max}		5.5 V

PM_OK#: PM_OK#

Open collector output, Isink max = 10 mA. No current limit

	MIN	MAX
Logic Level Low Voltage - V _{OL}		0.8 V
Voltage Withstand - V _{max}		5.5 V

RST_PM_[x]#: RST_PM_A#,RST_PM_B#,RST_PM_C#

Open collector output, Isink, max = 10 mA. No current limit

	MIN	MAX
Logic Level Low Voltage, - V _{OL}		0.8 V
Voltage Withstand - V _{max}		5.5 V

Shared Signals - All Models			
SMP: SMP Compliant to MicroTCA.0 R1.0 Section 4.6.5.4.3, requirements 4.221-4.225			
	MIN	MAX	
Voltage Range	4.5 V	6 V	
lsink		750 mA	
lsource		350 mA	

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I ² C Interface - All Models		
Operating Parameters		
I ² C Operating Voltage	3.3 V	Nominal
I ² C Operating Frequency	100 kHz	

SDA_[x]: SDA_A, SDA_B

Internal pull ups to 3.3 V. Source current limited by 10 Kohm (330 µA with SDA_[x] at 0.0 V). Bufferede to support hot-swap

	MIN	MAX
Logic Level Low - V _{IL}		0.7 V
Logic Level High - V _{IH}	2.70 V	

SCL_[x]: SCL_A, SCL_B

Internal pull ups to 3.3 V. Source current limited by 10 Kohm (330 uA with SCL_[x] at 0.0 V). Buffered to support hot-swap.

	MIN	MAX
Logic Level Low Voltage - V _{IL}		0.7 V
Logic Level High Voltage - V _{IH}	2.70 V	

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IPMB-0 Inte	erface				MTC600 Se 10 c	
РМ-ЕММС						
Functionality A PM-EMMC is implemented per MicroTCA.0 R1.0 requirements 4.116 through 4.120						
IPM Device						
IPMB Interface		PM-EMMC aggregate	s IPMB-A and IPMB-B IPMI	v1.5 protocol		
SDR Repository						
Sensors		Implements mandato	ory 2 temp sensors; Impler	ments voltage and currer	nt senors	
Watchdog Timer		Implements a watchd	log timer for resetting PM	's own PM-EMMC		
FRU Inventory						
Initialization Agent		PM-EMMC is responsi	ble for initializing it's own	event generation and se	ensors	
Internal Event Genera	tion					
External Event Genera	ation	ion Events sent over IPMB-0				
Power Channel Map	ping					
Power Channel	Management Power	Payload Power	Payload Power PS1# ENABLE# Autonomous Power			
1, 2	MP_M1, MP_M2	PP_M1, PP_M2	PS1_M1#, PS1_M2#	EN_M1#, EN_M2#	Depends on PWRON_ M1, PWRON_M2	
3, 4	MP_CU1, MP_CU2	PP_CU1, PP_CU2	PS1_CU1#, PS1_CU2#	EN_CU1#, EN_CU2#	Yes	
5-16	MP_1 - MP_12	PP_1 - PP_12	PS1_# - PS1-12#	EN_1# - EN_12#	No	
Supported Comma	ands					
Global Commands NetFN App Request=	06h; Response=07h					
Command		CMD		Note		
Get Device ID		01h	As defined in IPMI v	1.5; Broadcast Get Devid	ce ID not supported	
Cold Reset		02h	02h As defined in IPMI v1.5			
Event Commands NetFN S/E Request=04h; Response=05h						
Command		CMD		Note		
Set Event Receiver		00h As defined in IPMI v1.5				
Get Event Receiver		01h As defined in IPMI v1.5				
Platform Event		02h	02h As defined in IPMI v1.5			

IPMB-0 Interface (continued)

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Supported Commands (Continued)				
Sensor Device Commands NetFN S/E Request=04h; Response=05h				
Command	CMD	Note		
Get Device SDR Info	20h	As defined in IPMI v1.5		
Get Device SDR	21h	As defined in IPMI v1.5		
Reserve Device SDR Repository	22h	As defined in IPMI v1.5		
Set Sensor Hysteresis	24h	As defined in IPMI v1.5		
Get Sensor Hysteresis	25h	As defined in IPMI v1.5		
Set Sensor Threshold	26h	As defined in IPMI v1.5		
Get Sensor Threshold	27h	As defined in IPMI v1.5		
Get Sensor Reading	2Dh	As defined in IPMI v1.5		
FRU Device Commands NetFN Storage Request=0Ah; Response=0B	h			
Command	CMD	Note		
Get FRU Inventory Area Info	10h	As defined in IPMI v1.5		
Read FRU Data	11h	As defined in IPMI v1.5		
Write FRU Data	12h	As defined in IPMI v1.5		
PICMG Commands NetFN Storage Request=2Ch; Response=2D	h			
Command	CMD	Note		
Get PICMG Properties	00h	As defined in MicroTCA.0 R1.0		
Get FRU LED Properties	05h	As defined in PICMG3.0 R2.0 (ATCA)		
Get LED Color Capabilities	06h	As defined in PICMG3.0 R2.0 (ATCA)		
Set FRU LED State	07h	As defined in PICMG3.0 R2.0 (ATCA)		
Get FRU LED State	08h	As defined in PICMG3.0 R2.0 (ATCA)		
Set IPMB State	09h	As defined in PICMG3.0 R2.0 (ATCA)		
Get Device Locator Reader ID	0Dh	As defined in PICMG3.0 R2.0 (ATCA)		
Get IPMB Link Info	18h	As defined in PICMG3.0 R2.0 (ATCA)		
MicroTCA Commands NetFN PICGMG Request=2Ch; Reponse=2D	h			
Command	CMD	Note		
Power Channel Control	24h	As defined in MicroTCA.0.0 R1.0		
Get Power Channel Status	25h	As defined in MicroTCA.0.0 R1.0		
PM Reset	26h	As defined in MicroTCA.0.0 R1.0		
Get PM Status	27h	As defined in MicroTCA.0.0 R1.0		
PM Heartbeat	28h	As defined in MicroTCA.0.0 R1.0		

IPMB-0 Interface (continued)

Sensors - Mandatory per PICMG and Related Standards

Event and Status Sensors

These sensors are implemented according to the requirements and specifications of the relevant standards.

Sensor Name	Sensor Number	
Management Controller Device Locator	00h	
Power Channel Notification	01h	
PM Status	02h	
IPMB Physical Link	03h	
Hot Swap	04h	

Temperature Sensors

All temperature sensors have an accuracy of 5%. All temperature sensors have an offset of -40 °C.

Sensor Name	Sensor Number	Resolution	Applicable Models
Hotspot Temperature	05h	1 °C / bit	All
Ambient Temperature	06h	1 °C / bit	All
Thresholds	Assertion/Deassertion	Comparison Returned	Settable/Readable
Upper Non-Recoverable	Yes	Yes	R
Upper Critical	Yes	Yes	S/R
Upper Non-Critical	Yes	Yes	S/R
Lower Critical	Yes	Yes	S/R
Lower Non-Critical	Yes	Yes	S/R

Sensors - Non-Mandatory per PICMG and Related Standards

Internal Voltage Sensors

All voltage sensors have an accuracy of 2%.

Sensor Name	Sensor Number	Resolution	Applicable Models	
12 Volt	07h	07h 100 mV / bit		
3V3 Volt	08h	50 mV / bit	All	
5 V Volt	09h	50 mV / bit	All	
Thresholds	Assertion/Deassertion	Comparison Returned	Settable/Readable	
Upper Critical	Yes	Yes	S/R	
Lower Critical	Yes	Yes	S/R	

Internal Current Sensors

All current sensors have an accuracy of 2%.

Sensor Name	Sensor Number	Resolution	Applicable Models
12 V Current	0Ah	0.5 A / bit	All
3V3 Volt	0Bh	50 mA / bit	All
Thresholds	Assertion/Deassertion	Comparison Returned	Settable/Readable
Upper Critical	Yes	Yes	S/R

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IPMB-0 Interface (continued)

Sensors - Non-Mandatory per PICMG and Related Standards (continued)

Input Voltage Sensors

All voltage sensors have an accuracy of 2%.

Sensor Name	Sensor Number	Resolution	Applicable Models
AC Input Voltage	0Ch	2.0 V / bit	MTC600-AC only
DC Input Votlage A	0Ch	0.5 V / bit	MTC600-48 only
DC Input Voltage B	0Dh	0.5 V / bit	MTC600-48 only
DC Input Or-ed	0Eh	0.5 V / bit	MTC600-48 only
Thresholds	Assertion/Deassertion	Comparison Returned	Settable/Readable
Upper Critical	Yes	Yes	S/R
Lower Critical	Yes	Yes	S/R
Lower Non-Recoverable	Yes	Yes	R

Input Current Sensors

All current sensors have an accuracy of 2%.

Sensor Name	Sensor Number	Resolution	Applicable Models	
AC Input Current	0Dh	100 mA / bit	MTC600-AC only	
DC Input Current	0Fh	100 mA / bit	MTC600-48 only	
Thresholds	Assertion/Deassertion	Comparison Returned	Settable/Readable	
No thresholds implemented	n/a	n/a	n/a	

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Environmental Specifications

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emperature and Altitude Derating ⁸						
60 m below to 1800 m above sea level						
ondition	Temperature	Load				
torage Non-Operating	-45 °C to +70 °C	-				
old Start	-20 °C to -5 °C	Any valid condition				
Jormal Operation	-5 °C to 45 °C	100%				
hort Term Operation ⁹	45 °C to 55 °C	Linear derating to 80% at 55 $^\circ C$				
800 m to 4000 m above sea level						
ondition	Temperature	Load				
torage Non-Operating	-45 °C to +70 °C	-				
old Start	-20 °C to -5 °C	Any valid condition				
lormal Operation	-5 °C to 35 °C 35 °C to 45 °C	100% System dependent				
hort Term Operation ⁹	45 °C to 55 °C	System dependent				
ther Environmental						
riteria	Specification	Reference				
elative Hunidity	5% - 95%, non-condensing	GR-63-CORE, R4-7; IEC 60068-2-56, 2-30				
'ibration	0.1 g @ 5-100 Hz and back to 5 Hz at a rate of 0.1 octave/min or 1.5 g @ 100-500 Hz with 0.25 octave/min; 1.5 mm @ 2-9 Hz, 0.5 g @ 9-200 Hz	GR-63-CORE, R4-58, R4-59; IEC 60068-2-6, 2-36				
hock	4 g @ 22 ms	IEC 60068-2-27, 2-29				
Гор	Packaged: 450 mm drop height; Unpackaged: 25 mm drop height; Transportation: 1.2 m free fall	GR-63-CORE, R4-8, R4-9 IEC 60068-2-32				
ire Resistance	All material UL 94V-1 or better					
800 m to 4000 m above sea level condition torage Non-Operating cold Start lormal Operation hort Term Operation ⁹ Other Environmental Criteria celative Hunidity (ibration chock Drop	Temperature -45°C to +70°C -20°C to -5°C -5°C to 35°C 35°C to 45°C 45°C to 55°C 45°C to 55°C Specification 5% - 95%, non-condensing 0.1 g @ 5-100 Hz and back to 5 Hz at a rates of 0.1 octave/min or 1.5 g @ 100-500 Hz with 0.25 octave/min; 1.5 mm @ 2-9 Hz, 0.5 g @ 9-200 Hz 4 g @ 22 ms Packaged: 450 mm drop height; Unpackaged: 25 mm drop height; Transportation: 1.2 m free fall All material UL 94V-1 or better	Load Any valid condition 100% System dependent System dependent System dependent (Reference GR-63-CORE, R4-7; IEC 60068-2-56, 2-30 GR-63-CORE, R4-58, R4-59; IEC 60068-2-6, 2-36 IEC 60068-2-6, 2-36				

Standards Compliance for Telecommunications Applications

The Power Module will not hinder system compliance to the following environmental specifications:

Telcordia GR-63-CORE

- Telcordia GR-1089-CORE
- NEBS Level 3, per SR-3580
- ETS300 019-1-1, Part 1-1 (Class 1.2E equipment) ETS300 019-1-2, Part 1-2 (Class 2.3 equipment) •
- •
- ETS300 019-1-3, Part 1-3 (Class 3.2 equipment)
- Note 8: 12 CFM airflow for -48 V model; 15 CFM airflow for AC model.
- Note 9: Short Term Operation defined as total period of not more than 96 consecutive hours and total of not more than 15 days in 1 year.

Electromagnetic Compatibility

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All Models							
Radiated Emissions							
Standard	Limits & Test Parameters	Frequency Range	Criteria				
EN55022, Class A	Per Section 6	3 MHz to 1 GHz	N/A				
GR-1089-CORE	Per Section 3.2	10 KHz to 10 GHz	N/A				
Conducted Emissions							
EN55022, Class A	Per Section 6	150 KHz to 30 MHz	N/A				
GR-1089-CORE	Per Section 3.2 10 KHz to 30 MHz		N/A				
ElectroStatic Discharge							
EN61000-4-2	8 KV Contact, 15 KV Air discharge Impulsive		В				
Radiated Immunity							
EN61000-4-3	10 V/m (level measure unmodu- lated) 80% AM, 1 KHZ		A				
Conducted Immunity							
EN61000-4-6	3 V (level measured unmodulated) 80% AM, 1HKz	150 KHz to 80 MHz	A				
Voltage Dips & Interruptions							
EN61000-4-11	-100% for 10 ms @ 0°; -100% for 10 ms @ 180°; -60% for 100 ms; -30% for 500 ms; -100% for 5 s	Impulsive	B,C				
AC Models							
Fast Transients							
EN61000-4-4	5/50 ns 5 KHz pulse 1 KV direct	Impulsive	В				
Surge	1						
EN61000-4-5	1.2/50 μsec pulse 2 KV Line to Earth 1 KV Line to Line	Impulsive	В				
-48 Vdc Models							
Fast Transients							
EN61000-4-4	5/50 ns 5 KHz pulse 500 V direct	Impulsive	В				
Surge							
EN61000-4-5	1.2/50 μsec pulse 500 V Line to Earth 500 V Line to Line	Impulsive	В				

Mechanical Specifications (continued)

Front Panel - MTC600-48

Input Connector: Positronics QB7W2MN7T2, FCI 10070158, or equivalent

Mating Connector: Positronics QB7W2F00QH0/AA, FCI 10070165, or equivalent

Pinout: P1: Return P2: -48 V

1: Not Used 2: Not Used

Front Panel - MTC600-AC

Input Connector: IEC 320-C14, or equivalent

Mating Connector: IEC 320-C13, or equivalent

Pinout: L: Line N: Neutral G: Ground



General - MTC600-48

Weight: 25 oz. (700 grams) typical



General - MTC600-AC

Weight: 30 oz. (850 grams) typical

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Mechanical Specifications (continued)

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Output Connector

Output Connector: EPT P/N 501-50096-183, Tyco P/N 1469922-1, or equivalent Mating Connector: EPT P/N 502-50096-183, Tyco P/N 1469920-1, or equivalent

Pinout P1 PP_M1(2nd Mate) PP_1(2nd Mate) P13 P2 PP_CU1(2nd Mate) PP_2(2nd Mate) P14 PS1_x# P3 PP_CU2(2nd Mate) PP_3(2nd Mate) P15 EN_x# P4 PP_4(2nd Mate) P16 GND(1st Mate) SCL_x P5 PP_5(2nd Mate) GND(1st Mate) P17 SDA_x P6 GND(1st Mate) PP_6(2nd Mate) P18 P7 GND(1st Mate) PP_7(2nd Mate) P19 P8 GND(1st Mate) PP_8(2nd Mate) P20 P9 PP_9(2nd Mate) P21 GND(1st Mate) P10 GND(1st Mate) PP_10(2nd Mate) P22 P11 PP_11(2nd Mate) P23 GND(1st Mate) P12 PP_M2(2nd Mate) PP_12(2nd Mate) P24 1 PS PM# PM_OK# PS1_M1# PS1_CU1# EN_M1# (Last Mate) (3rd Mate) (3rd Mate) (3rd Mate) (3rd Mate) 2 N/C PMP A# PS1 2# PS1 1# EN 2# (3rd Mate) (3rd Mate) (3rd Mate) (3rd Mate) 3 PMP B# PS1 4# PS1_3# EN 4# N/C (3rd Mate) (3rd Mate) (3rd Mate) (3rd Mate) 4 N/C PMP_C# PS1 5# PS1_6# EN_6# (3rd Mate) (3rd Mate) (3rd Mate) (3rd Mate) 5 N/C RST PM IN# PS1 8# PS1 7# EN 8# (3rd Mate) (3rd Mate) (3rd Mate) (3rd Mate) 6 N/C RST_PM_A# PS1 10# PS1 9# EN 10# (3rd Mate) (3rd Mate) (3rd Mate) (3rd Mate) 7 GA0 RST_PM_B# PS1_12# PS1_11# EN_12# (3rd Mate) (3rd Mate) (3rd Mate) (3rd Mate) (3rd Mate) 8 GA1 RST PM C# PS1 M2# PS1 CU2# EN M2# (3rd Mate) (3rd Mate) (3rd Mate) (3rd Mate) (3rd Mate) 9 GA2 SMP SDA_B SCL_B SCL_A

Pin Description PP_x Payload Power (12V) for AMC/MCH/CU x MP_x Mgmt Power (3.3V) for AMC/MCH/CU x GND **Output Return** PS PM# Last Mate Pin GAx Geographical address line x PM Present and OK [Output] PM_OK# PMP_x# PM x Present and OK [Input] RST_PM_IN# Resets PM EMMC [Input] RST_PM_x# Reset signal from PM x [Output] PWR_ON_Mx Power-On signal from MCH x Detects Presence of AMC/MCH/CU x Enables (E)MMC of AMC/MCH/CU x I2C Clock Line for Bus x I2C Date Line for Bus x

EN_CU1#

(3rd Mate)

EN 1#

(3rd Mate)

EN 3#

(3rd Mate)

EN_5#

(3rd Mate)

EN 7#

(3rd Mate)

EN 9#

(3rd Mate)

EN_11#

(3rd Mate)

EN CU2#

(3rd Mate)

SDA A

(3rd Mate)

F

MP_M1#

(3rd Mate)

MP 2#

(3rd Mate)

MP 4#

(3rd Mate)

MP_6#

(3rd Mate)

MP 8#

(3rd Mate)

MP 10#

(3rd Mate)

MP_12#

(3rd Mate)

MP M2#

(3rd Mate)

PWR_ON_M2

(3rd Mate)

G

MP_CU1#

(3rd Mate)

MP 1#

(3rd Mate)

MP 3#

(3rd Mate)

MP 5#

(3rd Mate)

MP 7#

(3rd Mate)

MP 9#

(3rd Mate)

MP_11#

(3rd Mate)

MP CU2#

(3rd Mate)

PWR_ON_M2

(3rd Mate)

н

(3rd Mate)

B

(3rd Mate)

С

(3rd Mate)

D

(3rd Mate)

Ε

(3rd Mate)

Α

Mechanical Specifications

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MTC600-48



MTC600-AC





Ordering Information

	Power Level	Input Voltage	Redundant	Channel Count	Width	Height	Reserved
MTC	ppp -	- vv	rr	nn	W	h	xx J
	600 = 600 W	48 = -48 Vdc AC = 90-264 Vac	RR = Redundant Input and Redundant Output NR = Non- Redundant Input and Redundant Output	16 = 16ch	S = Single Width	9 = 9 HP 1 = 12 HP	For modified standards

MTC600-48RR16S9

600 W, -48 Vin, Redundant I/P, Redundant O/P, 16 channel, SW 9 HP

MTC600-ACNR16S1J

600 W, AC-in, Non-Redundant I/P, Redundant O/P, 16 channel, SW 12 HP

Americas

5810 Van Allen Way Carlsbad, CA 92008 USA Telephone: +1 760 930 4600 Facsimile: +1 760 930 0698 Rev. 05.26.08 MTC600 Series

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Europe (UK)

Waterfront Business Park Merry Hill, Dudley West Midlands, DY5 1LX United Kingdom Telephone: +44 (0) 1384 842 211 Facsimile: +44 (0) 1384 843 355

Asia (HK)

16th - 17th Floors, Lu Plaza 2 Wing Yip Street, Kwun Tong Kowloon, Hong Kong Telephone: +852 2176 3333 Facsimile: +852 2176 3888

For global contact, visit:

www.astecpower.com

www.artesyn.com technicalsupport@astec.com

technicalsupport@artesyn.com

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Printed in U.S.A. Issue SF3

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