

# Fast Settling Video Operational Amplifiers

## HOS-050/HOS-050A/HOS-050C

**FEATURES** 

80ns Settling to 0.1%; 200ns to 0.01% 100MHz Gain Bandwidth Product 55MHz 3dB Bandwidth 100mA Output @ ±10V

APPLICATIONS
D/A Current Converter
Video Pulse Amplifier
CRT Deflection Amplifier
Wideband Current Booster

GENERAL DESCRIPTION

The HOS-050, HOS-050A, and HOS-050C on amps are very high speed wideband operational amplifiers designed to complement the Analog Devices' lines of high speed data acquisition products. They feature a 100MHz gain bandwidth product; slew rate of  $300V/\mu s$ ; and settling time of 80ns to  $\pm 0.1\%$ .

The HOS-050A, HOS-050, and HOS-050C have typical input offset voltages of 10mV, 25mV, and 45mV, respectively.

All models have a rated output of  $\pm 100 mA$  minimum, and an exceptional noise spec of only  $7 \mu V$  rms, dc to 2 MHz; they are ideally suited for a broad range of video applications.

### **FAST-SETTLING OP AMPS**

At one time, operational amplifiers could be specified according slew rates, bandwidth, and drive capability; and these paramers would be sufficient. Settling time was not considered until the use of high speed video D/A converters became widespread.

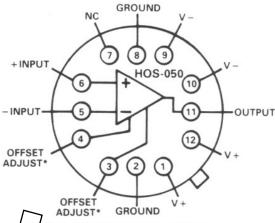
he conversion speed of the D/A can be limited by the settling me of the output amplifier, so it has become essential to select an op amp whose settling time is compatible with the D/A converter.

The increased emphasis on settling time has, in some cases, created a preoccupation with slew rates in the minds of some designers. But slew rate is only one component in establishing settling time.

The amount of overshoot, and the ringing which are present at the end of a step function change also have an effect. These parameters, in turn, are influenced by the bandwidth (or lack of it) when operating the op amp with closed loop gains greater than one.

(continued after Specifications)

HOS-050/A/C PIN DESIGNATIONS TO-8 PACKAGE



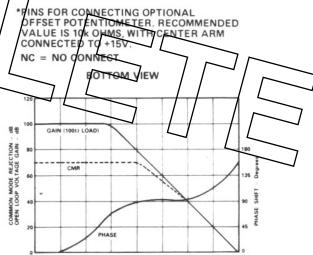


Figure 1. HOS-050 Frequency Response

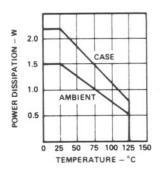


Figure 2. Power Dissipation vs. Temperature

4

Model		HOS-05	60			HOS-0	50A			HOS-	050C
ABSOLUTE MAXIMUM RATING Supply Voltages (V <sub>S</sub> ) Power Dissipation Input Voltage Differential Input Voltage Operating Temperature Range (ca Junction Temperature Storage Temperature Range Lead Temperature (soldering, 10 se	ise)	175°C	o + 125°C			* * * * * * * *	0 "			* * * * - 25°( * *	C to +85°C
DC ELECTRICAL CHARACTER	RISTICS										
Parameter	Conditions	Min	Тур	Max	Min	Тур	Max	Min	Тур	Max	Units
Open Loop Gain Rated Output Voltage Current (not short circuit protected)	$R_{L} = 100\Omega$ $R_{L} = >100\Omega$ $R_{L} = >100\Omega$	+ 10/ - 3	100 8 ± 100		*	*		*	*		dB V mA
Voltage Input Offset Voltage	$R_{L} = >200\Omega$ Adjustable to Zero	± 10			*			*			V
Initial vs. Femperature vs. Power Supply Voltage	@ +25°C		25 50 0.5	35 150		10 20 *	15 35		45 75 *	65 200	mV μV/°C mV/V
Input Bia Current Initial vs. Temperature Input Offset Jurrent	) + 25°C		l Double	2 es		*	*		*	*	nA /10°C
Imput Impedance Differential Common Mode	In parallel with 5pF		± 100	7	\ 	*			* *		pA Ω Ω
Input Voltage Range Common Mode Differential Common Mode Rejection		±10	// /o [	± 18 ± 18	• / ,		][ 7	7 /	$\supset$	*	V V
Input Noise dc to 100kHz dc to 2MHz	$R_{\rm FF} = 100\Omega; R_{\rm FB} = 1k\Omega$		5 7		L_	<i></i>	- 7 1		:/		μV rm:
AC ELECTRICAL CHARACTER	RISTICS1						L	$\int$			
Parameter	Conditions	Min	Тур	Max	Min	Тур	Max	Min	Typ	Max	Units
Slew Rate	$A = -1; R_{FF} = R_{FB} = 500\Omega;$ $Load = 100\Omega$		300			*			*		Vμs
Noninverting Slew Rate	$A = 2; R_{FF} = R_{FB} = 1000\Omega;$ Load = 1000		320			*					Vμs
Overload Recovery	50% Overdrive		400			*			*		ns
Unity Gain Bandwidth Product Small Signal Bandwidth, - 3dB	$R_{FF} = R_{FB} = 500\Omega$ $A = -1; R_{FF} = R_{FB} = 500\Omega$		100 45						*		MHz
oman orginal bandwidth, - odb	$A = -1; R_{FF} = R_{FB} = 1000\Omega$		35			*			*		MHz MHz
	$A = -2$ ; $R_{FF} = 500\Omega$ ; $R_{FB} = 1000\Omega$ $A = -4$ ; $R_{FF} = 250\Omega$ ;		35		,				*		MHz
	$R_{FB} = 1000\Omega$		30			*			*		MHz
Output Impedance Noninverting Bandwidth, - 3dB	$A = 2$ ; $R_{FF} = R_{FB} = 1000\Omega$ ; $100\Omega \log 10$ load; $10$ pF capacitance			<1			*			*	Ω
	5-volt p-p output 4-volt p-p output 2-volt p-p output $A = 3$ ; $R_{FB} = 500\Omega$ ; $R_{FB} = 1000\Omega$ ; $100\Omega$ , $1000\Omega$ , or $2000\Omega$ load; $10pF$		25 30 55			*			* * *		MHz MHz MHz
	capacitance 10-volt p-p output 5-volt p-p output		17 25								MHz MHz

$ \begin{array}{c} \text{or 2000}\Omega \text{load} \\ \text{capacitance} \\ \text{5-volt p-p} \\ \text{4-volt p-p} \\ \text{2-volt p-p} \\ \text{1-volt p-p} \\ \text{2-volt p-p} \\ \text{1-volt p-p} \\ \text{Output} = \pm \\ \text{R}_1 = 1000 \\ \text{Settling Time to } 0.1^{\circ}_{\circ} \\ \text{Inverting} \\ \text{(See Figure 5)} \\ \text{Noninverting} \\ \text{Harmonic Distortion} \\ \text{(See Figure 9)} \\ \text{Noninverting Harmonic} \\ \text{Distortion (See Figure 40)} \\ \end{array} $	$\Omega;100\Omega,1000\Omega,$ $d/10pF$ output output output output $5V;A=-1;$ $\Omega$ $EF=R_{EB}=500\Omega$ $\pm 5V$	15 30 40 40 20 100 80	Max Min	Typ	Max Min	Typ	Max	MHz MHz MHz MHz MHz
$\begin{array}{c} \text{(continued)} & R_{FB} = 20000\\ \text{or } 2000\Omega \Omega \text{load}\\ \text{capacitance} \\ 5\text{-volt p-p} \\ 4\text{-volt p-p} \\ 2\text{-volt p-p} \\ 4\text{-volt p-p} \\ 2\text{-volt p-p} \\ 1\text{-volt p-p} \\ 2\text{-volt p-p} \\ 2\text{-volt p-p} \\ 1\text{-volt p-p} \\ 2\text{-volt p-p}$	Ω; 100Ω, 1000Ω, d/10pF  output output output output 55V; A = -1; Ω FF = R <sub>FB</sub> = 500Ω ± 5V ± 2.5V = R <sub>FB</sub> = 500Ω	30 40 40 20		:		:		MHz MHz MHz
Full Power Bandwidth  (- 3dB) Settling Time to 0.1% Inverting (See Figure 5) Noninverting  Harmonic Distortion (See Figure 9) Noninverting Harmonic Distortion (See Figure 0)  Power Supply Voltage Voltage Current Power Consumption Power Dissipation  Temperature Range	output output output output output osty; A = -1; Ω FF = R <sub>FB</sub> = 500Ω ± 5V ± 2.5V = R <sub>FB</sub> = 500Ω	30 40 40 20		:		:		MHz MHz MHz
Full Power Bandwidth  (- 3dB) Settling Time to 0.1% Inverting (See Figure 5) Noninverting  Harmonic Distortion (See Figure 9) Noninverting Harmonic Distortion (See Figure 0)  Power Supply Voltage Voltage Current Power Consumption Power Dissipation  Temperature Range	output output output output output osty; A = -1; Ω FF = R <sub>FB</sub> = 500Ω ± 5V ± 2.5V = R <sub>FB</sub> = 500Ω	30 40 40 20		:		:		MHz MHz MHz
S-volt p-p   4-volt p-p   2-volt p-p   1-volt p-p   2-volt p-p   1-volt p-p   1-v	output output output :5V; A = -1; Ω £-F- = R <sub>FB</sub> = 500Ω £-5V £-2.5V = R <sub>FB</sub> = 500Ω	30 40 40 20		:		:		MHz MHz MHz
5-volt p-p 4-volt p-p 2-volt p-p 1-volt p-p	output output output :5V; A = -1; Ω £-F- = R <sub>FB</sub> = 500Ω £-5V £-2.5V = R <sub>FB</sub> = 500Ω	30 40 40 20		:		:		MHz MHz MHz
Full Power Bandwidth  (-3dB) Settling Time to 0.1% Inverting (See Figure 5) Noninverting  Harmonic Distortion (See Figure 9) Noninverting Harmonic Distortion (See Figure 0)  Power Supply Vottage Vottage Vottage Current Power Consumption Power Dissipation  Temperature Range	output output output :5V; A = -1; Ω £-F- = R <sub>FB</sub> = 500Ω £-5V £-2.5V = R <sub>FB</sub> = 500Ω	30 40 40 20		:		:		MHz MHz
Full Power Bandwidth  (-3dB)  Settling Time to 0.1%  Inverting  (See Figure 5)  Noninverting  Harmonic Distortion (See Figure 9)  Noninverting Harmonic Distortion (See Figure 0)  Power Supply Voltage Voltage Voltage Current Power Consumption Power Dissipation  Temperature Range	output output :5V; A = -1; Ω ± FF = R <sub>FB</sub> = 500Ω ± 5V ± 2.5V = R <sub>FB</sub> = 500Ω	40 40 20 100		:		:		MHz MHz
Full Power Bandwidth  (-3dB)  Settling Time to 0.1%  Inverting  (See Figure 5)  Noninverting  Harmonic Distortion (See Figure 9)  Noninverting Flamonic Distortion (See Figure 0)  Power Supply Voltage Voltage Current Power Consumption Power Dissipation  Temperature Range	output :5V; A = -1; Ω :EF = R <sub>FB</sub> = 500Ω ±5V ±2.5V = R <sub>FB</sub> = 500Ω	40 20 100						MHz
Full Power Bandwidth $(-3dB)$ Settling Time to $0.1\%$ Inverting $(See Figure 5)$ Noninverting  Harmonic Distortion $(See Figure 9)$ Noninverting Flatmonic Distortion (See Figure 0)  Power Supply Voltage Voltage Current Power Consumption Power Dissipation  Temperature Range	$\Omega$ $\Omega$ $\Omega$ $\Delta$ $\Delta$ $\Delta$ $\Delta$ $\Delta$ $\Delta$ $\Delta$ $\Delta$	20 100						
$ \begin{array}{c} (-3dB) \\ \text{Settling Time to } 0.1\% \\ \text{Inverting} \\ \text{(See Figure 5)} \\ \text{Noninverting} \\ \end{array} \begin{array}{c} R_1 = 1000 \\ A = -1; R_1 \\ V_{\text{OUT}} = 2 \\ V_{\text{OUT}} = 3 \\ V_{\text{OUT}} = 3 \\ V_{\text{OUT}} = 2 \\ V_{\text{OUT}}$	$\Omega = R_{FB} = 500\Omega = \pm 5V = 2.5V = R_{FB} = 500\Omega$	100						MHz
Settling Time to 0.1%  Inverting  (See Figure 5)  Noninverting  Harmonic Distortion (See Figure 9)  Noninverting Harmonic Distortion (See Figure 10)  Power Supply Voltage Voltage Voltage Voltage Current Power Consumption Power Dissipation  Temperature Range  A = -1; R <sub>1</sub> Voltage at 2; R <sub>1-1</sub> Max Load ca Voltage at 2; R <sub>1-1</sub> Load 10 Signal = 0  Rated performance at 2	± 5V ± 2.5V = R <sub>FB</sub> = 500Ω	100						
Inverting  (See Figure 5) Noninverting  Wout = 3 Vott = 3	± 5V ± 2.5V = R <sub>FB</sub> = 500Ω					*		
(See Figure 5) Noninverting  Vott = 3 A = 2; R <sub>EE</sub> Max Load ca Vott = 3 Vot	± 2.5V = R <sub>I-B</sub> = 500Ω				- 1			ns
Noninverting  A = 2; R <sub>H</sub> -Max Load ca  V <sub>OUT</sub> = 3  A = -1; Load = 1  Signal = 4  Power Supply  Voltage  Voltage  Voltage  Voltage  Current  Power Consumption  Power Dissipation  Temperature Range	- R <sub>I-B</sub> - 500Ω	80		*				ns
Harmonic Distortion (See Figure 9) Noninverting Harmonic Distortion (See Figure 0)  Power Supply Voltage Voltage Current Power Consumption Power Dissipation  Temperature Range  Max Load ea  Vott = 3  Vott = 3  A = -1; Lo  Signal = 4  A = 2; R <sub>1-</sub> = 1  Load = 1  Signal = 1  Rated perfor Operating a  Quiescent Quiescent								11.5
Harmonic Distortion (See Figure 9) Noninverting Harmonic Distortion (See Figure 0)  Power Supply Voltage Voltage Current Power Consumption Power Dissipation  Temperature Range  Vott = 2 Vott = 3 Vott =					1			
Harmonic Distortion (See Figure 9) Noninverting Harmonic Distortion (See Figure 0)  Power Supply Voltage Voltage Current Power Consumption Power Dissipation  Temperature Range  Voltage Voltage Quiescent Voltage Quiescent Quiescent		200						ns
Harmonic Distortion (See Figure 9) Noninverting Harmonic Distortion (See Figure 10)  Power Supply Voltage Voltage Voltage Current Power Consumption Power Dissipation  Temperature Range  A = -1; Lo Signal = 4 A = 2; R <sub>FF</sub> Load = 10 Signal = 9 Operating and Operating an		135	1					ns
(See Figure 9)  Noninverting Harmonic Distortion (See Figure 10)  Power Supply Voltage Voltage Current Power Consumption Power Dissipation  Temperature Range		133						lis .
Noninvertine Harsonic Distortion (See Figure 0)  Power Supply Voltage Voltage Current Power Consumption Power Dissipation  Temperature Range		63						dB
Power Supply Voltage Voltage Current Power Consumption Power Dissipation Temperature Range	· · · · · · · · · · · · · · · · · · ·	0.3						db db
Power Supply Voltage Voltage Current Power Consumption Power Dissipation Temperature Range								
Power Supply Voltage Voltage Current Power Consumption Power Dissipation Temperature Range		50						dB
Voltage Voltage Current Power Consumption Power Dissipation Temperature Range  Rated perform Operating a Quiescent Quiescent	4MHz; 2V output	- 59	- 1	-	1			db db
Vollage Current Power Consumption Power Dissipation Temperature Range								
Voltage Current Power Consumption Power Dissipation Temperature Range	marce (	± 15	1	*		*		V dc
Power Consumption Power Dissipation Temperature Range		2 ±	± 18   *		*   *		*	Vdc
Power Dissipation Temperature Range		20 \ ±	± 25	*	*	*	*	mA
Temperature Range		0.6	/ 1 /	*		*		W.
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Package Option <sup>2</sup>				-	$\overline{}$	//	/	
TO-8 (H-12A)		HOS-050	- 1	HOS-050A	<u> </u>	HOS-050	c /	<u> </u>
							-	
NOTES *Specification same as HOS-050						7	1 4	_
Specification for Inverting Mode unless otherwise noted.								
See Section 16 for package outline information.								/

#### PIN DESIGNATIONS

PINS	FUNCTION
1	+ V
2	GROUND
3	OFFSET ADJ
4	OFFSET ADJ
5	- INPUT
6	+ INPUT
7	NC
8	GROUND
9	- V
10	- V
11	OUTPUT
12	+ V

<sup>\*</sup>PINS FOR CONNECTING OPTIONAL OFFSET POTENTIOMETER. RECOMMENDED VALUE IS 10k OHMS, WITH CENTER ARM CONNECTED TO +15V.

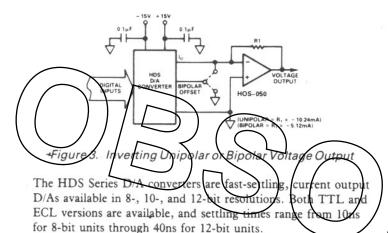
Individual socket assemblies (one per pin) are available from AMP as part number 6-330808-0. Specifications subject to change without notice.

The HOS-050 Series stands up under close scrutiny of these characteristics because of its 100MHz gain bandwidth product. The use of these amplifiers in a wide variety of applications has confirmed their suitability for video circuits.

### **VOLTAGE AMPLIFIERS/CURRENT BOOSTERS**

Video op amps such as the HOS-050 are generally characterized by high gain bandwidth products, fast settling times, and high output drive.

One of the most common uses of video op amps is for D/A converter output voltage amplification or current boosting. Figure 3 is one example of this type of application. In this circuit, the internal resistance of the D/A is the feed forward resistor for the op amp.



The circuit which is shown will provide a negative unipolar output with binary coding on the input, and bipolar offset grounded. It will provide a bipolar output with complementary offset binary coding on the input, and bipolar offset connected to Io.

An approximation of the total settling time for the D/A op amp combination is calculated by:

$$T_S = \sqrt{T_D^2 + T_O^2}$$

 $T_S = \sqrt{T_D{}^2 + \, T_O{}^2}$  where  $T_D$  is D/A settling time and  $T_O$  is HOS-050 settling time.

This approximation is valid because both the D/A and the HOS-050 exhibit 6dB/octave roll-off charateristics (single pole response); and the combination of low D/A output capacitance and op amp input capacitance does not materially affect the formula.

The user of the HOS-050 should remember the current flowing in the feedback resistor (R1) must be subtracted from the output available from the HOS-050.

There is a tendency, because of this fact, to use a high value of feedback resistor to assure maximum current drive being available for driving low impedances; but this approach may create undesirable side effects.

Calculating the minimum load that can be driven under two conditions of feedback resistor values will serve to illustrate the difference.

Assume the feedback resistor value is  $500\Omega$ . If output voltage of the HOS-050 is 10 volts, and output current is 100mA, minimum load would be:

$$\frac{E_O~max}{I_O~max~-~I_{RFB}} = \frac{10V}{100mA~-~20mA} = \frac{10V}{80mA} = ~125\Omega~minimum~load$$

where: Eo max = peak voltage needed

I<sub>O</sub> max = maximum continuous current HOS-050 can produce

I<sub>RFB</sub> = current in feedback resistor at peak voltage

Assume the feedback resistor value is 5,0000. Minimum load would be:

$$\frac{E_O \; max}{I_O \; max \; - \; I_{RFB}} \; = \; \frac{10V}{100mA \; - \; 2mA} \; = \; \frac{10V}{98mA} \; = \; 102\Omega \; \, minimum \; load \;$$

Designs which strive for driving a minimum load (by increasing the feedback resistor) can create settling problems because of a fundamental characteristic of op amp circuits . . . the higher the feedback resistance, the slower the system response.

This phenomenon is the result of increased impedance for driving stray capacitances in the circuit employing the op amp, and fixed capacitances in the summing node.

Impedances need to be kept as low as possible consistent with low distortion; and stray capacitances need to be eliminated to the maximum possible extent. A large ground plane structure is recommended to help assure low ground impedances. In addition, 0.1μF ceramic capacitors and 3-10μF tantalum capacitors connected as close as possible to power supply inputs will decrease the potential for parasitic oscillations and other noise signals.

Another argument for limiting the size of the feedback resistor is because of its effect on bandwidth. Bandwidth of the HOS-050 op amp and the value of the feedback resistor are inversely related.

any given gain of the op anp, the gain setting with the widest bandwidth will be the one which employs the lower value of feedback. As an example, a gain of 1 can be achieved with RFF  $R_{FB} = 500\Omega$  or  $R_{FF} = R_{FB} = 1,000\Omega$ . Small-signal bandwidth combination is typically 45MHz, bandwidth for the second is typically 35MHz.

OFFSET AND GAIN ADJUSTMENT

Figure 4 shows a method of using the HOS-050 op amp which allows adjusting the offset and gain of the output voltage.

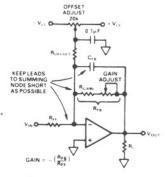


Figure 4. HOS-050 Offset and Gain Adjust

As shown, the gain of the circuit is established by the equation:

$$G = -\left(\frac{R_{FB}}{R_{FF}}\right)$$

where RFB is the total of RGAIN and Gain Adjust.

Once the user has established the desired gain for the illustrated circuit, the value of RFB can be used to determine the correct value of ROFFSET with the equation:

$$R_{OFFSET} = -\left(\frac{V_{CC} \times R_{FB}}{\Delta E_{O}}\right)$$

where  $\Delta E_O$  is the desired amount of offset on the output.

Assume  $\pm V_{CC} = \pm 15V$ ;  $R_{GAIN} = 900\Omega$ ; Gain Adjust = 100 $\Omega$ ; the desired change on the output =  $\pm 1$  volt.

Under these conditions, ROFFSET will be 15ku:

$$R_{OFFSET} = -\left(\frac{15V \times [900 + 100]}{1V}\right)$$

$$R_{OFFSET} = -\left(\frac{15kV}{1V}\right)$$

 $R_{OFFSET} = 15,000\Omega$ 

Figure 4 shows bipolar output operation. If unipolar output is desired, the appropriate  $V_{\rm CC}$  should be removed from the Offset Adjust potentiometer.

The  $0.1\mu F$  capacitor attached to the wiper arm of the Offset Adjust control isolates the control and helps prevent adjustment noise from appearing on the output of the HOS-050.

C<sub>I-B</sub> can be any value between 0 and 20pF, depending on the value of R<sub>OAIN</sub>, and should be selected to optimize settling time for the particular circuit layout in which the HOS-050 is being used.

The Cain Adjust control should be a low value low inductance cermet rimming potentiometer.

Note: R<sub>FF</sub>, R<sub>GAIN</sub>, C<sub>Fk</sub> and R<sub>OFFSET</sub> must be losated as close to the summing node of the HOS 050 as physically possible. This helps prevent additional capacitance in the summing rode and corresponding bad effects on frequency response and settling times.

Variable controls (such as Offset Adjust and Gain Adjust) should never be tied to the summing node of the op amp. Their correct electrical locations are those shown in Figure 4.

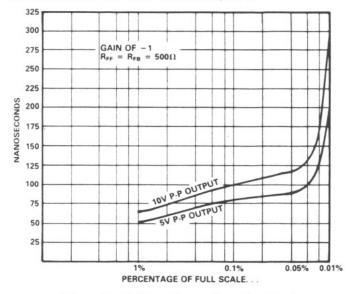


Figure 5. Settling Time - Inverting Mode

#### SETTLING TIME MEASUREMENT

Although there are some exceptions, most members of industry are in agreement on the description which says settling time is:

The interval of time from the application of an ideal step function input until the closed-loop amplifier output has entered and remains within a specified error band.

The well-informed user needs to be alert to the consequences of settling time specs which do not meet that description.

This definition encompasses the major components which comprise

settling time. They include (1) propogation delay through the amplifier; (2) slewing time to approach the final output value; (3) the time of recovery from the overload associated with slewing; and (4) linear settling to within the specified error band.

Expressed in these terms, the measurement of settling time is obviously a challenge and needs to be done accurately to assure the user that the amplifier is worth consideration for his application.

Figure 6 is the test circuit for measuring settling time to 0.1%. This method creates a "false" summing junction and the error band is observed at that point.

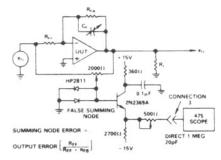


Figure 6. Settling Time Test Circuit for 0.1% Settling one were to attempt the measurement at the "true" summing function of the op amp, the results would be misleading. All scope probes will add capacitance to the input and will change the response of the system. Making the measurement at the output of the amplifier is also impractical, since scope nonlinearities and reading inaccuracies caused by overdriving the scope preclude accurate measurements to the tolerances which are required.

The false summing junction method causes the amplifier to subtract the output from the input; only one-half the actual error appears at the false junction, and it can be measured to the required accuracies.

The false junction is clamped with diodes to limit the voltage excursion appearing at that point. This is necessary because the amplifier will be overdriven and one-half its input voltage will appear at the junction. Without the clamps, the scope used for making the measurement would be overdriven and its recovery time would mask the settling time of the amplifier.

The test circuit for measuring settling time to 0.01%, Figure 7, is simply an extension of the same basic technique. Measuring to the closer tolerance requires additional gain in the circuit driving the oscilloscope.

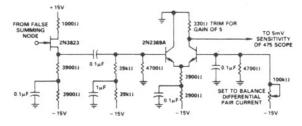


Figure 7. Settling Time Test Circuit for 0.01% Settling

#### IMPEDANCE MATCHING

The characteristics of the HOS-050 operational amplifier make it an ideal choice for matching the impedances of video circuits to the impedances of transmission lines.

In this application, source and load terminating resistors will cause the output voltage to be halved at the end of the cable being driven by the op amp. This makes it necessary to set the gain of the circuit to provide twice the desired voltage.

Three different values of resistors and cables are "phantomed" into the figure as examples of possible characteristic impedances which might be used. Figure 8 is *not* meant to imply the HOS-050 can drive three cables simultaneously.

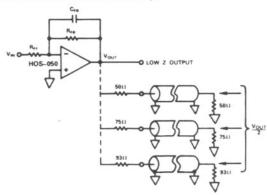


Figure 8. HOS-050 Impedance Matching

NONINVERTING OPERATION

The vast majority of video operational amplifiers display marked differences in settling times and bandwidths when operated in a noninverting mode instead of the inverting mode. There are a number of valid reasons for this characteristic.

Most high-speed op amps use feet forward compensation for optimizing performance in the inverting mode. This is necessary to obtain wide gain-bandwidth products while maintaining dc performance in these types of devices. In effect, the optimization a wideband ac channel which is not perfectly matched to the dechannel.

Feed-forward techniques enhance the performance of the op amp in the inverting mode by incresing the slew rate and smallsignal bandwidth. These techniques, however, also decrease the amplifier's tolerance to stray capacitances, so must be employed judiciously.

The overall input capacitance of the op amp is kept as low as possible in the design; and any mismatch in the capacitance of the two channels appears as an error in the output. Because of the inherently low total input capacitance of the op amp, even a small capacitive mismatch between channels shows up as a large effective error signal.

Decreasing the channel mismatch can be achieved only by complicating the design of the op amp with additional components, and rigorous selection of those components in the manufacturing process.

As a consequence, the mismatch is reduced to the smallest practical value consistent with the economics of producing and using the op amp. But it remains a mismatch, and manifests itself as a difference in performance in the inverting versus noninverting modes.

There are video op amps available at low cost which use a 741-type amplifier for high dc open loop gain in the noninverting channel. The user of these kinds of designs may sometimes gain an economic advantage, but at a high cost in performance. Bandwidths for noninverting applications are often measured in kHz, not MHz, for this approach.

A video op amp is acting as a voltage mode device at both inputs when operating in the noninverting mode. This contrasts with the inverting mode, where it is operating as a current mode device.

The Analog Devices HOS-050 has different performance characteristics when operating as a noninverting amplifier, but the care used in the design makes the differences less pronounced than they are in many competing units.

The HOS-050 can be considered a true differential video op amp. It requires little or no external compensation because its rolloff characteristics approach a 6dB/octave slope. This helps the user determine summing errors and loop response; and helps assure the stability of the system.

The performance parameters for both inverting and noninverting operation are shown elsewhere in this data sheet (see SPECIFI-CATIONS section and figures). A comparison of the characteristics will highlight the similarities in performance, with the exceptions noted above.

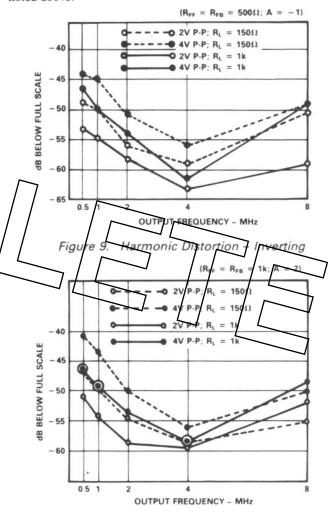


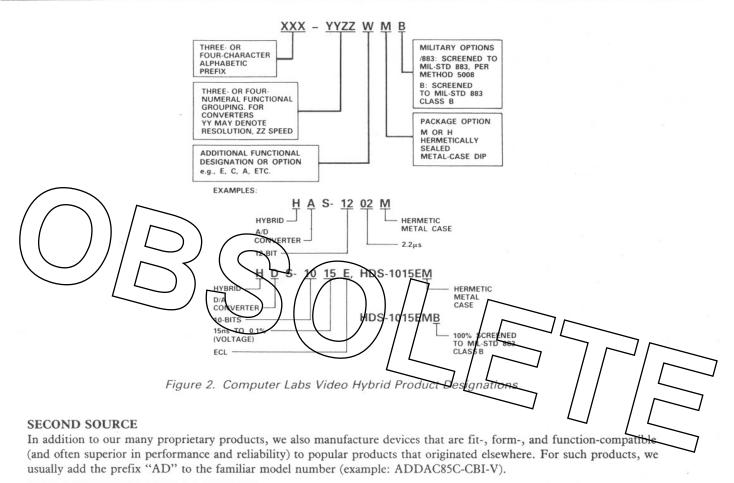
Figure 10. Harmonic Distortion - Noninverting

#### IN SUMMARY . . . A CAVEAT

Settling time specifications, bandwidth capabilities, harmonic distortion performance, and other parameters for video op amps cannot possibly include all possible situations and applications.

A multitude of seemingly insignificant conditions can have a major impact on the unit and its ability to operate in any given circuit.

The potential user is strongly urged to evaluate the effectiveness of the HOS-050 in the actual circuit in which it will be used. In many instances, the application conditions are different from the conditions used in specifying; there is no substitute for a trial in the proposed circuit to determine if the op amp will provide the desired results.



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