Legerity

# Subscriber Line Interface Circuit Le79555 Device 

## APPLICATIONS

## Ideal for high-density, low-power linecard applications <br> FEATURES

- Control states: Active, Reverse Polarity, Tip Open, Ringing, Standby, and Open Circuit
- Low standby power
- -40 to -58 V battery operation
- On-hook transmission
- Two-wire impedance set by single external impedance
- Programmable constant-current feed
- Low Off-Hook Active Overhead Voltage
- Programmable loop-detect threshold
- Ground-start detector
- Programmable ring-trip detect threshold
- No -5 V supply required
- Three on-chip relay drivers and relay snubbers, one ringing and two general purpose
- Tip Open state for ground-start lines
- On-chip switching regulator for Low power dissipation
- Supports 30 mA for Active Normal and Reverse Polarity operation.


## RELATED LITERATURE

- 080284 Introduction to the SLIC Product Family
- 080125 SLIC Switcher Circuit Application Note
- 080725 Le79555 Switching Regulator Applications Update
■ 080753 Le58QL02/021/031 QLSLAC Data Sheet
- 080754 Le58QL061/063 QLSLAC Data Sheet
- Evaluation Board Schematic available upon request


## ORDERING INFORMATION

| Device | Performance Grade/Package |
| :--- | :--- |
| Le79555-1VC | 52 dB Pol. Rev., 44-pin TQFP |
| Le79555-1QC* | 52 dB Pol. Rev., 32-pin QFN |
| Le79555-2VC | 63 dB Pol. Rev., 44-pin TQFP |
| Le79555-2QC* | 63 dB Pol. Rev., 32-pin QFN |
| Le79555-3VC | 52 dB No Pol. Rev., 44-pin TQFP |
| Le79555-3QC* | 52 dB No Pol. Rev., 32-pin QFN |
| Le79555-4VC | 63 dB No Pol. Rev., 44-pin TQFP |
| Le79555-4QC* | 63 dB No Pol. Rev., 32-pin QFN |

## *Note:

Due to size constraints, QFN devices are marked by omitting the "Le" prefix and the performance grade dash character. For example, Le79555-2QC is marked 795552QC.

## DESCRIPTION

The Le79555 device was designed for high-density POTS applications requiring a power saving, small footprint SLIC device. The new SLIC device fulfills today's requirements for POTS linecard markets that require a balance of highperformance and cost-effective silicon components. The Le79555 device delivers economical linecard solutions by offering power and space savings to linecard designers. The on-chip switching regulator allows for power dissipation to be minimized for the entire system. Another benefit is that the device is offered in a reduced footprint package type, a 44-pin TQFP. This small footprint allows designers to save board space, thus increasing the density or number of lines on the board.

Legerity offers a range of compatible SLAC devices providing a complete line circuit that can be optimized for varying requirements. The SLIC device is designed to operate with a range of SLAC devices from low cost, non-programmable to more advanced, highly programmable options viable for a range of applications.

## BLOCK DIAGRAM



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## PRODUCT DESCRIPTION

The Le79555 device is designed for short loop and long loop high-density POTS applications requiring a power saving, small footprint SLIC. The Le79555 device boasts increased power savings over Legerity's other POTS solutions by using an internal switching regulator for each channel to enhance system power management. The switching regulator eliminates the need for a second voltage supply, commonly required for SLIC devices in POTS applications. Such elimination passes on board space and cost savings to the designers. Thus, the smaller footprint and added features of the Le79555 device allows customers to amortize the cost of common hardware across more channels and increase the line density per board. Additionally, the Le79555 device gives linecard designers a simple control interface that supports six control states: Active, Ringing, Standby, Disconnect, Reverse Polarity, and Tip Open. The Le79555 device is a low cost, high performance device providing key features required for POTS markets worldwide, including: low power dissipation and ground key detection, as well as all of the features offered currently by Legerity's Transformer SLIC family, Am7920/22.

## BLOCK DESCRIPTIONS

## Two-Wire Interface

The two-wire interface provides DC current and sends voice signals to a telephone apparatus connected to the line card with a two-wire line. The two-wire interface also receives the returning voice signals from the telephone.

## Ground Detector

The ground detector block performs ground start and ground key detection, as well as automatically detects a ring-ground fault. Therefore, when the longitudinal current is greater than the ground key detector threshold, IGK, in either Active, Standby, or Tip Open, the $\overline{D E T}$ will go low. Note that when the device is in Active or Standby, $\overline{\mathrm{DET}}$ may be an indication of off-hook, ground fault, or both.

## Signal Transmission

The RSN input current controls the receive current sent to the two-wire interface. The AC line voltage is sensed by differential amplifiers between the A and HPA leads, and between HPB and B leads. The outputs of these amplifiers are equal to the AC metallic components of the line voltages. The transmission circuit also contains a longitudinal feedback circuit to shunt longitudinal signals to a DC bias voltage. The longitudinal feedback does not affect metallic signals.

## Power Feed Controller

The power feed controller has three sections: (1) the battery feed circuit, (2) the reverse polarity circuit, and (3) the bias circuit. The battery feed circuit regulates the amount of DC current and voltage supplied to the telephone over a wide range of loop resistance. The reverse polarity circuit provides the capability to reverse the loop current for pay telephone key pad disable and other applications. The bias circuit provides a reference voltage, which is offset from the subscriber line voltage. The reference voltage controls the switched mode regulator, which minimizes SLIC power consumption by providing the minimum supply voltage needed by the line drivers for proper operation.

## Switching Regulator

A switching regulator function is implemented on the chip with a few external components. The power feed controller generates a reference voltage which is the minimum voltage required to feed the output line amplifiers. The efficiency of the switching regulator ( $>80 \%$ ) minimizes both the on-chip power dissipation and the system power dissipation. This is particularly important for short loops operating at high currents which otherwise cause high power dissipation.

## Input Decoder and Control

The input decoder and control block provides a means for a microprocessor or SLAC IC to control such system functions as line activate, on-hook transmission, ringing, and reverse polarity. The input decoder and control block has TTL-compatible inputs, which set the operating states of the SLIC. It also provides the supervision signal sent back to the controller.

## Off-Hook Detector

The most important loop monitoring function is off-hook detection. The two-wire interface produces a current equal in magnitude to the loop current divided by a constant, and sends it out on the RD pin. An external resistor and capacitor (RD and CD) connect the RD pin to ground. The value of the voltage across resistor $R_{D}$ is proportional to the current leaving the $R D$ pin times the value of $R_{D}$. The $\overline{D E T}$ pin will show a logic Low when this voltage rises above a threshold.

## (Le) (Lity:

## Ring-Trip Detector

During the Ringing state, the DA pin is more positive than the DB pin, and the $\overline{\mathrm{DET}}$ pin will show high to indicate the on hook. When an off hook condition occurs, the DB pin becomes more positive than the DA pin, and the DET pin will go low to indicate an off-hook.

## Ring Relay Driver

The ring relay driver is active only in the Ringing state.

## Relay Driver

A relay driver is activated by logic Low at either input pin, D1, or D2. D1 controls relay driver RYOUT1; D2 controls relay driver RYOUT2.

## CONNECTION DIAGRAMS



## Note:

1. Pin $\mathbf{1}$ is marked for orientation.
2. $N / C=$ No Connect
3. $R S V D=$ Reserved
4. There is VBAT potential on the exposed pad. Do not connect to GND pin.

PIN DESCRIPTIONS

| Pin Name | Type | Description |
| :---: | :---: | :---: |
| AGND/ DGND | Ground | Analog and digital ground. |
| A(TIP) | Output | Output of A(TIP) power amplifier. |
| BGND | Ground | Battery (power) ground. |
| B(RING) | Output | Output of B(RING) power amplifier. |
| C3-C1 | Input | SLIC control pins. C3 is MSB and C1 is LSB. |
| CAS | Capacitor | Anti-Saturation pin for capacitor to filter reference voltage when operating in anti-saturation region. |
| CHCLK | Input | (Chopper Clock) Input to switching regulator. $\mathrm{f}=200$ to 600 kHz . |
| CHS | Input | (Chopper Stabilization) Connection for external stabilization components. |
| D2-D1 | Input | Relay Driver Control. D1 and D2 control the relay drivers RYOUT1 and RYOUT2. Logic Low on D1 activates the RYOUT1 relay driver. Logic Low on D2 activates the RYOUT2 relay driver. |
| DA | Input | Negative input to ring-trip comparator. |
| DB | Input | Positive input to ring-trip comparator. |
| $\overline{\mathrm{DET}}$ | Output | Hook-switch detector. A logic Low indicates that selected condition is detected. The detect condition is selected by the logic inputs (C3-C1). The output is open-collector with a built-in $15 \mathrm{k} \Omega$ pull-up resistor. |
| HPA | Capacitor | A (TIP) side of high-pass filter capacitor. |
| HPB | Capacitor | B (RING) side of high-pass filter capacitor. |
| L | Output | (Switching Regulator Power Transistor) Connection point for filter inductor and anode of catch diode. This pin will have up to 60 V of pulse waveform on it, and it must be isolated from sensitive circuits. Care must be taken to keep the diode connections short because of the high currents and di/dt. |
| N/C | - | No Connect. This pin is not internally connected. |
| QBAT | Battery | (Quiet Battery) Filtered battery supply for the signal-processing circuits. |
| RD | Resistor | Detector threshold set and filter pin. |
| RDC | Resistor | Connection point for the DC feed current programming network. The other end of the network connects to the receiver summing node (RSN). |
| RINGOUT | Output | Ring Relay Driver. Open-collector driver with emitter internally connected to BGND. |
| RSN | Input | Receive Summing Node. In the Active, Reverse Polarity, and Tip Open states, the metallic current (both $A C$ and $D C$ ) between $A(T I P)$ and $B($ RING ) is equal to 500 times the current into this pin. The networks which program receive gain, two-wire impedance, and feed resistance all connect to this node. |
| RYOUT1 | Output | Relay/Switch Driver. Open-collector driver with emitter internally connected to BGND. |
| RYOUT2 | Output | Relay/Switch Driver. Open-collector driver with emitter internally connected to BGND. |
| VBAT | Battery | Most negative battery. |
| RSVD | - | This is a reserved pin and must always be left open. |
| VCC | Power Supply | +5 V power supply. |
| VDC | Output | Output that is proportional to the line voltage: VDC $=\mathrm{KDC} \bullet \mathrm{VAB} . \mathrm{KDC}$ is the VDC scale factor. |
| VREG | Input | (Regulated Voltage) Provides internal negative power supply and connection point for inductor, filter capacitor, and chopper stabilization. |
| VTX | Output | Transmit Audio. This output is a 0.50 gain version of the A(TIP) and B(RING) metallic voltage. VTX also sources the two-wire input impedance programming network. |
| $\begin{gathered} \text { Exposed } \\ \text { Pad } \end{gathered}$ | Battery | This must be connected to the most negative battery on the SLIC device pin side of $\mathrm{D}_{\mathrm{VBH}}$ shown on the test and application circuits. |

## ELECTRICAL CHARACTERISTICS

## Absolute Maximum Ratings

Stresses greater than those listed under Absolute Maximum Ratings can cause permanent device failure. Functionality at or above these limits is not implied. Exposure to absolute maximum ratings for extended periods can effect device reliability.

| Storage temperature | -55 to $+150^{\circ} \mathrm{C}$ |
| :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$ with respect to AGND | -0.4 to +7.0 V |
| $\mathrm{V}_{\mathrm{BAT}}$ with respect to AGND: <br> Continuous <br> 10 ms | $\begin{aligned} & +0.4 \text { to }-70 \mathrm{~V} \\ & +0.4 \text { to }-75 \mathrm{~V} \end{aligned}$ |
| BGND with respect to AGND | +3 to -3 V |
| A (TIP) or B (RING) to BGND: <br> Continuous <br> $10 \mathrm{~ms}(\mathrm{f}=0.1 \mathrm{~Hz})$ <br> $1 \mu \mathrm{~s}$ ( $\mathrm{f}=0.1 \mathrm{~Hz}$ ) <br> 250 ns ( $\mathrm{f}=0.1 \mathrm{~Hz}$ ) | $\begin{aligned} & \mathrm{V}_{\text {BAT }} \text { to }+1 \mathrm{~V} \\ & -70 \text { to }+5 \mathrm{~V} \\ & -80 \text { to }+8 \mathrm{~V} \\ & -90 \text { to }+12 \mathrm{~V} \end{aligned}$ |
| Current from A (TIP) or B (RING) | $\pm 150 \mathrm{~mA}$ |
| RINGOUT/RYOUT1,2 current | 50 mA |
| RINGOUT/RYOUT1,2 voltage | BGND to +7 V |
| RINGOUT/RYOUT1,2 transient | BGND to +10 V |
| DA and DB inputs: <br> Voltage on ring-trip inputs Current into ring-trip inputs | $\begin{aligned} & \mathrm{V}_{\mathrm{BAT}} \text { to } 0 \mathrm{~V} \\ & \pm 10 \mathrm{~mA} \end{aligned}$ |
| C3-C1,D2-D1, CHCLK Input voltage | -0.4 to $\mathrm{V}_{\mathrm{CC}}+0.4 \mathrm{~V}$ |
| Maximum power dissipation, continuous, $\mathrm{T}_{\mathrm{A}}=70^{\circ} \mathrm{C}$, No heat sink (See note) <br> In 44-pin TQFP package <br> In 32-pin QFN package | $\begin{aligned} & \text { 1.4 W } \\ & \text { 3.0 W } \end{aligned}$ |
| Thermal Data: <br> In 44-pin TQFP package <br> In 32-pin QFN package | $\theta_{\mathrm{JA}}$ <br> $52^{\circ} \mathrm{C} / \mathrm{W}$ typ <br> $25^{\circ} \mathrm{C} / \mathrm{W}$ typ |
| ESD immunity/pin (HBM) | 1.5 kV |

## Note:

Thermal limiting circuitry on-chip will shut down the circuit at a junction temperature of about $165^{\circ} \mathrm{C}$. Operation above $145^{\circ} \mathrm{C}$ junction temperature may degrade device reliability.
Stresses above those listed under Absolute Maximum Ratings may cause permanent device failure. Functionality at or above these limits is not implied. Exposure to absolute maximum ratings for extended periods may affect device reliability.
Maximum power dissipation, continuous values are assured only through optimized printed circuit board design and layout. Where applicable, a thermal pad with vias must be used in conjunction with modeling of the convection and radiated heat loss characteristics of the printed circuit board and system.

## Operating Ranges

Legerity guarantees the performance of this device over commercial ( $0^{\circ}$ to $70^{\circ} \mathrm{C}$ ) and industrial $\left(-40^{\circ}\right.$ to $\left.85^{\circ} \mathrm{C}\right)$ temperature ranges by conducting electrical characterization over each range, and by conducting a production test with single insertion coupled to periodic sampling. These characterization and test procedures comply with section 4.6.2 of Bellcore TR-TSY-000357 Component Reliability Assurance Requirements for Telecommunications Equipment.

| Ambient temperature | -40 to $+85^{\circ} \mathrm{C}$ |
| :--- | :--- |
| $\mathrm{V}_{\mathrm{CC}}$ | 4.75 to 5.25 V |
| $\mathrm{~V}_{\text {BAT }}$ | -40 to -58 V |
| AGND | 0 V |
| BGND with respect to AGND | -100 to +100 mV |
| Load resistance on VTX to ground | $20 \mathrm{k} \Omega \mathrm{min}$ |

## SPECIFICATIONS

Refer to Figure 9 for the Le79555 test circuit specifications.

## Transmission Performance

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| 2-wire return loss | 200 Hz to 3.4 kHz | 26 |  |  | dB | 1,4 |
| Analog output (VTX) impedance |  |  | 1 | 20 | $\Omega$ | 4 |
| Analog (VTX) output offset voltage |  | -50 |  | +50 | mV |  |
| Overload level, 2-wire | Active state | 2.5 |  |  | Vpk | 2 a |
| Overload level | On hook, $\mathrm{R}_{\mathrm{LAC}}=600 \Omega$ | 1.1 |  |  |  |  |
| THD (Total Harmonic Distortion) | 0 dBm <br>  <br>  <br> 7 dBm |  | -64 |  |  |
| THD, On hook | $0 \mathrm{dBm}, \mathrm{R}_{\mathrm{LAC}}=600 \Omega$ | -50 |  |  |  |  |

## Longitudinal Capability

(See Figure 6.)

| Description | Test Conditions (See Note 1) | Perf. Grade | Min | Typ | Max | Unit | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Longitudinal to metallic L-T, L-4 200 Hz to 1 kHz | Normal Polarity: |  |  |  |  | dB |  |
|  | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | -2,-4 | 63 |  |  |  |  |
|  | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | -2,-4 | 58 |  |  |  | 4 |
|  | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | -1,-3 | 52 |  |  |  |  |
|  | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | -1,-3 | 50 |  |  |  | 4 |
|  | Reverse Polarity: |  |  |  |  |  |  |
|  | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | -2 | 54 |  |  |  | 4 |
|  | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | -1 | 52 |  |  |  |  |
|  | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | -1 | 50 |  |  |  | 4 |
| Longitudinal to metallic L-T, L-4 <br> 1 kHz to 3.4 kHz | Normal Polarity: |  |  |  |  |  |  |
|  | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | -2,-4 | 58 |  |  |  |  |
|  | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | -2,-4 | 53 |  |  |  | 4 |
|  | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | -1,-3 | 52 |  |  |  |  |
|  | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | -1,-3 | 50 |  |  |  | 4 |
|  | Reverse Polarity: |  |  |  |  |  |  |
|  | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | -2 | 53 |  |  |  | 4 |
|  | $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ | -1 | 52 |  |  |  |  |
|  | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | -1 | 50 |  |  |  | 4 |
| Longitudinal signal generation 4-L | 200 Hz to 3.4 kHz |  | 40 |  |  |  |  |
| Longitudinal current per pin (A or B) | Active state |  | 17 | 27 |  | mArms | 4, 8 |
| Longitudinal impedance at A or B | 0 to 100 Hz |  |  | 25 |  | $\Omega /$ pin | 4 |

## Idle Channel Noise

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| C-message weighted noise | $\mathrm{R}_{\mathrm{L}}=600 \Omega, 0^{\circ}$ to $+70^{\circ} \mathrm{C}$ |  | 7 | +10 | dBrnC |  |
|  | $\mathrm{R}_{\mathrm{L}}=600 \Omega,-40^{\circ}$ to $+85^{\circ} \mathrm{C}$ |  |  | +12 |  | 4 |
| Psophometric weighted noise | $\mathrm{R}_{\mathrm{L}}=600 \Omega, 0^{\circ}$ to $+70^{\circ} \mathrm{C}$ |  | -83 | -80 | dBmp |  |
|  | $\mathrm{R}_{\mathrm{L}}=600 \Omega,-40^{\circ}$ to $+85^{\circ} \mathrm{C}$ |  |  | -78 |  |  |

## Insertion Loss and Balance Return Signal

(See Figure 4 and Figure 5.)

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Gain accuracy, 4- to 2-wire | $0 \mathrm{dBm}, 1 \mathrm{kHz}$ $0^{\circ}$ to $+70^{\circ} \mathrm{C}$ <br> $0 \mathrm{dBm}, 1 \mathrm{kHz}$ $-40^{\circ}$ to $+85^{\circ} \mathrm{C}$ | $\begin{aligned} & \hline-0.10 \\ & -0.15 \end{aligned}$ | 0-6.02 | $\begin{aligned} & +0.10 \\ & +0.15 \end{aligned}$ | dB | $\begin{gathered} \hline 3 \\ 3,4 \end{gathered}$ |
| Gain accuracy 2- to 4-wire, 4- to 4-wire | $0 \mathrm{dBm}, 1 \mathrm{kHz}$ $0^{\circ}$ to $+70^{\circ} \mathrm{C}$ <br> $0 \mathrm{dBm}, 1 \mathrm{kHz}$ $-40^{\circ}$ to $+85^{\circ} \mathrm{C}$ | $\begin{aligned} & \hline-6.12 \\ & -6.17 \end{aligned}$ |  | $\begin{aligned} & \hline-5.92 \\ & -5.87 \end{aligned}$ |  | $\begin{gathered} 3 \\ 3,4 \end{gathered}$ |
| Gain accuracy, 4- to 2-wire | On hook | -0.35 |  | +0.35 |  | 3,4 |
| Gain accuracy, 2- to 4-wire, 4- to 4-wire | On hook | -6.37 | -6.02 | -5.67 |  |  |
| Gain accuracy over frequency | 300 to 3.4 kHz  <br> relative to 1 kHz  <br> 300 to 3.4 kHz $0^{\circ}$ to $+70^{\circ} \mathrm{C}$ <br> relative to 1 kHz $-40^{\circ}$ to $+85^{\circ} \mathrm{C}$ | $\begin{aligned} & -0.10 \\ & -0.15 \end{aligned}$ |  | $\begin{aligned} & +0.10 \\ & +0.15 \end{aligned}$ |  | $\begin{gathered} 3 \\ 3,4 \end{gathered}$ |
| Gain tracking | +3 dBm to -55 dBm relative to 0 dBm +3 dBm to -55 dBm relative to $0 \mathrm{dBm} \quad-40^{\circ}$ to $+80^{\circ} \mathrm{C}$ re ${ }^{\circ} \mathrm{C}$ | $\begin{aligned} & -0.10 \\ & -0.15 \end{aligned}$ |  | $\begin{aligned} & +0.10 \\ & +0.15 \end{aligned}$ |  | $\begin{aligned} & 3,4 \\ & 3,4 \end{aligned}$ |
| Gain tracking On hook | 0 dBm to -37 dBm +3 dBm to 0 dBm | $\begin{aligned} & \hline-0.15 \\ & -0.35 \end{aligned}$ |  | $\begin{aligned} & +0.15 \\ & +0.35 \end{aligned}$ |  | 3,4 |

## Line Characteristics

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{I}_{\mathrm{L}}$, Short Loops, Active state |  | 22.5 | 24.5 | 26.5 | mA |  |
| $\mathrm{I}_{\mathrm{L}}$, Long Loops, Active state | $\mathrm{R}_{\mathrm{L}}=2010 \Omega$ | 20 | 22.5 |  |  |  |
| ${ }_{\text {L }}$, Standby state | $\mathrm{R}_{\mathrm{L}}=2010 \Omega \quad \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ | 15 |  |  |  |  |
|  | $\mathrm{R}_{\mathrm{L}}=600 \Omega$ (current limit) | 18 | 30 |  |  |  |
| ILLIM | Active, A and B to ground |  | 75 | 120 |  |  |
| $\mathrm{K}_{\mathrm{DC}}$ ( $\mathrm{V}_{\mathrm{DC}}$ Scaling) | $\begin{aligned} & \mathrm{K}_{\mathrm{DC}}=\frac{\mathrm{V}_{\mathrm{DC}}}{\mathrm{~V}_{\mathrm{AB}}} \\ & \mathrm{R}_{\mathrm{L}}=300 \text { to } 1500 \Omega \end{aligned}$ | 0.052 | 0.055 | 0.058 |  |  |
| $\mathrm{V}_{\mathrm{AB}}$, Open Circuit voltage | Active state | 42.75 | 44 |  | V |  |
| $\mathrm{I}_{\mathrm{A}}$, Leakage, Tip Open state | $\mathrm{R}_{\mathrm{L}}=0$ |  |  | 100 | $\mu \mathrm{A}$ |  |
| $\mathrm{I}_{\mathrm{B}}$, Current, Tip Open state | B to GND | 15 | 30 | 56 | mA |  |
| $\mathrm{V}_{\mathrm{A}}$, Active state | $\begin{aligned} & \text { RA to BAT }=7 \mathrm{k} \Omega, \\ & \text { RB to GND }=100 \Omega \end{aligned}$ | -7.5 | -5 |  | V | 4 |

## Power Supply Rejection Ratio

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$, Active State | 50 Hz to 3.4 kHz <br> $\left(\mathrm{V}_{\text {RIPLE }}=100 \mathrm{mV} \mathrm{rms}\right)$ | 30 | 40 |  |  |  |
| $\mathrm{~V}_{\text {BAT }}$, Active State | 50 Hz to 3.4 kHz <br> Off-hook constant current region <br> $\left(\mathrm{V}_{\text {RIPLE }}=500 \mathrm{mV} \mathrm{pp}\right)$ | 28 | 50 |  | dB | 5 |
| Effective internal resistance | CAS pin to $\mathrm{V}_{\text {BAT }}$ | 85 | 170 | 255 | $\mathrm{k} \Omega$ | 4 |

## Power Dissipation

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| On-hook, Standby state | $\mathrm{R}_{\mathrm{L}}=$ Open |  | 45 | 70 | mW |  |
| On-hook Active State | $\mathrm{R}_{\mathrm{L}}=$ Open |  | 130 | 190 |  |  |
| Off-hook, Standby state |  |  | 860 | 1200 |  |  |
| Off-hook Active State |  |  | 350 | 400 |  |  |

## Supply Currents

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ${ }_{\mathrm{ICC}}$, On-hook $\mathrm{V}_{\mathrm{CC}}$ supply current | Standby State <br> Active/Polarity Reversed States <br> Open Circuit, $\mathrm{R}_{\mathrm{L}}=$ Open <br> Ringing, $\mathrm{R}_{\mathrm{L}}=$ Open |  | $\begin{gathered} \hline \hline 2.5 \\ 4.55 \\ 2.5 \\ 6.0 \end{gathered}$ | $\begin{aligned} & \hline \hline 3.2 \\ & 6.0 \end{aligned}$ | mA |  |
| $I_{\text {BAT }}$, <br> On-hook $V_{\text {BAT }}$ supply current $+\mathrm{V}_{\text {REG }}$ supply current | Standby State <br> Active/Polarity Reversed States <br> Open Circuit, $\mathrm{R}_{\mathrm{L}}=$ Open <br> Ringing, $\mathrm{R}_{\mathrm{L}}=$ Open |  | $\begin{gathered} \hline 0.65 \\ 2.3 \\ 0.5 \\ 1.5 \end{gathered}$ | $\begin{aligned} & 0.9 \\ & 4.0 \end{aligned}$ |  |  |

## RFI Rejection

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| VAB, RMS | 100 kHz to $30 \mathrm{MHz},($ See Figure 8) |  |  | 1.0 | mVrms | 4 |

## Receive Summing Node (RSN)

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| RSN DC voltage | $\mathrm{I}_{\text {RSN }}=0 \mathrm{~mA}$ |  | 0 |  | V | 4 |
| RSN impedance | 200 Hz to 3.4 kHz |  | 10 | 20 | $\Omega$ |  |

## Logic Inputs

(C3-C1, D2-D1, and CHCLK)

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{IH}}$, Input High voltage |  | 2.0 |  |  | V |  |
| $\mathrm{V}_{\text {IL }}$, Input Low voltage |  |  |  | 0.8 |  |  |
| $\mathrm{I}_{\text {IH }}$, Input High current |  | -75 |  | 40 | $\mu \mathrm{A}$ |  |
| $\mathrm{I}_{\text {IL }}$, Input Low current |  | -400 |  |  |  |  |

## Logic Output DET

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| V ${ }_{\text {OL }}$, Output Low voltage | $\mathrm{I}_{\text {OUT }}=0.3 \mathrm{~mA}$ |  |  | 0.40 | V |  |
| $\mathrm{V}_{\mathrm{OH}}$, Output High voltage | $\mathrm{I}_{\text {OUT }}=-0.1 \mathrm{~mA}$ | 2.4 |  |  |  |  |

## Ring-Trip Detector Input

(DA, DB)

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| Bias Current |  | -500 | -50 |  | nA |  |
| Offset voltage | Source resistance $=2 \mathrm{M} \Omega$ | -50 | 0 | +50 | mV | 6 |

## Loop Detector

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Off-hook threshold | $\mathrm{R}_{\mathrm{D}}=35.4 \mathrm{k} \Omega$ | 9.4 | 11.7 | 14.0 | mA |  |
| On-hook threshold | $\mathrm{R}_{\mathrm{D}}=35.4 \mathrm{k} \Omega$ | 8.8 | 10.4 | 12.0 |  |  |
| Hysteresis | $\mathrm{R}_{\mathrm{D}}=35.4 \mathrm{k} \Omega$ |  | 1.3 |  |  |  |
| IGK, Ground-key detector threshold | $\mathrm{R}_{\mathrm{L}}$ from BX to $G N D$ <br> Active, Standby, and Tip open | 5 | 9 | 13 |  |  |

## Relay Driver Output

(RINGOUT, RYOUT1, RYOUT2)

| Description | Test Conditions (See Note 1) | Min | Typ | Max | Unit | Note |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| On voltage | $\mathrm{I}_{\mathrm{OL}}=40 \mathrm{~mA}$ |  | +0.3 | +0.7 | V |  |
| Off leakage | $\mathrm{V}_{\mathrm{OH}}=+5 \mathrm{~V}$ |  |  | 100 | $\mu \mathrm{~A}$ |  |
| Zener breakover | $\mathrm{I}_{\mathrm{Z}}=100 \mu \mathrm{~A}$ | 6 | 7.2 |  | V |  |
| Zener On voltage | $\mathrm{I}_{\mathrm{Z}}=30 \mathrm{~mA}$ |  | 8 |  |  |  |

Figure 1. Relay Driver Schematic


1. Unless otherwise noted, $R_{L}=600 \Omega$. Also, refer to the Le 79555 device test circuit in Figure 9 .
2. 

a) Overload level is defined as THD $=1 \%$.
b) Overload level is defined as $T H D=1.5 \%$.
3. Balance return signal is the signal generated at $V_{T X}$ by $V_{R X}$. This specification assumes that the two-wire, AC-load impedance matches the programmed impedance.
4. Not tested in production. This parameter is guaranteed by characterization or correlation to other tests.
5. This parameter is tested at 1 kHz in production. Performance at other frequencies is guaranteed by characterization.
6. Tested with $0 \Omega$ source impedance. $2 M \Omega$ is specified for system design only.
7. Group delay can be greatly reduced by using a $Z_{T}$ network such as that shown in Figure 7. The network reduces the group delay to less than $2 \mu$ s and increases 2 WRL. The effect of group delay on linecard performance also may be compensated for by synthesizing complex impedance with the QLSLAC ${ }^{\text {TM }}$ device.
8. Minimum current level guaranteed not to cause a false loop detect.

Table 1. SLIC Device Decoding

| State | C3 | C2 | C1 | Two-Wire Status | $\overline{\text { DET Output }}$ |
| :---: | :---: | :---: | :---: | :--- | :--- |
| 0 | 0 | 0 | 0 | Reserved | X |
| 1 | 0 | 0 | 1 | Reserved | X |
| 2 | 0 | 1 | 0 | Active Reverse Polarity (-1, 2 devices) | Loop detector |
| 3 | 0 | 1 | 1 | Tip Open | Ring Ground (see note) |
| 4 | 1 | 0 | 0 | Open Circuit | Ring trip |
| 5 | 1 | 0 | 1 | Ringing | Ring trip |
| 6 | 1 | 1 | 0 | Active | Loop detector |
| 7 | 1 | 1 | 1 | Standby | Loop detector |

## Note:

Ring ground detection in Tip Open is automatic. If Iongitudinal current is greater than IGK in Active, Standby, or Tip Open, the $\overline{D E T}$ will go low. Therefore, if in Active or Standby, $\overline{D E T}$ may be an indication of off hook, ground fault, or both.

Table 2. User-Programmable Components

| $\mathrm{Z}_{\mathrm{T}}=250\left(\mathrm{Z}_{2 \text { WIN }}-2 \mathrm{R}_{\mathrm{F}}\right)$ | $\mathrm{Z}_{\mathrm{T}}$ is connected between the VTX and RSN pins. The fuse resistors are $R_{F}$, and $Z_{2 W I N}$ is the desired 2 -wire $A C$ input impedance. When computing $Z_{T}$, the internal current amplifier pole and any external stray capacitance between VTX and RSN must be taken into account. |
| :---: | :---: |
| $Z_{R x}=\frac{Z_{L}}{G_{42 L}} \cdot \frac{500 Z_{T}}{Z_{T}+250\left(Z_{L}+2 R_{F}\right)}$ | $Z_{R X}$ is connected from VRX to RSN. $Z_{T}$ is defined above, and $G_{42 L}$ is the desired receive gain. $\mathrm{Z}_{\mathrm{L}}=$ Load Impedance, AD to BD . |
| $\begin{aligned} & \mathrm{R}_{\mathrm{DC} 1}+\mathrm{R}_{\mathrm{DC} 2}=\frac{625}{\mathrm{~L}_{\mathrm{LOOP}}} \\ & \mathrm{C}_{\mathrm{DC}}=1.5 \mathrm{~ms} \cdot \frac{R_{\mathrm{DC} 1}+R_{\mathrm{DC} 2}}{\mathrm{R}_{\mathrm{DC} 1} \cdot \mathrm{R}_{\mathrm{DC} 2}} \end{aligned}$ | $R_{D C 1}, R_{D C 2}$, and $C_{D C}$ form the network connected to the $R_{D C}$ pin. $R_{D C 1}$ and $R_{D C 2}$ are approximately equal. $\mathrm{I}_{\text {Loop }}$ is the desired loop current in the constant-current region. |
| $\mathrm{I}_{\mathrm{T}_{\text {OFF }}}=\frac{414}{\mathrm{R}_{\mathrm{D}}}, \quad \mathrm{I}_{\mathrm{T}_{\text {ON }}}=\frac{368}{R_{\mathrm{D}}}, \quad \mathrm{C}_{\mathrm{D}}=\frac{0.5 \mathrm{~ms}}{\mathrm{R}_{\mathrm{D}}}$ <br> ( $I_{\text {Threshold }}$ on to off hook $)$ (I ${ }_{\text {Threshold }}$ off to on hook $)$ | $R_{D}$ and $C_{D}$ form the network connected from $R_{D}$ to AGND/DGND and $I_{T}$ is the threshold current between on-hook and off-hook. |
| $\mathrm{C}_{\mathrm{CAS}}=\frac{1}{170 \mathrm{k} \Omega \cdot 2 \pi \bullet \mathrm{f}_{\mathrm{C}}}$ | $\mathrm{C}_{\mathrm{CAS}}$ is the regulator filter capacitor and $\mathrm{f}_{\mathrm{C}}$ is the desired filter cut-off frequency. |
| $\mathrm{I}_{\text {STANDBY }}=\frac{\left\|\mathrm{V}_{\text {BAT }}\right\|-3 \mathrm{~V}}{400 \Omega+\mathrm{R}_{\mathrm{L}}}$ | Standby loop current (resistive region). |

Figure 2. Load Line (Typical)


## Regions:

1. Constant current region:
2. Battery tracking anti-sat:
$V_{A B}=I_{L} R_{L^{\prime}}=\frac{625}{R_{D C}} R_{L^{\prime}}$, where $R_{L}^{\prime}=R_{L}+2 R_{F}$ $R_{D C}=R_{D C 1}+R_{D C 2}$
$\mathrm{V}_{\mathrm{AB}}=|\mathrm{BAT}|-\mathrm{V}_{\text {Diode }}-7.2 \mathrm{~V}-\mathrm{I}_{\mathrm{L}}\left(\mathrm{R}_{\mathrm{DC}} / 210\right)$

Figure 3. Feed Programming


Figure 4. Two-to-Four-Wire Insertion Loss


Figure 5. Four-to-Two-Wire Insertion Loss and Balance Return Signal


Figure 6. Longitudinal Balance


Figure 7. Two-Wire Return Loss


Figure 8. RFI


## (Le)gerity.

Figure 9. Le79555 Engineering Test Circuit


## APPLICATION CIRCUITS



## Note:

1. Protection circuitry does not need to be battery tracking.
2. For CHCLK operation between 190 kHz and $290 \mathrm{kHz}, \mathrm{L} 1$ is recommended to be 2 mH . For CHCLK operation between 290 kHz and 600 $\mathrm{kHz}, \mathrm{L} 1$ is recommended to be 1 mH .

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## LINECARD PARTS LIST

The following list defines the parts and part values required to meet target specification limits for one channel.

| Item | Quantity | Type | Value | Tol. | Rating | Comments | Note |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{C}_{\mathrm{CH} 2}$ | 1 | Capacitor (COG) | 560 pF | 5\% | 50 V |  |  |
| $\mathrm{C}_{\mathrm{AX}}, \mathrm{C}_{\mathrm{BX}}$ | 2 | Capacitor (X7R) | 2200 pF | 20\% | 100 V |  |  |
| $\mathrm{C}_{\mathrm{CH} 1}$ | 1 | Capacitor (X7R) | 15 nF | 10\% | 50 V |  |  |
| $\mathrm{C}_{\mathrm{HP}}$ | 1 | Capacitor (X7R) | 220 nF | 20\% | 100 V |  |  |
| $\mathrm{C}_{\text {DC }}$ | 1 | Capacitor (X7R) | 220 nF | 20\% | 16 V |  |  |
| $\mathrm{C}_{\text {CAS }}$ | 1 | Capacitor (X7R) | 330 nF | 20\% | 100 V |  |  |
| $\mathrm{C}_{\text {QB }}$ | 1 | Capacitor (X7R) | 330 nF | 20\% | 100 V |  |  |
| $\mathrm{C}_{\mathrm{V} 1}$ | 1 | Capacitor (X7R) | 470 nF | 20\% | 100 V |  |  |
| $\mathrm{C}_{\text {FIL }}$ | 1 | Capacitor (Low ESR) | 470 nF | 20\% | 100 V |  |  |
| $\mathrm{C}_{\mathrm{D}}$ | 1 | Capacitor (X7R) | 15 nF | 10\% | 16 V |  |  |
| $\mathrm{R}_{\mathrm{F}}$ | 1 | Resistor Hybrid | 50 | 1\% |  |  |  |
| $\mathrm{R}_{\mathrm{CH}}$ | 1 | AXIAL/SMT | 1.3 k | 1\% | 0.1 W |  |  |
| $\begin{aligned} & \hline \text { RDC1, } \\ & \text { RDC2 } \end{aligned}$ | 2 | SMT | 13.0 k | 1\% | 0.1 W |  |  |
| RD | 1 | SMT | 35.7 k | 1\% | 0.1 W |  |  |
| RT | 1 | SMT | 124 k | 1\% | 0.1 W |  |  |
| RRX | 1 | SMT | 124 k | 1\% | 0.1 W |  |  |
| $\mathrm{D}_{\mathrm{VBH}}$, <br> $\mathrm{D}_{\text {CHCLK1 }}$ | 2 | MUR 120 (D0-41) DIODE |  |  | $\begin{gathered} 1 \mathrm{~A}, \\ 100 \mathrm{~V} \end{gathered}$ |  |  |
| L1 | 1 | Coiltronics SD25-102 Inductor | 1.0 mH | $(20>R>5)$ | 100 mA |  |  |
| U3 | 1 | Sidactor P0640EA70 |  |  |  |  |  |
| U2 | 1 | Diode Bridge EDF1DM |  |  |  |  |  |
| U1 | 1 | Le79555 |  |  |  |  |  |
| U4 | 1 | Le58QL063 |  |  |  |  |  |
| $\begin{aligned} & \mathrm{C}_{\text {IN }}, \mathrm{C}_{\text {OUT }}, \\ & \mathrm{C}_{\text {REF }} \end{aligned}$ | 3 | Capacitor (X7R) | 100 nF | 20\% | 16 V |  |  |
| RPA, RPB | 2 | SMT | 10 k | 1\% | 0.25 W |  |  |
| $\mathrm{R}_{\text {SR2 } 2}, \mathrm{R}_{\text {SR3 }}$ | 2 | SMT | 1 M | 1\% | 0.25 W |  |  |
| $\mathrm{R}_{\text {SR4 } 4, ~ \mathrm{R}_{\text {SR1 }}}$ | 2 | SMT | 909 k | 1\% | 0.25 W |  |  |
| $\mathrm{C}_{\text {SR1 } 1}, \mathrm{C}_{\text {SR2 }}$ | 2 | Capacitor (X7R) | 330 nF | 20\% | 100 V |  |  |
| $\mathrm{R}_{\text {SR }}$ | 1 | Resistor Hybrid | 400 | 1\% |  |  |  |

## PHYSICAL DIMENSIONS

## 44-Pin TQFP

TQFP 044



DETAIL X


Dwg rev. AS; 08/00

| Package | TQFP 044 |  |  |
| :---: | :---: | :---: | :---: |
| Jedec | MS-026 (C) ACB |  |  |
| SYMBDL | MIN | NDM | MAX |
| A | - | - | 1.20 |
| A1 | 0.05 | -- | 0.15 |
| A2 | 0.95 | 1.00 | 1.05 |
| D | 12.00 BSC |  |  |
| D1 | 10.00 BSC |  |  |
| E | 12.00 BSC |  |  |
| E1 | 10.00 BSC |  |  |
| L | 0.45 | 0.60 | 0.75 |
| N | 44 |  |  |
| e | 0.80 BASIC |  |  |
| $b$ | 0.30 | 0.37 | 0.45 |
| b1 | 0.30 | 0.35 | 0.40 |
| TILERANCES DF FDRM AND PISITIUN |  |  |  |
| ccc | 0.10 |  |  |
| ddd | 0.20 |  |  |
| a,a | 0.20 |  |  |

NOTES:

1. ALL DIMENSIONS AND TOLERANCES CONFORM TO ANSI Y14.5M-1982.
2. DATUM PLANE $-\mathrm{H}-$ IS LOCATED AT THE MOLD PARTING LINE AND IS COINCIDENT WITH THE BOTTOM OF THE LEAD WHERE THE LEAD EXITS THE PLASTIC BODY.
3. DIMENSIONS "D1" AND "E1" DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.254 mm PER SIDE.
DIMENSIONS "D1" AND "E1" INCLUDE MOLD MISMATCH AND ARE determined at datum plane - $-\mathrm{H}-$
4. DIMENSION "B" DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08 mm TOTAL IN EXCESS OF THE b DIMENSION AT MAXIMUM MATERIAL CONDITION. dambar can not be located on the lower radius or the FOOT.
5. CONTROLLING DIMENSIONS: MILLIMETER.
6. DIMENSIONS "D" AND "E" ARE MEASURED FROM BOTH INNERMOST AND OUTERMOST POINTS.
7. DEVIATION FROM LEAD-TIP TRUE POSITION SHALL BE WITHIN $\pm 0.076$ MM. FOR PITCH $>0.5 \mathrm{~mm}$.
AND WITHIN $\pm 0.04$ FOR PITCH $\leq 0.5 \mathrm{~mm}$.
8. LEAD COPLANARITY SHALL BE WITHIN: (REFER TO 06-500) $1-0.10 \mathrm{~mm}$ FOR DEVICES WITH LEAD PITCH OF $0.65-0.80 \mathrm{~mm}$. $2-0.076 \mathrm{~mm}$ FOR DEVICES WITH LEAD PITCH OF 0.50 mm . COPLANARITY IS MEASURED PER SPECIFICATION 06-500.
9. half span (Center of package to lead tip) shall be $15.30 \pm .165\left\{.602^{\prime \prime} \pm .0065^{\prime \prime}\right\}$
10. " N " IS THE TOTAL NUMBER OF TERMINALS.
11. THE top of package is smaller than the bottom of the PACKAGE BY 0.15 MILLIMETERS.
12. THIS OUTLINE CONFORMS TO JEDEC PUBLICATION 95 REGISTRATION MS-026.
13. The 160 Lead is a compliant depopulation of the 176 lead MS-026 VARIATION BGA.

## Note:

BSC is an ANSI standard for basic centering. Dimensions are measured in millimeters.


| Symbol | Dimension in mm |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Min | Nom | Max |  |
| A | 0.80 | 0.90 | 1.00 |  |
| A2 | $0.57 ~ R E F$ |  |  |  |
| b | 0.18 | 0.23 | 0.28 |  |
| D | 8.00 BSC |  |  |  |
| D2 | 5.70 | 5.80 | 5.90 |  |
| E | 8.00 BSC |  |  |  |
| E2 | 5.70 | 5.80 | 5.90 |  |
| e | 0.80 BSC |  |  |  |
| L | 0.43 | 0.53 | 0.63 |  |
| N | 32 |  |  |  |
| A1 | 0.00 | 0.02 | 0.05 |  |
| A3 | 0.20 REF |  |  |  |

NOTES :

1. DIMENSIONING AND TOLERANCING CONFORM TO ACME Y14,5M-1994.
2. ALL DIMENSIONS ARE IN MILLIMETERS, $\theta$ IS IN DEGREES.
3. $N$ IS THE TOTAL NUMBER OF TERMINALS.
4. THE TERMINAL \#1 IDENTIFIER AND TERMINAL NUMBERING CONVENTION SHALL CONFORM TO JEP 95-1 SSP-012. DETAILS OF THE TERMINAL \#1 IDENTIFIER ARE OPTIONAL, BUT MUST BE LOCATED WITHIN THE ZONE INDICATED. THE TERMINAL \#1 IDENTIFIER MAY BE EITHER A MOLD OR MARKED FEATURE.
5. COPLANARITY APPLIES TO EXPOSED PAD AS WELL AS THE TERMINALS.
6. REFERENCE DOCUMENT : JEDEC MO-220

REVISION HISTORY

## Revision A to B

- Updated document format.
- In the "Features" section, the following changes were made:
- Removed "(45 mW)" from Low standby power (since it's already in the specification).
- Changed battery voltage range from -16 V to -58 V to -40 V to -58 V .
- Removed "(6.5 V)" from Low Off-Hook Active Overhead Voltage.
- In "Related Literature", added the "Introduction to the SLIC Family" application note.
- Added the 32-pin PLCC information to the Ordering Information and Absolute Maximum Ratings sections and added the connection diagram.
- Updated the Connection Diagram.
- Updated the Pin Description table to correct inconsistencies; added range for CHCLK.
- In the Electrical Characteristics table:
- Updated the information in the Line Characteristics section on the Long Loops row and the VDC Accuracy row.
- Deleted the Disconnect state information in the Power Dissipation and Supply Currents sections.
- In "Specifications", the following changes were made:
- Added a column for performance grade in the Longitudinal Capability and Insertion Loss and Balance Return Signal tables.
- Changed test circuit reference in the Longitudinal Capability table
- Updated the Insertion Loss and Balance Return Signal table.
- In the Line Characteristics table, $\mathrm{I}_{\mathrm{L}}$ Standby state test conditions, changed the equation to $\mathrm{R}_{\mathrm{L}}=2.5 \mathrm{k}$.
- In the Line Characteristics table, added spec for Overhead Voltage.
- Made changes to test conditions for $\mathrm{I}_{\mathrm{L}}$, Long Loops, Active State; KDC ( $\mathrm{V}_{\mathrm{DC}}$ Accuracy); VAB, Open Circuit voltage in the Line Characteristics table.
- Added value for CHCLK in Note 1.
- In the "DC Feed Characteristics" section, revised equations in notes and updated DC Feed Characteristics graphic.
- Changed the equation for $Z_{R X}$ in the User-Programmables table
- Updated Engineering Test Circuit and Application Circuit graphics; added graphic for U4/Am79Q063
- Added Linecard Parts List page
- The physical dimension (PQT044) was added to the Physical Dimension section.


## Revision B to C

- Removed current gain feature from the "Features" section
- Updated "Related Literature" section to include the QLSLAC data sheets
- In the "Ordering Information" table, added dashes before performance grades
- Removed package graphic from "Ordering Information" section
- Added OPNs for the QFN package in "Ordering Information"; added note regarding markings on QFN packages
- Edited "Block Descriptions" section
- In "Connection Diagrams," added pinout diagram for 32-pin QFN package; added notes regarding exposed pad and RSVD pin
- In the "Pin Descriptions" table, the following edits were made:
- Updated the Pin Description table to correct inconsistencies
- Edited the description of the RSN pin
- Added range for CHCLK
- Made minor edits to RSVD description
- Added a sentence to the description for VDC
- Added a row to describe the exposed pad
- In "Electrical Characteristics", "Absolute Maximum Ratings" table, the following was added:
- Max power dissipation of 3.0 W for 32-pin QFN package
- Thermal data for 32-pin QFN package
- Added a note regarding maximum power dissipation values under the Absolute Maximum Ratings table
- In the "Operating Ranges" table, changed the ambient temperature range to $-40^{\circ}$ to $85^{\circ} \mathrm{C}$
- In "Specifications," the following changes were made:
- "Transmission Performance" table, Overload level, edited test conditions; changed Min to 1.1; changed units to Vpk.
_ "Transmission Performance" table, THD, On-hook, edited test conditions; changed units to dB
- "Longitudinal Capability" table, Longitudinal current per pin (A or B), added Note 4 to Note column
- "Insertion Loss and Balance Return Signal" table, Gain Accuracy, 2-to-4 and 4-to-4 wire, changed Max from -5.82 to 5.87
- "Insertion Loss and Balance Return Signal" table, deleted the Group delay row
- "Line Characteristics" table, changed $\mathrm{K}_{\mathrm{DC}}\left(\mathrm{V}_{\mathrm{DC}}\right.$ Accuracy) to $\mathrm{K}_{\mathrm{DC}}$ ( $\mathrm{V}_{\mathrm{DC}}$ Scaling)
- "Line Characterisitcs" table, $\mathrm{I}_{\mathrm{L}}$, Long Loops, Active state, edited the test conditions
- "Line Characterisitcs" table, $\mathrm{K}_{\mathrm{DC}}\left(\mathrm{V}_{\mathrm{DC}}\right.$ Scaling), edited the test conditions
- "Power Dissipation" table, changed the description "On-hook, Active, Polarity Reversal state" to "On-Hook Active state"
- "Power Dissipation" table, Changed Max value of Off-hook Active State from 380 mW to 400 mW
- "Supply Currents" table, added RL = Open to Open Circuit and Ringing test conditions; deleted references to Note 4
- "Power Dissipation" table, On-hook Standby and On-hook Active, added RL = Open to test conditions
- Changed "Power Supply Rejection Ratio" to "Power Supply Rejection Ratio at the Two-Wire Interface"
- "Power Dissipation" table, On-hook, Standby state, changed Max from 60 to 70
- "Logic Inputs" table, added CHCLK as an input
- "Logic Inputs" table, edited description of $\mathrm{V}_{\mathrm{IH}}$, Input High Voltage
- "Logic Inputs" table, deleted row for $\mathrm{V}_{\mathrm{IH}}, \mathrm{C} 3, \mathrm{CHCLK}$
- "Logic Inputs" table, edited description of $\mathrm{V}_{\mathrm{IL}}$
- "Logic Output DET" table, edited test conditions
- "Loop Detector" table, changed "On threshold" to "Off-hook threshold"
- "Loop Detector" table, changed "Off threshold" to "On-hook threshold"
- Extensively edited Note 1; removed Figure 2, "AC Input Impedance Programming Network"
- Made minor formatting edits to SLIC Device Decoding table
- In "User-Programmable Components", the following changes were made:
- Edited equations for $\mathrm{I}_{\text {TON }}$ and $\mathrm{I}_{\text {TOFF }}$
- Edited equation for $Z_{R X}$ and $C_{C A S}$.
- In "DC Feed Characteristics", edited Note 2
- In "Test Circuit Scenarios", the following changes were made:
- Edited title of graphic "Four-to-Four-Wire Insertion Loss and Balance Return Signal"
- Modified Longitudinal Balance graphic
- Modified Two-Wire Return Loss graphic (changed CT1 from 120 pF to 180 pF )
- Modified RFI graphic
- Modified Le79555 test circuit graphic
- Modified Application Circuit graphic
- Added Note 2 to "Application Circuit" section
- Updated Linecard Parts List to reflect the updated application circuit

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