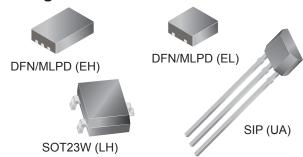


#### **Features and Benefits**

- Micropower operation
- Operation with north or south pole
- 2.5 to 3.5 V battery operation
- Chopper stabilized
  - Superior temperature stability
  - Extremely low switchpoint drift
  - Insensitive to physical stress
- High ESD protection
- Solid-state reliability
- Small size
- Easily manufacturable with magnet pole independence

#### Packages:



Not to scale

#### **Description**

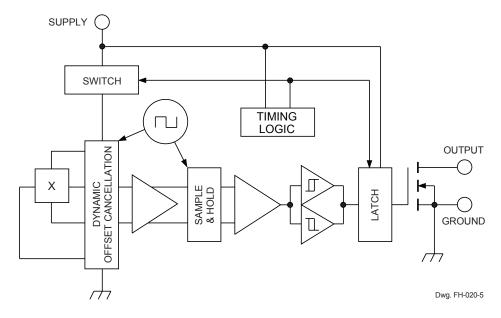
The A 3211 and A3212 integrated circuits are ultra-sensitive, pole independent Hall-effect switches with latched digital output. These sensors are especially suited for operation in battery-operated, hand-held equipment such as cellular and cordless telephones, pagers, and palmtop computers. A 2.5 volt to 3.5 volt operation and a unique clocking scheme reduce the average operating power requirements to less than 15  $\mu W$  with a 2.75 volt supply.

Unlike other Hall-effect switches, either a north or south pole of sufficient strength will turn the output on in the A3212, and in the absence of a magnetic field, the output is off. The A3211 provides an inverted output. The polarity independence and minimal power requirements allow these devices to easily replace reed switches for superior reliability and ease of manufacturing, while eliminating the requirement for signal conditioning.

Improved stability is made possible through chopper stabilization (dynamic offset cancellation), which reduces the residual offset voltage normally caused by device overmolding, temperature dependencies, and thermal stress.

Continued on the next page...

#### **Functional Block Diagram**



### A3211 and A3212

# Micropower, Ultrasensitive Hall Effect Switch

#### **Description (continued)**

This device includes on a single silicon chip a Hall-voltage generator, small-signal amplifier, chopper stabilization, a latch, and a MOSFET output. Advanced BiCMOS processing is used to take advantage of low-voltage and low-power requirements, component matching, very low input-offset errors, and small component geometries.

Four package styles provide magnetically optimized

solutions for most applications. Miniature lowprofile surface-mount package types EH and EL (0.75 and 0.50 mm nominal height) are leadless, LH is a leaded lowprofile SMD, and *UA* is a three-lead SIP for through-hole mounting. Packages are available in lead (Pb) free versions (suffix, -T) with 100% matte tin plated leadframe. EL package for limited release, engineering samples available.

#### **Selection Guide**

Part Number	Pb-free <sup>1</sup>	Packing <sup>2</sup> (Units/Pack)	Package	Ambient Temperature T <sub>A</sub> (°C)	
A3211EEHLT-T	Yes	Tape and Reel (3000)  Leadless Surface Mount			
A3211EELLT-T	Yes	Tape and Reel (3000)	Leadless Surface Mount	-40 to 85	
A3211ELHLT-T	Yes	Tape and Reel (3000)	3-Pin Surface Mount		
A3212EEHLT-T	Yes	Tape and Reel (3000)	Leadless Surface Mount		
A3212EELLT-T Yes		Tape and Reel (3000)	Leadless Surface Mount	-40 to 85	
A3212ELHLT-T Yes		Tape and Reel (3000)	3-Pin Surface Mount	-40 (0 65	
A3212EUA-T	Yes	Bulk Pack (500)	SIP-3 Through Hole, Straight Lead		
A3212LLHLT-T Yes		Tape and Reel (3000)	3-Pin Surface Mount	-40 to 150	
A3212LUA-T	Yes	Bulk Pack (500)	Bulk Pack (500) SIP-3 Through Hole, Straight Lead		

<sup>&</sup>lt;sup>1</sup>Pb-based variants are being phased out of the product line.

#### **Absolute Maximum Ratings**

Characteristic	Symbol	Notes	Rating	Units
Supply Voltage	V <sub>DD</sub>		5	V
Magnetic Flux Density	В		Unlimited	G
Output Off Voltage	V <sub>OUT</sub>		5	V
Output Current	I <sub>OUT</sub>		1	mA
Operating Ambient Temperature	_	Range E	-40 to 85	°C
Operating Ambient Temperature	T <sub>A</sub>	Range L	-40 to 150	°C
Maximum Junction Temperature	T <sub>J</sub> (max)		165	°C
Storage Temperature	T <sub>stg</sub>		-65 to 170	°C

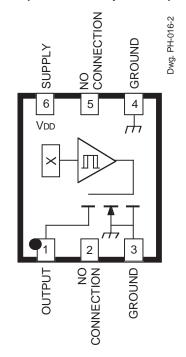


a. Certain variants cited in this footnote are in production but have been determined to be LAST TIME BUY. This classification indicates that sale of this device is currently restricted to existing customer applications. The device should not be purchased for new design applications because obsolescence in the near future is probable. Samples are no longer available. Status change: October 31, 2006. Deadlilne for receipt of LAST TIME BUY ORDERS: April 27, 2007. These variants include: A3212LLHLT and A3212LUA.

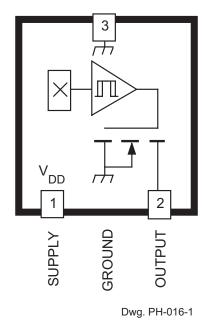
b. Certain variants cited in this footnote are in production but have been determined to be NOT FOR NEW DESIGN. This classification indicates that sale of this device is currently restricted to existing customer applications. The variants should not be purchased for new design applications because obsolescence in the near future is probable. Samples are no longer available. Status change: May 1, 2006 for A3212EEHLT, A3212ELHLT, and

<sup>&</sup>lt;sup>2</sup>Contact Allegro for additional packaging and handling options.

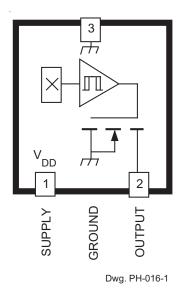
# Package Suffix 'EH' Pinning (Leadless Chip Carrier)



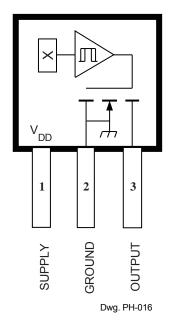
# Package Suffix 'LH' Pinning (SOT23W)



# Package Suffix 'EL' Pinning (Leadless Chip Carrier)



# Package Suffix 'UA' Pinning (SIP)



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Pinning is shown viewed from branded side.



#### ELECTRICAL CHARACTERISTICS over operating voltage and temperature range (unless otherwise specified).

Characteristic	Symbol	Test Conditions	Limits				
Characteristic			Min.	Typ.*	Max.	Units	
Supply Voltage Range	V <sub>DD</sub>	Operating	2.5	2.75	3.5	V	
Output Leakage Current	I <sub>OFF</sub>	V <sub>OUT</sub> = 3.5 V, Output off	_	<1.0	1.0	μΑ	
Output On Voltage	V <sub>OUT</sub>	I <sub>OUT</sub> = 1 mA, V <sub>DD</sub> = 2.75 V	_	100	300	mV	
Awake Time	t <sub>awake</sub>		_	45	90	μs	
Period	t <sub>period</sub>		_	45	90	ms	
Duty Cycle	d.c.		_	0.1	_	%	
Chopping Frequency	f <sub>C</sub>		_	340	-	kHz	
	I <sub>DD(EN)</sub>	Chip awake (enabled)	_	-	2.0	mA	
Supply Current	I <sub>DD(DIS)</sub>	Chip asleep (disabled)	_	-	8.0	μΑ	
Supply Current	I <sub>DD(AVG)</sub>	V <sub>DD</sub> = 2.75 V	_	5.1	10	μA	
		V <sub>DD</sub> = 3.5 V	_	6.7	10	μΑ	

<sup>\*</sup> Typical data is at  $T_A = 25$ °C and  $V_{DD} = 2.75$  V, and is for design information only.

#### 3211 MAGNETIC CHARACTERISTICS over operating voltage and temperature range (unless otherwise specified)

Characteristic Sy	Sumbal	Test Conditions	Limits			
	Symbol		Min.	Тур.	Max.	Units
Operate Points	B <sub>OPS</sub>	South pole to branded side; B > B <sub>OP</sub> , V <sub>OUT</sub> = High (Output Off)	_	37	55	G
Operate Points	B <sub>OPN</sub>	North pole to branded side; B > B <sub>OP</sub> , V <sub>OUT</sub> = High (Output Off)	<b>–</b> 55	<del>-4</del> 0	_	G
I Release Points -	B <sub>RPS</sub>	South pole to branded side; B < B <sub>RP</sub> , V <sub>OUT</sub> = Low (Output On)	10	31	-	G
	B <sub>RPN</sub>	North pole to branded side; B < B <sub>RP</sub> , V <sub>OUT</sub> = Low (Output On)	_	-34	-10	G
Hysteresis	B <sub>HYS</sub>	B <sub>OPx</sub> - B <sub>RPx</sub>	_	5.9	-	G

NOTES: 1. Negative flux densities are defined as less than zero (algebraic convention), i.e., -50 G is less than +10 G.

- 2.  $B_{OPx}$  = operate point (output turns off);  $B_{RPx}$  = release point (output turns on). 3. Typical Data is at  $T_A$  = +25°C and  $V_{DD}$  = 2.75 V and is for design information only. 4. 1 gauss (G) is exactly equal to 0.1 millitesla (mT).

#### 3212 MAGNETIC CHARACTERISTICS over operating voltage and temperature range (unless otherwise specified)

Characteristic	Symbol	mbol Test Conditions	Limits			
	Syllibol		Min.	Тур.	Max.	Units
Operate Points	B <sub>OPS</sub>	South pole to branded side; B > B <sub>OP</sub> , V <sub>OUT</sub> = Low (Output On)	ı	37	55	G
Operate Points E	B <sub>OPN</sub>	North pole to branded side; B > B <sub>OP</sub> , V <sub>OUT</sub> = Low (Output On)	<b>-</b> 55	-40	_	G
Release Points	B <sub>RPS</sub>	South pole to branded side; B < B <sub>RP</sub> , V <sub>OUT</sub> = High (Output Off)	10	31	_	G
Release Points	B <sub>RPN</sub>	North pole to branded side; $B < B_{RP}$ , $V_{OUT} = High$ (Output Off)	ı	-34	-10	G
Hysteresis	B <sub>HYS</sub>	B <sub>OPx</sub> - B <sub>RPx</sub>	ı	5.9	-	G

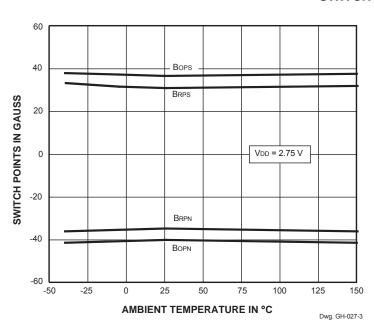
NOTES: 1. Negative flux densities are defined as less than zero (algebraic convention), i.e., -50 G is less than +10 G.

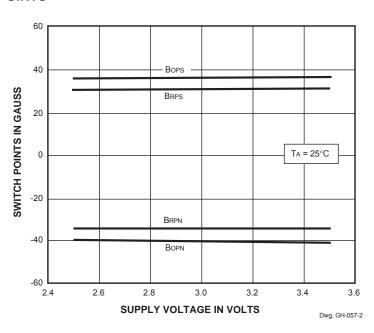
- 2.  $B_{OPx}$  = operate point (output turns on);  $B_{RPx}$  = release point (output turns off). 3. Typical Data is at  $T_A$  = +25°C and  $V_{DD}$  = 2.75 V and is for design information only.
- 4. 1 gauss (G) is exactly equal to 0.1 millitesla (mT).



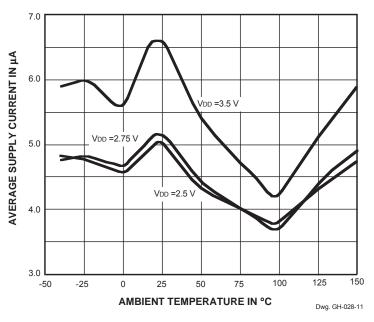
#### TYPICAL OPERATING CHARACTERISTICS

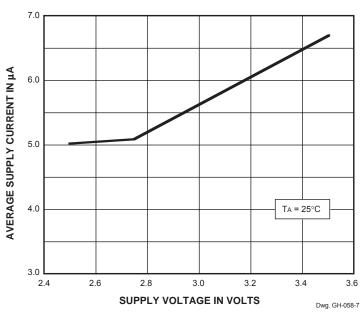
#### **SWITCH POINTS**





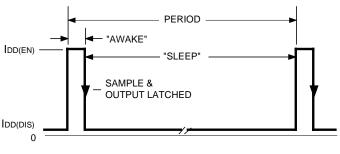
#### **SUPPLY CURRENT**



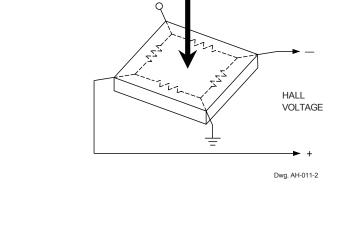


#### **FUNCTIONAL DESCRIPTION**

**Low Average Power.** Internal timing circuitry activates the sensor for 45  $\mu$ s and deactivates it for the remainder of the period (45 ms). A short "awake" time allows for stabilization prior to the sensor sampling and data latching on the falling edge of the timing pulse. The output during the "sleep" time is latched in the last sampled state. The supply current is not affected by the output state.

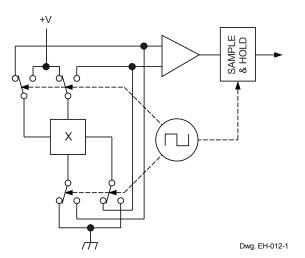


Dwg. WH-017-2



**Chopper-Stabilized Technique.** The Hall element can be considered as a resistor array similar to a Wheatstone bridge. A large portion of the offset is a result of the mismatching of these resistors. These devices use a proprietary dynamic offset cancellation technique, with an internal high-frequency clock to reduce the residual offset voltage of the Hall element that is normally caused by device overmolding, temperature dependencies, and thermal stress. The chopper-stabilizing technique cancels the mismatching of the resistor circuit by changing the direction of the current flowing through the Hall plate using CMOS switches and Hall voltage measurement taps, while maintaing the Hallvoltage signal that is induced by the external magnetic flux. The signal is then captured by a sample-and-hold circuit and further processed using low-offset bipolar circuitry. This technique produces devices that have an extremely stable quiescent Hall output voltage, are immune to thermal stress, and have precise recoverability after temperature cycling. A relatively high sampling frequency is used for faster signal processing capability can be processed.

More detailed descriptions of the circuit operation can be found in: Technical Paper STP 97-10, *Monolithic Magnetic Hall Sensor Using Dynamic Quadrature Offset Cancellation* and Technical Paper STP 99-1, *Chopper-Stabilized Amplifiers With A Track-and-Hold Signal Demodulator*.



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#### **FUNCTIONAL DESCRIPTION (cont'd)**

**Operation.** The output of the A3212 switches low (turns on) when a magnetic field perpendicular to the Hall sensor exceeds the operate point  $B_{OPS}$  (or is less than  $B_{OPN}$ ). After turn-on, the output is capable of sinking up to 1 mA and the output voltage is  $V_{OUT(ON)}$ . When the magnetic field is reduced below the release point  $B_{RPS}$  (or increased above  $B_{RPN}$ ), the device output switches high (turns off). The difference in the magnetic operate and release points is the hysteresis  $(B_{hys})$  of the device. This built-in hysteresis allows clean switching of the output even in the presence of external mechanical vibration and electrical noise. The A3211 functions in the same manner, except the output voltage is reversed from the A3212, as shown in the figures to the right.

As used here, negative flux densities are defined as less than zero (algebraic convention), i.e., -50 G is less than +10 G.

**Applications.** Allegro's pole-independent sensing technique allows for operation with either a north pole or south pole magnet orientation, enhancing the manufacturability of the device. The state-of-the-art technology provides the same output polarity for either pole face.

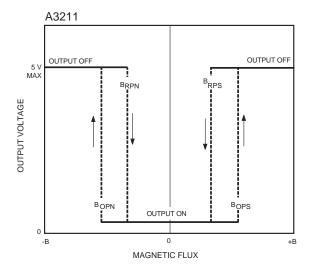
It is strongly recommended that an external bypass capacitor be connected (in close proximity to the Hall sensor) between the supply and ground of the device to reduce both external noise and noise generated by the chopper-stabilization technique. This is especially true due to the relatively high impedance of battery supplies.

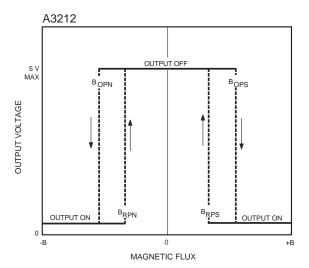
The simplest form of magnet that will operate these devices is a bar magnet with either pole near the branded surface of the device. Many other methods of operation are possible. Extensive applications information for Hall-effect sensors is available in:

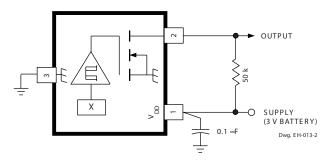
- Hall-Effect IC Applications Guide, Application Note 27701;
- Hall-Effect Devices: Soldering, Gluing, Potting, Encapsulating, and Lead Forming, Application Note 27703.1;
- Soldering of Through-Hole Hall-Sensor Dervices, Application Note 27703; and
- *Soldering of Surface-Mount Hall-Sensor Devices*, Application Note 27703.2.

All are provided at

www.allegromicro.com



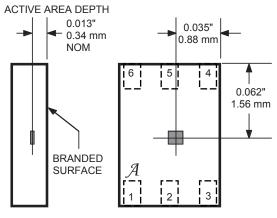






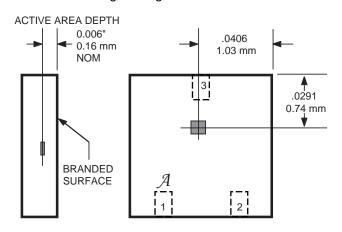
#### **SENSOR LOCATIONS**

#### Package Designator 'EH'

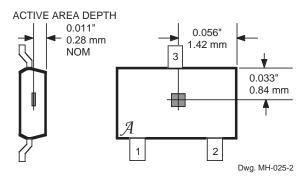


Dwg. MH-030

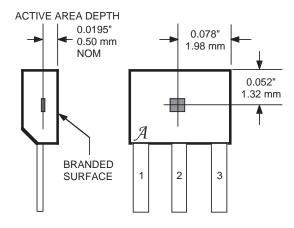
#### Package Designator 'EL'



#### Package Designator 'LH'



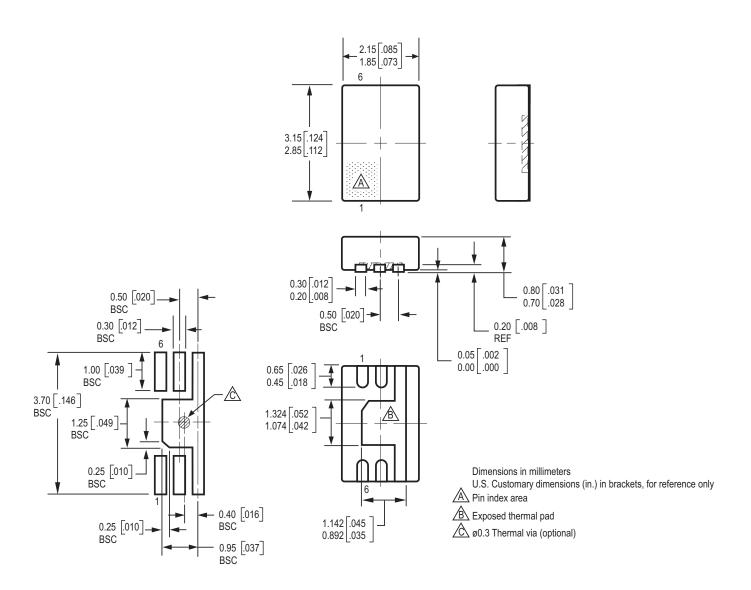
#### Package Designator 'UA'



Dwg. MH-011-13

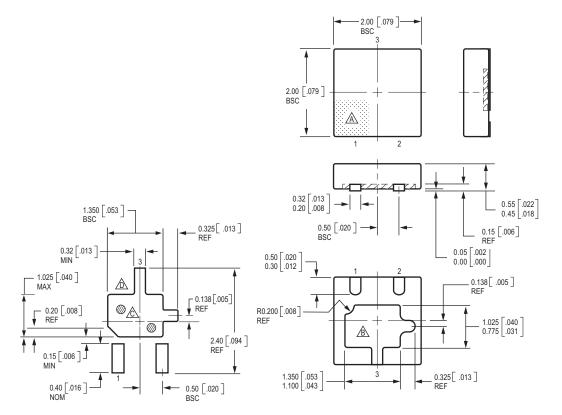
#### PACKAGE DESIGNATOR 'EH'

(Reference MO-229C WCED-1)



#### **PACKAGE DESIGNATOR 'EL'**

MLPD 3 Contact



Dimensions in millimeters U.S. Customary dimensions (in.) in brackets, for reference only

A Pin index area

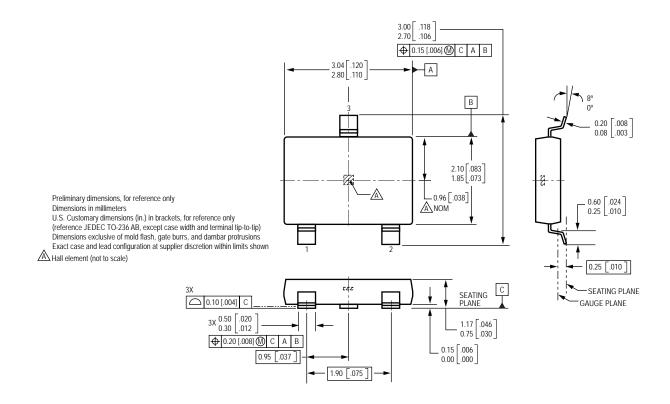
A Exposed thermal pad

Optional thermal vias, Ø0.30 [.012], pitch 1.2 [.047]

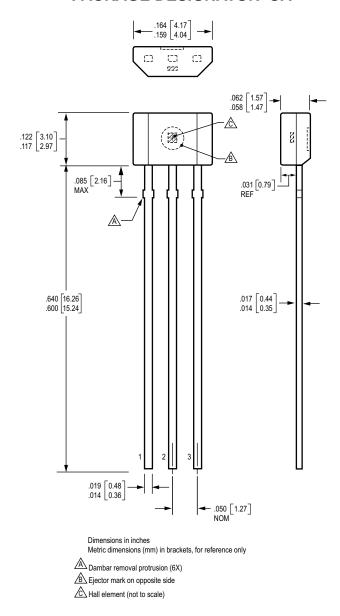
Typical pad layout; adjust as necessary to meet application process requirements

#### **PACKAGE DESIGNATOR 'LH'**

(SOT23W, fits SC-59A solder-pad layout)



#### PACKAGE DESIGNATOR 'UA'



The products described herein are manufactured under one or more of the following U.S. patents: 5,045,920; 5,264,783; 5,442,283; 5,389,889; 5,581,179; 5,517,112; 5,619,137; 5,621,319; 5,650,719; 5,686,894; 5,694,038; 5,729,130; 5,917,320; and other patents pending.

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