

## 2ch.Step-Up/Down DC/DC Controller ICs

GO-Compatible

### GENERAL DESCRIPTION

XC9502 series is PWM controlled, PWM/PFM automatic switching controlled, multi-functional, 2 channel step-up and down DC/DC controller ICs. With 0.9V of standard voltage supply internal, and using externally connected components, the output 1 voltage (step-up DC/DC controller) can be set freely within a range of 1.5V to 30V. Since the output 2 (step-down DC/DC controller) has a built-in 0.9V reference voltage (accuracy  $\pm 2\%$ ), 0.9V can be set using external components. With a 180kHz frequency, the size of the external components can be reduced. Switching frequencies of 300kHz and 500kHz are also available as custom-designed products. The control of the XC9502 series can be switched between PWM control and PWM/PFM automatic switching control using external signals. Control switches from PWM to PFM during light loads when automatic switching is selected and the series is highly efficient from light loads through to large output currents. Noise is easily reduced with PWM control since the frequency is fixed. The series gives freedom of control selection so that control suited to the application can be selected. Soft-start time is internally set to 10msec (Output1) and offers protection against in-rush currents when the power is switched. This also prevents voltage overshoot.

### APPLICATIONS

- PDA's
- Palmtop computers
- Portable audio
- Various power supplies

### FEATURES

#### 2ch DC/DC Controller

##### <Output 1: Step-Up DC/DC Controller>

- Output Voltage Range : 1.5V ~ 30V (set by FB1 pin)
- Output Current : More than 300mA  
( $V_{IN}=1.8V, V_{OUT}=3.3V$ )

- Maximum Duty Cycle : 80% (TYP.)
- High Efficiency : 83% (TYP.)

##### <Output 2: Step-Down DC/DC Controller>

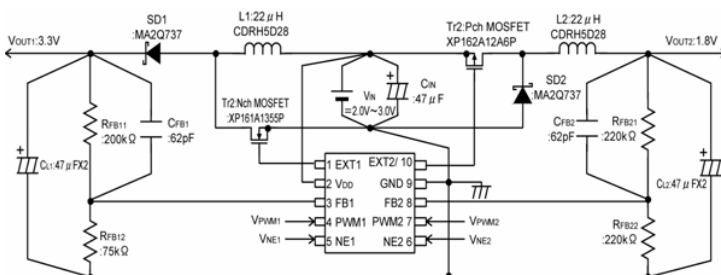
- Output Voltage Range : 0.9V ~ 6.0V (set by FB2 pin)
- Output Current : 1000mA ( $V_{IN}=3.3V, V_{OUT}=1.8V$ )
- Maximum Duty Cycle : 100% (TYP.)
- High Efficiency : 92% (TYP.)

##### <Common>

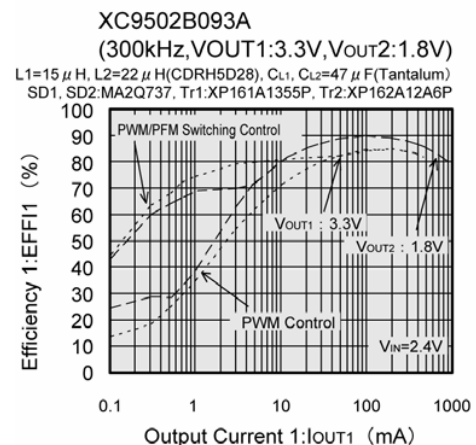
- Supply Voltage Range : 2.0V ~ 10.0V
- Input Voltage Range : 0.9V ~ 10.0V
- Oscillation Frequency : 180kHz ( $\pm 15\%$ )  
\* 300kHz, 500kHz custom
- Control Method : PWM or PWM/PFM selectable
- Stand-by Function : 3.0  $\mu$ F (MAX.)
- Soft-Start Time : 10ms (internally set)
- Package : MSOP-10, USP-10

### TYPICAL APPLICATION CIRCUIT

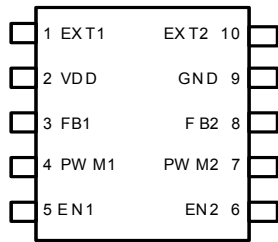
<XC9502B092A Input : 2 cell,  $V_{OUT1}$  : 3.3V,  $V_{OUT2}$  : 1.8V >



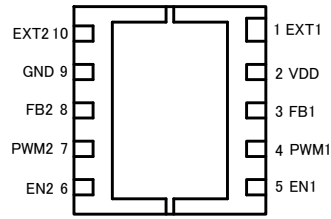
### TYPICAL PERFORMANCE CHARACTERISTICS



## PIN CONFIGURATION



MSOP-10  
(TOP VIEW)



USP-10  
(BOTTOM VIEW)

## PIN ASSIGNMENT

PIN NUMBER	PIN NAME	FUNCTIONS
1	EXT 1	Channel 1: External Transistor Drive Pin <Connected to N-ch Power MOSFET Gate>
2	VDD	Supply Voltage
3	FB1	Channel 1: Output Voltage Monitor Feedback Pin <Threshold value: 0.9V. Output voltage can be set freely by connecting split resistors between VOUT1 and Ground.>
4	PWM1	Channel 1: PWM/PFM Switching Pin <Control Output 1. PWM control when connected to VDD, PWM / PFM auto switching when connected to Ground. >
5	EN1	Channel 1: Enable Pin <Connected to Ground when Output 1 is in stand-by mode. Connected to VDD when Output 1 is active. EXT1 is low when in stand-by mode.>
6	EN2	Channel 2: Enable Pin <Connected to Ground when Output 2 is in stand-by mode. Connected to VDD when Output 2 is active. EXT2/ is high when in stand-by mode.>
7	PWM2	Channel 2: PWM/PFM Switching Pin <Control Output 2. PWM control when connected to VDD, PWM / PFM auto switching when connected to Ground.>
8	FB2	Channel 2: Output Voltage Monitor Feedback Pin <Threshold value: 0.9V. Output voltage can be set freely by connecting split resistors between VOUT2 and Ground.>
9	GND	Ground
10	EXT2/	Channel 2: External Transistor Drive Pin <Connected to P-ch Power MOSFET Gate>

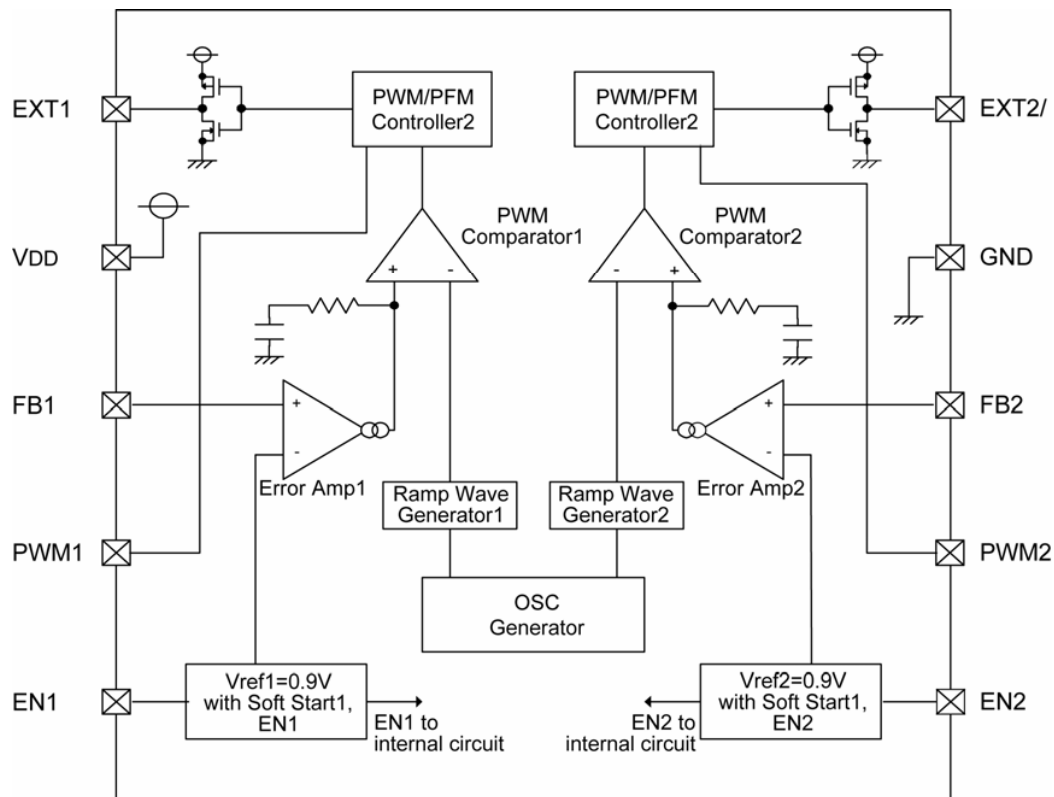
## PRODUCT CLASSIFICATION

Ordering Information

XC9502

DESIGNATOR	DESCRIPTION	SYMBOL	DESCRIPTION
	Type of DC/DC Controller	B	: Standard type (10 pin)
	Output Voltage	09	: FB products =0, =9 fixed
	Oscillation Frequency	2	: 180kHz
		3	: 300kHz (custom)
		5	: 500kHz (custom)
	Package	A	: MSOP-10
		D	: USP-10
	Device Orientation	R	: Embossed tape, standard feed
		L	: Embossed tape, reverse feed

## BLOCK DIAGRAM



## ABSOLUTE MAXIMUM RATINGS

Ta=25

PARAMETER	SYMBOL	RATINGS	UNITS
VDD Pin Voltage	VDD	- 0.3 ~ 12.0	V
FB1, 2 Pin Voltage	VFB	- 0.3 ~ 12.0	V
EN1, 2 Pin Voltage	VEN	- 0.3 ~ 12.0	V
PWM1, 2 Pin Voltage	VPWM	- 0.3 ~ 12.0	V
EXT1, 2 Pin Voltage	VEXT	- 0.3 ~ VDD + 0.3	V
EXT1, 2 Pin Current	IEXT	± 100	mA
Power Dissipation	MSOP-10	Pd	mW
	USP-10		
Operating Temperature Range	Topr	- 40 ~ + 85	°C
Storage Temperature Range	Tstg	- 55 ~ + 125	°C

\* Voltage is all ground standardized.

## ELECTRICAL CHARACTERISTICS

XC9502B092 Common Characteristics

(FOSC=180kHz)

Ta=25

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
Supply Voltage (*1)	VDD		2.0	-	10.0	V	
Maximum Input Voltage	VIN		10.0	-	-	V	
Output Voltage Range (*3)	VOUTSET	VDD 2.0V, IOUT1,2=1mA	VOUT1	0.9	-	-	V
		VDD VOUT1	VOUT2	0.9	-	VIN	V
		VIN 0.9V, IOUT1,2=1mA	VOUT1	2.0	-	10.0	V
		VDD=VOUT1	VOUT2	0.9	-	VIN	V
Supply Current 1	IDD1	FB1, 2=0V	-	70	160	μA	
Supply Current 1-1	IDD1-1	EN1=3.0V, EN2=0V, FB1=0V	-	60	120	μA	
Supply Current 1-2	IDD1-2	EN2=3.0V, EN1=0V, FB2=0V	-	50	110	μA	
Supply Current 1-3	IDD1-3	FB1=0V, FB2=1.0V	-	70	160	μA	
Supply Current 1-4	IDD1-4	FB1=1.0V, FB2=0V	-	60	130	μA	
Supply Current 2	IDD2	FB1, 2=1.0V	-	60	130	μA	
Stand-by Current	ISTB	Same as IDD1, EN1=EN2=0V	-	1.0	3.0	μA	
Oscillation Frequency	FOSC	Same as IDD1	153	180	207	kHz	
EN1, 2 "High" Voltage	VENH	FB1, 2=0V	0.65	-	-	V	
EN1, 2 "Low" Voltage	VENL	FB1, 2=0V	-	-	0.20	V	
EN1, 2 "High" Current	IENH	EN1, 2=3.0V	-	-	0.50	μA	
EN1, 2 "Low" Current	IENL	EN1, 2=0V, FB1, 2=3.0V	-	-	-0.50	μA	
PWM1, 2 "High" Current	IPWMH	FB1, 2=3.0V, PWM=3.0V	-	-	0.50	μA	
PWM1, 2 "Low" Current	IPWML	FB1, 2=3.0V, PWM=0V	-	-	-0.50	μA	
FB1, 2 "High" Current	IFBH	FB1, 2=3.0V	-	-	0.50	μA	
FB1, 2 "Low" Current	VFBL	FB1, 2=1.0V	-	-	-0.50	μA	

Unless otherwise stated, VDD=3.0V, PWM1, 2=3.0V, EN1, 2=3.0V

### Output 1 Characteristics: Step-Up Controller

Ta=25

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
FB1 Voltage	VFB1	VDD=3.0V, VIN=1.5V, IOUT1=10mA	0.882	0.900	0.918	V	
Operation Start Voltage1 (*2)	VST1-1	Using Tr: 2SD1628 IOUT1=1.0mA, RFB11=200k, RFB12=75k	-	-	0.9	V	
		VDD VOUT1: IOUT1=1mA	-	-	2.0	V	
Oscillation Start-up Voltage1	VST2-1	FB1=0V	-	-	0.8	V	
Maximum Duty Ratio1	MAXDTY1	Same as IDD1	75	80	85	%	
Minimum Duty Ratio1	MINDTY1	Same as IDD2	-	-	0	%	
PFM Duty Ratio1	PFMDTY1	No Load, VPWM1=0V	22	30	38	%	
Efficiency 1 (*4)	EFFI1	IOUT1=30mA, N-ch MOSFET: XP161A1355P	-	85	-	%	
Soft-Start Time1	TSS1	VOUT1 × 0.95V, EN1=0V 0.65V	5.0	10.0	20.0	ms	
EXT1 "High" ON Resistance	REXTBH1	FB1=0, EXT1=VDD-0.4V	-	28	47		
EXT1 "Low" ON Resistance	REXTBL1	EN1=FB2=0V, EXT1=0.4V	-	22	30		
PWM1 "High" Voltage	VPWMH1	No Load	0.65	-	-	V	
PWM1 "Low" Voltage	VPWML1	No Load	-	-	0.20	V	

Unless otherwise stated, VDD=EN1=PWM1=3.0V, EN2=PWM2=GND, EXT2=OPEN, FB2=OPEN, VIN=1.8V

### Output 2 Characteristics: Step-Down Controller

Ta=25

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
FB 2 Voltage	VFB2	VIN=3.0V, IOUT2=10mA	0.882	0.900	0.918	V	
Minimum Operating Voltage	VINmin		-	-	2.0	V	
Maximum Duty Ratio 2	MAXDTY2	Same as IDD1	100	-	-	%	
Minimum Duty Ratio 2	MINDTY2	Same as IDD2	-	-	0	%	
PFM Duty Ratio 2	PFMDTY2	No Load, VPWM2=0V	22	30	38	%	
Efficiency 2 (*4)	EFFI2	IOUT2=250mA P-ch MOSFET: XP162A12A6P	-	92	-	%	
Soft-Start Time 2	TSS2	VOUT2 × 0.95V, EN2=0V 0.65V	5.0	10.0	20.0	ms	
EXT2 "High" ON Resistance	REXTBH2	EN2=0, EXT2=VDD-0.4V	-	28	47		
EXT2 "Low" ON Resistance	REXTBL2	FB2=0V, EXT2=0.4V	-	22	30		
PWM2 "High" Voltage	VPWMH2	No Load	0.65	-	-	V	
PWM2 "Low" Voltage	VPWML2	No Load	-	-	0.20	V	

Unless otherwise stated, VDD=EN2=PWM2=3.0V, PWM1=EN1=GND, EXT1=OPEN, FB1=OPEN, VIN=5.0V

NOTE: \*1 : Although the IC's step-up operations start from a VDD of 0.8V, the output voltage and switching frequency are stabilized at VDD 2.0V. Therefore, a VDD of more than 2.0V is recommended when VDD is supplied from VIN or other power sources.

\*2 : Although the IC's switching operations start from a VIN of 0.9V, the IC's power supply pin (VDD) and output voltage monitor pin (FB1) should be connected to VOUT1. With operations from VIN=0.9V, the 2nd channel's (output 2) EN2 pin should be set to chip disable. Once output voltage VOUT1 is more than 2.0V, the EN2 pin should be set to chip enable.

\*3 : Please be careful not to exceed the breakdown voltage level of the external components.

\*4 :  $EFFI = \left\{ \frac{(\text{Output voltage}) \times (\text{Output current})}{(\text{Input voltage}) \times (\text{Input current})} \right\} \times 100$

## ELECTRICAL CHARACTERISTICS (Continued)

XC9502B093 Common Characteristics (FOSC=300kHz) Ta=25

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
Supply Voltage (*1)	V <sub>DD</sub>		2.0	-	10.0	V	
Maximum put Voltage	V <sub>IN</sub>		10.0	-	-	V	
Output Voltage Range (*3)	V <sub>OUTSET</sub>	V <sub>DD</sub> 0V, I <sub>OUT1,2</sub> =1mA	V <sub>OUT1</sub>	0.9	-	-	V
		V <sub>DD</sub> V <sub>OUT1</sub>	V <sub>OUT2</sub>	0.9	-	V <sub>IN</sub>	V
		V <sub>IN</sub> 0.9V, I <sub>OUT1,2</sub> =1mA	V <sub>OUT1</sub>	2.0	-	10.0	V
		V <sub>DD</sub> =V <sub>OUT1</sub>	V <sub>OUT2</sub>	0.9	-	V <sub>IN</sub>	V
Supply Current 1	I <sub>DD1</sub>	FB1, 2=0V	-	100	190	μA	
Supply Current 1-1	I <sub>DD1-1</sub>	EN1=3.0V, EN2=0V, FB1=0V	-	80	150	μA	
Supply Current 1-2	I <sub>DD1-2</sub>	EN2=3.0V, EN1=0V, FB2=0V	-	60	120	μA	
Supply Current 1-3	I <sub>DD1-3</sub>	FB1=0V, FB2=1.0V	-	100	190	μA	
Supply Current 1-4	I <sub>DD1-4</sub>	FB1=1.0V, FB2=0V	-	70	150	μA	
Supply Current 2	I <sub>DD2</sub>	FB1, 2=1.0V	-	70	150	μA	
Stand-by Current	I <sub>STB</sub>	Same as I <sub>DD1</sub> , EN1=EN2=0V	-	1.0	3.0	μA	
Oscillation Frequency	FOSC	Same as I <sub>DD1</sub>	255	300	345	kHz	
EN1, 2 "High" Voltage	V <sub>ENH</sub>	FB1, 2=0V	0.65	-	-	V	
EN1, 2 "Low" Voltage	V <sub>ENL</sub>	FB1, 2=0V	-	-	0.20	V	
EN1, 2 "High" Current	I <sub>ENH</sub>	EN1, 2=3.0V	-	-	0.50	μA	
EN1, 2 "Low" Current	I <sub>ENL</sub>	EN1, 2=0V, FB1, 2=3.0V	-	-	-0.50	μA	
PWM1, 2 "High" Current	I <sub>PWMH</sub>	FB1, 2=3.0V, PWM=3.0V	-	-	0.50	μA	
PWM1, 2 "Low" Current	I <sub>PWML</sub>	FB1, 2=3.0V, PWM=0V	-	-	-0.50	μA	
FB1, 2 "High" Current	I <sub>FBH</sub>	FB1, 2=3.0V	-	-	0.50	μA	
FB1, 2 "Low" Current	V <sub>FBL</sub>	FB1, 2=1.0V	-	-	-0.50	μA	

Unless otherwise stated. V<sub>DD</sub>=3.0V. PWM1,2=3.0V. EN1, 2 =3.0V

### Output 1 Characteristics: Step-Up Controller

Ta=25

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
FB1 Voltage	V <sub>FB1</sub>	V <sub>DD</sub> =3.0V, V <sub>IN</sub> =1.5V, I <sub>OUT1</sub> =10mA	0.882	0.900	0.918	V	
Operation Start Voltage (*2)	V <sub>ST1-1</sub>	Using Tr: 2SD1628	-	-	0.9	V	
		I <sub>OUT1</sub> =1.0mA, R <sub>FB11</sub> =200k, R <sub>FB12</sub> =75k	-	-	2.0	V	
		V <sub>DD</sub> V <sub>OUT1</sub> : I <sub>OUT1</sub> =1mA	-	-	2.0	V	
Oscillation Start Voltage2	V <sub>ST2-1</sub>	FB1=0V	-	-	0.8	V	
Maximum Duty Ratio	MAXD <sub>TY1</sub>	Same as I <sub>DD1</sub>	75	80	85	%	
Minimum Duty Ratio	MIND <sub>TY1</sub>	Same as I <sub>DD2</sub>	-	-	0	%	
PFM Duty Ratio	PFMD <sub>TY1</sub>	No Load, V <sub>PWM1</sub> =0V	22	30	38	%	
Efficiency (*4)	EFF <sub>11</sub>	I <sub>OUT</sub> =130mA N-ch MOSFET: XP161A1355P	-	85	-	%	
Soft-Start Time	T <sub>SS1</sub>	V <sub>OUT1</sub> × 0.95V, EN1=0V 0.65V	5.0	10.0	20.0	ms	
EXT1 "High" ON Resistance	R <sub>EXTBH1</sub>	FB1=0, EXT1=V <sub>DD</sub> -0.4V	-	28	47		
EXT1 "Low" ON Resistance	R <sub>EXTBL1</sub>	EN1=FB2=0V, EXT1=0.4V	-	22	30		
PWM1 "High" Voltage	V <sub>PWMH1</sub>	No Load	0.65	-	-	V	
PWM1 "Low" Voltage	V <sub>PWML1</sub>	No Load	-	-	0.20	V	

Unless otherwise stated, V<sub>DD</sub>=EN1=PWM1=3.0V, EN2=PWM2=GND, EXT2=OPEN, FB2=OPEN, V<sub>IN</sub>=1.8V

### Output 2 Characteristics: Step-Down Controller

Ta=25

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
FB2 Voltage	V <sub>FB2</sub>	V <sub>IN</sub> =3.0V, I <sub>OUT2</sub> =10mA	0.900	0.900	0.900	V	
Minimum Operating Voltage	V <sub>INmin</sub>		-	-	2.0	V	
Maximum Duty Ratio 2	MAXD <sub>TY2</sub>	Same as I <sub>DD1</sub>	100	-	-	%	
Minimum Duty Ratio 2	MIND <sub>TY2</sub>	Same as I <sub>DD2</sub>	-	-	0	%	
PFM Duty Ratio 2	PFMD <sub>TY2</sub>	No Load, V <sub>PWM2</sub> =0V	22	30	38	%	
Efficiency 2 (*4)	EFF <sub>12</sub>	I <sub>OUT2</sub> =250mA P-ch MOSFET: XP162A12A6P	-	92	-	%	
Soft-Start Time 2	T <sub>SS2</sub>	V <sub>OUT2</sub> × 0.95V, EN2=0V 0.65V	5.0	10.0	20.0	ms	
EXT2 "High" ON Resistance	R <sub>EXTBH2</sub>	EN2=0, EXT2=V <sub>DD</sub> -0.4V	-	28	47		
EXT2 "Low" ON Resistance	R <sub>EXTBL2</sub>	FB2=0V, EXT2=0.4V	-	22	30		
PWM2 "High" Voltage	V <sub>PWMH2</sub>	No Load	0.7	-	-	V	
PWM2 "Low" Voltage	V <sub>PWML2</sub>	No Load	-	-	0.20	V	

Unless otherwise stated, V<sub>DD</sub>=EN2=PWM2=3.0V, PWM1=EN1=GND, EXT1=OPEN, FB1=OPEN, V<sub>IN</sub>=5.0V

NOTE: \*1 : Although the IC's step-up operations start from a V<sub>DD</sub> of 0.8V, the output voltage and switching frequency are stabilized at V<sub>DD</sub> 2.0V. Therefore, a V<sub>DD</sub> of more than 2.0V is recommended when V<sub>DD</sub> is supplied from V<sub>IN</sub> or other power sources.

\*2 : Although the IC's switching operations start from a V<sub>IN</sub> of 0.9V, the IC's power supply pin (V<sub>DD</sub>) and output voltage monitor pin (FB1) should be connected to V<sub>OUT1</sub>. With operations from V<sub>IN</sub>=0.9V, the 2nd channel's (output 2) EN2 pin should be set to chip disable. Once output voltage V<sub>OUT1</sub> is more than 2.0V, the EN2 pin should be set to chip enable.

\*3 : Please be careful not to exceed the breakdown voltage level of the external components.

\*4 : EFFI=[ (output voltage) × (output current) ] / [ (input voltage) × (input current) ] × 100

## ELECTRICAL CHARACTERISTICS (Continued)

XC9502B095 Common Characteristics (FOSC=500kHz) Ta=25

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
Supply Voltage (*1)	V <sub>DD</sub>		2.0	-	10.0	V	
Maximum Input Voltage	V <sub>IN</sub>		10.0	-	-	V	
Output Voltage Range (*3)	V <sub>OUTSET</sub>	V <sub>DD</sub> = 2.0V, I <sub>OUT1,2</sub> = 1mA	V <sub>OUT1</sub>	0.9	-	-	V
		V <sub>DD</sub> ≠ V <sub>OUT1</sub>	V <sub>OUT2</sub>	0.9	-	V <sub>IN</sub>	V
		V <sub>IN</sub> = 0.9V, I <sub>OUT1,2</sub> = 1mA	V <sub>OUT1</sub>	2.0	-	10.0	V
		V <sub>DD</sub> = V <sub>OUT1</sub>	V <sub>OUT2</sub>	0.9	-	V <sub>IN</sub>	V
Supply Current 1	I <sub>DD1</sub>	FB1, 2=0V	-	130	250	μA	
Supply Current 1-1	I <sub>DD1-1</sub>	EN1=3.0V, EN2=0V, FB1=0V	-	110	220	μA	
Supply Current 1-2	I <sub>DD1-2</sub>	EN2=3.0V, EN1=0V, FB2=0V	-	80	150	μA	
Supply Current 1-3	I <sub>DD1-3</sub>	FB1=0V, FB2=1.0V	-	130	240	μA	
Supply Current 1-4	I <sub>DD1-4</sub>	FB1=1.0V, FB2=0V	-	90	190	μA	
Supply Current 2	I <sub>DD2</sub>	FB1, 2=1.0V	-	90	190	μA	
Stand-by Current	I <sub>STB</sub>	Same as I <sub>DD1</sub> , EN1=EN2=0V	-	1.0	3.0	μA	
Oscillation Frequency	FOSC	Same as I <sub>DD1</sub>	425	500	575	kHz	
EN1, 2 "High" Voltage	V <sub>ENH</sub>	FB1, 2=0V	0.65	-	-	V	
EN1, 2 "Low" Voltage	V <sub>ENL</sub>	FB1, 2=0V	-	-	0.20	V	
EN1, 2 "High" Current	I <sub>ENH</sub>	EN1, 2=3.0V	-	-	0.50	μA	
EN1, 2 "Low" Current	I <sub>ENL</sub>	EN1, 2=0V, FB1, 2=3.0V	-	-	-0.50	μA	
PWM1, 2 "High" Current	I <sub>PWMH</sub>	FB1, 2=3.0V, PWM=3.0V	-	-	0.50	μA	
PWM1, 2 "Low" Current	I <sub>PWML</sub>	FB1, 2=3.0V, PWM=0V	-	-	-0.50	μA	
FB1, 2 "High" Current	I <sub>FBH</sub>	FB1, 2=3.0V	-	-	0.50	μA	
FB1, 2 "Low" Current	I <sub>FBL</sub>	FB1, 2=1.0V	-	-	-0.50	μA	

Unless otherwise stated, V<sub>DD</sub>=3.0V, PWM1, 2=3.0V, EN1, 2 = 3.0V

### Output 1 Characteristics: Step-Up Controller

Ta=25

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
FB 1 Voltage	V <sub>FB1</sub>	V <sub>DD</sub> =3.0V, V <sub>IN</sub> =1.5V, I <sub>OUT1</sub> =10mA	0.882	0.900	0.918	V	
Operation Start Voltage 1 (*2)	V <sub>ST1-1</sub>	Using Tr: 2SD1628 I <sub>OUT1</sub> =1.0mA, R <sub>FB11</sub> =200k, R <sub>FB12</sub> =75k	-	-	0.9	V	
		V <sub>DD</sub> V <sub>OUT1</sub> : I <sub>OUT1</sub> =1mA	-	-	2.0	V	
Oscillation Start Voltage 2	V <sub>ST2-1</sub>	FB1=0V	-	-	0.8	V	
Maximum Duty Ratio 1	MAXD <sub>TY1</sub>	Same as I <sub>DD1</sub>	75	80	85	%	
Minimum Duty Ratio 1	MIND <sub>TY1</sub>	Same as I <sub>DD2</sub>	-	-	0	%	
PFM Duty Ratio 1	PFMD <sub>TY1</sub>	No Load, V <sub>PWM1</sub> =0V	22	30	38	%	
Efficiency 1 (*4)	EFF11	I <sub>OUT</sub> =130mA N-ch MOSFET: XP161A1355P	-	83	-	%	
Soft-Start Time 1	T <sub>SS1</sub>	V <sub>OUT1</sub> × 0.95V, EN1=0V 0.65V	5.0	10.0	20.0	ms	
EXT1 "High" ON Resistance	R <sub>EXTBH1</sub>	FB1=0, EXT1=V <sub>DD</sub> -0.4V	-	28	47		
EXT1 "Low" ON Resistance	R <sub>EXTBL1</sub>	EN1=FB2=0V, EXT1=0.4V	-	22	30		
PWM1 "High" Voltage	V <sub>PWMH1</sub>	No Load	0.65	-	-	V	
PWM1 "Low" Voltage	V <sub>PWML1</sub>	No Load	-	-	0.20	V	

Unless otherwise stated, V<sub>DD</sub>=EN1=PWM1=3.0V, EN2=PWM2=GND, EXT2=OPEN, FB2=OPEN, V<sub>IN</sub>=1.8V

### Output 2 Characteristics: Step-Down Controller

Ta=25

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
FB 2 Voltage	V <sub>FB2</sub>	V <sub>IN</sub> =3.0V, I <sub>OUT2</sub> =10mA	0.882	0.900	0.918	V	
Minimum Operating Voltage	V <sub>INmin</sub>		-	-	2.0	V	
Maximum Duty Ratio 2	MAXD <sub>TY2</sub>	Same as I <sub>DD1</sub>	100	-	-	%	
Minimum Duty Ratio 2	MIND <sub>TY2</sub>	Same as I <sub>DD2</sub>	-	-	0	%	
PFM Duty Ratio 2	PFMD <sub>TY2</sub>	No Load, V <sub>PWM2</sub> =0V	22	30	38	%	
Efficiency 2 (*4)	EFFI2	I <sub>OUT2</sub> =250mA P-ch MOSFET: XP162A12A6P	-	91	-	%	
Soft-Start Time 2	T <sub>SS2</sub>	V <sub>OUT2</sub> × 0.95V, EN2=0V 0.65V	5.0	10.0	20.0	ms	
EXT2 "High" ON Resistance	R <sub>EXTBH2</sub>	EN2=0, EXT2=V <sub>DD</sub> -0.4V	-	28	47		
EXT2 "Low" ON Resistance	R <sub>EXTBL2</sub>	FB2=0V, EXT2=0.4V	-	22	30		
PWM2 "High" Voltage	V <sub>PWMH2</sub>	No Load	0.65	-	-	V	
PWM2 "Low" Voltage	V <sub>PWML2</sub>	No Load	-	-	0.20	V	

Unless otherwise stated, V<sub>DD</sub>=EN2=PWM2=3.0V, PWM1=EN1=GND, EXT1=OPEN, FB1=OPEN, V<sub>IN</sub>=5.0V

NOTE: \*1 : Although the IC's step-up operations start from a V<sub>DD</sub> of 0.8V, the output voltage and switching frequency are stabilized at V<sub>DD</sub> 2.0V. Therefore, a V<sub>DD</sub> of more than 2.0V is recommended when V<sub>DD</sub> is supplied from V<sub>IN</sub> or other power sources.

\*2 : Although the IC's switching operations start from a V<sub>IN</sub> of 0.9V, the IC's power supply pin (V<sub>DD</sub>) and output voltage monitor pin (FB1) should be connected to V<sub>OUT1</sub>. With operations from V<sub>IN</sub>=0.9V, the 2nd channel's (output 2) EN2 pin should be set to chip disable. Once output voltage V<sub>OUT1</sub> is more than 2.0V, the EN2 pin should be set to chip enable.

\*3 : Please be careful not to exceed the breakdown voltage level of the external components.

\*4 : EFFI={ [(output voltage) × (output current)] / [(input voltage) × (input current)] } × 100

## OPERATIONAL EXPLANATION

The XC9502 series are multi-functional, 2 channel step-up and down DC/DC converter controller ICs with built-in high speed, low ON resistance drivers.

### <Error Amp. >

The error amplifier is designed to monitor the output voltage and it compares the feedback voltage (FB) with the reference voltage. In response to feedback of a voltage lower than the reference voltage, the output voltage of the error amp. decreases.

### <OSC Generator>

This circuit generates the switching frequency, which in turn generates the reference clock.

### <Ramp Wave Generator 1, 2>

The ramp wave generator generates a saw-tooth waveform based on outputs from the Phase Shift Generator.

### <PWM Comparator 1, 2>

The PWM comparator compares outputs from the error amp. and saw-tooth waveform. When the voltage from the error amp's output is low, the external switch will be set to ON.

### <PWM/PFM Controller 1, 2>

This circuit generates PFM pulses.

Control can be switched between PWM control and PWM/PFM automatic switching control using external signals.

The PWM/PFM automatic switching mode is selected when the voltage of the PWM1 (2) pin is less than 0.2V, and the control switches between PWM and PFM automatically depending on the load. As the PFM circuit generates pulses based on outputs from the PWM comparator, shifting between modes occurs smoothly. PWM control mode is selected when the voltage of the PWM1 (2) pin is more than 0.65V. Noise is easily reduced with PWM control since the switching frequency is fixed. Control suited to the application can easily be selected which is useful in audio applications, for example, where traditionally, efficiencies have been sacrificed during stand-by as a result of using PWM control (due to the noise problems associated with the PFM mode in stand-by).

### <Vref with Soft Start 1, 2>

The reference voltage, Vref (FB pin voltage)=0.9V, is adjusted and fixed by laser trimming (for output voltage settings, please refer to the notes on next page). To protect against inrush current, when the power is switched on, and also to protect against voltage overshoot, soft-start time is set internally to 10ms. It should be noted, however, that this circuit does not protect the load capacitor (CL) from inrush current. With the Vref voltage limited and depending upon the input to the error amps, the operation maintains a balance between the two inputs of the error amps and controls the EXT pin's ON time so that it doesn't increase more than is necessary.

### <Chip Enable Function>

This function controls the operation and shutdown of the IC. When the voltage of the EN1 or EN2 pins is 0.2V or less, the mode will be chip disable, the channel's operations will stop and the EXT1 pin will be kept at a low level (the external N-ch MOSFET will be OFF) and the EXT2 pin will be kept at a high level (the external P-type MOSFET will be OFF). When both EN1 and EN2 are in a state of chip disable, current consumption will be no more than 3.0  $\mu$ A.

When the EN1 or EN2 pin's voltage is 0.65V or more, the mode will be chip enable and operations will recommence. With soft-start, 95% of the set output voltage will be reached within 10ms (TYP.) from the moment of chip enable.

Although IC starts oscillation from a  $V_{IN}$  of 0.9V, the IC's power supply pin ( $V_{DD}$ ) and the output voltage monitor pin (FB1) should be connected to  $V_{OUT1}$ . The start-up sequence for EN1 and EN2 is required when operations begin with a power supply voltage of  $V_{DD}$ =0.9V, and channel two's (output 2) EN2 pin should be set to chip disable and turn it to enable when  $V_{OUT1}$  is more than 2.0V. For power supply voltages of  $V_{DD}$ <2.0V, oscillation may occur irrespective of the FB pin voltage. Should this happen, you may find that output voltage will be higher than the set voltage. The FB pin voltage and the reference voltage Vref will be compared and output voltage will be controlled when the power supply voltage is  $V_{DD}$ >2.0V or more. With power supply voltages of  $V_{DD}$ >2.0V, the start-up sequence for EN1 and EN2 will not be required.

## OPERATIONAL EXPLANATION (Continued)

### <Setting of Output Voltage>

Output voltage can be set by adding external split resistors. Output voltage is determined by the following equation, based on the values of RFB11 (RFB21) and RFB12 (RFB22). The sum of RFB11 (RFB21) and RFB12 (RFB22) should normally be 1M or less.

$$V_{OUT} = 0.9 \times (R_{FB11} + R_{FB12}) / R_{FB12}$$

The value of CFB1 (CFB2), speed-up capacitor for phase compensation, should be  $f_{zfb} = 1 / (2 \times \dots \times C_{FB1} \times R_{FB11})$  which is equal to 12kHz. Adjustments are required from 1kHz to 50kHz depending on the application, value of inductance (L), and value of load capacity (CL).

### [Example of Calculation]

When  $R_{FB11} = 200k$  and  $R_{FB12} = 75k$ ,  $V_{OUT1} = 0.9 \times (200k + 75k) / 75k = 3.3V$ .

### [Typical Example]

VOUT (V)	RFB11 (k)	RFB12 (k)	CFB1 (pF)	VOUT (V)	RFB11 (k)	RFB12 (k)	CFB1 (pF)	VOUT (V)	RFB11 (k)	RFB12 (k)	CFB1 (pF)
1.0	30	270	430	2.5	390	220	33	8.0	120	15	100
1.5	220	330	62	2.7	360	180	33	12.0	160	13	82
1.8	220	220	62	3.0	560	240	24	-	-	-	-
2.0	330	270	39	3.3	200	75	62	-	-	-	-
2.2	390	270	33	5.0	82	18	160	-	-	-	-

The same method can be also adopted for channel two (output 2).

### [External Components]

#### Output 1 (Step-Up DC/DC controller)

Tr 1: \* MOSFET

XP161A1355PR (N-ch Power MOSFET, TOREX)

Note: V<sub>GS</sub> Breakdown Voltage of this Tr. is 8V so please be careful with the power supply voltage. For 6V power supply voltage, XP161A1265PR which V<sub>GS</sub> breakdown voltage is 12V is recommended. V<sub>ST1</sub> of XP161A1355PR is 1.2V (MAX.) and that of XP161A1265PR is 1.5V (MAX.)

SD 1: MA2Q737 (Schottky, MATSUSHITA)  
CMS02 (Schottky, TOSHIBA)

L 1: 10 μH (CDRH5D28, SUMIDA, FOSC = 500kHz)  
15 μH (CDRH5D28, SUMIDA, FOSC = 300kHz)  
22 μH (CDRH5D28, SUMIDA, FOSC = 180kHz)

CL1: 16V, 47 μF (Tantalum)

Increase capacity according to the equation below when the step-up voltage ratio is large and output current is high.

$$C = (CL \text{ standard value}) \times (I_{OUT1}(\text{mA}) / 300\text{mA} \times V_{OUT1} / V_{IN})$$

Tr: \* NPN MOSFET 2SD1628 (SANYO)

RB1: 500 (Adjust in accordance with load & Tr.'s HFE.)  
Set according to the equation below:

$$R_{B1} = (V_{IN} - 0.7) \times h_{FE} / I_{C-REXTBH}$$

CB1: 2200pF (Ceramic)

Set according to the equation below:

$$C_{B1} = (2 \times R_{B2} \times FOSC \times 0.7)$$

#### Output 2 (Step-Down DC/DC controller)

Tr 2: \* MOSFET

XP162A12A6P (P-ch Power MOSFET, TOREX)

Note: V<sub>GS</sub> Breakdown Voltage of this Tr. is 12V so please be careful with the power supply voltage.

SD 2: MA2Q737 (Schottky, MATSUSHITA)  
CMS02 (Schottky, TOSHIBA)

L 2: 10 μH (CDRH5D28, SUMIDA, FOSC = 500kHz)  
22 μH (CDRH5D28, SUMIDA, FOSC = 300kHz)  
47 μH (CDRH5D28, SUMIDA, FOSC = 180kHz)

CL1: 16V, 47 μF (Tantalum)

Increase capacity according to the equation below when the step-up voltage ratio is large and output current is high.

$$C = (CL \text{ standard value}) \times (I_{OUT2}(\text{mA}) / 500\text{mA} \times V_{OUT2} / V_{IN})$$

Tr: \* PNP MOSFET 2SA1213 (SANYO)

RB1: 500 (Adjust in accordance with load & Tr.'s HFE.)  
Set according to the equation below:

$$R_{B2} = (V_{IN} - 0.7) \times h_{FE} / I_{C-REXTBH}$$

CB1: 2200pF (Ceramic)

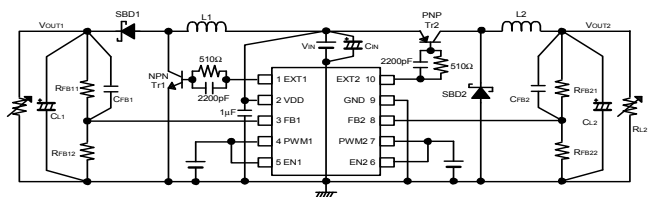
Set according to the equation below:

$$C_{B2} = (2 \times R_{B2} \times FOSC \times 0.7)$$

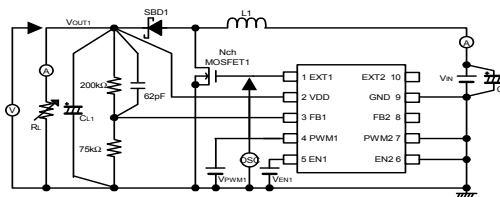


# TEST CIRCUITS

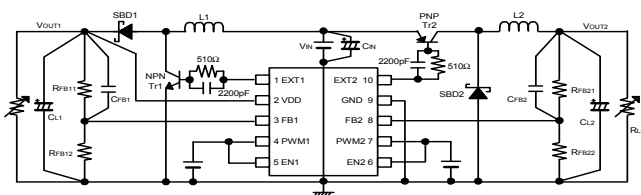
Circuit



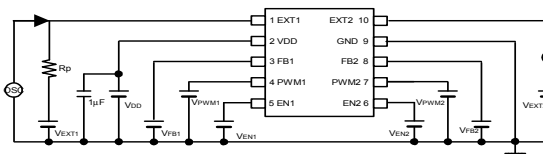
Circuit



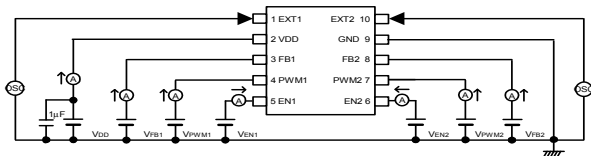
Circuit



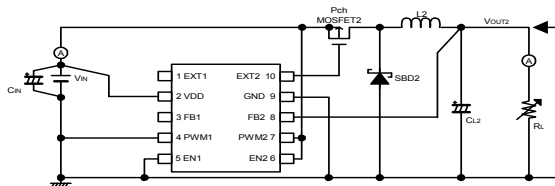
Circuit



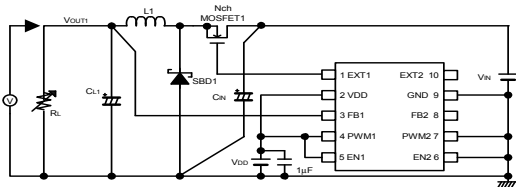
Circuit



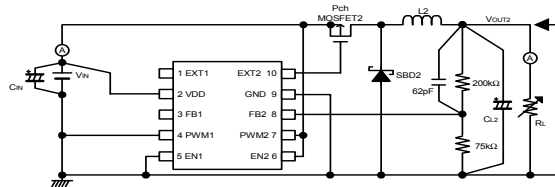
Circuit



Circuit



Circuit



## EXTERNAL COMPONENTS USED FOR TEST CIRCUITS

Circuit	L1, L2:	22 $\mu$ H (CDRH5D28, SUMIDA)	: XC9502B092A
		15 $\mu$ H (CDRH5D28, SUMIDA)	: XC9502B093A
		10 $\mu$ H (CDRH5D28, SUMIDA)	: XC9502B095A
	SD1, SD2:	CRS02 (Schottky diode, TOSHIBA)	
		EC10QS06 (Schottky diode, NIHON INTER)	
	CL1, CL2:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
		35MCE335MB2 x 3 (Tantalum, NIHON CHEMICON)	
	CIN:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	NPN Tr1:	2SD1628 (SANYO)	
	PNP Tr1:	2SA1213 (TOSHIBA)	
RFB:	Please use by the conditions as below:		
	$RFB11 + RFB12 \leq 1M$		
	$RFB21 + RFB22 \leq 1M$		
	$RFB11 / RFB12 = (\text{Setting output voltage} / 0.9) - 1$		
	$VOUT2 = (0.9 - VOUT1) \times (RFB21/RFB22) + 0.9V$		
CFB:	Please adjust as below:		
	$fxfb = 1 / (2 \times \pi \times CFB1 \times RFB11) = 1kHz \sim 50kHz$ (12kHz usual)		
	$fxfb = 1 / (2 \times \pi \times CFB2 \times RFB21) = 1kHz \sim 50kHz$ (12kHz usual)		
Circuit	L1:	22 $\mu$ H (CDRH5D28, SUMIDA)	
	SD1:	MA2Q737 (Schottky diode, MATSUSHITA)	
	CL1:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	CIN:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	N-ch MOSFET1:	XP161A1355P (TOREX)	
Circuit	L1:	22 $\mu$ H (CDRH5D28, SUMIDA)	: XC9502B092A
		15 $\mu$ H (CDRH5D28, SUMIDA)	: XC9502B093A
		10 $\mu$ H (CDRH5D28, SUMIDA)	: XC9502B095A
	SD1:	MA2Q737 (Schottky diode, MATSUSHITA)	
	CL1:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	CIN:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	N-ch MOSFET1:	XP161A1355P (TOREX)	
Circuit	L1:	22 $\mu$ H (CDRH5D28, SUMIDA)	
	SD1:	MA2Q737 (Schottky diode, MATSUSHITA)	
	CL1:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	CIN:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	P-ch MOSFET2:	XP162A12A6P (TOREX)	
Circuit	L2:	22 $\mu$ H (CDRH5D28, SUMIDA)	: XC9502B092A
		15 $\mu$ H (CDRH5D28, SUMIDA)	: XC9502B093A
		10 $\mu$ H (CDRH5D28, SUMIDA)	: XC9502B095A
	SD2:	MA2Q737 (Schottky diode, MATSUSHITA)	
	CL2:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	CIN:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	P-ch MOSFET2:	XP162A12A6P (TOREX)	

## NOTES ON USE

### 1. Checking for Intermittent Oscillation

The XC9502 series is subject to intermittent oscillation in the proximity of the maximum duty if the step-down ratio is low (e.g., from 4.2 V to 3.3 V) or a heavy load is applied where the duty ratio becomes high. Check waveforms at EXT under your operating conditions. A remedy for this problem is to raise the inductance of coil L or increase the load capacitance CL.

### 2. PWM/PFM Automatic Switching

If PWM/PFM automatic switching control is selected and the step-up ratio is low (e.g., from 4.5V to 5.0V) or the step-down ratio is high (e.g., from 10.0V to 1.0 V), the control mode remains in PFM setting in the whole load range, since the duty ratio under continuous-duty condition is smaller than the PFM duty ratio of the XC9502 series. The output voltage's ripple voltage becomes substantially high under heavy load conditions, with the XC9502 series appearing to be producing an abnormal oscillation. If this operation becomes a concern, set pins PWM1 and PWM2 to High to set the control mode to PWM setting. For use under the above-mentioned condition, measured data of PWM/PFM automatic switching control shown on the data sheets are available up to  $I_{OUT} = 100 \text{ mA}$ .

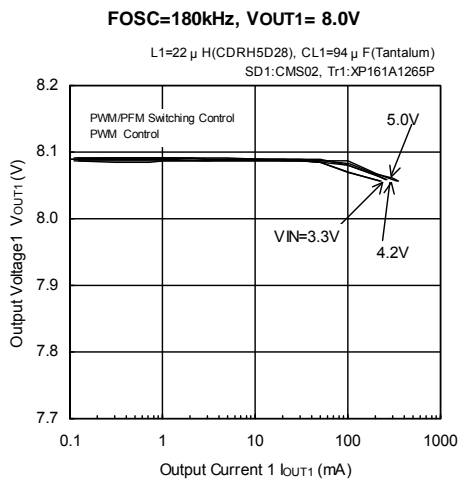
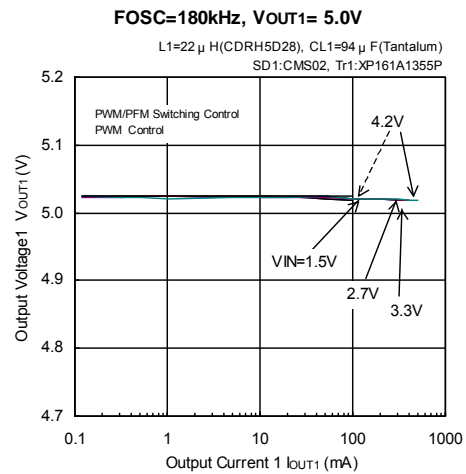
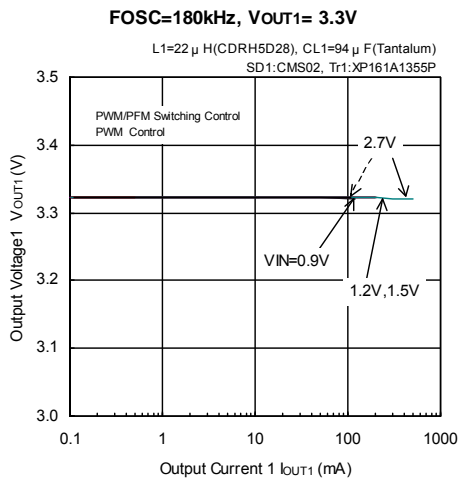
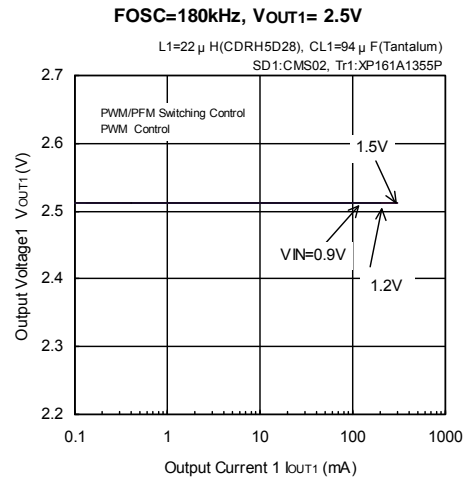
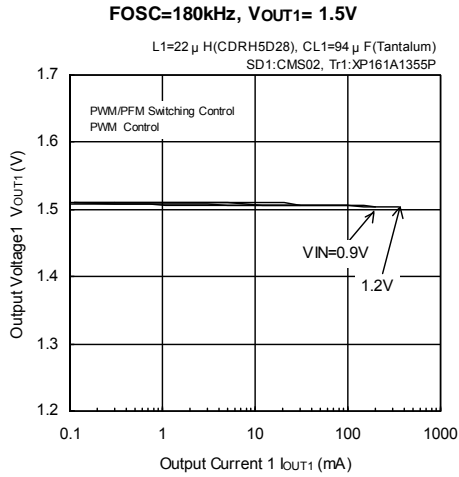
### 3. Ratings

Use the XC9502 series and external components within the limits of their ratings.

## TYPICAL PERFORMANCE CHARACTERISTICS

### < 1ch Step-Up DC/DC Controller >

#### (1) Output Voltage vs. Output Current

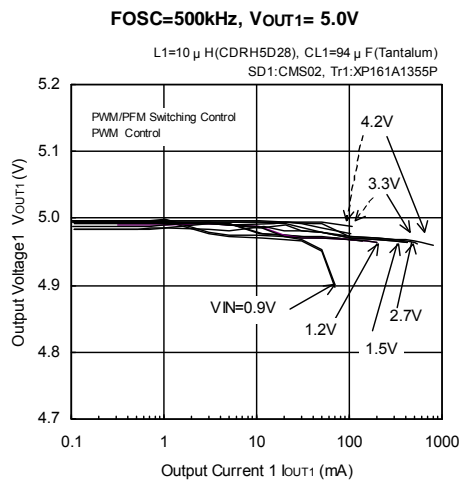
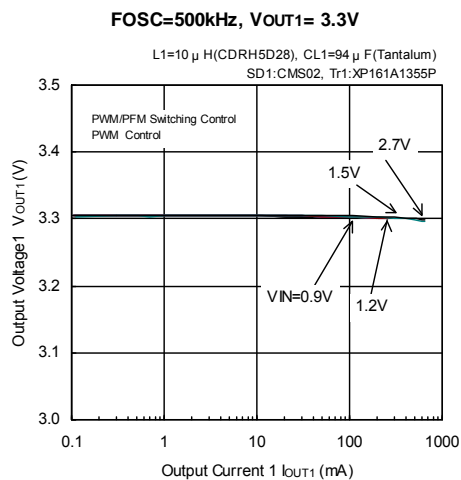
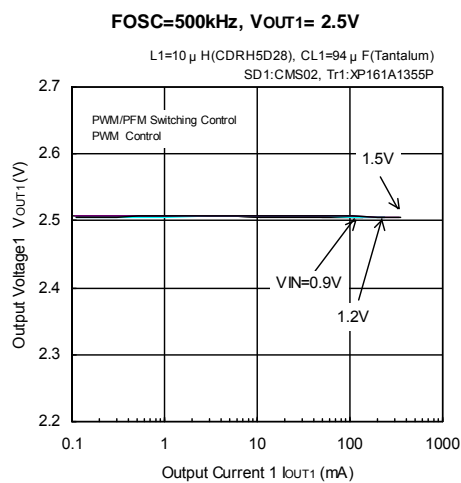
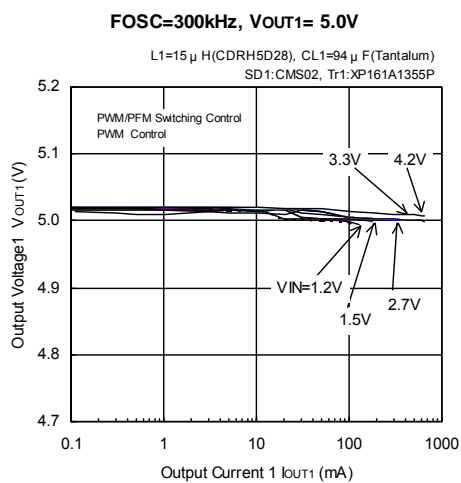
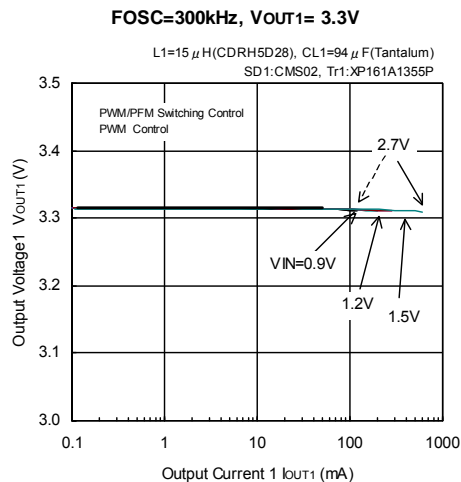
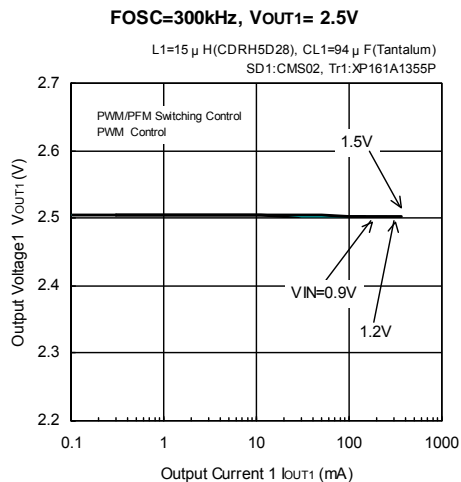


Dotted Arrowhead -----> PWM/PFM Switching Control

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### < 1ch Step-Up DC/DC Controller >

#### (1) Output Voltage vs. Output Current (Continued)

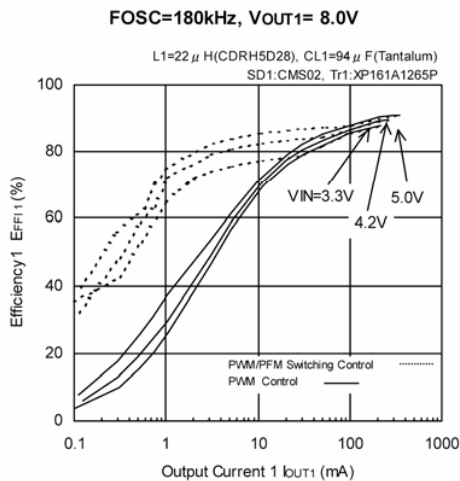
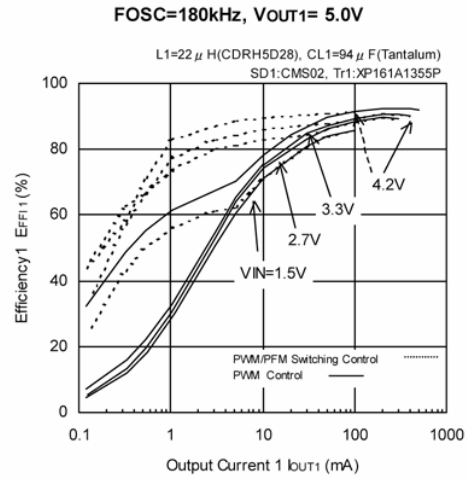
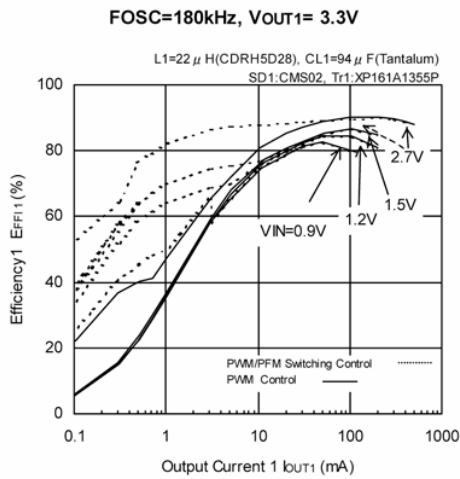
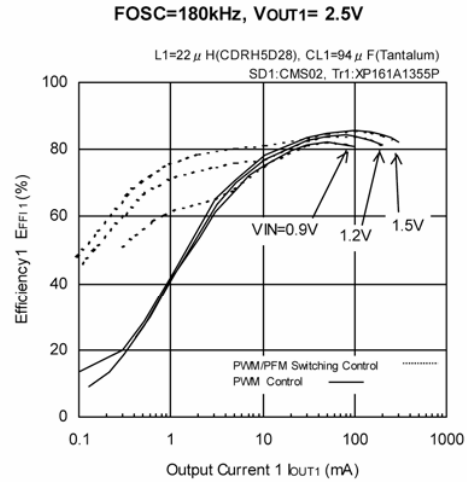
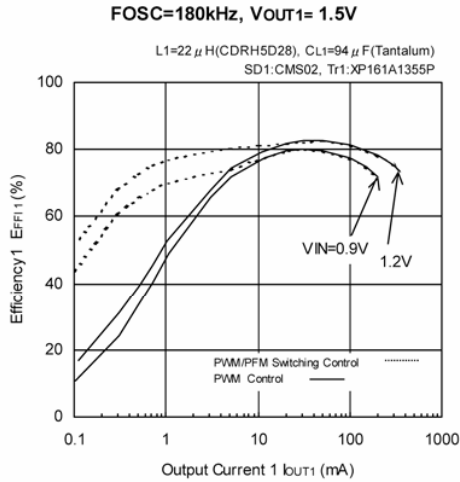


Dotted Arrowhead ----> PWM/PFM Switching Control

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### < 1ch Step-Up DC/DC Controller >

#### (2) Efficiency vs. Output Current

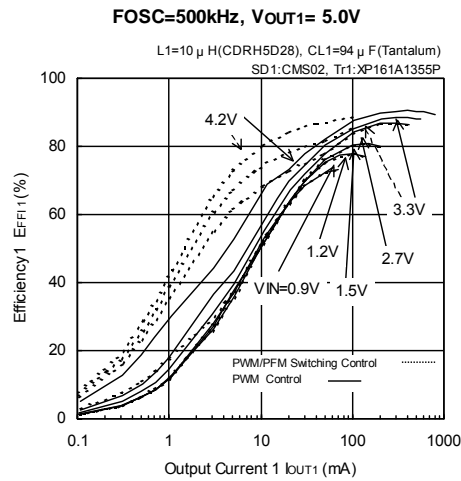
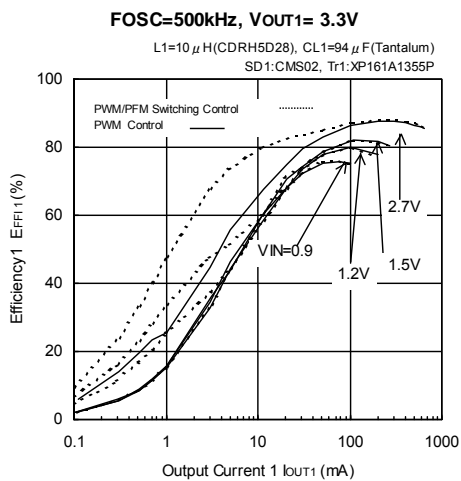
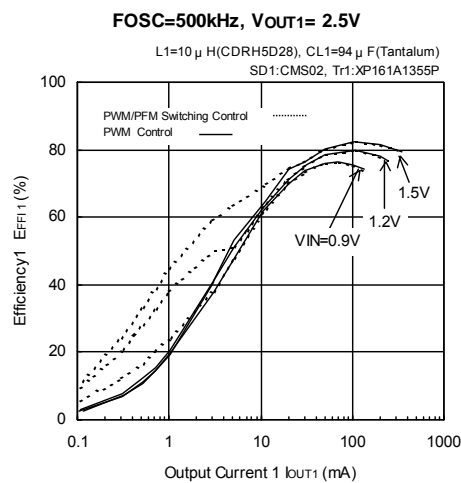
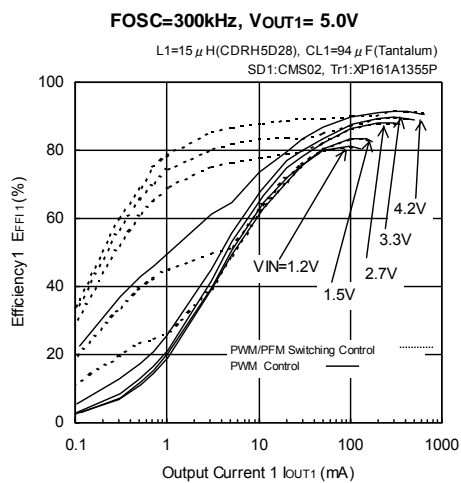
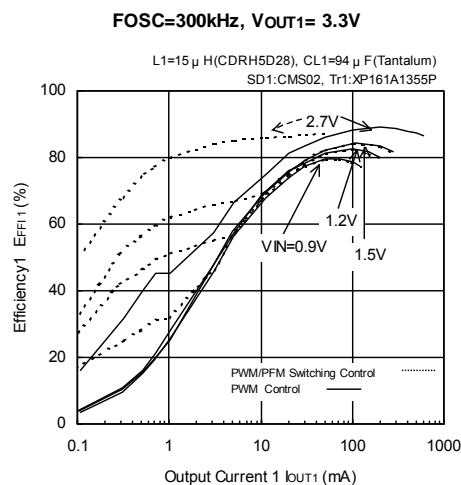
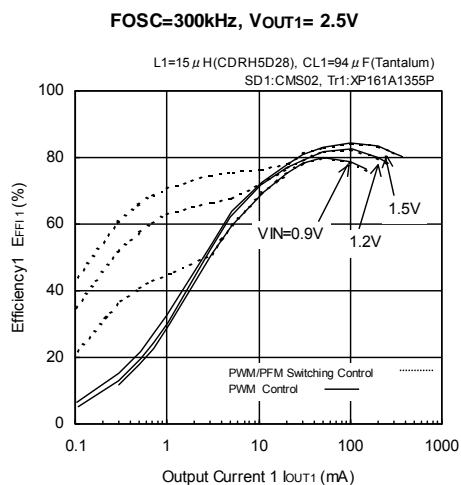


Dotted Arrowhead -----> PWM/PFM Switching Control

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### < 1ch Step-Up DC/DC Controller >

#### (2) Efficiency vs. Output Current (Continued)

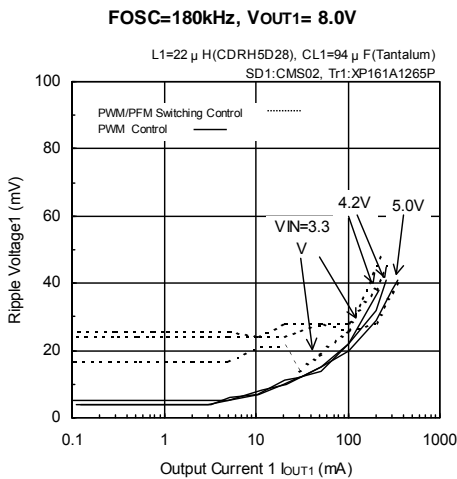
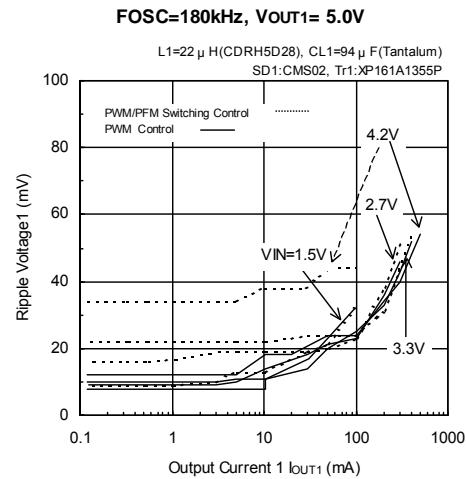
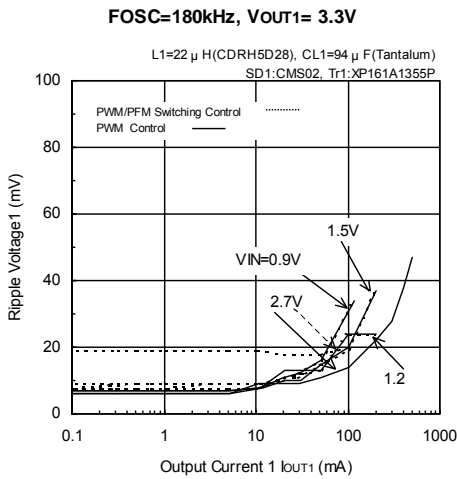
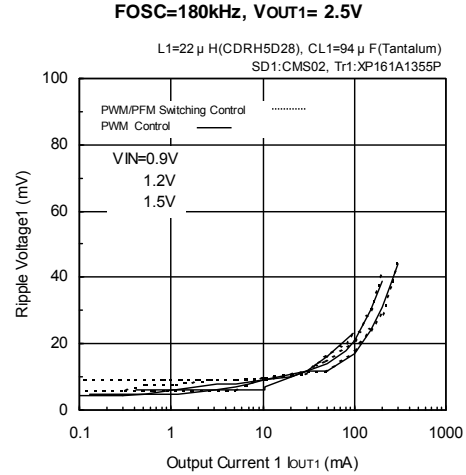
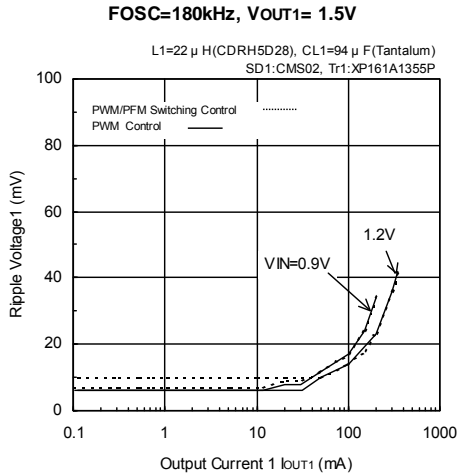


Dotted Arrowhead -----> PWM/PFM Switching Control

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### < 1ch Step-Up DC/DC Controller >

#### (3) Ripple Voltage vs. Output Current



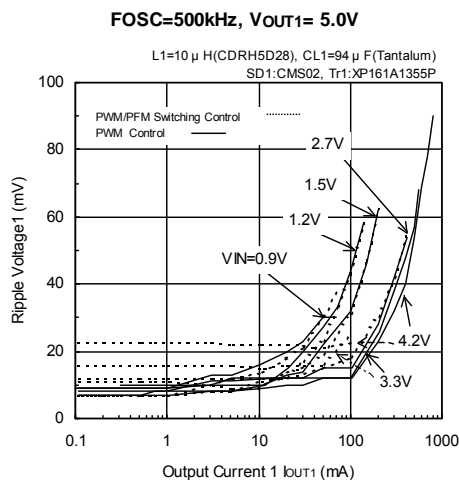
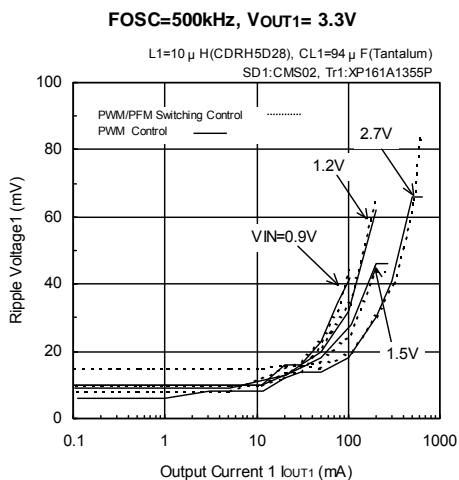
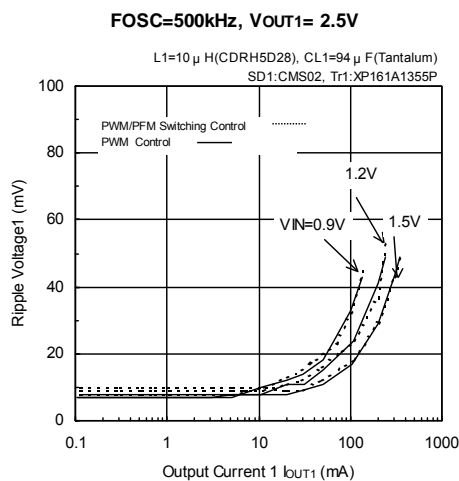
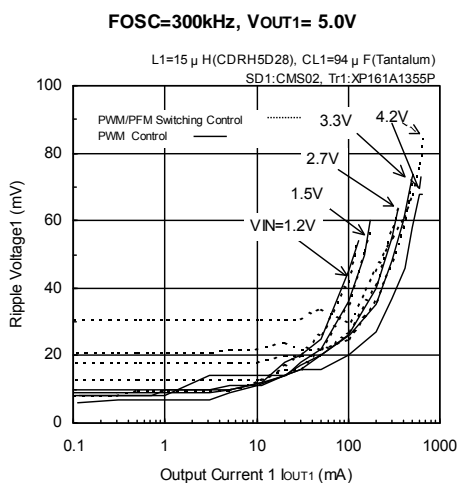
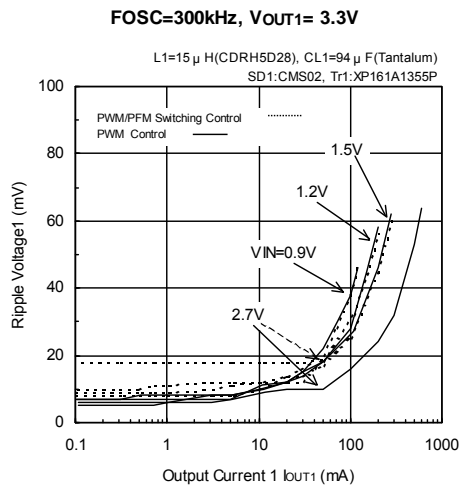
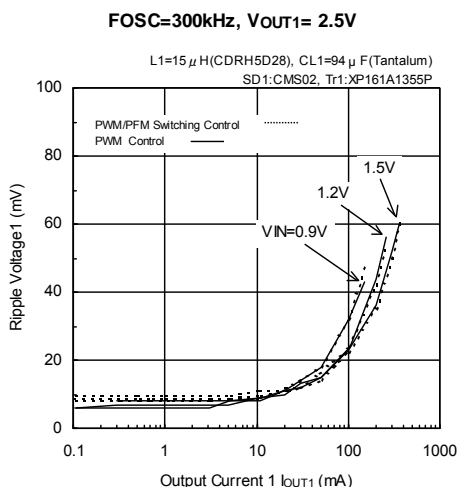
Dotted Arrowhead -----> PWM/PFM Switching Control



# TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

## < 1ch Step-Up DC/DC Controller >

### (3) Ripple Voltage vs. Output Current (Continued)

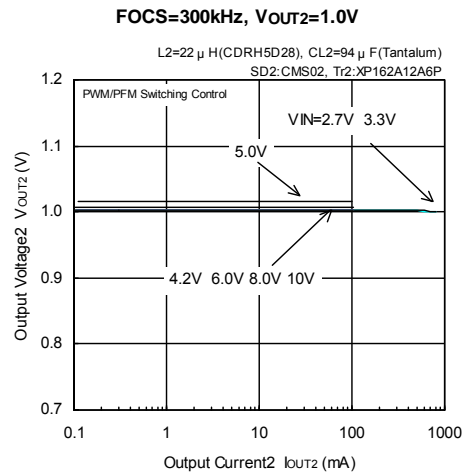
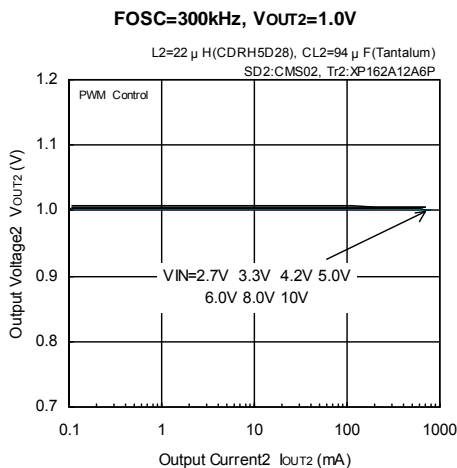
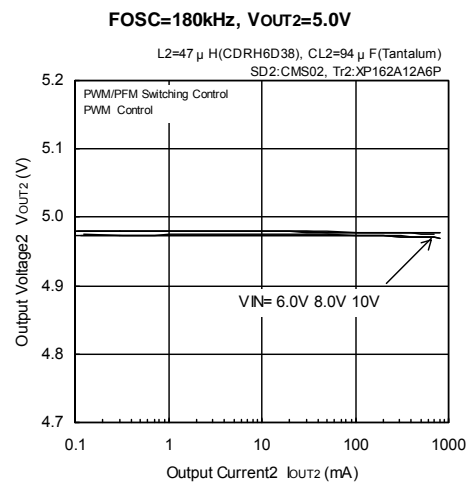
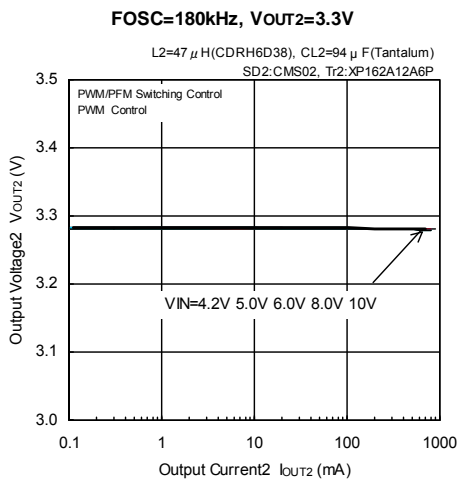
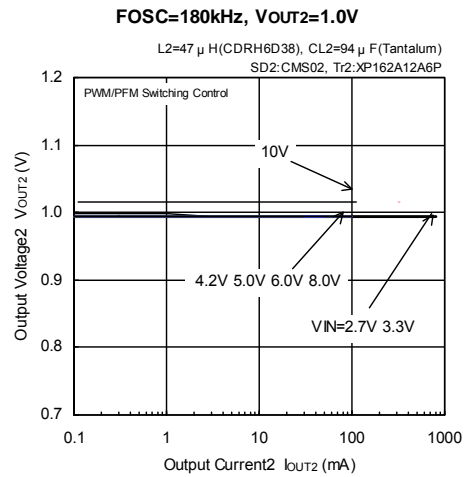
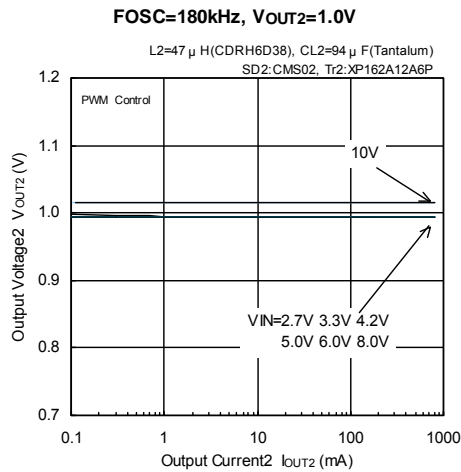


Dotted Arrowhead ----> PWM/PFM Switching Control

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

< 2ch Step-Down DC/DC Controller >

(4) Output Voltage vs. Output Current

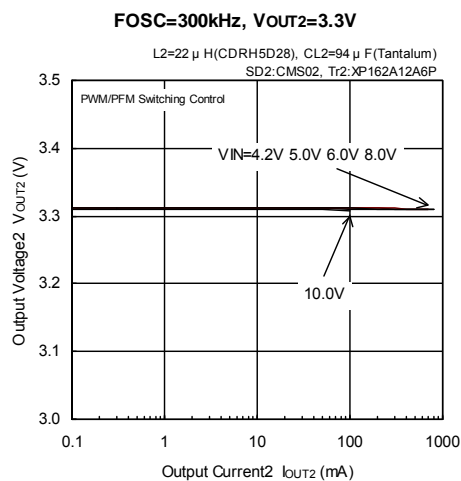
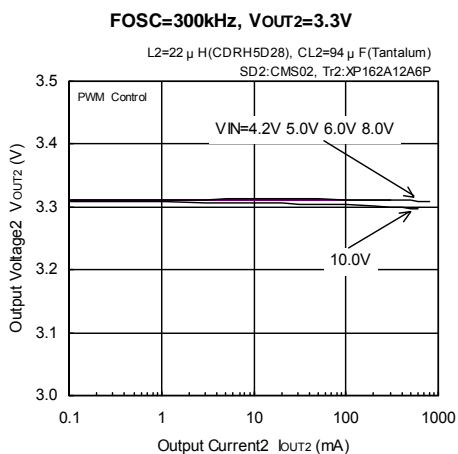
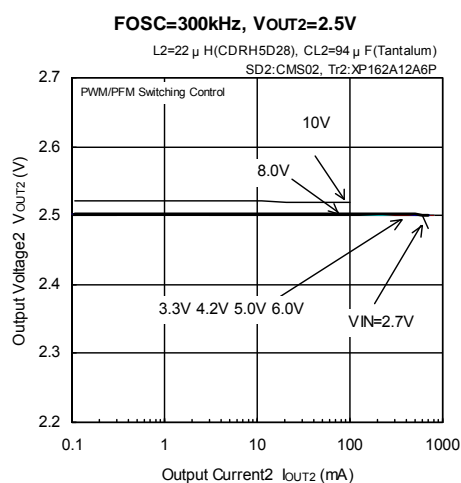
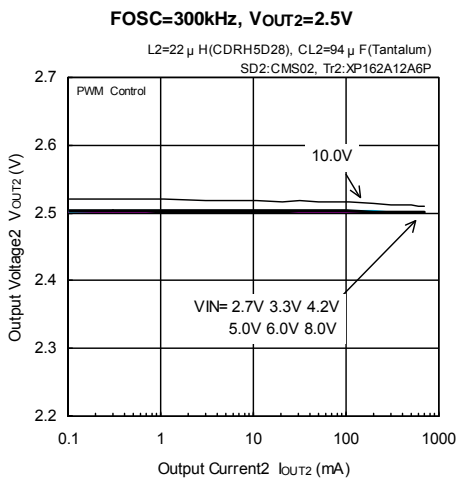
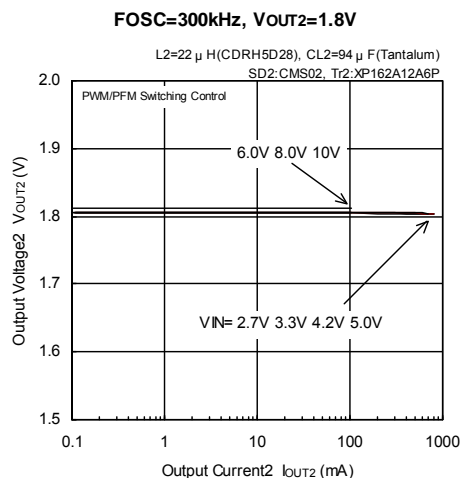
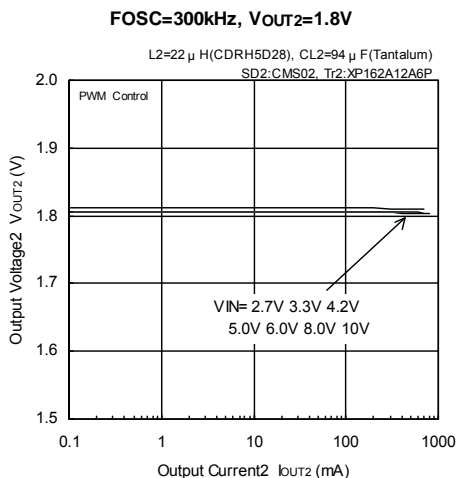


\* When setting VOUT = 1.0V, VIN = 8.0V, 10.0V  
 CL should be 94  $\mu$  F (Tantalum) + 100  $\mu$  F (OS capacitor)

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### < 2ch Step-Down DC/DC Controller >

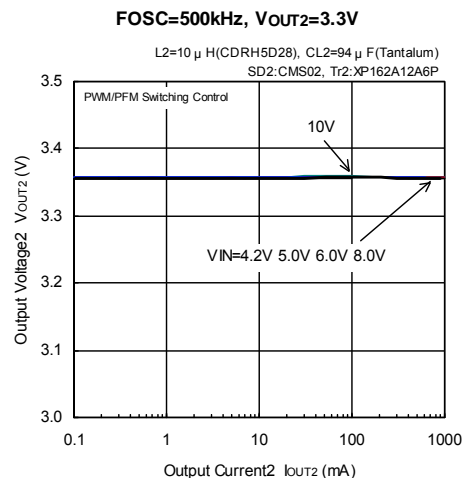
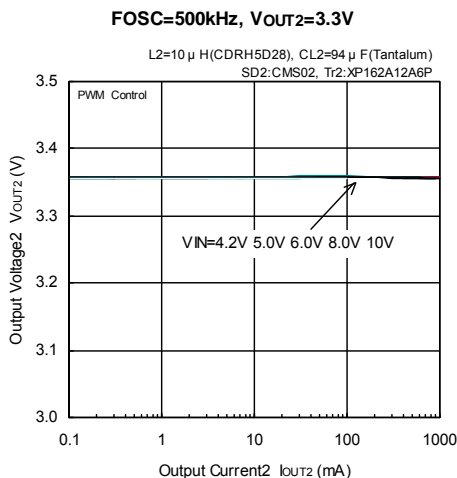
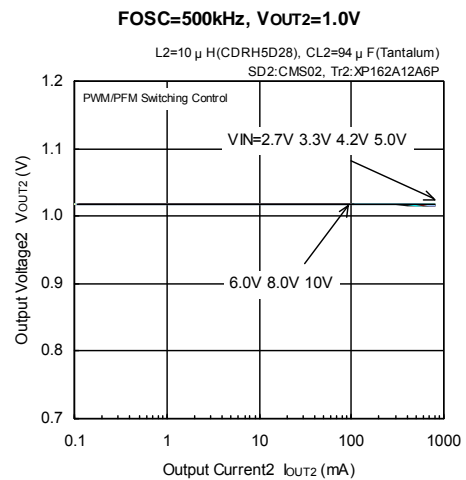
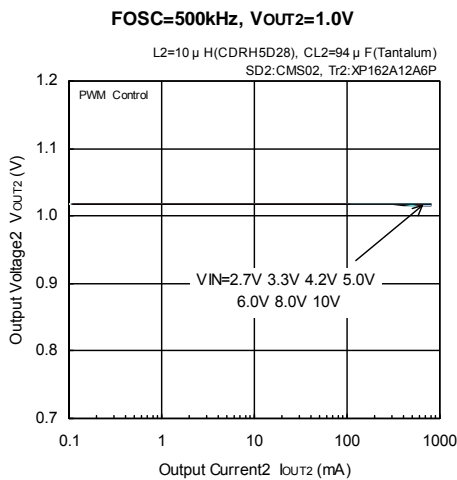
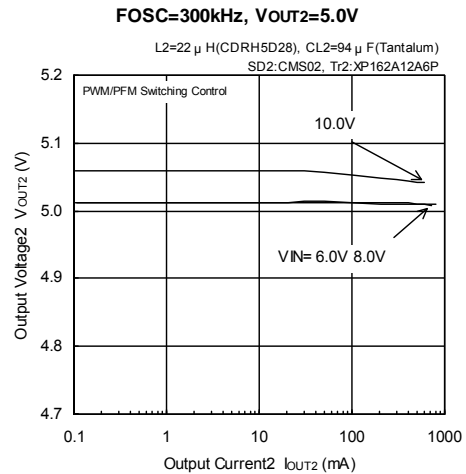
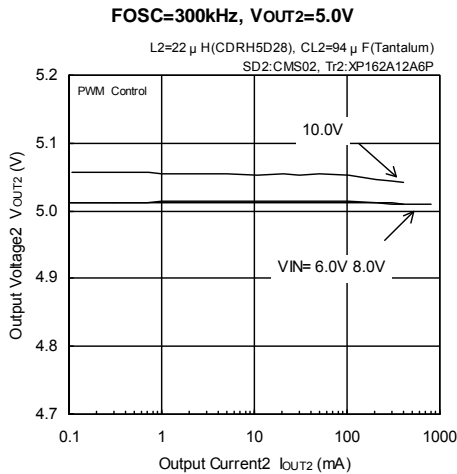
#### (4) Output Voltage vs. Output Current (Continued)



## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### < 2ch Step-Down DC/DC Controller >

#### (4) Output Voltage vs. Output Current (Continued)

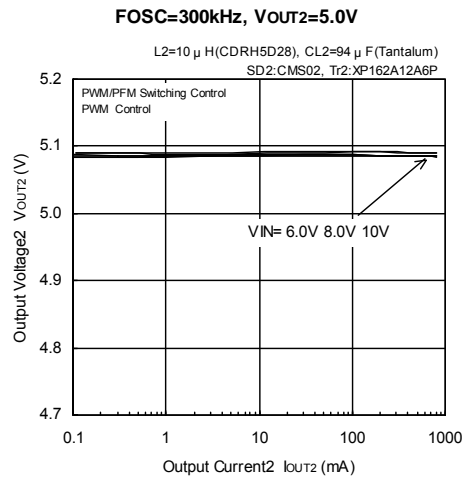


\*When setting Vout = 1.0V, VIN = 8.0V, 10.0V  
 CL should be 94  $\mu$  F (Tantalum) + 100  $\mu$  F (OS capacitor)

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### < 2ch Step-Down DC/DC Controller >

(4) Output Voltage vs. Output Current (Continued)

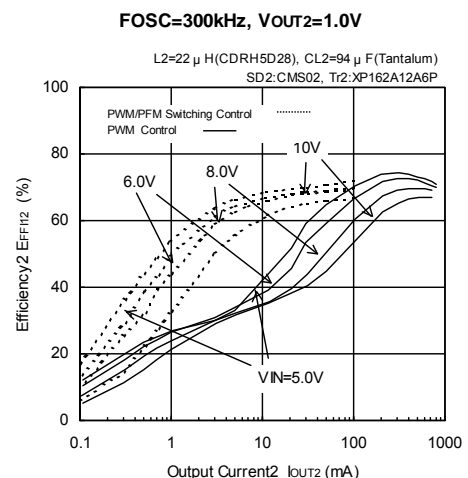
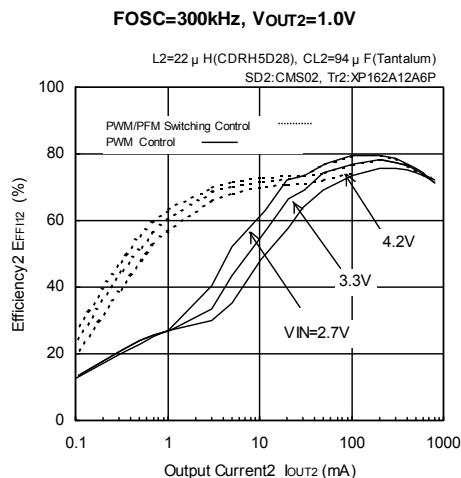
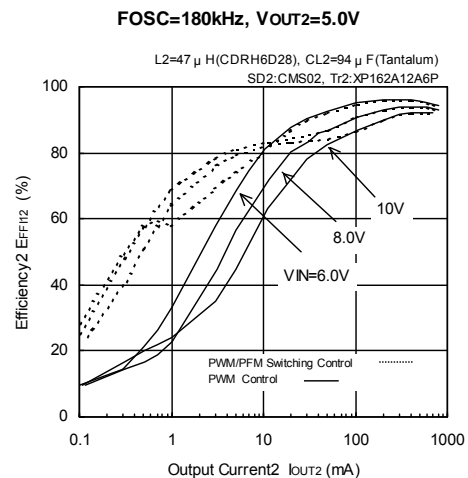
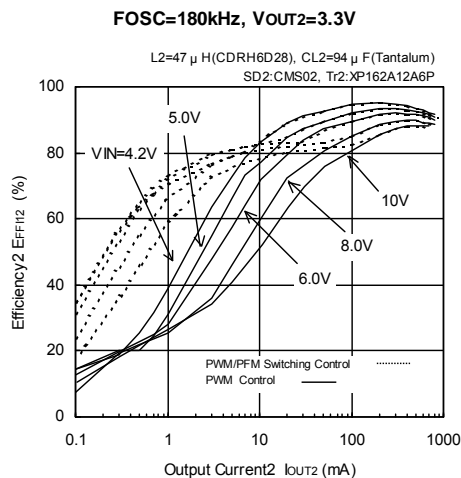
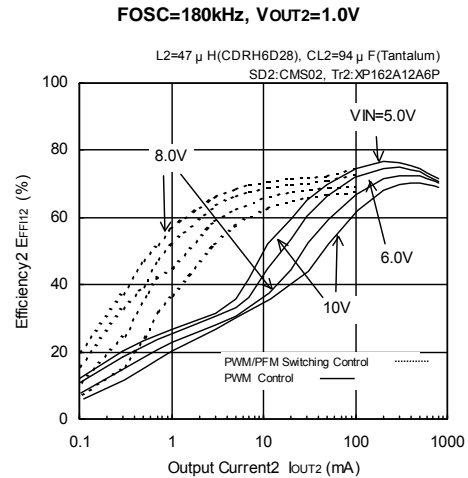
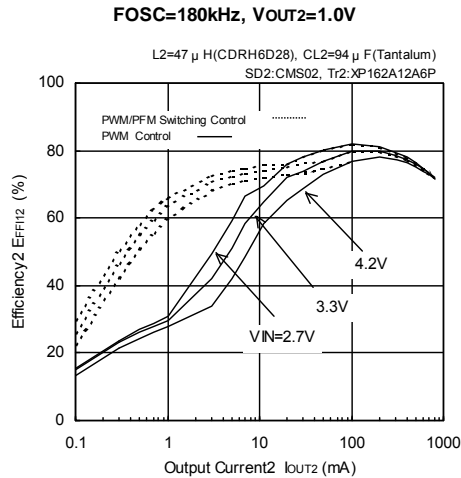


\*When setting VOUT = 1.0V, VIN = 8.0V, 10.0V  
CL should be 94  $\mu$  F (Tantalum) + 100  $\mu$  F (OS capacitor)

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

< 2ch Step-Down DC/DC Controller >

(5) Efficiency vs. Output Current

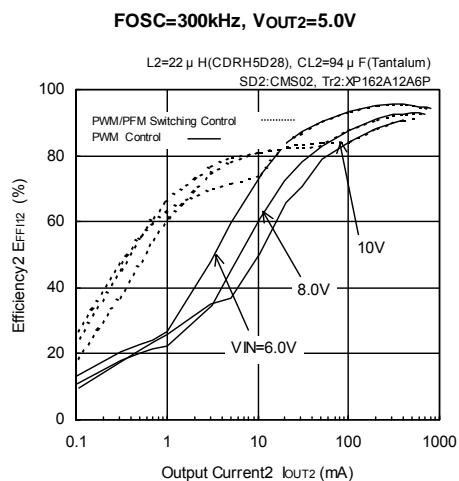
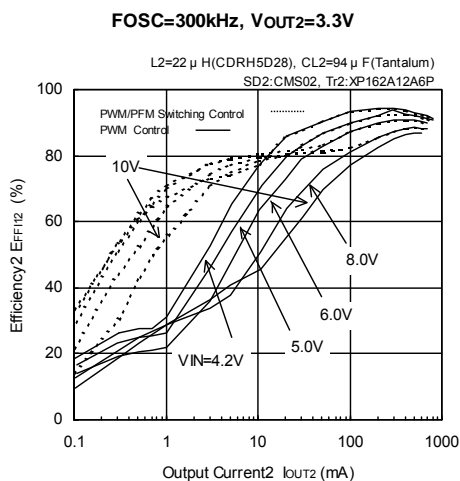
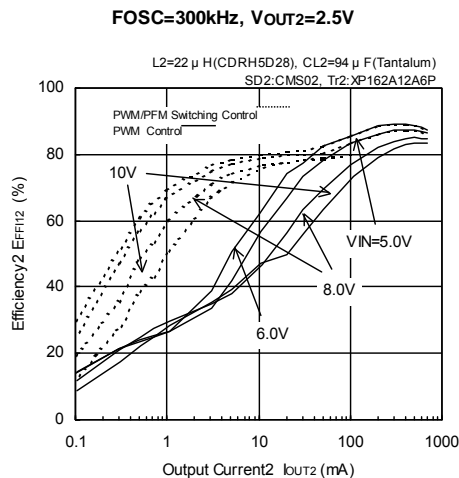
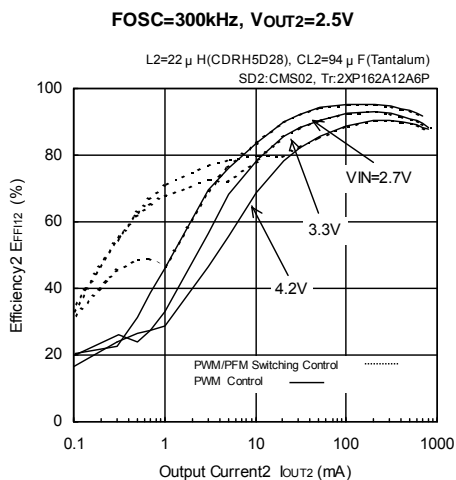
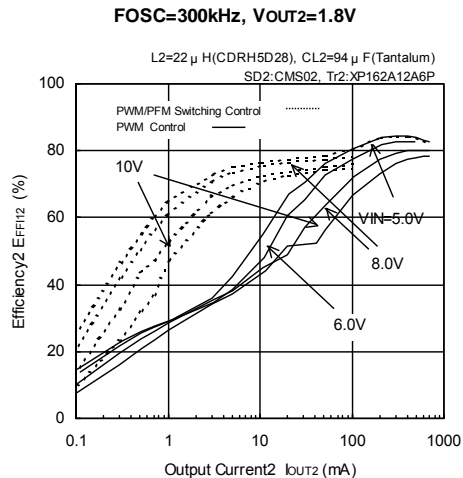
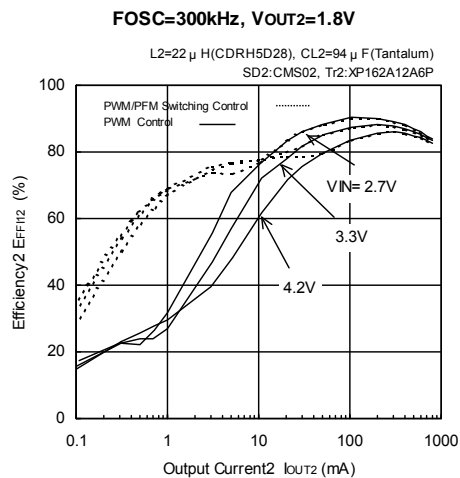


\*When setting VOUT = 1.0V, VIN = 8.0V, 10.0V  
CL should be 94  $\mu$  F (Tantalum) + 100  $\mu$  F (OS capacitor)

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### < 2ch Step-Down DC/DC Controller >

#### (5) Efficiency vs. Output Current (Continued)

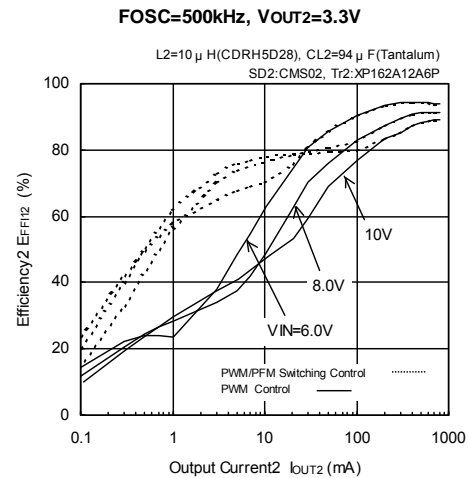
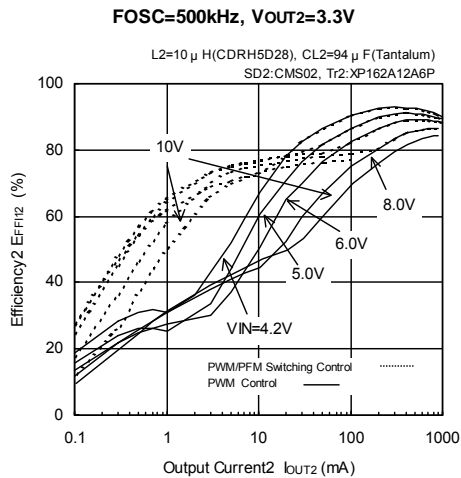
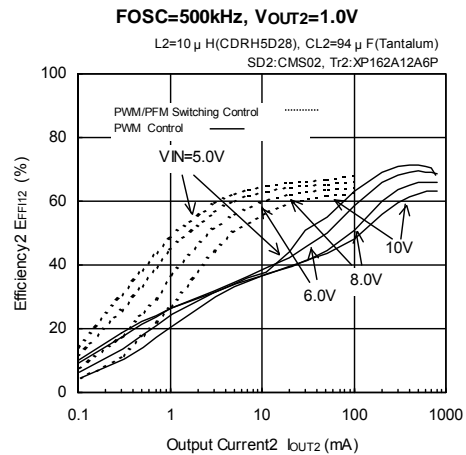
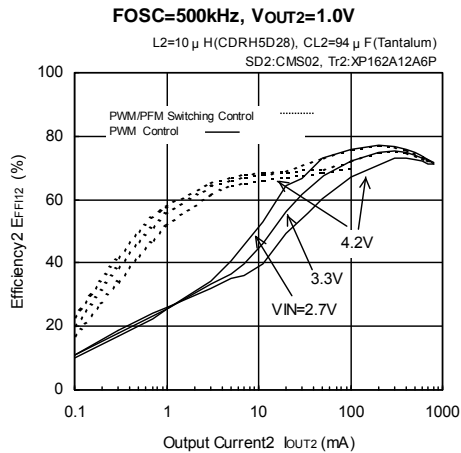


\*When setting V<sub>OUT</sub> = 1.0V, V<sub>IN</sub> = 8.0V, 10.0V  
CL should be 94  $\mu$  F (Tantalum) + 100  $\mu$  F (OS capacitor)

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### < 2ch Step-Down DC/DC Controller >

#### (5) Efficiency vs. Output Current (Continued)



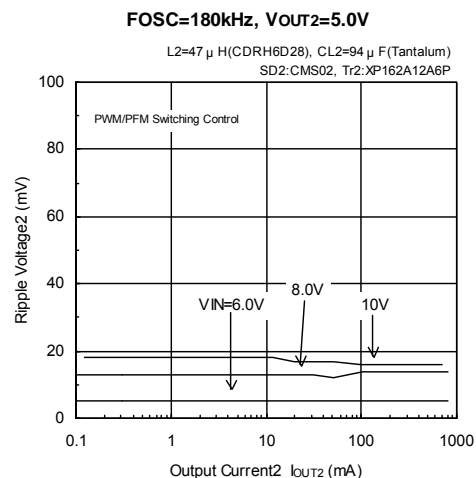
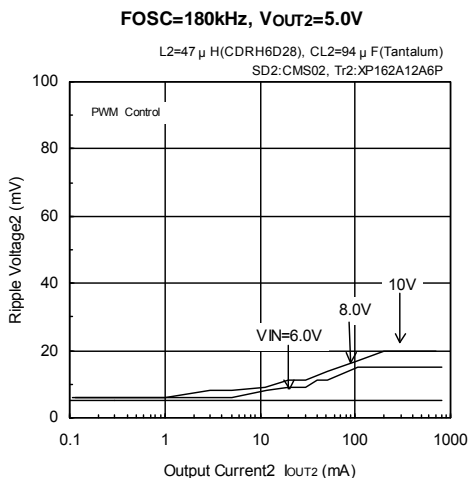
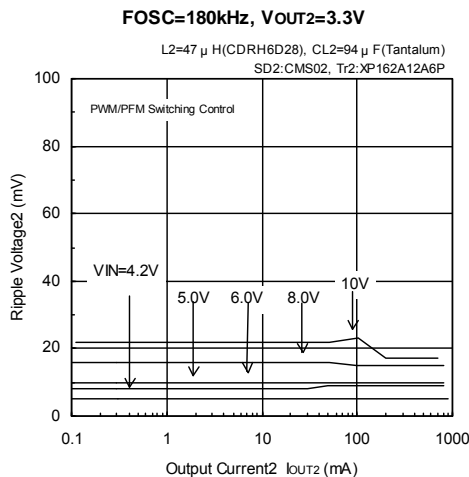
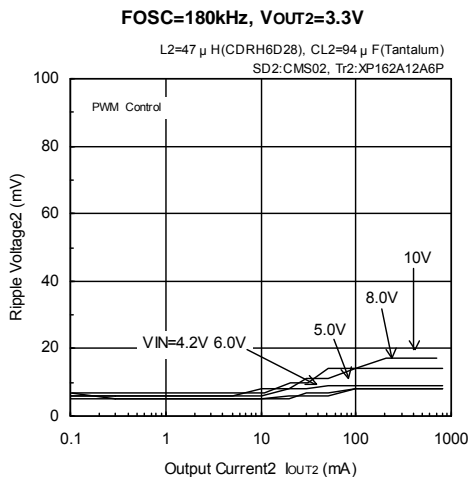
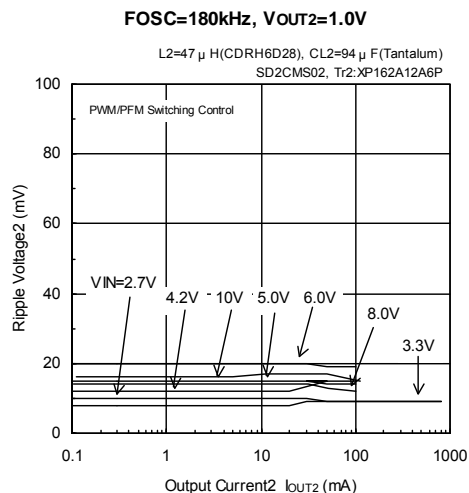
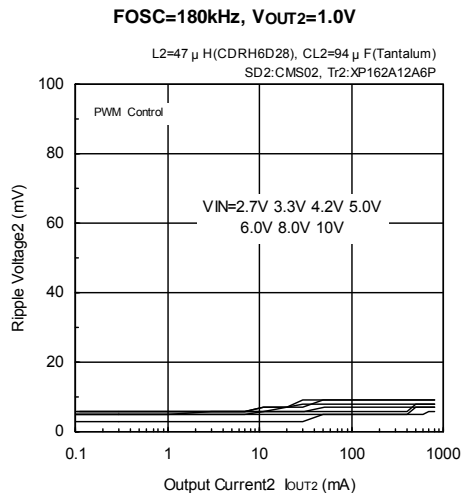
\*When setting V<sub>OUT</sub> = 1.0V, V<sub>IN</sub> = 8.0V, 10.0V  
 CL should be 94  $\mu$  F (Tantalum) + 100  $\mu$  F (OS capacitor)



## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### < 2ch Step-Down DC/DC Controller >

#### (6) Ripple Voltage vs. Output Current

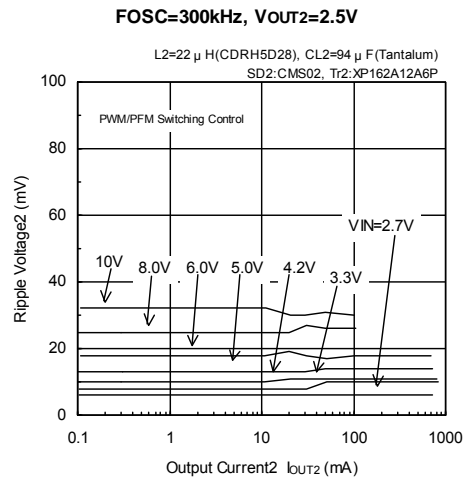
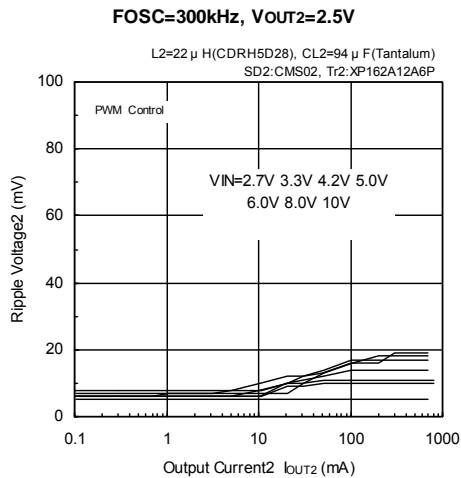
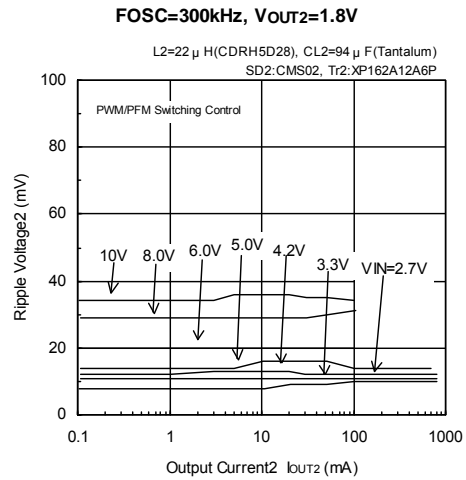
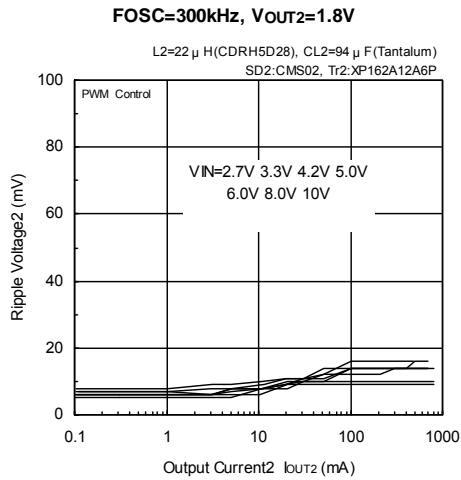
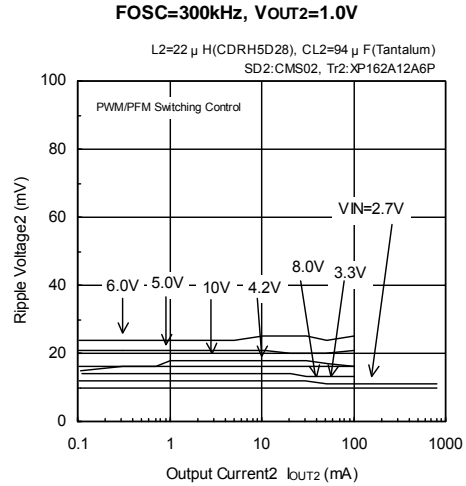
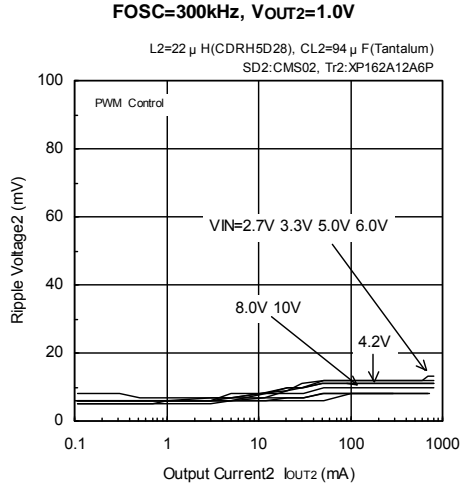


\* When setting VOUT = 1.0V, VIN = 8.0V, 10.0V  
CL should be 94  $\mu$  F (Tantalum) + 100  $\mu$  F (OS capacitor)

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### < 2ch Step-Down DC/DC Controller >

#### (6) Ripple Voltage vs. Output Current (Continued)

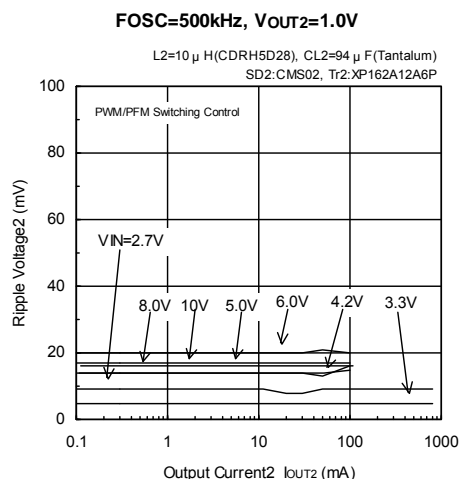
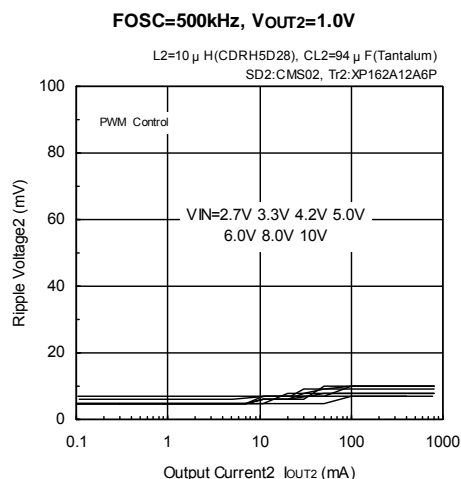
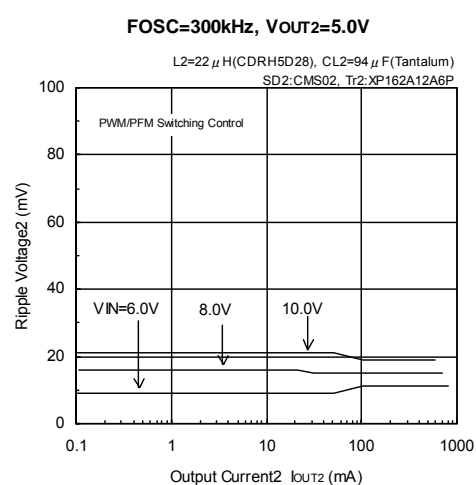
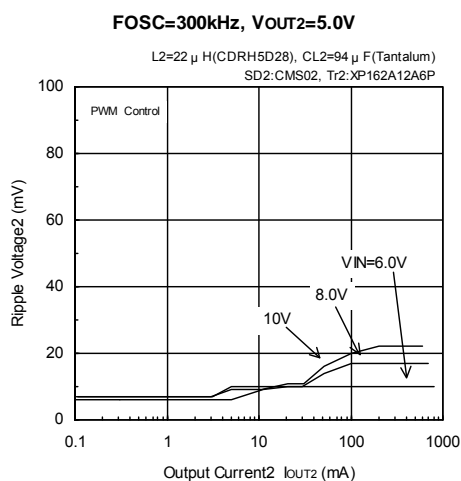
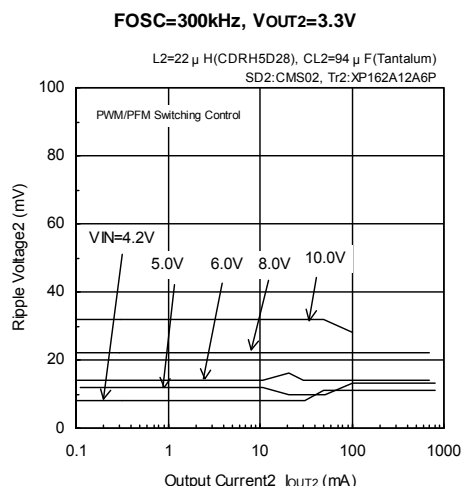
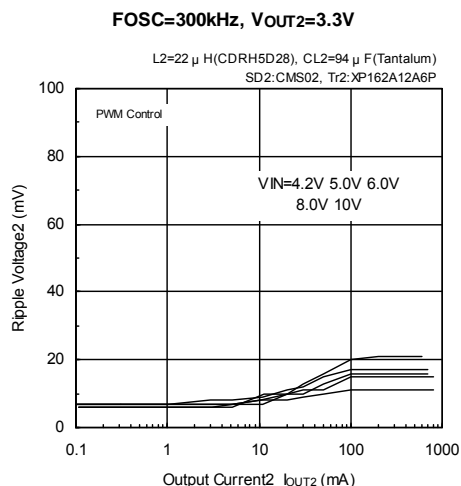


\*When setting V<sub>OUT</sub> = 1.0V, V<sub>IN</sub> = 8.0V, 10.0V  
CL should be 94  $\mu$  F (Tantalum) + 100  $\mu$  F (OS capacitor)

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### < 2ch Step-Down DC/DC Controller >

#### (6) Ripple Voltage vs. Output Current (Continued)

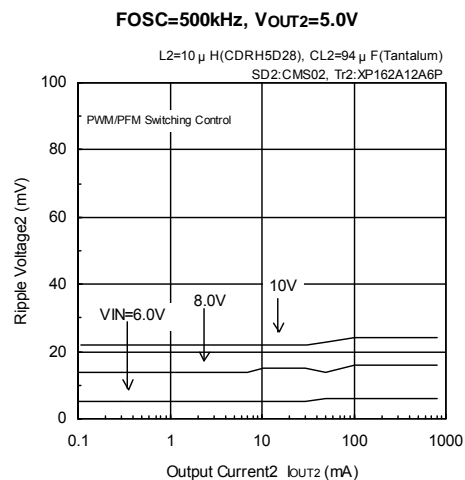
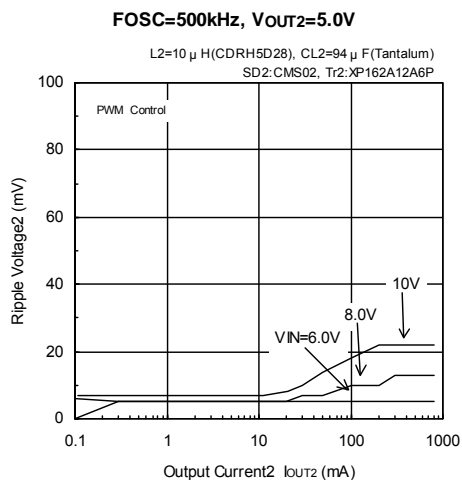
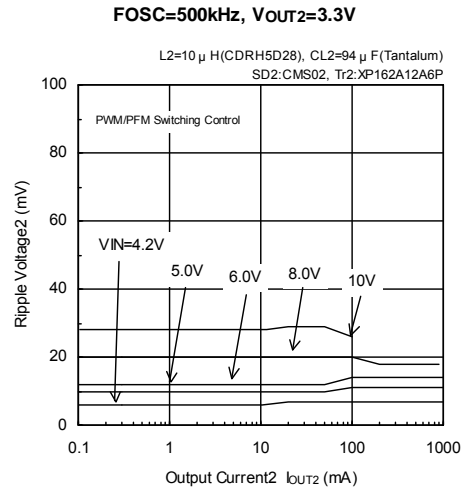
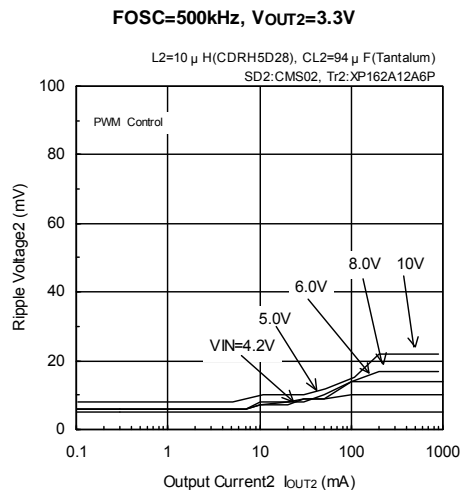


\* When setting VOUT = 1.0V, VIN = 8.0V, 10.0V  
CL should be 94  $\mu$  F (Tantalum) + 100  $\mu$  F (OS capacitor)

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

< 2ch Step-Down DC/DC Controller >

(6) Ripple Voltage vs. Output Current (Continued)

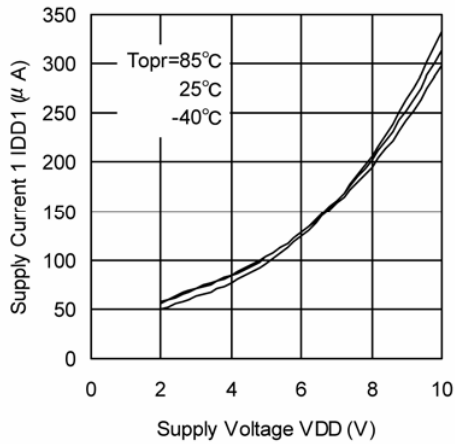


\* When setting V<sub>OUT</sub> = 1.0V, V<sub>IN</sub> = 8.0V, 10.0V  
CL should be 94  $\mu$  F (Tantalum) + 100  $\mu$  F (OS capacitor)

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

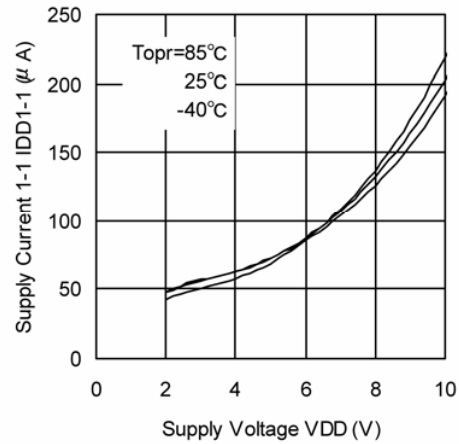
(7) Supply Current vs. Supply Voltage

**XC9502B092 (180kHz)**



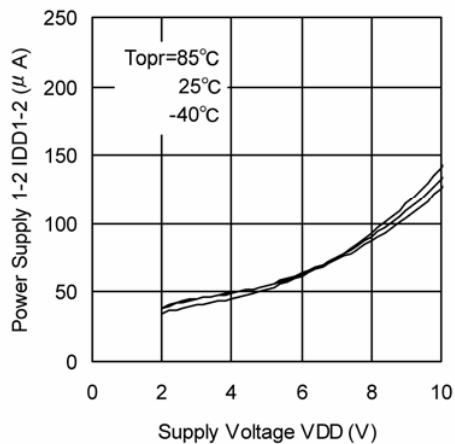
(8) Supply Current 1-1 vs. Supply Voltage

**XC9502B092 (180kHz)**



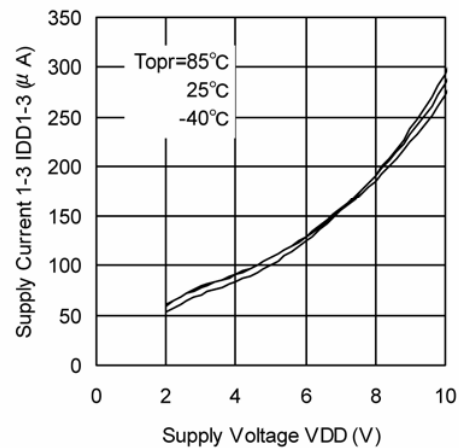
(9) Supply Current 1-2 vs. Supply Voltage

**XC9502B092 (180kHz)**



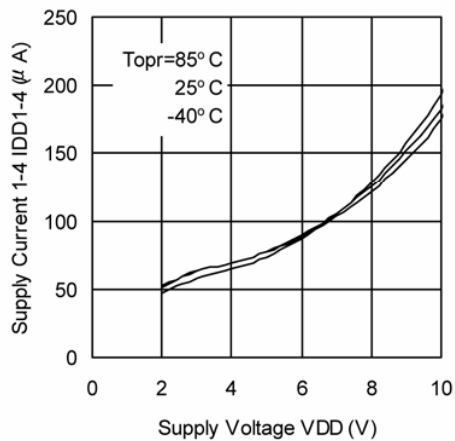
(10) Supply Current 1-3 vs. Supply Voltage

**XC9502B092 (180kHz)**



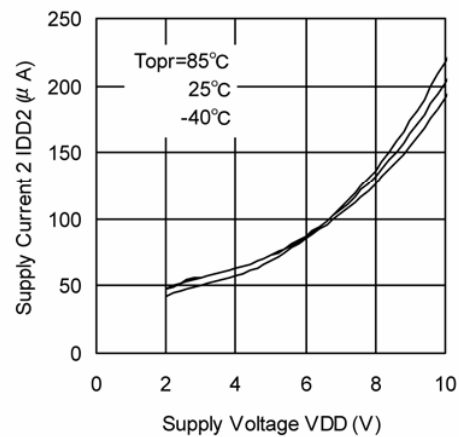
(11) Supply Current 1-4 vs. Supply Voltage

**XC9502B092 (180kHz)**



(12) Supply Current 2 vs. Supply Voltage

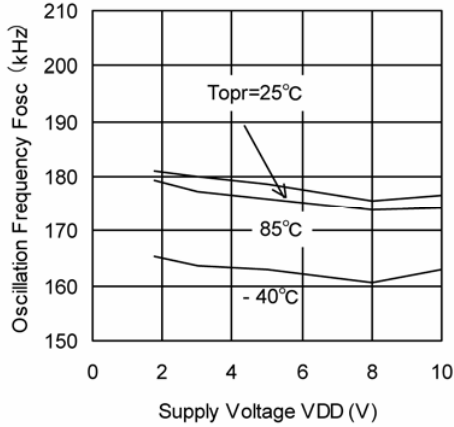
**XC9502B092 (180kHz)**



## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

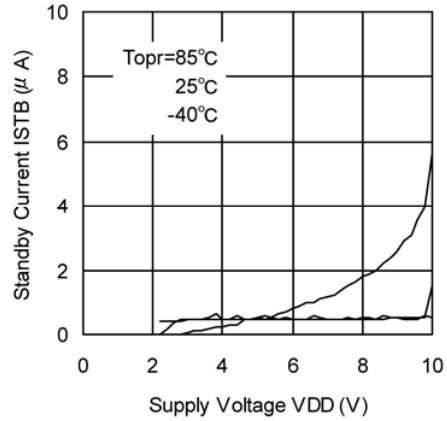
(13) Oscillation Frequency vs. Supply Voltage

**XC9502B092 (180kHz)**



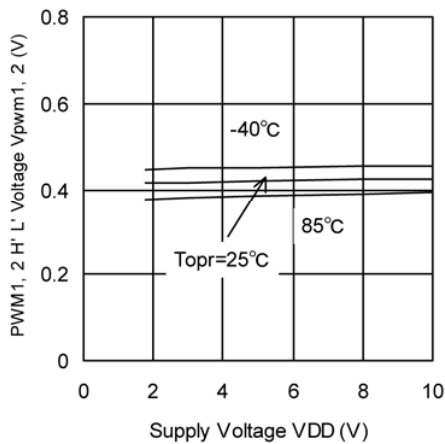
(14) Stand-by Current vs. Supply Voltage

**XC9502B092 (180kHz)**



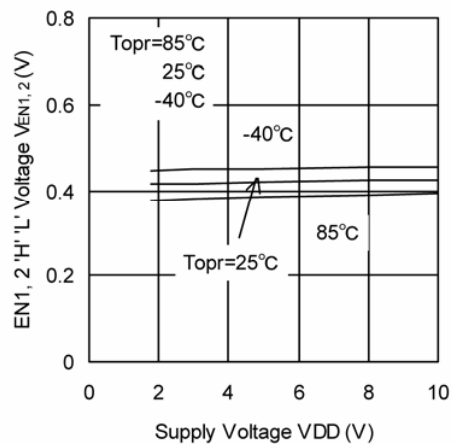
(15) PWM1, 2 'H' 'L' Voltage vs. Supply Voltage

**XC9502B092 (180kHz)**



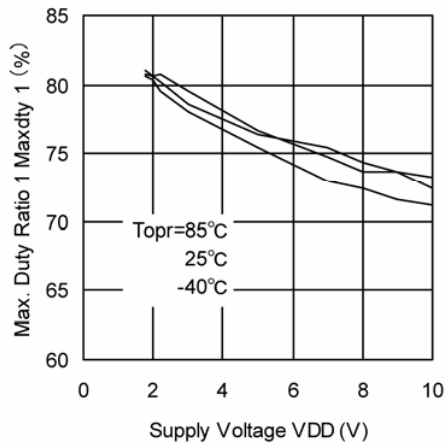
(16) EN1, 2 'H' 'L' Voltage vs. Supply Voltage

**XC9502B092 (180kHz)**



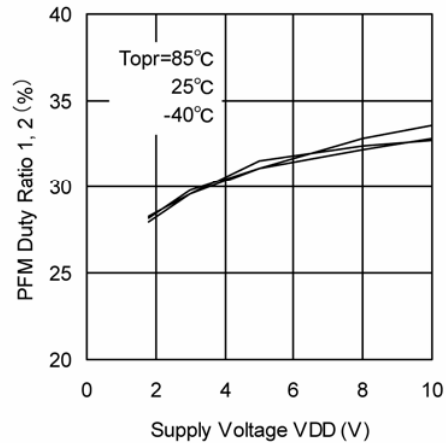
(17) Maximum Duty Ratio 1 vs. Supply Voltage

**XC9502B092 (180kHz)**



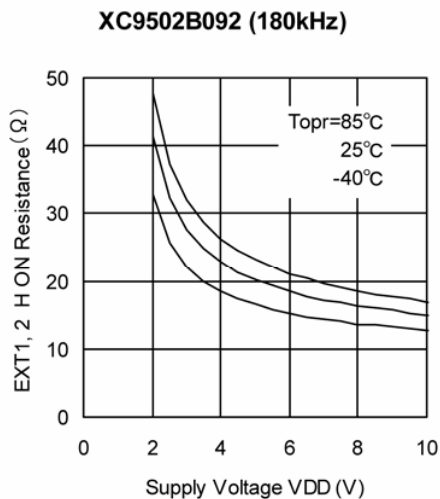
(18) PFM Duty Ratio 1, 2 vs. Supply Voltage

**XC9502B092(180kHz)**

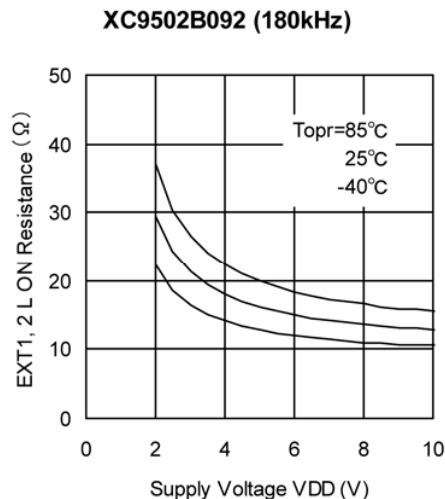


## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

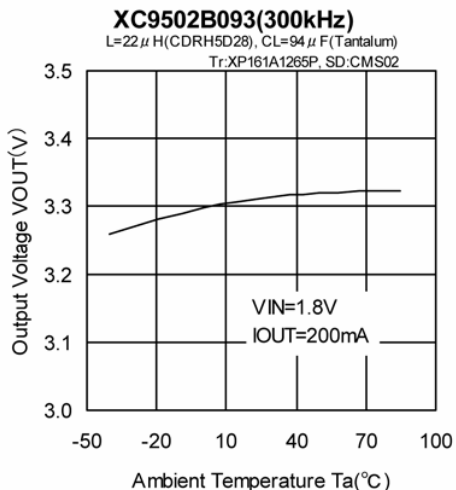
(19) EXT 1, 2 High ON Resistance vs. Supply Voltage



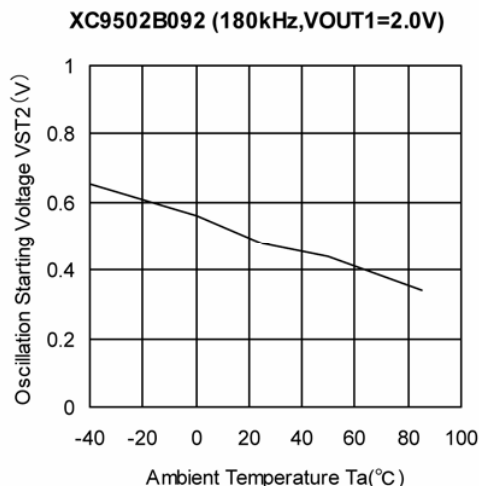
(20) EXT 1, 2 Low ON Resistance vs. Supply Voltage



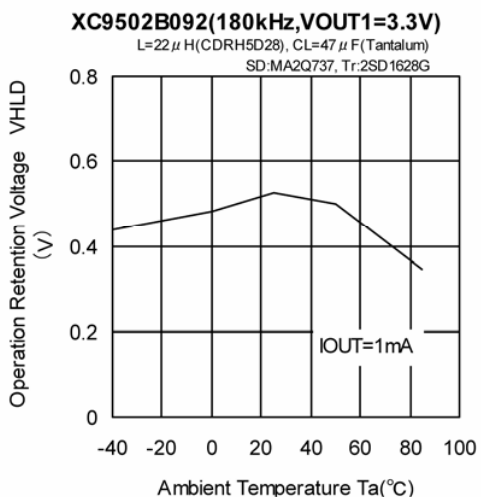
(21) Output Voltage vs. Ambient Temperature



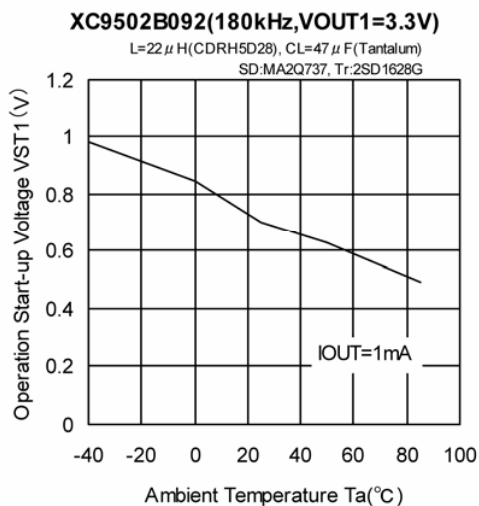
(22) Oscillation Start-Up Voltage vs. Ambient Temperature



(23) Operation Retention Voltage vs. Ambient Temperature



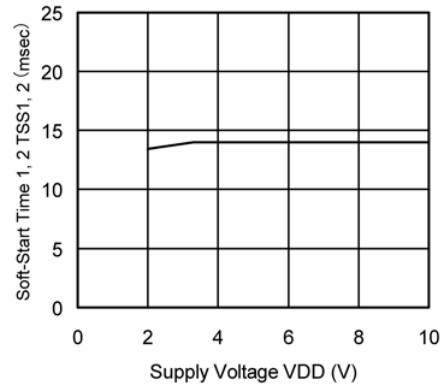
(24) Operation Start-Up Voltage vs. Ambient Temperature



## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(25) Soft-Start Time 1, 2 vs. Supply Voltage

**XC9502B092 (180kHz)**





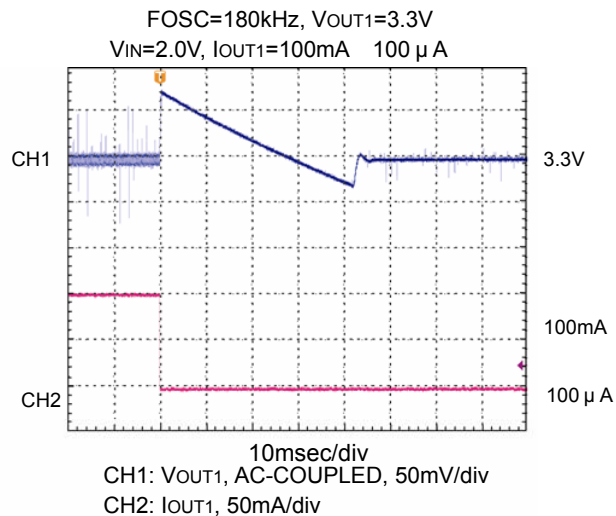
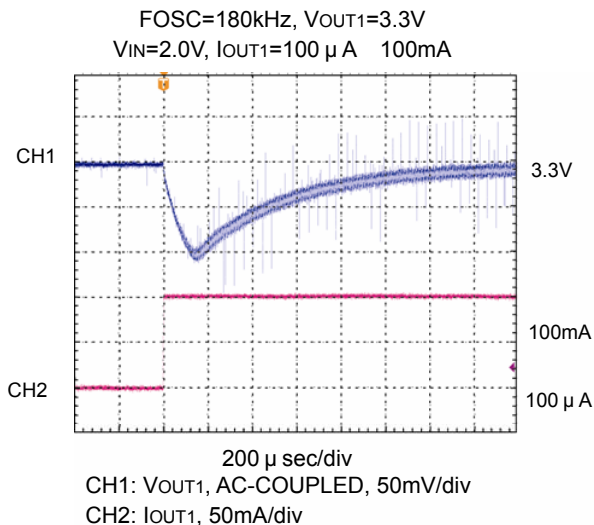
## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### (26) Load Transient Response

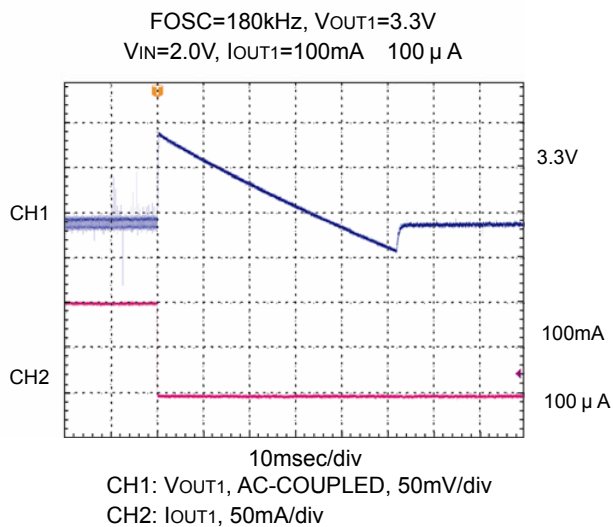
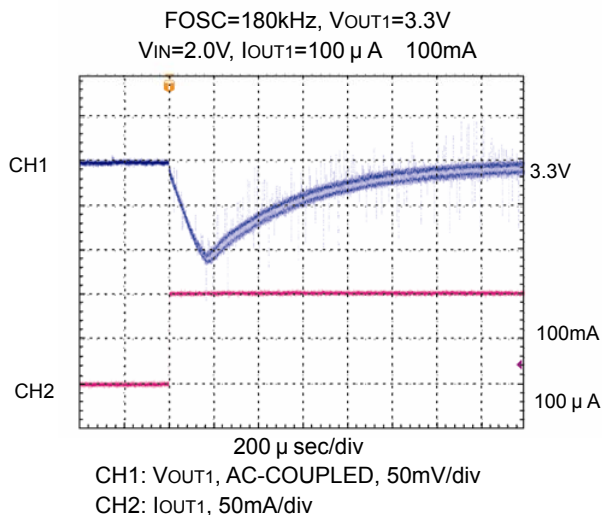
[1 channel: Step-Up DC/DC Controller]

<  $V_{OUT1} = 3.3V$ ,  $V_{IN} = 2.0V$ ,  $I_{OUT1,2} = 100\mu A \leftrightarrow 100mA$  >

#### PWM Control



#### PWM/PFM Switching Control

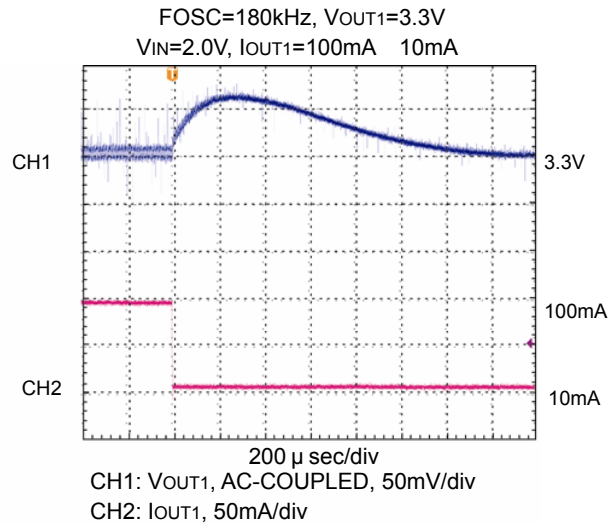
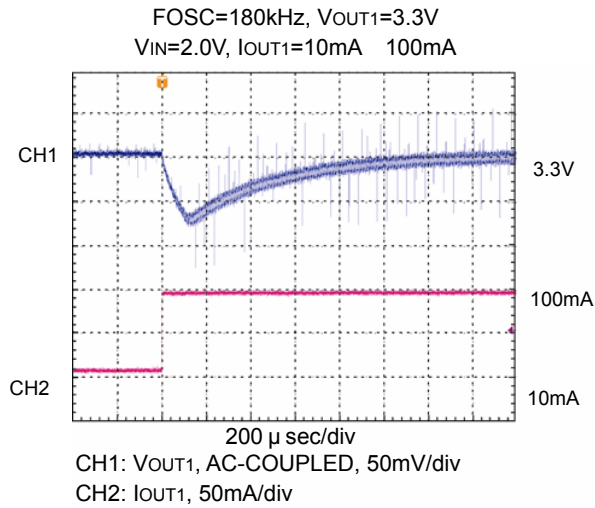


## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

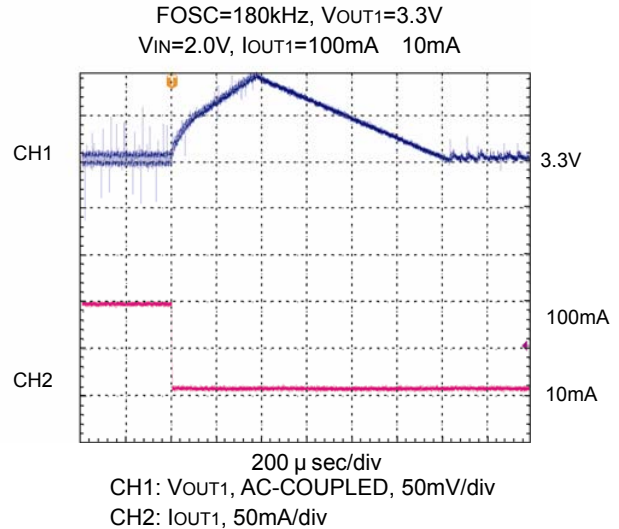
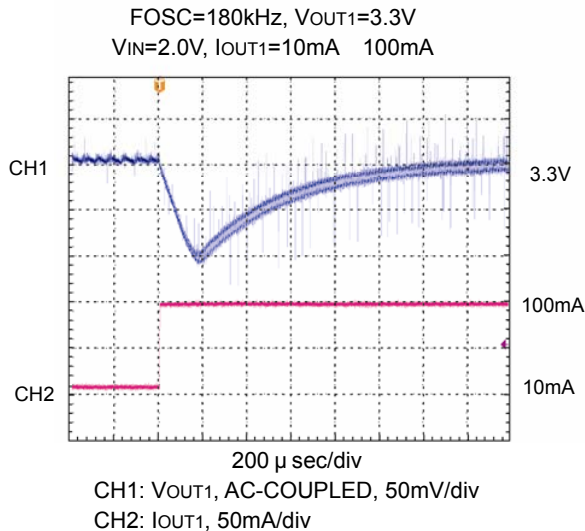
### (26) Load Transient Response (Continued)

<  $V_{OUT1} = 3.3V$ ,  $V_{IN} = 2.0V$ ,  $I_{OUT1, 2} = 10mA \leftrightarrow 100mA$  >

PWM Control



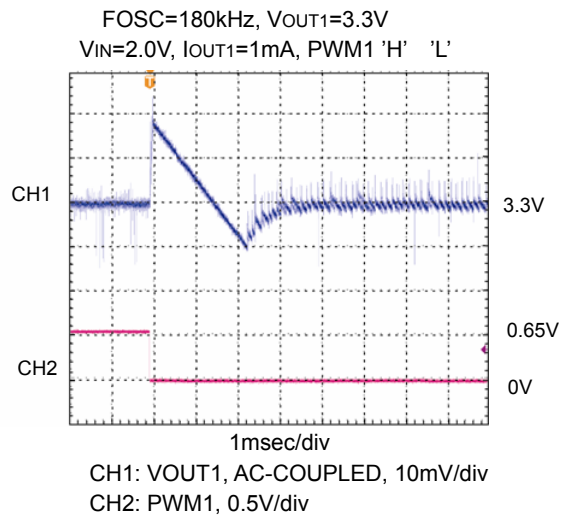
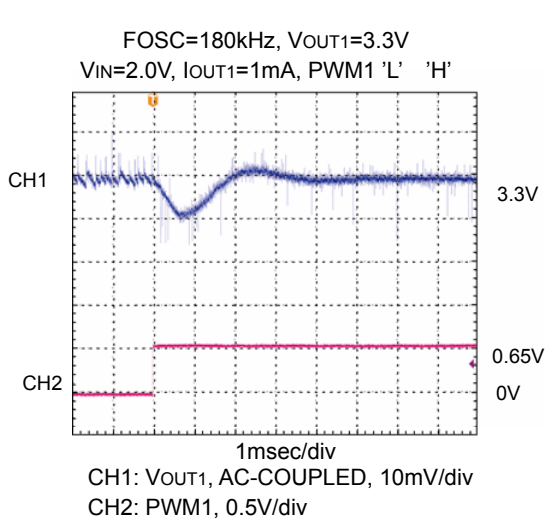
PWM/PFM Switching Control



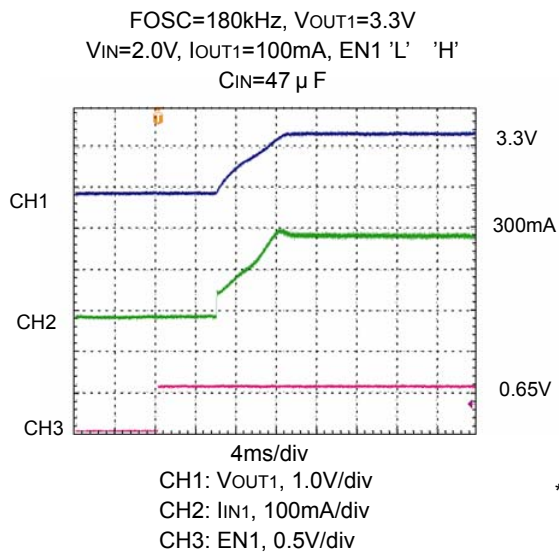
## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### (26) Load Transient Response (Continued)

<PWM Control PWM/PFM Switching Control>



<Soft Start Wave Form>



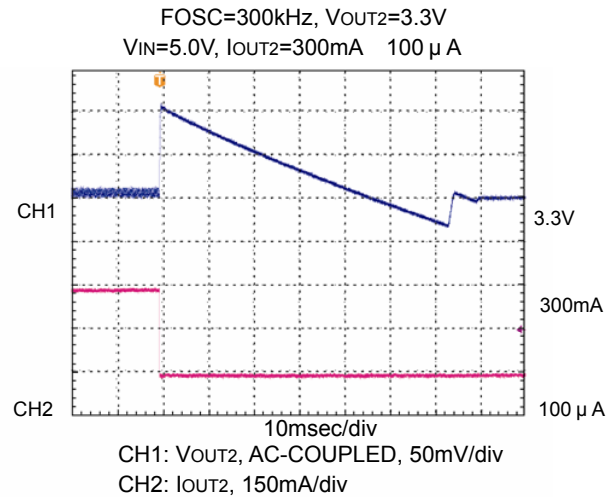
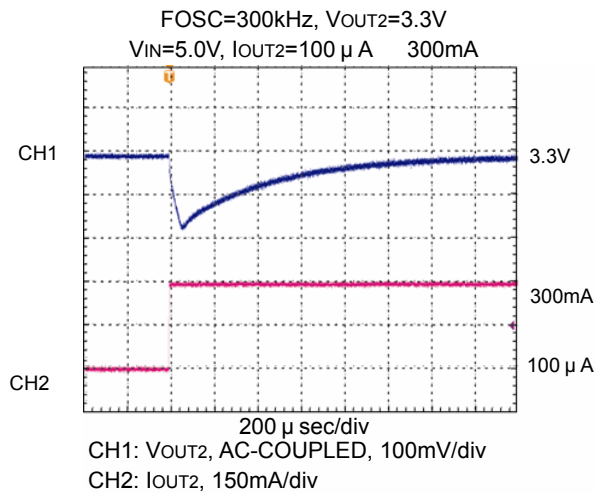
\* EN2=GND

## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

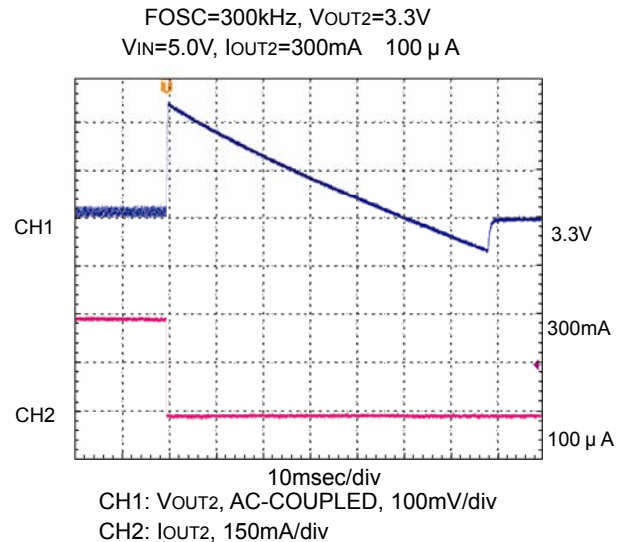
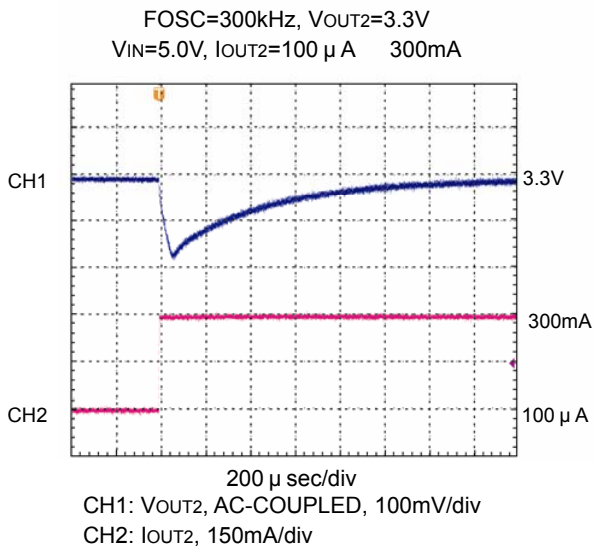
### (26) Load Transient Response (Continued)

<  $V_{OUT2}=3.3V$ ,  $V_{IN}=5.0V$ ,  $I_{OUT2}=100\mu A \leftrightarrow 300mA$  >

#### PWM Control



#### PWM/PFM Switching Control

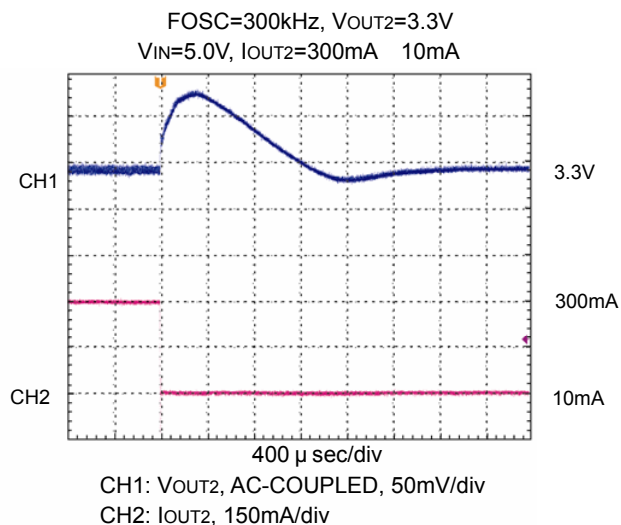
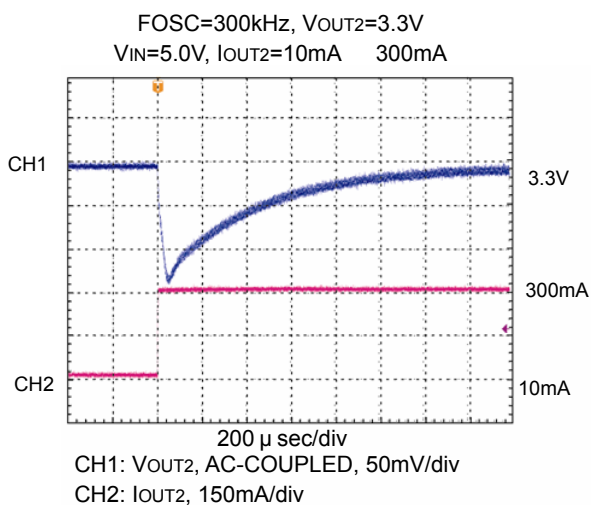


## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

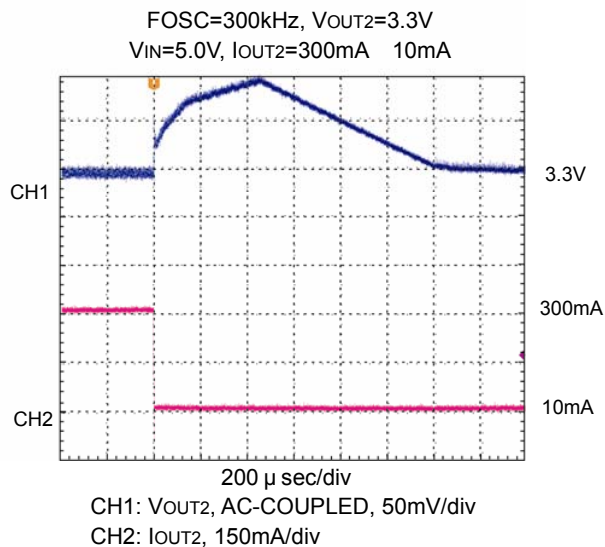
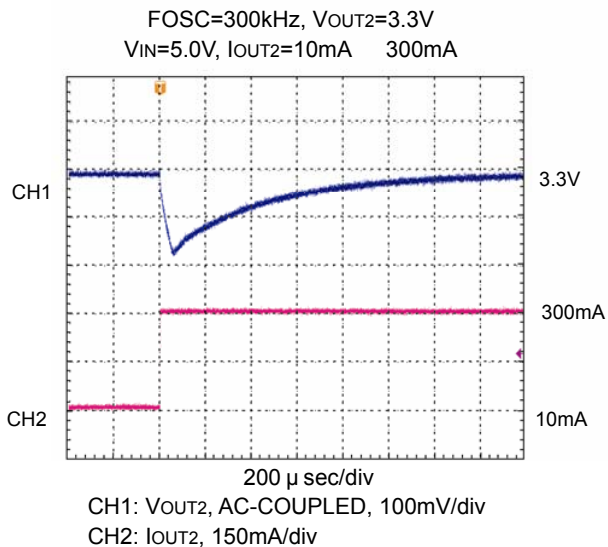
### (26) Load Transient Response (Continued)

<  $V_{OUT2}=3.3V$ ,  $V_{IN}=5.0V$ ,  $I_{OUT2}=10mA \leftrightarrow 300mA$  >

#### PWM Control



#### PWM/PFM Switching Control

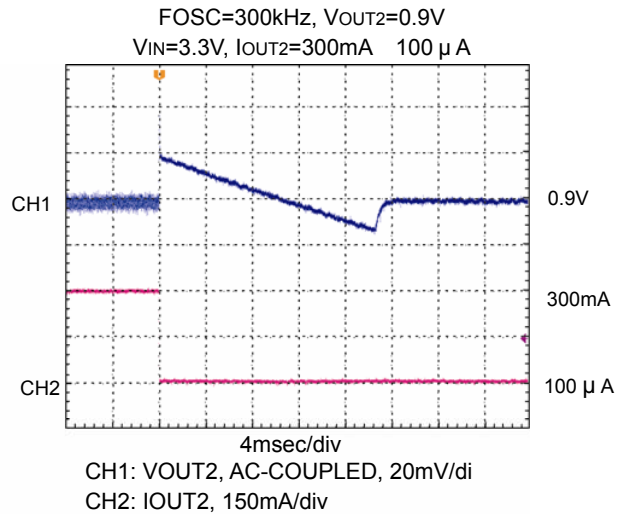
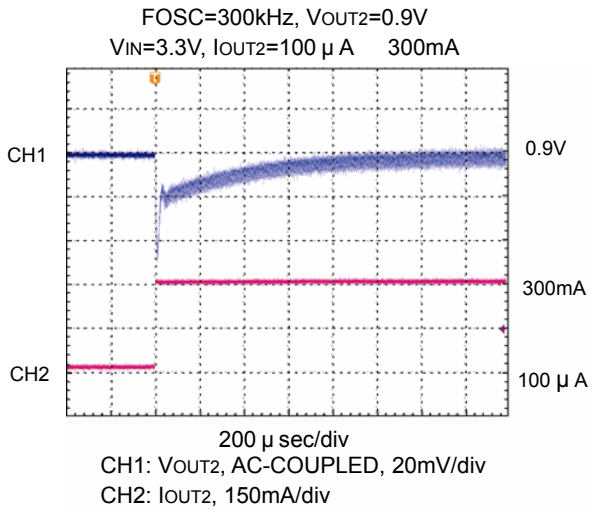


## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

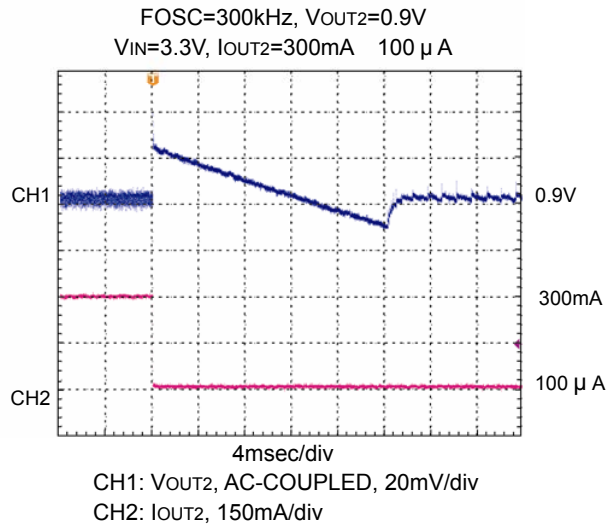
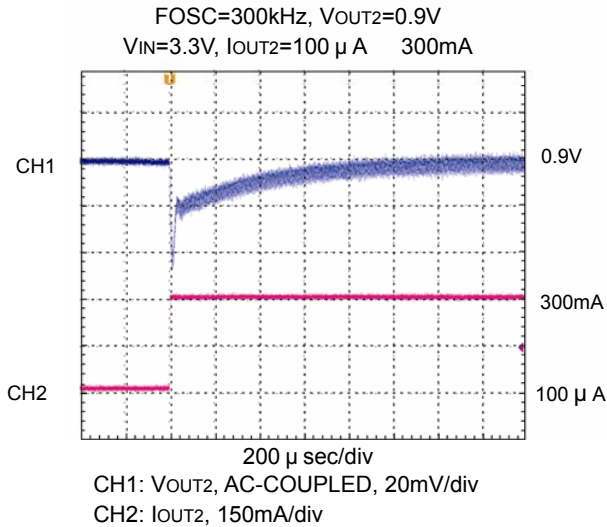
### (26) Load Transient Response (Continued)

<  $V_{OUT2}=0.9V$ ,  $V_{IN}=3.3V$ ,  $I_{OUT2}=100\mu A \leftrightarrow 300mA$  >

PWM Control



PWM/PFM Switching Control

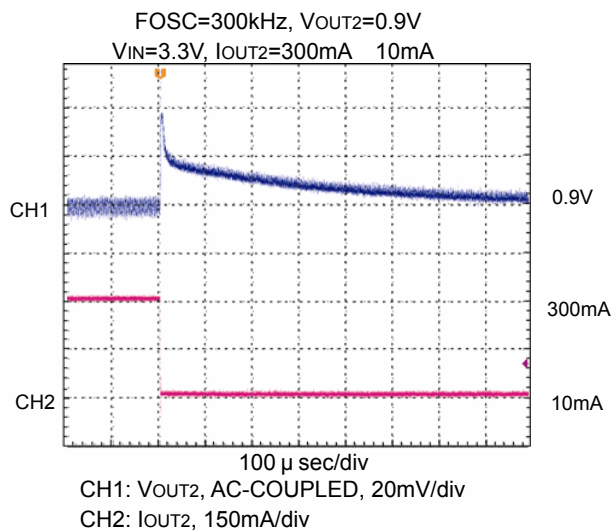
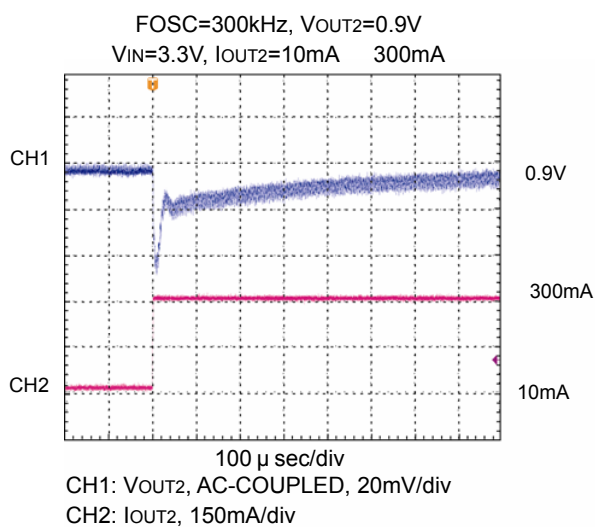


## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

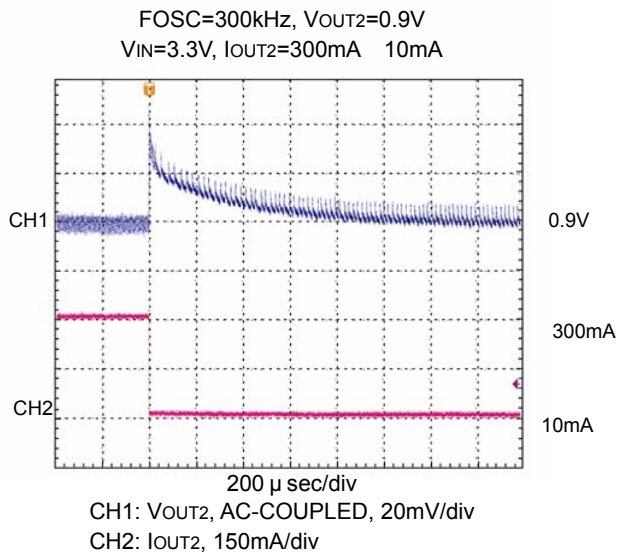
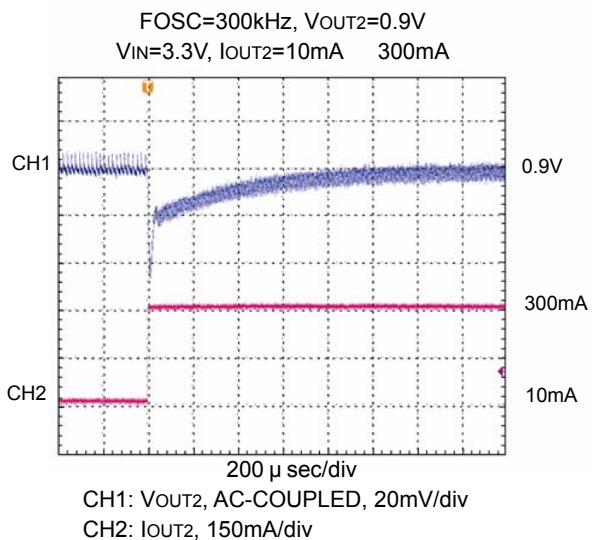
### (26) Load Transient Response (Continued)

<  $V_{OUT2}=0.9V$ ,  $V_{IN}=3.3V$ ,  $I_{OUT2}=10mA \leftrightarrow 300mA$  >

#### PWM Control



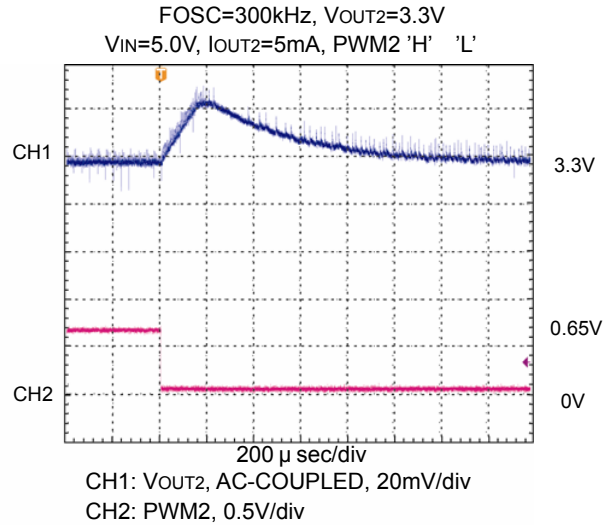
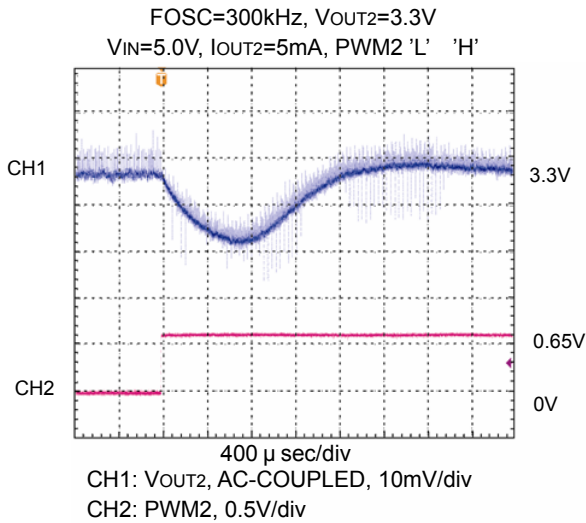
#### PWM/PFM Switching Control



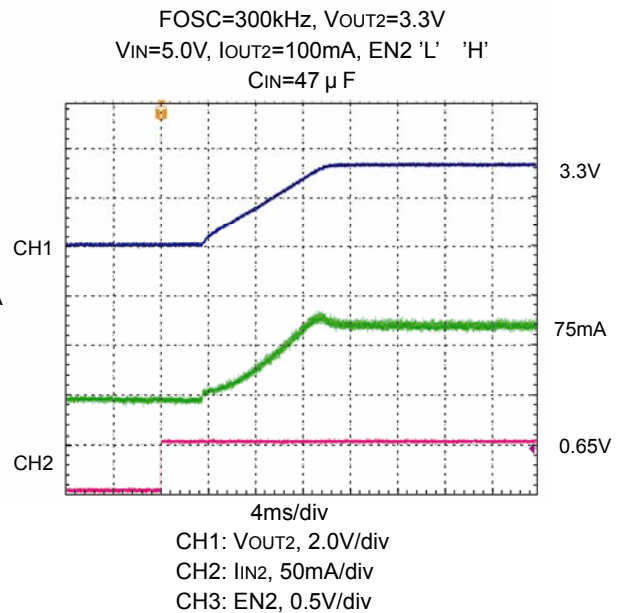
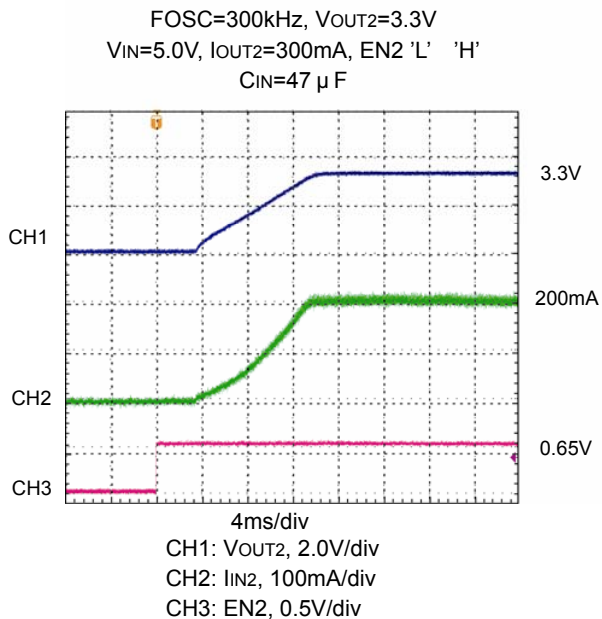
## TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

### (26) Load Transient Response (Continued)

<PWM Control    PWM/PFM Switching Control>



<Soft Start Wave Form>

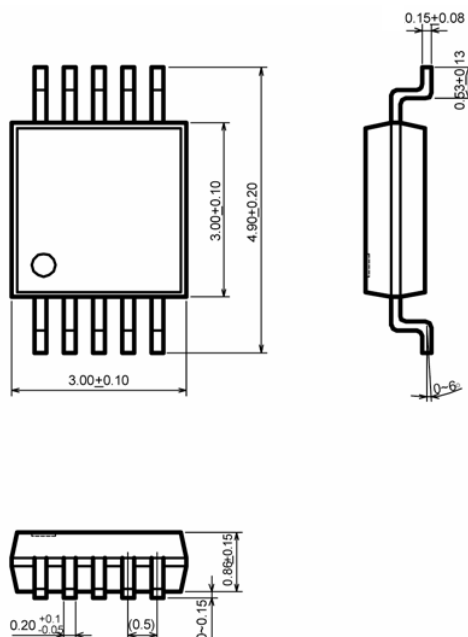


\* EN1=GND

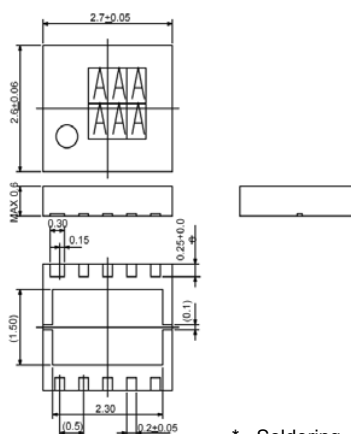


## PACKAGING INFORMATION

MSOP-10

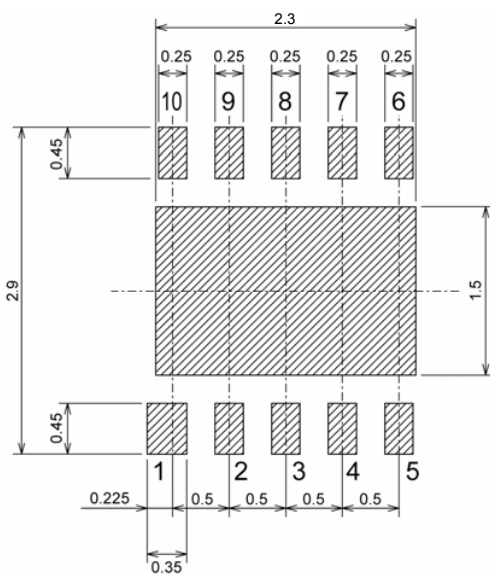


USP-10

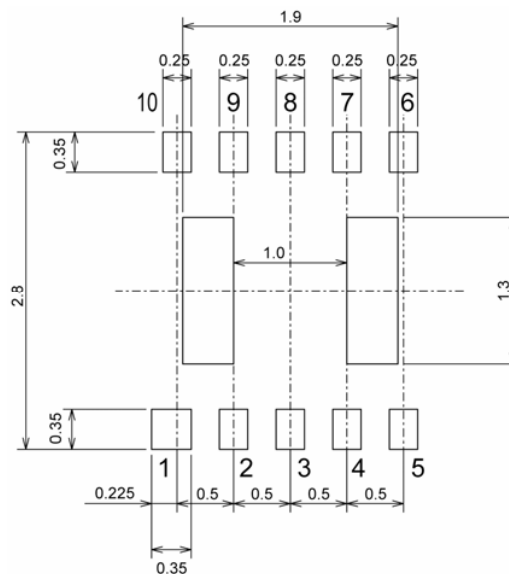


\* Soldering fillet surface is not formed because the sides of the pins are not plated.

USP-10 Recommended Pattern Layout

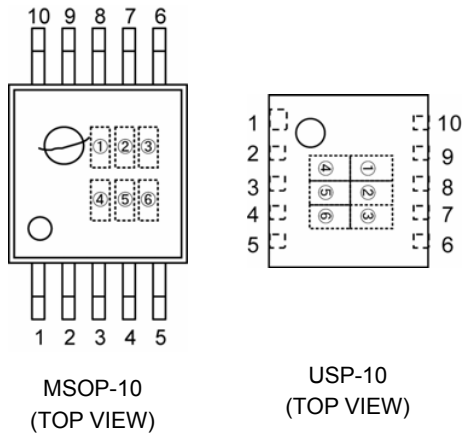


USP-10 Recommended Metal Mask Design



## MARKING RULE

MSOP-10, USP-10



Represents product series

MARK	PRODUCT SERIES
3	XC9502B09xxx

Represents type of DC/DC converter

MARK	PRODUCT SERIES
B	XC9502B09xxx

Represents FB voltage

MARK		VOLTAGE (V)	PRODUCT SERIES
0	9		

Represents oscillation frequency

MARK	OSCILLATION FREQUENCY (kHz)	PRODUCT SERIES
2	180	XC9502B092xx
3	300	XC9502B093xx
5	500	XC9502B095xx

Represents production lot number

0 to 9, A to Z repeated (G, I, J, O, Q, W expected)

Note: No character inversion used.

1. The products and product specifications contained herein are subject to change without notice to improve performance characteristics. Consult us, or our representatives before use, to confirm that the information in this catalog is up to date.
2. We assume no responsibility for any infringement of patents, patent rights, or other rights arising from the use of any information and circuitry in this catalog.
3. Please ensure suitable shipping controls (including fail-safe designs and aging protection) are in force for equipment employing products listed in this catalog.
4. The products in this catalog are not developed, designed, or approved for use with such equipment whose failure or malfunction can be reasonably expected to directly endanger the life of, or cause significant injury to, the user.  
(e.g. Atomic energy; aerospace; transport; combustion and associated safety equipment thereof.)
5. Please use the products listed in this catalog within the specified ranges.  
Should you wish to use the products under conditions exceeding the specifications, please consult us or our representatives.
6. We assume no responsibility for damage or loss due to abnormal use.
7. All rights reserved. No part of this catalog may be copied or reproduced without the prior permission of Torex Semiconductor Ltd.

**TOREX SEMICONDUCTOR LTD.**